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## Changes in previous releases

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<td>1550 Replace FTP4 dataCallback pointer-to-function-pointer with regular function pointer</td>
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<td>1548 Clarify Boot procedure when file name is absent2</td>
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| 2.5 | 1257 Correct the typedef definitions for EFI_BOOT_SERVICES/EFI_RUNTIME_SERVICES – Reiterate | February, 2015 |
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| 2.5 | 1251 EFI_REGULAR_EXPRESSION_PROTOCOL and EFI_IFR_MATCH2 HII op-code | February, 2015 |
| 2.5 | 1244 sections of the spec mis-arranged | February, 2015 |
| 2.5 | 1234 UEFI.Next feature - SmartCard edge protocol | February, 2015 |
| 2.5 | 1227 UEFI.Next feature - Platform recovery | February, 2015 |
| 2.5 | 1224 UEFI.Next - Adding support for No executable data areas | February, 2015 |
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| 2.5 | 1217 UEFI.Next feature - WiFi support | February, 2015 |
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| 2.5 | 1214 UEFI.Next feature - HTTPBoot | February, 2015 |
| 2.5 | 1213 UEFI.Next feature - HTTP helper API | February, 2015 |
| 2.5 | 1212 UEFI.Next feature - HTTP API | February, 2015 |
| 2.5 | 1204 new UEFI USB Function I/O Protocol addition to the UEFI spec | February, 2015 |
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| 2.3 | 449 Add missing EFI_IFR_GET, EFI_IFR_SET and EFI_IFR_MAP to the syntax. Section 28.2.5.7. | May 7, 2009 |
| 2.3 | 448 Section 28.2.5.4 Questions, Syntax, Update question-option-tag: Add EFI_IFR_READ and EFI_IFR_WRITE in the question syntax. | May 7, 2009 |
| 2.3 | Section 28.2.5.11.2 Moving Forms, Update line that starts with EFI_IFR_FORM to: EFI_IFR_FORM or EFI_IFR_FORM_MAP (and all references in EFI_IFR_REF) | May 7, 2009 |
| 2.3 | Section 28.2.5.2 Forms, Syntax, Change 3rd line to: form := EFI_IFR_FORM form-tag-list | May 7, 2009 |
| 2.3 | Table 194: EFI_IFR_FORM_MAP_OP, 2nd Column should be 0x5d (not 05xd) | May 7, 2009 |
| 2.3 | Section 28.2.5.1.1, section should be subheading, not heading level 5; Section 28.2.5.1, Syntax, line 3, text after := is not aligned with other text on line 2, 4 | May 7, 2009 |
| 2.3 | Section 28.3.8.3.38, EFI_IFR_MAP, Prototype, line 4, outdent 2 spaces. | May 7, 2009 |
| 2.3 | Section 28.3.8.3.64, EFI_IFR_SET, Prototype, lines 3-8, indentBy 2 spaces | May 7, 2009 |
| 2.3 | Change the defined type of EFI_STATUs from INTN to UINTN | May 7, 2009 |
| 2.3 | Incorrect definitions of UEFI_CONFIG_LANG and UEFI_CONFIG_LANG_2 in UEFI 2.3 Feb18 draft | Feb 25, 2009 |
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| 2.3 | EFI 2.3 split Figure 88 into 3 figures | Feb 12, 2009 |
| 2.3 | Partition Signature Clarification | Feb 12, 2009 |
| 2.3 | EFI 2.3 Feb Draft: 28.3.8.3.58 | Feb 12, 2009 |
| 2.3 | EFI 2.3 Feb Draft: Appendix M. | Feb 12, 2009 |
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| 2.3 | Change Appendix O from “UEFI ACPI Table” to “UEFI ACPI Data” | Feb 18, 2009 |
| 2.3 | Correct the definition of UEFI.CONFIG_LANG | Feb 18, 2009 |
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| 2.1C | 59 Add returnCode to Diagnostics Protocol | June 5, 2008 |
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<td>Adjust some of the #define names in the Simple Text Input Ex</td>
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<td>2.1A</td>
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<tr>
<td>2.1</td>
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<td>January 23, 2007</td>
</tr>
<tr>
<td>2.0</td>
<td>First release of specification.</td>
<td>January 31, 2006</td>
</tr>
</tbody>
</table>
This Unified Extensible Firmware Interface (UEFI) Specification describes an interface between the operating system (OS) and the platform firmware. UEFI was preceded by the Extensible Firmware Interface Specification 1.10 (EFI). As a result, some code and certain protocol names retain the EFI designation. Unless otherwise noted, EFI designations in this specification may be assumed to be part of UEFI.

The interface is in the form of data tables that contain platform-related information, and boot and runtime service calls that are available to the OS loader and the OS. Together, these provide a standard environment for booting an OS. This specification is designed as a pure interface specification. As such, the specification defines the set of interfaces and structures that platform firmware must implement. Similarly, the specification defines the set of interfaces and structures that the OS may use in booting. How either the firmware developer chooses to implement the required elements or the OS developer chooses to make use of those interfaces and structures is an implementation decision left for the developer.

The intent of this specification is to define a way for the OS and platform firmware to communicate only information necessary to support the OS boot process. This is accomplished through a formal and complete abstract specification of the software-visible interface presented to the OS by the platform and firmware.

Using this formal definition, a shrink-wrap OS intended to run on platforms compatible with supported processor specifications will be able to boot on a variety of system designs without further platform or OS customization. The definition will also allow for platform innovation to introduce new features and functionality that enhance platform capability without requiring new code to be written in the OS boot sequence.

Furthermore, an abstract specification opens a route to replace legacy devices and firmware code over time. New device types and associated code can provide equivalent functionality through the same defined abstract interface, again without impact on the OS boot support code.

The specification is applicable to a full range of hardware platforms from mobile systems to servers. The specification provides a core set of services along with a selection of protocol interfaces. The selection of protocol interfaces can evolve over time to be optimized for various platform market segments. At the same time, the specification allows maximum extensibility and customization abilities for OEMs to allow differentiation. In this, the purpose of UEFI is to define an evolutionary path from the traditional “PC-AT”-style boot world into a legacy-API free environment.

### 1.1 Principle of Inclusive Terminology

The UEFI Forum follows a Principle of Inclusive Terminology in building and maintaining content for specifications. This means that efforts are made to ensure that all wording is perceived or likely to be perceived as welcoming by everyone regardless of personal characteristics. In some cases, the Forum acknowledges that wording derived from earlier work, for example references to legacy specifications not controlled by the Forum, may not follow this principle. In order to preserve compatibility for code that reads on legacy specifications, particularly where that specification is no longer under maintenance or development, language in this specification may appear out of sync with the Principle. The Forum is resolved to work with other standards development bodies to eliminate such examples over time. In the meanwhile, by acknowledging and calling attention to this issue the hope is to promote discussion and action towards
more complete use of Inclusive Language reflective of the diverse and innovative population of the technical community that works on standards.

1.2 UEFI Driver Model Extensions

Access to boot devices is provided through a set of protocol interfaces. One purpose of the UEFI Driver Model is to provide a replacement for “PC-AT”-style option ROMs. It is important to point out that drivers written to the UEFI Driver Model are designed to access boot devices in the preboot environment. They are not designed to replace the high-performance, OS-specific drivers.

The UEFI Driver Model is designed to support the execution of modular pieces of code, also known as drivers, that run in the preboot environment. These drivers may manage or control hardware buses and devices on the platform, or they may provide some software-derived, platform-specific service.

The UEFI Driver Model also contains information required by UEFI driver writers to design and implement any combination of bus drivers and device drivers that a platform might need to boot a UEFI-compliant OS.

The UEFI Driver Model is designed to be generic and can be adapted to any type of bus or device. The UEFI Specification describes how to write PCI bus drivers, PCI device drivers, USB bus drivers, USB device drivers, and SCSI drivers. Additional details are provided that allow UEFI drivers to be stored in PCI option ROMs, while maintaining compatibility with legacy option ROM images.

One of the design goals in the UEFI Specification is keeping the driver images as small as possible. However, if a driver is required to support multiple processor architectures, a driver object file would also be required to be shipped for each supported processor architecture. To address this space issue, this specification also defines the EFI Byte Code Virtual Machine. A UEFI driver can be compiled into a single EFI Byte Code object file. UEFI Specification-compliant firmware must contain an EFI Byte Code interpreter. This allows a single EFI Byte Code object file that supports multiple processor architectures to be shipped. Another space saving technique is the use of compression. This specification defines compression and decompression algorithms that may be used to reduce the size of UEFI Drivers, and thus reduce the overhead when UEFI Drivers are stored in ROM devices.

The information contained in the UEFI Specification can be used by OSVs, IHVs, OEMs, and firmware vendors to design and implement firmware conforming to this specification, drivers that produce standard protocol interfaces, and operating system loaders that can be used to boot UEFI-compliant operating systems.

1.3 Organization

The high-level organization of this specification is as follows:

<table>
<thead>
<tr>
<th>Section(s)</th>
<th>Description</th>
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</thead>
<tbody>
<tr>
<td>Introduction / Overview</td>
<td>Introduces the UEFI Specification, and describes the major components of UEFI.</td>
</tr>
<tr>
<td>Boot Manager</td>
<td>Manager used to load drivers and applications written to this specification.</td>
</tr>
<tr>
<td>EFI System Table and Partitions</td>
<td>Describes an EFI System Table that is passed to every compliant driver and application, and defines a GUID-based partitioning scheme.</td>
</tr>
<tr>
<td>Block Transition Table</td>
<td>A layout and set of rules for doing block I/O that provide power fail write atomicity of a single block.</td>
</tr>
<tr>
<td>Boot Services</td>
<td>Contains the definitions of the fundamental services that are present in a UEFI-compliant system before an OS is booted.</td>
</tr>
<tr>
<td>Runtime Services</td>
<td>Contains definitions for the fundamental services that are present in a compliant system before and after an OS is booted.</td>
</tr>
</tbody>
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## Protocols

- The EFI Loaded Image Protocol describes a UEFI Image that has been loaded into memory.
- The Device Path Protocol provides the information needed to construct and manage device paths in the UEFI environment.
- The UEFI Driver Model describes a set of services and protocols that apply to every bus and device type.
- The Console Support Protocol defines I/O protocols that handle input and output of text-based information intended for the system user while executing in the boot services environment.
- The Media Access Protocol defines the Load File protocol, file system format and media formats for handling removable media.
- PCI Bus Support Protocols define PCI Bus Drivers, PCI Device Drivers, and PCI Option ROM layouts. The protocols described include the PCI Root Bridge I/O Protocol and the PCI I/O Protocol.
- SCSI Driver Models and Bus support defines the SCSI I/O Protocol and the Extended SCSI Pass Thru Protocol that is used to abstract access to a SCSI channel that is produced by a SCSI host controller.
- iSCSI protocol defines a transport for SCSI data over TCP/IP.
- The USB Support Protocol defines USB Bus Drivers and USB Device Drivers.
- Debugger Support Protocols describe an optional set of protocols that provide the services required to implement a source-level debugger for the UEFI environment.
- The Compression Algorithm Specification describes the compression/decompression algorithm in detail, plus a standard EFI decompression interface for use at boot time.
- ACPI Protocols may be used to install or remove an ACPI table from a platform.
- String Services: the Unicode Collation protocol allows code running in the boot services environment to perform lexical comparison functions on Unicode strings for given languages; the Regular Expression Protocol is used to match Unicode strings against Regular Expression patterns.

<table>
<thead>
<tr>
<th>EFI Byte Code Virtual Machine</th>
<th>Defines the EFI Byte Code virtual processor and its instruction set. It also defines how EBC object files are loaded into memory, and the mechanism for transitioning from native code to EBC code and back to native code.</th>
</tr>
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| Firmware Update and Reporting | Provides an abstraction for devices to provide firmware management support. | continues on next page |
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<th>Network Protocols</th>
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<tr>
<td>• SNP, PXE, BIS, and HTTP Boot protocols define the protocols that provide access to network devices while executing in the UEFI boot services environment.</td>
<td></td>
</tr>
<tr>
<td>• Managed Network protocols define the EFI Managed Network Protocol, which provides raw (unformatted) asynchronous network packet I/O services and Managed Network Service Binding Protocol, used to locate communication devices that are supported by an MNP driver.</td>
<td></td>
</tr>
<tr>
<td>• VLAN, EAP, Wi-Fi and Supplicant protocols define a protocol that is to provide a manageability interface for VLAN configurations.</td>
<td></td>
</tr>
<tr>
<td>• Bluetooth protocol definitions.</td>
<td></td>
</tr>
<tr>
<td>• ARP, DHCP, DNS, HTTP, and REST protocols define the EFI Address Resolution Protocol (ARP) Protocol interface and the EFI DHCPv4 Protocol.</td>
<td></td>
</tr>
<tr>
<td>• UDP and MTFTP protocols define the EFI UDPv4 (User Datagram Protocol version 4) Protocol that interfaces over the EFI IPv4 Protocol and defines the EFI MTFTPv4 Protocol interface that is built on the EFI UDPv4 Protocol.</td>
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<tr>
<th>Secure Boot and Driver Signing</th>
<th>Description</th>
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<tr>
<td>• Describes Secure Boot and a means of generating a digital signature for UEFI.</td>
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<tr>
<th>Human Interface Infrastructure</th>
<th>Description</th>
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<tr>
<td>• Defines the core code and (HII) services that are required for an implementation of the Human Interface Infrastructure (HII), including basic mechanisms for managing user input and code definitions for related protocols.</td>
<td></td>
</tr>
<tr>
<td>• Defines the data and APIs used to manage the system’s configuration: the actual data that describes the knobs and settings.</td>
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</table>

<table>
<thead>
<tr>
<th>Section(s)</th>
<th>Description</th>
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</thead>
<tbody>
<tr>
<td>User Identification</td>
<td>Describes services that describe the current user of the platform.</td>
</tr>
<tr>
<td>Secure Technologies</td>
<td>Describes the protocols for utilizing security technologies, including cryptographic hashing and key management.</td>
</tr>
<tr>
<td>Miscellaneous Protocols</td>
<td>The Timestamp protocol provides a platform independent interface for retrieving a high resolution timestamp counter. The Reset Notification Protocol provides services to register for a notification when ResetSystem is called.</td>
</tr>
</tbody>
</table>
### 1.4 Goals

The “PC-AT” boot environment presents significant challenges to innovation within the industry. Each new platform capability or hardware innovation requires firmware developers to craft increasingly complex solutions, and often requires OS developers to make changes to their boot code before customers can benefit from the innovation. This can be a time-consuming process requiring a significant investment of resources.

The primary goal of the UEFI specification is to define an alternative boot environment that can alleviate some of these considerations. In this goal, the specification is similar to other existing boot specifications. The main properties of this specification can be summarized by these attributes:

- **Coherent, scalable platform environment.** The specification defines a complete solution for the firmware to describe all platform features and surface platform capabilities to the OS during the boot process. The definitions are rich enough to cover a range of contemporary processor designs.

- **Abstraction of the OS from the firmware.** The specification defines interfaces to platform capabilities. Through the use of abstract interfaces, the specification allows the OS loader to be constructed with far less knowledge of the platform and firmware that underlie those interfaces. The interfaces represent a well-defined and stable boundary between the underlying platform and firmware implementation and the OS loader. Such a bound-
ary allows the underlying firmware and the OS loader to change provided both limit their interactions to the defined interfaces. The standard interfaces defined in this specification may be complemented by companion OS/firmware interfaces such as those defined by the ACPI specification. On the other hand, firmware-internal interfaces, such as those defined by the PI Specification, are produced and consumed by firmware only, and are not considered interfaces that a UEFI aware OS can connect to, interact with, or depend on.

- **Reasonable device abstraction free of legacy interfaces.** “PC-AT” BIOS interfaces require the OS loader to have specific knowledge of the workings of certain hardware devices. This specification provides OS loader developers with something different: abstract interfaces that make it possible to build code that works on a range of underlying hardware devices without having explicit knowledge of the specifics for each device in the range.

- **Abstraction of Option ROMs from the firmware.** This specification defines interfaces to platform capabilities including standard bus types such as PCI, USB, and SCSI. The list of supported bus types may grow over time, so a mechanism to extend to future bus types is included. These defined interfaces, and the ability to extend to future bus types, are components of the UEFI Driver Model. One purpose of the UEFI Driver Model is to solve a wide range of issues that are present in existing “PC-AT” option ROMs. Like OS loaders, drivers use the abstract interfaces so device drivers and bus drivers can be constructed with far less knowledge of the platform and firmware that underlie those interfaces.

- **Architecturally shareable system partition.** Initiatives to expand platform capabilities and add new devices often require software support. In many cases, when these platform innovations are activated before the OS takes control of the platform, they must be supported by code that is specific to the platform rather than to the customer’s choice of OS. The traditional approach to this problem has been to embed code in the platform during manufacturing (for example, in flash memory devices). Demand for such persistent storage is increasing at a rapid rate. This specification defines persistent store on large mass storage media types for use by platform support code extensions to supplement the traditional approach. The definition of how this works is made clear in the specification to ensure that firmware developers, OEMs, operating system vendors, and perhaps even third parties can share the space safely while adding to platform capability.

Defining a boot environment that delivers these attributes could be accomplished in many ways. Indeed, several alternatives, perhaps viable from an academic point of view, already existed at the time this specification was written. These alternatives, however, typically presented high barriers to entry given the current infrastructure capabilities surrounding supported processor platforms. This specification is intended to deliver the attributes listed above, while also recognizing the unique needs of an industry that has considerable investment in compatibility and a large installed base of systems that cannot be abandoned summarily. These needs drive the requirements for the additional attributes embodied in this specification:

- **Evolutionary, not revolutionary.** The interfaces and structures in the specification are designed to reduce the burden of an initial implementation as much as possible. While care has been taken to ensure that appropriate abstractions are maintained in the interfaces themselves, the design also ensures that reuse of BIOS code to implement the interfaces is possible with a minimum of additional coding effort. In other words, on PC-AT platforms the specification can be implemented initially as a thin interface layer over an underlying implementation based on existing code. At the same time, introduction of the abstract interfaces provides for migration away from legacy code in the future. Once the abstraction is established as the means for the firmware and OS loader to interact during boot, developers are free to replace legacy code underneath the abstract interfaces at leisure. A similar migration for hardware legacy is also possible. Since the abstractions hide the specifics of devices, it is possible to remove underlying hardware, and replace it with new hardware that provides improved functionality, reduced cost, or both. Clearly this requires that new platform firmware be written to support the device and present it to the OS loader via the abstract interfaces. However, without the interface abstraction, removal of the legacy device might not be possible at all.

- **Compatibility by design.** The design of the system partition structures also preserves all the structures that are currently used in the “PC-AT” boot environment. Thus, it is a simple matter to construct a single system that is capable of booting a legacy OS or an EFI-aware OS from the same disk.

- **Simplifies addition of OS-neutral platform value-add.** The specification defines an open, extensible interface that lends itself to the creation of platform “drivers.” These may be analogous to OS drivers, providing support for
new device types during the boot process, or they may be used to implement enhanced platform capabilities, such as fault tolerance or security. Furthermore, this ability to extend platform capability is designed into the specification from the outset. This is intended to help developers avoid many of the frustrations inherent in trying to squeeze new code into the traditional BIOS environment. As a result of the inclusion of interfaces to add new protocols, OEMs or firmware developers have an infrastructure to add capability to the platform in a modular way. Such drivers may potentially be implemented using high-level coding languages because of the calling conventions and environment defined in the specification. This in turn may help to reduce the difficulty and cost of innovation. The option of a system partition provides an alternative to nonvolatile memory storage for such extensions.

- **Built on existing investment.** Where possible, the specification avoids redefining interfaces and structures in areas where existing industry specifications provide adequate coverage. For example, the ACPI specification provides the OS with all the information necessary to discover and configure platform resources. Again, this philosophical choice for the design of the specification is intended to keep barriers to its adoption as low as possible.

### 1.5 Target Audience

This document is intended for the following readers:

- IHVs and OEMs who will be implementing UEFI drivers.
- OEMs who will be creating supported processor platforms intended to boot shrink-wrap operating systems.
- BIOS developers, either those who create general-purpose BIOS and other firmware products or those who modify these products for use in supported processor-based products.
- Operating system developers who will be adapting their shrink-wrap operating system products to run on supported processor-based platforms.

### 1.6 UEFI Design Overview

The design of UEFI is based on the following fundamental elements:

- **Reuse of existing table-based interfaces.** In order to preserve investment in existing infrastructure support code, both in the OS and firmware, a number of existing specifications that are commonly implemented on platforms compatible with supported processor specifications must be implemented on platforms wishing to comply with the UEFI specification. (For additional information, see Appendix Q — References.)
- **System partition.** The System partition defines a partition and file system that are designed to allow safe sharing between multiple vendors, and for different purposes. The ability to include a separate, sharable system partition presents an opportunity to increase platform value-add without significantly growing the need for nonvolatile platform memory.
- **Boot services.** Boot services provide interfaces for devices and system functionality that can be used during boot time. Device access is abstracted through “handles” and “protocols.” This facilitates reuse of investment in existing BIOS code by keeping underlying implementation requirements out of the specification without burdening the consumer accessing the device.
- **Runtime services.** A minimal set of runtime services is presented to ensure appropriate abstraction of base platform hardware resources that may be needed by the OS during its normal operations.

The Figure below shows the principal components of UEFI and their relationship to platform hardware and OS software. This Figure illustrates the interactions of the various components of an UEFI specification-compliant system that are used to accomplish platform and OS boot.
The platform firmware is able to retrieve the OS loader image from the System Partition. The specification provides for a variety of mass storage device types including disk, CD-ROM, and DVD as well as remote boot via a network. Through the extensible protocol interfaces, it is possible to add other boot media types, although these may require OS loader modifications if they require use of protocols other than those defined in this document.

Once started, the OS loader continues to boot the complete operating system. To do so, it may use the EFI boot services and interfaces defined by this or other required specifications to survey, comprehend, and initialize the various platform components and the OS software that manages them. EFI runtime services are also available to the OS loader during the boot phase.

1.7 UEFI Driver Model

This section describes the goals of a driver model for firmware conforming to this specification. The goal is for this driver model to provide a mechanism for implementing bus drivers and device drivers for all types of buses and devices. At the time of writing, supported bus types include PCI, USB, and so on.

As hardware architectures continue to evolve, the number and types of buses present in platforms are increasing. This trend is especially true in high-end servers. However, a more diverse set of bus types is being designed into desktop and mobile systems and even some embedded systems. This increasing complexity means that a simple method for describing and managing all the buses and devices in a platform is required in the preboot environment. The UEFI Driver Model provides this simple method in the form of protocols services and boot services.
1.7.1 UEFI Driver Model Goals

The UEFI Driver Model has the following goals:

- **Compatible** — Drivers conforming to this specification must maintain compatibility with the EFI 1.10 Specification and the UEFI Specification. This means that the UEFI Driver Model takes advantage of the extensibility mechanisms in the UEFI 2.0 Specification to add the required functionality.

- **Simple** — Drivers that conform to this specification must be simple to implement and simple to maintain. The UEFI Driver Model must allow a driver writer to concentrate on the specific device for which the driver is being developed. A driver should not be concerned with platform policy or platform management issues. These considerations should be left to the system firmware.

- **Scalable** — The UEFI Driver Model must be able to adapt to all types of platforms. These platforms include embedded systems, mobile, and desktop systems, as well as workstations and servers.

- **Flexible** — The UEFI Driver Model must support the ability to enumerate all the devices, or to enumerate only those devices required to boot the required OS. The minimum device enumeration provides support for more rapid boot capability, and the full device enumeration provides the ability to perform OS installations, system maintenance, or system diagnostics on any boot device present in the system.

- **Extensible** — The UEFI Driver Model must be able to extend to future bus types as they are defined.

- **Portable** — Drivers written to the UEFI Driver Model processor architectures.

- **Interoperable** — Drivers must coexist with other drivers and system firmware and must do so without generating resource conflicts.

- **Describe complex bus hierarchies** — The UEFI Driver Model must be able to describe a variety of bus topologies from very simple single bus platforms to very complex platforms containing many buses of various types.

- **Small driver footprint** — The size of executables produced by the UEFI Driver Model must be minimized to reduce the overall platform cost. While flexibility and extensibility are goals, the additional overhead required to support these must be kept to a minimum to prevent the size of firmware components from becoming unmanageable.

- **Address legacy option rom issues** — The UEFI Driver Model must directly address and solve the constraints and limitations of legacy option ROMs. Specifically, it must be possible to build add-in cards that support both UEFI drivers and legacy option ROMs, where such cards can execute in both legacy BIOS systems and UEFI-conforming platforms, without modifications to the code carried on the card. The solution must provide an evolutionary path to migrate from legacy option ROMs driver to UEFI drivers.

1.7.2 Legacy Option ROM Issues

This idea of supporting a driver model came from feedback on the UEFI Specification that provided a clear, market-driven requirement for an alternative to the legacy option ROM (sometimes also referred to as an expansion ROM). The perception is that the advent of the UEFI Specification represents a chance to escape the limitations implicit in the construction and operation of legacy option ROM images by replacing them with an alternative mechanism that works within the framework of the UEFI Specification.
1.8 Migration Requirements

Migration requirements cover the transition period from initial implementation of this specification to a future time when all platforms and operating systems implement to this specification. During this period, two major compatibility considerations are important:

- The ability to continue booting legacy operating systems;
- The ability to implement UEFI on existing platforms by reusing as much existing firmware code to keep development resource and time requirements to a minimum.

1.8.1 Legacy Operating System Support

The UEFI specification represents the preferred means for a shrink-wrap OS and firmware to communicate during the boot process. However, choosing to make a platform that complies with this specification in no way precludes a platform from also supporting existing legacy OS binaries that have no knowledge of the UEFI specification.

The UEFI specification does not restrict a platform designer who chooses to support both the UEFI specification and a more traditional “PC-AT” boot infrastructure. If such a legacy infrastructure is to be implemented, it should be developed in accordance with existing industry practice that is defined outside the scope of this specification. The choice of legacy operating systems that are supported on any given platform is left to the manufacturer of that platform.

1.8.2 Supporting the UEFI Specification on a Legacy Platform

The UEFI specification has been carefully designed to allow for existing systems to be extended to support it with a minimum of development effort. In particular, the abstract structures and services defined in the UEFI specification can all be supported on legacy platforms.

For example, to accomplish such support on an existing and supported 32-bit-based platform that uses traditional BIOS to support operating system boot, an additional layer of firmware code would need to be provided. This extra code would be required to translate existing interfaces for services and devices into support for the abstractions defined in this specification.

1.9 Conventions Used in this Document

This document uses typographic and illustrative conventions described below.

1.9.1 Data Structure Descriptions

Supported processors are “little endian” machines. This distinction means that the low-order byte of a multibyte data item in memory is at the lowest address, while the high-order byte is at the highest address. Some supported 64-bit processors may be configured for both “little endian” and “big endian” operation. All implementations designed to conform to this specification use “little endian” operation.

In some memory layout descriptions, certain fields are marked reserved. Software must initialize such fields to zero and ignore them when read. On an update operation, software must preserve any reserved field.
1.9.2 Protocol Descriptions

A protocol description generally has the following format:

**Protocol Name:** The formal name of the protocol interface.

**Summary:** A brief description of the protocol interface.

**GUID:** The 128-bit Globally Unique Identifier (GUID) for the protocol interface.

**Protocol Interface Structure:** A “C-style” data structure definition containing the procedures and data fields produced by this protocol interface.

**Parameters:** A brief description of each field in the protocol interface structure.

**Description:** A description of the functionality provided by the interface, including any limitations and caveats of which the caller should be aware.

**Related Definitions:** The type declarations and constants that are used in the protocol interface structure or any of its procedures.

1.9.3 Procedure Descriptions

A procedure description generally has the following format:

**ProcedureName():** The formal name of the procedure.

**Summary:** A brief description of the procedure.

**Prototype:** A “C-style” procedure header defining the calling sequence.

**Parameters:** A brief description of each field in the procedure prototype.

**Description:** A description of the functionality provided by the interface, including any limitations and caveats of which the caller should be aware.

**Related Definitions:** The type declarations and constants that are used only by this procedure.

**Status Codes Returned:** A description of any codes returned by the interface. The procedure is required to implement any status codes listed in this table. Additional error codes may be returned, but they will not be tested by standard compliance tests, and any software that uses the procedure cannot depend on any of the extended error codes that an implementation may provide.

1.9.4 Instruction Descriptions

An instruction description for EBC instructions generally has the following format:

**InstructionName:** The formal name of the instruction.

**Syntax:** A brief description of the instruction.

**Description:** A description of the functionality provided by the instruction accompanied by a table that details the instruction encoding.

**Operation:** Details the operations performed on operands.

**Behaviors and Restrictions:** An item-by-item description of the behavior of each operand involved in the instruction and any restrictions that apply to the operands or the instruction.
1.9.5 Pseudo-Code Conventions

Pseudo code is presented to describe algorithms in a more concise form. None of the algorithms in this document are intended to be compiled directly. The code is presented at a level corresponding to the surrounding text.

In describing variables, a list is an unordered collection of homogeneous objects. A queue is an ordered list of homogeneous objects. Unless otherwise noted, the ordering is assumed to be FIFO.

Pseudo code is presented in a C-like format, using C conventions where appropriate. The coding style, particularly the indentation style, is used for readability and does not necessarily comply with an implementation of the UEFI Specification.

1.9.6 Typographic Conventions

This document uses the typographic and illustrative conventions described below:

Plain text

The normal text typeface is used for the vast majority of the descriptive text in a specification.

Plain text (blue)

Any plain text that is underlined and in blue indicates an active link to the cross-reference. Click on the word to follow the hyperlink.

Bold

In text, a Bold typeface identifies a processor register name. In other instances, a Bold typeface can be used as a running head within a paragraph.

Italic

In text, an Italic typeface can be used as emphasis to introduce a new term or to indicate a manual or specification name.

BOLD Monospace

Computer code, example code segments, and all prototype code segments use a BOLD Monospace typeface with a dark red color. These code listings normally appear in one or more separate paragraphs, though words or segments can also be embedded in a normal text paragraph.

Bold Monospace (Blue, underlined)

Words in a Bold Monospace typeface that is underlined and in blue indicate an active hyperlink to the code definition for that function or type definition. Click on the word to follow the hyperlink.

Note: Due to management and file size considerations, only the first occurrence of the reference on each page is an active link. Subsequent references on the same page will not be actively linked to the definition and will use the standard, nonunderlined BOLD Monospace typeface. Find the first instance of the name (in the underlined BOLD Monospace typeface) on the page and click on the word to jump to the function or type definition.

Italic Monospace

In code or in text, words in Italic Monospace indicate placeholder names for variable information that must be supplied (i.e., arguments).
1.9.7 Number formats

A binary number is represented in this standard by any sequence of digits consisting of only the Western-Arabic numerals 0 and 1 immediately followed by a lower-case b (e.g., 0101b).

Underscores or spaces may be included between characters in binary number representations to increase readability or delineate field boundaries (e.g., 0 0101 1010b or 0_0101_1010b).

1.9.7.1 Hexadecimal

A hexadecimal number is represented in this standard by 0x preceding any sequence of digits consisting of only the Western-Arabic numerals 0 through 9 and/or the upper-case English letters A through F (e.g., 0xFA23).

Underscores or spaces may be included between characters in hexadecimal number representations to increase readability or delineate field boundaries (e.g., 0xB FD8C FA23 or 0xB_FD8C_FA23).

1.9.7.2 Decimal

A decimal number is represented in this standard by any sequence of digits consisting of only the Arabic numerals 0 through 9 not immediately followed by a lower-case b or lower-case h (e.g., 25).

This standard uses the following conventions for representing decimal numbers:
- the decimal separator (i.e., separating the integer and fractional portions of the number) is a period;
- the thousands separator (i.e., separating groups of three digits in a portion of the number) is a comma;
- the thousands separator is used in the integer portion and is not used in the fraction portion of a number.

1.9.8 SI & Binary prefixes

This standard uses the prefixes defined in the International System of Units (SI) for values that are powers of ten. See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “SI Binary Prefixes”.

SI prefixes

<table>
<thead>
<tr>
<th>Factor</th>
<th>Name</th>
<th>Symbol</th>
</tr>
</thead>
<tbody>
<tr>
<td>$10^3$</td>
<td>1,000</td>
<td>kilo</td>
</tr>
<tr>
<td>$10^6$</td>
<td>1,000,000</td>
<td>mega</td>
</tr>
<tr>
<td>$10^9$</td>
<td>1,000,000,000</td>
<td>giga</td>
</tr>
</tbody>
</table>

This standard uses the binary prefixes defined in ISO/IEC 80000-13 Quantities and units – Part 13: Information science and technology and IEEE 1514 Standard for Prefixes for Binary Multiples for values that are powers of two.

Binary prefixes

<table>
<thead>
<tr>
<th>Factor</th>
<th>Name</th>
<th>Symbol</th>
</tr>
</thead>
<tbody>
<tr>
<td>$2^{10}$</td>
<td>1,024</td>
<td>kibi</td>
</tr>
<tr>
<td>$2^{20}$</td>
<td>1,048,576</td>
<td>mebi</td>
</tr>
<tr>
<td>$2^{30}$</td>
<td>1,073,741,824</td>
<td>gibi</td>
</tr>
</tbody>
</table>

For example, 4 KB means 4,000 bytes and 4 KiB means 4,096 bytes.
1.9.9 Revision Numbers

Updates to the UEFI specification are considered either new revisions or errata as described below:

- **A new revision is produced when there is substantive new content or changes that may modify existing behavior.**
  New revisions are designated by a major.minor version number (e.g. xx.yy). In cases where the changes are exceptionally minor, we may have a major.minor.minor naming convention (e.g. xx.yy.zz).

- **Errata versions are produced when approved updates to the specification do not include any significant new material or modify existing behavior.** Errata are designated by adding an upper-case letter at the end of the version number, such as xx.yy errata A.
UEFI allows the extension of platform firmware by loading UEFI driver and UEFI application images. When UEFI drivers and UEFI applications are loaded they have access to all UEFI-defined runtime and boot services. See the Booting Sequence figure below.

Fig. 2.1: Booting Sequence

UEFI allows the consolidation of boot menus from the OS loader and platform firmware into a single platform firmware menu. These platform firmware menus will allow the selection of any UEFI OS loader from any partition on any boot medium that is supported by UEFI boot services. An UEFI OS loader can support multiple options that can appear on the user interface. It is also possible to include legacy boot options, such as booting from the A: or C: drive in the platform firmware boot menus.
UEFI supports booting from media that contain an UEFI OS loader or an UEFI-defined System Partition. An UEFI-defined System Partition is required by UEFI to boot from a block device. UEFI does not require any change to the first sector of a partition, so it is possible to build media that will boot on both legacy architectures and UEFI platforms.

2.1 Boot Manager

UEFI contains a boot manager that allows the loading of applications written to this specification (including OS first stage loader) or UEFI drivers from any file on an UEFI-defined file system or through the use of an UEFI-defined image loading service. UEFI defines NVRAM variables that are used to point to the file to be loaded. These variables also contain application-specific data that are passed directly to the UEFI application. The variables also contain a human readable string that can be displayed in a menu to the user.

The variables defined by UEFI allow the system firmware to contain a boot menu that can point to all of the operating systems, and even multiple versions of the same operating systems. The design goal of UEFI was to have one set of boot menus that could live in platform firmware. UEFI specifies only the NVRAM variables used in selecting boot options. UEFI leaves the implementation of the menu system as value added implementation space.

UEFI greatly extends the boot flexibility of a system over the current state of the art in the PC-AT-class system. The PC-AT-class systems today are restricted to boot from the first floppy, hard drive, CD-ROM, USB keys, or network card attached to the system. Booting from a common hard drive can cause many interoperability problems between operating systems, and different versions of operating systems from the same vendor.

2.1.1 UEFI Images

UEFI Images are a class of files defined by UEFI that contain executable code. The most distinguishing feature of UEFI Images is that the first set of bytes in the UEFI Image file contains an image header that defines the encoding of the executable image.

UEFI uses a subset of the PE32+ image format with a modified header signature. The modification to the signature value in the PE32+ image is done to distinguish UEFI images from normal PE32 executables. The “+” addition to PE32 provides the 64-bit relocation fix-up extensions to standard PE32 format.

For images with the UEFI image signature, the Subsystem values in the PE image header are defined below. The major differences between image types are the memory type that the firmware will load the image into, and the action taken when the image’s entry point exits or returns. A UEFI application image is always unloaded when control is returned from the image’s entry point. A UEFI driver image is only unloaded if control is passed back with a UEFI error code.

```c
// PE32+ Subsystem type for UEFI images
#define EFI_IMAGE_SUBSYSTEM_EFI_APPLICATION 10
#define EFI_IMAGE_SUBSYSTEM_EFI_BOOT_SERVICE_DRIVER 11
#define EFI_IMAGE_SUBSYSTEM_EFI_RUNTIME_DRIVER 12

// PE32+ Machine type for UEFI images
#define EFI_IMAGE_MACHINE_IA32 0x014c
#define EFI_IMAGE_MACHINE_IA64 0x0200
#define EFI_IMAGE_MACHINE_EBC 0x0EBC
#define EFI_IMAGE_MACHINE_x64 0x8664
#define EFI_IMAGE_MACHINE_ARMTHUMB_MIXED 0x01C2
#define EFI_IMAGE_MACHINE_AARCH64 0xAA64
#define EFI_IMAGE_MACHINE_RISCV32 0x5032
#define EFI_IMAGE_MACHINE_RISCV64 0x5064
#define EFI_IMAGE_MACHINE_RISCV128 0x5128
```
**Note:** This image type is chosen to enable UEFI images to contain Thumb and Thumb2 instructions while defining the EFI interfaces themselves to be in ARM mode.

<table>
<thead>
<tr>
<th>Subsystem Type</th>
<th>Code Memory Type</th>
<th>Data Memory Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_IMAGE_SUBSYSTEM_APPLICATION</td>
<td>EfiLoaderCode</td>
<td>EfiLoaderData</td>
</tr>
<tr>
<td>EFI_IMAGE_SUBSYSTEM_BOOT_SERVICE_DRIVER</td>
<td>EfiBootServicesCode</td>
<td>EfiBootServicesData</td>
</tr>
<tr>
<td>EFI_IMAGE_SUBSYSTEM_RUNTIME_DRIVER</td>
<td>EfiRuntimeServicesCode</td>
<td>EfiRuntimeServicesData</td>
</tr>
</tbody>
</table>

The Machine value that is found in the PE image file header is used to indicate the machine code type of the image. The machine code types for images with the UEFI image signature are defined below. A given platform must implement the image type native to that platform and the image type for EFI Byte Code (EBC). Support for other machine code types is optional to the platform.

A UEFI image is loaded into memory through the `EFI_BOOT_SERVICES.LoadImage()` Boot Service. This service loads an image with a PE32+ format into memory. This PE32+ loader is required to load all sections of the PE32+ image into memory. Once the image is loaded into memory, and the appropriate fix-ups have been performed, control is transferred to a loaded image at the AddressOfEntryPoint reference according to the normal indirect calling conventions of applications based on supported 32-bit, 64-bit, or 128-bit processors. All other linkage to and from an UEFI image is done programmatically.

### 2.1.2 UEFI Applications

Applications written to this specification are loaded by the Boot Manager or by other UEFI applications. To load a UEFI application the firmware allocates enough memory to hold the image, copies the sections within the UEFI application image to the allocated memory, and applies the relocation fix-ups needed. Once done, the allocated memory is set to be the proper type for code and data for the image. Control is then transferred to the UEFI application's entry point. When the application returns from its entry point, or when it calls the Boot Service `EFI_BOOT_SERVICES.LoadImage()`, the UEFI application is unloaded from memory and control is returned to the UEFI component that loaded the UEFI application.

When the Boot Manager loads a UEFI application, the image handle may be used to locate the “load options” for the UEFI application. The load options are stored in nonvolatile storage and are associated with the UEFI application being loaded and executed by the Boot Manager.

### 2.1.3 UEFI OS Loaders

A UEFI OS loader is a special type of UEFI application that normally takes over control of the system from firmware conforming to this specification. When loaded, the UEFI OS loader behaves like any other UEFI application in that it must only use memory it has allocated from the firmware and can only use UEFI services and protocols to access the devices that the firmware exposes. If the UEFI OS loader includes any boot service style driver functions, it must use the proper UEFI interfaces to obtain access to the bus specific-resources. That is, I/O and memory-mapped device registers must be accessed through the proper bus specific I/O calls like those that a UEFI driver would perform.

If the UEFI OS loader experiences a problem and cannot load its operating system correctly, it can release all allocated resources and return control back to the firmware via the Boot Service Exit() call. The Exit() call allows both an error code and ExitData to be returned. The ExitData contains both a string and OS loader-specific data to be returned. If the UEFI OS loader successfully loads its operating system, it can take control of the system by using the Boot
Service \texttt{EFI\_BOOT\_SERVICES.ExitBootServices()} . After successfully calling \texttt{ExitBootServices()}, all boot services in the system are terminated, including memory management, and the UEFI OS loader is responsible for the continued operation of the system.

### 2.1.4 UEFI Drivers

UEFI drivers are loaded by the Boot Manager, firmware conforming to this specification, or by other UEFI applications. To load a UEFI driver the firmware allocates enough memory to hold the image, copies the sections within the UEFI driver image to the allocated memory and applies the relocation fix-ups needed. Once done, the allocated memory is set to be the proper type for code and data for the image. Control is then transferred to the UEFI driver’s entry point. When the UEFI driver returns from its entry point, or when it calls the Boot Service \texttt{EFI\_BOOT\_SERVICES.ExitBootServices()}, the UEFI driver is optionally unloaded from memory and control is returned to the component that loaded the UEFI driver. A UEFI driver is not unloaded from memory if it returns a status code of \texttt{EFI\_SUCCESS} . If the UEFI driver’s return code is an error status code, then the driver is unloaded from memory.

There are two types of UEFI drivers: boot service drivers and runtime drivers. The only difference between these two driver types is that UEFI runtime drivers are available after a UEFI OS loader has taken control of the platform with the Boot Service \texttt{EFI\_BOOT\_SERVICES.ExitBootServices()}. UEFI boot service drivers are terminated when \texttt{ExitBootServices()} is called, and all the memory resources consumed by the UEFI boot service drivers are released for use in the operating system environment.

A runtime driver of type \texttt{EFI\_IMAGE\_SUBSYSTEM\_EFI\_RUNTIME\_DRIVER} gets fixed up with virtual mappings when the OS calls \texttt{SetVirtualAddressMap()}.  

### 2.2 Firmware Core

This section provides an overview of the services defined by UEFI. These include boot services and runtime services.

#### 2.2.1 UEFI Services

The purpose of the UEFI interfaces is to define a common boot environment abstraction for use by loaded UEFI images, which include UEFI drivers, UEFI applications, and UEFI OS loaders. The calls are defined with a full 64-bit interface, so that there is headroom for future growth. The goal of this set of abstracted platform calls is to allow the platform and OS to evolve and innovate independently of one another. Also, a standard set of primitive runtime services may be used by operating systems.

Platform interfaces defined in this section allow the use of standard Plug and Play Option ROMs as the underlying implementation methodology for the boot services. The interfaces have been designed in such as way as to map back into legacy interfaces. These interfaces have in no way been burdened with any restrictions inherent to legacy Option ROMs.

The UEFI platform interfaces are intended to provide an abstraction between the platform and the OS that is to boot on the platform. The UEFI specification also provides abstraction between diagnostics or utility programs and the platform; however, it does not attempt to implement a full diagnostic OS environment. It is envisioned that a small diagnostic OS-like environment can be easily built on top of an UEFI system. Such a diagnostic environment is not described by this specification. Interfaces added by this specification are divided into the following categories and are detailed later in this document:

- Runtime services
- Boot services interfaces, with the following subcategories:
  - Global boot service interfaces
– Device handle-based boot service interfaces
– Device protocols
– Protocol services

### 2.2.2 Runtime Services

This section describes UEFI runtime service functions. The primary purpose of the runtime services is to abstract minor parts of the hardware implementation of the platform from the OS. Runtime service functions are available during the boot process and also at runtime provided the OS switches into flat physical addressing mode to make the runtime call. However, if the OS loader or OS uses the Runtime Service `SetVirtualAddressMap()` service, the OS will only be able to call runtime services in a virtual addressing mode. All runtime interfaces are non-blocking interfaces and can be called with interrupts disabled if desired. To ensure maximum compatibility with existing platforms it is recommended that all UEFI modules that comprise the Runtime Services be represented in the MemoryMap as a single EFI_MEMORY_DESCRIPTOR of Type EfiRuntimeServicesCode.

In all cases memory used by the runtime services must be reserved and not used by the OS. runtime services memory is always available to an UEFI function and will never be directly manipulated by the OS or its components. UEFI is responsible for defining the hardware resources used by runtime services, so the OS can synchronize with those resources when runtime service calls are made, or guarantee that the OS never uses those resources. See the table below for lists of the Runtime Services functions.

<table>
<thead>
<tr>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>GetTime()</code></td>
<td>Returns the current time, time context, and time keeping capabilities.</td>
</tr>
<tr>
<td><code>SetTime()</code></td>
<td>Sets the current time and time context.</td>
</tr>
<tr>
<td><code>GetWakeupTime()</code></td>
<td>Returns the current wakeup alarm settings.</td>
</tr>
<tr>
<td><code>SetWakeupTime()</code></td>
<td>Sets the current wakeup alarm settings.</td>
</tr>
<tr>
<td><code>GetVariable()</code></td>
<td>Returns the value of a named variable.</td>
</tr>
<tr>
<td><code>GetNextVariableName()</code></td>
<td>Enumerates variable names.</td>
</tr>
<tr>
<td><code>SetVariable()</code></td>
<td>Sets, and if needed creates, a variable.</td>
</tr>
<tr>
<td><code>SetVirtualAddressMap()</code></td>
<td>Switches all runtime functions from physical to virtual addressing.</td>
</tr>
<tr>
<td><code>ConvertPointer()</code></td>
<td>Used to convert a pointer from physical to virtual addressing.</td>
</tr>
</tbody>
</table>

continues on next page
### 2.3 Calling Conventions

Unless otherwise stated, all functions defined in the UEFI specification are called through pointers in common, architecturally defined, calling conventions found in C compilers. Pointers to the various global UEFI functions are found in the EFI_RUNTIME_SERVICES and EFI_BOOT_SERVICES tables that are located via the system table. Pointers to other functions defined in this specification are located dynamically through device handles. In all cases, all pointers to UEFI functions are cast with the word EFIAP. This allows the compiler for each architecture to supply the proper compiler keywords to achieve the needed calling conventions. When passing pointer arguments to Boot Services, Runtime Services, and Protocol Interfaces, the caller has the following responsibilities:

- It is the caller’s responsibility to pass pointer parameters that reference physical memory locations. If a pointer is passed that does not point to a physical memory location (i.e., a memory mapped I/O region), the results are unpredictable and the system may halt.
- It is the caller’s responsibility to pass pointer parameters with correct alignment. If an unaligned pointer is passed to a function, the results are unpredictable and the system may halt.
- It is the caller’s responsibility to not pass in a NULL parameter to a function unless it is explicitly allowed. If a NULL pointer is passed to a function, the results are unpredictable and the system may hang.
- Unless otherwise stated, a caller should not make any assumptions regarding the state of pointer parameters if the function returns with an error.
- A caller may not pass structures that are larger than native size by value and these structures must be passed by reference (via a pointer) by the caller. Passing a structure larger than native width (4 bytes on supported 32-bit processors; 8 bytes on supported 64-bit processor instructions) on the stack will produce undefined results.

Calling conventions for supported 32-bit and supported 64-bit applications are described in more detail below. Any function or protocol may return any valid return code.

All public interfaces of a UEFI module must follow the UEFI calling convention. Public interfaces include the image entry point, UEFI event handlers, and protocol member functions. The type EFIAP is used to indicate conformance to the calling conventions defined in this section. Non public interfaces, such as private functions and static library calls, are not required to follow the UEFI calling conventions and may be optimized by the compiler.

---

**Table 2.2 – continued from previous page**

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Get Next High Monotonic Count</td>
<td>Subsumes the platform’s monotonic counter functionality.</td>
</tr>
<tr>
<td>ResetSystem()</td>
<td>Resets all processors and devices and reboots the system.</td>
</tr>
<tr>
<td>Update Capsule</td>
<td>Passes capsules to the firmware with both virtual and physical mapping.</td>
</tr>
<tr>
<td>QueryCapsuleCapabilities()</td>
<td>Returns if the capsule can be supported via UpdateCapsule().</td>
</tr>
<tr>
<td>QueryVariableInfo()</td>
<td>Returns information about the EFI variable store.</td>
</tr>
</tbody>
</table>

---

2.3. Calling Conventions 20
2.3.1 Data Types

See the table below which lists the common data types that are used in the interface definitions, and the following table, Modifiers for Common UEFI Data Types, lists their modifiers. Unless otherwise specified all data types are naturally aligned. Structures are aligned on boundaries equal to the largest internal datum of the structure and internal data are implicitly padded to achieve natural alignment.

The values of the pointers passed into or returned by the UEFI interfaces must provide natural alignment for the underlying types.

Common UEFI Data Types

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BOOLEAN</td>
<td>Logical Boolean. 1-byte value containing a 0 for FALSE or a 1 for TRUE. Other values are undefined.</td>
</tr>
<tr>
<td>INTN</td>
<td>Signed value of native width. (4 bytes on supported 32-bit processor instructions, 8 bytes on supported 64-bit processor instructions, 16 bytes on supported 128-bit processor instructions)</td>
</tr>
<tr>
<td>UINTN</td>
<td>Unsigned value of native width. (4 bytes on supported 32-bit processor instructions, 8 bytes on supported 64-bit processor instructions, 16 bytes on supported 128-bit processor instructions)</td>
</tr>
<tr>
<td>INT8</td>
<td>1-byte signed value.</td>
</tr>
<tr>
<td>UINT8</td>
<td>1-byte unsigned value.</td>
</tr>
<tr>
<td>INT16</td>
<td>2-byte signed value.</td>
</tr>
<tr>
<td>UINT16</td>
<td>2-byte unsigned value.</td>
</tr>
<tr>
<td>INT32</td>
<td>4-byte signed value.</td>
</tr>
<tr>
<td>UINT32</td>
<td>4-byte unsigned value.</td>
</tr>
<tr>
<td>INT64</td>
<td>8-byte signed value.</td>
</tr>
<tr>
<td>UINT64</td>
<td>8-byte unsigned value.</td>
</tr>
<tr>
<td>INT128</td>
<td>16-byte signed value.</td>
</tr>
<tr>
<td>UINT128</td>
<td>16-byte unsigned value.</td>
</tr>
<tr>
<td>CHAR8</td>
<td>1-byte character. Unless otherwise specified, all 1-byte or ASCII characters and strings are stored in 8-bit ASCII encoding format, using the ISO-Latin-1 character set.</td>
</tr>
<tr>
<td>CHAR16</td>
<td>2-byte Character. Unless otherwise specified all characters and strings are stored in the UCS-2 encoding format as defined by Unicode 2.1 and ISO/IEC 10646 standards.</td>
</tr>
<tr>
<td>VOID</td>
<td>Undeclared type.</td>
</tr>
<tr>
<td>EFI_GUID</td>
<td>128-bit buffer containing a unique identifier value. Unless otherwise specified, aligned on a 64-bit boundary.</td>
</tr>
<tr>
<td>EFI_STATUS</td>
<td>Status code. Type UINTN.</td>
</tr>
<tr>
<td>EFI_HANDLE</td>
<td>A collection of related interfaces. Type VOID *.</td>
</tr>
<tr>
<td>EFI_EVENT</td>
<td>Handle to an event structure. Type VOID * .</td>
</tr>
<tr>
<td>EFI_LBA</td>
<td>Logical block address. Type UINT64.</td>
</tr>
<tr>
<td>EFI_TPL</td>
<td>Task priority level. Type UINTN.</td>
</tr>
<tr>
<td>EFI_MAC_ADDRESS</td>
<td>32-byte buffer containing a network Media Access Control address.</td>
</tr>
<tr>
<td>EFI_IPv4_ADDRESS</td>
<td>4-byte buffer. An IPv4 internet protocol address.</td>
</tr>
<tr>
<td>EFI_IP_ADDRESS</td>
<td>16-byte buffer aligned on a 4-byte boundary. An IPv4 or IPv6 internet protocol address.</td>
</tr>
</tbody>
</table>

continues on next page
Table 2.3 – continued from previous page

<table>
<thead>
<tr>
<th>&lt;Enumerated Type&gt;</th>
<th>Element of a standard ANSI C enum type declaration. Type INT32 or UINT32. ANSI C does not define the size of sign of an enum so they should never be used in structures. ANSI C integer promotion rules make INT32 or UINT32 interchangeable when passed as an argument to a function.</th>
</tr>
</thead>
<tbody>
<tr>
<td>sizeof (VOID *)</td>
<td>4 bytes on supported 32-bit processor instructions. 8 bytes on supported 64-bit processor instructions. 16 bytes on supported 128-bit processor.</td>
</tr>
<tr>
<td>Bitfields</td>
<td>Bitfields are ordered such that bit 0 is the least significant bit.</td>
</tr>
</tbody>
</table>

Table 2.4: Modifiers for Common UEFI Data Types

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>IN</td>
<td>Datum is passed to the function.</td>
</tr>
<tr>
<td>OUT</td>
<td>Datum is returned from the function.</td>
</tr>
<tr>
<td>OPTIONAL</td>
<td>Passing the datum to the function is optional, and a NULL may be passed if the value is not supplied.</td>
</tr>
<tr>
<td>CONST</td>
<td>Datum is read-only.</td>
</tr>
<tr>
<td>EFIAPI</td>
<td>Defines the calling convention for UEFI interfaces.</td>
</tr>
</tbody>
</table>

2.3.2 IA-32 Platforms

All functions are called with the C language calling convention. The general-purpose registers that are volatile across function calls are eax, ecx, and edx. All other general-purpose registers are nonvolatile and are preserved by the target function. In addition, unless otherwise specified by the function definition, all other registers are preserved.

Firmware boot ‘services and runtime services run in the following processor execution mode prior to the OS calling ExitBootServices():

- Uniprocessor, as described in chapter 8.4 of:
  - Intel 64 and IA-32 Architectures Software Developer’s Manual
  - Volume 3, System Programming Guide, Part 1
  - Order Number: 253668-033US, December 2009
  - See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Intel Processor Manuals.”
- Protected mode
- Paging mode may be enabled. If paging mode is enabled, PAE (Physical Address Extensions) mode is recommended. If paging mode is enabled, any memory space defined by the UEFI memory map is identity mapped (virtual address equals physical address). The mappings to other regions are undefined and may vary from implementation to implementation.
- Selectors are set to be flat and are otherwise not used
- Interrupts are enabled-though no interrupt services are supported other than the UEFI boot services timer functions (All loaded device drivers are serviced synchronously by “polling.”)
- Direction flag in EFLAGS is clear
- Other general purpose flag registers are undefined
- 128 KiB, or more, of available stack space
- The stack must be 16-byte aligned. Stack may be marked as non-executable in identity mapped page tables.
• Floating-point control word must be initialized to 0x027F (all exceptions masked, double-precision, round-to-nearest)

• Multimedia-extensions control word (if supported) must be initialized to 0x1F80 (all exceptions masked, round-to-nearest, flush to zero for masked underflow).

• CR0.EM must be zero

• CR0.TS must be zero

An application written to this specification may alter the processor execution mode, but the UEFI image must ensure firmware boot services and runtime services are executed with the prescribed execution environment.

After an Operating System calls ExitBootServices(), firmware boot services are no longer available and it is illegal to call any boot service. After ExitBootServices, firmware runtime services are still available and may be called with paging enabled and virtual address pointers if SetVirtualAddressMap() has been called describing all virtual address ranges used by the firmware runtime service. For an operating system to use any UEFI runtime services, it must:

• Preserve all memory in the memory map marked as runtime code and runtime data

• Call the runtime service functions, with the following conditions:
  
  – In protected mode
  
  – Paging may or may not be enabled, however if paging is enabled and SetVirtualAddressMap() has not been called, any memory space defined by the UEFI memory map is identity mapped (virtual address equals physical address), although the attributes of certain regions may not have all read, write, and execute attributes or be unmarked for purposes of platform protection. The mappings to other regions are undefined and may vary from implementation to implementation. See description of SetVirtualAddressMap() for details of memory map after this function has been called.

  – Direction flag in EFLAGS clear
  
  – 4 KiB, or more, of available stack space
  
  – The stack must be 16-byte aligned

  – Floating-point control word must be initialized to 0x027F (all exceptions masked, double-precision, round-to-nearest)

  – Multimedia-extensions control word (if supported) must be initialized to 0x1F80 (all exceptions masked, round-to-nearest, flush to zero for masked underflow)

  – CR0.EM must be zero

  – CR0.TS must be zero

  – Interrupts disabled or enabled at the discretion of the caller

• ACPI Tables loaded at boot time can be contained in memory of type EfiACPIReclaimMemory (recommended) or EfiACPIMemoryNVS. ACPI FACS must be contained in memory of type EfiACPIMemoryNVS.

• The system firmware must not request a virtual mapping for any memory descriptor of type EfiACPIReclaimMemory or EfiACPIMemoryNVS.

• EFI memory descriptors of type EfiACPIReclaimMemory and EfiACPIMemoryNVS must be aligned on a 4 KiB boundary and must be a multiple of 4 KiB in size.

• Any UEFI memory descriptor that requests a virtual mapping via the EFI_MEMORY_DESCRIPTOR having the EFI_MEMORY_RUNTIME bit set must be aligned on a 4 KiB boundary and must be a multiple of 4 KiB in size.

• An ACPI Memory Op-region must inherit cacheability attributes from the UEFI memory map. If the system memory map does not contain cacheability attributes, the ACPI Memory Op-region must inherit its cacheability
attributes from the ACPI name space. If no cacheability attributes exist in the system memory map or the ACPI name space, then the region must be assumed to be non-cacheable.

- ACPI tables loaded at runtime must be contained in memory of type EfiACPIMemoryNVS. The cacheability attributes for ACPI tables loaded at runtime should be defined in the UEFI memory map. If no information about the table location exists in the UEFI memory map, cacheability attributes may be obtained from ACPI memory descriptors. If no information about the table location exists in the UEFI memory map or ACPI memory descriptors, the table is assumed to be non-cached.

- In general, UEFI Configuration Tables loaded at boot time (e.g., SMBIOS table) can be contained in memory of type EfiRuntimeServicesData (recommended), EfiBootServicesData, EfiACPIReclaimMemory or EfiACPIMemoryNVS. Tables loaded at runtime must be contained in memory of type EfiRuntimeServicesData (recommended) or EfiACPIMemoryNVS.

**Note:** Previous EFI specifications allowed ACPI tables loaded at runtime to be in the EfiReservedMemoryType and there was no guidance provided for other EFI Configuration Tables. EfiReservedMemoryType is not intended to be used for the storage of any EFI Configuration Tables. Also, only OSes conforming to the UEFI Specification are guaranteed to handle SMBIOS table in memory of type EfiBootServicesData.

### 2.3.2.1 Handoff State

When a 32-bit UEFI OS is loaded, the system firmware hands off control to the OS in flat 32-bit mode. All descriptors are set to their 4GiB limits so that all of memory is accessible from all segments.

The Figure below (Stack After AddressOfEntryPoint Called, IA-32) shows the stack after AddressOfEntryPoint in the image's PE32+ header has been called on supported 32-bit systems. All UEFI image entry points take two parameters. These are the image handle of the UEFI image, and a pointer to the EFI System Table.

![Stack After AddressOfEntryPoint Called, IA-32](image)

**Fig. 2.2: Stack After AddressOfEntryPoint Called, IA-32**

### 2.3.2.2 Calling Convention

All functions are called with the C language calling convention. The general-purpose registers that are volatile across function calls are eax, ecx, and edx. All other general-purpose registers are nonvolatile and are preserved by the target function.

In addition, unless otherwise specified by the function definition, all other CPU registers (including MMX and XMM) are preserved.

The floating point status register is not preserved by the target function. The floating point control register and MMX control register are saved by the target function.

### 2.3. Calling Conventions

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**Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A**

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attributes from the ACPI name space. If no cacheability attributes exist in the system memory map or the ACPI name space, then the region must be assumed to be non-cacheable.

- ACPI tables loaded at runtime must be contained in memory of type EfiACPIMemoryNVS. The cacheability attributes for ACPI tables loaded at runtime should be defined in the UEFI memory map. If no information about the table location exists in the UEFI memory map, cacheability attributes may be obtained from ACPI memory descriptors. If no information about the table location exists in the UEFI memory map or ACPI memory descriptors, the table is assumed to be non-cached.

- In general, UEFI Configuration Tables loaded at boot time (e.g., SMBIOS table) can be contained in memory of type EfiRuntimeServicesData (recommended), EfiBootServicesData, EfiACPIReclaimMemory or EfiACPIMemoryNVS. Tables loaded at runtime must be contained in memory of type EfiRuntimeServicesData (recommended) or EfiACPIMemoryNVS.

**Note:** Previous EFI specifications allowed ACPI tables loaded at runtime to be in the EfiReservedMemoryType and there was no guidance provided for other EFI Configuration Tables. EfiReservedMemoryType is not intended to be used for the storage of any EFI Configuration Tables. Also, only OSes conforming to the UEFI Specification are guaranteed to handle SMBIOS table in memory of type EfiBootServicesData.

### 2.3.2.1 Handoff State

When a 32-bit UEFI OS is loaded, the system firmware hands off control to the OS in flat 32-bit mode. All descriptors are set to their 4GiB limits so that all of memory is accessible from all segments.

The Figure below (Stack After AddressOfEntryPoint Called, IA-32) shows the stack after AddressOfEntryPoint in the image's PE32+ header has been called on supported 32-bit systems. All UEFI image entry points take two parameters. These are the image handle of the UEFI image, and a pointer to the EFI System Table.

![Stack After AddressOfEntryPoint Called, IA-32](image)

**Fig. 2.2: Stack After AddressOfEntryPoint Called, IA-32**

### 2.3.2.2 Calling Convention

All functions are called with the C language calling convention. The general-purpose registers that are volatile across function calls are eax, ecx, and edx. All other general-purpose registers are nonvolatile and are preserved by the target function.

In addition, unless otherwise specified by the function definition, all other CPU registers (including MMX and XMM) are preserved.

The floating point status register is not preserved by the target function. The floating point control register and MMX control register are saved by the target function.
If the return value is a float or a double, the value is returned in ST(0).

### 2.3.3 Intel® Itanium®-Based Platforms

UEFI executes as an extension to the SAL execution environment with the same rules as laid out by the SAL specification.

During boot services time the processor is in the following execution mode:

- Uniprocessor, as detailed in chapter 13.1.2 of:
  - Intel Itanium Architecture Software Developer’s Manual
  - Volume 2: System Architecture
  - Revision 2.2
  - January 2006
  - See “Links to UEFI-Related Documents” ([http://uefi.org/uefi](http://uefi.org/uefi)) under the heading “Intel Itanium Documentation”.
    - Document Number: 245318-005
- Physical mode
- 128 KiB, or more, of available stack space
- 16 KiB, or more, of available backing store space
  - FPSR.traps: Set to all 1’s (all exceptions disabled)
  - FPSR.sf0:
    - .pc: Precision Control - 11b (extended precision)
    - .rc: Rounding Control - 0 (round to nearest)
    - .wre: Widest Range Exponent - 0 (IEEE mode)
    - .ftz: Flush-To-Zero mode - 0 (off)
- FPSR.sf1:
  - .td: Traps Disable = 1 (traps disabled)
  - .pc: Precision Control - 11b (extended precision)
  - .rc: Rounding Control - 0 (round to nearest)
  - .wre: Widest Range Exponent - 1 (full register exponent range)
  - .ftz: Flush-To-Zero mode - 0 (off)
- FPSR.sf2,3:
  - .td: Traps Disable = 1 (traps disabled)
  - .pc: Precision Control - 11b (extended precision)
  - .rc: Rounding Control - 0 (round to nearest)
  - .wre: Widest Range Exponent - 0 (IEEE mode)
  - .ftz: Flush-To-Zero mode - 0 (off)
An application written to this specification may alter the processor execution mode, but the UEFI image must ensure firmware boot services and runtime services are executed with the prescribed execution environment.

After an Operating System calls ExitBootServices(), firmware boot services are no longer available and it is illegal to call any boot service. After ExitBootServices, firmware runtime services are still available. When calling runtime services, paging may or may not be enabled, however if paging is enabled and SetVirtualAddressMap() has not been called, any memory space defined by the UEFI memory map is identity mapped (virtual address equals physical address). The mappings to other regions are undefined and may vary from implementation to implementation. See description of SetVirtualAddressMap() for details of memory map after this function has been called. After ExitBootServices(), runtime service functions may be called with interrupts disabled or enabled at the discretion of the caller.

- ACPI tables loaded at boot time can be contained in memory of type EfiACPIReclaimMemory (recommended) or EfiACPIMemoryNVS. ACPI FACS must be contained in memory of type EfiACPIMemoryNVS.

- The system firmware must not request a virtual mapping for any memory descriptor of type EfiACPIReclaimMemory or EfiACPIMemoryNVS.

- EFI memory descriptors of type EfiACPIReclaimMemory and EfiACPIMemoryNVS must be aligned on an 8 KiB boundary and must be a multiple of 8 KiB in size.

- Any UEFI memory descriptor that requests a virtual mapping via the EFI_MEMORY_DESCRIPTOR having the EFI_MEMORY_RUNTIME bit set must be aligned on an 8 KiB boundary and must be a multiple of 8 KiB in size.

- An ACPI Memory Op-region must inherit cacheability attributes from the UEFI memory map. If the system memory map does not contain cacheability attributes the ACPI Memory Op-region must inherit its cacheability attributes from the ACPI name space. If no cacheability attributes exist in the system memory map or the ACPI name space, then the region must be assumed to be non-cacheable.

- ACPI tables loaded at runtime must be contained in memory of type EfiACPIMemoryNVS. The cacheability attributes for ACPI tables loaded at runtime should be defined in the UEFI memory map. If no information about the table location exists in the UEFI memory map, cacheability attributes may be obtained from ACPI memory descriptors. If no information about the table location exists in the UEFI memory map or ACPI memory descriptors, the table is assumed to be non-cached.

- In general, Configuration Tables loaded at boot time (e.g., SMBIOS table) can be contained in memory of type EfiRuntimeServicesData (recommended), EfiBootServicesData, EfiACPIReclaimMemory or EfiACPIMemoryNVS. Tables loaded at runtime must be contained in memory of type EfiRuntimeServicesData (recommended) or EfiACPIMemoryNVS.

Note: Previous EFI specifications allowed ACPI tables loaded at runtime to be in the EfiReservedMemoryType and there was no guidance provided for other EFI Configuration Tables. EfiReservedMemoryType is not intended to be used by firmware. Also, only OSes conforming to the UEFI Specification are guaranteed to handle SMBIOS table in memory of type EfiBootServicesData.

Refer to the IA-64 System Abstraction Layer Specification (Appendix Q — References) for details.

UEFI procedures are invoked using the P64 C calling conventions defined for Intel® Itanium® -based applications. Refer to the document 64 Bit Runtime Architecture and Software Conventions for IA-64 (Appendix Q — References) for more information.
2.3.3.1 Handoff State

UEFI uses the standard P64 C calling conventions that are defined for Itanium-based operating systems. The Figure below shows the stack after ImageEntryPoint has been called on Itanium-based systems. The arguments are also stored in registers: out0 contains EFI_HANDLE and out1 contains the address of the EFI_SYSTEM_TABLE. The gp for the UEFI Image will have been loaded from the plabel pointed to by the AddressOfEntryPoint in the image’s PE32+ header. All UEFI image entry points take two parameters. These are the image handle of the image, and a pointer to the System Table.

![Fig. 2.3: Stack after AddressOfEntryPoint Called, Itanium-based Systems](image)

The SAL specification (Appendix Q — References) defines the state of the system registers at boot handoff. The SAL specification also defines which system registers can only be used after UEFI boot services have been properly terminated.

2.3.3.2 Calling Convention

UEFI executes as an extension to the SAL execution environment with the same rules as laid out by the SAL specification. UEFI procedures are invoked using the P64 C calling conventions defined for Intel® Itanium®-based applications. Refer to the document 64 Bit Runtime Architecture and Software Conventions for IA-64 (see the index appendix for more information).

For floating point, functions may only use the lower 32 floating point registers Return values appear in f8-f15 registers. Single, double, and extended values are all returned using the appropriate format. Registers f6-f7 are local registers and are not preserved for the caller. All other floating point registers are preserved. Note that, when compiling UEFI programs, a special switch will likely need to be specified to guarantee that the compiler does not use f32-f127, which are not normally preserved in the regular calling convention for Itanium. A procedure using one of the preserved floating point registers must save and restore the caller’s original contents without generating a NaT consumption fault.

Floating point arguments are passed in f8-f15 registers when possible. Parameters beyond the registers appear in memory, as explained in Section 8.5 of the Itanium Software Conventions and Runtime Architecture Guide. Within the called function, these are local registers and are not preserved for the caller. Registers f6-f7 are local registers and are not preserved for the caller. All other floating point registers are preserved. Note that, when compiling UEFI programs, a special switch will likely need to be specified to guarantee that the compiler does not use f32-f127, which are not normally preserved in the regular calling convention for Itanium. A procedure using one of the preserved floating point registers must save and restore the caller’s original contents without generating a NaT consumption fault.

The floating point status register must be preserved across calls to a target function. Flags fields in SF1,2,3 are not preserved for the caller. Flags fields in SF0 upon return will reflect the value passed in, and with bits set to 1 corresponding to any IEEE exceptions detected on non-speculative floating-point operations executed as part of the callee.

Floating-point operations executed by the callee may require software emulation. The caller must be prepared to handle FP Software Assist (FPSWA) interruptions. Callees should not raise IEEE traps by changing FPSR.traps bits to 0 and then executing floating-point operations that raise such traps.

2.3. Calling Conventions 27
2.3.4 x64 Platforms

All functions are called with the C language calling convention. *Detailed Calling Conventions* for more detail.

During boot services time the processor is in the following execution mode:

- Uniprocessor, as described in chapter 8.4 of:
  - See “Links to UEFI-Related Documents” ([http://uefi.org/uefi](http://uefi.org/uefi)) under the heading “Intel Processor Manuals”.
- Paging mode is enabled and any memory space defined by the UEFI memory map is identity mapped (virtual address equals physical address), although the attributes of certain regions may not have all read, write, and execute attributes or be unmarked for purposes of platform protection. The mappings to other regions, such as those for unaccepted memory, are undefined and may vary from implementation to implementation.
- Selectors are set to be flat and are otherwise not used.
- Interrupts are enabled—though no interrupt services are supported other than the UEFI boot services timer functions (All loaded device drivers are serviced synchronously by “polling.”)
- Direction flag in EFLAGS is clear
- Other general purpose flag registers are undefined
- 128 KiB, or more, of available stack space
- The stack must be 16-byte aligned. Stack may be marked as non-executable in identity mapped page tables.
- Floating-point control word must be initialized to 0x037F (all exceptions masked, double-extended-precision, round-to-nearest)
- Multimedia-extensions control word (if supported) must be initialized to 0x1F80 (all exceptions masked, round-to-nearest, flush to zero for masked underflow).
- CR0.EM must be zero
- CR0.TS must be zero

For an operating system to use any UEFI runtime services, it must:

- Preserve all memory in the memory map marked as runtime code and runtime data
- Call the runtime service functions, with the following conditions:
  - In long mode, in 64-bit mode
  - Paging enabled
  - All selectors set to be flat with virtual = physical address. If the UEFI OS loader or OS used SetVirtualAddressMap() to relocate the runtime services in a virtual address space, then this condition does not have to be met. See description *SetVirtualAddressMap()* for details of memory map after this function has been called.
- Direction flag in EFLAGS clear
- 4 KiB, or more, of available stack space
- The stack must be 16-byte aligned
- Floating-point control word must be initialized to 0x037F (all exceptions masked, double-extended-precision, round-to-nearest)
• Multimedia-extensions control word (if supported) must be initialized to 0x1F80 (all exceptions masked, round-to-nearest, flush to zero for masked underflow)

• CR0.EM must be zero

• CR0.TS must be zero

• Interrupts may be disabled or enabled at the discretion of the caller.

• ACPI Tables loaded at boot time can be contained in memory of type EfiACPIReclaimMemory (recommended) or EfiACPIMemoryNVS. ACPI FACS must be contained in memory of type EfiACPIMemoryNVS.

• The system firmware must not request a virtual mapping for any memory descriptor of type EfiACPIReclaimMemory or EfiACPIMemoryNVS.

• EFI memory descriptors of type EfiACPIReclaimMemory and EfiACPIMemoryNVS must be aligned on a 4 KiB boundary and must be a multiple of 4 KiB in size.

• Any UEFI memory descriptor that requests a virtual mapping via the EFI_MEMORY_DESCRIPTOR having the EFI_MEMORY_RUNTIME bit set must be aligned on a 4 KiB boundary and must be a multiple of 4 KiB in size.

• An ACPI Memory Op-region must inherit cacheability attributes from the UEFI memory map. If the system memory map does not contain cacheability attributes, the ACPI Memory Op-region must inherit its cacheability attributes from the ACPI name space. If no cacheability attributes exist in the system memory map or the ACPI name space, then the region must be assumed to be non-cacheable.

• ACPI tables loaded at runtime must be contained in memory of type EfiACPIMemoryNVS. The cacheability attributes for ACPI tables loaded at runtime should be defined in the UEFI memory map. If no information about the table location exists in the UEFI memory map, cacheability attributes may be obtained from ACPI memory descriptors. If no information about the table location exists in the UEFI memory map or ACPI memory descriptors, the table is assumed to be non-cached.

• In general, UEFI Configuration Tables loaded at boot time (e.g., SMBIOS table) can be contained in memory of type EfiRuntimeServicesData (recommended), EfiBootServicesData, EfiACPIReclaimMemory or EfiACPIMemoryNVS. Tables loaded at runtime must be contained in memory of type EfiRuntimeServicesData (recommended) or EfiACPIMemoryNVS.

Note: Previous EFI specifications allowed ACPI tables loaded at runtime to be in the EfiReservedMemoryType and there was no guidance provided for other EFI Configuration Tables. EfiReservedMemoryType is not intended to be used by firmware. Also, only OSes conforming to the UEFI Specification are guaranteed to handle SMBIOS table in memory of type EfiBootServicesData.

2.3.4.1 Handoff State

Rcx - EFI_HANDLE
Rdx - EFI_SYSTEM_TABLE*
RSP - <return address>

2.3. Calling Conventions
2.3.4.2 Detailed Calling Conventions

The caller passes the first four integer arguments in registers. The integer values are passed from left to right in Rcx, Rdx, R8, and R9 registers. The caller passes arguments five and above onto the stack. All arguments must be right-justified in the register in which they are passed. This ensures the callee can process only the bits in the register that are required.

The caller passes arrays and strings via a pointer to memory allocated by the caller. The caller passes structures and unions of size 8, 16, 32, or 64 bits as if they were integers of the same size. The caller is not allowed to pass structures and unions of other than these sizes and must pass these unions and structures via a pointer.

The callee must dump the register parameters into their shadow space if required. The most common requirement is to take the address of an argument.

If the parameters are passed through varargs then essentially the typical parameter passing applies, including spilling the fifth and subsequent arguments onto the stack. The callee must dump the arguments that have their address taken.

Return values that fix into 64-bits are returned in the Rax register. If the return value does not fit within 64-bits, then the caller must allocate and pass a pointer for the return value as the first argument, Rcx. Subsequent arguments are then shifted one argument to the right, so for example argument one would be passed in Rdx. User-defined types to be returned must be 1, 2, 4, 8, 16, 32, or 64 bits in length.

The registers Rax, Rcx Rdx R8, R9, R10, R11, and XMM0-XMM5 are volatile and are, therefore, destroyed on function calls.

The registers RBX, RBP, RDI, RSI, R12, R13, R14, R15, and XMM6-XMM15 are considered nonvolatile and must be saved and restored by a function that uses them.

Function pointers are pointers to the label of the respective function and don’t require special treatment.

A caller must always call with the stack 16-byte aligned.

For MMX, XMM and floating-point values, return values that can fit into 64-bits are returned through RAX (including MMX types). However, XMM 128-bit types, floats, and doubles are returned in XMM0. The floating point status register is not saved by the target function. Floating-point and double-precision arguments are passed in XMM0 - XMM3 (up to 4) with the integer slot (RCX, RDX, R8, and R9) that would normally be used for that cardinal slot being ignored (see example) and vice versa. XMM types are never passed by immediate value but rather a pointer will be passed to memory allocated by the caller. MMX types will be passed as if they were integers of the same size. Callees must not unmask exceptions without providing correct exception handlers.

In addition, unless otherwise specified by the function definition, all other CPU registers (including MMX and XMM) are preserved.

2.3.4.3 Enabling Paging or Alternate Translations in an Application

Boot Services define an execution environment where paging is not enabled (supported 32-bit) or where translations are enabled but mapped virtual equal physical (x64) and this section will describe how to write an application with alternate translations or with paging enabled. Some Operating Systems require the OS Loader to be able to enable OS required translations at Boot Services time.

If a UEFI application uses its own page tables, GDT or IDT, the application must ensure that the firmware executes with each supplanted data structure. There are two ways that firmware conforms to this specification can execute when the application has paging enabled.

- Explicit firmware call
- Firmware preemption of application via timer event
An application with translations enabled can restore firmware required mapping before each UEFI call. However the possibility of preemption may require the translation enabled application to disable interrupts while alternate translations are enabled. It’s legal for the translation enabled application to enable interrupts if the application catches the interrupt and restores the EFI firmware environment prior to calling the UEFI interrupt ISR. After the UEFI ISR context is executed it will return to the translation enabled application context and restore any mappings required by the application.

2.3.5 AArch32 Platforms

All functions are called with the C language calling convention specified in Detailed Calling Convention. In addition, the invoking OSs can assume that unaligned access support is enabled if it is present in the processor.

During boot services time the processor is in the following execution mode:

- Unaligned access should be enabled if supported; Alignment faults are enabled otherwise.
- Uniprocessor.
- A privileged mode.
- The MMU is enabled (CP15 c1 System Control Register (SCTLR) SCTLR.M=1) and any RAM defined by the UEFI memory map is identity mapped (virtual address equals physical address). The mappings to other regions are undefined and may vary from implementation to implementation
- The core will be configured as follows (common across all processor architecture revisions):
  - MMU enabled
  - Instruction and Data caches enabled
  - Access flag disabled
  - Translation remap disabled
  - Little endian mode
  - Domain access control mechanism (if supported) will be configured to check access permission bits in the page descriptor
  - Fast Context Switch Extension (FCSE) must be disabled

This will be achieved by:

- Configuring the CP15 c1 System Control Register (SCTLR) as follows: I=1, C=1, B=0, TRE=0, AFE=0, M=1
- Configuring the CP15 c3 Domain Access Control Register (DACR) to 0x33333333.
- Configuring the CP15 c1 System Control Register (SCTLR), A=1 on ARMv4 and ARMv5, A=0, U=1 on ARMv6 and ARMv7.

The state of other system control register bits is not dictated by this specification.

- Implementations of boot services will enable architecturally manageable caches and TLBs i.e., those that can be managed directly using CP15 operations using mechanisms and procedures defined in the ARM Architecture Reference Manual. They should not enable caches requiring platform information to manage or invoke non-architectural cache/TLB lockdown mechanisms
- MMU configuration — Implementations must use only 4k pages and a single translation base register. On devices supporting multiple translation base registers, TTBR0 must be used solely. The binding does not mandate whether page tables are cached or un-cached.
On processors implementing the ARMv4 through ARMv6K architecture definitions, the core is additionally configured to disable extended page tables support, if present.

This will be achieved by configuring the CP15 c1 System Control Register (SCTLR) as follows: \( XP=0 \)

On processors implementing the ARMv7 and later architecture definitions, the core will be configured to enable the extended page table format and disable the TEX remap mechanism.

This will be achieved by configuring the CP15 c1 System Control Register (SCTLR) as follows: \( XP=1, \ TRE=0 \)

- Interrupts are enabled—though no interrupt services are supported other than the UEFI boot services timer functions (All loaded device drivers are serviced synchronously by “polling.”)

- 128 KiB or more of available stack space

For an operating system to use any runtime services, it must:

- Preserve all memory in the memory map marked as runtime code and runtime data

- Call the runtime service functions, with the following conditions:
  - In a privileged mode.
  - The system address regions described by all the entries in the EFI memory map that have the EFI_MEMORY_RUNTIME bit set must be identity mapped as they were for the EFI boot environment. If the OS Loader or OS used SetVirtualAddressMap() to relocate the runtime services in a virtual address space, then this condition does not have to be met. See description of SetVirtualAddressMap() for details of memory map after this function has been called.
  - The processor must be in a mode in which it has access to the system address regions specified in the EFI memory map with the EFI_MEMORY_RUNTIME bit set.
  - 4 KiB, or more, of available stack space
  - Interrupts may be disabled or enabled at the discretion of the caller

An application written to this specification may alter the processor execution mode, but the invoking OS must ensure firmware boot services and runtime services are executed with the prescribed execution environment.

If ACPI is supported:

- ACPI Tables loaded at boot time can be contained in memory of type EfiACPIReclaimMemory (recommended) or EfiACPIMemoryNVS. ACPI FACS must be contained in memory of type EfiACPIMemoryNVS

- The system firmware must not request a virtual mapping for any memory descriptor of type EfiACPIReclaimMemory or EfiACPIMemoryNVS.

- EFI memory descriptors of type EfiACPIReclaimMemory and EfiACPIMemoryNVS must be aligned on a 4 KiB boundary and must be a multiple of 4 KiB in size.

- Any UEFI memory descriptor that requests a virtual mapping via the EFI_MEMORY_DESCRIPTOR having the EFI_MEMORY_RUNTIME bit set must be aligned on a 4 KiB boundary and must be a multiple of 4 KiB in size.

- An ACPI Memory Op-region must inherit cacheability attributes from the UEFI memory map. If the system memory map does not contain cacheability attributes, the ACPI Memory Op-region must inherit its cacheability attributes from the ACPI name space. If no cacheability attributes exist in the system memory map or the ACPI name space, then the region must be assumed to be non-cacheable.

- ACPI tables loaded at runtime must be contained in memory of type EfiACPIMemoryNVS. The cacheability attributes for ACPI tables loaded at runtime should be defined in the UEFI memory map. If no information about the table location exists in the UEFI memory map, cacheability attributes may be obtained from ACPI
memory descriptors. If no information about the table location exists in the UEFI memory map or ACPI memory descriptors, the table is assumed to be non-cached.

- In general, UEFI Configuration Tables loaded at boot time (e.g., SMBIOS table) can be contained in memory of type EfiRuntimeServicesData (recommended), EfiBootServicesData, EfiACPIReclaimMemory or EfiACPIMemoryNVS. Tables loaded at runtime must be contained in memory of type EfiRuntimeServicesData (recommended) or EfiACPIMemoryNVS.

**Note:** Previous EFI specifications allowed ACPI tables loaded at runtime to be in the EfiReservedMemoryType and there was no guidance provided for other EFI Configuration Tables. EfiReservedMemoryType is not intended to be used by firmware. Also, only OSes conforming to the UEFI Specification are guaranteed to handle SMBIOS table in memory of type EfiBootServicesData.

### 2.3.5.1 Handoff State

R0 - EFI_HANDLE

R1 - EFI_SYSTEM_TABLE*

R14 - Return Address

### 2.3.5.2 Enabling Paging or Alternate Translations in an Application

Boot Services define a specific execution environment. This section will describe how to write an application that creates an alternative execution environment. Some Operating Systems require the OS Loader to be able to enable OS required translations at Boot Services time, and make other changes to the UEFI defined execution environment.

If a UEFI application uses its own page tables, or other processor state, the application must ensure that the firmware executes with each supplanted functionality. There are two ways that firmware conforming to this specification can execute in this alternate execution environment:

- Explicit firmware call
- Firmware preemption of application via timer event

An application with an alternate execution environment can restore the firmware environment before each UEFI call. However the possibility of preemption may require the alternate execution-enabled application to disable interrupts while the alternate execution environment is active. It’s legal for the alternate execution environment enabled application to enable interrupts if the application catches the interrupt and restores the EFI firmware environment prior to calling the UEFI interrupt ISR. After the UEFI ISR context is executed it will return to the alternate execution environment enabled application context.

An alternate execution environment created by a UEFI application must not change the semantics or behavior of the MMU configuration created by the UEFI firmware prior to invoking ExitBootServices(), including the bit layout of the page table entries.

After an OS loader calls ExitBootServices() it should immediately configure the exception vector to point to appropriate code.

### 2.3. Calling Conventions
2.3.5.3 Detailed Calling Convention

The base calling convention for the ARM binding is defined here:

Procedure Call Standard for the ARM Architecture V2.06 (or later)

See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Arm Architecture Base Calling Convention”.

This binding further constrains the calling convention in these ways:

- Calls to UEFI defined interfaces must be done assuming that the target code requires the ARM instruction set state. Images are free to use other instruction set states except when invoking UEFI interfaces.
- Floating point, SIMD, vector operations and other instruction set extensions must not be used.
- Only little endian operation is supported.
- The stack will maintain 8 byte alignment as described in the AAPCS for public interfaces.
- Use of coprocessor registers for passing call arguments must not be used.
- Structures (or other types larger than 64-bits) must be passed by reference and not by value.
- The EFI ARM platform binding defines register r9 as an additional callee-saved variable register.

2.3.6 AArch64 Platforms

AArch64 UEFI will only execute 64-bit ARM code, as the ARMv8 architecture does not allow for the mixing of 32-bit and 64-bit code at the same privilege level.

All functions are called with the C language calling convention specified in Detailed calling Convention section below. During boot services only a single processor is used for execution. All secondary processors must be either powered off or held in a quiescent state.

The primary processor is in the following execution mode:

- Unaligned access must be enabled.
- Use the highest 64 bit non secure privilege level available; Non-secure EL2 (Hyp) or Non-secure EL1(Kernel).
- The MMU is enabled and any RAM defined by the UEFI memory map is identity mapped (virtual address equals physical address). The mappings to other regions are undefined and may vary from implementation to implementation.
- The core will be configured as follows:
  - MMU enabled
  - Instruction and Data caches enabled
  - Little endian mode
  - Stack Alignment Enforced
  - NOT Top Byte Ignored
  - Valid Physical Address Space
  - 4K Translation Granule

This will be achieved by:

1. Configuring the System Control Register SCTLR_EL2 or SCTLR_EL1:
   - EE=0, I=1, SA=1, C=1, A=0, M=1
2. Configuring the appropriate Translation Control Register:

- **TCR_EL2**
  - TBI=0
  - PS must contain the valid Physical Address Space Size.
  - TG0=00

- **TCR_EL1**
  - TBI0=0
  - IPS must contain the valid Intermediate Physical Address Space Size.
  - TG0=00

**Note:** The state of other system control register bits is not dictated by this specification.

- All floating point traps and exceptions will be disabled at the relevant exception levels (FPCR=0, CPACR_EL1.FPEN=11, CPTR_EL2.TFP=0). This implies that the FP unit will be enabled by default.

- Implementations of boot services will enable architecturally manageable caches and TLBs i.e., those that can be managed directly using implementation independent registers using mechanisms and procedures defined in the ARM Architecture Reference Manual. They should not enable caches requiring platform information to manage or invoke non-architectural cache/TLB lockdown mechanisms.

- MMU configuration: Implementations must use only 4k pages and a single translation base register. On devices supporting multiple translation base registers, TTBR0 must be used solely. The binding does not mandate whether page tables are cached or un-cached.

- Interrupts are enabled, though no interrupt services are supported other than the UEFI boot services timer functions (All loaded device drivers are serviced synchronously by “polling”). All UEFI interrupts must be routed to the IRQ vector only.

- The architecture generic timer must be initialized and enabled. The Counter Frequency register (CNTFRQ) must be programmed with the timer frequency. Timer access must be provided to non-secure EL1 and EL0 by setting bits EL1PCTEN and EL1PCEN in register CNTHCTL_EL2.

- The system firmware is not expected to initialize EL2 registers that do not have an architectural reset value, except in cases where firmware itself is running at EL2 and needs to do so.

- 128 KiB or more of available stack space

- The ARM architecture allows mapping pages at a variety of granularities, including 4KiB and 64KiB. If a 64KiB physical page contains any 4KiB page with any of the following types listed below, then all 4KiB pages in the 64KiB page must use identical ARM Memory Page Attributes (as described in Map: EFI Cacheability Attributes to AArch64 Memory Types):
  - EfiRuntimeServicesCode
  - EfiRuntimeServicesData
  - EfiReserved
  - EfiACPIMemoryNVS

  Mixed attribute mappings within a larger page are not allowed.

**Note:** This constraint allows a 64K paged based Operating System to safely map runtime services memory.

For an operating system to use any runtime services, Runtime services must:

- Support calls from either the EL1 or the EL2 exception levels.
- Once called, simultaneous or nested calls from EL1 and EL2 are not permitted.
Note: Sequential, non-overlapping, calls from EL1 and EL2 are permitted.

Runtime services are permitted to make synchronous SMC and HVC calls into higher exception levels.

Note: These rules allow Boot Services to start at EL2, and Runtime services to be assigned to an EL1 Operating System. In this case a call to SetVirtualAddressMap() is expected to provide an EL1 appropriate set of mappings.

For an operating system to use any runtime services, it must:

- Enable unaligned access support.
- Preserve all memory in the memory map marked as runtime code and runtime data
- Call the runtime service functions, with the following conditions:
  - From either EL1 or EL2 exception levels.
  - Consistently call runtime services from the same exception level. Sharing of runtime services between different exception levels is not permitted.
  - Runtime services must only be assigned to a single operating system or hypervisor. They must not be shared between multiple guest operating systems.
  - The system address regions described by all the entries in the EFI memory map that have the EFI_MEMORY_RUNTIME bit set must be identity mapped as they were for the EFI boot environment. If the OS Loader or OS used SetVirtualAddressMap() to relocate the runtime services in a virtual address space, then this condition does not have to be met. See description of SetVirtualAddressMap() for details of memory map after this function has been called.
  - The processor must be in a mode in which it has access to the system address regions specified in the EFI memory map with the EFI_MEMORY_RUNTIME bit set.
  - 8 KiB, or more, of available stack space.
  - The stack must be 16-byte aligned (128-bit).
  - Interrupts may be disabled or enabled at the discretion of the caller.

An application written to this specification may alter the processor execution mode, but the invoking OS must ensure firmware boot services and runtime services are executed with the prescribed execution environment.

If ACPI is supported:

- ACPI Tables loaded at boot time can be contained in memory of type EfiACPIReclaimMemory (recommended) or EfiACPIMemoryNVS.
- ACPI FACS must be contained in memory of type EfiACPIMemoryNVS. The system firmware must not request a virtual mapping for any memory descriptor of type EfiACPIReclaimMemory or EfiACPIMemoryNVS.
- EFI memory descriptors of type EfiACPIReclaimMemory and EfiACPIMemoryNVS must be aligned on a 4 KiB boundary and must be a multiple of 4 KiB in size.
- Any UEFI memory descriptor that requests a virtual mapping via the EFI_MEMORY_DESCRIPTOR having the EFI_MEMORY_RUNTIME bit set must be aligned on a 4 KiB boundary and must be a multiple of 4 KiB in size.
- An ACPI Memory Op-region must inherit cacheability attributes from the UEFI memory map. If the system memory map does not contain cacheability attributes, the ACPI Memory Op-region must inherit its cacheability attributes from the ACPI name space. If no cacheability attributes exist in the system memory map or the ACPI name space, then the region must be assumed to be non-cacheable.
- ACPI tables loaded at runtime must be contained in memory of type EfiACPIMemoryNVS. The cacheability attributes for ACPI tables loaded at runtime should be defined in the UEFI memory map. If no information about the table location exists in the UEFI memory map, cacheability attributes may be obtained from ACPI
memory descriptors. If no information about the table location exists in the UEFI memory map or ACPI memory descriptors, the table is assumed to be non-cached.

- In general, UEFI Configuration Tables loaded at boot time (e.g., SMBIOS table) can be contained in memory of type EfiRuntimeServicesData (recommended), EfiBootServicesdata, EfiACPIReclaimMemory or EfiACPIMemoryNVS. Tables loaded at runtime must be contained in memory of type EfiRuntimeServicesData (recommended) or EfiACPIMemoryNVS.

**Note:** Previous EFI specifications allowed ACPI tables loaded at runtime to be in the EfiReservedMemoryType and there was no guidance provided for other EFI Configuration Tables. EfiReservedMemoryType is not intended to be used by firmware. UEFI 2.0 clarified the situation moving forward. Also, only OSes conforming to UEFI Specification are guaranteed to handle SMBIOS table in memory of type EfiBootServiceData.

### 2.3.6.1 Memory types

#### Table 2.5: Map: EFI Cacheability Attributes to AArch64Memory Types

<table>
<thead>
<tr>
<th>EFI Memory Type</th>
<th>ARM Memory Type: MAIR attribute encoding Attr&lt;n&gt; [7:4] [3:0]</th>
<th>ARM Memory Type: Meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_MEMORY_UC  (Not cachable)</td>
<td>0000 0000</td>
<td>Device-nGnRnE (Device non-Gathering, non-Reordering, no Early Write Acknowledgement)</td>
</tr>
<tr>
<td>EFI_MEMORY_WC  (Write combine)</td>
<td>0100 0100</td>
<td>Normal Memory Outer non-cacheable Inner non-cacheable</td>
</tr>
<tr>
<td>EFI_MEMORY_WT  (Write through)</td>
<td>1011 1011</td>
<td>Normal Memory Outer Write-through non-transient Inner Write-through non-transient</td>
</tr>
<tr>
<td>EFI_MEMORY_WB  (Write back)</td>
<td>1111 1111</td>
<td>Normal Memory Outer Write-back non-transient Inner Write-back non-transient</td>
</tr>
<tr>
<td>EFI_MEMORY_UCE</td>
<td>Not used or defined</td>
<td></td>
</tr>
</tbody>
</table>

#### Table 2.6: Map: UEFI Permission Attributes to ARM Paging Attributes

<table>
<thead>
<tr>
<th>EFI Memory Type</th>
<th>ARM Paging Attributes</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_MEMORY_XP</td>
<td>EL2 translation regime: XN Execute never EL1/0 translation regime: UXN Unprivileged execute never</td>
</tr>
<tr>
<td>EFI_MEMORY_RO</td>
<td>Read only access AP[2]=1</td>
</tr>
<tr>
<td>EFI_MEMORY_RP</td>
<td>Not used or defined</td>
</tr>
</tbody>
</table>

### 2.3.6.2 Handoff State

X0 - EFI_HANDLE

X1 - EFI_SYSTEM_TABLE

X30 - Return Address

### 2.3. Calling Conventions
2.3.6.3 Enabling Paging or Alternate Translations in an Application

Boot Services define a specific execution environment. This section will describe how to write an application that creates an alternative execution environment. Some Operating Systems require the OS Loader to be able to enable OS required translations at Boot Services time, and make other changes to the UEFI defined execution environment.

If a UEFI application uses its own page tables, or other processor state, the application must ensure that the firmware executes with each supplanted functionality. There are two ways that firmware conforming to this specification can execute in this alternate execution environment:

- Explicit firmware call
- Firmware preemption of application via timer event

An application with an alternate execution environment can restore the firmware environment before each UEFI call. However the possibility of preemption may require the alternate execution-enabled application to disable interrupts while the alternate execution environment is active. It’s legal for the alternate execution environment enabled application to enable interrupts if the application catches the interrupt and restores the EFI firmware environment prior to calling the UEFI interrupt ISR. After the UEFI ISR context is executed it will return to the alternate execution environment enabled application context.

An alternate execution environment created by a UEFI application must not change the semantics or behavior of the MMU configuration created by the UEFI firmware prior to invoking ExitBootServices(), including the bit layout of the page table entries.

After an OS loader calls ExitBootServices() it should immediately configure the exception vector to point to appropriate code.

2.3.6.4 Detailed Calling Convention

The base calling convention for the AArch64 binding is defined in the document *Procedure Call Standard for the ARM 64-bit Architecture Version A-0.06 (or later)*:

See “Links to UEFI-Related Documents” ([http://uefi.org/uefi](http://uefi.org/uefi)) under the heading “ARM 64-bit Base Calling Convention”

This binding further constrains the calling convention in these ways:

- The AArch64 execution state must not be modified by the callee.
- All code exits, normal and exceptional, must be from the A64 instruction set.
- Floating point and SIMD instructions may be used.
- Optional vector operations and other instruction set extensions may only be used:
  - After dynamically checking for their existence.
  - Saving and then later restoring any additional execution state context.
  - Additional feature enablement or control, such as power, must be explicitly managed.
- Only little endian operation is supported.
- The stack will maintain 16 byte alignment.
- Structures (or other types larger than 64-bits) must be passed by reference and not by value.
- The EFI AArch64 platform binding defines the platform register (r18) as “do not use”. Avoiding use of r18 in firmware makes the code compatible with both a fixed role for r18 defined by the OS platform ABI and the use of r18 by the OS and its applications as a temporary register.
2.3.7 RISC-V Platforms

All functions are called with the C language calling convention. See *Detailed Calling Convention* for more detail. On RISC-V platform, three privileged levels are currently introduced in RISC-V architecture. Beyond the User privilege, Supervisor privilege and Machine privileges cover all aspects of RISC-V system. The privileged instructions are also defined in each privilege level.

<table>
<thead>
<tr>
<th>Level</th>
<th>Encoding</th>
<th>Name</th>
<th>Abbreviation</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>User/Application</td>
<td>U</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>Supervisor</td>
<td>S</td>
</tr>
<tr>
<td>2</td>
<td>10</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>11</td>
<td>Machine</td>
<td>M</td>
</tr>
</tbody>
</table>

A RISC-V platform can contain one or more RISC-V cores and other components such as physical memory, fixed-function accelerators and I/O devices. The term RISC-V core refers to a component which contains an independent instruction fetch unit. A RISC-V core may have multiple RISC-V-compatible hardware threads, or hart. RISC-V UEFI firmware could be executed in either Machine mode or Supervisor mode during the entire POST, according to the hart capability and the platform design. However, RISC-V UEFI firmware has to switch the boot hart to Supervisor mode at either early or late POST if the platform is designed to boot a Supervisor mode OS or OS loader.

The machine mode has the highest privilege and this mode is the only mandatory privilege level for RISC-V platforms; all other privilege levels are optional depending on the platform requirements. Machine mode is the initial privilege mode entered at the power-on reset. This level is used in UEFI for low-level access to a hardware platform.

UEFI firmware implementation may provide the Supervisor Binary Interface (SBI) to allow the Supervisor mode execution environment to invoke privileged functions or access privileged hardware.

The processor is in the following execution mode during boot service:

- Total 32 general-purpose registers x1-x31. Register x0 is hardwired to 0. Each register has its ABI (Application Binary Interface) name. See *Detailed Calling Convention* for more detail.

- The width of the native base integer depends on the RISC-V privileged mode implementation. XLEN is a general term which used to refer the width of base integer in bits.
  - For the Base Integer ISA in 32-bit width, XLEN = 32
  - For the Base Integer ISA in 64-bit width, XLEN = 64
  - For the Base Integer ISA in 128-bit width, XLEN = 128

- The width of processor registers could be determined by placing the immediate 4 in a register then shifting the register left by 31 bits at a time. If zero after one shift, then the machine is RV32. If zero after two shifts, then the machine is RV64, else RV128.

- Processor reset vector is platform specified. In UEFI, it is configured to the platform implementation-defined reset vector. The reset vector address is the first instruction which fetched by RISC-V processor when the power-on reset.

- The mcause value after reset have implementation-specific interpretation, value 0 should be returned on implementations that do not distinguish different reset conditions. Implementations that distinguish different reset conditions should only use 0 to indicate the most complete reset (e.g., hard reset). The causes of reset could be power-on reset, external hard reset, brownout detected, watchdog timer elapse, sleep-mode wakeup, etc., which machine-mode UEFI system firmware has to distinguish.

- The mstatus.xIE indicates the current processor interrupt activation in current privilege mode.
  - mstatus.MIE is set to one while mstatus.SIE and mstatus.UIE are set to zero during early UEFI POST stage.
• The machine mode interrupt is enabled during boot service in UEFI. Two kinds of interrupts are enabled, one is for timer interrupt and another is software interrupt.
  - mie.MSIE = 1
  - mie.MTIE = 1
• The memory is in physical addressing mode. Page is disabled in RISC-V machine mode during UEFI boot service.
• I/O access is through memory map I/O.
• Only support Machine level Control and Status Registers (CSRs) in UEFI.
• Machine ISA (misa) register contains the information regarding to the capabilities of CPU implementation. The misa.MXL field encodes the native base integer ISA width in machine mode. MXLEN (Machine XLEN) is given by setting of misa.MXL.
  - misa.MXL = 1, MXLEN is 32 bit
  - misa.MXL = 2, MXLEN is 64 bit
  - misa.MXL = 3, MXLEN is 128 bit
• RISC-V processor supports extensive customization and specialization instruction sets. RISC-V variations provide various purposes of processor implementations and the processor capability is reported in the extension bits in misa register. UEFI drivers will need to know the capabilities of processor before executing the specified RISC-V extension instructions. The extensions fields encodes the presence of the standard extensions, with a single bit per letter of the alphabet. (Bit 0 encodes presence of extension “A”, Bit 1 encodes presence of extension “B” and so on. Currently the single letter extension mnemonics are as below,
  - A - Atomic extension
  - B - Tentatively reserved for Bit operations extension
  - C - Compressed extension
  - D - Double-Precision Floating-Point extension
  - E - Reduced Register Set Indicator RV32E (16 registers)
  - F - Single-Precision Floating-Point extension
  - G - Additional standard extensions present
  - H - Hypervisor extension
  - I - RV32I/64I/128I base ISA
  - J - Tentatively reserved for Dynamically Translated Languages extension
  - K - Reserved
  - L - Tentatively reserved for Decimal Floating-Point extension
  - M - Integer Multiplication and Division extension
  - N - User-level interrupts supported
  - O - Reserved
  - P - Tentatively reserved for Packed-SIMD extension
  - Q - Quad-Precision Floating-Point extension
  - S - Supervisor mode implemented
  - T - Tentatively reserved for Transactional Memory extension

2.3. Calling Conventions
– U - User mode implemented
– V - Tentatively reserved for Vector extension
– W - Reserved
– X - Non-standard extension present
– Y - Reserved
– Z - Reserved
– Zifenci - Instruction-Fetch Fence
– Zicsr - Control and Status Register Access

• Machine Vendor ID Register
  – The mvendorid is a 32-bit read-only register encoding the manufacture of the part. Value of 0 indicates this field is not implemented or this is a non-commercial implementation.

• Machine Architecture ID Register
  – The marchid is an MXLEN-bit read-only register encoding the base microarchitecture of the hart. The combination of mvendorid and marchid should uniquely identify the type of hart microarchitecture that is implemented.

• Machine Implementation ID Register
  – This provides a unique encoding of the version of processor implementation.

An application written to this specification may alter the processor execution mode, but the UEFI image must ensure firmware boot services and runtime services are executed with the prescribed execution environment.

After an Operating System calls ExitBootServices(), firmware boot services are no longer available and it is illegal to call any boot service. After ExitBootServices, firmware runtime services are still available and may be called with paging enabled and virtual address pointers if SetVirtualAddressMap() has been called describing all virtual address ranges used by the firmware runtime service.

If ACPI is supported:

• ACPI Tables loaded at boot time can be contained in memory of type EfiACPIReclaimMemory (recommended) or EfiACPIMemoryNVS. ACPI FACS must be contained in memory of type EfiACPIMemoryNVS.

• The system firmware must not request a virtual mapping for any memory descriptor of type EfiACPIReclaimMemory or EfiACPIMemoryNVS.

• EFI memory descriptors of type EfiACPIReclaimMemory and EfiACPIMemoryNVS must be aligned on a 4 KiB boundary and must be a multiple of 4 KiB in size.

• Any UEFI memory descriptor that requests a virtual mapping via the EFI_MEMORY_DESCRIPTOR having the EFI_MEMORY_RUNTIME bit set must be aligned on a 4 KiB boundary and must be a multiple of 4 KiB in size.

• An ACPI Memory Op-region must inherit cacheability attributes from the UEFI memory map. If the system memory map does not contain cacheability attributes, the ACPI Memory Op-region must inherit its cacheability attributes from the ACPI name space. If no cacheability attributes exist in the system memory map or the ACPI name space, then the region must be assumed to be non-cacheable.

• ACPI tables loaded at runtime must be contained in memory of type EfiACPIMemoryNVS.

The cacheability attributes for ACPI tables loaded at runtime should be defined in the UEFI memory map. If no information about the table location exists in the UEFI memory map, cacheability attributes may be obtained from ACPI memory descriptors. If no information about the table location exists in the UEFI memory map or ACPI memory descriptors, the table is assumed to be non-cached.
In general, UEFI Configuration Tables loaded at boot time (e.g., SMBIOS table) can be contained in memory of type `EfiRuntimeServicesData` (recommended), `EfiBootServicesData`, `EfiACPIReclaimMemory` or `EfiACPIMemoryNVS`. Tables loaded at runtime must be contained in memory of type `EfiRuntimeServicesData` (recommended) or `EfiACPIMemoryNVS`.

**Note:** Previous EFI specifications allowed ACPI tables loaded at runtime to be in the `EfiReservedMemoryType` and there was no guidance provided for other EFI Configuration Tables. `EfiReservedMemoryType` is not intended to be used by firmware. The UEFI Specification intends to clarify the situation moving forward. Also, only OSes conforming to the UEFI Specification are guaranteed to handle SMBIOS table in memory of type `EfiBootServicesData`.

### 2.3.7.1 Handoff State

When UEFI firmware hands off control to Supervisor mode OS, RISC-V boot hart must be operated in Supervisor mode, and the memory addressing must be operated in Bare mode which is no memory address translation or protection through the virtual page table entry.

In order to describe the heterogeneous RISC-V cores and harts for the next boot stage after POST, UEFI firmware must build up the information of core and hart hardware capabilities in the firmware data structure if the target bootable image requires this information. (e.g. If the platform supports SMBIOS structure, SMBIOS record type 44 record, see “Link to UEFI Specification-Related Document” on https://uefi.org/uefi under the heading “RISC-V Processor SMBIOS Specification”).

UEFI firmware must exposes RISC-V boot hart ID in the firmware data structure to OS:

- If platform supports SMBIOS, then SMBIOS type 44 record for the boot hart must have “Boot Hart” set to 1 in “RISC-V Processor-specific Data” structure.
- If platform supports Device Tree, the Device Tree must contains a unsigned integer (32bit) property “boot-hartid” under the /chosen node which would indicate the booting hart ID to the supervisor OS.

If the platform supports Device Tree structure to describe the system configurations, the Flattened Device Blob (DTB) must be installed in the EFI Configuration Table (EFI Configuration Table & Properties Table for details).

All UEFI images takes two parameters: the UEFI image handle and the pointer to EFI System Table. According to the RISC-V calling convention, `EFI_HANDLE` is passed through the a0 register and `EFI_SYSTEM_TABLE` is passed through the a1 register.

- `x10`: `EFI_HANDLE` (ABI name: a0)
- `x11`: `EFI_SYSTEM_TABLE *` (ABI name: a1)
- `x1`: Return Address (ABI name: ra)

### 2.3.7.2 Data Alignment

In the RV32I and RV64I, the datatypes must be aligned at its natural size when stored in memory. The following table describes the datatype and its alignment in RV32I and RV64I in UEFI.

<table>
<thead>
<tr>
<th>Datatype</th>
<th>Description</th>
<th>Alignment</th>
</tr>
</thead>
<tbody>
<tr>
<td>BOOLEAN</td>
<td>Logical Boolean</td>
<td>1</td>
</tr>
<tr>
<td>INTN</td>
<td>Signed value in native width.</td>
<td>4</td>
</tr>
<tr>
<td>UINTN</td>
<td>Unsigned value in native width.</td>
<td>4</td>
</tr>
<tr>
<td>INT8</td>
<td>1-byte signed value</td>
<td>1</td>
</tr>
<tr>
<td>UINT8</td>
<td>1-byte unsigned value</td>
<td>1</td>
</tr>
<tr>
<td>INT16</td>
<td>2-byte signed value</td>
<td>2</td>
</tr>
</tbody>
</table>

### 2.3. Calling Conventions

continues on next page
Table 2.8 – continued from previous page

<table>
<thead>
<tr>
<th>Datatype</th>
<th>Description</th>
<th>Alignment</th>
</tr>
</thead>
<tbody>
<tr>
<td>UINT16</td>
<td>2-byte unsigned value</td>
<td>2</td>
</tr>
<tr>
<td>INT32</td>
<td>4-byte signed value</td>
<td>4</td>
</tr>
<tr>
<td>UINT32</td>
<td>4-byte unsigned value</td>
<td>4</td>
</tr>
<tr>
<td>INT64</td>
<td>8-byte signed value</td>
<td>8</td>
</tr>
<tr>
<td>UINT64</td>
<td>8-byte unsigned value</td>
<td>8</td>
</tr>
<tr>
<td>CHAR8</td>
<td>1-byte character</td>
<td>1</td>
</tr>
<tr>
<td>CHAR16</td>
<td>2-byte character</td>
<td>2</td>
</tr>
<tr>
<td>VOID</td>
<td>Undeclared type</td>
<td>4</td>
</tr>
</tbody>
</table>

Table 2.9: RV64 datatype alignment

<table>
<thead>
<tr>
<th>Datatype</th>
<th>Description</th>
<th>Alignment</th>
</tr>
</thead>
<tbody>
<tr>
<td>BOOLEAN</td>
<td>Logical Boolean</td>
<td>1</td>
</tr>
<tr>
<td>INTN</td>
<td>Signed value in native width.</td>
<td>8</td>
</tr>
<tr>
<td>UINTN</td>
<td>Unsigned value in native width.</td>
<td>8</td>
</tr>
<tr>
<td>INT8</td>
<td>1-byte signed value</td>
<td>1</td>
</tr>
<tr>
<td>UINT8</td>
<td>1-byte unsigned value</td>
<td>1</td>
</tr>
<tr>
<td>INT16</td>
<td>2-byte signed value</td>
<td>2</td>
</tr>
<tr>
<td>UINT16</td>
<td>2-byte unsigned value</td>
<td>2</td>
</tr>
<tr>
<td>INT32</td>
<td>4-byte signed value</td>
<td>4</td>
</tr>
<tr>
<td>UINT32</td>
<td>4-byte unsigned value</td>
<td>4</td>
</tr>
<tr>
<td>INT64</td>
<td>8-byte signed value</td>
<td>8</td>
</tr>
<tr>
<td>UINT64</td>
<td>8-byte unsigned value</td>
<td>8</td>
</tr>
<tr>
<td>CHAR8</td>
<td>1-byte character</td>
<td>1</td>
</tr>
<tr>
<td>CHAR16</td>
<td>2-byte character</td>
<td>2</td>
</tr>
<tr>
<td>VOID</td>
<td>Undeclared type</td>
<td>8</td>
</tr>
</tbody>
</table>

2.3.7.3 Detailed Calling Convention

The RISC-V calling convention passes arguments in register when necessary. In RISC-V, total 32 general registers are declared, each register has its corresponding ABI name.

Table 2.10: Register name and ABI name

<table>
<thead>
<tr>
<th>Register</th>
<th>ABI Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>x0</td>
<td>zero</td>
<td>Hardwired to zero</td>
</tr>
<tr>
<td>x1</td>
<td>ra</td>
<td>Return address</td>
</tr>
<tr>
<td>x2</td>
<td>sp</td>
<td>Stack pointer</td>
</tr>
<tr>
<td>x3</td>
<td>gp</td>
<td>Global pointer</td>
</tr>
<tr>
<td>x4</td>
<td>tp</td>
<td>Thread pointer</td>
</tr>
<tr>
<td>x5-7</td>
<td>t0-2</td>
<td>Temporaries</td>
</tr>
<tr>
<td>x8</td>
<td>s0/fp</td>
<td>Saved register/frame pointer</td>
</tr>
<tr>
<td>x9</td>
<td>s1</td>
<td>Saved register</td>
</tr>
<tr>
<td>x10-11</td>
<td>a0-1</td>
<td>Function arguments/Return values</td>
</tr>
<tr>
<td>x12-17</td>
<td>a2-7</td>
<td>Function arguments</td>
</tr>
<tr>
<td>x18-27</td>
<td>s2-11</td>
<td>Saved registers</td>
</tr>
<tr>
<td>x28-31</td>
<td>t3-6</td>
<td>Temporaries</td>
</tr>
</tbody>
</table>

In the RISC-V calling convention, up to eight integer registers are used for passing argument, a0-a7. a0-a7 are the ABI names and the corresponding registers are x10-x17. Values are returned from functions in integer registers a0 and a1, those are register x10 and x11. In the standard RISC-V calling convention, the stack grows downward and the stack...
point is always kept 16-byte aligned. Five integer registers t0-t6 are temporary registers that are volatile across calls and must be saved by the caller if later used. Twelve integer registers s0-s11 are preserved across calls and must be saved by the callee if used.

In view of the following statement:

“In the standard ABI, procedures should not modify the integer registers tp and gp, because signal handlers may rely upon their values”

mentioned in the RISC-V EFL psABI Specification, and the RISC-V calling convention that gp and tp registers are not assigned a specific owner to save and restore their values (see links below), UEFI firmware must neither trust the values of tp and gp nor make an assumption of owning the write access to these register in any circumstances. (Such as in EFI Boot service, EFI Runtime service, EFI Management Mode service and any UEFI firmware interfaces which may invoked by the EFI drivers, OS or external firmware payload.)

Preserve the values in gp or tp register if UEFI firmware needs to change them, and never touch them after ExitBoot-Services(). Whether and how to preserve gp and tp in the UEFI firmware environment is implementation-specific.


2.4 Protocols

The protocols that a device handle supports are discovered through the EFI_BOOT_SERVICES.HandleProtocol() Boot Service or EFI_BOOT_SERVICES.OpenProtocol() Boot Service. Each protocol has a specification that includes the following:

• The protocol’s globally unique ID (GUID)
• The Protocol Interface structure
• The Protocol Services

Unless otherwise specified a protocol’s interface structure is not allocated from runtime memory and the protocol member functions should not be called at runtime. If not explicitly specified a protocol member function can be called at a TPL level of less than or equal to TPL_NOTIFY (Event, Timer, and Task Priority Services). Unless otherwise specified a protocol’s member function is not reentrant or MP safe.

Any status codes defined by the protocol member function definition are required to be implemented. Additional error codes may be returned, but they will not be tested by standard compliance tests, and any software that uses the procedure cannot depend on any of the extended error codes that an implementation may provide.

To determine if the handle supports any given protocol, the protocol’s GUID is passed to HandleProtocol() or OpenProtocol(). If the device supports the requested protocol, a pointer to the defined Protocol Interface structure is returned. The Protocol Interface structure links the caller to the protocol-specific services to use for this device.

The Figure below shows the construction of a protocol. The UEFI driver contains functions specific to one or more protocol implementations, and registers them with the Boot Service, see EFI_BOOT_SERVICES.InstallProtocolInterface(). The firmware returns the Protocol Interface for the protocol that is then used to invoke the protocol specific services. The UEFI driver keeps private, device-specific context with protocol interfaces.

The following C code fragment illustrates the use of protocols:

```c
// There is a global "EffectsDevice" structure. This
// structure contains information to the device.

// Connect to the ILLUSTRATION_PROTOCOL on the EffectsDevice,
```

(continues on next page)
// by calling HandleProtocol with the device's EFI device handle
// and the ILLUSTRATION_PROTOCOL GUID.

EffectsDevice.Handle = DeviceHandle;
Status = HandleProtocol (  
    EffectsDevice.EFIHandle,  
    &IllustrationProtocolGuid,  
    &EffectsDevice.IllustrationProtocol
);

// Use the EffectsDevice illustration protocol's "MakeEffects" 
// service to make flashy and noisy effects.

Status = EffectsDevice.IllustrationProtocol->MakeEffects (  
    EffectsDevice.IllustrationProtocol,  
    TheFlashyAndNoisyEffect
);

The Table below, UEFI Protocols, lists the UEFI protocols defined by this specification.

<table>
<thead>
<tr>
<th>Protocol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI Loaded Image Protocol</td>
<td>Provides information on the image.</td>
</tr>
<tr>
<td>EFI Loaded Image Device Path Protocol</td>
<td>Specifies the device path that was used when a PE/COFF image was loaded through the EFI Boot Service LoadImage().</td>
</tr>
<tr>
<td>EFI Device Path Protocol</td>
<td>Provides the location of the device.</td>
</tr>
</tbody>
</table>
### Table 2.11 – continued from previous page

<table>
<thead>
<tr>
<th>Protocol Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI Driver Binding Protocol</strong></td>
<td>Provides services to determine if an UEFI driver supports a given controller, and services to start and stop a given controller.</td>
</tr>
<tr>
<td><strong>EFI_DRIVER_FAMILY_OVERRIDE_PROTOCOL</strong></td>
<td>Provides the Driver Family Override mechanism for selecting the best driver for a given controller.</td>
</tr>
<tr>
<td><strong>EFI Platform Driver Override Protocol</strong></td>
<td>Provide a platform specific override mechanism for the selection of the best driver for a given controller.</td>
</tr>
<tr>
<td><strong>EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL</strong></td>
<td>Provides a bus specific override mechanism for the selection of the best driver for a given controller.</td>
</tr>
<tr>
<td><strong>EFI_DRIVER_DIAGNOSTICS2_PROTOCOL</strong></td>
<td>Provides diagnostics services for the controllers that UEFI drivers are managing.</td>
</tr>
<tr>
<td><strong>EFI_COMPONENT_NAME2_PROTOCOL</strong></td>
<td>Provides human readable names for UEFI Drivers and the controllers that the drivers are managing.</td>
</tr>
<tr>
<td><strong>EFI_SIMPLE_TEXT_INPUT_PROTOCOL</strong></td>
<td>Protocol interfaces for devices that support simple console style text input.</td>
</tr>
<tr>
<td><strong>EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL</strong></td>
<td>Protocol interfaces for devices that support console style text displaying.</td>
</tr>
<tr>
<td><strong>EFI_SIMPLE_POINTER_PROTOCOL</strong></td>
<td>Protocol interfaces for devices such as mice and trackballs.</td>
</tr>
<tr>
<td><strong>EFI_SERIAL_IO_PROTOCOL</strong></td>
<td>Protocol interfaces for devices that support serial character transfer.</td>
</tr>
<tr>
<td><strong>EFI_LOAD_FILE_PROTOCOL</strong></td>
<td>Protocol interface for reading a file from an arbitrary device.</td>
</tr>
<tr>
<td><strong>EFI_LOAD_FILE2_PROTOCOL</strong></td>
<td>Protocol interface for reading a non-boot option file from an arbitrary device.</td>
</tr>
<tr>
<td><strong>EFI_SIMPLE_FILE_SYSTEM_PROTOCOL</strong></td>
<td>Protocol interfaces for opening disk volume containing a UEFI file system.</td>
</tr>
<tr>
<td><strong>EFI_FILE_PROTOCOL</strong></td>
<td>Provides access to supported file systems.</td>
</tr>
<tr>
<td><strong>EFI_DISK_IO_PROTOCOL</strong></td>
<td>A protocol interface that layers onto any BLOCK_IO or BLOCK_IO_EX interface.</td>
</tr>
<tr>
<td><strong>EFI_BLOCK_IO_PROTOCOL</strong></td>
<td>Protocol interfaces for devices that support block I/O style accesses.</td>
</tr>
<tr>
<td><strong>EFI_BLOCK_IO2_PROTOCOL</strong></td>
<td>Protocol interfaces for devices that support block I/O style accesses. This interface is capable of non-blocking transactions.</td>
</tr>
<tr>
<td><strong>EFI_UNICODE_COLLATION_PROTOCOL</strong></td>
<td>Protocol interfaces for string comparison operations.</td>
</tr>
<tr>
<td><strong>EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL</strong></td>
<td>Protocol interfaces to abstract memory, I/O, PCI configuration, and DMA accesses to a PCI root bridge controller.</td>
</tr>
<tr>
<td><strong>EFI_PCI I/O Protocol</strong></td>
<td>Protocol interfaces to abstract memory, I/O, PCI configuration, and DMA accesses to a PCI controller on a PCI bus.</td>
</tr>
<tr>
<td><strong>EFI_USB_IO_PROTOCOL</strong></td>
<td>Protocol interfaces to abstract access to a USB controller.</td>
</tr>
<tr>
<td><strong>EFI_SIMPLE_NETWORK_PROTOCOL</strong></td>
<td>Provides interface for devices that support packet based transfers.</td>
</tr>
<tr>
<td><strong>EFI_PXE_BASE_CODE_PROTOCOL</strong></td>
<td>Protocol interfaces for devices that support network booting.</td>
</tr>
</tbody>
</table>

continues on next page
### Table 2.11 – continued from previous page

<table>
<thead>
<tr>
<th>Protocol Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_BIS_PROTOCOL</strong></td>
<td>Protocol interfaces to validate boot images before they are loaded and invoked.</td>
</tr>
<tr>
<td><strong>EFI_DEBUG_SUPPORT_PROTOCOL</strong></td>
<td>Protocol interfaces to save and restore processor context and hook processor exceptions.</td>
</tr>
<tr>
<td><strong>EFI_DEBUGPORT_PROTOCOL</strong></td>
<td>Protocol interface that abstracts a byte stream connection between a debug host and a debug target system.</td>
</tr>
<tr>
<td><strong>EFI_DECOMPRESS_PROTOCOL</strong></td>
<td>Protocol interfaces to decompress an image that was compressed using the EFI Compression Algorithm.</td>
</tr>
<tr>
<td><strong>EFI_EBC_PROTOCOL</strong></td>
<td>Protocols interfaces required to support an EFI Byte Code interpreter.</td>
</tr>
<tr>
<td><strong>EFI_GRAPHICS_OUTPUT_PROTOCOL</strong></td>
<td>Protocol interfaces for devices that support graphical output.</td>
</tr>
<tr>
<td><strong>EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL</strong></td>
<td>Protocol interfaces that allow NVM Express commands to be issued to an NVM Express controller.</td>
</tr>
<tr>
<td><strong>EFI_EXT_SCSI_PASS_THRU_PROTOCOL</strong></td>
<td>Protocol interfaces for a SCSI channel that allows SCSI Request Packets to be sent to SCSI devices.</td>
</tr>
<tr>
<td><strong>EFI_USB2_HC_PROTOCOL</strong></td>
<td>Protocol interfaces to abstract access to a USB Host Controller.</td>
</tr>
<tr>
<td><strong>EFI_AUTHENTICATION_INFO_PROTOCOL</strong></td>
<td>Provides access for generic authentication information associated with specific device paths.</td>
</tr>
<tr>
<td><strong>EFI_DEVICE_PATH_UTILITIES_PROTOCOL</strong></td>
<td>Aids in creating and manipulating device paths.</td>
</tr>
<tr>
<td><strong>EFI_DEVICE_PATH_TO_TEXT_PROTOCOL</strong></td>
<td>Converts device nodes and paths to text.</td>
</tr>
<tr>
<td><strong>EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL</strong></td>
<td>Converts text to device paths and device nodes.</td>
</tr>
<tr>
<td><strong>EFI_EDID_DISCOVERED_PROTOCOL</strong></td>
<td>Contains the EDID information retrieved from a video output device.</td>
</tr>
<tr>
<td><strong>EFI_EDID_ACTIVE_PROTOCOL</strong></td>
<td>Contains the EDID information for an active video output device.</td>
</tr>
<tr>
<td><strong>EFI_EDID_OVERRIDE_PROTOCOL</strong></td>
<td>Produced by the platform to allow the platform to provide EDID information to the producer of the Graphics Output protocol.</td>
</tr>
<tr>
<td><strong>EFI iSCSI Initiator Name Protocol</strong></td>
<td>Sets and obtains the iSCSI Initiator Name.</td>
</tr>
<tr>
<td><strong>EFI_TAPE_IO_PROTOCOL</strong></td>
<td>Provides services to control and access a tape drive.</td>
</tr>
<tr>
<td><strong>EFI Managed Network Protocol</strong></td>
<td>Used to locate communication devices that are supported by an MNP driver and create and destroy instances of the MNP child protocol driver that can use the underlying communications devices.</td>
</tr>
<tr>
<td><strong>EFI_ARP_SERVICE_BINDING_PROTOCOL</strong></td>
<td>Used to locate communications devices that are supported by an ARP driver and to create and destroy instances of the ARP child protocol driver.</td>
</tr>
<tr>
<td><strong>EFI_ARP_PROTOCOL</strong></td>
<td>Used to resolve local network protocol addresses into network hardware addresses.</td>
</tr>
<tr>
<td><strong>EFI_DHCP4_SERVICE_BINDING_PROTOCOL</strong></td>
<td>Used to locate communication devices that are supported by an EFI DHCPv4 Protocol driver and to create and destroy EFI DHCPv4 Protocol child driver instances that can use the underlying communications devices.</td>
</tr>
</tbody>
</table>

*continues on next page*
**Table 2.11 – continued from previous page**

<table>
<thead>
<tr>
<th>Protocol Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_DHCP4_PROTOCOL</strong></td>
<td>Used to collect configuration information for the EFI IPv4 Protocol drivers and to provide DHCPv4 server and PXE boot server discovery services.</td>
</tr>
<tr>
<td><strong>EFI_TCP4_SERVICE_BINDING_PROTOCOL</strong></td>
<td>Used to locate EFI TCPv4 Protocol drivers to create and destroy child of the driver to communicate with other host using TCP protocol.</td>
</tr>
<tr>
<td><strong>EFI_TCP4_PROTOCOL</strong></td>
<td>Provides services to send and receive data stream.</td>
</tr>
<tr>
<td><strong>EFI_IP4_SERVICE_BINDING_PROTOCOL</strong></td>
<td>Used to locate communication devices that are supported by an EFI IPv4 Protocol Driver and to create and destroy instances of the EFI IPv4 Protocol child protocol driver that can use the underlying communication device.</td>
</tr>
<tr>
<td><strong>EFI_IP4_PROTOCOL</strong></td>
<td>Provides basic network IPv4 packet I/O services.</td>
</tr>
<tr>
<td><strong>EFI_IP4_CONFIG2_PROTOCOL</strong></td>
<td>The EFI IPv4 Config Protocol driver performs platform- and policy-dependent configuration of the EFI IPv4 Protocol driver.</td>
</tr>
<tr>
<td><strong>EFI_IP4_CONFIG2_PROTOCOL</strong></td>
<td>The EFI IPv4 Configuration II Protocol driver performs platform- and policy-dependent configuration of the EFI IPv4 Protocol driver.</td>
</tr>
<tr>
<td><strong>EFI_UDP4_SERVICE_BINDING_PROTOCOL</strong></td>
<td>Used to locate communication devices that are supported by an EFI UDPv4 Protocol driver and to create and destroy instances of the EFI UDPv4 Protocol child protocol driver that can use the underlying communication device.</td>
</tr>
<tr>
<td><strong>EFI_UDP4_PROTOCOL</strong></td>
<td>Provides simple packet-oriented services to transmit and receive UDP packets.</td>
</tr>
<tr>
<td><strong>EFI_MTFTP4_SERVICE_BINDING_PROTOCOL</strong></td>
<td>Used to locate communication devices that are supported by an EFI MTFTPv4 Protocol driver and to create and destroy instances of the EFI MTFTPv4 Protocol child protocol driver that can use the underlying communication device.</td>
</tr>
<tr>
<td><strong>EFI_MTFTP4_PROTOCOL</strong></td>
<td>Provides basic services for client-side unicast or multicast TFTP operations.</td>
</tr>
<tr>
<td><strong>EFI_HASH_PROTOCOL</strong></td>
<td>Allows creating a hash of an arbitrary message digest using one or more hash algorithms.</td>
</tr>
<tr>
<td><strong>EFI_HASH_SERVICE_BINDING_PROTOCOL</strong></td>
<td>Used to locate hashing services support provided by a driver and create and destroy instances of the EFI Hash Protocol so that a multiple drivers can use the underlying hashing services.</td>
</tr>
<tr>
<td><strong>EFI_SD_MMC_PASS_THRU_PROTOCOL</strong></td>
<td>Protocol interface that allows SD/eMMC commands to be sent to an SD/eMMC controller.</td>
</tr>
</tbody>
</table>
2.5 UEFI Driver Model

The UEFI Driver Model is intended to simplify the design and implementation of device drivers, and produce small executable image sizes. As a result, some complexity has been moved into bus drivers and in a larger part into common firmware services.

A device driver is required to produce a Driver Binding Protocol on the same image handle on which the driver was loaded. It then waits for the system firmware to connect the driver to a controller. When that occurs, the device driver is responsible for producing a protocol on the controller’s device handle that abstracts the I/O operations that the controller supports. A bus driver performs these exact same tasks. In addition, a bus driver is also responsible for discovering any child controllers on the bus, and creating a device handle for each child controller found.

One assumption is that the architecture of a system can be viewed as a set of one or more processors connected to one or more core chipsets. The core chipsets are responsible for producing one or more I/O buses. The UEFI Driver Model does not attempt to describe the processors or the core chipsets. Instead, the UEFI Driver Model describes the set of I/O buses produced by the core chipsets, and any children of these I/O buses. These children can either be devices or additional I/O buses. This can be viewed as a tree of buses and devices with the core chipsets at the root of that tree.

The leaf nodes in this tree structure are peripherals that perform some type of I/O. This could include keyboards, displays, disks, network, etc. The nonleaf nodes are the buses that move data between devices and buses, or between different bus types. Desktop System shows a sample desktop system with four buses and six devices.

![Desktop System Diagram]

Server System is an example of a more complex server system. The idea is to make the UEFI Driver Model simple and extensible so more complex systems like the one below can be described and managed in the preboot environment. This system contains six buses and eight devices.

The combination of firmware services, bus drivers, and device drivers in any given platform is likely to be produced by a wide variety of vendors including OEMs, IBVs, and IHVs. These different components from different vendors are required to work together to produce a protocol for an I/O device than can be used to boot a UEFI compliant operating system. As a result, the UEFI Driver Model is described in great detail in order to increase the interoperability of these components.
This remainder of this section is a brief overview of the UEFI Driver Model. It describes the legacy option ROM issues that the UEFI Driver Model is designed to address, the entry point of a driver, host bus controllers, properties of device drivers, properties of bus drivers, and how the UEFI Driver Model can accommodate hot-plug events.

### 2.5.1 Legacy Option ROM Issues

Legacy option ROMs have a number of constraints and limitations that restrict innovation on the part of platform designers and adapter vendors. At the time of writing, both ISA and PCI adapters use legacy option ROMs. For the purposes of this discussion, only PCI option ROMs will be considered; legacy ISA option ROMs are not supported as part of the UEFI Specification.

The following is a list of the major constraints and limitations of legacy option ROMs. For each issue, the design considerations that went into the design of the UEFI Driver Model are also listed. Thus, the design of the UEFI Driver Model directly addresses the requirements for a solution to overcome the limitations implicit to PC-AT-style legacy option ROMs.

#### 2.5.1.1 32-bit/16-Bit Real Mode Binaries

Legacy option ROMs typically contain 16-bit real mode code for an IA-32 processor. This means that the legacy option ROM on a PCI card cannot be used in platforms that do not support the execution of IA-32 real mode binaries. Also, 16-bit real mode only allows the driver to access directly the lower 1 MiB of system memory. It is possible for the driver to switch the processor into modes other than real mode in order to access resources above 1 MiB, but this requires a lot of additional code, and causes interoperability issues with other option ROMs and the system BIOS. Also, option ROMs that switch the processor into to alternate execution modes are not compatible with Itanium Processors.

UEFI Driver Model design considerations:

- Drivers need flat memory mode with full access to system components.
• Drivers need to be written in C so they are portable between processor architectures.
• Drivers may be compiled into a virtual machine executable, allowing a single binary driver to work on machines using different processor architectures.

### 2.5.1.2 Fixed Resources for Working with Option ROMs

Since legacy option ROMs can only directly address the lower 1 MiB of system memory, this means that the code from the legacy option ROM must exist below 1 MiB. In a PC-AT platform, memory from 0x00000-0x9FFFF is system memory. Memory from 0xA0000-0xBFFFF is VGA memory, and memory from 0xF0000-0xFFFFF is reserved for the system BIOS. Also, since system BIOS has become more complex over the years, many platforms also use 0xE0000-0xEFFFF for system BIOS. This leaves 128 KiB of memory from 0xC0000-0xDFFFF for legacy option ROMs. This limits how many legacy option ROMs can be run during BIOS POST.

Also, it is not easy for legacy option ROMs to allocate system memory. Their choices are to allocate memory from Extended BIOS Data Area (EBDA), allocate memory through a Post Memory Manager (PMM), or search for free memory based on a heuristic. Of these, only EBDA is standard, and the others are not used consistently between adapters, or between BIOS vendors, which adds complexity and the potential for conflicts.

**UEFI Driver Model** design considerations:
• Drivers need flat memory mode with full access to system components.
• Drivers need to be capable of being relocated so that they can be loaded anywhere in memory (PE/COFF Images)
• Drivers should allocate memory through the boot services. These are well-specified interfaces, and can be guaranteed to function as expected across a wide variety of platform implementations.

### 2.5.1.3 Matching Option ROMs to their Devices

It is not clear which controller may be managed by a particular legacy option ROM. Some legacy option ROMs search the entire system for controllers to manage. This can be a lengthy process depending on the size and complexity of the platform. Also, due to limitation in BIOS design, all the legacy option ROMs must be executed, and they must scan for all the peripheral devices before an operating system can be booted. This can also be a lengthy process, especially if SCSI buses must be scanned for SCSI devices. This means that legacy option ROMs are making policy decision about how the platform is being initialized, and which controllers are managed by which legacy option ROMs. This makes it very difficult for a system designer to predict how legacy option ROMs will interact with each other. This can also cause issues with on-board controllers, because a legacy option ROM may incorrectly choose to manage the on-board controller.

**UEFI Driver Model** design considerations:
• Driver to controller matching must be deterministic
• Give OEMs more control through Platform Driver Override Protocol and Driver Configuration Protocol
• It must be possible to start only the drivers and controllers required to boot an operating system.
2.5.1.4 Ties to PC-AT System Design

Legacy option ROMs assume a PC-AT-like system architecture. Many of them include code that directly touches hardware registers. This can make them incompatible on legacy-free and headless platforms. Legacy option ROMs may also contain setup programs that assume a PC-AT-like system architecture to interact with a keyboard or video display. This makes the setup application incompatible on legacy-free and headless platforms.

UEFI Driver Model design considerations:

- Drivers should use well-defined protocols to interact with system hardware, system input devices, and system output devices.

2.5.1.5 Ambiguities in Specification and Workarounds Born of Experience

Many legacy option ROMs and BIOS code contain workarounds because of incompatibilities between legacy option ROMs and system BIOS. These incompatibilities exist in part because there are no clear specifications on how to write a legacy option ROM or write a system BIOS.

Also, interrupt chaining and boot device selection is very complex in legacy option ROMs. It is not always clear which device will be the boot device for the OS.

UEFI Driver Model design considerations:

- Drivers and firmware are written to follow this specification. Since both components have a clearly defined specification, compliance tests can be developed to prove that drivers and system firmware are compliant. This should eliminate the need to build workarounds into either drivers or system firmware (other than those that might be required to address specific hardware issues).
- Give OEMs more control through Platform Driver Override Protocol and Driver Configuration Protocol and other OEM value-add components to manage the boot device selection process.

2.5.2 Driver Initialization

The file for a driver image must be loaded from some type of media. This could include ROM, FLASH, hard drives, floppy drives, CD-ROM, or even a network connection. Once a driver image has been found, it can be loaded into system memory with the boot service `EFI_BOOT_SERVICES.LoadImage()`. LoadImage() loads a PE/COFF formatted image into system memory. A handle is created for the driver, and a Loaded Image Protocol instance is placed on that handle. A handle that contains a Loaded Image Protocol instance is called an Image Handle. At this point, the driver has not been started. It is just sitting in memory waiting to be started. The figure below shows the state of an image handle for a driver after LoadImage() has been called.

![Image Handle](image_handle.png)

Fig. 2.7: Image Handle
After a driver has been loaded with the boot service `LoadImage()`, it must be started with the boot service `EFI_BOOT_SERVICES.StartImage()`. This is true of all types of UEFI Applications and UEFI Drivers that can be loaded and started on an UEFI-compliant system. The entry point for a driver that follows the UEFI Driver Model must follow some strict rules. First, it is not allowed to touch any hardware. Instead, the driver is only allowed to install protocol instances onto its own `Image Handle`. A driver that follows the UEFI Driver Model is required to install an instance of the Driver Binding Protocol onto its own `Image Handle`. It may optionally install the Driver Configuration Protocol, the Driver Diagnostics Protocol, or the Component Name Protocol. In addition, if a driver wishes to be unloadable it may optionally update the Loaded Image Protocol (`EFI_LOADED_IMAGE_PROTOCOL`) to provide its own `Unload()` function. Finally, if a driver needs to perform any special operations when the boot service `EFI_BOOT_SERVICES.ExitBootServices()` is called, it may optionally create an event with a notification function that is triggered when the boot service ExitBootServices() is called. An `Image Handle` that contains a Driver Binding Protocol instance is known as a `Driver Image Handle`. `Driver Image Handle` shows a possible configuration for the Image Handle from Fig. 2.7 after the boot service `StartImage()` has been called.

Fig. 2.8: **Driver Image Handle**
2.5.3 Host Bus Controllers

Drivers are not allowed to touch any hardware in the driver’s entry point. As a result, drivers will be loaded and started, but they will all be waiting to be told to manage one or more controllers in the system. A platform component, like the Boot Manager, is responsible for managing the connection of drivers to controllers. However, before even the first connection can be made, there has to be some initial collection of controllers for the drivers to manage. This initial collection of controllers is known as the Host Bus Controllers. The I/O abstractions that the Host Bus Controllers provide are produced by firmware components that are outside the scope of the UEFI Driver Model. The device handles for the Host Bus Controllers and the I/O abstraction for each one must be produced by the core firmware on the platform, or a driver that may not follow the UEFI Driver Model. See the PCI Root Bridge I/O Protocol Specification for an example of an I/O abstraction for PCI buses.

A platform can be viewed as a set of processors and a set of core chipset components that may produce one or more host buses. The following figure shows a platform with n processors (CPUs), and a set of core chipset components that produce m host bridges.

Each host bridge is represented in UEFI as a device handle that contains a Device Path Protocol instance, and a protocol instance that abstracts the I/O operations that the host bus can perform. For example, a PCI Host Bus Controller supports one or more PCI Root Bridges that are abstracted by the PCI Root Bridge I/O Protocol. The following figure shows an example device handle for a PCI Root Bridge.

A PCI Bus Driver could connect to this PCI Root Bridge, and create child handles for each of the PCI devices in the system. PCI Device Drivers should then be connected to these child handles, and produce I/O abstractions that may be used to boot a UEFI compliant OS. The following section describes the different types of drivers that can be implemented within the UEFI Driver Model. The UEFI Driver Model is very flexible, so all the possible types of drivers will not be discussed here. Instead, the major types will be covered that can be used as a starting point for
designing and implementing additional driver types.

## 2.5.4 Device Drivers

A device driver is not allowed to create any new device handles. Instead, it installs additional protocol interfaces on an existing device handle. The most common type of device driver will attach an I/O abstraction to a device handle that was created by a bus driver. This I/O abstraction may be used to boot a UEFI compliant OS. Some example I/O abstractions would include Simple Text Output, Simple Input, Block I/O, and Simple Network Protocol. Fig. 2.11 shows a device handle before and after a device driver is connected to it. In this example, the device handle is a child of the XYZ Bus, so it contains an XYZ I/O Protocol for the I/O services that the XYZ bus supports. It also contains a Device Path Protocol that was placed there by the XYZ Bus Driver. The Device Path Protocol is not required for all device handles. It is only required for device handles that represent physical devices in the system. Handles for virtual devices will not contain a Device Path Protocol.

The device driver that connects to the device handle in the above Figure must have installed a Driver Binding Protocol on its own image handle. The Driver Binding Protocol contains three functions called Supported() (\texttt{EFI\_DRIVER\_BINDING\_PROTOCOL.Supported()}) ; Start() (\texttt{EFI\_DRIVER\_BINDING\_PROTOCOL.Start()}) , and Stop() (\texttt{EFI\_DRIVER\_BINDING\_PROTOCOL.Stop()}) . The Supported() function tests to see if the driver supports a given controller. In this example, the driver will check to see if the device handle supports the Device Path Protocol and the XYZ I/O Protocol. If a driver’s Supported() function passes, then the driver can be connected to the controller by calling the driver’s Start() function. The Start() function is what actually adds the additional I/O protocols to a device handle. In this example, the Block I/O Protocol is being installed. To provide symmetry, the Driver Binding Protocol also has a Stop() function that forces the driver to stop managing a device handle. This will cause the device driver to uninstall any protocol interfaces that were installed in Start().

The Supported(), Start(), and Stop() functions of the EFI Driver Binding Protocol are required to make use of the boot service \texttt{EFI\_BOOT\_SERVICES.OpenProtocol()} to get a protocol interface and the boot service \texttt{EFI\_BOOT\_SERVICES.CloseProtocol()} to release a protocol interface. OpenProtocol() and CloseProtocol() update the handle database maintained by the system firmware to track which drivers are consuming protocol interfaces. The information in the handle database can be used to retrieve information about both drivers and controllers. The new boot service \texttt{EFI\_BOOT\_SERVICES.OpenProtocolInformation()} can be used to get the list of components that are currently consuming a specific protocol interface.
Fig. 2.11: Connecting Device Drivers
2.5.5 Bus Drivers

Bus drivers and device drivers are virtually identical from the UEFI Driver Model’s point of view. The only difference is that a bus driver creates new device handles for the child controllers that the bus driver discovers on its bus. As a result, bus drivers are slightly more complex than device drivers, but this in turn simplifies the design and implementation of device drivers. There are two major types of bus drivers. The first creates handles for all child controllers on the first call to Start(). The other type allows the handles for the child controllers to be created across multiple calls to Start(). This second type of bus driver is very useful in supporting a rapid boot capability. It allows a few child handles or even one child handle to be created. On buses that take a long time to enumerate all of their children (e.g. SCSI), this can lead to a very large timesaving in booting a platform. Connecting Bus Drivers shows the tree structure of a bus controller before and after Start() is called. The dashed line coming into the bus controller node represents a link to the bus controller’s parent controller. If the bus controller is a Host Bus Controller, then it will not have a parent controller. Nodes A, B, C, D, and E represent the child controllers of the bus controller.

A bus driver that supports creating one child on each call to Start() might choose to create child C first, and then child E, and then the remaining children A, B, and D. The Supported(), Start(), and Stop() functions of the Driver Binding Protocol are flexible enough to allow this type of behavior.

A bus driver must install protocol interfaces onto every child handle that is creates. At a minimum, it must install a protocol interface that provides an I/O abstraction of the bus’s services to the child controllers. If the bus driver creates a child handle that represents a physical device, then the bus driver must also install a Device Path Protocol instance onto the child handle. A bus driver may optionally install a Bus Specific Driver Override Protocol onto each child handle. This protocol is used when drivers are connected to the child controllers. The boot service EFI_BOOT_SERVICES.ConnectController() uses architecturally defined precedence rules to choose the best set of drivers for a given controller. The Bus Specific Driver Override Protocol has higher precedence than a general driver search algorithm, and lower precedence than platform overrides. An example of a bus specific driver selection occurs with PCI. A PCI Bus Driver gives a driver stored in a PCI controller’s option ROM a higher precedence than drivers stored elsewhere in the platform. Child Device Handle with a Bus Specific Override shows an example child device handle that was created by the XYZ Bus Driver that supports a bus specific driver override mechanism.
2.5.6 Platform Components

Under the UEFI Driver Model, the act of connecting and disconnecting drivers from controllers in a platform is under the platform firmware’s control. This will typically be implemented as part of the UEFI Boot Manager, but other implementations are possible. The boot services `EFI_BOOT_SERVICES.ConnectController()` and `EFI_BOOT_SERVICES.DisconnectController()` can be used by the platform firmware to determine which controllers get started and which ones do not. If the platform wishes to perform system diagnostics or install an operating system, then it may choose to connect drivers to all possible boot devices. If a platform wishes to boot a preinstalled operating system, it may choose to only connect drivers to the devices that are required to boot the selected operating system. The UEFI Driver Model supports both these modes of operation through the boot services ConnectController() and DisconnectController(). In addition, since the platform component that is in charge of booting the platform has to work with device paths for console devices and boot options, all of the services and protocols involved in the UEFI Driver Model are optimized with device paths in mind.

Since the platform firmware may choose to only connect the devices required to produce consoles and gain access to a boot device, the OS present device drivers cannot assume that a UEFI driver for a device has been executed. The presence of a UEFI driver in the system firmware or in an option ROM does not guarantee that the UEFI driver will be loaded, executed, or allowed to manage any devices in a platform. All OS present device drivers must be able to handle devices that have been managed by a UEFI driver and devices that have not been managed by an UEFI driver.

The platform may also choose to produce a protocol named the Platform Driver Override Protocol. This is similar to the Bus Specific Driver Override Protocol, but it has higher priority. This gives the platform firmware the highest priority when deciding which drivers are connected to which controllers. The Platform Driver Override Protocol is attached to a handle in the system. The boot service ConnectController() will make use of this protocol if it is present in the system.
2.5.7 Hot-Plug Events

In the past, system firmware has not had to deal with hot-plug events in the preboot environment. However, with the advent of buses like USB, where the end user can add and remove devices at any time, it is important to make sure that it is possible to describe these types of buses in the UEFI Driver Model. It is up to the bus driver of a bus that supports the hot adding and removing of devices to provide support for such events. For these types of buses, some of the platform management is going to have to move into the bus drivers. For example, when a keyboard is hot added to a USB bus on a platform, the end user would expect the keyboard to be active. A USB Bus driver could detect the hot-add event and create a child handle for the keyboard device. However, because drivers are not connected to controllers unless \texttt{EFI\_BOOT\_SERVICES.ConnectController()} is called, the keyboard would not become an active input device. Making the keyboard driver active requires the USB Bus driver to call ConnectController() when a hot-add event occurs. In addition, the USB Bus Driver would have to call \texttt{EFI\_BOOT\_SERVICES.DisconnectController()} when a hot-remove event occurs. If \texttt{EFI\_BOOT\_SERVICES.DisconnectController()} returns an error the USB Bus Driver needs to retry the \texttt{EFI\_BOOT\_SERVICES.DisconnectController()} from a timer event until it succeeds.

Device drivers are also affected by these hot-plug events. In the case of USB, a device can be removed without any notice. This means that the Stop() functions of USB device drivers will have to deal with shutting down a driver for a device that is no longer present in the system. As a result, any outstanding I/O requests will have to be flushed without actually being able to touch the device hardware.

In general, adding support for hot-plug events greatly increases the complexity of both bus drivers and device drivers. Adding this support is up to the driver writer, so the extra complexity and size of the driver will need to be weighed against the need for the feature in the preboot environment.

2.5.8 EFI Services Binding

The UEFI Driver Model maps well onto hardware devices, hardware bus controllers, and simple combinations of software services that layer on top of hardware devices. However, the UEFI driver Model does not map well onto complex combinations of software services. As a result, an additional set of complementary protocols are required for more complex combinations of software services.

Figure below, Software Service Relationships, contains three examples showing the different ways that software services relate to each other. In the first two cases, each service consumes one or more other services, and at most one other service consumes all of the services. Case #3 differs because two different services consume service A. The \texttt{EFI\_DRIVER\_BINDING\_PROTOCOL} can be used to model cases #1 and #2, but it cannot be used to model case #3 because of the way that the UEFI Boot Service OpenProtocol() behaves. When used with the BY\_DRIVER open mode, OpenProtocol() allows each protocol to have only at most one consumer. This feature is very useful and prevents multiple drivers from attempting to manage the same controller. However, it makes it difficult to produce sets of software services that look like case #3.

Software Service Relationships The \texttt{EFI\_SERVICE\_BINDING\_PROTOCOL} provides the mechanism that allows protocols to have more than one consumer. The \texttt{EFI\_SERVICE\_BINDING\_PROTOCOL} is used with the \texttt{EFI\_DRIVER\_BINDING\_PROTOCOL}. A UEFI driver that produces protocols that need to be available to more than one consumer at the same time will produce both the \texttt{EFI\_DRIVER\_BINDING\_PROTOCOL} and the \texttt{EFI\_SERVICE\_BINDING\_PROTOCOL}. This type of driver is a hybrid driver that will produce the \texttt{EFI\_DRIVER\_BINDING\_PROTOCOL} in its driver entry point.

When the driver receives a request to start managing a controller, it will produce the \texttt{EFI\_SERVICE\_BINDING\_PROTOCOL} on the handle of the controller that is being started. The \texttt{EFI\_SERVICE\_BINDING\_PROTOCOL} is slightly different from other protocols defined in the UEFI Specification. It does not have a GUID associated with it. Instead, this protocol instance structure actually represents a family of protocols. Each software service driver that requires an *\texttt{EFI\_SERVICE\_BINDING\_PROTOCOL} instance will be required to generate a new GUID for its own type of \texttt{EFI\_SERVICE\_BINDING\_PROTOCOL}. This requirement is why the various network protocols in this specification contain two GUIDs. One is the \texttt{EFI\_SERVICE\_BINDING\_PROTOCOL} GUID for that network protocol, and the other GUID is for the protocol that
Case #1: Linear Stack

Case #2: Multiple Dependencies

Case #3: Multiple Consumers

Fig. 2.14: Software Service Relationships
contains the specific member services produced by the network driver. The mechanism defined here is not limited to network protocol drivers. It can be applied to any set of protocols that the `EFI_DRIVER_BINDING_PROTOCOL` cannot directly map because the protocols contain one or more relationships like case #3 in Software Service Relationships.

Neither the `EFI_DRIVER_BINDING_PROTOCOL` nor the combination of the `EFI_DRIVER_BINDING_PROTOCOL` and the `EFI_SERVICE_BINDING_PROTOCOL` can handle circular dependencies. There are methods to allow circular references, but they require that the circular link be present for short periods of time. When the protocols across the circular link are used, these methods also require that the protocol must be opened with an open mode of EXCLUSIVE, so that any attempts to deconstruct the set of protocols with a call to DisconnectController() will fail. As soon as the driver is finished with the protocol across the circular link, the protocol should be closed.

### 2.6 Requirements

This document is an architectural specification. As such, care has been taken to specify architecture in ways that allow maximum flexibility in implementation. However, there are certain requirements on which elements of this specification must be implemented to ensure that operating system loaders and other code designed to run with UEFI boot services can rely upon a consistent environment.

For the purposes of describing these requirements, the specification is broken up into required and optional elements. In general, an optional element is completely defined in the section that matches the element name. For required elements however, the definition may in a few cases not be entirely self contained in the section that is named for the particular element. In implementing required elements, care should be taken to cover all the semantics defined in this specification that relate to the particular element.

#### 2.6.1 Required Elements

*Required UEFI Implementation Elements* lists the required elements. Any system that is designed to conform to this specification must provide a complete implementation of all these elements. This means that all the required service functions and protocols must be present and the implementation must deliver the full semantics defined in the specification for all combinations of calls and parameters. Implementers of applications, drivers or operating system loaders that are designed to run on a broad range of systems conforming to the UEFI specification may assume that all such systems implement all the required elements.

A system vendor may choose not to implement all the required elements, for example on specialized system configurations that do not support all the services and functionality implied by the required elements. However, since most applications, drivers and operating system loaders are written assuming all the required elements are present on a system that implements the UEFI specification; any such code is likely to require explicit customization to run on a less than complete implementation of the required elements in this specification.

<table>
<thead>
<tr>
<th>Element</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI System Table</code></td>
<td>Provides access to UEFI Boot Services, UEFI Runtime Services, consoles, firmware vendor information, and the system configuration tables.</td>
</tr>
<tr>
<td><code>EFI_BOOT_SERVICES</code></td>
<td>All functions defined as boot services.</td>
</tr>
<tr>
<td><code>EFI_RUNTIME_SERVICES</code></td>
<td>All functions defined as runtime services.</td>
</tr>
<tr>
<td><code>EFI Loaded Image Protocol</code></td>
<td>Provides information on the image.</td>
</tr>
<tr>
<td><code>EFI Loaded Image Device Path Protocol</code></td>
<td>Specifies the device path that was used when a PE/COFF image was loaded through the EFI Boot Service Load-Image().</td>
</tr>
</tbody>
</table>

Table 2.12: Required UEFI Implementation Elements

continues on next page
### 2.6.2 Platform-Specific Elements

There are a number of elements that can be added or removed depending on the specific features that a platform requires. Platform firmware developers are required to implement UEFI elements based upon the features included. The following is a list of potential platform features and the elements that are required for each feature type:

1. If a platform includes console devices, the `EFI_SIMPLE_TEXT_INPUT_PROTOCOL`, `EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL`, and `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL` must be implemented.

2. If a platform includes a configuration infrastructure, then `EFI_HII_DATABASE_PROTOCOL`, `EFI_HII_STRING_PROTOCOL`, `EFI HII Configuration Routing Protocol`, and `EFI_HII_CONFIG_ACCESS_PROTOCOL` are required. If you support bitmapped fonts, you must support `EFI_HII_FONT_PROTOCOL`.

3. If a platform includes graphical console devices, then `EFI_GRAPHICS_OUTPUT_PROTOCOL`, `EFI_EDID_DISCOVERED_PROTOCOL`, and `EFI_EDID_ACTIVE_PROTOCOL` must be implemented. In order to support the `EFI_GRAPHICS_OUTPUT_PROTOCOL`, a platform must contain a driver to consume `EFI_GRAPHICS_OUTPUT_PROTOCOL` and produce `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL` even if the `EFI_GRAPHICS_OUTPUT_PROTOCOL` is produced by an external driver.

4. If a platform includes a pointer device as part of its console support, `EFI_SIMPLE_POINTER_PROTOCOL` must be implemented.

5. If a platform includes the ability to boot from a disk device, then `EFI_BLOCK_IO_PROTOCOL`, `EFI_DISK_IO_PROTOCOL`, `EFI_SIMPLE_FILE_SYSTEM_PROTOCOL`, and `EFI_UNICODE_COLLATION_PROTOCOL` are required. In addition, partition support for MBR, GPT, and El Torito must be implemented. For disk devices supporting the security commands of the SPC-4 or ATA8-ACS command set `EFI_STORAGE_SECURITY_COMMAND_PROTOCOL` is also required. An external driver may produce the Block I/O Protocol and the `EFI_STORAGE_SECURITY_COMMAND_PROTOCOL`. All other protocols required to boot from a disk device must be carried as part of the platform.

6. If a platform includes the ability to perform a TFTP-based boot from a network device, then `EFI_PXE_BASE_CODE_PROTOCOL` is required. The platform must be prepared to produce this protocol on any of `EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL` (UNDI), `EFI_SIMPLE_NETWORK_PROTOCOL`, or `EFI Managed Network Protocol`. If a platform includes the ability to validate a boot image received through a network device, it is also required that image verification be supported, including SetupMode equal zero and the boot image hash or a verification certificate corresponding to the image exist in the ‘db’ variable and not in the ‘dbx’ variable. An external driver may produce the UNDI interface. All other protocols required to boot from a network device must be carried by the platform.

7. If a platform supports UEFI general purpose network applications, then the `EFI Managed Network Protocol`, `EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL`, `EFI_ARP_PROTOCOL`, `EFI_ARP_SERVICE_BINDING_PROTOCOL`, `EFI_DHCP4_PROTOCOL`, `EFI_DHCP4_SERVICE_BINDING_PROTOCOL`, `EFI_TCP4_PROTOCOL`, `EFI_TCP4_SERVICE_BINDING_PROTOCOL`, `EFI_IP4_CONFIG2_PROTOCOL`, `EFI_IP4_SERVICE_BINDING_PROTOCOL`, `EFI_IP4_CONFIG2_PROTOCOL`, `EFI_UDP4_PROTOCOL`, and `EFI_UDP4_SERVICE_BINDING_PROTOCOL` are required. If additional IPv6 support is needed for the platform, then `EFI_DHCP6 Protocol`, `EFI_DHCP6_SERVICE_BINDING_PROTOCOL`,...
8. If a platform includes a byte-stream device such as a UART, then the \texttt{EFI\_SERIAL\_IO\_PROTOCOL} must be implemented.

9. If a platform includes PCI bus support, then the \texttt{EFI\_PCI\_ROOT\_BRIDGE\_IO\_PROTOCOL}, the \texttt{EFI\_PCI\_I/O\_PROTOCOL}, must be implemented.

10. If a platform includes USB bus support, then \texttt{EFI\_USB2\_HC\_PROTOCOL} and \texttt{EFI\_USB\_IO\_PROTOCOL} must be implemented. An external device can support USB by producing a USB Host Controller Protocol.

11. If a platform includes an NVM Express controller, then \texttt{EFI\_NVM\_EXPRESS\_PASS\_THRU\_PROTOCOL} must be implemented.

12. If a platform supports booting from a block-oriented NVM Express controller, then \texttt{EFI\_BLOCK\_IO\_PROTOCOL} must be implemented. An external driver may produce the \texttt{EFI\_NVM\_EXPRESS\_PASS\_THRU\_PROTOCOL}. All other protocols required to boot from an NVM Express subsystem must be carried by the platform.

13. If a platform includes an I/O subsystem that utilizes SCSI command packets, then \texttt{EFI\_EXT\_SCSI\_PASS\_THRU\_PROTOCOL} must be implemented.

14. If a platform supports booting from a block oriented SCSI peripheral, then \texttt{EFI\_SCSI\_I/O\_PROTOCOL} and \texttt{EFI\_BLOCK\_IO\_PROTOCOL} must be implemented. An external driver may produce the \texttt{EFI\_EXT\_SCSI\_PASS\_THRU\_PROTOCOL}. All other protocols required to boot from a SCSI I/O subsystem must be carried by the platform.

15. If a platform supports booting from an iSCSI peripheral, then the \texttt{EFI\_iSCSI\_Initiator\_Name\_Protocol} and \texttt{EFI\_AUTHENTICATION\_INFO\_PROTOCOL} must be implemented.

16. If a platform includes debugging capabilities, then \texttt{EFI\_DEBUG\_SUPPORT\_PROTOCOL}, the \texttt{EFI\_DEBUGPORT\_PROTOCOL}, and the \texttt{EFI\_Image\_Info\_Table} must be implemented.

17. If a platform includes the ability to override the default driver to the controller matching algorithm provided by the UEFI Driver Model, then \texttt{EFI\_Platform\_Driver\_Override\_Protocol} must be implemented.

18. If a platform includes an I/O subsystem that utilizes ATA command packets, then the \texttt{EFI\_ATA\_PASS\_THRU\_PROTOCOL} must be implemented.

19. If a platform supports option ROMs from devices not permanently attached to the platform and it supports the ability to authenticate those option ROMs, then it must support the option ROM validation methods described in Network Protocols — UDP and MTFTP and the authenticated EFI variables described in Exception for Machine Check, INIT, and NMI.

20. If a platform includes the ability to authenticate UEFI images and the platform potentially supports more than one OS loader, it must support the methods described in Network Protocols — UDP and MTFTP and the authenticated UEFI variables described in Exception for Machine Check, INIT, and NMI.

21. EBC support is no longer required as of UEFI Specification version 2.8. If an EBC interpreter is implemented, then it must produce the \texttt{EFI\_EBC\_PROTOCOL} interface.

22. If a platform includes the ability to perform a HTTP-based boot from a network device, then the \texttt{EFI\_HTTP\_SERVICE\_BINDING\_PROTOCOL}, \texttt{EFI\_HTTP\_PROTOCOL} and
 EFI_HTTP_UTILITIES_PROTOCOL are required. If it includes the ability to perform a HTTPS-based boot from network device, besides above protocols EFI TLS Service Binding Protocol, EFI TLS Protocol and EFI TLS Configuration Protocol are also required. If it includes the ability to perform a HTTP(S)-based boot with DNS feature, then EFI_DNS4_SERVICE_BINDING_PROTOCOL, EFI_DNS4_PROTOCOL are required for the IPv4 stack; EFI_DNS6_SERVICE_BINDING_PROTOCOL and EFI_DNS6_PROTOCOL are required for the IPv6 stack.

23. If a platform includes the ability to perform a wireless boot from a network device, and if this platform provides a standalone wireless EAP driver, then EFI_EAP_PROTOCOL, EFI EAP Configuration Protocol and EFI EAP Management2 Protocol are required; if the platform provides a standalone wireless supplicant, then EFI Supplicant Protocol and EFI EAP Configuration Protocol are required. If it includes the ability to perform a wireless boot with TLS feature, then EFI_TLS_Service_Binding Protocol, EFI_TLS Protocol and EFI_TLS_Configuration Protocol are required.

24. If a platform supports classic Bluetooth, then EFI_BLUETOOTH_HC_PROTOCOL, EFI_BLUETOOTH_IO_PROTOCOL, and EFI_BLUETOOTH_CONFIG_PROTOCOL must be implemented, and EFI Bluetooth Attribute Protocol may be implemented. If a platform supports Bluetooth Smart (Bluetooth Low Energy), then EFI_BLUETOOTH_HC_PROTOCOL, EFI Bluetooth Attribute Protocol and EFI_BLUETOOTH_LE_CONFIG_PROTOCOL must be implemented. If a platform supports both Bluetooth classic and BluetoothLE, then both above requirements should be satisfied.

25. If a platform supports RESTful communication over HTTP or over an in-band path to a BMC, then the EFI REST Protocol or EFI_REST_EX_PROTOCOL must be implemented. If EFI_REST_EX_PROTOCOL is implemented, EFI_REST_EX_SERVICE_BINDING_PROTOCOL must be implemented as well. If a platform supports Redfish communication over HTTP or over an in-band path to a BMC, the EFI_REDFISH_DISCOVER_PROTOCOL and EFI REST JSON Structure Protocol may be implemented.

26. If a platform includes the ability to use a hardware feature to create high quality random numbers, this capability should be exposed by instance of EFI_RNG_PROTOCOL with at least one EFI RNG Algorithm supported.

27. If a platform permits the installation of Load Option Variables, (Boot####, or Driver####, or SysPrep####), the platform must support and recognize all defined values for Attributes within the variable and report these capabilities in BootOptionSupport. If a platform supports installation of Load Option Variables of type Driver####, all installed Driver#### variables must be processed and the indicated driver loaded and initialized during every boot. And all installed SysPrep#### options must be processed prior to processing Boot#### options.

28. If the platform supports UEFI secure boot as described in Secure Boot and Driver Signing, the platform must provide the PKCS verification functions described in PKCS7 Verify Protocol.

29. If a platform includes an I/O subsystem that utilizes SD or eMMC command packets, then the EFI_SD_MMC_PASS_THRU_PROTOCOL must be implemented.

30. If a platform includes a mass storage device which supports hardware-based erase on a specified range, then EFI_ERASE_BLOCK_PROTOCOL must be implemented.

31. If a platform includes the ability to register for notifications when a call to ResetSystem is called, then the EFI_RESET_NOTIFICATION_PROTOCOL must be implemented.

32. If a platform includes UFS devices, the EFI UFS Device Config Protocol must be implemented.

33. If a platform cannot support calls defined in EFI_RUNTIME_SERVICES after ExitBootServices() is called, that platform is permitted to provide implementations of those runtime services that return EFI_UNSUPPORTED when invoked at runtime. On such systems, an EFI_RT_PROPERTIES_TABLE configuration table should be published describing which runtime services are supported at runtime.

34. If a platform includes support for CXL devices with coherent memory, then the platform must support extracting the Coherent Device Attribute Table (CDAT) from the device, using either the CXL Data Object Exchange ser-

2.6. Requirements
vices (as defined in the CXL 2.0 Specification) or the EFI_ADAPTER_INFORMATION_PROTOCOL instance (with EFI_ADAPTER_INFO_CDAT_TYPE_GUID type) installed on that device.

Note: Some of the required protocol instances are created by the corresponding Service Binding Protocol. For example, EFI_IP4_PROTOCOL is created by EFI_IP4_SERVICE_BINDING_PROTOCOL. Please refer to the corresponding sections of Service Binding Protocol for the details.

### 2.6.3 Driver-Specific Elements

There are a number of UEFI elements that can be added or removed depending on the features that a specific driver requires. Drivers can be implemented by platform firmware developers to support buses and devices in a specific platform. Drivers can also be implemented by add-in card vendors for devices that might be integrated into the platform hardware or added to a platform through an expansion slot.

The following list includes possible driver features, and the UEFI elements that are required for each feature type:

1. If a driver follows the driver model of this specification, the **EFI Driver Binding Protocol** must be implemented. It is strongly recommended that all drivers that follow the driver model of this specification also implement the **EFI_COMPONENT_NAME2_PROTOCOL**.

2. If a driver requires configuration information, the driver must use the **EFI_HII_DATABASE_PROTOCOL**. A driver should not otherwise display information to the user or request information from the user.

3. If a driver requires diagnostics, the **EFI_DRIVER_DIAGNOSTICS2_PROTOCOL** must be implemented. In order to support low boot times, limit diagnostics during normal boots. Time consuming diagnostics should be deferred until the **EFI_DRIVER_DIAGNOSTICS2_PROTOCOL** is invoked.

4. If a bus supports devices that are able to provide containers for drivers (e.g. option ROMs), then the bus driver for that bus type must implement the **EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL**.

5. If a driver is written for a console output device, then the **EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL** must be implemented.

6. If a driver is written for a graphical console output device, then the **EFI_GRAPHICS_OUTPUT_PROTOCOL**, **EFI_EDID_DISCOVERED_PROTOCOL** and **EFI_EDID_ACTIVE_PROTOCOL** must be implemented.

7. If a driver is written for a console input device, then the **EFI_SIMPLE_TEXT_INPUT_PROTOCOL** and **EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL** must be implemented.

8. If a driver is written for a pointer device, then the **EFI_SIMPLE_POINTER_PROTOCOL** must be implemented.

9. If a driver is written for a network device, then the **EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL**, **EFI_SIMPLE_NETWORK_PROTOCOL** or **EFI Managed Network Protocol** must be implemented. If VLAN is supported in hardware, then driver for the network device may implement the **EFI_VLAN_CONFIG_PROTOCOL**. If a network device chooses to only produce the ** EFI Managed Network Protocol**, then the driver for the network device must implement the **EFI_VLAN_CONFIG_PROTOCOL**. If a driver is written for a network device to supply wireless feature, besides above protocols, **EFI_ADAPTER_INFORMATION_PROTOCOL** must be implemented. If the wireless driver does not provide user configuration capability, **EFI Wireless MAC Connection II Protocol** must be implemented. If the wireless driver is written for a platform which provides a standalone wireless EAP driver, **EFI_EAP_PROTOCOL** must be implemented.

10. If a driver is written for a disk device, then the :ref:`efi-block-io-protocol` and the **EFI_BLOCK_IO2_PROTOCOL** must be implemented. In addition, the **EFI_STORAGE_SECURITY_COMMAND_PROTOCOL** must be implemented for disk devices supporting the security commands of the SPC-4 or ATA8-ACS command set. In addition, for devices that support incline encryption in the host storage controller, the **EFI_BLOCK_IO_CRYPTO_PROTOCOL** must be supported.

11. If a driver is written for a disk device, then the **EFI_BLOCK_IO_PROTOCOL** and the **EFI_BLOCK_IO2_PROTOCOL** must be implemented. In addition, the
12. If a driver is written for a device that is not a block oriented device but one that can provide a file system-like interface, then the \texttt{EFI\_SIMPLE\_FILE\_SYSTEM\_PROTOCOL} must be implemented.

13. If a driver is written for a PCI root bridge, then the \texttt{EFI\_PCI\_ROOT\_BRIDGE\_IO\_PROTOCOL} and the \texttt{EFI PCI I/O Protocol} must be implemented.

14. If a driver is written for an NVM Express controller, then the \texttt{EFI\_NVM\_EXPRESS\_PASS\_THRU\_PROTOCOL} must be implemented.

15. If a driver is written for a USB host controller, then the \texttt{EFI\_USB2\_HC\_PROTOCOL} and the \texttt{EFI\_USB\_IO\_PROTOCOL} must be implemented. If a driver is written for a USB host controller, then the must be implemented. TODO MISSING WORD END OF LAST SENTENCE

16. If a driver is written for a SCSI controller, then the \texttt{EFI\_EXT\_SCSI\_PASS\_THRU\_PROTOCOL} must be implemented.

17. If a driver is digitally signed, it must embed the digital signature in the PE/COFF image as described in \textit{Embedded Signatures}.

18. If a driver is written for a boot device that is not a block-oriented device, a file system-based device, or a console device, then the \texttt{EFI\_LOAD\_FILE2\_PROTOCOL} must be implemented.

19. If a driver follows the driver model of this specification, and the driver wants to produce warning or error messages for the user, then the \texttt{EFI Driver Health Protocol} must be used to produce those messages. The Boot Manager may optionally display the messages to the user.

20. If a driver follows the driver model of this specification, and the driver needs to perform a repair operation that is not part of the normal initialization sequence, and that repair operation requires an extended period of time, then the \texttt{EFI Driver Health Protocol} must be used to provide the repair feature. If the Boot Manager detects a boot device that requires a repair operation, then the Boot Manager must use the \texttt{EFI Driver Health Protocol} to perform the repair operation. The Boot Manager can optionally display progress indicators as the repair operation is performed by the driver.

21. If a driver follows the driver model of this specification, and the driver requires the user to make software and/or hardware configuration changes before the boot devices that the driver manages can be used, then the \texttt{EFI Driver Health Protocol} must be produced. If the Boot Manager detects a boot device that requires software and/or hardware configuration changes to make the boot device usable, then the Boot Manager may optionally allow the user to make those configuration changes.

22. If a driver is written for an ATA controller, then the \texttt{EFI\_ATA\_PASS\_THRU\_PROTOCOL} must be implemented.

23. If a driver follows the driver model of this specification, and the driver wants to be used with higher priority than the Bus Specific Driver Override Protocol when selecting the best driver for controller, then the \texttt{EFI\_DRIVER\_FAMILY\_OVERRIDE\_PROTOCOL} must be produced on the same handle as the \ref{efi-driver-binding-protocol-protocols-uefi-driver-model}.

24. If a driver supports firmware management by an external agent or application, then the \texttt{EFI\_FIRMWARE\_MANAGEMENT\_PROTOCOL} must be used to support firmware management.

25. If a driver follows the driver model of this specification and a driver is a device driver as defined in \textit{UEFI Driver Model}, it must perform bus transactions via the bus abstraction protocol produced by a parent bus driver. Thus a driver for a device that conforms to the PCI specification must use \texttt{EFI PCI I/O Protocol} for all PCI memory space, PCI I/O, PCI configuration space, and DMA operations.

26. If a driver is written for a classic Bluetooth controller, then \texttt{EFI\_BLUETOOTH\_HC\_PROTOCOL}, \texttt{EFI\_BLUETOOTH\_IO\_PROTOCOL} and \texttt{EFI\_BLUETOOTH\_CONF\_PROTOCOL} must be implemented, and \texttt{EFI Bluetooth Attribute Protocol} may be implemented. If a driver written for a Bluetooth Smart (Bluetooth Low Energy) controller, then \texttt{EFI\_BLUETOOTH\_HC\_PROTOCOL}, \texttt{EFI Bluetooth Attribute Protocol} and
2.6.4 Extensions to this Specification Published Elsewhere

This specification has been extended over time to include support for new devices and technologies. As the name of the specification implies, the original intent in its definition was to create a baseline for firmware interfaces that is extensible without the need to include extensions in the main body of this specification.

Readers of this specification may find that a feature or type of device is not treated by the specification. This does not necessarily mean that there is no agreed “standard” way to support the feature or device in implementations that claim conformance to this Specification. On occasion, it may be more appropriate for other standards organizations to publish their own extensions that are designed to be used in concert with the definitions presented here. This may for example allow support for new features in a more timely fashion than would be accomplished by waiting for a revision to this specification or perhaps that such support is defined by a group with a specific expertise in the subject area. Readers looking for means to access features or devices that are not treated in this document are therefore recommended to inquire of appropriate standards groups to ascertain if appropriate extension publications already exist before creating their own extensions.

By way of examples, at the time of writing the UEFI Forum is aware of a number of extension publications that are compatible with and designed for use with this specification. Such extensions include:

- **Developers Interface Guide for Itanium® Architecture Based Servers**: published and hosted by the DIG64 group (See “Links to UEFI-Related Documents” ([http://uefi.org/uefi](http://uefi.org/uefi)) under the heading “Developers Interface Guide for Itanium® Architecture Based Servers”). This document is a set of technical guidelines that define hardware, firmware, and operating system compatibility for Itanium™-based servers;

- **TCG EFI Platform Specification**: published and hosted by the Trusted Computing Group (See “Links to UEFI-Related Documents” ([http://uefi.org/uefi](http://uefi.org/uefi)) under the heading “TCG EFI Platform Specification”). This document is about the processes that boot an EFI platform and boot an OS on that platform. Specifically, this specification contains the requirements for measuring boot events into TPM PCRs and adding boot event entries into the Event Log.


Other extension documents may exist outside the view of the UEFI Forum or may have been created since the last revision of this document.

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*EFI_BLUETOOTH_LE_CONFIG_PROTOCOL* must be implemented. If a driver supports both Bluetooth classic and Bluetooth LE, then both above requirements should be satisfied.

27. If a driver is written for an SD controller or eMMC controller, then the *EFI_SD_MMC_PASS_THRU_PROTOCOL* must be implemented.

28. If a driver is written for a UFS device, then *EFI_UFS_DEVICE_CONFIG_PROTOCOL* must be implemented.
The UEFI boot manager is a firmware policy engine that can be configured by modifying architecturally defined global NVRAM variables. The boot manager will attempt to load UEFI drivers and UEFI applications (including UEFI OS boot loaders) in an order defined by the global NVRAM variables. The platform firmware must use the boot order specified in the global NVRAM variables for normal boot. The platform firmware may add extra boot options or remove invalid boot options from the boot order list.

The platform firmware may also implement value added features in the boot manager if an exceptional condition is discovered in the firmware boot process. One example of a value added feature would be not loading a UEFI driver if booting failed the first time the driver was loaded. Another example would be booting to an OEM-defined diagnostic environment if a critical error was discovered in the boot process.

The boot sequence for UEFI consists of the following:

- The boot order list is read from a globally defined NVRAM variable. Modifications to this variable are only guaranteed to take effect after the next platform reset. The boot order list defines a list of NVRAM variables that contain information about what is to be booted. Each NVRAM variable defines a name for the boot option that can be displayed to a user.
- The variable also contains a pointer to the hardware device and to a file on that hardware device that contains the UEFI image to be loaded.
- The variable might also contain paths to the OS partition and directory along with other configuration specific directories.

The NVRAM can also contain load options that are passed directly to the UEFI image. The platform firmware has no knowledge of what is contained in the load options. The load options are set by higher level software when it writes to a global NVRAM variable to set the platform firmware boot policy. This information could be used to define the location of the OS kernel if it was different than the location of the UEFI OS loader.

### 3.1 Firmware Boot Manager

The boot manager is a component in firmware conforming to this specification that determines which drivers and applications should be explicitly loaded and when. Once compliant firmware is initialized, it passes control to the boot manager. The boot manager is then responsible for determining what to load and any interactions with the user that may be required to make such a decision.

The actions taken by the boot manager depend upon the system type and the policies set by the system designer. For systems that allow the installation of new Boot Variables (See Boot Option Recovery), the Boot Manager must automatically or upon the request of the loaded item, initialize at least one system console, as well as perform all required initialization of the device indicated within the primary boot target. For such systems, the Boot Manager is also required to honor the priorities set in BootOrder variable.
In particular, likely implementation options might include any console interface concerning boot, integrated platform management of boot selections, and possible knowledge of other internal applications or recovery drivers that may be integrated into the system through the boot manager.

### 3.1.1 Boot Manager Programming

Programmatic interaction with the boot manager is accomplished through globally defined variables. On initialization the boot manager reads the values which comprise all of the published load options among the UEFI environment variables. By using the `SetVariable()` function the data that contain these environment variables can be modified. Such modifications are guaranteed to take effect after the next system boot commences. However, boot manager implementations may choose to improve on this guarantee and have changes take immediate effect for all subsequent accesses to the variables that affect boot manager behavior without requiring any form of system reset.

Each load option entry resides in a `Boot####`, `Driver####`, `SysPrep####`, `OsRecovery####` or `PlatformRecovery####` variable where `####` is replaced by a unique option number in printable hexadecimal representation using the digits 0-9, and the upper case versions of the characters A-F (0000-FFFF).

The `####` must always be four digits, so small numbers must use leading zeros. The load options are then logically ordered by an array of option numbers listed in the desired order. There are two such option ordering lists when booting normally. The first is `DriverOrder` that orders the `Driver####` load option variables into their load order. The second is `BootOrder` that orders the `Boot####` load options variables into their load order.

For example, to add a new boot option, a new `Boot####` variable would be added. Then the option number of the new `Boot####` variable would be added to the `BootOrder` ordered list and the `BootOrder` variable would be rewritten. To change boot option on an existing `Boot####`, only the `Boot####` variable would need to be rewritten. A similar operation would be done to add, remove, or modify the driver load list.

If the boot via `Boot####` returns with a status of `EFI_SUCCESS`, platform firmware supports boot manager menu, and if firmware is configured to boot in an interactive mode, the boot manager will stop processing the `BootOrder` variable and present a boot manager menu to the user. If any of the above-mentioned conditions is not satisfied, the next `Boot####` in the `BootOrder` variable will be tried until all possibilities are exhausted. In this case, boot option recovery must be performed (See `Boot Option Recovery`).

The boot manager may perform automatic maintenance of the database variables. For example, it may remove unreferenced load option variables or any load option variables that cannot be parsed, and it may rewrite any ordered list to remove any load lists that do not have corresponding load option variables. The boot manager can also, at its own discretion, provide an administrator with the ability to invoke manual maintenance operations as well. Examples include choosing the order of any or all load options, activating or deactivating load options, initiating OS-defined or platform-defined recovery, etc. In addition, if a platform intends to create `PlatformRecovery####`, before attempting to load and execute any `DriverOrder` or `BootOrder` entries, the firmware must create any and all `PlatformRecovery####` variables (See `Platform-Defined Boot Option Recovery`). The firmware should not, under normal operation, automatically remove any correctly formed `Boot####` variable currently referenced by the `BootOrder` or `BootNext` variables. Such removal should be limited to scenarios where the firmware is guided by direct user interaction.

The contents of `PlatformRecovery####` represent the final recovery options the firmware would have attempted had recovery been initiated during the current boot, and need not include entries to reflect contingencies such as significant hardware reconfiguration, or entries corresponding to specific hardware that the firmware is not yet aware of.

The behavior of the UEFI Boot Manager is impacted when Secure Boot is enabled, `Firmware/OS Key Exchange: Passing Public Keys`.

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**3.1. Firmware Boot Manager**
3.1.2 Load Option Processing

The boot manager is required to process the Driver load option entries before the Boot load option entries. If the EFI_OS_INDICATIONS_START_OS_RECOVERY bit has been set in OsIndications, the firmware shall attempt OS-defined recovery (See OS-Defined Boot Option Recovery) rather than normal boot processing. If the EFI_OS_INDICATIONS_START_PLATFORM_RECOVERY bit has been set in OsIndications, the firmware shall attempt platform-defined recovery (See platform-defined-boot-option-recovery_boot_manager) rather than normal boot processing or handling of the EFI_OS_INDICATIONS_START_OS_RECOVERY bit. In either case, both bits should be cleared.

Otherwise, the boot manager is also required to initiate a boot of the boot option specified by the BootNext variable as the first boot option on the next boot, and only on the next boot. The boot manager removes the BootNext variable before transferring control to the BootNext boot option. After the BootNext boot option is tried, the normal BootOrder list is used. To prevent loops, the boot manager deletes BootNext before transferring control to the preselected boot option.

If all entries of BootNext and BootOrder have been exhausted without success, or if the firmware has been instructed to attempt boot order recovery, the firmware must attempt boot option recovery (See Boot Option Recovery).

The boot manager must call EFI_BOOT_SERVICES.LoadImage() which supports at least EFI_SIMPLE_FILE_SYSTEM_PROTOCOL and EFI_LOAD_FILE_PROTOCOL for resolving load options. If LoadImage() succeeds, the boot manager must enable the watchdog timer for 5 minutes by using the EFI_BOOT_SERVICES.SetWatchdogTimer() boot service prior to calling EFI_BOOT_SERVICES.StartImage(). If a boot option returns control to the boot manager, the boot manager must disable the watchdog timer with an additional call to the SetWatchdogTimer() boot service.

If the boot image is not loaded via EFI_BOOT_SERVICES.LoadImage() the boot manager is required to check for a default application to boot. Searching for a default application to boot happens on both removable and fixed media types. This search occurs when the device path of the boot image listed in any boot option points directly to an EFI_SIMPLE_FILE_SYSTEM_PROTOCOL device and does not specify the exact file to load. The file discovery method is explained in Boot Option Recovery. The default media boot case of a protocol other than EFI_SIMPLE_FILE_SYSTEM_PROTOCOL is handled by the EFI_LOAD_FILE_PROTOCOL for the target device path and does not need to be handled by the boot manager.

The UEFI boot manager must support booting from a short-form device path that starts with the first element being a USB WWID (USBWWIDDevicePath) or a USB Class (USBClassDevicePath) device path. For USB WWID, the boot manager must use the device vendor ID, device product id, and serial number, and must match any USB device in the system that contains this information. If more than one device matches the USB WWID device path, the boot manager will pick one arbitrarily. For USB Class, the boot manager must use the vendor ID, Product ID, Device Class, Device Subclass, and Device Protocol, and must match any USB device in the system that contains this information. If any of the ID, Product ID, Device Class, Device Subclass, or Device Protocol contain all F’s (0xFFFF or 0xFF), this element is skipped for the purpose of matching. If more than one device matches the USB Class device path, the boot manager will pick one arbitrarily.

The boot manager must also support booting from a short-form device path that starts with the first element being a hard drive media device path (Hard Drive Media Device Path). The boot manager must use the GUID or signature and partition number in the hard drive device path to match it to a device in the system. If the drive supports the GPT partitioning scheme the GUID in the hard drive media device path is compared with the UniquePartitionGuid field of the GUID Partition Entry (GPT Partition Entry). If the drive supports the PC-AT MBR scheme the signature in the hard drive media device path is compared with the UniqueMBRSignature in the Legacy Master Boot Record (Legacy MBR). If a signature match is made, then the partition number must also be matched. The hard drive device path can be appended to the matching hardware device path and normal boot behavior can then be used. If more than one device matches the hard drive device path, the boot manager will pick one arbitrarily. Thus the operating system must ensure the uniqueness of the signatures on hard drives to guarantee deterministic boot behavior.

The boot manager must also support booting from a short-form device path that starts with the first element being a File Path Media Device Path (File Path Media Device Path). When the boot manager attempts to boot a short-form File
Path Media Device Path, it will enumerate all removable media devices, followed by all fixed media devices, creating boot options for each device. The boot option FilePathList[0] is constructed by appending short-form File Path Media Device Path to the device path of a media. The order within each group is undefined. These new boot options must not be saved to non volatile storage, and may not be added to BootOrder. The boot manager will then attempt to boot from each boot option. If a device does not support the EFI_SIMPLE_FILE_SYSTEM_PROTOCOL, but supports the EFI_BLOCK_IO_PROTOCOL protocol, then the EFI Boot Service ConnectController must be called for this device with DriverImageHandle and RemainingDevicePath set to NULL and the Recursive flag is set to TRUE. The firmware will then attempt to boot from any child handles produced using the algorithms outlined above.

The boot manager must also support booting from a short-form device path that starts with the first element being a URI Device Path (URI Device Path). When the boot manager attempts to boot a short-form URI Device Path, it could attempt to connect any device which will produce a device path protocol including a URI device path node until it matches a device, or fail to match any device. The boot manager will enumerate all LoadFile protocol instances, and invoke LoadFile protocol with FilePath set to the short-form device path during the matching process.

### 3.1.3 Load Options

Each load option variable contains an EFI_LOAD_OPTION descriptor that is a byte packed buffer of variable length fields.

```c
typedef struct _EFI_LOAD_OPTION {
    UINT32 Attributes;
    UINT16 FilePathListLength;
    // CHAR16 Description[];
    // EFI_DEVICE_PATH_PROTOCOL FilePathList[];
    // UINT8 OptionalData[];
} EFI_LOAD_OPTION;
```

**Parameters**

**Attributes**

The attributes for this load option entry. All unused bits must be zero and are reserved by the UEFI specification for future growth. See “Related Definitions.”

**FilePathListLength**

Length in bytes of the FilePathList. OptionalData starts at offset sizeof(UINT32) + sizeof(UINT16) + Str-Size(Description) + FilePathListLength of the EFI_LOAD_OPTION descriptor.

**Description**

The user readable description for the load option. This field ends with a Null character.

**FilePathList**

A packed array of UEFI device paths. The first element of the array is a device path that describes the device and location of the Image for this load option. The FilePathList[0] is specific to the device type. Other device paths may optionally exist in the FilePathList, but their usage is OSV specific. Each element in the array is variable length, and ends at the device path end structure. Because the size of Description is arbitrary, this data structure is not guaranteed to be aligned on a natural boundary. This data structure may have to be copied to an aligned natural boundary before it is used.

**OptionalData**

The remaining bytes in the load option descriptor are a binary data buffer that is passed to the loaded image. If the field is zero bytes long, a NULL pointer is passed to the loaded image. The number of bytes in OptionalData can be computed by subtracting the starting offset of OptionalData from total size in bytes of the EFI_LOAD_OPTION.
```
#define LOAD_OPTION_ACTIVE 0x00000001
#define LOAD_OPTION_FORCE_RECONNECT 0x00000002
#define LOAD_OPTION_HIDDEN 0x00000008
#define LOAD_OPTION_CATEGORY 0x00001F00
#define LOAD_OPTION_CATEGORY_BOOT 0x00000000
#define LOAD_OPTION_CATEGORY_APP 0x00000100

// All values 0x00000200-0x00001F00 are reserved
```

### Description

Calling `SetVariable()` creates a load option. The size of the load option is the same as the size of the `DataSize` argument to the `SetVariable()` call that created the variable. When creating a new load option, all undefined attribute bits must be written as zero. When updating a load option, all undefined attribute bits must be preserved.

If a load option is marked as `LOAD_OPTION_ACTIVE`, the boot manager will attempt to boot automatically using the device path information in the load option. This provides an easy way to disable or enable load options without needing to delete and re-add them.

If any `Driver###` load option is marked as `LOAD_OPTION_FORCE_RECONNECT`, then all of the UEFI drivers in the system will be disconnected and reconnected after the last `Driver###` load option is processed. This allows a UEFI driver loaded with a `Driver###` load option to override a UEFI driver that was loaded prior to the execution of the UEFI Boot Manager.

The executable indicated by `FilePathList[0]` in `Driver###` load option must be of type `EFI_IMAGE_SUBSYSTEM_EFI_BOOT_SERVICE_DRIVER` or `EFI_IMAGE_SUBSYSTEM_EFI_RUNTIME_DRIVER` otherwise the indicated executable will not be entered for initialization.

The executable indicated by `FilePathList[0]` in `SysPrep###`, `Boot###`, or `OsRecovery###` load option must be of type `EFI_IMAGE_SUBSYSTEM_EFI_APPLICATION`, otherwise the indicated executable will not be entered.

The `LOAD_OPTION_CATEGORY` is a sub-field of `Attributes` that provides details to the boot manager to describe how it should group the `Boot###` load options. This field is ignored for variables of the form `Driver###`, `SysPrep###`, or `OsRecovery###`.

`Boot###` load options with `LOAD_OPTION_CATEGORY` set to `LOAD_OPTION_CATEGORY_BOOT` are meant to be part of the normal boot processing.

`Boot###` load options with `LOAD_OPTION_CATEGORY` set to `LOAD_OPTION_CATEGORY_APP` are executables which are not part of the normal boot processing but can be optionally chosen for execution if boot menu is provided, or via Hot Keys. See `Launching Boot### Load Options Using Hot Keys` for details.

Boot options with reserved category values, will be ignored by the boot manager.

If any `Boot###` load option is marked as `LOAD_OPTION_HIDDEN`, then the load option will not appear in the menu (if any) provided by the boot manager for load option selection.

---

3.1. Firmware Boot Manager
3.1.4 Boot Manager Capabilities

The boot manager can report its capabilities through the global variable `BootOptionSupport`. If the global variable is not present, then an installer or application must act as if a value of 0 was returned.

```c
#define EFI_BOOT_OPTION_SUPPORT_KEY 0x00000001
#define EFI_BOOT_OPTION_SUPPORT_APP 0x00000002
#define EFI_BOOT_OPTION_SUPPORT_SYSPREP 0x00000010
#define EFI_BOOT_OPTION_SUPPORT_COUNT 0x00000300
```

If `EFI_BOOT_OPTION_SUPPORT_KEY` is set then the boot manager supports launching of `Boot####` load options using key presses. If `EFI_BOOT_OPTION_SUPPORT_APP` is set then the boot manager supports boot options with `LOAD_OPTION_CATEGORY_APP`. If `EFI_BOOT_OPTION_SUPPORT_SYSPREP` is set then the boot manager supports boot options of form `SysPrep####`.

The value specified in `EFI_BOOT_OPTION_SUPPORT_COUNT` describes the maximum number of key presses which the boot manager supports in the `EFI_KEY_OPTION.KeyData.InputKeyCount`. This value is only valid if `EFI_BOOT_OPTION_SUPPORT_KEY` is set. Key sequences with more keys specified are ignored.

3.1.5 Launching Boot#### Applications

The boot manager may support a separate category of `Boot####` load option for applications. The boot manager indicates that it supports this separate category by setting the `EFI_BOOT_OPTION_SUPPORT_APP` in the `BootOptionSupport` global variable.

When an application’s `Boot####` option is being added to the `BootOrder`, the installer should clear `LOAD_OPTION_ACTIVE` so that the boot manager does not attempt to automatically “boot” the application. If the boot manager indicates that it supports a separate application category, as described above, the installer should set `LOAD_OPTION_CATEGORY_APP`. If not, it should set `LOAD_OPTION_CATEGORY_BOOT`.

3.1.6 Launching Boot#### Load Options Using Hot Keys

The boot manager may support launching a `Boot####` load option using a special key press. If so, the boot manager reports this capability by setting `EFI_BOOT_OPTION_SUPPORT_KEY` in the `BootOptionSupport` global variable.

A boot manager which supports key press launch reads the current key information from the console. Then, if there was a key press, it compares the key returned against zero or more `Key####` global variables. If it finds a match, it verifies that the `Boot####` load option specified is valid and, if so, attempts to launch it immediately. The `####` in the `Key####` is a printable hexadecimal number (‘0’-‘9’, ‘A’-‘F’) with leading zeroes. The order which the `Key####` variables are checked is implementation-specific.

The boot manager may ignore `Key####` variables where the hot keys specified overlap with those used for internal boot manager functions. It is recommended that the boot manager delete these keys.

The `Key####` variables have the following format:

**Prototype**

```c
typedef struct _EFI_KEY_OPTION {
   EFI_BOOT_KEY_DATA     KeyData;
   UINT32                BootOptionCrc;
   UINT16                BootOption;
   // EFI_INPUT_KEY       Keys[];
} EFI_KEY_OPTION;
```

**Parameters**
KeyData
Specifies options about how the key will be processed. Type EFI_BOOT_KEY_DATA is defined in “Related Definitions” below.

BootOptionCrc
The CRC-32 which should match the CRC-32 of the entire EFI_LOAD_OPTION to which BootOption refers. If the CRC-32s do not match this value, then this key option is ignored.

BootOption
The Boot## option which will be invoked if this key is pressed and the boot option is active (LOAD_OPTION_ACTIVE is set).

Keys
The key codes to compare against those returned by the EFI_SIMPLE_TEXT_INPUT and EFI_SIMPLE_TEXT_INPUT_EX protocols. The number of key codes (0-3) is specified by the EFI_KEY_CODE_COUNT field in KeyOptions.

Related Definitions

```c
typedef union {
    struct {
        UINT32 Revision : 8;
        UINT32 ShiftPressed : 1;
        UINT32 ControlPressed : 1;
        UINT32 AltPressed : 1;
        UINT32 LogoPressed : 1;
        UINT32 MenuPressed : 1;
        UINT32 SysReqPressed : 1;
        UINT32 Reserved : 16;
        UINT32 InputKeyCount : 2;
    } Options;
    UINT32 PackedValue;
} EFI_BOOT_KEY_DATA;
```

Revision
Indicates the revision of the EFI_KEY_OPTION structure. This revision level should be 0.

ShiftPressed
Either the left or right Shift keys must be pressed (1) or must not be pressed (0).

ControlPressed
Either the left or right Control keys must be pressed (1) or must not be pressed (0).

AltPressed
Either the left or right Alt keys must be pressed (1) or must not be pressed (0).

LogoPressed
Either the left or right Logo keys must be pressed (1) or must not be pressed (0).

MenuPressed
The Menu key must be pressed (1) or must not be pressed (0).

SysReqPressed
The SysReq key must be pressed (1) or must not be pressed (0).

InputKeyCount
Specifies the actual number of entries in EFI_KEY_OPTION. Keys, from 0-3. If zero, then only the shift state is considered. If more than one, then the boot option will only be launched if all of the specified keys are pressed with the same shift state.
Example #1: ALT is the hot key. KeyData.PackedValue = 0x00000400.

Example #2: CTRL-ALT-P-R. KeyData.PackedValue = 0x80000600.

Example #3: CTRL-F1. KeyData.PackedValue = 0x40000200.

3.1.7 Required System Preparation Applications

A load option of the form SysPrep#### is intended to designate a UEFI application that is required to execute in order to complete system preparation prior to processing of any Boot#### variables. The execution order of SysPrep#### applications is determined by the contents of the variable SysPrepOrder in a way directly analogous to the ordering of Boot#### options by BootOrder.

The platform is required to examine all SysPrep#### variables referenced in SysPrepOrder. If Attributes bit LOAD_OPTION_ACTIVE is set, and the application referenced by FilePathList[0] is present, the UEFI Applications thus identified must be loaded and launched in the order they appear in SysPrepOrder and prior to the launch of any load options of type Boot####.

When launched, the platform is required to provide the application loaded by SysPrep####, with the same services such as console and network as are normally provided at launch to applications referenced by a Boot#### variable. SysPrep#### application must exit and may not call ExitBootServices(). Processing of any Error Code returned at exit is according to system policy and does not necessarily change processing of following boot options. Any driver portion of the feature supported by SysPrep#### boot option that is required to remain resident should be loaded by use of Driver#### variable.

The Attributes option LOAD_OPTION_FORCE_RECONNECT is ignored for SysPrep#### variables, and in the event that an application so launched performs some action that adds to the available hardware or drivers, the system preparation application shall itself utilize appropriate calls to ConnectController() or DisconnectController() to revise connections between drivers and hardware.

After all SysPrep#### variables have been launched and exited, the platform shall notify EFI_EVENT_GROUP_READY_TO_BOOT and EFI_EVENT_GROUP_AFTER_READY_TO_BOOT event groups. This should happen when the Boot Manager is about to load and execute Boot#### variables with Attributes set to LOAD_OPTIONCATEGORY_BOOT according to the order defined by BootOrder.

3.2 Boot Manager Policy Protocol

3.2.1 EFI_BOOT_MANAGER_POLICY_PROTOCOL

Summary

This protocol is used by EFI Applications to request the UEFI Boot Manager to connect devices using platform policy.

GUID

```c
#define EFI_BOOT_MANAGER_POLICY_PROTOCOL_GUID \ { 0xFEDF8E0C, 0xE147, 0x11E3, \ { 0x99, 0x03, 0xB8, 0xE8, 0x56, 0x2C, 0xBA, 0xFA } }
```

Protocol Interface Structure
typedef struct _EFI_BOOT_MANAGER_POLICY_PROTOCOL
    EFI_BOOT_MANAGER_POLICY_PROTOCOL;
struct _EFI_BOOT_MANAGER_POLICY_PROTOCOL {
    UINT64 Revision;
    EFI_BOOT_MANAGER_POLICY_CONNECT_DEVICE_PATH ConnectDevicePath;
    EFI_BOOT_MANAGER_POLICY_CONNECT_DEVICE_CLASS ConnectDeviceClass;
};

ConnectDevicePath
    Connect a Device Path following the platforms EFI Boot Manager policy.

ConnectDeviceClass
    Connect a class of devices, named by EFI_GUID, following the platforms UEFI Boot Manager policy.

Description
    The EFI_BOOT_MANAGER_POLICY_PROTOCOL is produced by the platform firmware to ex-
    pose Boot Manager policy and platform specific EFI_BOOT_SERVICES.ConnectController() 
    EFI_BOOT_SERVICES.ConnectController() behavior.

Related Definitions

#define EFI_BOOT_MANAGER_POLICY_PROTOCOL_REVISION 0x00010000

3.2.2 EFI_BOOT_MANAGER_POLICY_PROTOCOL.ConnectDevicePath()

Summary
    Connect a device path following the platform’s EFI Boot Manager policy.

Prototype
    typedef
    EFI_STATUS
    (EFIAPI *EFI_BOOT_MANAGER_POLICY_CONNECT_DEVICE_PATH)(
        IN EFI_BOOT_MANAGER_POLICY_PROTOCOL *This,
        IN EFI_DEVICE_PATH *DevicePath,
        IN BOOLEAN Recursive
    );

Parameters

This
    A pointer to the EFI_BOOT_MANAGER_POLICY_PROTOCOL instance. Type 
    EFI_BOOT_MANAGER_POLICY_PROTOCOL defined above.

DevicePath
    Points to the start of the EFI device path to connect. If DevicePath is NULL then all the controllers in the system 
    will be connected using the platform’s EFI Boot Manager policy.

Recursive
    If TRUE, then ConnectController() is called recursively until the entire tree of controllers below the controller 
    specified by DevicePath have been created. If FALSE, then the tree of controllers is only expanded one level. If 
    DevicePath is NULL then Recursive is ignored.

Description
The `ConnectDevicePath()` function allows the caller to connect a `DevicePath` using the same policy as the EFI Boot Manager.

If `Recursive` is **TRUE**, then `ConnectController()` is called recursively until the entire tree of controllers below the controller specified by `DevicePath` have been created. If `Recursive` is **FALSE**, then the tree of controllers is only expanded one level. If `DevicePath` is NULL then `Recursive` is ignored.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The <code>DevicePath</code> was connected</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The <code>DevicePath</code> was not found</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No driver was connected to <code>DevicePath</code>.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The user has no permission to start UEFI device drivers</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The current TPL is not <code>TPL_APPLICATION</code>.</td>
</tr>
</tbody>
</table>

3.2.3 **EFI_BOOT_MANAGER_POLICY_PROTOCOL.ConnectDeviceClass()**

**Summary**

Connect a class of devices using the platform Boot Manager policy.

**Prototype**

```c
typedef EFI_STATUS (EFIAPICALLTYPE *EFI_BOOT_MANAGER_POLICY_CONNECT_DEVICE_CLASS)(
    IN EFI_BOOT_MANAGER_POLICY_PROTOCOL *This,
    IN EFI_GUID *Class
);
```

**Parameters**

**This**

A pointer to the `EFI_BOOT_MANAGER_POLICY_PROTOCOL` instance. Type `EFI_BOOT_MANAGER_POLICY_PROTOCOL` is defined above.

**Class**

A pointer to an `EFI_GUID` that represents a class of devices that will be connected using the Boot Manager’s platform policy.

**Description**

The `ConnectDeviceClass()` function allows the caller to request that the Boot Manager connect a class of devices.

If `Class` is `EFI_BOOT_MANAGER_POLICY_CONSOLE_GUID` then the Boot Manager will use platform policy to connect consoles. Some platforms may restrict the number of consoles connected as they attempt to fast boot, and calling `ConnectDeviceClass()` with a `Class` value of `EFI_BOOT_MANAGER_POLICY_CONSOLE_GUID` must connect the set of consoles that follow the Boot Manager platform policy, and the `EFI_SIMPLE_TEXT_INPUT_PROTOCOL`, `EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL`, and the `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL` are produced on the connected handles. The Boot Manager may restrict which consoles get connected due to platform policy, for example a security policy may require that a given console is not connected.

If `Class` is `EFI_BOOT_MANAGER_POLICY_NETWORK_GUID` then the Boot Manager will connect the protocols the platform supports for UEFI general purpose network applications on one or more handles. The protocols associated with UEFI general purpose network applications are defined in Platform-Specific Elements, list item number 7. If more than one network controller is available a platform will connect, one, many, or all of the networks based on platform policy. Connecting UEFI networking protocols, like `EFI_DHCP4_PROTOCOL`, does not establish connections on
the network. The UEFI general purpose network application that called ConnectDeviceClass() may need to use the published protocols to establish the network connection. The Boot Manager can optionally have a policy to establish a network connection.

If Class is EFI_BOOT_MANAGER_POLICY_CONNECT_ALL_GUID then the Boot Manager will connect all UEFI drivers using the UEFI Boot Service EFI_BOOT_SERVICES.ConnectController(). If the Boot Manager has policy associated with connect all UEFI drivers this policy will be used.

A platform can also define platform specific Class values as a properly generated EFI_GUID would never conflict with this specification.

Related Definitions

```
#define EFI_BOOT_MANAGER_POLICY_CONSOLE_GUID
   { 0xCAB0E94C, 0xE15F, 0x11E3,\n     { 0x91, 0x8D, 0xB8, 0xE8, 0x56, 0x2C, 0xBA, 0xFA } }
#define EFI_BOOT_MANAGER_POLICY_NETWORK_GUID
   { 0xD04159DC, 0xE15F, 0x11E3,\n     { 0xB2, 0x61, 0xB8, 0xE8, 0x56, 0x2C, 0xBA, 0xFA } }
#define EFI_BOOT_MANAGER_POLICY_CONNECT_ALL_GUID
   { 0x113B2126, 0xFC8A, 0x11E3,\n     { 0xBD, 0x6C, 0xB8, 0xE8, 0x56, 0x2C, 0xBA, 0xFA } }
```

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>At least one devices of the Class was connected.</td>
</tr>
<tr>
<td>EFI_DE_ERROR</td>
<td>Devices were not connected due to an error.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The Class is not supported by the platform.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The current TPL is not TPL_APPLICATION.</td>
</tr>
</tbody>
</table>

3.3 Globally Defined Variables

This section defines a set of variables that have architecturally defined meanings. In addition to the defined data content, each such variable has an architecturally defined attribute that indicates when the data variable may be accessed. The variables with an attribute of NV are nonvolatile. This means that their values are persistent across resets and power cycles. The value of any environment variable that does not have this attribute will be lost when power is removed from the system and the state of firmware reserved memory is not otherwise preserved. The variables with an attribute of BS are only available before EFI_BOOT_SERVICES.ExitBootServices() is called. This means that these environment variables can only be retrieved or modified in the preboot environment. They are not visible to an operating system. Environment variables with an attribute of RT are available before and after ExitBootServices() is called. Environment variables of this type can be retrieved and modified in the preboot environment, and from an operating system. The variables with an attribute of AT are variables with a time-based authenticated write access defined in Using the EFI_VARIABLE_AUTHENTICATION_3 descriptor. All architecturally defined variables use the EFI_GLOBAL_VARIABLE VendorGuid.

```
#define EFI_GLOBAL_VARIABLE
   {0x8BE4DF61,0x93CA,0x11d2,\n    {0xAA,0x0D,0x00,0xE0,0x98,0x03,0x2B,0x8C}}
```

To prevent name collisions with possible future globally defined variables, other internal firmware data variables that are not defined here must be saved with a unique VendorGuid other than EFI_GLOBAL_VARIABLE or any other GUID defined by the UEFI Specification. Implementations must only permit the creation of variables with a UEFI Specification-defined VendorGuid when these variables are documented in the UEFI Specification.
Table 3.3: Global Variables

<table>
<thead>
<tr>
<th>Variable Name</th>
<th>Attribute</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AuditMode</td>
<td>BS, RT</td>
<td>Whether the system is operating in Audit Mode (1) or not (0). All other values are reserved. Should be treated as read-only except when DeployedMode is 0. Always becomes read-only after ExitBootServices() is called.</td>
</tr>
<tr>
<td>Boot####</td>
<td>NV, BS, RT</td>
<td>A boot load option. #### is a printed hex value. No 0x or h is included in the hex value.</td>
</tr>
<tr>
<td>BootCurrent</td>
<td>BS, RT</td>
<td>The boot option that was selected for the current boot.</td>
</tr>
<tr>
<td>BootNext</td>
<td>NV, BS, RT</td>
<td>The boot option for the next boot only.</td>
</tr>
<tr>
<td>BootOrder</td>
<td>NV, BS, RT</td>
<td>The ordered boot option load list.</td>
</tr>
<tr>
<td>BootOptionSupport</td>
<td>BS, RT</td>
<td>The types of boot options supported by the boot manager. Should be treated as read-only.</td>
</tr>
<tr>
<td>ConIn</td>
<td>NV, BS, RT</td>
<td>The device path of the default input console.</td>
</tr>
<tr>
<td>ConInDev</td>
<td>BS, RT</td>
<td>The device path of all possible console input devices.</td>
</tr>
<tr>
<td>ConOut</td>
<td>NV, BS, RT</td>
<td>The device path of the default output console.</td>
</tr>
<tr>
<td>ConOutDev</td>
<td>BS, RT</td>
<td>The device path of all possible console output devices.</td>
</tr>
<tr>
<td>dbDefault</td>
<td>BS, RT</td>
<td>The OEM’s default secure boot signature store. Should be treated as read-only.</td>
</tr>
<tr>
<td>dbrDefault</td>
<td>BS, RT</td>
<td>The OEM’s default OS Recovery signature store. Should be treated as read-only.</td>
</tr>
<tr>
<td>dbtDefault</td>
<td>BS, RT</td>
<td>The OEM’s default secure boot timestamp signature store. Should be treated as read-only.</td>
</tr>
<tr>
<td>dbxDefault</td>
<td>BS, RT</td>
<td>The OEM’s default secure boot blacklist signature store. Should be treated as read-only.</td>
</tr>
<tr>
<td>DeployedMode</td>
<td>BS, RT</td>
<td>Whether the system is operating in Deployed Mode (1) or not (0). All other values are reserved. Should be treated as read-only when its value is 1. Always becomes read-only after ExitBootServices() is called.</td>
</tr>
<tr>
<td>Driver####</td>
<td>NV, BS, RT</td>
<td>A driver load option. #### is a printed hex value.</td>
</tr>
<tr>
<td>DriverOrder</td>
<td>NV, BS, RT</td>
<td>The ordered driver load option list.</td>
</tr>
<tr>
<td>ErrOut</td>
<td>NV, BS, RT</td>
<td>The device path of the default error output device.</td>
</tr>
<tr>
<td>ErrOutDev</td>
<td>BS, RT</td>
<td>The device path of all possible error output devices.</td>
</tr>
<tr>
<td>HwErrRecSupport</td>
<td>NV, BS, RT</td>
<td>Identifies the level of hardware error record persistence support implemented by the platform. This variable is only modified by firmware and is read-only to the OS.</td>
</tr>
<tr>
<td>KEK</td>
<td>NV, BS, RT,AT</td>
<td>The Key Exchange Key Signature Database.</td>
</tr>
<tr>
<td>KEKDefault</td>
<td>BS, RT</td>
<td>The OEM’s default Key Exchange Key Signature Database. Should be treated as read-only.</td>
</tr>
<tr>
<td>Key####</td>
<td>NV, BS, RT</td>
<td>Describes hot key relationship with a Boot#### load option.</td>
</tr>
<tr>
<td>Lang</td>
<td>NV, BS, RT</td>
<td>The language code that the system is configured for. This value is deprecated.</td>
</tr>
<tr>
<td>LangCodes</td>
<td>BS, RT</td>
<td>The language codes that the firmware supports. This value is deprecated.</td>
</tr>
<tr>
<td>OsIndications</td>
<td>NV, BS, RT</td>
<td>Allows the OS to request the firmware to enable certain features and to take certain actions.</td>
</tr>
<tr>
<td>OsIndicationsSupported</td>
<td>BS, RT</td>
<td>Allows the firmware to indicate supported features and actions to the OS.</td>
</tr>
<tr>
<td>OsRecoveryOrder</td>
<td>BS, RT, NV, AT</td>
<td>OS-specified recovery options.</td>
</tr>
<tr>
<td>PK</td>
<td>NV, BS, RT, AT</td>
<td>The public Platform Key.</td>
</tr>
</tbody>
</table>

continues on next page
### Table 3.3 – continued from previous page

<table>
<thead>
<tr>
<th>Variable</th>
<th>Access</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>PKDefault</td>
<td>BS, RT</td>
<td></td>
<td>The OEM’s default public Platform Key. Should be treated as read-only.</td>
</tr>
<tr>
<td>PlatformLangCodes</td>
<td>BS, RT</td>
<td></td>
<td>The language codes that the firmware supports.</td>
</tr>
<tr>
<td>PlatformLang</td>
<td>NV, BS, RT</td>
<td></td>
<td>The language code that the system is configured for.</td>
</tr>
<tr>
<td>PlatformRecovery####</td>
<td>BS, RT</td>
<td></td>
<td>Platform-specified recovery options. These variables are only modified by firmware and are read-only to the OS.</td>
</tr>
<tr>
<td>SignatureSupport</td>
<td>BS, RT</td>
<td></td>
<td>Array of GUIDs representing the type of signatures supported by the platform firmware. Should be treated as read-only.</td>
</tr>
<tr>
<td>SecureBoot</td>
<td>BS, RT</td>
<td></td>
<td>Whether the platform firmware is operating in Secure boot mode (1) or not (0). All other values are reserved. Should be treated as read-only.</td>
</tr>
<tr>
<td>SetupMode</td>
<td>BS, RT</td>
<td></td>
<td>Whether the system should require authentication on SetVariable() requests to Secure Boot policy variables (0) or not (1). Should be treated as read-only. The system is in “Setup Mode” when SetupMode==1, AuditMode==0, and DeployedMode==0.</td>
</tr>
<tr>
<td>SysPrep####</td>
<td>NV, BS, RT</td>
<td></td>
<td>A System Prep application load option containing an EFI_LOAD_OPTION descriptor. #### is a printed hex value.</td>
</tr>
<tr>
<td>SysPrepOrder</td>
<td>NV, BS, RT</td>
<td></td>
<td>The ordered System Prep Application load option list.</td>
</tr>
<tr>
<td>Timeout</td>
<td>NV, BS, RT</td>
<td></td>
<td>The firmware’s boot managers timeout, in seconds, before initiating the default boot selection.</td>
</tr>
<tr>
<td>VendorKeys</td>
<td>BS, RT</td>
<td></td>
<td>Whether the system is configured to use only vendor-provided keys or not. Should be treated as read-only.</td>
</tr>
</tbody>
</table>

The PlatformLangCodes variable contains a null-terminated ASCII string representing the language codes that the firmware can support. At initialization time the firmware computes the supported languages and creates this data variable. Since the firmware creates this value on each initialization, its contents are not stored in nonvolatile memory. This value is considered read-only. PlatformLangCodes is specified in Native RFC 4646 format. Appendix M — Formats — Language Codes and Language Code Arrays. LangCodes is deprecated and may be provided for backwards compatibility.

The PlatformLang variable contains a null-terminated ASCII string language code that the machine has been configured for. This value may be changed to any value supported by PlatformLangCodes. If this change is made in the preboot environment, then the change will take effect immediately. If this change is made at OS runtime, then the change does not take effect until the next boot. If the language code is set to an unsupported value, the firmware will choose a supported default at initialization and set PlatformLang to a supported value. PlatformLang is specified in Native RFC 4646 array format. Appendix M — Formats — Language Codes and Language Code Arrays. Lang is deprecated and may be provided for backwards compatibility.

Lang has been deprecated. If the platform supports this variable, it must map any changes in the Lang variable into PlatformLang in the appropriate format.

Langcodes has been deprecated. If the platform supports this variable, it must map any changes in the Langcodes variable into PlatformLang in the appropriate format.

The Timeout variable contains a binary UINT16 that supplies the number of seconds that the firmware will wait before initiating the original default boot selection. A value of 0 indicates that the default boot selection is to be initiated immediately on boot. If the value is not present, or contains the value of 0xFFFF then firmware will wait for user input before booting. This means the default boot selection is not automatically started by the firmware.

The ConIn, ConOut, and ErrOut variables each contain an EFI Device Path Protocol descriptor that defines the default device to use on boot. Changes to these values made in the preboot environment take effect immediately. Changes to these values at OS runtime do not take effect until the next boot. If the firmware cannot resolve the device path, it is allowed to automatically replace the values, as needed, to provide a console for the system. If the device path starts with a USB Class device path (USB Class Device Path), then any input or output device that matches the device path must be used as a console if it is supported by the firmware.

### 3.3. Globally Defined Variables

The PlatformLangCodes variable contains a null-terminated ASCII string representing the language codes that the firmware can support. At initialization time the firmware computes the supported languages and creates this data variable. Since the firmware creates this value on each initialization, its contents are not stored in nonvolatile memory. This value is considered read-only. PlatformLangCodes is specified in Native RFC 4646 format. Appendix M — Formats — Language Codes and Language Code Arrays. LangCodes is deprecated and may be provided for backwards compatibility.

The PlatformLang variable contains a null-terminated ASCII string language code that the machine has been configured for. This value may be changed to any value supported by PlatformLangCodes. If this change is made in the preboot environment, then the change will take effect immediately. If this change is made at OS runtime, then the change does not take effect until the next boot. If the language code is set to an unsupported value, the firmware will choose a supported default at initialization and set PlatformLang to a supported value. PlatformLang is specified in Native RFC 4646 array format. Appendix M — Formats — Language Codes and Language Code Arrays. Lang is deprecated and may be provided for backwards compatibility.

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The ConIn, ConOut, and ErrOut variables each contain an EFI Device Path Protocol descriptor that defines the default device to use on boot. Changes to these values made in the preboot environment take effect immediately. Changes to these values at OS runtime do not take effect until the next boot. If the firmware cannot resolve the device path, it is allowed to automatically replace the values, as needed, to provide a console for the system. If the device path starts with a USB Class device path (USB Class Device Path), then any input or output device that matches the device path must be used as a console if it is supported by the firmware.
The `ConInDev`, `ConOutDev`, and `ErrOutDev` variables each contain an `EFI_DEVICE_PATH_PROTOCOL` descriptor that defines all the possible default devices to use on boot. These variables are volatile, and are set dynamically on every boot. `ConIn`, `ConOut`, and `ErrOut` are always proper subsets of `ConInDev`, `ConOutDev`, and `ErrOutDev`.

Each `Boot###` variable contains an `EFI_LOAD_OPTION`. Each `Boot###` variable is the name “Boot” appended with a unique four digit hexadecimal number. For example, `Boot0001`, `Boot0002`, `Boot0A02`, etc.

The `OsRecoveryOrder` variable contains an array of `EFI_GUID` structures. Each `EFI_GUID` structure specifies a namespace for variables containing OS-defined recovery entries (See `OS-DefinedBootOptionRecovery`). Write access to this variable is controlled by the security key database db (Using the `EFI_VARIABLE_AUTHENTICATION_3 descriptor`).

PlatformRecovery### variables share the same structure as Boot### variables. These variables are processed when the system is performing recovery of boot options.

The `BootOrder` variable contains an array of `UINT16`’s that make up an ordered list of the `Boot###` options. The first element in the array is the value for the first logical boot option, the second element is the value for the second logical boot option, etc. The `BootOrder` order list is used by the firmware’s boot manager as the default boot order.

The `BootNext` variable is a single `UINT16` that defines the `Boot###` option that is to be tried first on the next boot. After the `BootNext` boot option is tried the normal `BootOrder` list is used. To prevent loops, the boot manager deletes this variable before transferring control to the preselected boot option.

The `BootCurrent` variable is a single `UINT16` that defines the `Boot###` option that was selected on the current boot. The platform sets this variable before signaling `EFI_EVENT_GROUP_READY_TO_BOOT`. This variable is not set when attempting to launch OsRecovery### or PlatformRecovery### options.

The `BootOptionSupport` variable is a `UINT32` that defines the types of boot options supported by the boot manager.

Each `Driver###` variable contains an `EFI_LOAD_OPTION`. Each load option variable is appended with a unique number, for example `Driver0001`, `Driver0002`, etc.

The `DriverOrder` variable contains an array of `UINT16`’s that make up an ordered list of the `Driver###` variable. The first element in the array is the value for the first logical driver load option, the second element is the value for the second logical driver load option, etc. The `DriverOrder` list is used by the firmware’s boot manager as the default load order for UEFI drivers that it should explicitly load.

The `Key###` variable associates a key press with a single boot option. Each `Key###` variable is the name “Key” appended with a unique four digit hexadecimal number. For example, `Key0001`, `Key0002`, `Key00A0`, etc.

The `HwErrRecSupport` variable contains a binary `UINT16` that supplies the level of support for Hardware Error Record Persistence (`Hardware Error Record Persistence`) that is implemented by the platform. If the value is not present, then the platform implements no support for Hardware Error Record Persistence. A value of zero indicates that the platform implements no support for Hardware Error Record Persistence. A value of 1 indicates that the platform implements Hardware Error Record Persistence as defined in `Hardware Error Record Persistence`. Firmware initializes this variable. All other values are reserved for future use.

The `SetupMode` variable is an 8-bit unsigned integer that defines whether the system is should require authentication (0) or not (1) on `SetVariable()` requests to Secure Boot Policy Variables. Secure Boot Policy Variables include:

- The global variables `PK`, `KEK`, and `OsRecoveryOrder`
- All variables named `OsRecovery###` under all VendorGuids
- All variables with the VendorGuid `EFI_IMAGE_SECURITY_DATABASE_GUID`.

Secure Boot Policy Variables must be created using the `EFI_VARIABLE_AUTHENTICATION_2` structure.

The `AuditMode` variable is an 8-bit unsigned integer that defines whether the system is currently operating in Audit Mode.

The `DeployedMode` variable is an 8-bit unsigned integer that defines whether the system is currently operating in Deployed Mode.
The KEK variable contains the current Key Exchange Key database.

The PK variable contains the current Platform Key.

The VendorKeys variable is an 8-bit unsigned integer that defines whether the Security Boot Policy Variables have been modified by anyone other than the platform vendor or a holder of the vendor-provided keys. A value of 0 indicates that someone other than the platform vendor or a holder of the vendor-provided keys has modified the Secure Boot Policy Variables Otherwise, the value will be 1.

The KEKDefault variable, if present, contains the platform-defined Key Exchange Key database. This is not used at runtime but is provided in order to allow the OS to recover the OEM’s default key setup. The contents of this variable do not include an EFI_VARIABLE_AUTHENTICATION or EFI_VARIABLE_AUTHENTICATION2 structure.

The PKDefault variable, if present, contains the platform-defined Platform Key. This is not used at runtime but is provided in order to allow the OS to recover the OEM’s default key setup. The contents of this variable do not include an EFI_VARIABLE_AUTHENTICATION2 structure.

The dbDefault variable, if present, contains the platform-defined secure boot signature database. This is not used at runtime but is provided in order to allow the OS to recover the OEM’s default key setup. The contents of this variable do not include an EFI_VARIABLE_AUTHENTICATION2 structure.

The dbrDefault variable, if present, contains the platform-defined secure boot authorized recovery signature database. This is not used at runtime but is provided in order to allow the OS to recover the OEM’s default key setup. The contents of this variable do not include an EFI_VARIABLE_AUTHENTICATION2 structure.

The dbtDefault variable, if present, contains the platform-defined secure boot timestamp signature database. This is not used at runtime but is provided in order to allow the OS to recover the OEM’s default key setup. The contents of this variable do not include an EFI_VARIABLE_AUTHENTICATION2 structure.

The dbxDefault variable, if present, contains the platform-defined secure boot blacklist signature database. This is not used at runtime but is provided in order to allow the OS to recover the OEM’s default key setup. The contents of this variable do not include an EFI_VARIABLE_AUTHENTICATION2 structure.

The SignatureSupport variable returns an array of GUIDs, with each GUID representing a type of signature which the platform firmware supports for images and other data. The different signature types are described in “Signature Database”.

The SecureBoot variable is an 8-bit unsigned integer that defines whether the platform firmware is operating with Secure Boot enabled. A value of 1 indicates that platform firmware performs driver and boot application signature verification as specified in UEFI Image Validation during the current boot. A value of 0 indicates that driver and boot application signature verification is not active during the current boot. The SecureBoot variable is initialized prior to Secure Boot image authentication and thereafter should be treated as read-only and immutable. Its initialization value is determined by platform policy but must be 0 if the platform is in Setup Mode or Audit Mode during its initialization.

The OsIndicationsSupported variable indicates which of the OS indication features and actions that the firmware supports. This variable is recreated by firmware every boot, and cannot be modified by the OS (see SetVariable() Attributes usage rules once ExitBootServices() is performed).

The OsIndications variable is used to indicate which features the OS wants firmware to enable or which actions the OS wants the firmware to take. The OS will supply this data with a SetVariable() call. Exchanging information between the OS and Firmware for the variable definition.
3.4 Boot Option Recovery

Boot option recovery consists of two independent parts, operating system-defined recovery and platform-defined recovery. OS-defined recovery is an attempt to allow installed operating systems to recover any needed boot options, or to launch full operating system recovery. Platform-defined recovery includes any remedial actions performed by the platform as a last resort when no operating system is found, such as the Default Boot Behavior (Boot Option Variables Default Boot Behavior). This could include behaviors such as warranty service reconfiguration or diagnostic options.

In the event that boot option recovery must be performed, the boot manager must first attempt OS-defined recovery, re-attempt normal booting via Boot#### and BootOrder variables, and finally attempt platform-defined recovery if no options have succeeded.

3.4.1 OS-Defined Boot Option Recovery

If the EFI_OS_INDICATIONS_START_OS_RECOVERY bit is set in OsIndications, or if processing of BootOrder does not result in success, the platform must process OS-defined recovery options. In the case where OS-defined recovery is entered due to OsIndications, SysPrepOrder and SysPrep#### variables should not be processed. Note that in order to avoid ambiguity in intent, this bit is ignored in OsIndications if EFI_OS_INDICATIONS_START_PLATFORM_RECOVERY is set.

OS-defined recovery uses the OsRecoveryOrder variable, as well as variables created with vendor specific VendorGuid values and a name following the pattern OsRecovery####. Each of these variables must be an authenticated variable with the EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS attribute set.

To process these variables, the boot manager iterates over the array of EFI_GUID structures in the OsRecoveryOrder variable, and each GUID specified is treated as a VendorGuid associated with a series of variable names. For each GUID, the firmware attempts to load and execute, in hexadecimal sort order, every variable with that GUID and a name following the pattern OsRecovery####. These variables have the same format as Boot#### variables, and the boot manager must verify that each variable it attempts to load was created with a public key that is associated with a certificate chaining to one listed in the authorized recovery signature database dbr and not in the forbidden signature database, or is created by a key in the Key Exchange Key database KEK or the current Platform Key PK.

If the boot manager finishes processing OsRecovery#### options without EFI_BOOT_SERVICES.ExitBootServices() or ResetSystem() having been called, it must attempt to process BootOrder a second time. If booting does not succeed during that process, OS-defined recovery has failed, and the boot manager must attempt platform-based recovery.

If, while processing OsRecovery#### variables, the boot manager encounters an entry which cannot be loaded or executed due to a security policy violation, it must ignore that variable.

3.4.2 Platform-Defined Boot Option Recovery

If the EFI_OS_INDICATIONS_START_PLATFORM_RECOVERY bit is set in OsIndications, or if OS-defined recovery has failed, the system firmware must commence with platform-specific recovery by iterating its PlatformRecovery#### variables in the same manner as OsRecovery####, but must stop processing if any entry is successful. In the case where platform-specific recovery is entered due to OsIndications, SysPrepOrder and SysPrep#### variables should not be processed.
3.4.3 Boot Option Variables Default Boot Behavior

The default state of globally-defined variables is firmware vendor specific. However the boot options require a standard default behavior in the exceptional case that valid boot options are not present on a platform. The default behavior must be invoked any time the BootOrder variable does not exist or only points to nonexistent boot options, or if no entry in BootOrder can successfully be executed.

If system firmware supports boot option recovery as described in Boot Option Recovery, system firmware must include a PlatformRecovery### variable specifying a short-form File Path Media Device Path (Load Option Processing) containing the platform default file path for removable media (UEFI Image Types). It is recommended for maximal compatibility with prior versions of this specification that this entry be the first such variable, though it may be at any position within the list.

It is expected that this default boot will load an operating system or a maintenance utility. If this is an operating system setup program it is then responsible for setting the requisite environment variables for subsequent boots. The platform firmware may also decide to recover or set to a known set of boot options.

3.5 Boot Mechanisms

EFI can boot from a device using the EFI_SIMPLE_FILE_SYSTEM_PROTOCOL or the EFI_LOAD_FILE_PROTOCOL. A device that supports the EFI_SIMPLE_FILE_SYSTEM_PROTOCOL must materialize a file system protocol for that device to be bootable. If a device does not wish to support a complete file system it may produce an EFI_LOAD_FILE_PROTOCOL which allows it to materialize an image directly. The Boot Manager will attempt to boot using the EFI_SIMPLE_FILE_SYSTEM_PROTOCOL first. If that fails, then the EFI_LOAD_FILE_PROTOCOL will be used.

3.5.1 Boot via the Simple File Protocol

When booting via the EFI_SIMPLE_FILE_SYSTEM_PROTOCOL, the FilePath will start with a device path that points to the device that implements the EFI_SIMPLE_FILE_SYSTEM_PROTOCOL or the EFI_BLOCK_IO_PROTOCOL. The next part of the FilePath may point to the file name, including subdirectories, which contain the bootable image. If the file name is a null device path, the file name must be generated from the rules defined below.

If the FilePathList[0] device does not support the EFI_SIMPLE_FILE_SYSTEM_PROTOCOL, but supports the EFI_BLOCK_IO_PROTOCOL protocol, then the EFI Boot Service EFI_BOOT_SERVICES.ConnectController() must be called for FilePathList[0] with DriverImageHandle and RemainingDevicePath set to NULL and the Recursive flag is set to TRUE. The firmware will then attempt to boot from any child handles produced using the algorithms outlined below.

The format of the file system specified is contained in File System Format. While the firmware must produce an EFI_SIMPLE_FILE_SYSTEM_PROTOCOL that understands the UEFI file system, any file system can be abstracted with the EFI_SIMPLE_FILE_SYSTEM_PROTOCOL interface.
3.5.1.1 Removable Media Boot Behavior

To generate a file name when none is present in the FilePath, the firmware must append a default file name in the form `\EFIBOOTBOOT{machinetypeshort-name}.EFI` where machine type short-name defines a PE32+ image format architecture. Each file only contains one UEFI image type, and a system may support booting from one or more image types. *UEFI Image Types* lists the UEFI image types.

<table>
<thead>
<tr>
<th>PE Executable Machine Type</th>
<th>File Name Convention</th>
</tr>
</thead>
<tbody>
<tr>
<td>32-bit</td>
<td>BOOTIA32.EFI</td>
</tr>
<tr>
<td>x64</td>
<td>BOOTx64.EFI</td>
</tr>
<tr>
<td>Itanium architecture</td>
<td>BOOTIA64.EFI</td>
</tr>
<tr>
<td>AArch32 architecture</td>
<td>BOOTARM.EFI</td>
</tr>
<tr>
<td>AArch64 architecture</td>
<td>BOOTAA64.EFI</td>
</tr>
<tr>
<td>RISC-V 32-bit architecture</td>
<td>BOOTRISCV32.EFI</td>
</tr>
<tr>
<td>RISC-V 64-bit architecture</td>
<td>BOOTRISCV64.EFI</td>
</tr>
<tr>
<td>RISC-V 128-bit architecture</td>
<td>BOOTRISCV128.EFI</td>
</tr>
</tbody>
</table>

**Note:** The PE Executable machine type is contained in the machine field of the COFF file header as defined in the Microsoft PortableExecutable and Common Object File Format Specification, Revision 6.0

Media may support multiple architectures by simply having a `\EFIBOOTBOOT{machine type short-name}.EFI` file of each possible machine type.

3.5.2 Boot via the Load File Protocol

When booting via the *EFI_LOAD_FILE_PROTOCOL* protocol, the FilePath is a device path that points to a device that “speaks” the *EFI_LOAD_FILE_PROTOCOL*. The image is loaded directly from the device that supports the *EFI_LOAD_FILE_PROTOCOL*. The remainder of the FilePath will contain information that is specific to the device. Firmware passes this device-specific data to the loaded image, but does not use it to load the image. If the remainder of the FilePath is a null device path it is the loaded image’s responsibility to implement a policy to find the correct boot device.

The *EFI_LOAD_FILE_PROTOCOL* is used for devices that do not directly support file systems. Network devices commonly boot in this model where the image is materialized without the need of a file system.

3.5.2.1 Network Booting

Network booting is described by the *Preboot eXecution Environment (PXE) BIOS Support Specification*. PXE specifies UDP, DHCP, and TFTP network protocols that a booting platform can use to interact with an intelligent system load server. UEFI defines special interfaces that are used to implement PXE. These interfaces are contained in the *EFI_PXE_BASE_CODE_PROTOCOL*.
3.5.2.2 Future Boot Media

Since UEFI defines an abstraction between the platform and the OS and its loader it should be possible to add new types of boot media as technology evolves. The OS loader will not necessarily have to change to support new types of boot. The implementation of the UEFI platform services may change, but the interface will remain constant. The OS will require a driver to support the new type of boot media so that it can make the transition from UEFI boot services to OS control of the boot media.
This section describes the entry point to a UEFI image and the parameters that are passed to that entry point. There are three types of UEFI images that can be loaded and executed by firmware conforming to this specification. These are UEFI applications (UEFI Applications), UEFI boot service drivers (UEFI Drivers), and UEFI runtime drivers (UEFI Drivers). UEFI applications include UEFI OS loaders (UEFI OS Loaders). There are no differences in the entry point for these three image types.

4.1 UEFI Image Entry Point

The most significant parameter that is passed to an image is a pointer to the System Table (see definition immediately below), the main entry point for a UEFI Image. The System Table contains pointers to the active console devices, a pointer to the Boot Services Table, a pointer to the Runtime Services Table, and a pointer to the list of system configuration tables such as ACPI, SMBIOS, and the SAL System Table. This section describes the System Table in detail.

4.1.1 EFI_IMAGE_ENTRY_POINT

Summary

This is the main entry point for a UEFI Image. This entry point is the same for UEFI applications and UEFI drivers.

Prototype

```c
typedef EFI_STATUS
(EIFI_API *EFI_IMAGE_ENTRY_POINT) (  
    IN EFI_HANDLE ImageHandle,  
    IN EFI_SYSTEM_TABLE *SystemTable
);
```

Parameters

- **ImageHandle**
  The firmware allocated handle for the UEFI image.
- **SystemTable**
  A pointer to the EFI System Table.

Description

This function is the entry point to an EFI image. An EFI image is loaded and relocated in system memory by the EFI Boot Service `EFI_BOOT_SERVICES.LoadImage()`. An EFI image is invoked through the EFI Boot Service `EFI_BOOT_SERVICES.StartImage()`.

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Summary

This is the main entry point for a UEFI Image. This entry point is the same for UEFI applications and UEFI drivers.

 Prototype

```c
typedef EFI_STATUS
(EIFI_API *EFI_IMAGE_ENTRY_POINT) (  
    IN EFI_HANDLE ImageHandle,  
    IN EFI_SYSTEM_TABLE *SystemTable
);
```

Parameters

- **ImageHandle**
  The firmware allocated handle for the UEFI image.
- **SystemTable**
  A pointer to the EFI System Table.

Description

This function is the entry point to an EFI image. An EFI image is loaded and relocated in system memory by the EFI Boot Service `EFI_BOOT_SERVICES.LoadImage()`. An EFI image is invoked through the EFI Boot Service `EFI_BOOT_SERVICES.StartImage()`.
The first argument is the image’s image handle. The second argument is a pointer to the image’s system table. The system table contains the standard output and input handles, plus pointers to the EFI_BOOT_SERVICES and EFI_RUNTIME_SERVICES tables. The service tables contain the entry points in the firmware for accessing the core EFI system functionality. The handles in the system table are used to obtain basic access to the console. In addition, the System Table contains pointers to other standard tables that a loaded image may use if the associated pointers are initialized to nonzero values. Examples of such tables are ACPI, SMBIOS, SAL System Table, etc.

The ImageHandle is a firmware-allocated handle that is used to identify the image on various functions. The handle also supports one or more protocols that the image can use. All images support the EFI_LOADED_IMAGE_PROTOCOL and the EFI_LOADED_IMAGE_DEVICE_PATH_PROTOCOL that returns the source location of the image, the memory location of the image, the load options for the image, etc. The exact EFI_LOADED_IMAGE_PROTOCOL and EFI_LOADED_IMAGE_DEVICE_PATH_PROTOCOL structures are defined in EFI_LOADED_IMAGE_PROTOCOL.Unload().

If the UEFI image is a UEFI application that is not a UEFI OS loader, then the application executes and either returns or calls the EFI Boot Services EFI_BOOT_SERVICES.Exit(). A UEFI application is always unloaded from memory when it exits, and its return status is returned to the component that started the UEFI application.

If the UEFI image is a UEFI OS Loader, then the UEFI OS Loader executes and either returns, calls the EFI Boot Service Exit(), or calls the EFI Boot Service EFI_BOOT_SERVICES.ExitBootServices(). If the EFI OS Loader returns or calls Exit(), then the load of the OS has failed, and the EFI OS Loader is unloaded from memory and control is returned to the component that attempted to boot the UEFI OS Loader. If ExitBootServices() is called, then the UEFI OS Loader has taken control of the platform, and EFI will not regain control of the system until the platform is reset. One method of resetting the platform is through the EFI Runtime Service ResetSystem().

If the UEFI image is a UEFI Driver, then the UEFI driver executes and either returns or calls the Boot Service Exit(). If the UEFI driver returns an error, then the driver is unloaded from memory. If the UEFI driver returns EFI_SUCCESS, then it stays resident in memory. If the UEFI driver does not follow the UEFI Driver Model, then it performs any required initialization and installs its protocol services before returning. If the driver does follow the UEFI Driver Model, then the entry point is not allowed to touch any device hardware. Instead, the entry point is required to create and install the EFI Driver Binding Protocol (EFI Driver Binding Protocol) on the ImageHandle of the UEFI driver. If this process is completed, then EFI_SUCCESS is returned. If the resources are not available to complete the UEFI driver initialization, then EFI_OUT_OF_RESOURCES is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The driver was initialized.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

### 4.2 EFI Table Header

The data type EFI_TABLE_HEADER is the data structure that precedes all of the standard EFI table types. It includes a signature that is unique for each table type, a revision of the table that may be updated as extensions are added to the EFI table types, and a 32-bit CRC so a consumer of an EFI table type can validate the contents of the EFI table.
4.2.1 EFI_TABLE_HEADER

Summary
Data structure that precedes all of the standard EFI table types.

Related Definitions

typedef struct {
    UINT64   Signature;
    UINT32   Revision;
    UINT32   HeaderSize;
    UINT32   CRC32;
    UINT32   Reserved;
} EFI_TABLE_HEADER;

Parameters

Signature
A 64-bit signature that identifies the type of table that follows. Unique signatures have been generated for the
EFI System Table, the EFI Boot Services Table, and the EFI Runtime Services Table.

Revision
The revision of the EFI Specification to which this table conforms. The upper 16 bits of this field contain the
major revision value, and the lower 16 bits contain the minor revision value. The minor revision values are binary
coded decimals and are limited to the range of 00..99.

When printed or displayed UEFI spec revision is referred as (Major revision).(Minor revision upper decimal).(Minor revision lower decimal) or (Major revision).(Minor revision upper decimal) in case Minor revision lower decimal is set to 0. For example:

Specification with the revision value ((2<<16) | (30)) would be referred as 2.3;
A specification with the revision value ((2<<16) | (31)) would be referred as 2.3.1

HeaderSize
The size, in bytes, of the entire table including the FI_TABLE_HEADER.

CRC32
The 32-bit CRC for the entire table. This value is computed by setting this field to 0, and computing the 32-bit
CRC for HeaderSize bytes.

Reserved
Reserved field that must be set to 0.

NOTE: The capabilities found in the EFI system table, runtime table and boot services table may change over time.
The first field in each of these tables is an EFI_TABLE_HEADER. This header's Revision field is incremented when
new capabilities and functions are added to the functions in the table. When checking for capabilities, code should
verify that Revision is greater than or equal to the revision level of the table at the point when the capabilities were
added to the UEFI specification.

NOTE: Unless otherwise specified, UEFI uses a standard CCITT32 CRC algorithm with a seed polynomial value of
0x04c11db7 for its CRC calculations.

NOTE: The size of the system table, runtime services table, and boot services table may increase over time. It is very
important to always use the HeaderSize field of the EFI_TABLE_HEADER to determine the size of these tables.
4.3 EFI System Table

UEFI uses the EFI System Table, which contains pointers to the runtime and boot services tables. The definition for this table is shown in the following code fragments. Except for the table header, all elements in the service tables are pointers to functions as defined in Services — Boot Services and Services — Runtime Services. Prior to a call to EFI_BOOT_SERVICES.ExitBootServices(), all of the fields of the EFI System Table are valid. After an operating system has taken control of the platform with a call to ExitBootServices(), only the Hdr, FirmwareVendor, FirmwareRevision, RuntimeServices, NumberOfTableEntries, and ConfigurationTable fields are valid.

4.3.1 EFI_SYSTEM_TABLE

Summary

Contains pointers to the runtime and boot services tables.

Related Definitions

```
#define EFI_SYSTEM_TABLE_SIGNATURE 0x5453595320494249
#define EFI_2_90_SYSTEM_TABLE_REVISION ((2<<16) | (90))
#define EFI_2_80_SYSTEM_TABLE_REVISION ((2<<16) | (80))
#define EFI_2_70_SYSTEM_TABLE_REVISION ((2<<16) | (70))
#define EFI_2_60_SYSTEM_TABLE_REVISION ((2<<16) | (60))
#define EFI_2_50_SYSTEM_TABLE_REVISION ((2<<16) | (50))
#define EFI_2_40_SYSTEM_TABLE_REVISION ((2<<16) | (40))
#define EFI_2_31_SYSTEM_TABLE_REVISION ((2<<16) | (31))
#define EFI_2_30_SYSTEM_TABLE_REVISION ((2<<16) | (30))
#define EFI_2_20_SYSTEM_TABLE_REVISION ((2<<16) | (20))
#define EFI_2_10_SYSTEM_TABLE_REVISION ((2<<16) | (10))
#define EFI_2_00_SYSTEM_TABLE_REVISION ((2<<16) | (00))
#define EFI_1_10_SYSTEM_TABLE_REVISION ((1<<16) | (10))
#define EFI_1_02_SYSTEM_TABLE_REVISION ((1<<16) | (02))
#define EFI_SPECIFICATION_VERSION EFI_SYSTEM_TABLE_REVISION
#define EFI_SYSTEM_TABLE_REVISION EFI_2_90_SYSTEM_TABLE_REVISION

typedef struct {
    EFI_TABLE_HEADER Hdr;
    CHAR16 *FirmwareVendor;
    UINT32 FirmwareRevision;
    EFI_HANDLE ConsoleInHandle;
    EFI_SIMPLE_TEXT_INPUT_PROTOCOL *ConIn;
    EFI_HANDLE ConsoleOutHandle;
    EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *ConOut;
    EFI_HANDLE StandardErrorHandle;
    EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *StdErr;
    EFI_RUNTIME_SERVICES *RuntimeServices;
    EFI_BOOT_SERVICES *BootServices;
    UINTN NumberOfTableEntries;
    EFI_CONFIGURATION_TABLE *ConfigurationTable;
} EFI_SYSTEM_TABLE;
```

Parameters

Hdr

The table header for the EFI System Table. This header contains the EFI_SYSTEM_TABLE_SIGNATURE and
EFI_SYSTEM_TABLE_REVISION values along with the size of the EFI_SYSTEM_TABLE structure and a 32-bit CRC to verify that the contents of the EFI System Table are valid.

**FirmwareVendor**
A pointer to a null terminated string that identifies the vendor that produces the system firmware for the platform.

**FirmwareRevision**
A firmware vendor specific value that identifies the revision of the system firmware for the platform.

**ConsoleInHandle**
The handle for the active console input device. This handle must support EFI_SIMPLE_TEXT_INPUT_PROTOCOL and EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL. If there is no active console, these protocols must still be present.

**ConIn**
A pointer to the EFI_SIMPLE_TEXT_INPUT_PROTOCOL interface that is associated with ConsoleInHandle.

**ConsoleOutHandle**
The handle for the active console output device. This handle must support the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.

If there is no active console, this protocol must still be present.

**ConOut**
A pointer to the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL interface that is associated with ConsoleOutHandle.

**StandardErrorHandle**
The handle for the active standard error console device. This handle must support the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL. If there is no active console, this protocol must still be present.

**StdErr**
A pointer to the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL interface that is associated with StandardErrorHandle.

**RuntimeServices**
A pointer to the EFI Runtime Services Table.

**BootServices**
A pointer to the EFI Boot Services Table. See ref:efi-boot-services-table_efi_system_table.

**NumberOfTableEntries**
The number of system configuration tables in the buffer ConfigurationTable.

**ConfigurationTable**
A pointer to the system configuration tables. The number of entries in the table is NumberOfTableEntries.

### 4.4 EFI Boot Services Table

UEFI uses the EFI Boot Services Table, which contains a table header and pointers to all of the boot services. The definition for this table is shown in the following code fragments. Except for the table header, all elements in the EFI Boot Services Tables are prototypes of function pointers to functions as defined in Services — Boot Services. The function pointers in this table are not valid after the operating system has taken control of the platform with a call to EFI_BOOT_SERVICES.ExitBootServices().
4.4.1 EFI_BOOT_SERVICES

Summary
Contains a table header and pointers to all of the boot services.

Related Definitions

```c
#define EFI_BOOT_SERVICES_SIGNATURE 0x56524553544f4f42
#define EFI_BOOT_SERVICES_REVISION EFI_SPECIFICATION_VERSION

typedef struct {
    EFI_TABLE_HEADER Hdr;

    // Task Priority Services
    EFI_RAISE_TPL RaiseTPL; // EFI 1.0+
    EFI_RESTORE_TPL RestoreTPL; // EFI 1.0+

    // Memory Services
    EFI_ALLOCATE_PAGES AllocatePages; // EFI 1.0+
    EFI_FREE_PAGES FreePages; // EFI 1.0+
    EFI_GET_MEMORY_MAP GetMemoryMap; // EFI 1.0+
    EFI_ALLOCATE_POOL AllocatePool; // EFI 1.0+
    EFI_FREE_POOL FreePool; // EFI 1.0+

    // Event & Timer Services
    EFI_CREATE_EVENT CreateEvent; // EFI 1.0+
    EFI_SET_TIMER SetTimer; // EFI 1.0+
    EFI_WAIT_FOR_EVENT WaitForEvent; // EFI 1.0+
    EFI_SIGNAL_EVENT SignalEvent; // EFI 1.0+
    EFI_CLOSE_EVENT CloseEvent; // EFI 1.0+
    EFI_CHECK_EVENT CheckEvent; // EFI 1.0+

    // Protocol Handler Services
    EFI_INSTALL_PROTOCOL_INTERFACE InstallProtocolInterface; // EFI 1.0+
    EFI_REINSTALL_PROTOCOL_INTERFACE ReinstallProtocolInterface; // EFI 1.0+
    EFI_UNINSTALL_PROTOCOL_INTERFACE UninstallProtocolInterface; // EFI 1.0+
    EFI_HANDLE_PROTOCOL HandleProtocol; // EFI 1.0+
    VOID* Reserved; // EFI 1.0+
    EFI_REGISTER_PROTOCOL_NOTIFY RegisterProtocolNotify; // EFI 1.0+
    EFI_LOCATE_HANDLE LocateHandle; // EFI 1.0+
    EFI_LOCATE_DEVICE_PATH LocateDevicePath; // EFI 1.0+
    EFI_INSTALL_CONFIGURATION_TABLE InstallConfigurationTable; // EFI 1.0+

    // Image Services

} EFI_BOOT_SERVICES;
```

(continues on next page)
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(continued from previous page)

//
EFI_IMAGE_UNLOAD    LoadImage;   // EFI 1.0+
EFI_IMAGE_START     StartImage;  // EFI 1.0+
EFI_EXIT           Exit;        // EFI 1.0+
EFI_IMAGE_UNLOAD    UnloadImage; // EFI 1.0+
EFI_EXIT_BOOT_SERVICES ExitBootServices; // EFI 1.0+

//
// Miscellaneous Services
//
EFI_GET_NEXT_MONOTONIC_COUNT GetNextMonotonicCount; // EFI 1.0+
EFI_STALL          Stall;       // EFI 1.0+
EFI_SET_WATCHDOG_TIMER SetWatchdogTimer; // EFI 1.0+

//
// DriverSupport Services
//
EFI_CONNECT_CONTROLLER   ConnectController; // EFI 1.1
EFI_DISCONNECT_CONTROLLER DisconnectController; // EFI 1.1+

//
// Open and Close Protocol Services
//
EFI_OPEN_PROTOCOL     OpenProtocol;    // EFI 1.1+
EFI_CLOSE_PROTOCOL   CloseProtocol;    // EFI 1.1+
EFI_OPEN_PROTOCOL_INFORMATION OpenProtocolInformation; // EFI 1.1+

//
// Library Services
//
EFI_PROTOCOLS_PER_HANDLE ProtocolsPerHandle; // EFI 1.1+
EFI_LOCATE_HANDLE_BUFFER LocateHandleBuffer; // EFI 1.1+
EFI_LOCATE_PROTOCOL   LocateProtocol; // EFI 1.1+
EFI_UNINSTALL_MULTIPLE_PROTOCOL_INTERFACES InstallMultipleProtocolInterfaces; // EFI 1.1+
EFI_UNINSTALL_MULTIPLE_PROTOCOL_INTERFACES UninstallMultipleProtocolInterfaces; // EFI 1.1+

//
// 32-bit CRC Services
//
EFI_CALCULATE_CRC32   CalculateCrc32; // EFI 1.1+

//
// Miscellaneous Services
//
EFI_COPY_MEM         CopyMem;       // EFI 1.1+
EFI_SET_MEM          SetMem;        // EFI 1.1+
EFI_CREATE_EVENT_EX  CreateEventEx; // UEFI 2.0+
} EFI_BOOT_SERVICES;

Parameters

4.4. EFI Boot Services Table 93
The table header for the EFI Boot Services Table. This header contains the EFI_BOOT_SERVICES_SIGNATURE and EFI_BOOT_SERVICES_REVISION values along with the size of the EFI_BOOT_SERVICES structure and a 32-bit CRC to verify that the contents of the EFI Boot Services Table are valid.

RaiseTPL
  Raises the task priority level.

RestoreTPL
  Restores/lowers the task priority level.

AllocatePages
  Allocates pages of a particular type.

FreePages
  Frees allocated pages.

GetMemoryMap
  Returns the current boot services memory map and memory map key.

AllocatePool
  Allocates a pool of a particular type.

FreePool
  Frees allocated pool.

CreateEvent
  Creates a general-purpose event structure.

SetTimer
  Sets an event to be signaled at a particular time.

WaitForEvent
  Stops execution until an event is signaled.

SignalEvent
  Signals an event.

CloseEvent
  Closes and frees an event structure.

CheckEvent
  Checks whether an event is in the signaled state.

InstallProtocolInterface
  Installs a protocol interface on a device handle.

ReinstallProtocolInterface
  Reinstalls a protocol interface on a device handle.

UninstallProtocolInterface
  Removes a protocol interface from a device handle.

HandleProtocol
  Queries a handle to determine if it supports a specified protocol.

Reserved
  Reserved. Must be NULL.

RegisterProtocolNotify
  Registers an event that is to be signaled whenever an interface is installed for a specified protocol.
LocateHandle
   Returns an array of handles that support a specified protocol.

LocateDevicePath
   Locates all devices on a device path that support a specified protocol and returns the handle to the device that is
closest to the path.

InstallConfigurationTable
   Adds, updates, or removes a configuration table from the EFI System Table.

LoadImage
   Loads an EFI image into memory.

StartImage
   Transfers control to a loaded image’s entry point.

Exit
   Exits the image’s entry point.

UnloadImage
   Unloads an image.

ExitBootServices
   Terminates boot services.

GetNextMonotonicCount
   Returns a monotonically increasing count for the platform.

Stall
   Stalls the processor.

SetWatchdogTimer
   Resets and sets a watchdog timer used during boot services time.

ConnectController
   Uses a set of precedence rules to find the best set of drivers to manage a controller.

DisconnectController
   Informs a set of drivers to stop managing a controller.

OpenProtocol
   Adds elements to the list of agents consuming a protocol interface.

CloseProtocol
   Removes elements from the list of agents consuming a protocol interface.

OpenProtocolInformation
   Retrieve the list of agents that are currently consuming a protocol interface.

ProtocolsPerHandle
   Retrieves the list of protocols installed on a handle. The return buffer is automatically allocated.

LocateHandleBuffer
   Retrieves the list of handles from the handle database that meet the search criteria. The return buffer is automatically allocated.

LocateProtocol
   Finds the first handle in the handle database the supports the requested protocol.

InstallMultipleProtocolInterfaces
   Installs one or more protocol interfaces onto a handle.

UninstallMultipleProtocolInterfaces
   Uninstalls one or more protocol interfaces from a handle.
4.5 EFI Runtime Services Table

UEFI uses the EFI Runtime Services Table, which contains a table header and pointers to all of the runtime services. The definition for this table is shown in the following code fragments. Except for the table header, all elements in the EFI Runtime Services Tables are prototypes of function pointers to functions as defined in Services — Runtime Services. Unlike the EFI Boot Services Table, this table, and the function pointers it contains are valid after the UEFI OS loader and OS have taken control of the platform with a call to EFI_BOOT_SERVICES.ExitBootServices(). If a call to SetVirtualAddressMap() is made by the OS, then the function pointers in this table are fixed up to point to the new virtually mapped entry points.

4.5.1 EFI_RUNTIME_SERVICES

**Summary**

Contains a table header and pointers to all of the runtime services.

**Related Definitions**

```c
#define EFI_RUNTIME_SERVICES_SIGNATURE 0x56524553544e5552
#define EFI_RUNTIME_SERVICES_REVISION EFI_SPECIFICATION_VERSION
typedef struct {
    EFI_TABLE_HEADER Hdr;

    // // Time Services
    //
    EFI_GET_TIME    GetTime;
    EFI_SET_TIME    SetTime;
    EFI_GET_WAKEUP_TIME GetWakeupTime;
    EFI_SET_WAKEUP_TIME SetWakeupTime;

    // // Virtual Memory Services
    //
    EFI_SET_VIRTUAL_ADDRESS_MAP SetVirtualAddressMap;
    EFI_CONVERT_POINTER ConvertPointer;

    // // Variable Services
    //
    EFI_GET_VARIABLE GetVariable;
} EFI_RUNTIME_SERVICES;
```

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(continued from previous page)

```
EFI_GET_NEXT_VARIABLE_NAME    GetNextVariableName;
EFI_SET_VARIABLE              SetVariable;

// Miscellaneous Services
//
EFI_GET_NEXT_HIGH_MONO_COUNT  GetNextHighMonotonicCount;
EFI_RESET_SYSTEM              ResetSystem;

// UEFI 2.0 Capsule Services
//
EFI_UPDATE_CAPSULE            UpdateCapsule;
EFI_QUERY_CAPSULE_CAPABILITIES QueryCapsuleCapabilities;

// Miscellaneous UEFI 2.0 Service
//
EFI_QUERY_VARIABLE_INFO       QueryVariableInfo;
} EFI_RUNTIME_SERVICES;
```

**Parameters**

**Hdr**

The table header for the EFI Runtime Services Table. This header contains the EFI_RUNTIME_SERVICES_SIGNATURE and EFI_RUNTIME_SERVICES_REVISION values along with the size of the EFI_RUNTIME_SERVICES structure and a 32-bit CRC to verify that the contents of the EFI Runtime Services Table are valid.

**GetTime**

Returns the current time and date, and the time-keeping capabilities of the platform.

**SetTime**

Sets the current local time and date information.

**GetWakeupTime**

Returns the current wakeup alarm clock setting.

**SetWakeupTime**

Sets the system wakeup alarm clock time.

**SetVirtualAddressMap**

Used by a UEFI OS loader to convert from physical addressing to virtual addressing.

**ConvertPointer**

Used by EFI components to convert internal pointers when switching to virtual addressing.

**GetVariable**

Returns the value of a variable.

**GetNextVariableName**

Enumerates the current variable names.

**SetVariable**

Sets the value of a variable.

4.5. EFI Runtime Services Table 97
**GetNextHighMonotonicCount**
Returns the next high 32 bits of the platform’s monotonic counter.

**ResetSystem**
Resets the entire platform.

**UpdateCapsule**
Passed capsules to the firmware with both virtual and physical mapping.

**QueryCapsuleCapabilities**
Returns if the capsule can be supported via UpdateCapsule().

**QueryVariableInfo**
Returns information about the EFI variable store.

### 4.6 EFI Configuration Table & Properties Table

The EFI Configuration Table is the *ConfigurationTable* field in the EFI System Table. This table contains a set of GUID/pointer pairs. Each element of this table is described by the *EFI_CONFIGURATION_TABLE* structure below. The number of types of configuration tables is expected to grow over time. This is why a GUID is used to identify the configuration table type. The EFI Configuration Table may contain at most once instance of each table type.

#### 4.6.1 EFI_CONFIGURATION_TABLE

**Summary**
Contains a set of GUID/pointer pairs comprised of *ConfigurationTable* field in the EFI System Table.

**Related Definitions**

```c
typedef struct{
    EFI_GUID VendorGuid;
    VOID *VendorTable;
} EFI_CONFIGURATION_TABLE;
```

**Parameters**

**VendorGuid**
The 128-bit GUID value that uniquely identifies the system configuration table.

**VendorTable**
A pointer to the table associated with VendorGuid. Type of the memory that is used to store the table as well as whether this pointer is a physical address or a virtual address during runtime (whether or not a particular address reported in the table gets fixed up when a call to SetVirtualAddressMap() is made) is determined by the VendorGuid. Unless otherwise specified, memory type of the table buffer is defined by the guidelines set forth in the Calling Conventions section in Chapter 2. It is the responsibility of the specification defining the VendorTable to specify additional memory type requirements (if any) and whether to convert the addresses reported in the table. Any required address conversion is a responsibility of the driver that publishes corresponding configuration table.

A pointer to the table associated with VendorGuid. Whether this pointer is a physical address or a virtual address during runtime is determined by the VendorGuid. The VendorGuid associated with a given VendorTable pointer defines whether or not a particular address reported in the table gets fixed up when a call to *SetVirtualAddressMap()* is made. It is the responsibility of the specification defining the VendorTable to specify whether to convert the addresses reported in the table.
4.6.1.1 Industry Standard Configuration Tables

The following list shows the GUIDs for tables defined in some of the industry standards. These industry standards define tables accessed as UEFI Configuration Tables on UEFI-based systems. All the addresses reported in these table entries will be referenced as physical and will not be fixed up when transition from preboot to runtime phase. This list is not exhaustive and does not show GUIDs for all possible UEFI Configuration tables.

```c
#define EFI_ACPI_20_TABLE_GUID
  {0x8868e871,0xe4f1,0x11d3,
   {0xbc,0x22,0x00,0x80,0xc7,0x88,0x81}}

#define ACPI_TABLE_GUID
  {0xeb9d2d30,0x2d88,0x11d3,
   {0x9a,0x16,0x00,0x90,0x27,0x3f,0xc1,0x4d}}

#define SAL_SYSTEM_TABLE_GUID
  {0xeb9d2d32,0x2d88,0x11d3,
   {0x9a,0x16,0x00,0x90,0x27,0x3f,0xc1,0x4d}}

#define SMBIOS_TABLE_GUID
  {0xeb9d2d31,0x2d88,0x11d3,
   {0x9a,0x16,0x00,0x90,0x27,0x3f,0xc1,0x4d}}

#define SMBIOS3_TABLE_GUID
  {0xf2fd1544, 0x9794, 0x4a2c,
   {0x99,0x2e,0xe5,0xbb,0xcf,0x20,0xe3,0x94})

#define MPS_TABLE_GUID
  {0xeb9d2d3f,0x2d88,0x11d3,
   {0x9a,0x16,0x00,0x90,0x27,0x3f,0xc1,0x4d}}

LOSSAGE ACPI 2.0 or newer tables should use EFI_ACPI_TABLE_GUID

#define EFI_ACPI_TABLE_GUID
  {0x8868e871,0xe4f1,0x11d3,
   {0xbc,0x22,0x00,0x80,0xc7,0x88,0x81}}

#define EFI_ACPI_20_TABLE_GUID EFI_ACPI_TABLE_GUID

#define ACPI_TABLE_GUID
  {0xeb9d2d30,0x2d88,0x11d3,
   {0x9a,0x16,0x00,0x90,0x27,0x3f,0xc1,0x4d}}

#define ACPI_10_TABLE_GUID ACPI_TABLE_GUID
```

4.6. EFI Configuration Table & Properties Table
4.6.1.2 JSON Configuration Tables

The following list shows the GUIDs for tables defined for reporting firmware configuration data to EFI Configuration Tables and also for processing JSON payload capsule as defined in Section 23.5. The address reported in the table entry identified by EFI_JSON_CAPSULE_DATA_TABLE_GUID will be referenced as physical and will not be fixed up when transition from preboot to runtime phase. The addresses reported in these table entries identified by EFI_JSON_CONFIG_DATA_TABLE_GUID and EFI_JSON_CAPSULE_RESULT_TABLE_GUID will be referenced as virtual and will be fixed up when transition from preboot to runtime phase.

```c
#define EFI_JSON_CONFIG_DATA_TABLE_GUID
{0x87367f87, 0x1119, 0x41ce, 
{0xaa, 0xec, 0x8b, 0xe0, 0x11, 0x1f, 0x55, 0x8a }}
#define EFI_JSON_CAPSULE_DATA_TABLE_GUID
{0x35e7a725, 0x8dd2, 0x4cac, 
{ 0x80, 0x11, 0x33, 0xcd, 0xa8, 0x10, 0x90, 0x56 }}
#define EFI_JSON_CAPSULE_RESULT_TABLE_GUID
{0xdbc461c3, 0xb3de, 0x422a,
{b9, 0xb4, 0x98, 0x86, 0xfd, 0x49, 0xa1, 0xe5 }}
```

4.6.1.3 Devicetree Tables

The following list shows the GUIDs for the Devicetree table (DTB). For more information, see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the headings “Devicetree Specification”. The DTB must be contained in memory of type EfiACPIReclaimMemory. The address reported in this table entry will be referenced as physical and will not be fixed up when transition from preboot to runtime phase. Firmware must have the DTB resident in memory and installed in the EFI system table before executing any UEFI applications or drivers that are not part of the system firmware image. Once the DTB is installed as a configuration table, the system firmware must not make any modification to it or reference any data contained within the DTB.

UEFI applications are permitted to modify or replace the loaded DTB. System firmware must not depend on any data contained within the DTB. If system firmware makes use of a DTB for its own configuration, it should use a separate private copy that is not installed in the EFI System Table or otherwise be exposed to UEFI applications.

```c
// Devicetree table, in Flattened Devicetree Blob (DTB) format

#define EFI_DTB_TABLE_GUID
{0xb1b621d5, 0xf19c, 0x41a5, 
{83, 0x0b, 0xd9, 0x15, 0x2c, 0x69, 0xa9, 0xe0}}
```

4.6.2 EFI_RT_PROPERTIES_TABLE

This table should be published by a platform if it no longer supports all EFI runtime services once ExitBootServices() has been called by the OS. Note that this is merely a hint to the OS, which it is free to ignore, and so the platform is still required to provide callble implementations of unsupported runtime services that simply return EFI_UNSUPPORTED.

```c
#define EFI_RT_PROPERTIES_TABLE_GUID
\{ 0xeb66918a, 0x7eef, 0x402a, \}
\{ 0x84, 0x2e, 0x93, 0x1d, 0x21, 0xc3, 0x8a, 0xe9 \}
```

(continues on next page)
typedef struct {
    UINT16 Version;
    UINT16 Length;
    UINT32 RuntimeServicesSupported;
} EFI_RT_PROPERTIES_TABLE;

**Version**
Version of the table, must be 0x1

```c
#define EFI_RT_PROPERTIES_TABLE_VERSION 0x1
```

**Length**
Size in bytes of the entire EFI_RT_PROPERTIES_TABLE, must be 8.

**RuntimeServicesSupported**
Bitmask of which calls are or are not supported, where a bit set to 1 indicates that the call is supported, and 0 indicates that it is not.

```c
#define EFI_RT_SUPPORTED_GET_TIME 0x0001
#define EFI_RT_SUPPORTED_SET_TIME 0x0002
#define EFI_RT_SUPPORTED_GET_WAKEUP_TIME 0x0004
#define EFI_RT_SUPPORTED_SET_WAKEUP_TIME 0x0008
#define EFI_RT_SUPPORTED_GET_VARIABLE 0x0010
#define EFI_RT_SUPPORTED_GET_NEXT_VARIABLE_NAME 0x0020
#define EFI_RT_SUPPORTED_SET_VARIABLE 0x0040
#define EFI_RT_SUPPORTED_SET_VIRTUAL_ADDRESS_MAP 0x0080
#define EFI_RT_SUPPORTED_CONVERT_POINTER 0x0100
#define EFI_RT_SUPPORTED_GET_NEXT_HIGH_MONOTONIC_COUNT 0x0200
#define EFI_RT_SUPPORTED_RESET_SYSTEM 0x0400
#define EFI_RT_SUPPORTED_UPDATE_CAPSULE 0x0800
#define EFI_RT_SUPPORTED_QUERY_CAPSULE_CAPABILITIES 0x1000
#define EFI_RT_SUPPORTED_QUERY_VARIABLE_INFO 0x2000
```

The address reported in the EFI configuration table entry of this type will be referenced as physical and will not be fixed up when transitioning from preboot to runtime phase.

### 4.6.3 EFI_PROPERTIES_TABLE (deprecated)

**Note:** This table is deprecated and should no longer be used! It will be removed from future versions of the specification. EFI_MEMORY_ATTRIBUTES_TABLE described below provides alternative mechanism to implement runtime memory protection.

This table is published if the platform meets some of the construction requirements listed in the `MemoryProtectionAttributes`.

typedef struct {
    UINT32 Version;
    UINT32 Length;
    UINT64 MemoryProtectionAttribute;
} EFI_PROPERTIES_TABLE;
Version
This is revision of the table. Successive version may populate additional bits and growth the table length. In the case of the latter, the Length field will be adjusted appropriately.

```c
#define EFI_PROPERTIES_TABLE_VERSION 0x00010000
```

Length
This is the size of the entire EFI_PROPERTIES_TABLE structure, including the version. The initial version will be of length 16.

MemoryProtectionAttribute
This field is a bit mask. Any bits not defined shall be considered reserved. A set bit means that the underlying firmware has been constructed responsive to the given property.

```c
//
// Memory attribute (Not defined bits are reserved)
//
#define EFI_PROPERTIES_RUNTIME_MEMORY_PROTECTION_NON_EXECUTABLE_PE_DATA 0x1
\  
// BIT 0 - description - implies the runtime data is separated from the code
```

This bit implies that the UEFI runtime code and data sections of the executable image are separate and must be aligned as specified in Calling Conventions. This bit also implies that the data pages do not have any executable code.

It is recommended not to use this attribute, especially for implementations that broke the runtime code memory map descriptors into the underlying code and data sections within UEFI modules. This splitting causes interoperability issues with operating systems that invoke SetVirtualAddress() without realizing that there is a relationship between these runtime descriptors.

### 4.6.4 EFI_MEMORY_ATTRIBUTES_TABLE

**Summary**

When published by the system firmware, the EFI_MEMORY_ATTRIBUTES_TABLE provides additional information about regions within the run-time memory blocks defined in the EFI_MEMORY_DESCRIPTOR entries returned from EFI_BOOT_SERVICES.GetMemoryMap() function. The Memory Attributes Table is currently used to describe memory protections that may be applied to the UEFI Runtime code and data by an operating system or hypervisor. Consumers of this table must currently ignore entries containing any values for Type except for EfiRuntimeServicesData and EfiRuntimeServicesCode to ensure compatibility with future uses of this table. The Memory Attributes Table may define multiple entries to describe sub-regions that comprise a single entry returned by GetMemoryMap() however the sub-regions must total to completely describe the larger region and may not cross boundaries between entries reported by GetMemoryMap(). If a run-time region returned in GetMemoryMap() entry is not described within the Memory Attributes Table, this region is assumed to not be compatible with any memory protections.

Only entire EFI_MEMORY_DESCRIPTOR entries as returned by GetMemoryMap() may be passed to SetVirtualAddressMap().

The address reported in the EFI configuration table entry of this type will be referenced as physical and will not be fixed up when transition from preboot to runtime phase.

**Prototype**

```c
#define EFI_MEMORY_ATTRIBUTES_TABLE_GUID \
{0xdcfa911d, 0x26eb, 0x469f, \ 
  {0xa2, 0x20, 0x38, 0xb7, 0xdc, 0x46, 0x12, 0x20}}
```

With the following data structure
typedef struct {
    UINT32 Version ;
    UINT32 NumberOfEntries ;
    UINT32 DescriptorSize ;
    UINT32 Reserved ;
    // EFI_MEMORY_DESCRIPTOR Entry [1] ;
} EFI_MEMORY_ATTRIBUTES_TABLE;

Version
The version of this table. Present version is 0x00000001

NumberOfEntries
Count of EFI_MEMORY_DESCRIPTOR entries provided. This is typically the total number of PE/COFF sections within all UEFI modules that comprise the UEFI Runtime and all UEFI Data regions (e.g. runtime heap).

Entry
Array of Entries of type EFI_MEMORY_DESCRIPTOR.

DescriptorSize
Size of the memory descriptor.

Reserved
Reserved bytes.

Description
For each array entry, the EFI_MEMORY_DESCRIPTOR . Attribute field can inform a runtime agency, such as operating system or hypervisor, as to what class of protection settings can be made in the memory management unit for the memory defined by this entry. The only valid bits for Attribute field currently are EFI_MEMORY_RO , EFI_MEMORY_XP , plus EFI_MEMORY_RUNTIME . Irrespective of the memory protections implied by Attribute , the EFI_MEMORY_DESCRIPTOR . Type field should match the type of the memory in enclosing SetMemoryMap() entry. PhysicalStart must be aligned as specified in Calling Conventions . The list must be sorted by physical start address in ascending order. VirtualStart field must be zero and ignored by the OS since it has no purpose for this table. NumPages must cover the entire memory region for the protection mapping. Each Descriptor in the EFI_MEMORY_ATTRIBUTES_TABLE with attribute EFI_MEMORY_RUNTIME must not overlap any other Descriptor in the EFI_MEMORY_ATTRIBUTES_TABLE with attribute EFI_MEMORY_RUNTIME . Additionally, every memory region described by a Descriptor in EFI_MEMORY_ATTRIBUTES_TABLE must be a sub-region of, or equal to, a descriptor in the table produced by GetMemoryMap().

Table 4.1: Usage of Memory Attribute Definitions

<table>
<thead>
<tr>
<th></th>
<th>EFI_MEMORY_RO</th>
<th>EFI_MEMORY_XP</th>
<th>EFI_MEMORY_RUNTIME</th>
</tr>
</thead>
<tbody>
<tr>
<td>No memory access protection is possible for Entry</td>
<td>0</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>Write-protected Code</td>
<td>1</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>Read/Write Data</td>
<td>0</td>
<td>1</td>
<td>1</td>
</tr>
<tr>
<td>Read-only Data</td>
<td>1</td>
<td>1</td>
<td>1</td>
</tr>
</tbody>
</table>

Other Configuration Tables
The following list shows additional configuration tables defined in this specification:

- EFI_MEMORY_RANGE_CAPSULE_GUID
• EFI_DEBUG_IMAGE_INFO_TABLE (Section 18.4.3)
• EFI_SYSTEM_RESOURCE_TABLE (Section 23.4)
• EFI_IMAGE_EXECUTION_INFO_TABLE (Section 32.5.3.1)
• User Information Table (Section 36.5)
• HII Database export buffer (Section 33.2.11.1, OS Runtime Utilization)

4.7 Image Entry Point Examples

The examples in the following sections show how the various table examples are presented in the UEFI environment.

4.7.1 Image Entry Point Examples

The following example shows the image entry point for a UEFI Application. This application makes use of the EFI System Table, the EFI Boot Services Table, and the EFI Runtime Services Table.

```c
#include <stdio.h>

EFI_SYSTEM_TABLE *gST;
EFI_BOOT_SERVICES *gBS;
EFI_RUNTIME_SERVICES *gRT;

EfiApplicationEntryPoint(
    IN EFI_HANDLE ImageHandle,
    IN EFI_SYSTEM_TABLE *SystemTable
) {

    EFI_STATUS Status;
    EFI_TIME *Time;

    gST = SystemTable;
    gBS = gST->BootServices;
    gRT = gST->RuntimeServices;

    // Use EFI System Table to print "Hello World" to the active console output
    // device.
    Status = gST->ConOut->OutputString (gST->ConOut, L"Hello world\n\r");
    if (EFI_ERROR(Status)) {
        return Status;
    }

    // Use EFI Boot Services Table to allocate a buffer to store the current time
    // and date.
    Status = gBS->AllocatePool (EfiBootServicesData, sizeof (EFI_TIME), (VOID **) &Time
```

(continues on next page)
if (EFI_ERROR (Status)) {
    return Status;
}

// Use the EFI Runtime Services Table to get the current time and date.
// Status = gRT->GetTime (Time, NULL)
if (EFI_ERROR (Status)) {
    return Status;
}

return Status;

The following example shows the UEFI image entry point for a driver that does not follow the UEFI Driver Model. Since this driver returns EFI_SUCCESS, it will stay resident in memory after it exits.

```c
EfiDriverEntryPoint(
    IN EFI_HANDLE ImageHandle,
    IN EFI_SYSTEM_TABLE *SystemTable
) {
    gST = SystemTable;
    gBS = gST->BootServices;
    gRT = gST->RuntimeServices;

    // Implement driver initialization here.

    return EFI_SUCCESS;
}
```

The following example shows the UEFI image entry point for a driver that also does not follow the UEFI Driver Model. Since this driver returns EFI_DEVICE_ERROR, it will not stay resident in memory after it exits.

```c
EfiDriverEntryPoint(
    IN EFI_HANDLE ImageHandle,
    IN EFI_SYSTEM_TABLE *SystemTable
) {
    gST = SystemTable;
    gBS = gST->BootServices;
    gRT = gST->RuntimeServices;

    // Implement driver initialization here.

    return EFI_SUCCESS;
}
```
4.7.2 UEFI Driver Model Example

The following is an UEFI Driver Model example that shows the driver initialization routine for the ABC device controller that is on the XYZ bus. The EFI_DRIVER_BINDING_PROTOCOL and the function prototypes for AbcSupported(), AbcStart(), and AbcStop() are defined in EFI Driver Binding Protocol. This function saves the driver's image handle and a pointer to the EFI boot services table in global variables, so the other functions in the same driver can have access to these values. It then creates an instance of the EFI_DRIVER_BINDING_PROTOCOL and installs it onto the driver's image handle.

```c
extern EFI_GUID gEfiLoadedImageProtocolGuid;
extern EFI_GUID gEfiDriverBindingProtocolGuid;
EFI_BOOT_SERVICES *gBS;
static EFI_DRIVER_BINDING_PROTOCOL mAbcDriverBinding = {
  AbcSupported,
  AbcStart,
  AbcStop,
  1,
  NULL,
  NULL
};

AbcEntryPoint(
  IN EFI_HANDLE ImageHandle,
  IN EFI_SYSTEM_TABLE *SystemTable
)
{
  EFI_STATUS Status;

  gBS = SystemTable->BootServices;

  mAbcDriverBinding->ImageHandle = ImageHandle;
  mAbcDriverBinding->DriverBindingHandle = ImageHandle;

  Status = gBS->InstallMultipleProtocolInterfaces(
    &mAbcDriverBinding->DriverBindingHandle,
    &gEfiDriverBindingProtocolGuid, &mAbcDriverBinding,
    NULL
  );
}
```
4.7.3 UEFI Driver Model Example (Unloadable)

The following is the same UEFI Driver Model example as above, except it also includes the code required to allow
the driver to be unloaded through the boot service Unload() EDF_LOADED_IMAGE_PROTOCOL.Unload() . Any
protocols installed or memory allocated in AbcEntryPoint() must be uninstalled or freed in the AbcUnload().

```c
extern EFI_GUID gEfiLoadedImageProtocolGuid;
extern EFI_GUID gEfiDriverBindingProtocolGuid;
EFI_BOOT_SERVICES *gBS;
static EFI_DRIVER_BINDING_PROTOCOL mAbcDriverBinding = {
    AbcSupported,
    AbcStart,
    AbcStop,
    1,
    NULL,
    NULL
};

EFI_STATUS
AbcUnload (IN EFI_HANDLE ImageHandle);
AbcEntryPoint(
    IN EFI_HANDLE ImageHandle,
    IN EFI_SYSTEM_TABLE *SystemTable
)
{
    EFI_STATUS Status;
    EFI_LOADED_IMAGE_PROTOCOL *LoadedImage;

    gBS = SystemTable->BootServices;
    Status = gBS->OpenProtocol (    // Use OpenProtocol
        ImageHandle,           // ImageHandle
        &gEfiLoadedImageProtocolGuid,
        &LoadedImage,          // &LoadedImage
        ImageHandle,           // ImageHandle
        NULL,                 // NULL
        EFI_OPEN_PROTOCOL_GET_PROTOCOL
    );
    if (EFI_ERROR (Status)) {
        return Status;
    }
    LoadedImage->Unload = AbcUnload;

    mAbcDriverBinding->ImageHandle = ImageHandle;
    mAbcDriverBinding->DriverBindingHandle = ImageHandle;
```

(continues on next page)
Status = gBS->InstallMultipleProtocolInterfaces(
    &mAbcDriverBinding->DriverBindingHandle,
    &gEfiDriverBindingProtocolGuid, &mAbcDriverBinding,
    NULL);

    return Status;
}

EFI_STATUS Status
AbcUnload (IN EFI_HANDLE ImageHandle)
{
    EFI_STATUS Status;

    Status = gBS->UninstallMultipleProtocolInterfaces (
        ImageHandle,
        &gEfiDriverBindingProtocolGuid, &mAbcDriverBinding,
        NULL);
    return Status;
}

4.7.4 EFI Driver Model Example (Multiple Instances)

The following is the same as the first UEFI Driver Model example, except it produces three EFI Driver Binding Protocol instances. The first one is installed onto the driver’s image handle. The other two are installed onto newly created handles.

extern EFI_GUID gEfiDriverBindingProtocolGuid;
EFI_BOOT_SERVICES *gBS;

static EFI_DRIVER_BINDING_PROTOCOL mAbcDriverBindingA = {
    AbcSupportedA,
    AbcStartA,
    AbcStopA,
    1,
    NULL,
    NULL
};

static EFI_DRIVER_BINDING_PROTOCOL mAbcDriverBindingB = {
    AbcSupportedB,
    AbcStartB,
    AbcStopB,
    1,
    NULL,
    NULL
};
static EFI_DRIVER_BINDING_PROTOCOL mAbcDriverBindingC = {
    AbcSupportedC,
    AbcStartC,
    AbcStopC,
    1,
    NULL,
    NULL
};

AbcEntryPoint(
    IN EFI_HANDLE ImageHandle,
    IN EFI_SYSTEM_TABLE *SystemTable
)
{
    EFI_STATUS Status;
    gBS = SystemTable->BootServices;

    // Install mAbcDriverBindingA onto ImageHandle
    mAbcDriverBindingA->ImageHandle = ImageHandle;
    mAbcDriverBindingA->DriverBindingHandle = ImageHandle;
    Status = gBS->InstallMultipleProtocolInterfaces(
        &mAbcDriverBindingA->DriverBindingHandle,
        &gEfiDriverBindingProtocolGuid, &mAbcDriverBindingA,
        NULL
    );
    if (EFI_ERROR (Status)) {
        return Status;
    }

    // Install mAbcDriverBindingB onto a newly created handle
    mAbcDriverBindingB->ImageHandle = ImageHandle;
    mAbcDriverBindingB->DriverBindingHandle = NULL;
    Status = gBS->InstallMultipleProtocolInterfaces(
        &mAbcDriverBindingB->DriverBindingHandle,
        &gEfiDriverBindingProtocolGuid, &mAbcDriverBindingB,
        NULL
    );
    if (EFI_ERROR (Status)) {
        return Status;
    }

    //
    (continues on next page)
// Install mAbcDriverBindingC onto a newly created handle
//
mAbcDriverBindingC->ImageHandle = ImageHandle;
mAbcDriverBindingC->DriverBindingHandle = NULL;

Status = gBS->InstallMultipleProtocolInterfaces(
    &mAbcDriverBindingC->DriverBindingHandle,
    &gEfiDriverBindingProtocolGuid, &mAbcDriverBindingC,
    NULL
);

return Status;
}
5.1 GPT and MBR disk layout comparison

This specification defines the GUID Partition table (GPT) disk layout (i.e., partitioning scheme). The following list outlines the advantages of using the GPT disk layout over the legacy Master Boot Record (MBR) disk layout:

- Logical Block Addresses (LBAs) are 64 bits (rather than 32 bits).
- Supports many partitions (rather than just four primary partitions).
- Provides both a primary and backup partition table for redundancy.
- Uses version number and size fields for future expansion.
- Uses CRC32 fields for improved data integrity.
- Defines a GUID for uniquely identifying each partition.
- Uses a GUID and attributes to define partition content type.
- Each partition contains a 36 character human readable name.

5.2 LBA 0 Format

LBA 0 (i.e., the first logical block) of the hard disk contains either

- a legacy Master Boot Record (MBR) (See Legacy Master Boot Record (MBR))
- or a protective MBR (See Protective MBR).

5.2.1 Legacy Master Boot Record (MBR)

A legacy MBR may be located at LBA 0 (i.e., the first logical block) of the disk if it is not using the GPT disk layout (i.e., if it is using the MBR disk layout). The boot code on the MBR is not executed by UEFI firmware.

Table 5.1: Legacy MBR

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BootCode</td>
<td>0</td>
<td>424</td>
<td>x86 code used on a non-UEFI system to select an MBR partition record and load the first logical block of that partition. This code shall not be executed on UEFI systems.</td>
</tr>
</tbody>
</table>

continues on next page
Table 5.1 – continued from previous page

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>UniqueMB DiskSig-nature</td>
<td>440</td>
<td>4</td>
<td>Unique Disk Signature This may be used by the OS to identify the disk from other disks in the system. This value is always written by the OS and is never written by EFI firmware.</td>
</tr>
<tr>
<td>Unknown</td>
<td>444</td>
<td>2</td>
<td>Unknown. This field shall not be used by UEFI firmware.</td>
</tr>
<tr>
<td>PartitionRecord</td>
<td>446</td>
<td>16*4</td>
<td>Array of four legacy MBR partition records (See Legacy MBR Partition Record).</td>
</tr>
<tr>
<td>Signature</td>
<td>510</td>
<td>2</td>
<td>Set to 0xAA55 (i.e., byte 510 contains 0x55 and byte 511 contains 0xAA).</td>
</tr>
<tr>
<td>Reserved</td>
<td>512</td>
<td>Logical BlockSize - 512</td>
<td>The rest of the logical block, if any, is reserved.</td>
</tr>
</tbody>
</table>

The MBR contains four partition records (see Table 11) that each define the beginning and ending LBAs that a partition consumes on a disk.

Table 5.2: Legacy MBR Partition Record

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BootIndicator</td>
<td>0</td>
<td>1</td>
<td>0x80 indicates that this is the bootable legacy partition. Other values indicate that this is not a bootable legacy partition. This field shall not be used by UEFI firmware.</td>
</tr>
<tr>
<td>StartingCHS</td>
<td>1</td>
<td>3</td>
<td>Start of partition in CHS address format. This field shall not be used by UEFI firmware.</td>
</tr>
<tr>
<td>OSType</td>
<td>4</td>
<td>1</td>
<td>Type of partition. See See OS Types.</td>
</tr>
<tr>
<td>EndingCHS</td>
<td>5</td>
<td>3</td>
<td>End of partition in CHS address format. This field shall not be used by UEFI firmware.</td>
</tr>
<tr>
<td>StartingLBA</td>
<td>8</td>
<td>4</td>
<td>Starting LBA of the partition on the disk. This field is used by UEFI firmware to determine the start of the partition.</td>
</tr>
<tr>
<td>SizeInLBA</td>
<td>12</td>
<td>4</td>
<td>Size of the partition in LBA units of logical blocks. This field is used by UEFI firmware to determine the size of the partition.</td>
</tr>
</tbody>
</table>

If an MBR partition has an OSType field of 0xEF (i.e., UEFI System Partition), then the firmware must add the UEFI System Partition GUID to the handle for the MBR partition using InstallProtocolInterface() . This allows drivers and applications, including OS loaders, to easily search for handles that represent UEFI System Partitions.

The following test must be performed to determine if a legacy MBR is valid:

- The Signature must be 0xa55
- A Partition Record that contains an OSType value of zero or a SizeInLBA value of zero may be ignored.

Otherwise:

- The partition defined by each MBR Partition Record must physically reside on the disk (i.e., not exceed the capacity of the disk).
- Each partition must not overlap with other partitions.

Figure 5.1 (below) shows an example of an MBR disk layout with four partitions.

Related Definitions
#pragma pack(1)
///
/// MBR Partition Entry
///
typedef struct {
    UINT8 BootIndicator;
    UINT8 StartHead;
    UINT8 StartSector;
    UINT8 StartTrack;
    UINT8 OSIndicator;
    UINT8 EndHead;
    UINT8 EndSector;
    UINT8 EndTrack;
    UINT8 StartingLBA[4];
    UINT8 SizeInLBA[4];
} MBR_PARTITION_RECORD;

///
/// MBR Partition Table
///
typedef struct {
    UINT8 BootStrapCode[440];
    UINT8 UniqueMbrSignature[4];
    UINT8 Unknown[2];
    MBR_PARTITION_RECORD Partition[4];
    UINT16 Signature;
} MASTER_BOOT_RECORD;

#pragma pack()
5.2.2 OS Types

Unique types defined by this specification (other values are not defined by this specification):

- 0xEF (i.e., UEFI System Partition) defines a UEFI system partition.
- 0xEE (i.e., GPT Protective) is used by a protective MBR (see 5.2.2) to define a fake partition covering the entire disk.

Other values are used by legacy operating systems, and are allocated independently of the UEFI specification.

NOTE: “Partition types” by Andries Brouwer: See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “OS Type values used in the MBR disk layout”.

5.2.3 Protective MBR

For a bootable disk, a Protective MBR must be located at LBA 0 (i.e., the first logical block) of the disk if it is using the GPT disk layout. The Protective MBR precedes the GUID Partition Table Header to maintain compatibility with existing tools that do not understand GPT partition structures.

Table 5.3: Protective MBR

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>Boot Code</td>
<td>0</td>
<td>440</td>
<td>Unused by UEFI systems.</td>
</tr>
<tr>
<td>Unique MBR Disk Signature</td>
<td>440</td>
<td>4</td>
<td>Unused. Set to zero.</td>
</tr>
<tr>
<td>Unknown</td>
<td>444</td>
<td>2</td>
<td>Unused. Set to zero.</td>
</tr>
<tr>
<td>Partition Record</td>
<td>446</td>
<td>16*4</td>
<td>Array of four MBR partition records. Contains:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• one partition record as defined See Table (below); and</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• three partition records each set to zero.</td>
</tr>
<tr>
<td>Signature</td>
<td>510</td>
<td>2</td>
<td>Set to 0xAA55 (i.e., byte 510 contains 0x55 and byte 511 contains 0xAA).</td>
</tr>
<tr>
<td>Reserved</td>
<td>512</td>
<td>Logical Block Size - 512</td>
<td>The rest of the logical block, if any, is reserved. Set to zero.</td>
</tr>
</tbody>
</table>

One of the Partition Records shall be as defined in table 12, reserving the entire space on the disk after the Protective MBR itself for the GPT disk layout.

Table 5.4: Protective MBR Partition Record protecting the entire disk*

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>BootIndicator</td>
<td>0</td>
<td>1</td>
<td>Set to 0x00 to indicate a non-bootable partition. If set to any value other than 0x00 the behavior of this flag on non-UEFI systems is undefined. Must be ignored by UEFI implementations.</td>
</tr>
<tr>
<td>StartingCHS</td>
<td>1</td>
<td>3</td>
<td>Set to 0x000200, corresponding to the Starting LBA field.</td>
</tr>
<tr>
<td>OSType</td>
<td>4</td>
<td>1</td>
<td>Set to 0xEE (i.e., GPT Protective)</td>
</tr>
<tr>
<td>EndingCHS</td>
<td>5</td>
<td>3</td>
<td>Set to the CHS address of the last logical block on the disk. Set to 0xFFFFFFF if it is not possible to represent the value in this field.</td>
</tr>
</tbody>
</table>

continues on next page
Table 5.4 – continued from previous page

<table>
<thead>
<tr>
<th>StartingLBA</th>
<th>8</th>
<th>4</th>
<th>Set to 0x00000001 (i.e., the LBA of the GPT Partition Header).</th>
</tr>
</thead>
<tbody>
<tr>
<td>SizeInLBA</td>
<td>12</td>
<td>4</td>
<td>Set to the size of the disk minus one. Set to 0xFFFFFFFF if the size of the disk is too large to be represented in this field.</td>
</tr>
</tbody>
</table>

The remaining Partition Records shall each be set to zeros.

Figure 5.2 (below) shows an example of a GPT disk layout with four partitions with a protective MBR.

![Fig. 5.2: GPT disk layout with protective MBR](image)

Figure 5.3 (below) shows an example of a GPT disk layout with four partitions with a protective MBR, where the disk capacity exceeds LBA 0xFFFFFFFF.

![Fig. 5.3: GPT disk layout with protective MBR on a disk with capacity > LBA 0xFFFFFFFF](image)
5.2.4 Partition Information

Install an EFI_PARTITION_INFO protocol on each of the device handles that logical EFI_BLOCK_IO_PROTOTOLs are installed.

5.3 GUID Partition Table (GPT) Disk Layout

5.3.1 GPT overview

The GPT partitioning scheme is depicted in the Figure GUID Partition Table (GPT) example. The GPT Header (GPT Header) includes a signature and a revision number that specifies the format of the data bytes in the partition header. The GUID Partition Table Header contains a header size field that is used in calculating the CRC32 that confirms the integrity of the GPT Header. While the GPT Header’s size may increase in the future it cannot span more than one logical block on the device.

LBA 0 (i.e., the first logical block) contains a protective MBR (See Protective MBR).

Two GPT Header structures are stored on the device: the primary and the backup. The primary GPT Header must be located in LBA 1 (i.e., the second logical block), and the backup GPT Header must be located in the last LBA of the device. Within the GPT Header the My LBA field contains the LBA of the GPT Header itself, and the Alternate LBA field contains the LBA of the other GPT Header. For example, the primary GPT Header’s My LBA value would be 1 and its Alternate LBA would be the value for the last LBA of the device. The backup GPT Header’s fields would be reversed.

The GPT Header defines the range of LBAs that are usable by GPT Partition Entries. This range is defined to be inclusive of First Usable LBA through Last Usable LBA on the logical device. All data stored on the volume must be stored between the First Usable LBA through Last Usable LBA, and only the data structures defined by UEFI to manage partitions may reside outside of the usable space. The value of Disk GUID is a GUID that uniquely identifies the entire GPT Header and all its associated storage. This value can be used to uniquely identify the disk. The start of the GPT Partition Entry Array is located at the LBA indicated by the Partition Entry LBA field. The size of a GUID Partition Entry element is defined in the Size Of Partition Entry field. There is a 32-bit CRC of the GPT Partition Entry Array that is stored in the GPT Header in Partition Entry Array CRC32 field. The size of the GPT Partition Entry Array is Size Of Partition Entry multiplied by Number Of Partition Entries. If the size of the GUID Partition Entry Array is not an even multiple of the logical block size, then any space left over in the last logical block is Reserved and not covered by the Partition Entry Array CRC32 field. When a GUID Partition Entry is updated, the Partition Entry Array CRC32 must be updated. When the Partition Entry Array CRC32 is updated, the GPT Header CRC must also be updated, since the Partition Entry Array CRC32 is stored in the GPT Header.

The primary GPT Partition Entry Array must be located after the primary GPT Header and end before the First Usable LBA. The backup GPT Partition Entry Array must be located after the Last Usable LBA and end before the backup GPT Header.

Therefore the primary and backup GPT Partition Entry Arrays are stored in separate locations on the disk. Each GPT Partition Entry defines a partition that is contained in a range that is within the usable space declared by the GPT Header. Zero or more GPT Partition Entries may be in use in the GPT Partition Entry Array. Each defined partition must not overlap with any other defined partition. If all the fields of a GUID Partition Entry are zero, the entry is not in use. A minimum of 16,384 bytes of space must be reserved for the GPT Partition Entry Array.

If the block size is 512, the First Usable LBA must be greater than or equal to 34 (allowing 1 block for the Protective MBR, 1 block for the Partition Table Header, and 32 blocks for the GPT Partition Entry Array); if the logical block size is 4096, the First Useable LBA must be greater than or equal to 6 (allowing 1 block for the Protective MBR, 1 block for the GPT Header, and 4 blocks for the GPT Partition Entry Array).

The device may present a logical block size that is not 512 bytes long. In ATA, this is called the Long Logical Sector feature set; an ATA device reports support for this feature set in IDENTIFY DEVICE data word 106 bit 12 and reports
Fig. 5.4: GUID Partition Table (GPT) example

the number of words (i.e., 2 bytes) per logical sector in IDENTIFY DEVICE data words 117-118 (see ATA8-ACS). A SCSI device reports its logical block size in the READ CAPACITY parameter data Block Length In Bytes field (see SBC-3).

The device may present a logical block size that is smaller than the physical block size (e.g., present a logical block size of 512 bytes but implement a physical block size of 4,096 bytes). In ATA, this is called the Long Physical Sector feature set; an ATA device reports support for this feature set in IDENTIFY DEVICE data word 106 bit 13 and reports the Physical Sector Size/Logical Sector Size exponential ratio in IDENTIFY DEVICE data word 106 bits 3-0 (See ATA8-ACS). A SCSI device reports its logical block size/physical block exponential ratio in the READ CAPACITY (16) parameter data Logical Blocks Per Physical Block Exponent field (see SBC-3). These fields return $2^n$ logical sectors per physical sector (e.g., 3 means $2^3 = 8$ logical sectors per physical sector).

A device implementing long physical blocks may present logical blocks that are not aligned to the underlying physical block boundaries. An ATA device reports the alignment of logical blocks within a physical block in IDENTIFY DEVICE data word 209 (see ATA8-ACS). A SCSI device reports its alignment in the READ CAPACITY (16) parameter data Lowest Aligned Logical Block Address field (see SBC-3). Note that the ATA and SCSI fields are defined differently (e.g., to make LBA 63 aligned, ATA returns a value of 1 while SCSI returns a value of 7).

In SCSI devices, the Block Limits VPD page Optimal Transfer Length Granularity field (see SBC-3) may also report a granularity that is important for alignment purposes (e.g., RAID controllers may return their RAID stripe depth in that field).

GPT partitions should be aligned to the larger of:

a – The physical block boundary, if any

b – The optimal transfer length granularity, if any.

For example

a – If the logical block size is 512 bytes, the physical block size is 4,096 bytes (i.e., 512 bytes x 8 logical blocks), there is no optimal transfer length granularity, and logical block 0 is aligned to a physical block boundary, then each GPT partition should start at an LBA that is a multiple of 8.
b – If the logical block size is 512 bytes, the physical block size is 8,192 bytes (i.e., 512 bytes x 16 logical blocks), the optimal transfer length granularity is 65,536 bytes (i.e., 512 bytes x 128 logical blocks), and logical block 0 is aligned to a physical block boundary, then each GPT partition should start at an LBA that is a multiple of 128.

To avoid the need to determine the physical block size and the optimal transfer length granularity, software may align GPT partitions at significantly larger boundaries. For example, assuming logical block 0 is aligned, it may use LBAs that are multiples of 2,048 to align to 1,048,576 byte (1 MiB) boundaries, which supports most common physical block sizes and RAID stripe sizes.

References are as follows:
ISO/IEC 24739-200 [ANSI INCITS 452-2008] AT Attachment 8 - ATA/ATAPI Command Set (ATA8-ACS). By the INCITS T13 technical committee. (See “Links to UEFI-Related Documents” (http://uefi.org/uefi under the headings “InterNational Committee on Information Technology Standards (INCITS)” and “INCITS T13 technical committee”).

5.3.2 GPT Header

See Table (below) which defines the GPT Header.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Signature</td>
<td>0</td>
<td>8</td>
<td>Identifies EFI-compatible partition table header. This value must contain the ASCII string “EFI PART”, encoded as the 64-bit constant 0x54 52415020494645.</td>
</tr>
<tr>
<td>Revision</td>
<td>8</td>
<td>4</td>
<td>The revision number for this header. This revision value is not related to the UEFI Specification version. This header is version 1.0, so the correct value is 0x00010000.</td>
</tr>
<tr>
<td>HeaderSize</td>
<td>12</td>
<td>4</td>
<td>Size in bytes of the GPT Header. The HeaderSize must be greater than or equal to 92 and must be less than or equal to the logical block size.</td>
</tr>
<tr>
<td>HeaderCRC32</td>
<td>16</td>
<td>4</td>
<td>CRC32 checksum for the GPT Header structure. This value is computed by setting this field to 0, and computing the 32-bit CRC for HeaderSize bytes.</td>
</tr>
<tr>
<td>Reserved</td>
<td>20</td>
<td>4</td>
<td>Must be zero.</td>
</tr>
<tr>
<td>MyLBA</td>
<td>24</td>
<td>8</td>
<td>The LBA that contains this data structure.</td>
</tr>
<tr>
<td>AlternateLBA</td>
<td>32</td>
<td>8</td>
<td>LBA address of the alternate GPT Header.</td>
</tr>
<tr>
<td>FirstUsableLBA</td>
<td>40</td>
<td>8</td>
<td>The first usable logical block that may be used by a partition described by a GUID Partition Entry.</td>
</tr>
<tr>
<td>LastUsableLBA</td>
<td>48</td>
<td>8</td>
<td>The last usable logical block that may be used by a partition described by a GUID Partition Entry.</td>
</tr>
<tr>
<td>DiskGUID</td>
<td>56</td>
<td>16</td>
<td>GUID that can be used to uniquely identify the disk.</td>
</tr>
<tr>
<td>PartitionEntryLBA</td>
<td>72</td>
<td>8</td>
<td>The starting LBA of the GUID Partition Entry array.</td>
</tr>
<tr>
<td>NumberOfPartitionEntries</td>
<td>80</td>
<td>4</td>
<td>The number of Partition Entries in the GUID Partition Entry array.</td>
</tr>
</tbody>
</table>

continues on next page
Table 5.5 – continued from previous page

<table>
<thead>
<tr>
<th>SizeOf PartitionEntry</th>
<th>84</th>
<th>4</th>
<th>The size, in bytes, of each the GUID Partition Entry structures in the GUID Partition Entry array. This field shall be set to a value of $128 \times 2^n$ where $n$ is an integer greater than or equal to zero (e.g., 128, 256, 512, etc.). NOTE: Previous versions of this specification allowed any multiple of 8.</th>
</tr>
</thead>
<tbody>
<tr>
<td>PartitionEntryArray-CRC32</td>
<td>88</td>
<td>4</td>
<td>The CRC32 of the GUID Partition Entry array. Starts at PartitionEntryLBA and is computed over a byte length of NumberOfPartitionEntries * SizeOfPartitionEntry.</td>
</tr>
<tr>
<td>Reserved</td>
<td>92</td>
<td>BlockSize - 92</td>
<td>The rest of the block is reserved by UEFI and must be zero.</td>
</tr>
</tbody>
</table>

The following test must be performed to determine if a GPT is valid:

- Check the Signature
- Check the Header CRC
- Check that the MyLBA entry points to the LBA that contains the GUID Partition Table
- Check the CRC of the GUID Partition Entry Array

If the GPT is the primary table, stored at LBA 1:

- Check the AlternateLBA to see if it is a valid GPT

If the primary GPT is corrupt, software must check the last LBA of the device to see if it has a valid GPT Header and point to a valid GPT Partition Entry Array. If it points to a valid GPT Partition Entry Array, then software should restore the primary GPT if allowed by platform policy settings (e.g. a platform may require a user to provide confirmation before restoring the table, or may allow the table to be restored automatically). Software must report whenever it restores a GPT.

Software should ask a user for confirmation before restoring the primary GPT and must report whenever it does modify the media to restore a GPT. If a GPT formatted disk is reformatted to the legacy MBR format by legacy software, the last logical block might not be overwritten and might still contain a stale GPT. If GPT-cognizant software then accesses the disk and honors the stale GPT, it will misinterpret the contents of the disk. Software may detect this scenario if the legacy MBR contains valid partitions rather than a protective MBR (Legacy Master Boot Record (MBR)).

Any software that updates the primary GPT must also update the backup GPT. Software may update the GPT Header and GPT Partition Entry Array in any order, since all the CRCs are stored in the GPT Header. Software must update the backup GPT before the primary GPT, so if the size of device has changed (e.g. volume expansion) and the update is interrupted, the backup GPT is in the proper location on the disk.

If the primary GPT is invalid, the backup GPT is used instead and it is located on the last logical block on the disk. If the backup GPT is valid it must be used to restore the primary GPT. If the primary GPT is valid and the backup GPT is invalid software must restore the backup GPT. If both the primary and backup GPTs are corrupted this block device is defined as not having a valid GUID Partition Header.

Both the primary and backup GPTs must be valid before an attempt is made to grow the size of a physical volume. This is due to the GPT recovery scheme depending on locating the backup GPT at the end of the device. A volume may grow in size when disks are added to a RAID device. As soon as the volume size is increased the backup GPT must be moved to the end of the volume and the primary and backup GPT Headers must be updated to reflect the new volume size.
5.3.3 GPT Partition Entry Array

The GPT Partition Entry Array contains an array of GPT Partition Entries. See Table (below) which defines the GPT Partition Entry.

Table 5.6: GPT Partition Entry

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>PartitionTypeGUID</td>
<td>0</td>
<td>16</td>
<td>Unique ID that defines the purpose and type of this Partition. A value of zero defines that this partition entry is not being used.</td>
</tr>
<tr>
<td>UniquePartitionGUID</td>
<td>16</td>
<td>16</td>
<td>GUID that is unique for every partition entry. Every partition ever created will have a unique GUID. This GUID must be assigned when the GPT Partition Entry is created. The GPT Partition Entry is created whenever the NumberOfPartitionEntries in the GPT Header is increased to include a larger range of addresses.</td>
</tr>
<tr>
<td>StartingLBA</td>
<td>32</td>
<td>8</td>
<td>Starting LBA of the partition defined by this entry.</td>
</tr>
<tr>
<td>EndingLBA</td>
<td>40</td>
<td>8</td>
<td>Ending LBA of the partition defined by this entry.</td>
</tr>
<tr>
<td>Attributes</td>
<td>48</td>
<td>8</td>
<td>Attribute bits, all bits reserved by UEFI (Defined GPT Partition Entry — Partition Type GUIDs).</td>
</tr>
<tr>
<td>PartitionName</td>
<td>56</td>
<td>72</td>
<td>Null-terminated string containing a human-readable name of the partition.</td>
</tr>
<tr>
<td>Reserved</td>
<td>128</td>
<td>SizeOfPartitionEntry - 128</td>
<td>The rest of the GPT Partition Entry, if any, is reserved by UEFI and must be zero.</td>
</tr>
</tbody>
</table>

The SizeOfPartitionEntry variable in the GPT Header defines the size of each GUID Partition Entry. Each partition entry contains a Unique Partition GUID value that uniquely identifies every partition that will ever be created. Any time a new partition entry is created a new GUID must be generated for that partition, and every partition is guaranteed to have a unique GUID. The partition is defined as all the logical blocks inclusive of the StartingLBA and EndingLBA.

The PartitionTypeGUID field identifies the contents of the partition. This GUID is similar to the OS Type field in the MBR. Each filesystem must publish its unique GUID. The Attributes field can be used by utilities to make broad inferences about the usage of a partition and is defined in Table (below).

The firmware must add the PartitionTypeGuid to the handle of every active GPT partition using EFI_BOOT_SERVICES.InstallProtocolInterface(). This will allow drivers and applications, including OS loaders, to easily search for handles that represent EFI System Partitions or vendor specific partition types.

Software that makes copies of GPT-formatted disks and partitions must generate new Disk GUID values in the GPT Headers and new Unique Partition GUID values in each GPT Partition Entry. If GPT-cognizant software encounters two disks or partitions with identical GUIDs, results will be indeterminate.

Table 5.7: Defined GPT Partition Entry — Partition Type GUIDs

<table>
<thead>
<tr>
<th>Description</th>
<th>GUID Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Unused Entry</td>
<td>00000000-0000-0000-0000-000000000000</td>
</tr>
<tr>
<td>EFI System Partition</td>
<td>C12A7328-F81F-11D2-BA4B-00A0C93EC93B</td>
</tr>
<tr>
<td>Partition containing a legacy MBR</td>
<td>024DEE41-33E7-11D3-9D69-0008C781F39F</td>
</tr>
</tbody>
</table>

OS vendors need to generate their own Partition Type GUIDs to identify their partition types.
Table 5.8: Defined GPT Partition Entry - Attributes

<table>
<thead>
<tr>
<th>Bits</th>
<th>Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bit 0</td>
<td>Required Partition</td>
<td>If this bit is set, the partition is required for the platform to function. The owner/creator of the partition indicates that deletion or modification of the contents can result in loss of platform features or failure for the platform to boot or operate. The system cannot function normally if this partition is removed, and it should be considered part of the hardware of the system. Actions such as running diagnostics, system recovery, or even OS install or boot could potentially stop working if this partition is removed. Unless OS software or firmware recognizes this partition, it should never be removed or modified as the UEFI firmware or platform hardware may become non-functional.</td>
</tr>
<tr>
<td>Bit 1</td>
<td>No Block IO Protocol</td>
<td>If this bit is set, then firmware must not produce an EFI_BLOCK_IO_PROTOCOL device for this partition. See Partition Discovery for more details. By not producing an EFI_BLOCK_IO_PROTOCOL partition, file system mappings will not be created for this partition in UEFI.</td>
</tr>
<tr>
<td>Bit 2</td>
<td>Legacy BIOS Bootable</td>
<td>This bit is set aside by this specification to let systems with traditional PC-AT BIOS firmware implementations inform certain limited, special-purpose software running on these systems that a GPT partition may be bootable. For systems with firmware implementations conforming to this specification, the UEFI boot manager (see chapter 3) must ignore this bit when selecting a UEFI-compliant application, e.g., an OS loader (see 2.1.3). Therefore there is no need for this specification to define the exact meaning of this bit.</td>
</tr>
<tr>
<td>Bits 3-47</td>
<td>Undefined and must be zero. Reserved for expansion by future versions of the UEFI specification.</td>
<td></td>
</tr>
<tr>
<td>Bits 48-63</td>
<td>Reserved for GUID specific use. The use of these bits will vary depending on the PartitionTypeGUID. Only the owner of the PartitionTypeGUID is allowed to modify these bits. They must be preserved if Bits 0-47 are modified.</td>
<td></td>
</tr>
</tbody>
</table>

Related Definitions:

```c
#pragma pack(1)
///
/// GPT Partition Entry.
///
typedef struct {
    EFI_GUID PartitionTypeGUID;
    EFI_GUID UniquePartitionGUID;
    EFI_LBA StartingLBA;
    EFI_LBA EndingLBA;
    UINT64 Attributes;
    CHAR16 PartitionName[36];
} EFI_PARTITION_ENTRY;
#pragma pack()
```
This specification defines the Block Translation Table (BTT) metadata layout. The following sub-sections outline the BTT format that is utilized on the media, the data structures involved, and a detailed description of how SW is to interpret the BTT layout.

### 6.1 Block Translation Table (BTT) Background

A namespace defines a contiguously-addressed range of Non-Volatile Memory conceptually similar to a SCSI Logical Unit (LUN) or a NVM Express namespace.

Any namespace being utilized for block storage may contain a Block Translation Table (BTT), which is a layout and set of rules for doing block I/O that provide powerfail write atomicity of a single block. Traditional block storage, including hard disks and SSDs, usually protect against torn sectors, which are sectors partially written when interrupted by power failure. Existing software, mostly file systems, depend on this behavior, often without the authors realizing it. To enable such software to work correctly on namespaces supporting block storage access, the BTT layout defined by this document sub-divides a namespace into one or more BTT Arenas, which are large sections of the namespace that contain the metadata required to provide the desired write atomicity. Each of these BTT Arenas contains a metadata layout as shown in Figures 6-1 and 6-2 below.

Each arena contains the layout shown in Figure 6-1 (above), the primary info block, data area, map, flog, and a backup info block. Each of these areas is described in the following sections. When the namespace is larger than 512 GiB, multiple arenas are required by the BTT layout, as shown in Figure 6-2 (below). Each namespace using a BTT is divided into as many 512 GiB arenas as shall fit, followed by a smaller arena to contain any remaining space as appropriate. The smallest arena size is 16MiB so the last arena size shall be between 16MiB and 512GiBs. Any remaining space less than 16MiB is unused. Because of these rules for arena placement, software can locate every primary Info block and every backup Info block without reading any metadata, based solely on the namespace size.

### 6.2 Block Translation Table (BTT) Data Structures

The following sub-sections outline the data structures associated with the BTT Layout.
Fig. 6.1: The BTT Layout in a BTT Arena

Fig. 6.2: A BTT With Multiple Arenas in a Large Namespace
6.2.1 BTT Info Block

```
// Alignment of all BTT structures
#define EFI_BTT_ALIGNMENT 4096
#define EFI_BTT_INFO_UNUSED_LEN 3968

#define EFI_BTT_INFO_BLOCK_SIG_LEN 16

// Constants for Flags field
#define EFI_BTT_INFO_BLOCK_FLAGS_ERROR 0x00000001

// Constants for Major and Minor version fields
#define EFI_BTT_INFO_BLOCK_MAJOR_VERSION 2
#define EFI_BTT_INFO_BLOCK_MINOR_VERSION 0

typedef struct _EFI_BTT_INFO_BLOCK {
  CHAR8 Sig[EFI_BTT_INFO_BLOCK_SIG_LEN];
  EFI_GUID Uuid;
  EFI_GUID ParentUuid;
  UINT32 Flags;
  UINT16 Major;
  UINT16 Minor;
  UINT32 ExternalLbaSize;
  UINT32 ExternalNLba;
  UINT32 InternalLbaSize;
  UINT32 InternalNLba;
  UINT32 NFree;
  UINT32 InfoSize;
  UINT64 NextOff;
  UINT64 DataOff;
  UINT64 MapOff;
  UINT64 FlogOff;
  UINT64 InfoOff;
  CHAR8 Unused[EFI_BTT_INFO_UNUSED_LEN];
  UINT64 Checksum;
} EFI_BTT_INFO_BLOCK
```

**Sig**
Signature of the BTT Index Block data structure. Shall be “BTT_ARENA_INFO00”.

**UUID**
UUID identifying this BTT instance. A new UUID is created each time the initial BTT Arenas are written. This value shall be identical across all BTT Info Blocks within all arenas within a namespace.

**ParentUuid**
UUID of containing namespace, used when validating the BTT Info Block to ensure this instance of the BTT layout is intended for the current surrounding namespace, and not left over from a previous namespace that used the same area of the media. This value shall be identical across all BTT Info Blocks within all arenas within a namespace.

**Flags**
Boolean attributes of this BTT Info Block. See the additional description below on the use of the flags. The following values are defined:

- **EFI_BTT_INFO_BLOCK_FLAGS_ERROR** - The BTT Arena is in the error state. When a BTT implementation discovers issues such as inconsistent metadata or lost metadata due to unrecoverable media errors, the
error bit for the associated arena shall be set. See the BTT Theory of Operation section regarding handling of EFI_BTT_INFO_BLOCK_FLAGS_ERROR.

**Major**

Major version number. Currently at version 2. This value shall be identical across all BTT Info Blocks within all arenas within a namespace.

**Minor**

Minor version number. Currently at version 0. This value shall be identical across all BTT Info Blocks within all arenas within a namespace.

**ExternalLbaSize**

Advertised LBA size in bytes. I/O requests shall be in this size chunk. This value shall be identical across all BTT Info Blocks within all arenas within a namespace.

**ExternalNLba**

Advertised number of LBAs in this arena. The sum of this field, across all BTT Arenas, is the total number of available LBAs in the namespace.

**InternalLbaSize**

Internal LBA size shall be greater than or equal to ExternalLbaSize and shall not be smaller than 512 bytes. Each block in the arena data area is this size in bytes and contains exactly one block of data. Optionally, this may be larger than the ExternalLbaSize due to alignment padding between LBAs. This value shall be identical across all BTT Info Blocks within all arenas within a namespace.

**InternalNLba**

Number of internal blocks in the arena data area. This shall be equal to ExternalNLba + NFree because each internal lba is either mapped to an external lba or shown as free in the flog.

**NFree**

Number of free blocks maintained for writes to this arena. NFree shall be equal to InternalNLba – ExternalNLba. This value shall be identical across all BTT Info Blocks within all arenas within a namespace.

**InfoSize**

The size of this info block in bytes. This value shall be identical across all BTT Info Blocks within all arenas within a namespace.

**NextOff**

Offset of next arena, relative to the beginning of this arena. An offset of 0 indicates that no arenas follow the current arena. This field is provided for convenience as the start of each arena can be calculated from the size of the namespace as described in the Theory of Operation – Validating BTT Arenas at start-up description. This value shall be identical in the primary and backup BTT Info Blocks within an arena.

**DataOff**

Offset of the data area for this arena, relative to the beginning of this arena. The internal-LBA number zero lives at this offset. This value shall be identical in the primary and backup BTT Info Blocks within an arena.

**MapOff**

Offset of the map for this arena, relative to the beginning of this arena. This value shall be identical in the primary and backup BTT Info Blocks within an arena.

**FlogOff**

Offset of the flog for this arena, relative to the beginning of this arena. This value shall be identical in the primary and backup BTT Info Blocks within an arena.

**InfoOff**

Offset of the backup copy of this arena’s info block, relative to the beginning of this arena. This value shall be identical in the primary and backup BTT Info Blocks within an arena.

**Reserved**

Shall be zero.
6.2.2 BTT Map Entry

```c
typedef struct _EFI_BTT_MAP_ENTRY {
    UINT32 PostMapLba : 30;
    UINT32 Error : 1;
    UINT32 Zero : 1;
} EFI_BTT_MAP_ENTRY;
```

**PostMapLba**
- Post-map LBA number (block number in this arena’s data area)

**Error**
- When set and *Zero* is not set, reads on this block return an error. Writes to this block clear this flag.

**Zero**
- When set and *Error* is not set, reads on this block return a full block of zeros. Writes to this block clear this flag.

**BTT Map Description**

The BTT Map area maps an LBA that indexes into the arena, to its actual location. The BTT Map is located as high as possible in the arena, after room for the backup info block and flog (and any required alignment) has been taken into account. The terminology *pre-map LBA* and *post-map LBA* is used to describe the input and output values of this mapping.

The BTT Map area is indexed by the pre-map LBA and each entry in the map contains the 30 bit post-map LBA and bits to indicate if there is an error or if LBA contains zeroes (see EFI_BTT_MAP_ENTRY).

The *Error* and *Zero* bits indicate conditions that cannot both be true at the same time, so that combination is used to indicate a *normal* map entry, where no error or zeroed block is indicated. The error condition is indicated only when the *Error* bit is set and the *Zero* bit is clear, with similar logic for the zero block condition. When neither condition is indicated, both *Error* and *Zero* are set to indicate a map entry in its normal, non-error state. This leaves the case where both *Error* and *Zero* are bits are zero, which is the initial state of all map entries when the BTT layout is first written. Both bits zero means that the map entry contains the initial identity mapping where the pre-map LBA is mapped to the same post-map LBA. Defining the map this way allows an implementation to leverage the case where the initial contents of the namespace is known to be zero, requiring no writes to the map when writing the layout. This can greatly improve the layout time since the map is the largest BTT data structure written during layout.
6.2.3 BTT Flog

```c
// Alignment of each flog structure
#define EFI_BTT_FLOG_ENTRY_ALIGNMENT 64

typedef struct _EFI_BTT_FLOG {
    UINT32  Lba0;
    UINT32  OldMap0;
    UINT32  NewMap0;
    UINT32  Seq0;
    UINT32  Lba1;
    UINT32  OldMap1;
    UINT32  NewMap1;
    UINT32  Seq1;
} EFI_BTT_FLOG
```

**lba0**
Last pre-map LBA written using this flog entry. This value is used as an index into the BTT Map when updating it to complete the transaction.

**OldMap0**
Old post-map LBA. This is the old entry in the map when the last write using this flog entry occurred. If the transaction is complete, this LBA is now the free block associated with this flog entry.

**NewMap0**
New post-map LBA. This is the block allocated when the last write using this flog entry occurred. By definition, a write transaction is complete if the BTT Map entry contains this value.

**Seq0**
The `Seq0` field in each flog entry is used to determine which set of fields is newer between the two sets (Lba0, OldMap0, NewMap0, Seq0 vs Lba1, OldMap1, NewMap1, Seq1). Updates to a flog entry shall always be made to the older set of fields and shall be implemented carefully so that the `Seq0` bits are only written after the other fields are known to be committed to persistence. The figure below shows the progression of the `Seq0` bits over time, where the newer entry is indicated by a value that is clockwise of the older value.

![Fig. 6.3: Cyclic Sequence Numbers for Flog Entries](image_url)

6.2. Block Translation Table (BTT) Data Structures
**Lba1**
Alternate lba entry

**OldMap1**
Alternate old entry

**NewMap1**
Alternate new entry

**Seq1**
Alternate Seq entry

**BTT Flog Description**

The BTT Flog is so named to illustrate that it is both a free list and a log, rolled into one data structure. The Flog size is determined by the **NFree** field in the BTT Info Block which determines how many of these flog entries there are. The flog location is the highest address in the arena after space for the backup info block and alignment requirements have been taken in account.

**6.2.4 BTT Data Area**

Starting from the low address to high, the BTT Data Area starts immediately after the BTT Info Block and extends to the beginning of the BTT Map data structure. The number of internal data blocks that can be stored in an arena is calculated by first calculating the necessary space required for the BTT Info Blocks, map, and flog (plus any alignment required), subtracting that amount from the total arena size, and then calculating how many blocks fit into the resulting space.

**6.2.5 NVDIMM Label Protocol Address Abstraction Guid**

This version of the BTT layout and behavior is collectively described by the AddressAbstractionGuid in the UEFI NVDIMM Label protocol section utilizing this GUID:

```c
#define EFI_BTT_ABSTRACTION_GUID \
 {0x18633bfc,0x1735,0x4217,0x8a,0xc9,0x17,0x23,0x92,0x82,0xd3,0xf8}
```

**6.3 BTT Theory of Operation**

This section outlines the theory of operation for the BTT and describes the responsibilities that any software implementation shall follow.

A specific instance of the BTT layout depends on the size of the namespace and three administrative choices made at the time the initial layout is created:

- **ExternalLbaSize**: the desired block size
- **InternalLbaSize**: the block size with any internal padding
- **NFree**: the number of concurrent writes supported by the layout

The BTT data structures do not support an **InternalLbaSize** smaller than 512 bytes, so if **ExternalLbaSize** is smaller than 512 bytes, the **InternalLbaSize** shall be rounded up to 512. For performance, the **InternalLbaSize** may also include some padding bytes. For example, a BTT layout supporting 520-byte blocks may use 576-byte blocks internally in order to round up the size to a multiple of a 64-byte cache line size. In this example, the **ExternalLbaSize**, visible to software above the BTT software, would be 520 bytes, but the **InternalLbaSize** would be 576 bytes.
Once these administrative choices above are determined, the namespace is divided up into *arenas*, as described in the BTT Arenas section, where each arena uses the same values for ExternalLbaSize, InternalLbaSize, and Nfree.

### 6.3.1 BTT Arenas

In order to reduce the size of BTT metadata and increase the possibility of concurrent updates, the BTT layout in a namespace is divided into *arenas*. An arena cannot be larger than 512GiB or smaller than 16MiB. A namespace is divided into as many 512GiB arenas that shall fit, starting from offset zero and packed together without padding, followed by one arena smaller than 512GiB if the remaining space is at least 16MiB. The smaller area size is rounded down to be a multiple of EFI_BTT_ALIGNMENT if necessary. Because of these rules, the location and size of every BTT Arena in a namespace can be determined from the namespace size.

Within an arena, the amount of space used for the Flog is \( NFree \) times the amount of space required for each Flog entry. Flog entries shall be aligned on 64-byte boundaries. In addition, the full BTT Flog table shall be aligned on a EFI_BTT_ALIGNMENT boundary and have a size that is padded to be multiple of EFI_BTT_ALIGNMENT. In summary, the space in an arena taken by the Flog is:

\[
FlogSize = rounduP(NFree * rounduP(sizeof(EFI_BTT_FLOG),
EFI_BTT_FLOG_ENTRY_ALIGNMENT),
EFI_BTT_ALIGNMENT)
\]

Within an arena, the amount of space available for data blocks and the associated Map is the arena size minus the space used for the BTT Info Blocks and the Flog:

\[
DataAndMapSize = ArenaSize - 2 * sizeof(EFI_BTT_INFO_BLOCK) - FlogSize
\]

Within an arena, the number of data blocks is calculated by dividing the available space, DataAndMapSize, by the InternalLbaSize plus the map overhead required for each block, and rounding down the result to ensure the data area is aligned on a EFI_BTT_ALIGNMENT boundary:

\[
InternalNLba = \frac{(DataAndMapSize - EFI_BTT_ALIGNMENT)}{(InternalLbaSize + sizeof(EFI_BTT_MAP_ENTRY))}
\]

With the InternalNLba value known, the calculation for the number of external LBAs subtracts off NFree for the pool of unadvertised free blocks:

\[
ExternalNLba = InternalNLba - Nfree
\]

Within an arena, the number of bytes required for the BTT Map is one entry for each external LBA, plus any alignment required to maintain an alignment of EFI_BTT_ALIGNMENT for the entire map:

\[
MapSize = rounduP(ExternalNLba * sizeof(EFI_BTT_MAP_ENTRY),
EFI_BTT_ALIGNMENT)
\]

The number of concurrent writes allowed for an arena is based on the \( NFree \) value chosen at BTT layout time. For example, choosing \( NFree \) of 256 means the BTT Arena shall have 256 free blocks to use for in-flight write operations. Since BTT Arenas each have \( NFree \) free blocks, the number of concurrent writes allowed in a namespace may be larger when there are multiple arenas and the writes are spread out between multiple arenas.
### 6.3.2 Atomicity of Data Blocks in an Arena

The primary reason for the BTT is to provide failure atomicity when writing data blocks, so that any write of a single block cannot be torn by interruptions such as power loss. The BTT provides this by maintaining a pool of free blocks which are not part of the capacity advertised to software layers above the BTT software. The BTT Data Area is large enough to hold the advertised capacity as well as the pool of free blocks. The BTT software manages the blocks in the BTT Data Area as a list of *internal* LBAs, which are block numbers only visible internally to the BTT software. The block numbers that make up the advertised capacity are known as *external* LBAs, and at any given point in time, each one of those external LBAs is mapped by the BTT Map to one of the blocks in the BTT Data Area. Each block write done by the BTT software starts by allocating one of the free blocks, writing the data to it, and only when that block is fully persistent (including any flushes required), are steps taken to make that block active, as outlined in the BTT Theory of Operations - Write Path section.

The BTT Flog (a combination of a free list and a log) is at the heart of the atomic updates when writing blocks. The “quiet” state of a BTT Flog, when no in-flight writes are happening and no recovery steps are outstanding, is that the NFree free blocks currently available for writes are contained in the OldMap fields in the Flog entries. A write shall use one of those Flog entries to find a free block to write to, and then the Lba and NewMap fields in the Flog are used as a write-ahead-log for the BTT Map update when the data portion of the write is complete, as described in the Validating the Flog at start-up section.

It is up to run-time logic in the BTT software to ensure that only one Flog entry is in use at a time, and that any reads still executing on the block indicated by the OldMap entry have finished before starting a write using that block.

### 6.3.3 Atomicity of BTT Data Structures

Byte-addressable persistent media may not support atomic updates larger than 8-bytes, so any data structure larger than 8-bytes in the BTT uses software-implemented atomicity for updates. Note that 8-byte write atomicity, meaning an 8-byte store to the persistent media cannot be torn by interruptions such as power failures, is a minimal requirement for using the BTT described in this document.

There are four types of data structures in the BTT:

- The BTT Info Blocks
- The BTT Map
- The BTT Flog
- The BTT Data Area

The BTT Map entries are 4-bytes in size, and so can be updated atomically with a single store instruction. All other data structures are updated by following the rules described in this document, which update an inactive version of the data structure first, followed by steps to make it active atomically.

For the BTT Info Blocks, atomicity is provided by always writing the backup Info block first, and only after that update is fully persistent (the block checksums correctly), is the primary BTT Info Block updated as described in the Writing the initial BTT layout section. Recovery from an interrupted update is provided by checking the primary Info block’s checksum on start-up, and if it is bad, copying the backup Info block to the primary to complete the interrupted update as described in the Validating BTT Arenas at start-up section.

For the BTT Flog, each entry is double-sized, with two complete copies of every field (Lba, OldMap, NewMap, Seq). The active entry has the higher Seq number, so updates always write to the inactive fields, and once those fields are fully persistent, the Seq field for the inactive entry is updated to make it become the active entry atomically. This is described in the Validating the Flog at start-up section.

For the BTT Data Area, all block writes can be thought of as allocating writes, where an inactive block is chosen from the free list maintained by the Flog, and only after the new data written to that block is fully persistent, that block is made active atomically by updating the Flog and Map entries as described in the Write Path section.
6.3.4 Writing the Initial BTT layout

The overall layout of the BTT relies on the fact that all arenas shall be 512GiB in size, except the last arena which is a minimum of 16MiB. Initializing the BTT on-media structures only happens once in the lifetime of a BTT, when it is created. This sequence assumes that software has determined that new BTT layout needs to be created and the total raw size of the namespace is known.

Immediately before creating a new BTT layout, the UUID of the surrounding namespace may be updated to a newly-generated UUID. This optional step, depending on the needs of a BTT software implementation, has the effect of invalidating any previous BTT Info Blocks in the namespace and ensuring the detection of an invalid layout if the BTT layout creation process is interrupted. This detection works because the parent UUID field

The on-media structures in the BTT layout may be written out in any order except for the BTT Info Blocks, which shall be written out as the last step of the layout, starting from the last arena (highest offset in the namespace) to the first arena (lowest offset in the namespace), writing the backup BTT Info Block in each arena first, then writing the primary BTT Info block for that arena second. This allows the detection of an incomplete BTT layout when the algorithm in the Validating BTT Arenas at start-up section is executed.

Since the number of internal LBAs for an arena exceeds the number of external LBAs by \( N_{Free} \), there are enough internal LBA numbers to fully initialize the BTT Map as well as the BTT Flog, where the BTT Flog is initialized with the \( N_{Free} \) highest internal LBA numbers, and the rest are used in the BTT Map.

The BTT Map in each arena is initialized to zeros. Zero entries in the map indicate the identity mapping of all pre-map LBAs to the corresponding post-map LBAs. This uses all but \( N_{Free} \) of the internal LBAs, leaving \( N_{free} \) of them for the BTT Flog.

The BTT Flog in each arena is initialized by starting with all zeros for the entire flog area, setting the \( Lba0 \) field in each flog entry to unique pre-map LBAs, zero through \( N_{Free} - 1 \), and both \( OldMap0 \) and \( NewMap0 \) fields in each flog entry are set to one of the remaining internal LBAs. For example, flog entry zero would have \( Lba0 \) set to 0, and \( OldMap0 \) and \( NewMap0 \) both set to the first internal LBA not represented in the map (since there are \( ExternalNLba \) entries in the map, the next available internal LBA is equal to \( ExternalNLba \)).

6.3.5 Validating BTT Arenas at start-up

When software prepares to access the BTT layout in a namespace, the first step is to check the BTT Arenas for consistency. Reading and validating BTT Arenas relies on the fact that all arenas shall be 512GiB in size, except the last arena which is a minimum of 16MiB.

The following tests shall pass before software considers the BTT layout to be valid:

- For each BTT Arena:
  - ReadAndVerifyPrimaryBttInfoBlock
    - If the read of the primary BTT Info Block fails, goto ReadAndVerifyBackupBttInfoBlock
    - If the primary BTT Info Block contains an incorrect \( Sig \) field it is invalid, goto ReadAndVerifyBackupBttInfoBlock
    - If the primary BTT Info Block ParentUuid field does not match the UUID of the surrounding namespace, goto ReadAndVerifyBackupBttInfoBlock
    - If the primary BTT Info Block contains an incorrect \( Checksum \) it is invalid, goto ReadAndVerifyBackupBttInfoBlock
    - The primary BTT Info Block is valid. Use the \( NextOff \) field to find the start of the next arena and continue BTT Info Block validation, goto ReadAndVerifyPrimaryBttInfoBlock
  - ReadAndVerifyBackupBttInfoBlock
Determine the location of the backup BTT Info Block:

1. All of the arenas shall be the full 512GiB data area size except the last arena which is at least 16MiB.
2. The backup BTT Info Block is the last EFI_BTT_ALIGNMENT aligned block in the arena.

If the read of the backup BTT Info Block at the high address of the BTT Arena fails, neither copy could be read, and software shall assume that there is no valid BTT metadata layout for the namespace.

If the backup BTT Info Block contains an incorrect Sig field it is invalid, and software shall assume that there is no valid BTT metadata layout for the namespace.

If the backup BTT Info Block ParentUuid field does not match the UUID of the surrounding namespace it is invalid, and software shall assume that there is no valid BTT metadata layout for the namespace.

If the backup BTT Info Block contains an incorrect Checksum it is invalid, and software shall assume that there is no valid BTT metadata layout for the namespace.

The backup BTT Info Block is valid. Since the primary copy is bad, software shall copy the contents of the valid backup BTT Info Block down to the primary BTT Info Block before validation of all of the BTT Info Blocks in all of the arenas can complete successfully.

### 6.3.6 Validating the Flog entries at start-up

After validating the BTT Info Blocks as described in the Validating BTT Arenas at start-up section, the next step software shall take is to validate the BTT Flog entries. When blocks of data are being written, as described in the Write Path section below, the persistent Flog and Map states are not updated until the free block is written with new data. This ensures a power failure at any point during the data transfer is harmless, leaving the partially written data in a free block that remains free. Once the Flog is updated (made atomic by the Seq bits in the Flog entry), the write algorithm is committed to the update and a power failure from this point in the write flow onwards shall be handled by completing the update to the BTT Map on recovery. The Flog contains all the information required to complete the Map entry update.

Note that the Flog entry recovery outlined here is intended to happen single-threaded, on an inactive BTT (before the BTT block namespace is allowed to accept I/O requests). The maximum amount of time required for recovery is determined by \( N_{Free} \), but is only a few loads and a single store (and the corresponding cache flushes) for each incomplete write discovered.

The following steps are executed for each flog entry in each arena, to recover any interrupted writes and to verify the flog entries are consistent at start up. Any consistency issues found during these steps results in setting the error state (EFI_BTT_INFO_BLOCK_FLAGS_ERROR) for the arena and terminates the flog validation process for this arena.

1. The Seq0 and Seq1 fields are examined for the flog entry. If both fields are zero, or both fields are equal to each other, the flog entry is inconsistent. Otherwise, the higher Seq field indicates which set of flog fields to use for the next steps \((Lba0, OldMap0, NewMap0, versus Lba1, OldMap1, NewMap1)\). From this point on in this section, the chosen fields are referenced as Lba, OldMap, and NewMap.

2. If OldMap and NewMap are equal, this is a flog entry that was never used since the initial layout of the BTT was created.

3. The Lba field is checked to ensure it is a valid pre-map LBA (in the range zero to ExternalNLba – 1). If the check fails, the flog entry is inconsistent.

4. The BTT Map entry corresponding to the Flog entry Lba field is fetched. Since the Map can contain special zero entries to indicate identity mappings, the fetched entry is adjusted to the corresponding internal LBA when a zero is encountered (by interpreting the entry as the same LBA as the Flog entry Lba field).
5. If the adjusted map entry from the previous step does not match the NewMap field in the Flog entry, and it matches the OldMap field, then an interrupted BTT Map update has been detected. The recovery step is to write the NewMap field to the BTT Map entry indexed by the Flog entry Lba field.

### 6.3.7 Read Path

The following high level sequence describes the steps to read a single block of data while utilizing the BTT as is illustrated in the Figure: BTT Read Path Overview below:

1. If EFI_BTT_INFO_BLOCK_FLAGS_ERROR is set in the arena’s BTT Info Block, the BTT software may return an error for the read, or an implementation may choose to continue to provide read-only access and continue these steps.

