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Understanding UEFI and PI Architectural Events

UEFI 2021 Virtual Plugfest

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Meet the Presenter



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What is UEFI Event?

- Event is a UEFI callback-based binary-to-binary communication mechanism
 - Like OS event objects
 - Adopted to UEFI single-threaded environment
 - Facilitated by UEFI Boot Services (UEFI 2.9 spec., ch. 7.1)
- Event Roles \bullet
 - Actor: detects underlying condition
 - Reactor(s).
 - Can get notified via callback when even is signaled
 - Can query event status
- PI specification defines simplified event-like callback mechanisms for PEI and MM environments
- PI specification extends list of standard UEFI events



Let's Dot the i's and Cross the t's

- UFFI vs PI
 - UEFI is a Firmware to OS Interface. There are multiple ways to architect a UEFI solution —
 - PI is the mainstream UEFI implementation, but it's just one of the ways to implement ____ UEFI
 - The presentation covers both domains, but makes it clear which domain is implied —
- Events vs UEFI Events •
 - Unless noted otherwise, term "event" is used by the presentation in a broad sense ____ referring to all kinds of UEFI and PI callback mechanisms
- MM vs SMM: what's the difference? •
 - Spec view: SMM and MM used by the PI spec interchangeably
 - SMM is an older name that was later replaced with a more architecture-neutral MM. However, SMM is still used here and there.
 - Views on the ground
 - Some people use SMM and MM as a references to IA and ARM MM implementations
 - Some people use SMM to refer to a Traditional MM implementation and MM to refer to a Standalone MM implementation



Functional UEFI Event Classes

- Private events •
 - Events used by drivers to implement driver specific logic
- **Protocol Specific Events**
 - Used for a protocol-specific notifications to protocol consumers
- Timer Events \bullet
 - Timed one-shot or periodic callbacks
 - UEFI Polling Mechanism
 - PI 1.7 introduced a PEI timed callback mechanism (Delayed Dispatch PPI)
- **Protocol Installation Notifications** \bullet
 - Private events can be registered with DXE Foundation to get signaled when protocol with the specific GUID is installed
 - PI specification defines a simplified (non-UEFI event based) protocol installation notifications for PEI and MM environments
- System Events (UEFI and PI) lacksquare
 - System wide special conditions
 - Boot Flow Events (important subclass of the System Events) ____
 - Reaching certain point in the boot process •
 - Some of them are implemented as Protocol Installation Notifications



UEFI Event Notification Types





MM and PEI Notification Callbacks



Legend:

Event actor

Event reactors

(*) – PEI has an indirect way to introduce two priority levels. See "PEI Notification Types" slide below for details.





Playing Safe with the Events

- Your code may be interrupted by the event callbacks
 - Use UEFI TPL API to protect critical portions of the code against reentrancy
- Don't assume a specific order of callback dispatching
 - UEFI specification does not define execution order of the callbacks with the same TPL
 - PI specification does not define execution order of the callbacks
- Never break TPL restrictions (UEFI spec., ch. 7.1, table 7-3)
 - UEFI specification defines the highest priority level at which each interface can be used
- Use the lowest TPL possible \bullet
 - If your event handler is not on TPL Callback, you should know why
- Don't overburden the system with large number of timer events
 - UEFI specification does not prescribe timer resolution. It is implementation specific.
 - Large number of timer events can reduce system performance.
- Don't overuse Protocol Installation Notification Callbacks
 - In UEFI drivers prefer driver model over protocol callbacks to deal with the protocols of the managed device
 - In PI code prefer DepEx over protocol callbacks



System Events

- Memory Map Change (UEFI) \bullet
 - Signaled whenever memory map changes
 - Not fully supported by the edk2 implementation
- Reset System (*UEFI*)
 - Signaled when ResetSystem() is invoked, and the system is about to be reset(only prior to ExitBootServices() invocation).
 - Not supported by the edk2 implementation
- DXE Dispatch (*PI*)
 - Internal pluming used by DXE and MM Foundations
- **Boot Flow**
 - To be discussed...