2. Use the external LBA provided with the read operation to determine which BTT Arena to access. Starting from the first arena (lowest offset in the namespace), and looping through the arena in order, the ExternalNLba field in the BTT Info Block describes how many external LBAs are in that area. Once the correct arena is identified, the external LBAs contained in the lower, skipped, arenas are subtracted from the provided LBA to obtain the pre-map LBA for the selected arena.

3. Use the pre-map LBA to index into the arena’s BTT Map and the map entry.

4. If both the Zero and Error bits are set in the map entry, this indicates a normal entry. The PostMapLba field in the Map entry is used to index into the arena Data Area by multiplying it by the InternalLbaSize and adding the result to the DataOff field from the arena’s BTT Info Block. This provides the location of the data in the arena and software then copies ExternalLbaSize bytes into the provided buffer to satisfy the read request.

5. Otherwise, if only the Error bit is set in the map entry, a read error is returned.

6. Otherwise, if only the Zero bit is set in the map entry, a block of ExternalLbaSize bytes of zeros is copied into the provided buffer to satisfy the read request.

7. Finally, if both Zero and Error bits are clear, this the initial identity mapping and the pre-map LBA is used to index into the arena Data Area by multiplying it by the InternalLbaSize and adding the result to the DataOff field from the arena’s BTT Info Block. This provides the location of the data in the arena and software then copies ExternalLbaSize bytes into the provided buffer to satisfy the read request.

### 6.3.8 Write Path

The following high level sequence describes the steps to write a single block of data while utilizing the BTT as is illustrated in the Figure: BTT Write Path Overview below:

1. If EFI_BTT_INFO_BLOCK_FLAGS_ERROR is set in the arena’s BTT Info Block, the BTT software shall return an error for the write.

2. Use the external LBA provided with the write operation to determine which BTT Arena to access. Starting from the first arena (lowest offset in the namespace), and looping through the arena in order, the ExternalNLba field in the BTT Info Block describes how many external LBAs are in that area. Once the correct arena is identified, the external LBAs contained in the lower, skipped, arenas are subtracted from the provided LBA to obtain the pre-map LBA for the selected arena.

3. The BTT software allocates one of the Flog entries in the arena to be used for this write. The Flog entry shall not be shared by multiple concurrent writes. The exact method for managing the exclusive use of the Flog entries is BTT software implementation-dependent. There’s no on-media indication of whether a Flog entry is currently allocated to a write request or not. Note that the free block tracked by the Flog entry in the OldMap field, may still have reads from relatively slow threads operating on it. The BTT software implementation shall ensure any such reads have completed before moving to the next step.
4. Lock out access to the BTT Map area associated with the pre-map LBA for the next three steps. The granularity of the locking is implementation-dependent; an implementation may choose to lock individual Map entries, lock the entire BTT Map, or something in-between.

5. Use the pre-map LBA to index into the arena’s BTT Map and fetch the old map entry.

6. Update the Flog entry by writing the inactive set of Flog fields (the lower Seq number). First, update the Lba, OldMap, and NewMap fields with the pre-map LBA, old Map entry, and the free block chosen above, respectively. Once those fields are fully persistent (with any required flushes completed), the Seq field is updated to make the new fields active. This update of the Seq field commits the write - before this update, the write shall not take place if the operation is interrupted. After the Seq field is updated, the write shall take place even if the operation is interrupted because the Map update in the next step shall take place during the BTT recovery that happens on start-up.

7. Update the Map entry with the free block chosen above.

8. Drop the map lock acquired in step 4 above. The write request is now satisfied.
Fig. 6.5: BTT Write Path Overview
This section discusses the fundamental boot services that are present in a UEFI compliant system. The services are defined by interface functions that may be used by code running in the UEFI environment. Such code may include protocols that manage device access or extend platform capability, as well as applications running in the preboot environment, and OS loaders.

Two types of services apply in an compliant system:

**Boot Services**

Functions that are available before a successful call to `EFI_BOOT_SERVICES.ExitBootServices()`. These functions are described in this section.

**Runtime Services**

Functions that are available before and after any call to ExitBootServices(). These functions are described in [Services — Runtime Services](#).

During boot, system resources are owned by the firmware and are controlled through boot services interface functions. These functions can be characterized as “global” or “handle-based.” The term “global” simply means that a function accesses system services and is available on all platforms (since all platforms support all system services). The term “handle-based” means that the function accesses a specific device or device functionality and may not be available on some platforms (since some devices are not available on some platforms). Protocols are created dynamically. This section discusses the “global” functions and runtime functions; subsequent sections discuss the “handle-based.”

UEFI applications (including UEFI OS loaders) must use boot services functions to access devices and allocate memory. On entry, an Image is provided a pointer to a system table which contains the Boot Services dispatch table and the default handles for accessing the console. All boot services functionality is available until a UEFI OS loader loads enough of its own environment to take control of the system’s continued operation and then terminates boot services with a call to `ExitBootServices()`.

In principle, the `ExitBootServices()` call is intended for use by the operating system to indicate that its loader is ready to assume control of the platform and all platform resource management. Thus boot services are available up to this point to assist the UEFI OS loader in preparing to boot the operating system. Once the UEFI OS loader takes control of the system and completes the operating system boot process, only runtime services may be called. Code other than the UEFI OS loader, however, may or may not choose to call `ExitBootServices()`. This choice may in part depend upon whether or not such code is designed to make continued use of boot services or the boot services environment.

The rest of this section discusses individual functions. Global boot services functions fall into these categories:

- **Event, Timer, and Task Priority Services**
- **Memory Allocation Services**
- **Protocol Handler Services**
- **Image Services**
7.1 Event, Timer, and Task Priority Services

The functions that make up the Event, Timer, and Task Priority Services are used during preboot to create, close, signal, and wait for events; to set timers; and to raise and restore task priority levels. See the following table for details.

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>CreateEvent</td>
<td>Boot</td>
<td>Creates a general-purpose event structure</td>
</tr>
<tr>
<td>CreateEventEx</td>
<td>Boot</td>
<td>Creates an event structure as part of an event group</td>
</tr>
<tr>
<td>CloseEvent</td>
<td>Boot</td>
<td>Closes and frees an event structure</td>
</tr>
<tr>
<td>SignalEvent</td>
<td>Boot</td>
<td>Signals an event</td>
</tr>
<tr>
<td>WaitForEvent</td>
<td>Boot</td>
<td>Stops execution until an event is signaled</td>
</tr>
<tr>
<td>CheckEvent</td>
<td>Boot</td>
<td>Checks whether an event is in the signaled state</td>
</tr>
<tr>
<td>SetTimer</td>
<td>Boot</td>
<td>Sets an event to be signaled at a particular time</td>
</tr>
<tr>
<td>RaiseTPL</td>
<td>Boot</td>
<td>Raises the task priority level</td>
</tr>
<tr>
<td>RestoreTPL</td>
<td>Boot</td>
<td>Restores/lowers the task priority level</td>
</tr>
</tbody>
</table>

Execution in the boot services environment occurs at different task priority levels, or TPLs. The boot services environment exposes only three of these levels to UEFI applications and drivers (see table below: TPL Usage)

- **TPL_APPLICATION** — the lowest priority level
- **TPL_CALLBACK** — an intermediate priority level
- **TPL_NOTIFY** — the highest priority level

Tasks that execute at a higher priority level may interrupt tasks that execute at a lower priority level. For example, tasks that run at the TPL_NOTIFY level may interrupt tasks that run at the TPL_APPLICATION or TPL_CALLBACK level. While TPL_NOTIFY is the highest level exposed to the boot services applications, the firmware may have higher task priority items it deals with. For example, the firmware may have to deal with tasks of higher priority like timer ticks and internal devices. Consequently, there is a fourth TPL, TPL_HIGH_LEVEL (link needed), designed for use exclusively by the firmware.

The intended usage of the priority levels is shown in the TPL Usage table below, from the lowest level (TPL_APPLICATION) to the highest level (TPL_NOTIFY). As the level increases, the duration of the code and the amount of blocking allowed decrease. Execution generally occurs at the TPL.APPLICATION level. Execution occurs at other levels as a direct result of the triggering of an event notification function (this is typically caused by the signaling of an event). During timer interrupts, firmware signals timer events when an event’s “trigger time” has expired. This allows event notification functions to interrupt lower priority code to check devices (for example). The notification function can signal other events as required. After all pending event notification functions execute, execution continues at the TPL.APPLICATION level.

---

### Table 7.2: TPL Usage

<table>
<thead>
<tr>
<th>Task Priority Level</th>
<th>Usage</th>
</tr>
</thead>
<tbody>
<tr>
<td>TPL_APPLICATION</td>
<td>This is the lowest priority level. It is the level of execution which</td>
</tr>
<tr>
<td></td>
<td>occurs when no event notifications are pending and which interacts</td>
</tr>
<tr>
<td></td>
<td>with the user. User I/O (and blocking on User I/O) can be performed</td>
</tr>
<tr>
<td></td>
<td>at this level. The boot manager executes at this level and passes</td>
</tr>
<tr>
<td></td>
<td>control to other UEFI applications at this level.</td>
</tr>
<tr>
<td>TPL_CALLBACK</td>
<td>Interrupts code executing below TPL_CALLBACK level. Long term</td>
</tr>
<tr>
<td></td>
<td>operations (such as file system operations and disk I/O) can occur</td>
</tr>
<tr>
<td></td>
<td>at this level.</td>
</tr>
</tbody>
</table>
Table 7.2 – continued from previous page

<table>
<thead>
<tr>
<th>Name</th>
<th>Restrictions</th>
<th>Task Priority</th>
</tr>
</thead>
<tbody>
<tr>
<td>TPL_NOTIFY</td>
<td>Interrupts code executing below TPL_NOTIFY level. Blocking is not allowed at this level. Code executes to completion and returns. If code requires more processing, it needs to signal an event to wait to obtain control again at whatever level it requires. This level is typically used to process low level IO to or from a device.</td>
<td></td>
</tr>
<tr>
<td>Firmware Interrupts</td>
<td>This level is internal to the firmware. It is the level at which internal interrupts occur. Code running at this level interrupts code running at the TPL_NOTIFY level (or lower levels). If the interrupt requires extended time to complete, firmware signals another event (or events) to perform the longer term operations so that other interrupts can occur.</td>
<td></td>
</tr>
<tr>
<td>TPL_HIGH_LEVEL</td>
<td>Interrupts code executing below TPL_HIGH_LEVEL. This is the highest priority level. It is not interruptible (interrupts are disabled) and is used sparingly by firmware to synchronize operations that need to be accessible from any priority level. For example, it must be possible to signal events while executing at any priority level. Therefore, firmware manipulates the internal event structure while at this priority level.</td>
<td></td>
</tr>
</tbody>
</table>

Executing code can temporarily raise its priority level by calling the `EFI_BOOT_SERVICES.RaiseTPL()` function. Doing this masks event notifications from code running at equal or lower priority levels until the `EFI_BOOT_SERVICES.RestoreTPL()` function is called to reduce the priority to a level below that of the pending event notifications. There are restrictions on the TPL levels at which many UEFI service functions and protocol interface functions can execute. **TPL Restrictions** summarizes the restrictions.

Table 7.3: TPL Restrictions

<table>
<thead>
<tr>
<th>Name</th>
<th>Restrictions</th>
<th>Task Priority</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACPI Table Protocol</td>
<td>&lt;</td>
<td>TPL_NOTIFY</td>
</tr>
<tr>
<td>ARP</td>
<td>&lt;=</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>ARP Service Binding</td>
<td>&lt;=</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Authentication Info</td>
<td>&lt;=</td>
<td>TPL_NOTIFY</td>
</tr>
<tr>
<td>Block I/O Protocol</td>
<td>&lt;=</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Block I/O 2 Protocol</td>
<td>&lt;=</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Bluetooth Host</td>
<td>&lt;=</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Bluetooth Host Controller</td>
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<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Bluetooth IO Service Binding</td>
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<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Bluetooth IO</td>
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</tr>
<tr>
<td>Bluetooth Attribute</td>
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</tr>
<tr>
<td>Bluetooth Configuration</td>
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<tr>
<td>BluetoothLE Configuration</td>
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</tr>
<tr>
<td>CheckEvent()</td>
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<td>TPL_HIGH_LEVEL</td>
</tr>
<tr>
<td>CloseEvent()</td>
<td>&lt;</td>
<td>TPL_HIGH_LEVEL</td>
</tr>
<tr>
<td>CreateEvent()</td>
<td>&lt;</td>
<td>TPL_HIGH_LEVEL</td>
</tr>
<tr>
<td>Deferred Image Load Protocol</td>
<td>&lt;=</td>
<td>TPL_NOTIFY</td>
</tr>
<tr>
<td>Device Path Utilities</td>
<td>&lt;=</td>
<td>TPL_NOTIFY</td>
</tr>
<tr>
<td>Device Path From Text</td>
<td>&lt;=</td>
<td>TPL_NOTIFY</td>
</tr>
<tr>
<td>DHCP4 Service Binding</td>
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<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>DHCP4</td>
<td>&lt;=</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>DHCP6</td>
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<tr>
<td>DHCP6 Service Binding</td>
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</tr>
<tr>
<td>Disk I/O Protocol</td>
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<td>Disk I/O 2 Protocol</td>
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<tr>
<td>DNS4 Service Binding</td>
<td>&lt;=</td>
<td>TPL_CALLBACK</td>
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</table>

continues on next page
<table>
<thead>
<tr>
<th>Protocol/Service</th>
<th>Event Priority</th>
</tr>
</thead>
<tbody>
<tr>
<td>DNS4</td>
<td>TPL_CALLBACK</td>
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<td>DNS6 Service Binding</td>
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<td>DNS6</td>
<td>TPL_CALLBACK</td>
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<tr>
<td>Driver Health</td>
<td>TPL_NOTIFY</td>
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<td>EAP</td>
<td>TPL_CALLBACK</td>
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<td>EAP Configuration</td>
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<td>EAP Management</td>
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<tr>
<td>EAP Management2</td>
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<td>EDID Active</td>
<td>TPL_NOTIFY</td>
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<td>EDID Discovered</td>
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<td>EFI_SIMPLE_TEXT_INPUT_PROTOCOL</td>
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<td>EFI_SIMPLE_TEXT_INPUT_PROTOCOL.ReadKeyStroke</td>
<td>TPL_APPLICATION</td>
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<td>EFI_SIMPLE_TEXT_INPUT_PROTOCOL.Reset</td>
<td>TPL_APPLICATION</td>
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<tr>
<td>EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL</td>
<td>TPL_CALLBACK</td>
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<tr>
<td>EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.ReadKeyStrokeEx</td>
<td>TPL_APPLICATION</td>
</tr>
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<td>EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.Reset</td>
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<tr>
<td>Event Notification Levels</td>
<td>TPL_APPLICATION</td>
</tr>
<tr>
<td>Event Notification Levels</td>
<td>TPL_HIGH_LEVEL</td>
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<tr>
<td>Exit()</td>
<td>TPL_CALLBACK</td>
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<td>ExitBootServices()</td>
<td>TPL_APPLICATION</td>
</tr>
<tr>
<td>Form Browser2 Protocol/SendForm</td>
<td>TPL_APPLICATION</td>
</tr>
<tr>
<td>FTP</td>
<td>TPL_CALLBACK</td>
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<td>Graphics Output EDID Override</td>
<td>TPL_NOTIFY</td>
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<tr>
<td>HII Protocols</td>
<td>TPL_NOTIFY</td>
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<td>HTTP Service Binding</td>
<td>TPL_CALLBACK</td>
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<td>HTTP Utilities</td>
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<td>IP4 Service Binding</td>
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<td>TPL_CALLBACK</td>
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<tr>
<td>IPSec Configuration</td>
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<td>iSCSI Initiator Name</td>
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<td>LoadImage()</td>
<td>TPL_CALLBACK</td>
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<tr>
<td>Managed Network Service Binding</td>
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<tr>
<td>Memory Allocation Services</td>
<td>TPL_NOTIFY</td>
</tr>
<tr>
<td>MTFTP4 Service Binding</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>MTFTP4</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>MTFTP6</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>MTFTP6 Service Binding</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>PXE Base Code Protocol</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Protocol Handler Services</td>
<td>TPL_NOTIFY</td>
</tr>
<tr>
<td>REST</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Serial I/O Protocol</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>SetTimer()</td>
<td>TPL_HIGH_LEVEL</td>
</tr>
<tr>
<td>SignalEvent()</td>
<td>TPL_HIGH_LEVEL</td>
</tr>
</tbody>
</table>

continues on next page
Table 7.3 – continued from previous page

<table>
<thead>
<tr>
<th>Protocol</th>
<th>Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>Simple File System Protocol</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Simple Network Protocol</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Simple Text Output Protocol</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Stall()</td>
<td>TPL_HIGH_LEVEL</td>
</tr>
<tr>
<td>StartImage()</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Supplicant</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Tape IO</td>
<td>TPL_NOTIFY</td>
</tr>
<tr>
<td>TCP4 Service Binding</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>TCP4</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>TCP6</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>TCP6 Service Binding</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Time Services</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>TLS Service Binding</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>TLS</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>TLS Configuration</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>UDP4 Service Binding</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>UDP4</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>UDP6</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>UDP6 Service Binding</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>UnloadImage()</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>User Manager Protocol</td>
<td>TPL_NOTIFY</td>
</tr>
<tr>
<td>User Manager Protocol/Identify()</td>
<td>TPL_APPLICATION</td>
</tr>
<tr>
<td>User Credential Protocol</td>
<td>TPL_NOTIFY</td>
</tr>
<tr>
<td>User Info Protocol</td>
<td>TPL_NOTIFY</td>
</tr>
<tr>
<td>Variable Services</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>VLAN Configuration</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>WaitForEvent()</td>
<td>TPL_APPLICATION</td>
</tr>
<tr>
<td>Wireless MAC Connection</td>
<td>TPL_CALLBACK</td>
</tr>
<tr>
<td>Other protocols and services, if not listed above</td>
<td>TPL_NOTIFY</td>
</tr>
</tbody>
</table>

7.1.1 EFI_BOOT_SERVICES.CreateEvent()

Summary
Creates an event.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI * EFI_CREATE_EVENT) (  
    IN UINT32 Type,  
    IN EFI_TPL NotifyTpl,  
    IN EFI_EVENT_NOTIFY NotifyFunction, OPTIONAL  
    IN VOID *NotifyContext, OPTIONAL  
    OUT EFI_EVENT *Event  
);
```

Parameters

Type
The type of event to create and its mode and attributes. The #define statements in “Related Definitions” can be used to specify an event’s mode and attributes.

7.1. Event, Timer, and Task Priority Services
NotifyTpl
The task priority level of event notifications, if needed. See `EFI_BOOT_SERVICES.RaiseTPL()`.

NotifyFunction
Pointer to the event’s notification function, if any. See “Related Definitions.”

NotifyContext
Pointer to the notification function’s context; corresponds to parameter `Context` in the notification function.

Event
Pointer to the newly created event if the call succeeds; undefined otherwise.

Related Definitions

```c
//*******************************************************************************
// EFI_EVENT
//*******************************************************************************
typedef VOID *EFI_EVENT

// Event Types
//*******************************************************************************
// These types can be "ORed" together as needed - for example, 
// EVT_TIMER might be "Ored" with EVT_NOTIFY_WAIT or 
// EVT_NOTIFY_SIGNAL.
#define EVT_TIMER 0x80000000
#define EVT_RUNTIME 0x40000000
#define EVT_NOTIFY_WAIT 0x00000100
#define EVT_NOTIFY_SIGNAL 0x00000200
#define EVT_SIGNAL_EXIT_BOOT_SERVICES 0x00000201
#define EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE 0x60000202
```

EVT_TIMER
The event is a timer event and may be passed to `EFI_BOOT_SERVICES.SetTimer()` . Note that timers only function during boot services time.

EVT_RUNTIME
The event is allocated from runtime memory. If an event is to be signaled after the call to `EFI_BOOT_SERVICES.ExitBootServices()` the event’s data structure and notification function need to be allocated from runtime memory. For more information, see `SetVirtualAddressMap()`.

EVT_NOTIFY_WAIT
If an event of this type is not already in the signaled state, then the event’s NotificationFunction will be queued at the event’s NotifyTpl whenever the event is being waited on via `EFI_BOOT_SERVICES.WaitForEvent()` or `EFI_BOOT_SERVICES.CheckEvent()`.

EVT_NOTIFY_SIGNAL
The event’s NotifyFunction is queued whenever the event is signaled.

EVT_SIGNAL_EXIT_BOOT_SERVICES
This event is of type EVT_NOTIFY_SIGNAL. It should not be combined with any other event types. This event type is functionally equivalent to the EFI_EVENT_GROUP_EXIT_BOOT_SERVICES event group. Refer to EFI_EVENT_GROUP_EXIT_BOOT_SERVICES event group description in `EFI_BOOT_SERVICES.CreateEventEx()` section below for additional details.

EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE
The event is to be notified by the system when SetVirtualAddressMap() is performed. This event type is a
composite of EVT_NOTIFY_SIGNAL, EVT_RUNTIME, and EVT_RUNTIME_CONTEXT and should not be combined with any other event types.

```c
typedef VOID (EFIAPI *EFI_EVENT_NOTIFY) (IN EFI_EVENT Event, IN VOID *Context);
```

**Event**

Event whose notification function is being invoked.

**Context**

Pointer to the notification function’s context, which is implementation-dependent. Context corresponds to NotifyContext in `EFI_BOOT_SERVICES.CreateEventExt()`.

**Description**

The `CreateEvent()` function creates a new event of type `Type` and returns it in the location referenced by `Event`. The event’s notification function, context, and task priority level are specified by `NotifyFunction`, `NotifyContext`, and `NotifyTpl`, respectively.

Events exist in one of two states, “waiting” or “signaled.” When an event is created, firmware puts it in the “waiting” state. When the event is signaled, firmware changes its state to “signaled” and, if `EVT_NOTIFY_SIGNAL` is specified, places a call to its notification function in a FIFO queue. There is a queue for each of the “basic” task priority levels defined in `Event, Timer, and Task Priority Services` (`TPL_CALLBACK` and `TPL_NOTIFY`). The functions in these queues are invoked in FIFO order, starting with the highest priority level queue and proceeding to the lowest priority queue that is unmasked by the current TPL. If the current TPL is equal to or greater than the queued notification, it will wait until the TPL is lowered via `EFI_BOOT_SERVICES.RestoreTPL()`.

In a general sense, there are two “types” of events, synchronous and asynchronous. Asynchronous events are closely related to timers and are used to support periodic or timed interruption of program execution. This capability is typically used with device drivers. For example, a network device driver that needs to poll for the presence of new packets could create an event whose type includes `EVT_TIMER` and then call the `EFI_BOOT_SERVICES.SetTimer()` function. When the timer expires, the firmware signals the event.

Synchronous events have no particular relationship to timers. Instead, they are used to ensure that certain activities occur following a call to a specific interface function. One example of this is the cleanup that needs to be performed in response to a call to the `EFI_BOOT_SERVICES.ExitBootServices()` function. `ExitBootServices()` can clean up the firmware since it understands firmware internals, but it cannot clean up on behalf of drivers that have been loaded into the system. The drivers have to do that themselves by creating an event whose type is `EVT_SIGNAL_EXIT_BOOT_SERVICES` and whose notification function is a function within the driver itself. Then, when `ExitBootServices()` has finished its cleanup, it signals each event of type `EVT_SIGNAL_EXIT_BOOT_SERVICES`.

Another example of the use of synchronous events occurs when an event of type `EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE` is used in conjunction with the `SetVirtualAddressMap()`.

The `EVT_NOTIFY_WAIT` and `EVT_NOTIFY_SIGNAL` flags are exclusive. If neither flag is specified, the caller does not require any notification concerning the event and the `NotifyTpl`, `NotifyFunction`, and `NotifyContext` parameters are ignored. If `EVT_NOTIFY_WAIT` is specified and the event is not in the signaled state, then the `EVT_NOTIFY_WAIT` notify function is queued whenever a consumer of the event is waiting for the event (via `EFI_BOOT_SERVICES.WaitForEvent()` or `EFI_BOOT_SERVICES.CheckEvent()`). If the `EVT_NOTIFY_SIGNAL` flag is specified then the event’s notify function is queued whenever the event is signaled.

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NOTE: Because its internal structure is unknown to the caller, Event cannot be modified by the caller. The only way to manipulate it is to use the published event interfaces.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The event structure was created.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One of the parameters has an invalid value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Event is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Type has an unsupported bit set.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Type has both EVT_NOTIFY_SIGNAL and EVT_NOTIFY_WAIT set.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Type has either EVT_NOTIFY_SIGNAL or EVT_NOTIFY_WAIT set and NotifyFunction is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Type has either EVT_NOTIFY_SIGNAL or EVT_NOTIFY_WAIT set and NotifyTpl is not a supported TPL level.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The event could not be allocated.</td>
</tr>
</tbody>
</table>

7.1.2 EFI_BOOT_SERVICES.CreateEventEx()

Summary
Creates an event in a group.

Prototype

typedef

EFI_STATUS

(EIFIAP *EFI_CREATE_EVENT_EX) ( |
    IN UINT32 Type,
    IN EFI_TPL NotifyTpl,
    IN EFI_EVENT_NOTIFY NotifyFunction OPTIONAL,
    IN CONST VOID *NotifyContext OPTIONAL,
    IN CONST EFI_GUID *EventGroup OPTIONAL,
    OUT EFI_EVENT *Event |
);

Parameters

Type
The type of event to create and its mode and attributes.

NotifyTpl
The task priority level of event notifications, if needed. See EFI_BOOT_SERVICES.RaiseTPL().

NotifyFunction
Pointer to the event’s notification function, if any.

NotifyContext
Pointer to the notification function’s context; corresponds to parameter Context in the notification function.

EventGroup
Pointer to the unique identifier of the group to which this event belongs. If this is NULL, then the function behaves as if the parameters were passed to CreateEvent.

Event
Pointer to the newly created event if the call succeeds; undefined otherwise.

Description

7.1. Event, Timer, and Task Priority Services
The CreateEventEx function creates a new event of type Type and returns it in the specified location indicated by Event. The event’s notification function, context and task priority are specified by NotifyFunction, NotifyContext, and NotifyTpl, respectively. The event will be added to the group of events identified by EventGroup.

If no group is specified by EventGroup, then this function behaves as if the same parameters had been passed to CreateEvent.

Event groups are collections of events identified by a shared EFI_GUID where, when one member event is signaled, all other events are signaled and their individual notification actions are taken (as described in CreateEvent). All events are guaranteed to be signaled before the first notification action is taken. All notification functions will be executed in the order specified by their NotifyTpl.

A single event can only be part of a single event group. An event may be removed from an event group by using CloseEvent.

The Type of an event uses the same values as defined in CreateEvent except that EVT_SIGNAL_EXIT_BOOT_SERVICES and EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE are not valid.

If Type has EVT_NOTIFY_SIGNAL or EVT_NOTIFY_WAIT, then NotifyFunction must be non-NULL and NotifyTpl must be a valid task priority level. Otherwise these parameters are ignored.

More than one event of type EVT_TIMER may be part of a single event group. However, there is no mechanism for determining which of the timers was signaled.

Configuration Table Groups
The GUID for a configuration table also defines a corresponding event group GUID with the same value. If the data represented by a configuration table is changed, InstallConfigurationTable() should be called. When InstallConfigurationTable() is called, the corresponding event is signaled. When this event is signaled, any components that cache information from the configuration table can optionally update their cached state.

For example, EFI_ACPI_TABLE_GUID defines a configuration table for ACPI data. When ACPI data is changed, InstallConfigurationTable() is called. During the execution of InstallConfigurationTable(), a corresponding event group with EFI_ACPI_TABLE_GUID is signaled, allowing an application to invalidate any cached ACPI data.

Pre-Defined Event Groups
This section describes the pre-defined event groups used by the UEFI specification.

EFI_EVENT_GROUP_EXIT_BOOT_SERVICES
This event group is notified by the system when ExitBootServices() is invoked after notifying EFI_EVENT_GROUP_BEFORE_EXIT_BOOT_SERVICES event group. This event group is functionally equivalent to the EVT_SIGNAL_EXIT_BOOT_SERVICES flag for the Type argument of CreateEvent. The notification function for this event must comply with the following requirements:

- The notification function is not allowed to use the Memory Allocation Services, or call any functions that use the Memory Allocation Services, because these services modify the current memory map.

Note: Since consumer of the service does not necessarily knows if the service uses memory allocation services, this requirement is effectively a mandate to reduce usage of any external services (services implemented outside of the driver owning the notification function) to an absolute minimum required to perform an orderly transition to a runtime environment. Usage of the external services may yield unexpected results. Since UEFI specification does not guarantee any given order of notification function invocation, a notification function consuming the service may be invoked before or after the notification function of the driver providing the service. As a result, a service being called by the notification function may exhibit boot time behavior or a runtime behavior (which is undefined for a pure boot services).

- The notification function must not depend on timer events since timer services will be deactivated before any notification functions are called.

Refer to EFI_BOOT_SERVICES.ExitBootServices() below for additional details.

EFI_EVENT_GROUP_BEFORE_EXIT_BOOT_SERVICES
This event group is notified by the system ExitBootServices() is invoked right before notifying EFI_EVENT_GROUP_EXIT_BOOT_SERVICES event group. The event presents the last opportunity to use firmware interfaces in the boot environment.

The notification function for this event must not depend on any kind of delayed processing (processing that happens in a timer callback beyond the time span of the notification function) because system firmware deactivates timer services right after dispatching handlers for this event group.

Refer to EFI_BOOT_SERVICES.ExitBootServices() below for additional details.

**EFI_EVENT_GROUP_VIRTUAL_ADDRESS_CHANGE**

This event group is notified by the system when SetVirtualAddressMap() is invoked. This is functionally equivalent to the VT_SIGNAL_VIRTUAL_ADDRESS_CHANGE flag for the *Type* argument of CreateEvent.

**EFI_EVENT_GROUP_MEMORY_MAP_CHANGE**

This event group is notified by the system when the memory map has changed. The notification function for this event should not use Memory Allocation Services to avoid reentrancy complications.

**EFI_EVENT_GROUP_READY_TO_BOOT**

This event group is notified by the system right before notifying EFI_EVENT_GROUP_AFTER_READY_TO_BOOT event group when the Boot Manager is about to load and execute a boot option or a platform or OS recovery option. The event group presents the last chance to modify device or system configuration prior to passing control to a boot option.

**EFI_EVENT_GROUP_AFTER_READY_TO_BOOT**

This event group is notified by the system immediately after notifying EFI_EVENT_GROUP_READY_TO_BOOT event group when the Boot Manager is about to load and execute a boot option or a platform or OS recovery option. The event group presents the last chance to survey device or system configuration prior to passing control to a boot option.

**EFI_EVENT_GROUP_RESET_SYSTEM**

This event group is notified by the system when ResetSystem() is invoked and the system is about to be reset. The event group is only notified prior to ExitBootServices() invocation.

**Related Definitions**

*EVT_SIGNAL_EXIT_BOOT_SERVICE* and *EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE* are defined in *CreateEvent*.

```c
#define EFI_EVENT_GROUP_EXIT_BOOT_SERVICES \
{0x27abf055, 0xb1b8, 0x4c26, 0x80, 0x48, 0x74, 0x37, \n 0xba, 0xa2, 0xdf}\n
#define EFI_EVENT_GROUP_BEFORE_EXIT_BOOT_SERVICES \
 { 0x8be0e274, 0x3970, 0x4b44, { 0x80, 0xc5, 0x1a, 0xb9, 0x50, 0x2f, 0x3b, 0xfc } }\n
#define EFI_EVENT_GROUP_VIRTUAL_ADDRESS_CHANGE \
{0x13fa7698, 0xc831, 0x49c7, 0x87, 0xea, 0x8f, 0x43, \n 0xc2, 0x51, 0x96}\n
#define EFI_EVENT_GROUP_MEMORY_MAP_CHANGE \
{0x78bee926, 0x692f, 0x48fd, 0x9e, 0xdb, 0x1, 0x42, 0x2e, \n 0xf0, 0xd7, 0xab}\n```

(continues on next page)
#define EFI_EVENT_GROUP_READY_TO_BOOT
{0x7ce88fb3, 0x4bd7, 0x4679, 0x87, 0xa8, 0xa8, 0xd8, 0xde,
0xe5,0xd, 0x2b}
define EFI_EVENT_GROUP_AFTER_READY_TO_BOOT
{ 0x3a2a00ad, 0x98b9, 0x4cdf, { 0xa4, 0x78, 0x70, 0x27, 0x77,
0xf1, 0xc1, 0xb } }
#define EFI_EVENT_GROUP_RESET_SYSTEM
{ 0x62da6a56, 0x13fb, 0x485a, { 0xa8, 0xda, 0xa3, 0xdd, 0x79, 0x12, 0xcb, 0x6b
}

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The event structure was created.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One of the parameters has an invalid value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Event is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Type has an unsupported bit set.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Type has both EVT_NOTIFY_SIGNAL and EVT_NOTIFY_WAIT set.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Type has either EVT_NOTIFY_SIGNAL or EVT_NOTIFY_WAIT set and NotifyFunction is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Type has either EVT_NOTIFY_SIGNAL or EVT_NOTIFY_WAIT set and NotifyTpl is not a supported TPL level.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The event could not be allocated.</td>
</tr>
</tbody>
</table>

7.1.3 EFI_BOOT_SERVICES.CloseEvent()

Summary
Closes an event.

Prototype

typedef EFI_STATUS
(EIFIAPI *EFI_CLOSE_EVENT) (IN EFI_EVENT Event);

Parameters

Event
The event to close. Type EFI_EVENT is defined in the CreateEvent() function description.

Description
The CloseEvent() function removes the caller’s reference to the event, removes it from any event group to which it belongs, and closes it. Once the event is closed, the event is no longer valid and may not be used on any subsequent function calls. If Event was registered with RegisterProtocolNotify() then CloseEvent() will remove the corresponding registration. It is safe to call CloseEvent() within the corresponding notify function.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The event has been closed.</td>
</tr>
</tbody>
</table>
7.1.4 EFI_BOOT_SERVICES.SignalEvent()

Summary
Signals an event.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_SIGNAL_EVENT)(
    IN EFI_EVENT Event
);
```

Parameters

Event
The event to signal. Type EFI_EVENT is defined in the EFI_BOOT_SERVICES.CheckEvent() function description.

Description

The supplied Event is placed in the signaled state. If Event is already in the signaled state, then EFI_SUCCESS is returned. If Event is of type EVT_NOTIFY_SIGNAL, then the event’s notification function is scheduled to be invoked at the event’s notification task priority level. SignalEvent() may be invoked from any task priority level.

If the supplied Event is a part of an event group, then all of the events in the event group are also signaled and their notification functions are scheduled.

When signaling an event group, it is possible to create an event in the group, signal it and then close the event to remove it from the group. For example:

```c
EFI_EVENT Event;
EFI_GUID gMyEventGroupGuid = EFI_MY_EVENT_GROUP_GUID;
gBS->CreateEventEx (0,
    0,
    NULL,
    NULL,
    &gMyEventGroupGuid,
    &Event
);

gBS->SignalEvent (Event);
gBS->CloseEvent (Event);
```

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The event was signaled.</td>
</tr>
</tbody>
</table>
7.1.5 EFI_BOOT_SERVICES.WaitForEvent()

Summary
Stops execution until an event is signaled.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_WAIT_FOR_EVENT) (
    IN UINTN NumberOfEvents,
    IN EFI_EVENT *Event,
    OUT UINTN *Index
);

Parameters

NumberOfEvents
The number of events in the Event array.

Event
An array of EFI_EVENT. Type EFI_EVENT is defined in UEFI Forum, Inc. March 2021 148
EFI_BOOT_SERVICES.CreateEvent() function description.

Index
Pointer to the index of the event which satisfied the wait condition.

Description
This function must be called at priority level TPL_APPLICATION. If an attempt is made to call it at any other priority level, EFI_UNSUPPORTED is returned.

The list of events in the Event array are evaluated in order from first to last, and this evaluation is repeated until an event is signaled or an error is detected. The following checks are performed on each event in the Event array.

• If an event is of type EVT_NOTIFY_SIGNAL, then EFI_INVALID_PARAMETER is returned and Index indicates the event that caused the failure.

• If an event is in the signaled state, the signaled state is cleared and EFI_SUCCESS is returned, and Index indicates the event that was signaled.

• If an event is not in the signaled state but does have a notification function, the notification function is queued at the event’s notification task priority level. If the execution of the event’s notification function causes the event to be signaled, then the signaled state is cleared, EFI_SUCCESS is returned, and Index indicates the event that was signaled.

To wait for a specified time, a timer event must be included in the Event array.

To check if an event is signaled without waiting, an already signaled event can be used as the last event in the list being checked, or the CheckEvent() interface may be used.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The event indicated by Index was signaled.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>NumberOfEvents is 0.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The event indicated by Index is of type EVT_NOTIFY_SIGNAL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The current TPL is not TPL_APPLICATION.</td>
</tr>
</tbody>
</table>

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7.1.6 EFI_BOOT_SERVICES.CheckEvent()

**Summary**
Checks whether an event is in the signaled state.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_CHECK_EVENT) (
    IN EFI_EVENT Event
);
```

**Parameters**

**Event**
The event to check. Type EFI_EVENT is defined in the CreateEvent() function description.

**Description**
The CheckEvent() function checks to see whether Event is in the signaled state. If Event is of type EVT_NOTIFY_SIGNAL, then EFI_INVALID_PARAMETER is returned. Otherwise, there are three possibilities:

- If Event is in the signaled state, it is cleared and EFI_SUCCESS is returned.
- If Event is not in the signaled state and has no notification function, EFI_NOT_READY is returned.
- If Event is not in the signaled state but does have a notification function, the notification function is queued at the event's notification task priority level. If the execution of the notification function causes Event to be signaled, then the signaled state is cleared and EFI_SUCCESS is returned; if the Event is not signaled, then EFI_NOT_READY is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The event is in the signaled state.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The event is not in the signaled state.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Event is of type EVT_NOTIFY_SIGNAL.</td>
</tr>
</tbody>
</table>

7.1.7 EFI_BOOT_SERVICES.SetTimer()

**Summary**
Sets the type of timer and the trigger time for a timer event.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_SET_TIMER) (
    IN EFI_EVENT Event,
    IN EFI_TIMER_DELAY Type,
    IN UINT64 TriggerTime
);
```

**Parameters**

7.1. Event, Timer, and Task Priority Services
Event
The timer event that is to be signaled at the specified time. Type EFI_EVENT is defined in the CreateEvent() function description.

Type
The type of time that is specified in TriggerTime. See the timer delay types in “Related Definitions.”

TriggerTime
The number of 100ns units until the timer expires. A TriggerTime of 0 is legal. If Type is TimerRelative and TriggerTime is 0, then the timer event will be signaled on the next timer tick. If Type is TimerPeriodic and TriggerTime is 0, then the timer event will be signaled on every timer tick.

Related Definitions

```c
typedef enum {
    TimerCancel,
    TimerPeriodic,
    TimerRelative
} EFI_TIMER_DELAY;
```

TimerCancel
The event’s timer setting is to be cancelled and no timer trigger is to be set. TriggerTime is ignored when canceling a timer.

TimerPeriodic
The event is to be signaled periodically at TriggerTime intervals from the current time. This is the only timer trigger Type for which the event timer does not need to be reset for each notification. All other timer trigger types are “one shot.”

TimerRelative
The event is to be signaled in TriggerTime 100ns units.

Description
The SetTimer() function cancels any previous time trigger setting for the event, and sets the new trigger time for the event. This function can only be used on events of type EVT_TIMER.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The event has been set to be signaled at the requested time.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Event or Type is not valid.</td>
</tr>
</tbody>
</table>

7.1.8 EFI_BOOT_SERVICES.RaiseTPL()

Summary
Raises a task’s priority level and returns its previous level.

Prototype

```c
typedef EFI_TPL (EFIAPIC *EFI_RAISE_TPL) ( (continues on next page)```
Parameters

NewTpl

The new task priority level. It must be greater than or equal to the current task priority level. See “Related Definitions.”

Related Definitions

```c
typedef UINTN EFI_TPL

#define TPL_APPLICATION 4
#define TPL_CALLBACK 8
#define TPL_NOTIFY 16
#define TPL_HIGH_LEVEL 31
```

Description

This function raises the priority of the currently executing task and returns its previous priority level.

Only three task priority levels are exposed outside of the firmware during boot services execution. The first is TPL_APPLICATION where all normal execution occurs. That level may be interrupted to perform various asynchronous interrupt style notifications, which occur at the TPL_CALLBACK or TPL_NOTIFY level. By raising the task priority level to TPL_NOTIFY such notifications are masked until the task priority level is restored, thereby synchronizing execution with such notifications. Synchronous blocking I/O functions execute at TPL_NOTIFY. TPL_CALLBACK is the typically used for application level notification functions. Device drivers will typically use TPL_CALLBACK or TPL_NOTIFY for their notification functions. Applications and drivers may also use TPL_NOTIFY to protect data structures in critical sections of code.

The caller must restore the task priority level with `EFI_BOOT_SERVICES.RestoreTPL()` to the previous level before returning.

**NOTE:** If NewTpl is below the current TPL level, then the system behavior is indeterminate. Additionally, only TPL_APPLICATION, TPL_CALLBACK, TPL_NOTIFY `<Services\%20Boot\%20Services.htm#TPL_NOTIFY>`__, and TPL_HIGH_LEVEL may be used. All other values are reserved for use by the firmware; using them will result in unpredictable behavior. Good coding practice dictates that all code should execute at its lowest possible TPL level, and the use of TPL levels above TPL_APPLICATION must be minimized. Executing at TPL levels above TPL_APPLICATION for extended periods of time may also result in unpredictable behavior.

Status Codes Returned

Unlike other UEFI interface functions, `EFI_BOOT_SERVICES.RaiseTPL()` does not return a status code. Instead, it returns the previous task priority level, which is to be restored later with a matching call to RestoreTPL().

7.1. Event, Timer, and Task Priority Services 151
7.1.9 EFI_BOOT_SERVICES.RestoreTPL()

Summary
Restores a task’s priority level to its previous value.

Prototype

```c
typedef VOID (EFIAPI *EFI_RESTORE_TPL) (IN EFI_TPL OldTpl);
```

Parameters

**OldTpl**
The previous task priority level to restore (the value from a previous, matching call to **EFI_BOOT_SERVICES.RaiseTPL()**. Type **EFI_TPL** is defined in the **RaiseTPL()** function description.

Description

The **RestoreTPL()** function restores a task’s priority level to its previous value. Calls to **RestoreTPL()** are matched with calls to **RaiseTPL()**.

**NOTE:** If **OldTpl** is above the current **TPL** level, then the system behavior is indeterminate. Additionally, only **TPL_APPLICATION**, **TPL_CALLBACK**, **TPL_NOTIFY**, and **TPL_HIGH_LEVEL** may be used. All other values are reserved for use by the firmware; using them will result in unpredictable behavior. Good coding practice dictates that all code should execute at its lowest possible **TPL** level, and the use of **TPL** levels above **TPL_APPLICATION** must be minimized. Executing at **TPL** levels above **TPL_APPLICATION** for extended periods of time may also result in unpredictable behavior.

Status Codes Returned

None.

7.2 Memory Allocation Services

The functions that make up Memory Allocation Services are used during preboot to allocate and free memory, and to obtain the system’s memory map, below, **Memory Allocation Functions**.

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AllocatePages</td>
<td>Boot</td>
<td>Allocates pages of a particular type.</td>
</tr>
<tr>
<td>FreePages</td>
<td>Boot</td>
<td>Frees allocated pages.</td>
</tr>
<tr>
<td>GetMemoryMap</td>
<td>Boot</td>
<td>Returns the current boot services memory map and memory map key.</td>
</tr>
<tr>
<td>AllocatePool</td>
<td>Boot</td>
<td>Allocates a pool of a particular type</td>
</tr>
<tr>
<td>FreePool</td>
<td>Boot</td>
<td>Frees allocated pool.</td>
</tr>
</tbody>
</table>

The way in which these functions are used is directly related to an important feature of UEFI memory design. This feature, which stipulates that EFI firmware owns the system’s memory map during preboot, has three major consequences:

- During preboot, all components (including executing EFI images) must cooperate with the firmware by allocating and freeing memory from the system with the functions **EFI_BOOT_SERVICES.AllocatePages()**, **EFI_BOOT_SERVICES.AllocatePool()**, **EFI_BOOT_SERVICES.FreePages()**, and
The firmware dynamically maintains the memory map as these functions are called.

- During preboot, an executing EFI Image must only use the memory it has allocated.
- Before an executing EFI image exits and returns control to the firmware, it must free all resources it has explicitly allocated. This includes all memory pages, pool allocations, open file handles, etc. Memory allocated by the firmware to load an image is freed by the firmware when the image is unloaded.

This specification describes numerous memory buffers that are allocated by a service, where it is the caller’s responsibility to free the allocated memory. Unless stated otherwise in this specification, it is assumed that such memory buffers are allocated with AllocatePool() and freed with FreePool().

When memory is allocated, it is “typed” according to the values in EFI_MEMORY_TYPE (see the description for EFI_BOOT_SERVICES.AllocatePages()). Some of the types have a different usage before EFI_BOOT_SERVICES.ExitBootServices() is called than they do afterwards. See Table, below, Memory Type Usage before ExitBootServices() lists each type and its usage before the call; See Table Memory Type Usage after ExitBootServices() lists each type and its usage after the call. The system firmware must follow the processor-specific rules outlined in IA-32 Platforms and x64 Platforms in the layout of the EFI memory map to enable the OS to make the required virtual mappings.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EfiReservedMemoryType</td>
<td>Not usable.</td>
</tr>
<tr>
<td>EfiLoaderCode</td>
<td>The code portions of a loaded UEFI application.</td>
</tr>
<tr>
<td>EfiLoaderData</td>
<td>The data portions of a loaded UEFI application and the default data allocation type used by a UEFI application to allocate pool memory.</td>
</tr>
<tr>
<td>EfiBootServicesCode</td>
<td>The code portions of a loaded UEFI Boot Service Driver.</td>
</tr>
<tr>
<td>EfiBootServicesData</td>
<td>The data portions of a loaded UEFI Boot Serve Driver, and the default data allocation type used by a UEFI Boot Service Driver to allocate pool memory.</td>
</tr>
<tr>
<td>EfiRuntimeServicesCode</td>
<td>The code portions of a loaded UEFI Runtime Driver.</td>
</tr>
<tr>
<td>EfiRuntimeServicesData</td>
<td>The data portions of a loaded UEFI Runtime Driver and the default data allocation type used by a UEFI Runtime Driver to allocate pool memory.</td>
</tr>
<tr>
<td>EfiConventionalMemory</td>
<td>Free (unallocated) memory.</td>
</tr>
<tr>
<td>EfiUnusableMemory</td>
<td>Memory in which errors have been detected.</td>
</tr>
<tr>
<td>EfiACPIReclaimMemory</td>
<td>Memory that holds the ACPI tables.</td>
</tr>
<tr>
<td>EfiACPIMemoryNVS</td>
<td>Address space reserved for use by the firmware.</td>
</tr>
<tr>
<td>EfiMemoryMappedIO</td>
<td>Used by system firmware to request that a memory-mapped IO region be mapped by the OS to a virtual address so it can be accessed by EFI runtime services.</td>
</tr>
<tr>
<td>EfiMemoryMappedIOPortSpace</td>
<td>System memory-mapped IO region that is used to translate memory cycles to IO cycles by the processor.</td>
</tr>
<tr>
<td>EfiPalCode</td>
<td>Address space reserved by the firmware for code that is part of the processor.</td>
</tr>
<tr>
<td>EfiPersistentMemory</td>
<td>A memory region that operates as EfiConventionalMemory. However, it happens to also support byte-addressable non-volatility.</td>
</tr>
<tr>
<td>EfiUnacceptedMemoryType</td>
<td>A memory region that represents unaccepted memory, that must be accepted by the boot target before it can be used. Unless otherwise noted, all other EFI memory types are accepted. For platforms that support unaccepted memory, all unaccepted valid memory will be reported as unaccepted in the memory map. Unreported physical address ranges must be treated as not-present memory.</td>
</tr>
</tbody>
</table>

**Note:** There is only one region of type EfiMemoryMappedIOPortSpace defined in the architecture for Itanium-based platforms. As a result, there should be one and only one region of type EfiMemoryMappedIOPortSpace in the EFI memory map of an Itanium-based platform.
Table 7.10: Memory Type Usage after ExitBootServices()

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EfiReservedMemoryType</td>
<td>Not usable.</td>
</tr>
<tr>
<td>EfiLoaderCode</td>
<td>The UEFI OS Loader and/or OS may use this memory as they see fit. Note: the UEFI OS loader that called EFI_BOOT_SERVICES.ExitBootServices() is utilizing one or more EfiLoaderCode ranges.</td>
</tr>
<tr>
<td>EfiLoaderData</td>
<td>The Loader and/or OS may use this memory as they see fit. Note: the OS loader that called ExitBootServices() is utilizing one or more EfiLoaderData ranges.</td>
</tr>
<tr>
<td>EfiBootServicesCode</td>
<td>Memory available for general use.</td>
</tr>
<tr>
<td>EfiBootServicesData</td>
<td>Memory available for general use.</td>
</tr>
<tr>
<td>EfiRuntimeServicesCode</td>
<td>The memory in this range is to be preserved by the UEFI OS loader and OS in the working and ACPI S1-S3 states.</td>
</tr>
<tr>
<td>EfiRuntimeServicesData</td>
<td>The memory in this range is to be preserved by the UEFI OS Loader and OS in the working and ACPI S1-S3 states.</td>
</tr>
<tr>
<td>EfiConventionalMemory</td>
<td>Memory available for general use.</td>
</tr>
<tr>
<td>EfiUnusableMemory</td>
<td>Memory that contains errors and is not to be used.</td>
</tr>
<tr>
<td>EfiACPIReclaimMemory</td>
<td>This memory is to be preserved by the UEFI OS loader and OS until ACPI is enabled. Once ACPI is enabled, the memory in this range is available for general use.</td>
</tr>
<tr>
<td>EfiACPIMemoryNVS</td>
<td>This memory is to be preserved by the UEFI OS loader and OS in the working and ACPI S1-S3 states.</td>
</tr>
<tr>
<td>EfiMemoryMappedIO</td>
<td>This memory is not used by the OS. All system memory-mapped IO information should come from ACPI tables.</td>
</tr>
<tr>
<td>EfiMemoryMappedIOPortSpace</td>
<td>This memory is not used by the OS. All system memory-mapped IO port space information should come from ACPI tables.</td>
</tr>
<tr>
<td>EfiPalCode</td>
<td>This memory is to be preserved by the UEFI OS loader and OS in the working and ACPI S1-S4 states. This memory may also have other attributes that are defined by the processor implementation.</td>
</tr>
<tr>
<td>EfiPersistentMemory</td>
<td>A memory region that operates as EfiConventionalMemory. However, it happens to also support byte-addressable non-volatility.</td>
</tr>
<tr>
<td>EfiUnacceptedMemoryType</td>
<td>A memory region that represents unaccepted memory, that must be accepted by the boot target before it can be used. Unless otherwise noted, all other EFI memory types are accepted. For platforms that support unaccepted memory, all unaccepted valid memory will be reported as unaccepted in the memory map. Unreported physical address ranges must be treated as not-present memory.</td>
</tr>
</tbody>
</table>

**NOTE:** An image that calls ExitBootServices() (i.e., a UEFI OS Loader) first calls EFI_BOOT_SERVICES.GetMemoryMap() to obtain the current memory map. Following the ExitBootServices() call, the image implicitly owns all unused memory in the map. This includes memory types EfiLoaderCode, EfiLoaderData, EfiBootServicesCode, EfiBootServicesData, and EfiConventionalMemory. A UEFI OS Loader and OS must preserve the memory marked as EfiRuntimeServicesCode and EfiRuntimeServicesData.
### 7.2.1 EFI_BOOT_SERVICES.AllocatePages()

**Summary**

Allocates memory pages from the system.

**Prototype**

```c
typedef
EFI_STATUS
(EIFIAPI  *EFI_ALLOCATE_PAGES) (  
    IN EFI_ALLOCATE_TYPE Type,  
    IN EFI_MEMORY_TYPE MemoryType,  
    IN UINTN Pages,  
    IN OUT EFI_PHYSICAL_ADDRESS *Memory
);
```

**Parameters**

- **Type**
  
  The type of allocation to perform. See “Related Definitions.”

- **MemoryType**
  
  The type of memory to allocate. The type EFI_MEMORY_TYPE is defined in “Related Definitions” below. These memory types are also described in more detail in Memory Type Usage before ExitBootServices(), and Memory Type Usage after ExitBootServices(). Normal allocations (that is, allocations by any UEFI application) are of type EfiLoaderData. MemoryType values in the range 0x70000000..0x7FFFFFFF are reserved for OEM use. MemoryType values in the range 0x80000000..0xFFFFFFFF are reserved for use by UEFI OS loaders that are provided by operating system vendors.

- **Pages**
  
  The number of contiguous 4 KiB pages to allocate.

- **Memory**
  
  Pointer to a physical address. On input, the way in which the address is used depends on the value of Type. See “Description” for more information. On output the address is set to the base of the page range that was allocated. See “Related Definitions.”

**NOTE:** UEFI Applications, UEFI Drivers, and UEFI OS Loaders must not allocate memory of types EfiReservedMemoryType, EfiMemoryMappedIO, and EfiUnacceptedMemoryType.

**Related Definitions**

```c
//*******************************************************************************  
//EFI_ALLOCATE_TYPE  
//*******************************************************************************  
// These types are discussed in the "Description" section below.  
typedef enum {  
    AllocateAnyPages,  
    AllocateMaxAddress,  
    AllocateAddress,  
    MaxAllocateType  
} EFI_ALLOCATE_TYPE;
```
These type values are discussed in Memory Type Usage before ExitBootServices() and Memory Type Usage after ExitBootServices().

typedef enum {
    EfiReservedMemoryType,
    EfiLoaderCode,
    EfiLoaderData,
    EfiBootServicesCode,
    EfiBootServicesData,
    EfiRuntimeServicesCode,
    EfiRuntimeServicesData,
    EfiConventionalMemory,
    EfiUnusableMemory,
    EfiACPIReclaimMemory,
    EfiACPIMemoryNVS,
    EfiMemoryMappedIO,
    EfiMemoryMappedIOPortSpace,
    EfiPalCode,
    EfiPersistentMemory,
    EfiUnacceptedMemoryType,
    EfiMaxMemoryType
} EFI_MEMORY_TYPE;

EFI_PHYSICAL_ADDRESS

typedef UINT64 EFI_PHYSICAL_ADDRESS;

Description

The AllocatePages() function allocates the requested number of pages and returns a pointer to the base address of the page range in the location referenced by Memory. The function scans the memory map to locate free pages. When it finds a physically contiguous block of pages that is large enough and also satisfies the allocation requirements of Type, it changes the memory map to indicate that the pages are now of type MemoryType.

In general, UEFI OS loaders and UEFI applications should allocate memory (and pool) of type EfiLoaderData. UEFI boot service drivers must allocate memory (and pool) of type EfiBootServicesData. UEFI runtime drivers should allocate memory (and pool) of type EfiRuntimeServicesData (although such allocation can only be made during boot services time).

Allocation requests of Type AllocateAnyPages allocate any available range of pages that satisfies the request. On input, the address pointed to by Memory is ignored.

Allocation requests of Type AllocateMaxAddress allocate any available range of pages whose uppermost address is less than or equal to the address pointed to by Memory on input.

Allocation requests of Type AllocateAddress allocate pages at the address pointed to by Memory on input.

NOTE: UEFI drivers and UEFI applications that are not targeted for a specific implementation must perform memory allocations for the following runtime types using AllocateAnyPages address mode:

EfiACPIReclaimMemory,
EfiACPIMemoryNVS,
EfiRuntimeServicesCode,
EfiRuntimeServicesData,
EfiReservedMemoryType.
Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested pages were allocated.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The pages could not be allocated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Type is not AllocateAnyPages or AllocateMaxAddress or AllocateAddress</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>MemoryType is in the range EfiMaxMemoryType..0x6FFFFFFFF.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>MemoryType is EfiPersistentMemoryType or EfiUnacceptedMemory.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Memory is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The requested pages could not be found.</td>
</tr>
</tbody>
</table>

7.2.2 EFI_BOOT_SERVICES.FreePages()

Summary
Frees memory pages.

Prototype

typedef EFI_STATUS
(EFIAPI *EFI_FREE_PAGES) (IN EFI_PHYSICAL_ADDRESS Memory,
IN UINTN Pages);

Parameters
Memory
The base physical address of the pages to be freed. Type EFI_PHYSICAL_ADDRESS is defined in the EFI_BOOT_SERVICES.AllocatePages() function description.

Pages
The number of contiguous 4 KiB pages to free.

Description
The FreePages() function returns memory allocated by AllocatePages() to the firmware.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested memory pages were freed</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The requested memory pages were not allocated with AllocatePages().</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Memory is not a page-aligned address or Pages is invalid.</td>
</tr>
</tbody>
</table>

7.2.3 EFI_BOOT_SERVICES.GetMemoryMap()

Summary
Returns the current memory map.

Prototype

typedef EFI_STATUS
(EFIAPI EFI_GET_MEMORY_MAP) (continues on next page)
IN OUT UINTN *MemoryMapSize,
OUT EFI_MEMORY_DESCRIPTOR *MemoryMap,
OUT UINTN *MapKey,
OUT UINTN *DescriptorSize,
OUT UINT32 *DescriptorVersion
);  

Parameters

MemoryMapSize
A pointer to the size, in bytes, of the MemoryMap buffer. On input, this is the size of the buffer allocated by the caller. On output, it is the size of the buffer returned by the firmware if the buffer was large enough, or the size of the buffer needed to contain the map if the buffer was too small.

MemoryMap
A pointer to the buffer in which firmware places the current memory map. The map is an array of EFI_MEMORY_DESCRIPTORs. See “Related Definitions.”

MapKey
A pointer to the location in which firmware returns the key for the current memory map.

DescriptorSize
A pointer to the location in which firmware returns the size, in bytes, of an individual EFI_MEMORY_DESCRIPTOR.

DescriptorVersion
A pointer to the location in which firmware returns the version number associated with the EFI_MEMORY_DESCRIPTOR. See “Related Definitions.”

Related Definitions

..code-block:

```c
//****************************************************
//EFI_MEMORY_DESCRIPTOR
//****************************************************
typedef struct {
    UINT32 Type;
    EFI_PHYSICAL_ADDRESS PhysicalStart;
    EFI_VIRTUAL_ADDRESS VirtualStart;
    UINT64 NumberOfPages;
    UINT64 Attribute;
} EFI_MEMORY_DESCRIPTOR;
```

Type
Type of the memory region. Type EFI_MEMORY_TYPE is defined in the EFI_BOOT_SERVICES.AllocatePages() function description.

PhysicalStart
Physical address of the first byte in the memory region. PhysicalStart must be aligned on a 4 KiB boundary, and must not be above 0xfffffffffffff000. Type EFI_PHYSICALADDRESS is defined in the AllocatePages() function description.

VirtualStart
Virtual address of the first byte in the memory region. VirtualStart must be aligned on a 4 KiB boundary, and must not be above 0xfffffffffffff000. Type EFI_VIRTUALADDRESS is defined in “Related Definitions.”

7.2. Memory Allocation Services
**NumberOfPages**

Number of 4 KiB pages in the memory region. `NumberOfPages` must not be 0, and must not be any value that would represent a memory page with a start address, either physical or virtual, above 0xfffffffffffff000.

**Attribute**

Attributes of the memory region that describe the bit mask of capabilities for that memory region, and not necessarily the current settings for that memory region. See the following “Memory Attribute Definitions.”

```c
#define EFI_MEMORY_UC 0x0000000000000001
#define EFI_MEMORY_WC 0x0000000000000002
#define EFI_MEMORY_WT 0x0000000000000004
#define EFI_MEMORY_WB 0x0000000000000008
#define EFI_MEMORY_UCE 0x0000000000000010
#define EFI_MEMORY_WP 0x0000000000001000
#define EFI_MEMORY_RP 0x0000000000002000
#define EFI_MEMORY_XP 0x0000000000004000
#define EFI_MEMORY_NV 0x0000000000008000
#define EFI_MEMORY_MORE_RELIABLE 0x0000000000010000
#define EFI_MEMORY_RO 0x0000000000020000
#define EFI_MEMORY_SP 0x0000000000040000
#define EFI_MEMORY_CPU_CRYPTO 0x0000000000080000
#define EFI_MEMORY_RUNTIME 0x8000000000000000
```

**EFI_MEMORY_UC**

Memory cacheability attribute: The memory region supports being configured as not cacheable.

**EFI_MEMORY_WC**

Memory cacheability attribute: The memory region supports being configured as write combining.

**EFI_MEMORY_WT**

Memory cacheability attribute: The memory region supports being configured as cacheable with a “write through” policy. Writes that hit in the cache will also be written to main memory.

**EFI_MEMORY_WB**

Memory cacheability attribute: The memory region supports being configured as cacheable with a “write back” policy. Reads and writes that hit in the cache do not propagate to main memory. Dirty data is written back to main memory when a new cache line is allocated.

**EFI_MEMORY_UCE**

Memory cacheability attribute: The memory region supports being configured as not cacheable, exported, and supports the “fetch and add” semaphore mechanism.

**EFI_MEMORY_WP**

Physical memory protection attribute: The memory region supports being configured as write-protected by system hardware. This is typically used as a cacheability attribute today. The memory region supports being configured as cacheable with a “write protected” policy. Reads come from cache lines when possible, and read misses cause cache fills. Writes are propagated to the system bus and cause corresponding cache lines on all processors on the bus to be invalidated.

**EFI_MEMORY_SP**

Specific-purpose memory (SPM). The memory is earmarked for specific purposes such as for specific device drivers or applications. The SPM attribute serves as a hint to the OS to avoid allocating this memory for core OS data or code that can not be relocated. Prolonged use of this memory for purposes other than the intended purpose may result in suboptimal platform performance.

---

**7.2. Memory Allocation Services**
**EFI_MEMORY_CPU_CRYPTO**

If this flag is set, the memory region is capable of being protected with the CPU’s memory cryptographic capabilities. If this flag is clear, the memory region is not capable of being protected with the CPU’s memory cryptographic capabilities or the CPU does not support CPU memory cryptographic capabilities.

**Note:** *UEFI spec 2.5 and following: use EFI_MEMORY_RO as rite-protected physical memory protection attribute. Also, EFI_MEMORY_WP means cacheability attribute.*

**EFI_MEMORY_RP**

Physical memory protection attribute: The memory region supports being configured as read-protected by system hardware.

**EFI_MEMORY_XP**

Physical memory protection attribute: The memory region supports being configured so it is protected by system hardware from executing code.

**EFI_MEMORY_NV**

Runtime memory attribute: The memory region refers to persistent memory

**EFI_MEMORY_MORE_RELIABLE**

The memory region provides higher reliability relative to other memory in the system. If all memory has the same reliability, then this bit is not used.

**EFI_MEMORY_RO**

Physical memory protection attribute: The memory region supports making this memory range read-only by system hardware.

**EFI_MEMORY_RUNTIME**

Runtime memory attribute: The memory region needs to be given a virtual mapping by the operating system when `SetVirtualAddressMap()` is called (described in `Virtual Memory Services`).

---

```c
//****************************************************
//EFI_VIRTUAL_ADDRESS
//************************************************************************
typedef UINT64 EFI_VIRTUAL_ADDRESS;

//************************************************************************
// Memory Descriptor Version Number
//************************************************************************
#define EFI_MEMORY_DESCRIPTOR_VERSION 1
```

**Description**

The `GetMemoryMap()` function returns a copy of the current memory map. The map is an array of memory descriptors, each of which describes a contiguous block of memory. The map describes all of memory, no matter how it is being used. That is, it includes blocks allocated by `EFI_BOOT_SERVICES.AllocatePages()` and `EFI_BOOT_SERVICES.AllocatePool()`, as well as blocks that the firmware is using for its own purposes. The memory map is only used to describe memory that is present in the system. The firmware does not return a range description for address space regions that are not backed by physical hardware. Regions that are backed by physical hardware, but are not supposed to be accessed by the OS, must be returned as `EfiReservedMemoryType`. The OS may use addresses of memory ranges that are not described in the memory map at its own discretion.

Until `EFI_BOOT_SERVICES.ExitBootServices()` is called, the memory map is owned by the firmware and the currently executing UEFI Image should only use memory pages it has explicitly allocated.

If the MemoryMap buffer is too small, the `EFI_BUFFER_TOO_SMALL` error code is returned and the MemoryMapSize value contains the size of the buffer needed to contain the current memory map. The actual size of the buffer allocated for the consequent call to `GetMemoryMap()` should be bigger than the value returned in `MemoryMapSize`, since allocation of the new buffer may potentially increase memory map size.
On success a MapKey is returned that identifies the current memory map. The firmware’s key is changed every time something in the memory map changes. In order to successfully invoke `EFI_BOOT_SERVICES.ExitBootServices()` the caller must provide the current memory map key.

The `GetMemoryMap()` function also returns the size and revision number of the EFI_MEMORY_DESCRIPTOR. The DescriptorSize represents the size in bytes of an EFI_MEMORY_DESCRIPTOR array element returned in MemoryMap. The size is returned to allow for future expansion of the EFI_MEMORY_DESCRIPTOR in response to hardware innovation. The structure of the EFI_MEMORY_DESCRIPTOR may be extended in the future but it will remain backwards compatible with the current definition. Thus OS software must use the DescriptorSize to find the start of each EFI_MEMORY_DESCRIPTOR in the MemoryMap array.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The memory map was returned in the <code>MemoryMap</code> buffer.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The <code>MemoryMap</code> buffer was too small. The current buffer size needed to hold the memory map is returned in <code>MemoryMapSize</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>MemoryMapSize</code> is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>MemoryMap</code> buffer is not too small and <code>MemoryMap</code> is NULL.</td>
</tr>
</tbody>
</table>

### 7.2.4 EFI_BOOT_SERVICES.AllocatePool()

#### Summary
Allocates pool memory.

#### Prototype
```c
typedef EFI_STATUS
  (EFIAPI *EFI_ALLOCATE_POOL) (
    IN EFI_MEMORY_TYPE PoolType,
    IN UINTN Size,
    OUT VOID **Buffer
  );
```

#### Parameters
- **PoolType**: The type of pool to allocate. Type EFI_MEMORY_TYPE is defined in the `EFI_BOOT_SERVICES.AllocatePages()` function description. PoolType values in the range 0x70000000..0x7FFFFFFF are reserved for OEM use. PoolType values in the range 0x80000000..0xFFFFFFFF are reserved for use by UEFI OS loaders that are provided by operating system vendors.
- **Size**: The number of bytes to allocate from the pool.
- **Buffer**: A pointer to a pointer to the allocated buffer if the call succeeds; undefined otherwise.

**Note**: UEFI applications and UEFI drivers must not allocate memory of type EfiReservedMemoryType.

#### Description
The AllocatePool() function allocates a memory region of Size bytes from memory of type PoolType and returns the address of the allocated memory in the location referenced by Buffer. This function allocates pages from EfiConventionalMemory as needed to grow the requested pool type. All allocations are eight-byte aligned.

The allocated pool memory is returned to the available pool with the `EFI_BOOT_SERVICES.FreePool()` function.
Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested number of bytes was allocated.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The pool requested could not be allocated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PoolType is in the range EfiMaxMemoryType..0x6FFFFFFF.</td>
</tr>
<tr>
<td>EFI_INVAILD_PARAMETER</td>
<td>PoolType is EfiPersistentMemory.</td>
</tr>
<tr>
<td>EFI_INVAILD_PARAMETER</td>
<td>Buffer is NULL.</td>
</tr>
</tbody>
</table>

7.2.5 EFI_BOOT_SERVICES.FreePool()

Summary

Returns pool memory to the system.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_FREE_POOL) (
    IN VOID *Buffer
);

Parameters

Buffer

Pointer to the buffer to free.

Description

The FreePool() function returns the memory specified by Buffer to the system. On return, the memory’s type is Efi-ConventionalMemory. The Buffer that is freed must have been allocated by AllocatePool().

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The memory was returned to the system.</td>
</tr>
<tr>
<td>EFI_INVAILD_PARAMETER</td>
<td>Buffer was invalid.</td>
</tr>
</tbody>
</table>

7.3 Protocol Handler Services

In the abstract, a protocol consists of a 128-bit globally unique identifier (GUID) and a Protocol Interface structure. The structure contains the functions and instance data that are used to access a device. The functions that make up Protocol Handler Services allow applications to install a protocol on a handle, identify the handles that support a given protocol, determine whether a handle supports a given protocol, and so forth. See the Table, below.

Table 7.14: Protocol Interface Functions

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>InstallProtocolInterface</td>
<td>Boot</td>
<td>Installs a protocol interface on a device handle.</td>
</tr>
<tr>
<td>UninstallProtocolInterface</td>
<td>Boot</td>
<td>Removes a protocol interface from a device handle.</td>
</tr>
<tr>
<td>ReinstallProtocolInterface</td>
<td>Boot</td>
<td>Reinstalls a protocol interface on a device handle.</td>
</tr>
</tbody>
</table>

continues on next page
Table 7.14 – continued from previous page

<table>
<thead>
<tr>
<th>Function</th>
<th>Boot</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>RegisterProtocol-Notify</td>
<td>Boot</td>
<td>Registers an event that is to be signaled whenever an interface is installed for a specified protocol.</td>
</tr>
<tr>
<td>LocateHandle</td>
<td>Boot</td>
<td>Returns an array of handles that support a specified protocol.</td>
</tr>
<tr>
<td>HandleProtocol</td>
<td>Boot</td>
<td>Queries a handle to determine if it supports a specified protocol.</td>
</tr>
<tr>
<td>LocateDevicePath</td>
<td>Boot</td>
<td>Locates all devices on a device path that support a specified protocol and returns the handle to the device that is closest to the path.</td>
</tr>
<tr>
<td>OpenProtocol</td>
<td>Boot</td>
<td>Adds elements to the list of agents consuming a protocol interface.</td>
</tr>
<tr>
<td>CloseProtocol</td>
<td>Boot</td>
<td>Removes elements from the list of agents consuming a protocol interface.</td>
</tr>
<tr>
<td>OpenProtocolInformation</td>
<td>Boot</td>
<td>Retrieve the list of agents that are currently consuming a protocol interface.</td>
</tr>
<tr>
<td>ConnectController</td>
<td>Boot</td>
<td>Uses a set of precedence rules to find the best set of drivers to manage a controller.</td>
</tr>
<tr>
<td>DisconnectController</td>
<td>Boot</td>
<td>Informs a set of drivers to stop managing a controller.</td>
</tr>
<tr>
<td>ProtocolsPerHandle</td>
<td>Boot</td>
<td>Retrieves the list of protocols installed on a handle. The return buffer is automatically allocated.</td>
</tr>
<tr>
<td>LocateHandleBuffer</td>
<td>Boot</td>
<td>Retrieves the list of handles from the handle database that meet the search criteria. The return buffer is automatically allocated.</td>
</tr>
<tr>
<td>LocateProtocol</td>
<td>Boot</td>
<td>Finds the first handle in the handle database that supports the requested protocol.</td>
</tr>
<tr>
<td>InstallMultipleProtocolInterfaces</td>
<td>Boot</td>
<td>Installs one or more protocol interfaces onto a handle.</td>
</tr>
<tr>
<td>UninstallMultipleProtocolInterfaces</td>
<td>Boot</td>
<td>Uninstalls one or more protocol interfaces from a handle.</td>
</tr>
</tbody>
</table>

The Protocol Handler boot services have been modified to take advantage of the information that is now being tracked with the `EFI_BOOT_SERVICES.OpenProtocol()` and `EFI_BOOT_SERVICES.CloseProtocol()` functions. Since the usage of protocol interfaces is being tracked with these new boot services, it is now possible to safely uninstall and reinstall protocol interfaces that are being consumed by UEFI drivers.

As depicted in Figure 7-1 (below) the firmware is responsible for maintaining a “data base” that shows which protocols are attached to each device handle. (The figure depicts the “data base” as a linked list, but the choice of data structure is implementation-dependent.) The “data base” is built dynamically by calling the `EFI_BOOT_SERVICES.InstallProtocolInterface()` function. Protocols can only be installed by UEFI drivers or the firmware itself. In the figure, a device handle (EFI_HANDLE) refers to a list of one or more registered protocol interfaces for that handle. The first handle in the system has four attached protocols, and the second handle has two attached protocols. Each attached protocol is represented as a GUID/Interface pointer pair. The GUID is the name of the protocol, and Interface points to a protocol instance. This data structure will typically contain a list of interface functions, and some amount of instance data.

Access to devices is initiated by calling the `EFI_BOOT_SERVICES.HandleProtocol()` function, which determines whether a handle supports a given protocol. If it does, a pointer to the matching Protocol Interface structure is returned.

When a protocol is added to the system, it may either be added to an existing device handle or it may be added to create a new device handle. See Figure 7-1 (below) shows that protocol handlers are listed for each device handle and that each protocol handler is logically a UEFI driver.

The ability to add new protocol interfaces as new handles or to layer them on existing interfaces provides great flexibility. Layering makes it possible to add a new protocol that builds on a device’s basic protocols. An example of this might be to layer on a `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL` support that would build on the handle’s underlyin `EFI_SERIAL_IO_PROTOCOL`.
The ability to add new handles can be used to generate new devices as they are found, or even to generate abstract devices. An example of this might be to add a multiplexing device that replaces ConsoleOut with a virtual device that multiplexes the\texttt{EFI\_SIMPLE\_TEXT\_OUTPUT\_PROTOCOL} protocol onto multiple underlying device handles.

7.3.1 Driver Model Boot Services

Following is a detailed description of the new UEFI boot services that are required by the UEFI Driver Model. These boot services are being added to reduce the size and complexity of the bus drivers and device drivers. This, in turn, will reduce the amount of ROM space required by drivers that are programmed into ROMs on adapters or into system FLASH, and reduce the development and testing time required by driver writers.

These new services fall into two categories. The first group is used to track the usage of protocol interfaces by different agents in the system. Protocol interfaces are stored in a handle database. The handle database consists of a list of handles, and on each handle there is a list of one or more protocol interfaces. The boot services \texttt{EFI\_BOOT\_SERVICES.InstallProtocolInterface()}, \texttt{EFI\_BOOT\_SERVICES.UninstallProtocolInterface()} and \texttt{EFI\_BOOT\_SERVICES.ReinstallProtocolInterface()} are used to add, remove, and replace protocol interfaces in the handle database. The boot service \texttt{EFI\_BOOT\_SERVICES.HandleProtocol()} is used to look up a protocol interface in the handle database. However, agents that call \texttt{HandleProtocol()} are not tracked, so it is not safe to call \texttt{UninstallProtocolInterface()} or \texttt{ReinstallProtocolInterface()} because an agent may be using the protocol interface that is being removed or replaced.

The solution is to track the usage of protocol interfaces in the handle database itself. To accomplish this, each protocol interface includes a list of agents that are consuming the protocol interface. Figure 7-2 (below) shows an example handle database with these new agent lists. An agent consists of an image handle, a controller handle, and some attributes. The image handle identifies the driver or application that is consuming the protocol interface. The controller handle identifies the controller that is consuming the protocol interface. Since a driver may manage more than one controller,
the combination of a driver’s image handle and a controller’s controller handle uniquely identifies the agent that is consuming the protocol interface. The attributes show how the protocol interface is being used.

Fig. 7.2: Handle Database

In order to maintain these agent lists in the handle database, some new boot services are required. These are `EFI_BOOT_SERVICES.OpenProtocol()` , `EFI_BOOT_SERVICES.CloseProtocol()` , and `EFI_BOOT_SERVICES.OpenProtocolInformation()` . `OpenProtocol()` adds elements to the list of agents consuming a protocol interface. `CloseProtocol()` removes elements from the list of agents consuming a protocol interface, and ` EFI_BOOT_SERVICES.OpenProtocolInformation()` retrieves the entire list of agents that are currently using a protocol interface.

The second group of boot services is used to deterministically connect and disconnect drivers to controllers. The boot services in this group are `EFI_BOOT_SERVICES.ConnectController()` and `EFI_BOOT_SERVICES.DisconnectController()` . These services take advantage of the new features of the handle database along with the new protocols described in this document to manage the drivers and controllers present in the system. `ConnectController()` uses a set of strict precedence rules to find the best set of drivers for a controller. This provides a deterministic matching of drivers to controllers with extensibility mechanisms for OEMs, IBVs, and IHVs. `DisconnectController()` allows drivers to be disconnected from controllers in a controlled manner, and by using the new features of the handle database it is possible to fail a disconnect request because a protocol interface cannot be released at the time of the disconnect request.

The third group of boot services is designed to help simplify the implementation of drivers, and produce drivers with smaller executable footprints. The `EFI_BOOT_SERVICES.LocateHandleBuffer()` is a new version of `EFI_BOOT_SERVICES.LocateHandle()` that allocates the required buffer for the caller. This eliminates two calls to `LocateHandle()` and a call to `EFI_BOOT_SERVICES.AllocatePool()` from the caller’s code. `EFI_BOOT_SERVICES.LocateProtocol()` searches the handle database for the first protocol instance that matches the search criteria. The `EFI_BOOT_SERVICES.InstallMultipleProtocolInterfaces()` and
**EFI_BOOT_SERVICES.UninstallMultipleProtocolInterfaces()** are very useful to driver writers. These boot services allow one or more protocol interfaces to be added or removed from a handle. In addition, InstallMultipleProtocolInterfaces() guarantees that a duplicate device path is never added to the handle database. This is very useful to bus drivers that can create one child handle at a time, because it guarantees that the bus driver will not inadvertently create two instances of the same child handle.

### 7.3.2 EFI_BOOT_SERVICES.InstallProtocolInterface()

**Summary**

Installs a protocol interface on a device handle. If the handle does not exist, it is created and added to the list of handles in the system. InstallMultipleProtocolInterfaces() performs more error checking than InstallProtocolInterface(), so it is recommended that InstallMultipleProtocolInterfaces() be used in place of InstallProtocolInterface().

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_INSTALL_PROTOCOL_INTERFACE) (
    IN OUT EFI_HANDLE *Handle,
    IN EFI_GUID *Protocol,
    IN EFI_INTERFACE_TYPE InterfaceType,
    IN VOID *Interface
);
```

**Parameters**

**Handle**

A pointer to the EFI_HANDLE on which the interface is to be installed. If *Handle* is NULL on input, a new handle is created and returned on output. If *Handle* is not NULL on input, the protocol is added to the handle, and the handle is returned unmodified. The type EFI_HANDLE is defined in “Related Definitions.” If *Handle* is not a valid handle, then EFI_INVALID_PARAMETER is returned.

**Protocol**

The numeric ID of the protocol interface. The type EFI_GUID is defined in “Related Definitions.” It is the caller’s responsibility to pass in a valid GUID. For a description of valid GUID values, see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “RFC 4122”.

**InterfaceType**

Indicates whether Interface is supplied in native form. This value indicates the original execution environment of the request. See “Related Definitions.”

**Interface**

A pointer to the protocol interface. The Interface must adhere to the structure defined by Protocol. NULL can be used if a structure is not associated with Protocol.

**Related Definitions**

```c
//**************************************************************************************
//EFI_HANDLE
//**************************************************************************************
typedef VOID *EFI_HANDLE;

//**************************************************************************************
//EFI_GUID
//**************************************************************************************
```

(continues on next page)
typedef struct {
    UINT32 Data1;
    UINT16 Data2;
    UINT16 Data3;
    UINT8 Data4[8];
} EFI_GUID;

//EFI_INTERFACE_TYPE
#endif
typedef enum {
    EFI_NATIVE_INTERFACE
} EFI_INTERFACE_TYPE;

Description
The InstallProtocolInterface() function installs a protocol interface (a GUID/Protocol Interface structure pair) on a device handle. The same GUID cannot be installed more than once onto the same handle. If installation of a duplicate GUID on a handle is attempted, an EFI_INVALID_PARAMETER will result.

Installing a protocol interface allows other components to locate the Handle, and the interfaces installed on it.

When a protocol interface is installed, the firmware calls all notification functions that have registered to wait for the installation of Protocol. For more information, see the EFI_BOOT_SERVICES.RegisterProtocolNotify() function description.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The protocol interface was installed.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Space for a new handle could not be allocated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Handle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Protocol is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>InterfaceType is not EFI_NATIVE_INTERFACE.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Protocol is already installed on the handle specified by Handle.</td>
</tr>
</tbody>
</table>

7.3.3 EFI_BOOT_SERVICES.UninstallProtocolInterface()

Summary
Removes a protocol interface from a device handle. It is recommended that UninstallMultipleProtocolInterfaces() be used in place of UninstallProtocolInterface().

Prototype

typedef EFI_STATUS
(EFIAPI *EFI_UNINSTALL_PROTOCOL_INTERFACE) (       
    IN EFI_HANDLE Handle,
    IN EFI_GUID Protocol,
    IN VOID *Interface
    );

Parameters

7.3. Protocol Handler Services 167
Handle
The handle on which the interface was installed. If Handle is not a valid handle, then EFI_INVALID_PARAMETER is returned. Type EFI_HANDLE is defined in the EFI_BOOT_SERVICES.InstallProtocolInterface() function description.

Protocol
The numeric ID of the interface. It is the caller’s responsibility to pass in a valid GUID. For a description of valid GUID values, see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “RFC4122”. Type EFI_GUID is defined in the EFI_BOOT_SERVICES.InstallProtocolInterface() function description.

Interface
A pointer to the interface. NULL can be used if a structure is not associated with Protocol.

Description
The UninstallProtocolInterface() function removes a protocol interface from the handle on which it was previously installed. The Protocol and Interface values define the protocol interface to remove from the handle.

The caller is responsible for ensuring that there are no references to a protocol interface that has been removed. In some cases, outstanding reference information is not available in the protocol, so the protocol, once added, cannot be removed. Examples include Console I/O, Block I/O, Disk I/O, and (in general) handles to device protocols.

If the last protocol interface is removed from a handle, the handle is freed and is no longer valid.

EFI 1.10 Extension
The extension to this service directly addresses the limitations described in the section above. There may be some drivers that are currently consuming the protocol interface that needs to be uninstalled, so it may be dangerous to just blindly remove a protocol interface from the system. Since the usage of protocol interfaces is now being tracked for components that use the EFI_BOOT_SERVICES.OpenProtocol() and EFI_BOOT_SERVICES.CloseProtocol() boot services, a safe version of this function can be implemented. Before the protocol interface is removed, an attempt is made to force all the drivers that are consuming the protocol interface to stop consuming that protocol interface. This is done by calling the boot service EFI_BOOT_SERVICES.DisconnectController() for the driver that currently have the protocol interface open with an attribute of EFI_OPEN_PROTOCOL_BY_DRIVER or EFI_OPEN_PROTOCOL_BY_HANDLE_PROTOCOL | EFI_OPEN_PROTOCOL_EXCLUSIVE.

If the disconnect succeeds, then those agents will have called the boot service EFI_BOOT_SERVICES.CloseProtocol() to release the protocol interface. Lastly, all of the agents that have the protocol interface open with an attribute of EFI_OPEN_PROTOCOL_BY_HANDLE_PROTOCOL, EFI_OPEN_PROTOCOL_GET_PROTOCOL, or EFI_OPEN_PROTOCOL_TEST_PROTOCOL are closed. If there are any agents remaining that still have the protocol interface open, the protocol interface is not removed from the handle and EFI_ACCESS_DENIED is returned. In addition, all of the drivers that were disconnected with the boot service DisconnectController() earlier, are reconnected with the boot service EFI_BOOT_SERVICES.ConnectController(). If there are no agents remaining that are consuming the protocol interface, then the protocol interface is removed from the handle as described above.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The interface was removed.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The interface was not found.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The interface was not removed because the interface is still being used by a driver.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Handle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Protocol is NULL.</td>
</tr>
</tbody>
</table>
7.3.4 EFI_BOOT_SERVICES.ReinstallProtocolInterface()

Summary
Reinstalls a protocol interface on a device handle.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_REINSTALL_PROTOCOL_INTERFACE) (
    IN EFI_HANDLE Handle,
    IN EFI_GUID *Protocol,
    IN VOID *OldInterface,
    IN VOID *NewInterface);
```

Parameters

Handle
Handle on which the interface is to be reinstalled. If Handle is not a valid handle, then EFI_INVALID_PARAMETER is returned. Type EFI_HANDLE is defined in the EFI_BOOT_SERVICES.InstallProtocolInterface() function description.

Protocol
The numeric ID of the interface. It is the caller’s responsibility to pass in a valid GUID. For a description of valid GUID values, see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “RFC 4122”. Type EFI_GUID is defined in the InstallProtocolInterface() function description.

OldInterface
A pointer to the old interface. NULL can be used if a structure is not associated with Protocol.

NewInterface
A pointer to the new interface. NULL can be used if a structure is not associated with Protocol.

Description

The ReinstallProtocolInterface() function reinstalls a protocol interface on a device handle. The OldInterface for Protocol is replaced by the NewInterface. NewInterface may be the same as OldInterface. If it is, the registered protocol notifies occur for the handle without replacing the interface on the handle.

As with InstallProtocolInterface(), any process that has registered to wait for the installation of the interface is notified. The caller is responsible for ensuring that there are no references to the OldInterface that is being removed.

EFI 1.10 Extension

The extension to this service directly addresses the limitations described in the section above. There may be some number of drivers currently consuming the protocol interface that is being reinstalled. In this case, it may be dangerous to replace a protocol interface in the system. It could result in an unstable state, because a driver may attempt to use the old protocol interface after a new one has been reinstalled. Since the usage of protocol interfaces is now being tracked for components that use the EFI_BOOT_SERVICES.OpenProtocol() and EFI_BOOT_SERVICES.CloseProtocol() boot services, a safe version of this function can be implemented.

When this function is called, a call is first made to the boot service UninstallProtocolInterface(). This will guarantee that all of the agents are currently consuming the protocol interface OldInterface will stop using OldInterface. If UninstallProtocolInterface() returns EFI_ACCESS_DENIED, then this function returns EFI_ACCESS_DENIED. OldInterface remains on Handle, and the protocol notifies are not processed because NewInterface was never installed.
If UninstallProtocolInterface() succeeds, then a call is made to the boot service
EFI_BOOT_SERVICES.InstallProtocolInterface() to put the NewInterface onto Handle.

Finally, the boot service EFI_BOOT_SERVICES.ConnectController() is called so all agents that were forced to release
OldInterface with UninstallProtocolInterface() can now consume the protocol interface NewInterface that was installed
with InstallProtocolInterface(). After OldInterface has been replaced with NewInterface, any process that has registered
to wait for the installation of the interface is notified.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The protocol interface was reinstalled.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The OldInterface on the handle was not found.</td>
</tr>
</tbody>
</table>
| EFI_ACCESS_DENIED     | The protocol interface could not be reinstalled, because OldInterface is still
                       | being used by a driver that will not release it.                           |
| EFI_INVALID_PARAMETER | Handle is NULL.                                                             |
| EFI_INVALID_PARAMETER | Protocol is NULL.                                                           |

7.3.5 EFI_BOOT_SERVICES.RegisterProtocolNotify()

**Summary**

Creates an event that is to be signaled whenever an interface is installed for a specified protocol.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_REGISTER_PROTOCOL_NOTIFY) (  
    IN EFI_GUID *Protocol,  
    IN EFI_EVENT Event,  
    OUT VOID **Registration
);
```

**Parameters**

**Protocol**

The numeric ID of the protocol for which the event is to be registered. Type EFI_GUID is defined in the
EFI_BOOT_SERVICES.InstallProtocolInterface() function description.

**Event**

Event that is to be signaled whenever a protocol interface is registered for Protocol. The type EFI_EVENT is
defined in the CreateEvent() function description. The same EFI_EVENT may be used for multiple protocol
notify registrations.

**Registration**

A pointer to a memory location to receive the registration value. This value must be saved and used by the
notification function of Event to retrieve the list of handles that have added a protocol interface of type Protocol.

**Description**

The RegisterProtocolNotify() function creates an event that is to be signaled whenever a protocol interface is installed
for Protocol by InstallProtocolInterface() or EFI_BOOT_SERVICES.ReinstallProtocolInterface().

Once Event has been signaled, the EFI_BOOT_SERVICES.LocateHandle() function can be called to identify
the newly installed, or reinstalled, handles that support Protocol. The Registration parameter in
EFI_BOOT_SERVICES.RegisterProtocolNotify() corresponds to the SearchKey parameter in LocateHandle(). Note
that the same handle may be returned multiple times if the handle reinstallst the target protocol ID multiple times. This
is typical for removable media devices, because when such a device reappears, it will reinstall the Block I/O protocol to indicate that the device needs to be checked again. In response, layered Disk I/O and Simple File System protocols may then reinstall their protocols to indicate that they can be re-checked, and so forth.

Events that have been registered for protocol interface notification can be unregistered by calling CloseEvent().

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The notification event has been registered.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Space for the notification event could not be allocated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Protocol is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Event is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Registration is NULL.</td>
</tr>
</tbody>
</table>

**7.3.6 EFI_BOOT_SERVICES.LocateHandle()**

**Summary**

Retrieves an array of handles that support a specified protocol.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_LOCATE_HANDLE) (
    IN EFI_LOCATE_SEARCH_TYPE SearchType, 
    IN EFI_GUID *Protocol OPTIONAL, 
    IN VOID *SearchKey OPTIONAL, 
    IN OUT UINTN *BufferSize, 
    OUT EFI_HANDLE *Buffer
);```

**Parameters**

**SearchType**

Specifies which handle(s) are to be returned. Type EFI_LOCATE_SEARCH_TYPE is defined in “Related Definitions.”

**Protocol**

Specifies the protocol to search by. This parameter is only valid if SearchType is ByProtocol. Type EFI_GUID is defined in the EFI_BOOT_SERVICES.InstallProtocolInterface() function description.

**SearchKey**

Specifies the search key. This parameter is ignored if SearchType is AllHandles or ByProtocol. If SearchType is ByRegisterNotify, the parameter must be the Registration value returned by function EFI_BOOT_SERVICES.RegisterProtocolNotify() .

**BufferSize**

On input, the size in bytes of Buffer. On output, the size in bytes of the array returned in*Buffer*(if the buffer was large enough) or the size, in bytes, of the buffer needed to obtain the array (if the buffer was not large enough).

**Buffer**

The buffer in which the array is returned. Type EFI_HANDLE is defined in the InstallProtocolInterface() function description.

**Related Definitions**
AllHandles
Protocol and SearchKey are ignored and the function returns an array of every handle in the system.

ByRegisterNotify
SearchKey supplies the Registration value returned by `EFI_BOOT_SERVICES.RegisterProtocolNotify()` . The function returns the next handle that is new for the registration. Only one handle is returned at a time, starting with the first, and the caller must loop until no more handles are returned. Protocol is ignored for this search type.

ByProtocol
All handles that support Protocol are returned. SearchKey is ignored for this search type.

Description
The LocateHandle() function returns an array of handles that match the SearchType request. If the input value of BufferSize is too small, the function returns EFI_BUFFER_TOO_SMALL and updates BufferSize to the size of the buffer needed to obtain the array.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The array of handles was returned.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No handles match the search.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The BufferSize is too small for the result. BufferSize has been updated with the size needed to complete the request.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>SearchType is not a member of EFI_LOCATE_SEARCH_TYPE.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>SearchType is ByRegisterNotify and SearchKey is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>SearchType is ByProtocol and Protocol is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more matches are found and BufferSize is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>BufferSize is large enough for the result and Buffer is NULL.</td>
</tr>
</tbody>
</table>

7.3.7 EFI_BOOT_SERVICES.HandleProtocol()

Summary
Queries a handle to determine if it supports a specified protocol.

Prototype

typedef
EFI_STATUS
(EIFIAPIC *EFI_HANDLE_PROTOCOL) (  
    IN EFI_HANDLE Handle,
    IN EFI_GUID *Protocol,
    OUT VOID **Interface
);
Parameters

Handle
The handle being queried. If Handle is NULL, then EFI_INVALID_PARAMETER is returned. Type EFI_HANDLE is defined in the EFI_BOOT_SERVICES.InstallProtocolInterface() function description.

Protocol
The published unique identifier of the protocol. It is the caller’s responsibility to pass in a valid GUID. For a description of valid GUID values, see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “RFC 4122”. Type EFI_GUID is defined in the InstallProtocolInterface() function description.

Interface
Supplies the address where a pointer to the corresponding Protocol Interface is returned. NULL will be returned in * Interface if a structure is not associated with Protocol.

Description
The HandleProtocol() function queries Handle to determine if it supports Protocol. If it does, then on return Interface points to a pointer to the corresponding Protocol Interface. Interface can then be passed to any protocol service to identify the context of the request.

EFI 1.10 Extension
The HandleProtocol() function is still available for use by old EFI applications and drivers. However, all new applications and drivers should use EFI_BOOT_SERVICES.OpenProtocol() in place of HandleProtocol(). The following code fragment shows a possible implementation of HandleProtocol() using OpenProtocol(). The variable EfiCoreImageHandle is the image handle of the EFI core.

```c
EFI_STATUS
HandleProtocol (  
IN EFI_HANDLE Handle,  
IN EFI_GUID *Protocol,  
OUT VOID **Interface  
)
{
    return OpenProtocol (  
        Handle,  
        Protocol,  
        Interface,  
        EfiCoreImageHandle,  
        NULL,  
        EFI_OPEN_PROTOCOL_BY_HANDLE_PROTOCOL  
    );
}
```

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The interface information for the specified protocol was returned.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The device does not support the specified protocol.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Handle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Protocol is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Interface is NULL.</td>
</tr>
</tbody>
</table>
### 7.3.8 EFI_BOOT_SERVICES.LocateDevicePath()

#### Summary
Locates the handle to a device on the device path that supports the specified protocol.

#### Prototype
```
typedef
EFI_STATUS
(EFIAPI *EFI_LOCATE_DEVICE_PATH) (
    IN EFI_GUID *Protocol,
    IN OUT EFI_DEVICE_PATH_PROTOCOL **DevicePath,
    OUT EFI_HANDLE *Device
);
```

#### Parameters

**Protocol**
The protocol to search for. Type EFI_GUID is defined in the `EFI_BOOT_SERVICES.InstallProtocolInterface()` function description.

**DevicePath**
On input, a pointer to a pointer to the device path. On output, the device path pointer is modified to point to the remaining part of the device path—that is, when the function finds the closest handle, it splits the device path into two parts, stripping off the front part, and returning the remaining portion. EFI_DEVICE_PATH_PROTOCOL is defined in *EFI Device Path Protocol*.

**Device**
A pointer to the returned device handle. Type EFI_HANDLE is defined in the InstallProtocolInterface() function description.

#### Description
The `LocateDevicePath()` function locates all devices on `DevicePath` that support `Protocol` and returns the handle to the device that is closest to `DevicePath`. `DevicePath` is advanced over the device path nodes that were matched.

This function is useful for locating the proper instance of a protocol interface to use from a logical parent device driver. For example, a target device driver may issue the request with its own device path and locate the interfaces to perform I/O on its bus. It can also be used with a device path that contains a file path to strip off the file system portion of the device path, leaving the file path and handle to the file system driver needed to access the file.

If the handle for `DevicePath` supports the protocol (a direct match), the resulting device path is advanced to the device path terminator node. If `DevicePath` is a multi-instance device path, the function will operate on the first instance.

#### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The resulting handle was returned.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No handles matched the search.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Protocol is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DevicePath is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A handle matched the search and Device is NULL.</td>
</tr>
</tbody>
</table>

---

7.3. Protocol Handler Services
7.3.9 EFI_BOOT_SERVICES.OpenProtocol()

Summary
Queries a handle to determine if it supports a specified protocol. If the protocol is supported by the handle, it opens the protocol on behalf of the calling agent. This is an extended version of the EFI boot service EFI_BOOT_SERVICES.HandleProtocol() .

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_OPEN_PROTOCOL) (IN EFI_HANDLE Handle,
              IN EFI_GUID *Protocol,
              OUT VOID **Interface OPTIONAL,
              IN EFI_HANDLE AgentHandle,
              IN EFI_HANDLE ControllerHandle,
              IN UINT32 Attributes);
```

Parameters

Handle
The handle for the protocol interface that is being opened.

Protocol
The published unique identifier of the protocol. It is the caller’s responsibility to pass in a valid GUID. For a description of valid GUID values, see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “RFC 4122”.

Interface
Supplies the address where a pointer to the corresponding Protocol Interface is returned. NULL will be returned in *Interface if a structure is not associated with Protocol. This parameter is optional, and will be ignored if Attributes is EFI_OPEN_PROTOCOL_TEST_PROTOCOL.

AgentHandle
The handle of the agent that is opening the protocol interface specified by Protocol and Interface. For agents that follow the UEFI Driver Model, this parameter is the handle that contains the EFI_DRIVER_BINDING_PROTOCOL instance that is produced by the UEFI driver that is opening the protocol interface. For UEFI applications, this is the image handle of the UEFI application that is opening the protocol interface. For applications that use HandleProtocol() to open a protocol interface, this parameter is the image handle of the EFI firmware.

ControllerHandle
If the agent that is opening a protocol is a driver that follows the UEFI Driver Model, then this parameter is the controller handle that requires the protocol interface. If the agent does not follow the UEFI Driver Model, then this parameter is optional and may be NULL.

Attributes
The open mode of the protocol interface specified by Handle and Protocol. See “Related Definitions” for the list of legal attributes.

Description
This function opens a protocol interface on the handle specified by Handle for the protocol specified by Protocol. The first three parameters are the same as EFI_BOOT_SERVICES.HandleProtocol() . The only difference is that the agent that is opening a protocol interface is tracked in an EFI’s internal handle database. The tracking is used by the UEFI Driver Model, and also used to determine if it is safe to uninstall or reinstall a protocol interface.
The agent that is opening the protocol interface is specified by `AgentHandle`, `ControllerHandle`, and `Attributes`. If the protocol interface can be opened, then `AgentHandle`, `ControllerHandle`, and `Attributes` are added to the list of agents that are consuming the protocol interface specified by `Handle` and `Protocol`. In addition, the protocol interface is returned in `Interface`, and `EFI_SUCCESS` is returned. If `Attributes` is `TEST_PROTOCOL`, then `Interface` is optional, and can be NULL.

There are a number of reasons that this function call can return an error. If an error is returned, then `AgentHandle`, `ControllerHandle`, and `Attributes` are not added to the list of agents consuming the protocol interface specified by `Handle` and `Protocol`. `Interface` is returned unmodified for all error conditions except `EFI_UNSUPPORTED` and `EFI_ALREADY_STARTED`, NULL will be returned in `* Interface` when `EFI_UNSUPPORTED` and `Attributes` is not `EFI_OPEN_PROTOCOL_TEST_PROTOCOL`, the protocol interface will be returned in `* Interface` when `EFI_ALREADY_STARTED`.

The following is the list of conditions that must be checked before this function can return `EFI_SUCCESS`:

- If `Protocol` is NULL, then `EFI_INVALID_PARAMETER` is returned.
- If `Interface` is NULL and `Attributes` is not `TEST_PROTOCOL`, then `EFI_INVALID_PARAMETER` is returned.
- If `Handle` is NULL, then `EFI_INVALID_PARAMETER` is returned.
- If `Handle` does not support Protocol, then `EFI_UNSUPPORTED` is returned.
- If `Attributes` is not a legal value, then `EFI_INVALID_PARAMETER` is returned. The legal values are listed in “Related Definitions.”
- If `Attributes` is `BY_CHILD_CONTROLLER`, `BY_DRIVER`, `EXCLUSIVE`, or `BY_DRIVER|EXCLUSIVE`, and `AgentHandle` is NULL, then `EFI_INVALID_PARAMETER` is returned.
- If `Attributes` is `BY_CHILD_CONTROLLER`, `BY_DRIVER`, or `BY_DRIVER|EXCLUSIVE`, and `ControllerHandle` is NULL, then `EFI_INVALID_PARAMETER` is returned.
- If `Attributes` is `BY_CHILD_CONTROLLER` and `Handle` is identical to `ControllerHandle`, then `EFI_INVALID_PARAMETER` is returned.
- If `Attributes` is `BY_DRIVER`, `BY_DRIVER EXCLUSIVE`, or `EXCLUSIVE`, and there are any items on the open list of the protocol interface with an attribute of `EXCLUSIVE` or `BY_DRIVER|EXCLUSIVE`, then `EFI_ACCESS_DENIED` is returned.
- If `Attributes` is `BY_DRIVER`, and there are any items on the open list of the protocol interface with an attribute of `BY_DRIVER`, and `AgentHandle` is the same agent handle in the open list item, then `EFI_ALREADY_STARTED` is returned.
- If `Attributes` is `BY_DRIVER`, and there are any items on the open list of the protocol interface with an attribute of `BY_DRIVER`, and `AgentHandle` is different than the agent handle in the open list item, then `EFI_ACCESS_DENIED` is returned.
- If `Attributes` is `BY_DRIVER|EXCLUSIVE`, and there are any items on the open list of the protocol interface with an attribute of `BY_DRIVER|EXCLUSIVE`, and `AgentHandle` is the same agent handle in the open list item, then `EFI_ALREADY_STARTED` is returned.
- If `Attributes` is `BY_DRIVER EXCLUSIVE`, and there are any items on the open list of the protocol interface with an attribute of `BY_DRIVER|EXCLUSIVE`, and `AgentHandle` is different than the agent handle in the open list item, then `EFI_ACCESS_DENIED` is returned.
- If `Attributes` is `BY_DRIVER|EXCLUSIVE` or `EXCLUSIVE`, and there is an item on the open list of the protocol interface with an attribute of `BY_DRIVER`, then the boot service `EFI_BOOT_SERVICES.DisconnectController()` is called for the driver on the open list. If there is an item in the open list of the protocol interface with an attribute of `BY_DRIVER` remaining after the DisconnectController() call has been made, `EFI_ACCESS_DENIED` is returned.

Related Definitions

7.3. Protocol Handler Services
The following is the list of legal values for the Attributes parameter, and how each value is used.

**BY_HANDLE_PROTOCOL** Used in the implementation of `EFI_BOOT_SERVICES.HandleProtocol()` . Since `EFI_BOOT_SERVICES.OpenProtocol()` performs the same function as HandleProtocol() with additional functionality, HandleProtocol() can simply call OpenProtocol() with this `Attributes` value.

**GET_PROTOCOL** Used by a driver to get a protocol interface from a handle. Care must be taken when using this open mode because the driver that opens a protocol interface in this manner will not be informed if the protocol interface is uninstalled or reinstalled. The caller is also not required to close the protocol interface with `EFI_BOOT_SERVICES.CloseProtocol()` .

**TEST_PROTOCOL** Used by a driver to test for the existence of a protocol interface on a handle. Interface is optional for this attribute value, so it is ignored, and the caller should only use the return status code. The caller is also not required to close the protocol interface with CloseProtocol().

**BY_CHILD_CONTROLLER** Used by bus drivers to show that a protocol interface is being used by one of the child controllers of a bus. This information is used by the boot service `EFI_BOOT_SERVICES.ConnectController()` to recursively connect all child controllers and by the boot service `EFI_BOOT_SERVICES.DisconnectController()` to get the list of child controllers that a bus driver created.

**BY_DRIVER** Used by a driver to gain access to a protocol interface. When this mode is used, the driver’s Stop() function will be called by `EFI_BOOT_SERVICES.DisconnectController()` if the protocol interface is reinstalled or uninstalled. Once a protocol interface is opened by a driver with this attribute, no other drivers will be allowed to open the same protocol interface with the BY_DRIVER attribute.

**BY_DRIVER|EXCLUSIVE** Used by a driver to gain exclusive access to a protocol interface. If any other drivers have the protocol interface opened with an attribute of BY_DRIVER, then an attempt will be made to remove them with DisconnectController().

**EXCLUSIVE** Used by applications to gain exclusive access to a protocol interface. If any drivers have the protocol interface opened with an attribute of BY_DRIVER, then an attempt will be made to remove them by calling the driver’s Stop() function.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>An item was added to the open list for the protocol interface, and the protocol interface was returned in <code>Interface</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Protocol is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Interface is NULL, and Attributes is not TEST_PROTOCOL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Handle is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Handle does not support Protocol.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Attributes is not a legal value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Attributes is BY_CHILD_CONTROLLER and AgentHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Attributes is BY_DRIVER and AgentHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Attribute is BY_DRIVEREXCLUSIVE and AgentHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Attributes is EXCLUSIVE and AgentHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Attributes is BY_CHILD_CONTROLLER and ControllerHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Attributes is BY_DRIVER and ControllerHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Attributes is BY_DRIVEREXCLUSIVE and ControllerHandle is NULL.</td>
</tr>
</tbody>
</table>

continues on next page
Table 7.22 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Attributes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Attributes is BY_CHILD_CONTROLLER and Handle is identical to ControllerHandle.</td>
<td></td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Attributes is BY_DRIVER and there is an item on the open list with an attribute of BY_DRIVEREXCLUSIVE or EXCLUSIVE.</td>
<td></td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Attributes is BY_DRIVEREXCLUSIVE and there is an item on the open list with an attribute of EXCLUSIVE.</td>
<td></td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Attributes is EXCLUSIVE and there is an item on the open list with an attribute of BY_DRIVEREXCLUSIVE or EXCLUSIVE.</td>
<td></td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>Attributes is BY_DRIVER and there is an item on the open list with an attribute of BY_DRIVER whose agent handle is the same as AgentHandle.</td>
<td></td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Attributes is BY_DRIVER and there is an item on the open list with an attribute of BY_DRIVER whose agent handle is different than AgentHandle.</td>
<td></td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>Attributes is BY_DRIVEREXCLUSIVE and there is an item on the open list with an attribute of BY_DRIVEREXCLUSIVE whose agent handle is the same as AgentHandle.</td>
<td></td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Attributes is BY_DRIVEREXCLUSIVE and there is an item on the open list with an attribute of BY_DRIVEREXCLUSIVE whose agent handle is different than AgentHandle.</td>
<td></td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Attributes is BY_DRIVEREXCLUSIVE or EXCLUSIVE and there are items in the open list with an attribute of BY_DRIVER that could not be removed when EFI_BOOT_SERVICES.DisconnectController() was called for that open item.</td>
<td></td>
</tr>
</tbody>
</table>

Examples

```c
EFI_BOOT_SERVICES *gBS;
EFI_HANDLE ImageHandle;
EFI_DRIVER_BINDING_PROTOCOL *This;
IN EFI_HANDLE ControllerHandle,
extern EFI_GUID gEfiXyzIoProtocol;
EFI_XYZ_IO_PROTOCOL *XyzIo;
EFI_STATUS Status;

// EFI_OPEN_PROTOCOL_BY_HANDLE_PROTOCOL example
// Retrieves the XYZ I/O Protocol instance from ControllerHandle
// The application that is opening the protocol is identified by ImageHandle
// Possible return status codes:
//   EFI_SUCCESS : The protocol was opened and returned in XyzIo
//   EFI_UNSUPPORTED : The protocol is not present on ControllerHandle
// Status = gBS->OpenProtocol (ControllerHandle, &gEfiXyzIoProtocol, &XyzIo, ImageHandle, NULL, EFI_OPEN_PROTOCOL_BY_HANDLE_PROTOCOL);
```

(continues on next page)
// Retrieves the XYZ I/O Protocol instance from ControllerHandle
// The driver that is opening the protocol is identified by the
// Driver Binding Protocol instance This. This->DriverBindingHandle
// identifies the agent that is opening the protocol interface, and it
// is opening this protocol on behalf of ControllerHandle.
// Possible return status codes:
//   EFI_SUCCESS : The protocol was opened and returned in XyzIo
//   EFI_UNSUPPORTED : The protocol is not present on ControllerHandle
// Status = gBS->OpenProtocol (ControllerHandle,
// &gEfiXyzIoProtocol,
// &XyzIo,
// This->DriverBindingHandle,
// ControllerHandle,
// EFI_OPEN_PROTOCOL_GET_PROTOCOL);

// EFI_OPEN_PROTOCOL_TEST_PROTOCOL example
// Tests to see if the XYZ I/O Protocol is present on ControllerHandle
// The driver that is opening the protocol is identified by the
// Driver Binding Protocol instance This. This->DriverBindingHandle
// identifies the agent that is opening the protocol interface, and it
// is opening this protocol on behalf of ControllerHandle.
//   EFI_SUCCESS : The protocol was opened and returned in XyzIo
//   EFI_UNSUPPORTED : The protocol is not present on ControllerHandle
// Status = gBS->OpenProtocol (ControllerHandle,
// &gEfiXyzIoProtocol,
// NULL,
// This->DriverBindingHandle,
// ControllerHandle,
// EFI_OPEN_PROTOCOL_TEST_PROTOCOL);

// EFI_OPEN_PROTOCOL_BY_DRIVER example
// Opens the XYZ I/O Protocol on ControllerHandle
// The driver that is opening the protocol is identified by the
// Driver Binding Protocol instance This. This->DriverBindingHandle
// identifies the agent that is opening the protocol interface, and it
// is opening this protocol on behalf of ControllerHandle.
// Possible return status codes:
//   EFI_SUCCESS : The protocol was opened and returned in XyzIo
//   EFI_UNSUPPORTED : The protocol is not present on ControllerHandle
//   EFI_ALREADY_STARTED : The protocol is already opened by the driver
//   EFI_ACCESS_DENIED : The protocol is managed by a different driver
// Status = gBS->OpenProtocol (ControllerHandle,
&gEfiXyzIoProtocol,
&XyzIo,
This->DriverBindingHandle,
ControllerHandle,
EFI_OPEN_PROTOCOL_BY_DRIVER
);

// EFI_OPEN_PROTOCOL_BY_DRIVER \| EFI_OPEN_PROTOCOL_EXCLUSIVE example
// Opens the XYZ I/O Protocol on ControllerHandle
// The driver that is opening the protocol is identified by the
// Driver Binding Protocol instance This->DriverBindingHandle
// identifies the agent that is opening the protocol interface, and it
// is opening this protocol on behalf of ControllerHandle.
// Possible return status codes:
//   EFI_SUCCESS : The protocol was opened and returned in XyzIo. If //
// a different driver had the XYZ I/O Protocol opened
//   BY_DRIVER, then that driver was disconnected to
//   allow this driver to open the XYZ I/O Protocol.
//   EFI_UNSUPPORTED : The protocol is not present on ControllerHandle
//   EFI_ALREADY_STARTED : The protocol is already opened by the driver
//    EFI_ACCESS_DENIED : The protocol is managed by a different driver that //
// already has the protocol opened with an EXCLUSIVE // attribute.
// Status = gBS->OpenProtocol ( ControllerHandle,
// &gEfiXyzIoProtocol,
// &XyzIo,
// This->DriverBindingHandle,
// ControllerHandle,
// EFI_OPEN_PROTOCOL_BY_DRIVER \| EFI_OPEN_PROTOCOL_EXCLUSIVE
 );

7.3.10 EFI_BOOT_SERVICES.CloseProtocol()

Summary
Closes a protocol on a handle that was opened using EFI_BOOT_SERVICES.OpenProtocol().

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_CLOSE_PROTOCOL) ( 
  IN EFI_HANDLE Handle,
  IN EFI_GUID *Protocol,
  IN EFI_HANDLE AgentHandle,
  IN EFI_HANDLE ControllerHandle
 );

Parameters
Handle
The handle for the protocol interface that was previously opened with OpenProtocol(), and is now being closed.

Protocol
The published unique identifier of the protocol. It is the caller’s responsibility to pass in a valid GUID. For a description of valid GUID values, see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “RFC 4122”.

AgentHandle
The handle of the agent that is closing the protocol interface. For agents that follow the UEFI Driver Model, this parameter is the handle that contains the EFI_DRIVER_BINDING_PROTOCOL instance that is produced by the UEFI driver that is opening the protocol interface. For UEFI applications, this is the image handle of the UEFI application. For applications that used EFI_BOOT_SERVICES.HandleProtocol() to open the protocol interface, this will be the image handle of the EFI firmware.

ControllerHandle
If the agent that opened a protocol is a driver that follows the UEFI Driver Model, then this parameter is the controller handle that required the protocol interface. If the agent does not follow the UEFI Driver Model, then this parameter is optional and may be NULL.

Description
This function updates the handle database to show that the protocol instance specified by Handle and Protocol is no longer required by the agent and controller specified AgentHandle and ControllerHandle.

If Handle or AgentHandle is NULL, then EFI_INVALID_PARAMETER is returned. If ControllerHandle is not NULL, and ControllerHandle is NULL, then EFI_INVALID_PARAMETER is returned. If Protocol is NULL, then EFI_INVALID_PARAMETER is returned.

If the interface specified by Protocol is not supported by the handle specified by Handle, then EFI_NOT_FOUND is returned.

If the interface specified by Protocol is supported by the handle specified by Handle, then a check is made to see if the protocol instance specified by Protocol and Handle was opened by AgentHandle and ControllerHandle with EFI_BOOT_SERVICES.OpenProtocol(). If the protocol instance was not opened by AgentHandle and ControllerHandle, then EFI_NOT_FOUND is returned. If the protocol instance was opened by AgentHandle and ControllerHandle, then all of those references are removed from the handle database, and EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The protocol instance was closed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Handle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>AgentHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ControllerHandle is not NULL and ControllerHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Protocol is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Handle does not support the protocol specified by Protocol.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The protocol interface specified by Handle and Protocol is not currently open by AgentHandle and ControllerHandle.</td>
</tr>
</tbody>
</table>

Examples

```
EFI_BOOT_SERVICES *gBS;
EFI_HANDLE ImageHandle;
EFI_DRIVER_BINDING_PROTOCOL *This;
IN EFI_HANDLE ControllerHandle,
extern EFI_GUID gEfiXyzIoProtocol;
EFI_STATUS Status;
```

(continues on next page)
// Close the XYZ I/O Protocol that was opened on behalf of ControllerHandle
>Status = gBS->CloseProtocol(
    ControllerHandle,
    &gEfiXyzIoProtocol,
    This->DriverBindingHandle,
    ControllerHandle,
);

// Close the XYZ I/O Protocol that was opened with BY_HANDLE_PROTOCOL
>Status = gBS->CloseProtocol(
    ControllerHandle,
    &gEfiXyzIoProtocol,
    ImageHandle,
    NULL
);

7.3.11 EFI_BOOT_SERVICES.OpenProtocolInformation()

Summary
Retrieves the list of agents that currently have a protocol interface opened.

Prototype

typedef
 EFI_STATUS
 (EFIAPI *EFI_OPEN_PROTOCOL_INFORMATION) (  
   IN EFI_HANDLE Handle,  
   IN EFI_GUID *Protocol,  
   OUT EFI_OPEN_PROTOCOL_INFORMATION_ENTRY **EntryBuffer,  
   OUT UINTN *EntryCount  
   );

Parameters

Handle
The handle for the protocol interface that is being queried.

Protocol
The published unique identifier of the protocol. It is the caller’s responsibility to pass in a valid GUID. For a description of valid GUID values, see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “RFC 4122”.

EntryBuffer
A pointer to a buffer of open protocol information in the form of EFI_OPEN_PROTOCOL_INFORMATION_ENTRY structures. See “Related Definitions” for the declaration of this type. The buffer is allocated by this service, and it is the caller’s responsibility to free this buffer when the caller no longer requires the buffer’s contents.
EntryCount
A pointer to the number of entries in EntryBuffer.

Related Definitions

typedef struct {
    EFI_HANDLE AgentHandle;
    EFI_HANDLE ControllerHandle;
    UINT32 Attributes;
    UINT32 OpenCount;
} EFI_OPEN_PROTOCOL_INFORMATION_ENTRY;

Description
This function allocates and returns a buffer of EFI_OPEN_PROTOCOL_INFORMATION_ENTRY structures. The buffer is returned in EntryBuffer, and the number of entries is returned in EntryCount.

If the interface specified by Protocol is not supported by the handle specified by Handle, then EFI_NOT_FOUND is returned.

If the interface specified by Protocol is supported by the handle specified by Handle, then EntryBuffer is allocated with the boot service EFI_BOOT_SERVICES.AllocatePool(), and EntryCount is set to the number of entries in EntryBuffer. Each entry of EntryBuffer is filled in with the image handle, controller handle, and attributes that were passed to EFI_BOOT_SERVICES.OpenProtocol() when the protocol interface was opened. The field OpenCount shows the number of times that the protocol interface has been opened by the agent specified by ImageHandle, ControllerHandle, and Attributes. After the contents of EntryBuffer have been filled in, EFI_SUCCESS is returned. It is the caller’s responsibility to call EFI_BOOT_SERVICES.FreePool() on EntryBuffer when the caller no longer required the contents of EntryBuffer.

If there are not enough resources available to allocate EntryBuffer, then EFI_OUT_OF_RESOURCES is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The open protocol information was returned in EntryBuffer, and the number</td>
</tr>
<tr>
<td></td>
<td>of entries was returned EntryCount.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Handle does not support the protocol specified by Protocol.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There are not enough resources available to allocate EntryBuffer.</td>
</tr>
</tbody>
</table>

Examples
See example in the EFI_BOOT_SERVICES.LocateHandleBuffer() function description for an example on how LocateHandleBuffer(), OpenProtocol(), and EFI_BOOT_SERVICES.OpenProtocolInformation() can be used to traverse the entire handle database.

7.3.12 EFI_BOOT_SERVICES.ConnectController()

Summary
Connects one or more drivers to a controller.

Prototype

typedef
EFI_STATUS
(EIFIAP @EFI_CONNECT_CONTROLLER) (  
    IN EFI_HANDLE ControllerHandle,
    IN EFI_HANDLE *DriverImageHandle OPTIONAL,
) (continues on next page)
Parameters

ControllerHandle
The handle of the controller to which driver(s) are to be connected.

DriverImageHandle
A pointer to an ordered list handles that support the EFI_DRIVER_BINDING_PROTOCOL. The list is terminated by a NULL handle value. These handles are candidates for the Driver Binding Protocol(s) that will manage the controller specified by ControllerHandle. This is an optional parameter that may be NULL. This parameter is typically used to debug new drivers.

RemainingDevicePath
A pointer to the device path that specifies a child of the controller specified by ControllerHandle. This is an optional parameter that may be NULL. If it is NULL, then handles for all the children of ControllerHandle will be created. This parameter is passed unchanged to the EFI_DRIVER_BINDING_PROTOCOL.Supported() and EFI_DRIVER_BINDING_PROTOCOL.Start() services of the EFI_DRIVER_BINDING_PROTOCOL attached to ControllerHandle.

Recursive
If TRUE, then ConnectController() is called recursively until the entire tree of controllers below the controller specified by ControllerHandle have been created. If FALSE, then the tree of controllers is only expanded one level.

Description
This function connects one or more drivers to the controller specified by ControllerHandle. If ControllerHandle is NULL, then EFI_INVALID_PARAMETER is returned. If there are no EFI_DRIVER_BINDING_PROTOCOL instances present in the system, then return EFI_NOT_FOUND. If there are not enough resources available to complete this function, then EFI_OUT_OF_RESOURCES is returned.

If the platform supports user authentication, as specified in User Identification the device path associated with ControllerHandle is checked against the connect permissions in the current user profile. If forbidden, then EFI_SECURITY_VIOLATION is returned. Then, before connecting any of the DriverImageHandles, the device path associated with the handle is checked against the connect permissions in the current user profile.

If Recursive is FALSE, then this function returns after all drivers have been connected to ControllerHandle. If Recursive is TRUE, then ConnectController() is called recursively on all of the child controllers of ControllerHandle. The child controllers can be identified by searching the handle database for all the controllers that have opened ControllerHandle with an attribute of EFI_OPEN_PROTOCOL_BY.Child_CONTROLLER.

This functions uses five precedence rules when deciding the order that drivers are tested against controllers. These five rules from highest precedence to lowest precedence are as follows:

1. Context Override: DriverImageHandle is an ordered list of handles that support the EFI_DRIVER_BINDING_PROTOCOL. The highest priority image handle is the first element of the list, and the lowest priority image handle is the last element of the list. The list is terminated with a NULL image handle.

2. Platform Driver Override: If an EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL instance is present in the system, then the EFI Platform Driver Override Protocol service of this protocol is used to retrieve an ordered list of image handles for ControllerHandle. From this list, the image handles found in rule (1) above are removed. The first image handle returned from GetDriver() has the highest precedence, and the last image handle returned from GetDriver() has the lowest precedence. The ordered list is terminated when GetDriver() returns EFI_NOT_FOUND. It is legal for no image handles to be returned by GetDriver(). There can be at most a single
instance in the system of the EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL. If there is more than one, then the system behavior is not deterministic.

3. **Driver Family Override Search**: The list of available driver image handles can be found by using the boot service EFI_BOOT_SERVICES.LocateHandle() with a SearchType of ByProtocol for the GUID of the EFI_DRIVER_FAMILY_OVERRIDE_PROTOCOL. From this list, the image handles found in rules (1), and (2) above are removed. The remaining image handles are sorted from highest to lowest based on the value returned from the GetVersion() function of the EFI_DRIVER_FAMILY_OVERRIDE_PROTOCOL associated with each image handle.

4. **Bus Specific Driver Override**: If there is an instance of the EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL attached to ControllerHandle, then the EFI Platform Driver Override Protocol service of this protocol is used to retrieve an ordered list of image handle for ControllerHandle. From this list, the image handles found in rules (1), (2), and (3) above are removed. The first image handle returned from GetDriver() has the highest precedence, and the last image handle returned from GetDriver() has the lowest precedence. The ordered list is terminated when GetDriver() returns EFI_NOT_FOUND. It is legal for no image handles to be returned by GetDriver().

5. **Driver Binding Search**: The list of available driver image handles can be found by using the boot service EFI_BOOT_SERVICES.LocateHandle() with a SearchType of ByProtocol for the GUID of the EFI_DRIVER_BINDING_PROTOCOL. From this list, the image handles found in rules (1), (2), (3), and (4) above are removed. The remaining image handles are sorted from highest to lowest based on the Version field of the EFI_DRIVER_BINDING_PROTOCOL instance associated with each image handle.

Each of the five groups of image handles listed above is tested against ControllerHandle in order by using the EFI_DRIVER_BINDING_PROTOCOL.Supported(). RemainingDevicePath is passed into Supported() unmodified. The first image handle whose Supported() service returns EFI_SUCCESS is marked so the image handle will not be tried again during this call to ConnectController(). Then, EFI_DRIVER_BINDING_PROTOCOL.Start() service of the EFI_DRIVER_BINDING_PROTOCOL is called for ControllerHandle. Once again, RemainingDevicePath is passed in unmodified. Every time Supported() returns EFI_SUCCESS, the search for drivers restarts with the highest precedence image handle. This process is repeated until no image handles pass the Supported() check.

If at least one image handle returned EFI_SUCCESS from its Start() service, then EFI_SUCCESS is returned.

If no image handles returned EFI_SUCCESS from their Start() service then EFI_NOT_FOUND is returned unless RemainingDevicePath is not NULL, and RemainingDevicePath is an End Node. In this special case, EFI_SUCCESS is returned because it is not an error to fail to start a child controller that is specified by an End Device Path Node.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>One or more drivers were connected to ControllerHandle.</td>
</tr>
<tr>
<td>EFI_SUCCESS</td>
<td>No drivers were connected to ControllerHandle, but RemainingDevicePath is not NULL, and it is an End Device Path Node.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ControllerHandle is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>There are no EFI_DRIVER_BINDING_PROTOCOL instances present in the system.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No drivers were connected to ControllerHandle.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The user has no permission to start UEFI device drivers on the device path associated with the ControllerHandle or specified by the RemainingDevicePath.</td>
</tr>
</tbody>
</table>

### Examples

```c
// Connect All Handles Example
// The following example recursively connects all controllers in a platform.
```
EFI_STATUS Status;
EFI_BOOT_SERVICES *gBS;
UINTN HandleCount;
EFI_HANDLE *HandleBuffer;
UINTN HandleIndex;

// Retrieve the list of all handles from the handle database
//
Status = gBS->LocateHandleBuffer (
    AllHandles,
    NULL,
    NULL,
    &HandleCount,
    &HandleBuffer);
if (!EFI_ERROR (Status)) {
    for (HandleIndex = 0; HandleIndex < HandleCount; HandleIndex++) {
        Status = gBS->ConnectController (
            HANDLE(HandleBuffer[HandleIndex]),
            NULL,
            NULL,
            TRUE
        );
    }
gBS->FreePool(HandleBuffer);
}

// Connect Device Path Example
// The following example walks the device path nodes of a device path, and
// connects only the drivers required to force a handle with that device path
// to be present in the handle database. This algorithm guarantees that
// only the minimum number of devices and drivers are initialized.
//
EFI_STATUS Status;
EFI_DEVICE_PATH_PROTOCOL *DevicePath;
EFI_DEVICE_PATH_PROTOCOL *RemainingDevicePath;
EFI_HANDLE Handle;

do {
    //
    // Find the handle that best matches the Device Path. If it is only a
    // partial match the remaining part of the device path is returned in
    // RemainingDevicePath.
    //
    RemainingDevicePath = DevicePath;
    Status = gBS->LocateDevicePath (
        &gEfiDevicePathProtocolGuid,
&RemainingDevicePath,
 &Handle
);
if (EFI_ERROR(Status)) {
 return EFI_NOT_FOUND;
}

// Connect all drivers that apply to Handle and RemainingDevicePath
// If no drivers are connected Handle, then return EFI_NOT_FOUND
// The Recursive flag is FALSE so only one level will be expanded.
//
Status = gBS->ConnectController (  
Handle,  
NULL,  
RemainingDevicePath,  
FALSE  
);

if (EFI_ERROR(Status)) {
 return EFI_NOT_FOUND;
}

// Loop until RemainingDevicePath is an empty device path
//
} while (!IsDevicePathEnd (RemainingDevicePath));

//
// A handle with DevicePath exists in the handle database
//
return EFI_SUCCESS;

7.3.13 EFI_BOOT_SERVICES.DisconnectController()

Summary
Disconnects one or more drivers from a controller.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_DISCONNECT_CONTROLLER) (  
 IN EFI_HANDLE ControllerHandle,  
 IN EFI_HANDLE DriverImageHandle OPTIONAL,  
 IN EFI_HANDLE ChildHandle OPTIONAL  
);

Parameters
ControllerHandle
The handle of the controller from which driver(s) are to be disconnected.
**DriverImageHandle**

The driver to disconnect from `ControllerHandle`. If `DriverImageHandle` is NULL, then all the drivers currently managing `ControllerHandle` are disconnected from `ControllerHandle`.

**ChildHandle**

The handle of the child to destroy. If `ChildHandle` is NULL, then all the children of `ControllerHandle` are destroyed before the drivers are disconnected from `ControllerHandle`.

**Description**

This function disconnects one or more drivers from the controller specified by `ControllerHandle`. If `DriverImageHandle` is NULL, then all of the drivers currently managing `ControllerHandle` are disconnected from `ControllerHandle`. If `DriverImageHandle` is not NULL, then only the driver specified by `DriverImageHandle` is disconnected from `ControllerHandle`. If `ChildHandle` is NULL, then all of the children of `ControllerHandle` are destroyed before the drivers are disconnected from `ControllerHandle`. If `ChildHandle` is not NULL, then only the child controller specified by `ChildHandle` is destroyed. If `ChildHandle` is the only child of `ControllerHandle`, then the driver specified by `DriverImageHandle` will be disconnected from `ControllerHandle`. A driver is disconnected from a controller by calling the `Stop()` service of the `EFI_DRIVER_BINDING_PROTOCOL`. The `EFI_DRIVER_BINDING_PROTOCOL` is on the driver image handle, and the handle of the controller is passed into the `Stop()` service. The list of drivers managing a controller, and the list of children for a specific controller can be retrieved from the handle database with the boot service `EFI_BOOT_SERVICES.OpenProtocolInformation()`. If all the required drivers are disconnected from `ControllerHandle`, then `EFI_SUCCESS` is returned.

If `ControllerHandle` is NULL, then `EFI_INVALID_PARAMETER` is returned. If no drivers are managing `ControllerHandle`, then `EFI_SUCCESS` is returned. If `DriverImageHandle` is not NULL, and `DriverImageHandle` is not a valid `EFI_HANDLE`, then `EFI_INVALID_PARAMETER` is returned. If `DriverImageHandle` is not NULL, and `DriverImageHandle` is not currently managing `ControllerHandle`, then `EFI_SUCCESS` is returned. If `ChildHandle` is not NULL, and `ChildHandle` is not a valid `EFI_HANDLE`, then `EFI_INVALID_PARAMETER` is returned. If there are not enough resources available to disconnect drivers from `ControllerHandle`, then `EFI_OUT_OF_RESOURCES` is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>One or more drivers were disconnected from the controller.</td>
</tr>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>On entry, no drivers are managing <code>ControllerHandle</code>.</td>
</tr>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td><code>DriverImageHandle</code> is not NULL, and on entry <code>DriverImageHandle</code> is not managing <code>ControllerHandle</code>.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td><code>ControllerHandle</code> is NULL.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td><code>DriverImageHandle</code> is not NULL, and it is not a valid <code>EFI_HANDLE</code>.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td><code>ChildHandle</code> is not NULL, and it is not a valid <code>EFI_HANDLE</code>.</td>
</tr>
<tr>
<td><code>EFI_OUT_OF_RESOURCES</code></td>
<td>There are not enough resources available to disconnect any drivers from <code>ControllerHandle</code>.</td>
</tr>
<tr>
<td><code>EFI_DEVICE_ERROR</code></td>
<td>The controller could not be disconnected because of a device error.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td><code>DriverImageHandle</code> does not support the <code>EFI_DRIVER_BINDING_PROTOCOL</code>.</td>
</tr>
</tbody>
</table>

**Examples**

```c
// Disconnect All Handles Example
// The following example recursively disconnects all drivers from all
// controllers in a platform

EFI_STATUS Status;
EFI_BOOT_SERVICES *gBS;
```

(continues on next page)
UINTN HandleCount;
EFI_HANDLE *HandleBuffer;
UINTN HandleIndex;

// Retrieve the list of all handles from the handle database

Status = gBS->LocateHandleBuffer (AllHandles, NULL, NULL, &HandleCount, &HandleBuffer);
if (!EFI_ERROR (Status)) {
    for (HandleIndex = 0; HandleIndex < HandleCount; HandleIndex++) {
        Status = gBS->DisconnectController (HandleBuffer[HandleIndex], NULL, NULL);
    }
} gBS->FreePool(HandleBuffer);

7.3.14 EFI_BOOT_SERVICES.ProtocolsPerHandle()

Summary
Retrieves the list of protocol interface GUIDs that are installed on a handle in a buffer allocated from pool.

Prototype

typedef EFI_STATUS (EFIAPIC *EFI_PROTOCOLS_PER_HANDLE) (IN EFI_HANDLE Handle, OUT EFI_GUID ***ProtocolBuffer, OUT UINTN *ProtocolBufferCount);

Parameters

Handle
The handle from which to retrieve the list of protocol interface GUIDs.

ProtocolBuffer
A pointer to the list of protocol interface GUID pointers that are installed on Handle. This buffer is allocated with a call to the Boot Service EFI_BOOT_SERVICES.AllocatePool(). It is the caller’s responsibility to call the Boot Service EFI_BOOT_SERVICES.FreePool() when the caller no longer requires the contents of ProtocolBuffer.

ProtocolBufferCount
A pointer to the number of GUID pointers present in ProtocolBuffer.
Description

The ProtocolsPerHandle() function retrieves the list of protocol interface GUIDs that are installed on Handle. The list is returned in ProtocolBuffer, and the number of GUID pointers in ProtocolBuffer is returned in ProtocolBufferCount.

If Handle is NULL or Handle is NULL, then EFI_INVALID_PARAMETER is returned.

If ProtocolBuffer is NULL, then EFI_INVALID_PARAMETER is returned.

If ProtocolBufferCount is NULL, then EFI_INVALID_PARAMETER is returned.

If there are not enough resources available to allocate ProtocolBuffer, then EFI_OUT_OF.Resources is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The list of protocol interface GUIDs installed on Handle was returned in ProtocolBuffer. The number of protocol interface GUIDs was returned in ProtocolBufferCount.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Handle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ProtocolBuffer is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ProtocolBufferCount is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There is not enough pool memory to store the results.</td>
</tr>
</tbody>
</table>

Examples

See example in the EFI_BOOT_SERVICES.LocateHandleBuffer() function description for an example on how LocateHandleBuffer(), EFI_BOOT_SERVICES.ProtocolsPerHandle(), EFI_BOOT_SERVICES.OpenProtocol(), and EFI_BOOT_SERVICES.OpenProtocolInformation() can be used to traverse the entire handle database.

7.3.15 EFI_BOOT_SERVICES.LocateHandleBuffer()

Summary

Returns an array of handles that support the requested protocol in a buffer allocated from pool.

Prototype

```c
typedef EFI_STATUS
(EFIAPIC *EFI_LOCATE_HANDLE_BUFFER) (IN EFI_LOCATE_SEARCH_TYPE SearchType,
IN EFI_GUID Protocol OPTIONAL,
IN VOID SearchKey OPTIONAL,
OUT UINTN NoHandles,
OUT EFI_HANDLE **Buffer);
```

Parameters

SearchType

Specifies which handle(s) are to be returned.

Protocol

Provides the protocol to search by. This parameter is only valid for a SearchType of ByProtocol.

SearchKey

Supplies the search key depending on the SearchType.
NoHandles
The number of handles returned in Buffer.

Buffer
A pointer to the buffer to return the requested array of handles that support Protocol. This buffer is allocated with a call to the Boot Service EFI_BOOT_SERVICES.AllocatePool(). It is the caller’s responsibility to call the Boot Service EFI_BOOT_SERVICES.FreePool() when the caller no longer requires the contents of Buffer.

Description
The LocateHandleBuffer() function returns one or more handles that match the SearchType request. Buffer is allocated from pool, and the number of entries in Buffer is returned in NoHandles. Each SearchType is described below:

AllHandles
Protocol and SearchKey are ignored and the function returns an array of every handle in the system.

ByRegisterNotify
SearchKey supplies the Registration returned by EFI_BOOT_SERVICES.RegisterProtocolNotify(). The function returns the next handle that is new for the Registration. Only one handle is returned at a time, and the caller must loop until no more handles are returned. Protocol is ignored for this search type.

ByProtocol
All handles that support Protocol are returned. SearchKey is ignored for this search type.

If NoHandles is NULL, then EFI_INVALID_PARAMETER is returned.
If Buffer is NULL, then EFI_INVALID_PARAMETER is returned.
If there are no handles in the handle database that match the search criteria, then EFI_NOT_FOUND is returned.
If there are not enough resources available to allocate Buffer, then EFI_OUT_OF_RESOURCES is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The array of handles was returned in Buffer, and the number of handles in Buffer were returned in NoHandles.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>NoHandles is NULL</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Buffer is NULL</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No handles match the search.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There is not enough pool memory to store the matching results.</td>
</tr>
</tbody>
</table>

Examples

```
//
// The following example traverses the entire handle database. First all of
// the handles in the handle database are retrieved by using
// LocateHandleBuffer(). Then it uses ProtocolsPerHandle() to retrieve the
// list of protocol GUIDs attached to each handle. Then it uses OpenProtocol()
// to get the protocol instance associated with each protocol GUID on the
// handle. Finally, it uses OpenProtocolInformation() to retrieve the list of
// agents that have opened the protocol on the handle. The caller of these
// functions must make sure that they free the return buffers with FreePool()
// when they are done.
//
EFI_STATUS Status;
EFI_BOOT_SERVICES *gBS;
```
EFI_HANDLE ImageHandle;
UINTN HandleCount;
EFI_HANDLE *HandleBuffer;
UINTN HandleIndex;
EFI_GUID **ProtocolGuidArray;
UINTN ArrayCount;
UINTN ProtocolIndex;
EFI_OPEN_PROTOCOL_INFORMATION_ENTRY *OpenInfo;
UINTN OpenInfoCount;
UINTN OpenInfoIndex;

// Retrieve the list of all handles from the handle database
//
Status = gBS->LocateHandleBuffer (AllHandles, NULL, NULL, &HandleCount, &HandleBuffer);
if (!EFI_ERROR (Status)) {
    for (HandleIndex = 0; HandleIndex < HandleCount; HandleIndex++) {
        // Retrieve the list of all the protocols on each handle
        //
        Status = gBS->ProtocolsPerHandle (HandleBuffer[HandleIndex], &ProtocolGuidArray, &ArrayCount);
        if (!EFI_ERROR (Status)) {
            for (ProtocolIndex = 0; ProtocolIndex < ArrayCount; ProtocolIndex++) {
                // Retrieve the protocol instance for each protocol
                //
                Status = gBS->OpenProtocol (HandleBuffer[HandleIndex], ProtocolGuidArray[ProtocolIndex], &Instance, ImageHandle, NULL, EFI_OPEN_PROTOCOL_GET_PROTOCOL);
            }
            // Retrieve the list of agents that have opened each protocol
            //
            Status = gBS->OpenProtocolInformation (HandleBuffer[HandleIndex], ProtocolGuidArray[ProtocolIndex], &OpenInfo,
        }
    }
}

(continues on next page)
if (!EFI_ERROR (Status)) {
    for (OpenInfoIndex=0; OpenInfoIndex<OpenInfoCount; OpenInfoIndex++) {
        // HandleBuffer[HandleIndex] is the handle
        // ProtocolGuidArray[ProtocolIndex] is the protocol GUID
        // Instance is the protocol instance for the protocol
        // OpenInfo[OpenInfoIndex] is an agent that has opened a protocol
        //
        if (OpenInfo != NULL) {
            gBS->FreePool(OpenInfo);
        }
    }
    if (ProtocolGuidArray != NULL) {
        gBS->FreePool(ProtocolGuidArray);
    }
    if (HandleBuffer != NULL) {
        gBS->FreePool(HandleBuffer);
    }
}

7.3.16 EFI_BOOT_SERVICES.LocateProtocol()

Summary
Returns the first protocol instance that matches the given protocol.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_LOCATE_PROTOCOL) (
    IN EFI_GUID *Protocol,
    IN VOID *Registration OPTIONAL,
    OUT VOID **Interface
);

Parameters

Protocol
Provides the protocol to search for.

Registration
Optional registration key returned from EFI_BOOT_SERVICES.RegisterProtocolNotify(). If Registration is NULL, then it is ignored.

Interface
On return, a pointer to the first interface that matches Protocol and Registration.
Description

The LocateProtocol() function finds the first device handle that support Protocol, and returns a pointer to the protocol interface from that handle in Interface. If no protocol instances are found, then Interface is set to NULL.

If Interface is NULL, then EFI_INVALID_PARAMETER is returned.

If Protocol is NULL, then EFI_INVALID_PARAMETER is returned.

If Registration is NULL, and there are no handles in the handle database that support Protocol, then EFI_NOT_FOUND is returned.

If Registration is not NULL, and there are no new handles for Registration, then EFI_NOT_FOUND is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>A protocol instance matching Protocol was found and returned in Interface.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Interface is NULL. Protocol is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No protocol instances were found that match Protocol and Registration.</td>
</tr>
</tbody>
</table>

7.3.17 EFI_BOOT_SERVICES.InstallMultipleProtocolInterfaces()

Summary

Installs one or more protocol interfaces into the boot services environment.

Prototype

```c
typedef EFI_STATUS EFIAPI InstallMultipleProtocolInterfaces(
    IN OUT EFI_HANDLE *Handle,
    ...
);```

Parameters

Handle

The pointer to a handle to install the new protocol interfaces on, or a pointer to NULL if a new handle is to be allocated.

… A variable argument list containing pairs of protocol GUIDs and protocol interfaces.

Description

This function installs a set of protocol interfaces into the boot services environment. It removes arguments from the variable argument list in pairs. The first item is always a pointer to the protocol’s GUID, and the second item is always a pointer to the protocol’s interface. These pairs are used to call the boot service, see EFI_BOOT_SERVICES.InstallProtocolInterface() to add a protocol interface to Handle. If Handle is NULL on entry, then a new handle will be allocated. The pairs of arguments are removed in order from the variable argument list until a NULL protocol GUID value is found. If any errors are generated while the protocol interfaces are being installed, then all the protocols installed prior to the error will be uninstalled with the boot service

EFI_BOOT_SERVICES.UninstallProtocolInterface() before the error is returned. The same GUID cannot be installed more than once onto the same handle.

It is illegal to have two handles in the handle database with identical device paths. This service performs a test to guarantee a duplicate device path is not inadvertently installed on two different handles. Before any protocol interfaces are installed onto Handle, the list of GUID/pointer pair parameters are searched to see if a Device Path Protocol instance is being installed. If a Device Path Protocol instance is going to be installed onto Handle, then a check is made to see...
if a handle is already present in the handle database with an identical Device Path Protocol instance. If an identical
Device Path Protocol instance is already present in the handle database, then no protocols are installed onto Handle,
and EFI_ALREADY_STARTED is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>All the protocol interfaces were installed.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>A Device Path Protocol instance was passed in that is already present in the handle database.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There was not enough memory in pool to install all the protocols.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Handle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Protocol is already installed on the handle specified by Handle.</td>
</tr>
</tbody>
</table>

### 7.3.18 EFI_BOOT_SERVICES.UninstallMultipleProtocolInterfaces()

**Summary**

Removes one or more protocol interfaces into the boot services environment.

**Prototype**

```c
typedef EFI_STATUS
EFIAPI *EFI.UNINSTALL_MULTIPLE_PROTOCOL_INTERFACES) (  
    IN EFI_HANDLE Handle,  
    ...  
);
```

**Parameters**

- **Handle**
  - The handle to remove the protocol interfaces from.
  - … A variable argument list containing pairs of protocol GUIDs and protocol interfaces.

**Description**

This function removes a set of protocol interfaces from the boot services environment. It removes arguments from the variable argument list in pairs. The first item is always a pointer to the protocol’s GUID, and the second item is always a pointer to the protocol’s interface. These pairs are used to call the boot service `EFI_BOOT_SERVICES.UninstallProtocolInterface()` to remove a protocol interface from Handle. The pairs of arguments are removed in order from the variable argument list until a NULL protocol GUID value is found. If all of the protocols are uninstalled from Handle, then EFI_SUCCESS is returned. If any errors are generated while the protocol interfaces are being uninstalled, then the protocols uninstalled prior to the error will be reinstalled with the boot service `EFI_BOOT_SERVICES.InstallProtocolInterface()` and the status code EFI_INVALID_PARAMETER is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>All the protocol interfaces were removed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One of the protocol interfaces was not previously installed on Handle.</td>
</tr>
</tbody>
</table>
7.4 Image Services

Three types of images can be loaded: UEFI applications written (UEFI Applications), UEFI boot services drivers (UEFI Drivers), and EFI runtime drivers (UEFI Drivers). A UEFI OS Loader (UEFI OS Loaders) is a type of UEFI application. The most significant difference between these image types is the type of memory into which they are loaded by the firmware’s loader. See the Table, below, Image Type Differences Summary summarizes the differences between images.

Table 7.30: Image Type Differences Summary

<table>
<thead>
<tr>
<th>Description</th>
<th>UEFI Application</th>
<th>UEFI Boot Service Driver</th>
<th>UEFI Runtime Driver</th>
</tr>
</thead>
<tbody>
<tr>
<td>Description</td>
<td>A transient application that is loaded during boot services time. UEFI applications are either unloaded when they complete (see UEFI Applications), or they take responsibility for the continued operation of the system via Exit-BootServices() (see UEFI OS Loaders). The UEFI applications are loaded in sequential order by the boot manager, but one UEFI application may dynamically load another.</td>
<td>A program that is loaded into boot services memory and stays resident until boot services terminate. See UEFI Drivers.</td>
<td>A program that is loaded into runtime services memory and stays resident during runtime. The memory required for a UEFI runtime services driver must be performed in a single memory allocation, and marked as EfiRuntimeServicesData. (Note that the memory only stays resident when booting an EFI-compatible operating system. Legacy operating systems will reuse the memory.) See UEFI Drivers.</td>
</tr>
<tr>
<td>Loaded into memory type</td>
<td>EfiLoaderCode, EfiLoaderData</td>
<td>EfiBootServicesCode, EfiBootServicesData</td>
<td>EfiRuntimeServicesCode, EfiRuntimeServicesData</td>
</tr>
<tr>
<td>Default pool allocations from memory type</td>
<td>EfiLoaderData</td>
<td>EfiBootServicesData</td>
<td>EfiRuntimeServicesData</td>
</tr>
<tr>
<td>Exit behavior</td>
<td>When an application exits, firmware frees the memory used to hold its image.</td>
<td>When a UEFI boot service driver exits with an error code, firmware frees the memory used to hold its image. When a UEFI boot service driver’s entry point completes with EFI_SUCCESS, the image is retained in memory.</td>
<td>When a UEFI runtime driver exits with an error code, firmware frees the memory used to hold its image. When a UEFI runtime services driver’s entry point completes with EFI_SUCCESS, the image is retained in memory.</td>
</tr>
</tbody>
</table>

continues on next page
Most UEFI images are loaded by the boot manager. When a UEFI application or UEFI driver is installed, the installation procedure registers itself with the boot manager for loading. However, in some cases a UEFI application or UEFI driver may want to programmatically load and start another UEFI image. This can be done with the `EFI_BOOT_SERVICES.LoadImage()` and `EFI_BOOT_SERVICES.StartImage()` interfaces. UEFI drivers may only load UEFI applications during the UEFI driver’s initialization entry point. The Table, below, *Image Functions* lists the functions that make up Image Services.

### Table 7.31: Image Functions

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>LoadImage</td>
<td>Boot</td>
<td>Loads an EFI image into memory.</td>
</tr>
<tr>
<td>StartImage</td>
<td>Boot</td>
<td>Transfers control to a loaded image’s entry point.</td>
</tr>
<tr>
<td>UnloadImage</td>
<td>Boot</td>
<td>Unloads an image.</td>
</tr>
<tr>
<td>EFI_IMAGE_ENTRY_POINT</td>
<td>Boot</td>
<td>Prototype of an EFI Image’s entry point.</td>
</tr>
<tr>
<td>Exit</td>
<td>Boot</td>
<td>Exits the image’s entry point.</td>
</tr>
<tr>
<td>ExitBootServices</td>
<td>Boot</td>
<td>Terminates boot services.</td>
</tr>
</tbody>
</table>

The Image boot services have been modified to take advantage of the information that is now being tracked with the `EFI_BOOT_SERVICES.OpenProtocol()` and `EFI_BOOT_SERVICES.CloseProtocol()` boot services. Since the usage of protocol interfaces is being tracked with these new boot services, it is now possible to automatically close protocol interfaces when a UEFI application or a UEFI driver is unloaded or exited.

### 7.4.1 EFI_BOOT_SERVICES.LoadImage()

**Summary**

Loads an EFI image into memory.

**Prototype**

```c
typedef EFI_STATUS
  (EFIAPI *EFI_IMAGE_LOAD) (
    IN BOOLEAN BootPolicy,
    IN EFI_HANDLE ParentImageHandle,
    IN EFI_DEVICE_PATH_PROTOCOL *DevicePath OPTIONAL,
    IN VOID *SourceBuffer OPTIONAL
    IN UINTN SourceSize,
    OUT EFI_HANDLE *ImageHandle

Parameters

**BootPolicy**

If `TRUE`, indicates that the request originates from the boot manager, and that the boot manager is attempting to load `DevicePath` as a boot selection. Ignored if `SourceBuffer` is not NULL.
ParentImageHandle

The caller’s image handle. Type EFI_HANDLE is defined in the EFI_BOOT_SERVICES.InstallProtocolInterface() function description. This field is used to initialize the ParentHandle field of the EFI Loaded Image Protocol for the image that is being loaded.

DevicePath

The DeviceHandle specific file path from which the image is loaded. EFI_DEVICE_PATH_PROTOCOL is defined in EFI Device Path Protocol.

SourceBuffer

If not NULL, a pointer to the memory location containing a copy of the image to be loaded.

SourceSize

The size in bytes of SourceBuffer. Ignored if SourceBuffer is NULL.

ImageHandle

PointerType to the returned image handle that is created when the image is successfully loaded. Type EFI_HANDLE is defined in the InstallProtocolInterface() function description.

Related Definitions

#define EFI_HII_PACKAGE_LIST_PROTOCOL_GUID  
{ 0x6a1ee763, 0xd47a, 0x43b4,  
{ 0xaa, 0xbe, 0xef, 0x1d, 0xe2, 0xab, 0x56, 0xfc } }

typedef EFI_HII_PACKAGE_LIST_HEADER *EFI_HII_PACKAGE_LIST_PROTOCOL;

Description

The LoadImage() function loads an EFI image into memory and returns a handle to the image. The image is loaded in one of two ways.

- If SourceBuffer is not NULL, the function is a memory-to-memory load in which SourceBuffer points to the image to be loaded and SourceSize indicates the image’s size in bytes. In this case, the caller has copied the image into SourceBuffer and can free the buffer once loading is complete. The DevicePath is optional in this case. A DevicePath should still be provided since certain portions of firmware may use it to make certain security policy decisions.

- If SourceBuffer is NULL, the function is a file copy operation that uses the EFI_SIMPLE_FILE_SYSTEM_PROTOCOL.

If there is no instance of EFI_SIMPLE_FILE_SYSTEM_PROTOCOL associated with file path, then this function will attempt to use EFI_LOAD_FILE_PROTOCOL (BootPolicy is TRUE) or EFI_LOAD_FILE2_PROTOCOL, and then EFI_LOAD_FILE_PROTOCOL (BootPolicy is FALSE).

In all cases, this function will use the instance of these protocols associated with the handle that most closely matches DevicePath will be used. See the boot service description for more information on how the closest handle is located.

- In the case of EFI_SIMPLE_FILE_SYSTEM_PROTOCOL, the path name from the File Path Media Device Path node(s) of DevicePath is used.

- In the case of EFI_LOAD_FILE_PROTOCOL, the remaining device path nodes of DevicePath and the BootPolicy flag are passed to the EFI_LOAD_FILE_PROTOCOL function. The default image responsible for booting is loaded when DevicePath specifies only the device (and there are no further device nodes). For more information see the discussion of EFI_LOAD_FILE_PROTOCOL.

- In the case of EFI_LOAD_FILE2_PROTOCOL, the behavior is the same as above, except that it is only used if BootOption is FALSE. For more information, see the discussion of the EFI_LOAD_FILE2_PROTOCOL.

- If the platform supports driver signing, as specified in Image Execution Information Table and the image signature is not valid, then information about the image is recorded in the EFI_IMAGE_EXECUTION_INFO_TABLE.
(see Using the Image Execution Information Table in section 32.4.2. [cross-reference needed] and EFI_SECURITY_VIOLATION is returned.

- If the platform supports user authentication, as described in User Identification and loading of images on the specified FilePath is forbidden in the current user profile, then the information about the image is recorded (see Deferred Execution in Image Execution Information Table and EFI_SECURITY_VIOLATION is returned.

Once the image is loaded, firmware creates and returns an EFI_HANDLE that identifies the image and supports EFI Loaded Image Protocol and the EFI_LOADED_IMAGE_DEVICE_PATH_PROTOCOL. The caller may fill in the image’s “load options” data, or add additional protocol support to the handle before passing control to the newly loaded image by calling EFI_BOOT_SERVICES.StartImage(). Also, once the image is loaded, the caller either starts it by calling StartImage() or unloads it by calling EFI_BOOT_SERVICES.UnloadImage() .

Once the image is loaded, LoadImage() installs EFI_HII_PACKAGE_LIST_PROTOCOL on the handle if the image contains a custom PE/COFF resource with the type ‘HII’. The protocol’s interface pointer points to the HII package list which is contained in the resource’s data. The format of this is in EFI_HII_PACKAGE_HEADER .

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Image was loaded into memory correctly.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Both SourceBuffer and DevicePath are NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One of the parameters has an invalid value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ImageHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ParentImageHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ParentImageHandle is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The image type is not supported.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Image was not loaded due to insufficient resources.</td>
</tr>
<tr>
<td>EFI_LOAD_ERROR</td>
<td>Image was not loaded because the image format was corrupt or not understood.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Image was not loaded because the device returned a read error.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Image was not loaded because the platform policy prohibits the image from being loaded. NULL is returned in ImageHandle.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>Image was loaded and an ImageHandle was created with a valid EFI_LOADED_IMAGE_PROTOCOL. However, the current platform policy specifies that the image should not be started.</td>
</tr>
</tbody>
</table>

### 7.4.2 EFI_BOOT_SERVICES.StartImage()

**Summary**

Transfers control to a loaded image’s entry point.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPIC *EFI_IMAGE_START) (IN EFI_HANDLE ImageHandle,
OUT UINTN *ExitDataSize,
OUT CHAR16 **ExitData OPTIONAL
);
```

**Parameters**
ImageHandle
Handle of image to be started. Type EFI_HANDLE is defined in the EFI_BOOT_SERVICES.InstallProtocolInterface() function description.

ExitDataSize
Pointer to the size, in bytes, of ExitData. If ExitData is NULL, then this parameter is ignored and the contents of ExitDataSize are not modified.

ExitData
Pointer to a pointer to a data buffer that includes a Null-terminated string, optionally followed by additional binary data. The string is a description that the caller may use to further indicate the reason for the image’s exit.

Description
The StartImage() function transfers control to the entry point of an image that was loaded by EFI_BOOT_SERVICES.LoadImage(). The image may only be started one time.

Control returns from StartImage() when the loaded image’s EFI_IMAGE_ENTRY_POINT returns or when the loaded image calls EFI_BOOT_SERVICES.Exit() When that call is made, the ExitData buffer and ExitDataSize from Exit() are passed back through the ExitData buffer and ExitDataSize in this function. The caller of this function is responsible for returning the ExitData buffer to the pool by calling EFI_BOOT_SERVICES.FreePool() when the buffer is no longer needed. Using Exit() is similar to returning from the image’s EFI_IMAGE_ENTRY_POINT except that Exit() may also return additional ExitData. Exit() function description defines clean up procedure performed by the firmware once loaded image returns control.

EFI 1.10 Extension
To maintain compatibility with UEFI drivers that are written to the EFI 1.02 Specification, StartImage() must monitor the handle database before and after each image is started. If any handles are created or modified when an image is started, then EFI_BOOT_SERVICES.ConnectController() must be called with the Recursive parameter set to TRUE for each of the newly created or modified handles before StartImage() returns.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ImageHandle is either an invalid image handle or the image has already been initialized with StartImage</td>
</tr>
<tr>
<td>Exit code from image</td>
<td>Exit code from image.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The current platform policy specifies that the image should not be started.</td>
</tr>
</tbody>
</table>

7.4.3 EFI_BOOT_SERVICES.UnloadImage()

Summary
Unloads an image.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_IMAGE_UNLOAD) (IN EFI_HANDLE ImageHandle);
```

Parameters

ImageHandle
Handle that identifies the image to be unloaded.
Description

The UnloadImage() function unloads a previously loaded image.

There are three possible scenarios. If the image has not been started, the function unloads the image and returns EFI_SUCCESS.

If the image has been started and has an Unload() entry point, control is passed to that entry point. If the image’s unload function returns EFI_SUCCESS, the image is unloaded; otherwise, the error returned by the image’s unload function is returned to the caller. The image unload function is responsible for freeing all allocated memory and ensuring that there are no references to any freed memory, or to the image itself, before returning EFI_SUCCESS.

If the image has been started and does not have an Unload() entry point, the function returns EFI_UNSUPPORTED.

EFI 1.10 Extension

All of the protocols that were opened by ImageHandle using the boot service EFI_BOOT_SERVICES.OpenProtocol() are automatically closed with the boot service EFI_BOOT_SERVICES.CloseProtocol(). If all of the open protocols are closed, then EFI_SUCCESS is returned. If any call to CloseProtocol() fails, then the error code from CloseProtocol() is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The image has been unloaded.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The image has been started, and does not support unload.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ImageHandle is not a valid image handle.</td>
</tr>
<tr>
<td>Exit code from Unload handler</td>
<td>Exit code from the image's unload function.</td>
</tr>
</tbody>
</table>

7.4.4 EFI_IMAGE_ENTRY_POINT

Summary

This is the declaration of an EFI image entry point. This can be the entry point to an application written to this specification, an EFI boot service driver, or an EFI runtime driver.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_IMAGE_ENTRY_POINT) (  
    IN EFI_HANDLE ImageHandle, 
    IN EFI_SYSTEM_TABLE *SystemTable  
);  

Parameters

ImageHandle

Handle that identifies the loaded image. Type EFI_HANDLE is defined in the EFI_BOOT_SERVICES.InstallProtocolInterface() function description.

SystemTable

System Table for this image. Type EFI_SYSTEM_TABLE is defined in EFI System Table.

Description

An image’s entry point is of type EFI_IMAGE_ENTRY_POINT. After firmware loads an image into memory, control is passed to the image’s entry point. The entry point is responsible for initializing the image. The image’s ImageHandle is passed to the image. The ImageHandle provides the image with all the binding and data information it
needs. This information is available through protocol interfaces. However, to access the protocol interfaces on `ImageHandle` requires access to boot services functions. Therefore, `EFI_BOOT_SERVICES.LoadImage()` passes to the `EFI_IMAGE_ENTRY_POINT` a `SystemTable` that is inherited from the current scope of `LoadImage()`.

All image handles support the `EFILoadedImageProtocol` and the `EFI_LOADED_IMAGE_DEVICE_PATH_PROTOCOL`. These protocol can be used to obtain information about the loaded image’s state—for example, the device from which the image was loaded and the image’s load options. In addition, the `ImageHandle` may support other protocols provided by the parent image.

If the image supports dynamic unloading, it must supply an unload function in the `EFI_LOADED_IMAGE_PROTOCOL` structure before returning control from its entry point.

In general, an image returns control from its initialization entry point by calling `EFI_BOOT_SERVICES.Exit()` or by returning control from its entry point. If the image returns control from its entry point, the firmware passes control to `Exit()` using the return code as the `ExitStatus` parameter to `Exit()`.

See `Exit()` below for entry point exit conditions.

### 7.4.5 EFI_BOOT_SERVICES.Exit()

**Summary**

Terminates a loaded EFI image and returns control to boot services.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_EXIT) (
    IN EFI_HANDLE ImageHandle,
    IN EFI_STATUS ExitStatus,
    IN UINTN ExitDataSize,
    IN CHAR16 *ExitData OPTIONAL
);
```

**Parameters**

**ImageHandle**

Handle that identifies the image. This parameter is passed to the image on entry.

**ExitStatus**

The image’s exit code.

**ExitDataSize**

The size, in bytes, of `ExitData`. Ignored if `ExitStatus` is `EFI_SUCCESS`.

**ExitData**

Pointer to a data buffer that includes a Null-terminated string, optionally followed by additional binary data. The string is a description that the caller may use to further indicate the reason for the image’s exit. `ExitData` is only valid if `ExitStatus` is something other than `EFI_SUCCESS`. The `ExitData` buffer must be allocated by calling `EFI_BOOT_SERVICES.AllocatePool()`.

**Description**

The `Exit()` function terminates the image referenced by `ImageHandle` and returns control to boot services. This function may not be called if the image has already returned from its entry point (`EFI_IMAGE_ENTRY_POINT`) or if it has loaded any child images that have not exited (all child images must exit before this image can exit).

Using `Exit()` is similar to returning from the image’s `EFI_IMAGE_ENTRY_POINT` except that `Exit()` may also return additional `ExitData`.

---

7.4. Image Services
When an application exits a compliant system, firmware frees the memory used to hold the image. The firmware also frees its references to the `ImageHandle` and the handle itself. Before exiting, the application is responsible for freeing any resources it allocated. This includes memory (pages and/or pool), open file system handles, and so forth. The only exception to this rule is the ExitData buffer, which must be freed by the caller of `EFI_BOOT_SERVICES.StartImage()` . (If the buffer is needed, firmware must allocate it by calling `EFI_BOOT_SERVICES.AllocatePool()` and must return a pointer to it to the caller of `StartImage()`.)

When an EFI boot service driver or runtime service driver exits, firmware frees the image only if the `ExitStatus` is an error code; otherwise the image stays resident in memory. The driver must not return an error code if it has installed any protocol handlers or other active callbacks into the system that have not (or cannot) be cleaned up. If the driver exits with an error code, it is responsible for freeing all resources before exiting. This includes any allocated memory (pages and/or pool), open file system handles, and so forth.

It is valid to call `Exit()` or `UnloadImage()` for an image that was loaded by `EFI_BOOT_SERVICES.LoadImage()` before calling `EFI_BOOT_SERVICES.StartImage()` . This will free the image from memory without having started it.

**EFI 1.10 Extension**

If `ImageHandle` is a UEFI application, then all of the protocols that were opened by `ImageHandle` using the boot service `EFI_BOOT_SERVICES.OpenProtocol()` are automatically closed with the boot service `EFI_BOOT_SERVICES.CloseProtocol()` . If `ImageHandle` is a UEFI boot service driver or UEFI runtime service driver, and `ExitStatus` is an error code, then all of the protocols that were opened by `ImageHandle` using the boot service `OpenProtocol()` are automatically closed with the boot service `CloseProtocol()` . If `ImageHandle` is a UEFI boot service driver or UEFI runtime service driver, and `ExitStatus` is not an error code, then no protocols are automatically closed by this service.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>(Does not return.)</td>
<td>Image exit. Control is returned to the <code>StartImage()</code> call that invoked the image specified by <code>ImageHandle</code>.</td>
</tr>
<tr>
<td>EFI_SUCCESS</td>
<td>The image specified by <code>ImageHandle</code> was unloaded. This condition only occurs for images that have been loaded with <code>LoadImage()</code> but have not been started with <code>StartImage()</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The image specified by <code>ImageHandle</code> has been loaded and started with <code>LoadImage()</code> and <code>StartImage()</code>, but the image is not the currently executing image.</td>
</tr>
</tbody>
</table>

**7.4.6 EFI_BOOT_SERVICES.ExitBootServices()**

**Summary**

Terminates all boot services.

**Prototype**

```c
EFI_STATUS
(EFI_API *EFI_EXIT_BOOT_SERVICES) (
    IN EFI_HANDLE ImageHandle,
    IN UINTN MapKey
);
```

**Parameters**

*ImageHandle*

Handle that identifies the exiting image. Type `EFI_HANDLE` is defined in the `Image Execution Information Table` function description.
MapKey
Key to the latest memory map.

Description
The ExitBootServices() function is called by the currently executing UEFI OS loader image to terminate all boot services. On success, the UEFI OS loader becomes responsible for the continued operation of the system. All events from the EFI_EVENT_GROUP_BEFORE_EXIT_BOOT_SERVICES and EFIEVENT_GROUP_EXIT_BOOT_SERVICES event notification groups as well as events of type EVT_SIGNAL_EXIT_BOOT_SERVICES must be signaled before ExitBootServices() returns EFI_SUCCESS. The events are only signaled once even if ExitBootServices() is called multiple times.

A UEFI OS loader must ensure that it has the system’s current memory map at the time it calls ExitBootServices(). This is done by passing in the current memory map’s MapKey value as returned by EFI_BOOT_SERVICES.GetMemoryMap(). Care must be taken to ensure that the memory map does not change between these two calls. It is suggested that GetMemoryMap() be called immediately before calling ExitBootServices(). If MapKey value is incorrect, ExitBootServices() returns EFI_INVALID_PARAMETER and GetMemoryMap() with ExitBootServices() must be called again. Firmware implementation may choose to do a partial shutdown of the boot services during the first call to ExitBootServices(). A UEFI OS loader should not make calls to any boot service function other than Memory Allocation Services after the first call to ExitBootServices().

On success, the UEFI OS loader owns all available memory in the system. In addition, the UEFI OS loader can treat all memory in the map marked as EfiBootServicesCode and EfiBootServicesData as available free memory. No further calls to boot service functions or Efi device-handle-based protocols may be used, and the boot services watchdog timer is disabled. On success, several fields of the EFI System Table should be set to NULL. These include ConsoleInHandle, ConIn, ConsoleOutHandle, ConOut, StandardErrorHandle, StdErr, and Boot Services Table. In addition, since fields of the EFI System Table are being modified, the 32-bit CRC for the EFI System Table must be recomputed.

Firmware must guarantee the following order of processing:

- EFI_EVENT_GROUP_BEFORE_EXIT_BOOT_SERVICES handlers are called.
- Timer services are deactivated (timer event activity stopped).
- EVT_SIGNAL_EXIT_BOOT_SERVICES and EFI_EVENT_GROUP BEFORE_EXIT_BOOT_SERVICES handlers are called.

NOTE: The EVT_SIGNAL_EXIT_BOOT_SERVICES event type and EFI_EVENT_GROUP BEFORE_EXIT_BOOT_SERVICES event group are functionally equivalent. Firmware does not distinguish between the two while ordering the handlers.

Refer to EFI_EVENT_GROUP_EXIT_BOOT_SERVICES description in the EFI_BOOT_SERVICES.CreateEventEx() section above for additional restrictions on EXIT_BOOT_SERVICES handlers.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Boot services have been terminated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>MapKey is incorrect.</td>
</tr>
</tbody>
</table>

7.5 Miscellaneous Boot Services

This section contains the remaining function definitions for boot services not defined elsewhere but which are required to complete the definition of the EFI environment. The Table, below, lists the Miscellaneous Boot Services Functions.

Table 7.37: Miscellaneous Boot Services Functions

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SetWatchDogTimer</td>
<td>Boot</td>
<td>Resets and sets a watchdog timer used during boot services time.</td>
</tr>
</tbody>
</table>

continues on next page
The `EFI_BOOT_SERVICES.CalculateCrc32()` service was added because there are several places in EFI that 32-bit CRCs are used. These include the EFI System Table, the EFI Boot Services Table, the EFI Runtime Services Table, and the GUID Partition Table (GPT) structures. The CalculateCrc32() service allows new 32-bit CRCs to be computed, and existing 32-bit CRCs to be validated.

### 7.5.1 EFI_BOOT_SERVICES.SetWatchdogTimer()

**Summary**
Sets the system’s watchdog timer.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_SET_WATCHDOG_TIMER) ((
    IN UINTN Timeout,
    IN UINT64 WatchdogCode,
    IN UINTN DataSize,
    IN CHAR16 *WatchdogData OPTIONAL
);
```

**Parameters**

- **Timeout**
  The number of seconds to set the watchdog timer to. A value of zero disables the timer.

- **WatchdogCode**
  The numeric code to log on a watchdog timer timeout event. The firmware reserves codes 0x0000 to 0xFFFF. Loaders and operating systems may use other timeout codes.

- **DataSize**
  The size, in bytes, of `WatchdogData`.

- **WatchdogData**
  A data buffer that includes a Null-terminated string, optionally followed by additional binary data. The string is a description that the call may use to further indicate the reason to be logged with a watchdog event.

**Description**

The SetWatchdogTimer() function sets the system’s watchdog timer.

If the watchdog timer expires, the event is logged by the firmware. The system may then either reset with the Runtime Service `ResetSystem()` or perform a platform specific action that must eventually cause the platform to be reset. The watchdog timer is armed before the firmware’s boot manager invokes an EFI boot option. The watchdog must be set to a period of 5 minutes. The EFI Image may reset or disable the watchdog timer as needed. If control is returned to the firmware’s boot manager, the watchdog timer must be disabled.

7.5. Miscellaneous Boot Services
The watchdog timer is only used during boot services. On successful completion of ` EFI_BOOT_SERVICES.ExitBootServices()` the watchdog timer is disabled.

The accuracy of the watchdog timer is +/- 1 second from the requested Timeout.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The timeout has been set.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The supplied <code>WatchdogCode</code> is invalid.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The system does not have a watchdog timer.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The watch dog timer could not be programmed due to a hardware error.</td>
</tr>
</tbody>
</table>

#### 7.5.2 EFI_BOOT_SERVICES.Stall()

**Summary**
Induces a fine-grained stall.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_STALL) (IN UINTN Microseconds);
```

**Parameters**

**Microseconds**

The number of microseconds to stall execution.

**Description**

The Stall() function stalls execution on the processor for at least the requested number of microseconds. Execution of the processor is not yielded for the duration of the stall.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Execution was stalled at least the requested number of <code>Microseconds</code>.</td>
</tr>
</tbody>
</table>

#### 7.5.3 EFI_BOOT_SERVICES.CopyMem()

**Summary**

The `CopyMem()` function copies the contents of one buffer to another buffer.

**Prototype**

```c
typedef VOID (EFIAPI *EFI_COPY_MEM) (IN VOID *Destination, IN VOID *Source, IN UINTN Length);
```
Parameters

Destination
Pointer to the destination buffer of the memory copy.

Source
Pointer to the source buffer of the memory copy.

Length
Number of bytes to copy from Source to Destination.

Description
The CopyMem() function copies Length bytes from the buffer Source to the buffer Destination.

The implementation of CopyMem() must be reentrant, and it must handle overlapping Source and Destination buffers. This means that the implementation of CopyMem() must choose the correct direction of the copy operation based on the type of overlap that exists between the Source and Destination buffers. If either the Source buffer or the Destination buffer crosses the top of the processor’s address space, then the result of the copy operation is unpredictable.

The contents of the Destination buffer on exit from this service must match the contents of the Source buffer on entry to this service. Due to potential overlaps, the contents of the Source buffer may be modified by this service. The following rules can be used to guarantee the correct behavior:

1. If Destination and Source are identical, then no operation should be performed.
2. If Destination > Source and Destination < (Source + Length), then the data should be copied from the Source buffer to the Destination buffer starting from the end of the buffers and working toward the beginning of the buffers.
3. Otherwise, the data should be copied from the Source buffer to the Destination buffer starting from the beginning of the buffers and working toward the end of the buffers.

Status Codes Returned
None.

7.5.4 EFI_BOOT_SERVICES.SetMem()

Summary
The SetMem() function fills a buffer with a specified value.

Prototype

typedef VOID
EFIAPI *EFI_SET_MEM) (  
    IN VOID *Buffer,  
    IN UINTN Size,  
    IN UINT8 Value
);  

Parameters

Buffer
Pointer to the buffer to fill.

Size
Number of bytes in Buffer to fill.
### Value
Value to fill Buffer with.

### Description
This function fills Size bytes of Buffer with Value. The implementation of SetMem() must be reentrant. If Buffer crosses the top of the processor’s address space, the result of the SetMem() operation is unpredictable.

### Status Codes Returned
None.

#### 7.5.5 EFI_BOOT_SERVICES.GetNextMonotonicCount()

### Summary
Returns a monotonically increasing count for the platform.

### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_GET_NEXT_MONOTONIC_COUNT) (OUT UINT64 *Count);
```

### Parameters

- **Count**
  - Pointer to returned value.

### Description
The GetNextMonotonicCount() function returns a 64-bit value that is numerically larger then the last time the function was called.

The platform’s monotonic counter is comprised of two parts: the high 32 bits and the low 32 bits. The low 32-bit value is volatile and is reset to zero on every system reset. It is increased by 1 on every call to GetNextMonotonicCount(). The high 32-bit value is nonvolatile and is increased by one on whenever the system resets or the low 32-bit counter overflows.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The next monotonic count was returned.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device is not functioning properly.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Count is NULL.</td>
</tr>
</tbody>
</table>

#### 7.5.6 EFI_BOOT_SERVICES.InstallConfigurationTable()

### Summary
Adds, updates, or removes a configuration table entry from the EFI System Table.

### Prototype
typedef
EFI_STATUS
(EIFIAPI * EFI_INSTALL_CONFIGURATION_TABLE) (  
  IN EFI_GUID * Guid,  
  IN VOID * Table  
);

Parameters

Guid
A pointer to the GUID for the entry to add, update, or remove.

Table
A pointer to the configuration table for the entry to add, update, or remove. May be NULL.

Description

The InstallConfigurationTable() function is used to maintain the list of configuration tables that are stored in the EFI System Table. The list is stored as an array of (GUID, Pointer) pairs. The list must be allocated from pool memory with PoolType set to EfiRuntimeServicesData.

If Guid is NULL, EFI_INVALID_PARAMETER is returned. If Guid is valid, there are four possibilities:

• If Guid is not present in the System Table, and Table is not NULL, then the (Guid, Table) pair is added to the System Table. See Note below.

• If Guid is not present in the System Table, and Table is NULL, then EFI_NOT_FOUND is returned.

• If Guid is present in the System Table, and Table is not NULL, then the (Guid, Table) pair is updated with the new Table value.

• If Guid is present in the System Table, and Table is NULL, then the entry associated with Guid is removed from the System Table.

If an add, modify, or remove operation is completed, then EFI_SUCCESS is returned.

Note: If there is not enough memory to perform an add operation, then EFI_OUT_OF_RESOURCES is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The (Guid, Table) pair was added, updated, or removed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Guid is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>An attempt was made to delete a nonexistent entry.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There is not enough memory available to complete the operation.</td>
</tr>
</tbody>
</table>

7.5.7 EFI_BOOT_SERVICES.CalculateCrc32()

Summary

Computes and returns a 32-bit CRC for a data buffer.

Prototype

typedef
EFI_STATUS
(EIFIAPI * EFI_CALCULATE_CRC32) (  
  IN VOID * Data,  
  IN UINTN DataSize,  
);

(continues on next page)
OUT UINT32 *Crc32
);

Parameters

Data
A pointer to the buffer on which the 32-bit CRC is to be computed.

DataSize
The number of bytes in the buffer Data.

Crc32
The 32-bit CRC that was computed for the data buffer specified by Data and DataSize.

Description
This function computes the 32-bit CRC for the data buffer specified by Data and *DataSize. If the 32-bit CRC is computed, then it is returned in Crc32 and EFI_SUCCESS is returned.

If Data is NULL, then EFI_INVALID_PARAMETER is returned.
If Crc32 is NULL, then EFI_INVALID_PARAMETER is returned.
If DataSize is 0, then EFI_INVALID_PARAMETER is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The 32-bit CRC was computed for the data buffer and returned in Crc32.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Data is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Crc32 is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DataSize is 0.</td>
</tr>
</tbody>
</table>
CHAPTER EIGHT

SERVICES — RUNTIME SERVICES

This section discusses the fundamental services that are present in a compliant system. The services are defined by interface functions that may be used by code running in the EFI environment. Such code may include protocols that manage device access or extend platform capability, as well as applications running in the preboot environment and EFI OS loaders.

Two types of services are described here:

- **Boot Services.** Functions that are available before a successful call to `EFI_BOOT_SERVICES.ExitBootServices()`, described in *EFI_BOOT_SERVICES.ExitBootServices()*.
- **Runtime Services.** Functions that are available before and after any call to `ExitBootServices()`. These functions are described in this section.

During boot, system resources are owned by the firmware and are controlled through boot services interface functions. These functions can be characterized as “global” or “handle-based.” The term “global” simply means that a function accesses system services and is available on all platforms (since all platforms support all system services). The term “handle-based” means that the function accesses a specific device or device functionality and may not be available on some platforms (since some devices are not available on some platforms). Protocols are created dynamically. This section discusses the “global” functions and runtime functions; subsequent sections discuss the “handle-based.”

UEFI applications (including UEFI OS loaders) must use boot services functions to access devices and allocate memory. On entry, an image is provided a pointer to a system table which contains the Boot Services dispatch table and the default handles for accessing the console. All boot services functionality is available until a UEFI OS loader loads enough of its own environment to take control of the system’s continued operation and then terminates boot services with a call to `ExitBootServices()`.

In principle, the `ExitBootServices()` call is intended for use by the operating system to indicate that its loader is ready to assume control of the system and all platform resource management. Thus boot services are available up to this point to assist the UEFI OS loader in preparing to boot the operating system. Once the UEFI OS loader takes control of the system and completes the operating system boot process, only runtime services may be called. Code other than the UEFI OS loader, however, may or may not choose to call `ExitBootServices()`. This choice may in part depend upon whether or not such code is designed to make continued use of EFI boot services or the boot services environment.

The rest of this section discusses individual functions. Runtime Services fall into these categories:

- **Runtime Rules and Restrictions** (Runtime Services Rules and Restrictions)
- **Variable Services** (Exception for Machine Check, INIT, and NMI)
- **Time Services** (Time Services)
- **Virtual Memory Services** (Virtual Memory Services)
- **Miscellaneous Services** (Miscellaneous Runtime Services)
8.1 Runtime Services Rules and Restrictions

All of the Runtime Services may be called with interrupts enabled if desired. The Runtime Service functions will internally disable interrupts when it is required to protect access to hardware resources. The interrupt enable control bit will be returned to its entry state after the access to the critical hardware resources is complete.

All callers of Runtime Services are restricted from calling the same or certain other Runtime Service functions prior to the completion and return of a previous Runtime Service call. These restrictions apply to:

- Runtime Services that have been interrupted
- Runtime Services that are active on another processor.

Callers are prohibited from using certain other services from another processor or on the same processor following an interrupt as specified in Rules for Reentry Into Runtime Services. For this table ‘Busy’ is defined as the state when a Runtime Service has been entered and has not returned to the caller.

The consequence of a caller violating these restrictions is undefined except for certain special cases described below.

### Table 8.1: Rules for Reentry Into Runtime Services

<table>
<thead>
<tr>
<th>If previous call is busy in</th>
<th>Forbidden to call</th>
</tr>
</thead>
<tbody>
<tr>
<td>Any</td>
<td>SetVirtualAddressMap()</td>
</tr>
<tr>
<td>ConvertPointer()</td>
<td>ConvertPointer()</td>
</tr>
<tr>
<td>SetVariable(), ConvertPointer(), UpdateCapsule(), SetTime(), SetWakeupTime(), GetNextHighMonotonicCount()</td>
<td>ResetSystem()</td>
</tr>
<tr>
<td>GetVariable(), GetNextVariableName(), SetVariable(), QueryVariableInfo(), UpdateCapsule(), QueryCapsuleCapabilities(), GetNextHighMonotonicCount()</td>
<td>GetVariable(), GetNextVariableName(), SetVariable(), QueryVariableInfo(), UpdateCapsule(), QueryCapsuleCapabilities(), GetNextHighMonotonicCount()</td>
</tr>
<tr>
<td>GetTime()</td>
<td>GetTime()</td>
</tr>
<tr>
<td>SetTime()</td>
<td>SetTime()</td>
</tr>
<tr>
<td>GetWakeupTime()</td>
<td>GetWakeupTime()</td>
</tr>
<tr>
<td>SetWakeupTime()</td>
<td>SetWakeupTime()</td>
</tr>
</tbody>
</table>

If any EFI_RUNTIME_SERVICES* calls are not supported for use by the OS at runtime, an EFI_RT_PROPERTIES_TABLE configuration table should be published describing which runtime services are supported at runtime (EFI Configuration Table & Properties Table). Note that this is merely a hint to the OS, which it is free to ignore, and so the platform is still required to provide callable implementations of unsupported runtime services that simply return EFI_UNSUPPORTED.
8.1.1 Exception for Machine Check, INIT, and NMI

 Certain asynchronous events (e.g., NMI on IA-32 and x64 systems, Machine Check and INIT on Itanium systems) cannot be masked and may occur with any setting of interrupt enabled. These events also may require OS level handler’s involvement that may involve the invocation of some of the runtime services (see below).

 If SetVirtualAddressMap() has been called, all calls to runtime services after Machine Check, INIT, or NMI, must be made using the virtual address map set by that call.

 A Machine Check may have interrupted a runtime service (see below). If the OS determines that the Machine Check is recoverable, the OS level handler must follow the normal restrictions in the Table Rules for Reentry Into Runtime Services.

 If the OS determines that the Machine Check is non-recoverable, the OS level handler may ignore the normal restrictions and may invoke the runtime services described in the Table Functions that may be called after Machine Check, INIT and NMI even in the case where a previous call was busy. The system firmware will honor the new runtime service call(s) and the operation of the previous interrupted call is not guaranteed. Any interrupted runtime functions will not be restarted.

 The INIT and NMI events follow the same restrictions.

 **NOTE**: On Itanium systems, the OS Machine Check Handler must not call ResetSystem(). If a reset is required, the OS Machine Check Handler may request SAL to reset upon return to SAL_CHECK.

 The platform implementations are required to clear any runtime services in progress in order to enable the OS handler to invoke these runtime services even in the case where a previous call was busy. In this case, the proper operation of the original interrupted call is not guaranteed.

<table>
<thead>
<tr>
<th>Function</th>
<th>Called after Machine Check, INIT and NMI</th>
</tr>
</thead>
<tbody>
<tr>
<td>GetTime()</td>
<td>Yes, even if previously busy</td>
</tr>
<tr>
<td>GetVariable()</td>
<td>Yes, even if previously busy</td>
</tr>
<tr>
<td>GetNextVariableName()</td>
<td>Yes, even if previously busy</td>
</tr>
<tr>
<td>QueryVariableInfo()</td>
<td>Yes, even if previously busy</td>
</tr>
<tr>
<td>SetVariable()</td>
<td>Yes, even if previously busy</td>
</tr>
<tr>
<td>UpdateCapsule()</td>
<td>Yes, even if previously busy</td>
</tr>
<tr>
<td>QueryCapsuleCapabilities()</td>
<td>Yes, even if previously busy</td>
</tr>
<tr>
<td>ResetSystem()</td>
<td>Yes, even if previously busy</td>
</tr>
</tbody>
</table>

8.2 Variable Services

 Variables are defined as key/value pairs that consist of identifying information plus attributes (the key) and arbitrary data (the value). Variables are intended for use as a means to store data that is passed between the EFI environment implemented in the platform and EFI OS loaders and other applications that run in the EFI environment.

 Although the implementation of variable storage is not defined in this specification, variables must be persistent in most cases. This implies that the EFI implementation on a platform must arrange it so that variables passed in for storage are retained and available for use each time the system boots, at least until they are explicitly deleted or overwritten.
Provision of this type of nonvolatile storage may be very limited on some platforms, so variables should be used sparingly in cases where other means of communicating information cannot be used.

The Table below lists the variable services functions described in this section:

**Variable Services Functions**

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>GetVariable</td>
<td>Runtime</td>
<td>Returns the value of a variable.</td>
</tr>
<tr>
<td>GetNextVariableName</td>
<td>Runtime</td>
<td>Enumerates the current variable names.</td>
</tr>
<tr>
<td>SetVariable</td>
<td>Runtime</td>
<td>Sets the value of a variable.</td>
</tr>
<tr>
<td>QueryVariableInfo</td>
<td>Runtime</td>
<td>Returns information about the EFI variables</td>
</tr>
</tbody>
</table>

### 8.2.1 GetVariable()

**Summary**

Returns the value of a variable.

**Prototype**

```c
typedef EFI_STATUS GetVariable (  
    IN CHAR16 *VariableName,        
    IN EFI_GUID *VendorGuid,        
    OUT UINT32 *Attributes OPTIONAL,  
    IN OUT UINTN *DataSize,        
    OUT VOID *Data OPTIONAL  
);
```

**Parameters**

**VariableName**

A Null-terminated string that is the name of the vendor’s variable.

**VendorGuid**

A unique identifier for the vendor. Type EFI_GUID is defined in the `efi-boot-services-installprotocolinterface` function description.

**Attributes**

If not NULL, a pointer to the memory location to return the attributes bitmask for the variable. See “Related Definitions.” If not NULL, then *Attributes* is set on output both when *EFI_SUCCESS* and when *EFI_BUFFER_TOO_SMALL* is returned.

**DataSize**

On input, the size in bytes of the return Data buffer. On output the size of data returned in Data.

**Data**

The buffer to return the contents of the variable. May be NULL with a zero DataSize in order to determine the size buffer needed.
Related Definitions

```
// Variable Attributes

#define EFI_VARIABLE_NON_VOLATILE 0x00000001
#define EFI_VARIABLE_BOOTSERVICE_ACCESS 0x00000002
#define EFI_VARIABLE_RUNTIME_ACCESS 0x00000004
#define EFI_VARIABLE_HARDWARE_ERROR_RECORD 0x00000008 \ 
// This attribute is identified by the mnemonic 'HR' elsewhere
// in this specification.
#define EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS 0x00000010
// NOTE: EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS is deprecated
// and should be considered reserved.
#define EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS 0x00000020
#define EFI_VARIABLE_APPEND_WRITE 0x00000040
#define EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS 0x00000080
// This attribute indicates that the variable payload begins
// with an EFI_VARIABLE_AUTHENTICATION_3 structure, and
// potentially more structures as indicated by fields of this
// structure. See definition below and in SetVariable().
```

Description

Each vendor may create and manage its own variables without the risk of name conflicts by using a unique VendorGuid. When a variable is set its Attributes are supplied to indicate how the data variable should be stored and maintained by the system. The attributes affect when the variable may be accessed and volatility of the data. If EFI_BOOT_SERVICES.ExitBootServices() has already been executed, data variables without the EFI_VARIABLE_RUNTIME_ACCESS attribute set will not be visible to GetVariable() and will return an EFI_NOT_FOUND error.

If the Data buffer is too small to hold the contents of the variable, the error EFI_BUFFER_TOO_SMALL is returned and DataSize is set to the required buffer size to obtain the data.

The EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS and the EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS attributes may both be set in the returned Attributes bitmask parameter of a GetVariable() call, though it should be noted that the EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS attribute is deprecated and should no longer be used. The EFI_VARIABLE_APPEND_WRITE attribute will never be set in the returned Attributes bitmask parameter.

Variables stored with the EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS attribute set will return metadata in addition to variable data when GetVariable() is called. If a GetVariable() call indicates that this attribute is set, the GetVariable() payload must be interpreted according to the metadata headers. In addition to the headers described in SetVariable(), the following header is used to indicate what certificate may be currently associated with a variable.

```
// EFI_VARIABLE_AUTHENTICATION_3_CERT_ID descriptor
// An extensible structure to identify a unique x509 cert
// associated with a given variable
//
#define EFI_VARIABLE_AUTHENTICATION_3_CERT_ID_SHA256 1

typedef struct  
  
    UINT8 Type;

(continues on next page)
```
UINT32 IdSize;
// UINT8 Id[IdSize];
} EFI_VARIABLE_AUTHENTICATION_3_CERT_ID;

Type
Identifies the type of ID that is returned and how the ID should be interpreted.

IdSize
Indicates the size of the Id buffer that follows this field in the structure.

Id (Not a formal structure member)
This is a unique identifier for the associated certificate as defined by the Type field. For CERT_ID_SHA256, the
buffer will be a SHA-256 digest of the tbsCertificate (To Be Signed Certificate data defined in x509) data for the
cert.

When the attribute EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS is set, the Data buffer shall be interpreted as follows:

// NOTE: “||” indicates concatenation.
// Example: EFI_VARIABLE_AUTHENTICATION_3_TIMESTAMP_TYPE
EFI_VARIABLE_AUTHENTICATION_3 || EFI_TIME || EFI_VARIABLE_AUTHENTICATION_3CERT_ID || Data

// Example: EFI_VARIABLE_AUTHENTICATION_3_NONCE_TYPE
EFI_VARIABLE_AUTHENTICATION_3 || EFI_VARIABLE_AUTHENTICATION_3_NONCE || EFI_VARIABLE_AUTHENTICATION_3CERT_ID || Data

NOTE: The MetadataSize field of the EFI_VARIABLE_AUTHENTICATION_3 structure in each of these examples does not include any WIN_CERTIFICATE_UEFI_GUID structures. These structures are used in the SetVariable() interface, not GetVariable(), as described in the above examples.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The variable was not found.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The DataSize is too small for the result. DataSize has been updated with the size needed to complete the request. If Attributes is not NULL, then the attributes bitmask for the variable has been stored to the memory location pointed-to by Attributes.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>VariableName is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>VendorGuid is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DataSize is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The DataSize is not too small and Data is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The variable could not be retrieved due to a hardware error.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The variable could not be retrieved due to an authentication failure.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>After ExitBootServices() has been called, this return code may be returned if no variable storage is supported. The platform should describe this runtime service as unsupported at runtime via an EFI_RT_PROPERTIES_TABLE configuration table.</td>
</tr>
</tbody>
</table>

8.2. Variable Services
8.2.2 GetNextVariableName()

Summary
Enumerates the current variable names.

Prototype

```c
typedef EFI_STATUS
GetNextVariableName (
    IN OUT UINTN *VariableNameSize,  
    IN OUT CHAR16 *VariableName,     
    IN OUT EFI_GUID *VendorGuid     
);
```

Parameters

VariableNameSize
The size of the VariableName buffer. The size must be large enough to fit input string supplied in VariableName buffer.

VariableName
On input, supplies the last VariableName that was returned by *GetNextVariableName(). On output, returns the Null-terminated string of the current variable.

VendorGuid
On input, supplies the last VendorGuid that was returned by GetNextVariableName(). On output, returns the VendorGuid of the current variable. Type EFI_GUID is defined in the EFI_BOOT_SERVICES.InstallProtocolInterface() function description.

Description
GetNextVariableName() is called multiple times to retrieve the VariableName and VendorGuid of all variables currently available in the system. On each call to GetNextVariableName() the previous results are passed into the interface, and on output the interface returns the next variable name data. When the entire variable list has been returned, the error EFI_NOT_FOUND is returned.

Note that if EFI_BUFFER_TOO_SMALL is returned, the VariableName buffer was too small for the next variable. When such an error occurs, the VariableNameSize is updated to reflect the size of buffer needed. In all cases when calling GetNextVariableName() the VariableNameSize must not exceed the actual buffer size that was allocated for VariableName. The VariableNameSize must not be smaller the size of the variable name passed to GetNextVariableName() on input in the VariableName buffer.

To start the search, a Null-terminated string is passed in VariableName; that is, VariableName is a pointer to a Null character. This is always done on the initial call to GetNextVariableName(). When VariableName is a pointer to a Null character, VendorGuid is ignored. GetNextVariableName() cannot be used as a filter to return variable names with a specific GUID. Instead, the entire list of variables must be retrieved, and the caller may act as a filter if it chooses. Calls to SetVariable() between calls to GetNextVariableName() may produce unpredictable results. If a VariableName buffer on input is not a Null-terminated string, EFI_INVALID_PARAMETER is returned. If input values of VariableName and VendorGuid are not a name and GUID of an existing variable, EFI_INVALID_PARAMETER is returned.

Once EFI_BOOT_SERVICES.ExitBootServices() is performed, variables that are only visible during boot services will no longer be returned. To obtain the data contents or attribute for a variable returned by GetNextVariableName(), the GetVariable() interface is used.

Status Codes Returned
8.2.3 SetVariable()

Summary
Sets the value of a variable. This service can be used to create a new variable, modify the value of an existing variable, or to delete an existing variable.

Prototype
```c
typedef EFI_STATUS SetVariable ( 
    IN CHAR16 *VariableName, 
    IN EFI_GUID *VendorGuid, 
    IN UINT32 Attributes, 
    IN UINTN DataSize, 
    IN VOID *Data
);
```

Parameters
VariableName
A Null-terminated string that is the name of the vendor’s variable. Each VariableName is unique for each VendorGuid. VariableName must contain 1 or more characters. If VariableName is an empty string, then EFI_INVALID_PARAMETER is returned.

VendorGuid
A unique identifier for the vendor. Type EFI_GUID is defined in the EFI_BOOT_SERVICES.InstallProtocolInterface() function description.

Attributes
Attributes bitmask to set for the variable. Refer to the GetVariable() function description.

DataSize
The size in bytes of the Data buffer. Unless the EFI_VARIABLE_APPEND_WRITE, EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS, EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS, or EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS attribute is set, a size of zero causes the variable to be deleted. When the EFI_VARIABLE_APPEND_WRITE attribute is set, then a
SetVariable() call with a 
DataSize of zero will not cause any change to the variable value (the timestamp associated with the variable may be updated however, even if no new data value is provided; see the description of the EFI_VARIABLE_AUTHENTICATION_2 descriptor below). In this case the DataSize will not be zero since the EFI_VARIABLE_AUTHENTICATION_2 descriptor will be populated).

**Data**

The contents for the variable.

**Related Definitions**

```c
//****************************************************
// Variable Attributes
//****************************************************

// NOTE: This interface is deprecated and should no longer be used!

// EFI_VARIABLE_AUTHENTICATION descriptor
//
// A counter-based authentication method descriptor template
//
typedef struct {
  UINT64 MonotonicCount;
  WIN_CERTIFICATE_UEFI_GUID AuthInfo;
} EFI_VARIABLE_AUTHENTICATION;
```

**MonotonicCount**

Included in the signature of AuthInfo. Used to ensure freshness/no replay. Incremented during each “Write” access.

**AuthInfo**

Provides the authorization for the variable access. It is a signature across the variable data and the Monotonic Count value. Caller uses Private key that is associated with a public key that has been provisioned via the key exchange.

```c
//
// EFI_VARIABLE_AUTHENTICATION_2 descriptor
//
// A time-based authentication method descriptor template
//
typedef struct {
  EFI_TIME TimeStamp;
  WIN_CERTIFICATE_UEFI_GUID AuthInfo;
} EFI_VARIABLE_AUTHENTICATION_2;
```

**TimeStamp**

Time associated with the authentication descriptor. For the TimeStamp value, components Pad1, Nanosecond, TimeZone, Daylight and Pad2 shall be set to 0. This means that the time shall always be expressed in GMT.

**AuthInfo**

Provides the authorization for the variable access. Only a CertType of EFI_CERT_TYPE_PKCS7_GUID is accepted.

```c
//
// EFI_VARIABLE_AUTHENTICATION_3 descriptor
//
```

(continues on next page)
// An extensible implementation of the Variable Authentication structure.
//
#define EFI_VARIABLE_AUTHENTICATION_3_TIMESTAMP_TYPE 1
#define EFI_VARIABLE_AUTHENTICATION_3_NONCE_TYPE 2

typedef struct {
    UINT8 Version;
    UINT8 Type;
    UINT32 MetadataSize;
    UINT32 Flags;
} EFI_VARIABLE_AUTHENTICATION_3;

**Version**
This field is used in case the EFI_VARIABLE_AUTHENTICATION_3 structure itself ever requires updating. For now, it is hardcoded to “0x1”.

**Type**
Declares what structure immediately follows this structure in the Variable Data payload. For EFI_VARIABLE_AUTHENTICATION_3_TIMESTAMP_TYPE, it will be an instance of EFI_TIME (for the TimeStamp). For EFI_VARIABLE_AUTHENTICATION_3_NONCE_TYPE the structure will be an instance of EFI_VARIABLE_AUTHENTICATION_3_NONCE. This structure is defined below.

Note that none of these structures contains a WIN_CERTIFICATE_UEFI_GUID structure. See Using the EFI_VARIABLE_AUTHENTICATION_3 descriptor for an explanation of structure sequencing.

**MetadataSize**
Declares the size of all variable authentication metadata (data related to the authentication of the variable that is not variable data itself), including this header structure, and type-specific structures (eg. EFI_VARIABLE_AUTHENTICATION_3_NONCE), and any WIN_CERTIFICATE_UEFI_GUID structures.

**Flags**

Bitfield indicating any optional configuration for this call. Currently, the only defined value is: #define EFI_VARIABLE_ENHANCED_AUTH_FLAG_UPDATE_CERT 0x00000001 The presence of this flag on SetVariable() indicates that there are two instances of the WIN_CERTIFICATE_UEFI_GUID structure following the type-specific structures. The first instance describes the new cert to be set as the authority for the variable. The second is the signed data to authorize the current updated.

**NOTE:** All other bits are currently Reserved on SetVariable().

**NOTE:** All flags are reserved on GetVariable().

//
// EFI_VARIABLE_AUTHENTICATION_3_NONCE descriptor
//
// A nonce-based authentication method descriptor template. This structure will always be followed by a
// WIN_CERTIFICATE_UEFI_GUID structure.

(continues on next page)
typedef struct {
    UINT32 NonceSize;
    // UINT8 Nonce[NonceSize];
} EFI_VARIABLE_AUTHENTICATION_3_NONCE;

NonceSize
Indicates the size of the Nonce buffer that follows this field in the structure. Must not be 0.

Nonce (Not a formal structure member)
Unique, random value that guarantees a signed payload cannot be shared between multiple machines or machine families. On SetVariable(), if the Nonce field is all 0’s, the host machine will try to use an internally generated random number. Will return EFI_UNSUPPORTED if not possible. Also, on SetVariable() if the variable already exists and the nonce is identical to the current nonce, will return EFI_INVALID_PARAMETER.

Description
Variables are stored by the firmware and may maintain their values across power cycles. Each vendor may create and manage its own variables without the risk of name conflicts by using a unique VendorGuid.

Each variable has Attributes that define how the firmware stores and maintains the data value. If the EFI_VARIABLE_NON_VOLATILE attribute is not set, the firmware stores the variable in normal memory and it is not maintained across a power cycle. Such variables are used to pass information from one component to another. An example of this is the firmware’s language code support variable. It is created at firmware initialization time for access by EFI components that may need the information, but does not need to be backed up to nonvolatile storage.

EFI_VARIABLE_NON_VOLATILE variables are stored in fixed hardware that has a limited storage capacity; sometimes a severely limited capacity. Software should only use a nonvolatile variable when absolutely necessary. In addition, if software uses a nonvolatile variable it should use a variable that is only accessible at boot services time if possible.

A variable must contain one or more bytes of Data. Unless the EFI_VARIABLE_APPEND_WRITE, EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS, or EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS attribute is set (see below), using SetVariable() with a DataSize of zero will cause the entire variable to be deleted. The space consumed by the deleted variable may not be available until the next power cycle.

If a variable with matching name, GUID, and attributes already exists, its value is updated.

The Attributes have the following usage rules:

- If a preexisting variable is rewritten with different attributes, SetVariable() shall not modify the variable and shall return EFI_INVALID_PARAMETER. The only exception to this is when the only attribute differing is EFI_VARIABLE_APPEND_WRITE. In such cases the call’s successful outcome or not is determined by the actual value being written. There are two exceptions to this rule:
  - If a preexisting variable is rewritten with no access attributes specified, the variable will be deleted.
  - EFI_VARIABLE_APPEND_WRITE attribute presents a special case. It is acceptable to rewrite the variable with or without EFI_VARIABLE_APPEND_WRITE attribute.

- Setting a data variable with no access attributes causes it to be deleted.

- EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS is deprecated and should not be used. Platforms should return EFI_UNSUPPORTED if a caller to SetVariable() specifies this attribute.

- Unless the EFI_VARIABLE_APPEND_WRITE, EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS, or EFI_VARIABLE_ENHANCED_AUTHENTICATED_WRITE_ACCESS attribute is set, setting a data variable with zero DataSize specified, causes it to be deleted.
• Runtime access to a data variable implies boot service access. Attributes that have EFI_VARIABLE_RUNTIME_ACCESS set must also have EFI_VARIABLE_BOOTSERVICE_ACCESS set. The caller is responsible for following this rule.

• Once EFI_BOOT_SERVICES.ExitBootServices() is performed, data variables that did not have EFI_VARIABLE_RUNTIME_ACCESS set are no longer visible to GetVariable().

• Once ExitBootServices() is performed, only variables that have EFI_VARIABLE_RUNTIME_ACCESS and EFI_VARIABLE_NON_VOLATILE set can be set with SetVariable(). Variables that have runtime access but that are not nonvolatile are read-only data variables once ExitBootServices() is performed. When the EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS attribute is set in a SetVariable() call, the authentication shall use the EFI_VARIABLE_AUTHENTICATION_3 descriptor, which will be followed by any descriptors indicated in the Type and Flags fields.

• When the EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS attribute is set in a SetVariable() call, the authentication shall use the EFI_VARIABLE_AUTHENTICATION_2 descriptor.

• If both the EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS and the EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS attribute are set in a SetVariable() call, then the firmware must return EFI_INVALID_PARAMETER.

• If the EFI_VARIABLE_APPEND_WRITE attribute is set in a SetVariable() call, then any existing variable value shall be appended with the value of the Data parameter. If the firmware does not support the append operation, then the SetVariable() call shall return EFI_INVALID_PARAMETER.

• If the EFI_VARIABLE_HARDWARE_ERROR_RECORD attribute is set, VariableName and VendorGuid must comply with the rules stated in Hardware Error Record Variables and Appendix P — Hardware Error Record Persistence Usage. Otherwise, the SetVariable() call shall return EFI_INVALID_PARAMETER.

• Global Defined Variables must be created with the attributes defined in the Table Global Variables. If a globally defined variable is created with the wrong attributes, the result is indeterminate and may vary between implementations.

• If using the EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS interface to update the cert authority for a given variable, it is valid for the Data region of the payload to be empty. This would update the cert without modifying the data itself. If the Data region is empty AND no NewCert is specified, the variable will be deleted (assuming all authorizations are verified).

• Secure Boot Policy Variable must be created with the EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS attribute set, and the authentication shall use the EFI_VARIABLE_AUTHENTICATION_2 descriptor. If the appropriate attribute bit is not set, then the firmware shall return EFI_INVALID_PARAMETER.

The only rules the firmware must implement when saving a nonvolatile variable is that it has actually been saved to nonvolatile storage before returning EFI_SUCCESS, and that a partial save is not performed. If power fails during a call to SetVariable() the variable may contain its previous value, or its new value. In addition there is no read, write, or delete security protection.

To delete a variable created with the EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS attribute, SetVariable must be used with attributes matching the existing variable and the DataSize set to the size of the AuthInfo descriptor. The Data buffer must contain an instance of the AuthInfo descriptor which will be validated according to the steps in the appropriate section above referring to updates of Authenticated variables. An attempt to delete a variable created with the EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS attribute for which the prescribed AuthInfo validation fails or when called using DataSize of zero will fail with an EFI_SECURITY_VIOLATION status.

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To delete a variable created with the EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS attribute, Set-Variable must be used with attributes matching the existing variable and the DataSize set to the size of the entire payload including all descriptors and certificates. The Data buffer must contain an instance of the EFI_VARIABLE_AUTHENTICATION_3 descriptor which will indicate how to validate the payload according to the description in Using the EFI_VARIABLE_AUTHENTICATION_3 descriptor. An attempt to delete a variable created with the EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS attribute for which the prescribed validation fails or when called using DataSize of zero will fail with an EFI_SECURITY_VIOLATION status.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The firmware has successfully stored the variable and its data as defined by the Attributes.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>An invalid combination of attribute bits, name, and GUID was supplied, or the DataSize exceeds the maximum allowed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>VariableName is an empty string.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Not enough storage is available to hold the variable and its data.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The variable could not be saved due to a hardware failure.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The variable in question is read-only.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The variable in question cannot be deleted.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The variable could not be written due to EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS or EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS being set, but the payload does NOT pass the validation check carried out by the firmware.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The variable trying to be updated or deleted was not found.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This call is not supported by this platform at the time the call is made. The platform should describe this runtime service as unsupported at runtime via an EFI_RT_PROPERTIES_TABLE configuration table.</td>
</tr>
</tbody>
</table>

### 8.2.4 QueryVariableInfo()

**Summary**

Returns information about the EFI variables.

**Prototype**

```c
typedef EFI_STATUS
QueryVariableInfo (  
    IN UINT32 Attributes, 
    OUT UINT64 *MaximumVariableStorageSize, 
    OUT UINT64 *RemainingVariableStorageSize, 
    OUT UINT64 *MaximumVariableSize 
);
```

**Attributes**

Attributes bitmask to specify the type of variables on which to return information. Refer to the GetVariable() function description. The EFI_VARIABLE_APPEND_WRITE attribute, if set in the attributes bitmask, will be ignored.
**MaximumVariableStorageSize**
On output the maximum size of the storage space available for the EFI variables associated with the attributes specified.

**RemainingVariableStorageSize**
Returns the remaining size of the storage space available for EFI variables associated with the attributes specified.

**MaximumVariableSize**
Returns the maximum size of an individual EFI variable associated with the attributes specified.

**Description**
The QueryVariableInfo() function allows a caller to obtain the information about the maximum size of the storage space available for the EFI variables, the remaining size of the storage space available for the EFI variables and the maximum size of each individual EFI variable, associated with the attributes specified.

The `MaximumVariableSize` value will reflect the overhead associated with the saving of a single EFI variable with the exception of the overhead associated with the length of the string name of the EFI variable.

The returned `MaximumVariableStorageSize`, `RemainingVariableStorageSize`, `MaximumVariableSize` information may change immediately after the call based on other runtime activities including asynchronous error events. Also, these values associated with different attributes are not additive in nature.

After the system has transitioned into runtime (after ExitBootServices() is called), an implementation may not be able to accurately return information about the Boot Services variable store. In such cases, `EFI_INVALID_PARAMETER` should be returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Valid answer returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>An invalid combination of attribute bits was supplied</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The attribute is not supported on this platform, and the</td>
</tr>
<tr>
<td></td>
<td><code>MaximumVariableStorageSize</code>,</td>
</tr>
<tr>
<td></td>
<td><code>RemainingVariableStorageSize</code>,</td>
</tr>
<tr>
<td></td>
<td><code>MaximumVariableSize</code> are undefined.</td>
</tr>
</tbody>
</table>

### 8.2.5 Using the EFI_VARIABLE_AUTHENTICATION_3 descriptor

When the attribute `EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS` is set, the payload buffer (passed into SetVariable() as “Data”) shall be constructed as follows:

```c
// NOTE: “||” indicates concatenation.
// NOTE: “[ ]” indicates an optional element.

// Example: EFI_VARIABLE_AUTHENTICATION_3_TIMESTAMP_TYPE
EFI_VARIABLE_AUTHENTICATION_3 || EFI_TIME || [ NewCert ] || SigningCert || Data

// Example: EFI_VARIABLE_AUTHENTICATION_3_NONCE_TYPE
EFI_VARIABLE_AUTHENTICATION_3_NONCE || [ NewCert ] || SigningCert || Data
```

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In this example, NewCert and SigningCert are both instances of WIN_CERTIFICATE_UEFI_GUID. The presence of NewCert is indicated by the EFI_VARIABLE_AUTHENTICATION_3.Flags field (see Definition in SetVariable()). If provided – and assuming the payload passes all integrity and security verifications — this cert will be set as the new authority for the underlying variable, even if the variable is being newly created.

The NewCert element must have a CertType of EFI_CERT_TYPE_PKCS7_GUID, and the CertData must be a DER-encoded SignedData structure per PKCS#7 version 1.5 (RFC 2315), which shall be supported both with and without a DER-encoded ContentInfo structure per PKCS#7 version 1.5. When creating the SignedData structure, the following steps shall be followed:

1. Create a WIN_CERTIFICATE_UEFI_GUID structure where CertType is set to EFI_CERT_TYPE_PKCS7_GUID.
2. Use the x509 cert being added as the new authority to sign its own tbsCertificate data.
3. Construct a DER-encoded PKCS #7 version 1.5 SignedData (see [RFC2315]) with the signed content as follows:
   a - SignedData.version shall be set to 1.
   b - SignedData.digestAlgorithms shall contain the digest algorithm used when preparing the signature. Only a digest algorithm of SHA-256 is accepted.
   c - SignedData.contentInfo.contentType shall be set to id-data.
   d - SignedData.contentInfo.content shall be the tbsCertificate data that was signed for the new x509 cert.
   e - SignedData.certificates shall contain, at a minimum, the signer's DER-encoded X.509 certificate.
   f - SignedData.crls is optional.
   g - SignedData.signerInfos shall be constructed as:
      • SignerInfo.version shall be set to 1.
      • SignerInfo.issuerAndSerial shall be present and as in the signer's certificate.
      • SignerInfo.authenticatedAttributes shall not be present.
      • SignerInfo.digestEncryptionAlgorithm shall be set to the algorithm used to sign the data. Only a digest encryption algorithm of RSA with PKCS #1 v1.5 padding (RSASSA_PKCS1v1_5) is accepted.
      • SignerInfo.encryptedDigest shall be present.
      • SignerInfo.unauthenticatedAttributes shall not be present.
4. Set the CertData field to the DER-encoded PKCS#7 SignedData value.

A caller to SetVariable() attempting to create, update, or delete a variable with the EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS set shall perform the following steps to create the SignedData structure for SigningCert:

1. Create an EFI_VARIABLE_AUTHENTICATION_3 Primary Descriptor with the following values:
   a - Version shall be set appropriate to the version of metadata headers being used (currently 1).
   b - Type should be set based on caller specifications (see EFI_VARIABLE_AUTHENTICATION_3 descriptor under SetVariable()).
   c - MetadataSize can be ignored for now, and will be updated when constructing the final payload.
   d - Flags shall be set based on caller specifications.
2. A Secondary Descriptor may need to be created based on the Type.
   a - For EFI_VARIABLE_AUTHENTICATION_3_TIMESTAMP_TYPE type, this will be an instance of EFI_TIME set to the current time.
b - For EFI_VARIABLE_AUTHENTICATION_3_NONCE_TYPE type, this will be an instance of EFI_VARIABLE_AUTHENTICATION_3_NONCE updated with NonceSize set based on caller specifications (must not be zero), and Nonce (informal structure member) set to:

• All zeros to request that the platform create a random nonce.
• Caller specified value for a pre-generated nonce.

3. Hash a serialization of the payload. Serialization shall contain the following elements in this order:

   a - VariableName, VendorGuid, Attributes, and the Secondary Descriptor if it exists for this Type.

   b - Variable’s new value (ie. the Data parameter’s new variable content).

   c - If this is an update to or deletion of a variable with type EFI_VARIABLE_AUTHENTICATION_3_NONCE, serialize the current nonce. The current nonce is the one currently associated with this variable, not the one in the Secondary Descriptor. Serialize only the nonce buffer contents, not the size or any additional data. If this is an attempt to create a new variable (ie. there is no current nonce), skip this step.

   d - If the authority cert for this variable is being updated and the EFI_VARIABLE_AUTHENTICATION_3.Flags field indicates the presence of a NewCert structure, serialize the entire NewCert structure (described at the beginning of this section).

4. Sign the resulting digest.

5. Create a WIN_CERTIFICATE_UEFI_GUID structure where CertType is set to EFI_CERT_TYPE_PKCS7_GUID.

6. Construct a DER-encoded PKCS #7 version 1.5 SignedData (see [RFC2315]) following the steps described for NewCert (step 3), above, with the following exception:

   a - SignedData.contentInfo.content shall be absent (the content is provided in the Data parameter to the SetVariable() call)

7. Construct the final payload for SetVariable() according to the descriptions for “payload buffer” at the beginning of this section.

8. Update the EFI_VARIABLE_AUTHENTICATION_3.MetadataSize field to include all parts of the final payload except “Data”.

Firmware that implements the SetVariable() services and supports the EFI_VARIABLE_ENHANCED_AUTHENTICATED_ACCESS attribute shall do the following in response to being called:

1. Read the EFI_VARIABLE_AUTHENTICATION_3 descriptor to determine what type of authentication is being performed and how to parse the rest of the payload.

2. Verify that SigningCert.CertType EFI_CERT_TYPE_PKCS7_GUID.

   a - If EFI_VARIABLE_AUTHENTICATION_3.Flags field indicates presence of a NewCert, verify that-NewCert.CertType is EFI_CERT_TYPE_PKCS7_GUID.

   b - If either fails, return EFI_INVALID_PARAMETER.

3. If the variable already exists, verify that the incoming type matches the existing type.

4. Verify that any EFI_TIME structures have Pad1, Nanosecond, TimeZone, Daylight, and Pad2 fields set to zero.

5. If EFI_VARIABLE_AUTHENTICATION_3_NONCE_TYPE:

   a - Verify that NonceSize is greater than zero. If zero, return EFI_INVALID_PARAMETER.

   b - If incoming nonce is all zeros, confirm that platform supports generating random nonce. If unsupported, return EFI_UNSUPPORTED.

   c - If nonce is specified and variable already exists, verify that incoming nonce does not match existing nonce. If identical, return EFI_INVALID_PARAMETER.
6. If EFI_VARIABLE_AUTHENTICATION_3_TIMESTAMP_TYPE and variable already exists, verify that new timestamp is chronologically greater than current timestamp.

7. Verify the payload signature by:
   a - Parsing entire payload according to descriptors.
   b - Using descriptor contents (and, if necessary, metadata from existing variable) to construct the serialization described previously in this section (step 3 of the SetVariable() instructions).
   c - Compute the digest and compare with the result of applying the SigningCert’s public key to the signature.

8. If the variable already exists, verify that the SigningCert authority is the same as the authority already associated with the variable.

9. If NewCert is provided, verify the NewCert signature by:
   a - Parsing entire payload according to descriptors.
   b - Compute a digest of the tbsCertificate of x509 certificate in NewCert and compare with the result of applying NewCert’s public key to the signature.
   c - If this fails, return EFI_SECURITY_VIOLATION.

8.2.6 Using the EFI_VARIABLE_AUTHENTICATION_2 descriptor

When the attribute EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS is set, then the Data buffer shall begin with an instance of a complete (and serialized).

EFI_VARIABLE_AUTHENTICATION_2 descriptor. The descriptor shall be followed by the new variable value and DataSize shall reflect the combined size of the descriptor and the new variable value. The authentication descriptor is not part of the variable data and is not returned by subsequent calls to GetVariable().

A caller that invokes the SetVariable() service with the EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS attribute set shall do the following prior to invoking the service:

1. Create a descriptor

   Create an EFI_VARIABLE_AUTHENTICATION_2 descriptor where:

   • TimeStamp is set to the current time.

   **NOTE:** In certain environments a reliable time source may not be available. In this case, an implementation may still add values to an authenticated variable since the EFI_VARIABLE_APPEND_WRITE attribute, when set, disables timestamp verification (see below). In these instances, the special time value where every component of the EFI_TIME struct including the Day and Month is set to 0 shall be used.

   • AuthInfo.CertType is set to EFI_CERT_TYPE_PKCS7_GUID.

2. Hash the serialization of the values of the VariableName, VendorGuid and Attributes parameters of the SetVariable() call and the TimeStamp component of the EFI_VARIABLE_AUTHENTICATION_2 descriptor followed by the variable’s new value (i.e. the Data parameter’s new variable content). That is, digest = hash (VariableName, VendorGuid, Attributes, TimeStamp, DataNew_variable_content). The NULL character terminating the VariableName value shall not be included in the hash computation.

3. Sign the resulting digest using a selected signature scheme (e.g. PKCS #1 v1.5)
4. Construct a DER-encoded SignedData structure per PKCS#7 version 1.5 (RFC 2315), which shall be supported both with and without a DER-encoded ContentInfo structure per PKCS#7 version 1.5, with the signed content as follows:

a - SignedData.version shall be set to 1

b - SignedData.digestAlgorithms shall contain the digest algorithm used when preparing the signature. Only a digest algorithm of SHA-256 is accepted.

c - SignedData.contentInfo.contentType shall be set to id-data

d - SignedData.contentInfo.content shall be absent (the content is provided in the Data parameter to the SetVariable() call)

e - SignedData.certificates shall contain, at a minimum, the signers DER-encoded X.509 certificate.

f - SignedData.crls is optional.

g - SignedData.signerInfos shall be constructed as:
   • SignerInfo.version shall be set to 1
   • SignerInfo.issuerAndSerial shall be present and as in the signer’s certificate — SignerInfo.authenticatedAttributes shall not be present.
   • SignerInfo.digestEncryptionAlgorithm shall be set to the algorithm used to sign the data. Only a digest encryption algorithm of RSA with PKCS #1 v1.5 padding (RSASSA_PKCS1v1_5). is accepted.
   • SignerInfo.encryptedDigest shall be present
   • SignerInfo.unauthenticatedAttributes shall not be present.

5. Set AuthInfo.CertData to the DER-encoded PKCS #7 SignedData value.

6. Construct Data parameter: Construct the SetVariable()’s Data parameter by concatenating the complete, serialized EFI_VARIABLE_AUTHENTICATION_2 descriptor with the new value of the variable (DataNew_variable_content).

Firmware that implements the SetVariable() service and supports the EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS attribute shall do the following in response to being called:

1. Verify that the correct AuthInfo.CertType (EFI_CERT_TYPE_PKCS7_GUID) has been used and that the AuthInfo.CertData value parses correctly as a PKCS #7SignedData value

2. Verify that Pad1, Nanosecond, TimeZone, Daylight and Pad2 components of the TimeStamp value are set to zero. Unless the EFI_VARIABLE_APPEND_WRITE attribute is set, verify that the TimeStamp value is later than the current timestamp value associated with the variable.

3. If the variable SetupMode==1, and the variable is a secure boot policy variable, then the firmware implementation shall consider the checks in the following steps 4 and 5 to have passed, and proceed with updating the variable value as outlined below.

4. Verify the signature by:
   • extracting the EFI_VARIABLE_AUTHENTICATION_2 descriptor from the Data buffer;
   • using the descriptor contents and other parameters to (a) construct the input to the digest algorithm; (b) computing the digest; and (c) comparing the digest with the result of applying the signer’s public key to the signature.

5. If the variable is the global PK variable or the global KEK variable, verify that the signature has been made with the current Platform Key.
• If the variable is the “db”, “dbt”, “dbr”, or “dbx” variable mentioned in step 3, verify that the signer’s certificate chains to a certificate in the Key Exchange Key database (or that the signature was made with the current Platform Key).

• If the variable is the “OsRecoveryOrder” or “OsRecovery#####” variable mentioned in step 3, verify that the signer’s certificate chains to a certificate in the “dbr” database or the Key Exchange Key database, or that the signature was made with the current Platform Key.

• Otherwise, if the variable is none of the above, it shall be designated a Private Authenticated Variable. If the Private Authenticated Variable does not exist, then the CN of the signing certificate’s Subject and the hash of the tbsCertificate of the top-level issuer certificate (or the signing certificate itself if no other certificates are present or the certificate chain is of length 1) in SignedData.certificates is registered for use in subsequent verifications of this variable. Implementations may store just a single hash of these two elements to reduce storage requirements. If the Private Authenticated variable previously existed, that the signer’s certificate chains to the information previously associated with the variable. Observe that because no revocation list exists for them, if any member of the certificate chain is compromised, the only method to revoke trust in a certificate for a Private Authenticated Variable is to delete the variable, re-issue all certificate authorities in the chain, and re-create the variable using the new certificate chain. As such, the remaining benefits may be strong identification of the originator, or compliance with some certificate authority policy. Further note that the PKCS7 bundle for the authenticated variable update must contain the signing certificate chain, through and including the full certificate of the desired trust anchor. The trust anchor might be a mid-level certificate or root, though many roots may be unsuitable trust anchors due to the number of CAs they issue for different purposes. Some tools require non-default parameters to include the trust anchor certificate.

The driver shall update the value of the variable only if all of these checks pass. If any of the checks fails, firmware must return EFI_SECURITY_VIOLATION.

The firmware shall perform an append to an existing variable value only if the EFI_VARIABLE_APPEND_WRITE attribute is set.

For variables with the GUID EFI_IMAGE_SECURITY_DATABASE_GUID (i.e. where the data buffer is formatted as EFI_SIGNATURE_LIST), the driver shall not perform an append of EFI_SIGNATURE_DATA values that are already part of the existing variable value.

NOTE: This situation is not considered an error, and shall in itself not cause a status code other than EFI_SUCCESS to be returned or the timestamp associated with the variable not to be updated.

The firmware shall associate the new timestamp with the updated value (in the case when the EFI_VARIABLE_APPEND_WRITE attribute is set, this only applies if the new TimeStamp value is later than the current timestamp associated with the variable).

If the variable did not previously exist, and is not one of the variables listed in step 3 above, then firmware shall associate the signer’s public key with the variable for future verification purposes.

### 8.2.7 Using the EFI_VARIABLE_AUTHENTICATION descriptor

**NOTE: This interface is deprecated and should no longer be used! It will be removed from future versions of the spec.**

When the attribute EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS is set, but the EFI_VARIABLE_TIME_BASED_AUTHENTICATED_WRITE_ACCESS is not set (i.e. when the EFI_VARIABLE_AUTHENTICATION descriptor is used), then the Data buffer shall begin with an instance of the authentication descriptor AuthInfo prior to the data payload and DataSize should reflect the data and descriptor size. The authentication descriptor is not part of the variable data and is not returned by the subsequent calls to GetVariable. The caller shall digest the Monotonic Count value and the associated data for the variable update using the SHA-256 1-way hash algorithm. The ensuing the 32-byte digest will be signed using the private key associated with the public 2048-bit RSA key PublicKey described in the EFI_CERT_BLOCK_RSA_2048_SHA256 structure.
The WIN_CERTIFICATE shall be used to describe the signature of the variable *Data. In addition, the signature will also include the MonotonicCount value to guard against replay attacks. The MonotonicCount value must be increased by the caller prior to an update of the *Data* when the EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS is set.

From the EFI_CERT_BLOCK_RSA_2048_SHA256, the HashType will be EFI_SHA256_HASH* and the ANY-SIZE_ARRAY of Signature will be 256. The WIN_CERTIFICATE_PKCS1_15 could have been used but was not for the following reason: There are possibly various different principals to create authenticated variables, so the public key corresponding to a given principal is added to the EFI_CERT_BLOCK_RSA_2048_SHA256 within the WIN_CERTIFICATE. This does not lend cryptographic value so much as it provides something akin to a handle for the platform firmware to use during its verification operation.

The MonotonicCount value must be strictly greater for each successive variable update operation. This allows for ensuring freshness of the update operation and defense against replay attacks (i.e., if someone had the value of a former AuthInfo, such as a Man-in-the-Middle they could not re-invoke that same update session). For maintenance, the party who initially provisioned the variable (i.e., caller of SetVariable) and set the monotonic count will have to pass the credential (key-pair and monotonic count) to any party who is delegated to make successive updates to the variable with the EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS set. This 3-tuple of {public key, private key, monotonic count} becomes part of the management metadata for these access-controlled items.

The responsibility of the caller that invokes the SetVariable() service with the EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS attribute will do the following prior to invoking the service:

- Update the Monotonic Count value.
- Hash the variable contents (Data, Size, Monotonic count) using the HashType in the AuthInfo structure.
- Sign the resultant hash of above step using a caller private key and create the digital signature Signature. Ensure that the public key associated with signing private key is in the AuthInfo structure.
- Invoke SetVariables with EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS attribute set.

The responsibility of the firmware that implements the SetVariable() service and supports the EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS attribute will do the following in response to being called:

- The first time it uses SetVariable with the EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS attribute set. Use the public key in the AuthInfo structure for subsequent verification.
- Hash the variable contents (Data, Size, Monotonic count) using the HashType in the AuthInfo structure.
- Compare the public key in the AuthInfo structure with the public key passed in on the first invocation.
- Verify the digital signature Signature of the signed hash using the stored public key associated with the variable.
- Compare the verification of the signature with the instance generated by the caller.
- If comparison fails, return EFI_SECURITY_VIOLATION.
- Compare the new monotonic count and ensure that it is greater than the last SetVariable operation with the EFI_VARIABLE_AUTHENTICATED_WRITE_ACCESS attribute set.
- If new monotonic count is not strictly greater, then return EFI_SECURITY_VIOLATION.

**NOTE:** Special processing by SetVariable() for Secure Boot variables and the Platform Key is defined in Firmware/OS Key Exchange: Creating Trust Relationships.
8.2.8 Hardware Error Record Persistence

This section defines how Hardware Error Record Persistence is to be implemented. By implementing support for Hardware Error Record Persistence, the platform enables the OS to utilize the EFI Variable Services to save hardware error records so they are persistent and remain available across OS sessions until they are explicitly cleared or overwritten by their creator.

8.2.8.1 Hardware Error Record Non-Volatile Store

A platform which implements support hardware error record persistence is required to guarantee some amount of NVR is available to the OS for saving hardware error records. The platform communicates the amount of space allocated for error records via the QueryVariableInfo routine as described in Appendix P.

8.2.8.2 Hardware Error Record Variables

This section defines a set of Hardware Error Record variables that have architecturally defined meanings. In addition to the defined data content, each such variable has an architecturally defined attribute that indicates when the data variable may be accessed. The variables with an attribute of HR are stored in the portion of NVR allocated for error records. NV, BS and RT have the meanings defined in section 3.2. All hardware error record variables use the EFI_HARDWARE_ERROR_VARIABLE VendorGuid:

```
#define EFI_HARDWARE_ERROR_VARIABLE
{0x414E6BDD,0xE47B,0x47cc,{0xB2,0x44,0xBB,0x61,0x02,0x0C,0xF5,0x16}}
```

Table 8.8: Hardware Error Record Persistence Variables

<table>
<thead>
<tr>
<th>Variable Name</th>
<th>Attribute</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>HwErrRec####</td>
<td>NV, BS, RT, HR</td>
<td>A hardware error record. #### is a printed hex value. No 0x or h is included in the hex value</td>
</tr>
</tbody>
</table>

The HwErrRec#### variable contains a hardware error record. Each HwErrRec#### variable is the name “HwErrRec” appended with a unique 4-digit hexadecimal number. For example, HwErrRec0001, HwErrRec0002, HwErrRecF31A, etc. The HR attribute indicates that this variable is to be stored in the portion of NVR allocated for error records.

8.2.8.3 Common Platform Error Record Format

Error record variables persisted using this interface are encoded in the Common Platform Error Record format, which is described in appendix N of the UEFI Specification. Because error records persisted using this interface conform to this standardized format, the error information may be used by entities other than the OS.

8.3 Time Services

This section contains function definitions for time-related functions that are typically needed by operating systems at runtime to access underlying hardware that manages time information and services. The purpose of these interfaces is to provide operating system writers with an abstraction for hardware time devices, thereby relieving the need to access legacy hardware devices directly. There is also a stalling function for use in the preboot environment. Time Services Functions lists the time services functions described in this section:
### Table 8.9: Time Services Functions

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>GetTime</td>
<td>Runtime</td>
<td>Returns the current time and date, and the time-keeping capabilities of the platform.</td>
</tr>
<tr>
<td>SetTime</td>
<td>Runtime</td>
<td>Sets the current local time and date information.</td>
</tr>
<tr>
<td>GetWakeupTime</td>
<td>Runtime</td>
<td>Returns the current wakeup alarm clock setting.</td>
</tr>
<tr>
<td>SetWakeupTime</td>
<td>Runtime</td>
<td>Sets the system wakeup alarm clock time</td>
</tr>
</tbody>
</table>

#### 8.3.1 GetTime()

**Summary**

Returns the current time and date information, and the time-keeping capabilities of the hardware platform.

**Prototype**

```c
typedef EFI_STATUS GetTime ( 
    OUT EFI_TIME *Time, 
    OUT EFI_TIME_CAPABILITIES *Capabilities OPTIONAL 
);
```

**Parameters**

- **Time**: A pointer to storage to receive a snapshot of the current time. Type EFI_TIME is defined in “Related Definitions.”

- **Capabilities**: An optional pointer to a buffer to receive the real time clock device’s capabilities. Type EFI_TIME_CAPABILITIES is defined in “Related Definitions.”

**Related Definitions**

```c
//**********************************************************
//EFI_TIME
//**********************************************************
// This represents the current time information
typedef struct {
    UINT16 Year;  // 1900 - 9999
    UINT8 Month;  // 1 - 12
    UINT8 Day;    // 1 - 31
    UINT8 Hour;   // 0 - 23
    UINT8 Minute; // 0 - 59
    UINT8 Second; // 0 - 59
    UINT8 Pad1;
    UINT32 Nanosecond;  // 0 - 999,999,999
    INT16 TimeZone;     // -1440 to 1440 or 2047
    UINT8 Daylight;
    UINT8 Pad2;
} EFI_TIME;

//**********************************************************
// Bit Definitions for EFI_TIME.Daylight. See below.
```

(continues on next page)
Year, Month, Day
The current local date.

Hour, Minute, Second, Nanosecond
The current local time. Nanoseconds report the current fraction of a second in the device. The format of the time is \textit{hh:mm:ss.nnnnnnnn}. A battery backed real time clock device maintains the date and time.

TimeZone
The time’s offset in minutes from UTC. If the value is EFI_UNSPECIFIED_TIMEZONE, then the time is interpreted as a local time. The \textit{TimeZone} is the number of minutes that the local time is relative to UTC. To calculate the \textit{TimeZone} value, follow this equation: \textit{Localtime} = UTC - \textit{TimeZone}.

To further illustrate this, an example is given below:

PST (Pacific Standard Time is 12PM) = UTC (8PM) - 8 hours (480 minutes)

In this case, the value for \textit{Timezone} would be 480 if referencing PST.

Daylight
A bitmask containing the daylight savings time information for the time.

The EFI_TIME_ADJUST_DAYLIGHT bit indicates if the time is affected by daylight savings time or not. This value does not indicate that the time has been adjusted for daylight savings time. It indicates only that it should be adjusted when the EFI_TIME enters daylight savings time.

If EFI_TIME_IN_DAYLIGHT is set, the time has been adjusted for daylight savings time.

All other bits must be zero.

When entering daylight saving time, if the time is affected, but hasn’t been adjusted (DST = 1), use the new calculation:

1. The date/time should be increased by the appropriate amount.
2. The \textit{TimeZone} should be decreased by the appropriate amount (EX: +480 changes to +420 when moving from PST to PDT).
3. The \textit{Daylight} value changes to 3.

When exiting daylight saving time, if the time is affected and has been adjusted (DST = 3), use the new calculation:

1. The date/time should be decreased by the appropriate amount.
2. The \textit{TimeZone} should be increased by the appropriate amount.
3. The \textit{Daylight} value changes to 1.
interfaces.
typedef struct {
    UINT32 Resolution;
    UINT32 Accuracy;
    BOOLEAN SetsToZero;
} EFI_TIME_CAPABILITIES;

Resolution
Provides the reporting resolution of the real-time clock device in counts per second. For a normal PC-AT CMOS RTC device, this value would be 1 Hz, or 1, to indicate that the device only reports the time to the resolution of 1 second.

Accuracy
Provides the timekeeping accuracy of the real-time clock in an error rate of 1E-6 parts per million. For a clock with an accuracy of 50 parts per million, the value in this field would be 50,000,000.

SetsToZero
A TRUE indicates that a time set operation clears the device’s time below the Resolution reporting level. A FALSE indicates that the state below the Resolution level of the device is not cleared when the time is set. Normal PC-AT CMOS RTC devices set this value to FALSE.

Description
The GetTime() function returns a time that was valid sometime during the call to the function. While the returned EFI_TIME structure contains TimeZone and Daylight savings time information, the actual clock does not maintain these values. The current time zone and daylight saving time information returned by GetTime() are the values that were last set via SetTime().

The GetTime() function should take approximately the same amount of time to read the time each time it is called. All reported device capabilities are to be rounded up.

During runtime, if a PC-AT CMOS device is present in the platform the caller must synchronize access to the device before calling GetTime().

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Time is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The time could not be retrieved due to a hardware error.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This call is not supported by this platform at the time the call is made.</td>
</tr>
<tr>
<td></td>
<td>The platform should describe this runtime service as unsupported at runtime</td>
</tr>
<tr>
<td></td>
<td>via an EFI_RT_PROPERTIES_TABLE configuration table.</td>
</tr>
</tbody>
</table>

8.3.2 SetTime()

Summary
Sets the current local time and date information.

Prototype
typedef
EFI_STATUS
SetTime (  

8.3. Time Services
IN EFI_TIME *Time
);

Parameters

Time
A pointer to the current time. Type EFI_TIME is defined in the GetTime() function description. Full error checking is performed on the different fields of the EFI_TIME structure (refer to the EFI_TIME definition in the GetTime() function description for full details), and EFI_INVALID_PARAMETER is returned if any field is out of range.

Description
The SetTime() function sets the real time clock device to the supplied time, and records the current time zone and daylight savings time information. The SetTime() function is not allowed to loop based on the current time. For example, if the device does not support a hardware reset for the sub-resolution time, the code is not to implement the feature by waiting for the time to wrap.

During runtime, if a PC-AT CMOS device is present in the platform the caller must synchronize access to the device before calling SetTime().

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A time field is out of range.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The time could not be set due to a hardware error.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This call is not supported by this platform at the time the call is made. The</td>
</tr>
<tr>
<td></td>
<td>platform should describe this runtime service as unsupported at runtime via</td>
</tr>
<tr>
<td></td>
<td>an EFI_RT_PROPERTIES_TABLE configuration table.</td>
</tr>
</tbody>
</table>

8.3.3 GetWakeupTime()

Summary
Returns the current wakeup alarm clock setting.

Prototype

```c
typedef
EFI_STATUS
GetWakeupTime ( 
    OUT BOOLEAN *Enabled, 
    OUT BOOLEAN *Pending, 
    OUT EFI_TIME *Time
);
```

Parameters

Enabled
Indicates if the alarm is currently enabled or disabled.

Pending
Indicates if the alarm signal is pending and requires acknowledgement.

Time
The current alarm setting. Type EFI_TIME is defined in the GetTime() function description.
Description

The alarm clock time may be rounded from the set alarm clock time to be within the resolution of the alarm clock device. The resolution of the alarm clock device is defined to be one second.

During runtime, if a PC-AT CMOS device is present in the platform the caller must synchronize access to the device before calling GetWakeupTime().

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The alarm settings were returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><strong>Enabled</strong> is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><strong>Pending</strong> is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><strong>Time</strong> is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The wakeup time could not be retrieved due to a hardware error.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This call is not supported by this platform at the time the call is made.</td>
</tr>
<tr>
<td></td>
<td>The platform should describe this runtime service as unsupported at runtime</td>
</tr>
<tr>
<td></td>
<td>via an <strong>EFI_RT_PROPERTIES_TABLE</strong> configuration table.</td>
</tr>
</tbody>
</table>

8.3.4 SetWakeupTime()

Summary

Sets the system wakeup alarm clock time.

Prototype

typedef
EFI_STATUS
SetWakeupTime (  
    IN BOOLEAN Enable,  
    IN EFI_TIME *Time OPTIONAL  
);

Parameters

Enable

Enable or disable the wakeup alarm.

Time

If Enable is **TRUE**, the time to set the wakeup alarm for. Type **EFI_TIME** is defined in the **GetTime()** function description. If Enable is **FALSE**, then this parameter is optional, and may be NULL.

Description

Setting a system wakeup alarm causes the system to wake up or power on at the set time. When the alarm fires, the alarm signal is latched until it is acknowledged by calling **SetWakeupTime()** to disable the alarm. If the alarm fires before the system is put into a sleeping or off state, since the alarm signal is latched the system will immediately wake up. If the alarm fires while the system is off and there is insufficient power to power on the system, the system is powered on when power is restored.

For an ACPI-aware operating system, this function only handles programming the wakeup alarm for the desired wakeup time. The operating system still controls the wakeup event as it normally would through the ACPI Power Management register set.

The resolution for the wakeup alarm is defined to be 1 second.
During runtime, if a PC-AT CMOS device is present in the platform the caller must synchronize access to the device before calling SetWakeupTime().

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>If Enable is <strong>TRUE</strong>, then the wakeup alarm was enabled. If Enable is <strong>FALSE</strong>, then the wakeup alarm was disabled.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A time field is out of range.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The wakeup time could not be set due to a hardware error.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This call is not supported by this platform at the time the call is made. The platform should describe this runtime service as unsupported at runtime via an <code>EFI_RT_PROPERTIES_TABLE</code> configuration table.</td>
</tr>
</tbody>
</table>

### 8.4 Virtual Memory Services

This section contains function definitions for the virtual memory support that may be optionally used by an operating system at runtime. If an operating system chooses to make EFI runtime service calls in a virtual addressing mode instead of the flat physical mode, then the operating system must use the services in this section to switch the EFI runtime services from flat physical addressing to virtual addressing. *Virtual Memory Functions* lists the virtual memory service functions described in this section. The system firmware must follow the processor-specific rules outlined in *IA-32 Platforms* through *AArch64 Platforms* in the layout of the EFI memory map to enable the OS to make the required virtual mappings.

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SetVirtualAddressMap</td>
<td>Runtime</td>
<td>Used by an OS loader to convert from physical addressing to virtual addressing.</td>
</tr>
<tr>
<td>ConvertPointer</td>
<td>Runtime</td>
<td>Used by EFI components to convert internal pointers when switching to virtual addressing.</td>
</tr>
</tbody>
</table>

#### 8.4.1 SetVirtualAddressMap()

**Summary**

Changes the runtime addressing mode of EFI firmware from physical to virtual.

**Prototype**

```c
typedef
EFI_STATUS
SetVirtualAddressMap (  
    IN UINTN MemoryMapSize,
    IN UINTN DescriptorSize,
    IN UINT32 DescriptorVersion,
    IN EFI_MEMORY_DESCRIPTOR *VirtualMap
);
```

**Parameters**

- **MemoryMapSize**
  
  The size in bytes of `VirtualMap`. 

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**DescriptorSize**

The size in bytes of an entry in the VirtualMap.

**DescriptorVersion**

The version of the structure entries in VirtualMap.

**VirtualMap**

An array of memory descriptors which contain new virtual address mapping information for all runtime ranges. Type EFI_MEMORY_DESCRIPTOR is defined in the `EFI_BOOT_SERVICES.GetMemoryMap()` function description.

**Description**

The SetVirtualAddressMap() function is used by the OS loader. The function can only be called at runtime, and is called by the owner of the system’s memory map: i.e., the component which called `EFI_BOOT_SERVICES.ExitBootServices()`. All events of type EVT_SIGNAL_VIRTUAL_ADDRESS_CHANGE must be signaled before SetVirtualAddressMap() returns.

This call changes the addresses of the runtime components of the EFI firmware to the new virtual addresses supplied in the VirtualMap. The supplied VirtualMap must provide a new virtual address for every entry in the memory map at ExitBootServices() that is marked as being needed for runtime usage. All of the virtual address fields in the VirtualMap must be aligned on 4 KiB boundaries.

The call to SetVirtualAddressMap() must be done with the physical mappings. On successful return from this function, the system must then make any future calls with the newly assigned virtual mappings. All address space mappings must be done in accordance to the cacheability flags as specified in the original address map.

When this function is called, all events that were registered to be signaled on an address map change are notified. Each component that is notified must update any internal pointers for their new addresses. This can be done with the ConvertPointer() function. Once all events have been notified, the EFI firmware reapplyes image “fix-up” information to virtually relocate all runtime images to their new addresses. In addition, all of the fields of the EFI Runtime Services Table except SetVirtualAddressMap and ConvertPointer must be converted from physical pointers to virtual pointers using the ConvertPointer() service. The SetVirtualAddressMap() and ConvertPointer() services are only callable in physical mode, so they do not need to be converted from physical pointers to virtual pointers. Several fields of the EFI System Table must be converted from physical pointers to virtual pointers using the ConvertPointer() service. These fields include FirmwareVendor, RuntimeServices, and ConfigurationTable. Because contents of both the EFI Runtime Services Table and the EFI System Table are modified by this service, the 32-bit CRC for the EFI Runtime Services Table and the EFI System Table must be recomputed.

A virtual address map may only be applied one time. Once the runtime system is in virtual mode, calls to this function return EFI_UNSUPPORTED.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The virtual address map has been applied.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>EFI firmware is not at runtime, or the EFI firmware is already in virtual address mapped mode.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DescriptorSize or DescriptorVersion is invalid.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>A virtual address was not supplied for a range in the memory map that requires a mapping.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>A virtual address was supplied for an address that is not found in the memory map.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This call is not supported by this platform at the time the call is made. The platform should describe this runtime service as unsupported at runtime via an EFI_RT_PROPERTIES_TABLE configuration table.</td>
</tr>
</tbody>
</table>
8.4.2 ConvertPointer()

Summary
Determines the new virtual address that is to be used on subsequent memory accesses.

Prototype

```
typedef
EFI_STATUS
ConvertPointer (  
    IN UINTN DebugDisposition,  
    IN VOID **Address
    );
```

Parameters

DebugDisposition
Supplies type information for the pointer being converted. See “Related Definitions.”

Address
A pointer to a pointer that is to be fixed to be the value needed for the new virtual address mappings being applied.

Related Definitions

```
//**************************************************************
// EFI_OPTIONAL_PTR
//**************************************************************
#define EFI_OPTIONAL_PTR 0x00000001
```

Description
The ConvertPointer() function is used by an EFI component during the SetVirtualAddressMap() operation. ConvertPointer() must be called using physical address pointers during the execution of SetVirtualAddressMap().

The ConvertPointer() function updates the current pointer pointed to by Address to be the proper value for the new address map. Only runtime components need to perform this operation. The EFI_BOOT_SERVICES.CreateEvent() function is used to create an event that is to be notified when the address map is changing. All pointers the component has allocated or assigned must be updated.

If the EFI_OPTIONAL_PTR flag is specified, the pointer being converted is allowed to be NULL.

Once all components have been notified of the address map change, firmware fixes any compiled in pointers that are embedded in any runtime image.

Status Codes Returned

```
<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The pointer pointed to by Address was modified.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The pointer pointed to by Address was not found to be part of the current memory map. This is normally fatal.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Address is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>*Address is NULL and DebugDisposition does not have the EFI_OPTIONAL_PTR bit set.</td>
</tr>
</tbody>
</table>
```

continues on next page
Table 8.16 – continued from previous page

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_UNSUPPORTED</td>
<td></td>
<td>This call is not supported by this platform at the time the call is made. The platform should describe this runtime service as unsupported at runtime via an EFI_RT_PROPERTIES_TABLE configuration table.</td>
</tr>
</tbody>
</table>

8.5 Miscellaneous Runtime Services

This section contains the remaining function definitions for runtime services not defined elsewhere but which are required to complete the definition of the EFI environment. The Table, below, lists the Miscellaneous Runtime Services.

Miscellaneous Runtime Services

<table>
<thead>
<tr>
<th>Name</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>GetNextHigh-Monotonic-Count</td>
<td>Runtime</td>
<td>Returns the next high 32 bits of the platform’s monotonic counter.</td>
</tr>
<tr>
<td>ResetSystem</td>
<td>Runtime</td>
<td>Resets the entire platform.</td>
</tr>
<tr>
<td>UpdateCapsule</td>
<td>Runtime</td>
<td>Pass capsules to the firmware. The firmware may process the capsules immediately or return a value to be passed into Reset System that will cause the capsule to be processed by the firmware as part of the reset process.</td>
</tr>
<tr>
<td>QueryCapsule-Capabilities</td>
<td>Runtime</td>
<td>Returns if the capsule can be supported via UpdateCapsule()</td>
</tr>
</tbody>
</table>

8.5.1 Reset System

This section describes the reset system runtime service and its associated data structures.

8.5.1.1 ResetSystem()

Summary

Resets the entire platform. If the platform supports See ref:EFI_RESET_NOTIFICATION_PROTOCOL, then prior to completing the reset of the platform, all of the pending notifications must be called.

Prototype

typedef VOID (EFIAPI *EFI_RESET_SYSTEM) (IN EFI_RESET_TYPE ResetType, IN EFI_STATUS ResetStatus, IN UINTN DataSize, IN VOID *ResetData OPTIONAL);

Parameters

ResetType

The type of reset to perform. Type EFI_RESET_TYPE is defined in “Related Definitions” below.
ResetStatus
The status code for the reset. If the system reset is part of a normal operation, the status code would be EFI_SUCCESS. If the system reset is due to some type of failure the most appropriate EFI Status code would be used.

DataSize
The size, in bytes, of ResetData.

ResetData
For a ResetType of EfiResetCold, EfiResetWarm, or EfiResetShutdown the data buffer starts with a Null-terminated string, optionally followed by additional binary data. The string is a description that the caller may use to further indicate the reason for the system reset. For a ResetType of EfiResetPlatformSpecific the data buffer also starts with a Null-terminated string that is followed by an EFI_GUID that describes the specific type of reset to perform.

Related Definitions
```c
typedef enum {
    EfiResetCold,
    EfiResetWarm,
    EfiResetShutdown
    EfiResetPlatformSpecific
} EFI_RESET_TYPE;
```

Description
The ResetSystem() function resets the entire platform, including all processors and devices, and reboots the system.

Calling this interface with ResetType of EfiResetCold causes a system-wide reset. This sets all circuitry within the system to its initial state. This type of reset is asynchronous to system operation and operates without regard to cycle boundaries. EfiResetCold is tantamount to a system power cycle.

Calling this interface with ResetType of EfiResetWarm causes a system-wide initialization. The processors are set to their initial state, and pending cycles are not corrupted. If the system does not support this reset type, then an EfiResetCold must be performed.

Calling this interface with ResetType of EfiResetShutdown causes the system to enter a power state equivalent to the ACPI G2/S5 or G3 states. If the system does not support this reset type, then when the system is rebooted, it should exhibit the EfiResetCold attributes.

Calling this interface with ResetType of EfiResetPlatformSpecific causes a system-wide reset. The exact type of the reset is defined by the EFI_GUID that follows the Null-terminated Unicode string passed into ResetData. If the platform does not recognize the EFI_GUID in ResetData the platform must pick a supported reset type to perform. The platform may optionally log the parameters from any non-normal reset that occurs.

The ResetSystem() function does not return.
8.5.2 Get Next High Monotonic Count

This section describes the GetNextHighMonotonicCount runtime service and its associated data structures.

8.5.2.1 GetNextHighMonotonicCount()

Summary

Returns the next high 32 bits of the platform’s monotonic counter.

Prototype

```c
typedef EFI_STATUS
GetNextHighMonotonicCount (
    OUT UINT32 *HighCount
);
```

Parameters

HighCount

Pointer to returned value.

Description

The GetNextHighMonotonicCount() function returns the next high 32 bits of the platform’s monotonic counter.

The platform’s monotonic counter is comprised of two 32-bit quantities: the high 32 bits and the low 32 bits. During boot service time the low 32-bit value is volatile: it is reset to zero on every system reset and is increased by 1 on every call to GetNextMonotonicCount(). The high 32-bit value is nonvolatile and is increased by 1 whenever the system resets, whenever GetNextHighMonotonicCount() is called, or whenever the low 32-bit count (returned by GetNextMonoticCount()) overflows.

The EFI_BOOT_SERVICES.GetNextMonotonicCount() function is only available at boot services time. If the operating system wishes to extend the platform monotonic counter to runtime, it may do so by utilizing GetNextHighMonotonicCount(). To do this, before calling EFI_BOOT_SERVICES.ExitBootServices() the operating system would call GetNextMonotonicCount() to obtain the current platform monotonic count. The operating system would then provide an interface that returns the next count by:

- Adding 1 to the last count.
- Before the lower 32 bits of the count overflows, call GetNextHighMonotonicCount(). This will increase the high 32 bits of the platform’s nonvolatile portion of the monotonic count by 1.

This function may only be called at Runtime.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The next high monotonic count was returned.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device is not functioning properly.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>*HighCount is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This call is not supported by this platform at the time the call is made. The platform should describe this runtime service as unsupported at runtime via an EFI_RT_PROPERTIES_TABLE configuration table.</td>
</tr>
</tbody>
</table>

8.5. Miscellaneous Runtime Services 242
8.5.3 Update Capsule

This runtime function allows a caller to pass information to the firmware. Update Capsule is commonly used to update the firmware FLASH or for an operating system to have information persist across a system reset.

8.5.3.1 UpdateCapsule()

Summary

Passes capsules to the firmware with both virtual and physical mapping. Depending on the intended consumption, the firmware may process the capsule immediately. If the payload should persist across a system reset, the reset value returned from EFI_QueryCapsuleCapabilities must be passed into Reset System and will cause the capsule to be processed by the firmware as part of the reset process.

Prototype

```c
typedef EFI_STATUS UpdateCapsule (  
    IN EFI_CAPSULE_HEADER **CapsuleHeaderArray,  
    IN UINTN CapsuleCount,  
    IN EFI_PHYSICAL_ADDRESS ScatterGatherList OPTIONAL  
);
```

Parameters

CapsuleHeaderArray

Virtual pointer to an array of virtual pointers to the capsules being passed into update capsule. Each capsules is assumed to stored in contiguous virtual memory. The capsules in the CapsuleHeaderArray must be the same capsules as the ScatterGatherList. The CapsuleHeaderArray must have the capsules in the same order as the ScatterGatherList.

CapsuleCount

Number of pointers to EFI_CAPSULE_HEADER in CapsuleHeaderArray.

ScatterGatherList

Physical pointer to a set of EFI_CAPSULE_BLOCK_DESCRIPTOR that describes the location in physical memory of a set of capsules. See “Related Definitions” for an explanation of how more than one capsule is passed via this interface. The capsules in the ScatterGatherList must be in the same order as the CapsuleHeaderArray. This parameter is only referenced if the capsules are defined to persist across system reset.

Related Definitions

```c
typedef struct {  
    UINT64 Length;  
    union {  
        EFI_PHYSICAL_ADDRESS DataBlock;  
        EFI_PHYSICAL_ADDRESS ContinuationPointer;  
    } Union;  
} EFI_CAPSULE_BLOCK_DESCRIPTOR;
```

Length

Length in bytes of the data pointed to by DataBlock/ContinuationPointer.

DataBlock

Physical address of the data block. This member of the union is used if Length is not equal to zero.
ContinuationPointer

Physical address of another block of EFI_CAPSULE_BLOCK_DESCRIPTOR structures. This member of the union is used if Length is equal to zero. If ContinuationPointer is zero this entry represents the end of the list.

This data structure defines the ScatterGatherList list the OS passes to the firmware. ScatterGatherList represents an array of structures and is terminated with a structure member whose Length is 0 and DataBlock physical address is 0. If Length is 0 and DataBlock physical address is not 0, the specified physical address is known as a “continuation pointer” and it points to a further list of EFI_CAPSULE_BLOCK_DESCRIPTOR structures. A continuation pointer is used to allow the scatter gather list to be contained in physical memory that is not contiguous. It also is used to allow more than a single capsule to be passed at one time.

```c
typedef struct {
    EFI_GUID CapsuleGuid;
    UINT32 HeaderSize;
    UINT32 Flags;
    UINT32 CapsuleImageSize;
} EFI_CAPSULE_HEADER;
```

CapsuleGuid

A GUID that defines the contents of a capsule.

HeaderSize

The size of the capsule header. This may be larger than the size of the EFI_CAPSULE_HEADER since CapsuleGuid may imply extended header entries.

Flags

The Flags[15:0] bits are defined by CapsuleGuid. Flags[31:16] are defined by this specification.

CapsuleImageSize

Size in bytes of the capsule (including capsule header).

```c
#define CAPSULE_FLAGS_PERSIST_ACROSS_RESET 0x00010000
#define CAPSULE_FLAGS_POPULATE_SYSTEM_TABLE 0x00020000
#define CAPSULE_FLAGS_INITIATE_RESET 0x00040000
```

**NOTE:** A capsule which has the CAPSULE_FLAGS_INITIATE_RESET Flag must have CAPSULE_FLAGS_PERSIST_ACROSS_RESET set in its header as well. Firmware that encounters a capsule which has the CAPSULE_FLAGS_INITIATE_RESET Flag set in its header will initiate a reset of the platform which is compatible with the passed-in capsule request and will not return back to the caller.

```c
typedef struct {
    UINT32 CapsuleArrayNumber;
    VOID* CapsulePtr[1];
} EFI_CAPSULE_TABLE;
```

CapsuleArrayNumber

The number of entries in the array of capsules.

CapsulePtr

A pointer to an array of capsules that contain the same CapsuleGuid value. Each CapsulePtr points to an instance of an EFI_CAPSULE_HEADER, with the capsule data concatenated on its end.

Description

The UpdateCapsule() function allows the operating system to pass information to firmware. The UpdateCapsule() function supports passing capsules in operating system virtual memory back to firmware. Each capsule is contained in a contiguous virtual memory range in the operating system, but both a virtual and physical mapping for the capsules are passed to the firmware.
If a capsule has the CAPSULE_FLAGS_PERSIST_ACROSS_RESET Flag set in its header, the firmware will process the capsules after system reset. The caller must ensure to reset the system using the required reset value obtained from QueryCapsuleCapabilities. If this flag is not set, the firmware will process the capsules immediately.

A capsule which has the CAPSULE_FLAGS_POPULATE_SYSTEM_TABLE Flag must have CAPSULE_FLAGS_PERSIST_ACROSS_RESET set in its header as well. Firmware that processes a capsule that has the CAPSULE_FLAGS_POPULATE_SYSTEM_TABLE Flag set in its header will coalesce the contents of the capsule from the ScatterGatherList into a contiguous buffer and must then place a pointer to this coalesced capsule in the EFI System Table after the system has been reset. Agents searching for this capsule will look in the EFI_CONFIGURATION_TABLE and search for the capsule’s GUID and associated pointer to retrieve the data after the reset.

**Flag Firmware Behavior**

<table>
<thead>
<tr>
<th>Flags</th>
<th>Firmware Behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>No Specification defined flags</td>
<td>Firmware attempts to immediately processes or launch the capsule. If capsule is not recognized, can expect an error.</td>
</tr>
<tr>
<td>CAPSULE_FLAGS_PERSIST_ACROSS_RESET</td>
<td>Firmware will attempt to process or launch the capsule across a reset. If capsule is not recognized, can expect an error. If the processing requires a reset which is unsupported by the platform, expect an error.</td>
</tr>
<tr>
<td>CAPSULE_FLAGS_PERSIST_ACROSS_RESET + CAPSULE_FLAGS_POPULATE_SYSTEM_TABLE</td>
<td>Firmware will coalesce the capsule from the ScatterGatherList into a contiguous buffer and place a pointer to the coalesced capsule in the EFI System Table. Platform recognition of the capsule type is not required. If the action requires a reset which is unsupported by the platform, expect an error.</td>
</tr>
<tr>
<td>CAPSULE_FLAGS_PERSIST_ACROSS_RESET + CAPSULE_FLAGS_INITIATE_RESET</td>
<td>Firmware will attempt to process or launch the capsule across a reset. The firmware will initiate a reset which is compatible with the passed-in capsule request and will not return back to the caller. If the capsule is not recognized, can expect an error. If the processing requires a reset which is unsupported by the platform, expect an error.</td>
</tr>
<tr>
<td>CAPSULE_FLAGS_PERSIST_ACROSS_RESET + CAPSULE_FLAGS_INITIATE_RESET + CAPSULE_FLAGS_POPULATE_SYSTEM_TABLE</td>
<td>The firmware will initiate a reset which is compatible with the passed-in capsule request and not return back to the caller. Upon resetting, the firmware will coalesce the capsule from the ScatterGatherList into a contiguous buffer and place a pointer to the coalesced capsule in the EFI System Table. Platform recognition of the capsule type is not required. If the action requires a reset which is unsupported by the platform, expect an error.</td>
</tr>
</tbody>
</table>

The EFI System Table entry must use the GUID from the CapsuleGuid field of the EFI_CAPSULE_HEADER. The EFI System Table entry must point to an array of capsules that contain the same CapsuleGuid value. The array must be prefixed by a UINT32 that represents the size of the array of capsules.

The set of capsules is pointed to by ScatterGatherList and CapsuleHeaderArray so the firmware will know both the physical and virtual addresses of the operating system allocated buffers. The scatter-gather list supports the situation where the virtual address range of a capsule is contiguous, but the physical addresses are not.

On architectures where the processor’s view of main memory is incoherent with the caches when the memory management unit is disabled, callers to UpdateCapsule() must perform cache maintenance to main memory on each ScatterGatherList element before calling UpdateCapsule(). This requirement only applies after the OS has called ExitBootServices().

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If any of the capsules that are passed into this function encounter an error, the entire set of capsules will not be processed and the error encountered will be returned to the caller.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Valid capsule was passed. If CAPSULE_FLAGS_PERSIST ACROSS_RESET is not set, the capsule has been successfully processed by the firmware.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>CapsuleSize, or an incompatible set of flags were set in the capsule header.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>CapsuleCount is 0</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The capsule update was started, but failed due to a device error.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The capsule type is not supported on this platform.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>When ExitBootServices() has been previously called this error indicates the capsule is compatible with this platform but is not capable of being submitted or processed in runtime. The caller may resubmit the capsule prior to ExitBootServices().</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>When ExitBootServices() has not been previously called then this error indicates the capsule is compatible with this platform but there are insufficient resources to process.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This call is not supported by this platform at the time the call is made. The platform should describe this runtime service as unsupported at runtime via an EFI_RT_PROPERTIES_TABLE configuration table.</td>
</tr>
</tbody>
</table>

### 8.5.3.2 Capsule Definition

A capsule is simply a contiguous set of data that starts with an EFI_CAPSULE_HEADER. The CapsuleGuid field in the header defines the format of the capsule.

The capsule contents are designed to be communicated from an OS-present environment to the system firmware. To allow capsules to persist across system reset, a level of indirection is required for the description of a capsule, since the OS primarily uses virtual memory and the firmware at boot time uses physical memory. This level of abstraction is accomplished via the EFI_CAPSULE_BLOCK_DESCRIPTOR. The EFI_CAPSULE_BLOCK_DESCRIPTOR allows the OS to allocate contiguous virtual address space and describe this address space to the firmware as a discontinuous set of physical address ranges. The firmware is passed both physical and virtual addresses and pointers to describe the capsule so the firmware can process the capsule immediately or defer processing of the capsule until after a system reset.

In most instruction sets and OS architecture, allocation of physical memory is possible only on a “page” granularity (which can range for 4 KiB to at least 1 MiB). The EFI_CAPSULE_BLOCK_DESCRIPTOR must have the following properties to ensure the safe and well defined transition of the data:

- Each new capsule must start on a new page of memory.
- All pages except for the last must be completely filled by the capsule.
  - It is legal to pad the header to make it consume an entire page of data to enable the passing of page aligned data structures via a capsule. The last page must have at least one byte of capsule in it.
- Pages must be naturally aligned
- Pages may not overlap on another
- Firmware may never make an assumption about the page sizes the operating system is using.

Multiple capsules can be concatenated together and passed via a single call to UpdateCapsule(). The physical address description of capsules are concatenated by converting the terminating EFI_CAPSULE_BLOCK_DESCRIPTOR entry of the 1st capsule into a continuation pointer by making it point to the EFI_CAPSULE_BLOCK_DESCRIPTOR that...
represents the start of the 2nd capsule. There is only a single terminating EFI_CAPSULE_BLOCK_DESCRIPTOR entry and it is at the end of the last capsule in the chain.

The following algorithm must be used to find multiple capsules in a single scatter gather list:

- Look at the capsule header to determine the size of the capsule
  - The first Capsule header is always pointed to by the first EFI_CAPSULE_BLOCK_DESCRIPTOR entry
- Walk the EFI_CAPSULE_BLOCK_DESCRIPTOR list keeping a running count of the size each entry represents.
- If the EFI_CAPSULE_BLOCK_DESCRIPTOR entry is a continuation pointer and the running current capsule size count is greater than or equal to the size of the current capsule this is the start of the next capsule.
- Make the new capsules the current capsule and repeat the algorithm.

Figure, below, shows a Scatter-Gather list of EFI_CAPSULE_BLOCK_DESCRIPTOR structures that describes two capsules. The left side of the figure shows OS view of the capsules as two separate contiguous virtual memory buffers. The center of the figure shows the layout of the data in system memory. The right hand side of the figure shows the ScatterGatherList list passed into the firmware. Since there are two capsules two independent EFI_CAPSULE_BLOCK_DESCRIPTOR lists exist that were joined together via a continuation pointer in the first list.

![Fig. 8.1: Scatter-Gather List of EFI_CAPSULE_BLOCK_DESCRIPTOR Structures](image-url)
8.5.3.3 EFI_MEMORY_RANGE_CAPSULE_GUID

This capsule structure definition provides a means by which a third-party component (e.g. OS) can describe to firmware regions in memory should be left untouched across the next reset.

Support for this capsule is optional. For platforms that support this capsule, they must advertise EFI_MEMORY_RANGE_CAPSULE in the EFI Configuration table using the EFI_MEMORY_RANGE_CAPSULE_GUID as the GUID in the GUID/pointer pair.

```
// {0DE9F0EC-88B6-428F-977A-258F1D0E5E72}
#define EFI_MEMORY_RANGE_CAPSULE_GUID
  { 0xde9f0ec, 0x88b6, 0x428f, 
    { 0x97, 0x7a, 0x25, 0x8f, 0x1d, 0xe, 0x5e, 0x72 } }
```

A memory range descriptor.

```c
typedef struct
    EFI_PHYSICAL_ADDRESS Address;
    UINT64 Length;
} EFI_MEMORY_RANGE;
```

**Address**
Physical address of memory location being described.

**Length**
Length in bytes.

The capsule descriptor that describes the memory ranges a platform firmware should leave untouched.

```c
typedef struct {
    EFI_CAPSULE_HEADER Header;
    UINT32 OsRequestedMemoryType;
    UINT64 NumberOfMemoryRanges;
    EFI_MEMORY_RANGE MemoryRanges[];
} EFI_MEMORY_RANGE_CAPSULE;
```

**Header**
Header.CapsuleGuid = EFI_MEMORY_RANGE_CAPSULE_GUID
Header.Flags = CAPSULE_FLAGS_PERSIST_ACROSS_RESET

**OsRequestedMemoryType**
Must be in the 0x80000000-0xFFFFFFFF range
When UEFI Firmware processes the capsule, contents described in MemoryRanges[] will show up as OsRequestedMemoryType values in the EFI Memory Map.

**NumberOfMemoryRanges**
Number of MemoryRanges[] entries. Must be a value of 1 or greater.

**MemoryRanges[]**
An array of memory ranges. Equivalent to MemoryRanges[NumberOfMemoryRanges].

For a platform that intends to support the EFI_MEMORY_RANGE_CAPSULE, it must advertise EFI_MEMORY_RANGE_CAPSULE_RESULT in the EFI Configuration table using the EFI_MEMORY_RANGE_CAPSULE_GUID as the GUID in the GUID/pointer pair.
typedef struct {
    UINT64 FirmwareMemoryRequirement;
    UINT64 NumberOfMemoryRanges;
} EFI_MEMORY_RANGE_CAPSULE_RESULT

FirmwareMemoryRequirement
The maximum amount of memory in bytes that the UEFI firmware requires to initialize.

NumberOfMemoryRanges
Will be 0 if no EFI_MEMORY_RANGE_CAPSULE has been processed. If a EFI_MEMORY_RANGE_CAPSULE was processed, this number will be identical to the EFI_MEMORY_RANGE_CAPSULE.NumberOfMemoryRanges value.

8.5.3.4 QueryCapsuleCapabilities()

Summary
Returns if the capsule can be supported via UpdateCapsule().

Prototype

typedef
EFI_STATUS
QueryCapsuleCapabilities (  
    IN EFI_CAPSULE_HEADER **CapsuleHeaderArray,  
    IN UINTN CapsuleCount,  
    OUT UINT64 *MaximumCapsuleSize,  
    OUT EFI_RESET_TYPE *ResetType
  );

CapsuleHeaderArray
Virtual pointer to an array of virtual pointers to the capsules being passed into update capsule. The capsules are assumed to stored in contiguous virtual memory.

CapsuleCount*
Number of pointers to EFI_CAPSULE_HEADER in CapsuleHeaderArray.

MaximumCapsuleSize
On output the maximum size in bytes that UpdateCapsule() can support as an argument to UpdateCapsule() via CapsuleHeaderArray and ScatterGatherList. Undefined on input.

ResetType
Returns the type of reset required for the capsule update. Undefined on input.

Description
The QueryCapsuleCapabilities() function allows a caller to test to see if a capsule or capsules can be updated via UpdateCapsule(). The Flags values in the capsule header and size of the entire capsule is checked.

If the caller needs to query for generic capsule capability a fake EFI_CAPSULE_HEADER can be constructed where CapsuleImageSize is equal to HeaderSize that is equal to sizeof (EFI_CAPSULE_HEADER). To determine reset requirements, CAPSULE_FLAGS_PERSIST_ACROSS_RESET should be set in the Flags field of the EFI_CAPSULE_HEADER.

Status Codes Returned
<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Valid answer returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>MaximumCapsuleSize is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The capsule type is not supported on this platform, and MaximumCapsuleSize and ResetType are undefined.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>When ExitBootServices() has been previously called this error indicates the capsule is compatible with this platform but is not capable of being submitted or processed in runtime. The caller may resubmit the capsule prior to ExitBootServices().</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>When ExitBootServices() has not been previously called then this error indicates the capsule is compatible with this platform but there are insufficient resources to process.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This call is not supported by this platform at the time the call is made. The platform should describe this runtime service as unsupported at runtime via an EFI_RT_PROPERTIES_TABLE configuration table.</td>
</tr>
</tbody>
</table>

8.5.4 Exchanging information between the OS and Firmware

The firmware and an Operating System may exchange information through the OsIndicationsSupported and the OSIndications variables as follows:

- The OsIndications variable returns a UINT64 bitmask owned by the OS and is used to indicate which features the OS wants firmware to enable or which actions the OS wants the firmware to take. The OS will supply this data with a SetVariable() call.
- The OsIndicationsSupported variable returns a UINT64 bitmask owned by the firmware and indicates which of the OS indication features and actions that the firmware supports. This variable is recreated by firmware every boot, and cannot be modified by the OS.

The EFI_OS_INDICATIONS_BOOT_TO_FW_UI bit can be set in the OsIndicationsSupported variable by the firmware, if the firmware supports OS requests to stop at a firmware user interface. The EFI_OS_INDICATIONS_BOOT_TO_FW_UI bit can be set by the OS in the OsIndications variable, if the OS desires for the firmware to stop at a firmware user interface on the next boot. Once the firmware consumes this bit in the OsIndications variable and stops at the firmware user interface, the firmware should clear the bit from the OsIndications variable in order to acknowledge to the OS that the information was consumed and, more importantly, to prevent the firmware user interface from showing again on subsequent boots.

The EFI_OS_INDICATIONS_TIMESTAMP_REVOCATION bit can be set in the OsIndicationsSupported variable by the firmware, if the firmware supports timestamp based revocation and the “dbt” authorized timestamp database variable.

The EFI_OS_INDICATIONS_FMP_CAPSULE_SUPPORTED bit is set in OsIndicationsSupported variable if platform supports processing of Firmware Management Protocol update capsule as defined in Dependency Expression Instruction Set. If set in OsIndications variable, the EFI_OS_INDICATIONS_FMP_CAPSULE_SUPPORTED bit has no function and is cleared on the next reboot.

The EFI_OS_INDICATIONS_FILE_CAPSULE_DELIVERY_SUPPORTED bit in OsIndicationsSupported variable is set if platform supports processing of file capsules per Delivery of Capsules via file on Mass Storage Device.

When submitting capsule via the Mass Storage Device method of Delivery of Capsules via file on Mass Storage Device, the bit EFI_OS_INDICATIONS_FILE_CAPSULE_DELIVERY_SUPPORTED in OsIndications variable must be set by submitter to trigger processing of submitted capsule on next reboot. This bit will be cleared from OsIndications by system firmware in all cases during processing following reboot.

The EFI_OS_INDICATIONS_CAPSULE_RESULT_VAR_SUPPORTED bit is set in OsIndicationsSupported variable if platform supports reporting of deferred capsule processing by creation of result variable as defined in UEFI.
variable reporting on the Success or any Errors encountered in processing of capsules after restart. This bit has no function if set in OsIndications.

The EFI_OS_INDICATIONS_START_OS_RECOVERY bit is set in the OsIndicationsSupported variable if the platform supports both the ability for an OS to indicate that OS-defined recovery should commence upon reboot, as well as support for the short-form File Path Media Device Path (See Load Option Processing). If this bit is set in OsIndications, the platform firmware must bypass processing of the BootOrder variable during boot, and skip directly to OS-defined recovery (OS-Defined Boot Option Recovery) followed by Platform-defined recovery (Platform-Defined Boot Option Recovery). System firmware must clear this bit in OsIndications when it starts OS-defined recovery.

The EFI_OS_INDICATIONS_START_PLATFORM_RECOVERY bit is set in the OsIndicationsSupported variable if the platform supports both the ability for an OS to indicate that Platform-defined recovery should commence upon reboot, as well as support for the short-form File Path Media Device Path (Load Option Processing). If this bit is set in OsIndications, the platform firmware must bypass processing of the BootOrder variable during boot, and skip directly to Platform-Defined Boot Option Recovery. System firmware must clear this bit in OsIndications when it starts Platform-defined recovery.

In all cases, if either of EFI_OS_INDICATIONS_START_OS_RECOVERY or EFI_OS_INDICATIONS_START_PLATFORM_RECOVERY is set in OsIndicationsSupported, both must be set and supported.

The EFI_OS_INDICATIONS_JSON_CONFIG_DATA_REFRESH bit is set in the OsIndications variable by submitter to trigger collecting current configuration and reporting the refreshed data to EFI System Configuration Table on next boot. If not set, platform will not collect current configuration but report the cached configuration data to EFI System Configuration Table. The configuration data shall be installed to EFI System Configuration Table using the format of EFI_JSON_CAPSULE_CONFIG_DATA defined in Defined JSON Capsule Data Structure. This bit will be cleared from OsIndications by system firmware once the refreshed data is reported.

If set in the OsIndicationsSupported variable, the EFI_OS_INDICATIONS_JSON_CONFIG_DATA_REFRESH bit has no function and is cleared on the next reboot.

Related Definitions

```
#define EFI_OS_INDICATIONS_BOOT_TO_FW_UI 0x0000000000000001
#define EFI_OS_INDICATIONS_TIMESTAMP_REVOCATION \ 0x0000000000000002
#define EFI_OS_INDICATIONS_FILE_CAPSULE_DELIVERY_SUPPORTED \ 0x0000000000000004
#define EFI_OS_INDICATIONS_FMP_CAPSULE_SUPPORTED \ 0x0000000000000008
#define EFI_OS_INDICATIONS_CAPSULE_RESULT_VAR_SUPPORTED \ 0x0000000000000010
#define EFI_OS_INDICATIONS_START_OS_RECOVERY \ 0x0000000000000020
#define EFI_OS_INDICATIONS_START_PLATFORM_RECOVERY \ 0x0000000000000040
#define EFI_OS_INDICATIONS_JSON_CONFIG_DATA_REFRESH \ 0x0000000000000080
```

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8.5.5 Delivery of Capsules via file on Mass Storage Device

As an alternative to the UpdateCapsule() runtime API, capsules of any type supported by platform may also be delivered to firmware via a file within the EFI system partition on the mass storage device targeted for boot. Capsules staged using this method are processed on the next system restart. This method is only available when booting from mass storage devices which are formatted with GPT and contain an EFI System Partition in the device image. System firmware will search for capsule when EFI_OS_INDICATIONS_FILE_CAPSULE_DELIVERY_SUPPORTED bit in OsIndications is set as described in Exchanging information between the OS and Firmware.

The directory EFIUpdateCapsule (letter case ignored) within the active EFI System Partition is defined for delivery of capsule to firmware. The binary structure of a capsule file on mass storage device is identical to the contents of capsule delivered via the EFI RunTime API except that fragmentation using EFI_CAPSULE_BLOCK_DESCRIPTOR is not supported and the single capsule must be stored in contiguous bytes within the file starting with EFI_CAPSULE_HEADER. The size of the file must equal EFI_CAPSULE_HEADER. CapsuleImageSize or error will be generated and the capsule ignored. Only a single capsule with a single EFI_CAPSULE_HEADER may be submitted within a file but more than one file each containing a capsule may be submitted during a single restart.

The file name of the capsule shall be chosen by submitter using 8-bit ASCII characters appropriate to the file system of the EFI system partition (System Partition). After examination and processing of a file placed in this directory the file will (if possible) be deleted by firmware. The deletion is performed in case of successful processing and also in the case of error but failure to successfully delete is not itself a reportable error.

More than one capsule file each containing a single capsule image may be stored in the specified directory. In case of multiple files, the system firmware shall process files in alphabetical order using sort based on CHAR16 numerical value of file name characters, compared left to right. Lower case letter characters will be converted to upper case before compare. When comparing file names of unequal length, the space character shall be used to pad shorter file names. In case of file name containing one or more period characters (.), the right-most period, and the text to the right of the right-most period in the file name, will be removed before compare. In case of any file names with identical text after excluding any text after the right-most period, the order of processing shall be determined by sorting of any text found to right of the right-most period in file name string.

If a capsule processing is terminated by error any remaining additional capsule files will be processed normally.

The directory EFIUpdateCapsule is checked for capsules only within the EFI system partition on the device specified in the active boot option determine by reference to BootNext variable or BootOrder variable processing. The active Boot Variable is the variable with highest priority BootNext or within BootOrder that refers to a device found to be present. Boot variables in BootOrder but referring to devices not present are ignored when determining active boot variable.

The device to be checked for EFIUpdateCapsule is identified by reference to FilePathList field within the selected active Boot#### variable. The system firmware is not required to check mass storage devices that do not contain boot target that is highest priority for boot nor to check a second EFI system partition not the target of the active boot variable.

In all cases that a capsule is identified for processing the system is restarted after capsule processing is completed. In case where BootNext variable was set, this variable is cleared when capsule processing is performed without actual boot of the variable indicated.

8.5.6 UEFI variable reporting on the Success or any Errors encountered in processing of capsules after restart

In cases where the processing of capsules is (1) delivered by call to UpdateCapsule() API but deferred to next restart, or (2) when capsules are delivered via mass storage device, a UEFI variable is created by firmware to indicate to capsule provider the status of the capsule processing. In the case were multiple capsules are delivered in calls to UpdateCapsule(), or multiple files on disk as described in Delivery of Capsules via file on Mass Storage Device, or when a capsule contains multiple payloads as described in Dependency Expression Instruction Set, a separate result variable will be created for each capsule payload processed. The firmware will over-write result variables when calculated
variable name already exists. However, to avoid unnecessarily consuming system variable store, the result variable should be deleted by capsule provider after result status is examined.

UEFI variable reports will not be used when the entirety of capsule processing occurs within the call to UpdateCapsule() function.

The reporting variable attributes will be EFI_VARIABLE_NON_VOLATILE + EFI_VARIABLE_BOOTSERVICE_ACCESS + EFI_VARIABLE_RUNTIME_ACCESS.

The Vendor GUID of the reporting variable will be EFI_CAPSULE_REPORT_GUID. The name of the reporting variable will be CapsuleNNNN where NNNN is 4-digit hex number chosen by the firmware. The values of NNNN will be incremented by firmware starting at Capsule0000 and continuing up to the platform-defined maximum.

The platform will publish the platform maximum in a read-only variable named EFI_CAPSULE_REPORT_GUID: CapsuleMax. The contents of CapsuleMax will be the string “CapsuleNNNN” where NNNN is the highest value used by platform before rolling over to Capsule0000. The platform will also publish the name of the last variable created in EFI_CAPSULE_REPORT_GUID: CapsuleLast.

When creating a new result variable, any previous variable with the same name will be overwritten. In case where variable storage is limited, system firmware may optionally delete oldest report variables to create free space. If sufficient variable space cannot be freed, the variable is not created.

<table>
<thead>
<tr>
<th>Variable Name</th>
<th>Attributes</th>
<th>Internal Format</th>
</tr>
</thead>
<tbody>
<tr>
<td>Capsule0000, Capsule0001, ... up to max</td>
<td>NV, BS, RT</td>
<td>EFI_CAPSULE_RESULT_VARIABLE</td>
</tr>
<tr>
<td>CapsuleMax</td>
<td>BS, RT, Read-Only</td>
<td>CHAR16[11] (no zero terminator)</td>
</tr>
<tr>
<td>CapsuleLast</td>
<td>NV, BS, RT, Read-Only</td>
<td>CHAR16[11] (no zero terminator)</td>
</tr>
</tbody>
</table>

8.5.6.1 EFI_CAPSULE_REPORT_GUID

```c
// {39B68C46-F7FB-441B-B6EC-16B0F69821F3}
#define EFI_CAPSULE_REPORT_GUID \
            { 0x39b68c46, 0xf7fb, 0x441b, \
              {0xb6, 0xec, 0x16, 0xb0, 0xf6, 0x98, 0x21, 0xf3 }};
```

8.5.6.1.1 Structure of the Capsule Processing Result Variable

The Capsule Processing Result Variable contents always begin with the EFI_CAPSULE_RESULT_VARIABLE_HEADER structure. The value of CapsuleGuid determines any additional data that may follow within the instance of the Result Variable contents. For some values of CapsuleGuid no additional data may be defined.

As noted below, VariableTotalSize is the size of complete result variable including the entire header and any additional data required for particular CapsuleGuid types.

```c
typedef struct {
  UINT32 VariableTotalSize;
  UINT32 Reserved; // for alignment
  EFI_GUID CapsuleGuid;
  EFI_TIME CapsuleProcessed;
  EFI_STATUS CapsuleStatus;
} EFI_CAPSULE_RESULT_VARIABLE_HEADER;
```
**VariableTotalSize**
Size in bytes of the variable including any data beyond header as specified by `CapsuleGuid`.

**CapsuleGuid**
Guid from EFI_CAPSULE_HEADER

**CapsuleProcessed**
Timestamp using system time when processing completed.

**CapsuleStatus**
Result of the capsule processing. Exact interpretation of any error code may depend upon type of capsule processed.

### 8.5.6.1.2 Additional Structure When CapsuleGuid is EFI_FIRMWARE_MANAGEMENT_CAPSULE_ID_GUID

The capsule Processing Result Variable contents always begin with EFI_CAPSULE_RESULT_VARIABLE_HEADER. When `CapsuleGuid` is EFI_FIRMWARE_MANAGEMENT_CAPSULE_ID_GUID, the header is followed by additional data as defined by EFI_CAPSULE_RESULT_VARIABLE_FMP.

```c
typedef struct {
    UINT16 Version;
    UINT8 PayloadIndex;
    UINT16 UpdateImageIndex;
    EFI_GUID UpdateImageTypeId;
    // CHAR16 CapsuleFileName [];
    // CHAR16 CapsuleTarget [];
    EFI_CAPSULE_RESULT_VARIABLE_FMP;
} EFI_CAPSULE_RESULT_VARIABLE_FMP;
```

**Version**
The version of this structure, currently 0x00000001.

**PayloadIndex**
The index, starting from zero, of the payload within the FMP capsule which was processed to generate this report.

**UpdateImageIndex**
The `UpdateImageIndex` from EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER (after unsigned conversion from UINT8 to UINT16).

**UpdateImageTypeId**
The `UpdateImageTypeId` Guid from EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER.

**CapsuleFileName**
In case of capsule loaded from disk, the zero-terminated array containing file name of capsule that was processed. In case of capsule submitted directly to UpdateCapsule() there is no file name, and this field is required to contain a single 16-bit zero character which is included in `VariableTotalSize`.

**CapsuleTarget**
This field will contain a zero-terminated CHAR16 string containing the text representation of the device path of device publishing Firmware Management Protocol (if present). In case where device path is not present and the target is not otherwise known to firmware, or when payload was blocked by policy, or skipped, this field is required to contain a single 16-bit zero character which is included in `VariableTotalSize`.

---

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8.5.6.1.3 Additional Structure When CapsuleGuid is EFI_JSON_CAPSULE_ID_GUID

The Capsule Processing Result Variable contents always begin with EFI_CAPSULE_RESULT_VARIABLE_HEADER. When CapsuleGuid is EFI_JSON_CAPSULE_ID_GUID, the header is followed by additional data as defined by EFI_CAPSULE_RESULT_VARIABLE_JSON.

```
typedef struct {
    UINT32 Version;
    UINT32 CapsuleId;
    UINT32 RespLength;
    UINT8 Resp[];
} EFI_CAPSULE_RESULT_VARIABLE_JSON;
```

**Version**

The version of this structure, currently 0x00000001.

**CapsuleId**

The unique identifier of the capsule whose processing result is recorded in this variable.  
0x00000000 - 0xFFFFFFFF - Implementation Reserved  
0xF0000000 - 0xFFFFFFFF - Specification Reserved  
#define REDFISH_DEFINED_JSON_SCHEMA 0xF000000  
The JSON payload shall conform to a Redfish-defined JSON schema, see DMTF-Redfish Specification.

**RespLength**

The length of `Resp` in bytes.

**Resp**

Variable length buffer containing the replied JSON payload to the caller who delivered JSON capsule to system.  The definition of the JSON schema used in the replied payload is beyond the scope of this specification.

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>Valid capsule was passed and the capsule has been successfully processed by the firmware.</td>
</tr>
<tr>
<td><strong>EFI_INVALID_PARAMETER</strong></td>
<td>Invalid capsule size, or an incompatible set of flags were set in the capsule header. In the case of a capsule file, the file size was not valid or an error was detected in the internal structure of the file.</td>
</tr>
<tr>
<td><strong>EFI_DEVICE_ERROR</strong></td>
<td>The capsule update was started, but failed due to a device error.</td>
</tr>
<tr>
<td><strong>EFI_ACCESS_DENIED</strong></td>
<td>Image within capsule was not loaded because the platform policy prohibits the image from being loaded.</td>
</tr>
<tr>
<td><strong>EFI_LOAD_ERROR</strong></td>
<td>For capsule with included driver, no driver with correct format for the platform was found.</td>
</tr>
<tr>
<td><strong>EFI_UNSUPPORTED</strong></td>
<td>The capsule type is not supported on this platform. Or the capsule internal structures were not recognized as valid by the platform.</td>
</tr>
<tr>
<td><strong>EFI_OUT_OF_RESOURCES</strong></td>
<td>There were insufficient resources to process the capsule.</td>
</tr>
<tr>
<td><strong>EFI_NOT_READY</strong></td>
<td>Capsule payload blocked by platform policy.</td>
</tr>
<tr>
<td><strong>EFI_ABORTED</strong></td>
<td>Capsule payload was skipped.</td>
</tr>
<tr>
<td><strong>EFI_UNSUPPORTED</strong></td>
<td>This call is not supported by this platform at the time the call is made. The platform should describe this runtime service as unsupported at runtime via an EFI_RT_PROPERTIES_TABLE configuration table.</td>
</tr>
</tbody>
</table>

8.5. Miscellaneous Runtime Services
This section defines EFI_LOADED_IMAGE_PROTOCOL and the EFI_LOADED_IMAGE_DEVICE_PATH_PROTOCOL. Respectively, these protocols describe an Image that has been loaded into memory and specifies the device path used when a PE/COFF image was loaded through the EFI Boot Service LoadImage(). These descriptions include the source from which the image was loaded, the current location of the image in memory, the type of memory allocated for the image, and the parameters passed to the image when it was invoked.

9.1 EFI Loaded Image Protocol

9.1.1 EFI_LOADED_IMAGE_PROTOCOL

Summary
Can be used on any image handle to obtain information about the loaded image.

GUID

#define EFI_LOADED_IMAGE_PROTOCOL_GUID
{0x5B1B31A1,0x9562,0x11d2,
  {0x8E,0x3F,0x00,0xA0,0xC9,0x69,0x72,0x3B}}

Revision Number

#define EFI_LOADED_IMAGE_PROTOCOL_REVISION 0x1000

Protocol Interface Structure

typedef struct {
  UINT32 Revision;
  EFI_HANDLE ParentHandle;
  *SystemTable;

  // Source location of the image
  EFI_HANDLE DeviceHandle;
  *FilePath;
  *Reserved;

  // Image’s load options
  UINT32 LoadOptionsSize;
  *LoadOptions;
} EFI_LOADED_IMAGE_PROTOCOL;

(continues on next page)
Parameters

Revision
Defines the revision of the EFI_LOADED_IMAGE_PROTOCOL structure. All future revisions will be backward compatible to the current revision.

ParentHandle
Parent image’s image handle. NULL if the image is loaded directly from the firmware’s boot manager. Type EFI_HANDLE is defined in Services – Boot Services.

SystemTable
The image’s EFI system table pointer. Type EFI_SYSTEM_TABLE defined in EFI System Table.

DeviceHandle
The device handle that the EFI Image was loaded from. Type EFI_HANDLE is defined in Services – Boot Services.

FilePath
A pointer to the file path portion specific to DeviceHandle that the EFI Image was loaded from. EFI_DEVICE_PATH_PROTOCOL is defined in EFI Device Path Protocol.

Reserved
Reserved. DO NOT USE.

LoadOptionsSize
The size in bytes of LoadOptions.

LoadOptions
A pointer to the image’s binary load options. See the OptionalData parameter in the Load Options section of the Boot Manager chapter for information on the source of the LoadOptions data.

ImageBase
The base address at which the image was loaded.

ImageSize
The size in bytes of the loaded image.

ImageCodeType
The memory type that the code sections were loaded as. Type EFI_MEMORY_TYPE is defined in Services – Boot Services.

ImageDataType
The memory type that the data sections were loaded as. Type EFI_MEMORY_TYPE is defined in Services – Boot Services.

Unload
Function that unloads the image - see Section 9.1.2.

Description
Each loaded image has an image handle that supports EFI_LOADED_IMAGE_PROTOCOL. When an image is started, it is passed the image handle for itself. The image can use the handle to obtain its relevant image data stored in the
EFI_LOADED_IMAGE_PROTOCOL structure, such as its load options.

### 9.1.2 EFI_LOADED_IMAGE_PROTOCOLUnload()

**Summary**

Unloads an image from memory.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_IMAGE_UNLOAD) (
    IN EFI_HANDLE ImageHandle,
);
```

**Parameters**

- **ImageHandle**
  
  The handle to the image to unload. Type EFI_HANDLE [Driver Model Boot Services](https://www.uefi.org/specs/

**Description**

The Unload() function is a callback that a driver registers to do cleanup when the UnloadImage boot service function is called.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The image was unloaded.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>ImageHandle</code> was not valid.</td>
</tr>
</tbody>
</table>

### 9.2 EFI Loaded Image Device Path Protocol

#### 9.2.1 EFI_LOADED_IMAGE_DEVICE_PATH_PROTOCOL

**Summary**

When installed, the Loaded Image Device Path Protocol specifies the device path that was used when a PE/COFF image was loaded through the EFI Boot Service LoadImage().

**GUID**

```c
#define EFI_LOADED_IMAGE_DEVICE_PATH_PROTOCOL_GUID \
    {0xbc62157e,0x3e33,0x4fec,\ 
    {0x99,0x20,0x2d,0x3b,0x36,0xd7,0x50,0xdf}}
```

**Description**

The Loaded Image Device Path Protocol uses the same protocol interface structure as the Device Path Protocol defined in Chapter 9. The only difference between the Device Path Protocol and the Loaded Image Device Path Protocol is the protocol GUID value.

The Loaded Image Device Path Protocol must be installed onto the image handle of a PE/COFF image loaded through the EFI Boot Service LoadImage(). A copy of the device path specified by the `DevicePath` parameter to the EFI Boot Service LoadImage() is made before it is installed onto the image handle. It is legal to call LoadImage() for a buffer in
memory with a NULL DevicePath parameter. In this case, the Loaded Image Device Path Protocol is installed with a NULL interface pointer.
This section contains the definition of the device path protocol and the information needed to construct and manage device paths in the UEFI environment. A device path is constructed and used by the firmware to convey the location of important devices, such as the boot device and console, consistent with the software-visible topology of the system.

10.1 Device Path Overview

A Device Path is used to define the programmatic path to a device. The primary purpose of a Device Path is to allow an application, such as an OS loader, to determine the physical device that the interfaces are abstracting.

A collection of device paths is usually referred to as a name space. ACPI, for example, is rooted around a name space that is written in ASL (ACPI Source Language). Given that EFI does not replace ACPI and defers to ACPI when ever possible, it would seem logical to utilize the ACPI name space in EFI. However, the ACPI name space was designed for usage at operating system runtime and does not fit well in platform firmware or OS loaders. Given this, EFI defines its own name space, called a Device Path.

A Device Path is designed to make maximum leverage of the ACPI name space. One of the key structures in the Device Path defines the linkage back to the ACPI name space. The Device Path also is used to fill in the gaps where ACPI defers to buses with standard enumeration algorithms. The Device Path is able to relate information about which device is being used on buses with standard enumeration mechanisms. The Device Path is also used to define the location on a medium where a file should be, or where it was loaded from. A special case of the Device Path can also be used to support the optional booting of legacy operating systems from legacy media.

The Device Path was designed so that the OS loader and the operating system could tell which devices the platform firmware was using as boot devices. This allows the operating system to maintain a view of the system that is consistent with the platform firmware. An example of this is a “headless” system that is using a network connection as the boot device and console. In such a case, the firmware will convey to the operating system the network adapter and network protocol information being used as the console and boot device in the device path for these devices.

10.2 EFI Device Path Protocol

This section provides a detailed description of EFI_DEVICE_PATH_PROTOCOL.

Summary

Can be used on any device handle to obtain generic path/location information concerning the physical device or logical device. If the handle does not logically map to a physical device, the handle may not necessarily support the device path protocol. The device path describes the location of the device the handle is for. The size of the Device Path can be determined from the structures that make up the Device Path.

GUID
Protocol Interface Structure

```c
//EFI_DEVICE_PATH_PROTOCOL
typedef struct _EFI_DEVICE_PATH_PROTOCOL {
    UINT8     Type;
    UINT8     SubType;
    UINT8     Length[2];
} EFI_DEVICE_PATH_PROTOCOL;
```

Description

The executing UEFI Image may use the device path to match its own device drivers to the particular device. Note that the executing UEFI OS loader and UEFI application images must access all physical devices via Boot Services device handles until `EFI_BOOT_SERVICES.ExitBootServices()` is successfully called. A UEFI driver may access only a physical device for which it provides functionality.

10.3 Device Path Nodes

There are six major types of Device Path nodes:

- Hardware Device Path. This Device Path defines how a device is attached to the resource domain of a system, where resource domain is simply the shared memory, memory mapped I/O, and I/O space of the system.
- ACPI Device Path. This Device Path is used to describe devices whose enumeration is not described in an industry-standard fashion. These devices must be described using ACPI AML in the ACPI name space; this Device Path is a linkage to the ACPI name space.
- Messaging Device Path. This Device Path is used to describe the connection of devices outside the resource domain of the system. This Device Path can describe physical messaging information such as a SCSI ID, or abstract information such as networking protocol IP addresses.
- Media Device Path. This Device Path is used to describe the portion of a medium that is being abstracted by a boot service. For example, a Media Device Path could define which partition on a hard drive was being used.
- BIOS Boot Specification Device Path. This Device Path is used to point to boot legacy operating systems; it is based on the BIOS Boot Specification Version 1.01. Refer to Appendix Q — References’ for details on obtaining this specification.
- End of Hardware Device Path. Depending on the Sub-Type, this Device Path node is used to indicate the end of the Device Path instance or Device Path structure.
10.3.1 Generic Device Path Structures

A Device Path is a variable-length binary structure that is made up of variable-length generic Device Path nodes. *Generic Device Path Node Structure* defines the structure of a variable-length generic Device Path node and the lengths of its components. The table (below) defines the type and sub-type values corresponding to the Device Paths described in *Device Path Nodes*; all other type and sub-type values are Reserved.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 0x01 - Hardware Device Path</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Type 0x02 - ACPI Device Path</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Type 0x03 - Messaging Device Path</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Type 0x04 - Media Device Path</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Type 0x05 - BIOS Boot Specification Device Path</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Type 0x7F - End of Hardware Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type - Varies by Type. (See table below)</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 4 + n bytes.</td>
</tr>
<tr>
<td>Specific</td>
<td>4</td>
<td>n</td>
<td>Specific Device Path data. Type and Sub-Type define type of data. Size</td>
</tr>
<tr>
<td>Device Path</td>
<td></td>
<td></td>
<td>data is included in Length.</td>
</tr>
</tbody>
</table>

A Device Path is a series of generic Device Path nodes. The first Device Path node starts at byte offset zero of the Device Path. The next Device Path node starts at the end of the previous Device Path node. Therefore all nodes are byte-packed data structures that may appear on any byte boundary. All code references to device path notes must assume all fields are unaligned. Since every Device Path node contains a length field in a known place, it is possible to traverse Device Path nodes that are of an unknown type. There is no limit to the number, type, or sequence of nodes in a Device Path.

A Device Path is terminated by an End of Hardware Device Path node. This type of node has two sub-types (*Device Path End Structures*):

- **End This Instance of a Device Path** (sub-type 0x01). This type of node terminates one Device Path instance and denotes the start of another. This is only required when an environment variable represents multiple devices. An example of this would be the *ConsoleOut* environment variable that consists of both a VGA console and serial output console. This variable would describe a console output stream that is sent to both VGA and serial concurrently and thus has a Device Path that contains two complete Device Paths.

- **End Entire Device Path** (sub-type 0xFF). This type of node terminates an entire Device Path. Software searches for this sub-type to find the end of a Device Path. All Device Paths must end with this sub-type.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 0x7F - End of Hardware Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 0xFF - End Entire Device Path, or Sub-Type 0x01 - End This Instance of a Device Path and start a new Device Path</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 4 bytes.</td>
</tr>
</tbody>
</table>
10.3.2 Hardware Device Path

This Device Path defines how a device is attached to the resource domain of a system, where resource domain is simply the shared memory, memory mapped I/O, and I/O space of the system. It is possible to have multiple levels of Hardware Device Path such as a PCCARD device that was attached to a PCCARD PCI controller.

10.3.2.1 PCI Device Path

The Device Path for PCI defines the path to the PCI configuration space address for a PCI device. There is one PCI Device Path entry for each device and function number that defines the path from the root PCI bus to the device. Because the PCI bus number of a device may potentially change, a flat encoding of single PCI Device Path entry cannot be used. An example of this is when a PCI device is behind a bridge, and one of the following events occurs:

- OS performs a Plug and Play configuration of the PCI bus.
- A hot plug of a PCI device is performed.
- The system configuration changes between reboots.

The PCI Device Path entry must be preceded by an ACPI Device Path entry that uniquely identifies the PCI root bus. The programming of root PCI bridges is not defined by any PCI specification and this is why an ACPI Device Path entry is required.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 1 - Hardware Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 1 - PCI</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure is 6 bytes</td>
</tr>
<tr>
<td>Function</td>
<td>4</td>
<td>1</td>
<td>PCI Function Number</td>
</tr>
<tr>
<td>Device</td>
<td>5</td>
<td>1</td>
<td>PCI Device Number</td>
</tr>
</tbody>
</table>

10.3.2.2 PCCARD Device Path

Pccard Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 1 - Hardware Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 2 - PCCARD</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 5 bytes.</td>
</tr>
<tr>
<td>Function Number</td>
<td>4</td>
<td>1</td>
<td>Function Number (0 = First Function)</td>
</tr>
</tbody>
</table>
10.3.2.3 Memory Mapped Device Path

Table 10.5: Memory Mapped Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 1 - Hardware Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 3 - Memory Mapped.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 24 bytes.</td>
</tr>
</tbody>
</table>
| Memory Type    | 4           | 4           | EFI_MEMORY_TYPE. Type EFI_MEMORY_TYPE is defined in the function description.
| Start Address  | 8           | 8           | Starting Memory Address.                                                   |
| End Address    | 16          | 8           | Ending Memory Address.                                                     |

10.3.2.4 Vendor Device Path

The Vendor Device Path allows the creation of vendor-defined Device Paths. A vendor must allocate a Vendor GUID for a Device Path. The Vendor GUID can then be used to define the contents on the n bytes that follow in the Vendor Device Path node.

Table 10.6: Vendor-Defined Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 1 - Hardware Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 4 - Vendor.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 20 + n bytes.</td>
</tr>
<tr>
<td>Vendor_GUID</td>
<td>4</td>
<td>16</td>
<td>Vendor-assigned GUID that defines the data that follows.</td>
</tr>
<tr>
<td>Vendor Defined Data</td>
<td>20</td>
<td>n</td>
<td>Vendor-defined variable size data.</td>
</tr>
</tbody>
</table>

10.3.2.5 Controller Device Path

Table 10.7: Controller Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 1 - Hardware Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 5 - Controller.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 8 bytes.</td>
</tr>
<tr>
<td>Controller Number</td>
<td>4</td>
<td>4</td>
<td>Controller number.</td>
</tr>
</tbody>
</table>
10.3.2.6 BMC Device Path

The Device Path for a Baseboard Management Controller (BMC) host interface.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 1 - Hardware Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub Type 6 - BMC</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 13 bytes.</td>
</tr>
<tr>
<td>Interface Type</td>
<td>4</td>
<td>1</td>
<td>The Baseboard Management Controller (BMC) host interface type:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0x00: Unknown 0x01: KCS: Keyboard Controller Style 0x02: SMIC: Server Management Interface Chip 0x03: BT: Block Transfer</td>
</tr>
<tr>
<td>Base Address</td>
<td>5</td>
<td>8</td>
<td>Base address (either memory-mapped or I/O) of the BMC. If the least-significant bit of the field is a 1, the address is in I/O space; otherwise, the address is memory-mapped. Refer to the IPMI Interface Specification for usage details.</td>
</tr>
</tbody>
</table>

10.3.3 ACPI Device Path

This Device Path contains ACPI Device IDs that represent a device’s Plug and Play Hardware ID and its corresponding unique persistent ID. The ACPI IDs are stored in the ACPI _HID, _CID, and _UID device identification objects that are associated with a device. The ACPI Device Path contains values that must match exactly the ACPI name space that is provided by the platform firmware to the operating system. Refer to the ACPI specification for a complete description of the _HID, _CID, and _UID device identification objects.

The _HID and _CID values are optional device identification objects that appear in the ACPI name space. If only _HID is present, the _HID must be used to describe any device that will be enumerated by the ACPI driver. The _CID, if present, contains information that is important for the OS to attach generic driver (e.g., PCI Bus Driver), while the _HID contains information important for the OS to attach device-specific driver. The ACPI bus driver only enumerates a device when no standard bus enumerator exists for a device.

The _UID object provides the OS with a serial number-style ID for a device that does not change across reboots. The object is optional, but is required when a system contains two devices that report the same _HID. The _UID only needs to be unique among all device objects with the same _HID value. If no _UID exists in the ACPI name space for a _HID the value of zero must be stored in the _UID field of the ACPI Device Path.

The ACPI Device Path is only used to describe devices that are not defined by a Hardware Device Path. An _HID (along with _CID if present) is required to represent a PCI root bridge, since the PCI specification does not define the programming model for a PCI root bridge. There are two subtypes of the ACPI Device Path: a simple subtype that only includes the _HID and _UID fields, and an extended subtype that includes the _HID, _CID, and _UID fields.

The ACPI Device Path node only supports numeric 32-bit values for the _HID and _UID values. The Expanded ACPI Device Path node supports both numeric and string values for the _HID, _UID, and _CID values. As a result, the ACPI Device Path node is smaller and should be used if possible to reduce the size of device paths that may potentially be stored in nonvolatile storage. If a string value is required for the _HID field, or a string value is required for the _UID field, or a _CID field is required, then the Expanded ACPI Device Path node must be used. If a string field of the Expanded ACPI Device Path node is present, then the corresponding numeric field is ignored.

The _HID and _CID fields in the ACPI Device Path node and Expanded ACPI Device Path node are stored as a 32-bit compressed EISA-type IDs. The following macro can be used to compute these EISA-type IDs from a Plug and Play...
Hardware ID. The Plug and Play Hardware IDs used to compute the _HID and _CID fields in the EFI device path nodes must match the Plug and Play Hardware IDs used to build the matching entries in the ACPI tables. The compressed EISA-type IDs produced by this macro differ from the compressed EISA-type IDs stored in ACPI tables. As a result, the compressed EISA-type IDs from the ACPI Device Path nodes cannot be directly compared to the compressed EISA-type IDs from the ACPI table.

```
#define EFI_PNP_ID(ID) (UINT32)(((ID) << 16) | 0x41D0)
#define EISA_PNP_ID(ID) EFI_PNP_ID(ID)
```

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 2 - ACPI Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 1 ACPI Device Path.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 12 bytes.</td>
</tr>
<tr>
<td>_HID</td>
<td>4</td>
<td>4</td>
<td>Device’s PnP hardware ID stored in a numeric 32-bit compressed EISA-type ID. This value must match the corresponding _HID in the ACPI name space.</td>
</tr>
<tr>
<td>_UID</td>
<td>8</td>
<td>4</td>
<td>Unique ID that is required by ACPI if two devices have the same _HID. This value must also match the corresponding _UID/_HID pair in the ACPI name space. Only the 32-bit numeric value type of _UID is supported; thus strings must not be used for the _UID in the ACPI name space.</td>
</tr>
</tbody>
</table>

Table 10.9: ACPI Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 2 - ACPI Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 2 Expanded ACPI Device Path.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Minimum length is 19 bytes. The actual size will depend on the size of the _HIDSTR, _UIDSTR, and _CIDSTR fields.</td>
</tr>
<tr>
<td>_HID</td>
<td>4</td>
<td>4</td>
<td>Device’s PnP hardware ID stored in a numeric 32-bit compressed EISA-type ID. This value must match the corresponding _HID in the ACPI name space.</td>
</tr>
<tr>
<td>_UID</td>
<td>8</td>
<td>4</td>
<td>Unique ID that is required by ACPI if two devices have the same _HID. This value must also match the corresponding _UID/_HID pair in the ACPI name space.</td>
</tr>
<tr>
<td>_CID</td>
<td>12</td>
<td>4</td>
<td>Device’s compatible PnP hardware ID stored in a numeric 32-bit compressed EISA-type ID. This value must match at least one of the compatible device IDs returned by the corresponding _CID in the ACPI name space.</td>
</tr>
<tr>
<td>_HIDSTR</td>
<td>16</td>
<td>&gt;=1</td>
<td>Device’s PnP hardware ID stored as a null-terminated ASCII string. This value must match the corresponding _HID in the ACPI name space. If the length of this string not including the null-terminator is 0, then the _HID field is used. If the length of this null-terminated string is greater than 0, then this field supersedes the _HID field.</td>
</tr>
</tbody>
</table>

Table 10.10: Expanded ACPI Device Path

continues on next page
Table 10.10 – continued from previous page

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>_UIDSTR</td>
<td>Varies</td>
<td>&gt;=1</td>
<td>Unique ID that is required by ACPI if two devices have the same _HID. This value must also match the corresponding _UID/_HID pair in the ACPI name space. This value is stored as a null-terminated ASCII string. If the length of this string not including the null-terminator is 0, then the _UID field is used. If the length of this null-terminated string is greater than 0, then this field supersedes the _UID field. The Byte Offset of this field can be computed by adding 16 to the size of the _HIDSTR field.</td>
</tr>
<tr>
<td>_CIDSTR</td>
<td>Varies</td>
<td>&gt;=1</td>
<td>Device’s compatible PnP hardware ID stored as a null-terminated ASCII string. This value must match at least one of the compatible device IDs returned by the corresponding _CID in the ACPI name space. If the length of this string not including the null-terminator is 0, then the _CID field is used. If the length of this null-terminated string is greater than 0, then this field supersedes the _CID field. The Byte Offset of this field can be computed by adding 16 to the sum of the sizes of the _HIDSTR and _UIDSTR fields.</td>
</tr>
</tbody>
</table>

10.3.3.1 ACPI _ADR Device Path

The _ADR device path is used to contain video output device attributes to support the Graphics Output Protocol. The device path can contain multiple _ADR entries if multiple video output devices are displaying the same output.

Table 10.11: ACPI _ADR Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 2 - ACPI Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type3 _ADR Device Path</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Minimum length is 8.</td>
</tr>
<tr>
<td>_ADR</td>
<td>4</td>
<td>4</td>
<td>_ADR value. For video output devices the value of this field comes from Table B-2 ACPI 3.0 specification. At least one _ADR value is required</td>
</tr>
<tr>
<td>Additional _ADR</td>
<td>8</td>
<td>N</td>
<td>This device path may optionally contain more than one _ADR entry.</td>
</tr>
</tbody>
</table>

10.3.3.2 NVDIMM Device Path

This device path describes an NVDIMM device using the ACPI 6.0 specification defined NFIT Device Handle as the identifier.

Table 10.12: NVDIMM Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 2 - ACPI Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-type 4 - NVDIMM Device</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>8 - Single NFIT Device Handle is supported.</td>
</tr>
<tr>
<td>NFIT Device Handle</td>
<td>4</td>
<td>4</td>
<td>NFIT Device Handle - Unique physical identifier. See ACPI Defined Devices and Device Specific Objects section, NVDIMM Devices sub-chapter for the specific definition of the fields utilized for this handle.</td>
</tr>
</tbody>
</table>

10.3. Device Path Nodes
10.3.4 Messaging Device Path

This Device Path is used to describe the connection of devices outside the resource domain of the system. This Device Path can describe physical messaging information like SCSI ID, or abstract information like networking protocol IP addresses.

10.3.4.1 ATAPI Device Path

Table 10.13: ATAPI Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 1 - ATAPI</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 8 bytes.</td>
</tr>
<tr>
<td>PrimarySecondary</td>
<td>4</td>
<td>1</td>
<td>Set to zero for primary or one for secondary</td>
</tr>
<tr>
<td>SlaveMaster</td>
<td>5</td>
<td>1</td>
<td>Set to zero for master or one for slave mode</td>
</tr>
<tr>
<td>Logical Unit Number</td>
<td>6</td>
<td>2</td>
<td>Logical Unit Number</td>
</tr>
</tbody>
</table>

10.3.4.2 SCSI Device Path

Table 10.14: SCSI Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 2 - SCSI</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 8 bytes.</td>
</tr>
<tr>
<td>Target ID</td>
<td>4</td>
<td>2</td>
<td>Target ID on the SCSI bus (PUN)</td>
</tr>
<tr>
<td>Logical Unit Number</td>
<td>6</td>
<td>2</td>
<td>Logical Unit Number (LUN)</td>
</tr>
</tbody>
</table>

10.3.4.3 Fibre Channel Device Path

Table 10.15: Fibre Channel Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 3 - Fibre Channel</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 24 bytes.</td>
</tr>
<tr>
<td>Reserved</td>
<td>4</td>
<td>4</td>
<td>Reserved</td>
</tr>
<tr>
<td>World Wide Name</td>
<td>8</td>
<td>8</td>
<td>Fibre Channel World Wide Name</td>
</tr>
<tr>
<td>Logical Unit Number</td>
<td>16</td>
<td>8</td>
<td>Fibre Channel Logical Unit Number</td>
</tr>
</tbody>
</table>
Table 10.16: Fibre Channel Ex Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 21 - Fibre Channel Ex</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 24 bytes.</td>
</tr>
<tr>
<td>Reserved</td>
<td>4</td>
<td>4</td>
<td>Reserved</td>
</tr>
<tr>
<td>World Wide Name</td>
<td>8</td>
<td>8</td>
<td>8 byte array containing Fibre Channel End Device Port Name (a.k.a., World Wide Name)</td>
</tr>
<tr>
<td>Logical Unit Number</td>
<td>16</td>
<td>8</td>
<td>8 byte array containing Fibre Channel Logical Unit Number</td>
</tr>
</tbody>
</table>

The Fibre Channel Ex device path clarifies the definition of the Logical Unit Number field to conform with the T-10 SCSI Architecture Model 4 specification. The 8 byte Logical Unit Number field in the device path must conform with a logical unit number returned by a SCSI REPORT LUNS command.

When the Fibre Channel Ex Device Path is used with the Extended SCSI Pass Thru Protocol the UINT64 LUN argument must be converted to the eight byte array Logical Unit Number field in the device path by treating the eight byte array as an EFI UINT64. For example a Logical Unit Number array of \( \{0, 1, 2, 3, 4, 5, 6, 7\} \) becomes a UINT64 of \(0x0706050403020100\).

When an application client displays or otherwise makes a 64-bit LUN visible to a user, it should be done in conformance with SAM-4. SAM-4 requires a LUN to be displayed in hexadecimal format with byte 0 first (i.e., on the left) and byte 7 last (i.e., on the right) regardless of the internal representation of the LUN. UEFI defines all data structures a “little endian” and SCSI defines all data structures as “big endian”. Fibre Channel Ex Device Path Example shows an example device path for a Fibre Channel controller on a typical UEFI platform. This Fibre Channel Controller is connected to the port 0 of the root hub, and its interface number is 0. The Fibre Channel Host Controller is a PCI device whose PCI device number 0x1F and PCI function 0x00. So, the whole device path for this Fibre Channel Controller consists an ACPI Device Path Node, a PCI Device Path Node, a Fibre Channel Device Path Node and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The Fibre Channel WWN and LUN were picked to show byte order and they are not typical real world values. The shorthand notation for this device path is:

\[ \text{PciRoot}(0)/\text{PCI}(31,0)/\text{FibreEx}(0x0001020304050607, 0x0001020304050607) \]

Table 10.17: Fibre Channel Ex Device Path Example

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>1</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>2</td>
<td>2</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>8</td>
<td>4</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>12</td>
<td>1</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>13</td>
<td>1</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>14</td>
<td>2</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>16</td>
<td>1</td>
<td>0x0</td>
<td>PCI Function</td>
</tr>
<tr>
<td>17</td>
<td>1</td>
<td>0x1F</td>
<td>PCI Device</td>
</tr>
<tr>
<td>18</td>
<td>1</td>
<td>0x03</td>
<td>Generic Device Path Header - Type Message Device Path</td>
</tr>
<tr>
<td>19</td>
<td>1</td>
<td>0x15</td>
<td>Sub type - Fibre Channel Ex</td>
</tr>
<tr>
<td>20</td>
<td>2</td>
<td>0x14</td>
<td>Length - 20 bytes</td>
</tr>
<tr>
<td>21</td>
<td>1</td>
<td>0x00</td>
<td>8 byte array containing Fibre Channel End Device Port Name (a.k.a., World Wide Name)</td>
</tr>
<tr>
<td>22</td>
<td>1</td>
<td>0x01</td>
<td></td>
</tr>
<tr>
<td>23</td>
<td>1</td>
<td>0x02</td>
<td></td>
</tr>
<tr>
<td>24</td>
<td>1</td>
<td>0x03</td>
<td></td>
</tr>
<tr>
<td>25</td>
<td>1</td>
<td>0x04</td>
<td></td>
</tr>
<tr>
<td>26</td>
<td>1</td>
<td>0x05</td>
<td></td>
</tr>
<tr>
<td>27</td>
<td>1</td>
<td>0x06</td>
<td></td>
</tr>
<tr>
<td>28</td>
<td>1</td>
<td>0x07</td>
<td></td>
</tr>
<tr>
<td>29</td>
<td>1</td>
<td>0x00</td>
<td>8 byte array containing Fibre Channel Logical Unit Number</td>
</tr>
<tr>
<td>30</td>
<td>1</td>
<td>0x01</td>
<td></td>
</tr>
<tr>
<td>31</td>
<td>1</td>
<td>0x02</td>
<td></td>
</tr>
<tr>
<td>32</td>
<td>1</td>
<td>0x03</td>
<td></td>
</tr>
<tr>
<td>33</td>
<td>1</td>
<td>0x04</td>
<td></td>
</tr>
<tr>
<td>34</td>
<td>1</td>
<td>0x05</td>
<td></td>
</tr>
<tr>
<td>35</td>
<td>1</td>
<td>0x06</td>
<td></td>
</tr>
<tr>
<td>36</td>
<td>1</td>
<td>0x07</td>
<td></td>
</tr>
<tr>
<td>37</td>
<td>1</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>38</td>
<td>1</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>39</td>
<td>2</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

### 10.3.4.4 1394 Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 4 - 1394</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 16 bytes.</td>
</tr>
<tr>
<td>Reserved</td>
<td>4</td>
<td>4</td>
<td>Reserved</td>
</tr>
<tr>
<td>GUID ¹</td>
<td>8</td>
<td>8</td>
<td>1394 Global Unique ID (GUID) ¹</td>
</tr>
</tbody>
</table>

**Note:** ¹ The usage of the term GUID is per the 1394 specification. This is not the same as the EFI_GUID type defined in the EFI Specification.

### 10.3.4.5 USB Device Paths

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 5 - USB</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 6 bytes.</td>
</tr>
<tr>
<td>USB Parent Port Number</td>
<td>4</td>
<td>1</td>
<td>USB Parent Port Number</td>
</tr>
<tr>
<td>Interface</td>
<td>5</td>
<td>1</td>
<td>USB Interface Number</td>
</tr>
</tbody>
</table>
10.3.4.5.1 USB Device Path Example

**USB Device Path Example** shows an example device path for a USB controller on a desktop platform. This USB Controller is connected to the port 0 of the root hub, and its interface number is 0. The USB Host Controller is a PCI device whose PCI device number 0x1F and PCI function 0x02. So, the whole device path for this USB Controller consists an ACPI Device Path Node, a PCI Device Path Node, a USB Device Path Node and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

PciRoot(0)/PCI(31,2)/USB(0,0).

### Table 10.20: USB Device Path Examples

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string 'PNP' and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x02</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x1F</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x03</td>
<td>Generic Device Path Header - Type Message Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x05</td>
<td>Sub type - USB</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x01</td>
<td>0x00</td>
<td>Parent Hub Port Number</td>
</tr>
<tr>
<td>0x17</td>
<td>0x01</td>
<td>0x00</td>
<td>Controller Interface Number</td>
</tr>
<tr>
<td>0x18</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x19</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

Another example is a USB Controller (interface number 0) that is connected to port 3 of a USB Hub Controller (interface number 0), and this USB Hub Controller is connected to the port 1 of the root hub. The shorthand notation for this device path is:

PciRoot(0)/PCI(31,2)/USB(1,0)/USB(3,0).

See table (below) showing the device path for this USB Controller.

### Table 10.21: Another USB Device Path Example

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
</tbody>
</table>

Continues on next page
Table 10.21 – continued from previous page

<table>
<thead>
<tr>
<th>Offset</th>
<th>Type</th>
<th>Sub-Type</th>
<th>Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0</td>
<td>0xAA03</td>
<td>HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
<td></td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>_Generic Device Path Header - Type Hardware Device Path</td>
<td></td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
<td></td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
<td></td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x02</td>
<td>PCI Function</td>
<td></td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x1F</td>
<td>PCI Device</td>
<td></td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x03</td>
<td>_Generic Device Path Header - Type Message Device Path</td>
<td></td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x05</td>
<td>Sub type - USB</td>
<td></td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
<td></td>
</tr>
<tr>
<td>0x16</td>
<td>0x01</td>
<td>0x01</td>
<td>Parent Hub Port Number</td>
<td></td>
</tr>
<tr>
<td>0x17</td>
<td>0x01</td>
<td>0x00</td>
<td>Controller Interface Number</td>
<td></td>
</tr>
<tr>
<td>0x18</td>
<td>0x01</td>
<td>0x03</td>
<td>_Generic Device Path Header - Type Message Device Path</td>
<td></td>
</tr>
<tr>
<td>0x19</td>
<td>0x01</td>
<td>0x05</td>
<td>Sub type - USB</td>
<td></td>
</tr>
<tr>
<td>0x1A</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
<td></td>
</tr>
<tr>
<td>0x1C</td>
<td>0x01</td>
<td>0x03</td>
<td>Parent Hub Port Number</td>
<td></td>
</tr>
<tr>
<td>0x1D</td>
<td>0x01</td>
<td>0x00</td>
<td>Controller Interface Number</td>
<td></td>
</tr>
<tr>
<td>0x1E</td>
<td>0x01</td>
<td>0x7F</td>
<td>_Generic Device Path Header - Type End of Hardware Device Path</td>
<td></td>
</tr>
<tr>
<td>0x1F</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
<td></td>
</tr>
<tr>
<td>0x20</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
<td></td>
</tr>
</tbody>
</table>

10.3.4.6 SATA Device Path

Table 10.22: SATA Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 18 - SATA</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 10 bytes.</td>
</tr>
<tr>
<td>HBA Port Number</td>
<td>4</td>
<td>2</td>
<td>The HBA port number that facilitates the connection to the device or a port multiplier. The value 0xFFFF is reserved.</td>
</tr>
<tr>
<td>Port Multiplier Port Number</td>
<td>6</td>
<td>2</td>
<td>The Port multiplier port number that facilitates the connection to the device. Must be set to 0xFFFF if the device is directly connected to the HBA.</td>
</tr>
<tr>
<td>Logical Unit Number</td>
<td>8</td>
<td>2</td>
<td>Logical Unit Number.</td>
</tr>
</tbody>
</table>

10.3.4.7 USB Device Paths (WWID)

This device path describes a USB device using its serial number.

Specifications, such as the USB Mass Storage class, bulk-only transport subclass, require that some portion of the suffix of the device’s serial number be unique with respect to the vendor and product id for the device. So, in order to avoid confusion and overlap of WWID’s, the interface’s class, subclass, and protocol are included.

10.3. Device Path Nodes
Table 10.23: USB WWID Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 16 - USB WWID</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 10+</td>
</tr>
<tr>
<td>• Interface Number</td>
<td>4</td>
<td>2</td>
<td>USB interface number</td>
</tr>
<tr>
<td>• Device Vendor Id</td>
<td>6</td>
<td>2</td>
<td>USB vendor id of the device</td>
</tr>
<tr>
<td>• Device Product Id</td>
<td>8</td>
<td>2</td>
<td>USB product id of the device</td>
</tr>
<tr>
<td>• Serial Number</td>
<td>10</td>
<td>n</td>
<td>Last 64-or-fewer UTF-16 characters of the USB serial number. The length of the string is determined by the Length field less the offset of the Serial Number field (10)</td>
</tr>
</tbody>
</table>

Devices that do not have a serial number string must use the USB Device Path (type 5) as described in USB Device Path Example.

Including the interface as part of this node allows distinction for multi-interface devices, e.g., an HID interface and a Mass Storage interface on the same device, or two Mass Storage interfaces.

Load Option Processing defines special rules for processing the USB WWID Device Path. These special rules enable a device location to change and still have the system boot from the device.

10.3.4.8 Device Logical Unit

For some classes of devices, such as USB Mass Storage, it is necessary to specify the Logical Unit Number (LUN), since a single device may have multiple logical units. In order to boot from one of these logical units of the device, the Device Logical Unit device node is appended to the device path. The EFI path node subtype is defined, as in the Table below.

Table 10.24: Device Logical Unit

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 17 - Device Logical unit</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 5</td>
</tr>
<tr>
<td>LUN</td>
<td>4</td>
<td>1</td>
<td>Logical Unit Number for the interface</td>
</tr>
</tbody>
</table>

Load Option Processing defines special rules for processing the USB Class Device Path. These special rules enable a device location to change and still have the system recognize the device.

Globally Defined Variables defines how the ConIn, ConOut, and ErrOut variables are processed and contains special rules for processing the USB Class device path. These special rules allow all USB keyboards to be specified as valid input devices.
Table 10.25: USB Class Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 15 - USB Class.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 11 bytes.</td>
</tr>
<tr>
<td>Vendor ID</td>
<td>4</td>
<td>2</td>
<td>Vendor ID assigned by USB-IF. A value of 0xFFFF will match any Vendor ID.</td>
</tr>
<tr>
<td>Product ID</td>
<td>6</td>
<td>2</td>
<td>Product ID assigned by USB-IF. A value of 0xFFFF will match any Product ID.</td>
</tr>
<tr>
<td>Device Class</td>
<td>8</td>
<td>1</td>
<td>The class code assigned by the USB-IF. A value of 0xFF will match any class code.</td>
</tr>
<tr>
<td>Device Subclass</td>
<td>9</td>
<td>1</td>
<td>The subclass code assigned by the USB-IF. A value of 0xFF will match any subclass code.</td>
</tr>
<tr>
<td>Device Protocol</td>
<td>10</td>
<td>1</td>
<td>The protocol code assigned by the USB-IF. A value of 0xFF will match any protocol code.</td>
</tr>
</tbody>
</table>

10.3.4.9 I2O Device Path

Table 10.26: I2O Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 6 - I2O Random Block Storage Class</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 8 bytes.</td>
</tr>
<tr>
<td>TID</td>
<td>4</td>
<td>4</td>
<td>Target ID (TID) for a device</td>
</tr>
</tbody>
</table>

10.3.4.10 MAC Address Device Path

Table 10.27: MAC Address Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 11 - MAC Address for a network interface</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 37 bytes.</td>
</tr>
<tr>
<td>MAC Address</td>
<td>4</td>
<td>32</td>
<td>The MAC address for a network interface padded with 0s</td>
</tr>
<tr>
<td>IfType</td>
<td>36</td>
<td>1</td>
<td>Network interface type (i.e., 802.3, FDDI). See RFC 3232</td>
</tr>
</tbody>
</table>

10.3.4.11 IPv4 Device Path

Previous versions of the specification only defined a 19 byte IPv4 device path. To access fields at offset 19 or greater, the size of the device path must be checked first.

Table 10.28: IPv4 Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
</tbody>
</table>

continues on next page
Table 10.28 – continued from previous page

<table>
<thead>
<tr>
<th>Sub-Type</th>
<th>1</th>
<th>1</th>
<th>Sub-Type 12 - IPv4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 27 bytes.</td>
</tr>
<tr>
<td>Local IP Address</td>
<td>4</td>
<td>4</td>
<td>The local IPv4 address</td>
</tr>
<tr>
<td>Remote IP Address</td>
<td>8</td>
<td>4</td>
<td>The remote IPv4 address</td>
</tr>
<tr>
<td>Local Port</td>
<td>12</td>
<td>2</td>
<td>The local port number</td>
</tr>
<tr>
<td>Remote Port</td>
<td>14</td>
<td>2</td>
<td>The remote port number</td>
</tr>
<tr>
<td>Protocol</td>
<td>16</td>
<td>2</td>
<td>The network protocol (i.e., UDP, TCP). See RFC 3232</td>
</tr>
<tr>
<td>StaticIPAddress</td>
<td>18</td>
<td>1</td>
<td>0x00 - The Source IP Address was assigned though DHCP 0x01 - The Source IP Address is statically bound</td>
</tr>
<tr>
<td>GatewayIPAddress</td>
<td>19</td>
<td>4</td>
<td>The Gateway IP Address</td>
</tr>
<tr>
<td>Subnet Mask</td>
<td>23</td>
<td>4</td>
<td>Subnet mask</td>
</tr>
</tbody>
</table>

10.3.4.12 IPv6 Device Path

Table 10.29: IPv6 Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 13 - IPv6</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 60 bytes.</td>
</tr>
<tr>
<td>Local IP Address</td>
<td>4</td>
<td>16</td>
<td>The local IPv6 address</td>
</tr>
<tr>
<td>Remote IP Address</td>
<td>20</td>
<td>16</td>
<td>The remote IPv6 address</td>
</tr>
<tr>
<td>Local Port</td>
<td>36</td>
<td>2</td>
<td>The local port number</td>
</tr>
<tr>
<td>Remote Port</td>
<td>38</td>
<td>2</td>
<td>The remote port number</td>
</tr>
<tr>
<td>Protocol</td>
<td>40</td>
<td>2</td>
<td>The network protocol (i.e., UDP, TCP). See RFC 3232</td>
</tr>
<tr>
<td>IPAddressOrigin</td>
<td>42</td>
<td>1</td>
<td>0x00 - The Local IP Address was manually configured. 0x01 - The Local IP Address is assigned through IPv6 stateless auto -configuration. 0x02 - The Local IP Address is assigned through IPv6 stateful configuration.</td>
</tr>
<tr>
<td>PrefixLength</td>
<td>43</td>
<td>1</td>
<td>The Prefix Length</td>
</tr>
<tr>
<td>GatewayIPAddress</td>
<td>44</td>
<td>16</td>
<td>The Gateway IP Address</td>
</tr>
</tbody>
</table>

10.3.4.13 2. VLAN device path node

Table 10.30: VLAN device path node

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 20 - Vlan (802.1q)</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this device node</td>
</tr>
<tr>
<td>Vlanid</td>
<td>4</td>
<td>2</td>
<td>VLAN identifier (0-4094)</td>
</tr>
</tbody>
</table>
10.3.4.14 InfiniBand Device Path

Table 10.31: InfiniBand Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 9 - InfiniBand</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 48 bytes.</td>
</tr>
<tr>
<td>Resource Flags</td>
<td>4</td>
<td>4</td>
<td>Flags to help identify/manage InfiniBand device path elements:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 0: IOC/Service (0b = IOC, 1b = Service)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 1: Extend Boot Environment</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 2: Console Protocol</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 3: Storage Protocol</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 4: Network Protocol</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>All other bits are reserved.</td>
</tr>
<tr>
<td>PORT GID</td>
<td>8</td>
<td>16</td>
<td>128-bit Global Identifier for remote fabric port</td>
</tr>
<tr>
<td>IOC GUID/Service ID</td>
<td>24</td>
<td>8</td>
<td>64-bit unique identifier to remote IOC or server process. Interpretation of field specified by Resource Flags (bit 0)</td>
</tr>
<tr>
<td>Target Port ID</td>
<td>32</td>
<td>8</td>
<td>64-bit persistent ID of remote IOC port</td>
</tr>
<tr>
<td>Device ID</td>
<td>40</td>
<td>8</td>
<td>64-bit persistent ID of remote device</td>
</tr>
</tbody>
</table>

Note: The usage of the terms GUID and GID is per the InfiniBand Specification. The term GUID is not the same as the EFI_GUID type defined in this EFI Specification.

10.3.4.15 UART Device Path

Table 10.32: UART Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 – Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 14 – UART</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 19 bytes.</td>
</tr>
<tr>
<td>Reserved</td>
<td>4</td>
<td>4</td>
<td>Reserved</td>
</tr>
<tr>
<td>Baud Rate</td>
<td>8</td>
<td>8</td>
<td>The baud rate setting for the UART style device. A value of 0 means that the device’s default baud rate will be used.</td>
</tr>
<tr>
<td>Data Bits</td>
<td>16</td>
<td>1</td>
<td>The number of data bits for the UART style device. A value of 0 means that the device’s default number of data bits will be used.</td>
</tr>
</tbody>
</table>

continues on next page
### Parity

<table>
<thead>
<tr>
<th>Parity</th>
<th>17</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>The parity setting for the UART style device.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Parity 0x00 - Default Parity</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Parity 0x01 - No Parity</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Parity 0x02 - Even Parity</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Parity 0x03 - Odd Parity</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Parity 0x04 - Mark Parity</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Parity 0x05 - Space Parity</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Stop Bits

<table>
<thead>
<tr>
<th>Stop Bits</th>
<th>18</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>The number of stop bits for the UART style device.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Stop Bits 0x00 - Default Stop Bits</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Stop Bits 0x01 - 1 Stop Bit</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Stop Bits 0x02 - 1.5 Stop Bits</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Stop Bits 0x03 - 2 Stop Bits</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### 10.3.4.16 Vendor-Defined Messaging Device Path

#### Table 10.33: Vendor-Defined Messaging Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 10 - Vendor</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 20 + n bytes.</td>
</tr>
<tr>
<td>Vendor GUID</td>
<td>4</td>
<td>16</td>
<td>Vendor-assigned GUID that defines the data that follows</td>
</tr>
<tr>
<td>Vendor Defined Data</td>
<td>20</td>
<td>n</td>
<td>Vendor-defined variable size data</td>
</tr>
</tbody>
</table>

The following GUIDs are used with a Vendor-Defined Messaging Device Path to describe the transport protocol for use with PC-ANSI, VT-100, VT-100+, and VT-UTF8 terminals. Device paths can be constructed with this node as the last node in the device path. The rest of the device path describes the physical device that is being used to transmit and receive data. The PC-ANSI, VT-100, VT-100+, and VT-UTF8 GUIDs define the format of the data that is being sent though the physical device. Additional GUIDs can be generated to describe additional transport protocols.

```c
#define EFI_PC_ANSI_GUID
{0xe0c14753,0xf9be,0x11d2,{0x9a,0x0c,0x00,0x90,0x27,0x3f,0xc1,0x4d}}

#define EFI_VT_100_GUID
{0xdfa66065,0xb419,0x11d3,{0x9a,0x2d,0x00,0x90,0x27,0x3f,0xc1,0x4d}}

#define EFI_VT_100_PLUS_GUID
{0x7baec70b,0x57e0,0x4c76,{0x8e,0x87,0x2f,0x9e,0x28,0x08,0x83,0x43}}

#define EFI_VT_UTF8_GUID
{0xad15a0d6,0x8bec,0x4acf,{0xa0,0x73,0xd0,0x1d,0xe7,0x7e,0x2d,0x88}}
```
10.3.4.17 UART Flow Control Messaging Path

The UART messaging device path defined in the EFI 1.02 specification does not contain a provision for flow control. Therefore, a new device path node is needed to declare flow control characteristics. It is a vendor-defined messaging node which may be appended to the UART node in a device path. It has the following definition:

```c
#define DEVICE_PATH_MESSAGING_UART_FLOW_CONTROL {
    0x37499a9d, 0x542f, 0x4c89, {0xa0, 0x26, 0x35, 0xda, 0x14, 0x20, 0x94, 0xe4}
```

Table 10.34: UART Flow Control Messaging Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 10 - Vendor</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 24 bytes.</td>
</tr>
<tr>
<td>Vendor GUID</td>
<td>4</td>
<td>16</td>
<td>DEVICE_PATH_MESSAGING_UART_FLOW_CONTROL</td>
</tr>
<tr>
<td>Flow_Control_Map</td>
<td>20</td>
<td>4</td>
<td>Bitmap of supported flow control types.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 0 set indicates hardware flow control.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 1 set indicates Xon/Xoff flow control.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• All other bits are reserved and are clear.</td>
</tr>
</tbody>
</table>

A debugport driver that implements Xon/Xoff flow control would produce a device path similar to the following:

```
PciRoot(0)/Pci(0x1f,0)/ACPI(PNP0501,0)/UART(115200,N,8,1)/UartFlowCtrl(2)/DebugPort()
```

Note: If no bits are set in the Flow_Control_Map, this indicates there is no flow control and is equivalent to leaving the flow control node out of the device path completely.

10.3.4.18 Serial Attached SCSI (SAS) Device Path

This section defines the device node for Serial Attached SCSI (SAS) devices.

Table 10.35: SAS Messaging Device Path Structure

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type -3 Messaging</td>
</tr>
<tr>
<td>Sub Type</td>
<td>1</td>
<td>1</td>
<td>10 (Vendor)</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this Structure</td>
</tr>
<tr>
<td>Vendor GUID</td>
<td>4</td>
<td>16</td>
<td>d487dd b4-008b-11d9-af dc-001083fca4d</td>
</tr>
<tr>
<td>Reserved</td>
<td>20</td>
<td>4</td>
<td>Reserved for future use</td>
</tr>
<tr>
<td>SAS Address</td>
<td>24</td>
<td>8</td>
<td>SAS Address for Serial Attached SCSI Target.</td>
</tr>
<tr>
<td>Logical Unit Number</td>
<td>32</td>
<td>8</td>
<td>SAS Logical Unit Number</td>
</tr>
<tr>
<td>SAS/SATA device and Topology Info</td>
<td>40</td>
<td>2</td>
<td>More Information about the device and its interconnect</td>
</tr>
<tr>
<td>Relative Target Port</td>
<td>42</td>
<td>2</td>
<td>Relative Target Port (RTP)</td>
</tr>
</tbody>
</table>

Summary
The device node represented by the structure in the table above shall be appended after the Hardware Device Path node in the device path.

There are two cases for boot devices connected with SAS HBA’s. Each of the cases is described below with an example of the expected Device Path for these.

- **SAS Device anywhere in an SAS domain accessed through SSP Protocol.**

  \[
  \text{PciRoot(0)/PCI(1,0)/Sas(0x31000004CF13F6BD, 0)}
  \]

  The first 64-bit number represents the SAS address of the target SAS device.

  The second number is the boot LUN of the target SAS device.

  The third number is the Relative Target Port (RTP)

- **SATA Device connected directly to a HBA port.**

  \[
  \text{PciRoot(0)/PCI(1,0)/Sas(0x31000004CF13F6BD)}
  \]

  The first number represents either a real SAS address reserved by the HBA for above connections, or a fake but unique SAS address generated by the HBA to represent the SATA device.

### 10.3.4.18.1 Device and Topology Information

First Byte (At offset 40 into the structure):

Bits 0:3:
- Value 0x0 -> No Additional Information about device topology.
- Value 0x1 -> More Information about device topology valid in this byte.
- Value 0x2 -> More Information about device topology valid in this and next 1 byte.
- Values 0x3 thru 0xF -> Reserved.

Bits 4:5: Device Type (Valid only if the More Information field above is non-zero)
- Value 0x0 -> SAS Internal Device
- Value 0x1 -> SATA Internal Device
- Value 0x2 -> SAS External Device
- Value 0x3 -> SATA External Device

Bits 6:7: Topology / Interconnect (Valid only if the More Information field above is non-zero)
- Value 0x0 -> Direct Connect (Connected directly with the HBA Port/Phy)
- Value 0x1 -> Expander Connect (Connected thru/via one or more Expanders)
- Value 0x2 and 0x3 > Reserved
10.3.4.18.2 Device and Topology Information

Second Byte (At offset 41 into the structure). Valid only if bits 0-3 of More Information in Byte 40 have a value of 2:
Bits 0-7: Internal Drive/Bay Id (Only applicable if Internal Drive is indicated in Device Type)
Value 0x0 thru 0xFF -> Drive 1 thru Drive 256

10.3.4.18.3 Relative Target Port

At offset 42 into the structure:
This two-byte field shall contain the “Relative Target Port” of the target SAS port. Relative Target Port can be obtained by performing an INQUIRY command to VPD page 0x83 in the target. Implementation of RTP is mandatory for SAS targets as defined in Section 10.2.10 of sas1r07 specification (or later).

NOTE: If a LUN is seen thru multiple RTPs in a given target, then the UEFI driver shall create separate device path instances for both paths. RTP in the device path shall distinguish these two device path instantiations.

NOTE: Changing the values of the SAS/SATA device topology information or the RTP fields of the device path will make UEFI think this is a different device.

10.3.4.18.4 Examples Of Correct Device Path Display Format

Case 1: When Additional Information is not Valid or Not Present (Bits 0:3 of Byte 40 have a value of 0)

\[\text{PciRoot}(0)/\text{PCI}(1,0)/\text{SAS}(0x31000004CF13F6BD, 0)\]

Case 2: When Additional Information is Valid and present (Bits 0:3 of Byte 40 have a value of 1 or 2)

- If Bits 4-5 of Byte 40 (Device and Topology information) indicate an SAS device (Internal or External) i.e., has values 0x0 or 0x2, then the following format shall be used.

\[\text{PciRoot}(0)/\text{PCI}(1,0)/\text{SAS}(0x31000004CF13F6BD, 0, \text{SAS})\]

- If Bits 4-5 of Byte 40 (Device and Topology information) indicate a SATA device (Internal or External) i.e., has a value of 0x1 or 0x3, then the following format shall be used.

\[\text{ACPI(PnP)}/\text{PCI}(1,0)/\text{SAS}(0x31000004CF13F6BD, \text{SATA})\]

10.3.4.19 Serial Attached SCSI (SAS) Extended Device Path

This section defines the extended device node for Serial Attached SCSI (SAS) devices. In this device path the SAS Address and LUN are now defined as arrays to remove the need to endian swap the values.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type -3 Messaging</td>
</tr>
<tr>
<td>Sub Type</td>
<td>1</td>
<td>1</td>
<td>Sub-type 22 SAS Ex</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this Structure. 32 bytes</td>
</tr>
</tbody>
</table>

continues on next page
Table 10.36 – continued from previous page

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>SAS Address</td>
<td>4</td>
<td>8</td>
<td>8-byte array of the SAS Address for Serial Attached SCSI Target Port.</td>
</tr>
<tr>
<td>Logical Unit Number</td>
<td>20</td>
<td>8</td>
<td>8-byte array of the SAS Logical Unit Number.</td>
</tr>
<tr>
<td>SAS/SATA device and Topology Info</td>
<td>28</td>
<td>2</td>
<td>More Information about the device and its interconnect</td>
</tr>
<tr>
<td>Relative Target Port</td>
<td>30</td>
<td>2</td>
<td>Relative Target Port (RTP)</td>
</tr>
</tbody>
</table>

The SAS Ex device path clarifies the definition of the Logical Unit Number field to conform with the T-10 SCSI Architecture Model 4 specification. The 8 byte Logical Unit Number field in the device path must conform with a logical unit number returned by a SCSI REPORT LUNS command.

When the SAS Device Path Ex is used with the Extended SCSI Pass Thru Protocol, the UINT64 LUN must be converted to the eight byte array Logical Unit Number field in the device path by treating the eight byte array as an EFI UINT64. For example, a Logical Unit Number array of \{ 0,1,2,3,4,5,6,7 \} becomes a UINT64 of 0x0706050403020100.

When an application client displays or otherwise makes a 64-bit LUN (8 byte array) visible to a user, it should be done in conformance with SAM-4. SAM-4 requires a LUN to be displayed in hexadecimal format with byte 0 first (i.e., on the left) and byte 7 last (i.e., on the right) regardless of the internal representation of the LUN. UEFI defines all data structures a “little endian” and SCSI defines all data structures as “big endian”.

10.3.4.20 iSCSI Device Path

Table 10.37: iSCSI Device Path Node (Base Information)

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 19 - (iSCSI)</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is (18 + n) bytes</td>
</tr>
<tr>
<td>Protocol</td>
<td>4</td>
<td>2</td>
<td>Network Protocol (0 = TCP, 1+ = reserved)</td>
</tr>
<tr>
<td>Options</td>
<td>6</td>
<td>2</td>
<td>iSCSI Login Options</td>
</tr>
<tr>
<td>Logical Unit Number</td>
<td>8</td>
<td>8</td>
<td>8 byte array containing the iSCSI Logical Unit Number</td>
</tr>
<tr>
<td>Target Portal group tag</td>
<td>16</td>
<td>2</td>
<td>iSCSI Target Portal group tag the initiator intends to establish a session with.</td>
</tr>
<tr>
<td>iSCSI Target Name</td>
<td>18</td>
<td>n</td>
<td>iSCSI Node Target Name. The length of the name is determined by subtracting the offset of this field from Length.</td>
</tr>
</tbody>
</table>

10.3.4.20.1 iSCSI Login Options

The iSCSI Device Node Options describe the iSCSI login options for the key values:

Bits 0:1:
0 = No Header Digest
2 = Header Digest Using CRC32C

Bits 2:3:
0 = No Data Digest
2 = Data Digest Using CRC32C

Bits 4-9:
Reserved for future use

Bits 10-11:
0 = AuthMethod_CHAP
2 = AuthMethod_None

Bit 12:
0 = CHAP_BI
1 = CHAP_UNI

For each specific login key, none, some or all of the defined values may be configured. If none of the options are defined for a specific key, the iSCSI driver shall propose “None” as the value. If more than one option is configured for a specific key, all the configured values will be proposed (ordering of the values is implementation dependent).

- **Portal Group Tag**: defines the iSCSI portal group the initiator intends to establish Session with.
- **Logical Unit Number**: defines the 8 byte SCSI LUN. The Logical Unit Number field must conform to the T-10 SCSI Architecture Model 4 specification. The 8 byte Logical Unit Number field in the device path must conform with a logical unit number returned by a SCSI REPORT LUNS command.
- **iSCSI Target Name**: defines the iSCSI Target Name for the iSCSI Node. The size of the iSCSI Target Name can be up to a maximum of 223 bytes.

### 10.3.4.20.2 Device Path Examples

Some examples for the Device Path for the case the boot device connected to iSCSI bootable controller:

- With IPv4 configuration:

  ```plaintext
  PciRoot(0)/Pci(19|0)/Mac( 001320F5FA77,0x01)/
  IPv4(192.168.0.100,TCP,Static,192.168.0.1)/ iSCSI(iqn.1991-05.com.microsoft:iscsitarget-iscsidisk-target,0x1,0x0,
  None,None,None,TCP)/
  HD(1,GPT,15E39A00-1DD2-1000-8D7F-00A0C92408FC,0x22,0x2710000)
  ``

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>1</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>1</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>2</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>4</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>4</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>1</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>1</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>2</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>1</td>
<td>0x0</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>1</td>
<td>0x19</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>1</td>
<td>0x03</td>
<td>Generic Device Path Header - Messaging Device Path</td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>Hex</th>
<th>No.</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x13</td>
<td>1</td>
<td>0x0B</td>
<td>Sub type - MAC Address Device path</td>
</tr>
<tr>
<td>0x14</td>
<td>2</td>
<td>0x25</td>
<td>Length - 0x25</td>
</tr>
<tr>
<td>0x16</td>
<td>32</td>
<td>0x00, 0x13, 0x20, 0xF5, 0xFA, 0x77, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00</td>
<td>MAC address for a network interface padded with zeros</td>
</tr>
<tr>
<td>0x36</td>
<td>1</td>
<td>0x01</td>
<td>Network Interface Type - other</td>
</tr>
<tr>
<td>0x37</td>
<td>1</td>
<td>0x03</td>
<td>Generic Device Path Header - Messaging Device Path</td>
</tr>
<tr>
<td>0x38</td>
<td>1</td>
<td>0x0c</td>
<td>Sub type - IPv4</td>
</tr>
<tr>
<td>0x39</td>
<td>2</td>
<td>0x1B</td>
<td>Length - 27</td>
</tr>
<tr>
<td>0x3b</td>
<td>4</td>
<td>0xC0, 0xA8, 0x00, 0x01</td>
<td>Local IPv4 address - 192.168.0.1</td>
</tr>
<tr>
<td>0x3F</td>
<td>4</td>
<td>0xC0, 0xA8, 0x00, 0x64</td>
<td>Remote IPv4 address - 192.168.0.100</td>
</tr>
<tr>
<td>0x43</td>
<td>2</td>
<td>0x0000</td>
<td>Local Port Number - 0</td>
</tr>
<tr>
<td>0x45</td>
<td>2</td>
<td>0xCBC</td>
<td>Remote Port Number - 3260</td>
</tr>
<tr>
<td>0x47</td>
<td>2</td>
<td>0x6</td>
<td>Network Protocol. See RFC 3232. TCP</td>
</tr>
<tr>
<td>0x49</td>
<td>1</td>
<td>1</td>
<td>Static IP Address</td>
</tr>
<tr>
<td>0x4A</td>
<td>4</td>
<td></td>
<td>Gateway IP Address</td>
</tr>
<tr>
<td>0x4E</td>
<td>4</td>
<td></td>
<td>Subnet mask</td>
</tr>
<tr>
<td>0x52</td>
<td>1</td>
<td>0x03</td>
<td>Generic Device Path Header - Messaging Device Path</td>
</tr>
<tr>
<td>0x53</td>
<td>1</td>
<td>0x13</td>
<td>Sub type - iSCSI</td>
</tr>
<tr>
<td>0x54</td>
<td>2</td>
<td>0x49</td>
<td>Length - 0x49</td>
</tr>
</tbody>
</table>

continues on next page
Table 10.38 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Length</th>
<th>Value</th>
<th>Network Protocol</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x56</td>
<td>2</td>
<td>0x00</td>
<td></td>
</tr>
<tr>
<td>0x58</td>
<td>2</td>
<td>0x800</td>
<td>iSCSI Login Options - AuthMethod_None</td>
</tr>
<tr>
<td>0x5A</td>
<td>8</td>
<td></td>
<td>iSCSI LUN</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Code</th>
<th>Length</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x62</td>
<td>2</td>
<td>0x01</td>
<td>Target Portal group tag</td>
</tr>
<tr>
<td>0x64</td>
<td>55</td>
<td></td>
<td>iSCSI node name.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x69, 0x71, 0x6E, 0x2E, 0x31, 0x39, 0x39, 0x31, 0x2D, 0x30, 0x35, 0x2E, 0x63, 0x6F, 0x6D, 0x2E, 0x6D, 0x69, 0x63, 0x72, 0x6F, 0x73, 0x6F, 0x66, 0x74,</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x74, 0x3A, 0x69, 0x73, 0x63, 0x73, 0x69, 0x74, 0x61, 0x72, 0x67, 0x65, 0x74, 0x2D, 0x69, 0x73, 0x63, 0x73, 0x69, 0x64, 0x69, 0x73, 0x6B, 0x2D, 0x74, 0x61, 0x72, 0x67, 0x65, 0x74, 0x00</td>
<td>iSCSI node (cont.)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>continues on next page</td>
</tr>
</tbody>
</table>

### 10.3. Device Path Nodes

- 0x9B: 1 byte, 0x04: Generic Device Path Header - Media Device Path
- 0x9C: 1 byte, 0x01: Sub type - Hard Drive
- 0x9D: 2 bytes, 0x2A: Length - 0x2a
- 0x9F: 4 bytes, 0x1: Partition Number
- 0xA3: 8 bytes, 0x22: Partition Start
- 0xAB: 8 bytes, 0x2710000: Partition Size

continues on next page
Table 10.38 – continued from previous page

<table>
<thead>
<tr>
<th>Byte</th>
<th>Offset</th>
<th>Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xB3</td>
<td>16</td>
<td></td>
<td>0x00, 0x9A, 0xE3, 0x15, 0xD2, 0x1D, 0x00, 0x10, 0x8D, 0x7F, 0x00, 0xA0, 0xC9, 0x24, 0x08, xFC</td>
<td>Partition Signature</td>
</tr>
<tr>
<td>0xC3</td>
<td>1</td>
<td></td>
<td>0x02</td>
<td>Partition Format - GPT</td>
</tr>
<tr>
<td>0xC4</td>
<td>1</td>
<td></td>
<td>0x02</td>
<td>Signature Type - GUID</td>
</tr>
<tr>
<td>0xC5</td>
<td>1</td>
<td></td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0xC6</td>
<td>1</td>
<td></td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0xC7</td>
<td>2</td>
<td></td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

- With IPv6 configuration:

```
PciRoot(0x0)/Pci(0x1C,0x2)/Pci(0x0,0x0)/MAC(001517215593,0x0)/IPv6(2001:4898:000A:1005:95A6:EE6C:BED3:4859,TCPDHCP,2001:4898:000A:1005:0215:17FF:FE21:5593)/iSCSI(iqn.1991-05.com.microsoft:iscsiipv6-ipv6test-target,0x1,0x0,None,None,None,TCP)/HD(1,MBR,0xA0021243,0x800,0x2EE000)
```
<table>
<thead>
<tr>
<th>Code</th>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x17</td>
<td>1</td>
<td>0x00</td>
</tr>
<tr>
<td>0x18</td>
<td>1</td>
<td>0x03</td>
</tr>
<tr>
<td>0x19</td>
<td>1</td>
<td>0x0B</td>
</tr>
<tr>
<td>0x1A</td>
<td>2</td>
<td>0x25</td>
</tr>
<tr>
<td>0x1C</td>
<td>32</td>
<td></td>
</tr>
<tr>
<td>0x3C</td>
<td>1</td>
<td>0x01</td>
</tr>
<tr>
<td>0x3D</td>
<td>1</td>
<td>0x03</td>
</tr>
<tr>
<td>0x3E</td>
<td>1</td>
<td>0x0C</td>
</tr>
<tr>
<td>0x3F</td>
<td>2</td>
<td>0x3C</td>
</tr>
</tbody>
</table>

continues on next page
| 0x41 | 16 | 0x20, 0x01, 0x48, 0x98, 0x00, 0x0A, 0x10, 0x05, 0x02, 0x15, 0x17, 0xFF, 0xFE, 0x21, 0x55, 0x93 | Local IPv6 address - 2001:4898:000A:1005:0215:17FF:FE21:5593 |
| 0x51 | 16 | 0x20, 0x01, 0x48, 0x98, 0x00, 0x0A, 0x10, 0x05, 0x95, 0xA6, 0xEE, 0x6C, 0xBE, 0xD3, 0x48, 0x59 | Remote IPv6 address - 2001:4898:000A:1005:95A6:EE6C:BED3:4859 |
| 0x61 | 2 | 0x0000 | Local Port Number - 0 |
| 0x63 | 2 | 0x0CBC | Remote Port Number - 3260 |
| 0x65 | 2 | 0x6 | Network Protocol. See RFC 3232. TCP |
| 0x66 | 1 | 1 | IP Address Origin |
| 0x67 | 1 | 1 | The Prefix Length |
| 0x68 | 16 | The Gateway IP Address |
| 0x78 | 1 | 0x03 | Generic Device Path Header - Messaging Device Path |
| 0x79 | 1 | 0x13 | Sub type - iSCSI |
| 0x7A | 2 | 0x46 | Length - 0x46 |
| 0x7C | 2 | 0x00 | Network Protocol |
| 0x7E | 2 | 0x800 | iSCSI Login Options - AuthMethod_None |
| 0x81 | 8 | 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00 | iSCSI LUN |
| 0x89 | 2 | 0x01 | Target Portal group tag |

continues on next page
Table 10.39 – continued from previous page

<table>
<thead>
<tr>
<th>Format</th>
<th>Length</th>
<th>Data Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x8B</td>
<td>52</td>
<td>iSCSI node name.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x69, 0x71, 0x6E, 0x2E, 0x31, 0x39, 0x39, 0x31, 0x2D, 0x30, 0x35, 0x2E, 0x63, 0x6F, 0x6D, 0x2E, 0x6D, 0x69, 0x63, 0x72, 0x6F, 0x73, 0x6F, 0x66, 0x74, 0x3A, 0x69, 0x73, 0x63, 0x73, 0x69, 0x69, 0x70, 0x76, 0x69, 0x70, 0x76, 0x74, 0x36, 0x74, 0x65, 0x73, 0x74, 0x2D, 0x74, 0x61, 0x72, 0x67, 0x65, 0x74, 0x00</td>
</tr>
<tr>
<td>0x8B</td>
<td>52</td>
<td>iSCSI node name (cont.)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x36, 0x2D, 0x69, 0x70, 0x76, 0x36, 0x74, 0x65, 0x73, 0x74, 0x2D, 0x74, 0x61, 0x72, 0x67, 0x65, 0x74, 0x00</td>
</tr>
<tr>
<td>0xBF</td>
<td>1</td>
<td>0x04</td>
</tr>
<tr>
<td>0xC0</td>
<td>1</td>
<td>0x01</td>
</tr>
<tr>
<td>0xC1</td>
<td>2</td>
<td>0x2A</td>
</tr>
<tr>
<td>0xC3</td>
<td>4</td>
<td>0x1</td>
</tr>
<tr>
<td>0xC7</td>
<td>8</td>
<td>0x800</td>
</tr>
<tr>
<td>0xCF</td>
<td>8</td>
<td>0x2EE000</td>
</tr>
</tbody>
</table>

continues on next page
Table 10.39 – continued from previous page

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0xDF</td>
<td>16</td>
<td>Partition Signature</td>
</tr>
<tr>
<td>0xEF</td>
<td>1</td>
<td>Partition Format - MBR</td>
</tr>
<tr>
<td>0xF0</td>
<td>1</td>
<td>Signature Type - 32bit signature</td>
</tr>
<tr>
<td>0xF1</td>
<td>1</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0xF2</td>
<td>1</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0xF3</td>
<td>2</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

10.3.4.21 NVM Express namespace messaging device path node

Table 10.40: NVM Express Namespace Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub Type 23 - NVM Express Namespace</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 16 bytes.</td>
</tr>
<tr>
<td>Namespace Identifier</td>
<td>4</td>
<td>4</td>
<td>Namespace identifier (NSID). The values of 0 and 0xFFFFFFFF are invalid.</td>
</tr>
<tr>
<td>IEEE Extended Unique Identifier</td>
<td>8</td>
<td>8</td>
<td>This field contains the IEEE Extended Unique Identifier (EUI-64). Devices without an EUI-64 value must initialize this field with a value of 0.</td>
</tr>
</tbody>
</table>

Refer to the latest NVM Express specification for descriptions of Namespace Identifier (NSID) and IEEE Extended Unique Identifier (EUI-64); See “Links to UEFI-Related Documents” (http://www.nvmexpress.org/index) under the heading “NVMe Specification”.

Note: When an application client displays or otherwise makes the EUI-64 identifiers visible to a user, the values should be displayed in hexadecimal format with byte 7 first (i.e., on the left) and byte 0 last (i.e., on the right) regardless of the internal representation of the EUI-64.
10.3.4.22 Uniform Resource Identifiers (URI) Device Path

Refer to RFC 3986 for details on the URI contents.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub Type 24 - Universal Resource Identifier (URI) Device Path</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 4 + n bytes.</td>
</tr>
<tr>
<td>...</td>
<td>4</td>
<td>n</td>
<td>Instance of the URI pursuant to RFC 3986. For an empty URI, Length is 4 bytes.</td>
</tr>
</tbody>
</table>

10.3.4.23 UFS (Universal Flash Storage) device messaging devicepath node

Refer to the UFS 2.0 specification for additional LUN descriptions: See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “UFS 2.0 Specification”.

- PUN field: According to current available UFS 2.0 spec, the topology is one device per UFS port. A topology to support multiple devices on a single interface is planned for future revision. So suggest to reserve/introduce this field to support multiple devices per UFS port. This value should be 0 for current UFS2.0 spec compliance.
- LUN field: This field is used to specify up to 8 normal LUNs(0-7) and 4 well-known LUNs(81h, D0h, B0h and C4h). For those well-known LUNs, the BIT7 is set. See Figure 10.2 of UFS 2.0 spec for details.

10.3.4.24 SD (Secure Digital) Device Path

Refer to the UFS 2.0 specification for additional LUN descriptions: See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “UFS 2.0 Specification”.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 26 - SD</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 5 bytes.</td>
</tr>
<tr>
<td>Slot Number</td>
<td>4</td>
<td>1</td>
<td>Slot Number</td>
</tr>
</tbody>
</table>
10.3.4.25 EFI Bluetooth Device Path

Table 10.44: EFI Bluetooth Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 27 - Bluetooth</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 10 bytes.</td>
</tr>
<tr>
<td>Bluetooth</td>
<td>4</td>
<td>6</td>
<td>48-bit Bluetooth device address.</td>
</tr>
</tbody>
</table>

10.3.4.26 Wireless Device Path

10.3.4.27 eMMC (Embedded Multi-Media Card) Device Path

Table 10.45: eMMC Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 29 - eMMC</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 5 bytes.</td>
</tr>
<tr>
<td>Slot Number</td>
<td>4</td>
<td>1</td>
<td>Slot Number</td>
</tr>
</tbody>
</table>

10.3.4.28 EFI BluetoothLE Device Path

Table 10.46: EFI BluetoothLE Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 30 - BluetoothLE</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 11 bytes.</td>
</tr>
<tr>
<td>Bluetooth</td>
<td>4</td>
<td>6</td>
<td>48-bit Bluetooth device address.</td>
</tr>
<tr>
<td>Address Type</td>
<td>10</td>
<td>1</td>
<td>0x00 - Public Device Address</td>
</tr>
</tbody>
</table>

10.3.4.29 DNS Device Path

Table 10.47: DNS Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 31 - DNS Device Path</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 5 + n bytes.</td>
</tr>
<tr>
<td>IsIPv6</td>
<td>4</td>
<td>1</td>
<td>0x00 - The DNS server address is IPv4 address. 0x01 - The DNS server address is IPv6 address.</td>
</tr>
</tbody>
</table>

continues on next page
Table 10.47 – continued from previous page

| ... | 5 | n | One or more instances of the DNS server address in EFI_IP_ADDRESS. |

10.3.4.30 NVDIMM Namespace path

This device path describes a bootable NVDIMM namespace that is defined by a namespace label. The presence of this type of device path indicates that UEFI supports booting to the namespace including any address abstraction specified by the namespace label. Refer to the NVDIMM Label Protocol section to retrieve relevant details about the namespace.

Table 10.48: NVDIMM Namespace Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 32 - NVDIMM Namespace</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>20 - Single namespace UUID is supported.</td>
</tr>
<tr>
<td>Uuid</td>
<td>4</td>
<td>16</td>
<td>Namespace unique label identifier UUID. See the Uuid description in the NVDIMM Label Protocol - Label definitions section for details on this field.</td>
</tr>
</tbody>
</table>

10.3.4.31 REST Service Device Path

Table 10.49: REST Service Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 0x03 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 33- REST Service Device Path</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 6 bytes.</td>
</tr>
<tr>
<td>REST Service</td>
<td>4</td>
<td>1</td>
<td>0x01 = Redfish REST Service - 0x02 = OData REST Service</td>
</tr>
<tr>
<td>Access Mode</td>
<td>5</td>
<td>1</td>
<td>(0x01) In-Band REST Service, - (0x02) Out-of-band REST Service.</td>
</tr>
</tbody>
</table>

Device path example of Out-of-band Redfish REST Service through NIC:

```
PciRoot(0x2)/Pci(0x2,0x0)/Pci(0x0,0x0)/MAC(FD19FA10672,0x0)/IPv4(0.0.0.0,0x0,DHCP,0.0.0.0,0.0.0.0,0.0.0.0)/RestService(1,2)
```

Table 10.50: Vendor-Specific REST Service Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 0x03 - Messaging Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 33- REST Service Device Path</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 21 + n bytes.</td>
</tr>
<tr>
<td>REST Service</td>
<td>4</td>
<td>1</td>
<td>0xFF = Vendor specific REST Service</td>
</tr>
<tr>
<td>Access Mode</td>
<td>5</td>
<td>1</td>
<td>(0x01) In-Band REST Service, (0x02) Out-of-band REST Service.</td>
</tr>
<tr>
<td>Vendor specific REST service GUID</td>
<td>6</td>
<td>16</td>
<td>GUID of vendor specific REST service.</td>
</tr>
</tbody>
</table>

continues on next page
Device path example of In-band vendor-specific REST Service through BMC:

```
PciRoot(0x2)/Pci(0x2,0x0)/Pci(0x0,0x0)/BMC(0,0xf0000000)/RestService(0xff, 1, 00000000-0000-0000-0000000000000000,0,0)
```

### 10.3.5 Media Device Path

This Device Path is used to describe the portion of the medium that is being abstracted by a boot service. An example of Media Device Path would be defining which partition on a hard drive was being used.

#### 10.3.5.1 Hard Drive

The Hard Drive Media Device Path is used to represent a partition on a hard drive. Each partition has at least Hard Drive Device Path node, each describing an entry in a partition table. EFI supports MBR and GPT partitioning formats. Partitions are numbered according to their entry in their respective partition table, starting with 1. Partitions are addressed in EFI starting at LBA zero. A partition number of zero can be used to represent the raw hard drive or a raw extended partition.

The partition format is stored in the Device Path to allow new partition formats to be supported in the future. The Hard Drive Device Path also contains a Disk Signature and a Disk Signature Type. The disk signature is maintained by the OS and only used by EFI to partition Device Path nodes. The disk signature enables the OS to find disks even after they have been physically moved in a system.

*Load Option Processing* defines special rules for processing the Hard Drive Media Device Path. These special rules enable a disk’s location to change and still have the system boot from the disk.

#### Table 10.51: Hard Drive Media Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 4 — Media Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 1 — Hard Drive</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 42 bytes.</td>
</tr>
<tr>
<td>Partition Number</td>
<td>4</td>
<td>4</td>
<td>Describes the entry in a partition table, starting with entry 1. Partition number zero represents the entire device. Valid partition numbers for a MBR partition are [1, 4]. Valid partition numbers for a GPT partition are [1, NumberOfPartitionEntries].</td>
</tr>
<tr>
<td>Partition Start</td>
<td>8</td>
<td>8</td>
<td>Starting LBA of the partition on the hard drive</td>
</tr>
<tr>
<td>Partition Size</td>
<td>16</td>
<td>8</td>
<td>Size of the partition in units of Logical Blocks</td>
</tr>
<tr>
<td>Partition Signature</td>
<td>24</td>
<td>16</td>
<td>Signature unique to this partition: If SignatureType is 0, this field has to be initialized with 16 zeroes. If SignatureType is 1, the MBR signature is stored in the first 4 bytes of this field. The other 12 bytes are initialized with zeroes. If SignatureType is 2, this field contains a 16 byte signature.</td>
</tr>
<tr>
<td>Partition Format</td>
<td>40</td>
<td>1</td>
<td>Partition Format: (Unused values reserved) 0x01 - PC-AT compatible legacy MBR (<em>Legacy MBR</em>). Partition Start and Partition Size come from <em>PartitionStartingLBA</em> and <em>PartitionSizeInLBA</em> for the partition.0x02—GUID Partition Table</td>
</tr>
</tbody>
</table>

continues on next page
Table 10.51 – continued from previous page

| Signature Type | 41 | 1 | Type of Disk Signature: (Unused values reserved) 0x00 - No Disk Signature. 0x01 - 32-bit signature from address 0x1b8 of the type 0x01 MBR. 0x02 - GUID signature. |

10.3.5.2 CD-ROM Media Device Path

The CD-ROM Media Device Path is used to define a system partition that exists on a CD-ROM. The CD-ROM is assumed to contain an ISO-9660 file system and follow the CD-ROM “El Torito” format. The Boot Entry number from the Boot Catalog is how the “El Torito” specification defines the existence of bootable entities on a CD-ROM. In EFI the bootable entity is an EFI System Partition that is pointed to by the Boot Entry.

Table 10.52: CD-ROM Media Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 4 - Media Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 2 - CD-ROM “El Torito” Format.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 24 bytes.</td>
</tr>
<tr>
<td>Boot Entry</td>
<td>4</td>
<td>4</td>
<td>Boot Entry number from the Boot Catalog. The Initial/Default entry is defined as zero.</td>
</tr>
<tr>
<td>Partition Start</td>
<td>8</td>
<td>8</td>
<td>Starting RBA of the partition on the medium. CD-ROMs use Relative logical Block Addressing.</td>
</tr>
<tr>
<td>Partition Size</td>
<td>16</td>
<td>8</td>
<td>Size of the partition in units of Blocks, also called Sectors.</td>
</tr>
</tbody>
</table>

10.3.5.3 Vendor-Defined Media Device Path

Table 10.53: Vendor-Defined Media Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 4 - Media Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 3 - Vendor.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 20 + n bytes.</td>
</tr>
<tr>
<td>Vendor GUID</td>
<td>4</td>
<td>16</td>
<td>Vendor-assigned GUID that defines the data that follows.</td>
</tr>
<tr>
<td>Vendor Defined Data</td>
<td>20</td>
<td>n</td>
<td>Vendor-defined variable size data.</td>
</tr>
</tbody>
</table>

10.3.5.4 File Path Media Device Path

Table 10.54: File Path Media Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 4 - Media Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 4 - File Path.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 4 + n bytes.</td>
</tr>
</tbody>
</table>

continues on next page
Table 10.54 – continued from previous page

| Path Name | 4 | $N$ | A NULL-terminated Path string including directory and file names. The length of this string $n$ can be determined by subtracting 4 from the Length entry. A device path may contain one or more of these nodes. Each node can optionally add a "" separator to the beginning and/or the end of the Path Name string. The complete path to a file can be found by logically concatenating all the Path Name strings in the File Path Media Device Path nodes. This is typically used to describe the directory path in one node, and the filename in another node. |

Rules for Path Name conversion:

- When concatenating two Path Names, ensure that the resulting string does not contain a double-separator “\”. If it does, convert that double-separator to a single-separator.
- In the case where a Path Name which has no end separator is being concatenated to a Path Name with no beginning separator, a separator will need to be inserted between the Path Names.
- Single file path nodes with no directory path data are presumed to have their files located in the root directory of the device.

10.3.5.5 Media Protocol Device Path

The Media Protocol Device Path is used to denote the protocol that is being used in a device path at the location of the path specified. Many protocols are inherent to the style of device path.

Table 10.55: Media Protocol Media Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 4 - Media Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 5 - Media Protocol.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 20 bytes.</td>
</tr>
<tr>
<td>Protocol GUID</td>
<td>4</td>
<td>16</td>
<td>The ID of the protocol.</td>
</tr>
</tbody>
</table>

10.3.5.6 PIWG Firmware File

This type is used by systems implementing the UEFI PI Specification to describe a firmware file. The exact format and usage are defined in that specification.

Table 10.56: PIWG Firmware File Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 4 - Media Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 6 - PIWG Firmware File.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is $4 + n$ bytes.</td>
</tr>
<tr>
<td>…</td>
<td>4</td>
<td>$n$</td>
<td>Contents are defined in the UEFI PI Specification.</td>
</tr>
</tbody>
</table>
10.3.5.7 PIWG Firmware Volume

This type is used by systems implementing the UEFI PI Specification to describe a firmware volume. The exact format and usage are defined in that specification.

Table 10.57: PIWG Firmware Volume Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 4 - Media Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 7 - PIWG Firmware Volume.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 4 + n bytes.</td>
</tr>
<tr>
<td>...</td>
<td>4</td>
<td>n</td>
<td>Contents are defined in the UEFI PI Specification.</td>
</tr>
</tbody>
</table>

10.3.5.8 Relative Offset Range

This device path node specifies a range of offsets relative to the first byte available on the device. The starting offset is the first byte of the range and the ending offset is the last byte of the range (not the last byte + 1).

Table 10.58: Relative Offset Range

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 4 - Media Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 8 - Relative Offset Range</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 4 + n bytes.</td>
</tr>
<tr>
<td>Reserved</td>
<td>4</td>
<td>4</td>
<td>Reserved for future use.</td>
</tr>
<tr>
<td>Starting Offset</td>
<td>8</td>
<td>8</td>
<td>Offset of the first byte, relative to the parent device node.</td>
</tr>
<tr>
<td>Ending Offset</td>
<td>16</td>
<td>8</td>
<td>Offset of the last byte, relative to the parent device node.</td>
</tr>
</tbody>
</table>

10.3.5.9 RAM Disk

Table 10.59: RAM Disk Device Path

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 4 - Media Device Path</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub Type 9 - RAM Disk Device Path</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 38 bytes.</td>
</tr>
<tr>
<td>Starting Address</td>
<td>4</td>
<td>8</td>
<td>Starting Memory Address.</td>
</tr>
<tr>
<td>Ending Address</td>
<td>12</td>
<td>8</td>
<td>Ending Memory Address.</td>
</tr>
<tr>
<td>Disk Type GUID</td>
<td>20</td>
<td>16</td>
<td>GUID that defines the type of the RAM Disk. The GUID can be any of the values defined below, or a vendor defined GUID.</td>
</tr>
<tr>
<td>Disk Instance</td>
<td>36</td>
<td>2</td>
<td>RAM Disk instance number, if supported. The default value is zero.</td>
</tr>
</tbody>
</table>

The following GUIDs are used with a RAM Disk Device Path to describe the RAM Disk Type. Additional GUIDs can be generated to describe additional RAM Disk Types. The Disk Type GUID values used in the RAM Disk device path must match the corresponding values in the Address Range Type GUID of the ACPI NFIT table. Refer to the ACPI specification for details.

This GUID defines a RAM Disk supporting a raw disk format in volatile memory:
### 10.3.6 BIOS Boot Specification Device Path

This Device Path is used to describe the booting of non-EFI-aware operating systems. This Device Path is based on the IPL and BCV table entry data structures defined in Appendix A of the *BIOS Boot Specification*. The BIOS Boot Specification Device Path defines a complete Device Path and is not used with other Device Path entries. This Device Path is only needed to enable platform firmware to select a legacy non-EFI OS as a boot option.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 5 - BIOS Boot Specification Device Path.</td>
</tr>
<tr>
<td>Sub-Type</td>
<td>1</td>
<td>1</td>
<td>Sub-Type 1 - BIOS Boot Specification Version 1.01.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 8 + n bytes.</td>
</tr>
<tr>
<td>Device Type</td>
<td>4</td>
<td>2</td>
<td>Device Type as defined by the BIOS Boot Specification.</td>
</tr>
<tr>
<td>Status Flag</td>
<td>6</td>
<td>2</td>
<td>Status Flags as defined by the BIOS Boot Specification.</td>
</tr>
<tr>
<td>Description String</td>
<td>8</td>
<td>n</td>
<td>A null-terminated ASCII string that describes the boot device to a user.</td>
</tr>
</tbody>
</table>

Example BIOS Boot Specification Device Types include:

- 00h = Reserved
- 01h = Floppy
- 02h = Hard Disk
- 03h = CD-ROM
- 04h = PCMCIA
- 05h = USB
• 06h = Embedded network
• 07h..7Fh = Reserved
• 80h = BEV device
• 81h..FEh = Reserved
• FFh = Unknown

NOTE: When UEFI Secure Boot is enabled, attempts to boot non-UEFI OS shall fail; Firmware/OS Key Exchange: Passing Public Keys.

10.4 Device Path Generation Rules

10.4.1 Housekeeping Rules

The Device Path is a set of Device Path nodes. The Device Path must be terminated by an End of Device Path node with a sub-type of End the Entire Device Path. A NULL Device Path consists of a single End Device Path Node. A Device Path that contains a NULL pointer and no Device Path structures is illegal.

All Device Path nodes start with the generic Device Path structure. Unknown Device Path types can be skipped when parsing the Device Path since the length field can be used to find the next Device Path structure in the stream. Any future additions to the Device Path structure types will always start with the current standard header. The size of a Device Path can be determined by traversing the generic Device Path structures in each header and adding up the total size of the Device Path. This size will include the four bytes of the End of Device Path structure.

Multiple hardware devices may be pointed to by a single Device Path. Each hardware device will contain a complete Device Path that is terminated by the Device Path End Structure. The Device Path End Structures that do not end the Device Path contain a sub-type of End This Instance of the Device Path. The last Device Path End Structure contains a sub-type of End Entire Device Path.

10.4.2 Rules with ACPI _HID and _UID

As described in the ACPI specification, ACPI supports several different kinds of device identification objects, including _HID, _CID and _UID. The _UID device identification objects are optional in ACPI and only required if more than one _HID exists with the same ID. The ACPI Device Path structure must contain a zero in the _UID field if the ACPI name space does not implement _UID. The _UID field is a unique serial number that persists across reboots.

If a device in the ACPI name space has a _HID and is described by a _CRS (Current Resource Setting) then it should be described by an ACPI Device Path structure. A _CRS implies that a device not mapped by any other standard. A _CRS is used by ACPI to make a nonstandard device into a Plug and Play device. The configuration methods in the ACPI name space allow the ACPI driver to configure the device in a standard fashion. The presence of a _CID determines whether the ACPI Device Path node or the Expanded ACPI Device Path node should be used.

See Table below.

Table 10.61: ACPI_CRS to EFI Device Path Mapping

<table>
<thead>
<tr>
<th>ACPI _CRS Item</th>
<th>EFI Device Path</th>
</tr>
</thead>
<tbody>
<tr>
<td>PCI Root Bus</td>
<td>ACPI Device Path: _HID PNP0A03, _UID</td>
</tr>
<tr>
<td>Floppy</td>
<td>ACPI Device Path: _HID PNP0604, _UID drive select encoding 0-3</td>
</tr>
<tr>
<td>Keyboard</td>
<td>ACPI Device Path: _HID PNP0301, _UID 0</td>
</tr>
<tr>
<td>Serial Port</td>
<td>ACPI Device Path: _HID PNP0501, _UID Serial Port COM number 0-3</td>
</tr>
<tr>
<td>Parallel Port</td>
<td>ACPI Device Path: _HID PNP0401, _UID LPT number 0-3</td>
</tr>
</tbody>
</table>
Support of root PCI bridges requires special rules in the EFI Device Path. A root PCI bridge is a PCI device usually contained in a chipset that consumes a proprietary bus and produces a PCI bus. In typical desktop and mobile systems there is only one root PCI bridge. On larger server systems there are typically multiple root PCI bridges. The operation of root PCI bridges is not defined in any current PCI specification. A root PCI bridge should not be confused with a PCI to PCI bridge that both consumes and produces a PCI bus. The operation and configuration of PCI to PCI bridges is fully specified in current PCI specifications.

Root PCI bridges will use the plug and play ID of PNP0A03. This will be stored in the ACPI Device Path _HID field, or in the Expanded ACPI Device Path _CID field to match the ACPI name space. The _UID in the ACPI Device Path structure must match the _UID in the ACPI name space.

### 10.4.3 Rules with ACPI _ADR

If a device in the ACPI name space can be completely described by a _ADR object then it will map to an EFI ACPI, Hardware, or Message Device Path structure. A _ADR method implies a bus with a standard enumeration algorithm. If the ACPI device has a _ADR and a _CRS method, then it should also have a _HID method and follow the rules for using _HID. See the table below as it relates the ACPI _ADR bus definition to the EFI Device Path:

<table>
<thead>
<tr>
<th>ACPI _ADR Bus</th>
<th>EFI Device Path</th>
</tr>
</thead>
<tbody>
<tr>
<td>EISA</td>
<td>Not supported</td>
</tr>
<tr>
<td>Floppy Bus</td>
<td>ACPI Device Path: _HID PNP0604, _UID drive select encoding 0-3</td>
</tr>
<tr>
<td>IDE Controller</td>
<td>ATAPI Message Device Path: Master/Slave : LUN</td>
</tr>
<tr>
<td>IDE Channel</td>
<td>ATAPI Message Device Path: Master/Slave : LUN</td>
</tr>
<tr>
<td>PCI</td>
<td>PCI Hardware Device Path</td>
</tr>
<tr>
<td>PCMCIA</td>
<td>Not Supported</td>
</tr>
<tr>
<td>PC CARD</td>
<td>PC CARD Hardware Device Path</td>
</tr>
<tr>
<td>SMBus</td>
<td>Not Supported</td>
</tr>
<tr>
<td>SATA bus</td>
<td>SATA Messaging Device Path</td>
</tr>
</tbody>
</table>

### 10.4.4 Hardware vs. Messaging Device Path Rules

Hardware Device Paths are used to define paths on buses that have a standard enumeration algorithm and that relate directly to the coherency domain of the system. The coherency domain is defined as a global set of resources that is visible to at least one processor in the system. In a typical system this would include the processor memory space, IO space, and PCI configuration space.

Messaging Device Paths are used to define paths on buses that have a standard enumeration algorithm, but are not part of the global coherency domain of the system. SCSI and Fibre Channel are examples of this kind of bus. The Messaging Device Path can also be used to describe virtual connections over network-style devices. An example would be the TCP/IP address of an internet connection.

Thus Hardware Device Path is used if the bus produces resources that show up in the coherency resource domain of the system. A Message Device Path is used if the bus consumes resources from the coherency domain and produces resources outside the coherency domain of the system.
10.4.5 Media Device Path Rules

The Media Device Path is used to define the location of information on a medium. Hard Drives are subdivided into partitions by the MBR and a Media Device Path is used to define which partition is being used. A CD-ROM has boot partitions that are defined by the “El Torito” specification, and the Media Device Path is used to point to these partitions.

A **EFI_BLOCK_IO_PROTOCOL** is produced for both raw devices and partitions on devices. This allows the **EFI_SIMPLE_FILE_SYSTEM_PROTOCOL** protocol to not have to understand media formats. The **EFI_BLOCK_IO_PROTOCOL** for a partition contains the same Device Path as the parent **EFI_BLOCK_IO_PROTOCOL** for the raw device with the addition of a Media Device Path that defines which partition is being abstracted.

The Media Device Path is also used to define the location of a file in a file system. This Device Path is used to load files and to represent what file an image was loaded from.

10.4.6 Other Rules

The BIOS Boot Specification Device Path is not a typical Device Path. A Device Path containing the BIOS Boot Specification Device Path should only contain the required End Device Path structure and no other Device Path structures. The BIOS Boot Specification Device Path is only used to allow the EFI boot menus to boot a legacy operating system from legacy media.

The EFI Device Path can be extended in a compatible fashion by assigning your own vendor GUID to a Hardware, Messaging, or Media Device Path. This extension is guaranteed to never conflict with future extensions of this specification.

The EFI specification reserves all undefined Device Path types and subtypes. Extension is only permitted using a Vendor GUID Device Path entry.

10.5 Device Path Utilities Protocol

This section describes the **EFI_DEVICE_PATH_UTILITIES_PROTOCOL**, which aids in creating and manipulating device paths.

10.5.1 EFI_DEVICE_PATH_UTILITIES_PROTOCOL

**Summary**

Creates and manipulates device paths and device nodes.

**GUID**

```
// {0379BE4E-D706-437d-B037-EDB82FB772A4}
#define EFI_DEVICE_PATH_UTILITIES_PROTOCOL_GUID
{0x379be4e,0xd706,0x437d,
 {0xb0,0x37,0xed,0xb8,0x2f,0xb7,0x72,0xa4 }}
```

**Protocol Interface Structure**

```c
typedef struct _EFI_DEVICE_PATH_UTILITIES_PROTOCOL {
    EFI_DEVICE_PATH_UTILS_GET_DEVICE_PATH_SIZE GetDevicePathSize;
    EFI_DEVICE_PATH_UTILS_DUPDEVICE_PATH DuplicateDevicePath;
    EFI_DEVICE_PATH_UTILS_APPEND_PATH AppendDevicePath;
} EFI_DEVICE_PATH_UTILITIES_PROTOCOL;
```
Parameters

GetDevicePathSize
Returns the size of the specified device path, in bytes.

DuplicateDevicePath
Duplicates a device path structure.

AppendDeviceNode
Appends the device node to the specified device path.

AppendDevicePath
Appends the device path to the specified device path.

AppendDevicePathInstance
Appends a device path instance to another device path.

GetNextDevicePathInstance
Retrieves the next device path instance from a device path data structure.

IsDevicePathMultiInstance
Returns TRUE if this is a multi-instance device path.

CreateDeviceNode
Allocates memory for a device node with the specified type and sub-type.

Description
The EFI_DEVICE_PATH_UTILITIES_PROTOCOL provides common utilities for creating a manipulating device paths and device nodes.

10.5.2 EFI_DEVICE_PATH_UTILITIES_PROTOCOL.GetDevicePathSize()

Summary
Returns the size of the device path, in bytes.

Prototype

typedef
UINTN
(EIFIAPI *EFI_DEVICE_PATH_UTILS_GET_DEVICE_PATH_SIZE) (   
   IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePath
   );

Parameters

DevicePath
Points to the start of the EFI device path.

Description
This function returns the size of the specified device path, in bytes, including the end-of-path tag. If DevicePath is NULL then zero is returned.

Related Definitions
EFI_DEVICE_PATH_PROTOCOL is defined in *EFI Device Path Protocol*.

10.5.3 EFI_DEVICE_PATH_UTILITIES_PROTOCOL.DuplicateDevicePath()

Summary
Create a duplicate of the specified path.

Prototype

typedef EFI_DEVICE_PATH_PROTOCOL* (EFIAPI *EFI_DEVICE_PATH_UTILS_DUP_DEVICE_PATH) (IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePath);

Parameters
DevicePath
Points to the source device path.

Description
This function creates a duplicate of the specified device path. The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated. If DevicePath is NULL then NULL will be returned and no memory will be allocated.

Related Definitions
EFI_DEVICE_PATH_PROTOCOL is defined in *EFI Device Path Protocol*.

Returns
This function returns a pointer to the duplicate device path or NULL if there was insufficient memory.

10.5.4 EFI_DEVICE_PATH_UTILITIES_PROTOCOL.AppendDevicePath()

Summary
Create a new path by appending the second device path to the first.

Prototype

typedef EFI_DEVICE_PATH_PROTOCOL* (EFIAPI *EFI_DEVICE_PATH_UTILS_APPEND_PATH) (IN CONST EFI_DEVICE_PATH_PROTOCOL *Src1, IN CONST EFI_DEVICE_PATH_PROTOCOL *Src2);

Parameters
Src1
Points to the first device path.
Src2

Points to the second device path.

Description

This function creates a new device path by appending a copy of the second device path to a copy of the first device path in a newly allocated buffer. Only the end-of-device-path device node from the second device path is retained. If Src1 is NULL and Src2 is non-NULL, then a duplicate of Src2 is returned. If Src1 is non-NULL and Src2 is NULL, then a duplicate of Src1 is returned. If Src1 and Src2 are both NULL, then a copy of an end-of-device-path is returned.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in EFI Device Path Protocol.

Returns

This function returns a pointer to the newly created device path or NULL if memory could not be allocate.

10.5.5 EFI_DEVICE_PATH_UTILITIES_PROTOCOL.AppendDeviceNode()

Summary

Creates a new path by appending the device node to the device path.

Prototype

```c
typedef EFI_DEVICE_PATH_PROTOCOL*
(EFIAPI *EFI_DEVICE_PATH_UTILS_APPEND_NODE) (  
  IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePath,  
  IN CONST EFI_DEVICE_PATH_PROTOCOL *DeviceNode
);
```

Parameters

DevicePath

Points to the device path.

DeviceNode

Points to the device node.

Description

This function creates a new device path by appending a copy of the specified device node to a copy of the specified device path in an allocated buffer. The end-of-device-path device node is moved after the end of the appended device node. If DeviceNode is NULL then a copy of DevicePath is returned. If DevicePath is NULL then a copy of DeviceNode, followed by an end-of-device path device node is returned. If both DeviceNode and DevicePath are NULL then a copy of an end-of-device-path device node is returned.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in EFI Device Path Protocol.

Returns
This function returns a pointer to the allocated device path, or NULL if there was insufficient memory.

### 10.5.6 EFI_Device_PathUtilitiesProtocol.AppendDevicePathInstance()

**Summary**

Creates a new path by appending the specified device path instance to the specified device path.

**Prototype**

```
typedef
EFI_DEVICE_PATH_PROTOCOL*
(EFIAPI *EFI_DEVICE_PATH_UTILS_APPEND_INSTANCE) (  
  IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePath,  
  IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePathInstance  
);
```

**Parameters**

- **DevicePath**
  Points to the device path. If NULL, then ignored.

- **DevicePathInstance**
  Points to the device path instance

**Description**

This function creates a new device path by appending a copy of the specified device path instance to a copy of the specified device path in an allocated buffer. The end-of-device-path device node is moved after the end of the appended device node and a new end-of-device-path-instance node is inserted between. If `DevicePath` is NULL, then a copy if `DevicePathInstance` is returned instead.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

**Related Definitions**

EFI_DEVICE_PATH_PROTOCOL is defined in *EFI Device Path Protocol*.

**Returns**

This function returns a pointer to the newly created device path or NULL if `DevicePathInstance` is NULL or there was insufficient memory.

### 10.5.7 EFI_Device_PathUtilitiesProtocol.GetNextDevicePathInstance()

**Summary**

Creates a copy of the current device path instance and returns pointer to the next device path instance.

**Prototype**

```
typedef
EFI_DEVICE_PATH_PROTOCOL*
(EFIAPI *EFI_DEVICE_PATH_UTILS_GET_NEXT_INSTANCE) (  
  IN OUT EFI_DEVICE_PATH_PROTOCOL **DevicePathInstance,  
  OUT UINTN *DevicePathInstanceSize* OPTIONAL  
);
```
Parameters

DevicePathInstance
On input, this holds the pointer to the current device path instance. On output, this holds the pointer to the next device path instance or NULL if there are no more device path instances in the device path.

DevicePathInstanceSize
On output, this holds the size of the device path instance, in bytes or zero, if DevicePathInstance is NULL. If NULL, then the instance size is not output.

Description
This function creates a copy of the current device path instance. It also updates DevicePathInstance to point to the next device path instance in the device path (or NULL if no more) and updates DevicePathInstanceSize to hold the size of the device path instance copy.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions
EFI_DEVICE_PATH_PROTOCOL is defined in EFI Device Path Protocol.

Returns
This function returns a pointer to the copy of the current device path instance or NULL if DevicePathInstance was NULL on entry or there was insufficient memory.

10.5.8 EFI_DEVICE_PATHUTILITIES_PROTOCOL.CreateDeviceNode()

Summary
Creates a device node

Prototype

typedef EFI_DEVICE_PATH_PROTOCOL* (EFIAPI *EFI_DEVICE_PATH_UTILS_CREATE_NODE) (  
  IN UINT8 NodeType,  
  IN UINT8 NodeSubType,  
  IN UINT16 NodeLength  
);  

Parameters

NodeType
NodeType is the device node type (EFI_DEVICE_PATH_PROTOCOL.Type) for the new device node.

NodeSubType
NodeSubType is the device node sub-type (EFI_DEVICE_PATH_PROTOCOL.SubType) for the new device node.

NodeLength
NodeLength is the length of the device node (EFI_DEVICE_PATH_PROTOCOL.Length) for the new device node.

Description
This function creates a new device node in a newly allocated buffer.
The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI\_DEVICE\_PATH\_PROTOCOL is defined in *EFI Device Path Protocol*.

Returns

This function returns a pointer to the created device node or NULL if *NodeLength* is less than the size of the header or there was insufficient memory.

### 10.5.9 EFI\_DEVICE\_PATH\_UTILITIES\_PROTOCOL.IsDevicePathMultiInstance()

Summary

Returns whether a device path is multi-instance.

Prototype

```c
typedef BOOLEAN (EFIAPI *EFI\_DEVICE\_PATH\_UTILITIES\_IS\_MULTI\_INSTANCE) (IN CONST EFI\_DEVICE\_PATH\_PROTOCOL *DevicePath);
```

Parameters

DevicePath

Points to the device path. If NULL, then ignored.

Description

This function returns whether the specified device path has multiple path instances.

Related Definitions

EFI\_DEVICE\_PATH\_PROTOCOL* is defined in *EFI Device Path Protocol*.

Returns

This function returns **TRUE** if the device path has more than one instance or **FALSE** if it is empty or contains only a single instance.

### 10.6 EFI Device Path Display Format Overview

This section describes the recommended conversion between an EFI Device Path Protocol and text. It also describes standard protocols for implementing these. The goals are:

- Standardized display format. This allows documentation and test tools to understand output coming from drivers provided by multiple vendors.
- Increase Readability. Device paths need to be read by people, so the format should be in a form which can be deciphered, maintaining as much as possible the industry standard means of presenting data. In this case, there are two forms, a display-only form and a parse-able form.
- Round-trip conversion from text to binary form and back to text without loss, if desired.
• Ease of command-line parsing. Since device paths can appear on the command-lines of UEFI applications executed from a shell, the conversion format should not prohibit basic command-line processing, either by the application or by a shell.

10.6.1 Design Discussion

The following subsections describe the design considerations for conversion to and from the EFI Device Path Protocol binary format and its corresponding text form.

10.6.1.1 Standardized Display Format

Before the UEFI 2.0, there was no standardized format for the conversion from the EFI Device Path protocol and text. Some de-facto standards arose, either as part of the standard implementation or in descriptive text in the EFI Device Driver Writer’s Guide, although they didn’t agree. The standardized format attempts to maintain at least the spirit of these earlier ideas.

10.6.1.2 Readability

Since these are conversions to text and, in many cases, users have to read and understand the text form of the EFI Device Path, it makes sense to make them as readable as reasonably possible. Several strategies are used to accomplish this:

• Creating simplified forms for well-known device paths. For example, a PCI root Bridge can be represented as Acpi(PNP0A03,0), but makes more sense as PciRoot(0). When converting from text to binary form, either form is accepted, but when converting from binary form to text, the latter is preferred.

• Omitting the conversion of fields which have empty or default values. By doing this, the average display length is greatly shortened, which improves readability.

10.6.1.3 Round-Trip Conversion

The conversions specified here guarantee at least that conversion to and from the binary representation of the EFI Device Path will be semantically identical.

Text-to-Binary-Conversion

Text \( \delta \) Binary \( \delta \) Text \( \delta \) Binary 2

In the above conversion, the process described in this section is applied to Text1, converting it to Binary1. Subsequently, Binary1 is converted to Text2. Finally, the Text2 is converted to Binary2. In these cases, Binary1 and Binary2 will always be identical. Text1 and Text2 may or may not be identical. This is the result of the fact that the text representation has, in some cases, more than one way of representing the same EFI Device Path node.

Binary to Text Conversion

Binary \( \delta \) Text \( \delta \) Binary \( \delta \) Text 2

In the above conversion, the process described in this section is applied to Binary1, converting it to Text1. Subsequently, Text1 is converted to Binary2. Finally, Binary2 is converted to Text2. In these cases, Binary1 and Binary2 will always be identical and Text1 and Text2 will always be identical.

Another consideration in round-trip conversion is potential ambiguity in parsing. This happens when the text representation could be converted into more than type of device node, thus requiring information beyond that contained in the text representation in order to determine the correct conversion to apply. In the case of EFI Device Paths, this causes problems primarily with literal strings in the device path, such as those found in file names, volumes or directories.
For example, the file name Acpi(PNP0A03,0) might be a legal FAT32 file name. However, in parsing this, it is not clear whether it refers to an Acpi device node or a file name. Thus, it is ambiguous. In order to prevent ambiguity, certain characters may only be used for device node keywords and may not be used in file names or directories.

10.6.1.4 Command-Line Parsing

Applications written to this specification need to accept the text representation of EFI device paths as command-line parameters, possibly in the context of a command-prompt or shell. In order to do this, the text representation must follow simple guidelines concerning its format.

Command-line parsing generally involves three separate concepts: substitution, redirection and division.

In substitution, the invoker of the application modifies the actual contents of the command-line before it is passed to the application. For example:

```
copy *.xyz
```

In redirection, the invoker of the application gleans from the command line parameters which it uses to, for example, redirect or pipe input or output. For example:

```
echo This text is copied to a file >abc
dir | more
```

Finally, in division, the invoker or the application startup code divides the command-line up into individual arguments. The following line, for example, has (at least) three arguments, divided by whitespace:

```
copy /b file1.info file2.info
```

10.6.1.5 Text Representation Basics

This section describes the basic rules for the text representation of device nodes and device paths. The formal grammar describing appears later.

The text representation of a device path (or text device path) consists of one or more text device nodes, each preceded by a ‘/’ or ‘\’ character. The behavior of a device path where the first node is not preceded by one of these characters is undefined. Some implementations may treat it as a relative path from a current working directory.

Spaces are not allowed at any point within the device path, except when contained in double quotes (“”). The ‘|’ (bar), ‘<’ (less than) and ‘>’ (greater than) characters are likewise reserved for use by the shell.

Device Path Text Representation

```
device-path:="\device-node
\device-node
\device-path device-node
\device-path device-node
```

There are two types of text device nodes: file-name/directory or canonical. Canonical text device nodes are prefixed by an option name consisting of only alphanumerical characters, followed by a parenthesis, followed by option-specific parameters separated by a ‘,’ (comma). File names and directories have no prefixes.

Text Device Node Names
The canonical device node can have zero or more option parameters between the parentheses. Multiple option parameters are separated by a comma. The meaning of the option parameters depends primarily on the option name, then the parameter-identifier (if present) and then the order of appearance in the parameter list. The parameter identifier allows the text representation to only contain the non-default option parameter value, even if it would normally appear fourth in the list of option parameters. Missing parameters do not require the comma unless needed as a placeholder to correctly increment the parameter count for a subsequent parameter.

Consider:

```plaintext
AcpiEx(HWP0002, PNP0A03,0)
```

Which could also be written:

```plaintext
AcpiEx(HWP0002,CID=PNP0A03) or
AcpiEx(HWP0002,PNP0A03)
```

Since CID and UID are optional parameters. Or consider:

```plaintext
Acpi(HWP0002,0)
```

Which could also be written:

```plaintext
Acpi(HWP0002)
```

Since UID is an optional parameter.

### Device Node Option Names

| option-name := alphanumeric characters string |
| option-parameters := option-parameter |
| option-parameters, option-parameter |
| option-parameter := parameter-value |
| parameter-identifier=parameter-value |

### 10.6.1.6 Text Device Node Reference

In each of the following table rows, a specific device node type and sub-type are given, along with the most general form of the text representation. Any parameters for the device node are listed in italics. In each case, the type is listed and along with it what is required or optional, and any default value, if applicable. On subsequent lines, alternate representations are listed. In general, these alternate representations are simplified by the assumption that one or more of the parameters is set to a specific value.

#### Parameter Types

This section describes the various types of option parameter values.
Table 10.63: EFI Device Path Option Parameter Values

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>GUID</td>
<td>An EFI GUID in standard format xxxxxxxx-xxxx-xxxx-xxxx-xxxxxxxxxxxx. (See Appendix A)</td>
</tr>
<tr>
<td>Keyword</td>
<td>In some cases, one of a series of keywords must be listed.</td>
</tr>
<tr>
<td>Integer</td>
<td>Unless otherwise specified, this indicates an unsigned integer in the range of 0 to 2^32-1. The value is decimal, unless preceded by “0x” or “0X”, in which case it is hexadecimal.</td>
</tr>
<tr>
<td>EISAID</td>
<td>A seven character text identifier in the format used by the ACPI specification. The first three characters must be alphabetic, either upper or lower case. The second four characters are hexadecimal digits, either numeric, upper case or lower case. Optionally, it can be the number 0.</td>
</tr>
<tr>
<td>String</td>
<td>Series of alphabetic, numeric and punctuation characters not including a right parenthesis ‘)’, bar ‘</td>
</tr>
<tr>
<td>HexDump</td>
<td>Series of bytes, represented by two hexadecimal characters per byte. Unless otherwise indicated, the size is only limited by the length of the device node.</td>
</tr>
<tr>
<td>IPv4 Address</td>
<td>Series of four integer values (each between 0-255), separated by a ‘.’. Optionally, followed by a ‘:’ and an integer value between 0-65535. If the ‘:’ is not present, then the port value is zero.</td>
</tr>
<tr>
<td>IPv6 Address</td>
<td>IPv6 Address is expressed in the format [address]:port. The ‘address’ is expressed in the way defined in RFC4291 Section 2.2. The ‘:port’ after the [address] is optional. If present, the ‘port’ is an integer value between 0-65535 to represent the port number, or else, port number is zero.</td>
</tr>
</tbody>
</table>

Table 10.64: Device Node Table

<table>
<thead>
<tr>
<th>Device Type/SubType/Other</th>
<th>Description</th>
</tr>
</thead>
</table>
| (when type is not recognized) | **Path (type, subtype, data)**  
The type is an integer from 0-255.  
The sub-type is an integer from 0-255.  
The data is a hex dump. |
| Type: 1 (Hardware Device Path) (when subtype is not recognized) | **HardwarePath** (subtype, data)  
The subtype is an integer from 0-255.  
The data is a hex dump. |
| Type: 1 (Hardware Device Path) SubType: 1 (PCI) | Pci(Device, Function)  
The Device is an integer from 0-31 and is required.  
The Function is an integer from 0-7 and is required. |
| Type: 1 (Hardware Device Path) SubType: 2 (PcPcard) | PcCard (Function)  
The Function is an integer from 0-255 and is required. |

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Table 10.64 – continued from previous page

| Type: 1 (Hardware Device Path) | **MemoryMapped** *(EfiMemoryType,StartingAddress, EndingAddress)*  
The EfiMemoryType is a 32-bit integer and is required.  
The StartingAddress and EndingAddress are both 64-bit integers and are both required. |
| Type: 1 (Hardware Device Path) SubType: 3 (Memory Mapped) |

| Type: 1 (Hardware Device Path) SubType: 4 (Vendor) | **VenHw(Guid, Data)**  
The Guid is a GUID and is required.  
The Data is a Hex Dump and is optional. The default value is zero bytes. |
| Type: 1 (Hardware Device Path) SubType: 4 (Vendor) |

| Type: 1 (Hardware Device Path) SubType: 5 (Controller) | **Ctrl(Controller)**  
The Controller is an integer and is required. |
| Type: 1 (Hardware Device Path) SubType: 5 (Controller) |

| Type: 1 (Hardware Device Path) SubType: 6 (BMC) | **BMC** *(Type,Address)*  
The Type is an integer from 0-255, and is required.  
The Address is an unsigned 64-bit integer, and is required. |
| Type: 1 (Hardware Device Path) SubType: 6 (BMC) |

| Type: 2 (ACPI Device Path) (when subtype is not recognized) | **AcpiPath(subtype, data)** The subtype is an integer from 0-255. The data is a hex dump. |
| Type: 2 (ACPI Device Path) |

| Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path) | **Acpi(HID,UID)**  
The HID parameter is an EISAID and is required.  
The UID parameter is an integer and is optional. The default value is zero. |
| Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path) |

| Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path) HID=PNP0A03 | **PciRoot(UID)**  
The UID parameter is an integer. It is optional but required for display. The default value is zero. |
| Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path) HID=PNP0A03 |

| Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path) HID=PNP0A08 | **PcieRoot(UID)**  
The UID parameter is an integer. It is optional but required for display. The default value is zero. |
| Type: 2 (ACPI Device Path) SubType: 1 (ACPI Device Path) HID=PNP0A08 |

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Table 10.64 – continued from previous page

<table>
<thead>
<tr>
<th>Type: 2 (ACPI Device Path)</th>
<th>Floppy(UID)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 1 (ACPI Device Path) HID=PNP0604</td>
<td>The UID parameter is an integer. It is optional for input but required for display. The default value is zero.</td>
</tr>
<tr>
<td>Type: 2 (ACPI Device Path)</td>
<td>Keyboard(UID)</td>
</tr>
<tr>
<td>SubType: 1 (ACPI Device Path) HID=PNP0301</td>
<td>The UID parameter is an integer. It is optional for input but required for display. The default value is 0.</td>
</tr>
<tr>
<td>Type: 2 (ACPI Device Path)</td>
<td>Serial(UID)</td>
</tr>
<tr>
<td>SubType: 1 (ACPI Device Path) HID=PNP0501</td>
<td>The UID parameter is an integer. It is optional for input but required for display. The default value is 0.</td>
</tr>
<tr>
<td>Type: 2 (ACPI Device Path)</td>
<td>ParallelPort(UID)</td>
</tr>
<tr>
<td>SubType: 1 (ACPI Device Path) HID=PNP0401</td>
<td>The UID parameter is an integer. It is optional for input but required for display. The default value is 0.</td>
</tr>
<tr>
<td>Type: 2 (ACPI Device Path)</td>
<td>AcpiEx( HID,CID,UID,HIDSTR,CIDSTR,UIDSTR)</td>
</tr>
<tr>
<td>SubType: 2 (ACPI Expanded Device Path)</td>
<td>AcpiEx(HID ,(CID Only)</td>
</tr>
<tr>
<td></td>
<td>The HID parameter is an EISAID. The default value is 0. Either HID or HIDSTR must be present.</td>
</tr>
<tr>
<td></td>
<td>The CID parameter is an EISAID. The default value is 0. Either CID must be 0 or CIDSTR must be empty.</td>
</tr>
<tr>
<td></td>
<td>The UID parameter is an integer. The default value is 0. Either UID must be 0 or UIDSTR must be empty.</td>
</tr>
<tr>
<td></td>
<td>The HIDSTR is a string. The default value is the empty string. Either HID or HIDSTR must be present.</td>
</tr>
<tr>
<td></td>
<td>The CIDSTR is a string. The default value is an empty string. Either CID must be 0 or CIDSTR must be empty.</td>
</tr>
<tr>
<td></td>
<td>The UIDSTR is a string. The default value is an empty string. Either UID must be 0 or UIDSTR must be empty.</td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>Type: 2 (ACPI Device Path)</th>
<th>AcpiExp(HID,CID,UIDSTR)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 2 (ACPI Expanded Device Path)</td>
<td>The HID parameter is an EISAID. It is required. The CID parameter is an EISAID. It is optional and has a default value of 0. The UIDSTR parameter is a string. If UID is 0 and UIDSTR is empty, then use AcpiEx format.</td>
</tr>
<tr>
<td>HIDSTR=empty</td>
<td></td>
</tr>
<tr>
<td>CIDSTR=empty</td>
<td></td>
</tr>
<tr>
<td>UID STR!=empty</td>
<td></td>
</tr>
</tbody>
</table>

| Type: 2 (ACPI Device Path) | PciRoot(UID|UIDSTR) (Display Only) |
|----------------------------|----------------------------------|
| SubType: 2 (ACPI Expanded Device Path) | |
| HID=PNP0A03 or CID=PNP0A03 and HID != PNP0A08. | |

| Type: 2 (ACPI Device Path) | PcieRoot(UID|UIDSTR) (Display Only) |
|----------------------------|----------------------------------|
| SubType: 2 (ACPI Expanded Device Path) | |
| HID=PNP0A08 or CID=PNP0A08. | |

<table>
<thead>
<tr>
<th>Type: 2 (ACPI Device Path)</th>
<th>AcpiAdr(DisplayDevice[, DisplayDevice...])</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 3 (ACPI ADR Device Path)</td>
<td>The DisplayDevice parameter is an Integer. There may be one or more, separated by a comma.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 MessagingPath (when subtype is not recognized)</th>
<th>Msg(subtype, data)</th>
</tr>
</thead>
<tbody>
<tr>
<td>The subtype is an integer from 0-255. The data is a hex dump.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>Ata (Controller,Drive,LUN)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 1 (ATAPI)</td>
<td>The Controller is either an integer with a value of 0 or 1 or else the keyword Primary (0) or Secondary (1). It is required. The Drive is either an integer with the value of 0 or 1 or else the keyword Master (0) or Slave (1). It is required. The LUN is a 16-bit integer. It is required.</td>
</tr>
</tbody>
</table>

continues on next page
Table 10.64 – continued from previous page

| Type: 3 (Messaging Device Path) SubType: 2 (SCSI) | **Scsi** (*PUN,LUN*) |
| Type: 3 (Messaging Device Path) SubType: 3 (Fibre Channel) | **Fibre** (WWN,LUN) |
| Type: 3 (Messaging Device Path) SubType: 21 (Fibre Channel Ex) | **FibreEx** (WWN,LUN) |
| Type: 3 (Messaging Device Path) SubType: 4 (1394) | **1394** (*GUID*) |
| Type: 3 (Messaging Device Path) SubType: 5 (USB) | **USB** (*Port,Interface*) |
| Type: 3 (Messaging Device Path) SubType: 6 (I2O) | **I2O** (*TID*) |
| Type: 3 (Messaging Device Path) SubType: 9 (Infiniband) | **Infiniband** (*Flags, Guid, ServiceId, TargetId, DeviceId*) |
| Type: 3 (Messaging Device Path) SubType: 10 (Vendor) | VenMsg(Guid, Data) |

The *PUN* is an integer between 0 and 65535 and is required. The *LUN* is an integer between 0 and 65535 and is required.

The WWN is a 64-bit unsigned integer and is required. The LUN is a 64-bit unsigned integer and is required.

The WWN is an 8 byte array that is displayed in hexadecimal format with byte 0 first (i.e., on the left) and byte 7 last (i.e., on the right), and is required. The LUN is an 8 byte array that is displayed in hexadecimal format with byte 0 first (i.e., on the left) and byte 7 last (i.e., on the right), and is required.

The *GUID* is a GUID and is required.

The *Port* is an integer between 0 and 255 and is required. The *Interface* is an integer between 0 and 255 and is required.

The TID is an integer and is required.

*Flags* is an integer. *Guid* is a guid. *ServiceId*, *TargetId*, and *DeviceId* are 64-bit unsigned integers. All fields are required.

The *Guid* is a GUID and is required. The *Data* is a Hex Dump and is option. The default value is zero bytes.

continues on next page
<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>VenPcAnsi()</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 10 (Vendor)</td>
<td></td>
</tr>
<tr>
<td>GUID= EFI_PC_ANSI_GUID</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>VenVt100()</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 10 (Vendor)</td>
<td></td>
</tr>
<tr>
<td>GUID= EFI_VT_100_GUID</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>VenVt100Plus()</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 10 (Vendor)</td>
<td></td>
</tr>
<tr>
<td>GUID= EFI_VT_100_PLUS_GUID</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>VenUtf8()</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 10 (Vendor)</td>
<td></td>
</tr>
<tr>
<td>GUID= EFI_VT_UTF8_GUID</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UartFlowCtrl (Value)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 10 (Vendor)</td>
<td></td>
</tr>
<tr>
<td>GUID=DEVDICE_PATH_MESSAGING_UART_FLOW_CONTROL</td>
<td>The Value is either an integer with the value 0, 1 or 2 or the keywords XonXoff (2) or Hardware (1) or None (0).</td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path) SubType: 10 (Serial Attached SCSI) Vendor GUID: d487ddb4-008b-11d9-afdc-001083ffca4d</th>
<th><strong>SAS</strong> (<em>Address, LUN, RTP, SASSATA, Location, Connect, DriveBay, Reserved</em>)</th>
</tr>
</thead>
<tbody>
<tr>
<td>The Address is a 64-bit unsigned integer representing the SAS Address and is required.</td>
<td>The LUN is a 64-bit unsigned integer representing the Logical Unit Number and is optional. The default value is 0. The RTP is a 16-bit unsigned integer representing the Relative Target Port and is optional. The default value is 0. The SASSATA is a keyword SAS or SATA or NoTopology or an unsigned 16-bit integer and is optional. The default is NoTopology. If NoTopology or an integer are specified, then Location, Connect and DriveBay are prohibited. If SAS or SATA is specified, then Location and Connect are required, but DriveBay is optional. If an integer is specified, then the topology information is filled with the integer value. The Location is an integer between 0 and 1 or else the keyword Internal (0) or External (1) and is optional. If SASSATA is an integer or NoTopology, it is prohibited. The default value is 0. The Connect is an integer between 0 and 3 or else the keyword Direct (0) or Expanded (1) and is optional. If SASSATA is an integer or NoTopology, it is prohibited. The default value is 0. The DriveBay is an integer between 1 and 256 and is optional unless SASSATA is an integer or NoTopology, in which case it is prohibited. The Reserved field is an integer and is optional. The default value is 0.</td>
</tr>
<tr>
<td>DebugPort()</td>
<td></td>
</tr>
<tr>
<td>Type: 3 (Messaging Device Path) SubType: 11 (MAC Address) GUID=EFI_DEBUGPORT_PROTOCOL_GUID</td>
<td><strong>MAC</strong>(MacAddr, IfType)</td>
</tr>
<tr>
<td>The MacAddr is a Hex Dump and is required. If IfType is 0 or 1, then the MacAddr must be exactly six bytes. The IfType is an integer from 0-255 and is optional. The default is zero.</td>
<td></td>
</tr>
</tbody>
</table>
### Table 10.64 – continued from previous page

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>IPv4(RemoteIp, Protocol, Type, LocalIp, GatewayIPAddress, SubnetMask) IPv4(RemoteIp) (Display Only)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 12 (IPv4)</td>
<td>The RemoteIp is an IP Address and is required. The Protocol is an integer between 0 and 255 or else the keyword UDP (17) or TCP (6). The default value is UDP. The Type is a keyword, either Static (1) or DHCP (0). It is optional. The default value is DHCP. The LocalIp is an IP Address and is optional. The default value is all zeroes. The GatewayIPAddress is an IP Address and is optional. The default value is all zeroes. The SubnetMask is an IP Address and is optional. The default value is all zeroes.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>IPv6(RemoteIp, Protocol, IPAddressOrigin, LocalIp, GatewayIPAddress, SubnetMask) IPv6(RemoteIp) (Display Only)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 13 (IPv6)</td>
<td>The RemoteIp is an IPv6 Address and is required. The Protocol is an integer between 0 and 255 or else the keyword UDP (17) or TCP (6). The default value is UDP. The IPAddressOrigin is a keyword, could be Static (0), StatelessAutoConfigure (1), or StatefulAutoConfigure (2). The LocalIp is the IPv6 Address and is optional. The default value is all zeroes. The GatewayIPAddress is an IP Address. The PrefixLength is the prefix length of the Local IPv6 Address. The GatewayIPAddress is the IPv6 Address of the Gateway.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>Uart(Baud, DataBits, Parity, StopBits)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 14 (UART)</td>
<td>The Baud is a 64-bit integer and is optional. The default value is 115200. The DataBits is an integer from 0 to 255 and is optional. The default value is 8. The Parity is either an integer from 0-255 or else a keyword and should be D (0), N (1), E (2), O (3), M (4) or S (5). It is optional. The default value is 0. The StopBits is a either an integer from 0-255 or else a keyword and should be D (0), 1 (1), 1.5 (2), 2 (3). It is optional. The default value is 0. Parity and StopBits can either be two integers or two keywords. Mixing formats is prohibited.</td>
</tr>
</tbody>
</table>

Continues on next page
Table 10.64 – continued from previous page

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>SubType: 15 (USB Class)</th>
<th>UsbClass (VID,PID,Class,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The Class is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>SubType: 15 (USB Class)</th>
<th>UsbAudio(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>SubType: 15 (USB Class)</th>
<th>UsbCDControl(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The VID is an optional integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The PID is an optional integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The SubClass is an optional integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The Protocol is an optional integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>SubType: 15 (USB Class)</th>
<th>UsbHID(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbImage(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td>Class 6</td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbPrinter(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td>Class 7</td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbMassStor age(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td>Class 8</td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbHub(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td>Class 9</td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

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### Table 10.64 – continued from previous page

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbC DCData(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td></td>
</tr>
<tr>
<td>Class 10</td>
<td></td>
</tr>
<tr>
<td></td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbSmart(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td></td>
</tr>
<tr>
<td>Class 11</td>
<td></td>
</tr>
<tr>
<td></td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbVideo(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td></td>
</tr>
<tr>
<td>Class 14</td>
<td></td>
</tr>
<tr>
<td></td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbDiagnostic(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td></td>
</tr>
<tr>
<td>Class 220</td>
<td></td>
</tr>
<tr>
<td></td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

*continues on next page*
<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbWireless(VID,PID,SubClass,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td></td>
</tr>
<tr>
<td>Class 224</td>
<td></td>
</tr>
<tr>
<td></td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The SubClass is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbDeviceFirmwareUpdate(VID,PID,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td></td>
</tr>
<tr>
<td>Class 254</td>
<td></td>
</tr>
<tr>
<td>SubClass: 1</td>
<td></td>
</tr>
<tr>
<td></td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbIrdaBridge(VID,PID,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td></td>
</tr>
<tr>
<td>Class 254</td>
<td></td>
</tr>
<tr>
<td>SubClass: 2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>UsbTestAndMeasurement(VID,PID,Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 15 (USB Class)</td>
<td></td>
</tr>
<tr>
<td>Class 254</td>
<td></td>
</tr>
<tr>
<td>SubClass: 3</td>
<td></td>
</tr>
<tr>
<td></td>
<td>The VID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The PID is an integer between 0 and 65535 and is optional. The default value is 0xFFFF.</td>
</tr>
<tr>
<td></td>
<td>The Protocol is an integer between 0 and 255 and is optional. The default value is 0xFF.</td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path) SubType: 16 (USB WWID Class)</th>
<th>UsbWwd(VID,PID,InterfaceNumber,&quot;WWID&quot;)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>The VID is an integer between 0 and 65535 and is required.</td>
</tr>
<tr>
<td></td>
<td>The PID is an integer between 0 and 65535 and is required.</td>
</tr>
<tr>
<td></td>
<td>The InterfaceNumber is an integer between 0 and 255 and is required.</td>
</tr>
<tr>
<td></td>
<td>The WWID is a string and is required.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path) SubType: 17 (Logical Unit Class)</th>
<th>Unit(LUN)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>The LUN is an integer and is required.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path) SubType: 18 (SATA)</th>
<th>Sata(HPN, PMPN, LUN)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>The HPN is an integer between 0 and 65534 and is required.</td>
</tr>
<tr>
<td></td>
<td>The PMPN is an integer between 0 and 65535 and is optional. If not provided, the default is 0xFFFF, which implies no port multiplier.</td>
</tr>
<tr>
<td></td>
<td>The LUN is a 16-bit integer. It is required. Note that LUN is applicable to ATAPI devices only, and most ATAPI devices assume LUN=0</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path) SubType: 19 (iSCSI)</th>
<th>iSCSI(TargetName, PortalGroup, LUN, HeaderDigest, DataDigest, Authentication, Protocol)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>The TargetName is a string and is required.</td>
</tr>
<tr>
<td></td>
<td>PortalGroup is an unsigned 16-bit integer and is required.</td>
</tr>
<tr>
<td></td>
<td>The LUN is an 8 byte array that is displayed in hexadecimal format with byte 0 first (i.e., on the left) and byte 7 last (i.e., on the right), and is required.</td>
</tr>
<tr>
<td></td>
<td>The HeaderDigest is a keyword None or CRC32C is optional. The default is None.</td>
</tr>
<tr>
<td></td>
<td>The DataDigest is a keyword None or CRC32C is optional. The default is None.</td>
</tr>
<tr>
<td></td>
<td>The Authentication is a keyword None or CHAP_BI or CHAP_UNI and optional. The default is None.</td>
</tr>
<tr>
<td></td>
<td>The Protocol defines the network protocol used by iSCSI and is optional. The default is TCP.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path) SubType: 20 (VLAN)</th>
<th>Vlan (VlanId)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>continues on next page</td>
</tr>
<tr>
<td>Type: 3 (Messaging Device Path) SubType: 22 (Serial Attached SCSI Ex)</td>
<td>\textit{SasEx} (Address, LUN, RTP, SASSATA, Location, Connect, DriveBay)</td>
</tr>
<tr>
<td>---</td>
<td>---</td>
</tr>
<tr>
<td></td>
<td>The \textit{Address} is an 8 byte array that is displayed in hexadecimal format with byte 0 first (i.e., on the left) and byte 7 last (i.e., on the right), and is required. The \textit{LUN} is an 8 byte array that is displayed in hexadecimal format with byte 0 first (i.e., on the left) and byte 7 last (i.e., on the right), and is optional. The default value is 0. The \textit{RTP} is a 16-bit unsigned integer representing the Relative Target Port and is optional. The default value is 0. The \textit{SASSATA} is a keyword \textit{SA} S or \textit{SATA} or \textit{NoTopology} or an unsigned 16-bit integer and is optional. The default is \textit{NoTopology}. If \textit{NoTopology} or an integer are specified, then \textit{Location}, \textit{Connect} and \textit{DriveBay} are prohibited. If \textit{SAS} or \textit{SATA} is specified, then \textit{Location} and \textit{Connect} are required, but \textit{DriveBay} is optional. If an integer is specified, then the topology information is filled with the integer value. The \textit{Location} is an integer between 0 and 1 or else the keyword \textit{Internal} (0) or \textit{External} (1) and is optional. If \textit{SASSATA} is an integer or \textit{NoTopology}, it is prohibited. The default value is 0. The \textit{Connect} is an integer between 0 and 3 or else the keyword Direct (0) or Expanded (1) and is optional. If \textit{SASSATA} is an integer or \textit{NoTopology}, it is prohibited. The default value is 0. The \textit{DriveBay} is an integer between 1 and 256 and is optional unless \textit{SASSATA} is an integer or \textit{NoTopology}, in which case it is prohibited.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path) SubType: 23 (NVM Express Namespace)</th>
<th>\textit{NVMe(NSID,EUI)}</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>The \textit{NSID} is a namespace identifier that is displayed in hexadecimal format with an integer value between 0 and 0xFFFFFFFF. The \textit{EUI} is the IEEE Extended Unique Identifier (EUI-64) that is displayed in hexadecimal format represented as a set of octets separated by dashes (hexadecimal notation), e.g., FF-FF-FF-FF-FF-FF-FF.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path) SubType: 24 (URI)</th>
<th>\textit{Uri(Uri)}</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>The \textit{Uri} is optional.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path) SubType: 25 (Universal Flash Storage)</th>
<th>\textit{UFS} (PUN,LUN)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>The \textit{PUN} is 0 for current UFS2.0 spec. For future UFS specs which support multiple devices on a UFS port, it would reflect the device ID on the UFS port. The \textit{LUN} is 0-7 for common LUNs or 81h, D0h, B0h and C4h for well-known LUNs supported by UFS.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path) SubType: 26 (SD)</th>
<th>\textit{SD} (Slot Number)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>\textit{SlotNumber} is an integer. It is optional and has a default value of 0.</td>
</tr>
</tbody>
</table>
### Table 10.64 – continued from previous page

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>Bluetooth(BD_ADDR)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 27 (Bluetooth)</td>
<td><em>BD_ADDR</em> is HEX dump of 48-bit Bluetooth device address.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>Wi-Fi (SSID)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 28 (Wi-Fi)</td>
<td>The <em>SSID</em> is a string and is required.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>eMMC (SlotNumber)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 29 (eMMC)</td>
<td>SlotNumber is an integer. It is optional and has a default value of 0.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>BluetoothLE(BD_ADDR, AddressType)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 30 (BluetoothLE)</td>
<td>BD_ADDR is HEX dump of 48-bit Bluetooth device address. AddressType is an integer.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>Dns(DnsServerIp[, DnsServerIp…])</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 31 (DNS)</td>
<td>DnsServerIp is optional. It is the IP address of DNS server.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>RestService(RestExServiceType, AccessMode)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 32 (NVDIMM Service)</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 3 (Messaging Device Path)</th>
<th>RestService(RestExServiceType, AccessMode)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 33 (REST Service)</td>
<td>For vendor-specific REST service: RestService(RestExServiceType, AccessMode, VendorRestServiceGuid, VendorDefinedData) RestExServiceType is 0xff in this case.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 4 (Media Device Path)</th>
<th>MediaPath(subtype, data)</th>
</tr>
</thead>
<tbody>
<tr>
<td>(when subtype is not recognized)</td>
<td>The subtype is an integer from 0-255 and is required. The data is a hex dump.</td>
</tr>
</tbody>
</table>
| Type: 4 (Media Device Path) | H D(Partition,Type,Signature,Start, Size)  
|                           | HD(Partition,Type,Signature) (Display Only) |
|                           | The Partition is an integer representing the partition number. It is optional and the default is 0. If Partition is 0, then Start and Size are prohibited. The Type is an integer between 0-255 or else the keyword MBR (1) or GPT (2). The type is optional and the default is 2. Signature is an integer if Type is 1 or else GUID if Type is 2. The signature is required. The Start is a 64-bit unsigned integer. It is prohibited if Partition is 0. Otherwise it is required. The Size is a 64-bit unsigned integer. It is prohibited if Partition is 0. Otherwise it is required. |
| SubType: 1 (Hard Drive)   | |
| Type: 4 (Media Device Path) | CDROM(Entry,Start,Size)  
|                           | CDROM(Entry) (Display Only) |
|                           | The Entry is an integer representing the Boot Entry from the Boot Catalog. It is optional and the default is 0. The Start is a 64-bit integer and is required. The Size is a 64-bit integer and is required. |
| SubType: 2 (CD-ROM)       | |
| Type: 4 (Media | Device Path) | VenMedia(GUID, Data) |
|                           | The Guid is a GUID and is required. | The Data is a Hex Dump and is option. The default value is zero bytes. |
| SubType: 3 (Vendor)       | |
| Type: 4 (Media Device Path) | String |
|                           | The String is the file path and is a string. |
| SubType: 4 (File Path)    | |
| Type: 4 (Media Device Path) | Media(Guid) |
|                           | The Guid is a GUID and is required. |
| SubType: 5 (Media Protocol) | |
| Type: 4 (Media Device Path) | Contents are defined in the UEFI PI Specification. |
| SubType: 6 (PIWG Firmware File) | |

continues on next page
<table>
<thead>
<tr>
<th>Type: 4 (Media Device Path)</th>
<th>Contents are defined in the UEFI PI Specification.</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 7 (PIWG Firmware Volume)</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 4 (Media Device Path)</th>
<th>Offset (StartingOffset,EndingOffset)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 8 (Relative Offset Range)</td>
<td>The StartingOffset is an unsigned 64-bit integer. The EndingOffset is an unsigned 64-bit integer.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 4 (Media Device Path)</th>
<th>RamDisk (StartingAddress,EndingAddress,DiskInstance,DiskTypeGuid)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 9 (RAM Disk)</td>
<td>The StartingAddress and EndingAddress are both 64-bit integers and are both required. The DiskInstance is a 16-bit integer and is optional. The default value is 0. The DiskTypeGuid is a GUID and is required.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 4 (Media Device Path)</th>
<th>VirtualDisk StartingAddress,EndingAddress,DiskInstance</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 9 (RAM Disk)</td>
<td>The StartingAddress and EndingAddress are both 64-bit integers and are both required. The DiskInstance is a 16-bit integer and is optional. The default value is 0.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 4 (Media Device Path)</th>
<th>VirtualCD (StartingAddress,EndingAddress,DiskInstance)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 9 (RAM Disk)</td>
<td>The StartingAddress and EndingAddress are both 64-bit integers and are both required. The DiskInstance is a 16-bit integer and is optional. The default value is 0.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 4 (Media Device Path)</th>
<th>PersistentVirtualDisk (StartingAddress,EndingAddress,DiskInstance)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 9 (RAM Disk)</td>
<td>The StartingAddress and EndingAddress are both 64-bit integers and are both required. The DiskInstance is a 16-bit integer and is optional. The default value is 0.</td>
</tr>
</tbody>
</table>

continues on next page
Table 10.64 – continued from previous page

<table>
<thead>
<tr>
<th>Type: 4 (Media Device Path)</th>
<th>PersistentVirtualCD (StartingAddress, EndingAddress, DiskInstance)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 9 (RAM Disk)</td>
<td>The StartingAddress and EndingAddress are both 64-bit integers and are both required.</td>
</tr>
<tr>
<td>Disk Type GUID=</td>
<td>The DiskInstance is a 16-bit integer and is optional. The default value is 0.</td>
</tr>
<tr>
<td>EFI_PERSISTENT_VIRTUAL_CD_GUID</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 5 (Media Device Path)</th>
<th>BbsPath(subtype, data)</th>
</tr>
</thead>
<tbody>
<tr>
<td>(when subtype is not recognized)</td>
<td>The subtype is an integer from 0-255.</td>
</tr>
<tr>
<td></td>
<td>The data is a hex dump.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Type: 5 (BIOS Boot Specification Device Path)</th>
<th>BBS(Type,Id,Flags)</th>
</tr>
</thead>
<tbody>
<tr>
<td>SubType: 1 (BBS 1.01)</td>
<td>BBS(Type, Id) (Display Only)</td>
</tr>
<tr>
<td></td>
<td>The Type is an integer from 0-65535 or else one of the following keywords: Floppy (1), HD (2), CDROM (3), PCMCIA (4), USB (5), Network (6). It is required.</td>
</tr>
<tr>
<td></td>
<td>The Id is a string and is required.</td>
</tr>
<tr>
<td></td>
<td>The Flags are an integer and are optional. The default value is 0.</td>
</tr>
</tbody>
</table>

### 10.6.2 Device Path to Text Protocol

#### 10.6.2.1 EFI_DEVICE_PATH_TO_TEXT_PROTOCOL

**Summary**

Convert device nodes and paths to text.

**GUID**

```c
#define EFI_DEVICE_PATH_TO_TEXT_PROTOCOL_GUID \
  {0x8b843e20,0x8132,0x4852,\ 
   {0x90,0xcc,0x55,0x1a,0x4e,0x4a,0x7f,0x1c}}
```

**Protocol Interface Structure**

```c
typedef struct _EFI_DEVICE_PATH_TO_TEXT_PROTOCOL {
  EFI_DEVICE_PATH_TO_TEXT_NODE ConvertDeviceNodeToText;
  EFI_DEVICE_PATH_TO_TEXT_PATH ConvertDevicePathToText;
} EFI_DEVICE_PATH_TO_TEXT_PROTOCOL;
```

**Parameters**

ConvertDeviceNodeToText
- Converts a device node to text.
ConvertDevicePathToText

Converts a device path to text.

Description

The EFI_DEVICE_PATH_TO_TEXT_PROTOCOL provides common utility functions for converting device nodes and device paths to a text representation.

10.6.3 EFI_DEVICE_PATH_TO_TEXT_PROTOCOL.ConvertDeviceNodeToText()

Summary

Convert a device node to its text representation.

Prototype

typedef
CHAR16*
(EFIAPI *EFI_DEVICE_PATH_TO_TEXT_NODE) (
    IN CONST EFI_DEVICE_PATH_PROTOCOL* DeviceNode,
    IN BOOLEAN DisplayOnly,
    IN BOOLEAN AllowShortcuts
);

Parameters

DeviceNode

Points to the device node to be converted.

DisplayOnly

If DisplayOnly is TRUE, then the shorter text representation of the display node is used, where applicable. If DisplayOnly is FALSE, then the longer text representation of the display node is used.

AllowShortcuts

If AllowShortcuts is TRUE, then the shortcut forms of text representation for a device node can be used, where applicable.

Description

The ConvertDeviceNodeToText function converts a device node to its text representation and copies it into a newly allocated buffer.

The DisplayOnly parameter controls whether the longer (parseable) or shorter (display-only) form of the conversion is used.

The AllowShortcuts is FALSE, then the shortcut forms of text representation for a device node cannot be used. A shortcut form is one which uses information other than the type or subtype.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in EFI Device Path Protocol

Returns

This function returns the pointer to the allocated text representation of the device node data or else NULL if DeviceNode was NULL or there was insufficient memory.
10.6.4 EFI_DEVICE_PATH_TO_TEXT_PROTOCOL.ConvertDevicePathToText()

Summary
Convert a device path to its text representation.

Prototype

```c
typedef CHAR16* (EFIAPI *EFI_DEVICE_PATH_TO_TEXT_PATH) (
    IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePath,
    IN BOOLEAN DisplayOnly,
    IN BOOLEAN AllowShortcuts
);
```

Parameters

**DeviceNode**
Points to the device path to be converted.

**DisplayOnly**
If `DisplayOnly` is `TRUE`, then the shorter text representation of the display node is used, where applicable. If `DisplayOnly` is `FALSE`, then the longer text representation of the display node is used.

**AllowShortcuts**
The `AllowShortcuts` is `FALSE`, then the shortcut forms of text representation for a device node cannot be used.

Description
This function converts a device path into its text representation and copies it into an allocated buffer.

The `DisplayOnly` parameter controls whether the longer (parseable) or shorter (display-only) form of the conversion is used.

The `AllowShortcuts` is `FALSE`, then the shortcut forms of text representation for a device node cannot be used. A shortcut form is one which uses information other than the type or subtype.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions
EFI_DEVICE_PATH_PROTOCOL* is defined in *EFI Device Path Protocol*.

Returns
This function returns a pointer to the allocated text representation of the device node or `NULL` if `DevicePath` was `NULL` or there was insufficient memory.

10.6.5 Device Path from Text Protocol

10.6.5.1 EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL

Summary
Convert text to device paths and device nodes.

GUID
#define EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL_GUID \  {0x5c99a21,0xc70f,0x4ad2,\  {0x8a,0x5f,0x35,0xdf,0x33,0x43,0xf5, 0x1e}}

Protocol Interface Structure

typedef struct _EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL {
  EFI_DEVICE_PATH_FROM_TEXT_NODE ConvertTextToDeviceNode;
  EFI_DEVICE_PATH_FROM_TEXT_PATH ConvertTextToDevicePath;
} EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL;

Parameters

ConvertTextToDeviceNode
  Converts text to a device node.

ConvertTextToDevicePath
  Converts text to a device path.

Description

The EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL provides common utilities for converting text to device paths and device nodes.

10.6.5.2 EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL.ConvertTextToDeviceNode()

Summary

Convert text to the binary representation of a device node.

Prototype

typedef EFI_DEVICE_PATH_PROTOCOL*  
(EFIAPI *EFI_DEVICE_PATH_FROM_TEXT_NODE) ( 
  IN CONST CHAR16* TextDeviceNode 
); 

Parameters

TextDeviceNode
  TextDeviceNode points to the text representation of a device node. Conversion starts with the first character and continues until the first non-device node character.

Description

This function converts text to its binary device node representation and copies it into an allocated buffer.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

EFI_DEVICE_PATH_PROTOCOL is defined in EFI Device Path Protocol.

Returns

This function returns a pointer to the EFI device node or NULL if TextDeviceNode is NULL or there was insufficient memory.
10.6.5.3 EFI_DEVICE_PATH_FROM_TEXT_PROTOCOL.ConvertTextToDevicePath()

Summary
Convert a text to its binary device path representation.

Prototype

```c
typedef
EFI_DEVICE_PATH_PROTOCOL*
(EFIAPI *EFI_DEVICE_PATH_FROM_TEXT_PATH) (
    IN CONST CHAR16* TextDevicePath
);
```

Parameters

**TextDevicePath**

*TextDevicePath* points to the text representation of a device path. Conversion starts with the first character and continues until the first non-device path character.

Description

This function converts text to its binary device path representation and copies it into an allocated buffer.

The memory is allocated from EFI boot services memory. It is the responsibility of the caller to free the memory allocated.

Related Definitions

*EFI_DEVICE_PATH_PROTOCOL* is defined in *EFI Device Path Protocol*.

Returns

This function returns a pointer to the allocated device path or NULL if *TextDevicePath* is NULL or there was insufficient memory.
EFI drivers that follow the UEFI Driver Model are not allowed to search for controllers to manage. When a specific controller is needed, the EFI boot service `EFI_BOOT_SERVICES.ConnectController()` is used along with the `EFI Driver Binding Protocol` services to identify the best drivers for a controller. Once `ConnectController()` has identified the best drivers for a controller, the start service in the `EFI_DRIVER_BINDING_PROTOCOL` is used by `ConnectController()` to start each driver on the controller. Once a controller is no longer needed, it can be released with the EFI boot service `EFI_BOOT_SERVICES.DisconnectController()` . `DisconnectController()` calls the stop service in each `EFI_DRIVER_BINDING_PROTOCOL` to stop the controller.

The driver initialization routine of an UEFI driver is not allowed to touch any device hardware. Instead, it just installs an instance of the `EFI_DRIVER_BINDING_PROTOCOL` on the ImageHandle of the UEFI driver. The test to determine if a driver supports a given controller must be performed in as little time as possible without causing any side effects on any of the controllers it is testing. As a result, most of the controller initialization code is present in the start and stop services of the `EFI_DRIVER_BINDING_PROTOCOL`.

### 11.1 EFI Driver Binding Protocol

This section provides a detailed description of the `EFI_DRIVER_BINDING_PROTOCOL` . This protocol is produced by every driver that follows the UEFI Driver Model, and it is the central component that allows drivers and controllers to be managed. It provides a service to test if a specific controller is supported by a driver, a service to start managing a controller, and a service to stop managing a controller. These services apply equally to drivers for both bus controllers and device controllers.

#### 11.1.1 EFI_DRIVER_BINDING_PROTOCOL

**Summary**

Provides the services required to determine if a driver supports a given controller. If a controller is supported, then it also provides routines to start and stop the controller.

**GUID**

```
#define EFI_DRIVER_BINDING_PROTOCOL_GUID
\{0x18A031AB,0xB443,0x4D1A,\}
\{0xA5,0xC0,0x0C,0x09,0x26,0x1E,0x9F,0x71}\}
```

**Protocol Interface Structure**

```
typedef struct _EFI_DRIVER_BINDING_PROTOCOL {    
    EFI_DRIVER_BINDING_PROTOCOL_SUPPORTED Supported;
    EFI_DRIVER_BINDING_PROTOCOL_START    Start;
} ...
```
Parameters

Supported
Tests to see if this driver supports a given controller. This service is called by the EFI boot service EFI_BOOT_SERVICES.ConnectController(). In order to make drivers as small as possible, there are a few calling restrictions for this service. ConnectController() must follow these calling restrictions. If any other agent wishes to call EFI_DRIVER_BINDING_PROTOCOL.Supported() it must also follow these calling restrictions. See the Supported() function description.

Start
Starts a controller using this driver. This service is called by the EFI boot service ConnectController(). In order to make drivers as small as possible, there are a few calling restrictions for this service. ConnectController() must follow these calling restrictions. If any other agent wishes to call EFI_DRIVER_BINDING_PROTOCOL.Start() it must also follow these calling restrictions. See the Start() function description.

Stop
Stops a controller using this driver. This service is called by the EFI boot service EFI_BOOT_SERVICES.DisconnectController(). In order to make drivers as small as possible, there are a few calling restrictions for this service. DisconnectController() must follow these calling restrictions. If any other agent wishes to call EFI_DRIVER_BINDING_PROTOCOL.Stop() it must also follow these calling restrictions. See the Stop() function description.

Version
The version number of the UEFI driver that produced the EFI_DRIVER_BINDING_PROTOCOL. This field is used by the EFI boot service ConnectController() to determine the order that driver’s Supported() service will be used when a controller needs to be started. EFI Driver Binding Protocol instances with higher Version values will be used before ones with lower Version values. The Version values of 0x0-0x0f and 0xffffffff-0xfffffff0 are reserved for platform/OEM specific drivers. The Version values of 0x10-0xffffffef are reserved for IHV-developed drivers.

ImageHandle
The image handle of the UEFI driver that produced this instance of the EFI_DRIVER_BINDING_PROTOCOL.

DriverBindingHandle
The handle on which this instance of the EFI_DRIVER_BINDING_PROTOCOL is installed. In most cases, this is the same handle as ImageHandle. However, for UEFI drivers that produce more than one instance of the EFI_DRIVER_BINDING_PROTOCOL, this value may not be the same as ImageHandle.

Description
The EFI_DRIVER_BINDING_PROTOCOL provides a service to determine if a driver supports a given controller. If a controller is supported, then it also provides services to start and stop the controller. All UEFI drivers are required to be reentrant so they can manage one or more controllers. This requires that drivers not use global variables to store device context. Instead, they must allocate a separate context structure per controller that the driver is managing. Bus drivers must support starting and stopping the same bus multiple times, and they must also support starting and stopping all of their children, or just a subset of their children.

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11.1.2 EFI_DRIVER_BINDING_PROTOCOL.Supported()

Summary
Tests to see if this driver supports a given controller. If a child device is provided, it further tests to see if this driver supports creating a handle for the specified child device.

Prototype

typedef
EFI_STATUS
(EFI_API *EFI_DRIVER_BINDING_PROTOCOL_SUPPORTED) (  
IN EFI_DRIVER_BINDING_PROTOCOL *This,  
IN EFI_HANDLE ControllerHandle,  
IN EFI_DEVICE_PATH_PROTOCOL *RemainingDevicePath OPTIONAL  
);

Parameters
This
A pointer to the EFI Driver Binding Protocol instance.

ControllerHandle
The handle of the controller to test. This handle must support a protocol interface that supplies an I/O abstraction to the driver. Sometimes just the presence of this I/O abstraction is enough for the driver to determine if it supports ControllerHandle. Sometimes, the driver may use the services of the I/O abstraction to determine if this driver supports ControllerHandle.

RemainingDevicePath
A pointer to the remaining portion of a device path. For bus drivers, if this parameter is not NULL, then the bus driver must determine if the bus controller specified by ControllerHandle and the child controller specified by RemainingDevicePath are both supported by this bus driver.

Description
This function checks to see if the driver specified by This supports the device specified by ControllerHandle. Drivers will typically use the device path attached to ControllerHandle and/or the services from the bus I/O abstraction attached to ControllerHandle to determine if the driver supports ControllerHandle. This function may be called many times during platform initialization. In order to reduce boot times, the tests performed by this function must be very small, and take as little time as possible to execute. This function must not change the state of any hardware devices, and this function must be aware that the device specified by ControllerHandle may already be managed by the same driver or a different driver. This function must match its calls to EFI_BOOT_SERVICES.AllocatePages() with EFI_BOOT_SERVICES.FreePages(), EFI_BOOT_SERVICES.AllocatePool() with EFI_BOOT_SERVICES.FreePool(), and EFI_BOOT_SERVICES.OpenProtocol() with EFI_BOOT_SERVICES.CloseProtocol(). Since ControllerHandle may have been previously started by the same driver, if a protocol is already in the opened state, then it must not be closed with CloseProtocol(). This is required to guarantee the state of ControllerHandle is not modified by this function.

If any of the protocol interfaces on the device specified by ControllerHandle that are required by the driver specified by This are already open for exclusive access by a different driver or application, then EFI_ACCESS_DENIED is returned.

If any of the protocol interfaces on the device specified by ControllerHandle that are required by the driver specified by This are already open by the same driver, then EFI_ALREADY_STARTED is returned. However, if the driver specified by This is a bus driver, then it is not an error, and the bus driver should continue with its test of ControllerHandle and RemainingDevicePath. This allows a bus driver to create one child handle on the first call to EFI_DRIVER_BINDING_PROTOCOL.Supported() and EFI_DRIVER_BINDING_PROTOCOL.Start(), and create additional child handles on additional calls to Supported() and Start().
handle on the first call to Supported() and Start() by specifying an End of Device Path Node RemainingDevicePath, and create additional child handles on additional calls to Supported() and Start().

If ControllerHandle is not supported by This, then EFI_UNSUPPORTED is returned.

If This is a bus driver that creates child handles with an EFI Device Path Protocol, then ControllerHandle must support the EFI_DEVICE_PATH_PROTOCOL. If it does not, then EFI_UNSUPPORTED is returned.

If ControllerHandle is supported by This, and This is a device driver, then EFI_SUCCESS is returned.

If ControllerHandle is supported by This, and This is a bus driver, and RemainingDevicePath is NULL or the first Device Path Node is the End of Device Path Node, then EFI_SUCCESS is returned.

If ControllerHandle is supported by This, and This is a bus driver, and RemainingDevicePath is not NULL, then RemainingDevicePath must be analyzed. If the first node of RemainingDevicePath is the End of Device Path Node or an EFI Device Path node that the bus driver recognizes and supports, then EFI_SUCCESS is returned. Otherwise, EFI_UNSUPPORTED is returned.

The Supported() function is designed to be invoked from the EFI boot service EFI_BOOT_SERVICES.ConnectController(). As a result, much of the error checking on the parameters to Supported() has been moved into this common boot service. It is legal to call Supported() from other locations, but the following calling restrictions must be followed or the system behavior will not be deterministic.

ControllerHandle must be a valid EFI_HANDLE. If RemainingDevicePath is not NULL, then it must be a pointer to a naturally aligned EFI_DEVICE_PATH_PROTOCOL.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device specified by ControllerHandle and RemainingDevicePath is supported by the driver specified by This.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The device specified by ControllerHandle and RemainingDevicePath is already being managed by the driver specified by This.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The device specified by ControllerHandle and RemainingDevicePath is already being managed by a different driver or an application that requires exclusive access.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The device specified by ControllerHandle and RemainingDevicePath is not supported by the driver specified by This.</td>
</tr>
</tbody>
</table>

**Examples**

```c
extern EFI_GUID gEfiDriverBindingProtocolGuid;
EFI_HANDLE DriverImageHandle;
EFI_HANDLE ControllerHandle;
EFI_DRIVER_BINDING_PROTOCOL *DriverBinding;
EFI_DEVICE_PATH_PROTOCOL *RemainingDevicePath;

// Use the DriverImageHandle to get the Driver Binding protocol instance
//
// Status = gBS->OpenProtocol (    
// DriverImageHandle,    
// &gEfiDriverBindingProtocolGuid,    
// &DriverBinding,    
// DriverImageHandle,    
// NULL,    
// EFI_OPEN_PROTOCOL_GET_PROTOCOL    
// );
```

(continues on next page)
if (EFI_ERROR (Status)) {
    return Status;
}

// EXAMPLE #1
//
// Use the Driver Binding Protocol instance to test to see if the
// driver specified by DriverImageHandle supports the controller
// specified by ControllerHandle
/
Status = DriverBinding->Supported (  
    DriverBinding,  
    ControllerHandle,  
    NULL  
);  
return Status;

// EXAMPLE #2
//
// The RemainingDevicePath parameter can be used to initialize only
// the minimum devices required to boot. For example, maybe we only
// want to initialize 1 hard disk on a SCSI channel. If DriverImageHandle
// is a SCSI Bus Driver, and ControllerHandle is a SCSI Controller, and
// we only want to create a child handle for PUN=3 and LUN=0, then the
// RemainingDevicePath would be SCSI(3,0)/END. The following example
// would return EFI_SUCCESS if the SCSI driver supports creating the
// child handle for PUN=3, LUN=0. Otherwise it would return an error.
/
Status = DriverBinding->Supported ( 
    DriverBinding, 
    ControllerHandle, 
    RemainingDevicePath 
);  
return Status;

Pseudo Code

Listed below are the algorithms for the EFI_DRIVER_BINDING_PROTOCOL.Supported() function for three different types of drivers. How the EFI_DRIVER_BINDING_PROTOCOL.Start() function of a driver is implemented can affect how the Supported() function is implemented. All of the services in the EFI Driver Binding Protocol need to work together to make sure that all resources opened or allocated in Supported() and Start() are released in EFI_DRIVER_BINDING_PROTOCOL.Stop()

The first algorithm is a simple device driver that does not create any additional handles. It only attaches one or more protocols to an existing handle. The second is a bus driver that always creates all of its child handles on the first call to Start(). The third is a more advanced bus driver that can either create one child handle at a time on successive calls to Start(), or it can create all of its child handles or all of the remaining child handles in a single call to Start().

Device Driver:

1. Ignore the parameter RemainingDevicePath.

2. Open all required protocols with EFI_BOOT_SERVICES.OpenProtocol(). A standard driver should use an
Attribute of `EFI_OPEN_PROTOCOL_BY_DRIVER`. If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an Attribute of `EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE`.

3. If any of the calls to `OpenProtocol()` in (2) returned an error, then close all of the protocols opened in (2) with `EFI_BOOT_SERVICES.CloseProtocol()`, and return the status code from the call to `OpenProtocol()` that returned an error.

4. Use the protocol instances opened in (2) to test to see if this driver supports the controller. Sometimes, just the presence of the protocols is enough of a test. Other times, the services of the protocols opened in (2) are used to further check the identity of the controller. If any of these tests fails, then close all the protocols opened in (2) with `CloseProtocol()` and return `EFI_UNSUPPORTED`.

5. Close all protocols opened in (2) with `CloseProtocol()`.

6. Return `EFI_SUCCESS`.

**Bus Driver that creates all of its child handles on the first call to Start():**

1. Check the contents of the first Device Path Node of `RemainingDevicePath` to make sure it is the End of Device Path Node or a legal Device Path Node for this bus driver’s children. If it is not, then return `EFI_UNSUPPORTED`.

2. Open all required protocols with `EFI_BOOT_SERVICES.OpenProtocol()`. A standard driver should use an Attribute of `EFI_OPEN_PROTOCOL_BY_DRIVER`. If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an Attribute of `EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE`.

3. If any of the calls to `OpenProtocol()` in (2) returned an error, then close all of the protocols opened in (2) with `EFI_BOOT_SERVICES.CloseProtocol()`, and return the status code from the call to `OpenProtocol()` that returned an error.

4. Use the protocol instances opened in (2) to test to see if this driver supports the controller. Sometimes, just the presence of the protocols is enough of a test. Other times, the services of the protocols opened in (2) are used to further check the identity of the controller. If any of these tests fails, then close all the protocols opened in (2) with `CloseProtocol()` and return `EFI_UNSUPPORTED`.

5. Close all protocols opened in (2) with `CloseProtocol()`.

6. Return `EFI_SUCCESS`.

**Bus Driver that is able to create all or one of its child handles on each call to Start():**

1. Check the contents of the first Device Path Node of `RemainingDevicePath` to make sure it is the End of Device Path Node or a legal Device Path Node for this bus driver’s children. If it is not, then return `EFI_UNSUPPORTED`.

2. Open all required protocols with `OpenProtocol()`. A standard driver should use an Attribute of `EFI_OPEN_PROTOCOL_BY_DRIVER`. If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an Attribute of `EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE`.

3. If any of the calls to `OpenProtocol()` in (2) failed with an error other than `EFI_ALREADY_STARTED`, then close all of the protocols opened in (2) that did not return `EFI_ALREADY_STARTED` with `CloseProtocol()`, and return the status code from the `OpenProtocol()` call that returned an error.

4. Use the protocol instances opened in (2) to test to see if this driver supports the controller. Sometimes, just the presence of the protocols is enough of a test. Other times, the services of the protocols opened in (2) are used to further check the identity of the controller. If any of these tests fails, then close all the protocols opened in (2) that did not return `EFI_ALREADY_STARTED` with `CloseProtocol()` and return `EFI_UNSUPPORTED`.

5. Close all protocols opened in (2) that did not return `EFI_ALREADY_STARTED` with `CloseProtocol()`.

6. Return `EFI_SUCCESS`.

11.1. EFI Driver Binding Protocol
Listed below is sample code of the `EFI_DRIVER_BINDING_PROTOCOL.Supported()` function of device driver for a device on the XYZ bus. The XYZ bus is abstracted with the `EFI_XYZ_IO_PROTOCOL`. Just the presence of the `EFI_XYZ_IO_PROTOCOL` on ControllerHandle is enough to determine if this driver supports ControllerHandle. The `gBS` variable is initialized in this driver's entry point.:ref:`efi-system-table`.

```c
extern EFI_GUID gEfiXyzIoProtocol;
EFI_BOOT_SERVICES *gBS;

EFI_STATUS
AbcSupported ( 
    IN EFI_DRIVER_BINDING_PROTOCOL *This,
    IN EFI_HANDLE ControllerHandle,
    IN EFI_DEVICE_PATH_PROTOCOL *RemainingDevicePath OPTIONAL)
{
    EFI_STATUS Status;
    EFI_XYZ_IO_PROTOCOL *XyzIo;

    Status = gBS->OpenProtocol ( 
        ControllerHandle, 
        &gEfiXyzIoProtocol, 
        &XyzIo, 
        This->DriverBindingHandle, 
        ControllerHandle, 
        EFI_OPEN_PROTOCOL_BY_DRIVER 
    );
    if (EFI_ERROR (Status)) {
        return Status;
    }

    gBS->CloseProtocol ( 
        ControllerHandle, 
        &gEfiXyzIoProtocol, 
        This->DriverBindingHandle, 
        ControllerHandle 
    );

    return EFI_SUCCESS;
}
```

### 11.1.3 EFI_DRIVER_BINDING_PROTOCOL.Start()

**Summary**

Starts a device controller or a bus controller. The `Start()` and efi-driver-binding-protocol-stop-protocols-uefi-driver-model mirror each other.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI *EFI_DRIVER_BINDING_PROTOCOL_START) ( 
(continues on next page)
```
Parameters

This

A pointer to the EFI_DRIVER_BINDING_PROTOCOL instance.

ControllerHandle

The handle of the controller to start. This handle must support a protocol interface that supplies an I/O abstraction to the driver.

RemainingDevicePath

A pointer to the remaining portion of a device path. For a bus driver, if this parameter is NULL, then handles for all the children of Controller are created by this driver.

If this parameter is not NULL and the first Device Path Node is not the End of Device Path Node, then only the handle for the child device specified by the first Device Path Node of RemainingDevicePath is created by this driver.

If the first Device Path Node of RemainingDevicePath is the End of Device Path Node, no child handle is created by this driver.

Description

This function starts the device specified by Controller with the driver specified by This. Whatever resources are allocated in Start() must be freed in Stop(). For example, every EFI_BOOT_SERVICES.AllocatePool(), EFI_BOOT_SERVICES.AllocatePages(), EFI_BOOT_SERVICES.OpenProtocol(), and EFI_BOOT_SERVICES.InstallProtocolInterface() in Start() must be matched with a EFI_BOOT_SERVICES.FreePool(), EFI_BOOT_SERVICES.FreePages(), EFI_BOOT_SERVICES.CloseProtocol(), and EFI_BOOT_SERVICES.UninstallProtocolInterface() in Stop().

If Controller is started, then EFI_SUCCESS is returned.

If Controller could not be started, but can potentially be repaired with configuration or repair operations using the EFI_DRIVER_HEALTH_PROTOCOL and this driver produced an instance of the EFI_DRIVER_HEALTH_PROTOCOL for Controller, then return EFI_SUCCESS.

If Controller cannot be started due to a device error and the driver does not produce the EFI_DRIVER_HEALTH_PROTOCOL for Controller, then return EFI_DEVICE_ERROR.

If the driver does not support Controller then EFI_DEVICE_ERROR is returned. This condition will only be met if Supported() returns EFI_SUCCESS and a more extensive supported check in Start() fails.

If there are not enough resources to start the device or bus specified by Controller, then EFI_OUT_OF_RESOURCES is returned.

If the driver specified by This is a device driver, then RemainingDevicePath is ignored.

If the driver specified by This is a bus driver, and RemainingDevicePath is NULL, then all of the children of Controller are discovered and enumerated, and a device handle is created for each child.

If the driver specified by This is a bus driver, and RemainingDevicePath is not NULL and begins with the End of Device Path node, then the driver must not enumerate any of the children of Controller nor create any child device handle. Only the controller initialization should be performed. If the driver implements EFI_DRIVER_DIAGNOSTICS2_PROTOCOL, EFI_COMPONENT_NAME2_PROTOCOL, EFI_SERVICE_BINDING_PROTOCOL, EFI_DRIVER_FAMILY_OVERRIDE_PROTOCOL, or...
If the driver specified by This is a bus driver that is capable of creating one child handle at a time and RemainingDevicePath is not NULL and does not begin with the End of Device Path node, then an attempt is made to create the device handle for the child device specified by RemainingDevicePath. Depending on the bus type, all of the child devices may need to be discovered and enumerated, but at most only the device handle for the one child specified by RemainingDevicePath shall be created.

The Start() function is designed to be invoked from the EFI boot service EFI_BOOT_SERVICES.ConnectController(). As a result, much of the error checking on the parameters to Start() has been moved into this common boot service. It is legal to call Start() from other locations, but the following calling restrictions must be followed or the system behavior will not be deterministic:

- ControllerHandle must be a valid EFI_HANDLE.
- If RemainingDevicePath is not NULL, then it must be a pointer to a naturally aligned EFI_DEVICE_PATH_PROTOCOL.
- Prior to calling Start(), EFI_DRIVER_BINDING_PROTOCOL.Supported() function for the driver specified by This must have been called with the same calling parameters, and Supported() must have returned EFI_SUCCESS.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device was started.</td>
</tr>
<tr>
<td>EFI_SUCCESS</td>
<td>The device could not be started because the device needs to be configured</td>
</tr>
<tr>
<td></td>
<td>by the user or requires a repair operation, and the driver produced the</td>
</tr>
<tr>
<td></td>
<td>Driver Health Protocol that will return the required configuration and repair</td>
</tr>
<tr>
<td></td>
<td>operations for this device.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The driver does not produce the Driver Health Protocol and the device could</td>
</tr>
<tr>
<td></td>
<td>not be started due to a device error.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The driver produces the Driver Health Protocol, and the driver does not</td>
</tr>
<tr>
<td></td>
<td>support the device.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

Examples

```c
extern EFI_GUID gEfiDriverBindingProtocolGuid;
EFI_HANDLE DriverImageHandle;
EFI_HANDLE ControllerHandle;
EFI_DRIVER_BINDING_PROTOCOL *DriverBinding;
EFI_DEVICE_PATH_PROTOCOL *RemainingDevicePath;

// Use the DriverImageHandle to get the Driver Binding Protocol instance
//
Status = gBS->OpenProtocol (
    DriverImageHandle,
    &gEfiDriverBindingProtocolGuid,
    &DriverBinding,
    DriverImageHandle,
    NULL,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL);
```

(continues on next page)
if (EFI_ERROR (Status)) {
    return Status;
}

// EXAMPLE #1
// Use the Driver Binding Protocol instance to test to see if the
driver specified by DriverImageHandle supports the controller
// specified by ControllerHandle
// Status = DriverBinding->Supported (
        DriverBinding,
        ControllerHandle,
        NULL
    );
if (!EFI_ERROR (Status)) {
    Status = DriverBinding->Start (
        DriverBinding,
        ControllerHandle,
        NULL
    );
}
return Status;

// EXAMPLE #2
// The RemainingDevicePath parameter can be used to initialize only
// the minimum devices required to boot. For example, maybe we only
// want to initialize 1 hard disk on a SCSI channel. If DriverImageHandle
// is a SCSI Bus Driver, and ControllerHandle is a SCSI Controller, and
// we only want to create a child handle for PUN=3 and LUN=0, then the
// RemainingDevicePath would be SCSI(3,0)/END. The following example
// would return EFI_SUCCESS if the SCSI driver supports creating the
// child handle for PUN=3, LUN=0. Otherwise it would return an error.
// Status = DriverBinding->Supported (
        DriverBinding,
        ControllerHandle,
        RemainingDevicePath
    );
if (!EFI_ERROR (Status)) {
    Status = DriverBinding->Start (
        DriverBinding,
        ControllerHandle,
        RemainingDevicePath
    );
}
return Status;

Pseudo Code
Listed below are the algorithms for the `EFI_DRIVER_BINDING_PROTOCOL.Supported()` function for three different types of drivers. How the `EFI_DRIVER_BINDING_PROTOCOL.Start()` function of a driver is implemented can affect how the `EFI_DRIVER_BINDING_PROTOCOL.Supported()` function is implemented. All of the services in the EFI Driver Binding Protocol need to work together to make sure that all resources opened or allocated in `Supported()` and `Start()` are released in `EFI_DRIVER_BINDING_PROTOCOL.Stop()`.

The first algorithm is a simple device driver that does not create any additional handles. It only attaches one or more protocols to an existing handle. The second is a simple bus driver that always creates all of its child handles on the first call to `Start()`. It does not attach any additional protocols to the handle for the bus controller. The third is a more advanced bus driver that can either create one child handles at a time on successive calls to `Start()`, or it can create all of its child handles or all of the remaining child handles in a single call to `Start()`. Once again, it does not attach any additional protocols to the handle for the bus controller.

**Device Driver:**

1. Ignore the parameter `RemainingDevicePath` ..

2. Open all required protocols with `EFI_BOOT_SERVICES.OpenProtocol()` . A standard driver should use an Attribute of `EFI_OPEN_PROTOCOL_BY_DRIVER` . If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an Attribute of `EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE` . It must use the same Attribute value that was used in `Supported()`.

3. If any of the calls to `OpenProtocol()` in (2) returned an error, then close all of the protocols opened in (2) with `EFI_BOOT_SERVICES.CloseProtocol()` , and return the status code from the call to `OpenProtocol()` that returned an error.

4. Initialize the device specified by `ControllerHandle` . If the driver does not support the device specified by `ControllerHandle` , then close all of the protocols opened in (2) with `CloseProtocol()` , and return `EFI_DEVICE_ERROR` . If the driver does support the device specified by `ControllerHandle` and an error is detected, and that error can not be resolved with the `EFI_DRIVER_HEALTH_PROTOCOL` , then close all of the protocols opened in (2) with `CloseProtocol()` , and return `EFI_DEVICE_ERROR` . If the driver does support the device specified by `ControllerHandle` and an error is detected, and that error can be resolved with the `EFI_DRIVER_HEALTH_PROTOCOL` , then produce the `EFI_DRIVER_HEALTH_PROTOCOL` for `ControllerHandle` and make sure `EFI_SUCCESS` is returned from `Start()` . In this case, depending on the type of error detected, not all of the following steps may be completed

5. Allocate and initialize all of the data structures that this driver requires to manage the device specified by `ControllerHandle` . This would include space for public protocols and space for any additional private data structures that are related to `ControllerHandle` . If an error occurs allocating the resources, then close all of the protocols opened in (2) with `CloseProtocol()` , and return `EFI_OUT_OF_RESOURCES`.

6. Install all the new protocol interfaces onto `ControllerHandle` using `EFI_BOOT_SERVICES.InstallMultipleProtocolInterfaces()` . If an error occurs, close all of the protocols opened in (1) with `CloseProtocol()` , and return the error from `InstallMultipleProtocolInterfaces()`.

7. Return `EFI_SUCCESS`.

**Bus Driver that creates all of its child handles on the first call to Start():**

1. Ignore the parameter `RemainingDevicePath` with the exception that if the first Device Path Node is the End of Device Path Node, skip steps 5-8.

2. Open all required protocols with `EFI_BOOT_SERVICES.OpenProtocol()` . A standard driver should use an Attribute of `EFI_OPEN_PROTOCOL_BY_DRIVER` . If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an Attribute of `EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE` . It must use the same Attribute value that was used in `Supported()` `EFI_DRIVER_BINDING_PROTOCOL.Supported()`.
3. If any of the calls to `OpenProtocol()` in (2) returned an error, then close all of the protocols opened in (2) with `EFI_BOOT_SERVICES.CloseProtocol()` , and return the status code from the call to `OpenProtocol()` that returned an error.

4. Initialize the device specified by `ControllerHandle` . If the driver does not support the device specified by `ControllerHandle` , then close all of the protocols opened in (2) with `CloseProtocol()` , and return `EFI_DEVICE_ERROR` . If the driver does support the device specified by `ControllerHandle` and an error is detected, and that error cannot be resolved with the `EFI_DRIVER_HEALTH_PROTOCOL` , then close all of the protocols opened in (2) with `CloseProtocol()` , and return `EFI_DEVICE_ERROR` . If the driver does support the device specified by `ControllerHandle` and an error is detected, and that error can be resolved with the `EFI_DRIVER_HEALTH_PROTOCOL` , then produce the `EFI_DRIVER_HEALTH_PROTOCOL` for `ControllerHandle` and make sure `EFI_SUCCESS` is returned from `Start()` . In this case, depending on the type of error detected, not all of the following steps may be completed.

5. Discover all the child devices of the bus controllers specified by `ControllerHandle` .

6. If the bus requires it, allocate resources to all the child devices of the bus controller specified by `ControllerHandle` .

7. FOR each child C of `ControllerHandle`:
   - Allocate and initialize all of the data structures that this driver requires to manage the child device C. This would include space for public protocols and space for any additional private data structures that are related to the child device C. If an error occurs allocating the resources, then close all of the protocols opened in (2) with `CloseProtocol()` , and return `EFI_OUT_OF_RESOURCES` .
   - If the bus driver creates device paths for the child devices, then create a device path for the child C based upon the device path attached to `ControllerHandle` .
   - Initialize the child device C. If an error occurs, close all of the protocols opened in (2) with `CloseProtocol()` , and return `EFI_DEVICE_ERROR` .
   - Create a new handle for C, and install the protocol interfaces for child device C using `EFI_BOOT_SERVICES.InstallMultipleProtocolInterfaces()` . This may include the `EFI Device Path Protocol` .
   - Call `OpenProtocol()` on behalf of the child C with an `Attribute` of `EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER` .

8. END FOR

9. If the bus driver also produces protocols on `ControllerHandle` , then install all the new protocol interfaces onto `ControllerHandle` using `InstallMultipleProtocolInterfaces()` . If an error occurs, close all of the protocols opened in (2) with `CloseProtocol()` , and return the error from `InstallMultipleProtocolInterfaces()` .

10. Return `EFI_SUCCESS` .

**Bus Driver that is able to create all or one of its child handles on each call to `Start()`:**

1. Open all required protocols with `EFI_BOOT_SERVICES.OpenProtocol()` . A standard driver should use an `Attribute` of `EFI_OPEN_PROTOCOL_BY_DRIVER` . If this driver needs exclusive access to a protocol interface, and it requires any drivers that may be using the protocol interface to disconnect, then the driver should use an `Attribute` of `EFI_OPEN_PROTOCOL_BY_DRIVER | EFI_OPEN_PROTOCOL_EXCLUSIVE` . It must use the same `Attribute` value that was used in `Supported()` `EFI_DRIVER_BINDING_PROTOCOL` `Supported()` .

2. If any of the calls to `OpenProtocol()` in (1) returned an error, then close all of the protocols opened in (1) with `EFI_BOOT_SERVICES.CloseProtocol()` , and return the status code from the call to `OpenProtocol()` that returned an error.

3. Initialize the device specified by `ControllerHandle` . If the driver does not support the device specified by `ControllerHandle` , then close all of the protocols opened in (1) with `CloseProtocol()` , and return `EFI_DEVICE_ERROR` . If the driver does support the device specified by `ControllerHandle` and an error is detected, and that error cannot be resolved with the `EFI_DRIVER_HEALTH_PROTOCOL` , then close all of
the protocols opened in (1) with CloseProtocol(), and return EFI_DEVICE_ERROR. If the driver does support the device specified by ControllerHandle and an error is detected, and that error can be resolved with the EFI_DRIVER_HEALTH_PROTOCOL, then produce the EFI_DRIVER_HEALTH_PROTOCOL for ControllerHandle and make sure EFI_SUCCESS is returned from Start(). In this case, depending on the type of error detected, not all of the following steps may be completed.

4. IF RemainingDevicePath is not NULL, THEN
   a – C is the child device specified by RemainingDevicePath. If the first Device Path Node is the End of Device Path Node, proceed to step 6.
   b – Allocate and initialize all of the data structures that this driver requires to manage the child device C. This would include space for public protocols and space for any additional private data structures that are related to the child device C. If an error occurs allocating the resources, then close all of the protocols opened in (1) with CloseProtocol(), and return EFI_OUT_OF_RESOURCES.
   c – If the bus driver creates device paths for the child devices, then create a device path for the child C based upon the device path attached to ControllerHandle.
   d – Initialize the child device C.
   e – Create a new handle for C, and install the protocol interfaces for child device C using EFI_BOOT_SERVICES.InstallMultipleProtocolInterfaces(). This may include the EFI Device Path Protocol.
   f – Call OpenProtocol() on behalf of the child C with an Attribute of EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER.
ELSE
   a – Discover all the child devices of the bus controller specified by ControllerHandle.
   b – If the bus requires it, allocate resources to all the child devices of the bus controller specified by ControllerHandle.
   c – FOR each child C of ControllerHandle
      Allocate and initialize all of the data structures that this driver requires to manage the child device C. This would include space for public protocols and space for any additional private data structures that are related to the child device C. If an error occurs allocating the resources, then close all of the protocols opened in (1) with CloseProtocol(), and return EFI_OUT_OF_RESOURCES.
      If the bus driver creates device paths for the child devices, then create a device path for the child C based upon the device path attached to ControllerHandle.
      Initialize the child device C.
      Create a new handle for C, and install the protocol interfaces for child device C using InstallMultipleProtocolInterfaces(). This may include the EFI_DEVICE_PATH_PROTOCOL.
      Call EFI_BOOT_SERVICES.OpenProtocol() on behalf of the child C with an Attribute of EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER.
   d – END FOR
5. END IF

6. If the bus driver also produces protocols on ControllerHandle, then install all the new protocol interfaces onto ControllerHandle using InstallMultipleProtocolInterfaces(). If an error occurs, close all of the protocols opened in (2) with CloseProtocol(), and return the error from InstallMultipleProtocolInterfaces().

7. Return EFI_SUCCESS.
Listed below is sample code of the `EFI_DRIVER_BINDING_PROTOCOL.Start()` function of a device driver for a device on the XYZ bus. The XYZ bus is abstracted with the `EFI_XYZ_IO_PROTOCOL`. This driver does allow the `EFI_XYZ_IO_PROTOCOL` to be shared with other drivers, and just the presence of the `EFI_XYZ_IO_PROTOCOL` on ControllerHandle is enough to determine if this driver supports ControllerHandle. This driver installs the `EFI_ABC_IO_PROTOCOL` on ControllerHandle. The `gBS` variable is initialized in this driver’s entry point as shown in the UEFI Driver Model examples in `UEFI Driver Model`.

```c
extern EFI_GUID gEfiXyzIoProtocol;
extern EFI_GUID gEfiAbcIoProtocol;
EFI_BOOT_SERVICES *gBS;

EFI_STATUS AbcStart (
    IN EFI_DRIVER_BINDING_PROTOCOL *This,
    IN EFI_HANDLE ControllerHandle,
    IN EFI_DEVICE_PATH_PROTOCOL *RemainingDevicePath OPTIONAL
) {
    EFI_STATUS Status;
    EFI_XYZ_IO_PROTOCOL *XyzIo;
    EFI_ABC_DEVICE AbcDevice;

    // Open the Xyz I/O Protocol that this driver consumes
    Status = gBS->OpenProtocol (
        ControllerHandle,
        &gEfiXyzIoProtocol,
        &XyzIo,
        This->DriverBindingHandle,
        ControllerHandle,
        EFI_OPEN_PROTOCOL_BY_DRIVER
    );
    if (EFI_ERROR (Status)) {
        return Status;
    }

    // Allocate and zero a private data structure for the Abc device.
    Status = gBS->AllocatePool (EfiBootServicesData,
        sizeof (EFI_ABC_DEVICE),
        &AbcDevice
    );
    if (EFI_ERROR (Status)) {
        goto ErrorExit;
    }
    ZeroMem (AbcDevice, sizeof (EFI_ABC_DEVICE));

    // Initialize the contents of the private data structure for the Abc device.
    // (continues on next page)
}
```

11.1. EFI Driver Binding Protocol
// This includes the XyzIo protocol instance and other private data fields
// and the EFI_ABC_IO_PROTOCOL instance that will be installed.

AbcDevice->Signature = EFI_ABC_DEVICE_SIGNATURE;
AbcDevice->XyzIo = XyzIo;

AbcDevice->PrivateData1 = PrivateValue1;
AbcDevice->PrivateData2 = PrivateValue2;
...
AbcDevice->PrivateDataN = PrivateValueN;

AbcDevice->AbcIo.Revision = EFI_ABC_IO_PROTOCOL_REVISION;
AbcDevice->AbcIo.Func1 = AbcIoFunc1;
AbcDevice->AbcIo.Func2 = AbcIoFunc2;
...
AbcDevice->AbcIo.FuncN = AbcIoFuncN;

AbcDevice->AbcIo.Data1 = Value1;
AbcDevice->AbcIo.Data2 = Value2;
...
AbcDevice->AbcIo.DataN = ValueN;

// Install protocol interfaces for the ABC I/O device.

Status = gBS->InstallMultipleProtocolInterfaces (
    &ControllerHandle,
    &gEfiAbcIoProtocolGuid, &AbcDevice->AbcIo,
    NULL
);
if (EFI_ERROR (Status)) {
    goto ErrorExit;
}

return EFI_SUCCESS;

ErrorExit:

    // When there is an error, the private data structures need to be freed and
    // the protocols that were opened need to be closed.

    if (AbcDevice != NULL) {
        gBS->FreePool (AbcDevice);
    }
    gBS->CloseProtocol (          
        ControllerHandle,          
        &gEfiXyzIoProtocolGuid,          
        This->DriverBindingHandle,          
        ControllerHandle          
    );
    return Status;
}
### 11.1.4 EFI_DRIVER_BINDING_PROTOCOL.Stop()

#### Summary

Stops a device controller or a bus controller. The `EFI_DRIVER_BINDING_PROTOCOL.Start()` and `Stop()` services of the `EFI_DRIVER_BINDING_PROTOCOL.Start()` and `Stop()` mirror each other.

#### Prototype

```c
typedef EFI_STATUS
(CONVEXITY *EFI_DRIVER_BINDING_PROTOCOL_STOP) (
    IN EFI_DRIVER_BINDING_PROTOCOL *This,
    IN EFI_HANDLE ControllerHandle,
    IN UINTN NumberOfChildren,
    IN EFI_HANDLE *ChildHandleBuffer OPTIONAL
);
```

#### Parameters

**This**

A pointer to the `EFI_DRIVER_BINDING_PROTOCOL` instance. Type `EFI_DRIVER_BINDING_PROTOCOL` is defined in *EFI Driver Binding Protocol*.

**ControllerHandle**

A handle to the device being stopped. The handle must support a bus specific I/O protocol for the driver to use to stop the device.

**NumberOfChildren**

The number of child device handles in ChildHandleBuffer.

**ChildHandleBuffer**

An array of child handles to be freed. May be NULL if NumberOfChildren is 0.

#### Description

This function performs different operations depending on the parameter NumberOfChildren. If NumberOfChildren is not zero, then the driver specified by This is a bus driver, and it is being requested to free one or more of its child handles specified by NumberOfChildren and ChildHandleBuffer. If all of the child handles are freed, then `EFI_SUCCESS` is returned. If NumberOfChildren is zero, then the driver specified by This is either a device driver or a bus driver, and it is being requested to stop the controller specified by ControllerHandle. If ControllerHandle is stopped, then `EFI_SUCCESS` is returned. In either case, this function is required to undo what was performed in `Start()`. Whatever resources are allocated in `Start()` must be freed in `Stop()`. For example, every `EFI_BOOT_SERVICES.AllocatePool()`, `EFI_BOOT_SERVICES.AllocatePages()`, `EFI_BOOT_SERVICES.OpenProtocol()`, and `EFI_BOOT_SERVICES.InstallProtocolInterface()` in `Start()` must be matched with a `EFI_BOOT_SERVICES.FreePool()`, `EFI_BOOT_SERVICES.FreePages()`, `EFI_BOOT_SERVICES.CloseProtocol()`, and `EFI_BOOT_SERVICES.UninstallProtocolInterface()` in `Stop()`.

If ControllerHandle cannot be stopped, then `EFI_DEVICE_ERROR` is returned. If, for some reason, there are not enough resources to stop ControllerHandle, then `EFI_OUT_OF_RESOURCES` is returned.

The `Stop()` function is designed to be invoked from the EFI boot service `EFI_BOOT_SERVICES.DisconnectController()`. As a result, much of the error checking on the parameters to `Stop()` has been moved into this common boot service. It is legal to call `Stop()` from other locations, but the following calling restrictions must be followed or the system behavior will not be deterministic.

- `ControllerHandle` must be a valid `EFI_HANDLE` that was used on a previous call to this same driver's `EFI_DRIVER_BINDING_PROTOCOL.Start()` function.
• The first `NumberOfChildren` handles of `ChildHandleBuffer` must all be a valid `EFI_HANDLE`. In addition, all of these handles must have been created in this driver’s `Start()` function, and the `Start()` function must have called `EFI_BOOT_SERVICES.OpenProtocol()` on `ControllerHandle` with an Attribute of `EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER`.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code> EFI_SUCCESS</code></td>
<td>The device was stopped.</td>
</tr>
<tr>
<td><code>EFI_DEVICE_ERROR</code></td>
<td>The device could not be stopped due to a device error.</td>
</tr>
</tbody>
</table>

### Examples

```c
extern EFI_GUID gEfiDriverBindingProtocolGuid;
EFI_HANDLE DriverImageHandle;
EFI_HANDLE ControllerHandle;
EFI_HANDLE ChildHandle;
EFI_DRIVER_BINDING_PROTOCOL *DriverBinding;

// Use the DriverImageHandle to get the Driver Binding Protocol instance
Status = gBS->OpenProtocol (
    DriverImageHandle,
    &gEfiDriverBindingProtocolGuid,
    &DriverBinding,
    DriverImageHandle,
    NULL,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL
);
if (EFI_ERROR (Status)) {
    return Status;
}

// Use the Driver Binding Protocol instance to free the child
// specified by ChildHandle. Then, use the Driver Binding
// Protocol to stop ControllerHandle.
Status = DriverBinding->Stop (
    DriverBinding,
    ControllerHandle,
    1,
    &ChildHandle
);
Status = DriverBinding->Stop (
    DriverBinding,
    ControllerHandle,
    0,
    NULL
);
```

### Pseudo Code

**Device Driver:**

11.1. `EFI Driver Binding Protocol` 348
1. Uninstall all the protocols that were installed onto ControllerHandle in EFI_DRIVER_BINDING_PROTOCOL.Start().

2. Close all the protocols that were opened on behalf of ControllerHandle in Start().

3. Free all the structures that were allocated on behalf of ControllerHandle in Start().

4. Return EFI_SUCCESS.

**Bus Driver that creates all of its child handles on the first call to Start():**

**Bus Driver that is able to create all or one of its child handles on each call to Start():**

1. IF NumberOfChildren is zero THEN:
   • Uninstall all the protocols that were installed onto ControllerHandle in Start().
   • Close all the protocols that were opened on behalf of ControllerHandle in Start().
   • Free all the structures that were allocated on behalf of ControllerHandle in Start().

2. ELSE
   • FOR each child C in ChildHandleBuffer: Uninstall all the protocols that were installed onto C in Start(). Close all the protocols that were opened on behalf of C in Start(). Free all the structures that were allocated on behalf of C in Start().
   • END FOR

3. END IF

4. Return EFI_SUCCESS.

Listed below is sample code of the EFI_DRIVER_BINDING_PROTOCOL.Stop() function of a device driver for a device on the XYZ bus. The XYZ bus is abstracted with the EFI_XYZ_IO_PROTOCOL. This driver does allow the EFI_XYZ_IO_PROTOCOL to be shared with other drivers, and just the presence of the EFI_XYZ_IO_PROTOCOL on ControllerHandle is enough to determine if this driver supports ControllerHandle. This driver installs the EFI_ABC_IO_PROTOCOL on ControllerHandle in EFI_DRIVER_BINDING_PROTOCOL.Start(). The gBS variable is initialized in this driver’s entry point:ref:efi-system-table_efi_system_table . extern EFI_GUID
gEfiXyzIoProtocol;
gEfiAbcIoProtocol;
*gBS;

EFI_STATUS
AbcStop (  
   IN EFI_DRIVER_BINDING_PROTOCOL *This,  
   IN EFI_HANDLE ControllerHandle  
   IN UINTN NumberOfChildren,  
   IN EFI_HANDLE *ChildHandleBuffer OPTIONAL
)  
{
   EFI_STATUS Status;
   EFI_ABC_IO AbcIo;
   EFI_ABC_DEVICE AbcDevice;

   // Get our context back
   //
   Status = gBS->OpenProtocol (  
   
(continues on next page)
ControllerHandle,
&gEfiAbcIoProtocolGuid,
&AbcIo,
This->DriverBindingHandle,
ControllerHandle,
EFI_OPEN_PROTOCOL_GET_PROTOCOL
);
if (EFI_ERROR (Status)) {
    return EFI_UNSUPPORTED;
}

// Use Containment Record Macro to get AbcDevice structure from
// a pointer to the AbcIo structure within the AbcDevice structure.
//
AbcDevice = ABC_IO_PRIVATE_DATA_FROM_THIS (AbcIo);

// Uninstall the protocol installed in Start()
//
Status = gBS->UninstallMultipleProtocolInterfaces (
    ControllerHandle,
    &gEfiAbcIoProtocolGuid, &AbcDevice->AbcIo,
    NULL
);
if (!EFI_ERROR (Status)) {
    // Close the protocol opened in Start()
    //
    Status = gBS->CloseProtocol (
        ControllerHandle,
        &gEfiXyzIoProtocolGuid, This->DriverBindingHandle,
    ControllerHandle
    );

    // Free the structure allocated in Start().
    //
    gBS->FreePool (AbcDevice);
}
return Status;
11.2 EFI Platform Driver Override Protocol

This section provides a detailed description of the EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL. This protocol can override the default algorithm for matching drivers to controllers.

EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL

Summary

This protocol matches one or more drivers to a controller. A platform driver produces this protocol, and it is installed on a separate handle. This protocol is used by the EFI_BOOT_SERVICES.ConnectController() boot service to select the best driver for a controller. All of the drivers returned by this protocol have a higher precedence than drivers found from an EFI Bus Specific Driver Override Protocol or drivers found from the general UEFI driver Binding search algorithm. If more than one driver is returned by this protocol, then the drivers are returned in order from highest precedence to lowest precedence.

GUID

```c
#define EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL_GUID
{0x6b30c738,0xa391,0x11d4,0x9a3b,0x00,0x90,0x27,0x3f,0xc1,0x4d}
```

Protocol Interface Structure

```c
typedef struct _EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL {
    EFI_PLATFORM_DRIVER_OVERRIDE_GET_DRIVER GetDriver;
    EFI_PLATFORM_DRIVER_OVERRIDE_GET_DRIVER_PATH GetDriverPath;
    EFI_PLATFORM_DRIVER_OVERRIDE_DRIVER_LOADED DriverLoaded;
} EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL;
```

Parameters

GetDriver

- Retrieves the image handle of a platform override driver for a controller in the system. See the EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.GetDriver() function description.

GetDriverPath

- Retrieves the device path of a platform override driver for a controller in the system. See the GetDriverPath() EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.GetDriverPath() function description.

DriverLoaded

- This function is used after a driver has been loaded using a device path returned by EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.GetDriverPath(). This function associates a device path to an image handle, so the image handle can be returned the next time that GetDriver() is called for the same controller. See the DriverLoaded() EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.DriverLoaded() function description.

Description

The EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL is used by the EFI boot service EFI_BOOT_SERVICES.ConnectController() to determine if there is a platform specific driver override for a controller that is about to be started. The bus drivers in a platform will use a bus defined matching algorithm for matching drivers to controllers. This protocol allows the platform to override the bus driver’s default driver matching algorithm. This protocol can be used to specify the drivers for on-board devices whose drivers may be in a system ROM not directly associated with the on-board controller, or it can even be used to manage the matching of drivers and controllers in add-in cards. This can be very useful if there are two adapters that are identical except for the revision of the driver in the adapter’s ROM. This protocol, along with a platform configuration utility, could specify which of the two drivers to use for each of the adapters.
The drivers that this protocol returns can be either in the form of an image handle or a device path. `EFI_BOOT_SERVICES.ConnectController()` can only use image handles, so `ConnectController()` is required to use the `EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.GetDriver()` service. A different component, such as the Boot Manager, will have to use the `GetDriverPath()` service to retrieve the list of drivers that need to be loaded from I/O devices. Once a driver has been loaded and started, this same component can use the `DriverLoaded()` service to associate the device path of a driver with the image handle of the loaded driver. Once this association has been established, the image handle can then be returned by the `GetDriver()` service the next time it is called by `ConnectController()`.

### 11.2.1 EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.GetDriver()

**Summary**

Retrieves the image handle of the platform override driver for a controller in the system.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_PLATFORM_DRIVER_OVERRIDE_GET_DRIVER) (
    IN EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL *This,
    IN EFI_HANDLE ControllerHandle,
    IN OUT EFI_HANDLE *DriverImageHandle
);
```

**Parameters**

**This**

A pointer to the `EFI Platform Driver Override Protocol` instance.

**ControllerHandle**

The device handle of the controller to check if a driver override exists.

**DriverImageHandle**

On input, a pointer to the previous driver image handle returned by `GetDriver()`. On output, a pointer to the next driver image handle. Passing in a NULL, will return the first driver image handle for `ControllerHandle`.

**Description**

This function is used to retrieve a driver image handle that is selected in a platform specific manner. The first driver image handle is retrieved by passing in a DriverImageHandle value of `NULL`. This will cause the first driver image handle to be returned in DriverImageHandle. On each successive call, the previous value of DriverImageHandle must be passed in. If a call to this function returns a valid driver image handle, then `EFI_SUCCESS` is returned. This process is repeated until `EFI_NOT_FOUND` is returned. If a DriverImageHandle is passed in that was not returned on a prior call to this function, then `EFI_INVALID_PARAMETER` is returned. If ControllerHandle is `NULL`, then `EFI_INVALID_PARAMETER` is returned. The first driver image handle has the highest precedence, and the last driver image handle has the lowest precedence. This ordered list of driver image handles is used by the boot service `EFI_BOOT_SERVICES.ConnectController()` to search for the best driver for a controller.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The driver override for ControllerHandle was returned in DriverImageHandle.</td>
</tr>
<tr>
<td><code>EFI_NOT_FOUND</code></td>
<td>A driver override for ControllerHandle was not found.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>The handle specified by ControllerHandle is not a valid handle.</td>
</tr>
</tbody>
</table>

continues on next page
Table 11.4 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DriverImageHandle is not a handle that was returned on a previous call to GetDriver().</td>
</tr>
</tbody>
</table>

11.2.2 EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.GetDriverPath()

Summary

Retrieves the device path of the platform override driver for a controller in the system.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_PLATFORM_DRIVER_OVERRIDE_GET_DRIVER_PATH) (  
    IN EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL *This,  
    IN EFI_HANDLE ControllerHandle,  
    IN OUT EFI_DEVICE_PATH_PROTOCOL **DriverImagePath
);
```

Parameters

This

A pointer to the `EFI Platform Driver Override Protocol` instance.

ControllerHandle

The device handle of the controller to check if a driver override exists.

DriverImagePath

On input, a pointer to the previous driver device path returned by GetDriverPath(). On output, a pointer to the next driver device path. Passing in a pointer to NULL, will return the first driver device path for `ControllerHandle`.

Description

This function is used to retrieve a driver device path that is selected in a platform specific manner. The first driver device path is retrieved by passing in a DriverImagePath value that is a pointer to `NULL`. This will cause the first driver device path to be returned in DriverImagePath. On each successive call, the previous value of DriverImagePath must be passed in. If a call to this function returns a valid driver device path, then `EFI_SUCCESS` is returned. This process is repeated until `EFI_NOT_FOUND` is returned. If a DriverImagePath is passed in that was not returned on a prior call to this function, then `EFI_INVALID_PARAMETER` is returned. If ControllerHandle is `NULL`, then `EFI_INVALID_PARAMETER` is returned. The first driver device path has the highest precedence, and the last driver device path has the lowest precedence. This ordered list of driver device paths is used by a platform specific component, such as the EFI Boot Manager, to load and start the platform override drivers by using the EFI boot services `EFI_BOOT_SERVICES.LoadImage()` and `EFI_BOOT_SERVICES.StartImage()` . Each time one of these drivers is loaded and started, the DriverLoaded() `EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.DriverLoaded()` service is called.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The driver override for ControllerHandle was returned in DriverImagePath.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The operation is not supported.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>A driver override for ControllerHandle was not found.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The handle specified by ControllerHandle is not a valid handle.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DriverImagePath is not a device path that was returned on a previous call to GetDriverPath().</td>
</tr>
</tbody>
</table>
11.2.3 EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.DriverLoaded()

Summary

Used to associate a driver image handle with a device path that was returned on a prior call to the GetDriverPath()
EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.GetDriverPath() service. This driver image handle will then
be available through the EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.GetDriver() service.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_PLATFORM_DRIVER_OVERRIDE_DRIVER_LOADED) (  
    IN EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL *This,  
    IN EFI_HANDLE ControllerHandle,  
    IN EFI_DEVICE_PATH_PROTOCOL *DriverImagePath,  
    IN EFI_HANDLE DriverImageHandle
);

Parameters

This

A pointer to the EFI Platform Driver Override Protocol instance.

ControllerHandle

The device handle of a controller. This must match the controller handle that was used in a prior call to Get-
Driver() to retrieve DriverImagePath.

DriverImagePath

A pointer to the driver device path that was returned in a prior call to GetDriverPath().

DriverImageHandle

The driver image handle that was returned by EFI_BOOT_SERVICES.LoadImage() when the driver specified by
DriverImagePath was loaded into memory.

Description

This function associates the image handle specified by DriverImageHandle with the device path of a driver specified
by DriverImagePath. DriverImagePath must be a value that was returned on a prior call to GetDriverPath() for the
controller specified by ControllerHandle. Once this association has been established, then the service GetDriver()
must return DriverImageHandle as one of the override drivers for the controller specified by ControllerHandle.

If the association between the image handle specified by DriverImageHandle and the device path specified by Driver-
ImagePath is established for the controller specified by ControllerHandle, then EFI_SUCCESS is returned. If Con-
trollerHandle is NULL, or DriverImagePath is not a valid device path, or DriverImageHandle is NULL, then
EFI_INVALID_PARAMETER is returned. If DriverImagePath is not a device path that was returned on a prior call
to EFI_PLATFORM_DRIVER_OVERRIDE_PROTOCOL.GetDriver() for the controller specified by ControllerHan-
dle, then EFI_NOT_FOUND is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
</table>
| EFI_SUCCESS            | The association between DriverImagePath and DriverImageHandle was es-
                        | tablished for the controller specified by ControllerHandle.               |
| EFI_UNSUPPORTED        | The operation is not supported.                                            |
| EFI_NOT_FOUND          | DriverImagePath is not a device path that was returned on a prior call to  |
                        | GetDriverPath() for the controller specified by ControllerHandle.         |
| EFI_INVALID_PARAMETER  | ControllerHandle is not a valid device handle.                             |
| EFI_INVALID_PARAMETER  | DriverImagePath is not a valid device path.                                |

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11.3 EFI Bus Specific Driver Override Protocol

This section provides a detailed description of the `EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL`. Bus drivers that have a bus specific algorithm for matching drivers to controllers are required to produce this protocol for each controller. For example, a PCI Bus Driver will produce an instance of this protocol for every PCI controller that has a PCI option ROM that contains one or more UEFI drivers. The protocol instance is attached to the handle of the PCI controller.

11.3.1 EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL

Summary

This protocol matches one or more drivers to a controller. This protocol is produced by a bus driver, and it is installed on the child handles of buses that require a bus specific algorithm for matching drivers to controllers. This protocol is used by the `EFI_BOOT_SERVICES.ConnectController()` boot service to select the best driver for a controller. All of the drivers returned by this protocol have a higher precedence than drivers found in the general EFI Driver Binding search algorithm, but a lower precedence than those drivers returned by the EFI Platform Driver Override Protocol. If more than one driver image handle is returned by this protocol, then the drivers image handles are returned in order from highest precedence to lowest precedence.

GUID

```
#define EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL_GUID \
{0x3bc1b285,0x8a15,0x4a82,\ 
 {0xaa,0xbf,0x4d,0x7d,0x13,0xfb,0x32,0x65}}
```

Protocol Interface Structure

```
typedef struct _EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL {
    EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_GET_DRIVER GetDriver;
} EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL;
```

Parameters

**GetDriver**

Uses a bus specific algorithm to retrieve a driver image handle for a controller. See the `EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL.GetDriver()` function description.

Description

The `EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL` provides a mechanism for bus drivers to override the default driver selection performed by the `ConnectController()` boot service. This protocol is attached to the handle of a child device after the child handle is created by the bus driver. The service in this protocol can return a bus specific override driver to `ConnectController()`. `ConnectController()` must call this service until all of the bus specific override drivers have been retrieved. `ConnectController()` uses this information along with the EFI Platform Driver Override Protocol and all of the EFI Driver Binding protocol instances to select the best drivers for a controller. Since a controller can be managed by more than one driver, this protocol can return more than one bus specific override driver.
11.3.2 EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL.GetDriver()

Summary

Uses a bus specific algorithm to retrieve a driver image handle for a controller.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_GET_DRIVER) (  
    IN EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL *This,
    IN OUT EFI_HANDLE *DriverImageHandle
);
```

Parameters

This

A pointer to the EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL instance.

DriverImageHandle

On input, a pointer to the previous driver image handle returned by GetDriver(). On output, a pointer to the next driver image handle. Passing in a NULL, will return the first driver image handle.

Description

This function is used to retrieve a driver image handle that is selected in a bus specific manner. The first driver image handle is retrieved by passing in a DriverImageHandle value of NULL. This will cause the first driver image handle to be returned in DriverImageHandle. On each successive call, the previous value of DriverImageHandle must be passed in. If a call to this function returns a valid driver image handle, then EFI_SUCCESS is returned. This process is repeated until EFI_NOT_FOUND is returned. If a DriverImageHandle is passed in that was not returned on a prior call to this function, then EFI_INVALID_PARAMETER is returned. The first driver image handle has the highest precedence, and the last driver image handle has the lowest precedence. This ordered list of driver image handles is used by the boot service EFI_BOOT_SERVICES.ConnectController() to search for the best driver for a controller.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>A bus specific override driver is returned in DriverImageHandle.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The end of the list of override drivers was reached. A bus specific override driver is not returned in DriverImageHandle.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DriverImageHandle is not a handle that was returned on a previous call to GetDriver().</td>
</tr>
</tbody>
</table>

11.4 EFI Driver Diagnostics Protocol

This section provides a detailed description of the EFI_DRIVER_DIAGNOSTICS2_PROTOCOL. This is a protocol that allows a UEFI driver to perform diagnostics on a controller that the driver is managing.
11.4.1 EFI_DRIVER_DIAGNOSTICS2_PROTOCOL

Summary

Used to perform diagnostics on a controller that a UEFI GUID

#define EFI_DRIVER_DIAGNOSTICS_PROTOCOL_GUID \ 
{"0x4d330321,0x025f,0x4aac,\ 
{"0x90,0xd8,0x5e,0xd9,0x00,0x17,0x3b,0x63}}

Protocol Interface Structure

typedef struct _EFI_DRIVER_DIAGNOSTICS2_PROTOCOL {
    EFI_DRIVER_DIAGNOSTICS2_RUN_DIAGNOSTICS RunDiagnostics;
    CHAR8 *SupportedLanguages;
} EFI_DRIVER_DIAGNOSTICS2_PROTOCOL;

Parameters

RunDiagnostics

Runs diagnostics on a controller. See the RunDiagnostics() EFI_DRIVER_DIAGNOSTICS2_PROTOCOL.RunDiagnostics() function description.

SupportedLanguages

A Null-terminated ASCII string that contains one or more supported language codes. This is the list of language codes that this protocol supports. The number of languages supported by a driver is up to the driver writer. SupportedLanguages is specified in RFC 4646 format. Appendix M — Formats — Language Codes and Language Code Arrays for the format of language codes and language code arrays.

Description

The EFI_DRIVER_DIAGNOSTICS2_PROTOCOL is used by a platform management utility to allow the user to run driver specific diagnostics on a controller. This protocol is optionally attached to the image handle of driver in the driver’s entry point. The platform management utility can collect all the EFI_DRIVER_DIAGNOSTICS2_PROTOCOL instances present in the system, and present the user with a menu of the controllers that have diagnostic capabilities. This platform management utility is invoked through a platform component such as the EFI Boot Manager.

11.4.2 EFI_DRIVER_DIAGNOSTICS2_PROTOCOL.RunDiagnostics()

Summary

Runs diagnostics on a controller.

Prototype

typedef
EFI_STATUS
(EFIAPIC *EFI_DRIVER_DIAGNOSTICS2_RUN_DIAGNOSTICS) ( \ 
    IN EFI_DRIVER_DIAGNOSTICS2_PROTOCOL *This, \ 
    IN EFI_HANDLE ControllerHandle, \ 
    IN EFI_HANDLE ChildHandle OPTIONAL, \ 
    IN EFI_DRIVER_DIAGNOSTIC_TYPE DiagnosticType, \ 
    IN CHAR8 *Language, \ 
    OUT EFI_GUID **ErrorType, \ 
    OUT UINTN *BufferSize, \ 
)(continues on next page)
OUT CHAR16 **Buffer

Parameters

This
A pointer to the EFI_DRIVER_DIAGNOSTICS2_PROTOCOL instance.

ControllerHandle
The handle of the controller to run diagnostics on.

ChildHandle
The handle of the child controller to run diagnostics on. This is an optional parameter that may be NULL. It will be NULL for device drivers. It will also be NULL for a bus drivers that attempt to run diagnostics on the bus controller. It will not be NULL for a bus driver that attempts to run diagnostics on one of its child controllers.

DiagnosticType
Indicates type of diagnostics to perform on the controller specified by ControllerHandle and ChildHandle. See “Related Definitions” for the list of supported types.

Language
A pointer to a Null-terminated ASCII string array indicating the language. This is the language in which the optional error message should be returned in Buffer, and it must match one of the languages specified in Sup- portedLanguages. The number of languages supported by a driver is up to the driver writer. Language is specified in RFC 4646 language code format. Appendix M — Formats — Language Codes and Language Code Arrays

Callers of interfaces that require RFC 4646 language codes to retrieve a Unicode string must use the RFC 4647 algorithm to lookup the Unicode string with the closest matching RFC 4646 language code.

ErrorType
A GUID that defines the format of the data returned in Buffer.

BufferSize
The size, in bytes, of the data returned in Buffer.

Buffer
A buffer that contains a Null-terminated string plus some additional data whose format is defined by ErrorType. Buffer is allocated by this function with EFI_BOOT_SERVICES.AllocatePool() , and it is the caller’s responsibility to free it with a call to EFI_BOOT_SERVICES.FreePool() .

Description
This function runs diagnostics on the controller specified by ControllerHandle and ChildHandle. DiagnosticType specifies the type of diagnostics to perform on the controller specified by ControllerHandle and ChildHandle. If the driver specified by This does not support the language specified by Language, then EFI_UNSUPPORTED is returned. If the controller specified by ControllerHandle and ChildHandle is not supported by the driver specified by This, then EFI_UNSUPPORTED is returned. If the diagnostics type specified by DiagnosticType is not supported by this driver, then EFI_UNSUPPORTED is returned. If there are not enough resources available to complete the diagnostic, then EFI_OUT_OF_RESOURCES is returned. If the controller specified by ControllerHandle and ChildHandle passes the diagnostic, then EFI_SUCCESS is returned. Otherwise, EFIDEVICE_ERROR is returned.

If the language specified by Language is supported by this driver, then status information is returned in ErrorType, BufferSize, and Buffer. Buffer contains a Null-terminated string followed by additional data whose format is defined by ErrorType. BufferSize is the size of Buffer in bytes, and it is the caller’s responsibility to call FreePool() on Buffer when the caller is done with the return data. If there are not enough resources available to return the status information, then EFI_OUT_OF_RESOURCES is returned.

Related Definitions
typedef enum {
    EfiDriverDiagnosticTypeStandard = 0,
    EfiDriverDiagnosticTypeExtended = 1,
    EfiDriverDiagnosticTypeManufacturing = 2,
    EfiDriverDiagnosticTypeCancel = 3,
    EfiDriverDiagnosticTypeMaximum
} EFI_DRIVER_DIAGNOSTIC_TYPE;

EfiDriverDiagnosticTypeStandard

Performs standard diagnostics on the controller. This diagnostic type is required to be supported by all
implementations of this protocol.

EfiDriverDiagnosticTypeExtended

This is an optional diagnostic type that performs diagnostics on the controller that may take an extended
amount of time to execute.

EfiDriverDiagnosticTypeManufacturing

This is an optional diagnostic type that performs diagnostics on the controller that are suitable for a man-
ufacturing and test environment.

EfiDriverDiagnosticTypeCancel

This is an optional diagnostic type that would only be used in the situation where an EFI_NOT_READY
had been returned by a previous call to RunDiagnostics() and there is a desire to cancel the current running
diagnostics operation.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The controller specified by ControllerHandle and ChildHandle passed the</td>
</tr>
<tr>
<td></td>
<td>diagnostic.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The request for initiating diagnostics was unable to be completed due to</td>
</tr>
<tr>
<td></td>
<td>some underlying hardware or software state.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ControllerHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The driver specified by This is not a device driver, and ChildHandle is not</td>
</tr>
<tr>
<td></td>
<td>NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Language is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ErrorType is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>BufferSize is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The driver specified by This does not support running diagnostics for the</td>
</tr>
<tr>
<td></td>
<td>controller specified by ControllerHandle and ChildHandle.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The driver specified by This does not support the type of diagnostic specified</td>
</tr>
<tr>
<td></td>
<td>by DiagnosticType.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The driver specified by This does not support the language specified by Lan-</td>
</tr>
<tr>
<td></td>
<td>guage.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There are not enough resources available to complete the diagnostics.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There are not enough resources available to return the status information in</td>
</tr>
<tr>
<td></td>
<td>ErrorType, BufferSize, and Buffer.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The controller specified by ControllerHandle and ChildHandle did not pass</td>
</tr>
<tr>
<td></td>
<td>the diagnostic.</td>
</tr>
</tbody>
</table>

continues on next page
11.5 EFI Component Name Protocol

This section provides a detailed description of the EFI_COMPONENT_NAME2_PROTOCOL. This is a protocol that allows an driver to provide a user readable name of a UEFI Driver, and a user readable name for each of the controllers that the driver is managing. This protocol is used by platform management utilities that wish to display names of components. These names may include the names of expansion slots, external connectors, embedded devices, and add-in devices.

11.5.1 EFI_COMPONENT_NAME2_PROTOCOL

Summary

Used to retrieve user readable names of drivers and controllers managed by UEFI Drivers.

GUID

#define EFI_COMPONENT_NAME2_PROTOCOL_GUID \
{0x6a7a5cfff, 0xe8d9, 0x4f70, }\n    {0xba, 0xda, 0x75, 0xab, 0x30,0x25, 0xce, 0x14}

Protocol Interface Structure

typedef struct _EFI_COMPONENT_NAME2_PROTOCOL {
    EFI_COMPONENT_NAME_GET_DRIVER_NAME GetDriverName;
    EFI_COMPONENT_NAME_GET_CONTROLLER_NAME GetControllerName;
    CHAR8 SupportedLanguages;
} EFI_COMPONENT_NAME2_PROTOCOL;

Parameters

GetDriverName

Retrieves a string that is the user readable name of the driver. See the GetDriverName() EFI_COMPONENT_NAME2_PROTOCOL.GetDriverName() function description.

GetControllerName

Retrieves a string that is the user readable name of a controller that is being managed by a driver. See the GetControllerName() EFI_COMPONENT_NAME2_PROTOCOL.GetControllerName() function description.

SupportedLanguages

A Null-terminated ASCII string array that contains one or more supported language codes. This is the list of language codes that this protocol supports. The number of languages supported by a driver is up to the driver writer. SupportedLanguages is specified in RFC 4646 format. Appendix M — Formats — Language Codes and Language Code Arrays

Description

The EFI_COMPONENT_NAME2_PROTOCOL is used retrieve a driver’s user readable name and the names of all the controllers that a driver is managing from the driver's point of view. Each of these names is returned as a Null-terminated string. The caller is required to specify the language in which the string is returned, and this language must be present in the list of languages that this protocol supports specified by SupportedLanguages.
11.5.2 EFI_COMPONENTNAME2_PROTOCOL.GetDriverName()

Summary
Retrieves a string that is the user readable name of the driver.

Prototype

```c
typedef EFI_STATUS EFIAPI *EFI_COMPONENT_NAME_GET_DRIVER_NAME) (  
    IN EFI_COMPONENT_NAME2_PROTOCOL *This,  
    IN CHAR8 *Language,  
    OUT CHAR16 **DriverName
);
```

Parameters

This
A pointer to the EFI_COMPONENT_NAME2_PROTOCOL instance.

Language
A pointer to a Null-terminated ASCII string array indicating the language. This is the language of the driver name that the caller is requesting, and it must match one of the languages specified in SupportedLanguages. The number of languages supported by a driver is up to the driver writer. Language is specified in RFC 4646 language code format. Appendix M — Formats — Language Codes and Language Code Arrays for the format of language codes.

Callers of interfaces that require RFC 4646 language codes to retrieve a Unicode string must use the RFC 4647 algorithm to lookup the Unicode string with the closest matching RFC 4646 language code.

DriverName
A pointer to the string to return. This string is the name of the driver specified by This in the language specified by Language.

Description
This function retrieves the user readable name of a driver in the form of a string. If the driver specified by This has a user readable name in the language specified by Language, then a pointer to the driver name is returned in DriverName, and EFI_SUCCESS is returned. If the driver specified by This does not support the language specified by Language, then EFI_UNSUPPORTED is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The string for the user readable name in the language specified by Language for the driver specified by This was returned in DriverName.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Language is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DriverName is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The driver specified by This does not support the language specified by Language.</td>
</tr>
</tbody>
</table>
11.5.3 EFI_COMPONENT_NAME2_PROTOCOL.GetControllerName()

Summary
Retrieves a string that is the user readable name of the controller that is being managed by a driver.

Prototype

```c
typedef EFI_STATUS
  (EFIAPICALLCONVENTION *EFI_COMPONENT_NAME_GET_CONTROLLER_NAME) (
    IN EFI_COMPONENT_NAME2_PROTOCOL *This,
    IN EFI_HANDLE ControllerHandle,
    IN EFI_HANDLE ChildHandle OPTIONAL,
    IN CHAR8 *Language,
    OUT CHAR16 **ControllerName
  );
```

Parameters

This
A pointer to the EFI_COMPONENT_NAME2_PROTOCOL instance.

ControllerHandle
The handle of a controller that the driver specified by This is managing. This handle specifies the controller whose name is to be returned.

ChildHandle
The handle of the child controller to retrieve the name of. This is an optional parameter that may be NULL. It will be NULL for device drivers. It will also be NULL for bus drivers that attempt to retrieve the name of the bus controller. It will not be NULL for a bus driver that attempts to retrieve the name of a child controller.

Language
A pointer to a Null-terminated ASCII string array indicating the language. This is the language of the controller name that the caller is requesting, and it must match one of the languages specified in SupportedLanguages. The number of languages supported by a driver is up to the driver writer. Language is specified in RFC 4646 language code format. Appendix M — Formats — Language Codes and Language Code Arrays for the format of language codes.

Callers of interfaces that require RFC 4646 language codes to retrieve a Unicode string must use the RFC 4647 algorithm to lookup the Unicode string with the closest matching RFC 4646 language code.

ControllerName
A pointer to the string to return. This string is the name of the controller specified by ControllerHandle and ChildHandle in the language specified by Language from the point of view of the driver specified by This.

Description
This function retrieves the user readable name of the controller specified by ControllerHandle and ChildHandle in the form of a string. If the driver specified by This has a user readable name in the language specified by Language, then a pointer to the controller name is returned in ControllerName, and EFI_SUCCESS is returned.

If the driver specified by This is not currently managing the controller specified by ControllerHandle and ChildHandle, then EFI_UNSUPPORTED is returned.

If the driver specified by This does not support the language specified by Language, then EFI_UNSUPPORTED is returned.
Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The string for the user readable name specified by This, ControllerHandle, ChildHandle, and Language was returned in ControllerName.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ControllerHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The driver specified by This is not a device driver, and ChildHandle is not NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Language is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ControllerName is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The driver specified by This is a device driver and ChildHandle is not NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The driver specified by This is not currently managing the controller specified by ControllerHandle and ChildHandle.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The driver specified by This does not support the language specified by Language.</td>
</tr>
</tbody>
</table>

11.6 EFI Service Binding Protocol

This section provides a detailed description of the `EFI_SERVICE_BINDING_PROTOCOL`. This protocol may be produced only by drivers that follow the UEFI Driver Model. Use this protocol with the `EFI Driver Binding Protocol` to produce a set of protocols related to a device. The `EFI_DRIVER_BINDING_PROTOCOL` supports simple layering of protocols on a device, but it does not support more complex relationships such as trees or graphs. The `EFI_SERVICE_BINDING_PROTOCOL` provides a member function to create a child handle with a new protocol installed on it, and another member function to destroy a previously created child handle. These member functions apply equally to all drivers.

11.6.1 EFI_SERVICE_BINDING_PROTOCOL

Summary

Provides services that are required to create and destroy child handles that support a given set of protocols.

GUID

This protocol does not have its own GUID. Instead, drivers for other protocols will define a GUID that shares the same protocol interface as the `EFI_SERVICE_BINDING_PROTOCOL`. The protocols defined in this document that have this property include for example the following:

- EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL
- EFI_ARP_SERVICE_BINDING_PROTOCOL
- EFI_EAP_SERVICE_BINDING_PROTOCOL
- EFI_IP4_SERVICE_BINDING_PROTOCOL
- EFI_TCP4_SERVICE_BINDING_PROTOCOL
- EFI_UDP4_SERVICE_BINDING_PROTOCOL
- EFI_MTFTP4_SERVICE_BINDING_PROTOCOL
- EFI_DHCP4_SERVICE_BINDING_PROTOCOL
- EFI_REST_EX_SERVICE_BINDING_PROTOCOL

Protocol Interface Structure

```c
typedef struct _EFI_SERVICE_BINDING_PROTOCOL {
    EFI_SERVICE_BINDING_CREATE_CHILD CreateChild;
} EFI_SERVICE_BINDING_PROTOCOL;
```

(continues on next page)
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(continued from previous page)

```c
 EFI_SERVICE_BINDING_DESTROY_CHILD DestroyChild;
}
EFI_SERVICE_BINDING_PROTOCOL;
```

### Parameters

**CreateChild**

Creates a child handle and installs a protocol. See the `EFI_SERVICE_BINDING_PROTOCOL.CreateChild()` function description.

**DestroyChild**

Destroys a child handle with a protocol installed on it. See the `EFI_SERVICE_BINDING_PROTOCOL.DestroyChild()` function description.

### Description

The `EFI_SERVICE_BINDING_PROTOCOL` provides member functions to create and destroy child handles. A driver is responsible for adding protocols to the child handle in `CreateChild()` and removing protocols in `DestroyChild()`.

It is also required that the `CreateChild()` function opens the parent protocol BY_CHILD_CONTROLLER to establish the parent-child relationship, and closes the protocol in `DestroyChild()`.

The pseudo code for `CreateChild()` and `DestroyChild()` is provided to specify the required behavior, not to specify the required implementation. Each consumer of a software protocol is responsible for calling `CreateChild()` when it requires the protocol and calling `DestroyChild()` when it is finished with that protocol.

#### 11.6.2 EFI_SERVICE_BINDING_PROTOCOL.CreateChild()

**Summary**

Creates a child handle and installs a protocol.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI *EFI_SERVICE_BINDING_CREATE_CHILD) ( 
    IN EFI_SERVICE_BINDING_PROTOCOL *This,
    IN OUT EFI_HANDLE *ChildHandle
);
```

**Parameters**

**This**

Pointer to the `EFI_SERVICE_BINDING_PROTOCOL` instance.

**ChildHandle**

Pointer to the handle of the child to create. If it is a pointer to `NULL`, then a new handle is created. If it is a pointer to an existing UEFI handle, then the protocol is added to the existing UEFI handle.

**Description**

The `CreateChild()` function installs a protocol on `ChildHandle`. If `ChildHandle` is a pointer to `NULL`, then a new handle is created and returned in `ChildHandle`. If `ChildHandle` is not a pointer to `NULL`, then the protocol installs on the existing `ChildHandle`.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The protocol was added to <code>ChildHandle</code></td>
</tr>
</tbody>
</table>

continues on next page
### Examples

The following example shows how a consumer of the EFI ARP Protocol would use the `CreateChild()` function of the `EFI_SERVICE_BINDING_PROTOCOL` to create a child handle with the EFI ARP Protocol installed on that handle.

```c
EFI_HII_HANDLE ControllerHandle;
EFI_HANDLE DriverBindingHandle;
EFI_HANDLE ChildHandle;
EFI_ARP_SERVICE_BINDING_PROTOCOL *ArpSb;
EFI_ARP_PROTOCOL *Arp;

// Get the ArpServiceBinding Protocol
Status = gBS->OpenProtocol(
    ControllerHandle,
    &gEfiArpServiceBindingProtocolGuid,
    (VOID **) &ArpSb,
    DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL);
if (EFI_ERROR (Status)) {
    return Status;
}

// Initialize a ChildHandle
ChildHandle = NULL;

// Create a ChildHandle with the Arp Protocol
Status = ArpSb->CreateChild(ArpSb, &ChildHandle);
if (EFI_ERROR (Status)) {
    goto ErrorExit;
}

// Retrieve the Arp Protocol from ChildHandle
Status = gBS->OpenProtocol(
    ChildHandle,
    &gEfiArpProtocolGuid,
    (VOID **) &Arp,
    DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_BY_DRIVER);
if (EFI_ERROR (Status)) {
    (continues on next page)
```
The following is the general algorithm for implementing the `CreateChild()` function:

1. Allocate and initialize any data structures that are required to produce the requested protocol on a child handle. If the allocation fails, then return `EFI_OUT_OF_RESOURCES`.

2. Install the requested protocol onto `ChildHandle`. If `ChildHandle` is a pointer to `NULL`, then the requested protocol installs onto a new handle.

3. Open the parent protocol `BY_CHILD_CONTROLLER` to establish the parent-child relationship. If the parent protocol cannot be opened, then destroy the `ChildHandle` created in step 2, free the data structures allocated in step 1, and return an error.

4. Increment the number of children created by `CreateChild()`.

5. Return `EFI_SUCCESS`.

Listed below is sample code of the `CreateChild()` function of the EFI ARP Protocol driver. This driver looks up its private context data structure from the instance of the `EFI_SERVICE_BINDING_PROTOCOL` produced on the handle for the network controller. After retrieving the private context data structure, the driver can use its contents to build the private context data structure for the child being created. The EFI ARP Protocol driver then installs the `EFI_ARP_PROTOCOL` onto `ChildHandle`.

```c
EFI_STATUS

EFIAPI
ArpServiceBindingCreateChild (  
    IN EFI_SERVICE_BINDING_PROTOCOL *This,  
    IN EFI_HANDLE *ChildHandle  
)  
{  
    EFI_STATUS Status;  
    ARP_PRIVATE_DATA *Private;  
    ARP_PRIVATE_DATA *PrivateChild;  

    // Retrieve the Private Context Data Structure  
    //  
    Private = ARP_PRIVATE_DATA_FROM_SERVICE_BINDING_THIS (This);  
    //  
    // Create a new child  
    //  
    PrivateChild = EfiLibAllocatePool (sizeof (ARP_PRIVATE_DATA));  
    if (PrivateChild == NULL) {  
        return EFI_OUT_OF_RESOURCES;  
    }  

    // Copy Private Context Data Structure  
    //  
    gBS->CopyMem (PrivateChild, Private, sizeof (ARP_PRIVATE_DATA));  

    // (continues on next page)
```
// Install Arp onto ChildHandle

Status = gBS->InstallMultipleProtocolInterfaces (
    ChildHandle,
    &gEfiArpProtocolGuid, &PrivateChild->Arp,
    NULL
);
if (EFI_ERROR (Status)) {
gBS->FreePool (PrivateChild);
    return Status;
}

Status = gBS->OpenProtocol (
    Private->ChildHandle,
    &gEfiManagedNetworkProtocolGuid,
    (VOID **)&PrivateChild->ManagedNetwork,
    gArpDriverBinding.DriverBindingHandle,
    *ChildHandle,
    EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER
);
if (EFI_ERROR (Status)) {
    ArpSB->DestroyChild (This, ChildHandle);
    return Status;
}

// Increase number of children created
//
Private->NumberCreated++;

return EFI_SUCCESS;

11.6.3 EFI_SERVICE_BINDING_PROTOCOL.DestroyChild()

Summary
Destroys a child handle with a protocol installed on it.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_SERVICE_BINDING_DESTROY_CHILD) (  
    IN EFI_SERVICE_BINDING_PROTOCOL *This,
    IN EFI_HANDLE ChildHandle
    );

Parameters

This
    Pointer to the EFI_SERVICE_BINDING_PROTOCOL instance.
ChildHandle
Handle of the child to destroy.

Description
The DestroyChild() function does the opposite of CreateChild(). It removes a protocol that was installed by CreateChild() from ChildHandle. If the removed protocol is the last protocol on ChildHandle, then ChildHandle is destroyed.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The protocol was removed from ChildHandle.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>ChildHandle does not support the protocol that is being removed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ChildHandle is not a valid UEFI handle.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The protocol could not be removed from the ChildHandle because its services are being used.</td>
</tr>
<tr>
<td>Other</td>
<td>The child handle was not destroyed.</td>
</tr>
</tbody>
</table>

Examples
The following example shows how a consumer of the EFI ARP Protocol would use the DestroyChild() function of the EFI_SERVICE_BINDING_PROTOCOL to destroy a child handle with the EFI ARP Protocol installed on that handle.

```c
 EFI_HANDLE ControllerHandle;
 EFI_HANDLE DriverBindingHandle;
 EFI_HANDLE ChildHandle;
 EFI_ARP\_SERVICE_BINDING_PROTOCOL *Arp;

// Get the Arp Service Binding Protocol
//
Status = gBS->OpenProtocol(
    ControllerHandle,
    &gEfiArpServiceBindingProtocolGuid,
    (VOID **) &ArpSb,
    DriverBindingHandle,
    ControllerHandle,
    EFI_OPEN_PROTOCOL_GET_PROTOCOL);
if (EFI_ERROR (Status)) {
    return Status;
}

// Destroy the ChildHandle with the Arp Protocol
//
Status = ArpSb->DestroyChild (ArpSb, ChildHandle);
if (EFI_ERROR (Status)) {
    return Status;
}
```

Pseudo Code
The following is the general algorithm for implementing the DestroyChild() function:

11.6. EFI Service Binding Protocol
1. Retrieve the protocol from ChildHandle. If this retrieval fails, then return EFI_SUCCESS because the child has already been destroyed.

2. If this call is a recursive call to destroy the same child, then return EFI_SUCCESS.

3. Close the parent protocol with CloseProtocol().

4. Set a flag to detect a recursive call to destroy the same child.

5. Remove the protocol from ChildHandle. If this removal fails, then reopen the parent protocol and clear the flag to detect a recursive call to destroy the same child.

6. Free any data structures that allocated in CreateChild().

7. Decrement the number of children that created with CreateChild().

8. Return EFI_SUCCESS.

Listed below is sample code of the DestroyChild() function of the EFI ARP Protocol driver. This driver looks up its private context data structure from the instance of the EFI_SERVICE_BINDING_PROTOCOL produced on the handle for the network controller. The driver attempts to retrieve the EFI_ARP_PROTOCOL from ChildHandle. If that fails, then EFI_SUCCESS is returned. The EFI_ARP_PROTOCOL is then used to retrieve the private context data structure for the child. The private context data stores the flag that detects if DestroyChild() is being called recursively. If a recursion is detected, then EFI_SUCCESS is returned. Otherwise, the EFI_ARP_PROTOCOL is removed from ChildHandle, the number of children are decremented, and EFI_SUCCESS is returned.

```c
EFI_STATUS
EFIAPI
ArpServiceBindingDestroyChild (  
    IN EFI_SERVICE_BINDING_PROTOCOL *This,  
    IN EFI_HANDLE ChildHandle  
)  
{
    EFI_STATUS Status;
    EFI_ARP_PROTOCOL *Arp;
    ARP_PRIVATE_DATA *Private;
    ARP_PRIVATE_DATA *PrivateChild;

    // // Retrieve the Private Context Data Structure
    // // Private = ARP\_PRIVATE_DATA_FROM_SERVICE_BINDING_THIS (This);

    // // Retrieve Arp Protocol from ChildHandle
    // //
    Status = gBS->OpenProtocol (  
        ChildHandle,  
        &gEfiArpProtocolGuid,  
        (VOID **) &Arp,  
        gArpDriverBinding.DriverBindingHandle,  
        ChildHandle,  
        EFI_OPEN_PROTOCOL_GET_PROTOCOL  
    );
    if (EFI_ERROR (Status)) {
        return EFI_SUCCESS;
    }
}
```
// Retrieve Private Context Data Structure
//
PrivateChild = ARP_PRIVATE_DATA_FROM_ARP_THIS (Arp);
if (PrivateChild->Destroy) {
    return EFI_SUCCESS;
}

// Close the ManagedNetwork Protocol
//
gBS->CloseProtocol(
    Private->ChildHandle,
    &gEfiManagedNetworkProtocolGuid,
    gArpDriverBinding.DriverBindingHandle,
    ChildHandle
);

PrivateChild->Destroy = TRUE;

// Uninstall Arp from ChildHandle
//
Status = gBS->UninstallMultipleProtocolInterfaces(
    ChildHandle,
    &gEfiArpProtocolGuid, &PrivateChild->Arp,
    NULL
);
if (EFI_ERROR (Status)) {
    // Uninstall failed, so reopen the parent Arp Protocol and return an error
    PrivateChild->Destroy = FALSE;
    gBS->OpenProtocol(
        Private->ChildHandle,
        &gEfiManagedNetworkProtocolGuid,
        (VOID **) &PrivateChild->ManagedNetwork,
        gArpDriverBinding.DriverBindingHandle,
        ChildHandle,
        EFI_OPEN_PROTOCOL_BY_CHILD_CONTROLLER
    );
    return Status;
}

// Free Private Context Data Structure
//
gBS->FreePool (PrivateChild);
11.7 EFI Platform to Driver Configuration Protocol

This section provides a detailed description of the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL. This is a protocol that is optionally produced by the platform and optionally consumed by a UEFI Driver in its Start() function. This protocol allows the driver to receive configuration information as part of being started.

11.7.1 EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL

Summary
Used to retrieve configuration information for a device that a UEFI driver is about to start.

GUID

```
#define EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL_GUID \
  { 0x642cd590, 0x8059, 0x4c0a,\ 
    { 0xa9, 0x58, 0xc5, 0xec, 0x07, 0xd2, 0x3c, 0x4b } }
```

Protocol Interface Structure

```
typedef struct _EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL {
    EFI_PLATFORM_TO_DRIVER_CONFIGURATION_QUERY Query;
    EFI_PLATFORM_TO_DRIVER_CONFIGURATION_RESPONSE Response;
} EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL;
```

Parameters

**Query**
Called by the UEFI Driver Start() function to get configuration information from the platform.

**Response**
Called by the UEFI Driver Start() function to let the platform know how UEFI driver processed the data return from Query.

Description

The EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL is used by the UEFI driver to query the platform for configuration information. The UEFI driver calls EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL.Query() multiple times to get configuration information from the platform. For every call to Query() there must be a matching call to EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL.Response() so the UEFI driver can inform the platform how it used the information passed in from Query().

It’s legal for a UEFI driver to use Response() to inform the platform it does not understand the data returned via Query() and thus no action was taken.
### 11.7.2 EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL.Query()

#### Summary
Allows the UEFI driver to query the platform for configuration information needed to complete the drivers `Start()` operation.

#### Prototype
```c
typedef EFI_STATUS (EFIAPI *EFI_PLATFORM_TO_DRIVER_CONFIGURATION_QUERY) (  
  IN EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL *This,  
  IN EFI_HANDLE ControllerHandle,  
  IN EFI_HANDLE ChildHandle OPTIONAL,  
  IN UINTN *Instance,  
  OUT EFI_GUID **ParameterTypeGuid,  
  OUT VOID **ParameterBlock,  
  OUT UINTN *ParameterBlockSize
);
```

#### Parameters
- **This**: A pointer to the `EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL` instance.
- **ControllerHandle**: The handle the platform will return configuration information about.
- **ChildHandle**: The handle of the child controller to return information on. This is an optional parameter that may be NULL. It will be NULL for device drivers, and for bus drivers that attempt to get options for the bus controller. It will not be NULL for a bus driver that attempts to get options for one of its child controllers.
- **Instance**: Pointer to the Instance value. Zero means return the first query data. The caller should increment this value by one each time to retrieve successive data.
- **ParameterTypeGuid**: An `EFI_GUID` that defines the contents of ParameterBlock. UEFI drivers must use the ParameterTypeGuid to determine how to parse the ParameterBlock. The caller should not attempt to free `ParameterTypeGuid`.
- **ParameterBlock**: The platform returns a pointer to the `ParameterBlock` structure which contains details about the configuration parameters specific to the `ParameterTypeGuid`. This structure is defined based on the protocol and may be different for different protocols. UEFI driver decodes this structure and its contents based on `ParameterTypeGuid`. `ParameterBlock` is allocated by the platform and the platform is responsible for freeing the `ParameterBlock` after `Response` is called.
- **ParameterBlockSize**: The platform returns the size of the ParameterBlock in bytes.

#### Description
The UEFI driver must call Query early in the `Start()` function before any time consuming operations are performed. If `ChildHandle` is NULL the driver is requesting information from the platform about the `ControllerHandle` that is being started. Information returned from Query may lead to the drivers `Start()` function failing.

If the UEFI driver is a bus driver and producing a `ChildHandle` the driver must call Query after the child handle has been created and an `EFI_DEVICE_PATH_PROTOCOL` has been placed on that handle, but before any time consuming operations are performed.
operation is performed. If information return by *Query* may lead the driver to decide to not create the ChildHandle. The driver must then cleanup and remove the ChildHandle from the system.

The UEFI driver repeatedly calls Query, processes the information returned by the platform, and calls Response passing in the arguments returned from Query. The *Instance* value passed into Response must be the same value passed to the corresponding call to Query. The UEFI driver must continuously call Query and Response until EFI_NOT_FOUND is returned by Query.

If the UEFI driver does not recognize the *ParameterTypeGuid*, it calls Response with a *ConfigurationAction* of Efi-PlatformConfigurationActionUnsupportedGuid. The UEFI driver must then continue calling Query and Response until EFI_NOT_FOUND is returned by Query. This gives the platform an opportunity to pass additional configuration settings using a different *ParameterTypeGuid* that may be supported by the driver.

An *Instance* value of zero means the first ParameterBlock in the set of unprocessed parameter blocks. The driver should increment the *Instance* value by one for each successive call to Query.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The platform return parameter information for ControllerHandle.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No more unread Instance exists.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ControllerHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Instance is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to return parameter block inform-</td>
</tr>
<tr>
<td></td>
<td>ation for the controller specified by ControllerHandle and ChildHandle.</td>
</tr>
<tr>
<td>EFI_OUT_RESOURCES</td>
<td>There are not enough resources available to set the configuration options for</td>
</tr>
<tr>
<td></td>
<td>the controller specified by ControllerHandle and ChildHandle.</td>
</tr>
</tbody>
</table>

### 11.7.3 EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL.Response()

**Summary**

Tell the platform what actions where taken by the driver after processing the data returned from Query.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_PLATFORM_TO_DRIVER_CONFIGURATION_RESPONSE) ( 
    IN EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL *This, 
    IN EFI_HANDLE ControllerHandle, 
    IN EFI_HANDLE ChildHandle OPTIONAL, 
    IN UINTN *Instance, 
    IN EFI_GUID *ParameterTypeGuid, 
    IN VOID *ParameterBlock, 
    IN UINTN ParameterBlockSize, 
    IN EFI_PLATFORM_CONFIGURATION_ACTION ConfigurationAction 
); 
```

**Parameters**

**This**

A pointer to the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL instance.

**ControllerHandle**

The handle the driver is returning configuration information about.
ChildHandle
The handle of the child controller to return information on. This is an optional parameter that may be NULL. It will be NULL for device drivers, and for bus drivers that attempt to get options for the bus controller. It will not be NULL for a bus driver that attempts to get options for one of its child controllers.

Instance
Instance data passed to EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL.Query().

ParameterTypeGuid
ParameterTypeGuid returned from Query.

ParameterBlock
ParameterBlock returned from Query.

ParameterBlockSize
The ParameterBlock size returned from Query.

ConfigurationAction
The driver tells the platform what action is required for ParameterBlock to take effect. See “Related Definitions” for a list of actions.

Description
The UEFI driver repeatedly calls Query, processes the information returned by the platform, and calls Response passing in the arguments returned from Query. The UEFI driver must continuously call Query until EFI_NOT_FOUND is returned. For every call to Query that returns EFI_SUCCESS a corresponding call to Response is required passing in the same ControllerHandle, ChildHandle, Instance, ParameterTypeGuid, ParameterBlock, and ParameterBlockSize. The UEFI driver may update values in ParameterBlock based on rules defined by ParameterTypeGuid.

The platform is responsible for freeing ParameterBlock and the UEFI driver must not try to free it.

Related Definitions

typedef enum {
    EfiPlatformConfigurationActionNone = 0,
    EfiPlatformConfigurationActionStopController = 1,
    EfiPlatformConfigurationActionRestartController = 2,
    EfiPlatformConfigurationActionRestartPlatform = 3,
    EfiPlatformConfigurationActionNvramFailed = 4,
    EfiPlatformConfigurationActionUnsupportedGuid = 5,
    EfiPlatformConfigurationActionMaximum
} EFI_PLATFORM_CONFIGURATION_ACTION;

EfiPlatformConfigurationActionNone
The controller specified by ControllerHandle is still in a usable state, it’s configuration has been updated via parsing the ParameterBlock. If required by the parameter block and the module supports an NVRAM store the configuration information from ParameterBlock was successfully saved to the NVRAM. No actions are required before this controller can be used again with the updated configuration settings.

EfiPlatformConfigurationStopController
The driver has detected that the controller specified by ControllerHandle is not in a usable state, and it needs to be stopped. The calling agent can use the EFI_BOOT_SERVICES.DisconnectController() service to perform this operation, and it should be performed as soon as possible.

EfiPlatformConfigurationRestartController
This controller specified by ControllerHandle needs to be stopped and restarted before it can be used again. The calling agent can use the DisconnectController() and EFI_BOOT_SERVICES.ConnectController() services to perform this operation. The restart operation can be delayed until all of the configuration options have been set.

11.7. EFI Platform to Driver Configuration Protocol
EfiPlatformConfigurationRestartPlatform

A configuration change has been made that requires the platform to be restarted before the controller specified by ControllerHandle can be used again. The calling agent can use the ResetSystem() services to perform this operation. The restart operation can be delayed until all of the configuration options have been set.

EfiPlatformConfigurationActionNvramFailed

The controller specified by ControllerHandle is still in a usable state; its configuration has been updated via parsing the ParameterBlock. The driver tried to update the driver’s private NVRAM store with information from ParameterBlock and failed. No actions are required before this controller can be used again with the updated configuration settings, but these configuration settings are not guaranteed to persist after ControllerHandle is stopped.

EfiPlatformConfigurationActionUnsupportedGuid

The controller specified by ControllerHandle is still in a usable state; its configuration has not been updated via parsing the ParameterBlock. The driver did not support the ParameterBlock format identified by ParameterTypeGuid. No actions are required before this controller can be used again. On additional Query calls from this ControllerHandle, the platform should stop returning a ParameterBlock qualified by this same ParameterTypeGuid. If no other ParameterTypeGuid is supported by the platform, Query should return EFI_NOT_FOUND.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The platform return parameter information for ControllerHandle.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Instance was not found.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ControllerHandle is NULL.</td>
</tr>
</tbody>
</table>

11.7.4 DMTF SM CLP ParameterTypeGuid

The following parameter protocol ParameterTypeGuid provides the support for parameters communicated through the DMTF SM CLP Specification 1.0 Final Standard to be used to configure the UEFI driver.

In this section the producer of the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL is platform firmware and the consumer is the UEFI driver.

Note: If future versions of the DMTF SM CLP Specification require changes to the parameter block definition, newer ParameterTypeGuid will be used.

GUID

```c
#define EFI_PLATFORM_TO_DRIVER_CONFIGURATION_CLP_GUID \
{0x345ecc0e, 0xcb6, 0x4b75, \
  {0xbb, 0x57, 0x1b, 0x12, 0x9c, 0x47, 0x33,0x3e}}
```

Parameter Block

```c
typedef struct {
  CHAR8       *CLPCommand;
  UINT32      CLPCommandLength;
  CHAR8       *CLPReturnString;*
  UINT32      CLPReturnStringLength;
  UINT8       CLPCmdStatus;
  UINT8       CLPErrorValue;
  UINT16      CLPMsgCode;
} EFI_CONFIGURE_CLP_PARAMETER_BLK;
```

Structure Member Definitions
**CLPCommand**
A pointer to the null-terminated UTF-8 string that specifies the DMTF SM CLP command line that the driver is required to parse and process when this function is called. See the DMTF SM CLP Specification 1.0 Final Standard for details on the format and syntax of the CLP command line string. CLPCommand buffer is allocated by the producer of the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL.

**CLPCommandLength**
The length of the CLP Command in bytes.

**CLPReturnString**
A pointer to the null-terminated UTF-8 string that indicates the CLP return status that the driver is required to provide to the calling agent. The calling agent may parse and/or pass this for processing and user feedback. The SM CLP Command Response string buffer is filled in by the UEFI driver in the “keyword=value” format described in the SM CLP Specification (see section 3.table 101, “Output Data”), unless otherwise requested via the SM CLP -output option in the Command Line string buffer. UEFI driver’s support for this default “keyword=value” output format is required if the UEFI driver supports this protocol, while support for other SM CLP output formats is optional. (The UEFI Driver should set CLPCmdStatus=2 (COMMAND PROCESSING FAILED) and CLPErrorValue=249 (OUTPUT FORMAT NOT SUPPORTED) if the SM CLP -output option requested by the caller is not supported by the UEFI Driver.)

CLPReturnString* buffer is allocated by the consumer of the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL and undefined prior to the call to Response().

**CLPReturnStringLength**
The length of the CLP return status string in bytes.

**CLPCmdStatus**
SM CLP Command Status (see DMTF SM CLP Specification 1.0 Final Standard - Table 4)

**CLPErrorValue**
SM CLP Processing Error Value (see DMTF SM CLP Specification 1.0 Final Standard - Table 6).

This field is filled in by the consumer of the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL and undefined prior to the call to Response().

**CLPMsgCode**

Bit 15: OEM Message Code Flag
0 = Message Code is an SM CLP Probable Cause Value. (see SM CLP Specification Table 11)

Bits 14-0: Message Code
This field is filled in by the consumer of the EFI_PLATFORM_TO_DRIVER_CONFIGURATION_PROTOCOL and undefined prior to the call to Response().

### 11.8 EFI Driver Supported EFI Version Protocol

#### 11.8.1 EFI_DRIVER_SUPPORTED_EFI_VERSION_PROTOCOL

**Summary**
Provides information about the version of the EFI specification that a driver is following. This protocol is required for EFI drivers that are on PCI and other plug in cards.

**GUID**
Protocol Interface Structure

```
#define EFI_DRIVER_SUPPORTED_EFI_VERSION_PROTOCOL_GUID
{ 0x5c198761, 0x16a8, 0xe69, 0x97, 0x2c, 0x89, 0xd6, 0x79, 0x54, 0xf8, 0x1d }
```

**Protocol Interface Structure**

```c
typedef struct _EFI_DRIVER_SUPPORTED_EFI_VERSION_PROTOCOL {
    UINT32 Length;
    UINT32 FirmwareVersion;
} EFI_DRIVER_SUPPORTED_EFI_VERSION_PROTOCOL;
```

**Parameters**

**Length**

The size, in bytes, of the entire structure. Future versions of this specification may grow the size of the structure.

**FirmwareVersion**

The latest version of the UEFI Specification that this driver conforms to. Refer to the `EFI_SPECIFICATION_VERSION` definition in *EFI System Table*.

**Description**

The `EFI_DRIVER_SUPPORTED_EFI_VERSION_PROTOCOL` provides a mechanism for an EFI driver to publish the version of the EFI specification it conforms to. This protocol must be placed on the drivers image handle when the driver’s entry point is called.

### 11.9 EFI Driver Family Override Protocol

#### 11.9.1 Overview

This section defines the Driver Family Override Protocol, and contains the following:

- Description and code definitions of the Driver Family Override Protocol.
- Required updates to the EFI Boot Services `ConnectController()`.
- Typical production of the Driver Family Override Protocol by an EFI Driver that follows the EFI Driver Model.

The Driver Family Override Protocol provides a method for an EFI Driver to opt-in to a higher priority rule for connecting drivers to controllers in the EFI Boot Service `ConnectController()`. This new rule is higher priority than the Bus Specific Driver Override Protocol rule and lower priority than the Platform Driver Override Rule.

The Driver Family Override Protocol is a backwards compatible extension to the EFI Driver Model and is only available during boot time. The Driver Family Override Protocol may be optionally produced by a driver that follows the EFI Driver Model. If this protocol is produced, it must be installed onto the Driver Image Handle. Drivers that follow the EFI Driver Model typically install the EFI Driver Binding Protocol onto the driver’s image handle. In this case, the Driver Family Override Protocol must also be installed onto the driver’s image handle. If a single EFI Driver produces more than one instance of the EFI Driver Binding Protocol, then the Driver Family Override Protocol must be installed onto the same handle as the EFI Driver Binding Protocol that is associated with the Driver Family Override Protocol.

Since it is legal for a single EFI Driver to produce multiple EFI Driver Binding Protocol instances, it is also legal for a single EFI Driver to produce multiple Driver Family Override Protocol instances.
11.9.1.1 EFI_DRIVER_FAMILY_OVERRIDE_PROTOCOL

Summary
When installed, the Driver Family Override Protocol informs the UEFI Boot Service `ConnectController()` that this driver is higher priority than the list of drivers returned by the Bus Specific Driver Override Protocol.

GUID
```
define EFI_DRIVER_FAMILY_OVERRIDE_PROTOCOL_GUID \
{0xb1ee129e,0xda36,0x4181,\ 
{0x91,0xf8,0x04,0xa4,0x92,0x37,0x66,0xa7}}
```

Protocol Interface Structure
```
typedef struct _EFI_DRIVER_FAMILY_OVERRIDE_PROTOCOL { 
   EFI_DRIVER_FAMILY_OVERRIDE_GET_VERSION GetVersion; 
} EFI_DRIVER_FAMILY_OVERRIDE_PROTOCOL;
```

Parameters
**GetVersion**
Retrieves the version of the driver that is used by the UEFI Boot Service `ConnectController()` to sort the set of Driver Binding Protocols in order from highest priority to lowest priority. For drivers that support the Driver Family Override Protocol, those drivers are sorted so that the drivers with higher values returned by `GetVersion()` are high priority that drivers that return lower values from `GetVersion()`.

Description
This protocol contains a single service that returns a version value for the driver that produces this protocol. High values are higher priority than lower values when evaluated by the UEFI Boot Service `ConnectController()` . This is an optional protocol that may be produced by an EFI Driver that follows the EFI Driver Model. If this protocol is produced, it must be installed onto a handle that also contains the EFI Driver Binding Protocol.

If this protocol is not produced by an EFI Driver, then the rules used to connect a driver to a controller from highest priority to lowest priority are as follows:

- Context Override
- Platform Driver Override
- Bus Specific Driver Override Protocol
- Driver Binding Search

If this protocol is produced by an EFI Driver, then the rules used to connect a driver to a controller from highest priority to lowest priority are as follows:

- Context Override
- Platform Driver Override
- Driver Family Override
- Bus Specific Driver Override
- Driver Binding Search
11.9.1.2 EFI_DRIVER_FAMILY_OVERRIDE_PROTOCOL.GetVersion()

Summary
Retrieves the version of the driver that is used by the EFI Boot Service ConnectController() to sort the set of Driver Binding Protocols in order from highest priority to lowest priority. For drivers that support the Driver Family Override Protocol, those drivers are sorted so that the drivers with higher values returned by GetVersion() are high priority that drivers that return lower values from GetVersion().

Prototype

typedef
UINT32
(EIFIAPI *EFI_DRIVER_FAMILY_OVERRIDE_GET_VERSION) (IN EFI_DRIVER_FAMILY_OVERRIDE_PROTOCOL *This);

Parameters
This A pointer to the EFI_DRIVER_FAMILY_OVERRIDE_PROTOCOL instance.

Description
This function returns the version value associated with the driver specified by This.

11.10 EFI Driver Health Protocol

This section contains the basic definitions of the Driver Health Protocol.

11.10.1 EFI_DRIVER_HEALTH_PROTOCOL

Summary
When installed, the Driver Health Protocol produces a collection of services that allow the health status for a controller to be retrieved. If a controller is not in a usable state, status messages may be reported to the user, repair operations can be invoked, and the user may be asked to make software and/or hardware configuration changes. All display, as well as interaction, with the user must be handled by the consumer of the Driver Health Protocol.

The Driver Health Protocol must be installed onto the same handle as the associated Driver Binding handle.

GUID

```
#define EFI_DRIVER_HEALTH_PROTOCOL_GUID \
{0x2a534210,0x9280,0x41d8,\ 
 {0xae,0x79,0xca,0xda,0x01,0xa2,0xb1,0x27 }}
```

Protocol Interface Structure

```
typedef struct _EFI_DRIVER_HEALTH_PROTOCOL {
 EFI_DRIVER_HEALTH_GET_HEALTH_STATUS GetHealthStatus;
 EFI_DRIVER_HEALTH_REPAIR Repair;
} EFI_DRIVER_HEALTH_PROTOCOL;
```

Parameters
GetHealthStatus
Retrieves the health status of a controller in the platform. This function can also optionally return warning messages, error messages, and an HII Form that may be used to repair a controller that is not properly configured.

Repair
Performs a repair operation on a controller in the platform. This function can optionally report repair progress information back to the platform.

Description
The Driver Health Protocol is optionally produced by a driver that follows the EFI Driver Model. If an EFI Driver needs to report health status to the platform, provide warning or error messages to the user, perform length repair operations, or request the user to make hardware or software configuration changes, then the Driver Health Protocol must be produced.

A controller that is managed by a driver that follows the EFI Driver Model and produces the Driver Health Protocol must report the current health of the controllers that the driver is currently managing. The controller can initially be healthy, failed, require repair, or require configuration. If a controller requires configuration, and the user make configuration changes, the controller may then need to be reconnected or the system may need to be rebooted for the configuration changes to take effect. Figure 2-1 below shows all the possible health states of a controller, the set of initial states, the set of terminal states, and the legal transitions between the health states.

Fig. 11.1: Driver Health Status States
11.10.2 EFI_DRIVER_HEALTH_PROTOCOL.GetHealthStatus()

Summary
Retrieves the health status of a controller in the platform. This function can also optionally return warning messages, error messages, and an HII Form that may be used to repair a controller that is not properly configured.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_DRIVER_HEALTH_GET_HEALTH_STATUS) (  
    IN EFI_DRIVER_HEALTH_PROTOCOL *This,  
    IN EFI_HANDLE ControllerHandle, OPTIONAL  
    IN EFI_HANDLE ChildHandle, OPTIONAL  
    OUT EFI_DRIVER_HEALTH_STATUS *HealthStatus,  
    OUT EFI_DRIVER_HEALTH_HII_MESSAGE **MessageList, OPTIONAL  
    OUT EFI_HII_HANDLE *FormHiiHandle OPTIONAL
)
```

Parameters

This
A pointer to the EFI_DRIVER_HEALTH_PROTOCOL instance.

ControllerHandle
The handle of the controller to retrieve the health status on. This is an optional parameter that may be NULL. If this parameter is NULL, then the value of ChildHandle is ignored, and the combined health status of all the devices that the driver is managing is returned.

ChildHandle
The handle of the child controller to retrieve the health status on. This is an optional parameter that may be NULL. It will be NULL for device drivers. It will also be NULL for bus drivers when an attempt is made to collect the health status of the bus controller. If will not be NULL when an attempt is made to collect the health status for a child controller produced by the driver. If ControllerHandle is NULL, then this parameter is ignored.

HealthStatus
A pointer to the health status that is returned by this function. The health status for the controller specified by ControllerHandle and ChildHandle is returned.

MessageList
A pointer to an array of warning or error messages associated with the controller specified by ControllerHandle and ChildHandle. This is an optional parameter that may be NULL. MessageList is allocated by this function with the EFI Boot Service AllocatePool(), and it is the caller’s responsibility to free MessageList with the EFI Boot Service FreePool(). Each message is specified by tuple of an EFI_HII_HANDLE and an EFI_STRING_ID. The array of messages is terminated by tuple containing a EFI_HII_HANDLE with a value of NULL. The EFI_HII_STRING_PROTOCOL.GetString() function can be used to retrieve the warning or error message as a Null-terminated string in a specific language. Messages may be returned for any of the HealthStatus values except EfiDriverHealthStatusReconnectRequired and EfiDriverHealthStatusRebootRequired.

FormHiiHandle
A pointer to the HII handle containing the HII form used when configuration is required. The HII handle is associated with the controller specified by ControllerHandle and ChildHandle. If this is NULL, then no HII form is available. An HII handle will only be returned with a HealthStatus value of EfiDriverHealthStatusConfigurationRequired.
This function returns the health status associated with the controller specified by `ControllerHandle` and `ChildHandle`. If `ControllerHandle` is NULL, and if the EFI driver is not managing any controller then `EFI_UNSUPPORTED` is returned. If `ControllerHandle` is not NULL and the driver specified by `This` is not currently managing the controller specified by `ControllerHandle` and `ChildHandle`, then `EFI_UNSUPPORTED` is returned. If `HealthStatus` is NULL, then `EFI_INVALID_PARAMETER` is returned.

If `ControllerHandle` is NULL, then the cumulative health status of all the controllers managed by the EFI driver is returned. If all the controller manages by the driver are healthy, then `EfiDriverHealthStatusHealthy` must be returned in `HealthStatus`. If one or more of the controllers managed by the EFI Driver is not healthy, then `EfiDriverHealthStatusFailed` must be returned.

If `ControllerHandle` is not NULL and `ChildHandle` is NULL, then the health status of the controller specified by `ControllerHandle` is returned in `HealthStatus` and `EFI_SUCCESS` is returned.

If `MessageList` is NULL, then no messages are returned from this function.

If `MessageList` is not NULL, and `HealthStatus` is `EfiDriverHealthStatusReconnectRequired` or `EfiDriverHealthStatusRebootRequired` then no messages are returned and `*MessageList` must be set to NULL.

If `MessageList` is not NULL, and there are no warning or error messages associated with the controller specified by `ControllerHandle` and `ChildHandle`, then `*MessageList` must be set to NULL.

If `MessageList` is not NULL, and there are one or more warning or error messages associated with the controller specified by `ControllerHandle` and `ChildHandle`, then `*MessageList` must point to a buffer allocated with the EFI Boot Service `AllocatePool()`. The number of `EFI_DRIVER_HEALTH_HII_MESSAGE` structures allocated in the buffer must be one more than the total number of warning or error messages, and the `HiiHandle` field of the last `EFI_DRIVER_HEALTH_HII_MESSAGE` structure must be set to NULL to terminate the list of messages. It is the caller’s responsibility to free the buffer returned in `*MessageList` using the EFI Boot Service `FreePool()`. Each message is specified by an `EFI_HII_HANDLE` and an `EFI_STRING_ID`. The caller may use the `EFI_HII_STRING_PROTOCOL.GetString()` function to convert each message into a Null-terminated string that can be displayed on a console device.

If `FormHiiHandle` is NULL, then no forms are returned from this function.

If `FormHiiHandle` is not NULL, and `HealthStatus` is `EfiDriverHealthStatusConfigurationRequired`, then no forms are returned and `*FormHiiHandle` must be set to NULL.

If `FormHiiHandle` is not NULL, and `FormSetGuid` is not NULL, and `HealthStatus` is `EfiDriverHealthStatusConfigurationRequired`, then `FormHiiHandle` is assigned to the HII handle which contains the HII form required to perform the configuration operation.

If `ControllerHandle` is NULL, and there are no devices being managed by the driver then `EFI_UNSUPPORTED` is returned.

**Related Definitions**

```c
typedef enum {
    EfiDriverHealthStatusHealthy,
    EfiDriverHealthStatusRepairRequired,
    EfiDriverHealthStatusConfigurationRequired,
    EfiDriverHealthStatusFailed,
    EfiDriverHealthStatusReconnectRequired,
    EfiDriverHealthStatusRebootRequired
} EFI_DRIVER_HEALTH_STATUS;
```
**EfiDriverHealthStatusHealthy**
- The controller is in a healthy state.

**EfiDriverHealthStatusRepairRequired**
- The controller requires a repair operation that will take an extended period of time to perform. The EFI Boot Manager is required to call the `Repair()` function when this state is detected. After the `Repair()` function completed, the health status may be `EfiDriverHealthStatusHealthy`, `EfiDriverHealthStatusConfigurationRequired`, or `EfiDriverHealthStatusFailed`.

**EfiDriverHealthStatusConfigurationRequired**
- The controller requires the user to make software or hardware configuration changes in order to put the controller into a healthy state. The set of software configuration changes are specified by the FormHiiHandle and Form-SetGuid parameters. The EFI Boot Manager may call the `EFI_FORM_BROWSER2_PROTOCOL.SendForm()` function to display configuration information and allow the user to make the required configuration changes. The HII form is the first enabled form in the form set class `EFI_HII_DRIVER_HEALTH_FORMSET_GUID`, which is installed on the returned HII handle `FormHiiHandle`. The `MessageList` parameter may be used to identify additional user configuration operations required to place the controller in a healthy state. After the `FormHiiHandle` and `MessageList` have been processed by the EFI Boot Manager, the health status may be `EfiDriverHealthStatusHealthy`, `EfiDriverHealthStatusRepairRequired`, `EfiDriverHealthStatusConfigurationRequired`, `EfiDriverHealthStatusConfigurationRequired`, `EfiDriverHealthStatusRepairRequired`, and `EfiDriverHealthStatusFailed`.

**EfiDriverHealthStatusFailed**
- The controller is in a failed state, and there are no actions that can place the controller into a healthy state. This controller cannot be used as a boot device and no boot devices behind this controller can be used as a boot device.

**EfiDriverHealthStatusReconnectRequired**
- A hardware and/or software configuration change was performed by the user, and the controller needs to be reconnected before the controller can be placed in a healthy state. The EFI Boot Manager is required to call the `EFI_BOOTSERVICE_DISCONNECTCONTROLLER()` followed by the `EFI_BOOTSERVICE_CONNECTCONTROLLER()` to reconnect the controller.

**EfiDriverHealthStatusRebootRequired**
- A hardware and/or software configuration change was performed by the user, and the controller requires the entire platform to be rebooted before the controller can be placed in a healthy state. The EFI Boot Manager should complete the configuration and repair operations on all the controllers that are not in a healthy state before rebooting the system.

```c
//******************************************************************************
// EFI_DRIVER_HEALTH_HII_MESSAGE
//******************************************************************************
typedef struct {
  EFI_HII_HANDLE HiiHandle;
  EFI_STRING_ID StringId;
  UINT64 MessageCode;
} EFI_DRIVER_HEALTH_HII_MESSAGE;
```

**HiiHandle**
- The `EFI_HII_HANDLE` that was returned by `EFI_HII_DATABASE_PROTOCOL.NewPackageList()` when the string pack containing `StringId` was registered with the HII Database.
**StringId**

The identifier for a single string token in the string pack associated with Hi Hibale.

**MessageCode**

64-bit numeric value of the warning/error specified by this message. A value of 0x0000000000000000 is used to indicate that MessageCode is not specified.

The values 0x0000000000000001 to 0x0fffffffffffffff are reserved for allocation by the UEFI Specification.

The values 0x1000000000000000 to 0x1fffffffffffffff are reserved for IHV-developed drivers.

The values 0x8000000000000000 to 0x8fffffffffffffff is reserved for platform/OEM drivers.

All other values are reserved and should not be used.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The health status of the controller specified by ControllerHandle and Child-Handle was returned in HealthStatus. A list of warning and error messages may be optionally returned in MessageList, and an HII Form may be optionally specified by FormHiiHandle.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>ControllerHandle is not NULL, and the controller specified by Controller-Handle and ChildHandle is not currently being managed by the driver specified by This.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>ControllerHandle is NULL and there are no devices being managed by the driver.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HealthStatus is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>MessageList is not NULL, and there are not enough resource available to allocate memory for MessageList.</td>
</tr>
</tbody>
</table>

**11.10.3 EFI_DRIVER_HEALTH_PROTOCOL.Repair()**

**Summary**

Performs a repair operation on a controller in the platform. This function can optionally report repair progress information back to the platform.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_DRIVER_HEALTH_REPAIR) (  
    IN EFI_DRIVER_HEALTH_PROTOCOL *This,  
    IN EFI_HANDLE ControllerHandle,  
    IN EFI_HANDLE ChildHandle OPTIONAL,  
    IN EFI_HANDLE EFI_DRIVER_HEALTH_REPAIR_NOTIFY RepairNotify OPTIONAL
);  
```

**Parameters**

**This**

A pointer to the EFI_DRIVER_HEALTH_PROTOCOL instance.

**ControllerHandle**

The handle of the controller to repair.

**ChildHandle**

The handle of the child controller to repair. This is an optional parameter that may be NULL. It will be NULL
for device drivers. It will also be NULL for bus drivers when an attempt is made to repair a bus controller. If will not be NULL when an attempt is made to repair a child controller produced by the driver.

**RepairNotify**
A notification function that may be used by a driver to report the progress of the repair operation. This is an optional parameter that may be NULL.

**Description**
This function repairs the controller specified by `ControllerHandle` and `ChildHandle`. If the driver specified by `This` is not currently managing the controller specified by `ControllerHandle` and `ChildHandle`, then `EFI_UNSUPPORTED` is returned. If there are not enough resource available to complete the repair operation, then `EFI_OUT_OF_RESOURCES` is returned. Otherwise, `EFI_SUCCESS` is returned. A return value of `EFI_SUCCESS` does not guarantee that the controller is in a healthy state. The EFI Boot Manager must call the `GetHealthStatus()` function to determine the result of the repair operation.

If `RepairNotify` is not NULL, and the repair operation requires an extended period of time to execute, then the driver performing the repair operation may intermittently call the `RepairNotify` function to inform the EFI Boot Manager of the progress of the repair operation. The `RepairNotify` function take two parameters to specify the current progress value and the limit value. These two values may be used by the EFI Boot Manager to present status information for the current repair operation.

**Related Definitions**

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_DRIVER_HEALTH_REPAIR_NOTIFY) (
    IN UINTN Value,
    IN UINTN Limit
);
```

**Value**
A value between 0 and Limit that identifies the current progress of the repair operation.

**Limit**
The maximum value of Value for the current repair operation. If Limit is 0, then the completion progress is indeterminate. For example, a driver that wants to specify progress in percent would use a Limit value of 100.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
</table>
| `EFI_SUCCESS`       | An attempt to repair the controller specified by `ControllerHandle` and `ChildHandle` was performed. The result of the repair operation can be determined by calling `GetHealthStatus()`.
| `EFI_UNSUPPORTED`   | The driver specified by `This` is not currently managing the controller specified by `ControllerHandle` and `ChildHandle`.
| `EFI_OUT_OF_RESOURCES` | There are not enough resources to perform the repair operation. |

11.10. EFI Driver Health Protocol
11.10.4 UEFI Boot Manager Algorithms

This section contains example algorithms that a UEFI Boot Manager or UEFI Application could use to interact with one or more instances of the EFI Driver Health Protocol present in the platform.

11.10.4.1 All Controllers Healthy

This section contains example algorithms that a UEFI Boot Manager or UEFI Application could use to interact with one or more instances of the EFI Driver Health Protocol present in the platform.

The following algorithm collects all the EFI Driver Health Protocols currently present in the EFI Handle Database, and queries each EFI Driver Health Protocol to determine if one or more of the controllers managed by each EFI Driver Health Protocol instance are not healthy. The variable AllHealthy is TRUE if all the controllers in the platform are healthy. AllHealthy is FALSE if one of more of the controllers in the platform are not healthy.

```c
EFI_STATUS Status;
UINTN NoHandles;
EFI_HANDLE *Handles;
UINTN Index;
EFI_DRIVER_HEALTH_PROTOCOL *DriverHealth;
BOOLEAN AllHealthy;

Status = gBS->LocateHandleBuffer (  
    ByProtocol,  
    &gEfiDriverHealthProtocolGuid,  
    NULL,  
    &NoHandles,  
    &Handles  
);
if (EFI_ERROR (Status)) {
    return;
}

AllHealthy = TRUE;
for (Index = 0; Index < NoHandles; Index++) {
    Status = gBS->HandleProtocol (  
        Handles[Index],  
        &gEfiDriverHealthProtocolGuid,  
        (VOID *) &DriverHealth  
    );
    if (!EFI_ERROR (Status)) {
        Status = DriverHealth->GetHealthStatus (  
            DriverHealth,  
            NULL,  
            NULL,  
            NULL,  
            NULL,  
            NULL  
        );
        if (EFI_ERROR (Status)) {
            AllHealthy = FALSE;
        }
    }
}
```

(continues on next page)
11.10.4.2 Process a Controller Until Terminal State Reached

The following algorithm processes a single controller using the EFI Driver Health Protocol associated with that controller. This algorithm continues to query the `GetHealthStatus()` service until one of the legal terminal states of the EFI Driver Health Protocol is reached. This may require the processing of HII Messages, HII Form, and invocation of repair operations.

```c
EFI_STATUS Status;
EFI_DRIVER_HEALTH_PROTOCOL *DriverHealth;
EFI_HANDLE ControllerHandle;
EFI_HANDLE ChildHandle;
EFI_DRIVER_HEALTH_HEALTH_STATUS HealthStatus;
EFI_DRIVER_HEALTH_HII_MESSAGE *MessageList;
EFI_HII_HANDLE FormHiiHandle;

do {
    HealthStatus = EfiDriverHealthStatusHealthy;
    Status = DriverHealth->GetHealthStatus (
        DriverHealth,
        ControllerHandle,
        ChildHandle,
        &HealthStatus,
        &MessageList,
        &FormHiiHandle
    );
    ProcessMessages (MessageList);
    if (HealthStatus == EfiDriverHealthStatusRepairRequired) {
        Status = DriverHealth->Repair (
            DriverHealth,
            ControllerHandle,
            ChildHandle,
            RepairNotify
        );
    }
    if (HealthStatus == EfiDriverHealthStatusConfigurationRequired) {
        ProcessForm (FormHiiHandle
    }
} while (HealthStatus == EfiDriverHealthStatusConfigurationRequired ||
    HealthStatus == EfiDriverHealthStatusRepairRequired);
//
// Check for RebootRequired or ReconnectRequired
//
```

11.10. EFI Driver Health Protocol
11.10.4.3 Repair Notification Function

The following is an example repair notification function.

```c
VOID
RepairNotify (  
    UINTN Value,  
    UINTN Limit  
)  
{
    UINTN Percent;

    if (Limit == 0) {
        Print (L"Repair Progress Undefined\n\r");
    } else {
        Percent = Value * 100 / Limit;
        Print (L"Repair Progress = %3d%%", Percent);
    }
}
```

11.10.4.4 Process Message List

The following algorithm processes a set of messages returned by the `GetHealthStatus()` service of the EFI Driver Health Protocol.

```c
EFI_STATUS Status;
EFI_DRIVER_HEALTH_HII_MESSAGE *MessageList;
UINTN MessageIndex;
EFI_HII_STRING_PROTOCOL *HiiString;
EFI_STRING MessageString [200];

for (MessageIndex = 0;
    MessageList[MessageIndex].HiiHandle != 0;
    MessageIndex++) {
    MessageLength = sizeof (MessageString);
    Status = HiiString->GetString (  
        HiiString,  
        NULL,  
        MessageList[MessageIndex].HiiHandle,  
        MessageList[MessageIndex].StringId,  
        MessageString  
        &MessageLength,  
        NULL  
    );
    if (!EFI_ERROR (Status)) {
        // Log or Print or Display MessageString
    }
}
```
11.10.4.5 Process HII Form

The following algorithm processes an HII Form returned by the GetHealthStatus() service of the EFI Driver Health Protocol.

```c
EFI_STATUS Status;
EFI_FORM_BROWSER2_PROTOCOL *FormBrowser;
EFI_HII_HANDLE FormHiiHandle;

Status = FormBrowser->SendForm(
    FormBrowser,
    &FormHiiHandle,
    1,
    &gEfiHiiDriverHealthFormsetGuid,
    ,
    0,
    NULL,
    NULL
);
```

11.10.5 UEFI Driver Algorithms

A UEFI Driver that supports the EFI Driver Health Protocol will typically make the following changes:

11.10.5.1 Driver Entry Point Updates

Install Driver Health Protocol on the driver image handle.
Register HII String/IFR packs with the HII Database.

- HII String/IFR packs can also be carried in a PE/COFF image extension eliminating the need for the driver to perform the registration
- The HII String and HII Forms may be produced dynamically when the GetHealthStatus() service is called.

11.10.5.2 Add global variable

Add global variable to track combined health status of all controllers managed by the driver. The variable is TRUE if all the controllers managed by the driver are healthy. The variable is FALSE if one or more controllers managed by the drover are not healthy.

11.10.5.3 Update private context structure

Update private context structure to track health status of each controller managed by the driver. This may also include the current set of HII Strings and HII Forms associated with the controllers that are not healthy.
11.10.5.4 Implement GetHealthStatus() service

Implement GetHealthStatus() service of the EFI Driver Health Protocol

- Make sure only legal state transitions are implemented
- Evaluate configuration data and repair status
- Return HII Strings for message(s) associated with the current state
- If configuration required, return HII Form to be processed

11.10.5.5 Implement Repair() service

Implement Repair() service of the EFI Driver Health Protocol

- Calling Repair Notification callback is optional, but recommended.
- Update health status in private context structure before returning
- Make sure only legal state transitions are implemented

11.11 EFI Adapter Information Protocol

This section provides a detailed description of the `EFI_ADAPTER_INFORMATION_PROTOCOL`. The EFI Adapter Information Protocol is used to dynamically and quickly discover or set device information for an adapter. The discovery of information and state of an adapter should be quick and only return dynamic information. The information should never be cached or stale. The setting information for the adapter should also be fast and simple. The only information that should be set is operating state information, like setting a speed. This protocol is meant to be light weight and non-blocking.

11.11.1 EFI_ADAPTER_INFORMATION_PROTOCOL

Summary

Since this protocol will return and set information for the adapter, the adapter device driver must publish the `EFI_ADAPTER_INFORMATION_PROTOCOL`.

There are many kinds of adapters. The set and get adapter information functions should be used to determine the current state of the adapter, or to set a state for an adapter, like device speed.

GUID

```c
#define EFI_ADAPTER_INFORMATION_PROTOCOL_GUID \
{ 0xE5DD1403, 0xD622, 0xC24E, \n  { 0x84, 0x88, 0xC7, 0x1B, 0x17, 0xF5, 0xE8, 0x02 } }
```

Protocol Interface Structure

```c
typedef struct _EFI_ADAPTER_INFORMATION_PROTOCOL {
  EFI_ADAPTER_INFO_GET_INFO GetInformation;
  EFI_ADAPTER_INFO_SET_INFO SetInformation;
  EFI_ADAPTER_INFO_GET_SUPPORTED_TYPES GetSupportedTypes;
} EFI_ADAPTER_INFORMATION_PROTOCOL;
```

Parameters

11.11. EFI Adapter Information Protocol 390
GetInformation

Gets device state information from adapter. See GetInformation() for more function description.

SetInformation

Sets device information for adapter. See SetInformation() for more function description.

GetSupportedTypes

Gets a list of supported information types for this instance of the protocol.

Description

The EFI_ADAPTER_INFORMATION_PROTOCOL is used to get or set the state for an adapter.

11.11.2 EFI_ADAPTER_INFORMATION_PROTOCOL.EFI_ADAPTER_GET_INFO()

Summary

Returns the current state information for the adapter.

Prototype

```c
typedef EFI_STATUS
(EIFIAP1 *EFI_ADAPTER_INFO_GET_INFO) (    
    IN EFI_ADAPTER_INFORMATION_PROTOCOL *This,     
    IN EFI_GUID *InformationType,              
    OUT VOID **InformationBlock,             
    OUT UINTN *InformationBlockSize);        
```

Parameters

This

A pointer to the EFI_ADAPTER_INFORMATION_PROTOCOL instance.

InformationType

A pointer to an EFI_GUID that defines the contents of InformationBlock. The caller must use the InformationType to specify the information it needs to retrieve from this service and to determine how to parse the InformationBlock. The driver should not attempt to free InformationType.

InformationBlock

This service returns a pointer to the buffer with the InformationBlock structure which contains details about the data specific to InformationType. This structure is defined based on the type of data returned, and will be different for different data types. This service and caller decode this structure and its contents based on InformationType. This buffer is allocated by this service, and it is the responsibility of the caller to free it after using it. Ignored if InformationBlockSize is 0.

InformationBlockSize

The driver returns the size of the InformationBlock in bytes.

Description

The GetInformation() function returns information of type InformationType from the adapter. If an adapter does not support the requested informational type, then EFI_UNSUPPORTED is returned. If an adapter does not contain Information for the requested InformationType, it fills InformationBlockSize with 0 and returns EFI_NOT_FOUND.

Status Codes Returned
11.11.3 EFI_ADAPTER_INFORMATION_PROTOCOL.EFI_ADAPTER_INFO_SET_INFO()

Summary
Sets state information for an adapter.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_ADAPTER_INFO_SET_INFO) (
    IN EFI_ADAPTER_INFORMATION_PROTOCOL *This,
    IN EFI_GUID *InformationType,
    IN VOID *InformationBlock,
    IN UINTN InformationBlockSize
);```

Parameters

**This**
A pointer to the `EFI_ADAPTER_INFORMATION_PROTOCOL` instance.

**InformationType**
A pointer to an `EFI_GUID` that defines the contents of `InformationBlock`. The caller must use the `InformationType` to specify the information it wants the service.

**InformationBlock**
A pointer to the `InformationBlock` structure which contains details about the data specific to `InformationType`. This structure is defined based on the type of data sent, and will be different for different data types. The driver and caller decode this structure and its contents based on `InformationType`. This buffer is allocated by the caller. It is the responsibility of the caller to free it after the caller has set the requested parameters.

**InformationBlockSize**
The size of the `InformationBlock` in bytes.

Description
The `SetInformation()` function sends information of type `InformationType` for an adapter. If an adapter does not support the requested informational type, then `EFI_UNSUPPORTED` is returned.

Related Definitions

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The <code>InformationType</code> information was received and interpreted successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The <code>InformationType</code> is not known.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>InformationBlock</code> is NULL</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>InformationBlockSize</code> is NULL</td>
</tr>
</tbody>
</table>

continues on next page
### 11.11.4 EFI_ADAPTER_INFORMATION_PROTOCOL . EFI_ADAPTER_INFO_GET_SUPPORTED_TYPES()

#### Summary

Get a list of supported information types for this instance of the protocol.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_ADAPTER_INFO_GET_SUPPORTED_TYPES)(
    IN EFI_ADAPTER_INFORMATION_PROTOCOL *This,
    OUT EFI_GUID **InfoTypesBuffer,
    OUT UINTN *InfoTypesBufferCount
);
```

#### Parameters

**This**

A pointer to the `EFI_ADAPTER_INFORMATION_PROTOCOL` instance.

**InfoTypesBuffer**

A pointer to the array of `InformationType` GUIDs that are supported by `This`. This buffer is allocated by this service, and it is the responsibility of the caller to free it after using it.

**InfoTypesBufferCount**

A pointer to the number of GUIDs present in `InfoTypesBuffer`.

#### Description

The `GetSupportedTypes()` function returns a list of `InformationType` GUIDs that are supported on an adapter with this instance of `EFI_ADAPTER_INFORMATION_PROTOCOL`. The list is returned in `InfoTypesBuffer`, and the number of GUID pointers in `InfoTypesBuffer` is returned in `InfoTypesBufferCount`.

#### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The list of information type GUIDs that are supported on this adapter was returned in <code>InfoTypesBuffer</code>. The number of information type GUIDs was returned in <code>InfoTypesBufferCount</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>This</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>InfoTypesBuffer</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>InfoTypesBufferCount</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There is not enough pool memory to store the results.</td>
</tr>
</tbody>
</table>

---

Table 11.18 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>This</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>InformationBlock</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The <code>InformationType</code> cannot be modified using <code>EFI_ADAPTER_INFO_SET_INFO()</code>.</td>
</tr>
</tbody>
</table>
11.12 EFI Adapter Information Protocol Information Types

Note: In addition to the information block types defined in this section, driver writers may define additional information type blocks for their own use provided all such blocks are each identified by a unique GUID created by the definer. Clients of the protocol should ignore any unrecognized block types returned by GetSupportedTypes().

11.12.1 Network Media State

For network adapters, the EFI_ADAPTER_INFORMATION_PROTOCOL must be installed on the same handle as the UNDI protocol. If SNP or MNP protocol, instead of the UNDI protocol, is installed on adapter handle, then the EFI_ADAPTER_INFORMATION_PROTOCOL must be installed on the same handle as the SNP or MNP protocol.

InformationType

```c
#define EFI_ADAPTER_INFO_MEDIA_STATE_GUID
{0xD7C74207, 0xA831, 0x4A26
 {0xB1,0xF5,0xD1,0x93,0x06,0x5C,0xE8,0xB6}}
```

Corresponding InformationBlock:

```c
typedef struct {
    EFI_STATUS MediaState;
} EFI_ADAPTER_INFO_MEDIA_STATE;
```

MediaState

Returns the current media state status. MediaState can have any of the following values:

EFI_SUCCESS : There is media attached to the network adapter.

EFI_NOT_READY : This detects a bounced state. There was media attached to the network adapter, but it was removed and is trying to attach to the network adapter again. If re-attached, the status will be updated to EFI_SUCCESS later.

EFI_NO_MEDIA : There is not any media attached to the network adapter.

11.12.2 Network Boot

For iSCSI and FCoE HBA adapters, the EFI_ADAPTER_INFORMATION_PROTOCOL must be installed on the same handle as the EFI_EXT_SCSI_PASS_THRU_PROTOCOL. When the EFI_EXT_SCSI_PASS_THRU_PROTOCOL cannot be installed because the adapter was not adequately configured, or if the relevant SCSI bus handles cannot be produced, this information must be installed on the controller handle that has been passed to the adapter Pass Thru Driver’s EFI_DRIVER_BINDING_PROTOCOL.Start() function. This will typically be a handle with the EFI_PCI_IO_PROTOCOL and EFI_DEVICE_PATH_PROTOCOL. If the handle with the EFI_EXT_SCSI_PASS_THRU_PROTOCOL is produced at a later time, the information on the controller handle must be uninstalled so as to avoid duplicate information.
**InformationType**

```c
#define EFI_ADAPTER_INFO_NETWORK_BOOT_GUID \
{0x1FBD2960, 0x4130, 0x41E5,\} 
{0x94,0xAC,0xD2, 0xCF, 0x03, 0x7F, 0xB3, 0x7C}}
```

**Corresponding InformationBlock**

```c
typedef struct {
    BOOLEAN iScsiIpv4BootCapability;
    BOOLEAN iScsiIpv6BootCapability;
    BOOLEAN FCoeBootCapability;
    BOOLEAN OffloadCapability;
    BOOLEAN iScsiMpioCapability
    BOOLEAN iScsiIpv4Boot;
    BOOLEAN iScsiIpv6Boot;
    BOOLEAN FCoeBoot;
} EFI_ADAPTER_INFO_NETWORK_BOOT;
```

- **iScsiIpv4BootCapability**
  - TRUE if the adapter supports booting from iSCSI IPv4 targets.

- **iScsiIpv6BootCapability**
  - TRUE if the adapter supports booting from iSCSI IPv6 targets.

- **FCoeBootCapability**
  - TRUE if the adapter supports booting from FCoE targets.

- **OffloadCapability**
  - TRUE if the adapter supports an offload engine (such as TCP Offload Engine (TOE) for its iSCSI or FCoE boot operations.

- **iScsiMpioCapability**
  - TRUE if the adapter supports multipath I/O (MPIO) for its iSCSI boot operations.

- **iScsiIpv4Boot**
  - TRUE if the adapter is currently configured to boot from iSCSI IPv4 targets.

- **iScsiIpv6Boot**
  - TRUE if the adapter is currently configured to boot from iSCSI IPv6 targets.

- **FCoeBoot**
  - TRUE if the adapter is currently configured to boot from FCoE targets.

**Note:** The adapter should set the **iScsiIpv4BootCapability**, **iScsiIpv6BootCapability**, or **FCoeBootCapability** fields to **TRUE** if it supports that boot capability, even if that capability is currently disabled or not configured.

### 11.12.3 SAN MAC Address

**Summary**

This information block for the **EFI_ADAPTER_INFORMATION_PROTOCOL** supports ascertaining the SAN MAC address for an FCOE-aware network interface controller. This address is the Fabric-Provided MAC Address (FPMA) that gets assigned to the adapter port after the fabric login.

**Note:** An instance of the **EFI_ADAPTER_INFORMATION_PROTOCOL** supporting this GUID must be installed on the same handle as the **EFI_EXT_SCSI_PASS_THRU_PROTOCOL** when it is produced. However, this address is available to the adapter only when the fabric login has occurred, so in cases where the login cannot happen, where the...
adapter was not adequately configured, or if the relevant SCSI bus handles cannot be produced, this information type may not be produced.

**SAN MAC address information** InformationType

```c
#define EFI_ADAPTER_INFO_SAN_MAC_ADDRESS_GUID \
{0x114da5ef, 0x2cf1, 0x4e12, \
  {0x9b, 0xbb, 0xc4, 0x70, 0xb5, 0x05, 0xd9}}
```

Corresponding InformationBlock

```c
typedef struct {
  EFI_MAC_ADDRESS SanMacAddress;
} EFI_ADAPTER_INFO_SAN_MAC_ADDRESS;
```

SanMacAddress

Returns the SAN MAC address for the adapter.

### 11.12.4 IPV6 Support from UNDI

For network adapters, the `EFI_ADAPTER_INFORMATION_PROTOCOL` must be installed on the same handle as the UNDI protocol.

- `Ipv6Support` returns capability of UNDI to support IPV6 traffic.
- `Ipv6Support` can have any of the following values:

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>TRUE</td>
<td>The UNDI supports IPV6.</td>
</tr>
<tr>
<td>FALSE</td>
<td>This UNDI does not support IPV6 traffic.</td>
</tr>
</tbody>
</table>

**InformationType**

```c
#define EFI_ADAPTER_INFO_UNDI_IPV6_SUPPORT_GUID \
{ 0x4bd56be3, 0x4975, 0x4d8a, \
  {0xa0, 0xad, 0xc4, 0x91, 0x20, 0x4b, 0x5d, 0x4d}}
```

Corresponding InformationBlock

```c
typedef struct {
  BOOLEAN Ipv6Support;
} EFI_ADAPTER_INFO_UNDI_IPV6_SUPPORT;
```

### 11.12.5 Network Media Type

For network adapters, the ` EFI_ADAPTER_INFORMATION_PROTOCOL` must be installed on the same handle as the UNDI protocol. If SNP or MNP protocol, instead of the UNDI protocol, is installed on adapter handle, then the `EFI_ADAPTER_INFORMATION_PROTOCOL` must be installed on the same handle as the SNP or MNP protocol.

**Information Type**
#define EFI_ADAPTER_INFO_MEDIA_TYPE_GUID \
{ 0x8484472f, 0x71ec, 0x411a, \
{ 0xb3, 0x9c, 0x62, 0xcd, 0x94, 0xd9, 0x91, 0x6e }}

Corresponding InformationBlock:

```c
typedef struct {
    UINT8 MediaType;
} EFI_ADAPTER_INFO_MEDIA_TYPE;
```

`MediaType` indicates the current media type, and can have any of the following values:

1: Ethernet Network Adapter
2: Ethernet Wireless Network Adapter
3~255: Reserved

## 11.12.6 Coherent Device Attribute Table (CDAT) Type

This section defines Adapter Information Protocol type for Coherent Device Attribute Table (CDAT). Compute Express Link (CXL) and other CPU-to-Memory interconnects enable coherent memory devices or coherent accelerator devices to be attached to the CPU. Unlike memory DIMMs, the system software or firmware may not have apriori knowledge of the attributes of memory located on these devices and would benefit from the device directly exposing the NUMA attributes such as latency and bandwidth characteristics. The necessary data structures are defined in the Coherent Device Attribute Table (CDAT) structures. For more information, refer to “Links to UEFI-Related Documents” (*http://uefi.org/uefi*) under the heading “Coherent Device Attribute Table (CDAT) Specification”.

**Note:** For CXL devices that support coherent memory, the EFI_ADAPTER_INFORMATION_PROTOCOL instance supporting this type may be installed by the EFI driver associated with this device on the device controller handle. This may happen during the driver initialization in the EFI_IMAGE_ENTRY_POINT of the driver, allowing for the CDAT structures to be published without relying on the Driver Model platform connect policy.

### Information Type

#define EFI_ADAPTER_INFO_CDAT_TYPE_GUID \ 
{0x77af24d1, 0xb6f0, 0x42b9, \ 
{0x83, 0xf5, 0x8f, 0xe6, 0xe8, 0x3e, 0xb6, 0xf0}}

Corresponding InformationBlock:

```c
typedef struct {
    UINTN CdatSize;
    UINT8 Cdat[];
} EFI_ADAPTER_INFO_CDAT_TYPE_TYPE;
```

`CdatSize` of the Cdat structure, in bytes.

CdatCoherent Device Attribute Table (CDAT) structures.
This section explores console support protocols, including SimpleText Input, Simple Text Output, Simple Pointer, Serial IO, and Graphics Output protocols.

12.1 Console I/O Protocol

This section defines the Console I/O protocol. This protocol is used to handle input and output of text-based information intended for the system user during the operation of code in the boot services environment. Also included here are the definitions of three console devices: one for input and one each for normal output and errors.

These interfaces are specified by function call definitions to allow maximum flexibility in implementation. For example, there is no requirement for compliant systems to have a keyboard or screen directly connected to the system. Implementations may choose to direct information passed using these interfaces in arbitrary ways provided that the semantics of the functions are preserved (in other words, provided that the information is passed to and from the system user).

12.1.1 Overview

The UEFI console is built out of the `EFI_SIMPLE_TEXT_INPUT_PROTOCOL` and the `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL`. These two protocols implement a basic text-based console that allows platform firmware, applications written to this specification, and UEFI OS loaders to present information to and receive input from a system administrator. The UEFI console supported 16-bit Unicode character codes, a simple set of input control characters (Scan Codes), and a set of output-oriented programmatic interfaces that give functionality equivalent to an intelligent terminal. The console does not support pointing devices on input or bitmaps on output.

This specification requires that the `EFI_SIMPLE_TEXT_INPUT_PROTOCOL` support the same languages as the corresponding `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL`. The `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL` is recommended to support at least the printable Basic Latin Unicode character set to enable standard terminal emulation software to be used with an EFI console. The Basic Latin Unicode character set implements a superset of ASCII that has been extended to 16-bit characters. Any number of other Unicode character sets may be optionally supported.
12.1.2 ConsoleIn Definition

The EFI_SIMPLE_TEXT_INPUT_PROTOCOL defines an input stream that contains Unicode characters and required EFI scan codes. Only the control characters defined in Supported Unicode Control Characters have meaning in the Unicode input or output streams. The control characters are defined to be characters U+0000 through U+001F. The input stream does not support any software flow control.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Unicode</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Null</td>
<td>U+0000</td>
<td>Null character ignored when received.</td>
</tr>
<tr>
<td>BS</td>
<td>U+0008</td>
<td>Backspace. Moves cursor left one column. If the cursor is at the left margin, no action is taken.</td>
</tr>
<tr>
<td>TAB</td>
<td>U+0x0009</td>
<td>Tab.</td>
</tr>
<tr>
<td>LF</td>
<td>U+000A</td>
<td>Linefeed. Moves cursor to the next line.</td>
</tr>
<tr>
<td>CR</td>
<td>U+000D</td>
<td>Carriage Return. Moves cursor to left margin of the current line.</td>
</tr>
</tbody>
</table>

The input stream supports Scan Codes in addition to Unicode characters. If the Scan Code is set to 0x00 then the Unicode character is valid and should be used. If the Scan Code is set to a non-0x00 value it represents a special key as defined by the Table EFI Scan Codes for EFI_SIMPLE_TEXT_INPUT_PROTOCOL.

12.2 Simple Text Input Ex Protocol

The Simple Text Input Ex protocol defines an extension to the Simple Text Input protocol which enables various new capabilities describes in this section.

12.2.1 EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL

Summary

This protocol is used to obtain input from the ConsoleIn device. The EFI specification requires that the EFI_SIMPLE_TEXT_INPUT_PROTOCOL supports the same languages as the corresponding EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.

GUID

```c
#define EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL_GUID \
{0xdd9e7534, 0x7762, 0x4698, \
 {0x8c, 0x14, 0xf5, 0x85, 0x17, 0xa6, 0x25, 0xaa}}
```

Protocol Interface Structure

```c
typedef struct _ EFI SIMPLE TEXT INPUT EX_PROTOCOL {  
EFI_INPUT_RESET_EX  Reset;  
EFI_INPUT_READ_KEY_EX ReadKeyStrokeEx;  
EFI_EVENT  WaitForKeyEx;  
EFI_SET_STATE  SetState;  
EFI_REGISTER_KEYSTROKE_NOTIFY RegisterKeyNotify;  
EFI_UNREGISTER_KEYSTROKE_NOTIFY UnregisterKeyNotify;  
} EFI SIMPLE TEXT INPUT EX_PROTOCOL;
```

Parameters
Reset
Reset the ConsoleIn device. See Reset().

ReadKeyStrokeEx
Returns the next input character. See ReadKeyStrokeEx().

WaitForKeyEx
Event to use with WaitForEvent() to wait for a key to be available. An Event will only be triggered if KeyData.Key has information contained within it.

SetState
Set the EFI_KEY_TOGGLE_STATE state settings for the input device.

RegisterKeyNotify
Register a notification function to be called when a given key sequence is hit.

UnregisterKeyNotify
Removes a specific notification function.

Description
The EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL is used on the ConsoleIn device. It is an extension to the Simple Text Input protocol which allows a variety of extended shift state information to be returned.

12.2.2 EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.Reset()

Summary
Resets the input device hardware.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_INPUT_RESET_EX) (
    IN EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL *This,
    IN BOOLEAN ExtendedVerification
);

Parameters
This
A pointer to the EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL instance. Type EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL is defined in this section.

ExtendedVerification
Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description
The Reset() function resets the input device hardware.

The implementation of Reset is required to clear the contents of any input queues resident in memory used for buffering keystroke data and put the input stream in a known empty state.

As part of initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the ExtendedVerification flag is TRUE the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.
Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device was reset.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device is not functioning correctly and could not be reset.</td>
</tr>
</tbody>
</table>

12.2.3 EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.ReadKeyStrokeEx()

Summary

Reads the next keystroke from the input device.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_INPUT_READ_KEY_EX) (
    IN EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL *This,
    OUT EFI_KEY_DATA *KeyData
);

Parameters

This

A pointer to the EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL instance. Type EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL is defined in this section.

KeyData

A pointer to a buffer that is filled in with the keystroke state data for the key that was pressed. Type EFI_KEY_DATA is defined in “Related Definitions” below.

Related Definitions

```c
//EFI_KEY_DATA
typedef struct {
    EFI_INPUT_KEY Key;
    EFI_KEY_STATE KeyState;
} EFI_KEY_DATA;
```

Key

The EFI scan code and Unicode value returned from the input device.

KeyState

The current state of various toggled attributes as well as input modifier values.

```c
//EFI_KEY_STATE
typedef struct EFI_KEY_STATE {
    UINT32 KeyShiftState;
};
```

(continues on next page)
KeyShiftState
Reflects the currently pressed shift modifiers for the input device. The returned value is valid only if the high order bit has been set.

KeyToggleState
Reflects the current internal state of various toggled attributes. The returned value is valid only if the high order bit has been set.

#define EFI_SHIFT_STATE_VALID 0x80000000
#define EFI_RIGHT_SHIFT_PRESSED 0x00000001
#define EFI_LEFT_SHIFT_PRESSED 0x00000002
#define EFI_RIGHT_CONTROL_PRESSED 0x00000004
#define EFI_LEFT_CONTROL_PRESSED 0x00000008
#define EFI_RIGHT_ALT_PRESSED 0x00000010
#define EFI_LEFT_ALT_PRESSED 0x00000020
#define EFI_RIGHT_LOGO_PRESSED 0x00000040
#define EFI_LEFT_LOGO_PRESSED 0x00000080
#define EFI_MENU_KEY_PRESSED 0x00000100
#define EFI_SYS_REQ_PRESSED 0x00000200

//*************************************************************
// EFI_KEY_TOGGLE_STATE
//*************************************************************
typedef UINT8 EFI_KEY_TOGGLE_STATE;

#define EFI_TOGGLE_STATE_VALID 0x80
#define EFI_KEY_STATE_EXPOSED 0x40
#define EFI_SCROLL_LOCK_ACTIVE 0x01
#define EFI_NUM_LOCK_ACTIVE 0x02
#define EFI_CAPS_LOCK_ACTIVE 0x04

Description
The ReadKeyStrokeExt() function reads the next keystroke from the input device. If there is no pending keystroke the function returns EFI_NOT_READY. If there is a pending keystroke, then KeyData.Key.ScanCode is the EFI scan code defined in EFI Scan Codes for EFI_SIMPLE_TEXT_INPUT_PROTOCOL. The KeyData.Key.UnicodeChar is the actual printable character or is zero if the key does not represent a printable character (control key, function key, etc.). The KeyData.KeyState is the modifier shift state for the character reflected in KeyData.Key.UnicodeChar or KeyData.Key.ScanCode. This function mirrors the behavior of ReadKeyStroke() in the Simple Input Protocol in that a keystroke will only be returned when KeyData.Key has data within it.

When interpreting the data from this function, it should be noted that if a class of printable characters that are normally adjusted by shift modifiers (e.g. Shift Key + “f” key) would be presented solely as a KeyData.Key.UnicodeChar without the associated shift state. So in the previous example of a Shift Key + “i” key being pressed, the only pertinent data returned would be KeyData.Key.UnicodeChar with the value of “F”. This of course would not typically be the case for non-printable characters such as the pressing of the Right Shift Key + F10 key since the corresponding returned data would be reflected both in the KeyData.KeyState.KeyShiftState and KeyData.KeyState.KeyToggleState. This function mirrors the behavior of ReadKeyStroke() in the Simple Input Protocol in that a keystroke will only be returned when KeyData.Key has data within it.

UEFI drivers which implement the EFI_SIMPLE_TEXT_INPUT_EX protocol are required to return KeyData.Key and KeyData.KeyState values. These drivers must always return the most current state of KeyData.KeyState.KeyShiftState and KeyData.KeyState.KeyToggleState. It should also be noted that certain input devices may not be able to produce shift or toggle state information, and in those cases the high order bit in the respective Toggle and Shift state fields...
should not be active.

If the `EFI_KEY_STATE_EXPOSED` bit is turned on, then this instance of the `EFI_SIMPLE_INPUT_EX_PROTOCOL` supports the ability to return partial keystrokes. With `EFI_KEY_STATE_EXPOSED` bit enabled, the `ReadKeyStrokeEx` function will allow the return of incomplete keystrokes such as the holding down of certain keys which are expressed as a part of `KeyState` when there is no `Key` data.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The keystroke information was returned.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>There was no keystroke data available. Current KeyData.KeyState values are exposed.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The keystroke information was not returned due to hardware errors.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The device does not support the ability to read keystroke data.</td>
</tr>
</tbody>
</table>

### 12.2.4 EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.SetState()

**Summary**

Set certain state for the input device.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_SET_STATE) (IN EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL *This,
                                          IN EFI_KEY_TOGGLE_STATE *KeyToggleState);
```

**Parameters**

- **This**
  
  A pointer to the `EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL` instance. Type `EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL` is defined in this section.

- **KeyToggleState**
  
  Pointer to the `EFI_KEY_TOGGLE_STATE` to set the state for the input device. Type `EFI_KEY_TOGGLE_STATE` is defined in “Related Definitions” for `EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.ReadKeyStrokeEx()` above.

The `SetState()` function allows the input device hardware to have state settings adjusted. By calling the `SetState()` function with the `EFI_KEY_STATE_EXPOSED` bit active in the `KeyToggleState` parameter, this will enable the `ReadKeyStrokeEx` function to return incomplete keystrokes such as the holding down of certain keys which are expressed as a part of `KeyState` when there is no `Key` data.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device state was set appropriately.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device is not functioning correctly and could not have the setting adjusted.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The device does not support the ability to have its state set or the requested state change was not supported.</td>
</tr>
</tbody>
</table>
12.2.5  EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.RegisterKeyNotify()

Summary
Register a notification function for a particular keystroke for the input device.

Prototype

```c
typedef
  EFI_STATUS
  (EFIAPI *EFI_REGISTER_KEYSTROKE_NOTIFY) (
    IN EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL *This,
    IN EFI_KEY_DATA *KeyData,
    IN EFI_KEY_NOTIFY_FUNCTION KeyNotificationFunction,
    OUT VOID **NotifyHandle
  );
```

Parameters

- **This**
  A pointer to the `EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL` instance. Type `EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL` is defined in this section.

- **KeyData**
  A pointer to a buffer that is filled in with the keystroke information for the key that was pressed. If `KeyData.Key`, `KeyData.KeyState.KeyToggleState` and `KeyData.KeyState.KeyShiftState` are 0, then any incomplete keystroke will trigger a notification of the `KeyNotificationFunction`.

- **KeyNotificationFunction**
  Points to the function to be called when the key sequence is typed specified by `KeyData`. This notification function should be called at `<= TPL_CALLBACK`. See `EFI_KEY_NOTIFY_FUNCTION` below.

- **NotifyHandle**
  Points to the unique handle assigned to the registered notification.

Description

The `RegisterKeyStrokeNotify()` function registers a function which will be called when a specified keystroke will occur. The keystroke being specified can be for any combination of `KeyData.Key` or `KeyData.KeyState` information.

Related Definitions

```c
// ********************************************************************************
// EFI_KEY_NOTIFY
// ********************************************************************************
typedef
  EFI_STATUS
  (EFIAPI \*EFI_KEY_NOTIFY_FUNCTION) (\n    IN EFI_KEY_DATA *KeyData
  );
```

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Key notify was registered successfully.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to allocate necessary data structures.</td>
</tr>
</tbody>
</table>
12.2.6 EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL.UnregisterKeyNotify()

Summary
Remove the notification that was previously registered.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_UNREGISTER_KEYSTROKE_NOTIFY) (
    IN EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL *This, 
    IN VOID *NotificationHandle 
);
```

**Parameters**

This
A pointer to the EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL instance. Type `EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL` is defined in this section.

NotificationHandle
The handle of the notification function being unregistered.

Description
The UnregisterKeystrokeNotify() function removes the notification which was previously registered.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Key notify was unregistered successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The NotificationHandle is invalid.</td>
</tr>
</tbody>
</table>

12.3 Simple Text Input Protocol

The Simple Text Input protocol defines the minimum input required to support the ConsoleIn device.

12.3.1 EFI_SIMPLE_TEXT_INPUT_PROTOCOL

Summary
This protocol is used to obtain input from the ConsoleIn device. The EFI specification requires that the `EFI_SIMPLE_TEXT_INPUT_PROTOCOL` supports the same languages as the corresponding `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL`.

GUID

```c
#define EFI_SIMPLE_TEXT_INPUT_PROTOCOL_GUID \ 
{0x387477c1,0x69c7,0x11d2,\ 
 {0xe,0x39,0x00,0xa0,0xc9,0x69,0x72,0x3b}}
```

Protocol Interface Structure
typedef struct _EFI_SIMPLE_TEXT_INPUT_PROTOCOL {
  EFI_INPUT_RESET       Reset;
  EFI_INPUT_READ_KEY    ReadKeyStroke;
  EFI_EVENT             WaitForKey;
} EFI_SIMPLE_TEXT_INPUT_PROTOCOL;

Parameters

Reset
Reset the ConsoleIn device, \textit{EFI_SIMPLE_TEXT_INPUT_PROTOCOL.Reset}().

ReadKeyStroke
Returns the next input character, \textit{EFI_SIMPLE_TEXT_INPUT_PROTOCOL.ReadKeyStroke}().

WaitForKey
Event to use with \textit{EFI_BOOT_SERVICES.WaitForEvent}() to wait for a key to be available.

Description
The \textit{EFI_SIMPLE_TEXT_INPUT_PROTOCOL} is used on the ConsoleIn device. It is the minimum required protocol for ConsoleIn.

12.3.2 \textit{EFI_SIMPLE_TEXT_INPUT_PROTOCOL.Reset}()

Summary
Resets the input device hardware.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_INPUT_RESET) (
  IN EFI_SIMPLE_TEXT_INPUT_PROTOCOL *This,
  IN BOOLEAN ExtendedVerification
);
```

Parameters

This
A pointer to the \textit{EFI_SIMPLE_TEXT_INPUT_PROTOCOL} instance. Type \textit{EFI_SIMPLE_TEXT_INPUT_PROTOCOL} is defined in \textit{EFI_SIMPLE_TEXT_INPUT_PROTOCOL}

ExtendedVerification
Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description
The \textit{Reset}() function resets the input device hardware.

The implementation of \textit{Reset} is required to clear the contents of any input queues resident in memory used for buffering keystroke data and put the input stream in a known empty state.

As part of initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the ExtendedVerification flag is \textbf{TRUE} the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.

12.3. Simple Text Input Protocol
Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device was reset.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device is not functioning correctly and could not be reset.</td>
</tr>
</tbody>
</table>

12.3.3 EFI_SIMPLE_TEXT_INPUT_PROTOCOL.ReadKeyStroke()

Summary

Reads the next keystroke from the input device.

Prototype

```c
typedef EFI_STATUS
  (EFIAPI *EFI_INPUT_READ_KEY) (   
    IN EFI_SIMPLE_TEXT_INPUT_PROTOCOL *This,
    OUT EFI_INPUT_KEY *Key
  );
```

Parameters

This

A pointer to the EFI_SIMPLE_TEXT_INPUT_PROTOCOL instance. Type EFI_SIMPLE_TEXT_INPUT_PROTOCOL is defined in `EFI_SIMPLE_TEXT_INPUT_PROTOCOL`.

Key

A pointer to a buffer that is filled in with the keystroke information for the key that was pressed. Type EFI_INPUT_KEY is defined in “Related Definitions” below.

Related Definitions

```c
typedef struct {   
  UINT16 ScanCode;
  CHAR16 UnicodeChar;
} EFI_INPUT_KEY;
```

Description

The ReadKeyStroke() function reads the next keystroke from the input device. If there is no pending keystroke the function returns EFI_NOT_READY. If there is a pending keystroke, then ScanCode is the EFI scan code defined in EFI Scan Codes for EFI_SIMPLE_TEXT_INPUT_PROTOCOL. The UnicodeChar is the actual printable character or is zero if the key does not represent a printable character (control key, function key, etc.).

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The keystroke information was returned.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>There was no keystroke data available.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The keystroke information was not returned due to hardware errors.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The device does not support the ability to read keystroke data.</td>
</tr>
</tbody>
</table>
12.3.4 ConsoleOut or StandardError

The `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL` must implement the same Unicode code pages as the `EFI_SIMPLE_TEXT_INPUT_PROTOCOL`. The protocol must also support the Unicode control characters defined in `Supported Unicode Control Characters`. The `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL` supports special manipulation of the screen by programmatic methods and therefore does not support the EFI scan codes defined in `EFI Scan Codes for EFI_SIMPLE_TEXT_INPUT_PROTOCOL`.

12.4 Simple Text Output Protocol

The Simple Text Output protocol defines the minimum requirements for a text-based ConsoleOut device. The EFI specification requires that the `EFI_SIMPLE_TEXT_INPUT_PROTOCOL` support the same languages as the corresponding `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL`.

### 12.4.1 EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL

**Summary**

This protocol is used to control text-based output devices.

**GUID**

```
#define EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL_GUID
{0x387477c2, 0x69c7, 0x11d2, 
  {0x8e, 0x39, 0x00, 0xa0, 0xc9, 0x72, 0x3b}}
```

**Protocol Interface Structure**

```
typedef struct _EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL {
  EFI_TEXT_RESET Reset;
  EFI_TEXT_STRING OutputString;
  EFI_TEXT_STRING TestString;
  EFI_TEXT_QUERY_MODE QueryMode;
  EFI_TEXT_SET_MODE SetMode;
  EFI_TEXT_SET_ATTRIBUTE SetAttribute;
  EFI_TEXT_CLEAR_SCREEN ClearScreen;
  EFI_TEXT_SET_CURSOR_POSITION SetCursorPosition;
  EFI_TEXT_ENABLE_CURSOR EnableCursor;
  simple_text_output_mode *Mode;
} EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL;
```

**Parameters**

- **Reset**
  
  Reset the ConsoleOut device. `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.Reset()`.

- **OutputString**
  
  Displays the string on the device at the current cursor location. See `OutputString()` `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.OutputString()`.

- **TestString**
  
  Tests to see if the ConsoleOut device supports this string. See `TestString()` `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.TestString()`.
QueryMode
Queries information concerning the output device’s supported text mode. See QueryMode()

EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.QueryMode() .

SetMode
Sets the current mode of the output device. EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.SetMode() .

SetAttribute
Sets the foreground and background color of the text that is output. EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.SetAttribute() .

ClearScreen
Clears the screen with the currently set background color. See ClearScreen()
EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.ClearScreen() .

SetCursorPosition
Sets the current cursor position. See SetCursorPosition() EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.SetCursorPosition() .

EnableCursor
Turns the visibility of the cursor on/off. See EnableCursor() EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.EnableCursor() .

Mode
Pointer to SIMPLE_TEXT_OUTPUT_MODE data. Type SIMPLE_TEXT_OUTPUT_MODE is defined in “Related Definitions” below.

The following data values in the SIMPLE_TEXT_OUTPUT_MODE interface are read-only and are changed by using the appropriate interface functions:

MaxMode
The number of modes supported by QueryMode() and SetMode().

Mode
The text mode of the output device(s).

Attribute
The current character output attribute.

CursorColumn
The cursor’s column.

CursorRow
The cursor’s row.

CursorVisible
The cursor is currently visible or not.

Related Definitions

```c
//**********************************************************
// SIMPLE_TEXT_OUTPUT_MODE
//**********************************************************
typedef struct {
    INT32 MaxMode;
    // current settings
    INT32 Mode;
    INT32 Attribute;
    INT32 CursorColumn;
    INT32 CursorRow;
} SIMPLE_TEXT_OUTPUT_MODE;
```

(continues on next page)
Description

The SIMPLE_TEXT_OUTPUT protocol is used to control text-based output devices. It is the minimum required protocol for any handle supplied as the ConsoleOut or StandardError device. In addition, the minimum supported text mode of such devices is at least 80 x 25 characters.

A video device that only supports graphics mode is required to emulate text mode functionality. Output strings themselves are not allowed to contain any control codes other than those defined in Supported Unicode Control Characters. Positional cursor placement is done only via the SetCursorPosition() function. It is highly recommended that text output to the StandardError device be limited to sequential string outputs. (That is, it is not recommended to use ClearScreen() or SetCursorPosition() on output messages to StandardError.)

If the output device is not in a valid text mode at the time of the EFI_BOOT_SERVICES.HandleProtocol() call, the device is to indicate that its CurrentMode is -1. On connecting to the output device the caller is required to verify the mode of the output device, and if it is not acceptable to set it to something it can use.

12.4.2 EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.Reset()

Summary

Resets the text output device hardware.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_TEXT_RESET)(
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,
    IN BOOLEAN ExtendedVerification
);
```

Parameters

This

A pointer to the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL instance. Type EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL is defined in the “Related Definitions” of EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.

ExtendedVerification

Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description

The Reset() function resets the text output device hardware. The cursor position is set to (0, 0), and the screen is cleared to the default background color for the output device.

As part of initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the ExtendedVerification flag is TRUE the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.
Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The text output device was reset.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The text output device is not functioning correctly and could not be reset.</td>
</tr>
</tbody>
</table>

12.4.3 EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.OutputString()

Summary
Writes a string to the output device.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_TEXT_STRING) ( 
  IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This, 
  IN CHAR16 *String
);
```

Parameters

This
A pointer to the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL instance. Type EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL is defined in the “Related Definitions” of Simple Text Output Protocol.

String
The Null-terminated string to be displayed on the output device(s). All output devices must also support the Unicode drawing character codes defined in “Related Definitions.”

Related Definitions

```c
//******************************************************
// UNICODE DRAWING CHARACTERS
//******************************************************

#define BOXDRAW_HORIZONTAL 0x2500
#define BOXDRAW_VERTICAL 0x2502
#define BOXDRAW_DOWN_RIGHT 0x250c
#define BOXDRAW_DOWN_LEFT 0x2510
#define BOXDRAW_UP_RIGHT 0x2514
#define BOXDRAW_UP_LEFT 0x2518
#define BOXDRAW_VERTICAL_RIGHT 0x251c
#define BOXDRAW_VERTICAL_LEFT 0x2524
#define BOXDRAW_DOWN_HORIZONTAL 0x252c
#define BOXDRAW_UP_HORIZONTAL 0x2534
#define BOXDRAW_VERTICAL_HORIZONTAL 0x253c

#define BOXDRAW_DOUBLE_HORIZONTAL 0x2550
#define BOXDRAW_DOUBLE_VERTICAL 0x2551
#define BOXDRAW_DOWN_RIGHT_DOUBLE 0x2552
#define BOXDRAW_DOWN_DOUBLE_RIGHT 0x2553
#define BOXDRAW_DOUBLE_DOWN_RIGHT 0x2554
#define BOXDRAW_DOWN_LEFT_DOUBLE 0x2555
```

(continues on next page)
```c
#define BOXDRAW_DOWN_DOUBLE_LEFT 0x2556  
#define BOXDRAW_DOUBLE_DOWN_LEFT 0x2557

#define BOXDRAW_UP_RIGHT_DOUBLE 0x2558  
#define BOXDRAW_UP_DOUBLE_RIGHT 0x2559  
#define BOXDRAW_DOUBLE_UP_RIGHT 0x255a  
#define BOXDRAW_UP_LEFT_DOUBLE 0x255b   
#define BOXDRAW_UP_DOUBLE_LEFT 0x255c   
#define BOXDRAW_DOUBLE_UP_LEFT 0x255d

#define BOXDRAW_VERTICAL_RIGHT_DOUBLE 0x255e  
#define BOXDRAW_VERTICAL_DOUBLE_RIGHT 0x255f  
#define BOXDRAW_DOUBLE_VERTICAL_RIGHT 0x2560

#define BOXDRAW_HORIZONTAL_DOWN_DOUBLE 0x2564  
#define BOXDRAW_DOWN_DOUBLE_HORIZONTAL 0x2565  
#define BOXDRAW_DOUBLE_DOWN_HORIZONTAL 0x2566

#define BOXDRAW_VERTICAL_LEFT_DOUBLE 0x2561  
#define BOXDRAW_VERTICAL_DOUBLE_LEFT 0x2562  
#define BOXDRAW_DOUBLE_VERTICAL_LEFT 0x2563

#define BOXDRAW_HORIZONTAL_UP_DOUBLE 0x2567  
#define BOXDRAW_UP_DOUBLE_HORIZONTAL 0x2568  
#define BOXDRAW_DOUBLE_UP_HORIZONTAL 0x2569

#define BOXDRAW_VERTICAL_HORIZONTAL_DOUBLE 0x256a  
#define BOXDRAW_VERTICAL_DOUBLE_HORIZONTAL 0x256b  
#define BOXDRAW_DOUBLE_VERTICAL_HORIZONTAL 0x256c

//***************************************************************
// EFI Required Block Elements Code Chart
//***************************************************************

#define BLOCKELEMENT_FULL_BLOCK 0x2588  
#define BLOCKELEMENT_LIGHT_SHADE 0x2591

//***************************************************************
// EFI Required Geometric Shapes Code Chart
//***************************************************************

#define GEOMETRICSHAPE_UP_TRIANGLE 0x25b2  
#define GEOMETRICSHAPE_RIGHT_TRIANGLE 0x25ba  
#define GEOMETRICSHAPE_DOWN_TRIANGLE 0x25bc  
#define GEOMETRICSHAPE_LEFT_TRIANGLE 0x25c4

//***************************************************************
// EFI Required Arrow Shapes
//***************************************************************

#define ARROW_UP 0x2191  
#define ARROW_DOWN 0x2193
```

12.4. Simple Text Output Protocol
Description

The OutputString() *EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL*::OutputString() function writes a string to the output device. This is the most basic output mechanism on an output device. The String is displayed at the current cursor location on the output device(s) and the cursor is advanced according to the rules listed in *EFI Cursor Location/Advance Rules*.

Table 12.10: EFI Cursor Location/Advance Rules

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Unicode</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Null</td>
<td>U+0000</td>
<td>Ignore the character, and do not move the cursor.</td>
</tr>
<tr>
<td>BS</td>
<td>U+0008</td>
<td>If the cursor is not at the left edge of the display, then move the cursor left one column.</td>
</tr>
<tr>
<td>LF</td>
<td>U+000A</td>
<td>If the cursor is at the bottom of the display, then scroll the display one row, and do not update the cursor position. Otherwise, move the cursor down one row.</td>
</tr>
<tr>
<td>CR</td>
<td>U+000D</td>
<td>Move the cursor to the beginning of the current row.</td>
</tr>
<tr>
<td>Other</td>
<td>U+XXXX</td>
<td>Print the character at the current cursor position and move the cursor right one column. If this moves the cursor past the right edge of the display, then the line should wrap to the beginning of the next line. This is equivalent to inserting a CR and an LF. Note that if the cursor is at the bottom of the display, and the line wraps, then the display will be scrolled one line.</td>
</tr>
</tbody>
</table>

Note: *If desired, the system’s NVRAM environment variables may be used at install time to determine the configured locale of the system or the installation procedure can query the user for the proper language support. This is then used to either install the proper EFI image/loader or to configure the installed image’s strings to use the proper text for the selected locale.*

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The string was output to the device.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while attempting to output the text.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The output device’s mode is not currently in a defined text mode.</td>
</tr>
<tr>
<td>EFI_WARN_UNKNOWN_GLYPH</td>
<td>This warning code indicates that some of the characters in the string could not be rendered and were skipped.</td>
</tr>
</tbody>
</table>

12.4.4 *EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL*.TestString()

Summary

Verifies that all characters in a string can be output to the target device.

Prototype

```c
typedef
EFI_STATUS
(EFIAPIC *EFI_TEXT_TEST_STRING) (  
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,  
    IN CHAR16 *String  
    ) ;
```

Parameters

This

A pointer to the *EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL* instance. Type *EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL* is defined in the “Related Definitions” of *Simple Text Output Protocol*. 

12.4. Simple Text Output Protocol
String

The Null-terminated string to be examined for the output device(s).

Description

The TestString() function verifies that all characters in a string can be output to the target device. This function provides a way to know if the desired character codes are supported for rendering on the output device(s). This allows the installation procedure (or EFI image) to at least select character codes that the output devices are capable of displaying. Since the output device(s) may be changed between boots, if the loader cannot adapt to such changes it is recommended that the loader call OUTPUTSTRING() \texttt{EFI\_SIMPLE\_TEXT\_OUTPUT\_PROTOCOL}::\texttt{OutputString()} with the text it has and ignore any “unsupported” error codes. Devices that are capable of displaying the Unicode character codes will do so.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\texttt{EFI_SUCCESS}</td>
<td>The device(s) are capable of rendering the output string.</td>
</tr>
<tr>
<td>\texttt{EFI_UNUnsupported}</td>
<td>Some of the characters in the string cannot be rendered by one or more of the output devices mapped by the EFI handle.</td>
</tr>
</tbody>
</table>

12.4.5 \texttt{EFI\_SIMPLE\_TEXT\_OUTPUT\_PROTOCOL}::\texttt{QueryMode()}

Summary

Returns information for an available text mode that the output device(s) supports.

Prototype

```c
typedef
EFI\_STATUS
(EFI\_API  *EFI\_TEXT\_QUERY\_MODE)  (  
   IN EFI\_SIMPLE\_TEXT\_OUTPUT\_PROTOCOL  \texttt{This},
   IN UINTN  \texttt{ModeNumber},
   OUT UINTN  \texttt{Columns},
   OUT UINTN  \texttt{Rows}
);
```

Parameters

\texttt{This}

A pointer to the \texttt{EFI\_SIMPLE\_TEXT\_OUTPUT\_PROTOCOL} instance. Type \texttt{EFI\_SIMPLE\_TEXT\_OUTPUT\_PROTOCOL} is defined in the “Related Definitions” of \textit{Simple Text Output Protocol}.

\texttt{ModeNumber}

The mode number to return information on.

\texttt{Columns, Rows}

Returns the geometry of the text output device for the request \texttt{ModeNumber}.

Description

The \texttt{QueryMode()} function returns information for an available text mode that the output device(s) supports. It is required that all output devices support at least 80x25 text mode. This mode is defined to be mode 0. If the output devices support 80x50, that is defined to be mode 1. All other text dimensions supported by the device will follow as modes 2 and above. If an output device supports modes 2 and above, but does not support 80x50, then querying for mode 1 will return \texttt{EFI\_UNSupported} .
Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested mode information was returned.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device had an error and could not complete the request.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The mode number was not valid.</td>
</tr>
</tbody>
</table>

12.4.6 EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.SetMode()

Summary

Sets the output device(s) to a specified mode.

Prototype

```c
typedef EFI_STATUS (*EFIAPI EFI_TEXT_SET_MODE) (  
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,  
    IN UINTN ModeNumber
);
```

Parameters

This

A pointer to the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL instance. Type EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL is defined in the “Related Definitions” of Simple Text Output Protocol.

ModeNumber

The text mode to set.

Description

The SetMode() function sets the output device(s) to the requested mode. On success the device is in the geometry for the requested mode, and the device has been cleared to the current background color with the cursor at (0,0).

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested text mode was set.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device had an error and could not complete the request.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The mode number was not valid.</td>
</tr>
</tbody>
</table>

12.4.7 EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.SetAttribute()

Summary

Sets the background and foreground colors for the OutputString(), EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.OutputString() and ClearScreen() EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.ClearScreen() functions.

Prototype

```c
typedef EFI_STATUS (EFIAPI EFI_TEXT_SET_ATTRIBUTE) (  
    IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,
    (continues on next page)
```
Parameters

This

A pointer to the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL instance. Type EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL is defined in the “Related Definitions” Simple Text Output Protocol.

Attribute

The attribute to set. Bits 0..3 are the foreground color, and bits 4..6 are the background color. All other bits are reserved. See “Related Definitions” below.

Related Definitions

```
#define EFI_BLACK 0x00
#define EFI_BLUE 0x01
#define EFI_GREEN 0x02
#define EFI_CYAN 0x03
#define EFI_RED 0x04
#define EFI_MAGENTA 0x05
#define EFI_BROWN 0x06
#define EFI_LIGHTGRAY 0x07
#define EFI_BRIGHT 0x08
#define EFI_DARKGRAY(EFI_BLACK | EFI_BRIGHT) 0x08
#define EFI_LIGHTBLUE 0x09
#define EFI_LIGHTGREEN 0x0A
#define EFI_LIGHTCYAN 0x0B
#define EFI_LIGHTRED 0x0C
#define EFI_LIGHTMAGENTA 0x0D
#define EFI_YELLOW 0x0E
#define EFI_WHITE 0x0F
#define EFI_BACKGROUND_BLACK 0x00
#define EFI_BACKGROUND_BLUE 0x10
#define EFI_BACKGROUND_GREEN 0x20
#define EFI_BACKGROUND_CYAN 0x30
#define EFI_BACKGROUND_RED 0x40
#define EFI_BACKGROUND_MAGENTA 0x50
#define EFI_BACKGROUND_BROWN 0x60
#define EFI_BACKGROUND_LIGHTGRAY 0x70
```

// Macro to accept color values in their raw form to create // a value that represents both a foreground and background // color in a single byte.

// For Foreground, and EFI_* value is valid from EFI_BLACK(0x00) // to EFI_WHITE (0x0F).

// For Background, only EFI_BLACK, EFI_BLUE, EFI_GREEN, EFI_CYAN, EFI_RED, EFI_MAGENTA, EFI_BROWN, and EFI_LIGHTGRAY

(continues on next page)
// are acceptable.
//
// Do not use EFI_BACKGROUND_xxx values with this macro.
//#define EFI_TEXT_ATTR(Foreground,Background) 
((Foreground) | ((Background) << 4))

Description
The SetAttribute() function sets the background and foreground colors for the OutputString() and ClearScreen() functions.

The color mask can be set even when the device is in an invalid text mode.

Devices supporting a different number of text colors are required to emulate the above colors to the best of the device’s capabilities.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested attributes were set.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device had an error and could not complete the request.</td>
</tr>
</tbody>
</table>

12.4.8 EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.ClearScreen()

Summary
Clears the output device(s) display to the currently selected background color.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_TEXT_CLEAR_SCREEN) (IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This);

Parameters

This

A pointer to the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL instance. Type EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL is defined in the “Related Definitions” of Simple Text Output Protocol.

Description
The ClearScreen() function clears the output device(s) display to the currently selected background color. The cursor position is set to (0, 0).

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device had an error and could not complete the request.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The output device is not in a valid text mode.</td>
</tr>
</tbody>
</table>
12.4.9 EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.SetCursorPosition()

Summary
Sets the current coordinates of the cursor position.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_TEXT_SET_CURSOR_POSITION) (    
  IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,    
  IN UINTN Column,    
  IN UINTN Row
);
```

Parameters

This
A pointer to the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL instance. Type
EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL is defined in the “Related Definitions” of Simple Text Output Protocol.

Column, Row
The position to set the cursor to. Must greater than or equal to zero and less than the number of columns and rows returned by EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.QueryMode().

Description
The SetCursorPosition() function sets the current coordinates of the cursor position. The upper left corner of the screen is defined as coordinate (0, 0).

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device had an error and could not complete the request.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The output device is not in a valid text mode, or the cursor position is invalid for the current mode.</td>
</tr>
</tbody>
</table>

12.4.10 EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.EnableCursor()

Summary
Makes the cursor visible or invisible.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_TEXT_ENABLE_CURSOR) (    
  IN EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL *This,    
  IN BOOLEAN Visible
);
```

Parameters

This
A pointer to the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL instance. Type

12.4. Simple Text Output Protocol
**EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL** is defined in the “Related Definitions” of *Simple Text Output Protocol*.

**Visible**

If **TRUE**, the cursor is set to be visible. If **FALSE**, the cursor is set to be invisible.

**Description**

The EnableCursor() function makes the cursor visible or invisible.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device had an error and could not complete the request or the device</td>
</tr>
<tr>
<td></td>
<td>does not support changing the cursor mode.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The output device does not support visibility control of the cursor.</td>
</tr>
</tbody>
</table>

### 12.5 Simple Pointer Protocol

This section defines the Simple Pointer Protocol and a detailed description of the **EFI_SIMPLE_POINTER_PROTOCOL**. The intent of this section is to specify a simple method for accessing pointer devices. This would include devices such as mice and trackballs.

The **EFI_SIMPLE_POINTER_PROTOCOL** allows information about a pointer device to be retrieved. This would include the status of buttons and the motion of the pointer device since the last time it was accessed. This protocol is attached the device handle of a pointer device, and can be used for input from the user in the preboot environment.

#### 12.5.1 EFI_SIMPLE_POINTER_PROTOCOL

**Summary**

Provides services that allow information about a pointer device to be retrieved.

**GUID**

```c
#define EFI_SIMPLE_POINTER_PROTOCOL_GUID \\  {0x31878c87,0xb75,0x11d5,\ \\  {0x9a,0x4f,0x00,0x90,0x27,0x3f,0xc1,0x4d}}
```

**Protocol Interface Structure**

```c
typedef struct \_EFI_SIMPLE_POINTER_PROTOCOL {
    EFI_SIMPLE_POINTER_RESET Reset;
    EFI_SIMPLE_POINTER_GET_STATE GetState;
    EFI_EVENT WaitForInput;
    EFI_SIMPLE_INPUT_MODE *Mode;
} EFI_SIMPLE_POINTER_PROTOCOL;
```

**Parameters**

**Reset**

Resets the pointer device. **EFI_SIMPLE_POINTER_PROTOCOL.Reset()** function description.

**GetState**

Retrieves the current state of the pointer device, **EFI_SIMPLE_POINTER_PROTOCOL.GetState()** function description.
WaitForInput

Event to use with \texttt{EFI\_BOOT\_SERVICES.WaitForEvent()} to wait for input from the pointer device.

Mode

Pointer to \texttt{EFI\_SIMPLE\_POINTER\_MODE} data. The type \texttt{EFI\_SIMPLE\_POINTER\_MODE} is defined in “Related Definitions” below.

Related Definitions

```c
//*****************************************************************************
// EFI\_SIMPLE\_POINTER\_MODE
//*****************************************************************************
typedef struct {
    UINT64 ResolutionX;
    UINT64 ResolutionY;
    UINT64 ResolutionZ;
    BOOLEAN LeftButton;
    BOOLEAN RightButton;
} EFI\_SIMPLE\_POINTER\_MODE;
```

The following data values in the \texttt{EFI\_SIMPLE\_POINTER\_MODE} interface are read-only and are changed by using the appropriate interface functions:

ResolutionX

The resolution of the pointer device on the x-axis in counts/mm. If 0, then the pointer device does not support an x-axis.

ResolutionY

The resolution of the pointer device on the y-axis in counts/mm. If 0, then the pointer device does not support a y-axis.

ResolutionZ

The resolution of the pointer device on the z-axis in counts/mm. If 0, then the pointer device does not support a z-axis.

LeftButton

\texttt{TRUE} if a left button is present on the pointer device. Otherwise \texttt{FALSE}.

RightButton

\texttt{TRUE} if a right button is present on the pointer device. Otherwise \texttt{FALSE}.

Description

The \texttt{EFI\_SIMPLE\_POINTER\_PROTOCOL} provides a set of services for a pointer device that can use used as an input device from an application written to this specification. The services include the ability to reset the pointer device, retrieve the state of the pointer device, and retrieve the capabilities of the pointer device.

12.5.2 \texttt{EFI\_SIMPLE\_POINTER\_PROTOCOL.Reset()}

Summary

Resets the pointer device hardware.

Prototype

```c
typedef
EFI\_STATUS
(EFI\_API \*EFI\_SIMPLE\_POINTER\_RESET) (```

(continues on next page)
IN EFI_SIMPLE_POINTER_PROTOCOL *This,
IN BOOLEAN ExtendedVerification
);

Parameters

This
A pointer to the EFI_SIMPLE_POINTER_PROTOCOL instance. Type EFI_SIMPLE_POINTER_PROTOCOL is defined in Simple Pointer Protocol.

ExtendedVerification
Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description
This Reset() function resets the pointer device hardware. As part of initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the ExtendedVerification flag is TRUE the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible. The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device was reset.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device is not functioning correctly and could not be reset.</td>
</tr>
</tbody>
</table>

12.5.3 EFI_SIMPLE_POINTER_PROTOCOL.GetState()

Summary
Retrieves the current state of a pointer device.

Prototype

typedef
EFI_STATUS
(EIFIAPIC *EFI_SIMPLE_POINTER_GET_STATE)
    IN EFI_SIMPLE_POINTER_PROTOCOL *This,
    OUT EFI_SIMPLE_POINTER_STATE *State
);

Parameters

This
A pointer to the EFI_SIMPLE_POINTER_PROTOCOL instance. Type EFI_SIMPLE_POINTER_PROTOCOL is defined in Simple Pointer Protocol.

State
A pointer to the state information on the pointer device. Type EFI_SIMPLE_POINTER_STATE is defined in “Related Definitions” below.

Related Definitions

//*******************************************************************************
// EFI_SIMPLE_POINTER_STATE
//*******************************************************************************

(continues on next page)
typedef struct {
    INT32 RelativeMovementX;
    INT32 RelativeMovementY;
    INT32 RelativeMovementZ;
    BOOLEAN LeftButton;
    BOOLEAN RightButton;
} EFI_SIMPLE_POINTER_STATE;

RelativeMovementX

The signed distance in counts that the pointer device has been moved along the x-axis. The actual distance moved is RelativeMovementX / ResolutionX millimeters. If the ResolutionX field of the EFI_SIMPLE_POINTER_MODE see EFI_SIMPLE_POINTER_PROTOCOL structure is 0, then this pointer device does not support an x-axis, and this field must be ignored.

RelativeMovementY

The signed distance in counts that the pointer device has been moved along the y-axis. The actual distance moved is RelativeMovementY / ResolutionY millimeters. If the ResolutionY field of the EFI_SIMPLE_POINTER_MODE see EFI_SIMPLE_POINTER_PROTOCOL structure is 0, then this pointer device does not support a y-axis, and this field must be ignored.

RelativeMovementZ

The signed distance in counts that the pointer device has been moved along the z-axis. The actual distance moved is RelativeMovementZ / ResolutionZ millimeters. If the ResolutionZ field of the EFI_SIMPLE_POINTER_MODE structure is 0, then this pointer device does not support a z-axis, and this field must be ignored.

LeftButton

If TRUE, then the left button of the pointer device is being pressed. If FALSE, then the left button of the pointer device is not being pressed. If the LeftButton field of the EFI_SIMPLE_POINTER_MODE see EFI_SIMPLE_POINTER_PROTOCOL structure is FALSE, then this field is not valid, and must be ignored.

RightButton

If TRUE, then the right button of the pointer device is being pressed. If FALSE, then the right button of the pointer device is not being pressed. If the RightButton field of the EFI_SIMPLE_POINTER_MODE structure is FALSE, then this field is not valid, and must be ignored.

Description

The GetState() function retrieves the current state of a pointer device. This includes information on the buttons associated with the pointer device and the distance that each of the axes associated with the pointer device has been moved. If the state of the pointer device has not changed since the last call to GetState(), then EFI_NOT_READY is returned. If the state of the pointer device has changed since the last call to GetState(), then the state information is placed in State, and EFI_SUCCESS is returned. If a device error occurs while attempting to retrieve the state information, then EFI_DEVICE_ERROR is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The state of the pointer device was returned in State.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The state of the pointer device has not changed since the last call to GetState().</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to retrieve the pointer device's current state.</td>
</tr>
</tbody>
</table>
12.6 EFI Simple Pointer Device Paths

An EFI Simple Pointer Device Paths must be installed on a handle for its services to be available to drivers and applications written to this specification. In addition to the EFI_SIMPLE_POINTER_PROTOCOL, an EFI Device Path Protocol must also be installed on the same handle. EFI Device Path Protocol for a detailed description of the EFI_DEVICE_PATH_PROTOCOL.

A device path describes the location of a hardware component in a system from the processor's point of view. This includes the list of busses that lie between the processor and the pointer controller. The UEFI Specification takes advantage of the ACPI Specification to name system components. The following set of examples efi-device-path-protocol shows sample device paths for a PS/2* mouse, a serial mouse, and a USB mouse.

The Table below shows an example device path for a PS/2 mouse that is located behind a PCI to ISA bridge that is located at PCI device number 0x07 and PCI function 0x00, and is directly attached to a PCI root bridge. This device path consists of an ACPI Device Path Node for the PCI Root Bridge, a PCI Device Path Node for the PCI to ISA bridge, an ACPI Device Path Node for the PS/2 mouse, and a Device Path End Structure. The _HID and _UID of the first ACPI Device Path Node must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI(PNP0A03,0)/PCI(7,0)/ACPI(PNP0F03,0):

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x04</td>
<td>0x41D0, 0x0F03</td>
<td>_HID PNP0A03 - 0x41D0 represents a compressed string ‘PNP’ and is in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x1E</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x1F</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x20</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

Serial Mouse Device Path shows an example device path for a serial mouse that is located on COM 1 behind a PCI to ISA bridge that is located at PCI device number 0x07 and PCI function 0x00. The PCI to ISA bridge is directly...
attached to a PCI root bridge, and the communications parameters for COM 1 are 1200 baud, no parity, 8 data bits, and 1 stop bit. This device path consists of an ACPI Device Path Node for the PCI Root Bridge, a PCI Device Path Node for the PCI to ISA bridge, an ACPI Device Path Node for COM 1, a UART Device Path Node for the communications parameters, an ACPI Device Path Node for the serial mouse, and a Device Path End Structure. The _HID and _UID of the first ACPI Device Path Node must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI(PNP0A03,0)/PCI(7,0)/ACPI(PNP0501,0)/UART(1200,N,8,1)/ACPI(PNP0F01,0)

Table 12.21: Serial Mouse Device Path

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0,</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0A03</td>
<td>‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x04</td>
<td>0x41D0,</td>
<td>_HID PNP0501 - 0x41D0 represents the compressed string</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0501</td>
<td>‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x1E</td>
<td>0x01</td>
<td>0x03</td>
<td>Generic Device Path Header - Messaging Device Path</td>
</tr>
<tr>
<td>0x1F</td>
<td>0x01</td>
<td>0x0E</td>
<td>Sub type - UART Device Path</td>
</tr>
<tr>
<td>0x20</td>
<td>0x02</td>
<td>0x13</td>
<td>Length - 0x13 bytes</td>
</tr>
<tr>
<td>0x22</td>
<td>0x04</td>
<td>0x00</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x26</td>
<td>0x08</td>
<td>1200</td>
<td>Baud Rate</td>
</tr>
<tr>
<td>0x2E</td>
<td>0x01</td>
<td>0x08</td>
<td>Data Bits</td>
</tr>
<tr>
<td>0x2F</td>
<td>0x01</td>
<td>0x01</td>
<td>Parity</td>
</tr>
<tr>
<td>0x30</td>
<td>0x01</td>
<td>0x01</td>
<td>Stop Bits</td>
</tr>
<tr>
<td>0x31</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x32</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x33</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x35</td>
<td>0x04</td>
<td>0x41D0,</td>
<td>_HID PNP0F01 - 0x41D0 represents the compressed string</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0F01</td>
<td>‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x39</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x3D</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x3E</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x3F</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

See USB Mouse Device Path shows an example device path for a USB mouse that is behind a PCI to USB host controller that is located at PCI device number 0x07 and PCI function 0x02. The PCI to USB host controller is directly attached to
a PCI root bridge. This device path consists of an ACPI Device Path Node for the PCI Root Bridge, a PCI Device Path Node for the PCI to USB controller, a USB Device Path Node, and a Device Path End Structure. The _HID and _UID of the first ACPI Device Path Node must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

`ACPI(PNP0A03,0)/PCI(7,2)/USB(0,0)`

### Table 12.22: USB Mouse Device Path

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents a compressed string 'PNP' and is in the low order bytes.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x02</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x03</td>
<td>Generic Device Path Header - Type Messaging Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x05</td>
<td>Sub type - USB</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x01</td>
<td>0x00</td>
<td>USB Port Number</td>
</tr>
<tr>
<td>0x17</td>
<td>0x01</td>
<td>0x00</td>
<td>USB Endpoint Number</td>
</tr>
<tr>
<td>0x18</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x19</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

## 12.7 Absolute Pointer Protocol

This section defines the Absolute Pointer Protocol and a detailed description of the `EFI_ABSOLUTE_POINTER_PROTOCOL`. The intent of this section is to specify a simple method for accessing absolute pointer devices. This would include devices like touch screens, and digitizers.

The `EFI_ABSOLUTE_POINTER_PROTOCOL` allows information about a pointer device to be retrieved. This would include the status of buttons and the coordinates of the pointer device on the last time it was activated. This protocol is attached to the device handle of an absolute pointer device, and can be used for input from the user in the preboot environment.

Supported devices may return 1, 2, or 3 axis of information. The Z axis may optionally be used to return pressure data measurements derived from user pen force.

All supported devices must support a touch-active status. Supported devices may optionally support a second input button, for example a pen side-button.
12.7.1 EFI_ABSOLUTE_POINTER_PROTOCOL

Summary
Provides services that allow information about an absolute pointer device to be retrieved.

GUID

```
#define EFI_ABSOLUTE_POINTER_PROTOCOL_GUID \
{0x8D59D32B, 0xC655, 0x4AE9, \ 
 {0x9B, 0x15, 0xF2, 0x59, 0x04, 0x99, 0x2A, 0x43}}
```

Protocol Interface Structure

```
typedef struct _EFI_ABSOLUTE_POINTER_PROTOCOL {
  EFI_ABSOLUTE_POINTER_RESET Reset;
  EFI_ABSOLUTE_POINTER_GET_STATE GetState;
  EFI_EVENT WaitForInput;
  EFI_ABSOLUTE_POINTER_MODE *Mode;
} EFI_ABSOLUTE_POINTER_PROTOCOL;
```

Parameters

**Reset**
Resets the pointer device. See the `Reset()` function description.

**GetState**
Retrieves the current state of the pointer device. See the `GetState()` function description.

**WaitForInput**
Event to use with `WaitForEvent()` to wait for input from the pointer device.

**Mode**
Pointer to `EFI_ABSOLUTE_POINTER_MODE` data. The type `EFI_ABSOLUTE_POINTER_MODE` is defined in “Related Definitions” below.

Related Definitions

```
//****************************************************
// EFI_ABSOLUTE_POINTER_MODE
//****************************************************
typedef struct {
  UINT64 AbsoluteMinX;
  UINT64 AbsoluteMinY;
  UINT64 AbsoluteMinZ;
  UINT64 AbsoluteMaxX;
  UINT64 AbsoluteMaxY;
  UINT64 AbsoluteMaxZ;
  UINT32 Attributes;
} EFI_ABSOLUTE_POINTER_MODE;
```

The following data values in the `EFI_ABSOLUTE_POINTER_MODE` interface are read-only and are changed by using the appropriate interface functions:

**AbsoluteMinX**
The Absolute Minimum of the device on the x-axis

**AbsoluteMinY**
The Absolute Minimum of the device on the y-axis.
AbsoluteMinZ
The Absolute Minimum of the device on the z-axis.

AbsoluteMaxX
The Absolute Maximum of the device on the x-axis. If 0, and the AbsoluteMinX is 0, then the pointer device
does not support a x-axis.

AbsoluteMaxY
The Absolute Maximum of the device on the y-axis. If 0, and the AbsoluteMinY is 0, then the pointer device
does not support a y-axis.

AbsoluteMaxZ
The Absolute Maximum of the device on the z-axis. If 0, and the AbsoluteMinZ is 0, then the pointer device
does not support a z-axis.

Attributes
The following bits are set as needed (or’d together) to indicate the capabilities of the device supported. The
remaining bits are undefined and should be returned as 0.

```c
#define EFI_ABSP_SupportsAltActive 0x00000001
#define EFI_ABSP_SupportsPressureAsZ 0x00000002
```

- EFI_ABSP_SupportsAltActive
  If set, indicates this device supports an alternate button input.

- EFI_ABSP_SupportsPressureAsZ
  If set, indicates this device returns pressure data in parameter CurrentZ.

The driver is not permitted to return all zeros for all three pairs of Min and Max as this would indicate no axis supported.

Description
The EFI_ABSOLUTE_POINTER_PROTOCOL provides a set of services for a pointer device that can be used as an
input device from an application written to this specification. The services include the ability to reset the pointer device,
retrieve the state of the pointer device, and retrieve the capabilities of the pointer device. In addition certain data items
describing the device are provided.

12.7.2 EFI_ABSOLUTE_POINTER_PROTOCOL.Reset()

Summary
Resets the pointer device hardware.

Prototype

```c
typedef EFI_STATUS
(EIFIAPI *EFI_ABSOLUTE_POINTER_RESET) (   
    IN EFI_ABSOLUTE_POINTER_PROTOCOL Protocols,   
    IN BOOLEAN ExtendedVerification   
);   
```

Parameters

- This
  A pointer to the EFI_ABSOLUTE_POINTER_PROTOCOL instance. Type
  EFI_ABSOLUTE_POINTER_PROTOCOL is defined in this section.
ExtendedVerification
Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description
This Reset() function resets the pointer device hardware. As part of initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the ExtendedVerification flag is TRUE the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.

Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device was reset.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device is not functioning correctly and could not be reset.</td>
</tr>
</tbody>
</table>

12.7.3 EFI_ABSOLUTE_POINTER_PROTOCOL.GetState()

Summary
Retrieves the current state of a pointer device.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_ABSOLUTE_POINTER_GET_STATE) (IN EFI_ABSOLUTE_POINTER_PROTOCOL *This, OUT EFI_ABSOLUTE_POINTER_STATE *State);

Parameters

This
A pointer to EFI_ABSOLUTE_POINTER_PROTOCOL instance. Type EFI_ABSOLUTE_POINTER_PROTOCOL is defined in EFI_ABSOLUTE_POINTER_PROTOCOL.

State
A pointer to the state information on the pointer device. Type EFI_ABSOLUTE_POINTER_STATE is defined in “Related Definitions” below.

Related Definitions

```c
//EFI_ABSOLUTE_POINTER_STATE
typedef struct
{
  UINT64 CurrentX;
  UINT64 CurrentY;
  UINT64 CurrentZ;
  UINT32 ActiveButtons;
} EFI_ABSOLUTE_POINTER_STATE;
```

CurrentX
The unsigned position of the activation on the x axis If the AboluteMinX and the AboluteMaxX fields of the
EFI_ABSOLUTE_POINTER_MODE structure are both 0, then this pointer device does not support an x-axis, and this field must be ignored.

**CurrentY**
The unsigned position of the activation on the y axis. If the AboluteMinY and the AboluteMaxY fields of the EFI_ABSOLUTE_POINTER_MODE structure are both 0, then this pointer device does not support a y-axis, and this field must be ignored.

**CurrentZ**
The unsigned position of the activation on the z axis, or the pressure measurement. If the AboluteMinZ and the AboluteMaxZ fields of the EFI_ABSOLUTE_POINTER_MODE structure are both 0, then this pointer device does not support a z-axis, and this field must be ignored.

**ActiveButtons**
Bits are set to 1 in this structure item to indicate that device buttons are active.

### Related Definitions
```c
//*****************************
//definitions of bits within ActiveButtons
//*****************************
#define EFI_ABSP_TouchActive 0x00000001
#define EFI_ABS_AltActive 0x00000002
```

**EFI_ABSP_TouchActive** This bit is set if the touch sensor is active.

**EFI_ABS_AltActive** This bit is set if the alt sensor, such as pen-side button, is active.

### Description
The GetState() function retrieves the current state of a pointer device. This includes information on the active state associated with the pointer device and the current position of the axes associated with the pointer device. If the state of the pointer device has not changed since the last call to GetState(), then EFI_NOT_READY is returned. If the state of the pointer device has changed since the last call to GetState(), then the state information is placed in State, and EFI_SUCCESS is returned. If a device error occurs while attempting to retrieve the state information, then EFI_DEVICE_ERROR is returned.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The state of the pointer device was returned in State.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The state of the pointer device has not changed since the last call to GetState().</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to retrieve the pointer device's current state.</td>
</tr>
</tbody>
</table>

## 12.8 Serial I/O Protocol

This section defines the Serial I/O protocol. This protocol is used to abstract byte stream devices.
12.8.1 EFI_SERIAL_IO_PROTOCOL

Summary
This protocol is used to communicate with any type of character-based I/O device.

GUID

```
#define EFI_SERIAL_IO_PROTOCOL_GUID \ 
{0xBB25CF6F,0xF1D4,0x11D2,\ 
{0x9a,0x0c,0x00,0x90,0x27,0x3f,0xc1,0xfd}}
```

Revision Number

```
#define EFI_SERIAL_IO_PROTOCOL_REVISION 0x00010000
#define EFI_SERIAL_IO_PROTOCOL_REVISION1p1 0x00010001
```

Protocol Interface Structure

```
typedef struct {
    UINT32 Revision;
    EFI_SERIAL_RESET Reset;
    EFI_SERIAL_SET_ATTRIBUTES SetAttributes;
    EFI_SERIAL_SET_CONTROL_BITS SetControl;
    EFI_SERIAL_GET_CONTROL_BITS GetControl;
    EFI_SERIAL_WRITE Write;
    EFI_SERIAL_READ Read;
    SERIAL_IO_MODE *Mode;
    CONST EFI_GUID *DeviceTypeGuid; // Revision 1.1
} EFI_SERIAL_IO_PROTOCOL;
```

Parameters

Revision
The revision to which the EFI_SERIAL_IO_PROTOCOL adheres. All future revisions must be backwards com-
patible. If a future version is not back wards compatible, it is not the same GUID.

Reset
Resets the hardware device.

SetAttributes
Sets communication parameters for a serial device. These include the baud rate, receive FIFO depth, transmit/receive time out, parity, data bits, and stop bit attributes.

SetControl
Sets the control bits on a serial device. These include Request to Send and Data Terminal Ready.

GetControl
Reads the status of the control bits on a serial device. These include Clear to Send, Data Set Ready, Ring Indicator, and Carrier Detect.

Write
Sends a buffer of characters to a serial device.

Read
Receives a buffer of characters from a serial device.

Mode
Pointer to SERIAL_IO_MODE data. Type SERIAL_IO_MODE is defined in “Related Definitions” below.
DeviceTypeGuid
Pointer to a GUID identifying the device connected to the serial port. This field is NULL when the protocol is installed by the serial port driver and may be populated by a platform driver for a serial port with a known device attached. The field will remain NULL if there is no platform serial device identification information available.

Related Definitions

```c
//****************************************************
// SERIAL_IO_MODE
//----------------------------------------------------------------------------
typedef struct {
    UINT32 ControlMask;

    // current Attributes
    UINT32 Timeout;
    UINT64 BaudRate;
    UINT32 ReceiveFifoDepth;
    UINT32 DataBits;
    UINT32 Parity;
    UINT32 StopBits;
} SERIAL_IO_MODE;
```

The data values in the SERIAL_IO_MODE are read-only and are updated by the code that produces the EFI_SERIAL_IO_PROTOCOL functions:

ControlMask
A mask of the Control bits that the device supports. The device must always support the Input Buffer Empty control bit.

Timeout
If applicable, the number of microseconds to wait before timing out a Read or Write operation.

BaudRate
If applicable, the current baud rate setting of the device; otherwise, baud rate has the value of zero to indicate that device runs at the device’s designed speed.

ReceiveFifoDepth
The number of characters the device will buffer on input.

DataBits
The number of data bits in each character.

Parity
If applicable, this is the EFI_PARITY_TYPE that is computed or checked as each character is transmitted or received. If the device does not support parity the value is the default parity value.

StopBits
If applicable, the EFI_STOP_BITS_TYPE number of stop bits per character. If the device does not support stop bits the value is the default stop bit value.

```c
//******************************************************************************
// EFI_PARITY_TYPE
//----------------------------------------------------------------------------
typedef enum {
    DefaultParity,
    NoParity,
    EvenParity,
    OddParity,
} EFI_PARITY_TYPE;
```

(continues on next page)
MarkParity,
SpaceParity
} EFI_PARITY_TYPE;

//****************************************************************************
// EFI_STOP_BITS_TYPE
//*****************************************************************************
typedef enum {
    DefaultStopBits,
    OneStopBit,    // 1 stop bit
    OneFiveStopBits, // 1.5 stop bits
    TwoStopBits   // 2 stop bits
} EFI_STOP_BITS_TYPE;

Description

The Serial I/O protocol is used to communicate with UART-style serial devices. These can be standard UART serial ports in PC-AT systems, serial ports attached to a USB interface, or potentially any character-based I/O device.

The Serial I/O protocol can control byte I/O style devices from a generic device, to a device with features such as a UART. As such many of the Serial I/O features are optional to allow for the case of devices that do not have UART controls. Each of these options is called out in the specific serial I/O functions.

The default attributes for all UART-style serial device interfaces are: 115,200 baud, a 1 byte receive FIFO, a 1,000,000 microsecond timeout per character, no parity, 8 data bits, and 1 stop bit. Flow control is the responsibility of the software that uses the protocol. Hardware flow control can be implemented through the use of the EFI_SERIAL_IO_PROTOCOL.GetControl() and EFI_SERIAL_IO_PROTOCOL.SetControl() functions (described below) to monitor and assert the flow control signals. The XON/XOFF flow control algorithm can be implemented in software by inserting XON and XOFF characters into the serial data stream as required.

Special care must be taken if a significant amount of data is going to be read from a serial device. Since UEFI drivers are polled mode drivers, characters received on a serial device might be missed. It is the responsibility of the software that uses the protocol to check for new data often enough to guarantee that no characters will be missed. The required polling frequency depends on the baud rate of the connection and the depth of the receive FIFO.

12.8.2 Serial Device Identification

Serial device identification is accomplished through the interaction of three distinct drivers. The serial port driver binds to the serial port hardware and produces the EFI_SERIAL_IO_PROTOCOL. At the time the protocol is produced the DeviceTypeGuid field is NULL.

During the UEFI Driver Binding process a platform driver, with a EFI_DRIVER_BINDING_PROTOCOL Version field in the range of 0xffffffff to 0xffffffff can check for the presence of the EFI_SERIAL_IO_PROTOCOL and any other necessary information in Supported() to check if the serial port instance is recognized for the purposes of providing serial device identification information. If the port instance is recognized then EFI_SUCCESS will be returned from Supported(). Since the driver binding Version field is higher than any device driver the platform’s serial device identification driver binding instance will have Start() called. This function will write the DeviceTypeGuid with a value that identifies the attached serial device.

When the driver binding process continues the serial device driver can use the DeviceTypeGuid field to determine the serial device connected to the port is supported.

Serial device drivers for non-terminal devices that will co-exist with backwards-compatible terminal drivers must check that the EFI_SERIAL_IO_PROTOCOL Revision field is at least 0x00010001 and compare the DeviceTypeGuid in their driver binding Supported() function. Terminal drivers provide backwards compatibility by assuming a Terminal device
is present when a protocol instance Revision is the original 0x00010000 value. Terminal drivers may also assume a Terminal device is present if the DeviceTypeGuid is NULL for cases where the platform does not provide serial identification information.

12.8.3 Serial Device Type GUIDs

#define EFI_SERIAL_TERMINALDEVICE_TYPE_GUID \ 
  { 0x6ad9a60f, 0x5815, 0x4c7c, \ 
  { 0x8a, 0x10, 0x50, 0x53, 0xd2, 0xbf, 0x7a, 0x1b } }

The EFI_SERIAL_TERMINAL_DEVICE_TYPE_GUID describes a serial terminal type device suitable for use as a UEFI console.

Vendors may define and use additional GUIDs for other serial device types.

![Serial Device Identification Driver Relationships](image)

Fig. 12.1: Serial Device Identification Driver Relationships

12.8.3.1 EFI_SERIAL_IO_PROTOCOL.Reset()

Summary

Resets the serial device.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_SERIAL_RESET) ( 
  IN EFI_SERIAL_IO_PROTOCOL  *This 
 );

Parameters
A pointer to the EFI_SERIAL_IO_PROTOCOL instance. Type EFI_SERIAL_IO_PROTOCOL is defined in Serial I/O Protocol.

Description
The Reset() function resets the hardware of a serial device.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The serial device was reset.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The serial device could not be reset.</td>
</tr>
</tbody>
</table>

12.8.3.2 EFI_SERIAL_IO_PROTOCOL.SetAttributes()

Summary
Sets the baud rate, receive FIFO depth, transmit/receive time out, parity, data bits, and stop bits on a serial device.

```c
EFI_STATUS
(EFI_API *EFI_SERIAL_SET_ATTRIBUTES) (  
    IN EFI_SERIAL_IO_PROTOCOL *This,  
    IN UINT64 BaudRate,  
    IN UINT32 ReceiveFifoDepth,  
    IN UINT32 Timeout  
    IN EFI_PARITY_TYPE Parity,  
    IN UINT8 DataBits,  
    IN EFI_STOP_BITS_TYPE StopBits
);
```

Parameters

This
A pointer to the EFI_SERIAL_IO_PROTOCOL instance. Type EFI_SERIAL_IO_PROTOCOL is defined in Serial I/O Protocol.

BaudRate
The requested baud rate. A BaudRate value of 0 will use the device’s default interface speed.

ReceiveFifoDepth
The requested depth of the FIFO on the receive side of the serial interface. A ReceiveFifoDepth value of 0 will use the device’s default FIFO depth.

Timeout
The requested time out for a single character in microseconds. This timeout applies to both the transmit and receive side of the interface. A Timeout value of 0 will use the device’s default time out value.

Parity
The type of parity to use on this serial device. A Parity value of DefaultParity will use the device’s default parity value. Type EFI_PARITY_TYPE is defined in “Related Definitions” in Serial I/O Protocol.

DataBits
The number of data bits to use on this serial device. A DataBits value of 0 will use the device’s default data bit setting.

StopBits
The number of stop bits to use on this serial device. A StopBits value of DefaultStopBits will use the device’s.
default number of stop bits. Type EFI_STOP_BITS_TYPE is defined in “Related Definitions” in Serial I/O Protocol.

**Description**

The SetAttributes() function sets the baud rate, receive-FIFO depth, transmit/receive time out, parity, data bits, and stop bits on a serial device.

The controller for a serial device is programmed with the specified attributes. If the Parity, DataBits, or StopBits values are not valid, then an error will be returned. If the specified BaudRate is below the minimum baud rate supported by the serial device, an error will be returned. The nearest baud rate supported by the serial device will be selected without exceeding the BaudRate parameter. If the specified ReceiveFifoDepth is below the smallest FIFO size supported by the serial device, an error will be returned. The nearest FIFO size supported by the serial device will be selected without exceeding the ReceiveFifoDepth parameter.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The new attributes were set on the serial device.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the attributes has an unsupported value.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The serial device is not functioning correctly.</td>
</tr>
</tbody>
</table>

**12.8.3.3 EFI_SERIAL_IO_PROTOCOL.SetControl()**

**Summary**

Sets the control bits on a serial device.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_SERIAL_SET_CONTROL_BITS) ( IN EFI_SERIAL_IO_PROTOCOL *This,
                                                          IN UINT32 Control );
```

**Parameters**

**This**

A pointer to the EFI_SERIAL_IO_PROTOCOL instance. Type EFI_SERIAL_IO_PROTOCOL is defined in Serial I/O Protocol.

**Control**

Sets the bits of Control that are settable. See “Related Definitions” below.

**Related Definitions**

```c
//***************************************************************
// CONTROL BITS
//***************************************************************

#define EFI_SERIAL_CLEAR_TO_SEND 0x0010
#define EFI_SERIAL_DATA_SET_READY 0x0020
#define EFI_SERIAL_RING_INDICATE 0x0040
#define EFI_SERIAL_CARRIER_DETECT 0x0080
#define EFI_SERIAL_REQUEST_TO_SEND 0x0002
#define EFI_SERIAL_DATA_TERMINAL_READY 0x0001
```

(continues on next page)
#define EFI_SERIAL_INPUT_BUFFER_EMPTY 0x0100
#define EFI_SERIAL_OUTPUT_BUFFER_EMPTY 0x0200
#define EFI_SERIAL_HARDWARE_LOOPBACK_ENABLE 0x1000
#define EFI_SERIAL_SOFTWARE_LOOPBACK_ENABLE 0x2000
#define EFI_SERIAL_HARDWARE_FLOW_CONTROL_ENABLE 0x4000

Description

The SetControl() function is used to assert or deassert the control signals on a serial device. The following signals are set according to their bit settings:

- Request to Send
- Data Terminal Ready

Only the REQUEST_TO_SEND, DATA_TERMINAL_READY, HARDWARE_LOOPBACK_ENABLE, SOFTWARE_LOOPBACK_ENABLE, and HARDWARE_FLOW_CONTROL_ENABLE bits can be set with SetControl(). All the bits can be read with EFI_SERIAL_IO_PROTOCOL.GetControl().

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The new control bits were set on the serial device.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The serial device does not support this operation.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The serial device is not functioning correctly.</td>
</tr>
</tbody>
</table>

12.8.3.4 EFI_SERIAL_IO_PROTOCOL.GetControl()

Summary

Retrieves the status of the control bits on a serial device.

Prototype

typedef EFI_STATUS
(EFIAPI *EFI_SERIAL_GET_CONTROL_BITS) (
    IN EFI_SERIAL_IO_PROTOCOL *This,
    OUT UINT32 *Control
);

Parameters

This

A pointer to the EFI_SERIAL_IO_PROTOCOL instance. Type EFI_SERIAL_IO_PROTOCOL is defined in Serial I/O Protocol.

Control

A pointer to return the current control signals from the serial device. See “Related Definitions” below.

Related Definitions

```c
//******************************************************************************
// CONTROL BITS
//******************************************************************************

#define EFI_SERIAL_CLEAR_TO_SEND 0x0010
```
#define EFI_SERIAL_DATA_SET_READY 0x0020
#define EFI_SERIAL_RING_INDICATE 0x0040
#define EFI_SERIAL_CARRIER_DETECT 0x0080
#define EFI_SERIAL_REQUEST_TO_SEND 0x0002
#define EFI_SERIAL_DATA_TERMINAL_READY 0x0001
#define EFI_SERIAL_INPUT_BUFFER_EMPTY 0x0100
#define EFI_SERIAL_OUTPUT_BUFFER_EMPTY 0x0200
#define EFI_SERIAL_HARDWARE_LOOPBACK_ENABLE 0x1000
#define EFI_SERIAL_SOFTWARE_LOOPBACK_ENABLE 0x2000
#define EFI_SERIAL_HARDWARE_FLOW_CONTROL_ENABLE 0x4000

Description
The GetControl() function retrieves the status of the control bits on a serial device.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The control bits were read from the serial device.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The serial device is not functioning correctly.</td>
</tr>
</tbody>
</table>

12.8.3.5 EFI_SERIAL_IO_PROTOCOL.Write()

Summary
Writes data to a serial device.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_SERIAL_WRITE) ( 
  IN EFI_SERIAL_IO_PROTOCOL *This, 
  IN OUT UINTN *BufferSize, 
  IN VOID *Buffer 
  );
```

Parameters

This
A pointer to the EFI_SERIAL_IO_PROTOCOL instance. Type EFI_SERIAL_IO_PROTOCOL is defined in Serial I/O Protocol.

BufferSize
On input, the size of the Buffer. On output, the amount of data actually written.

Buffer
The buffer of data to write.

Description
The Write() function writes the specified number of bytes to a serial device. If a time out error occurs while data is being sent to the serial port, transmission of this buffer will terminate, and EFI_TIMEOUT will be returned. In all cases the number of bytes actually written to the serial device is returned in BufferSize.

Status Codes Returned
### 12.8.3.6 EFI_SERIAL_IO_PROTOCOL.Read()

**Summary**

Reads data from a serial device.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_SERIAL_READ) (
    IN EFI_SERIAL_IO_PROTOCOL *This,
    IN OUT UINTN *BufferSize,
    OUT VOID *Buffer
);
```

**Parameters**

- **This**
  A pointer to the EFI_SERIAL_IO_PROTOCOL instance. Type EFI_SERIAL_IO_PROTOCOL is defined in `Serial I/O Protocol`.

- **BufferSize**
  On input, the size of the Buffer. On output, the amount of data returned in Buffer.

- **Buffer**
  The buffer to return the data into.

**Description**

The Read() function reads a specified number of bytes from a serial device. If a time out error or an overrun error is detected while data is being read from the serial device, then no more characters will be read, and an error will be returned. In all cases the number of bytes actually read is returned in BufferSize.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was read.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The serial device reported an error.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The operation was stopped due to a timeout or overrun.</td>
</tr>
</tbody>
</table>

### 12.9 Graphics Output Protocol

The goal of this section is to replace the functionality that currently exists with VGA hardware and its corresponding video BIOS. The Graphics Output Protocol is a software abstraction and its goal is to support any foreseeable graphics hardware and not require VGA hardware, while at the same time also lending itself to implementation on the current generation of VGA hardware.

Graphics output is important in the pre-boot space to support modern firmware features. These features include the display of logos, the localization of output to any language, and setup and configuration screens.
Graphics output may also be required as part of the startup of an operating system. There are potentially times in modern operating systems prior to the loading of a high performance OS graphics driver where access to graphics output device is required. The Graphics Output Protocol supports this capability by providing the EFI OS loader access to a hardware frame buffer and enough information to allow the OS to draw directly to the graphics output device.

The EFI_GRAPHICS_OUTPUT_PROTOCOL supports three member functions to support the limited graphics needs of the pre-boot environment. These member functions allow the caller to draw to a virtualized frame buffer, retrieve the supported video modes, and to set a video mode. These simple primitives are sufficient to support the general needs of pre-OS firmware code.

The EFI_GRAPHICS_OUTPUT_PROTOCOL also exports enough information about the current mode for operating system startup software to access the linear frame buffer directly.

The interface structure for the Graphics Output protocol is defined in this section. A unique Graphics Output protocol must represent each video frame buffer in the system that is driven out to one or more video output devices.

12.9.1 Blt Buffer

The basic graphics operation in the EFI_GRAPHICS_OUTPUT_PROTOCOL is the Block Transfer or Blt. The Blt operation allows data to be read or written to the video adapter's video memory. The Blt operation abstracts the video adapters hardware implementation by introducing the concept of a software Blt buffer.

The frame buffer abstracts the video display as an array of pixels. Each pixel's location on the video display is defined by its X and Y coordinates. The X coordinate represents a scan line. A scan line is a horizontal line of pixels on the display. The Y coordinate represents a vertical line on the display. The upper left hand corner of the video display is defined as (0, 0) where the notation (X, Y) represents the X and Y coordinate of the pixel. The lower right corner of the video display is represented by (Width -1, Height -1).

The software Blt buffer is structured as an array of pixels. Pixel (0, 0) is the first element of the software Blt buffer. The Blt buffer can be thought of as a set of scan lines. It is possible to convert a pixel location on the video display to the Blt buffer using the following algorithm: Blt buffer array index = Y * Width + X.

Each software Blt buffer entry represents a pixel that is comprised of a 32-bit quantity. The color components of Blt buffer pixels are in PixelBlueGreenRedReserved8BitPerColor format as defined by EFI_GRAPHICS_OUTPUT_BLT_PIXEL. The byte values for the red, green, and blue components represent the color intensity. This color intensity value range from a minimum intensity of 0 to maximum intensity of 255.

12.9.2 EFI_GRAPHICS_OUTPUT_PROTOCOL

Summary

Provides a basic abstraction to set video modes and copy pixels to and from the graphics controller's frame buffer. The linear address of the hardware frame buffer is also exposed so software can write directly to the video hardware.

GUID

```c
#define EFI_GRAPHICS_OUTPUT_PROTOCOL_GUID \
{0x9042a9de,0x23dc,0x4a38,\ 
 {0x96,0xfb,0x7a,0xde,0xd0,0x80,0x80,0x51,0x6a}}
```

Protocol Interface Structure

```c
typedef struct EFI_GRAPHICS_OUTPUT_PROTOCOL {
    EFI_GRAPHICS_OUTPUT_PROTOCOL_QUERY_MODE QueryMode;
    EFI_GRAPHICS_OUTPUT_PROTOCOL_SET_MODE SetMode;
    EFI_GRAPHICS_OUTPUT_PROTOCOL_BLT Blt;
} EFI_GRAPHICS_OUTPUT_PROTOCOL;
```

(continues on next page)
Fig. 12.2: Software BLT Buffer
 EFI_GRAPHICS_OUTPUT_PROTOCOL_MODE *Mode;
) EFI_GRAPHICS_OUTPUT_PROTOCOL;

Parameters

QueryMode
Returns information for an available graphics mode that the graphics device and the set of active video output
devices supports.

SetMode
Set the video device into the specified mode and clears the visible portions of the output display to black.

Blt
Software abstraction to draw on the video device’s frame buffer.

Mode
Pointer to EFI_GRAPHICS_OUTPUT_PROTOCOL_MODE data. Type
EFI_GRAPHICS_OUTPUT_PROTOCOL_MODE is defined in “Related Definitions” below.

Related Definitions

typedef struct {
  UINT32       RedMask;
  UINT32       GreenMask;
  UINT32       BlueMask;
  UINT32       ReservedMask;
} EFI_PIXEL_BITMASK;

If a bit is set in RedMask, GreenMask, or BlueMask then those bits of the pixel represent the corresponding color. Bits in RedMask, GreenMask, BlueMask, and ReservedMask must not overlap bit positions. The values for the red, green, and blue components in the bit mask represent the color intensity. The color intensities must increase as the color values for a each color mask increase with a minimum intensity of all bits in a color mask set.

typedef enum {
  PixelRedGreenBlueReserved8BitPerColor,
  PixelBlueGreenRedReserved8BitPerColor,
  PixelBitMask,
  PixelBltOnly,
  PixelFormatMax
} EFI_GRAPHICS_PIXEL_FORMAT;

PixelRedGreenBlueReserved8BitPerColor
A pixel is 32-bits and byte zero represents red, byte one represents green, byte two represents blue, and byte three is reserved. This is the definition for the physical frame buffer. The byte values for the red, green, and blue components represent the color intensity. This color intensity value range from a minimum intensity of 0 to maximum intensity of 255.

PixelBlueGreenRedReserved8BitPerColor
A pixel is 32-bits and byte zero represents blue, byte one represents green, byte two represents red, and byte three is reserved. This is the definition for the physical frame buffer. The byte values for the red, green, and blue components represent the color intensity. This color intensity value range from a minimum intensity of 0 to maximum intensity of 255.
PixelBitMask

The pixel definition of the physical frame buffer is defined by EFI_PIXEL_BITMASK.

PixelBltOnly

This mode does not support a physical frame buffer.

PixelFormatMax

Valid EFI_GRAPHICS_PIXEL_FORMAT enum values are less than this value.

typedef struct {
  UINT32 Version;
  UINT32 HorizontalResolution;
  UINT32 VerticalResolution;
  EFI_GRAPHICS_PIXEL_FORMATPixelFormat;
  EFI PIXEL_BITMASK PixelInformation;
  UINT32 PixelsPerScanLine;
} EFI_GRAPHICS_OUTPUT_MODE_INFORMATION;

Version

The version of this data structure. A value of zero represents the EFI_GRAPHICS_OUTPUT_MODE_INFORMATION structure as defined in this specification. Future version of this specification may extend this data structure in a backwards compatible way and increase the value of Version.

HorizontalResolution

The size of video screen in pixels in the X dimension.

VerticalResolution

The size of video screen in pixels in the Y dimension.

PixelFormat

Enumeration that defines the physical format of the pixel. A value of PixelBltOnly implies that a linear frame buffer is not available for this mode.

PixelInformation

This bit-mask is only valid ifPixelFormat is set to PixelPixelBitMask. A bit being set defines what bits are used for what purpose such as Red, Green, Blue, or Reserved.

PixelsPerScanLine

Defines the number of pixel elements per video memory line. For performance reasons, or due to hardware restrictions, scan lines may be padded to an amount of memory alignment. These padding pixel elements are outside the area covered by HorizontalResolution and are not visible. For direct frame buffer access, this number is used as a span between starts of pixel lines in video memory. Based on the size of an individual pixel element and PixelsPerScanline, the offset in video memory from pixel element (x, y) to pixel element (x, y+1) has to be calculated as “sizeof(PixelElement) * PixelsPerScanLine”, not “sizeof(PixelElement) * HorizontalResolution”, though in many cases those values can coincide. This value can depend on video hardware and mode resolution. GOP implementation is responsible for providing accurate value for this field.

Note: The following code sample is an example of the intended field usage:

```c
INTN GetPixelElementSize (  
  IN EFI_PIXEL_BITMASK *PixelBits
)
{
  INTN HighestPixel = -1;

  // Implementation...

  return HighestPixel;
}
```
INTN BluePixel;
INTN RedPixel;
INTN GreenPixel;
INTN RsvdPixel;

BluePixel = FindHighestSetBit (PixelBits->BlueMask);
RedPixel = FindHighestSetBit (PixelBits->RedMask);
GreenPixel = FindHighestSetBit (PixelBits->GreenMask);
RsvdPixel = FindHighestSetBit (PixelBits->ReservedMask);

HighestPixel = max (BluePixel, RedPixel);
HighestPixel = max (HighestPixel, GreenPixel);
HighestPixel = max (HighestPixel, RsvdPixel);

return HighestPixel;
}

EFI_PHYSICAL_ADDRESS NewPixelAddress;
EFI_PHYSICAL_ADDRESS CurrentPixelAddress* ;
EFI_GRAPHICS_OUTPUT_MODE_INFORMATION OutputInfo;
INTN PixelElementSize;

switch (OutputInfo.PixelFormat) {
  case PixelBitMask:
    PixelElementSize =
      GetPixelElementSize (&OutputInfo.PixelInformation);
    break;

  case PixelBlueGreenRedReserved8BitPerColor:
  case PixelRedGreenBlueReserved8BitPerColor:
    PixelElementSize =
      sizeof (EFI_GRAPHICS_OUTPUT_BLT_PIXEL);
    break;
}

// NewPixelAddress after execution points to the pixel
// positioned one line below the one pointed by
// CurrentPixelAddress

NewPixelAddress = CurrentPixelAddress +
  (PixelElementSize *
    OutputInfo.PixelsPerScanLine);

End of note code sample.

typedef struct {
  UINT32 MaxMode;
  UINT32 Mode;
  EFI_GRAPHICS_OUTPUT_MODE_INFORMATION *Info;
  UINTN SizeOfInfo;
  EFI_PHYSICAL_ADDRESS FrameBufferBase;
}
The EFI_GRAPHICS_OUTPUT_PROTOCOL_MODE is read-only and values are only changed by using the appropriate interface functions:

**MaxMode**
The number of modes supported by QueryMode() and EFI_GRAPHICS_OUTPUT_PROTOCOL.SetMode().

**Mode**
Current Mode of the graphics device. Valid mode numbers are 0 to MaxMode -1.

**Info**
Pointer to read-only EFI_GRAPHICS_OUTPUT_MODE_INFORMATION data.

**SizeOfInfo**
Size of Info structure in bytes. Future versions of this specification may increase the size of the EFI_GRAPHICS_OUTPUT_MODE_INFORMATION data.

**FrameBufferBase**
Base address of graphics linear frame buffer. Info contains information required to allow software to draw directly to the frame buffer without using Blt(). Offset zero in FrameBufferBase represents the upper left pixel of the display.

**FrameBufferSize**
Amount of frame buffer needed to support the active mode as defined by $\text{PixelsPerScanLine} \times \text{VerticalResolution} \times \text{PixelElementSize}$.

**Description**
The EFI_GRAPHICS_OUTPUT_PROTOCOL provides a software abstraction to allow pixels to be drawn directly to the frame buffer. The EFI_GRAPHICS_OUTPUT_PROTOCOL is designed to be lightweight and to support the basic needs of graphics output prior to Operating System boot.

### 12.9.2.1 EFI_GRAPHICS_OUTPUT_PROTOCOL.QueryMode()

**Summary**
Returns information for an available graphics mode that the graphics device and the set of active video output devices supports.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPI *EFI_GRAPHICS_OUTPUT_PROTOCOL_QUERY_MODE) (
    IN EFI_GRAPHICS_OUTPUT_PROTOCOL *This,
    IN UINT32 ModeNumber,
    OUT UINTN *SizeOfInfo
    OUT EFI_GRAPHICS_OUTPUT_MODE_INFORMATION **Info
);
```

**Parameters**

**This**
The **EFI_GRAPHICS_OUTPUT_PROTOCOL** instance. Type EFI_GRAPHICS_OUTPUT_PROTOCOL is defined in this section.
**ModeNumber**

The mode number to return information on. The current mode and valid modes are read-only values in the Mode structure of the `EFI_GRAPHICS_OUTPUT_PROTOCOL`.

**SizeOfInfo**

A pointer to the size, in bytes, of the Info buffer.

**Info**

A pointer to a callee allocated buffer that returns information about ModeNumber.

**Description**

The QueryMode() function returns information for an available graphics mode that the graphics device and the set of active video output devices supports. If ModeNumber is not between 0 and MaxMode - 1, then EFI_INVALID_PARAMETER is returned. MaxMode is available from the Mode structure of the `EFI_GRAPHICS_OUTPUT_PROTOCOL`.

The size of the Info structure should never be assumed and the value of SizeOfInfo is the only valid way to know the size of Info.

If the EFI_GRAPHICS_OUTPUT_PROTOCOL is installed on the handle that represents a single video output device, then the set of modes returned by this service is the subset of modes supported by both the graphics controller and the video output device.

If the EFI_GRAPHICS_OUTPUT_PROTOCOL is installed on the handle that represents a combination of video output devices, then the set of modes returned by this service is the subset of modes supported by the graphics controller and the all of the video output devices represented by the handle.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Valid mode information was returned.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A hardware error occurred trying to retrieve the video mode.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>ModeNumber</code> is not valid.</td>
</tr>
</tbody>
</table>

### 12.9.2.2 EFI_GRAPHICS_OUTPUT_PROTOCOL.SetMode()

**Summary**

Set the video device into the specified mode and clears the visible portions of the output display to black.

**Prototype**

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_GRAPHICS_OUTPUT_PROTOCOL_SET_MODE) ( 
    IN EFI_GRAPHICS_OUTPUT_PROTOCOL     *This, 
    IN UINT32                    ModeNumber 
);
```

**Parameters**

**This**

The `EFI_GRAPHICS_OUTPUT_PROTOCOL` instance. Type EFI_GRAPHICS_OUTPUT_PROTOCOL is defined in this section.

**ModeNumber**

Abstraction that defines the current video mode. The current mode and valid modes are read-only values in the Mode structure of the `EFI_GRAPHICS_OUTPUT_PROTOCOL`.

### 12.9. Graphics Output Protocol
Description

This SetMode() function sets the graphics device and the set of active video output devices to the video mode specified by ModeNumber. If ModeNumber is not supported EFI_UNSUPPORTED is returned.

If a device error occurs while attempting to set the video mode, then EFI_DEVICE_ERROR is returned. Otherwise, the graphics device is set to the requested geometry, the set of active output devices are set to the requested geometry, the visible portion of the hardware frame buffer is cleared to black, and EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The graphics mode specified by ModeNumber was selected.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device had an error and could not complete the request.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>ModeNumber is not supported by this device.</td>
</tr>
</tbody>
</table>

12.9.2.3 EFI_GRAPHICS_OUTPUT_PROTOCOL.Blt()

Summary

Blt a rectangle of pixels on the graphics screen. Blt stands for BLock Transfer.

Prototype

```c
typedef struct {
    UINT8 Blue;
    UINT8 Green;
    UINT8 Red;
    UINT8 Reserved;
} EFI_GRAPHICS_OUTPUT_BLT_PIXEL;

typedef enum {
    EfiBltVideoFill,
    EfiBltVideoToBltBuffer,
    EfiBltBufferToVideo,
    EfiBltVideoToVideo,
    EfiGraphicsOutputBltOperationMax
} EFI_GRAPHICS_OUTPUT_BLT_OPERATION;

typedef
EFI_STATUS
(EIFIAPI *EFI_GRAPHICS_OUTPUT_PROTOCOL_BLT) ( IN EFI_GRAPHICS_OUTPUT_PROTOCOL
IN OUT EFI_GRAPHICS_OUTPUT_BLT_PIXEL
IN EFI_GRAPHICS_OUTPUT_BLT_OPERATION
IN UINTN
IN UINTN
IN UINTN
IN UINTN
IN UINTN
IN UINTN
IN UINTN
IN UINTN

);```

Parameters

12.9. Graphics Output Protocol
This
The *EFI_GRAPHICS_OUTPUT_PROTOCOL* instance.

**BltBuffer**
The data to transfer to the graphics screen. Size is at least Width*Height*sizeof(EFI_GRAPHICS_OUTPUT_BLT_PIXEL).

**BltOperation**
The operation to perform when copying BltBuffer on to the graphics screen.

**SourceX**
The X coordinate of the source for the BltOperation. The origin of the screen is 0, 0 and that is the upper left-hand corner of the screen. **SourceY** The Y coordinate of the source for the BltOperation. The origin of the screen is 0, 0 and that is the upper left-hand corner of the screen.

**DestinationX**
The X coordinate of the destination for the BltOperation. The origin of the screen is 0, 0 and that is the upper left-hand corner of the screen.

**DestinationY**
The Y coordinate of the destination for the BltOperation. The origin of the screen is 0, 0 and that is the upper left-hand corner of the screen.

**Width**
The width of a rectangle in the blt rectangle in pixels. Each pixel is represented by an EFI_GRAPHICS_OUTPUT_BLT_PIXEL element.

**Height**
The height of a rectangle in the blt rectangle in pixels. Each pixel is represented by an EFI_GRAPHICS_OUTPUT_BLT_PIXEL element.

**Delta**
Not used for EfiBltVideoFill or the EfiBltVideoToVideo operation. If a Delta of zero is used, the entire BltBuffer is being operated on. If a subrectangle of the BltBuffer is being used then Delta represents the number of bytes in a row of the BltBuffer.

**Description**
The Blt() function is used to draw the BltBuffer rectangle onto the video screen.

The BltBuffer represents a rectangle of Height by Width pixels that will be drawn on the graphics screen using the operation specified by BltOperation. The Delta value can be used to enable the BltOperation to be performed on a sub-rectangle of the BltBuffer.