Boot Flow Events

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PEI Boot Flow Events



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Fun Facts and Things to Note

- Since PEI Boot Flow events are PPI notifications, they can be used as callbacks or as dependencies
- Master Boot Mode PPI is typically installed prior to Memory Discovered PPI, but it's not required by the PI spec
- Boot in Recovery Mode PPI can be installed at any point in the \bullet PEI execution before Dxelpl->Entry()
- According to the spec, if permanent and temporary RAM can coexist(mainstream scenario on IA platforms), temporary RAM (CAR) should be disabled after Memory Discovered PPI installation; however, edk2 implementation disables CAR before the PPI installation
- Prefer dispatch notifications over callbacks notifications



PEI Notification Types

- PI Specification defines two types of PPI installation notifications(PI 1.7A, vol. 1, ch. 4.2, 7.4): \bullet
 - Callback notification
 - Callback functions are called right after the PPI installation (before returning from InstallPpi PEI service)
 - Dispatch notification
 - Invocation of callback functions is deferred until PEIM that installed the PPI returns control back to PEI Foundation
- Dispatch notification type was originally intended to optimize stack usage by reducing number of nested stack frames
 - Thanks to hardware advances, stack overflow is not a typical problem, however, it still occasionally happens. For example, it may happen
 - On special boot paths
 - On S3 resume due to reduced amount of available memory
 - On Recovery due to increased memory usage
 - On feature rich firmware configurations
 - On embedded servers where small core hardware meets server feature set
- Dispatch notifications can be used as a control flow tool •
 - Dispatch notifications are guaranteed to by invoked after all the callback notifications has been invoked



DXE, BDS, and RT Boot Flow Events





Event Pairs

- UEFI and PI specs define 3 event pairs (events) signaled sequentially one after another) to implement smooth transition between the phases
 - First event presents the last chance to access system interfaces and/or to change system configuration before the transition
 - Second event can be used by handlers that facilitate the transition and by handlers that are interested in the finalized pre-transition configuration



UEFI and PI Event Pairs

- End-of-DXE, MM Ready-to-lock (PI) \bullet
 - End-of-DXE: last chance to use services that are to be disabled and to modify hardware state that is to be locked
 - MM Ready-to-lock: switch hardware into a secure state (e.g., lock SPI writes), disable or harden software interfaces (e.g., stop registration of new MM handlers, lock sensitive UEFI variables)
- Ready-to-Boot, After-Ready-to-Boot (UEFI)
 - Ready-to-Boot: last chance to change system configuration before the boot
 - After-Ready-to-Boot: process pre-boot configuration (e.g., finalize SMBIOS and/or ACPI tables, send config data to BKC)
- Before-Exit-Boot-Services, Exit-Boot-Services (UEFI)
 - Before-Exit-Boot-Services: last chance to use the boot services
 - Exit-Boot-Services: transition a driver to runtime





Fun Facts and Things to Note

- Don't take event name literally •
 - End-of-DXE is not necessarily the end of DXE phase
 - According to PI spec the event is signaled before "third party extensible modules such as UEFI • drivers and UEFI applications are executed". So, a portion of BDS may run prior to this event
 - MM is typically locked way before MM Ready-to-Lock is signaled
- DXE MM Ready-to-lock is a protocol
 - Unlike the other non-MM boot flow events, this one is implemented as a protocol ____
- Relative order of peer DXE and MM events is not defined
 - DXE Ready-to-Boot handlers may run before or after MM Ready-to-Boot handler
- MM Ready-to-Boot and MM Exit-Boot-Services are beyond the platform trust \bullet boundary
 - MM code should work properly if events are never signaled
 - Any data coming form outside the MM environment should be treated as untrusted
- Ready-to-Boot can happen more than once •
- Services called by Exit-Boot-Services callbacks may exhibit a boot time or a runtime • behavior
- Services called by Virtual-Address-Change callbacks may not work as intended if \bullet service being called has already transitioned to the virtual address memory map





Questions?

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More Questions?

Following today's webinar, join the live, interactive WebEx Q&A for the opportunity to chat with the presenter

Visit this link to attend: https://bit.ly/3aob707 Meeting number (access code): 182 688 4062 Meeting password: UEFIForum (83343678 from phones) and video systems)



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