**Blt Operation Table** describes the BltOperations that are supported on rectangles. Rectangles have coordinates (left, upper) (right, bottom):

<table>
<thead>
<tr>
<th>Blt Operation</th>
<th>Operation</th>
</tr>
</thead>
<tbody>
<tr>
<td>EfiBltVideoFill</td>
<td>Write data from the BltBuffer pixel (0,0) directly to every pixel of the video display rectangle (DestinationX, DestinationY) (DestinationX + Width, DestinationY + Height). Only one pixel will be used from the BltBuffer. Delta is NOT used.</td>
</tr>
<tr>
<td>EfiBltVideoToVideo</td>
<td>Read data from the video display rectangle (SourceX, SourceY) (SourceX + Width, SourceY + Height) and place it in the BltBuffer rectangle (DestinationX, DestinationY) (DestinationX + Width, DestinationY + Height). If DestinationX or DestinationY is not zero then Delta must be set to the length in bytes of a row in the BltBuffer.</td>
</tr>
</tbody>
</table>
Table 12.32 – continued from previous page

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EfiBltBufferToVideo</td>
<td>Write data from the BltBuffer rectangle (SourceX, SourceY) (SourceX + Width, SourceY + Height) directly to the video display rectangle (DestinationX, DestinationY) (DestinationX + Width, DestinationY + Height). If SourceX or SourceY is not zero then Delta must be set to the length in bytes of a row in the BltBuffer.</td>
</tr>
<tr>
<td>EfiBltVideoToVideo</td>
<td>Copy from the video display rectangle (SourceX, SourceY) (SourceX + Width, SourceY + Height) to the video display rectangle (DestinationX, DestinationY) (DestinationX + Width, DestinationY + Height). The BltBuffer and Delta are not used in this mode. There is no limitation on the overlapping of the source and destination rectangles.</td>
</tr>
</tbody>
</table>

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>BltBuffer was drawn to the graphics screen.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>BltOperation is not valid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device had an error and could not complete the request.</td>
</tr>
</tbody>
</table>

12.9.2.4 EFI_EDID_DISCOVERED_PROTOCOL

Summary

This protocol contains the EDID information retrieved from a video output device.

GUID

```c
#define EFI_EDID_DISCOVERED_PROTOCOL_GUID
{0x1c0c34f6,0xd380,0x41fa,
{0xa0,0x49,0x8a,0xd0,0x6c,0x1a,0x66,0xaa}}
```

Protocol Interface Structure

```c
typedef struct {
    UINT32 SizeOfEdid;
    UINT8 *Edid;
} EFI_EDID_DISCOVERED_PROTOCOL;
```

Parameter

**SizeOfEdid**

The size, in bytes, of the Edid buffer. 0 if no EDID information is available from the video output device. Otherwise, it must be a minimum of 128 bytes.

**Edid**

A pointer to a read-only array of bytes that contains the EDID information for a video output device. This pointer is NULL if no EDID information is available from the video output device. The minimum size of a valid Edid buffer is 128 bytes. EDID information is defined in the E-EDID EEPROM specification published by VESA (www.vesa.org <www.vesa.org>).

Description

EFI_EDID_DISCOVERED_PROTOCOL represents the EDID information that is returned from a video output device. If the video output device does not contain any EDID information, then the SizeOfEdid field must set to zero and the Edid field must be set to NULL. The EFI_EDID_DISCOVERED_PROTOCOL must be placed on every child handle that represents a possible video output device. The EFI_EDID_DISCOVERED_PROTOCOL is never placed on child handles that represent combinations of two or more video output devices.

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12.9.2.5 EFI_EDID_ACTIVE_PROTOCOL

Summary
This protocol contains the EDID information for an active video output device. This is either the EDID information retrieved from the EFI_EDID_OVERRIDE_PROTOCOL if an override is available, or an identical copy of the EDID information from the EFI_EDID_DISCOVERED_PROTOCOL if no overrides are available.

GUID

```c
#define EFI_EDID_ACTIVE_PROTOCOL_GUID \
{0xbd8c1056,0x9f36,0x44ec,\ 
 {0x92,0xa8,0xa6,0x7f,0x81,0x86}}
```

Protocol Interface Structure

```c
typedef struct {
    UINT32 SizeOfEdid;
    UINT8 *Edid;
} EFI_EDID_ACTIVE_PROTOCOL;
```

Parameter

SizeOfEdid
The size, in bytes, of the Edid buffer. 0 if no EDID information is available from the video output device. Otherwise, it must be a minimum of 128 bytes.

Edid
A pointer to a read-only array of bytes that contains the EDID information for an active video output device. This pointer is NULL if no EDID information is available for the video output device. The minimum size of a valid Edid buffer is 128 bytes. EDID information is defined in the E-EDID EEPROM specification published by VESA (www.vesa.org).

Description
When the set of active video output devices attached to a frame buffer are selected, the EFI_EDID_ACTIVE_PROTOCOL must be installed onto the handles that represent the each of those active video output devices. If the EFI_EDID.Override_PROTOCOL has override EDID information for an active video output device, then the EDID information specified by GetEdid() is used for the EFI_EDID_ACTIVE_PROTOCOL. Otherwise, the EDID information from the EFI_EDID_DISCOVERED_PROTOCOL is used for the EFI_EDID_ACTIVE_PROTOCOL. Since all EDID information is read-only, it is legal for the pointer associated with the EFI_EDID_ACTIVE_PROTOCOL to be the same as the pointer associated with the EFI_EDID_DISCOVERED_PROTOCOL when no overrides are present.

12.9.2.6 EFI_EDID_OVERRIDE_PROTOCOL

Summary
This protocol is produced by the platform to allow the platform to provide EDID information to the producer of the Graphics Output protocol.

GUID

```c
#define EFI_EDID_OVERRIDE_PROTOCOL_GUID \
{0x48ecb431,0xfb72,0x45c0,\ 
 {0xa9,0x22,0xfe,0x58,0xe0,0x40b,0xd5}}
```

Protocol Interface Structure
typedef struct _EFI_EDID_OVERRIDE_PROTOCOL {
    EFI_EDID_OVERRIDE_PROTOCOL_GET_EDID GetEdid;
} EFI_EDID_OVERRIDE_PROTOCOL;

Parameter

GetEdid

Returns EDID values and attributes that the Video BIOS must use

Description

This protocol is produced by the platform to allow the platform to provide EDID information to the producer of the Graphics Output protocol.

12.9.2.7 EFI_EDID_OVERRIDE_PROTOCOL.GetEdid()  

Summary

Returns policy information and potentially a replacement EDID for the specified video output device.

Prototype

typedef  
EFI_STATUS  
(EIFI_API) EFI_EDID_OVERRIDE_PROTOCOL_GET_EDID (  
    IN  EFI_EDID_OVERRIDE_PROTOCOL  *This,  
    IN  EFI_HANDLE  *ChildHandle,  
    OUT  UINT32  *Attributes,  
    OUT  UINTN  *EdidSize,  
    OUT  UINT8 **Edid  
    );

Parameters

This

The EFI_EDID_OVERRIDE_PROTOCOL.GetEdid() instance. Type EFI_EDID_OVERRIDE_PROTOCOL is defined in Rules for PCI/AGP Devices.

ChildHandle

A pointer to a child handle that represents a possible video output device.

Attributes

A pointer to the attributes associated with ChildHandle video output device.

EdidSize

A pointer to the size, in bytes, of the Edid buffer.

Edid

A pointer to the callee allocated buffer that contains the EDID information associated with ChildHandle. If EdidSize is 0, then a pointer to NULL is returned.

Note: the (EFI_HANDLE) type of the “ChildHandle” parameter is an historical typing error in the UEFI specification. To match existent practice however, implementors and callers of the protocol are now expected to conform to the declaration of the parameter as written. That is, callers must pass the address of an EFI_HANDLE object as “ChildHandle”, and implementors must dereference “ChildHandle” for finding the EFI_HANDLE object.

Related Definitions

12.9. Graphics Output Protocol
Table 12.34: Attributes Definition Table

<table>
<thead>
<tr>
<th>Attribute Bit</th>
<th>Edid-Size</th>
<th>Operation</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_EDID_OVERRIDE_DONT_OVERRIDE=0</td>
<td>0</td>
<td>No override support device.</td>
</tr>
<tr>
<td>EFI_EDID_OVERRIDE_DONT_OVERRIDE!=0</td>
<td>!= 0</td>
<td>Always use returned display device.</td>
</tr>
<tr>
<td>EFI_EDID_OVERRIDE_DONT_OVERRIDE!=0</td>
<td>0</td>
<td>No override support for the display device.</td>
</tr>
<tr>
<td>EFI_EDID_OVERRIDE_DONT_OVERRIDE!=0</td>
<td>!= 0</td>
<td>Only use returned override EDID if the display device has no EDID or the EDID is incorrect. Otherwise, use the EDID from the display device.</td>
</tr>
<tr>
<td>EFI_EDID_OVERRIDE_ENABLE_HOT_PLUG=0</td>
<td>0</td>
<td>No hot plug support for the display device. A Graphics Output protocol will not be installed if no display device is not present.</td>
</tr>
<tr>
<td>EFI_EDID_OVERRIDE_ENABLE_HOT_PLUG=0</td>
<td>!= 0</td>
<td>No hot plug support for the display device. The returned override EDID should be used according to the EFI_EDID_OVERRIDE_DONT_OVERRIDE attribute bit if the display device is present.</td>
</tr>
<tr>
<td>EFI_EDID_OVERRIDE_ENABLE_HOT_PLUG!=0</td>
<td>0</td>
<td>Invalid. The client of this protocol will not enable hot plug for the display device, and a Graphics Output protocol will not be installed if no other display is present.</td>
</tr>
<tr>
<td>EFI_EDID_OVERRIDE_ENABLE_HOT_PLUG!=0</td>
<td>!= 0</td>
<td>Enable hot plug for the display device. A Graphics Output protocol will be installed even if the display device is not present.</td>
</tr>
</tbody>
</table>

Description

This protocol is optionally provided by the platform to override or provide EDID information and/or output device display properties to the producer of the Graphics Output protocol. If ChildHandle does not represent a video output device, or there are no override for the video output device specified by ChildHandle, then EFI_UNSUPPORTED is returned. Otherwise, the Attributes, EdidSize, and Edid parameters are returned along with a status of EFI_SUCCESS. The Attributes Definition Table defines the behavior for the combinations of the Attribute and EdidSize parameters when EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Valid over rides returned for ChildHandle.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>ChildHandle has no over rides.</td>
</tr>
</tbody>
</table>
# 12.10 Rules for PCI/AGP Devices

A UEFI driver that produces the Graphics Output Protocol must follow the UEFI driver model, produce an *EFI Driver Binding Protocol*, and follow the rules on implementing the ` EFI_DRIVER_BINDING_PROTOCOL::Supported()` , *efi-driver-binding-protocol-Start-protocols-uefi-driver-model* , and *:ref:`efi-driver-binding-protocol-Stop-protocols-uefi-driver-model`*. The `Start()` function must not update the video output device in any way that is visible to the user. The `Start()` function must create child handle for each physical video output device and each supported combination of video output devices. The driver must retrieve the EDID information from each physical video output device and produce a `EFI_EDID_DISCOVERED_PROTOCOL` on the child handle that corresponds each physical video output device. The following summary describes the common initialization steps for a driver that produces the EFI_GRAPHICS_OUTPUT_PROTOCOL. This summary assumes the graphics controller supports a single frame buffer. If a graphics device supports multiple frame buffers, then handles for the frame buffers must be created first, and then the handles for the video output devices can be created as children of the frame buffer handles.

**Summary of Initialization Steps:**

- "If RemainingDevicePath is NULL or the first Device Path Node is the End of Device Path Node, then `Supported()` returns `EFI_SUCCESS` . Otherwise, if the first node of RemainingDevicePath is not an ACPI _ADR node or the first two nodes of RemainingDevicePath are not a Controller node followed by an ACPI _ADR node, then `Supported()` returns `EFI_UNSUPPORTED` .
- "If `Supported()` returned `EFI_SUCCESS` , system calls `Start()` .
- "If RemainingDevicePath is NULL , then a default set of active video output devices are selected by the driver.
- "If the first Device Path Node of RemainingDevicePath is the End of Device Path Node, then skip to the “The EFi Driver must provide `EFI_COMPONENT_NAME2_PROTOCOL` ” step.

**Start() function creates a ChildHandle for each physical video output device and installs the EFI_DEVICE_PATH_PROTOCOL onto the created ChildHandle. The EFI_DEVICE_PATH_PROTOCOL is constructed by appending an ACPI _ADR device path node describing the physical video output device to the end of the device path installed on the ControllerHandle passed into Start().**

**Start() function retrieves EDID information for each physical video output device and installs the EFI_EDID_DISCOVERED_PROTOCOL onto the ChildHandle for each physical video output device. If no EDID data is available from the video output device, then SizeOfEdid is set to zero, and Edid is set to NULL.**

**Start() function create a ChildHandle for each valid combination of two or more video output devices, and installs the EFI_DEVICE_PATH_PROTOCOL onto the created ChildHandle. The EFI_DEVICE_PATH_PROTOCOL is constructed by appending an ACPI _ADR device path node describing the combination of video output devices to the end of the device path installed on the ControllerHandle passed into Start(). The ACPI _ADR entry can represent complex topologies of devices and it is possible to have more than one ACPI _ADR entry in a single device path node. Support of complex video output device topologies is an optional feature.**

**Start() function evaluates the RemainingDevicePath to select the set of active video output devices. If RemainingDevicePath is NULL, then Start() selects a default set of video output devices. If RemainingDevicePath is not NULL, and ACPI _ADR device path node of RemainingDevicePath does not match any of the created ChildHandles, then Start() must destroy all its ChildHandles and return EFI_UNSUPPORTED. Otherwise, Start() selects the set of active video output devices specified by the ACPI _ADR device path node in RemainingDevicePath.**

**Start() retrieves the ChildHandle associated with each active video output device. Only ChildHandles that represent a physical video output device are considered. Start() calls the EFI_EDID_OVERRIDE_PROTOCOL::GetEdid() service passing in ChildHandle. Depending on the return values from GetEdid(), either the override EDID information or the EDID information from the EFI_EDID_DISCOVERED_PROTOCOL on ChildHandle is selected. See GetEdid() for a detailed description of this decision. The selected EDID information is used to produce the EFI_EDID_ACTIVE_PROTOCOL, and that protocol is installed onto ChildHandle.**
• Start() retrieves the one ChildHandle that represents the entire set of active video output devices. If this set is a single video output device, then this ChildHandle will be the same as the one used in the previous step. If this set is a combination of video output devices, then this will not be one of the ChildHandles used in the previous two steps. The EFI_GRAPHICS_OUTPUT_PROTOCOL is installed onto this ChildHandle.

• The QueryMode() service of the EFI_GRAPHICS_OUTPUT_PROTOCOL returns the set of modes that both the graphics controller and the set of active video output devices all support. If a different set of active video output device is selected, then a different set of modes will likely be produced by QueryMode().

• Start() function optionally initializes video frame buffer hardware. The EFI driver has the option of delaying this operation until SetMode() is called.

• The EFI Driver must provide EFI_COMPONENT_NAME2_PROTOCOL GetControllerName() support for ControllerHandle and all the ChildHandles created by this driver. The name returned for ControllerHandle must return the name of the graphics device. The name returned for each of the ChildHandles allow the user to pick output display settings and should be constructed with this in mind.

• The EFI Driver’s Stop() function must cleanly undo what the Start() function created.

• An EFI_GRAPHICS_OUTPUT_PROTOCOL must be implemented for every video frame buffer that exists on a video adapter. In most cases there will be a single EFI_GRAPHICS_OUTPUT_PROTOCOL placed on one of the children of the ControllerHandle passed into the EFI_DRIVER_BINDING:Start() function.

If a single PCI device/function contains multiple frame buffers the EFI_GRAPHICS_OUTPUT_PROTOCOL must create child handles of the PCI handle that inherit its PCI device path and appends a controller device path node. The handles for the video output devices are children of the handles that represent the frame buffers.

A video device can support an arbitrary number of geometries, but it must support one or more of the following modes to conform to this specification:

Onboard graphics device

• A mode required in a platform design guide

• Native mode of the display

Plug in graphics device

• A mode required in a platform design guide

• 800 x 600 with 32-bit color depth or 640 x 480 with 32-bit color depth and a pixel format described by PixelRed-GreenBlueReserved8BitPerColor or PixelBlueGreenRedReserved8BitPerColor.

If graphics output device supports both landscape and portrait mode displays it must return a different mode via QueryMode(). For example landscape mode could be 800 horizontal and 600 vertical while the equivalent portrait mode would be 600 horizontal and 800 vertical.
13.1 Load File Protocol

The Load File protocol is used to obtain files, that are primarily boot options, from arbitrary devices.

13.1.1 EFI_LOAD_FILE_PROTOCOL

Summary

Used to obtain files, that are primarily boot options, from arbitrary devices.

GUID

```
#define EFI_LOAD_FILE_PROTOCOL_GUID \ 
{0x56EC3091,0x954C,0x11d2,\ 
 {0x8e,0x3f,0x00,0xa0, 0xc9,0x69,0x72,0x3b}}
```

Protocol Interface Structure

```
typedef struct __ EFI_LOAD_FILE_PROTOCOL {
    EFI_LOAD_FILE LoadFile;
} EFI_LOAD_FILE_PROTOCOL;
```

Parameters

LoadFile

Causes the driver to load the requested file. See the `EFI_LOAD_FILE_PROTOCOL.LoadFile()` function description.

Description

The EFI_LOAD_FILE_PROTOCOL is a simple protocol used to obtain files from arbitrary devices.

When the firmware is attempting to load a file, it first attempts to use the device’s Simple File System protocol to read the file. If the file system protocol is found, the firmware implements the policy of interpreting the File Path value of the file being loaded. If the device does not support the file system protocol, the firmware then attempts to read the file via the EFI_LOAD_FILE_PROTOCOL and the LoadFile() function. In this case the LoadFile() function implements the policy of interpreting the File Path value.
13.1.2 EFI_LOAD_FILE_PROTOCOL.LoadFile()

Summary
Causes the driver to load a specified file.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_LOAD_FILE) (  
    IN EFI_LOAD_FILE_PROTOCOL *This,  
    IN EFI_DEVICE_PATH_PROTOCOL *FilePath,  
    IN BOOLEAN BootPolicy,  
    IN OUT UINTN *BufferSize,  
    IN VOID *Buffer OPTIONAL
);
```

Parameters

This
Indicates a pointer to the calling context. Type EFI_LOAD_FILE_PROTOCOL is defined in Load File Protocol.

FilePath
The device specific path of the file to load. Type EFI_DEVICE_PATH_PROTOCOL is defined in EFI Device Path Protocol.

BootPolicy
If TRUE, indicates that the request originates from the boot manager, and that the boot manager is attempting to load FilePath as a boot selection. If FALSE, then FilePath must match an exact file to be loaded.

BufferSize
On input the size of Buffer in bytes. On output with a return code of EFI_SUCCESS, the amount of data transferred to Buffer. On output with a return code of EFI_BUFFER_TOO_SMALL, the size of Buffer required to retrieve the requested file.

Buffer
The memory buffer to transfer the file to. If Buffer is NULL, then the size of the requested file is returned in BufferSize.

Description
The LoadFile() function interprets the device-specific FilePath parameter, returns the entire file into Buffer, and sets BufferSize to the amount of data returned. If Buffer is NULL, then the size of the file is returned in BufferSize. If Buffer is not NULL, and BufferSize is not large enough to hold the entire file, then EFI_BUFFER_TOO_SMALL is returned, and BufferSize is updated to indicate the size of the buffer needed to obtain the file. In this case, no data is returned in Buffer.

If BootPolicy is FALSE the FilePath must match an exact file to be loaded. If no such file exists, EFI_NOT_FOUND is returned. If BootPolicy is FALSE, and an attempt is being made to perform a network boot through the PXE Base Code protocol, EFI_UNSUPPORTED is returned.

If BootPolicy is TRUE the firmware's boot manager is attempting to load an EFI image that is a boot selection. In this case, FilePath contains the file path value in the boot selection option. Normally the firmware would implement the policy on how to handle an inexact boot file path; however, since in this case the firmware cannot interpret the file path, the LoadFile() function is responsible for implementing the policy. For example, in the case of a network boot through the PXE Base Code protocol, FilePath merely points to the root of the device, and the firmware interprets this as wanting to boot from the first valid loader. The following is a list of events that LoadFile() will implement for a PXE boot:

13.1. Load File Protocol  455
• Perform DHCP.
• Optionally prompt the user with a menu of boot selections.
• Discover the boot server and the boot file.
• Download the boot file into Buffer and update BufferSize with the size of the boot file.

If the boot file downloaded from boot server is not an UEFI-formatted executable, but a binary image which contains a UEFI-compliant file system, then EFI_WARN_FILE_SYSTEM is returned, and a new RAM disk mapped on the returned Buffer is registered.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The file was loaded.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The device does not support the provided BootPolicy.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>FilePath is not a valid device path, or BufferSize is NULL.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>No medium was present to load the file.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The file was not loaded due to a device error.</td>
</tr>
<tr>
<td>EFI_NO_RESPONSE</td>
<td>The remote system did not respond.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The file was not found.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>The file load process was manually cancelled.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The BufferSize is too small to read the current directory entry. BufferSize has been updated with the size needed to complete the request.</td>
</tr>
<tr>
<td>EFI_WARN_FILE_SYSTEM</td>
<td>The resulting Buffer contains UEFI-compliant file system.</td>
</tr>
</tbody>
</table>

### 13.2 Load File 2 Protocol

The Load File 2 protocol is used to obtain files from arbitrary devices that are not boot options.

#### 13.2.1 EFI_LOAD_FILE2_PROTOCOL

**Summary**

Used to obtain files from arbitrary devices but are not used as boot options.

**GUID**

```c
#define EFI_LOAD_FILE2_PROTOCOL_GUID \
{ 0x4006c0c1, 0xfcb3, 0x403e, \
{ 0x99, 0x6d, 0x4a, 0x6c, 0x87, 0x24, 0xe0, 0x6d } }
```

**Protocol Interface Structure**

```c
typedef EFI_LOAD_FILE2_PROTOCOL EFI_LOAD_FILE2_PROTOCOL;
```

**Parameters**

**LoadFile**

Causes the driver to load the requested file. See the `LoadFile()` functional description.

**Description**

The `EFI_LOAD_FILE2_PROTOCOL` is a simple protocol used to obtain files from arbitrary devices that are not boot options. It is used by `LoadImage()` when its `BootOption` parameter is `FALSE` and the `FilePath` does not have an instance of the `EFI_SIMPLE_FILE_SYSTEM_PROTOCOL`. 
13.2.2 EFI_LOAD_FILE2_PROTOCOL.LoadFile()

Summary
Causes the driver to load a specified file.

Prototype
The same prototype as EFI_LOAD_FILE_PROTOCOL.LoadFile().

Parameters
This
Indicates a pointer to the calling context.

FilePath
The device specific path of the file to load.

BootPolicy
Should always be FALSE.

BufferSize
On input the size of Buffer in bytes. On output with a return code of EFI_SUCCESS, the amount of data transferred to Buffer. On output with a return code of EFI_BUFFER_TOO_SMALL, the size of Buffer required to retrieve the requested file.

Buffer
The memory buffer to transfer the file to. If Buffer is NULL, then no the size of the requested file is returned in BufferSize.

Description
The LoadFile() function interprets the device-specific FilePath parameter, returns the entire file into Buffer, and sets BufferSize to the amount of data returned. If Buffer is NULL, then the size of the file is returned in BufferSize. If Buffer is not NULL, and BufferSize is not large enough to hold the entire file, then EFI_BUFFER_TOO_SMALL is returned, and BufferSize is updated to indicate the size of the buffer needed to obtain the file. In this case, no data is returned in Buffer.

FilePath contains the file path value in the boot selection option. Normally the firmware would implement the policy on how to handle an inexact boot file path; however, since in this case the firmware cannot interpret the file path, the LoadFile() function is responsible for implementing the policy.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The file was loaded.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>BootPolicy is TRUE.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>FilePath is not a valid device path, or BufferSize is NULL.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>No medium was present to load the file.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The file was not loaded due to a device error.</td>
</tr>
<tr>
<td>EFI_NO_RESPONSE</td>
<td>The remote system did not respond.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The file was not found.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>The file load process was manually cancelled.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The BufferSize is too small to read the current directory entry. BufferSize has been updated with the size needed to complete the request.</td>
</tr>
</tbody>
</table>
13.3 File System Format

The file system supported by the Extensible Firmware Interface is based on the FAT file system. EFI defines a specific version of FAT that is explicitly documented and testable. Conformance to the EFI specification and its associate reference documents is the only definition of FAT that needs to be implemented to support EFI. To differentiate the EFI file system from pure FAT, a new partition file system type has been defined.

EFI encompasses the use of FAT32 for a system partition, and FAT12 or FAT16 for removable media. The FAT32 system partition is identified by an OSType value other than that used to identify previous versions of FAT. This unique partition type distinguishes an EFI defined file system from a normal FAT file system. The file system supported by EFI includes support for long file names.

The definition of the EFI file system will be maintained by specification and will not evolve over time to deal with errata or variant interpretations in OS file system drivers or file system utilities. Future enhancements and compatibility enhancements to FAT will not be automatically included in EFI file systems. The EFI file system is a target that is fixed by the EFI specification, and other specifications explicitly referenced by the EFI specification.

For more information about the EFI file system and file image format, visit the website from which this document was obtained.

13.3.1 System Partition

A System Partition is a partition in the conventional sense of a partition on a legacy system. For a hard disk, a partition is a contiguous grouping of sectors on the disk where the starting sector and size are defined by the Master Boot Record (MBR), which resides on LBA 0 (i.e., the first sector of the hard disk) (LBA 0 Format), or the GUID Partition Table (GPT), which resides on logical block 1 (the second sector of the hard disk) (GPT overview). For a diskette (floppy) drive, a partition is defined to be the entire media. A System Partition can reside on any media that is supported by EFI Boot Services.

A System Partition supports backward compatibility with legacy systems by reserving the first block (sector) of the partition for compatibility code. On legacy systems, the first block (sector) of a partition is loaded into memory and execution is transferred to this code. EFI firmware does not execute the code in the MBR. The EFI firmware contains knowledge about the partition structure of various devices, and can understand legacy MBR, GPT, and “El Torito.”

The System Partition contains directories, data files, and UEFI Images. UEFI Images can contain an OS Loader, an driver to extend platform firmware capability, or an application that provides a transient service to the system. Applications written to this specification could include things such as a utility to create partitions or extended diagnostics. A System Partition can also support data files, such as error logs, that can be defined and used by various OS or system firmware software components.

13.3.1.1 File System Format

The first block (sector) of a partition contains a data structure called the BIOS Parameter Block (BPB) that defines the type and location of FAT file system on the drive. The BPB contains a data structure that defines the size of the media, the size of reserved space, the number of FAT tables, and the location and size of the root directory (not used in FAT32). The first block (sector) also contains code that will be executed as part of the boot process on a legacy system. This code in the first block (sector) usually contains code that can read a file from the root directory into memory and transfer control to it. Since EFI firmware contains a file system driver, EFI firmware can load any file from the file system with out the FAT32, FAT16, and FAT12 variants of the EFI file system. What variant of EFI FAT to use is defined by the size of the media. The rules defining the ending to execute any code from the media.
The EFI firmware must support the FAT32, FAT16, and FAT12 variants of the EFI file system. What variant of EFI FAT to use is defined by the size of the media. The rules defining the relationship between media size and FAT variants is defined in the specification for the EFI file system.

The UEFI system partition FAT32 Data region should be aligned to the physical block boundary and optimal transfer length granularity of the device (GPT overview). This is controlled by the BPB_RsvdSecCnt field and the applicable BPB_FATSz field (e.g., formatting software may set the BPB_RsvdSecCnt field to a value that results in alignment and/or may set the BPB_FATSz field to a value that ensures alignment).

13.3.1.2 File Names

FAT stores file names in two formats. The original FAT format limited file names to eight characters with three extension characters. This type of file name is called an 8.3, pronounced eight dot three, file name. FAT was extended to include support for long file names (LFN).

FAT 8.3 file names are always stored as uppercase ASCII characters. LFN can either be stored as ASCII or UCS-2 characters and are stored case sensitive. The string that was used to open or create the file is stored directly into LFN. FAT defines that all files in a directory must have a unique name, and unique is defined as a case insensitive match. The following are examples of names that are considered to be the same and cannot exist in a single directory:

- “ThisIsAnExampleDirectory.Dir”
- “thisisanexamppledirectory.dir”
- THISISANEXAMPLEDIRECTORY.DIR
- ThisIsAnExampleDirectory.DIR

Note: Although the FAT32 specification allows file names to be encoded using UTF-16, this specification only recognizes the UCS-2 subset for the purposes of sorting or collation.

13.3.1.3 Directory Structure

An EFI system partition that is present on a hard disk must contain an EFI defined directory in the root directory. This directory is named EFI. All OS loaders and applications will be stored in subdirectories below EFI. Applications that are loaded by other applications or drivers are not required to be stored in any specific location in the EFI system partition. The choice of the subdirectory name is up to the vendor, but all vendors must pick names that do not collide with any other vendor’s subdirectory name. This applies to system manufacturers, operating system vendors, BIOS vendors, and third party tool vendors, or any other vendor that wishes to install files on an EFI system partition. There must also only be one executable EFI image for each supported processor architecture in each vendor subdirectory. This guarantees that there is only one image that can be loaded from a vendor subdirectory by the EFI Boot Manager. If more than one executable EFI image is present, then the boot behavior for the system will not be deterministic. There may also be an optional vendor subdirectory called BOOT.

This directory contains EFI images that aide in recovery if the boot selections for the software installed on the EFI system partition are ever lost. Any additional UEFI-compliant executables must be in subdirectories below the vendor subdirectory. The following is a sample directory structure for an EFI system partition present on a hard disk.

```
\EFI
  \<OS Vendor 1 Directory>
    <OS Loader Image>
  \<OS Vendor 2 Directory>
    <OS Loader Image>
  ...
  \<OS Vendor N Directory>
```

(continues on next page)
For removable media devices there must be only one UEFI-compliant system partition, and that partition must contain an UEFI-defined directory in the root directory. The directory will be named EFI. All OS loaders and applications will be stored in a subdirectory below EFI called BOOT. There must only be one executable EFI image for each supported processor architecture in the BOOT directory. For removable media to be bootable under EFI, it must be built in accordance with the rules laid out in Removable Media Boot Behavior. This guarantees that there is only one image that can be automatically loaded from a removable media device by the EFI Boot Manager. Any additional EFI executables must be in directories other than BOOT. The following is a sample directory structure for an EFI system partition present on a removable media device.

```
\EFI
  \BOOT
    BOOT{machine type short name}.EFI
```

### 13.3.2 Partition Discovery

This specification requires the firmware to be able to parse the Legacy MBR, GUID Partition Table (GPT), and El Torito (ISO-9660 and El Torito) logical device volumes. The EFI firmware produces a logical EFI_BLOCK_IO_PROTOCOL device for:

- each GUID Partition Entry (see table 16 in 5.3.3) with bit 1 set to zero;
- each El Torito logical device volume; and
- if no GPT is present, each partition found in the legacy MBR partition tables.

LBA zero of the EFI_BLOCK_IO_PROTOCOL device will correspond to the first logical block of the partition. See Nesting of Legacy MBR Partition Records. If a GPT Partition Entry has Attribute bit 1 set then a logical EFI_BLOCK_IO_PROTOCOL device must not be created.

The following is the order in which a block device must be scanned to determine if it contains partitions. When a check for a valid partitioning scheme succeeds, the search terminates.

1. Check for GUID Partition Table Headers.
2. Follow ISO-9660 specification to search for ISO-9660 volume structures on the magic LBA.
3. Check for an “El Torito” volume extension and follow the “El Torito” CD-ROM specification.
4. If none of the above, check LBA 0 for a legacy MBR partition table.
5. No partition found on device.

If a disk contains a recognized RAID structure (e.g. DDF structure as defined in The Storage Networking Industry Association Common RAID Disk Data Format Specification— see Glossary), the data on the disk must be ignored, unless the driver is using the RAID structure to produce a logical RAID volume.

EFI supports the nesting of legacy MBR partitions, by allowing any legacy MBR partition to contain more legacy MBR partitions. This is accomplished by supporting the same partition discovery algorithm on every logical block device. It
should be noted that the GUID Partition Table does not allow nesting of GUID Partition Table Headers. Nesting is not needed since a GUID Partition Table Header can support an arbitrary number of partitions (the addressability limits of a 64-bit LBA are the limiting factor).

13.3.2.1 ISO-9660 and El Torito

ISO-9660 is the industry standard low level format used on CD-ROM and DVD-ROM. The CD-ROM format is completely described by the “El Torito” Bootable CD-ROM Format Specification Version 1.0. To boot from a CD-ROM or DVD-ROM in the boot services environment, an EFI System partition is stored in a “no emulation” mode as defined by the “El Torito” specification. A Platform ID of 0xEF indicates an EFI System Partition. The Platform ID is in either the Section Header Entry or the Validation Entry of the Booting Catalog as defined by the “El Torito” specification. EFI differs from “El Torito” “no emulation” mode in that it does not load the “no emulation” image into memory and jump to it. EFI interprets the “no emulation” image as an EFI system partition. EFI interprets the Sector Count in the Initial/Default Entry or the Section Header Entry to be the size of the EFI system partition. If the value of Sector Count is set to 0 or 1, EFI will assume the system partition consumes the space from the beginning of the “no emulation” image to the end of the CD-ROM.

A DVD-ROM image formatted as required by the UDF 2.0 specification (OSTA Universal Disk Format Specification, Revision 2.0) shall be booted by UEFI if:

- the DVD-ROM image conforms to the “UDF Bridge” format defined in the UDF 2.0 specification, and
- the DVD-ROM image contains exactly one ISO-9660 file system, and

Booting from a DVD-ROM that satisfies the above requirements is accomplished using the same methods as booting from a CD-ROM: the ISO-9660 file system shall be booted.

Since the EFI file system definition does not use the same Initial/Default entry as a legacy CD-ROM it is possible to boot personal computers using an EFI CD-ROM or DVD-ROM. The inclusion of boot code for personal computers is optional and not required by EFI.
13.3.3 Number and Location of System Partitions

UEFI does not impose a restriction on the number or location of System Partitions that can exist on a system. System Partitions are discovered when required by UEFI firmware by examining the partition GUID and verifying that the contents of the partition conform to the FAT file system as defined in File System Format. Further, UEFI implementations may allow the use of conforming FAT partitions which do not use the ESP GUID. Partition creators may prevent UEFI firmware from examining and using a specific partition by setting bit 1 of the Partition Attributes (see 5.3.3) which will exclude the partition as a potential ESP.

Software installation may choose to create and locate an ESP on each target OS boot disk, or may choose to create a single ESP independent of the location of OS boot disks and OS partitions. It is outside of the scope of this specification to attempt to coordinate the specification of size and location of an ESP that can be shared by multiple OS or Diagnostics installations, or to manage potential namespace collisions in directory naming in a single (central) ESP.

13.3.4 Media Formats

This section describes how booting from different types of removable media is handled. In general the rules are consistent regardless of a media’s physical type and whether it is removable or not.

13.3.4.1 Removable Media

Removable media may contain a standard FAT12, FAT16, or FAT32 file system.

Booting from a removable media device can be accomplished the same way as any other boot. The boot file path provided to the boot manager can consist of a UEFI application image to load, or can merely be the path to a removable media device. In the first case, the path clearly indicates the image that is to be loaded. In the later case, the boot manager implements the policy to load the default application image from the device.

For removable media to be bootable under EFI, it must be built in accordance with the rules laid out in Removable Media Boot Behavior.

13.3.4.2 Diskette

EFI bootable diskettes follow the standard formatting conventions used on personal computers. The diskette contains only a single partition that complies to the EFI file system type. For diskettes to be bootable under EFI, it must be built in accordance with the rules laid out in Removable Media Boot Behavior.

Since the EFI file system definition does not use the code in the first block of the diskette, it is possible to boot personal computers using a diskette that is also formatted as an EFI bootable removable media device. The inclusion of boot code for personal computers is optional and not required by EFI.

Diskettes include the legacy 3.5-inch diskette drives as well as the newer larger capacity removable media drives such as an Iomega® Zip,® Fujitsu MO, or MKE LS-120/SuperDisk®.
13.3.4.3 Hard Drive

Hard drives may contain multiple partitions as defined in See Partition Discovery on partition discovery. Any partition on the hard drive may contain a file system that the EFI firmware recognizes. Images that are to be booted must be stored under the EFI subdirectory as defined in System Partition and Partition Discovery.

EFI code does not assume a fixed block size.

Since EFI firmware does not execute the MBR code and does not depend on the BootIndicator field in the legacy MBR partition records, the hard disk can still boot and function normally.

13.3.4.4 CD-ROM and DVD-ROM

A CD-ROM or DVD-ROM may contain multiple partitions as defined in System Partition and Partition Discovery and in the “El Torito” specification.

EFI code does not assume a fixed block size.

Since the EFI file system definition does not use the same Initial/Default entry as a legacy CD-ROM, it is possible to boot personal computers using an EFI CD-ROM or DVD-ROM. The inclusion of boot code for personal computers is optional and not required by EFI.

13.3.4.5 Network

To boot from a network device, the Boot Manager uses the Load File Protocol to perform a EFI_LOAD_FILE_PROTOCOL.LoadFile() on the network device. This uses the PXE Base Code Protocol to perform DHCP and Discovery. This may result in a list of possible boot servers along with the boot files available on each server. The Load File Protocol for a network boot may then optionally produce a menu of these selections for the user to choose from. If this menu is presented, it will always have a timeout, so the Load File Protocol can automatically boot the default boot selection. If there is only one possible boot file, then the Load File Protocol can automatically attempt to load the one boot file.

The Load File Protocol will download the boot file using the MTFTP service in the PXE Base Code Protocol. The downloaded image must be an EFI image that the platform supports.

13.4 Simple File System Protocol

The Simple File System protocol allows code running in the EFI boot services environment to obtain file based access to a device. EFI_SIMPLE_FILE_SYSTEM_PROTOCOL is used to open a device volume and return an EFI_FILE_PROTOCOL that provides interfaces to access files on a device volume.

13.4.1 EFI_SIMPLE_FILE_SYSTEM_PROTOCOL

Summary

Provides a minimal interface for file-type access to a device.

GUID

```
#define EFI_SIMPLE_FILE_SYSTEM_PROTOCOL_GUID \
\{0x0964e5b22,0x6459,0x11d2,\}
\{0x8e,0x39,0x00,0xa0,0xc9,0x72,0x3b}\}
```

Revision Number
#define EFI_SIMPLE_FILE_SYSTEM_PROTOCOL_REVISION 0x00010000

Protocol Interface Structure

typedef struct _EFI_SIMPLE_FILE_SYSTEM_PROTOCOL {
    UINT64 Revision;
    EFI_SIMPLE_FILE_SYSTEM_PROTOCOL_OPEN_VOLUME OpenVolume;
} EFI_SIMPLE_FILE_SYSTEM_PROTOCOL;

Parameters

Revision
The version of the EFI.FILE_PROTOCOL. The version specified by this specification is 0x00010000. All future revisions must be backwards compatible. If a future version is not backwards compatible, it is not the same GUID.

OpenVolume
Opens the volume for file I/O access. See the OpenVolume() EFI_SIMPLE_FILE_SYSTEM_PROTOCOL.OpenVolume() function description.

Description
The EFI_SIMPLE_FILE_SYSTEM_PROTOCOL provides a minimal interface for file-type access to a device. This protocol is only supported on some devices.

Devices that support the Simple File System protocol return an EFI_FILE_PROTOCOL. The only function of this interface is to open a handle to the root directory of the file system on the volume. Once opened, all accesses to the volume are performed through the volume’s file handles, using the EFI_FILE_PROTOCOL protocol. The volume is closed by closing all the open file handles.

The firmware automatically creates handles for any block device that supports the following file system formats:

- FAT12
- FAT16
- FAT32

13.4.2 EFI_SIMPLE_FILE_SYSTEM_PROTOCOL.OpenVolume()

Summary
Opens the root directory on a volume.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_SIMPLE_FILE_SYSTEM_PROTOCOL_OPEN_VOLUME) (
    IN EFI_SIMPLE_FILE_SYSTEM_PROTOCOL *This,
    OUT EFI_FILE_PROTOCOL **Root)
);

Parameters

This
A pointer to the volume to open the root directory of. See the type EFI_SIMPLE_FILE_SYSTEM_PROTOCOL description.
Root
A pointer to the location to return the opened file handle for the root directory. See the type see `EFI_FILE_PROTOCOL` description.

Description
The OpenVolume() function opens a volume, and returns a file handle to the volume’s root directory. This handle is used to perform all other file I/O operations. The volume remains open until all the file handles to it are closed.

If the medium is changed while there are open file handles to the volume, all file handles to the volume will return EFI_MEDIA_CHANGED. To access the files on the new medium, the volume must be reopened with OpenVolume(). If the new medium is a different file system than the one supplied in the EFI_HANDLE’s DevicePath for the EFI_SIMPLE_SYSTEM_PROTOCOL, OpenVolume() will return EFI_UNSUPPORTED.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The file volume was opened.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The volume does not support the requested file system type.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>The device has no medium.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error.</td>
</tr>
<tr>
<td>EFI_VOLUME_CORRUPTED</td>
<td>The file system structures are corrupted.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The service denied access to the file.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The file volume was not opened.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The device has a different medium in it or the medium is no longer supported.</td>
</tr>
</tbody>
</table>

Any existing file handles for this volume are no longer valid. To access the files on the new medium, the volume must be reopened with OpenVolume().

13.5 File Protocol

The protocol and functions described in this section support access to EFI-supported file systems.

13.5.1 EFI_FILE_PROTOCOL

Summary
Provides file based access to supported file systems.

Revision Number

```c
#define EFI_FILE_PROTOCOL_REVISION 0x00010000
#define EFI_FILE_PROTOCOL_REVISION2 0x00020000
#define EFI_FILE_PROTOCOL_LATEST_REVISION EFI_FILE_PROTOCOL_REVISION2
```

Protocol Interface Structure

```c
typedef struct EFI_FILE_PROTOCOL {
    UINT64 Revision;
    EFI_FILE_OPEN Open;
    EFI_FILE_CLOSE Close;
    EFI_FILE_DELETE Delete;
    EFI_FILE_READ Read;
    EFI_FILE_WRITE Write;
    EFI_FILE_GET_POSITION GetPosition;
}(*EFI_FILE_PROTOCOL)(
```

(continues on next page)
### EFI_FILE_PROTOCOL

```c
EFI_FILE_SET_POSITION SetPosition;
EFI_FILE_GET_INFO GetInfo;
EFI_FILE_SET_INFO SetInfo;
EFI_FILE_FLUSH Flush;
EFI_FILE_OPEN_EX OpenEx; // Added for revision 2
EFI_FILE_READ_EX ReadEx; // Added for revision 2
EFI_FILE_WRITE_EX WriteEx; // Added for revision 2
EFI_FILE_FLUSH_EX FlushEx; // Added for revision 2
} EFI_FILE_PROTOCOL;
```

### Parameters

#### Revision

The version of the EFI_FILE_PROTOCOL interface. The version specified by this specification is `EFI_FILE_PROTOCOL_LATEST_REVISION`. Future versions are required to be backward compatible to version 1.0.

#### Open

Opens or creates a new file. See the `EFI_FILE_PROTOCOL.Open()` function description.

#### Close

Closes the current file handle. See the `EFI_FILE_PROTOCOL.Close()` function description.

#### Delete

Deletes a file. See the `EFI_FILE_PROTOCOL.Delete()` function description.

#### Read

Reads bytes from a file. See the `EFI_FILE_PROTOCOL.Read()` function description.

#### Write

Writes bytes to a file. See the `EFI_FILE_PROTOCOL.Write()` function description.

#### GetPosition

Returns the current file position. See the `EFI_FILE_PROTOCOL.GetPosition()` function description.

#### SetPosition

Sets the current file position. See the `EFI_FILE_PROTOCOL.SetPosition()` function description.

#### GetInfo

Gets the requested file or volume information. See the `EFI_FILE_PROTOCOL.GetInfo()` function description.

#### SetInfo

Sets the requested file information. See the `EFI_FILE_PROTOCOL.SetInfo()` function description.

#### Flush

Flushes all modified data associated with the file to the device. See the `EFI_FILE_PROTOCOL.Flush()` function description.

#### OpenEx

Opens a new file relative to the source directory’s location.

#### ReadEx

Reads data from a file.

#### WriteEx

Writes data to a file.

#### FlushEx

Flushes all modified data associated with a file to a device.
Description

The EFI_FILE_PROTOCOL provides file IO access to supported file systems.

An EFI_FILE_PROTOCOL provides access to a file’s or directory’s contents, and is also a reference to a location in the directory tree of the file system in which the file resides. With any given file handle, other files may be opened relative to this file’s location, yielding new file handles.

On requesting the file system protocol on a device, the caller gets the EFI_FILE_PROTOCOL to the volume. This interface is used to open the root directory of the file system when needed. The caller must EFI_FILE_PROTOCOL.Close() the file handle to the root directory, and any other opened file handles before exiting. While there are open files on the device, usage of underlying device protocol(s) that the file system is abstracting must be avoided. For example, when a file system that is layered on an EFI_DISK_IO_PROTOCOL EFI_BLOCK_IO_PROTOCOL, direct block access to the device for the blocks that comprise the file system must be avoided while there are open file handles to the same device.

A file system driver may cache data relating to an open file. A Flush() function is provided that flushes all dirty data in the file system, relative to the requested file, to the physical medium. If the underlying device may cache data, the file system must inform the device to flush as well.

Implementations must account for cases where there is pending queued asynchronous I/O when a call is received on a blocking protocol interface. In these cases the pending I/O will be processed and completed before the blocking function is executed so that operation are carried out in the order they were requested.

13.5.2 EFI_FILE_PROTOCOL.Open()

Summary

Opens a new file relative to the source file’s location.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_FILE_OPEN) (  
    IN EFI_FILE_PROTOCOL *This,  
    OUT EFI_FILE_PROTOCOL **NewHandle,  
    IN CHAR16 *FileName,  
    IN UINT64 OpenMode,  
    IN UINT64 Attributes);  

Parameters

This

A pointer to the EFI_FILE_PROTOCOL instance that is the file handle to the source location. This would typically be an open handle to a directory. See the type EFI_FILE_PROTOCOL description.

NewHandle

A pointer to the location to return the opened handle for the new file. See the type EFI_FILE_PROTOCOL description.

FileName

The Null-terminated string of the name of the file to be opened. The file name may contain the following path modifiers: “”, “.”, and “..”.

OpenMode

The mode to open the file. The only valid combinations that the file may be opened with are: Read, Read/Write, or Create/Read/Write. See “Related Definitions” below.
Attributes

Only valid for EFI_FILE_MODE_CREATE, in which case these are the attribute bits for the newly created file. See “Related Definitions” below.

Related Definitions

```c
//**************************************************************
// Open Modes
//**************************************************************
#define EFI_FILE_MODE_READ 0x0000000000000001
#define EFI_FILE_MODE_WRITE 0x0000000000000002
#define EFI_FILE_MODE_CREATE 0x8000000000000000

//**************************************************************
// File Attributes
//**************************************************************
#define EFI_FILE_READ_ONLY 0x0000000000000001
#define EFI_FILE_HIDDEN 0x0000000000000002
#define EFI_FILE_SYSTEM 0x0000000000000004
#define EFI_FILE_RESERVED 0x0000000000000008
#define EFI_FILE_DIRECTORY 0x0000000000000010
#define EFI_FILE_ARCHIVE 0x0000000000000020
#define EFI_FILE_VALID_ATTR 0x0000000000000037
```

Description

The Open() function opens the file or directory referred to by FileName relative to the location of This and returns a NewHandle. The FileName may include the following path modifiers:

```
\"
```

If the filename starts with a “\" the relative location is the root directory that This resides on; otherwise “” separates name components. Each name component is opened in turn, and the handle to the last file opened is returned.

```
..```

Opens the parent directory for the current location.

```
..```

Opens the current location.

If EFI_FILE_MODE_CREATE is set, then the file is created in the directory. If the final location of FileName does not refer to a directory, then the operation fails. If the file does not exist in the directory, then a new file is created. If the file already exists in the directory, then the existing file is opened.

If the medium of the device changes, all accesses (including the File handle) will result in EFI_MEDIA_CHANGED. To access the new medium, the volume must be reopened.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The file was opened.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified file could not be found on the device.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>The device has no medium.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The device has a different medium in it or the medium is no longer supported.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error.</td>
</tr>
<tr>
<td>EFI_VOLUME_CORRUPTED</td>
<td>The file system structures are corrupted.</td>
</tr>
</tbody>
</table>

continues on next page
Table 13.4 – continued from previous page

<table>
<thead>
<tr>
<th>Code Point</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>An attempt was made to create a file, or open a file for write when the media is write-protected.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The service denied access to the file.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Not enough resources were available to open the file.</td>
</tr>
<tr>
<td>EFI_VOLUME_FULL</td>
<td>The volume is full.</td>
</tr>
</tbody>
</table>

### 13.5.3 EFI_FILE_PROTOCOL.Close()

**Summary**
Closes a specified file handle.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI *EFI_FILE_CLOSE) (  
    IN EFI_FILE_PROTOCOL *This  
);
```

**Parameters**

**This**
A pointer to the `EFI_FILE_PROTOCOL` instance that is the file handle to close. See the type `EFI_FILE_PROTOCOL` description.

**Description**

The `Close()` function closes a specified file handle. All “dirty” cached file data is flushed to the device, and the file is closed. In all cases the handle is closed. The operation will wait for all pending asynchronous I/O requests to complete before completing.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code Point</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The file was closed.</td>
</tr>
</tbody>
</table>

### 13.5.4 EFI_FILE_PROTOCOL.Delete()

**Summary**
Closes and deletes a file.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI *EFI_FILE_DELETE) (  
    IN EFI_FILE_PROTOCOL *This  
);
```

**Parameters**

**This**
A pointer to the `EFI_FILE_PROTOCOL` instance that is the handle to the file to delete. See the type `EFI_FILE_PROTOCOL` description.
Description

The Delete() function closes and deletes a file. In all cases the file handle is closed. If the file cannot be deleted, the warning code EFI_WARN_DELETE_FAILURE is returned, but the handle is still closed.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The file was closed and deleted, and the handle was closed.</td>
</tr>
<tr>
<td>EFI_WARN_DELETE_FAILURE</td>
<td>The handle was closed, but the file was not deleted.</td>
</tr>
</tbody>
</table>

13.5.5 EFI_FILE_PROTOCOL.Read()

Summary

Reads data from a file.

Prototype

```c
typedef EFI_STATUS
  (EFIAPIC _EFI_FILE_READ) (  
    IN EFI_FILE_PROTOCOL *This,
    IN OUT UINTN *BufferSize,
    OUT VOID *Buffer
  );
```

Parameters

**This**

A pointer to the EFI_FILE_PROTOCOL instance that is the file handle to read data from. See the type EFI_FILE_PROTOCOL description.

**BufferSize**

On input, the size of the Buffer. On output, the amount of data returned in Buffer. In both cases, the size is measured in bytes.

**Buffer**

The buffer into which the data is read.

Description

The Read() function reads data from a file.

If This is not a directory, the function reads the requested number of bytes from the file at the file's current position and returns them in Buffer. If the read goes beyond the end of the file, the read length is truncated to the end of the file. The file's current position is increased by the number of bytes returned.

If This is a directory, the function reads the directory entry at the file's current position and returns the entry in Buffer. If the Buffer is not large enough to hold the current directory entry, then EFI_BUFFER_TOO_SMALL is returned and the current file position is not updated. BufferSize is set to be the size of the buffer needed to read the entry. On success, the current position is updated to the next directory entry. If there are no more directory entries, the read returns a zero-length buffer. EFI_FILE_INFO is the structure returned as the directory entry.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was read.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>The device has no medium.</td>
</tr>
</tbody>
</table>

continues on next page
Table 13.6 – continued from previous page

<table>
<thead>
<tr>
<th>Constant</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An attempt was made to read from a deleted file.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>On entry, the current file position is beyond the end of the file.</td>
</tr>
<tr>
<td>EFI_VOLUME_CORRUPTED</td>
<td>The file system structures are corrupted.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The BufferSize is too small to read the current directory entry. BufferSize has been updated with the size needed to complete the request.</td>
</tr>
</tbody>
</table>

13.5.6 EFI_FILE_PROTOCOL.Write()

Summary
 Writes data to a file.

Prototype

```c
typedef EFI_STATUS (EFlAPI *EFI_FILE_WRITE) (  
    IN EFI_FILE_PROTOCOL *This,  
    IN OUT UINTN *BufferSize,  
    IN VOID *Buffer  
);
```

Parameters

This
 A pointer to the EFI_FILE_PROTOCOL instance that is the file handle to write data to. See the type EFI_FILE_PROTOCOL description.

BufferSize
 On input, the size of the Buffer. On output, the amount of data actually written. In both cases, the size is measured in bytes.

Buffer
 The buffer of data to write.

Description
 The Write() function writes the specified number of bytes to the file at the current file position. The current file position is advanced the actual number of bytes written, which is returned in BufferSize. Partial writes only occur when there has been a data error during the write attempt (such as “file space full”). The file is automatically grown to hold the data if required.

Direct writes to opened directories are not supported.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was written.</td>
</tr>
<tr>
<td>EFI_UNSUPPORT</td>
<td>Writes to open directory files are not supported.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>The device has no medium.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error.</td>
</tr>
<tr>
<td>EFI_VOLUME_ERROR</td>
<td>An attempt was made to write to a deleted file.</td>
</tr>
<tr>
<td>EFI_VOLUME_CORRUPTED</td>
<td>The file system structures are corrupted.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The file or medium is write-protected.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The file was opened read only.</td>
</tr>
</tbody>
</table>

continues on next page
**Table 13.7 – continued from previous page**

| EFI_VOLUME_FULL | The volume is full. |

### 13.5.7 EFI_FILE_PROTOCOL.OpenEx()

**Summary**
Opens a new file relative to the source directory’s location.

**Prototype**

```c
typedef EFI_STATUS (EFIAPICALLTYPE EFI_FILE_OPEN_EX) (
    IN EFI_FILE_PROTOCOL *This,
    OUT EFI_FILE_PROTOCOL **NewHandle,
    IN CHAR16 *FileName,
    IN UINT64 OpenMode,
    IN UINT64 Attributes,
    IN OUT EFI_FILE_IO_TOKEN *Token
);
```

**Parameters**

**This**
A pointer to the EFI_FILE_PROTOCOL instance that is the file handle to read data from. See the type EFI_FILE_PROTOCOL description.

**NewHandle**
A pointer to the location to return the opened handle for the new file. See the type EFI_FILE_PROTOCOL description. For asynchronous I/O, this pointer must remain valid for the duration of the asynchronous operation.

**FileName**
The Null-terminated string of the name of the file to be opened. The file name may contain the following path modifiers: “”, “.”, and “..”.

**OpenMode**
The mode to open the file. The only valid combinations that the file may be opened with are: Read, Read/Write, or Create/Read/Write. See “Related Definitions” below.

**Attributes**
Only valid for EFI_FILE_MODE_CREATE, in which case these are the attribute bits for the

**Token**
A pointer to the token associated with the transaction. Type EFI_FILE_IO_TOKEN is defined in “Related Definitions” below.

**Description**
The OpenEx() function opens the file or directory referred to by FileName relative to the location of This and returns a NewHandle. The FileName may include the path modifiers described previously in Open().

If EFI_FILE_MODE_CREATE is set, then the file is created in the directory. If the final location of FileName does not refer to a directory, then the operation fails. If the file does not exist in the directory, then a new file is created. If the file already exists in the directory, then the existing file is opened.

If the medium of the device changes, all accesses (including the File handle) will result in EFI_MEDIA_CHANGED. To access the new medium, the volume must be reopened.
If an error is returned from the call to OpenEx() and non-blocking I/O is being requested, the Event associated with this request will not be signaled. If the call to OpenEx() succeeds then the Event will be signaled upon completion of the open or if an error occurs during the processing of the request. The status of the read request can be determined from the Status field of the Token once the event is signaled.

**Related Definitions**

```c
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    UINTN BufferSize;
    VOID *Buffer;
} EFI_FILE_IO_TOKEN;
```

**Event**

If Event is NULL, then blocking I/O is performed. If Event is not NULL and non-blocking I/O is supported, then non-blocking I/O is performed, and Event will be signaled when the read request is completed. The caller must be prepared to handle the case where the callback associated with Event occurs before the original asynchronous I/O request call returns.

**Status**

Defines whether or not the signaled event encountered an error.

**BufferSize**

For OpenEx(): Not Used, ignored
For ReadEx(): On input, the size of the Buffer. On output, the amount of data returned in Buffer. In both cases, the size is measured in bytes.
For WriteEx(): On input, the size of the Buffer. On output, the amount of data actually written. In both cases, the size is measured in bytes.
For FlushEx(): Not used, ignored

**Buffer**

For OpenEx(): Not Used, ignored
For ReadEx(): The buffer into which the data is read.
For WriteEx(): The buffer of data to write.
For FlushEx(): Not Used, ignored

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
</table>
| EFI_SUCCESS          | Returned from the call OpenEx()  
If Event is NULL (blocking I/O): The file was opened successfully.  
If Event is not NULL (asynchronous I/O): The request was successfully queued for processing.  
Event will be signaled upon completion. Returned in the token after signaling Event  
The file was opened successfully. |
| EFI_NOT_FOUND        | The device has no medium. |
| EFI_NO_MEDIA         | The specified file could not be found on the device. |
| EFI_VOLUME_CORRUPTED | The file system structures are corrupted. |

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Table 13.8 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>An attempt was made to create a file, or open a file for write when the media is write-protected.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The service denied access to the file.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to queue the request or open the file due to lack of resources.</td>
</tr>
<tr>
<td>EFI_VOLUME_FULL</td>
<td>The volume is full.</td>
</tr>
</tbody>
</table>

13.5.8 EFI_FILE_PROTOCOL.ReadEx()

Summary
Reads data from a file.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_FILE_READ_EX) (
  IN EFI_FILE_PROTOCOL *This,
  IN OUT EFI_FILE_IO_TOKEN *Token
);
```

Parameters

This
A pointer to the EFI_FILE_PROTOCOL instance that is the file handle to read data from. See the type EFI_FILE_PROTOCOL description.

Token
A pointer to the token associated with the transaction. Type EFI_FILE_IO_TOKEN is defined in “Related Definitions” below.

Description
The ReadEx() function reads data from a file.

If This is not a directory, the function reads the requested number of bytes from the file at the file’s current position and returns them in Buffer. If the read goes beyond the end of the file, the read length is truncated to the end of the file. The file’s current position is increased by the number of bytes returned.

If This is a directory, the function reads the directory entry at the file’s current position and returns the entry in *Buffer. If the Buffer is not large enough to hold the current directory entry, then EFI_BUFFER_TOO_SMALL is returned and the current file position is not updated. BufferSize is set to be the size of the buffer needed to read the entry. On success, the current position is updated to the next directory entry. If there are no more directory entries, the read returns a zero-length buffer. EFI_FILE_INFO is the structure returned as the directory entry.

If non-blocking I/O is used the file pointer will be advanced based on the order that read requests were submitted.

If an error is returned from the call to ReadEx() and non-blocking I/O is being requested, the Event associated with this request will not be signaled. If the call to ReadEx() succeeds then the Event will be signaled upon completion of the read or if an error occurs during the processing of the request. The status of the read request can be determined from the Status field of the Token once the event is signaled.

Status Codes Returned
13.5.9 EFI_FILE_PROTOCOL.WriteEx()

Summary
Writes data to a file.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_FILE_WRITE_EX) ( IN EFI_FILE_PROTOCOL *This, IN OUT EFI_FILE_IO_TOKEN *Token );

Parameters

This
A pointer to the EFI_FILE_PROTOCOL instance that is the file handle to write data to. See the type EFI_FILE_PROTOCOL description.

Token
A pointer to the token associated with the transaction. Type EFI_FILE_IO_TOKEN is defined in “Related Definitions” above.

Description

The WriteEx() function writes the specified number of bytes to the file at the current file position. The current file position is advanced the actual number of bytes written, which is returned in BufferSize. Partial writes only occur when there has been a data error during the write attempt (such as “file space full”). The file is automatically grown to hold the data if required.

Direct writes to opened directories are not supported.

If non-blocking I/O is used the file pointer will be advanced based on the order that write requests were submitted.

If an error is returned from the call to WriteEx() and non-blocking I/O is being requested, the Event associated with this request will not be signaled. If the call to WriteEx() succeeds then the Event will be signaled upon completion of
the write or if an error occurs during the processing of the request. The status of the write request can be determined from the Status field of the Token once the event is signaled.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Returned from the call WriteEx()</td>
</tr>
<tr>
<td></td>
<td>If Event is NULL (blocking I/O):</td>
</tr>
<tr>
<td></td>
<td>The data was written successfully.</td>
</tr>
<tr>
<td></td>
<td>If Event is not NULL (asynchronous I/O):</td>
</tr>
<tr>
<td></td>
<td>The request was successfully queued for processing. Event will be signaled</td>
</tr>
<tr>
<td></td>
<td>upon completion.</td>
</tr>
<tr>
<td></td>
<td>Returned in the token after signaling Event</td>
</tr>
<tr>
<td></td>
<td>The data was written successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Writes to open directory files are not supported.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>The device has no medium.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An attempt was made to write to a deleted file.</td>
</tr>
<tr>
<td>EFI_VOLUME_CORRUPTED</td>
<td>The file system structures are corrupted.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The file or medium is write-protected.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The file was opened read only.</td>
</tr>
<tr>
<td>EFI_VOLUME_FULL</td>
<td>The volume is full.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to queue the request due to lack of resources.</td>
</tr>
</tbody>
</table>

### 13.5.10 EFI_FILE_PROTOCOL.FlushEx()

**Summary**

Flushes all modified data associated with a file to a device.

**Prototype**

```c
typedef
EFI_STATUS
(EIFIAPFI *EFI_FILE_FLUSH_EX) (  
    IN EFI_FILE_PROTOCOL *This,  
    IN OUT EFI_FILE_IO_TOKEN *Token
);
```

**Parameters**

**This**

A pointer to the EFI_FILE_PROTOCOL instance that is the file handle to flush. See the type EFI_FILE_PROTOCOL description.

**Token**

A pointer to the token associated with the transaction. Type EFI_FILE_IO_TOKEN is defined in “Related Definitions” above. The BufferSize and Buffer fields are not used for a FlushEx operation.

**Description**

The FlushEx() function flushes all modified data associated with a file to a device.

For non-blocking I/O all writes submitted before the flush request will be flushed.
If an error is returned from the call to \textit{FlushEx}() and non-blocking I/O is being requested, the Event associated with this request will not be signaled.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Returned from the call \textit{FlushEx}()</td>
</tr>
<tr>
<td></td>
<td>If Event is NULL (blocking I/O):</td>
</tr>
<tr>
<td></td>
<td>The data was flushed successfully.</td>
</tr>
<tr>
<td></td>
<td>If Event is not NULL (asynchronous I/O):</td>
</tr>
<tr>
<td></td>
<td>The request was successfully queued for processing. Event will be signaled</td>
</tr>
<tr>
<td></td>
<td>upon completion.</td>
</tr>
<tr>
<td></td>
<td>Returned in the token after signaling Event</td>
</tr>
<tr>
<td></td>
<td>The data was flushed successfully.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>The device has no medium.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error.</td>
</tr>
<tr>
<td>EFI_VOLUME_CORRUPTED</td>
<td>The file system structures are corrupted.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The file or medium is write-protected.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The file was opened read-only.</td>
</tr>
<tr>
<td>EFI_VOLUME_FULL</td>
<td>The volume is full.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to queue the request due to lack of resources.</td>
</tr>
</tbody>
</table>

### 13.5.11 \texttt{EFI\_FILE\_PROTOCOL.SetPosition()}\

**Summary**

Sets a file’s current position.

**Prototype**

```c
typedef
EFI_STATUS
(EIFIAPU *EFI\_FILE\_SET\_POSITION) ( 
    IN EFI\_FILE\_PROTOCOL  *This,
    IN UINT64              Position
);```

**Parameters**

**This**

A pointer to the \texttt{EFI\_FILE\_PROTOCOL} instance that is the file handle to set the requested position on. See the type \texttt{EFI\_FILE\_PROTOCOL} description.

**Position**

The byte position from the start of the file to set.

**Description**

The \texttt{SetPosition()} function sets the current file position for the handle to the position supplied. With the exception of seeking to position 0xFFFFFFFFFFFFFFFF, only absolute positioning is supported, and seeking past the end of the file is allowed (a subsequent write would grow the file). Seeking to position 0xFFFFFFFFFFFFFFFF causes the current position to be set to the end of the file.
If This is a directory, the only position that may be set is zero. This has the effect of starting the read process of the directory entries over.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The position was set.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The seek request for nonzero is not valid on open directories.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An attempt was made to set the position of a deleted file.</td>
</tr>
</tbody>
</table>

### 13.5.12 EFI_FILE_PROTOCOL.GetPosition()

**Summary**

Returns a file’s current position.

**Prototype**

```c
typedef EFI_STATUS
  (EFI_FILE_GET_POSITION) ( IN EFI_FILE_PROTOCOL *This,
                                      OUT UINT64 *Position );
```

**Parameters**

**This**

A pointer to the `EFI_FILE_PROTOCOL` instance that is the file handle to get the current position on. See the type `EFI_FILE_PROTOCOL` description.

**Position**

The address to return the file’s current position value.

**Description**

The GetPosition() function returns the current file position for the file handle. For directories, the current file position has no meaning outside of the file system driver and as such the operation is not supported. An error is returned if This is a directory.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The position was returned.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The request is not valid on open directories.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An attempt was made to get the position from a deleted file.</td>
</tr>
</tbody>
</table>

### 13.5.13 EFI_FILE_PROTOCOL.GetInfo()

**Summary**

Returns information about a file.

**Prototype**

```c
typedef EFI_STATUS
  (EFI_FILE_GET_INFO) ( IN EFI_FILE_PROTOCOL *This,
                                      OUT EFI_FILE_INFO *Info );
```
(continued from previous page)

```c
(EIFIAPI *EFI_FILE_GET_INFO) (  
    IN EFI_FILE_PROTOCOL *This,  
    IN EFI_GUID *InformationType,  
    IN OUT UINTN *BufferSize,  
    OUT VOID *Buffer  
);  
```

**Parameters**

**This**  
A pointer to the `EFI_FILE_PROTOCOL` instance that is the file handle the requested information is for. See the type `EFI_FILE_PROTOCOL` description.

**InformationType**  
The type identifier for the information being requested. Type `EFI_GUID` is defined on page 181. See the `EFI_FILE_INFO` and `EFI_FILE_SYSTEM_INFO` descriptions for the related GUID definitions.

**BufferSize**  
On input, the size of Buffer. On output, the amount of data returned in Buffer. In both cases, the size is measured in bytes.

**Buffer**  
A pointer to the data buffer to return. The buffer’s type is indicated by `InformationType`.

**Description**

The `GetInfo()` function returns information of type `InformationType` for the requested file. If the file does not support the requested information type, then `EFI_UNSUPPORTED` is returned. If the buffer is not large enough to fit the requested structure, `EFI_BUFFER_TOO_SMALL` is returned and the `BufferSize` is set to the size of buffer that is required to make the request.

The information types defined by this specification are required information types that all file systems must support.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The information was set.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The <code>InformationType</code> is not known.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>The device has no medium.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error.</td>
</tr>
<tr>
<td>EFI_VOLUME_CORRUPTED</td>
<td>The file system structures are corrupted.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The <code>BufferSize</code> is too small to read the current directory entry.</td>
</tr>
<tr>
<td></td>
<td><code>BufferSize</code> has been updated with the size needed to complete the request.</td>
</tr>
</tbody>
</table>

**13.5.14 EFI_FILE_PROTOCOL.SetInfo()**

**Summary**

Sets information about a file.

**Prototype**

```c
typedef
EFI_STATUS
```

(continues on next page)
Parameters

This
A pointer to the EFI_FILE_PROTOCOL instance that is the file handle the information is for. See the type EFI_FILE_PROTOCOL description.

InformationType
The type identifier for the information being set. Type EFI_GUID is defined in page 181. See the EFI_FILE_INFO and EFI_FILE_SYSTEM_INFO descriptions in this section for the related GUID definitions.

BufferSize
The size, in bytes, of Buffer

Buffer
A pointer to the data buffer to write. The buffer's type is indicated by InformationType.

Description
The SetInfo() function sets information of type InformationType on the requested file. Because a read-only file can be opened only in read-only mode, an InformationType of EFI_FILE_INFO_ID can be used with a read-only file because this method is the only one that can be used to convert a read-only file to a read-write file. In this circumstance, only the Attribute field of the EFI_FILE_INFO structure may be modified. One or more calls to SetInfo() to change the Attribute field are permitted before it is closed. The file attributes will be valid the next time the file is opened with Open().

An InformationType of EFI_FILE_SYSTEM_INFO_ID or EFI_FILE_SYSTEM_VOLUME_LABEL_ID may not be used on read-only media.

Status Codes Returned

<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The information was set.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The InformationType is not known.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>The device has no medium.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error.</td>
</tr>
<tr>
<td>EFI_VOLUME_CORRUPTED</td>
<td>The file system structures are corrupted.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>InformationType is EFI_FILE_INFO_ID and the media is read-only.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>InformationType is EFI_FILE_PROTOCOL_SYSTEM_INFO_ID and the media is read-only.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>InformationType is EFI_FILE_SYSTEM_VOLUME_LABEL_ID and the media is read-only.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>An attempt is made to change the name of a file to a file that is already present.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>An attempt is being made to change the EFI_FILE_DIRECTORY Attribute.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>An attempt is being made to change the size of a directory.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>InformationType is EFI_FILE_INFO_ID and the file was opened read-only and an attempt is being made to modify a field other than Attribute.</td>
</tr>
<tr>
<td>EFI_VOLUME_FULL</td>
<td>The volume is full.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>BufferSize is smaller than the size of the type indicated by InformationType.</td>
</tr>
</tbody>
</table>
13.5.15 EFI_FILE_PROTOCOL.Flush()

Summary
Flushes all modified data associated with a file to a device.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_FILE_FLUSH) (IN EFI_FILE_PROTOCOL *This);
```

Parameters

This
A pointer to the EFI_FILE_PROTOCOL instance that is the file handle to flush. See the type EFI_FILE_PROTOCOL description.

Description
The Flush() function flushes all modified data associated with a file to a device.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was flushed.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>The device has no medium.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error.</td>
</tr>
<tr>
<td>EFI_VOLUME_CORRUPTED</td>
<td>The file system structures are corrupted.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The file or medium is write-protected.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The file was opened read-only.</td>
</tr>
<tr>
<td>EFI_VOLUME_FULL</td>
<td>The volume is full.</td>
</tr>
</tbody>
</table>

13.5.16 EFI_FILE_INFO

Summary
Provides a GUID and a data structure that can be used with EFI_FILE_PROTOCOL.SetInfo() and EFI_FILE_PROTOCOL.GetInfo() to set or get generic file information.

GUID

```c
#define EFI_FILE_INFO_ID \
{0x09576e92,0x6d3f,0x11d2,\ 
 {0x8e39,0x00,0xa0,0xc9,0x69,0x72,0x3b}}
```

Related Definitions

```c
typedef struct { 
    UINT64  Size;
    UINT64  FileSize;
    UINT64  PhysicalSize;
    EFI_TIME CreateTime;
    EFI_TIME LastAccessTime;
    EFI_TIME ModificationTime;
} EFI_FILE_INFO;
```

(continues on next page)
UINT64 Attribute;
CHAR16 FileName [];
} EFI_FILE_INFO;

#define EFI_FILE_READ_ONLY 0x0000000000000001
#define EFI_FILE_HIDDEN 0x0000000000000002
#define EFI_FILE_SYSTEM 0x0000000000000004
#define EFI_FILE_RESERVED 0x0000000000000008
#define EFI_FILE_DIRECTORY 0x0000000000000010
#define EFI_FILE_ARCHIVE 0x0000000000000020
#define EFI_FILE_VALID_ATTR 0x0000000000000037

Parameters

Size
Size of the EFI_FILE_INFO structure, including the Null-terminated FileName string.

FileSize
The size of the file in bytes.

PhysicalSize
The amount of physical space the file consumes on the file system volume.

CreateTime
The time the file was created.

LastAccessTime
The time when the file was last accessed.

ModificationTime
The time when the file’s contents were last modified.

Attribute
The attribute bits for the file. See “Related Definitions” above.

FileName
The Null-terminated name of the file. For a root directory, the name is an empty string.

Description
The EFI_FILE_INFO data structure supports EFI_FILE_PROTOCOL.GetInfo() and EFI_FILE_PROTOCOL.SetInfo() requests. In the case of SetInfo(), the following additional rules apply:

- On directories, the file size is determined by the contents of the directory and cannot be changed by setting FileSize. On directories, FileSize is ignored during a SetInfo().
- The PhysicalSize is determined by the FileSize and cannot be changed. This value is ignored during a SetInfo() request.
- The EFI_FILE_DIRECTORY attribute bit cannot be changed. It must match the file’s actual type.
- A value of zero in CreateTime, LastAccess, or ModificationTime causes the fields to be ignored (and not updated).
13.5.17 EFI_FILE_SYSTEM_INFO

Summary

Provides a GUID and a data structure that can be used with EFI_FILE_PROTOCOL.GetInfo() to get information about
the system volume, and EFI_FILE_PROTOCOL.SetInfo() to set the system volume’s volume label.

GUID

#define EFI_FILE_SYSTEM_INFO_ID
{0x09576e93,0x6d3f,0x11d2,0x8e39,0x00,0xa0,0xc9,0x69,0x72,\}
0x3b}

Related Definitions

typedef struct {
    UINT64 Size;
    BOOLEAN ReadOnly;
    UINT64 VolumeSize;
    UINT64 FreeSpace;
    UINT32 BlockSize;
    CHAR16 VolumeLabel[];
} EFI_FILE_SYSTEM_INFO;

Parameters

Size
Size of the EFI_FILE_SYSTEM_INFO structure, including the Null-terminated VolumeLabel string.

ReadOnly
TRUE if the volume only supports read access.

VolumeSize
The number of bytes managed by the file system.

FreeSpace
The number of available bytes for use by the file system.

BlockSize
The nominal block size by which files are typically grown.

VolumeLabel
The Null-terminated string that is the volume’s label.

Description

The EFI_FILE_SYSTEM_INFO data structure is an information structure that can be obtained on the root directory file handle. The root directory file handle is the file handle first obtained on the initial call to the EFI_BOOT_SERVICES.HandleProtocol() function to open the file system interface. All of the fields are read-only except for VolumeLabel. The system volume’s VolumeLabel can be created or modified by calling EFI_FILE_PROTOCOL.SetInfo() with an updated VolumeLabel field.
13.5.18 EFI_FILE_SYSTEM_VOLUME_LABEL

Summary
Provides a GUID and a data structure that can be used with EFI_FILE_PROTOCOL.GetInfo() or EFI_FILE_PROTOCOL.SetInfo() to get or set information about the system’s volume label.

GUID
#define EFI_FILE_SYSTEM_VOLUME_LABEL_ID \
{0xdb47d7d3,0xfe81,0x11d3,0x9a35,\ 
{0x00,0x90,0x27,0x3f,0xC1,0x4d}}

Related Definitions
typedef struct {
    CHAR16 VolumeLabel[];
} EFI_FILE_SYSTEM_VOLUME_LABEL;

Parameters
VolumeLabel
    The Null-terminated string that is the volume’s label.

Description
The EFI_FILE_SYSTEM_VOLUME_LABEL data structure is an information structure that can be obtained on the root directory file handle. The root directory file handle is the file handle first obtained on the initial call to the TODO LINK See EFI_BOOT_SERVICES.HandleProtocol() function to open the file system interface. The system volume's VolumeLabel can be created or modified by calling EFI_FILE_PROTOCOL.SetInfo() with an updated VolumeLabel field.

13.6 Tape Boot Support

13.6.1 Tape I/O Support
This section defines the Tape I/O Protocol and standard tape header format. These enable the support of booting from tape on UEFI systems. This protocol is used to abstract the tape drive operations to support applications written to this specification.

13.6.2 Tape I/O Protocol
This section defines the Tape I/O Protocol and its functions. This protocol is used to abstract the tape drive operations to support applications written to this specification.
13.6.2.1 EFI_TAPE_IO_PROTOCOL

Summary
The EFI Tape IO protocol provides services to control and access a tape device.

GUID

```
#define EFI_TAPE_IO_PROTOCOL_GUID \
{0x1e93e633,0xd65a,0x459e, \ 
 {0xab,0x84,0x93,0xd9,0xec,0x26,0x6d,0x18}}
```

Protocol Interface Structure

```
typedef struct_EFI_TAPE_IO_PROTOCOL {
    EFI_TAPE_READ TapeRead;
    EFI_TAPE_WRITE TapeWrite;
    EFI_TAPE_REWIND TapeRewind;
    EFI_TAPE_SPACE TapeSpace;
    EFI_TAPE_WRITEFM TapeWriteFM;
    EFI_TAPE_RESET TapeReset;
} EFI_TAPE_IO_PROTOCOL;
```

Parameters

TapeRead
Read a block of data from the tape. See the `EFI_TAPE_IO_PROTOCOL.TapeRead()` description.

TapeWrite
Write a block of data to the tape. See the `EFI_TAPE_IO_PROTOCOL.TapeWrite()` description.

TapeRewind
Rewind the tape. See the `EFI_TAPE_IO_PROTOCOL.TapeRewind()` description.

TapeSpace
Position the tape. See the `EFI_TAPE_IO_PROTOCOL.TapeSpace()` description.

TapeWriteFM
Write filemarks to the tape. See the `EFI_TAPE_IO_PROTOCOL.TapeWriteFM()` description.

TapeReset
Reset the tape device or its parent bus. See the `EFI_TAPE_IO_PROTOCOL.TapeReset()` description.

Description
The EFI_TAPE_IO_PROTOCOL provides basic sequential operations for tape devices. These include read, write, rewind, space, write filemarks and reset functions. Per this specification, a boot application uses the services of this protocol to load the bootloader image from tape.

No provision is made for controlling or determining media density or compression settings. The protocol relies on devices to behave normally and select settings appropriate for the media loaded. No support is included for tape partition support, setmarks or other tapemarks such as End of Data. Boot tapes are expected to use normal variable or fixed block size formatting and filemarks.
13.6.2.2 EFI_TAPE_IO_PROTOCOL.TapeRead()

Summary
Reads from the tape.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI  *EFI_TAPE_READ) (
    IN EFI_TAPE_IO_PROTOCOL *This,
    IN OUT UINTN *BufferSize,
    OUT VOID *Buffer
);
```

Parameters

This
A pointer to the EFI_TAPE_IO_PROTOCOL instance.

BufferSize
Size of the buffer in bytes pointed to by Buffer

Buffer
Pointer to the buffer for data to be read into.

Description

This function will read up to BufferSize bytes from media into the buffer pointed to by Buffer using an implementation-specific timeout. BufferSize will be updated with the number of bytes transferred.

Each read operation for a device that operates in variable block size mode reads one media data block. Unread bytes which do not fit in the buffer will be skipped by the next read operation. The number of bytes transferred will be limited by the actual media block size. Best practice is for the buffer size to match the media data block size. When a filemark is encountered in variable block size mode the read operation will indicate that 0 bytes were transferred and the function will return an EFI_END_OF_FILE error condition.

In fixed block mode the buffer is expected to be a multiple of the data block size. Each read operation for a device that operates in fixed block size mode may read multiple media data blocks. The number of bytes transferred will be limited to an integral number of complete media data blocks. BufferSize should be evenly divisible by the device’s fixed block size. When a filemark is encountered in fixed block size mode the read operation will indicate that the number of bytes transferred is less than the number of blocks that would fit in the provided buffer (possibly 0 bytes transferred) and the function will return an EFI_END_OF_FILE error condition.

Two consecutive filemarks are normally used to indicate the end of the last file on the media.

The value specified for BufferSize should correspond to the actual block size used on the media. If necessary, the value for BufferSize may be larger than the actual media block size.

Specifying a BufferSize of 0 is valid but requests the function to provide read-related status information instead of actual media data transfer. No data will be attempted to be read from the device however this operation is classified as an access for status handling. The status code returned may be used to determine if a filemark has been encountered by the last read request with a non-zero size, and to determine if media is loaded and the device is ready for reading. A NULL value for Buffer is valid when BufferSize is zero.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Data was successfully transferred from the media.</td>
</tr>
</tbody>
</table>

continues on next page
### Table 13.17 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_END_OF_FILE</td>
<td>A filemark was encountered which limited the data transferred by the read operation or the head is positioned just after a filemark.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>No media is loaded in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The media in the device was changed since the last access. The transfer was aborted since the current position of the media may be incorrect.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to transfer data from the media.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A NULL Buffer was specified with a non-zero BufferSize or the device is operating in fixed block size mode and the BufferSize was not a multiple of device’s fixed block size</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The transfer failed since the device was not ready (e.g. not online). The transfer may be retried at a later time.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The device does not support this type of transfer.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The transfer failed to complete within the timeout specified.</td>
</tr>
</tbody>
</table>

### 13.6.2.3 EFI_TAPE_IO_PROTOCOL.TapeWrite()

**Summary**

Write to the tape.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPIC *EFI_TAPE_WRITE) (IN EFI_TAPE_IO_PROTOCOL *This,
                           IN UINTN *BufferSize,
                           IN VOID *Buffer);
```

**Parameters**

**This**

A pointer to the EFI_TAPE_IO_PROTOCOL instance.

**BufferSize**

Size of the buffer in bytes pointed to by Buffer.

**Buffer**

Pointer to the buffer for data to be written from.

**Description**

This function will write BufferSize bytes from the buffer pointed to by Buffer to media using an implementation-specific timeout.

Each write operation for a device that operates in variable block size mode writes one media data block of BufferSize bytes.

Each write operation for a device that operates in fixed block size mode writes one or more media data blocks of the device’s fixed block size. BufferSize must be evenly divisible by the device’s fixed block size.

Although sequential devices in variable block size mode support a wide variety of block sizes, many issues may be avoided in I/O software, adapters, hardware and firmware if common block sizes are used such as: 32768, 16384, 8192, 4096, 2048, 1024, 512, and 80.

BufferSize will be updated with the number of bytes transferred.
When a write operation occurs beyond the logical end of media an EFI_END_OF_MEDIA error condition will occur. Normally data will be successfully written and BufferSize will be updated with the number of bytes transferred. Additional write operations will continue to fail in the same manner. Excessive writing beyond the logical end of media should be avoided since the physical end of media may be reached.

Specifying a BufferSize of 0 is valid but requests the function to provide write-related status information instead of actual media data transfer. No data will be attempted to be written to the device however this operation is classified as an access for status handling. The status code returned may be used to determine if media is loaded, writable and if the logical end of media point has been reached. A NULL value for Buffer is valid when BufferSize is zero.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Data was successfully transferred to the media.</td>
</tr>
<tr>
<td>EFI_END_OF_MEDIA</td>
<td>The logical end of media has been reached. Data may have been successfully</td>
</tr>
<tr>
<td></td>
<td>transferred to the media.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>No media is loaded in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The media in the device was changed since the last access. The transfer was</td>
</tr>
<tr>
<td></td>
<td>aborted since the current position of the media may be incorrect.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The media in the device is write-protected. The transfer was aborted since</td>
</tr>
<tr>
<td></td>
<td>a write cannot be completed.</td>
</tr>
<tr>
<td>EFIDEVICE_ERROR</td>
<td>A device error occurred while attempting to transfer data from the media.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A NULL Buffer was specified with a non-zero BufferSize or the device is</td>
</tr>
<tr>
<td></td>
<td>operating in fixed block size mode and BufferSize was not a multiple of</td>
</tr>
<tr>
<td></td>
<td>device’s fixed block size.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The transfer failed since the device was not ready (e.g. not online). The</td>
</tr>
<tr>
<td></td>
<td>transfer may be retried at a later time.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The device does not support this type of transfer.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The transfer failed to complete within the timeout specified.</td>
</tr>
</tbody>
</table>

13.6.2.4 EFI_TAPE_IO_PROTOCOL.TapeRewind()

**Summary**

Rewinds the tape.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_TAPE_REWIND) ( 
    IN EFI_TAPE_IO_PROTOCOL );
```

**Parameters**

**This**

A pointer to the EFI_TAPE_IO_PROTOCOL instance.

**Description**

This function will rewind the media using an implementation-specific timeout. The function will check if the media was changed since the last access and reinstall the EFI_TAPE_IO_PROTOCOL interface for the device handle if needed.

**Status Codes Returned**
**Summary**
Positions the tape.

**Prototype**

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_TAPE_SPACE) (  
    IN EFI_TAPE_IO_PROTOCOL *This,
    IN INTN Direction,
    IN UINTN Type
);
```

**Parameters**

**This**
A pointer to the `EFI_TAPE_IO_PROTOCOL` instance.

**Direction**
Direction and number of data blocks or filemarks to space over on media.

**Type**
Type of mark to space over on media.

**Description**
This function will position the media using an implementation-specific timeout.

A positive `Direction` value will indicate the number of data blocks or filemarks to forward space the media. A negative `Direction` value will indicate the number of data blocks or filemarks to reverse space the media.

The following `Type` marks are mandatory:

<table>
<thead>
<tr>
<th>Type of Tape</th>
<th>Mark MarkType</th>
</tr>
</thead>
<tbody>
<tr>
<td>BLOCK</td>
<td>0</td>
</tr>
<tr>
<td>FILEMARK</td>
<td>1</td>
</tr>
</tbody>
</table>

Space operations position the media past the data block or filemark. Forward space operations leave media positioned with the tape device head after the data block or filemark. Reverse space operations leave the media positioned with the tape device head before the data block or filemark.

If beginning of media is reached before a reverse space operation passes the requested number of data blocks or filemarks an `EFI_END_OF_MEDIA` error condition will occur. If end of recorded data or end of physical media is reached before a forward space operation passes the requested number of data blocks or filemarks an `EFI_END_OF_MEDIA` error condition will occur. An `EFI_END_OF_MEDIA` error condition will not occur due to spacing over data blocks or filemarks past the logical end of media point used to indicate when write operations should be limited.
Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The media was successfully repositioned.</td>
</tr>
<tr>
<td>EFI_END_OF_MEDIA</td>
<td>Beginning or end of media was reached before the indicated number of data</td>
</tr>
<tr>
<td></td>
<td>blocks or filemarks were found.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>No media is loaded in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The media in the device was changed since the last access. Repositioning</td>
</tr>
<tr>
<td></td>
<td>the media was aborted since the current position of the media may be</td>
</tr>
<tr>
<td></td>
<td>incorrect.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to reposition the media.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>Repositioning the media failed since the device was not ready (e.g. not</td>
</tr>
<tr>
<td></td>
<td>online). The transfer may be retried at a later time.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The device does not support this type of media repositioning.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Repositioning of the media did not complete within the timeout specified.</td>
</tr>
</tbody>
</table>

13.6.2.6 EFI_TAPE_IO_PROTOCOL.TapeWriteFM()

Summary
Writes filemarks to the media.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_TAPE_WRITEFM) (IN EFI_TAPE_IO_PROTOCOL *This,
                                           IN UINTN Count);

Parameters

This
A pointer to the EFI_TAPE_IO_PROTOCOL instance.

Count
Number of filemarks to write to the media.

Description
This function will write filemarks to the tape using an implementation-specific timeout.

Writing filemarks beyond logical end of tape does not result in an error condition unless physical end of media is reached.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Data was successfully transferred from the media.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>No media is loaded in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The media in the device was changed since the last access. The transfer was</td>
</tr>
<tr>
<td></td>
<td>aborted since the current position of the media may be incorrect.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to transfer data from the media.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The transfer failed since the device was not ready (e.g. not online). The</td>
</tr>
<tr>
<td></td>
<td>transfer may be retried at a later time.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The device does not support this type of transfer.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The transfer failed to complete within the timeout specified.</td>
</tr>
</tbody>
</table>
13.6.2.7 EFI_TAPE_IO_PROTOCOL.TapeReset()

**Summary**
Resets the tape device.

**Prototype**
```c
typedef
EFI_STATUS
(EFIAPI *EFI_TAPE_RESET) (
    IN EFI_TAPE_IO_PROTOCOL *This,
    IN BOOLEAN ExtendedVerification
);
```

**Parameters**

**This**
A pointer to the EFI_TAPE_IO_PROTOCOL instance.

**ExtendedVerification**
Indicates whether the parent bus should also be reset.

**Description**
This function will reset the tape device. If ExtendedVerification is set to TRUE, the function will reset the parent bus (e.g., SCSI bus). The function will check if the media was changed since the last access and reinstall the EFI_TAPE_IO_PROTOCOL interface for the device handle if needed. Note media needs to be loaded and device online for the reset, otherwise, EFI_DEVICE_ERROR is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The bus and/or device were successfully reset.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>No media is loaded in the device.</td>
</tr>
<tr>
<td>EFIDEVICE_ERROR</td>
<td>A device error occurred while attempting to reset the bus and/or device.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The reset failed since the device and/or bus was not ready. The reset may be</td>
</tr>
<tr>
<td></td>
<td>retried at a later time.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The device does not support this type of reset.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The reset did not complete within the timeout allowed.</td>
</tr>
</tbody>
</table>

13.6.3 Tape Header Format

The boot tape will contain a Boot Tape Header to indicate it is a valid boot tape. The Boot Tape Header must be located within the first 20 blocks on the tape. One or more tape filemarks may appear prior to the Boot Tape Header so that boot tapes may include tape label files. The Boot Tape Header must begin on a block boundary and be contained completely within a block. The Boot Tape Header will have the following format:

<table>
<thead>
<tr>
<th>Bytes (Dec)</th>
<th>Value</th>
<th>Purpose</th>
</tr>
</thead>
<tbody>
<tr>
<td>0-7</td>
<td>0x544f4f4f220494645</td>
<td>Signature (‘EFI BOOT’ in ASCII)</td>
</tr>
<tr>
<td>8-11</td>
<td>1</td>
<td>Revision</td>
</tr>
<tr>
<td>12-15</td>
<td>1024</td>
<td>Tape Header Size in bytes</td>
</tr>
<tr>
<td>16-19</td>
<td>calculated</td>
<td>Tape Header CRC</td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>Offset</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>20-35</td>
<td>{ 0x8befa29a, 0x3511, 0x4cf7, { 0xa2, 0xeb, 0x5f, 0xe3, 0x7c, 0x3b, 0xf5, 0x5b } }</td>
<td>EFI Boot Tape GUID (same for all EFI Boot Tapes, like EFI Disk GUID)</td>
</tr>
<tr>
<td>36-51</td>
<td>User Defined</td>
<td>EFI Boot Tape Type GUID (bootloader / OS specific, like EFI Partition Type GUID)</td>
</tr>
<tr>
<td>52-67</td>
<td>User Defined</td>
<td>EFI Boot Tape Unique GUID (unique for every EFI Boot Tape)</td>
</tr>
<tr>
<td>68-71</td>
<td>e.g. 2</td>
<td>File Number of EFI Bootloader relative to the Boot Tape Header (first file immediately after the Boot Tape Header is file number 1, ANSI labels are counted)</td>
</tr>
<tr>
<td>72-75</td>
<td>e.g. 0x400</td>
<td>EFI Bootloader Block Size in bytes</td>
</tr>
<tr>
<td>76-79</td>
<td>e.g. 0x20000</td>
<td>EFI Bootloader Total Size in bytes</td>
</tr>
<tr>
<td>80-119</td>
<td>e.g. HPUX 11.23</td>
<td>OS Version (ASCII)</td>
</tr>
<tr>
<td>120-159</td>
<td>e.g. Ignite-UX C.6.2.241</td>
<td>Application Version (ASCII)</td>
</tr>
<tr>
<td>160-169</td>
<td>e.g.1993-02-28</td>
<td>EFI Boot Tape creation date (UTC) (yyyy-mm-dd ASCII)</td>
</tr>
<tr>
<td>170-179</td>
<td>e.g. 13:24:55</td>
<td>EFI Boot Tape creation time (UTC) (hh:mm:ss in ASCII)</td>
</tr>
<tr>
<td>180-435</td>
<td>e.g. testsys1 (alt e.g. testsys1.xyzcorp.com)</td>
<td>Computer System Name (UTF-8, ref: RFC 2044)</td>
</tr>
<tr>
<td>436-555</td>
<td>e.g. Primary Disaster Recovery</td>
<td>Boot Tape Title / Comment (UTF-8, ref: RFC 2044)</td>
</tr>
<tr>
<td>556-1023</td>
<td>reserved</td>
<td></td>
</tr>
</tbody>
</table>

All numeric values will be specified in binary format. Note that all values are specified in Little Endian byte ordering. The Boot Tape Header can also be represented as the following data structure:

```c
typedef struct EFI_TAPE_HEADER {
    UINT64    Signature;
    UINT32    Revision;
    UINT32    BootDescSize;
    UINT32    BootDescCRC;
    EFI_GUID  TapeGUID;
    EFI_GUID  TapeType;
    EFI_GUID  TapeUnique;
    UINT32    BLLocation;
    UINT32    BLBlocksize;
    UINT32    BLFileSize;
    CHAR8     OSVersion[40];
    CHAR8     AppVersion[40];
    CHAR8     CreationDate[10];
    CHAR8     CreationTime[10];
    CHAR8     SystemName[256]; // UTF-8
    CHAR8     TapeTitle[120]; // UTF-8
    CHAR8     pad[468]; // pad to 1024
} EFI_TAPE_HEADER;
```
13.7 Disk I/O Protocol

This section defines the Disk I/O protocol. This protocol is used to abstract the block accesses of the Block I/O protocol to a more general offset-length protocol. The firmware is responsible for adding this protocol to any Block I/O interface that appears in the system that does not already have a Disk I/O protocol. File systems and other disk access code utilize the Disk I/O protocol.

13.7.1 EFI_DISK_IO_PROTOCOL

Summary

This protocol is used to abstract Block I/O interfaces.

GUID

```
#define EFI_DISK_IO_PROTOCOL_GUID \
{0xCE345171,0xBA0B,0x11d2,\ 
 {0x8e,0x4F,0x00,0xa0,0xc9,0x69,0x72,0x3b}}
```

Revision Number

```
#define EFI_DISK_IO_PROTOCOL_REVISION 0x00010000
```

Protocol Interface Structure

```
typedef struct _EFI_DISK_IO_PROTOCOL {
    UINT64 Revision;
    EFI_DISK_READ ReadDisk;
    EFI_DISK_WRITE WriteDisk;
} EFI_DISK_IO_PROTOCOL;
```

Parameters

Revision

The revision to which the disk I/O interface adheres. All future revisions must be backwards compatible. If a future version is not backwards compatible, it is not the same GUID.

ReadDisk

Reads data from the disk. See the `EFI_DISK_IO_PROTOCOL.ReadDisk()` function description.

WriteDisk

Writes data to the disk. See the `EFI_DISK_IO_PROTOCOL.WriteDisk()` function description.

Description

The EFI_DISK_IO_PROTOCOL is used to control block I/O interfaces.

The disk I/O functions allow I/O operations that need not be on the underlying device’s block boundaries or alignment requirements. This is done by copying the data to/from internal buffers as needed to provide the proper requests to the block I/O device. Outstanding write buffer data is flushed by using the `EFI_BLOCK_IO_PROTOCOL.FlushBlocks()` function of the `EFI_BLOCK_IO_PROTOCOL` on the device handle.

The firmware automatically adds an EFI_DISK_IO_PROTOCOL interface to any EFI_BLOCK_IO_PROTOCOL interface that is produced. It also adds file system, or logical block I/O, interfaces to any EFI_DISK_IO_PROTOCOL interface that contains any recognized file system or logical block I/O devices. The firmware must automatically support the following required formats:

- The EFI FAT12, FAT16, and FAT32 file system type.
• The legacy master boot record partition block. (The presence of this on any block I/O device is optional, but if it is present the firmware is responsible for allocating a logical device for each partition).
• The extended partition record partition block.
• The El Torito logical block devices.

13.7.2 EFI_DISK_IO_PROTOCOL.ReadDisk()

Summary
Reads a specified number of bytes from a device.

Prototype

typedef EFI_STATUS (EFIAPIC *EFI_DISK_READ) (
    IN EFI_DISK_IO_PROTOCOL *This,
    IN UINT32 MediaId,
    IN UINT64 Offset,
    IN UINTN BufferSize,
    OUT VOID *Buffer
);

Parameters

This
Indicates a pointer to the calling context. Type EFI_DISK_IO_PROTOCOL is defined in the EFI_DISK_IO_PROTOCOL description.

MediaId
ID of the medium to be read.

Offset
The starting byte offset on the logical block I/O device to read from.

BufferSize
The size in bytes of Buffer. The number of bytes to read from the device.

Buffer
A pointer to the destination buffer for the data. The caller is responsible for either having implicit or explicit ownership of the buffer.

Description
The ReadDisk() function reads the number of bytes specified by BufferSize from the device. All the bytes are read, or an error is returned. If there is no medium in the device, the function returns EFI_NO_MEDIA. If the MediaId is not the ID of the medium currently in the device, the function returns EFI_MEDIA_CHANGED.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was read correctly from the device.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while performing the read operation.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no medium in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The MediaId is not for the current medium.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The read request contains device addresses that are not valid for the device.</td>
</tr>
</tbody>
</table>
13.7.3 EFI_DISK_IO_PROTOCOL.WriteDisk()

Summary
Writes a specified number of bytes to a device.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_DISK_WRITE) (  
  IN EFI_DISK_IO_PROTOCOL  *This,
  IN UINT32  MediaId,
  IN UINT64  Offset,
  IN UINTN  BufferSize,
  IN VOID  *Buffer
);
```

Parameters

This
Indicates a pointer to the calling context. Type EFI_DISK_IO_PROTOCOL is defined in the EFI_DISK_IO_PROTOCOL protocol description.

MediaId
ID of the medium to be written.

Offset
The starting byte offset on the logical block I/O device to write.

BufferSize
The size in bytes of Buffer. The number of bytes to write to the device.

Buffer
A pointer to the buffer containing the data to be written.

Description
The WriteDisk() function writes the number of bytes specified by BufferSize to the device. All bytes are written, or an error is returned. If there is no medium in the device, the function returns EFI_NO_MEDIA. If the MediaId is not the ID of the medium currently in the device, the function returns EFI_MEDIA_CHANGED.

Status Codes Returned

<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The data was written correctly to the device.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The device cannot be written to.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no medium in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The MediaId is not for the current medium.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while performing the write operation.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The write request contains device addresses that are not valid for the device.</td>
</tr>
</tbody>
</table>
13.8 Disk I/O 2 Protocol

The Disk I/O 2 protocol defines an extension to the Disk I/O protocol to enable non-blocking / asynchronous byte-oriented disk operation.

13.8.1 EFI_DISK_IO2_PROTOCOL

Summary

This protocol is used to abstract Block I/O interfaces in a non-blocking manner.

GUID

```c
#define EFI_DISK_IO2_PROTOCOL_GUID
{ 0x151c8eae, 0x7f2c, 0x472c,
  {0x9e, 0x54, 0x98, 0x28, 0x19, 0x4f, 0x6a, 0x88 }}
```

Revision Number

```c
#define EFI_DISK_IO2_PROTOCOL_REVISION 0x00020000
```

Protocol Interface Structure

```c
typedef struct _EFI_DISK_IO2_PROTOCOL {
  UINT64 Revision;
  EFI_DISK_CANCEL_EX Cancel;
  EFI_DISK_READ_EX ReadDiskEx;
  EFI_DISK_WRITE_EX WriteDiskEx;
  EFI_DISK_FLUSH_EX FlushDiskEx;
} EFI_DISK_IO2_PROTOCOL;
```

Parameters

Revision

The revision to which the disk I/O interface adheres. All future revisions must be backwards compatible.

Cancel

Terminate outstanding requests. See the Cancel() function description.

ReadDiskEx

Reads data from the disk. See the ReadDiskEx() function description.

WriteDiskEx

Writes data to the disk. See the WriteDiskEx() function description.

FlushDiskEx

Flushes all modified data to the physical device. See the FlushDiskEx() function description.

Description

The EFI_DISK_IO2_PROTOCOL is used to control block I/O interfaces.

The disk I/O functions allow I/O operations that need not be on the underlying device’s block boundaries or alignment requirements. This is done by copying the data to/from internal buffers as needed to provide the proper re-
quests to the block I/O device. Outstanding write buffer data is flushed by using the `FlushBlocksEx()` function of the `EFI_BLOCK_IO2_PROTOCOL` on the device handle.

The firmware automatically adds an `EFI_DISK_IO2_PROTOCOL` interface to any `EFI_BLOCK_IO2_PROTOCOL` interface that is produced. It also adds file system, or logical block I/O, interfaces to any `EFI_DISK_IO2_PROTOCOL` interface that contains any recognized file system or logical block I/O devices.

Implementations must account for cases where there is pending queued asynchronous I/O when a call is received on a blocking protocol interface. In these cases the pending I/O will be processed and completed before the blocking function is executed so that operation are carried out in the order they were requested.

### 13.8.2 EFI_DISK_IO2_PROTOCOL.Cancel()

**Summary**

Terminate outstanding asynchronous requests to a device.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_DISK_CANCEL_EX) (  
    IN EFI_DISK_IO2_PROTOCOL *This
);
```

**Parameters**

**This**

Indicates a pointer to the calling context. Type `EFI_DISK_IO2_PROTOCOL` is defined in the `EFI_DISK_IO2_PROTOCOL` description.

**Description**

The `Cancel()` function will terminate any in-flight non-blocking I/O requests by signaling the `EFI_DISK_IO2_TOKEN` Event and with `TransactionStatus` set to `EFI_ABORTED`. After the `Cancel()` function returns it is safe to free any `Token` or `Buffer` data structures that were allocated as part of the non-blocking I/O operation.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>All outstanding requests were successfully terminated.</td>
</tr>
<tr>
<td><code>EFI_DEVICE_ERROR</code></td>
<td>The device reported an error while performing the cancel operation.</td>
</tr>
</tbody>
</table>

### 13.8.3 EFI_DISK_IO2_PROTOCOL.ReadDiskEx()

**Summary**

Reads a specified number of bytes from a device.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_DISK_READ_EX) (  
    IN EFI_DISK_IO2_PROTOCOL *This,
    IN UINT32 MediaId,
    IN UINT64 Offset,
    ...
);
```
IN OUT EFI_DISK_IO2_TOKEN *Token,
IN UINTN BufferSize,
OUT VOID *Buffer
);

Parameters

This
Indicates a pointer to the calling context. Type EFI_DISK_IO2_PROTOCOL is defined in the EFI_DISK_IO2_PROTOCOL description.

MediaId
ID of the medium to be read.

Offset
The starting byte offset on the logical block I/O device to read from.

Token
A pointer to the token associated with the transaction. Type EFI_DISK_IO2_TOKEN is defined in “Related Definitions” below. If this field is NULL, synchronous/blocking IO is performed.

BufferSize
The size in bytes of Buffer. The number of bytes to read from the device.

Buffer
A pointer to the destination buffer for the data. The caller is responsible either having implicit or explicit ownership of the buffer.

Description

The ReadDiskEx() function reads the number of bytes specified by BufferSize from the device. All the bytes are read, or an error is returned. If there is no medium in the device, the function returns EFI_NO_MEDIA. If the MediaId is not the ID of the medium currently in the device, the function returns EFI_MEDIA_CHANGED.

If an error is returned from the call to ReadDiskEx() and non-blocking I/O is being requested, the Event associated with this request will not be signaled. If the call to ReadDiskEx() succeeds then the Event will be signaled upon completion of the read or if an error occurs during the processing of the request. The status of the read request can be determined from the Status field of the Token once the event is signaled.

Related Definitions

typedef struct {
    EFI_EVENT Event;
    EFI_STATUS TransactionStatus;
} EFI_DISK_IO2_TOKEN;

Event
If Event is NULL, then blocking I/O is performed. If Event is not NULL and non-blocking I/O is supported, then non-blocking I/O is performed, and Event will be signaled when the I/O request is completed. The caller must be prepared to handle the case where the callback associated with Event occurs before the original asynchronous I/O request call returns.

TransactionStatus
Defines whether or not the signaled event encountered an error.

Status Codes Returned
13.8.4 EFI_DISK_IO2_PROTOCOL.WriteDiskEx()

Summary
Writes a specified number of bytes to a device.

Prototype

typedef
EFOX_STATUS
(EIFIAPI *EFI_DISK_WRITE_EX) (  
  IN EFI_DISK_IO2_PROTOCOL *This,
  IN UINT32 MediaId,
  IN UINT64 Offset,
  IN OUT EFI_DISK_IO2_TOKEN *Token,
  IN UINTN BufferSize,
  IN VOID *Buffer
);

Parameters

This
Indicates a pointer to the calling context. Type EFI_DISK_IO2_PROTOCOL is defined in the EFI_DISK_IO2_PROTOCOL description.

MediaId
ID of the medium to be written.

Offset
The starting byte offset on the logical block I/O device to write to.

Token
A pointer to the token associated with the transaction. Type EFI_DISK_IO2_TOKEN is defined in “Related Definitions” below. If this field is NULL, synchronous/blocking IO is performed.

BufferSize
The size in bytes of Buffer. The number of bytes to write to the device.
Buffer
A pointer to the source buffer for the data. The caller is responsible.

Description
The WriteDiskEx() function writes the number of bytes specified by BufferSize to the device. All bytes are written, or an error is returned. If there is no medium in the device, the function returns EFI_NO_MEDIA. If the MediaId is not the ID of the medium currently in the device, the function returns EFI_MEDIA_CHANGED.

If an error is returned from the call to WriteDiskEx() and non-blocking I/O is being requested, the Event associated with this request will not be signaled. If the call to WriteDiskEx() succeeds then the Event will be signaled upon completion of the write or if an error occurs during the processing of the request. The status of the write request can be determined from the Status field of the Token once the event is signaled.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Returned from the call WriteDiskEx()</td>
</tr>
<tr>
<td></td>
<td>If Event is NULL (blocking I/O):</td>
</tr>
<tr>
<td></td>
<td>• The data was written correctly to the device.</td>
</tr>
<tr>
<td></td>
<td>If Event is not NULL (asynchronous I/O):</td>
</tr>
<tr>
<td></td>
<td>• The request was successfully queued for processing.</td>
</tr>
<tr>
<td></td>
<td>Event will be signaled upon completion.</td>
</tr>
<tr>
<td></td>
<td>Returned in the token after signaling Event</td>
</tr>
<tr>
<td></td>
<td>• The data was written correctly to the device.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The device cannot be written to.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while performing the write operation.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no medium in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The MediaId is not for the current medium.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The read request contains device addresses that are not valid for the device.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources</td>
</tr>
</tbody>
</table>

13.8.5 EFI_DISK_IO2_PROTOCOL.FlushDiskEx()

Summary
Flushes all modified data to the physical device.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_DISK_FLUSH_EX)(
    IN EFI_DISK_IO2_PROTOCOL *This,
    IN OUT EFI_DISK_IO2_TOKEN *Token
);

Parameters
This
Indicates a pointer to the calling context. Type EFI_DISK_IO2_PROTOCOL is defined in the EFI_DISK_IO2_PROTOCOL description.
Token

A pointer to the token associated with the transaction. Type *EFI_DISK_IO2_TOKEN* is defined in “Related Definitions” below. If this field is NULL, synchronous/blocking IO is performed.

Description

The *FlushDiskEx()* function flushes all modified data to the physical device. If an error is returned from the call to *FlushDiskEx()* and non-blocking I/O is being requested, the Event associated with this request will not be signaled. If the call to *FlushDiskEx()* succeeds then the Event will be signaled upon completion of the flush or if an error occurs during the processing of the request. The status of the flush request can be determined from the Status field of the Token once the event is signaled.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Returned from the call <em>FlushDiskEx()</em></td>
</tr>
<tr>
<td></td>
<td>If Event is NULL (blocking I/O):</td>
</tr>
<tr>
<td></td>
<td>• The data was flushed successfully to the device.</td>
</tr>
<tr>
<td></td>
<td>If Event is not NULL (asynchronous I/O):</td>
</tr>
<tr>
<td></td>
<td>• The request was successfully queued for processing.</td>
</tr>
<tr>
<td></td>
<td>Event will be signaled upon completion.</td>
</tr>
<tr>
<td></td>
<td>Returned in the token after signaling Event</td>
</tr>
<tr>
<td></td>
<td>The data was flushed successfully to the device.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The device cannot be written to.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while performing the flush operation.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no medium in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The medium in the device has changed since the last access.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Token is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources</td>
</tr>
</tbody>
</table>

13.9 Block I/O Protocol

This section defines the Block I/O protocol. This protocol is used to abstract mass storage devices to allow code running in the EFI boot services environment to access them without specific knowledge of the type of device or controller that manages the device. Functions are defined to read and write data at a block level from mass storage devices as well as to manage such devices in the EFI boot services environment.

13.9.1 EFI_BLOCK_IO_PROTOCOL

Summary

This protocol provides control over block devices.

GUID

```c
#define EFI_BLOCK_IO_PROTOCOL_GUID  
{0x964e5b21,0x6459,0x11d2,\ 
 {0x8e,0x39,0x00,0xa0,0xc9,0x69,0x72,0x3b}}
```
Revision Number

```c
#define EFI_BLOCK_IO_PROTOCOL_REVISION2 0x00020001
#define EFI_BLOCK_IO_PROTOCOL_REVISION3 ((2<<16) | (31))
```

Protocol Interface Structure

```c
typedef struct _EFI_BLOCK_IO_PROTOCOL {
    UINT64 Revision;
    EFI_BLOCK_IO_MEDIA *Media;
    EFI_BLOCK_RESET Reset;
    EFI_BLOCK_READ ReadBlocks;
    EFI_BLOCK_WRITE WriteBlocks;
    EFI_BLOCK_FLUSH FlushBlocks;
} EFI _BLOCK_IO_PROTOCOL;
```

Parameters

Revision

The revision to which the block IO interface adheres. All future revisions must be backwards compatible. If a future version is not backwards compatible it is not the same GUID.

Media

A pointer to the EFI_BLOCK_IO_MEDIA data for this device. Type EFI_BLOCK_IO_MEDIA is defined in “Related Definitions” below.

Reset

Resets the block device hardware. See the `EFI_BLOCK_IO_PROTOCOL.Reset()` function description.

ReadBlocks

Reads the requested number of blocks from the device. See the `EFI_BLOCK_IO_PROTOCOL.ReadBlocks()` function description.

WriteBlocks

Writes the requested number of blocks to the device. See the `EFI_BLOCK_IO_PROTOCOL.WriteBlocks()` function description.

FlushBlocks

Flushes any cache blocks. This function is optional and only needs to be supported on block devices that cache writes. See the `EFI_BLOCK_IO_PROTOCOL.FlushBlocks()` function description.

Related Definitions

```c
//@----------------------------------------------------
//@ EFI_BLOCK_IO_MEDIA
//@----------------------------------------------------

typedef struct {
    UINT32 MediaId;
    BOOLEAN RemovableMedia;
    BOOLEAN MediaPresent;
    BOOLEAN LogicalPartition;
    BOOLEAN ReadOnly;
    BOOLEAN WriteCaching;
    UINT32 BlockSize;
    UINT32 IoAlign;
    EFI_LBA LastBlock;
} EFI_BLOCK_IO_MEDIA;
```

(continues on next page)
The following data values in EFI_BLOCK_IO_MEDIA are read-only and are updated by the code that produces the EFI_BLOCK_IO_PROTOCOL functions:

MediaId
The current media ID. If the media changes, this value is changed.

RemovableMedia
TRUE if the media is removable; otherwise, FALSE.

MediaPresent
TRUE if there is a media currently present in the device; otherwise, FALSE. This field shows the media present status as of the most recent EFI_BLOCK_IO_PROTOCOL.ReadBlocks() or WriteBlocks() call.

LogicalPartition
TRUE if the EFI_BLOCK_IO_PROTOCOL was produced to abstract partition structures on the disk. FALSE if the BLOCK_IO protocol was produced to abstract the logical blocks on a hardware device.

ReadOnly
TRUE if the media is marked read-only otherwise, FALSE. This field shows the read-only status as of the most recent EFI_BLOCK_IO_PROTOCOL.WriteBlocks() call.

WriteCaching
TRUE if the WriteBlocks() function caches write data.

BlockSize
The intrinsic block size of the device. If the media changes, then this field is updated. Returns the number of bytes per logical block. For ATA devices, this is reported in IDENTIFY DEVICE data words 117-118 (i.e., Words per Logical Sector) (see ATA8-ACS). For SCSI devices, this is reported in the READ CAPACITY (16) parameter data Logical Block Length In Bytes field (see SBC-3).

IoAlign
Supplies the alignment requirement for any buffer used in a data transfer. IoAlign values of 0 and 1 mean that the buffer can be placed anywhere in memory. Otherwise, IoAlign must be a power of 2, and the requirement is that the start address of a buffer must be evenly divisible by IoAlign with no remainder.

LastBlock
The last LBA on the device. If the media changes, then this field is updated. For ATA devices, this is reported in IDENTIFY DEVICE data words 60-61 (i.e., Total number of user addressable logical sectors) (see ATA8-ACS) minus one. For SCSI devices, this is reported in the READ CAPACITY (16) parameter data Returned Logical Block Address field (see SBC-3) minus one.

LowestAlignedLba
Only present if EFI_BLOCK_IO_PROTOCOL.Revision is greater than or equal to EFI_BLOCK_IO_PROTOCOL_REVISION2. Returns the first LBA that is aligned to a physical block.
boundary (See GPT overview). Note that this field follows the SCSI definition, not the ATA definition. If LogicalPartition is TRUE this value will be zero.

**LogicalBlocksPerPhysicalBlock**
Only present if EFI_BLOCK_IO_PROTOCOL.Revision is greater than or equal to EFI_BLOCK_IO_PROTOCOL_REVISION2. Returns the number of logical blocks per physical block (See GPT overview). Unlike the ATA and SCSI fields that provide the information for this field, this field does not contain an exponential value. A value of 0 means there is either one logical block per physical block, or there are more than one physical block per logical block. If LogicalPartition is TRUE this value will be zero.

**OptimalTransferLengthGranularity**
Only present if EFI_BLOCK_IO_PROTOCOL.Revision is greater than or equal to EFI_BLOCK_IO_PROTOCOL_REVISION3. Returns the optimal transfer length granularity as a number of logical blocks (See GPT overview). A value of 0 means there is no reported optimal transfer length granularity. If LogicalPartition is TRUE this value will be zero.

**Description**
The LogicalPartition is TRUE if the device handle is for a partition. For media that have only one partition, the value will always be TRUE. For media that have multiple partitions, this value is FALSE for the handle that accesses the entire device. The firmware is responsible for adding device handles for each partition on such media.

The firmware is responsible for adding an EFI_DISK_IO_PROTOCOL interface to every EFI_BLOCK_IO_PROTOCOL interface in the system. The EFI_DISK_IO_PROTOCOL interface allows byte-level access to devices.

### 13.9.2 EFI_BLOCK_IO_PROTOCOL.Reset()

**Summary**
Resets the block device hardware.

**Prototype**

```c
typedef EFI_STATUS
(EIFIAPI *EFI_BLOCK_RESET) (  
    IN EFI_BLOCK_IO_PROTOCOL *This,  
    IN BOOLEAN ExtendedVerification  
    );
```

**Parameters**

**This**
Indicates a pointer to the calling context. Type EFI_BLOCK_IO_PROTOCOL is defined in the EFI_BLOCK_IO_PROTOCOL description.

**ExtendedVerification**
Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

**Description**
The Reset() function resets the block device hardware.

As part of the initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the ExtendedVerification flag is TRUE the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.
13.9.3 EFI_BLOCK_IO_PROTOCOL.ReadBlocks()

Summary
Reads the requested number of blocks from the device.

Prototype

```
typedef
EFI_STATUS
(EIFIAPI *EFI_BLOCK_READ) (  
    IN EFI_BLOCK_IO_PROTOCOL *This,  
    IN UINT32 MediaId,  
    IN EFI_LBA LBA,  
    IN UINTN BufferSize,  
    OUT VOID *Buffer
);  
```

Parameters

This
Indicates a pointer to the calling context. Type EFI_BLOCK_IO_PROTOCOL is defined in the EFI_BLOCK_IO_PROTOCOL description.

MediaId
The media ID that the read request is for.

LBA
The starting logical block address to read from on the device. Type EFI_LBA is defined in the EFI_BLOCK_IO_PROTOCOL description.

BufferSize
The size of the Buffer in bytes. This must be a multiple of the intrinsic block size of the device.

Buffer
A pointer to the destination buffer for the data. The caller is responsible for either having implicit or explicit ownership of the buffer.

Description
The ReadBlocks() function reads the requested number of blocks from the device. All the blocks are read, or an error is returned.

If there is no media in the device, the function returns EFI_NO_MEDIA. If the MediaId is not the ID for the current media in the device, the function returns EFI_MEDIA_CHANGED. The function must return EFI_NO_MEDIA or EFI_MEDIA_CHANGED even if LBA, BufferSize, or Buffer are invalid so the caller can probe for changes in media state.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was read correctly from the device.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while attempting to perform the read operation.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no media in the device.</td>
</tr>
</tbody>
</table>

continues on next page
### 13.9.4 EFI_BLOCK_IO_PROTOCOL.WriteBlocks()

**Summary**

Writes a specified number of blocks to the device.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_BLOCK_WRITE) (
    IN EFI_BLOCK_IO_PROTOCOL *This,
    IN UINT32 MediaId,
    IN EFI_LBA LBA,
    IN UINTN BufferSize,
    IN VOID *Buffer
);
```

**Parameters**

- **This**
  
  Indicates a pointer to the calling context. Type is defined in the See `EFI_BLOCK_IO_PROTOCOL` description.

- **MediaId**
  
  The media ID that the write request is for.

- **LBA**
  
  The starting logical block address to be written. The caller is responsible for writing to only legitimate locations. Type EFI_LBA is defined in the `EFI_BLOCK_IO_PROTOCOL` description.

- **BufferSize**
  
  The size in bytes of Buffer. This must be a multiple of the intrinsic block size of the device.

- **Buffer**
  
  A pointer to the source buffer for the data.

**Description**

The WriteBlocks() function writes the requested number of blocks to the device. All blocks are written, or an error is returned.

If there is no media in the device, the function returns EFI_NO_MEDIA. If the MediaId is not the ID for the current media in the device, the function returns EFI_MEDIA_CHANGED. The function must return EFI_NO_MEDIA or EFI_MEDIA_CHANGED even if LBA, BufferSize, or Buffer are invalid so the caller can probe for changes in media state.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data were written correctly to the device.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The device cannot be written to.</td>
</tr>
</tbody>
</table>
Table 13.32 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no media in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The MediaId is not for the current media.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while attempting to perform the write operation.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>The BufferSize parameter is not a multiple of the intrinsic block size of the device.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The write request contains LBAs that are not valid, or the buffer is not on proper alignment.</td>
</tr>
</tbody>
</table>

### 13.9.5 EFI_BLOCK_IO_PROTOCOL.FlushBlocks()

**Summary**

Flushes all modified data to a physical block device.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_BLOCK_FLUSH) (IN EFI_BLOCK_IO_PROTOCOL *This);
```

**Parameters**

**This**

Indicates a pointer to the calling context. Type EFI_BLOCK_IO_PROTOCOL is defined in the EFI_BLOCK_IO_PROTOCOL protocol description.

**Description**

The FlushBlocks() function flushes all modified data to the physical block device.

All data written to the device prior to the flush must be physically written before returning EFI_SUCCESS from this function. This would include any cached data the driver may have cached, and cached data the device may have cached. A flush may cause a read request following the flush to force a device access.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>All outstanding data were written correctly to the device.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while attempting to write data.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no media in the device.</td>
</tr>
</tbody>
</table>

### 13.10 Block I/O 2 Protocol

The Block I/O 2 protocol defines an extension to the Block I/O protocol which enables the ability to read and write data at a block level in a non-blocking manner.
13.10.1 EFI_BLOCK_IO2_PROTOCOL

Summary
This protocol provides control over block devices.

GUID
#define EFI_BLOCK_IO2_PROTOCOL_GUID
{0xa77b2472, 0xe282, 0x4e9f, \
 {0xa2, 0x45, 0xc2, 0xc0, 0xe2, 0x7b, 0xbc, 0xc1}}

Protocol Interface Structure
typedef struct _EFI_BLOCK_IO2_PROTOCOL {
    EFI_BLOCK_IO_MEDIA *Media;
    EFI_BLOCK_RESET_EX Reset;
    EFI_BLOCK_READ_EX ReadBlocksEx;
    EFI_BLOCK_WRITE_EX WriteBlocksEx;
    EFI_BLOCK_FLUSH_EX FlushBlocksEx;
} EFI_BLOCK_IO2_PROTOCOL;

Parameters
Media
A pointer to the EFI_BLOCK_IO_MEDIA data for this device. Type EFI_BLOCK_IO_MEDIA is defined in the EFI_BLOCK_IO_PROTOCOL section.

Reset
Resets the block device hardware. See the EFI_BLOCK_IO_PROTOCOL.Reset() function description following below.

ReadBlocksEx
Reads the requested number of blocks from the device. See the EFI_BLOCK_IO2_PROTOCOL function description.

WriteBlocksEx
Writes the requested number of blocks to the device. See the EFI_BLOCK_IO2_PROTOCOL.WriteBlocksEx() function description.

FlushBlocksEx
Flushes any cache blocks. This function is optional and only needs to be supported on block devices that cache writes. See the EFI_BLOCK_IO2_PROTOCOL.FlushBlocksEx() function description.

13.10.2 EFI_BLOCK_IO2_PROTOCOL.Reset()

Summary
Resets the block device hardware.

Prototype
typedef
EFI_STATUS
(DECLSPEC(EFIAPI) EFI_BLOCK_RESET_EX) (*EFIAPI)(
    IN EFI_BLOCK_IO2_PROTOCOL *This,
    IN BOOLEAN ExtendedVerification
);
Parameters

This
Indicates a pointer to the calling context. Type `EFI_BLOCK_IO2_PROTOCOL` is defined in the `EFI_BLOCK_IO2_PROTOCOL` description.

ExtendedVerification
Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description

The `Reset()` function resets the block device hardware.

As part of the initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the `ExtendedVerification` flag is `TRUE` the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.

The `Reset()` function will terminate any in-flight non-blocking I/O requests by signaling an `EFI_ABORTED` in the `TransactionStatus` member of the `EFI_BLOCK_IO2_TOKEN` for the non-blocking I/O. After the `Reset()` function returns it is safe to free any `Token` or `Buffer` data structures that were allocated to initiate the non-blocking I/O requests that were in-flight for this device.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The block device was reset.</td>
</tr>
<tr>
<td><code>EFI_DEVICE_ERROR</code></td>
<td>The block device is not functioning correctly and could not be reset.</td>
</tr>
</tbody>
</table>

13.10.3 EFI_BLOCK_IO2_PROTOCOL.ReadBlocksEx()

Summary

Reads the requested number of blocks from the device.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BLOCK_READ_EX) (  
  IN EFI_BLOCK_IO2_PROTOCOL  *This,  
  IN UINT32 MediaId,  
  IN EFI_LBA LBA,  
  IN OUT EFI_BLOCK_IO2_TOKEN Token,  
  IN UINTN BufferSize,  
  OUT VOID *Buffer );
```

Parameters

This
Indicates a pointer to the calling context. Type `EFI_BLOCK_IO2_PROTOCOL` is defined in the `EFI_BLOCK_IO2_PROTOCOL` description.

MediaId
The media ID that the read request is for.
LBA
The starting logical block address to read from on the device. Type \textit{EFI_LBA} is defined in the \textit{EFI_BLOCK_IO_PROTOCOL} description.

Token
A pointer to the token associated with the transaction. Type \textit{EFI_BLOCK_IO2_TOKEN} is defined in “Related Definitions” below.

BufferSize
The size of the \textit{Buffer} in bytes. This must be a multiple of the intrinsic block size of the device.

Buffer
A pointer to the destination buffer for the data. The caller is responsible for either having implicit or explicit ownership of the buffer.

Description
The \textit{ReadBlocksEx()} function reads the requested number of blocks from the device. All the blocks are read, or an error is returned.

If there is no media in the device, the function returns \textit{EFI_NO_MEDIA}. If the MediaId is not the ID for the current media in the device, the function returns \textit{EFI_MEDIA_CHANGED}. The function must return \textit{EFI_NO_MEDIA} or \textit{EFI_MEDIA_CHANGED} even if \textit{LBA}, \textit{BufferSize}, or \textit{Buffer} are invalid so the caller can probe for changes in media state.

If \textit{EFI_DEVICE_ERROR}, \textit{EFI_NO_MEDIA}, *, or \textit{EFI_MEDIA_CHANGED} is returned and non-blocking I/O is being used, the \textit{Event} associated with this request will not be signaled.

Related Definitions

\begin{verbatim}
typedef struct {
  EFI_EVENT Event;
  EFI_STATUS TransactionStatus;
} EFI_BLOCK_IO2_TOKEN;
\end{verbatim}

Event
If \textit{Event} is \texttt{NULL}, then blocking I/O is performed. If \textit{Event} is not \texttt{NULL} and non-blocking I/O is supported, then non-blocking I/O is performed, and \textit{Event} will be signaled when the read request is completed.

TransactionStatus
Defines whether the signaled event encountered an error.

Status Codes Returned

\begin{tabular}{|l|l|}
\hline
\textbf{EFI_SUCCESS} & The read request was queued if Token-> Event is not \texttt{NULL}. The data was read correctly from the device if the Token-> Event is \texttt{NULL}.
\hline
\textbf{EFI_DEVICE_ERROR} & The device reported an error while attempting to perform the read operation.
\hline
\textbf{EFI_NO_MEDIA} & There is no media in the device.
\hline
\textbf{EFI_MEDIA_CHANGED} & The \textit{MediaId} is not for the current media.
\hline
\textbf{EFI_BAD_BUFFER_SIZE} & The \textit{BufferSize} parameter is not a multiple of the intrinsic block size of the device.
\hline
\textbf{EFI_INVALID_PARAMETER} & The read request contains LBAs that are not valid, or the buffer is not on proper alignment.
\hline
\textbf{EFI_OUT_OF_RESOURCES} & The request could not be completed due to a lack of resources.
\hline
\end{tabular}
13.10.4 EFI_BLOCK_IO2_PROTOCOL.WriteBlocksEx()

Summary

Writes a specified number of blocks to the device.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_BLOCK_WRITE_EX) (  
    IN EFI_BLOCK_IO2_PROTOCOL *This,  
    IN UINT32 MediaId,  
    IN EFI_LBA LBA,  
    IN OUT EFI_BLOCK_IO2_TOKEN *Token,  
    IN UINTN BufferSize,  
    IN VOID *Buffer
    );

Parameters

This

Indicates a pointer to the calling context. Type EFI_BLOCK_IO2_PROTOCOL is defined in the EFI_BLOCK_IO2_PROTOCOL description.

MediaId

The media ID that the write request is for.

LBA

The starting logical block address to be written. The caller is responsible for writing to only legitimate locations. Type EFI_LBA is defined in the EFI_BLOCK_IO2_PROTOCOL description.

Token

A pointer to the token associated with the transaction. Type EFI_BLOCK_IO2_TOKEN is defined in EFI_BLOCK_IO2_PROTOCOL.ReadBlocksEx() “Related Definitions”.

BufferSize

The size in bytes of Buffer. This must be a multiple of the intrinsic block size of the device.

Buffer

A pointer to the source buffer for the data.

Description

The WriteBlocksEx() function writes the requested number of blocks to the device. All blocks are written, or an error is returned.

If there is no media in the device, the function returns EFI_NO_MEDIA. If the MediaId is not the ID for the current media in the device, the function returns EFI_MEDIA_CHANGED. The function must return EFI_NO_MEDIA or EFI_MEDIA_CHANGED even if LBA, BufferSize, or Buffer are invalid so the caller can probe for changes in media state.

If EFI_DEVICE_ERROR, EFI_NO_MEDIA, *_EFI_WRITE_PROTECTED* or EFI_MEDIA_CHANGED is returned and non-blocking I/O is being used, the Event associated with this request will not be signaled.

Related Definitions
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS TransactionStatus;
} EFI_BLOCK_IO2_TOKEN;

Event
    If Event is NULL, then blocking I/O is performed. If Event is not NULL and non-blocking I/O is supported, then non-blocking I/O is performed, and Event will be signaled when the write request is completed.

TransactionStatus
    Defines whether the signaled event encountered an error.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The write request was queued if Event is not NULL. The data was written correctly to the device if the Event is NULL.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The device cannot be written to.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no media in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The Mediald is not for the current media.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while attempting to perform the write operation.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>The BufferSize parameter is not a multiple of the intrinsic block size of the device.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The write request contains LBAs that are not valid, or the buffer is not on proper alignment.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources</td>
</tr>
</tbody>
</table>

13.10.5 EFI_BLOCK_IO2_PROTOCOL.FlushBlocksEx()

Summary
    Flushes all modified data to a physical block device.

Prototype

typedef EFI_STATUS
(EIFIAPI *EFI_BLOCK_FLUSH_EX) (  
    IN EFI_BLOCK_IO2_PROTOCOL *This,
    IN OUT EFI_BLOCK_IO2_TOKEN *Token,
);  

Parameters

This
    Indicates a pointer to the calling context. Type EFI_BLOCK_IO2_PROTOCOL is defined in the EFI_BLOCK_IO2_PROTOCOL protocol description.

Token
    A pointer to the token associated with the transaction. Type EFI_BLOCK_IO2_TOKEN is defined in EFI_BLOCK_IO2_PROTOCOL.ReadBlocksEx() “Related Definitions”.

Related Definitions
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS TransactionStatus;
} EFI_BLOCK_IO2_TOKEN;

Event
If Event is NULL, then blocking I/O is performed. If Event is not NULL and non-blocking I/O is supported, then non-blocking I/O is performed, and Event will be signaled when the flush request is completed.

TransactionStatus
Defines whether the signaled event encountered an error.

Description
The FlushBlocksEx() function flushes all modified data to the physical block device.
All data written to the device prior to the flush must be physically written before returning EFI_SUCCESS from this function. This would include any cached data the driver may have cached, and cached data the device may have cached. A flush may cause a read request following the flush to force a device access.
If EFI_DEVICE_ERROR, EFI_NO_MEDIA, EFI_WRITE_PROTECTED or EFI_MEDIA_CHANGED is returned and non-blocking I/O is being used, the Event associated with this request will not be signaled.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The flush request was queued if Event is not NULL. All outstanding data was written correctly to the device if the Event is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while attempting to write data.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The device cannot be written to.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no media in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The MediaId is not for the current media.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

13.11 Inline Cryptographic Interface Protocol

13.11.1 EFI_BLOCK_IO_CRYPTO_PROTOCOL

Summary
The UEFI Inline Cryptographic Interface protocol provides services to abstract access to inline cryptographic capabilities.

The usage model of this protocol is similar to the one of the EFI_STORAGE_SECURITY_COMMAND_PROTOCOL where FDE (Full Disk Encryption) solutions leave ESP partition unprotected (uncrypted) allowing storage clients to continue using EFI_BLOCK_IO_PROTOCOL or EFI_BLOCK_IO2_PROTOCOL protocol interfaces to load OS boot components from ESP partition. For other partitions boot apps (including OS boot app) that are enlightened to take advantage of inline cryptographic capability will be empowered to use this new protocol.

GUID
#define EFI_BLOCK_IO_CRYPTO_PROTOCOL_GUID \
{0xa00490ba,0x3f1a,0x4b4c,\} \
{0xab,0x90,0x4f,0xa9,0x97,0xa1,0xe8}
```c
typedef struct _EFI_BLOCK_IO_CRYPTO_PROTOCOL {
    EFI_BLOCK_IO_MEDIA *Media;
    EFI_BLOCK_IO_CRYPTO_RESET Reset;
    EFI_BLOCK_IO_CRYPTO_GET_CAPABILITIES GetCapabilities;
    EFI_BLOCK_IO_CRYPTO_SET_CONFIGURATION SetConfiguration;
    EFI_BLOCK_IO_CRYPTO_GET_CONFIGURATION GetConfiguration;
    EFI_BLOCK_IO_CRYPTO_READ_DEVICE_EXTENDED ReadExtended;
    EFI_BLOCK_IO_CRYPTO_WRITE_DEVICE_EXTENDED WriteExtended;
    EFI_BLOCK_IO_CRYPTO_FLUSH FlushBlocks;
} EFI_BLOCK_IO_CRYPTO_PROTOCOL;
```

**Parameters**

**Media**

A pointer to the `EFI_BLOCK_IO_MEDIA` data for this device. Type `EFI_BLOCK_IO_MEDIA` is defined in the `EFI_BLOCK_IO_PROTOCOL` section.

**Reset**

Reset the block device hardware.

**GetCapabilities**

Get the current capabilities of the ICI.

**SetConfiguration**

Set the configuration for the ICI instance.

**GetConfiguration**

Get the configuration for the ICI instance.

**ReadExtended**

Provide an extended version of the storage device read command.

**WriteExtended**

Provide an extended version of the storage device write command.

**FlushBlocks**

Flushes any cache blocks. This function is optional and only needs to be supported on block devices that cache writes.

**Related Definitions**

Some functions defined for this protocol require the caller to specify the device capabilities, keys and/or attributes of the keys to be used. These parameters must be consistent with the supported capabilities as reported by the device.

```c
typedef struct {
    EFI_GUID Algorithm;
    UINT64 KeySize;
    UINT64 CryptoBlockSizeBitMask;
} EFI_BLOCK_IO_CRYPTO_CAPABILITY;
```

**Algorithm**

GUID of the algorithm.

**KeySize**

Specifies `KeySize` in bits used with this Algorithm.

**CryptoBlockSizeBitMask**

Specifies bitmask of block sizes supported by this algorithm. Bit j being set means that 2^j bytes crypto block size is supported.
#define EFI_BLOCK_IO_CRYPTO_ALGO_GUID_AES_XTS  
{0x2f87ba6a,\  
 0x5c04,0x4385,0xa7,0x80,0xf3,0xbf,0x78,0xa9,0x7b,0xec}

EFI_BLOCK_IO_CRYPTO_ALGO_GUID_AES_XTS GUID represents Inline Cryptographic Interface capability supporting AES XTS crypto algorithm as described in IEEE Std 1619-2007: IEEE Standard for Cryptographic Protection of Data on Block-Oriented Storage Devices.

typedef struct {  
  EFI_BLOCK_IO_CRYPTO_IV_INPUT Header;  
  UINT64 CryptoBlockNumber;  
  UINT64 CryptoBlockByteSize;  
} EFI_BLOCK_IO_CRYPTO_IV_INPUT_AES_XTS;

EFI_BLOCK_IO_CRYPTO_IV_INPUT_AES_XTS structure is used as CryptoIvInput parameter to the ReadExtended and WriteExtended methods for Inline Cryptographic Interface supporting and using AES XTS algorithm with IV input as defined for AES XTS algorithm. IO operation (read or write) range should consist of one or more blocks of CryptoBlockByteSize size. CryptoBlockNumber is used as the AES XTS IV for the first crypto block and is incremented by one for each consecutive crypto block in the IO operation range.

#define EFI_BLOCK_IO_CRYPTO_ALGO_GUID_AES_CBC_MICROSOFT_BITLOCKER  
{0x689e4c62,\  
 0x70bf,0x4cf3,0x88,0xbb,0x33,0xb3,0x18,0x26,0x86,0x70}

EFI_BLOCK_IO_CRYPTO_ALGO_GUID_AES_CBC_MICROSOFT_BITLOCKER GUID represents Inline Cryptographic Interface capability supporting AES CBC crypto algorithm in the non-diffuser mode as described in following Microsoft white paper, section 4: See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Inline Cryptographic Interface–Bit Locker Cipher”. It is important to note that when excluding diffuser operations (A diffuser and B diffuser) described in the above document one should also exclude derivation of sector key and XOR-ing it with plaintext as that operation is part of the diffuser part of the algorithm and does not belong to the AES-CBC Microsoft BitLocker algorithm being referred to here.

typedef struct {  
  EFI_BLOCK_IO_CRYPTO_IV_INPUT Header;  
  UINT64 CryptoBlockByteOffset;  
  UINT64 CryptoBlockByteSize;  
} EFI_BLOCK_IO_CRYPTO_IV_INPUT_AES_CBC_MICROSOFT_BITLOCKER;

EFI_BLOCK_IO_CRYPTO_IV_INPUT_AES_CBC_MICROSOFT_BITLOCKER structure is used to pass as CryptoIvInput parameter to the ReadExtended and WriteExtended methods for Inline Cryptographic Interface supporting and using AES CBC algorithm with IV input as defined for Microsoft BitLocker Drive Encryption. IO operation (read or write) range should consist of one or more blocks of CryptoBlockByteSize size. CryptoBlockByteOffset is used as the AES CBC Microsoft Bitlocker algorithm IV for the first crypto block and is incremented by CryptoBlockByteSize for each consecutive crypto block in the IO operation range.

typedef struct {  
  UINT64 InputSize;  
} EFI_BLOCK_IO_CRYPTO_IV_INPUT;

 EFI_BLOCK_IO_CRYPTO_IV_INPUT structure is used as a common header in CryptoIvInput parameters passed to the ReadExtended and WriteExtended methods for Inline Cryptographic Interface. Its purpose is to pass size of the entire CryptoIvInput parameter memory buffer to the Inline Cryptographic Interface.

Further extensions of crypto algorithm support by Inline Cryptographic Interface should follow the same pattern established above for the AES XTS and AES CBC Microsoft BitLocker algorithms. In particular each added crypto
algorithm should:

- Define its crypto algorithm GUID using following pattern:

```c
#define EFI_BLOCK_IO_CRYPTO_ALGO_GUID_<algo-name> {<algo-guid>}
```

- Define its corresponding `CryptoIvInput` parameter structure and describe how it is populated for each IO operation (read / write):

```c
typedef struct {
    EFI_BLOCK_IO_CRYPTO_IV_INPUT Header;
    <TBD> <TBD>;
} EFI_BLOCK_IO_CRYPTO_IV_INPUT_<algo-name>;
```

```c
#define EFI_BLOCK_IO_CRYPTO_INDEX_ANY 0xFFFFFFFFFFFFFFFF
```

```c
typedef struct {
    BOOLEAN Supported;
    UINT64 KeyCount;
    UINT64 CapabilityCount;
    EFI_BLOCK_IO_CRYPTO_CAPABILITY Capabilities [1];
} EFI_BLOCK_IO_CRYPTO_CAPABILITIES;
```

**Supported**

Is inline cryptographic capability supported on this device.

**KeyCount**

Maximum number of keys that can be configured at the same time.

**CapabilityCount**

Number of supported capabilities.

**Capabilities**

Array of supported capabilities.

```c
typedef struct {
    UINT64 Index;
    EFI_GUID KeyOwnerGuid;
    EFI_BLOCK_IO_CRYPTO_CAPABILITY Capability;
    VOID *CryptoKey;
} EFI_BLOCK_IO_CRYPTO_CONFIGURATION_TABLE_ENTRY;
```

**Index**

Configuration table index. A special Index `EFI_BLOCK_IO_CRYPTO_INDEX_ANY` can be used to set any available entry in the configuration table.

**KeyOwnerGuid**

Identifies the owner of the configuration table entry. Entry can also be used with the Nil value to clear key from the configuration table index.

**Capability**

A supported capability to be used. The `CryptoBlockSizeBitMask` field of the structure should have only one bit set from the supported mask.

**CryptoKey**

Pointer to the key. The size of the key is defined by the `KeySize` field of the capability specified by the Capability parameter.

---

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typedef struct {
    UINT64 Index;
    EFI_GUID KeyOwnerGuid;
    EFI_BLOCK_IO_CRYPTO_CAPABILITY Capability;
} EFI_BLOCK_IO_CRYPTO_RESPONSE_CONFIGURATION_ENTRY;

Index
Configuration table index.

KeyOwnerGuid
Identifies the current owner of the entry.

Capability
The capability to be used. The CryptoBlockSizeBitMask field of the structure has only one bit set from the supported mask.

Description
The EFI_BLOCK_IO_CRYPTO_PROTOCOL defines a UEFI protocol that can be used by UEFI drivers and applications to perform block encryption on a storage device, such as UFS.

The EFI_BLOCK_IO_CRYPTO_PROTOCOL instance will be on the same handle as the device path of the inline encryption device.

While this protocol is intended to abstract the encryption process for block device access, the protocol user does not have to be aware of the specific underlying encryption hardware.

13.11.2 EFI_BLOCK_IO_CRYPTO_PROTOCOL.Reset()

Summary
Resets the block device hardware.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_BLOCK_IO_CRYPTO_RESET) (  
In EFI_BLOCK_IO_CRYPTO_PROTOCOL *This,
In BOOLEAN ExtendedVerification
);

Parameters

This
Pointer to the EFI_BLOCK_IO_CRYPTO_PROTOCOL instance.

ExtendedVerification
Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description
The Reset() function resets the block device hardware.

As part of the initialization process, the firmware/device will make a quick but reasonable attempt to verify that the device is functioning. If the ExtendedVerification flag is TRUE the firmware may take an extended amount of time to verify the device is operating on reset. Otherwise the reset operation is to occur as quickly as possible.

The hardware verification process is not defined by this specification and is left up to the platform firmware or driver to implement.

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Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The block device was reset.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The block device is not functioning correctly and could not be reset.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
</tbody>
</table>

13.11.3 EFI_BLOCK_IO_CRYPTO_PROTOCOL.GetCapabilities()

Summary
Get the capabilities of the underlying inline cryptographic interface.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *
EFI_BLOCK_IO_CRYPTO_GET_CAPABILITIES) (  
  IN EFI_BLOCK_IO_CRYPTO_PROTOCOL *This,
  OUT EFI_BLOCK_IO_CRYPTO_CAPABILITIES *Capabilities
);
```

Parameters

**This**
Pointer to the `EFI_BLOCK_IO_CRYPTO_PROTOCOL` instance.

**Capabilities**
Pointer to the `EFI_BLOCK_IO_CRYPTO_CAPABILITIES` structure.

Description
The `GetCapabilities()` function determines whether pre-OS controllable inline crypto is supported by the system for the current disk and, if so, returns the capabilities of the crypto engine.

The caller is responsible for providing the Capabilities structure with a sufficient number of entries. If the structure is too small, the `EFI_BUFFER_TOO_SMALL` error code is returned and the CapabilityCount field contains the number of entries needed to contain the capabilities.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The ICI is ready for use.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The Capabilities structure was too small.</td>
</tr>
<tr>
<td></td>
<td>The number of entries needed is returned in the CapabilityCount field of the structure.</td>
</tr>
<tr>
<td>EFI_NO_RESPONSE</td>
<td>No response was received from the ICI</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An error occurred when attempting to access the ICI</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>This</code> is NULL.</td>
</tr>
<tr>
<td></td>
<td>Capabilities is NULL</td>
</tr>
</tbody>
</table>
13.11.4 EFI_BLOCK_IO_CRYPTO_PROTOCOL.SetConfiguration()

Summary
Set the configuration of the underlying inline cryptographic interface.

Prototype

```c
typedef EFI_STATUS
(EFIAPIC *EFI_BLOCK_IO_CRYPTO_SET_CONFIGURATION) (
  IN EFI_BLOCK_IO_CRYPTO_PROTOCOL *This,
  IN UINT64 ConfigurationCount,
  IN EFI_BLOCK_IO_CRYPTO_CONFIGURATION_TABLE_ENTRY *ConfigurationTable,
  OUT EFI_BLOCK_IO_CRYPTO_RESPONSE_CONFIGURATION_ENTRY *ResultingTable OPTIONAL
);
```

Parameters

This
Pointer to the EFI_BLOCK_IO_CRYPTO_PROTOCOL instance.

ConfigurationCount
Number of entries being configured with this call.

ConfigurationTable
Pointer to a table used to populate the configuration table.

ResultingTable
Optional pointer to a table that receives the newly configured entries.

Description

The SetConfiguration() function allows the user to set the current configuration of the inline cryptographic interface and should be called before attempting any crypto operations.

This configures the configuration table entries with algorithms, key sizes and keys. Each configured entry can later be referred to by index at the time of storage transaction.

The configuration table index will refer to the combination of KeyOwnerGuid, Algorithm, and CryptoKey. KeyOwnerGuid identifies the component taking ownership of the entry. It helps components to identify their own entries, cooperate with other owner components, and avoid conflicts. This Guid identifier is there to help coordination between cooperating components and not a security or synchronization feature. The Nil GUID can be used by a component to release use of entry owned. It is also used to identify potentially available entries (see GetConfiguration).

CryptoKey specifies algorithm-specific key material to use within parameters of selected crypto capability.

This function is called infrequently - typically once, on device start, before IO starts. It can be called at later times in cases the number of keys used on the drive is higher than what can be configured at a time or a new key has to be added.

Components setting or changing an entry or entries for a given index or indices must ensure that IO referencing affected indices is temporarily blocked (run-down) at the time of change.

Indices parameters in each parameter table entry allow to set only a portion of the available table entries in the crypto module anywhere from single entry to entire table supported.

If corresponding table entry or entries being set are already in use by another owner the call should be failed and none of the entries should be modified. The interface implementation must enforce atomicity of this
operation (should either succeed fully or fail completely without modifying state). Note that components using GetConfiguration command to discover available entries should be prepared that by the time calling SetConfiguration the previously available entry may have become occupied. Such components should be prepared to re-try the sequence of operations. Alternatively \texttt{EFI\_BLOCK\_IO\_CRYPTO\_INDEX\_ANY} can be used to have the implementation discover and allocate available, if any, indices atomically.

An optional ResultingTable pointer can be provided by the caller to receive the newly configured entries. The array provided by the caller must have at least \texttt{ConfigurationCount} of entries.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\texttt{EFI_SUCCESS}</td>
<td>The ICI is ready for use.</td>
</tr>
<tr>
<td>\texttt{EFI_NO_RESPONSE}</td>
<td>No response was received from the ICI</td>
</tr>
<tr>
<td>\texttt{EFI_DEVICE_ERROR}</td>
<td>An error occurred when attempting to access the ICI</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>This is \texttt{NULL}.</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>ConfigurationTable is \texttt{NULL}.</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>ConfigurationCount is 0.</td>
</tr>
<tr>
<td>\texttt{EFI_OUT_OF_RESOURCES}</td>
<td>Could not find the requested number of available entries in the configuration table.</td>
</tr>
</tbody>
</table>

### 13.11.5 \texttt{EFI\_BLOCK\_IO\_CRYPTO\_PROTOCOL.GetConfiguration()}

**Summary**

Get the configuration of the underlying inline cryptographic interface.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_BLOCK_IO_CRYPTO_GET_CONFIGURATION) (  
    IN EFI_BLOCK_IO_CRYPTO_PROTOCOL *This,  
    IN UINT64 StartIndex,  
    IN UINT64 ConfigurationCount,  
    IN EFI_GUID *KeyOwnerGuid OPTIONAL,  
    OUT EFI_BLOCK_IO_CRYPTO_RESPONSE_CONFIGURATION_ENTRY *ConfigurationTable
);
```

**Parameters**

- **This**
  - Pointer to the \texttt{EFI\_BLOCK\_IO\_CRYPTO\_PROTOCOL} instance.

- **StartIndex**
  - Configuration table index at which to start the configuration query.

- **ConfigurationCount**
  - Number of entries to return in the response table.

- **KeyOwnerGuid**
  - Optional parameter to filter response down to entries with a given owner. A pointer to the Nil value can be used to return available entries. Set to NULL when no owner filtering is required.

- **ConfigurationTable**
  - Table of configured configuration table entries (with no CryptoKey returned): configuration table index, \texttt{KeyOwnerGuid}, Capability. Should have sufficient space to store up to \texttt{ConfigurationCount} entries.
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Description

The GetConfiguration() function allows the user to get the configuration of the inline cryptographic interface.

Retrieves, entirely or partially, the currently configured key table. Note that the keys themselves are not retrieved, but rather just indices, owner GUIDs and capabilities.

If fewer entries than specified by ConfigurationCount are returned, the Index field of the unused entries is set to EFI_BLOCK_IO_CRYPTO_INDEX_ANY.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The ICI is ready for use.</td>
</tr>
<tr>
<td>EFI_NO_RESPONSE</td>
<td>No response was received from the ICI</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An error occurred when attempting to access the ICI</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Configuration table is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>StartIndex is out of bounds.</td>
</tr>
</tbody>
</table>

13.11.6 EFI_BLOCK_IO_CRYPTO_PROTOCOL.ReadExtended()

Summary

Reads the requested number of blocks from the device and optionally decrypts them inline.

Prototype

```c
typedef EFI_STATUS
  (EFIAPI *EFI_BLOCK_IO_CRYPTO_READ_EXTENDED) (  
    IN EFI_BLOCK_IO_CRYPTO_PROTOCOL *This, 
    IN UINT32 MediaId, 
    IN EFI_LBA LBA, 
    IN OUT EFI_BLOCK_IO_CRYPTO_TOKEN *Token, 
    IN UINT64 BufferSize, 
    OUT VOID *Buffer, 
    IN UINT64 *Index OPTIONAL, 
    IN VOID *CryptoIvInput OPTIONAL
  );
```

Parameters

This

Pointer to the EFI_BLOCK_IO_CRYPTO_PROTOCOL instance.

MediaId

The media ID that the read request is for.

LBA

The starting logical block address to read from on the device. Type EFI_LBA is defined in the EFI_BLOCK_IO_PROTOCOL description.

Token

A pointer to the token associated with the transaction. Type EFI_BLOCK_IO_CRYPTO_TOKEN is defined in “Related Definitions” below.

BufferSize

The size of the Buffer in bytes. This must be a multiple of the intrinsic block size of the device.
Buffer
A pointer to the destination buffer for the data. The caller is responsible for either having implicit or explicit ownership of the buffer.

Index
A pointer to the configuration table index. This is optional.

CryptoIvInput
A pointer to a buffer that contains additional cryptographic parameters as required by the capability referenced by the configuration table index, such as cryptographic initialization vector.

Description
The ReadExtended() function allows the caller to perform a storage device read operation. The function reads the requested number of blocks from the device and then if Index is specified decrypts them inline. All the blocks are read and decrypted (if decryption requested), or an error is returned.

If there is no media in the device, the function returns EFI_NO_MEDIA. If the MediaId is not the ID for the current media in the device, the function returns EFI_MEDIA_CHANGED.

If EFI_DEVICE_ERROR, EFI_NO_MEDIA, or EFI_MEDIA_CHANGED is returned and non-blocking I/O is being used, the Event associated with this request will not be signaled.

In addition to standard storage transaction parameters (LBA, IO size, and buffer), this command will also specify a configuration table Index and CryptoIvInput when data has to be decrypted inline by the controller after being read from the storage device. If an Index parameter is not specified, no decryption is performed.

Related Definitions
typedef struct {
   EFI_EVENT Event;
   EFI_STATUS TransactionStatus;
} EFI_BLOCK_IO_CRYPTO_TOKEN;

Event
If Event is NULL, then blocking I/O is performed. If Event is not NULL and non-blocking I/O is supported, then non-blocking I/O is performed, and Event will be signaled when the read request is completed and data was decrypted (when Index was specified).

TransactionStatus
Defines whether or not the signaled event encountered an error.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The read request was queued if Token-&gt; Event is not NULL. The data was read correctly from the device if the Token-&gt; Event is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while attempting to perform the read operation and/or decryption operation.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no media in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The MediaId is not for the current media.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>The BufferSize parameter is not a multiple of the intrinsic block size of the device.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL, or the read request contains LBAs that are not valid, or the buffer is not on proper alignment.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>CryptoIvInput is incorrect.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>
13.11.7 EFI_BLOCK_IO_CRYPTO_PROTOCOL.WriteExtended()

Summary
Optionally encrypts a specified number of blocks inline and then writes to the device.

Prototype

```
typedef EFI_STATUS
  (EFIAPI *EFI_BLOCK_IO_CRYPTO_WRITE_EXTENDED) (
    IN EFI_BLOCK_IO_CRYPTO_PROTOCOL *This,
    IN UINT32 MediaId,
    IN EFI_LBA LBA,
    IN OUT EFI_BLOCK_IO_CRYPTO_TOKEN *Token,
    IN UINT64 BufferSize,
    IN VOID *Buffer,
    IN UINT64 *Index, OPTIONAL
    IN VOID *CryptoIvInput OPTIONAL
  );
```

Parameters

This
Pointer to the EFI_BLOCK_IO_CRYPTO_PROTOCOL instance.

MediaId
The media ID that the read request is for.

LBA
The starting logical block address to read from on the device. Type EFI_LBA is defined in the EFI_BLOCK_IO_PROTOCOL description.

Token
A pointer to the token associated with the transaction. Type EFI_BLOCK_IO_CRYPTO_TOKEN is defined in “Related Definitions” section for ReadExtended() function above.

BufferSize
The size of the Buffer in bytes. This must be a multiple of the intrinsic block size of the device.

Buffer
A pointer to the source buffer for the data.

Index
A pointer to the configuration table index. This is optional.

CryptoIvInput
A pointer to a buffer that contains additional cryptographic parameters as required by the capability referenced by the configuration table index, such as cryptographic initialization vector.

Description
The WriteExtended() function allows the caller to perform a storage device write operation. The function encrypts the requested number of blocks inline if Index is specified and then writes them to the device. All the blocks are encrypted (if encryption requested) and written, or an error is returned.

If there is no media in the device, the function returns EFI_NO_MEDIA. If the MediaId is not the ID for the current media in the device, the function returns EFI_MEDIA_CHANGED.

If EFI_DEVICE_ERROR, EFI_NO_MEDIA, EFI_WRITE_PROTECTED or EFI_MEDIA_CHANGED is returned and non-blocking I/O is being used, the Event associated with this request will not be signaled.
In addition to standard storage transaction parameters (LBA, IO size, and buffer), this command will also specify a configuration table Index and a CryptoIvInput when data has to be encrypted inline by the controller before being written to the storage device. If no Index parameter is specified, no encryption is performed.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The request to encrypt (optionally) and write was queued if Event is not NULL. The data was encrypted (optionally) and written correctly to the device if the Event is NULL.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The device cannot be written to.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no media in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The Mediald is not for the current media.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while attempting to encrypt blocks or to perform the write operation.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>The BufferSize parameter is not a multiple of the intrinsic block size of the device.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL, or the write request contains LBAs that are not valid, or the buffer is not on proper alignment.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>CryptoIvInput is incorrect.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

13.11.8 EFI_BLOCK_IO_CRYPTO_PROTOCOL.FlushBlocks()

Summary

Flushes all modified data to a physical block device.

Prototype

```c
typedef EFI_STATUS
(EFIAPIC *EFI_BLOCK_IO_CRYPTO_FLUSH) (    
    IN EFI_BLOCK_IO_CRYPTO_PROTOCOL *This,
    IN OUT EFI_BLOCK_IO_CRYPTO_TOKEN *Token
    );
```

Parameters

This

Pointer to the EFI_BLOCK_IO_CRYPTO_PROTOCOL instance.

Token

A pointer to the token associated with the transaction. Type EFI_BLOCK_IO_CRYPTO_TOKEN is defined in “Related Definitions” section for ReadExtended() function above.

Description

The FlushBlocks() function flushes all modified data to the physical block device. Any modified data that has to be encrypted must have been already encrypted as a part of WriteExtended() operation - inline crypto operation cannot be a part of flush operation.

All data written to the device prior to the flush must be physically written before returning EFI_SUCCESS from this function. This would include any cached data the driver may have cached, and cached data the device may have cached. A flush may cause a read request following the flush to force a device access.

If EFI_DEVICE_ERROR, EFI_NO_MEDIA, EFI_WRITE_PROTECTED or EFI_MEDIA_CHANGED is returned and non-blocking I/O is being used, the Event associated with this request will not be signaled.
Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The flush request was queued if Event is not NULL. All outstanding data was written correctly to the device if the Event is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while attempting to write data.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The device cannot be written to.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no media in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The MediaId is not for the current media.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

13.12 Erase Block Protocol

13.12.1 EFI_ERASE_BLOCK_PROTOCOL

Summary

This protocol provides the ability for a device to expose erase functionality. This optional protocol is installed on the same handle as the EFI_BLOCK_IO_PROTOCOL or EFI_BLOCK_IO2_PROTOCOL.

GUID

```
#define EFI_ERASE_BLOCK_PROTOCOL_GUID \
{0x95A9A93E, 0xA86E, 0x4926, \
 {0xaa, 0xef, 0x99, 0x18, 0xe7, 0x72, 0x87, 0x87}}
```

Revision Number

```
#define EFI_ERASE_BLOCK_PROTOCOL_REVISION ((2<<16) \(60))
```

Protocol Interface Structure

```
typedef struct _EFI_ERASE_BLOCK_PROTOCOL {
    UINT64 Revision;
    UINT32 EraseLengthGranularity;
    EFI_BLOCK_ERASE EraseBlocks;
} EFI_ERASE_BLOCK_PROTOCOL;
```

Parameters

**Revision**

The revision to which the EFI_ERASE_BLOCK_PROTOCOL adheres. All future revisions must be backwards compatible. If a future version is not backwards compatible, it is not the same GUID.

**EraseLengthGranularity**

Returns the erase length granularity as a number of logical blocks. A value of 1 means the erase granularity is one logical block.

**EraseBlocks**

Erase the requested number of blocks from the device. See the EraseBlocks() function description.
13.12.2 **EFI_ERASE_BLOCK_PROTOCOL.EraseBlocks()**

**Summary**

Erase a specified number of device blocks.

**Prototype**

```c
typedef EFI_STATUS *
(EFIAPI *EFI_BLOCK_ERASE)(
    IN EFI_BLOCK_IO_PROTOCOL *This,
    IN UINT32 MediaId,
    IN EFI_LBA LBA,
    IN OUT EFI_ERASE_BLOCK_TOKEN *Token,
    IN UINTN Size
);
```

**Parameters**

- **This**
  Indicates a pointer to the calling context. Type is defined in the `EFI_ERASE_BLOCK_PROTOCOL` description.

- **MediaId**
  The media ID that the erase request is for.

- **LBA**
  The starting logical block address to be erased. The caller is responsible for erasing only legitimate locations. Type `EFI_LBA` is defined in the `EFI_BLOCK_IO_PROTOCOL` description.

- **Token**
  A pointer to the token associated with the transaction. Type `EFI_ERASE_BLOCK_TOKEN` is defined in “Related Definitions” below.

- **Size**
  The size in bytes to be erased. This must be a multiple of the physical block size of the device.

**Description**

The `EraseBlocks()` function erases the requested number of device blocks. Upon the successful execution of `EraseBlocks()` with an `EFI_SUCCESS` return code, any subsequent reads of the same LBA range would return an initialized/formatted value.

If there is no media in the device, the function returns `EFI_NO_MEDIA`. If the `MediaId` is not the ID for the current media in the device, the function returns `EFI_MEDIA_CHANGED`. The function must return `EFI_NO_MEDIA` or `EFI_MEDIA_CHANGED` even if LBA or Size are invalid so the caller can probe for changes in media state.

It is the intention of the `EraseBlocks()` operation to be at least as performant as writing zeroes to each of the specified LBA locations while ensuring the equivalent security.

On some devices, the granularity of the erasable units is defined by `EraseLengthGranularity` which is the smallest number of consecutive blocks which can be addressed for erase. The size of the `EraseLengthGranularity` is device specific and can be obtained from `EFI_ERASE_BLOCK_MEDIA` structure. The fields of `EFI_ERASE_MEDIA` are not the same as `EFI_BLOCK_IO_MEDIA`, so look at the `EFI_BLOCK_IO_PROTOCOL` and/or `EFI_BLOCK_IO2_PROTOCOL` on the handle for the complete list of fields, if needed. For optimal performance, the starting LBA to be erased shall be `EraseLengthGranularity` aligned and the Size shall be an integer multiple of an `EraseLengthGranularity`.

**Related Definitions**
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS TransactionStatus;
} EFI_ERASE_BLOCK_TOKEN;

Event
If Event is NULL, then blocking I/O is performed. If Event is not NULL and non-blocking I/O is supported, then non-blocking I/O is performed, and Event will be signaled when the erase request is completed.

TransactionStatus
Defines whether the signaled event encountered an error.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The erase request was queued if Event is not NULL. The data was erased correctly to the device if the Event is NULL to the device.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The device cannot be erased due to write protection.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error while attempting to perform the erase operation.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The erase request contains LBAs that are not valid.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no media in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The MediaId is not for the current media.</td>
</tr>
</tbody>
</table>

13.13 ATA Pass Thru Protocol

13.13.1 EFI_ATA_PASS_THRU_PROTOCOL

This section provides a detailed description of the EFI_ATA_PASS_THRU_PROTOCOL.

Summary
Provides services that allow ATA commands to be sent to ATA Devices attached to an ATA controller. Packet-based commands would be sent to ATAPI devices only through the Extended SCSI Pass Thru Protocol. While the ATA_PASS_THRU interface would expose an interface to the underlying ATA devices on an ATA controller, EXT_SCSI_PASS_THRU is responsible for exposing a packet-based command interface for the ATAPI devices on the same ATA controller.

GUID

```c
#define EFI_ATA_PASS_THRU_PROTOCOL_GUID \
{0x1d3de7f0,0x807,0x424f,\ 
 {0xaa,0x69,0x11,0xa5,0x19,0xa4,0x6f}}
```

Protocol Interface Structure

```c
typedef struct _EFI_ATA_PASS_THRU_PROTOCOL {
    EFI_ATA_PASS_THRU_MODE *Mode;
    EFI_ATA_PASS_THRU_PASSTHRU PassThru;
    EFI_ATA_PASS_THRU_GET_NEXT_PORT GetNextPort;
    EFI_ATA_PASS_THRU_GET_NEXT_DEVICE GetNextDevice;
    EFI_ATA_PASS_THRU_BUILD_DEVICE_PATH BuildDevicePath;
    EFI_ATA_PASS_THRU_GET_DEVICE GetDevice;
    EFI_ATA_PASS_THRU_RESET_PORT ResetPort;
} EFI_ATA_PASS_THRU_PROTOCOL;
```
Parameters

Mode
A pointer to the EFI_ATA_PASS_THRU_MODE data for this ATA controller. EFI_ATA_PASS_THRU_MODE is defined in “Related Definitions” below.

PassThru
Sends an ATA command to an ATA device that is connected to the ATA controller. See the PassThru() function description.

GetNextPort
Retrieves the list of legal ports for ATA devices on an ATA controller. See the GetNextPort() function description.

GetNextDevice
Retrieves the list of legal ATA devices on a specific port of an ATA controller. See the GetNextDevice() function description.

BuildDevicePath
Allocates and builds a device path node for an ATA Device on an ATA controller. See the BuildDevicePath() function description.

GetDevice
Translates a device path node to a port and port multiplier port. See the GetDevice() function description.

ResetPort
Resets an ATA port or channel (PATA). This operation resets all the ATA devices connected to the ATA port or channel. See the ResetPort() function description.

ResetDevice
Resets an ATA device that is connected to the ATA controller. See the ResetDevice() function description.

Note: The following data values in the EFI_ATA_PASS_THRU_MODE interface are read-only.

Attributes
Additional information on the attributes of the ATA controller. See “Related Definitions” below for the list of possible attributes.

IoAlign
Supplies the alignment requirement for any buffer used in a data transfer. IoAlign values of 0 and 1 mean that the buffer can be placed anywhere in memory. Otherwise, IoAlign must be a power of 2, and the requirement is that the start address of a buffer must be evenly divisible by IoAlign with no remainder.

Related Definitions

typedef struct {
    UINT32 Attributes;
    UINT32 IoAlign;
} EFI_ATA_PASS_THRU_MODE;

#define EFI_ATA_PASS_THRU_ATTRIBUTES_PHYSICAL 0x0001
#define EFI_ATA_PASS_THRU_ATTRIBUTES_LOGICAL 0x0002
#define EFI_ATA_PASS_THRU_ATTRIBUTES_NONBLOCKIO 0x0004

If this bit is set, then the EFI_ATA_PASS_THRU_PROTOCOL interface is for physical devices on the ATA controller.
 EFI_ATA_PASS_THRU_ATTRIBUTES_LOGICAL
If this bit is set, then the EFI_ATA_PASS_THRU_PROTOCOL interface is for logical devices on the ATA controller.

EFI_ATA_PASS_THRU_ATTRIBUTES_NONBLOCKIO
If this bit is set, then the EFI_ATA_PASS_THRU_PROTOCOL interface supports non-blocking I/O. Every EFI_ATA_PASS_THRU_PROTOCOL must support blocking I/O. The support of non-blocking I/O is optional.

Description
The EFI_ATA_PASS_THRU_PROTOCOL provides information about an ATA controller and the ability to send ATA Command Blocks to any ATA device attached to that ATA controller. To send ATAPI command blocks to ATAPI device attached to that ATA controller, use the EXT_SCSI_PASS_THRU_PROTOCOL interface.

The ATAPI devices support a small set of the non-packet-based ATA commands. The EFI_ATA_PASS_THRU_PROTOCOL may be used to send such ATA commands to ATAPI devices.

The printable name for the controller can be provided through the EFI_COMPONENT_NAME2_PROTOCOL for multiple languages.

The Attributes field of the Mode member of the EFI_ATA_PASS_THRU_PROTOCOL interface tells if the interface is for physical ATA devices or logical ATA devices. Drivers for non-RAID ATA controllers will set both the EFI_ATA_PASS_THRU_ATTRIBUTES_PHYSICAL, and the EFI_ATA_PASS_THRU_ATTRIBUTES_LOGICAL bits.

Drivers for RAID controllers that allow access to the physical devices and logical devices will produce two EFI_ATA_PASS_THRU_PROTOCOL interfaces: one with the just the EFI_ATA_PASS_THRU_ATTRIBUTES_PHYSICAL bit set and another with just the EFI_ATA_PASS_THRU_ATTRIBUTES_LOGICAL bit set. One interface can be used to access the physical devices attached to the RAID controller, and the other can be used to access the logical devices attached to the RAID controller for its current configuration.

Drivers for RAID controllers that do not allow access to the physical devices will produce one EFI_ATA_PASS_THROUGH_PROTOCOL interface with just the EFI_ATA_PASS_THRU_LOGICAL bit set. The interface for logical devices can also be used by a file system driver to mount the RAID volumes. An EFI_ATA_PASS_THRU_PROTOCOL with neither EFI_ATA_PASS_THRU_ATTRIBUTES_LOGICAL nor EFI_ATA_PASS_THRU_ATTRIBUTES_PHYSICAL set is an illegal configuration.

The Attributes field also contains the EFI_ATA_PASS_THRU_ATTRIBUTES_NONBLOCKIO bit. All EFI_ATA_PASS_THRU_PROTOCOL interfaces must support blocking I/O. If this bit is set, then the interface supports both blocking I/O and non-blocking I/O.

Each EFI_ATA_PASS_THRU_PROTOCOL instance must have an associated device path. Typically this will have an ACPI device path node and a PCI device path node, although variation will exist.

Additional information about the ATA controller can be obtained from protocols attached to the same handle as the EFI_ATA_PASS_THRU_PROTOCOL, or one of its parent handles. This would include the device I/O abstraction used to access the internal registers and functions of the ATA controller.

This protocol may also be used for PATA devices (or devices in a PATA-compatible mode). PATA devices are mapped to ports and port multiplier ports using the following table:

<table>
<thead>
<tr>
<th>PATA Device Connection</th>
<th>Emulated Port Number</th>
<th>Emulated Port Multiplier Port Number</th>
</tr>
</thead>
<tbody>
<tr>
<td>Primary Master</td>
<td>0</td>
<td>0</td>
</tr>
<tr>
<td>Primary Slave</td>
<td>0</td>
<td>1</td>
</tr>
<tr>
<td>Secondary Master</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>Secondary Slave</td>
<td>1</td>
<td>1</td>
</tr>
</tbody>
</table>
13.13.2 EFI_ATA_PASS_THRU_PROTOCOL.PassThru()

Summary
Sends an ATA command to an ATA device that is attached to the ATA controller. This function supports both blocking I/O and non-blocking I/O. The blocking I/O functionality is required, and the non-blocking I/O functionality is optional.

Prototype
```c
typedef EFI_STATUS
(EFIAPI *EFI_ATA_PASS_THRU_PASSTHRU) (
    IN EFI_ATA_PASS_THRU_PROTOCOL *This,
    IN UINT16 Port,
    IN UINT16 PortMultiplierPort,
    IN OUT EFI_ATA_PASS_THRU_COMMAND_PACKET *Packet,
    IN EFI_EVENT Event OPTIONAL
);
```

Parameters

This
A pointer to the `EFI_ATA_PASS_THRU_PROTOCOL` instance.

Port
The port number of the ATA device to send the command.

PortMultiplierPort
The port multiplier port number of the ATA device to send the command. If there is no port multiplier, then specify `0xFFFF`.

Packet
A pointer to the ATA command to send to the ATA device specified by `Port` and `PortMultiplierPort`. See “Related Definitions” below for a description of `EFI_ATA_PASS_THRU_COMMAND_PACKET`.

Event
If non-blocking I/O is not supported then `Event` is ignored, and blocking I/O is performed. If `Event` is `NULL`, then blocking I/O is performed. If `Event` is not `NULL` and non-blocking I/O is supported, then non-blocking I/O is performed, and `Event` will be signaled when the ATA command completes.

Related Definitions
```c
typedef struct {
    EFI_ATA_STATUS_BLOCK *Asb;
    EFI_ATA_COMMAND_BLOCK *Acb;
    UINT64 Timeout;
    VOID *InDataBuffer;
    VOID *OutDataBuffer;
    UINT32 InTransferLength;
    UINT32 OutTransferLength;
    EFI_ATA_PASS_THRU_CMD_PROTOCOL Protocol;
    EFI_ATA_PASS_THRU_LENGTH Length;
} EFI_ATA_PASS_THRU_COMMAND_PACKET;
```

Timeout
The timeout, in 100 ns units, to use for the execution of this ATA command. A `Timeout` value of 0 means that this function will wait indefinitely for the ATA command to execute. If `Timeout` is greater than zero, then this function will return `EFI_TIMEOUT` if the time required to execute the ATA command is greater than `Timeout`.
InDataBuffer
A pointer to the data buffer to transfer between the ATA controller and the ATA device for read and bidirectional commands. For all write and non data commands where InTransferLength is 0 this field is optional and may be NULL. If this field is not NULL, then it must be aligned on the boundary specified by the IoAlign field in the EFI_ATA_PASS_THRU_MODE structure.

OutDataBuffer
A pointer to the data buffer to transfer between the ATA controller and the ATA device for write or bidirectional commands. For all read and non data commands where OutTransferLength is 0 this field is optional and may be NULL. If this field is not NULL, then it must be aligned on the boundary specified by the IoAlign field in the EFI_ATA_PASS_THRU_MODE structure.

InTransferLength
On input, the size, in bytes, of InDataBuffer. On output, the number of bytes transferred between the ATA controller and the ATA device. If InTransferLength is larger than the ATA controller can handle, no data will be transferred, InTransferLength will be updated to contain the number of bytes that the ATA controller is able to transfer, and EFI_BAD_BUFFER_SIZE will be returned.

OutTransferLength
On Input, the size, in bytes of OutDataBuffer. On Output, the Number of bytes transferred between ATA Controller and the ATA device. If OutTransferLength is larger than the ATA controller can handle, no data will be transferred, OutTransferLength will be updated to contain the number of bytes that the ATA controller is able to transfer, and EFI_BAD_BUFFER_SIZE will be returned.

Asb
A pointer to the sense data that was generated by the execution of the ATA command. It must be aligned to the boundary specified in the IoAlign field in the EFI_ATA_PASS_THRU_MODE structure.

Acb
A pointer to buffer that contains the Command Data Block to send to the ATA device specified by Port and PortMultiplierPort.

Protocol
Specifies the protocol used when the ATA device executes the command. Type EFI_ATA_PASS_THRU_CMD_PROTOCOL is defined below.

Length
Specifies the way in which the ATA command length is encoded. Type EFI_ATA_PASS_THRU_LENGTH is defined below.

typedef struct _EFI_ATA_COMMAND_BLOCK {
  UINT8 Reserved1[2];
  UINT8 AtaCommand;
  UINT8 AtaFeatures;
  UINT8 AtaSectorNumber;
  UINT8 AtaCylinderLow;
  UINT8 AtaCylinderHigh;
  UINT8 AtaDeviceHead;
  UINT8 AtaSectorNumberExp;
  UINT8 AtaCylinderLowExp;
  UINT8 AtaCylinderHighExp;
  UINT8 AtaFeaturesExp;
  UINT8 AtaSectorCount;
  UINT8 AtaSectorCountExp;
  UINT8 Reserved2 [6];
} EFI_ATA_COMMAND_BLOCK;

(continues on next page)
typedef struct _EFI_ATA_STATUS_BLOCK {
    UINT8 Reserved1[2];
    UINT8 AtaStatus;
    UINT8 AtaError;
    UINT8 AtaSectorNumber;
    UINT8 AtaCylinderLow;
    UINT8 AtaCylinderHigh;
    UINT8 AtaDeviceHead;
    UINT8 AtaSectorNumberExp;
    UINT8 AtaCylinderLowExp;
    UINT8 AtaCylinderHighExp;
    UINT8 Reserved2;
    UINT8 AtaSectorCount;
    UINT8 AtaSectorCountExp;
    UINT8 Reserved3[6];
} EFI_ATA_STATUS_BLOCK;

typedef UINT8 EFI_ATA_PASS_THRU_CMD_PROTOCOL;

#define EFI_ATA_PASS_THRU_PROTOCOL_ATA_HARDWARE_RESET 0x00
#define EFI_ATA_PASS_THRU_PROTOCOL_ATA_SOFTWARE_RESET 0x01
#define EFI_ATA_PASS_THRU_PROTOCOL_ATA_NON_DATA 0x02
#define EFI_ATA_PASS_THRU_PROTOCOLPIO_DATA_IN 0x04
#define EFI_ATA_PASS_THRU_PROTOCOLPIO_DATA_OUT 0x05
#define EFI_ATA_PASS_THRU_PROTOCOL_DMA 0x06
#define EFI_ATA_PASS_THRU_PROTOCOL_DMA_QUEUED 0x07
#define EFI_ATA_PASS_THRU_PROTOCOL_DEVICE_DIAGNOSTIC 0x08
#define EFI_ATA_PASS_THRU_PROTOCOLDEVICE_RESET 0x0A
#define EFI_ATA_PASS_THRU_PROTOCOLUDMA_DATA_IN 0x0B
#define EFI_ATA_PASS_THRU_PROTOCOLUDMA_DATA_OUT 0x0C
#define EFI_ATA_PASS_THRU_PROTOCOL_FPDMA 0x0D
#define EFI_ATA_PASS_THRU_PROTOCOL_RETURN_RESPONSE 0xFF

typedef UINT8 EFI_ATA_PASS_THRU_LENGTH;

#define EFI_ATA_PASS_THRU_LENGTH_BYTES 0x80
#define EFI_ATA_PASS_THRU_LENGTH_MASK 0x70
#define EFI_ATA_PASS_THRU_LENGTH_NO_DATA_TRANSFER 0x00
#define EFI_ATA_PASS_THRU_LENGTH_FEATURES 0x10
#define EFI_ATA_PASS_THRU_LENGTH_SECTOR_COUNT 0x20
#define EFI_ATA_PASS_THRU_LENGTH_TPSIU 0x30

#define EFI_ATA_PASS_THRU_LENGTH_COUNT 0x0F

Description

The PassThru() function sends the ATA command specified by Packet to the ATA device specified by Port and PortMultiplierPort. If the driver supports non-blocking I/O and Event is not NULL, then the driver will return immediately
after the command is sent to the selected device, and will later signal Event when the command has completed.

If the driver supports non-blocking I/O and Event is NULL, then the driver will send the command to the selected device and block until it is complete. If the driver does not support non-blocking I/O, then the Event parameter is ignored, and the driver will send the command to the selected device and block until it is complete.

If Packet is successfully sent to the ATA device, then EFI_SUCCESS is returned. If Packet cannot be sent because there are too many packets already queued up, then EFI_NOT_READY is returned. The caller may retry Packet at a later time. If a device error occurs while sending the Packet, then EFI_DEVICE_ERROR is returned. If a timeout occurs during the execution of Packet, then EFI_TIMEOUT is returned.

If Port or PortMultiplierPort are not in a valid range for the ATA controller, then EFI_INVALID_PARAMETER is returned. If InDataBuffer, OutDataBuffer or Asb do not meet the alignment requirement specified by the IoAlign field of the EFI_ATA_PASS_THRU_MODE structure, then EFI_INVALID_PARAMETER is returned. If any of the other fields of Packet are invalid, then EFI_INVALID_PARAMETER is returned.

If the data buffer described by InDataBuffer and InTransferLength is too big to be transferred in a single command, then no data is transferred and EFI_BAD_BUFFER_SIZE is returned. The number of bytes that can be transferred in a single command are returned in InTransferLength. If the data buffer described by OutDataBuffer and OutTransferLength is too big to be transferred in a single command, then no data is transferred and EFI_BAD_BUFFER_SIZE is returned. The number of bytes that can be transferred in a single command are returned in OutTransferLength.

If the command described in Packet is not supported by the host adapter, then EFI_UNSUPPORTED is returned.

If EFI_SUCCESS, EFI_BAD_BUFFER_SIZE, EFI_DEVICE_ERROR, or EFI_TIMEOUT is returned, then the caller must examine Asb.

If non-blocking I/O is being used, then the status fields in Packet will not be valid until the Event associated with Packet is signaled.

If EFI_NOT_READY, EFI_INVALID_PARAMETER or EFI_UNSUPPORTED is returned, then Packet was never sent, so the status fields in Packet are not valid. If non-blocking I/O is being used, the Event associated with Packet will not be signaled.

This function will determine if data transfer is necessary based on the Acb->Protocol and Acb->Length fields. The Acb->AtaCommand field is ignored except to copy it into the ATA Command register. The following table describes special programming considerations based on the protocol specified by Acb->Protocol.

<table>
<thead>
<tr>
<th>Protocol Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_ATA_PASS_THRU_PROTOCOL_ATA_HARDWARE_RESET</td>
<td>For PATA devices, then RST- is asserted. For SATA devices, then COMRESET will be issued.</td>
</tr>
<tr>
<td>EFI_ATA_PASS_THRU_PROTOCOL_ATA_SOFTWARE_RESET</td>
<td>A software reset will be issued to the ATA device.</td>
</tr>
<tr>
<td>EFI_ATA_PASS_THRU_PROTOCOLPIO_DATA_IN</td>
<td>The command is sent to the ATA device. If the value is inappropriate for the command specified by Acb-&gt;AtaCommand, the results are undefined.</td>
</tr>
<tr>
<td>EFI_ATA_PASS_THRU_PROTOCOL_FPDMA</td>
<td></td>
</tr>
<tr>
<td>EFI_ATA_PASS_THRU_RETURN_RESPONSE</td>
<td>This command will only return the contents of the ATA status block.</td>
</tr>
</tbody>
</table>

The ATA host and the ATA device should already be configured for the PIO, DMA, and UDMA transfer rates that are supported by the ATA controller and the ATA device. The results of changing the device’s timings using this function are undefined.
If `Packet->Length` is not set to `EFI_ATA_PASS_THRU_LENGTH_NO_DATA_TRANSFER`, then if `EFI_ATA_PASS_THRU_LENGTH_BYTES` is set in `Packet->Length`, then `Packet->InTransferLength` and `Packet->OutTransferLength` are interpreted as bytes.

If `Packet->Length` is not set to `EFI_ATA_PASS_THRU_LENGTH_NO_DATA_TRANSFER`, then if `EFI_ATA_PASS_THRU_LENGTH_BYTES` is clear in `Packet->Length`, then `Packet->InTransferLength` and `Packet->OutTransferLength` are interpreted as blocks.

If `Packet->Length` is set to `EFI_ATA_PASS_THRU_LENGTH_SECTOR_COUNT`, then the transfer length will be programmed into `Acb->AtaSectorCount`.

If `Packet->Length` is set to `EFI_ATA_PASS_THRU_LENGTH_TPSIU`, then the transfer length will be programmed into the TPSIU.

- For PIO data transfers, the number of sectors to transfer is 2 \((Packet->Length \& EFI_ATA_PASS_THRU_LENGTH_COUNT)\).

For all commands, the contents of the ATA status block will be returned in `Asb`.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The ATA command was sent by the host. For bi-directional commands, <code>InTransferLength</code> bytes were transferred from <code>InDataBuffer</code>. For write and bi-directional commands, <code>OutTransferLength</code> bytes were transferred by <code>OutDataBuffer</code>. See <code>Asb</code> for additional status information.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>The ATA command was not executed. The number of bytes that could be transferred is returned in <code>InTransferLength</code>. For write and bi-directional commands, <code>OutTransferLength</code> bytes were transferred by <code>OutDataBuffer</code>. See <code>Asb</code> for additional status information.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The ATA command could not be sent because there are too many ATA commands already queued. The caller may retry again later.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to send the ATA command. See <code>Asb</code> for additional status information.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>Port</code>, <code>PortMultiplierPort</code>, or the contents of <code>Acb</code> are invalid. The ATA command was not sent, so no additional status information is available.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The command described by the ATA command is not supported by the host adapter. The ATA command was not sent, so no additional status information is available.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>A timeout occurred while waiting for the ATA command to execute. See <code>Asb</code> for additional status information.</td>
</tr>
</tbody>
</table>

### 13.13.3 EFI_ATA_PASS_THRU_PROTOCOL.GetNextPort()

**Summary**

Used to retrieve the list of legal port numbers for ATA devices on an ATA controller. These can either be the list of ports where ATA devices are actually present or the list of legal port numbers for the ATA controller. Regardless, the caller of this function must probe the port number returned to see if an ATA device is actually present at that location on the ATA controller.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPIC *EFI_ATA_PASS_THRU_GET_NEXT_PORT) (IN EFI_ATA_PASS_THRU_PROTOCOL *This,
```

(continues on next page)
13.13.4 EFI_ATA_PASS_THRU_PROTOCOL.GetNextDevice()

Summary

Used to retrieve the list of legal port multiplier port numbers for ATA devices on a port of an ATA controller. These can either be the list of port multiplier ports where ATA devices are actually present on port or the list of legal port multiplier ports on that port. Regardless, the caller of this function must probe the port number and port multiplier port number returned to see if an ATA device is actually present.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_ATA_PASS_THRU_GET_NEXT_DEVICE) (  
    IN EFI_ATA_PASS_THRU_PROTOCOL *This,  
    IN UINT16 Port,  
    IN OUT UINT16 *PortMultiplierPort  
);  
```

Parameters

This

A pointer to the EFI_ATA_PASS_THRU_PROTOCOL instance.
Port
The port number present on the ATA controller.

PortMultiplierPort
On input, a pointer to the port multiplier port number of an ATA device present on the ATA controller. If on input a PortMultiplierPort of 0xFFFF is specified, then the port multiplier port number of the first ATA device is returned. On output, a pointer to the port multiplier port number of the next ATA device present on an ATA controller.

Description
The GetNextDevice() function retrieves the port multiplier port number of an ATA device present on a port of an ATA controller.

If PortMultiplierPort points to a port multiplier port number value that was returned on a previous call to GetNextDevice(), then the port multiplier port number of the next ATA device on the port of the ATA controller is returned in PortMultiplierPort, and EFI_SUCCESS is returned.

If PortMultiplierPort points to 0xFFFF, then the port multiplier port number of the first ATA device on port of the ATA controller is returned in PortMultiplierPort and EFI_SUCCESS is returned.

If PortMultiplierPort is not 0xFFFF and the value pointed to by PortMultiplierPort was not returned on a previous call to GetNextDevice(), then EFI_INVALID_PARAMETER is returned.

If PortMultiplierPort is the port multiplier port number of the last ATA device on the port of the ATA controller, then EFI_NOT_FOUND is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The port multiplier port number of the next ATA device on the port of the ATA controller was returned in PortMultiplierPort.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>There are no more ATA devices on this port of the ATA controller.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PortMultiplierPort is not 0xFFFF, and PortMultiplierPort was not returned on a previous call to GetNextDevice().</td>
</tr>
</tbody>
</table>

13.13.5 EFI_ATA_PASS_THRU_PROTOCOL.BuildDevicePath()

Summary
Used to allocate and build a device path node for an ATA device on an ATA controller.

Prototype

typedef
EFI_STATUS
(EIFIAPI  *EFI_ATA_PASS_THRU_BUILD_DEVICE_PATH) (  
    IN EFI_ATA_PASS_THRU_PROTOCOL *This,
    IN UINT16 Port,
    IN UINT16 PortMultiplierPort,
    OUT EFI_DEVICE_PATH_PROTOCOL **DevicePath  
);  

Parameters
This
A pointer to the EFI_ATA_PASS_THRU_PROTOCOL instance.
Port
Port specifies the port number of the ATA device for which a device path node is to be allocated and built.

PortMultiplierPort
The port multiplier port number of the ATA device for which a device path node is to be allocated and built. If there is no port multiplier, then specify 0xFFFF.

DevicePath
A pointer to a single device path node that describes the ATA device specified by Port and PortMultiplierPort. This function is responsible for allocating the buffer DevicePath with the boot service AllocatePool(). It is the caller’s responsibility to free DevicePath when the caller is finished with DevicePath.

Description
The BuildDevicePath() function allocates and builds a single device node for the ATA device specified by Port and PortMultiplierPort. If the ATA device specified by Port and PortMultiplierPort is not present on the ATA controller, then EFI_NOT_FOUND is returned. If DevicePath is NULL, then EFI_INVALID_PARAMETER is returned. If there are not enough resources to allocate the device path node, then EFI_OUT_OF_RESOURCES is returned.

Otherwise, DevicePath is allocated with the boot service AllocatePool(), the contents of DevicePath are initialized to describe the ATA device specified by Port and PortMultiplierPort, and EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device path node that describes the ATA device specified by Port and PortMultiplierPort was allocated and returned in DevicePath.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The ATA device specified by Port and PortMultiplierPort does not exist on the ATA controller.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DevicePath is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There are not enough resources to allocate DevicePath.</td>
</tr>
</tbody>
</table>

13.13.6 EFI_ATA_PASS_THRU_PROTOCOL.GetDevice()

Summary
Used to translate a device path node to a port number and port multiplier port number.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_ATA_PASS_THRU_GET_DEVICE) (   
IN EFI_ATA_PASS_THRU_PROTOCOL *This,   
IN EFI_DEVICE_PATH_PROTOCOL *DevicePath,   
OUT UINT16 *Port,   
OUT UINT16 *PortMultiplierPort   
);

Parameters

This
A pointer to the EFI_ATA_PASS_THRU_PROTOCOL instance.

DevicePath
A pointer to the device path node that describes an ATA device on the ATA controller.
Port
On return, points to the port number of an ATA device on the ATA controller.

PortMultiplierPort
On return, points to the port multiplier port number of an ATA device on the ATA controller.

Description
The GetDevice() function determines the port and port multiplier port number associated with the ATA device described by DevicePath. If DevicePath is a device path node type that the ATA Pass Thru driver supports, then the ATA Pass Thru driver will attempt to translate the contents DevicePath into a port number and port multiplier port number.

If this translation is successful, then that port number and port multiplier port number are returned in Port and PortMultiplierPort, and EFI_SUCCESS is returned.

If DevicePath, Port, or PortMultiplierPort are NULL, then EFI_INVALID_PARAMETER is returned.

If DevicePath is not a device path node type that the ATA Pass Thru driver supports, then EFI_UNSUPPORTED is returned.

If DevicePath is a device path node type that the ATA Pass Thru driver supports, but there is not a valid translation from DevicePath to a port number and port multiplier port number, then EFI_NOT_FOUND is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>DevicePath was successfully translated to a port number and port multiplier port number, and they were returned in Port and PortMultiplierPort.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DevicePath is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Port is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PortMultiplierPort is NULL</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This driver does not support the device path node type in DevicePath.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>A valid translation from DevicePath to a port number and port multiplier port number does not exist.</td>
</tr>
</tbody>
</table>

13.13.7 EFI_ATA_PASS_THRU_PROTOCOL.ResetPort()

Summary
Resets a specific port on the ATA controller. This operation also resets all the ATA devices connected to the port.

Prototype

typedef
EFI_STATUS
(EIFIAP1 *EFI_ATA_PASS_THRU_RESET_PORT) (
    IN EFI_ATA_PASS_THRU_PROTOCOL *This,
    IN UINT16 *Port
);
The `ResetChannel()` function resets an a specific port on an ATA controller. This operation resets all the ATA devices connected to that port. If this ATA controller does not support a reset port operation, then `EFI_UNSUPPORTED` is returned.

If a device error occurs while executing that port reset operation, then `EFI_DEVICE_ERROR` is returned.

If a timeout occurs during the execution of the port reset operation, then `EFI_TIMEOUT` is returned.

If the port reset operation is completed, then `EFI_SUCCESS` is returned.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The ATA controller port was reset.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The ATA controller does not support a port reset operation.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to reset the ATA port.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>A timeout occurred while attempting to reset the ATA port.</td>
</tr>
</tbody>
</table>

### 13.13.8 EFI_ATA_PASS_THRU_PROTOCOL.ResetDevice()

#### Summary
Resets an ATA device that is connected to an ATA controller.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_ATA_PASS_THRU_RESET_DEVICE) (
    IN EFI_ATA_PASS_THRU_PROTOCOL *This,
    IN UINT16 Port,
    IN UINT16 PortMultiplierPort
);
```

#### Parameters

**This**
A pointer to the `EFI_ATA_PASS_THRU_PROTOCOL` instance.

**Port**
Port represents the port number of the ATA device to be reset.

**PortMultiplierPort**
The port multiplier port number of the ATA device to reset. If there is no port multiplier, then specify 0xFFFF.

#### Description
The `ResetDevice()` function resets the ATA device specified by `Port` and `PortMultiplierPort`. If this ATA controller does not support a device reset operation, then `EFI_UNSUPPORTED` is returned.

If `Port` or `PortMultiplierPort` are not in a valid range for this ATA controller, then `EFI_INVALID_PARAMETER` is returned.

If a device error occurs while executing that device reset operation, then `EFI_DEVICE_ERROR` is returned.

If a timeout occurs during the execution of the device reset operation, then `EFI_TIMEOUT` is returned.

If the device reset operation is completed, then `EFI_SUCCESS` is returned.

### Status Codes Returned
13.14 Storage Security Command Protocol

This section defines the storage security command protocol. This protocol is used to abstract mass storage devices to allow code running in the EFI boot services environment to send security protocol commands to mass storage devices without specific knowledge of the type of device or controller that manages the device. Functions are defined to send or retrieve security protocol defined data to and from mass storage devices. This protocol shall be supported on all physical and logical storage devices supporting the EFI_BLOCK_IO_PROTOCOL or EFI_BLOCK_IO2_PROTOCOL in the EFI boot services environment and one of the following command sets (or their alternative) at the bus level:

- TRUSTED SEND/RECEIVE commands of the ATA8-ACS command set or its successor
- SECURITY PROTOCOL IN/OUT commands of the SPC-4 command set or its successor.

If the mass storage device is part of a RAID set, the specific physical device may not support the block IO protocols directly, but they are supported by the logical device defining the RAID set. In this case the MediaId parameter may not be available and its value is undefined for this interface.

13.14.1 EFI_STORAGE_SECURITY_COMMAND_PROTOCOL

Summary
This protocol provides ability to send security protocol commands to mass storage devices.

GUID

```c
#define EFI_STORAGE_SECURITY_COMMAND_PROTOCOL_GUID
{0xc88b0b6d, 0x0dfc, 0x49a7,
  {0x9c, 0xb4, 0x49, 0x7, 0x4b, 0x3a, 0x78}}
```

Protocol Interface Structure

```c
typedef struct _EFI_STORAGE_SECURITY_COMMAND_PROTOCOL {
    EFI_STORAGE_SECURITY_RECEIVE_DATA   ReceiveData;
    EFI_STORAGE_SECURITY_SEND_DATA     SendData;
} EFI_STORAGE_SECURITY_COMMAND_PROTOCOL;
```

Parameters

**ReceiveData**
Issues a security protocol command to the requested device that receives data and/or the result of one or more commands sent by SendData. See the ReceiveData() function description.

**SendData**
Issues a security protocol command to the requested device. See the SendData() function description.
Description

The EFI_STORAGE_SECURITY_COMMAND_PROTOCOL is used to send security protocol commands to a mass storage device. Two types of security protocol commands are supported. SendData sends a command with data to a device. ReceiveData sends a command that receives data and/or the result of one or more commands sent by SendData.

The security protocol command formats supported shall be based on the definition of the SECURITY_PROTOCOL_IN and SECURITY_PROTOCOL_OUT commands defined in SPC-4. If the device uses the SCSI command set, no translation is needed in the firmware and the firmware can package the parameters into a SECURITY_PROTOCOL_IN or SECURITY_PROTOCOL_OUT command and send the command to the device. If the device uses a non-SCSI command set, the firmware shall map the command and data payload to the corresponding command and payload format defined in the non-SCSI command set (for example, TRUSTED RECEIVE and TRUSTED SEND in ATA8-ACS).

The firmware shall automatically add an EFI_STORAGE_SECURITY_COMMAND_PROTOCOL for any storage devices detected during system boot that support SPC-4, ATA8-ACS or their successors.

13.14.2 EFI_STORAGE_SECURITY_COMMAND_PROTOCOL.ReceiveData()

Summary

Send a security protocol command to a device that receives data and/or the result of one or more commands sent by SendData.

Prototype

typedef

EFI_STATUS

(EIFIAPI *EFI_STORAGE_SECURITY_RECEIVE_DATA) (  
    IN EFI_STORAGE_SECURITY_COMMAND_PROTOCOL

        *This,
    IN UINT32           MediaId,
    IN UINT64           Timeout,
    IN UINT8            SecurityProtocol,
    IN UINT16           SecurityProtocolSpecificData,
    IN UINTN            PayloadBufferSize,
    OUT VOID            *PayloadBuffer,
    OUT UINTN           *PayloadTransferSize

);

Parameters

This

Indicates a pointer to the calling context. Type EFI_STORAGE_SECURITY_COMMAND_PROTOCOL is defined in the EFI_STORAGE_SECURITY_COMMAND_PROTOCOL description.

MediaId

ID of the medium to receive data from. If there is no block IO protocol supported by the physical device, the value of MediaId is undefined.

Timeout

The timeout, in 100ns units, to use for the execution of the security protocol command. A Timeout value of 0 means that this function will wait indefinitely for the security protocol command to execute. If Timeout is greater than zero, then this function will return EFI_TIMEOUT if the time required to execute the receive data command is greater than Timeout.

SecurityProtocolId

The value of the “Security Protocol” parameter of the security protocol command to be sent.
SecurityProtocolSpecificData
The value of the “Security Protocol Specific” parameter of the security protocol command to be sent. This value is in big-endian format.

PayloadBufferSize
Size in bytes of the payload data buffer.

PayloadBuffer
A pointer to a destination buffer to store the security protocol command specific payload data for the security protocol command. The caller is responsible for having either implicit or explicit ownership of the buffer.

PayloadTransferSize
A pointer to a buffer to store the size in bytes of the data written to the payload data buffer.

Description
The ReceiveData function sends a security protocol command to the given MediaId. The security protocol command sent is defined by SecurityProtocolId and contains the security protocol specific data SecurityProtocolSpecificData. The function returns the data from the security protocol command in PayloadBuffer.

For devices supporting the SCSI command set, the security protocol command is sent using the SECURITY PROTOCOL IN command defined in SPC-4.

For devices supporting the ATA command set, the security protocol command is sent using one of the TRUSTED RECEIVE commands defined in ATA8-ACS if PayloadBufferSize is non-zero. If the PayloadBufferSize is zero, the security protocol command is sent using the Trusted Non-Data command defined in ATA8-ACS.

If PayloadBufferSize is too small to store the available data from the security protocol command, the function shall copy PayloadBufferSize bytes into the PayloadBuffer and return EFI_WARN_BUFFER_TOO_SMALL.

If PayloadBuffer or PayloadTransferSize is NULL and PayloadBufferSize is non-zero, the function shall return EFI_INVALID_PARAMETER.

If the given MediaId does not support security protocol commands, the function shall return EFI_UNSUPPORTED.

If there is no media in the device, the function returns EFI_NO_MEDIA. If the MediaId is not the ID for the current media in the device, the function returns EFI_MEDIA_CHANGED.

If the security protocol fails to complete within the Timeout period, the function shall return EFI_TIMEOUT.

If the security protocol command completes without an error, the function shall return EFI_SUCCESS. If the security protocol command completes with an error, the function shall return EFI_DEVICE_ERROR.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The security protocol command completed successfully.</td>
</tr>
<tr>
<td>EFI_WARN_BUFFER_TOO_SMALL</td>
<td>The PayloadBufferSize was too small to store the available data from the device. The PayloadBuffer contains the truncated data.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The given MediaId does not support security protocol commands.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The security protocol command completed with an error.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no media in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The MediaId is not for the current media.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The PayloadBuffer or PayloadTransferSize is NULL and PayloadBufferSize is non-zero.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>A timeout occurred while waiting for the security protocol command to execute.</td>
</tr>
</tbody>
</table>
13.14.3 EFI_STORAGE_SECURITY_COMMAND_PROTOCOL.SendData()

Summary
Send a security protocol command to a device.

Prototype

```c
typedef
  EFI_STATUS
  (EFIAPI *EFI_STORAGE_SECURITY_SEND_DATA) (
    IN EFI_STORAGE_SECURITY_COMMAND_PROTOCOL *This,
    IN UINT32 MediaId,
    IN UINT64 Timeout,
    IN UINT8 SecurityProtocolId,
    IN UINT16 SecurityProtocolSpecificData,
    IN UINTN PayloadBufferSize,
    IN VOID *PayloadBuffer
  );
```

Parameters

**This**
Indicates a pointer to the calling context. Type `EFI_STORAGE_SECURITY_COMMAND_PROTOCOL` is defined in the `EFI_STORAGE_SECURITY_COMMAND_PROTOCOL` description.

**MediaId**
ID of the medium to send data to. If there is no block IO protocol supported by the physical device, the value of `MediaId` is undefined.

**Timeout**
The timeout, in 100ns units, to use for the execution of the security protocol command. A `Timeout` value of 0 means that this function will wait indefinitely for the security protocol command to execute. If `Timeout` is greater than zero, then this function will return `EFI_TIMEOUT` if the time required to execute the receive data command is greater than `Timeout`.

**SecurityProtocolId**
The value of the “Security Protocol” parameter of the security protocol command to be sent.

**SecurityProtocolSpecificData**
The value of the “Security Protocol Specific” parameter of the security protocol command to be sent.

**PayloadBufferSize**
Size in bytes of the payload data buffer.

**PayloadBuffer**
A pointer to a buffer containing the security protocol command specific payload data for the security protocol command.

Description
The `SendData` function sends a security protocol command containing the payload `PayloadBuffer` to the given `MediaId`. The security protocol command sent is defined by `SecurityProtocolId` and contains the security protocol specific data `SecurityProtocolSpecificData`. If the underlying protocol command requires a specific padding for the command payload, the SendData function shall add padding bytes to the command payload to satisfy the padding requirements.
For devices supporting the SCSI command set, the security protocol command is sent using the SECURITY PROTOCOL OUT command defined in SPC-4.

For devices supporting the ATA command set, the security protocol command is sent using one of the TRUSTED SEND commands defined in ATA8-ACS if PayloadBufferSize is non-zero. If the PayloadBufferSize is zero, the security protocol command is sent using the Trusted Non-Data command defined in ATA8-ACS.

If PayloadBuffer is NULL and PayloadBufferSize is non-zero, the function shall return EFI_INVALID_PARAMETER.

If there is no media in the device, the function returns EFI_NO_MEDIA. If the MediaId is not the ID for the current media in the device, the function returns EFI_MEDIA_CHANGED.

If the security protocol fails to complete within the Timeout period, the function shall return EFI_TIMEOUT.

If the security protocol command completes without an error, the function shall return EFI_SUCCESS. If the security protocol command completes with an error, the function shall return EFI_DEVICE_ERROR.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The security protocol command completed successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The given MediaId does not support security protocol commands.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The security protocol command completed with an error.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no media in the device.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>The MediaId is not for the current media.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The PayloadBuffer is NULL and PayloadBufferSize is non-zero.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>A timeout occurred while waiting for the security protocol command to execute.</td>
</tr>
</tbody>
</table>

### 13.15 NVM Express Pass Through Protocol

#### 13.15.1 EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL

This section provides a detailed description of the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.

**Summary**

This protocol provides services that allow NVM Express commands to be sent to an NVM Express controller or to a specific namespace in a NVM Express controller. This protocol interface is optimized for storage.

**GUID**

```c
#define EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL_GUID
{ 0x52c78312, 0x8edc, 0x4233,
{ 0x98, 0xf2, 0x1a, 0x1a, 0xa5, 0xe3, 0x88, 0xa5 } );
```

**Protocol Interface Structure**

```c
ttypedef struct __EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL {
EFI_NVM_EXPRESS_PASS_THRU_MODE *Mode;
EFI_NVM_EXPRESS_PASS_THRU_PASSTHRU PassThru;
EFI_NVM_EXPRESS_PASS_THRU_GET_NEXT_NAMESPACE GetNextNamespace;
EFI_NVM_EXPRESS_PASS_THRU_BUILD_DEVICE_PATH BuildDevicePath;
EFI_NVM_EXPRESS_PASS_THRU_GET_NAMESPACE GetNamespace;
} EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL;
```
Parameters

Mode
A pointer to the EFI_NVM_EXPRESS_PASS_THRU_MODE data for this NVM Express controller. EFI_NVM_EXPRESS_PASS_THRU_MODE is defined in “Related Definitions” below.

PassThru
Sends an NVM Express Command Packet to an NVM Express controller. See the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.PassThru() function description.

GetNextNamespace
Retrieves the next namespace ID for this NVM Express controller. See the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.GetNextNamespace() function description.*

BuildDevicePath
Allocates and builds a device path node for a namespace on an NVM Express controller. See the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.BuildDevicePath() function description.*

GetNamespace
Translates a device path node to a namespace ID. See the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.GetNamespace() function description.

The following data values in the EFI_NVM_EXPRESS_PASS_THRU_MODE interface are read-only.

Attributes
Additional information on the attributes of the NVM Express controller. See “Related Definitions” below for the list of possible attributes.

IoAlign
Supplies the alignment requirement for any buffer used in a data transfer. IoAlign values of 0 and 1 mean that the buffer can be placed anywhere in memory. Otherwise, IoAlign must be a power of 2, and the requirement is that the start address of a buffer must be evenly divisible by IoAlign with no remainder.

NvmeVersion
Indicates the version of the NVM Express specification that the controller implementation supports. The format of this field is defined in the Version field of the Controller Registers in the NVM Express Specification.

Related Definitions

typedef struct {
    UINT32 Attributes;
    UINT32 IoAlign;
    UINT32 NvmeVersion;
} EFI_NVM_EXPRESS_PASS_THRU_MODE;

#define EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_PHYSICAL 0x0001
#define EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_LOGICAL 0x0002
#define EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_NONBLOCKIO 0x0004
#define EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_CMD_SET_NVM 0x0008

EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_PHYSICAL
If this bit is set, then the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL interface is for directly addressable namespaces.

EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_LOGICAL
If this bit is set, then the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL interface is for a single volume logical namespace comprised of multiple namespaces.

EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_NONBLOCKIO
If this bit is set, then the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL interface supports non-blocking I/O.
** EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_CMD_SET_NVM **

If this bit is set, then the `EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL` interface supports NVM command set.

**Description**

The `EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL` provides information about an NVM Express controller and the ability to send NVM Express commands to an NVM Express controller or to a specific namespace in a NVM Express controller.

- The printable name for the NVM Express controller can be provided through the `EFI_COMPONENT_NAME_PROTOCOL` and the `EFI_COMPONENT_NAME2_PROTOCOL` for multiple languages.

The `Attributes` field of the `EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL` interface tells if the interface is for physical NVM Express controllers or logical NVM Express controllers. Drivers for non-RAID NVM Express controllers will set both the `EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_PHYSICAL` and the `EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_LOGICAL` bits.

Drivers for RAID controllers that allow access to the physical controllers and logical controllers will produce two `EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL` interfaces: one with just the `EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_PHYSICAL` bit set and another with just the `EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_LOGICAL` bit set. One interface can be used to access the physical controllers attached to the RAID controller, and the other can be used to access the logical controllers attached to the RAID controller for its current configuration.

Drivers for RAID controllers that do not allow access to the physical controllers will produce one `EFI_NVM_EXPRESS_PASS_THROUGH_PROTOCOL` interface with just the `EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_LOGICAL` bit set. The interface for logical controllers can also be used by a file system driver to mount the RAID volumes. An `EFI_NVM_EXPRESS_PASS_THROUGH_PROTOCOL` with neither `EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_LOGICAL` nor `EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_PHYSICAL` set is an illegal configuration.

The `Attributes` field also contains the `EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_NONBLOCKIO` bit. All `EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL` interfaces must support blocking I/O. If this bit is set, then the interface supports both blocking I/O and non-blocking I/O.

The `Attributes` field also contains the `EFI_NVM_EXPRESS_PASS_THRU_ATTRIBUTES_CMD_SET_NVM` bit. If this bit is set, the controller supports the NVM Express command set.

- Each `EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL` instance must have an associated device path. Typically this will have an ACPI device path node and a PCI device path node, although variation will exist.

**13.15.2 EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.PassThru()**

**Summary**

Sends an NVM Express Command Packet to an NVM Express controller or namespace. This function supports both blocking I/O and non-blocking I/O. The blocking I/O functionality is required, and the non-blocking I/O functionality is optional.

**Prototype**

```c
typedef EFI_STATUS
    (EFIAPI *EFI_NVM_EXPRESS_PASS_THRU_PASSTHRU) (
    IN EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL This,
    IN UINT32 NamespaceId,

(continues on next page)```
IN OUT EFI_NVM_EXPRESS_PASS_THRU_COMMAND_PACKET *Packet,
IN EFI_EVENT Event OPTIONAL
);

Parameters

This
A pointer to the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL instance. Type EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL is defined in See NVM Express Pass Through Protocol, above.

NamespaceId
A 32 bit namespace ID as defined in the NVMe specification to which the NVM Express Command Packet will be sent. A value of 0 denotes the NVM Express controller, a value of all 0xFF’s (all bytes are 0xFF ) in the namespace ID specifies that the command packet should be sent to all valid namespaces.

Packet
A pointer to the NVM Express Command Packet. See “Related Definitions” below for a description of EFI_NVM_EXPRESS_PASS_THRU_COMMAND_PACKET.

Event
If non-blocking I/O is not supported then Event is ignored, and blocking I/O is performed. If Event is NULL, then blocking I/O is performed. If Event is not NULL and non-blocking I/O is supported, then non-blocking I/O is performed, and Event will be signaled when the NVM Express Command Packet completes.

Related Definitions

typedef struct {
    UINT64 CommandTimeout;
    VOID TransferBuffer OPTIONAL;
    UINT32 TransferLength OPTIONAL;
    VOID *MetaDataBuffer OPTIONAL;
    UINT32 MetadataLength OPTIONAL;
    UINT8 QueueType;
    EFI_NVM_EXPRESS_COMMAND *NvmeCmd;
    EFI_NVM_EXPRESS_COMPLETION *NvmeCompletion;
} EFI_NVM_EXPRESS_PASS_THRU_COMMAND_PACKET;

CommandTimeout
The timeout in 100 ns units to use for the execution of this NVM Express Command Packet. A Timeout value of 0 means that this function will wait indefinitely for the command to execute. If Timeout is greater than zero, then this function will return EFI_TIMEOUT if the time required to execute the NVM Express command is greater than Timeout.

TransferBuffer
A pointer to the data buffer to transfer between the host and the NVM Express controller for read, write, and bi-directional commands. For all write and non-data commands where TransferLength is 0 this field is optional and may be NULL. If this field is not NULL, then it must be aligned on the boundary specified by the IoAlign field in the EFI_NVM_EXPRESS_PASS_THRU_MODE structure.

TransferLength
On input, the size in bytes of TransferBuffer*. On output, the number of bytes transferred to or from the NVM Express controller or namespace.

MetadataBuffer
A pointer to the optional metadata buffer to transfer between the host and the NVM Express controller. For all commands where no metadata is transferred between the host and the controller, this field is optional and may
be NULL. If this field is not NULL, then it must be aligned on the boundary specified by the IoAlign field in the EFI_NVM_EXPRESS_PASS_THRU_MODE structure.

MetadataLength
On input, the size in bytes of MetadataBuffer. On output, the number of bytes transferred to or from the NVM Express controller or namespace.

QueueType
The type of the queue that the NVMe command should be posted to. A value of 0 indicates it should be posted to the Admin Submission Queue. A value of 1 indicates it should be posted to an I/O Submission Queue.

NvmeCmd
A pointer to an NVM Express Command Packet.

NvmeCompletion
The raw NVM Express completion queue entry as defined in the NVM Express Specification.

Description
The PassThru() function sends the NVM Express Command Packet specified by Packet to the NVM Express controller. If the driver supports non-blocking I/O and Event is not NULL, then the driver will return immediately after the command is sent to the selected controller, and will later signal Event when the command has completed.

If the driver supports non-blocking I/O and Event is NULL, then the driver will send the command to the selected device and block until it is complete.

If the driver does not support non-blocking I/O, and Event parameter is ignored, and the driver will send the command to the selected device and block until it is complete.

If Packet is successfully sent to the NVM Express controller, then EFI_SUCCESS is returned.

If a device error occurs while sending the Packet, then EFI_DEVICE_ERROR is returned.

If a timeout occurs during the execution of Packet, then EFI_TIMEOUT is returned.

If NamespaceId is invalid for the NVM Express controller, then EFI_INVALID_PARAMETER is returned.

If TransferBuffer or MetadataBuffer do not meet the alignment requirement specified by the IoAlign field of the EFI_NVM_EXPRESS_PASS_THRU_MODE structure, then EFI_INVALID_PARAMETER is returned. If the QueueType is not 0 (Admin Submission Queue) or 1 (I/O Submission Queue), then EFI_INVALID_PARAMETER is returned.

If any of the other fields of Packet are invalid, then EFI_INVALID_PARAMETER is returned.

If the data buffer described by TransferBuffer and TransferLength is too big to be transferred in a single command, then no data is transferred and EFI_BAD_BUFFER_SIZE is returned. The number of bytes that can be transferred in a single command are returned in TransferLength.

If EFI_SUCCESS, EFI_DEVICE_ERROR, or EFI_TIMEOUT is returned, then the caller must examine the NvmeCompletion field in Packet.

If non-blocking I/O is being used, then the NvmeCompletion field in Packet will not be valid until the Event associated with Packet is signaled.

If EFI_NOT_READY, EFI_INVALID_PARAMETER, EFI_BAD_BUFFER_SIZE, or EFI_UNSUPPORTED is returned, then Packet was never sent, so the NvmeCompletion field in Packet is not valid. If non-blocking I/O is being used, the Event associated with Packet will not be signaled.

Status Codes Returned

| EFI_SUCCESS | The NVM Express Command Packet was sent by the host. TransferLength bytes were transferred to or from TransferBuffer. See NvmeCompletion (above) for additional status information. |

continues on next page
Table 13.56 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>The NVM Express Command Packet was not executed. The number of bytes that could be transferred is returned in TransferLength.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The NVM Express Command Packet could not be sent because the controller is not ready. The caller may retry again later.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to send the NVM Express Command Packet. See NvmeCompletion (above) for additional status information.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>NamespaceId or the contents of EFI_NVM_EXPRESS_PASS_THRU_COMMAND_PACKET are invalid. The NVM Express Command Packet was not sent, so no additional status information is available.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The command described by the NVM Express Command Packet is not supported by the NVM Express controller. The NVM Express Command Packet was not sent so no additional status information is available.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>A timeout occurred while waiting for the NVM Express Command Packet to execute. See NvmeCompletion (above) for additional status information.</td>
</tr>
</tbody>
</table>

Related Definitions

typedef struct {
    UINT32 OpCode;     8;
    UINT32 FusedOperation; 2;
    UINT32 Reserved : 22;
} NVME_CDW0;

//********************************************************
// FusedOperation
//********************************************************
#define NORMAL_CMD 0x00
#define FUSED_FIRST_CMD 0x01
#define FUSED_SECOND_CMD 0x02

typedef struct {
    NVME_CDW0 Cdw0;
    UINT8 Flags;
    UINT32 Nsid;
    UINT32 Cdw2;
    UINT32 Cdw3;
    UINT32 Cdw10;
    UINT32 Cdw11;
    UINT32 Cdw12;
    UINT32 Cdw13;
    UINT32 Cdw14;
    UINT32 Cdw15;
} EFI_NVM_EXPRESS_COMMAND;

//********************************************************
// Flags
//********************************************************
#define CDW2_VALID 0x01
#define CDW3_VALID 0x02
#define CDW10_VALID 0x04
#define CDW11_VALID 0x08

(continues on next page)
#define CDW12_VALID 0x10
#define CDW13_VALID 0x20
#define CDW14_VALID 0x40
#define CDW15_VALID 0x80

// This structure maps to the NVM Express specification Completion Queue Entry
typedef struct{
    UINT32 DW0;
    UINT32 DW1;
    UINT32 DW2;
    UINT32 DW3;
} EFI_NVM_EXPRESS_COMPLETION;

### 13.15.3 EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.GetNextNamespace()

#### Summary
Used to retrieve the next namespace ID for this NVM Express controller.

#### Prototype
```c
typedef EFI_STATUS (EFIAPI *EFI_NVM_EXPRESS_PASS_THRU_GET_NEXT_NAMESPACE) (IN EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL *This,
                                                                                    IN OUT UINT32 *NamespaceId);
```

#### Parameters

**This**
A pointer to the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL instance.

**NamespaceId**
On input, a pointer to a valid namespace ID on this NVM Express controller or a pointer to the value 0xFFFFFFFF. A pointer to the value 0xFFFFFFFF retrieves the first valid namespace ID defined on the NVM Express controller.

#### Description
The EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.GetNextNamespace() function retrieves the next valid namespace ID on this NVM Express controller. If on input the value pointed to by *NamespaceId* is 0xFFFFFFFF, then the first valid namespace ID defined on the NVM Express controller is returned in the location pointed to by *NamespaceId* and a status of EFI_SUCCESS is returned.

If on input the value pointed to by *NamespaceId* is an invalid namespace ID other than 0xFFFFFFFF, then EFI_INVALID_PARAMETER is returned.

If on input the value pointed to by *NamespaceId* is a valid namespace ID, then the next valid namespace ID on the NVM Express controller is returned in the location pointed to by *NamespaceId*, and EFI_SUCCESS is returned.

If the value pointed to by *NamespaceId* is the namespace ID of the last namespace on the NVM Express controller, then EFI_NOT_FOUND is returned.

#### Status Codes Returned
13.15.4 EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.BuildDevicePath()

Summary

Used to allocate and build a device path node for an NVMExpress namespace on an NVM Express controller.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_NVM_EXPRESS_PASS_THRU_BUILD_DEVICE_PATH) ( 
    IN EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL *This,
    IN UINT32 NamespaceId,
    OUT EFI_DEVICE_PATH_PROTOCOL **DevicePath
    );

Parameters

This

A pointer to the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL*instance. Type *EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL is defined in NVM Express Pass Through Protocol.

NamespaceId

The NVM Express namespace ID for which a device path node is to be allocated and built.

DevicePath

A pointer to a single device path node that describes the NVM Express namespace specified by NamespaceId. This function is responsible for allocating the buffer*DevicePath* with the boot service AllocatePool(). It is the caller’s responsibility to free DevicePath when the caller is finished with DevicePath.

Description

The EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.BuildDevicePath() function allocates and builds a single device path node for the NVM Express namespace specified by NamespaceId. If the NamespaceId is not valid, then EFI_NOT_FOUND is returned. If DevicePath is NULL, then EFI_INVALID_PARAMETER is returned. If there are not enough resources to allocate the device path node, then EFI_OUT_OF_RESOURCES is returned. Otherwise, DevicePath is allocated with the boot service AllocatePool(), the contents of DevicePath are initialized to describe the NVM Express namespace specified by NamespaceId, and EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device path node that describes the NVM Express namespace specified by NamespaceId was allocated and returned in DevicePath</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The NamespaceId is not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DevicePath is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There are not enough resources to allocate the DevicePath node.</td>
</tr>
</tbody>
</table>
13.15.5 EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.GetNamespace()

Summary
Used to translate a device path node to a namespace ID.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_NVM_EXPRESS_PASS_THRU_GET_NAMESPACE) (  
  IN EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL *This,
  IN EFI_DEVICE_PATH_PROTOCOL *DevicePath,
  OUT UINT32 *NamespaceId
);```

Parameters

This
A pointer to the EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL instance. Type EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL is defined in NVM Express Pass Through Protocol.

DevicePath
A pointer to the device path node that describes an NVM Express namespace on the NVM Express controller.

NamespaceId
The NVM Express namespace ID contained in the device path node.

Description
The EFI_NVM_EXPRESS_PASS_THRU_PROTOCOL.GetNamespace() function determines the namespace ID associated with the namespace described by DevicePath. If DevicePath is a device path node type that the NVM Express Pass Thru driver supports, then the NVM Express Pass Thru driver will attempt to translate the contents DevicePath into a namespace ID. If this translation is successful, then that namespace ID is returned in NamespaceId, and EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>If DevicePath or NamespaceId are NULL, then EFI_INVALID_PARAMETER is returned.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>If DevicePath is not a device path node type that the NVM Express Pass Thru driver supports, then EFI_UNSUPPORTED is returned.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>If DevicePath is a device path node type that the NVM Express Pass Thru driver supports, but there is not a valid translation from DevicePath to a namespace ID, then EFI_NOT_FOUND is returned.</td>
</tr>
</tbody>
</table>
13.16 SD MMC Pass Thru Protocol

13.16.1 EFI_SD_MMC_PASS_THRU_PROTOCOL

This section provides a detailed description of the EFI_SD_MMC_PASS_THRU_PROTOCOL. The protocol provides services that allow SD/eMMC commands to be sent to an SD/eMMC controller. All interfaces and definitions from this section apply equally to SD and eMMC controllers.

For the sake of brevity, the rest of this section refers only to SD devices and controllers and does not specifically mention eMMC devices and controllers.

GUID

#define EFI_SD_MMC_PASS_THRU_PROTOCOL_GUID \ 
{ 0x716ef0d9, 0xff83, 0x4f69, \ 
{ 0x81, 0xe9, 0x51, 0x8b, 0xd3, 0x9a, 0x8e, 0x70 } }

Protocol Interface Structure

typedef struct _EFI_SD_MMC_PASS_THRU_PROTOCOL {
    UINTN IoAlign;
    EFI_SD_MMC_PASS_THRU_PASSTHRU PassThru;
    EFI_SD_MMC_PASS_THRU_GET_NEXT_SLOT GetNextSlot;
    EFI_SD_MMC_PASS_THRU_BUILD_DEVICE_PATH BuildDevicePath;
    EFI_SD_MMC_PASS_THRU_GET_SLOT_NUMBER GetSlotNumber;
    EFI_SD_MMC_PASS_THRU_RESET_DEVICE ResetDevice;
} EFI_SD_MMC_PASS_THRU_PROTOCOL;

Parameters

IoAlign
    Supplies the alignment requirement for any buffer used in a data transfer. IoAlign values of 0 and 1 mean that the buffer can be placed anywhere in memory. Otherwise, IoAlign must be a power of 2, and the requirement is that the start address of a buffer must be evenly divisible by IoAlign with no remainder.

PassThru
    Sends SD command to the SD controller. See the PassThru() function description.

GetNextSlot
    Retrieves a next slot on an SD controller. See the GetNextSlot() function description.

BuildDevicePath
    Allocates and builds a device path node for an SD card on the SD controller. See the BuildDevicePath() function description.

GetSlotNumber
    Retrieves the SD card slot number based on the input device path. See the GetSlotNumber() function description.

ResetDevice
    Resets an SD card connected to the SD controller. See the ResetDevice() function description.
13.16.2 EFI_SD_MMC_PASS_THRU_PROTOCOL.PassThru()

Summary
Sends SD command to an SD card that is attached to the SD controller.

Prototype

typedef EFI_STATUS
(EIFIAPIC EFI_SD_MMC_PASS_THRU_PASSTHRU) (    
    IN EFI_SD_MMC_PASS_THRU_PROTOCOL *This,
    IN UINT8 Slot,
    IN OUT EFI_SD_MMC_PASS_THRU_COMMAND_PACKET *Packet,
    IN EFI_EVENT Event OPTIONAL
);

Parameters

This
A pointer to the EFI_SD_MMC_PASS_THRU_PROTOCOL instance.

Slot
The slot number of the SD card to send the command to.

Packet
A pointer to the SD command data structure. See “Related Definitions” below for a description of EFI_SD_MMC_PASS_THRU_COMMAND_PACKET.

Event
If non-blockingI/O is not supported then Event is ignored, and blocking I/O is performed. If Event is NULL, then blockingI/O is performed. If Event is not NULL and non-blockingI/O is supported, then non-blockingI/O is performed, and Event will be signaled when the SD command completes.

Related Definitions

typedef struct {
    EFI_SD_MMC_COMMAND_BLOCK *SdMmcCmdBlk;
    EFI_SD_MMC_STATUS_BLOCK *SdMmcStatusBlk;
    UINT64 Timeout
    VOID *InDataBuffer;
    VOID *OutDataBuffer;
    UINT32 InTransferLength;
    UINT32 OutTransferLength;
    EFI_STATUS TransactionStatus;
} EFI_SD_MMC_PASS_THRU_COMMAND_PACKET;

SdMmcCmdBlk
A pointer to a command specific data buffer allocated and filled by the caller. See “Related Definitions” below for a description of EFI_SD_MMC_COMMAND_BLOCK.

SdMmcStatusBlk
A pointer to a command specific response data buffer allocated by the caller and filled by the PassThru function. See “Related Definitions” below for a description of EFI_SD_MMC_STATUS_BLOCK.

Timeout
The timeout, in 100 ns units, to use for the execution of this SD command. A Timeout value of 0 means that this function will wait indefinitely for the SD command to execute. If Timeout is greater than zero, then this function will return EFI_TIMEOUT if the time required to execute the SD command is greater than Timeout.
**InDataBuffer**  
A pointer to a buffer for the data transferred from the SD card during processing of read and bidirectional commands. For all write and non-data commands this field is optional and may be **NULL**.

**OutDataBuffer**  
A pointer to a buffer for the data to be transferred to the SD card during processing of write or bidirectional commands. For all read and non-data commands this field is optional and may be **NULL**.

**InTransferLength**  
On input, the size, in bytes, of **InDataBuffer**. On output, the number of bytes transferred between the SD controller and the SD device. If **InTransferLength** is larger than the SD controller can handle, no data will be transferred, **InTransferLength** will be updated to contain the number of bytes that the SD controller is able to transfer, and **EFI_BAD_BUFFER_SIZE** will be returned.

**OutTransferLength**  
On Input, the size, in bytes of **OutDataBuffer**. On Output, the Number of bytes transferred between SD Controller and the SD device. If **OutTransferLength** is larger than the SD controller can handle, no data will be transferred. **OutTransferLength** will be updated to contain the number of bytes that the SD controller is able to transfer, and **EFI_BAD_BUFFER_SIZE** will be returned.

**TransactionStatus**  
Transaction status. When **PathThru()** function is used in a blocking mode, the status must be the same as the status returned by the **PathThru()** function. When **PathThru()** function is used in a non-blocking mode, the field is updated with the transaction status once transaction is completed.

**Related Definitions**

```c
typedef struct {
    UNIT16 CommandIndex;
    UINT32 CommandArgument;
    UINT32 CommandType; // One of the EFI_SD_MMC_COMMAND_TYPE values
    UINT32 ResponseType; // One of the EFI_SD_MMC_RESPONSE_TYPE values
} EFI_SD_MMC_COMMAND_BLOCK;

typedef struct {
    UINT32 Resp0;
    UINT32 Resp1;
    UINT32 Resp2;
    UINT32 Resp3;
} EFI_SD_MMC_STATUS_BLOCK;

typedef enum {
    SdMmcCommandTypeBc, // Broadcast commands, no response
    SdMmcCommandTypeBcr, // Broadcast commands with response
    SdMmcCommandTypeAc, // Addressed(point-to-point) commands
    SdMmcCommandTypeAdtc // Addressed(point-to-point) data transfer
    // commands
} EFI_SD_MMC_COMMAND_TYPE;

typedef enum {
    SdMmcResponceTypeR1,
    SdMmcResponceTypeR1b,
    SdMmcResponceTypeR2,
    SdMmcResponceTypeR3,
    SdMmcResponceTypeR4,
    SdMmcResponceTypeR5,
}
```

(continues on next page)
SdMmcResponseTypeR5b,
SdMmcResponseTypeR6,
SdMmcResponseTypeR7
} EFI_SD_MMC_RESPONSE_TYPE;

**Description**

The `PassThru()` function sends the SD command specified by `Packet` to the SD card specified by `Slot`.

If `Packet` is successfully sent to the SD card, then `EFI_SUCCESS` is returned. If a device error occurs while sending the `Packet`, then `EFI_DEVICE_ERROR` is returned. If `Slot` is not in a valid range for the SD controller, then `EFI_INVALID_PARAMETER` is returned. If `Packet` defines a data command but both `InDataBuffer` and `OutDataBuffer` are `NULL`, `EFI_INVALID_PARAMETER` is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The SD Command Packet was sent by the host.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to send the SD command Packet.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Packet, Slot, or the contents of the Packet is invalid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Packet defines a data command but both InDataBuffer and OutDataBuffer are NULL.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>SD Device not present in the Slot.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The command described by the SD Command Packet is not supported by the host controller.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>The InTransferLength or OutTransferLength exceeds the limit supported by SD card (i.e. if the number of bytes exceed the Last LBA).</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The command was not sent due to a device error</td>
</tr>
</tbody>
</table>

**13.16.3 EFI_SD_MMC_PASS_THRU_PROTOCOL.GetNextSlot()**

**Summary**

Used to retrieve next slot numbers supported by the SD controller. The function returns information about all available slots (populated or not-populated).

**Prototype**

```c
typedef EFI_STATUS
(EFIAPI *EFI_SD_MMC_PASS_THRU_GET_NEXT_SLOT) (  
  IN EFI_SD_MMC_PASS_THRU_PROTOCOL *This,  
  IN OUT UINT8 *Slot
);
```

**Parameters**

**This**

A pointer to the EFI_SD_MMMC_PASS_THRU_PROTOCOL instance.

**Slot**

On input, a pointer to a slot number on the SD controller. On output, a pointer to the next slot number on the SD controller. An input value of 0xFF retrieves the first slot number on the SD controller.

**Description**
The `GetNextSlot()` function retrieves the next slot number on an SD controller. If on input `Slot` is `0xFF`, then the slot number of the first slot on the SD controller is returned.

If `Slot` is a slot number that was returned on a previous call to `GetNextSlot()`, then the slot number of the next slot on the SD controller is returned.

If `Slot` is not `0xFF` and `Slot` was not returned on a previous call to `GetNextSlot()`, `EFI_INVALID_PARAMETER` is returned.

If `Slot` is the slot number of the last slot on the SD controller, then `EFI_NOT_FOUND` is returned.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The next slot number on the SD controller was returned in Slot.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>There are no more slots on this SD controller.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>Slot</code> is not <code>0xFF</code> and <code>Slot</code> was not returned on a previous call to <code>GetNextSlot()</code>.</td>
</tr>
</tbody>
</table>

### 13.16.4 EFI_SD_MMC_PASS_THRU_PROTOCOL.BuildDevicePath()

**Summary**

*Used to allocate and build a device path node for an SD card on the SD controller.*

**Prototype**

```c
typedef EFI_STATUS
(EFIAPI *EFI_SD_MMC_PASS_THRU_BUILD_DEVICE_PATH) (
    IN EFI_SD_MMC_PASS_THRU_PROTOCOL *This,
    IN UINT8 Slot,
    OUT EFI_DEVICE_PATH_PROTOCOL **DevicePath
);
```

**Parameters**

- **This**
  A pointer to the `EFI_SD_MMC_PASS_THRU_PROTOCOL` instance.

- **Slot**
  Specifies the slot number of the SD card for which a device path node is to be allocated and built.

- **DevicePath**
  A pointer to a single device path node that describes the SD card specified by `Slot`. This function is responsible for allocating the buffer `DevicePath` with the boot service `AllocatePool()`. It is the caller’s responsibility to free `DevicePath` when the caller is finished with `DevicePath`.

**Description**

The `BuildDevicePath()` function allocates and builds a single device node for the SD card specified by `Slot`. If the SD card specified by `Slot` is not present on the SD controller, then `EFI_NOT_FOUND` is returned. If `DevicePath` is NULL, then `EFI_INVALID_PARAMETER` is returned. If there are not enough resources to allocate the device path node, then `EFI_OUT_OF_RESOURCES` is returned.

Otherwise, `DevicePath` is allocated with the boot service `AllocatePool()`, the contents of `DevicePath` are initialized to describe the SD card specified by `Slot`, and `EFI_SUCCESS` is returned.

### Status Codes Returned
### 13.16.5 EFI_SD_MMC_PASS_THRU_PROTOCOL.GetSlotNumber()

**Summary**
This function retrieves an SD card slot number based on the input device path.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_SD_MMC_PASS_THRU_GET_SLOT_NUMBER) (
    IN EFI_SD_MMC_PASS_THRU_PROTOCOL *This,
    IN EFI_DEVICE_PATH_PROTOCOL *DevicePath,
    OUT UINT8 *Slot
);
```

**Parameters**

- **This**
  A pointer to the `EFI_SD_MMC_PASS_THRU_PROTOCOL` instance.

- **DevicePath**
  A pointer to the device path node that describes a SD card on the SD controller.

- **Slot**
  On return, points to the slot number of an SD card on the SD controller.

**Description**

The `GetSlotNumber()` function retrieves slot number for the SD card specified by the `DevicePath` node. If `DevicePath` is NULL, `EFI_INVALID_PARAMETER` is returned. If `DevicePath` is not a device path node type that the SD Pass Thru driver supports, `EFI_UNSUPPORTED` is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>SD card slot number is returned in <code>Slot</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Slot or <code>DevicePath</code> is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td><code>DevicePath</code> is not a device path node type that the SD Pass Thru driver supports.</td>
</tr>
</tbody>
</table>
13.16.6 EFI_SD_MMC_PASS_THRU_PROTOCOL.ResetDevice()

Summary
Resets an SD card that is connected to the SD controller.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_SD_MMC_PASS_THRU_RESET_DEVICE) (
    IN EFI_SD_MMC_PASS_THRU_PROTOCOL *This,
    IN UINT8 Slot
);
```

Parameters

This
A pointer to the EFI_SD_MMC_PASS_THRU_PROTOCOL instance.

Slot
Specifies the slot number of the SD card to be reset.

Description
The ResetDevice() function resets the SD card specified by Slot. If this SD controller does not support a device reset operation, EFI_UNSUPPORTED is returned. If Slot is not in a valid slot number for this SD controller, EFI_INVALID_PARAMETER is returned.

If the device reset operation is completed, EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The SD card specified by Slot was reset.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The SD controller does not support a device reset operation.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Slot number is invalid.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>SD Device not present in the Slot.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The reset command failed due to a device error</td>
</tr>
</tbody>
</table>

13.17 RAM Disk Protocol

13.17.1 EFI_RAM_DISK_PROTOCOL

Summary
RAM disk aware application invokes this protocol to register/unregister a specified RAM disk.

GUID

```c
#define EFI_RAM_DISK_PROTOCOL_GUID \   
    { 0xab38a0df, 0x6873, 0x44a9, \   
      0x87, 0xe6, 0xd4, 0xeb, 0x56, 0x14, 0x84, 0x49 }\}
```

Protocol Interface Structure
typedef struct _EFI_RAM_DISK_PROTOCOL {
    EFI_RAM_DISK_REGISTER_RAMDISK Register;
    EFI_RAM_DISK_UNREGISTER_RAMDISK Unregister;
} EFI_RAM_DISK_PROTOCOL;

Members

Register
    Register a RAM disk with specified buffer address, size and type.

Unregister
    Unregister the RAM disk specified by a device path.

Description

This protocol defines a standard interface for UEFI applications, drivers and OS loaders to register/unregister a RAM disk.

The key points are:

• The consumer of this protocol is responsible for allocating/freeing memory used by RAM Disk if needed and deciding the initial content, as in most scenarios only the consumer knows which type and how much memory should be used.

13.17.2 EFI_RAM_DISK_PROTOCOL.Register()

Summary

This function is used to register a RAM disk with specified address, size and type.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_RAM_DISK_REGISTER_RAMDISK) (  
    IN UINT64 RamDiskBase,  
    IN UINT64 RamDiskSize,  
    IN EFI_GUID *RamDiskType,  
    IN EFI_DEVICE_PATH *ParentDevicePath OPTIONAL,  
    OUT EFI_DEVICE_PATH_PROTOCOL **DevicePath
);  

Parameters

RamDiskBase
    The base address of registered RAM disk.

RamDiskSize
    The size of registered RAM disk.

RamDiskType
    The type of registered RAM disk. The GUID can be any of the values defined in RAM Disk, or a vendor defined GUID.

ParentDevicePath
    Pointer to the parent device path. If there is no parent device path then ParentDevicePath is NULL.

DevicePath
    On return, points to a pointer to the device path of the RAM disk device. If ParentDevicePath is not NULL, the
returned DevicePath is created by appending a RAM disk node to the parent device path. If ParentDevicePath is NULL, the returned DevicePath is a RAM disk device path without appending. This function is responsible for allocating the buffer DevicePath with the boot service AllocatePool().

Description

The Register function is used to register a specified RAM Disk. The consumer of this API is responsible for allocating the space of the RAM disk and deciding the initial content of the RAM disk. The producer of this API is responsible for installing the RAM disk device path and block I/O related protocols on the RAM disk device handle.

RamDiskBase, RamDiskSize and RamDiskType are used to fill RAM disk device node. If RamDiskSize is 0, then EFI_INVALID_PARAMETER is returned. If RamDiskType is NULL, then EFI_INVALID_PARAMETER is returned.

DevicePath returns the device path of the registered RAM disk. If DevicePath is NULL, then EFI_INVALID_PARAMETER is returned. If there are not enough resources to allocate the device path node, then EFI_OUT_OF_RESOURCES is returned. Otherwise, DevicePath is allocated with the boot service AllocatePool(). If ParentDevicePath is not NULL, the DevicePath instance is created by appending a RAM disk device node to the ParentDevicePath. If ParentDevicePath is NULL, the DevicePath instance is a pure RAM disk device path. If the created DevicePath instance is already present in the handle database, then EFI_ALREADY_STARTED is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The RAM disk is registered successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DevicePath or RamDiskType is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>RamDiskSize is 0.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>A Device Path Protocol instance to be created is already present in the handle database.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The RAM disk register operation fails due to resource limitation.</td>
</tr>
</tbody>
</table>

13.17.3 EFI_RAM_DISK_PROTOCOL.Unregister()

Summary

This function is used to unregister a RAM disk specified by DevicePath.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_RAM_DISK_UNREGISTER_RAMDISK) (  
  IN EFI_DEVICE_PATH_PROTOCOL  *DevicePath
);
```

Parameters

DevicePath

A pointer to the device path that describes a RAM Disk device.

Description

The Unregister function is used to unregister a specified RAM Disk. The producer of this protocol is responsible for uninstalling the RAM disk device path and block I/O related protocols and freeing the RAM disk device handle. It is the consumer of this protocol’s responsibility to free the memory used by this RAM disk.

Status Codes Returned
### 13.18 Partition Information Protocol

**Summary**

Installed along with EFI_BLOCK_IO_PROTOCOL for logical partitions. The PARTITION_INFORMATION_PROTOCOL provides cached partition information for MBR and GPT partition types.

- Set System to 1 for partition identified as EFI_SYSTEM_PARTITIONs, otherwise set System to 0.
- Set Type to PARTITION_TYPE_OTHER for partitions that are not GPT or MBR to indicate no cached data.

**GUID**

```c
#define EFI_PARTITION_INFO_PROTOCOL_GUID \
{ \n 0x8cf2f62c, 0xbc9b, 0x4821, {0x80, 0x8d, 0xec, 0x9e, \n    0xc4, 0x21, 0xa1, 0xa0} \n}
```

**Protocol Interface Structure**

```c
#define EFI_PARTITION_INFO_PROTOCOL_REVISION 0x0001000
#define PARTITION_TYPE_OTHER 0x00
#define PARTITION_TYPE_MBR 0x01
#define PARTITION_TYPE_GPT 0x02

#pragma pack(1)

typedef struct {
    UINT32 Revision;
    UINT32 Type;
    UINT8 System;
    UINT8 Reserved[7];
    union {
        ///
        /// MBR data
        ///
        MBR_PARTITION_RECORD Mbr;
        
        ///
        /// GPT data
        ///
        EFI_PARTITION_ENTRY Gpt;
    } Info;
} EFI_PARTITION_INFO_PROTOCOL;
```

(continues on next page)
See the *Legacy MBR* for the definition of MBR_PARTITION_RECORD.

See *Protective MBR* for the definition of EFI_PARTITION_ENTRY.

**Parameters**

**Revision**
- Set to EFI_PARTITION_INFO_PROTOCOL_REVISION

**Type**
- Partition info type (MBR, GPT, or Other).

**System**
- If 1, partition describes an EFI System Partition.

**Mbr**
- MBR information, if type is MBR.

**Gpt**
- GPT information, if type is GPT

**Description**

The EFI_PARTITION_INFO_PROTOCOL is a simple protocol used to cache the partition information for potential File System Drivers.

Care must be taken by UEFI utilities that manipulate partitions. The utility must gain exclusive access to the physical disk to cause the partition driver to be stopped before it changes the partition information. If the exclusive request is not granted, then the utility must reset the system after changing the partition information.

When Type is set to PARTITION_TYPE_OTHER, data in the union Info is undefined.

### 13.19 NVDIMM Label Protocol

#### 13.19.1 EFI_NVDIMM_LABEL_PROTOCOL

This section provides a detailed description of the EFI_NVDIMM_LABEL_PROTOCOL. For a high-level overview of the NVDIMM Label protocol see the Label Storage Area Description section.

**Summary**

Provides services that allow management of labels contained in a Label Storage Area that are associated with a specific NVDIMM Device Path. The labels describe how the data on the NVDIMM is organized in to namespaces, the layout being utilized, logical block size, unique label identifier, label state, etc.

**GUID**

```
#define EFI_NVDIMM_LABEL_PROTOCOL_GUID \ 
{0xd40b6b80,0x97d5,0x4282, \ 
 {0xbb,0x1d,0x22,0x3a,0x16,0x91,0x80,0x58}}
```

**Protocol Interface Structure**
typedef struct _EFI_NVDIMM_LABEL_PROTOCOL {
    EFI_NVDIMM_LABEL_STORAGE_INFORMATION LabelStorageInformation;
    EFI_NVDIMM_LABEL_STORAGE_READ LabelStorageRead;
    EFI_NVDIMM_LABEL_STORAGE_WRITE LabelStorageWrite;
} Parameters

LabelStorageInformation
Reports the size of the Label Storage Area and the maximum amount of label data that can be read in a single
call to LabelStorageRead or written in a single call to LabelStorageWrite.

LabelStorageRead
Returns the label data stored for the NVDIMM at the requested offset and length in the Label Storage Area.

LabelStorageWrite
Writes the label data stored for the NVDIMM at the requested offset and length in the Label Storage Area.

13.19.2 EFI_NVDIMM_LABEL_PROTOCOL.LabelStorageInformation()

Summary
Retrieves the Label Storage Area size and the maximum transfer size for the LabelStorageRead and LabelStorageWrite
methods that are associated with a specific NVDIMM Device Path.

Prototype
typedef
 EFI_STATUS
 (EFIAPI * EFI_NVDIMM_LABEL_STORAGE_INFORMATION) (
     IN EFI_NVDIMM_LABEL_PROTOCOL *This,
     OUT UINT32 *SizeOfLabelStorageArea,
     OUT UINT32 *MaxTransferLength
 );

Parameters
This
A pointer to the EFI_NVDIMM_LABEL_PROTOCOL instance.

SizeOfLabelStorageArea
The size of the Label Storage Area for the NVDIMM in bytes.

MaxTransferLength
The maximum number of bytes that can be transferred in a single call to LabelStorageRead or LabelStorageWrite.

Description
Retrieves the Label Storage Area size and the maximum transfer size for the LabelStorageRead and LabelStorageWrite
methods.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The size of the Label Storage Area and maximum transfer size returned are</td>
</tr>
<tr>
<td></td>
<td>valid.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The Label Storage Area for the NVDIMM device is not currently accessible</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A physical device error occurred and the data transfer failed to complete</td>
</tr>
</tbody>
</table>

13.19. NVDIMM Label Protocol
13.19.3 EFI_NVDIMM_LABEL_PROTOCOL.LabelStorageRead()

**Summary**
Retrieves label data for the NVDIMM for the requested byte offset and length from within the Label Storage Area that are associated with a specific NVDIMM Device Path.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPI *EFI_NVDIMM_LABEL_STORAGE_READ) (
    IN CONST EFI_NVDIMM_LABEL_PROTOCOL *This,
    IN UINT32 Offset,
    IN UINT32 TransferLength,
    OUT UINT8 *LabelData
);
```

**Parameters**

- **This**
  A pointer to the EFI_NVDIMM_LABEL_PROTOCOL instance.

- **Offset**
  The byte offset within the Label Storage Area to read from.

- **TransferLength**
  Number of bytes to read from the Label Storage Area beginning at the byte Offset specified. A TransferLength of 0 reads no data.

- **LabelData**
  The return label data read at the requested offset and length from within the Label Storage Area.

**Description**
Retrieves the label data for the requested offset and length from within the Label Storage Area for the NVDIMM. See the Label Index Block and Label Definitions sections below for details on the contents of the label data.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The label data from the Label Storage Area for the NVDIMM was read successfully at the specified Offset and TransferLength and LabelData contains valid data.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Returned if any of the following are <strong>TRUE</strong>: - Offset &gt; SizeOfLabelStorageArea reported in the LabelStorageInformation return data. - Offset + TransferLength is &gt; SizeOfLabelStorageArea reported in the LabelStorageInformation return data. - TransferLength is &gt; MaxTransferLength reported in the LabelStorageInformation return data.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The Label Storage Area for the NVDIMM device is not currently accessible and labels cannot be read at this time.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A physical device error occurred and the data transfer failed to complete</td>
</tr>
</tbody>
</table>
### 13.19.4 EFI_NVDIMM_LABEL_PROTOCOL.LabelStorageWrite()

**Summary**

Writes label data for the NVDIMM for the requested byte offset and length to the Label Storage Area that are associated with a specific NVDIMM Device Path.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_NVDIMM_LABEL_STORAGE_WRITE) (
    IN CONST EFI_NVDIMM_LABEL_PROTOCOL *This,
    IN UINT32 Offset,
    IN UINT32 TransferLength,
    IN UINT8 *LabelData
);
```

**Parameters**

- **This**
  
  A pointer to the EFI_NVDIMM_LABEL_PROTOCOL instance.

- **Offset**
  
  The byte offset within the Label Storage Area to write to.

- **TransferLength**
  
  Number of bytes to write to the Label Storage Area beginning at the byte Offset specified. A TransferLength of 0 writes no data.

- **LabelBuffer**
  
  The label data to write at the requested offset and length from within the Label Storage Area.

**Description**

Writes the label data for the requested offset and length in to the Label Storage Area for the NVDIMM. See the Label Index Block and Label Definitions sections below for details on the contents of the label data.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The LabelData for the Label Storage Area for the NVDIMM was written successfully at the specified Offset and TransferLength.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER              | Returned this status if any of the following are **TRUE**:  
  - Offset > SizeOfLabelStorageArea reported in the LabelStorageInformation return data.  
  - Offset + LabelBufferLength is > SizeOfLabelStorageArea reported in the LabelStorageInformation return data.  
  - TransferLength is > MaxTransferLength reported in the LabelStorageInformation return data. |
| EFI_ACCESS_DENIED                  | The Label Storage Area for the NVDIMM device is not currently accessible and labels cannot be written at this time. |
| EFI_DEVICE_ERROR                   | A physical device error occurred and the data transfer failed to complete |
Label Index Block Definitions

```c
#define EFI_NVDIMM_LABEL_INDEX_SIG_LEN 16
#define EFI_NVDIMM_LABEL_INDEX_ALIGN 256

typedef struct EFI_NVDIMM_LABEL_INDEX_BLOCK {
  CHAR8 Sig[EFI_NVDIMM_LABEL_INDEX_SIG_LEN];
  UINT8 Flags[3];
  UINT8 LabelSize;
  UINT32 Seq;
  UINT64 MyOff;
  UINT64 MySize;
  UINT64 OtherOff;
  UINT64 LabelOff;
  UINT32 NSlot;
  UINT16 Major;
  UINT16 Minor;
  UINT64 Checksum;
  UINT8 Free[];
};
```

**Sig**
Signature of the Index Block data structure. Must be “NAMESPACE_INDEX0”.

**Flags**
Boolean attributes of this Label Storage Area. There are no flag bits defined at this time, so this field must be zero.

**LabelSize**
Size of each label in bytes, 128 bytes << LabelSize. 1 means 256 bytes, 2 means 512 bytes, etc. Shall be 1 or greater.

**Seq**
Sequence number used to identify which of the two Index Blocks is current. Only the least-significant two bits of this field are used in the current definition, rotating through the values depicted in Figure Z: Cyclic Sequence Numbers in Label Index Block below. The other bits must be zero.

Fig. 13.2: Cyclic Sequence Numbers in Label Index Block

Each time an Index Block is written, the sequence number of the current Index Block is “incremented” by moving to the next value clockwise as shown.
Since there are two Index Blocks, written alternatively with successive sequence numbers, the older Index Block’s sequence number will be immediately behind (counter-clockwise to) the current Index Block’s sequence number. This property is used during software initialization to identify the current Index Block.

The sequence number 00 is used to indicate an uninitialized or invalid Index Block. Software never writes the sequence number 00, so a correctly check-summed Index Block with this sequence number probably indicates a critical error. When software discovers this case it treats it as an invalid Index Block indication. If two Index Blocks with identical sequence numbers are found, software shall treat the Index Block at the higher offset as the valid Index Block.

**MyOff**

The offset of this Index Block in the Label Storage Area.

**MySize**

The size of this Index Block in bytes. This field must be a multiple of the EFI_NVDIMM_LABEL_INDEX_ALIGN.

**OtherOff**

The offset of the other Index Block paired with this one.

**LabelOff**

The offset of the first slot where labels are stored in this Label Storage Area.

**NSlot**

The total number of slots for storing labels in this Label Storage Area. The NSlot field is typically calculated once at Label Storage Area initialization as described in the Initial Label Storage Area Configuration description.

**Major**

Major version number. Value shall be 1.

**Minor**

Minor version number. Value shall be 2.

**Checksum**

64-bit Fletcher64 checksum of all fields in this Index Block. This field is considered zero when the checksum is computed. For references to the Fletcher64 algorithm see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Fletcher64 Checksum Algorithm”

**Free**

Array of unsigned bytes implementing a bitmask that tracks which label slots are free. A bit value of 0 indicates in use, 1 indicates free. The size of this field is the number of bytes required to hold the bitmask with NSlot bits, padded with additional zero bytes to make the Index Block size a multiple of EFI_NVDIMM_LABEL_INDEX_ALIGN. Any bits allocated beyond NSlot bits must be zero.

The bitmask is organized where the label slot with the lowest offset in the Label Storage Area is tracked by the least significant bit of the first byte of the free array. Missing from the above layout is a total count of free slots. Since the common use case for the Label Storage Area is to read all labels during software initialization, it is recommended that software create a total free count (or in use count, or both), maintained at run-time. Rules for maintaining the Index Blocks are described in the Label Rules Description and Validating Index Blocks Description below. See the Initial Label Storage Area Configuration section for a more details on how the total number of slots are calculated.

**Label Definitions**

```c
#define EFI_NVDIMM_LABEL_NAME_LEN 64

// Constants for Flags field
#define EFI_NVDIMM_LABEL_FLAGS_ROLABEL 0x00000001
#define EFI_NVDIMM_LABEL_FLAGS_LOCAL 0x00000002
#define EFI_NVDIMM_LABEL_FLAGS_SPACOOKIE_BOUND 0x00000010
```

(continues on next page)
// This reserved flag is utilized on older implementations
// and has been deprecated. Do not use
#define EFI_NVDIMM_LABEL_FLAGS_RESERVED 0x00000004
#define EFI_NVDIMM_LABEL_FLAGS_UPDATING 0x00000008

typedef struct EFI_NVDIMM_LABEL{
    EFI_GUID Uuid;
    CHAR8 Name[EFI_NVDIMM_LABEL_NAME_LEN];
    UINT32 Flags;
    UINT16 NLabel;
    UINT16 Position;
    UINT64 SetCookie;
    UINT64 LbaSize;
    UINT64 Dpa;
    UINT64 RawSize;
    UINT32 Slot;
    UINT8 Alignment;
    UINT8 Reserved[3];
    EFI_GUID TypeGuid;
    EFI_GUID AddressAbstractionGuid;
    UINT64 SPALocationCookie;
    UINT8 Reserved1[80];
    UINT64 Checksum;
};

Uuid
Unique Label Identifier UUID per RFC 4122. This field provides two functions. First, the namespace is associated with a UUID that software can use to uniquely identify it and providing a way for the namespace to be matched up with applications using it. Second, when multiple labels are required to describe a namespace, the UUID is the mechanism used to group the labels together. See the additional descriptions below describing the process for grouping the labels together by UUID, checking for missing labels, recovering from partial label changes, etc.

Name
NULL-terminated string using UTF-8 character formatting. The Name field is optionally used by software to store a more friendly name for the namespace. When this field is unused, it contains zeros.

If there is a name for a Local Namespace, as indicated by the EFI_NVDIMM_LABEL_FLAGS_LOCAL Flags, the name shall be stored in the first label of the set. All Name fields in subsequent labels for that Local Namespace are ignored. The Name field can be set at label creation time, or updated by following the rules in the additional descriptions below.

Flags
Boolean attributes of this namespace. See the additional description below on the use of the flags. The following values are defined:

EFI_NVDIMM_LABEL_FLAGS_ROLABEL - The label is read-only. This indicates the namespace is exported to a domain where configuration changes to the label are not allowed, such as a virtual machine. This indicates that device software and manageability software should refuse to make changes to the labels. This is a not a security mechanism, but a usability feature instead. In cases where EFI_NVDIMM_LABEL_FLAGS_ROLABEL is set, such as virtual machine guests, attempting to make configuration changes that affect the labels will fail (i.e. because the VM guest is not in a position to make the change correctly). For these cases, the VMM can set the EFI_NVDIMM_LABEL_FLAGS_ROLABEL bit on the label exposed to the guest to provide a better user experience where manageability refuses to make changes with a
friendlier error message.

**EFI_NVDIMM_LABEL_FLAGS_LOCAL** - When set, the complete label set is local to a single NVDIMM Label Storage Area. When clear, the complete label set is contained on multiple NVDIMM Label Storage Areas. If NLlabel is 1, then setting this flag is optional and it is implied that the **EFI_NVDIMM_LABEL_FLAGS_LOCAL** flag is set, as the complete label set is local to a single NVDIMM Label Storage Area.

**EFI_NVDIMM_LABEL_FLAGS_UPDATING** - When set, the label set is being updated. During an operation that may require updating multiple Label Storage Areas, the **EFI_NVDIMM_LABEL_FLAGS_UPDATING** flag is used to make the update atomic across interruptions. Updates happen in two phases, first writing the label with the **EFI_NVDIMM_LABEL_FLAGS_UPDATING** flag set, second writing the updated label without the **EFI_NVDIMM_LABEL_FLAGS_UPDATING** flag. As described in Recovery Steps for a Non-Local Label Set Description, this allows recovery actions during software initialization to either roll back or roll forward the multiple Label Storage Area changes. If **EFI_NVDIMM_LABEL_FLAGS_LOCAL** is set, the labels are contained in a single Label Storage Area and there is no need to set **EFI_NVDIMM_LABEL_FLAGS_UPDATING**, since the label can be written in one atomic operation.

**EFI_NVDIMM_LABEL_FLAGS_SPACOOKIE_BOUND** - When set, the SPA Location Cookie in the namespace label is valid and should match the current value in the NFIT SPA Range Structure.

**NLlabel**

Total number of labels describing this namespace. The NLlabel field contains the number of labels required to describe a namespace.

**Position**

Position of this label in list of labels for this namespace. See NLlabel description above. In the non-local case, each label is numbered as to its position in the list of labels using the Position field. For example, the common case where a namespace requires exactly one label, NLlabel will be 1 and Position will be 0. If a namespace is built on an Interleave Set that spans multiple Label Storage Areas, each Label Storage Area will contain a label with increasing Position values to show each labels position in the set. For Local Namespaces, NLlabel is valid only for the first label (lowest DPA) and position shall be 0 for that label. As part of organizing and validating the labels, SW shall have organized the labels from lowest to highest DPA so the first label in that ordered list of labels will have the lowest DPA. Position and NLlabel for all subsequent labels in that namespace shall be set to 0xFF. See the Local Namespace description in the Validating Labels Description section for details.

**SetCookie**

Interleave Sets and the NVDIMMs they contain are defined in the NFIT and the Uuid in the label is used to uniquely identify each interleave set. The SetCookie is utilized by SW to perform consistency checks on the Interleave Set to verify the current physical device configuration matches the original physical configuration when the labels were created for the set. The label is considered invalid if the actual label set cookie doesn't match the cookie stored here. The SetCookie field in each label for that namespace is derived from data in the NVDIMM’s Serial Presence Detect (SPD). See the SetCookie Description section below for SetCookie details. For references to the JEDEC SPD annex see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “JEDEC SPD Annex”

**LbaSize**

This is the default logical block size in bytes and may be superseded by a block size that is specified in the AbstractionGuid.

- A non-zero value indicates the logical block size that is being emulated.
- A value of zero indicates an unspecified size and its meaning is implementation specific

**Dpa**

The DPA is the Device Physical Address where the NVM contributing to this namespace begins on this NVDIMM.
The extent of the DPA contributed by this label.

Current slot in the Label Storage Area where this label is stored.

Alignment hint used to advertise the preferred alignment of the data from within the namespace defined by this label.

Shall be 0

Range Type GUID that describes the access mechanism for the specified DPA range. The GUIDs utilized for the type are defined in the ACPI 6.0 specification in the NVDIMM FW Interface Table (NFIT) chapter. Those values are utilized here to describe the Type of namespace the label is describing. See the Address Range Type GUID field described in the System Physical Address (SPA) Range Structure table.

Identifies the address abstraction mechanism for this namespace. A value of 0 indicates no mechanism used.

When creating the label, this value is set to the value from the NFIT SPA Range Structure if the SPALocation-Cookie flag (bit 2) is set. If EFI_NVDIMM_LABEL_FLAGS_SPACOOKIE_BOUND is set, the SPALocation-Cookie value stored in the namespace label should match the current value in the NFIT SPA Range Structure. Otherwise, the data may not be read correctly.

Shall be 0

64-bit Fletcher64 checksum of all fields in this Label. This field is considered zero when the checksum is computed. For references to the Fletcher64 algorithm see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Fletcher64 Checksum Algorithm”

typedef struct EFI_NVDIMM_LABEL_SET_COOKIE_INFO {
    typedef struct EFI_NVDIMM_LABEL_SET_COOKIE_MAP {
        UINT64 RegionOffset;
        UINT32 SerialNumber;
        UINT16 VendorId;
        UINT16 ManufacturingDate;
        UINT8 ManufacturingLocation;
        UINT8 Reserved[31];
    } Mapping[NumberOfNvdimmsInInterleaveSet];
} SetCookie Definition

The number of NVDIMMs in the interleave set. This is 1 if EFI_NVDIMM_LABEL_FLAGS_LOCAL Flags is set indicating a Local Namespaces.

The Region Offset field from the ACPI NFIT NVDIMM Region Mapping Structure for a given entry. This determines the entry’s position in the set. Region offset is 0 for Local Namespaces.

The serial number of the NVDIMM, assigned by the module vendor. This field shall be set to the value of the NVDIMM Serial Presence Detect (SPD) Module Serial Number field defined by JEDEC with byte 0 set to SPD
byte 325, byte 1 set to SPD byte 326, byte 2 set to SPD byte 327, and byte 3 set to SPD byte 328. For references to the JEDEC SPD annex see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “JEDEC SPD Annex”

VendorId
The identifier indicating the vendor of the NVDIMM. This field shall be set to the value of the NVDIMM SPD Module Manufacturer ID Code field with byte 0 set to DDR4 SPD byte 320 and byte 1 set to DDR4 SPD byte 321. For references to the JEDEC SPD annex see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “JEDEC SPD Annex”

ManufacturingDate
The manufacturing date of the NVDIMM, assigned by the module vendor. This field shall be set to the value of the NVDIMM SPD Module Manufacturing Date field with byte 0 set to SPD byte 323 and byte 1 set to SPD byte 324. For references to the JEDEC SPD annex see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “JEDEC SPD Annex”

ManufacturingLocation
The manufacturing location from for the NVDIMM, assigned by the module vendor. This field shall be set to the value of the NVDIMM SPD Module Manufacturing Location field (SPD byte 322). For references to the JEDEC SPD annex see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “JEDEC SPD Annex”

Reserved
Shall be 0

SetCookie Description
This value is used to detect a change in the set configuration that has rendered existing data invalid and otherwise validates that the namespace belongs to a given NVDIMM. For each set create a data structure of the form EFI_NVDIMM_LABEL_SET_COOKIE_INFO. The SetCookie is then calculated by sorting the Mapping[] array by RegionOffset and then taking the Fletcher64 sum of the total EFI_NVDIMM_LABEL_SET_COOKIE_INFO structure. For references to the Fletcher64 algorithm see “Links to UEFI-Related Documents” (http://uefi.org/uefi ) under the heading “Fletcher64 Checksum Algorithm”

13.19.5 Label Storage Area Description

Namespaces are defined by Labels which are stored in the Label Storage Area(s) and accessed via means described in the Label Rules Description.

The figure below shows the organization of the Label Storage Area. A header called the Index Block appears twice at the top of the Label Storage Area. This provides a powerfail-safe method for updating the information in the Label Storage Area by alternating between the two Index Blocks when writing (more details on this mechanism below).

Following the Index Blocks, an array for storing labels takes up the remainder of the Label Storage Area. The size of the Label Storage Area is NVDIMM implementation specific. The Index Blocks contain a bitmap which indicates which label slots are currently free and which are in use. The same powerfail-safe mechanism used for updating the Index Blocks covers the update of labels in the Label Storage Area.

The powerfail-safe update mechanism uses the principle of avoiding writes to active metadata. Instead, a shadow copy is updated and checksums and sequence numbers are used to make the last written copy active (a complete description of this mechanism is in Updating an Existing Label Description).

Initial Label Storage Area Configuration

The size of an Index Block depends on how many label slots fit into the Label Storage Area. The minimum size of an Index Block is 256 bytes and the size must be a multiple of EFI_NVDIMM_LABEL_INDEX_ALIGN bytes. As necessary, padding with zero bytes at the end of the structure is used to meet these size requirements. The minimum size of the Label Storage Area is large enough to hold 2 index blocks and 2 labels. As an example, for Label Storage Areas of 128KB and 256KB, the corresponding Index Block size is 256 or 512 bytes:
Before Index Blocks and labels can be utilized, the software managing the Label Storage Area must determine the total number of labels that will be supported and utilizing the description above, calculate the size of the Index Blocks required. Once the initial Label Storage Area is written with the first Index Blocks (typically done when the first Label needs to be written), the total number of slots is fixed and this initial calculation is not performed again.

**Label Description**

Each slot in the Label Storage Area is either free or contains an active label.

In the cases where multiple labels are used to describe a namespace, the label fields NLabel and Position provide an ordering (“label one of two, label two of two”) so that incomplete label sets can be detected.

A namespace is described by one or more labels. Local namespaces describe one or more device physical address ranges from a single NVDIMM while non-Local namespaces describe a single SPA range that may have contributions from 2 or more NVDIMMs. The number of labels needed to describe a non-Local namespace is equal to the number of NVDIMMs contributing to the SPA range, 1 per-NVDIMM. For a Local namespace any number, up to the max number
of labels supported by the Index Block / Label Storage Area, of device physical address ranges in the given NVDIMM can be described.

Label Rules Description

All the algorithms related to labels in this specification assume single-threaded / non-entrant execution. The algorithm for updating labels guarantees that at least one slot in the Label Storage Area will be free, ensuring it is always possible to update labels using this method.

Software shall maintain the following invariants to use the on-media data structures correctly and to inter-operate with other software components.

At all times, the following must be TRUE:

• The size of the Label Storage Area is known (this must be TRUE even if no namespace metadata has been written yet). The Label Storage Area size is queried from the NVDIMM.

• The Label Storage Area either contains no valid Index Blocks, indicating there are no labels on the NVDIMM (all slots free), or the validation rules below produce a single, valid, Index Block.

• 2 free slots are required in order to add a Label. Having only a single free slot indicates that no more labels can be added. Only fully written, active labels, and full-written labels with the EFI_NVDIMM_LABEL_FLAGS_UPDATING flag are marked in-use by the Index Block.

• Write to active label slots are not allowed; all updates to labels must be done by writing to free slots and then updating the Index Block to make them active.

Validating Index Blocks Description

The following tests shall pass before software considers Index Blocks valid:

• Both Index Blocks must be read successfully from the Label Storage Area.

• Any Index Block with an incorrect Sig field is invalid.

• Any Index Block with an incorrect Checksum is invalid.

• Any Index Block with an incorrect MyOff, MySize, or OtherOff field is invalid.

• Any Index Block with a sequence number Seq of zero is invalid.

• If two valid Index Blocks remain, after passing all the above tests, and their sequence numbers match, the Index Block at the lower offset in the Label Storage Area is invalid.

• If two Index Blocks remain, after passing all the above tests, their sequence numbers are compared and the block whose sequence number is the predecessor of the other (immediately counter-clockwise to it, as shown in Figure Z: Cyclic Sequence Numbers in Label Index Block in the Seq description) is invalid.

• If one Index Block remains, that is the current, valid block and software should make note that the next update to the Index Block will write the other Index Block. However, if no valid Index Blocks remain, all slots are considered free and the next update to the index will write to the lower-addressed block location (i.e. the start of the Label Storage Area).

Validating Labels Description

The following tests shall pass before software considers individual Labels slots valid:

• The corresponding free bit for the label Slot in the Index Block Free array must be clear (i.e. label slot is active).

• The label Checksum shall validate.

• The Slot value in the Label shall match the logical slot location of the Label.

• The SetCookie field in the label matches the expected value as described in SetCookie Definition.
• The address range type GUID TypeGuid shall match the System Physical Address Range Structure that describes the access mechanism for this namespace. For Hardware Block Namespaces it shall match the GUID for the NVDIMM Block Data Window Region.

For Local Namespaces:

• If 2 or more labels share the same Dpa value, all labels with the duplicated value are considered invalid.

• The count of all valid labels for a given namespace Uuid shall match the NLabel value in the first label.

• The first label, the label with the lowest Dp a value, shall have Position 0 and non-zero NLabel value.

• All labels other than the first have Position and NLabel set to 0xff.

Reading Labels Description

For a given NVDIMM, the following steps are used to read one or more labels for validation and namespace assembly:

Pre-condition: both Index Blocks have been read and the rules in Validating Index Blocks Description have been followed to determine the current valid Index Block.

• Check that the label at a given slot is active. Specifically bit N is clear in the Free bitmask field where N corresponds to the logical slot number label.

• Read the label in that slot at the offset given by: 
  \[ (2 \times \text{sizeof(EFI_NVDIMM_LABEL_INDEX_BLOCK)} + \text{slot} \times \text{sizeof(EFI_NVDIMM_LABEL)}) \]

Recovery Steps for a Non-Local Label Set Description

Given that a non-Local Label set potentially spans multiple Label Storage Areas for multiple NVDIMMs it is not possible to guarantee that the set is updated atomically with respect to unexpected system interruption. Recovery shall be performed before validating the set to roll the set forward to a consistent state or invalidate / free the label slots corresponding to an inconsistent state. Note that individual Index Block updates are safe with respect to unexpected system interruption given the sequence number mechanism for indicating the currently active Index Block.

The sequence below describes how the EFI_NVDIMM_LABEL_FLAGS_UPDATING flag is used when validating a non-Local Label Set.

• Pre-condition: The labels have been read.

• For each set of labels with the same UUID, if no labels in the set are found with the EFI_NVDIMM_LABEL_FLAGS_UPDATING flag set, then no recovery is required for that set.

• For the sets where EFI_NVDIMM_LABEL_FLAGS_UPDATING appear at least once, if the set is incomplete (some NVDIMMs in the set do not contain a label in the Label Storage Area with the UUID), the recovery action is to roll back the interrupted create operation that left this state. I.e. for each NVDIMM in the set containing a label with the given UUID, delete the label.

• For a set where EFI_NVDIMM_LABEL_FLAGS_UPDATING appears at least once and the set is otherwise complete (each NVDIMM in the Interleave Set contains a label with the UUID, some with EFI_NVDIMM_LABEL_FLAGS_UPDATING set, some with EFI_NVDIMM_LABEL_FLAGS_UPDATING clear), the recovery action is to roll forward the change that was interrupted. I.e. for each NVDIMM in the set if EFI_NVDIMM_LABEL_FLAGS_UPDATING is set, write an updated label with EFI_NVDIMM_LABEL_FLAGS_UPDATING clear and with the name field copied from the first label in the set (the label with a Position field of 0).

Recovery Steps for a Local Label Set Description

Given that a Local Label set is always contained in a single Label Storage Area for a single NVDIMM, labels are added/updated atomically, as long as there is a free Label available as outlined in Label Storage Area Description and Label Description. EFI_NVDIMM_LABEL_FLAGS_UPDATING should not be set for Local sets and no additional recovery is required.

Assembling Labels into Complete Sets Description
After collecting a set of labels corresponding to a given UUID and performing the recovery actions on the set, software shall follow the steps in this section to assemble complete sets of labels representing usable namespaces:

1. Precondition: Labels have been read and the recovery actions have been taken.
2. For each set of labels with the same UUID
   a. If the set describes a non-Local namespace, it is considered complete if labels with unique Position fields are found for every position from 0 to \( N_{Label}-1 \).
   b. If the set describes a Local namespace, it is considered complete if a valid first label is found, according to the validation rules, and the number of labels in the set matches \( N_{Label} \).

The recovery action for the case where software finds incomplete namespaces is implementation specific.

### Updating an Existing Label Description

Updating an existing label in the Label Storage Area requires the software to follow these steps:

1. Pre-conditions: the software has an updated label constructed to be written to a specific NVDIMM’s Label Storage Area. There is at least 1 free slot in the Label Storage Area Free bitmask.
2. The software chooses a free slot from the Index Block, fills in that slot number in the label’s Slot field
3. The software writes the updated label to that slot in the Label Storage Area
4. The software updates the Index Block by taking the current Index Block, setting the appropriate bit in the Free field to make the old version of the label inactive and clearing the appropriate bit in the Free field to make the new version active, incrementing the sequence number as shown in Figure Z: Cyclic Sequence Numbers in Label Index Block in the Seq description, and then writing the Index Block over the inactive Index Block location (making this location the new active Index Block if the write succeeds)

### Deleting a Label Description

The software updates the Index Block by taking the current active Index Block, setting the appropriate bit in the Free field to make the deleted label inactive, incrementing the sequence number as shown in Figure Z: Cyclic Sequence Numbers in Label Index Block in the Seq description, and then writing the new Index Block over the inactive Index Block location (making this location the new active Index Block if the write succeeds)

### Creating Namespaces Description

Namespace creation procedures are different for Local vs non-Local namespaces. A Local namespace is created from 1 or more DPA ranges of a single NVDIMM, while a non-Local namespace is created from a single range contributed from multiple NVDIMMs. Both procedures share a common flow for establishing new labels in an Index Block.

### Writing New Labels Description

Transitioning a label slot from free to active shall follow this sequence:

1. Pre-conditions: the software has a new label constructed to be written to a specific NVDIMM’s Label Storage Area. Because of the free Label rules outlined in Label Storage Area Description and Label Description, there are at least 2 free slots in the Label Storage Area as described in the Label Rules Description and Label Description sections. Choose a free slot from the Index Block, fills in that slot number in the label’s Slot field
2. Write the new label to that slot in the Label Storage Area
3. Update the Index Block by taking the current Index Block, clearing the appropriate bit in the Free field, incrementing the sequence number as shown in Figure Z: Cyclic Sequence Numbers in Label Index Block in the Seq description, and then writing the Index Block over the inactive Index Block location (making this location the new active Index Block if the write succeeds)
Creating a Non-Local Namespace

When creating a new Non-Local Namespace, the software shall follow these steps:

1. Pre-conditions: the labels to be written to each NVDIMM contributing to the namespace have been constructed, each with a unique Position field from 0 to NLabel−1, and all labels with the same new UUID. All Index Blocks involved have at least 2 label slots free as described in the Label Rules Description and Label Description sections.

2. For each label in the set, the label is written with the EFI_NVDIMM_LABEL_FLAGS_UPDATING flag set, using the flow outlined in Writing New Labels Description to its corresponding NVDIMM/Label Storage Area.

3. For each label in the set, the label is updated with the same contents as the previous step, but with the EFI_NVDIMM_LABEL_FLAGS_UPDATING flag clear, using the flow outlined in Updating an Existing Label Description.

In the case of an unexpected system interruption, the above flows leave either a partial set of labels, all with the new UUID, with the EFI_NVDIMM_LABEL_FLAGS_UPDATING flag set, or a complete set of labels is left where some of them have the EFI_NVDIMM_LABEL_FLAGS_UPDATING flag set. The recovery steps in Recovery Steps for a Non-Local Label Set Description comprehend these two cases so that software can determine whether the set is consistent or needs to be invalidated.

Creating a Local Namespace

Updating labels that are all on the same NVDIMM is atomic with respect to system interruption by nature of the Index Block update rules. Since Local namespaces reside on a single NVDIMM, the EFI_NVDIMM_LABEL_FLAGS_UPDATING flag and multi-pass update described in the previous section are not used. Software creating new Local namespaces shall follow these steps:

1. Pre-conditions: the labels to be written to the NVDIMM Label Storage Area have been constructed, whereby Position, NLabel and SetCookie adhere to the validation rules described earlier, and all labels share the same UUID. The Index Blocks involved have at least NLabel + 1 label slots free, so that after the new labels are written, it will have at least 1 free label slot left.

All labels are written to free slots and made active in one step using steps similar to the flow described above in Writing New Labels Description:

a. Free slots are identified using the current Index Block, the Slot field in each label is updated accordingly
b. All new labels are written into their free slots
c. The new Index Block is constructed so the new label slots are no longer marked free, the sequence number is advanced as shown in Figure Z: Cyclic Sequence Numbers in Label Index Block in the Seq description, and then the new Index Block is written over the inactive Index Block location (making this location the new active Index Block if the write succeeds)

13.19.5.1 Updating the Name of a Namespace Description

Updating Local Labels

When updating the name on a Local set the sequence outlined in Writing New Labels Description must be followed where the Name is updated before writing the updated Label.

Updating Non Local Labels

To update the Name field associated with a non-Local Namespace, the software must follow these steps:

1. Pre-conditions: the namespace must already exist. Each NVDIMM in the namespace must have at least 1 free slot.
2. For each NVDIMM in the namespace, the label on that NVDIMM is updated with a label with the new Name field and the EFI_NVDIMM_LABEL_FLAGS_UPDATING flag set. The “for each NVDIMM” operation in this step must start with the NVDIMM containing the label whose Position field is zero.

3. For each NVDIMM in the namespace, the label is updated with the same contents as the previous step, but with the EFI_NVDIMM_LABEL_FLAGS_UPDATING flag clear, using the updating an existing label flow described above in Updating an Existing Label Description.

If the above steps are interrupted unexpectedly, the recovery steps in Recovery Steps for a Non-Local Label Set Description handle the case where a Name update is incomplete and finish the update.

# 13.20 EFI UFS Device Config Protocol

## 13.20.1 EFI_UFS_DEVICE_CONFIG_PROTOCOL

### Summary
User invokes this protocol to access the UFS device descriptors/flags/attributes and configure UFS device behavior.

### GUID
```
#define EFI_UFS_DEVICE_CONFIG_GUID
{ 0xb81bfab0, 0xeb3, 0x4cf9,
{ 0x84, 0x65, 0x7f, 0xa9, 0x86, 0x36, 0x16, 0x64}}
```

### Protocol Interface Structure
```
typedef struct _EFI_UFS_DEVICE_CONFIG_PROTOCOL {
    EFI_UFS_DEVICE_CONFIG_RW_DESCRIPTOR RwUfsDescriptor;
    EFI_UFS_DEVICE_CONFIG_RW_FLAG RwUfsFlag;
    EFI_UFS_DEVICE_CONFIG_RW_ATTRIBUTE RwUfsAttribute;
} EFI_UFS_DEVICE_CONFIG_PROTOCOL;
```

### Members
- **RwUfsDescriptor**
  Read or write specified device descriptor of a UFS device.
- **RwUfsFlag**
  Read or write specified flag of a UFS device.
- **RwUfsAttribute**
  Read or write specified attribute of a UFS device.

### Description
This protocol aims at defining a standard interface for UEFI drivers and applications to access UFS device descriptors/flags/attributes and configure the UFS device behavior.
13.20.2 EFI_UFS_DEVICE_CONFIG_PROTOCOL.RwUfsDescriptor()

Summary
This function is used to read or write specified device descriptor of a UFS device.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_UFS_DEVICE_CONFIG_RW_DESCRIPTOR) (  
    IN EFI_UFS_DEVICE_CONFIG_PROTOCOL *This,
    IN BOOLEAN Read,
    IN UINT8 DescId,
    IN UINT8 Index,
    IN UINT8 Selector,
    IN OUT UINT8 Descriptor,
    IN OUT UINT32 *DescSize,
);
```

Parameters

This
The pointer to the EFI_UFS_DEVICE_CONFIG_PROTOCOL instance.

Read
The boolean variable to show r/w direction.

DescId
The ID of device descriptor.

Index
The Index of device descriptor.

Selector
The Selector of device descriptor.

Descriptor
The buffer of device descriptor to be read or written.

DescSize
The size of device descriptor buffer. On input, the size, in bytes, of the data buffer specified by Descriptor. On output, the number of bytes that were actually transferred.

Description
The RwUfsDescriptor function is used to read/write UFS device descriptors. The consumer of this API is responsible for allocating the data buffer pointed by Descriptor.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device descriptor is read/written successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL or Descriptor is NULL or DescSize is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DescId, Index and Selector are invalid combination to point to a type of UFS device descriptor.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device descriptor is not read/written successfully.</td>
</tr>
</tbody>
</table>
13.20.3 EFI_UFSDEVICE_CONFIG_PROTOCOL.RwUfsFlag()

Summary
This function is used to read or write specified flag of a UFS device.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_UFSDEVICE_CONFIG_RW_FLAG) (  
    IN EFI_UFSDEVICE_CONFIG_PROTOCOL *This,
    IN BOOLEAN Read,
    IN UINT8 FlagId,
    IN OUT UINT8 *Flag,
);  

Parameters
This
The pointer to the EFI_UFSDEVICE_CONFIG_PROTOCOL instance.
Read
The boolean variable to show r/w direction.
FlagId
The ID of flag to be read or written.
Flag
The buffer to set or clear flag.

Description
The RwUfsFlag function is used to read/write UFS flag descriptors. The consumer of this API is responsible for allocating the buffer pointed by Flag. The buffer size is 1 byte as UFS flag descriptor is just a single Boolean value that represents a TRUE or FALSE, ‘0’ or ‘1’, ON or OFF type of value.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The flag descriptor is set/clear successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL or Flag is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>FlagId is an invalid UFS flag ID.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The flag is not set/clear successfully.</td>
</tr>
</tbody>
</table>

13.20.4 EFI_UFSDEVICE_CONFIG_PROTOCOL.RwUfsAttribute()

Summary
This function is used to read or write specified attribute of a UFS device.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_UFSDEVICE_CONFIG_RW_ATTRIBUTE) (  
    IN EFI_UFSDEVICE_CONFIG_PROTOCOL *This,
    IN BOOLEAN Read,
    (continues on next page)
IN UINT8 AttrId,
IN UINT8 Index,
IN UINT8 Selector,
IN OUT UINT8 *Attribute,
IN OUT UINT32 *AttrSize,
);

Parameters

This
The pointer to the EFI_UFS_DEVICE_CONFIG_PROTOCOL instance.

Read
The boolean variable to show r/w direction.

AttrId
The ID of Attribute.

Index
The Index of Attribute.

Selector
The Selector of Attribute.

Attribute
The buffer of Attribute to be read or written.

AttrSize
The size of Attribute buffer. On input, the size, in bytes, of the data buffer specified by Attribute. On output, the number of bytes that were actually transferred.

Description
The RwUfsAttribute function is used to read/write UFS attributes. The consumer of this API is responsible for allocating the data buffer pointed by Attribute.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The attribute is read/written successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL or Attribute is NULL or AttrSize is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>AttrId, Index and Selector are invalid combination to point to a type of UFS attribute.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The attribute is not read/written successfully.</td>
</tr>
</tbody>
</table>
CHAPTER
FOURTEEN

PROTOCOLS — PCI BUS SUPPORT

14.1 PCI Root Bridge I/O Support

This section and the following one (Section 14.2) describe the PCI Root Bridge I/O Protocol. This protocol provides an I/O abstraction for a PCI Root Bridge that is produced by a PCI Host Bus Controller. A PCI Host Bus Controller is a hardware component that allows access to a group of PCI devices that share a common pool of PCI I/O and PCI Memory resources. This protocol is used by a PCI Bus Driver to perform PCI Memory, PCI I/O, and PCI Configuration cycles on a PCI bus. It also provides services to perform different types of bus mastering DMA on a PCI bus. PCI device drivers will not directly use this protocol. Instead, they will use the I/O abstraction produced by the PCI Bus Driver. Only drivers that require direct access to the entire PCI bus should use this protocol. In particular, this chapter defines functions for managing PCI buses, although other bus types may be supported in a similar fashion as extensions to this specification.

All the services described in this chapter that generate PCI transactions follow the ordering rules defined in the PCI Specification. If the processor is performing a combination of PCI transactions and system memory transactions, then there is no guarantee that the system memory transactions will be strongly ordered with respect to the PCI transactions. If strong ordering is required, then processor-specific mechanisms may be required to guarantee strong ordering. Some 64-bit systems may require the use of memory fences to guarantee ordering.

14.1.1 PCI Root Bridge I/O Overview

The interfaces provided in the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL are for performing basic operations to memory, I/O, and PCI configuration space. The system provides abstracted access to basic system resources to allow a driver to have a programmatic method to access these basic system resources.

The EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL allows for future innovation of the platform. It abstracts device-specific code from the system memory map. This allows system designers to make changes to the system memory map without impacting platform independent code that is consuming basic system resources.

A platform can be viewed as a set of processors and a set of core chipset components that may produce one or more host buses. Figure Host Bus Controllers shows a platform with \( n \) processors (CPUs in the figure), and a set of core chipset components that produce \( m \) host bridges.

Simple systems with one PCI Host Bus Controller will contain a single instance of the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL. More complex system may contain multiple instances of this protocol. It is important to note that there is no relationship between the number of chipset components in a platform and the number of EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL instances. This protocol abstracts access to a PCI Root Bridge from a software point of view, and it is attached to a device handle that represents a PCI Root Bridge. A PCI Root Bridge is a chipset component(s) that produces a physical PCI Bus. It is also the parent to a set of PCI devices that share common PCI I/O, PCI Memory, and PCI Prefetchable Memory regions. A PCI Host Bus Controller is composed of one or more PCI Root Bridges.
Fig. 14.1: Host Bus Controllers
A PCI Host Bridge and PCI Root Bridge are different than a PCI Segment. A PCI Segment is a collection of up to 256 PCI busses that share the same PCI Configuration Space. Depending on the chipset, a single EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL may abstract a portion of a PCI Segment, or an entire PCI Segment. A PCI Host Bridge may produce one or more PCI Root Bridges. When a PCI Host Bridge produces multiple PCI Root Bridges, it is possible to have more than one PCI Segment.

PCI Root Bridge I/O Protocol instances are either produced by the system firmware or by a UEFI driver. When a PCI Root Bridge I/O Protocol is produced, it is placed on a device handle along with an EFI Device Path Protocol instance. The figure below (Device Handle for a PCI Root Bridge Controller) shows a sample device handle that includes an instance of the EFI_DEVICE_PATH_PROTOCOL and the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.

Section Section 14.2 describes the PCI Root Bridge I/O Protocol in detail, and Section 14.2.19 describes how to build device paths for PCI Root Bridges. The EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL does not abstract access to the chipset-specific registers used to manage a PCI Root Bridge. This functionality is hidden within the system firmware or the driver that produces the handles that represent the PCI Root Bridges.

![Device Handle](image)

Fig. 14.2: Device Handle for a PCI Root Bridge Controller

### 14.1.2 Sample PCI Architectures

The PCI Root Bridge I/O Protocol is designed to provide a software abstraction for a wide variety of PCI architectures including the ones described in this section. This section is not intended to be an exhaustive list of the PCI architectures that the PCI Root Bridge I/O Protocol can support. Instead, it is intended to show the flexibility of this protocol to adapt to current and future platform designs.

See Desktop System with One PCI Root Bridge shows an example of a PCI Host Bus with one PCI Root Bridge. This PCI Root Bridge produces one PCI Local Bus that can contain PCI Devices on the motherboard and/or PCI slots. This would be typical of a desktop system. A higher end desktop system might contain a second PCI Root Bridge for AGP devices. The firmware for this platform would produce one instance of the PCI Root Bridge I/O Protocol.

Figure Server System with Four PCI Root Bridges shows an example of a larger server with one PCI Host Bus and four PCI Root Bridges. The PCI devices attached to the PCI Root Bridges are all part of the same coherency domain. This means they share a common PCI I/O Space, a common PCI Memory Space, and a common PCI Prefetchable Memory Space. Each PCI Root Bridge produces one PCI Local Bus that can contain PCI Devices on the motherboard or PCI slots. The firmware for this platform would produce four instances of the PCI Root Bridge I/O Protocol.

The Figure Server System with Two PCI Segments, below, shows an example of a server with one PCI Host Bus and two PCI Root Bridges. Each of these PCI Root Bridges is a different PCI Segment which allows the system to have up to 512 PCI Buses. A single PCI Segment is limited to 256 PCI Buses. These two segments do not share the same PCI
14.1. PCI Root Bridge I/O Support

Fig. 14.3: Desktop System with One PCI Root Bridge

Fig. 14.4: Server System with Four PCI Root Bridges
Configuration Space, but they do share the same PCI I/O, PCI Memory, and PCI Prefetchable Memory Space. This is why it can be described by a single PCI Host Bus. The firmware for this platform would produce two instances of the PCI Root Bridge I/O Protocol.

The Figure, Server System with Two PCI Host Buses, below, shows a server system with two PCI Host Buses and one PCI Root Bridge per PCI Host Bus. This system supports up to 512 PCI Buses, but the PCI I/O, PCI Memory Space, and PCI Prefetchable Memory Space are not shared between the two PCI Root Bridges. The firmware for this platform would produce two instances of the PCI Root Bridge I/O Protocol.

14.2 PCI Root Bridge I/O Protocol

This section provides detailed information on the PCI Root Bridge I/O Protocol and its functions.

14.2.1 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL

Summary

Provides the basic Memory, I/O, PCI configuration, and DMA interfaces that are used to abstract accesses to PCI controllers behind a PCI Root Bridge Controller.

GUID

```
#define EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_GUID
{0x2F707EBB,0x4A1A,0x11d4,}
{0x9A,0x38,0x00,0x90,0x27,0x3F,0xC1,0x4D}
```
Protocol Interface Structure

typedef struct _EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL {
  EFI_HANDLE ParentHandle;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_POLL_IO_MEM PollMem;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_POLL_IO_MEM PollIo;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ACCESS Mem;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ACCESS Io;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ACCESS Pci;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_COPY_MEM CopyMem;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_MAP Map;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_UNMAP Unmap;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ALLOCATE_BUFFER AllocateBuffer;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_FREE_BUFFER FreeBuffer;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_FLUSH Flush;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_GET_ATTRIBUTES GetAttributes;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_SET_ATTRIBUTES SetAttributes;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_CONFIGURATION Configuration;
  UINT32 SegmentNumber;
} EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL;

Parameters

ParentHandle

The EFI_HANDLE of the PCI Host Bridge of which this PCI Root Bridge is a member.
**PollMem**
Polls an address in memory mapped I/O space until an exit condition is met, or a timeout occurs. See the `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.PollMem()` function description.

**PollIo**
Polls an address in I/O space until an exit condition is met, or a timeout occurs. See the `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.PollIo()` function description.

**Mem.Read**
Allows reads from memory mapped I/O space. See the `Mem.Read()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Mem.Read()` function description.

**Mem.Write**
Allows writes to memory mapped I/O space. See the `Mem.Write()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Mem.Write()` function description.

**Io.Read**
Allows reads from I/O space. See the `Io.Read()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Io.Read()` function description.

**Io.Write**
Allows writes to I/O space. See the `Io.Write()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Io.WRITE()` function description.

**Pci.Read**
Allows reads from PCI configuration space. See the `Pci.Read()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Pci.Read()` function description.

**Pci.Write**
Allows writes to PCI configuration space. See the `Pci.Write()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Pci.Write()` function description.

**CopyMem**
Allows one region of PCI root bridge memory space to be copied to another region of PCI root bridge memory space. See the `CopyMem()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.CopyMem()` function description.

**Map**
Provides the PCI controller-specific addresses needed to access system memory for DMA. See the `Map()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Map()` function description.

**Unmap**
Releases any resources allocated by Map(). See the `Unmap()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Unmap()` function description.

**AllocateBuffer**
Allocates pages that are suitable for a common buffer mapping. See the `AllocateBuffer()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.AllocateBuffer()` function description.

**FreeBuffer**
Free pages that were allocated with AllocateBuffer(). See the `FreeBuffer()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.FreeBuffer()` function description.

**Flush**
Flushes all PCI posted write transactions to system memory. See the `Flush()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Flush()` function description.

**GetAttributes**
Gets the attributes that a PCI root bridge supports setting with `SetAttributes()` and the attributes that a PCI root bridge is currently using. See the `GetAttributes()` `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.GetAttributes()` function description.
SetAttributes
Sets attributes for a resource range on a PCI root bridge. See EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.SetAttributes() function description.

Configuration
Gets the current resource settings for this PCI root bridge. See the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Configuration() function description.

SegmentNumber
The segment number that this PCI root bridge resides.

Related Definitions

typedef enum {
  EfiPciWidthUint8,
  EfiPciWidthUint16,
  EfiPciWidthUint32,
  EfiPciWidthUint64,
  EfiPciWidthFifoUint8,
  EfiPciWidthFifoUint16,
  EfiPciWidthFifoUint32,
  EfiPciWidthFifoUint64,
  EfiPciWidthFillUint8,
  EfiPciWidthFillUint16,
  EfiPciWidthFillUint32,
  EfiPciWidthFillUint64,
  EfiPciWidthMaximum
} EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH;

typedef EFI_STATUS (EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_POLL_IO_MEM) (
  IN struct EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,
  IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,
  IN UINT64 Address,
  IN UINT64 Mask,
  IN UINT64 Value,
  IN UINT64 Delay,
  OUT UINT64 *Result
);

typedef EFI_STATUS (EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM) (}
IN UINT64 Address,
IN UINTN Count,
IN OUT VOID *Buffer
);

//******************************************************************************
// EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ACCESS
//******************************************************************************
typedef struct {
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM Read;
  EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM Write;
} EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ACCESS;

//******************************************************************************
// EFI PCI Root Bridge I/O Protocol Attribute bits
//******************************************************************************
#define EFI_PCI_ATTRIBUTE_ISA_MOTHERBOARD_IO 0x0001
#define EFI_PCI_ATTRIBUTE_ISA_IO 0x0002
#define EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO 0x0004
#define EFI_PCI_ATTRIBUTE_VGA_MEMORY 0x0008
#define EFI_PCI_ATTRIBUTE_VGA_IO 0x0010
#define EFI_PCI_ATTRIBUTE_IDE_PRIMARY_IO 0x0020
#define EFI_PCI_ATTRIBUTE_IDE_SECONDARY_IO 0x0040
#define EFI_PCI_ATTRIBUTE_MEMORY_WRITE_COMBINE 0x0080
#define EFI_PCI_ATTRIBUTE_MEMORY_CACHED 0x0800
#define EFI_PCI_ATTRIBUTE_MEMORY_DISABLE 0x1000
#define EFI_PCI_ATTRIBUTE_DUAL_ADDRESS_CYCLE 0x8000
#define EFI_PCI_ATTRIBUTE_ISA_IO_16 0x10000
#define EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO_16 0x20000
#define EFI_PCI_ATTRIBUTE_VGA_IO_16 0x40000

EFI_PCI_ATTRIBUTE_ISA_IO_16
If this bit is set, then the PCI I/O cycles between 0x100 and 0x3FF are forwarded onto a PCI root bridge using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for legacy ISA devices onto a PCI root bridge. This bit may not be combined with EFI_PCI_ATTRIBUTE_ISA_IO.

EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO_16
If this bit is set, then the PCI I/O write cycles for 0x3C6, 0x3C8, and 0x3C9 are forwarded onto a PCI root bridge using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O write cycles to the VGA palette registers onto a PCI root bridge. This bit may not be combined with EFI_PCI_ATTRIBUTE_VGA_IO or EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO.

EFI_PCI_ATTRIBUTE_VGA_IO_16
If this bit is set, then the PCI I/O cycles in the ranges 0x3B0-0x3BB and 0x3C0-0x3DF are forwarded onto a PCI root bridge using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for a VGA controller onto a PCI root bridge. This bit may not be combined with EFI_PCI_ATTRIBUTE_VGA_IO or EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO. Because EFI_PCI_ATTRIBUTE_VGA_IO_16 also includes the I/O range described by EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO_16, the EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO_16 bit is ignored if EFI_PCI_ATTRIBUTE_VGA_IO_16 is set.

EFI_PCI_ATTRIBUTE_ISA_MOTHERBOARD_IO

14.2. PCI Root Bridge I/O Protocol
If this bit is set, then the PCI I/O cycles between 0x00000000 and 0x000000FF are forwarded onto a PCI root bridge. This bit is used to forward I/O cycles for ISA motherboard devices onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_ISA_IO
If this bit is set, then the PCI I/O cycles between 0x100 and 0x3FF are forwarded onto a PCI root bridge using a 10-bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and address bits 16..31 must be zero. This bit is used to forward I/O cycles for legacy ISA devices onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_VGA_PALETTE_IO
If this bit is set, then the PCI I/O write cycles for 0x3C6, 0x3C8, and 0x3C9 are forwarded onto a PCI root bridge using a 10 bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and address bits 16..31 must be zero. This bit is used to forward I/O write cycles to the VGA palette registers onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_VGA_MEMORY
If this bit is set, then the PCI memory cycles between 0xA0000 and 0xBFFFF are forwarded onto a PCI root bridge. This bit is used to forward memory cycles for a VGA frame buffer onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_VGA_IO
If this bit is set, then the PCI I/O cycles in the ranges 0x3B0-0x3BB and 0x3C0-0x3DF are forwarded onto a PCI root bridge using a 10-bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and the address bits 16..31 must be zero. This bit is used to forward I/O cycles for a VGA controller onto a PCI root bridge. Since EFI_PCI_ATTRIBUTE_ENABLE_VGA_IO also includes the I/O range described by EFI_PCI_ATTRIBUTE_ENABLE_VGA_PALETTE_IO, the EFI_PCI_ATTRIBUTE_ENABLE_VGA_PALETTE_IO bit is ignored if EFI_PCI_ATTRIBUTE_ENABLE_VGA_IO is set.

EFI_PCI_ATTRIBUTE_IDE_PRIMARY_IO
If this bit is set, then the PCI I/O cycles in the ranges 0x1F0-0x1F7 and 0x3F6-0x3F7 are forwarded onto a PCI root bridge using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for a Primary IDE controller onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_IDE_SECONDARY_IO
If this bit is set, then the PCI I/O cycles in the ranges 0x170-0x177 and 0x376-0x377 are forwarded onto a PCI root bridge using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for a Secondary IDE controller onto a PCI root bridge.

EFI_PCI_ATTRIBUTE_MEMORY_WRITE_COMBINE
If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is accessed in a write combining mode. By default, PCI memory ranges are not accessed in a write combining mode.

EFI_PCI_ATTRIBUTE_MEMORY_CACHED
If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is accessed in a cached mode. By default, PCI memory ranges are accessed noncached.

EFI_PCI_ATTRIBUTE_MEMORY_DISABLE
If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is disabled, and can no longer be accessed. By default, all PCI memory ranges are enabled.

EFI_PCI_ATTRIBUTE_DUAL_ADDRESS_CYCLE
This bit may only be used in the Attributes parameter to EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.AllocateBuffer(). If this bit is set, then the PCI controller that is requesting a buffer through AllocateBuffer() is capable of producing PCI Dual Address Cycles, so it is able to access a 64-bit address space. If this bit is not set, then the PCI controller that is requesting a buffer through AllocateBuffer() is not capable of producing PCI Dual Address Cycles, so it is only able to access a 32-bit address space.

//******************************************************************************
//# EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_OPERATION

(continues on next page)
typedef enum {
  EfiPciOperationBusMasterRead,
  EfiPciOperationBusMasterWrite,
  EfiPciOperationBusMasterCommonBuffer,
  EfiPciOperationBusMasterRead64,
  EfiPciOperationBusMasterWrite64,
  EfiPciOperationBusMasterCommonBuffer64,
  EfiPciOperationMaximum
} EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_OPERATION;

EfiPciOperationBusMasterRead
A read operation from system memory by a bus master that is not capable of producing PCI dual address cycles.

EfiPciOperationBusMasterWrite
A write operation to system memory by a bus master that is not capable of producing PCI dual address cycles.

EfiPciOperationBusMasterCommonBuffer
Provides both read and write access to system memory by both the processor and a bus master that is not capable of producing PCI dual address cycles. The buffer is coherent from both the processor’s and the bus master’s point of view.

EfiPciOperationBusMasterRead64
A read operation from system memory by a bus master that is capable of producing PCI dual address cycles.

EfiPciOperationBusMasterWrite64
A write operation to system memory by a bus master that is capable of producing PCI dual address cycles.

EfiPciOperationBusMasterCommonBuffer64
Provides both read and write access to system memory by both the processor and a bus master that is capable of producing PCI dual address cycles. The buffer is coherent from both the processor’s and the bus master’s point of view.

Description
The EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL provides the basic Memory, I/O, PCI configuration, and DMA interfaces that are used to abstract accesses to PCI controllers. There is one EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL instance for each PCI root bridge in a system. Embedded systems, desktops, and workstations will typically only have one PCI root bridge. High-end servers may have multiple PCI root bridges. A device driver that wishes to manage a PCI bus in a system will have to retrieve the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL instance that is associated with the PCI bus to be managed. A device handle for a PCI Root Bridge will minimally contain an EFI Device Path Protocol instance and an EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL instance. The PCI bus driver can look at the EFI_DEVICE_PATH_PROTOCOL instances to determine which EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL instance to use.

Bus mastering PCI controllers can use the DMA services for DMA operations. There are three basic types of bus mastering DMA that is supported by this protocol. These are DMA reads by a bus master, DMA writes by a bus master, and common buffer DMA. The DMA read and write operations may need to be broken into smaller chunks. The caller of EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Map() must pay attention to the number of bytes that were mapped, and if required, loop until the entire buffer has been transferred. The following is a list of the different bus mastering DMA operations that are supported, and the sequence of EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL APIs that are used for each DMA operation type. See “Related Definitions” above for the definition of the different DMA operation types.

DMA Bus Master Read Operation
• Call EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Map() for EfiPciOperationBusMasterRead or EfiPciOperationBusMasterRead64.
• Program the DMA Bus Master with the DeviceAddress returned by Map().
• Start the DMA Bus Master.
• Wait for DMA Bus Master to complete the read operation.
• Call $EFI\_PCI\_ROOT\_BRIDGE\_IO\_PROTOCOL.Unmap()$

DMA Bus Master Write Operation

• Call $EFI\_PCI\_ROOT\_BRIDGE\_IO\_PROTOCOL.Map()$ for EfiPciOperationBusMasterWrite or EfiPciOperationBusMasterRead64.
• Program the DMA Bus Master with the DeviceAddress returned by $EFI\_PCI\_IO\_PROTOCOL.Map()$
• Start the DMA Bus Master.
• Wait for DMA Bus Master to complete the write operation.
• Perform a PCI controller specific read transaction to flush all PCI write buffers (See PCI Specification Section 3.2.5.2).
• Call $EFI\_PCI\_ROOT\_BRIDGE\_IO\_PROTOCOL.Flush()$
• Call Unmap.

DMA Bus Master Common Buffer Operation

• Call $EFI\_PCI\_ROOT\_BRIDGE\_IO\_PROTOCOL.AllocateBuffer()$ to allocate a common buffer.
• Call Map() for EfiPciOperationBusMasterCommonBuffer or EfiPciOperationBusMasterCommonBuffer64.
• Program the DMA Bus Master with the DeviceAddress returned by $EFI\_PCI\_ROOT\_BRIDGE\_IO\_PROTOCOL.Map()$.
• The common buffer can now be accessed equally by the processor and the DMA bus master.
• Call Unmap().
• Call $EFI\_PCI\_ROOT\_BRIDGE\_IO\_PROTOCOL.FreeBuffer()$. 

14.2.2 $EFI\_PCI\_ROOT\_BRIDGE\_IO\_PROTOCOL.PollMem()$

Summary
Reads from the memory space of a PCI Root Bridge. Returns when either the polling exit criteria is satisfied or after a defined duration.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_POLL_IO_MEM) (  
  IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL Width,  
  IN UINT64 Address,  
  IN UINT64 Mask,  
  IN UINT64 Value,  
  IN UINT64 Delay,  
  OUT UINT64 *Result  
);  
```

Parameters
This
A pointer to the `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL`. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL` is defined in the Section `PCI Root Bridge I/O Protocol`.

**Width**
Signifies the width of the memory operations. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH` see Related Definitions in the section `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL`.

**Address**
The base address of the memory operations. The caller is responsible for aligning Address if required.

**Mask**
Mask used for the polling criteria. Bytes above Width in Mask are ignored. The bits in the bytes below Width which are zero in Mask are ignored when polling the memory address.

**Value**
The comparison value used for the polling exit criteria.

**Delay**
The number of 100 ns units to poll. Note that timer available may be of poorer granularity.

**Result**
Pointer to the last value read from the memory location.

**Description**
This function provides a standard way to poll a PCI memory location. A PCI memory read operation is performed at the PCI memory address specified by `Address` for the width specified by `Width`. The result of this PCI memory read operation is stored in `Result`. This PCI memory read operation is repeated until either a timeout of `Delay` 100 ns units has expired, or `(Result & Mask)` is equal to `Value`.

This function will always perform at least one PCI memory read access no matter how small `Delay` may be. If `Delay` is zero, then `Result` will be returned with a status of `EFI_SUCCESS` even if `Result` does not match the exit criteria. If `Delay` expires, then `EFI_TIMEOUT` is returned.

If `Width` is not `EfiPciWidthUint8`, `EfiPciWidthUint16`, `EfiPciWidthUint32`, or `EfiPciWidthUint64`, then `EFI_INVALID_PARAMETER` is returned.

The memory operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and memory width restrictions that a PCI Root Bridge on a platform might require. For example on some platforms, width requests of `EfiPciWidthUint64` are not supported.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns. However, if the memory mapped I/O region being accessed by this function has the `EFI_PCI_ATTRIBUTE_MEMORY_CACHED` attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The last data returned from the access matched the poll exit criteria.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>Width is invalid.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>Result is NULL.</td>
</tr>
<tr>
<td><code>EFI_TIMEOUT</code></td>
<td>Delay expired before a match occurred.</td>
</tr>
<tr>
<td><code>EFI_OUT_OF_RESOURCES</code></td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>
14.2.3 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.PollIo()

Summary

Reads from the I/O space of a PCI Root Bridge. Returns when either the polling exit criteria is satisfied or after a defined duration.

Prototype

typedef EFI_STATUS (EFIAPIC *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_POLL_IO_MEM) (  
IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,  
IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,  
IN UINT64 Address,  
IN UINT64 Mask,  
IN UINT64 Value,  
IN UINT64 Delay,  
OUT UINT64 *Result

);  

Parameters

This

A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in PCI Root Bridge I/O Protocol.

Width

Signifies the width of the I/O operations. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH see Related Definitions in the section PCI Root Bridge I/O Protocol.

Address

The base address of the I/O operations. The caller is responsible for aligning Address if required.

Mask

Mask used for the polling criteria. Bytes above Width in Mask are ignored. The bits in the bytes below Width which are zero in Mask are ignored when polling the I/O address.

Value

The comparison value used for the polling exit criteria.

Delay

The number of 100 ns units to poll. Note that timer available may be of poorer granularity.

Result

Pointer to the last value read from the memory location.

Description

This function provides a standard way to poll a PCI I/O location. A PCI I/O read operation is performed at the PCI I/O address specified by Address for the width specified by Width. The result of this PCI I/O read operation is stored in Result. This PCI I/O read operation is repeated until either a timeout of Delay 100 ns units has expired, or ( Result & Mask ) is equal to Value.

This function will always perform at least one I/O access no matter how small Delay may be. If Delay is zero, then Result will be returned with a status of EFI_SUCCESS even if Result does not match the exit criteria. If Delay expires, then EFI_TIMEOUT is returned.
If Width is not EfiPciWidthUint8, EfiPciWidthUint16, EfiPciWidthUint32, or EfiPciWidthUint64, then EFI_INVALID_PARAMETER is returned.

The I/O operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and I/O width restrictions that the PCI Root Bridge on a platform might require. For example, on some platforms, width requests of EfiPciWidthUint64 do not work.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The last data returned from the access matched the poll exit criteria.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Width is invalid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Result is NULL.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Delay expired before a match occurred.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

14.2.4 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Mem.Read()

14.2.5 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Mem.Write()

Summary

Enables a PCI driver to access PCI controller registers in the PCI root bridge memory space.

Prototype

```c
typedef EFI_STATUS
(EIFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM) (
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,
    IN UINT64 Address,
    IN UINTN Count,
    IN OUT VOID *Buffer
);```

Parameters

This

A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in PCI Root Bridge I/O Protocol.

Width

Signifies the width of the memory operation. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH see Related Definitions in the section PCI Root Bridge I/O Protocol.

Address

The base address of the memory operation. The caller is responsible for aligning the Address if required.

Count

The number of memory operations to perform. Bytes moved is Width size * Count, starting at Address.

Buffer

For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.
Description

The `Mem.Read()` and `Mem.Write()` functions enable a driver to access PCI controller registers in the PCI root bridge memory space.

The memory operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and memory width restrictions that a PCI Root Bridge on a platform might require. For example, on some platforms, width requests of `EfiPciWidthUint64` do not work.

If `Width` is `EfiPciWidthUint8`, `EfiPciWidthUint16`, `EfiPciWidthUint32`, or `EfiPciWidthUint64`, then both `Address` and `Buffer` are incremented for each of the `Count` operations performed.

If `Width` is `EfiPciWidthFifoUint8`, `EfiPciWidthFifoUint16`, `EfiPciWidthFifoUint32`, or `EfiPciWidthFifoUint64`, then only `Buffer` is incremented for each of the `Count` operations performed. The read or write operation is performed `Count` times on the same `Address`.

If `Width` is `EfiPciWidthFillUint8`, `EfiPciWidthFillUint16`, `EfiPciWidthFillUint32`, or `EfiPciWidthFillUint64`, then only `Address` is incremented for each of the `Count` operations performed. The read or write operation is performed `Count` times from the first element of `Buffer`.

All the PCI read transactions generated by this function are guaranteed to be completed before this function returns.

All the PCI write transactions generated by this function will follow the write ordering and completion rules defined in the PCI Specification. However, if the memory-mapped I/O region being accessed by this function has the `EFI_PCI_ATTRIBUTE_MEMORY_CACHED` attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was read from or written to the PCI root bridge.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Width is invalid for this PCI root bridge.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

14.2.6 `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Io.Read()`

14.2.7 `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Io.Write()`

Summary

Enables a PCI driver to access PCI controller registers in the PCI root bridge I/O space.

Prototype

```c
typedef EFI_STATUS
    (EFIAPICALLTYPE *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM)(
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,
    IN UINT64 Address,
    IN UINTN Count,
    IN OUT VOID *Buffer
    );
```

Parameters
This
A pointer to the `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL`. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL` is defined in `PCI Root Bridge I/O Protocol`.

**Width**
Signifies the width of the memory operation. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH` see Related Definitions in the section `PCI Root Bridge I/O Protocol`.

**Address**
The base address of the I/O operation. The caller is responsible for aligning the Address if required.

**Count**
The number of I/O operations to perform. Bytes moved is Width size * Count, starting at Address.

**Buffer**
For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.

**Description**
The `Io.Read()` , and `Io.Write()` functions enable a driver to access PCI controller registers in the PCI root bridge I/O space.

The I/O operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and I/O width restrictions that a PCI root bridge on a platform might require. For example on some platforms, width requests of `EfiPciWidthUint64` do not work.

If `Width` is `EfiPciWidthUint8`, `EfiPciWidthUint16`, `EfiPciWidthUint32`, or `EfiPciWidthUint64`, then both `Address` and `Buffer` are incremented for each of the `Count` operations performed.

If `Width` is `EfiPciWidthFifoUint8`, `EfiPciWidthFifoUint16`, `EfiPciWidthFifoUint32`, or `EfiPciWidthFifoUint64`, then only `Buffer` is incremented for each of the `Count` operations performed. The read or write operation is performed `Count` times on the same `Address`.

If `Width` is `EfiPciWidthFillUint8`, `EfiPciWidthFillUint16`, `EfiPciWidthFillUint32`, or `EfiPciWidthFillUint64`, then only `Address` is incremented for each of the `Count` operations performed. The read or write operation is performed `Count` times from the first element of `Buffer`.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was read from or written to the PCI root bridge.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Width is invalid for this PCI root bridge.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

14.2.8 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Pci.Read()

14.2.9 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Pci.Write()

**Summary**
Enables a PCI driver to access PCI controller registers in a PCI root bridge's configuration space.

**Prototype**
typedef EFI_STATUS (EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_IO_MEM) (IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This, IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width, IN UINT64 Address, IN UINTN Count, IN OUT VOID *Buffer);

Parameters

This
A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in PCI Root Bridge I/O Protocol.

Width
Signifies the width of the memory operation. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH see Related Definitions in the section PCI Root Bridge I/O Protocol.

Address
The address within the PCI configuration space for the PCI controller. See PCI Configuration Address for the format of Address.

Count
The number of PCI configuration operations to perform. Bytes moved is Width size * Count, starting at Address.

Buffer
For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.

Description
The Pci.Read() and Pci.Write() functions enable a driver to access PCI configuration registers for a PCI controller.

The PCI Configuration operations are carried out exactly as requested. The caller is responsible for any alignment and PCI configuration width issues that a PCI Root Bridge on a platform might require. For example on some platforms, width requests of EfiPciWidthUint64 do not work.

If Width is EfiPciWidthUint8, EfiPciWidthUint16, EfiPciWidthUint32, or EfiPciWidthUint64, then both Address and Buffer are incremented for each of the Count operations performed.

If Width is EfiPciWidthFifoUint8, EfiPciWidthFifoUint16, EfiPciWidthFifoUint32, or EfiPciWidthFifoUint64, then only Buffer is incremented for each of the Count operations performed. The read or write operation is performed Count times on the same Address.

If Width is EfiPciWidthFillUint8, EfiPciWidthFillUint16, EfiPciWidthFillUint32, or EfiPciWidthFillUint64, then only Address is incremented for each of the Count operations performed. The read or write operation is performed Count times from the first element of Buffer.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns.

### Table 14.5: PCI Configuration Address

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Register</td>
<td>0</td>
<td>1</td>
<td>The register number on the PCI Function.</td>
</tr>
<tr>
<td>Function</td>
<td>1</td>
<td>1</td>
<td>The PCI Function number on the PCI Device.</td>
</tr>
<tr>
<td>Device</td>
<td>2</td>
<td>1</td>
<td>The PCI Device number on the PCI Bus.</td>
</tr>
</tbody>
</table>

continues on next page
### Table 14.5 – continued from previous page

<table>
<thead>
<tr>
<th>Bus</th>
<th>3</th>
<th>1</th>
<th>The PCI Bus number.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ext-</td>
<td>4</td>
<td>4</td>
<td>The register number on the PCI Function. If this field is zero, then the Register field is used for the register number. If this field is nonzero, then the Register field is ignored, and the ExtendedRegister field is used for the register number.</td>
</tr>
</tbody>
</table>

#### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was read from or written to the PCI root bridge.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Width is invalid for this PCI root bridge.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

### 14.2.10 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.CopyMem()

#### Summary

Enables a PCI driver to copy one region of PCI root bridge memory space to another region of PCI root bridge memory space.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_COPY_MEM) (  
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,  
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH Width,  
    IN UINT64 DestAddress,  
    IN UINT64 SrcAddress,  
    IN UINTN Count  
);
```

#### Parameters

- **This**
  A pointer to the `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL`. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL` is defined in `PCI Root Bridge I/O Protocol`.

- **Width**
  Signifies the width of the memory operation. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_WIDTH` see `Related Definitions` in the section `PCI Root Bridge I/O Protocol`.

- **DestAddress**
  The destination address of the memory operation. The caller is responsible for aligning the DestAddress if required.

- **SrcAddress**
  The source address of the memory operation. The caller is responsible for aligning the SrcAddress if required.

- **Count**
  The number of memory operations to perform. Bytes moved is Width size * Count, starting at DestAddress and SrcAddress.

#### Description
The CopyMem() function enables a PCI driver to copy one region of PCI root bridge memory space to another region of PCI root bridge memory space. This is especially useful for video scroll operation on a memory mapped video buffer.

The memory operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and memory width restrictions that a PCI root bridge on a platform might require. For example on some platforms, width requests of EfiPciWidthUint64 do not work.

If Width is EfiPciIoWidthUint8, EfiPciIoWidthUint16, EfiPciIoWidthUint32, or EfiPciIoWidthUint64, then Count read/write transactions are performed to move the contents of the SrcAddress buffer to the DestAddress buffer. The implementation must be reentrant, and it must handle overlapping SrcAddress and DestAddress buffers. This means that the implementation of CopyMem() must choose the correct direction of the copy operation based on the type of overlap that exists between the SrcAddress and DestAddress buffers. If either the SrcAddress buffer or the DestAddress buffer crosses the top of the processor’s address space, then the result of the copy operation is unpredictable.

The contents of the DestAddress buffer on exit from this service must match the contents of the SrcAddress buffer on entry to this service. Due to potential overlaps, the contents of the SrcAddress buffer may be modified by this service. The following rules can be used to guarantee the correct behavior:

- If DestAddress > SrcAddress and DestAddress < (SrcAddress + Width size * Count), then the data should be copied from the SrcAddress buffer to the DestAddress buffer starting from the end of buffers and working toward the beginning of the buffers.
- Otherwise, the data should be copied from the SrcAddress buffer to the DestAddress buffer starting from the beginning of the buffers and working toward the end of the buffers.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns. All the PCI write transactions generated by this function will follow the write ordering and completion rules defined in the PCI Specification. However, if the memory-mapped I/O region being accessed by this function has the EFI_PCI_ATTRIBUTE_MEMORY_CACHED attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was copied from one memory region to another memory region.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Width is invalid for this PCI root bridge.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

14.2.11 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Map()

Summary

Provides the PCI controller-specific addresses required to access system memory from a DMA bus master.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_MAP) (  
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_OPERATION
    IN VOID
    IN OUT UINTN
    OUT EFI_PHYSICAL_ADDRESS
    OUT VOID
);
This

A pointer to the `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL`. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL` is defined in `PCI Root Bridge I/O Protocol`.

Operation

Indicates if the bus master is going to read or write to system memory. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_OPERATION` defined in Section `PCI Root Bridge I/O Protocol`.

HostAddress

The system memory address to map to the PCI controller.

NumberOfBytes

On input the number of bytes to map. On output the number of bytes that were mapped.

DeviceAddress

The resulting map address for the bus master PCI controller to use to access the system memory’s `HostAddress`. Type `EFI_PHYSICAL_ADDRESS`, defined in `EFI_BOOT_SERVICES.AllocatePool()`. This address cannot be used by the processor to access the contents of the buffer specified by `HostAddress`.

Mapping

The value to pass to `Unmap()` when the bus master DMA operation is complete.

Description

The `Map()` function provides the PCI controller specific addresses needed to access system memory. This function is used to map system memory for PCI bus master DMA accesses.

All PCI bus master accesses must be performed through their mapped addresses and such mappings must be freed with `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Unmap()` when complete. If the bus master access is a single read or single write data transfer, then `EfiPciOperationBusMasterRead`, `EfiPciOperationBusMasterRead64`, `EfiPciOperationBusMasterWrite`, or `EfiPciOperationBusMasterWrite64` is used and the range is unmapped to complete the operation. If performing an `EfiPciOperationBusMasterRead` or `EfiPciOperationBusMasterRead64` operation, all the data must be present in system memory before `Map()` is performed. Similarly, if performing an `EfiPciOperationBusMasterWrite` or `EfiPciOperationBusMasterWrite64` the data cannot be properly accessed in system memory until `Unmap()` is performed.

Bus master operations that require both read and write access or require multiple host device interactions within the same mapped region must use `EfiPciOperation-BusMasterCommonBuffer` or `EfiPciOperationBusMasterCommonBuffer64`. However, only memory allocated via the `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.AllocateBuffer()` interface can be mapped for this type of operation.

In all mapping requests the resulting `NumberOfBytes` actually mapped may be less than the requested amount. In this case, the DMA operation will have to be broken up into smaller chunks. The `Map()` function will map as much of the DMA operation as it can at one time. The caller may have to loop on `Map()` and `Unmap()` in order to complete a large DMA transfer.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The range was mapped for the returned <code>NumberOfBytes</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Operation is invalid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>HostAddress</code> is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>NumberOfBytes</code> is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>DeviceAddress</code> is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>Mapping</code> is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The <code>HostAddress</code> cannot be mapped as a common buffer.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The system hardware could not map the requested address.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

14.2. PCI Root Bridge I/O Protocol
14.2.12 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Unmap()

Summary

Completes the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Map() operation and releases any corresponding resources.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_UNMAP) (   
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,   
    IN VOID *Mapping
);
```

Parameters

This

A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL, defined in PCI Root Bridge I/O Protocol.

Mapping

The mapping value returned from Map().

Description

The Unmap() function completes the Map() operation and releases any corresponding resources. If the operation was an EfiPciOperationBusMasterWrite or EfiPciOperationBusMasterWrite64, the data is committed to the target system memory. Any resources used for the mapping are freed.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The range was unmapped.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Mapping is not a value that was returned by Map().</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The data was not committed to the target system memory.</td>
</tr>
</tbody>
</table>

14.2.13 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.AllocateBuffer()

Summary

Allocates pages that are suitable for an EfiPciOperationBusMasterCommonBuffer or EfiPciOperationBusMasterCommonBuffer64 mapping.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_ALLOCATE_BUFFER) (   
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,   
    IN EFI_ALLOCATE_TYPE Type,   
    IN EFI_MEMORY_TYPE MemoryType,   
    IN UINTN Pages,   
    OUT VOID **HostAddress,   
    IN UINT64 Attributes
);
```
Parameters

This
A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL. Type EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL is defined in Section PCI Root Bridge I/O Protocol.

Type
This parameter is not used and must be ignored.

Memory
Type The type of memory to allocate, EfiBootServicesData or EfiRuntimeServicesData. Type EFI_MEMORY_TYPE is defined in EFI_BOOT_SERVICES.AllocatePages().

Pages
The number of pages to allocate.

HostAddress
A pointer to store the base system memory address of the allocated range.

Attributes
The requested bit mask of attributes for the allocated range. Only the attributes EFI_PCI_ATTRIBUTE_MEMORY_WRITE_COMBINE, EFI_PCI_ATTRIBUTE_MEMORY_CACHED, and EFI_PCI_ATTRIBUTE_DUAL_ADDRESS_CYCLE may be used with this function. If any other bits are set, then EFI_UNSUPPORTED is returned. This function may choose to ignore this bit mask. The EFI_PCI_ATTRIBUTE_MEMORY_WRITE_COMBINE and EFI_PCI_ATTRIBUTE_MEMORY_CACHED attributes provide a hint to the implementation that may improve the performance of the calling driver. The implementation may choose any default for the memory attributes including write combining, cached, both, or neither as long as the allocated buffer can be seen equally by both the processor and the PCI bus master.

Description
The AllocateBuffer() function allocates pages that are suitable for an EfiPciOperationBusMasterCommonBuffer or EfiPciOperationBusMasterCommonBuffer64 mapping. This means that the buffer allocated by this function must support simultaneous access by both the processor and a PCI Bus Master. The device address that the PCI Bus Master uses to access the buffer can be retrieved with a call to EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Map().

If the EFI_PCI_ATTRIBUTE_DUAL_ADDRESS_CYCLE bit of Attributes is set, then when the buffer allocated by this function is mapped with a call to Map(), the device address that is returned by Map() must be within the 64-bit device address space of the PCI Bus Master.

If the EFI_PCI_ATTRIBUTE_DUAL_ADDRESS_CYCLE bit of Attributes is clear, then when the buffer allocated by this function is mapped with a call to Map(), the device address that is returned by Map() must be within the 32-bit device address space of the PCI Bus Master.

If the memory allocation specified by MemoryType and Pages cannot be satisfied, then EFI_OUT_OF_RESOURCES is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested memory pages were allocated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>MemoryType is invalid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HostAddress is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Attributes is unsupported. The only legal attribute bits are EFI_PCI_ATTRIBUTE_MEMORY_WRITE_COMBINE, EFI_PCI_ATTRIBUTE_MEMORY_CACHED, and EFI_PCI_ATTRIBUTE_DUAL_ADDRESS_CYCLE.</td>
</tr>
</tbody>
</table>

continues on next page
### 14.2.14 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.FreeBuffer()

**Summary**

Frees memory that was allocated with `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.AllocateBuffer()`.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_FREE_BUFFER) (
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,
    IN UINTN Pages,
    IN VOID *HostAddress
);
```

**Parameters**

- **This**
  
  A pointer to the `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL`. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL` is defined in *PCI Root Bridge I/O Protocol*.

- **Pages**
  
  The number of pages to free.

- **HostAddress**
  
  The base system memory address of the allocated range.

**Description**

The `FreeBuffer()` function frees memory that was allocated with `AllocateBuffer()`.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested memory pages were freed.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | The memory range specified by HostAddress and Pages was not allocated with `AllocateBuffer()`.

### 14.2.15 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Flush()

**Summary**

Flushes all PCI posted write transactions from a PCI host bridge to system memory.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_FLUSH) (
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This
);
```

**Parameters**

None
This

A pointer to the `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL`. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL` is defined in Section `PCI Root Bridge I/O Protocol`.

Description

The `Flush()` function flushes any PCI posted write transactions from a PCI host bridge to system memory. Posted write transactions are generated by PCI bus masters when they perform write transactions to target addresses in system memory.

This function does not flush posted write transactions from any PCI bridges. A PCI controller specific action must be taken to guarantee that the posted write transactions have been flushed from the PCI controller and from all the PCI bridges into the PCI host bridge. This is typically done with a PCI read transaction from the PCI controller prior to calling `Flush()`.

If the PCI controller specific action required to flush the PCI posted write transactions has been performed, and this function returns `EFI_SUCCESS`, then the PCI bus master’s view and the processor’s view of system memory are guaranteed to be coherent. If the PCI posted write transactions cannot be flushed from the PCI host bridge, then the PCI bus master and processor are not guaranteed to have a coherent view of system memory, and `EFI_DEVICE_ERROR` is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The PCI posted write transactions were flushed from the PCI host bridge to system memory.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The PCI posted write transactions were not flushed from the PCI host bridge due to a hardware error.</td>
</tr>
</tbody>
</table>

14.2.16 `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.GetAttributes()`

Summary

Gets the attributes that a PCI root bridge supports setting with `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.SetAttributes()`, and the attributes that a PCI root bridge is currently using. Prototype

```c
typedef EFI_STATUS (EFIAPICALLNAME(EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_GET_ATTRIBUTES)) (  
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,  
    OUT UINT64 *Supports OPTIONAL,  
    OUT UINT64 *Attributes OPTIONAL  
);  
```

Parameters

This

A pointer to the `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL`. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL` is defined in Section `PCI Root Bridge I/O Protocol`.

Supports

A pointer to the mask of attributes that this PCI root bridge supports setting with `SetAttributes()`. The available attributes are listed in See `PCI Root Bridge I/O Protocol`. This is an optional parameter that may be `NULL`.

Attributes

A pointer to the mask of attributes that this PCI root bridge is currently using. The available attributes are listed in See `PCI Root Bridge I/O Protocol`. This is an optional parameter that may be `NULL`.

14.2. PCI Root Bridge I/O Protocol
Description

The `GetAttributes()` function returns the mask of attributes that this PCI root bridge supports and the mask of attributes that the PCI root bridge is currently using. If `Supports` is not NULL, then `Supports` is set to the mask of attributes that the PCI root bridge supports. If `Attributes` is not NULL, then `Attributes` is set to the mask of attributes that the PCI root bridge is currently using. If both `Supports` and `Attributes` are NULL, then `EFI_INVALID_PARAMETER` is returned. Otherwise, `EFI_SUCCESS` is returned.

If a bit is set in `Supports`, then the PCI root bridge supports this attribute type, and a call can be made to `SetAttributes()` using that attribute type. If a bit is set in `Attributes`, then the PCI root bridge is currently using that attribute type. Since a PCI host bus may be composed of more than one PCI root bridge, different `Attributes` values may be returned by different PCI root bridges.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>If <code>Supports</code> is not NULL, then the attributes that the PCI root bridge supports is returned in <code>Supports</code>. If <code>Attributes</code> is not NULL, then the attributes that the PCI root bridge is currently using is returned in <code>Attributes</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Both <code>Supports</code> and <code>Attributes</code> are NULL.</td>
</tr>
</tbody>
</table>

14.2.17 EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.SetAttributes()

Summary

Sets attributes for a resource range on a PCI root bridge.

Prototype

```c
typedef EFI_STATUS (EFIAPI * EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_SET_ATTRIBUTES) (  
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL *This,  
    IN UINT64 Attributes,  
    IN OUT UINT64 *ResourceBase OPTIONAL,  
    IN OUT UINT64 *ResourceLength OPTIONAL  
);  
```

Parameters

This

A pointer to the `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL`. Type `EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL` is defined in `PCI Root Bridge I/O Protocol`.

Attributes

The mask of attributes to set. If the attribute bit MEMORY_WRITE_COMBINE, MEMORY_CACHED, or MEMORY_DISABLE is set, then the resource range is specified by `ResourceBase` and `ResourceLength`. If MEMORY_WRITE_COMBINE, MEMORY_CACHED, and MEMORY_DISABLE are not set, then `ResourceBase` and `ResourceLength` are ignored, and may be NULL. The available attributes are listed in `PCI Root Bridge I/O Protocol`.

ResourceBase

A pointer to the base address of the resource range to be modified by the attributes specified by `Attributes`. On return, `ResourceBase` will be set the actual base address of the resource range. Not all resources can be set to a byte boundary, so the actual base address may differ from the one passed in by the caller. This parameter is only used if the MEMORY_WRITE_COMBINE bit, the MEMORY_CACHED bit, or the MEMORY_DISABLE bit of `Attributes` is set. Otherwise, it is ignored, and may be NULL.
**ResourceLength**

A pointer to the length of the resource range to be modified by the attributes specified by Attributes. On return, ResourceLength will be set the actual length of the resource range. Not all resources can be set to a byte boundary, so the actual length may differ from the one passed in by the caller. This parameter is only used if the MEMORY_WRITE_COMBINE bit, the MEMORY_CACHED bit, or the MEMORY_DISABLE bit of Attributes is set. Otherwise, it is ignored, and may be **NULL**.

**Description**

The **SetAttributes()** function sets the attributes specified in Attributes for the PCI root bridge on the resource range specified by ResourceBase and ResourceLength. Since the granularity of setting these attributes may vary from resource type to resource type, and from platform to platform, the actual resource range and the one passed in by the caller may differ. As a result, this function may set the attributes specified by Attributes on a larger resource range than the caller requested. The actual range is returned in ResourceBase and ResourceLength. The caller is responsible for verifying that the actual range for which the attributes were set is acceptable.

If the attributes are set on the PCI root bridge, then the actual resource range is returned in ResourceBase and ResourceLength, and **EFI_SUCCESS** is returned.

If the attributes specified by Attributes are not supported by the PCI root bridge, then **EFI_UNSUPPORTED** is returned. The set of supported attributes for a PCI root bridge can be found by calling **EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.GetAttributes()**.

If either ResourceBase or ResourceLength are NULL, and a resource range is required for the attributes specified in Attributes, then **EFI_INVALID_PARAMETER** is returned.

If more than one resource range is required for the set of attributes specified by Attributes, then **EFI_INVALID_PARAMETER** is returned.

If there are not enough resources available to set the attributes, then **EFI_OUT_OF_RESOURCES** is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>The set of attributes specified by Attributes for the resource range specified by ResourceBase and ResourceLength were set on the PCI root bridge, and the actual resource range is returned in ResourceBase and ResourceLength.</td>
</tr>
<tr>
<td><strong>EFI_UNSUPPORTED</strong></td>
<td>A bit is set in Attributes that is not supported by the PCI Root Bridge. The supported attribute bits are reported by <strong>EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.GetAttributes()</strong>.</td>
</tr>
<tr>
<td><strong>EFI_INVALID_PARAMETER</strong></td>
<td>More than one attribute bit is set in Attributes that requires a resource range.</td>
</tr>
<tr>
<td><strong>EFI_INVALID_PARAMETER</strong></td>
<td>A resource range is required, and ResourceBase is NULL.</td>
</tr>
<tr>
<td><strong>EFI_INVALID_PARAMETER</strong></td>
<td>A resource range is required, and ResourceLength is NULL.</td>
</tr>
<tr>
<td><strong>EFI_OUT_OF_RESOURCES</strong></td>
<td>There are not enough resources to set the attributes on the resource range specified by BaseAddress and Length.</td>
</tr>
</tbody>
</table>

**14.2.18 **EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Configuration()**

**Summary**

Retrieves the current resource settings of this PCI root bridge in the form of a set of ACPI resource descriptors.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL_CONFIGURATION) ( 
    IN EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL  
     /*This, 
```
OUT VOID **Resources

Parameters

This
A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL, which is defined in *PCI Root Bridge I/O Protocol*.

Resources
A pointer to the resource descriptors that describe the current configuration of this PCI root bridge. The storage for the resource descriptors is allocated by this function. The caller must treat the return buffer as read-only data, and the buffer must not be freed by the caller. See “Related Definitions” for the resource descriptors that may be used.

Related Definitions

There are only two resource descriptor types from the ACPI Specification that may be used to describe the current resources allocated to a PCI root bridge. These are the QWORD Address Space Descriptor, and the End Tag. The QWORD Address Space Descriptor can describe memory, I/O, and bus number ranges for dynamic or fixed resources. The configuration of a PCI root bridge is described in the Tables below with one or more QWORD Address Space Descriptors followed by an End Tag which contain these two descriptor types.

Please see the ACPI Specification for details on the field values. The definition of the Address Space Granularity field in the QWORD Address Space Descriptor differs from the ACPI Specification, and the definition in the table below is the one that must be used.

Table 14.15: QWORD Address Space Descriptor

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x8A</td>
<td>QWORD Address Space Descriptor</td>
</tr>
<tr>
<td>0x01</td>
<td>0x02</td>
<td>0x2B</td>
<td>Length of this descriptor in bytes not including the first two fields</td>
</tr>
<tr>
<td>0x03</td>
<td>0x01</td>
<td></td>
<td>Resource Type</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0 - Memory Range</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>1 - I/O Range</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>2 - Bus Number Range</td>
</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
<td></td>
<td>General Flags</td>
</tr>
<tr>
<td>0x05</td>
<td>0x01</td>
<td></td>
<td>Type Specific Flags</td>
</tr>
<tr>
<td>0x06</td>
<td>0x08</td>
<td></td>
<td>Address Space Granularity. Used to differentiate between a 32-bit memory</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>request and a 64-bit memory request. For a 32-bit memory request, this</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>field should be set to 32. For a 64-bit memory request, this field</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>should be set to 64.</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x08</td>
<td></td>
<td>Address Range Minimum</td>
</tr>
<tr>
<td>0x16</td>
<td>0x08</td>
<td></td>
<td>Address Range Maximum</td>
</tr>
<tr>
<td>0x1E</td>
<td>0x08</td>
<td></td>
<td>Address Translation Offset. Offset to apply to the Starting address to</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>convert it to a PCI address. This value is zero unless the HostAddress and</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>DeviceAddress for the root bridge are different.</td>
</tr>
<tr>
<td>0x26</td>
<td>0x08</td>
<td></td>
<td>Address Length</td>
</tr>
</tbody>
</table>
Description

The Configuration() function retrieves a set of resource descriptors that contains the current configuration of this PCI root bridge. If the current configuration can be retrieved, then it is returned in Resources and EFI_SUCCESS is returned. See “Related Definitions” below for the resource descriptor types that are supported by this function. If the current configuration cannot be retrieved, then EFI_UNSUPPORTED is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The current configuration of this PCI root bridge was returned in Resources.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The current configuration of this PCI root bridge could not be retrieved.</td>
</tr>
</tbody>
</table>

### 14.2.19 PCI Root Bridge Device Paths

See EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL must be installed on a handle for its services to be available to drivers. In addition to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL, an EFI Device Path Protocol must also be installed on the same handle.

Typically, an ACPI Device Path Node is used to describe a PCI Root Bridge. Depending on the bus hierarchy in the system, additional device path nodes may precede this ACPI Device Path Node. A desktop system will typically contain only one PCI Root Bridge, so there would be one handle with a EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL and an EFI_DEVICE_PATH_PROTOCOL. A server system may contain multiple PCI Root Bridges, so it would contain a handle for each PCI Root Bridge present, and on each of those handles would be an EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL and an EFI_DEVICE_PATH_PROTOCOL. In all cases, the contents of the ACPI Device Path Nodes for PCI Root Bridges must match the information present in the ACPI tables for that system.

Table below: PCI Root Bridge Device Path for a Desktop System shows an example device path for a PCI Root Bridge in a desktop system. Today, a desktop system typically contains only one PCI Root Bridge. This device path consists of an ACPI Device Path Node, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. For a system with only one PCI Root Bridge, the _UID value is usually 0x0000. The shorthand notation for this device path is ACPI(PNP0A03,0).

Table 14.18: PCI Root Bridge Device Path for a Desktop System

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>
In the Tables belows, *PCI Root Bridge Device Path for Bridge #0 in a Server System* through *PCI Root Bridge Device Path for Bridge #3 in a Server System* show example device paths for the PCI Root Bridges in a server system with four PCI Root Bridges. Each of these device paths consists of an ACPI Device Path Node, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridges. The only difference between each of these device paths is the _UID field. The shorthand notation for these four device paths is ACPI(PNP0A03,0), ACPI(PNP0A03,1), ACPI(PNP0A03,2), and ACPI(PNP0A03,3).

### Table 14.19: PCI Root Bridge Device Path for Bridge #0 in a Server System

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0,</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0A03</td>
<td>encoded in the low order bytes. The compression method is described in the</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

### Table 14.20: PCI Root Bridge Device Path for Bridge #1 in a Server System

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0,</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0A03</td>
<td>encoded in the low order bytes. The compression method is described in the</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0001</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

### Table 14.21: PCI Root Bridge Device Path for Bridge #2 in a Server System

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0,</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0A03</td>
<td>encoded in the low order bytes. The compression method is described in the</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>ACPI Specification.</td>
</tr>
</tbody>
</table>

continues on next page
Table 14.21 – continued from previous page

<table>
<thead>
<tr>
<th>Byte</th>
<th>Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0002</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0xF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

Table 14.22: PCI Root Bridge Device Path for Bridge #3 in a Server System

<table>
<thead>
<tr>
<th>Byte Off-set</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0003</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

The Table below, **PCI Root Bridge Device Path Using Expanded ACPI Device Path**, shows an example device path for a PCI Root Bridge using an Expanded ACPI Device Path. This device path consists of an Expanded ACPI Device Path Node, and a Device Path End Structure. The _UID and _CID fields must match the ACPI table description of the PCI Root Bridge. For a system with only one PCI Root Bridge, the _UID value is usually 0x0000. The shorthand notation for this device path is \textit{ACPI(12345678,0,PNP0A03)}.

Table 14.23: PCI Root Bridge Device Path Using Expanded ACPI Device Path

<table>
<thead>
<tr>
<th>Byte Off-set</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x02</td>
<td>Sub type - Expanded ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x10</td>
<td>Length - 0x10 bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x1234, 0x5678</td>
<td>_HID-device specific</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x04</td>
<td>0x41D0, 0x0A03</td>
<td>_CID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x12</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>
14.3 PCI Driver Model

PCI Driver Model and EFI PCI I/O Protocol describe the PCI Driver Model. This includes the behavior of PCI Bus Drivers, the behavior of a PCI Device Drivers, and a detailed description of the PCI I/O Protocol. The PCI Bus Driver manages PCI buses present in a system, and PCI Device Drivers manage PCI controllers present on PCI buses. The PCI Device Drivers produce an I/O abstraction that can be used to boot an EFI compliant operating system.

This document provides enough material to implement a PCI Bus Driver, and the tools required to design and implement a PCI Device Drivers. It does not provide any information on specific PCI devices.

The material contained in this section is designed to extend this specification and the UEFI Driver Model in a way that supports PCI device drivers and PCI bus drivers. These extensions are provided in the form of PCI-specific protocols. This section provides the information required to implement a PCI Bus Driver in system firmware. The section also contains the information required by driver writers to design and implement PCI Device Drivers that a platform may need to boot a UEFI-compliant OS.

The PCI Driver Model described here is intended to be a foundation on which a PCI Bus Driver and a wide variety of PCI Device Drivers can be created.

14.3.1 PCI Driver Initialization

There are very few differences between a PCI Bus Driver and PCI Device Driver in the entry point of the driver. The file for a driver image must be loaded from some type of media. This could include ROM, FLASH, hard drives, floppy drives, CD-ROM, or even a network connection. Once a driver image has been found, it can be loaded into system memory with the Boot Service: EFI_BOOT_SERVICES.LoadImage(). LoadImage() loads a PE/COFF formatted image into system memory. A handle is created for the driver, and a Loaded Image Protocol instance is placed on that handle. A handle that contains a Loaded Image Protocol instance is called an Image Handle. At this point, the driver has not been started. It is just sitting in memory waiting to be started. The figure below shows the state of an image handle for a driver after LoadImage() has been called.

![Image Handle](image-url)

Fig. 14.7: Image Handle

After a driver has been loaded with the Boot Service EFI_BOOT_SERVICES.LoadImage(), it must be started with the Boot Service EFI_BOOT_SERVICES.StartImage(). This is true of all types of applications and drivers that can be loaded and started on an UEFI compliant system. The entry point for a driver that follows the UEFI Driver Model must follow some strict rules. First, it is not allowed to touch any hardware. Instead, it is only allowed to install protocol instances onto its own Image Handle. A driver that follows the UEFI Driver Model is required to install an instance of the Driver Binding Protocol onto its own Image Handle. It may optionally install the Driver Diagnostics
Protocol or the Component Name Protocol. In addition, if a driver wishes to be unloadable it may optionally update the Loaded Image Protocol to provide its own Unload() \texttt{EFI\_LOADED\_IMAGE\_PROTOCOL.Unload()} function. Finally, if a driver needs to perform any special operations when the Boot Service \texttt{EFI\_BOOT\_SERVICES} is called (Services — Boot Services), the driver may optionally create an event with a notification function that is triggered when the Boot Service \texttt{ExitBootServices()} is called. An Image Handle that contains a Driver Binding Protocol instance is known as a Driver Image Handle. The Figure below, \textit{PCI Driver Image Handle}, shows a possible configuration for the Image Handle from figure: \textit{Image Handle} after the Boot Service \texttt{StartImage()} has been called.

![Diagram of PCI Driver Image Handle]

\textbf{Fig. 14.8: PCI Driver Image Handle}

\section*{14.3.2 Driver Diagnostics Protocol}

If a PCI Bus Driver or a PCI Device Driver requires diagnostics, then an \texttt{EFI\_DRIVER\_DIAGNOSTICS2\_PROTOCOL} must be installed on the image handle in the entry point for the driver. This protocol contains functions to perform diagnostics on a controller. The \texttt{EFI\_DRIVER\_DIAGNOSTICS2\_PROTOCOL} is not allowed to interact with the user. Instead, it must return status information through a buffer. The functions of this protocol will be invoked by a platform management utility.
14.3.3 Component Name Protocol

Both a PCI Bus Driver and a PCI Device Driver are able to produce user readable names for the PCI drivers and/or the set of PCI controllers that the PCI drivers are managing. This is accomplished by installing an instance of the EFI_COMPONENT_NAME2_PROTOCOL on the image handle of the driver. This protocol can produce driver and controller names in the form of a string in one of several languages. This protocol can be used by a platform management utility to display user readable names for the drivers and controllers present in a system. Please see the EFI Driver Model Specification for details on the EFI_COMPONENT_NAME2_PROTOCOL.

14.3.4 Driver Family Override Protocol

If a PCI Bus Driver or PCI Device Driver always wants the PCI driver delivered in a PCI Option ROM to manage the PCI controller associated with the PCI Option ROM, then the Driver Family Override Protocol must not be produced.

If a PCI Bus Driver or PCI Device Driver always wants the PCI driver with the highest Version value in the Driver Binding Protocol to manage all the PCI Controllers in the same family of PCI controllers, then the Driver Family Override Protocol must be produced on the same handle as the Driver Binding Protocol.

14.3.5 PCI Bus Drivers

A PCI Bus Driver manages PCI Host Bus Controllers that can contain one or more PCI Root Bridges. PCI Host Bus Controller shows an example of a desktop system that has one PCI Host Bus Controller with one PCI Root Bridge.

![Fig. 14.9: PCI Host Bus Controller](image)

The PCI Host Bus Controller shown above is abstracted in software with the PCI Root Bridge I/O Protocol. A PCI Bus Driver will manage handles that contain this protocol. Device Handle for a PCI Host Bus Controller shows an example
device handle for a PCI Host Bus Controller. It contains a Device Path Protocol instance and a PCI Root Bridge I/O Protocol Instance.

![Device Handle](image)

**Fig. 14.10: Device Handle for a PCI Host Bus Controller**

### 14.3.6 Driver Binding Protocol for PCI Bus Drivers

The Driver Binding Protocol contains three services. These are `Supported()` (EFI_DRIVER_BINDING_PROTOCOL.Supported()), `Start()` (EFI_DRIVER_BINDING_PROTOCOL.Start()), and `Stop()` (EFI_DRIVER_BINDING_PROTOCOL.Stop()). `Supported()` tests to see if the PCI Bus Driver can manage a device handle. A PCI Bus Driver can only manage device handles that contain the Device Path Protocol and the PCI Root Bridge I/O Protocol, so a PCI Bus Driver must look for these two protocols on the device handle that is being tested.

The `Start()` function tells the PCI Bus Driver to start managing a device handle. The device handle should support the protocols shown in [Device Handle for a PCI Host Bus Controller](image). The PCI Root Bridge I/O Protocols provide access to the PCI I/O, PCI Memory, PCI Prefetchable Memory, and PCI DMA functions. The PCI Controllers behind a PCI Root Bridge may exist on one or more PCI Buses. The standard mechanism for expanding the number of PCI Buses on a single PCI Root Bridge is to use PCI to PCI Bridges. Once a PCI Enumerator configures these bridges, they are invisible to software. As a result, the PCI Bus Driver flattens the PCI Bus hierarchy when it starts managing a device handle that represents a PCI Host Controller. **Physical PCI Bus Structure** shows the physical tree structure for a set of PCI Device denoted by A, B, C, D, and E. Device A and C are PCI to PCI Bridges. Connecting a PCI Bus Driver shows the tree structure generated by a PCI Bus Driver before and after `Start()` is called. This is a logical view of set of PCI controller, and not a physical view. The physical tree is flattened, so any PCI to PCI bridge devices are invisible. In this example, the PCI Bus Driver finds the five child PCI Controllers on the PCI Bus from **Physical PCI Bus Structure**. A device handle is created for every PCI Controller including all the PCI to PCI Bridges. The arrow with the dashed line coming into the PCI Host Bus Controller represents a link to the PCI Host Bus Controller’s parent. If the PCI Host Bus Controller is a Root Bus Controller, then it will not have a parent. The PCI Driver Model does not require that a PCI Host Bus Controller be a Root Bus Controller. A PCI Host Bus Controller can be present at any location in the tree, and the PCI Bus Driver should be able to manage the PCI Host Bus Controller.

The PCI Bus Driver has the option of creating all of its children in one call to `Start()` , or spreading it across several calls to `Start()`. In general, if it is possible to design a bus driver to create one child at a time, it should do so to support the rapid boot capability in the UEFI Driver Model. Each of the child device handles created in `Start()` must contain a Device Path Protocol instance, a PCI I/O protocol instance, and optionally a Bus Specific Driver Override Protocol instance. The PCI I/O Protocol is described in [EFI PCI I/O Protocol](image). The format of device paths for PCI Controllers is described in Section 2.6, and details on the Bus Specific Driver Override Protocol can be found in the EFI Driver Model Specification. The Figure below shows an example child device handle that is created by a PCI Bus Driver for a PCI Controller.
Fig. 14.11: Physical PCI Bus Structure

Fig. 14.12: Connecting a PCI Bus Driver
A PCI Bus Driver must perform several steps to manage a PCI Host Bus Controller, as follows:

- Initialize the PCI Host Bus Controller.
- If the PCI buses have not been initialized by a previous agent, perform PCI Enumeration on all the PCI Root Bridges that the PCI Host Bus Controller contains. This involves assigning a PCI bus number, allocating PCI I/O resources, PCI Memory resources, and PCI Prefetchable Memory resources.
- Discover all the PCI Controllers on all the PCI Root Bridges. If a PCI Controller is a PCI to PCI Bridge, then the I/O and Memory bits in the Control register of the PCI Configuration Header should be placed in the enabled state. The Bus Master bit in the Control Register may be enabled by default or enabled or disabled based on the needs of downstream devices for DMA access during the boot process. The PCI Bus Driver should disable the I/O, Memory, and Bus Master bits for PCI Controllers that respond to legacy ISA resources (e.g., VGA). It is a PCI Device Driver’s responsibility to enable the I/O, Memory, and Bus Master bits (if they are not already enabled by the PCI bus driver) of the Control register as required with a call to the `EFI_PCI_IO_PROTOCOL.Attributes()` service when the PCI Device Driver is started. A similar call to the Attributes() service should be made when the PCI Device Driver is stopped to restore original Attributes() state, including the I/O, Memory, and Bus Master bits of the Control register.
- Create a device handle for each PCI Controller found. If a request is being made to start only one PCI Controller, then only create one device handle.
- Install a Device Path Protocol instance and a PCI I/O Protocol instance on the device handle created for each PCI Controller.
- If the PCI Controller has a PCI Option ROM, then allocate a memory buffer that is the same size as the PCI Option ROM, and copy the PCI Option ROM contents to the memory buffer.
- If the PCI Option ROM contains any UEFI drivers, then attach a Bus Specific Driver Override Protocol to the device handle of the PCI Controller that is associated with the PCI Option ROM.

The `EFI_DRIVER_BINDING_PROTOCOL.Stop()` function tells the PCI Bus Driver to stop managing a PCI Host Bus Controller. The `Stop()` function can destroy one or more of the device handles that were created on a previous call to `EFI_DRIVER_BINDING_PROTOCOL.Start()`. If all of the child device handles have been destroyed, then `Stop()` will place the PCI Host Bus Controller in a quiescent state. The functionality of `Stop()` mirrors `Start()`, as follows:

1. Complete all outstanding transactions to the PCIHost Bus Controller.
2. If the PCI Host Bus Controller is being stopped, then place it in a quiescent state.
3. If one or more child handles are being destroyed, then:
   a. Uninstall all the protocols from the device handles for the PCI Controllers found in Start().
   b. Free any memory buffers allocated for PCI Option ROMs.
   c. Destroy the device handles for the PCI controllers created in Start().

14.3.7 PCI Enumeration

The PCI Enumeration process is a platform-specific operation that depends on the properties of the chipset that produces the PCI bus. As a result, details on PCI Enumeration are outside the scope of this document. A PCI Bus Driver requires that PCI Enumeration has been performed, so it either needs to have been done prior to the PCI Bus Driver starting, or it must be part of the PCI Bus Driver’s implementation.

14.3.8 PCI Device Drivers

PCI Device Drivers manage PCI Controllers. Device handles for PCI Controllers are created by PCI Bus Drivers. A PCI Device Driver is not allowed to create any new device handles. Instead, it attaches protocol instance to the device handle of the PCI Controller. These protocol instances are I/O abstractions that allow the PCI Controller to be used in the preboot environment. The most common I/O abstractions are used to boot an EFI compliant OS.

14.3.9 Driver Binding Protocol for PCI Device Drivers

The Driver Binding Protocol contains three services. These are `EFI_DRIVER_BINDING_PROTOCOL.Supported()` , `EFI_DRIVER_BINDING_PROTOCOL.Start()` , and `EFI_DRIVER_BINDING_PROTOCOL.Stop()`. Supported() tests to see if the PCI Device Driver can manage a device handle. A PCI Device Driver can only manage device handles that contain the Device Path Protocol and the PCI I/O Protocol, so a PCI Device Driver must look for these two protocols on the device handle that is being tested. In addition, it needs to check to see if the device handle represents a PCI Controller that the PCI Device Driver knows how to manage. This is typically done by using the services of the PCI I/O Protocol to read the PCI Configuration Header for the PCI Controller, and looking at the `VendorId` , `DeviceId` , and `SubsystemId` fields.

The Start() function tells the PCI Device Driver to start managing a PCI Controller. A PCI Device Driver is not allowed to create any new device handles. Instead, it installs one or more addition protocol instances on the device handle for the PCI Controller. A PCI Device Driver is not allowed to modify the resources allocated to a PCI Controller. These resource allocations are owned by the PCI Bus Driver or some other firmware component that initialized the PCI Bus prior to the execution of the PCI Bus Driver. This means that the PCI BARs (Base Address Registers) and the configuration of any PCI to PCI bridge controllers must not be modified by a PCI Device Driver. A PCI Bus Driver will leave a PCI Device in a disabled safe initial state. A PCI Device Driver should save the original Attributes() state. It is a PCI Device Driver’s responsibility to call Attributes() to enable the I/O, Memory, and Bus Master decodes if they are not already enabled by the PCI bus driver.

The `EFI_DRIVER_BINDING_PROTOCOL.Stop()` function mirrors the `EFI_DRIVER_BINDING_PROTOCOL.Start()` function, so the Stop() function completes any outstanding transactions to the PCI Controller and removes the protocol interfaces that were installed in Start(). The Figure below shows the device handle for a PCI Controller before and after Start() is called. In this example, a PCI Device Driver is adding the Block I/O Protocol to the device handle for the PCI Controller. It is also a PCI Device Driver’s responsibility to restore original Attributes() state, including the I/O, Memory, and Bus Master decodes by calling `EFI_PCI_IO_PROTOCOL.Attributes()` .
Fig. 14.14: Connecting a PCI Device Driver
14.4 EFI PCI I/O Protocol

This section provides a detailed description of the EFI PCI I/O Protocol. This protocol is used by code, typically drivers, running in the EFI boot services environment to access memory and I/O on a PCI controller. In particular, functions for managing devices on PCI buses are defined here.

The interfaces provided in the EFI_PCI_IO_PROTOCOL are for performing basic operations to memory, I/O, and PCI configuration space. The system provides abstracted access to basic system resources to allow a driver to have a programmatic method to access these basic system resources. The main goal of this protocol is to provide an abstraction that simplifies the writing of device drivers for PCI devices. This goal is accomplished by providing the following features:

- A driver model that does not require the driver to search the PCI busses for devices to manage. Instead, drivers are provided the location of the device to manage or have the capability to be notified when a PCI controller is discovered.
- A device driver model that abstracts the I/O addresses, Memory addresses, and PCI Configuration addresses from the PCI device driver. Instead, BAR (Base Address Register) relative addressing is used for I/O and Memory accesses, and device relative addressing is used for PCI Configuration accesses. The BAR relative addressing is specified in the PCI I/O services as a BAR index. A PCI controller may contain a combination of 32-bit and 64-bit BARs. The BAR index represents the logical BAR number in the standard PCI configuration header starting from the first BAR. The BAR index does not represent an offset into the standard PCI Configuration Header because those offsets will vary depending on the combination and order of 32-bit and 64-bit BARs.
- The Device Path for the PCI device can be obtained from the same device handle that the EFI_PCI_IO_PROTOCOL resides.
- The PCI Segment, PCI Bus Number, PCI Device Number, and PCI Function Number of the PCI device if they are required. The general idea is to abstract these details away from the PCI device driver. However, if these details are required, then they are available.
- Details on any nonstandard address decoding that is not covered by the PCI device’s Base Address Registers.
- Access to the PCI Root Bridge I/O Protocol for the PCI Host Bus for which the PCI device is a member.
- A copy of the PCI Option ROM if it is present in system memory.
- Functions to perform bus mastering DMA. This includes both packet based DMA and common buffer DMA.

14.4.1 EFI_PCI_IO_PROTOCOL

Summary

Provides the basic Memory, I/O, PCI configuration, and DMA interfaces that a driver uses to access its PCI controller.

GUID

```
#define EFI_PCI_IO_PROTOCOL_GUID \
{0x4cf5b200,0x68b8,0x4ca5,\} \
{0x9e,0xec,0xb2,0x3e,0x3f,0x50,0x02,0x9a}
```

Protocol Interface Structure

```
typedef struct __EFI_PCI_IO_PROTOCOL {
  EFI_PCI_IO_PROTOCOL_POLL_IO_MEM PollMem;
  EFI_PCI_IO_PROTOCOL_POLL_IO_MEM PollIo;
  EFI_PCI_IO_PROTOCOL_ACCESS Mem;
} EFI_PCI_IO_PROTOCOL;
```

(continues on next page)
Parameters

PollMem
Polls an address in PCI memory space until an exit condition is met, or a timeout occurs.

PollIo
Polls an address in PCI I/O space until an exit condition is met, or a timeout occurs.

Mem.Read
Allows BAR relative reads to PCI memory space.

Mem.Write
Allows BAR relative writes to PCI memory space.

Io.Read
Allows BAR relative reads to PCI I/O space.

Io.Write
Allows BAR relative writes to PCI I/O space.

Pci.Read
Allows PCI controller relative reads to PCI configuration space.

Pci.Write
Allows PCI controller relative writes to PCI configuration space.

CopyMem
Allows one region of PCI memory space to be copied to another region of PCI memory space.

Map
Provides the PCI controller-specific address needed to access system memory for DMA.
Unmap
Releases any resources allocated by Map(). See the \textit{EFI-PCI-I/O-PROTOCOL-Unmap()} function description.

AllocateBuffer
Allocates pages that are suitable for a common buffer mapping. See the \textit{EFI_PCI_IO_PROTOCOL.AllocateBuffer()} function description.

FreeBuffer
Frees pages that were allocated with AllocateBuffer(). See the \textit{EFI_PCI_IO_PROTOCOL.FreeBuffer()} function description.

Flush
Flushes all PCI posted write transactions to system memory. See the \textit{EFI_PCI_IO_PROTOCOL.Flush()} function description.

GetLocation
Retrieves this PCI controller’s current PCI bus number, device number, and function number. See the \textit{EFI_PCI_IO_PROTOCOL.GetLocation()} function description.

Attributes
Performs an operation on the attributes that this PCI controller supports. The operations include getting the set of supported attributes, retrieving the current attributes, setting the current attributes, enabling attributes, and disabling attributes. See the \textit{EFI_PCI_IO_PROTOCOL.Attributes()} function description.

GetBarAttributes
Gets the attributes that this PCI controller supports setting on a BAR using \textit{EFI_PCI_IO_PROTOCOL.SetBarAttributes()}, and retrieves the list of resource descriptors for a BAR. See the \textit{EFI_PCI_IO_PROTOCOL.GetBarAttributes()} function description.

SetBarAttributes
Sets the attributes for a range of a BAR on a PCI controller. See the SetBarAttributes() function description.

RomSize
The size, in bytes, of the ROM image.

RomImage
A pointer to the in memory copy of the ROM image. The PCI Bus Driver is responsible for allocating memory for the ROM image, and copying the contents of the ROM to memory. The contents of this buffer are either from the PCI option ROM that can be accessed through the ROM BAR of the PCI controller, or it is from a platform-specific location. The \textit{EFI_PCI_IO_PROTOCOL.Attributes()} function can be used to determine from which of these two sources the RomImage buffer was initialized.

Related Definitions

\begin{verbatim}
//******************************************************************************
// EFI_PCI_IO_PROTOCOL_WIDTH
//******************************************************************************
typedef enum {
   EfiPciIoWidthUint8,
   EfiPciIoWidthUint16,
   EfiPciIoWidthUint32,
   EfiPciIoWidthUint64,
   EfiPciIoWidthFifoUint8,
   EfiPciIoWidthFifoUint16,
   EfiPciIoWidthFifoUint32,
   EfiPciIoWidthFifoUint64,
   EfiPciIoWidthFillUint8,
   EfiPciIoWidthFillUint16,
}(continues on next page)
\end{verbatim}
EfiPciIoWidthFillUint32,
EfiPciIoWidthFillUint64,
EfiPciIoWidthMaximum
} EFI_PCI_IO_PROTOCOL_WIDTH;

#define EFI_PCI_IO_PASS_THROUGH_BAR 0xff

//*************************************************************
// EFI_PCI_IO_PROTOCOL_POLL_IO_MEM
//************************************************************************
typedef
EFI_STATUS
(EIFIAPIM *EFI_PCI_IO_PROTOCOL_POLL_IO_MEM) (  
  IN EFI_PCI_IO_PROTOCOL *This,
  IN EFI_PCI_IO_PROTOCOL_WIDTH Width,
  IN UINT8 BarIndex,
  IN UINT64 Offset,
  IN UINT64 Mask,
  IN UINT64 Value,
  IN UINT64 Delay,
  OUT UINT64 *Result
);
//************************************************************************

//*************************************************************
// EFI_PCI_IO_PROTOCOL_IO_MEM
//************************************************************************
typedef
EFI_STATUS
(EIFIAPIM *EFI_PCI_IO_PROTOCOL_IO_MEM) (  
  IN EFI_PCI_IO_PROTOCOL *This,
  IN EFI_PCI_IO_PROTOCOL_WIDTH Width,
  IN UINT8 BarIndex,
  IN UINT64 Offset,
  IN UINTN Count,
  IN OUT VOID *Buffer
);
//************************************************************************

//*************************************************************
// EFI_PCI_IO_PROTOCOL_ACCESS
//************************************************************************
typedef struct {
  EFI_PCI_IO_PROTOCOL_IO_MEM Read;
  EFI_PCI_IO_PROTOCOL_IO_MEM Write;
} EFI_PCI_IO_PROTOCOL_ACCESS;

//************************************************************************

//*************************************************************
// EFI_PCI_IO_PROTOCOL_CONFIG
//************************************************************************
typedef
EFI_STATUS
(EIFIAPIM *EFI_PCI_IO_PROTOCOL_CONFIG) (  
  IN EFI_PCI_IO_PROTOCOL *This,
  IN EFI_PCI_IO_PROTOCOL_WIDTH Width,
  IN EFI_PCI_IO_PROTOCOL_WIDTH
) (continued on next page)
typedef struct {
    EFI_PCI_IO_PROTOCOL_CONFIG Read;
    EFI_PCI_IO_PROTOCOL_CONFIG Write;
} EFI_PCI_IO_PROTOCOL_CONFIG_ACCESS;

EFI_PCI_IO_ATTRIBUTE_ISA_MOTHERBOARD_IO 0x0001
EFI_PCI_IO_ATTRIBUTE_ISA_IO 0x0002
EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO 0x0004
EFI_PCI_IO_ATTRIBUTE_VGA_MEMORY 0x0008
EFI_PCI_IO_ATTRIBUTE_VGA_IO 0x0010
EFI_PCI_IO_ATTRIBUTE_IDE_PRIMARY_IO 0x0020
EFI_PCI_IO_ATTRIBUTE_IDE_SECONDARY_IO 0x0040
EFI_PCI_IO_ATTRIBUTE_MEMORY_WRITE_COMBINE 0x0080
EFI_PCI_IO_ATTRIBUTE_IO 0x0100
EFI_PCI_IO_ATTRIBUTE_MEMORY 0x0200
EFI_PCI_IO_ATTRIBUTE_BUS_MASTER 0x0400
EFI_PCI_IO_ATTRIBUTE_MEMORY_CACHED 0x0800
EFI_PCI_IO_ATTRIBUTE_MEMORY_DISABLE 0x1000
EFI_PCI_IO_ATTRIBUTE_EMBEDDED_DEVICE 0x2000
EFI_PCI_IO_ATTRIBUTE_EMBEDDED_ROM 0x4000
EFI_PCI_IO_ATTRIBUTE_DUAL_ADDRESS_CYCLE 0x8000
EFI_PCI_IO_ATTRIBUTE_ISA_IO_16 0x10000
EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO_16 0x20000
EFI_PCI_IO_ATTRIBUTE_VGA_IO_16 0x40000

EFI_PCI_IO_ATTRIBUTE_ISA_IO_16
If this bit is set, then the PCI I/O cycles between 0x100 and 0x3FF are forwarded to the PCI controller using a
16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O
cycles for legacy ISA devices. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges
between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles.
This bit may not be combined with EFI_PCI_IO_ATTRIBUTE_ISA_IO.

EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO_16
If this bit is set, then the PCI I/O write cycles for 0x3C6, 0x3C8, and 0x3C9 are forwarded to the PCI controller
using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward
I/O write cycles to the VGA palette registers on a PCI controller. If this bit is set, then the PCI Host Bus Controller
and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured
to forward these PCI I/O cycles. This bit may not be combined with EFI_PCI_IO_ATTRIBUTE_VGA_IO or
EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO.

EFI_PCI_IO_ATTRIBUTE_VGA_IO_16
If this bit is set, then the PCI I/O cycles in the ranges 0x3B0-0x3BB and 0x3C0-0x3DF are forwarded to the PCI
controller using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used
to forward I/O cycles for a VGA controller to a PCI controller. If this bit is set, then the PCI Host Bus Controller
and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles. This bit may not be combined with EFI_PCI_IO_ATTRIBUTE_VGA_IO or EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO. Because EFI_PCI_IO_ATTRIBUTE_VGA_IO_16 also includes the I/O range described by EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO_16, the EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO_16 bit is ignored if EFI_PCI_IO_ATTRIBUTE_VGA_IO_16 is set.

EFI_PCI_IO_ATTRIBUTE_ISA_MOTHERBOARD_IO
If this bit is set, the PCI I/O cycles between 0x00000000 and 0x000000FF are forwarded to the PCI controller. This bit is used to forward I/O cycles for ISA motherboard devices. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles.

EFI_PCI_IO_ATTRIBUTE_ISA_IO
If this bit is set, then the PCI I/O cycles between 0x100 and 0x3FF are forwarded to the PCI controller using a 10-bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and address bits 16..31 must be zero. This bit is used to forward I/O cycles for legacy ISA devices. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles.

EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO
If this bit is set, then the PCI I/O write cycles for 0x3C6, 0x3C8, and 0x3C9 are forwarded to the PCI controller using a 10-bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and address bits 16..31 must be zero. This bit is used to forward I/O write cycles to the VGA palette registers on a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles.

EFI_PCI_IO_ATTRIBUTE_VGA_MEMORY
If this bit is set, then the PCI memory cycles between 0xA0000 and 0xBFFFF are forwarded to the PCI controller. This bit is used to forward memory cycles for a VGA frame buffer on a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI Memory cycles.

EFI_PCI_IO_ATTRIBUTE_VGA_IO
If this bit is set, then the PCI I/O cycles in the ranges 0x3B0-0x3BB and 0x3C0-0x3DF are forwarded to the PCI controller using a 10-bit address decoder on address bits 0..9. Address bits 10..15 are not decoded, and the address bits 16..31 must be zero. This bit is used to forward I/O cycles for a VGA controller to a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles. Since EFI_PCI_IO_ATTRIBUTE_VGA_IO also includes the I/O range described by EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO, the EFI_PCI_IO_ATTRIBUTE_VGA_PALETTE_IO bit is ignored if EFI_PCI_IO_ATTRIBUTE_VGA_IO is set.

EFI_PCI_IO_ATTRIBUTE_IDE_PRIMARY_IO
If this bit is set, then the PCI I/O cycles in the ranges 0x1F0-0x1F7 and 0x3F6-0x3F7 are forwarded to a PCI controller using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for a Primary IDE controller to a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles.

EFI_PCI_IO_ATTRIBUTE_IDE_SECONDARY_IO
If this bit is set, then the PCI I/O cycles in the ranges 0x170-0x177 and 0x376-0x377 are forwarded to a PCI controller using a 16-bit address decoder on address bits 0..15. Address bits 16..31 must be zero. This bit is used to forward I/O cycles for a Secondary IDE controller to a PCI controller. If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are configured to forward these PCI I/O cycles.

EFI_PCI_IO_ATTRIBUTE_MEMORY_WRITE_COMBINE

14.4. EFI PCI I/O Protocol
If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is accessed in a write combining mode. This bit is used to improve the write performance to a memory buffer on a PCI controller. By default, PCI memory ranges are not accessed in a write combining mode.

**EFI_PCI_IO_ATTRIBUTE_MEMORY_CACHED**
If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is accessed in a cached mode. By default, PCI memory ranges are accessed noncached.

**EFI_PCI_IO_ATTRIBUTE_IO**
If this bit is set, then the PCI device will decode the PCI I/O cycles that the device is configured to decode.

**EFI_PCI_IO_ATTRIBUTE_MEMORY**
If this bit is set, then the PCI device will decode the PCI Memory cycles that the device is configured to decode.

**EFI_PCI_IO_ATTRIBUTE_BUS_MASTER**
If this bit is set, then the PCI device is allowed to act as a bus master on the PCI bus.

**EFI_PCI_IO_ATTRIBUTE_MEMORY_DISABLE**
If this bit is set, then this platform supports changing the attributes of a PCI memory range so that the memory range is disabled, and can no longer be accessed. By default, all PCI memory ranges are enabled.

**EFI_PCI_IO_ATTRIBUTE_EMBEDDED_DEVICE**
If this bit is set, then the PCI controller is an embedded device that is typically a component on the system board. If this bit is clear, then this PCI controller is part of an adapter that is populating one of the systems PCI slots.

**EFI_PCI_IO_ATTRIBUTE_EMBEDDED_ROM**
If this bit is set, then the PCI option ROM described by the **RomImage** and **RomSize** fields is not from ROM BAR of the PCI controller. If this bit is clear, then the **RomImage** and **RomSize** fields were initialized based on the PCI option ROM found through the ROM BAR of the PCI controller.

**EFI_PCI_IO_ATTRIBUTE_DUAL_ADDRESS_CYCLE**
If this bit is set, then the PCI controller is capable of producing PCI Dual Address Cycles, so it is able to access a 64-bit address space. If this bit is not set, then the PCI controller is not capable of producing PCI Dual Address Cycles, so it is only able to access a 32-bit address space.

If this bit is set, then the PCI Host Bus Controller and all the PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller are capable of producing PCI Dual Address Cycles. If any of them is not capable of producing PCI Dual Address Cycles, attempt to perform Set or Enable operation using **Attributes()** function with this bit set will fail with the **EFI_UNSUPPORTED** error code.

```c
typedef enum {
  EfiPciIoOperationBusMasterRead,
  EfiPciIoOperationBusMasterWrite,
  EfiPciIoOperationBusMasterCommonBuffer,
  EfiPciIoOperationMaximum
} EFI_PCI_IO_PROTOCOL_OPERATION;
```

**EfiPciIoOperationBusMasterRead**
A read operation from system memory by a bus master.

**EfiPciIoOperationBusMasterWrite**
A write operation to system memory by a bus master.

**EfiPciIoOperationBusMasterCommonBuffer**
Provides both read and write access to system memory by both the processor and a bus master. The buffer is coherent from both the processor’s and the bus master’s point of view.
Description

The *EFI_PCI_IO_PROTOCOL* provides the basic Memory, I/O, PCI configuration, and DMA interfaces that are used to abstract accesses to PCI controllers. There is one *EFI_PCI_IO_PROTOCOL* instance for each PCI controller on a PCI bus. A device driver that wishes to manage a PCI controller in a system will have to retrieve the *EFI_PCI_IO_PROTOCOL* instance that is associated with the PCI controller. A device handle for a PCI controller will minimally contain an *EFI Device Path Protocol* instance and an *EFI_PCI_IO_PROTOCOL* instance.

Bus mastering PCI controllers can use the DMA services for DMA operations. There are three basic types of bus mastering DMA that is supported by this protocol. These are DMA reads by a bus master, DMA writes by a bus master, and common buffer DMA. The DMA read and write operations may need to be broken into smaller chunks. The caller of *EFI_PCI_IO_PROTOCOL.Map()* must pay attention to the number of bytes that were mapped, and if required, loop until the entire buffer has been transferred. The following is a list of the different bus mastering DMA operations that are supported, and the sequence of *EFI_PCI_IO_PROTOCOL* interfaces that are used for each DMA operation type.

**DMA Bus Master Read Operation**

Call *EFI_PCI_IO_PROTOCOL.Map()* for EfiPciIoOperationBusMasterRead.

Program the DMA Bus Master with the *DeviceAddress* returned by *Map()*.

Start the DMA Bus Master.

Wait for DMA Bus Master to complete the read operation.

Call *EFI_PCI_IO_PROTOCOL.Unmap()*.

**DMA Bus Master Write Operation**

Call *Map()* for EfiPciIoOperationBusMasterWrite.

Program the DMA Bus Master with the *DeviceAddress* returned by *Map()*.

Start the DMA Bus Master.

Wait for DMA Bus Master to complete the write operation.

Perform a PCI controller specific read transaction to flush all PCI write buffers (See PCI Specification Section 3.2.5.2).

Call *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.Flush()*.

Call *Unmap()*.

**DMA Bus Master Common Buffer Operation**

Call *EFI_PCI_IO_PROTOCOL.AllocateBuffer()* to allocate a common buffer.

Call *Map()* for EfiPciIoOperationBusMasterCommonBuffer.

Program the DMA Bus Master with the *DeviceAddress* returned by *Map()*.

The common buffer can now be accessed equally by the processor and the DMA bus master.

Call Unmap().

Call *EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL.FreeBuffer()*.
14.4.2 EFI_PCI_IO_PROTOCOL.PollMem()

Summary

Reads from the memory space of a PCI controller. Returns when either the polling exit criteria is satisfied or after a defined duration.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_IO_PROTOCOL_POLL_IO_MEM) (
    IN EFI_PCI_IO_PROTOCOL *This,
    IN EFI_PCI_IO_PROTOCOL_WIDTH Width,
    IN UINT8 BarIndex,
    IN UINT64 Offset,
    IN UINT64 Mask,
    IN UINT64 Value,
    IN UINT64 Delay,
    OUT UINT64 *Result
);
```

Parameters

**This**
A pointer to the EFI PCI I/O Protocol instance. Type EFI_PCI_IO_PROTOCOL is defined in EFI PCI I/O Protocol.

**Width**
Signifies the width of the memory operations, defined in EFI PCI I/O Protocol.

**BarIndex**
The BAR index of the standard PCI Configuration header to use as the base address for the memory operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value EFI_PCI_IO_PASS_THROUGH_BAR can be used to bypass the BAR relative addressing and pass Offset to the PCI Root Bridge I/O Protocol unchanged. Type EFI_PCI_IO_PASS_THROUGH_BAR is defined in EFI_PCI_IO_Protocol.

**Offset**
The offset within the selected BAR to start the memory operation.

**Mask**
Mask used for the polling criteria. Bytes above Width in Mask are ignored. The bits in the bytes below Width which are zero in Mask are ignored when polling the memory address.

**Value**
The comparison value used for the polling exit criteria.

**Delay**
The number of 100 ns units to poll. Note that timer available may be of poorer granularity.

**Result**
Pointer to the last value read from the memory location.

Description

This function provides a standard way to poll a PCI memory location. A PCI memory read operation is performed at the PCI memory address specified by BarIndex and Offset for the width specified by Width. The result of this PCI memory read operation is stored in Result. This PCI memory read operation is repeated until either a timeout of Delay 100 ns units has expired, or (Result & Mask) is equal to Value.
This function will always perform at least one memory access no matter how small Delay may be. If Delay is 0, then Result will be returned with a status of EFI_SUCCESS even if Result does not match the exit criteria. If Delay expires, then EFI_TIMEOUT is returned.

If Width is not EfiPciIoWidthUint8, EfiPciIoWidthUint16, EfiPciIoWidthUint32, or EfiPciIoWidthUint64, then EFI_INVALID_PARAMETER is returned.

The memory operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and memory width restrictions that a PCI controller on a platform might require. For example on some platforms, width requests of EfiPciIoWidthUint64 do not work.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns. However, if the memory mapped I/O region being accessed by this function has the EFI_PCI_IO_ATTRIBUTE_MEMORY_CACHED attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The last data returned from the access matched the poll exit criteria.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Width is invalid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Result is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>BarIndex not valid for this PCI controller.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Offset is not valid for the BarIndex of this PCI controller.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Delay expired before a match occurred.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

#### 14.4.3 EFI_PCI_IO_PROTOCOL.PollIo()

**Summary**

Reads from the I/O space of a PCI controller. Returns when either the polling exit criteria is satisfied or after a defined duration.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_IO_PROTOCOL_POLL_IO_MEM) ( 
    IN EFI_PCI_IO_PROTOCOL *This, 
    IN EFI_PCI_IO_PROTOCOL_WIDTH Width, 
    IN UINT8 BarIndex, 
    IN UINT64 Offset, 
    IN UINT64 Mask, 
    IN UINT64 Value, 
    IN UINT64 Delay, 
    OUT UINT64 *Result
);
```

**Parameters**

**This**

A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in See EFI PCI I/O Protocol.

**Width**

Signifies the width of the I/O operations. Type EFI_PCI_IO_PROTOCOL_WIDTH, defined in EFI_PCI I/O Protocol.
BarIndex
The BAR index of the standard PCI Configuration header to use as the base address for the I/O operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value EFI_PCI_IO_PASS_THROUGH_BAR can be used to bypass the BAR relative addressing and pass Offset to the PCI Root Bridge I/O Protocol unchanged. Type EFI_PCI_IO_PASS_THROUGH_BAR is defined in EFI_PCI_IO_Protocol.

Offset
The offset within the selected BAR to start the I/O operation.

Mask
Mask used for the polling criteria. Bytes above Width in Mask are ignored. The bits in the bytes below Width which are zero in Mask are ignored when polling the I/O address.

Value
The comparison value used for the polling exit criteria.

Delay
The number of 100 ns units to poll. Note that timer available may be of poorer granularity.

Result
Pointer to the last value read from the memory location.

Description
This function provides a standard way to poll a PCI I/O location. A PCI I/O read operation is performed at the PCI I/O address specified by BarIndex and Offset for the width specified by Width. The result of this PCI I/O read operation is stored in Result. This PCI I/O read operation is repeated until either a timeout of Delay 100 ns units has expired, or (Result & Mask) is equal to Value.

This function will always perform at least one I/O access no matter how small Delay may be. If Delay is 0, then Result will be returned with a status of EFI_SUCCESS even if Result does not match the exit criteria. If Delay expires, then EFI_TIMEOUT is returned.

If Width is not EfiPciIoWidthUint8, EfiPciIoWidthUint16, EfiPciIoWidthUint32, or EfiPciIoWidthUint64, then EFI_INVALID_PARAMETER is returned.

The I/O operations are carried out exactly as requested. The caller is responsible satisfying any alignment and I/O width restrictions that the PCI controller on a platform might require. For example on some platforms, width requests of EfiPciIoWidthUint64 do not work.

All the PCI read transactions generated by this function are guaranteed to be completed before this function returns.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
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<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The last data returned from the access matched the poll exit criteria.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Width is invalid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Result is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>BarIndex not valid for this PCI controller.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Offset is not valid for the PCI BAR specified by BarIndex.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Delay expired before a match occurred.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>
14.4.4 EFI_PCI_IO_PROTOCOL.Mem.Read()

14.4.5 EFI_PCI_IO_PROTOCOL.Mem.Write()

Summary
Enable a PCI driver to access PCI controller registers in the PCI memory space.

Prototype

```c
typedef EFI_STATUS
    (EFIAPI *EFI_PCI_IO_PROTOCOL_MEM) (  
    IN EFI_PCI_IO_PROTOCOL *This,
    IN EFI_PCI_IO_PROTOCOL_WIDTH Width,
    IN UINT8 BarIndex,
    IN UINT64 Offset,
    IN UINTN Count,
    IN OUT VOID *Buffer
    )
```

Parameters

This
A pointer to the See **EFI_PCI_IO_PROTOCOL** instance. Type EFI_PCI_IO_PROTOCOL is defined in **EFI PCI I/O Protocol**.

Width
Signifies the width of the memory operations. Type EFI_PCI_IO_PROTOCOL_WIDTH, defined in **EFI PCI I/O Protocol**.

BarIndex
The BAR index of the standard PCI Configuration header to use as the base address for the memory operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value **EFI_PCI_IO_PASS_THROUGH_BAR** can be used to bypass the BAR relative addressing and pass Offset to the PCI Root Bridge I/O Protocol unchanged. Type EFI_PCI_IO_PASS_THROUGH_BAR is defined in **EFI_PCI_IO_Protocol**.

Offset
The offset within the selected BAR to start the memory operation.

Count
The number of memory operations to perform. Bytes moved is Width size * Count, starting at Offset.

Buffer
For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.

Description
The Mem.Read() , and Mem.Write() functions enable a driver to access controller registers in the PCI memory space. The I/O operations are carried out exactly as requested. The caller is responsible for any alignment and I/O width issues which the bus, device, platform, or type of I/O might require. For example on some platforms, width requests of EfiPciIoWidthUint64 do not work.
If \textit{Width} is \texttt{EfiPciIoWidthUint8}, \texttt{EfiPciIoWidthUint16}, \texttt{EfiPciIoWidthUint32}, or \texttt{EfiPciIoWidthUint64}, then both \textit{Address} and \textit{Buffer} are incremented for each of the \textit{Count} operations performed.

If \textit{Width} is \texttt{EfiPciIoWidthFifoUint8}, \texttt{EfiPciIoWidthFifoUint16}, \texttt{EfiPciIoWidthFifoUint32}, or \texttt{EfiPciIoWidthFifoUint64}, then only \textit{Buffer} is incremented for each of the \textit{Count} operations performed. The read or write operation is performed \textit{Count} times on the same \textit{Address}.

If \textit{Width} is \texttt{EfiPciIoWidthFillUint8}, \texttt{EfiPciIoWidthFillUint16}, \texttt{EfiPciIoWidthFillUint32}, or \texttt{EfiPciIoWidthFillUint64}, then only \textit{Address} is incremented for each of the \textit{Count} operations performed. The read or write operation is performed \textit{Count} times from the first element of \textit{Buffer}.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns. All the PCI write transactions generated by this function will follow the write ordering and completion rules defined in the PCI Specification. However, if the memory-mapped I/O region being accessed by this function has the \texttt{EFI_PCI_IO_ATTRIBUTE_MEMORY_CACHED} attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

\textbf{Status Codes Returned}

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was read from or written to the PCI controller.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Width is invalid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Buffer is \texttt{NULL}.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>BarIndex not valid for this PCI controller.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The address range specified by Offset, Width, and Count is not valid for the PCI BAR specified by BarIndex.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

\subsection{14.4.6 EFI_PCI_IO_PROTOCOL.Io.Read()}

\subsection{14.4.7 EFI_PCI_IO_PROTOCOL.Io.Write()}

\textbf{Summary}

Enable a PCI driver to access PCI controller registers in the PCI I/O space.

\textbf{Prototype}

\begin{verbatim}
typedef EFI_STATUS (EFIAPI *EFI_PCI_IO_PROTOCOL_MEM) (  
  IN EFI_PCI_IO_PROTOCOL This,  
  IN EFI_PCI_IO_PROTOCOL_WIDTH Width,  
  IN UINT8 BarIndex,  
  IN UINT64 Offset,  
  IN UINTN Count,  
  IN OUT VOID Buffer  
);  
\end{verbatim}

\textbf{Parameters}

\textbf{This}

A pointer to the \texttt{EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL} instance. Type \texttt{EFI_PCI_IO_PROTOCOL} is defined in \texttt{EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL}.  

\section{14.4. EFI PCI I/O Protocol}

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Width
Signifies the width of the memory operations. Type EFI_PCI_IO_PROTOCOL_WIDTH, defined in EFI PCI I/O Protocol.

BarIndex
The BAR index of the standard PCI Configuration header to use as the base address for the I/O operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value EFI_PCI_IO_PASS_THROUGH_BAR can be used to bypass the BAR relative addressing and pass Offset to the PCI Root Bridge I/O Protocol unchanged. Type EFI_PCI_IO_PASS_THROUGH_BAR is defined in EFI_PCI_IO_Protocol.

Offset
The offset within the selected BAR to start the I/O operation.

Count
The number of I/O operations to perform. Bytes moved is Width size * Count, starting at Offset.

Buffer
For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.

Description
The Io.Read() and Io.Write() functions enable a driver to access PCI controller registers in PCI I/O space.

The I/O operations are carried out exactly as requested. The caller is responsible for any alignment and I/O width issues which the bus, device, platform, or type of I/O might require. For example on some platforms, width requests of EfiPciloWidthUint64 do not work.

If Width is EfiPciloWidthUint8, EfiPciloWidthUint16, EfiPciloWidthUint32, or EfiPciloWidthUint64, then both Address and Buffer are incremented for each of the Count operations performed.

If Width is EfiPciloWidthFifoUint8, EfiPciloWidthFifoUint16, EfiPciloWidthFifoUint32, or EfiPciloWidthFifoUint64, then only Buffer is incremented for each of the Count operations performed. The read or write operation is performed Count times on the same Address.

If Width is EfiPciloWidthFillUint8, EfiPciloWidthFillUint16, EfiPciloWidthFillUint32, or EfiPciloWidthFillUint64, then only Address is incremented for each of the Count operations performed. The read or write operation is performed Count times from the first element of Buffer.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was read from or written to the PCI controller.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Width is invalid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>BarIndex not valid for this PCI controller.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The address range specified by Offset, Width, and Count is not valid for the PCI BAR specified by BarIndex.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>
14.4.8 EFI_PCI_IO_PROTOCOL.Pci.Read()

14.4.9 EFI_PCI_IO_PROTOCOL.Pci.Write()

Summary

Enable a PCI driver to access PCI controller registers in PCI configuration space.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_IO_PROTOCOL_CONFIG) (
    IN EFI_PCI_IO_PROTOCOL *This,
    IN EFI_PCI_IO_PROTOCOL_WIDTH Width,
    IN UINT32 Offset,
    IN UINTN Count,
    IN OUT VOID *Buffer
    );
```

Parameters

This

A pointer to the See EFI PCI I/O Protocol instance. Type EFI_PCI_IO_PROTOCOL is defined in See EFI PCI I/O Protocol.

Width

Signifies the width of the memory operations. Type EFI_PCI_IO_PROTOCOL_WIDTH, defined in EFI PCI I/O Protocol.

Offset

The offset within the PCI configuration space for the PCI controller.

Count

The number of PCI configuration operations to perform. Bytes moved is Width size * Count, starting at Offset.

Buffer

For read operations, the destination buffer to store the results. For write operations, the source buffer to write data from.

Description

The Pci.Read() and Pci.Write() functions enable a driver to access PCI configuration registers for the PCI controller.

The PCI Configuration operations are carried out exactly as requested. The caller is responsible for any alignment and I/O width issues which the bus, device, platform, or type of I/O might require. For example on some platforms, width requests of EfiPciIoWidthUint64 do not work.

If Width is EfiPciIoWidthUint8, EfiPciIoWidthUint16, EfiPciIoWidthUint32, or EfiPciIoWidthUint64, then both Address and Buffer are incremented for each of the Count operations performed.

If Width is EfiPciIoWidthFifoUint8, EfiPciIoWidthFifoUint16, EfiPciIoWidthFifoUint32, or EfiPciIoWidthFifoUint64, then only Buffer is incremented for each of the Count operations performed. The read or write operation is performed Count times on the same Address.

If Width is EfiPciIoWidthFillUint8, EfiPciIoWidthFillUint16, EfiPciIoWidthFillUint32, or EfiPciIoWidthFillUint64, then only Address is incremented for each of the Count operations performed. The read or write operation is performed Count times from the first element of Buffer.
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

All the PCI transactions generated by this function are guaranteed to be completed before this function returns.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was read from or written to the PCI controller.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Width is invalid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The address range specified by Offset, Width, and Count is not valid for the PCI configuration header of the PCI controller.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

### 14.4.10 EFI_PCI_IO_PROTOCOL.CopyMem()

**Summary**

Enables a PCI driver to copy one region of PCI memory space to another region of PCI memory space.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_IO_PROTOCOL_COPY_MEM)(
    IN EFI_PCI_IO_PROTOCOL *This,
    IN EFI_PCI_IO_PROTOCOL_WIDTH Width,
    IN UINT8 DestBarIndex,
    IN UINT64 DestOffset,
    IN UINT8 SrcBarIndex,
    IN UINT64 SrcOffset,
    IN UINTN Count);
```

**Parameters**

- **This**
  A pointer to the **EFI_PCI_IO_PROTOCOL** instance. Type **EFI_PCI_IO_PROTOCOL** is defined in **EFI_PCI_IO_Protocol**.

- **Width**
  Signifies the width of the memory operations. Type **EFI_PCI_IO_PROTOCOL_WIDTH**, defined in **EFI PCI I/O Protocol**.

- **DestBarIndex**
  The BAR index of the standard PCI Configuration header to use as the base address for the memory operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value **EFI_PCI_IO_PASS_THROUGH_BAR** can be used to bypass the BAR relative addressing and pass **Offset** to the PCI Root Bridge I/O Protocol unchanged. Type **EFI_PCI_IO_PASS_THROUGH_BAR** is defined in **EFI_PCI_IO_Protocol**.

- **DestOffset**
  The destination offset within the BAR specified by DestBarIndex to start the memory writes for the copy operation. The caller is responsible for aligning the DestOffset if required.

- **SrcBarIndex**
  The BAR index of the standard PCI Configuration header to use as the base address for the memory operation to perform. This allows all drivers to use BAR relative addressing. The legal range for this field is 0..5. However, the value **EFI_PCI_IO_PASS_THROUGH_BAR** can be used to bypass the BAR relative addressing and pass
Offset to the PCI Root Bridge I/O Protocol unchanged. Type EFI_PCI_IO_PASS_THROUGH_BAR is defined in EFI_PCI_IO_Protocol.

SrcOffset
The source offset within the BAR specified by SrcBarIndex to start the memory reads for the copy operation. The caller is responsible for aligning the SrcOffset if required.

Count
The number of memory operations to perform. Bytes moved is Width size * Count, starting at DestOffset and SrcOffset.

Description
The CopyMem() function enables a PCI driver to copy one region of PCI memory space to another region of PCI memory space on a PCI controller. This is especially useful for video scroll operations on a memory mapped video buffer.

The memory operations are carried out exactly as requested. The caller is responsible for satisfying any alignment and memory width restrictions that a PCI controller on a platform might require. For example on some platforms, width requests of EfiPciIoWidthUint64 do not work.

If Width is EfiPciIoWidthUint8, EfiPciIoWidthUint16, EfiPciIoWidthUint32, or EfiPciIoWidthUint64, then Count read/write transactions are performed to move the contents of the SrcOffset buffer to the DestOffset buffer. The implementation must be reentrant, and it must handle overlapping SrcOffset and DestOffset buffers. This means that the implementation of CopyMem() must choose the correct direction of the copy operation based on the type of overlap that exists between the SrcOffset and DestOffset buffers. If either the SrcOffset buffer or the DestOffset buffer crosses the top of the processor’s address space, then the result of the copy operation is unpredictable.

The contents of the DestOffset buffer on exit from this service must match the contents of the SrcOffset buffer on entry to this service. Due to potential overlaps, the contents of the SrcOffset buffer may be modified by this service. The following rules can be used to guarantee the correct behavior:

- If DestOffset > SrcOffset and DestOffset < (SrcOffset + Width size * Count), then the data should be copied from the SrcOffset buffer to the DestOffset buffer starting from the end of buffers and working toward the beginning of the buffers.
- Otherwise, the data should be copied from the SrcOffset buffer to the DestOffset buffer starting from the beginning of the buffers and working toward the end of the buffers.

All the PCI transactions generated by this function are guaranteed to be completed before this function returns. All the PCI write transactions generated by this function will follow the write ordering and completion rules defined in the PCI Specification. However, if the memory-mapped I/O region being accessed by this function has the EFI_PCI_IO_ATTRIBUTE_MEMORY_CACHED attribute set, then the transactions will follow the ordering rules defined by the processor architecture.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was copied from one memory region to another memory region.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Width is invalid.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>DestBarIndex not valid for this PCI controller.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>SrcBarIndex not valid for this PCI controller.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The address range specified by DestOffset, Width, and Count is not valid for the PCI BAR specified by DestBarIndex.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The address range specified by SrcOffset, Width, and Count is not valid for the PCI BAR specified by SrcBarIndex.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>
14.4.11 EFI_PCI_IO_PROTOCOL.Map()

Summary
Provides the PCI controller-specific addresses needed to access system memory.

Prototype

```c
typedef EFI_STATUS
    (EFIAPI *EFI_PCI_IO_PROTOCOL_MAP) (
    IN EFI_PCI_IO_PROTOCOL *This,
    IN EFI_PCI_IO_PROTOCOL_OPERATION Operation,
    IN VOID *HostAddress,
    IN OUT UINTN *NumberOfBytes,
    OUT EFI_PHYSICAL_ADDRESS *DeviceAddress,
    OUT VOID **Mapping
    );
```

Parameters

This
A pointer to the EFI_PCI_ROOT_BRIDGE_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in See EFI PCI I/O Protocol.

Operation
Indicates if the bus master is going to read or write to system memory. Type EFI_PCI_IO_PROTOCOL_OPERATION is defined in See EFI PCI I/O Protocol.

HostAddress
The system memory address to map to the PCI controller.

NumberOfBytes
On input the number of bytes to map. On output the number of bytes that were mapped.

DeviceAddress
The resulting map address for the bus master PCI controller to use to access the hosts HostAddress. Type EFI_PHYSICAL_ADDRESS is defined in EFI_BOOT_SERVICES.AllocatePool(). This address cannot be used by the processor to access the contents of the buffer specified by HostAddress.

Mapping
A resulting value to pass to EFI-PCI-IO-PROTOCOL-Unmap() .

Description
The EFI_PCI_IO_PROTOCOL.Map() function provides the PCI controller-specific addresses needed to access system memory. This function is used to map system memory for PCI bus master DMA accesses.

All PCI bus master accesses must be performed through their mapped addresses and such mappings must be freed with EFI_PCI_IO_PROTOCOL-Unmap() when complete. If the bus master access is a single read or write data transfer, then EfiPciIoOperationBusMasterRead or EfiPciIoOperation-BusMasterWrite is used and the range is unmapped to complete the operation. If performing an EfiPciIoOperationBusMasterRead operation, all the data must be present in system memory before the Map() is performed. Similarly, if performing an EfiPciIoOperation-BusMasterWrite, the data cannot be properly accessed in system memory until Unmap() is performed.

Bus master operations that require both read and write access or require multiple host device interactions within the same mapped region must use EfiPciIoOperation-BusMasterCommonBuffer. However, only memory allocated via the EFI_PCI_IO_PROTOCOL.AllocateBuffer() interface can be mapped for this operation type.

In all mapping requests the resulting NumberOfBytes actually mapped may be less than the requested amount. In this case, the DMA operation will have to be broken up into smaller chunks. The Map() function will map as much of the
DMA operation as it can at one time. The caller may have to loop on Map() and Unmap() in order to complete a large DMA transfer.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The range was mapped for the returned NumberOfBytes.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Operation is invalid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HostAddress is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>NumberOfBytes is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DeviceAddress is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Mapping is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The HostAddress cannot be mapped as a common buffer.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The system hardware could not map the requested address.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

14.4.12 EFI-PCI-IO-PROTOCOL-Unmap()

Summary
Completes the EFI_PCI_IO_PROTOCOL.Map() operation and releases any corresponding resources.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_IO_PROTOCOL_UNMAP) (
  IN EFI_PCI_IO_PROTOCOL *This,
  IN VOID *Mapping
);
```

Parameters

**This**
A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in EFI PCI I/O Protocol.

**Mapping**
The mapping value returned from Map().

Description
The Unmap() function completes the Map() operation and releases any corresponding resources. If the operation was an EfiPciIoOperationBusMasterWrite, the data is committed to the target system memory. Any resources used for the mapping are freed.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The range was unmapped.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The data was not committed to the target system memory.</td>
</tr>
</tbody>
</table>
### 14.4.13 EFI_PCI_IO_PROTOCOL.AllocateBuffer()

**Summary**

Allocates pages that are suitable for an *EfiPciIoOperationBusMasterCommonBuffer* mapping.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_IO_PROTOCOL_ALLOCATE_BUFFER) (
  IN EFI_PCI_IO_PROTOCOL *This,
  IN EFI_ALLOCATE_TYPE Type,
  IN EFI_MEMORY_TYPE MemoryType,
  IN UINTN Pages,
  OUT VOID **HostAddress,
  IN UINT64 Attributes
);
```

**Parameters**

**This**

A pointer to the See *EFI PCI I/O Protocol* instance. Type EFI_PCI_IO_PROTOCOL is defined in *EFI PCI I/O Protocol*.

**Type**

This parameter is not used and must be ignored.

**MemoryType**

The type of memory to allocate, *EfiBootServicesData* or *EfiRuntimeServicesData*. Type EFI_MEMORY_TYPE is defined in *EFI_PCI_IO_PROTOCOL.AllocateBuffer()*.

**Pages**

The number of pages to allocate.

**HostAddress**

A pointer to store the base system memory address of the allocated range.

**Attributes**

The requested bit mask of attributes for the allocated range. Only the attributes *EFI_PCI_IO_ATTRIBUTE_MEMORY_WRITE_COMBINE*, and *EFI_PCI_IO_ATTRIBUTE_MEMORY_CACHED* may be used with this function. If any other bits are set, then EFI_UNSUPPORTED is returned. This function may choose to ignore this bit mask. The *EFI_PCI_IO_ATTRIBUTE_MEMORY_WRITE_COMBINE*, and *EFI_PCI_IO_ATTRIBUTE_MEMORY_CACHED* attributes provide a hint to the implementation that may improve the performance of the calling driver. The implementation may choose any default for the memory attributes including write combining, cached, both, or neither as long as the allocated buffer can be seen equally by both the processor and the PCI bus master.

**Description**

The *AllocateBuffer()* function allocates pages that are suitable for an *EfiPciIoOperationBusMasterCommonBuffer* mapping. This means that the buffer allocated by this function must support simultaneous access by both the processor and a PCI Bus Master. The device address that the PCI Bus Master uses to access the buffer can be retrieved with a call to *EFI_PCI_IO_PROTOCOL.Map()*.
If the current attributes of the PCI controller has the `EFI_PCI_IO_ATTRIBUTE_DUAL_ADDRESS_CYCLE` bit set, then when the buffer allocated by this function is mapped with a call to `Map()`, the device address that is returned by `Map()` must be within the 64-bit device address space of the PCI Bus Master. The attributes for a PCI controller can be managed by calling `EFI_PCI_IO_PROTOCOL.Attributes()`.

If the current attributes for the PCI controller has the `EFI_PCI_IO_ATTRIBUTE_DUAL_ADDRESS_CYCLE` bit clear, then when the buffer allocated by this function is mapped with a call to `Map()`, the device address that is returned by `Map()` must be within the 32-bit device address space of the PCI Bus Master. The attributes for a PCI controller can be managed by calling `Attributes()`.

If the memory allocation specified by `MemoryType` and `Pages` cannot be satisfied, then `EFI_OUT_OF_RESOURCES` is returned.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Message</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested memory pages were allocated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>MemoryType is invalid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HostAddress is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Attributes is unsupported. The only legal attribute bits are <code>MEMORY_WRITE_COMBINE</code> and <code>MEMORY_CACHED</code>.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The memory pages could not be allocated.</td>
</tr>
</tbody>
</table>

### 14.4.14 EFI_PCI_IO_PROTOCOL.FreeBuffer()

**Summary**

Frees memory that was allocated with `EFI_PCI_IO_PROTOCOL.AllocateBuffer()`.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_IO_PROTOCOL_FREE_BUFFER) (  
  IN EFI_PCI_IO_PROTOCOL ^This,  
  IN UINTN Pages,  
  IN VOID ^HostAddress  
);
```

**Parameters**

- **This**
  - A pointer to the `EFI_PCI_IO_PROTOCOL` instance. Type `EFI_PCI_IO_PROTOCOL` is defined in `EFI PCI I/O Protocol`.

- **Pages**
  - The number of pages to free.

- **HostAddress**
  - The base system memory address of the allocated range.

**Description**

The `FreeBuffer()` function frees memory that was allocated with `AllocateBuffer()`.

**Status Codes Returned**
14.4.15 EFI_PCI_IO_PROTOCOL.Flush()

Summary
Flushes all PCI posted write transactions from a PCI host bridge to system memory.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_PCI_IO_PROTOCOL_FLUSH) (
    IN EFI_PCI_IO_PROTOCOL *This
);

Parameters

This
A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in EFI PCI I/O Protocol.

Description
The Flush() function flushes any PCI posted write transactions from a PCI host bridge to system memory. Posted write transactions are generated by PCI bus masters when they perform write transactions to target addresses in system memory.

This function does not flush posted write transactions from any PCI bridges. A PCI controller specific action must be taken to guarantee that the posted write transactions have been flushed from the PCI controller and from all the PCI bridges into the PCI host bridge. This is typically done with a PCI read transaction from the PCI controller prior to calling Flush().

If the PCI controller specific action required to flush the PCI posted write transactions has been performed, and this function returns EFI_SUCCESS, then the PCI bus master's view and the processor's view of system memory are guaranteed to be coherent. If the PCI posted write transactions cannot be flushed from the PCI host bridge, then the PCI bus master and processor are not guaranteed to have a coherent view of system memory, and EFI_DEVICE_ERROR is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The PCI posted write transactions were flushed from the PCI host bridge to system memory.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The PCI posted write transactions were not flushed from the PCI host bridge due to a hardware error.</td>
</tr>
</tbody>
</table>
14.4.16 EFI_PCI_IO_PROTOCOL.GetLocation()

Summary
Retrieves this PCI controller’s current PCI bus number, device number, and function number.

Prototype

```
typedef
EFI_STATUS
(EIFIAPI *EFI_PCI_IO_PROTOCOL_GET_LOCATION) (
    IN EFI_PCI_IO_PROTOCOL *This,
    OUT UINTN *SegmentNumber,
    OUT UINTN *BusNumber,
    OUT UINTN *DeviceNumber,
    OUT UINTN *FunctionNumber
);
```

Parameters

This
A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in EFI_PCI_I/O Protocol.

SegmentNumber
The PCI controller’s current PCI segment number.

BusNumber
The PCI controller’s current PCI bus number.

DeviceNumber
The PCI controller’s current PCI device number.

FunctionNumber
The PCI controller’s current PCI function number.

Description
The GetLocation() function retrieves a PCI controller’s current location on a PCI Host Bridge. This is specified by a PCI segment number, PCI bus number, PCI device number, and PCI function number. These values can be used with the PCI Root Bridge I/O Protocol to perform PCI configuration cycles on the PCI controller, or any of its peer PCI controller’s on the same PCI Host Bridge.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The PCI controller location was returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>SegmentNumber is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>BusNumber is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DeviceNumber is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>FunctionNumber is NULL.</td>
</tr>
</tbody>
</table>
14.4.17 EFI_PCI_IO_PROTOCOL.Attributes()

Summary
Performs an operation on the attributes that this PCI controller supports. The operations include getting the set of supported attributes, retrieving the current attributes, setting the current attributes, enabling attributes, and disabling attributes.

Prototype

```c
typedef EFI_STATUS (EFIAPICALLNAME *EFI_PCI_IO_PROTOCOL_ATTRIBUTES) (  
  IN EFI_PCI_IO_PROTOCOL *This,  
  IN EFI_PCI_IO_PROTOCOL_ATTRIBUTE_OPERATION Operation,  
  IN UINT64 Attributes,  
  OUT UINT64 *Result OPTIONAL
);
```

Parameters
This
A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in EFI PCI I/O Protocol.

Operation
The operation to perform on the attributes for this PCI controller. Type EFI_PCI_IO_PROTOCOL_ATTRIBUTE_OPERATION is defined in “Related Definitions” below.

Attributes
The mask of attributes that are used for Set, Enable, and Disable operations. The available attributes are listed in See EFI PCI I/O Protocol.

Result
A pointer to the result mask of attributes that are returned for the Get and Supported operations. This is an optional parameter that may be NULL for the Set, Enable, and Disable operations. The available attributes are listed in EFI PCI I/O Protocol.

Related Definitions

```c
//****************************
// EFI_PCI_IO_PROTOCOL_ATTRIBUTE_OPERATION
//****************************
typedef enum {
  EfiPciIoAttributeOperationGet,
  EfiPciIoAttributeOperationSet,
  EfiPciIoAttributeOperationEnable,
  EfiPciIoAttributeOperationDisable,
  EfiPciIoAttributeOperationSupported,
  EfiPciIoAttributeOperationMaximum
} EFI_PCI_IO_PROTOCOL_ATTRIBUTE_OPERATION;
```

EfiPciIoAttributeOperationGet
Retrieve the PCI controller’s current attributes, and return them in Result. If Result is NULL, then EFI_INVALID_PARAMER is returned. For this operation, Attributes is ignored.
EfiPciIoAttributeOperationSet

Set the PCI controller’s current attributes to Attributes. If a bit is set in Attributes that is not supported by this PCI controller or one of its parent bridges, then EFI_UNSUPPORTED is returned. For this operation, Result is an optional parameter that may be NULL.

EfiPciIoAttributeOperationEnable

Enable the attributes specified by the bits that are set in Attributes for this PCI controller. Bits in Attributes that are clear are ignored. If a bit is set in Attributes that is not supported by this PCI controller or one of its parent bridges, then EFI_UNSUPPORTED is returned. For this operation, Result is an optional parameter that may be NULL.

EfiPciIoAttributeOperationDisable

Disable the attributes specified by the bits that are set in Attributes for this PCI controller. Bits in Attributes that are clear are ignored. If a bit is set in Attributes that is not supported by this PCI controller or one of its parent bridges, then EFI_UNSUPPORTED is returned. For this operation, Result is an optional parameter that may be NULL.

EfiPciIoAttributeOperationSupported

Retrieve the PCI controller’s supported attributes, and return them in Result. If Result is NULL, then EFI_INVALID_PARAMETER is returned. For this operation, Attributes is ignored.

Description

The Attributes() function performs an operation on the attributes associated with this PCI controller. If Operation is greater than or equal to the maximum operation value, then EFI_INVALID_PARAMETER is returned. If Operation is Get or Supported, and Result is NULL, then EFI_INVALID_PARAMETER is returned. If Operation is Set, Enable, or Disable for an attribute that is not supported by the PCI controller, then EFI_UNSUPPORTED is returned. Otherwise, the operation is performed as described in “Related Definitions” and EFI_SUCCESS is returned. It is possible for this function to return EFI_UNSUPPORTED even if the PCI controller supports the attribute. This can occur when the PCI root bridge does not support the attribute. For example, if VGA I/O and VGA Memory transactions cannot be forwarded onto PCI root bridge #2, then a request by a PCI VGA driver to enable the VGA_IO and VGA_MEMORY bits will fail even though a PCI VGA controller behind PCI root bridge #2 is able to decode these transactions.

This function will also return EFI_UNSUPPORTED if more than one PCI controller on the same PCI root bridge has already successfully requested one of the ISA addressing attributes. For example, if one PCI VGA controller had already requested the VGA_IO and VGA_MEMORY attributes, then a second PCI VGA controller on the same root bridge cannot succeed in requesting those same attributes. This restriction applies to the ISA-, VGA-, and IDE-related attributes.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation on the PCI controller’s attributes was completed. If the operation was Get or Supported, then the attribute mask is returned in Result.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Operation is greater than or equal to EfiPciIoAttributeOperationMaximum.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Operation is Get and Result is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Operation is Supported and Result is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Operation is Set, and one or more of the bits set in Attributes are not supported by this PCI controller or one of its parent bridges.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Operation is Enable, and one or more of the bits set in Attributes are not supported by this PCI controller or one of its parent bridges.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Operation is Disable, and one or more of the bits set in Attributes are not supported by this PCI controller or one of its parent bridges.</td>
</tr>
</tbody>
</table>
14.4.18 EFI_PCI_IO_PROTOCOL.GetBarAttributes()

Summary

Gets the attributes that this PCI controller supports setting on a BAR using EFI_PCI_IO_PROTOCOL.SetBarAttributes(), and retrieves the list of resource descriptors for a BAR.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_PCI_IO_PROTOCOL_GET_BAR_ATTRIBUTES) (
    IN EFI_PCI_IO_PROTOCOL *This,
    IN UINT8 BarIndex,
    OUT UINT64 *Supports OPTIONAL,
    OUT VOID **Resources OPTIONAL
);
```

Parameters

This

A pointer to the EFI_PCI_IO_PROTOCOL instance. Type EFI_PCI_IO_PROTOCOL is defined in EFI PCI I/O Protocol.

BarIndex

The BAR index of the standard PCI Configuration header to use as the base address for resource range. The legal range for this field is 0..5.

Supports

A pointer to the mask of attributes that this PCI controller supports setting for this BAR with SetBarAttributes(). The list of attributes is listed in See EFI PCI I/O Protocol. This is an optional parameter that may be NULL.

Resources

A pointer to the resource descriptors that describe the current configuration of this BAR of the PCI controller. This buffer is allocated for the caller with the Boot Service EFI_BOOT_SERVICES.AllocatePool(). It is the caller’s responsibility to free the buffer with the Boot Service EFI_BOOT_SERVICES.FreePool(). See “Related Definitions” below for the resource descriptors that may be used. This is an optional parameter that may be NULL.

Related Definitions

There are only two resource descriptor types from the ACPI Specification that may be used to describe the current resources allocated to BAR of a PCI Controller. These are the QWORD Address Space Descriptor, and the End Tag. The QWORD Address Space Descriptor can describe memory, I/O, and bus number ranges for dynamic or fixed resources. The configuration of a BAR of a PCI Controller is described with one or more QWORD Address Space Descriptors followed by an End Tag. The Tables below contain these two descriptor types. Please see the ACPI Specification for details on the field values. The ACPI Specification does not define how to use the Address Translation Offset for non-bridge devices. The UEFI Specification is extending the definition of Address Translation Offset to support systems that have different mapping for HostAddress and DeviceAddress. The definition of the Address Space Granularity field in the QWORD Address Space Descriptor differs from the ACPI Specification and the definition in the table below is the one that must be used.
Table 14.37: QWORD Address Space Descriptor

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x8A</td>
<td>QWORD Address Space Descriptor</td>
</tr>
<tr>
<td>0x01</td>
<td>0x02</td>
<td>0x2B</td>
<td>Length of this descriptor in bytes not including the first two fields</td>
</tr>
<tr>
<td>0x03</td>
<td>0x01</td>
<td></td>
<td>Resource Type</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0 - Memory Range</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>1 - I/O Range</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>2 - Bus Number Range</td>
</tr>
<tr>
<td>0x04</td>
<td>0x01</td>
<td></td>
<td>General Flags</td>
</tr>
<tr>
<td>0x05</td>
<td>0x01</td>
<td></td>
<td>Type Specific Flags</td>
</tr>
<tr>
<td>0x06</td>
<td>0x08</td>
<td></td>
<td>Address Space Granularity.Used to differentiate between a 32-bit memory request and a 64-bit memory request. For a 32-bit memory request, this field should be set to 32. For a 64-bit memory request, this field should be set to 64.</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x08</td>
<td></td>
<td>Address Range Minimum. Starting address of BAR.</td>
</tr>
<tr>
<td>0x16</td>
<td>0x08</td>
<td></td>
<td>Address Range Maximum. Ending address of BAR.</td>
</tr>
<tr>
<td>0x1E</td>
<td>0x08</td>
<td></td>
<td>Address Translation Offset. Offset to apply to the Starting address of a BAR to convert it to a PCI address. This value is zero unless the HostAddress and DeviceAddress for the BAR are different.</td>
</tr>
<tr>
<td>0x26</td>
<td>0x08</td>
<td></td>
<td>Address Length</td>
</tr>
</tbody>
</table>

Table 14.38: End Tag

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x79</td>
<td>End Tag</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x00</td>
<td>Checksum. If 0, then checksum is assumed to be valid.</td>
</tr>
</tbody>
</table>

Description

The GetBarAttributes() function returns in Supports the mask of attributes that the PCI controller supports setting for the BAR specified by BarIndex. It also returns in Resources a list of resource descriptors for the BAR specified by BarIndex. Both Supports and Resources are optional parameters. If both Supports and Resources are NULL, then EFI_INVALID_PARAMETER is returned. It is the caller’s responsibility to free Resources with the Boot Service EFI_BOOT_SERVICES.FreePool() when the caller is done with the contents of Resources. If there are not enough resources to allocate Resources, then EFI_OUT_OF_RESOURCES is returned.

If a bit is set in Supports, then the PCI controller supports this attribute type for the BAR specified by BarIndex, and a call can be made to EFI_PCI_IO_PROTOCOL.SetBarAttributes() using that attribute type.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>If Supports is not NULL, then the attributes that the PCI controller supports are returned in Supports. If Resources is not NULL, then the resource descriptors that the PCI controller is currently using are returned in Resources.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There are not enough resources available to allocate Resources.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>BarIndex not valid for this PCI controller.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Both Supports and Attributes are NULL.</td>
</tr>
</tbody>
</table>

14.4. EFI PCI I/O Protocol
**14.4.19 EFI_PCI_IO_PROTOCOL.SetBarAttributes()**

**Summary**
Sets the attributes for a range of a BAR on a PCI controller.

**Prototype**
```c
typedef
EFI_STATUS
(EFIAPI *EFI_PCI_IO_PROTOCOL_SET_BAR_ATTRIBUTES) (  
    IN EFI_PCI_IO_PROTOCOL *This,
    IN UINT64 Attributes,
    IN UINT8 BarIndex,
    IN OUT UINT64 *Offset,
    IN OUT UINT64 *Length
    );
```

**Parameters**

**This**
A pointer to the EFI_PCI_I/O Protocol instance. Type EFI_PCI_IO_PROTOCOL is defined in EFI PCI I/O Protocol.

**Attributes**
The mask of attributes to set for the resource range specified by BarIndex, Offset, and Length.

**BarIndex**
The BAR index of the standard PCI Configuration header to use as the base address for the resource range. The legal range for this field is 0..5.

**Offset**
A pointer to the BAR relative base address of the resource range to be modified by the attributes specified by Attributes. On return, Offset will be set to the actual base address of the resource range. Not all resources can be set to a byte boundary, so the actual base address may differ from the one passed in by the caller.

**Length**
A pointer to the length of the resource range to be modified by the attributes specified by Attributes. On return, Length will be set to the actual length of the resource range. Not all resources can be set to a byte boundary, so the actual length may differ from the one passed in by the caller.

**Description**
The SetBarAttributes() function sets the attributes specified in Attributes for the PCI controller on the resource range specified by BarIndex, Offset, and Length. Since the granularity of setting these attributes may vary from resource type to resource type, and from platform to platform, the actual resource range and the one passed in by the caller may differ. As a result, this function may set the attributes specified by Attributes on a larger resource range than the caller requested. The actual range is returned in Offset and Length. The caller is responsible for verifying that the actual range for which the attributes were set is acceptable.

If the attributes are set on the PCI controller, then the actual resource range is returned in Offset and Length, and EFI_SUCCESS is returned. Many of the attribute types also require that the state of the PCI Host Bus Controller and the state of any PCI to PCI bridges between the PCI Host Bus Controller and the PCI Controller to be modified. This function will only return EFI_SUCCESS is all of these state changes are made. The PCI Controller may support a combination of attributes, but unless the PCI Host Bus Controller and the PCI to PCI bridges also support that same combination of attributes, then this call will return an error.
If the attributes specified by Attributes, or the resource range specified by BarIndex, Offset, and Length are not supported by the PCI controller, then EFI_UNSUPPORTED is returned. The set of supported attributes for the PCI controller can be found by calling EFI_PCI_IO_PROTOCOL.GetBarAttributes().

If either Offset or Length is NULL then EFI_INVALID_PARAMETER is returned.

If there are not enough resources available to set the attributes, then EFI_OUT_OF_RESOURCES is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The set of attributes specified by Attributes for the resource range specified by BarIndex, Offset, and Length were set on the PCI controller, and the actual resource range is returned in Offset and Length.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The set of attributes specified by Attributes is not supported by the PCI controller for the resource range specified by BarIndex, Offset, and Length.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Offset is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Length is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There are not enough resources to set the attributes on the resource range specified by BarIndex, Offset, and Length.</td>
</tr>
</tbody>
</table>

14.4.20 PCI Device Paths

An EFI_PCI_IO_PROTOCOL must be installed on a handle for its services to be available to PCI device drivers. In addition to the EFI_PCI_IO_PROTOCOL, an EFI Device Path Protocol must also be installed on the same handle (see chapter 9).

Typically, an ACPI Device Path Node is used to describe a PCI Root Bridge. Depending on the bus hierarchy in the system, additional device path nodes may precede this ACPI Device Path Node. A PCI device path is described with PCI Device Path Nodes. There will be one PCI Device Path node for the PCI controller itself, and one PCI Device Path Node for each PCI to PCI Bridge that is between the PCI controller and the PCI Root Bridge.

Table PCI Device 7, Function 0 on PCI Root Bridge 0 shows an example device path for a PCI controller that is located at PCI device number 0x07 and PCI function 0x00, and is directly attached to a PCI root bridge. This device path consists of an ACPI Device Path Node, a PCI Device Path Node, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

```
ACPI(PNP0A03,0)/PCI(7,0)
```

Table 14.41: PCI Device 7, Function 0 on PCI Root Bridge 0

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0,</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0A03</td>
<td></td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Device</td>
</tr>
</tbody>
</table>

continues on next page
Table 14.41 – continued from previous page

<table>
<thead>
<tr>
<th>Offset</th>
<th>Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

Table 14.42: PCI Device 7, Function 0 behind PCI to PCI bridge

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0,0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string 'PNP' and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x05</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x17</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x18</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x19</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

### 14.4.21 PCI Option ROMs

EFI takes advantage of both the PCI Firmware Specification and the PE/COFF Specification to store EFI images in a PCI Option ROM. There are several rules that must be followed when constructing a PCI Option ROM:

- A PCI Option ROM can be no larger than 16 MiB.
- A PCI Option ROM may contain one or more images.
- Each image must be written on a 512-byte boundary.
- Each image must be an even multiple of 512 bytes in length. This means that images that are not an even multiple of 512 bytes in length must be padded to the next 512-byte boundary.
- Legacy Option ROM images begin with a Standard PCI Expansion ROM Header (Standard PCI Expansion ROM Header (Example from PCI Firmware Specification 3.0) (example-from-pci-firmware-specification-3.0).
• EFI Option ROM images begin with an EFI PCI Expansion ROM Header (Recommended PCI Device Driver Layout).

• Each image must contain a PCIR data structure in the first 64 KiB of the image.

• The image data for an EFI Option ROM image must begin in the first 64 KiB of the image.

• The image data for an EFI Option ROM image must be a PE/COFF image or a compressed PE/COFF image following the UEFI Compression Algorithm, and referencing Appendix H — Compression Source Code for the Compression Source Code.

• The PCIR data structure must begin on a 4-byte boundary.

• If the PCI Option ROM contains a Legacy Option ROM image, it must be the first image.

• The images are placed in the PCI Option ROM in order from highest to lowest priority. This priority is used to build the ordered list of Driver Image Handles that are produced by the Bus Specific Driver Override Protocol for a PCI Controller.

• xxxx When PCI device provides an EFI option ROM that is signed in accordance with Chapter 27, use of UEFI Compression Algorithm storage option is preferred. When performing signature validation upon compressed driver, the size returned by EFI_DECOMPRESS_PROTOCOL.GetInfo() will be used as driver size and input to signature validation process. Thus any post-driver padding required to reach exact multiple of 512 bytes per Unsigned PCI Driver Image Layout is ignored by signature validation.

• When PCI device provides an EFI option ROM that is signed in accordance with Chapter 27 and stored uncompressed, the end of the driver for signature validation will be assumed to be the 512-byte boundary indicated by the ‘Initialization Size’ value in the EFI PCI Expansion ROM Header (Table EFI PCI Expansion ROM Header). As the signed driver may not exactly fill the indicated ‘Initialization Size’, it is recommended that the value ‘Offset to EFI Image’ (also Table EFI PCI Expansion ROM Header) be adjusted to ensure the last byte of the signed, uncompressed driver, coincides with the end of the ROM as indicated by ‘Initialization Size’. And any required padding bytes are to be inserted ahead of the signed uncompressed driver image.

There are several options available when building a PCI option ROM for a PCI adapter. A PCI Option ROM can choose to support only a legacy PC-AT platform, only an EFI compliant platform, or both. This flexibility allows a migration path from adapters that support only legacy PC-AT platforms, to adapters that support both PC-AT platforms and EFI compliant platforms, to adapters that support only EFI compliant platforms. The following is a list of the image combinations that may be placed in a PCI option ROM. This is not an exhaustive list. Instead, it provides what will likely be the most common PCI option ROM layouts. EFI compliant system firmware must work with all of these PCI option ROM layouts, plus any other layouts that are possible within the PCI Firmware Specification. The format of a Legacy Option ROM image is defined in the PCI Firmware Specification.

• Legacy Option ROM image
  • IA-32 UEFI driver
  • x64 UEFI driver
  • AArch32 UEFI driver
  • AArch64 UEFI driver
  • RISCV32 UEFI driver
  • RISCV64 UEFI driver
  • RISCV128 UEFI driver
  • Legacy Option ROM image + x64 UEFI driver
  • Legacy Option ROM image + x64 UEFI driver + AArch64 UEFI driver
  • x64 UEFI driver + AArch64 UEFI driver
• Itanium Processor Family UEFI driver
• EBC Driver

In addition to combinations of UEFI drivers with different processor binding, it is also possible to include multiple drivers of different function but the same processor binding. When processing option ROM contents, all drivers of appropriate processor binding type must be loaded and added to ordered list of drivers previously mentioned.

It is also possible to place an application written to this specification in a PCI Option ROM. However, the PCI Bus Driver will ignore these images. The exact mechanism by which applications can be loaded and executed from a PCI Option ROM is outside the scope of this document.

Table 14.43: Standard PCI Expansion ROM Header (Example from PCI Firmware Specification 3.0)

<table>
<thead>
<tr>
<th>Offset</th>
<th>Byte Length</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>1</td>
<td>0x55</td>
<td>ROM Signature, byte 1</td>
</tr>
<tr>
<td>0x01</td>
<td>1</td>
<td>0xAA</td>
<td>ROM Signature, byte 2</td>
</tr>
<tr>
<td>0x02-0x17</td>
<td>22</td>
<td>XX</td>
<td>Reserved per processor architecture unique data</td>
</tr>
<tr>
<td>0x18-0x19</td>
<td>2</td>
<td>XX</td>
<td>Pointer to PCIR Data Structure</td>
</tr>
</tbody>
</table>

Table 14.44: PCI Expansion ROM Code Types (Example from PCI Firmware Specification 3.0)

<table>
<thead>
<tr>
<th>Code Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>IA-32, PC-AT compatible</td>
</tr>
<tr>
<td>0x01</td>
<td>Open Firmware standard for PCI</td>
</tr>
<tr>
<td>0x02</td>
<td>Hewlett-Packard PA RISC</td>
</tr>
<tr>
<td>0x03</td>
<td>EFI Image</td>
</tr>
<tr>
<td>0x04-0xFF</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

Table 14.45: EFI PCI Expansion ROM Header

<table>
<thead>
<tr>
<th>Offset</th>
<th>Byte Length</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>1</td>
<td>0x55</td>
<td>ROM Signature, byte 1</td>
</tr>
<tr>
<td>0x01</td>
<td>1</td>
<td>0xAA</td>
<td>ROM Signature, byte 2</td>
</tr>
<tr>
<td>0x02</td>
<td>2</td>
<td>XXXX</td>
<td>Initialization Size - size of this image in units of 512 bytes. The size includes this header.</td>
</tr>
<tr>
<td>0x04</td>
<td>4</td>
<td>0x0EF1</td>
<td>Signature from EFI image header</td>
</tr>
<tr>
<td>0x08</td>
<td>2</td>
<td>XX</td>
<td>Subsystem value for EFI image header</td>
</tr>
<tr>
<td>0x0a</td>
<td>2</td>
<td>XX</td>
<td>Machine type from EFI image header</td>
</tr>
<tr>
<td>0x0c</td>
<td>2</td>
<td>XX</td>
<td>Compression type</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0x0000 - The image is uncompressed</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0x0001 - The image is compressed. See the UEFI Compression Algorithm and Appendix H — Compression Source Code.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0x0002 - 0xFFFF - Reserved</td>
</tr>
<tr>
<td>0x0e</td>
<td>8</td>
<td>0x00</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

continues on next page
### 14.4.22 PCI Bus Driver Responsibilities

A PCI Bus Driver must scan a PCI Option ROM for PCI Device Drivers. If a PCI Option ROM is found during PCI Enumeration, then a copy of the PCI Option ROM is placed in a memory buffer. The PCI Bus Driver will use the memory copy of the PCI Option ROM to search for UEFI drivers after PCI Enumeration. The PCI Bus Driver will search the list of images in a PCI Option ROM for the ones that have a Code Type of 0x03 in the PCIR Data Structure, and a Signature of 0xEF1 in the EFI PCI Expansion ROM Header. Then, it will examine the Subsystem Type of the EFI PCI Expansion ROM Header. If the Subsystem Type is `IMAGE_SUBSYSTEM_EFI_BOOT_SERVICE_DRIVER` (11) or `IMAGE_SUBSYSTEM_EFI_RUNTIME_DRIVER` (12), then the PCI Bus Driver can load the PCI Device Driver from the PCI Option ROM. The Offset to EFI Image Header field of the EFI PCI Expansion ROM Header is used to get a pointer to the beginning of the PE/COFF image in the PCI Option ROM. The PE/COFF image may have been compressed using the UEFI Compression Algorithm. If it has been compressed, then the PCI Bus Driver must decompress the driver to a memory buffer. The Boot Service `EFI_BOOT_SERVICES.LoadImage()` can then be used to load the driver. All UEFI driver images discovered in the PCI Option ROM and meeting these requirements must be processed and loaded via `LoadImage()` . If the platform does not support the Machine Type of the driver, then `LoadImage()` may fail.

It is the PCI Bus Driver’s responsibility to verify that the Expansion ROM Header and PCIR Data Structure are valid. It is the responsibility of the Boot Service `LoadImage()` to verify that the PE/COFF image is valid. The Boot Service `LoadImage()` may fail for several reasons including a corrupt PE/COFF image or an unsupported Machine Type.

If a PCI Option ROM contains one or more UEFI images, then the PCI Bus Driver must install an instance of the `EFI_LOAD_FILE2_PROTOCOL` on the PCI controller handle. Then, when the PCI Bus Driver loads a PE/COFF image from a PCI Option ROM using the Boot Service `LoadImage()` , the PCI Bus Driver must provide the device path of the image being loaded. The device path of an image loaded from a PCI Option ROM must be the device path to the PCI Controller to which the PCI Option ROM is attached followed by a Relative Offset Range node. The Starting Offset field of the Relative Offset Range node must be the byte offset from the beginning of the PCI Option ROM to the beginning of the EFI Option ROM image, and the Ending Offset field of the Relative Offset Range node must be the byte offset from the beginning of the PCI Option ROM to the end of the EFI Option ROM image. The table below shows an example device path for an EFI driver loaded from a PCI Option ROM. The EFI Driver starts at offset 0x8000 into the PCI Option ROM and is 0x2000 bytes long. The shorthand notation for this device path is:

```
PciRoot(0)/PCI(5,0)/PCI(7,0)/ Offset(0x8000,0x9FFF)
```

<table>
<thead>
<tr>
<th>Offset</th>
<th>Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0,0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string &quot;PNP&quot; and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x8000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
</tbody>
</table>

Table 14.46: Device Path for an EFI Driver loaded from PCI Option ROM

Continues on next page
Table 14.46 – continued from previous page

<table>
<thead>
<tr>
<th>Offset</th>
<th>Byte Length</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x05</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x17</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x18</td>
<td>0x01</td>
<td>0x04</td>
<td>Generic Device Path Header - Type Media Device Path</td>
</tr>
<tr>
<td>0x19</td>
<td>0x01</td>
<td>0x08</td>
<td>Sub type - Relative Offset Range</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x02</td>
<td>0x14</td>
<td>Length - 0x14 bytes</td>
</tr>
<tr>
<td>0x1C</td>
<td>0x08</td>
<td>0x8000</td>
<td>Start Address - Offset into PCI Option ROM</td>
</tr>
<tr>
<td>0x24</td>
<td>0x08</td>
<td>0x9FFF</td>
<td>End Address - Offset into PCI Option ROM</td>
</tr>
<tr>
<td>0x2C</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x2D</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x2E</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

The PCI Option ROM search may produce one or more Driver Image Handles for the PCI Controller that is associated with the PCI Option ROM. The PCI Bus Driver is responsible for producing a Bus Specific Driver Override Protocol instance for every PCI Controller has a PCI Option ROM that contains one or more UEFI Drivers. The Bus Specific Driver Override Protocol produces an ordered list of Driver Image Handles. The order that the UEFI Drivers are placed in the PCI Option ROM is the order of Driver Image Handles that must be returned by the Bus Specific Driver Override Protocol. This gives the party that builds the PCI Option ROM control over the order that the drivers are used in the Boot Service `EFI_BOOT_SERVICES.ConnectController()`.

### 14.4.23 PCI Device Driver Responsibilities

A PCI Device Driver should not be designed to care where it is stored. It can reside in a PCI Option ROM, the system’s motherboard ROM, a hard drive, a CD-ROM drive, etc. All PCI Device Drivers are compiled and linked to generate a PE/COFF image. When a PE/COFF image is placed in a PCI Option ROM, it must follow the rules outlined in See PCI Option ROMs. The recommended image layout is to insert an EFI PCI Expansion ROM Header and a PCIR Data Structure in front of the PE/COFF image, and pad the entire image up to the next 512-byte boundary. See Unsigned PCI Driver Image Layout shows the format of a single PCI Device Driver that can be added to a PCI Option ROM.

Following are recommended layouts and flow charts for various types of driver signage and compression states for PCI device driver images. See Unsigned PCI Driver Image Layout shows an unsigned layout.

Figures Signed and Compressed PCI Driver Image Flow and Signed and Compressed PCI Driver Image Flow show a signed and compressed PCI device driver image flow chart and layout, respectively.

Figure Signed but not Compressed PCI Driver Image Flow and Figure Signed and Uncompressed PCI Driver Image Layout show a signed but not compressed flow chart and a signed and uncompressed PCI device driver image layout, respectively.

The field values for the EFI PCI Expansion ROM Header and the PCIR Data Structure would be as follows in this recommended PCI Driver image layout. An image must start at a 512-byte boundary, and the end of the image must be padded to the next 512-byte boundary.

Table 14.47: Recommended PCI Device Driver Layout

<table>
<thead>
<tr>
<th>Offset</th>
<th>Byte Length</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>1</td>
<td>0x55</td>
<td>ROM Signature, byte 1</td>
</tr>
<tr>
<td>0x01</td>
<td>1</td>
<td>0xAA</td>
<td>ROM Signature, byte 2</td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>Offset</th>
<th>Size</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x02</td>
<td>2</td>
<td>XXXX</td>
<td>Initialization Size - size of this image in units of 512 bytes. The size includes this header</td>
</tr>
<tr>
<td>0x04</td>
<td>4</td>
<td>0x0EF1</td>
<td>Signature from EFI image header</td>
</tr>
<tr>
<td>0x08</td>
<td>2</td>
<td>XX</td>
<td>Subsystem Value from the PCI Driver’s PE/COFF Image Header</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0B</td>
<td>Subsystem Value for an EFI Boot Service Driver</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0C</td>
<td>Subsystem Value for an EFI Runtime Driver</td>
</tr>
<tr>
<td>0x0a</td>
<td>2</td>
<td>XX</td>
<td>Machine type from the PCI Driver’s PE/COFF Image Header</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x014C</td>
<td>IA-32 Machine Type</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0200</td>
<td>Itanium processor type</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0EBC</td>
<td>EFI Byte Code (EBC) Machine Type</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x8664</td>
<td>X64 Machine Type</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x01c2</td>
<td>ARM Machine Type</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0xAA64</td>
<td>ARM 64-bit Machine Type</td>
</tr>
<tr>
<td>0x0C</td>
<td>2</td>
<td>XXXX</td>
<td>Compression Type</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0000</td>
<td>Uncompressed</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0001</td>
<td>Compressed following the UEFI Compression Algorithm</td>
</tr>
<tr>
<td>0x0E</td>
<td>8</td>
<td>0x00</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x16</td>
<td>2</td>
<td>0x0034</td>
<td>Offset to EFI Image</td>
</tr>
<tr>
<td>0x18</td>
<td>2</td>
<td>0x001C</td>
<td>Offset to PCIR Data Structure</td>
</tr>
<tr>
<td>0x1A</td>
<td>2</td>
<td>0x0000</td>
<td>Padding to align PCIR Data Structure on a 4 byte boundary</td>
</tr>
<tr>
<td>0x1C</td>
<td>4</td>
<td>‘PCIR’</td>
<td>PCIR Data Structure Signature</td>
</tr>
<tr>
<td>0x20</td>
<td>2</td>
<td>XXXX</td>
<td>Vendor ID from the PCI Controller’s Configuration Header</td>
</tr>
<tr>
<td>0x22</td>
<td>2</td>
<td>XXXX</td>
<td>Device ID from the PCI Controller’s Configuration Header</td>
</tr>
<tr>
<td>0x24</td>
<td>2</td>
<td>0x0000</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x26</td>
<td>2</td>
<td>0x0018</td>
<td>The length if the PCIR Data Structure in bytes</td>
</tr>
<tr>
<td>0x28</td>
<td>1</td>
<td>0x00</td>
<td>PCIR Data Structure Revision. Value for PCI 2.2 Option ROM</td>
</tr>
<tr>
<td>0x29</td>
<td>3</td>
<td>XXXX</td>
<td>Class Code from the PCI Controller’s Configuration Header</td>
</tr>
<tr>
<td>0x2C</td>
<td>2</td>
<td>XXXX</td>
<td>Code Image Length in units of 512 bytes. Same as Initialization Size</td>
</tr>
<tr>
<td>0x2E</td>
<td>2</td>
<td>XXXX</td>
<td>Revision Level of the Code/Data. This field is ignored</td>
</tr>
<tr>
<td>0x30</td>
<td>1</td>
<td>0x03</td>
<td>Code Type</td>
</tr>
<tr>
<td>0x31</td>
<td>1</td>
<td>XX</td>
<td>Indicator. Bit 7 clear means another image follows. Bit 7 set means that this image is the last image in the PCI Option ROM. Bits 0-6 are reserved.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x00</td>
<td>Additional images follow this image in the PCI Option ROM This image is the last image in the PCI Option ROM</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x80</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x32</td>
<td>2</td>
<td>0x0000</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x34</td>
<td>X</td>
<td>XXXX</td>
<td>The beginning of the PCI Device Driver’s PE/COFF Image</td>
</tr>
</tbody>
</table>
Fig. 14.15: Unsigned PCI Driver Image Layout

Fig. 14.16: Signed and Compressed PCI Driver Image Flow
Fig. 14.17: Signed and Compressed PCI Driver Image Layout
Fig. 14.18: Signed but not Compressed PCI Driver Image Flow
Fig. 14.19: Signed and Uncompressed PCI Driver Image Layout
14.4.24 Nonvolatile Storage

A PCI adapter may contain some form of nonvolatile storage. Since there are no standard access mechanisms for nonvolatile storage on PCI adapters, the PCI I/O Protocol does not provide any services for nonvolatile storage. However, a PCI Device Driver may choose to implement its own access mechanisms. If there is a private channel between a PCI Controller and a nonvolatile storage device, a PCI Device Driver can use it for configuration options or vital product data.

**Note:** The fields RomImage and RomSize in the PCI I/O Protocol do not provide direct access to the PCI Option ROM on a PCI adapter. Instead, they provide access to a copy of the PCI Option ROM in memory. If the contents of the RomImage are modified, only the memory copy is updated. If a vendor wishes to update the contents of a PCI Option ROM, they must provide their own utility or driver to perform this task. There is no guarantee that the BAR for the PCI Option ROM is valid at the time that the utility or driver may execute, so the utility or driver must provide the code required to gain write access to the PCI Option ROM contents. The algorithm for gaining write access to a PCI Option ROM is both platform specific and adapter specific, so it is outside the scope of this document.

14.4.25 PCI Hot-Plug Events

It is possible to design a PCI Bus Driver to work with PCI Bus that conforms to the PCI Hot-Plug Specification. There are two levels of functionality that could be provided in the preboot environment. The first is to initialize the PCI Hot-Plug capable bus so it can be used by an operating system that also conforms to the PCI Hot-Plug Specification. This only affects the PCI Enumeration that is performed in either the PCI Bus Driver’s initialization, or a firmware component that executes prior to the PCI Bus Driver’s initialization. None of the PCI Device Drivers need to be aware of the fact that a PCI Controller may exist in a slot that is capable of a hot-plug event. Also, the addition, removal, and replacement of PCI adapters in the preboot environment would not be allowed.

The second level of functionality is to actually implement the full hot-plug capability in the PCI Bus Driver. This is not recommended because it adds a great deal of complexity to the PCI Bus Driver design with very little added value. However, there is nothing about the PCI Driver Model that would preclude this implementation. It would require using an event based periodic timer to monitor the hot-plug capable slots, and take advantage of the `EFI_BOOT_SERVICES.ConnectController()` and `EFI_BOOT_SERVICES.DisconnectController()` Boot Services to dynamically start and stop the drivers that manage the PCI controller that is being added, removed, or replaced. If the `EFI_BOOT_SERVICES.DisconnectController()` Boot Service fails it must be retried via a periodic timer.
The intent of this chapter is to specify a method of providing direct access to SCSI devices. These protocols provide services that allow a generic driver to produce the Block I/O protocol for SCSI disk devices, and allows an EFI utility to issue commands to any SCSI device. The main reason to provide such an access is to enable S.M.A.R.T. functionality during POST (i.e., issuing Mode Sense, Mode Select, and Log Sense to SCSI devices). This is accomplished by using a generic API such as SCSI Pass Thru. The use of this method will enable additional functionality in the future without modifying the EFI SCSI Pass Thru driver. SCSI Pass Thru is not limited to SCSI channels. It is applicable to all channel technologies that utilize SCSI commands such as SCSI, ATAPI, and Fibre Channel. This chapter describes the SCSI Driver Model. This includes the behavior of SCSI Bus Drivers, the behavior of SCSI Device Drivers, and a detailed description of the SCSI I/O Protocol. This chapter provides enough material to implement a SCSI Bus Driver, and the tools required to design and implement SCSI Device Drivers. It does not provide any information on specific SCSI devices.

15.1 SCSI Driver Model Overview

The EFI SCSI Driver Stack includes the SCSI Pass Thru Driver, SCSI Bus Driver and individual SCSI Device Drivers.

**SCSI Pass Thru Driver**: A SCSI Pass Through Driver manages a SCSI Host Controller that contains one or more SCSI Buses. It creates SCSI Bus Controller Handles for each SCSI Bus, and attaches Extended SCSI Pass Thru Protocol and Device Path Protocol to each handle the driver produced. Please refer to *Extended SCSI Pass Thru Protocol* and Appendix G. *Using the EFI Extended SCSI Pass Thru Protocol*.

**SCSI Bus Driver**: A SCSI Bus Driver manages a SCSI Bus Controller Handle that is created by SCSI Pass Thru Driver. It creates SCSI Device Handles for each SCSI Device Controller detected during SCSI Bus Enumeration, and attaches SCSI I/O Protocol and Device Path Protocol to each handle the driver produced.

**SCSI Device Driver**: A SCSI Device Driver manages one kind of SCSI Device. Device handles for SCSI Devices are created by SCSI Bus Drivers. A SCSI Device Driver could be a bus driver itself, and may create child handles. But most SCSI Device Drivers will be device drivers that do not create new handles. For the pure device driver, it attaches protocol instance to the device handle of the SCSI Device. These protocol instances are I/O abstractions that allow the SCSI Device to be used in the pre-boot environment. The most common I/O abstractions are used to boot an EFI compliant OS.
15.2 SCSI Bus Drivers

A SCSI Bus Driver manages a SCSI Bus Controller Handle. A SCSI Bus Controller Handle is created by a SCSI Pass Thru Driver and is abstracted in software with the Extended SCSI Pass Thru Protocol. A SCSI Bus Driver will manage handles that contain this protocol. The Figure below, Device Handle for a SCSI Bus Controller, shows an example device handle for a SCSI Bus handle. It contains a Device Path Protocol instance and an Extended SCSI Pass Thru Protocol Instance.

![Device Handle for a SCSI Bus Controller](image)

Fig. 15.1: Device Handle for a SCSI Bus Controller

15.2.1 Driver Binding Protocol for SCSI Bus Drivers

The Driver Binding Protocol contains three services. These are Supported(), Start(), and Stop(). Supported() tests to see if the SCSI Bus Driver can manage a device handle. A SCSI Bus Driver can only manage device handle that contain the Device Path Protocol and the Extended SCSI Pass Thru Protocol, so a SCSI Bus Driver must look for these two protocols on the device handle that is being tested.

The Start() function tells the SCSI Bus Driver to start managing a device handle. The device handle should support the protocols shown in Figure Device Handle for a SCSI Bus Controller. The Extended SCSI Pass Thru Protocol provides information about a SCSI Channel and the ability to communicate with any SCSI devices attached to that SCSI Channel.

The SCSI Bus Driver has the option of creating all of its children in one call to Start(), or spreading it across several calls to Start(). In general, if it is possible to design a bus driver to create one child at a time, it should do so to support the rapid boot capability in the UEFI Driver Model. Each of the child device handles created in Start() must contain a Device Path Protocol instance, and a SCSI I/O protocol instance. The SCSI I/O Protocol is described in EFI SCSI I/O Protocol and Section 14.4. The format of device paths for SCSI Devices is described in SCSI Device Paths. The Figure below, Child Handle Created by a SCSI Bus Driver, shows an example child device handle that is created by a SCSI Bus Driver for a SCSI Device.

A SCSI Bus Driver must perform several steps to manage a SCSI Bus.

1. Scan for the SCSI Devices on the SCSI Channel that connected to the SCSI Bus Controller. If a request is being made to scan only one SCSI Device, then only looks for the one specified. Create a device handle for the SCSI Device found.

2. Install a Device Path Protocol instance and a SCSI I/O Protocol instance on the device handle created for each SCSI Device.

The Stop() function tells the SCSI Bus Driver to stop managing a SCSI Bus. The Stop() function can destroy one or more of the device handles that were created on a previous call to Start(). If all of the child device handles have been
destroyed, then \texttt{Stop()} will place the SCSI Bus Controller in a quiescent state. The functionality of \texttt{Stop()} mirrors \texttt{Start()}.

15.2.2 SCSI Enumeration

The purpose of the SCSI Enumeration is only to scan for the SCSI Devices attached to the specific SCSI channel. The SCSI Bus driver need not allocate resources for SCSI Devices (like PCI Bus Drivers do), nor need it connect a SCSI Device with its Device Driver (like USB Bus Drivers do). The details of the SCSI Enumeration is implementation specific, thus is out of the scope of this document.

15.3 SCSI Device Drivers

SCSI Device Drivers manage SCSI Devices. Device handles for SCSI Devices are created by SCSI Bus Drivers. A SCSI Device Driver could be a bus driver itself, and may create child handles. But most SCSI Device Drivers will be device drivers that do not create new handles. For the pure device driver, it attaches protocol instance to the device handle of the SCSI Device. These protocol instances are I/O abstractions that allow the SCSI Device to be used in the pre-boot environment. The most common I/O abstractions are used to boot an EFI compliant OS.

15.3.1 Driver Binding Protocol for SCSI Device Drivers

The Driver Binding Protocol contains three services. These are \texttt{Supported()}, \texttt{Start()}, and \texttt{Stop()}. \texttt{Supported()} tests to see if the SCSI Device Driver can manage a device handle. A SCSI Device Driver can only manage device handle that contain the Device Path Protocol and the SCSI I/O Protocol, so a SCSI Device Driver must look for these two protocols on the device handle that is being tested. In addition, it needs to check to see if the device handle represents a SCSI Device that SCSI Device Driver knows how to manage. This is typically done by using the services of the SCSI I/O Protocol to see whether the device information retrieved is supported by the device driver.

The \texttt{Start()} function tells the SCSI Device Driver to start managing a SCSI Device. A SCSI Device Driver could be a bus driver itself, and may create child handles. But most SCSI Device Drivers will be device drivers that do not create new handles. For the pure device driver, it installs one or more addition protocol instances on the device handle for the SCSI Device.
The \texttt{Stop()} function mirrors the \texttt{Start()} function, so the \texttt{Stop()} function completes any outstanding transactions to the SCSI Device and removes the protocol interfaces that were installed in \texttt{Start()}. 

### 15.4 EFI SCSI I/O Protocol

This section defines the EFI SCSI I/O protocol. This protocol is used by code, typically drivers, running in the EFI boot services environment to access SCSI devices. In particular, functions for managing devices on SCSI buses are defined here.

The interfaces provided in the \texttt{EFI_SCSI_IO_PROTOCOL} are for performing basic operations to access SCSI devices.

#### 15.4.1 \texttt{EFI_SCSI_IO_PROTOCOL}

This section provides a detailed description of the \texttt{EFI_SCSI_IO_PROTOCOL}.

**Summary**

Provides services to manage and communicate with SCSI devices.

**GUID**

\begin{verbatim}
#define EFI_SCSI_IO_PROTOCOL_GUID \
{0x932f47e6,0x2362,0x4002,\ 
 {0x80,0x3e,0x3c,0xd5,0x4b,0x13,0x8f,0x85}}
\end{verbatim}

**Protocol Interface Structure**

\begin{verbatim}
typedef struct _ EFI_SCSI_IO_PROTOCOL {
    EFI_SCSI_IO_PROTOCOL_GET_DEVICE_TYPE GetDeviceType;
    EFI_SCSI_IO_PROTOCOL_GET_DEVICE_LOCATION GetDeviceLocation;
    EFI_SCSI_IO_PROTOCOL_RESET_BUS ResetBus;
    EFI_SCSI_IO_PROTOCOL_RESET DEVICE ResetDevice;
    EFI_SCSI_IO_PROTOCOL_EXECUTE_SCSI_COMMAND ExecuteScsiCommand;
    UINT32 IoAlign;
} EFI_SCSI_IO_PROTOCOL;
\end{verbatim}

**Parameters**

- \texttt{IoAlign}
  Supplies the alignment requirement for any buffer used in a data transfer. \texttt{IoAlign} values of 0 and 1 mean that the buffer can be placed anywhere in memory. Otherwise, \texttt{IoAlign} must be a power of 2, and the requirement is that the start address of a buffer must be evenly divisible by \texttt{IoAlign} with no remainder.

- \texttt{GetDeviceType}
  Retrieves the information of the device type which the SCSI device belongs to \texttt{EFI_SCSI_IO_PROTOCOL.GetDeviceType()}.  

- \texttt{GetDeviceLocation}
  Retrieves the device location information in the SCSI bus \texttt{EFI_SCSI_IO_PROTOCOL.GetDeviceLocation()}. 

- \texttt{ResetBus}
  Resets the entire SCSI bus the SCSI device attaches to \texttt{EFI_SCSI_IO_PROTOCOL.ResetBus()}. 

ResetDevice

Resets the SCSI Device that is specified by the device handle the SCSI I/O protocol attaches

EFI_SCSI_IO_PROTOCOL.ResetDevice() .

ExecuteScsiCommand

Sends a SCSI command to the SCSI device and waits for the execution completion until an exit condition is met, or a timeout occurs

EFI_SCSI_IO_PROTOCOL.ExecuteScsiCommand() .

Description

The EFI_SCSI_IO_PROTOCOL provides the basic functionalities to access and manage a SCSI Device. There is one EFI_SCSI_IO_PROTOCOL instance for each SCSI Device on a SCSI Bus. A device driver that wishes to manage a SCSI Device in a system will have to retrieve the EFI_SCSI_IO_PROTOCOL instance that is associated with the SCSI Device. A device handle for a SCSI Device will minimally contain an EFI_DEVICE_PATH_PROTOCOL instance and an EFI_SCSI_IO_PROTOCOL instance.

15.4.2 EFI_SCSI_IO_PROTOCOL.GetDeviceType()

Summary

Retrieves the device type information of the SCSI Device.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_SCSI_IO_PROTOCOL_GET_DEVICE_TYPE) (  
  IN EFI_SCSI_IO_PROTOCOL *This,
  OUT UINT8 *DeviceType
);

Parameters

This

A pointer to the EFI_SCSI_IO_PROTOCOL instance. Type EFI_SCSI_IO_PROTOCOL is defined in EFI_SCSI_IO_PROTOCOL.

DeviceType

A pointer to the device type information retrieved from the SCSI Device. See “Related Definitions” for the possible returned values of this parameter.

Description

This function is used to retrieve the SCSI device type information. This function is typically used for SCSI Device Drivers to quickly recognize whether the SCSI Device could be managed by it.

If DeviceType is NULL, then EFI_INVALID_PARAMETER is returned. Otherwise, the device type is returned in DeviceType and EFI_SUCCESS is returned.

Related Definitions

//Defined in the SCSI Primary Commands standard (e.g., SPC-4)

//
#define EFI_SCSI_IO_TYPE_DISK 0x00 // Disk device
#define EFI_SCSI_IO_TYPE_TAPE 0x01 // Tape device
#define EFI_SCSI_IO_TYPE_PRINTER 0x02 // Printer
#define EFI_SCSI_IO_TYPE_PROCESSOR 0x03 // Processor
#define EFI_SCSI_IO_TYPE_WORM 0x04 // Write-once read-multiple

(continues on next page)
#define EFI_SCSI_IO_TYPE_CDROM 0x05 // CD or DVD device
#define EFI_SCSI_IO_TYPE_SCANNER 0x06 // Scanner device
#define EFI_SCSI_IO_TYPE_OPTICAL 0x07 // Optical memory device
#define EFI_SCSI_IO_TYPE_MEDIUMCHANGER 0x08 // Medium Changer device
#define EFI_SCSI_IO_TYPE_COMMUNICATION 0x09 // Communications device
#define MFI_SCSI_IO_TYPE_A 0x0A // Obsolete
#define MFI_SCSI_IO_TYPE_B 0x0B // Obsolete
#define MFI_SCSI_IO_TYPE_RAID 0x0C // Storage array controller
  // device (e.g., RAID)
#define MFI_SCSI_IO_TYPE_SES 0x0D // Enclosure services device
#define MFI_SCSI_IO_TYPE_RBC 0x0E // Simplified direct-access
  // device (e.g., magnetic
  // disk)
#define MFI_SCSI_IO_TYPE_OCRW 0x0F // Optical card reader/
  // writer device
#define MFI_SCSI_IO_TYPE_BRIDGE 0x10 // Bridge Controller
  // Commands
#define MFI_SCSI_IO_TYPE_OSD 0x11 // Object-based Storage
  // Device
#define EFI_SCSI_IO_TYPE_RESERVED_LOW 0x12 // Reserved (low)
#define EFI_SCSI_IO_TYPE_RESERVED_HIGH 0x1E // Reserved (high)
#define EFI_SCSI_IO_TYPE_UNKNOWN 0x1F // Unknown no device type

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Retrieves the device type information successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The DeviceType is NULL.</td>
</tr>
</tbody>
</table>

15.4.3 EFI_SCSI_IO_PROTOCOL.GetDeviceLocation()

Summary

Retrieves the SCSI device location in the SCSI channel.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_SCSI_IO_PROTOCOL_GET_DEVICE_LOCATION) (  
  IN EFI_SCSI_IO_PROTOCOL *This,  
  IN OUT UINT8 **Target,  
  OUT UINT64 *Lun  
);

Parameters

This

A pointer to the EFI_SCSI_IO_PROTOCOL instance. Type EFI_SCSI_IO_PROTOCOL is defined in EFI_SCSI_IO_PROTOCOL.

Target

A pointer to the Target Array which represents the ID of a SCSI device on the SCSI channel.
Lun

A pointer to the Logical Unit Number of the SCSI device on the SCSI channel.

Description

This function is used to retrieve the SCSI device location in the SCSI bus. The device location is determined by a (Target, Lun) pair. This function allows a SCSI Device Driver to retrieve its location on the SCSI channel, and may use the Extended SCSI Pass Thru Protocol to access the SCSI device directly.

If Target or Lun is NULL, then EFI_INVALID_PARAMETER is returned. Otherwise, the device location is returned in Target and Lun, and EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Retrieves the device location successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Target or Lun is NULL.</td>
</tr>
</tbody>
</table>

15.4.4 EFI_SCSI_IO_PROTOCOL.ResetBus()

Summary

Resets the SCSI Bus that the SCSI Device is attached to.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_SCSI_IO_PROTOCOL_RESET_BUS) (IN EFI_SCSI_IO_PROTOCOL *This);

Parameters

This

A pointer to the EFI_SCSI_IO_PROTOCOL instance. Type EFI_SCSI_IO_PROTOCOL is defined in EFI_SCSI_IO_PROTOCOL.

Description

This function provides the mechanism to reset the whole SCSI bus that the specified SCSI Device is connected to. Some SCSI Host Controller may not support bus reset, if so, EFI_UNSUPPORTED is returned. If a device error occurs while executing that bus reset operation, then EFI_DEVICE_ERROR is returned. If a timeout occurs during the execution of the bus reset operation, then EFI_TIMEOUT is returned. If the bus reset operation is completed, then EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The SCSI bus is reset successfully.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Errors encountered when resetting the SCSI bus.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The bus reset operation is not supported by the SCSI Host Controller.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>A timeout occurred while attempting to reset the SCSI bus.</td>
</tr>
</tbody>
</table>
15.4.5 EFI_SCSI_IO_PROTOCOL.ResetDevice()

Summary
Resets the SCSI Device that is specified by the device handle that the SCSI I/O Protocol is attached.

Prototype

typedef
 EFI_STATUS
 (EFIAPI *EFI_SCSI_IO_PROTOCOL_RESET_DEVICE) (  
    IN EFI_SCSI_IO_PROTOCOL  *This  
  );

Parameters

This
A Pointer to the EFI_SCSI_IO_PROTOCOL instance. Type EFI_SCSI_IO_PROTOCOL is defined in EFI_SCSI_IO_PROTOCOL.

Description
This function provides the mechanism to reset the SCSI Device. If the SCSI bus does not support a device reset operation, then EFI_UNSUPPORTED is returned. If a device error occurs while executing that device reset operation, then EFI_DEVICE_ERROR is returned. If a timeout occurs during the execution of the device reset operation, then EFI_TIMEOUT is returned. If the device reset operation is completed, then EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Reset the SCSI Device successfully.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Errors are encountered when resetting the SCSI Device.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The SCSI bus does not support a device reset operation.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>A timeout occurred while attempting to reset the SCSI Device.</td>
</tr>
</tbody>
</table>

15.4.6 EFI_SCSI_IO_PROTOCOL.ExecuteScsiCommand()

Summary
Sends a SCSI Request Packet to the SCSI Device for execution.

Prototype

typedef
 EFI_STATUS
 (EFIAPI *EFI_SCSI_IO_PROTOCOL_EXECUTE_SCSI_COMMAND) (  
    IN EFI_SCSI_IO_PROTOCOL  *This,  
    IN OUT EFI_SCSI_IO_SCSI_REQUEST_PACKET  *Packet,  
    IN EFI_EVENT Event OPTIONAL  
  );

Parameters

This
A pointer to the EFI_SCSI_IO_PROTOCOL instance. Type EFI_SCSI_IO_PROTOCOL is defined in EFI_SCSI_IO_PROTOCOL.
Packet
The SCSI request packet to send to the SCSI Device specified by the device handle. See “Related Definitions” for a description of EFI_SCSI_IO_SCSI_REQUEST_PACKET.

Event
If the SCSI bus where the SCSI device is attached does not support non-blocking I/O, then Event is ignored, and blocking I/O is performed. If Event is NULL, then blocking I/O is performed. If Event is not NULL and non-blocking I/O is supported, then non-blocking I/O is performed, and Event will be signaled when the SCSI Request Packet completes.

Related Definitions

typedef struct {
    UINT64 Timeout;
    VOID *InDataBuffer;
    VOID *OutDataBuffer;
    VOID *SenseData;
    VOID *Cdb;
    UINT32 InTransferLength;
    UINT32 OutTransferLength;
    UINT8 CdbLength;
    UINT8 DataDirection;
    UINT8 HostAdapterStatus;
    UINT8 TargetStatus;
    UINT8 SenseDataLength;
} EFI_SCSI_IO_SCSI_REQUEST_PACKET;

Timeout
The timeout, in 100 ns units, to use for the execution of this SCSI Request Packet. A Timeout value of 0 means that this function will wait indefinitely for the SCSI Request Packet to execute. If Timeout is greater than zero, then this function will return EFI_TIMEOUT if the time required to execute the SCSI Request Packet is greater than Timeout.

DataBuffer
A pointer to the data buffer to transfer from or to the SCSI device.

InDataBuffer
A pointer to the data buffer to transfer between the SCSI controller and the SCSI device for SCSI READ command. For all SCSI WRITE Commands this must point to NULL.

OutDataBuffer
A pointer to the data buffer to transfer between the SCSI controller and the SCSI device for SCSI WRITE command. For all SCSI READ commands this field must point to NULL.

SenseData
A pointer to the sense data that was generated by the execution of the SCSI Request Packet.

Cdb
A pointer to buffer that contains the Command Data Block to send to the SCSI device.

InTransferLength
On Input, the size, in bytes, of InDataBuffer. On output, the number of bytes transferred between the SCSI controller and the SCSI device. If InTransferLength is larger than the SCSI controller can handle, no data will be transferred, InTransferLength will be updated to contain the number of bytes that the SCSI controller is able to transfer, and EFI_BAD_BUFFER_SIZE will be returned.

OutTransferLength
On Input, the size, in bytes of OutDataBuffer. On Output, the Number of bytes transferred between SCSI Controller and the SCSI device. If OutTransferLength is larger than the SCSI controller can handle, no data will
be transferred, OutTransferLength will be updated to contain the number of bytes that the SCSI controller is able
to transfer, and EFI_BAD_BUFFER_SIZE will be returned.

CdbLength
The length, in bytes, of the buffer Cdb. The standard values are 6, 10, 12, and 16, but other values are possible
if a variable length CDB is used.

DataDirection
The direction of the data transfer. 0 for reads, 1 for writes. A value of 2 is Reserved for Bi-Directional SCSI
commands. For example XDREADWRITE. All other values are reserved, and must not be used.

HostAdapterStatus
The status of the SCSI Host Controller that produces the SCSI bus where the SCSI device attached when the
SCSI Request Packet was executed on the SCSI Controller. See the possible values listed below.

TargetStatus
The status returned by the SCSI device when the SCSI Request Packet was executed. See the possible values
listed below.

SenseDataLength
On input, the length in bytes of the SenseData buffer. On output, the number of bytes written to the SenseData
buffer.

```
#define EFI_SCSI_IO_DATA_DIRECTION_READ 0
#define EFI_SCSI_IO_DATA_DIRECTION_WRITE 1
#define EFI_SCSI_IO_DATA_DIRECTION_BIDIRECTIONAL 2
```

```
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_OK 0x00
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_TIMEOUT_COMMAND 0x09
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_TIMEOUT 0x0b
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_MESSAGE_REJECT 0x0d
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_BUS_RESET 0x0e
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_PARITY_ERROR 0x0f
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_REQUEST_SENSE_FAILED 0x10
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_SELECTION_TIMEOUT 0x11
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_DATA_OVERRUN_UNDERRUN 0x12
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_BUS_FREE 0x13
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_PHASE_ERROR 0x14
#define EFI_SCSI_IO_STATUS_HOST_ADAPTER_OTHER 0x7f
```

```
#define EFI_SCSI_IO_STATUS_TARGET_GOOD 0x00
#define EFI_SCSI_IO_STATUS_TARGET_CHECK_CONDITION 0x02
#define EFI_SCSI_IO_STATUS_TARGET_CONDITION_MET 0x04
#define EFI_SCSI_IO_STATUS_TARGET_BUSY 0x08
#define EFI_SCSI_IO_STATUS_TARGET_INTERMEDIATE 0x10
#define EFI_SCSI_IO_STATUS_TARGET_INTERMEDIATE_CONDITION_METn 0x14
#define EFI_SCSI_IO_STATUS_TARGETReservation_CONFLICT 0x18
```

(continues on next page)
Description

This function sends the SCSI Request Packet specified by Packet to the SCSI Device.

If the SCSI Bus supports non-blocking I/O and Event is not NULL, then this function will return immediately after the command is sent to the SCSI Device, and will later signal Event when the command has completed. If the SCSI Bus supports non-blocking I/O and Event is NULL, then this function will send the command to the SCSI Device and block until it is complete. If the SCSI Bus does not support non-blocking I/O, the Event parameter is ignored, and the function will send the command to the SCSI Device and block until it is complete.

If Packet is successfully sent to the SCSI Device, then EFI_SUCCESS is returned.

If Packet cannot be sent because there are too many packets already queued up, then EFI_NOT_READY is returned. The caller may retry Packet at a later time.

If a device error occurs while sending the Packet, then EFI_DEVICE_ERROR is returned.

If a timeout occurs during the execution of Packet, then EFI_TIMEOUT is returned.

If any field of Packet is invalid, then EFI_INVALID_PARAMETER is returned.

If the data buffer described by DataBuffer and TransferLength is too big to be transferred in a single command, then EFI_BAD_BUFFER_SIZE is returned. The number of bytes actually transferred is returned in TransferLength.

If the command described in Packet is not supported by the SCSI Host Controller that produces the SCSI bus, then EFI_UNSUPPORTED is returned.

If EFI_SUCCESS, EFI_BAD_BUFFER_SIZE, EFI_DEVICE_ERROR, or EFI_TIMEOUT is returned, then the caller must examine the status fields in Packet in the following precedence order: HostAdapterStatus followed by TargetStatus followed by SenseDataLength, followed by SenseData. If non-blocking I/O is being used, then the status fields in Packet will not be valid until the Event associated with Packet is signaled.

If EFI_NOT_READY, EFI_INVALID_PARAMETER or EFI_UNSUPPORTED is returned, then Packet was never sent, so the status fields in Packet are not valid. If non-blocking I/O is being used, the Event associated with Packet will not be signaled.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The SCSI Request Packet was sent by the host. For read and bi-directional commands, InTransferLength bytes were transferred to InDataBuffer. For write and bi-directional commands, OutTransferLength bytes were transferred from OutDataBuffer. See HostAdapterStatus, TargetStatus, SenseDataLength, and SenseData in that order for additional status information.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>The SCSI Request Packet was not executed. For read and bi-directional commands, the number of bytes that could be transferred is returned in InTransferLength. For write and bi-directional commands, the number of bytes that could be transferred is returned in OutTransferLength. See HostAdapterStatus and TargetStatus in that order for additional status information.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The SCSI Request Packet could not be sent because there are too many SCSI Command Packets already queued. The caller may retry again later.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to send the SCSI Request Packet. See HostAdapterStatus, TargetStatus, SenseDataLength, and SenseData in that order for additional status information.</td>
</tr>
</tbody>
</table>

continues on next page
Table 15.3 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The contents of CommandPacket are invalid. The SCSI Request Packet was not sent, so no additional status information is available.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The command described by the SCSI Request Packet is not supported by the SCSI initiator (i.e., SCSI Host Controller). The SCSI Request Packet was not sent, so no additional status information is available.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>A timeout occurred while waiting for the SCSI Request Packet to execute. See HostAdapterStatus, TargetStatus, SenseDataLength, and SenseData in that order for additional status information.</td>
</tr>
</tbody>
</table>

15.5 SCSI Device Paths

An EFI_SCSI_IO_PROTOCOL must be installed on a handle for its services to be available to SCSI device drivers. In addition to the EFI_SCSI_IO_PROTOCOL, an EFIDEVICE_PATH_PROTOCOL must also be installed on the same handle. See Protocols – Device Path Protocol for detailed description of the EFIDEVICE_PATH_PROTOCOL.

The SCSI Driver Model defined in this document can support the SCSI channel generated or emulated by multiple architectures, such as Parallel SCSI, ATAPI, Fibre Channel, InfiniBand, and other future channel types. In this section, there are four example device paths provided, including SCSI device path, ATAPI device path, Fibre Channel device path and InfiniBand device path.

15.5.1 SCSI Device Path Example

Table 15.4 shows an example device path for a SCSI device controller on a desktop platform. This SCSI device controller is connected to a SCSI channel that is generated by a PCI SCSI host controller. The PCI SCSI host controller generates a single SCSI channel, it is located at PCI device number 0x07 and PCI function 0x00, and is directly attached to a PCI root bridge. The SCSI device controller is assigned SCSI Id 2, and its LUN is 0.

This sample device path consists of an ACPI Device Path Node, a PCI Device Path Node, a SCSI Node, and a Device PathEndStructure. The_HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI(PNP0A03,0)/PCI(7,0)/SCSI(2,0).

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x03</td>
<td>Generic Device Path Header - Type Message Device Path</td>
</tr>
</tbody>
</table>

15.5. SCSI Device Paths 672 continues on next page
Table 15.4 – continued from previous page

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x02</td>
<td>Sub type - SCSI</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x08</td>
<td>Length - 0x08 bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x02</td>
<td>0x0002</td>
<td>Target ID on the SCSI bus (PUN)</td>
</tr>
<tr>
<td>0x18</td>
<td>0x02</td>
<td>0x0000</td>
<td>Logical Unit Number (LUN)</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x1B</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x1C</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

### 15.5.2 ATAPI Device Path Example

The Table below, ATAPI Device Path Examples, shows an example device path for an ATAPI device on a desktop platform. This ATAPI device is connected to the IDE bus on Primary channel, and is configured as the Master device on the channel. The IDE bus is generated by the IDE controller that is a PCI device. It is located at PCI device number 0x1F and PCI function 0x01, and is directly attached to a PCI root bridge.

This sample device path consists of an ACPI Device Path Node, a PCI Device Path Node, an ATAPI Node, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

```
ACPI(PNP0A03,0)/PCI(7,0)/ATA(Primary,Master,0).
```

Table 15.5: ATAPI Device Path Examples

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string 'PNP' and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x03</td>
<td>Generic Device Path Header - Type Message Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ATAPI</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x08</td>
<td>Length - 0x08 bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x01</td>
<td>0x00</td>
<td>PrimarySecondary - Set to zero for primary or one for secondary.</td>
</tr>
<tr>
<td>0x17</td>
<td>0x01</td>
<td>0x00</td>
<td>SlaveMaster - set to zero for master or one for slave.</td>
</tr>
<tr>
<td>0x18</td>
<td>0x02</td>
<td>0x0000</td>
<td>Logical Unit Number,LUN.</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x1B</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x1C</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

15.5. SCSI Device Paths
15.5.3 Fibre Channel Device Path Example

Section 10.3.4.3 shows an example device path for a SCSI device that is connected to a Fibre Channel Port on a desktop platform. The Fibre Channel Port is a PCI device that is located at PCI device number 0x08 and PCI function 0x00, and is directly attached to a PCI root bridge. The Fibre Channel Port is addressed by the World Wide Number, and is assigned as X (X is a 64bit value); the SCSI device’s Logical Unit Number is 0.

This sample device path consists of an ACPI Device Path Node, a PCI Device Path Node, a Fibre Channel Device Path Node, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

\[
\text{ACPI(PNP0A03,0)/PCI(8,0)/Fibre(X,0).}
\]

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string 'PNP' and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x08</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x03</td>
<td>Generic Device Path Header - Type Message Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x02</td>
<td>Sub type - Fibre Channel</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x24</td>
<td>Length - 0x24 bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x04</td>
<td>0x00</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x08</td>
<td>X</td>
<td>Fibre Channel World Wide Number</td>
</tr>
<tr>
<td>0x22</td>
<td>0x08</td>
<td>0x00</td>
<td>Fibre Channel Logical Unit Number (LUN).</td>
</tr>
<tr>
<td>0x2A</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x2B</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x2C</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

15.5.4 InfiniBand Device Path Example

The Table below, InfiniBand Device Path Examples, shows an example device path for a SCSI device in an InfiniBand Network. This SCSI device is connected to a single SCSI channel generated by a SCS Host Adapter, and the SCS Host Adapter is an end node in the InfiniBand Network. The SCS Host Adapter is a PCI device that is located at PCI device number 0x07 and PCI function 0x00, and is directly attached to a PCI root bridge. The SCSI device is addressed by the (IOU X, IOC Y, DeviceId Z) in the InfiniBand Network. (X, Y, Z are EUI-64 compliant identifiers).

This sample device path consists of an ACPI Device Path Node, a PCI Device Path Node, an InfiniBand Node, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:
### Table 15.7: InfiniBand Device Path Examples

<table>
<thead>
<tr>
<th>Offset</th>
<th>Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string 'PNP' and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x03</td>
<td>Generic Device Path Header - Type Message Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x09</td>
<td>Sub type - InfiniBand</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x20</td>
<td>Length - 0x20 bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x04</td>
<td>0x00</td>
<td>Reserved</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x08</td>
<td>X</td>
<td>64bit node GUID of the IOU</td>
</tr>
<tr>
<td>0x22</td>
<td>0x08</td>
<td>Y</td>
<td>64bit GUID of the IOC</td>
</tr>
<tr>
<td>0x2A</td>
<td>0x08</td>
<td>Z</td>
<td>64bit persistent ID of the device.</td>
</tr>
<tr>
<td>0x32</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x33</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x34</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

### 15.6 SCSI Pass Thru Device Paths

An `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` must be installed on a handle for its services to be available to UEFI drivers and applications. In addition to the `EFI_EXT_SCSI_PASS_THRU_PROTOCOL`, the `EFI Device Path Protocol` must also be installed on the same handle. See Protocols – Device Path Protocol for a detailed description of the `EFI_DEVICE_PATH_PROTOCOL`.

A device path describes the location of a hardware component in a system from the processor’s point of view. This includes the list of busses that lie between the processor and the SCSI controller. The EFI Specification takes advantage of the ACPI Specification to name system components. For the following set of examples, a PCI SCSI controller is assumed. The examples will show a SCSI controller on the root PCI bus, and a SCSI controller behind a PCI-PCI bridge. In addition, an example of a multichannel SCSI controller will be shown.

See Single Channel PCI SCSI Controller shows an example device path for a single channel PCI SCSI controller that is located at PCI device number 0x07 and PCI function 0x00, and is directly attached to a PCI root bridge. This device path consists of an ACPI Device Path Node, a PCI Device Path Node, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI(0A03,0)/PCI(7,0).
Table 15.8: Single Channel PCI SCSI Controller

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0xA03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string 'PNP' and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

The Table below, *Single Channel PCI SCSI Controller Behind a PCI Bridge*, shows an example device path for a single channel PCI SCSI controller that is located behind a PCI to PCI bridge at PCI device number 0x07 and PCI function 0x00. The PCI to PCI bridge is directly attached to a PCI root bridge, and it is at PCI device number 0x05 and PCI function 0x00. This device path consists of an ACPI Device Path Node, two PCI Device Path Nodes, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation for this device path is:

ACPI(PNP0A03,0)/PCI(5,0)/PCI(7,0).

Table 15.9: Single Channel PCI SCSI Controller Behind a PCI Bridge

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0xA03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string 'PNP' and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x05</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x17</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x18</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x19</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>
Table 15.10 shows an example device path for channel #3 of a four channel PCI SCSI controller that is located behind a PCI to PCI bridge at PCI device number 0x07 and PCI function 0x00. The PCI to PCI bridge is directly attached to a PCI root bridge, and it is at PCI device number 0x05 and PCI function 0x00. This device path consists of an ACPI Device Path Node, two PCI Device Path Nodes, a Controller Node, and a Device Path End Structure. The _HID and _UID must match the ACPI table description of the PCI Root Bridge. The shorthand notation of the device paths for all four of the SCSI channels are listed below:

ACPI(PNP0A03,0)/PCI(5,0)/PCI(7,0)/Ctrl(0)
ACPI(PNP0A03,0)/PCI(5,0)/PCI(7,0)/Ctrl(1)
ACPI(PNP0A03,0)/PCI(5,0)/PCI(7,0)/Ctrl(2)
ACPI(PNP0A03,0)/PCI(5,0)/PCI(7,0)/Ctrl(3)

The following table shows the last device path listed.

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x01</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>0x01</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>0x02</td>
<td>0x02</td>
<td>0x0C</td>
<td>Length - 0x0C bytes</td>
</tr>
<tr>
<td>0x04</td>
<td>0x04</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string 'PNP' and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>0x08</td>
<td>0x04</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>0x0C</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x0D</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x0E</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x10</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x11</td>
<td>0x01</td>
<td>0x05</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x12</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x13</td>
<td>0x01</td>
<td>0x01</td>
<td>Sub type - PCI</td>
</tr>
<tr>
<td>0x14</td>
<td>0x02</td>
<td>0x06</td>
<td>Length - 0x06 bytes</td>
</tr>
<tr>
<td>0x16</td>
<td>0x01</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>0x17</td>
<td>0x01</td>
<td>0x07</td>
<td>PCI Device</td>
</tr>
<tr>
<td>0x18</td>
<td>0x01</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>0x19</td>
<td>0x01</td>
<td>0x05</td>
<td>Sub type - Controller</td>
</tr>
<tr>
<td>0x1A</td>
<td>0x02</td>
<td>0x08</td>
<td>Length - 0x08 bytes</td>
</tr>
<tr>
<td>0x1C</td>
<td>0x04</td>
<td>0x0003</td>
<td>Controller Number</td>
</tr>
<tr>
<td>0x20</td>
<td>0x01</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>0x21</td>
<td>0x01</td>
<td>0xFF</td>
<td>Sub type - End of Entire Device Path</td>
</tr>
<tr>
<td>0x22</td>
<td>0x02</td>
<td>0x04</td>
<td>Length - 0x04 bytes</td>
</tr>
</tbody>
</table>

15.6. SCSI Pass Thru Device Paths


15.7 Extended SCSI Pass Thru Protocol

This section defines the Extended SCSI Pass Thru Protocol. This protocol allows information about a SCSI channel to be collected, and allows SCSI Request Packets to be sent to any SCSI devices on a SCSI channel even if those devices are not boot devices. This protocol is attached to the device handle of each SCSI channel in a system that the protocol supports, and can be used for diagnostics. It may also be used to build a Block I/O driver for SCSI hard drives and SCSI CD-ROM or DVD drives to allow those devices to become boot devices. As ATAPI cmds are derived from SCSI cmds, the above statements also are applicable for ATAPI devices attached to a ATA controller. Packet-based commands (ATAPI cmds) would be sent to ATAPI devices only through the Extended SCSI Pass Thru Protocol.

15.7.1 EFI_EXT_SCSI_PASS_THRU_PROTOCOL

This section provides a detailed description of the EFI_EXT_SCSI_PASS_THRU_PROTOCOL.

Summary

Provides services that allow SCSI Pass Thru commands to be sent to SCSI devices attached to a SCSI channel. It also allows packet-based commands (ATAPI cmds) to be sent to ATAPI devices attached to a ATA controller.

GUID

#define EFI_EXT_SCSI_PASS_THRU_PROTOCOL_GUID
{0x143b7632, 0xb81b, 0x4cb7, 0xab, 0xd3, 0xb6, 0x25, 0xa5, 0xb9, 0xbf, 0xfe}

Protocol Interface Structure

typedef struct _EFI_EXT_SCSI_PASS_THRU_PROTOCOL {
    EFI_EXT_SCSI_PASS_THRU_MODE *Mode;
    EFI_EXT_SCSI_PASS_THRU_PASSTHRU PassThru;
    EFI_EXT_SCSI_PASS_THRU_GET_NEXT_TARGET_LUN GetNextTargetLun;
    EFI_EXT_SCSI_PASS_THRU_BUILDDEVICE_PATH BuildDevicePath;
    EFI_EXT_SCSI_PASS_THRU_GETTARGET_LUN GetTargetLun;
    EFI_EXT_SCSI_PASS_THRU_RESETCHANNEL ResetChannel;
    EFI_EXT_SCSI_PASS_THRU_RESETTARGET_LUN ResetTargetLun;
    EFI_EXT_SCSI_PASS_THRU_GETNEXTTARGET GetNextTarget;
    EFI_EXT_SCSI_PASS_THRU_PROTOCOL;
} EFI_EXT_SCSI_PASS_THRU_PROTOCOL;

Parameters

Mode

A pointer to the EFI_EXT_SCSI_PASS_THRU_MODE data for this SCSI channel. EFI_EXT_SCSI_PASS_THRU_MODE is defined in “Related Definitions” below.

PassThru

Sends a SCSI Request Packet to a SCSI device that is Connected to the SCSI channel. See the EFI_EXT_SCSI_PASS_THRU_PROTOCOL.PassThru() function description.

GetNextTargetLun

Retrieves the list of legal Target IDs and LUNs for the SCSI devices on a SCSI channel. See the EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetNextTargetLun() function description.

BuildDevicePath

Allocates and builds a device path node for a SCSI Device on a SCSI channel. See the EFI_EXT_SCSI_PASS_THRU_PROTOCOL.BuildDevicePath() function description.
getTargetLun
Translates a device path node to a Target ID and LUN. See the EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetTargetLun() function description.

ResetChannel
Resets the SCSI channel. This operation resets all the SCSI devices connected to the SCSI channel. See the EFI_EXT_SCSI_PASS_THRU_PROTOCOL.ResetChannel() function description.

ResetTargetLun
Resets a SCSI device that is connected to the SCSI channel. See the EFI_EXT_SCSI_PASS_THRU_PROTOCOL.ResetTargetLun() function description.

GetNextTarget
Retrieves the list of legal Target IDs for the SCSI devices on a SCSI channel. See the EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetNextTarget() function description.

The following data values in the EFI_EXT_SCSI_PASS_THRU_MODE interface are read-only.

AdapterId
The Target ID of the host adapter on the SCSI channel.

Attributes
Additional information on the attributes of the SCSI channel. See “Related Definitions” below for the list of possible attributes.

IoAlign
Supplies the alignment requirement for any buffer used in a data transfer. IoAlign values of 0 and 1 mean that the buffer can be placed anywhere in memory. Otherwise, IoAlign must be a power of 2, and the requirement is that the start address of a buffer must be evenly divisible by IoAlign with no remainder.

Related Definitions

typedef struct {
    UINT32 *AdapterId; *
    UINT32 *Attributes; *
    UINT32 *IoAlign; *
} EFI_EXT_SCSI_PASS_THRU_MODE;

#define TARGET_MAX_BYTES 0x10
#define EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL 0x0001
#define EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL 0x0002
#define EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_NONBLOCKIO 0x0004

EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL
If this bit is set, then the EFI_EXT_SCSI_PASS_THRU_PROTOCOL interface is for physical devices on the SCSI channel.

EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL
If this bit is set, then the EFI_EXT_SCSI_PASS_THRU_PROTOCOL interface is for logical devices on the SCSI channel.

EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_NONBLOCKIO
If this bit is set, then the EFI_EXT_SCSI_PASS_THRU_PROTOCOL interface supports non blocking I/O. Every EFI_EXT_SCSI_PASS_THRU_PROTOCOL must support blocking I/O. The support of nonblocking I/O is optional.

Description
The EFI_EXT_SCSI_PASS_THRU_PROTOCOL provides information about a SCSI channel and the ability to send SCI Request Packets to any SCSI device attached to that SCSI channel. The information includes the Target ID of the
host controller on the SCSI channel and the attributes of the SCSI channel.

The printable name for the SCSI controller, and the printable name of the SCSI channel can be provided through the `EFI_COMPONENT_NAME2_PROTOCOL` for multiple languages.

The `Attributes` field of the `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` interface tells if the interface is for physical SCSI devices or logical SCSI devices. Drivers for non-RAID SCSI controllers will set both the `EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL`, and the `EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL` bits.

Drivers for RAID controllers that allow access to the physical devices and logical devices will produce two `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` interfaces: one with just the `EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL` bit set and another with just the `EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL` bit set. One interface can be used to access the physical devices attached to the RAID controller, and the other can be used to access the logical devices attached to the RAID controller for its current configuration.

Drivers for RAID controllers that do not allow access to the physical devices will produce one `EFI_EXT_SCSI_PASS_THROUGH_PROTOCOL` interface with just the `EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL` bit set. The interface for logical devices can also be used by a file system driver to mount the RAID volumes. An `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` with neither `EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL` nor `EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL` set is an illegal configuration.

The `Attributes` field also contains the `EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_NONBLOCKIO` bit. All `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` interfaces must support blocking I/O. If this bit is set, then the interface support both blocking I/O and nonblocking I/O.

Each `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` instance must have an associated device path. Typically this will have an ACPI device path node and a PCI device path node, although variation will exist. For a SCSI controller that supports only one channel per PCI bus/device/function, it is recommended, but not required, that an additional Controller device path node (for controller 0) be appended to the device path.

For a SCSI controller that supports multiple channels per PCI bus/device/function, it is required that a Controller device path node be appended for each channel.

Additional information about the SCSI channel can be obtained from protocols attached to the same handle as the `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` or one of its parent handles. This would include the device I/O abstraction used to access the internal registers and functions of the SCSI controller.

### 15.7.2 EFI_EXT_SCSI_PASS_THRU_PROTOCOL.PassThru()

**Summary**

Sends a SCSI Request Packet to a SCSI device that is attached to the SCSI channel. This function supports both blocking I/O and nonblocking I/O. The blocking I/O functionality is required, and the nonblocking I/O functionality is optional.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI *EFI_EXT_SCSI_PASS_THRU_PASSSTHRU) (  
    IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL
    IN EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_PHYSICAL
    IN EFI_EXT_SCSI_PASS_THRU_ATTRIBUTES_LOGICAL
    IN UINT8
    IN UINT64
    IN OUT EFI_EXT_SCSI_PASS_THRU_SCSI_REQUEST_PACKET
    IN EFI_EVENT
);```

---

15.7. Extended SCSI Pass Thru Protocol 680
Parameters

This
A pointer to the `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` instance. Type `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` is defined in `Extended SCSI Pass Thru Protocol`.

Target
The Target is an array of size `TARGET_MAX_BYTES` and it represents the id of the SCSI device to send the SCSI Request Packet. Each transport driver may choose to utilize a subset of this size to suit the needs of transport target representation. For example, a Fibre Channel driver may use only 8 bytes (WWN) to represent an FC target.

Lun
The LUN of the SCSI device to send the SCSI Request Packet.

Packet
A pointer to the SCSI Request Packet to send to the SCSI device specified by `Target` and `Lun`. See “Related Definitions” below for a description of `EFI_EXT_SCSI_PASS_THRU_SCSI_REQUEST_PACKET`.

Event
If nonblocking I/O is not supported then `Event` is ignored, and blocking I/O is performed. If `Event` is `NULL`, then blocking I/O is performed. If `Event` is not `NULL` and non blocking I/O is supported, then nonblocking I/O is performed, and `Event` will be signaled when the SCSI Request Packet completes.

Related Definitions

```c
typedef struct {
    UINT64 Timeout;
    VOID *InDataBuffer;
    VOID *OutDataBuffer;
    VOID *SenseData;
    VOID *Cdb;
    UINT32 InTransferLength;
    UINT32 OutTransferLength;
    UINT8 CdbLength;
    UINT8 DataDirection;
    UINT8 HostAdapterStatus;
    UINT8 TargetStatus;
    UINT8 SenseDataLength;
} EFI_EXT_SCSI_PASS_THRU_SCSI_REQUEST_PACKET;
```

Timeout
The timeout, in 100 ns units, to use for the execution of this SCSI Request Packet. A `Timeout` value of 0 means that this function will wait indefinitely for the SCSI Request Packet to execute. If `Timeout` is greater than zero, then this function will return `EFI_TIMEOUT` if the time required to execute the SCSI Request Packet is greater than `Timeout`.

InDataBuffer
A pointer to the data buffer to transfer between the SCSI controller and the SCSI device for read and bidirectional commands. For all write and non data commands where `InTransferLength` is 0 this field is optional and may be `NULL`. If this field is not `NULL`, then it must be aligned on the boundary specified by the `IoAlign` field in the `EFI_EXT_SCSI_PASS_THRU_MODE` structure.

OutDataBuffer
A pointer to the data buffer to transfer between the SCSI controller and the SCSI device for write or bidirectional commands. For all read and non data commands where `OutTransferLength` is 0 this field is optional and may be `NULL`. If this field is not `NULL`, then it must be aligned on the boundary specified by the `IoAlign` field in the `EFI_EXT_SCSI_PASS_THRU_MODE` structure.
SenseData
A pointer to the sense data that was generated by the execution of the SCSI Request Packet. If SenseDataLength is 0, then this field is optional and may be NULL. It is strongly recommended that a sense data buffer of at least 252 bytes be provided to guarantee the entire sense data buffer generated from the execution of the SCSI Request Packet can be returned. If this field is not NULL, then it must be aligned to the boundary specified in the IoAlign field in the EFI_EXT_SCSI_PASS_THRU_MODE structure.

Cdb
A pointer to buffer that contains the Command Data Block to send to the SCSI device specified by Target and Lun.

InTransferLength
On Input, the size, in bytes, of InDataBuffer. On output, the number of bytes transferred between the SCSI controller and the SCSI device. If InTransferLength is larger than the SCSI controller can handle, no data will be transferred. InTransferLength will be updated to contain the number of bytes that the SCSI controller is able to transfer, and EFI_BAD_BUFFER_SIZE will be returned.

OutTransferLength
On Input, the size, in bytes of OutDataBuffer. On Output, the Number of bytes transferred between SCSI Controller and the SCSI device. If OutTransferLength is larger than the SCSI controller can handle, no data will be transferred, OutTransferLength will be updated to contain the number of bytes that the SCSI controller is able to transfer, and EFI_BAD_BUFFER_SIZE will be returned.

CdbLength
The length, in bytes, of the buffer Cdb. The standard values are 6, 10, 12, and 16, but other values are possible if a variable length CDB is used.

DataDirection
The direction of the data transfer. 0 for reads, 1 for writes. A value of 2 is Reserved for Bi-Directional SCSI commands. For example XDREADWRITE. All other values are reserved, and must not be used.

HostAdapterStatus
The status of the host adapter specified by This when the SCSI Request Packet was executed on the target device. See the possible values listed below. If bit 7 of this field is set, then HostAdapterStatus is a vendor defined error code.

TargetStatus
The status returned by the device specified by Target and Lun when the SCSI Request Packet was executed. See the possible values listed below.

SenseDataLength
On input, the length in bytes of the SenseData buffer. On output, the number of bytes written to the SenseData buffer.

```
// DataDirection
#
#define EFI_EXT_SCSI_DATA_DIRECTION_READ 0
#define EFI_EXT_SCSI_DATA_DIRECTION_WRITE 1
#define EFI_EXT_SCSI_DATA_DIRECTION_BIDIRECTIONAL 2
#
// HostAdapterStatus
#
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_OK 0x00
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_TIMEOUT_COMMAND 0x09
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_TIMEOUT 0x0b
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_MESSAGE_REJECT 0x0d
```
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_BUS_RESET 0x0e
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_PARITY_ERROR 0xf
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_REQUESTSENSEFAILED 0x10
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_SELECTION_TIMEOUT 0x11
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_DATA_OVERRUN_UNDERRUN 0x12
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_BUS_FREE 0x13
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_PHASE_ERROR 0x14
#define EFI_EXT_SCSI_STATUS_HOST_ADAPTER_OTHER 0x7f

// TargetStatus

#define EFI_EXT_SCSI_STATUS_TARGET_GOOD 0x00
#define EFI_EXT_SCSI_STATUS_TARGET_CHECK_CONDITION 0x02
#define EFI_EXT_SCSI_STATUS_TARGET_CONDITION_MET 0x04
#define EFI_EXT_SCSI_STATUS_TARGET_BUSY 0x08
#define EFI_EXT_SCSI_STATUS_TARGET_INTERMEDIATE 0x10
#define EFI_EXT_SCSI_STATUS_TARGET_INTERMEDIATECONDITIONMET 0x14
#define EFI_EXT_SCSI_STATUS_TARGETReservationCONFLICT 0x18
#define EFI_EXT_SCSI_STATUS_TARGET_TASK_SET_FULL 0x28
#define EFI_EXT_SCSI_STATUS_TARGET_ACA_ACTIVE 0x30
#define EFI_EXT_SCSI_STATUS_TARGET_TASK_ABORTED 0x40

Description

The \texttt{EFI_EXT_SCSI_PASS_THRU_PROTOCOL.PassThru()} function sends the SCSI Request Packet specified by \texttt{Packet} to the SCSI device specified by \texttt{Target} and \texttt{Lun}. If the driver supports nonblocking I/O and \texttt{Event} is not \texttt{NULL}, then the driver will return immediately after the command is sent to the selected device, and will later signal \texttt{Event} when the command has completed.

If the driver supports nonblocking I/O and \texttt{Event} is \texttt{NULL}, then the driver will send the command to the selected device and block until it is complete.

If the driver does not support nonblocking I/O, then the \texttt{Event} parameter is ignored, and the driver will send the command to the selected device and block until it is complete.

If \texttt{Packet} is successfully sent to the SCSI device, then EFI\_SUCCESS is returned.

If \texttt{Packet} cannot be sent because there are too many packets already queued up, then EFI\_NOT\_READY is returned. The caller may retry \texttt{Packet} at a later time.

If a device error occurs while sending the \texttt{Packet}, then EFI\_DEVICE\_ERROR is returned.

If a timeout occurs during the execution of \texttt{Packet}, then EFI\_TIMEOUT is returned.

If a device is not present but the target/LUN address in the packet are valid, then EFI\_TIMEOUT is returned, and HostStatus is set to EFI\_EXT\_SCSI\_STATUS\_HOST\_ADAPTER\_TIMEOUT\_COMMAND.

If \texttt{Target} or \texttt{Lun} are not in a valid range for the SCSI channel, then EFI\_INVALID\_PARAMETER is returned. If \texttt{InDataBuffer}, \texttt{OutDataBuffer} or \texttt{SenseData} do not meet the alignment requirement specified by the IoAlign field of the EFI\_EXT\_SCSI\_PASS\_THRU\_MODE structure, then EFI\_INVALID\_PARAMETER is returned. If any of the other fields of \texttt{Packet} are invalid, then EFI\_INVALID\_PARAMETER is returned.

If the data buffer described by \texttt{InDataBuffer} and \texttt{InTransferLength} is too big to be transferred in a single command, then no data is transferred and EFI\_BAD\_BUFFER\_SIZE is returned. The number of bytes that can be transferred in a single command are returned in \texttt{InTransferLength}.

If the data buffer described by \texttt{OutDataBuffer} and \texttt{OutTransferLength} is too big to be transferred in a single command, then no data is transferred and EFI\_BAD\_BUFFER\_SIZE is returned. The number of bytes that can be transferred in
a single command are returned in \textit{OutTransferLength}.

If the command described in \textit{Packet} is not supported by the host adapter, then \textit{EFI_UNSUPPORTED} is returned.

If \textit{EFI_SUCCESS}, \textit{EFI_BAD_BUFFER_SIZE}, \textit{EFI_DEVICE_ERROR}, or \textit{EFI_TIMEOUT} is returned, then the caller must examine the status fields in \textit{Packet} in the following precedence order: \textit{HostAdapterStatus} followed by \textit{TargetStatus} followed by \textit{SenseDataLength}, followed by \textit{SenseData}.

If nonblocking I/O is being used, then the status fields in \textit{Packet} will not be valid until the Event associated with \textit{Packet} is signaled.

If \textit{EFI_NOT_READY}, \textit{EFI_INVALID_PARAMETER} or \textit{EFI_UNSUPPORTED} is returned, then \textit{Packet} was never sent, so the status fields in \textit{Packet} are not valid. If nonblocking I/O is being used, the Event associated with \textit{Packet} will not be signaled.

\textbf{Note:} Some examples of SCSI read commands are \textit{READ}, \textit{INQUIRY}, and \textit{MODE_SENSE}.

\textbf{Note:} Some examples of SCSI write commands are \textit{WRITE} and \textit{MODE_SELECT}.

\textbf{Note:} An example of a SCSI non data command is \textit{TEST_UNIT_READY}.

\textbf{Status Codes Returned}

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\texttt{EFI_SUCCESS}</td>
<td>The SCSI Request Packet was sent by the host. For bi-directional commands, \textit{InTransferLength} bytes were transferred from \textit{InDataBuffer}. For write and bi-directional commands, \textit{OutTransferLength} bytes were transferred by \textit{OutDataBuffer}. See \textit{HostAdapterStatus}, \textit{TargetStatus}, \textit{SenseDataLength}, and \textit{SenseData} in that order for additional status information.</td>
</tr>
<tr>
<td>\texttt{EFI_BAD_BUFFER_SIZE}</td>
<td>The SCSI Request Packet was not executed. The number of bytes that could be transferred is returned in \textit{InTransferLength}. For write and bi-directional commands, \textit{OutTransferLength} bytes were transferred by \textit{OutDataBuffer}. See \textit{HostAdapterStatus}, \textit{TargetStatus}, and \textit{SenseData} in that order for additional status information.</td>
</tr>
<tr>
<td>\texttt{EFI_NOT_READY}</td>
<td>The SCSI Request Packet could not be sent because there are too many SCSI Request Packets already queued. The caller may retry again later.</td>
</tr>
<tr>
<td>\texttt{EFI_DEVICE_ERROR}</td>
<td>A device error occurred while attempting to send the SCSI Request Packet. See \textit{HostAdapterStatus}, \textit{TargetStatus}, \textit{SenseDataLength}, and \textit{SenseData} in that order for additional status information.</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>\textit{Target}, \textit{Lun}, or the contents of \textit{ScsiRequestPacket} are invalid. The SCSI Request Packet was not sent, so no additional status information is available.</td>
</tr>
<tr>
<td>\texttt{EFI_UNSUPPORTED}</td>
<td>The command described by the SCSI Request Packet is not supported by the host adapter. This includes the case of Bi-directional SCSI commands not supported by the implementation. The SCSI Request Packet was not sent, so no additional status information is available.</td>
</tr>
<tr>
<td>\texttt{EFI_TIMEOUT}</td>
<td>A timeout occurred while waiting for the SCSI Request Packet to execute. See \textit{HostAdapterStatus}, \textit{TargetStatus}, \textit{SenseDataLength}, and \textit{SenseData} in that order for additional status information.</td>
</tr>
</tbody>
</table>
15.7.3 *EFI_EXT_SCSI_PASS_THRU_PROTOCOL*.GetNextTargetLun()

**Summary**

Used to retrieve the list of legal Target IDs and LUNs for SCSI devices on a SCSI channel. These can either be the list SCSI devices that are actually present on the SCSI channel, or the list of legal Target Ids and LUNs for the SCSI channel. Regardless, the caller of this function must probe the Target ID and LUN returned to see if a SCSI device is actually present at that location on the SCSI channel.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI *EFI_EXT_SCSI_PASS_THRU_GET_NEXT_TARGET_LUN) (  
    IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL *This,  
    IN OUT UINT8 **Target,  
    IN OUT UINT64 *Lun
);
```

**Parameters**

- **This**
  A pointer to the `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` instance. Type `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` is defined in *Extended SCSI Pass Thru Protocol*.

- **Target**
  On input, a pointer to a legal Target ID (an array of size `TARGET_MAX_BYTES`) for a SCSI device present on the SCSI channel. On output, a pointer to the next legal Target ID (an array of `TARGET_MAX_BYTES`) of a SCSI device on a SCSI channel. An input value of `0xFF`'s (all bytes in the array are `0xFF`) in the Target array retrieves the first legal Target ID for a SCSI device present on a SCSI channel.

- **Lun**
  On input, a pointer to the LUN of a SCSI device present on the SCSI channel. On output, a pointer to the LUN of the next SCSI device ID on a SCSI channel.

**Description**

The `EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetNextTargetLun()` function retrieves a list of legal Target ID and LUN of a SCSI channel. If on input a `Target` is specified by all `0xFF` in the Target array, then the first legal Target ID and LUN for a SCSI device on a SCSI channel is returned in `Target` and `Lun`, and `EFI_SUCCESS` is returned.

If `Target` and `Lun` is a Target ID and LUN value that was returned on a previous call to `GetNextTargetLun()` , then the next legal Target ID and LUN for a SCSI device on the SCSI channel is returned in `Target` and `Lun`, and `EFI_SUCCESS` is returned.

If `Target array` is not all `0xFF`'s and `Target` and `Lun` were not returned on a previous call to `GetNextTargetLun()` , then `EFI_INVALID_PARAMETER` is returned.

If `Target` and `Lun` are the Target ID and LUN of the last SCSI device on the SCSI channel, then `EFI_NOT_FOUND` is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The Target ID and LUN of the next SCSI device on the SCSI channel was returned in <code>Target</code> and <code>Lun</code>.</td>
</tr>
<tr>
<td><code>EFI_NOT_FOUND</code></td>
<td>There are no more SCSI devices on this SCSI channel.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td><code>Target array</code> is not all <code>0xFF</code>'s, and <code>Target</code> and <code>Lun</code> were not returned on a previous call to <code>GetNextTargetLun()</code>.</td>
</tr>
</tbody>
</table>
### 15.7.4 EFI_EXT_SCSI_PASS_THRU_PROTOCOL.BuildDevicePath()

**Summary**

Used to allocate and build a device path node for a SCSI device on a SCSI channel.

**Prototype**

```c
typedef EFI_STATUS
   (EFIAPI *EFI_EXT_SCSI_PASS_THRU_BUILD_DEVICE_PATH) (
   IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL *This,
   IN UINT8 *Target,
   IN UINT64 Lun
   OUT EFI_DEVICE_PATH_PROTOCOL **DevicePath
   );
```

**Parameters**

- **This**: A pointer to the `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` instance. Type `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` is defined in *Extended SCSI Pass Thru Protocol*.

- **Target**: The Target is an array of size `TARGET_MAX_BYTES` and it specifies the Target ID of the SCSI device for which a device path node is to be allocated and built. Transport drivers may choose to utilize a subset of this size to suit the representation of targets. For example, a Fibre Channel driver may use only 8 bytes (WWN) in the array to represent a FC target.

- **Lun**: The Lun of the SCSI device for which a device path node is to be allocated and built.

- **DevicePath**: A pointer to a single device path node that describes the SCSI device specified by `Target` and `Lun`. This function is responsible for allocating the buffer `DevicePath` with the boot service `AllocatePool()`. It is the caller's responsibility to free `DevicePath` when the caller is finished with `DevicePath`.

**Description**

The `EFI_EXT_SCSI_PASS_THRU_PROTOCOL.BuildDevicePath()` function allocates and builds a single device path node for the SCSI device specified by `Target` and `Lun`. If the SCSI device specified by `Target` and `Lun` are not present on the SCSI channel, then `EFI_NOT_FOUND` is returned. If `DevicePath` is `NULL`, then `EFI_INVALID_PARAMETER` is returned. If there are not enough resources to allocate the device path node, then `EFI_OUT_OF_RESOURCES` is returned. Otherwise, `DevicePath` is allocated with the boot service `AllocatePool()`, the contents of `DevicePath` are initialized to describe the SCSI device specified by `Target` and `Lun`, and `EFI_SUCCESS` is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device path node that describes the SCSI device specified by <code>Target</code> and <code>Lun</code> was allocated and returned in <code>DevicePath</code>.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The SCSI devices specified by <code>Target</code> and <code>Lun</code> does not exist on the SCSI channel.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>DevicePath</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There are not enough resources to allocate <code>DevicePath</code>.</td>
</tr>
</tbody>
</table>
15.7.5 EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetTargetLun()

Summary
Used to translate a device path node to a Target ID and LUN.

Prototype

typedef
EFI_STATUS
(EIFIAPIC EFI_EXT_SCSI_PASS_THRU_GET_TARGET_LUN) (  
  IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL *This,  
  IN EFI_DEVICE_PATH_PROTOCOL *DevicePath  
  OUT UINT8 **Target,  
  OUT UINT64 *Lun  
);  

Parameters

This
A pointer to the EFI_EXT_SCSI_PASS_THRU_PROTOCOL instance. Type EFI_EXT_SCSI_PASS_THRU_PROTOCOL is defined in Extended SCSI Pass Thru Protocol.

DevicePath
A pointer to the device path node that describes a SCSI device on the SCSI channel.

Target
A pointer to the Target Array which represents the ID of a SCSI device on the SCSI channel.

Lun
A pointer to the LUN of a SCSI device on the SCSI channel.

Description

The EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetTargetLun() function determines the Target ID and LUN associated with the SCSI device described by DevicePath. If DevicePath is a device path node type that the SCSI Pass Thru driver supports, the SCSI Pass Thru driver will attempt to translate the contents DevicePath into a Target ID and LUN. If this translation is successful, then that Target ID and LUN are returned in Target and Lun, and EFI_SUCCESS is returned.

If DevicePath, Target, or Lun are NULL, then EFI_INVALID_PARAMETER is returned.

If DevicePath is not a device path node type that the SCSI Pass Thru driver supports, then EFI_UNSUPPORTED is returned.

If DevicePath is a device path node type that the SCSI Pass Thru driver supports, but there is not a valid translation from DevicePath to a Target ID and LUN, then EFI_NOT_FOUND is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>DevicePath was successfully translated to a Target ID and LUN, and they were returned in Target and Lun.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DevicePath is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Target is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Lun is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This driver does not support the device path node type in DevicePath.</td>
</tr>
</tbody>
</table>

continues on next page
A valid translation from DevicePath to a Target ID and LUN does not exist.

15.7.6 EFI_EXT_SCSI_PASS_THRU_PROTOCOL.ResetChannel()

Summary
Resets a SCSI channel. This operation resets all the SCSI devices connected to the SCSI channel.

Prototype

```c
typedef
 EFI_STATUS
 (EFIAPIC *EFI_EXT_SCSI_PASS_THRU_RESET_CHANNEL) (
   IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL *This
);
```

Parameters

This
A pointer to the EFI_EXT_SCSI_PASS_THRU_PROTOCOL instance. Type EFI_EXT_SCSI_PASS_THRU_PROTOCOL is defined in Extended SCSI Pass Thru Protocol.

Description

The EFI_EXT_SCSI_PASS_THRU_PROTOCOL.ResetChannel() function resets a SCSI channel. This operation resets all the SCSI devices connected to the SCSI channel. If this SCSI channel does not support a reset operation, then EFI_UNSUPPORTED is returned.

If a device error occurs while executing that channel reset operation, then EFI_DEVICE_ERROR is returned.

If a timeout occurs during the execution of the channel reset operation, then EFI_TIMEOUT is returned. If the channel reset operation is completed, then EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The SCSI channel was reset.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The SCSI channel does not support a channel reset operation.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to reset the SCSI channel.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>A timeout occurred while attempting to reset the SCSI channel.</td>
</tr>
</tbody>
</table>

15.7.7 EFI_EXT_SCSI_PASS_THRU_PROTOCOL.ResetTargetLun()

Summary

Resets a SCSI logical unit that is connected to a SCSI channel.

Prototype

```c
typedef
 EFI_STATUS
 (EFIAPIC *EFI_EXT_SCSI_PASS_THRU_RESET_TARGET_LUN) (
   IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL *This,
   IN UINT8 *Target,
   IN UINT64 Lun
);
```
Parameters

This

A pointer to the `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` instance. Type `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` is defined in *Extended SCSI Pass Thru Protocol*.

Target

The Target is an array of size `TARGET_MAX_BYTE` and it represents the target port ID of the SCSI device containing the SCSI logical unit to reset. Transport drivers may choose to utilize a subset of this array to suit the representation of their targets. For example, a Fibre Channel driver may use only 8 bytes in the array (WWN) to represent a FC target.

Lun

The LUN of the SCSI device to reset.

Description

The `EFI_EXT_SCSI_PASS_THRU_PROTOCOL.ResetTargetLun()` function resets the SCSI logical unit specified by `Target` and `Lun`. If this SCSI channel does not support a target reset operation, then `EFI_UNSUPPORTED` is returned.

If `Target` or `Lun` are not in a valid range for this SCSI channel, then `EFI_INVALID_PARAMETER` is returned.

If a device error occurs while executing that logical unit reset operation, then `EFI_DEVICE_ERROR` is returned.

If a timeout occurs during the execution of the logical unit reset operation, then `EFI_TIMEOUT` is returned.

If the logical unit reset operation is completed, then `EFI_SUCCESS` is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The SCSI device specified by <code>Target</code> and <code>Lun</code> was reset</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The SCSI channel does not support a target reset operation.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Target or <code>Lun</code> are invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A device error occurred while attempting to reset the SCSI device specified by <code>Target</code> and <code>Lun</code>.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>A timeout occurred while attempting to reset the SCSI device specified by <code>Target</code> and <code>Lun</code>.</td>
</tr>
</tbody>
</table>

15.7.8 `EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetNextTarget()`

Summary

Used to retrieve the list of legal Target IDs for SCSI devices on a SCSI channel. These can either be the list of SCSI devices that are actually present on the SCSI channel, or the list of legal Target IDs for the SCSI channel. Regardless, the caller of this function must probe the Target ID returned to see if a SCSI device is actually present at that location on the SCSI channel.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_EXT_SCSI_PASS_THRU_GET_NEXT_TARGET) (  
    IN EFI_EXT_SCSI_PASS_THRU_PROTOCOL *This,  
    IN OUT UINT8 **Target,
);```

Parameters
This
A pointer to the EFI_EXT_SCSI_PASS_THRU_PROTOCOL instance. Type EFI_EXT_SCSI_PASS_THRU_PROTOCOL is defined in Extended SCSI Pass Thru Protocol.

Target
On input, a pointer to the Target ID (an array of size TARGET_MAX_BYTES) of a SCSI device present on the SCSI channel. On output, a pointer to the Target ID (an array of TARGET_MAX_BYTES) of the next SCSI device present on a SCSI channel. An input value of 0xFF’s (all bytes in the array are 0xFF) in the Target array retrieves the Target ID of the first SCSI device present on a SCSI channel.

Description
The EFI_EXT_SCSI_PASS_THRU_PROTOCOL.GetNextTarget() function retrieves the Target ID of a SCSI device present on a SCSI channel. If on input a Target is specified by all 0xF in the Target array, then the Target ID of the first SCSI device is returned in Target and EFI_SUCCESS is returned.

If Target is a Target ID value that was returned on a previous call to GetNextTarget(), then the Target ID of the next SCSI device on the SCSI channel is returned in Target, and EFI_SUCCESS is returned.

If Target array is not all 0xFF’s and Target were not returned on a previous call to GetNextTarget(), then EFI_INVALID_PARAMETER is returned.

If Target is the Target ID of the last SCSI device on the SCSI channel, then EFI_NOT_FOUND is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Target ID of the next SCSI device on the SCSI channel was returned in Target.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>There are no more SCSI devices on this SCSI channel.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Target array is not all 0xFF’s, and Target were not returned on a previous call to GetNextTarget().</td>
</tr>
</tbody>
</table>
16.1 Overview

The iSCSI protocol defines a transport for SCSI data over TCP/IP. It also provides an interoperable solution that takes advantage of existing internet infrastructure, management facilities, and addresses distance limitations. The iSCSI protocol specification was developed by the Internet Engineering Task Force (IETF) and is SCSIArchitecture Model-2 (SAM-2) compliant. iSCSI encapsulates block-oriented SCSI commands into iSCSI Protocol Data Units (PDU) that traverse the network over TCP/IP. iSCSI defines a Session, the initiator and target nexus (I-T nexus), which could be a bundle of one or more TCP connections.

Similar to other existing mass storage protocols like Fibre Channel and parallel SCSI, boot over iSCSI is an important functionality. This document will attempt to capture the various cases for iSCSI boot and common up with generic EFI protocol changes to address them.

16.1.1 iSCSI UEFI Driver Layering

iSCSI UEFI Drivers may exist in two different forms:

- **iSCSI UEFI Driver on a NIC:**
  The driver will be layered on top of the networking layers. It will use the DHCP, IP, and TCP and packet level interface protocols of the UEFI networking stack. The driver will use an iSCSI software initiator.

- **iSCSI UEFI Driver on a Host Bus Adapter (HBA) that may use an offloading engine such as TOE (or another TCP offload card):**
  The driver will be layered on top of the TOE TCP interfaces. It will use the DHCP, IP, TCP protocols of the TOE. The driver will present itself as a SCSI device driver using interfaces such as `EFI_EXT_SCSI_PASS_THRU_PROTOCOL`.

To help in detecting iSCSI UEFI Drivers and their capabilities, the iSCSI UEFI driver handle must include an instance of the `EFI_ADAPTER_INFORMATION_PROTOCOL` with a `EFI_ADAPTER_INFO_NETWORK_BOOT` structure.

16.2 EFI iSCSI Initiator Name Protocol

This protocol sets and obtains the iSCSI Initiator Name. The iSCSI Initiator Name protocol builds a default iSCSI name. The iSCSI name configures using the programming interfaces defined below. Successive configuration of the iSCSI initiator name overwrites the previously existing name. Once overwritten, the previous name will not be retrievable. Setting an iSCSI name string that is zero length is illegal. The maximum size of the iSCSI Initiator Name is 224 bytes (including the NULL terminator).
16.2.1 EFI_ISCSI_INITIATOR_NAME_PROTOCOL

Summary

iSCSI Initiator Name Protocol for setting and obtaining the iSCSI Initiator Name.

GUID

```c
#define EFI_ISCSI_INITIATOR_NAME_PROTOCOL_GUID \
{0x59324945, 0xec44, 0x4c0d, \
 {0xb1, 0xcd, 0x9d, 0xb1, 0x39, 0xdf, 0x07, 0x0c}}
```

Protocol Interface Structure

```
typedef struct _EFI_ISCSI_INITIATOR_NAME_PROTOCOL {
    EFI_ISCSI_INITIATOR_NAME_GET Get;
    EFI_ISCSI_INITIATOR_NAME_SET Set;
} EFI_ISCSI_INITIATOR_NAME_PROTOCOL;
```

Parameters

Get

Used to retrieve the iSCSI Initiator Name.

Set

Used to set the iSCSI Initiator Name.

Description

The `EFI_ISCSI_INIT_NAME_PROTOCOL` provides the ability to get and set the iSCSI Initiator Name.

16.2.2 EFI_ISCSI_INITIATOR_NAME_PROTOCOL. Get()

Summary

Retrieves the current set value of iSCSI Initiator Name.

Prototype

```
typedef EFI_STATUS
(EFIAPI *EFI_ISCSI_INITIATOR_NAME_GET) ( 
    IN EFI_ISCSI_INITIATOR_NAME_PROTOCOL *This,
    IN OUT UINTN *BufferSize,
    OUT VOID *Buffer
    );
```

Parameters

This

Pointer to the `EFI_ISCSI_INITIATOR_NAME_PROTOCOL` instance.

BufferSize

Size of the buffer in bytes pointed to by Buffer / Actual size of the variable data buffer.

Buffer

Pointer to the buffer for data to be read. The data is a null-terminated UTF-8 encoded string. The maximum length is 223 characters, including the null-terminator.
Description
This function will retrieve the iSCSI Initiator Name from Non-volatile memory.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Data was successfully retrieved into the provided buffer and the BufferSize was sufficient to handle the iSCSI initiator name.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>BufferSize is too small for the result. BufferSize will be updated with the size required to complete the request. Buffer will not be affected.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>BufferSize is NULL. BufferSize and Buffer will not be affected.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Buffer is NULL. BufferSize and Buffer will not be affected.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The iSCSI initiator name could not be retrieved due to a hardware error.</td>
</tr>
</tbody>
</table>

16.2.3 EFI_ISCSI_INITIATOR_NAME_PROTOCOL.Set()

Summary
Sets the iSCSI Initiator Name.

Prototype

typedef EFI_STATUS
(EFIAPI *EFI_ISCSI_INITIATOR_NAME_SET) (  
  IN EFI_ISCSI_INITIATOR_NAME_PROTOCOL *This,
  IN OUT UINTN *BufferSize,
  IN VOID *Buffer
);

Parameters
This
Pointer to the EFI_ISCSI_INITIATOR_NAME_PROTOCOL instance

BufferSize
Size of the buffer in bytes pointed to by Buffer.

Buffer
Pointer to the buffer for data to be written. The data is a null-terminated UTF-8 encoded string. The maximum length is 223 characters, including the null-terminator.

Description
This function will set the iSCSI Initiator Name into Non-volatile memory.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Data was successfully stored by the protocol</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Platform policies do not allow for data to be written.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>BufferSize exceeds the maximum allowed limit. BufferSize will be updated with the maximum size required to complete the request.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>BufferSize is NULL. BufferSize and Buffer will not be affected</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Buffer is NULL. BufferSize and Buffer will not be affected</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The data could not be stored due to a hardware error.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Not enough storage is available to hold the data</td>
</tr>
</tbody>
</table>

continues on next page
| EFI_PROTOCOL_ERROR              | Input iSCSI initiator name does not adhere to RFC 3720 (and other related protocols) |
17.1 USB2 Host Controller Protocol

USB2 Host Controller Protocol and USB Host Controller Protocol Overview describe the USB2 Host Controller Protocol. This protocol provides an I/O abstraction for a USB2 Host Controller. The USB2 Host Controller is a hardware component that interfaces to a Universal Serial Bus (USB). It moves data between system memory and devices on the USB by processing data structures and generating transactions on the USB. This protocol is used by a USB Bus Driver to perform all data transaction over the Universal Serial Bus. It also provides services to manage the USB root hub that is integrated into the USB Host Controller. USB device drivers do not use this protocol directly. Instead, they use the I/O abstraction produced by the USB Bus Driver. This protocol should only be used by drivers that require direct access to the USB bus.

17.1.1 USB Host Controller Protocol Overview

The USB Host Controller Protocol is used by code, typically USB bus drivers, running in the EFI boot services environment, to perform data transactions over a USB bus. In addition, it provides an abstraction for the root hub of the USB bus.

The interfaces provided in the EFI_USB2_HC_PROTOCOL are used to manage data transactions on a USB bus. It also provides control methods for the USB root hub. The EFI_USB2_HC_PROTOCOL is designed to support both USB 1.1 and USB 2.0 - compliant host controllers.

The EFI_USB2_HC_PROTOCOL abstracts basic functionality that is designed to operate with the EHCI, UHCI and OHCI standards. By using this protocol, a single USB bus driver can be implemented without knowing if the underlying USB host controller conforms to the XHCI, EHCI, OHCI or the UHCI standards.

Each instance of the EFI_USB2_HC_PROTOCOL corresponds to a USB host controller in a platform. The protocol is attached to the device handle of a USB host controller that is created by a device driver for the USB host controller’s parent bus type. For example, a USB host controller that is implemented as a PCI device would require a PCI device driver to produce an instance of the EFI_USB2_HC_PROTOCOL.

17.1.2 EFI_USB2_HC_PROTOCOL

Summary

Provides basic USB host controller management, basic data transactions over USB bus, and USB root hub access.

GUID

#define EFI_USB2_HC_PROTOCOL_GUID \
{0x3e745226,0x9818,0x45b6,\} 
   {0xa2,0xac,0xd7,0xcd,0x0e,0x8b,0xa2,0xbc}
Protocol Interface Structure

typedef struct _EFI_USB2_HC_PROTOCOL {
    EFI_USB2_HC_PROTOCOL_GET_CAPABILITY GetCapability;
    EFI_USB2_HC_PROTOCOL_RESET Reset;
    EFI_USB2_HC_PROTOCOL_GET_STATE GetState;
    EFI_USB2_HC_PROTOCOL_SET_STATE SetState;
    EFI_USB2_HC_PROTOCOL_CONTROL_TRANSFER ControlTransfer;
    EFI_USB2_HC_PROTOCOL_BULK_TRANSFER BulkTransfer;
    EFI_USB2_HC_PROTOCOL_ASYNC_INTERRUPT_TRANSFER AsyncInterruptTransfer;
    EFI_USB2_HC_PROTOCOL_ASYNC_INTERRUPT_TRANSFER SyncInterruptTransfer;
    EFI_USB2_HC_PROTOCOL_ISOCHRONOUS_TRANSFER IsochronousTransfer;
    EFI_USB2_HC_PROTOCOL_ASYNC_ISOCHRONOUS_TRANSFER AsyncIsochronousTransfer;
    EFI_USB2_HC_PROTOCOL_GET_ROOTHUB_PORT_STATUS GetRootHubPortStatus;
    EFI_USB2_HC_PROTOCOL_SET_ROOTHUB_PORT_FEATURE SetRootHubPortFeature;
    EFI_USB2_HC_PROTOCOL_CLEAR_ROOTHUB_PORT_FEATURE ClearRootHubPortFeature
    UINT16 MajorRevision;
    UINT16 MinorRevision;
} EFI_USB2_HC_PROTOCOL;

Parameters

GetCapability
Retrieves the capabilities of the USB host controller. See the \textit{EFI_USB2_HC_PROTOCOL.GetCapability()} function description.

Reset
Software reset of USB. See the \textit{EFI_USB2_HC_PROTOCOL.Reset()} function description.

GetState
Retrieves the current state of the USB host controller. See the \textit{EFI_USB2_HC_PROTOCOL.GetState()} function description.

SetState
Sets the USB host controller to a specific state. See the \textit{EFI_USB2_HC_PROTOCOL.SetState()} function description.

ControlTransfer
Submits a control transfer to a target USB device. See the \textit{EFI_USB2_HC_PROTOCOL.ControlTransfer()} function description.

BulkTransfer
Submits a bulk transfer to a bulk endpoint of a USB device. See the \textit{EFI_USB2_HC_PROTOCOL.BulkTransfer()} function description.

AsyncInterruptTransfer
Submits an asynchronous interrupt transfer to an interrupt endpoint of a USB device. See the \textit{EFI_USB2_HC_PROTOCOL.AsyncInterruptTransfer()} function description.

SyncInterruptTransfer
Submits a synchronous interrupt transfer to an interrupt endpoint of a USB device. See the \textit{EFI_USB2_HC_PROTOCOL.SyncInterruptTransfer()} function description.

IsochronousTransfer
Submits isochronous transfer to an isochronous endpoint of a USB device. See the \textit{EFI_USB2_HC_PROTOCOL.IsochronousTransfer()} function description.

AsyncIsochronousTransfer
Submits nonblocking USB isochronous transfer. See the \textit{EFI_USB2_HC_PROTOCOL.AsyncIsochronousTransfer()} function description.
function description.

**GetRootHubPortStatus**
Retrieves the status of the specified root hub port. See the `EFI_USB2_HC_PROTOCOL.GetRootHubPortStatus()` function description.

**SetRootHubPortFeature**
Sets the feature for the specified root hub port. See the `EFI_USB2_HC_PROTOCOL.SetRootHubPortFeature()` function description.

**ClearRootHubPortFeature**
Clears the feature for the specified root hub port. See the `EFI_USB2_HC_PROTOCOL.ClearRootHubPortFeature()` function description.

**MajorRevision**
The major revision number of the USB host controller. The revision information indicates the release of the Universal Serial Bus Specification with which the host controller is compliant.

**MinorRevision**
The minor revision number of the USB host controller. The revision information indicates the release of the Universal Serial Bus Specification with which the host controller is compliant.

**Description**
The `EFI_USB2_HC_PROTOCOL` provides USB host controller management, basic data transactions over a USB bus, and USB root hub access. A device driver that wishes to manage a USB bus in a system retrieves the `EFI_USB2_HC_PROTOCOL` instance that is associated with the USB bus to be managed. A device handle for a USB host controller will minimally contain an `EFI Device Path Protocol` instance, and an `EFI_USB2_HC_PROTOCOL` instance.

### 17.1.3 `EFI_USB2_HC_PROTOCOL.GetCapability()`

**Summary**
Retrieves the Host Controller capabilities.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_GET_CAPABILITY) (
    IN EFI_USB2_HC_PROTOCOL *This,
    OUT UINT8 *MaxSpeed,
    OUT UINT8 *PortNumber,
    OUT UINT8 *Is64BitCapable
);
```

**Parameters**

**This**
A pointer to the `EFI_USB2_HC_PROTOCOL` instance. Type `EFI_USB2_HC_PROTOCOL` is defined in `USB2 Host Controller Protocol`.

**MaxSpeed**
Host controller data transfer speed; see Related Definitions below for a list of supported transfer speed values.

**PortNumber**
Number of the root hub ports.
**Is64BitCapable**

TRUE if controller supports 64-bit memory addressing, FALSE otherwise.

**Related Definitions**

```c
#define EFI_USB_SPEED_LOW 0x0000
#define EFI_USB_SPEED_FULL 0x0001
#define EFI_USB_SPEED_HIGH 0x0002
#define EFI_USB_SPEED_SUPER 0x0003
```

<table>
<thead>
<tr>
<th>EFI_USB_SPEED_LOW</th>
<th>Low speed USB device; data bandwidth is up to 1.5 Mb/s. Supported by USB 1.1 OHCI and UHCI host controllers.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_USB_SPEED_FULL</td>
<td>Full speed USB device; data bandwidth is up to 12 Mb/s. Supported by USB 1.1 OHCI and UHCI host controllers.</td>
</tr>
<tr>
<td>EFI_USB_SPEED_HIGH</td>
<td>High speed USB device; data bandwidth is up to 480 Mb/s. Supported by USB 2.0 EHCI host controllers.</td>
</tr>
<tr>
<td>EFI_USB_SPEED_SUPER</td>
<td>Super speed USB device; data bandwidth is up to 4.8Gbs. Supported by USB 3.0 XHCI host controllers.</td>
</tr>
</tbody>
</table>

**Description**

This function is used to retrieve the host controller capabilities. *MaxSpeed* indicates the maximum data transfer speed the controller is capable of; this information is needed for the subsequent transfers. *PortNumber* is the number of root hub ports, it is required by the USB bus driver to perform bus enumeration. *Is64BitCapable* indicates that controller is capable of 64-bit memory access so that the host controller software can use memory blocks above 4 GiB for the data transfers.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The host controller capabilities were retrieved successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>MaxSpeed or PortNumber or Is64BitCapable is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An error was encountered while attempting to retrieve the capabilities.</td>
</tr>
</tbody>
</table>

**17.1.4 EFI_USB2_HC_PROTOCOL.Reset()**

**Summary**

Provides software reset for the USB host controller.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_USB2_HC_PROTOCOL_RESET) (  
    IN EFI_USB2_HC_PROTOCOL     This,  
    IN UINT16                  Attributes
    );
```

**Parameters**

**This**

A pointer to the *EFI_USB2_HC_PROTOCOL* instance. Type EFI_USB2_HC_PROTOCOL is defined in *USB2 Host Controller Protocol*. 
Attributes
A bit mask of the reset operation to perform. See Related Definitions below for a list of the supported bit mask values.

Related Definitions

#define EFI_USB_HC_RESET_GLOBAL 0x0001
#define EFI_USB_HC_RESET_HOST_CONTROLLER 0x0002
#define EFI_USB_HC_RESET_GLOBAL_WITH_DEBUG 0x0004
#define EFI_USB_HC_RESET_HOST_WITH_DEBUG 0x0008

EFI_USB_HC_RESET_GLOBAL
If this bit is set, a global reset signal will be sent to the USB bus. This resets all of the USB bus logic, including the USB host controller hardware and all the devices attached on the USB bus.

EFI_USB_HC_RESET_HOST_CONTROLLER
If this bit is set, the USB host controller hardware will be reset. No reset signal will be sent to the USB bus.

EFI_USB_HC_RESET_GLOBAL_WITH_DEBUG
If this bit is set, then a global reset signal will be sent to the USB bus. This resets all of the USB bus logic, including the USB host controller and all of the devices attached on the USB bus. If this is an XHCI or EHCI controller and the debug port has been configured, then this will still reset the host controller.

EFI_USB_HC_RESET_HOST_WITH_DEBUG
If this bit is set, the USB host controller hardware will be reset. If this is an XHCI or EHCI controller and the debug port has been configured, then this will still reset the host controller.

Description
This function provides a software mechanism to reset a USB host controller. The type of reset is specified by the Attributes parameter. If the type of reset specified by Attributes is not valid, then EFI_INVALID_PARAMETER is returned. If the reset operation is completed, then EFI_SUCCESS is returned. If the type of reset specified by Attributes is not currently supported by the host controller hardware, EFI_UNSUPPORTED is returned. If a device error occurs during the reset operation, then EFI_DEVICE_ERROR is returned.

Note: For XHCI or EHCI controllers, the EFI_USB_HC_RESET_GLOBAL and EFI_USB_HC_RESET_HOST_CONTROLLER types of reset do not actually reset the bus if the debug port has been configured. In these cases, the function will return EFI_ACCESS_DENIED.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The reset operation succeeded.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Attributes is not valid.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The type of reset specified by Attributes is not currently supported by the host controller hardware.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Reset operation is rejected due to the debug port being configured and active; only EFI_USB_HC_RESET_GLOBAL_WITH_DEBUG or EFI_USB_HC_RESET_HOST_WITH_DEBUG reset Attributes can be used to perform reset operation for this host controller.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An error was encountered while attempting to perform the reset operation.</td>
</tr>
</tbody>
</table>
### 17.1.5 EFI_USB2_HC_PROTOCOL.GetState()

**Summary**
Retrieves current state of the USB host controller.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_GET_STATE) (
    IN EFI_USB2_HC_PROTOCOL *This,
    OUT EFI_USB_HC_STATE *State
);
```

**Parameters**

**This**
A pointer to the `EFI_USB2_HC_PROTOCOL` instance. Type `EFI_USB2_HC_PROTOCOL` is defined in [USB2 Host Controller Protocol](#).

**State**
A pointer to the `EFI_USB_HC_STATE` data structure that indicates current state of the USB host controller. Type `EFI_USB_HC_STATE` is defined in [Related Definitions](#).

**Related Definitions**

```c
typedef enum {
    EfiUsbHcStateHalt,
    EfiUsbHcStateOperational,
    EfiUsbHcStateSuspend,
    EfiUsbHcStateMaximum
} EFI_USB_HC_STATE;
```

**EfiUsbHcStateHalt**
The host controller is in halt state. No USB transactions can occur while in this state. The host controller can enter this state for three reasons:

- After host controller hardware reset.
- Explicitly set by software.
- Triggered by a fatal error such as consistency check failure.

**EfiUsbHcStateOperational**
The host controller is in an operational state. When in this state, the host controller can execute bus traffic. This state must be explicitly set to enable the USB bus traffic.

**EfiUsbHcStateSuspend**
The host controller is in the suspend state. No USB transactions can occur while in this state. The host controller enters this state for the following reasons:

- Explicitly set by software.
- Triggered when there is no bus traffic for 3 microseconds.

**Description**
This function is used to retrieve the USB host controller’s current state. The USB Host Controller Protocol publishes three states for USB host controller, as defined in Related Definitions below. If State is NULL, then EFI_INVALID_PARAMETER is returned. If a device error occurs while attempting to retrieve the USB host controllers current state, then EFI_DEVICE_ERROR is returned. Otherwise, the USB host controller’s current state is returned in State, and EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The state information of the host controller was returned in State.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>State is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An error was encountered while attempting to retrieve the host controller’s current state.</td>
</tr>
</tbody>
</table>

17.1.6 EFI_USB2_HC_PROTOCOL.SetState()

Summary

Sets the USB host controller to a specific state.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_USB2_HC_PROTOCOL_SET_STATE) (
  IN EFI_USB2_HC_PROTOCOL *This,
  IN EFI_USB_HC_STATE State
);
```

Parameters

This

A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in USB2 Host Controller Protocol.

State

Indicates the state of the host controller that will be set. See the definition and description of the type EFI_USB_HC_STATE in the EFI_USB2_HC_PROTOCOL.GetState() function description.

Description

This function is used to explicitly set a USB host controller’s state. There are three states defined for the USB host controller. These are the halt state, the operational state and the suspend state. The Figure below, Software Triggered State Transitions of a USB Host Controller, illustrates the possible state transitions:

![Software Triggered State Transitions of a USB Host Controller](image)

Fig. 17.1: Software Triggered State Transitions of a USB Host Controller
If the state specified by *State* is not valid, then *EFI_INVALID_PARAMETER* is returned. If a device error occurs while attempting to place the USB host controller into the state specified by *State*, then *EFI_DEVICE_ERROR* is returned. If the USB host controller is successfully placed in the state specified by *State*, then *EFI_SUCCESS* is returned.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>The USB host controller was successfully placed in the state specified by</td>
</tr>
<tr>
<td><strong>EFI_INVALID_PARAMETER</strong></td>
<td><em>State</em>.</td>
</tr>
<tr>
<td><strong>EFI_DEVICE_ERROR</strong></td>
<td>Failed to set the state specified by <em>State</em> due to device error.</td>
</tr>
</tbody>
</table>

#### 17.1.7 EFI_USB2_HC_PROTOCOL.ControlTransfer()

**Summary**

Submits control transfer to a target USB device.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_USB2_HC_PROTOCOL_CONTROL_TRANSFER) (  
    IN EFI_USB2_HC_PROTOCOL *This,  
    IN UINT8 DeviceAddress,  
    IN UINT8 DeviceSpeed,  
    IN UINTN MaximumPacketLength,  
    IN EFI_USB_DEVICE_REQUEST *Request,  
    IN EFI_USB_DATA_DIRECTION TransferDirection,  
    IN OUT VOID *Data OPTIONAL,  
    IN OUT UINTN *DataLength OPTIONAL,  
    IN UINTN TimeOut,  
    IN EFI_USB2_HC_TRANSACTION_TRANSLATOR *Translator,  
    OUT UINT32 *TransferResult  
);
```

**Related Definitions**

```c
typedef struct {  
    UINT8 TranslatorHubAddress,  
    UINT8 TranslatorPortNumber  
} EFI_USB2_HC_TRANSACTION_TRANSLATOR;
```

**Parameters**

**This**

A pointer to the *EFI_USB2_HC_PROTOCOL* instance. Type *EFI_USB2_HC_PROTOCOL* is defined in *USB2 Host Controller Protocol*.

**DeviceAddress**

Represents the address of the target device on the USB, which is assigned during USB enumeration.

**DeviceSpeed**

Indicates device speed. See Related Definitions in GetCapability() for a list of the supported values.

**MaximumPacketLength**

Indicates the maximum packet size that the default control transfer endpoint is capable of sending or receiving.
Request
A pointer to the USB device request that will be sent to the USB device. Refer to \texttt{UsbControlTransfer()} (\textit{USB I/O Protocol}) for the definition of this function type.

TransferDirection
Specifies the data direction for the transfer. There are three values available, \texttt{EfiUsbDataIn}, \texttt{EfiUsbDataOut} and \texttt{EfiUsbNoData}. Refer to \texttt{UsbControlTransfer()} (\textit{USB I/O Protocol}) for the definition of this function type.

Data
A pointer to the buffer of data that will be transmitted to USB device or received from USB device.

DataLength
On input, indicates the size, in bytes, of the data buffer specified by Data. On output, indicates the amount of data actually transferred.

Translator
A pointer to the transaction translator data. See “Description” for the detailed information of this data structure.

TimeOut
Indicates the maximum time, in milliseconds, which the transfer is allowed to complete.

TransferResult
A pointer to the detailed result information generated by this control transfer. Refer to \texttt{UsbControlTransfer()} (\textit{USB I/O Protocol}) for transfer result types (\textit{EFI_USB_ERR_x}).

Description
This function is used to submit a control transfer to a target USB device specified by DeviceAddress. Control transfers are intended to support configuration/command/status type communication flows between host and USB device.

There are three control transfer types according to the data phase. If the TransferDirection parameter is \texttt{EfiUsbNoData}, Data is \texttt{NULL}, and DataLength is 0, then no data phase is present in the control transfer. If the TransferDirection parameter is \texttt{EfiUsbDataOut}, then Data specifies the data to be transmitted to the device, and DataLength specifies the number of bytes to transfer to the device. In this case, there is an OUT DATA stage followed by a SETUP stage. If the TransferDirection parameter is \texttt{EfiUsbDataIn}, then Data specifies the data to be received from the device, and DataLength specifies the number of bytes to receive from the device. In this case there is an IN DATA stage followed by a SETUP stage.

Translator is necessary to perform split transactions on low-speed or full-speed devices connected to a high-speed hub. Such transaction require the device connection information: device address and the port number of the hub that device is connected to. This information is passed through the fields of \textit{EFI_USB2_HC_TRANSACTION_TRANSLATOR} structure. See Related Definitions for the structure field names. Translator is passed as \texttt{NULL} for the USB1.1 host controllers transfers or when the transfer is requested for high-speed device connected to USB2.0 controller.

If the control transfer has completed successfully, then \texttt{EFI_SUCCESS} is returned. If the transfer cannot be completed within the timeout specified by TimeOut, then \texttt{EFI_TIMEOUT} is returned. If an error other than timeout occurs during the USB transfer, then \texttt{EFI_DEVICE_ERROR} is returned and the detailed error code will be returned in the TransferResult parameter.

\texttt{EFI_INVALID_PARAMETER} is returned if one of the following conditions is satisfied:

- TransferDirection is invalid.
- TransferDirection, Data, and DataLength do not match one of the three control transfer types described above.
- Request pointer is NULL.
- MaximumPacketLength is not valid. If DeviceSpeed is \texttt{EFI_USB_SPEED_LOW}, then MaximumPacketLength must be 8. If DeviceSpeed is \texttt{EFI_USB_SPEED_FULL} or \texttt{EFI_USB_SPEED_HIGH}, then MaximumPacketLength must be 8, 16, 32, or 64. If DeviceSpeed is \texttt{EFI_USB_SPEED_SUPER}, then MaximumPacketLength must be 512.
• TransferResult pointer is NULL.
• Translator is NULL while the requested transfer requires split transaction. The conditions of the split transactions are described above in “Description” section.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The control transfer was completed successfully.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The control transfer could not be completed due to a lack of resources.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Some parameters are invalid. The possible invalid parameters are described in “Description” above.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The control transfer failed due to timeout.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The control transfer failed due to host controller or device error. Caller should check TransferResult for detailed error information.</td>
</tr>
</tbody>
</table>

17.1.8 EFI_USB2_HC_PROTOCOL.BulkTransfer()

Summary

Submits bulk transfer to a bulk endpoint of a USB device.

Prototype

typedef
EFI_STATUS
(EIFIAPIC *EFI_USB2_HC_PROTOCOL_BULK_TRANSFER) (        
    IN EFI_USB2_HC_PROTOCOL *This,                     
    IN UINT8 DeviceAddress,                            
    IN UINT8 EndPointAddress,                          
    IN UINT8 DeviceSpeed,                              
    IN UINTN MaximumPacketLength,                      
    IN UINT8 DataBuffersNumber,                        
    IN OUT VOID *Data[EFI_USB_MAX_BULK_BUFFER_NUM],    
    IN OUT UINTN *DataLength,                          
    IN OUT UINT8 *DataToggle,                          
    IN UINTN TimeOut,                                  
    IN EFI_USB2_HC_TRANSACTION_TRANSLATOR *Translator, 
    OUT UINT32 *TransferResult);                       

Parameters

This
A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in USB2 Host Controller Protocol.

DeviceAddress
Represents the address of the target device on the USB, which is assigned during USB enumeration.

EndPointAddress
The combination of an endpoint number and an endpoint direction of the target USB device. Each endpoint address supports data transfer in one direction except the control endpoint (whose default endpoint address is 0). It is the caller’s responsibility to make sure that the EndPointAddress represents a bulk endpoint.

DeviceSpeed
Indicates device speed. The supported values are EFI_USB_SPEED_FULL, EFI_USB_SPEED_HIGH or EFI_USB_SPEED_SUPER.
MaximumPacketLength
Indicates the maximum packet size the target endpoint is capable of sending or receiving.

DataBuffersNumber
Number of data buffers prepared for the transfer.

Data
Array of pointers to the buffers of data that will be transmitted to USB device or received from USB device.

DataLength
When input, indicates the size, in bytes, of the data buffers specified by Data. When output, indicates the actually transferred data size.

DataToggle
A pointer to the data toggle value. On input, it indicates the initial data toggle value the bulk transfer should adopt; on output, it is updated to indicate the data toggle value of the subsequent bulk transfer.

Translator
A pointer to the transaction translator data. See ControlTransfer() “Description” for the detailed information of this data structure.

TimeOut
Indicates the maximum time, in milliseconds, which the transfer is allowed to complete.

TransferResult
A pointer to the detailed result information of the bulk transfer. Refer to UsbControlTransfer() in USB I/O Protocol for transfer result types (EFI_USB_ERR_x).

Description
This function is used to submit bulk transfer to a target endpoint of a USB device. The target endpoint is specified by DeviceAddress and EndpointAddress. Bulk transfers are designed to support devices that need to communicate relatively large amounts of data at highly variable times where the transfer can use any available bandwidth. Bulk transfers can be used only by full-speed and high-speed devices.

High-speed bulk transfers can be performed using multiple data buffers. The number of buffers that are actually prepared for the transfer is specified by DataBuffersNumber. For full-speed bulk transfers this value is ignored.

Data represents a list of pointers to the data buffers. For full-speed bulk transfers only the data pointed by Data[0] shall be used. For high-speed transfers depending on DataLength there several data buffers can be used. The total number of buffers must not exceed EFI_USB_MAX_BULK_BUFFER_NUM. See Related Definitions for the EFI_USB_MAX_BULK_BUFFER_NUM value.

The data transfer direction is determined by the endpoint direction that is encoded in the EndpointAddress parameter. Refer to USB Specification, Revision 2.0 on the Endpoint Address encoding.

The DataToggle parameter is used to track target endpoint’s data sequence toggle bits. The USB provides a mechanism to guarantee data packet synchronization between data transmitter and receiver across multiple transactions. The data packet synchronization is achieved with the data sequence toggle bits and the DATA0/DATA1 PIDs. A bulk endpoint’s toggle sequence is initialized to DATA0 when the endpoint experiences a configuration event. It toggles between DATA0 and DATA1 in each successive data transfer. It is host’s responsibility to track the bulk endpoint’s data toggle sequence and set the correct value for each data packet. The input DataToggle value points to the data toggle value for the first data packet of this bulk transfer; the output DataToggle value points to the data toggle value for the last successfully transferred data packet of this bulk transfer. The caller should record the data toggle value for use in subsequent bulk transfers to the same endpoint.

If the bulk transfer is successful, then EFI_SUCCESS is returned. If USB transfer cannot be completed within the timeout specified by TimeOut, then EFI_TIMEOUT is returned. If an error other than timeout occurs during the USB transfer, then EFI_DEVICE_ERROR is returned and the detailed status code is returned in TransferResult.

EFI_INVALID_PARAMETER is returned if one of the following conditions is satisfied:
- `Data` is `NULL`.
- `DataLength` is 0.
- `DeviceSpeed` is not valid; the legal values are `EFI_USB_SPEED_FULL`, `EFI_USB_SPEED_HIGH`, or `EFI_USB_SPEED_SUPER`.
- `MaximumPacketLength` is not valid. The legal value of this parameter is 64 or less for full-speed, 512 or less for high-speed, and 1024 or less for super-speed transactions.
- `DataToggle` points to a value other than 0 and 1.
- `TransferResult` is `NULL`.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The bulk transfer was completed successfully.</td>
</tr>
<tr>
<td><code>EFI_OUT_OF_RESOURCES</code></td>
<td>The bulk transfer could not be submitted due to lack of resource.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>Some parameters are invalid. The possible invalid parameters are described in “Description” above.</td>
</tr>
<tr>
<td><code>EFI_TIMEOUT</code></td>
<td>The bulk transfer failed due to timeout.</td>
</tr>
<tr>
<td><code>EFI_DEVICE_ERROR</code></td>
<td>The bulk transfer failed due to host controller or device error. Caller should check <code>TransferResult</code> for detailed error information.</td>
</tr>
</tbody>
</table>

### 17.1.9 `EFI_USB2_HC_PROTOCOL.AsyncInterruptTransfer()`

#### Summary

Submits an asynchronous interrupt transfer to an interrupt endpoint of a USB device.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_USB2_HC_PROTOCOL_ASYNC_INTERRUPT_TRANSFER) (
    IN EFI_USB2_HC_PROTOCOL *This,
    IN UINT8 DeviceAddress,
    IN UINT8 EndPointAddress,
    IN UINT8 DeviceSpeed,
    IN UINT8 MaximumPacketLength,
    IN BOOLEAN IsNewTransfer,
    IN UINT8 DataToggle,
    IN UINT8 PollingInterval OPTIONAL,
    IN UINTN DataLength OPTIONAL,
    IN EFI_USB2_HC_TRANSACTION_TRANSLATOR *Translator OPTIONAL,
    IN EFI_ASYNC_USB_TRANSFER_CALLBACK CallBackFunction OPTIONAL,
    IN VOID *Context OPTIONAL
);
```

#### Parameters

- **This**
  
  A pointer to the `EFI_USB2_HC_PROTOCOL` instance. Type `EFI_USB2_HC_PROTOCOL` is defined in `USB2 Host Controller Protocol`.

- **DeviceAddress**
  
  Represents the address of the target device on the USB, which is assigned during USB enumeration.
**EndPointAddress**

The combination of an endpoint number and an endpoint direction of the target USB device. Each endpoint address supports data transfer in one direction except the control endpoint (whose default endpoint address is zero). It is the caller’s responsibility to make sure that the `EndPointAddress` represents an interrupt endpoint.

**DeviceSpeed**

Indicates device speed. See Related Definitions in `EFI_USB2_HC_PROTOCOL.ControlTransfer()` for a list of the supported values.

**MaximumPacketLength**

Indicates the maximum packet size the target endpoint is capable of sending or receiving.

**IsNewTransfer**

If TRUE, an asynchronous interrupt pipe is built between the host and the target interrupt endpoint. If FALSE, the specified asynchronous interrupt pipe is canceled. If TRUE, and an interrupt transfer exists for the target endpoint, then `EFI_INVALID_PARAMETER` is returned.

**DataToggle**

A pointer to the data toggle value. On input, it is valid when `IsNewTransfer` is TRUE, and it indicates the initial data toggle value the asynchronous interrupt transfer should adopt. On output, it is valid when `IsNewTransfer` is FALSE, and it is updated to indicate the data toggle value of the subsequent asynchronous interrupt transfer.

**PollingInterval**

Indicates the interval, in milliseconds, that the asynchronous interrupt transfer is polled. This parameter is required when `IsNewTransfer` is TRUE.

**DataLength**

Indicates the length of data to be received at the rate specified by `PollingInterval` from the target asynchronous interrupt endpoint. This parameter is only required when `IsNewTransfer` is TRUE.

**Translator**

A pointer to the transaction translator data.

**CallBackFunction**

The Callback function. This function is called at the rate specified by `PollingInterval`. This parameter is only required when `IsNewTransfer` is TRUE. Refer to `UsbAsyncInterruptTransfer()` in `USB I/O Protocol` for the definition of this function type.

**Context**

The context that is passed to the `CallBackFunction`. This is an optional parameter and may be NULL.

**Description**

This function is used to submit asynchronous interrupt transfer to a target endpoint of a USB device. The target endpoint is specified by `DeviceAddress` and `EndpointAddress`. In the USB Specification, Revision 2.0, interrupt transfer is one of the four USB transfer types. In the `EFI_USB2_HC_PROTOCOL`, interrupt transfer is divided further into synchronous interrupt transfer and asynchronous interrupt transfer.

An asynchronous interrupt transfer is typically used to query a device’s status at a fixed rate. For example, keyboard, mouse, and hub devices use this type of transfer to query their interrupt endpoints at a fixed rate. The asynchronous interrupt transfer is intended to support the interrupt transfer type of “submit once, execute periodically.” Unless an explicit request is made, the asynchronous transfer will never retire.

If `IsNewTransfer` is TRUE, then an interrupt transfer is started at a fixed rate. The rate is specified by `PollingInterval`, the size of the receive buffer is specified by `DataLength`, and the callback function is specified by `CallBackFunction`. `Context` specifies an optional context that is passed to the `CallBackFunction` each time it is called. The `CallBackFunction` is intended to provide a means for the host to periodically process interrupt transfer data.

If `IsNewTransfer` is TRUE, and an interrupt transfer exists for the target end point, then `EFI_INVALID_PARAMETER` is returned.
If `IsNewTransfer` is `FALSE`, then the interrupt transfer is canceled.

`EFI_INVALID_PARAMETER` is returned if one of the following conditions is satisfied:

- Data transfer direction indicated by `EndPointAddress` is other than `EfiUsbDataIn`.
- `IsNewTransfer` is `TRUE` and `DataLength` is 0.
- `IsNewTransfer` is `TRUE` and `DataToggle` points to a value other than 0 and 1.
- `IsNewTransfer` is `TRUE` and `PollingInterval` is not in the range 1..255.
- `IsNewTransfer` requested where an interrupt transfer exists for the target end point.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The asynchronous interrupt transfer request has been successfully submitted or canceled.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>Some parameters are invalid. The possible invalid parameters are described in “Description” above. When an interrupt transfer exists for the target end point and a new transfer is requested, <code>EFI_INVALID_PARAMETER</code> is returned.</td>
</tr>
<tr>
<td><code>EFI_OUT_OF_RESOURCES</code></td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
</tbody>
</table>

### 17.1.10 EFI_USB2_HC_PROTOCOL.SyncInterruptTransfer()

**Summary**

Submits synchronous interrupt transfer to an interrupt endpoint of a USB device.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_USB2_HC_PROTOCOL_SYNC_INTERRUPT_TRANSFER) (  
    IN EFI_USB2_HC_PROTOCOL  *This,  
    IN UINT8                 DeviceAddress,  
    IN UINT8                 EndPointAddress,  
    IN UINT8                 DeviceSpeed,  
    IN UINTN                 MaximumPacketLength,  
    IN OUT VOID              *Data,  
    IN OUT UINTN             *DataLength,  
    IN OUT UINT8             *DataToggle,  
    IN UINTN                 TimeOut,  
    IN EFI_USB2_HC_TRANSACTION_TRANSLATOR  *Translator  
    OUT UINT32               *TransferResult
);
```

**Parameters**

- **This**
  
  A pointer to the `EFI_USB2_HC_PROTOCOL` instance. Type `EFI_USB2_HC_PROTOCOL` is defined in `USB2 Host Controller Protocol`.

- **DeviceAddress**
  
  Represents the address of the target device on the USB, which is assigned during USB enumeration.
**EndPointAddress**

The combination of an endpoint number and an endpoint direction of the target USB device. Each endpoint address supports data transfer in one direction except the control endpoint (whose default endpoint address is zero). It is the caller’s responsibility to make sure that the *EndPointAddress* represents an interrupt endpoint.

**DeviceSpeed**

Indicates device speed. See Related Definitions in *EFI_USB2_HC_PROTOCOL.ControlTransfer()* for a list of the supported values.

**MaximumPacketLength**

Indicates the maximum packet size the target endpoint is capable of sending or receiving.

**Data**

A pointer to the buffer of data that will be transmitted to USB device or received from USB device.

**DataLength**

On input, the size, in bytes, of the data buffer specified by *Data*. On output, the number of bytes transferred.

**DataToggle**

A pointer to the data toggle value. On input, it indicates the initial data toggle value the synchronous interrupt transfer should adopt; on output, it is updated to indicate the data toggle value of the subsequent synchronous interrupt transfer.

**TimeOut**

Indicates the maximum time, in milliseconds, which the transfer is allowed to complete.

**Translator**

A pointer to the transaction translator data.

**TransferResult**

A pointer to the detailed result information from the synchronous interrupt transfer. Refer to *UsbControlTransfer()* in *USB I/O Protocol* for transfer result types (*EFI_USB_ERR_*).

**Description**

This function is used to submit a synchronous interrupt transfer to a target endpoint of a USB device. The target endpoint is specified by *DeviceAddress* and *EndpointAddress*. In the USB Specification, Revision 2.0, interrupt transfer is one of the four USB transfer types. In the *EFI_USB2_HC_PROTOCOL*, interrupt transfer is divided further into synchronous interrupt transfer and asynchronous interrupt transfer.

The synchronous interrupt transfer is designed to retrieve small amounts of data from a USB device through an interrupt endpoint. A synchronous interrupt transfer is only executed once for each request. This is the most significant difference from the asynchronous interrupt transfer.

If the synchronous interrupt transfer is successful, then *EFI_SUCCESS* is returned. If the USB transfer cannot be completed within the timeout specified by *Timeout*, then *EFI_TIMEOUT* is returned. If an error other than timeout occurs during the USB transfer, then *EFI_DEVICE_ERROR* is returned and the detailed status code is returned in *TransferResult*.

*EFI_INVALID_PARAMETER* is returned if one of the following conditions is satisfied:

- *Data* is NULL.
- *DataLength* is 0.
- *MaximumPacketLength* is not valid. The legal value of this parameter should be 3072 or less for high-speed device, 64 or less for a full-speed device; for a slow device, it is limited to 8 or less. For the full-speed device, it should be 8, 16, 32, or 64; for the slow device, it is limited to 8.
- *DataToggle* points to a value other than 0 and 1.
- *TransferResult* is NULL.

17.1. USB2 Host Controller Protocol
Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The synchronous interrupt transfer was completed successfully.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The synchronous interrupt transfer could not be submitted due to lack of resource.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Some parameters are invalid. The possible invalid parameters are described in “Description” above.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The synchronous interrupt transfer failed due to timeout.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The synchronous interrupt transfer failed due to host controller or device error. Caller should check TransferResult for detailed error information.</td>
</tr>
</tbody>
</table>

17.1.11 EFI_USB2_HC_PROTOCOL.IsochronousTransfer()

Summary
Submits isochronous transfer to an isochronous endpoint of a USB device.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_USB2_HC_PROTOCOL_ISOCHRONOUS_TRANSFER) (  
  IN EFI_USB2_HC_PROTOCOL *This,  
  IN UINT8 DeviceAddress,  
  IN UINT8 EndPointAddress,  
  IN UINT8 DeviceSpeed,  
  IN UINTN MaximumPacketLength,  
  IN UINT8 DataBuffersNumber,  
  IN OUT VOID *Data[EFI_USB_MAX_ISO_BUFFER_NUM],  
  IN UINTN DataLength,  
  IN EFI_USB2_HC_TRANSACTION_TRANSLATOR *Translator,  
  OUT UINT32 *TransferResult  
);```

Related Definitions

```c
#define EFI_USB_MAX_ISO_BUFFER_NUM 7
#define EFI_USB_MAX_ISO_BUFFER_NUM1 2
```

Parameters

This
A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in USB2 Host Controller Protocol.

DeviceAddress
Represents the address of the target device on the USB, which is assigned during USB enumeration.

EndPointAddress
The combination of an endpoint number and an endpoint direction of the target USB device. Each endpoint address supports data transfer in one direction except the control endpoint (whose default endpoint address is 0). It is the caller’s responsibility to make sure that the EndPointAddress represents an isochronous endpoint.

DeviceSpeed
Indicates device speed. The supported values are EFI_USB_SPEED_FULL, EFI_USB_SPEED_HIGH, or EFI_USB_SPEED_SUPER.
MaximumPacketLength
Indicates the maximum packet size the target endpoint is capable of sending or receiving. For isochronous endpoints, this value is used to reserve the bus time in the schedule, required for the per-frame data payloads. The pipe may, on an ongoing basis, actually use less bandwidth than that reserved.

DataBuffersNumber
Number of data buffers prepared for the transfer.

Data
Array of pointers to the buffers of data that will be transmitted to USB device or received from USB device.

DataLength
Specifies the length, in bytes, of the data to be sent to or received from the USB device.

Translator
A pointer to the transaction translator data. See ControlTransfer() “Description” for the detailed information of this data structure.

TransferResult
A pointer to the detail result information of the isochronous transfer. Refer to UsbControlTransfer() in USB I/O Protocol for transfer result types (EFI_USB_ERR_x).

Description
This function is used to submit isochronous transfer to a target endpoint of a USB device. The target endpoint is specified by DeviceAddress and EndpointAddress. Isochronous transfers are used when working with isochronous data. It provides periodic, continuous communication between the host and a device. Isochronous transfers can be used only by full-speed, high-speed, and super-speed devices.

High-speed isochronous transfers can be performed using multiple data buffers. The number of buffers that are actually prepared for the transfer is specified by DataBuffersNumber. For full-speed isochronous transfers this value is ignored.

Data represents a list of pointers to the data buffers. For full-speed isochronous transfers only the data pointed by Data[0] shall be used. For high-speed isochronous transfers and for the split transactions depending on DataLength there several data buffers can be used. For the high-speed isochronous transfers the total number of buffers must not exceed EFI_USB_MAX_ISO_BUFFER_NUM. For split transactions performed on full-speed device by high-speed host controller the total number of buffers is limited to EFI_USB_MAX_ISO_BUFFER_NUM1 See Related Definitions for the EFI_USB_MAX_ISO_BUFFER_NUM and EFI_USB_MAX_ISO_BUFFER_NUM1 values.

If the isochronous transfer is successful, then EFI_SUCCESS is returned. The isochronous transfer is designed to be completed within one USB frame time, if it cannot be completed, EFI_TIMEOUT is returned. If an error other than timeout occurs during the USB transfer, then EFI_DEVICE_ERROR is returned and the detailed status code will be returned in TransferResult.

EFI_INVALID_PARAMETER is returned if one of the following conditions is satisfied:

- Data is NULL.
- DataLength is 0.
- DeviceSpeed is not one of the supported values listed above.
- MaximumPacketLength is invalid. MaximumPacketLength must be 1023 or less for full-speed devices, and 1024 or less for high-speed and super-speed devices.
- TransferResult is NULL.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The isochronous transfer was completed successfully.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The isochronous transfer could not be submitted due to lack of resource.</td>
</tr>
</tbody>
</table>

Continues on next page
Table 17.8 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Some parameters are invalid. The possible invalid parameters are described in &quot;Description&quot; above.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The isochronous transfer cannot be completed within the one USB frame time.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The isochronous transfer failed due to host controller or device error. Caller should check TransferResult for detailed error information.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation doesn’t support an Isochronous transfer function.</td>
</tr>
</tbody>
</table>

17.1.12 EFI_USB2_HC_PROTOCOL.AsyncIsochronousTransfer()

Summary
Submits nonblocking isochronous transfer to an isochronous endpoint of a USB device.

Prototype

typedef
EFI_STATUS
(EIFIAPi * EFI_USB2_HC_PROTOCOL_ASYNC_ISOCHRONOUS_TRANSFER) (  
    IN EFI_USB2_HC_PROTOCOL *This,  
    IN UINT8 DeviceAddress,  
    IN UINT8 EndPointAddress,  
    IN UINT8 DeviceSpeed,  
    IN UINTN MaximumPacketLength,  
    IN UINT8 DataBuffersNumber,  
    IN OUT VOID *Data[EFI_USB_MAX_ISO_BUFFER_NUM],  
    IN UINTN DataLength,  
    IN EFI_USB2_HC_TRANSACTION_TRANSLATOR *Translator,  
    IN EFI_ASYNC_USB_TRANSFER_CALLBACK IsochronousCallBack,  
    IN VOID *Context OPTIONAL  
);

Parameters

This
A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in USB2 Host Controller Protocol.

DeviceAddress
Represents the address of the target device on the USB, which is assigned during USB enumeration.

EndPointAddress
The combination of an endpoint number and an endpoint direction of the target USB device. Each endpoint address supports data transfer in one direction except the control endpoint (whose default endpoint address is zero). It is the caller’s responsibility to make sure that the EndPointAddress represents an isochronous endpoint.

DeviceSpeed
Indicates device speed. The supported values are EFI_USB_SPEED_FULL, EFI_USB_SPEED_HIGH, or EFI_USB_SPEED_SUPER.

MaximumPacketLength
Indicates the maximum packet size the target endpoint is capable of sending or receiving. For isochronous endpoints, this value is used to reserve the bus time in the schedule, required for the per-frame data payloads. The pipe may, on an ongoing basis, actually use less bandwidth than that reserved.
DataBuffersNumber

Number of data buffers prepared for the transfer.

Data

Array of pointers to the buffers of data that will be transmitted to USB device or received from USB device.

DataLength

Specifies the length, in bytes, of the data to be sent to or received from the USB device.

Translator

A pointer to the transaction translator data. See ControlTransfer() “Description” for the detailed information of this data structure.

IsochronousCallback

The Callback function. This function is called if the requested isochronous transfer is completed. Refer to UsbAsyncInterruptTransfer() in USB I/O Protocol for the definition of this function type.

Context

Data passed to the IsochronousCallback function. This is an optional parameter and may be NULL.

Description

This is an asynchronous type of USB isochronous transfer. If the caller submits a USB isochronous transfer request through this function, this function will return immediately. When the isochronous transfer completes, the IsochronousCallback function will be triggered, the caller can know the transfer results. If the transfer is successful, the caller can get the data received or sent in this callback function.

The target endpoint is specified by DeviceAddress and EndpointAddress. Isochronous transfers are used when working with isochronous date. It provides periodic, continuous communication between the host and a device. Isochronous transfers can be used only by full-speed, high-speed, and super-speed devices.

High-speed isochronous transfers can be performed using multiple data buffers. The number of buffers that are actually prepared for the transfer is specified by DataBuffersNumber. For full-speed isochronous transfers this value is ignored.

Data represents a list of pointers to the data buffers. For full-speed isochronous transfers only the data pointed by Data[0] shall be used. For high-speed isochronous transfers and for the split transactions depending on DataLength there several data buffers can be used. For the high-speed isochronous transfers the total number of buffers must not exceed EFI_USB_MAX_ISO_BUFFER_NUM. For split transactions performed on full-speed device by high-speed host controller the total number of buffers is limited to EFI_USB_MAX_ISO_BUFFER_NUM1. See Related Definitions in IsochronousTransfer() section for the EFI_USB_MAX_ISO_BUFFER_NUM and EFI_USB_MAX_ISO_BUFFER_NUM1 values.

EFI_INVALID_PARAMETER is returned if one of the following conditions is satisfied:

- Data is NULL.
- DataLength is 0.
- DeviceSpeed is not one of the supported values listed above.
- MaximumPacketLength is invalid. MaximumPacketLength must be 1023 or less for full-speed devices and 1024 or less for high-speed and super-speed devices.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The asynchronous isochronous transfer was completed successfully.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The asynchronous isochronous transfer could not be submitted due to lack of resource.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Some parameters are invalid. The possible invalid parameters are described in “Description” above.</td>
</tr>
</tbody>
</table>

continues on next page
Table 17.9 – continued from previous page

| EFI_UNSUPPORTED                      | The implementation doesn’t support Isochronous transfer function |

17.1.13 **EFI_USB2_HC_PROTOCOL.GetRootHubPortStatus()**

Summary

Retrieves the current status of a USB root hub port.

Prototype

```c
typedef
EFI_STATUS
( EFIAPIC * EFI_USB2_HC_PROTOCOL_GET_ROOTHUB_PORT_STATUS ) (  
  IN EFI_USB2_HC_PROTOCOL *This,  
  IN UINT8 PortNumber,  
  OUT EFI_USB_PORT_STATUS *PortStatus  
);
```

Parameters

This

A pointer to the `EFI_USB2_HC_PROTOCOL` instance. Type `EFI_USB2_HC_PROTOCOL` is defined in `USB2 Host Controller Protocol`.

PortNumber

 Specifies the root hub port from which the status is to be retrieved. This value is zero based. For example, if a root hub has two ports, then the first port is numbered 0, and the second port is numbered 1.

PortStatus

A pointer to the current port status bits and port status change bits. The type `EFI_USB_PORT_STATUS` is defined in Related Definitions below.

Related Definitions

```c
typedef struct {
  UINT16 PortStatus;
  UINT16 PortChangeStatus;
} EFI_USB_PORT_STATUS;
```

//**************************************************
// EFI_USB_PORT_STATUS.PortStatus bit definition
//**************************************************

```c
#define USB_PORT_STAT_CONNECTION 0x0001
#define USB_PORT_STAT_ENABLE 0x0002
#define USB_PORT_STAT_SUSPEND 0x0004
#define USB_PORT_STAT_OVERCURRENT 0x0008
#define USB_PORT_STAT_RESET 0x0010
#define USB_PORT_STAT_POWER 0x0100
#define USB_PORT_STAT_LOW_SPEED 0x0200
#define USB_PORT_STAT_HIGH_SPEED 0x0400
#define USB_PORT_STAT_SUPER_SPEED 0x0800
#define USB_PORT_STAT_OWNER 0x2000
```

(continues on next page)
PortStatus
Contains current port status bitmap. The root hub port status bitmap is unified with the USB hub port status bitmap. See Table below, USB Hub Port Status Bitmap, for a reference, which is borrowed from Chapter 11, Hub Specification, of USB Specification, Revision 1.1.

PortChangeStatus
Contains current port status change bitmap. The root hub port change status bitmap is unified with the USB hub port status bitmap. See Table below, Hub Port Change Status Bitmap for a reference, which is borrowed from Chapter 11, Hub Specification, of USB Specification, Revision 1.1.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Current Connect Status: (USB_PORT_STAT_CONNECTION) This field reflects whether or not a device is currently connected to this port. 0 = No device is present 1 = A device is present on this port</td>
</tr>
<tr>
<td>1</td>
<td>Port Enable / Disabled: (USB_PORT_STAT_ENABLE) Ports can be enabled by software only. Ports can be disabled by either a fault condition (disconnect event or other fault condition) or by software. 0 = Port is disabled 1 = Port is enabled</td>
</tr>
<tr>
<td>2</td>
<td>Suspend: (USB_PORT_STAT_SUSPEND) This field indicates whether or not the device on this port is suspended. 0 = Not suspended 1 = Suspended</td>
</tr>
<tr>
<td>3</td>
<td>Over-current Indicator: (USB_PORT_STAT_OVERCURRENT) This field is used to indicate that the current drain on the port exceeds the specified maximum. 0 = All no over-current condition exists on this port 1 = An over-current condition exists on this port</td>
</tr>
</tbody>
</table>
Table 17.10 – continued from previous page

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>4</td>
<td>Reset: (USB_PORT_STAT_RESET) Indicates whether port is in reset state.</td>
</tr>
<tr>
<td></td>
<td>0 = Port is not in reset state</td>
</tr>
<tr>
<td></td>
<td>1 = Port is in reset state</td>
</tr>
<tr>
<td>5-7</td>
<td>Reserved These bits return 0 when read.</td>
</tr>
<tr>
<td>8</td>
<td>Port Power: (USB_PORT_STAT_POWER) This field reflects a port’s logical,</td>
</tr>
<tr>
<td></td>
<td>power control state.</td>
</tr>
<tr>
<td></td>
<td>0 = This port is in the Powered-off state</td>
</tr>
<tr>
<td></td>
<td>1 = This port is not in the Powered-off state</td>
</tr>
<tr>
<td>9</td>
<td>Low Speed Device Attached: (USB_PORT_STAT_LOW_SPEED) This is relevant only</td>
</tr>
<tr>
<td></td>
<td>if a device is attached.</td>
</tr>
<tr>
<td></td>
<td>0 = Full-speed device attached to this port</td>
</tr>
<tr>
<td></td>
<td>1 = Low-speed device attached to this port</td>
</tr>
<tr>
<td>10</td>
<td>High Speed Device Attached: (USB_PORT_STAT_HIGH_SPEED) This field indicates</td>
</tr>
<tr>
<td></td>
<td>whether the connected device is high-speed device</td>
</tr>
<tr>
<td></td>
<td>0 = High-speed device is not attached to this port</td>
</tr>
<tr>
<td></td>
<td>1 = High-speed device attached to this port</td>
</tr>
<tr>
<td></td>
<td>NOTE: this bit has precedence over Bit 9; if set, bit 9 must be ignored.</td>
</tr>
<tr>
<td>11</td>
<td>Super Speed Device Attached: (USB_PORT_STAT_SUPER_SPEED) This field indicates</td>
</tr>
<tr>
<td></td>
<td>whether the connected device is a super-speed device.</td>
</tr>
<tr>
<td></td>
<td>0 = Super-speed device is not attached to this port.</td>
</tr>
<tr>
<td></td>
<td>1 = Super-speed device is attached to this port.</td>
</tr>
<tr>
<td></td>
<td>NOTE: This bit has precedence over Bit 9 and Bit 10; if set bits 9,10 must</td>
</tr>
<tr>
<td></td>
<td>be ignored.</td>
</tr>
<tr>
<td>12</td>
<td>Reserved. Bit returns 0 when read.</td>
</tr>
<tr>
<td>13</td>
<td>The host controller owns the specified port.</td>
</tr>
<tr>
<td></td>
<td>0 = Controller does not own the port.</td>
</tr>
<tr>
<td></td>
<td>1 = Controller owns the port</td>
</tr>
<tr>
<td>14-15</td>
<td>Reserved These bits return 0 when read.</td>
</tr>
</tbody>
</table>

Table 17.11: Hub Port Change Status Bitmap

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>continues on next page</td>
</tr>
</tbody>
</table>
Table 17.11 – continued from previous page

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
</table>
| 0   | Connect Status Change: (USB_PORT_STAT_C_CONNECTION) Indicates a change has occurred in the port’s Current Connect Status.  
0 = No change has occurred to Current Connect status  
1 = Current Connect status has changed |
| 1   | Port Enable/Disable Change: (USB_PORT_STAT_C_ENABLE)  
0 = No change  
1 = Port enabled/disabled status has changed |
| 2   | Suspend Change: (USB_PORT_STAT_C_SUSPEND) This field indicates a change in the host-visible suspend state of the attached device.  
0 = No change  
1 = Resume complete |
| 3   | Over-Current Indicator Change: (USB_PORT_STAT_C_OVERCURRENT)  
0 = No change has occurred to Over-Current Indicator  
1 = Over-Current Indicator has changed |
| 4   | Reset Change: (USB_PORT_STAT_C_RESET) This field is set when reset processing on this port is complete.  
0 = No change  
1 = Reset complete |
| 5-15| Reserved. These bits return 0 when read. |

Description

This function is used to retrieve the status of the root hub port specified by PortNumber.

EFI_USB_PORT_STATUS found in Related Definitions EFI_USB2_HC_PROTOCOL.GetRootHubPortStatus() describes the port status of a specified USB port. This data structure is designed to be common to both a USB root hub port and a USB hub port.

The number of root hub ports attached to the USB host controller can be determined with the function EFI_USB2_HC_PROTOCOL.GetRootHubPortStatus(). If PortNumber is greater than or equal to the number of ports returned by GetRootHubPortNumber(), then EFI_INVALID_PARAMETER is returned. Otherwise, the status of the USB root hub port is returned in PortStatus, and EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The status of the USB root hub port specified by PortNumber was returned in PortStatus.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PortNumber is invalid.</td>
</tr>
</tbody>
</table>
17.1.14 EFI_USB2_HC_PROTOCOL.SetRootHubPortFeature()

Summary
Sets a feature for the specified root hub port.

Prototype

```c
typedef EFI_STATUS
 (EFIAPIC *EFI_USB2_HC_PROTOCOL_SET_ROOTHUB_PORT_FEATURE) (
  IN EFI_USB2_HC_PROTOCOL *This,
  IN UINT8 PortNumber,
  IN EFI_USB_PORT_FEATURE PortFeature
);
```

Parameters

This
A pointer to the EFI_USB2_HC_PROTOCOL instance. Type EFI_USB2_HC_PROTOCOL is defined in USB2 Host Controller Protocol.

PortNumber
Specifies the root hub port whose feature is requested to be set. This value is zero based. For example, if a root hub has two ports, then the first port is number 0, and the second port is numbered 1.

PortFeature
Indicates the feature selector associated with the feature set request. The port feature indicator is defined in Related Definitions and The Table below, USB Port Features.

Related Definitions

```c
typedef enum {
  EfiUsbPortEnable = 1,
  EfiUsbPortSuspend = 2,
  EfiUsbPortReset = 4,
  EfiUsbPortPower = 8,
  EfiUsbPortOwner = 13,
  EfiUsbPortConnectChange = 16,
  EfiUsbPortEnableChange = 17,
  EfiUsbPortSuspendChange = 18,
  EfiUsbPortOverCurrentChange = 19,
  EfiUsbPortResetChange = 20
} EFI_USB_PORT_FEATURE;
```

The feature values specified in the enumeration variable have special meaning. Each value indicates its bit index in the port status and status change bitmaps, if combines these two bitmaps into a 32-bit bitmap. The meaning of each port feature is listed in Table below, USB Port Features.

<table>
<thead>
<tr>
<th>Port Feature</th>
<th>For SetRootHubPortFeature</th>
<th>For ClearRootHubPortFeature</th>
</tr>
</thead>
<tbody>
<tr>
<td>EfiUsbPortEnable</td>
<td>Enable the given port of the root hub.</td>
<td>Disable the given port of the root hub.</td>
</tr>
<tr>
<td>EfiUsbPortSuspend</td>
<td>Put the given port into suspend state.</td>
<td>Restore the given port from the previous suspend state.</td>
</tr>
</tbody>
</table>

continues on next page
Table 17.12 – continued from previous page

<table>
<thead>
<tr>
<th>Function</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EfiUsbPortReset</td>
<td>Reset the given port of the root hub. Clear the RESET signal for the given</td>
</tr>
<tr>
<td></td>
<td>port of the root hub.</td>
</tr>
<tr>
<td>EfiUsbPortPower</td>
<td>Power the given port. Shutdown the power from the given port.</td>
</tr>
<tr>
<td>EfiUsbPortOwner</td>
<td>N/A. Releases the port ownership of this port to companion host controller.</td>
</tr>
<tr>
<td>EfiUsbPortConnectChange</td>
<td>Clear USB_PORT_STAT_C_CONNECTION bit of the given port of the root hub.</td>
</tr>
<tr>
<td>EfiUsbPortEnableChange</td>
<td>Clear USB_PORT_STAT_C_ENABLE bit of the given port of the root hub.</td>
</tr>
<tr>
<td>EfiUsbPortSuspendChange</td>
<td>Clear USB_PORT_STAT_C_SUSPEND bit of the given port of the root hub.</td>
</tr>
<tr>
<td>EfiUsb PortOverCurrentChange</td>
<td>Clear USB_PORT_STAT_C_OVERCURRENT bit of the given port of the root hub.</td>
</tr>
<tr>
<td>EfiUsbPortResetChange</td>
<td>Clear USB_PORT_STAT_C_RESET bit of the given port of the root hub.</td>
</tr>
</tbody>
</table>

**Description**

This function sets the feature specified by *PortFeature* for the USB root hub port specified by *PortNumber*. Setting a feature enables that feature or starts a process associated with that feature. For the meanings about the defined features, refer to Table USB Hub Port Status Bitmap and Table Hub Port Change Status Bitmap.

The number of root hub ports attached to the USB host controller can be determined with the function EFI_USB2_HC_PROTOCOL.GetRootHubPortStatus(). If *PortNumber* is greater than or equal to the number of ports returned by GetRootHubPortNumber(), then EFI_INVALID_PARAMETER is returned. If *PortFeature* is not EfiUsbPortEnable, EfiUsbPortSuspend, EfiUsbPortReset nor EfiUsbPortPower, then EFI_INVALID_PARAMETER is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
</table>
| EFI_SUCCESS | The feature specified by *PortFeature* was set for the USB root hub port spe-
|             | cified by *PortNumber*.                                                     |
| EFI_INVALID_PARAMETER | PortNumber is invalid or *PortFeature* is invalid for this function.       |

**17.1.15 EFI_USB2_HC_PROTOCOL.ClearRootHubPortFeature()**

**Summary**

Clears a feature for the specified root hub port.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI *EFI_USB2_HC_PROTOCOL_CLEAR_ROOTHUB_PORT_FEATURE) (            
    IN EFI_USB2_HC_PROTOCOL *This,                                     
    IN UINT8 PortNumber,                                              
);                                                                   
```
Parameters

This

A pointer to the `EFI_USB2_HC_PROTOCOL` instance, which is defined in *USB2 Host Controller Protocol*.

PortNumber

Specifies the root hub port whose feature is requested to be cleared. This value is zero-based. For example, if a root hub has two ports, then the first port is number 0, and the second port is numbered 1.

PortFeature

Indicates the feature selector associated with the feature clear request. The port feature indicator `EFI_USB_PORT_FEATURE` is defined in Section 17.1.14 in the “Related Definitions” section, and in Table 17.12.

Description

This function clears the feature specified by PortFeature for the USB root hub port specified by PortNumber. Clearing a feature disables that feature or stops a process associated with that feature. For the meanings about the defined features, refer to Table *USB Hub Port Status Bitmap* and Table *Hub Port Change Status Bitmap*.

The number of root hub ports attached to the USB host controller can be determined with the function `EFI_USB2_HC_PROTOCOL.GetRootHubPortStatus()`. If PortNumber is greater than or equal to the number of ports returned by GetRootHubPortNumber(), then `EFI_INVALID_PARAMETER` is returned. If PortFeature is not `EfiUsbPortEnable`, `EfiUsbPortSuspend`, `EfiUsbPortPower`, `EfiUsbPortConnectChange`, `EfiUsbPortResetChange`, `EfiUsbPortEnableChange`, `EfiUsbPortSuspendChange`, or `EfiUsbPortOverCurrentChange`, then `EFI_INVALID_PARAMETER` is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The feature specified by PortFeature was cleared for the USB root hub port specified by PortNumber.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>PortNumber is invalid or PortFeature is invalid.</td>
</tr>
</tbody>
</table>

17.2 USB Driver Model

17.2.1 Scope

Section *USB Driver Model* describes the USB Driver Model. This includes the behavior of USB Bus Drivers, the behavior of a USB Device Drivers, and a detailed description of the EFI USB I/O Protocol. This document provides enough material to implement a USB Bus Driver, and the tools required to design and implement USB Device Drivers. It does not provide any information on specific USB devices.

The material contained in this section is designed to extend this specification and the UEFI Driver Model in a way that supports USB device drivers and USB bus drivers. These extensions are provided in the form of USB specific protocols. This document provides the information required to implement a USB Bus Driver in system firmware. The document also contains the information required by driver writers to design and implement USB Device Drivers that a platform may need to boot a UEFI-compliant OS.

The USB Driver Model described here is intended to be a foundation on which a USB Bus Driver and a wide variety of USB Device Drivers can be created. USB Driver Model Overview

The USB Driver Stack includes the USB Bus Driver, USB Host Controller Driver, and individual USB device drivers.
In the USB Bus Driver Design, the USB Bus Controller is managed by two drivers. One is USB Host Controller Driver, which consumes its parent bus EFI_XYZ_IO_PROTOCOL, and produces EFI_USB2_HC_PROTOCOL, and attaches it to the Bus Controller Handle. The other one is USB Bus Driver, which consumes EFI_USB2_HC_PROTOCOL, and performs bus enumeration. Figure USB Bus Controller Handle shows protocols that are attached to the USB Bus Controller Handle. Detailed descriptions are presented in the following sections.

17.2.2 USB Bus Driver

USB Bus Driver performs periodic Enumeration on the USB Bus. In USB bus enumeration, when a new USB controller is found, the bus driver does some standard configuration for that new controller, and creates a device handle for it. The EFI_USB_IO_PROTOCOL and EFI_DEVICE_PATH_PROTOCOL are attached to the device handle so that the USB controller can be accessed. The USB Bus Driver is also responsible for connecting USB device drivers to USB controllers. When a USB device is detached from a USB bus, the USB bus driver will stop that USB controller, and uninstall the EFI_USB_IO_PROTOCOL and the EFI_DEVICE_PATH_PROTOCOL from that handle. A detailed description is given in USB Hot-Plug Event.

17.2.2.1 USB Bus Driver Entry Point

Like all other device drivers, the entry point for a USB Bus Driver attaches the EFI Driver Binding Protocol to image handle of the USB Bus Driver.

17.2.2.2 Driver Binding Protocol for USB Bus Drivers

The Driver Binding Protocol contains three services. These are:

- EFI_DRIVER_BINDING_PROTOCOL.SUPPORTED()
- EFI_DRIVER_BINDING_PROTOCOL.START()
- EFI_DRIVER_BINDING_PROTOCOL.STOP()

Supported() tests to see if the USB Bus Driver can manage a device handle. A USB Bus Driver can only manage a device handle that contains EFI_USB2_HC_PROTOCOL.

The general idea is that the USB Bus Driver is a generic driver. Since there are several types of USB Host Controllers, an EFI_USB2_HC_PROTOCOL is used to abstract the host controller interface. Actually, a USB Bus Driver only requires an EFI_USB2_HC_PROTOCOL.

The Start() function tells the USB Bus Driver to start managing the USB Bus. In this function, the USB Bus Driver creates a device handle for the root hub, and creates a timer to monitor root hub connection changes.
The `Stop()` function tells the USB Bus Driver to stop managing a USB Host Bus Controller. The `Stop()` function simply deconfigures the devices attached to the root hub. The deconfiguration is a recursive process. If the device to be deconfigured is a USB hub, then all USB devices attached to its downstream ports will be deconfigured first, then itself. If all of the child devices handles have been destroyed then the `EFI_USB2_HC_PROTOCOL` is closed. Finally, the `Stop()` function will then place the USB Host Bus Controller in a quiescent state.

### 17.2.2.3 USB Hot-Plug Event

Hot-Plug is one of the most important features provided by USB. A USB bus driver implements this feature through two methods. There are two types of hubs defined in the USB specification. One is the USB root hub, which is implemented in the USB Host controller. A timer event is created for the root hub. The other one is a USB Hub. An event is created for each hub that is correctly configured. All these events are associated with the same trigger which is USB bus numerator.

When USB bus enumeration is triggered, the USB Bus Driver checks the source of the event. This is required because the root hub differs from standard USB hub in checking the hub status. The status of a root hub is retrieved through the `EFI_USB2_HC_PROTOCOL`, and that status of a standard USB hub is retrieved through a USB control transfer. A detailed description of the enumeration process is presented in the next section.

### 17.2.2.4 USB Bus Enumeration

When the periodic timer or the hubs notify event is signaled, the USB Bus Driver will perform bus enumeration.

1. Determine if the event is from the roothub or a standard USB hub.
2. Determine the port on which the connection change event occurred.
3. Determine if it is a connection change or a disconnection change.
4. If a connect change is detected, then a new device has been attached. Perform the following:
   a – Reset and enable that port.
   b – Configure the new device.
   c – Parse the device configuration descriptors; get all of its interface descriptors (i.e., all USB controllers), and configure each interface.
   d – Create a new handle for each interface (USB Controller) within the USB device. Attach the `EFI Device Path Protocol`, and `EFI_USB_IO_PROTOCOL` to each handle.
   e – Connect the USB Controller to a USB device driver with the Boot Service `EFI_BOOT_SERVICES.ConnectController()` if applicable.
   f – If the USB Controller is a USB hub, create a Hub notify event which is associated with the USB Bus Enumerator, and submit an Asynchronous Interrupt Transfer Request (`USB I/O Protocol`).
5. If a disconnect change, then a device has been detached from the USB Bus. Perform the following:
   a – If the device is not a USB Hub, then find and deconfigure the USB Controllers within the device. Then, stop each USB controller with `EFI_BOOT_SERVICES.DisconnectController()`, and uninstall the `EFI_DEVICE_PATH_PROTOCOL` and the `EFI_USB_IO_PROTOCOL` from the controller’s handle. If the `EFI_BOOT_SERVICES.DisconnectController()` call fails this process must be retried on a subsequent timer tick.
   b – If the USB controller is USB hub controller, first find and deconfigure all its downstream USB devices (this is a recursive process, since there may be additional USB hub controllers on the downstream ports), then deconfigure USB hub controller itself.

17.2. USB Driver Model
17.2.3 USB Device Driver

A USB Device Driver manages a USB Controller and produces a device abstraction for use by a preboot application.

17.2.3.1 USB Device Driver Entry Point

Like all other device drivers, the entry point for a USB Device Driver attaches EFI Driver Binding Protocol to image handle of the USB Device Driver.

17.2.3.2 Driver Binding Protocol for USB Device Drivers

The Driver Binding Protocol contains three services. These are:

- EFI_DRIVER_BINDING_PROTOCOL.Supported()
- EFI_DRIVER_BINDING_PROTOCOL.Start()
- EFI_DRIVER_BINDING_PROTOCOL.Stop()

The Supported() tests to see if the USB Device Driver can manage a device handle. This function checks to see if a controller can be managed by the USB Device Driver. This is done by opening the See EFI_USB_IO_PROTOCOL bus abstraction on the USB Controller handle, and using the EFI_USB_IO_PROTOCOL services to determine if this USB Controller matches the profile that the USB Device Driver is capable of managing.

The Start() function tells the USB Device Driver to start managing a USB Controller. It opens the EFI_USB_IO_PROTOCOL instance from the handle for the USB Controller. This protocol instance is used to perform USB packet transmission over the USB bus. For example, if the USB controller is USB keyboard, then the USB keyboard driver would produce and install the EFI_SIMPLE_TEXT_INPUT_PROTOCOL to the USB controller handle.

The Stop() function tells the USB Device Driver to stop managing a USB Controller. It removes the I/O abstraction protocol instance previously installed in Start() from the USB controller handle. It then closes the EFI_USB_IO_PROTOCOL.

17.2.4 USB I/O Protocol

This section provides a detailed description of the EFI_USB_IO_PROTOCOL. This protocol is used by code, typically drivers, running in the EFI boot services environment to access USB devices like USB keyboards, mice and mass storage devices. In particular, functions for managing devices on USB buses are defined here.

The interfaces provided in the EFI_USB_IO_PROTOCOL are for performing basic operations to access USB devices. Typically, USB devices are accessed through the four different transfers types:

- **Controller Transfer**  
  Typically used to configure the USB device into an operation mode.

- **Interrupt Transfer**  
  Typically used to get periodic small amount of data, like USB keyboard and mouse.

- **Bulk Transfer**  
  Typically used to transfer large amounts of data like reading blocks from USB mass storage devices.

- **Isochronous Transfer**  
  Typically used to transfer data at a fixed rate like voice data.

This protocol also provides mechanisms to manage and configure USB devices and controllers.
17.2.5 EFI_USB_IO_PROTOCOL

Summary
Provides services to manage and communicate with USB devices.

GUID

```
#define EFI_USB_IO_PROTOCOL_GUID\
{0x2B2F68D6,0x0CD2,0x44cf,\
 {0x8E,0x8B,0xBB,0xA2,0x0B,0x1B,0x5B,0x75}}
```

Protocol Interface Structure

```
typedef struct _EFI_USB_IO_PROTOCOL {
  EFI_USB_IO_CONTROL_TRANSFER UsbControlTransfer;
  EFI_USB_IO_BULK_TRANSFER UsbBulkTransfer;
  EFI_USB_IO_ASYNC_INTERRUPT_TRANSFER UsbAsyncInterruptTransfer;
  EFI_USB_IO_SYNC_INTERRUPT_TRANSFER UsbSyncInterruptTransfer
  EFI_USB_IO_ISOCHRONOUS_TRANSFER UsbIsochronousTransfer;
  EFI_USB_IO_ASYNC_ISOCHRONOUS_TRANSFER UsbAsyncIsochronousTransfer;
  EFI_USB_IO_GET_DEVICE_DESCRIPTOR UsbGetDeviceDescriptor;
  EFI_USB_IO_GET_CONFIG_DESCRIPTOR UsbGetConfigDescriptor;
  EFI_USB_IO_GET_INTERFACE_DESCRIPTOR UsbGetInterfaceDescriptor;
  EFI_USB_IO_GET_ENDPOINT_DESCRIPTOR UsbGetEndpointDescriptor;
  EFI_USB_IO_GET_STRING_DESCRIPTOR UsbGetStringDescriptor;
  EFI_USB_IO_GET_SUPPORTED_LANGUAGES UsbGetSupportedLanguages;
  EFI_USB_IO_PORT_RESET UsbPortReset;
} EFI_USB_IO_PROTOCOL;
```

Parameters

**UsbControlTransfer**
Accesses the USB Device through USB Control Transfer Pipe. See the `EFI_USB_IO_PROTOCOL.UsbControlTransfer()` function description.

**UsbBulkTransfer**
Accesses the USB Device through USB Bulk Transfer Pipe. See the `EFI_USB_IO_PROTOCOL.UsbBulkTransfer()` function description.

**UsbAsyncInterruptTransfer**
Non-block USB interrupt transfer. See the `EFI_USB_IO_PROTOCOL.UsbAsyncInterruptTransfer()` function description.

**UsbSyncInterruptTransfer**
Accesses the USB Device through USB Synchronous Interrupt Transfer Pipe. See the `EFI_USB_IO_PROTOCOL.UsbSyncInterruptTransfer()` function description.

**UsbIsochronousTransfer**
Accesses the USB Device through USB Isochronous Transfer Pipe. See the `EFI_USB_IO_PROTOCOL.UsbIsochronousTransfer()` function description.

**UsbAsyncIsochronousTransfer**
Non-block USB Isochronous transfer. See the `EFI_USB_IO_PROTOCOL.UsbAsyncIsochronousTransfer()` function description.

**UsbGetDeviceDescriptor**
Retrieves the device descriptor of a USB device. See the `EFI_USB_IO_PROTOCOL.UsbGetDeviceDescriptor()` function description.

17.2. USB Driver Model
UsbGetConfigDescriptor
Retrieves the activated configuration descriptor of a USB device. See the
EFI_USB_IO_PROTOCOL.UsbGetConfigDescriptor() function description.

UsbGetInterfaceDescriptor
Retrieves the interface descriptor of a USB Controller. See the EFI_USB_IO_PROTOCOL.UsbGetInterfaceDescriptor()
function description.

UsbGetEndpointDescriptor
Retrieves the endpoint descriptor of a USB Controller. See the EFI_USB_IO_PROTOCOL.UsbGetEndpointDescriptor()
function description.

UsbGetStringDescriptor
Retrieves the string descriptor inside a USB Device. See the EFI_USB_IO_PROTOCOL.UsbGetStringDescriptor()
function description.

UsbGetSupportedLanguages
Retrieves the array of languages that the USB device supports. See the
EFI_USB_IO_PROTOCOL.UsbGetSupportedLanguages() function description.

UsbPortReset
Resets and reconfigures the USB controller. See the EFI_USB_IO_PROTOCOL.UsbPortReset() function de-
scription.

Description
The EFI_USB_IO_PROTOCOL provides four basic transfers types described in the USB 1.1 Specification. These
include control transfer, interrupt transfer, bulk transfer and isochronous transfer. The EFI_USB_IO_PROTOCOL also
provides some basic USB device/controller management and configuration interfaces. A USB device driver uses the
services of this protocol to manage USB devices.

17.2.6 EFI_USB_IO_PROTOCOL.UsbControlTransfer()

Summary
This function is used to manage a USB device with a control transfer pipe. A control transfer is typically used to
perform device initialization and configuration.

Prototype

```
typedef EFI_STATUS
(EFIAPI *EFI_USB_IO_CONTROL_TRANSFER) (
    IN EFI_USB_IO_PROTOCOL *This,
    IN EFI_USB_DEVICE_REQUEST *Request,
    IN EFI_USB_DATA_DIRECTION Direction,
    IN UINT32 Timeout,
    IN OUT VOID *Data OPTIONAL,
    IN UINTN DataLength OPTIONAL,
    OUT UINT32 *Status
);
```

Parameters

This
A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in USB I/O
Protocol.
Request
A pointer to the USB device request that will be sent to the USB device. See Related Definitions below.

Direction
Indicates the data direction. See Related Definitions below for this type.

Data
A pointer to the buffer of data that will be transmitted to USB device or received from USB device.

Timeout
Indicating the transfer should be completed within this time frame. The units are in milliseconds. If Timeout is 0, then the caller must wait for the function to be completed until EFI_SUCCESS or EFI_DEVICE_ERROR is returned.

DataLength
The size, in bytes, of the data buffer specified by Data.

Status
A pointer to the result of the USB transfer.

Related Definitions

typedef enum {
    EfiUsbDataIn,
    EfiUsbDataOut,
    EfiUsbNoData
} EFI_USB_DATA_DIRECTION;

// Error code for USB Transfer Results
#define EFI_USB_NOERROR 0x0000
#define EFI_USB_ERR_NOTEXECUTE 0x0001
#define EFI_USB_ERR_STALL 0x0002
#define EFI_USB_ERR_BUFFER 0x0004
#define EFI_USB_ERR_BABBLE 0x0008
#define EFI_USB_ERR_NAK 0x0010
#define EFI_USB_ERR_CRC 0x0020
#define EFI_USB_ERR_TIMEOUT 0x0040
#define EFI_USB_ERR_BITSTUFF 0x0080
#define EFI_USB_ERR_SYSTEM 0x0100

typedef struct {
    UINT8 RequestType;
    UINT8 Request;
    UINT16 Value;
    UINT16 Index;
    UINT16 Length;
} EFI_USB_DEVICE_REQUEST;

RequestType
The field identifies the characteristics of the specific request.

Request
This field specifies the particular request.

Value
This field is used to pass a parameter to USB device that is specific to the request.
Index

This field is also used to pass a parameter to USB device that is specific to the request.

Length

This field specifies the length of the data transferred during the second phase of the control transfer. If it is 0, then there is no data phase in this transfer.

Description

This function allows a USB device driver to communicate with the USB device through a Control Transfer. There are three control transfer types according to the data phase. If the Direction parameter is EfiUsbNoData, Data is NULL, and DataLength is 0, then no data phase exists for the control transfer. If the Direction parameter is EfiUsbDataOut, then Data specifies the data to be transmitted to the device, and DataLength specifies the number of bytes to transfer to the device. In this case there is an OUT DATA stage followed by a SETUP stage. If the Direction parameter is EfiUsbDataIn, then Data specifies the data that is received from the device, and DataLength specifies the number of bytes to receive from the device. In this case there is an IN DATA stage followed by a SETUP stage. After the USB transfer has completed successfully, EFI_SUCCESS is returned. If the transfer cannot be completed due to timeout, then EFI_TIMEOUT is returned. If an error other than timeout occurs during the USB transfer, then EFI_DEVICE_ERROR is returned and the detailed status code is returned in Status.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The control transfer has been successfully executed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The parameter Direction is not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Request is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Status is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The control transfer fails due to timeout.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The transfer failed. The transfer status is returned in Status.</td>
</tr>
</tbody>
</table>

17.2.7 EFI_USB_IO_PROTOCOL.UsbBulkTransfer()

Summary

This function is used to manage a USB device with the bulk transfer pipe. Bulk Transfers are typically used to transfer large amounts of data to/from USB devices.

Prototype

typedef
EFI_STATUS
(EIFIAPIT *EFI_USB_IO_BULK_TRANSFER) (    
  IN EFI_USB_IO_PROTOCOL *This,        
  IN UINT8 DeviceEndpoint,           
  IN VOID *Data,                     
  IN OUT UINTN *DataLength,          
  IN UINTN Timeout,                  
  OUT UINT32 *Status                 
);    

Parameters

This

A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in USB I/O Protocol.
DeviceEndpoint
The destination USB device endpoint to which the device request is being sent. DeviceEndpoint must be between 0x01 and 0x0F or between 0x81 and 0x8F, otherwise EFI_INVALID_PARAMETER is returned. If the endpoint is not a BULK endpoint, EFI_INVALID_PARAMETER is returned. The MSB of this parameter indicates the endpoint direction. The number “1” stands for an IN endpoint, and “0” stands for an OUT endpoint.

Data
A pointer to the buffer of data that will be transmitted to USB device or received from USB device.

DataLength
On input, the size, in bytes, of the data buffer specified by Data. On output, the number of bytes that were actually transferred.

Timeout
Indicating the transfer should be completed within this time frame. The units are in milliseconds. If Timeout is 0, then the caller must wait for the function to be completed until EFI_SUCCESS or EFI_DEVICE_ERROR is returned.

Status
This parameter indicates the USB transfer status.

Description
This function allows a USB device driver to communicate with the USB device through Bulk Transfer. The transfer direction is determined by the endpoint direction. If the USB transfer is successful, then EFI_SUCCESS is returned. If USB transfer cannot be completed within the Timeout frame, EFI_TIMEOUT is returned. If an error other than timeout occurs during the USB transfer, then EFI_DEVICE_ERROR is returned and the detailed status code will be returned in the Status parameter.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The bulk transfer has been successfully executed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>If DeviceEndpoint is not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Data is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DataLength is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Status is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The bulk transfer cannot be completed within Timeout timeframe.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The transfer failed other than timeout, and the transfer status is returned in Status.</td>
</tr>
</tbody>
</table>

17.2.8 EFI_USB_IO_PROTOCOL.UsbAsyncInterruptTransfer()

Summary
This function is used to manage a USB device with an interrupt transfer pipe. An Asynchronous Interrupt Transfer is typically used to query a device’s status at a fixed rate. For example, keyboard, mouse, and hub devices use this type of transfer to query their interrupt endpoints at a fixed rate.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_USB_IO_ASYNC_INTERRUPT_TRANSFER) (
    IN EFI_USB_IO_PROTOCOL *This,
    IN UINT8 DeviceEndpoint,
    IN UINT8 DataLength,
    OUT PVOID Data,
    IN UINTN Timeout,
    OUT UINTN Status);
```
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

(continued from previous page)

```
IN BOOLEAN IsNewTransfer,
IN UINTN PollingInterval OPTIONAL,
IN UINTN DataLength OPTIONAL,
IN EFI_ASYNC_USB_TRANSFER_CALLBACK InterruptCallBack OPTIONAL,
IN VOID *Context OPTIONAL
);
```

Parameters

This

A pointer to the `EFI_USB_IO_PROTOCOL` instance. Type `EFI_USB_IO_PROTOCOL` is defined in `USB I/O Protocol`.

DeviceEndpoint

The destination USB device endpoint to which the device request is being sent. `DeviceEndpoint` must be between 0x01 and 0x0F or between 0x81 and 0x8F, otherwise `EFI_INVALID_PARAMETER` is returned. If the endpoint is not an INTERRUPT endpoint, `EFI_INVALID_PARAMETER` is returned. The MSB of this parameter indicates the endpoint direction. The number “1” stands for an IN endpoint, and “0” stands for an OUT endpoint.

IsNewTransfer

If `TRUE`, a new transfer will be submitted to USB controller. If `FALSE`, the interrupt transfer is deleted from the device’s interrupt transfer queue. If `TRUE`, and an interrupt transfer exists for the target endpoint, then `EFI_INVALID_PARAMETER` is returned.

PollingInterval

Indicates the periodic rate, in milliseconds, that the transfer is to be executed. This parameter is required when `IsNewTransfer` is `TRUE`. The value must be between 1 to 255, otherwise `EFI_INVALID_PARAMETER` is returned. The units are in milliseconds.

DataLength

Specifies the length, in bytes, of the data to be received from the USB device. This parameter is only required when `IsNewTransfer` is `TRUE`.

Context

Data passed to the `InterruptCallback` function. This is an optional parameter and may be `NULL`.

InterruptCallback

The `Callback` function. This function is called if the asynchronous interrupt transfer is completed. This parameter is required when `IsNewTransfer` is `TRUE`. See Related Definitions for the definition of this type.

Related Definitions

```c
typedef
EFI_STATUS
(EFIAPICALL * EFI_ASYNC_USB_TRANSFER_CALLBACK) (  
    IN VOID *Data,
    IN UINTN DataLength,
    IN VOID *Context,
    IN UINT32 Status
);
```

Data

Data received or sent via the USB Asynchronous Transfer, if the transfer completed successfully.

DataLength

The length of Data received or sent via the Asynchronous Transfer, if transfer successfully completes.

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Context
Data passed from `EFI_USB_IO_PROTOCOL.UsbAsyncInterruptTransfer()` request.

Status
Indicates the result of the asynchronous transfer.

Description
This function allows a USB device driver to communicate with a USB device with an Interrupt Transfer. Asynchronous Interrupt transfer is different than the other four transfer types because it is a nonblocking transfer. The interrupt endpoint is queried at a fixed rate, and the data transfer direction is always in the direction from the USB device towards the system.

If `IsNewTransfer` is `TRUE`, then an interrupt transfer is started at a fixed rate. The rate is specified by `PollingInterval`, the size of the receive buffer is specified by `DataLength`, and the callback function is specified by `InterruptCallback`.

If `IsNewTransfer` is `TRUE`, and an interrupt transfer exists for the target end point, then `EFI_INVALID_PARAMETER` is returned.

If `IsNewTransfer` is `FALSE`, then the interrupt transfer is canceled.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The asynchronous USB transfer request has been successfully executed.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The asynchronous USB transfer request failed. When an interrupt transfer exists for the target endpoint and a new transfer is requested, <code>EFI_INVALID_PARAMETER</code> is returned.</td>
</tr>
</tbody>
</table>

Examples
Below is an example of how an asynchronous interrupt transfer is used. The example shows how a USB Keyboard Device Driver can periodically receive data from interrupt endpoint.

```c
Efi_USB_IO_PROTOCOL *UsbIo;
Efi_Status Status;
usb_keyboard_dev *UsbKeyboardDevice;
Efi_USB_INTERRUPT_CALLBACK *KeyboardHandle;

... Status = UsbIo->UsbAsyncInterruptTransfer(
    UsbIo,
    UsbKeyboardDevice->IntEndpointAddress,
    TRUE,
    UsbKeyboardDevice->IntPollingInterval, 8,
    KeyboardHandler,
    UsbKeyboardDevice
    );

// The following is the InterruptCallback function. If there is any results got from Asynchronous Interrupt Transfer, this function will be called.
//
Efi_Status
KeyboardHandler(
```

(continues on next page)
17.2.9 EFI_USB_IO_PROTOCOL.UsbSyncInterruptTransfer()

Summary
This function is used to manage a USB device with an interrupt transfer pipe. The difference between
EFI_USB_IO_PROTOCOL.UsbAsyncInterruptTransfer() and UsbSyncInterruptTransfer() is that the Synchronous interrup
transfer will only be executed one time. Once it returns, regardless of its status, the interrupt request will be
deleted in the system.

Prototype

typedef
EFI_STATUS
(EFI_API *EFI_USB_IO_SYNC_INTERRUPT_TRANSFER) (  
  IN EFI_USB_IO_PROTOCOL *This,
  IN UINT8 DeviceEndpoint,
  IN OUT VOID *Data,
  IN OUT UINTN *DataLength,
  IN UINTN Timeout,
  OUT UINT32 *Status
);
This

A pointer to the \texttt{EFI_USB_IO_PROTOCOL} instance. Type \texttt{EFI_USB_IO_PROTOCOL} is defined in \textit{USB I/O Protocol}.

DeviceEndpoint

The destination USB device endpoint to which the device request is being sent. DeviceEndpoint must be between 0x01 and 0x0F or between 0x81 and 0x8F, otherwise \texttt{EFI_INVALID_PARAMETER} is returned. If the endpoint is not an INTERRUPT endpoint, \texttt{EFI_INVALID_PARAMETER} is returned. The MSB of this parameter indicates the endpoint direction. The number “1” stands for an IN endpoint, and “0” stands for an OUT endpoint.

Data

A pointer to the buffer of data that will be transmitted to USB device or received from USB device.

DataLength

On input, then size, in bytes, of the buffer Data. On output, the amount of data actually transferred.

Timeout

The time out, in milliseconds, for this transfer. If Timeout is 0, then the caller must wait for the function to be completed until \texttt{EFI_SUCCESS} or \texttt{EFI_DEVICE_ERROR} is returned. If the transfer is not completed in this time frame, then \texttt{EFI_TIMEOUT} is returned.

Status

This parameter indicates the USB transfer status.

Description

This function allows a USB device driver to communicate with a USB device through a synchronous interrupt transfer. The \texttt{UsbSyncInterruptTransfer()} differs from \texttt{EFI_USB_IO_PROTOCOL.UsbAsyncInterruptTransfer()} described in the previous section in that it is a blocking transfer request. The caller must wait for the function return, either successfully or unsuccessfully.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\texttt{EFI_SUCCESS}</td>
<td>The sync interrupt transfer has been successfully executed.</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>The parameter DeviceEndpoint is not valid.</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>Data is \texttt{NULL}.</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>DataLength is \texttt{NULL}.</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>Status is \texttt{NULL}.</td>
</tr>
<tr>
<td>\texttt{EFI_OUT_OF_RESOURCES}</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
<tr>
<td>\texttt{EFI_TIMEOUT}</td>
<td>The transfer cannot be completed within Timeout timeframe.</td>
</tr>
<tr>
<td>\texttt{EFI_DEVICE_ERROR}</td>
<td>The transfer failed other than timeout, and the transfer status is returned in Status.</td>
</tr>
</tbody>
</table>

17.2.10 \texttt{EFI_USB_IO_PROTOCOL.UsbIsochronousTransfer()}

Summary

This function is used to manage a USB device with an isochronous transfer pipe. An Isochronous transfer is typically used to transfer streaming data.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_USB_IO_ISOCHRONOUS_TRANSFER)(
    IN EFI_USB_IO_PROTOCOL *This,
    IN UINT32 DeviceEndpoint,
    IN EFI_USB_IO_DATA_TRANSFER Data,
    IN UINT32 DataLength,
    IN UINT32 Timeout,
    OUT EFI_STATUS *Status)
```

(continues on next page)
Parameters

This
   A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in USB I/O Protocol.

DeviceEndpoint
   The destination USB device endpoint to which the device request is being sent. DeviceEndpoint must be between 0x01 and 0x0F or between 0x81 and 0x8F, otherwise EFI_INVALID_PARAMETER is returned. If the endpoint is not an ISOCHRONOUS endpoint, EFI_INVALID_PARAMETER is returned. The MSB of this parameter indicates the endpoint direction. The number “1” stands for an IN endpoint, and “0” stands for an OUT endpoint.

Data
   A pointer to the buffer of data that will be transmitted to USB device or received from USB device.

DataLength
   The size, in bytes, of the data buffer specified by Data.

Status
   This parameter indicates the USB transfer status.

Description

This function allows a USB device driver to communicate with a USB device with an Isochronous Transfer. The type of transfer is different than the other types because the USB Bus Driver will not attempt to perform error recovery if transfer fails. If the USB transfer is completed successfully, then EFI_SUCCESS is returned. The isochronous transfer is designed to be completed within 1 USB frame time, if it cannot be completed, EFI_TIMEOUT is returned. If the transfer fails due to other reasons, then EFI_DEVICE_ERROR is returned and the detailed error status is returned in Status. If the data length exceeds the maximum payload per USB frame time, then it is this function’s responsibility to divide the data into a set of smaller packets that fit into a USB frame time. If all the packets are transferred successfully, then EFI_SUCCESS is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The isochronous transfer has been successfully executed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The parameter DeviceEndpoint is not valid.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to a lack of resources.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The transfer cannot be completed within the 1 USB frame time.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The transfer failed due to the reason other than timeout, The error status is returned in Status.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation doesn’t support an Isochronous transfer function.</td>
</tr>
</tbody>
</table>
17.2.11 EFI_USB_IO_PROTOCOL.UsbAsyncIsochronousTransfer()

Summary
This function is used to manage a USB device with an isochronous transfer pipe. An asynchronous Isochronous transfer is a nonblocking USB isochronous transfer.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_USB_IO_ASYNC_ISOCHRONOUS_TRANSFER) (
  IN EFI_USB_IO_PROTOCOL *This,
  IN UINT8 DeviceEndpoint,
  IN OUT VOID *Data,
  IN UINTN DataLength,
  IN EFI_ASYNC_USB_TRANSFER_CALLBACK IsochronousCallBack,
  IN VOID *Context OPTIONAL
);
```

Parameters

**This**
A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in USB I/O Protocol.

**DeviceEndpoint**
The destination USB device endpoint to which the device request is being sent. DeviceEndpoint must be between 0x01 and 0x0F or between 0x81 and 0x8F, otherwise EFI_INVALID_PARAMETER is returned. If the endpoint is not an ISOCHRONOUS endpoint, EFI_INVALID_PARAMETER is returned. The MSB of this parameter indicates the endpoint direction. The number “1” stands for an IN endpoint, and “0” stands for an OUT endpoint.

**Data**
A pointer to the buffer of data that will be transmitted to USB device or received from USB device.

**DataLength**
Specifies the length, in bytes, of the data to be sent to or received from the USB device.

**Context**
Data passed to the IsochronousCallback() in Protocols_USB_Support.rst function. This is an optional parameter and may be NULL.

**IsochronousCallback**
The IsochronousCallback() function. This function is called if the requested isochronous transfer is completed. See the Related Definitions section of the EFI_USB_IO_PROTOCOL.UsbAsyncInterruptTransfer() function description.

Description
This is an asynchronous type of USB isochronous transfer. If the caller submits a USB isochronous transfer request through this function, this function will return immediately. When the isochronous transfer completes, the IsochronousCallback() function will be triggered, the caller can know the transfer results. If the transfer is successful, the caller can get the data received or sent in this callback function.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The asynchronous isochronous transfer has been successfully submitted to the system.</td>
</tr>
</tbody>
</table>
Table 17.18 – continued from previous page

<table>
<thead>
<tr>
<th>EFI_INVALID_PARAMETER</th>
<th>The parameter DeviceEndpoint is not valid.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be submitted due to a lack of resources.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation doesn’t support an asynchronous Isochronous transfer function.</td>
</tr>
</tbody>
</table>

17.2.12 EFI_USB_IO_PROTOCOL.UsbGetDeviceDescriptor()

Summary
Retrieves the USB Device Descriptor.

Prototype

typedef EFI_STATUS (EFIAPI * EFI_USB_IO_GET_DEVICE_DESCRIPTOR) (  
  IN EFI_USB_IO_PROTOCOL *This,  
  OUT EFI_USB_DEVICE_DESCRIPTOR *DeviceDescriptor  
);

Parameters

This
A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in USB I/O Protocol.

DeviceDescriptor
A pointer to the caller allocated USB Device Descriptor. See Related Definitions for a detailed description.

Related Definitions

// See USB1.1 for detail description.
//
typedef struct {
  UINT8 Length;
  UINT8 DescriptorType;
  UINT16 BcdUSB;
  UINT8 DeviceClass;
  UINT8 DeviceSubClass;
  UINT8 DeviceProtocol;
  UINT8 MaxPacketSize0;
  UINT16 IdVendor;
  UINT16 IdProduct;
  UINT16 BcdDevice;
  UINT8 StrManufacturer;
  UINT8 StrProduct;
  UINT8 StrSerialNumber;
  UINT8 NumConfigurations;
} EFI_USB_DEVICE_DESCRIPTOR;

Description
This function is used to retrieve information about USB devices. This information includes the device class, subclass, and the number of configurations the USB device supports. If DeviceDescriptor is NULL, then
EFI_INVALID_PARAMETER is returned. If the USB device descriptor is not found, then EFI_NOT_FOUND is returned. Otherwise, the device descriptor is returned in DeviceDescriptor, and EFI_SUCCESS is returned.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device descriptor was retrieved successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>DeviceDescriptor is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The device descriptor was not found. The device may not be configured.</td>
</tr>
</tbody>
</table>

#### 17.2.13 EFI_USB_IO_PROTOCOL.UsbGetConfigDescriptor()

**Summary**

Retrieves the USB Device Configuration Descriptor.

**Prototype**

```c
typedef EFI_STATUS (EFIAPICALLTYPE EFI_USB_IO_GET_CONFIG_DESCRIPTOR)(
    IN EFI_USB_IO_PROTOCOL *This,
    OUT EFI_USB_CONFIG_DESCRIPTOR *ConfigurationDescriptor
);
```

**Parameters**

- **This**
  
  A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in USB I/O Protocol.

- **ConfigurationDescriptor**
  
  A pointer to the caller allocated USB Active Configuration Descriptor. See Related Definitions for a detailed description.

**Related Definitions**

```c
// See USB1.1 for detail description.
//
typedef struct {
    UINT8 Length;
    UINT8 DescriptorType;
    UINT16 TotalLength;
    UINT8 NumInterfaces;
    UINT8 ConfigurationValue;
    UINT8 Configuration;
    UINT8 Attributes;
    UINT8 MaxPower;
} EFI_USB_CONFIG_DESCRIPTOR;
```

**Description**

This function is used to retrieve the active configuration that the USB device is currently using. If ConfigurationDescriptor is NULL, then EFI_INVALID_PARAMETER is returned. If the USB controller does not contain an active configuration, then EFI_NOT_FOUND is returned. Otherwise, the active configuration is returned in ConfigurationDescriptor, and EFI_SUCCESS is returned.
Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The active configuration descriptor was retrieved successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ConfigurationDescriptor is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>An active configuration descriptor cannot be found. The device may not be configured.</td>
</tr>
</tbody>
</table>

17.2.14 EFI_USB_IO_PROTOCOL.UsbGetInterfaceDescriptor()

Summary
Retrieves the Interface Descriptor for a USB Device Controller. As stated earlier, an interface within a USB device is equivalently to a USB Controller within the current configuration.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_USB_IO_GET_INTERFACE_DESCRIPTOR) (
    IN EFI_USB_IO_PROTOCOL *This,
    OUT EFI_USB_INTERFACE_DESCRIPTOR *InterfaceDescriptor
);

Parameters

This
A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in USB I/O Protocol.

InterfaceDescriptor
A pointer to the caller allocated USB Interface Descriptor within the configuration setting. See Related Definitions for a detailed description.

Related Definitions

//
// See USB1.1 for detail description.
//
typedef struct {
    UINT8 Length;
    UINT8 DescriptorType;
    UINT8 InterfaceNumber;
    UINT8 AlternateSetting;
    UINT8 NumEndpoints;
    UINT8 InterfaceClass;
    UINT8 InterfaceSubClass;
    UINT8 InterfaceProtocol;
    UINT8 Interface;
} EFI_USB_INTERFACE_DESCRIPTOR;

Description
This function is used to retrieve the interface descriptor for the USB controller. If InterfaceDescriptor is NULL, then EFI_INVALID_PARAMETER is returned. If the USB controller does not contain an interface descriptor, then EFI_NOT_FOUND is returned. Otherwise, the interface descriptor is returned in InterfaceDescriptor, and EFI_SUCCESS is returned.
Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The interface descriptor retrieved successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>InterfaceDescriptor is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The interface descriptor cannot be found. The device may not be correctly configured.</td>
</tr>
</tbody>
</table>

17.2.15 EFI_USB_IO_PROTOCOL.UsbGetEndpointDescriptor()

Summary
Retrieves an Endpoint Descriptor within a USB Controller.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_USB_IO_GET_ENDPOINT_DESCRIPTOR) (  
    IN EFI_USB_IO_PROTOCOL *This,  
    IN UINT8 EndpointIndex,  
    OUT EFI_USB_ENDPOINT_DESCRIPTOR *EndpointDescriptor  
);  
```

Parameters

**This**
A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in USB I/O Protocol.

**EndpointIndex**
Indicates which endpoint descriptor to retrieve. The valid range is 0..15.

**EndpointDescriptor**
A pointer to the caller allocated USB Endpoint Descriptor of a USB controller. See Related Definitions for a detailed description.

Related Definitions

```c
// See USB1.1 for detail description.  
//
typedef struct {  
    UINT8 Length;  
    UINT8 DescriptorType;  
    UINT8 EndpointAddress;  
    UINT8 Attributes;  
    UINT16 MaxPacketSize;  
    UINT8 Interval;  
} EFI_USB_ENDPOINT_DESCRIPTOR;
```

Description
This function is used to retrieve an endpoint descriptor within a USB controller. If EndpointIndex is not in the range 0..15, then EFI_INVALID_PARAMETER is returned. If EndpointDescriptor is NULL, then EFI_INVALID_PARAMETER is returned. If the endpoint specified by EndpointIndex does not exist within the USB
controller, then `EFI_NOT_FOUND` is returned. Otherwise, the endpoint descriptor is returned in `EndpointDescriptor`, and `EFI_SUCCESS` is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The endpoint descriptor was retrieved successfully.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>EndpointIndex is not valid.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>EndpointDescriptor is NULL.</td>
</tr>
<tr>
<td><code>EFI_NOT_FOUND</code></td>
<td>The endpoint descriptor cannot be found. The device may not be correctly configured.</td>
</tr>
</tbody>
</table>

**Examples**

The following code fragment shows how to retrieve all the endpoint descriptors from a USB controller.

```c
EFI_USB_IO_PROTOCOL *UsbIo;
EFI_USB_INTERFACE_DESCRIPTOR InterfaceDesc;
EFI_USB_ENDPOINT_DESCRIPTOR EndpointDesc;
UINTN Index;

Status = UsbIo->GetInterfaceDescriptor (  
    UsbIo,  
    &InterfaceDesc  
);  
.
.
for (Index = 0; Index < InterfaceDesc.NumEndpoints; Index++) {
    Status = UsbIo->GetEndpointDescriptor(  
        UsbIo,  
        Index,  
        &EndpointDesc  
    );
    .
.
}
```

**17.2.16 EFI_USB_IO_PROTTOCOL.UsbGetStringDescriptor()**

**Summary**

Retrieves a string stored in a USB Device.

**Prototype**

```c
typedef
EFI_STATUS  
(EFIAPI *EFI_USB_IO_GET_STRING_DESCRIPTOR) (  
    IN EFI_USB_IO_PROTOCOL *This,  
    IN UINT16 LangID,  
    IN UINT8 StringID,  
    OUT CHAR16 **String  
);  
```

**Parameters**
This
A pointer to the `EFI_USB_IO_PROTOCOL` instance. Type `EFI_USB_IO_PROTOCOL` is defined in `USB I/O Protocol`.

LangID
The Language ID for the string being retrieved. See the `EFI_USB_IO_PROTOCOL.UsbGetSupportedLanguages()` function description for a more detailed description.

StringID
The ID of the string being retrieved.

String
A pointer to a buffer allocated by this function with `EFI_BOOT_SERVICES.AllocatePool()` to store the string. If this function returns `EFI_SUCCESS`, it stores the string the caller wants to get. The caller should release the string buffer with `EFI_BOOT_SERVICES.FreePool()` after the string is not used any more.

Description
This function is used to retrieve strings stored in a USB device. The string to retrieve is identified by a language and an identifier. The language is specified by `LangID`, and the identifier is specified by `StringID`. If the string is found, it is returned in `String`, and `EFI_SUCCESS` is returned. If the string cannot be found, then `EFI_NOT_FOUND` is returned. The string buffer is allocated by this function with `AllocatePool()`. The caller is responsible for calling `FreePool()` for `String` when it is no longer required.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The string was retrieved successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The string specified by LangID and StringID was not found.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There are not enough resources to allocate the return buffer String.</td>
</tr>
</tbody>
</table>

17.2.17 EFI_USB_IO_PROTOCOL.UsbGetSupportedLanguages()

Summary
Retrieves all the language ID codes that the USB device supports.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_USB_IO_GET_SUPPORTED_LANGUAGES) (  
    IN EFI_USB_IO_PROTOCOL  *This,  
    OUT UINT16              *LangIDTable,  
    OUT UINT16              *TableSize
);
```

Parameters

This
A pointer to the `EFI_USB_IO_PROTOCOL` instance. Type `EFI_USB_IO_PROTOCOL` is defined in `USB I/O Protocol`.

LangIDTable
Language ID for the string the caller wants to get. This is a 16-bit ID defined by Microsoft. This buffer pointer is allocated and maintained by the USB Bus Driver, the caller should not modify its contents.

TableSize
The size, in bytes, of the table `LangIDTable`. 
Description
Retrieves all the language ID codes that the USB device supports.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The support languages were retrieved successfully.</td>
</tr>
</tbody>
</table>

17.2.18 EFI_USB_IO_PROTOCOL.UsbPortReset()

Summary
Resets and reconfigures the USB controller. This function will work for all USB devices except USB Hub Controllers.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPIC *EFI_USB_IO_PORT_RESET) (
    IN EFI_USB_IO_PROTOCOL *This
);
```

Parameters

This
A pointer to the EFI_USB_IO_PROTOCOL instance. Type EFI_USB_IO_PROTOCOL is defined in USB I/O Protocol.

Description
This function provides a reset mechanism by sending a RESET signal from the parent hub port. A reconfiguration process will happen (that includes setting the address and setting the configuration). This reset function does not change the bus topology. A USB hub controller cannot be reset using this function, because it would impact the downstream USB devices. So if the controller is a USB hub controller, then EFI_INVALID_PARAMETER is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The USB controller was reset.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>If the controller specified by This is a USB hub.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An error occurred during the reconfiguration process.</td>
</tr>
</tbody>
</table>

17.3 USB Function Protocol

This section describes the USB Function Protocol, enabling a USB Function device with a UEFI driver that implements the protocol to communicate with a USB Host device.

The USB Function Protocol provides an I/O abstraction for a USB Controller operating in Function mode (also commonly referred to as Device, Peripheral, or Target mode) and the mechanisms by which the USB Function can communicate with the USB Host. It is used by other UEFI drivers or applications to perform data transactions and basic USB controller management over a USB Function port.

This simple protocol only supports USB 2.0 bulk transfers on systems with a single configuration and a single interface. It does not support isochronous or interrupt transfers, alternate interfaces, or USB 3.0 functionality. Future revisions of this protocol may support these or additional features.
17.3.1 EFI_USBFN_IO_PROTOCOL

Summary
Provides basic data transactions and basic USB controller management for a USB Function port.

GUID

// {32D2963A-FE5D-4F30-B633-6E5DC55803CC}
#define EFI_USBFN_IO_PROTOCOL_GUID \
{0x32d2963a, 0xfe5d, 0x4f30,} \
{0xb6, 0x33, 0x6e, 0x5d, 0xc5, 0x58, 0x3, 0xcc};

Revision Number

#define EFI_USBFN_IO_PROTOCOL_REVISION 0x00010001

Protocol Interface Structure

typedef struct _EFI_USBFN_IO_PROTOCOL {
    UINT32 Revision;
    EFI_USBFN_IO_DETECT_PORT DetectPort;
    EFI_USBFN_IO_CONFIGURE_ENABLE_ENDPOINTS ConfigureEnableEndpoints;
    EFI_USBFN_IO_GET_ENDPOINT_MAXPACKET_SIZE GetEndpointMaxPacketSize;
    EFI_USBFN_IO_GET_DEVICE_INFO GetDeviceInfo;
    EFI_USBFN_IO_GET_VENDOR_ID_PRODUCT_ID GetVendorIdProductId;
    EFI_USBFN_IO_ABORT_TRANSFER AbortTransfer;
    EFI_USBFN_IO_GET_ENDPOINT_STALL_STATE GetEndpointStallState;
    EFI_USBFN_IO_SET_ENDPOINT_STALL_STATE SetEndpointStallState;
    EFI_USBFN_IO_EVENTHANDLER EventHandler;
    EFI_USBFN_IO_TRANSFER Transfer;
    EFI_USBFN_IO_GET_MAXTRANSFER_SIZE GetMaxTransferSize;
    EFI_USBFN_IO_ALLOCATE_TRANSFER_BUFFER AllocateTransferBuffer;
    EFI_USBFN_IO_FREE_TRANSFER_BUFFER FreeTransferBuffer;
    EFI_USBFN_IO_START_CONTROLLER StartController;
    EFI_USBFN_IO_STOP_CONTROLLER StopController;
    EFI_USBFN_IO_SET_ENDPOINT_POLICY SetEndpointPolicy;
    EFI_USBFN_IO_GET_ENDPOINT_POLICY GetEndpointPolicy;
} EFI_USBFN_IO_PROTOCOL;

Parameters

Revision
The revision to which the EFI_USBFN_IO_PROTOCOL adheres. All future revisions must be backwards compatible. If a future version is not backwards compatible, a different GUID must be used.

DetectPort
Returns information about the USB port type. See Related Definitions EFI_USBFN_IO_PROTOCOL.DetectPort(), for more details.
ConfigureEnableEndpoints
   Initializes all endpoints based on supplied device and configuration descriptors. Enables the device by setting
   the run/stop bit.

GetEndpointMaxPacketSize
   Returns the maximum packet size of the specified endpoint.

GetDeviceInfo
   Returns device specific information based on the supplied identifier as a Unicode string.

GetVendorIdProductId
   Returns the vendor-id and product-id of the device.

AbortTransfer
   Aborts the transfer on the specified endpoint.

GetEndpointStallState
   Returns the stall state on the specified endpoint.

SetEndpointStallState
   Sets or clears the stall state on the specified endpoint.

EventHandler
   This function is called repeatedly to get information on USB bus states, receive-completion and transmit-
   completion events on the endpoints, and notification on setup packet on endpoint 0.

Transfer
   This function handles transferring data to or from the host on the specified endpoint, depending on the direction
   specified.

GetMaxTransferSize
   The maximum supported transfer size in bytes.

AllocateTransferBuffer
   Allocates a transfer buffer of the specified size that satisfies the controller requirements.

FreeTransferBuffer
   Deallocates the memory allocated for the transfer buffer by EFI_USBFN_IO_PROTOCOL.AllocateTransferBuffer() function.

StartController
   This function initializes the hardware and the internal data structures. The port must not be activated by this
   function.

StopController
   This function disables the device by deactivating the port.

SetEndpointPolicy
   This function sets the configuration policy for the specified non-control endpoint. There are a few calling restric-
   tions for this function. See the EFI_USBFN_IO_PROTOCOL.SetEndpointPolicy() function definition for more
details.

GetEndpointPolicy
   This functions retrieves the configuration policy for the specified non-control endpoint.

Description
   This protocol provides basic data transactions and USB controller management for a USB Function port. It provides a
   lightweight communication mechanism between a USB Host and a USB Function in the UEFI environment.

   Like other UEFI device drivers, the entry point for a USB function driver attaches EFI_DRV DRIVER_BINDING_PROTOCOL to image handle of EFI_USBFN_IO_PROTOCOL driver.

17.3. USB Function Protocol
The driver binding protocol contains three services, Supported, Start and Stop.

The Supported function must test to see if this driver supports a given controller.

The Start function must supply power to the USB controller if needed, initialize hardware and internal data structures, and then return. The port must not be activated by this function.

The Stop function must disable the USB controller and power it off if needed.

### 17.3.2 EFI_USBFN_IO_PROTOCOL.DetectPort()

**Summary**

Returns information about what USB port type was attached.

**Prototype**

```c
typedef EFI_STATUS
(EIFIAPIC * EFI_USBFN_IO_DETECT_PORT) (  
  IN EFI_USBFN_IO_PROTOCOL *This,
  OUT EFI_USBFN_PORT_TYPE *PortType
);
```

**Parameters**

- **This**
  
  A pointer to the `EFI_USBFN_IO_PROTOCOL` instance.

- **PortType**
  
  Returns the USB port type. Refer to the `Related Definitions` for this function below for details.

**Description**

Returns information about the USB port type attached. Refer to the `Related Definitions` below for further details.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The physical device is busy or not ready to process this request or there is no USB port attached to the device</td>
</tr>
</tbody>
</table>

**Related Definitions**

```c
typedef enum _EFI_USBFN_PORT_TYPE {  
  EfiUsbUnknownPort = 0,
  EfiUsbStandardDownstreamPort,
  EfiUsbChargingDownstreamPort,
  EfiUsbDedicatedChargingPort,
  EfiUsbInvalidDedicatedChargingPort
} EFI_USBFN_PORT_TYPE;
```

**Unknown Port**

Driver internal default port type, this is never returned by the driver with a success status code.
Standard Downstream Port
Standard USB host; refer to *USB Battery Charging Specification, Revision 1.2* in Appendix Q.1 for details and the link.

Charging Downstream Port
Standard USB host with special charging properties; refer to *USB Battery Charging Specification, Revision 1.2* in Appendix Q.1 for the details and link.

Dedicated Charging Port
A wall-charger, not USB host; refer to *USB Battery Charging Specification, Revision 1.2*, in Appendix Q.1 for details and the link.

Invalid Dedicated Charging Port
Neither a USB host nor a dedicated charging port as defined by the *USB Battery Charging Specification, Revision 1.2*, in Appendix Q.1 for details and the link.) An example is a USB charger that raises the voltages on D+/D-, causing the charger to look like an SDP even though it will never issue a setup packet to the upstream facing port.

### 17.3.3 EFI_USBFSN_IO_PROTOCOL.ConfirmEnableEndpoints()

**Summary**
Configures endpoints based on supplied device and configuration descriptors.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI * EFI_USBFSN_IO_PROTOCOL ConfigureEnableEndpoints) (  
  IN EFI_USBFSN_IO_PROTOCOL *This,
  IN EFI_USB_DEVICE_INFO *DeviceInfo
);
```

**Parameters**

*This*
A pointer to the *EFI_USBFSN_IO_PROTOCOL* instance.

*DeviceInfo*
A pointer to *EFI_USBFSN_DEVICE_INFO* instance. Refer to the Related Definitions for this function below for details.

**Description**
Assuming that the hardware has already been initialized, this function configures the endpoints using the device information supplied by *DeviceInfo*, activates the port, and starts receiving USB events.

This function must ignore the *bMaxPacketSize0* field of the Standard Device Descriptor and the *wMaxPacketSize* field of the Standard Endpoint Descriptor that are made available through *DeviceInfo*.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The physical device is busy or not ready to process this request.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The request could not be completed due to lack of resources.</td>
</tr>
</tbody>
</table>

**Related Definitions**

17.3. USB Function Protocol
typedef struct {
    EFI_USB_INTERFACE_DESCRIPTOR *InterfaceDescriptor;
    EFI_USB_ENDPOINT_DESCRIPTOR **EndpointDescriptorTable;
} EFI_USB_INTERFACE_INFO;

typedef struct {
    EFI_USB_CONFIG_DESCRIPTOR *ConfigDescriptor*;
    EFI_USB_INTERFACE_INFO **InterfaceInfoTable*;
} EFI_USB_CONFIG_INFO;

typedef struct {
    EFI_USB_DEVICE_DESCRIPTOR *DeviceDescriptor*;
    EFI_USB_CONFIG_INFO **ConfigInfoTable*;
} EFI_USB_DEVICE_INFO;

USB_DEVICE_DESCRIPTOR, USB_CONFIG_DESCRIPTOR, USB_INTERFACE_DESCRIPTOR, and
USB_ENDPOINT_DESCRIPTOR are defined in Section USB I/O Protocol.

17.3.4 EFI_USBFN_IO_PROTOCOL.GetEndpointMaxPacketSize()

Summary

Returns the maximum packet size of the specified endpoint type for the supplied bus speed.

Prototype

```c
typedef EFI_STATUS (EFIAPI * EFI_USBFN_IO_GET_ENDPOINT_MAXPACKET_SIZE) (
    IN EFI_USBFN_IO_PROTOCOL *This,
    IN EFI_USB_ENDPOINT_TYPE EndpointType,
    IN EFI_USB_BUS_SPEED BusSpeed,
    OUT UINT16 *MaxPacketSize
);```

Parameters

This

A pointer to the EFI_USBFN_IO_PROTOCOL instance.

EndpointType

Endpoint type as defined as EFI_USB_ENDPOINT_TYPE in the Related Definitions for this function below for details.

BusSpeed

Bus speed as defined as EFI_USB_BUS_SPEED in the Related Definitions for the EventHandle function for details.

MaxPacketSize

The maximum packet size, in bytes, of the specified endpoint type.

Description

Returns the maximum packet size of the specified endpoint type for the supplied bus speed. If the BusSpeed is Usb-BusSpeedUnknown, the maximum speed the underlying controller supports is assumed.
This protocol currently does not support isochronous or interrupt transfers. Future revisions of this protocol may eventually support it.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The physical device is busy or not ready to process this request.</td>
</tr>
</tbody>
</table>

### Related Definitions

```c
typedef enum _EFI_USB_ENDPOINT_TYPE
{
    UsbEndpointControl = 0x00,
    // UsbEndpointIsynchronous = 0x01,
    UsbEndpointBulk = 0x02,
    // UsbEndpointInterrupt = 0x03
} EFI_USB_ENDPOINT_TYPE;
```

### 17.3.5 EFI_USBFN_IO_PROTOCOL.GetDeviceInfo()

#### Summary

Returns device specific information based on the supplied identifier as a Unicode string.

#### Prototype

```c
typedef EFI_STATUS
(EFIAPI * EFI_USBFN_IO_GET_DEVICE_INFO) (    
    IN EFI_USBFN_IO_PROTOCOL *This,             
    IN EFI_USBFN_DEVICE_INFO_ID Id,             
    IN OUT UINTN BufferSize,                   
    OUT VOID Buffer OPTIONAL                   
);
```

#### Parameters

**This**

A pointer to the `EFI_USBFN_IO_PROTOCOL` instance.

**Id**

The requested information id. Refer to the Related Definitions for this function below for details.

**BufferSize**

On input, the size of the `Buffer` in bytes. On output, the amount of data returned in `Buffer` in bytes.

**Buffer**

A pointer to a buffer to return the requested information as a Unicode string.

#### Description

Returns device specific information based on the supplied identifier as a Unicode string. If the supplied `Buffer` isn't large enough, or is `NULL`, the method fails with `EFI_BUFFER_TOO_SMALL` and the required size is returned through `BufferSize`. All returned strings are in Unicode format.
An \textit{Id} of \texttt{EfiUsbDeviceInfoUnknown} is treated as an invalid parameter.

\textbf{Status Codes Returned}

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\texttt{EFI_SUCCESS}</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>One or more of the following conditions is \texttt{TRUE}:  \begin{itemize} \item BufferSize is \texttt{NULL}. \item BufferSize(^1) is not 0 and Buffer is \texttt{NULL}. \item Id in invalid. \end{itemize}</td>
</tr>
<tr>
<td>\texttt{EFI_DEVICE_ERROR}</td>
<td>The physical device reported an error.</td>
</tr>
<tr>
<td>\texttt{EFI_NOT_READY}</td>
<td>The physical device is busy or not ready to process this request.</td>
</tr>
<tr>
<td>\texttt{EFI_BUFFER_TOO_SMALL}</td>
<td>The buffer is too small to hold the buffer. (^1)BufferSize has been updated with the size needed to hold the request string.</td>
</tr>
</tbody>
</table>

\textbf{Related Definitions}

\begin{verbatim}
typedef enum _EFI_USBFN_DEVICE_INFO_ID
{    EfiUsbDeviceInfoUnknown = 0,
    EfiUsbDeviceInfoSerialNumber,
    EfiUsbDeviceInfoManufacturerName,
    EfiUsbDeviceInfoProductName
} EFI_USBFN_DEVICE_INFO_ID;
\end{verbatim}

\textbf{17.3.6 EFI_USBFN_IO_PROTOCOL.GetVendorIdProductId()}

\textbf{Summary}

Returns the vendor-id and product-id of the device.

\textbf{Prototype}

\begin{verbatim}
typedef EFI_STATUS
(EFIAPI * EFI_USBFN_IO_GET_VENDOR_ID_PRODUCT_ID) (  
    IN EFI_USBFN_IO_PROTOCOL *This,
    OUT UINT16 *Vid,
    OUT UINT16 *Pid
);
\end{verbatim}

\textbf{Parameters}

\begin{itemize}
\item \textbf{This} \hspace{1cm} A pointer to the \texttt{EFI_USBFN_IO_PROTOCOL} instance.
\item \textbf{Vid} \hspace{1cm} Returned vendor-id of the device.
\item \textbf{Pid} \hspace{1cm} Returned product-id of the device.
\end{itemize}

\textbf{Description}

Returns vendor-id and product-id of the device.
Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Unable to return the vendor-id or the product-id</td>
</tr>
</tbody>
</table>

Related Definitions

Vendor IDs (VIDs) are 16-bit numbers that represent the device’s vendor company and are assigned and maintained by the USB-IF. Product IDs (PIDs) are 16-bit numbers assigned by each vendor to the device.

17.3.7 EFI_USBFN_IO_PROTOCOL.AbortTransfer()

Summary
Aborts the transfer on the specified endpoint.

Prototype

```c
typedef EFI_STATUS
(EFIAPI * EFI_USBFN_IO_ABORT_TRANSFER) (  
    IN EFI_USBFN_IO_PROTOCOL *This,
    IN UINT8 EndpointIndex,
    IN EFI_USBFN_ENDPOINT_DIRECTION Direction
);
```

Parameters

This
A pointer to the EFI_USBFN_IO_PROTOCOL instance.

EndpointIndex
Indicates the endpoint on which the ongoing transfer needs to be canceled.

Direction
Direction of the endpoint. Refer to the Related Definitions for this function (below) for details.

Description
Aborts the transfer on the specified endpoint. This function should fail with EFI_INVALID_PARAMETER if the specified direction is incorrect for the endpoint.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The physical device is busy or not ready to process this request.</td>
</tr>
</tbody>
</table>

Related Definitions

```c
typedef enum _EFI_USBFN_ENDPOINT_DIRECTION 
{
    EfiUsbEndpointDirectionHostOut = 0,
    EfiUsbEndpointDirectionHostIn, 
};
```
EfiUsbEndpointDirectionDeviceTx = EfiUsbEndpointDirectionHostIn,
EfiUsbEndpointDirectionDeviceRx = EfiUsbEndpointDirectionHostOut
} EFI_USBFN_ENDPOINT_DIRECTION;

17.3.8 EFI_USBFN_IO_PROTOCOL.GetEndpointStallState()

Summary
Returns the stall state on the specified endpoint.

Prototype

typedef EFI_STATUS
(EIFIAPI * EFI_USBFN_IO_GET_ENDPOINTSTALL_STATE) (  
  IN EFI_USBFN_IO_PROTOCOL *This,
  IN UINT8 EndpointIndex,
  IN EFI_USBFN_ENDPOINT_DIRECTION Direction,
  IN OUT BOOLEAN *State
);

Parameters

This
A pointer to the EFI_USBFN_IO_PROTOCOL instance.

EndpointIndex
Indicates the endpoint.

Direction
Direction of the endpoint. Refer to the Related Definitions for details see EFI_USBFN_IO_PROTOCOL.AbortTransfer() .

State
Boolean, true value indicates that the endpoint is in a stalled state, false otherwise.

Description
Returns the stall state on the specified endpoint. This function would fail with EFI_INVALID_PARAMETER if the specified direction is incorrect for the endpoint.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The physical device is busy or not ready to process this request.</td>
</tr>
</tbody>
</table>
17.3.9 EFI_USBFIN_IO_PROTOCOL.SetEndpointStallState()

Summary
Sets or clears the stall state on the specified endpoint.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI * EFI_USBFIN_IO_SET_ENDPOINTSTALL_STATE) (
    IN EFI_USBFIN_IO_PROTOCOL *This,
    IN UINT8 EndpointIndex,
    IN EFI_USBFIN_ENDPOINT_DIRECTION Direction,
    IN BOOLEAN State
);
```

Parameters

**This**
A pointer to the `EFI_USBFIN_IO_PROTOCOL` instance.

**EndpointIndex**
Indicates the endpoint.

**Direction**
Direction of the endpoint. Refer to the Related Definitions for the `EFI_USBFIN_IO_PROTOCOL_ABORTTRANSFER()` function for details.

**State**
Requested stall state on the specified endpoint. `TRUE` value causes the endpoint to stall; `FALSE` value clears an existing stall.

Description
Sets or clears the stall state on the specified endpoint. This function would fail with `EFI_INVALID_PARAMETER` if the specified direction is incorrect for the endpoint.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The physical device is busy or not ready to process this request.</td>
</tr>
</tbody>
</table>
17.3.10 EFI_USBFN_IO_PROTOCOL.EventHandler()

Summary
This function is called repeatedly to get information on USB bus states, receive-completion and transmit-completion events on the endpoints, and notification on setup packet on endpoint 0.

Prototype

typedef
EFI_STATUS
(EIFIAPI * EFI_USBFN_IO_EVENTHANDLER) (  
    IN EFI_USBFN_IO_PROTOCOL *This,
    OUT EFI_USBFN_MESSAGE *Message,
    IN OUT UINTN *PayloadSize,
    OUT EFI_USBFN_MESSAGE_PAYLOAD *Payload  
);

Parameters
This
A pointer to the EFI_USBFN_IO_PROTOCOL instance.

Message
Indicates the event that initiated this notification. Refer to the Related Definitions for this function (below) for all possible types.

PayloadSize
On input, the size of the memory pointed by Payload. On output, the amount of data returned in Payload.

Payload
A pointer to EFI_USBFN_MESSAGE_PAYLOAD instance to return additional payload for current message. Refer to the Related Definitions for this function (below) for details on the type.

Description
This function is called repeatedly to get information on USB bus states, receive-completion and transmit-completion events on the endpoints, and notification on setup packet on endpoint 0. A class driver must call EFI_USBFN_IO_PROTOCOL.EventHandler() repeatedly to receive updates on the transfer status and number of bytes transferred on various endpoints. Refer to Figure Sequence of Operations with Endpoint Policy Changes for details.

A few messages have an associated payload that is returned in the supplied buffer. The following table describes various messages and their payload:

<table>
<thead>
<tr>
<th>Message</th>
<th>Payload</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EfiUsbMsgSetupPacket</td>
<td>EFI_USB_DEVICE_REQUEST</td>
<td>SETUP packet was received.</td>
</tr>
<tr>
<td>EfiUsbMsgEndpointStatusChangedRx</td>
<td>EFI_USBFN_TRANSFER_RESULT</td>
<td>Some of the requested data has been transmitted to the host. It is the responsibility of the class driver to determine if any remaining data needs to be re-sent. The Buffer supplied to EFI_USBFN_IO_PROTOCOL.Transfer() must be same as the Buffer field of the payload.</td>
</tr>
</tbody>
</table>

continues on next page
#### Table 17.33 – continued from previous page

| EfiUsbMsgEndpointStatusChangedTx | EFI_USBFN_TRANSFER_RESULT | Some of the requested data has been received from the host. It is the responsibility of the class driver to determine if it needs to wait for any remaining data. The Buffer supplied to EFI_USBFN_IO_PROTOCOL.Transfer() must be same as the Buffer field of the payload. |
| EfiUsbMsgBusEventReset | None | A RESET bus event was signaled. |
| EfiUsbMsgBusEventDetach | None | A DETACH bus event was signaled. |
| EfiUsbMsgBusEventAttach | None | An ATTACH bus event was signaled. |
| EfiUsbMsgBusEventSuspend | None | A SUSPEND bus event was signaled. |
| EfiUsbMsgBusEventResume | None | A RESUME bus event was signaled. |
| EfiUsbMsgBusEventSpeed | EFI_USB_BUS_SPEED | A Bus speed update was signaled. |

#### Status Codes Returned

| EFI_SUCCESS | The function returned successfully. |
| EFI_INVALID_PARAMETER | A parameter is invalid. |
| EFI_DEVICE_ERROR | The physical device reported an error. |
| EFI_NOT_READY | The physical device is busy or not ready to process this request. |
| EFI_BUFFER_TOO_SMALL | The Supplied buffer is not large enough to hold the message payload. |

#### Related Definitions

```c
typedef enum _EFI_USBFN_MESSAGE {
    //
    // Nothing
    //
    EfiUsbMsgNone = 0,
    //
    // SETUP packet is received, returned Buffer contains
    // EFI_USB_DEVICE_REQUEST struct
    //
    EfiUsbMsgSetupPacket,
    //
    // Indicates that some of the requested data has been
    // received from the host. It is the responsibility of the
    // class driver to determine if it needs to wait for any
    // remaining data. Returned Buffer contains
    // EFI_USBFN_TRANSFER_RESULT struct containing endpoint
    // number, transfer status and count of bytes received.
    //
    EfiUsbMsgEndpointStatusChangedRx,

(continues on next page)```
// Indicates that some of the requested data has been
// transmitted to the host. It is the responsibility of the
// class driver to determine if any remaining data needs to be
// resent. Returned Buffer contains
// EFI_USBFN_TRANSFER_RESULT struct containing endpoint
// number, transfer status and count of bytes sent.
// EfiUsbMsgEndpointStatusChangedTx,

// DETACH bus event signaled
// EfiUsbMsgBusEventDetach,
// ATTACH bus event signaled
// EfiUsbMsgBusEventAttach,
// RESET bus event signaled
// EfiUsbMsgBusEventReset,
// SUSPEND bus event signaled
// EfiUsbMsgBusEventSuspend,
// RESUME bus event signaled
// EfiUsbMsgBusEventResume,
// Bus speed updated, returned buffer indicated bus speed
// using following enumeration named EFI_USB_BUS_SPEED
// EfiUsbMsgBusEventSpeed
} EFI_USBFN_MESSAGE;

typedef enum _EFI_USBFN_TRANSFER_STATUS {
    UsbTransferStatusUnknown = 0,
    UsbTransferStatusComplete,
    UsbTransferStatusAborted,
    UsbTransferStatusActive,
    UsbTransferStatusNone
} EFI_USBFN_TRANSFER_STATUS;

typedef struct _EFI_USBFN_TRANSFER_RESULT {
    UINTN BytesTransferred;
    EFI_USBFN_TRANSFER_STATUS TransferStatus;
    UINT8 EndpointIndex;
    EFI_USBFN_ENDPOINT_DIRECTION Direction;
    VOID *Buffer;
} EFI_USBFN_TRANSFER_RESULT;
typedef enum _EFI_USB_BUS_SPEED {
    UsbBusSpeedUnknown = 0,
    UsbBusSpeedLow,
    UsbBusSpeedFull,
    UsbBusSpeedHigh,
    UsbBusSpeedSuper,
    UsbBusSpeedMaximum = UsbBusSpeedSuper
} EFI_USB_BUS_SPEED;

typedef union _EFI_USBFN_MESSAGE_PAYLOAD {
    EFI_USB_DEVICE_REQUEST udr;
    EFI_USBFN_TRANSFER_RESULT utr;
    EFI_USB_BUS_SPEED ubs;
} EFI_USBFN_MESSAGE_PAYLOAD;

17.3.11 EFI_USBFN_IO_PROTOCOL.Transfer()

Summary
This function handles transferring data to or from the host on the specified endpoint, depending on the direction specified.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_USBFN_IO_TRANSFER) (IN EFI_USBFN_IO_PROTOCOL *This,
IN UINT8 EndpointIndex,
IN EFI_USBFN_ENDPOINT_DIRECTION Direction,
IN OUT UINTN *BufferSize,
IN OUT VOID *Buffer);

Parameters

This
A pointer to the EFI_USBFN_IO_PROTOCOL instance.

EndpointIndex
Indicates the endpoint on which TX or RX transfer needs to take place.

Direction
Direction of the endpoint. Refer to the Related Definitions of the EFI_USBFN_IO_PROTOCOL.ABORTTRANSFER() function for details.

BufferSize
If Direction is EfiUsbEndpointDirectionDeviceRx: On input, the size of the Buffer in bytes. On output, the amount of data returned in Buffer in bytes.

If Direction is EfiUsbEndpointDirectionDeviceTx: On input, the size of the Buffer in bytes. On output, the amount of data transmitted in bytes.

Buffer
If Direction is EfiUsbEndpointDirectionDeviceRx: The Buffer to return the received data.
If *Direction* is EfiUsbEndpointDirectionDeviceTx: The Buffer that contains the data to be transmitted.

**Note:** This buffer is allocated and freed using the *EFI_USBFN_IO_PROTOCOL.AbortTransfer()* and *
EFI_USBFN_IO_PROTOCOL.FreeTransferBuffer()* functions. The caller of this function must not free or reuse
the buffer until EfiUsbMsgEndpointStatusChangedRx or EfiUsbMsgEndpointStatusChangedTx message was received
along with the address of the transfer buffer as part of the message payload. Refer to the function definition for
*EFI_USBFN_IO_PROTOCOL.EventHandler()* for more information on various messages and their payloads.

**Description**

This function handles transferring data to or from the host on the specified endpoint, depending on the direction spec-
ified.

<table>
<thead>
<tr>
<th>Direction</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EfiUsbEndpointDirectionDeviceTx</td>
<td>Start a transmit transfer on the specified endpoint and return immediately.</td>
</tr>
<tr>
<td>EfiUsbEndpointDirectionDeviceRx</td>
<td>Start a receive transfer on the specified endpoint and return immediately with available data.</td>
</tr>
</tbody>
</table>

A class driver must call *EFI_USBFN_IO_PROTOCOL.EventHandler()* repeatedly to receive updates on the trans-
fer status and the number of bytes transferred on various endpoints. Upon an update of the transfer status,
the *Buffer* field of the *EFI_USBFN_TRANSFER_RESULT* structure (as described in the function description for
*EFI_USBFN_IO_PROTOCOL.EventHandler()* must be initialized with the *Buffer* pointer that was supplied to this
method.

The overview of the call sequence is illustrated in Figure *Sequence of Operations with Endpoint Policy Changes.*

This function should fail with *EFI_INVALID_PARAMETER* if the specified direction is incorrect for the endpoint.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The physical device is busy or not ready to process this request.</td>
</tr>
</tbody>
</table>

**17.3.12 EFI_USBFN_IO_PROTOCOL.GetMaxTransferSize()**

**Summary**

Returns the maximum supported transfer size.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI * EFI_USBFN_IO_GET_MAXTRANSFER_SIZE) (  
  IN EFI_USBFN_IO_PROTOCOL *This,
  OUT UINTN *MaxTransferSize  
);
```

**Parameters**
This
A pointer to the `EFI_USBFN_IO_PROTOCOL` instance.

MaxTransferSize
The maximum supported transfer size, in bytes.

Description
Returns the maximum number of bytes that the underlying controller can accommodate in a single transfer.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The physical device is busy or not ready to process this request.</td>
</tr>
</tbody>
</table>

17.3.13 `EFI_USBFN_IO_PROTOCOL.AllocateTransferBuffer()`

Summary
Allocates a transfer buffer of the specified size that satisfies the controller requirements.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI * EFI_USBFN_IO_ALLOCATE_TRANSFER_BUFFER) (  
    IN EFI_USBFN_IO_PROTOCOL *This,
    IN UINTN Size,
    OUT VOID **Buffer
);
```

Parameters

This
A pointer to the `EFI_USBFN_IO_PROTOCOL` instance.

Size
The number of bytes to allocate for the transfer buffer.

Buffer
A pointer to a pointer to the allocated buffer if the call succeeds; undefined otherwise.

Description
The `AllocateTransferBuffer()` function allocates a memory region of `Size` bytes and returns the address of the allocated memory that satisfies the underlying controller requirements in the location referenced by `Buffer`.

The allocated transfer buffer must be freed using a matching call `EFI_USBFN_IO_PROTOCOL.FreeTransferBuffer()` function.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The requested transfer buffer could not be allocated.</td>
</tr>
</tbody>
</table>

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17.3.14 EFI_USBFN_IO_PROTOCOL.FreeTransferBuffer()

Summary
Deallocates the memory allocated for the transfer buffer by the EFI_USBFN_IO_PROTOCOL.AllocateTransferBuffer() function.

Prototype

```c
typedef EFI_STATUS
(EFIAPI * EFI_USBFN_IO_FREE_TRANSFER_BUFFER) (
    IN EFI_USBFN_IO_PROTOCOL *This,
    IN VOID *Buffer
);
```

Parameters

This
A pointer to the EFI_USBFN_IO_PROTOCOL instance.

Buffer
A pointer to the transfer buffer to deallocate.

Description
The EFI_USBFN_IO_PROTOCOL.FreeTransferBuffer() function deallocates the memory specified by Buffer. The Buffer that is freed must have been allocated by EFI_USBFN_IO_PROTOCOL.AllocateTransferBuffer().

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
</tbody>
</table>

17.3.15 EFI_USBFN_IO_PROTOCOL.StartController()

Summary
This function supplies power to the USB controller if needed and initializes the hardware and the internal data structures. The port must not be activated by this function.

Prototype

```c
typedef EFI_STATUS
(EFIAPI * EFI_USBFN_IO_START_CONTROLLER) (
    IN EFI_USBFN_IO_PROTOCOL *This
);
```

Parameters

This
A pointer to the EFI_USBFN_IO_PROTOCOL instance.

Description
This function starts the hardware by supplying power to the USB controller if needed, and initializing the hardware and internal data structures. The port must not be activated by this function.
Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
</tbody>
</table>

17.3.16 EFI_USBFN_IO_PROTOCOL.StopController()

Summary
This function stops the USB hardware device.

Prototype

typedef EFI_STATUS
(EIFIAPIT * EFI_USBFN_IO_STOP_CONTROLLER) (    
    IN EFI_USBFN_IO_PROTOCOL *This
);

Parameters
This
A pointer to the EFI_USBFN_IO_PROTOCOL instance.

17.3.16.1 Description
This function stops the USB hardware device.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
</tbody>
</table>

17.3.17 EFI_USBFN_IO_PROTOCOL.SetEndpointPolicy()

Summary
This function sets the configuration policy for the specified non-control endpoint. Refer to the description for calling restrictions.

Prototype

typedef EFI_STATUS
(EIFIAPIT * EFI_USBFN_SET_ENDPOINT_POLICY) (    
    IN EFI_USBFN_IO_PROTOCOL *This,    
    IN UINT8 EndpointIndex,    
    IN EFI_USBFN_ENDPOINT_DIRECTION Direction,    
    IN EFI_USBFN_POLICY_TYPE PolicyType,    
    IN UINTN BufferSize,
);

(continues on next page)
Parameters

This

A pointer to the `EFI_USBFN_IO_PROTOCOL` instance.

EndpointIndex

Indicates the non-control endpoint for which the policy needs to be set.

Direction

Direction of the endpoint. Refer to the Related Definitions for the `EFI_USBFN_IO_PROTOCOL.AbortTransfer()` function for details.

PolicyType

Policy type the user is trying to set for the specified non-control endpoint. Refer to Related Definitions for this function below for details.

BufferSize

The size of the `Buffer` in bytes.

Buffer

The new value for the policy parameter that `PolicyType` specifies. Refer to Related Definitions for this function below for details.

Description

This function sets the configuration policy for the specified non-control endpoint. This function can only be called before `EFI_USBFN_IO_PROTOCOL.StartController()` or after `EFI_USBFN_IO_PROTOCOL.StopController()` has been called.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Changing this policy value is not supported.</td>
</tr>
</tbody>
</table>

Related Definitions

typedef enum _EFI_USBFN_POLICY_TYPE
{
    EfiUsbPolicyUndefined = 0,
    EfiUsbPolicyMaxTransactionSize,
    EfiUsbPolicyZeroLengthTerminationSupport,
    EfiUsbPolicyZeroLengthTermination
} EFI_USBFN_POLICY_TYPE;

EfiUsbPolicyUndefined

Invalid policy value that must never be used across driver boundary. If used, the function must not return a success status code.

EfiUsbPolicyMaxTransactionSize

EfiUsbPolicyMaxTransactionSize is only used with `EFI_USBFN_IO_PROTOCOL.GETENDPOINTPOLICY()`. It provides the size of the largest single transaction (delivery of service to an endpoint) supported by a

17.3. USB Function Protocol
controller. It must be greater than or equal to the maximum transfer size that can be retrieved by calling `EFI_USBFN_IO_PROTOCOL.GETMAXTRANSFERSIZE()`.

<table>
<thead>
<tr>
<th>GetEndpointPolicy</th>
<th>SetEndpointPolicy</th>
</tr>
</thead>
<tbody>
<tr>
<td>BufferSize</td>
<td>4 bytes, sizeof(UINT32)</td>
</tr>
<tr>
<td>Return Status</td>
<td>EFI_STATUS</td>
</tr>
</tbody>
</table>

**EfiUsbPolicyZeroLengthTerminationSupport**

EfiUsbPolicyZeroLengthTerminationSupport is only used with XXX `EFI_USBFN_IO_PROTOCOL.GETENDPOINTPOLICY()` . It is **TRUE** if the USB controller is capable of automatically handling zero length packets when the transfer size is a multiple of USB maximum packet size and **FALSE** if it is not supported by the controller.

<table>
<thead>
<tr>
<th>GetEndpointPolicy</th>
<th>SetEndpointPolicy</th>
</tr>
</thead>
<tbody>
<tr>
<td>BufferSize</td>
<td>1 byte, sizeof(BOOLEAN)</td>
</tr>
<tr>
<td>Return Status</td>
<td>EFI_STATUS</td>
</tr>
</tbody>
</table>

**EfiUsbPolicyZeroLengthTermination**

When used with `EFI_USBFN_IO_PROTOCOL.GETENDPOINTPOLICY()` , a **TRUE** value is returned if the USB controller hardware is configured to automatically handle zero length packets when the transfer size is a multiple of USB maximum packet size; a **FALSE** value is returned if the controller hardware is not configured to do this.

Using `EFI_USBFN_IO_PROTOCOL.SETENDPOINTPOLICY()` to set the EfiUsbPolicyZeroLengthTermination policy is only applicable to USB controller hardware capable of supporting automatic zero length packet termination. When this value is set to **TRUE**, the controller must be configured to handle zero length termination for the specified endpoint. When this value is set to **FALSE**, the controller must be configured to not handle zero length termination for the specified endpoint.

The USB controller’s default policy must not enable automatic zero length packet termination, even if the hardware is capable of supporting it.

<table>
<thead>
<tr>
<th>GetEndpointPolicy</th>
<th>SetEndpointPolicy</th>
</tr>
</thead>
<tbody>
<tr>
<td>BufferSize</td>
<td>1 byte, sizeof(BOOLEAN)</td>
</tr>
<tr>
<td>Return Status</td>
<td>EFI_STATUS</td>
</tr>
</tbody>
</table>

17.3. USB Function Protocol
17.3.18 EFI_USBFN_IO_PROTOCOL.GetEndpointPolicy()

Summary
This function retrieves the configuration policy for the specified non-control endpoint. There are no associated calling restrictions for this function.

Prototype

```c
typedef EFI_STATUS
(EIFIAPI * EFI_USBFN_GET_ENDPOINT_POLICY) (   
    IN EFI_USBFN_IO_PROTOCOL *This,
    IN UINT8 EndpointIndex
    IN EFI_USBFN_ENDPOINT_DIRECTION Direction,
    IN EFI_USBFN_POLICY_TYPE PolicyType,
    IN OUT UINTN *BufferSize,
    IN OUT VOID *Buffer
);
```

Parameters

This
A pointer to the EFI_USBFN_IO_PROTOCOL instance.

EndpointIndex
Indicates the non-control endpoint for which the policy needs to be set.

Direction
Direction of the endpoint. Refer to the Related Definitions for the EFI_USBFN_IO_PROTOCOL.Aborttransfer() function for details.

PolicyType
Policy type the user is trying to retrieve for the specified non-control endpoint. Refer to the Related Definitions for the EFI_USBFN_IO_PROTOCOL.Setendpointpolicy() function for details.

BufferSize
On input, the size of Buffer in bytes. On output, the amount of data returned in Buffer in bytes.

Buffer
A pointer to a buffer to return requested endpoint policy value. Refer to the Related Definitions for the EFI_USBFN_IO_PROTOCOL.SetEndpointPolicy() function for size requirements of various policy types.

Description
This function retrieves the configuration policy for the specified non-control endpoint. This function has no calling restrictions.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>A parameter is invalid.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The physical device reported an error.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The specified policy value is not supported.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>Supplied buffer is not large enough to hold requested policy value.</td>
</tr>
</tbody>
</table>
17.3.19 USB Function Sequence Diagram
Fig. 17.3: Sequence of Operations with Endpoint Policy Changes

17.3. USB Function Protocol
PROTOCOLS — DEBUGGER SUPPORT

This chapter describes a minimal set of protocols and associated data structures necessary to enable the creation of source level debuggers for EFI. It does not fully define a debugger design. Using the services described in this document, it should also be possible to implement a variety of debugger solutions.

18.1 Overview

Efficient UEFI driver and application development requires the availability of source level debugging facilities. Although completely on-target debuggers are clearly possible, UEFI debuggers are generally expected to be remotely hosted. That is to say, the debugger itself will be split between two machines, which are the host and target. A majority of debugger code runs on the host that is typically responsible for disassembly, symbol management, source display, and user interface. Similarly, a smaller piece of code runs on the target that establishes the communication to the host and proxies requests from the host. The on-target code is known as the “debug agent.”

The debug agent design is subdivided further into two parts, which are the processor/platform abstraction and the debugger host specific communication grammar. This specification describes architectural interfaces for the former only. Specific implementations for various debugger host communication grammars can be created that make use of the facilities described in this specification.

The processor/platform abstraction is presented as a pair of protocol interfaces, which are the Debug Support protocol and the Debug Port protocol.

The Debug Support protocol abstracts the processor’s debugging facilities, namely a mechanism to manage the processor’s context via caller-installable exception handlers.

The Debug Port protocol abstracts the device that is used for communication between the host and target. Typically this will be a 16550 serial port, 1394 device, or other device that is nominally a serial stream.

Furthermore, a table driven, quiescent, memory-only mechanism for determining the base address of PE32+ images is provided to enable the debugger host to determine where images are located in memory.

Aside from timing differences that occur because of running code associated with the debug agent and user initiated changes to the machine context, the operation of the on-target debugger component must be transparent to the rest of the system. In addition, no portion of the debug agent that runs in interrupt context may make any calls to EFI services or other protocol interfaces.

The services described in this document do not comprise a complete debugger, rather they provide a minimal abstraction required to implement a wide variety of debugger solutions.
18.2 EFI Debug Support Protocol

This section defines the EFI Debug Support protocol which is used by the debug agent.

18.2.1 EFI Debug Support Protocol Overview

The debug-agent needs to be able to gain control of the machine when certain types of events occur; i.e., breakpoints, processor exceptions, etc. Additionally, the debug agent must also be able to periodically gain control during operation of the machine to check for asynchronous commands from the host. The EFI Debug Support protocol services enable these capabilities.

The EFI Debug Support protocol interfaces produce callback registration mechanisms which are used by the debug agent to register functions that are invoked either periodically or when specific processor exceptions. When they are invoked by the Debug Support driver, these callback functions are passed the current machine context record. The debug agent may modify this context record to change the machine context which is restored to the machine after the callback function returns. The debug agent does not run in the same context as the rest of UEFI and all modifications to the machine context are deferred until after the callback function returns.

It is expected that there will typically be two instances of the EFI Debug Support protocol in the system. One associated with the native processor instruction set (IA-32, x64, ARM, RISC-V, or Itanium processor family), and one for the EFI virtual machine that implements EFI byte code (EBC).

While multiple instances of the EFI Debug Support protocol are expected, there must never be more than one for any given instruction set.

18.2.2 EFI_DEBUG_SUPPORT_PROTOCOL

Summary

This protocol provides the services to allow the debug agent to register callback functions that are called either periodically or when specific processor exceptions occur.

GUID

```c
#define EFI_DEBUG_SUPPORT_PROTOCOL_GUID \
{0x2755590C,0x6F3C,0x42FA,\ 
{0x9E,0xA4,0xA3,0xBA,0x54,0x3C,0xDA,0x25}}
```

Protocol Interface Structure

```c
typedef struct {
    EFI_INSTRUCTION_SET_ARCHITECTURE Isa;
    EFI_GET_MAXIMUM_PROCESSOR_INDEX GetMaximumProcessorIndex;
    EFI_REGISTER_PERIODIC_CALLBACK RegisterPeriodicCallback;
    EFI_REGISTER_EXCEPTION_CALLBACK RegisterExceptionCallback;
    EFI_INVALIDATE_INSTRUCTION_CACHE InvalidateInstructionCache;
} EFI_DEBUG_SUPPORT_PROTOCOL;
```

Parameters

Isa

Declares the processor architecture for this instance of the EFI Debug Support protocol.

GetMaximumProcessorIndex

Returns the maximum processor index value that may be used with
RegisterPeriodicCallback
Registers a callback function that will be invoked periodically and asynchronously to the execution of EFI. See the RegisterPeriodicCallback() function description.

RegisterExceptionCallback
Registers a callback function that will be called each time the specified processor exception occurs. See the RegisterExceptionCallback() function description.

InvalidateInstructionCache
Invalidates the instruction cache of the processor. This is required by processor architectures where instruction and data caches are not coherent when instructions in the code under debug has been modified by the debug agent. See the InvalidateInstructionCache() function description.

Related Definitions
Refer to the Microsoft PE/COFF Specification revision 6.2 or later for IMAGE_FILE_MACHINE definitions.

Note: At the time of publication of this specification, the latest revision of the PE/COFF specification was 6.2. The definition of IMAGE_FILE_MACHINE_EBC is not included in revision 6.2 of the PE/COFF specification. It will be added in a future revision of the PE/COFF specification.

```c
// Machine type definition
typedef enum {
    IsaIa32 = IMAGE_FILE_MACHINE_I386, // 0x014C
    IsaX64 = IMAGE_FILE_MACHINE_X64, // 0x8664
    IsaIpf = IMAGE_FILE_MACHINE_IA64, // 0x0200
    IsaEbc = IMAGE_FILE_MACHINE_EBC,  // 0x0EBC
    IsaArm = IMAGE_FILE_MACHINE_ARMTHUMB_MIXED // 0x1C2
    IsaAarch64 = IMAGE_FILE_MACHINE_AARCH64 // 0xAA64
    IsaRISCV32 = IMAGE_FILE_MACHINE_RISCV32 // 0x5032
    IsaRISCV64 = IMAGE_FILE_MACHINE_RISCV64 // 0x5064
    IsaRISCV128 = IMAGE_FILE_MACHINE_RISCV128 // 0x5128
} EFI_INSTRUCTION_SET_ARCHITECTURE;
```

Description
The EFI Debug Support protocol provides the interfaces required to register debug agent callback functions and to manage the processor’s instruction stream as required. Registered callback functions are invoked in interrupt context when the specified event occurs.

The driver that produces the EFI Debug Support protocol is also responsible for saving the machine context prior to invoking a registered callback function and restoring it after the callback function returns prior to returning to the code under debug. If the debug agent has modified the context record, the modified context must be used in the restore operation.

Furthermore, if the debug agent modifies any of the code under debug (to set a software breakpoint for example), it must call the InvalidateInstructionCache() function for the region of memory that has been modified.
18.2.3 EFI_DEBUG_SUPPORT_PROTOCOL.GetMaximumProcessorIndex()

Summary

Returns the maximum value that may be used for the ProcessorIndex parameter in EFI_DEBUG_SUPPORT_PROTOCOL.REGISTERPERIODICCALLBACK() and EFI_DEBUG_SUPPORT_PROTOCOL.REGISTEREXCEPTIONCALLBACK().

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_GET_MAXIMUM_PROCESSOR_INDEX) (
    IN EFI_DEBUG_SUPPORT_PROTOCOL *This,
    OUT UINTN *MaxProcessorIndex
);
```

Parameters

**This**

A pointer to the EFI_DEBUG_SUPPORT_PROTOCOL instance. Type EFI_DEBUG_SUPPORT_PROTOCOL is defined in this section.

**MaxProcessorIndex**

Pointer to a caller-allocated UINTN in which the maximum supported processor index is returned.

Description

The GetMaximumProcessorIndex() function returns the maximum processor index in the output parameter MaxProcessorIndex. This value is the largest value that may be used in the ProcessorIndex parameter for both RegisterPeriodicCallback() and RegisterExceptionCallback(). All values between 0 and MaxProcessorIndex must be supported by RegisterPeriodicCallback() and RegisterExceptionCallback().

It is the responsibility of the caller to insure all parameters are correct. There is no provision for parameter checking by GetMaximumProcessorIndex(). The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
</tbody>
</table>

18.2.4 EFI_DEBUG_SUPPORT_PROTOCOL.RegisterPeriodicCallback()

Summary

Registers a function to be called back periodically in interrupt context.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_REGISTER_PERIODIC_CALLBACK) (
    IN EFI_DEBUG_SUPPORT_PROTOCOL *This,
    IN UINTN ProcessorIndex,
    IN EFI_PERIODIC_CALLBACK PeriodicCallback
);
```

Parameters

**This**

A pointer to the EFI_DEBUG_SUPPORT_PROTOCOL instance. Type EFI_DEBUG_SUPPORT_PROTOCOL is defined in this section.

**ProcessorIndex**

Processor index to be used for the callback.

**PeriodicCallback**

Function to be called periodically in interrupt context.
This
A pointer to the EFI_DEBUG_SUPPORT_PROTOCOL instance. Type EFI_DEBUG_SUPPORT_PROTOCOL
is defined in EFI_DEBUG_SUPPORT_PROTOCOL.

ProcessorIndex
Specifies which processor the callback function applies to.

PeriodicCallback
A pointer to a function of type PERIODIC_CALLBACK that is the main periodic entry point of the debug agent.
It receives as a parameter a pointer to the full context of the interrupted execution thread.

Related Definitions

typedef
VOID (*EFI_PERIODIC_CALLBACK) (  
IN OUT EFI_SYSTEM_CONTEXT SystemContext
);

// Universal EFI_SYSTEM_CONTEXT definition
typedef union {
  EFI_SYSTEM_CONTEXT_EBC      *SystemContextEbc;
  EFI_SYSTEM_CONTEXT_IA32     *SystemContextIa32;
  EFI_SYSTEM_CONTEXT_X64      *SystemContextX64;
  EFI_SYSTEM_CONTEXT_IPF      *SystemContextIpf;
  EFI_SYSTEM_CONTEXT_ARM      *SystemContextArm;
  EFI_SYSTEM_CONTEXT_ARM64    *SystemContextIA64;
  EFI_SYSTEM_CONTEXT_IPF      *SystemContextIpf;
  EFI_SYSTEM_CONTEXT_IPF      *SystemContextIpf;
  EFI_SYSTEM_CONTEXT_RISCV32  *SystemContextRiscV32;
  EFI_SYSTEM_CONTEXT_RISCV64  *SystemContextRiscV64;
  EFI_SYSTEM_CONTEXT_RISCV128 *SystemContextRiscv128;
} EFI_SYSTEM_CONTEXT;

// System context for virtual EBC processors
typedef struct {
  UINT64          R0, R1, R2, R3, R4, R5, R6, R7;
  UINT64          Flags;
  UINT64          ControlFlags;
  UINT64          Ip;
} EFI_SYSTEM_CONTEXT_EBC;

// System context for RISC-V 32
typedef struct {
  // Integer registers
  UINT32         Zero, Ra, Sp, Gp, Tp, T0, T1, T2;
  UINT32         S0FP, S1, A0, A1, A2, A3, A4, A5, A6, A7;
  UINT32         S2, S3, S4, S5, S6, S7, S8, S9, S10, S11;
  UINT32         T3, T4, T5, T6;

  // Floating registers for F, D and Q Standard Extensions
  UINT128        Ft0, Ft1, Ft2, Ft3, Ft4, Ft5, Ft6, Ft7;
  UINT128        Fs0, Fs1, Fa0, Fa1, Fa2, Fa3, Fa4, Fa5, Fa6, Fa7;
  UINT128        Fs2, Fs3, Fs4, Fs5, Fs6, Fs7, Fs8, Fs9, Fs10, Fs11;
  UINT128        Ft8, Ft9, Ft10, Ft11;
} EFI_SYSTEM_CONTEXT_RISCV32;

(continues on next page)
typedef struct {
  // Integer registers
  UINT64 Zero, Ra, Sp, Gp, Tp, T0, T1, T2;
  UINT64 S0FP, S1, A0, A1, A2, A3, A4, A5, A6, A7;
  UINT64 S2, S3, S4, S5, S6, S7, S8, S9, S10, S11;
  UINT64 T3, T4, T5, T6;
  // Floating registers for F, D and Q Standard Extensions
  UINT128 Ft0, Ft1, Ft2, Ft3, Ft4, Ft5, Ft6, Ft7;
  UINT128 Fs0, Fs1, Fa0, Fa1, Fa2, Fa3, Fa4, Fa5, Fa6, Fa7;
  UINT128 Fs2, Fs3, Fs4, Fs5, Fs6, Fs7, Fs8, Fs9, Fs10, Fs11;
  UINT128 Ft8, Ft9, Ft10, Ft11;
} EFI_SYSTEM_CONTEXT_RISCV64;

typedef struct {
  // Integer registers
  UINT128 Zero, Ra, Sp, Gp, Tp, T0, T1, T2;
  UINT128 S0FP, S1, A0, A1, A2, A3, A4, A5, A6, A7;
  UINT128 S2, S3, S4, S5, S6, S7, S8, S9, S10, S11;
  UINT128 T3, T4, T5, T6;
  // Floating registers for F, D and Q Standard Extensions
  UINT128 Ft0, Ft1, Ft2, Ft3, Ft4, Ft5, Ft6, Ft7;
  UINT128 Fs0, Fs1, Fa0, Fa1, Fa2, Fa3, Fa4, Fa5, Fa6, Fa7;
  UINT128 Fs2, Fs3, Fs4, Fs5, Fs6, Fs7, Fs8, Fs9, Fs10, Fs11;
  UINT128 Ft8, Ft9, Ft10, Ft11;
} EFI_SYSTEM_CONTEXT_RISCV128;

Note: When the context record field is larger than the register being stored in it, the upper bits of the context record field are unused and ignored.
// FXSAVE_STATE - FP / MMX / XMM registers
typedef struct {
    UINT16 Fcw;
    UINT16 Fsw;
    UINT16 Ftw;
    UINT16 Opcode;
    UINT32 Eip;
    UINT16 Cs;
    UINT16 Reserved1;
    UINT32 DataOffset;
    UINT16 Ds;
    UINT8  St0Mm0[10];
    UINT8  St1Mm1[10], Reserved3[6];
    UINT8  St2Mm2[10], Reserved5[6];
    UINT8  St3Mm3[10], Reserved6[6];
    UINT8  St4Mm4[10], Reserved7[6];
    UINT8  St5Mm5[10], Reserved8[6];
    UINT8  St6Mm6[10], Reserved9[6];
    UINT8  St7Mm7[10], Reserved10[6];
    UINT8  Xmm0[16];
    UINT8  Xmm1[16];
    UINT8  Xmm2[16];
    UINT8  Xmm3[16];
    UINT8  Xmm4[16];
    UINT8  Xmm5[16];
    UINT8  Xmm6[16];
    UINT8  Xmm7[16];
    UINT8  Reserved11[14 * 16];
} EFI_FX_SAVE_STATE_IA32;

// System context for x64 processors
typedef struct {
    UINT64 ExceptionData; // ExceptionData is
    // additional data pushed
    // on the stack by some
    // types of x64 64-bit
    // mode exceptions
    EFI_FX_SAVE_STATE_X64 FxSaveState;
    UINT64  Dr0, Dr1, Dr2, Dr3, Dr6, Dr7;
    UINT64  Cr0, Cr1 /* Reserved */ , Cr2, Cr3, Cr4, Cr8;
    UINT64  Rflags;
    UINT64  Ldtr, Tr;
    UINT64  Gdtr[2], Idtr[2];
    UINT64  Rip;
    UINT64  Gs, Fs, Es, Ds, Cs, Ss;
    UINT64  Rdi, Rsi, Rbp, Rsp, Rbx, Rdx, Rcx, Rax;
    UINT64  R8, R9, R10, R11, R12, R13, R14, R15;
} EFI_SYSTEM_CONTEXT_X64;
// FXSAVE_STATE - FP / MMX / XMM registers
typedef struct {
    UINT16 Fcw;
    UINT16 Fsw;
    UINT16 Ftw;
    UINT16 Opcode;
    UINT64 Rip;
    UINT64 DataOffset;
    UINT8 Reserved1[8];
    UINT8 St0Mm0[10], Reserved2[6];
    UINT8 St1Mm1[10], Reserved3[6];
    UINT8 St2Mm2[10], Reserved4[6];
    UINT8 St3Mm3[10], Reserved5[6];
    UINT8 St4Mm4[10], Reserved6[6];
    UINT8 St5Mm5[10], Reserved7[6];
    UINT8 St6Mm6[10], Reserved8[6];
    UINT8 St7Mm7[10], Reserved9[6];
    UINT8 Xmm0[16];
    UINT8 Xmm1[16];
    UINT8 Xmm2[16];
    UINT8 Xmm3[16];
    UINT8 Xmm4[16];
    UINT8 Xmm5[16];
    UINT8 Xmm6[16];
    UINT8 Xmm7[16];
    UINT8 Reserved11[14 * 16];
} EFI_FX_SAVE_STATE_X64;

// System context for Itanium processor family
typedef struct {
    UINT64 R1, R2, R3, R4, R5, R6, R7, R8, R9, R10,
        R11, R12, R13, R14, R15, R16, R17, R18, R19, R20,
        R21, R22, R23, R24, R25, R26, R27, R28, R29, R30,
        R31;
    UINT64 R1[2], R2[2], R3[2], R4[2], R5[2], R6[2],
        F7[2], F8[2], F9[2], F10[2], F11[2],
        F12[2], F13[2], F14[2], F15[2], F16[2],
        F17[2], F18[2], F19[2], F20[2], F21[2],
        F22[2], F23[2], F24[2], F25[2], F26[2],
        F27[2], F28[2], F29[2], F30[2], F31[2];
    UINT64 Pr;
    UINT64 B0, B1, B2, B3, B4, B5, B6, B7;

    // application registers
    UINT64 ArRsc, ArBsp, ArBspstore, ArRnat;
    UINT64 ArFcr;
    UINT64 ArEflag, ArCsd, ArSsd, ArCflg;
} EFI_SYSTEM_CONTEXT_X64;
UINT64 ArFsr, ArFir, ArFdr;
UINT64 ArCcv;
UINT64 ArUnat;
UINT64 ArFpsr;
UINT64 ArPfs, ArLc, ArEc;

// control registers
UINT64 CrDcr, CrItm, CrIva, CrPta, CrIpsr, CrIsr;
UINT64 CrIip, CrIfa, CrItir, CrIipa, CrIfs, CrIim;
UINT64 CrIha;

// debug registers
UINT64 Dbr0, Dbr1, Dbr2, Dbr3, Dbr4, Dbr5, Dbr6, Dbr7;
UINT64 Ibr0, Ibr1, Ibr2, Ibr3, Ibr4, Ibr5, Ibr6, Ibr7;

// virtual registers
UINT64 IntNat; // nat bits for R1-R31

} EFI_SYSTEM_CONTEXT_IPF;

//
// ARM processor context definition
//
typedef struct {
    UINT32 R0;
    UINT32 R1;
    UINT32 R2;
    UINT32 R3;
    UINT32 R4;
    UINT32 R5;
    UINT32 R6;
    UINT32 R7;
    UINT32 R8;
    UINT32 R9;
    UINT32 R10;
    UINT32 R11;
    UINT32 R12;
    UINT32 SP;
    UINT32 LR;
    UINT32 PC;
    UINT32 CPSR;
    UINT32 DFSR;
    UINT32 DFAR;
    UINT32 IFSR;
} EFI_SYSTEM_CONTEXT_ARM;

///
/// AARCH64 processor context definition.
///
typedef struct {
    // General Purpose Registers

UINT64 X0;
UINT64 X1;
UINT64 X2;
UINT64 X3;
UINT64 X4;
UINT64 X5;
UINT64 X6;
UINT64 X7;
UINT64 X8;
UINT64 X9;
UINT64 X10;
UINT64 X11;
UINT64 X12;
UINT64 X13;
UINT64 X14;
UINT64 X15;
UINT64 X16;
UINT64 X17;
UINT64 X18;
UINT64 X19;
UINT64 X20;
UINT64 X21;
UINT64 X22;
UINT64 X23;
UINT64 X24;
UINT64 X25;
UINT64 X26;
UINT64 X27;
UINT64 FP; // x29 - Frame Pointer
UINT64 LR; // x30 - Link Register
UINT64 SP; // x31 - Stack Pointer
    // FP/SIMD Registers
UINT64 V0[2];
UINT64 V1[2];
UINT64 V2[2];
UINT64 V3[2];
UINT64 V4[2];
UINT64 V5[2];
UINT64 V6[2];
UINT64 V7[2];
UINT64 V8[2];
UINT64 V9[2];
UINT64 V10[2];
UINT64 V11[2];
UINT64 V12[2];
UINT64 V13[2];
UINT64 V14[2];
UINT64 V15[2];
UINT64 V16[2];
UINT64 V17[2];
UINT64 V18[2];
Description

The `RegisterPeriodicCallback()` function registers and enables the on-target debug agent’s periodic entry point. To unregister and disable calling the debug agent’s periodic entry point, call `RegisterPeriodicCallback()` passing a NULL `PeriodicCallback` parameter.

The implementation must handle saving and restoring the processor context to/from the system context record around calls to the registered callback function.

If the interrupt is also used by the firmware for the EFI time base or some other use, two rules must be observed. First, the registered callback function must be called before any EFI processing takes place. Second, the Debug Support implementation must perform the necessary steps to pass control to the firmware’s corresponding interrupt handler in a transparent manner.

There is no quality of service requirement or specification regarding the frequency of calls to the registered `PeriodicCallback` function. This allows the implementation to mitigate a potential adverse impact to EFI timer based services due to the latency induced by the context save/restore and the associated callback function.

It is the responsibility of the caller to insure all parameters are correct. There is no provision for parameter checking by `RegisterPeriodicCallback()`. The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>Non-NULL <code>PeriodicCallback</code> parameter when a callback function was previously registered.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>System has insufficient memory resources to register new callback function.</td>
</tr>
</tbody>
</table>

18.2. EFI Debug Support Protocol
18.2.5 EFI_DEBUG_SUPPORT_PROTOCOL.RegisterExceptionCallback()

Summary
Registers a function to be called when a given processor exception occurs.

Prototype

```c
typedef EFI_STATUS (EFIAPI *REGISTER_EXCEPTION_CALLBACK) ( 
    IN EFI_DEBUG_SUPPORT_PROTOCOL *This, 
    IN UINTN ProcessorIndex, 
    IN EFI_EXCEPTION_CALLBACK ExceptionCallback, 
    IN EFI_EXCEPTION_TYPE ExceptionType 
);
```

Parameters

**This**
A pointer to the EFI_DEBUG_SUPPORT_PROTOCOL instance. Type EFI_DEBUG_SUPPORT_PROTOCOL is defined in EFI_DEBUG_SUPPORT_PROTOCOL.

**ProcessorIndex**
Specifies which processor the callback function applies to.

**ExceptionCallback**
A pointer to a function of type EXCEPTION_CALLBACK* that is called when the processor exception specified by ExceptionType occurs. Passing NULL unregisters any previously registered function associated with ExceptionType.

**ExceptionType**
Specifies which processor exception to hook.

Related Definitions

```c
typedef VOID (*EFI_EXCEPTION_CALLBACK) ( 
    IN EFI_EXCEPTION_TYPE ExceptionType, 
    IN OUT EFI_SYSTEM_CONTEXT SystemContext 
);

typedef INTN EFI_EXCEPTION_TYPE;

// EBC Exception types
#define EXCEPT_EBC_UNDEFINED 0
#define EXCEPT_EBC_DIVIDE_ERROR 1
#define EXCEPT_EBC_DEBUG 2
#define EXCEPT_EBC_BREAKPOINT 3
#define EXCEPT_EBC_OVERFLOW 4
#define EXCEPT_EBC_INVALID_OPCODE 5
#define EXCEPT_EBC_STACK_FAULT 6
#define EXCEPT_EBC_ALIGNMENT_CHECK 7
#define EXCEPT_EBC_INSTRUCTION_ENCODING 8
#define EXCEPT_EBC_BAD_BREAK 9
#define EXCEPT_EBC_SINGLE_STEP 10
```

(continues on next page)
### IA-32 Exception types

```
#define EXCEPT_IA32_DIVIDE_ERROR 0
#define EXCEPT_IA32_DEBUG 1
#define EXCEPT_IA32_NMI 2
#define EXCEPT_IA32_BREAKPOINT 3
#define EXCEPT_IA32_OVERFLOW 4
#define EXCEPT_IA32_BOUND 5
#define EXCEPT_IA32_INVALID_OPCODE 6
#define EXCEPT_IA32_DOUBLE_FAULT 8
#define EXCEPT_IA32_INVALID_TSS 10
#define EXCEPT_IA32_SEG_NOT_PRESENT 11
#define EXCEPT_IA32_STACK_FAULT 12
#define EXCEPT_IA32_GP_FAULT 13
#define EXCEPT_IA32_PAGE_FAULT 14
#define EXCEPT_IA32_FP_ERROR 16
#define EXCEPT_IA32_ALIGNMENT_CHECK 17
#define EXCEPT_IA32_MACHINE_CHECK 18
#define EXCEPT_IA32_SIMD 19
```

### X64 Exception types

```
#define EXCEPT_X64_DIVIDE_ERROR 0
#define EXCEPT_X64_DEBUG 1
#define EXCEPT_X64_NMI 2
#define EXCEPT_X64_BREAKPOINT 3
#define EXCEPT_X64_OVERFLOW 4
#define EXCEPT_X64_BOUND 5
#define EXCEPT_X64_INVALID_OPCODE 6
#define EXCEPT_X64_DOUBLE_FAULT 8
#define EXCEPT_X64_INVALID_TSS 10
#define EXCEPT_X64_SEG_NOT_PRESENT 11
#define EXCEPT_X64_STACK_FAULT 12
#define EXCEPT_X64_GP_FAULT 13
#define EXCEPT_X64_PAGE_FAULT 14
#define EXCEPT_X64_FP_ERROR 16
#define EXCEPT_X64_ALIGNMENT_CHECK 17
#define EXCEPT_X64_MACHINE_CHECK 18
#define EXCEPT_X64_SIMD 19
```

### Itanium Processor Family Exception types

```
#define EXCEPT_IPF_VHTP_TRANSLATION 0
#define EXCEPT_IPF_INSTRUCTION_TLB 1
#define EXCEPT_IPF_DATA_TLB 2
#define EXCEPT_IPF_ALT_INSTRUCTION_TLB 3
#define EXCEPT_IPF_ALT_DATA_TLB 4
#define EXCEPT_IPF_DATA_NESTED_TLB 5
#define EXCEPT_IPF_INSTRUCTION_KEY_MISSED 6
#define EXCEPT_IPF_DATA_KEY_MISSED 7
#define EXCEPT_IPF_DIRTY_BIT 8
#define EXCEPT_IPF_INSTRUCTION_ACCESS_BIT 9
#define EXCEPT_IPF_DATA_ACCESS_BIT 10
```

(continues on next page)
#define EXCEPT_IPF_BREAKPOINT 11
#define EXCEPT_IPF_EXTERNAL_INTERRUPT 12
// 13 - 19 reserved
#define EXCEPT_IPF_PAGE_NOT_PRESENT 20
#define EXCEPT_IPF_KEY_PERMISSION 21
#define EXCEPT_IPF_INSTRUCTION_ACCESS_RIGHTS 22
#define EXCEPT_IPF_DATA_ACCESS_RIGHTS 23
#define EXCEPT_IPF_GENERAL_EXCEPTION 24
#define EXCEPT_IPF_DISABLED_FP_REGISTER 25
#define EXCEPT_IPF_NAT_CONSUMPTION 26
#define EXCEPT_IPF_SPECULATION 27
// 28 reserved
#define EXCEPT_IPF_DEBUG 29
#define EXCEPT_IPF_UNALIGNED_REFERENCE 30
#define EXCEPT_IPF_UNSUPPORTED_DATA_REFERENCE 31
#define EXCEPT_IPF_FP_FAULT 32
#define EXCEPT_IPF_FP_TRAP 33
#define EXCEPT_IPF_LOWER_PRIVILEGE_TRANSFER_TRAP 34
#define EXCEPT_IPF_TAKEN_BRANCH 35
#define EXCEPT_IPF_SINGLE_STEP 36
// 37 - 44 reserved
#define EXCEPT_IPF_IA32_EXCEPTION 45
#define EXCEPT_IPF_IA32_INTERCEPT 46
#define EXCEPT_IPF_IA32_INTERRUPT 47

// ARM processor exception types
#define EXCEPT_ARM_RESET 0
#define EXCEPT_ARM_UNDEFINED_INSTRUCTION 1
#define EXCEPT_ARM_SOFTWARE_INTERRUPT 2
#define EXCEPT_ARM_PREFETCH_ABORT 3
#define EXCEPT_ARM_DATA_ABORT 4
#define EXCEPT_ARM_RESERVED 5
#define EXCEPT_ARM_IRQ 6
#define EXCEPT_ARM_FIQ 7

// For coding convenience, define the maximum valid ARM exception.
#define MAX_ARM_EXCEPTION EXCEPT_ARM_FIQ

/// AARCH64 processor exception types.
///
#define EXCEPT_AARCH64_SYNCHRONOUS_EXCEPTIONS 0
#define EXCEPT_AARCH64_IRQ 1
#define EXCEPT_AARCH64_FIQ 2
#define EXCEPT_AARCH64_SERROR 3

/// For coding convenience, define the maximum valid AARCH64 exception.
///
```c
#define MAX_AARCH64_EXCEPTION EXCEPT_AARCH64_SERROR

///
/// RISC-V processor exception types.
///
#define EXCEPT_RISCV_INST_MISALIGNED 0
#define EXCEPT_RISCV_INST_ACCESS_FAULT 1
#define EXCEPT_RISCV_ILLEGAL_INST 2
#define EXCEPT_RISCV_BREAKPOINT 3
#define EXCEPT_RISCV_LOAD_ADDRESS_MISALIGNED 4
#define EXCEPT_RISCV_LOAD_ACCESS_FAULT 5
#define EXCEPT_RISCV_STORE_AMO_ADDRESS_MISALIGNED 6
#define EXCEPT_RISCV_STORE_AMO_ACCESS_FAULT 7
#define EXCEPT_RISCV_ENV_CALL_FROM_UMODE 8
#define EXCEPT_RISCV_ENV_CALL_FROM_SMODE 9
#define EXCEPT_RISCV_ENV_CALL_FROM_MMODE 11
#define EXCEPT_RISCV_INST_PAGE_FAULT 12
#define EXCEPT_RISCV_LOAD_PAGE_FAULT 13
#define EXCEPT_RISCV_STORE_AMO_PAGE_FAULT 15

///
/// RISC-V processor interrupt types.
///
#define EXCEPT_RISCV_SUPERVISOR_SOFTWARE_INT 1
#define EXCEPT_RISCV_MACHINE_SOFTWARE_INT 3
#define EXCEPT_RISCV_SUPERVISOR_TIMER_INT 5
#define EXCEPT_RISCV_MACHINE_TIMER_INT 7
#define EXCEPT_RISCV_SUPERVISOR_EXTERNAL_INT 9
#define EXCEPT_RISCV_MACHINE_EXTERNAL_INT 11
```

**Description**

The `RegisterExceptionCallback()` function registers and enables an exception callback function for the specified exception. The specified exception must be valid for the instruction set architecture. To unregister the callback function and stop servicing the exception, call `RegisterExceptionCallback()` passing a `NULL ExceptionCallback` parameter.

The implementation must handle saving and restoring the processor context to/from the system context record around calls to the registered callback function. No chaining of exception handlers is allowed.

It is the responsibility of the caller to insure all parameters are correct. There is no provision for parameter checking by `RegisterExceptionCallback()`. The implementation behavior when an invalid parameter is passed is not defined by this specification.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>Non-<code>NULL</code> ExceptionCallback parameter when a callback function was previously registered.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>System has insufficient memory resources to register new callback function.</td>
</tr>
</tbody>
</table>
18.2.6 EFI_DEBUG_SUPPORT_PROTOCOL.InvalidateInstructionCache()

Summary
Invalidates processor instruction cache for a memory range. Subsequent execution in this range causes a fresh memory fetch to retrieve code to be executed.

Prototype

```c
typedef EFI_STATUS
( EFIAPICALLCONVENTION EFI_INVALIDATE_INSTRUCTION_CACHE) ( 
  IN EFI_DEBUG_SUPPORT_PROTOCOL *This, 
  IN UINTN ProcessorIndex, 
  IN VOID *Start, 
  IN UINT64 Length 
);
```

Parameters

This
A pointer to the EFI_DEBUG_SUPPORT_PROTOCOL instance. Type EFI_DEBUG_SUPPORT_PROTOCOL is defined in EFI_DEBUG_SUPPORT_PROTOCOL.

ProcessorIndex
Specifies which processor’s instruction cache is to be invalidated.

Start
Specifies the physical base of the memory range to be invalidated.

Length
Specifies the minimum number of bytes in the processor’s instruction cache to invalidate.

Description

Typical operation of a debugger may require modifying the code image that is under debug. This can occur for many reasons, but is typically done to insert/remove software break instructions. Some processor architectures do not have coherent instruction and data caches so modifications to the code image require that the instruction cache be explicitly invalidated in that memory region.

The InvalidateInstructionCache() function abstracts this operation from the debug agent and provides a general purpose capability to invalidate the processor’s instruction cache.

It is the responsibility of the caller to insure all parameters are correct. There is no provision for parameter checking by EFI_DEBUG_SUPPORT_PROTOCOL.REGISTEREXCEPTIONCALLBACK(). The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
</tbody>
</table>
18.3 EFI Debugport Protocol

This section defines the EFI Debugport protocol. This protocol is used by debug agent to communicate with the remote debug host.

18.3.1 EFI Debugport Overview

Historically, remote debugging has typically been done using a standard UART serial port to connect the host and target. This is obviously not possible in a legacy reduced system that does not have a UART. The Debugport protocol solves this problem by providing an abstraction that can support many different types of debugport hardware. The debug agent should use this abstraction to communicate with the host.

The interface is minimal with only reset, read, write, and poll abstractions. Since these functions are called in interrupt context, none of them may call any EFI services or other protocol interfaces.

Debugport selection and configuration is handled by setting defaults via an environment variable which contains a full device path to the debug port. This environment variable is used during the debugport driver’s initialization to configure the debugport correctly. The variable contains a full device path to the debugport, with the last node (prior to the terminal node) being a debugport messaging node. See Debugport Device Path for details.

The driver must also produce an instance of the EFI Device Path protocol to indicate what hardware is being used for the debugport. This may be used by the OS to maintain the debugport across a call to EFI_BOOT_SERVICES.ExitBootServices().

18.3.2 EFI_DEBUGPORT_PROTOCOL

Summary

This protocol provides the communication link between the debug agent and the remote host.

GUID

```
#define EFI_DEBUGPORT_PROTOCOL_GUID \
{0xEBA4E8D2,0x3858,0x41EC,\ 
 {0xA2,0x81,0x26,0x47,0xBA,0x96,0x60,0xD0}}
```

Protocol Interface Structure

```
typedef struct {
    EFI_DEBUGPORT_RESET Reset;
    EFI_DEBUGPORT_WRITE Write;
    EFI_DEBUGPORT_READ Read;
    EFI_DEBUGPORT_POLL Poll;
} EFI_DEBUGPORT_PROTOCOL;
```

Parameters

Reset
Resets the debugport hardware.

Write
Send a buffer of characters to the debugport device.

Read
Receive a buffer of characters from the debugport device.
Poll
Determine if there is any data available to be read from the debugport device.

Description
The Debugport protocol is used for byte stream communication with a debugport device. The debugport can be a standard UART Serial port, a USB-based character device, or potentially any character-based I/O device.

The attributes for all UART-style debugport device interfaces are defined in the DEBUGPORT variable (Debugport Device Path).

18.3.3 EFI_DEBUGPORT_PROTOCOL.Reset()

Summary
Resets the debugport.

Prototype

typedef
EFI_STATUS
(EIFIAPIC EFI_DEBUGPORT_RESET) (   
  IN EFI_DEBUGPORT_PROTOCOL *This   
);

Parameters
This
A pointer to the EFI_DEBUGPORT_PROTOCOL instance. Type EFI_DEBUGPORT_PROTOCOL is defined in EFI_DEBUGPORT_PROTOCOL.

Description
The Reset() function resets the debugport device.

It is the responsibility of the caller to insure all parameters are valid. There is no provision for parameter checking by Reset(). The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The debugport device was reset and is in usable state.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The debugport device could not be reset and is unusable.</td>
</tr>
</tbody>
</table>

18.3.4 EFI_DEBUGPORT_PROTOCOL.Write()

Summary
Writes data to the debugport.

Prototype

typedef
EFI_STATUS
(EIFIAPIC EFI_DEBUGPORT_WRITE) (   
  IN EFI_DEBUGPORT_PROTOCOL *This,   
  IN UINT32 Timeout,   
  IN OUT UINTN *BufferSize,   
);

(continues on next page)
Parameters

This
A pointer to the EFI_DEBUGPORT_PROTOCOL instance. Type EFI_DEBUGPORT_PROTOCOL is defined in EFI_DEBUGPORT_PROTOCOL.

Timeout
The number of microseconds to wait before timing out a write operation.

BufferSize
On input, the requested number of bytes of data to write. On output, the number of bytes of data actually written.

Buffer
A pointer to a buffer containing the data to write.

Description
The Write() function writes the specified number of bytes to a debugport device. If a timeout error occurs while data is being sent to the debugport, transmission of this buffer will terminate, and EFI_TIMEOUT will be returned. In all cases the number of bytes actually written to the debugport device is returned in BufferSize.

It is the responsibility of the caller to insure all parameters are valid. There is no provision for parameter checking by Write(). The implementation behavior when an invalid parameter is passed is not defined by this specification.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was written.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The device reported an error.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The data write was stopped due to a timeout.</td>
</tr>
</tbody>
</table>

18.3.5 EFI_DEBUGPORT_PROTOCOL.Read()

Summary
Reads data from the debugport.

Prototype

typedef
EFI_STATUS
(EFI_API *EFI_DEBUGPORT_READ) (  
  IN EFI_DEBUGPORT_PROTOCOL *This,  
  IN UINT32 Timeout,  
  IN OUT UINTN *BufferSize,  
  OUT VOID *Buffer  
);  

Parameters

This
A pointer to the EFI_DEBUGPORT_PROTOCOL instance. Type EFI_DEBUGPORT_PROTOCOL is defined in EFI_DEBUGPORT_PROTOCOL.
### Timeout
The number of microseconds to wait before timing out a read operation.

### BufferSize
A pointer to an integer which, on input contains the requested number of bytes of data to read, and on output contains the actual number of bytes of data read and returned in Buffer.

### Buffer
A pointer to a buffer into which the data read will be saved.

### Description
The `Read()` function reads a specified number of bytes from a debugport. If a timeout error or an overrun error is detected while data is being read from the debugport, then no more characters will be read, and `EFI_TIMEOUT` will be returned. In all cases the number of bytes actually read is returned in `*BufferSize`.

It is the responsibility of the caller to ensure all parameters are valid. There is no provision for parameter checking by `Read()`. The implementation behavior when an invalid parameter is passed is not defined by this specification.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was read.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The debugport device reported an error.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The operation was stopped due to a timeout or overrun.</td>
</tr>
</tbody>
</table>

### 18.3.6 EFI_DEBUGPORT_PROTOCOL.Poll()  

#### Summary
Checks to see if any data is available to be read from the debugport device.

#### Prototype
```c
typedef EFI_STATUS (EFIAPI *EFI_DEBUGPORT_POLL) ( 
    IN EFI_DEBUGPORT_PROTOCOL *This 
); 
```

#### Parameters

<table>
<thead>
<tr>
<th>This</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>*This</td>
<td>A pointer to the <code>EFI_DEBUGPORT_PROTOCOL</code> instance. Type <code>EFI_DEBUGPORT_PROTOCOL</code> is defined in <code>EFI_DEBUGPORT_PROTOCOL</code>.</td>
</tr>
</tbody>
</table>

#### Description
The `Poll()` function checks if there is any data available to be read from the debugport device and returns the result. No data is actually removed from the input stream. This function enables simpler debugger design since buffering of reads is not necessary by the caller.

#### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>At least one byte of data is available to be read.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>No data is available to be read.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The debugport device is not functioning correctly.</td>
</tr>
</tbody>
</table>
18.3.7 Debugport Device Path

The debugport driver must establish and maintain an instance of the EFI Device Path protocol for the debugport. A graceful handoff of debugport ownership between the EFI Debugport driver and an OS debugport driver requires that the OS debugport driver can determine the type, location, and configuration of the debugport device.

The Debugport Device Path is a vendor-defined messaging device path with no data, only a GUID. It is used at the end of a conventional device path to tag the device for use as the debugport. For example, a typical UART debugport would have the following fully qualified device path:

```
PciRoot(0)/Pci(0x1f,0)/ACPI(PNP0501,0)/UART(115200,N,8,1)/DebugPort()
```

The Vendor_GUID that defines the debugport device path is the same as the debugport protocol GUID, as defined below.

```
#define DEVICE_PATH_MESSAGING_DEBUGPORT EFI_DEBUGPORT_PROTOCOL_GUID
```

The Table below, Debugport Messaging Device Path, shows all fields of the debugport device path.

```
<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>1</td>
<td>Type 3 - Messaging Device Path.</td>
</tr>
<tr>
<td>Sub Type</td>
<td>1</td>
<td>1</td>
<td>Sub Type 10 - Vendor.</td>
</tr>
<tr>
<td>Length</td>
<td>2</td>
<td>2</td>
<td>Length of this structure in bytes. Length is 20 bytes.</td>
</tr>
<tr>
<td>Vendor_GUID</td>
<td>4</td>
<td>16</td>
<td>DEVICE_PATH_MESSAGING_DEBUGPORT.</td>
</tr>
</tbody>
</table>
```

18.3.8 EFI Debugport Variable

Even though there may be more than one hardware device that could function as a debugport in a system, only one debugport may be active at a time. The DEBUGPORT variable is used to declare which hardware device will act as the debugport, and what communication parameters it should assume.

Like all EFI variables, the DEBUGPORT variable has both a name and a GUID. The name is “DEBUGPORT.” The GUID is the same as the `EFI_DEBUGPORT_PROTOCOL_GUID`:

```
#define EFI_DEBUGPORT_VARIABLE_NAME L"DEBUGPORT"
#define EFI_DEBUGPORT_VARIABLE_GUID EFI_DEBUGPORT_PROTOCOL_GUID
```

The data contained by the DEBUGPORT variable is a fully qualified debugport device path (Debugport Device Path).

The desired communication parameters for the debugport are declared in the DEBUGPORT variable. The debugport driver must read this variable during initialization to determine how to configure the debug port.

To reduce the required complexity of the debugport driver, the debugport driver is not required to support all possible combinations of communication parameters. What combinations of parameters are possible is implementation specific.

Additionally debugport drivers implemented for PNP0501 devices, that is debugport devices with a PNP0501 ACPI node in the device path, must support the following defaults. These defaults must be used in the absence of a DEBUGPORT variable, or when the communication parameters specified in the DEBUGPORT variable are not supported by the driver.

- Baud : 115200
• 8 data bits
• No parity
• 1 stop bit
• No flow control (See Appendix A for flow control details)

In the absence of the DEBUGPORT variable, the selection of which port to use as the debug port is implementation specific.

Future revisions of this specification may define new defaults for other debugport types.

The debugport device path must be constructed to reflect the actual settings for the debugport. Any code needing to know the state of the debug port must reference the device path rather than the DEBUGPORT variable, since the debugport may have assumed a default setting in spite of the existence of the DEBUGPORT variable.

If it is not possible to configure the debug port using either the settings declared in the DEBUGPORT variable or the default settings for the particular debugport type, the driver initialization must not install any protocol interfaces and must exit with an error.

18.4 EFI Debug Support Table

This chapter defines the EFI Debug Support Table which is used by the debug agent or an external debugger to determine loaded image information in a quiescent manner.

18.4.1 Overview

Every executable image loaded in EFI is represented by an EFI handle populated with an instance of the EFI Loaded Image Protocol protocol. This handle is known as an “image handle.” The associated Loaded Image protocol provides image information that is of interest to a source level debugger. Normal EFI executables can access this information by using EFI services to locate all instances of the Loaded Image protocol.

A debugger has two problems with this scenario. First, if it is an external hardware debugger, the location of the EFI system table is not known. Second, even if the location of the EFI system table is known, the services contained therein are generally unavailable to a debugger either because it is an on-target debugger that is running in interrupt context, or in the case of an external hardware debugger there is no debugger code running on the target at all.

Since a source level debugger must be capable of determining image information for all loaded images, an alternate mechanism that does not use EFI services must be provided. Two features are added to the EFI system software to enable this capability.

First, an alternate mechanism of locating the EFI system table is required. A check-summed structure containing the physical address of the EFI system table is created and located on a 4M aligned memory address. A hardware debugger can search memory for this structure to determine the location of the EFI system table.

Second, an EFI_CONFIGURATION_TABLE is published that leads to a database of pointers to all instances of the Loaded Image protocol. Several layers of indirection are used to allow dynamically managing the data as images are loaded and unloaded. Once the address of the EFI system table is known, it is possible to discover a complete and accurate list of EFI images. (Note that the EFI core itself must be represented by an instance of the Loaded Image protocol.)

Debug Support Table Indirection and Pointer Usage illustrates the table indirection and pointer usage.
The EFI system table can be located by an off-target hardware debugger by searching for the `EFI_SYSTEM_TABLE_POINTER` structure. The `EFI_SYSTEM_TABLE_POINTER` structure is located on a 4M boundary as close to the top of physical memory as feasible. It may be found searching for the `EFI_SYSTEM_TABLE_SIGNATURE` on each 4M boundary starting at the top of memory and scanning down. When the signature is found, the entire structure must verified using the `Crc32` field. The 32-bit CRC of the entire structure is calculated assuming the `Crc32` field is zero. This value is then written to the `Crc32` field.

```c
typedef struct _EFI_SYSTEM_TABLE_POINTER {
    UINT64 Signature;
    EFI_PHYSICAL_ADDRESS EfiSystemTableBase;
    UINT32 Crc32;
} EFI_SYSTEM_TABLE_POINTER;
```

**Signature**
A constant UINT64 that has the value `EFI_SYSTEM_TABLE_SIGNATURE` (see the EFI 1.0 specification).

**EfiSystemTableBase**
The physical address of the EFI system table.

**Crc32**
A 32-bit CRC value that is used to verify the `EFI_SYSTEM_TABLE_POINTER` structure is valid.
18.4.3 EFI Image Info

The EFI_DEBUG_IMAGE_INFO_TABLE is an array of pointers to EFI_DEBUG_IMAGE_INFO unions. Each member of an EFI_DEBUG_IMAGE_INFO union is a pointer to a data structure representing a particular image type. For each image that has been loaded, there is an appropriate image data structure with a pointer to it stored in the EFI_DEBUG_IMAGE_INFO_TABLE. Data structures for normal images and SMM images are defined. All other image types are reserved for future use.

The process of locating the EFI_DEBUG_IMAGE_INFO_TABLE begins with an EFI configuration table.

```c
// EFI_DEBUG_IMAGE_INFO_TABLE configuration table
// GUID declaration - {49152E77-1ADA-4764-B7A2-7AFEDED95E8B}

#define EFI_DEBUG_IMAGE_INFO_TABLE_GUID
{0x49152E77,0x1ADA,0x4764,
 {0xB7,0xA2,0x7A,0xFE,0xFE,0xD9,0x5E,0x8B }}
```

The address reported in the EFI configuration table entry of this type will be referenced as physical and will not be fixed up when transition from preboot to runtime phase.

The configuration table leads to an EFI_DEBUG_IMAGE_INFO_TABLE_HEADER structure that contains a pointer to the EFI_DEBUG_IMAGE_INFO_TABLE and some status bits that are used to control access to the EFI_DEBUG_IMAGE_INFO_TABLE when it is being updated.

```c
// UpdateStatus bits
//
#define EFI_DEBUG_IMAGE_INFO_UPDATE_IN_PROGRESS 0x01
#define EFI_DEBUG_IMAGE_INFO_TABLE_MODIFIED 0x02

typedef struct {
 volatile UINT32 UpdateStatus;
 UINT32 TableSize;
 EFI_DEBUG_IMAGE_INFO *EfiDebugImageInfoTable;
} EFI_DEBUG_IMAGE_INFO_TABLE_HEADER;
```

**UpdateStatus**

UpdateStatus is used by the system to indicate the state of the debug image info table.

The EFI_DEBUG_IMAGE_INFO_UPDATE_IN_PROGRESS bit must be set when the table is being modified. Software consuming the table must qualify the access to the table with this bit.

The EFI_DEBUG_IMAGE_INFO_TABLE_MODIFIED bit is always set by software that modifies the table. It may be cleared by software that consumes the table once the entire table has been read. It is essentially a sticky version of the EFI_DEBUG_IMAGE_INFO_UPDATE_IN_PROGRESS bit and is intended to provide an efficient mechanism to minimize the number of times the table must be scanned by the consumer.

**TableSize**

The number of EFI_DEBUG_IMAGE_INFO elements in the array pointed to by EfiDebugImageInfoTable.

**EfiDebugImageInfoTable**

A pointer to the first element of an array of EFI_DEBUG_IMAGE_INFO structures.

```c
#define EFI_DEBUG_IMAGE_INFO_TYPE_NORMAL 0x01

typedef union {
```

(continues on next page)
 typedef struct {
    UINT32 *ImageInfoType;
    EFI_DEBUG_IMAGE_INFO *NormalImage;
} EFI_DEBUG_IMAGE_INFO;

typedef struct {
    UINT32 ImageInfoType;
    EFI_LOADED_IMAGE_PROTOCOL *LoadedImageProtocolInstance;
    EFI_HANDLE ImageHandle;
} EFI_DEBUG_IMAGE_INFO_NORMAL;

**ImageInfoType**
Indicates the type of image info structure. For PE32 EFI images, this is set to EFI_DEBUG_IMAGE_INFO_TYPE_NORMAL.

**LoadedImageProtocolInstance**
A pointer to an instance of the loaded image protocol for the associated image.

**ImageHandle**
Indicates the image handle of the associated image.
In EFI firmware storage, binary codes/data are often compressed to save storage space. These compressed codes/data are extracted into memory for execution at boot time. This demands an efficient lossless compression/decompression algorithm. The compressor must produce small compressed images, and the decompressor must operate fast enough to avoid delays at boot time.

This chapter describes in detail the UEFI compression/decompression algorithm, as well as the EFI Decompress Protocol. The EFI Decompress Protocol provides a standard decompression interface for use at boot time.

### 19.1 Algorithm Overview

In this chapter, the term “character” denotes a single byte and the term “string” denotes a series of concatenated characters.

The compression/decompression algorithm used in EFI firmware storage is a combination of the LZ77 algorithm and Huffman Coding. The LZ77 algorithm replaces a repeated string with a pointer to the previous occurrence of the string. Huffman Coding encodes symbols in a way that the more frequently a symbol appears in a text, the shorter the code that is assigned to it.

The compression process contains two steps:

- The first step is to find repeated strings (using LZ77 algorithm) and produce intermediate data.

  Beginning with the first character, the compressor scans the source data and determines if the characters starting at the current position can form a string previously appearing in the text. If a long enough matching string is found, the compressor will output a pointer to the string. If the pointer occupies more space than the string itself, the compressor will output the original character at the current position in the source data. Then the compressor advances to the next position and repeats the process. To speed up the compression process, the compressor dynamically maintains a String Info Log to record the positions and lengths of strings encountered, so that string comparisons are performed quickly by looking up the String Info Log.

Because a compressor cannot have unlimited resources, as the compression continues the compressor removes “old” string information. This prevents the String Info Log from becoming too large. As a result, the algorithm can only look up repeated strings within the range of a fixed-sized “sliding window” behind the current position.

In this way, a stream of intermediate data is produced which contains two types of symbols: the Original Characters (to be preserved in the decompressed data), and the Pointers (representing a previous string). A Pointer consists of two elements: the String Position and the String Length, representing the location and the length of the target string, respectively.

- To improve the compression ratio further, Huffman Coding is utilized as the second step.

  The intermediate data (consisting of original characters and pointers) is divided into Blocks so that the compressor can perform Huffman Coding on a Block immediately after it is generated; eliminating the need for a second pass from the beginning after the intermediate data has been generated. Also, since symbol frequency
distribution may differ in different parts of the intermediate data, Huffman Coding can be optimized for each specific Block. The compressor determines Block Size for each Block according to the specifications defined in Data Format.

In each Block, two symbol sets are defined for Huffman Coding. The Char&Len Set consists of the Original Characters plus the String Lengths and the Position Set consists of String Positions (Note that the two elements of a Pointer belong to separate symbol sets). The Huffman Coding schemes applied on these two symbol sets are independent.

The algorithm uses “canonical” Huffman Coding so a Huffman tree can be represented as an array of code lengths in the order of the symbols in the symbol set. This code length array represents the Huffman Coding scheme for the symbol set. Both the Char&Len Set code length array and the Position Set code length array appear in the Block Header.

Huffman coding is used on the code length array of the Char&Len Set to define a third symbol set. The Extra Set is defined based on the code length values in the Char&Len Set code length array. The code length array for the Huffman Coding of Extra Set also appears in the Block Header together with the other two code length arrays. For exact format of the Block Header, Block Header.

The decompression process is straightforward given that the compression process is known. The decompressor scans the compressed data and decodes the symbols one by one, according to the Huffman code mapping tables generated from code length arrays. Along the process, if it encounters an original character, it outputs it; if it encounters a pointer, it looks it up in the already decompressed data and outputs the associated string.

19.2 Data Format

This section describes in detail the format of the compressed data produced by the compressor. The compressed data serves as input to the decompressor and can be fully extracted to the original source data.

19.2.1 Bit Order

In computer data representation, a byte is the minimum unit and there is no differentiation in the order of bits within a byte. However, the compressed data is a sequence of bits rather than a sequence of bytes and as a result the order of bits in a byte needs to be defined. In a compressed data stream, the higher bits are defined to precede the lower bits in a byte. The Figure, below, Bit Sequence of Compressed Data illustrates a compressed data sequence written as bytes from left to right. For each byte, the bits are written in an order with bit 7 (the highest bit) at the left and bit 0 (the lowest bit) at the right. Concatenating the bytes from left to right forms a bit sequence.

![Bit Sequence of Compressed Data](image)

The bits of the compressed data are actually formed by a sequence of data units. These data units have variable bit lengths. The bits of each data unit are arranged so that the higher bit of the data unit precedes the lower bit of the data unit.
19.2.2 Overall Structure

The compressed data begins with two 32-bit numerical fields: the compressed size and the original size. The compressed data following these two fields is composed of one or more Blocks. Each Block is a unit for Huffman Coding with a coding scheme independent of the other Blocks. Each Block is composed of a Block Header containing the Huffman code trees for this Block and a Block Body with the data encoded using the coding scheme defined by the Huffman trees. The compressed data is terminated by an additional byte of zero.

The overall structure of the compressed data is shown in Compressed Data Structure.

<table>
<thead>
<tr>
<th>Compressed Size</th>
<th>Original Size</th>
<th>Block 0</th>
<th>Block 1</th>
<th>...</th>
<th>Block n</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>4 Bytes</td>
<td>4 Bytes</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Terminator 1 Byte

Fig. 19.2: Compressed Data Structure

Note the following:

- Blocks are of variable lengths.
- Block lengths are counted by bits and not necessarily divisible by 8. Blocks are tightly packed (there are no padding bits between blocks). Neither the starting position nor ending position of a Block is necessarily at a byte boundary. However, if the last Block is not terminated at a byte boundary, there should be some bits of 0 to fill up the remaining bits of the last byte of the block, before the terminator byte of 0.
- Compressed Size =
  Size in bytes of (Block 0 + Block 1 +… + Block N + Filling Bits (if any) + Terminator).
- Original Size is the size in bytes of original data.
- Both Compressed Size and Original Size are “little endian” (starting from the least significant byte).

19.2.3 Block Structure

A Block is composed of a Block Header and a Block Body, as shown in the figure below. These two parts are packed tightly (there are no padding bits between them). The lengths in bits of Block Header and Block Body are not necessarily divisible by eight.

Fig. 19.3: Block Structure
19.2.3.1 Block Header

The Block Header contains the Huffman encoding information for this block. Since “canonical” Huffman Coding is being used, a Huffman tree is represented as an array of code lengths in increasing order of the symbols in the symbol set. Code lengths are limited to be less than or equal to 16 bits. This requires some extra handling of Huffman codes in the compressor, which is described in Block Structure.

There are three code length arrays for three different symbol sets in the Block Header: one for the Extra Set, one for the Char&Len Set, and one for the Position Set.

The Block Header is composed of the tightly packed (no padding bits) fields described in the Table, below, Block Header Fields.

<table>
<thead>
<tr>
<th>Field Name</th>
<th>Length (bits)</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Block Size</td>
<td>16</td>
<td>The size of this Block. Block Size is defined as the number of original characters plus the number of pointers that appear in the Block Body:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Block Size = Number of Original Characters in the Block Body + Number of Pointers in the Block Body.</td>
</tr>
<tr>
<td>Extra Set Code Length</td>
<td>5</td>
<td>The number of code lengths in the Extra Set Code Length Array. The Extra Set Code Length Array contains code lengths of the Extra Set in</td>
</tr>
<tr>
<td>Array Size</td>
<td></td>
<td>increasing order of the symbols, and if all symbols greater than a certain symbol have zero code length, the Extra Set Code Length Array</td>
</tr>
<tr>
<td></td>
<td></td>
<td>terminates at the last nonzero code length symbol. Since there are 19 symbols in the Extra Set (see the description of the Char&amp;Len Set</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Code Length Array), the maximum Extra Set Code Length Array Size is 19.</td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>Extra Set Code Length Array</th>
<th>Variable</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>If Extra Set Code Length Array Size is 0, then this field is a 5-bit value that represents the only Huffman code used.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>If Extra Set Code Length Array Size is not 0, then this field is an encoded form of a concatenation of code lengths in increasing order of the symbols.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The concatenation of Code lengths are encoded as follows:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>If a code length is less than 7, then it is encoded as a 3-bit value;</td>
<td></td>
<td></td>
</tr>
<tr>
<td>If a code length is equal to or greater than 7, then it is encoded as a series of “1”s followed by a terminating “0.” The number of “1”s = Code length - 4. For example, code length “ten” is encoded as “1111110”; code length “seven” is encoded as “1110.”</td>
<td></td>
<td></td>
</tr>
<tr>
<td>After the third length of the code length concatenation, a 2-bit value is used to indicate the number of consecutive zero lengths immediately after the third length. (Note this 2-bit value only appears once after the third length, and does NOT appear multiple times after every 3rd length.)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>This 2-bit value ranges from 0 to 3. For example, if the 2-bit value is “00,” then it means there are no zero lengths at the point, and following encoding starts from the fourth code length;</td>
<td></td>
<td></td>
</tr>
<tr>
<td>if the 2-bit value is “10” then it means the fourth and fifth length are zero and following encoding starts from the sixth code length.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Position Set Code Length Array Size</td>
<td>4</td>
<td></td>
</tr>
<tr>
<td>The number of code lengths in the Position Set Code Length Array.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The Position Set Code Length Array contains code lengths of Position Set in increasing order of the symbols in the Position Set, and if all symbols greater than a certain symbol have zero code length, the Position Set Code Length Array terminates at the last nonzero code length symbol.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Since there are 14 symbols in the Position Set (see 3.3.2), the maximum Position Set Code Length Array Size is 14.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Char&Len Set Code Length Array | Variable |
--- | --- |
| | If Char&Len Set Code Length Array Size is 0, then this field is a 9-bit value that represents the only Huffman code used.

If Char&Len Set Code Length Array Size is not 0, then this field is an encoded form of a concatenation of code lengths in increasing order of the symbols. The concatenation of Code lengths are two-step encoded:

Step 1:

If a code length is not zero, then it is encoded as “code length + 2”;
If a code length is zero, then the number of consecutive zero lengths starting from this code length is counted —

- If the count is equal to or less than 2, then the code “0” is used for each zero length;
- if the count is greater than 2 and less than 19, then the code “1” followed by a 4-bit value of “count - 3” is used for these consecutive zero lengths;
- if the count is equal to 19, then it is treated as “1 + 18,” and a code “0” and a code “1” followed by a 4-bit value of “15” are used for these consecutive zero lengths;
- if the count is greater than 19, then the code “2” followed by a 9-bit value of “count - 20” is used for these consecutive zero lengths.

Step 2:

The second step encoding is a Huffman encoding of the codes produced by first step.

(While encoding codes “1” and “2,” their appended values are not encoded and preserved in the resulting text).

The code lengths of generated Huffman tree are just the contents of the Extra Set Code Length Array.

Position Set Code Length Array Size | 4 |
--- | --- |
| | The number of code lengths in the Position Set Code Length Array.

The Position Set Code Length Array contains code lengths of Position Set in increasing order of the symbols in the Position Set, and if all symbols greater than a certain symbol have zero code length, the Position Set Code Length Array terminates at the last nonzero code length symbol.

Since there are 14 symbols in the Position Set (see 3.3.2), the maximum Position Set Code Length Array Size is 14.

continues on next page
Table 19.1 – continued from previous page

<table>
<thead>
<tr>
<th>Position Set Code Length Array</th>
<th>Variable</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>If Position Set Code Length Array Size is 0, then this field is a 5-bit value that represents the only Huffman code used.</td>
</tr>
<tr>
<td></td>
<td>If Position Set Code Length Array Size is not 0, then this field is an encoded form of a concatenation of code lengths in increasing order of the symbols.</td>
</tr>
<tr>
<td></td>
<td>The concatenation of Code lengths are encoded as follows:</td>
</tr>
<tr>
<td></td>
<td>If a code length is less than 7, then it is encoded as a normal 3-bit value;</td>
</tr>
<tr>
<td></td>
<td>If a code length is equal to or greater than 7, then it is encoded as a series of “1”s followed by a terminating “0.” The number of “1”s = Code length - 4. For example, code length “10” is encoded as “1111110”; code length “7” is encoded as “1110.”</td>
</tr>
</tbody>
</table>

19.2.3.2 Block Body

The Block Body is simply a mixture of Original Characters and Pointers, while each Pointer has two elements: String Length preceding String Position. All these data units are tightly packed together.

![Block Body Diagram](image)

Fig. 19.4: Block Body

The Original Characters, String Lengths and String Positions are all Huffman coded using the Huffman trees presented in the Block Header, with some additional variations. The exact format is described below:

An Original Character is a byte in the source data. A String Length is a value that is greater than 3 and less than 257 (this range should be ensured by the compressor). By calculating “(String Length - 3) | 0x100,” a value set is obtained that ranges from 256 to 509. By combining this value set with the value set of Original Characters (0 ~ 255), the Char&Len Set (ranging from 0 to 509) is generated for Huffman Coding.

A String Position is a value that indicates the distance between the current position and the target string. The String Position value is defined as “Current Position - Starting Position of the target string - 1.” The String Position value ranges from 0 to 8190 (so 8192 is the “sliding window” size, and this range should be ensured by the compressor). The lengths of the String Position values (in binary form) form a value set ranging from 0 to 13 (it is assumed that value 0 has length of 0). This value set is the Position Set for Huffman Coding. The full representation of a String Position value is composed of two consecutive parts: one is the Huffman code for the value length; the other is the actual String Position value of “length - 1” bits (excluding the highest bit since the highest bit is always “1”). For example, String Position value 18 is represented as: Huffman code for “5” followed by “0010.” If the value length is 0 or 1, then no value is appended to the Huffman code. This kind of representation favors small String Position values, which is a hint for compressor design.
19.3 Compressor Design

The compressor takes the source data as input and produces a compressed image. This section describes the design used in one possible implementation of a compressor that follows the UEFI Compression Algorithm. The source code that illustrates an implementation of this specific design is listed in Appendix H.

19.3.1 Overall Process

The compressor scans the source data from the beginning, character by character. As the scanning proceeds, the compressor generates Original Characters or Pointers and outputs the compressed data packed in a series of Blocks representing individual Huffman coding units.

The compressor maintains a String Info Log containing data that facilitates string comparison. Old data items are deleted and new data items are inserted regularly.

The compressor does not output a Pointer immediately after it sees a matching string for the current position. Instead, it delays its decision until it gets the matching string for the next position. The compressor has two criteria at hand: one is that the former match length should be no shorter than three characters; the other is that the former match length should be no shorter than the latter match length.

Only when these two criteria are met does the compressor output a Pointer to the former matching string.

The overall process of compression can be described by following pseudo code:

```
Set the Current Position at the beginning of the source data;
Delete the outdated string info from the String Info Log;
Search the String Info Log for matching string;
Add the string info of the current position into the String Info Log;
WHILE not end of source data DO
    Remember the last match;
    Advance the Current Position by 1;
    Delete the outdated String Info from the String Info Log;
    Search the String Info Log for matching string;
    Add the string info of the current position into the String Info Log;
    IF the last match is shorter than 3 characters or this match is longer than the last match THEN
        Call Output() to output the character at the previous position as an Original Character;
    ELSE
        Call Output() to output a Pointer to the last matching string;
        WHILE (--last match length) > 0 DO
            Advance the Current Position by 1;
            Delete the outdated piece of string info from the String Info Log;
            Add the string info of the current position into the String Info Log;
        ENDFOR
    ENDIF
ENDWHILE

The Output() is the function that is responsible for generating Huffman codes and Blocks. It accepts an Original Character or a Pointer as input and maintains a Block Buffer to temporarily store data units that are to be Huffman coded. The following pseudo code describes the function:

```
FUNCTION NAME: Output
INPUT: an Original Character or a Pointer

(continues on next page)
Put the Original Character or the Pointer into the Block Buffer;
Advance the Block Buffer position pointer by 1;
IF the Block Buffer is full THEN
   Encode the Char&Len Set in the Block buffer;
   Encode the Position Set in the Block buffer;
   Encode the Extra Set;
   Output the Block Header containing the code length arrays;
   Output the Block Body containing the Huffman encoded Original Characters and Pointers;
   Reset the Block Buffer position pointer to point to the beginning of the Block buffer;
ENDIF

19.3.2 String Info Log

The provision of the String Info Log is to speed up the process of finding matching strings. The design of this has significant impact on the overall performance of the compressor. This section describes in detail how String Info Log is implemented and the typical operations on it.

19.3.2.1 Data Structures

The String Info Log is implemented as a set of search trees. These search trees are dynamically updated as the compression proceeds through the source data. The structure of a typical search tree is depicted in the Figure, below, String Info Log Search Tree.

There are three types of nodes in a search tree: the root node, internal nodes, and leaves. The root node has a “character” attribute, which represents the starting character of a string. Each edge also has a “character” attribute, which represents the next character in the string. Each internal node has a “level” attribute, which indicates the character on any edge that leads to its child nodes is the “level + 1”th character in the string. Each internal node or leaf has a “position” attribute that indicates the string’s starting position in the source data.

To speed up the tree searching, a hash function is used. Given the parent node and the edge-character, the hash function will quickly find the expected child node.

19.3.2.2 Searching the Tree

Traversing the search tree is performed as follows:

The following example uses the search tree shown in the Figure, above, String Info Log Search Tree. Assume that the current position in the source data contains the string “camxrsxpj...”

1. The starting character “c” is used to find the root of the tree. The next character “a” is used to follow the edge from node 1 to node 2. The “position” of node 2 is 500, so a string starting with “ca” can be found at position 500. The string at the current position is compared with the string starting at position 500.

2. Node 2 is at Level 3; so at most three characters are compared. Assume that the three-character comparison passes.

3. The fourth character “x” is used to follow the edge from Node 2 to Node 5. The position value of node 5 is 400, which means there is a string located in position 400 that starts with “cam” and the character at position 403 is an “x.”
Fig. 19.5: String Info Log Search Tree
4. Node 5 is at Level 8, so the fifth to eighth characters of the source data are compared with the string starting at position 404. Assume the strings match.

5. At this point, the ninth character “p” has been reached. It is used to follow the edge from Node 5 to Node 7.

6. This process continues until a mismatch occurs, or the length of the matching strings exceeds the predefined MAX_MATCH_LENGTH. The most recent matching string (which is also the longest) is the desired matching string.

19.3.2.3 Adding String Info

String info needs to be added to the String Info Log for each position in the source data. Each time a search for a matching string is performed, the new string info is inserted for the current position. There are several cases that can be discussed:

1. No root is found for the first character. A new tree is created with the root node labeled with the starting character and a child leaf node with its edge to the root node labeled with the second character in the string. The “position” value of the child node is set to the current position.

2. One root node matches the first character, but the second character does not match any edge extending from the root node. A new child leaf node is created with its edge labeled with the second character. The “position” value of the new leaf child node is set to the current position.

3. A string comparison succeeds with an internal node, but a matching edge for the next character does not exist. This is similar to (2) above. A new child leaf node is created with its edge labeled with the character that does not exist. The “position” value of the new leaf child node is set to the current position.

4. A string comparison exceeds MAX_MATCH_LENGTH. Note: This only happens with leaf nodes. For this case, the “position” value in the leaf node is updated with the current position.

5. If a string comparison with an internal node or leaf node fails (mismatch occurs before the “Level + 1”th character is reached or MAX_MATCH_LENGTH is exceeded), then a “split” operation is performed as follows:

Suppose a comparison is being performed with a level 9 Node, at position 350, and the current position is 1005. If the sixth character at position 350 is an “x” and the sixth character at position 1005 is a “y,” then a mismatch will occur. In this case, a new internal node and a new child node are inserted into the tree, as depicted in Node Split.

19.3.2.4 Deleting String Info

The String Info Log will grow as more and more string information is logged. The size of the String Info Log must be limited, so outdated information must be removed on a regular basis. A sliding window is maintained behind the current position, and the searches are always limited within the range of the sliding window. Each time the current position is advanced, outdated string information that falls outside the sliding window should be removed from the tree. The search for outdated string information is simplified by always updating the nodes’ “position” attribute when searching for matching strings.
The b) portion of *Node Split* has two new inserted nodes, which reflects the new string information that was found at the current position. The process splits the old node into two child nodes, and that is why this operation is called a "split."

Fig. 19.6: Node Split
19.3.3 Huffman Code Generation

Another major component of the compressor design is generation of the Huffman Code.

Huffman Coding is applied to the Char&Len Set, the Position Set, and the Extra Set. The Huffman Coding used here has the following features:

- The Huffman tree is represented as an array of code lengths (“canonical” Huffman Coding);
- The maximum code length is limited to 16 bits.

The Huffman code generation process can be divided into three steps. These are the generation of Huffman tree, the adjustment of code lengths, and the code generation.

19.3.3.1 Huffman Tree Generation

This process generates a typical Huffman tree. First, the frequency of each symbol is counted, and a list of nodes is generated with each node containing a symbol and the symbol’s frequency. The two nodes with the lowest frequency values are merged into a single node. This new node becomes the parent node of the two nodes that are merged. The frequency value of this new parent node is the sum of the two child nodes’ frequency values. The node list is updated to include the new parent node but exclude the two child nodes that are merged. This process is repeated until there is a single node remaining that is the root of the generated tree.

19.3.3.2 Code Length Adjustment

The leaf nodes of the tree generated by the previous step represent all the symbols that were generated. Traditionally the code for each symbol is found by traversing the tree from the root node to the leaf node. Going down a left edge generates a “0,” and going down a right edge generates a “1.” However, a different approach is used here. The number of codes of each code length is counted. This generates a 16-element LengthCount array, with LengthCount[i] = Number Of Codes whose Code Length is i. Since a code length may be longer than 16 bits, the sixteenth entry of the LengthCount array is set to the Number Of Codes whose Code Length is greater than or equal to 16.

The LengthCount array goes through further adjustment described by following code:

```
INT32 i, k;
UINT32 cum;

cum = 0;
for (i = 16; i > 0; i--) {
    cum += LengthCount[i] << (16 - i);
}
while (cum != (1U << 16)) {
    LengthCount[16]--;
    for (i = 15; i > 0; i--) {
        if (LengthCount[i] != 0) {
            LengthCount[i]--;
            LengthCount[i+1] += 2;
            break;
        }
    }
    cum--;
}
```
19.3.3.3 Code Generation

In the previous step, the count of each length was obtained. Now, each symbol is going to be assigned a code. First, the length of the code for each symbol is determined. Naturally, the code lengths are assigned in such a way that shorter codes are assigned to more frequently appearing symbols. A CodeLength array is generated with CodeLength[i] = the code length of symbol i. Given this array, a code is assigned to each symbol using the algorithm described by the pseudo code below (the resulting codes are stored in array Code such that Code[i] = the code assigned to symbol i):

```plaintext
INT32 i;
UINT16 Start[18];

Start[1] = 0;

for (i = 1; i <= 16; i++) {
    Start[i + 1] = (UINT16)((Start[i] + LengthCount[i]) << 1);
}

for (i = 0; i < NumberOfSymbols; i++) {
    Code[i] = Start[CodeLength[i]]++;
}
```

The code length adjustment process ensures that no code longer than the designated length will be generated. As long as the decompressor has the CodeLength array at hand, it can regenerate the codes.

19.4 Decompressor Design

The decompressor takes the compressed data as input and produces the original source data. The main tasks for the decompressor are decoding Huffman codes and restoring Pointers to the strings to which they point.

The following pseudo code describes the algorithm used in the design of a decompressor. The source code that illustrates an implementation of this design is listed in Appendix I.

```plaintext
WHILE not end of data DO
    IF at block boundary THEN
        Read in the Extra Set Code Length Array;
        Generate the Huffman code mapping table for the Extra Set;
        Read in and decode the Char&Len Set Code Length Array;
        Generate the Huffman code mapping table for the Char&Len Set;
        Read in the Position Set Code Length Array;
        Generate the Huffman code mapping table for the Position Set;
    ENDIF
    Get next code;
    Look the code up in the Char&Len Set code mapping table.
    Store the result as C;
    IF C < 256 (it represents an Original Character) THEN
        Output this character;
    ELSE (it represents a String Length)
        Transform C to be the actual String Length value;
        Get next code and look it up in the Position Set code mapping table, and
        with some additional transformation, store the result as P;
        Output C characters starting from the position "Current Position - P";
    ENDIF
ENDWHILE
```
19.5 Decompress Protocol

This section provides a detailed description of the \textit{EFI\_DECOMPRESS\_PROTOCOL}.

19.5.1 EFI\_DECOMPRESS\_PROTOCOL

Summary

Provides a decompression service.

GUID

\begin{verbatim}
#define EFI\_DECOMPRESS\_PROTOCOL\_GUID \ 
{0xd8117cfe,0x94a6,0x11d4,\ 
 {0x9a,0x3a,0x00,0x90,0x27,0x3f,0xc1,0x4d}}
\end{verbatim}

Protocol Interface Structure

\begin{verbatim}
typedef struct _EFI\_DECOMPRESS\_PROTOCOL {
      EFI\_DECOMPRESS\_GET\_INFO GetInfo;
      EFI\_DECOMPRESS\_DECOMPRESS Decompress;
  } EFI\_DECOMPRESS\_PROTOCOL;
\end{verbatim}

Parameters

GetInfo

Given the compressed source buffer, this function retrieves the size of the uncompressed destination buffer and the size of the scratch buffer required to perform the decompression. It is the caller’s responsibility to allocate the destination buffer and the scratch buffer prior to calling \textit{EFI\_DECOMPRESS\_PROTOCOL}(). See the \textit{EFI\_DECOMPRESS\_PROTOCOL.GetInfo()} function description.

Decompress

Decompresses a compressed source buffer into an uncompressed destination buffer. It is the caller’s responsibility to allocate the destination buffer and a scratch buffer prior to making this call. See the \textit{Decompress()} function description.

Description

The \textit{EFI\_DECOMPRESS\_PROTOCOL} provides a decompression service that allows a compressed source buffer in memory to be decompressed into a destination buffer in memory. It also requires a temporary scratch buffer to perform the decompression. The \textit{GetInfo()} function retrieves the size of the destination buffer and the size of the scratch buffer that the caller is required to allocate. The \textit{Decompress()} function performs the decompression. The scratch buffer can be freed after the decompression is complete.

19.5.2 EFI\_DECOMPRESS\_PROTOCOL.GetInfo()

Summary

Given a compressed source buffer, this function retrieves the size of the uncompressed buffer and the size of the scratch buffer required to decompress the compressed source buffer.

Prototype
typedef EFI_STATUS
(EFI_API *EFI_DECOMPRESS_GET_INFO) (
    IN EFI_DECOMPRESS_PROTOCOL *This,
    IN VOID *Source,
    IN UINT32 SourceSize,
    OUT UINT32 *DestinationSize,
    OUT UINT32 *ScratchSize);

Parameters

This
A pointer to the EFI_DECOMPRESS_PROTOCOL instance. Type EFI_DECOMPRESS_PROTOCOL is defined in EFI_DECOMPRESS_PROTOCOL.

Source
The source buffer containing the compressed data.

SourceSize
The size, in bytes, of the source buffer.

DestinationSize
A pointer to the size, in bytes, of the uncompressed buffer that will be generated when the compressed buffer specified by Source and SourceSize is decompressed.

ScratchSize
A pointer to the size, in bytes, of the scratch buffer that is required to decompress the compressed buffer specified by Source and SourceSize.

Description
The GetInfo() function retrieves the size of the uncompressed buffer and the temporary scratch buffer required to decompress the buffer specified by Source and SourceSize. If the size of the uncompressed buffer or the size of the scratch buffer cannot be determined from the compressed data specified by Source and SourceSize, then EFI_INVALID_PARAMETER is returned. Otherwise, the size of the uncompressed buffer is returned in DestinationSize, the size of the scratch buffer is returned in ScratchSize, and EFI_SUCCESS is returned.

The GetInfo() function does not have scratch buffer available to perform a thorough checking of the validity of the source data. It just retrieves the “Original Size” field from the beginning bytes of the source data and output it as DestinationSize. And ScratchSize is specific to the decompression implementation.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The size of the uncompressed data was returned in DestinationSize and the size of the scratch buffer was returned in ScratchSize.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The size of the uncompressed data or the size of the scratch buffer cannot be determined from the compressed data specified by Source and SourceSize.</td>
</tr>
</tbody>
</table>
19.5.3 EFI_DECOMPRESS_PROTOCOL.De compress()

Summary
Decompresses a compressed source buffer.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_DECOMPRESS_DECOMPRESS) (  
    IN EFI_DECOMPRESS_PROTOCOL *This,
    IN VOID *Source,
    IN UINT32 SourceSize,
    IN OUT VOID *Destination,
    IN UINT32 DestinationSize,
    IN OUT VOID *Scratch,
    IN UINT32 ScratchSize
);

Parameters

This
A pointer to the EFI_DECOMPRESS_PROTOCOL instance. Type EFI_DECOMPRESS_PROTOCOL is defined in EFI_DECOMPRESS_PROTOCOL.

Source
The source buffer containing the compressed data.

SourceSize
The size of source data.

Destination
On output, the destination buffer that contains the uncompressed data.

DestinationSize
The size of the destination buffer. The size of the destination buffer needed is obtained from EFI_DECOMPRESS_PROTOCOL.GetInfo().

Scratch
A temporary scratch buffer that is used to perform the decompression.

ScratchSize
The size of scratch buffer. The size of the scratch buffer needed is obtained from GetInfo().

Description
The Decompress() function extracts decompressed data to its original form.

This protocol is designed so that the decompression algorithm can be implemented without using any memory services. As a result, the Decompress() function is not allowed to call EFI_BOOT_SERVICES.AllocatePool() or EFI_BOOT_SERVICES.AllocatePages() in its implementation. It is the caller’s responsibility to allocate and free the Destination and Scratch buffers.

If the compressed source data specified by Source and SourceSize is successfully decompressed into Destination, then EFI_SUCCESS is returned. If the compressed source data specified by Source and SourceSize is not in a valid compressed data format, then EFI_INVALID_PARAMETER is returned.

Status Codes Returned
<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Decompression completed successfully, and the uncompressed buffer is returned in Destination.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The source buffer specified by Source and SourceSize is corrupted (not in a valid compressed format).</td>
</tr>
</tbody>
</table>

19.5. Decompress Protocol
20.1 EFI_ACPI_TABLE_PROTOCOL

Summary

This protocol may be used to install or remove an ACPI table from a platform.

GUID

```
#define EFI_ACPI_TABLE_PROTOCOL_GUID  \\  {0xffe06bdd, 0x6107, 0x46a6,  \\    {0x7b, 0xb2, 0x5a, 0x9c, 0x7e, 0xc5, 0x27, 0x5c}}
```

Protocol Interface Structure

```
typedef struct _EFI_ACPI_TABLE_PROTOCOL {
    EFI_ACPI_TABLE_INSTALL_ACPI_TABLE InstallAcpiTable;
    EFI_ACPI_TABLE_UNINSTALL_ACPI_TABLE UninstallAcpiTable;
} EFI_ACPI_TABLE_PROTOCOL;
```

Parameters

**InstallAcpiTable**
Installs an ACPI table into the system.

**UninstallAcpiTable**
Removes a previously installed ACPI table from the system.

Description

The `EFI_ACPI_TABLE_PROTOCOL` provides the ability for a component to install and uninstall ACPI tables from a platform.

20.2 EFI_ACPI_TABLE_PROTOCOL.InstallAcpiTable()

Summary

Installs an ACPI table into the RSDT/XSDT.

Prototype
```c
typedef EFI_STATUS
(EFIAPI *EFI_ACPI_TABLE_INSTALL_ACPI_TABLE) (
    IN EFI_ACPI_TABLE_PROTOCOL *This,
    IN VOID *AcpiTableBuffer,
    IN UINTN AcpiTableBufferSize,
    OUT UINTN *TableKey,
);
```

### Parameters

**This**
- A pointer to a `EFI_ACPI_TABLE_PROTOCOL`.

**AcpiTableBuffer**
- A pointer to a buffer containing the ACPI table to be installed.

**AcpiTableBufferSize**
- Specifies the size, in bytes, of the `AcpiTableBuffer` buffer.

**TableKey**
- Returns a key to refer to the ACPI table.

### Description

The `InstallAcpiTable()` function allows a caller to install an ACPI table. The ACPI table may either by a System Description Table or the FACS. For all tables except for the DSDT and FACS, a copy of the table will be linked by the RSDT/XSDT. For the FACS and DSDT, the pointer to a copy of the table will be updated in the FADT, if present.

To prevent namespace collision, ACPI tables may be created using UEFI ACPI table format, Appendix O — UEFI ACPI Data Table. If this protocol is used to install a table with a signature already present in the system, the new table will not replace the existing table. It is a platform implementation decision to add a new table with a signature matching an existing table or disallow duplicate table signatures and return `EFI_ACCESS_DENIED`.

On successful output, `TableKey` is initialized with a unique key. Its value may be used in a subsequent call to `UninstallAcpiTable` to remove an ACPI table.

On successful output, the `EFI_ACPI_TABLE_PROTOCOL` will ensure that the checksum field is correct for both the RSDT/XSDT table and the copy of the table being installed that is linked by the RSDT/XSDT.

On successful completion, this function reinstalls the relevant `EFI_CONFIGURATION_TABLE` pointer to the RSDT.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The table was successfully inserted</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>AcpiTableBuffer</code> is <code>NULL</code>, the <code>TableKey</code> is <code>NULL</code>; the <code>AcpiTableBufferSize</code> and the size field embedded in the ACPI table pointed to by <code>AcpiTableBuffer</code> are not in sync.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Insufficient resources exist to complete the request.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The table signature matches a table already present in the system and platform policy does not allow duplicate tables of this type.</td>
</tr>
</tbody>
</table>
20.3 EFI_ACPI_TABLE_PROTOCOL.UninstallAcpiTable()

Summary
Removes an ACPI table from the RSDT/XSDT.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_ACPI_TABLE_UNINSTALL_ACPI_TABLE) (  
    IN EFI_ACPI_TABLE_PROTOCOL *This,  
    IN UINTN TableKey,
);
```

Parameters

This
A pointer to a ` EFI_ACPI_TABLE_PROTOCOL`.  

TableKey
Specifies the table to uninstall. The key was returned from `InstallAcpiTable()`.  

Description

The `UninstallAcpiTable()` function allows a caller to remove an ACPI table. The routine will remove its reference from the RSDT/XSDT. A table is referenced by the TableKey parameter returned from a prior call to `InstallAcpiTable()`.  

On successful completion, this function reinstalls the relevant `EFI_CONFIGURATION_TABLE` pointer to the RSDT.  

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The table was successfully inserted</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>TableKey does not refer to a valid key for a table entry.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Insufficient resources exist to complete the request.</td>
</tr>
</tbody>
</table>
21.1 Unicode Collation Protocol

This section defines the Unicode Collation protocol. This protocol is used to allow code running in the boot services environment to perform lexical comparison functions on Unicode strings for given languages.

21.1.1 EFI_UNICODE_COLLATION_PROTOCOL

Summary
Is used to perform case-insensitive comparisons of strings.

GUID

```c
#define EFI_UNICODE_COLLATION_PROTOCOL2_GUID \
   {0xa4c751fc, 0x23ae, 0x4c3e, \
    {0x92, 0xe9, 0x49, 0x64, 0xcf, 0x63, 0xf3, 0x49}}
```

Protocol Interface Structure

```c
typedef struct {
    EFI_UNICODE_COLLATION_STRICOLL StriColl;
    EFI_UNICODE_COLLATION_METAIMATCH MetaiMatch;
    EFI_UNICODE_COLLATION_STRLWR StrLwr;
    EFI_UNICODE_COLLATION_STRUPR StrUpr;
    EFI_UNICODE_COLLATION_FATTOSTR FatToStr;
    EFI_UNICODE_COLLATION_STRTOFAT StrToFat;
    CHAR8 *SupportedLanguages;
} EFI_UNICODE_COLLATION_PROTOCOL;
```

Parameters

**StriColl**
Performs a case-insensitive comparison of two Null-terminated strings. See the `EFI_UNICODE_COLLATION_PROTOCOL.StriColl()` function description.

**MetaiMatch**
Performs a case-insensitive comparison between a Null-terminated pattern string and a Null-terminated string. The pattern string can use the ‘?’ wildcard to match any character, and the ‘*’ wildcard to match any substring. See the `EFI_UNICODE_COLLATION_PROTOCOL.MetaiMatch()` function description.
StrLwr
Converting all the characters in a Null-terminated string to lowercase characters. See the EFI_UNICODE_COLLATION_PROTOCOL.StrLwr() function description.

StrUp
Converting all the characters in a Null-terminated string to uppercase characters. See the EFI_UNICODE_COLLATION_PROTOCOL.StrUp() function description.

StrToFat
Converts a Null-terminated string to legal characters in a FAT filename using an OEM character set. See the EFI_UNICODE_COLLATION_PROTOCOL.StrToFat() function description.

SupportedLanguages
A Null-terminated ASCII string array that contains one or more language codes. This array is specified in RFC 4646 format. See Appendix M — Formats — Language Codes and Language Code Arrays

Description
The EFI_UNICODE_COLLATION_PROTOCOL is used to perform case-insensitive comparisons of strings. One or more of the EFI_UNICODE_COLLATION_PROTOCOL instances may be present at one time. Each protocol instance can support one or more language codes. The language codes supported in the EFI_UNICODE_COLLATION_PROTOCOL are declared in SupportedLanguages.

The SupportedLanguages is a Null-terminated ASCII string array that contains one or more supported language codes. This is the list of language codes that this protocol supports. See Appendix M — Formats — Language Codes and Language Code Arrays for the format of language codes and language code arrays.

The main motivation for this protocol is to help support file names in a file system driver. When a file is opened, a file name needs to be compared to the file names on the disk. In some cases, this comparison needs to be performed in a case-insensitive manner. In addition, this protocol can be used to sort files from a directory or to perform a case-insensitive file search.

21.1.2 EFI_UNICODE_COLLATION_PROTOCOL.StriColl()

Summary
Performs a case-insensitive comparison of two Null-terminated strings.

Prototype

typedef INTN (EFIAPICNF *EFI_UNICODE_COLLATION_STRICOLL) ( IN EFI_UNICODE_COLLATION_PROTOCOL *This,
IN CHAR16 *s1,
IN CHAR16 *s2);

Parameters
This
A pointer to the EFI_UNICODE_COLLATION_PROTOCOL instance. Type EFI_UNICODE_COLLATION_PROTOCOL is defined above.
s1
A pointer to a Null-terminated string.

s2
A pointer to a Null-terminated string.

Description
The StriColl() function performs a case-insensitive comparison of two Null-terminated strings.

This function performs a case-insensitive comparison between the string s1 and the string s2 using the rules for the language codes that this protocol instance supports. If s1 is equivalent to s2, then 0 is returned. If s1 is lexically less than s2, then a negative number will be returned. If s1 is lexically greater than s2, then a positive number will be returned. This function allows strings to be compared and sorted.

Status Codes Returned

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>s1 is equivalent to s2.</td>
</tr>
<tr>
<td>&gt; 0</td>
<td>s1 is lexically greater than s2.</td>
</tr>
<tr>
<td>&lt; 0</td>
<td>s1 is lexically less than s2.</td>
</tr>
</tbody>
</table>

21.1.3 EFI_UNICODE_COLLATION_PROTOCOL.MetaiMatch()

Summary
Performs a case-insensitive comparison of a Null-terminated pattern string and a Null-terminated string.

Prototype

typedef BOOLEAN (EFIAPI *EFI_UNICODE_COLLATION_METAIMATCH) (
    IN EFI_UNICODE_COLLATION_PROTOCOL *This,
    IN CHAR16 *String,
    IN CHAR16 *Pattern
);

Parameters

This
A pointer to the EFI_UNICODE_COLLATION_PROTOCOL instance. Type EFI_UNICODE_COLLATION_PROTOCOL is defined above.

String
A pointer to a Null-terminated string.

Pattern
A pointer to a Null-terminated string.

Description
The MetaiMatch() function performs a case-insensitive comparison of a Null-terminated pattern string and a Null-terminated string.

This function checks to see if the pattern of characters described by Pattern are found in String. The pattern check is a case-insensitive comparison using the rules for the language codes that this protocol instance supports. If the pattern match succeeds, then TRUE is returned. Otherwise FALSE is returned. The following syntax can be used to build the string Pattern:
**Status Codes Returned**

<table>
<thead>
<tr>
<th>TRUE</th>
<th>Pattern was found in String.</th>
</tr>
</thead>
<tbody>
<tr>
<td>FALSE</td>
<td>Pattern was not found in String.</td>
</tr>
</tbody>
</table>

### 21.1.4 EFI_UNICODE_COLLATION_PROTOCOL.StrLwr()

**Summary**

Converts all the characters in a Null-terminated string to lowercase characters.

**Prototype**

```c
typedef VOID (EFIAPI *EFI_UNICODE_COLLATION_STRLWR) (
    IN EFI_UNICODE_COLLATION_PROTOCOL *This,
    IN OUT CHAR16 *String
);
```

**Parameters**

**This**

A pointer to the `EFI_UNICODE_COLLATION_PROTOCOL` instance. Type `EFI_UNICODE_COLLATION_PROTOCOL` is defined above.

**String**

A pointer to a Null-terminated string.

**Description**

This function walks through all the characters in `String`, and converts each one to its lowercase equivalent if it has one. The converted string is returned in `String`.

---

21.1. Unicode Collation Protocol
21.1.5 EFI_UNICODE_COLLATION_PROTOCOL.StrUpr()

Summary
Converts all the characters in a Null-terminated string to uppercase characters.

Prototype

typedef
VOID
(EIFIAPI *EFI_UNICODE_COLLATION_STRUPR) (  
    IN EFI_UNICODE_COLLATION_PROTOCOL *This,  
    IN OUT CHAR16 *String  
);

Parameters

This
A pointer to the EFI_UNICODE_COLLATION_PROTOCOL instance. Type EFI_UNICODE_COLLATION_PROTOCOL is defined above.

String
A pointer to a Null-terminated string.

Description
This function walks through all the characters in String, and converts each one to its uppercase equivalent if it has one. The converted string is returned in String.

21.1.6 EFI_UNICODE_COLLATION_PROTOCOL.FatToStr()

Summary
Converts an 8.3 FAT file name in an OEM character set to a Null-terminated string.

Prototype

typedef
VOID
(EIFIAPI *EFI_UNICODE_COLLATION_FATTOSTR) (  
    IN EFI_UNICODE_COLLATION_PROTOCOL *This,  
    IN UINTN FatSize,  
    IN CHAR8 *Fat,  
    OUT CHAR16 *String  
);

Parameters

This
A pointer to the EFI_UNICODE_COLLATION_PROTOCOL instance. Type EFI_UNICODE_COLLATION_PROTOCOL is defined above.

FatSize
The size of the string Fat in bytes.

Fat
A pointer to a Null-terminated string that contains an 8.3 file name encoded using an 8-bit OEM character set.
String
A pointer to a Null-terminated string. The string must be allocated in advance to hold FatSize characters.

Description
This function converts the string specified by Fat with length FatSize to the Null-terminated string specified by String. The characters in Fat are from an OEM character set.

21.1.7 EFI_UNICODE_COLLATION_PROTOCOL.StrToFat()

Summary
Converts a Null-terminated string to legal characters in a FAT filename using an OEM character set.

Prototype

typedef BOOLEAN (EFIAPI *EFI_UNICODE_COLLATION_STRTOFAT) (  
    IN EFI_UNICODE_COLLATION_PROTOCOL *This,  
    IN CHAR16 *String,  
    IN UINTN FatSize,  
    OUT CHAR8 *Fat  
);  

Parameters
This
A pointer to the EFI_UNICODE_COLLATION_PROTOCOL instance. Type EFI_UNICODE_COLLATION_PROTOCOL is defined above.

String
A pointer to a Null-terminated string.

FatSize
The size of the string Fat in bytes.

Fat
A pointer to a string that contains the converted version of String using legal FAT characters from an OEM character set.

Description
This function converts the characters from String into legal FAT characters in an OEM character set and stores then in the string Fat. This conversion continues until either FatSize bytes are stored in Fat, or the end of String is reached. The characters '.' (period) and ' ' (space) are ignored for this conversion. Characters that map to an illegal FAT character are substituted with an '_'. If no valid mapping from a character to an OEM character is available, then it is also substituted with an '_'. If any of the character conversions are substituted with a '_', then TRUE is returned. Otherwise FALSE is returned.

Status Codes Returned

| TRUE      | One or more conversions failed and were substituted with '_'. |
| FALSE     | None of the conversions failed. |
21.2 Regular Expression Protocol

This section defines the Regular Expression Protocol. This protocol is used to match Unicode strings against Regular Expression patterns.

21.2.1 EFI_REGULAR_EXPRESSION_PROTOCOL

Summary

GUID

```c
#define EFI_REGULAR_EXPRESSION_PROTOCOL_GUID \
{ 0xB3F79D9A, 0x436C, 0xDC11,} \n{ 0xB0, 0x52, 0xCD, 0x85, 0xDF, 0x52, 0x4C, 0xE6 } 
```

Protocol Interface Structure

```c
typedef struct {
    EFI_REGULAR_EXPRESSION_MATCH   MatchString;
    EFI_REGULAR_EXPRESSION_GET_INFO GetInfo;
} EFI_REGULAR_EXPRESSION_PROTOCOL;
```

Parameters

MatchString

Search the input string for anything that matches the regular expression.

GetInfo

Returns information about the regular expression syntax types supported by the implementation.

21.2.2 EFI_REGULAR_EXPRESSION_PROTOCOL.MatchString()

Summary

Checks if the input string matches to the regular expression pattern.

Prototype

```c
typedef
EFI_STATUS
EFIAPI *EFI_REGULAR_EXPRESSION_MATCH) ( 
    IN EFI_REGULAR_EXPRESSION_PROTOCOL *This, 
    IN CHAR16 *String, 
    IN CHAR16 *Pattern, 
    IN EFI_REJEX_SYNTAX_TYPE *SyntaxType, OPTIONAL 
    OUT BOOLEAN *Result, 
    OUT EFI_REJEX_CAPTURE **Captures, OPTIONAL 
    OUT UINTN *CapturesCount 
); 
```

Parameters

This

A pointer to the EFI_REGULAR_EXPRESSION_PROTOCOL instance. Type EFI_REGULAR_EXPRESSION_PROTOCOL is defined in above.
String
A pointer to a NULL terminated string to match against the regular expression string specified by Pattern.

Pattern
A pointer to a NULL terminated string that represents the regular expression.

SyntaxType
A pointer to the EFI_REGEX_SYNTAX_TYPE that identifies the regular expression syntax type to use. May be NULL in which case the function will use its default regular expression syntax type.

Result
On return, points to TRUE if String fully matches against the regular expression Pattern using the regular expression SyntaxType. Otherwise, points to FALSE.

Captures
A Pointer to an array of EFI_REGEX_CAPTURE objects to receive the captured groups in the event of a match. The full sub-string match is put in Captures [0], and the results of N capturing groups are put in Captures [1:N]. If Captures is NULL, then this function doesn’t allocate the memory for the array and does not build up the elements. It only returns the number of matching patterns in CapturesCount. If Captures is not NULL, this function returns a pointer to an array and builds up the elements in the array. CapturesCount is also updated to the number of matching patterns found. It is the caller’s responsibility to free the memory pool in Captures and in each CapturePtr in the array elements.

CapturesCount
On output, CapturesCount is the number of matching patterns found in String. Zero means no matching patterns were found in the string.

Description
The MatchString() function performs a matching of a Null-terminated input string with the NULL terminated pattern string. The pattern string syntax type is optionally identified in SyntaxType.

This function checks to see if String fully matches against the regular expression described by Pattern. The pattern check is performed using regular expression rules that are supported by this implementation, as indicated in the return value of GetInfo function. If the pattern match succeeds, then TRUE is returned in Result. Otherwise FALSE is returned.

Related Definitions

typedef struct {
    CONST CHAR16 *CapturePtr;
    UINTN Length;
} EFI_REGEX_CAPTURE;

*CapturePtr
Pointer to the start of the captured sub-expression within matched String.

Length
Length of captured sub-expression.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The regular expression string matching completed successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The regular expression syntax specified by SyntaxType is not supported by this driver.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The regular expression string matching failed due to a hardware or firmware error.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>String, Pattern, Result, or CapturesCount is NULL.</td>
</tr>
</tbody>
</table>
21.2.3 EFI_REGULAR_EXPRESSION_PROTOCOL.GetInfo()

Summary
Returns information about the regular expression syntax types supported by the implementation.

Prototype

typedef
EFI_STATUS
EFI_API *EFI_REGULAR_EXPRESSION_GET_INFO) (  
  IN EFI_REGULAR_EXPRESSION_PROTOCOL *This,
  IN OUT UINTN *RegExSyntaxTypeListSize,
  OUT EFI_REGEX_SYNTAX_TYPE *RegExSyntaxTypeList
);

Parameters

This
A pointer to the EFI_REGULAR_EXPRESSION_PROTOCOL instance.

RegExSyntaxTypeListSize
On input, the size in bytes of RegExSyntaxTypeList. On output with a return code of EFI_SUCCESS, the size in bytes of the data returned in RegExSyntaxTypeList. On output with a return code of EFI_BUFFER_TOO_SMALL, the size of RegExSyntaxTypeList required to obtain the list.

RegExSyntaxTypeList
A caller-allocated memory buffer filled by the driver with one EFI_REGEX_SYNTAX_TYPE element for each supported regular expression syntax type. The list must not change across multiple calls to the same driver. The first syntax type in the list is the default type for the driver.

Description
This function returns information about supported regular expression syntax types. A driver implementing the EFI_REGULAR_EXPRESSION_PROTOCOL need not support more than one regular expression syntax type, but shall support a minimum of one regular expression syntax type.

Related Definitions

typedef EFI_GUID EFI_REGEX_SYNTAX_TYPE;

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The regular expression syntax types list was returned successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The service is not supported by this driver.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The list of syntax types could not be retrieved due to a hardware or firmware error.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The buffer RegExSyntaxTypeList is too small to hold the result.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>RegExSyntaxTypeListSize is NULL.</td>
</tr>
</tbody>
</table>

21.2. Regular Expression Protocol
21.2.4 EFI Regular Expression Syntax Type Definitions

Summary

This sub-section provides EFI_GUID values for a selection of EFI_REGULAR_EXPRESSION_PROTOCOL syntax types. The types listed are optional, not meant to be exhaustive and may be augmented by vendors or other industry standards.

Prototype

For regular expression rules specified in the POSIX Extended Regular Expression (ERE) Syntax:

```
#define EFI_REGEX_SYNTAX_TYPE_POSIX_EXTENDED_GUID \
{0x5F05B20F, 0x4A56, 0xC231,\ 
  { 0xFA, 0x0B, 0xA7, 0xB1, 0xF1, 0x10, 0x04, 0x1D }}
```

For regular expression rules specified in the Perl standard:

```
#define EFI_REGEX_SYNTAX_TYPE_PERL_GUID \
{0x63E60A51, 0x497D, 0xD427,\ 
  { 0xC4, 0xA5, 0xB8, 0xAB, 0xDC, 0x3A, 0xAE, 0xB6 }}
```

For regular expression rules specified in the ECMA 262 Specification:

```
#define EFI_REGEX_SYNTAX_TYPE_ECMA_262_GUID \
{ 0x9A473A4A, 0x4CEB, 0xB95A, 0x41,\ 
  { 0x5E, 0x5B, 0xA0, 0xBC, 0x63, 0x9B, 0x2E }}
```

For regular expression rules specified in the POSIX Extended Regular Expression (ERE) Syntax, where the Pattern and String input strings need to be converted to ASCII:

```
#define EFI_REGEX_SYNTAX_TYPE_POSIX_EXTENDED_ASCII_GUID \
{0x3FD32128, 0x4BB1, 0xF632, \ 
  { 0xBE, 0x4F, 0xBA, 0xBF, 0x85, 0xC9, 0x36, 0x76 }}
```

For regular expression rules specified in the Perl standard, where the Pattern and String input strings need to be converted to ASCII:

```
#define EFI_REGEX_SYNTAX_TYPE_PERL_ASCII_GUID \
{0x87DFB76D, 0x4B58, 0xEF3A, \ 
  { 0xF7, 0xC6, 0x16, 0xA4, 0x2A, 0x68, 0x28, 0x10 }}
```

For regular expression rules specified in the ECMA 262 Specification, where the Pattern and String input strings need to be converted to ASCII:

```
#define EFI_REGEX_SYNTAX_TYPE_ECMA_262_ASCII_GUID \
{ 0xB2284A2F, 0x4491, 0x6D9D, \ 
  { 0xE9, 0xB7, 0x11, 0xB0, 0x67, 0xD4, 0x9B, 0x9A }}
```

See Appendix Q — References for more information.
This section defines an EFI Byte Code (EBC) Virtual Machine that can provide platform- and processor-independent mechanisms for loading and executing EFI device drivers.

### 22.1 Overview

The current design for option ROMs that are used in personal computer systems has been in place since 1981. Attempts to change the basic design requirements have failed for a variety of reasons. The EBC Virtual Machine described in this chapter is attempting to help achieve the following goals:

- Abstract and extensible design
- Processor independence
- OS independence
- Build upon existing specifications when possible
- Facilitate the removal of legacy infrastructure
- Exclusive use of EFI Services

One way to satisfy many of these goals is to define a pseudo or virtual machine that can interpret a predefined instruction set. This will allow the virtual machine to be ported across processor and system architectures without changing or recompiling the option ROM. This specification defines a set of machine level instructions that can be generated by a C compiler.

The following sections are a detailed description of the requirements placed on future option ROMs.

### 22.1.1 Processor Architecture Independence

Option ROM images shall be independent of supported 32-bit and supported 64-bit architectures. In order to abstract the architectural differences between processors option ROM images shall be EBC. This model is presented below:

- 64-bit C source code
- The EFI EBC image is the flashed image
- The system BIOS implements the EBC interpreter
- The interpreter handles 32 vs. 64 bit issues

Current Option ROM technology is processor dependent and heavily reliant upon the existence of the PC-AT infrastructure. These dependencies inhibit the evolution of both hardware and software under the veil of “backward compatibility.” A solution that isolates the hardware and support infrastructure through abstraction will facilitate the uninhibited progression of technology.
22.1.2 OS Independent

Option ROMs shall not require or assume the existence of a particular OS.

22.1.3 EFI Compliant

Option ROM compliance with EFI requires (but is not limited to) the following:

- Little endian layout
- Single-threaded model with interrupt polling if needed
- Where EFI provides required services, EFI is used exclusively. These include:
  - Console I/O
  - Memory Management
  - Timer services
  - Global variable access
- When an Option ROM provides EFI services, the EFI specification is strictly followed:
  - Service/protocol installation
  - Calling conventions
  - Data structure layouts
  - Guaranteed return on services

22.1.4 Coexistence of Legacy Option ROMs

The infrastructure shall support coexistent Legacy Option ROM and EBC Option ROM images. This case would occur, for example, when a Plug and Play Card has both Legacy and EBC Option ROM images flashed. The details of the mechanism used to select which image to load is beyond the scope of this document. Basically, a legacy System BIOS would not recognize an EBC Option ROM and therefore would never load it. Conversely, an EFI Firmware Boot Manager would only load images that it supports.

The EBC Option ROM format must utilize a legacy format to the extent that a Legacy System BIOS can:

- Determine the type of the image, in order to ignore the image. The type must be incompatible with currently defined types.
- Determine the size of the image, in order to skip to the next image.

22.1.5 Relocatable Image

An EBC option ROM image shall be eligible for placement in any system memory area large enough to accommodate it.

Current option ROM technology requires images to be shadowed in system memory address range 0xC0000 to 0xEFFFF on a 2048 byte boundary. This dependency not only limits the number of Option ROMs, it results in unused memory fragments up to 2 KiB.
22.1.6 Size Restrictions Based on Memory Available

EBC option ROM images shall not be limited to a predetermined fixed maximum size.

Current option ROM technology limits the size of a preinitialization option ROM image to 128 KiB (126 KiB actual). Additionally, in the DDIM an image is not allowed to grow during initialization. It is inevitable that 64-bit solutions will increase in complexity and size. To avoid revisiting this issue, EBC option ROM size is only limited by available system memory. EFI memory allocation services allow device drivers to claim as much memory as they need, within limits of available system memory.

The PCI specification limits the size of an image stored in an option ROM to 16 MB. If the driver is stored on the hard drive then the 16MB option ROM limit does not apply. In addition, the PE/COFF object format limits the size of images to 2 GB.

22.2 Memory Ordering

The term memory ordering refers to the order in which a processor issues reads (loads) and writes (stores) out onto the bus to system memory. The EBC Virtual Machine enforces strong memory ordering, where reads and writes are issued on the system bus in the order they occur in the instruction stream under all circumstances.

22.3 Virtual Machine Registers

The EBC virtual machine utilizes a simple register set. There are two categories of VM registers: general purpose registers and dedicated registers. All registers are 64-bits wide. There are eight (8) general-purpose registers (R0-R7), which are used by most EBC instructions to manipulate or fetch data. The Table below, General Purpose VM Registers, lists the general-purpose registers in the VM and the conventions for their usage during execution.

<table>
<thead>
<tr>
<th>Index</th>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>R0</td>
<td>Points to the top of the stack</td>
</tr>
<tr>
<td>1-3</td>
<td>R1-R3</td>
<td>Preserved across calls</td>
</tr>
<tr>
<td>4-7</td>
<td>R4-R7</td>
<td>Scratch, not preserved across calls</td>
</tr>
</tbody>
</table>

Register R0 is used as a stack pointer and is used by the CALL, RET, PUSH, and POP instructions. The VM initializes this register to point to the incoming arguments when an EBC image is started or entered. This register may be modified like any other general purpose VM register using EBC instructions. Register R7 is used for function return values.

Unlike the general-purpose registers, the VM dedicated registers have specific purposes. There are two dedicated registers: the instruction pointer (IP), and the flags (Flags) register. Specialized instructions provide access to the dedicated registers. These instructions reference the particular dedicated register by its assigned index value. Dedicated VM Registers lists the dedicated registers and their corresponding index values.

<table>
<thead>
<tr>
<th>Index</th>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>FLAGS</td>
<td>Bit</td>
</tr>
</tbody>
</table>

continues on next page
Table 22.2 – continued from previous page

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>C = Condition code</td>
</tr>
<tr>
<td>1</td>
<td>SS = Single step</td>
</tr>
<tr>
<td>2..63</td>
<td>Reserved</td>
</tr>
<tr>
<td>1</td>
<td>IP Points to current instruction</td>
</tr>
<tr>
<td>2..7</td>
<td>Reserved Not defined</td>
</tr>
</tbody>
</table>

The VM Flags register contains VM status and context flags. *VM Flags Register* lists the descriptions of the bits in the Flags register.

Table 22.3: VM Flags Register

<table>
<thead>
<tr>
<th>Bit</th>
<th>Flag</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>C</td>
<td>Condition code. Set to 1 if the result of the last compare was TRUE, or set to 0 if the last compare was FALSE. Used by conditional JMP instructions.</td>
</tr>
<tr>
<td>1</td>
<td>S</td>
<td>Single-step. If set, causes the VM to generate a single-step exception after executing each instruction. The bit is not cleared by the VM following the exception.</td>
</tr>
<tr>
<td>2..63</td>
<td>—</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

The VM IP register is used as an instruction pointer and holds the address of the currently executing EBC instruction. The virtual machine will update the IP to the address of the next instruction on completion of the current instruction, and will continue execution from the address indicated in IP. The IP register can be moved into any general-purpose register (R0-R7). Data manipulation and data movement instructions can then be used to manipulate the value. The only instructions that may modify the IP are the `JMP`, `CALL`, and `RET` instructions. Since the instruction set is designed to use words as the minimum instruction entity, the low order bit (bit 0) of IP is always cleared to 0. If a JMP, CALL, or RET instruction causes bit 0 of IP to be set to 1, then an alignment exception occurs.

### 22.4 Natural Indexing

The natural indexing mechanism is the critical functionality that enables EBC to be executed unchanged on 32- or 64-bit systems. Natural indexing is used to specify the offset of data relative to a base address. However, rather than specifying the offset as a fixed number of bytes, the offset is encoded in a form that specifies the actual offset in two parts: a constant offset, and an offset specified as a number of natural units (where one natural unit = sizeof (VOID *)). These two values are used to compute the actual offset to data at runtime. When the VM decodes an index during execution, the resultant offset is computed based on the natural processor size. The encoded indexes themselves may be 16, 32, or 64 bits in size. The Table below describes the fields in a natural index encoding.

Table 22.4: Index Encoding

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>N</td>
<td>Sign bit (sign), most significant bit</td>
</tr>
<tr>
<td>N-3..N-1</td>
<td>Bits assigned to natural units (w)</td>
</tr>
<tr>
<td>A..N-4</td>
<td>Constant units (c)</td>
</tr>
<tr>
<td>0..A-1</td>
<td>Natural units (n)</td>
</tr>
</tbody>
</table>

As shown in the Table above for a given encoded index, the most significant bit (bit N) specifies the sign of the resultant offset after it has been calculated. The sign bit is followed by three bits (N-3..N-1) that are used to compute the width of the natural units field (n). The value (w) from this field is multiplied by the index size in bytes to determine the actual width (A) of the natural units field (n). Once the width of the natural units field has been determined, then the natural units (n) and constant units (c) can be extracted. The offset is then calculated at runtime according to the following equation:
Offset = \( (c + n \times (\text{sizeof (VOID *))}) \times \text{sign} \)

The following sections describe each of these fields in more detail.

### 22.4.1 Sign Bit

The sign bit determines the sign of the index once the offset calculation has been performed. All index computations using "n" and "c" are done with positive numbers, and the sign bit is only used to set the sign of the final offset computed.

### 22.4.2 Bits Assigned to Natural Units

This 3-bit field that is used to determine the width of the natural units field. The units vary based on the size of the index according to the Table, below, *Index Size in Index Encoding*. For example, for a 16-bit index, the value contained in this field would be multiplied by 2 to get the actual width of the natural-units field.

<table>
<thead>
<tr>
<th>Index Size</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>16 bits</td>
<td>2 bits</td>
</tr>
<tr>
<td>32 bits</td>
<td>4 bits</td>
</tr>
<tr>
<td>64 bits</td>
<td>8 bits</td>
</tr>
</tbody>
</table>

### 22.4.3 Constant

The constant is the number of bytes in the index that do not scale with processor size. When the index is a 16-bit value, the maximum constant is 4095. This index is achieved when the bits assigned to natural units is 0.

### 22.4.4 Natural Units

Natural units are used when a structure has fields that can vary with the architecture of the processor. Fields that precipitate the use of natural units include pointers and EFI INTN and UINTN data types. The size of one pointer or INTN/UINTN equals one natural unit. The natural units field in an index encoding is a count of the number of natural fields whose sizes (in bytes) must be added to determine a field offset.

As an example, assume that a given EBC instruction specifies a 16-bit index of 0xA048. This breaks down into:

- Sign bit (bit 15) = 1 (negative offset)
- Bits assigned to natural units (w, bits 14-12) = 2. Multiply by index size in bytes = 2 x 2 = 4 (A)
- \( c = \) bits 11-4 = 4
- \( n = \) bits 3-0 = 8

On a 32-bit machine, the offset is then calculated to be:

- Offset = \( (4 + 8 \times 4) \times -1 = -36 \)

On a 64-bit machine, the offset is calculated to be:

- Offset = \( (4 + 8 \times 8) \times -1 = -68 \)
22.5 EBC Instruction Operands

The VM supports an EBC instruction set that performs data movement, data manipulation, branching, and other miscellaneous operations typical of a simple processor. Most instructions operate on two operands, and have the general form:

```
INSTRUCTION Operand1, Operand2
```

Typically, instruction operands will be one of the following:

- Direct
- Indirect
- Indirect with index
- Immediate

The following subsections explain these operands.

### 22.5.1 Direct Operands

When a direct operand is specified for an instruction, the data to operate upon is contained in one of the VM general-purpose registers R0-R7. Syntactically, an example of direct operand mode could be the `ADD` instruction:

```
ADD64 R1, R2
```

This form of the instruction utilizes two direct operands. For this particular instruction, the VM would take the contents of register R2, add it to the contents of register R1, and store the result in register R1.

### 22.5.2 Indirect Operands

When an indirect operand is specified, a VM register contains the address of the operand data. This is sometimes referred to as register indirect, and is indicated by prefixing the register operand with “@.” Syntactically, an example of an indirect operand mode could be this form of the ADD instruction:

```
ADD32 R1, @R2
```

For this instruction, the VM would take the 32-bit value at the address specified in R2, add it to the contents of register R1, and store the result in register R1.

### 22.5.3 Indirect with Index Operands

When an indirect with index operand is specified, the address of the operand is computed by adding the contents of a register to a decoded natural index that is included in the instruction. Typically with indexed addressing, the base address will be loaded in the register and an index value will be used to indicate the offset relative to this base address. Indexed addressing takes the form:

```
@ R1(+n,+c)
```

where:

- R1 is one of the general-purpose registers (R0-R7) which contains the base address
- +n is a count of the number of “natural” units offset. This portion of the total offset is computed at runtime as (n * sizeof (VOID *))

22.5. EBC Instruction Operands
• +c is a byte offset to add to the natural offset to resolve the total offset

The values of n and c can be either positive or negative, though they must both have the same sign. These values get encoded in the indexes associated with EBC instructions as shown in Index Encoding. Indexes can be 16-, 32-, or 64-bits wide depending on the instruction. An example of indirect with index syntax would be:

```
ADD32 R1, @R2 (+1, +8)
```

This instruction would take the address in register R2, add \((8 + 1 \times \text{sizeof (VOID *)})\), read the 32-bit value at the address, add the contents of R1 to the value, and store the result back to R1.

### 22.5.4 Immediate Operands

Some instructions support an immediate operand, which is simply a value included in the instruction encoding. The immediate value may or may not be sign extended, depending on the particular instruction. One instruction that supports an immediate operand is \textit{MOVI}. An example usage of this instruction is:

```
MOVIww R1, 0x1234
```

This instruction moves the immediate value 0x1234 directly into VM register R1. The immediate value is contained directly in the encoding for the \textit{MOVI} instruction.

### 22.6 EBC Instruction Syntax

Most EBC instructions have one or more variations that modify the size of the instruction and/or the behavior of the instruction itself. These variations will typically modify an instruction in one or more of the following ways:

• The size of the data being operated upon
• The addressing mode for the operands
• The size of index or immediate data
• To represent these variations syntactically in this specification the following conventions are used:
  • Natural indexes are indicated with the “Index” keyword, and may take the form of “Index16,” “Index32,” or “Index64” to indicate the size of the index value supported. Sometimes the form Index16|32|64 is used here, which is simply a shorthand notation for Index16|Index32|Index64. A natural index is encoded per Index Encoding is resolved at runtime.
  • Immediate values are indicated with the “Immed” keyword, and may take the form of “Immed16,” “Immed32,” or “Immed64” to indicate the size of the immediate value supported. The shorthand notation Immed16|32|64 is sometimes used when different size immediate values are supported.
• Terms in brackets \([\ ]\) are required.
• Terms in braces \{\} are optional.
• Alternate terms are separated by a vertical bar |.
• The form R1 and R2 represent Operand 1 register and Operand 2 register respectfully, and can typically be any VM general-purpose register R0-R7.
• Within descriptions of the instructions, brackets \([\ ]\) enclosing a register and/or index indicate that the contents of the memory pointed to by the enclosed contents are used.
22.7 Instruction Encoding

Most EBC instructions take the form:

\[
\text{INSTRUCTION R1, R2 Index|Immed}
\]

For those instructions that adhere to this form, the binary encoding for the instruction will typically consist of an opcode byte, followed by an operands byte, followed by two or more bytes of immediate or index data. Thus the instruction stream will be:

\[
(1 \text{ Byte Opcode}) + (1 \text{ Byte Operands}) + (\text{Immediate data|Index data})
\]

22.7.1 Instruction Opcode Byte Encoding

The first byte of an instruction is the opcode byte, and an instruction’s actual opcode value consumes 6 bits of this byte. The remaining two bits will typically be used to indicate operand sizes and/or presence or absence of index or immediate data. The Table below, \textit{Opcode Byte Encoding} defines the bits in the opcode byte for most instructions, and their usage.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Sym</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>6..7</td>
<td>Modifiers</td>
<td>One or more of:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Index or immediate data present/absent</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Operand size</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Index or immediate data size</td>
</tr>
<tr>
<td>0..5</td>
<td>Op</td>
<td>Instruction opcode</td>
</tr>
</tbody>
</table>

For those instructions that use bit 7 to indicate the presence of an index or immediate data and bit 6 to indicate the size of the index or immediate data, if bit 7 is 0 (no immediate data), then bit 6 is ignored by the VM. Otherwise, unless otherwise specified for a given instruction, setting unused bits in the opcode byte results in an instruction encoding exception when the instruction is executed. Setting the modifiers field in the opcode byte to reserved values will also result in an instruction encoding exception.

22.7.2 Instruction Operands Byte Encoding

The second byte of most encoded instructions is an operand byte, which encodes the registers for the instruction operands and whether the operands are direct or indirect. The Table below, \textit{Operand Byte Encoding} defines the encoding for the operand byte for these instructions. Unless otherwise specified for a given instruction, setting unused bits in the operand byte results in an instruction encoding exception when the instruction is executed. Setting fields in the operand byte to reserved values will also result in an instruction encoding exception.

| Bit | Description |
|-----|-------------|-------------|
Table 22.7 – continued from previous page

<table>
<thead>
<tr>
<th>7</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Operand 2 is direct</td>
</tr>
<tr>
<td>1</td>
<td>Operand 2 is indirect</td>
</tr>
<tr>
<td>4..6</td>
<td>Operand 2 register</td>
</tr>
<tr>
<td>3</td>
<td>Description</td>
</tr>
<tr>
<td>0</td>
<td>Operand 1 is direct</td>
</tr>
<tr>
<td>1</td>
<td>Operand 1 is indirect</td>
</tr>
<tr>
<td>0..2</td>
<td>Operand 1 register</td>
</tr>
</tbody>
</table>

22.7.3 Index/Immediate Data Encoding

Following the operand bytes for most instructions is the instruction’s immediate data. The immediate data is, depending on the instruction and instruction encoding, either an unsigned or signed literal value, or an index encoded using natural encoding. In either case, the size of the immediate data is specified in the instruction encoding.

For most instructions, the index/immediate value in the instruction stream is interpreted as a signed immediate value if the register operand is direct. This immediate value is then added to the contents of the register to compute the instruction operand. If the register is indirect, then the data is usually interpreted as a natural index (NATURAL INDEXING) and the computed index value is added to the contents of the register to get the address of the operand.

22.8 EBC Instruction Set

The following sections describe each of the EBC instructions in detail. Information includes an assembly-language syntax, a description of the instruction functionality, binary encoding, and any limitations or unique behaviors of the instruction.

22.8.1 ADD

Syntax:

\[
\text{ADD[32|64]} \{@\}\text{R1}, \{@\}\text{R2} \{\text{Index16|Immed16}\}
\]

Description

Adds two signed operands and stores the result to Operand 1. The operation can be performed on either 32-bit (ADD32) or 64-bit (ADD64) operands.

Operation:

\[
\text{Operand 1} \leftarrow \text{Operand 1} + \text{Operand 2}
\]

Table 22.8: ADD Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
</tr>
</tbody>
</table>

continues on next page
Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index and the Operand 2 value is fetched from memory as a signed value at address [R2 + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the R2 register contents such that Operand 2 = R2 + Immed16.
- If the instruction is ADD32 and Operand 1 is direct, then the result is stored back to the Operand 1 register with the upper 32 bits cleared.

22.8.2 AND

Syntax

\[ \text{AND}[32|64] \{@\}R1, \{@\}R2 \{Index16|Immed16} \]

Description

Performs a logical AND operation on two operands and stores the result to Operand 1. The operation can be performed on either 32-bit (AND32) or 64-bit (AND64) operands.

Operation

\[ \text{Operand 1} \leftarrow \text{Operand 1 AND Operand 2} \]

Table 22.9: AND Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
</tr>
</tbody>
</table>

continues on next page
Table 22.9 – continued from previous page

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>7</td>
<td>0 = Immediate/index absent</td>
</tr>
<tr>
<td></td>
<td>1 = Immediate/index present</td>
</tr>
<tr>
<td>6</td>
<td>0 = 32-bit operation</td>
</tr>
<tr>
<td></td>
<td>1 = 64-bit operation</td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x14</td>
</tr>
<tr>
<td>1</td>
<td>Bit</td>
</tr>
<tr>
<td>7</td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td>4..6</td>
<td>Operand 2</td>
</tr>
<tr>
<td>3</td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td>Operand 1</td>
</tr>
<tr>
<td>2..3</td>
<td>Optional 16-bit immediate data/index</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address \([R2 + \text{Index16}]\).
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the register contents such that Operand 2 = \(R2 + \text{Immed16}\).
- If the instruction is AND32 and Operand 1 is direct, then the result is stored to the Operand 1 register with the upper 32 bits cleared.

22.8.3 ASHR

Syntax

ASHR\([32|64]\) \{@\}R1, \{@\}R2 \{Index16|Immed16\}

Description

Performs an arithmetic right-shift of a signed 32-bit (ASHR32) or 64-bit (ASHR64) operand and stores the result back to Operand 1

Operation

Operand 1 <= Operand 1 SHIFT-RIGHT Operand 2
Table 22.10 – continued from previous page

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>7</td>
<td>0 = Immediate/index absent</td>
</tr>
<tr>
<td></td>
<td>1 = Immediate/index present</td>
</tr>
<tr>
<td>6</td>
<td>0 = 32-bit operation</td>
</tr>
<tr>
<td></td>
<td>1 = 64-bit operation</td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x19</td>
</tr>
<tr>
<td>1</td>
<td>Bit Description</td>
</tr>
<tr>
<td>7</td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td>4..6</td>
<td>Operand 2</td>
</tr>
<tr>
<td>3</td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td>Optional 16-bit immediate data/index</td>
</tr>
<tr>
<td>2..3</td>
<td></td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address [R2 + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the register contents such that Operand 2 = R2 + Immed16.
- If the instruction is ASHR32, and Operand 1 is direct, then the result is stored back to the Operand 1 register with the upper 32 bits cleared.

22.8.4 BREAK

Syntax:

```
BREAK [break code]
```

Description

The BREAK instruction is used to perform special processing by the VM. The break code specifies the functionality to perform.

**BREAK 0** - Runaway program break. This indicates that the VM is likely executing code from cleared memory. This results in a bad break exception.

**BREAK 1** - Get virtual machine version. This instruction returns the 64-bit virtual machine revision number in VM register R7. The encoding is shown in the Tables, below, *VM Version Format* and *BREAK Instruction Encoding*. A VM that conforms to this version of the specification should return a version number of 0x00010000.
Table 22.11: VM Version Format

<table>
<thead>
<tr>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>63-32</td>
<td>Reserved = 0</td>
</tr>
<tr>
<td>31..16</td>
<td>VM major version</td>
</tr>
<tr>
<td>15..0</td>
<td>VM minor version</td>
</tr>
</tbody>
</table>

**BREAK 3** - Debug breakpoint. Executing this instruction results in a debug break exception. If a debugger is attached or available, then it may halt execution of the image.

**BREAK 4** - System call. There are no system calls supported for use with this break code, so the VM will ignore the instruction and continue execution at the following instruction.

**BREAK 5** - Create thunk. This causes the interpreter to create a thunk for the EBC entry point whose 32-bit IP-relative offset is stored at the 64-bit address in VM register R7. The interpreter then replaces the contents of the memory location pointed to by R7 to point to the newly created thunk. Since all EBC IP-relative offsets are relative to the next instruction or data object, the original offset is off by 4, so must be incremented by 4 to get the actual address of the entry point.

**BREAK 6** - Set compiler version. An EBC C compiler can insert this break instruction into an executable to set the compiler version used to build an EBC image. When the VM executes this instruction it takes the compiler version from register R7 and may perform version compatibility checking. The compiler version number follows the same format as the VM version number returned by the BREAK 1 instruction.

Table 22.12: BREAK Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Opcode = 0x00</td>
</tr>
<tr>
<td>1</td>
<td>0 = Runaway program break</td>
</tr>
<tr>
<td></td>
<td>1 = Get virtual machine version</td>
</tr>
<tr>
<td></td>
<td>3 = Debug breakpoint</td>
</tr>
<tr>
<td></td>
<td>4 = System call</td>
</tr>
<tr>
<td></td>
<td>5 = Create thunk</td>
</tr>
<tr>
<td></td>
<td>6 = Set compiler version</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

- Executing an undefined BREAK code results in a bad break exception.
- Executing BREAK 0 results in a bad break exception.

### 22.8.5 CALL

**Syntax:**

- CALL32{EX}{a} {@}R1 {Immed32|Index32}
- CALL64{EX}{a} Immed64

**Description**

The CALL instruction pushes the address of the following instruction on the stack and jumps to a subroutine. The subroutine may be either EBC or native code, and may be to an absolute or IP-relative address. CALL32 is used to jump directly to EBC code within a given application, whereas CALLEX is used to jump to external code (either native or EBC), which requires thunking. Functionally, the CALL does the following:
R0 = R0 - 8;
PUSH64 ReturnAddress
if (Opcode.ImmedData64Bit) {
    if (Operands.EbcCall) {
        IP = Immed64;
    } else {
        NativeCall (Immed64);
    }
} else {
    if (Operand1 != R0) {
        Addr = Operand1;
    } else {
        Addr = Immed32;
    }
    if (Operands.EbcCall) {
        if (Operands.RelativeAddress) {
            IP += Addr + SizeOfThisInstruction;
        } else {
            IP = Addr
        }
    } else {
        if (Operands.RelativeAddress) {
            NativeCall (IP + Addr)
        } else {
            NativeCall (Addr)
        }
    }
}

Operation:
R0 <= R0 - 16
[R0] <= IP + SizeOfThisInstruction
IP <= IP + SizeOfThisInstruction + Operand 1 (relative CALL)
IP <= Operand 1 (absolute CALL)

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
</tr>
<tr>
<td></td>
<td>Description</td>
</tr>
</tbody>
</table>
| 7    | 0 = Immediate/index data absent
|      | 1 = Immediate/index data present |
| 6    | 0 = CALL32 with 32-bit immediate data/index if present
|      | 1 = CALL64 with 64-bit immediate data |
| 0..5 | Opcode = 0x03 |
| 1    | Bit         |
|      | Description |
| 6..7 | Reserved = 0 |

continues on next page
<table>
<thead>
<tr>
<th></th>
<th>Description</th>
</tr>
</thead>
</table>
| 5 | 0 = Call to EBC  
    1 = Call to native code                                                 |
| 4 | 0 = Absolute address  
    1 = Relative address                                                    |
| 3 | 0 = Operand 1 direct  
    1 = Operand 1 indirect                                                   |
| 0..2 | Operand 1                                                                 |
| 2..5 | Optional 32-bit index/immediate for CALL32 |
| 2..9 | Required 64-bit immediate data for CALL64 |

**BEHAVIOR AND RESTRICTIONS**

- For the CALL32 forms, if Operand 1 is indirect, then the immediate data is interpreted as an index, and the Operand 1 value is fetched from memory address [R1 + Index32].
- For the CALL32 forms, if Operand 1 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 1 register contents such that Operand 1 = R1 + Immed32.
- For the CALLEX forms, the VM must fix up the stack pointer and execute a call to native code in a manner compatible with the native code such that the callee is able to access arguments passed on the VM stack.
- For the CALLEX forms, the value returned by the callee should be returned in R7.
- For the CALL64 forms, the Operand 1 fields are ignored.
- If Byte7:Bit6 = 1 (CALL64), then Byte1:Bit4 is assumed to be 0 (absolute address)
- For CALL32 forms, if Operand 1 register = R0, then the register operand is ignored and only the immediate data is used in the calculation of the call address.
- Prior to the call, the VM will decrement the stack pointer R0 by 16 bytes, and store the 64-bit return address on the stack.
- Offsets for relative calls are relative to the address of the instruction following the CALL instruction.

**22.8.6 CMP**

**Syntax**

```
CMP[32|64][eq|lte|gte|ulte|ugte] R1, {@}R2 {Index16|Immed16}
```

**Description**

The CMP instruction is used to compare Operand 1 to Operand 2. Supported comparison modes are =, <=, >=, unsigned <, and unsigned >=. The comparison size can be 32 bits (CMP32) or 64 bits (CMP64). The effect of this instruction is to set or clear the condition code bit in the Flags register per the comparison results. The operands are compared as signed values except for the CMPulte and CMPugte forms.

**Operation**
CMPeq: Flags.C <= (Operand 1 == Operand 2)
CMPlte: Flags.C <= (Operand 1 <= Operand 2)
CMPgte: Flags.C <= (Operand 1 >= Operand 2)
CMPulte: Flags.C <= (Operand 1 <= Operand 2) (unsigned)
CMPugte: Flags.C <= (Operand 1 >= Operand 2) (unsigned)

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit Description</td>
</tr>
</tbody>
</table>
| 7    | 0 = Immediate/index data absent  
       | 1 = Immediate/index data present |
| 6    | 0 = 32-bit comparison  
       | 1 = 64-bit comparison |
| 0..5 | Opcode  
       | 0x05 = CMPeq compare equal  
       | 0x06 = CMPlte compare signed less than/equal  
       | 0x07 = CMPgte compare signed greater than/equal  
       | 0x08 = CMPulte compare unsigned less than/equal  
       | 0x09 = CMPugte compare unsigned greater than/equal |
| 1    | Bit Description |
| 7    | 0 = Operand 2 direct  
       | 1 = Operand 2 indirect |
| 4..6 | Operand 2 |
| 3    | Reserved = 0 |
| 0..2 | Operand 1 |
| 2..3 | Optional 16-bit immediate data/index |

**Behaviors and Restrictions**

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory address [R2 + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the register contents such that Operand 2 = R2 + Immed16.
- Only register direct is supported for Operand 1.
22.8.7 CMPI

Syntax

CMPI[32|64]{w|d}{eq|lte|gte|ulte|ugte} [@]R1 {Index16}, Immed16|Immed32

Description

Compares two operands, one of which is an immediate value, for =, <=, >=, unsigned <=, or unsigned >=, and sets or clears the condition flag bit in the Flags register accordingly. Comparisons can be performed on a 32-bit (CMPI32) or 64-bit (CMPI64) basis. The size of the immediate data can be either 16 bits (CMPIw) or 32 bits (CMPId).

Operation:

| CMPIeq: Flags.C <= (Operand 1 == Operand 2) |
| CMPIlte: Flags.C <= (Operand 1 <= Operand 2) |
| CMPIgte: Flags.C <= (Operand 1 >= Operand 2) |
| CMPIulte: Flags.C <= (Operand 1 <= Operand 2) |
| CMPIugte: Flags.C <= (Operand 1 >= Operand 2) |

Table 22.15: CMPI Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
</tr>
<tr>
<td>7</td>
<td>0 = 16-bit immediate data</td>
</tr>
<tr>
<td>6</td>
<td>0 = 32-bit comparison</td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode</td>
</tr>
<tr>
<td></td>
<td>0x2D = CMPIeq compare equal</td>
</tr>
<tr>
<td></td>
<td>0x2E = CMPIlte compare signed less than/equal</td>
</tr>
<tr>
<td></td>
<td>0x2F = CMPIgte compare signed greater than/equal</td>
</tr>
<tr>
<td></td>
<td>0x30 = CMPIulte compare unsigned less than/equal</td>
</tr>
<tr>
<td></td>
<td>0x31 = CMPIugte compare unsigned greater than/equal</td>
</tr>
<tr>
<td>1</td>
<td>Bit</td>
</tr>
<tr>
<td>5..7</td>
<td>Reserved = 0</td>
</tr>
<tr>
<td>4</td>
<td>0 = Operand 1 index absent</td>
</tr>
<tr>
<td>3</td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td>0..2</td>
<td>Operand 1</td>
</tr>
<tr>
<td>2..3</td>
<td>Optional 16-bit Operand 1 index</td>
</tr>
</tbody>
</table>
Behaviors and Restrictions

- The immediate data is fetched as a signed value.
- If the immediate data is smaller than the comparison size, then the immediate data is sign-extended appropriately.
- If Operand 1 is direct, and an Operand 1 index is specified, then an instruction encoding exception is generated.

### 22.8.8 DIV

**Syntax:**
```
DIV[32|64] {@}R1, {@}R2 {Index16|Immed16}
```

**Description**
Performs a divide operation on two signed operands and stores the result to Operand 1. The operation can be performed on either 32-bit (DIV32) or 64-bit (DIV64) operands.

**Operation:**

```
Operand 1 <= Operand 1 / Operand 2
```

**Table 22.16: DIV Instruction Encoding**

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
</tr>
<tr>
<td>7</td>
<td>0 = Immediate/index absent</td>
</tr>
<tr>
<td></td>
<td>1 = Immediate/index present</td>
</tr>
<tr>
<td>6</td>
<td>0 = 32-bit operation</td>
</tr>
<tr>
<td></td>
<td>1 = 64-bit operation</td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x10</td>
</tr>
<tr>
<td>1</td>
<td>Bit</td>
</tr>
<tr>
<td>7</td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td>4..6</td>
<td>Operand 2</td>
</tr>
<tr>
<td>3</td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td>Operand 1</td>
</tr>
<tr>
<td>2..3</td>
<td>Optional 16-bit immediate data/index</td>
</tr>
</tbody>
</table>

**Behaviors and Restrictions**

22.8. EBC Instruction Set
• If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address [R2+ Index16].
• If Operand 2 is direct, then the immediate data is considered a signed value and is added to the register contents such that Operand 2 = R2 + Immed16
• If the instruction is DIV32 form, and Operand 1 is direct, then the upper 32 bits of the result are set to 0 before storing to the Operand 1 register.
• A divide-by-0 exception occurs if Operand 2 = 0.

22.8.9 DIVU

Syntax:

DIVU[32|64] {®}R1, {®}R2 {Index16|Immed16}

Description
Performs a divide operation on two unsigned operands and stores the result to Operand 1. The operation can be performed on either 32-bit (DIVU32) or 64-bit (DIVU64) operands.

Operation:

Operand 1 <= Operand 1 / Operand 2

Table 22.17: DIVU Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
</table>
| 0    | Bit         | 0 = Immediate/index absent  
|      |             | 1 = Immediate/index present |
| 6    | 0 = 32-bit operation  
|      | 1 = 64-bit operation |
| 0..5 | Opcode = 0x11 |
| 1    | Bit         | Description |
| 7    | 0 = Operand 2 direct  
|      | 1 = Operand 2 indirect |
| 4..6 | Operand 2 |
| 3    | 0 = Operand 1 direct  
|      | 1 = Operand 1 indirect |
| 0..2 | Operand 1 |
| 2..3 | Optional 16-bit immediate data/index |

Behaviors and Restrictions
• If Operand 2 is indirect, then the immediate data is interpreted as an index, and the value is fetched from memory as an unsigned value at address \([R2+ \text{Index16}]\).

• If Operand 2 is direct, then the immediate data is considered an unsigned value and is added to the Operand 2 register contents such that \(\text{Operand 2} = R2 + \text{Immed16}\).

• For the DIVU32 form, if Operand 1 is direct then the upper 32 bits of the result are set to 0 before storing back to the Operand 1 register.

• A divide-by-0 exception occurs if Operand 2 = 0.

### 22.8.10 EXTNDB

**Syntax:**

\[
\text{EXTNDB}\{32|64\} \{@\}R1, \{@\}R2 \{\text{Index16|Immed16}\}
\]

**Description**

Sign-extend a byte value and store the result to Operand 1. The byte can be signed extended to 32 bits (EXTNDB32) or 64 bits (EXTNDB64).

**Operation:**

\[
\text{Operand 1} \leftarrow (\text{sign extended}) \text{Operand 2}
\]

**Table 22.18: EXTNDB Instruction Encoding**

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td></td>
</tr>
</tbody>
</table>
| 7    |             | 0 = Immediate/index absent  
|      |             | 1 = Immediate/index present|
| 6    |             | 0 = 32-bit operation  
|      |             | 1 = 64-bit operation |
| 0..5 | Opcode = 0x1A |             |
| 1    | Bit         | Description |
| 7    |             | 0 = Operand 2 direct  
|      |             | 1 = Operand 2 indirect |
| 4..6 | Operand 2   |             |
| 3    |             | 0 = Operand 1 direct  
|      |             | 1 = Operand 1 indirect |
| 0..2 | Operand 1   |             |
| 2..3 | Optional 16-bit immediate data/index |             |

**Behaviors and Restrictions**
• If Operand 2 is indirect, then the immediate data is interpreted as an index, and the byte Operand 2 value is fetched from memory as a signed value at address [R2 + Index16].

• If Operand 2 is direct, then the immediate data is considered a signed immediate value, is added to the signed-extended byte from the Operand 2 register, and the byte result is sign extended to 32 or 64 bits.

• If the instruction is EXTNDB32 and Operand 1 is direct, then the 32-bit result is stored in the Operand 1 register with the upper 32 bits cleared.

22.8.11 EXTNDD

Syntax:

\[
\text{EXTNDD}[32|64] \{@\}R1, \{@\}R2 \{\text{Index16}|	ext{Immed16}\}
\]

Description

Sign-extend a 32-bit Operand 2 value and store the result to Operand 1. The Operand 2 value can be extended to 32 bits (EXTNDD32) or 64 bits (EXTNDD64).

Operation

\[\text{Operand 1} \leftarrow (\text{sign extended}) \text{Operand 2}\]

Table 22.19: EXTNDD Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit Description</td>
</tr>
<tr>
<td>7</td>
<td>0 = Immediate/index absent</td>
</tr>
<tr>
<td></td>
<td>1 = Immediate/index present</td>
</tr>
<tr>
<td>6</td>
<td>0 = 32-bit operation</td>
</tr>
<tr>
<td></td>
<td>1 = 64-bit operation</td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x1C</td>
</tr>
<tr>
<td>1</td>
<td>Bit Description</td>
</tr>
<tr>
<td>7</td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td>4..6</td>
<td>Operand 2</td>
</tr>
<tr>
<td>3</td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td>Operand 1</td>
</tr>
<tr>
<td>2..3</td>
<td>Optional 16-bit immediate</td>
</tr>
<tr>
<td></td>
<td>data/index</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

• If Operand 2 is indirect, then the immediate data is interpreted as an index, and the 32-bit value is fetched from memory as a signed value at address [R2 + Index16].
• If Operand 2 is direct, then the immediate data is considered a signed immediate value such that Operand 2 = R2 + Immed16, and the value is sign extended to 32 or 64 bits accordingly.

• If the instruction is EXTNDD32 and Operand 1 is direct, then the result is stored in the Operand 1 register with the upper 32 bits cleared.

22.8.12 EXTNDW

Syntax

\[
\text{EXTNDW}[32|64] \{@\}R1, \{@\}R2 \{\text{Index16}\} \text{Immed16}
\]

Description

Sign-extend a 16-bit Operand 2 value and store the result back to Operand 1. The value can be signed extended to 32 bits (EXTNDW32) or 64 bits (EXTNDW64).

Operation

\[
\text{Operand 1} \leftarrow (\text{sign extended}) \text{ Operand 2}
\]

Table 22.20: EXTNDW Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
</table>
| 0      | 7           | 0 = Immediate/index absent  
|        |             | 1 = Immediate/index present |
| 6      | 0 = 32-bit operation  
|        | 1 = 64-bit operation |
| 0..5   | Opcode = 0x1B |
| 1      | 7           | 0 = Operand 2 direct  
|        |             | 1 = Operand 2 indirect |
| 4..6   | Operand 2   |
| 3      | 0 = Operand 1 direct  
|        | 1 = Operand 1 indirect |
| 0..2   | Operand 1   |
| 2..3   | Optional 16-bit immediate data/index |

Behaviors and Restrictions

• If Operand 2 is indirect, then the immediate data is interpreted as an index, and the word value is fetched from memory as a signed value at address [R2 + Index16].

• If Operand 2 is direct, then the immediate data is considered a signed immediate value such that Operand 2 = R2 + Immed16, and the value is sign extended to 32 or 64 bits accordingly.
• If the instruction is EXTNDW32 and Operand 1 is direct, then the 32-bit result is stored in the Operand 1 register with the upper 32 bits cleared.

### 22.8.13 JMP

#### Syntax

<table>
<thead>
<tr>
<th>32-bit form</th>
<th>64-bit form</th>
</tr>
</thead>
<tbody>
<tr>
<td>`JMP32{cs</td>
<td>cc} {@[R1} {Immed32</td>
</tr>
</tbody>
</table>

#### Description

The JMP instruction is used to conditionally or unconditionally jump to a relative or absolute address and continue executing EBC instructions. The condition test is done using the condition bit in the VM Flags register. The JMP64 form only supports an immediate value that can be used for either a relative or absolute jump. The JMP32 form adds support for indirect addressing of the JMP offset or address. The JMP is implemented as:

```c
if (ConditionMet) {
    if (Operand.RelativeJump) {
        IP += Operand1 + SizeOfThisInstruction;
    } else {
        IP = Operand1;
    }
}
```

#### Operation

- `IP <= Operand1` (absolute address)
- `IP <= IP + SizeOfThisInstruction + Operand1` (relative address)

#### Table 22.21: JMP Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit Description</td>
</tr>
</tbody>
</table>
| 7 | 0 = Immediate/index data absent  
| | 1 = Immediate/index data present |
| 6 | 0 = JMP32  
| | 1 = JMP64 |
| 0..5 | Opcode = 0x01 |
| 1 | Bit Description |
| 7 | 0 = Unconditional jump  
| | 1 = Conditional jump |
| 6 | 0 = Jump if Flags.C is clear (cc)  
| | 1 = Jump if Flags.C is set (cs) |

continues on next page
Table 22.21 – continued from previous page

<table>
<thead>
<tr>
<th></th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>5</td>
<td>Reserved = 0</td>
</tr>
</tbody>
</table>
| 4 | 0 = Absolute address  
1 = Relative address |
| 3 | 0 = Operand 1 direct  
1 = Operand 1 indirect |
| 0..2 | Operand 1 |
| 2..5 | Optional 32-bit immediate data/index for JMP32 |
| 2..9 | 64-bit immediate data for JMP64 |

Behaviors and Restrictions

- If the instruction is JMP32, and Operand 1 register = R0, then the register contents are assumed to be 0.
- If the instruction is JMP32, and Operand 1 is indirect, then the immediate data is interpreted as an index, and the jump offset or address is fetched as a 32-bit signed value from address [R1 + Index32]
- If the instruction is JMP32, and Operand 1 is direct, then the immediate data is considered a signed immediate value such that Operand 1 = R1 + Immed32
- If the jump is unconditional, then Byte1:Bit6 (condition) is ignored
- If the instruction is JMP64, and Byte0:Bit7 is clear (no immediate data), then an instruction encoding exception is generated.
- If the instruction is JMP32, and Operand 2 is indirect, then the Operand 2 value is read as a natural value from memory address [R1 + Index32]
- An alignment check exception is generated if the jump is taken and the target address is odd.

22.8.14 JMP8

Syntax

\[ \text{JMP8}\{\text{cs|cc}\} \text{ Immed8} \]

Description

Conditionally or unconditionally jump to a relative offset and continue execution. The offset is a signed one-byte offset specified in the number of words. The offset is relative to the start of the following instruction.

Operation

\[ \text{IP} = \text{IP} + \text{SizeOfThisInstruction} + (\text{Immed8} \times 2) \]
### Table 22.22: JMP8 Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>0 = Unconditional jump</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1 = Conditional jump</td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>0 = Jump if Flags.C is clear (cc)</td>
<td></td>
</tr>
<tr>
<td></td>
<td>1 = Jump if Flags.C is set (cs)</td>
<td></td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x02</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Immediate data (signed word offset)</td>
<td></td>
</tr>
</tbody>
</table>

**Behaviors and Restrictions**
- If the jump is unconditional, then Byte0:Bit6 (condition) is ignored

### 22.8.15 LOADSP

**Syntax**

LOADSP [Flags], R2

**Description**

This instruction loads a VM dedicated register with the contents of a VM general-purpose register R0-R7. The dedicated register is specified by its index as shown in *Dedicated VM Registers*.

**Operation**

Operand 1 <= R2

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td></td>
</tr>
<tr>
<td>6..7</td>
<td>Reserved = 0</td>
<td></td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x29</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>7</td>
<td>Reserved</td>
</tr>
<tr>
<td></td>
<td>4..6</td>
<td>Operand 2 general purpose register</td>
</tr>
<tr>
<td></td>
<td>3</td>
<td>Reserved</td>
</tr>
<tr>
<td></td>
<td>0..2</td>
<td>Operand 1 dedicated register index</td>
</tr>
</tbody>
</table>

**Behaviors and Restrictions**
- Attempting to load any register (Operand 1) other than the Flags register results in an instruction encoding exception.
- Specifying a reserved dedicated register index results in an instruction encoding exception.
- If Operand 1 is the Flags register, then reserved bits in the Flags register are not modified by this instruction.
22.8.16 MOD

Syntax

```
MOD[32|64] {@}R1, {@}R2 {Index16|Immed16}
```

Description

Perform a modulus on two signed 32-bit (MOD32) or 64-bit (MOD64) operands and store the result to Operand 1.

Operation

```
Operand 1 <= Operand 1 MOD Operand 2
```

Table 22.24: MOD Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td>Description</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
| 7    |                      | 0 = Immediate/index absent  
|      |                      | 1 = Immediate/index present |
| 6    |                      | 0 = 32-bit operation  
|      |                      | 1 = 64-bit operation |
| 0..5 | Opcode = 0x12        |                  |
| 1    | Bit                  | Description      |
|      |                      |                  |
| 7    |                      | 0 = Operand 2 direct  
|      |                      | 1 = Operand 2 indirect |
| 4..6 | Operand 2            |                  |
| 3    |                      | 0 = Operand 1 direct  
|      |                      | 1 = Operand 1 indirect |
| 0..2 |                      | Operand 1        |
| 2..3 | Optional 16-bit imme-
|      | diate data/index      |                  |

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address [R2 + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value such that Operand 2 = R2 + Immed16, and the value is sign extended to 32 or 64 bits accordingly.
- If Operand 2 = 0, then a divide-by-zero exception is generated.
22.8.17 MODU

Syntax

\[
\text{MODU[32|64]} \, \{\text{@}R1, \{\text{@}R2 \, \{\text{Index16}\text{|Immed16}}\right)\]

Description
Perform a modulus on two unsigned 32-bit (MODU32) or 64-bit (MODU64) operands and store the result toOperand 1.

Operation

\[
\text{Operand 1} \, \text{<=} \, \text{Operand 1 MOD Operand 2}
\]

Table 22.25: MODU Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td>Description</td>
</tr>
<tr>
<td>7</td>
<td></td>
<td>0 = Immediate/index absent</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = Immediate/index present</td>
</tr>
<tr>
<td>6</td>
<td></td>
<td>0 = 32-bit operation</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = 64-bit operation</td>
</tr>
<tr>
<td>0..5</td>
<td>Opocode = 0x13</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Bit</td>
<td>Description</td>
</tr>
<tr>
<td>7</td>
<td></td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td>4..6</td>
<td>Operand 2</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td></td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td>Operand 1</td>
<td></td>
</tr>
<tr>
<td>2..3</td>
<td>Optional 16-bit imme-</td>
<td></td>
</tr>
<tr>
<td></td>
<td>diate data/index</td>
<td></td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R2 + Index16].
- If Operand 2 is direct, then the immediate data is considered an unsigned immediate value such that Operand 2 = R2 + Immed16.
- If Operand 2 = 0, then a divide-by-zero exception is generated.
22.8.18 MOV

Syntax

\[
\text{MOV}[b|w|d|q]{w|d} \{@\}R1 \{\text{Index16|32}\}, \{@\}R2 \{\text{Index16|32}\} \\
\text{MOVqq} \{@\}R1 \{\text{Index64}\}, \{@\}R2 \{\text{Index64}\}
\]

Description

This instruction moves data from Operand 2 to Operand 1. Both operands can be indexed, though both indexes are the same size. In the instruction syntax for the first form, the first variable character indicates the size of the data move, which can be 8 bits (b), 16 bits (w), 32 bits (d), or 64 bits (q). The optional character indicates the presence and size of the index value(s), which may be 16 bits (w) or 32 bits (d). The MOVqq instruction adds support for 64-bit indexes.

Operation

Operand 1 <= Operand 2

Table 22.26: MOV Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td></td>
</tr>
</tbody>
</table>
| 7    |             | 0 = Operand 1 index absent 
|      |             | 1 = Operand 1 index present |
| 6    |             | 0 = Operand 2 index absent 
|      |             | 1 = Operand 2 index present |
| 0..5 |             | 0x1D = MOVbw opcode 
|      |             | 0x1E = MOVww opcode 
|      |             | 0x1F = MOVdw opcode 
|      |             | 0x20 = MOVqw opcode 
|      |             | 0x21 = MOVbd opcode 
|      |             | 0x22 = MOVwd opcode 
|      |             | 0x23 = MOVdq opcode 
|      |             | 0x24 = MOVqd opcode 
|      |             | 0x28 = MOVqq opcode |
| 1    | Bit         | Description |
| 7    |             | 0 = Operand 2 direct 
|      |             | 1 = Operand 2 indirect |
| 4..6 | Operand 2   |             |
| 3    |             | 0 = Operand 1 direct 
|      |             | 1 = Operand 1 indirect |
| 0..2 | Operand 1   |             |

continues on next page
### Behaviors and Restrictions
- If an index is specified for Operand 1, and Operand 1 is direct, then an instruction encoding exception is generated.

#### 22.8.19 MOVI

**Syntax**

\[
\text{MOVI}[b|w|d|q][w|d|q] \{\#\}R1 \{\#\text{Index16}\}, \text{Immed16}|32|64
\]

**Description**

This instruction moves a signed immediate value to Operand 1. In the instruction syntax, the first variable character specifies the width of the move, which may be 8 bits (b), 16 bits (w), 32-bits (d), or 64 bits (q). The second variable character specifies the width of the immediate data, which may be 16 bits (w), 32 bits (d), or 64 bits (q).

**Operation**

\[
\text{Operand 1} \leftarrow \text{Operand 2}
\]

**Table 22.27: MOVI Instruction Encoding**

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td>Bit</td>
</tr>
</tbody>
</table>
| 6..7 | 0 = Reserved
|      | 1 = Immediate data is 16 bits (w)
|      | 2 = Immediate data is 32 bits (d)
|      | 3 = Immediate data is 64 bits (q) |
| 0..5 | Opcode = 0x37 |
| 1    | Bit Description |
| 7    | Reserved = 0 |
| 6    | 0 = Operand 1 index absent
|      | 1 = Operand 1 index present |

continues on next page
Table 22.27 – continued from previous page

<table>
<thead>
<tr>
<th>4..5</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 = 8 bit (b) move</td>
<td></td>
</tr>
<tr>
<td>1 = 16 bit (w) move</td>
<td></td>
</tr>
<tr>
<td>2 = 32 bit (d) move</td>
<td></td>
</tr>
<tr>
<td>3 = 64 bit (q) move</td>
<td></td>
</tr>
</tbody>
</table>

| 3 |
| 0 = Operand 1 direct |
| 1 = Operand 1 indirect |

| 0..2 |
| Operand 1 |

| 2..3 |
| Optional 16-bit index |

| 2..3/4..5 |
| 16-bit immediate data |

| 2..5/4..7 |
| 32-bit immediate data |

| 2..9/4..11 |
| 64-bit immediate data |

Behaviors and Restrictions

- Specifying an index value with Operand 1 direct results in an instruction encoding exception.
- If the immediate data is smaller than the move size, then the value is sign-extended to the width of the move.
- If Operand 1 is a register, then the value is stored to the register with bits beyond the move size cleared.

22.8.20 MOVIn

Syntax

```
MOVIn[w|d|q] {@[0]R1 {Index16}, Index16|32|64
```

Description

This instruction moves an indexed value of form (+n,+c) to Operand 1. The index value is converted from (+n, +c) format to a signed offset per the encoding described in Index Encoding. The size of the Operand 2 index data can be 16 (w), 32 (d), or 64 (q) bits.

Operation

Operand 1 <= Operand 2 (index value)

Table 22.28: MOVIn Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Description</td>
</tr>
<tr>
<td>6..7</td>
<td>0 = Reserved</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 2 index value is 16 bits (w)</td>
</tr>
<tr>
<td></td>
<td>2 = Operand 2 index value is 32 bits (d)</td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x38</td>
</tr>
<tr>
<td>1</td>
<td>Description</td>
</tr>
<tr>
<td>7</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

continues on next page
22.28 Table 22.28 – continued from previous page

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
</table>
| 6    | 0 = Operand 1 index absent  
|      | 1 = Operand 1 index present |
| 4..5 | Reserved = 0 |
| 3    | 0 = Operand 1 direct  
|      | 1 = Operand 1 indirect |
| 0..2 | Operand 1 |
| 2..3 | Optional 16-bit Operand 1 index |
| 2..3/4..5 | 16-bit Operand 2 index |
| 2..5/4..7 | 32-bit Operand 2 index |
| 2..9/4..11 | 64-bit Operand 2 index |

Behaviors and Restrictions
- Specifying an Operand 1 index when Operand 1 is direct results in an instruction encoding exception.
- The Operand 2 index is sign extended to the size of the move if necessary.
- If the Operand 2 index size is smaller than the move size, then the value is truncated.
- If Operand 1 is direct, then the Operand 2 value is sign extended to 64 bits and stored to the Operand 1 register.

### 22.8.21 MOVn

**Syntax**

\[
\text{MOVn}\{w|d\} \{@\}R1 \{\text{Index16}\,|\,32\}, \{@\}R2 \{\text{Index16}\,|\,32\}
\]

**Description**

This instruction loads an unsigned natural value from Operand 2 and stores the value to Operand 1. Both operands can be indexed, though both operand indexes are the same size. The operand index(s) can be 16 bits (w) or 32 bits (d).

**Operation**

\[
\text{Operand1} <= (\text{UINTN})\text{Operand2}
\]

**Table 22.29: MOVn Instruction Encoding**

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
</tr>
</tbody>
</table>
| 7    | 0 = Operand 1 index absent  
|      | 1 = Operand 1 index present |
| 6    | 0 = Operand 2 index absent  
|      | 1 = Operand 2 index present |

continues on next page
Table 22.29 – continued from previous page

<table>
<thead>
<tr>
<th>0..5</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x32 = MOVnw opcode</td>
<td></td>
</tr>
<tr>
<td>0x33 = MOVnd opcode</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>1</th>
<th>Bit Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>7</td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td>4..6</td>
<td>Operand 2</td>
</tr>
<tr>
<td>3</td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td>Operand 1</td>
</tr>
<tr>
<td>2..3</td>
<td>Optional Operand 1 16-bit index</td>
</tr>
<tr>
<td>2..3/4..5</td>
<td>Optional Operand 2 16-bit index</td>
</tr>
<tr>
<td>2..5</td>
<td>Optional Operand 1 32-bit index</td>
</tr>
<tr>
<td>2..5/6..9</td>
<td>Optional Operand 2 32-bit index</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

- If an index is specified for Operand 2, and Operand 2 register is direct, then the Operand 2 index value is added to the register contents such that Operand 2 = (UINTN)(R2 + Index).
- If an index is specified for Operand 1, and Operand 1 is direct, then an instruction encoding exception is generated.
- If Operand 1 is direct, then the Operand 2 value will be 0-extended to 64 bits on a 32-bit machine before storing to the Operand 1 register.

22.8.22 MOVREL

Syntax

```
MOVREL[w|d|q] {@}R1 {Index16}, Immed16|32|64
```

Description

This instruction fetches data at an IP-relative immediate offset (Operand 2) and stores the result to Operand 1. The offset is a signed offset relative to the following instruction. The fetched data is unsigned and may be 16 (w), 32 (d), or 64 (q) bits in size.

Operation

```
Operand 1 <= [IP + SizeOfThisInstruction + Immed]
```

Table 22.30: MOVREL Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit Description</td>
</tr>
</tbody>
</table>

continues on next page
Table 22.30 – continued from previous page

<table>
<thead>
<tr>
<th>6..7</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Reserved</td>
</tr>
<tr>
<td>1</td>
<td>Immediate data is 16 bits (w)</td>
</tr>
<tr>
<td>2</td>
<td>Immediate data is 32 bits (d)</td>
</tr>
<tr>
<td>3</td>
<td>Immediate data is 64 bits (q)</td>
</tr>
</tbody>
</table>

| 0..5 | Opcode = 0x39                                                              |
| 1    | Bit Description                                                            |
| 7    | Reserved = 0                                                                |

<table>
<thead>
<tr>
<th>6</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Operand 1 index absent</td>
</tr>
<tr>
<td>1</td>
<td>Operand 1 index present</td>
</tr>
</tbody>
</table>

| 4..5 | Reserved = 0                                                                |

<table>
<thead>
<tr>
<th>3</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Operand 1 direct</td>
</tr>
<tr>
<td>1</td>
<td>Operand 1 indirect</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>0..2</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>2..3</td>
<td>Optional 16-bit Operand 1 index</td>
</tr>
<tr>
<td>2..3/4..5</td>
<td>16-bit immediate offset</td>
</tr>
<tr>
<td>2..5/4..7</td>
<td>32-bit immediate offset</td>
</tr>
<tr>
<td>2..9/4..11</td>
<td>64-bit immediate offset</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

- If an Operand 1 index is specified and Operand 1 is direct, then an instruction encoding exception is generated.

22.8.23 MOVsn

Syntax

```
MOVsn{w} {@}R1, {Index16}, {@}R2 {Index16|Immed16}
MOVsn{d} {@}R1 {Index32}, {@}R2 {Index32|Immed32}
```

Description

Moves a signed natural value from Operand 2 to Operand 1. Both operands can be indexed, though the indexes are the same size. Indexes can be either 16 bits (MOVsnw) or 32 bits (MOVsnd) in size.

Operation

```
Operand 1 <= Operand 2
```

Table 22.31: MOVsn Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
</tr>
</tbody>
</table>

continues on next page
Table 22.31 – continued from previous page

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
</table>
| 7   | 0 = Operand 1 index absent  
     | 1 = Operand 1 index present |
| 6   | 0 = Operand 2 index/immediate data absent  
     | 1 = Operand 2 index/immediate data present |
| 0..5| 0x25 = MOVsnw opcode  
     | 0x26 = MOVsnd opcode |
| 1   | Bit |
| 7   | 0 = Operand 2 direct  
     | 1 = Operand 2 indirect |
| 4..6| Operand 2 |
| 3   | 0 = Operand 1 direct  
     | 1 = Operand 1 indirect |
| 0..2| Operand 1 |
| 2..3| Optional 16-bit Operand 1 index (MOVsnw) |
| 2..3/4..5| Optional 16-bit Operand 2 index (MOVsnw) |
| 2..5| Optional 32-bit Operand 1 index/immediate data (MOVsnd) |
| 2..5/6..9| Optional 32-bit Operand 2 index/immediate data (MOVsnd) |

Behaviors and Restrictions

- If Operand 2 is direct, and Operand 2 index/immediate data is specified, then the immediate value is read as a signed immediate value and is added to the contents of Operand 2 register such that Operand 2 = R2 + Immed.
- If Operand 2 is indirect, and Operand 2 index/immediate data is specified, then the immediate data is interpreted as an index and the Operand 2 value is fetched from memory as a signed value at address [R2 + Index16].
- If an index is specified for Operand 1, and Operand 1 is direct, then an instruction encoding exception is generated.
- If Operand 1 is direct, then the Operand 2 value is sign-extended to 64-bits on 32-bit native machines.
22.8.24 MUL

Syntax

\[ \text{MUL}[32|64] \{@\}R1, \{@\}R2 \{\text{Index16}|\text{Immed16}\} \]

Description
Perform a signed multiply of two operands and store the result back to Operand 1. The operands can be either 32 bits (MUL32) or 64 bits (MUL64).

Operation

\[ \text{Operand 1 } \leftarrow \text{Operand } \times \text{Operand 2} \]

Table 22.32: MUL Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0..5</td>
<td>Opcode = 0x0E</td>
</tr>
<tr>
<td>1</td>
<td>Bit Description</td>
</tr>
</tbody>
</table>
| 7    | 0 = Operand 2 immediate/index absent  
|      | 1 = Operand 2 immediate/index present |
| 6    | 0 = 32-bit operation  
|      | 1 = 64-bit operation |
| 4..6 | Operand 2 |
| 3    | 0 =Operand 1 direct  
|      | 1 =Operand 1 indirect |
| 0..2 | Operand 1 |
| 2..3 | Optional 16-bit Operand 2 immediate data/index |

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address [R2 + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R2 + Immed16.
- If the instruction is MUL32, and Operand 1 is direct, then the result is stored to Operand 1 register with the upper 32 bits cleared.
22.8.25 MULU

Syntax

MULU[32|64] {@}R1, {@}R2 {Index16|Immed16}

Description
Performs an unsigned multiply of two 32-bit (MULU32) or 64-bit (MULU64) operands, and stores the result back to Operand 1.

Operation

Operand 1 <= Operand * Operand 2

Table 22.33: MULU Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>7</td>
<td>0 = Operand 2 immediate/index absent</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>1 = Operand 2 immediate/index present</td>
</tr>
<tr>
<td></td>
<td>6</td>
<td>0</td>
<td>0 = 32-bit operation</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1</td>
<td>1 = 64-bit operation</td>
</tr>
<tr>
<td></td>
<td>0..5</td>
<td>Opcode</td>
<td>Opcode = 0x0F</td>
</tr>
<tr>
<td>1</td>
<td>Bit</td>
<td>Description</td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>0</td>
<td>0</td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td></td>
<td>1</td>
<td>1</td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td>4..6</td>
<td>Operand 2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>0</td>
<td>0</td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td></td>
<td>1</td>
<td>1</td>
<td>1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td>Operand 1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2..3</td>
<td>Optional</td>
<td>16-bit</td>
<td>16-bit immediate data/index</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R2 + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R2 + Immed16.
- If the instruction is MULU32 and Operand 1 is direct, then the result is written to the Operand 1 register with the upper 32 bits cleared.
22.8.26 NEG

Syntax

```
NEG[32|64] {@[}R1, {@[}R2 {Index16|Immed16}
```

Description
Multiply Operand 2 by negative 1, and store the result back to Operand 1. Operand 2 is a signed value and fetched as either a 32-bit (NEG32) or 64-bit (NEG64) value.

Operation

```
Operand 1 <= -1 * Operand 2
```

Table 22.34: NEG Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td>Description</td>
</tr>
<tr>
<td>7</td>
<td></td>
<td>0 = Operand 2 immediate/index absent</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = Operand 2 immediate/index present</td>
</tr>
<tr>
<td>6</td>
<td></td>
<td>0 = 32-bit operation</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = 64-bit operation</td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x0B</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Bit</td>
<td>Description</td>
</tr>
<tr>
<td>7</td>
<td></td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td>4..6</td>
<td>Operand 2</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td></td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td>Operand 1</td>
<td></td>
</tr>
<tr>
<td>2..3</td>
<td>Optional 16-bit</td>
<td></td>
</tr>
<tr>
<td></td>
<td>immediate data/index</td>
<td></td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address [R2 + Index16].

- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R2 + Immed16.

- If the instruction is NEG32 and Operand 1 is direct, then the result is stored in Operand 1 register with the upper 32-bits cleared.
### 22.8.27 NOT

**Syntax**

\[ \text{NOT}[32|64] \{@\}R1, \{@\}R2 \{\text{Index16}|\text{Immed16}\} \]

**Description**

Performs a logical NOT operation on Operand 2, an unsigned 32-bit (NOT32) or 64-bit (NOT64) value, and stores the result back to Operand 1.

**Operation**

\[ \text{Operand 1} \Leftarrow \text{NOT } \text{Operand 2} \]

**Table 22.35: NOT Instruction Encoding**

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Bit Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Opcode = 0x0A</td>
<td>0 = Operand 2 immediate/index absent</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = Operand 2 immediate/index present</td>
</tr>
<tr>
<td>6</td>
<td>0 = 32-bit operation</td>
<td>0 = 32-bit operation</td>
</tr>
<tr>
<td></td>
<td>1 = 64-bit operation</td>
<td></td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x0A</td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td>1</td>
<td></td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td>7</td>
<td></td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td>4..6</td>
<td></td>
<td>Operand 2</td>
</tr>
<tr>
<td>3</td>
<td></td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td></td>
<td>Operand 1</td>
</tr>
<tr>
<td>2..3</td>
<td>Optional 16-bit immediate data/index</td>
<td></td>
</tr>
</tbody>
</table>

**Behaviors and Restrictions**

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R2 + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R2 + Immed16.
- If the instruction is NOT32 and Operand 1 is a register, then the result is stored in the Operand 1 register with the upper 32 bits cleared.
22.8.28 OR

Syntax

\[
\text{OR}[32|64] \{\@\}R1, \{\@\}R2 \{\text{Index16}\text{Immed16}\}
\]

Description

Performs a bit-wise OR of two 32-bit (OR32) or 64-bit (OR64) operands, and stores the result back to Operand 1.

Operation

\[
\text{Operand 1} \leftarrow \text{Operand 1 OR Operand 2}
\]

Table 22.36: OR Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit Description</td>
</tr>
</tbody>
</table>
| 7    | 0 = Operand 2 immediate/index absent  
|      | 1 = Operand 2 immediate/index present |
| 6    | 0 = 32-bit operation  
|      | 1 = 64-bit operation |
| 0..5 | Opcode = 0x15 |
| 1    | Bit Description |
| 7    | 0 = Operand 2 direct  
|      | 1 = Operand 2 indirect |
| 4..6 | Operand 2 |
| 3    | 0 = Operand 1 direct  
|      | 1 = Operand 1 indirect |
| 0..2 | Operand 1 |
| 2..3 | Optional 16-bit immediate data/index |

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address \([R2 + \text{Index16}]\).
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that \(\text{Operand 2} = R2 + \text{Immed16}\).
- If the instruction is OR32 and Operand 1 is direct, then the result is stored to Operand 1 register with the upper 32 bits cleared.
22.8.29 POP

Syntax

```
POP[32|64] {@}R1 {Index16|Immed16}
```

Description

This instruction pops a 32-bit (POP32) or 64-bit (POP64) value from the stack, stores the result to Operand 1, and adjusts the stack pointer R0 accordingly.

Operation

```
Operand 1 <= [R0]
R0 <= R0 + 4 (POP32)
R0 <= R0 + 8 (POP64)
```

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Description</td>
</tr>
<tr>
<td></td>
<td>Bit Description</td>
</tr>
<tr>
<td>7</td>
<td>0 = Immediate/index absent</td>
</tr>
<tr>
<td></td>
<td>1 = Immediate/index present</td>
</tr>
<tr>
<td>6</td>
<td>0 = 32-bit operation</td>
</tr>
<tr>
<td></td>
<td>1 = 64-bit operation</td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x2C</td>
</tr>
<tr>
<td>1</td>
<td>Bit Description</td>
</tr>
<tr>
<td>7..4</td>
<td>Reserved = 0</td>
</tr>
<tr>
<td>3</td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td>Operand 1</td>
</tr>
<tr>
<td>2..3</td>
<td>Optional 16-bit immediate data/index</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

- If Operand 1 is direct, and an index/immediate data is specified, then the immediate data is read as a signed value and is added to the value popped from the stack, and the result stored to the Operand 1 register.
- If Operand 1 is indirect, then the immediate data is interpreted as an index, and the value popped from the stack is stored to address [R1 + Index16].
- If the instruction is POP32, and Operand 1 is direct, then the popped value is sign-extended to 64 bits before storing to the Operand 1 register.
22.8.30 POPn

Syntax

\[
\text{POPn} \{\#\} \text{R}1 \ \{\text{Index16} \| \text{Immed16}\}
\]

Description

Read an unsigned natural value from memory pointed to by stack pointer R0, adjust the stack pointer accordingly, and store the value back to Operand 1.

Operation

\[
\begin{align*}
\text{Operand 1} & \leftarrow (\text{UINTN})[\text{R}0] \\
\text{R}0 & \leftarrow \text{R}0 + \text{sizeof (VOID *)}
\end{align*}
\]

Table 22.38: POPn Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td>Description</td>
</tr>
</tbody>
</table>
| 7    |             | 0 = Immediate/index absent \\
|      |             | 1 = Immediate/index present |
| 6    |             | Reserved = 0 |
| 0..5 | Opcode      | Opcode = 0x36 |
| 1    | Bit         | Description |
| 7..4 |             | Reserved = 0 |
| 3    |             | 0 = Operand 1 direct \\
|      |             | 1 = Operand 1 indirect |
| 0..2 |             | Operand 1 |
| 2..3 | Optional 16-bit immediate data/index | |

Behaviors and Restrictions

- If Operand 1 is direct, and an index/immediate data is specified, then the immediate data is fetched as a signed value and is added to the value popped from the stack and the result is stored back to the Operand 1 register.
- If Operand 1 is indirect, and an index/immediate data is specified, then the immediate data is interpreted as a natural index and the value popped from the stack is stored at [R1 + Index16].
- If Operand 1 is direct, and the instruction is executed on a 32-bit machine, then the result is stored to the Operand 1 register with the upper 32 bits cleared.
22.8.31 PUSH

Syntax

\[
\text{PUSH}[32|64] \{@[R1 \{Index16|Immed16}\}
\]

Description

Adjust the stack pointer R0 and store a 32-bit (PUSH32) or 64-bit (PUSH64) Operand 1 value on the stack.

Operation

\[
\begin{align*}
\text{R0} &\leftarrow \text{R0} - 4 \quad \text{(PUSH32)} \\
\text{R0} &\leftarrow \text{R0} - 8 \quad \text{(PUSH64)} \\
[\text{R0}] &\leftarrow \text{Operand 1}
\end{align*}
\]

Table 22.39: PUSH Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
</tr>
</tbody>
</table>
| 7    | 0 = Immediate/index absent  \\
|      | 1 = Immediate/index present |
| 6    | 0 = 32-bit operation  \\
|      | 1 = 64-bit operation |
| 0..5 | Opcode = 0x2B |
| 1    | Bit         |
| 7..4 | Reserved = 0 |
| 3    | 0 = Operand 1 direct  \\
|      | 1 = Operand 1 indirect |
| 0..2 | Operand 1 |
| 2..3 | Optional 16-bit immediate data/index |

Behaviors and Restrictions

- If Operand 1 is direct, and an index/immediate data is specified, then the immediate data is read as a signed value and is added to the Operand 1 register contents such that \(\text{Operand 1} = \text{R1} + \text{Immed16}\).
- If Operand 1 is indirect, and an index/immediate data is specified, then the immediate data is interpreted as a natural index and the pushed value is read from \([\text{R1} + \text{Index16}]\).
22.8.32 PUSHn

Syntax

PUSHn \{@\}R1 \{Index16|Immed16\}

Description

Adjust the stack pointer R0, and store a natural value on the stack.

Operation

\[
R0 \leftarrow R0 - \text{sizeof} \ (\text{VOID}^*) \\
[R0] \leftarrow \text{Operand 1}
\]

Table 22.40: PUSHn Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
</tr>
</tbody>
</table>
| 7    | 0 = Immediate/index absent  
|      | 1 = Immediate/index present |
| 6    | Reserved = 0 |
| 0,5  | Opcode = 0x35 |
| 1    | Bit | Description |
| 7,4  | Reserved = 0 |
| 3    | 0 = Operand 1 direct  
|      | 1 = Operand 1 indirect |
| 0,2  | Operand 1 |
| 2,3  | Optional 16-bit immediate data/index |

Behaviors and Restrictions

- If Operand 1 is direct, and an index/ immediate data is specified, then the immediate data is fetched as a signed value and is added to the Operand 1 register contents such that Operand 1 = R1 + Immed16.
- If Operand 1 is indirect, and an index/immediate data is specified, then the immediate data is interpreted as a natural index and the Operand 1 value pushed is fetched from [R1 + Index16].

22.8.33 RET

Syntax

RET

Description

This instruction fetches the return address from the stack, sets the IP to the value, adjusts the stack pointer register R0, and continues execution at the return address. If the RET is a final return from the EBC driver, then execution control returns to the caller, which may be EBC or native code.

Operation
$\text{IP} \leftarrow [\text{R0}]$

$\text{R0} \leftarrow \text{R0} + 16$

### Table 22.41: RET Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td>Description</td>
</tr>
<tr>
<td>6..7</td>
<td>Reserved = 0</td>
<td></td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x04</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Reserved = 0</td>
<td></td>
</tr>
</tbody>
</table>

### Behaviors and Restrictions

- An alignment exception will be generated if the return address is not aligned on a 16-bit boundary.

### 22.8.34 SHL

#### Syntax

SHL[32|64] {@[}R1, {@[}R2 {Index16|Immed16}

#### Description

Left-shifts Operand 1 by Operand 2 bit positions and stores the result back to Operand 1. The operand sizes may be either 32-bits (SHL32) or 64 bits (SHL64).

#### Operation

$\text{Operand 1} \leftarrow \text{Operand 1} \ll \text{Operand 2}$

### Table 22.42: SHL Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td>Description</td>
</tr>
</tbody>
</table>
| 7    | 0 = Operand 2 immediate/index absent  
|      | 1 = Operand 2 immediate/index present |
| 6    | 0 = 32-bit operation  
|      | 1 = 64-bit operation |
| 0..5 | Opcode = 0x17 |
| 1    | Bit         |
| 7    | 0 = Operand 2 direct  
|      | 1 = Operand 2 indirect |
| 4..6 | Operand 2 |

continues on next page
Behaviors and Restrictions

• If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address \([R2 + \text{Index16}]\).

• If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = \(R2 + \text{Immed16}\).

• If the instruction is SHL\(_{32}\), and Operand 1 is direct, then the result is stored to the Operand 1 register with the upper 32 bits cleared.

### 22.8.35 SHR

**Syntax**

\[
\text{SHR[32|64] } \{@\}R1, \{@\}R2 \{\text{Index16}\|\text{Immed16}\}
\]

**Description**

Right-shifts unsigned Operand 1 by Operand 2 bit positions and stores the result back to Operand 1. The operand sizes may be either 32-bits (SHR\(_{32}\)) or 64 bits (SHR\(_{64}\)).

**Operation**

\[
\text{Operand 1} \leftarrow \text{Operand 1} \gg \text{Operand 2}
\]

### Table 22.43: SHR Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td>Description</td>
</tr>
<tr>
<td>7</td>
<td></td>
<td>0 = Operand 2 immediate/index absent</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = Operand 2 immediate/index present</td>
</tr>
<tr>
<td>6</td>
<td></td>
<td>0 = 32-bit operation</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = 64-bit operation</td>
</tr>
<tr>
<td>0..5</td>
<td>0 = Opcode 0x18</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Bit</td>
<td>Description</td>
</tr>
<tr>
<td>7</td>
<td></td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td>4..6</td>
<td>Operand 2</td>
<td></td>
</tr>
</tbody>
</table>

continues on next page
Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address \([R2 + \text{Index16}]\).
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R2 + Immed16.
- If the instruction is SHR32, and Operand 1 is direct, then the result is stored to the Operand 1 register with the upper 32 bits cleared.

### 22.8.36 STORESP

**Syntax**

\[
\text{STORESP R1, [IP|Flags]}
\]

**Description**

This instruction transfers the contents of a dedicated register to a general-purpose register. See the Table, below, *Dedicated VM Registers* for the VM dedicated registers and their corresponding index values.

**Operation**

\[
\text{Operand 1} \iff \text{Operand 2}
\]

**Table 22.44: STORESP Instruction Encoding**

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
</tr>
<tr>
<td></td>
<td>Description</td>
</tr>
<tr>
<td>6..7</td>
<td>Reserved = 0</td>
</tr>
<tr>
<td>0..5</td>
<td>Opcode = 0x2A</td>
</tr>
<tr>
<td>1</td>
<td>7</td>
</tr>
<tr>
<td></td>
<td>Reserved = 0</td>
</tr>
<tr>
<td></td>
<td>4..6</td>
</tr>
<tr>
<td></td>
<td>Operand 2 dedicated register index</td>
</tr>
<tr>
<td>3</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>Reserved = 0</td>
</tr>
<tr>
<td>0..2</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>Operand 1 general purpose register</td>
</tr>
</tbody>
</table>

**Behaviors and Restrictions**

- Specifying an invalid dedicated register index results in an instruction encoding exception.
22.8.37 SUB

Syntax

\[
\text{SUB}[32|64] \{\@\}R1, \{\@\}R2 \{\text{Index16|Immed16}\}
\]

Description

Subtracts a 32-bit (SUB32) or 64-bit (SUB64) signed Operand 2 value from a signed Operand 1 value of the same size, and stores the result to Operand 1.

Operation

\[
\text{Operand 1} \leftarrow \text{Operand 1} - \text{Operand 2}
\]

Table 22.45: SUB Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td><strong>Bit</strong> Description</td>
</tr>
<tr>
<td></td>
<td>7</td>
</tr>
<tr>
<td></td>
<td>0 = Operand 2 immediate/index absent</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 2 immediate/index present</td>
</tr>
<tr>
<td></td>
<td>6</td>
</tr>
<tr>
<td></td>
<td>0 = 32-bit operation</td>
</tr>
<tr>
<td></td>
<td>1 = 64-bit operation</td>
</tr>
<tr>
<td></td>
<td>0..5</td>
</tr>
<tr>
<td></td>
<td>Opcode = Ox0D</td>
</tr>
<tr>
<td>1</td>
<td><strong>Bit</strong> Description</td>
</tr>
<tr>
<td></td>
<td>7</td>
</tr>
<tr>
<td></td>
<td>0 = Operand 2 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 2 indirect</td>
</tr>
<tr>
<td></td>
<td>4..6</td>
</tr>
<tr>
<td></td>
<td>Operand 2</td>
</tr>
<tr>
<td>3</td>
<td>0</td>
</tr>
<tr>
<td></td>
<td>0 = Operand 1 direct</td>
</tr>
<tr>
<td></td>
<td>1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td><strong>Operand</strong></td>
</tr>
<tr>
<td>2..3</td>
<td>Optional 16-bit immediate data/index</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as a signed value at address \([R2 + \text{Index16}]\).
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = \(R2 + \text{Immed16}\).
- If the instruction is SUB32 and Operand 1 is direct, then the result is stored to theOperand 1 register with the upper 32 bits cleared.
22.8.38 XOR

Syntax

\[
\text{XOR}[32|64] \{@\text{R1}, \{@\text{R2} \{\text{Index16|Immed16}\}
\]

Description

Performs a bit-wise exclusive OR of two 32-bit (XOR32) or 64-bit (XOR64) operands, and stores the result back to Operand 1.

Operation

\[
\text{Operand 1} \leftarrow \text{Operand 1 XOR Operand 2}
\]

Table 22.46: XOR Instruction Encoding

<table>
<thead>
<tr>
<th>BYTE</th>
<th>Description</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Bit</td>
<td>Description</td>
</tr>
<tr>
<td></td>
<td>7</td>
<td>0 = Operand 2 immediate/index absent&lt;br&gt;1 = Operand 2 immediate/index present</td>
</tr>
<tr>
<td></td>
<td>6</td>
<td>0 = 32-bit operation&lt;br&gt;1 = 64-bit operation</td>
</tr>
<tr>
<td></td>
<td>0..5</td>
<td>Opcode = 0x16</td>
</tr>
<tr>
<td>1</td>
<td>Bit</td>
<td>Description</td>
</tr>
<tr>
<td></td>
<td>7</td>
<td>0 = Operand 2 direct&lt;br&gt;1 = Operand 2 indirect</td>
</tr>
<tr>
<td></td>
<td>4..6</td>
<td>Operand 2</td>
</tr>
<tr>
<td>3</td>
<td></td>
<td>0 = Operand 1 direct&lt;br&gt;1 = Operand 1 indirect</td>
</tr>
<tr>
<td>0..2</td>
<td></td>
<td>Operand 1</td>
</tr>
<tr>
<td>2..3</td>
<td>Optional 16-bit immediate data/index</td>
<td></td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

- If Operand 2 is indirect, then the immediate data is interpreted as an index, and the Operand 2 value is fetched from memory as an unsigned value at address [R2 + Index16].
- If Operand 2 is direct, then the immediate data is considered a signed immediate value and is added to the Operand 2 register contents such that Operand 2 = R2 + Immed16.
- If the instruction is XOR32 and Operand1 is direct, then the result is stored to the Operand 1 register with the upper 32-bits cleared.
22.9 Runtime and Software Conventions

22.9.1 Calling Outside VM

Calls can be made to routines in other modules that are native or in another VM. It is the responsibility of the calling VM to prepare the outgoing arguments correctly to make the call outside the VM. It is also the responsibility of the VM to prepare the incoming arguments correctly for the call from outside the VM. Calls outside the VM must use the CALLEX \textit{CALL} instruction.

22.9.2 Calling Inside VM

Calls inside VM can be made either directly using the \textit{CALL} or \textit{CALLEX} instructions. Using direct \textit{CALL} instructions is an optimization.

22.9.3 Parameter Passing

Parameters are pushed on the VM stack per the CDECL calling convention. Per this convention, the last argument in the parameter list is pushed on the stack first, and the first argument in the parameter list is pushed on the stack last.

All parameters are stored or accessed as natural size (using naturally sized instruction) except 64-bit integers, which are pushed as 64-bit values. 32-bit integers are pushed as natural size (since they should be passed as 64-bit parameter values on 64-bit machines).

22.9.4 Return Values

Return values of 8 bytes or less in size are returned in general-purpose register R7. Return values larger than 8 bytes are not supported.

22.9.5 Binary Format

PE32+ format will be used for generating binaries for the VM. A VarBss section will be included in the binary image. All global and static variables will be placed in this section. The size of the section will be based on worst-case 64-bit pointers. Initialized data and pointers will also be placed in the VarBss section, with the compiler generating code to initialize the values at runtime.

22.10 Architectural Requirements

This section provides a high level overview of the architectural requirements that are necessary to support execution of EBC on a platform.
22.10.1 EBC Image Requirements

All EBC images will be PE32+ format. Some minor additions to the format will be required to support EBC images. See the Microsoft Portable Executable and Common Object File Format Specification pointed to in Appendix Q — References for details of this image file format.

A given EBC image must be executable on different platforms, independent of whether it is a 32- or 64-bit processor. All EBC images should be driver implementations.

22.10.2 EBC Execution Interfacing Requirements

EBC drivers will typically be designed to execute in an (usually preboot) EFI environment. As such, EBC drivers must be able to invoke protocols and expose protocols for use by other drivers or applications. The following execution transitions must be supported:

- EBC calling EBC
- EBC calling native code
- Native code calling EBC
- Native code calling native code
- Returning from all the above transitions

Obviously native code calling native code is available by default, so is not discussed in this document.

To maintain backward compatibility with existing native code, and minimize the overhead for non-EBC drivers calling EBC protocols, all four transitions must be seamless from the application perspective. Therefore, drivers, whether EBC or native, shall not be required to have any knowledge of whether or not the calling code, or the code being called, is native or EBC compiled code. The onus is put on the tools and interpreter to support this requirement.

22.10.3 Interfacing Function Parameters Requirements

To allow code execution across protocol boundaries, the interpreter must ensure that parameters passed across execution transitions are handled in the same manner as the standard parameter passing convention for the native processor.

22.10.4 Function Return Requirements

The interpreter must support standard function returns to resume execution to the caller of external protocols. The details of this requirement are specific to the native processor. The called function must not be required to have any knowledge of whether or not the caller is EBC or native code.

22.10.5 Function Return Values Requirements

The interpreter must support standard function return values from called protocols. The exact implementation of this functionality is dependent on the native processor. This requirement applies to return values of 64 bits or less. The called function must not be required to have any knowledge of whether or not the caller is EBC or native code. Note that returning of structures is not supported.
22.11 EBC Interpreter Protocol

The EFI EBC protocol provides services to execute EBC images, which will typically be loaded into option ROMs.

22.11.1 EFI_EBC_PROTOCOL

Summary

This protocol provides the services that allow execution of EBC images.

GUID

```
#define EFI_EBC_PROTOCOL_GUID \
{0x13ac6dd1,0x73d0,0x11d4,\ 
{0xb0,0x6b,0x00,0xaa,0x00,0xb0,0x6d,0xe7}}
```

Protocol Interface Structure

```
typedef struct _EFI_EBC_PROTOCOL {
    EFI_EBC_CREATEThunk CreateThunk;
    EFI_EBC_UNLOAD_IMAGE UnloadImage;
    EFI_EBC_REGISTER_ICACHE_FLUSH RegisterICacheFlush;
    EFI_EBC_GET_VERSION GetVersion;
} EFI_EBC_PROTOCOL;
```

Parameters

CreateThunk

Creates a thunk for an EBC image entry point or protocol service, and returns a pointer to the thunk. See the `EFI_EBC_PROTOCOL.CreateThunk()` function description.

UnloadImage

Called when an EBC image is unloaded to allow the interpreter to perform any cleanup associated with the image’s execution. See the `EFI_EBC_PROTOCOL.UnloadImage()` function description.

RegisterICacheFlush

Called to register a callback function that the EBC interpreter can call to flush the processor instruction cache after creating thunks. See the `EFI_EBC_PROTOCOL.RegisterICacheFlush()` function description.

GetVersion

Called to get the version of the associated EBC interpreter. See the `EFI_EBC_PROTOCOL.GetVersion()` function description.

Description

The EFI EBC protocol provides services to load and execute EBC images, which will typically be loaded into option ROMs. The image loader will load the EBC image, perform standard relocations, and invoke the `EFI_EBC_PROTOCOL.CreateThunk()` service to create a thunk for the EBC image’s entry point. The image can then be run using the standard EFI start image services.
22.11.2 EFI_EBC_PROTOCOL.CreateThunk()

Summary
Creates a thunk for an EBC entry point, returning the address of the thunk.

Prototype

```c
typedef EFI_STATUS
(EIFIAPI *EFI_EBC_CREATEThunk) (
    IN EFI_EBC_PROTOCOL *This,
    IN EFI_HANDLE ImageHandle,
    IN VOID *EbcEntryPoint,
    OUT VOID **Thunk
);
```

Parameters

This
A pointer to the EFI_EBC_PROTOCOL instance. This protocol is defined in EBC Interpreter Protocol.

ImageHandle
Handle of image for which the thunk is being created.

EbcEntryPoint
Address of the actual EBC entry point or protocol service the thunk should call.

Thunk
Returned pointer to a thunk created.

Description
A PE32+ EBC image, like any other PE32+ image, contains an optional header that specifies the entry point for image execution. However for EBC images this is the entry point of EBC instructions, so is not directly executable by the native processor. Therefore when an EBC image is loaded, the loader must call this service to get a pointer to native code (thunk) that can be executed which will invoke the interpreter to begin execution at the original EBC entry point.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Image entry point is not 2-byte aligned.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Memory could not be allocated for the thunk.</td>
</tr>
</tbody>
</table>

22.11.3 EFI_EBC_PROTOCOL.UnloadImage()

Summary
Called prior to unloading an EBC image from memory.

Prototype

```c
typedef EFI_STATUS
(EIFIAPI *EFI_EBC_UNLOAD_IMAGE) (
    IN EFI_EBC_PROTOCOL *This,
    IN EFI_HANDLE ImageHandle
);
```
Parameters

This

A pointer to the `EFI_EBC_PROTOCOL` instance. This protocol is defined in `EBC Interpreter Protocol`.

ImageHandle

Image handle of the EBC image that is being unloaded from memory.

Description

This function is called after an EBC image has exited, but before the image is actually unloaded. It is intended to provide the interpreter with the opportunity to perform any cleanup that may be necessary as a result of loading and executing the image.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Image handle is not recognized as belonging to an EBC image that has been executed.</td>
</tr>
</tbody>
</table>

22.11.4 EFI_EBC_PROTOCOL.RegisterICacheFlush()

Summary

Registers a callback function that the EBC interpreter calls to flush the processor instruction cache following creation of thunks.

Prototype

```c
typedef EFI_STATUS (* EFI_EBC_REGISTER_ICACHE_FLUSH) (IN EFI_EBC_PROTOCOL **This,
                                                      IN EBC_ICACHE_FLUSH *Flush);
```

Parameters

This

A pointer to the `EFI_EBC_PROTOCOL` instance. This protocol is defined in `EBC Interpreter Protocol`.

Flush

Pointer to a function of type `EBC_ICACH_FLUSH`. See “Related Definitions” below for a detailed description of this type.

Related Definitions

```c
typedef EFI_STATUS (* EBC_ICACHE_FLUSH) (IN EFI_PHYSICAL_ADDRESS Start,
                                          IN UINT64 Length);
```

Start

The beginning physical address to flush from the processor’s instruction cache.
Length

The number of bytes to flush from the processor’s instruction cache.

This is the prototype for the Flush callback routine. A pointer to a routine of this type is passed to the EBC EFI_EBC_REGISTER_ICACHE_FLUSH protocol service.

Description

An EBC image’s original PE32+ entry point is not directly executable by the native processor. Therefore to execute an EBC image, a thunk (which invokes the EBC interpreter for the image’s original entry point) must be created for the entry point, and the thunk is executed when the EBC image is started. Since the thunks may be created on-the-fly in memory, the processor’s instruction cache may require to be flushed after thunks are created. The caller to this EBC service can provide a pointer to a function to flush the instruction cache for any thunks created after the EFI_EBC_PROTOCOL.CreateThunk() service has been called. If an instruction-cache flush callback is not provided to the interpreter, then the interpreter assumes the system has no instruction cache, or that flushing the cache is not required following creation of thunks.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
</tbody>
</table>

22.11.5 EFI_EBC_PROTOCOL.GetVersion()

Summary

Called to get the version of the interpreter.

Prototype

```c
typedef
EFI_STATUS
(* EFI_EBC_GET_VERSION) (
    IN EFI_EBC_PROTOCOL *This,
    OUT UINT64 *Version
);
```

Parameters

This

A pointer to the EFI_EBC_PROTOCOL instance. This protocol is defined in EBC Interpreter Protocol.

Version

Pointer to where to store the returned version of the interpreter.

Description

This function is called to get the version of the loaded EBC interpreter. The value and format of the returned version is identical to that returned by the EBC BREAK 1 instruction.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Version pointer is NULL.</td>
</tr>
</tbody>
</table>
22.12 EBC Tools

22.12.1 EBC C Compiler

This section describes the responsibilities of the EBC C compiler. To fully specify these responsibilities requires that the thunking mechanisms between EBC and native code be described.

22.12.2 C Coding Convention

The EBC C compiler supports only the C programming language. There is no support for C++, inline assembly, floating point types/operations, or C calling conventions other than CDECL.

Pointer type in C is supported only as 64-bit pointer. The code should be 64-bit pointer ready (not assign pointers to integers and vice versa).

The compiler does not support user-defined sections through pragmas.

Global variables containing pointers that are initialized will be put in the uninitialized VarBss section and the compiler will generate code to initialize these variables during load time. The code will be placed in an init text section. This compiler-generated code will be executed before the actual image entry point is executed.

22.12.3 EBC Interface Assembly Instructions

The EBC instruction set includes two forms of a CALL instruction that can be used to invoke external protocols. Their assembly language formats are:

```
CALLEX Immed64
CALLEX32 @R1 {Immed32}
```

Both forms can be used to invoke external protocols at an absolute address specified by the immediate data and/or register operand. The second form also supports jumping to code at a relative address. When one of these instructions is executed, the interpreter is responsible for thunking arguments and then jumping to the destination address. When the called function returns, code begins execution at the EBC instruction following the CALL instruction. The process by which this happens is called thunking. Later sections describe this operation in detail.

22.12.4 Stack Maintenance and Argument Passing

There are several EBC assembly instructions that directly manipulate the stack contents and stack pointer. These instructions operate on the EBC stack, not the interpreter stack. The instructions include the EBC PUSH, POP, PUSHN, and POPN, and all forms of the MOV instructions.

These instructions must adjust the EBC stack pointer in the same manner as equivalent instructions of the native instruction set. With this implementation, parameters pushed on the stack by an EBC driver can be accessed normally for stack-based native code. If native code expects parameters in registers, then the interpreter thunking process must transfer the arguments from EBC stack to the appropriate processor registers. The process would need to be reversed when native code calls EBC.
22.12.5 Native to EBC Arguments Calling Convention

The calling convention for arguments passed to EBC functions follows the standard CDECL calling convention. The arguments must be pushed as their native size. After the function arguments have been pushed on the stack, execution is passed to the called EBC function. The overhead of thunking the function parameters depends on the standard parameter passing convention for the host processor. The implementation of this functionality is left to the interpreter.

22.12.6 EBC to Native Arguments Calling Convention

When EBC makes function calls via function pointers, the EBC C compiler cannot determine whether the calls are to native code or EBC. It therefore assumes that the calls are to native code, and emits the appropriate EBC CALL instructions. To be compatible with calls to native code, the calling convention of EBC calling native code must follow the parameter passing convention of the native processor. The EBC C compiler generates EBC instructions that push all arguments on the stack. The interpreter is then responsible for performing the necessary thunking. The exact implementation of this functionality is left to the interpreter.

22.12.7 EBC to EBC Arguments Calling Convention

If the EBC C compiler is able to determine that a function call is to a local function, it can emit a standard EBC CALL instruction. In this case, the function arguments are passed as described in the other sections of this specification.

22.12.8 Function Returns

When EBC calls an external function, the thunking process includes setting up the host processor stack or registers such that when the called function returns, execution is passed back to the EBC at the instruction following the call. The implementation is left to the interpreter, but it must follow the standard function return process of the host processor. Typically this will require the interpreter to push the return address on the stack or move it to a processor register prior to calling the external function.

22.12.9 Function Return Values

EBC function return values of 8 bytes or less are returned in VM general-purpose register R7. Returning values larger than 8 bytes on the stack is not supported. Instead, the caller or callee must allocate memory for the return value, and the caller can pass a pointer to the callee, or the callee can return a pointer to the value in the standard return register R7.

If an EBC function returns to native code, then the interpreter thunking process is responsible for transferring the contents of R7 to an appropriate location such that the caller has access to the value using standard native code. Typically the value will be transferred to a processor register. Conversely, if a native function returns to an EBC function, the interpreter is responsible for transferring the return value from the native return memory or register location into VM register R7.
22.12.10 Thunking

Thunking is the process by which transitions between execution of native and EBC are handled. The major issues that must be addressed for thunking are the handling of function arguments, how the external function is invoked, and how return values and function returns are handled. The following sections describe the thunking process for the possible transitions.

22.12.10.1 Thunking EBC to Native Code

By definition, all external calls from within EBC are calls to native code. The EBC CALL instructions are used to make these calls. A typical application for EBC calling native code would be a simple “Hello World” driver. For a UEFI driver, the code could be written as shown below.

```c
EFI_STATUS EfiMain (
    IN EFI_HANDLE ImageHandle,
    IN EFI_SYSTEM_TABLE *ST
)
{
    ST->ConOut->OutputString(ST->ConOut, L"Hello World!");
    return EFI_SUCCESS;
}
```

This C code, when compiled to EBC assembly, could result in two PUSHn instructions to push the parameters on the stack, some code to get the absolute address of the `EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL.OutputString()` function, then a CALL instruction to jump to native code. Typical pseudo assembly code for the function call could be something like the following:

- PUSHn _HelloString
- PUSHn _ConOut
- MOVnw R1, _OutputString
- CALL EX64 R1

The interpreter is responsible for executing the PUSHn instructions to push the arguments on the EBC stack when interpreting the PUSHn instructions. When the CALL EX64 instruction is encountered, it must thunk to external native code. The exact thunking mechanism is native processor dependent. For example, a supported 32-bit thunking implementation could simply move the system stack pointer to point to the EBC stack, then perform a CALL to the absolute address specified in VM register R1. However, the function calling convention for the Itanium processor family calls for the first 8 function arguments being passed in registers. Therefore, the Itanium processor family thunking mechanism requires the arguments to be copied from the EBC stack into processor registers. Then a CALL can be performed to jump to the absolute address in VM register R1. Note that since the interpreter is not aware of the number of arguments to the function being called, the maximum amount of data may be copied from the EBC stack into processor registers.

22.12.10.2 Thunking Native Code to EBC

An EBC driver may install protocols for use by other EBC drivers, or UEFI drivers or applications. These protocols provide the mechanism by which external native code can call EBC. Typical C code to install a generic protocol is shown below.

```c
EFI_STATUS Foo(UINT32 Arg1, UINT32 Arg2);

MyProtInterface->Service1 = Foo;
```

(continues on next page)
To support thunking native code to EBC, the EBC compiler resolves all EBC function pointers using one level of indirection. In this way, the address of an EBC function actually becomes the address of a piece of native (thunk) code that invokes the interpreter to execute the actual EBC function. As a result of this implementation, any time the address of an EBC function is taken, the EBC C compiler must generate the following:

- A 64-bit function pointer data object that contains the actual address of the EBC function
- EBC initialization code that is executed before the image entry point that will execute EBC `BREAK` 5 instructions to create thunks for each function pointer data object
- Associated relocations for the above

So for the above code sample, the compiler must generate EBC initialization code similar to the following. This code is executed prior to execution of the actual EBC driver’s entry point.

```
MOVq R7, Foo_pointer ; get address of Foo pointer
BREAK 5 ; create a thunk for the function
```

The `BREAK` instruction causes the interpreter to create native thunk code elsewhere in memory, and then modify the memory location pointed to by R7 to point to the newly created thunk code for EBC function Foo. From within EBC, when the address of Foo is taken, the address of the thunk is actually returned. So for the assignment of the protocol `Service1` above, the EBC C compiler will generate something like the following:

```
MOVq R7, Foo_pointer ; get address of Foo function pointer
MOVq R7, @R7 ; one level of indirection
MOVn R6, _MyProtInterface->Service1 ; get address of variable
MOVq @R6, R7 ; address of thunk to ->Service1
```

### 22.12.10.3 Thunking EBC to EBC

EBC can call EBC via function pointers or protocols. These two mechanisms are treated identically by the EBC C compiler, and are performed using EBC `CALL` instructions. For EBC to call EBC, the EBC being called must have provided the address of the function. As described above, the address is actually the address of native thunk code for the actual EBC function. Therefore, when EBC calls EBC, the interpreter assumes native code is being called so prepares function arguments accordingly, and then makes the call. The native thunk code assumes native code is calling EBC, so will basically “undo” the preparation of function arguments, and then invoke the interpreter to execute the actual EBC function of interest.

### 22.12.11 EBC Linker

New constants must be defined for use by the linker in processing EBC images. For EBC images, the linker must set the machine type in the PE file header accordingly to indicate that the image contains EBC.

```
#define IMAGE_FILE_MACHINE_EBC 0x0EBC
```

In addition, the linker must support EBC images with of the following subsystem types as set in a PE32+ optional header:
For EFI EBC images and object files, the following relocation types must be supported:

```c
#define IMAGE_REL_EBC_ABSOLUTE 0x0000
#define IMAGE_REL_EBC_ADDR32NB 0x0001
#define IMAGE_REL_EBC_REL32 0x0002
#define IMAGE_REL_EBC_SECTION 0x0003
#define IMAGE_REL_EBC_SECREL 0x0004
```

The ADDR32NB relocation is used internally to the linker when RVAs are emitted. It also is used for version resources which probably will not be used. The REL32 relocation is for PC relative addressing on code. The SECTION and SECREL relocations are used for debug information.

### 22.12.12 Image Loader

The EFI image loader is responsible for loading an executable image into memory and applying relocation information so that an image can execute at the address in memory where it has been loaded prior to execution of the image. For EBC images, the image loader must also invoke the interpreter protocol to create a thunk for the image entry point and return the address of this thunk. After loading the image in this manner, the image can be executed in the standard manner. To implement this functionality, only minor changes will be made to EFI service `EFI_BOOT_SERVICES.LoadImage()`, and no changes should be made to `EFI_BOOT_SERVICES.StartImage()`.

After the image is unloaded, the EFI image load service must call the EBC `EFI_BOOT_SERVICES.UnloadImage()` service to perform any cleanup to complete unloading of the image. Typically this will include freeing up any memory allocated for thunks for the image during load and execution.

### 22.12.13 Debug Support

The interpreter must support debugging in an EFI environment per the EFI debug support protocol.

### 22.13 VM Exception Handling

This section lists the different types of exceptions that the VM may assert during execution of an EBC image. If a debugger is attached to the EBC driver via the EFI debug support protocol, then the debugger should be able to capture and identify the exception type. If a debugger is not attached, then depending on the severity of the exception, the interpreter may do one of the following:

- Invoke the EFI ASSERT() macro, which will typically display an error message and halt the system
- Sit in a while(1) loop to hang the system
- Ignore the exception and continue execution of the image (minor exceptions only)

It is a platform policy decision as to the action taken in response to EBC exceptions. The following sections describe the exceptions that may be generated by the VM.

---

**Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A**
22.13.1 Divide By 0 Exception

A divide-by-0 exception can occur for the EBC instructions `DIV`, `DIVU`, `MOD`, and `MODU`.

22.13.2 Debug Break Exception

A debug break exception occurs if the VM encounters a `BREAK` instruction with a break code of 3.

22.13.3 Invalid Opcode Exception

An invalid opcode exception will occur if the interpreter encounters a reserved opcode during execution.

22.13.4 Stack Fault Exception

A stack fault exception can occur if the interpreter detects that function nesting within the interpreter or system interrupts was sufficient to potentially corrupt the EBC image’s stack contents. This exception could also occur if the EBC driver attempts to adjust the stack pointer outside the range allocated to the driver.

22.13.5 Alignment Exception

An alignment exception can occur if the particular implementation of the interpreter does not support unaligned accesses to data or code. It may also occur if the stack pointer or instruction pointer becomes misaligned.

22.13.6 Instruction Encoding Exception

An instruction encoding exception can occur for the following:

- For some instructions, if an Operand 1 index is specified and Operand 1 is direct
- If an instruction encoding has reserved bits set to values other than 0
- If an instruction encoding has a field set to a reserved value.

22.13.7 Bad Break Exception

A bad break exception occurs if the VM encounters a `BREAK` instruction with a break code of 0, or any other unrecognized or unsupported break code.

22.13.8 Undefined Exception

An undefined exception can occur for other conditions detected by the VM. The cause of such an exception is dependent on the VM implementation, but will most likely include internal VM faults.
22.14 Option ROM Formats

The new option ROM capability is designed to be a departure from the legacy method of formatting an option ROM. PCI local bus add-in cards are the primary targets for this design although support for future bus types will be added as necessary. EFI EBC drivers can be stored in option ROMs or on hard drives in an EFI system partition.

The new format defined for the UEFI specification is intended to coexist with legacy format PCI Expansion ROM images. This provides the ability for IHVs to make a single option ROM binary that contains both legacy and new format images at the same time. This is important for the ability to have single add-in card SKUs that can work in a variety of systems both with and without native support for UEFI. Support for multiple image types in this way provides a smooth migration path during the period before widespread adoption of UEFI drivers as the primary means of support for software needed to accomplish add-in card operation in the pre-OS boot timeframe.

22.14.1 EFI Drivers for PCI Add-in Cards

The location mechanism for UEFI drivers in PCI option ROM containers is described fully in EFI_BUS_SPECIFIC_DRIVER_OVERRIDE_PROTOCOL. Readers should refer to this section for complete details of the scheme and associated data structures.

22.14.2 Non-PCI Bus Support

EFI expansion ROMs are not supported on any other bus besides PCI local bus in the current revision of the UEFI specification.

This means that support for UEFI drivers in legacy ISA add-in card ROMs is explicitly excluded.

Support for UEFI drivers to be located on add-in card type devices for future bus designs other than PCI local bus will be added to future revisions of the UEFI specification. This support will depend upon the specifications that govern such new bus designs with respect to the mechanisms defined for support of driver code on devices.
The UEFI Firmware Management Protocol provides an abstraction for device to provide firmware management support. The base requirements for managing device firmware images include identifying firmware image revision level and programming the image into the device. The protocol for managing firmware provides the following services.

- Get the attributes of the current firmware image. Attributes include revision level.
- Get a copy of the current firmware image. As an example, this service could be used by a management application to facilitate a firmware roll-back.
- Program the device with a firmware image supplied by the user.
- Label all the firmware images within a device with a single version.

When UEFI Firmware Management Protocol (FMP) instance is intended to perform the update of an option ROM loaded from a PCI or PCI Express device, it is recommended that the FMP instance be attached to the handle with `EFI_LOADED_IMAGE_PROTOCOL` for said Option ROM.

When the FMP instance is intended to update internal device firmware, or a combination of device firmware and Option ROM, the FMP instance may instead be attached to the Controller handle of the device. However in the case where multiple devices represented by multiple controller handles are served by the same firmware store, only a single Controller handle should expose FMP. In all cases a specific updatable hardware firmware store must be represented by exactly one FMP instance.

Care should be taken to ensure that the FMP instance reports current version data that accurately represents the actual contents of the firmware store of the device exposing FMP, because in some cases the device driver currently operating the device may have been loaded from another device or media.

### 23.1 Firmware Management Protocol

#### 23.1.1 EFI_FIRMWARE_MANAGEMENT_PROTOCOL

**Summary**

Firmware Management application invokes this protocol to manage device firmware.

**GUID**

```c
// {86C77A67-0B97-4633-A187-49104D0685C7}
#define EFI_FIRMWARE_MANAGEMENT_PROTOCOL_GUID
{ 0x86c77a67, 0xb97, 0x4633, \
  {0xa1, 0x87, 0x49, 0x10, 0x4d, 0x06, 0x85, 0xc7 }}
```

**Protocol**
typedef struct _EFI_FIRMWARE_MANAGEMENT_PROTOCOL {
    EFI_FIRMWARE_MANAGEMENT_PROTOCOL_GET_IMAGE_INFO GetImageInfo;
    EFI_FIRMWARE_MANAGEMENT_PROTOCOL_GET_IMAGE GetImage;
    EFI_FIRMWARE_MANAGEMENT_PROTOCOL_SET_IMAGE SetImage;
    EFI_FIRMWARE_MANAGEMENT_PROTOCOL_CHECK_IMAGE CheckImage;
    EFI_FIRMWARE_MANAGEMENT_PROTOCOL_GET_PACKAGE_INFO GetPackageInfo;
    EFI_FIRMWARE_MANAGEMENT_PROTOCOL_SET_PACKAGE_INFO SetPackageInfo;
} EFI_FIRMWARE_MANAGEMENT_PROTOCOL;

Members

GetImageInfo
Returns information about the current firmware image(s) of the device.

GetImage
Retrieves a copy of the current firmware image of the device.

SetImage
Updates the device firmware image of the device.

CheckImage
Checks if the firmware image is valid for the device.

GetPackageInfo
Returns information about the current firmware package.

SetPackageInfo
Updates information about the firmware package.

23.1.2 EFI_FIRMWARE_MANAGEMENT_PROTOCOL.GetImageInfo()

Summary
Returns information about the current firmware image(s) of the device.

Protocol

typedef
EFI_STATUS
(EFIAPI *EFI_FIRMWARE_MANAGEMENT_PROTOCOL_GET_IMAGE_INFO) (  
    IN EFI_FIRMWARE_MANAGEMENT_PROTOCOL *This,
    IN OUT UINTN *ImageInfoSize,
    IN OUT EFI_FIRMWARE_IMAGE_DESCRIPTOR *ImageInfo,
    OUT UINT32 *DescriptorVersion
    OUT UINT8 *DescriptorCount,
    OUT UINTN *DescriptorSize,
    OUT UINT32 *PackageVersion,
    OUT CHAR16 **PackageVersionName
) ;

Parameters

This
A pointer to the EFI_FIRMWARE_MANAGEMENT_PROTOCOL instance.

ImageInfoSize
A pointer to the size, in bytes, of the ImageInfo buffer. On input, this is the size of the buffer allocated by the
caller. On output, it is the size of the buffer returned by the firmware if the buffer was large enough, or the size of the buffer needed to contain the image(s) information if the buffer was too small.

**ImageInfo**
A pointer to the buffer in which firmware places the current image(s) information. The information is an array of `EFI_FIRMWARE_IMAGE_DESCRIPTOR`, see “Related Definitions”. May be NULL with a zero `ImageInfoSize` in order to determine the size of the buffer needed.

**DescriptorVersion**
A pointer to the location in which firmware returns the version number associated with the `EFI_FIRMWARE_IMAGE_DESCRIPTOR`. See “Related Definitions”.

**DescriptorCount**
A pointer to the location in which firmware returns the number of descriptors or firmware images within this device.

**DescriptorSize**
A pointer to the location in which firmware returns the size, in bytes, of an individual `EFI_FIRMWARE_IMAGE_DESCRIPTOR`.

**PackageVersion**
A version number that represents all the firmware images in the device. The format is vendor specific and new version must have a greater value than the old version. If `PackageVersion` is not supported, the value is 0xFFFFFFFF. A value of 0xFFFFFFFFF indicates that package version comparison is to be performed using `PackageVersionName`. A value of 0xFFFFFFFD indicates that package version update is in progress.

**PackageVersionName**
A pointer to a pointer to a null-terminated string representing the package version name. The buffer is allocated by this function with `AllocatePool()`, and it is the caller’s responsibility to free it with a call to `FreePool()`.

**Related Definitions**

```c
typedef struct {
    UINT8     ImageIndex;
    EFI_GUID  ImageTypeId;
    UINT64    ImageId;
    CHAR16    *ImageIdName;
    UINT32    Version;
    CHAR16    *VersionName;
    UINTN     Size;
    UINT64    AttributesSupported;
    UINT64    AttributesSetting;
    UINT64    Compatibilities;
    //Introduced with DescriptorVersion 2+
    UINT32    LowestSupportedImageVersion; \n    //Introduced with DescriptorVersion 3+
    UINT32    LastAttemptVersion;
    UINT32    LastAttemptStatus;
    UINT64    HardwareInstance;
    //Introduced with DescriptorVersion 4+
    EFI_FMP_DEP *Dependencies;
} EFI_FIRMWARE_IMAGE_DESCRIPTOR;
```

**ImageIndex**
A unique number identifying the firmware image within the device. The number is between 1 and Descriptor-Count.

**ImageTypeId**
A unique GUID identifying the firmware image type.

**ImageId**
A unique number identifying the firmware image.

**ImageIdName**
A pointer to a null-terminated string representing the firmware image name.

**Version**
Identifies the version of the device firmware. The format is vendor specific and new version must have a greater value than an old version.

**VersionName**
A pointer to a null-terminated string representing the firmware image version name.

**Size**
Size of the image in bytes. If size=0, then only ImageIndex and ImageTypeId are valid.

**AttributesSupported**
Image attributes that are supported by this device. See “Image Attribute Definitions” for possible returned values of this parameter. A value of 1 indicates the attribute is supported and the current setting value is indicated in AttributesSetting. A value of 0 indicates the attribute is not supported and the current setting value in AttributesSetting is meaningless.

**AttributesSetting**
Image attributes. See “Image Attribute Definitions” for possible returned values of this parameter.

**Compatibilities**
Image compatibilities. See “Image Compatibility Definitions” for possible returned values of this parameter.

**LowestSupportedImageVersion**
Describes the lowest ImageDescriptor version that the device will accept. Only present in version 2 or higher.

**LastAttemptVersion**
Describes the version that was last attempted to update. If no update attempted the value will be 0. If the update attempted was improperly formatted and no version number was available then the value will be zero. Only present in version 3 or higher.

**LastAttemptStatus**
Describes the status that was last attempted to update. If no update has been attempted the value will be LAST_ATTEMPT_STATUS_SUCCESS. See “Related Definitions” in EFI_SYSTEM_RESOURCE_TABLE for Last Attempt Status values. Only present in version 3 or higher.

**HardwareInstance**
An optional number to identify the unique hardware instance within the system for devices that may have multiple instances (Example: a plug in pci network card). This number must be unique within the namespace of the ImageTypeId GUID and ImageIndex. For FMP instances that have multiple descriptors for a single hardware instance, all descriptors must have the same HardwareInstance value. This number must be consistent between boots and should be based on some sort of hardware identified unique id (serial number, etc) whenever possible. If a hardware based number is not available the FMP provider may use some other characteristic such as device path, bus/dev/function, slot num, etc for generating the HardwareInstance. For implementations that will never have more than one instance a zero can be used. A zero means the FMP provider is not able to determine a unique hardware instance number or a hardware instance number is not needed. Only present in version 3 or higher.

**Dependencies**
A pointer to an array of FMP depex expression op-codes that are terminated by an EFI_FMP_DEP_END op-code.
The attribute `IMAGE_ATTRIBUTE_IMAGE_UPDATABLE` indicates that this device supports firmware image update.

The attribute `IMAGE_ATTRIBUTE_RESET_REQUIRED` indicates a reset of the device is required for the new firmware image to take effect after a firmware update. The device is the device hosting the firmware image.

The attribute `IMAGE_ATTRIBUTE_AUTHENTICATION_REQUIRED` indicates authentication is required to perform the following image operations: `GetImage()`, `SetImage()`, and `CheckImage()`. See “Image Attribute - Authentication”.

The attribute `IMAGE_ATTRIBUTE_IN_USE` indicates the current state of the firmware image. This distinguishes firmware images in a device that supports redundant images.

The attribute `IMAGE_ATTRIBUTE_UEFI_IMAGE` indicates that this image is an EFI compatible image.

Values from `0x0000000000000002` thru `0x0000000000000000FFFFFF` are reserved for future assignments.

Values from `0x0000000000000100` thru `0xFFFFFFFFFFFFFF` are used by firmware vendor for compatibility check.

(continues on next page)
WIN_CERTIFICATE_UEFI_GUID AuthInfo;
} EFI_FIRMWARE_IMAGE_AUTHENTICATION;

**MonotonicCount**

It is included in the signature of AuthInfo. It is used to ensure freshness/no replay. It is incremented during each firmware image operation.

**AuthInfo**

Provides the authorization for the firmware image operations.

If the image has dependencies associated with it, a signature across the image data will be created by including the Monotonic Count followed by the dependency values. If there are no dependencies, the signature will be across the image data and the Monotonic Count value.

Caller uses the private key that is associated with a public key that has been provisioned via the key exchange. Because this is defined as a signature, WIN_CERTIFICATE_UEFI_GUID. CertType must be EFI_CERT_TYPE_PKCS7_GUID.

**Description**

GetImageInfo() is the only required function. GetImage(), SetImage(), CheckImage(), GetPackageInfo(), and SetPackageInfo() shall return EFI_UNSUPPORTED if not supported by the driver.

A package can have one to many firmware images. The firmware images can have the same version naming or different version naming. PackageVersion may be used as the representative version for all the firmware images. PackageVersion can be obtained from GetPackageInfo(). PackageVersion is also available in GetImageInfo() as GetPackageInfo() is optional. It also ensures the package version is in sync with the versions of the images within the package by returning the package version and image version(s) in a single function call.

The value of ImageTypeID is implementation specific. This feature facilitates vendor to target a single firmware release to cover multiple products within a product family. As an example, a vendor has an initial product A and then later developed a product B that is of the same product family. Product A and product B will have the same ImageTypeID to indicate firmware compatibility between the two products.

To determine image attributes, software must use both AttributesSupported and AttributesSetting. An attribute setting in AttributesSetting is meaningless if the corresponding attribute is not supported in AttributesSupported.

Compatibilities are used to ensure the targeted firmware image supports the current hardware configuration. Compatibilities are set based on the current hardware configuration and firmware update policy should match the current settings to those supported by the new firmware image, and only permits update to proceed if the new firmware image settings are equal or greater than the current hardware configuration settings. For example, if this function returns Compatibilities = 0x000000000070001 and the new firmware image supports settings=0x000000000030001, then the update policy should block the firmware update and notify the user that updating the hardware with the new firmware image may render the hardware inoperable. This situation usually occurs when updating the hardware with an older version of firmware.

The authentication support leverages the authentication scheme employed in variable authentication. Please reference EFI_VARIABLE_AUTHENTICATION in the “Variable Services” section of “Services - Runtime Services” chapter.

If IMAGE_ATTRIBUTE_AUTHENTICATION_REQUIRED is supported and clear, then authentication is not required to perform the firmware image operations. In firmware image operations, the image pointer points to the start of the firmware image and the image size is the firmware image.

If IMAGE_ATTRIBUTE_AUTHENTICATION_REQUIRED is supported and set, then authentication is required to perform the firmware image operations. In firmware image operations, the image pointer points to the start of the authentication data and the image size is the size of the authentication data and the size of the firmware image.

If IMAGE_ATTRIBUTE_DEPENDENCY is supported and set, then there are dependencies associated with the image. See the *Dependency Expression Instruction Set* for details on the format of the dependency op-codes and how they are
Fig. 23.1: Firmware Image with no Authentication Support

Fig. 23.2: Firmware Image with Authentication Support
to be used.

Fig. 23.3: Firmware Image with Dependency/AuthenticationSupport

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The image information was successfully returned.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The ImageInfo buffer was too small. The current buffer size needed to hold</td>
</tr>
<tr>
<td></td>
<td>the image(s) information is returned in ImageInfoSize.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ImageInfoSize is not too small and ImageInfo is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ImageInfoSize is non-zero and DescriptorVersion is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ImageInfoSize is non-zero and DescriptorCount is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ImageInfoSize is non-zero and DescriptorSize is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ImageInfoSize is non-zero and PackageVersion is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ImageInfoSize is non-zero and PackageVersionName is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Valid information could not be returned. Possible corrupted image.</td>
</tr>
</tbody>
</table>

### 23.1.3 EFI_FIRMWARE_MANAGEMENT_PROTOCOL.GetImage()

#### Summary

Retrieves a copy of the current firmware image of the device.

#### Protocol

```c
typedef EFI_STATUS (EFIAPI *EFI_FIRMWARE_MANAGEMENT_PROTOCOL_GET_IMAGE) (  
    IN EFI_FIRMWARE_MANAGEMENT_PROTOCOL *This,  
    IN UINT8 ImageIndex,  
    OUT VOID *Image,  
    IN OUT UINTN *ImageSize
);```

23.1. Firmware Management Protocol
Parameters

This
A pointer to the EFI_FIRMWARE_MANAGEMENT_PROTOCOL instance.

ImageIndex
A unique number identifying the firmware image(s) within the device. The number is between 1 and DescriptorCount.

Image
Points to the buffer where the current image is copied to. May be NULL with a zero ImageSize in order to determine the size of the buffer needed.

ImageSize
On entry, points to the size of the buffer pointed to by Image, in bytes. On return, points to the length of the image, in bytes.

Related Definitions
None

Description
This function allows a copy of the current firmware image to be created and saved. The saved copy could later been used, for example, in firmware image recovery or rollback.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The current image was successfully copied to the buffer.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The buffer specified by ImageSize is too small to hold the image. The current buffer size needed to hold the image is returned in ImageSize.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The ImageSize is not too small and Image is NULL</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The current image is not copied to the buffer.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The operation is not supported.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The operation could not be performed due to an authentication failure.</td>
</tr>
</tbody>
</table>

23.1.4 EFI_FIRMWARE_MANAGEMENT_PROTOCOL.SetImage()

Summary
Updates the firmware image of the device.

Protocol

typedef
EFI_STATUS
(EFIAPI *EFI_FIRMWARE_MANAGEMENT_PROTOCOL_SET_IMAGE) (  
  IN EFI_FIRMWARE_MANAGEMENT_PROTOCOL  *This,  
  IN UINT8  ImageIndex,  
  IN CONST VOID  *Image,  
  IN UINTN  ImageSize,  
  IN CONST VOID  *VendorCode,  
  IN EFI_FIRMWARE_MANAGEMENT_UPDATE_IMAGE_PROGRESS  Progress,  
  OUT CHAR16 **AbortReason  
) ;

Parameters
This
A pointer to the EFI_FIRMWARE_MANAGEMENT_PROTOCOL instance.

ImageIndex
A unique number identifying the firmware image(s) within the device. The number is between 1 and DescriptorCount.

Image
Points to the new image.

ImageSize
Size of the new image in bytes.

VendorCode
This enables vendor to implement vendor-specific firmware image update policy. Null indicates the caller did not specify the policy or use the default policy.

Progress
A function used by the driver to report the progress of the firmware update.

AbortReason
A pointer to a pointer to a null-terminated string providing more details for the aborted operation. The buffer is allocated by this function with AllocatePool(), and it is the caller’s responsibility to free it with a call to FreePool().

Related Definitions

typedef
EFI_STATUS
(EFIAPI *EFI_FIRMWARE_MANAGEMENT_UPDATE_IMAGE_PROGRESS) ( 
  IN UINTN Completion
)
;

Completion
A value between 1 and 100 indicating the current completion progress of the firmware update. Completion progress is reported as from 1 to 100 percent. A value of 0 is used by the driver to indicate that progress reporting is not supported.

On EFI_SUCCESS, SetImage() continues to do the callback if supported. On NOT EFI_SUCCESS, SetImage() discontinues the callback and completes the update and returns.

Description
This function updates the hardware with the new firmware image.

This function returns EFI_UNSUPPORTED if the firmware image is not updatable.

If the firmware image is updatable, the function should perform the following minimal validations before proceeding to do the firmware image update.

- Validate the image authentication if image has attribute IMAGE_ATTRIBUTE_AUTHENTICATION_REQUIRED. The function returns EFI_SECURITY_VIOLATION if the validation fails.
- Validate the image is a supported image for this device. The function returns EFI_ABORTED if the image is unsupported. The function can optionally provide more detailed information on why the image is not a supported image.
- Validate the data from VendorCode if not null. Image validation must be performed before VendorCode data validation. VendorCode data is ignored or considered invalid if image validation failed. The function returns EFI_ABORTED if the data is invalid.
VendorCode enables vendor to implement vendor-specific firmware image update policy. Null if the caller did not specify the policy or use the default policy. As an example, vendor can implement a policy to allow an option to force a firmware image update when the abort reason is due to the new firmware image version is older than the current firmware image version or bad image checksum. Sensitive operations such as those wiping the entire firmware image and render the device to be non-functional should be encoded in the image itself rather than passed with the VendorCode.

AbortReason enables vendor to have the option to provide a more detailed description of the abort reason to the caller.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The device was successfully updated with the new image.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>The operation is aborted.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The Image was NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The operation is not supported.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The operation could not be performed due to an authentication failure.</td>
</tr>
</tbody>
</table>

23.1.5 EFI_FIRMWARE_MANAGEMENT_PROTOCOL.CheckImage()

Summary

Checks if the firmware image is valid for the device.

Protocol

```c
typedef EFI_STATUS
(EFIAPI *EFI_FIRMWARE_MANAGEMENT_PROTOCOL_CHECK_IMAGE) (  
    IN EFI_FIRMWARE_MANAGEMENT_PROTOCOL *This,
    IN UINT8 ImageIndex,
    IN CONST VOID *Image,
    IN UINTN ImageSize,
    OUT UINT32 *ImageUpdatable
  ) ;
```

Parameters

This

A pointer to the EFI_FIRMWARE_MANAGEMENT_PROTOCOL instance.

ImageIndex

A unique number identifying the firmware image(s) within the device. The number is between 1 and DescriptorCount.

Image

Points to the new image.

ImageSize

Size of the new image in bytes.

ImageUpdatable

Indicates if the new image is valid for update. It also provides, if available, additional information if the image is invalid. See “Related Definitions”.

Related Definitions

23.1. Firmware Management Protocol
IMAGE_UPDATABLE_VALID
indicates `SetImage()` will accept the new image and update the device with the new image. The version of the new image could be higher or lower than the current image. `SetImage VendorCode` is optional but can be used for vendor specific action.

IMAGE_UPDATABLE_INVALID
indicates `SetImage()` will reject the new image. No additional information is provided for the rejection.

IMAGE_UPDATABLE_INVALID_TYPE
indicates `SetImage()` will reject the new image. The rejection is due to the new image is not a firmware image recognized for this device.

IMAGE_UPDATABLE_INVALID_OLD
indicates `SetImage()` will reject the new image. The rejection is due to the new image version is older than the current firmware image version in the device. The device firmware update policy does not support firmware version downgrade.

IMAGE_UPDATABLE_VALID_WITH_VENDOR_CODE
indicates `SetImage()` will accept and update the new image only if a correct `VendorCode` is provided or else image would be rejected and `SetImage` will return appropriate error.

Description
This function allows firmware update application to validate the firmware image without invoking the `SetImage()` first. Please see `SetImage()` for the type of image validations performed.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The image was successfully checked.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>Image</code> was NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The operation is not supported.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The operation could not be performed due to an authentication failure.</td>
</tr>
</tbody>
</table>

23.1.6 EFI_FIRMWARE_MANAGEMENT_PROTOCOL.GetPackageInfo()

Summary
Returns information about the firmware package.

Protocol
```c
typedef
EFI_STATUS
(EFIAPI *EFI_FIRMWARE_MANAGEMENT_PROTOCOL_GET_PACKAGE_INFO)(
  IN EFI_FIRMWARE_MANAGEMENT_PROTOCOL* *This,
  OUT UINT32* PackageVersion,
  OUT CHAR16* **PackageVersionName,
)
```

(continues on next page)
Parameters

This

A pointer to the EFI_FIRMWARE_MANAGEMENT_PROTOCOL instance.

PackageVersion

A version number that represents all the firmware images in the device. The format is vendor specific and new version must have a greater value than the old version. If PackageVersion is not supported, the value is 0xFFFFFFFF. A value of 0xFFFFFFFFE indicates that package version comparison is to be performed using PackageVersionName. A value of 0xFFFFFFFD indicates that package version update is in progress.

PackageVersionName

A pointer to a pointer to a null-terminated string representing the package version name. The buffer is allocated by this function with AllocatePool(), and it is the caller’s responsibility to free it with a call to FreePool().

PackageVersionNameMaxLen

The maximum length of package version name if device supports update of package version name. A value of 0 indicates the device does not support update of package version name. Length is the number of Unicode characters, including the terminating null character.

AttributesSupported

Package attributes that are supported by this device. See “Package Attribute Definitions” for possible returned values of this parameter. A value of 1 indicates the attribute is supported and the current setting value is indicated in AttributesSetting. A value of 0 indicates the attribute is not supported and the current setting value in AttributesSetting is meaningless.

AttributesSetting

Package attributes. See “Package Attribute Definitions” for possible returned values of this parameter.

Related Definitions

```
// Package Attribute Definitions

#define PACKAGE_ATTRIBUTE_VERSION_UPDATABLE   0x0000000000000001
#define PACKAGE_ATTRIBUTE_RESET_REQUIRED      0x0000000000000002
#define PACKAGE_ATTRIBUTE_AUTHENTICATION_REQUIRED 0x0000000000000004
```

The attribute PACKAGE_ATTRIBUTE_VERSION_UPDATABLE indicates this device supports the update of the firmware package version.

The attribute PACKAGE_ATTRIBUTE_RESET_REQUIRED indicates a reset of the device is required for the new package info to take effect after an update.

The attribute PACKAGE_ATTRIBUTE_AUTHENTICATION_REQUIRED indicates authentication is required to update the package info.

Description

This function returns package information.

Status Codes Returned
23.1.7 EFI_FIRMWARE_MANAGEMENT_PROTOCOL.SetPackageInfo()

**Summary**
Updates information about the firmware package.

**Protocol**

```c
typedef
EFI_STATUS
(EFIAPIC *EFI_FIRMWARE_MANAGEMENT_PROTOCOL_SET_PACKAGE_INFO) (
    IN EFI_FIRMWARE_MANAGEMENT_PROTOCOL* *This,
    IN CONST VOID *Image,
    IN UINTN ImageSize,
    IN CONST VOID *VendorCode,
    IN UINT32 PackageVersion,
    IN CONST CHAR16 *PackageVersionName
);
```

**Parameters**

- **This**
  A pointer to the `EFI_FIRMWARE_MANAGEMENT_PROTOCOL` instance.

- **Image**
  Points to the authentication image. Null if authentication is not required.

- **ImageSize**
  Size of the authentication image in bytes. 0 if authentication is not required.

- **VendorCode**
  This enables vendor to implement vendor-specific firmware image update policy. Null if the caller did not specify this policy or use the default policy.

- **PackageVersion**
  The new package version.

- **PackageVersionName**
  A pointer to the new null-terminated Unicode string representing the package version name. The string length is equal to or less than the value returned in `PackageVersionNameMaxLen`.

**Description**
This function updates package information.

This function returns `EFI_UNSUPPORTED` if the package information is not updatable.

`VendorCode` enables vendor to implement vendor-specific package information update policy. Null if the caller did not specify this policy or use the default policy.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The package information was successfully returned.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The operation is not supported.</td>
</tr>
</tbody>
</table>

Continues on next page
23.2 Dependency Expression Instruction Set

The following topics describe each of the firmware management protocol dependency expression (depex) opcodes in detail. Information includes a description of the instruction functionality, binary encoding, and any limitations or unique behaviors of the instruction.

Several of the opcodes require a GUID operand. The GUID operand is a 16-byte value that matches the type `EFI_GUID` that is described in Chapter 2 of the UEFI 2.0 specification. These GUIDs represent the `EFI_FIRMWARE_IMAGE_DESCRIPTOR .ImageTypeId` that are exposed by an ` EFI_FIRMWARE_MANAGE_PROTOCOL` instance. A dependency expression is a packed byte stream of opcodes and operands. As a result, some of the GUID operands will not be aligned on natural boundaries. Care must be taken on processor architectures that do allow unaligned accesses.

The dependency expression is stored in a packed byte stream using postfix notation. As a dependency expression is evaluated, the operands are pushed onto a stack. Operands are popped off the stack to perform an operation. After the last operation is performed, the value on the top of the stack represents the evaluation of the entire dependency expression. If a push operation causes a stack overflow, then the entire dependency expression evaluates to `FALSE`. If a pop operation causes a stack underflow, then the entire dependency expression evaluates to `FALSE`. Reasonable implementations of a dependency expression evaluator should not make arbitrary assumptions about the maximum stack size it will support. Instead, it should be designed to grow the dependency expression stack as required. In addition, FMP images that contain dependency expressions should make an effort to keep their dependency expressions as small as possible to help reduce the size of the FMP image.

All opcodes are 8-bit values, and if an invalid opcode is encountered, then the entire dependency expression evaluates to `FALSE`.

When the dependency expression is being evaluated and a GUID specified cannot be found, then the result of the conditional operation evaluates to `FALSE`.

If, when evaluating two popped values from the stack, it is determined that they are of different types (e.g. BOOLEAN value and 32-bit value), then the entire dependency expression evaluates to `FALSE`

If an END opcode is not present in a dependency expression, then the entire dependency expression evaluates to `FALSE`.

The final evaluation of the dependency expression results in either a `TRUE` or `FALSE` result.

### Table 23.4: Dependency Expression Opcode Summary

<table>
<thead>
<tr>
<th>Opcode</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>Push FMP GUID (1 op-code + 16 bytes)</td>
</tr>
<tr>
<td>0x01</td>
<td>Push 32-bit version value</td>
</tr>
<tr>
<td>0x02</td>
<td>Declare NULL-terminated string (Human-readable Version)</td>
</tr>
<tr>
<td>0x03</td>
<td>AND – Pop 2 BOOLEAN values and Push <code>TRUE</code> if both are <code>TRUE</code>.</td>
</tr>
<tr>
<td>0x04</td>
<td>OR – Pop 2 BOOLEAN values and Push <code>TRUE</code> if either are <code>TRUE</code>.</td>
</tr>
<tr>
<td>0x05</td>
<td>NOT – Pop BOOLEAN value Push NOT of BOOLEAN value.</td>
</tr>
<tr>
<td>0x06</td>
<td>Push <code>TRUE</code></td>
</tr>
<tr>
<td>0x07</td>
<td>Push <code>FALSE</code></td>
</tr>
<tr>
<td>0x08</td>
<td>EQ – Pop 2 32-bit version values and push <code>TRUE</code> if equal.</td>
</tr>
</tbody>
</table>

continues on next page
Table 23.4 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x09</td>
<td>GT - Pop 2 32-bit version values and push TRUE if first value is greater than the second.</td>
</tr>
<tr>
<td>0x0A</td>
<td>GTE - Pop 2 32-bit version values and push TRUE if first value is greater than or equal to the second.</td>
</tr>
<tr>
<td>0x0B</td>
<td>LT - Pop 2 32-bit version values and push TRUE if first value is less than the second.</td>
</tr>
<tr>
<td>0x0C</td>
<td>LTE - Pop 2 32-bit version values and push TRUE if first value is less than or equal to the second.</td>
</tr>
<tr>
<td>0x0D</td>
<td>END</td>
</tr>
<tr>
<td>0x0E</td>
<td>DECLARE_LENGTH - declares a 32-bit byte length of the entire dependency expression</td>
</tr>
</tbody>
</table>

### 23.2.1 PUSH_GUID

**Syntax**

PUSH_GUID `<FMP GUID>`

**Description**

Pushes the GUID value onto the stack. This GUID should be exposed by an `EFI_FIRMWARE_MANAGEMENT_PROTOCOL` instance. The GUID should match one of the `EFI_FIRMWARE_IMAGE_DESCRIPTOR`. ImageTypeId values exposed through the `GetImageInfo()` function.

**Operation**

1. Search through all instances of the `EFI_FIRMWARE_MANAGEMENT_PROTOCOL`.
   a - In each instance, use the `GetImageInfo()` function to retrieve the ImageInfo->ImageTypeId value and ensure it matches the GUID specified in the op-code.
   b - If it doesn’t match the GUID and no other instances match either, POP all values from the stack and PUSH FALSE onto the stack when evaluating a conditional operation involving the missing GUID.

2. Having found the matching `EFI_FIRMWARE_MANAGEMENT_PROTOCOL` instance, use the `GetImageInfo()` function and push the ImageInfo->Version value onto the stack.

**Table 23.5: PUSH_GUID Instruction Encoding**

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x00</td>
</tr>
<tr>
<td>1..16</td>
<td>A 16-byte GUID that represents an ImageTypeId in an FMP instance. The format is the same as type <code>EFI_GUID</code>.</td>
</tr>
</tbody>
</table>

**Behaviors and Restrictions**

None.

### 23.2.2 PUSH_VERSION

**Syntax**

PUSH_VERSION `<32-bit Version>`

**Description**

Pushes the 32-bit version value to compare against onto the stack. This value will be used to compare against Version values exposed through the `GetImageInfo()` function.
Table 23.6: PUSH_VERSION Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x01</td>
</tr>
<tr>
<td>1..4</td>
<td>A 32-bit version to compare against.</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions
None.

23.2.3 DECLARE_VERSION_NAME

Syntax

DECLARE_VERSION_NAME <NULL-terminated string>

Description
Declares an optional null-terminated version string that is the equivalent of the VersionName in the EFI_FIRMWARE_MANAGEMENT_DESCRIPTOR. Due to the OEM/IHV-specific format of version strings, this null-terminated string will not be used for purposes of comparison. Only the 32-bit integer values will be used for comparisons.

Table 23.7: DECLARE_VERSION_NAME Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x02</td>
</tr>
<tr>
<td>1..n</td>
<td>A null-terminated UNICODE string.</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions
None.

23.2.4 AND

Syntax

AND

Description
Pops two Boolean operands off the stack, performs a Boolean AND operation between the two operands, and pushes the result back onto the stack.

Operation

Operand1 <= POP Boolean stack element
Operand2 <= POP Boolean stack element
Result <= Operand1 AND Operand2
PUSH Result

Table 23.8: AND Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x03</td>
</tr>
</tbody>
</table>
Behaviors and Restrictions
None.

23.2.5 OR

Syntax

OR

Description
Pops two Boolean operands off the stack, performs a Boolean OR operation between the two operands, and pushes the result back onto the stack.

Operation

Operand1 <= POP Boolean stack element
Operand2 <= POP Boolean stack element
Result <= Operand1 OR Operand2
PUSH Result

Table 23.9: OR Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x04</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions
None.

23.2.6 NOT

Syntax

NOT

Description
Pops a Boolean operand off the stack, performs a Boolean NOT operation on the operand, and pushes the result back onto the stack.

Operation

Operand <= POP Boolean stack element
Result <= NOT Operand
PUSH Result

Table 23.10: NOT Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x05</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions
None.
23.2.7 TRUE

Syntax

```plaintext
**TRUE**
```

Description

Pushes a Boolean TRUE onto the stack.

Operation

```plaintext
PUSH **TRUE**
```

Table 23.11: TRUE Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x06</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

None.

23.2.8 FALSE

Syntax

```plaintext
**FALSE**
```

Description

Pushes a Boolean FALSE onto the stack.

Operation

```plaintext
PUSH **FALSE**
```

Table 23.12: FALSE Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x07</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions

None.

23.2.9 EQ

Syntax

```plaintext
EQ
```

Description

Pops two 32-bit operands off the stack, performs a Boolean equals comparison operation between the two operands, and pushes the result back onto the stack.
Operation

Operand1 ? POP 32-bit stack element
Operand2 ? POP 32-bit stack element
Result ? Operand1 EQ Operand2
PUSH Result

Table 23.13: EQ Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x08</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions
None.

23.2.10 GT

Syntax

GT

Description
Pops two 32-bit operands off the stack, performs a Boolean greater-than comparison operation between the two operands, and pushes the result back onto the stack.

Operation

Operand1 <= POP 32-bit stack element
Operand2 <= POP 32-bit stack element
Result <= Operand1 GT Operand2
PUSH Result

Table 23.14: GT Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x09</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions
None.

23.2.11 GTE

Syntax

GTE

Description
Pops two 32-bit operands off the stack, performs a Boolean greater-than-or-equal comparison operation between the two operands, and pushes the result back onto the stack.

Operation
Operand1 ? POP 32-bit stack element
Operand2 ? POP 32-bit stack element
Result ? Operand1 GTE Operand2
PUSH Result

Table 23.15: GTE Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x0A</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions
None.

23.2.12 LT

Syntax
LT

Description
Pops two 32-bit operands off the stack, performs a Boolean less-than comparison operation between the two operands, and pushes the result back onto the stack.

Operation
Operand1 ? POP 32-bit stack element
Operand2 ? POP 32-bit stack element
Result ? Operand1 LT Operand2
PUSH Result

Table 23.16: LT Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x0B</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions
None.

23.2.13 LTE

Syntax
LTE

Description
Pops two 32-bit operands off the stack, performs a Boolean less-than-or-equal comparison operation between the two operands, and pushes the result back onto the stack.

Operation
Operand1 ? POP 32-bit stack element
Operand2 ? POP 32-bit stack element
Result ? Operand1 LTE Operand2
PUSH Result

Table 23.17: LTE Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x0C</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions
None.

23.2.14 END

Syntax
END

Description
Pops the final result of the dependency expression evaluation off the stack and exits the dependency expression evaluator.

Operation
POP Result
RETURN Result

Table 23.18: END Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0x0D</td>
</tr>
</tbody>
</table>

Behaviors and Restrictions
This opcode must be the last one in a dependency expression.

23.2.15 DECLARE_LENGTH

Syntax
DECLARE_LENGTH <32-bit Length>

Description
Declares an 32-bit byte length of the entire dependency expression.

Table 23.19: DECLARE_LENGTH Instruction Encoding

<table>
<thead>
<tr>
<th>Byte</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0X0e 1..4</td>
</tr>
<tr>
<td></td>
<td>A 32-bit byte length for the entire dependency expression.</td>
</tr>
</tbody>
</table>
Behaviors and Restrictions
This opcode must be the first one in a dependency expression.

23.3 Delivering Capsules Containing Updates to Firmware Management Protocol

Summary
This section defines a method for delivery of a Firmware Management Protocol defined update using the UpdateCapsule runtime API.

23.3.1 EFI_FIRMWARE_MANAGEMENT_CAPSULE_ID_GUID

GUID

```c
// {6DCBD5ED-E82D-4C44-BDA1-7194199AD92A}
#define EFI_FIRMWARE_MANAGEMENT_CAPSULE_ID_GUID
{0x6dcbd5ed, 0xe82d, 0x4c44, 
 {0xbd, 0xa1, 0x71, 0x94, 0x19, 0x9a, 0xd9, 0x2a }}
```

Description
This GUID is used in the CapsuleGuid field of EFI_CAPSULE_HEADER struct within a capsule constructed according to the definitions of section Capsule Definition. Use of this GUID indicates a capsule with body conforming to the additional structure defined in DEFINED FIRMWARE MANAGEMENT PROTOCOL DATA CAPSULE STRUCTURE.

When delivered to platform firmware QueryCapsuleCapabilities() the capsule will be examined according to the structure defined in DEFINED FIRMWARE MANAGEMENT PROTOCOL DATA CAPSULE STRUCTURE. and if it is possible for the platform to process EFI_SUCCESS will be returned.

When delivered to platform firmware UpdateCapsule() the capsule will be examined according to the structure defined in DEFINED FIRMWARE MANAGEMENT PROTOCOL DATA CAPSULE STRUCTURE. and if it is possible for the platform to process the update will be processed.

By definition Firmware Management protocol services are not available in EFI runtime and depending upon platform capabilities, EFI runtime delivery of this capsule may not be supported and may return an error when delivered in EFI runtime with CAPSULE_FLAGS_PERSIST_ACROSS_RESET bit defined. However any platform supporting this capability is required to accept this form of capsule in Boot Services, including optional use of CAPSULE_FLAGS_PERSIST_ACROSS_RESET bit.

23.3.2 DEFINED FIRMWARE MANAGEMENT PROTOCOL DATA CAPSULE STRUCTURE

Structure of the Capsule Body
Generic EFI Capsule Body is defined in Capsule Definition. When an EFI Capsule is identified by EFI_FIRMWARE_MANAGEMENT_CAPSULE_ID_GUID, the internal structure of the capsule _FIRMWARE_MANAGEMENT_CAPSULE_HEADER followed by optional EFI drivers to be loaded by the platform and optional binary payload items to be processed and passed to Firmware Management Protocol image update function. Each binary payload item is preceded by EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER. Internal capsule structure diagram follows.
Fig. 23.4: Optional Scatter-Gather Construction of Capsule Submitted to Update Capsule()
Fig. 23.5: Capsule Header and Firmware Management Capsule Header
Fig. 23.6: Firmware Management and Firmware Image Management headers
Related Definitions

```c
#pragma pack(1)
typedef struct {
    UINT32         Version;
    UINT16         EmbeddedDriverCount;
    UINT16         PayloadItemCount;
    // UINT64       ItemOffsetList[];
} EFI_FIRMWARE_MANAGEMENT_CAPSULE_HEADER;
```

**Version**
Version of the structure, initially 0x00000001.

**EmbeddedDriverCount**
The number of drivers included in the capsule and the number of corresponding offsets stored in `ItemOffsetList` array. This field may be zero in the case where no driver is required.

**PayloadItemCount**
The number of payload items included in the capsule and the number of corresponding offsets stored in the `ItemOffsetList` array. This field may be zero in the case where no binary payload object is required to accomplish the update.

**ItemOffsetList**
Variable length array of dimension `[EmbeddedDriverCount + PayloadItemCount]` containing offsets of each of the drivers and payload items contained within the capsule. The offsets of the items are calculated relative to the base address of the `EFI_FIRMWARE_MANAGEMENT_CAPSULE_HEADER` struct. Offset may indicate structure begins on any byte boundary. Offsets in the array must be sorted in ascending order with all drivers preceding all binary payload elements.

```c
#pragma pack(1)
typedef struct {
    UINT32         Version;
    EFI_GUID       UpdateImageTypeId;
    UINT8          UpdateImageIndex;
    UINT8          reserved_bytes[3];
    UINT32         UpdateImageSize;
    UINT32         UpdateVendorCodeSize;
    UINT64         UpdateHardwareInstance; //Introduced in v2
    UINT64         ImageCapsuleSupport; //Introduced in v3
} EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER;
```

**Version**
Version of the structure, initially 0x00000003.

**UpdateImageTypeId**
Used to identify device firmware targeted by this update. This guid is matched by system firmware against `ImageTypeId` field within a `EFI_FIRMWARE_IMAGE_DESCRIPTOR` returned by an instance of `EFI_FIRMWARE_MANAGEMENT_PROTOCOL.GetImageInfo()` in the system.

**UpdateImageIndex**
Passed as `ImageIndex` in call to `EFI_FIRMWARE_MANAGEMENT_PROTOCOL.SetImage()`.

**UpdateImageSize**
Size of the binary update image which immediately follows this structure. Passed as `ImageSize` to `EFI_FIRMWARE_MANAGEMENT_PROTOCOL.SetImage()`. This size may or may not include Firmware Image Authentication information.

23.3. Delivering Capsules Containing Updates to Firmware Management Protocol 908
UpdateVendorCodeSize
Size of the VendorCode bytes which optionally immediately follow binary update image in the capsule. Pointer to these bytes passed in VendorCode to EFI_FIRMWARE_MANAGEMENT_PROTOCOL_SetImage(). If UpdateVendorCodeSize is zero, then VendorCode is null in SetImage() call.

UpdateHardwareInstance
The HardwareInstance to target with this update. If value is zero it means match all HardwareInstances. This field allows update software to target only a single device in cases where there are more than one device with the same ImageTypeId GUID. This header is outside the signed data of the Authentication Info structure and therefore can be modified without changing the Auth data.

ImageCapsuleSupport
A 64-bit bitmask that determines what sections are added to the payload.

```
#define CAPSULE_SUPPORT_AUTHENTICATION 0x0000000000000001
#define CAPSULE_SUPPORT_DEPENDENCY 0x0000000000000002
```

Description
The EFI_FIRMWARE_MANAGEMENT_CAPSULE_HEADER structure is located at the lowest offset within the body of the capsule identified by EFI_FIRMWARE_MANAGEMENT_CAPSULE_ID_GUID. The structure is variable length with the number of element offsets within of the ItemOffsetList array determined by the count of drivers within the capsule plus the count of binary payload elements. It is expected that drivers whose presence is indicated by non-zero EmbeddedDriverCount will be used to supply an implementation of EFI_FIRMWARE_MANAGEMENT_PROTOCOL for devices that lack said protocol within the image to be updated.

Each payload item contained within the capsule body is preceded by a EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER struct used to provide information required to prepare the payload item as an image for delivery to a instance of EFI_FIRMWARE_MANAGEMENT_PROTOCOL_SetImage() function.

NOTE: [Caution] The capsule identified by EFI_FIRMWARE_MANAGEMENT_CAPSULE_ID_GUID uses packed structures and structure fields may not be naturally aligned within the capsule buffer as delivered. Drivers and binary payload elements may start on byte boundary with no padding. Processing firmware may need to copy content elements during capsule unpacking in order to achieve any required natural alignment.

23.3.3 Firmware Processing of the Capsule Identified by EFI_FIRMWARE_MANAGEMENT_CAPSULE_ID_GUID

1. Capsule is presented to system firmware via call to UpdateCapsule() or using mass storage delivery procedure of Delivery of Capsules via file on Mass Storage Device. The capsule must be constructed to consist of a single EFI_FIRMWARE_MANAGEMENT_CAPSULE_HEADER structure with the 0 or more drivers and 0 or more binary payload items. However a capsule in which driver count and payload count are both zero is not processed.

2. Capsule is recognized by EFI_CAPSULE_HEADER member CapsuleGuid equal to EFI_FIRMWARE_MANAGEMENT_CAPSULE_ID_GUID. CapsuleFlags_PopulateSystemTable flag must be 0.

3. If system is not in boot services and platform does not support persistence of capsule across reset when initiated within EFI Runtime, EFI_OUT_OF_RESOURCES error is returned.

4. If device requires hardware reset to unlock flash write protection, CapsuleFlags_PersistAcrossReset and optionally CapsuleFlags_InitiateReset should be set to 1 in the EFI_CAPSULE_HEADER.

5. When reset is requested using CapsuleFlags_PersistAcrossReset, the capsule is processed in Boot Services, before the EFI_EVENT_GROUP_READY_TO_BOOT event.
6. All scatter-gather fragmentation is removed by the platform firmware and the capsule is processed as a contiguous buffer.

7. Examining EFI_FIRMWARE_MANAGEMENT_CAPSULE_HEADER, if EmbeddedDriverCount is non-zero, for each of the included drivers up to indicated count, the portion of the capsule body starting at the offset indicated by ItemOffsetList[n] and continuing for a size encompassing all bytes up to the next element’s offset stored in ItemOffsetList[n+1] or the end of the capsule, will be copied to a buffer. The driver contained within the capsule body may not be naturally aligned and the exact driver size in bytes should be respected to ensure successful security validation. In the case where a driver is last element in the ItemOffsetList array, the driver size may be calculated by reference to body size as calculated from CapsuleImageSize in EFI_CAPSULE_HEADER.

8. Each extracted driver is placed into a buffer and passed to LoadImage(). The driver image passed to LoadImage() must successfully pass all image format, platform type, and security checks including those related to UEFI secure boot, if enabled on the platform. After LoadImage() returns the processing of the capsule is continued with next driver if present until all drivers have been passed to LoadImage(). The driver being installed must check for matching hardware and instantiate any required protocols during call to EFI_IMAGE_ENTRY_POINT. In case where matching hardware is not found the driver should exit with error. In case where capsule creator has preference as to which of several included drivers to be made resident, later drivers in the capsule should confirm earlier driver successfully loaded and then exit with load error.

9. After driver processing is complete the platform firmware examines PayloadItemCount, and if zero the capsule processing is complete. Otherwise platform firmware sequentially locates each EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER found within the capsule and processes according to steps 10-14.

10. For all instances of EFI_FIRMWARE_MANAGEMENT_PROTOCOL in the system, GetImageInfo() is called to return arrays of EFI_FIRMWARE_IMAGE_DESCRIPTOR structures.

11. Find the matching FMP instance(s):

   a – If the EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER is version 1 or it is version 2 with UpdateHardwareInstance set to 0, then system firmware will use only the ImageTypeId to determine a match. For each instance of EFI_FIRMWARE_MANAGEMENT_PROTOCOL that returns a EFI_FIRMWARE_IMAGE_DESCRIPTOR containing an ImageTypeId GUID that matches the UpdateImageTypeId GUID within EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER, the system firmware will call SetImage() function within that instance. In some cases there may be more than one instance of matching EFI_FIRMWARE_MANAGEMENT_PROTOCOL when multiple matching devices are installed in the system and all instances will be checked for GUID match and SetImage() call if match is successful.

   b – If the EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER is version 2 and contains a non-zero value in the UpdateHardwareInstance field, then system firmware will use both ImageTypeId and HardwareInstance to determine a match. For the instance of EFI_FIRMWARE_MANAGEMENT_PROTOCOL that returns a EFI_FIRMWARE_IMAGE_DESCRIPTOR containing an ImageTypeId GUID that matches the UpdateImageTypeId GUID and a HardwareInstance matching the UpdateHardwareInstance within EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER, the system firmware will call the SetImage() function within that instance. There will never be more than one instance since the ImageId must be unique.

12. In the situation where platform configuration or policy prohibits the processing of a capsule or individual FMP payload, the error EFI_NOT_READY will be returned in capsule result variable CapsuleStatus field. Otherwise SetImage() parameters are constructed using the UpdateImageIndex, UpdateImageSize and UpdateVendorCodeSize fields within EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER. In the case of capsule containing multiple payloads, or a payload matching multiple FMP instances, a separate Capsule Result Variable will be created with the results of each call to SetImage(). If any call to SetImage() selected per above matching algorithm returns an error, the processing of additional FMP instances or payload items in that capsule will be skipped and EFI_ABORTED returned in Capsule Result Variable for each potential call to SetImage() that was skipped.

13. SetImage() performs any required image authentication as described in that functions definition within this chap-
14. Note: if multiple separate component updates including multiple ImageIndex values are required then additional EFI_FIRMWARE_MANAGEMENT_CAPSULE_IMAGE_HEADER structures and image binaries are included within the capsule.

15. After all items in the capsule are processed the system is restarted by the platform firmware.

23.4 EFI System Resource Table

23.4.1 EFI_SYSTEM_RESOURCE_TABLE

Summary
The EFI System Resource Table (ESRT) provides an optional mechanism for identifying device and system firmware resources for the purposes of targeting firmware updates to those resources. Each entry in the ESRT describes a device or system firmware resource that can be targeted by a firmware capsule update. Each entry in the ESRT will also be used to report status of the last attempted update. See EFI Configuration Table & Properties Table for description of how to publish ESRT using EFI_CONFIGURATION_TABLE. The ESRT shall be stored in memory of type EfiBootServicesData. See Update Capsule and Delivery of Capsules via file on Mass Storage Device for details on delivery of updates to devices listed in ESRT.

GUID

```c
#define EFI_SYSTEM_RESOURCE_TABLE_GUID \
  { 0xb122a263, 0x3661, 0x4f68, \} \
  { 0x99, 0x29, 0x78, 0xf8, 0xb0, 0xd6, 0x21, 0x80 }}
```

Table Structure

```c
typedef struct {
  UINT32 FwResourceCount;
  UINT32 FwResourceCountMax;
  UINT64 FwResourceVersion;
  //EFI_SYSTEM_RESOURCE_ENTRY Entries[];
} EFI_SYSTEM_RESOURCE_TABLE;
```

Members

FwResourceCount
The number of firmware resources in the table, must not be zero.

FwResourceCountMax
The maximum number of resource array entries that can be within the table without reallocating the table, must not be zero.

FwResourceVersion
The version of the EFI_SYSTEM_RESOURCE_ENTRY entities used in this table. This field should be set to 1. See EFI_SYSTEM_RESOURCE_TABLE_FIRMWARE_RESOURCE_VERSION.

Entries
Array of EFI_SYSTEM_RESOURCE_ENTRY

Related Definitions
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

```c
// Current Entry Version
#define EFI_SYSTEM_RESOURCE_TABLE_FIRMWARE_RESOURCE_VERSION 1

typedef struct {
    EFI_GUID   FwClass;
    UINT32     FwType;
    UINT32     FwVersion;
    UINT32     LowestSupportedFwVersion;
    UINT32     CapsuleFlags;
    UINT32     LastAttemptVersion;
    UINT32     LastAttemptStatus;
} EFI_SYSTEM RESOURCE_ENTRY;
```

**FwClass**

The firmware class field contains a GUID that identifies a firmware component that can be updated via `UpdateCapsule()`. This GUID must be unique within all entries of the ESRT.

**FwType**

Identifies the type of firmware resource. See “Firmware Type Definitions” below for possible values.

**FwVersion**

The firmware version field represents the current version of the firmware resource, value must always increase as a larger number represents a newer version.

**LowestSupportedFwVersion**

The lowest firmware resource version to which a firmware resource can be rolled back for the given system/device. Generally this is used to protect against known and fixed security issues.

**CapsuleFlags**

The capsule flags field contains the `CapsuleGuid` flags (bits 0-15) as defined in the `EFI_CAPSULE_HEADER` that will be set in the capsule header.

**LastAttemptVersion**

The last attempt version field describes the last firmware version for which an update was attempted (uses the same format as Firmware Version).

Last Attempt Version is updated each time an `UpdateCapsule()` is attempted for an ESRT entry and is preserved across reboots (non-volatile). However, in cases where the attempt version is not recorded due to limitations in the update process, the field shall set to zero after a failed update. Similarly, in the case of a removable device, this value is set to 0 in cases where the device has not been updated since being added to the system.

**LastAttemptStatus**

The last attempt status field describes the result of the last firmware update attempt for the firmware resource entry.

`LastAttemptStatus` is updated each time an `UpdateCapsule()` is attempted for an ESRT entry and is preserved across reboots (non-volatile).

If a firmware update has never been attempted or is unknown, for example after fresh insertion of a removable device, `LastAttemptStatus` must be set to Success.

```
// Firmware Type Definitions

//
#define ESRT_FW_TYPE_UNKNOWN 0x00000000
#define ESRT_FW_TYPE_SYSTEMFIRMWARE 0x00000001
#define ESRT_FW_TYPE_DEVICEFIRMWARE 0x00000002
```

(continues on next page)
23.4.2 Adding and Removing Devices from the ESRT

ESRT entries must be updated by System Firmware before handoff to the Operating System under the following conditions. Devices and systems that support hot swapping (once the OS has been loaded) will not get their ESRT entries updated until the next reboot and execution of ESRT updating logic in the UEFI space.

- **Required**: System firmware is responsible for updating the FirmwareVersion, LowestSupportedFirmwareVersion, LastAttemptVersion and LastAttemptStatus values in the ESRT any time UpdateCapsule is called and a firmware update attempt is made for the corresponding ESRT entry.
- **Required**: the ESRT must be updated each time a configuration change is detected by system firmware, such as when a device is added or removed from the system.
- **Optional**: all devices in the ESRT should be polled for any configuration changes any time UpdateCapsule is called.

23.4.3 ESRT and Firmware Management Protocol

Although the ESRT does not require firmware to use Firmware Management Protocol for updates it is designed to work with and extend the capabilities of FMP. The ESRT can be used to represent system and device firmware serviced by capsules that have an implementation specific format as well as devices that support Firmware Management Protocol and that are serviced by capsules formatted as described in Dependency Expression Instruction Set, Delivering Capsules Containing Updates to Firmware Management Protocol. For system expansion devices, the task of building ESRT table entries is to be performed by the system firmware based upon FMP data published by the device.
23.4.4 Mapping Firmware Management Protocol Descriptors to ESRT Entries

Firmware management Protocol descriptors define most of the information needed for an ESRT entry. The table below helps identify which members map to which fields. Some members are dependent on certain versions of FMP and it is left to system firmware to resolve any mappings when information is not present in the FMP instance. FMP descriptors should only be mapped to ESRT entries if the following are true:

- An entry with the same ImageTypeId is not already in the ESRT.
- AttributesSupported and AttributesSetting have the IMAGE_ATTRIBUTE_IN_USE bit set.
- In the case where DescriptorCount returned by GetImageInfo() is greater than one, firmware shall populate the ESRT according to system policy, noting however that multiple ESRT entries with identical FwClass values are not permitted.

<table>
<thead>
<tr>
<th>ESRT Field</th>
<th>FMP Field</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>FwClass</td>
<td>ImageTypeId</td>
<td>The ImageTypeId GUID from the Firmware Management Protocol instance for a device is used as the Firmware Class GUID in the ESRT. Where there are multiple identical devices in the system, system firmware must create a mapping to ensure that the ESRT FwClass GUIDs are unique and consistent.</td>
</tr>
<tr>
<td>FwVersion</td>
<td>Version</td>
<td>Represents the current version of device firmware for an FMP instance.</td>
</tr>
</tbody>
</table>
| LowestSupported FwVer-
| Version        | LowestSupported ImageV-
| ersion          | ersion         |                                                                         |
| LastAttemptVersion | LastAttemptVersion | To be set after the completion of a firmware update attempt. In descriptor v3+ only. Default value is 0. |
| LastAttemptStatus | LastAttemptStatus | To be set after the completion of a firmware update attempt. In descriptor v3+ only. Default value is SUCCESS. |

23.5 Delivering Capsule Containing JSON payload

Summary

This section defines a method for delivery of JSON payload to perform firmware configuration or firmware update using the UpdateCapsule runtime API or using mass storage delivery.

23.5.1 EFI_JSON_CAPSULE_ID_GUID

GUID

```c
// {67D6F4CD-D6B8-4573-BF4A-DE5E252D61AE}
#define EFI_JSON_CAPSULE_ID_GUID
{0x67d6f4cd, 0xd6b8, 0x4573, \
{0xbf, 0x4a, 0xde, 0x5e, 0x25, 0x2d, 0x61, 0xae }}
```

Description

23.5. Delivering Capsule Containing JSON payload 914
This GUID is used in the CapsuleGuid field of EFI_CAPSULE_HEADER struct within a capsule constructed according to the definitions of Update Capsule. Use of this GUID indicates a capsule with body conforming to the additional structure defined in Defined JSON Capsule Data Structure.

When delivered to platform firmware QueryCapsuleCapabilities() the capsule will be examined according to the structure defined in Defined JSON Capsule Data Structure, and if it is possible for the platform to process that then EFI_SUCCESS will be returned.

When delivered to platform firmware UpdateCapsule() the capsule will be examined according to the structure defined in Defined JSON Capsule Data Structure, and if it is possible for the platform to process that the update will be processed.

By definition, firmware configuration and firmware update are not available in EFI runtime. Depending on platform capabilities, EFI runtime delivery of the capsule may not be supported, and may return an error when delivered in EFI runtime with CAPSULE_FLAGS_PERSIST_ACROSS_RESET bit defined. However, any platform supporting this capability is required to accept this form of capsule in Boot Services, including optional use of the CAPSULE_FLAGS_PERSIST_ACROSS_RESET bit.

### 23.5.2 Defined JSON Capsule Data Structure

**Structure of the Capsule Body**

A generic EFI Capsule Body is defined in Update Capsule. When an EFI Capsule is identified by EFI_JSON_CAPSULE_ID_GUID, the internal structure of the capsule header is defined in this section, see EFI_JSON_CAPSULE_HEADER. Note that if multiple JSON capsules are delivered together, each JSON capsule should contain one EFI_CAPSULE_HEADER and one EFI_JSON_CAPSULE_HEADER separately.

**Related Definitions**

```c
#pragma pack(1)
typedef struct {
  UINT32 Version;
  UINT32 CapsuleId;
  UINT32 PayloadLength;
  UINT8 Payload[];
} EFI_JSON_CAPSULE_HEADER;
#pragma pack ()
```

**Version**

Version of the structure, initially 0x00000001.

**CapsuleId**

The unique identifier of this capsule.

**PayloadLength**

The length of the JSON payload immediately following this header, in bytes.

**Payload**

Variable length buffer containing the JSON payload that should be parsed and applied to the system. The definition of the JSON schema used in the payload is beyond the scope of this specification.

**Description**

The EFI_JSON_CAPSULE_HEADER structure is located at the lowest offset within the body of the capsule identified by EFI_JSON_CAPSULE_ID_GUID. It is expected that drivers which process the JSON payload have the specific knowledge of the JSON schema used in the payload. The drivers should parse the JSON payload firstly to understand
whether the capsule wants to perform firmware configure or firmware update then route the JSON payload to corresponding modules. For instance, the capsule may be delivered to `EFI_FIRMWARE_MANAGEMENT_PROTOCOL` instance to update the firmware image.

**Structure of the Configuration Data**

During the system boot, current configuration data or cached configuration data is reported to the EFI System Configuration Table with `EFI_JSON_CONFIG_DATA_TABLE_GUID` according to the value of `EFI_OS_INDICATIONS_JSON_CONFIG_DATA_REFRESH` bit in `OsIndications`. The structure to record the configuration data is defined in this section, see `EFI_JSON_CAPSULE_CONFIG_DATA`.

**Related Definitions**

```c
#pragma pack(1)
typedef struct {
    UINT32 Version;
    UINT32 TotalLength;
    EFI_JSON_CONFIG_DATA_ITEM ConfigDataList[];
} EFI_JSON_CAPSULE_CONFIG_DATA;
#pragma pack ()
```

**Version**

Version of the structure, initially 0x00000001.

**TotalLength**

The total length of `EFI_JSON_CAPSULE_CONFIG_DATA`, in bytes.

**ConfigDataList**

Array of configuration data groups. Type `EFI_JSON_CONFIG_DATA_ITEM` is defined below.

```c
typedef struct {
    UINT32 ConfigDataLength;
    UINT8 ConfigData[];
} EFI_JSON_CONFIG_DATA_ITEM;
```

**ConfigDataLength**

The length of the following `ConfigData`, in bytes.

**ConfigData**

Variable length buffer containing the JSON payload that describes one group of configuration data within current system. The definition of the JSON schema used in this payload is beyond the scope of this specification.

**Description**

For supporting multiple groups of configuration data, a list of `EFI_JSON_CONFIG_DATA_ITEM` are included in `EFI_JSON_CAPSULE_CONFIG_DATA` and each item indicates one group of configuration data. It is expected that particular drivers have the specific knowledge of the JSON schema used in the payload so that they can describe system configuration data in JSON then install to the EFI System Configuration Table. The drivers should check `EFI_OS_INDICATIONS_JSON_CONFIG_DATA_REFRESH` bit in `OsIndications` to understand whether they need collect current configuration firstly.
23.5.3 Firmware Processing of the Capsule Identified by EFI_JSON_CAPSULE_ID_GUID

1. Capsule is presented to system firmware via call to UpdateCapsule() or using mass storage delivery procedure of Delivery of Capsules via file on Mass Storage Device. The capsule must be constructed to consist of a single EFI_JSON_CAPSULE_HEADER structure with JSON payload follows. A capsule in which PayloadLength is zero will not be processed.

2. Capsule is recognized by EFI_CAPSULE_HEADER member CapsuleGuid equal to EFI_JSON_CAPSULE_ID_GUID. CAPSULE_FLAGS_POPULATE_SYSTEM_TABLE flag must be 0.

3. If system is not in boot services and platform does not support persistence of capsule across reset when initiated within EFI Runtime, EFI_OUT_OF_RESOURCES error is returned.

4. If device requires hardware reset to unlock flash write protection, CAPSULE_FLAGS_PERSIST_ACROSS_RESET and optionally CAPSULE_FLAGS_INITIATE_RESET should be set to 1 in the EFI_CAPSULE_HEADER.

5. When reset is requested using CAPSULE_FLAGS_PERSIST_ACROSS_RESET, the capsule is processed in Boot Services, before the EFI_EVENT_GROUP_READY_TO_BOOT event.

6. All scatter-gather fragmentation is removed by the platform firmware and the capsule is processed as a contiguous buffer.

7. When a capsule identified by EFI_JSON_CAPSULE_ID_GUID is received, the system firmware shall place a pointer to the coalesced capsule in the EFI System Configuration Table with EFI_JSON_CAPSULE_DATA_TABLE_GUID before loading any third party modules such as option ROM. If multiple capsules identified by EFI_JSON_CAPSULE_ID_GUID are received, the system firmware shall place a list of pointers to the capsules, preceded by a UINTN that represents the number of pointers, in the EFI System Configuration Table with EFI_JSON_CAPSULE_DATA_TABLE_GUID before loading any third party modules such as option ROM. The UINTN and each pointer must be naturally aligned.

8. The system configuration driver should check EFI System Configuration Table and parse the JSON payload, to identify the configuration data type of JSON payload, and route the JSON payload to corresponding modules. The corresponding capsule pointer shall be removed from the EFI System Configuration Table and also be cleared after it is processed.

9. The processing result shall be installed to EFI System Configuration Table using the format of EFI_CAPSULE_RESULT_VARIABLE_HEADER and EFI_CAPSULE_RESULT_VARIABLE_JSON defined in Section 8.5.6 with EFI_JSON_CAPSULE_RESULT_TABLE_GUID. If the capsule is delivered via mass storage device, the process result shall be recorded by using UEFI variables as described in UEFI variable reporting on the Success or any Errors encountered in processing of capsules after restart.
24.1 Simple Network Protocol

This section defines the Simple Network Protocol. This protocol provides a packet level interface to a network adapter.

24.1.1 EFI_SIMPLE_NETWORK_PROTOCOL

Summary

The EFI_SIMPLE_NETWORK_PROTOCOL provides services to initialize a network interface, transmit packets, receive packets, and close a network interface.

GUID

```c
#define EFI_SIMPLE_NETWORK_PROTOCOL_GUID
{0xA19832B9,0xAC25,0x11D3,
 {0x9A,0x2D,0x00,0x90,0x27,0x3f,0xc1,0x4d}}
```

Revision Number

```c
#define EFI_SIMPLE_NETWORK_PROTOCOL_REVISION 0x00010000
```

Protocol Interface Structure

```c
typedef struct \_EFI_SIMPLE_NETWORK_PROTOCOL\_ {
    UINT64 Revision;
    EFI_SIMPLE_NETWORK_START Start;
    EFI_SIMPLE_NETWORK_STOP Stop;
    EFI_SIMPLE_NETWORK_INITIALIZE Initialize;
    EFI_SIMPLE_NETWORK_RESET Reset;
    EFI_SIMPLE_NETWORK_SHUTDOWN Shutdown;
    EFI_SIMPLE_NETWORK_RECEIVE_FILTERS ReceiveFilters;
    EFI_SIMPLE_NETWORK_STATION_ADDRESS StationAddress;
    EFI_SIMPLE_NETWORK_STATISTICS Statistics;
    EFI_SIMPLE_NETWORK_MCAST_IP_TO_MAC MCastIpToMac;
    EFI_SIMPLE_NETWORK_NVDATA NvData;
    EFI_SIMPLE_NETWORK_GET_STATUS GetStatus;
    EFI_SIMPLE_NETWORK_TRANSMIT Transmit;
    EFI_SIMPLE_NETWORK_RECEIVE Receive;
    EFI_EVENT WaitForPacket;
} EFI_SIMPLE_NETWORK_PROTOCOL;
```

(continues on next page)
EFI_SIMPLE_NETWORK_MODE *Mode;
}

CPU Architecture

Parameters

Revision
Revision of the EFI_SIMPLE_NETWORK_PROTOCOL. All future revisions must be backwards compatible. If a future version is not backwards compatible it is not the same GUID.

Start
Prepares the network interface for further command operations. No other EFI_SIMPLE_NETWORK_PROTOCOL interface functions will operate until this call is made. See the EFI_SIMPLE_NETWORK.Start() function description.

Stop
Stops further network interface command processing. No other EFI_SIMPLE_NETWORK_PROTOCOL interface functions will operate after this call is made until another Start() call is made. See the EFI_SIMPLE_NETWORK.Stop() function description.

Initialize
Resets the network adapter and allocates the transmit and receive buffers. See the EFI_SIMPLE_NETWORK.Initialize() function description.

Reset
Resets the network adapter and reinitializes it with the parameters provided in the previous call to Initialize(). See the EFI_SIMPLE_NETWORK.Reset() function description.

Shutdown
Resets the network adapter and leaves it in a state safe for another driver to initialize. The memory buffers assigned in the Initialize() call are released. After this call, only the Initialize() or Stop() calls may be used. See the EFI_SIMPLE_NETWORK.Shutdown() function description.

ReceiveFilters
Enables and disables the receive filters for the network interface and, if supported, manages the filtered multicast HW MAC (Hardware Media Access Control) address list. See the EFI_SIMPLE_NETWORK.ReceiveFilters() function description.

StationAddress
Modifies or resets the current station address, if supported. See the EFI_SIMPLE_NETWORK.StationAddress() function description.

Statistics
Collects statistics from the network interface and allows the statistics to be reset. See the EFI_SIMPLE_NETWORK.Statistics() function description.

MCastIpToMac
Maps a multicast IP address to a multicast HW MAC address. See the EFI_SIMPLE_NETWORK.MCastIpToMAC() function description.

NvData
Reads and writes the contents of the NVRAM devices attached to the network interface. See the EFI_SIMPLE_NETWORK.NvData() function description.

GetStatus
Reads the current interrupt status and the list of recycled transmit buffers from the network interface. See the EFI_SIMPLE_NETWORK.GetStatus() function description.

Transmit
Places a packet in the transmit queue. See EFI_SIMPLE_NETWORK.Transmit() function description.

24.1. Simple Network Protocol
Receive
Retrieves a packet from the receive queue, along with the status flags that describe the packet type. See the `EFI_SIMPLE_NETWORK.Receive()` function description.

WaitForPacket
Event used with `EFI_BOOT_SERVICES.WaitForEvent()` to wait for a packet to be received.

Mode
Pointer to the EFI_SIMPLE_NETWORK_MODE data for the device. See “Related Definitions” below.

Related Definitions

```c
typedef struct {
  UINT32 State;
  UINT32 HwAddressSize;
  UINT32 MediaHeaderSize;
  UINT32 MaxPacketSize;
  UINT32 NvRamSize;
  UINT32 NvRamAccessSize;
  UINT32 ReceiveFilterMask;
  UINT32 ReceiveFilterSetting;
  UINT32 MaxMCastFilterCount;
  UINT32 MCastFilterCount;
  EFI_MAC_ADDRESS MCastFilter[MAX_MCAST_FILTER_CNT];
  EFI_MAC_ADDRESS CurrentAddress;
  EFI_MAC_ADDRESS BroadcastAddress;
  EFI_MAC_ADDRESS PermanentAddress;
  UINT8 IfType;
  BOOLEAN MacAddressChangeable;
  BOOLEAN MultipleTxSupported;
  BOOLEAN MediaPresentSupported;
  BOOLEAN MediaPresent;
} EFI_SIMPLE_NETWORK_MODE;
```

State
Reports the current state of the network interface (see `EFI_SIMPLE_NETWORK_STATE_WORK_STATE` below). When an EFI_SIMPLE_NETWORK_PROTOCOL driver initializes a network interface, the network interface is left in the EfiSimpleNetworkStopped state.

HwAddressSize
The size, in bytes, of the network interface’s HW address.

MediaHeaderSize
The size, in bytes, of the network interface’s media header.

MaxPacketSize
The maximum size, in bytes, of the packets supported by the network interface.
NvRamSize
The size, in bytes, of the NVRAM device attached to the network interface. If an NVRAM device is not attached to the network interface, then this field will be zero. This value must be a multiple of NvramAccessSize.

NvRamAccessSize
The size that must be used for all NVRAM reads and writes. The start address for NVRAM read and write operations and the total length of those operations, must be a multiple of this value. The legal values for this field are 0, 1, 2, 4, and 8. If the value is zero, then no NVRAM devices are attached to the network interface.

ReceiveFilterMask
The multicast receive filter settings supported by the network interface.

ReceiveFilterSetting
The current multicast receive filter settings. See “Bit Mask Values for ReceiveFilterSetting ” below.

MaxMCastFilterCount
The maximum number of multicast address receive filters supported by the driver. If this value is zero, then ReceiveFilters() cannot modify the multicast address receive filters. This field may be less than MAX_MCAST_FILTER_CNT (see below).

MCastFilterCount
The current number of multicast address receive filters.

MCastFilter
Array containing the addresses of the current multicast address receive filters.

CurrentAddress
The current HW MAC address for the network interface.

BroadcastAddress
The current HW MAC address for broadcast packets.

PermanentAddress
The permanent HW MAC address for the network interface.

IfType
The interface type of the network interface. See RFC 3232, section “Number Hardware Type.”

MacAddressChangeable
TRUE if the HW MAC address can be changed.

MultipleTxSupported
TRUE if the network interface can transmit more than one packet at a time.

MediaPresentSupported
TRUE if the presence of media can be determined; otherwise FALSE. If FALSE, MediaPresent cannot be used.

MediaPresent
TRUE if media are connected to the network interface; otherwise FALSE. This field shows the media present status as of the most recent GetStatus() call.

```c
typedef enum {
  EfiSimpleNetworkStopped,
  EfiSimpleNetworkStarted,
  EfiSimpleNetworkInitialized,
  EfiSimpleNetworkMaxState
} EFI_SIMPLE_NETWORK_STATE;
```

(continues on next page)
//*******************************************************
// MAX_MCAST_FILTER_CNT
//*******************************************************
#define MAX_MCAST_FILTER_CNT 16

//*******************************************************
// Bit Mask Values for ReceiveFilterSetting.
//*******************************************************
#define EFI_SIMPLE_NETWORK_RECEIVE_UNICAST 0x01
#define EFI_SIMPLE_NETWORK_RECEIVE_MULTICAST 0x02
#define EFI_SIMPLE_NETWORK_RECEIVE_BROADCAST 0x04
#define EFI_SIMPLE_NETWORK_RECEIVE_PROMISCUOUS 0x08
#define EFI_SIMPLE_NETWORK_RECEIVE_PROMISCUOUS_MULTICAST 0x10

Description

The EFI_SIMPLE_NETWORK_PROTOCOL protocol is used to initialize access to a network adapter. Once the
network adapter initializes, the EFI_SIMPLE_NETWORK_PROTOCOL protocol provides services that allow packets
to be transmitted and received. This provides a packet level interface that can then be used by higher level drivers to
produce boot services like DHCP, TFTP, and MTFTP. In addition, this protocol can be used as a building block in a
full UDP and TCP/IP implementation that can produce a wide variety of application level network interfaces. See the
Preboot Execution Environment (PXE) Specification for more information.

NOTE The underlying network hardware may only be able to access 4 GiB (32-bits) of system memory. Any requests
to transfer data to/from memory above 4 GiB with 32-bit network hardware will be double-buffered (using intermediate
buffers below 4 GiB) and will reduce performance.

NOTE The same handle can have an instance of the EFI_ADAPTER_INFORMATION_PROTOCOL with a
EFI_ADAPTER_INFO_MEDIA_STATE type structure.

24.1.2 EFI_SIMPLE_NETWORK.Start()

Summary

Changes the state of a network interface from “stopped” to “started.”

Prototype

typedef
 EFI_STATUS
(EFI_API *EFI_SIMPLE_NETWORK_START) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL *This
    );

Parameters

This

A pointer to the EFI_SIMPLE_NETWORK_PROTOCOL instance.

Description

This function starts a network interface. If the network interface successfully starts, then EFI_SUCCESS will be
returned.
Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The network interface was started.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The network interface is already in the started state.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This parameter was NULL or did not point to a valid EFI_SIMPLE_NETWORK_PROTOCOL structure.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The command could not be sent to the network interface.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This function is not supported by the network interface.</td>
</tr>
</tbody>
</table>

24.1.3 EFI_SIMPLE_NETWORK.Stop()

Summary
Changes the state of a network interface from “started” to “stopped.”

Prototype

typedef EFI_STATUS (EFIAPI *EFI.Simple.Network_Stop) (  
    IN EFI_SIMPLE_NETWORK_PROTOCOL *This  
);

Parameters

This
A pointer to the EFI_SIMPLE_NETWORK_PROTOCOL instance.

Description
This function stops a network interface. This call is only valid if the network interface is in the started state. If the network interface was successfully stopped, then EFI_SUCCESS will be returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The network interface was stopped.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The network interface has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This parameter was NULL or did not point to a valid EFI_SIMPLE_NETWORK_PROTOCOL structure.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The command could not be sent to the network interface.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This function is not supported by the network interface.</td>
</tr>
</tbody>
</table>

24.1.4 EFI_SIMPLE_NETWORK.Initialize()

Summary
Resets a network adapter and allocates the transmit and receive buffers required by the network interface; optionally, also requests allocation of additional transmit and receive buffers.

Prototype

typedef EFI_STATUS (EFIAPI *EFI.Simple.Network.Initialize) (  
     (continues on next page)
IN EFI_SIMPLE_NETWORK_PROTOCOL *This,
IN UINTN ExtraRxBufferSize OPTIONAL,
IN UINTN ExtraTxBufferSize OPTIONAL
);

Parameters

This
A pointer to the \textit{EFI_SIMPLE_NETWORK_PROTOCOL} instance.

ExtraRxBufferSize
The size, in bytes, of the extra receive buffer space that the driver should allocate for the network interface. Some network interfaces will not be able to use the extra buffer, and the caller will not know if it is actually being used.

ExtraTxBufferSize
The size, in bytes, of the extra transmit buffer space that the driver should allocate for the network interface. Some network interfaces will not be able to use the extra buffer, and the caller will not know if it is actually being used.

Description
This function allocates the transmit and receive buffers required by the network interface. If this allocation fails, then EFI\_OUT\_OF\_RESOURCES is returned. If the allocation succeeds and the network interface is successfully initialized, then EFI\_SUCCESS will be returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The network interface was initialized.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The network interface has not been started.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There was not enough memory for the transmit and receive buffers.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This parameter was \textit{NULL} or did not point to a valid\textit{EFI_SIMPLE_NETWORK_PROTOCOL} structure.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The command could not be sent to the network interface.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The increased buffer size feature is not supported.</td>
</tr>
</tbody>
</table>

24.1.5 \textit{EFI\_SIMPLE\_NETWORK}\_Reset()

Summary
Resets a network adapter and reinitializes it with the parameters that were provided in the previous call to \textit{EFI\_SIMPLE\_NETWORK\_Initialize}.

Prototype

typedef
EFI\_STATUS
(EFI\_API \*EFI\_SIMPLE\_NETWORK\_RESET) (
    IN EFI\_SIMPLE\_NETWORK\_PROTOCOL \*This,
    IN BOOLEAN ExtendedVerification
);

Parameters

This
A pointer to the \textit{EFI\_SIMPLE\_NETWORK\_PROTOCOL} instance.
Extended Verification
Indicates that the driver may perform a more exhaustive verification operation of the device during reset.

Description
This function resets a network adapter and reinitializes it with the parameters that were provided in the previous call to Initialize(). The transmit and receive queues are emptied and all pending interrupts are cleared. Receive filters, the station address, the statistics, and the multicast-IP-to-HW MAC addresses are not reset by this call. If the network interface was successfully reset, then EFI_SUCCESS will be returned. If the driver has not been initialized, EFI_DEVICE_ERROR will be returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The network interface was reset.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The network interface has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the parameters has an unsupported value.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The command could not be sent to the network interface.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This function is not supported by the network interface.</td>
</tr>
</tbody>
</table>

24.1.6 EFI_SIMPLE_NETWORK.Shutdown()

Summary
Resets a network adapter and leaves it in a state that is safe for another driver to initialize.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_SIMPLE_NETWORK_SHUTDOWN) (  
   IN EFI_SIMPLE_NETWORK_PROTOCOL *This  
);

Parameters

This
A pointer to the EFI_SIMPLE_NETWORK_PROTOCOL instance.

Description
This function releases the memory buffers assigned in the EFI_SIMPLE_NETWORK.Initialize() call. Pending transmits and receives are lost, and interrupts are cleared and disabled. After this call, only the Initialize() and EFI_SIMPLE_NETWORK.Stop() calls may be used. If the network interface was successfully shutdown, then EFI_SUCCESS will be returned. If the driver has not been initialized, EFI_DEVICE_ERROR will be returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The network interface was shutdown.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The network interface has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This parameter was NULL or did not point to a valid EFI_SIMPLE_NETWORK_PROTOCOL structure.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The command could not be sent to the network interface.</td>
</tr>
</tbody>
</table>
24.1.7 EFI_SIMPLE_NETWORK.ReceiveFilters()

Summary
Manages the multicast receive filters of a network interface.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_SIMPLE_NETWORK_RECEIVE_FILTERS) (  
  IN EFI_SIMPLE_NETWORK_PROTOCOL *This,
  IN UINT32 Enable,
  IN UINT32 Disable,
  IN BOOLEAN ResetMCastFilter,
  IN UINTN MCastFilterCnt OPTIONAL,
  IN EFI_MAC_ADDRESS MCastFilter OPTIONAL,
);
```

Parameters

This
A pointer to the EFI_SIMPLE_NETWORK_PROTOCOL instance.

Enable
A bit mask of receive filters to enable on the network interface.

Disable
A bit mask of receive filters to disable on the network interface. For backward compatibility with EFI 1.1 platforms, the EFI_SIMPLE_NETWORK_RECEIVE_MULTICAST bit must be set when the ResetMCastFilter parameter is TRUE.

ResetMCastFilter
Set to TRUE to reset the contents of the multicast receive filters on the network interface to their default values.

MCastFilterCnt
Number of multicast HW MAC addresses in the new MCastFilter list. This value must be less than or equal to the MCastFilterCnt field of EFI_SIMPLE_NETWORK_MODE. This field is optional if ResetMCastFilter is TRUE.

MCastFilter
A pointer to a list of new multicast receive filter HW MAC addresses. This list will replace any existing multicast HW MAC address list. This field is optional if ResetMCastFilter is TRUE.

Description
This function is used enable and disable the hardware and software receive filters for the underlying network device.

The receive filter change is broken down into three steps:

- The filter mask bits that are set (ON) in the Enable parameter are added to the current receive filter settings.
- The filter mask bits that are set (ON) in the Disable parameter are subtracted from the updated receive filter settings.
- If the resulting receive filter setting is not supported by the hardware a more liberal setting is selected.

If the same bits are set in the Enable and Disable parameters, then the bits in the Disable parameter takes precedence.

If the ResetMCastFilter parameter is TRUE, then the multicast address list filter is disabled (irregardless of what other multicast bits are set in the Enable and Disable parameters). The SNP->Mode->MCastFilterCount field is set to zero. The SNP->Mode->MCastFilter contents are undefined.
After enabling or disabling receive filter settings, software should verify the new settings by checking the Snp->Mode->ReceiveFilterSettings, Snp->Mode->MCastFilterCount and Snp->Mode->MCastFilter fields.

**Note:** Some network drivers and/or devices will automatically promote receive filter settings if the requested setting can not be honored. For example, if a request for four multicast addresses is made and the underlying hardware only supports two multicast addresses the driver might set the promiscuous or promiscuous multicast receive filters instead. The receiving software is responsible for discarding any extra packets that get through the hardware receive filters.

**Note:** To disable all receive filter hardware, the network driver must be Shutdown() and Stopped(). Calling ReceiveFilters() with Disable set to Snp->Mode->ReceiveFilterSettings will make it so no more packets are returned by the Receive() function, but the receive hardware may still be moving packets into system memory before inspecting and discarding them. Unexpected system errors, reboots and hangs can occur if an OS is loaded and the network devices are not Shutdown() and Stopped().

If ResetMCastFilter is TRUE, then the multicast receive filter list on the network interface will be reset to the default multicast receive filter list. If ResetMCastFilter is FALSE, and this network interface allows the multicast receive filter list to be modified, then the MCastFilterCnt and MCastFilter are used to update the current multicast receive filter list. The modified receive filter list settings can be found in the MCastFilter field of EFI_SIMPLE_NETWORK_MODE in Network Protocols — SNP, PXE, BIS and HTTP Boot. If the network interface does not allow the multicast receive filter list to be modified, then EFI_INVALID_PARAMETER will be returned. If the driver has not been initialized, EFI_DEVICE_ERROR will be returned.

If the receive filter mask and multicast receive filter list have been successfully updated on the network interface, EFI_SUCCESS will be returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The multicast receive filter list was updated.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The network interface has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>• One or more of the following conditions is TRUE :</td>
</tr>
<tr>
<td></td>
<td>• This is NULL</td>
</tr>
<tr>
<td></td>
<td>• There are bits set in Enable that are not set in Snp-&gt;Mode-&gt;ReceiveFilterMask</td>
</tr>
<tr>
<td></td>
<td>• There are bits set in Disable that are not set in Snp-&gt;Mode-&gt;ReceiveFilterMask</td>
</tr>
</tbody>
</table>
|                       | • Multicast is being enabled (the EFI_SIMPLE_NETWORK_RECEIVE_MULTICAST bit is set in Enable, it is not set in Disable, and ResetMCastFilter is FALSE ) and MCastFilterCount is zero
|                       | • Multicast is being enabled and MCastFilterCount is greater than Snp->Mode->MaxMCastFilterCount |
|                       | • Multicast is being enabled and MCastFilter is NULL                        |
|                       | • Multicast is being enabled and one or more of the addresses in the MCastFilter list are not valid multicast MAC addresses |
| EFI_DEVICE_ERROR      | • One or more of the following conditions is TRUE :                            |
|                       | • The network interface has been started but has not been initialized         |
|                       | • An unexpected error was returned by the underlying network driver or device |
| EFI_UNSUPPORTED       | This function is not supported by the network interface.                     |
24.1.8 EFI_SIMPLE_NETWORK.StationAddress()

Summary
Modifies or resets the current station address, if supported.

Prototype

```c
typedef EFI_STATUS
(EFIAPIC *EFI_SIMPLE_NETWORK_STATION_ADDRESS) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL *This,
    IN BOOLEAN Reset,
    IN EFI_MAC_ADDRESS *New OPTIONAL
);
```

Parameters

This
A pointer to the `EFI_SIMPLE_NETWORK_PROTOCOL` instance.

Reset
Flag used to reset the station address to the network interface’s permanent address.

New
New station address to be used for the network interface.

Description
This function modifies or resets the current station address of a network interface, if supported. If `Reset` is `TRUE`, then the current station address is set to the network interface’s permanent address. If `Reset` is `FALSE`, and the network interface allows its station address to be modified, then the current station address is changed to the address specified by `New`. If the network interface does not allow its station address to be modified, then `EFI_INVALID_PARAMETER` will be returned. If the station address is successfully updated on the network interface, `EFI_SUCCESS` will be returned. If the driver has not been initialized, `EFI_DEVICE_ERROR` will be returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The network interface’s station address was updated.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The Simple Network Protocol interface has not been started by calling <code>Start()</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>New</code> station address was not accepted by the NIC.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The NIC does not support changing the network interface’s station address.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The Simple Network Protocol interface has not been initialized by calling <code>Initialize()</code>.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An error occurred attempting to set the new station address.</td>
</tr>
</tbody>
</table>

24.1. Simple Network Protocol
24.1.9 EFI_SIMPLE_NETWORK.Statistics()

Summary
Resets or collects the statistics on a network interface.

Prototype

typedef
EFI_STATUS
(EIFIAPIT *EFI_SIMPLE_NETWORK_STATISTICS) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL *This,
    IN BOOLEAN Reset,
    IN OUT UINTN *StatisticsSize OPTIONAL,
    OUT EFI_NETWORK_STATISTICS *StatisticsTable OPTIONAL
);

Parameters

This
A pointer to the EFI_SIMPLE_NETWORK_PROTOCOL instance.

Reset
Set to TRUE to reset the statistics for the network interface.

StatisticsSize
On input the size, in bytes, of StatisticsTable. On output the size, in bytes, of the resulting table of statistics.

StatisticsTable
A pointer to the EFI_NETWORK_STATISTICS in Network Protocols — SNP, PXE, BIS and HTTP Boot structure that contains the statistics. Type EFI_NETWORK_STATISTICS is defined in “Related Definitions” below.

Related Definitions

//*******************************************************
// EFI_NETWORK_STATISTICS
// Any statistic value that is -1 is not available
// on the device and is to be ignored.
//*******************************************************
typedef struct {
    UINT64    RxTotalFrames;
    UINT64    RxGoodFrames;
    UINT64    RxUndersizeFrames;
    UINT64    RxOversizeFrames;
    UINT64    RxDroppedFrames;
    UINT64    RxUnicastFrames;
    UINT64    RxBroadcastFrames;
    UINT64    RxMulticastFrames;
    UINT64    RxCrcErrorFrames;
    UINT64    RxTotalBytes;
    UINT64    TxTotalFrames;
    UINT64    TxGoodFrames;
    UINT64    TxUndersizeFrames;
} EFI_NETWORK_STATISTICS;
UINT64 TxOversizeFrames;
UINT64 TxDroppedFrames;
UINT64 TxUnicastFrames;
UINT64 TxBroadcastFrames;
UINT64 TxMulticastFrames;
UINT64 TxCrcErrorFrames;
UINT64 TxTotalBytes;
UINT64 Collisions;
UINT64 UnsupportedProtocol;
UINT64 RxDuplicatedFrames;
UINT64 RxDecryptErrorFrames;
UINT64 TxErrorFrames;
UINT64 TxRetryFrames;
} EFI_NETWORK_STATISTICS;

RxTotalFrames
Total number of frames received. Includes frames with errors and dropped frames.

RxGoodFrames
Number of valid frames received and copied into receive buffers.

RxUndersizeFrames
Number of frames below the minimum length for the communications device.

RxOversizeFrames
Number of frames longer than the maximum length for the communications device.

RxDroppedFrames
Valid frames that were dropped because receive buffers were full.

RxUnicastFrames
Number of valid unicast frames received and not dropped.

RxBroadcastFrames
Number of valid broadcast frames received and not dropped.

RxMulticastFrames
Number of valid multicast frames received and not dropped.

RxCrcErrorFrames
Number of frames with CRC or alignment errors.

RxTotalBytes
Total number of bytes received. Includes frames with errors and dropped frames.

TxTotalFrames
Total number of frames transmitted. Includes frames with errors and dropped frames.

TxGoodFrames
Number of valid frames transmitted and copied into receive buffers.

TxUndersizeFrames
Number of frames below the minimum length for the media. This would be less than 64 for Ethernet.

TxOversizeFrames
Number of frames longer than the maximum length for the media. This would be greater than 1500 for Ethernet.

TxDroppedFrames
Valid frames that were dropped because receive buffers were full.
**TxUnicastFrames**
Number of valid unicast frames transmitted and not dropped.

**TxBroadcastFrames**
Number of valid broadcast frames transmitted and not dropped.

**TxMulticastFrames**
Number of valid multicast frames transmitted and not dropped.

**TxCrcErrorFrames**
Number of frames with CRC or alignment errors.

**TxTotalBytes**
Total number of bytes transmitted. Includes frames with errors and dropped frames.

**Collisions**
Number of collisions detected on this subnet.

**UnsupportedProtocol**
Number of frames destined for unsupported protocol.

**RxDuplicatedFrames**
Number of valid frames received that were duplicated.

**RxDecryptErrorFrames**
Number of encrypted frames received that failed to decrypt.

**TxErrorFrames**
Number of frames that failed to transmit after exceeding the retry limit.

**TxRetryFrames**
Number of frames transmitted successfully after more than one attempt.

**Description**
This function resets or collects the statistics on a network interface. If the size of the statistics table specified by *StatisticsSize* is not big enough for all the statistics that are collected by the network interface, then a partial buffer of statistics is returned in *StatisticsTable*, *StatisticsSize* is set to the size required to collect all the available statistics, and *EFI_BUFFER_TOO_SMALL* is returned.

If *StatisticsSize* is big enough for all the statistics, then *StatisticsTable* will be filled, *StatisticsSize* will be set to the size of the returned *StatisticsTable* structure, and *EFI_SUCCESS* is returned. If the driver has not been initialized, *EFI_DEVICE_ERROR* will be returned.

If *Reset* is **FALSE**, and both *StatisticsSize* and *StatisticsTable* are NULL, then no operations will be performed, and *EFI_SUCCESS* will be returned.

If *Reset* is **TRUE**, then all of the supported statistics counters on this network interface will be reset to zero.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested operation succeeded.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The Simple Network Protocol interface has not been started by calling <em>Start()</em></td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td><em>StatisticsSize</em> is not <strong>NULL</strong> and <em>StatisticsTable</em> is <strong>NULL</strong>. The current buffer size that is needed to hold all the statistics is returned in <em>StatisticsSize</em>.</td>
</tr>
<tr>
<td>EFIBUFFER_TOO_SMALL</td>
<td><em>StatisticsSize</em> is not <strong>NULL</strong> and <em>StatisticsTable</em> is <strong>NULL</strong>. The current buffer size that is needed to hold all the statistics is returned in <em>StatisticsSize</em>. A partial set of statistics is returned in <em>StatisticsTable</em>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><em>StatisticsSize</em> is <strong>NULL</strong> and <em>StatisticsTable</em> is <strong>NULL</strong>.</td>
</tr>
</tbody>
</table>

continues on next page
Table 24.7 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The Simple Network Protocol interface has not been initialized by calling</td>
</tr>
<tr>
<td></td>
<td>Initialize().</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An error was encountered collecting statistics from the NIC.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The NIC does not support collecting statistics from the network interface.</td>
</tr>
</tbody>
</table>

### 24.1.10 EFI_SIMPLE_NETWORK.MCastIPtoMAC()

#### Summary

Converts a multicast IP address to a multicast HW MAC address.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_SIMPLE_NETWORK_MCAST_IP_TO_MAC) (  
   IN EFI_SIMPLE_NETWORK_PROTOCOL *This,  
   IN BOOLEAN IPv6,  
   IN EFI_IP_ADDRESS *IP,  
   OUT EFI_MAC_ADDRESS *MAC  
);
```

#### Parameters

- **This**
  A pointer to the `EFI_SIMPLE_NETWORK_PROTOCOL` instance.

- **IPv6**
  Set to `TRUE` if the multicast IP address is IPv6 [RFC 2460]. Set to `FALSE` if the multicast IP address is IPv4 [RFC 791].

- **IP**
  The multicast IP address that is to be converted to a multicast HW MAC address.

- **MAC**
  The multicast HW MAC address that is to be generated from IP.

#### Description

This function converts a multicast IP address to a multicast HW MAC address for all packet transactions. If the mapping is accepted, then EFI_SUCCESS will be returned.

#### Status Codes Returned

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The multicast IP address was mapped to the multicast HW MAC address.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The Simple Network Protocol interface has not been started by calling</td>
</tr>
<tr>
<td></td>
<td>Start().</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>IP is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>MAC is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>IP does not point to a valid IPv4 or IPv6 multicast address.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The Simple Network Protocol interface has not been initialized by calling</td>
</tr>
<tr>
<td></td>
<td>Initialize().</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>IPv6 is TRUE and the implementation does not support IPv6 multicast to</td>
</tr>
<tr>
<td></td>
<td>MAC address conversion.</td>
</tr>
</tbody>
</table>
24.1.11 EFI_SIMPLE_NETWORK.NvData()

Summary
Performs read and write operations on the NVRAM device attached to a network interface.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_SIMPLE_NETWORK_NVDATA)(
   IN EFI_SIMPLE_NETWORK_PROTOCOL *This,
   IN BOOLEAN ReadWrite,
   IN UINTN Offset,
   IN UINTN BufferSize,
   IN OUT VOID *Buffer
);
```

Parameters

This
A pointer to the EFI_SIMPLE_NETWORK_PROTOCOL instance.

ReadWrite
TRUE for read operations, FALSE for write operations.

Offset
Byte offset in the NVRAM device at which to start the read or write operation. This must be a multiple of NvRamAccessSize and less than NvRamSize. (See EFI_SIMPLE_NETWORK_MODE in Network Protocols — SNP, PXE, BIS and HTTP Boot.

BufferSize
The number of bytes to read or write from the NVRAM device. This must also be a multiple of 2.

Buffer
A pointer to the data buffer.

Description
This function performs read and write operations on the NVRAM device attached to a network interface. If ReadWrite is TRUE, a read operation is performed. If ReadWrite is FALSE, a write operation is performed.

Offset specifies the byte offset at which to start either operation. Offset must be a multiple of NvRamAccessSize, and it must have a value between zero and NvRamSize.

BufferSize specifies the length of the read or write operation. BufferSize must also be a multiple of NvRamAccessSize, and Offset + BufferSize must not exceed NvRamSize.

If any of the above conditions is not met, then EFI_INVALID_PARAMETER will be returned.

If all the conditions are met and the operation is “read,” the NVRAM device attached to the network interface will be read into Buffer and EFI_SUCCESS will be returned. If this is a write operation, the contents of Buffer will be used to update the contents of the NVRAM device attached to the network interface and EFI_SUCCESS will be returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The NVRAM access was performed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The network interface has not been started.</td>
</tr>
</tbody>
</table>
### 24.1.12 EFI_SIMPLE_NETWORK.GetStatus()

**Summary**
Reads the current interrupt status and recycled transmit buffer status from a network interface.

**Prototype**
```c
typedef EFI_STATUS
(EFI_API *EFI_SIMPLE_NETWORK_GET_STATUS) (
    IN EFI_SIMPLE_NETWORK_PROTOCOL *This,
    OUT UINT32 *InterruptStatus OPTIONAL,
    OUT VOID **TxBuf OPTIONAL
);
```

**Parameters**

**This**
A pointer to the `EFI_SIMPLE_NETWORK_PROTOCOL` instance.

**InterruptStatus**
A pointer to the bit mask of the currently active interrupts (see “Related Definitions”). If this is NULL, the interrupt status will not be read from the device. If this is not NULL, the interrupt status will be read from the device. When the interrupt status is read, it will also be cleared. Clearing the transmit interrupt does not empty the recycled transmit buffer array.

**TxBuf**
Recycled transmit buffer address. The network interface will not transmit if its internal recycled transmit buffer array is full. Reading the transmit buffer does not clear the transmit interrupt. If this is NULL, then the transmit buffer status will not be read. If there are no transmit buffers to recycle and `TxBuf` is not NULL, `*TxBuf` will be set to NULL.

**Related Definitions**

```c
//***********************************************************************
// Interrupt Bit Mask Settings for InterruptStatus.
```

(continues on next page)
Description

This function gets the current interrupt and recycled transmit buffer status from the network interface. The interrupt status is returned as a bit mask in `InterruptStatus`. If `InterruptStatus` is NULL, the interrupt status will not be read. Upon successful return of the media status, the `MediaPresent` field of `EFI_SIMPLE_NETWORK_MODE` will be updated to reflect any change of media status. Upon successful return of the media status, the `MediaPresent` field of `EFI_SIMPLE_NETWORK_MODE` will be updated to reflect any change of media status. If `TxBuf` is not NULL, a recycled transmit buffer address will be retrieved. If a recycled transmit buffer address is returned in `TxBuf`, then the buffer has been successfully transmitted, and the status for that buffer is cleared. If the status of the network interface is successfully collected, EFI_SUCCESS will be returned. If the driver has not been initialized, EFI_DEVICE_ERROR will be returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The status of the network interface was retrieved.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The network interface has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This parameter was NULL or did not point to a valid EFI_SIMPLE_NETWORK_PROTOCOL structure.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The command could not be sent to the network interface.</td>
</tr>
</tbody>
</table>

### 24.1.13 EFI_SIMPLE_NETWORK.Transmit()

**Summary**

Places a packet in the transmit queue of a network interface.

**Prototype**

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_SIMPLE_NETWORK_TRANSMIT) (  
    IN EFI_SIMPLE_NETWORK_PROTOCOL *This,
    IN UINTN HeaderSize,  
    IN UINTN BufferSize,  
    IN VOID *Buffer,  
    IN EFI_MAC_ADDRESS *SrcAddr OPTIONAL,  
    IN EFI_MAC_ADDRESS *DestAddr OPTIONAL,  
    IN UINT16 *Protocol OPTIONAL,  
) ;
```

**Parameters**

**This**

A pointer to the ` EFI_SIMPLE_NETWORK_PROTOCOL ` instance.

**HeaderSize**

The size, in bytes, of the media header to be filled in by the Transmit() function. If `HeaderSize` is nonzero,
then it must be equal to This->Mode->MediaHeaderSize and the DestAddr and Protocol parameters must not be NULL.

**Buffersize**
The size, in bytes, of the entire packet (media header and data) to be transmitted through the network interface.

**Buffer**
A pointer to the packet (media header followed by data) to be transmitted. This parameter cannot be NULL. If HeaderSize is zero, then the media header in Buffer must already be filled in by the caller. If HeaderSize is nonzero, then the media header will be filled in by the Transmit() function.

**SrcAddr**
The source HW MAC address. If HeaderSize is zero, then this parameter is ignored. If HeaderSize is nonzero and SrcAddr is NULL, then This->Mode->CurrentAddress is used for the source HW MAC address.

**DestAddr**
The destination HW MAC address. If HeaderSize is zero, then this parameter is ignored.

**Protocol**
The type of header to build. If HeaderSize is zero, then this parameter is ignored. See RFC 3232, section “Ether Types,” for examples.

**Description**
This function places the packet specified by Header and Buffer on the transmit queue. If HeaderSize is nonzero and HeaderSize is not equal to This->Mode->MediaHeaderSize, then EFI_INVALID_PARAMETER will be returned. If BufferSize is less than This->Mode->MediaHeaderSize, then EFI_BUFFER_TOO_SMALL will be returned. If Buffer is NULL, then EFI_INVALID_PARAMETER will be returned. If HeaderSize is nonzero and DestAddr or Protocol is NULL, then EFI_INVALID_PARAMETER will be returned. If the transmit engine of the network interface is busy, then EFI_NOT_READY will be returned. If this packet can be accepted by the transmit engine of the network interface, the packet contents specified by Buffer will be placed on the transmit queue of the network interface, and EFI_SUCCESS will be returned. EFI_SIMPLE_NETWORK.GetStatus() can be used to determine when the packet has actually been transmitted. The contents of the Buffer must not be modified until the packet has actually been transmitted.

The Transmit() function performs nonblocking I/O. A caller who wants to perform blocking I/O, should call Transmit(), and then GetStatus() until the transmitted buffer shows up in the recycled transmit buffer.

If the driver has not been initialized, EFI_DEVICE_ERROR will be returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The packet was placed on the transmit queue.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The network interface has not been started.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The network interface is too busy to accept this transmit request.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The BufferSize parameter is too small.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the parameters has an unsupported value.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The command could not be sent to the network interface.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This function is not supported by the network interface.</td>
</tr>
</tbody>
</table>
24.1.14 EFI_SIMPLE_NETWORK.Receive()

Summary
Receives a packet from a network interface.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_SIMPLE_NETWORK_RECEIVE) (  
    IN EFI_SIMPLE_NETWORK_PROTOCOL *This,  
    OUT UINTN *HeaderSize OPTIONAL,  
    IN OUT UINTN *BufferSize,  
    OUT VOID *Buffer,  
    OUT EFI_MAC_ADDRESS *SrcAddr OPTIONAL,  
    OUT EFI_MAC_ADDRESS *DestAddr OPTIONAL,  
    OUT UINT16 *Protocol OPTIONAL  
);  
```

Parameters

**This**
A pointer to the `EFI_SIMPLE_NETWORK_PROTOCOL` instance.

**HeaderSize**
The size, in bytes, of the media header received on the network interface. If this parameter is NULL, then the media header size will not be returned.

**BufferSize**
On entry, the size, in bytes, of `Buffer`. On exit, the size, in bytes, of the packet that was received on the network interface.

**Buffer**
A pointer to the data buffer to receive both the media header and the data.

**SrcAddr**
The source HW MAC address. If this parameter is NULL, the HW MAC source address will not be extracted from the media header.

**DestAddr**
The destination HW MAC address. If this parameter is NULL, the HW MAC destination address will not be extracted from the media header.

**Protocol**
The media header type. If this parameter is NULL, then the protocol will not be extracted from the media header. See RFC 1700 section “Ether Types” for examples.

Description
This function retrieves one packet from the receive queue of a network interface. If there are no packets on the receive queue, then EFI_NOT_READY will be returned. If there is a packet on the receive queue, and the size of the packet is smaller than `BufferSize`, then the contents of the packet will be placed in `Buffer`, and `BufferSize` will be updated with the actual size of the packet. In addition, if `SrcAddr`, `DestAddr`, and `Protocol` are not NULL, then these values will be extracted from the media header and returned. EFI_SUCCESS will be returned if a packet was successfully received. If `BufferSize` is smaller than the received packet, then the size of the receive packet will be placed in `BufferSize` and EFI_BUFFER_TOO_SMALL will be returned. If the driver has not been initialized, EFI_DEVICE_ERROR will be returned.

Status Codes Returned
<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The received data was stored in Buffer, and BufferSize has been updated to</td>
</tr>
<tr>
<td></td>
<td>the number of bytes received.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The network interface has not been started.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>No packets have been received on the network interface.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>BufferSize is too small for the received packets. BufferSize has been</td>
</tr>
<tr>
<td></td>
<td>updated to the required size.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• The This parameter is NULL</td>
</tr>
<tr>
<td></td>
<td>• The This parameter does not point to a valid EFI_SIMPLE_NETWORK_PROTOCOL</td>
</tr>
<tr>
<td></td>
<td>structure.</td>
</tr>
<tr>
<td></td>
<td>• The BufferSize parameter is NULL</td>
</tr>
<tr>
<td></td>
<td>• The Buffer parameter is NULL</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The command could not be sent to the network interface.</td>
</tr>
</tbody>
</table>

### 24.2 Network Interface Identifier Protocol

This is an optional protocol that is used to describe details about the software layer that is used to produce the Simple Network Protocol. This protocol is only required if the underlying network interface is 16-bit UNDI, 32/64-bit S/W UNDI, or H/W UNDI. It is used to obtain type and revision information about the underlying network interface.

An instance of the Network Interface Identifier protocol must be created for each physical external network interface that is controlled by the !PXE structure. The !PXE structure is defined in the 32/64-bit UNDI Specification in Appendix E.

#### 24.2.1 EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL

**Summary**

An optional protocol that is used to describe details about the software layer that is used to produce the Simple Network Protocol.

**GUID**

```c
#define EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL_GUID_31 \
{0x1ACED566, 0x76ED, 0x4218, \ 
 {0xBC, 0x81, 0x76, 0x7F, 0x1F, 0x97, 0x7A, 0x89}}
```

**Revision Number**

```c
#define EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL_REVISION \ 0x00002000
```

**Protocol Interface Structure**

```c
typedef struct {
    UINT64   Revision;
    UINT64   Id;
    UINT64   ImageAddr;
    UINT32   ImageSize;
    CHAR8    StringId[4];
} vücud網絡介面識別協定控制子 palabras;```

(continues on next page)
UINT8 Type;
UINT8 MajorVer;
UINT8 MinorVer;
BOOLEAN Ipv6Supported;
UINT16 IfNum;
} EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL;

Parameters

Revision
The revision of the EFI_NETWORK_INTERFACE_IDENTIFIER protocol.

Id
Address of the first byte of the identifying structure for this network interface. This is only valid when the network interface is started (see EFI_SIMPLE_NETWORK.Start()). When the network interface is not started, this field is set to zero.

16-bit UNDI and 32/64-bit S/W UNDI:
Id contains the address of the first byte of the copy of the !PXE structure in the relocated UNDI code segment. See the Preboot Execution Environment (PXE) Specification and Appendix E.

H/W UNDI:
Id contains the address of the !PXE structure.

ImageAddr
Address of the unrelocated network interface image.

16-bit UNDI:
ImageAddr is the address of the PXE option ROM image in upper memory.

32/64-bit S/W UNDI:
ImageAddr is the address of the unrelocated S/W UNDI image.

H/W UNDI:
ImageAddr contains zero.

ImageSize
Size of unrelocated network interface image.

16-bit UNDI:
ImageSize is the size of the PXE option ROM image in upper memory.

32/64-bit S/W UNDI:
ImageSize is the size of the unrelocated S/W UNDI image.

H/W UNDI:
ImageSize contains zero.

StringId
A four-character ASCII string that is sent in the class identifier field of option 60 in DHCP. For a Type of EfiNetworkInterfaceUndi, this field is “UNDI.”

Type
Network interface type. This will be set to one of the values in EFI_NETWORK_INTERFACE_TYPE (see “Related Definitions” below).
MajorVer
Major version number.

16-bit UNDI:

MajorVer comes from the third byte of the UNDIRev field in the UNDI ROM ID structure. Refer to the Preboot Execution Environment (PXE) Specification.

32/64-bit S/W UNDI and H/W UNDI:

MajorVer comes from the Major field in the !PXE structure. See Appendix E.

MinorVer
Minor version number.

16-bit UNDI:

MinorVer comes from the second byte of the UNDIRev field in the UNDI ROM ID structure. Refer to the Preboot Execution Environment (PXE) Specification.

32/64-bit S/W UNDI and H/W UNDI:

MinorVer comes from the Minor field in the !PXE structure. See Appendix E.

Ipv6Supported
TRUE if the network interface supports IPv6; otherwise FALSE.

IfNum
The network interface number that is being identified by this Network Interface Identifier Protocol. This field must be less than or equal to the (IFcnt | IFcntExt <<8 ) field in the !PXE structure.

Related Definitions

```c
typedef enum {
    EfiNetworkInterfaceUndi = 1
} EFI_NETWORK_INTERFACE_TYPE;
```

Description
The EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL is used by EFI_PXE_BASE_CODE_PROTOCOL and OS loaders to identify the type of the underlying network interface and to locate its initial entry point.

24.3 PXE Base Code Protocol

This section defines the Preboot Execution Environment (PXE) Base Code protocol, which is used to access PXE-compatible devices for network access and network booting. For more information about PXE, see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Preboot Execution Environment (PXE) Specification”.

24.3. PXE Base Code Protocol 940
24.3.1 EFI_PXE_BASE_CODE_PROTOCOL

Summary
The EFI_PXE_BASE_CODE_PROTOCOL is used to control PXE-compatible devices. The features of these devices are defined in the Preboot Execution Environment (PXE) Specification. An EFI_PXE_BASE_CODE_PROTOCOL will be layered on top of an EFI_MANAGED_NETWORK_PROTOCOL protocol in order to perform packet level transactions. The EFI_PXE_BASE_CODE_PROTOCOL handle also supports the See EFI_LOAD_FILE_PROTOCOL protocol. This provides a clean way to obtain control from the boot manager if the boot path is from the remote device.

GUID

```c
#define EFI_PXE_BASE_CODE_PROTOCOL_GUID \ 
  {0x03C4E603,0xAC28,0x11d3,\ 
   {0x9A,0x2D,0x00,0x90,0x27,0x3F,0xC1,0x4D}}
```

Revision Number

```c
#define EFI_PXE_BASE_CODE_PROTOCOL_REVISION 0x00010000
```

Protocol Interface Structure

```c
typedef struct {
  UINT64 Revision;
  EFI_PXE_BASE_CODE_START Start;
  EFI_PXE_BASE_CODE_STOP Stop;
  EFI_PXE_BASE_CODE_DHCP Dhcp;
  EFI_PXE_BASE_CODE_DISCOVER Discover;
  EFI_PXE_BASE_CODE_MTFTP Mtftp;
  EFI_PXE_BASE_CODE_UDP_WRITE UdpWrite;
  EFI_PXE_BASE_CODE_UDP_READ UdpRead;
  EFI_PXE_BASE_CODE_SET_IP_FILTER SetIpFilter;
  EFI_PXE_BASE_CODE_ARP Arp;
  EFI_PXE_BASE_CODE_SET_PARAMETERS SetParameters;
  EFI_PXE_BASE_CODE_SET_STATION_IP SetStationIp;
  EFI_PXE_BASE_CODE_SET_PACKETS SetPackets;
  EFI_PXE_BASE_CODE_MODE *Mode;
} EFI_PXE_BASE_CODE_PROTOCOL;
```

Parameters

Revision
The revision of the EFI_PXE_BASE_CODE_PROTOCOL. All future revisions must be backwards compatible. If a future version is not backwards compatible it is not the same GUID.

Start
Starts the PXE Base Code Protocol. Mode structure information is not valid and no other Base Code Protocol functions will operate until the Base Code is started. See the EFI_PXE_BASE_CODE_PROTOCOL.Start() function description.

Stop
Stops the PXE Base Code Protocol. Mode structure information is unchanged by this function. No Base Code Protocol functions will operate until the Base Code is restarted. See the EFI_PXE_BASE_CODE_PROTOCOL.Stop() function description.

Dhcp
Attempts to complete a DHCPv4 D.O.R.A. (discover / offer / request / acknowledge) or DHCPv6 S.A.R.R (solicit
/ advertise / request / reply) sequence. See the *EFI_PXE_BASE_CODE_PROTOCOL.Dhcp()* function description.

**Discover**
Attempts to complete the PXE Boot Server and/or boot image discovery sequence. See the *EFI_PXE_BASE_CODE_PROTOCOL.Discover()* function description.

**Mtftp**
Performs TFTP and MTFTP services. See the *EFI_PXE_BASE_CODE_PROTOCOL.Mtftp()* function description.

**UdpWrite**
Writes a UDP packet to the network interface. See the *EFI_PXE_BASE_CODE_PROTOCOL.UdpWrite()* function description.

**UdpRead**
Reads a UDP packet from the network interface. See the *EFI_PXE_BASE_CODE_PROTOCOL.UdpRead()* function description.

**SetIpFilter**
Updates the IP receive filters of the network device. See the *EFI_PXE_BASE_CODE_PROTOCOL.SetIpFilter()* function description.

**Arp**
Uses the ARP protocol to resolve a MAC address. See the *EFI_PXE_BASE_CODE_PROTOCOL.Arp()* function description.

**SetParameters**
Updates the parameters that affect the operation of the PXE Base Code Protocol. See the *EFI_PXE_BASE_CODE_PROTOCOL.SetParameters()* function description.

**SetStationIp**
Updates the station IP address and subnet mask values. See the *EFI_PXE_BASE_CODE_PROTOCOL.SetStationIp()* function description.

**SetPackets**
Updates the contents of the cached DHCP and Discover packets. See the *EFI_PXE_BASE_CODE_PROTOCOL.SetPackets()* function description.

**Mode**
Pointer to the *EFI_PXE_BASE_CODE_MODE* for this device. The *EFI_PXE_BASE_CODE_MODE* structure is defined in “Related Definitions” below.

**Related Definitions**

```c
//Maximum ARP and Route Entries
#define EFI_PXE_BASE_CODE_MAX_ARP_ENTRIES 8
#define EFI_PXE_BASE_CODE_MAX_ROUTE_ENTRIES 8

// EFI_PXE_BASE_CODE_MODE
// The data values in this structure are read-only and are updated by the code that produces the
// EFI_PXE_BASE_CODE_PROTOCOL functions.
typedef struct {
```

(continues on next page)
### 24.3. PXE Base Code Protocol

| BOOLEAN    | Started;                     |
| BOOLEAN    | Ipv6Available;               |
| BOOLEAN    | Ipv6Supported;               |
| BOOLEAN    | UsingIpv6;                   |
| BOOLEAN    | BisSupported;                |
| BOOLEAN    | BisDetected;                 |
| BOOLEAN    | AutoArp;                     |
| BOOLEAN    | SendGUID;                    |
| BOOLEAN    | DhcpDiscoverValid;           |
| BOOLEAN    | DhcpAckReceived;             |
| BOOLEAN    | ProxyOfferReceived;          |
| BOOLEAN    | PxeDiscoverValid;            |
| BOOLEAN    | PxeReplyReceived;            |
| BOOLEAN    | PxeBisReplyReceived;         |
| BOOLEAN    | IcmpErrorReceived;           |
| BOOLEAN    | TftpErrorReceived;           |
| BOOLEAN    | MakeCallbacks;               |
| UINT8      | TTL;                         |
| UINT8      | ToS;                         |
| EFI_IP_ADDRESS | StationIp;               |
| EFI_IP_ADDRESS | SubnetMask;                |
| EFI_PXE_BASE_CODE_PACKET | DhcpDiscover; |
| EFI_PXE_BASE_CODE_PACKET | DhcpAck;                |
| EFI_PXE_BASE_CODE_PACKET | ProxyOffer;               |
| EFI_PXE_BASE_CODE_PACKET | PxeDiscover;              |
| EFI_PXE_BASE_CODE_PACKET | PxeReply;                 |
| EFI_PXE_BASE_CODE_PACKET | PxeBisReply;              |
| EFI_PXE_BASE_CODE_IP_FILTER  | IpFilter;                |
| UINT32     | ArpCacheEntries;            |
| EFI_PXE_BASE_CODE_ARP_ENTRY  | ArpCache[EFI_PXE_BASE_CODE_MAX_ARP_ENTRIES]; |
| UINT32     | RouteTableEntries;          |
| EFI_PXE_BASE_CODE_ROUTE_ENTRY  | RouteTable[EFI_PXE_BASE_CODE_MAX_ROUTE_ENTRIES]; |
| EFI_PXE_BASE_CODE_ICMP_ERROR  | IcmpError;               |
| EFI_PXE_BASE_CODE_TFTP_ERROR  | TftpError;               |

**Started**

TRUE if this device has been started by calling `EFI_PXE_BASE_CODE_PROTOCOL.Start()` . This field is set to TRUE by the Start() function and to FALSE by the `EFI_PXE_BASE_CODE_PROTOCOL.Stop()` function.

**Ipv6Available**

TRUE if the UNDI protocol supports IPv6.

**Ipv6Supported**

TRUE if this PXE Base Code Protocol implementation supports IPv6.

**UsingIpv6**

TRUE if this device is currently using IPv6. This field is set by the Start() function.

**BisSupported**

TRUE if this PXE Base Code implementation supports Boot Integrity Services (BIS). This field is set by the Start() function.

**BisDetected**

TRUE if this device and the platform support Boot Integrity Services (BIS). This field is set by the Start() function.
function.

**AutoArp**

TRUE for automatic ARP packet generation; FALSE otherwise. This field is initialized to TRUE by Start() and can be modified with the \texttt{EFI_PXE_BASE_CODE_PROTOCOL.SetParameters()} function.

**SendGUID**

This field is used to change the Client Hardware Address (chaddr) field in the DHCP and Discovery packets. Set to TRUE to send the SystemGuid (if one is available). Set to FALSE to send the client NIC MAC address. This field is initialized to FALSE by Start() and can be modified with the SetParameters() function.

**DhcpDiscoverValid**

This field is initialized to FALSE by the Start() function and set to TRUE when the \texttt{EFI_PXE_BASE_CODE_PROTOCOL.Dhcp()} function completes successfully. When TRUE, the DhcpDiscover field is valid. This field can also be changed by the \texttt{EFI_PXE_BASE_CODE_PROTOCOL.SetPackets()} function.

**DhcpAckReceived**

This field is initialized to FALSE by the Start() function and set to TRUE when the Dhcp() function completes successfully and a proxy DHCP offer packet was received. When TRUE, the ProxyOffer packet field is valid. This field can also be changed by the SetPackets() function.

**ProxyOfferReceived**

This field is initialized to FALSE by the Start() function and set to TRUE when the Dhcp() function completes successfully and a proxy DHCP offer packet was received. When TRUE, the ProxyOffer packet field is valid. This field can also be changed by the SetPackets() function.

**PxeDiscoverValid**

When TRUE, the PxeDiscover packet field is valid. This field is set to FALSE by the Start() and Dhcp() functions, and can be set to TRUE or FALSE by the \texttt{EFI_PXE_BASE_CODE_PROTOCOL.Discover()} and \texttt{SetPackets()} functions.

**PxeReplyReceived**

When TRUE, the PxeReply packet field is valid. This field is set to FALSE by the Start() and Dhcp() functions, and can be set to TRUE or FALSE by the Discover() and SetPackets() functions.

**PxeBisReplyReceived**

When TRUE, the PxeBisReply packet field is valid. This field is set to FALSE by the Start() and Dhcp() functions, and can be set to TRUE or FALSE by the Discover() and SetPackets() functions.

**IcmpErrorReceived**

Indicates whether the IcmpError field has been updated. This field is reset to FALSE by the Start(), Dhcp(), Discover(), \texttt{EFI_PXE_BASE_CODE_PROTOCOL.Mtftp()}, \texttt{EFI_PXE_BASE_CODE_PROTOCOL.UdpRead()}, \texttt{EFI_PXE_BASE_CODE_PROTOCOL.UdpWrite()} and \texttt{EFI_PXE_BASE_CODE_PROTOCOL.Arp()} functions. If an ICMP error is received, this field will be set to TRUE after the IcmpError field is updated.

**TftpErrorReceived**

Indicates whether the TftpError field has been updated. This field is reset to FALSE by the Start() and Mtftp() functions. If a TFTP error is received, this field will be set to TRUE after the TftpError field is updated.

**MakeCallbacks**

When FALSE, callbacks will not be made. When TRUE, make callbacks to the PXE Base Code Callback Protocol. This field is reset to FALSE by the Start() function if the PXE Base Code Callback Protocol is not available. It is reset to TRUE by the Start() function if the PXE Base Code Callback Protocol is available.

**TTL**

The “time to live” field of the IP header. This field is initialized to DEFAULT_TTL (See “Related Definitions”) by the Start() function and can be modified by the \texttt{EFI_PXE_BASE_CODE_PROTOCOL.SetParameters()} function.
ToS
The type of service field of the IP header. This field is initialized to DEFAULT_ToS (See “Related Definitions”) by \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.Start()}, and can be modified with the \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.SetParameters()} function.

StationIp
The device’s current IP address. This field is initialized to a zero address by \texttt{Start()}. This field is set when the \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.Dhcp()} function completes successfully. This field can also be set by the \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.SetStationIp()} function. This field must be set to a valid IP address by either Dhcp() or SetStationIp() before the \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.Discover()}, \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.Mtftp()}, \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.UdpRead()}, \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.UdpWrite()} and \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.Arp()} functions are called.

SubnetMask
The device’s current subnet mask. This field is initialized to a zero address by the \texttt{Start()} function. This field is set when the \texttt{Dhcp()} function completes successfully. This field can also be set by the \texttt{SetStationIp()} function. This field must be set to a valid subnet mask by either Dhcp() or SetStationIp() before the Discover(), Mtftp(), UdpRead(), UdpWrite(), or Arp() functions are called.

DhcpDiscover
Cached DHCP Discover packet. This field is zero-filled by the \texttt{Start()} function, and is set when the \texttt{Dhcp()} function completes successfully. The contents of this field can replaced by the \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.SetPackets()} function.

DhcpAck
Cached DHCP Ack packet. This field is zero-filled by the \texttt{Start()} function, and is set when the Dhcp() function completes successfully. The contents of this field can be replaced by the \texttt{SetPackets()} function.

ProxyOffer
Cached Proxy Offer packet. This field is zero-filled by the \texttt{Start()} function, and is set when the Dhcp() function completes successfully. The contents of this field can be replaced by the \texttt{SetPackets()} function.

PxeDiscover
Cached PXE Discover packet. This field is zero-filled by the \texttt{Start()} function, and is set when the Discover() function completes successfully. The contents of this field can be replaced by the \texttt{SetPackets()} function.

PxeReply
Cached PXE Reply packet. This field is zero-filled by the \texttt{Start()} function, and is set when the Discover() function completes successfully. The contents of this field can be replaced by the \texttt{SetPackets()} function.

PxeBisReply
Cached PXE BIS Reply packet. This field is zero-filled by the \texttt{Start()} function, and is set when the Discover() function completes successfully. This field can be replaced by the \texttt{SetPackets()} function.

IpFilter
The current IP receive filter settings. The receive filter is disabled and the number of IP receive filters is set to zero by the \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.Start()} function, and is set by the \texttt{EFI\_PXE\_BASE\_CODE\_PROTOCOL.SetIpFilter()} function.

ArpCacheEntries
The number of valid entries in the ARP cache. This field is reset to zero by the \texttt{Start()} function.

ArpCache
Array of cached ARP entries.

RouteTableEntries
The number of valid entries in the current route table. This field is reset to zero by the \texttt{Start()} function.
RouteTable
Array of route table entries.

IcmpError
ICMP error packet. This field is updated when an ICMP error is received and is undefined until the first ICMP error is received. This field is zero-filled by the Start() function.

TftpError
TFTP error packet. This field is updated when a TFTP error is received and is undefined until the first TFTP error is received. This field is zero-filled by the Start() function.

24.3.2 DHCP Packet Data Types
This section defines the data types for DHCP packets, ICMP error packets, and TFTP error packets. All of these are byte-packed data structures.

NOTE: All the multibyte fields in these structures are stored in network order.
typedef struct {
    UINT32 MessageType:8;
    UINT32 TransactionId:24;
    UINT8 DhcpOptions[1024];
} EFI_PXE_BASE_CODE_DHCPV6_PACKET;

typedef union {
    UINT8 Raw[1472];
    EFI_PXE_BASE_CODE_DHCPV4_PACKET Dhcpv4;
    EFI_PXE_BASE_CODE_DHCPV6_PACKET Dhcpv6;
} EFI_PXE_BASE_CODE_PACKET;

typedef struct {
    UINT8 Type;
    UINT8 Code;
    UINT16 Checksum;
    union {
        UINT32 reserved;
        UINT32 Mtu;
        struct {
            UINT16 Identifier;
            UINT16 Sequence;
        } Echo;
    } u;
} EFI_PXE_BASE_CODE_ICMP_ERROR;

(continues on next page)
24.3.3 IP Receive Filter Settings

This section defines the data types for IP receive filter settings.

```c
#define EFI_PXE_BASE_CODE_MAX_IPCNT8

//******************************************************************************
// EFI_PXE_BASE_CODE_IP_FILTER
//******************************************************************************
typedef struct {
    UINT8 Filters;
    UINT8 IpCnt;
    UINT16 reserved;
    EFI_IP_ADDRESS IpList[EFI_PXE_BASE_CODE_MAX_IPCNT8];
} EFI_PXE_BASE_CODE_IP_FILTER;

#define EFI_PXE_BASE_CODE_IP_FILTER_STATION_IP 0x0001
#define EFI_PXE_BASE_CODE_IP_FILTER_BROADCAST 0x0002
#define EFI_PXE_BASE_CODE_IP_FILTER_PROMISCUOUS 0x0004
#define EFI_PXE_BASE_CODE_IP_FILTER_PROMISCUOUS_MULTICAST 0x0008
```

24.3.4 ARP Cache Entries

This section defines the data types for ARP cache entries, and route table entries.

```c
//******************************************************************************
// EFI_PXE_BASE_CODE_ARP_ENTRY
//******************************************************************************
typedef struct {
    EFI_IP_ADDRESS IpAddr;
    EFI_MAC_ADDRESS MacAddr;
} EFI_PXE_BASE_CODE_ARP_ENTRY;

//******************************************************************************
// EFI_PXE_BASE_CODE_ROUTE_ENTRY
//******************************************************************************
typedef struct {
    EFI_IP_ADDRESS IpAddr;
    EFI_IP_ADDRESS SubnetMask;
}
```
24.3.5 Filter Operations for UDP Read/Write Functions

This section defines the types of filter operations that can be used with the EFI_PXE_BASE_CODE_PROTOCOL.UdpRead() and EFI_PXE_BASE_CODE_PROTOCOL.UdpWrite() functions.

```c
#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_ANY_SRC_IP 0x0001
#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_ANY_SRC_PORT 0x0002
#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_ANY_DEST_IP 0x0004
#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_ANY_DEST_PORT 0x0008
#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_USE_FILTER 0x0010
#define EFI_PXE_BASE_CODE_UDP_OPFLAGS_MAY_FRAGMENT 0x0020
#define DEFAULT_TTL 16
#define DEFAULT_ToS 0
```

The following table defines values for the PXE DHCP and Bootserver Discover packet tags that are specific to the UEFI environment. Complete definitions of all PXE tags are defined in the Table below, “PXE DHCP Options (Full List),” in the PXE Specification.
Table 24.13: PXE Tag Definitions for EFI

<table>
<thead>
<tr>
<th>Tag Name</th>
<th>Tag #</th>
<th>Length</th>
<th>Data Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>Client Network Interface Identifier</td>
<td>94 [0x5E]</td>
<td>3 [0x03]</td>
<td>Type (1), MajorVer (1), MinorVer (1) Type is a one byte field that identifies the network interface that will be used by the downloaded program. Type is followed by two one byte version number fields, MajorVer and MinorVer. Type UNDI (1) = 0x01 Versions 16-bit UNDI: MajorVer = 0x02. MinorVer = 0x00 PXE-2.0 16-bit UNDI: MajorVer = 0x02, MinorVer = 0x01 32/64-bit UNDI &amp; H/W UNDI: MajorVer = 0x03, MinorVer = 0x00</td>
</tr>
<tr>
<td>Client System Architecture</td>
<td>93 [0x5D]</td>
<td>2 [0x02]</td>
<td>Type (2) Type is a two byte, network order, field that identifies the processor and programming environment of the client system. For the various architecture type encodings, see the table “Processor Architecture Types” at “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “Processor Architecture Types”</td>
</tr>
<tr>
<td>Class Identifier</td>
<td>60 [0x3C]</td>
<td>32 [0x20]</td>
<td>“PXE Client:Arch:xxx xx:UNDI:yyyzzz” “PXEClient:…” is used to identify communication between PXE clients and servers. Information from tags 93 &amp; 94 is embedded in the Class Identifier string. (The strings defined in this tag are case sensitive and must not be NULL-terminated.) xxxxx = ASCII representation of Client System Architecture. yyyzzz = ASCII representation of Client Network Interface Identifier version numbers MajorVer(yyy) and MinorVer(zzz). <strong>Example</strong> “PXE Client:Arch:00 002:UNDI:00300” identifies an IA64 PC w/ 32/64-bit UNDI</td>
</tr>
</tbody>
</table>

**Description**

The basic mechanisms and flow for remote booting in UEFI are identical to the remote boot functionality described in detail in the PXE Specification. However, the actual execution environment, linkage, and calling conventions are replaced and enhanced for the UEFI environment.

The DHCP Option for the Client System Architecture is used to inform the DHCP server if the client is a UEFI environment in supported systems. The server may use this information to provide default images if it does not have a specific boot profile for the client.

The DHCP Option for Client Network Interface Identifier is used to inform the DHCP server of the client underlying network interface information. If the NII protocol is present, such information will be acquired by this protocol. Otherwise, Type = 0x01, MajorVer=0x03, MinorVer=0x00 will be the default value.

A handle that supports `EFI_PXE_BASE_CODE_PROTOCOL` is required to support `EFI_LOAD_FILE_PROTOCOL`. The `EFI_LOAD_FILE_PROTOCOL` function is used by the firmware to load files from devices that do not support file
system type accesses. Specifically, the firmware’s boot manager invokes LoadFile() with `BootPolicy` being `TRUE` when attempting to boot from the device. The firmware then loads and transfers control to the downloaded PXE boot image. Once the remote image is successfully loaded, it may utilize the `EFI_PXE_BASE_CODE_PROTOCOL` interfaces, or even the `EFI_SIMPLE_NETWORK_PROTOCOL` interfaces, to continue the remote process.

### 24.3.6 `EFI_PXE_BASE_CODE_PROTOCOL.Start()`

#### Summary

Enables the use of the PXE Base Code Protocol functions.

#### Prototype

```c
typedef EFI_STATUS
  (EFIAPI *EFI_PXE_BASE_CODE_START) (
    IN EFI_PXE_BASE_CODE_PROTOCOL *This,
    IN BOOLEAN UseIpv6
  );
```

#### Parameters

**This**

Pointer to the `EFI_PXE_BASE_CODE_PROTOCOL` instance.

**UseIpv6**

Specifies the type of IP addresses that are to be used during the session that is being started. Set to `TRUE` for IPv6 addresses, and `FALSE` for IPv4 addresses.

#### Description

This function enables the use of the PXE Base Code Protocol functions. If the `Started` field of the `EFI_PXE_BASE_CODE_MODE` structure is already `TRUE`, then `EFI_ALREADY_STARTED` will be returned. If `UseIpv6` is `TRUE`, then IPv6 formatted addresses will be used in this session. If `UseIpv6` is `FALSE`, then IPv4 formatted addresses will be used in this session. If `UseIpv6` is `TRUE`, and the `Ipv6Supported` field of the `EFI_PXE_BASE_CODE_MODE` structure is `FALSE`, then `EFI_UNSUPPORTED` will be returned. If there is not enough memory or other resources to start the PXE Base Code Protocol, then `EFI_OUT_OF_RESOURCES` will be returned. Otherwise, the PXE Base Code Protocol will be started, and all of the fields of the `EFI_PXE_BASE_CODE_MODE` structure will be initialized as follows:

<table>
<thead>
<tr>
<th>Field</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>Started</code></td>
<td>Set to <code>TRUE</code>.</td>
</tr>
<tr>
<td><code>Ipv6Supported</code></td>
<td>Unchanged.</td>
</tr>
<tr>
<td><code>Ipv6Available</code></td>
<td>Unchanged.</td>
</tr>
<tr>
<td><code>UsingIpv6</code></td>
<td>Set to <code>*UseIpv6*</code>.</td>
</tr>
<tr>
<td><code>BisSupported</code></td>
<td>Unchanged.</td>
</tr>
<tr>
<td><code>BisDetected</code></td>
<td>Unchanged.</td>
</tr>
<tr>
<td><code>AutoArp</code></td>
<td>Set to <code>TRUE</code>.</td>
</tr>
<tr>
<td><code>SendGUID</code></td>
<td>Set to <code>FALSE</code>.</td>
</tr>
<tr>
<td><code>TTL</code></td>
<td>Set to <code>DEFAULT_TTL</code></td>
</tr>
<tr>
<td><code>ToS</code></td>
<td>Set to <code>DEFAULT_ToS</code></td>
</tr>
<tr>
<td><code>DhcpCompleted</code></td>
<td>Set to <code>FALSE</code>.</td>
</tr>
<tr>
<td><code>ProxyOfferReceived</code></td>
<td>Set to <code>FALSE</code>.</td>
</tr>
<tr>
<td><code>StationIp</code></td>
<td>Set to an address of all zeros.</td>
</tr>
<tr>
<td><code>SubnetMask</code></td>
<td>Set to a subnet mask of all zeros.</td>
</tr>
<tr>
<td><code>DhcpDiscover</code></td>
<td>Zero-filled.</td>
</tr>
<tr>
<td><code>DhcpAck</code></td>
<td>Zero-filled.</td>
</tr>
</tbody>
</table>

(continues on next page)
ProxyOffer: Zero-filled.
PxeDiscoverValid: Set to FALSE.
PxeDiscover: Zero-filled.
PxeReplyValid: Set to FALSE.
PxeReply: Zero-filled.
PxeBisReplyValid: Set to FALSE.
PxeBisReply: Zero-filled.
IpFilter: Set the *Filters* field to 0 and the *IpCnt* field to 0.
ArpCacheEntries: Set to 0.
ArpCache: Zero-filled.
RouteTableEntries: Set to 0.
RouteTable: Zero-filled.
IcmpErrorReceived: Set to FALSE.
IcmpError: Zero-filled.
TftpErrorReceived: Set to FALSE.
MakeCallback: Set to TRUE if the PXE Base Code Callback Protocol is available. Set to FALSE if the PXE Base Code Callback Protocol is not available.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The PXE Base Code Protocol was started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The This parameter is NULL or does not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Useipv6 is TRUE, but the IPv6Supported field of the EFI_PXE_BASE_CODE_MODE structure is FALSE.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The PXE Base Code Protocol is already in the started state.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The network device encountered an error during this operation.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate enough memory or other resources to start the PXE Base Code Protocol.</td>
</tr>
</tbody>
</table>

24.3.7 EFI_PXE_BASE_CODE_PROTOCOL.Stop()

Summary

Disables the use of the PXE Base Code Protocol functions.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_PXE_BASE_CODE_STOP) (IN EFI_PXE_BASE_CODE_PROTOCOL *This);

Parameters

This

Pointer to the EFI_PXE_BASE_CODE_PROTOCOL instance.

Description
This function stops all activity on the network device. All the resources allocated in `EFI_PXE_BASE_CODE_PROTOCOL.Start()` are released, the `Started` field of the `EFI_PXE_BASE_CODE_MODE` structure is set to `FALSE` and `EFI_SUCCESS` is returned. If the `Started` field of the `EFI_PXE_BASE_CODE_MODE` structure is already `FALSE`, then `EFI_NOT_STARTED` will be returned.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The PXE Base Code Protocol was stopped.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The PXE Base Code Protocol is already in the stopped state.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>This</code> parameter is <code>NULL</code> or does not point to a valid <code>EFI_PXE_BASE_CODE_PROTOCOL</code> structure.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The network device encountered an error during this operation.</td>
</tr>
</tbody>
</table>

### 24.3.8 EFI_PXE_BASE_CODE_PROTOCOL.Dhcp()

**Summary**

Attempts to complete a DHCPv4 D.O.R.A. (discover / offer / request / acknowledge) or DHCPv6 S.A.R.R (solicit / advertise / request / reply) sequence.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_PXE_BASE_CODE_DHCP) (  
    IN EFI_PXE_BASE_CODE_PROTOCOL *This,  
    IN BOOLEAN SortOffers  
);
```

**Parameters**

- **This**
  - Pointer to the `EFI_PXE_BASE_CODE_PROTOCOL` instance.

- **SortOffers**
  - `TRUE` if the offers received should be sorted. Set to `FALSE` to try the offers in the order that they are received.

**Description**

This function attempts to complete the DHCP sequence. If this sequence is completed, then `EFI_SUCCESS` is returned, and the `DhcpCompleted`, `ProxyOfferReceived`, `StationIp`, `SubnetMask`, `DhcpDiscover`, `DhcpAck`, and `ProxyOffer` fields of the `EFI_PXE_BASE_CODE_MODE` structure are filled in.

If `SortOffers` is `TRUE`, then the cached DHCP offer packets will be sorted before they are tried. If `SortOffers` is `FALSE`, then the cached DHCP offer packets will be tried in the order in which they are received. Please see the Preboot Execution Environment (PXE) Specification for additional details on the implementation of DHCP.

This function can take at least 31 seconds to timeout and return control to the caller. If the DHCP sequence does not complete, then `EFI_TIMEOUT` will be returned.

If the Callback Protocol does not return `EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE`, then the DHCP sequence will be stopped and `EFI_ABORTED` will be returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Valid DHCP has completed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The PXE Base Code Protocol is in the stopped state.</td>
</tr>
</tbody>
</table>

continues on next page
Table 24.16 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>This</code> parameter is <code>NULL</code> or does not point to a valid <code>EFI_PXE_BASE_CODE_PROTOCOL</code> structure.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The network device encountered an error during this operation.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate enough memory to complete the DHCP Protocol.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>The callback function aborted the DHCP Protocol.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The DHCP Protocol timed out.</td>
</tr>
<tr>
<td>EFI_ICMP_ERROR</td>
<td>An ICMP error packet was received during the DHCP session. The ICMP error packet has been cached in the <code>EFI_PXE_BASE_CODE_MODE.IcmpError</code> packet structure. Information about ICMP packet contents can be found in RFC 792.</td>
</tr>
<tr>
<td>EFI_NO_RESPONSE</td>
<td>Valid PXE offer was not received.</td>
</tr>
</tbody>
</table>

24.3.9 EFI_PXE_BASE_CODE_PROTOCOL.Discover()

Summary
Attempts to complete the PXE Boot Server and/or boot image discovery sequence.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_PXE_BASE_CODE_DISCOVER) (  
    IN EFI_PXE_BASE_CODE_PROTOCOL *This,  
    IN UINT16 Type,  
    IN UINT16 *Layer,  
    IN BOOLEAN UseBis,  
    IN EFI_PXE_BASE_CODE_DISCOVER_INFO *Info OPTIONAL  
);```

Parameters

This
Pointer to the `EFI_PXE_BASE_CODE_PROTOCOL` instance.

Type
The type of bootstrap to perform. See “Related Definitions” below.

Layer
Pointer to the boot server layer number to discover, which must be `PXE_BOOT_LAYER_INITIAL` when a new server type is being discovered. This is the only layer type that will perform multicast and broadcast discovery. All other layer types will only perform unicast discovery. If the boot server changes `Layer`, then the new `Layer` will be returned.

UseBis
TRUE if Boot Integrity Services are to be used. FALSE otherwise.

Info
Pointer to a data structure that contains additional information on the type of discovery operation that is to be performed. If this field is NULL, then the contents of the cached `DhcpAck` and `ProxyOffer` packets will be used.

Related Definitions

```c
//********************************************************************
// Bootstrap Types
```

(continues on next page)
//*******************************************************
#define EFI_PXE_BASE_CODE_BOOT_TYPE_BOOTSTRAP 0
#define EFI_PXE_BASE_CODE_BOOT_TYPE_MS_WINNT_RIS 1
#define EFI_PXE_BASE_CODE_BOOT_TYPE_INTEL_LCM 2
#define EFI_PXE_BASE_CODE_BOOT_TYPE_DOSUNDI 3
#define EFI_PXE_BASE_CODE_BOOT_TYPE_NEC_ESMPRO 4
#define EFI_PXE_BASE_CODE_BOOT_TYPE_IBM_WSoD 5
#define EFI_PXE_BASE_CODE_BOOT_TYPE_IBM_LCCM 6
#define EFI_PXE_BASE_CODE_BOOT_TYPE_CA_UNICENTER_TNG 7
#define EFI_PXE_BASE_CODE_BOOT_TYPE_HP_OPENVIEW 8
#define EFI_PXE_BASE_CODE_BOOT_TYPE_ALTIRIS_9 9
#define EFI_PXE_BASE_CODE_BOOT_TYPE_ALTIRIS_10 10
#define EFI_PXE_BASE_CODE_BOOT_TYPE_ALTIRIS_11 11
#define EFI_PXE_BASE_CODE_BOOT_TYPE_NOT_USED_12 12
#define EFI_PXE_BASE_CODE_BOOT_TYPE_REDDHAT_INSTALL 13
#define EFI_PXE_BASE_CODE_BOOT_TYPE_REDDHAT_BOOT 14
#define EFI_PXE_BASE_CODE_BOOT_TYPE_REDDHAT_BOOT 15
#define EFI_PXE_BASE_CODE_BOOT_TYPE_BEOBOOT 16
//
// Values 17 through 32767 are reserved.
// Values 32768 through 65279 are for vendor use.
// Values 65280 through 65534 are reserved.
//
#define EFI_PXE_BASE_CODE_BOOT_TYPE_PXETEST 65535
#define EFI_PXE_BASE_CODE_BOOT_LAYER_MASK 0x7FFF
#define EFI_PXE_BASE_CODE_BOOT_LAYER_INITIAL 0x0000

//*******************************************************
// EFI_PXE_BASE_CODE_DISCOVER_INFO
//*******************************************************
typedef struct {
    BOOLEAN UseMCast;
    BOOLEAN UseBCast;
    BOOLEAN UseUCast;
    BOOLEAN MustUseList;
    EFI_IP_ADDRESS ServerMCastIp;
    UINT16 IpCnt;
    EFI_PXE_BASE_CODE_SRVLIST SrvList[IpCnt];
} EFI_PXE_BASE_CODE_DISCOVER_INFO;

//*******************************************************
// EFI_PXE_BASE_CODE_SRVLIST
//*******************************************************
typedef struct {
    UINT16 Type;
    BOOLEAN AcceptAnyResponse;
    UINT8 reserved;
    EFI_IP_ADDRESS IpAddr;
} EFI_PXE_BASE_CODE_SRVLIST;
Description

This function attempts to complete the PXE Boot Server and/or boot image discovery sequence. If this sequence is completed, then EFI_SUCCESS is returned, and the PxeDiscoverValid, PxeDiscover, PxeReplyReceived, and PxeReply fields of the EFI_PXE_BASE_CODE_MODE in Network Protocols — SNP, PXE, BIS and HTTP Boot structure are filled in. If UseBis is TRUE, then the PxeBisReplyReceived and PxeBisReply fields of the EFI_PXE_BASE_CODE_MODE structure will also be filled in. If UseBis is FALSE, then PxeBisReplyValid will be set to FALSE.

In the structure referenced by parameter Info, the PXE Boot Server list, SrvList[], has two uses: It is the Boot Server IP address list used for unicast discovery (if the UseUCast field is TRUE), and it is the list used for Boot Server verification (if the MustUseList field is TRUE). Also, if the MustUseList field in that structure is TRUE and the AcceptAnyResponse field in the SrvList[] array is TRUE, any Boot Server reply of that type will be accepted. If the AcceptAnyResponse field is FALSE, only responses from Boot Servers with matching IP addresses will be accepted.

This function can take at least 10 seconds to timeout and return control to the caller. If the Discovery sequence does not complete, then EFI_TIMEOUT will be returned. Please see the Preboot Execution Environment (PXE) Specification for additional details on the implementation of the Discovery sequence.

If the Callback Protocol does not return EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE, then the Discovery sequence is stopped and EFI_ABORTED will be returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Discovery sequence has been completed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The PXE Base Code Protocol is in the stopped state.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions was TRUE:</td>
</tr>
<tr>
<td></td>
<td>• The This parameter was NULL</td>
</tr>
<tr>
<td></td>
<td>• The This parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL</td>
</tr>
<tr>
<td></td>
<td>• The Layer parameter was NULL</td>
</tr>
<tr>
<td></td>
<td>• The Info-&gt;ServerMCastIp parameter does not contain a valid multicast IP</td>
</tr>
<tr>
<td></td>
<td>address</td>
</tr>
<tr>
<td></td>
<td>• The Info-&gt;UseUCast parameter is not FALSE and the Info-&gt;IpCnt parameter is</td>
</tr>
<tr>
<td></td>
<td>zero</td>
</tr>
<tr>
<td></td>
<td>One or more of the IP addresses in the Info-&gt;SrvList[] array is not a valid</td>
</tr>
<tr>
<td></td>
<td>unicast IP address.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The network device encountered an error during this operation.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate enough memory to complete Discovery.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>The callback function aborted the Discovery sequence.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The Discovery sequence timed out.</td>
</tr>
<tr>
<td>EFI_ICMP_ERROR</td>
<td>An ICMP error packet was received during the PXE discovery session. The</td>
</tr>
<tr>
<td></td>
<td>ICMP error packet has been cached in the EFI_PXE_BASE_CODE_MODE. IcmpError</td>
</tr>
<tr>
<td></td>
<td>packet structure. Information about ICMP packet contents can be found in</td>
</tr>
<tr>
<td></td>
<td>RFC 792.</td>
</tr>
</tbody>
</table>
24.3.10 EFI_PXE_BASE_CODE_PROTOCOL.Mtftp()

Summary
Used to perform TFTP and MTFTP services.

Prototype

```c
typedef
EFI_STATUS
(EFI_PXE_BASE_CODE_MTFTP) (...);
```

Parameters

**This**
Pointer to the `EFI_PXE_BASE_CODE_PROTOCOL` instance.

**Operation**
The type of operation to perform. See “Related Definitions” below for the list of operation types.

**BufferPtr**
A pointer to the data buffer. Ignored for read file if `DontUseBuffer` is TRUE.

**Overwrite**
Only used on write file operations. TRUE if a file on a remote server can be overwritten.

**BufferSize**
For get-file-size operations, BufferSize returns the size of the requested file. For read-file and write-file operations, this parameter is set to the size of the buffer specified by the `BufferPtr` parameter. For read-file operations, if `EFI_BUFFER_TOO_SMALL` is returned, `BufferSize` returns the size of the requested file.

**BlockSize**
The requested block size to be used during a TFTP transfer. This must be at least 512. If this field is NULL, then the largest block size supported by the implementation will be used.

**ServerIp**
The TFTP / MTFTP server IP address.

**Filename**
A Null-terminated ASCII string that specifies a directory name or a file name. This is ignored by MTFTP read directory.

**Info**
Pointer to the MTFTP information. This information is required to start or join a multicast TFTP session. It is also required to perform the “get file size” and “read directory” operations of MTFTP. See “Related Definitions” below for the description of this data structure.

**DontUseBuffer**
Set to FALSE for normal TFTP and MTFTP read file operation. Setting this to TRUE will cause TFTP and
MTFTP read file operations to function without a receive buffer, and all of the received packets are passed to the Callback Protocol which is responsible for storing them. This field is only used by TFTP and MTFTP read file.

Related Definitions

```c
//*******************************************************
// EFI_PXE_BASE_CODE_TFTP_OPCODE
//*******************************************************
typedef enum {
    EFI_PXE_BASE_CODE_TFTP_FIRST,
    EFI_PXE_BASE_CODE_TFTP_GET_FILE_SIZE,
    EFI_PXE_BASE_CODE_TFTP_READ_FILE,
    EFI_PXE_BASE_CODE_TFTP_WRITE_FILE,
    EFI_PXE_BASE_CODE_TFTP_READ_DIRECTORY,
    EFI_PXE_BASE_CODE_MTFTP_GET_FILE_SIZE,
    EFI_PXE_BASE_CODE_MTFTP_READ_FILE,
    EFI_PXE_BASE_CODE_MTFTP_READ_DIRECTORY,
    EFI_PXE_BASE_CODE_MTFTP_LAST
} EFI_PXE_BASE_CODE_TFTP_OPCODE;
```

```c
//*******************************************************
// EFI_PXE_BASE_CODE_MTFTP_INFO
//*******************************************************
typedef struct {
    EFI_IP_ADDRESS MCastIp;
    EFI_PXE_BASE_CODE_UDP_PORT CPort;
    EFI_PXE_BASE_CODE_UDP_PORT SPort;
    UINT16 ListenTimeout;
    UINT16 TransmitTimeout;
} EFI_PXE_BASE_CODE_MTFTP_INFO;
```

**MCastIp**
File multicast IP address. This is the IP address to which the server will send the requested file.

**CPort**
Client multicast listening port. This is the UDP port to which the server will send the requested file.

**SPort**
Server multicast listening port. This is the UDP port on which the server listens for multicast open requests and data acks.

**ListenTimeout**
The number of seconds a client should listen for an active multicast session before requesting a new multicast session.

**TransmitTimeout**
The number of seconds a client should wait for a packet from the server before retransmitting the previous open request or data ack packet.

**Description**
This function is used to perform TFTP and MTFTP services. This includes the TFTP operations to get the size of a file, read a directory, read a file, and write a file. It also includes the MTFTP operations to get the size of a file, read a directory, and read a file. The type of operation is specified by `Operation`. If the callback function that is invoked during the TFTP/MTFTP operation does not return EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE, then EFI_ABORTED will be returned.

For read operations, the return data will be placed in the buffer specified by `BufferPtr`. If `BufferSize` is too small
to contain the entire downloaded file, then EFI_BUFFER_TOO_SMALL will be returned and BufferSize will be set to zero or the size of the requested file (the size of the requested file is only returned if the TFTP server supports TFTP options). If BufferSize is large enough for the read operation, then BufferSize will be set to the size of the downloaded file, and EFI_SUCCESS will be returned. Applications using the PxeBc.Mtftp() services should use the get-file-size operations to determine the size of the downloaded file prior to using the read-file operations—especially when downloading large (greater than 64 MiB) files—instead of making two calls to the read-file operation. Following this recommendation will save time if the file is larger than expected and the TFTP server does not support TFTP option extensions. Without TFTP option extension support, the client has to download the entire file, counting and discarding the received packets, to determine the file size.

For write operations, the data to be sent is in the buffer specified by BufferPtr. BufferSize specifies the number of bytes to send. If the write operation completes successfully, then EFI_SUCCESS will be returned.

For TFTP “get file size” operations, the size of the requested file or directory is returned in BufferSize, and EFI_SUCCESS will be returned. If the TFTP server does not support options, the file will be downloaded into a bit bucket and the length of the downloaded file will be returned. For MTFTP “get file size” operations, if the MTFTP server does not support the “get file size” option, EFI_UNSUPPORTED will be returned.

This function can take up to 10 seconds to timeout and return control to the caller. If the TFTP sequence does not complete, EFI_TIMEOUT will be returned.

If the Callback Protocol does not return EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE, then the TFTP sequence is stopped and EFI_ABORTED will be returned.

The format of the data returned from a TFTP read directory operation is a null-terminated filename followed by a null-terminated information string, of the form “size year-month-day hour:minute:second” (i.e., %d %d-%d-%d %d:%d:%f - note that the seconds field can be a decimal number), where the date and time are UTC. For an MTFTP read directory command, there is additionally a null-terminated multicast IP address preceding the filename of the form %d.%d.%d.%d for IP v4. The final entry is itself null-terminated, so that the final information string is terminated with two null octets.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The TFTP/MTFTP operation was completed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The PXE Base Code Protocol is in the stopped state.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions was TRUE :</td>
</tr>
<tr>
<td></td>
<td>• The This parameter was NULL</td>
</tr>
<tr>
<td></td>
<td>• The This parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure</td>
</tr>
<tr>
<td></td>
<td>• The Operation parameter was not one of the listed EFI_PXE_BASE_CODE_TFTP_OPCODE constants</td>
</tr>
<tr>
<td></td>
<td>• The BufferPtr parameter was NULL and the DontUseBuffer parameter was FALSE</td>
</tr>
<tr>
<td></td>
<td>• The BufferSize parameter was NULL</td>
</tr>
<tr>
<td></td>
<td>• The BlockSize parameter was not NULL and * BlockSize was less than 512</td>
</tr>
<tr>
<td></td>
<td>• The ServerIp parameter was NULL or did not contain a valid unicast IP address</td>
</tr>
<tr>
<td></td>
<td>• The Filename parameter was NULL for a file transfer or information request</td>
</tr>
<tr>
<td></td>
<td>• The Info parameter was NULL for a multicast request</td>
</tr>
<tr>
<td></td>
<td>The Info-&gt;MCastIp parameter is not a valid multicast IP address</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The network device encountered an error during this operation.</td>
</tr>
</tbody>
</table>

continues on next page
Table 24.18 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The buffer is not large enough to complete the read operation.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>The callback function aborted the TFTP/MTFTP operation.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The TFTP/MTFTP operation timed out.</td>
</tr>
<tr>
<td>EFI_TFTP_ERROR</td>
<td>A TFTP error packet was received during the MTFTP session. The TFTP error packet has been cached in the EFI_PXE_BASE_CODE_MODE. TftpError packet structure. Information about TFTP error packet contents can be found in RFC 1350.</td>
</tr>
<tr>
<td>EFI_ICMP_ERROR</td>
<td>An ICMP error packet was received during the MTFTP session. The ICMP error packet has been cached in the EFI_PXE_BASE_CODE_MODE. IcmpError packet structure. Information about ICMP packet contents can be found in RFC 792.</td>
</tr>
</tbody>
</table>

24.3.11 EFI_PXE_BASE_CODE_PROTOCOL.UdpWrite()

Summary

Writes a UDP packet to the network interface.

Prototype

```c
typedef EFI_STATUS (EFI_PXE_BASE_CODE_UDP_WRITE) (    
  IN EFI_PXE_BASE_CODE_PROTOCOL *This,              
  IN UINT16 OpFlags,                               
  IN EFI_IP_ADDRESS *DestIp,                       
  IN EFI_PXE_BASE_CODE_UDP_PORT *DestPort,         
  IN EFI_IP_ADDRESS *GatewayIp, OPTIONAL           
  IN EFI_IP_ADDRESS *SrcIp, OPTIONAL               
  IN OUT EFI_PXE_BASE_CODE_UDP_PORT *SrcPort, OPTIONAL 
  IN UINTN *HeaderSize, OPTIONAL                   
  IN VOID *HeaderPtr, OPTIONAL                     
  IN UINTN *BufferSize,                            
  IN VOID *BufferPtr                               
  )
```

Parameters

This

Pointer to the EFI_PXE_BASE_CODE_PROTOCOL instance.

OpFlags

The UDP operation flags. If MAY_FRAGMENT is set, then if required, this UDP write operation may be broken up across multiple packets.

DestIp

The destination IP address.

DestPort

The destination UDP port number.

GatewayIp

The gateway IP address. If DestIp is not in the same subnet as StationIp, then this gateway IP address will be used. If this field is NULL, and the DestIp is not in the same subnet as StationIp, then the RouteTable will be used.
SrcIp
The source IP address. If this field is NULL, then StationIp will be used as the source IP address.

SrcPort
The source UDP port number. If OpFlags has ANY_SRC_PORT set or SrcPort is NULL, then a source UDP port will be automatically selected. If a source UDP port was automatically selected, and SrcPort is not NULL, then it will be returned in SrcPort.

HeaderSize
An optional field which may be set to the length of a header at HeaderPtr to be prefixed to the data at BufferPtr.

HeaderPtr
If HeaderSize is not NULL, a pointer to a header to be prefixed to the data at BufferPtr.

BufferSize
A pointer to the size of the data at BufferPtr.

BufferPtr
A pointer to the data to be written.

Description
This function writes a UDP packet specified by the (optional HeaderPtr and) BufferPtr parameters to the network interface. The UDP header is automatically built by this routine. It uses the parameters OpFlags, DestIp, DestPort, GatewayIp, SrcIp, and SrcPort to build this header. If the packet is successfully built and transmitted through the network interface, then EFI_SUCCESS will be returned. If a timeout occurs during the transmission of the packet, then EFI_TIMEOUT will be returned. If an ICMP error occurs during the transmission of the packet, then the IcmpError-Received field is set to TRUE, the IcmpError field is filled in and EFI_ICMP_ERROR will be returned. If the Callback Protocol does not return EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE, then EFI_ABORTED will be returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The UDP Write operation was completed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The PXE Base Code Protocol is in the stopped state.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more of the following conditions was TRUE:
  • The This parameter was NULL
  • The This parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure
  • Reserved bits in the OpFlags parameter were not set to zero - The DestIp parameter was NULL
  • The DestPort parameter was NULL
  • The GatewayIp parameter was not NULL and did not contain a valid unicast IP address.
  • The HeaderSize parameter was not NULL and *HeaderSize is zero
  • The HeaderSize parameter was not zero and the HeaderPtr parameter was *NULL
  • The BufferSize parameter was NULL
  • The BufferSize parameter was not zero and the BufferPtr parameter was *NULL
| EFI_DEVICE_ERROR      | The network device encountered an error during this operation.              |
| EFI_BAD_BUFFER_SIZE   | The buffer is too long to be transmitted.                                   |
| EFI_ABORTED           | The callback function aborted the UDP Write operation.                     |

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Table 24.19 – continued from previous page

<table>
<thead>
<tr>
<th>Macro</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_TIMEOUT</td>
<td>The UDP Write operation timed out.</td>
</tr>
<tr>
<td>EFI_ICMP_ERROR</td>
<td>An ICMP error packet was received during the UDP write session. The ICMP</td>
</tr>
<tr>
<td></td>
<td>error packet has been cached in the EFI_PXE_BASE_CODE_MODE. IcmpError packet</td>
</tr>
<tr>
<td></td>
<td>structure. Information about ICMP packet contents can be found in RFC 792.</td>
</tr>
</tbody>
</table>

### 24.3.12 EFI_PXE_BASE_CODE_PROTOCOL.UdpRead()

**Summary**

Reads a UDP packet from the network interface.

**Prototype**

```c
typedef EFI_STATUS (EFIAPICallingConvention EFI_PXE_BASE_CODE_UDP_READ) (   
  IN EFI_PXE_BASE_CODE_PROTOCOL *This,   
  IN UINT16 OpFlags,   
  IN OUT EFI_IP_ADDRESS *DestIp, OPTIONAL,   
  IN OUT EFI_PXE_BASE_CODE_UDP_PORT *DestPort, OPTIONAL,   
  IN OUT EFI_IP_ADDRESS *SrcIp, OPTIONAL,   
  IN OUT EFI_PXE_BASE_CODE_UDP_PORT *SrcPort, OPTIONAL,   
  IN UINTN *HeaderSize, OPTIONAL,   
  IN VOID *HeaderPtr,   
  IN OUT UINTN *BufferSize,   
  IN VOID *BufferPtr   
);   
```

**Parameters**

- **This**
  
  Pointer to the *EFI_PXE_BASE_CODE_PROTOCOL* instance.

- **OpFlags**
  
  The UDP operation flags.

- **DestIp**
  
  The destination IP address.

- **DestPort**
  
  The destination UDP port number.

- **SrcIp**
  
  The source IP address.

- **SrcPort**
  
  The source UDP port number.

- **HeaderSize**
  
  An optional field which may be set to the length of a header to be put in *HeaderPtr*.

- **HeaderPtr**
  
  If *HeaderSize* is not NULL, a pointer to a buffer to hold the *HeaderSize* bytes which follow the UDP header.

- **BufferSize**
  
  On input, a pointer to the size of the buffer at *BufferPtr*. On output, the size of the data written to *BufferPtr*.
**BufferPtr**
A pointer to the data to be read.

**Description**
This function reads a UDP packet from a network interface. The data contents are returned in (the optional `HeaderPtr` and) `BufferPtr`, and the size of the buffer received is returned in `BufferSize`. If the input `BufferSize` is smaller than the UDP packet received (less optional `HeaderSize`), it will be set to the required size, and `EFI_BUFFER_TOO_SMALL` will be returned. In this case, the contents of `BufferPtr` are undefined, and the packet is lost. If a UDP packet is successfully received, then `EFI_SUCCESS` will be returned, and the information from the UDP header will be returned in `DestIp, DestPort, SrcIp, and SrcPort` if they are not NULL. Depending on the values of `OpFlags` and the `DestIp, DestPort, SrcIp, and SrcPort` input values, different types of UDP packet receive filtering will be performed. The following tables summarize these receive filter operations.

**Destination IP Filter Operation**

<table>
<thead>
<tr>
<th>OpFlags USE_FILTER</th>
<th>OpFlags ANY_DEST_IP</th>
<th>DestIp</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>NULL</td>
<td>Receive a packet sent to <code>StationIp</code>.</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>NULL</td>
<td>Receive a packet sent to any IP address.</td>
</tr>
<tr>
<td>1</td>
<td>x</td>
<td>NULL</td>
<td>Receive a packet whose destination IP address passes the IP filter.</td>
</tr>
<tr>
<td>0</td>
<td>0</td>
<td>not NULL</td>
<td>Receive a packet whose destination IP address matches <code>DestIp</code>.</td>
</tr>
<tr>
<td>0</td>
<td>1</td>
<td>not NULL</td>
<td>Receive a packet sent to any IP address and, return the destination IP address in <code>DestIp</code>.</td>
</tr>
<tr>
<td>1</td>
<td>x</td>
<td>not NULL</td>
<td>Receive a packet whose destination IP address passes the IP filter, and return the destination IP address in <code>DestIp</code>.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>OpFlags ANY_DEST_PORT</th>
<th>DestPort</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>NULL</td>
<td>Return <code>EFI_INVALID_PARAMETER</code>.</td>
</tr>
<tr>
<td>1</td>
<td>NULL</td>
<td>Receive a packet sent to any UDP port.</td>
</tr>
<tr>
<td>0</td>
<td>not NULL</td>
<td>Receive a packet whose destination Port matches <code>DestPort</code>.</td>
</tr>
<tr>
<td>1</td>
<td>not NULL</td>
<td>Receive a packet sent to any UDP port, and return the destination port in <code>DestPort</code>.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>OpFlags ANY_SRC_IP</th>
<th>SrcIp</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>NULL</td>
<td>Return <code>EFI_INVALID_PARAMETER</code>.</td>
</tr>
</tbody>
</table>

---

continues on next page
Table 24.22 – continued from previous page

<table>
<thead>
<tr>
<th>OpFlags</th>
<th>NULL</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>NULL</td>
<td>Receive a packet sent from any IP address.</td>
</tr>
<tr>
<td>0</td>
<td>not NULL</td>
<td>Receive a packet whose source IP address matches SrcIp.</td>
</tr>
<tr>
<td>1</td>
<td>not NULL</td>
<td>Receive a packet sent from any IP address, and return the source IP address in SrcIp.</td>
</tr>
</tbody>
</table>

Table 24.23: Source UDP Port Filter Operation

<table>
<thead>
<tr>
<th>OpFlags</th>
<th>SrcPort</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>ANY_SRC_PORT</td>
<td>NULL</td>
<td>Return EFI_INVALID_PARAMETER.</td>
</tr>
<tr>
<td>0</td>
<td>NULL</td>
<td>Return EFI_INVALID_PARAMETER.</td>
</tr>
<tr>
<td>1</td>
<td>NULL</td>
<td>Receive a packet sent from any UDP port.</td>
</tr>
<tr>
<td>0</td>
<td>not NULL</td>
<td>Receive a packet whose source UDP port matches SrcPort.</td>
</tr>
<tr>
<td>1</td>
<td>not NULL</td>
<td>Receive a packet sent from any UDP port, and return the source UDP port in SrcPort.</td>
</tr>
</tbody>
</table>

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The UDP Read operation was completed.</td>
</tr>
<tr>
<td>EFi_NOT_STARTED</td>
<td>The PXE Base Code Protocol is in the stopped state.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions was True:</td>
</tr>
<tr>
<td></td>
<td>• The This parameter was NULL</td>
</tr>
<tr>
<td></td>
<td>• The This parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure</td>
</tr>
<tr>
<td></td>
<td>• Reserved bits in the OpFlags parameter were not set to zero</td>
</tr>
<tr>
<td></td>
<td>• The HeaderSize parameter is not NULL and * HeaderSize is zero</td>
</tr>
<tr>
<td></td>
<td>• The HeaderSize parameter is not NULL L and the HeaderPtr parameter is NULL</td>
</tr>
<tr>
<td></td>
<td>• The BufferSize parameter is NULL</td>
</tr>
<tr>
<td></td>
<td>• The BufferPtr parameter is NULL</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The network device encountered an error during this operation.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The packet is larger than Buffer can hold.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>The callback function aborted the UDP Read operation.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The UDP Read operation timed out.</td>
</tr>
</tbody>
</table>

24.3.13 EFI_PXE_BASE_CODE_PROTOCOL.SetIpFilter()

Summary

Updates the IP receive filters of a network device and enables software filtering.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_PXE_BASE_CODE_SET_IP_FILTER) ( |
  IN EFI_PXE_BASE_CODE_PROTOCOL *This, |
  IN EFI_PXE_BASE_CODE_IP_FILTER *NewFilter |
);
Parameters

This

Pointer to the EFI_PXE_BASE_CODE_PROTOCOL instance.

NewFilter

Pointer to the new set of IP receive filters.

Description

The NewFilter field is used to modify the network device’s current IP receive filter settings and to enable a software filter. This function updates the IpFilter field of the EFI_PXE_BASE_CODE_MODE in Network Protocols — SNP, PXE, BIS and HTTP Boot structure with the contents of NewIpFilter. The software filter is used when the USE_FILTER in OpFlags is set to EFI_PXE_BASE_CODE_PROTOCOL.UdpRead(). The current hardware filter remains in effect no matter what the settings of OpFlags are, so that the meaning of ANY_DEST_IP set in OpFlags to UdpRead() is from those packets whose reception is enabled in hardware - physical NIC address (unicast), broadcast address, logical address or addresses (multicast), or all (promiscuous). UdpRead() does not modify the IP filter settings.

EFI_PXE_BASE_CODE_PROTOCOL.Dhcp()

, EFI_PXE_BASE_CODE_PROTOCOL.Discover()

, and

EFI_PXE_BASE_CODE_PROTOCOL.Mtftp()

set the IP filter, and return with the IP receive filter list emptied and the filter set to EFI_PXE_BASE_CODE_IP_FILTER_STATION_IP. If an application or driver wishes to preserve the IP receive filter settings, it will have to preserve the IP receive filter settings before these calls, and use

EFI_PXE_BASE_CODE_PROTOCOL.SetIpFilter() to restore them after the calls. If incompatible filtering is requested (for example, PROMISCUOUS with anything else) or if the device does not support a requested filter setting and it cannot be accommodated in software (for example, PROMISCUOUS not supported), EFI_INVALID_PARAMETER will be returned. The IPlist field is used to enable IPs other than the StationIP. They may be multicast or unicast. If IPcnt is set as well as EFI_PXE_BASE_CODE_IP_FILTER_STATION_IP, then both the StationIP and the IPs from the IPlist will be used.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The IP receive filter settings were updated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>• One or more of the following conditions was TRUE:</td>
</tr>
<tr>
<td></td>
<td>• The This parameter was NULL</td>
</tr>
<tr>
<td></td>
<td>• The This parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL</td>
</tr>
<tr>
<td></td>
<td>structure</td>
</tr>
<tr>
<td></td>
<td>• The NewFilter parameter was NULL</td>
</tr>
<tr>
<td></td>
<td>• The NewFilter -&gt; IPlist [] array contains one or more broadcast IP</td>
</tr>
<tr>
<td></td>
<td>addresses</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The PXE Base Code Protocol is not in the started state.</td>
</tr>
</tbody>
</table>

24.3.14 EFI_PXE_BASE_CODE_PROTOCOL.Arp()

Summary

Uses the ARP protocol to resolve a MAC address.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_PXE_BASE_CODE_ARP) (    IN EFI_PXE_BASE_CODE_PROTOCOL *This,
    ...

(continues on next page)
IN EFI_IP_ADDRESS *IpAddr,
IN EFI_MAC_ADDRESS *MacAddr OPTIONAL
);

Parameters

This
Pointer to the EFI_PXE_BASE_CODE_PROTOCOL instance.

IpAddr
Pointer to the IP address that is used to resolve a MAC address. When the MAC address is resolved, the Arp-CacheEntries and ArpCache fields of the EFI_PXE_BASE_CODE_MODE in Network Protocols — SNP, PXE, BIS and HTTP Boot structure are updated.

MacAddr
If not NULL, a pointer to the MAC address that was resolved with the ARP protocol.

Description

This function uses the ARP protocol to resolve a MAC address. The UsingIpv6 field of the EFI_PXE_BASE_CODE_MODE structure is used to determine if IPv4 or IPv6 addresses are being used. The IP address specified by IpAddr is used to resolve a MAC address in the case of IPv4; the concept of Arp is not supported in IPv6, though.

If the ARP protocol succeeds in resolving the specified address, then the ArpCacheEntries and ArpCache fields of the EFI_PXE_BASE_CODE_MODE structure are updated, and EFI_SUCCESS is returned. If MacAddr is not NULL, the resolved MAC address is placed there as well.

If the PXE Base Code protocol is in the stopped state, then EFI_NOT_STARTED is returned. If the ARP protocol encounters a timeout condition while attempting to resolve an address, then EFI_TIMEOUT is returned. If the Call-back Protocol does not return EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE, then EFI_ABORTED is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The IP or MAC address was resolved.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more of the following conditions was :  
• The This parameter was NULL  
• The This parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure  
• The IpAddr parameter was NULL |
| EFI_DEVICE_ERROR | The network device encountered an error during this operation. |
| EFI_NOT_STARTED | The PXE Base Code Protocol is in the stopped state. |
| EFI_TIMEOUT | The ARP Protocol encountered a timeout condition. |
| EFI_ABORTED | The callback function aborted the ARP Protocol. |
| EFI_UNSUPPORTED | When Mode->UsingIpv6 is TRUE because the Arp is a concept special for IPv4. |
24.3.15 EFI_PXE_BASE_CODE_PROTOCOL.SetParameters()

Summary
Updates the parameters that affect the operation of the PXE Base Code Protocol.

Prototype

typedef
EFI_STATUS
(EIFIAP1 *EFI_PXE_BASE_CODE_SET_PARAMETERS) (
    IN EFI_PXE_BASE_CODE_PROTOCOL *This,
    IN BOOLEAN *NewAutoArp, OPTIONAL
    IN BOOLEAN *NewSendGUID, OPTIONAL
    IN UINT8 *NewTTL, OPTIONAL
    IN UINT8 *NewToS, OPTIONAL
    IN BOOLEAN *NewMakeCallback OPTIONAL
);

Parameters

This
Pointer to the EFI_PXE_BASE_CODE_PROTOCOL instance.

NewAutoArp
If not NULL, a pointer to a value that specifies whether to replace the current value of AutoARP. TRUE for automatic ARP packet generation, FALSE otherwise. If NULL, this parameter is ignored.

NewSendGUID
If not NULL, a pointer to a value that specifies whether to replace the current value of SendGUID. TRUE to send the SystemGUID (if there is one) as the client hardware address in DHCP; FALSE to send client NIC MAC address. If NULL, this parameter is ignored. If NewSendGUID is TRUE and there is no SystemGUID, then EFI_INVALID_PARAMETER is returned.

NewTTL
If not NULL, a pointer to be used in place of the current value of TTL, the “time to live” field of the IP header. If NULL, this parameter is ignored.

NewToS
If not NULL, a pointer to be used in place of the current value of ToS, the “type of service” field of the IP header. If NULL, this parameter is ignored.

NewMakeCallback
If not NULL, a pointer to a value that specifies whether to replace the current value of the MakeCallback field of the Mode structure. If NULL, this parameter is ignored. If the Callback Protocol is not available EFI_INVALID_PARAMETER is returned.

Description
This function sets parameters that affect the operation of the PXE Base Code Protocol. The parameter specified by NewAutoArp is used to control the generation of ARP protocol packets. If NewAutoArp is TRUE, then ARP Protocol packets will be generated as required by the PXE Base Code Protocol. If NewAutoArp is FALSE, then no ARP Protocol packets will be generated. In this case, the only mappings that are available are those stored in the ArpCache of the EFI_PXE_BASE_CODE_MODE in Network Protocols — SNP, PXE, BIS and HTTP Boot structure. If there are not enough mappings in the ArpCache to perform a PXE Base Code Protocol service, then the service will fail. This function updates the AutoArp field of the EFI_PXE_BASE_CODE_MODE structure to NewAutoArp.
The \texttt{EFI_PXE_BASE_CODE_PROTOCOL.SetParameters()} call must be invoked after a Callback Protocol is installed to enable the use of callbacks.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The new parameters values were updated.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER| • One or more of the following conditions was \textit{TRUE}:
  • The This parameter was \texttt{NULL}
  • The This parameter did not point to a valid \texttt{EFI_PXE_BASE_CODE_PROTOCOL} structure
  • The \texttt{NewSendGUID} parameter is not \texttt{NULL} and * \texttt{NewSendGUID} is \texttt{TRUE} and a system GUID could not be located
  • The \texttt{NewMakeCallback} parameter is not \texttt{NULL} and * \texttt{NewMakeCallback} is \texttt{TRUE} and an \texttt{EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL} could not be located on the network device handle. |
| EFI_NOT_STARTED     | The PXE Base Code Protocol is not in the started state.                     |

### 24.3.16 \texttt{EFI_PXE_BASE_CODE_PROTOCOL.SetStationIp()}

**Summary**

Updates the station IP address and/or subnet mask values of a network device.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_PXE_BASE_CODE_SET_STATION_IP) (  
  IN EFI_PXE_BASE_CODE_PROTOCOL *This,
  IN EFI_IP_ADDRESS *NewStationIp, OPTIONAL
  IN EFI_IP_ADDRESS *NewSubnetMask OPTIONAL
);
```

**Parameters**

- **This**
  Pointer to the \texttt{EFI_PXE_BASE_CODE_PROTOCOL} instance.

- **NewStationIp**
  Pointer to the new IP address to be used by the network device. If this field is NULL, then the StationIp address will not be modified.

- **NewSubnetMask**
  Pointer to the new subnet mask to be used by the network device. If this field is NULL, then the SubnetMask will not be modified.

**Description**

This function updates the station IP address and/or subnet mask values of a network device.

The \texttt{NewStationIp} field is used to modify the network device’s current IP address. If \texttt{NewStationIp} is NULL, then the current IP address will not be modified. Otherwise, this function updates the StationIp field of the \texttt{EFI_PXE_BASE_CODE_MODE} in \textit{Network Protocols — SNP, PXE, BIS and HTTP Boot} structure with \texttt{NewStationIp}.  

24.3. PXE Base Code Protocol
The `NewSubnetMask` field is used to modify the network device’s current subnet mask. If `NewSubnetMask` is NULL, then the current subnet mask will not be modified. Otherwise, this function updates the `SubnetMask` field of the `EFI_PXE_BASE_CODE_MODE` structure with `NewSubnetMask`.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The new station IP address and/or subnet mask were updated.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER    | One or more of the following conditions was `TRUE`:
- The `This` parameter was `NULL`
- The `This` parameter did not point to a valid `EFI_PXE_BASE_CODE_PROTOCOL` structure
- The `NewStationIp` parameter is not `NULL`, and `*NewStationIp` is not a valid unicast IP address
- The `NewSubnetMask` parameter is not `NULL`, and `*NewSubnetMask` does not contain a valid IP subnet mask |
| EFI_NOT_STARTED          | The PXE Base Code Protocol is not in the started state.                     |

### 24.3.17 `EFI_PXE_BASE_CODE_PROTOCOL.SetPackets()`

#### Summary
Updates the contents of the cached DHCP and Discover packets.

#### Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_PXE_BASE_CODE_SET_PACKETS) (  
    IN EFI_PXE_BASE_CODE_PROTOCOL *This,  
    IN BOOLEAN *NewDhcpDiscoverValid, OPTIONAL  
    IN BOOLEAN *NewDhcpAckReceived, OPTIONAL  
    IN BOOLEAN *NewProxyOfferReceived, OPTIONAL  
    IN BOOLEAN *NewPxeDiscoverValid, OPTIONAL  
    IN BOOLEAN *NewPxeReplyReceived, OPTIONAL  
    IN BOOLEAN *NewPxeBisReplyReceived, OPTIONAL  
    IN EFI_PXE_BASE_CODE_PACKET *NewDhcpDiscover, OPTIONAL  
    IN EFI_PXE_BASE_CODE_PACKET *NewDhcpAck, OPTIONAL  
    IN EFI_PXE_BASE_CODE_PACKET *NewProxyOffer, OPTIONAL  
    IN EFI_PXE_BASE_CODE_PACKET *NewPxeDiscover, OPTIONAL  
    IN EFI_PXE_BASE_CODE_PACKET *NewPxeReply, OPTIONAL  
    IN EFI_PXE_BASE_CODE_PACKET *NewPxeBisReply OPTIONAL
);```

#### Parameters

- **This**
  Pointer to the `EFI_PXE_BASE_CODE_PROTOCOL` instance.

- **NewDhcpDiscoverValid**
  Pointer to a value that will replace the current `DhcpDiscoverValid` field. If NULL, this parameter is ignored.

- **NewDhcpAckReceived**
  Pointer to a value that will replace the current `DhcpAckReceived` field. If NULL, this parameter is ignored.
NewProxyOfferReceived
Pointer to a value that will replace the current ProxyOfferReceived field. If NULL, this parameter is ignored.

NewPxeDiscoverValid
Pointer to a value that will replace the current ProxyOfferReceived field. If NULL, this parameter is ignored.

NewPxeReplyReceived
Pointer to a value that will replace the current PxeReplyReceived field. If NULL, this parameter is ignored.

NewPxeBisReplyReceived
Pointer to a value that will replace the current PxeBisReplyReceived field. If NULL, this parameter is ignored.

NewDhcpDiscover
Pointer to the new cached DHCP Discover packet contents. If NULL, this parameter is ignored.

NewDhcpAck
Pointer to the new cached DHCP Ack packet contents. If NULL, this parameter is ignored.

NewProxyOffer
Pointer to the new cached Proxy Offer packet contents. If NULL, this parameter is ignored.

NewPxeDiscover
Pointer to the new cached PXE Discover packet contents. If NULL, this parameter is ignored.

NewPxeReply
Pointer to the new cached PXE Reply packet contents. If NULL, this parameter is ignored.

NewPxeBisReply
Pointer to the new cached PXE BIS Reply packet contents. If NULL, this parameter is ignored.

Description
The pointers to the new packets are used to update the contents of the cached packets in the EFI_PXE_BASE_CODE_MODE structure.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The cached packet contents were updated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>• One or more of the following conditions was TRUE :</td>
</tr>
<tr>
<td></td>
<td>• The This parameter was NULL</td>
</tr>
<tr>
<td></td>
<td>The This parameter did not point to a valid EFI_PXE_BASE_CODE_PROTOCOL structure.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The PXE Base Code Protocol is not in the started state.</td>
</tr>
</tbody>
</table>

24.3.18 Netboot6

For IPv4, PXE drivers typically install a LoadFile protocol on the NIC handle. In the case of supporting both IPv4 and IPv6 where two PXE Base Code and LoadFile protocol instances need be produced, the PXE driver will have to create two child handles and install EFI_LOAD_FILE_PROTOCOL, EFI_SIMPLE_NETWORK_PROTOCOL and PXE_BASE_CODE_PROTOCOL on each child handle. To distinguish these two child handles, an IP device path node can be appended to the parent device path, for example:

PciRoot(0x0)/Pci(0x19,0x0)/MAC(001320F4B4FF,0x0)/IPv4(...)  
PciRoot(0x0)/Pci(0x19,0x0)/MAC(001320F4B4FF,0x0)/IPv6(...)
These two instances allow for the boot manager to decide a preference of IPv6 versus IPv4 since the IETF and other bodies do not speak to this policy choice.

### 24.3.18.1 DHCP6 options for PXE

In IPv4-based PXE, as defined by the rfc2131, rfc2132 and rfc4578, and described by the PXE2.1 specification and the UEFI specification, there are the following PXE related options/fields in DHCPv4 packet:

- siaddr field/ServerAddress option (54) - next server address.
- BootFileName option (67)
  - NBP file name.
- BootFileSize option (13)
  - NBP file size.
- ClassIdentifier (60)
  - PXE client tag.
- ClientSystemArchitectureType option (93)
  - client architecture type.
- ClientNetworkInterfaceIdentifier option (94)
  - client network interface identifier.

In IPv6-based PXE, or 'netboot6', there are the following PXE related options in the DHCPv6 packet:

- BootFileURL option - OPT_BOOTFILE_URL (59) — next server address and NBP (Network Bootable Program) file name.
- BootFileParameters option
  - OPT_BOOTFILE_PARAM (60) — NBP file size.
- VendorClass option (16)
  - PXE client tag.
- ClientSystemArchitectureType option — OPTION_CLIENT_ARCH_TYPE (61) — client architecture type.
- ClientNetworkInterfaceIdentifier option (62) — client network interface identifier.

The BootFileURL option is used to deliver the next server address or the next server address with NBP file name.

As an example where the next server address delivered only: “tftp://[FEDC:BA98:7654:3210:FE][D:BA98:7654:3210];mode=octet”.

As an example where the next server address and BOOTFILE_NAME delivered both: “tftp://[FEDC:BA98:7654:3210:FE][D:BA98:7654:3210]/BOOTFILE_NAME;mode=octet”.

The BootFileParameters option is used to deliver the NBP file size with the unit of 512-octet blocks. The maximum of the NBP file size is 65535 * 512 bytes.

As an example where the NBP file size is 1600 * 512 bytes:

```
para-len 1 = 4
parameter 1 = "1600"
```
The VendorClass option is used to deliver the PXE client tag.

As an example where the client architecture is EFI-X64 and the client network interface identifier is UNDI:

```
Enterprise-number = (343)
Vendor-class-data = "PXEClient:Arch:00006:UNDI:003016"
#define DUID-UUID 4
```

The Netboot6 client will use the DUID-UUID to report the platform identifier as part of the netboot6 DHCP options.

### 24.3.18.2 IPv6-based PXE boot

As PXE 2.1 specification describes step-by-step synopsis of the IPv4-based PXE process, Figure 1 describes the corresponding synopsis for netboot6.

#### 24.3.18.2.1 Step 1.

The client multicasts a SOLICIT message to the standard DHCP6 port (547). It contains the following:

- A tag for client UNDI version.
- A tag for the client system architecture.
- A tag for PXE client, Vendor Class data set to
  - “PXEClient:Arch:xxxxx:UNDI:yyyyMMdd”.

#### 24.3.18.2.2 Step 2.

The DHCP6 or Proxy DHCP6 service responds by sending a ADVERTISE message to the client on the standard DHCP6 reply port (546). If this is a Proxy DHCP6 service, the next server (Boot Server) address is delivered by Boot File URL option. If this is a DHCP6 service, the new assigned client address is delivered by IA option. The extension tags information will be conveyed via the VENDOR OPTS field.

#### 24.3.18.2.3 Steps 3 and 4.

If the client selects an address from a DHCP6 service, then it must complete the standard DHCP6 process by sending a REQUEST for the address back to the service and then waiting for an REPLY from the service.

#### 24.3.18.2.4 Step 5.

The client multicasts a REQUEST message to the Boot Server port 4011, it contains the following:

- A tag for client UNDI version.
- A tag for the client system architecture.
- A tag for PXE client, Vendor Class option, set to
  - “PXEClient:Arch:xxxxx:UNDI:yyyyMMdd”.

### 24.3. PXE Base Code Protocol
Fig. 24.1: IPv6-based PXE Boot

- PXE Client
- DHCP6/Proxy Service
- DHCP6 Solicit to 547: Contains "PXEClient" ext tags
- DHCP6 Advertise to 546: Contains PXE server ext tags + [Other DHCP6 option tags] + client address + BootFileURL (Boot Server address)
- DHCP6 Request to 547: Contains "PXEClient" ext tags + [Other DHCP6 option tags]
- DHCP6 Reply to 546
- Boot Service Request to port 4011: Contains "PXEClient" ext tags + [Other DHCP6 option tags]
- Boot Service Reply to client port: Contains PXE server ext tags + BootFileURL (Boot Server address and NBP file name + BootfilePara (NBP file size))
- TFTP ReadFile to 69 to request NBP file
- NBP file download to client port
24.3.18.2.5 Step 6.

The Boot Server unicasts a REPLY message back to the client on the client port. It contains the following:

- A tag for NBP file name.
- A tag for NBP file size if needed.

24.3.18.2.6 Step 7.

The client requests the NBP file using TFTP (port 69).

24.3.18.2.7 Step 8.

The NBP file, dependent on the client’s CPU architecture, is downloaded into client’s memory.

24.3.18.3 Proxy DHCP6

The netboot6 DHCP6 options may be supplied by the DHCP6 service or a Proxy DHCP6 service. This Proxy DHCP6 service may reside on the same server as the DHCP6 service, or it may be located on a separate server. A Proxy DHCP6 service on the same server as the DHCP6 service is illustrated in Figure 2. In this case, the Proxy DHCP6 service is listening to UDP port (4011), and communication with the Proxy DHCP6 service occurs after completing the standard DHCP6 process. Proxy DHCP6 uses port (4011) because it cannot share port (547) with the DHCP6 service. The netboot6 client knows how to interrogate the Proxy DHCP6 service because the ADVERTISE from the DHCP6 service contains a VendorClass option “PXEClient” tag without a BootFileURL option (including NBP file name). The client will not request option 16 (OPTION_VENDOR_CLASS) in ORO, but server must still reply with “PXEClient” in order to inform the client to start the Proxy DHCPv6 mode. The client will accept just the string “PXEClient” as sufficient, the server need not echo back the entire OPTION_VENDOR_CLASS.

The Figure below, IPv6-based PXE boot (DHCP6 and Proxy DHCP6 reside on the different server) illustrates the case of a Proxy DHCP6 service and the DHCP6 service on different servers. In this case, the Proxy DHCP6 service listens to UDP port (547) and responds in parallel with DHCP6 service.

24.4 PXE Base Code Callback Protocol

This protocol is a specific instance of the PXE Base Code Callback Protocol that is invoked when the PXE Base Code Protocol is about to transmit, has received, or is waiting to receive a packet. The PXE Base Code Callback Protocol must be on the same handle as the PXE Base Code Protocol.

24.4.1 EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL

Summary

Protocol that is invoked when the PXE Base Code Protocol is about to transmit, has received, or is waiting to receive a packet.

GUID

#define EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL_GUID "
{0x245DCA21,0xFB7B,0x11d3,"
 {0x8F,0x01,0x00,0xA0, 0xC9,0x69,0x72,0x3B}}
Fig. 24.2: Netboot6 (DHCP6 and ProxyDHCP6 reside on the same server)
Fig. 24.3: IPv6-based PXE boot (DHCP6 and ProxyDHCP6 reside on the different server)
#define EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL_REVISION \0x00010000

Protocol Interface Structure

typedef struct {
    UINT64 Revision;
    EFI_PXE_CALLBACK Callback;
} EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL;

Parameters

Revision
The revision of the EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL. All future revisions must be backwards compatible. If a future revision is not backwards compatible, it is not the same GUID.

Callback
Callback routine used by the PXE Base Code EFI_PXE_BASE_CODE_PROTOCOL.Dhcp(), EFI_PXE_BASE_CODE_PROTOCOL.Discover(), EFI_PXE_BASE_CODE_PROTOCOL.Mtftp(), EFI_PXE_BASE_CODE_PROTOCOL.UdpWrite(), and EFI_PXE_BASE_CODE_PROTOCOL.Arp() functions.

24.4.2 EFI_PXE_BASE_CODE_CALLBACK.Callback()

Summary
Callback function that is invoked when the PXE Base Code Protocol is about to transmit, has received, or is waiting to receive a packet.

Prototype

typedef
EFI_PXE_BASE_CODE_CALLBACK_STATUS
(*EFI_PXE_CALLBACK) (
    IN EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL *This,
    IN EFI_PXE_BASE_CODE_FUNCTION Function,
    IN BOOLEAN Received,
    IN UINT32 PacketLen,
    IN EFI_PXE_BASE_CODE_PACKET *Packet OPTIONAL
);

Parameters

This
    Pointer to the See EFI_PXE_BASE_CODE_PROTOCOL instance.

Function
    The PXE Base Code Protocol function that is waiting for an event.

Received
    TRUE if the callback is being invoked due to a receive event. FALSE if the callback is being invoked due to a transmit event.

PacketLen
    The length, in bytes, of Packet. This field will have a value of zero if this is a wait for receive event.
Packet

If Received is TRUE, a pointer to the packet that was just received; otherwise a pointer to the packet that is about to be transmitted. This field will be NULL if this is not a packet event.

Related Definitions

```c
typedef enum {
    EFI_PXE_BASE_CODE_CALLBACK_STATUS_FIRST,
    EFI_PXE_BASE_CODE_CALLBACK_STATUS_CONTINUE,
    EFI_PXE_BASE_CODE_CALLBACK_STATUS_ABORT,
    EFI_PXE_BASE_CODE_CALLBACK_STATUS_LAST,
} EFI_PXE_BASE_CODE_CALLBACK_STATUS;
```

```c
typedef enum {
    EFI_PXE_BASE_CODE_FUNCTION_FIRST,
    EFI_PXE_BASE_CODE_FUNCTION_DHCP,
    EFI_PXE_BASE_CODE_FUNCTION_DISCOVER,
    EFI_PXE_BASE_CODE_FUNCTION_MTFTP,
    EFI_PXE_BASE_CODE_FUNCTION_UDP_WRITE,
    EFI_PXE_BASE_CODE_FUNCTION_UDP_READ,
    EFI_PXE_BASE_CODE_FUNCTION_ARP,
    EFI_PXE_BASE_CODE_FUNCTION_IGMP,
    EFI_PXE_BASE_CODE_PXE_FUNCTION_LAST,
} EFI_PXE_BASE_CODE_FUNCTION;
```

Description

This function is invoked when the PXE Base Code Protocol is about to transmit, has received, or is waiting to receive a packet. Parameters Function and Received specify the type of event. Parameters PacketLen and Packet specify the packet that generated the event. If these fields are zero and NULL respectively, then this is a status update callback. If the operation specified by Function is to continue, then CALLBACK_STATUS_CONTINUE should be returned. If the operation specified by Function should be aborted, then CALLBACK_STATUS_ABORT should be returned. Due to the polling nature of UEFI device drivers, a callback function should not execute for more than 5 ms.

The `EFI_PXE_BASE_CODE_PROTOCOL.SetParameters()` function must be called after a Callback Protocol is installed to enable the use of callbacks.

24.5 Boot Integrity Services Protocol

This section defines the Boot Integrity Services (BIS) protocol, which is used to check a digital signature of a data block against a digital certificate for the purpose of an integrity and authorization check. BIS is primarily used by the Preboot Execution Environment (PXE) Base Code protocol See `EFI_PXE_BASE_CODE_PROTOCOL` to check downloaded network boot images before executing them. BIS is a UEFI Boot Service Driver, so its services are also available to applications written to this specification until the time of `EFI_BOOT_SERVICES.ExitBootServices()`. More information about BIS can be found in the Boot Integrity Services Application Programming Interface Version 1.0.

This section defines the Boot Integrity Services Protocol. This protocol is used to check a digital signature of a data block against a digital certificate for the purpose of an integrity and authorization check.
24.5.1 EFI_BIS_PROTOCOL

Summary

The EFI_BIS_PROTOCOL is used to check a digital signature of a data block against a digital certificate for the purpose of an integrity and authorization check.

GUID

```c
#define EFI_BIS_PROTOCOL_GUID \
{0xb64aab0,0x5429,0x11d4,\ 
 {0x98,0x16,0x00,0xa0,0xc9,0x1f,0xad,0xcf}}
```

Protocol Interface Structure

```c
typedef struct _EFI_BIS_PROTOCOL {
    EFI_BIS_INITIALIZE Initialize;
    EFI_BIS_SHUTDOWN Shutdown;
    EFI_BIS_FREE Free;
    EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_CERTIFICATE GetBootObjectAuthorizationCertificate;
    EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_CHECKFLAG GetBootObjectAuthorizationCheckFlag;
    EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_UPDATE_TOKEN GetBootObjectAuthorizationUpdateToken;
    EFI_BIS_GET_SIGNATURE_INFO GetSignatureInfo;
    EFI_BIS_UPDATE_BOOT_OBJECT_AUTHORIZATION UpdateBootObjectAuthorization;
    EFI_BIS_VERIFY_BOOT_OBJECT VerifyBootObject;
    EFI_BIS_VERIFY_OBJECT_WITH_CREDENTIAL VerifyObjectWithCredential;
} EFI_BIS_PROTOCOL;
```

Parameters

**Initialize**

Initializes an application instance of the EFI_BIS protocol, returning a handle for the application instance. Other functions in the EFI_BIS protocol require a valid application instance handle obtained from this function. See the EFI_BIS_PROTOCOL.Initialize() function description.

**Shutdown**

Ends the lifetime of an application instance of the EFI_BIS protocol, invalidating its application instance handle. The application instance handle may no longer be used in other functions in the EFI_BIS protocol. See the EFI_BIS_PROTOCOL.Shutdown() function description.

**Free**

Frees memory structures allocated and returned by other functions in the EFI_BIS protocol. See the EFI_BIS_PROTOCOL.Free() function description.

**GetBootObjectAuthorizationCertificate**

Retrieves the current digital certificate (if any) used by the EFI_BIS protocol as the source of authorization for verifying boot objects and altering configuration parameters. See the EFI_BIS_PROTOCOL.GetBootObjectAuthorizationCertificate() function description.

**GetBootObjectAuthorizationCheckFlag**

Retrieves the current setting of the authorization check flag that indicates whether or not authorization checks are required for boot objects. See the EFI_BIS_PROTOCOL.GetBootObjectAuthorizationCheckFlag() function description.
**GetBootObjectAuthorizationUpdateToken**

Retrieves an uninterpreted token whose value gets included and signed in a subsequent request to alter the configuration parameters, to protect against attempts to “replay” such a request. See the `EFI_BIS_PROTOCOL.GetBootObjectAuthorizationUpdateToken()` function description.

**GetSignatureInfo**

Retrieves information about the digital signature algorithms supported and the identity of the installed authorization certificate, if any. See the `EFI_BIS_PROTOCOL.GetSignatureInfo()` function description.

**UpdateBootObjectAuthorization**

Requests that the configuration parameters be altered by installing or removing an authorization certificate or changing the setting of the check flag. See the `EFI_BIS_PROTOCOL.UpdateBootObjectAuthorization()` function description.

**VerifyBootObject**

Verifies a boot object according to the supplied digital signature and the current authorization certificate and check flag setting. See the `EFI_BIS_PROTOCOL.VerifyBootObject()` function description.

**VerifyObjectWithCredential**

Verifies a data object according to a supplied digital signature and a supplied digital certificate. See the `EFI_BIS_PROTOCOL.VerifyObjectWithCredential()` function description.

**Description**

The `EFI_BIS_PROTOCOL` provides a set of functions as defined in this section. There is no physical device associated with these functions, however, in the context of UEFI every protocol operates on a device. Accordingly, BIS installs and operates on a single abstract device that has only a software representation.

### 24.5.2 EFI_BIS_PROTOCOL.Initialize()

**Summary**

Initializes the BIS service, checking that it is compatible with the version requested by the caller. After this call, other BIS functions may be invoked.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_BIS_INITIALIZE)(
    IN EFI_BIS_PROTOCOL *This,
    OUT BIS_APPLICATION_HANDLE *AppHandle,
    IN OUT EFI_BIS_VERSION *InterfaceVersion,
    IN EFI_BIS_DATA *TargetAddress
);
```

**Parameters**

**This**

A pointer to the `EFI_BIS_PROTOCOL` object. The protocol implementation may rely on the actual pointer value and object location, so the caller must not copy the object to a new location.

**AppHandle**

The function writes the new BIS_APPLICATION_HANDLE if successful, otherwise it writes `NULL`. The caller must eventually destroy this handle by calling `EFI_BIS_PROTOCOL.Shutdown()`.

**InterfaceVersion**

On input, the caller supplies the major version number of the interface version desired. The minor version number
supplied on input is ignored since interface compatibility is determined solely by the major version number. On output, both the major and minor version numbers are updated with the major and minor version numbers of the interface (and underlying implementation). This update is done whether or not the initialization was successful. Type \textit{EFI\_BIS\_VERSION} is defined in “Related Definitions” below.

**TargetAddress**

Indicates a network or device address of the BIS platform to connect to. Local-platform BIS implementations require that the caller sets \textit{TargetAddress\_Data} to NULL, but otherwise ignores this parameter. BIS implementations that redirect calls to an agent at a remote address must define their own format and interpretation of this parameter outside the scope of this document. For all implementations, if the \textit{TargetAddress} is an unsupported value, the function fails with the error \textit{EFI\_UNSUPPORTED}. Type \textit{EFI\_BIS\_DATA} is defined in “Related Definitions” below.

**Related Definitions**

```c
typedef VOID *BIS\_APPLICATION\_HANDLE;
```

This type is an opaque handle representing an initialized instance of the BIS interface. A \textit{BIS\_APPLICATION\_HANDLE} value is returned by the \textit{Initialize()} function as an “out” parameter. Other BIS functions take a \textit{BIS\_APPLICATION\_HANDLE} as an “in” parameter to identify the BIS instance.

```c
typedef struct \_EFI\_BIS\_VERSION {
    UINT32 Major;
    UINT32 Minor;
} EFI\_BIS\_VERSION;
```

**Major**

This describes the major BIS version number. The major version number defines version compatibility. That is, when a new version of the BIS interface is created with new capabilities that are not available in the previous interface version, the major version number is increased.

**Minor**

This describes a minor BIS version number. This version number is increased whenever a new BIS implementation is built that is fully interface compatible with the previous BIS implementation. This number may be reset when the major version number is increased.

This type represents a version number of the BIS interface. This is used as an “in out” parameter of the \textit{Initialize()} function for a simple form of negotiation of the BIS interface version between the caller and the BIS implementation.

```c
#define BIS\_CURRENT\_VERSION\_MAJOR \_BIS\_VERSION\_1
#define BIS\_VERSION\_1 1
```

These C preprocessor macros supply values for the major version number of an \textit{EFI\_BIS\_VERSION}. At the time of initialization, a caller supplies a value to request a BIS interface version. On return, the (IN OUT) parameter is overwritten with the actual version of the interface.
typedef struct _EFI_BIS_DATA {
    UINT32 Length;
    UINT8 *Data;
} EFI_BIS_DATA;

Length
The length of the data buffer in bytes.

Data
A pointer to the raw data buffer.

This type defines a structure that describes a buffer. BIS uses this type to pass back and forth most large objects such as digital certificates, strings, etc. Several of the BIS functions allocate a EFI_BIS_DATA* and return it as an “out” parameter. The caller must eventually free any allocated EFI_BIS_DATA* using the EFI_BIS_PROTOCOL.Free() function.

Description
This function must be the first BIS function invoked by an application. It passes back a BIS_APPLICATION_HANDLE value that must be used in subsequent BIS functions. The handle must be eventually destroyed by a call to the EFI_BIS_PROTOCOL.Shutdown() function, thus ending that handle’s lifetime. After the handle is destroyed, BIS functions may no longer be called with that handle value. Thus all other BIS functions may only be called between a pair of EFI_BIS_PROTOCOL.Initialize() and Shutdown() functions.

There is no penalty for calling Initialize() multiple times. Each call passes back a distinct handle value. Each distinct handle must be destroyed by a distinct call to Shutdown(). The lifetimes of handles created and destroyed with these functions may be overlapped in any way.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_INCOMPATIBLE_VERSION</td>
<td>The InterfaceVersion.Major requested by the caller was not compatible with the interface version of the implementation. The InterfaceVersion.Major has been updated with the current interface version.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This is a local-platform implementation and TargetAddress.Data was not NULL, or TargetAddress.Data was any other value that was not supported by the implementation.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The function failed due to lack of memory or other resources.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The function encountered an unexpected internal failure while initializing a cryptographic software module, or No cryptographic software module with compatible version was found, or A resource limitation was encountered while using a cryptographic software module.</td>
</tr>
</tbody>
</table>

continues on next page
24.5.3 EFI_BIS_PROTOCOL.Shutdown()

Summary

Shuts down an application’s instance of the BIS service, invalidating the application handle. After this call, other BIS functions may no longer be invoked using the application handle value.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BIS_SHUTDOWN)(
    IN BIS_APPLICATION_HANDLE AppHandle
);
```

Parameters

**AppHandle**

An opaque handle that identifies the caller’s instance of initialization of the BIS service. Type BIS_APPLICATION_HANDLE is defined in the EFI_BIS_PROTOCOL.Initialize() function description.

Description

This function shuts down an application’s instance of the BIS service, invalidating the application handle. After this call, other BIS functions may no longer be invoked using the application handle value.

This function must be paired with a preceding successful call to the Initialize() function. The lifetime of an application handle extends from the time the handle was returned from Initialize() until the time the handle is passed to Shutdown(). If there are other remaining handles whose lifetime is still active, they may still be used in calling BIS functions.

The caller must free all memory resources associated with this AppHandle that were allocated and returned from other BIS functions before calling Shutdown(). Memory resources are freed using the EFI_BIS_PROTOCOL.Free() function. Failure to free such memory resources is a caller error, however, this function does not return an error code under this circumstance. Further attempts to access the outstanding memory resources cause unspecified results.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The AppHandle parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.</td>
</tr>
</tbody>
</table>
**Table 24.31 – continued from previous page**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The function encountered an unexpected internal error while returning</td>
</tr>
<tr>
<td></td>
<td>resources associated with a cryptographic software module, or</td>
</tr>
<tr>
<td></td>
<td>The function encountered an internal error while trying to shut down a</td>
</tr>
<tr>
<td></td>
<td>cryptographic software module.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The function failed due to lack of memory or other resources.</td>
</tr>
</tbody>
</table>

### 24.5.4 EFI_BIS_PROTOCOL.Free()

**Summary**

Frees memory structures allocated and returned by other functions in the **EFI_BIS** protocol.

**Prototype**

```c
typedef EFI_STATUS (EFIAPPI *EFI_BIS_FREE)(
    IN BIS_APPLICATION_HANDLE AppHandle,
    IN EFI_BIS_DATA *ToFree
);
```

**Parameters**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>AppHandle</td>
<td>An opaque handle that identifies the caller’s instance of initialization of the BIS service. Type BIS_APPLICATION_HANDLE is defined in the <strong>EFI_BIS_PROTOCOL.Initialize()</strong> function description.</td>
</tr>
<tr>
<td>ToFree</td>
<td>An <strong>EFI_BIS_DATA</strong> and associated memory block to be freed. This <strong>EFI_BIS_DATA</strong> must have been allocated by one of the other BIS functions. Type <strong>EFI_BIS_DATA</strong> is defined in the <strong>Initialize()</strong> function description.</td>
</tr>
</tbody>
</table>

**Description**

This function deallocates an **EFI_BIS_DATA** and associated memory allocated by one of the other BIS functions. Callers of other BIS functions that allocate memory in the form of an **EFI_BIS_DATA** must eventually call this function to deallocate the memory before calling the **EFI_BIS_PROTOCOL.Shutdown()** function for the application handle under which the memory was allocated. Failure to do so causes unspecified results, and the continued correct operation of the BIS service cannot be guaranteed.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The <strong>AppHandle</strong> parameter is not or is no longer a valid application instance handle associated with the <strong>EFI_BIS</strong> protocol.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <strong>ToFree</strong> parameter is not or is no longer a memory resource associated with this <strong>AppHandle</strong>.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The function failed due to lack of memory or other resources.</td>
</tr>
</tbody>
</table>
24.5.5 EFI_BIS_PROTOCOL.GetBootObjectAuthorizationCertificate()

Summary
Retrieves the certificate that has been configured as the identity of the organization designated as the source of authorization for signatures of boot objects.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_CERTIFICATE) (IN BIS_APPLICATION_HANDLE AppHandle, OUT EFI_BIS_DATA **Certificate);

Parameters

AppHandle
An opaque handle that identifies the caller’s instance of initialization of the BIS service. Type BIS_APPLICATION_HANDLE is defined in the EFI_BIS_PROTOCOL.Initialize() function description.

Certificate
The function writes an allocated EFI_BIS_DATA* containing the Boot Object Authorization Certificate object. The caller must eventually free the memory allocated by this function using the function EFI_BIS_PROTOCOL.Free(). Type EFI_BIS_DATA is defined in the Initialize() function description.

Description
This function retrieves the certificate that has been configured as the identity of the organization designated as the source of authorization for signatures of boot objects.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The AppHandle parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>There is no Boot Object Authorization Certificate currently installed.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The function failed due to lack of memory or other resources.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The Certificate parameter supplied by the caller is NULL or an invalid memory reference.</td>
</tr>
</tbody>
</table>

24.5.6 EFI_BIS_PROTOCOL.GetBootObjectAuthorizationCheckFlag()

Summary
Retrieves the current status of the Boot Authorization Check Flag.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_CHECKFLAG) (IN BIS_APPLICATION_HANDLE AppHandle, (continues on next page)
OUT BOOLEAN *CheckIsRequired
);

Parameters

AppHandle

An opaque handle that identifies the caller’s instance of initialization of the BIS service. Type BIS_APPLICATION_HANDLE is defined in the EFI_BIS_PROTOCOL.Initialize() function description.

CheckIsRequired

The function writes the value TRUE if a Boot Authorization Check is currently required on this platform, otherwise the function writes FALSE.

Description

This function retrieves the current status of the Boot Authorization Check Flag (in other words, whether or not a Boot Authorization Check is currently required on this platform).

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The AppHandle parameter is not or is no longer a valid application instance handle associated with the EBI_BIS protocol.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The function failed due to lack of memory or other resources.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The CheckIsRequired parameter supplied by the caller is NULL or an invalid memory reference.</td>
</tr>
</tbody>
</table>

24.5.7 EFI_BIS_PROTOCOL.GetBootObjectAuthorizationUpdateToken()

Summary

Retrieves a unique token value to be included in the request credential for the next update of any parameter in the Boot Object Authorization set (Boot Object Authorization Certificate and Boot Authorization Check Flag).

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_BIS_GET_BOOT_OBJECT_AUTHORIZATION_UPDATE_TOKEN)(
    IN BIS_APPLICATION_HANDLE AppHandle,
    OUT EFI_BIS_DATA **UpdateToken
);
```

Parameters

AppHandle

An opaque handle that identifies the caller’s instance of initialization of the BIS service. Type BIS_APPLICATION_HANDLE is defined in the EFI_BIS_PROTOCOL.Initialize() function description.

UpdateToken

The function writes an allocated EFI_BIS_DATA* containing the new unique update token value. The caller must eventually free the memory allocated by this function using the function EFI_BIS_PROTOCOL.Free(). Type EFI_BIS_DATA is defined in the Initialize() function description.

Description
This function retrieves a unique token value to be included in the request credential for the next update of any parameter in the Boot Object Authorization set (Boot Object Authorization Certificate and Boot Authorization Check Flag). The token value is unique to this platform, parameter set, and instance of parameter values. In particular, the token changes to a new unique value whenever any parameter in this set is changed.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The <code>AppHandle</code> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The function failed due to lack of memory or other resources.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The function encountered an unexpected internal error in a cryptographic software module.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>UpdateToken</code> parameter supplied by the caller is <code>NULL</code> or an invalid memory reference.</td>
</tr>
</tbody>
</table>

### 24.5.8 EFI_BIS_PROTOCOL.GetSignatureInfo()

#### Summary

Retrieves a list of digital certificate identifier, digital signature algorithm, hash algorithm, and key-length combinations that the platform supports.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BIS_GET_SIGNATURE_INFO)(
    IN BIS_APPLICATION_HANDLE AppHandle,
    OUT EFI_BIS_DATA **SignatureInfo
);
```

#### Parameters

- **AppHandle**
  
  An opaque handle that identifies the caller’s instance of initialization of the BIS service. Type `BIS_APPLICATION_HANDLE` is defined in the `EFI_BIS_PROTOCOL.Initialize()` function description.

- **SignatureInfo**
  
  The function writes an allocated `EFI_BIS_DATA*` containing the array of `EFI_BIS_SIGNATURE_INFO` structures representing the supported digital certificate identifier, algorithm, and key length combinations. The caller must eventually free the memory allocated by this function using the function `EFI_BIS_PROTOCOL.Free()` . Type `EFI_BIS_DATA` is defined in the `Initialize()` function description. Type `EFI_BIS_SIGNATURE_INFO` is defined in “Related Definitions” below.

#### Related Definitions

```c
#include "Efi.h"

typedef struct __EFI_BIS_SIGNATURE_INFO {
    BIS_CERT_ID CertificateID;
    BIS_ALG_ID AlgorithmID;
    UINT16 KeyLength;
} EFI_BIS_SIGNATURE_INFO;
```
CertificateID
A shortened value identifying the platform’s currently configured Boot Object Authorization Certificate, if one is currently configured. The shortened value is derived from the certificate as defined in the Related Definition for BIS_CERT_ID below. If there is no certificate currently configured, the value is one of the reserved BIS_CERT_ID_XXX values defined below. Type BIS_CERT_ID and its predefined reserved values are defined in “Related Definitions” below.

AlgorithmID
A predefined constant representing a particular digital signature algorithm. Often this represents a combination of hash algorithm and encryption algorithm, however, it may also represent a standalone digital signature algorithm. Type BIS_ALG_ID and its permitted values are defined in “Related Definitions” below.

KeyLength
The length of the public key, in bits, supported by this digital signature algorithm.

This type defines a digital certificate, digital signature algorithm, and key-length combination that may be supported by the BIS implementation. This type is returned by GetSignatureInfo() to describe the combination(s) supported by the implementation.

```c
//**************************************************
// BIS_GET_SIGINFO_COUNT macro
// Tells how many EFI_BIS_SIGNATURE_INFO elements are contained
// in a EFI_BIS_DATA struct pointed to by the provided
// EFI_BIS_DATA*.  
//**************************************************
#define BIS_GET_SIGINFO_COUNT(BisDataPtr) \  
((BisDataPtr)->Length/sizeof(EFI_BIS_SIGNATURE_INFO))
```

BisDataPtr
Supplies the pointer to the target EFI_BIS_DATA structure.

(return value)
The number of EFI_BIS_SIGNATURE_INFO elements contained in the array.

This macro computes how many EFI_BIS_SIGNATURE_INFO elements are contained in an EFI_BIS_DATA structure returned from GetSignatureInfo(). The number returned is the count of items in the list of supported digital certificate, digital signature algorithm, and key-length combinations.

```c
//**************************************************
// BIS_GET_SIGINFO_ARRAY macro
// Produces a EFI_BIS_SIGNATURE_INFO* from a given
// EFI_BIS_DATA*.  
//**************************************************
#define BIS_GET_SIGINFO_ARRAY(BisDataPtr) \  
((EFI_BIS_SIGNATURE_INFO*)(BisDataPtr)->Data)
```

BisDataPtr
Supplies the pointer to the target EFI_BIS_DATA structure.

(return value)
The pointer to the EFI_BIS_SIGNATURE_INFO array, cast as an EFI_BIS_SIGNATURE_INFO*.

This macro returns a pointer to the EFI_BIS_SIGNATURE_INFO array contained in an EFI_BIS_DATA structure returned from GetSignatureInfo() representing the list of supported digital certificate, digital signature algorithm, and key-length combinations.
typedef UINT32 BIS_CERT_ID;

This type represents a shortened value that identifies the platform’s currently configured Boot Object Authorization Certificate. The value is the first four bytes, in “little-endian” order, of the SHA-1 hash of the certificate, except that the most-significant bits of the second and third bytes are reserved, and must be set to zero regardless of the outcome of the hash function. This type is included in the array of values returned from the GetSignatureInfo() function to indicate the required source of a signature for a boot object or a configuration update request. There are a few predefined reserved values with special meanings as described below.

#define BIS_CERT_ID_DSA BIS_ALG_DSA // CSSM_ALGID_DSA
#define BIS_CERT_ID_RSA_MD5 BIS_ALG_RSA_MD5 // CSSM_ALGID_MD5_WITH_RSA

These C preprocessor symbols provide values for the BIS_CERT_ID type. These values are used when the platform has no configured Boot Object Authorization Certificate. They indicate the signature algorithm that is supported by the platform. Users must be careful to avoid constructing Boot Object Authorization Certificates that transform to BIS_CERT_ID values that collide with these predefined values or with the BIS_CERT_ID values of other Boot Object Authorization Certificates they use.

#define BIS_CERT_ID_MASK (0xFF7F7FFF)

This C preprocessor symbol may be used as a bit-wise “AND” value to transform the first four bytes (in little-endian order) of a SHA-1 hash of a certificate into a certificate ID with the “reserved” bits properly set to zero.

typedef UINT16 BIS_ALG_ID;

This type represents a digital signature algorithm. A digital signature algorithm is often composed of a particular combination of secure hash algorithm and encryption algorithm. This type also allows for digital signature algorithms that cannot be decomposed. Predefined values for this type are as defined below.

#define BIS_ALG_ID predefined values
#define AlgorithmID. The exact numeric values come from “Common Data Security Architecture (CDSA) Specification.”

(continues on next page)
These values represent the two digital signature algorithms predefined for BIS. Each implementation of BIS must support at least one of these digital signature algorithms. Values for the digital signature algorithms are chosen by an industry group known as The Open Group. Developers planning to support additional digital signature algorithms or define new digital signature algorithms should refer to The Open Group for interoperable values to use.

**Description**

This function retrieves a list of digital certificate identifier, digital signature algorithm, hash algorithm, and key-length combinations that the platform supports. The list is an array of (certificate id, algorithm id, key length) triples, where the certificate id is derived from the platform’s Boot Object Authorization Certificate as described in the Related Definition for `BIS_CERT_ID` above, the algorithm id represents the combination of signature algorithm and hash algorithm, and the key length is expressed in bits. The number of array elements can be computed using the `Length` field of the retrieved `EFI_BIS_DATA`.

The retrieved list is in order of preference. A digital signature algorithm for which the platform has a currently configured Boot Object Authorization Certificate is preferred over any digital signature algorithm for which there is not a currently configured Boot Object Authorization Certificate. Thus the first element in the list has a `CertificateID` representing a Boot Object Authorization Certificate if the platform has one configured. Otherwise the `CertificateID` of the first element in the list is one of the reserved values representing a digital signature algorithm.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The <code>AppHandle</code> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The function failed due to lack of memory or other resources.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The function encountered an unexpected internal error in a cryptographic software module, or The function encountered an unexpected internal consistency check failure (possible corruption of stored Boot Object Authorization Certificate).</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>SignatureInfo</code> parameter supplied by the caller is <code>NULL</code> or an invalid memory reference.</td>
</tr>
</tbody>
</table>

### 24.5.9 EFI_BIS_PROTOCOL.UpdateBootObjectAuthorization()

**Summary**

Updates one of the configurable parameters of the Boot Object Authorization set (Boot Object Authorization Certificate or Boot Authorization Check Flag).

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_BIS_UPDATE_BOOT_OBJECT_AUTHORIZATION)(
    IN BIS_APPLICATION_HANDLE AppHandle, 
    IN EFI_BIS_DATA *RequestCredential,
);
```

(continues on next page)
Parameters

AppHandle
An opaque handle that identifies the caller’s instance of initialization of the BIS service. Type BIS_APPLICATION_HANDLE is defined in the EFI_BIS_PROTOCOL.Initialize() function description.

RequestCredential
This is a Signed Manifest with embedded attributes that carry the details of the requested update. The required syntax of the Signed Manifest is described in the Related Definition for Manifest Syntax below. The key used to sign the request credential must be the private key corresponding to the public key in the platform’s configured Boot Object Authorization Certificate. Authority to update parameters in the Boot Object Authorization set cannot be delegated.

If there is no Boot Object Authorization Certificate, the request credential may be signed with any private key. In this case, this function interacts with the user in a platform-specific way to determine whether the operation should succeed. Type EFI_BIS_DATA is defined in the Initialize() function description.

NewUpdateToken
The function writes an allocated EFI_BIS_DATA* containing the new unique update token value. The caller must eventually free the memory allocated by this function using the function EFI_BIS_PROTOCOL.Free(). Type EFI_BIS_DATA is defined in the Initialize() function description.

Related Definitions

//**********************************************************
// Manifest Syntax
//**********************************************************

The Signed Manifest consists of three parts grouped together into an Electronic Shrink Wrap archive as described in [SM spec]: a manifest file, a signer’s information file, and a signature block file. These three parts, along with examples are described in the following sections. In these examples, text in parentheses is a description of the text that would appear in the signed manifest. Text outside of parentheses must appear exactly as shown. Also note that manifest files and signer’s information files must conform to a 72-byte line-length limit. Continuation lines (lines beginning with a single “space” character) are used for lines longer than 72 bytes. The examples given here follow this rule for continuation lines.

Note that the manifest file and signer’s information file parts of a Signed Manifest are ASCII text files. In cases where these files contain a base-64 encoded string, the string is an ASCII string before base-64 encoding.

//**********************************************************
// Manifest File Example
//**********************************************************

The manifest file must include a section referring to a memory-type data object with the reserved name as shown in the example below. This data object is a zero-length object whose sole purpose in the manifest is to serve as a named collection point for the attributes that carry the details of the requested update. The attributes are also contained in the manifest file. An example manifest file is shown below.

Manifest-Version: 2.0
ManifestPersistentId: (base-64 representation of a unique GUID)
Name: memory:UpdateRequestParameters
Digest-Algorithms: SHA-1
SHA-1-Digest: (base-64 representation of a SHA-1 digest of zero-length buffer)
X-Intel-BIS-ParameterSet: (base-64 representation of BootObjectAuthorizationSetGUID)
X-Intel-BIS-ParameterSetToken: (base-64 representation of the current update token)
X-Intel-BIS-ParameterId: (base-64 representation of "BootObjectAuthorizationCertificate" or "BootAuthorizationCheckFlag")
X-Intel-BIS-ParameterValue: (base-64 representation of certificate or single-byte boolean flag)

A line-by-line description of this manifest file is as follows.

Manifest-Version: 2.0

This is a standard header line that all signed manifests have. It must appear exactly as shown.

ManifestPersistentId: (base-64 representation of a unique GUID)

The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every manifest file created. The Win32 function UuidCreate() can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].

Name: memory:UpdateRequestParameters

This identifies the manifest section that carries a dummy zero-length data object serving as the collection point for the attribute values appearing later in this manifest section (lines prefixed with "X-Intel-BIS-" ). The string "memory:UpdateRequestParameters" must appear exactly as shown.

Digest-Algorithms: SHA-1

This enumerates the digest algorithms for which integrity data is included for the data object. These are required even though the data object is zero-length. For systems with DSA signing, SHA-1 hash, and 1024-bit key length, the digest algorithm must be "SHA-1." For systems with RSA signing, MD5 hash, and 512-bit key length, the digest algorithm must be "MD5." Multiple algorithms can be specified as a whitespace-separated list. For every digest algorithm XXX listed, there must also be a corresponding XXX-Digest line.

SHA-1-Digest: (base-64 representation of a SHA-1 digest of zero-length buffer)

Gives the corresponding digest value for the dummy zero-length data object. The value is base-64 encoded. Note that for both MD5 and SHA-1, the digest value for a zero-length data object is not zero.

X-Intel-BIS-ParameterSet: (base-64 representation of BootObjectAuthorizationSetGUID)

A named attribute value that distinguishes updates of BIS parameters from updates of other parameters. The left-hand attribute-name keyword must appear exactly as shown. The GUID value for the right-hand side is always the same, and can be found under the preprocessor symbol BOOT_OBJECT_AUTHORIZATION_PARMSET_GUIDVALUE. The representation inserted into the manifest is base-64 encoded.

Note the "X-Intel-BIS-" prefix on this and the following attributes. The "X-" part of the prefix was chosen to avoid collisions with future reserved keywords defined by future versions of the signed manifest specification. The "Intel-BIS-" part of the prefix was chosen to avoid collisions with other user-defined attribute names within the user-defined attribute name space.
### X-Intel-BIS-ParameterSetToken: (base-64 representation of the current update token)

A named attribute value that makes this update of BIS parameters different from any other on the same target platform. The left-hand attribute-name keyword must appear exactly as shown. The value for the right-hand side is generally different for each update-request manifest generated. The value to be base-64 encoded is retrieved through the functions `EFI_BIS_PROTOCOL.GetBootObjectAuthorizationUpdateToken()` or `EFI_BIS_PROTOCOL.UpdateBootObjectAuthorization()`.

### X-Intel-BIS-ParameterId: (base-64 representation of "BootObjectAuthorizationCertificate" or "BootAuthorizationCheckFlag")

A named attribute value that indicates which BIS parameter is to be updated. The left-hand attribute-name keyword must appear exactly as shown. The value for the right-hand side is the base-64 encoded representation of one of the two strings shown.

### X-Intel-BIS-ParameterValue: (base-64 representation of certificate or single-byte boolean flag)

A named attribute value that indicates the new value to be set for the indicated parameter. The left-hand attribute-name keyword must appear exactly as shown. The value for the right-hand side is the appropriate base-64 encoded new value to be set. In the case of the Boot Object Authorization Certificate, the value is the new digital certificate raw data. A zero-length value removes the certificate altogether. In the case of the Boot Authorization Check Flag, the value is a single-byte Boolean value, where a nonzero value “turns on” the check and a zero value “turns off” the check.

```
//**********************************************************
// Signer's Information File Example
//**********************************************************
```

The signer’s information file must include a section whose name matches the reserved data object section name of the section in the Manifest file. This section in the signer’s information file carries the integrity data for the attributes in the corresponding section in the manifest file. An example signer’s information file is shown below.

```plaintext
Signature-Version: 2.0
SignerInformationPersistentId: (base-64 representation of a unique GUID)
SignerInformationName: BIS_UpdateManifestSignerInfoName
Name: memory:UpdateRequestParameters
Digest-Algorithms: SHA-1
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the corresponding manifest section)
```

A line-by-line description of this signer’s information file is as follows.

```
Signature-Version: 2.0
```

This is a standard header line that all signed manifests have. It must appear exactly as shown.

```
SignerInformationPersistentId: (base-64 representation of a unique GUID)
```

The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every signer’s information file created. The Win32 function UuidCreate() can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].
SignerInformationName: BIS_UpdateManifestSignerInfoName

The left-hand string must appear exactly as shown. The right-hand string must appear exactly as shown.

Name: memory:UpdateRequestParameters

This identifies the section in the signer’s information file corresponding to the section with the same name in the manifest file described earlier. The string “memory:UpdateRequestParameters” must appear exactly as shown.

Digest-Algorithms: SHA-1

This enumerates the digest algorithms for which integrity data is included for the corresponding manifest section. Strings identifying digest algorithms are the same as in the manifest file. The digest algorithms specified here must match those specified in the manifest file. For every digest algorithm XXX listed, there must also be a corresponding XXX-Digest line.

SHA-1-Digest: (base-64 representation of a SHA-1 digest of the corresponding manifest section)

Gives the corresponding digest value for the corresponding manifest section. The value is base-64 encoded. Note that for the purpose of computing the hash of the manifest section, the manifest section starts at the beginning of the opening "Name:" keyword and continues up to, but not including, the next section’s "Name:" keyword or the end-of-file. Thus the hash includes the blank line(s) at the end of a section and any newline(s) preceding the next "Name:" keyword or end-of-file.

//**********************************************************
// Signature Block File Example
//**********************************************************
A signature block file is a raw binary file (not base-64 encoded) that is a PKCS#7 defined format signature block. The signature block covers exactly the contents of the signer’s information file. There must be a correspondence between the name of the signer’s information file and the signature block file. The base name matches, and the three-character extension is modified to reflect the signature algorithm used according to the following rules:

• DSA signature algorithm (which uses SHA-1 hash): extension is DSA.
• RSA signature algorithm with MD5 hash: extension is RSA.

So for example with a signer’s information file name of “myinfo.SF,” the corresponding DSA signature block file name would be “myinfo.DSA.”

The format of a signature block file is defined in [PKCS].

//**********************************************************
// "X-Intel-BIS-ParameterSet" Attribute value
// Binary Value of "X-Intel-BIS-ParameterSet" Attribute.
// (Value is Base-64 encoded in actual signed manifest).
//**********************************************************

#define BOOT_OBJECT_AUTHORIZATION_PARMSET_GUID \
{0xedd35e31,0x7b9,0x11d2,{0x83,0xa3,0x0,0xa0,0xc9,0x1f,0xad,0xcf}}

This preprocessor symbol gives the value for an attribute inserted in signed manifests to distinguish updates of BIS parameters from updates of other parameters. The representation inserted into the manifest is base-64 encoded.

**Description**
This function updates one of the configurable parameters of the Boot Object Authorization set (Boot Object Authorization Certificate or Boot Authorization Check Flag). It passes back a new unique update token that must be included in the request credential for the next update of any parameter in the Boot Object Authorization set. The token value is unique to this platform, parameter set, and instance of parameter values. In particular, the token changes to a new unique value whenever any parameter in this set is changed.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The <code>AppHandle</code> parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The function failed due to lack of memory or other resources.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The function encountered an unexpected internal error in a cryptographic software module.</td>
</tr>
</tbody>
</table>

continues on next page
The signed manifest supplied as the `RequestCredential` parameter was invalid (could not be parsed), or

The signed manifest supplied as the `RequestCredential` parameter failed to verify using the installed Boot Object Authorization Certificate or the signer’s Certificate in `RequestCredential`, or Platform-specific authorization failed, or The signed manifest supplied as the `RequestCredential` parameter did not include the X-Intel-BIS-ParameterSet attribute value, or

The X-Intel-BIS-ParameterSet attribute value supplied did not match the required GUID value, or

The signed manifest supplied as the `RequestCredential` parameter did not include the X-Intel-BIS-ParameterSetToken attribute value, or

The X-Intel-BIS-ParameterSetToken attribute value supplied did not match the platform’s current update-token value, or

The signed manifest supplied as the `RequestCredential` parameter did not include the X-Intel-BIS-ParameterId attribute value, or

The X-Intel-BIS-ParameterId attribute value supplied did not match one of the permitted values, or

The signed manifest supplied as the `RequestCredential` parameter did not include the X-Intel-BIS-ParameterValue attribute value, or

Any other required attribute value was missing, or

The new certificate supplied was too big to store, or

The new certificate supplied was invalid (could not be parsed), or

The new certificate supplied had an unsupported combination of key algorithm and key length, or

The new check flag value supplied is the wrong length (1 byte), or

The signed manifest supplied as the `RequestCredential` parameter did not include a signer certificate, or

The signed manifest supplied as the `RequestCredential` parameter did not include the manifest section named "memory:UpdateRequestParameters," or

The signed manifest supplied as the `RequestCredential` parameter had a signing certificate with an unsupported public-key algorithm, or

The manifest section named “memory:UpdateRequestParameters” did not include a digest with a digest algorithm corresponding to the signing certificate’s public key algorithm, or

The zero-length data object referenced by the manifest section named “memory:UpdateRequestParameters” did not verify with the digest supplied in that manifest section, or

The signed manifest supplied as the `RequestCredential` parameter did not include a signer’s information file with the `SignerInformationName` identifying attribute value "* BIS_UpdateManifestSignerInfoName,*" or

There were no signers associated with the identified signer’s information file, or

There was more than one signer associated with the identified signer’s information file, or

Any other unspecified security violation occurred.
Table 24.37 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected internal error occurred while analyzing the new certificate’s key algorithm, or</td>
</tr>
<tr>
<td></td>
<td>An unexpected internal error occurred while attempting to retrieve the public key algorithm of the manifest’s signer’s certificate, or</td>
</tr>
<tr>
<td></td>
<td>An unexpected internal error occurred in a cryptographic software module.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The RequestCredential parameter supplied by the caller is NULL or an invalid memory reference, or</td>
</tr>
<tr>
<td></td>
<td>The RequestCredential.Data parameter supplied by the caller is NULL or an invalid memory reference, or</td>
</tr>
<tr>
<td></td>
<td>The NewUpdateToken parameter supplied by the caller is NULL or an invalid memory reference.</td>
</tr>
</tbody>
</table>

### 24.5.10 EFI_BIS_PROTOCOL.VerifyBootObject()

**Summary**

Verifies the integrity and authorization of the indicated data object according to the indicated credentials.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_BIS_VERIFY_BOOT_OBJECT)(
    IN BIS_APPLICATION_HANDLE AppHandle,
    IN EFI_BIS_DATA *Credentials,
    IN EFI_BIS_DATA *DataObject,
    OUT BOOLEAN *IsVerified
);
```

**Parameters**

- **AppHandle**
  
  An opaque handle that identifies the caller’s instance of initialization of the BIS service. Type BIS_APPLICATION_HANDLE is defined in the `EFI_BIS_PROTOCOL.Initialize()` function description.

- **Credentials**
  
  A Signed Manifest containing verification information for the indicated data object. The Manifest signature itself must meet the requirements described below. This parameter is optional if a Boot Authorization Check is currently not required on this platform (Credentials.Data may be NULL), otherwise this parameter is required. The required syntax of the Signed Manifest is described in the Related Definition for Manifest Syntax below. Type EFI_BIS_DATA is defined in the `Initialize()` function description.

- **DataObject**
  
  An in-memory copy of the raw data object to be verified. Type EFI_BIS_DATA is defined in the `Initialize()` function description.

- **IsVerified**
  
  The function writes `TRUE` if the verification succeeded, otherwise `FALSE`.

**Related Definitions**
The Signed Manifest consists of three parts grouped together into an Electronic Shrink Wrap archive as described in [SM spec]: a manifest file, a signer’s information file, and a signature block file. These three parts along with examples are described in the following sections. In these examples, text in parentheses is a description of the text that would appear in the signed manifest. Text outside of parentheses must appear exactly as shown. Also note that manifest files and signer’s information files must conform to a 72-byte line-length limit. Continuation lines (lines beginning with a single “space” character) are used for lines longer than 72 bytes. The examples given here follow this rule for continuation lines.

Note that the manifest file and signer’s information file parts of a Signed Manifest are ASCII text files. In cases where these files contain a base-64 encoded string, the string is an ASCII string before base-64 encoding.

The manifest file must include a section referring to a memory-type data object with the reserved name as shown in the example below. This data object is the Boot Object to be verified. An example manifest file is shown below.

```
Manifest-Version: 2.0
ManifestPersistentId: (base-64 representation of a unique GUID)
Name: memory:BootObject
Digest-Algorithms: SHA-1
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the boot object)
```

A line-by-line description of this manifest file is as follows.

```
Manifest-Version: 2.0

This is a standard header line that all signed manifests have. It must appear exactly as shown.

ManifestPersistentId: (base-64 representation of a unique GUID)

The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every manifest file created. The Win32 function UuidCreate() can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].

Name: memory:BootObject

This identifies the section that carries the integrity data for the Boot Object. The string “memory:BootObject” must appear exactly as shown. Note that the Boot Object cannot be found directly from this manifest. A caller verifying the Boot Object integrity must load the Boot Object into memory and specify its memory location explicitly to this verification function through the DataObject parameter.

Digest-Algorithms: SHA-1

This enumerates the digest algorithms for which integrity data is included for the data object. For systems with DSA signing, SHA-1 hash, and 1024-bit key length, the digest algorithm must be “SHA-1.” For systems with RSA signing, MD5 hash, and 512-bit key length, the digest algorithm must be “MD5.” Multiple algorithms can be specified as a whitespace-separated list. For every digest algorithm XXX listed, there must also be a corresponding XXX-Digest line.
The signer's information file must include a section whose name matches the reserved data object section name of the section in the Manifest file. This section in the signer's information file carries the integrity data for the corresponding section in the manifest file. An example signer's information file is shown below.

Signature-Version: 2.0
SignerInformationPersistentId: (base-64 representation of a unique GUID)
SignerInformationName: BIS_VerifiableObjectSignerInfoName
Name: memory:BootObject
Digest-Algorithms: SHA-1
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the corresponding manifest section)

A line-by-line description of this signer's information file is as follows.

Signature-Version: 2.0
This is a standard header line that all signed manifests have. It must appear exactly as shown.

SignerInformationPersistentId: (base-64 representation of a unique GUID)
The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every signer's information file created. The Win32 function UuidCreate() can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].

SignerInformationName: BIS_VerifiableObjectSignerInfoName
The left-hand string must appear exactly as shown. The right-hand string must appear exactly as shown.

Name: memory:BootObject
This identifies the section in the signer's information file corresponding to the section with the same name in the manifest file described earlier. The string "memory:BootObject" must appear exactly as shown.

Digest-Algorithms: SHA-1
This enumerates the digest algorithms for which integrity data is included for the corresponding manifest section. Strings identifying digest algorithms are the same as in the manifest file. The digest algorithms specified here must match those specified in the manifest file. For every digest algorithm XXX listed, there must also be a corresponding XXX-Digest line.

SHA-1-Digest: (base-64 representation of a SHA-1 digest of the corresponding manifest section)
Gives the corresponding digest value for the corresponding manifest section. The value is base-64 encoded. Note that for the purpose of computing the hash of the manifest section, the manifest section starts at the beginning of the opening
A signature block file is a raw binary file (not base-64 encoded) that is a PKCS#7 defined format signature block. The signature block covers exactly the contents of the signer’s information file. There must be a correspondence between the name of the signer’s information file and the signature block file. The base name matches, and the three-character extension is modified to reflect the signature algorithm used according to the following rules:

- DSA signature algorithm (which uses SHA-1 hash): extension is DSA.
- RSA signature algorithm with MD5 hash: extension is RSA.

So for example with a signer’s information file name of “myinfo.SF,” the corresponding DSA signature block file name would be “myinfo.DSA.”

The format of a signature block file is defined in [PKCS].

**Description**

This function verifies the integrity and authorization of the indicated data object according to the indicated credentials. The rules for successful verification depend on whether or not a Boot Authorization Check is currently required on this platform.

If a Boot Authorization Check is not currently required on this platform, no authorization check is performed. However, the following rules are applied for an integrity check:

- In this case, the credentials are optional. If they are not supplied (Credentials.Data is NULL), no integrity check is performed, and the function returns immediately with a “success” indication and IsVerified is TRUE.
- If the credentials are supplied (Credentials.Data is other than NULL), integrity checks are performed as follows:
  - Verify the credentials - The credentials parameter is a valid signed Manifest, with a single signer. The signer’s identity is included in the credential as a certificate.
  - Verify the data object - The Manifest must contain a section named “memory:BootObject,” with associated verification information (in other words, hash value). The hash value from this Manifest section must match the hash value computed over the specified DataObject data.

If these checks succeed, the function returns with a “success” indication and * IsVerified* is TRUE. Otherwise, IsVerified is FALSE and the function returns with a “security violation” indication.

If a Boot Authorization Check is currently required on this platform, authorization and integrity checks are performed. The integrity check is the same as in the case above, except that it is required. The following rules are applied:

- Verify the credentials - The credentials parameter is required in this case (Credentials.Data must be other than NULL). The credentials parameter is a valid Signed Manifest, with a single signer. The signer’s identity is included in the credential as a certificate.
- Verify the data object - The Manifest must contain a section named “memory:BootObject,” with associated verification information (in other words, hash value). The hash value from this Manifest section must match the hash value computed over the specified DataObject data.
- Do Authorization check — This happens one of two ways depending on whether or not the platform currently has a Boot Object Authorization Certificate configured.
  - If a Boot Object Authorization Certificate is not currently configured, this function interacts with the user in a platform-specific way to determine whether the operation should succeed.
– If a Boot Object Authorization Certificate is currently configured, this function uses the Boot Object Authorization Certificate to determine whether the operation should succeed. The public key certified by the signer’s certificate must match the public key in the Boot Object Authorization Certificate configured for this platform. The match must be direct, that is, the signature authority cannot be delegated along a certificate chain.

– If these checks succeed, the function returns with a “success” indication and IsVerified is TRUE. Otherwise, IsVerified is FALSE and the function returns with a “security violation” indication.

Note that if a Boot Authorization Check is currently required on this platform this function always performs an authorization check, either through platform-specific user interaction or through a signature generated with the private key corresponding to the public key in the platform’s Boot Object Authorization Certificate.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The AppHandle parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The Credentials parameter supplied by the caller is NULL or an invalid memory reference, or The Boot Authorization Check is currently required on this platform and the Credentials.Data parameter supplied by the caller is NULL or an invalid memory reference, or The DataObject parameter supplied by the caller is NULL or an invalid memory reference, or The DataObject.Data parameter supplied by the caller is NULL or an invalid memory reference, or The IsVerified parameter supplied by the caller is NULL or an invalid memory reference.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The function failed due to lack of memory or other resources.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The signed manifest supplied as the Credentials parameter was invalid (could not be parsed), or The signed manifest supplied as the Credentials parameter failed to verify using the installed Boot Object Authorization Certificate or the signer’s Certificate in Credentials, or Platform-specific authorization failed, or Any other required attribute value was missing, or The signed manifest supplied as the Credentials parameter did not include a signer certificate, or</td>
</tr>
</tbody>
</table>

continues on next page

24.5. Boot Integrity Services Protocol
Table 24.38 – continued from previous page

| EFI_SECURITY_VIOLATION | The signed manifest supplied as the Credentials parameter did not include the manifest section named “memory:BootObject,” or  
The signed manifest supplied as the Credentials parameter had a signing certificate with an unsupported public-key algorithm, or  
The manifest section named “memory:BootObject” did not include a digest with a digest algorithm corresponding to the signing certificate’s public key algorithm, or  
The data object supplied as the DataObject parameter and referenced by the manifest section named “memory:BootObject” did not verify with the digest supplied in that manifest section, or  
The signed manifest supplied as the Credentials parameter did not include a signer’s information file with the SignerInformationName identifying attribute value “BIS_VerifiableObjectSignerInfoName,” or  
There were no signers associated with the identified signer’s information file, or  
There was more than one signer associated with the identified signer’s information file, or  
The platform’s check flag is “on” (requiring authorization checks) but the Credentials.Data supplied by the caller is NULL, or  
Any other unspecified security violation occurred. |
|------------------------|--------------------------------------------------------------------------------------------------|
| EFIDEVICE_ERROR        | An unexpected internal error occurred while attempting to retrieve the public key algorithm of the manifest’s signer’s certificate, or  
An unexpected internal error occurred in a cryptographic software module. |

24.5.11 EFI_BIS_PROTOCOL.VerifyObjectWithCredential()

Summary

Verifies the integrity and authorization of the indicated data object according to the indicated credentials and authority certificate.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_BIS_VERIFY_OBJECT_WITH_CREDENTIAL)(
    IN BIS_APPLICATION_HANDLE AppHandle,
    IN EFI_BIS_DATA *Credentials,
)(continues on next page)
IN EFI_BIS_DATA *DataObject,  
IN EFI_BIS_DATA *SectionName,  
IN EFI_BIS_DATA *AuthorityCertificate,  
OUT BOOLEAN *IsVerified
);

Parameters

AppHandle
An opaque handle that identifies the caller’s instance of initialization of the BIS service. Type BIS_APPLICATION_HANDLE is defined in the EFI_BIS_PROTOCOL.Initialize() function description.

Credentials
A Signed Manifest containing verification information for the indicated data object. The Manifest signature itself must meet the requirements described below. The required syntax of the Signed Manifest is described in the Related Definition of Manifest Syntax below. Type EFI_BIS_DATA is defined in the Initialize() function description.

DataObject
An in-memory copy of the raw data object to be verified. Type EFI_BIS_DATA is defined in the Initialize() function description.

SectionName
An ASCII string giving the section name in the manifest holding the verification information (in other words, hash value) that corresponds to DataObject. Type EFI_BIS_DATA is defined in the Initialize() function description.

AuthorityCertificate
A digital certificate whose public key must match the signer’s public key which is found in the credentials. This parameter is optional (AuthorityCertificate.Data may be NULL). Type EFI_BIS_DATA is defined in the EFI_BIS_PROTOCOL.Initialize() function description.

IsVerified
The function writes TRUE if the verification was successful. Otherwise, the function writes FALSE.

Related Definitions

//**********************************************************
// Manifest Syntax
//**********************************************************

The Signed Manifest consists of three parts grouped together into an Electronic Shrink Wrap archive as described in [SM spec]: a manifest file, a signer’s information file, and a signature block file. These three parts along with examples are described in the following sections. In these examples, text in parentheses is a description of the text that would appear in the signed manifest. Text outside of parentheses must appear exactly as shown. Also note that manifest files and signer’s information files must conform to a 72-byte line-length limit. Continuation lines (lines beginning with a single “space” character) are used for lines longer than 72 bytes. The examples given here follow this rule for continuation lines.

Note that the manifest file and signer’s information file parts of a Signed Manifest are ASCII text files. In cases where these files contain a base-64 encoded string, the string is an ASCII string before base-64 encoding.

The manifest file must include a section referring to a memory-type data object with the caller-chosen name as shown in the example below. This data object is the Data Object to be verified. An example manifest file is shown below.
A line-by-line description of this manifest file is as follows.

**Manifest-Version: 2.0**
This is a standard header line that all signed manifests have. It must appear exactly as shown.

**ManifestPersistentId: (base-64 representation of a unique GUID)**
The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every manifest file created. The Win32 function UuidCreate() can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].

**Name: (a memory-type data object name)**
This identifies the section that carries the integrity data for the target Data Object. The right-hand string must obey the syntax for memory-type references, that is, it is of the form "memory:SomeUniqueName." The "memory:" part of this string must appear exactly. The "SomeUniqueName" part is chosen by the caller. It must be unique within the section names in this manifest file. The entire "memory:SomeUniqueName" string must match exactly the corresponding string in the signer’s information file described below. Furthermore, this entire string must match the value given for the **SectionName** parameter to this function. Note that the target Data Object cannot be found directly from this manifest. A caller verifying the Data Object integrity must load the Data Object into memory and specify its memory location explicitly to this verification function through the **DataObject** parameter.

**Digest-Algorithms: SHA-1**
This enumerates the digest algorithms for which integrity data is included for the data object. For systems with DSA signing, SHA-1 hash, and 1024-bit key length, the digest algorithm must be "SHA-1." For systems with RSA signing, MD5 hash, and 512-bit key length, the digest algorithm must be "MD5." Multiple algorithms can be specified as a whitespace-separated list. For every digest algorithm XXX listed, there must also be a corresponding **XXX-Digest** line.

**SHA-1-Digest: (base-64 representation of a SHA-1 digest of the data object)**
Gives the corresponding digest value for the data object. The value is base-64 encoded.

The signer’s information file must include a section whose name matches the reserved data object section name of the section in the Manifest file. This section in the signer's information file carries the integrity data for the corresponding section in the manifest file. An example signer’s information file is shown below.

**Signature-Version: 2.0**
**SignerInformationPersistentId: (base-64 representation of a unique GUID)**
**SignerInformationName: BIS_VerifiableObjectSignerInfoName**

(continues on next page)
Name: (a memory-type data object name)
Digest-Algorithms: SHA-1
SHA-1-Digest: (base-64 representation of a SHA-1 digest of the corresponding manifest section)

A line-by-line description of this signer’s information file is as follows.

Signature-Version: 2.0

This is a standard header line that all signed manifests have. It must appear exactly as shown.

SignerInformationPersistentId: (base-64 representation of a unique GUID)

The left-hand string must appear exactly as shown. The right-hand string must be a unique GUID for every signer’s information file created. The Win32 function UuidCreate() can be used for this on Win32 systems. The GUID is a binary value that must be base-64 encoded. Base-64 is a simple encoding scheme for representing binary values that uses only printing characters. Base-64 encoding is described in [BASE-64].

SignerInformationName: BIS_VerifiableObjectSignerInfoName

The left-hand string must appear exactly as shown. The right-hand string must appear exactly as shown.

Name: (a memory-type data object name)

This identifies the section in the signer’s information file corresponding to the section with the same name in the manifest file described earlier. The right-hand string must match exactly the corresponding string in the manifest file described above.

Digest-Algorithms: SHA-1

This enumerates the digest algorithms for which integrity data is included for the corresponding manifest section. Strings identifying digest algorithms are the same as in the manifest file. The digest algorithms specified here must match those specified in the manifest file. For every digest algorithm XXX listed, there must also be a corresponding XXX-Digest line.

SHA-1-Digest: (base-64 representation of a SHA-1 digest of the corresponding manifest section)

Gives the corresponding digest value for the corresponding manifest section. The value is base-64 encoded. Note that for the purpose of computing the hash of the manifest section, the manifest section starts at the beginning of the opening " Name: ” keyword and continues up to, but not including, the next section’s ” Name: ” keyword or the end-of-file. Thus the hash includes the blank line(s) at the end of a section and any newline(s) preceding the next ” Name: ” keyword or end-of-file.

//**********************************************************
// Signature Block File Example
//**********************************************************

A signature block file is a raw binary file (not base-64 encoded) that is a PKCS#7 defined format signature block. The signature block covers exactly the contents of the signer’s information file. There must be a correspondence between the name of the signer’s information file and the signature block file. The base name matches, and the three-character extension is modified to reflect the signature algorithm used according to the following rules:
- DSA signature algorithm (which uses SHA-1 hash): extension is DSA.
• RSA signature algorithm with MD5 hash: extension is RSA.

So for example with a signer’s information file name of “myinfo.SF,” the corresponding DSA signature block file name would be “myinfo.DSA.”

The format of a signature block file is defined in [PKCS].

Description

This function verifies the integrity and authorization of the indicated data object according to the indicated credentials and authority certificate. Both an integrity check and an authorization check are performed. The rules for a successful integrity check are:

• Verify the credentials - The credentials parameter is a valid Signed Manifest, with a single signer. The signer’s identity is included in the credential as a certificate.

• Verify the data object - The Manifest must contain a section with the name as specified by the SectionName parameter, with associated verification information (in other words, hash value). The hash value from this Manifest section must match the hash value computed over the data specified by the DataObject parameter of this function.

The authorization check is optional. It is performed only if the AuthorityCertificate.Data parameter is other than NULL. If it is other than NULL, the rules for a successful authorization check are:

• The AuthorityCertificate parameter is a valid digital certificate. There is no requirement regarding the signer (issuer) of this certificate.

• The public key certified by the signer’s certificate must match the public key in the AuthorityCertificate. The match must be direct, that is, the signature authority cannot be delegated along a certificate chain.

If all of the integrity and authorization check rules are met, the function returns with a “success” indication and IsVerified is TRUE. Otherwise, it returns with a nonzero specific error code and IsVerified is FALSE.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The AppHandle parameter is not or is no longer a valid application instance handle associated with the EFI_BIS protocol.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The Credentials parameter supplied by the caller is NULL or an invalid memory reference, or</td>
</tr>
<tr>
<td></td>
<td>The Credentials.Data parameter supplied by the caller is NULL or an invalid memory reference, or</td>
</tr>
<tr>
<td></td>
<td>The Credentials.Length supplied by the caller is zero, or The DataObject parameter supplied by the caller is NULL or an invalid memory reference, or</td>
</tr>
<tr>
<td></td>
<td>The DataObject.Data parameter supplied by the caller is NULL or an invalid memory reference, or</td>
</tr>
<tr>
<td>Code</td>
<td>Description</td>
</tr>
<tr>
<td>-----------------------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>SectionName</code> parameter supplied by the caller is NULL or an invalid memory reference, or The <code>SectionName.Data</code> parameter supplied by the caller is NULL or an invalid memory reference, or The <code>SectionName.Length</code> supplied by the caller is zero, or The <code>AuthorityCertificate</code> parameter supplied by the caller is NULL or an invalid memory reference, or The <code>IsVerified</code> parameter supplied by the caller is NULL or an invalid memory reference.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The function failed due to lack of memory or other resources.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The <code>Credentials.Data</code> supplied by the caller is NULL, or The <code>AuthorityCertificate</code> supplied by the caller was invalid (could not be parsed), or The signed manifest supplied as <code>Credentials</code> failed to verify using the <code>AuthorityCertificate</code> supplied by the caller or the manifest’s signer’s certificate, or Any other required attribute value was missing, or The signed manifest supplied as the <code>Credentials</code> parameter did not include a signer certificate, or The signed manifest supplied as the <code>Credentials</code> parameter did not include the manifest section named according to <code>SectionName</code>, or The signed manifest supplied as the <code>Credentials</code> parameter had a signing certificate with an unsupported public-key algorithm, or The manifest section named according to <code>SectionName</code> did not include a digest with a digest algorithm corresponding to the signing certificate’s public key algorithm, or The data object supplied as the <code>DataObject</code> parameter and referenced by the manifest section named according to <code>SectionName</code> did not verify with the digest supplied in that manifest section, or</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The signed manifest supplied as the <code>Credentials</code> parameter did not include a signer’s information file with the <code>SignerInformationName</code> identifying attribute value &quot;BI S_VerifiableObjectSignerInfoName,&quot; or There were no signers associated with the identified signer’s information file, or There was more than one signer associated with the identified signer’s information file, or Any other unspecified security violation occurred.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected internal error occurred while attempting to retrieve the public key algorithm of the manifest’s signer’s certificate, or An unexpected internal error occurred in a cryptographic software module.</td>
</tr>
</tbody>
</table>
24.6 DHCP options for iSCSI on IPV6

Option 59 is the iSCSI Root path

The format of the root path is “iscsi:”<servername>:”<protocol>:”<port>:”<LUN>:”<targetname>

This is per the description in IETF RFC 4173. See https://uefi.org/uefi#RFC4173 for a link to this document.

Option 60 is the DHCP Server address.

This is formatted the same as parameter 1 in OPT_BOOTFILE_PARAM (60) of the IPv6 address of the DHCP server (IETF RFC 5970). See `https://uefi.org/uefi` for a link to this document.

24.7 HTTP Boot

24.7.1 Boot from URL

Elsewhere in this specification there is defined a discoverable network boot using DHCP as a control channel allowing a firmware client machine export its architecture type, and then have the boot server response with a binary image. For the UEFI architecture types defined in “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “IANA DHCPv6 parameters”, the binary image on the boot service is a UEFI-formatted executable with a machine subsystem type that corresponds to the UEFI firmware on the client machine, or it could be mounted as a RAM disk which contains a UEFI-compliant file system (See File System Format). This binary image is often referred to as a “Network Boot Program” (NBP). The UEFI client machine that downloads the NBP uses the IPv4 or IPv6 TFTP protocol to address the indicated server, depending upon if DHCP4 or DHCP6 was used initially, in order to download images such as 64-bit UEFI (type 0x07).

This section defines a related method indicated by other codes in the DHCP options, in which the name and path of the NBP are specified as a URI string in one of several formats specifying protocol and unique name identifying the NBP for the specified protocol. In this method the NBP will be downloaded via IPv4 or IPv6 HTTP protocol if the tag indicates x64 UEFI HTTP Boot (type code 0x0f for x86 and 0x10 for x64).

In the future other protocols such as FTP or NFS could be encoded with both new tag types and corresponding URIs (e.g., ftp://nbp.efi or nfs://nbp.efi, respectively). However, assignment of these type codes has not yet occurred.

The rest of this section will describe ‘HTTP Boot’ as one example of ‘boot from URL’. It is expected that the procedure can be extended as additional protocol type codes are defined.

Please reference the definitions of EFI_DNS4_PROTOCOL and EFI_DNS6_PROTOCOL elsewhere in this document. In systems that also support one of both of these protocols, the target URI can be specified using Internet domain name format understood by DNS servers supporting the appropriate RFC specifications.

Also, elsewhere in this document, the PXE2.1 and UEFI2.4 netboot6 sections talk about the ‘boot from TFTP’ method of ‘boot from URL’.

The following RFC documents documents should be consulted for network message details related to the processes described in this chapter:

1. RFC1034 - “Domain Names - Concepts and Facilities”,
2. RFC 1035 - “Domain Names - Implementation and Specification”,
4. RFC 3596 - DNS Extensions to Support IP Version 6
5. RFC 2131 - Dynamic Host Configuration Protocol
6. RFC 2132 - DHCP options and BOOTP Vendor Extensions
HTTP Boot is client-server communication based application. It combines the DHCP, DNS, and HTTP protocols to provide the capability for system deployment and configuration over the network. This new capability can be utilized as a higher-performance replacement for tftp-based PXE boot methods of network deployment.

24.7.2 Concept configuration for a typical HTTP Boot scenario

HTTP Boot network configuration may involve one or more UEFI client systems, and several server systems. The Figure below show a typical HTTP Boot network topology for a corporate environment.

24.7.2.1 Use in Corporate environment

- **UEFI HTTP Boot Client** initiates the communication between the client and different server systems.
- **DHCP server with HTTPBoot extension** for boot service discovery. Besides the standard host configuration information (such as address/subnet/gateway/name-server, etc...), the DHCP server with the extensions can also provide the discovery of URI locations for boot images on the HTTP server.
- **HTTP server** could be located either inside the corporate environment or across networks, such as on the Internet. The boot resource itself is deployed on the HTTP server. In this example, “http://webserver/boot/boot.efi” is used as the boot resource. Such an application is also called a Network Boot Program (NBP). NBPs are used to setup the client system, which may include installation of an operating system, or running a service OS for maintenance and recovery tasks.
- **DNS server** is optional; and provides standard domain name resolution service.
24.7.2.2 Use case in Home environment

In a corporate environment, a standard DHCP server can be enhanced to support the HTTPBoot extension. In a home network, generally only an optional standard DHCP server may be available for host configuration information assignment. The Figure, below, shows the concept network topology for a typical home PC environment.

![HTTP Boot Network Topology Concept](image)

**UEFI HTTP Boot Client** initiates the communication between the client and different servers. In the home configuration however, the client will expect the boot resource information to be available from a source other than the standard DHCP server, and that source does not typically have HTTPBoot extensions. Instead of DHCP, the boot URI could be created by a UEFI application or extracted from text entered by a user.

**DHCP server** is optional, and if available in the network, provides the standard service to assign host configuration information to the UEFI Client (e.g. address/subnet/gateway/name-server/etc.). In case the standard DHCP server is not available, the same host configuration information should be provided by a UEFI application or extracted from text entered by a user prior to the client initiating the communication.

**DNS Server** is optional, and provides standard domain name resolution service.

24.7.3 Protocol Layout for UEFI HTTP Boot Client

This figure illustrates the UEFI network layers related to how the HTTP Boot works.

The HTTP Boot driver is layered on top of a UEFI Network stack implementation. It consumes DHCP service to do the Boot service discovery, and DNS service to do domain name resolution if needed. It also consumes HTTP serviced to retrieve images from the HTTP server. The functionality needed in the HTTP Boot scenario is limited to client initiated requests to download the boot image.

TLS is consumed if HTTPS functionality is needed. The TLS design is covered in *EFI TLS Protocol*.

The HTTP Boot driver produces *LoadFile* protocol and device path protocol. BDS will provide the boot options for the HTTP Boot. Once a boot option for HTTP boot is executed, a particular network interface is selected. HTTP Boot driver will perform all steps on that interface and it is not required to use other interfaces.
Fig. 24.6: UEFI HTTP Boot Protocol Layout
24.7.3.1 Device Path

If both IPv4 and IPv6 are supported, the HTTP Boot driver should create two child handles, with LoadFile and DevicePath installed on each child handle. For the device path, an IP device path node and a BootURI device path are appended to the parent device path, for example:

PciRoot(0x0)/Pci(0x19, 0x0)/MAC(001230F4B4FF, 0x0)/IPv4(0.0.0.0, 0, DHCP, 0.0.0.0, 0.0.0.0, 0.0.0.0)/Uri()
PciRoot(0x0)/Pci(0x19, 0x0)/MAC(001230F4B4FF, 0x0)/IPv6(:,:,128, 0, Static, :/:128, :/:128, 0)/Uri()

Also, after retrieving the boot resource information and IP address, the BootURI device path node will be updated to include the BootURI information. For example, if the NBP is a UEFI-formatted executable, the device path will be updated to

PciRoot(0x0)/Pci(0x19, 0x0)/MAC(001230F4B4FF, 0x0)/IPv4(192.168.1.100, TCP, DHCP, 192.168.1.5, 192.168.1.1, 255.255.255.0)/Uri(http://192.168.1.100/shell.efi)
PciRoot(0x0)/Pci(0x19, 0x0)/MAC(001230F4B4FF, 0x0)/IPv6(2015::100, TCP, StatefulAutoConfigure, 2015::5, 2015::10, 64)/Uri(http://2015::100/shell.efi)

These two instances allow for the boot manager to decide a preference of IPv6 versus IPv4.

If the NBP is a binary image which could be mounted as a RAM disk, the device path will be updated to

PciRoot(0x0)/Pci(0x19, 0x0)/MAC(001230F4B4FF, 0x0)/IPv4(192.168.1.100, TCP, DHCP, 192.168.1.5, 192.168.1.1, 255.255.255.0)/Uri(http://192.168.1.100/boot.iso [^])
PciRoot(0x0)/Pci(0x19, 0x0)/MAC(001230F4B4FF, 0x0)/IPv6(2015::100, TCP, StatefulAutoConfigure, 2015::5, 2015::10, 64)/Uri(http://2015::100/boot.iso)

In this case, the HTTP Boot driver will register RAM disk with the downloaded NBP, by appending a RamDisk device node to the device path above, like

PciRoot(0x0)/Pci(0x19, 0x0)/MAC(001230F4B4FF, 0x0)/IPv4(192.168.1.100, TCP, DHCP, 192.168.1.5, 192.168.1.1, 255.255.255.0)/Uri(http://192.168.1.100/boot.iso )/RamDisk(0x049EA000, 0x5DEA000, 0, 3D5ABD30-4175-87CE-6D64-D2ADE523C4BB)
PciRoot(0x0)/Pci(0x19, 0x0)/MAC(001230F4B4FF, 0x0)/IPv6(2015::100, TCP, StatefulAutoConfigure, 2015::5, 2015::10, 64)/Uri(http://2015::100/boot.iso)/RamDisk(0x049EA000, 0x5DEA000, 0, 3D5ABD30-4175-87CE-6D64-D2ADE523C4BB)

In some cases, Uri includes a host name and DNS become mandatory for translating the name to the IP address of the host. The HTTP Boot driver may append DNS device path node immediately before Uri device path node, for example:

PciRoot(0x0)/Pci(0x19, 0x0)/MAC(001230F4B4FF, 0x0)/IPv4(192.168.1.100, TCP, DHCP, 192.168.1.5, 192.168.1.1, 255.255.255.0)/Dns(192.168.22.100, 192.168.22.101)/Uri(http://www.bootserver.com/boot.iso )/RamDisk(0x049EA000, 0x5DEA000, 0, 3D5ABD30-4175-87CE-6D64-D2ADE523C4BB)
PciRoot(0x0)/Pci(0x19, 0x0)/MAC(001230F4B4FF, 0x0)/IPv6(2015::100, TCP, StatefulAutoConfigure, 2015::5, 2015::10, 64)/Dns(2016::100, 2016::101)/Uri(http://www.bootserver.com/boot.iso )/RamDisk(0x049EA000, 0x5DEA000, 0, 3D5ABD30-4175-87CE-6D64-D2ADE523C4BB)

If HTTP Boot driver cannot obtain the DNS server addresses, it should not append an empty DNS device path node.

The boot manager could use the example device paths to match the device which produces a device path protocol including a URI device path node in the system, without matching the Specific Device Path data in IP device path node and URI device path node, because the IP device path node and URI device path node might be updated by HTTP Boot driver in different scenarios.

The BootURI information could be retrieved from a DHCP server with HTTPBoot extension, or from a boot option which includes a short-form URI device path, or from a boot option which includes a URI device path node, or created by a UEFI application or extracted from text entered by a user.
Once the HTTP Boot driver retrieves the BootURI information from the short-form URI device path, it will perform all other steps for HTTP boot except retrieving the BootURI from DHCP server. Also, when the short-form URI device path is inputted to HTTP Boot driver via LoadFile protocol, the HTTP Boot driver should expand the short-form URI device path to above example device path after retrieving IP address configuration (address, subnet, gateway, and optionally the name-server) from the DHCP server. In case of the home environment with no DHCP server, the same information may be provisioned by OEM or input by the end user through Setup Options. The IP and optional DNS device path nodes, constructed with this information and prefixed to the short-form URI device path, can be inputted to the HTTP Boot driver via LoadFile protocol. The name server information in the form of DNS device path node is optional, and is used only when the BootURI contains the server name or FQDN. The HTTP Boot driver will then consume the information in the device path and initiate the necessary communication.

Once the HTTP Boot driver retrieves the BootURI information from a boot option which includes a URI device path node, it should retrieve the IP address configuration from the IP device path node of the same boot option. If the IP address configuration or BootURI information is empty, the HTTP Boot driver could retrieve the required information from DHCP server. If the IP address configuration or BootURI information is not empty but invalid, the HTTP boot process will fail.

The HTTP Boot block diagram (UEFI HTTP Boot Protocol Layout) describes a suggested implementation for HTTP Boot. Other implementation can create their own HTTP Netboot Driver which meets the requirements for their netboot methodology.

24.7.4 Concept of Message Exchange in a typical HTTPBoot scenario (IPv4 in Corporate Environment)

In summary, the newly installed networked client machine (UEFI HTTP Boot Client) should be able to enter a heterogeneous network, acquire a network address from a DHCP server, and then download an NBP to set itself up.

The concept of HTTP Boot message exchange sequence is as follows. The client initiates the DHCPv4 D.O.R.A process by broadcasting a DHCPDISCOVER containing the extension that identifies the request as coming from a client that implements the HTTP Boot functionality. Assuming that a DHCP server or a Proxy DHCP server implementing this extension is available, after several intermediate steps, besides the standard configuration such as address/subnet/router/dns-server, boot resource location will be provided to the client system in the format of a URI. The URI points to the NBP which is appropriate for this client hardware configuration. A boot option is created, and if selected by the system logic the client then uses HTTP to download the NBP from the HTTP server into memory. Finally, the client executes the downloaded NBP image from memory. This image can then consume other UEFI interfaces for further system setup.

24.7.4.1 Message exchange between EFI Client and DHCP server using DHCP Client Extensions

24.7.4.1.1 Client broadcast

The client broadcasts a DHCP Discover message to the standard DHCP port (67).

An option field in this packet contains the following:

- Fill DHCP option 55 - Parameter Requested List option
  - Address configuration, Server information, Name server, Vendor class identifier
- A DHCP option 97: UUID/GUID-based Client Identifier
- A DHCP option 94: Client Network Identifier Option
  - If support UNDI, fill this option (Refer RFC5970)
- A DHCP option 93: the client system architecture (Refer [Arch-Type])
  - 0x0F - x86 UEFI HTTP Boot
Fig. 24.7: HTTP Boot Overall Flow
A DHCP option 60, Vendor Class ID, set to “HTTPClient:Arch:XXXX:UNDI:YYZZZ”

DHCP server response

The DHCP server responds by sending DHCPOFFER message on standard DHCP reply port (68).

The HTTP Boot Client may possibly receive multiple DHCPOFFER packets from different sources of DHCP Services, possibly from DHCP Services which recognize the HTTP extensions or from Standard DHCP Services.

A service recognizing HTTP extensions must respond with an offer that has Option 60 (Vendor class identifier) parameter set to “HTTPClient”, in response to the Vendor class identifier requested in option 55 in the DHCP Discover message.

Each message contains standard DHCP parameters: an IP address for the client and any other parameters that the administrator might have configured on the DHCP or Proxy DHCP Service. The DHCP service or Proxy DHCP which recognizes the HTTPBoot extension will provide DHCPOFFER with HTTPClient extensions. If this is a Proxy DHCP service, then the client IP address field is (0.0.0.0). If this is from a DHCP service, then the returned client IP address field is valid.

From the received DHCPOFFER(s), the client records the information as follows:

- Client IP address (and other parameters) offered by a standard DHCP/BOOTP services.
- If Boot URI information is provided thru ‘file’ field in DHCP Header or option 67, then the client will record the information as well.
- Optional Name-server information if URI is displayed using domain-name

  - Timeout: After Client sent out the DHCP Discover packet, the Client will wait for a timeout to collect enough DHCP Offers. If failed to retrieve all the required information, the DHCP Discover will be retried, at most four times. The four timeout mechanisms is 4, 8, 16 and 32 seconds respectively,
  - Priority: Among all the received DHCPOFFERs, the Priority is considered as follows:

24.7.5 Priority1

Choose the DHCPOFFER that provides all required information:

<IP address configuration, Boot URI configuration, Name-server configuration (if domain-name used in Boot URI)>

If Boot URI and IP address configuration provided in different DHCPOFFER, Using 5 DHCPOFFER as example for priority description

- Packet1 - DHCPOFFER, provide <IP address configuration, Name server>
- Packet2 - DHCPOFFER, provide <IP address configuration>
- Packet3 - DHCPOFFER, provide <domain-name expressed URI>
- Packet4 - DHCPOFFER, provide <IP address expressed URI>
- Packet5 - DHCPOFFER, provide <IP address, domain-name expressed URI>

Then,
24.7.6 Priority2

Choose the DHCPOFFER from different packet, firstly find out URI info represented in IP address mode, then choose DHCPOFFER which provide IP address configuration.

In this example, the chosen DHCPOFFER packet is packet4 + packet1 / packet2 (packet 1/2 take same priority, implementation can make its own implementation choice).

24.7.7 Priority3

Choose the DHCPOFFER from different packet, firstly find out URI info represented in domain-name mode, then choose DHCPOFFER which provide <IP address configuration, domain-name expressed URI>.

In this example, the chosen DHCPOFFER packet is packet3 / packet5 + packet1.

NOTE: If packet5, then client IP address assigned by Packet5 will be override by IP address in packet1.

24.7.8 Priority4

If failed to retrieve <Boot URI / IP address / (on-demand) Name-server> information through all received DHCPOFFERs, this is deemed as FAILED-CONFIGURATION.

Assuming the boot image is in the boot subdirectory of the web server root, the supported URI could be one of below formats. [RFC3986] where `/boot/` is replaced by administrator-created directory, and `image` is the file name of the NBP.

`http://reg-name:port/boot/image`

`http://ipv4address:port/boot/image`

`http://ipv6address:port/boot/image`

In the URL example, Port is optional if web service is provided through port 80 for the HTTP data transfer. Commonly, the reg-name use DNS as name registry mechanism.

After retrieving the boot URI through Device Path, if IP address (either IPv4 or IPv6 address) is provided, the HTTP Boot Client can directly use that address for next step HTTP transfer. If a reg-name is provided in the URI, the HTTP Boot Client driver need initiate DNS process (See Message in DNS Query/Reply) to resolve its IP address.

DHCP Request

The HTTP Boot Client selects an IP address offered by a DHCP Service, and then it completes the standard DHCP protocol by sending a DHCP Request packet for the address to the DHCP Server and waiting for acknowledgement from the DHCP server.

DHCP ACK

The server acknowledges the IP address by sending DHCP ACK packet to the client.
24.7.8.1 Message exchange between UEFI Client and DHCP server not using DHCP Client Extensions

In a home environment, because the Boot URI Information will not be provided by the DHCP Offers, we need other channels to provide this information. The implementation suggestion is provisioning this information by OEM or input by end user through Setup Options, henceforth, the UEFI Boot Client already know the Boot URI before contacting the DHCP server.

The message exchange between the EFI Client and DHCP server will be standard DHCP D.O.R.A to obtain <IP address, Name-server>.

In the case of a home environment without a DHCP server, the above message exchange is not needed, and the UEFI HTTP Boot Client will have the <IP address, Name-server> provisioned by OEM or input by the end user through Setup Options.

24.7.8.2 Message in DNS Query/Reply

The DNS Query/Reply is a standard process defined in DNS Protocol [RFC 1034, RFC 1035]. Multiple IP address might be retrieved from the DNS process. It’s the HTTP Boot Client driver’s responsibility to select proper IP address automatically or expose user interface for customer to decide proper IP address.

24.7.8.3 Message in HTTP Download

In the HTTP Boot scenario, HTTP GET message is used to get image from the Web server.

24.7.9 Concept of Message Exchange in HTTP Boot scenario (IPv6)

24.7.9.1 Message exchange between EFI Client and DHCPv6 server with DHCP Client extensions

24.7.9.1.1 Client multicast a DHCPv6 Solicit message to the standard DHCPv6 port (547)

Besides the options required for address auto-configuration, option field in this packet also contains the following:

- Fill DHCPv6 Option 6 - Option Request Option
  - Request server to supply option 59 (OPT_BOOTFILE_URL), option 60 (OPT_BOOTFILE_PARAM), option 23 (OPT_DNS_SERVERS), option 16 (OPTION_VENDOR_CLASS).

- A DHCPv6 option 1, Client identifier

- A DHCPv6 option 16, Vendor Class ID, set to “HTTPClient:Arch:XXXX:UNDI:YYYYZZZ”

- A DHCPv6 option 61: the client system architecture (Refer [Arch-Type])
  - 0x0F - x86 UEFI HTTP Boot
  - 0x10 - x64 UEFI HTTP Boot

- A DHCPv6 option 62: Client Network Identifier Option
  - If support UNDI, fill this option (Refer RFC5970)
24.7.9.1.2 Server unicast DHCPv6 Advertisement to the Client to the DHCPv6 port (546)

The HTTP Boot Client will receive multiple advertisements from different sources of DHCPv6 Services, possibly from DHCPv6 Services which recognize the HTTP extensions or from Standard DHCPv6 Services.

A DHCPv6 service recognizing HTTP extensions must respond with an Advertisement that has Option 16 (OPTION_VENDOR_CLASS) parameters set to “HTTPClient”, in response to the OPTION_VENDOR_CLASS requested in Option 6 in the DHCPv6 Solicit message.

Each message contains standard DHCP parameters: Identify Association (IA) option which conveys information including <IP address, lifetime, etc...>. Name server option conveys the DNS server address. The DHCP service or Proxy DHCP which recognizes the HTTPBoot extension will provide DHCPv6 Advertisement with HTTPClient extensions, including Boot URI and Optional Boot Parameters.

From the received DHCPOFFER(s), the client records the information as follows:

- Client IP address (and other parameters) provide through IA option
- Boot URI provided thru option 59
- Optional BootFile Parameter provided through option 60 (if no other parameter needed for this boot URI, this option can be eliminated)
- Optional Name-server information provided through option 23, if URI is displayed using domain-name.

24.7.9.1.3 Client multicast DHCPv6 Request to the selected DHCP Advertisement to confirm the IP address assigned by that server

This packet is the same with the DHCPv6 Solicit packet except for the message type is Request.

24.7.9.1.4 Server unicast the DHCPv6 Reply to acknowledge the Client IP address for the UEFI HTTP-Client

24.7.9.2 Message exchange between UEFI Client and DHCPv6 server not using DHCP Client Extensions

In a home environment, the Boot URI Information will not be provided by the DHCPv6 Offers, we need other channels to provide this information. Like what is described in Message exchange between UEFI Client and DHCP server not using DHCP Client Extensions, the implementation suggestion is provisioning this information by OEM or input by end user through Setup Options, henceforth, the UEFI Boot Client already know the Boot URI before contacting the DHCP server.

The message exchange between the EFI Client and DHCP server will be standard DHCP S.A.R.R. to obtain <IP address, Name-server>.

In the case of a home environment without a DHCPv6 server, the above message exchange is not needed, and the UEFI HTTP Boot Client will have the <IP address, Name-server> provisioned by OEM or input by the end user through Setup Options.
24.7.9.3 Message exchange between UEFI Client and DNS6server

The DNS Query/Reply for domain name resolution is the same process as described in See Message in DNS Query/Reply.

24.7.9.4 Message in HTTP Download

HTTP Download process is the same process as described in Message in HTTP Download.

24.7.10 EFI HTTP Boot Callback Protocol

This section defines the EFI HTTP Boot Callback Protocol that is invoked when the HTTP Boot driver is about to transmit or has received a packet. The EFI HTTP Boot Callback Protocol must be installed on the same handle as the Load File Protocol for the HTTP Boot.

24.7.11 EFI_HTTP_BOOT_CALLBACK_PROTOCOL

Summary
Protocol that is invoked when the HTTP Boot driver is about to transmit or has received a packet.

GUID

#define EFI_HTTP_BOOT_CALLBACK_PROTOCOL_GUID \ 
{0xba23b311, 0x343d, 0x11e6, {0x91, 0x85, 0x58, 0x20, 0xb1, 0xd6, 0x52, 0x99}}

Protocol Interface Structure

typedef struct _EFI_HTTP_BOOT_CALLBACK_PROTOCOL {
    EFI_HTTP_BOOT_CALLBACK Callback;
} EFI_HTTP_BOOT_CALLBACK_PROTOCOL;

Parameters

Callback
    Callback routine used by the HTTP Boot driver.

24.7.12 EFI_HTTP_BOOT_CALLBACK_PROTOCOL.Callback()

Summary
Callback function that is invoked when the HTTP Boot driver is about to transmit or has received a packet.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_HTTP_BOOT_CALLBACK) (  
    IN EFI_HTTP_BOOT_CALLBACK_PROTOCOL *This,  
    IN EFI_HTTP_BOOT_CALLBACK_DATA_TYPE DataType,  
    IN BOOLEAN Received,  
    IN UINT32 DataLength,  
    (continues on next page)
Parameters

This

Pointer to the EFI_HTTP_BOOT_CALLBACK_PROTOCOL instance.

DataType

The event that occurs in the current state. Type EFI_HTTP_BOOT_CALLBACK_DATA_TYPE is defined below.

Received

TRUE if the callback is being invoked due to a receive event. FALSE if the callback is being invoked due to a transmit event.

DataLength

The length in bytes of the buffer pointed to by Data.

Data

A pointer to the buffer of data, the data type is specified by DataType.

Related Definitions

```c
typedef enum {
    HttpBootDhcp4,
    HttpBootDhcp6,
    HttpBootHttpRequest,
    HttpBootHttpResponse,
    HttpBootHttpEntityBody,
    HttpBootTypeMax
} EFI_HTTP_BOOT_CALLBACK_DATA_TYPE;
```

HttpBootDhcp4

Data points to a DHCP4 packet which is about to transmit or has received.

HttpBootDhcp6

Data points to a DHCP6 packet which is about to be transmit or has received.

HttpBootHttpRequest

Data points to an EFI_HTTP_MESSAGE structure, which contains a HTTP request message to be transmitted.

HttpBootHttpResponse

Data points to an EFI_HTTP_MESSAGE structure, which contains a received HTTP response message.

HttpBootHttpEntityBody

Part of the entity body has been received from the HTTP server. Data points to the buffer of the entity body data.

Description

This function is invoked when the HTTP Boot driver is about to transmit or has received packet. Parameters DataType and Received specify the type of event and the format of the buffer pointed to by Data. Due to the polling nature of UEFI device drivers, this callback function should not execute for more than 5 ms. The returned status code determines the behavior of the HTTP Boot driver.

Status Codes Returned

24.7. HTTP Boot
<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>Tells the HTTP Boot driver to continue the HTTP Boot process.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_ABORTED</td>
<td>Tells the HTTP Boot driver to abort the current HTTP Boot process.</td>
</tr>
</tbody>
</table>
25.1 EFI Managed Network Protocol

This chapter defines the EFI Managed Network Protocol. It is split into the following two main sections:

• Managed Network Service Binding Protocol (MNSBP)
• Managed Network Protocol (MNP)

The MNP provides raw (unformatted) asynchronous network packet I/O services. These services make it possible for multiple-event-driven drivers and applications to access and use the system network interfaces at the same time.

25.1.1 EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL

Summary

The MNSBP is used to locate communication devices that are supported by an MNP driver and to create and destroy instances of the MNP child protocol driver that can use the underlying communications device.

The EFI Service Binding Protocol in *EFI Services Binding* defines the generic Service Binding Protocol functions. This section discusses the details that are specific to the MNP.

GUID

```c
#define EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL_GUID \
{0xf36ff770,0xa7e1,0x42cf,\ 
{0xe,0xd2,0x56,0xf0,0xf2,0xf4,0x4c}}
```

Description

A network application (or driver) that requires shared network access can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish an MNSBP GUID. Each device with a published MNSBP GUID supports MNP and may be available for use.

After a successful call to the *EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL.CreateChild()* function, the child MNP driver instance is in an unconfigured state; it is not ready to send and receive data packets.

Before a network application terminates execution, every successful call to the *EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL.CreateChild()* function must be matched with a call to the *EFI_MANAGED_NETWORK_SERVICE_BINDING_PROTOCOL.DestroyChild()* function.
25.1.2 EFI_MANAGED_NETWORK_PROTOCOL

Summary
The MNP is used by network applications (and drivers) to perform raw (unformatted) asynchronous network packet I/O.

GUID
#define EFI_MANAGED_NETWORK_PROTOCOL_GUID
{0x7ab33a91, 0xace5, 0x4326,
 {0xb5, 0x72, 0xe7, 0xee, 0x33, 0xd3, 0x9f, 0x16}}

Protocol Interface Structure

typedef struct _EFI_MANAGED_NETWORK_PROTOCOL {
    EFI_MANAGED_NETWORK_GET_MODE_DATA GetModeData;
    EFI_MANAGED_NETWORK_CONFIGURE Configure;
    EFI_MANAGED_NETWORK_MCAST_IP_TO_MAC McastIpToMac;
    EFI_MANAGED_NETWORK_GROUPS Groups;
    EFI_MANAGED_NETWORK_TRANSMIT Transmit;
    EFI_MANAGED_NETWORK_RECEIVE Receive;
    EFI_MANAGED_NETWORK_CANCEL Cancel;
    EFI_MANAGED_NETWORK_POLL Poll;
} EFI_MANAGED_NETWORK_PROTOCOL;

Parameters
GetModeData
Returns the current MNP child driver operational parameters. May also support returning underlying Simple Network Protocol (SNP) driver mode data. See the GetModeData() function description.

Configure
Sets the Configure() function description.

McastIpToMac
Translates a software (IP) multicast address to a hardware (MAC) multicast address. This function may be unsupported in some MNP implementations. See the McastIpToMac() function description.

Groups
Enables and disables receive filters for multicast addresses. This function may be unsupported in some MNP implementations. See the Groups() function description.

Transmit
Places asynchronous outgoing data packets into the transmit queue. See the Transmit() function description.

Receive
Places an asynchronous receiving request into the receiving queue. See the Receive() function description.

Cancel
Aborts a pending transmit or receive request. See the Cancel() function description.

Poll
Polls for incoming data packets and processes outgoing data packets. See the Poll() function description.

Description
The services that are provided by MNP child drivers make it possible for multiple drivers and applications to send and receive network traffic using the same network device.
Before any network traffic can be sent or received, the `EFI_MANAGED_NETWORK_PROTOCOL.Configure()` function must initialize the operational parameters for the MNP child driver instance. Once configured, data packets can be received and sent using the following functions:

- `EFI_MANAGED_NETWORK_PROTOCOL.Transmit()`
- `EFI_MANAGED_NETWORK_PROTOCOL.Receive()`
- `EFI_MANAGED_NETWORK_PROTOCOL.Poll()`

### 25.1.3 EFI_MANAGED_NETWORK_PROTOCOL.GetModeData()

**Summary**

Returns the operational parameters for the current MNP child driver. May also support returning the underlying SNP driver mode data.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_MANAGED_NETWORK_GET_MODE_DATA) (
    IN EFI_MANAGED_NETWORK_PROTOCOL *This,
    OUT EFI_MANAGED_NETWORK_CONFIG_DATA *MnpConfigData OPTIONAL,
    OUT EFI_SIMPLE_NETWORK_MODE *SnpModeData OPTIONAL
);
```

**Parameters**

- **This**
  - Pointer to the `EFI_MANAGED_NETWORK_PROTOCOL` instance.

- **MnpConfigData**
  - Pointer to storage for MNP operational parameters. Type `EFI_MANAGED_NETWORK_CONFIG_DATA` is defined in “Related Definitions” below.

- **SnpModeData**
  - Pointer to storage for SNP operational parameters. This feature may be unsupported. Type `EFI_SIMPLE_NETWORK_MODE` is defined in the `EFI_SIMPLE_NETWORK_PROTOCOL`.

**Description**

The `GetModeData()` function is used to read the current mode data (operational parameters) from the MNP or the underlying SNP.

**Related Definitions**

```c
//***************************************************
// EFI_MANAGED_NETWORK_CONFIG_DATA
//***************************************************
typedef struct {
    UINT32 ReceivedQueueTimeoutValue;
    UINT32 TransmitQueueTimeoutValue;
    UINT16 ProtocolTypeFilter;
    BOOLEAN EnableUnicastReceive;
    BOOLEAN EnableMulticastReceive;
    BOOLEAN EnableBroadcastReceive;
    BOOLEAN EnablePromiscuousReceive;
} EFI_MANAGED_NETWORK_CONFIG_DATA;
```

(continues on next page)
BOOLEAN FlushQueuesOnReset;
BOOLEAN EnableReceiveTimestamps;
BOOLEAN DisableBackgroundPolling;
} EFI_MANAGED_NETWORK_CONFIG_DATA;

ReceivedQueueTimeoutValue
Timeout value for a UEFI one-shot timer event. A packet that has not been removed from the MNP receive queue by a call to EFI_MANAGED_NETWORK_PROTOCOL.Poll() will be dropped if its receive timeout expires. If this value is zero, then there is no receive queue timeout. If the receive queue fills up, then the device receive filters are disabled until there is room in the receive queue for more packets. The startup default value is 10,000,000 (10 seconds).

TransmitQueueTimeoutValue
Timeout value for a UEFI one-shot timer event. A packet that has not been removed from the MNP transmit queue by a call to EFI_MANAGED_NETWORK_PROTOCOL.Poll() will be dropped if its transmit timeout expires. If this value is zero, then there is no transmit queue timeout. If the transmit queue fills up, then the EFI_MANAGED_NETWORK_PROTOCOL.Transmit() function will return EFI_NOT_READY until there is room in the transmit queue for more packets. The startup default value is 10,000,000 (10 seconds).

ProtocolTypeFilter
Ethernet type II 16-bit protocol type in host byte order. Valid values are zero and 1,500 to 65,535. Set to zero to receive packets with any protocol type. The startup default value is zero.

EnableUnicastReceive
Set to TRUE to receive packets that are sent to the network device MAC address. The startup default value is FALSE.

EnableMulticastReceive
Set to TRUE to receive packets that are sent to any of the active multicast groups. The startup default value is FALSE.

EnableBroadcastReceive
Set to TRUE to receive packets that are sent to the network device broadcast address. The startup default value is FALSE.

EnablePromiscuousReceive
Set to TRUE to receive packets that are sent to any MAC address. Note that setting this field to TRUE may cause packet loss and degrade system performance on busy networks. The startup default value is FALSE.

FlushQueuesOnReset
Set to TRUE to drop queued packets when the configuration is changed. The startup default value is FALSE.

EnableReceiveTimestamps
Set to TRUE to timestamp all packets when they are received by the MNP. Note that timestamps may be unsupported in some MNP implementations. The startup default value is FALSE.

DisableBackgroundPolling
Set to TRUE to disable background polling in this MNP instance. Note that background polling may not be supported in all MNP implementations. The startup default value is FALSE, unless background polling is not supported.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The requested feature is unsupported in this MNP implementation.</td>
</tr>
</tbody>
</table>

continues on next page
This MNP child driver instance has not been configured. The default values are returned in MnpConfigData if it is not NULL.

The mode data could not be read.

### 25.1.4 EFI_MANAGED_NETWORK_PROTOCOL.Configure()

**Summary**

Sets or clears the operational parameters for the MNP child driver.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_MANAGED_NETWORK_CONFIGURE) (  
  IN EFI_MANAGED_NETWORK_PROTOCOL *This,  
  IN EFI_MANAGED_NETWORK_CONFIG_DATA *MnpConfigData OPTIONAL  
);
```

**Parameters**

*This

Pointer to the EFI_MANAGED_NETWORK_PROTOCOL instance.

*MnpConfigData

Pointer to configuration data that will be assigned to the MNP child driver instance. If NULL, the MNP child driver instance is reset to startup defaults and all pending transmit and receive requests are flushed. Type EFI_MANAGED_NETWORK_CONFIG_DATA is defined in EFI_MANAGED_NETWORK_PROTOCOL.GetModeData().

**Description**

The Configure() function is used to set, change, or reset the operational parameters for the MNP child driver instance. Until the operational parameters have been set, no network traffic can be sent or received by this MNP child driver instance. Once the operational parameters have been reset, no more traffic can be sent or received until the operational parameters have been set again.

Each MNP child driver instance can be started and stopped independently of each other by setting or resetting their receive filter settings with the Configure() function.

After any successful call to Configure(), the MNP child driver instance is started. The internal periodic timer (if supported) is enabled. Data can be transmitted and may be received if the receive filters have also been enabled.

**NOTE:** If multiple MNP child driver instances will receive the same packet because of overlapping receive filter settings, then the first MNP child driver instance will receive the original packet and additional instances will receive copies of the original packet.

**NOTE:** WARNING: Receive filter settings that overlap will consume extra processor and/or DMA resources and degrade system and network performance.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
</tbody>
</table>

continues on next page
Table 25.2 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <em>TRUE</em> :&lt;br&gt;• <em>This</em> is NULL.&lt;br&gt;• <em>MnpConfigData.ProtocolTypeFilter</em> is not valid.&lt;br&gt;• The operational data for the MNP child driver instance is unchanged.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources (usually memory) could not be allocated.&lt;br&gt;The MNP child driver instance has been reset to startup defaults.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The requested feature is unsupported in this [MNP] implementation.&lt;br&gt;The operational data for the MNP child driver instance is unchanged.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network or system error occurred.&lt;br&gt;The MNP child driver instance has been reset to startup defaults.</td>
</tr>
<tr>
<td>Other</td>
<td>The MNP child driver instance has been reset to startup defaults.</td>
</tr>
</tbody>
</table>

25.1.5 EFI_MANAGED_NETWORK_PROTOCOL.McastIpToMac()

**Summary**

Translates an IP multicast address to a hardware (MAC) multicast address. This function may be unsupported in some MNP implementations.

**Prototype**

```c
typedef EFI_STATUS (EFIAPICALLNAME *EFI_MANAGED_NETWORK_MCAST_IP_TO_MAC) (
    IN EFI_MANAGED_NETWORK_PROTOCOL *This,
    IN BOOLEAN Ipv6Flag,
    IN EFI_IP_ADDRESS *IpAddress,
    OUT EFI_MAC_ADDRESS *MacAddress
);
```

**Parameters**

- **This**
  Pointer to the *EFI_MANAGED_NETWORK_PROTOCOL* instance.

- **Ipv6Flag**
  Set to *TRUE* to if *IpAddress* is an IPv6 multicast address.<br>Set to *FALSE* if *IpAddress* is an IPv4 multicast address.

- **IpAddress**
  Pointer to the multicast IP address (in network byte order) to convert.

- **MacAddress**
  Pointer to the resulting multicast MAC address.

**Description**

25.1. EFI Managed Network Protocol
The `McastIpToMac()` function translates an IP multicast address to a hardware (MAC) multicast address. This function may be implemented by calling the underlying `EFI_SIMPLE_NETWORK.MCastIpToMac()` function, which may also be unsupported in some MNP implementations.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One of the following conditions is **TRUE**:
|                       |   • *This* is NULL.                                                          |
|                       |   • *IpAddress* is NULL.                                                    |
|                       |   • *IpAddress* is not a valid multicast IP address.                        |
|                       |   • *MacAddress* is NULL.                                                   |
| EFI_NOT_STARTED       | This MNP child driver instance has not been configured.                    |
| EFI_UNSUPPORTED      | The requested feature is unsupported in this MNP implementation.           |
| EFI_DEVICE_ERROR      | An unexpected network or system error occurred.                             |
| Other                 | The address could not be converted.                                         |

### 25.1.6 `EFI_MANAGED_NETWORK_PROTOCOL.Groups()`

#### Summary

Enables and disables receive filters for multicast address. This function may be unsupported in some MNP implementations.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_MANAGED_NETWORK_GROUPS) (  
    IN EFI_MANAGED_NETWORK_PROTOCOL *This,  
    IN BOOLEAN JoinFlag,  
    IN EFI_MAC_ADDRESS *MacAddress OPTIONAL  
);
```

#### Parameters

**This**

Pointer to the `EFI_MANAGED_NETWORK_PROTOCOL` instance.

**JoinFlag**

Set to `TRUE` to join this multicast group.
Set to `FALSE` to leave this multicast group.

**MacAddress**

Pointer to the multicast MAC group (address) to join or leave.

#### Description

The `Groups()` function only adds and removes multicast MAC addresses from the filter list. The MNP driver does not transmit or process Internet Group Management Protocol (IGMP) packets.

If `JoinFlag` is `FALSE` and `MacAddress` is `NULL`, then all joined groups are left.
Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• JoinFlag is TRUE and MacAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>• * MacAddress is not a valid multicast MAC address.</td>
</tr>
<tr>
<td></td>
<td>The MNP multicast group settings are unchanged.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This MNP child driver instance has not been configured.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The supplied multicast group is already joined.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The supplied multicast group is not joined.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network or system error occurred.</td>
</tr>
<tr>
<td></td>
<td>The MNP child driver instance has been reset to startup defaults.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The requested feature is unsupported in this MNP implementation.</td>
</tr>
<tr>
<td>Other</td>
<td>The requested operation could not be completed. The MNP multicast group</td>
</tr>
<tr>
<td></td>
<td>settings are unchanged.</td>
</tr>
</tbody>
</table>

25.1.7 EFI_MANAGED_NETWORK_PROTOCOL.Transmit()

Summary
Places asynchronous outgoing data packets into the transmit queue.

Prototype

```c
typedef EFI_STATUS
   (EFIAPIC *EFI_MANAGED_NETWORK_TRANSMIT) (    
   IN EFI_MANAGED_NETWORK_PROTOCOL *This,     
   IN EFI_MANAGED_NETWORK_COMPLETION_TOKEN *Token
   );
```

Parameters

This
Pointer to the EFI_MANAGED_NETWORK_PROTOCOL instance.

Token
Pointer to a token associated with the transmit data descriptor. Type EFI_MANAGED_NETWORK_COMPLETION_TOKEN is defined in “Related Definitions” below.

Description
The Transmit() function places a completion token into the transmit packet queue. This function is always asynchronous. The caller must fill in the Token.Event and Token.TxData fields in the completion token, and these fields cannot be NULL. When the transmit operation completes, the MNP updates the Token.Status field and the Token.Event is signaled.

NOTE There may be a performance penalty if the packet needs to be defragmented before it can be transmitted by the network device. Systems in which performance is critical should review the requirements and features of the underlying communications device and drivers.
Related Definitions

typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    union {
        EFI_MANAGED_NETWORK_RECEIVE_DATA *RxData;
        EFI_MANAGED_NETWORK_TRANSMIT_DATA *TxData;
    } Packet;
} EFI_MANAGED_NETWORK_COMPLETION_TOKEN;

Event

This Event will be signaled after the Status field is updated by the MNP. The type of Event must be EVT_NOTIFY_SIGNAL. The Task Priority Level (TPL) of Event must be lower than or equal to TPL_CALLBACK.

Status

This field will be set to one of the following values:

EFI_SUCCESS: The receive or transmit completed successfully.
EFI_ABORTED: The receive or transmit was aborted.
EFI_TIMEOUT: The transmit timeout expired.
EFI_DEVICE_ERROR: There was an unexpected system or network error.
EFI_NO_MEDIA: There was a media error

RxData

When this token is used for receiving, RxData is a pointer to the EFI_MANAGED_NETWORK_RECEIVE_DATA.

TxData

When this token is used for transmitting, TxData is a pointer to the EFI_MANAGED_NETWORK_TRANSMIT_DATA.

The EFI_MANAGED_NETWORK_COMPLETION_TOKEN structure is used for both transmit and receive operations. When it is used for transmitting, the Event and TxData fields must be filled in by the MNP client. After the transmit operation completes, the MNP updates the Status field and the Event is signaled.

When it is used for receiving, only the Event field must be filled in by the MNP client. After a packet is received, the MNP fills in the RxData and Status fields and the Event is signaled.
BOOLEAN MulticastFlag;
BOOLEAN PromiscuousFlag;
UINT16 ProtocolType;
VOID *DestinationAddress;
VOID *SourceAddress;
VOID *MediaHeader;
VOID *PacketData;
} EFI_MANAGED_NETWORK.Receive_DATA;

**Timestamp**
System time when the MNP received the packet. *Timestamp* is zero filled if receive timestamps are disabled or unsupported.

**RecycleEvent**
MNP clients must signal this event after the received data has been processed so that the receive queue storage can be reclaimed. Once *RecycleEvent* is signaled, this structure and the received data that is pointed to by this structure must not be accessed by the client.

**PacketLength**
Length of the entire received packet (media header plus the data).

**HeaderLength**
Length of the media header in this packet.

**AddressLength**
Length of a MAC address in this packet.

**DataLength**
Length of the data in this packet.

**BroadcastFlag**
Set to *TRUE* if this packet was received through the broadcast filter. (The destination MAC address is the broadcast MAC address.)

**MulticastFlag**
Set to *TRUE* if this packet was received through the multicast filter. (The destination MAC address is in the multicast filter list.)

**PromiscuousFlag**
Set to *TRUE* if this packet was received through the promiscuous filter. (The destination address does not match any of the other hardware or software filter lists.)

**ProtocolType**
16-bit protocol type in host byte order. Zero if there is no protocol type field in the packet header.

**DestinationAddress**
Pointer to the destination address in the media header.

**SourceAddress**
Pointer to the source address in the media header.

**MediaHeader**
Pointer to the first byte of the media header.

**PacketData**
Pointer to the first byte of the packet data (immediately following media header).

An *EFI_MANAGED_NETWORK.Receive_DATA* structure is filled in for each packet that is received by the MNP.
If multiple instances of this MNP driver can receive a packet, then the receive data structure and the received packet are duplicated for each instance of the MNP driver that can receive the packet.

```c
//**************************************************************
// EFI_MANAGED_NETWORK_TRANSMIT_DATA
//**************************************************************
typedef struct {
    EFI_MAC_ADDRESS *DestinationAddress OPTIONAL;
    EFI_MAC_ADDRESS *SourceAddress OPTIONAL;
    UINT16 ProtocolType OPTIONAL;
    UINT32 DataLength;
    UINT16 HeaderLength OPTIONAL;
    UINT16 FragmentCount;
    EFI_MANAGED_NETWORK_FRAGMENT_DATA FragmentTable[1];
} EFI_MANAGED_NETWORK_TRANSMIT_DATA;
```

**DestinationAddress**

Pointer to the destination MAC address if the media header is not included in *FragmentTable[]. If NULL, then the media header is already filled in *FragmentTable[].

**SourceAddress**

Pointer to the source MAC address if the media header is not included in *FragmentTable[]. Ignored if *DestinationAddress is NULL.

**ProtocolType**

The protocol type of the media header in host byte order. Ignored if *DestinationAddress is NULL.

**DataLength**

Sum of all *FragmentLength fields in *FragmentTable[] minus the media header length.

**HeaderLength**

Length of the media header if it is included in the *FragmentTable. Must be zero if *DestinationAddress is not NULL.

**FragmentCount**

Number of data fragments in *FragmentTable[]. This field cannot be zero.

**FragmentTable**

Table of data fragments to be transmitted. The first byte of the first entry in *FragmentTable[] is also the first byte of the media header or, if there is no media header, the first byte of payload. Type *EFI_MANAGED_NETWORK_FRAGMENT_DATA is defined below.

The *EFI_MANAGED_NETWORK_TRANSMIT_DATA structure describes a (possibly fragmented) packet to be transmitted.

The *DataLength field plus the *HeaderLength field must be equal to the sum of all of the *FragmentLength fields in the *FragmentTable.

If the media header is included in *FragmentTable[], then it cannot be split between fragments.

```c
//**************************************************************
// EFI_MANAGED_NETWORK_FRAGMENT_DATA
//**************************************************************
typedef struct {
    UINT32 FragmentLength;
    VOID *FragmentBuffer;
} EFI_MANAGED_NETWORK_FRAGMENT_DATA;
```
FragmentLength
Number of bytes in the FragmentBuffer. This field may not be set to zero.

FragmentBuffer
Pointer to the fragment data. This field may not be set to NULL.

The EFI_MANAGED_NETWORK_FRAGMENT_DATA structure describes the location and length of a packet fragment to be transmitted.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The transmit completion token was cached.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This MNP child driver instance has not been configured.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER| One or more of the following conditions is TRUE:

  • This is NULL.
  • Token is NULL.
  • Token.Event is NULL.
  • Token.TxD ata is NULL.
  • Token.TxD ata.DestinationAddress is not NULL and Token.TxD ata.HeaderLength is zero.
  • Token.TxD ata.FragmentCount is zero.
  • (Token.TxD ata.HeaderLength + Token.TxD ata.DataLength) is not equal to the sum of the Token.TxD ata.FragmentTable.[].FragmentLength fields.
  • One or more of the Token.TxD ata.FragmentTable.[].FragmentLength fields is zero.
  • One or more of the Token.TxD ata.FragmentTable.[].FragmentBuffer fields is NULL.
  • Token.TxD ata.DataLength is greater than MTU. |
| EFI_ACCESS_DENIED    | The transmit completion token is already in the transmit queue.|
| EFI_OUT_OF_RESOURCES | The transmit data could not be queued due to a lack of system resources (usually memory). |
| EFI_DEVICE_ERROR     | An unexpected system or network error occurred. The MNP child driver instance has been reset to startup defaults. |
| EFI_NOT_READY        | The transmit request could not be queued because the transmit queue is full. |
| EFI_NO_MEDIA         | There was a media error.                                     |

25.1.8 EFI_MANAGED_NETWORK_PROTOCOL.Receive()

Summary
Places an asynchronous receiving request into the receiving queue.

Prototype

typedef
EFI_STATUS
(EIFIAPI EFI_MANAGED_NETWORK.Receive)(
  IN EFI_MANAGED_NETWORK_PROTOCOL *This,

(continues on next page)
IN EFI_MANAGED_NETWORK_COMPLETION_TOKEN *Token
);

Parameters
This
Pointer to the EFI_MANAGED_NETWORK_PROTOCOL instance.

Token
Pointer to a token associated with the receive data descriptor. Type
EFI_MANAGED_NETWORK_COMPLETION_TOKEN is defined in EFI_MANAGED_NETWORK_PROTOCOL .Transmit().

Description
The Receive() function places a completion token into the receive packet queue. This function is always asynchronous.

The caller must fill in the Token.Event field in the completion token, and this field cannot be NULL. When the receive operation completes, the MNP updates the Token.Status and Token.RxData fields and the Token.Event is signaled.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The receive completion token was cached.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This MNP child driver instance has not been configured.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token.Event is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The transmit data could not be queued due to a lack of system resources</td>
</tr>
<tr>
<td></td>
<td>(usually memory).</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The MNP child driver</td>
</tr>
<tr>
<td></td>
<td>instance has been reset to startup defaults.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The receive completion token was already in the receive queue.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The receive request could not be queued because the receive queue is full.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

25.1.9 EFI_MANAGED_NETWORK_PROTOCOL.Cancel()

Summary
Aborts an asynchronous transmit or receive request.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_MANAGED_NETWORK_CANCEL)(
   IN EFI_MANAGED_NETWORK_PROTOCOL *This,
   IN EFI_MANAGED_NETWORK_COMPLETION_TOKEN *Token OPTIONAL
);

Parameters
This
Pointer to the `EFI_MANAGED_NETWORK_PROTOCOL` instance.

Token

Pointer to a token that has been issued by
`EFI_MANAGED_NETWORK_PROTOCOL.Transmit()` or
`EFI_MANAGED_NETWORK_PROTOCOL.Receive()`. If `NULL`, all pending tokens are aborted. Type
`EFI_MANAGED_NETWORK_COMPLETION_TOKEN` is defined in
`EFI_MANAGED_NETWORK_PROTOCOL.Transmit()`.

Description

The `Cancel()` function is used to abort a pending transmit or receive request. If the token is in the transmit or receive request queues, after calling this function, `Token.Status` will be set to `EFI_ABORTED` and then `Token.Event` will be signaled. If the token is not in one of the queues, which usually means that the asynchronous operation has completed, this function will not signal the token and `EFI_NOT_FOUND` is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The asynchronous I/O request was aborted and <code>Token.Event</code> was signaled.</td>
</tr>
<tr>
<td></td>
<td>When <code>Token</code> is <code>NULL</code>, all pending requests were aborted and their events</td>
</tr>
<tr>
<td></td>
<td>were signaled.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This MNP child driver instance has not been configured.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>This</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>When <code>Token</code> is not <code>NULL</code>, the asynchronous I/O request was not found in</td>
</tr>
<tr>
<td></td>
<td>the transmit or receive queue. It has either completed or was not issued by</td>
</tr>
<tr>
<td></td>
<td><code>Transmit()</code> and <code>Receive()</code>.</td>
</tr>
</tbody>
</table>

25.1.10 EFI_MANAGED_NETWORK_PROTOCOL.Poll()

Summary

Polls for incoming data packets and processes outgoing data packets.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_MANAGED_NETWORK_POLL) (IN EFI_MANAGED_NETWORK_PROTOCOL *This);
```

Parameters

This

Pointer to the `EFI_MANAGED_NETWORK_PROTOCOL` instance.

Description

The `Poll()` function can be used by network drivers and applications to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

Normally, a periodic timer event internally calls the `Poll()` function. But, in some systems, the periodic timer event may not call `Poll()` fast enough to transmit and/or receive all data packets without missing packets. Drivers and applications that are experiencing packet loss should try calling the `Poll()` function more often.
### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This MNP child driver instance has not been configured.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The MNP child driver instance has been reset to startup defaults.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>No incoming or outgoing data was processed. Consider increasing the polling rate.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Data was dropped out of the transmit and/or receive queue. Consider increasing the polling rate.</td>
</tr>
</tbody>
</table>
26.1 EFI Bluetooth Host Controller Protocol

26.1.1 EFI_BLUETOOTH_HC_PROTOCOL

Summary
This protocol abstracts the Bluetooth host controller layer message transmit and receive.

GUID
#define EFI_BLUETOOTH_HC_PROTOCOL_GUID
{ 0xb3930571, 0xbeba, 0x4fc5,
{ 0x92, 0x3, 0x94, 0x27, 0x24, 0x2e, 0x6a, 0x43 }}

Protocol Interface Structure
typedef struct _EFI_BLUETOOTH_HC_PROTOCOL {
  EFI_BLUETOOTH_HC_SEND_COMMAND SendCommand;
  EFI_BLUETOOTH_HC_RECEIVE_EVENT ReceiveEvent;
  EFI_BLUETOOTH_HC_ASYNC_RECEIVE_EVENT AsyncReceiveEvent;
  EFI_BLUETOOTH_HC_SEND_ACL_DATA SendACLData;
  EFI_BLUETOOTH_HC_RECEIVE_ACL_DATA ReceiveACLData;
  EFI_BLUETOOTH_HC_ASYNC_RECEIVE_ACL_DATA AsyncReceiveACLData;
  EFI_BLUETOOTH_HC_SEND_SCO_DATA SendSCOData;
  EFI_BLUETOOTH_HC_RECEIVE_SCO_DATA ReceiveSCOData;
  EFI_BLUETOOTH_HC_ASYNC_RECEIVE_SCO_DATA AsyncReceiveSCOData;
} EFI_BLUETOOTH_HC_PROTOCOL;

Parameters

SendCommand
Send HCI command packet. See the SendCommand() function description.

ReceiveEvent
Receive HCI event packets. See the ReceiveEvent() function description.

AsyncReceiveEvent
Non-blocking receive HCI event packets. See the AsyncReceiveEvent() function description.

SendACLData
Send HCI ACL (asynchronous connection-oriented) data packets. See the SendACLData() function description.

ReceiveACLData
Receive HCI ACL data packets. See the ReceiveACLData() function description.
AsyncReceiveACLData
Non-blocking receive HCI ACL data packets. See the AsyncReceiveACLData() function description.

SendSCOData
Send HCI synchronous (SCO and eSCO) data packets. See the SendSCOData() function description.

ReceiveSCOData
Receive HCI synchronous data packets. See the ReceiveSCOData() function description.

AsyncReceiveSCOData
Non-blocking receive HCI synchronous data packets. See the AsyncReceiveSCOData() function description.

Description

The EFI_BLUETOOTH_HC_PROTOCOL is used to transmit or receive HCI layer data packets. For detail of different HCI packet (command, event, ACL, SCO), please refer to Bluetooth specification.

26.1.2 BLUETOOTH_HC_PROTOCOL.SendCommand()

Summary
Send HCI command packet.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_HC_SEND_COMMAND)(
    IN EFI_BLUETOOTH_HC_PROTOCOL *This,
    IN OUT UINTN *BufferSize,
    IN VOID *Buffer,
    IN UINTN Timeout
);
```

Parameters

This
Pointer to the EFI_BLUETOOTH_HC_PROTOCOL instance.

BufferSize
On input, indicates the size, in bytes, of the data buffer specified by Buffer. On output, indicates the amount of data actually transferred.

Buffer
A pointer to the buffer of data that will be transmitted to Bluetooth host controller.

Timeout
Indicating the transfer should be completed within this time frame. The units are in milliseconds. If Timeout is 0, then the caller must wait for the function to be completed until EFI_SUCCESS or EFI_DEVICE_ERROR is returned.

Description

The SendCommand() function sends HCI command packet. Buffer holds the whole HCI command packet, including OpCode, OCF, OGF, parameter length, and parameters. When this function is returned, it just means the HCI command packet is sent, it does not mean the command is success or complete. Caller might need to wait a command status event to know the command status, or wait a command complete event to know if the command is completed. (see in Bluetooth specification, HCI Command Packet for more detail).

Status Codes Returned
26.1.3 BLUETOOTH_HC_PROTOCOL.ReceiveEvent()

Summary
Receive HCI event packet.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_HC_RECEIVE_EVENT)(
    IN EFI_BLUETOOTH_HC_PROTOCOL *This,
    IN OUT UINTN *BufferSize,
    OUT VOID *Buffer,
    IN UINTN Timeout
);
```

Parameters

This
Pointer to the `EFI_BLUETOOTH_HC_PROTOCOL` instance.

BufferSize
On input, indicates the size, in bytes, of the data buffer specified by `Buffer`. On output, indicates the amount of data actually transferred.

Buffer
A pointer to the buffer of data that will be received from Bluetooth host controller.

Timeout
Indicating the transfer should be completed within this time frame. The units are in milliseconds. If `Timeout` is 0, then the caller must wait for the function to be completed until `EFI_SUCCESS` or `EFI_DEVICE_ERROR` is returned.

Description

The `ReceiveEvent()` function receives HCI event packet. `Buffer` holds the whole HCI event packet, including `Event-Code`, parameter length, and parameters. (See in Bluetooth specification, HCI Event Packet for more detail.)

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The HCI event packet is received successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>* BufferSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>* BufferSize is 0.</td>
</tr>
<tr>
<td></td>
<td>* Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Sending HCI command packet fail due to timeout.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Sending HCI command packet fail due to host controller or device error.</td>
</tr>
</tbody>
</table>

continues on next page
26.1.4 BLUETOOTH_HC_PROTOCOL.AsyncReceiveEvent()

Summary
Receive HCI event packet in non-blocking way.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_HC_ASYNC_RECEIVE_EVENT) (
    IN EFI_BLUETOOTH_HC_PROTOCOL *This,
    IN BOOLEAN IsNewTransfer,
    IN UINTN PollingInterval,
    IN UINTN DataLength,
    IN EFI_BLUETOOTH_HC_ASYNC_FUNC_CALLBACK Callback,
    IN VOID *Context
);
```

Parameters

This
Pointer to the EFI_BLUETOOTH_HC_PROTOCOL instance.

IsNewTransfer
If TRUE, a new transfer will be submitted. If FALSE, the request is deleted.

PollingInterval
Indicates the periodic rate, in milliseconds, that the transfer is to be executed.

DataLength
Specifies the length, in bytes, of the data to be received.

Callback
The callback function. This function is called if the asynchronous transfer is completed.

Context
Data passed into Callback function. This is optional parameter and may be NULL.

Description
The AsyncReceiveEvent() function receives HCI event packet in non-blocking way. Data in Callback function holds the whole HCI event packet, including EventCode, parameter length, and parameters. (See in Bluetooth specification, HCI Event Packet for more detail.)

Related Definitions

Table 26.2 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• BufferSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• * BufferSize is 0.</td>
</tr>
<tr>
<td></td>
<td>• Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Receiving HCI event packet fail due to timeout.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Receiving HCI event packet fail due to host controller or device error.</td>
</tr>
</tbody>
</table>
typedef
EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_HC_ASYNC_FUNC_CALLBACK)(
  IN VOID *Data,
  IN UINTN DataLength,
  IN VOID *Context
);

Data
Data received via asynchronous transfer.

DataLength
The length of Data in bytes, received via asynchronous transfer.

Context
Context passed from asynchronous transfer request.

Status Codes Returned

<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The HCI asynchronous receive request is submitted successfully.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• DataLength is 0.</td>
</tr>
<tr>
<td></td>
<td>• IfisNewTransfer is TRUE, and an asynchronous receive request already exists.</td>
</tr>
</tbody>
</table>

26.1.5 BLUETOOTH_HC_PROTOCOL.SendACLData()

Summary
Send HCI ACL data packet.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_HC_SEND_ACL_DATA)(
  IN EFI_BLUETOOTH_HC_PROTOCOL *This,
  IN OUT UINTN *BufferSize,
  IN VOID *Buffer,
  IN UINTN Timeout
);

Parameters

This
Pointer to the EFI_BLUETOOTH_HC_PROTOCOL instance.

BufferSize
On input, indicates the size, in bytes, of the data buffer specified by Buffer. On output, indicates the amount of data actually transferred.

Buffer
A pointer to the buffer of data that will be transmitted to Bluetooth host controller.
Timeout
Indicating the transfer should be completed within this time frame. The units are in milliseconds. If Timeout is 0, then the caller must wait for the function to be completed until EFI_SUCCESS or EFI_DEVICE_ERROR is returned.

Description
The SendACLData() function sends HCI ACL data packet. Buffer holds the whole HCI ACL data packet, including Handle, PB flag, BC flag, data length, and data. (See in Bluetooth specification, HCI ACL Data Packet for more detail.)

The SendACLData() function and ReceiveACLData() function just send and receive data payload from application layer. In order to protect the payload data, the Bluetooth bus is required to call HCI_Set_Connection_Encryption command to enable hardware based encryption after authentication completed, according to pairing mode and host capability.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The HCI ACL data packet is sent successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• BufferSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• *BufferSize is 0.</td>
</tr>
<tr>
<td></td>
<td>• Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Sending HCI ACL data packet fail due to timeout.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Sending HCI ACL data packet fail due to host controller or device error.</td>
</tr>
</tbody>
</table>

26.1.6 BLUETOOTH_HC_PROTOCOL.ReceiveACLData()

Summary
Receive HCI ACL data packet.

Prototype

```c
typedef EFI_STATUS
(EFIAPIC *EFI_BLUETOOTH_HC_RECEIVE_ACL_DATA)(
    IN EFI_BLUETOOTH_HC_PROTOCOL *This,
    IN OUT UINTN *BufferSize,
    OUT VOID *Buffer,
    IN UINTN Timeout
);
```

Parameters

This
Pointer to the EFI_BLUETOOTH_HC_PROTOCOL instance.

BufferSize
On input, indicates the size, in bytes, of the data buffer specified by Buffer. On output, indicates the amount of data actually transferred.

Buffer
A pointer to the buffer of data that will be received from Bluetooth host controller.
Timeout
Indicating the transfer should be completed within this time frame. The units are in milliseconds. If Timeout is 0, then the caller must wait for the function to be completed until EFI_SUCCESS or EFI_DEVICE_ERROR is returned.

Description
The ReceiveACLData() function receives HCI ACL data packet. Buffer holds the whole HCI ACL data packet, including Handle, PB flag, BC flag, data length, and data. (See in Bluetooth specification, HCI ACL Data Packet for more detail.)

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The HCI ACL data packet is received successfully.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more of the following conditions is TRUE:
|                   | • BufferSize is NULL.                           |
|                   | • *BufferSize is 0.                             |
|                   | • Buffer is NULL.                               |
| EFI_TIMEOUT       | Receiving HCI ACL data packet fail due to timeout.|
| EFI_DEVICE_ERROR  | Receiving HCI ACL data packet fail due to host controller or device error.|

26.1.7 BLUETOOTH_HC_PROTOCOL.AsyncReceiveACLData()

Summary
Receive HCI ACL data packet in non-blocking way.

Prototype

define EFI_STATUS (EFI_API *EFI_BLUETOOTH_HC_ASYNC_RECEIVE_ACL_DATA) (IN EFI_BLUETOOTH_HC_PROTOCOL *This, IN BOOLEAN IsNewTransfer, IN UINTN PollingInterval, IN UINTN DataLength, IN EFI_BLUETOOTH_HC_ASYNC_FUNC_CALLBACK Callback, IN VOID *Context);

Parameters
This
Pointer to the EFI_BLUETOOTH_HC_PROTOCOL instance.

IsNewTransfer
If TRUE, a new transfer will be submitted.
If FALSE, the request is deleted.

PollingInterval
Indicates the periodic rate, in milliseconds, that the transfer is to be executed.
**DataLength**
Specifies the length, in bytes, of the data to be received.

**Callback**
The callback function. This function is called if the asynchronous transfer is completed.

**Context**
Data passed into `Callback` function. This is optional parameter and may be NULL.

**Description**
The `AsyncReceiveACLData()` function receives HCI ACL data packet in non-blocking way. *Data* in `Callback` holds the whole HCI ACL data packet, including Handle, PB flag, BC flag, data length, and data. (See in Bluetooth specification, HCI ACL Data Packet for more detail.)

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The HCI asynchronous receive request is submitted successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• <code>DataLength</code> is 0.</td>
</tr>
<tr>
<td></td>
<td>• If <code>IsNewTransfer</code> is <strong>TRUE</strong>, and an asynchronous receive request already</td>
</tr>
<tr>
<td></td>
<td>exists.</td>
</tr>
</tbody>
</table>

### 26.1.8 BLUETOOTH_HC_PROTOCOL.SendSCOData()

**Summary**
Send HCI SCO data packet.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_HC_SEND_SCO_DATA)(
    IN EFI_BLUETOOTH_HC_PROTOCOL *This,
    IN OUT UINTN *BufferSize,
    IN VOID *Buffer,
    IN UINTN Timeout
);
```

**Parameters**

**This**
Pointer to the `EFI_BLUETOOTH_HC_PROTOCOL` instance.

**BufferSize**
On input, indicates the size, in bytes, of the data buffer specified by `Buffer`. On output, indicates the amount of data actually transferred.

**Buffer**
A pointer to the buffer of data that will be transmitted to Bluetooth host controller.

**Timeout**
Indicating the transfer should be completed within this time frame. The units are in milliseconds. If `Timeout` is 0, then the caller must wait for the function to be completed until `EFI_SUCCESS` or `EFI_DEVICE_ERROR` is returned.
Description

The `SendSCOData()` function sends HCI SCO data packet. *Buffer* holds the whole HCI SCO data packet, including `ConnectionHandle`, `PacketStatus` flag, data length, and data. (See in Bluetooth specification, HCI Synchronous Data Packet for more detail.)

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>The HCI SCO data packet is sent successfully.</td>
</tr>
<tr>
<td><strong>EFI_UNSUPPORTED</strong></td>
<td>The implementation does not support HCI SCO transfer.</td>
</tr>
<tr>
<td><strong>EFI_INVALID_PARAMETER</strong></td>
<td>One or more of the following conditions is <strong>TRUE</strong>: &lt;br&gt;• <em>BufferSize</em> is NULL.  &lt;br&gt;• <em>BufferSize</em> is 0.  &lt;br&gt;• <em>Buffer</em> is NULL.</td>
</tr>
<tr>
<td><strong>EFI_TIMEOUT</strong></td>
<td>Sending HCI SCO data packet fail due to timeout.</td>
</tr>
<tr>
<td><strong>EFI_DEVICE_ERROR</strong></td>
<td>Sending HCI SCO data packet fail due to host controller or device error.</td>
</tr>
</tbody>
</table>

26.1.9 `BLUETOOTH_HC_PROTOCOL.ReceiveSCOData()`

**Summary**

Receive HCI SCO data packet.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_HC_RECEIVE_SCO_DATA)(
    IN EFI_BLUETOOTH_HC_PROTOCOL *This,
    IN OUT UINTN *BufferSize,
    OUT VOID *Buffer,
    IN UINTN Timeout
);
```

**Parameters**

**This**

Pointer to the `EFI_BLUETOOTH_HC_PROTOCOL` instance.

**BufferSize**

On input, indicates the size, in bytes, of the data buffer specified by *Buffer*. On output, indicates the amount of data actually transferred.

**Buffer**

A pointer to the buffer of data that will be received from Bluetooth host controller.

**Timeout**

Indicating the transfer should be completed within this time frame. The units are in milliseconds. If *Timeout* is 0, then the caller must wait for the function to be completed until **EFI_SUCCESS** or **EFI_DEVICE_ERROR** is returned.

**Description**

---

26.1. EFI Bluetooth Host Controller Protocol 1045
The `ReceiveSCOData()` function receives HCI SCO data packet. `Buffer` holds the whole HCI SCO data packet, including `ConnectionHandle`, `PacketStatus` flag, data length, and data. (See in Bluetooth specification, HCI Synchronous Data Packet for more detail.)

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The HCI SCO data packet is received successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• BufferSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• <em>BufferSize</em> is 0.</td>
</tr>
<tr>
<td></td>
<td>• Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Receiving HCI SCO data packet fail due to timeout.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Receiving HCI SCO data packet fail due to host controller or device error.</td>
</tr>
</tbody>
</table>

### 26.1.10 BLUETOOTH_HC_PROTOCOL.AsyncReceiveSCOData()

#### Summary
Receive HCI SCO data packet in non-blocking way.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_HC_ASYNC_RECEIVE_SCO_DATA) (    
    IN EFI_BLUETOOTH_HC_PROTOCOL *This,    
    IN BOOLEAN IsNewTransfer,    
    IN UINTN PollingInterval,    
    IN UINTN DataLength,    
    IN EFI_BLUETOOTH_HC_ASYNC_FUNC_CALLBACK Callback,    
    IN VOID *Context    
);```

#### Parameters

- **This**
  Pointer to the `EFI_BLUETOOTH_HC_PROTOCOL` instance.

- **IsNewTransfer**
  If `TRUE`, a new transfer will be submitted. If `FALSE`, the request is deleted.

- **PollingInterval**
  Indicates the periodic rate, in milliseconds, that the transfer is to be executed.

- **DataLength**
  Specifies the length, in bytes, of the data to be received.

- **Callback**
  The callback function. This function is called if the asynchronous transfer is completed.

- **Context**
  Data passed into `Callback` function. This is optional parameter and may be `NULL`.

#### Description

26.1. EFI Bluetooth Host Controller Protocol 1046
The AsyncReceiveSCOData() function receives HCI SCO data packet in non-blocking way. Data in Callback holds the whole HCI SCO data packet, including ConnectionHandle, PacketStatus flag, data length, and data. (See in Bluetooth specification, HCI SCO Data Packet for more detail.)

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The HCI asynchronous receive request is submitted successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• DataLength is 0.</td>
</tr>
<tr>
<td></td>
<td>• If IsNewTransfer is TRUE, and an asynchronous receive request already exists.</td>
</tr>
</tbody>
</table>

26.2  EFI Bluetooth Bus Protocol

26.2.1  EFI_BLUETOOTH_IO_SERVICE_BINDING_PROTOCOL

Summary
The EFI Bluetooth IO Service Binding Protocol is used to locate EFI Bluetooth IO Protocol drivers to create and destroy child of the driver to communicate with other Bluetooth device by using Bluetooth IO protocol.

GUID

```c
#define EFI_BLUETOOTH_IO_SERVICE_BINDING_PROTOCOL_GUID \
  { 0x388278d3, 0x7b85, 0x42f0, \
    { 0xab, 0xa9, 0xfb, 0x4b, 0xfd, 0x69, 0xf5, 0xab } }
```

Description
The Bluetooth IO consumer need locate EFI_BLUETOOTH_IO_SERVICE_BINDING_PROTOCOL and call CreateChild() to create a new child of EFI_BLUETOOTH_IO_PROTOCOL instance. Then use EFI_BLUETOOTH_IO_PROTOCOL for Bluetooth communication. After use, the Bluetooth IO consumer need call DestroyChild() to destroy it.

26.2.2  EFI_BLUETOOTH_IO_PROTOCOL

Summary
This protocol provides service for Bluetooth L2CAP (Logical Link Control and Adaptation Protocol) and SDP (Service Discovery Protocol).

GUID

```c
#define EFI_BLUETOOTH_IO_PROTOCOL_GUID \
  { 0x467313de, 0x4e30, 0x43f1, \
    { 0x94, 0x3e, 0x32, 0x3f, 0x89, 0x84, 0x5d, 0xb5 } }
```

Protocol Interface Structure
typedef struct _EFI_BLUETOOTH_IO_PROTOCOL {
    EFI_BLUETOOTH_IO_GET_DEVICE_INFO GetDeviceInfo;
    EFI_BLUETOOTH_IO_GET_SDP_INFO GetSdpInfo;
    EFI_BLUETOOTH_IO_L2CAP_RAW_SEND L2CapRawSend;
    EFI_BLUETOOTH_IO_L2CAP_RAW_RECEIVE L2CapRawReceive;
    EFI_BLUETOOTH_IO_L2CAP_RAW_ASYNC_RECEIVE L2CapRawAsyncReceive;
    EFI_BLUETOOTH_IO_L2CAP_SEND L2CapSend;
    EFI_BLUETOOTH_IO_L2CAP_RECEIVE L2CapReceive;
    EFI_BLUETOOTH_IO_L2CAP_ASYNC_RECEIVE L2CapAsyncReceive;
    EFI_BLUETOOTH_IO_L2CAP_CONNECT L2CapConnect;
    EFI_BLUETOOTH_IO_L2CAP_DISCONNECT L2CapDisconnect;
    EFI_BLUETOOTH_IO_L2CAP_REGISTER_SERVICE L2CapRegisterService;
} EFI_BLUETOOTH_IO_PROTOCOL;

Parameters

GetDeviceInfo
Get Bluetooth device Information. See the GetDeviceInfo() function description.

GetSdpInfo
Get Bluetooth device SDP information. See the GetSdpInfo() function description.

L2CapRawSend
Send L2CAP message (including L2CAP header). See the L2CapRawSend() function description.

L2CapRawReceive
Receive L2CAP message (including L2CAP header). See the L2CapRawReceive() function description.

L2CapRawAsyncReceive
Non-blocking receive L2CAP message (including L2CAP header). See the L2CapRawAsyncReceive() function description.

L2CapSend
Send L2CAP message (excluding L2CAP header) to a specific channel. See the L2CapSend() function description.

L2CapReceive
Receive L2CAP message (excluding L2CAP header) from a specific channel. See the L2CapReceive() function description.

L2CapAsyncReceive
Non-blocking receive L2CAP message (excluding L2CAP header) from a specific channel. See the L2CapAsyncReceive() function description.

L2CapConnect
Do L2CAP connection. See the L2CapConnect() function description.

L2CapDisconnect
Do L2CAP disconnection. See the L2CapDisconnect() function description.

L2CapRegisterService
Register L2CAP callback function for special channel. See the L2CapRegisterService() function description.

Description
The EFI_BLUETOOTH_IO_PROTOCOL provides services in L2CAP protocol and SDP protocol. For detail of L2CAP packet format, and SDP service, please refer to Bluetooth specification.
26.2.3 BLUETOOTH_IO_PROTOCOL.GetDeviceInfo

Summary
Get Bluetooth device information.

Prototype

```c
typedef EFI_STATUS
(EIFIAPI *EFI_BLUETOOTH_IO_GET_DEVICE_INFO)(
    IN EFI_BLUETOOTH_IO_PROTOCOL *This,
    OUT UINTN *DeviceInfoSize,
    OUT VOID **DeviceInfo
);
```

Parameters

This
Pointer to the EFI_BLUETOOTH_IO_PROTOCOL instance.

DeviceInfoSize
A pointer to the size, in bytes, of the DeviceInfo buffer.

DeviceInfo
A pointer to a callee allocated buffer that returns Bluetooth device information. Callee allocates this buffer by using EFI Boot Service AllocatePool().

Description

The GetDeviceInfo() function returns Bluetooth device information. The size of DeviceInfo structure should never be assumed and the value of DeviceInfoSize is the only valid way to know the size of DeviceInfo.

Related Definitions

```c
typedef struct {
    UINT32 Version;
    BLUETOOTH_ADDRESS BD_ADDR;
    UINT8 PageScanRepetitionMode;
    BLUETOOTH_CLASS_OF_DEVICE ClassOfDevice;
    UINT16 ClockOffset;
    UINT8 RSSI;
    UINT8 ExtendedInquiryResponse [240];
} EFI_BLUETOOTH_DEVICE_INFO;
```

Version
The version of the structure. A value of zero represents the EFI_BLUETOOTH_DEVICE_INFO structure as defined here. Future version of this specification may extend this data structure in a backward compatible way and increase the value of Version.

BD_ADDR
48bit Bluetooth device address.

PageScanRepetitionMode*
Bluetooth PageScanRepetitionMode. See Bluetooth specification for detail.

ClassOfDevice
Bluetooth ClassOfDevice. See Bluetooth specification for detail.
ClockOffset

Bluetooth CloseOffset. See Bluetooth specification for detail.

RSSI

Bluetooth RSSI. See Bluetooth specification for detail.

ExtendedInquiryResponse

Bluetooth ExtendedInquiryResponse. See Bluetooth specification for detail.

typedef struct {
    UINT8 Address [6];
} BLUETOOTH_ADDRESS;

typedef struct {
    UINT8 FormatType:2;
    UINT8 MinorDeviceClass:6;
    UINT16 MajorDeviceClass:5;
    UINT16 MajorServiceClass:11;
} BLUETOOTH_CLASS_OF_DEVICE;

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth device information is returned successfully.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A hardware error occurred trying to retrieve the Bluetooth device information.</td>
</tr>
</tbody>
</table>

26.2.4 BLUETOOTH_IO_PROTOCOL.GetSdpInfo

Summary

Get Bluetooth SDP information.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_IO_GET_SDP_INFO)(
    IN EFI_BLUETOOTH_IO_PROTOCOL *This,
    OUT UINTN *SdpInfoSize,
    OUT VOID **SdpInfo
);

Parameters

This

Pointer to the EFI_BLUETOOTH_IO_PROTOCOL instance.

SdpInfoSize

A pointer to the size, in bytes, of the SdpInfo buffer.

SdpInfo

A pointer to a callee allocated buffer that returns Bluetooth SDP information. Callee allocates this buffer by using EFI Boot Service AllocatePool().

Description
The `GetSdpInfo()` function returns Bluetooth SDP information. The size of `SdpInfo` structure should never be assumed and the value of `SdpInfoSize` is the only valid way to know the size of `SdpInfo`.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth SDP information is returned successfully.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A hardware error occurred trying to retrieve the Bluetooth SDP information.</td>
</tr>
</tbody>
</table>

### 26.2.5 BLUETOOTH_IO_PROTOCOL.L2CapRawSend

Summary

Send L2CAP message (including L2CAP header).

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_IO_L2CAP_RAW_SEND)(
    IN EFI_BLUETOOTH_IO_PROTOCOL *This,
    IN OUT UINTN *BufferSize,
    IN VOID *Buffer,
    IN UINTN Timeout
);
```

Parameters

**This**

Pointer to the `EFI_BLUETOOTH_IO_PROTOCOL` instance.

**BufferSize**

On input, indicates the size, in bytes, of the data buffer specified by `Buffer`. On output, indicates the amount of data actually transferred.

**Buffer**

A pointer to the buffer of data that will be transmitted to Bluetooth L2CAP layer.

**Timeout**

Indicating the transfer should be completed within this time frame. The units are in milliseconds. If Timeout is 0, then the caller must wait for the function to be completed until EFI_SUCCESS or EFI_DEVICE_ERROR is returned.

Description

`EFI iSCSI Initiator Name Protocol` sends L2CAP layer message (including L2CAP header). `Buffer` holds the whole L2CAP message, including Length, ChannelID, and information payload. (See the Bluetooth specification, L2CAP Data Packet Format for more details.)

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The L2CAP message is sent successfully.</td>
</tr>
</tbody>
</table>
Table 26.12 – continued from previous page

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• BufferSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• BufferSize is 0.</td>
</tr>
<tr>
<td></td>
<td>• Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Sending L2CAP message fail due to timeout.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Sending L2CAP message fail due to host controller or device error.</td>
</tr>
</tbody>
</table>

26.2.6 BLUETOOTH_IO_PROTOCOL.L2CapRawReceive

**Summary**

Receive L2CAP message (including L2CAP header).

**Prototype**

```c
typedef EFI_STATUS (EFIAPI * EFI_BLUETOOTH_IO_L2CAP_RAW_RECEIVE) (  
    IN EFI_BLUETOOTH_IO_PROTOCOL *This,  
    IN OUT UINTN *BufferSize,  
    OUT VOID *Buffer,  
    IN UINTN Timeout  
    );
```

**Parameters**

**This**

Pointer to the EFI_BLUETOOTH_IO_PROTOCOL instance.

**BufferSize**

On input, indicates the size, in bytes, of the data buffer specified by Buffer. On output, indicates the amount of data actually transferred.

**Buffer**

A pointer to the buffer of data that will be received from Bluetooth L2CAP layer.

**Timeout**

Indicating the transfer should be completed within this time frame. The units are in milliseconds. If Timeout is 0, then the caller must wait for the function to be completed until EFI_SUCCESS or EFI_DEVICE_ERROR is returned.

**Description**

The L2CapRawReceive() function receives L2CAP layer message (including L2CAP header). Buffer holds the whole L2CAP message, including Length, ChannelID, and information payload. (See in Bluetooth specification, L2CAP Data Packet Format for more detail.)

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The L2CAP message is received successfully.</td>
</tr>
</tbody>
</table>

continues on next page
Table 26.13 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• BufferSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• *BufferSize is 0.</td>
</tr>
<tr>
<td></td>
<td>• Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Receiving L2CAP message fail due to timeout.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Receiving L2CAP message fail due to host controller or device error.</td>
</tr>
</tbody>
</table>

### 26.2.7 BLUETOOTH_IO_PROTOCOL.L2CapRawAsyncReceive

**Summary**
Receive L2CAP message (including L2CAP header) in non-blocking way.

**Prototype**
```c
typedef EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_IO_L2CAP_RAW_ASYNC_RECEIVE)(
    IN EFI_BLUETOOTH_IO_PROTOCOL *This,
    IN BOOLEAN IsNewTransfer,
    IN UINTN PollingInterval,
    IN UINTN DataLength,
    IN EFI_BLUETOOTH_IO_ASYNC_FUNC_CALLBACK Callback,
    IN VOID *Context
);
```

**Parameters**

**This**  
Pointer to the `EFI_BLUETOOTH_IO_PROTOCOL` instance.

**IsNewTransfer**

If **TRUE**, a new transfer will be submitted.  
If **FALSE**, the request is deleted.

**PollingInterval**  
Indicates the periodic rate, in milliseconds, that the transfer is to be executed.

**DataLength**
Specifies the length, in bytes, of the data to be received.

**Callback**
The callback function. This function is called if the asynchronous transfer is completed.

**Context**
Data passed into `Callback` function. This is optional parameter and may be **NULL**.

**Description**

The `L2CapRawAsyncReceive()` function receives L2CAP layer message (including L2CAP header) in non-blocking way. Data in `Callback` function holds the whole L2CAP message, including Length, ChannelID, and information payload. (See in Bluetooth specification, L2CAP Data Packet Format for more detail.)
Related Definitions

typedef 
EFI_STATUS 
(EIFIAPI *EFI_BLUETOOTH_IO_ASYNC_FUNC_CALLBACK) ( 
    IN UINT16 ChannelID, 
    IN VOID *Data, 
    IN UINTN DataLength, 
    IN VOID *Context 
); 

ChannelID
    Bluetooth L2CAP message channel ID.

Data
    Data received via asynchronous transfer.

DataLength
    The length of Data in bytes, received via asynchronous transfer.

Context
    Context passed from asynchronous transfer request.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The L2CAP asynchronous receive request is submitted successfully.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more of the following conditions is TRUE:  
  • DataLength is 0.  
  • If IsNewTransfer is TRUE, and an asynchronous receive request already exists. |

26.2.8 BLUETOOTH_IO_PROTOCOL.L2CapSend

Summary
Send L2CAP message (excluding L2CAP header) to a specific channel.

Prototype

typedef 
EFI_STATUS 
(EIFIAPI *EFI_BLUETOOTH_IO_L2CAP_SEND)( 
    IN EFI_BLUETOOTH_IO_PROTOCOL *This, 
    IN EFI_HANDLE Handle, 
    IN OUT UINTN *BufferSize, 
    IN VOID *Buffer, 
    IN UINTN Timeout 
); 

Parameters

This
    Pointer to the EFI_BLUETOOTH_IO_PROTOCOL instance.
Handle
A handle created by `EFI_BLUETOOTH_IO_PROTOCOL.L2CapConnect` indicates which channel to send.

BufferSize
On input, indicates the size, in bytes, of the data buffer specified by Buffer. On output, indicates the amount of data actually transferred.

Buffer
A pointer to the buffer of data that will be transmitted to Bluetooth L2CAP layer.

Timeout
Indicating the transfer should be completed within this time frame. The units are in milliseconds. If Timeout is 0, then the caller must wait for the function to be completed until `EFI_SUCCESS` or `EFI_DEVICE_ERROR` is returned.

Description
The `L2CapSend()` function sends L2CAP layer message (excluding L2CAP header) to Bluetooth channel indicated by Handle. Buffer only holds information payload. (See in Bluetooth specification, L2CAP Data Packet Format for more detail.) Handle

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The L2CAP message is sent successfully.</td>
</tr>
<tr>
<td><code>EFI_NOT_FOUND</code></td>
<td>Handle is invalid or not found.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• BufferSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• *BufferSize is 0.</td>
</tr>
<tr>
<td></td>
<td>• Buffer is NULL.</td>
</tr>
<tr>
<td><code>EFI_TIMEOUT</code></td>
<td>Sending L2CAP message fail due to timeout.</td>
</tr>
<tr>
<td><code>EFI_DEVICE_ERROR</code></td>
<td>Sending L2CAP message fail due to host controller or device error.</td>
</tr>
</tbody>
</table>

26.2.9 BLUETOOTH_IO_PROTOCOL.L2CapReceive

Summary
Receive L2CAP message (excluding L2CAP header) from a specific channel.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_IO_L2CAP_RECEIVE)(
    IN EFI_BLUETOOTH_IO_PROTOCOL *This,
    IN EFI_HANDLE Handle,
    OUT UINTN *BufferSize,
    OUT VOID **Buffer,
    IN UINTN Timeout
);
```

Parameters

This
Pointer to the `EFI_BLUETOOTH_IO_PROTOCOL` instance.
Handle
A handle created by `EFI_BLUETOOTH_IO_PROTOCOL.L2CapConnect` indicates which channel to receive.

BufferSize
Indicates the size, in bytes, of the data buffer specified by Buffer.

Buffer
A pointer to the buffer of data that will be received from Bluetooth L2CAP layer. Callee allocates this buffer by using EFI Boot Service `AllocatePool()`.

Timeout
Indicating the transfer should be completed within this time frame. The units are in milliseconds. If `Timeout` is 0, then the caller must wait for the function to be completed until `EFI_SUCCESS` or `EFI_DEVICE_ERROR` is returned.

Description
The `L2CapReceive()` function receives L2CAP layer message (excluding L2CAP header) from Bluetooth channel indicated by Handle. Buffer only holds information payload. (See in Bluetooth specification, L2CAP Data Packet Format for more detail.)

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The L2CAP message is received successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Handle is invalid or not found.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• BufferSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• BufferSize is 0.</td>
</tr>
<tr>
<td></td>
<td>• Buffer is NULL.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Receiving L2CAP message fail due to timeout.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Receiving L2CAP message fail due to host controller or device error.</td>
</tr>
</tbody>
</table>

26.2.10 BLUETOOTH_IO_PROTOCOL.L2CapAsyncReceive

Summary
Receive L2CAP message (including L2CAP header) in non-blocking way from a specific channel.

Prototype

```c
typedef EFI_STATUS
(EFI_API *EFI_BLUETOOTH_IO_L2CAP_ASYNC_RECEIVE)(
    IN EFI_BLUETOOTH_IO_PROTOCOL *This,
    IN EFI_HANDLE Handle,
    IN EFI_BLUETOOTH_IO_CHANNEL_SERVICE_CALLBACK Callback,
    IN VOID *Context
)(
```

Parameters

This
Pointer to the `EFI_BLUETOOTH_IO_PROTOCOL` instance.

Handle
A handle created by `EFI_BLUETOOTH_IO_PROTOCOL.L2CapConnect` indicates which channel to receive.
Callback
The callback function. This function is called if the asynchronous transfer is completed.

Context
Data passed into Callback function. This is optional parameter and may be NULL.

Description
The L2CapAsyncReceive() function receives L2CAP layer message (excluding L2CAP header) in non-blocking way from Bluetooth channel indicated by Handle. Data in Callback function only holds information payload. (See in Bluetooth specification, L2CAP Data Packet Format for more detail.)

Related Definitions

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_IO_CHANNEL_SERVICE_CALLBACK) (
    IN VOID *Data,
    IN UINTN DataLength,
    IN VOID *Context
);
```

Data
Data received via asynchronous transfer.

DataLength
The length of Data in bytes, received via asynchronous transfer.

Context
Context passed from asynchronous transfer request.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The L2CAP asynchronous receive request is submitted successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Handle is invalid or not found.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• DataLength is 0.</td>
</tr>
<tr>
<td></td>
<td>• If an asynchronous receive request already exists on same Handle.</td>
</tr>
</tbody>
</table>

26.2.11 BLUETOOTH_IO_PROTOCOL.L2CapConnect

Summary
Do L2CAP connection.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_IO_L2CAP_CONNECT) (
    IN EFI_BLUETOOTH_IO_PROTOCOL *This,
    OUT EFI_HANDLE *Handle,
    IN UINT16 Psm,
    IN UINT16 Mtu,
);
```
IN EFI_BLUETOOTH_IO_CHANNEL_SERVICE_CALLBACK Callback,
IN VOID *Context
);

Parameters

This  
Pointer to the EFI_BLUETOOTH_IO_PROTOCOL instance.
Handle  
A handle to indicate this L2CAP connection.
Psm  
Bluetooth PSM. See Bluetooth specification for detail.
Mtu  
Bluetooth MTU. See Bluetooth specification for detail.
Callback  
The callback function. This function is called whenever there is message received in this channel.
Context  
Data passed into Callback function. This is optional parameter and may be NULL.

Description

The L2CapConnect() function does all necessary steps for Bluetooth L2CAP layer connection in blocking way. It might take long time. Once this function is returned Handle is created to indicate the connection.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth L2CAP layer connection is created successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• Handle is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A hardware error occurred trying to do Bluetooth L2CAP connection.</td>
</tr>
</tbody>
</table>

26.2.12 BLUETOOTH_IO_PROTOCOL.L2CapDisconnect

Summary

Do L2CAP disconnection.

Prototype

typedef
EFI_STATUS
(EFIAPICALL _EfiBluetoohIoL2CapDisconnect)(
    IN EFI_BLUETOOTH_IO_PROTOCOL *This,
    IN EFI_HANDLE Handle
);

Parameters

This  
Pointer to the EFI_BLUETOOTH_IO_PROTOCOL instance.
Handle
A handle to indicate this L2CAP connection.

Description
The L2CapDisconnect() function does all necessary steps for Bluetooth L2CAP layer disconnection in blocking way. It might take long time. Once this function is returned Handle is no longer valid.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth L2CAP layer disconnection is created successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Handle is invalid or not found.</td>
</tr>
<tr>
<td>EFI DEVICE_ERROR</td>
<td>A hardware error occurred trying to do Bluetooth L2CAP disconnection.</td>
</tr>
</tbody>
</table>

26.2.13 BLUETOOTH_IO_PROTOCOL.L2CapRegisterService

Summary
Register L2CAP callback function for special channel.

Prototype

typedef
 EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_IO_L2CAP_REGISTER_SERVICE)(
  IN EFI_BLUETOOTH_IO_PROTOCOL *This,
  OUT EFI_HANDLE *Handle,
  IN UINT16 Psm,
  IN UINT16 Mtu,
  IN EFI_BLUETOOTH_IO_CHANNEL_SERVICE_CALLBACK Callback,
  IN VOID *Context
);

Parameters

This
Pointer to the EFI_BLUETOOTH_IO_PROTOCOL instance.

Handle

Psm
Bluetooth PSM. See Bluetooth specification for detail.

Mtu
Bluetooth MTU. See Bluetooth specification for detail.

Callback
The callback function. This function is called whenever there is message received in this channel. NULL means unregister.

Context
Data passed into Callback function. This is optional parameter and may be NULL.

Description
The L2CapRegisterService() function registers L2CAP callback function for a special channel. Once this function is returned Handle is created to indicate the connection.

Status Codes Returned
### 26.3 EFI Bluetooth Configuration Protocol

#### 26.3.1 EFI_BLUETOOTH_CONFIG_PROTOCOL

**Summary**

This protocol abstracts user interface configuration for Bluetooth device.

**GUID**

```c
#define EFI_BLUETOOTH_CONFIG_PROTOCOL_GUID \
{ 0x62960cf3, 0x40ff, 0x4263,\ 
  { 0xa7, 0x7c, 0xdf, 0xde, 0xbd, 0x19, 0x1b, 0x4b }}
```

**Protocol Interface Structure**

```c
typedef struct _EFI_BLUETOOTH_CONFIG_PROTOCOL {
    EFI_BLUETOOTH_CONFIG_INIT Init;
    EFI_BLUETOOTH_CONFIG_SCAN Scan;
    EFI_BLUETOOTH_CONFIG_CONNECT Connect;
    EFI_BLUETOOTH_CONFIG_DISCONNECT Disconnect;
    EFI_BLUETOOTH_CONFIG_GET_DATA GetData;
    EFI_BLUETOOTH_CONFIG_SET_DATA SetData;
    EFI_BLUETOOTH_CONFIG_GET_REMOTE_DATA GetRemoteData;
    EFI_BLUETOOTH_CONFIG_REGISTER_PIN_CALLBACK RegisterPinCallback;
    EFI_BLUETOOTH_CONFIG/php-get-link-key-callback RegisterGetLinkKeyCallback;
    EFI_BLUETOOTH_CONFIG/php-set-link-key-callback RegisterSetLinkKeyCallback;
    EFI_BLUETOOTH_CONFIG/php-register-connect-complete-callback RegisterConnectCompleteCallback;
} EFI_BLUETOOTH_CONFIG_PROTOCOL;
```

**Parameters**

- **Init**
  
  Initialize Bluetooth host controller and local device. See the `Init()` function description.

- **Scan**
  
  Scan Bluetooth device. See the `Scan()` function description.

- **Connect**
  
  Connect one Bluetooth device. See the `Connect()` function description.

- **Disconnect**
  
  Disconnect one Bluetooth device. See the `Disconnect()` function description.

- **GetData**
  
  Get Bluetooth configuration data. See the `GetData()` function description.

- **SetData**
  
  Set Bluetooth configuration data. See the `SetData()` function description.
GetRemoteData
   Get remote Bluetooth device data. See the GetRemoteData() function description.

RegisterPinCallback
   Register PIN callback function. See the RegisterPinCallback() function description.

RegisterGetLinkKeyCallback
   Register get link key callback function. See the RegisterGetLinkKeyCallback() function description.

RegisterSetLinkKeyCallback
   Register set link key callback function. See the RegisterSetLinkKeyCallback() function description.

RegisterLinkConnectCompleteCallback
   Register link connect complete callback function. See the RegisterLinkConnectCompleteCallback() function description.

Description
The EFI_BLUETOOTH_CONFIG_PROTOCOL abstracts the Bluetooth configuration. User can use Bluetooth configuration to interactive with Bluetooth bus driver.

26.3.2 BLUETOOTH_CONFIG_PROTOCOL.Init

Summary
Initialize Bluetooth host controller and local device.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_CONFIG_INIT)(
   IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This
);
```

Parameters

This
   Pointer to the EFI_BLUETOOTH_CONFIG_PROTOCOL instance.

Description
The Init() function initializes Bluetooth host controller and local device.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth host controller and local device is initialized successfully.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A hardware error occurred trying to initialize the Bluetooth host controller and local device.</td>
</tr>
</tbody>
</table>
26.3.3 BLUETOOTH_CONFIG_PROTOCOL.Scan

Summary
Scan Bluetooth device.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_BLUETOOTH_CONFIG_SCAN)(
    IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,
    IN BOOLEAN ReScan,
    IN UINT8 ScanType,
    IN EFI_BLUETOOTH_CONFIG_SCAN_CALLBACK_FUNCTION Callback,
    IN VOID *Context
);

Parameters

This
Pointer to the \texttt{EFI\_BLUETOOTH\_CONFIG\_PROTOCOL} instance.

ReScan
If \textit{TRUE}, a new scan request is submitted no matter there is scan result before. If \textit{FALSE} and there is scan result, the previous scan result is returned and no scan request is submitted.

ScanType
Bluetooth scan type, Inquiry and/or Page. See Bluetooth specification for detail.

Callback
The callback function. This function is called if a Bluetooth device is found during scan process.

Context
Data passed into \textit{Callback} function. This is optional parameter and may be \textit{NULL}.

Description

The \texttt{Scan()} function scans Bluetooth device. When this function is returned, it just means scan request is submitted. It does not mean scan process is started or finished. Whenever there is a Bluetooth device is found, the \textit{Callback} function will be called. \textit{Callback} function might be called before this function returns or after this function returns.

Related Definitions

typedef
EFI_STATUS
(EIFIAPI *EFI_BLUETOOTH_CONFIG_SCAN_CALLBACK_FUNCTION) (
    IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,
    IN VOID *Context,
    IN EFI_BLUETOOTH_SCAN_CALLBACK_INFORMATION *CallbackInfo
);

This
Pointer to the \texttt{EFI\_BLUETOOTH\_CONFIG\_PROTOCOL} instance.

Context
Context passed from scan request.
CallbackInfo

Data related to scan result. NULL CallbackInfo means scan complete.

typedef
typedef struct{
    BLUETOOTH_ADDRESS BDAddr;
    UINT8 RemoteDeviceState;
    BLUETOOTH_CLASS_OF_DEVICE ClassOfDevice;
    UINT8 RemoteDeviceName[BLUETOOTH_HCI_COMMAND_LOCAL_READABLE_NAME_MAX_SIZE];
} EFI_BLUETOOTH_SCAN_CALLBACK_INFORMATION;

#define BLUETOOTH_HCI_COMMAND_LOCAL_READABLE_NAME_MAX_SIZE 248

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth scan request is submitted.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A hardware error occurred trying to scan the Bluetooth device.</td>
</tr>
</tbody>
</table>

26.3.4 BLUETOOTH_CONFIG_PROTOCOL.Connect

Summary

Connect a Bluetooth device.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_CONFIG_CONNECT)(
    IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,
    IN BLUETOOTH_ADDRESS *BD_ADDR
);

Parameters

This

Pointer to the EFI_BLUETOOTH_CONFIG_PROTOCOL instance.

BD_ADDR

The address of Bluetooth device to be connected.

Description

The Connect() function connects a Bluetooth device. When this function is returned successfully, a new EFI_BLUETOOTH_IO_PROTOCOL is created.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth device is connected successfully.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The Bluetooth device is already connected.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The Bluetooth device is not found.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A hardware error occurred trying to connect the Bluetooth device.</td>
</tr>
</tbody>
</table>
26.3.5 BLUETOOTH_CONFIG_PROTOCOL.Disconnect

Summary
Disconnect a Bluetooth device.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_CONFIG_DISCONNECT)(
    IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,
    IN BLUETOOTH_ADDRESS *BD_ADDR,
    IN UINT8 *Reason
);

Parameters

This
Pointer to the EFI_BLUETOOTH_CONFIG_PROTOCOL instance.

BD_ADDR
The address of Bluetooth device to be connected.

Reason
Bluetooth disconnect reason. See Bluetooth specification for detail.

Description

The Disconnect() function disconnects a Bluetooth device. When this function is returned successfully, the EFI_BLUETOOTH_IO_PROTOCOL associated with this device is destroyed and all services associated are stopped.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth device is disconnected successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The Bluetooth device is not connected.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The Bluetooth device is not found.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A hardware error occurred trying to disconnect the Bluetooth device.</td>
</tr>
</tbody>
</table>

26.3.6 BLUETOOTH_CONFIG_PROTOCOL.GetData

Summary

Get Bluetooth configuration data.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_CONFIG_GET_DATA) (
    IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,
    IN EFI_BLUETOOTH_CONFIG_DATA_TYPE DataType,
    IN OUT UINTN *DataSize,
    IN OUT VOID *Data
);

Parameters

This
Pointer to the EFI_BLUETOOTH_CONFIG_PROTOCOL instance.

DataType
The type of configuration data.

DataSize
The size of the configuration data.

Data
The configuration data.
This

Pointer to the EFI_BLUEETOOTH_CONFIG_PROTOCOL instance.

**DataType**

Configuration data type.

**DataSize**

On input, indicates the size, in bytes, of the data buffer specified by Data. On output, indicates the amount of data actually returned.

**Data**

A pointer to the buffer of data that will be returned.

**Description**

The **GetData() function** returns Bluetooth configuration data. For remote Bluetooth device configuration data, please use **GetRemoteData()** function with valid BD_ADDR.

**Related Definitions**

```c
typedef enum {
    EfiBluetoothConfigDataTypeDeviceName,    /* Relevant for LE*/
    EfiBluetoothConfigDataTypeClassOfDevice,
    EfiBluetoothConfigDataTypeRemoteDeviceState,  /* Relevant for LE*/
    EfiBluetoothConfigDataTypeSdpInfo,
    EfiBluetoothConfigDataTypeBDADDR,       /* Relevant for LE*/
    EfiBluetoothConfigDataTypeDiscoverable,  /* Relevant for LE*/
    EfiBluetoothConfigDataTypeControllerStoredPairedDeviceList,
    EfiBluetoothConfigDataTypeAvailableDeviceList,
    EfiBluetoothConfigDataTypeRandomAddress,  /* Relevant for LE*/
    EfiBluetoothConfigDataTypeRSSI,          /* Relevant for LE*/
    EfiBluetoothConfigDataTypeAdvertisementData,  /* Relevant for LE*/
    EfiBluetoothConfigDataTypeIoCapability,  /* Relevant for LE*/
    EfiBluetoothConfigDataTypeOOBDataFlag,   /* Relevant for LE*/
    EfiBluetoothConfigDataTypeKeyType,       /* Relevant for LE*/
    EfiBluetoothConfigDataTypeEncKeySize,    /* Relevant for LE*/
    EfiBluetoothConfigDataTypeMax,
} EFI_BLUEETOOTH_CONFIG_DATA_TYPE;
```

EfiBluetoothConfigDataTypeAdvertisementDataReport Advertisement report. Data structure is `UNIT8[]`.  

**EfiBluetoothConfigDataTypeKeyType**

Key Type of Authentication Requirements flag of local device as `UINT8`, indicating requested security properties. See Bluetooth specification 3.H.3.5.1. BIT0: MITM, BIT1: SC.

**EfiBluetoothConfigDataTypeDeviceName**

Local/Remote Bluetooth device name. Data structure is zero terminated `CHAR8[]`.

**EfiBluetoothConfigDataTypeClassOfDevice**

Local/Remote Bluetooth device ClassOfDevice. Data structure is `BLUETOOTH_CLASS_OF_DEVICE`.

**EfiBluetoothConfigDataTypeRemoteDeviceState**

Remote Bluetooth device state. Data structure is `EFI_BLUEETOOTH_CONFIG_REMOTE_DEVICE_STATE_TYPE`.

**EfiBluetoothConfigDataTypeSdpInfo**

Local/Remote Bluetooth device SDP information. Data structure is `UINT8[]`.

**EfiBluetoothConfigDataTypeBDADDR**

Local Bluetooth device address. Data structure is `BLUETOOTH_ADDRESS`.

---

26.3. EFI Bluetooth Configuration Protocol
EfiBluetoothConfigDataTypeDiscoverable
Local Bluetooth discoverable state. Data structure is UINT8. (Page scan and/or Inquiry scan)

EfiBluetoothConfigDataTypeControllerStoredPairedDeviceList
Local Bluetooth controller stored paired device list. Data structure is BLUETOOTH_ADDRESS[].

EfiBluetoothConfigDataTypeAvailableDeviceList
Local available device list. Data structure is BLUETOOTH_ADDRESS[].

typedef EFI_BLUETOOTH_CONFIG_REMOTE_DEVICE_STATE_TYPE UINT32;
#define EFI_BLUETOOTH_CONFIG_REMOTE_DEVICE_STATE_CONNECTED 0x1
#define EFI_BLUETOOTH_CONFIG_REMOTE_DEVICE_STATE_PAIRED 0x2

#define BLUETOOTH_HCI_LINK_KEY_SIZE 16

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth configuration data is returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• DataSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• * DataSize is not 0 and Data is NULL</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The DataType is unsupported.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The DataType is not found.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The buffer is too small to hold the buffer. DataSize has been updated with the size needed to complete the request.</td>
</tr>
</tbody>
</table>

26.3.7 BLUETOOTH_CONFIG_PROTOCOL.SetData

Summary
Set Bluetooth configuration data.

Prototype

typedef EFI_STATUS
(EIFIAPI *EFI_BLUETOOTH_CONFIG_SET_DATA) (  
    IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,  
    IN EFI_BLUETOOTH_CONFIG_DATA_TYPE DataType,  
    IN UINTN DataSize,  
    IN VOID *Data  
);  

Parameters

This
Pointer to the EFI_BLUETOOTH_CONFIG_PROTOCOL instance.

DataType
Configuration data type.

DataSize
Indicates the size, in bytes, of the data buffer specified by Data.
Data
A pointer to the buffer of data that will be set.

Description
The SetData() function sets local Bluetooth device configuration data. Not all DataType can be set.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth configuration data is set successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• DataType is unsupported.</td>
</tr>
<tr>
<td></td>
<td>• DataSize is 0.</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The <strong>DataType</strong> is unsupported.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>Cannot set configuration data.</td>
</tr>
</tbody>
</table>

26.3.8 BLUETOOTH_CONFIG_PROTOCOL.GetRemoteData

Summary
Get remote Bluetooth device configuration data.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_CONFIG_GET_REMOTE_DATA) (
    IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,
    IN EFI_BLUETOOTH_CONFIG_DATA_TYPE DataType,
    IN BLUETOOTH_ADDRESS *BDAddr,
    IN OUT UINTN *DataSize,
    IN OUT VOID *Data
);
```

Parameters

**This**
Pointer to the **EFI_BLUETOOTH_CONFIG_PROTOCOL** instance.

**DataType**
Configuration data type.

**BDAddr**
Remote Bluetooth device address.

**DataSize**
On input, indicates the size, in bytes, of the data buffer specified by **Data**. On output, indicates the amount of data actually returned.

**Data**
A pointer to the buffer of data that will be returned.

Description
The GetRemoteData() function returns remote Bluetooth device configuration data.

Status Codes Returned
### EFI_SUCCESS
The remote Bluetooth device configuration data is returned successfully.

### EFI_INVALID_PARAMETER
One or more of the following conditions is TRUE:
- DataSize is NULL.
- * DataSize is not 0 and Data is NULL

### EFI_UNSUPPORTED
The DataType is unsupported.

### EFI_NOT_FOUND
The DataType is not found.

### EFI_BUFFER_TOO_SMALL
The buffer is too small to hold the buffer. DataSize has been updated with the size needed to complete the request.

## 26.3.9 BLUETOOTH_CONFIG_PROTOCOL.RegisterPinCallback

### Summary
Register PIN callback function.

### Prototype
```c
typedef
    EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_CONFIG_REGISTER_PIN_CALLBACK) (    
    IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,
    IN EFI_BLUETOOTH_CONFIG_REGISTER_PIN_CALLBACK_FUNCTION *Callback,
    IN VOID *Context
);
```

### Parameters
**This**
Pointer to the `EFI_BLUETOOTH_CONFIG_PROTOCOL` instance.

**Callback**
The callback function. `NULL` means unregister.

**Context**
Data passed into `Callback` function. This is optional parameter and may be `NULL`.

### Description
The `RegisterPinCallback()` function registers Bluetooth PIN callback function. The Bluetooth configuration driver must call `RegisterPinCallback()` to register a callback function. During pairing, Bluetooth bus driver must trigger this callback function, and Bluetooth configuration driver must handle callback function according to `Callback-Type` during pairing. Both Legacy pairing and SSP (secure simple pairing) are required to be supported. See `EFI_BLUETOOTH_PIN_CALLBACK_TYPE` below for detail of each pairing mode.

### Related Definitions
```c
typedef
    EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_CONFIG_REGISTER_PIN_CALLBACK_FUNCTION) (    
    IN EFI_BLUETOOTH_CONFIG_PROTOCOL * *This,
    IN VOID * *Context,
    IN EFI_BLUETOOTH_PIN_CALLBACK_TYPE *CallbackType,
    IN VOID * *InputBuffer,
    ...
);
```
This

  Pointer to the\n  \textit{EFI\_BLUETOOTH\_CONFIG\_PROTOCOL} instance.

\textbf{Context}

  Context passed from registration.

\textbf{CallbackType}\* Callback type in \textit{EFI\_BLUETOOTH\_PIN\_CALLBACK\_TYPE}.

\textbf{InBuffer}

  A pointer to the buffer of data that is input from callback caller.

\textbf{InputBufferSize}

  Indicates the size, in bytes, of the data buffer specified by \textit{InBuffer}.

\textbf{OutputBuffer}

  A pointer to the buffer of data that will be output from callback callee. Callee allocates this buffer by using EFI Boot Service \texttt{AllocatePool()}.

\textbf{OutputBufferSize}\*

  Indicates the size, in bytes, of the data buffer specified by \textit{OutputBuffer}.

\begin{Verbatim}
\textbf{typedef enum} \\
\{ \\
  \texttt{EfiBluetoothCallbackTypeUserPasskeyNotification,} \\
  \texttt{EfiBluetoothCallbackTypeUserConfirmationRequest,} \\
  \texttt{EfiBluetoothCallbackTypeOOBDataRequest,} \\
  \texttt{EfiBluetoothCallbackTypePinCodeRequest,} \\
  \texttt{EfiBluetoothCallbackTypeMax,} \\
\} \texttt{EFI\_BLUETOOTH\_PIN\_CALLBACK\_TYPE;}
\end{Verbatim}

\textbf{EfiBluetoothCallbackTypeUserPasskeyNotification}

  For SSP - passkey entry. Input buffer is Passkey (4 bytes). No output buffer. See Bluetooth HCI command for detail.

\textbf{EfiBluetoothCallbackTypeUserConfirmationRequest}

  For SSP - just work and numeric comparison. Input buffer is numeric value (4 bytes). Output buffer is BOOLEAN (1 byte). See Bluetooth HCI command for detail.

\textbf{EfiBluetoothCallbackTypeOOBDataRequest}

  For SSP - OOB. See Bluetooth HCI command for detail.

\textbf{EfiBluetoothCallbackTypePinCodeRequest}

  For legacy paring. No input buffer. Output buffer is PIN code (<= 16 bytes). See Bluetooth HCI command for detail.

\textbf{Status Codes Returned}

| \textbf{EFI\_SUCCESS} | The PIN callback function is registered successfully. |

\section{26.3. EFI Bluetooth Configuration Protocol}
26.3.10 BLUETOOTH_CONFIG_PROTOCOL.RegisterGetLinkKeyCallback

**Summary**
Register get link key callback function.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_CONFIG_REGISTER_GET_LINK_KEY_CALLBACK) (IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This, IN EFI_BLUETOOTH_CONFIG_REGISTER_GET_LINK_KEY_CALLBACK_FUNCTION Callback, IN VOID *Context);
```

**Parameters**

- **This**
  Pointer to the `EFI_BLUETOOTH_CONFIG_PROTOCOL` instance.

- **Callback**
  The callback function. `NULL` means unregister.

- **Context**
  Data passed into `Callback` function. This is optional parameter and may be `NULL`.

**Description**

The `RegisterGetLinkKeyCallback()` function registers Bluetooth get link key callback function. The Bluetooth configuration driver may call `RegisterGetLinkKeyCallback()` to register a callback function. When Bluetooth bus driver get Link_Key_Request_Event, Bluetooth bus driver must trigger this callback function if it is registered. Then the callback function in Bluetooth configuration driver must pass link key to Bluetooth bus driver. When the callback function is returned Bluetooth bus driver gets link key and must send HCI_Link_Key_Request_Reply to remote device. If this `GetLinkKey` callback function is not registered or Bluetooth configuration driver fails to return a valid link key, the Bluetooth bus driver must send HCI_Link_Key_Request_Negative_Reply to remote device. The original link key is passed by Bluetooth bus driver to Bluetooth configuration driver by using `EFI_BLUETOOTH_CONFIG_REGISTER_SET_LINK_KEY_CALLBACK_FUNCTION`. The Bluetooth configuration driver need save link key to a non-volatile safe place. (See Bluetooth specification, HCI_Link_Key_Request_Reply)

**Related Definitions**

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_CONFIG_REGISTER_GET_LINK_KEY_CALLBACK_FUNCTION) (IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This, IN VOID *Context, IN BLUETOOTH_ADDRESS *BDAddr, OUT UINT8 LinkKey[BLUETOOTH_HCI_LINK_KEY_SIZE]);
```

- **This**
  Pointer to the `EFI_BLUETOOTH_CONFIG_PROTOCOL` instance.

- **Context**
  Context passed from registration.

- **CallbackType**
  Callback type in `EFI_BLUETOOTH_PIN_CALLBACK_TYPE`. 
BDAddr
A pointer to Bluetooth device address.

LinkKey
A pointer to the buffer of link key.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The link key callback function is registered successfully.</td>
</tr>
</tbody>
</table>

26.3.11 BLUETOOTH_CONFIG_PROTOCOL.RegisterSetLinkKeyCallback

Summary
Register set link key callback function.

Prototype
typedef
EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_CONFIG_REGISTER_SET_LINK_KEY_CALLBACK) (  
 IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,  
 IN EFI_BLUETOOTH_CONFIG_REGISTER_SET_LINK_KEY_CALLBACK_FUNCTION *Callback,  
 IN VOID *Context  
);

Parameters
This
Pointer to the EFI_BLUETOOTH_CONFIG_PROTOCOL instance.

Callback
The callback function. NULL means unregister.

Context
Data passed into Callback function. This is optional parameter and may be NULL.

Description
The RegisterSetLinkKeyCallback() function registers Bluetooth link key callback function. The Bluetooth configuration driver may call RegisterSetLinkKeyCallback() to register a callback function to get link key from Bluetooth bus driver. When Bluetooth bus driver gets Link_Key_Notification_Event, Bluetooth bus driver must call this callback function if it is registered. Then the callback function in Bluetooth configuration driver must save link key to a safe place. This link key will be used by EFI_BLUETOOTH_CONFIG_REGISTER_GET_LINK_KEY_CALLBACK_FUNCTION later. (See Bluetooth specification, Link_Key_Notification_Event)

Related Definitions
typedef
EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_CONFIG_REGISTER_SET_LINK_KEY_CALLBACK_FUNCTION) (  
 IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,  
 IN VOID *Context,  
 IN BLUETOOTH_ADDRESS *BDAddr,  
 IN UINT8 LinkKey[BLUETOOTH_HCI_LINK_KEY_SIZE]  
);
This
Pointer to the EFI_BLUETOOTH_CONFIG_PROTOCOL instance.

Context
Context passed from registration.

CallbackType
Callback type in EFI_BLUETOOTH_PIN_CALLBACK_TYPE.

BDAddr
A pointer to Bluetooth device address.

LinkKey
A pointer to the buffer of link key.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The link key callback function is registered successfully.</td>
</tr>
</tbody>
</table>

26.3.12 BLUETOOTH_CONFIG_PROTOCOL.RegisterLinkConnectCompleteCallback

Summary
Register link connect complete callback function.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_CONFIG_REGISTER_CONNECT_COMPLETE_CALLBACK) (  
    IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,  
    IN EFI_BLUETOOTH_CONFIG_REGISTER_CONNECT_COMPLETE_CALLBACK_FUNCTION Callback,  
    IN VOID *Context  
);

Parameters

This
Pointer to the EFI_BLUETOOTH_CONFIG_PROTOCOL instance.

Callback
The callback function. NULL means unregister. to CallbackType defined by EFI_BLUETOOTH_CONNECT_COMPLETE_CALLBACK_TYPE.

Context
Data passed into Callback function. This is optional parameter and may be NULL.

Description
The RegisterLinkConnectCompleteCallback() function registers Bluetooth link connect complete callback function. The Bluetooth Configuration driver may call RegisterLinkConnectCompleteCallback() to register a callback function. During pairing, Bluetooth bus driver must trigger this callback function to report device state, if it is registered. Then Bluetooth Configuration driver will get information on device connection, according

Related Definitions

typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_CONFIG_REGISTER_CONNECT_COMPLETE_CALLBACK_FUNCTION) (  
    (continues on next page)
IN EFI_BLUETOOTH_CONFIG_PROTOCOL *This,
IN VOID *Context,
IN EFI_BLUETOOTH_CONNECT_COMPLETE_CALLBACK_TYPE CallbackType,
IN BLUETOOTH_ADDRESS *BDAddr,
IN VOID *InputBuffer,
IN UINTN InputBufferSize
);

This
   Pointer to the EFI_BLUETOOTH_CONFIG_PROTOCOL instance.

Context
   Context passed from registration.

CallbackType
   Callback type in EFI_BLUETOOTH_CONNECT_COMPLETE_CALLBACK_TYPE.

BDAddr
   A pointer to Bluetooth device address.

InputBuffer
   A pointer to the buffer of data that is input from callback caller.

InputBufferSize
   Indicates the size, in bytes, of the data buffer specified by InputBuffer.

typedef enum {
    EfiBluetoothConnCallbackTypeDisconnected,
    EfiBluetoothConnCallbackTypeConnected,
    EfiBluetoothConnCallbackTypeAuthenticated,
    EfiBluetoothConnCallbackTypeEncrypted,
} EFI_BLUETOOTH_CONNECT_COMPLETE_CALLBACK_TYPE;

EfiBluetoothConnCallbackTypeDisconnected
   This callback is called when Bluetooth receive Disconnection_Complete event. Input buffer is Event Parameters of Disconnection_Complete Event defined in Bluetooth specification.

EfiBluetoothConnCallbackTypeConnected
   This callback is called when Bluetooth receive Connection_Complete event. Input buffer is Event Parameters of Connection_Complete Event defined in Bluetooth specification.

EfiBluetoothConnCallbackTypeAuthenticated
   This callback is called when Bluetooth receive Authentication_Complete event. Input buffer is Event Parameters of Authentication_Complete Event defined in Bluetooth specification.

EfiBluetoothConnCallbackTypeEncrypted
   This callback is called when Bluetooth receive Encryption_Change event. Input buffer is Event Parameters of Encryption_Change Event defined in Bluetooth specification.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The link connect complete callback function is registered successfully.</td>
</tr>
</tbody>
</table>
26.4 EFI Bluetooth Attribute Protocol

26.4.1 EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL

Summary
This protocol provides service for Bluetooth ATT (Attribute Protocol) and GATT (Generic Attribute Profile) based protocol interfaces.

GUID

```c
#define EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL_GUID \ 
{ 0x898890e9, 0x84b2, 0x4f3a, { 0x8c, 0x58, 0xd8, 0x57, 0x78, 0x13, 0xe0, 0xac } }
```

Protocol Interface Structure

```
typedef struct _EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL {
    EFI_BLUETOOTH_ATTRIBUTE_SEND_REQUEST SendRequest;
    EFI_BLUETOOTH_ATTRIBUTE_REGISTER_FOR_SERVER_NOTIFICATION RegisterForServerNotification;
    EFI_BLUETOOTH_ATTRIBUTE_GET_SERVICE_INFO GetServiceInfo;
    EFI_BLUETOOTH_ATTRIBUTE_GET_DEVICE_INFO GetDeviceInfo;
} EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL;
```

Parameters

SendRequest
Send a “REQUEST” or “COMMAND” message to remote server and receive a “RESPONSE” message for “REQUEST” from remote server according to Bluetooth attribute protocol data unit (PDU). See the SendRequest() function description.

RegisterForServerNotification
Register or unregister a server initiated PDU, such as “NOTIFICATION” or “INDICATION” on a characteristic value on remote server. See the RegisterForServerInitiatedMessage() function description.

GetServiceInfo
Get discovered service data information from connected remote device. See GetServiceInfo() function description.

GetDeviceInfo
Get the device information. See GetDeviceInfo() function description.

Description
The EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL provides services in ATT protocol and GATT profile. For detail of ATT protocol, and GATT profile, please refer to Bluetooth specification.
26.4.2 BLUETOOTH_ATTRIBUTE_PROTOCOL.SendRequest

Summary
Send a “REQUEST” or “COMMAND” message to remote server and receive a “RESPONSE” message for “REQUEST” from remote server according to Bluetooth attribute protocol data unit (PDU).

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_ATTRIBUTE_SEND_REQUEST) (
    IN EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL *This,
    IN VOID *Data,
    IN UINTN DataLength,
    IN EFI_BLUETOOTH_ATTRIBUTE_CALLBACK_FUNCTION Callback,
    IN VOID *Context
);
```

Parameters

- **This**
  Pointer to the EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL instance.

- **Data**
  Data of a REQUEST or COMMAND message. The first byte is the attribute PDU related opcode, followed by opcode specific fields. See Bluetooth specification, Vol 3, Part F, Attribute Protocol.

- **DataLength**
  The length of Data in bytes.

- **Callback**
  Callback function to notify the RESPONSE is received to the caller, with the response buffer. Caller must check the response buffer content to know if the request action is success or fail. It may be NULL if the data is a COMMAND.

- **Context**
  Data passed into Callback function. It is optional parameter and may be NULL.

Description

The **SendRequest() function** sends a “REQUEST” or “COMMAND” message to remote server and receive a “RESPONSE” message for “REQUEST” from remote server according to Bluetooth attribute protocol data unit (PDU). In most cases, this interface is used to read attributes from remote device, or write attributes to remote device.

Related Definitions

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_ATTRIBUTE_CALLBACK_FUNCTION) (
    IN EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL *This,
    IN VOID *Data,
    IN UINTN DataLength,
    IN VOID *Context
);
```

- **This**
  Pointer to the EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL instance.
Data received. The first byte is the attribute opcode, followed by opcode specific fields. See Bluetooth specification, Vol 3, Part F, Attribute Protocol. It might be a normal RESPONSE message, or ERROR RESPONSE message.

**DataLength**

The length of Data in bytes.

**Context**

The context passed from the callback registration request.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The request is sent successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more parameters are invalid due to following conditions:</td>
</tr>
<tr>
<td></td>
<td>• The Buffer is NULL.</td>
</tr>
<tr>
<td></td>
<td>• The BufferLength is 0.</td>
</tr>
<tr>
<td></td>
<td>• The opcode in Buffer is not a valid OPCODE according to Bluetooth</td>
</tr>
<tr>
<td></td>
<td>specification.</td>
</tr>
<tr>
<td></td>
<td>• The Callback is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Sending the request failed due to the host controller or the device error.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>A GATT operation is already underway for this device.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The attribute does not support the corresponding operation</td>
</tr>
</tbody>
</table>

#### 26.4.3 BLUETOOTH_ATTRIBUTE_PROTOCOL.RegisterForServerNotification

Summary Register or unregister a server initiated message, such as NOTIFICATION or INDICATION, on a characteristic value on remote server.

**Prototype**

code-block:

```c
typedef EFI_STATUS
  (EFIAPI *EFI_BLUETOOTH_ATTRIBUTE_REGISTER_FOR_SERVER_NOTIFICATION)(
    IN EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL *This,
    IN EFI_BLUETOOTH_ATTRIBUTE_CALLBACK_PARAMETER *CallbackParameter,
    IN EFI_BLUETOOTH_ATTRIBUTE_CALLBACK_FUNCTION Callback,
    IN VOID *Context
  );
```

**Parameters**

**This**

Pointer to the EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL instance.

**CallbackParameter**

The parameter of the callback.

**Callback**

Callback function for server initiated attribute protocol. NULL callback function means unregister the server initiated callback.
Context
Data passed into Callback function. It is optional parameter and may be NULL.

Description
The RegisterForServerNotification() function can be issued to request Bluetooth to register or unregister a server initiated message, such as notification or indication, on a characteristic value on remote server. It can only be done if the characteristic supports that operation.

Related Definitions
typedef struct {
    UINT16 AttributeHandle;
} EFI_BLUETOOTH_ATTRIBUTE_CALLBACK_PARAMETER_NOTIFICATION;
typedef struct {
    UINT16 AttributeHandle;
} EFI_BLUETOOTH_ATTRIBUTE_CALLBACK_PARAMETER_INDICATION;
typedef struct {
    UINT32 Version;
    UINT8 AttributeOpCode;
    union {
        EFI_BLUETOOTH_ATTRIBUTE_CALLBACK_PARAMETER_NOTIFICATION Notification;
        EFI_BLUETOOTH_ATTRIBUTE_CALLBACK_PARAMETER_INDICATION Indication;
    } Parameter;
} EFI_BLUETOOTH_ATTRIBUTE_CALLBACK_PARAMETER;

Todo: check above code, indents barely discernable

Version
The version of the structure. A value of zero represents the EFI_BLUETOOTH_ATTRIBUTE_CALLBACK_PARAMETER structure as defined here. Future version of this specification may extend this data structure in a backward compatible way and increase the value of Version.

AttributeOpCode

AttributeHandle
The attribute handle for notification or indication.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The callback function is registered or unregistered successfully</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The attribute opcode is not server initiated message opcode. See Bluetooth</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>A callback function is already registered on the same attribute opcode and</td>
</tr>
<tr>
<td></td>
<td>attribute handle, when the Callback is not NULL.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>A callback function is not registered on the same attribute opcode and</td>
</tr>
<tr>
<td></td>
<td>attribute handle, when the Callback is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>A GATT operation is already underway for this device</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The attribute does not support notification</td>
</tr>
</tbody>
</table>
26.4.4 BLUETOOTH_ATTRIBUTE_PROTOCOL.GetServiceInfo

Summary
Get Bluetooth discovered service information.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_BLUETOOTH_ATTRIBUTE_GET_SERVICE_INFO)(
   IN EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL *This,
   OUT UINTN *ServiceInfoSize,
   OUT VOID **ServiceInfo
);
```

Parameters

**This**
Pointer to the EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL instance.

**ServiceInfoSize**
A pointer to the size, in bytes, of the ServiceInfo buffer.

**ServiceInfo**
A pointer to a callee allocated buffer that returns Bluetooth discovered service information. Callee allocates this buffer by using EFI Boot Service AllocatePool().

Description

The GetServiceInfo() function returns Bluetooth discovered service information. The size of ServiceInfo structure should never be assumed and the value of ServiceInfoSize is the only valid way to know the size of ServiceInfo. The ServiceInfo buffer is a list Bluetooth service information structures defined below.

Related Definitions

```c
typedef struct {
   UINT8 Length;
   union {
      UINT16 Uuid16;
      UINT32 Uuid32;
      UINT8 Uuid128[16];
   } Data;
} EFI_BLUETOOTH_UUID;
```

**Length**
The length of Bluetooth UUID data. The valid value is 2, 4, or 16.

**Uuid16**
The 16-bit Bluetooth UUID data.

**Uuid32**
The 32-bit Bluetooth UUID data.

**Uuid128**
The 128-bit Bluetooth UUID data.
typedef struct {
    EFI_BLUETOOTH_UUID Type;
    UINT16 Length;
    UINT16 AttributeHandle;
    EFI_BLUETOOTH_ATTRIBUTE_PERMISSION AttributePermission;
} EFI_BLUETOOTH_ATTRIBUTE_HEADER;

Type
The type of this structure. It must be EFI_BLUETOOTH_UUID. See Bluetooth GATT definition. Primary Service is 0x2800. Secondary Service is 0x2801. Include Service is 0x2802. Characteristic is 0x2803. Characteristic Descriptor is 0x2900.

Length
The length of this structure.

AttributeHandle
The handle of the service declaration. See Bluetooth specification.

AttributePermission
The permission of the attribute. This field is only valid for the attribute of the local device. This field should be ignored for the attribute of the remote device.

// Bluetooth Attribute Permission
//
typedef union {
    struct {
        UINT16 Readable : 1;
        UINT16 ReadEncryption : 1;
        UINT16 ReadAuthentication : 1;
        UINT16 ReadAuthorization : 1;
        UINT16 ReadKeySize : 5;
        UINT16 Reserved1 : 7;
        UINT16 Writeable : 1;
        UINT16 WriteEncryption : 1;
        UINT16 WriteAuthentication : 1;
        UINT16 WriteAuthorization : 1;
        UINT16 WriteKeySize : 5;
        UINT16 Reserved2 : 7;
    } Permission;
    UINT32 Data32;
} EFI_BLUETOOTH_ATTRIBUTE_PERMISSION;

Readable
The attribute is readable.

ReadEncryption
The encryption is required on read.

ReadAuthentication
The authentication is required on read.

ReadAuthorization
The authorization is required on read.

ReadKeySize
The size of key in bytes on read.
**Writeable**
The attribute is writeable.

**WriteEncryption**
The encryption is required on write.

**WriteAuthentication**
The authentication is required on write.

**WriteAuthorization**
The authorization is required on write.

**WriteKeySize**
The size of key in bytes on write.

```c
typedef struct {
  EFI_BLUETOOTH_ATTRIBUTE_HEADER Header;
  UINT16 EndGroupHandle;
  EFI_BLUETOOTH_UUID ServiceUuid;
} EFI_BLUETOOTH_GATT_PRIMARY_SERVICE_INFO;
```

**EndGroupHandle**
The handle of the last attribute within the service definition. See Bluetooth specification.

**Header**
The header of this structure.

```c
typedef struct {
  EFI_BLUETOOTH_ATTRIBUTE_HEADER Header;
  UINT16 StartGroupHandle;
  UINT16 EndGroupHandle;
  EFI_BLUETOOTH_UUID ServiceUuid;
} EFI_BLUETOOTH_GATT_INCLUDE_SERVICE_INFO;
```

**Header**
The header of this structure.

```c
typedef struct {
  EFI_BLUETOOTH_ATTRIBUTE_HEADER Header;
  UINT8 CharacteristicProperties;
  UINT16 CharacteristicValueHandle;
  EFI_BLUETOOTH_UUID CharacteristicUuid;
} EFI_BLUETOOTH_GATT_CHARACTERISTIC_INFO;
```

**Header**
The header of this structure.

```c
typedef struct {
  EFI_BLUETOOTH_ATTRIBUTE_HEADER Header;
  EFI_BLUETOOTH_UUID CharacteristicDescriptorUuid;
} EFI_BLUETOOTH_GATT_CHARACTERISTIC_DESCRIPTOR_INFO;
```

**Header**
The header of this structure.

**Status Codes Returned**

26.4. EFI Bluetooth Attribute Protocol
### 26.4.5 BLUETOOTH_ATTRIBUTE_PROTOCOL.GetDeviceInfo

**Summary**

Get Bluetooth device information.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_ATTRIBUTE_GET_DEVICE_INFO)(
    IN EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL *This,
    OUT UINTN *DeviceInfoSize,
    OUT VOID **DeviceInfo
);
```

**Parameters**

- **This**
  
  Pointer to the `EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL` instance.

- **DeviceInfoSize**
  
  A pointer to the size, in bytes, of the `DeviceInfo` buffer.

- **DeviceInfo**
  
  A pointer to a callee allocated buffer that returns Bluetooth device information. Callee allocates this buffer by using EFI Boot Service `AllocatePool()`. If this device is Bluetooth classic device, `EFI_BLUETOOTH_DEVICE_INFO` should be used. If this device is Bluetooth LE device, `EFI_BLUETOOTH_LE_DEVICE_INFO` should be used.

**Description**

The `GetDeviceInfo()` function returns Bluetooth device information. The size of `DeviceInfo` structure should never be assumed and the value of `DeviceInfoSize` is the only valid way to know the size of `DeviceInfo`.

**Related Definitions**

```c
typedef struct {
    UINT8 Address[6];
    UINT8 Type;
} BLUETOOTH_LE_ADDRESS;

typedef struct {
    UINT32 Version;
    BLUETOOTH_LE_ADDRESS BD_ADDR;
    BLUETOOTH_LE_ADDRESS DirectAddress;
    UINT8 RSSI;
    UINTN AdvertisementDataSize;
    VOID *AdvertisementData;
} EFI_BLUETOOTH_LE_DEVICE_INFO;
```
Version
The version of the structure. A value of zero represents the EFI_BLUETOOTH_LE_DEVICE_INFO structure as defined here. Future version of this specification may extend this data structure in a backward compatible way and increase the value of Version.

BD_ADDR
48bit Bluetooth device address and 1byte address type.

DirectAddress
48bit random device address and 1byte address type.

RSSI
Bluetooth RSSI. See Bluetooth specification for detail.

AdvertisementDataSize
The size of AdvertisementData in bytes.

AdvertisementData
Bluetooth LE advertisement data. See Bluetooth specification for detail.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth device information is returned successfully.</td>
</tr>
<tr>
<td>EFIDEVICE_ERROR</td>
<td>A hardware error occurred trying to retrieve the Bluetooth device information.</td>
</tr>
</tbody>
</table>

26.4.6 EFI_BLUETOOTH_ATTRIBUTE_SERVICE_BINDING_PROTOCOL

Summary
The EFI Bluetooth ATTRIBUTE Service Binding Protocol is used to locate EFI Bluetooth ATTRIBUTE Protocol drivers to create and destroy child of the driver to communicate with other Bluetooth device by using Bluetooth ATTRIBUTE protocol.

GUID

```
#define EFI_BLUETOOTH_ATTRIBUTE_SERVICE_BINDING_PROTOCOL_GUID
{ 0x5639867a, 0x8c8e, 0x408d, 0xac, 0x2f, 0x61, 0xbd, 0xc0, 0xbb, 0xbb }
```

Description
The Bluetooth ATTRIBUTE consumer need locate EFI_BLUETOOTH_ATTRIBUTE_SERVICE_BINDING_PROTOCOL and call CreateChild() to create a new child of EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL instance. Then use EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL for Bluetooth communication. After use, the Bluetooth ATTRIBUTE consumer need call DestroyChild() to destroy it.
26.5 EFI Bluetooth LE Configuration Protocol

26.5.1 EFI_BLUETOOTH_LE_CONFIG_PROTOCOL

Summary
This protocol abstracts user interface configuration for BluetoothLe device.

GUID
#define EFI_BLUETOOTH_LE_CONFIG_PROTOCOL_GUID "
{ 0x8f76da58, 0x1f99, 0x4275, { 0xa4, 0xec, 0x47, 0x56, 0x51, 0x5b, 0x1c, 0xe8 }}

Protocol Interface Structure

typedef struct__EFI_BLUETOOTH_LE_CONFIG_PROTOCOL {
    EFI_BLUETOOTH_LE_CONFIG_INIT Init;
    EFI_BLUETOOTH_LE_CONFIG_SCAN Scan;
    EFI_BLUETOOTH_LE_CONFIG_CONNECT Connect;
    EFI_BLUETOOTH_LE_CONFIG_DISCONNECT Disconnect;
    EFI_BLUETOOTH_LE_CONFIG_GET_DATA GetData;
    EFI_BLUETOOTH_LE_CONFIG_SET_DATA SetData;
    EFI_BLUETOOTH_LE_CONFIG_GET_REMOTE_DATA GetRemoteData;
    EFI_BLUETOOTH_LE_CONFIG_REGISTER_SMP_AUTH_CALLBACK RegisterSmpAuthCallback;
    EFI_BLUETOOTH_LE_CONFIG_SEND_SMP_AUTH_DATA SendSmpAuthData;
    EFI_BLUETOOTH_LE_CONFIG_REGISTER_SMP_GET_DATA_CALLBACK RegisterSmpGetDataCallback;
    EFI_BLUETOOTH_LE_CONFIG_REGISTER_SMP_SET_DATA_CALLBACK RegisterSmpSetDataCallback;
    EFI_BLUETOOTH_LE_CONFIG_REGISTER_CONNECT_COMPLETE_CALLBACK RegisterLinkConnectCompleteCallback;
} EFI_BLUETOOTH_LE_CONFIG_PROTOCOL;

Parameters
Init
Initialize BluetoothLE host controller and local device. See the Init() function description.

Scan
Scan BluetoothLE device. See the Scan() function description.

Connect
Connect one BluetoothLE device. See the Connect() function description.

Disconnect
Disconnect one BluetoothLE device. See the Disconnect() function description.

GetData
Get BluetoothLE configuration data. See the GetData() function description.

SetData
Set BluetoothLE configuration data. See the SetData() function description.

GetRemoteData
Get remote BluetoothLE device data. See the GetRemoteData() function description.

RegisterSmpAuthCallback
Register Security Manager Callback function. This function will be called from Bluetooth BUS driver whenever user interaction is required for security protocol authorization/authentication. See the RegisterSmpAuthCallback() function description.
SendSmpAuthData
Send user input (Authentication/Authorization) such as passkey, confirmation (yes/no) in response to pairing request. See the SendSmpAuthData() function description.

RegisterSmpGetDataCallback
Register a callback function to get SMP related data. See the RegisterSmpGetDataCallback() function description.

RegisterSmpSetDataCallback
Register a callback function to set SMP related data. See the RegisterSmpGetDataCallback() function description.

RegisterLinkConnectCompleteCallback
Register link connect complete callback function. See the RegisterLinkConnectCompleteCallback() function description.

Description
The EFI_BLUETOOTH_LE_CONFIG_PROTOCOL abstracts the BluetoothLE configuration. User can use BluetoothLE configuration to interactive with BluetoothLE bus driver.

26.5.2 BLUETOOTH_LE_CONFIG_PROTOCOL.Init

Summary
Initialize BluetoothLE host controller and local device.

Prototype

typedef
EFI_STATUS
(EIFIAPIC *EFI_BLUETOOTH_LE_CONFIG_INIT)(
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This
    )

Parameters
This
Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

Description
The Init() function initializes BluetoothLE host controller and local device.

Status Codes Returned

<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The BluetoothLE host controller and local device is initialized successfully.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A hardware error occurred trying to initialize the BluetoothLE host controller and local device.</td>
</tr>
</tbody>
</table>
26.5.3 BLUETOOTH_LE_CONFIG_PROTOCOL.Scan

**Summary**

Scan BluetoothLE device.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_LE_CONFIG_SCAN)(
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,
    IN BOOLEAN ReScan,
    IN UIN32 Timeout;
    IN EFI_BLUETOOTH_LE_CONFIG_SCAN_PARAMETER *ScanParameter,
    OPTIONAL
    IN EFI_BLUETOOTH_LE_CONFIG_SCAN_CALLBACK_FUNCTION Callback,
    IN VOID *Context
);
```

**Parameters**

**This**

Pointer to the `EFI_BLUETOOTH_LE_CONFIG_PROTOCOL` instance.

**ReScan**

If `TRUE`, a new scan request is submitted no matter there is scan result before. If `FALSE` and there is scan result, the previous scan result is returned and no scan request is submitted.

**Timeout**

Duration in milliseconds for which to scan.

**ScanParameter**

If it is not `NULL`, the ScanParameter is used to perform a scan by the BluetoothLE bus driver. If it is `NULL`, the default parameter is used.

**Callback**

The callback function. This function is called if a BluetoothLE device is found during scan process.

**Context**

Data passed into `Callback` function. This is optional parameter and may be `NULL`.

**Description**

The `Scan()` function scans BluetoothLE device. When this function is returned, it just means scan request is submitted. It does not mean scan process is started or finished. Whenever there is a BluetoothLE device is found, the `Callback` function will be called. `Callback` function might be called before this function returns or after this function returns.

**Related Definitions**

```c
typedef struct {
    // Scan parameter
    UINT32 Version;
    UINT8 ScanType;
    UINT16 ScanInterval;
    UINT16 ScanWindow;
    UINT8 ScanningFilterPolicy;
} EFI_BLUETOOTH_LE_CONFIG_SCAN_PARAMETER;
```

(continues on next page)
// Scan result filter
UINT8 AdvertisementFlagFilter;
} EFI_BLUETOOTH_LE_CONFIG_SCAN_PARAMETER;

**Version**

The version of the structure. A value of zero represents the EFI_BLUETOOTH_LE_CONFIG_SCAN_PARAMETER structure as defined here. Future version of this specification may extend this data structure in a backward compatible way and increase the value of Version.

**ScanType**

Passive scanning or active scanning. See Bluetooth specification.

**ScanInterval**

Recommended scan interval to be used while performing scan.

**ScanWindow**

Recommended scan window to be used while performing a scan.

**ScanningFilterPolicy**

Recommended scanning filter policy to be used while performing a scan.

**AdvertisementFlagFilter**

This is one byte flag to serve as a filter to remove unneeded scan result. For example, set BIT0 means scan in LE Limited Discoverable Mode. Set BIT1 means scan in LE General Discoverable Mode. See Supplement to Bluetooth Core Specification.

```c
typedef EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_LE_CONFIG_SCAN_CALLBACK_FUNCTION) (
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,
    IN VOID *Context,
    IN EFI_BLUETOOTH_LE_SCAN_CALLBACK_INFORMATION *CallbackInfo
);
```

**This**

Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

**Context**

Context passed from scan request.

**CallbackInfo**

Data related to scan result. NULL CallbackInfo means scan complete.

```c
typedef struct{
    BLUETOOTH_LE_ADDRESS            BDAddr;
    BLUETOOTH_LE_ADDRESS            DirectAddress;
    UINT8                           RemoteDeviceState;
    INT8                            RSSI;
    UINTN                           AdvertisementDataSize;
    VOID *                          AdvertisementData;
} EFI_BLUETOOTH_LE_SCAN_CALLBACK_INFORMATION;
```

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Bluetooth scan request is submitted.</td>
</tr>
</tbody>
</table>

continues on next page
**26.5.4 BLUETOOTH_LE_CONFIG_PROTOCOL.Connect**

**Summary**

Connect a BluetoothLE device.

**Prototype**

```c
typedef EFI_STATUS
(EPIAPI *EFI_BLUETOOTH_LE_CONFIG_CONNECT)(
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,
    IN BOOLEAN AutoReconnect,
    IN BOOLEAN DoBonding;
    IN EFI_BLUETOOTH_LE_CONFIG_CONNECT_PARAMETER *ConnectParameter, OPTIONAL
    IN BLUETOOTH_LE_ADDRESS *BD_ADDR
);
```

**Parameters**

- **This**
  
  Pointer to the `EFI_BLUETOOTH_LE_CONFIG_PROTOCOL` instance.

- **AutoReconnect**
  
  If `TRUE`, the BluetoothLE host controller needs to do an auto reconnect. If `FALSE`, the BluetoothLE host controller does not do an auto reconnect.

- **DoBonding**
  
  If `TRUE`, the BluetoothLE host controller needs to do a bonding. If `FALSE`, the BluetoothLE host controller does not do a bonding.

- **ConnectParameter**
  
  If it is not `NULL`, the ConnectParameter is used to perform a scan by the BluetoothLE bus driver. If it is `NULL`, the default parameter is used.

- **BD_ADDR**
  
  The address of the BluetoothLE device to be connected.

**Description**

The `Connect()` function connects a Bluetooth device. When this function is returned successfully, a new `EFI_BLUETOOTH_IO_PROTOCOL` is created.

**Related Definitions**

```c
typedef struct {
    UINT32 Version;
    UINT16 ScanInterval;
    UINT16 ScanWindow;
    UINT16 ConnIntervalMin;
    UINT16 ConnIntervalMax;
    UINT16 ConnLatency;
    UINT16 SupervisionTimeout;
} EFI_BLUETOOTH_LE_CONFIG_CONNECT_PARAMETER;
```
Version
   The version of the structure. A value of zero represents the EFI_BLUETOOTH_LE_CONFIG_CONNECT_PARAMETER structure as defined here. Future version of this specification may extend this data structure in a backward compatible way and increase the value of Version.

ScanInterval
   Recommended scan interval to be used while performing scan before connect.

ScanWindow
   Recommended scan window to be used while performing a connection.

ConnIntervalMin
   Minimum allowed connection interval. Shall be less than or equal to ConnIntervalMax.

ConnIntervalMax
   Maximum allowed connection interval. Shall be greater than or equal to ConnIntervalMin.

ConnLatency
   Slave latency for the connection in number of connection events.

SupervisionTimeout
   Link supervision timeout for the connection.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The BluetoothLE device is connected successfully.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The BluetoothLE device is already connected.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The BluetoothLE device is not found.</td>
</tr>
<tr>
<td>EFIDEVICE_ERROR</td>
<td>A hardware error occurred trying to connect the BluetoothLE device.</td>
</tr>
</tbody>
</table>

26.5.5 BLUETOOTH_LE_CONFIG_PROTOCOL.Disconnect

Summary
Disconnect a BluetoothLE device.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_BLUETOOTH_LE_CONFIG_DISCONNECT)(
   IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,
   IN BLUETOOTH_LE_ADDRESS *BD_ADDR,
   IN UINT8 Reason
);

Parameters

This
   Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

BD_ADDR
   The address of BluetoothLE device to be connected.

Reason
   BluetoothLE disconnect reason. See Bluetooth specification for detail.

Description
The Disconnect() function disconnects a BluetoothLE device. When this function is returned successfully, the EFI_BLUETOOTH_ATTRIBUTE_PROTOCOL associated with this device is destroyed and all services associated are stopped.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The BluetoothLE device is disconnected successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The BluetoothLE device is not connected.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The BluetoothLE device is not found.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>A hardware error occurred trying to disconnect the BluetoothLE device.</td>
</tr>
</tbody>
</table>

26.5.6 BLUETOOTH_LE_CONFIG_PROTOCOL.GetData

Summary

Get BluetoothLE configuration data.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_LE_CONFIG_GET_DATA) (  
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,  
    IN EFI_BLUETOOTH_CONFIG_DATA_TYPE DataType,  
    IN OUT UINTN *DataSize,  
    IN OUT VOID *Data  
);
```

Parameters

This

Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

DataType

Configuration data type.

DataSize

On input, indicates the size, in bytes, of the data buffer specified by Data. On output, indicates the amount of data actually returned.

Data

A pointer to the buffer of data that will be returned.

Description

The GetData() function returns BluetoothLE configuration data. For remote BluetoothLE device configuration data, please use GetRemoteData() function with valid BD_ADDR.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The BluetoothLE configuration data is returned successfully.</td>
</tr>
<tr>
<td>continues on next page</td>
<td></td>
</tr>
</tbody>
</table>
Table 26.36 – continued from previous page

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• DataSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• * DataSize is 0.</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The DataType is unsupported.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The DataType is not found.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The buffer is too small to hold the buffer.</td>
</tr>
</tbody>
</table>

26.5.7 BLUEETOOTH_LE_CONFIG_PROTOCOL.SetData

**Summary**
Set BluetoothLE configuration data.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_LE_CONFIG_SET_DATA) (
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,
    IN EFI_BLUETOOTH_CONFIG_DATA_TYPE DataType,
    IN UINTN DataSize,
    IN VOID *Data);
```

**Parameters**

**This**
Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

**DataType**
Configuration data type.

**DataSize**
Indicates the size, in bytes, of the data buffer specified by Data.

**Data**
A pointer to the buffer of data that will be set.

**Description**

The SetData() function sets local BluetoothLE device configuration data. Not all DataType can be set.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The BluetoothLE configuration data is set successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• DataSize is 0.</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The DataType is unsupported.</td>
</tr>
</tbody>
</table>

continues on next page
26.5.8 BLUETOOTH_LE_CONFIG_PROTOCOL.GetRemoteData

Summary
Get remove BluetoothLE device configuration data.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_LE_CONFIG_GET_REMOTE_DATA) (
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,
    IN EFI_BLUETOOTH_CONFIG_DATA_TYPE DataType,
    IN BLUETOOTH_LE_ADDRESS *BDAddr,
    IN OUT UINTN *DataSize,
    IN OUT VOID *Data
);
```

Parameters

**This**
Pointer to the `EFI_BLUETOOTH_LE_CONFIG_PROTOCOL` instance.

**DataType**
Configuration data type.

**BDAddr**
Remote BluetoothLE device address.

**DataSize**
On input, indicates the size, in bytes, of the data buffer specified by `Data`. On output, indicates the amount of data actually returned.

**Data**
A pointer to the buffer of data that will be returned.

Description
The `GetRemoteData()` function returns remote BluetoothLE device configuration data.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The remote BluetoothLE device configuration data is returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• <code>DataSize</code> is NULL.</td>
</tr>
<tr>
<td></td>
<td>• <code>DataSize</code> is 0.</td>
</tr>
<tr>
<td></td>
<td>• <code>Data</code> is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The <code>DataType</code> is unsupported.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The <code>DataType</code> is not found.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The buffer is too small to hold the buffer.</td>
</tr>
</tbody>
</table>
26.5.9 BLUETOOTH_LE_CONFIG_PROTOCOL.RegisterSmpAuthCallback

Summary
Register Security Manager Protocol callback function for user authentication/authorization.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_LEREGISTER_SMP_AUTH_CALLBACK)(
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,
    IN EFI_BLUETOOTH_LE_SMP_CALLBACK Callback,
    IN VOID *Context
);

Parameters

This
Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

Callback
Callback function for user authentication/authorization.

Context
Data passed into callback function. This is optional parameter and may be NULL.

Description

The RegisterSmpAuthCallback() function register Security Manager Protocol callback function for user authentication/authorization.

Related Definitions

typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_LE_SMP_CALLBACK)(
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,
    IN VOID *Context,
    IN BLUETOOTH_LE_ADDRESS *BDAddr,
    IN EFI_BLUETOOTH_LE_SMP_EVENT_DATA_TYPE EventDataType,
    IN UINTN DataSize,
    IN VOID *Data
);

This
Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

Context
Data passed into callback function. This is optional parameter and may be NULL.

BDAddr
Remote BluetoothLE device address.

EventDataType
Event data type in EFI_BLUETOOTH_LE_SMP_EVENT_DATA_TYPE.

DataSize
Indicates the size, in bytes, of the data buffer specified by Data.
Data
A pointer to the buffer of data.

typedef enum {
    EfiBlutoothSmpAuthorizationRequestEvent,
    EfiBlutoothSmpPasskeyReadyEvent,
    EfiBlutoothSmpPasskeyRequestEvent,
    EfiBlutoothSmpOOBDaDataRequestEvent,
    EfiBlutoothSmpNumericComparisonEvent,
} EFI_BLUETOOTH_LE_SMP_EVENT_DATA_TYPE;

EfiBlutoothSmpAuthorizationRequestEvent
It indicates an authorization request. No data is associated with the callback input. In the output data, the application should return the authorization value. The data structure is BOOLEAN. TRUE means YES. FALSE means NO.

EfiBlutoothSmpPasskeyReadyEvent
It indicates that a passkey has been generated locally by the driver, and the same passkey should be entered at the remote device. The callback input data is the passkey of type UINT32, to be displayed by the application. No output data should be returned.

EfiBlutoothSmpPasskeyRequestEvent
It indicates that the driver is requesting for the passkey has been generated at the remote device. No data is associated with the callback input. The output data is the passkey of type UINT32, to be entered by the user.

EfiBlutoothSmpOOBDaDataRequestEvent
It indicates that the driver is requesting for the passkey that has been pre-shared out-of-band with the remote device. No data is associated with the callback input. The output data is the stored OOB data of type UINT8[16].

EfiBlutoothSmpNumericComparisonEvent
It indicates that a number have been generated locally by the bus driver, and also at the remote device, and the bus driver wants to know if the two numbers match. The callback input data is the number of type UINT32. The output data is confirmation value of type BOOLEAN. TRUE means comparison pass. FALSE means comparison fail.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The SMP callback function is registered successfully.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>A callback function is already registered on the same attribute opcode and attribute handle, when the Callback is not NULL.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>A callback function is not registered on the same attribute opcode and attribute handle, when the Callback is NULL.</td>
</tr>
</tbody>
</table>

26.5.10 BLUETOOTH_LE_CONFIG_PROTOCOL.SendSmpAuthData

Summary
Send user authentication/authorization to remote device.

Prototype

typedef EFI_STATUS
(EFIAP *EFI_BLUETOOTH_LE_SEND_SMP_AUTH_DATA) (    
   IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,    
   IN BLUETOOTH_LE_ADDRESS *BDAddr,    
)
IN EFI_BLUETOOTH_LE_SMP_EVENT_DATA_TYPE EventDataType,
IN UINTN DataSize,
IN VOID *Data
);

Parameters

This
Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

BDAddr
Remote BluetoothLE device address.

EventDataType
Event data type in EFI_BLUETOOTH_LE_SMP_EVENT_DATA_TYPE.

DataSize
The size of Data in bytes, of the data buffer specified by Data.

Data
A pointer to the buffer of data that will be sent. The data format depends on the type of SMP event data being responded to. See EFI_BLUETOOTH_LE_SMP_EVENT_DATA_TYPE.

Description
The SendSmpAuthData() function sends user authentication/authorization to remote device. It should be used to send these information after the caller gets the request data from the callback function by RegisterSmpAuthCallback().

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The SMP authorization data is sent successfully.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>SMP is not in the correct state to receive the auth data</td>
</tr>
</tbody>
</table>

26.5.11 BLUETOOTH_LE_CONFIG_PROTOCOL.RegisterSmpGetDataCallback

Summary
Register a callback function to get SMP related data.

Prototype

typedef
EFI_STATUS
(EIFIAPI * EFI_BLUETOOTH_LE_CONFIG_REGISTER_SMP_GET_DATA_CALLBACK )(
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,
    IN EFI_BLUETOOTH_LE_CONFIG_SMP_GET_DATA_CALLBACK Callback,
    IN VOID *Context
);

Parameters

This
Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

Callback
Callback function for SMP get data.
Context
Data passed into callback function. This is optional parameter and may be NULL.

Description
The RegisterSmpGetDataCallback() function registers a callback function to get SMP related data.

Related Definitions

typedef
EFI_STATUS
(EIFIAPI * EFI_BLUETOOTH_LE_CONFIG_SMP_GET_DATA_CALLBACK) (
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,
    IN VOID *Context,
    IN BLUETOOTH_LE_ADDRESS *BDAddr,
    IN EFI_BLUETOOTH_LE_SMP_DATA_TYPE DataType,
    IN OUT UINTN *DataSize,
    OUT VOID *Data
);

This
Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

Context
Data passed into callback function. This is optional parameter and may be NULL.

BDAddr
Remote BluetoothLE device address. For Local device setting, it should be NULL.

DataType
Data type in EFI_BLUETOOTH_LE_SMP_DATA_TYPE.

DataSize
On input, indicates the size, in bytes, of the data buffer specified by Data. On output, indicates the amount of data actually returned.

Data
A pointer to the buffer of data that will be returned.

typedef enum {
    // For local device only
    EfiBluetoothSmpLocalIR, /* If Key hierarchy is supported */
    EfiBluetoothSmpLocalER, /* If Key hierarchy is supported */
    EfiBluetoothSmpLocalDHK, /* If Key hierarchy is supported. OPTIONAL */

    // For peer specific
    EfiBluetoothSmpKeysDistributed = 0x1000,
    EfiBluetoothSmpKeySize,
    EfiBluetoothSmpKeyType,
    EfiBluetoothSmpPeerLTK,
    EfiBluetoothSmpPeerIRK,
    EfiBluetoothSmpPeerCSRK,
    EfiBluetoothSmpPeerRand,
    EfiBluetoothSmpPeerEDIV,
    EfiBluetoothSmpPeerSignCounter,
    EfiBluetoothSmpLocalLTK, /* If Key hierarchy not supported */
    EfiBluetoothSmpLocalIRK, /* If Key hierarchy not supported */
    EfiBluetoothSmpLocalCSRK, /* If Key hierarchy not supported */
}
(continues on next page)
EfiBlutoothSmpLocalIR

It is a 128-bit Identity Root (IR) key to generate IRK. Data structure is UINT8[16]. See Bluetooth specification. This is only required when Bluetooth key hierarchy is supported. This type is for the local device only.

EfiBlutoothSmpLocalER

It is a 128-bit Encryption Root (ER) key to generate LTK and CSRK. Data structure is UINT8[16]. See Bluetooth specification. This is only required when Bluetooth key hierarchy is supported. This type is for the local device only.

EfiBlutoothSmpLocalDHK

It is a 128-bit Diversifier Hiding Key (DHK) to generate EDIV. Data structure is UINT8[16]. See Bluetooth specification. This is only required when Bluetooth key hierarchy is supported. This type is for the local device only.

EfiBlutoothSmpKeysDistributed

It is LE Key Distribution Format. Data structure is UINT8. See Bluetooth specification. This is the peer device specific information.

EfiBlutoothSmpKeySize

It indicates the size of keys in bytes. It is the negotiated key size between local device and peer device. Data structure is UINTN. This is the peer device specific information.

EfiBlutoothSmpKeyType

Indicates support for MITM/Secure connection. It is the negotiated Authentication Requirements between local device and peer device. See Bluetooth Spec 3.H.3.5.1. Data structure is UINT8. BIT0: MITM, BIT1: SC. This is the peer device specific information.

EfiBlutoothSmpPeerLTK

It is a 128-bit Long-Term Key (LTK) to generate the contributory session key for an encrypted connection. Data structure is UINT8[16]. See Bluetooth specification. This is the peer device specific information.

EfiBlutoothSmpPeerIRK

It is a 128-bit Identity Resolving Key (IRK) to generate and resolve random addresses. Data structure is UINT8[16]. See Bluetooth specification. This is the peer device specific information.

EfiBlutoothSmpPeerCSRK

It is a 128-bit Connection-Signature Resolving Key (CSRK) to sign data and verify signatures on the receiving device. Data structure is UINT8[16]. See Bluetooth specification. This is the peer device specific information.

EfiBlutoothSmpPeerRand

It is a 64-bit Random number (Rand) to identify the LTK distributed during LE legacy pairing. Data structure is UINT64. See Bluetooth specification. This is the peer device specific information.

EfiBlutoothSmpPeerEDIV

It is a 16-bit Encrypted Diversifier (EDIV) to identify the LTK distributed during LE legacy pairing. Data structure is UINT16. See Bluetooth specification. This is the peer device specific information.

EfiBlutoothSmpPeerSignCounter

It is a 32-bit Sign Counter to assist MAC generation. Data structure is UINT32. See Bluetooth specification. This is the peer device specific information.

EfiBlutoothSmpLocalLTK

It is a 128-bit Long-Term Key (LTK) to generate the contributory session key for an encrypted connection. Data structure is UINT8[16]. See Bluetooth specification. This is the peer device specific information.
structure is UINT8[16]. See Bluetooth specification. This is only required when Bluetooth key hierarchy is not supported. This is the peer specific local device information.

**EfiBlutoothSmpLocalIRK**

It is a 128-bit Identity Resolving Key (IRK) to generate and resolve random addresses. Data structure is UINT8[16]. See Bluetooth specification. This is only required when Bluetooth key hierarchy is not supported. This is the peer specific local device information.

**EfiBlutoothSmpLocalCSRK**

It is a 128-bit Connection-Signature Resolving Key (CSRK) to sign data and verify signatures on the receiving device. Data structure is UINT8[16]. See Bluetooth specification. This is only required when Bluetooth key hierarchy is not supported. This is the peer specific local device information.

**EfiBlutoothSmpLocalSignCounter**

It is a 32-bit Sign Counter to assist MAC generation. Data structure is UINT32. See Bluetooth specification. This is the peer specific local device information.

**EfiBlutoothSmpLocalDIV**

It is a 16-bit Diversifier (DIV) to be used as index to recover LTK. Data structure is UINT16. See Bluetooth specification. This is the peer specific local device information.

**EfiBlutoothSmpPeerAddressList**

A list of Bluetooth peer addresses that have been connected before. The data structure is BLUE-TOOTH_LE_ADDRESS[]. The data size must be a multiple of sizeof(BLUETOOTH_LE_ADDRESS).

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The SMP get data callback function is registered successfully.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>A callback function is already registered on the same attribute opcode and attribute handle, when the Callback is not NULL.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>A callback function is not registered on the same attribute opcode and attribute handle, when the Callback is NULL.</td>
</tr>
</tbody>
</table>

**26.5.12 BLUETOOTH_LE_CONFIG_PROTOCOL.RegisterSmpSetDataCallback**

**Summary**

Register a callback function to set SMP related data.

**Prototype**

```c
typedef
 EFI_STATUS
 (EFIAPI * EFI_BLUETOOTH_LE_CONFIG_REGISTER_SMP_SET_DATA_CALLBACK )(
   IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL   *This,
   IN EFI_BLUETOOTH_LE_CONFIG_SMP_SET_DATA_CALLBACK Callback,
   IN VOID                              *Context
);
```

**Parameters**

**This**

Pointer to the *EFI_BLUETOOTH_LE_CONFIG_PROTOCOL* instance.

**Callback**

Callback function for SMP set data.
**Context**

Data passed into callback function. This is optional parameter and may be NULL.

**Description**

The `RegisterSmpSetDataCallback()` function registers a callback function to set SMP related data.

**Related Definitions**

```c
typedef EFI_STATUS (EFIAPI * EFI_BLUETOOTH_LE_CONFIG_SMP_SET_DATA_CALLBACK) (
    IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,
    IN VOID *Context,
    IN BLUETOOTH_LE_ADDRESS *BDAddr,
    IN EFI_BLUETOOTH_LE_SMP_DATA_TYPE Type,
    IN UINTN DataSize,
    IN VOID *Data );
```

This

Pointer to the `EFI_BLUETOOTH_LE_CONFIG_PROTOCOL` instance.

**Context**

Data passed into callback function. This is optional parameter and may be NULL.

**BDAddr**

Remote BluetoothLE device address.

**DataType**

Data type in `EFI_BLUETOOTH_LE_SMP_DATA_TYPE`.

**DataSize**

Indicates the size, in bytes, of the data buffer specified by `Data`.

**Data**

A pointer to the buffer of data.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The SMP get data callback function is registered successfully.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>A callback function is already registered on the same attribute opcode and attribute handle, when the Callback is not NULL.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>A callback function is not registered on the same attribute opcode and attribute handle, when the Callback is NULL.</td>
</tr>
</tbody>
</table>

**26.5.13 BLUETOOTH_LE_CONFIG_PROTOCOL.RegisterLinkConnectCompleteCallback**

**Summary**

Register link connect complete callback function.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_BLUETOOTH_LE_CONFIG_REGISTER_CONNECT_COMPLETE_CALLBACK) (continues on next page)
```
Parameters

This

Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

Callback

The callback function. NULL means unregister.

Context

Data passed into Callback function. This is optional parameter and may be NULL.

Description

The RegisterLinkConnectCompleteCallback() function registers Bluetooth link connect complete callback function. The Bluetooth Configuration driver may call RegisterLinkConnectCompleteCallback() to register a callback function. During pairing, Bluetooth bus driver must trigger this callback function to report device state, if it is registered. Then Bluetooth Configuration driver will get information on device connection, according to CallbackType defined by EFI_BLUETOOTH_CONNECT_COMPLETE_CALLBACK_TYPE.

Related Definitions

typedef

EFI_STATUS (EFIAPI *EFI_BLUETOOTH_LE_CONFIG_CONNECT_COMPLETE_CALLBACK) (  
  IN EFI_BLUETOOTH_LE_CONFIG_PROTOCOL *This,  
  IN VOID *Context,  
  IN EFI_BLUETOOTH_CONNECT_COMPLETE_CALLBACK_TYPE CallbackType,  
  IN BLUETOOTH_LE_ADDRESS *BDAddr,  
  IN VOID *InputBuffer,  
  IN UINTN InputBufferSize  
);  

This

Pointer to the EFI_BLUETOOTH_LE_CONFIG_PROTOCOL instance.

Context

Context passed from registration.

CallbackType

Callback type in EFI_BLUETOOTH_CONNECT_COMPLETE_CALLBACK_TYPE.

BDAddr

A pointer to BluetoothLE device address.

InputBuffer

A pointer to the buffer of data that is input from callback caller.

InputBufferSize

Indicates the size, in bytes, of the data buffer specified by InputBuffer.

Status Codes Returned
<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The link connect complete callback function is registered successfully.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>A callback function is already registered on the same attribute opcode and attribute handle, when the Callback is not NULL.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>A callback function is not registered on the same attribute opcode and attribute handle, when the Callback is NULL.</td>
</tr>
</tbody>
</table>
CHAPTER TWENTYSEVEN

NETWORK PROTOCOLS — VLAN, EAP, WI-FI AND SUPPLICANT

27.1 VLAN Configuration Protocol

27.1.1 EFI_VLAN_CONFIG_PROTOCOL

Summary
This protocol is to provide manageability interface for VLAN configuration.

GUID

```c
#define EFI_VLAN_CONFIG_PROTOCOL_GUID
{0x9e23d768, 0xd2f3, 0x4366,
 {0x9f, 0xc3, 0x3a, 0x7a, 0xba, 0x86, 0x43, 0x74}}
```

Protocol Interface Structure

```c
typedef struct _EFI_VLAN_CONFIG_PROTOCOL {
   EFI_VLAN_CONFIG_SET Set;
   EFI_VLAN_CONFIG_FIND Find;
   EFI_VLAN_CONFIG_REMOVE Remove;
} EFI_VLAN_CONFIG_PROTOCOL;
```

Parameters

Set
Create new VLAN device or modify configuration parameter of an already-configured VLAN

Find
Find configuration information for specified VLAN or all configured VLANs.

Remove
Remove a VLAN device.

Description
This protocol is to provide manageability interface for VLAN setting. The intended VLAN tagging implementation is IEEE802.1Q.
27.1.2 EFI_VLAN_CONFIG_PROTOCOL.Set()

Summary
Create a VLAN device or modify the configuration parameter of an already-configured VLAN

Prototype

```c
typedef
EFI_STATUS
(EFIAPID * EFI_VLAN_CONFIG_SET) (
    IN EFI_VLAN_CONFIG_PROTOCOL *This,
    IN UINT16 VlanId,
    IN UINT8 Priority
);
```

Parameters

This
Pointer to EFI_VLAN_CONFIG_PROTOCOL instance.

VlanId
A unique identifier (1-4094) of the VLAN which is being created or modified, or zero (0).

Priority
3 bit priority in VLAN header. Priority 0 is default value. If VlanId is zero (0), Priority is ignored.

Description
The Set() function is used to create a new VLAN device or change the VLAN configuration parameters. If the VlanId hasn’t been configured in the physical Ethernet device, a new VLAN device will be created. If a VLAN with this VlanId is already configured, then related configuration will be updated as the input parameters.

If VlanId is zero, the VLAN device will send and receive untagged frames. Otherwise, the VLAN device will send and receive VLAN-tagged frames containing the VlanId.

If VlanId is out of scope of (0-4094), EFI_INVALID_PARAMETER is returned.

If Priority is out of the scope of (0-7), then EFI_INVALID_PARAMETER is returned.

If there is not enough system memory to perform the registration, then EFI_OUT_OF_RESOURCES is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The VLAN is successfully configured</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of following conditions is TRUE</td>
</tr>
<tr>
<td></td>
<td>• This is NULL</td>
</tr>
<tr>
<td></td>
<td>• VlanId is an invalid VLAN Identifier</td>
</tr>
<tr>
<td></td>
<td>• Priority is invalid</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There is not enough system memory to perform the registration.</td>
</tr>
</tbody>
</table>
27.1.3 EFI_VLAN_CONFIG_PROTOCOL.Find()

Summary
Find configuration information for specified VLAN or all configured VLANs.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_VLAN_CONFIG_FIND) (
    IN EFI_VLAN_CONFIG_PROTOCOL *This,
    IN UINT16 *VlanId, OPTIONAL
    OUT UINT16 *NumberOfVlan,
    OUT EFI_VLAN_FIND_DATA **Entries
);
```

Parameters

- **This**
  Pointer to EFI_VLAN_CONFIG_PROTOCOL instance.

- **VlanId**
  Pointer to VLAN identifier. Set to NULL to find all configured VLANs

- **NumberOfVlan**
  The number of VLANs which is found by the specified criteria

- **Entries**
  The buffer which receive the VLAN configuration. Type EFI_VLAN_FIND_DATA is defined below.

Description

The Find() function is used to find the configuration information for matching VLAN and allocate a buffer into which those entries are copied.

Related Definitions

```c
//**************************************************************
// EFI_VLAN_FIND_DATA
//**************************************************************
typedef struct {
    UINT16 VlanId;
    UINT8 Priority;
} EFI_VLAN_FIND_DATA;
```

- **VlanId**
  Vlan Identifier

- **Priority**
  Priority of this VLAN

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The VLAN is successfully found</td>
</tr>
</tbody>
</table>

continues on next page
Table 27.2 – continued from previous page

| EFI_INVALID_PARAMETER | One or more of following conditions is TRUE  
|                       | • This is NULL  
|                       | • Specified VlanId is invalid |
| EFI_NOT_FOUND         | No matching VLAN is found |

27.1.4 EFI_VLAN_CONFIG_PROTOCOL.Remove()

Summary
Remove the configured VLAN device

Prototype

typedef
EFI_STATUS
(EFI_API * EFI_VLAN_CONFIG_REMOVE) (  
    IN EFI_VLAN_CONFIG_PROTOCOL *This,  
    IN UINT16 VlanId  
);

Parameters

This
Pointer to EFI_VLAN_CONFIG_PROTOCOL instance.

VlanId
Identifier (0-4094) of the VLAN to be removed.

Description
The Remove() function is used to remove the specified VLAN device. If the VlanId is out of the scope of (0-4094), EFI_INVALID_PARAMETER is returned. If specified VLAN hasn’t been previously configured, EFI_NOT_FOUND is returned.

Status Codes Returned

| EFI_SUCCESS | The VLAN is successfully removed |
| EFI_INVALID_PARAMETER | One or more of following conditions is TRUE  
|                       | • This is NULL  
|                       | • VlanId is an invalid parameter. |
| EFI_NOT_FOUND | The to-be-removed VLAN does not exist |
27.2 EAP Protocol

This section defines the EAP protocol. This protocol is designed to make the EAP framework configurable and extensible. It is intended for the supplicant side.

27.2.1 EFI_EAP_PROTOCOL

Summary

This protocol is used to abstract the ability to configure and extend the EAP framework.

GUID

```c
#define EFI_EAP_PROTOCOL_GUID \
{ 0x5d9f96db, 0xe731, 0x4caa,\ 
 {0xa0, 0x0d, 0x72, 0xe1, 0x87, 0xcd, 0x77, 0x62 }}
```

Protocol Interface Structure

```c
typedef struct _EFI_EAP_PROTOCOL {
    EFI_EAP_SET_DESIRED_AUTHENTICATION_METHOD SetDesiredAuthMethod;
    EFI_EAP_REGISTER_AUTHENTICATION_METHOD RegisterAuthMethod;
} EFI_EAP_PROTOCOL;
```

Parameters

**SetDesiredAuthMethod**
Set the desired EAP authentication method for the Port. See the `SetDesiredAuthMethod()` function description.

**RegisterAuthMethod**
Register an EAP authentication method. See the `RegisterAuthMethod()` function description.

Description

`EFI_EAP_PROTOCOL` is used to configure the desired EAP authentication method for the EAP framework and extend the EAP framework by registering new EAP authentication method on a Port. The EAP framework is built on a per-Port basis. Herein, a Port means a NIC. For the details of EAP protocol, please refer to RFC 2284.

Related Definitions

```c
// Type for the identification number assigned to the Port by the
// System in which the Port resides.
//
typedef VOID * EFI_PORT_HANDLE;
```
27.2.2 EFI_EAP.SetDesiredAuthMethod()

Summary
Set the desired EAP authentication method for the Port.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_EAP_SET_DESIRED_AUTHENTICATION_METHOD) (
    IN struct _EFI_EAP_PROTOCOL *This,    
    IN UINT8 EapAuthType
);
```

Parameters

This
A pointer to the EFI_EAP_PROTOCOL instance that indicates the calling context. Type EFI_EAP_PROTOCOL is defined in Section 1.1.

EapAuthType
The type of the desired EAP authentication method for the Port. It should be the type value defined by RFC. See RFC 2284 for details. Current valid values are defined in “Related Definitions”.

Related Definitions

```c
// EAP Authentication Method Type (RFC 3748)
#define EFI_EAP_TYPE_TLS 13 /* REQUIRED - RFC 5216 */
```

Description

The SetDesiredAuthMethod() function sets the desired EAP authentication method indicated by EapAuthType for the Port.

If EapAuthType is an invalid EAP authentication type, then EFI_INVALID_PARAMETER is returned.

If the EAP authentication method of EapAuthType is unsupported, then it will return EFI_UNSUPPORTED.

The cryptographic strength of EFI_EAP_TYPE_TLS shall be at least of hash strength SHA-256 and RSA key length of at least 2048 bits.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The desired EAP authentication method is set successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>EapAuthType is an invalid EAP authentication type.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The EAP authentication method of EapAuthType is unsupported by the Port.</td>
</tr>
</tbody>
</table>
27.2.3 EFI_EAP.RegisterAuthMethod()

Summary
Register an EAP authentication method.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_EAP_REGISTER_AUTHENTICATION_METHOD) (
    IN struct _EFI_EAP_PROTOCOL *This,
    IN UINT8 EapAuthType,
    IN EFI_EAP_BUILD_RESPONSE_PACKET Handler
);
```

Parameters

This
A pointer to the EFI_EAP_PROTOCOL instance that indicates the calling context. Type EFI_EAP_PROTOCOL is defined in Section 1.1.

EapAuthType
The type of the EAP authentication method to register. It should be the type value defined by RFC. See RFC 2284 for details. Current valid values are defined in the SetDesiredAuthMethod() function description.

Handler
The handler of the EAP authentication method to register. Type EFI_EAP_BUILD_RESPONSE_PACKET is defined in “Related Definitions”.

Related Definitions

```c
typedef EFI_STATUS (EFIAPI *EFI_EAP_BUILD_RESPONSE_PACKET) (
    IN EFI_PORT_HANDLE PortNumber,
    IN UCHAR *RequestBuffer,
    IN UINTN RequestSize,
    IN UCHAR *Buffer,
    IN OUT UINTN *BufferSize
);
```

Routine Description:
Build EAP response packet in response to the EAP request packet specified by (RequestBuffer, RequestSize).

Arguments

PortNumber — Specified the Port where the EAP request packet comes.
RequestBuffer — Pointer to the most recently received EAP-Request packet.
RequestSize — Packet size in bytes for the most recently received EAP-Request packet.
Buffer — Pointer to the buffer to hold the built packet.
BufferSize — Pointer to the buffer size in bytes. On input, it is the buffer size provided by the caller. On output, it is the buffer size in fact needed to contain the packet.
Returns:

  EFI_SUCCESS — The required EAP response packet is built successfully. Others — Failures are encountered during the packet building process.

Description

The RegisterAuthMethod() function registers the user provided EAP authentication method, the type of which is EapAuthType and the handler of which is Handler.

If EapAuthType is an invalid EAP authentication type, then EFI_INVALID_PARAMETER is returned.

If there is not enough system memory to perform the registration, then EFI_OUT_OF_RESOURCES is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The EAP authentication method of EapAuthType is registered successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>EapAuthType is an invalid EAP authentication type.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There is not enough system memory to perform the registration.</td>
</tr>
</tbody>
</table>

27.2.4 EAP Management Protocol

This section defines the EAP management protocol. This protocol is designed to provide ease of management and ease of test for EAPOL state machine. It is intended for the supplicant side. It conforms to IEEE 802.1x specification.

27.2.5 EFI_EAP_MANAGEMENT_PROTOCOL

Summary

This protocol provides the ability to configure and control EAPOL state machine, and retrieve the status and the statistics information of EAPOL state machine.

GUID

```c
#define EFI_EAP_MANAGEMENT_PROTOCOL_GUID 
{ 0xbb62e663, 0x625d, 0x40b2, 
{ 0xa0, 0x88, 0xbb, 0xe8, 0x36, 0x23, 0xa2, 0x45 }
```

Protocol Interface Structure

```c
typedef struct _EFI_EAP_MANAGEMENT_PROTOCOL {
  EFI_EAP_GET_SYSTEM_CONFIGURATION GetSystemConfiguration;
  EFI_EAP_SET_SYSTEM_CONFIGURATION SetSystemConfiguration;
  EFI_EAP_INITIALIZE_PORT InitializePort;
  EFI_EAP_USER_LOGON UserLogon;
  EFI_EAP_USER_LOGOFF UserLogoff;
  EFI_EAP_GET_SUPPLICANT_STATUS GetSupplicantStatus;
  EFI_EAP_SET_SUPPLICANT_CONFIGURATION SetSupplicantConfiguration;
  EFI_EAP_GET_SUPPLICANT_STATISTICS GetSupplicantStatistics;
} EFI_EAP_MANAGEMENT_PROTOCOL;
```

Parameters

GetSystemConfiguration

  Read the system configuration information associated with the Port. See the GetSystemConfiguration() function description.
SetSystemConfiguration
Set the system configuration information associated with the Port. See the SetSystemConfiguration() function description.

InitializePort
Cause the EAPOL state machines for the Port to be initialized. See the InitializePort() function description.

UserLogon
Notify the EAPOL state machines for the Port that the user of the System has logged on. See the UserLogon() function description.

UserLogoff
Notify the EAPOL state machines for the Port that the user of the System has logged off. See the UserLogoff() function description.

GetSupplicantStatus
Read the status of the Supplicant PAE state machine for the Port, including the current state and the configuration of the operational parameters. See the GetSupplicantStatus() function description.

SetSupplicantConfiguration
Set the configuration of the operational parameter of the Supplicant PAE state machine for the Port. See the SetSupplicantConfiguration() function description.

GetSupplicantStatistics
Read the statistical information regarding the operation of the Supplicant associated with the Port. See the GetSupplicantStatistics() function description.

Description
The EFI_EAP_MANAGEMENT protocol is used to control, configure and monitor EAPOL state machine on a Port. EAPOL state machine is built on a per-Port basis. Herein, a Port means a NIC. For the details of EAPOL, please refer to IEEE 802.1x specification.

27.2.6 EFI_EAP_MANAGEMENT.GetSystemConfiguration()

Summary
Read the system configuration information associated with the Port.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_EAP_GET_SYSTEM_CONFIGURATION) (    
    IN struct _EFI_EAP_MANAGEMENT_PROTOCOL *This,
    OUT BOOLEAN *SystemAuthControl,
    OUT EFI_EAPOL_PORT_INFO *PortInfo OPTIONAL
    );

Parameters

This
A pointer to the EFI_EAP_MANAGEMENT_PROTOCOL instance that indicates the calling context. Type EFI_EAP_MANAGEMENT_PROTOCOL is defined in EAPManagement Protocol.

SystemAuthControl
Returns the value of the SystemAuthControl parameter of the System. TRUE means Enabled. FALSE means Disabled.
PortInfo

Returns EFI_EAPOL_PORT_INFO structure to describe the Port’s information. This parameter can be NULL to ignore reading the Port’s information. Type EFI_EAPOL_PORT_INFO is defined in “Related Definitions”.

Related Definitions

```c
// PAE Capabilities

//
#define PAE_SUPPORT_AUTHENTICATOR 0x01
#define PAE_SUPPORT_SUPPLICANT 0x02

typedef struct _EFI_EAPOL_PORT_INFO {
    EFI_PORT_HANDLE PortNumber;
    UINT8 ProtocolVersion;
    UINT8 PaeCapabilities;
} EFI_EAPOL_PORT_INFO;
```

PortNumber

The identification number assigned to the Port by the System in which the Port resides.

ProtocolVersion

The protocol version number of the EAPOL implementation supported by the Port.

PaeCapabilities

The capabilities of the PAE associated with the Port. This field indicates whether Authenticator functionality, Supplicant functionality, both, or neither, is supported by the Port’s PAE.

Description

The GetSystemConfiguration() function reads the system configuration information associated with the Port, including the value of the SystemAuthControl parameter of the System is returned in SystemAuthControl and the Port’s information is returned in the buffer pointed to by PortInfo. The Port’s information is optional. If PortInfo is NULL, then reading the Port’s information is ignored.

If SystemAuthControl is NULL, then EFI_INVALID_PARAMETER is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The system configuration information of the Port is read successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>SystemAuthControl is NULL.</td>
</tr>
</tbody>
</table>

27.2.7 EFI_EAP_MANAGEMENT.SetSystemConfiguration()

Summary

Set the system configuration information associated with the Port.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_EAP_SET_SYSTEM_CONFIGURATION) (   
    IN struct _EFI_EAP_MANAGEMENT_PROTOCOL   *This,   
    IN BOOLEAN SystemAuthControl
    );
```
Parameters

This
A pointer to the EFI_EAP_MANAGEMENT_PROTOCOL instance that indicates the calling context. Type EFI_EAP_MANAGEMENT_PROTOCOL is defined in EAPManagement Protocol.

SystemAuthControl
The desired value of the SystemAuthControl parameter of the System. TRUE means Enabled. FALSE means Disabled.

Description
The SetSystemConfiguration() function sets the value of the SystemAuthControl parameter of the System to SystemAuthControl.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The system configuration information of the Port is set successfully.</td>
</tr>
</tbody>
</table>

27.2.8 EFI_EAP_MANAGEMENT.InitializePort()

Summary
Cause the EAPOL state machines for the Port to be initialized.

Prototype

define

typedef

EFI_STATUS

(EFIAPI *EFI_EAP_INITIALIZE_PORT) (

    IN struct _EFI_EAP_MANAGEMENT_PROTOCOL *This

);

Parameters

This
A pointer to the EFI_EAP_MANAGEMENT_PROTOCOL instance that indicates the calling context. Type EFI_EAP_MANAGEMENT_PROTOCOL is defined in EAPManagement Protocol.

Description
The InitializePort() function causes the EAPOL state machines for the Port.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Port is initialized successfully.</td>
</tr>
</tbody>
</table>

27.2.9 EFI_EAP_MANAGEMENT.UserLogon()

Summary
Notify the EAPOL state machines for the Port that the user of the System has logged on.

Prototype
typedef EFI_STATUS (EFIAPI *EFI_EAP_USER_LOGON) (IN struct _EFI_EAP_MANAGEMENT_PROTOCOL *This,
);

Parameters

This
A pointer to the EFI_EAP_MANAGEMENT_PROTOCOL instance that indicates the calling context. Type EFI_EAP_MANAGEMENT_PROTOCOL is defined in EAPManagement Protocol.

Description
The UserLogon() function notifies the EAPOL state machines for the Port.

Status Codes Returned

| EFI_SUCCESS       | The Port is notified successfully. |

27.2.10 EFI_EAP_MANAGEMENT.UserLogoff()

Summary
Notify the EAPOL state machines for the Port that the user of the System has logged off.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_EAP_USER_LOGOFF) (IN struct _EFI_EAP_MANAGEMENT_PROTOCOL *This,
);

Parameters

This
A pointer to the EFI_EAP_MANAGEMENT_PROTOCOL instance that indicates the calling context. Type EFI_EAP_MANAGEMENT_PROTOCOL is defined in EAPManagement Protocol.

Description
The UserLogoff() function notifies the EAPOL state machines for the Port.

Status Codes Returned

| EFI_SUCCESS       | The Port is notified successfully. |
27.2.11 EFI_EAP_MANAGEMENT.GetSupplicantStatus()

**Summary**

Read the status of the Supplicant PAE state machine for the Port, including the current state and the configuration of the operational parameters.

**Prototype**

```c
typedef EFI_STATUS
(EIFIAP *EFI_EAP_GET_SUPPLICANT_STATUS) (
    IN struct _EFI_EAP_MANAGEMENT_PROTOCOL *This,
    OUT EFI_EAPOL_SUPPLICANT_PAE_STATE *CurrentState,
    IN OUT EFI_EAPOL_SUPPLICANT_PAE_CONFIGURATION *Configuration OPTIONAL
);
```

**Parameters**

**This**

A pointer to the `EFI_EAP_MANAGEMENT_PROTOCOL` instance that indicates the calling context. Type `EFI_EAP_MANAGEMENT_PROTOCOL` is defined in `EAPManagement Protocol`.

**CurrentState**

Returns the current state of the Supplicant PAE state machine for the Port. Type `EFI_EAPOL_SUPPLICANT_PAE_STATE` is defined in “Related Definitions”.

**Configuration**

Returns the configuration of the operational parameters of the Supplicant PAE state machine for the Port as required. This parameter can be `NULL` to ignore reading the configuration. On input, `Configuration. ValidFieldMask` specifies the operational parameters to be read. On output, `Configuration` returns the configuration of the required operational parameters. Type `EFI_EAPOL_SUPPLICANT_PAE_CONFIGURATION` is defined in “Related Definitions”.

**Related Definitions**

```c
//
// Supplicant PAE state machine (IEEE Std 802.1X Section 8.5.10)
//
typedef enum _EFI_EAPOL_SUPPLICANT_PAE_STATE {
    Logoff,  
    Disconnected,  
    Connecting,  
    Acquired,  
    Authenticating,  
    Held,  
    Authenticated,
    MaxSupplicantPaeState
  } EFI_EAPOL_SUPPLICANT_PAE_STATE;

//
// Definitions for ValidFieldMask
//
#define AUTH_PERIOD_FIELD_VALID    0x01
#define HELD_PERIOD_FIELD_VALID    0x02
#define START_PERIOD_FIELD_VALID   0x04
```

(continues on next page)
```c
#define MAX_START_FIELD_VALID 0x08

typedef struct _EFI_EAPOL_SUPPLICANT_PAE_CONFIGURATION {
    UINT8 ValidFieldMask;
    UINTN AuthPeriod;
    UINTN HeldPeriod;
    UINTN StartPeriod;
    UINTN MaxStart;
} EFI_EAPOL_SUPPLICANT_PAE_CONFIGURATION;
```

**ValidFieldMask**
Indicates which of the following fields are valid.

**AuthPeriod**
The initial value for the authWhile timer. Its default value is 30 s.

**HeldPeriod**
The initial value for the heldWhile timer. Its default value is 60 s.

**StartPeriod**
The initial value for the startWhen timer. Its default value is 30 s.

**MaxStart**
The maximum number of successive EAPOL-Start messages will be sent before the Supplicant assumes that there is no Authenticator present. Its default value is 3.

**Description**
The `GetSupplicantStatus()` function reads the status of the Supplicant PAE state machine for the Port, including the current state `CurrentState` and the configuration of the operational parameters `Configuration`. The configuration of the operational parameters is optional. If `Configuration` is `NULL`, then reading the configuration is ignored. The operational parameters in `Configuration` to be read can also be specified by `Configuration. ValidFieldMask`.

If `CurrentState` is `NULL`, then `EFI_INVALID_PARAMETER` is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The status of the Supplicant PAE state machine for the Port is read successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>CurrentState</code> is <code>NULL</code>.</td>
</tr>
</tbody>
</table>

### 27.2.12 `EFI_EAP_MANAGEMENT.SetSupplicantConfiguration()`

**Summary**
Set the configuration of the operational parameter of the Supplicant PAE state machine for the Port.

**Prototype**
```c
typedef
EFI_STATUS
(EIFIAPI *EFI_EAP_SET_SUPPLICANT_CONFIGURATION) (  
    IN struct _EFI_EAP_MANAGEMENT_PROTOCOL *This,  
    IN EFI_EAPOL_SUPPLICANT_PAE_CONFIGURATION *Configuration  
);
```
Parameters

**This**
A pointer to the `EFI_EAP_MANAGEMENT_PROTOCOL` instance that indicates the calling context. Type `EFI_EAP_MANAGEMENT_PROTOCOL` is defined in EAP Management Protocol.

**Configuration**
The desired configuration of the operational parameters of the Supplicant PAE state machine for the Port as required. Type `EFI_EAPOL_SUPPLICANT_PAE_CONFIGURATION` is defined in the `GetSupplicantStatus()` function description.

Description
The `SetSupplicantConfiguration()` function sets the configuration of the operational parameter of the Supplicant PAE state machine for the Port to Configuration. The operational parameters in Configuration to be set can be specified by Configuration.ValidFieldMask.

If Configuration is NULL, then EFI_INVALID_PARAMETER is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The configuration of the operational parameter of the Supplicant PAE state machine for the Port is set successfully.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Configuration is NULL.</td>
</tr>
</tbody>
</table>

### 27.2.13 EFI_EAP_MANAGEMENT.GetSupplicantStatistics()

**Summary**

Read the statistical information regarding the operation of the Supplicant associated with the Port.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_EAP_GET_SUPPLICANT_STATISTICS) (
    IN struct _EFI_EAP_MANAGEMENT_PROTOCOL *This,
    OUT EFI_EAPOL_SUPPLICANT_PAE_STATISTICS *Statistics
);
```

**Parameters**

**This**
A pointer to the `EFI_EAP_MANAGEMENT_PROTOCOL` instance that indicates the calling context. Type `EFI_EAP_MANAGEMENT_PROTOCOL` is defined in EAP Management Protocol.

**Statistics**
Returns the statistical information regarding the operation of the Supplicant for the Port. Type `EFI_EAPOL_SUPPLICANT_PAE_STATISTICS` is defined in “Related Definitions”.

**Related Definitions**

// Supplicant Statistics (IEEE Std 802.1X Section 9.5.2)
//
typedef struct _EFI_EAPOL_SUPPLICANT_PAE_STATISTICS {
    UINTN EapolFramesReceived;
    UINTN EapolFramesTransmitted;
}
EapolFramesReceived
   The number of EAPOL frames of any type that have been received by this Supplicant.

EapolFramesTransmitted
   The number of EAPOL frames of any type that have been transmitted by this Supplicant.

EapolStartFramesTransmitted
   The number of EAPOL Start frames that have been transmitted by this Supplicant.

EapolLogoffFramesTransmitted
   The number of EAPOL Logoff frames that have been transmitted by this Supplicant.

EapRespIdFramesTransmitted
   The number of EAP Resp/Id frames that have been transmitted by this Supplicant.

EapResponseFramesTransmitted
   The number of valid EAP Response frames (other than Resp/Id frames) that have been transmitted by this Supplicant.

EapReqIdFramesReceived
   The number of EAP Req/Id frames that have been received by this Supplicant.

EapRequestFramesReceived
   The number of EAP Request frames (other than Rq/Id frames) that have been received by this Supplicant.

InvalidEapolFramesReceived
   The number of EAPOL frames that have been received by this Supplicant in which the frame type is not recognized.

EapLengthErrorFramesReceived
   The number of EAPOL frames that have been received by this Supplicant in which the Packet Body Length field (7.5.5) is invalid.

LastEapolFrameVersion
   The protocol version number carried in the most recently received EAPOL frame.

LastEapolFrameSource
   The source MAC address carried in the most recently received EAPOL frame.

Description
The GetSupplicantStatistics() function reads the statistical information Statistics regarding the operation of the Supplicant associated with the Port.

If Statistics is NULL, then EFI_INVALID_PARAMETER is returned.

Status Codes Returned
 EFI_SUCCESS  The statistical information regarding the operation of the Supplicant for the Port is read successfully.
 EFI_INVALID_PARAMETER  Statistics is NULL.

27.2.14 EFI EAP Management2 Protocol

27.2.14.1 EFI_EAP_MANAGEMENT2_PROTOCOL

Summary
This protocol provides the ability to configure and control EAPOL state machine, and retrieve the information, status and the statistics information of EAPOL state machine.

GUID

```
#define EFI_EAP_MANAGEMENT2_PROTOCOL_GUID \\
{ 0x5e93c847, 0x456d, 0x40b3, \\
 { 0xa6, 0xb4, 0x78, 0xb0, 0xc9, 0xcf, 0x7f, 0x20 }}
```

Protocol Interface Structure

```
typedef struct _EFI_EAP_MANAGEMENT2_PROTOCOL {
    ....... // Same as EFI_EAP_MANAGEMENT_PROTOCOL
    EFI_EAP_GET_KEY GetKey;
} EFI_EAP_MANAGMENT2_PROTOCOL;
```

Parameters

GetKey
Provide Key information parsed from EAP packet. See the GetKey() function description.

Description
The EFI_EAP_MANAGEMENT2_PROTOCOL is used to control, configure and monitor EAPOL state machine on a Port, and return information of the Port. EAPOL state machine is built on a per-Port basis. Herein, a Port means a NIC. For the details of EAPOL, please refer to IEEE 802.1x specification.

27.2.15 EFI_EAP_MANAGEMENT2_PROTOCOL.GetKey()

Summary
Return key generated through EAP process.

Prototype

```
typedef
EFI_STATUS
(EFIAPIM *EFI_EAP_GET_KEY) ( 
    IN EFI_EAP_MANAGEMENT2_PROTOCOL *This, 
    IN OUT UINT8 *Msk, 
    IN OUT UINTN *MskSize, 
    IN OUT UINT8 *Emsk, 
    IN OUT UINT8 *EmskSize 
);
Parameters

This

Pointer to the EFI_EAP_MANAGEMENT2_PROTOCOL instance.

Msk

Pointer to MSK (Master Session Key) buffer.

MskSize

MSK buffer size.

Emsk

Pointer to EMSK (Extended Master Session Key) buffer.

EmskSize

EMSK buffer size.

Description

The GetKey() function return the key generated through EAP process, so that the 802.11 MAC layer driver can use MSK to derive more keys, e.g. PMK (Pairwise Master Key).

Status Codes Returned

<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The operation completed successfully.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• Msk is NULL.</td>
</tr>
<tr>
<td></td>
<td>• MskSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Emsk is NULL.</td>
</tr>
<tr>
<td></td>
<td>• EmskSize is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>MSK and EMSK are not generated in current session yet.</td>
</tr>
</tbody>
</table>

27.2.16 EFI EAP Configuration Protocol

27.2.16.1 EFI_EAP_CONFIGURATION_PROTOCOL

Summary

This protocol provides a way to set and get EAP configuration.

GUID

```c
#define EFI_EAP_CONFIGURATION_PROTOCOL_GUID \
{ 0xe5b58dbb, 0x7688, 0x44b4, \ 
{ 0x97, 0xbf, 0x5f, 0x1d, 0x4b, 0x7c, 0xc8, 0xdb }}
```

Protocol Interface Structure

```c
typedef struct _EFI_EAP_CONFIGURATION_PROTOCOL {
    EFI_EAP_CONFIGURATION_SET_DATA    SetData;
    EFI_EAP_CONFIGURATION_GET_DATA    GetData;
} EFI_EAP_CONFIGURATION_PROTOCOL;
```
SetData
Set EAP configuration data. See the SetData() function description.

GetData
Get EAP configuration data. See the GetData() function description.

Description
The EFI_EAP_CONFIGURATION_PROTOCOL is designed to provide a way to set and get EAP configuration, such as Certificate, private key file.

27.2.17 EFI_EAP_CONFIGURATION_PROTOCOL.SetData()

Summary
Set EAP configuration data.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_EAP_CONFIGURATION_SET_DATA)(
    IN EFI_EAP_CONFIGURATION_PROTOCOL *This,
    IN EFI_EAP_TYPE EapType,
    IN EFI_EAP_CONFIG_DATA_TYPE DataType,
    IN VOID *Data,
    IN UINTN DataSize
);  

Parameters

This
Pointer to the EFI_EAP_CONFIGURATION_PROTOCOL instance.

EapType
EAP type. See EFI_EAP_TYPE.

DataType
Configuration data type. See EFI_EAP_CONFIG_DATA_TYPE

Data
Pointer to configuration data.

DataSize
Total size of configuration data.

Description
The SetData() function sets EAP configuration to non-volatile storage or volatile storage.

Related Definitions

//
// Make sure it not conflict with any real EapTypeXXX
//
#define EFI_EAP_TYPE_ATTRIBUTE 0

typedef enum {
    // EFI_EAP_TYPE_ATTRIBUTE
(continues on next page)
EfiEapConfigEapAuthMethod,
EfiEapConfigEapSupportedAuthMethod,
  // EapTypeIdentity
EfiEapConfigIdentityString,
  // EapTypeEAPTLS/EapTypePEAP
EfiEapConfigEapTlsCA_cert,
EfiEapConfigEapTlsClientCert,
EfiEapConfigEapTlsClientPrivateKeyFile,
EfiEapConfigEapTlsClientPrivateKeyFilePassword,\n  // ASCII format, Volatile
EfiEapConfigEapTlsCipherSuite,
EfiEapConfigEapTlsSupportedCipherSuite,
  // EapTypeMSChapV2
EfiEapConfigEapMSChapV2Password, // UNICODE format, Volatile
  // EapTypePEAP
EfiEapConfigEap2ndAuthMethod,
  // More...
} EFI_EAP_CONFIG_DATA_TYPE;

//
// EFI_EAP_TYPE
//
typedef UINT8 EFI_EAP_TYPE;
#define EFI_EAP_TYPE_ATTRIBUTE 0
#define EFI_EAP_TYPE_IDENTITY 1
#define EFI_EAP_TYPE_NOTIFICATION 2
#define EFI_EAP_TYPE_NAK 3
#define EFI_EAP_TYPE_MD5CHALLENGE 4
#define EFI_EAP_TYPE_OTP 5
#define EFI_EAP_TYPE_GTC 6
#define EFI_EAP_TYPE_EAPTLS 13
#define EFI_EAP_TYPE_EAPSIM 18
#define EFI_EAP_TYPE_TTLS 21
#define EFI_EAP_TYPE_PEAP 25
#define EFI_EAP_TYPE_MSCHAPV2 26
#define EFI_EAP_TYPE_EAP_EXTENSION 33

......

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The EAP configuration data is set successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL.</td>
</tr>
<tr>
<td></td>
<td>• DataSize is 0.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The EapType or DataType is unsupported.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
</tbody>
</table>

27.2. EAP Protocol
27.2.18 EFI_EAP_CONFIGURATION_PROTOCOL.GetData()

Summary
Get EAP configuration data.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI * EFI_EAP_CONFIGURATION_GET_DATA)(
    IN EFI_EAP_CONFIGURATION_PROTOCOL *This,
    IN EFI_EAP_TYPE EapType,
    IN EFI_EAP_CONFIG_DATA_TYPE DataType,
    IN OUT VOID *Data,
    IN OUT UINTN *DataSize
);
```

Parameters

This
    Pointer to the EFI_EAP_CONFIGURATION_PROTOCOL instance.

EapType
    EAP type. See EFI_EAP_TYPE.

DataType
    Configuration data type. See EFI_EAP_CONFIG_DATA_TYPE

Data
    Pointer to configuration data.

DataSize
    Total size of configuration data. On input, it means the size of Data * buffer. On output, it means the size of copied *Data buffer if EFI_SUCCESS, and means the size of desired Data buffer if EFI_BUFFER_TOO_SMALL.

Description
The GetData() function gets EAP configuration.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The EAP configuration data is got successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL.</td>
</tr>
<tr>
<td></td>
<td>• DataSize is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The EapType or DataType is unsupported.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The EAP configuration data is not found.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The buffer is too small to hold the buffer.</td>
</tr>
</tbody>
</table>
27.3 EFI Wireless MAC Connection Protocol

27.3.1 EFI_WIRELESS_MAC_CONNECTION_PROTOCOL

Summary
This protocol provides management service interfaces of 802.11 MAC layer. It is used by network applications (and drivers) to establish wireless connection with an access point (AP).

GUID

```c
#define EFI_WIRELESS_MAC_CONNECTION_PROTOCOL_GUID
  { 0xda55bc9, 0x45f8, 0x4bb4,
    { 0x87, 0x19, 0x52, 0x24, 0xf1, 0x8a, 0x4d, 0x45 }}
```

Protocol Interface Structure

```c
typedef struct _EFI_WIRELESS_MAC_CONNECTION_PROTOCOL {
  EFI_WIRELESS_MAC_CONNECTION_SCAN Scan;
  EFI_WIRELESS_MAC_CONNECTION_ASSOCIATE Associate;
  EFI_WIRELESS_MAC_CONNECTION_DISASSOCIATE Disassociate;
  EFI_WIRELESS_MAC_CONNECTION_AUTHENTICATE Authenticate;
  EFI_WIRELESS_MAC_CONNECTION_DEAUTHENTICATE Deauthenticate;
} EFI_WIRELESS_MAC_CONNECTION_PROTOCOL;
```

Parameters

Scan
Determine the characteristics of the available BSSs. See the `Scan()` function description.

Associate
Places an association request with a specific peer MAC entity. See the `Associate()` function description.

Disassociate
Reports a disassociation with a specific peer MAC entity. See the `Disassociate()` function description.

Authenticate
Requests authentication with a specific peer MAC entity. See the `Authenticate()` function description.

Deauthenticate
Invalidates an authentication relationship with a peer MAC entity. See the `Deauthenticate()` function description.

Description
The `EFI_WIRELESS_MAC_CONNECTION_PROTOCOL` is designed to provide management service interfaces for the EFI wireless network stack to establish wireless connection with AP. An EFI Wireless MAC Connection Protocol instance will be installed on each communication device that the EFI wireless network stack runs on.
27.3.2 EFI_WIRELESS_MAC_CONNECTION_PROTOCOL.Scan()

Summary
Request a survey of potential BSSs that administrator can later elect to try to join.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_WIRELESS_MAC_CONNECTION_SCAN)(
    IN EFI_WIRELESS_MAC_CONNECTION_PROTOCOL *This,
    IN EFI_80211_SCAN_DATA_TOKEN *Data
);

Parameters

This
Pointer to the EFI_WIRELESS_MAC_CONNECTION_PROTOCOL

Data
Pointer to the scan token. Type EFI_80211_SCAN_DATA_TOKEN is defined in “Related Definitions” below.

Description
The Scan() function returns the description of the set of BSSs detected by the scan process. Passive scan operation is performed by default.

Related Definitions

typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    EFI_80211_SCAN_DATA *Data;
    EFI_80211_SCAN_RESULT_CODE ResultCode;
    EFI_80211_SCAN_RESULT *Result;
} EFI_80211_SCAN_DATA_TOKEN;

Event
This Event will be signaled after the Status field is updated by the EFI Wireless MAC Connection Protocol driver. The type of Event must be EFI_NOTIFY_SIGNAL.

Status
Will be set to one of the following values:

  EFI_SUCCESS: Scan operation completed successfully.
  EFI_NOT_FOUND: Failed to find available BSS.
  EFI_DEVICE_ERROR: An unexpected network or system error occurred.
  EFI_ACCESS_DENIED: The scan operation is not completed due to some underlying hardware or software state.
  EFI_NOT_READY: The scan operation is started but not yet completed.
Data
Pointer to the scan data. Type `EFI_80211_SCAN_DATA` is defined below.

ResultCode
Indicates the scan state. Type `EFI_80211_SCAN_RESULT_CODE` is defined below.

Result
Indicates the scan result. It is caller’s responsibility to free this buffer. Type `EFI_80211_SCAN_RESULT` is defined below.

The `EFI_80211_SCAN_DATA_TOKEN` structure is defined to support the process of determining the characteristics of the available BSSs. As input, the `Data` field must be filled in by the caller of EFI Wireless MAC Connection Protocol. After the scan operation completes, the EFI Wireless MAC Connection Protocol driver updates the `Status`, `ResultCode` and `Result` field and the `Event` is signaled.

```c
//**********************************************
//  EFI_80211_SCAN_DATA
//**********************************************

typedef struct {
  EFI_80211_BSS_TYPE BSSType;
  EFI_80211_MAC_ADDRESS BSSID;
  UINT8 SSIdLen;
  UINT8 *SSId;
  BOOLEAN PassiveMode;
  UINT32 ProbeDelay;
  UINT32 *ChannelList;
  UINT32 MinChannelTime;
  UINT32 MaxChannelTime;
  EFI_80211_ELEMENT_REQ *RequestInformation;
  EFI_80211_ELEMENT_SSID *SSIDList;
  EFI_80211_ACC_NET_TYPE AccessNetworkType;
  UINT8 *VendorSpecificInfo;
} EFI_80211_SCAN_DATA;
```

BSSType
Determines whether infrastructure BSS, IBSS, MBSS, or all, are included in the scan. Type `EFI_80211_BSS_TYPE` is defined below.

BSSID
Indicates a specific or wildcard BSSID. Use all binary 1s to represent all SSIDs. Type `EFI_80211_MAC_ADDRESS` is defined below.

SSIdLen
Length in bytes of the SSId. If zero, ignore the SSId field.

SSID
Specifies the desired SSID or the wildcard SSID. Use NULL to represent all SSIDs.

PassiveMode
Indicates passive scanning if TRUE.

ProbeDelay
The delay in microseconds to be used prior to transmitting a Probe frame during active scanning. If zero, the value can be overridden by an implementation-dependent default value.

ChannelList
Specifies a list of channels that are examined when scanning for a BSS. If set to NULL, all valid channels will be scanned.
MinChannelTime
Indicates the minimum time in TU to spend on each channel when scanning. If zero, the value can be overridden by an implementation-dependent default value.

MaxChannelTime
Indicates the maximum time in TU to spend on each channel when scanning. If zero, the value can be overridden by an implementation-dependent default value.

RequestInformation
Points to an optionally present element. This is an optional parameter and may be NULL. Type EFI_80211_ELEMENT_REQ is defined below.

SSIDList
Indicates one or more SSID elements that are optionally present. This is an optional parameter and may be NULL. Type EFI_80211_ELEMENT_SSID is defined below.

AccessNetworkType
Specifies a desired specific access network type or the wildcard access network type. Use 15 as wildcard access network type. Type EFI_80211_ACC_NET_TYPE is defined below.

VendorSpecificInfo
Specifies zero or more elements. This is an optional parameter and may be NULL.

//**********************************************
// EFI_80211_BSS_TYPE
//**********************************************
typedef enum {
  IeeeInfrastructureBSS,
  IeeeIndependentBSS,
  IeeeMeshBSS,
  IeeeAnyBss
} EFI_80211_BSS_TYPE;

The EFI_80211_BSS_TYPE is defined to enumerate BSS type.

//**********************************************
// EFI_80211_MAC_ADDRESS
//**********************************************
typedef struct {
  UINT8 Addr[6];
} EFI_80211_MAC_ADDRESS;

The EFI_80211_MAC_ADDRESS is defined to record a 48-bit MAC address.

//**********************************************
// EFI_80211_ELEMENT_REQ
//**********************************************
typedef struct {
  EFI_80211_ELEMENT_HEADER Hdr;
  UINT8 RequestIDs[1];
} EFI_80211_ELEMENT_REQ;

Hdr
Common header of an element. Type EFI_80211_ELEMENT_HEADER is defined below.

RequestIDs
Start of elements that are requested to be included in the Probe Response frame. The elements are listed in order of increasing element ID.
ElementID
A unique element ID defined in IEEE 802.11 specification.

Length
Specifies the number of octets in the element body.

Hdr
Common header of an element.

SSID
Service set identifier. If Hdr.Length is zero, this field is ignored.

 EFI_80211_ELEMENT_HEADER
typedef struct {
    UINT8    ElementID;
    UINT8    Length;
} EFI_80211_ELEMENT_HEADER;

 EFI_80211_ELEMENT_SSID
typedef struct {
    EFI_80211_ELEMENT_HEADER  Hdr;
    UINT8  SSId [32];
} EFI_80211_ELEMENT_SSID;

 EFI_80211_ACC_NET_TYPE
typedef enum {
    IeeePrivate = 0,
    IeeePrivatewithGuest = 1,
    IeeeChargeablePublic = 2,
    IeeeFreePublic = 3,
    IeeePersonal = 4,
    IeeeEmergencyServOnly = 5,
    IeeeTestOrExp = 14,
    IeeeWildcard = 15
} EFI_80211_ACC_NET_TYPE;

 The EFI_80211_ACC_NET_TYPE records access network types defined in IEEE 802.11 specification.

 EFI_80211_SCAN_RESULT_CODE
typedef enum {
    ScanSuccess,
    ScanNotSupported
} EFI_80211_SCAN_RESULT_CODE;

 ScanSuccess
The scan operation finished successfully.
ScanNotSupported

The scan operation is not supported in current implementation.

```c
typedef struct {
    UINTN NumOfBSSDesp;
    EFI_80211_BSS_DESCRIPTION **BSSDespSet;
    UINTN NumOfBSSDespFromPilot;
    EFI_80211_BSS_DESP_PILOT **BSSDespFromPilotSet;
    UINT8 *VendorSpecificInfo;
} EFI_80211_SCAN_RESULT;
```

**NumOfBSSDesp**

The number of EFI_80211_BSS_DESCRIPTION in BSSDespSet. If zero, BSSDespSet should be ignored.

**BSSDespSet**

Points to zero or more instances of EFI_80211_BSS_DESCRIPTION. Type EFI_80211_BSS_DESCRIPTION is defined below.

**NumOfBSSDespFromPilot**

The number of EFI_80211_BSS_DESP_PILOT in BSSDespFromPilotSet. If zero, BSSDespFromPilotSet should be ignored.

**BSSDespFromPilotSet**

Points to zero or more instances of EFI_80211_BSS_DESP_PILOT. Type EFI_80211_BSS_DESP_PILOT is defined below.

**VendorSpecificInfo**

Specifies zero or more elements. This is an optional parameter and may be NULL.

```c
typedef struct {
    EFI_80211_MAC_ADDRESS *BSSID;
    UINT8 *SSID;
    UINT8 SSIDLen;
    EFI_80211_BSS_TYPE BSSType;
    UINT16 BeaconPeriod;
    UINT64 Timestamp;
    UINT16 CapabilityInfo;
    UINT8 *BSSBasicRateSet;
    UINT8 *OperationalRateSet;
    EFI_80211_ELEMENT_COUNTRY *Country;
    EFI_80211_ELEMENT_RSN RSN;
    UINT8 RSSI;
    UINT8 RCPIMeasurement;
    UINT8 RSNIMeasurement;
    UINT8 *RequestedElements;
    UINT8 *BSSMembershipSelectorSet;
    EFI_80211_ELEMENT_EXT_CAP *ExtCapElement;
} EFI_80211_BSS_DESCRIPTION;
```

**BSSID**

27.3. EFI Wireless MAC Connection Protocol
Indicates a specific BSSID of the found BSS.

**SSID**
Specifies the SSID of the found BSS. If NULL, ignore SSIdLen field.

**SSIDLen**
Length in bytes of the SSId. If zero, ignore SSId field.

**BSSType**
Specifies the type of the found BSS.

**BeaconPeriod**
The beacon period in TU of the found BSS.

**Timestamp**
The timestamp of the received frame from the found BSS.

**CapabilityInfo**
The advertised capabilities of the BSS.

**BSSBasicRateSet**
The set of data rates that shall be supported by all STAs that desire to join this BSS.

**OperationalRateSet**
The set of data rates that the peer STA desires to use for communication within the BSS.

**Country**
The information required to identify the regulatory domain in which the peer STA is located. Type EFI_80211_ELEMENT_COUNTRY is defined below.

**RSN**
The cipher suites and AKM suites supported in the BSS. Type EFI_80211_ELEMENT_RSN is defined below.

**RSSI**
Specifies the RSSI of the received frame.

**RCPIMeasurement**
Specifies the RCPI of the received frame.

**RSNI Measurement**
Specifies the RSNI of the received frame.

**RequestedElements**
Specifies the elements requested by the request element of the Probe Request frame. This is an optional parameter and may be NULL.

**BSSMembershipSelectorSet**
Specifies the BSS membership selectors that represent the set of features that shall be supported by all STAs to join this BSS.

**ExtCapElement**
Specifies the parameters within the Extended Capabilities element that are supported by the MAC entity. This is an optional parameter and may be NULL. Type EFI_80211_ELEMENT_EXT_CAP is defined below.

```c
// ************************************************************************
// EFI_80211_ELEMENT_COUNTRY
// ************************************************************************
typedef struct {
    EFI_80211_ELEMENT_HEADER Hdr;
    UINT8 CountryStr [3];
    EFI_80211_COUNTRY_TRIPLET CountryTriplet[1];
} EFI_80211_ELEMENT_COUNTRY;
```

---

**27.3. EFI Wireless MAC Connection Protocol**
Hdr
Common header of an element.

CountryStr
Specifies country strings in 3 octets.

CountryTriplet
Indicates a triplet that repeated in country element. The number of triplets is determined by the Hdr.Length field.

```c
typedef union {
  EFI_80211_COUNTRY_TRIPLET_SUBBAND Subband;
  EFI_80211_COUNTRY_TRIPLET_OPERATE Operating;
} EFI_80211_COUNTRY_TRIPLET;
```

Subband
The subband triplet.

Operating
The operating triplet.

```c
typedef struct {
  UINT8 FirstChannelNum;
  UINT8 NumOfChannels;
  UINT8 MaxTxPowerLevel;
} EFI_80211_COUNTRY_TRIPLET_SUBBAND;
```

FirstChannelNum
Indicates the lowest channel number in the subband. It has a positive integer value less than 201.

NumOfChannels
Indicates the number of channels in the subband.

MaxTxPowerLevel
Indicates the maximum power in dBm allowed to be transmitted.

```c
typedef struct {
  UINT8 OperatingExtId;
  UINT8 OperatingClass;
  UINT8 CoverageClass;
} EFI_80211_COUNTRY_TRIPLET_OPERATE;
```

OperatingExtId
Indicates the operating extension identifier. It has a positive integer value of 201 or greater.

OperatingClass
Index into a set of values for radio equipment set of rules.

CoverageClass
Specifies an AirPropagationTime characteristics used in BSS operation. Refer the definition of an AirPropagationTime in IEEE 802.11 specification.

```c
//******************************************************
// EFI_80211_ELEMENT_RSN
//******************************************************
typedef struct {
    EFI_80211_ELEMENT_HEADER      Hdr;
    EFI_80211_ELEMENT_DATA_RSN   *Data;
} EFI_80211_ELEMENT_RSN;
```

**Hdr**
Common header of an element.

**Data**
Points to RSN element. Type EFI_80211_ELEMENT_DATA_RSN is defined below. The size of a RSN element is limited to 255 octets.

```c
//******************************************************
// EFI_80211_ELEMENT_DATA_RSN
//******************************************************
typedef struct {
    UINT16  Version;
    UINT32  GroupDataCipherSuite;
    //UINT16  PairwiseCipherSuiteCount;
    //UINT32  PairwiseCipherSuiteList [PairwiseCipherSuiteCount];
    //UINT16  AKMSuiteCount;
    //UINT32  AKMSuiteList [AKMSuiteCount];
    //UINT16  RSNCapabilities;
    //UINT16  PMKIDCount;
    //UINT8   PMKIDList [PMKIDCount][16];
    //UINT32  GroupManagementCipherSuite;
} EFI_80211_ELEMENT_DATA_RSN;
```

**Version**
Indicates the version number of the RSNA protocol. Value 1 is defined in current IEEE 802.11 specification.

**GroupDataCipherSuite**
Specifies the cipher suite selector used by the BSS to protect group address frames.

**PairwiseCipherSuiteCount**
Indicates the number of pairwise cipher suite selectors that are contained in PairwiseCipherSuiteList.

**PairwiseCipherSuiteList**
Contains a series of cipher suite selectors that indicate the pairwise cipher suites contained in this element.

**AKMSuiteCount**
Indicates the number of AKM suite selectors that are contained in AKMSuiteList.

**AKMSuiteList**
Contains a series of AKM suite selectors that indicate the AKM suites contained in this element.

**RSNCapabilities**
Indicates requested or advertised capabilities.

**PMKIDCount**
Indicates the number of PKMIDs in the PMKIDList.
PMKIDList
Contains zero or more PMKIDs that the STA believes to be valid for the destination AP.

GroupManagementCipherSuite
Specifies the cipher suite selector used by the BSS to protect group addressed robust management frames.

```c
//**********************************************************
// EFI_80211_ELEMENT_EXT_CAP
//**********************************************************
typedef struct {
    EFI_80211_ELEMENT_HEADER  Hdr;
    UINT8                    Capabilities[1];
} EFI_80211_ELEMENT_EXT_CAP;
```

Hdr
Common header of an element.

Capabilities
Indicates the capabilities being advertised by the STA transmitting the element. This is a bit field with variable length. Refer to IEEE 802.11 specification for bit value.

```c
//**********************************************************
// EFI_80211_BSS_DESP_PILOT
//**********************************************************
typedef struct {
    EFI_80211_MAC_ADDRESS BSSID;
    EFI_80211_BSS_TYPE   BSSType;
    UINT8                 ConCapInfo;
    UINT8                 ConCountryStr[2];
    UINT8                 OperatingClass;
    UINT8                 Channel;
    UINT8                 Interval;
    EFI_80211_MULTIPLE_BSSID *MultipleBSSID;
    UINT8                 RCPIMeasurement;
    UINT8                 RSNIMeasurement;
} EFI_80211_BSS_DESP_PILOT;
```

BSSID
Indicates a specific BSSID of the found BSS.

BSSType
Specifies the type of the found BSS.

ConCapInfo
One octet field to report condensed capability information.

ConCountryStr
Two octet’s field to report condensed country string.

OperatingClass
Indicates the operating class value for the operating channel.

Channel
Indicates the operating channel.

Interval
Indicates the measurement pilot interval in TU.

27.3. EFI Wireless MAC Connection Protocol 1131
MultipleBSSID
Indicates that the BSS is within a multiple BSSID set.

RCPI Measurement
Specifies the RCPI of the received frame.

RSNIMeasurement
Specifies the RSNI of the received frame.

```
//**********************************************
// EFI_80211_MULTIPLE_BSSID
//**********************************************
typedef struct {
    EFI_80211_ELEMENT_HEADER Hdr;
    UINT8 Indicator;
    EFI_80211_SUBELEMENT_INFO SubElement[1];
} EFI_80211_MULTIPLE_BSSID;
```

Hdr
Common header of an element.

Indicator
Indicates the maximum number of BSSIDs in the multiple BSSID set. When Indicator is set to n, 2n is the maximum number.

SubElement
Contains zero or more sub-elements. Type EFI_80211_SUBELEMENT_INFO is defined below.

```
//**********************************************
// EFI_80211_SUBELEMENT_INFO
//**********************************************
typedef struct {
    UINT8 SubElementID;
    UINT8 Length;
    UINT8 Data[1];
} EFI_80211_SUBELEMENT_INFO;
```

SubElementID
Indicates the unique identifier within the containing element or sub-element.

Length
Specifies the number of octets in the Data field.

Data
A variable length data buffer.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Data -&gt; Data is NULL.</td>
</tr>
</tbody>
</table>

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27.3.3 EFI_WIRELESS_MAC_CONNECTION_PROTOCOL.Associate()

Summary
Request an association with a specified peer MAC entity that is within an AP.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_WIRELESS_MAC_CONNECTION_ASSOCIATE)(
    IN EFI_WIRELESS_MAC_CONNECTION_PROTOCOL *This,
    IN EFI_80211_ASSOCIATE_DATA_TOKEN *Data
);
```

Parameters

This
Pointer to the EFI_WIRELESS_MAC_CONNECTION_PROTOCOL instance.

Data
Pointer to the association token. Type EFI_80211_ASSOCIATE_DATA_TOKEN is defined in Related Definitions below.

Description
The Associate() function provides the capability for MAC layer to become associated with an AP.

Related Definitions

```c
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    EFI_80211_ASSOCIATE_DATA Data;
    EFI_80211_ASSOCIATE_RESULT_CODE ResultCode;
    EFI_80211_ASSOCIATE_RESULT Result;
} EFI_80211_ASSOCIATE_DATA_TOKEN;
```

Event
This Event will be signaled after the Status field is updated by the EFI Wireless MAC Connection Protocol driver. The type of Event must be EFI_NOTIFY_SIGNAL.

Status
Will be set to one of the following values: EFI_SUCCESS: Association operation completed successfully. EFI_DEVICE_ERROR: An unexpected network or system error occurred.

Data
Pointer to the association data. Type EFI_80211_ASSOCIATE_DATA is defined below.
**ResultCode**
Indicates the association state. Type `EFI_80211_ASSOCIATE_RESULT_CODE` is defined below.

**Result**
Indicates the association result. It is caller’s responsibility to free this buffer. Type `EFI_80211_ASSOCIATE_RESULT` is defined below.

The `EFI_80211_ASSOCIATE_DATA_TOKEN` structure is defined to support the process of association with a specified AP. As input, the `Data` field must be filled in by the caller of EFI Wireless MAC Connection Protocol. After the association operation completes, the EFI Wireless MAC Connection Protocol driver updates the `Status`, `ResultCode` and `Result` field and the `Event` is signaled.

```c
//**********************************************
// EFI_80211_ASSOCIATE_DATA
//**********************************************
typedef struct {
    EFI_80211_MAC_ADDRESS BSSID;
    UINT16                CapabilityInfo;
    UINT32                FailureTimeout;
    UINT32                ListenInterval;
    EFI_80211_ELEMENT_SUPP_CHANNEL *Channels;
    EFI_80211_ELEMENT_RSN    RSN;
    EFI_80211_ELEMENT_EXT_CAP ExtCapElement;
    UINT8                 *VendorSpecificInfo;
} EFI_80211_ASSOCIATE_DATA;
```

**BSSID**
Specifies the address of the peer MAC entity to associate with.

**CapabilityInfo**
Specifies the requested operational capabilities to the AP in 2 octets.

**FailureTimeout**
Specifies a time limit in TU, after which the associate procedure is terminated.

**ListenInterval**
Specifies if in power save mode, how often the STA awakes and listens for the next beacon frame in TU.

**Channels**
Indicates a list of channels in which the STA is capable of operating. Type `EFI_80211_ELEMENT_SUPP_CHANNEL` is defined below.

**RSN**
The cipher suites and AKM suites selected by the STA.

**ExtCapElement**
Specifies the parameters within the Extended Capabilities element that are supported by the MAC entity. This is an optional parameter and may be NULL.

**VendorSpecificInfo**
Specifies zero or more elements. This is an optional parameter and may be NULL.
EFI_80211_ELEMENT_SUPP_CHANNEL_TUPLE Subband[1];
} EFI_80211_ELEMENT_SUPP_CHANNEL;

Hdr
Common header of an element.

Subband
Indicates one or more tuples of (first channel, number of channels). Type
EFI_80211_ELEMENT_SUPP_CHANNEL_TUPLE is defined below.

//**********************************************
// EFI_80211_ELEMENT_SUPP_CHANNEL_TUPLE
//**********************************************
typedef struct {
    UINT8 FirstChannelNumber;
    UINT8 NumberOfChannels;
} EFI_80211_ELEMENT_SUPP_CHANNEL_TUPLE;

FirstChannelNumber
The first channel number in a subband of supported channels.

NumberOfChannels
The number of channels in a subband of supported channels.

//**********************************************
// EFI_80211_ASSOCIATE_RESULT_CODE
//**********************************************
typedef enum {
    AssociateSuccess,
    AssociateRefusedReasonUnspecified,
    AssociateRefusedCapsMismatch,
    AssociateRefusedExtReason,
    AssociateRefusedAPOutOfMemory,
    AssociateRefusedBasicRatesMismatch,
    AssociateRejectedEmergencyServicesNotSupported,
    AssociateRefusedTemporarily
} EFI_80211_ASSOCIATE_RESULT_CODE;

The EFI_80211_ASSOCIATE_RESULT_CODE records the result responses to the association request, which are de-
defined in IEEE 802.11 specification.

//**********************************************
// EFI_80211_ASSOCIATE_RESULT
//**********************************************
typedef struct {
    EFI_80211_MAC_ADDRESS BSSID;
    UINT16 CapabilityInfo;
    UINT16 AssociationID;
    UINT8 RCPIValue;
   UINT8 RSNIValue;
    EFI_80211_ELEMENT_EXT_CAP *ExtCapElement;
    EFI_80211_ELEMENT_TIMEOUT_VAL TimeoutInterval;
    UINT8 *VendorSpecificInfo;
} EFI_80211_ASSOCIATE_RESULT;
BSSID
Specifies the address of the peer MAC entity from which the association request was received.

CapabilityInfo
Specifies the operational capabilities advertised by the AP.

AssociationID
Specifies the association ID value assigned by the AP.

RCPIValue
Indicates the measured RCPI of the corresponding association request frame. It is an optional parameter and is set to zero if unavailable.

RSNIValue
Indicates the measured RSNI at the time the corresponding association request frame was received. It is an optional parameter and is set to zero if unavailable.

ExtCapElement
Specifies the parameters within the Extended Capabilities element that are supported by the MAC entity. This is an optional parameter and may be NULL.

TimeoutInterval
Specifies the timeout interval when the result code is AssociateRefusedTemporarily.

VendorSpecificInfo
Specifies zero or more elements. This is an optional parameter and may be NULL.

```c
typedef struct {
    EFI_80211_ELEMENT_HEADER     Hdr;
    UINT8 Type;
    UINT32 Value;
} EFI_80211_ELEMENT_TIMEOUT_VAL;
```

Hdr
Common header of an element.

Type
Specifies the timeout interval type.

Value
Specifies the timeout interval value.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Data -&gt; Data is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>One or more of the input parameters are not supported by this implementation.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The association process is already started.</td>
</tr>
</tbody>
</table>

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Table 27.14 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_NOT_READY</td>
<td>Authentication is not performed before this association process.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified peer MAC entity is not found.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
</tbody>
</table>

27.3.4 EFI_WIRELESS_MAC_CONNECTION_PROTOCOL.Disassociate()

Summary
Request a disassociation with a specified peer MAC entity.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_WIRELESS_MAC_CONNECTION_DISASSOCIATE)(
    IN EFI_WIRELESS_MAC_CONNECTION_PROTOCOL *This,
    IN EFI_80211_DISASSOCIATE_DATA_TOKEN *Data
);
```

Parameters

This 
Pointer to the EFI_WIRELESS_MAC_CONNECTION_PROTOCOL instance.

Data 
Pointer to the disassociation token. Type EFI_80211_DISASSOCIATE_DATA_TOKEN is defined in Related Definitions below.

Description

The Disassociate() function is invoked to terminate an existing association. Disassociation is a notification and cannot be refused by the receiving peer except when management frame protection is negotiated and the message integrity check fails.

Related Definitions

```c
//******************************************************
// EFI_80211_DISASSOCIATE_DATA_TOKEN
//******************************************************
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    EFI_80211_DISASSOCIATE_DATA *Data;
    EFI_80211_DISASSOCIATE_RESULT_CODE ResultCode;
} EFI_80211_DISASSOCIATE_DATA_TOKEN;
```

Event

This Event will be signaled after the Status field is updated by the EFI Wireless MAC Connection Protocol driver. The type of Event must be EFI_NOTIFY_SIGNAL.

Status

Will be set to one of the following values:

- EFI_SUCCESS: Disassociation operation completed successfully.
- EFI_DEVICE_ERROR: An unexpected network or system error occurred.
 EFI_ACCESS_DENIED: The disassociation operation is not completed due to some underlying hardware or software state.
 EFI_NOT_READY: The disassociation operation is started but not yet completed.

**Data**
Pointer to the disassociation data. Type EFI_80211_DISASSOCIATE_DATA is defined below.

**ResultCode**
Indicates the disassociation state. Type EFI_80211_DISASSOCIATE_RESULT_CODE is defined below.

```c
typedef struct {
    EFI_80211_MAC_ADDRESS BSSId;
    EFI_80211_REASON_CODE ReasonCode;
    UINT8 *VendorSpecificInfo;
} EFI_80211_DISASSOCIATE_DATA;
```

**BSSId**
Specifies the address of the peer MAC entity with which to perform the disassociation process.

**ReasonCode**
Specifies the reason for initiating the disassociation process.

**VendorSpecificInfo**
Zero or more elements, may be NULL.

```c
typedef enum {
    Ieee80211UnspecifiedReason = 1,
    Ieee80211PreviousAuthenticateInvalid = 2,
    Ieee80211DeauthenticatedSinceLeaving = 3,
    Ieee80211DisassociatedDueToInactive = 4,
    Ieee80211DisassociatedSinceApUnable = 5,
    Ieee80211Class2FrameNonauthenticated = 6,
    Ieee80211Class3FrameNonassociated = 7,
    Ieee80211DisassociatedSinceLeaving = 8,
    // ...
} EFI_80211_REASON_CODE;
```

**Note:** The reason codes are defined in chapter 8.4.1.7 Reason Code field, IEEE 802.11-2012.

```c
typedef enum {
    DisassociateSuccess,
    DisassociateInvalidParameters
} EFI_80211_DISASSOCIATE_RESULT_CODE;
```

**DisassociateSuccess**
Disassociation process completed successfully.
DisassociateInvalidParameters
Disassociation failed due to any input parameter is invalid.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The disassociation process is already started.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The disassociation service is invoked to a nonexistent association relation-</td>
</tr>
<tr>
<td></td>
<td>ship.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified peer MAC entity is not found.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
</tbody>
</table>

27.3.5 EFI_WIRELESS_MAC_CONNECTION_PROTOCOL.Authenticate()

Summary
Request the process of establishing an authentication relationship with a peer MAC entity.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_WIRELESS_MAC_CONNECTION_AUTHENTICATE)(
    IN EFI_WIRELESS_MAC_CONNECTION_PROTOCOL *This,
    IN EFI_80211_AUTHENTICATE_DATA_TOKEN *Data
);

Parameters

This
Pointer to the EFI_WIRELESS_MAC_CONNECTION_PROTOCOL instance.

Data
Pointer to the authentication token. Type EFI_80211_AUTHENTICATE_DATA_TOKEN is defined in Related Definitions below.

Description
The Authenticate() function requests authentication with a specified peer MAC entity. This service might be time-consuming thus is designed to be invoked independently of the association service.

Related Definitions

```c
//****************************************************************************
// EFI_80211_AUTHENTICATE_DATA_TOKEN
//****************************************************************************
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    EFI_80211_AUTHENTICATE_DATA *Data;
    EFI_80211_AUTHENTICATE_RESULT_CODE ResultCode;
} EFI_80211_AUTHENTICATE_DATA_TOKEN;
```
Event
This Event will be signaled after the Status field is updated by the EFI Wireless MAC Connection Protocol driver. The type of Event must be EFI_NOTIFY_SIGNAL.

Status
Will be set to one of the following values:

- EFI_PROTOCOL_ERROR: Peer MAC entity rejects the authentication.
- EFI_NO_RESPONSE: Peer MAC entity does not response the authentication request.
- EFI_DEVICE_ERROR: An unexpected network or system error occurred.
- EFI_ACCESS_DENIED: The authentication operation is not completed due to some underlying hardware or software state.
- EFI_NOT_READY: The authentication operation is started but not yet completed.

Data
Pointer to the authentication data. Type EFI_80211_AUTHENTICATE_DATA is defined below.

ResultCode
Indicates the association state. Type EFI_80211_AUTHENTICATE_RESULT_CODE is defined below.

Result
Indicates the association result. It is caller’s responsibility to free this buffer. Type EFI_80211_AUTHENTICATE_RESULT is defined below.

```c
typedef struct {
    EFI_80211_MAC_ADDRESS     BSSID;
    EFI_80211_AUTHENTICATION_TYPE AuthType;
    UINT32                    FailureTimeout;
    UINT8 *                   FTContent;
    UINT8 *                   SAEContent;
    UINT8 *                   VendorSpecificInfo;
} EFI_80211_AUTHENTICATE_DATA;
```

BSSID
Specifies the address of the peer MAC entity with which to perform the authentication process.

AuthType
Specifies the type of authentication algorithm to use during the authentication process.

FailureTimeout
Specifies a time limit in TU after which the authentication procedure is terminated.

FTContent
Specifies the set of elements to be included in the first message of the FT authentication sequence, may be NULL.

SAEContent
Specifies the set of elements to be included in the SAE Commit Message or SAE Confirm Message, may be NULL.
VendorSpecificInfo
Zero or more elements, may be NULL.

---

 EFI_80211_MAC_ADDRESS BSSID;
 UINT8 *FTContent;
 UINT8 *SAEContent;
 UINT8 *VendorSpecificInfo;
} EFI_80211_AUTHENTICATE_RESULT;

---

The result code indicates the result response to the authentication request from the peer MAC entity.

---

 EFI_80211_MAC_ADDRESS BSSID;
 UINT8 *FTContent;
 UINT8 *SAEContent;
 UINT8 *VendorSpecificInfo;
} EFI_80211_AUTHENTICATE_RESULT;

---

//**********************************************
// EFI_80211_AUTHENTICATION_TYPE
//**********************************************
typedef enum {
    OpenSystem,
    SharedKey,
    FastBSSTransition,
    SAE
} EFI_80211_AUTHENTICATION_TYPE;

---

 OpenSystem
Open system authentication, admits any STA to the DS.

---

 SharedKey
Shared Key authentication relies on WEP to demonstrate knowledge of a WEP encryption key.

---

 FastBSSTransition
FT authentication relies on keys derived during the initial mobility domain association to authenticate the stations.

---

 SAE
SAE authentication uses finite field cryptography to prove knowledge of a shared password.

---

 EFI_80211_AUTHENTICATE_RESULT_CODE
**********************************************
typedef enum {
    AuthenticateSuccess,
    AuthenticateRefused,
    AuthenticateAnticLoggingTokenRequired,
    AuthenticateFiniteCyclicGroupNotSupported,
    AuthenticationRejected,
    AuthenticateInvalidParameter
} EFI_80211_AUTHENTICATE_RESULT_CODE;

---

 The result code indicates the result response to the authentication request from the peer MAC entity.
Specifies the set of elements to be included in the SAE Commit Message or SAE Confirm Message, may be NULL.

**VendorSpecificInfo**
Zero or more elements, may be NULL.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Data Data is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>One or more of the input parameters are not supported by this implementation.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The authentication process is already started.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified peer MAC entity is not found.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
</tbody>
</table>

### 27.3.6 EFI_WIRELESS_MAC_CONNECTION_PROTOCOL.Deauthenticate()  

#### Summary

Invalidate the authentication relationship with a peer MAC entity.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_WIRELESS_MAC_CONNECTION_DEAUTHENTICATE)(
    IN EFI_WIRELESS_MAC_CONNECTION_PROTOCOL *This,
    IN EFI_80211_DEAUTHENTICATE_DATA_TOKEN *Data
);
```

#### Parameters

**This**
Pointer to the `EFI_WIRELESS_MAC_CONNECTION_PROTOCOL` instance.

**Data**
Pointer to the deauthentication token. Type `EFI_80211_DEAUTHENTICATE_DATA_TOKEN` is defined in Related Definitions below.

#### Description

The `Deauthenticate()` function requests that the authentication relationship with a specified peer MAC entity be invalidated. Deauthentication is a notification and when it is sent out the association at the transmitting station is terminated.

#### Related Definitions

```c

(continues on next page)```
Event
This Event will be signaled after the Status field is updated by the EFI Wireless MAC Connection Protocol driver. The type of Event must be EFI_NOTIFY_SIGNAL.

Status
Will be set to one of the following values:

- EFI_SUCCESS: Deauthentication operation completed successfully.
- EFI_DEVICE_ERROR: An unexpected network or system error occurred.
- EFI_ACCESS_DENIED: The deauthentication operation is not completed due to some underlying hardware or software state.
- EFI_NOT_READY: The deauthentication operation is started but not yet completed.

Data
Pointer to the deauthentication data. Type EFI_80211_DEAUTHENTICATE_DATA is defined below.

```c
typedef struct {
    EFI_80211_MAC_ADDRESS BSSID;
    EFI_80211_REASON_CODE ReasonCode;
    UINT8 *VendorSpecificInfo;
} EFI_80211_DEAUTHENTICATE_DATA;
```

BSSID
Specifies the address of the peer MAC entity with which to perform the deauthentication process.

ReasonCode
Specifies the reason for initiating the deauthentication process.

VendorSpecificInfo
Zero or more elements, may be NULL.

Status CodesReturned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Data Data is NULL.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The deauthentication process is already started.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The deauthentication service is invoked to a nonexistent association or authentification relationship.</td>
</tr>
</tbody>
</table>
27.4 EFI Wireless MAC Connection II Protocol

This section provides a detailed description of EFI Wireless MAC Connection II Protocol.

27.4.1 EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL

Summary

The EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL provides network management service interfaces for 802.11 network stack. It is used by network applications (and drivers) to establish wireless connection with a wireless network.

GUID

```
#define EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL_GUID
{ 0x1b0fb9bf, 0x699d, 0x4fdd, 
{ 0xa7, 0xc3, 0x25, 0x46, 0x68, 0x1b, 0xf6, 0x3b }}
```

Protocol Interface Structure

```
typedef _EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL {
    EFI_WIRELESS_MAC_CONNECTION_II_GET_NETWORKS GetNetworks;
    EFI_WIRELESS_MAC_CONNECTION_II_CONNECT_NETWORK ConnectNetwork;
    EFI_WIRELESS_MAC_CONNECTION_II_DISCONNECT_NETWORK DisconnectNetwork;
} EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL;
```

Parameters

GetNetworks

Get a list of nearby detectable wireless network. See the GetNetworks() function description.

ConnectNetwork

Places a connection request with a specific wireless network. See the ConnectNetwork() function description.

DisconnectNetwork

Places a disconnection request with a specific wireless network. See the DisconnectNetwork() function description.

Description

The EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL is designed to provide management service interfaces for the EFI wireless network stack to establish relationship with a wireless network (identified by EFI_80211_NETWORK defined below). An EFI Wireless MAC Connection II Protocol instance will be installed on each communication device that the EFI wireless network stack runs on.
27.4.2 EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL.GetNetworks()

Summary
Request a survey of potential wireless networks that administrator can later elect to try to join.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_WIRELESS_MAC_CONNECTION_II_GET_NETWORKS)(
    IN EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL *This,
    IN EFI_80211_GET_NETWORKS_TOKEN *Token
);
```

Parameters

**This**
- Pointer to the `EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL` instance.

**Token**
- Pointer to the token for getting wireless network. Type `EFI_80211_GET_NETWORKS_TOKEN` is defined in Related Definitions below.

Description

The `GetNetworks()` function returns the description of a list of wireless networks detected by wireless UNDI driver. This function is always non-blocking. If the operation succeeds or fails due to any error, the `Token->Event` will be signaled and `Token->Status` will be updated accordingly. The caller of this function is responsible for inputting SSIDs in case of searching hidden networks.

Related Definitions

```
// ******************************************************
// EFI_80211_GET_NETWORKS_TOKEN
// ******************************************************
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    EFI_80211_GET_NETWORKS_DATA *Data;
    EFI_80211_GET_NETWORKS_RESULT *Result;
} EFI_80211_GET_NETWORKS_TOKEN;
```

**Event**
- If the status code returned by `GetNetworks()` is `EFI_SUCCESS`, then this Event will be signaled after the Status field is updated by the EFI Wireless MAC Connection Protocol II driver. The type of Event must be `EFI_NOTIFY_SIGNAL`.

**Status**
- Will be set to one of the following values:

  - `EFI_SUCCESS`: The operation completed successfully.
  - `EFI_NOT_FOUND`: Failed to find available wireless networks.
  - `EFI_DEVICE_ERROR`: An unexpected network or system error occurred.
  - `EFI_ACCESS_DENIED`: The operation is not completed due to some underlying hardware or software state.
  - `EFI_NOT_READY`: The operation is started but not yet completed.
Data
Pointer to the input data for getting networks. Type EFI_80211_GET_NETWORKS_DATA is defined below.

Result
Indicates the scan result. It is caller’s responsibility to free this buffer. Type EFI_80211_GET_NETWORKS_RESULT is defined below.

```
//**********************************************
// EFI_80211_GET_NETWORKS_DATA
//**********************************************
typedef struct {
    UINT32 NumOfSSID;
    EFI_80211_SSID SSIDList[1];
} EFI_80211_GET_NETWORKS_DATA;
```

NumOfSSID
The number of EFI_80211_SSID in SSIDList. If zero, SSIDList should be ignored.

SSIDList
The SSIDList is a pointer to an array of EFI_80211_SSID instances. The number of entries is specified by NumOfSSID. The array should only include SSIDs of hidden networks. It is suggested that the caller inputs less than 10 elements in the SSIDList. It is the caller’s responsibility to free this buffer. Type EFI_80211_SSID is defined below.

```
#define EFI_MAX_SSID_LEN 32
//**********************************************
// EFI_80211_SSID
//**********************************************
typedef struct {
    UINT8 SSIdLen;
    UINT8 SSId[EFI_MAX_SSID_LEN];
} EFI_80211_SSID;
```

SSIdLen
Length in bytes of the SSId. If zero, ignore SSId field.

SSID
Specifies the service set identifier.

```
//**********************************************
// EFI_80211_GET_NETWORKS_RESULT
//**********************************************
typedef struct {
    UINT8 NumOfNetworkDesc;
    EFI_80211_NETWORK_DESCRIPTION NetworkDesc[1];
} EFI_80211_GET_NETWORKS_RESULT;
```

NumOfNetworkDesc
The number of elements in NetworkDesc. If zero, NetworkDesc should be ignored.

NetworkDesc
The NetworkDesc is a variable-length array of elements of type EFI_80211_NETWORK_DESCRIPTION. Type EFI_80211_NETWORK_DESCRIPTION is defined below.
typedef struct {
    EFI_80211_NETWORK Network;
    UINT8 NetworkQuality;
} EFI_80211_NETWORK_DESCRIPTION;

Network
Specifies the found wireless network. Type EFI_80211_NETWORK is defined below.

NetworkQuality
Indicates the network quality as a value between 0 to 100, where 100 indicates the highest network quality.

typedef struct {
    EFI_80211_BSS_TYPE BSSType;
    EFI_80211_SSID SSId;
    EFI_80211_AKM_SUITE_SELECTOR *AKMSuite;
    EFI_80211_CIPHER_SUITE_SELECTOR *CipherSuite;
} EFI_80211_NETWORK;

BSSType
Specifies the type of the BSS. Type EFI_80211_BSS_TYPE is defined below.

SSId
Specifies the SSID of the BSS. Type EFI_80211_SSID is defined above.

AKMSuite
Pointer to the AKM suites supported in the wireless network. Type EFI_80211_AKM_SUITE_SELECTOR is defined below.

CipherSuite
Pointer to the cipher suites supported in the wireless network. Type EFI_80211_CIPHER_SUITE_SELECTOR is defined below.

typedef enum {
    IeeeInfrastructureBSS,
    IeeeIndependentBSS,
    IeeeMeshBSS,
    IeeeAnyBss
} EFI_80211_BSS_TYPE;

The EFI_80211_BSS_TYPE is defined to enumerate BSS type.
UINT8     SuiteType;
} EFi_80211_SUITE_SELECTOR;

Oui
Organization Unique Identifier, as defined in IEEE 802.11 standard, usually set to 00-0F-AC.

SuiteType
Suites types, as defined in IEEE 802.11 standard.

typedef struct {
    UINT16 AKMSuiteCount;
    EFI_80211_SUITE_SELECTOR AKMSuiteList[1];
} EFI_80211_AKM_SUITE_SELECTOR;

AKMSuiteCount
Indicates the number of AKM suite selectors that are contained in AKMSuiteList. If zero, the AKMSuiteList is ignored.

AKMSuiteList
A variable-length array of AKM suites, as defined in IEEE 802.11 standard, Table 8-101. The number of entries is specified by AKMSuiteCount.

typedef struct {
    UINT16 CipherSuiteCount;
    EFI_80211_SUITE_SELECTOR CipherSuiteList[1];
} EFI_80211_CIPHER_SUITE_SELECTOR;

CipherSuiteCount
Indicates the number of cipher suites that are contained in CipherSuiteList. If zero, the CipherSuiteList is ignored.

CipherSuiteList
A variable-length array of cipher suites, as defined in IEEE 802.11 standard, Table 8-99. The number of entries is specified by CipherSuiteCount.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation started, and an event will eventually be raised for the caller.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more of the following conditions is TRUE:  
This is NULL.  
Token is NULL. |
| EFI_UNSUPPORTED | One or more of the input parameters is not supported by this implementation. |
| EFI_ALREADY_STARTED | The operation of getting wireless network is already started. |
| EFI_OUT_OF_RESOURCES | Required system resources could not be allocated. |
27.4.3 EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL.ConnectNetwork()

**Summary**
Connect a wireless network specified by a particular SSID, BSS type and Security type.

**Prototype**

```c
typedef EFI_STATUS
(EIFIAPI *EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOLinis)
(IN EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL *This,
IN EFI_80211_CONNECT_NETWORK_TOKEN *Token);
```

**Parameters**

- **This**: Pointer to the `EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL` instance.

- **Token**: Pointer to the token for connecting wireless network. Type `EFI_80211_CONNECT_NETWORK_TOKEN` is defined in Related Definitions below.

**Description**

The `ConnectNetwork()` function places a request to wireless UNDI driver to connect a wireless network specified by a particular SSID, BSS type, Authentication method and cipher. This function will trigger wireless UNDI driver to perform authentication and association process to establish connection with a particular Access Point for the specified network. This function is always non-blocking. If the connection succeeds or fails due to any error, the `Token->Event` will be signaled and `Token->Status` will be updated accordingly.

After having signaled a successful connection completion, the UNDI driver will update the network connection state using the network media state information type in the `EFI_ADAPTER_INFORMATION_PROTOCOL`. If needed, the caller should use `EFI_ADAPTER_INFORMATION_PROTOCOL` to regularly get the network media state to find if the UNDI driver is still connected to the wireless network (`EFI_SUCCESS`) or not (`EFI_NO_MEDIA`).

Generally a driver or application in WiFi stack would provide user interface to end user to manage profiles for selecting which wireless network to join and other state management. This module should prompt the user to select a network and input WiFi security data such as certificate, private key file, password, etc. Then the module should deploy WiFi security data through EFI Supplicant Protocol and/or EFI EAP Configuration Protocol before calling `ConnectNetwork()` function.

**Related Definitions**

```c
//**********************************************
// EFI_80211_CONNECT_NETWORK_TOKEN
//**********************************************
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    EFI_80211_CONNECT_NETWORK_DATA *Data;
    EFI_80211_CONNECT_NETWORK_RESULT_CODE ResultCode;
} EFI_80211_CONNECT_NETWORK_TOKEN;
```
Event

If the status code returned by ConnectNetwork() is EFI_SUCCESS, then this Event will be signaled after the Status field is updated by the EFI Wireless MAC Connection Protocol II driver. The type of Event must be EFI_NOTIFY_SIGNAL.

Status

Will be set to one of the following values:

- EFI_SUCCESS: The operation completed successfully.
- EFI_DEVICE_ERROR: An unexpected network or system error occurred.
- EFI_ACCESS_DENIED: The operation is not completed due to some underlying hardware or software state.
- EFI_NOT_READY: The operation is started but not yet completed.

Data

Pointer to the connection data. Type EFI_80211_CONNECT_NETWORK_DATA is defined below.

ResultCode

Indicates the connection state. Type EFI_80211_CONNECT_NETWORK_RESULT_CODE is defined below.

The EFI_80211_CONNECT_NETWORK_TOKEN structure is defined to support the process of determining the characteristics of the available networks. As input, the Data field must be filled in by the caller of EFI Wireless MAC Connection II Protocol. After the operation completes, the EFI Wireless MAC Connection II Protocol driver updates the Status and ResultCode field and the Event is signaled.

```
//****************************************************************************
// EFI_80211_CONNECT_NETWORK_TOKEN
//****************************************************************************
typedef struct {
    EFI_80211_NETWORK     *Network;
    UINT32                 FailureTimeout;
} EFI_80211_CONNECT_NETWORK_TOKEN;
```

Network

Specifies the wireless network to connect to. Type EFI_80211_NETWORK is defined above.

FailureTimeout

Specifies a time limit in seconds that is optionally present, after which the connection establishment procedure is terminated by the UNDI driver. This is an optional parameter and may be 0. Values of 5 seconds or higher are recommended.

```
//****************************************************************************
// EFI_80211_CONNECT_NETWORK_RESULT_CODE
//****************************************************************************
typedef enum {
    ConnectSuccess,
    ConnectRefused,
    ConnectFailed,
    ConnectFailureTimeout,
    ConnectFailedReasonUnspecified
} EFI_80211_CONNECT_NETWORK_RESULT_CODE;
```

ConnectSuccess

The connection establishment operation finished successfully.
ConnectRefused
   The connection was refused by the Network.

ConnectFailed
   The connection establishment operation failed (i.e, Network is not detected).

ConnectFailureTimeout
   The connection establishment operation was terminated on timeout.

ConnectFailedReasonUnspecified
   The connection establishment operation failed on other reason.

Status Codes Returned

<table>
<thead>
<tr>
<th>StatusCode</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation started successfully. Results will be notified eventually.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>Token is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>One or more of the input parameters are not supported by this implementa-</td>
</tr>
<tr>
<td></td>
<td>tion.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The connection process is already started.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified wireless network is not found.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
</tbody>
</table>

27.4.4 EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL.DisconnectNetwork()

Summary

Request a disconnection with current connected wireless network.

Prototype
typedef
EFI_STATUS
(EIFIAPI *EFI_WIRELESS_MAC_CONNECTION_II_DISCONNECT_NETWORK)(
   IN EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL  *This,
   IN EFI_80211_DISCONNECT_NETWORK_TOKEN    *Token
);

Parameters

This
   Pointer to the EFI_WIRELESS_MAC_CONNECTION_II_PROTOCOL instance.

Token
   Pointer to the token for disconnecting wireless network. Type EFI_80211_DISCONNECT_NETWORK_TOKEN is defined in Related Definitions below.

Description

The DisconnectNetwork() function places a request to wireless UNDI driver to disconnect from the wireless network it is connected to. This function will trigger the wireless UNDI driver to perform disassociation and deauthentication process to terminate an existing connection. This function is always non-blocking. After wireless UNDI driver received acknowledgment frame from AP and freed up corresponding resources, the Token->Event will be signaled and Token->Status will be updated accordingly.
Related Definitions

typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
} EFI_80211_DISCONNECT_NETWORK_TOKEN;

Event
If the status code returned by DisconnectNetwork() is EFI_SUCCESS, then this Event will be signaled after the Status field is updated by the EFI Wireless MAC Connection Protocol II driver. The type of Event must be EFI_NOTIFY_SIGNAL.

Status
Will be set to one of the following values:

- EFI_SUCCESS: The operation completed successfully
- EFI_DEVICE_ERROR: An unexpected network or system error occurred.
- EFI_ACCESS_DENIED: The operation is not completed due to some underlying hardware or software state.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation started successfully. Results will be notified eventually.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>Token is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>One or more of the input parameters are not supported by this implementation.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Not connected to a wireless network.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
</tbody>
</table>

27.5 EFI Supplicant Protocol

This section defines the EFI Supplicant Protocol.

27.5.1 Supplicant Service Binding Protocol

27.5.2 EFI_SUPPLICANT_SERVICE_BINDING_PROTOCOL

Summary
The EFI Supplicant Service Binding Protocol is used to locate EFI Supplicant Protocol drivers to create and destroy child of the driver to communicate with other host using Supplicant protocol.

GUID
A module that requires supplicant services can call one of the protocol handler services, such as `BS-LocateHandleBuffer()`, to search devices that publish an EFI Supplicant Service Binding Protocol GUID. Such device supports the EFI Supplicant Protocol and may be available for use. After a successful call to the `EFI.Suppllicant_Service_BINDING_PROTOCOL.CreateChild()` function, the newly created child EFI Supplicant Protocol driver is in an un-configured state; it is not ready to do any operation until configured via SetData(). Every successful call to the `EFI.Suppllicant_Service_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI.Suppllicant_Service_BINDING_PROTOCOL.DestroyChild()` function to release the protocol driver.

### 27.5.3 Supplicant Protocol

### 27.5.4 EFI.Suppllicant_PROTOCOL

#### Summary

This protocol provides services to process authentication and data encryption/decryption for security management.

#### GUID

```
#define EFI.Suppllicant_PROTOCOL_GUID
{ 0x54fcc43e, 0xaa89, 0x4333, \
    0x9a, 0x85, 0xdc, 0xea, 0x24, 0x5, 0xe, 0x9e }
```

#### Protocol Interface Structure

```
typedef struct _EFI.Suppllicant_PROTOCOL {
    EFI.Suppllicant_BUILD_RESPONSE_PACKET BuildResponsePacket;
    EFI.Suppllicant_PROCESS_PACKET ProcessPacket;
    EFI.Suppllicant_SET_DATA SetData;
    EFI.Suppllicant_GET_DATA GetData;
} EFI.Suppllicant_PROTOCOL;
```

#### Parameters

**BuildResponsePacket**

This API processes security data for handling key management. See the `BuildResponsePacket()` function description.

**ProcessPacket**

This API processes frame for encryption or decryption. See the `ProcessPacket()` function description.

**SetData**

This API sets the information needed during key generated in handshake. See the `SetData()` function description.

**GetData**

This API gets the information generated in handshake. See the `GetData()` function description.

#### Description

The `EFI.Suppllicant_PROTOCOL` is designed to provide unified place for WIFI and EAP security management. Both PSK authentication and 802.1X EAP authentication can be managed via this protocol and driver or application.
as a consumer can only focus on about packet transmitting or receiving. For 802.1X EAP authentication, an instance of *EFI_EAP_CONFIGURATION_PROTOCOL* must be installed to the same handle as the EFI Supplicant Protocol.

### 27.5.5 **EFI_SUPPLICANT_PROTOCOL::BuildResponsePacket()**

**Summary**

*BuildResponsePacket()* is called during STA and AP authentication is in progress. Supplicant derives the PTK or session keys depend on type of authentication is being employed.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_SUPPLICANT_BUILD_RESPONSE_PACKET)(
    IN EFI_SUPPLICANT_PROTOCOL *This,
    IN UINT8 *RequestBuffer, OPTIONAL
    IN UINTN RequestBufferSize, OPTIONAL
    OUT UINT8 *Buffer,
    IN OUT UINTN *BufferSize
);
```

**Parameters**

**This**

Pointer to the *EFI_SUPPLICANT_PROTOCOL* instance.

**RequestBuffer**

Pointer to the most recently received EAPOL packet. *NULL* means the supplicant need initiate the EAP authentication session and send EAPOL-Start message.

**RequestSize**

Packet size in bytes for the most recently received EAPOL packet. 0 is only valid when *RequestBuffer* is *NULL*.

**Buffer**

Pointer to the buffer to hold the built packet.

**BufferSize**

Pointer to the buffer size in bytes. On input, it is the buffer size provided by the caller. On output, it is the buffer size in fact needed to contain the packet.

**Description**

The consumer calls *BuildResponsePacket()* when it receives the security frame. It simply passes the data to supplicant to process the data. It could be WPA-PSK which starts the 4-way handshake, or WPA-EAP first starts with Authentication process and then 4-way handshake, or 2-way group key handshake. In process of authentication, 4-way handshake or group key handshake, Supplicant needs to communicate with its peer (AP/AS) to fill the output buffer parameter. Once the 4 way handshake or group key handshake is over, and PTK (Pairwise Transient keys) and GTK (Group Temporal Key) are generated.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The required EAPOL packet is built successfully.</td>
</tr>
</tbody>
</table>

continues on next page
Table 27.21 – continued from previous page

<table>
<thead>
<tr>
<th>Code Point</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• RequestBuffer is NULL, but RequestSize is NOT 0.</td>
</tr>
<tr>
<td></td>
<td>• RequestSize is 0.</td>
</tr>
<tr>
<td></td>
<td>• Buffer is NULL, but RequestBuffer is NOT 0.</td>
</tr>
<tr>
<td></td>
<td>• RequestSize is 0.</td>
</tr>
<tr>
<td></td>
<td>• BufferSize is NULL.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>BufferSize is too small to hold the response packet.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>Current EAPOL session state is NOT ready to build ResponsePacket.</td>
</tr>
</tbody>
</table>

### 27.5.6 EFI_SUPPLICANT_PROTOCOL.ProcessPacket()

**Summary**

`ProcessPacket()` is called to Supplicant driver to encrypt or decrypt the data depending type of authentication type.

**Prototype**

```c
typedef EFI_STATUS (EFIAPIC *EFI_SUPPLICANT_PROCESS_PACKET)(
  IN EFI_SUPPLICANT_PROTOCOL *This,
  IN OUT EFI_SUPPLICANT_FRAGMENT_DATA **FragmentTable,
  IN UINT32 *FragmentCount,
  IN EFI_SUPPLICANT_CRYPT_MODE CryptMode
);
```

**Parameters**

- **This**
  - Pointer to the `EFI_SUPPLICANT_PROTOCOL` instance.

- **FragmentTable**
  - Pointer to a list of fragment. The caller will take responsible to handle the original `FragmentTable` while it may be reallocated in Supplicant driver.

- **FragmentCount**
  - Number of fragment.

- **CryptMode**
  - Crypt mode.

**Description**

`ProcessPacket()` is responsible for encrypting or decrypting the data traffic as per authentication type. The consumer routes the data frame as it is to Supplicant module and encrypts or decrypts packet with updated length comes as output parameter. Supplicant holds the derived PTK and GTKs and uses this key to encrypt or decrypt the network traffic.

If the Supplicant driver does not support any encryption and decryption algorithm, then `EFI_UNSUPPORTED` is returned.

**Related Definitions**
typedef struct {
    UINT32 FragmentLength;
    VOID *FragmentBuffer;
} EFI_SUPPLICANT_FRAGMENT_DATA;

**FragmentLength**
Length of data buffer in the fragment.

**FragmentBuffer**
Pointer to the data buffer in the fragment.

typedef enum {
    EfiSupplicantEncrypt,
    EfiSupplicantDecrypt,
} EFI_SUPPLICANT_CRYPT_MODE;

**EfiSupplicantEncrypt**
Encrypt data provided in the fragment buffers.

**EfiSupplicantDecrypt**
Decrypt data provided in the fragment buffers.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• FragmentTable is NULL.</td>
</tr>
<tr>
<td></td>
<td>• FragmentCount is NULL.</td>
</tr>
<tr>
<td></td>
<td>• CryptMode is invalid.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>Current supplicant state is NOT Authenticated.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>Something wrong decryption the message.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This API is not supported.</td>
</tr>
</tbody>
</table>

### 27.5.7 EFI_SUPPLICANT_PROTOCOL.SetData()

**Summary**
Set Supplicant configuration data.

**Prototype**

typedef EFI_STATUS (EFIAPI *EFI_SUPPLICANT_SET_DATA)(
    IN EFI_SUPPLICANT_PROTOCOL *This,
    (continues on next page)
IN EFI_SUPPLICANT_DATA_TYPE DataType,
IN VOID *Data,
IN UINTN DataSize
);

Parameters

This

Pointer to the EFI_SUPPLICANT_PROTOCOL instance.

DataType

The type of data.

Data

Pointer to the buffer to hold the data.

DataSize

Pointer to the buffer size in bytes.

Description

The SetData() function sets Supplicant configuration. For example, Supplicant driver need to know Password and TargetSSIDName to calculate PSK. Supplicant driver need to know StationMac and TargetSSIDMac to calculate PTK. Then it can derive KCK(key confirmation key) which is needed to calculate MIC, and KEK(key encryption key) which is needed to unwrap GTK.

Related Definitions

    //*************************************************************
    // EFI_SUPPLICANT_DATA_TYPE
    //*************************************************************
typedef enum {
    // Session Configuration
    //
    EfiSupplicant80211AKMSuite,
    EfiSupplicant80211GroupDataCipherSuite,
    EfiSupplicant80211PairwiseCipherSuite,
    EfiSupplicant80211PskPassword,
    EfiSupplicant80211TargetSSIDName,
    EfiSupplicant80211StationMac,
    EfiSupplicant80211TargetSSIDMac,
    //
    // Session Information
    //
    EfiSupplicant80211PTK,
    EfiSupplicant80211GTK,
    EfiSupplicantState,
    EfiSupplicant80211LinkState,
    EfiSupplicantKeyRefresh,
    //
    // Session Configuration
    //
    EfiSupplicant80211SupportedAKMSuites,
    EfiSupplicant80211SupportedSoftwareCipherSuites,
EfiSupplicant80211SupportedHardwareCipherSuites,

    //
    // Session Information
    //
    EfiSupplicant80211GTK,
    EfiSupplicant80211PMK,
    EfiSupplicantDataTypeMaximum

} EFI_SUPPLICANT_DATA_TYPE;

EfiSupplicant80211AKMSuite
Current authentication type in use. The corresponding Data is of type EFI_80211_AKM_SUITE_SELECTOR.

EfiSupplicant80211GroupDataCipherSuite
Group data encryption type in use. The corresponding Data is of type EFI_80211_CIPHER_SUITE_SELECTOR.

EfiSupplicant80211PairwiseCipherSuite
Pairwise encryption type in use. The corresponding Data is of type EFI_80211_CIPHER_SUITE_SELECTOR.

EfiSupplicant80211PskPassword
PSK password. The corresponding Data is a NULL-terminated ASCII string.

EfiSupplicant80211TargetSSIDName
Target SSID name. The corresponding Data is of type EFI_80211_SSID.

EfiSupplicant80211StationMac
Station MAC address. The corresponding Data is of type EFI_80211_MAC_ADDRESS.

EfiSupplicant80211TargetSSIDMac
Target SSID MAC address. The corresponding Data is 6 bytes MAC address.

EfiSupplicant80211PTK
802.11 PTK. The corresponding Data is of type EFI_SUPPLICANT_KEY.

EfiSupplicant80211GTK
802.11 GTK. The corresponding Data is of type EFI_SUPPLICANT_GTK_LIST.

EfiSupplicantState
Supplicant state. The corresponding Data is EFI_EAPOL_SUPPLICANT_PAE_STATE.

EfiSupplicant80211LinkState
802.11 link state. The corresponding Data is EFI_80211_LINK_STATE.

EfiSupplicantKeyRefresh
Flag indicates key is refreshed. The corresponding Data is EFI_SUPPLICANT_KEY_REFRESH.

EfiSupplicant80211SupportedAKMSuites
Supported authentication types. The corresponding Data is of type EFI_80211_AKM_SUITE_SELECTOR.

EfiSupplicant80211SupportedSoftwareCipherSuites
Supported software encryption types provided by supplicant driver. The corresponding Data is of type EFI_80211_CIPHER_SUITE_SELECTOR.

EfiSupplicant80211SupportedHardwareCipherSuites
Supported hardware encryption types provided by wireless UNDI driver. The corresponding Data is of type EFI_80211_CIPHER_SUITE_SELECTOR.
EfiSupplicant80211IGTK

802.11 Integrity GTK. The corresponding Data is of type EFI_SUPPLICANT_GTK_LIST.

EfiSupplicant80211IPMK

802.11 PMK. The corresponding Data is 32 bytes pairwise master key.

```c
typedef enum {  
    Ieee80211UnauthenticatedUnassociated,  
    Ieee80211AuthenticatedUnassociated,  
    Ieee80211PendingRSNAuthentication,  
    Ieee80211AuthenticatedAssociated  
} EFI_80211_LINK_STATE;
```

- **Ieee80211UnauthenticatedUnassociated**: Indicates initial start state, unauthenticated, unassociated.
- **Ieee80211AuthenticatedUnassociated**: Indicates authenticated, unassociated.
- **Ieee80211PendingRSNAuthentication**: Indicates authenticated and associated, but pending RSN authentication.
- **Ieee80211AuthenticatedAssociated**: Indicates authenticated and associated.

```c
typedef struct {  
    BOOLEAN GTKRefresh;  
} EFI_SUPPLICANT_KEY_REFRESH;
```

**GTKRefresh**: If TRUE, indicates GTK is just refreshed after a successful call to EFI_SUPPLICANT_PROTOCOL.BuildResponsePacket().

```c
typedef struct {  
    UINT8 GTKCount;  
    EFI_SUPPLICANT_KEY GTKList[1];  
} EFI_SUPPLICANT_GTK_LIST;
```

**GTKCount**: Indicates the number of GTKs that are contained in GTKList.

**GTKList**: A variable-length array of GTKs of type EFI_SUPPLICANT_KEY. The number of entries is specified by GTKCount.

```c
#define EFI_MAX_KEY_LEN 64
```

(continues on next page)
typedef struct {
  UINT8 Key[EFI_MAX_KEY_LEN];
  UINT8 KeyLen;
  UINT8 KeyId;
  EFI_SUPPLICANT_KEY_TYPE KeyType;
  EFI_80211_MAC_ADDRESS Addr;
  UINT8 Rsc[8];
  UINT8 RscLen;
  BOOLEAN IsAuthenticator;
  EFI_80211_SUITE_SELECTOR CipherSuite;
  EFI_SUPPLICANT_KEY_DIRECTION Direction;
} EFI_SUPPLICANT_KEY;

The EFI_SUPPLICANT_KEY descriptor is defined in the IEEE 802.11 standard, section 6.3.19.1.2.

Key
  The key value.

KeyLen
  Length in bytes of the Key. Should be up to EFI_MAX_KEY_LEN.

KeyId
  The key identifier.

KeyType
  Defines whether this key is a group key, pairwise key, PeerKey, or Integrity Group.

Addr
  The value is set according to the KeyType.

Rsc
  The Receive Sequence Count value.

RscLen
  Length in bytes of the Rsc. Should be up to 8.

IsAuthenticator
  Indicates whether the key is configured by the Authenticator or Supplicant. The value true indicates Authenticator.

CipherSuite
  The cipher suite required for this association.

Direction
  Indicates the direction for which the keys are to be installed.
IGTK
) EFI_SUPPLICANT_KEY_TYPE;

The EFI_SUPPLICANT_KEY_TYPE is defined in the IEEE 802.11 specification.

```c
typedef enum {
    Receive,
    Transmit,
    Both
} EFI_SUPPLICANT_KEY_DIRECTION;
```

- **Receive**: Indicates that the keys are being installed for the receive direction.
- **Transmit**: Indicates that the keys are being installed for the transmit direction.
- **Both**: Indicates that the keys are being installed for both the receive and transmit directions.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Supplicant configuration data is set successfully.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more of the following conditions is TRUE:
  * Data is NULL.
  * DataSize is 0. |
| EFI_UNSUPPORTED     | The DataType is unsupported.                                                |
| EFI_OUT_OF_RESOURCES| Required system resources could not be allocated.                          |

### 27.5.8 EFI_SUPPLICANT_PROTOCOL.GetData()

#### Summary
Get Supplicant configuration data.

#### Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_SUPPLICANT_GET_DATA)(
    IN EFI_SUPPLICANT_PROTOCOL    *This,
    IN EFI_SUPPLICANT_DATA_TYPE   *DataType,
    OUT UINT8                     *Data,
    OUT UINTN                     *DataSize
);
```

#### Parameters
This
   Pointer to the \textit{EFI\_SUPPLICANT\_PROTOCOL} instance.

\textbf{DataType}
   The type of data.

\textbf{Data}
   Pointer to the buffer to hold the data. Ignored if \textit{DataSize} is 0.

\textbf{DataSize}
   Pointer to the buffer size in bytes. On input, it is the buffer size provided by the caller. On output, it is the buffer size in fact needed to contain the packet.

\textbf{Description}
   The \textit{GetData()} function gets Supplicant configuration. The typical example is PTK and GTK derived from handshake. The wireless NIC can support software encryption or hardware encryption. If the consumer uses software encryption, it can call \textit{ProcessPacket()} to get result. If the consumer supports hardware encryption, it can get PTK and GTK via \textit{GetData()} and program to hardware register.

\textbf{Status Codes Returned}

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\textbf{EFI_SUCCESS}</td>
<td>The Supplicant configuration data is got successfully.</td>
</tr>
<tr>
<td>\textbf{EFI_INVALID_PARAMETER}</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>\quad • This is NULL.</td>
</tr>
<tr>
<td></td>
<td>\quad • DataSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>\quad • Data is NULL if DataSize is not zero.</td>
</tr>
<tr>
<td>\textbf{EFI_UNSUPPORTED}</td>
<td>The \textit{DataType} is unsupported.</td>
</tr>
<tr>
<td>\textbf{EFI_NOT_FOUND}</td>
<td>The Supplicant configuration data is not found.</td>
</tr>
<tr>
<td>\textbf{EFI_BUFFER_TOO_SMALL}</td>
<td>The size of \textit{Data} is too small for the specified configuration data and the required size is returned in \textit{DataSize}.</td>
</tr>
</tbody>
</table>
28.1 EFI TCPv4 Protocol

This section defines the EFI TCPv4 (Transmission Control Protocol version 4) Protocol.

28.1.1 TCP4 Service Binding Protocol

28.1.2 EFI_TCP4_SERVICE_BINDING_PROTOCOL

Summary

The EFI TCPv4 Service Binding Protocol is used to locate EFI TCPv4 Protocol drivers to create and destroy child of the driver to communicate with other host using TCP protocol.

GUID

```c
#define EFI_TCP4_SERVICE_BINDING_PROTOCOL_GUID \
{0x00720665,0x67EB,0x4a99,\ 
 {0xBA,0xF7,0xD3,0xC3,0x3A,0x1C,0x7C,0xC9}}
```

Description

A network application that requires TCPv4 I/O services can call one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search devices that publish an EFI TCPv4 Service Binding Protocol GUID. Such device supports the EFI TCPv4 Protocol and may be available for use.

After a successful call to the `EFI_TCP4_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the newly created child EFI TCPv4 Protocol driver is in an un-configured state; it is not ready to do any operation except `Poll()` send and receive data packets until configured as the purpose of the user and perhaps some other indispensable function belonged to TCPv4 Protocol driver is called properly.

Every successful call to the `EFI_TCP4_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI_TCP4_SERVICE_BINDING_PROTOCOL.DestroyChild()` function to release the protocol driver.
28.1.3 TCP4 Protocol

28.1.4 EFI_TCP4_PROTOCOL

Summary

The EFI TCPv4 Protocol provides services to send and receive data stream.

GUID

```
#define EFI_TCP4_PROTOCOL_GUID \
  {0x65530BC7,0xA359,0x410f,\ 
   {0xB0,0x10,0x5A,0xAD,0xC7,0xEC,0x2B,0x62}}
```

Protocol Interface Structure

```c
typedef struct _EFI_TCP4_PROTOCOL {
  EFI_TCP4_GET_MODE_DATA GetModeData;
  EFI_TCP4_CONFIGURE Configure;
  EFI_TCP4_ROUTES Routes;
  EFI_TCP4_CONNECT Connect;
  EFI_TCP4_ACCEPT Accept;
  EFI_TCP4_TRANSMIT Transmit;
  EFI_TCP4_RECEIVE Receive;
  EFI_TCP4_CLOSE Close;
  EFI_TCP4_CANCEL Cancel;
  EFI_TCP4_POLL Poll;
} EFI_TCP4_PROTOCOL;
```

Parameters

GetModeData

Get the current operational status. See the GetModeData() function description.

Configure

Initialize, change, or brutally reset operational settings of the EFI TCPv4 Protocol. See the Configure() function description.

Routes

Add or delete routing entries for this TCP4 instance. See the Routes() function description.

Connect

Initiate the TCP three-way handshake to connect to the remote peer configured in this TCP instance. The function is a nonblocking operation. See the Connect() function description.

Accept

Listen for incoming TCP connection request. This function is a nonblocking operation. See the Accept() function description.

Transmit

Queue outgoing data to the transmit queue. This function is a nonblocking operation. See the Transmit() function description.

Receive

Queue a receiving request token to the receive queue. This function is a nonblocking operation. See the Receive() function description.
Close
Gracefully disconnecting a TCP connection follow RFC 793 or reset a TCP connection. This function is a nonblocking operation. See the Close() function description.

Cancel
Abort a pending connect, listen, transmit or receive request. See the Cancel() function description.

Poll
Poll to receive incoming data and transmit outgoing TCP segments. See the Poll() function description.

Description
The EFI_TCP4_PROTOCOL defines the EFI TCPv4 Protocol child to be used by any network drivers or applications to send or receive data stream. It can either listen on a specified port as a service or actively connected to remote peer as a client. Each instance has its own independent settings, such as the routing table.

Note: In this document, all IPv4 addresses and incoming/outgoing packets are stored in network byte order. All other parameters in the functions and data structures that are defined in this document are stored in host byte order unless explicitly specified.

28.1.5 EFI_TCP4_PROTOCOL.GetModeData()

Summary
Get the current operational status.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_TCP4_GET_MODE_DATA) (  
IN EFI_TCP4_PROTOCOL *This,  
OUT EFI_TCP4_CONNECTION_STATE *Tcp4State OPTIONAL,  
OUT EFI_TCP4_CONFIG_DATA *Tcp4ConfigData OPTIONAL,  
OUT EFI_IPv4_MODE_DATA *Ip4ModeData OPTIONAL,  
OUT EFI_MANAGED_NETWORK_CONFIG_DATA *MnpConfigData OPTIONAL,  
OUT EFI_SIMPLE_NETWORK_MODE *SnpModeData OPTIONAL);

Parameters

This
Pointer to the EFI_TCP4_PROTOCOL instance.

Tcp4State
Pointer to the buffer to receive the current TCP state. Type EFI_TCP4_CONNECTION_STATE is defined in “Related Definitions” below.

Tcp4ConfigData
Pointer to the buffer to receive the current TCP configuration. Type EFI_TCP4_CONFIG_DATA is defined in “Related Definitions” below.

Ip4ModeData
Pointer to the buffer to receive the current IPv4 configuration data used by the TCPv4 instance. Type EFI_IP4_MODE_DATA is defined in EFI_IP4_PROTOCOL.GetModeData().

MnpConfigData
Pointer to the buffer to receive the current MNP configuration data used indirectly by
the TCPv4 instance. Type `EFI_MANAGED_NETWORK_CONFIG_DATA` is defined in `EFI_MANAGED_NETWORK_PROTOCOL.GetModeData()`.

**SnpModeData**

Pointer to the buffer to receive the current SNP configuration data used indirectly by the TCPv4 instance. Type `EFI_SIMPLE_NETWORK_MODE` is defined in the `EFI_SIMPLE_NETWORK_PROTOCOL`.

**Description**

The `GetModeData()` function copies the current operational settings of this EFI TCPv4 Protocol instance into user-supplied buffers. This function can also be used to retrieve the operational setting of underlying drivers such as IPv4, MNP, or SNP.

**Related Definition**

```c
typedef struct {
    BOOLEAN UseDefaultAddress;
    EFI_IPv4_ADDRESS StationAddress;
    EFI_IPv4_ADDRESS SubnetMask;
    UINT16 StationPort;
    EFI_IPv4_ADDRESS RemoteAddress;
    UINT16 RemotePort;
    BOOLEAN ActiveFlag;
} EFI_TCP4_ACCESS_POINT;
```

**UseDefaultAddress**

Set to `TRUE` to use the default IP address and default routing table. If the default IP address is not available yet, then the underlying EFI IPv4 Protocol driver will use `EFI_IP4_CONFIG2_PROTOCOL` to retrieve the IP address and subnet information.

**StationAddress**

The local IP address assigned to this EFI TCPv4 Protocol instance. The EFI TCPv4 and EFI IPv4 Protocol drivers will only deliver incoming packets whose destination addresses exactly match the IP address. Not used when `UseDefaultAddress` is `TRUE`.

**SubnetMask**

The subnet mask associated with the station address. Not used when `UseDefaultAddress` is `TRUE`.

**StationPort**

The local port number to which this EFI TCPv4 Protocol instance is bound. If the instance doesn’t care the local port number, set `StationPort` to zero to use an ephemeral port.

**RemoteAddress**

The remote IP address to which this EFI TCPv4 Protocol instance is connected. If `ActiveFlag` is `FALSE` (i.e., a passive TCPv4 instance), the instance only accepts connections from the `RemoteAddress`. If `ActiveFlag` is `TRUE` the instance is connected to the `RemoteAddress`, i.e., outgoing segments will be sent to this address and only segments from this address will be delivered to the application. When `ActiveFlag` is `FALSE` it can be set to zero and means that incoming connection request from any address will be accepted.

**RemotePort**

The remote port to which this EFI TCPv4 Protocol instance is connects or connection request from which is accepted by this EFI TCPv4 Protocol instance. If `ActiveFlag` is `FALSE` it can be zero and means that incoming connection request from any port will be accepted. Its value can not be zero when `ActiveFlag` is `TRUE`.

**ActiveFlag**

Set it to `TRUE` to initiate an active open. Set it to `FALSE` to initiate a passive open to act as a server.
UINT32 SendBufferSize;
UINT32 MaxSynBackLog;
UINT32 ConnectionTimeout;
UINT32 DataRetries;
UINT32 FinTimeout;
UINT32 TimeWaitTimeout;
UINT32 KeepAliveProbes;
UINT32 KeepAliveTime;
UINT32 KeepAliveInterval;
BOOLEAN EnableNagle;
BOOLEAN EnableTimeStamp;
BOOLEAN EnableWindowScaling;
BOOLEAN EnableSelectiveAck;
BOOLEAN EnablePathMtuDiscovery;
}

**ReceiveBufferSize**

The size of the TCP receive buffer.

**SendBufferSize**

The size of the TCP send buffer.

**MaxSynBackLog**

The length of incoming connect request queue for a passive instance. When set to zero, the value is implementation specific.

**ConnectionTimeout**

The maximum seconds a TCP instance will wait for before a TCP connection established. When set to zero, the value is implementation specific.

**DataRetries**

The number of times TCP will attempt to retransmit a packet on an established connection. When set to zero, the value is implementation specific.

**FinTimeout**

How many seconds to wait in the FIN_WAIT_2 states for a final FIN flag before the TCP instance is closed. This timeout is in effective only if the application has called `Close()` to disconnect the connection completely. It is also called FIN_WAIT_2 timer in other implementations. When set to zero, it should be disabled because the FIN_WAIT_2 timer itself is against the standard.

**TimeWaitTimeout**

How many seconds to wait in TIME_WAIT state before the TCP instance is closed. The timer is disabled completely to provide a method to close the TCP connection quickly if it is set to zero. It is against the related RFC documents.

**KeepAliveProbes**

The maximum number of TCP keep-alive probes to send before giving up and resetting the connection if no response from the other end. Set to zero to disable keep-alive probe.

**KeepAliveTime**

The number of seconds a connection needs to be idle before TCP sends out periodical keep-alive probes. When set to zero, the value is implementation specific. It should be ignored if keep-alive probe is disabled.

**KeepAliveInterval**

The number of seconds between TCP keep-alive probes after the periodical keep-alive probe if no response. When set to zero, the value is implementation specific. It should be ignored if keep-alive probe is disabled.
EnableNagle
Set it to **TRUE** to enable the Nagle algorithm as defined in RFC896. Set it to **FALSE** to disable it.

EnableTimeStamp
Set it to **TRUE** to enable TCP timestamps option as defined in RFC7323. Set to **FALSE** to disable it.

EnableWindowScaling
Set it to **TRUE** to enable TCP window scale option as defined in RFC7323. Set it to **FALSE** to disable it.

EnableSelectiveAck
Set it to **TRUE** to enable selective acknowledge mechanism described in RFC 2018. Set it to **FALSE** to disable it. Implementation that supports SACK can optionally support DSAK as defined in RFC 2883.

EnablePathMtudiscovery
Set it to **TRUE** to enable path MTU discovery as defined in RFC 1191. Set to **FALSE** to disable it.

Option setting with digital value will be modified by driver if it is set out of the implementation specific range and an implementation specific default value will be set accordingly.

```c
typedef struct {
    // Receiving Filters
    // I/O parameters
    UINT8       TypeOfService;
    UINT8       TimeToLive;

    // Access Point
    EFI_TCP4_ACCESS_POINT AccessPoint;

    // TCP Control Options
    EFI_TCP4_OPTION     ControlOption;
} EFI_TCP4_CONFIG_DATA;
```

**TypeOfService**
*TypeOfService* field in transmitted IPv4 packets.

**TimeToLive**
*TimeToLive* field in transmitted IPv4 packets.

**AccessPoint**
Used to specify TCP communication end settings for a TCP instance.

**ControlOption**
Used to configure the advance TCP option for a connection. If set to **NULL**, implementation specific options for TCP connection will be used.
TCP4StateEstablished = 4,
TCP4StateFinWait1 = 5,
TCP4StateFinWait2 = 6,
TCP4StateClosing = 7,
TCP4StateTimeWait = 8,
TCP4StateCloseWait = 9,
TCP4StateLastAck = 10
} EFI_TCP4_CONNECTION_STATE;

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The mode data was read.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>No configuration data is available because this instance hasn’t been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
</tbody>
</table>

28.1.6 EFI_TCP4_PROTOCOL.Configure()

Summary
Initialize or brutally reset the operational parameters for this EFI TCPv4 instance.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_TCP4_PROTOCOL) (  
    IN EFI_TCP4_PROTOCOL *This,
    IN EFI_TCP4_CONFIG_DATA *TcpConfigData OPTIONAL
);

Parameters

This
Pointer to the EFI_TCP4_PROTOCOL instance.

TcpConfigData
Pointer to the configure data to configure the instance.

Description
The Configure() function does the following:

- Initialize this EFI TCPv4 instance, i.e., initialize the communication end setting, specify active open or passive open for an instance.
- Reset this TCPv4 instance brutally, i.e., cancel all pending asynchronous tokens, flush transmission and receiving buffer directly without informing the communication peer.

No other TCPv4 Protocol operation can be executed by this instance until it is configured properly. For an active TCP4 instance, after a proper configuration it may call Connect() to initiates the three-way handshake. For a passive TCP4 instance, its state will transit to Tcp4StateListen after configuration, and Accept() may be called to listen the incoming TCP connection request. If TcpConfigData is set to NULL, the instance is reset. Resetting process will be done brutally, the state machine will be set to Tcp4StateClosed directly, the receive queue and transmit queue will be flushed, and no traffic is allowed through this instance.

Status Codes Returned
<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operational settings are set, changed, or reset successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (through DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more following conditions are TRUE:  
  • This is NULL.  
  • TcpConfigData  
      -> AccessPoint.StationAddress isn’t a valid unicast IPv4 address  
      when TcpConfigData  
      -> AccessPoint.UseDefaultAddress is FALSE.  
  • TcpConfigData  
      -> AccessPoint.SubnetMask isn’t a valid IPv4 address mask when  
      TcpConfigData  
      -> AccessPoint.UseDefaultAddress is FALSE. The subnet mask must be contiguous.  
  • TcpConfigData  
      -> AccessPoint.RemoteAddress isn’t a valid unicast IPv4 address.  
  • TcpConfigData  
      -> AccessPoint.RemoteAddress is zero or TcpConfigData  
      -> AccessPoint.RemotePort is zero when TcpConfigData  
      -> AccessPoint.ActiveFlag is TRUE.  
  • A same access point has been configured in other TCP instance properly. |
| EFI_ACCESS_DENIED   | Configuring TCP instance when it is configured without calling Configure() with NULL to reset it. |
| EFI_DEVICE_ERROR    | An unexpected network or system error occurred.                              |
| EFI_UNSUPPORTED    | One or more of the control options are not supported in the implementation. |
| EFI_OUT_OF_RESOURCES | Could not allocate enough system resources when executing Configure().      |

### 28.1.7 EFI_TCP4_PROTOCOL.Routes()

#### Summary
Add or delete routing entries.

#### Prototype

```c
typedef EFI_STATUS (EFAPI *EFI_TCP4_ROUTES) (  
    IN EFI_TCP4_PROTOCOL *This,  
    IN BOOLEAN DeleteRoute,  
    IN EFI_IPv4_ADDRESS *SubnetAddress,  
    IN EFI_IPv4_ADDRESS *SubnetMask,  
    IN EFI_IPv4_ADDRESS *GatewayAddress  
);
```

#### Parameters

**This**
Pointer to the EFI_TCP4_PROTOCOL instance.
DeleteRoute
Set it to \texttt{TRUE} to delete this route from the routing table. Set it to \texttt{FALSE} to add this route to the routing table. \textit{DestinationAddress} and \textit{SubnetMask} are used as the keywords to search route entry.

\textbf{SubnetAddress}
The destination network.

\textbf{SubnetMask}
The subnet mask of the destination network.

\textbf{GatewayAddress}
The gateway address for this route. It must be on the same subnet with the station address unless a direct route is specified.

\textbf{Description}
The \textit{Routes()} function adds or deletes a route from the instance’s routing table.

The most specific route is selected by comparing the \textit{SubnetAddress} with the destination IP address’s arithmetical \texttt{AND} to the \textit{SubnetMask}.

The default route is added with both \textit{SubnetAddress} and \textit{SubnetMask} set to 0.0.0.0. The default route matches all destination IP addresses if there is no more specific route.

Direct route is added with \textit{GatewayAddress} set to 0.0.0.0. Packets are sent to the destination host if its address can be found in the Address Resolution Protocol (ARP) cache or it is on the local subnet. If the instance is configured to use default address, a direct route to the local network will be added automatically.

Each TCP instance has its own independent routing table. Instance that uses the default IP address will have a copy of the \texttt{EFI_IP4_CONFIG2_PROTOCOL}’s routing table. The copy will be updated automatically whenever the IP driver reconfigures its instance. As a result, the previous modification to the instance’s local copy will be lost.

The priority of checking the route table is specific with IP implementation and every IP implementation must comply with RFC 1122.

\textbf{Note: There is no way to set up routes to other network interface cards (NICs) because each NIC has its own independent network stack that shares information only through EFI TCP4 variable.}

\textbf{Status Codes Returned}

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI TCPv4 Protocol instance has not been configured.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more of the following conditions is \texttt{TRUE}:  
  \begin{itemize}  
  \item \texttt{This is NULL.}  
  \item \textit{SubnetAddress} is \texttt{NULL.}  
  \item \textit{SubnetMask} is \texttt{NULL.}  
  \item \textit{GatewayAddress} is \texttt{NULL.}  
  \item \textit{SubnetAddress} is not \texttt{NULL} a valid subnet address.  
  \item \textit{SubnetMask} is not a valid subnet mask.  
  \item \textit{GatewayAddress} is not a valid unicast IP address or it is not in the same subnet.  
  \end{itemize} |
| EFI_OUT_OF_RESOURCES | Could not allocate enough resources to add the entry to the routing table. |
| EFI_NOT_FOUND | This route is not in the routing table. |

continues on next page
Table 28.3 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The route is already defined in the routing table.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The TCP driver does not support this operation.</td>
</tr>
</tbody>
</table>

### 28.1.8 EFI_TCP4_PROTOCOL.Connect()

**Summary**

Initiate a nonblocking TCP connection request for an active TCP instance.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_TCP4_CONNECT) (IN EFI_TCP4_PROTOCOL *This,
IN EFI_TCP4_CONNECTION_TOKEN *ConnectionToken,
);
```

**Parameters**

- **This**
  Pointer to the `EFI_TCP4_PROTOCOL` instance.

- **ConnectionToken**
  Pointer to the connection token to return when the TCP three way handshake finishes. Type `EFI_TCP4_CONNECTION_TOKEN` is defined in “Related Definition” below.

**Description**

The `Connect()` function will initiate an active open to the remote peer configured in current TCP instance if it is configured active. If the connection succeeds or fails due to any error, the `ConnectionToken->CompletionToken.Event` will be signaled and `ConnectionToken->CompletionToken.Status` will be updated accordingly. This function can only be called for the TCP instance in `Tcp4StateClosed` state. The instance will transfer into `Tcp4StateSynSent` if the function returns `EFI_SUCCESS`. If TCP three way handshake succeeds, its state will become `Tcp4StateEstablished`, otherwise, the state will return to `Tcp4StateClosed`.

**Related Definition**

```c
//********************************************************
// EFI_TCP4_COMPLETION_TOKEN
//********************************************************
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
} EFI_TCP4_COMPLETION_TOKEN;
```

- **Event**
  The `Event` to signal after request is finished and `Status` field is updated by the EFI TCPv4 Protocol driver. The type of `Event` must be `EVT_NOTIFY_SIGNAL`, and its Task Priority Level (TPL) must be lower than or equal to `TPL_CALLBACK`.

- **Status**
  The variable to receive the result of the completed operation. `EFI_NO_MEDIA`. There was a media error

The `EFI_TCP4_COMPLETION_TOKEN` is used as a common header for various asynchronous tokens.
typedef struct {
  EFI_TCP4_COMPLETION_TOKEN CompletionToken;
} EFI_TCP4_CONNECTION_TOKEN;

Status

The Status in the CompletionToken will be set to one of the following values if the active open succeeds or an unexpected error happens:

**EFI_SUCCESS.** The active open succeeds and the instance is in Tcp4StateEstablished.

**EFI_CONNECTION_RESET.** The connect fails because the connection is reset either by instance itself or communication peer.

**EFI_CONNECTION_REFUSED.** The connect fails because this connection is initiated with an active open and the connection is refused.

**EFI_ABORTED.** The active open was aborted.

**EFI_TIMEOUT.** The connection establishment timer expired and no more specific information is available.

**EFI_NETWORK_UNREACHABLE.** The active open fails because an ICMP network unreachable error is received.

**EFI_HOST_UNREACHABLE.** The active open fails because an ICMP host unreachable error is received.

**EFI_PROTOCOL_UNREACHABLE.** The active open fails because an ICMP protocol unreachable error is received.

**EFI_PORT_UNREACHABLE.** The connection establishment timer times out and an ICMP port unreachable error is received.

**EFI_ICMP_ERROR.** The connection establishment timer timeout and some other ICMP error is received.

**EFI_DEVICE_ERROR.** An unexpected system or network error occurred.

Status Codes Returned
<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The connection request is successfully initiated and the state of this TCPv4 instance has been changed to Tcp4StateSynSent.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI TCPv4 Protocol instance has not been configured.</td>
</tr>
</tbody>
</table>
| EFI_ACCESS_DENIED | One or more of the following conditions are TRUE:  
  • This instance is not configured as an active one.  
  • This instance is not in Tcp4StateClosed state. |
| EFI_INVALID_PARAMETER | One or more of the following are TRUE:  
  • This is NULL.  
  • ConnectionToken is NULL.  
  • ConnectionToken -> CompletionToken. Event is NULL. |
| EFI_OUT_OF_RESOURCES | The driver can’t allocate enough resource to initiate the active open. |
| EFI_DEVICE_ERROR | An unexpected system or network error occurred. |

### 28.1.9 EFI_TCP4_PROTOCOL.Accept()

**Summary**

Listen on the passive instance to accept an incoming connection request. This is a nonblocking operation.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_TCP4_ACCEPT) (  
    IN EFI_TCP4_PROTOCOL *This,  
    IN EFI_TCP4_LISTEN_TOKEN *ListenToken  
);
```

**Parameters**

**This**

Pointer to the EFI_TCP4_PROTOCOL instance.

**ListenToken**

Pointer to the listen token to return when operation finishes. Type EFI_TCP4_LISTEN_TOKEN is defined in “Related Definition” below.

**Related Definition**

```c
/*********************************************************************/
// EFI_TCP4_LISTEN_TOKEN
/*********************************************************************/
typedef struct {  
    EFI_TCP4_COMPLETION_TOKEN CompletionToken;  
    EFI_HANDLE NewChildHandle;  
} EFI_TCP4_LISTEN_TOKEN;
```

**Status**

The Status in CompletionToken will be set to the following value if accept finishes:
**EFI_SUCCESS.** A remote peer has successfully established a connection to this instance. A new TCP instance has also been created for the connection.

**EFI_CONNECTION_RESET.** The accept fails because the connection is reset either by instance itself or communication peer.

**EFI_ABORTED.** The accept request has been aborted.

**NewChildHandle**
The new TCP instance handle created for the established connection.

**Description**
The `Accept()` function initiates an asynchronous accept request to wait for an incoming connection on the passive TCP instance. If a remote peer successfully establishes a connection with this instance, a new TCP instance will be created and its handle will be returned in `ListenToken->NewChildHandle`. The newly created instance is configured by inheriting the passive instance’s configuration and is ready for use upon return. The instance is in the Tcp4StateEstablished state.

The `ListenToken->CompletionToken.Event` will be signaled when a new connection is accepted, user aborts the listen or connection is reset.

This function only can be called when current TCP instance is in Tcp4StateListen state.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The listen token has been queued successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI TCPv4 Protocol instance has not been configured.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>One or more of the following are <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• This instance is not a passive instance.</td>
</tr>
<tr>
<td></td>
<td>• This instance is not in Tcp4StateListen state.</td>
</tr>
<tr>
<td></td>
<td>• The same listen token has already existed in the listen token queue of this</td>
</tr>
<tr>
<td></td>
<td>TCP instance.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <code>ListenToken</code> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <code>ListenToken-&gt;CompletionToken.Event</code> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate enough resource to finish the operation.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Any unexpected and not belonged to above category error.</td>
</tr>
</tbody>
</table>
28.1.10 EFI_TCP4_PROTOCOL.Transmit()

**Summary**
Queues outgoing data into the transmit queue.

**Prototype**
```c
typedef EFI_STATUS (EFIAPI *EFI_TCP4_TRANSMIT) (
    IN EFI_TCP4_PROTOCOL *This,
    IN EFI_TCP4_IO_TOKEN *Token
);
```

**Parameters**

*This*  
Pointer to the `EFI_TCP4_PROTOCOL` instance.

*Token*  
Pointer to the completion token to queue to the transmit queue. Type `EFI_TCP4_IO_TOKEN` is defined in “Related Definitions” below.

**Description**
The `Transmit()` function queues a sending request to this TCPv4 instance along with the user data. The status of the token is updated and the event in the token will be signaled once the data is sent out or some error occurs.

**Related Definition**
```c
typedef struct {
    EFI_TCP4_COMPLETION_TOKEN CompletionToken;
    union {
        EFI_TCP4_RECEIVE_DATA *RxData;
        EFI_TCP4_TRANSMIT_DATA *TxData;
    } Packet;
} EFI_TCP4_IO_TOKEN;
```

**Status**
When transmission finishes or meets any unexpected error it will be set to one of the following values:

*EFI_SUCCESS*. The receiving or transmission operation completes successfully.

*EFI_CONNECTION_FIN*: The receiving operation fails because the communication peer has closed the connection and there is no more data in the receive buffer of the instance.

*EFI_CONNECTION_RESET*. The receiving or transmission operation fails because this connection is reset either by instance itself or communication peer.
**EFI_ABORTED.** The receiving or transmission is aborted.

**EFI_TIMEOUT.** The transmission timer expires and no more specific information is available.

**EFI_NETWORK_UNREACHABLE.** The transmission fails because an ICMP network unreachable error is received.

**EFI_HOST_UNREACHABLE.** The transmission fails because an ICMP host unreachable error is received.

**EFI_PROTOCOL_UNREACHABLE.** The transmission fails because an ICMP protocol unreachable error is received.

**EFI_PORT_UNREACHABLE.** The transmission fails and an ICMP port unreachable error is received.

**EFI_ICMP_ERROR.** The transmission fails and some other ICMP error is received.

**EFI_DEVICE_ERROR.** An unexpected system or network error occurs.

**EFI_NO_MEDIA.** There was a media error

**RxData**
When this token is used for receiving, RxData is a pointer to **EFI_TCP4_RECEIVE_DATA**. Type **EFI_TCP4_RECEIVE_DATA** is defined below.

**TxData**
When this token is used for transmitting, TxData is a pointer to **EFI_TCP4_TRANSMIT_DATA**. Type **EFI_TCP4_TRANSMIT_DATA** is defined below.

The **EFI_TCP4_IO_TOKEN** structures are used for both transmit and receive operations.

When used for transmitting, the CompletionToken.Event and TxData fields must be filled in by the user. After the transmit operation completes, the CompletionToken.Status field is updated by the instance and the Event is signaled.

- When used for receiving, the CompletionToken.Event and RxData fields must be filled in by the user. After a receive operation completes, RxData and Status are updated by the instance and the Event is signaled.

```c
#define EFI_CONNECTION_FIN EFIERR (104)
#define EFI_CONNECTION_RESET EFIERR (105)
#define EFI_CONNECTION_REFUSED EFIERR (106)
```

**NOTE:** **EFIERR()** sets the maximum bit. Similar to how error codes are described in Appendix D — Status Codes.
typedef struct {
    BOOLEAN UrgentFlag;
    UINT32 DataLength;
    UINT32 FragmentCount;
    EFI_TCP4_FRAGMENT_DATA FragmentTable[1];
} EFI_TCP4_RECEIVE_DATA;

UrgentFlag
Whether those data are urgent. When this flag is set, the instance is in urgent mode. The implementations of this specification should follow RFC793 to process urgent data, and should NOT mix the data across the urgent point in one token.

DataLength
When calling Receive() function, it is the byte counts of all Fragment buffer in FragmentTable allocated by user. When the token is signaled by TCPv4 driver it is the length of received data in the fragments.

FragmentCount
Number of fragments.

FragmentTable
An array of fragment descriptors. Type EFI_TCP4_FRAGMENT_DATA is defined below.

When TCPv4 driver wants to deliver received data to the application, it will pick up the first queued receiving token, update its Token->Packet.RxData then signal the Token->CompletionToken.Event.

• The FragmentBuffers in FragmentTable are allocated by the application when calling Receive() function and received data will be copied to those buffers by the driver. FragmentTable may contain multiple buffers that are NOT in the continuous memory locations. The application should combine those buffers in the FragmentTable to process data if necessary.

typedef struct {
    UINT32 FragmentLength;
    VOID *FragmentBuffer;
} EFI_TCP4_FRAGMENT_DATA;

FragmentLength
Length of data buffer in the fragment.

FragmentBuffer
Pointer to the data buffer in the fragment.

EFI_TCP4_FRAGMENT_DATA allows multiple receive or transmit buffers to be specified. The purpose of this structure is to provide scattered read and write.

typedef struct {
    BOOLEAN Push;
    BOOLEAN Urgent;
} EFI_TCP4_TRANSMIT_DATA;

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Pull
If TRUE, data must be transmitted promptly, and the PUSH bit in the last TCP segment created will be set. If FALSE, data transmission may be delay to combine with data from subsequent Transmit() s for efficiency.

Urgent
The data in the fragment table are urgent and urgent point is in effect if TRUE. Otherwise those data are NOT considered urgent.

DataLength
Length of the data in the fragments.

FragmentCount
Number of fragments.

FragmentTable
A array of fragment descriptors. Type EFI_TCP4_FRAGMENT_DATA is defined above.

The EFI TCPv4 Protocol user must fill this data structure before sending a packet. The packet may contain multiple buffers in non-continuous memory locations.

Status Codes Returned

<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The data has been queued for transmission.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI TCPv4 Protocol instance has not been configured.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;CompletionToken.Event is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;Packet.TxData is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;PacketFragmentCount is zero.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;Packet.DataLength is not equal to the sum of fragment lengths.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• A transmit completion token with the same Token-&gt;CompletionToken.Event was already in the transmission queue.</td>
</tr>
<tr>
<td></td>
<td>• The current instance is in Tcp4StateClosed state.</td>
</tr>
<tr>
<td></td>
<td>• The current instance is a passive one and it is in Tcp4StateListen state.</td>
</tr>
<tr>
<td></td>
<td>• User has called Close() to disconnect this connection.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The completion token could not be queued because the transmit queue is full.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not queue the transmit data because of resource shortage.</td>
</tr>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>There is no route to the destination network or address.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>
28.1.10.1 EFI_TCP4_PROTOCOL.Receive()

Summary
Places an asynchronous receive request into the receiving queue.

Prototype

typedef
EFI_STATUS
(EFIAPI EFI_TCP4_RECEIVE) (  
    IN EFI_TCP4_PROTOCOL *This,
    IN EFI_TCP4_IO_TOKEN *Token
);

Parameters

This
Pointer to the EFI_TCP4_PROTOCOL instance.

Token
Pointer to a token that is associated with the receive data descriptor. Type EFI_TCP4_IO_TOKEN is defined in EFI_TCP4_PROTOCOL.Transmit().

Description

The Receive() function places a completion token into the receive packet queue. This function is always asynchronous. The caller must allocate the Token->CompletionToken.Event and the FragmentBuffer used to receive data. He also must fill the DataLength which represents the whole length of all FragmentBuffer. When the receive operation completes, the EFI TCPv4 Protocol driver updates the Token->CompletionToken.Status and Token->Packet.RxData fields and the Token->CompletionToken.Event is signaled. If got data the data and its length will be copy into the FragmentTable, in the same time the full length of received data will be recorded in the DataLength fields. Providing a proper notification function and context for the event will enable the user to receive the notification and receiving status. That notification function is guaranteed to not be re-entered.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The receive completion token was cached.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI TCPv4 Protocol instance has not been configured.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is</td>
</tr>
<tr>
<td></td>
<td>not finished yet.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;CompletionToken.Event is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;Packet.RxData is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;Packet.RxData-&gt;DataLength is 0.</td>
</tr>
<tr>
<td></td>
<td>• The Token-&gt;Packet.RxData-&gt;DataLength is not the sum of all FragmentBuffer</td>
</tr>
<tr>
<td></td>
<td>length in FragmentTable.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The receive completion token could not be queued due to a lack of system</td>
</tr>
<tr>
<td></td>
<td>resources (usually memory).</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The EFI TCPv4 Protocol</td>
</tr>
<tr>
<td></td>
<td>instance has been reset to startup defaults.</td>
</tr>
</tbody>
</table>

continues on next page
Table 28.7 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>One or more of the following conditions is <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• A receive completion token with the same <strong>Token-&gt;CompletionToken_Event</strong> was already in the receive queue.</td>
</tr>
<tr>
<td></td>
<td>• The current instance is in <strong>Tcp4StateClosed</strong> state.</td>
</tr>
<tr>
<td></td>
<td>• The current instance is a passive one and it is in <strong>Tcp4StateListen</strong> state.</td>
</tr>
<tr>
<td></td>
<td>• User has called <strong>Close()</strong> to disconnect this connection.</td>
</tr>
<tr>
<td>EFI_CONNECTION_FIN</td>
<td>The communication peer has closed the connection and there is no any buffered data in the receive buffer of this instance.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The receive request could not be queued because the receive queue is full.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

### 28.1.11 EFI_TCP4_PROTOCOL.Close()

**Summary**

Disconnecting a TCP connection gracefully or reset a TCP connection. This function is a nonblocking operation.

**Prototype**

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_TCP4_CLOSE)(
    IN EFI_TCP4_PROTOCOL *This,
    IN EFI_TCP4_CLOSE_TOKEN *CloseToken
);
```

**Parameters**

**This**

Pointer to the **EFI_TCP4_PROTOCOL** instance.

**CloseToken**

Pointer to the close token to return when operation finishes. Type **EFI_TCP4_CLOSE_TOKEN** is defined in “Related Definition” below.

**Related Definition**

```c
//********************************************************
// EFI_TCP4_CLOSE_TOKEN
//********************************************************
typedef struct {
    EFI_TCP4_COMPLETION_TOKEN CompletionToken;
    BOOLEAN AbortOnClose;
} EFI_TCP4_CLOSE_TOKEN;
```

**Status**

When close finishes or meets any unexpected error it will be set to one of the following values:

- **EFI_SUCCESS**. The close operation completes successfully.
- **EFI_ABORTED**. User called configure with NULL without close stopping.
AbortOnClose

Abort the TCP connection on close instead of the standard TCP close process when it is set to **TRUE**. This option can be used to satisfy a fast disconnect.

**Description**

Initiate an asynchronous close token to TCP driver. After Close() is called, any buffered transmission data will be sent by TCP driver and the current instance will have a graceful close working flow described as RFC 793 if AbortOnClose is set to **FALSE**, otherwise, a rest packet will be sent by TCP driver to fast disconnect this connection. When the close operation completes successfully the TCP instance is in Tcp4StateClosed state, all pending asynchronous operation is signaled and any buffers used for TCP network traffic is flushed.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Close() is called successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI TCPv4 Protocol instance has not been configured.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>One or more of the following are <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• Configure() has been called with TcpConfigData set to NULL and this function has not returned.</td>
</tr>
<tr>
<td></td>
<td>• Previous Close() call on this instance has not finished.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• CloseToken is NULL.</td>
</tr>
<tr>
<td></td>
<td>• CloseToken-&gt;CompletionToken. Event is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate enough resource to finish the operation.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Any unexpected and not belonged to above category error.</td>
</tr>
</tbody>
</table>

**28.1.12 EFI_TCP4_PROTOCOL.Cancel()**

**Summary**

Abort an asynchronous connection, listen, transmission or receive request.

**Prototype**

```c
typedef
EFI_STATUS
(EIFI_API *EFI_TCP4_CANCEL)(
    IN EFI_TCP4_PROTOCOL *This,
    IN EFI_TCP4_COMPLETION_TOKEN *Token OPTIONAL
);
```

**Parameters**

**This**

Pointer to the **EFI_TCP4_PROTOCOL** instance.

**Token**

Pointer to a token that has been issued by
The ** EFI_TCP4_PROTOCOL.Connect() ** function aborts a pending connection, listen, transmit or receive request. If **Token** is not **NULL** and the token is in the connection, listen, transmission or receive queue when it is being cancelled, its **Token->Status** will be set to **EFI_ABORTED** and then **Token->Event** will be signaled. If the token is not in one of the queues, which usually means that the asynchronous operation has completed, **EFI_NOT_FOUND** is returned. If **Token** is **NULL** all asynchronous token issued by **Connect()**, **Accept()**, **Transmit()** and **Receive()** will be aborted.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>The asynchronous I/O request is aborted and <strong>Token-&gt;Event</strong> is signaled.</td>
</tr>
<tr>
<td><strong>EFI_INVALID_PARAMETER</strong></td>
<td><em>This is NULL.</em></td>
</tr>
<tr>
<td><strong>EFI_NOT_STARTED</strong></td>
<td>This instance hasn’t been configured.</td>
</tr>
<tr>
<td><strong>EFI_NO_MAPPING</strong></td>
<td>When using the default address, configuration (DHCP, BOOTP, RARP, etc.) hasn’t finished yet.</td>
</tr>
<tr>
<td><strong>EFI_NOT_FOUND</strong></td>
<td>The asynchronous I/O request isn’t found in the transmission or receive queue. It has either completed or wasn’t issued by <strong>Transmit()</strong> and <strong>Receive()</strong>.</td>
</tr>
<tr>
<td><strong>EFI_UNSUPPORTED</strong></td>
<td>The implementation does not support this function.</td>
</tr>
</tbody>
</table>

### 28.1.13 EFI_TCP4_PROTOCOL.Poll()

#### Summary

Poll to receive incoming data and transmit outgoing segments.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_TCP4_POLL) (IN EFI_TCP4_PROTOCOL *This);
```

#### Parameters

**This**

Pointer to the **EFI_TCP4_PROTOCOL** instance.

#### Description

The **Poll()** function increases the rate that data is moved between the network and application and can be called when the TCP instance is created successfully. Its use is optional.

In some implementations, the periodical timer in the MNP driver may not poll the underlying communications device fast enough to avoid drop packets. Drivers and applications that are experiencing packet loss should try calling the **Poll()** function in a high frequency.
Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>No incoming or outgoing data is processed.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Data was dropped out of the transmission or receive queue. Consider increasing the polling rate.</td>
</tr>
</tbody>
</table>

28.2 EFI TCPv6 Protocol

This section defines the EFI TCPv6 (Transmission Control Protocol version 6) Protocol.

28.2.1 TCPv6 Service Binding Protocol

28.2.2 EFI_TCP6_SERVICE_BINDING_PROTOCOL

Summary

The EFI TCPv6 Service Binding Protocol is used to locate EFI TCPv6 Protocol drivers to create and destroy protocol child instance of the driver to communicate with other host using TCP protocol.

GUID

```
#define EFI_TCP6_SERVICE_BINDING_PROTOCOL_GUID \
  {0xec20eb79,0x6c1a,0x4664,\ 
   {0x9a,0x0d,0xd2,0xe4,0xcc,0x16,0xd6, 0x64}}
```

Description

A network application that requires TCPv6 I/O services can call one of the protocol handler services, such as BS->LocateHandleBuffer(), to search devices that publish an EFI TCPv6 Service Binding Protocol GUID. Such device supports the EFI TCPv6 Protocol and may be available for use.

After a successful call to the EFI_TCP6_SERVICE_BINDING_PROTOCOL.CreateChild() function, the newly created child EFI TCPv6 Protocol driver is in an un-configured state; it is not ready to do any operation except Poll() send and receive data packets until configured.

Every successful call to the EFI_TCP6_SERVICE_BINDING_PROTOCOL.CreateChild() function must be matched with a call to the EFI_TCP6_SERVICE_BINDING_PROTOCOL.DestroyChild() function to release the protocol driver.

28.2.3 TCPv6 Protocol

28.2.4 EFI_TCP6_PROTOCOL

Summary

The EFI TCPv6 Protocol provides services to send and receive data stream.

GUID
Protocol Interface Structure

typedef struct _EFI_TCP6_PROTOCOL {
    EFI_TCP6_GET_MODE_DATA GetModeData;
    EFI_TCP6_CONFIGURE Configure;
    EFI_TCP6_CONNECT Connect;
    EFI_TCP6_ACCEPT Accept;
    EFI_TCP6_TRANSMIT Transmit;
    EFI_TCP6_RECEIVE Receive;
    EFI_TCP6_CLOSE Close;
    EFI_TCP6_CANCEL Cancel;
    EFI_TCP6_POLL Poll;
} EFI_TCP6_PROTOCOL;

Parameters

GetModeData
Get the current operational status. See the GetModeData() function description.

Configure
Initialize, change, or brutally reset operational settings of the EFI TCPv6 Protocol. See the Configure() function description.

Connect
Initiate the TCP three-way handshake to connect to the remote peer configured in this TCP instance. The function is a nonblocking operation. See the Connect() function description.

Accept
Listen for incoming TCP connection requests. This function is a nonblocking operation. See the Accept() function description.

Transmit
Queue outgoing data to the transmit queue. This function is a nonblocking operation. See the Transmit() function description.

Receive
Queue a receiving request token to the receive queue. This function is a nonblocking operation. See the Receive() function description.

Close
Gracefully disconnect a TCP connection follow RFC 793 or reset a TCP connection. This function is a non-blocking operation. See the Close() function description.

Cancel
Abort a pending connect, listen, transmit or receive request. See the Cancel() function description.

Poll
Poll to receive incoming data and transmit outgoing TCP segments. See the Poll() function description.

Description

The EFI_TCP6_PROTOCOL defines the EFI TCPv6 Protocol child to be used by any network drivers or applications to send or receive data stream. It can either listen on a specified port as a service or actively connect to remote peer as a client. Each instance has its own independent settings.
Note: Byte Order: In this document, all IPv6 addresses and incoming/outgoing packets are stored in network byte order. All other parameters in the functions and data structures that are defined in this document are stored in host byte order unless explicitly specified.

28.2.5 EFI_TCP6_PROTOCOL.GetModeData()

Summary
Get the current operational status.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_TCP6_GET_MODE_DATA) (
    IN EFI_TCP6_PROTOCOL *This,
    OUT EFI_TCP6_CONNECTION_STATE *Tcp6State OPTIONAL,
    OUT EFI_TCP6_CONFIG_DATA *Tcp6ConfigData OPTIONAL,
    OUT EFI_IPv6_MODE_DATA *Ip6ModeData OPTIONAL,
    OUT EFI_MANAGED_NETWORK_CONFIG_DATA *MnpConfigData OPTIONAL,
    OUT EFI_SIMPLE_NETWORK_MODE *SnpModeData OPTIONAL
    );

Parameters

This
Pointer to the EFI_TCP6_PROTOCOL instance.

Tcp6State
The buffer in which the current TCP state is returned. Type EFI_TCP6_CONNECTION_STATE is defined in “Related Definitions” below.

Tcp6ConfigData
The buffer in which the current TCP configuration is returned. Type EFI_TCP6_CONFIG_DATA is defined in “Related Definitions” below.

Ip6ModeData
The buffer in which the current IPv6 configuration data used by the TCP instance is returned. Type EFI_IP6_MODE_DATA is defined in EFI_IP6_PROTOCOL.GetModeData().

MnpConfigData
The buffer in which the current MNP configuration data used indirectly by the TCP instance is returned. Type EFI_MANAGED_NETWORK_CONFIG_DATA is defined in EFI_MANAGED_NETWORK_PROTOCOL.GetModeData().

SnpModeData
The buffer in which the current SNP mode data used indirectly by the TCP instance is returned. Type EFI_SIMPLE_NETWORK_MODE is defined in the EFI_SIMPLE_NETWORK_PROTOCOL.

Description
The GetModeData() function copies the current operational settings of this EFI TCPv6 Protocol instance into user-supplied buffers. This function can also be used to retrieve the operational setting of underlying drivers such as IPv6, MNP, or SNP.

Related Definition
typedef struct {
    EFI_IPv6_ADDRESS StationAddress;
    UINT16 StationPort;
    EFI_IPv6_ADDRESS RemoteAddress;
    UINT16 RemotePort;
    BOOLEAN ActiveFlag;
} EFI_TCP6_ACCESS_POINT;

StationAddress
The local IP address assigned to this TCP instance. The EFI TCPv6 driver will only deliver incoming packets whose destination addresses exactly match the IP address. Set to zero to let the underlying IPv6 driver choose a source address. If not zero it must be one of the configured IP addresses in the underlying IPv6 driver.

StationPort
The local port number to which this EFI TCPv6 Protocol instance is bound. If the instance doesn't care the local port number, set StationPort to zero to use an ephemeral port.

RemoteAddress
The remote IP address to which this EFI TCPv6 Protocol instance is connected. If ActiveFlag is FALSE (i.e., a passive TCPv6 instance), the instance only accepts connections from the RemoteAddress. If ActiveFlag is TRUE the instance will connect to the RemoteAddress, i.e., outgoing segments will be sent to this address and only segments from this address will be delivered to the application. When ActiveFlag is FALSE, it can be set to zero and means that incoming connection requests from any address will be accepted.

RemotePort
The remote port to which this EFI TCPv6 Protocol instance connects or from which connection request will be accepted by this EFI TCPv6 Protocol instance. If ActiveFlag is FALSE it can be zero and means that incoming connection request from any port will be accepted. Its value can not be zero when ActiveFlag is TRUE.

ActiveFlag
Set it to TRUE to initiate an active open. Set it to FALSE to initiate a passive open to act as a server.

//****************************************************
// EFI_TCP6_OPTION
//****************************************************
typedef struct {
    UINT32 ReceiveBufferSize;
    UINT32 SendBufferSize;
    UINT32 MaxSynBackLog;
    UINT32 ConnectionTimeout;
    UINT32 DataRetries;
    UINT32 FinTimeout;
    UINT32 TimeWaitTimeout;
    UINT32 KeepAliveProbes;
    UINT32 KeepAliveTime;
    UINT32 KeepAliveInterval;
    BOOLEAN EnableNagle;
    BOOLEAN EnableTimeStamp;
    BOOLEAN EnableWindowScaling;
    BOOLEAN EnableSelectiveAck;
    BOOLEAN EnablePathMtuDiscovery;
} EFI_TCP6_OPTION;

ReceiveBufferSize
The size of the TCP receive buffer.
SendBufferSize
The size of the TCP send buffer.

MaxSynBackLog
The length of incoming connect request queue for a passive instance. When set to zero, the value is implemen-
tation specific.

ConnectionTimeout
The maximum seconds a TCP instance will wait for before a TCP connection established. When set to zero, the
value is implementation specific.

DataRetries
The number of times TCP will attempt to retransmit a packet on an established connection. When set to zero,
the value is implementation specific.

FinTimeout
How many seconds to wait in the FIN_WAIT_2 states for a final FIN flag before the TCP instance is closed. This
timeout is in effective only if the application has called Close() to disconnect the connection completely. It is
also called FIN_WAIT_2 timer in other implementations. When set to zero, it should be disabled because the
FIN_WAIT_2 timer itself is against the standard.

TimeWaitTimeout
How many seconds to wait in TIME_WAIT state before the TCP instance is closed. The timer is disabled com-
pletely to provide a method to close the TCP connection quickly if it is set to zero. It is against the related RFC
documents.

KeepAliveProbes
The maximum number of TCP keep-alive probes to send before giving up and resetting the connection if no
response from the other end. Set to zero to disable keep-alive probe.

KeepAliveTime
The number of seconds a connection needs to be idle before TCP sends out periodical keep-alive probes. When
set to zero, the value is implementation specific. It should be ignored if keep-alive probe is disabled.

KeepAliveInterval
The number of seconds between TCP keep-alive probes after the periodical keep-alive probe if no response.
When set to zero, the value is implementation specific. It should be ignored if keep-alive probe is disabled.

EnableNagle
Set it to TRUE to enable the Nagle algorithm as defined in RFC896. Set it to FALSE to disable it.

EnableTimeStamp
Set it to TRUE to enable TCP timestamps option as defined in RFC7323. Set to FALSE to disable it.

EnableWindowScaling
Set it to TRUE to enable TCP window scale option as defined in RFC7323. Set it to FALSE to disable it.

EnableSelectiveAck
Set it to TRUE to enable selective acknowledge mechanism described in RFC 2018. Set it to FALSE to disable
it. Implementation that supports SACK can optionally support DSAK as defined in RFC 2883.

EnablePathMtudiscovery
Set it to TRUE to enable path MTU discovery as defined in RFC 1191. Set to FALSE to disable it.

Option setting with digital value will be modified by driver if it is set out of the implementation specific range and an
implementation specific default value will be set accordingly.

//********************************************************
// EFI_TCP6_CONFIG_DATA
//********************************************************
typedef struct {
    UINT8 TrafficClass;
    UINT8 HopLimit;
    EFI_TCP6_ACCESS_POINT AccessPoint;
    EFI_TCP6_OPTION *ControlOption;
} EFI_TCP6_CONFIG_DATA;

TrafficClass
TrafficClass field in transmitted IPv6 packets.

HopLimit
HopLimit field in transmitted IPv6 packets.

AccessPoint
Used to specify TCP communication end settings for a TCP instance.

ControlOption
Used to configure the advance TCP option for a connection. If set to NULL, implementation specific options for TCP connection will be used.

//********************************************************
// EFI_TCP6_CONNECTION_STATE
//********************************************************

typedef enum {
    Tcp6StateClosed = 0,
    Tcp6StateListen = 1,
    Tcp6StateSynSent = 2,
    Tcp6StateSynReceived = 3,
    Tcp6StateEstablished = 4,
    Tcp6StateFinWait1 = 5,
    Tcp6StateFinWait2 = 6,
    Tcp6StateClosing = 7,
    Tcp6StateTimeWait = 8,
    Tcp6StateCloseWait = 9,
    Tcp6StateLastAck = 10
} EFI_TCP6_CONNECTION_STATE;

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The mode data was read.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>No configuration data is available because this instance hasn’t been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
</tbody>
</table>
### 28.2.6 EFI_TCP6_PROTOCOL.Configure()

#### Summary

Initialize or brutally reset the operational parameters for this TCP instance.

#### Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_TCP6_CONFIGURE)(
    IN EFI_TCP6_PROTOCOL *This,
    IN EFI_TCP6_CONFIG_DATA *Tcp6ConfigData OPTIONAL
);
```

#### Parameters

- **This**
  - Pointer to the `EFI_TCP6_PROTOCOL` instance.

- **Tcp6ConfigData**
  - Pointer to the configure data to configure the instance.

#### Description

The `Configure()` function does the following:

- Initialize this TCP instance, i.e., initialize the communication end settings and specify active open or passive open for an instance.
- Reset this TCP instance brutally, i.e., cancel all pending asynchronous tokens, flush transmission and receiving buffer directly without informing the communication peer.

No other TCPv6 Protocol operation except `Poll()` can be executed by this instance until it is configured properly. For an active TCP instance, after a proper configuration it may call `Connect()` to initiates the three-way handshake. For a passive TCP instance, its state will transit to `Tcp6StateListen` after configuration, and `Accept()` may be called to listen the incoming TCP connection requests. If `Tcp6ConfigData` is set to `NULL`, the instance is reset. Resetting process will be done brutally, the state machine will be set to `Tcp6StateClosed` directly, the receive queue and transmit queue will be flushed, and no traffic is allowed through this instance.

#### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The operational settings are set, changed, or reset successfully.</td>
</tr>
<tr>
<td><code>EFI_NO_MAPPING</code></td>
<td>The underlying IPv6 driver was responsible for choosing a source address for this instance, but no source address was available for use.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>One or more of the following conditions are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is <code>NULL</code>.</td>
</tr>
<tr>
<td></td>
<td>• <code>Tcp6ConfigData-&gt;AccessPoint.StationAddress</code> is neither zero nor one of the configured IP addresses in the underlying IPv6 driver.</td>
</tr>
<tr>
<td></td>
<td>• <code>Tcp6ConfigData-&gt;AccessPoint.RemoteAddress</code> isn’t a valid unicast IPv6 address.</td>
</tr>
<tr>
<td></td>
<td>• <code>Tcp6ConfigData-&gt;AccessPoint.RemoteAddress</code> is zero or <code>Tcp6ConfigData-&gt;AccessPoint.RemotePort</code> is zero when <code>Tcp6ConfigData-&gt;AccessPoint.ActiveFlag</code> is <code>TRUE</code>.</td>
</tr>
<tr>
<td></td>
<td>• A same access point has been configured in other TCP instance properly.</td>
</tr>
</tbody>
</table>

Continues on next page...
Table 28.12 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Configuring TCP instance when it is configured without calling Configure()</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>One or more of the control options are not supported in the implementation.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate enough system resources when executing Configure().</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network or system error occurred.</td>
</tr>
</tbody>
</table>

28.2.7 EFI_TCP6_PROTOCOL.Connect()

Summary
Initiate a nonblocking TCP connection request for an active TCP instance.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_TCP6_CONNECT) (  
  IN EFI_TCP6_PROTOCOL *This,  
  IN EFI_TCP6_CONNECTION_TOKEN *ConnectionToken  
);
```

Parameters

This
Pointer to the EFI_TCP6_PROTOCOL instance.

ConnectionToken
Pointer to the connection token to return when the TCP three-way handshake finishes. Type EFI_TCP6_CONNECTION_TOKEN is defined in Related Definition below.

Description
The Connect() function will initiate an active open to the remote peer configured in current TCP instance if it is configured active. If the connection succeeds or fails due to any error, the ConnectionToken->CompletionToken.Event will be signaled and ConnectionToken->CompletionToken.Status will be updated accordingly. This function can only be called for the TCP instance in Tcp6StateClosed state. The instance will transfer into Tcp6StateSynSent if the function returns EFI_SUCCESS. If TCP three-way handshake succeeds, its state will become Tcp6StateEstablished, otherwise, the state will return to Tcp6StateClosed.

Related Definition

```c
//****************************************************************************
// EFI_TCP6_COMPLETION_TOKEN
//****************************************************************************
typedef struct {  
  EFI_EVENT Event;  
  EFI_STATUS Status;  
} EFI_TCP6_COMPLETION_TOKEN;
```

Event
The Event to signal after request is finished and Status field is updated by the EFI TCPv6 Protocol driver. The type of Event must be EVT_NOTIFY_SIGNAL.

Status
The result of the completed operation. EFI_NO_MEDIA. There was a media error

The EFI_TCP6_COMPLETION_TOKEN is used as a common header for various asynchronous tokens.
typedef struct {
  EFI_TCP6_COMPLETION_TOKEN CompletionToken;
} EFI_TCP6_CONNECTION_TOKEN;

Status

The *Status* in the *CompletionToken* will be set to one of the following values if the active open succeeds or an unexpected error happens:

**EFI_SUCCESS**: The active open succeeds and the instance’s state is Tcp6StateEstablished.

**EFI_CONNECTION_RESET**: The connect fails because the connection is reset either by instance itself or the communication peer.

**EFI_CONNECTION_REFUSED**: The receiving or transmission operation fails because this connection is refused.

**EFI_ABORTED**: The active open is aborted.

**EFI_TIMEOUT**: The connection establishment timer expires and no more specific information is available.

**EFI_NETWORK_UNREACHABLE**: The active open fails because an ICMP network unreachable error is received.

**EFI_HOST_UNREACHABLE**: The active open fails because an ICMP host unreachable error is received.

**EFI_PROTOCOL_UNREACHABLE**: The active open fails because an ICMP protocol unreachable error is received.

**EFI_PORT_UNREACHABLE**: The connection establishment timer times out and an ICMP port unreachable error is received.

**EFI_ICMP_ERROR**: The connection establishment timer times out and some other ICMP error is received.

**EFI_DEVICE_ERROR**: An unexpected system or network error occurred.

**EFI_SECURITY_VIOLATION**: The active open was failed because of IPSec policy check.
Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The connection request is successfully initiated and the state of this TCP instance has been changed to Tcp6StateSynSent.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI TCPv6 Protocol instance has not been configured.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>One or more of the following conditions are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This instance is not configured as an active one.</td>
</tr>
<tr>
<td></td>
<td>• This instance is not in Tcp6StateClosed state.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This instance is configured as an active one.</td>
</tr>
<tr>
<td></td>
<td>• ConnectionToken is NULL.</td>
</tr>
<tr>
<td></td>
<td>• ConnectionToken-&gt;CompletionToken.Event is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The driver can’t allocate enough resource to initiate the active open.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
</tbody>
</table>

28.2.8 EFI_TCP6_PROTOCOL.Accept()

Summary
Listen on the passive instance to accept an incoming connection request. This is a nonblocking operation.

Prototype

typedef
EFI_STATUS
(EIFIAPIC *EFI_TCP6_ACCEPT) (    IN EFI_TCP6_PROTOCOL    *This,
 IN EFI_TCP6_LISTEN_TOKEN *ListenToken    );

Parameters
This
Pointer to the EFI_TCP6_PROTOCOL instance.

ListenToken
Pointer to the listen token to return when operation finishes. Type EFI_TCP6_LISTEN_TOKEN is defined in Related Definition below.

Related Definition

```c
//**************************************************************************
// EFI_TCP6_LISTEN_TOKEN
//**************************************************************************
typedef struct {
    EFI_TCP6_COMPLETION_TOKEN CompletionToken;
    EFI_HANDLE NewChildHandle;
} EFI_TCP6_LISTEN_TOKEN;
```

Status
The Status in CompletionToken will be set to the following value if accept finishes:
**EFI_SUCCESS**: A remote peer has successfully established a connection to this instance. A new TCP instance has also been created for the connection.

**EFI_CONNECTION_RESET**: The accept fails because the connection is reset either by instance itself or communication peer.

**EFI_ABORTED**: The accept request has been aborted.

**EFI_SECURITY_VIOLATION**: The accept operation was failed because of IPSec policy check.

**NewChildHandle**

The new TCP instance handle created for the established connection.

**Description**

The `Accept()` function initiates an asynchronous accept request to wait for an incoming connection on the passive TCP instance. If a remote peer successfully establishes a connection with this instance, a new TCP instance will be created and its handle will be returned in `ListenToken->NewChildHandle`. The newly created instance is configured by inheriting the passive instance’s configuration and is ready for use upon return. The new instance is in the `Tcp6StateEstablished` state.

The `ListenToken->CompletionToken.Event` will be signaled when a new connection is accepted, user aborts the listen or connection is reset.

This function only can be called when current TCP instance is in `Tcp6StateListen` state.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>The listen token has been queued successfully.</td>
</tr>
<tr>
<td><strong>EFI_NOT_STARTED</strong></td>
<td>This EFI TCPv6 Protocol instance has not been configured.</td>
</tr>
<tr>
<td><strong>EFI_ACCESS_DENIED</strong></td>
<td>One or more of the following are <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• This instance is not a passive instance.</td>
</tr>
<tr>
<td></td>
<td>• This instance is not in <code>Tcp6StateListen</code> state.</td>
</tr>
<tr>
<td></td>
<td>• The same listen token has already existed in the listen token queue of this TCP instance.</td>
</tr>
<tr>
<td><strong>EFI_INVALID_PARAMETER</strong></td>
<td>One or more of the following are <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• <code>ListenToken</code> is NULL.</td>
</tr>
<tr>
<td></td>
<td>• <code>ListenToken-&gt;CompletionToken.Event</code> is NULL.</td>
</tr>
<tr>
<td><strong>EFI_OUT_OF_RESOURCES</strong></td>
<td>Could not allocate enough resource to finish the operation.</td>
</tr>
<tr>
<td><strong>EFI_DEVICE_ERROR</strong></td>
<td>Any unexpected and not belonged to above category error.</td>
</tr>
</tbody>
</table>
28.2.9 EFI_TCP6_PROTOCOL.Transmit()

Summary
Queues outgoing data into the transmit queue.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_TCP6_TRANSMIT) (
  IN EFI_TCP6_PROTOCOL *This,
  IN EFI_TCP6_IO_TOKEN *Token
);
```

Parameters

This
Pointer to the EFI_TCP6_PROTOCOL instance.

Token
Pointer to the completion token to queue to the transmit queue. Type EFI_TCP6_IO_TOKEN is defined in “Related Definitions” below.

Description

The Transmit() function queues a sending request to this TCP instance along with the user data. The status of the token is updated and the event in the token will be signaled once the data is sent out or some error occurs.

Related Definition

```c
//**********************************************************
// EFI_TCP6_IO_TOKEN
//**********************************************************
typedef struct {
  EFI_TCP6_COMPLETION_TOKEN CompletionToken;
  union {
    EFI_TCP6_RECEIVE_DATA *RxData;
    EFI_TCP6_TRANSMIT_DATA *TxData;
  } Packet;
} EFI_TCP6_IO_TOKEN;
```

Status

When transmission finishes or meets any unexpected error it will be set to one of the following values:

- **EFI_SUCCESS**: The receiving or transmission operation completes successfully.
- **EFI_CONNECTION_FIN**: The receiving operation fails because the communication peer has closed the connection and there is no more data in the receive buffer of the instance.
- **EFI_CONNECTION_RESET**: The receiving or transmission operation fails because this connection is reset either by instance itself or the communication peer.
- **EFI_ABORTED**: The receiving or transmission is aborted.
- **EFI_TIMEOUT**: The transmission timer expires and no more specific information is available.
**EFI_NETWORK_UNREACHABLE**: The transmission fails because an ICMP network unreachable error is received.

**EFI_HOST_UNREACHABLE**: The transmission fails because an ICMP host unreachable error is received.

**EFI_PROTOCOL_UNREACHABLE**: The transmission fails because an ICMP protocol unreachable error is received.

**EFI_PORT_UNREACHABLE**: The transmission fails and an ICMP port unreachable error is received.

**EFI_ICMP_ERROR**: The transmission fails and some other ICMP error is received.

**EFI_DEVICE_ERROR**: An unexpected system or network error occurs.

**EFI_SECURITY_VIOLATION**: The receiving or transmission operation was failed because of IPSec policy check.

### RxData
When this token is used for receiving, RxData is a pointer to `EFI_TCP6_RECEIVE_DATA`. Type `EFI_TCP6_RECEIVE_DATA` is defined below.

### TxData
When this token is used for transmitting, TxData is a pointer to `EFI_TCP6_TRANSMIT_DATA`. Type `EFI_TCP6_TRANSMIT_DATA` is defined below.

The `EFI_TCP6_IO_TOKEN` structure is used for both transmit and receive operations.

When used for transmitting, the CompletionToken.Event and TxData fields must be filled in by the user. After the transmit operation completes, the CompletionToken.Status field is updated by the instance and the Event is signaled.

When used for receiving, the CompletionToken.Event and RxData fields must be filled in by the user. After a receive operation completes, RxData and Status are updated by the instance and the Event is signaled.

```c
typedef struct {
    BOOLEAN UrgentFlag;
    UINT32 DataLength;
    UINT32 FragmentCount;
    EFI_TCP6_FRAGMENT_DATA FragmentTable[1];
} EFI_TCP6_RECEIVE_DATA;
```

**UrgentFlag**
Whether the data is urgent. When this flag is set, the instance is in urgent mode. The implementations of this specification should follow RFC793 to process urgent data, and should NOT mix the data across the urgent point in one token.

**DataLength**
When calling `Receive()` function, it is the byte counts of all `Fragmentbuffer` in `FragmentTable` allocated by user. When the token is signaled by TCPv6 driver it is the length of received data in the fragments.

**FragmentCount**
Number of fragments.

**FragmentTable**
An array of fragment descriptors. Type `EFI_TCP6_FRAGMENT_DATA` is defined below.

When TCPv6 driver wants to deliver received data to the application, it will pick up the first queued receiving token, update its `Token->Packet.RxData` then signal the `Token->CompletionToken.Event`.

The `FragmentBuffer` in `FragmentTable` is allocated by the application when calling `Receive()` function and received data will be copied to those buffers by the driver. `FragmentTable` may contain multiple buffers that are NOT in the

---

28.2. EFI TCPv6 Protocol 1196
continuous memory locations. The application should combine those buffers in the FragmentTable to process data if necessary.

```c
typedef struct {
    UINT32 FragmentLength;
    VOID *FragmentBuffer;
} EFI_TCP6_FRAGMENT_DATA;
```

**FragmentLength**
Length of data buffer in the fragment.

**FragmentBuffer**
Pointer to the data buffer in the fragment. `EFI_TCP6_FRAGMENT_DATA` allows multiple receive or transmit buffers to be specified. The purpose of this structure is to provide scattered read and write.

```c
typedef struct {
    BOOLEAN Push;
    BOOLEAN Urgent;
    UINT32 DataLength;
    UINT32 FragmentCount;
    EFI_TCP6_FRAGMENT_DATA FragmentTable[1];
} EFI_TCP6_TRANSMIT_DATA;
```

**Push**
If `TRUE`, data must be transmitted promptly, and the PUSH bit in the last TCP segment created will be set. If `FALSE`, data transmission may be delayed to combine with data from subsequent `Transmit()`s for efficiency.

**Urgent**
The data in the fragment table are urgent and urgent point is in effect if `TRUE`. Otherwise those data are NOT considered urgent.

**DataLength**
Length of the data in the fragments.

**FragmentCount**
Number of fragments.

**FragmentTable**
An array of fragment descriptors. Type `EFI_TCP6_FRAGMENT_DATA` is defined above.

The EFI TCPv6 Protocol user must fill this data structure before sending a packet. The packet may contain multiple buffers in non-continuous memory locations.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data has been queued for transmission.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI TCPv6 Protocol instance has not been configured.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The underlying IPv6 driver was responsible for choosing a source address for this instance, but no source address was available for use.</td>
</tr>
</tbody>
</table>
Table 28.15 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;CompletionToken.Event is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;Packet.TxData is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;Packet.FragmentCount is zero.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;Packet.DataLength is not equal to the sum of fragment lengths.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>One or more of the following conditions are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• A transmit completion token with the same Token-&gt;CompletionToken.Event was already in the transmission queue.</td>
</tr>
<tr>
<td></td>
<td>• The current instance is in Tcp6StateClosed state.</td>
</tr>
<tr>
<td></td>
<td>• The current instance is a passive one and it is in Tcp6StateListen state.</td>
</tr>
<tr>
<td></td>
<td>• User has called Close() to disconnect this connection.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The completion token could not be queued because the transmit queue is full.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not queue the transmit data because of resource shortage.</td>
</tr>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>There is no route to the destination network or address.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

28.2.10 EFI_TCP6_PROTOCOL.Receive()

Summary
Places an asynchronous receive request into the receiving queue.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_TCP6_RECEIVE) (  
    IN EFI_TCP6_PROTOCOL *This,  
    IN EFI_TCP6_IO_TOKEN *Token  
);
```

Parameters

This

Pointer to the EFI_TCP6_PROTOCOL instance.

Token

Pointer to a token that is associated with the receive data descriptor. Type EFI_TCP6_IO_TOKEN is defined in EFI_TCP6_PROTOCOL.Transmit().

Description

The Receive() function places a completion token into the receive packet queue. This function is always asynchronous. The caller must allocate the Token->CompletionToken.Event and the FragmentBuffer used to receive data. The caller also must fill the DataLength which represents the whole length of all FragmentBuffer. When the receive operation completes, the EFI TCPv6 Protocol driver updates the Token->CompletionToken.Status and Token->Packet.RxData.
fields and the `Token->CompletionToken.Event` is signaled. If got data the data and its length will be copied into the `FragmentTable`, at the same time the full length of received data will be recorded in the `DataLength` fields. Providing a proper notification function and context for the event will enable the user to receive the notification and receiving status. That notification function is guaranteed to not be re-entered.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The receive completion token was cached.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI TCPv6 Protocol instance has not been configured.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The underlying IPv6 driver was responsible for choosing a source address for this instance, but no source address was available for use.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;CompletionToken.Event is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;Packet.RxData is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token-&gt;Packet.RxData-&gt;DataLength is 0.</td>
</tr>
<tr>
<td></td>
<td>• The Token-&gt;Packet.RxData-&gt;DataLength is not the sum of all FragmentBuffer length in FragmentTable.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The receive completion token could not be queued due to a lack of system resources (usually memory).</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The EFI TCPv6 Protocol instance has been reset to startup defaults.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• A receive completion token with the same <code>Token-&gt;CompletionToken.Event</code> was already in the receive queue.</td>
</tr>
<tr>
<td></td>
<td>• The current instance is in Tcp6StateClosed state.</td>
</tr>
<tr>
<td></td>
<td>• The current instance is a passive one and it is in Tcp6StateListen state.</td>
</tr>
<tr>
<td></td>
<td>• User has called <code>Close()</code> to disconnect this connection.</td>
</tr>
<tr>
<td>EFI_CONNECTION_FIN</td>
<td>The communication peer has closed the connection and there is no any buffered data in the receive buffer of this instance.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The receive request could not be queued because the receive queue is full.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

### 28.2.11 EFI_TCP6_PROTOCOL.Close()

**Summary**

Disconnecting a TCP connection gracefully or reset a TCP connection. This function is a nonblocking operation.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_TCP6_CLOSE)(
    IN EFI_TCP6_PROTOCOL *This,
    IN EFI_TCP6_CLOSE_TOKEN *CloseToken
);
```
Parameters

This

Pointer to the EFI_TCP6_PROTOCOL instance.

CloseToken

Pointer to the close token to return when operation finishes. Type EFI_TCP6_CLOSE_TOKEN is defined in Related Definition below.

Related Definition

```c
//************************************************
// EFI_TCP6_CLOSE_TOKEN
//************************************************
typedef struct {
    EFI_TCP6_COMPLETION_TOKEN CompletionToken;
    BOOLEAN AbortOnClose;
} EFI_TCP6_CLOSE_TOKEN;
```

Status

When close finishes or meets any unexpected error it will be set to one of the following values:

**EFI_SUCCESS**: The close operation completes successfully.

**EFI_ABORTED**: User called configure with NULL without close stopping.

**EFI_SECURITY_VIOLATION**: The close operation was failed because of IPSec policy check

AbortOnClose

Abort the TCP connection on close instead of the standard TCP close process when it is set to TRUE. This option can be used to satisfy a fast disconnect.

Description

Initiate an asynchronous close token to TCP driver. After Close() is called, any buffered transmission data will be sent by TCP driver and the current instance will have a graceful close working flow described as RFC 793 if AbortOnClose is set to FALSE, otherwise, a rest packet will be sent by TCP driver to fast disconnect this connection. When the close operation completes successfully the TCP instance is in Tcp6StateClosed state, all pending asynchronous operations are signaled and any buffers used for TCP network traffic are flushed.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Close() is called successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI TCPv6 Protocol instance has not been configured.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>One or more of the following conditions are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• CloseToken or CloseToken-&gt;CompletionToken.Event is already in use.</td>
</tr>
<tr>
<td></td>
<td>• Previous Close() call on this instance has not finished.</td>
</tr>
</tbody>
</table>

continues on next page
Table 28.17 – continued from previous page

| EFI_INVALID_PARAMETER | One or more of the following conditions are TRUE:  
|                      | • This is NULL.  
|                      | • CloseToken is NULL.  
|                      | • CloseToken->CompletionToken.Event is NULL. |
| EFI_OUT_OF_RESOURCES | Could not allocate enough resource to finish the operation. |
| EFI_DEVICE_ERROR     | Any unexpected and not belonged to above category error. |

28.2.12 EFI_TCP6_PROTOCOL.Cancel()

Summary
Abort an asynchronous connection, listen, transmission or receive request.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_TCP6_CANCEL)(
    IN EFI_TCP6_PROTOCOL *This,
    IN EFI_TCP6_COMPLETION_TOKEN *Token OPTIONAL
);
```

Parameters

This
Pointer to the EFI_TCP6_PROTOCOL instance.

Token
Pointer to a token that has been issued by

- EFI_TCP6_PROTOCOL.Connect(),
- EFI_TCP6_PROTOCOL.Accept(),
- EFI_TCP6_PROTOCOL.Transmit() or
- EFI_TCP6_PROTOCOL.Receive(). If NULL, all pending tokens issued by above four functions will be aborted. Type

```c
EFI_TCP6_COMPLETION_TOKEN
```

is defined in

- EFI_TCP6_PROTOCOL.Connect().

Description
The Cancel() function aborts a pending connection, listen, transmit or receive request. If Token is not NULL and the token is in the connection, listen, transmission or receive queue when it is being cancelled, its Token->Status will be set to EFI_ABORTED and then Token->Event will be signaled. If the token is not in one of the queues, which usually means that the asynchronous operation has completed, EFI_NOT_FOUND is returned. If Token is NULL all asynchronous token issued by Connect(), Accept(), Transmit() and Receive() will be aborted.

Status Codes Returned
### 28.2.13 EFI_TCP6_PROTOCOL.Poll()

**Summary**

Poll to receive incoming data and transmit outgoing segments.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_TCP6_POLL) (
    IN EFI_TCP6_PROTOCOL *This
);
```

**Parameters**

*This*

Pointer to the *EFI_TCP6_PROTOCOL* instance.

**Description**

The `Poll()` function increases the rate that data is moved between the network and application and can be called when the TCP instance is created successfully. Its use is optional.

In some implementations, the periodical timer in the MNP driver may not poll the underlying communications device fast enough to avoid drop packets. Drivers and applications that are experiencing packet loss should try calling the `Poll()` function in a high frequency.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This instance hasn’t been configured.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The asynchronous I/O request isn’t found in the transmission or receive queue.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation does not support this function.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>No incoming or outgoing data is processed.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Data was dropped out of the transmission or receive queue. Consider increasing the polling rate.</td>
</tr>
</tbody>
</table>

### 28.3 EFI IPv4 Protocol

This section defines the EFI IPv4 (Internet Protocol version 4) Protocol interface. It is split into the following three main sections:

- EFI IPv4 Service Binding Protocol
- EFI IPv4 Variable
- EFI IPv4 Protocol
The EFI IPv4 Protocol provides basic network IPv4 packet I/O services, which includes support for a subset of the Internet Control Message Protocol (ICMP) and may include support for the Internet Group Management Protocol (IGMP).

The EFI IPv4 Protocol supports IPv4 classless IP addressing, and deprecates the original IPv4 classful IP addressing. Please see links to the following RFC documents at http://uefi.org/uefi:

1. RFC 1122 — “Requirements for Internet Hosts – Communication Layers”,**
2. RFC 4632 — “Classless Inter-domain Routing (CIDR): The Internet Address Assignment and Aggregation Plan”,
3. RFC 3021 — “Using 31-Bit Prefixes on IPv4 Point-to-Point Links”

28.3.1 IP4 Service Binding Protocol

28.3.2 EFI_IP4_SERVICE_BINDING_PROTOCOL

Summary

The EFI IPv4 Service Binding Protocol is used to locate communication devices that are supported by an EFI IPv4 Protocol driver and to create and destroy instances of the EFI IPv4 Protocol child protocol driver that can use the underlying communications device.

GUID

```c
#define EFI_IP4_SERVICE_BINDING_PROTOCOL_GUID \
    {0xc51711e7,0xb4bf,0x404a,\ 
    {0xbf,0xb8,0x0a,0x04,0xe8,0xf1,0xff,0xe4}}
```

Description

A network application that requires basic IPv4 I/O services can use one of the protocol handler services, such as BS->LocateHandleBuffer(), to search for devices that publish an EFI IPv4 Service Binding Protocol GUID. Each device with a published EFI IPv4 Service Binding Protocol GUID supports the EFI IPv4 Protocol and may be available for use.

After a successful call to the EFI_IP4_SERVICE_BINDING_PROTOCOL.CreateChild() function, the newly created child EFI IPv4 Protocol driver is in an unconfigured state; it is not ready to send and receive data packets.

Before a network application terminates execution, every successful call to the EFI_IP4_SERVICE_BINDING_PROTOCOL.CreateChild() function must be matched with a call to the EFI_IP4_SERVICE_BINDING_PROTOCOL.DestroyChild() function.

28.3.3 IP4 Protocol

28.3.4 EFI_IP4_PROTOCOL

Summary

The EFI IPv4 Protocol implements a simple packet-oriented interface that can be used by drivers, daemons, and applications to transmit and receive network packets.

GUID

```c
#define EFI_IP4_PROTOCOL_GUID \
    {0x41d94cd2,0x35b6,0x455a,\ 
    {0x82,0x58,0xd4,0xe5,0x13,0x34,0xaa,0xdd}}
```
Protocol Interface Structure

typedef struct _EFI_IP4_PROTOCOL {
    EFI_IP4_GET_MODE_DATA GetModeData;
    EFI_IP4_CONFIGURE Configure;
    EFI_IP4_GROUPS Groups;
    EFI_IP4/routes Routes;
    EFI_IP4_TRANSMIT Transmit;
    EFI_IP4_RECEIVE Receive;
    EFI_IP4Cancelar Cancel;
    EFI_IP4_poll Poll;
} EFI_IP4_PROTOCOL;

Parameters

GetModeData
Get the current operational settings for this instance of the EFI IPv4 Protocol driver. See the GetModeData() function description.

Configure
Changes or resets the operational settings for the EFI IPv4 Protocol. See the Configure() function description.

Groups
Joins and leaves multicast groups. See the Groups() function description.

Routes
Adds and deletes routing table entries. See the Routes() function description.

Transmit
Places outgoing data packets into the transmit queue. See the Transmit() function description.

Receive
Places a receiving request into the receiving queue. See the Receive() function description.

Cancel
Aborts a pending transmit or receive request. See the Cancel() function description.

Poll
Polls for incoming data packets and processes outgoing data packets. See the Poll() function description.

Description

The EFI_IP4_PROTOCOL defines a set of simple IPv4, ICMPv4, and IGMPv4 services that can be used by any network protocol driver, daemon, or application to transmit and receive IPv4 data packets.

NOTE: All the IPv4 addresses that are described in EFI_IP4_PROTOCOL are stored in network byte order. Both incoming and outgoing IP packets are also in network byte order. All other parameters that are defined in functions or data structures are stored in host byte order.

28.3.5 EFI_IP4_PROTOCOL.GetModeData()

Summary
Gets the current operational settings for this instance of the EFI IPv4 Protocol driver.

Prototype

typedef
EFI_STATUS

(continues on next page)
(EFIAPI *EFI_IP4_GET_MODE_DATA) (  
  IN EFI_IP4_PROTOCOL *This,  
  OUT EFI_IP4_MODE_DATA *Ip4ModeData OPTIONAL,  
  OUT EFI_MANAGED_NETWORK_CONFIG_DATA *MnpConfigData OPTIONAL,  
  OUT EFI_SIMPLE_NETWORK_MODE *SnpModeData OPTIONAL  
);  

Parameters  

This  
  Pointer to the EFI_IP4_PROTOCOL instance.  

Ip4ModeData  
  Pointer to the EFI IPv4 Protocol mode data structure. Type EFI_IP4_MODE_DATA is defined in “Related Definitions” below.  

MnpConfigData  
  Pointer to the managed network configuration data structure. Type EFI_MANAGED_NETWORK_CONFIG_DATA is defined in EFI_MANAGED_NETWORK_PROTOCOL.GetModeData().  

SnpData  
  Pointer to the simple network mode data structure. Type EFI_SIMPLE_NETWORK_MODE is defined in the EFI_SIMPLE_NETWORK_PROTOCOL.  

Description  

The GetModeData() function returns the current operational mode data for this driver instance. The data fields in EFI_IP4_MODE_DATA are read only. This function is used optionally to retrieve the operational mode data of underlying networks or drivers.  

Related Definition  

//******************************************************  
// EFI_IP4_MODE_DATA  
//*****************************************************************************/  
typedef struct {  
  BOOLEAN IsStarted;  
  UINT32 MaxPacketSize;  
  EFI_IP4_CONFIG_DATA ConfigData;  
  BOOLEAN IsConfigured;  
  UINT32 GroupCount;  
  EFI_IPv4_ADDRESS *GroupTable;  
  UINT32 RouteCount;  
  EFI_IP4_ROUTE_TABLE RouteTable;  
  UINT32 IcmpTypeCount;  
  EFI_IP4_ICMP_TYPE *IcmpTypeList;  
  EFI_IP4_MODE_DATA;  
} EFI_IP4_MODE_DATA;  

IsStarted  
  Set to TRUE after this EFI IPv4 Protocol instance has been successfully configured with operational parameters by calling the Configure() interface when EFI IPv4 Protocol instance is stopped. All other fields in this structure are undefined until this field is TRUE.  
  
  Set to FALSE when the instance's operational parameter has been reset.  

MaxPackeSize  
  The maximum packet size, in bytes, of the packet which the upper layer driver could feed.
ConfigData
Current configuration settings. Undefined until IsStarted is TRUE. Type EFI_IP4_CONFIG_DATA is defined below.

IsConfigured
Set to TRUE when the EFI IPv4 Protocol instance has a station address and subnet mask. If it is using the default address, the default address has been acquired.

Set to FALSE when the EFI IPv4 Protocol driver is not configured.

GroupCount
Number of joined multicast groups. Undefined until IsConfigured is TRUE.

GroupTable
List of joined multicast group addresses. Undefined until IsConfigured is TRUE.

RouteCount
Number of entries in the routing table. Undefined until IsConfigured is TRUE.

RouteTable
Routing table entries. Undefined until IsConfigured is TRUE. Type EFI_IP4_ROUTE_TABLE is defined below.

IcmpTypeCount
Number of entries in the supported ICMP types list.

IcmpTypeList
Array of ICMP types and codes that are supported by this EFI IPv4 Protocol driver. Type EFI_IP4_ICMP_TYPE is defined below.

The EFI_IP4_MODE_DATA structure describes the operational state of this IPv4 interface.

```
// **********************************************
// EFI_IP4_CONFIG_DATA
// **********************************************
typedef struct {
  UINT8 DefaultProtocol;
  BOOLEAN AcceptAnyProtocol;
  BOOLEAN AcceptIcmpErrors;
  BOOLEAN AcceptBroadcast;
  BOOLEAN AcceptPromiscuous;
  BOOLEAN UseDefaultAddress;
  EFI_IPv4_ADDRESS StationAddress;
  EFI_IPv4_ADDRESS SubnetMask;
  UINT8 TypeOfService;
  UINT8 TimeToLive;
  BOOLEAN DoNotFragment;
  BOOLEAN RawData;
  UINT32 ReceiveTimeout;
  UINT32 TransmitTimeout;
} EFI_IP4_CONFIG_DATA;
```

DefaultProtocol
The default IPv4 protocol packets to send and receive. Ignored when AcceptPromiscuous is TRUE. An updated list of protocol numbers can be found at “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “IANA Assigned Internet Protocol Numbers list”.

AcceptAnyProtocol
Set to TRUE to receive all IPv4 packets that get through the receive filters. Set to FALSE to receive only the DefaultProtocol IPv4 packets that get through the receive filters. Ignored when AcceptPromiscuous is TRUE.
AcceptIcmpErrors
Set to TRUE to receive ICMP error report packets. Ignored when AcceptPromiscuous or AcceptAnyProtocol is TRUE.

AcceptBroadcast
Set to TRUE to receive broadcast IPv4 packets. Ignored when AcceptPromiscuous is TRUE. Set to FALSE to stop receiving broadcast IPv4 packets.

AcceptPromiscuous
Set to TRUE to receive all IPv4 packets that are sent to any hardware address or any protocol address. Set to FALSE to stop receiving all promiscuous IPv4 packets.

UseDefaultAddress
Set to TRUE to use the default IPv4 address and default routing table. If the default IPv4 address is not available yet, then the EFI IPv4 Protocol driver will use EFI_IP4_CONFIG2_PROTOCOL to retrieve the IPv4 address and subnet information. (This field can be set and changed only when the EFI IPv4 driver is transitioning from the stopped to the started states.)

StationAddress
The station IPv4 address that will be assigned to this EFI IPv4 Protocol instance. The EFI IPv4 Protocol driver will deliver only incoming IPv4 packets whose destination matches this IPv4 address exactly. Address 0.0.0.0 is also accepted as a special case in which incoming packets destined to any station IP address are always delivered. When EFI_IP4_CONFIG_DATA is used in Configure(), it is ignored if UseDefaultAddress is TRUE; When EFI_IP4_CONFIG_DATA is used in GetModeData(), it contains the default address if UseDefaultAddress is TRUE and the default address has been acquired.

SubnetMask
The subnet address mask that is associated with the station address. When EFI_IP4_CONFIG_DATA is used in Configure(), it is ignored if UseDefaultAddress is TRUE; When EFI_IP4_CONFIG_DATA is used in GetModeData(), it contains the default subnet mask if UseDefaultAddress is TRUE and the default address has been acquired.

TypeOfService
TypeOfService field in transmitted IPv4 packets.

TimeToLive
TimeToLive field in transmitted IPv4 packets.

DoNotFragment
State of the DoNotFragment bit in transmitted IPv4 packets.

RawData
Set to TRUE to send and receive unformatted packets. The other IPv4 receive filters are still applied. Fragmentation is disabled for RawData mode. NOTE: Unformatted packets include the IP header and payload. The media header is appended automatically for outgoing packets by underlying network drivers.

ReceiveTimeout
The timer timeout value (number of microseconds) for the receive timeout event to be associated with each assembled packet. Zero means do not drop assembled packets.

TransmitTimeout
The timer timeout value (number of microseconds) for the transmit timeout event to be associated with each outgoing packet. Zero means do not drop outgoing packets.

The EFI_IP4_CONFIG_DATA structure is used to report and change IPv4 session parameters.

//**********************************************
// EFI_IP4_ROUTE_TABLE
//**********************************************

(continues on next page)
typedef struct {
    EFI_IPv4_ADDRESS SubnetAddress;
    EFI_IPv4_ADDRESS SubnetMask;
    EFI_IPv4_ADDRESS GatewayAddress;
} EFI_IP4_ROUTE_TABLE;

SubnetAddress
The subnet address to be routed.

SubnetMask
The subnet mask. If (DestinationAddress & SubnetMask == SubnetAddress), then the packet is to be directed to the GatewayAddress.

GatewayAddress
The IPv4 address of the gateway that redirects packets to this subnet. If the IPv4 address is 0.0.0.0, then packets to this subnet are not redirected.

EFI_IP4_ROUTE_TABLE is the entry structure that is used in routing tables.

//******************************************************
// EFI_IP4_ICMP_TYPE
//******************************************************
typedef struct {
    UINT8 Type;
    UINT8 Code;
} EFI_IP4_ICMP_TYPE

Type
The type of ICMP message. See RFC 792 and RFC 950.

Code
The code of the ICMP message, which further describes the different ICMP message formats under the same Type. See RFC 792 and RFC 950.

EFI_IP4_ICMP_TYPE is used to describe those ICMP messages that are supported by this EFI IPv4 Protocol driver.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The required mode data could not be allocated.</td>
</tr>
</tbody>
</table>

28.3.6 EFI_IP4_PROTOCOL.Configure()

Summary
Assigns an IPv4 address and subnet mask to this EFI IPv4 Protocol driver instance.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_IP4_CONFIGURE) ( 
    IN EFI_IP4_PROTOCOL *This,
IN EFI_IP4_CONFIG_DATA *IpConfigData OPTIONAL
);

Parameters

This

Pointer to the EFI_IP4_PROTOCOL instance.

IpConfigData

Pointer to the EFI IPv4 Protocol configuration data structure. Type EFI_IP4_CONFIG_DATA is defined in EFI_IP4_PROTOCOL.GetModeData().

Description

The Configure() function is used to set, change, or reset the operational parameters and filter settings for this EFI IPv4 Protocol instance. Until these parameters have been set, no network traffic can be sent or received by this instance. Once the parameters have been reset (by calling this function with IpConfigData set to NULL), no more traffic can be sent or received until these parameters have been set again. Each EFI IPv4 Protocol instance can be started and stopped independently of each other by enabling or disabling their receive filter settings with the Configure() function.

When IpConfigData.UseDefaultAddress is set to FALSE, the new station address will be appended as an alias address into the addresses list in the EFI IPv4 Protocol driver. While set to TRUE, Configure() will trigger the EFI_IP4_CONFIG2_PROTOCOL to retrieve the default IPv4 address if it is not available yet. Clients could frequently call GetModeData() to check the status to ensure that the default IPv4 address is ready.

If operational parameters are reset or changed, any pending transmit and receive requests will be cancelled. Their completion token status will be set to EFI_ABORTED and their events will be signaled.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The driver instance was successfully opened.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_IP_ADDRESS_CONFLICT</td>
<td>There is an address conflict in response to the Arp invocation</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• IpConfigData.StationAddress is not a unicast IPv4 address.</td>
</tr>
<tr>
<td></td>
<td>• IpConfigData.SubnetMask is not a valid IPv4 subnet mask.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• A configuration protocol (DHCP, BOOTP, RARP, etc.) could not be located when clients choose to use the default IPv4 address. This EFI IPv4 Protocol implementation does not support this requested filter or timeout setting.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The EFI IPv4 Protocol driver instance data could not be allocated.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The interface is already open and must be stopped before the IPv4 address or subnet mask can be changed. The interface must also be stopped when switching to/from raw packet mode.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The EFI IPv4 Protocol driver instance is not opened.</td>
</tr>
</tbody>
</table>
28.3.7 EFI_IP4_PROTOCOL.Groups()

Summary
Joins and leaves multicast groups.

Prototype

```c
typedef
EFI_STATUS
(EFIAPIC *EFI_IP4_GROUPS) (  
    IN EFI_IP4_PROTOCOL  *This,
    IN BOOLEAN  JoinFlag,
    IN EFI_IPv4_ADDRESS  *GroupAddress OPTIONAL
);
```

Parameters

This
Pointer to the EFI_IP4_PROTOCOL instance.

JoinFlag
Set to TRUE to join the multicast group session and FALSE to leave.

GroupAddress
Pointer to the IPv4 multicast address.

Description

The Groups() function is used to join and leave multicast group sessions. Joining a group will enable reception of matching multicast packets. Leaving a group will disable the multicast packet reception.

If JoinFlag is FALSE and GroupAddress is NULL, all joined groups will be left.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• JoinFlag is TRUE and GroupAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>• GroupAddress is not NULL and ** GroupAddress* is not a multicast IPv4 address.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>System resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This EFI IPv4 Protocol implementation does not support multicast groups.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The group address is already in the group table (when JoinFlag is TRUE ).</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The group address is not in the group table (when JoinFlag is FALSE ).</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
</tbody>
</table>
28.3.8 EFI_IP4_PROTOCOL::Routes()

Summary
Adds and deletes routing table entries.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_IP4_ROUTES) (
    IN EFI_IP4_PROTOCOL *This,
    IN BOOLEAN DeleteRoute,
    IN EFI_IPv4_ADDRESS *SubnetAddress,
    IN EFI_IPv4_ADDRESS *SubnetMask,
    IN EFI_IPv4_ADDRESS *GatewayAddress
);
```

Parameters

**This**
Pointer to the EFI_IP4_PROTOCOL instance.

**DeleteRoute**
Set to TRUE to delete this route from the routing table. Set to FALSE to add this route to the routing table. SubnetAddress and SubnetMask are used as the key to each route entry.

**SubnetAddress**
The address of the subnet that needs to be routed.

**SubnetMask**
The subnet mask of SubnetAddress.

**GatewayAddress**
The unicast gateway IPv4 address for this route.

Description

The Routes() function adds a route to or deletes a route from the routing table.

Routes are determined by comparing the SubnetAddress with the destination IPv4 address arithmetically AND-ed with the SubnetMask. The gateway address must be on the same subnet as the configured station address.

The default route is added with SubnetAddress and SubnetMask both set to 0.0.0.0. The default route matches all destination IPv4 addresses that do not match any other routes.

A GatewayAddress that is zero is a nonroute. Packets are sent to the destination IP address if it can be found in the ARP cache or on the local subnet. One automatic nonroute entry will be inserted into the routing table for outgoing packets that are addressed to a local subnet (gateway address of 0.0.0.0).

Each EFI IPv4 Protocol instance has its own independent routing table. Those EFI IPv4 Protocol instances that use the default IPv4 address will also have copies of the routing table that was provided by the EFI_IP4_CONFIG2_PROTOCOL, and these copies will be updated whenever the EIF IPv4 Protocol driver reconfigures its instances. As a result, client modification to the routing table will be lost.

**NOTE:** There is no way to set up routes to other network interface cards because each network interface card has its own independent network stack that shares information only through EFI IPv4 variable.

Status Codes Returned
<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The driver instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• SubnetAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>• SubnetMask is NULL.</td>
</tr>
<tr>
<td></td>
<td>• GatewayAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>• * SubnetAddress is not a valid subnet address.</td>
</tr>
<tr>
<td></td>
<td>• * SubnetMask is not a valid subnet mask.</td>
</tr>
<tr>
<td></td>
<td>• * GatewayAddress is not a valid unicast IPv4 address.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not add the entry to the routing table.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>This route is not in the routing table (when DeleteRoute is TRUE).</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The route is already defined in the routing table (when DeleteRoute is FALSE).</td>
</tr>
</tbody>
</table>

### 28.3.9 EFI_IP4_PROTOCOL.Transmit()

#### Summary
Places outgoing data packets into the transmit queue.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_IP4_TRANSMIT) (  
  IN EFI_IP4_PROTOCOL *This,  
  IN EFI_IP4_COMPLETION_TOKEN *Token  
);
```

#### Parameters

**This**

Pointer to the `EFI_IP4_PROTOCOL` instance.

**Token**

Pointer to the transmit token. Type `EFI_IP4_COMPLETION_TOKEN` is defined in “Related Definitions” below.

#### Description

The `Transmit()` function places a sending request in the transmit queue of this EFI IPv4 Protocol instance. Whenever the packet in the token is sent out or some errors occur, the event in the token will be signaled and the status is updated.

#### Related Definition

```c
//EFI_IP4_PROTOCOL
//EFI_IP4_COMPLETION_TOKEN
typedef struct {  
  EFI_EVENT Event;
};
```

(continues on next page)
Event

This Event will be signaled after the Status field is updated by the EFI IPv4 Protocol driver. The type of Event must be EFI_NOTIFY_SIGNAL. The Task Priority Level (TPL) of Event must be lower than or equal to TPL_CALLBACK.

Status

Will be set to one of the following values:

- **EFI_SUCCESS.** The receive or transmit completed successfully.
- **EFI_ABORTED.** The receive or transmit was aborted.
- **EFI_TIMEOUT.** The transmit timeout expired.
- **EFI_ICMP_ERROR.** An ICMP error packet was received.
- **EFIDEVICEERROR.** An unexpected system or network error occurred.
- **EFI_NO_MEDIA.** There was a media error

RxData

When this token is used for receiving, RxData is a pointer to the EFI_IP4_RECEIVE_DATA. Type EFI_IP4_RECEIVE_DATA is defined below.

TxData

When this token is used for transmitting, TxData is a pointer to the EFI_IP4_TRANSMIT_DATA. Type EFI_IP4_TRANSMIT_DATA is defined below.

EFI_IP4_COMPLETION_TOKEN structures are used for both transmit and receive operations.

When the structure is used for transmitting, the Event and TxData fields must be filled in by the EFI IPv4 Protocol client. After the transmit operation completes, EFI IPv4 Protocol updates the Status field and the Event is signaled.

When the structure is used for receiving, only the Event field must be filled in by the EFI IPv4 Protocol client. After a packet is received, the EFI IPv4 Protocol fills in the RxData and Status fields and the Event is signaled. If the packet is an ICMP error message, the Status is set to EFI_ICMP_ERROR, and the packet is delivered up as usual. The protocol from the IP head in the ICMP error message is used to de-multiplex the packet.

```c
typedef struct {
    EFI_STATUS Status;
    union {
        EFI_IP4_RECEIVE_DATA *RxData;
        EFI_IP4_TRANSMIT_DATA *TxData;
        } Packet;
    } EFI_IP4_COMPLETION_TOKEN;
```
 EFI_TIME     \hspace{1cm} TimeStamp;
 EFI_EVENT    \hspace{1cm} RecycleSignal;
 UINT32       \hspace{1cm} HeaderLength;
 EFI_IP4_HEADER *Header;
 UINT32       \hspace{1cm} OptionsLength;
 VOID         \hspace{1cm} Options;
 UINT32       \hspace{1cm} DataLength;
 UINT32       \hspace{1cm} FragmentCount;
 EFI_IP4_FRAGMENT_DATA FragmentTable[1];
} EFI_IP4_RECEIVE_DATA;

**TimeStamp**
Time when the EFI IPv4 Protocol driver accepted the packet. *TimeStamp* is zero filled if receive timestamps are disabled or unsupported.

**RecycleSignal**
After this event is signaled, the receive data structure is released and must not be referenced.

**HeaderLength**
Length of the IPv4 packet header. Zero if *ConfigData.RawData* is TRUE.

**Header**
Pointer to the IPv4 packet header. If the IPv4 packet was fragmented, this argument is a pointer to the header in the first fragment. NULL if *ConfigData.RawData* is TRUE. Type *EFI_IP4_HEADER* is defined below.

**OptionsLength**
Length of the IPv4 packet header options. May be zero.

**Options**
Pointer to the IPv4 packet header options. If the IPv4 packet was fragmented, this argument is a pointer to the options in the first fragment. May be NULL.

**DataLength**
Sum of the lengths of IPv4 packet buffers in *FragmentTable*. May be zero.

**FragmentCount**
Number of IPv4 payload (or raw) fragments. If *ConfigData.RawData* is TRUE, this count is the number of raw IPv4 fragments received so far. May be zero.

**FragmentTable**
Array of payload (or raw) fragment lengths and buffer pointers. If *ConfigData.RawData* is TRUE, each buffer points to a raw IPv4 fragment and thus IPv4 header and options are included in each buffer. Otherwise, IPv4 headers and options are not included in these buffers. Type *EFI_IP4_FRAGMENT_DATA* is defined below.

The EFI IPv4 Protocol receive data structure is filled in when IPv4 packets have been assembled (or when raw packets have been received). In the case of IPv4 packet assembly, the individual packet fragments are only verified and are not reorganized into a single linear buffer.

The *FragmentTable* contains a sorted list of zero or more packet fragment descriptors. The referenced packet fragments may not be in contiguous memory locations.

```
//**********************************************
// EFI_IP4_HEADER
//**********************************************
#pragma pack(1)
typedef struct {
    UINT8     \hspace{1cm} HeaderLength:4;
```
The fields in the IPv4 header structure are defined in the Internet Protocol version 4 specification, which can be found at “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Internet Protocol version 4 Specification”.

```c
typedef struct {
    UINT32     FragmentLength;
    VOID       *FragmentBuffer;
} EFI_IP4_FRAGMENT_DATA;
```

**FragmentLength**
Length of fragment data. This field may not be set to zero.

**FragmentBuffer**
Pointer to fragment data. This field may not be set to `NULL`.

The `EFI_IP4_FRAGMENT_DATA` structure describes the location and length of the IPv4 packet fragment to transmit or that has been received.

```c
typedef struct {
    EFI_IPv4_ADDRESS DestinationAddress;
    EFI_IP4_OVERRIDE_DATA *OverrideData;
    UINT32           OptionsLength;
    VOID             *OptionsBuffer;
    UINT32           TotalDataLength;
    UINT32           FragmentCount;
    EFI_IP4_FRAGMENT_DATA FragmentTable[1];
} EFI_IP4_TRANSMIT_DATA;
```

**DestinationAddress**
The destination IPv4 address. Ignored if `RawData` is `TRUE`.

**OverrideData**
If not `NULL`, the IPv4 transmission control override data. Ignored if `RawData` is `TRUE`. Type `EFI_IP4_OVERRIDE_DATA` is defined below.

**OptionsLength**
Length of the IPv4 header options data. Must be zero if the IPv4 driver does not support IPv4 options. Ignored

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if RawData is **TRUE**.

**OptionsBuffer**
Pointer to the IPv4 header options data. Ignored if OptionsLength is zero. Ignored if RawData is **TRUE**.

**TotalDataLength**
Total length of the FragmentTable data to transmit.

**FragmentCount**
Number of entries in the fragment data table.

**FragmentTable**
Start of the fragment data table. Type `EFI_IP4_FRAGMENT_DATA` is defined above.

The `EFI_IP4_TRANSMIT_DATA` structure describes a possibly fragmented packet to be transmitted.

```c
//**********************************************
// EFI_IP4_OVERRIDE_DATA
//@**************************************************************************
typedef struct {
    EFI_IPv4_ADDRESS SourceAddress;
    EFI_IPv4_ADDRESS GatewayAddress;
    UINT8 Protocol;
    UINT8 TypeOfService;
    UINT8 TimeToLive;
    BOOLEAN DoNotFragment;
} EFI_IP4_OVERRIDE_DATA;
```

**SourceAddress**
Source address override.

**GatewayAddress**
Gateway address to override the one selected from the routing table. This address must be on the same subnet as this station address. If set to 0.0.0.0, the gateway address selected from routing table will not be overridden.

**Protocol**
Protocol type override.

**TypeOfService**
Type-of-service override.

**TimeToLive**
Time-to-live override.

**DoNotFragment**
Do-not-fragment override.

The information and flags in the override data structure will override default parameters or settings for one `Transmit()` function call.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>The data has been queued for transmission.</td>
</tr>
<tr>
<td><strong>EFI_NOT_STARTED</strong></td>
<td>This instance has not been started.</td>
</tr>
<tr>
<td><strong>EFI_NO_MAPPING</strong></td>
<td>When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
</tbody>
</table>
Table 28.24 – continued from previous page

<table>
<thead>
<tr>
<th>EFI_INVALID_PARAMETER</th>
<th>One or more of the following is <strong>TRUE</strong>:</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>• This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <strong>Token</strong> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <strong>Token.Event</strong> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <strong>Token.Packet.TxData</strong> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <strong>Token.Packet.TxData.OverrideData.</strong> <strong>GatewayAddress</strong> in the override data structure is not a unicast IPv4 address if <strong>OverrideData</strong> is not <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <strong>Token.Packet.TxData.OverrideData.</strong> <strong>SourceAddress</strong> is not a unicast IPv4 address if <strong>OverrideData</strong> is not <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <strong>Token.Packet.OptionsLength</strong> is not zero and <strong>Token.Packet.OptionsBuffer</strong> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <strong>Token.Packet.FragmentCount</strong> is zero.</td>
</tr>
<tr>
<td></td>
<td>• One or more of the <strong>Tok en.Packet.TxData.FragmentTable[]</strong>. <strong>FragmentLength</strong> fields is zero.</td>
</tr>
<tr>
<td></td>
<td>• One or more of the <strong>Tok en.Packet.TxData.FragmentTable[]</strong>. <strong>FragmentBuffer</strong> fields is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <strong>Tok en.Packet.TxData.TotalDataLength</strong> is zero or not equal to the sum of fragment lengths.</td>
</tr>
<tr>
<td></td>
<td>• The IP header in <strong>FragmentTable</strong> is not a well-formed header when <strong>RawData</strong> is <strong>TRUE</strong>.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>EFI_ACCESS_DENIED</th>
<th>The transmit completion token with the same <strong>Token.Event</strong> was already in the transmit queue.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_NOT_READY</td>
<td>The completion token could not be queued because the transmit queue is full.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Not route is found to destination address.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not queue the transmit data.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td><strong>Tok en.Packet.TxData.TotalDataLength</strong> is too short to transmit.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>The length of the IPv4 header + option length + total data length is greater than MTU (or greater than the maximum packet size if * *<em>Token.Packet.TxData.OverrideData. DoNotFragment</em> is <strong>TRUE</strong>.)</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

### 28.3.10 EFI_IP4_PROTOCOL.Receive()

**Summary**

Places a receiving request into the receiving queue.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_IP4_RECEIVE) (;
    IN EFI_IP4_PROTOCOL *This,
    IN EFI_IP4_COMPLETION_TOKEN *Token);
```

**Parameters**
This

Pointer to the *EFI_IP4_PROTOCOL* instance.

Token

Pointer to a token that is associated with the receive data descriptor. Type *EFI_IP4_COMPLETION_TOKEN* is defined in “Related Definitions” of above *Transmit()*.  

Description

The *Receive()* function places a completion token into the receive packet queue. This function is always asynchronous.

The *Token.Event* field in the completion token must be filled in by the caller and cannot be NULL. When the receive operation completes, the EFI IPv4 Protocol driver updates the *Token.Status* and *Token.Packet.RxData* fields and the *Token.Event* is signaled.

Status Codes Returned

<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The receive completion token was cached.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI IPv4 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token.Event is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The receive completion token could not be queued due to a lack of system resources (usually memory).</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The EFI IPv4 Protocol instance has been reset to startup defaults.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The receive completion token with the same <em>Token.Event</em> was already in the receive queue.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The receive request could not be queued because the receive queue is full.</td>
</tr>
<tr>
<td>EFI_ICMP_ERROR</td>
<td>An ICMP error packet was received.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

**28.3.11 EFI_IP4_PROTOCOL.Cancel()**

Summary

Abort an asynchronous transmit or receive request.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_IP4_CANCEL)(
    IN EFI_IP4_PROTOCOL *This,
    IN EFI_IP4_COMPLETION_TOKEN *Token OPTIONAL
);  
```

Parameters

This

Pointer to the *EFI_IP4_PROTOCOL* instance.
Token

Pointer to a token that has been issued by `EFI_IP4_PROTOCOL.Transmit()` or `EFI_IP4_PROTOCOL.Receive()`. If NULL, all pending tokens are aborted. Type `EFI_IP4_COMPLETION_TOKEN` is defined in `EFI_IP4_PROTOCOL.Transmit()`.

Description

The `Cancel()` function is used to abort a pending transmit or receive request. If the token is in the transmit or receive request queues, after calling this function, `Token->Status` will be set to `EFI_ABORTED` and then `Token->Event` will be signaled. If the token is not in one of the queues, which usually means the asynchronous operation has completed, this function will not signal the token and `EFI_NOT_FOUND` is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The asynchronous I/O request was aborted and <code>Token-&gt;Event</code> was signaled.</td>
</tr>
<tr>
<td></td>
<td>When <code>Token</code> is NULL, all pending requests were aborted and their events</td>
</tr>
<tr>
<td></td>
<td>were signaled.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is</td>
</tr>
<tr>
<td></td>
<td>not finished yet.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>When <code>Token</code> is not NULL, the asynchronous I/O request was not found in</td>
</tr>
<tr>
<td></td>
<td>the transmit or receive queue. It has either completed or was not issued by</td>
</tr>
<tr>
<td></td>
<td><code>Transmit()</code> and <code>Receive()</code>.</td>
</tr>
</tbody>
</table>

28.3.12 `EFI_IP4_PROTOCOL.Poll()`

Summary

Polls for incoming data packets and processes outgoing data packets.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_IP4_POLL) (IN EFI_IP4_PROTOCOL *This);
```

Parameters

This

Pointer to the `EFI_IP4_PROTOCOL` instance.

Description

The `Poll()` function polls for incoming data packets and processes outgoing data packets. Network drivers and applications can call the `EFI_IP4_PROTOCOL.Poll()` function to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

In some systems the periodic timer event may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the `EFI_IP4_PROTOCOL.Poll()` function more often.

Status Codes Returned
28.4 EFI IPv4 Configuration Protocol

This section provides a detailed description of the EFI IPv4 Configuration Protocol.

IMPORTANT NOTICE: The EFI_IP4_CONFIG_PROTOCOL has been replaced with the new EFI_IP4_CONFIG2_PROTOCOL.

- All new designs based on this specification should exclusively use EFI_IP4_CONFIG2_PROTOCOL.
- The EFI_IP4_CONFIG_PROTOCOL will be removed in the next revision of this specification.

28.4.1 EFI_IP4_CONFIG_PROTOCOL

IMPORTANT NOTICE: The EFI_IP4_CONFIG_PROTOCOL has been replaced with the new EFI_IP4_CONFIG2_PROTOCOL.

- All new designs based on this specification should exclusively use EFI_IP4_CONFIG2_PROTOCOL.
- The EFI_IP4_CONFIG_PROTOCOL will be removed in the next revision of this specification.

Summary

The EFI_IP4_CONFIG_PROTOCOL driver performs platform- and policy-dependent configuration for the EFI IPv4 Protocol driver.

GUID

```
#define EFI_IP4_CONFIG_PROTOCOL_GUID \ 
{0x3b95aa31,0x3793,0x434b,\ 
 {0x86,0x67,0xc8,0x07,0x08,0x92,0xe0,0x5e}}
```

Protocol Interface Structure

```
typedef struct _EFI_IP4_CONFIG_PROTOCOL { 
  EFI_IP4_CONFIG_START Start;
  EFI_IP4_CONFIG_STOP Stop;
  EFI_IP4_CONFIG_GET_DATA GetData;
} EFI_IP4_CONFIG_PROTOCOL;
```

Parameters

Start

Starts running the configuration policy for the EFI IPv4 Protocol driver. See the Start() function description.

Stop

Stops running the configuration policy for the EFI IPv4 Protocol driver. See the Stop() function description.
GetData

Returns the default configuration data (if any) for the EFI IPv4 Protocol driver. See the GetData() function description.

Description

In an effort to keep platform policy code out of the EFI IPv4 Protocol driver, the EFI_IP4_CONFIG_PROTOCOL driver will be used as the central repository of any platform- and policy-specific configuration for the EFI IPv4 Protocol driver.

An EFI IPv4 Configuration Protocol interface will be installed on each communications device handle that is managed by the platform setup policy. The driver that is responsible for creating EFI IPv4 variable must open the EFI IPv4 Configuration Protocol driver interface BY_DRIVER|EXCLUSIVE.

An example of a configuration policy decision for the EFI IPv4 Protocol driver would be to use a static IP address/subnet mask pair on the platform management network interface and then use dynamic IP addresses that are configured by DHCP on the remaining network interfaces.

28.4.2 EFI_IP4_CONFIG_PROTOCOL.Start()

IMPORTANT NOTICE: The EFI_IP4_CONFIG_PROTOCOL has been replaced with the new EFI_IP4_CONFIG2_PROTOCOL.

- All new designs based on this specification should exclusively use EFI_IP4_CONFIG2_PROTOCOL.
- The EFI_IP4_CONFIG_PROTOCOL will be removed in the next revision of this specification.

Summary

Starts running the configuration policy for the EFI IPv4 Protocol driver.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_IP4_CONFIG_START) (
    IN EFI_IP4_CONFIG_PROTOCOL *This,
    IN EFI_EVENT DoneEvent,
    IN EFI_EVENT ReconfigEvent
);
```

Parameters

This

Pointer to the EFI_IP4_CONFIG_PROTOCOL instance.

DoneEvent

Event that will be signaled when the EFI IPv4 Protocol driver configuration policy completes execution. This event must be of type EVT_NOTIFY_SIGNAL.

ReconfigEvent

Event that will be signaled when the EFI IPv4 Protocol driver configuration needs to be updated. This event must be of type EVT_NOTIFY_SIGNAL.

Description

The Start() function is called to determine and to begin the platform configuration policy by the EFI IPv4 Protocol driver. This determination may be as simple as returning EFI_UNSUPPORTED if there is no EFI IPv4 Protocol driver configuration policy. It may be as involved as loading some defaults from nonvolatile storage, downloading dynamic data from a DHCP server, and checking permissions with a site policy server.
Starting the configuration policy is just the beginning. It may finish almost instantly or it may take several minutes before it fails to retrieve configuration information from one or more servers. Once the policy is started, drivers should use the $DoneEvent$ parameter to determine when the configuration policy has completed. $EFI_{IP4\_CONFIG\_PROTOCOL\_GetData()}$ must then be called to determine if the configuration succeeded or failed.

Until the configuration completes successfully, EFI IPv4 Protocol driver instances that are attempting to use default configurations must return $EFI\_NO\_MAPPING$.

Once the configuration is complete, the EFI IPv4 Configuration Protocol driver signals $DoneEvent$. The configuration may need to be updated in the future, however; in this case, the EFI IPv4 Configuration Protocol driver must signal $ReconfigEvent$, and all EFI IPv4 Protocol driver instances that are using default configurations must return $EFI\_NO\_MAPPING$ until the configuration policy has been rerun.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>$EFI_SUCCESS$</td>
<td>The configuration policy for the EFI IPv4 Protocol driver is now running.</td>
</tr>
<tr>
<td>$EFI_INVALID_PARAMETER$</td>
<td>One or more of the following parameters is $NULL$:</td>
</tr>
<tr>
<td></td>
<td>• $This$</td>
</tr>
<tr>
<td></td>
<td>• $DoneEvent$</td>
</tr>
<tr>
<td></td>
<td>• $ReconfigEvent$</td>
</tr>
<tr>
<td>$EFI_OUT_OF_RESOURCES$</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>$EFI_ALREADY_STARTED$</td>
<td>The configuration policy for the EFI IPv4 Protocol driver was already started.</td>
</tr>
<tr>
<td>$EFI_DEVICE_ERROR$</td>
<td>An unexpected system error or network error occurred.</td>
</tr>
<tr>
<td>$EFI_UNSUPPORTED$</td>
<td>This interface does not support the EFI IPv4 Protocol driver configuration.</td>
</tr>
</tbody>
</table>

### 28.4.3 $EFI\_IP4\_CONFIG\_PROTOCOL\_Stop()$

**IMPORTANT NOTICE:** The $EFI\_IP4\_CONFIG\_PROTOCOL$ has been replaced with the new $EFI\_IP4\_CONFIG2\_PROTOCOL$.

- All new designs based on this specification should exclusively use $EFI\_IP4\_CONFIG2\_PROTOCOL$.
- The $EFI\_IP4\_CONFIG\_PROTOCOL$ will be removed in the next revision of this specification.

**Summary**

Stops running the configuration policy for the EFI IPv4 Protocol driver.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_IP4_CONFIG_STOP) (IN EFI_IP4_CONFIG_PROTOCOL *This);
```

**Parameters**

- **This**
  - Pointer to the $EFI\_IP4\_CONFIG\_PROTOCOL$ instance.

**Description**
The \texttt{Stop()} function stops the configuration policy for the EFI IPv4 Protocol driver. All configuration data will be lost after calling \texttt{Stop()}.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The configuration policy for the EFI IPv4 Protocol driver has been stopped.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER       | This is \texttt{NULL}.
| EFI_NOT_STARTED             | The configuration policy for the EFI IPv4 Protocol driver was not started.  |

28.4.4 \texttt{EFI_IP4_CONFIG_PROTOCOL.GetData()}

**IMPORTANT NOTICE:** The \texttt{EFI_IP4_CONFIG_PROTOCOL} has been replaced with the new \texttt{EFI_IP4_CONFIG2_PROTOCOL}.

- All new designs based on this specification should exclusively use \texttt{EFI_IP4_CONFIG2_PROTOCOL}.
- The \texttt{EFI_IP4_CONFIG_PROTOCOL} will be removed in the next revision of this specification.

**Summary**

Returns the default configuration data (if any) for the EFI IPv4 Protocol driver.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPIC *EFI_IP4_CONFIG_GET_DATA) (
    IN EFI_IP4_CONFIG_PROTOCOL *This,
    IN OUT UINTN *IpConfigDataSize,
    OUT EFI_IP4_IPCONFIG_DATA *IpConfigData OPTIONAL
);
```

**Parameters**

- **This**
  Pointer to the \texttt{EFI_IP4_CONFIG_PROTOCOL} instance.

- **IpConfigDataSize**
  On input, the size of the \texttt{IpConfigData} buffer. On output, the count of bytes that were written into the \texttt{IpConfigData} buffer.

- **IpConfigData**
  Pointer to the EFI IPv4 Configuration Protocol driver configuration data structure. Type \texttt{EFI_IP4_IPCONFIG_DATA} is defined in “Related Definitions” below.

**Description**

The \texttt{GetData()} function returns the current configuration data for the EFI IPv4 Protocol driver after the configuration policy has completed.

**Related Definition**

```c
//******************************************************************************
// EFI_IP4_IPCONFIG_DATA
//******************************************************************************
typedef struct {
    EFI_IPv4_ADDRESS StationAddress;
    EFI_IPv4_ADDRESS SubnetMask;
}';
```

(continues on next page)
StationAddress
   Default station IP address, stored in network byte order.

SubnetMask
   Default subnet mask, stored in network byte order.

RouteTableSize
   Number of entries in the following RouteTable. May be zero.

RouteTable
   Default routing table data (stored in network byte order). Ignored if RouteTableSize is zero. Type EFI_IP4_ROUTE_TABLE is defined in EFI_IP4_PROTOCOL.GetModeData().

EFI_IP4_IPCONFIG_DATA contains the minimum IPv4 configuration data that is needed to start basic network communication. The StationAddress and SubnetMask must be a valid unicast IP address and subnet mask.

If RouteTableSize is not zero, then RouteTable contains a properly formatted routing table for the StationAddress/SubnetMask, with the last entry in the table being the default route.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The EFI IPv4 Protocol driver configuration has been returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The configuration policy for the EFI IPv4 Protocol driver is not running.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>EFI IPv4 Protocol driver configuration is still running.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>EFI IPv4 Protocol driver configuration could not complete.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>* IpConfigDataSize is smaller than the configuration data buffer or IpConfigData is NULL.</td>
</tr>
</tbody>
</table>

28.5 EFI IPv4 Configuration II Protocol

This section provides a detailed description of the EFI IPv4 Configuration II Protocol.

28.5.1 EFI_IP4_CONFIG2_PROTOCOL

Summary

The EFI_IP4_CONFIG2_PROTOCOL provides the mechanism to set and get various types of configurations for the EFI IPv4 network stack.

GUID

```
#define EFI_IP4_CONFIG2_PROTOCOL_GUID \
  { 0x5b446ed1, 0xe30b, 0x4faa,\ 
    { 0x87, 0x1a, 0x36, 0x54, 0xec, 0xa3, 0x60, 0x80 } }
```

Protocol Interface Structure

28.5. EFI IPv4 Configuration II Protocol
typedef struct _EFI_IP4_CONFIG2_PROTOCOL {
    EFI_IP4_CONFIG2_SET_DATA    SetData;
    EFI_IP4_CONFIG2_GET_DATA    GetData;
    EFI_IP4_CONFIG2_REGISTER_NOTIFY RegisterDataNotify;
    EFI_IP4_CONFIG2_UNREGISTER_NOTIFY UnregisterDataNotify;
} EFI_IP4_CONFIG2_PROTOCOL;

Parameters

SetData
   Set the configuration for the EFI IPv4 network stack running on the communication device this EFI IPv4 Configuration II Protocol instance manages. See the SetData() function description.

GetData
   Get the configuration for the EFI IPv4 network stack running on the communication device this EFI IPv4 Configuration II Protocol instance manages. See the GetData() function description.

RegisterDataNotify
   Register an event that is to be signaled whenever a configuration process on the specified configuration data is done.

UnregisterDataNotify
   Remove a previously registered event for the specified configuration data.

Description

The EFI_IP4_CONFIG2_PROTOCOL is designed to be the central repository for the common configurations and the administrator configurable settings for the EFI IPv4 network stack.

An EFI IPv4 Configuration II Protocol instance will be installed on each communication device that the EFI IPv4 network stack runs on.

NOTE: All the network addresses described in EFI_IP4_CONFIG2_PROTOCOL are stored in network byte order. All other parameters defined in functions or data structures are stored in host byte order.

28.5.2 EFI_IP4_CONFIG2_PROTOCOL.SetData()

Summary

Set the configuration for the EFI IPv4 network stack running on the communication device this EFI IPv4 Configuration II Protocol instance manages.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_IP4_CONFIG2_SET_DATA) (  
    IN EFI_IP4_CONFIG2_PROTOCOL  *This,  
    IN EFI_IP4_CONFIG2_DATA_TYPE  DataType,  
    IN UINTN  DataSize,  
    IN VOID  *Data
    );

Parameters

This
   Pointer to the EFI_IP4_CONFIG2_PROTOCOL instance.
**DataType**

The type of data to set. Type `EFI_IP4_CONFIG2_DATA_TYPE` is defined in “Related Definitions” below.

**DataSize**

Size of the buffer pointed to by `Data` in bytes.

**Data**

The data buffer to set. The type of the data buffer is associated with the `DataType`. The various types are defined in “Related Definitions” below.

**Description**

This function is used to set the configuration data of type `DataType` for the EFI IPv4 network stack running on the communication device this EFI IPv4 Configuration II Protocol instance manages. The successfully configured data is valid after system reset or power-off.

The `DataSize` is used to calculate the count of structure instances in the `Data` for some `DataType` that multiple structure instances are allowed.

This function is always non-blocking. When setting some type of configuration data, an asynchronous process is invoked to check the correctness of the data, such as doing address conflict detection on the manually set local IPv4 address. `EFI_NOT_READY` is returned immediately to indicate that such an asynchronous process is invoked and the process is not finished yet. The caller willing to get the result of the asynchronous process is required to call `RegisterDataNotify()` to register an event on the specified configuration data. Once the event is signaled, the caller can call `GetData()` to get back the configuration data in order to know the result. For other types of configuration data that do not require an asynchronous configuration process, the result of the operation is immediately returned.

**Related Definition**

```c
typedef enum {
    Ip4Config2DataTypeInterfaceInfo,
    Ip4Config2DataTypePolicy,
    Ip4Config2DataTypeManualAddress,
    Ip4Config2DataTypeGateway,
    Ip4Config2DataTypeDnsServer,
    Ip4Config2DataTypeMaximum
} EFI_IP4_CONFIG2_DATA_TYPE;
```

**Ip4Config2DataTypeInterfaceInfo**

The interface information of the communication device this EFI IPv4 Configuration II Protocol instance manages. This type of data is read only. The corresponding `Data` is of type `EFI_IP4_CONFIG2_INTERFACE_INFO`.

**Ip4Config2DataTypePolicy**

The general configuration policy for the EFI IPv4 network stack running on the communication device this EFI IPv4 Configuration II Protocol instance manages. The policy will affect other configuration settings. The corresponding `Data` is of type `EFI_IP4_CONFIG2_POLICY`.

**Ip4Config2DataTypeManualAddress**

The station addresses set manually for the EFI IPv4 network stack. It is only configurable when the policy is `Ip4Config2PolicyStatic`. The corresponding `Data` is of type `EFI_IP4_CONFIG2_MANUAL_ADDRESS`. When `DataSize` is 0 and `Data` is NULL, the existing configuration is cleared from the EFI IPv4 Configuration II Protocol instance.

**Ip4Config2DataTypeGateway**

The gateway addresses set manually for the EFI IPv4 network stack running on the communication device this EFI IPv4 Configuration II Protocol manages. It is not configurable when the policy is `Ip4Config2PolicyDhcp`.
The gateway addresses must be unicast IPv4 addresses. The corresponding Data is a pointer to an array of EFI_IPv4_ADDRESS instances. When DataSize is 0 and Data is NULL, the existing configuration is cleared from the EFI IPv4 Configuration II Protocol instance.

**Ip4Config2Data**

The DNS server list for the EFI IPv4 network stack running on the communication device this EFI IPv4 Configuration II Protocol manages. It is not configurable when the policy is Ip4Config2PolicyDhcp. The DNS server addresses must be unicast IPv4 addresses. The corresponding Data is a pointer to an array of EFI_IPv4_ADDRESS instances. When DataSize is 0 and Data is NULL, the existing configuration is cleared from the EFI IPv4 Configuration II Protocol instance.

```c
//****************************************************************************
// EFI_IP4_CONFIG2_INTERFACE_INFO related definitions
//****************************************************************************
#define EFI_IP4_CONFIG2_INTERFACE_INFO_NAME_SIZE 32

// EFI_IP4_CONFIG2_INTERFACE_INFO
typedef struct {
    CHAR16 Name[EFI_IP4_CONFIG2_INTERFACE_INFO_NAME_SIZE];
    UINT8 IfType;
    UINT32 HwAddressSize;
    EFI_MAC_ADDRESS HwAddress;
    EFI_IPv4_ADDRESS StationAddress;
    EFI_IPv4_ADDRESS SubnetMask;
    UINT32 RouteTableSize;
    EFI_IP4_ROUTE_TABLE *RouteTable OPTIONAL;
} EFI_IP4_CONFIG2_INTERFACE_INFO;
```

Name

The name of the interface. It is a NULL-terminated Unicode string.

IfType

The interface type of the network interface. See RFC 1700, section “Number Hardware Type”.

HwAddressSize

The size, in bytes, of the network interface’s hardware address.

HwAddress

The hardware address for the network interface.

StationAddress

The station IPv4 address of this EFI IPv4 network stack.

SubnetMask

The subnet address mask that is associated with the station address.

RouteTableSize

Size of the following RouteTable, in bytes. May be zero.

RouteTable

The route table of the IPv4 network stack runs on this interface. Set to NULL if RouteTableSize is zero. Type EFI_IP4_ROUTE_TABLE is defined in EFI_IP4_PROTOCOL.GetModeData().
followings are the route table if present. The caller should NOT free the buffer pointed to by RouteTable, and the caller is only required to free the whole buffer if the data is not needed any more.

```c
//EFI_IP4_CONFIG2_POLICY
typedef enum {
    Ip4Config2PolicyStatic,
    Ip4Config2PolicyDhcp,
    Ip4Config2PolicyMax
} EFI_IP4_CONFIG2_POLICY;

// TODO: please note there is a missing explanatory note for Ip4Config2PolicyMax not included in the list below.
```

**Ip4Config2PolicyStatic**
Under this policy, the Ip4Config2DataTypeManualAddress, Ip4Config2DataTypeGateway and Ip4Config2DataTypeDnsServer configuration data are required to be set manually. The EFI IPv4 Protocol will get all required configuration such as IPv4 address, subnet mask and gateway settings from the EFI IPv4 Configuration II protocol.

**Ip4Config2PolicyDhcp**
Under this policy, the Ip4Config2DataTypeManualAddress, Ip4Config2DataTypeGateway and Ip4Config2DataTypeDnsServer configuration data are not allowed to set via SetData(). All of these configurations are retrieved from DHCP server or other auto-configuration mechanism.

The EFI_IP4_CONFIG2_POLICY defines the general configuration policy the EFI IPv4 Configuration II Protocol supports. The default policy for a newly detected communication device is beyond the scope of this document. An implementation might leave it to platform to choose the default policy.

The configuration data of type Ip4Config2DataTypeManualAddress, Ip4Config2DataTypeGateway and Ip4Config2DataTypeDnsServer will be flushed if the policy is changed from Ip4Config2PolicyStatic to Ip4Config2PolicyDhcp.

```c
//EFI_IP4_CONFIG2_MANUAL_ADDRESS
typedef struct {
    EFI_IPv4_ADDRESS Address;
    EFI_IPv4_ADDRESS SubnetMask;
} EFI_IP4_CONFIG2_MANUAL_ADDRESS;
```

**Address**
The IPv4 unicast address.

**SubnetMask**
The subnet mask.

The EFI_IP4_CONFIG2_MANUAL_ADDRESS structure is used to set the station address information for the EFI IPv4 network stack manually when the policy is Ip4Config2PolicyStatic.

The EFI_IP4_CONFIG2_DATA_TYPE includes current supported data types; this specification allows future extension to support more data types.

**Status Codes Returned**
28.5.3 _EFI_IP4_CONFIG2_PROTOCOL.GetData()

Summary

Get the configuration data for the EFI IPv4 network stack running on the communication device this EFI IPv4 Configuration II Protocol instance manages.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_IP4_CONFIG2_GET_DATA) (  
  IN EFI_IP4_CONFIG2_PROTOCOL *This,  
  IN EFI_IP4_CONFIG2_DATA_TYPE DataType,  
  IN OUT UINTN *DataSize,  
  IN VOID *Data OPTIONAL
);
```

Parameters

This

Pointer to the _EFI_IP4_CONFIG2_PROTOCOL instance.

DataType

The type of data to get. Type _EFI_IP4_CONFIG2_DATA_TYPE is defined in _EFI_IP4_CONFIG2_PROTOCOL.SetData().

DataSize

On input, in bytes, the size of Data. On output, in bytes, the size of buffer required to store the specified configuration data.

Data

The data buffer in which the configuration data is returned. The type of the data buffer is associated with the DataType. Ignored if DataSize is 0. The various types are defined in _EFI_IP4_CONFIG2_PROTOCOL.SetData().
Description

This function returns the configuration data of type *DataType* for the EFI IPv4 network stack running on the communication device this EFI IPv4 Configuration II Protocol instance manages.

The caller is responsible for allocating the buffer used to return the specified configuration data and the required size will be returned to the caller if the size of the buffer is too small.

*EFI_NOT_READY* is returned if the specified configuration data is not ready due to an already in progress asynchronous configuration process. The caller can call *RegisterDataNotify()* to register an event on the specified configuration data. Once the asynchronous configuration process is finished, the event will be signaled and a subsequent *GetData()* call will return the specified configuration data.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The specified configuration data is got successfully.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER*| One or more of the followings are **TRUE**:  
|                       | • This is **NULL**.  
|                       | • DataSize is **NULL**.  
|                       | • Data is **NULL** if DataSize is not zero.  |
| EFI_BUFFER_TOO_SMALL  | The size of Data is too small for the specified configuration data and the required size is returned in DataSize. |
| EFI_NOT_READY         | The specified configuration data is not ready due to an already in progress asynchronous configuration process. |
| EFI_NOT_FOUND         | The specified configuration data is not found.                              |

28.5.4  *EFI_IP4_CONFIG2_PROTOCOL*.RegisterDataNotify()

Summary

Register an event that is to be signaled whenever a configuration process on the specified configuration data is done.

Prototype

```c
typedef EFI_STATUS
    (EFIAPI *EFI_IP4_CONFIG2_REGISTER_NOTIFY) (  
    IN EFI_IP4_CONFIG2_PROTOCOL *This,  
    IN EFI_IP4_CONFIG2_DATA_TYPE DataType,  
    IN EFI_EVENT Event  
    )

Parameters

This  
Pointer to the *EFI_IP4_CONFIG2_PROTOCOL* instance.

DataType  
The type of data to unregister the event for. Type *EFI_IP4_CONFIG2_DATA_TYPE* is defined in *EFI_IP4_CONFIG2_PROTOCOL*.SetData().

Event  
The event to register.
Description

This function registers an event that is to be signaled whenever a configuration process on the specified configuration data is done. An event can be registered for different `DataType` simultaneously and the caller is responsible for determining which type of configuration data causes the signaling of the event in such case.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The notification event for the specified configuration data is registered.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL or Event is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The configuration data type specified by <code>DataType</code> is not supported.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The <code>Event</code> is already registered for the <code>DataType</code>.</td>
</tr>
</tbody>
</table>

28.5.5  `EFI_IP4_CONFIG2_PROTOCOL.UnregisterDataNotify()`

Summary

Remove a previously registered event for the specified configuration data.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_IP4_CONFIG2_UNREGISTER_NOTIFY) (
    IN EFI_IP4_CONFIG2_PROTOCOL *This,
    IN EFI_IP4_CONFIG2_DATA_TYPE DataType,
    IN EFI_EVENT Event
);
```

Parameters

This

Pointer to the `EFI_IP4_CONFIG2_PROTOCOL` instance.

DataType

The type of data to remove the previously registered event for. Type `EFI_IP4_CONFIG2_DATA_TYPE` is defined in `EFI_IP4_CONFIG2_PROTOCOL.SetData()`.

Event

The event to unregister.

Description

This function removes a previously registered event for the specified configuration data.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The event registered for the specified configuration data is removed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL or Event is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The <code>Event</code> has not been registered for the specified <code>DataType</code>.</td>
</tr>
</tbody>
</table>
28.6 EFI IPv6 Protocol

This section defines the EFI IPv6 (Internet Protocol version 6) Protocol interface. It is split into the following three main sections:

- EFI IPv6 Service Binding Protocol
- EFI IPv6 Variable
- EFI IPv6 Protocol

The EFI IPv6 Protocol provides basic network IPv6 packet I/O services, which includes support for Neighbor Discovery Protocol (ND), Multicast Listener Discovery Protocol (MLD), and a subset of the Internet Control Message Protocol (ICMPv6).

28.6.1 IPv6 Service Binding Protocol

28.6.2 EFI_IP6_SERVICE_BINDING_PROTOCOL

Summary

The EFI IPv6 Service Binding Protocol is used to locate communication devices that are supported by an EFI IPv6 Protocol driver and to create and destroy EFI IPv6 Protocol child instances of the IP6 driver that can use the underlying communications device.

GUID

```
#define EFI_IP6_SERVICE_BINDING_PROTOCOL _GUID {
  0xec835dd3,0xfe0f,0x617b,
  {0xa6,0x21,0xb3,0x50,0xc3,0xe1,0x33,0x88}
}
```

Description

A network application that requires basic IPv6 I/O services can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish an EFI IPv6 Service Binding Protocol GUID. Each device with a published EFI IPv6 Service Binding Protocol GUID supports the EFI IPv6 Protocol and may be available for use.

After a successful call to the `EFI_IP6_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the newly created child EFI IPv6 Protocol driver is in an un-configured state; it is not ready to send and receive data packets.

Before a network application terminates execution, every successful call to the `EFI_IP6_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI_IP6_SERVICE_BINDING_PROTOCOL.DestroyChild()` function.
28.6.3 IPv6 Protocol

28.6.4 EFI_IP6_PROTOCOL

Summary

The EFI IPv6 Protocol implements a simple packet-oriented interface that can be used by drivers, daemons, and applications to transmit and receive network packets.

GUID

```c
#define EFI_IP6_PROTOCOL_GUID
{0x2c8759d5,0x5c2d,0x66ef,\n 0x92,0x5f,0xb6,0x6c,0x10,0x19,0x57,0xe2}
```

Protocol Interface Structure

```c
typedef struct _EFI_IP6_PROTOCOL {
  EFI_IP6_GET_MODE_DATA GetModeData;
  EFI_IP6_CONFIGURE Configure;
  EFI_IP6_GROUPS Groups;
  EFI_IP6_ROUTES Routes;
  EFI_IP6_NEIGHBOR Neighbors;
  EFI_IP6_TRANSMIT Transmit;
  EFI_IP6_RECEIVE Receive;
  EFI_IP6_CANCEL Cancel;
  EFI_IP6_POLL Poll;
} EFI_IP6_PROTOCOL;
```

Parameters

**GetModeData**

 Gets the current operational settings for this instance of the EFI IPv6 Protocol driver. See the `GetModeData()` function description.

**Configure**

 Changes or resets the operational settings for the EFI IPv6 Protocol. See the `Configure()` function description.

**Groups**

 Joins and leaves multicast groups. See the `Groups()` function description.

**Routes**

 Adds and deletes routing table entries. See the `Routes()` function description.

**Neighbors**

 Adds and deletes neighbor cache entries. See the `Neighbors()` function description.

**Transmit**

 Places outgoing data packets into the transmit queue. See the `Transmit()` function description.

**Receive**

 Places a receiving request into the receiving queue. See the `Receive()` function description.

**Cancel**

 Aborts a pending transmit or receive request. See the `Cancel()` function description.

**Poll**

 Polls for incoming data packets and processes outgoing data packets. See the `Poll()` function description.
Description

The EFI_IP6_PROTOCOL defines a set of simple IPv6, and ICMPv6 services that can be used by any network protocol driver, daemon, or application to transmit and receive IPv6 data packets.

NOTE: Byte Order: All the IPv6 addresses that are described in EFI_IP6_PROTOCOL are stored in network byte order. Both incoming and outgoing IP packets are also in network byte order. All other parameters that are defined in functions or data structures are stored in host byte order.

28.6.5 EFI_IP6_PROTOCOL.GetModeData()

Summary

Gets the current operational settings for this instance of the EFI IPv6 Protocol driver.

Prototype

```c
EFI_STATUS (EFIAPI *EFI_IP6_GET_MODE_DATA) (  
  IN EFI_IP6_PROTOCOL *This,  
  OUT EFI_IP6_MODE_DATA *Ip6ModeData OPTIONAL,  
  OUT EFI_MANAGED_NETWORK_CONFIG_DATA *MnpConfigData OPTIONAL,  
  OUT EFI_SIMPLE_NETWORK_MODE *SnpModeData OPTIONAL);  
```

Parameters

This

Pointer to the EFI_IP6_PROTOCOL instance.

Ip6ModeData

Pointer to the EFI IPv6 Protocol mode data structure. Type EFI_IP6_MODE_DATA is defined in “Related Definitions” below.

MnpConfigData

Pointer to the managed network configuration data structure. Type EFI_MANAGED_NETWORK_CONFIG_DATA is defined in EFI_MANAGED_NETWORK_PROTOCOL.GetModeData().

SnpData

Pointer to the simple network mode data structure. Type EFI_SIMPLE_NETWORK_MODE is defined in the EFI_SIMPLE_NETWORK_PROTOCOL.

Description

The GetModeData() function returns the current operational mode data for this driver instance. The data fields in EFI_IP6_MODE_DATA are read only. This function is used optionally to retrieve the operational mode data of underlying networks or drivers.

Related Definition

```c
//***************************************************************
// EFI_IP6_MODE_DATA
//***************************************************************
typedef struct {
    BOOLEAN IsStarted;
    UINT32 MaxPacketSize;
    EFI_IP6_CONFIG_DATA ConfigData;
    BOOLEAN IsConfigured;
}  
```
IsStarted
Set to TRUE after this EFI IPv6 Protocol instance is started. All other fields in this structure are undefined until this field is TRUE. Set to FALSE when the EFI IPv6 Protocol instance is stopped.

MaxPackeSize
The maximum packet size, in bytes, of the packet which the upper layer driver could feed.

ConfigData
Current configuration settings. Undefined until IsStarted is TRUE. Type EFI_IP6_CONFIG_DATA is defined below.

IsConfigured
Set to TRUE when the EFI IPv6 Protocol instance is configured. The instance is configured when it has a station address and corresponding prefix length. Set to FALSE when the EFI IPv6 Protocol instance is not configured.

AddressCount
Number of configured IPv6 addresses on this interface.

AddressList
List of currently configured IPv6 addresses and corresponding prefix lengths assigned to this interface. It is caller’s responsibility to free this buffer. Type EFI_IP6_ADDRESS_INFO is defined below.

GroupCount
Number of joined multicast groups. Undefined until IsConfigured is TRUE.

GroupTable
List of joined multicast group addresses. It is caller’s responsibility to free this buffer. Undefined until IsConfigured is TRUE.

RouteCount
Number of entries in the routing table. Undefined until IsConfigured is TRUE.

RouteTable
Routing table entries. It is caller’s responsibility to free this buffer. Type EFI_IP6_ROUTE_TABLE is defined below.

NeighborCount
Number of entries in the neighbor cache. Undefined until IsConfigured is TRUE.

NeighborCache
Neighbor cache entries. It is caller’s responsibility to free this buffer. Undefined until IsConfigured is TRUE. Type EFI_IP6_NEIGHBOR_CACHE is defined below.

PrefixCount
Number of entries in the prefix table. Undefined until IsConfigured is TRUE.
PrefixTable
On-link Prefix table entries. It is caller’s responsibility to free this buffer. Undefined until IsConfigured is TRUE.
Type EFI_IP6_ADDRESS_INFO is defined below.

IcmpTypeCount
Number of entries in the supported ICMP types list.

IcmpTypeList
Array of ICMP types and codes that are supported by this EFI IPv6 Protocol driver. It is caller’s responsibility to free this buffer. Type EFI_IP6_ICMP_TYPE is defined below.

```c
//**************************************
// EFI_IP6_CONFIG_DATA
//**************************************
typedef struct {
  UINT8 DefaultProtocol;
  BOOLEAN AcceptAnyProtocol;
  BOOLEAN AcceptIcmpErrors;
  BOOLEAN AcceptPromiscuous;
  EFI_IPv6_ADDRESS DestinationAddress;
  EFI_IPv6_ADDRESS StationAddress;
  UINT8 TrafficClass;
  UINT8 HopLimit;
  UINT32 FlowLabel;
  UINT32 ReceiveTimeout;
  UINT32 TransmitTimeout;
} EFI_IP6_CONFIG_DATA;
```

DefaultProtocol
For the IPv6 packet to send and receive, this is the default value of the ‘Next Header’ field in the last IPv6 extension header or in the IPv6 header if there are no extension headers. Ignored when AcceptPromiscuous is TRUE. An updated list of protocol numbers can be found at “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “IANA Assigned Internet Protocol Numbers”. The following values are illegal: 0 (IPv6 Hop-by-Hop Option), 1(ICMP), 2(IGMP), 41(IPv6), 43(Routing Header for IPv6), 44(Fragment Header for IPv6), 59(No Next Header for IPv6), 60(Destination Options for IPv6), 124(ISIS over IPv4).

AcceptAnyProtocol
Set to TRUE to receive all IPv6 packets that get through the receive filters. Set to FALSE to receive only the DefaultProtocol IPv6 packets that get through the receive filters. Ignored when AcceptPromiscuous is TRUE.

AcceptIcmpErrors
Set to TRUE to receive ICMP error report packets. Ignored when AcceptPromiscuous or AcceptAnyProtocol is TRUE.

AcceptPromiscuous
Set to TRUE to receive all IPv6 packets that are sent to any hardware address or any protocol address. Set to FALSE to stop receiving all promiscuous IPv6 packets.

DestinationAddress
The destination address of the packets that will be transmitted. Ignored if it is unspecified.

StationAddress
The station IPv6 address that will be assigned to this EFI IPv6 Protocol instance. This field can be set and changed only when the EFI IPv6 driver is transitioning from the stopped to the started states. If the StationAddress is specified, the EFI IPv6 Protocol driver will deliver only incoming IPv6 packets whose destination matches this IPv6 address exactly. The StationAddress is required to be one of currently configured IPv6 addresses. An address containing all zeroes is also accepted as a special case. Under this situation, the IPv6 driver is responsible for binding a source address to this EFI IPv6 protocol instance according to the source address
selection algorithm. Only incoming packets destined to the selected address will be delivered to the user. And the selected station address can be retrieved through later GetModeData() call. If no address is available for selecting, EFI_NO_MAPPING will be returned, and the station address will only be successfully bound to this EFI IPv6 protocol instance after IP6ModeData.IsConfigured changed to TRUE.

TrafficClass
TrafficClass field in transmitted IPv6 packets. Default value is zero.

HopLimit
HopLimit field in transmitted IPv6 packets.

FlowLabel
FlowLabel field in transmitted IPv6 packets. Default value is zero.

ReceiveTimeout
The timer timeout value (number of microseconds) for the receive timeout event to be associated with each assembled packet. Zero means do not drop assembled packets.

TransmitTimeout
The timer timeout value (number of microseconds) for the transmit timeout event to be associated with each outgoing packet. Zero means do not drop outgoing packets.

The EFI_IP6_CONFIG_DATA structure is used to report and change IPv6 session parameters.

```c
// ***********************************************************************
// EFI_IP6_ADDRESS_INFO
// ***********************************************************************
typedef struct {
    EFI_IPv6_ADDRESS Address;
    UINT8 PrefixLength;
} EFI_IP6_ADDRESS_INFO;

todo: tweaked the indent on this code. ok?

Address
The IPv6 address.

PrefixLength
The length of the prefix associated with the Address.

```c
// ***********************************************************************
// EFI_IP6_ROUTE_TABLE
// ***********************************************************************
typedef struct {
    EFI_IPv6_ADDRESS Gateway;
    EFI_IPv6_ADDRESS Destination;
    UINT8 PrefixLength;
} EFI_IP6_ROUTE_TABLE;

Gateway
The IPv6 address of the gateway to be used as the next hop for packets to this prefix. If the IPv6 address is all zeros, then the prefix is on-link.

Destination
The destination prefix to be routed.

PrefixLength
The length of the prefix associated with the Destination.
**EFI_IP6_ROUTE_TABLE** is the entry structure that is used in routing tables.

```c
typedef struct {
    EFI_IPv6_ADDRESS Neighbor;
    EFI_MAC_ADDRESS LinkAddress;
    EFI_IP6_NEIGHBOR_STATE State;
} EFI_IP6_NEIGHBOR_CACHE;
```

**Neighbor**  
The on-link unicast / anycast IP address of the neighbor.

**LinkAddress**  
Link-layer address of the neighbor.

**State**  
State of this neighbor cache entry.

**EFI_IP6_NEIGHBOR_CACHE** is the entry structure that is used in neighbor cache. It records a set of entries about individual neighbors to which traffic has been sent recently.

```c
typedef enum {
    EfiNeighborInComplete,
    EfiNeighborReachable,
    EfiNeighborStale,
    EfiNeighborDelay,
    EfiNeighborProbe
} EFI_IP6_NEIGHBOR_STATE;
```

Following is a description of the fields in the above enumeration.

**EfiNeighborInComplete**  
Address resolution is being performed on this entry. Specially, Neighbor Solicitation has been sent to the solicited-node multicast address of the target, but corresponding Neighbor Advertisement has not been received.

**EfiNeighborReachable**  
Positive confirmation was received that the forward path to the neighbor was functioning properly.

**EfiNeighborStale**  
Reachable Time has elapsed since the last positive confirmation was received. In this state, the forward path to the neighbor was functioning properly.

**EfiNeighborDelay**  
This state is an optimization that gives upper-layer protocols additional time to provide reachability confirmation.

**EfiNeighborProbe**  
A reachability confirmation is actively sought by retransmitting Neighbor Solicitations every RetransTimer milliseconds until a reachability confirmation is received.
UINT8 Type;
UINT8 Code;
} EFI_IP6_ICMP_TYPE;

Type

The type of ICMP message. See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Internet Control Message Protocol Version 6 (ICMPv6) Parameters” for the complete list of ICMP message type.

Code

The code of the ICMP message, which further describes the different ICMP message formats under the same Type. See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Internet Control Message Protocol Version 6 (ICMPv6) Parameters” for details for code of ICMP message.

EFI_IP6_ICMP_TYPE is used to describe those ICMP messages that are supported by this EFI IPv6 Protocol driver.

//*******************************************************
// ICMPv6 type definitions for error messages
//*******************************************************
#define ICMP_V6_DEST_UNREACHABLE 0x1
#define ICMP_V6_PACKET_TOO_BIG 0x2
#define ICMP_V6_TIME_EXCEEDED 0x3
#define ICMP_V6_PARAMETER_PROBLEM 0x4

//*******************************************************
// ICMPv6 type definition for informational messages
//*******************************************************
#define ICMP_V6_ECHO_REQUEST 0x80
#define ICMP_V6_ECHO_REPLY 0x81
#define ICMP_V6_LISTENER_QUERY 0x82
#define ICMP_V6_LISTENER_REPORT 0x83
#define ICMP_V6_LISTENER_DONE 0x84
#define ICMP_V6_ROUTER_SOLICIT 0x85
#define ICMP_V6_ROUTER_ADVERTISE 0x86
#define ICMP_V6_NEIGHBOR_SOLICIT 0x87
#define ICMP_V6_NEIGHBOR_ADVERTISE 0x88
#define ICMP_V6_REDIRECT 0x89
#define ICMP_V6_LISTENER_REPORT_2 0x8F

//*******************************************************
// ICMPv6 code definitions for ICMP_V6_DEST_UNREACHABLE
//*******************************************************
#define ICMP_V6_NO_ROUTE_TO_DEST 0x0
#define ICMP_V6_COMM_PROHIBITED 0x1
#define ICMP_V6_BEYOND_SCOPE 0x2
#define ICMP_V6_ADDR_UNREACHABLE 0x3
#define ICMP_V6_PORT_UNREACHABLE 0x4
#define ICMP_V6_SOURCE_ADDR_FAILED 0x5
#define ICMP_V6_ROUTE_REJECTED 0x6

//*******************************************************
// ICMPv6 code definitions for ICMP_V6_TIME_EXCEEDED
//*******************************************************
(continues on next page)
//*******************************************************
#define ICMP_V6_TIMEOUT_HOP_LIMIT 0x0
#define ICMP_V6_TIMEOUT_REASSEMBLE 0x1
//*******************************************************
// ICMPv6 code definitions for ICMP_V6_PARAMETER_PROBLEM
//*******************************************************
#define ICMP_V6_ERRONEOUS_HEADER 0x0
#define ICMP_V6_UNRECOGNIZE_NEXT_HDR 0x1
#define ICMP_V6_UNRECOGNIZE_OPTION 0x2

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The required mode data could not be allocated.</td>
</tr>
</tbody>
</table>

28.6.6 EFI_IP6_PROTOCOL.Configure()

Summary

Assign IPv6 address and other configuration parameter to this EFI IPv6 Protocol driver instance.

Prototype

typedef EFI_STATUS
(EIFI_API *EFI_IP6_CONFIGURE) (  
    IN EFI_IP6_PROTOCOL *This,  
    IN EFI_IP6_CONFIG_DATA *Ip6ConfigData OPTIONAL  
);

Parameters

This

Pointer to the EFI_IP6_PROTOCOL instance.

Ip6ConfigData

Pointer to the EFI IPv6 Protocol configuration data structure. Type EFI_IP6_CONFIG_DATA is defined in EFI_IP6_PROTOCOL.GetModeData().

Description

The Configure() function is used to set, change, or reset the operational parameters and filter settings for this EFI IPv6 Protocol instance. Until these parameters have been set, no network traffic can be sent or received by this instance. Once the parameters have been reset (by calling this function with Ip6ConfigData set to NULL), no more traffic can be sent or received until these parameters have been set again. Each EFI IPv6 Protocol instance can be started and stopped independently of each other by enabling or disabling their receive filter settings with the Configure() function.

If Ip6ConfigData.StationAddress is a valid non-zero IPv6 unicast address, it is required to be one of the currently configured IPv6 addresses list in the EFI IPv6 drivers, or else EFI_INVALID_PARAMETER will be returned. If Ip6ConfigData.StationAddress is unspecified, the IPv6 driver will bind a source address according to the source address selection algorithm. Clients could frequently call GetModeData() to check get currently configured IPv6 address list in the EFI IPv6 driver. If both Ip6ConfigData.StationAddress and Ip6ConfigData.Destination are unspecified, when
transmitting the packet afterwards, the source address filled in each outgoing IPv6 packet is decided based on the destination of this packet.

If operational parameters are reset or changed, any pending transmit and receive requests will be cancelled. Their completion token status will be set toEFI_ABORTED and their events will be signaled.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The driver instance was successfully opened.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>Ip6ConfigData.StationAddress is neither zero nor a unicast IPv6 address.</td>
</tr>
<tr>
<td></td>
<td>Ip6ConfigData.StationAddress is neither zero nor one of the configured IP</td>
</tr>
<tr>
<td></td>
<td>addresses in the EFI IPv6 driver.</td>
</tr>
<tr>
<td></td>
<td>Ip6ConfigData.DefaultProtocol is illegal.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The EFI IPv6 Protocol driver instance data could not be allocated.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The IPv6 driver was responsible for choosing a source address for this</td>
</tr>
<tr>
<td></td>
<td>instance, but no source address was available for use.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The interface is already open and must be stopped before the IPv6 address</td>
</tr>
<tr>
<td></td>
<td>or prefix length can be changed.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The EFI IPv6 Protocol driver</td>
</tr>
<tr>
<td></td>
<td>instance is not opened.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Default protocol specified through</td>
</tr>
<tr>
<td></td>
<td>Ip6ConfigData.DefaultProtocol isn’t supported.</td>
</tr>
</tbody>
</table>

### 28.6.7 EFI_IP6_PROTOCOL.Groups()

**Summary**

Joins and leaves multicast groups.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPIC *EFI_IP6_GROUPS) (   
    IN EFI_IP6_PROTOCOL *This,   
    IN BOOLEAN JoinFlag,        
    IN EFI_IPv6_ADDRESS *GroupAddress OPTIONAL
);```

**Parameters**

**This**

Pointer to the EFI_IP6_PROTOCOL instance.

**JoinFlag**

Set to TRUE to join the multicast group session and FALSE to leave.

**GroupAddress**

Pointer to the IPv6 multicast address.
Description

The Groups() function is used to join and leave multicast group sessions. Joining a group will enable reception of matching multicast packets. Leaving a group will disable reception of matching multicast packets. Source-Specific Multicast isn’t required to be supported.

If JoinFlag is FALSE and GroupAddress is NULL, all joined groups will be left.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following is TRUE:</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>JoinFlag is TRUE and GroupAddress is NULL</td>
</tr>
<tr>
<td></td>
<td>GroupAddress is not NULL and * GroupAddress is a multicast IPv6 address.</td>
</tr>
<tr>
<td></td>
<td>GroupAddress is not NULL and * GroupAddress is in the range of SSM destination address.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This instance has not been started.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>System resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This EFI IPv6 Protocol implementation does not support multicast groups.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The group address is already in the group table (when JoinFlag is TRUE ).</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The group address is not in the group table (when JoinFlag is FALSE ).</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
</tbody>
</table>

28.6.8 EFI_IP6_PROTOCOL.Routes()

Summary

Adds and deletes routing table entries.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_IP6_Routes) (  
  IN EFI_IP6_PROTOCOL *This,  "This,
  IN BOOLEAN DeleteRoute,    "DeleteRoute,
  IN EFI_IPv6_ADDRESS *Destination OPTIONAL,  "Destination OPTIONAL,
  IN UINT8 PrefixLength,     "PrefixLength,
  IN EFI_IPv6_ADDRESS *GatewayAddress OPTIONAL  
);```

Parameters

This

Pointer to the EFI_IP6_PROTOCOL instance.

DeleteRoute

Set to TRUE to delete this route from the routing table. Set to FALSE to add this route to the routing table. Destination, PrefixLength and Gateway are used as the key to each route entry.

Destination

The address prefix of the subnet that needs to be routed.
PrefixLength
The prefix length of Destination. Ignored if Destination is NULL.

GatewayAddress
The unicast gateway IPv6 address for this route.

Description
The Routes() function adds a route to or deletes a route from the routing table.

Routes are determined by comparing the leftmost PrefixLength bits of Destination with the destination IPv6 address arithmetically. The gateway address must be on the same subnet as the configured station address.

The default route is added with Destination and PrefixLength both set to all zeros. The default route matches all destination IPv6 addresses that do not match any other routes.

All EFI IPv6 Protocol instances share a routing table.

NOTE: There is no way to set up routes to other network interface cards because each network interface card has its own independent network stack that shares information only through the EFI IPv6 variable.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The driver instance has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>When DeleteRoute is TRUE, both Destination and GatewayAddress are NULL.</td>
</tr>
<tr>
<td></td>
<td>When DeleteRoute is FALSE, either Destination or GatewayAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>* GatewayAddress is not a valid unicast IPv6 address.</td>
</tr>
<tr>
<td></td>
<td>* GatewayAddress is one of the local configured IPv6 addresses.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not add the entry to the routing table.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>This route is not in the routing table (when DeleteRoute is TRUE).</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The route is already defined in the routing table (when DeleteRoute is FALSE).</td>
</tr>
</tbody>
</table>

28.6.9 EFI_IP6_PROTOCOL.Neighbors()

Summary
Add or delete Neighbor cache entries.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_IP6_NEIGHBORS) (IN EFI_IP6_PROTOCOL This,
IN BOOLEAN DeleteFlag,
IN EFI_IPv6_ADDRESS *TargetIp6Address,
IN EFI_MAC_ADDRESS *TargetLinkAddress OPTIONAL,
IN UINT32 Timeout,
(continues on next page)
Parameters

This

Pointer to the `EFI_IP6_PROTOCOL` instance.

DeleteFlag

Set to `TRUE` to delete the specified cache entry, set to `FALSE` to add (or update, if it already exists and Override is `TRUE`) the specified cache entry. `TargetIp6Address` is used as the key to find the requested cache entry.

TargetIp6Address

Pointer to Target IPv6 address.

TargetLinkAddress

Pointer to link-layer address of the target. Ignored if `NULL`.

Timeout

Time in 100-ns units that this entry will remain in the neighbor cache, it will be deleted after Timeout. A value of zero means that the entry is permanent. A non-zero value means that the entry is dynamic.

Override

If `TRUE`, the cached link-layer address of the matching entry will be overridden and updated; if `FALSE`, `EFI_ACCESS_DENIED` will be returned if a corresponding cache entry already existed.

Description

The `Neighbors()` function is used to add, update, or delete an entry from neighbor cache.

IPv6 neighbor cache entries are typically inserted and updated by the network protocol driver as network traffic is processed. Most neighbor cache entries will time out and be deleted if the network traffic stops. Neighbor cache entries that were inserted by `Neighbors()` may be static (will not timeout) or dynamic (will time out).

The implementation should follow the neighbor cache timeout mechanism which is defined in RFC4861. The default neighbor cache timeout value should be tuned for the expected network environment.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td><code>EFI_NOT_STARTED</code></td>
<td>The driver instance has not been started.</td>
</tr>
</tbody>
</table>
| `EFI_INVALID_PARAMETER` | One or more of the following conditions is `TRUE`:
This is `NULL`.
`TargetIpAddress` is `NULL`.
* `TargetLinkAddress` is invalid when not `NULL`.
* `TargetIpAddress` is not a valid unicast IPv6 address.
* `TargetIpAddress` is one of the local configured IPv6 addresses. |
| `EFI_OUT_OF_RESOURCES` | Could not add the entry to the neighbor cache. |
| `EFI_NOT_FOUND` | This entry is not in the neighbor cache (when `DeleteFlag` is `TRUE` or when `DeleteFlag` is `FALSE` while `TargetLinkAddress` is `NULL`). |
| `EFI_ACCESS_DENIED` | The to-be-added entry is already defined in the neighbor cache, and that entry is tagged as un-overridden (when `DeleteFlag` is `FALSE`). |
28.6.10 EFI_IP6_PROTOCOL.Transmit()

Summary
Places outgoing data packets into the transmit queue.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_IP6_TRANSMIT) (
    IN EFI_IP6_PROTOCOL *This,
    IN EFI_IP6_COMPLETION_TOKEN *Token
);
```

Parameters

**This**
Pointer to the EFI_IP6_PROTOCOL instance.

**Token**
Pointer to the transmit token. Type EFI_IP6_COMPLETION_TOKEN is defined in “Related Definitions” below.

Description
The Transmit() function places a sending request in the transmit queue of this EFI IPv6 Protocol instance. Whenever the packet in the token is sent out or some errors occur, the event in the token will be signaled and the status is updated.

Related Definition

```c
//***************************************
// EFI_IP6_COMPLETION_TOKEN
//***************************************
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    union {
        EFI_IP6_RECEIVE_DATA *RxData;
        EFI_IP6_TRANSMIT_DATA *TxData;
    } Packet;
} EFI_IP6_COMPLETION_TOKEN;
```

**Event**
This Event will be signaled after the Status field is updated by the EFI IPv6 Protocol driver. The type of Event must be EFI_NOTIFY_SIGNAL.

**Status**
Will be set to one of the following values:

- **EFI_SUCCESS**: The receive or transmit completed successfully.
- **EFI_ABORTED**: The receive or transmit was aborted.
- **EFI_TIMEOUT**: The transmit timeout expired.
**EFI_ICMP_ERROR:** An ICMP error packet was received.

**EFI_DEVICE_ERROR:** An unexpected system or network error occurred.

**EFI_SECURITY_VIOLATION:** The transmit or receive was failed because of an IPsec policy check.

**RxData**
When the Token is used for receiving, RxData is a pointer to the `EFI_IP6_RECEIVE_DATA`. Type `EFI_IP6_RECEIVE_DATA` is defined below.

**TxData**
When the Token is used for transmitting, TxData is a pointer to the `EFI_IP6_TRANSMIT_DATA`. Type `EFI_IP6_TRANSMIT_DATA` is defined below.

`EFI_IP6_COMPLETION_TOKEN` structures are used for both transmit and receive operations.

When the structure is used for transmitting, the `Event` and `TxData` fields must be filled in by the EFI IPv6 Protocol client. After the transmit operation completes, the EFI IPv6 Protocol driver updates the `Status` field and the `Event` is signaled.

When the structure is used for receiving, only the `Event` field must be filled in by the EFI IPv6 Protocol client. After a packet is received, the EFI IPv6 Protocol driver fills in the RxData and `Status` fields and the Event is signaled.

```c
//***********************************************************
// EFI_IP6_RECEIVE_DATA
//***********************************************************
typedef struct _EFI_IP6_RECEIVE_DATA {
  EFI_TIME TimeStamp;
  EFI_EVENT RecycleSignal;
  UINT32 HeaderLength;
  EFI_IP6_HEADER *Header;
  UINT32 DataLength;
  UINT32 FragmentCount;
  EFI_IP6_FRAGMENT_DATA FragmentTable[1];
} EFI_IP6_RECEIVE_DATA;
```

**TimeStamp**
Time when the EFI IPv6 Protocol driver accepted the packet. *TimeStamp is zero filled if timestamps are disabled or unsupported.*

**RecycleSignal**
After this event is signaled, the receive data structure is released and must not be referenced.

**HeaderLength**
Length of the IPv6 packet headers, including both the IPv6 header and any extension headers.

**Header**
Pointer to the IPv6 packet header. If the IPv6 packet was fragmented, this argument is a pointer to the header in the first fragment. Type `EFI_IP6_HEADER` is defined below.

**DataLength**
Sum of the lengths of IPv6 packet buffers in `FragmentTable`. May be zero.

**FragmentCount**
Number of IPv6 payload fragments. May be zero.
FragmentTable

Array of payload fragment lengths and buffer pointers. Type EFI_IP6_FRAGMENT_DATA is defined below.

The EFI IPv6 Protocol receive data structure is filled in when IPv6 packets have been assembled. In the case of IPv6 packet assembly, the individual packet fragments are only verified and are not reorganized into a single linear buffer.

The FragmentTable contains a sorted list of zero or more packet fragment descriptors. The referenced packet fragments may not be in contiguous memory locations.

//****************************************
// EFI_IP6_HEADER
//****************************************
#pragma pack(1)
typedef struct _EFI_IP6_HEADER {
    UINT8 TrafficClassH:4;
    UINT8 Version:4;
    UINT8 FlowLabelH:4;
    UINT8 TrafficClassL:4;
    UINT16 FlowLabelL;
    UINT16 PayloadLength;
    UINT8 NextHeader;
    UINT8 HopLimit;
    EFI_IPv6_ADDRESS SourceAddress;
    EFI_IPv6_ADDRESS DestinationAddress;
} EFI_IP6_HEADER;
#pragma pack

The fields in the IPv6 header structure are defined in the Internet Protocol version6 specification, which can be found at “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Internet Protocol version 6 Specification”.

//**********************************************
// EFI_IP6_FRAGMENT_DATA
//**********************************************
typedef struct _EFI_IP6_FRAGMENT_DATA {
    UINT32 FragmentLength;
    VOID *FragmentBuffer;
} EFI_IP6_FRAGMENT_DATA;

FragmentLength

Length of fragment data. This field may not be set to zero.

FragmentBuffer

Pointer to fragment data. This field may not be set to NULL.

The EFI_IP6_FRAGMENT_DATA structure describes the location and length of the IPv6 packet fragment to transmit or that has been received.

//*********************************************
// EFI_IP6_TRANSMIT_DATA
//*********************************************
typedef struct _EFI_IP6_TRANSMIT_DATA {
    EFI_IPv6_ADDRESS DestinationAddress;
    EFI_IP6_OVERRIDE_DATA *OverrideData;
    UINT32 ExtHdrsLength;
    VOID *ExtHdrs;
} EFI_IP6_TRANSMIT_DATA;

(continues on next page)
### EFI_IP6_TRANSMIT_DATA

<table>
<thead>
<tr>
<th>Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>UINT8</td>
<td>NextHeader;</td>
</tr>
<tr>
<td>UINT32</td>
<td>DataLength;</td>
</tr>
<tr>
<td>UINT32</td>
<td>FragmentCount</td>
</tr>
<tr>
<td>EFI_IP6_FRAGMENT_DATA</td>
<td>FragmentTable[1];</td>
</tr>
</tbody>
</table>

The `EFI_IP6_TRANSMIT_DATA` structure describes a possibly fragmented packet to be transmitted.

#### EFI_IP6_OVERRIDE_DATA

```c
typedef struct _EFI_IP6_OVERRIDE_DATA {
    UINT8 Protocol;
    UINT8 HopLimit;
    UINT32 FlowLabel;
} EFI_IP6_OVERRIDE_DATA;
```

- **Protocol**: Protocol type override.
- **HopLimit**: Hop-Limit override.
- **FlowLabel**: Flow-Label override.

The information and flags in the override data structure will override default parameters or settings for one `Transmit()` function call.

#### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data has been queued for transmission.</td>
</tr>
</tbody>
</table>

(continued from previous page)
Table 28.40 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The IPv6 driver was responsible for choosing a source address for this trans-</td>
</tr>
<tr>
<td></td>
<td>mission, but no source address was available for use.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token.Event is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token.Packet.TxData is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token.Packet.ExtHdrsLength is not zero and</td>
</tr>
<tr>
<td></td>
<td>Token.Packet.ExtHdrs is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token.Packet.FragmentCount is zero.</td>
</tr>
<tr>
<td></td>
<td>• One or more of the</td>
</tr>
<tr>
<td></td>
<td>Token.Packet.TxDat.FragmentTable[].FragmentLength fields is zero.</td>
</tr>
<tr>
<td></td>
<td>• One or more of the Token.Packet.TxDat.FragmentTable[].FragmentBuffer</td>
</tr>
<tr>
<td></td>
<td>fields is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token.Packet.TxData.DataLength is zero or not equal to the sum of</td>
</tr>
<tr>
<td></td>
<td>fragment lengths.</td>
</tr>
<tr>
<td></td>
<td>• Token.Packet.TxData.DestinationAddress is non-zero when</td>
</tr>
<tr>
<td></td>
<td>DestinationAddress is configured as non-zero when doing Configure() for</td>
</tr>
<tr>
<td></td>
<td>this EFI IPv6 protocol instance.</td>
</tr>
<tr>
<td></td>
<td>• Token.Packet.TxData.DestinationAddress is unspecified when</td>
</tr>
<tr>
<td></td>
<td>DestinationAddress is unspecified when doing Configure() for this EFI</td>
</tr>
<tr>
<td></td>
<td>IPv6 protocol instance.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The transmit completion token with the same Token.Event was already in</td>
</tr>
<tr>
<td></td>
<td>the transmit queue.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The completion token could not be queued because the transmit queue is</td>
</tr>
<tr>
<td></td>
<td>full.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No route was found to destination address.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not queue the transmit data.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>Token.Packet.TxData.DataLength is too short to transmit.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>If Token.Packet.TxData.DataLength is beyond the maximum that which can</td>
</tr>
<tr>
<td></td>
<td>be described through the Fragment Offset field in Fragment header when</td>
</tr>
<tr>
<td></td>
<td>performing fragmentation.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

### 28.6.11 EFI_IP6_PROTOCOL.Receive()  

**Summary**

Places a receiving request into the receiving queue.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_IP6_RECEIVE) (
    IN EFI_IP6_PROTOCOL *This,
    ...
);  
```
IN EFI_IP6_COMPLETION_TOKEN *Token
);

Parameters

This

Pointer to the EFI_IP6_PROTOCOL instance.

Token

Pointer to a token that is associated with the receive data descriptor. Type EFI_IP6_COMPLETION_TOKEN is defined in “Related Definitions” of above Transmit().

Description

The Receive() function places a completion token into the receive packet queue. This function is always asynchronous.

The Token.Event field in the completion token must be filled in by the caller and cannot be NULL. When the receive operation completes, the EFI IPv6 Protocol driver updates the Token.Status and Token.Packet.RxData fields and the Token.Event is signaled.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The receive completion token was cached.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI IPv6 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When IP6 driver responsible for binding source address to this instance, while no source address is available for use.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>Token.Event is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The receive completion token could not be queued due to a lack of system resources (usually memory).</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The EFI IPv6 Protocol instance has been reset to startup defaults.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The receive completion token with the same Token.Event was already in the receive queue.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The receive request could not be queued because the receive queue is full.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

28.6.12 EFI_IP6_PROTOCOL.Cancel()

Summary

Abort an asynchronous transmits or receive request.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_IP6_CANCEL)(
    IN EFI_IP6_PROTOCOL *This,
);
Parameters

This

Pointer to the \texttt{EFI\_IP6\_PROTOCOL} instance.

Token

Pointer to a token that has been issued by \texttt{EFI\_IP6\_PROTOCOL.Transmit()} or \texttt{EFI\_IP6\_PROTOCOL.Receive()}. If \texttt{NULL}, all pending tokens are aborted. Type \texttt{EFI\_IP6\_COMPLETION\_TOKEN} is defined in \texttt{EFI\_IP6\_PROTOCOL.Transmit()}.

Description

The \texttt{Cancel()} function is used to abort a pending transmit or receive request. If the token is in the transmit or receive request queues, after calling this function, \texttt{Token->Status} will be set to \texttt{EFI\_ABORTED} and then \texttt{Token->Event} will be signaled. If the token is not in one of the queues, which usually means the asynchronous operation has completed, this function will not signal the token and \texttt{EFI\_NOT\_FOUND} is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\texttt{EFI_SUCCESS}</td>
<td>The asynchronous I/O request was aborted and \texttt{Token-&gt;Event} was signaled. When \texttt{Token} is \texttt{NULL}, all pending requests were aborted and their events were signaled.</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>\texttt{This} is \texttt{NULL}.</td>
</tr>
<tr>
<td>\texttt{EFI_NOT_STARTED}</td>
<td>This instance has not been started.</td>
</tr>
<tr>
<td>\texttt{EFI_NOT_FOUND}</td>
<td>When \texttt{Token} is not \texttt{NULL}, the asynchronous I/O request was not found in the transmit or receive queue. It has either completed or was not issued by \texttt{Transmit()} and \texttt{Receive()}.</td>
</tr>
<tr>
<td>\texttt{EFI_DEVICE_ERROR}</td>
<td>An unexpected system or network error occurred.</td>
</tr>
</tbody>
</table>

28.6.13 \texttt{EFI\_IP6\_PROTOCOL.Poll()}

Summary

Polls for incoming data packets and processes outgoing data packets.

Prototype

```c
typedef EFI_STATUS
(EFIAPIC *EFI\_IP6\_POLL) (     
    IN EFI\_IP6\_PROTOCOL *This    
);
```

Description

The \texttt{Poll()} function polls for incoming data packets and processes outgoing data packets. Network drivers and applications can call the \texttt{EFI\_IP6\_PROTOCOL.Poll()} function to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

In some systems the periodic timer event may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the \texttt{EFI\_IP6\_PROTOCOL.Poll()} function more often.
Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI IPv6 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>No incoming or outgoing data is processed.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Data was dropped out of the transmit and/or receive queue. Consider increas-ing the polling rate.</td>
</tr>
</tbody>
</table>

28.7 EFI IPv6 Configuration Protocol

This section provides a detailed description of the EFI IPv6 Configuration Protocol.

28.7.1 EFI_IP6_CONFIG_PROTOCOL

Summary

The EFI_IP6_CONFIG_PROTOCOL provides the mechanism to set and get various types of configurations for the EFI IPv6 network stack.

GUID

```c
#define EFI_IP6_CONFIG_PROTOCOL_GUID \
{0x937fe521,0x95ae,0x4d1a,\ 
 {0x89,0x29,0x48,0xbc,0xd9,0x0a,0xd3,0x1a}
```

Protocol Interface Structure

```c
typedef struct _EFI_IP6_CONFIG_PROTOCOL {
    EFI_IP6_CONFIG_SET_DATA SetData;
    EFI_IP6_CONFIG_GET_DATA GetData;
    EFI_IP6_CONFIG_REGISTER_NOTIFY RegisterDataNotify;
    EFI_IP6_CONFIG_UNREGISTER_NOTIFY UnregisterDataNotify;
} EFI_IP6_CONFIG_PROTOCOL;
```

Parameters

SetData
Set the configuration for the EFI IPv6 network stack running on the communication device this EFI IPv6 Configuration Protocol instance manages. See the `SetData()` function description.

GetData
Get the configuration or register an event to monitor the change of the configuration for the EFI IPv6 network stack running on the communication device this EFI IPv6 Configuration Protocol instance manages. See the `GetData()` function description.

RegisterDataNotify
Register an event that is to be signaled whenever a configuration process on the specified configuration data is done.

UnregisterDataNotify
Remove a previously registered event for the specified configuration data.
Description

The \textit{EFI_IP6_CONFIG_PROTOCOL} is designed to be the central repository for the common configurations and the
administrator configurable settings for the EFI IPv6 network stack.

An EFI IPv6 Configuration Protocol instance will be installed on each communication device that the EFI IPv6 network
stack runs on.

\textbf{28.7.2 EFI_IP6_CONFIG_PROTOCOL.SetData()}

Summary

Set the configuration for the EFI IPv6 network stack running on the communication device this EFI IPv6 Configuration
Protocol instance manages.

Prototype

\begin{verbatim}
typedef EFI_STATUS
  (EFIAPIC *EFI_IP6_CONFIG_SET_DATA) (  
  IN EFI_IP6_CONFIG_PROTOCOL *This,  
  IN EFI_IP6_CONFIG_DATA_TYPE DataType,  
  IN UINTN DataSize,  
  IN VOID *Data  
);  
\end{verbatim}

Parameters

\textbf{This} 

Pointer to the \textit{EFI_IP6_CONFIG_PROTOCOL} instance.

\textbf{DataType} 

The type of data to set. Type \textit{EFI_IP6_CONFIG_DATA_TYPE} is defined in “Related Definitions” below.

\textbf{DataSize} 

Size of the buffer pointed to by \textit{Data} in bytes.

\textbf{Data} 

The data buffer to set. The type of the data buffer is associated with the \textit{DataType}. The various types are defined
in “Related Definitions” below.

Description

This function is used to set the configuration data of type \textit{DataType} for the EFI IPv6 network stack running on the
communication device this EFI IPv6 Configuration Protocol instance manages.

The \textit{DataSize} is used to calculate the count of structure instances in the Data for some \textit{DataType} that multiple structure
instances are allowed.

This function is always non-blocking. When setting some type of configuration data, an asynchronous process is
invoked to check the correctness of the data, such as doing Duplicate Address Detection on the manually set local
IPv6 addresses. \textit{EFI_NOT_READY} is returned immediately to indicate that such an asynchronous process is invoked
and the process is not finished yet. The caller willing to get the result of the asynchronous process is required to call
\textit{RegisterDataNotify()} to register an event on the specified configuration data. Once the event is signaled, the caller can
call \textit{GetData()} to get back the configuration data in order to know the result. For other types of configuration data that
do not require an asynchronous configuration process, the result of the operation is immediately returned.

Related Definition
typedef enum {
    Ip6ConfigDataTypeInterfaceInfo,
    Ip6ConfigDataTypeAltInterfaceId,
    Ip6ConfigDataTypePolicy,
    Ip6ConfigDataTypeDupAddrDetectTransmits,
    Ip6ConfigDataTypeManualAddress,
    Ip6ConfigDataTypeGateway,
    Ip6ConfigDataTypeDnsServer,
    Ip6ConfigDataTypeMaximum
} EFI_IP6_CONFIG_DATA_TYPE;

Ip6ConfigDataTypeInterfaceInfo
The interface information of the communication device this EFI IPv6 Configuration Protocol instance manages. This type of data is read only. The corresponding Data is of type EFI_IP6_CONFIG_INTERFACE_INFO.

Ip6ConfigDataTypeAltInterfaceId
The alternative interface ID for the communication device this EFI IPv6 Configuration Protocol instance manages if the link local IPv6 address generated from the interfaced IP6 address based on the default source the EFI IPv6 Protocol uses is a duplicate address. The length of the interface ID is 64 bit. The corresponding Data is of type EFI_IP6_CONFIG_INTERFACE_ID.

Ip6ConfigDataTypePolicy
The general configuration policy for the EFI IPv6 network stack running on the communication device this EFI IPv6 Configuration Protocol instance manages. The policy will affect other configuration settings. The corresponding Data is of type EFI_IP6_CONFIG_POLICY.

Ip6ConfigDataTypeDupAddrDetectTransmits
The number of consecutive Neighbor Solicitation messages sent while performing Duplicate Address Detection on a tentative address. A value of zero indicates that Duplicate Address Detection will not be performed on tentative addresses. The corresponding Data is of type EFI_IP6_CONFIG_DUP_ADDR_DETECT_TRANSMITS.

Ip6ConfigDataTypeManualAddress
The station addresses set manually for the EFI IPv6 network stack. It is only configurable when the policy is Ip6ConfigPolicyManual. The corresponding Data is a pointer to an array of EFI_IPv6_ADDRESS instances. When DataSize is 0 and Data is NULL, the existing configuration is cleared from the EFI IPv6 Configuration Protocol instance.

Ip6ConfigDataTypeGateway
The gateway addresses set manually for the EFI IPv6 network stack running on the communication device this EFI IPv6 Configuration Protocol manages. It is not configurable when the policy is Ip6ConfigPolicyAutomatic. The gateway addresses must be unicast IPv6 addresses. The corresponding Data is a pointer to an array of EFI_IPv6_ADDRESS instances. When DataSize is 0 and Data is NULL, the existing configuration is cleared from the EFI IPv6 Configuration Protocol instance.

Ip6ConfigDataTypeDnsServer
The DNS server list for the EFI IPv6 network stack running on the communication device this EFI IPv6 Configuration Protocol manages. It is not configurable when the policy is Ip6ConfigPolicyAutomatic. The DNS server addresses must be unicast IPv6 addresses. The corresponding Data is a pointer to an array of EFI_IPv6_ADDRESS instances. When DataSize is 0 and Data is NULL, the existing configuration is cleared from the EFI IPv6 Configuration Protocol instance.
typedef struct {
    CHAR16 Name[32];
    UINT8 IfType;
    UINT32 HwAddressSize;
    EFI_MAC_ADDRESS HwAddress;
    UINT32 AddressInfoCount;
    EFI_IP6_ADDRESS_INFO *AddressInfo;
    UINT32 RouteCount;
    EFI_IP6_ROUTE_TABLE *RouteTable;
} EFI_IP6_CONFIG_INTERFACE_INFO;

Name
The name of the interface. It is a NULL-terminated string.

IfType
The interface type of the network interface. See RFC 3232, section “Number Hardware Type”.

HwAddressSize
The size, in bytes, of the network interface’s hardware address.

HwAddress
The hardware address for the network interface.

AddressInfoCount
Number of EFI_IP6_ADDRESS_INFO structures pointed to by AddressInfo.

AddressInfo
Pointer to an array of EFI_IP6_ADDRESS_INFO instances which contain the local IPv6 addresses and the corresponding prefix length information. Set to NULL if AddressInfoCount is zero. Type EFI_IP6_ADDRESS_INFO is defined in EFI_IP6_PROTOCOL.GetModeData().

RouteCount
Number of route table entries in the following RouteTable.

RouteTable
The route table of the IPv6 network stack runs on this interface. Set to NULL if RouteCount is zero. Type EFI_IP6_ROUTE_TABLE is defined in EFI_IP6_PROTOCOL.GetModeData().

The EFI_IP6_CONFIG_INTERFACE_INFO structure describes the operational state of the interface this EFI IPv6 Configuration Protocol instance manages. This type of data is read-only. When reading, the caller allocated buffer is used to return all of the data, i.e., the first part of the buffer is EFI_IP6_CONFIG_INTERFACE_INFO and the followings are the array of EFI_IP6_ADDRESS_INFO and the route table if present. The caller should NOT free the buffer pointed to by AddressInfo or RouteTable, and the caller is only required to free the whole buffer if the data is not needed any more.

//*****************************************************************************
// EFI_IP6_CONFIG_INTERFACE_ID
//*****************************************************************************
typedef struct {
    UINT8 Id[8];
} EFI_IP6_CONFIG_INTERFACE_ID;

The EFI_IP6_CONFIG_INTERFACE_ID structure describes the 64-bit interface ID.
//**************************************************
// EFI_IP6_CONFIG_POLICY
//**************************************************
typedef enum {
    Ip6ConfigPolicyManual,
    Ip6ConfigPolicyAutomatic
} EFI_IP6_CONFIG_POLICY;

Ip6ConfigPolicyManual
Under this policy, the Ip6ConfigDataTypeManualAddress, Ip6ConfigDataTypeGateway and Ip6ConfigDataTypeDnsServer configuration data are required to be set manually. The EFI IPv6 Protocol will get all required configuration such as address, prefix and gateway settings from the EFI IPv6 Configuration protocol.

Ip6ConfigPolicyAutomatic
Under this policy, the Ip6ConfigDataTypeManualAddress, Ip6ConfigDataTypeGateway and Ip6ConfigDataTypeDnsServer configuration data are not allowed to set via SetData(). All of these configurations are retrieved from some auto configuration mechanism. The EFI IPv6 Protocol will use the IPv6 stateless address autoconfiguration mechanism and/or the IPv6 stateful address autoconfiguration mechanism described in the related RFCs to get address and other configuration information.

The EFI_IP6_CONFIG_POLICY defines the general configuration policy the EFI IPv6 Configuration Protocol supports. The default policy for a newly detected communication device is beyond the scope of this document. An implementation might leave it to platform to choose the default policy.

The configuration data of type Ip6ConfigDataTypeManualAddress, Ip6ConfigDataTypeGateway and Ip6ConfigDataTypeDnsServer will be flushed if the policy is changed from Ip6ConfigPolicyManual to Ip6ConfigPolicyAutomatic.

//**************************************************
// EFI_IP6_CONFIG_DUP_ADDR_DETECT_TRANSMITS
//**************************************************
typedef struct {
    UINT32 DupAddrDetectTransmits;
} EFI_IP6_CONFIG_DUP_ADDR_DETECT_TRANSMITS;

The EFI_IP6_CONFIG_DUP_ADDR_DETECT_TRANSMITS structure describes the number of consecutive Neighbor Solicitation messages sent while performing Duplicate Address Detection on a tentative address. The default value for a newly detected communication device is 1.

//**************************************************
// EFI_IP6_CONFIG_MANUAL_ADDRESS
//**************************************************
typedef struct {
    EFI_IPv6_ADDRESS Address;
    BOOLEAN IsAnycast;
    UINT8 PrefixLength;
} EFI_IP6_CONFIG_MANUAL_ADDRESS;

Address
The IPv6 unicast address.

IsAnycast
Set to TRUE if Address is anycast.

PrefixLength
The length, in bits, of the prefix associated with this Address.

The EFI_IP6_CONFIG_MANUAL_ADDRESS structure is used to set the station address information for the EFI IPv6 network stack manually when the policy is Ip6ConfigPolicyManual.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The specified configuration data for the EFI IPv6 network stack is set successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• One or more fields in Data and DataSize do not match the requirement of the data type indicated by DataType.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>The specified configuration data is read-only or the specified configuration data can not be set under the current policy.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Another set operation on the specified configuration data is already in process.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>An asynchronous process is invoked to set the specified configuration data and the process is not finished yet.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>The DataSize does not match the size of the type indicated by DataType.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This DataType is not supported.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system error or network error occurred.</td>
</tr>
</tbody>
</table>

#### 28.7.3 EFI_IP6_CONFIG_PROTOCOL.GetData()

**Summary**

Get the configuration data for the EFI IPv6 network stack running on the communication device this EFI IPv6 Configuration Protocol instance manages.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPI *EFI_IP6_CONFIG_GET_DATA) (
    IN EFI_IP6_CONFIG_PROTOCOL *This,
    IN EFI_IP6_CONFIG_DATA_TYPE DataType,
    IN OUT UINTN *DataSize,
    IN VOID *Data OPTIONAL
);
```

**Parameters**

**This**

Pointer to the EFI_IP6_CONFIG_PROTOCOL instance.

**DataType**

The type of data to get. Type EFI_IP6_CONFIG_DATA_TYPE is defined in EFI_IP6_CONFIG_PROTOCOL.SetData().

**DataSize**

On input, in bytes, the size of Data. On output, in bytes, the size of buffer required to store the specified configuration data.
Data
The data buffer in which the configuration data is returned. The type of the data buffer is associated with the
DataType. Ignored if DataSize is 0. The various types are defined in EFI_IP6_CONFIG_PROTOCOL.SetData().

Description
This function returns the configuration data of type DataType for the EFI IPv6 network stack running on the commu-
nication device this EFI IPv6 Configuration Protocol instance manages.

The caller is responsible for allocating the buffer used to return the specified configuration data and the required size
will be returned to the caller if the size of the buffer is too small.

EFI_NOT_READY is returned if the specified configuration data is not ready due to an already in progress asyn-
chronous configuration process. The caller can call RegisterDataNotify() to register an event on the specified config-
uration data. Once the asynchronous configuration process is finished, the event will be signaled and a subsequent
GetData() call will return the specified configuration data.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The specified configuration data is got successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the followings are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• DataSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL if * DataSize is not zero.</td>
</tr>
<tr>
<td>EFIBUFFER_TOO_SMALL</td>
<td>The size of Data is too small for the specified configuration data and the</td>
</tr>
<tr>
<td></td>
<td>required size is returned in DataSize.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The specified configuration data is not ready due to an already in progress</td>
</tr>
<tr>
<td></td>
<td>asynchronous configuration process.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified configuration data is not found.</td>
</tr>
</tbody>
</table>

28.7.4 EFI_IP6_CONFIG_PROTOCOL.RegisterTypeNotify()

Summary
Register an event that is to be signaled whenever a configuration process on the specified configuration data is done.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_IP6_CONFIG_REGISTER_NOTIFY) (  
    IN EFI_IP6_CONFIG_PROTOCOL   *This,
    IN EFI_IP6_CONFIG_DATA_TYPE  DataType,
    IN EFI_EVENT                Event
);  

Parameters

This
Pointer to the EFI_IP6_CONFIG_PROTOCOL instance.

DataType
The type of data to unregister the event for. Type EFI_IP6_CONFIG_DATA_TYPE is defined in
EFI_IP6_CONFIG_PROTOCOL.SetData().
Event
The event to register.

Description
This function registers an event that is to be signaled whenever a configuration process on the specified configuration data is done. An event can be registered for different DataType simultaneously and the caller is responsible for determining which type of configuration data causes the signaling of the event in such case.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The notification event for the specified configuration data is registered.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL or Event is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The configuration data type specified by DataType is not supported.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The Event is already registered for the DataType.</td>
</tr>
</tbody>
</table>

28.7.5 EFI_IP6_CONFIG_PROTOCOL.UnregisterDataNotify()

Summary
Remove a previously registered event for the specified configuration data.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_IP6_CONFIG_UNREGISTER_NOTIFY) (    
    IN EFI_IP6_CONFIG_PROTOCOL *This, 
    IN EFI_IP6_CONFIG_DATA_TYPE DataType, 
    IN EFI_EVENT Event 
);```

Parameters

This
Pointer to the EFI_IP6_CONFIG_PROTOCOL instance.

DataType
The type of data to remove the previously registered event for. Type EFI_IP6_CONFIG_DATA_TYPE is defined in EFI_IP6_CONFIG_PROTOCOL.SetD ata().

Event
The event to unregister.

Description
This function removes a previously registered event for the specified configuration data.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The event registered for the specified configuration data is removed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL or Event is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The event has not been registered for the specified DataType.</td>
</tr>
</tbody>
</table>
28.8 IPsec

28.8.1 IPsec Overview

IPsec is a framework of open standards that provides data confidentiality, data integrity, data authentication and replay protection between participating peers. A set of security services is provided by IPsec for traffic at the IP layer, in both the IPv4 and IPv6 environment. To the stronger, IPV6 requires IPSec support.

IPsec is documented in a series of Internet RFCs. The overall IPsec architecture and implementation are guided by “Security Architecture for the Internet Protocol”, RFC 4301.

Two different security protocols - Authentication Header (AH, described in RFC 4302) and Encapsulated Security Payload (ESP, described in RFC 4303) - are used to provide package-level security for IP datagram.

This section attempts to capture the generic configuration for an IPsec implementation in an EFI environment.

28.8.2 EFI IPsec Configuration Protocol

This section provides a detailed description of the EFI IPsec Configuration Protocol. This protocol sets and obtains the IPsec configuration information.

28.8.3 EFI_IPSEC_CONFIG_PROTOCOL

Summary

The EFI_IPSEC_CONFIG_PROTOCOL provides the mechanism to set and retrieve security and policy related information for the EFI IPsec protocol driver.

GUID

```
#define EFI_IPSEC_CONFIG_PROTOCOL_GUID \
{0xce5e5929,0xc7a3,0x4602,\ 
 {0xad,0x9e,0xc9,0xda,0xf9,0x4e,0xbf,0xcf}}
```

Protocol Interface Structure

```
typedef struct _EFI_IPSEC_CONFIG_PROTOCOL {
    EFI_IPSEC_CONFIG_SET_DATA       SetData;
    EFI_IPSEC_CONFIG_GET_DATA       GetData;
    EFI_IPSEC_CONFIG_GET_NEXT_SELECTOR GetDataNext;
    EFI_IPSEC_CONFIG_REGISTER_NOTIFY RegisterDataNotify;
    EFI_IPSEC_CONFIG_UNREGISTER_NOTIFY UnregisterDataNotify;
} EFI_IPSEC_CONFIG_PROTOCOL;
```

Parameters

SetData

Set the configuration and control information for the EFI IPsec protocol driver. See the SetData() function description.

GetData

Look up and retrieve the IPsec configuration data. See the GetData() function description.

GetNextSelector

Enumerates the current IPsec configuration data entry selector. See the GetNextSelector() function description.
RegisterNotify
Register an event that is to be signaled whenever a configuration process on the specified IPsec configuration data is done.

UnregisterNotify
Remove a registered event for the specified IPsec configuration data.

Description
The `EFI_IPSEC_CONFIG_PROTOCOL` provides the ability to set and lookup the IPsec SAD (Security Association Database), SPD (Security Policy Database) data entry and configure the security association management protocol such as IKEv2. This protocol is used as the central repository of any policy-specific configuration for EFI IPsec driver.

`EFI_IPSEC_CONFIG_PROTOCOL` can be bound to both IPv4 and IPv6 stack. User can use this protocol for IPsec configuration in both IPv4 and IPv6 environment.

28.8.4 `EFI_IPSEC_CONFIG_PROTOCOL.SetData()`

Summary
Set the security association, security policy and peer authorization configuration information for the EFI IPsec driver.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_IPSEC_CONFIG_SET_DATA) (
    IN EFI_IPSEC_CONFIG_PROTOCOL *This,
    IN EFI_IPSEC_CONFIG_DATA_TYPE DataType,
    IN EFI_IPSEC_CONFIG_SELECTOR *Selector
    IN VOID *Data
    IN EFI_IPSEC_CONFIG_SELECTOR *InsertBefore OPTIONAL
);
```

Parameters

This
Pointer to the `EFI_IPSEC_CONFIG_PROTOCOL` instance.

InsertBefore
Pointer to one entry selector which describes the expected position the new data entry will be added. If `InsertBefore` is `NULL`, the new entry will be appended the end of database.

DataType
The type of data to be set. Type `EFI_IPSEC_CONFIG_DATA_TYPE` is defined in “Related Definitions” below.

Selector
Pointer to an entry selector on operated configuration data specified by `DataType`. A `NULL` `Selector` causes the entire specified-type configuration information to be flushed.

Data
The data buffer to be set. The structure of the data buffer is associated with the `DataType`. The various types are defined in “Related Definitions” below.

Description
This function is used to set the IPsec configuration information of type `DataType` for the EFI IPsec driver.

The IPsec configuration data has a unique selector/identifier separately to identify a data entry. The selector structure depends on `DataType`'s definition.
Using `SetData()` with a `Data` of `NULL` causes the IPsec configuration data entry identified by `DataType` and `Selector` to be deleted.

**Related Definition**

```c
typedef enum {
    IPsecConfigDataTypeSpd,
    IPsecConfigDataTypeSad,
    IPsecConfigDataTypePad,
    IPsecConfigDataTypeMaximum
} EFI_IPSEC_CONFIG_DATA_TYPE;
```

**IPsecConfigDataSpd**

The IPsec Security Policy Database (aka SPD) setting. In IPsec, an essential element of Security Association (SA) processing is underlying SPD that specifies what services are to be offered to IP datagram and in what fashion. The SPD must be consulted during the processing of all traffic (inbound and outbound), including traffic not protected by IPsec, that traverse the IPsec boundary. With this `DataType`, `SetData()` function is to set the SPD entry information, which may add one new entry, delete one existed entry or flush the whole database according to the parameter values. The corresponding Data is of type `EFI_IPSEC_SPD_DATA`.

**IPsecConfigDataSad**

The IPsec Security Association Database (aka SAD) setting. A SA is a simplex connection that affords security services to the traffic carried by it. Security services are afforded to an SA by the use of AH, or ESP, but not both. The corresponding Data is of type `EFI_IPSEC_SA_DATA2` or `EFI_IPSEC_SAD_DATA`. Compared with `EFI_IPSEC_SA_DATA`, the `EFI_IPSEC_SA_DATA2` contains the extra Tunnel Source Address and Tunnel Destination Address thus it is recommended to be use if the implementation supports tunnel mode.

**IPsecConfigDataPad**

The IPsec Peer Authorization Database (aka PAD) setting, which provides the link between the SPD and a security association management protocol. The PAD entry specifies the authentication protocol (e.g. IKEv1, IKEv2) method used and the authentication data. The corresponding `Data` is of type `EFI_IPSEC_PAD_DATA`.

```c
typedef union {
    EFI_IPSEC_SPD_SELECTOR SpdSelector;
    EFI_IPSEC_SA_ID SaId;
    EFI_IPSEC_PAD_ID PadId;
} EFI_IPSEC_CONFIG_SELECTOR;
```

The `EFI_IPSEC_CONFIG_SELECTOR` describes the expected IPsec configuration data selector of type `EFI_IPSEC_CONFIG_DATA_TYPE`.

```c
typedef struct _EFI_IPSEC_SPD_SELECTOR {
    UINT32 LocalAddressCount;
    EFI_IP_ADDRESS_INFO *LocalAddress;
    UINT32 RemoteAddressCount;
    EFI_IP_ADDRESS_INFO *RemoteAddress;
} EFI_IPSEC_SPD_SELECTOR;
```
UINT16 NextLayerProtocol;

// Several additional selectors depend on the ProtoFamily
UINT16 LocalPort;
UINT16 LocalPortRange;
UINT16 RemotePort;
UINT16 RemotePortRange;
} EFI_IPSEC_SPD_SELECTOR;

LocalAddressCount
Specifies the actual number of entries in LocalAddress.

LocalAddress
A list of ranges of IPv4 or IPv6 addresses, which refers to the addresses being protected by IPsec policy.

RemoteAddressCount
Specifies the actual number of entries in RemoteAddress.

RemoteAddress
A list of ranges of IPv4 or IPv6 addresses, which are peer entities to LocalAddress.

NextLayerProtocol
Next layer protocol. Obtained from the IPv4 Protocol or the IPv6 Next Header fields. The next layer protocol is whatever comes after any IP extension headers that are present. A zero value is a wildcard that matches any value in NextLayerProtocol field.

LocalPort
Local Port if the Next Layer Protocol uses two ports (as do TCP, UDP, and others). A zero value is a wildcard that matches any value in LocalPort field.

LocalPortRange
A designed port range size. The start port is LocalPort, and the total number of ports is described by LocalPortRange. This field is ignored if NextLayerProtocol does not use ports.

RemotePort
Remote Port if the Next Layer Protocol uses two ports. A zero value is a wildcard that matches any value in RemotePort field.

RemotePortRange
A designed port range size. The start port is RemotePort, and the total number of ports is described by RemotePortRange. This field is ignored if NextLayerProtocol does not use ports.

NOTE: The LocalPort and RemotePort selectors have different meaning depending on the NextLayerProtocol field. For example, if NextLayerProtocol value is ICMP, LocalPort and RemotePort describe the ICMP message type and code. This is described in section 4.4.1.1 of RFC 4301).

//****************************************************
// EFI_IP_ADDRESS_INFO
//****************************************************
typedef struct _EFI_IP_ADDRESS_INFO {
  EFI_IP_ADDRESS Address;
  UINT8 PrefixLength;
} EFI_IP_ADDRESS_INFO;

Address
The IPv4 or IPv6 address.
PrefixLength
The length of the prefix associated with the Address.

#define MAX_PEERID_LEN 128
OSTEXT_STRINGLIKE
PrefixLength defines the length of the prefix associated with an Address.

typedef struct _EFI_IPSEC_SPD_DATA {
  UINT8 *Name[MAX_PEERID_LEN];
  UINT32 PackageFlag;
  EFI_IPSEC_TRAFFIC_DIR TrafficDirection;
  EFI_IPSEC_ACTION Action;
  EFI_IPSEC_PROCESS_POLICY *ProcessingPolicy;
  UINTN SaIdCount;
  EFI_IPSEC_SA_ID *SaId[1];
} EFI_IPSEC_SPD_DATA;

Name
A null-terminated ASCII name string which is used as a symbolic identifier for an IPsec Local or Remote address. The Name is optional, and can be NULL.

PackageFlag
Bit-mapped list describing Populate from Packet flags. When creating a SA, if PackageFlag bit is set to TRUE, instantiate the selector from the corresponding field in the package that triggered the creation of the SA, else from the value(s) in the corresponding SPD entry. The PackageFlag bit setting for corresponding selector field of EFI_IPSEC_SPD_SELECTOR:

Bit 0: EFI_IPSEC_SPD_SELECTOR. LocalAddress
Bit 1: EFI_IPSEC_SPD_SELECTOR. RemoteAddress
Bit 2: EFI_IPSEC_SPD_SELECTOR. NextLayerProtocol
Bit 3: EFI_IPSEC_SPD_SELECTOR. LocalPort
Bit 4: EFI_IPSEC_SPD_SELECTOR. RemotePort
Others: Reserved.

TrafficDirection
The traffic direction of data gram.

Action
Processing choices to indicate which action is required by this policy.

ProcessingPolicy
The policy and rule information for a SPD entry. The type EFI_IPSEC_PROCESSPOLICY is defined in below.

SaIdCount
Specifies the actual number of entries in SaId list.

SaId
Pointer to the SAD entry used for the traffic processing. The existed SAD entry links indicate this is the manual key case.
typedef enum {
    EfiIPsecInBound,
    EfiIPsecOutBound
} EFI_IPSEC_TRAFFIC_DIR;

The `EFI_IPSEC_TRAFFIC_DIR` represents the directionality in an SPD entry. The `EfiIPsecInBound` refers to traffic entering an IPsec implementation via the unprotected interface or emitted by the implementation on the unprotected side of the boundary and directed towards the protected interface. The `EfiIPsecOutBound` refers to traffic entering the implementation via the protected interface, or emitted by the implementation on the protected side of the boundary and directed toward the unprotected interface.

```
//******************************************************************************
// EFI_IPSEC_ACTION
//******************************************************************************
typedef enum {
    EfiIPsecActionDiscard,
    EfiIPsecActionBypass,
    EfiIPsecActionProtect
} EFI_IPSEC_ACTION;
```

For any inbound or outbound datagram, `EFI_IPSEC_ACTION` represents three possible processing choices:

**EfiIPsecActionDiscard**
- Refers to traffic that is not allowed to traverse the IPsec boundary (in the direction specified by `EFI_IPSEC_TRAFFIC_DIR`);

**EfiIPsecActionByPass**
- Refers to traffic that is allowed to cross the IPsec boundary without protection.

**EfiIPsecActionProtect**
- Refers to traffic that is afforded IPsec protection, and for such traffic the SPD must specify the security protocols to be employed, their mode, security service options, and the cryptographic algorithms to be used.

```
//******************************************************************************
// EFI_IPSEC_PROCESS_POLICY
//******************************************************************************
typedef struct _EFI_IPSEC_PROCESS_POLICY {
    BOOLEAN           ExtSeqNum;
    BOOLEAN           SeqOverflow;
    BOOLEAN           FragCheck;
    EFI_IPSEC_SA_LIFETIME  SaLifetime;
    EFI_IPSEC_MODE        Mode;
    EFI_IPSEC_TUNNEL_OPTION *TunnelOption;
    EFI_IPSEC_PROTOCOL_TYPE  Proto;
    UINT8               AuthAlgoId;
    UINT8               EncAlgoId;
} EFI_IPSEC_PROCESS_POLICY;
```

If required action of an SPD entry is `EfiIPsecActionProtect`, the `EFI_IPSEC_PROCESS_POLICY` structure describes a policy list for traffic processing.

**ExtSeqNum**
- Extended Sequence Number. Is this SA using extended sequence numbers. 64 bit counter is used if `TRUE`.

**SeqOverflow**
- A flag indicating whether overflow of the sequence number counter should generate an auditable event and
prevent transmission of additional packets on the SA, or whether rollover is permitted.

**FragCheck**
Is this SA using stateful fragment checking. **TRUE** represents stateful fragment checking.

**SaLifetime**
A time interval after which a SA must be replaced with a new SA (and new SPI) or terminated. The type **EFI_IPSEC_SA_LIFETIME** is defined in below.

**Mode**
IPsec mode: tunnel or transport

**TunnelOption**
Tunnel Option. **TunnelOption** is ignored if Mode is **EfiIPsecTransport**. The type **EFI_IPSEC_TUNNEL_OPTION** is defined in below

**Proto**
IPsec protocol: AH or ESP

**AuthAlgoId**
Cryptographic algorithm type used for authentication

**EncAlgoId**
Cryptographic algorithm type used for encryption. **EncAlgo** is **NULL** when IPsec protocol is AH. For ESP protocol, **EncAlgo** can also be used to describe the algorithm if a combined mode algorithm is used.

```c
typedef struct _EFI_IPSEC_SA_LIFETIME {
    UINT64 ByteCount;
    UINT64 SoftLifetime;
    UINT64 HardLifetime
} EFI_IPSEC_SA_LIFETIME;
```

**EFI_IPSEC_SA_LIFETIME** defines the lifetime of an SA, which represents when a SA must be replaced or terminated. A value of all 0 for each field removes the limitation of a SA lifetime.

**ByteCount**
The number of bytes to which the IPsec cryptographic algorithm can be applied. For ESP, this is the encryption algorithm and for AH, this is the authentication algorithm. The **ByteCount** includes pad bytes for cryptographic operations.

**SoftLifetime**
A time interval in second that warns the implementation to initiate action such as setting up a replacement SA.

**HardLifetime**
A time interval in second when the current SA ends and is destroyed.

```c
typedef enum {
    EfiIPsecTransport,
    EfiIPsecTunnel
} EFI_IPSEC_MODE;
```

There are two modes of IPsec operation: transport mode and tunnel mode. In **EfiIPsecTransport** mode, AH and ESP provide protection primarily for next layer protocols; In **EfiIPsecTunnel** mode, AH and ESP are applied to tunneled IP
The option of copying the DF bit from an outbound package to the tunnel mode header that it emits, when traffic is carried via a tunnel mode SA. This applies to SAs where both inner and outer headers are IPv4. The value can be:

**EfiIPsecTunnelClearDf:**
Clear DF bit from inner header

**EfiIPsecTunnelSetDf:**
Set DF bit from inner header

**EfiIPsecTunnelCopyDf:**
Copy DF bit from inner header

---

LocalTunnelAddress
Local tunnel address when IPsec mode is **EfiIPsecTunnel**

RemoteTunnelAddress
Remote tunnel address when IPsec mode is **EfiIPsecTunnel**

DF
The option of copying the DF bit from an outbound package to the tunnel mode header that it emits, when traffic is carried via a tunnel mode SA.

---

IPsec protocols definition. **EfiIPsecAH** is the IP Authentication Header protocol which is specified in RFC 4302. **EfiIPsecESP** is the IP Encapsulating Security Payload which is specified in RFC 4303.

---

(continues on next page)
A triplet to identify an SA, consisting of the following members:

**Spi**
Security Parameter Index (aka SPI). An arbitrary 32-bit value that is used by a receiver to identity the SA to which an incoming package should be bound.

**Proto**
IPsec protocol: AH or ESP

**DestAddress**
Destination IP address.

```c
typedef struct _EFI_IPSEC_SA_DATA {
  EFI_IPSEC_MODE Mode;
  UINT64 SNCount;
  UINT8 AntiReplayWindows;
  EFI_IPSEC_ALGO_INFO AlgoInfo;
  EFI_IPSEC_SA_LIFETIME SaLifetime;
  UINT32 PathMTU;
  EFI_IPSEC_SPD_SELECTOR *SpdSelector;
  BOOLEAN ManualSet
} EFI_IPSEC_SA_DATA;
```

The data items defined in one SAD entry:

**Mode**
IPsec mode: tunnel or transport

**SNCount**
Sequence Number Counter. A 64-bit counter used to generate the sequence number field in AH or ESP headers.

**ReplayWindows**
Anti-Replay Window. A 64-bit counter and a bit-map used to determine whether an inbound AH or ESP packet is a replay.

**AlgoInfo**
AH/ESP cryptographic algorithm, key and parameters.

**SaLifeTime**
Lifetime of this SA.

**PathMTU**
Any observed path MTU and aging variables. The Path MTU processing is defined in section 8 of RFC 4301.

**SpdSelector**
Link to one SPD entry.

**ManualSet**
Indication of whether it’s manually set or negotiated automatically. If `ManualSet` is `FALSE`, the corresponding SA entry is inserted through IKE protocol negotiation.
The data items defined in one SAD entry:

**Mode**
IPsec mode: tunnel or transport

**SNCount**
Sequence Number Counter. A 64-bit counter used to generate the sequence number field in AH or ESP headers.

**ReplayWindows**
Anti-Replay Window. A 64-bit counter and a bit-map used to determine whether an inbound AH or ESP packet is a replay.

**AlgoInfo**
AH/ESP cryptographic algorithm, key and parameters.

**SaLifeTime**
Lifetime of this SA.

**PathMTU**
Any observed path MTU and aging variables. The Path MTU processing is defined in section 8 of RFC 4301.

**SpdSelector**
Link to one SPD entry.

**ManualSet**
Indication of whether it’s manually set or negotiated automatically. If ManualSet is **FALSE**, the corresponding SA entry is inserted through IKE protocol negotiation.

**TunnelSourceAddress**
The tunnel header IP source address.

**TunnelDestinationAddress**
The tunnel header IP destination address.
The security algorithm selection for IPsec AH authentication. The required authentication algorithm is specified in RFC 4305.

The security algorithm selection for IPsec ESP encryption and authentication. The required authentication algorithm is specified in RFC 4305. EncAlgoId fields can also specify an ESP combined mode algorithm (e.g. AES with CCM mode, specified in RFC 4309), which provides both confidentiality and authentication services.

The entry selector for IPsec PAD that represents how to authenticate each peer. EFI_IPSEC_PAD_ID specifies the identifier for PAD entry, which is also used for SPD lookup.

**IpAddress**

Pointer to the IPv4 or IPv6 address range.

**PeerId**

Pointer to a null-terminated ASCII string representing the symbolic names. A PeerId can be a DNS name, Distinguished Name, RFC 822 email address or Key ID (specified in section 4.4.3.1 of RFC 4301)
The data items defined in one PAD entry:

**AuthProtocol**

Authentication Protocol for IPsec security association management

**AuthMethod**

Authentication method used.

**IkeIdFlag**

The IKE ID payload will be used as a symbolic name for SPD lookup if IkeIdFlag is **TRUE**. Otherwise, the remote IP address provided in traffic selector payloads will be used.

**AuthDataSize**

The size of Authentication data buffer, in bytes.

**AuthData**

Buffer for Authentication data, (e.g., the pre-shared secret or the trust anchor relative to which the peer’s certificate will be validated).

**RevocationDataSize**

The size of RevocationData, in bytes.

**RevocationData**

Pointer to CRL or OCSP data, if certificates are used for authentication method.

```c
typedef enum {
    EfiIPsecAuthProtocolIKEv1,
    EfiIPsecAuthProtocolIKEv2,
    EfiIPsecAuthProtocolMaximum
} EFI_IPSEC_AUTH_PROTOCOL_TYPE;
```

**EFI_IPSEC_AUTH_PROTOCOL_TYPE** defines the possible authentication protocol for IPsec security association management.

```c
typedef enum {
    EfiIPsecAuthMethodPreSharedSecret,
    EfiIPsecAuthMethodCertificates,
    EfiIPsecAuthMethodMaximum
} EFI_IPSEC_AUTH_METHOD;
```

**EfiIPsecAuthMethodPreSharedSecret**

Using Pre-shared Keys for manual security associations.
**EfiIPsecAuthMethodCertificates**
IKE employs X.509 certificates for SA establishment.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The specified configuration entry data is set successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The specified <em>DataType</em> is not supported.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The required system resource could not be allocated.</td>
</tr>
</tbody>
</table>

28.8.5 **EFI_IPSEC_CONFIG_PROTOCOL.GetData()**

**Summary**
Return the configuration value for the EFI IPsec driver.

**Prototype**
```
typedef EFI_STATUS
(EFI_API *EFI_IPSEC_CONFIG_GET_DATA) (    
    IN EFI_IPSEC_CONFIG_PROTOCOL *This, 
    IN EFI_IPSEC_CONFIG_DATA_TYPE DataType, 
    IN EFI_IPSEC_CONFIG_SELECTOR *Selector, 
    IN UINTN *DataSize, 
    OUT VOID *Data 
);
```

**Parameters**

**This**
Pointer to the *EFI_IPSEC_CONFIG_PROTOCOL* instance.

**DataType**
The type of data to retrieve. Type

\[ EFI_IPSEC_CONFIG_DATA_TYPE \] is defined in \[ EFI_IPSEC_CONFIG_PROTOCOL.SetData() \].

**Selector**
Pointer to an entry selector which is an identifier of the IPsec configuration data entry. Type

\[ EFI_IPSEC_CONFIG_SELECTOR \] is defined in the \[ EFI_IPSEC_CONFIG_PROTOCOL.SetData() \] function description.

**DataSize**
On output the size of data returned in *Data*. 
Data
The buffer to return the contents of the IPsec configuration data. The type of the data buffer is associated with the *DataType*.

Description
This function lookup the data entry from IPsec database or IKEv2 configuration information. The expected data type and unique identification are described in *DataType* and *Selector* parameters.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The specified configuration data is got successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the followings are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• <em>This</em> is NULL.</td>
</tr>
<tr>
<td></td>
<td>• <em>Selector</em> is NULL.</td>
</tr>
<tr>
<td></td>
<td>• <em>DataSize</em> is NULL.</td>
</tr>
<tr>
<td></td>
<td>• <em>Data</em> is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The configuration data specified by <em>Selector</em> is not found.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The specified <em>DataType</em> is not supported.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The <em>DataSize</em> is too small for the result. <em>DataSize</em> has been updated with the size needed to complete the request.</td>
</tr>
</tbody>
</table>

28.8.6 EFI_IPSEC_CONFIG_PROTOCOL.GetNextSelector()

Summary
Enumerates the current selector for IPsec configuration data entry.

Prototype

```c
typedef EFI_STATUS
(EFI_API *EFI_IPSEC_CONFIG_GET_NEXT_SELECTOR) (  
  IN EFI_IPSEC_CONFIG_PROTOCOL *This,  
  IN EFI_IPSEC_CONFIG_DATA_TYPE DataType,  
  IN OUT UINTN *SelectorSize,  
  IN OUT EFI_IPSEC_CONFIG_SELECTOR *Selector,  
  );
```

Parameters

This
Pointer to the *EFI_IPSEC_CONFIG_PROTOCOL* instance.

DataType
The type of IPsec configuration data to retrieve. Type *EFI_IPSEC_CONFIG_DATA_TYPE* is defined in *EFI_IPSEC_CONFIG_PROTOCOL.SetData()*.

SelectorSize
The size of the *Selector* buffer.

Selector
On input, supplies the pointer to last *Selector* that was returned by GetNextSelector(). On output, returns one
copy of the current entry Selector of a given DataType. Type EFI_IPSEC_CONFIG_SELECTOR is defined in the EFI_IPSEC_CONFIG_PROTOCOL.SetData() function description.

Description
This function is called multiple times to retrieve the entry Selector in IPsec configuration database. On each call to GetNextSelector(), the next entry Selector are retrieved into the output interface. If the entire IPsec configuration database has been iterated, the error EFI_NOT_FOUND is returned. If the Selector buffer is too small for the next Selector copy, an EFI_BUFFER_TOO_SMALL error is returned, and SelectorSize is updated to reflect the size of buffer needed.

On the initial call to GetNextSelector() to start the IPsec configuration database search, a pointer to the buffer with all zero value is passed in Selector. Calls to SetData() between calls to GetNextSelector may produce unpredictable results.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The specified configuration data is got successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the followings are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• SelectorSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Selector is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The next configuration data entry was not found.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The specified DataType is not supported.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The SelectorSize is too small for the result. This parameter has been updated with the size needed to complete the search request.</td>
</tr>
</tbody>
</table>

28.8.7 EFI_IPSEC_CONFIG_PROTOCOL.RegisterDataNotify ()

Summary
Register an event that is to be signaled whenever a configuration process on the specified IPsec configuration information is done.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_IPSEC_CONFIG_REGISTER_NOTIFY) (
    IN EFI_IPSEC_CONFIG_PROTOCOL *This,
    IN EFI_IPSEC_CONFIG_DATA_TYPE DataType,
    IN EFI_EVENT Event
);

Parameters
This
Pointer to the EFI_IPSEC_CONFIG_PROTOCOL instance.

DataType
The type of data to be registered the event for. Type EFI_IPSEC_CONFIG_DATA_TYPE is defined in EFI_IPSEC_CONFIG_PROTOCOL.SetData() function description.
Event

The event to be registered.

Description

This function registers an event that is to be signaled whenever a configuration process on the specified IPsec configuration data is done (e.g., IPsec security policy database configuration is ready). An event can be registered for different DataType simultaneously and the caller is responsible for determining which type of configuration data causes the signaling of the event in such case.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The event is registered successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL or Event is NULL.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The Event is already registered for the DataType.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The notify registration unsupported or the specified DataType is not supported.</td>
</tr>
</tbody>
</table>

28.8.8 EFI_IPSEC_CONFIG_PROTOCOL.UnregisterDataNotify()

Summary

Remove the specified event that is previously registered on the specified IPsec configuration data.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_IPSEC_CONFIG_UNREGISTER_NOTIFY) (
    IN EFI_IPSEC_CONFIG_PROTOCOL *This,
    IN EFI_IPSEC_CONFIG_DATA_TYPE DataType,
    IN EFI_EVENT Event
);
```

Parameters

This

Pointer to the EFI_IPSEC_CONFIG_PROTOCOL instance.

DataType

The configuration data type to remove the registered event for. Type EFI_IPSEC_CONFIG_DATA_TYPE is defined in EFI_IPSEC_CONFIG_PROTOCOL.SetData() function description.

Event

The event to be unregistered.

Description

This function removes a previously registered event for the specified configuration data.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The event is removed successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The Event specified by DataType could not be found in the database.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL or Event is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The notify registration unsupported or the specified DataType is not supported.</td>
</tr>
</tbody>
</table>

28.8. IPsec
28.8.9 EFI IPsec Protocol

This section provides a detailed description of the EFI_IPSEC_PROTOCOL. This protocol handles IPsec-protected traffic.*

28.8.10 EFI_IPSEC_PROTOCOL

Summary

The EFI_IPSEC_PROTOCOL is used to abstract the ability to deal with the individual packets sent and received by the host and provide packet-level security for IP datagram.

GUID

```
#define EFI_IPSEC_PROTOCOL_GUID \
{0xdfb386f7,0xe100,0x43ad,\ 
 {0x9c,0x9a,0xed,0x90,0xd0,0x8a,0x5e,0x12 }}
```

Protocol Interface Structure

```
typedef struct _EFI_IPSEC_PROTOCOL {
    EFI_IPSEC_PROCESS Process;
    EFI_EVENT DisabledEvent;
    BOOLEAN DisabledFlag;
} EFI_IPSEC_PROTOCOL;
```

Parameters

Process

Handle the IPsec message.

DisabledEvent

Event signaled when the interface is disabled.

DisabledFlag

State of the interface.

Description

The EFI_IPSEC_PROTOCOL provides the ability for securing IP communications by authenticating and/or encrypting each IP packet in a data stream.

EFI_IPSEC_PROTOCOL can be consumed by both the IPv4 and IPv6 stack. A user can employ this protocol for IPsec package handling in both IPv4 and IPv6 environment.

28.8.11 EFI_IPSEC_PROTOCOL.Process()

Summary

Handles IPsec packet processing for inbound and outbound IP packets.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_IPSEC_PROCESS) ( 
    IN EFI_IPSEC_PROTOCOL *This,
```

(continues on next page)
\section*{Uniform Extensible Firmware Interface (UEFI) Specification, Release 2.9A}

\begin{verbatim}
IN EFI_HANDLE NicHandle,
IN UINT8 IpVer,
IN OUT VOID *IpHead,
IN UINT8 *LastHead,
IN VOID *OptionsBuffer,
IN UINT32 OptionsLength,
IN OUT EFI_IPSEC_FRAGMENT_DATA **FragmentTable,
IN UINT32 *FragmentCount,
IN EFI_IPSEC_TRAFFIC_DIR TrafficDirection,
OUT EFI_EVENT *RecycleSignal
);
\end{verbatim}

\textbf{Related Definition}

```c
typedef struct _EFI_IPSEC_FRAGMENT_DATA {
    UINT32 FragmentLength;
    VOID *FragmentBuffer;
} EFI_IPSEC_FRAGMENT_DATA;
```

\textit{EFI_IPSEC_FRAGMENT_DATA} defines the instances of packet fragments.

\textbf{This}

Pointer to the \textit{EFI_IPSEC_PROTOCOL} instance.

\textbf{NicHandle}

Instance of the network interface.

\textbf{IpVer}

IPV4 or IPV6.

\textbf{IpHead}

Pointer to the IP Header.

\textbf{LastHead}

The protocol of the next layer to be processed by IPsec.

\textbf{OptionsBuffer}

Pointer to the options buffer.

\textbf{OptionsLength}

Length of the options buffer.

\textbf{FragmentTable}

Pointer to a list of fragments.

\textbf{FragmentCount}

Number of fragments.

\textbf{TrafficDirection}

Traffic direction.

\textbf{RecycleSignal}

Event for recycling of resources.

\textbf{Description}

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The *EFI_IPSEC_PROCESS* process routine handles each inbound or outbound packet. The behavior is that it can perform one of the following actions: bypass the packet, discard the packet, or protect the packet.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The packet was bypassed and all buffers remain the same.</td>
</tr>
<tr>
<td>EFI_SUCCESS</td>
<td>The packet was protected.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The packet was discarded.</td>
</tr>
</tbody>
</table>

### 28.8.12 EFI IPsec2 Protocol

This section provides a detailed description of the *EFI_IPSEC2_PROTOCOL*. This protocol handles IPsec-protected traffic.

### 28.8.13 EFI_IPSEC2_PROTOCOL

**Summary**

The *EFI_IPSEC2_PROTOCOL* is used to abstract the ability to deal with the individual packets sent and received by the host and provide packet-level security for IP datagram.

**GUID**

```c
#define EFI_IPSEC2_PROTOCOL_GUID \
    {0xa3979e64, 0xace8, 0x4ddc, \ 
    {0xbc, 0x07, 0x4d, 0x66, 0xb8, 0xfd, 0x09, 0x77}};
```

**Protocol Interface Structure**

```c
typedef struct _EFI_IPSEC2_PROTOCOL {
    EFI_IPSEC_PROCESSEXT ProcessExt;
    EFI_EVENT DisabledEvent;
    BOOLEAN DisabledFlag;
} EFI_IPSEC2_PROTOCOL;
```

**Parameters**

- **ProcessExt**
  Handle the IPsec message with the extension header processing support.

- **DisabledEvent**
  Event signaled when the interface is disabled.

- **DisabledFlag**
  State of the interface.

**Description**

The *EFI_IPSEC2_PROTOCOL* provides the ability for securing IP communications by authenticating and/or encrypting each IP packet in a data stream.

*EFI_IPSEC2_PROTOCOL* can be consumed by both the IPv4 and IPv6 stack. A user can employ this protocol for IPsec package handling in both IPv4 and IPv6 environment.
28.8.14 EFI_IPSEC2_PROTOCOL.ProcessExt()

Summary
Handles IPsec processing for both inbound and outbound IP packets. Compare with Process() in EFI_IPSEC_PROTOCOL, this interface has the capability to process Option(Extension Header).

Prototype

```c
typedef EFI_STATUS
( EFIAPI * EFI_IPSEC_PROCESSEXT ) ( 
  IN EFI_IPSEC2_PROTOCOL *This,
  IN EFI_HANDLE NicHandle,
  IN UINT8 IpVer,
  IN OUT VOID *IpHead,
  IN OUT UINT8 *LastHead,
  IN OUT VOID **OptionsBuffer,
  IN OUT UINT32 *OptionsLength,
  IN OUT EFI_IPSEC_FRAGMENT_DATA **FragmentTable,
  IN OUT UINT32 *FragmentCount,
  IN EFI_IPSEC_TRAFFIC_DIR TrafficDirection,
  OUT EFI_EVENT *RecycleSignal
);
```

Parameters

This
Pointer to the EFI_IPSEC2_PROTOCOL instance.

NicHandle
Instance of the network interface.

IpVer
IP version.IPV4 or IPV6.

IpHead
Pointer to the IP Header it is either the EFI_IP4_HEADER or EFI_IP6_HEADER. On input, it contains the IP header. On output,

1. in tunnel mode and the traffic direction is inbound, the buffer will be reset to zero by IPsec;
2. in tunnel mode and the traffic direction is outbound, the buffer will reset to be the tunnel IP header.
3. in transport mode, the related fielders (like payload length, Next header) in IP header will be modified according to the condition.

LastHead
For IP4, it is the next protocol in IP header. For IP6 it is the Next Header of the last extension header.

OptionsBuffer
On input, it contains the options (extensions header) to be processed by IPsec. On output,

1. in tunnel mode and the traffic direction is outbound, it will be set to NULL, and that means this contents was wrapped after inner header and should not be concatenated after tunnel header again;
2. in transport mode and the traffic direction is inbound, if there are IP options (extension headers) protected by IPsec, IPsec will concatenate the those options after the input options (extension headers);
3. on other situations, the output of contents of OptionsBuffer might be same with input’s. The caller should take the responsibility to free the buffer both on input and on output.
OptionsLength
On input, the input length of the options buffer. On output, the output length of the options buffer.

FragmentTable
Pointer to a list of fragments. On input, these fragments contain the IP payload. On output,
1. in tunnel mode and the traffic direction is inbound, the fragments contain the whole IP payload which is from the IP inner header to the last byte of the packet;*
2. in tunnel mode and the traffic direction is the outbound, the fragments contains the whole encapsulated payload which encapsulates the whole IP payload between the encapsulated header and encapsulated trailer fields.*
3. in transport mode and the traffic direction is inbound, the fragments contains the IP payload which is from the next layer protocol to the last byte of the packet;*
4. in transport mode and the traffic direction is outbound, the fragments contains the whole encapsulated payload which encapsulates the next layer protocol information between the encapsulated header and encapsulated trailer fields.*

FragmentCount
Number of fragments.

TrafficDirection
Traffic direction.

RecycleSignal
Event for recycling of resources.

Description
The EFI_IPSEC_PROCESSEXT process routine handles each inbound or outbound packet with the support of options (extension headers) processing. The behavior is that it can perform one of the following actions: bypass the packet, discard the packet, or protect the packet.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The packet was bypassed and all buffers remain the same.</td>
</tr>
<tr>
<td>EFI_SUCCESS</td>
<td>The packet was processed by IPsec successfully.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The packet was discarded.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The IKE negotiation is invoked and the packet was discarded.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One of more of following are <strong>TRUE</strong></td>
</tr>
<tr>
<td></td>
<td>If OptionsBuffer is <strong>NULL</strong>;</td>
</tr>
<tr>
<td></td>
<td>If OptionsLength is <strong>NULL</strong>;</td>
</tr>
<tr>
<td></td>
<td>If FragmentTable is <strong>NULL</strong>;</td>
</tr>
<tr>
<td></td>
<td>If FragmentCount is <strong>NULL</strong>;</td>
</tr>
</tbody>
</table>
28.9 Network Protocol - EFI FTP Protocol

This section defines the EFI FTPv4 (File Transfer Protocol version 4) Protocol that interfaces over EFI FTPv4 Protocol.

28.9.1 EFI_FTP4_SERVICE_BINDING_PROTOCOL Summary

Summary

The EFI_FTP4_SERVICE_BINDING_PROTOCOL is used to locate communication devices that are supported by an EFI FTPv4 Protocol driver and to create and destroy instances of the EFI FTPv4 Protocol child protocol driver that can use the underlying communication device.

GUID

```c
#define EFI_FTP4_SERVICE_BINDING_PROTOCOL_GUID \
    {0xfaaecb1, 0x226e, 0x4782,\ 
     {0xaa, 0xce, 0x7d, 0xb9, 0xbc, 0xbf, 0x4d, 0xaf}}
```

Description

A network application or driver that requires FTPv4 I/O services can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish an EFI FTPv4 Service Binding Protocol GUID. Each device with a published EFI FTPv4 Service Binding Protocol GUID supports the EFI FTPv4 Protocol service and may be available for use.

After a successful call to the `EFI_FTP4_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the newly created child EFI FTPv4 Protocol driver instance is in an unconfigured state; it is not ready to transfer data.

Before a network application terminates execution, every successful call to the `EFI_FTP4_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI_FTP4_SERVICE_BINDING_PROTOCOL.DestroyChild()` function.

Each instance of the EFI FTPv4 Protocol driver can support one file transfer operation at a time. To download two files at the same time, two instances of the EFI FTPv4 Protocol driver will need to be created.

**NOTE:** Byte Order: If not specifically specified, the IP addresses used in the EFI_FTP4_PROTOCOL are in network byte order and the ports are in host byte order.

28.9.2 EFI_FTP4_PROTOCOL

Summary

The EFI FTPv4 Protocol provides basic services for client-side FTP (File Transfer Protocol) operations.

GUID

```c
#define EFI_FTP4_PROTOCOL_GUID \
    {0xeb338826, 0x681b, 0x4295,\ 
     {0xb3, 0x56, 0x2b, 0x36, 0x4c, 0x75, 0x7b, 0x09}}
```

Protocol Interface Structure

```c
typedef struct _EFI_FTP4_PROTOCOL {
    EFI_FTP4_GET_MODE_DATA GetModeData;
    EFI_FTP4_CONNECT    Connect;
    EFI_FTP4_CLOSE      Close;
} EFI_FTP4_PROTOCOL;
```

(continues on next page)
Parameters

GetModeData
Reads the current operational settings. See the GetModeData() function description.

Connect
Establish control connection with the FTP server by using the TELNET protocol according to FTP protocol definition. See the Connect() function description.

Close
Gracefully disconnecting a FTP control connection. This function is a nonblocking operation. See the Close() function description.

Configure
Sets and clears operational parameters for an FTP child driver. See the Configure() function description.

ReadFile
Downloads a file from an FTPv4 server. See the ReadFile() function description.

WriteFile
Uploads a file to an FTPv4 server. This function may be unsupported in some EFI implementations. See the WriteFile() function description.

ReadDirectory
Download a related file “directory” from an FTPv4 server. This function may be unsupported in some implementations. See the ReadDirectory() function description.

Poll
Polls for incoming data packets and processes outgoing data packets. See the Poll() function description.

28.9.3 EFI_FTP4_PROTOCOL.GetModeData()

Summary
Gets the current operational settings.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_FTP4_GET_MODE_DATA)(
   IN EFI_FTP4_PROTOCOL *This,
   OUT EFI_FTP4_CONFIG_DATA *ModeData
);

Parameters
This
Pointer to the EFI_FTP4_PROTOCOL instance.
ModeData
Pointer to storage for the EFI FTPv4 Protocol driver mode data. Type EFI_FTP4_CONFIG_DATA is defined in “Related Definitions” below. The string buffers for Username and Password in EFI_FTP4_CONFIG_DATA are allocated by the function, and the caller should take the responsibility to free the buffer later.

Description
The GetModeData() function reads the current operational settings of this EFI FTPv4 Protocol driver instance. EFI_FTP4_CONFIG_DATA is defined in the EFI_FTP4_PROTOCOL.Configure.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>This function is called successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are TRUE: • This is NULL. • ModeData is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI FTPv4 Protocol driver has not been started.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate enough resource to finish the operation.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
</tbody>
</table>

28.9.4 EFI_FTP4_PROTOCOL.Connect()

Summary
Initiate a FTP connection request to establish a control connection with FTP server

Prototype

typedef EFI_STATUS (EFIAPI *EFI_FTP4_CONNECT) (IN EFI_FTP4_PROTOCOL *This, IN EFI_FTP4_CONNECTION_TOKEN *Token);

Parameters

This
Pointer to the EFI_FTP4_PROTOCOL instance.

Token
Pointer to the token used to establish control connection.

Related Definition

```
//***************************************************
// EFI_FTP4_CONNECTION_TOKEN
//***************************************************
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
} EFI_FTP4_CONNECTION_TOKEN;
```
Event
The Event to signal after the connection is established and Status field is updated by the EFI FTP v4 Protocol driver. The type of Event must be EVENT_NOTIFY_SIGNAL, and its Task Priority Level (TPL) must be lower than or equal to TPL_CALLBACK. If it is set to NULL, this function will not return until the function completes.

Status
The variable to receive the result of the completed operation.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The FTP connection is established successfully.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The FTP server denied the access the user’s request to access it.</td>
</tr>
<tr>
<td>EFI_CONNECTION_RESET</td>
<td>The connect fails because the connection is reset either by instance itself or communication peer.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The connection establishment timer expired and no more specific information is available.</td>
</tr>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>The active open fails because an ICMP network unreachable error is received.</td>
</tr>
<tr>
<td>EFI_HOST_UNREACHABLE</td>
<td>The active open fails because an ICMP host unreachable error is received.</td>
</tr>
<tr>
<td>EFI_PROTOCOL_UNREACHABLE</td>
<td>The active open fails because an ICMP protocol unreachable error is received.</td>
</tr>
<tr>
<td>EFI_PORT_UNREACHABLE</td>
<td>The connection establishment timer times out and an ICMP port unreachable error is received.</td>
</tr>
<tr>
<td>EFI_ICMP_ERROR</td>
<td>The connection establishment timer timeout and some other ICMP error is received.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
</tbody>
</table>

Description
The Connect() function will initiate a connection request to the remote FTP server with the corresponding connection token. If this function returns EFI_SUCCESS, the connection sequence is initiated successfully. If the connection succeeds or failed due to any error, the Token->Event will be signaled and Token->Status will be updated accordingly.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The connection sequence is successfully initiated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are TRUE:</td>
</tr>
<tr>
<td></td>
<td>2 This is NULL.</td>
</tr>
<tr>
<td></td>
<td>2 Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>2 Token-&gt;Event is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI FTPv4 Protocol driver has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate enough resource to finish the operation.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
</tbody>
</table>
28.9.5 EFI_FTP4_PROTOCOL.Close()

**Summary**
Disconnected a FTP connection gracefully.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_FTP4_CLOSE)(
    IN EFI_FTP4_PROTOCOL *This,
    IN EFI_FTP4_CONNECTION_TOKEN *Token
);
```

**Parameters**

- **This**
  Pointer to the EFI_FTP4_PROTOCOL instance.

- **Token**
  Pointer to the token used to close control connection.

**Description**

The Close() function will initiate a close request to the remote FTP server with the corresponding connection token. If this function returns EFI_SUCCESS, the control connection with the remote FTP server is closed.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The close request is successfully initiated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• ConnectionToken is NULL.</td>
</tr>
<tr>
<td></td>
<td>• ConnectionToken-&gt;Event is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI FTPv4 Protocol driver has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate enough resource to finish the operation.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
</tbody>
</table>

28.9.6 EFI_FTP4_PROTOCOL.Configure()

**Summary**
Sets or clears the operational parameters for the FTP child driver.

**Prototype**
typedef
EFI_STATUS
(EFIAPI *EFI_FTP4_CONFIGURE) (  
  IN EFI_FTP4_PROTOCOL *This,
  IN EFI_FTP4_CONFIG_DATA *FtpConfigData OPTIONAL
);

Parameters

This
Pointer to the EFI_FTP4_PROTOCOL instance.

FtpConfigData
Pointer to configuration data that will be assigned to the FTP child driver instance. If NULL, the FTP child driver instance is reset to startup defaults and all pending transmit and receive requests are flushed.

Related Definition

typedef struct {
  UINT8 *Username;
  UINT8 *Password;
  BOOLEAN Active;
  BOOLEAN UseDefaultSetting;
  EFI_IPv4_ADDRESS StationIp;
  EFI_IPv4_ADDRESS SubnetMask;
  EFI_IPv4_ADDRESS GatewayIp;
  EFI_IPv4_ADDRESS ServerIp;
  UINT16 ServerPort;
  UINT16 AltDataPort;
  UINT8 RepType;
  UINT8 FileStruct;
  UINT8 TransMode;
} EFI_FTP4_CONFIG_DATA;

Username
Pointer to a ASCII string that contains user name. The caller is responsible for freeing Username after GetModeData() is called.

Password
Pointer to a ASCII string that contains password. The caller is responsible for freeing Password after GetModeData() is called.

Active
Set it to TRUE to initiate an active data connection. Set it to FALSE to initiate a passive data connection.

UseDefaultSetting
Boolean value indicating if default network setting used.

StationIp
IP address of station if UseDefaultSetting is FALSE.

SubnetMask
Subnet mask of station if UseDefaultSetting is FALSE.
**GatewayIp**
IP address of gateway if `UseDefaultSetting` is **FALSE**.

**ServerIp**
IP address of FTPv4 server.

**ServerPort**
FTPv4 server port number of control connection, and the default value is 21 as convention.

**ALTDataPort**
FTPv4 server port number of data connection. If it is zero, use `(ServerPort - 1)` by convention.

**RepType**
A byte indicate the representation type. The right 4 bit is used for first parameter, the left 4 bit is use for second parameter

- For the first parameter, 0x0 = image, 0x1 = EBCDIC, 0x2 = ASCII, 0x3 = local
- For the second parameter, 0x0 = Non-print, 0x1 = Telnet format effectors, 0x2 = Carriage Control
- If it is a local type, the second parameter is the local byte byte size.
- If it is a image type, the second parameter is undefined.

**FileStruct**
Defines the file structure in FTP used. 0x00 = file, 0x01 = record, 0x02 = page

**TransMode**
Defines the transfer mode used in FTP. 0x00 = stream, 0x01 = Block, 0x02 = Compressed

**Description**
The `Configure()` function will configure the connected FTP session with the configuration setting specified in `FtpConfigData`. The configuration data can be reset by calling `Configure()` with `FtpConfigData` set to **NULL**.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The FTPv4 driver was configured successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more following conditions are <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• <strong>This</strong> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <code>FtpConfigData.RepType</code> is invalid.</td>
</tr>
<tr>
<td></td>
<td>• <code>FtpConfigData.FileStruct</code> in invalid.</td>
</tr>
<tr>
<td></td>
<td>• <code>FtpConfigData.TransMode</code> is invalid.</td>
</tr>
<tr>
<td></td>
<td>• IP address in <code>FtpConfigData</code> is invalid.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) has not finished yet.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>One or more of the configuration parameters are not supported by this implementation.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The EFI FTPv4 Protocol driver instance data could not be allocated.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The EFI FTPv4 Protocol driver instance is not configured.</td>
</tr>
</tbody>
</table>
28.9.7 EFI_FTP4_PROTOCOL.ReadFile()

Summary
Downloads a file from an FTPv4 server.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_FTP4_READ_FILE)(
    IN EFI_FTP4_PROTOCOL *This,
    IN EFI_FTP4_COMMAND_TOKEN *Token
);
```

Parameters

This
Pointer to the EFI_FTP4_PROTOCOL instance.

Token
Pointer to the token structure to provide the parameters that are used in this operation. Type EFI_FTP4_COMMAND_TOKEN is defined in “Related Definitions” below.

Related Definition

```c
// ****************************************************
// EFI_FTP4_COMMAND_TOKEN
// ****************************************************
typedef struct {
    EFI_EVENT Event;
    UINT8 *Pathname;
    UINT64 DataBufferSize;
    VOID *DataBuffer;
    EFI_FTP4_DATA_CALLBACK DataCallback;
    VOID *Context;
    EFI_STATUS Status;
} EFI_FTP4_COMMAND_TOKEN;
```

Event

The Event to signal after request is finished and Status field is updated by the EFI FTP v4 Protocol driver. The type of Event must be EVT_NOTIFY_SIGNAL, and its Task Priority Level (TPL) must be lower than or equal to TPL_CALLBACK. If it is set to NULL, related function must wait until the function completes.

Pathname

Pointer to a null-terminated ASCII name string.

DataBuffersize

The size of data buffer in bytes.

DataBuffer

Pointer to the data buffer. Data downloaded from FTP server through connection is downloaded here.

DataCallback

Pointer to a callback function. If it is receiving function that leads to inbound data, the callback function is called when databuffer is full. Then, old data in the data buffer should be flushed and new data is stored from
the beginning of data buffer. If it is a transmit function that lead to outbound data and $DataBufferSize$ of $Data$ in $DataBuffer$ has been transmitted, this callback function is called to supply additional data to be transmitted. The size of additional data to be transmitted is indicated in $DataBufferSize$, again. If there is no data remained, $DataBufferSize$ should be set to 0

**Context**

Pointer to the parameter for $DataCallback$.

**Status**

The variable to receive the result of the completed operation.

- **EFI_SUCCESS** — The FTP command is completed successfully.

- **EFI_ACCESS_DENIED** — The FTP server denied the access to the requested file.

- **EFI_CONNECTION_RESET** — The connect fails because the connection is reset either by instance itself or communication peer.

- **EFI_TIMEOUT** — The connection establishment timer expired and no more specific information is available.

- **EFI_NETWORK_UNREACHABLE** — The active open fails because an ICMP network unreachable error is received.

- **EFI_HOST_UNREACHABLE** — The active open fails because an ICMP host unreachable error is received.

- **EFI_PROTOCOL_UNREACHABLE** — The active open fails because an ICMP protocol unreachable error is received.

- **EFI_PORT_UNREACHABLE** — The connection establishment timer times out and an ICMP port unreachable error is received.

- **EFI_ICMP_ERROR** — The connection establishment timer timeout and some other ICMP error is received.

- **EFI_DEVICE_ERROR** — An unexpected system or network error occurred.

**Related Definition**

```c
//********************************************************************************
// EFI_FTP4_DATA_CALLBACK
//********************************************************************************
typedef
EFI_STATUS
(EFIAPI *EFI_FTP4_DATA_CALLBACK)(
```

(continues on next page)
IN EFI_FTP4_COMMAND_TOKEN *Token,
IN EFI_FTP4_PROTOCOL *This,
);

This
Pointer to the EFI_FTP4_PROTOCOL instance.

Token
Pointer to the token structure to provide the parameters that are used in this operation. Type
EFI_FTP4_COMMAND_TOKEN is defined in “Related Definitions” above.

Description
The ReadFile() function is used to initialize and start an FTPv4 download process and optionally wait for completion.
When the download operation completes, whether successfully or not, the Token.Status field is updated by the EFI
FTPv4 Protocol driver and then Token.Event is signaled (if it is not NULL).

Data will be downloaded from the FTPv4 server into Token.DataBuffer. If the file size is larger than To-
ken.DataBufferSize, Token.DataCallback will be called to allow for processing data and then new data will be placed
at the beginning of Token.DataBuffer.

Status Codes Returned

<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The data file is being downloaded successfully.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the parameters is not valid.</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token. Pathname is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token. DataBuffer is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token. DataBufferSize is 0.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI FTPv4 Protocol driver has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network error or system error occurred.</td>
</tr>
</tbody>
</table>

28.9.8 EFI_FTP4_PROTOCOL.WriteFile()

Summary
Uploads a file from an FTPv4 server.

Prototype
typedef
EFI_STATUS
(EFIAPIC *EFI_FTP4_WRITE_FILE)(
    IN EFI_FTP4_PROTOCOL *This,
    IN EFI_FTP4_COMMAND_TOKEN *Token
    );

Parameters
This

Pointer to the `EFI_FTP4_PROTOCOL` instance.

Token

Pointer to the token structure to provide the parameters that are used in this operation. Type `EFI_FTP4_COMMAND_TOKEN` is defined in "`EFI_FTP4_READ_FILE`".

Description

The `WriteFile` function is used to initialize and start an FTPv4 upload process and optionally wait for completion. When the upload operation completes, whether successfully or not, the `Token.Status` field is updated by the EFI FTPv4 Protocol driver and then `Token.Event` is signaled (if it is not `NULL`).

Data to be uploaded to server is stored into `Token.DataBuffer`. `Token.DataBufferSize` is the number bytes to be transferred. If the file size is larger than `Token.DataBufferSize`, `Token.DataCallback` will be called to allow for processing data and then new data will be placed at the beginning of `Token.DataBuffer`. `Token.DataBufferSize` is updated to reflect the actual number of bytes to be transferred. `Token.DataBufferSize` is set to 0 by the call back to indicate the completion of data transfer.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data file is being uploaded successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The operation is not supported by this implementation.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the parameters is not valid.</td>
</tr>
<tr>
<td></td>
<td>• This is <code>NULL</code>.</td>
</tr>
<tr>
<td></td>
<td>• Token is <code>NULL</code>.</td>
</tr>
<tr>
<td></td>
<td>• Token. Pathname is <code>NULL</code>.</td>
</tr>
<tr>
<td></td>
<td>• Token. DataBuffer is <code>NULL</code>.</td>
</tr>
<tr>
<td></td>
<td>• Token. DataBufferSize is 0.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI FTPv4 Protocol driver has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is</td>
</tr>
<tr>
<td></td>
<td>not finished yet.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network error or system error occurred.</td>
</tr>
</tbody>
</table>

28.9.9 `EFI_FTP4_PROTOCOL.ReadDirectory()`

Summary

Download a data file “directory” from a FTPv4 server. May be unsupported in some EFI implementations.

Prototype

```c
typedef EFI_STATUS
  (EFIAPICALLTYPE EFI_FTP4_READ_DIRECTORY) (
    IN EFI_FTP4_PROTOCOL *This,
    IN EFI_FTP4_COMMAND_TOKEN *Token
  );
```

Parameters

This

Pointer to the `EFI_FTP4_PROTOCOL` instance.
Token

Pointer to the token structure to provide the parameters that are used in this operation. Type EFI_FTP4_COMMAND_TOKEN is defined in “EFI_FTP4_READ_FILE”.

Description

The ReadDirectory() function is used to return a list of files on the FTPv4 server that logically (or operationally) related to Token.Pathname, and optionally wait for completion. When the download operation completes, whether successfully or not, the Token.Status field is updated by the EFI FTPv4 Protocol driver and then Token.Event is signaled (if it is not NULL).

Data will be downloaded from the FTPv4 server into Token.DataBuffer. If the file size is larger than Token.DataBufferSize, Token.DataCallback will be called to allow for processing data and then new data will be placed at the beginning of Token.DataBuffer.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The file list information is being downloaded successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The operation is not supported by this implementation.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the parameters is not valid.</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token. DataBuffer is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Token. DataBufferSize is 0.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI FTPv4 Protocol driver has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network error or system error occurred.</td>
</tr>
</tbody>
</table>

28.9.10 EFI_FTP4_PROTOCOL.Poll()

Summary

Polls for incoming data packets and processes outgoing data packets.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_FTP4_POLL) (
    IN EFI_FTP4_PROTOCOL *This
);
```

Parameters

This

Pointer to the EFI_FTP4_PROTOCOL instance.

Description

The Poll() function can be used by network drivers and applications to increase the rate that data packets are moved between the communications device and the transmit and receive queues.
In some systems, the periodic timer event in the managed network driver may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the \texttt{Poll()} function more often.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI FTPv4 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is \texttt{NULL}.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Data was dropped out of the transmit and/or receive queue. Consider increasing the polling rate.</td>
</tr>
</tbody>
</table>

### 28.10 EFI TLS Protocols

#### 28.10.1 EFI TLS Service Binding Protocol

#### 28.10.1.1 EFI_TLS_SERVICE_BINDING_PROTOCOL

**Summary**

The EFI TLS Service Binding Protocol is used to locate EFI TLS Protocol drivers to create and destroy child of the driver to communicate with other host using TLS protocol.

**GUID**

```c
#define EFI_TLS_SERVICE_BINDING_PROTOCOL_GUID
    { 
    0x952cb795, 0xff36, 0x48cf, 0xa2, 0x49, 0x4d, 0xf4, 0x86, 0xd6, 0xab, 0x8d 
    }
```

**Description**

The TLS consumer need locate EFI_TLS_SERVICE_BINDING_PROTOCOL and call CreateChild() to create a new child of EFI_TLS_PROTOCOL and EFI_TLS_CONFIGURATION_PROTOCOL instance. Then use EFI_TLS_CONFIGURATION_PROTOCOL to set TLS configuration data, and use EFI_TLS_PROTOCOL to start TLS session. After use, the TLS consumer needs to call DestroyChild() to destroy it.

#### 28.10.2 EFI TLS Protocol

#### 28.10.2.1 EFI_TLS_PROTOCOL

**Summary**

This protocol provides the ability to manage TLS session.

**GUID**

```c
#define EFI_TLS_PROTOCOL_GUID
    { 0xca959f, 0x6cfa, 0x4db1, 
        {0x95, 0xbc, 0xe4, 0x6c, 0x47, 0x51, 0x43, 0x90 } 
    }
```

**Protocol Interface Structure**
typedef struct _EFI_TLS_PROTOCOL {
    EFI_TLS_SET_SESSION_DATA    SetSessionData;
    EFI_TLS_GET_SESSION_DATA    GetSessionData;
    EFI_TLS_BUILD_RESPONSE_PACKET BuildResponsePacket;
    EFI_TLS_PROCESS_PACKET      ProcessPacket;
} EFI_TLS_PROTOCOL;

Parameters

SetSessionData
Set TLS session data. See the SetSessionData () function description.

GetSessionData
Get TLS session data. See the GetSessionData () function description.

BuildResponsePacket
Build response packet according to TLS state machine. This function is only valid for alert, handshake and change_cipher_spec content type. See the BuildResponsePacket () function description.

ProcessPacket
Decrypt or encrypt TLS packet during session. This function is only valid after session connected and for application_data content type. See the ProcessPacket () function description.

Description
The EFI_TLS_PROTOCOL is used to create, destroy and manage TLS session. For detail of TLS, please refer to TLS related RFC.

28.10.3 EFI_TLS_PROTOCOL.SetSessionData ()

Summary
Set TLS session data.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_TLS_SET_SESSION_DATA)(
    IN EFI_TLS_PROTOCOL *This,
    IN EFI_TLS_SESSION_DATA_TYPE  DataType,
    IN VOID *Data,
    IN UINTN DataSize
);

Parameters

This
Pointer to the EFI_TLS_PROTOCOL instance.

DataType
TLS session data type. See EFI_TLS_SESSION_DATA_TYPE

Data
Pointer to session data.

DataSize
Total size of session data.
Description

The `SetSessionData()` function sets data for a new TLS session. All session data should be set before `BuildResponsePacket()` invoked.

Related Definition

```c
//*******************************************************
// EFI_TLS_SESSION_DATA_TYPE
//*******************************************************
typedef enum {
    EfiTlsVersion,
    EfiTlsConnectionEnd,
    EfiTlsCipherList,
    EfiTlsCompressionMethod,
    EfiTlsExtensionData,
    EfiTlsVerifyMethod,
    EfiTlsSessionID,
    EfiTlsSessionState,
    EfiTlsClientRandom,
    EfiTlsServerRandom,
    EfiTlsKeyMaterial,
    EfiTlsVerifyHost,
    EfiTlsSessionDataTypeMaximum
} EFI_TLS_SESSION_DATA_TYPE;
```

.. TODO: Please note that explanatory text for `EfiTlsSessionDataTypeMaximum` is missing, below.

`EfiTlsVersion`

TLS session Version. The corresponding `Data` is of type `EFI_TLS_VERSION`.

`EfiTlsConnectionEnd`

TLS session as client or as server. The corresponding `Data` is of `EFI_TLS_CONNECTION_END`.

`EfiTlsCipherList`

A priority list of preferred algorithms for the TLS session. The corresponding `Data` is a list of `EFI_TLS_CIPHER`.

`EfiTlsCompressionMethod`

TLS session compression method. The corresponding `Data` is of type `EFI_TLS_COMPRESSION`.

`EfiTlsExtensionData`

TLS session extension data. The corresponding `Data` is a list of type `EFI_TLS_EXTENDION`.

`EfiTlsVerifyMethod`

TLS session verify method. The corresponding `Data` is of type `EFI_TLS_VERIFY`.

`EfiTlsSessionID`

TLS session data session ID. For `SetSessionData()`, it is TLS session ID used for session resumption. For `GetSessionData()`, it is the TLS session ID used for current session. The corresponding `Data` is of type `EFI_TLS_SESSION_ID`.

`EfiTlsSessionState`

TLS session data session state. The corresponding `Data` is of type `EFI_TLS_SESSION_STATE`.

`EfiTlsClientRandom`

TLS session data client random. The corresponding `Data` is of type `EFI_TLS_RANDOM`.

`EfiTlsServerRandom`

TLS session data server random. The corresponding `Data` is of type `EFI_TLS_SERVER_RANDOM`.
**EfiTlsKeyMaterial**

TLS session data key material. The corresponding *Data* is of type `EFI_TLS_MASTER_SECRET`.

**EfiTlsVerifyHost**

TLS session hostname for validation which is used to verify whether the name within the peer certificate matches a given host name. This parameter is invalid when `EfiTlsVerifyMethod` is `EFI_TLS_VERIFY_NONE`. The corresponding Data is of type `EFI_TLS_VERIFY_HOST`.

```c
typedef struct {
    UINT8 Major;
    UINT8 Minor;
} EFI_TLS_VERSION;
```

**NOTE:** The TLS version definition is from SSL3.0 to latest TLS (e.g. 1.2). SSL2.0 is obsolete and should not be used.

```c
typedef enum {
    EfiTlsClient,
    EfiTlsServer,
} EFI_TLS_CONNECTION_END;
```

TLS connection end is to define TLS session as client or as server.

```c
typedef struct {
    UINT8 Data1;
    UINT8 Data2;
} EFI_TLS_CIPHER;
```

**NOTE:** The definition of `EFI_TLS_CIPHER` is from RFC5246 A.4.1. Hello Messages. The value of `EFI_TLS_CIPHER` is from TLS Cipher Suite Registry of IANA.

```c
typedef UINT8 EFI_TLS_COMPRESSION;
```

**NOTE:** The value of `EFI_TLS_COMPRESSION` definition is from RFC 3749.

```c
typedef struct {
    UINT16 ExtensionType;
    UINT16 Length;
    UINT8 Data[];
} EFI_TLS_EXTENSION;
```

**NOTE:** The definition of `EFI_TLS_EXTENSION` is from RFC 5246 A.4.1. Hello Messages.
The consumer needs to use either `EFI_TLS_VERIFY_NONE` or `EFI_TLS_VERIFY_PEER`. `EFI_TLS_VERIFY_FAIL_IF_NO_PEER_CERT` and `EFI_TLS_VERIFY_CLIENT_ONCE` can be ORed with `EFI_TLS_VERIFY_PEER`. `EFI_TLS_VERIFY_FAIL_IF_NO_PEER_CERT` is only meaningful in the server mode, which means the TLS session will fail if the client certificate is absent. `EFI_TLS_VERIFY_CLIENT_ONCE` means the TLS session only verifies the client once, and doesn't request a certificate during re-negotiation.

**Flags**
- The host name validation flags. The flags arguments can be ORed.

**HostName**
- The specified host name to be verified.
would not match “www.sub.example.com”.

**EFI_TLS_VERIFY_FLAG_NEVER_CHECK_SUBJECT** means never check the Subject Distinguished Name (DN) even there is no Subject Alternative Name (SAN) in the certificate.

If both **EFI_TLS_VERIFY_FLAG_ALWAYS_CHECK_SUBJECT** and **EFI_TLS_VERIFY_FLAG_NEVER_CHECK_SUBJECT** are specified, **EFI_INVALID_PARAMETER** will be returned. If **EFI_TLS_VERIFY_FLAG_NO_WILDCARDS** is set with **EFI_TLS_VERIFY_FLAG_NO_PARTIAL_WILDCARDS** or **EFI_TLS_VERIFY_FLAG_MULTI_LABEL_WILDCARDS**, **EFI_INVALID_PARAMETER** will be returned.

```c
typedef struct {
    UINT32 GmtUnixTime;
    UINT8 RandomBytes[28];
} EFI_TLS_RANDOM;
```

**NOTE:** The definition of **EFI_TLS_RANDOM** is from RFC 5246 A.4.1. Hello Messages.

```c
typedef struct {
    UINT8 *Data[48];
} EFI_TLS_MASTER_SECRET;
```

**NOTE:** The definition of **EFI_TLS_MASTER_SECRET** is from RFC 5246 8.1. Computing the Master Secret.

```c
#define MAX_TLS_SESSION_ID_LENGTH 32
typedef struct {
    UINT16 Length;
    UINT8 Data[MAX_TLS_SESSION_ID_LENGTH];
} EFI_TLS_SESSION_ID;
```

**NOTE:** The definition of **EFI_TLS_SESSION_ID** is from RFC 5246 A.4.1. Hello Messages.

```c
Typedef enum {
    EfiTlsSessionNotStarted,
    EfiTlsSessionHandShaking,
    EfiTlsSessionDataTransferring,
    EfiTlsSessionClosing,
    EfiTlsSessionError,
    EfiTlsSessionStateMaximum
} EFI_TLS_SESSION_STATE;
```

The definition of **EFI_TLS_SESSION_STATE** is below:

When a new child of TLS protocol is created, the initial state of TLS session is **EfiTlsSessionNotStarted**.
The consumer can call `BuildResponsePacket()` with NULL to get ClientHello to start the TLS session. Then the status is `EfiTlsSessionHandShaking`.

During handshake, the consumer need call `BuildResponsePacket()` with input data from peer, then get response packet and send to peer. After handshake finish, the TLS session status becomes `EfiTlsSessionDataTransferring`, and consume can use `ProcessPacket()` for data transferring.

Finally, if consumer wants to active close TLS session, consumer need call SetSessionData to set TLS session state to `EfiTlsSessionClosing`, and call `BuildResponsePacket()` with NULL to get CloseNotify alert message, and sent it out.

If any error happen during parsing ApplicationData content type, EFI_ABORT will be returned by `ProcessPacket()`, and TLS session state will become `EfiTlsSessionError`. Then consumer need call `BuildResponsePacket()` with NULL to get alert message and sent it out.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The TLS session data is set successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• This is <strong>NULL</strong></td>
</tr>
<tr>
<td></td>
<td>• Data is <strong>NULL</strong></td>
</tr>
<tr>
<td></td>
<td>• DataSize is 0.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The <strong>DataType</strong> is unsupported.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>If the <strong>DataType</strong> is one of below:</td>
</tr>
<tr>
<td></td>
<td>• EfiTlsClientRandom</td>
</tr>
<tr>
<td></td>
<td>• EfiTlsServerRandom</td>
</tr>
<tr>
<td></td>
<td>• EfiTlsKeyMaterial</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>Current TLS session state is NOT <code>EfiTlsSessionStateNotStarted</code>.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
</tbody>
</table>

**28.10.4 EFI_TLS_PROTOCOL.GetSessionData ()**

**Summary**

Get TLS session data.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI *EFI_TLS_GET_SESSION_DATA)(
    IN EFI_TLS_PROTOCOL *This,
    IN EFI_TLS_SESSION_DATA_TYPE DataType,
    IN OUT VOID *Data, OPTIONAL
    IN OUT UINTN *DataSize
);
```

**Parameters**

**This**

Pointer to the `EFI_TLS_PROTOCOL` instance.
**DataType**

TLS session data type. See EFI_TLS_SESSION_DATA_TYPE

**Data**

Pointer to session data.

**DataSize**

Total size of session data. On input, it means the size of Data buffer. On output, it means the size of copied Data buffer if EFI_SUCCESS, and means the size of desired Data buffer if EFI_BUFFER_TOO_SMALL.

**Description**

The GetSessionData() function return the TLS session information.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The TLS session data is got successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• DataSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Data is NULL if *DataSize is not zero.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The DataType is unsupported.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The TLS session data is not found.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The DataType is not ready in current session state.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The buffer is too small to hold the data.</td>
</tr>
</tbody>
</table>

**28.10.5 EFI_TLS_PROTOCOL.BuildResponsePacket ()**

**Summary**

Build response packet according to TLS state machine. This function is only valid for alert, handshake and change_cipher_spec content type.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_TLS_BUILD_RESPONSE_PACKET)(
    IN EFI_TLS_PROTOCOL *This,
    IN UINT8 *RequestBuffer, OPTIONAL
    IN UINTN RequestSize, OPTIONAL
    OUT UINT8 *Buffer, OPTIONAL
    IN OUT UINTN *BufferSize
);
```

**Parameters**

**This**

Pointer to the EFI_TLS_PROTOCOL instance.

**RequestBuffer**

Pointer to the most recently received TLS packet. NULL means TLS need initiate the TLS session and response packet need to be ClientHello.
RequestSize
Packet size in bytes for the most recently received TLS packet. 0 is only valid when RequestBuffer is NULL.

Buffer
Pointer to the buffer to hold the built packet.

BufferSize
Pointer to the buffer size in bytes. On input, it is the buffer size provided by the caller. On output, it is the buffer size in fact needed to contain the packet.

Description
The BuildResponsePacket() function builds TLS response packet in response to the TLS request packet specified by RequestBuffer and RequestSize. If RequestBuffer is NULL and RequestSize is 0, and TLS session status is EfiTlsSessionNotStarted, the TLS session will be initiated and the response packet needs to be ClientHello. If RequestBuffer is NULL and RequestSize is 0, and TLS session status is EfiTlsSessionClosing, the TLS session will be closed and response packet needs to be CloseNotify. If RequestBuffer is NULL and RequestSize is 0, and TLS session status is EfiTlsSessionError, the TLS session has errors and the response packet needs to be Alert message based on error type.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The required TLS packet is built successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• RequestBuffer is NULL but RequestSize is NOT 0.</td>
</tr>
<tr>
<td></td>
<td>• RequestSize is 0 but RequestBuffer is NOT NULL.</td>
</tr>
<tr>
<td></td>
<td>• BufferSize is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Buffer is NULL if BufferSize is not zero.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>BufferSize is too small to hold the response packet.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>Current TLS session state is NOT ready to build ResponsePacket.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>Something wrong build response packet.</td>
</tr>
</tbody>
</table>

28.10.6 EFI_TLS_PROTOCOL.ProcessPacket()

Summary
Decrypt or encrypt TLS packet during session. This function is only valid after session connected and for application_data content type.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_TLS_PROCESS_PACKET)(
    IN EFI_TLS_PROTOCOL *This,
    IN OUT EFI_TLS_FRAGMENT_DATA *FragmentTable,
    IN UINT32 *FragmentCount,
    IN EFI_TLS_CRYPT_MODE CryptMode
);

Parameters

This
Pointer to the EFI_TLS_PROTOCOL instance.
FragmentTable
   Pointer to a list of fragment. The caller will take responsible to handle the original FragmentTable while it may be reallocated in TLS driver. If CryptMode is EfiTlsEncrypt, on input these fragments contain the TLS header and plain text TLS APP payload; on output these fragments contain the TLS header and cypher text TLS APP payload. If CryptMode is EfiTlsDecrypt, on input these fragments contain the TLS header and cypher text TLS APP payload; on output these fragments contain the TLS header and plain text TLS APP payload.

FragmentCount
   Number of fragment.

CryptMode
   Crypt mode.

Description
   The ProcessPacket () function process each inbound or outbound TLS APP packet.

Related Definition

```c
//*****************************************************/
// EFI_TLS_FRAGMENT_DATA
//*****************************************************/
typedef struct {
    UINT32 FragmentLength;
    VOID *FragmentBuffer;
} EFI_TLS_FRAGMENT_DATA;
```

FragmentLength
   Length of data buffer in the fragment.

FragmentBuffer
   Pointer to the data buffer in the fragment.

```c
//*****************************************************/
// EFI_TLS_CRYPT_MODE
//*****************************************************/
typedef enum {
    EfiTlsEncrypt,
    EfiTlsDecrypt,
} EFI_TLS_CRYPT_MODE;
```

EfiTlsEncrypt
   Encrypt data provided in the fragment buffers.

EfiTlsDecrypt
   Decrypt data provided in the fragment buffers.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
</tbody>
</table>

continues on next page
Table 28.67 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• FragmentTable is NULL.</td>
</tr>
<tr>
<td></td>
<td>• FragmentCount is NULL.</td>
</tr>
<tr>
<td></td>
<td>• CryptoMode is invalid.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>Current TLS session state is NOT EfiTlsSessionDataTransferring.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>Something wrong decryption the message. TLS session status will become EfiTlsSessionError. The caller need call BuildResponsePacket() to generate Error Alert message and send it out.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>No enough resource to finish the operation.</td>
</tr>
</tbody>
</table>

28.10.7 EFI TLS Configuration Protocol

28.10.7.1 EFI_TLS_CONFIGURATION_PROTOCOL

Summary
This protocol provides a way to set and get TLS configuration.

GUID

```c
#define EFI_TLS_CONFIGURATION_PROTOCOL_GUID \
{ 0x1682fe44, 0xbd7a, 0x4407, \ 
  {0xb7, 0xc7, 0xdc, 0xa3, 0x7c, 0xa3, 0x92, 0x2d }}
```

Protocol Interface Structure

```c
typedef struct _EFI_TLS_CONFIGURATION_PROTOCOL {
  EFI_TLS_CONFIGURATION_SET_DATA  SetData;
  EFI_TLS_CONFIGURATION_GET_DATA  GetData;
} EFI_TLS_CONFIGURATION_PROTOCOL;
```

Parameters

SetData
Set TLS configuration data. See the SetData() function description.

GetData
Get TLS configuration data. See the GetData() function description.

Description
The EFI_TLS_CONFIGURATION_PROTOCOL is designed to provide a way to set and get TLS configuration, such as Certificate, private key file.
28.10.8 EFI_TLS_CONFIGURATION_PROTOCOL.SetData()

Summary
Set TLS configuration data.

Prototype

```c
typedef EFI_STATUS (EFIAPIC *EFI_TLS_CONFIGURATION_SET_DATA)(
    IN EFI_TLS_CONFIGURATION_PROTOCOL *This,
    IN EFI_TLS_CONFIG_DATA_TYPE DataType,
    IN VOID *Data,
    IN UINTN DataSize
);
```

Parameters

This
Pointer to the EFI_TLS_CONFIGURATION_PROTOCOL instance.

DataType
Configuration data type. See EFI_TLS_CONFIG_DATA_TYPE

Data
Pointer to configuration data.

DataSize
Total size of configuration data.

Description
The SetData() function sets TLS configuration to non-volatile storage or volatile storage.

Related Definition

```c
typedef enum {
    EfiTlsConfigDataTypeHostPublicCert,
    EfiTlsConfigDataTypeHostPrivateKey,
    EfiTlsConfigDataTypeCACertificate,
    EfiTlsConfigDataTypeCertRevocationList,
    EfiTlsConfigDataTypeMaximum
} EFI_TLS_CONFIG_DATA_TYPE;
```

EfiTlsConfigDataTypeHostPublicCert
Local host configuration data: public certificate data. This data should be DER-encoded binary X.509 certificate or PEM-encoded X.509 certificate.

EfiTlsConfigDataTypeHostPrivateKey
Local host configuration data: private key data.

EfiTlsConfigDataTypeCACertificate
CA certificate to verify peer. This data should be PEM-encoded RSA or PKCS#8 private key.
EfiTlsConfigDataTypeCertRevocationList
CA-supplied Certificate Revocation List data. This data should be DER-encoded CRL data.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The TLS configuration data is set successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• Data is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• DataSize is 0.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The <strong>DataType</strong> is unsupported.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
</tbody>
</table>

28.10.9 EFI_TLS_CONFIGURATION_PROTOCOL.GetData()

Summary
Get TLS configuration data.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_TLS_CONFIGURATION_GET_DATA)(
    IN EFI_TLS_CONFIGURATION_PROTOCOL *This,
    IN EFI_TLS_CONFIG_DATA_TYPE DataType,
    IN OUT VOID *Data,
    OPTIONAL IN OUT UINTN *DataSize
);
```

Parameters

**This**
Pointer to the **EFI_TLS_CONFIGURATION_PROTOCOL** instance.

**DataType**
Configuration data type. See EFI_TLS_CONFIG_DATA_TYPE

**Data**
Pointer to configuration data.

**DataSize**
Total size of configuration data. On input, it means the size of **Data** buffer. On output, it means the size of copied **Data** buffer if EFI_SUCCESS, and means the size of desired **Data** buffer if EFI_BUFFER_TOO_SMALL.

Description
The **GetData()** function gets TLS configuration.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The TLS configuration data is got successfully.</td>
</tr>
</tbody>
</table>
Table 28.69 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• <strong>This</strong> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <strong>DataSize</strong> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <strong>Data</strong> is <strong>NULL</strong> if <strong>DataSize</strong> is not zero.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The <strong>DataType</strong> is unsupported.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The TLS configuration data is not found.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The buffer is too small to hold the data.</td>
</tr>
</tbody>
</table>
29.1 ARP Protocol

This section defines the EFI Address Resolution Protocol (ARP) Protocol interface. It is split into the following two main sections:

- ARP Service Binding Protocol (ARPSBP)
- ARP Protocol (ARP)

ARP provides a generic implementation of the Address Resolution Protocol that is described in RFCs 826 and 1122. For RFCs can be found see “Links to UEFI-Related Documents” (uefi.org/uefi) under the heading “IETF” (RFCs 826 and 1122) for details for code of ICMP message.

29.1.1 EFI_ARP_SERVICE_BINDING_PROTOCOL

Summary

The ARPSBP is used to locate communication devices that are supported by an ARP driver and to create and destroy instances of the ARP child protocol driver.

The EFI Service Binding Protocol in EFI Services Binding defines the generic Service Binding Protocol functions. This section discusses the details that are specific to the ARP.

GUID

```c
#define EFI_ARP_SERVICE_BINDING_PROTOCOL_GUID \
{0xf44c00ee,0x1f2c,0x4a00,\ 
  {0xaa,0x09,0x1c,0x9f,0x3e,0x08,0x00,0xa3}}
```

Description

A network application (or driver) that requires network address resolution can use one of the protocol handler services, such as BS->LocateHandleBuffer(), to search for devices that publish a ARPSBP GUID. Each device with a published ARPSBP GUID supports ARP and may be available for use.

After a successful call to the EFI_ARP_SERVICE_BINDING_PROTOCOL.CreateChild() function, the child ARP driver instance is in an unconfigured state; it is not ready to resolve addresses.

All child ARP driver instances that are created by one EFI_ARP_SERVICE_BINDING_PROTOCOL instance will share an ARP cache to improve efficiency.

Before a network application terminates execution, every successful call to the
EFI_ARP_SERVICE_BINDING_PROTOCOL.CreateChild() function must be matched with a call to the
EFI_ARP_SERVICE_BINDING_PROTOCOL.DestroyChild() function.

NOTE: All the network addresses that are described in EFI_ARP_PROTOCOL are stored in network byte order. Both incoming and outgoing ARP packets are also in network byte order. All other parameters that are defined in functions or data structures are stored in host byte order.

29.1.2 EFI_ARP_PROTOCOL

Summary
ARP is used to resolve local network protocol addresses into network hardware addresses.

GUID

```c
#define EFI_ARP_PROTOCOL_GUID \
  {0xf4b427bb,0xba21,0x4f16,\ 
   {0xbc,0x4e,0x43,0xe4,0x16,0xab,0x61,0x9c}}
```

Protocol Interface Structure

```c
typedef struct _EFI_ARP_PROTOCOL {
    EFI_ARP_CONFIGURE Configure;
    EFI_ARP_ADD Add;
    EFI_ARP_FIND Find;
    EFI_ARP_DELETE Delete;
    EFI_ARP_FLUSH Flush;
    EFI_ARP_REQUEST Request;
    EFI_ARP_CANCEL Cancel;
} EFI_ARP_PROTOCOL;
```

Parameters

Configure
Add a new station address (protocol type and network address) to the ARP cache. See the Configure() function description.

Add
Manually inserts an entry to the ARP cache for administrative purpose. See the Add() function description.

Find
Locates one or more entries in the ARP cache. See the Find() function description.

Delete
Removes an entry from the ARP cache. See the Delete() function description.

Flush
Removes all dynamic ARP cache entries of a specified protocol type. See the Flush() function description.

Request
Starts an ARP request session. See the Request() function description.

Cancel
Abort previous ARP request session. See the Cancel() function description.
Description

The *EFI_ARP_PROTOCOL* defines a set of generic ARP services that can be used by any network protocol driver to resolve subnet local network addresses into hardware addresses. Normally, a periodic timer event internally sends and receives packets for ARP. But in some systems where the periodic timer is not supported, drivers and applications that are experiencing packet loss should try calling the *Poll()* function of the EFI Managed Network Protocol frequently.

**NOTE**: Add() and Delete() are typically used for administrative purposes, such as denying traffic to and from a specific remote machine, preventing ARP requests from coming too fast, and providing static address pairs to save time. Find() is also used to update an existing ARP cache entry.

### 29.1.3 *EFI_ARP_PROTOCOL*.Configure()

**Summary**

Assigns a station address (protocol type and network address) to this instance of the ARP cache.

**Prototype**

```c
typedef EFI_STATUS (EFAPI *EFI_ARP_CONFIGURE) (  
  IN EFI_ARP_PROTOCOL *This,  
  IN EFI_ARP_CONFIG_DATA *ConfigData OPTIONAL
);
```

**Parameters**

- **This**
  A pointer to the *EFI_ARP_PROTOCOL* instance.

- **ConfigData**
  A pointer to the *EFI_ARP_CONFIG_DATA* structure. Type *EFI_ARP_CONFIG_DATA* is defined in “Related Definitions” below.

**Description**

The Configure() function is used to assign a station address to the ARP cache for this instance of the ARP driver. Each ARP instance has one station address. The *EFI_ARP_PROTOCOL* driver will respond to ARP requests that match this registered station address. A call to Configure() with the ConfigData field set to NULL will reset this ARP instance.

Once a protocol type and station address have been assigned to this ARP instance, all the following ARP functions will use this information. Attempting to change the protocol type or station address to a configured ARP instance will result in errors.

**Related Definitions**

```c
//EFI_ARP_CONFIG_DATA
typedef struct {
  UINT16 SwAddressType;
  UINT8 SwAddressLength;
  VOID *StationAddress;
  UINT32 EntryTimeOut;
  UINT32 RetryCount;
  UINT32 RetryTimeOut;
} EFI_ARP_CONFIG_DATA;
```
SwAddressType

16-bit protocol type number in host byte order. For more information see “Links to UEFI-Related Documents” (uefi.org/uefi) under the heading “16-bit protocol type numbers”.

SwAddressLength

Length in bytes of the station’s protocol address to register.

StationAddress

Pointer to the first byte of the protocol address to register. For example, if SwAddressType is 0x0800 (IP), then StationAddress points to the first byte of this station’s IP address stored in network byte order.

EntryTimeOut

The timeout value in 100-ns units that is associated with each new dynamic ARP cache entry. If it is set to zero, the value is implementation-specific.

RetryCount

The number of retries before a MAC address is resolved. If it is set to zero, the value is implementation-specific.

RetryTimeOut

The timeout value in 100-ns units that is used to wait for the ARP reply packet or the timeout value between two retries. Set to zero to use implementation-specific value.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The new station address was successfully registered.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | • One or more of the following conditions is TRUE:  
• This is NULL.  
• SwAddressLength is zero when ConfigData is not NULL.  
• StationAddress is NULL when ConfigData is not NULL. |
| EFI_ACCESS_DENIED | The SwAddressType, SwAddressLength, or StationAddress is different from the one that is already registered. |
| EFI_OUT_OF_RESOURCES | Storage for the new StationAddress could not be allocated. |

29.1.4 EFI_ARP_PROTOCOL.Add()

Summary

 Inserts an entry to the ARP cache.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_ARP_ADD) ( 
    IN EFI_ARP_PROTOCOL *This,  
    IN BOOLEAN DenyFlag,  
    IN VOID *TargetSwAddress OPTIONAL,  
    IN VOID *TargetHwAddress OPTIONAL,  
    IN UINT32 TimeoutValue,  
    IN BOOLEAN Overwrite  
);

Parameters
This
A pointer to the EFI_ARP_PROTOCOL instance..

DenyFlag

Set to TRUE if this entry is a “deny” entry.
Set to FALSE if this entry is a “normal” entry.

TargetSwAddress
Pointer to a protocol address to add (or deny). May be set to NULL if DenyFlag is TRUE.

TargetHwAddress
Pointer to a hardware address to add (or deny). May be set to NULL if DenyFlag is *TRUE.*

TimeoutValue
Time in 100-ns units that this entry will remain in the ARP cache. A value of zero means that the entry is permanent. A nonzero value will override the one given by Configure() if the entry to be added is dynamic entry.

Overwrite

If TRUE, the matching cache entry will be overwritten with the supplied parameters.
If FALSE, EFI_ACCESS_DENIED is returned if the corresponding cache entry already exists.

Description
The Add() function is used to insert entries into the ARP cache.

ARP cache entries are typically inserted and updated by network protocol drivers as network traffic is processed. Most ARP cache entries will time out and be deleted if the network traffic stops. ARP cache entries that were inserted by the Add() function may be static (will not time out) or dynamic (will time out).

Default ARP cache timeout values are not covered in most network protocol specifications (although RFC 1122 comes pretty close) and will only be discussed in general in this specification. The timeout values that are used in the EFI Sample Implementation should be used only as a guideline. Final product implementations of the EFI network stack should be tuned for their expected network environments.

The Add() function can insert the following two types of entries into the ARP cache:
• “Normal” entries
• “Deny” entries

“Normal” entries must have both a TargetSwAddress and TargetHwAddress and are used to resolve network protocol addresses into network hardware addresses. Entries are keyed by TargetSwAddress. Each TargetSwAddress can have only one TargetHwAddress. A TargetHwAddress may be referenced by multiple TargetSwAddress entries.

“Deny” entries may have a TargetSwAddress or a TargetHwAddress, but not both. These entries tell the ARP driver to ignore any traffic to and from (and to) these addresses. If a request comes in from an address that is being denied, then the request is ignored.

If a normal entry to be added matches a deny entry of this driver, Overwrite decides whether to remove the matching deny entry. On the other hand, an existing normal entry can be removed based on the value of Overwrite if a deny entry to be added matches the existing normal entry. Two entries are matched only when they have the same addresses or when one of the normal entry addresses is the same as the address of a deny entry.

Status Codes Returned

| EFI_SUCCESS | The entry has been added or updated. |

continues on next page
Table 29.2 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>DenyFlag is FALSE and TargetHwAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>DenyFlag is FALSE and TargetSwAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>TargetHwAddress is NULL and TargetSwAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>Both TargetSwAddress and TargetHwAddress are not NULL when DenyFlag is TRUE.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The new ARP cache entry could not be allocated.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The ARP cache entry already exists and Overwrite is not TRUE.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The ARP driver instance has not been configured.</td>
</tr>
</tbody>
</table>

### 29.1.5 EFI_ARP_PROTOCOL.Find()

#### Summary

Locates one or more entries in the ARP cache.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_ARP_FIND) (  
    IN EFI_ARP_PROTOCOL *This,  
    IN BOOLEAN BySwAddress,  
    IN VOID *AddressBuffer OPTIONAL,  
    OUT UINT32 *EntryLength OPTIONAL,  
    OUT UINT32 *EntryCount OPTIONAL,  
    OUT EFI_ARP_FIND_DATA **Entries OPTIONAL,  
    IN BOOLEAN Refresh
);
```

#### Parameters

**This**

A pointer to the `EFI_ARP_PROTOCOL` instance.

**BySwAddress**

Set to `TRUE` to look for matching software protocol addresses.
Set to `FALSE` to look for matching hardware protocol addresses.

**AddressBuffer**

Pointer to address buffer. Set to `NULL` to match all addresses.

**EntryLength**

The size of an entry in the entries buffer. To keep the `EFI_ARP_FIND_DATA` structure properly aligned, this field may be longer than `sizeof(EFI_ARP_FIND_DATA)` plus the length of the software and hardware addresses.

**EntryCount**

The number of ARP cache entries that are found by the specified criteria.
Entries

Pointer to the buffer that will receive the ARP cache entries. Type `EFI_ARP_FIND_DATA` is defined in “Related Definitions” below.

Refresh

Set to **TRUE** to refresh the timeout value of the matching ARP cache entry.

Description

The `Find()` function searches the ARP cache for matching entries and allocates a buffer into which those entries are copied. The first part of the allocated buffer is `EFI_ARP_FIND_DATA`, following which are protocol address pairs and hardware address pairs.

When finding a specific protocol address ( `BySwAddress` is **TRUE** and `AddressBuffer` is not **NULL** ), the ARP cache timeout for the found entry is reset if `Refresh` is set to **TRUE**. If the found ARP cache entry is a permanent entry, it is not affected by `Refresh`.

Related Definitions

```c
//*************************************************
// EFI_ARP_FIND_DATA
//*************************************************
typedef struct {
    UINT32 Size;
    BOOLEAN DenyFlag;
    BOOLEAN StaticFlag;
    UINT16 HwAddressType;
    UINT16 SwAddressType;
    UINT8  HwAddressLength;
    UINT8  SwAddressLength;
} EFI_ARP_FIND_DATA;
```

Size

Length in bytes of this entry.

DenyFlag

Set to **TRUE** if this entry is a “deny” entry.
Set to **FALSE** if this entry is a “normal” entry.

StaticFlag

Set to **TRUE** if this entry will not time out.
Set to **FALSE** if this entry will time out.

HwAddressType

16-bit ARP hardware identifier number.

SwAddressType

16-bit protocol type number.

HwAddressLength

Length of the hardware address.

SwAddressLength

Length of the protocol address.

Status Codes Returned
29.1.6 EFI_ARP_PROTOCOL.Delete()

**Summary**

Removes entries from the ARP cache.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_ARP_DELETE) (
    IN EFI_ARP_PROTOCOL *This,
    IN BOOLEAN BySwAddress,
    IN VOID *AddressBuffer OPTIONAL
);
```

**Parameters**

- **This**
  
  A pointer to the `EFI_ARP_PROTOCOL` instance.

- **BySwAddress**
  
  Set to `TRUE` to delete matching protocol addresses.
  
  Set to `FALSE` to delete matching hardware addresses.

- **AddressBuffer**
  
  Pointer to the address buffer that is used as a key to look for the cache entry. Set to `NULL` to delete all entries.

**Description**

The `Delete()` function removes specified ARP cache entries.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The entry was removed from the ARP cache.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER| One or more of the following conditions is `TRUE`:
  • `This` is `NULL`.
  • Both `EntryCount` and `EntryLength` are `NULL`, when `Refresh` is `FALSE`. |
| EFI_NOT_FOUND        | No matching entries were found.                                             |
| EFI_NOT_STARTED      | The ARP driver instance has not been configured.                            |
29.1.7 EFI_ARP_PROTOCOL.Flush()

**Summary**
Removes all dynamic ARP cache entries that were added by this interface.

**Prototype**
```c
typedef EFI_STATUS (EFIAPI *EFI_ARP_FLUSH) (IN EFI_ARP_PROTOCOL *This);
```

**Parameters**

**This**
A pointer to the EFI_ARP_PROTOCOL instance.

**Description**
The Flush() function deletes all dynamic entries from the ARP cache that match the specified software protocol type.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The cache has been flushed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>There are no matching dynamic cache entries.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The ARP driver instance has not been configured.</td>
</tr>
</tbody>
</table>

29.1.8 EFI_ARP_PROTOCOL.Request()

**Summary**
Starts an ARP request session.

**Prototype**
```c
typedef EFI_STATUS (EFIAPI *EFI_ARP_REQUEST) (IN EFI_ARP_PROTOCOL *This,
                                             IN VOID *TargetSwAddress OPTIONAL,
                                             IN EFI_EVENT ResolvedEvent OPTIONAL,
                                             OUT VOID *TargetHwAddress);
```

**Parameters**

**This**
A pointer to the EFI_ARP_PROTOCOL instance.

**TargetSwAddress**
Pointer to the protocol address to resolve.
ResolvedEvent
Pointer to the event that will be signaled when the address is resolved or some error occurs.

TargetHwAddress
Pointer to the buffer for the resolved hardware address in network byte order. The buffer must be large enough
to hold the resulting hardware address. TargetHwAddress must not be NULL.

Description
The Request() function tries to resolve the TargetSwAddress and optionally returns a TargetHwAddress if it already
exists in the ARP cache.

If the registered SwAddressType (see EFI_ARP_PROTOCOL.Add() ) is IPv4 or IPv6 and the TargetSwAddress is a multicast address, then the TargetSwAddress is resolved using the underlying EFI_MANAGED_NETWORK_PROTOCOL.McastIpToMac() function.

If the TargetSwAddress is NULL, then the network interface hardware broadcast address is returned immediately in TargetHwAddress.

If the ResolvedEvent is not NULL and the address to be resolved is not in the ARP cache, then the event will be
signaled when the address request completes and the requested hardware address is returned in the TargetHwAddress.

If the timeout expires and the retry count is exceeded or an unexpected error occurs, the event will be signaled to notify
the caller, which should check the TargetHwAddress to see if the requested hardware address is available. If it is not
available, the TargetHwAddress is filled by zero.

If the address to be resolved is already in the ARP cache and resolved, then the event will be signaled immediately if it
is not NULL, and the requested hardware address is also returned in TargetHwAddress.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data was copied from the ARP cache into the TargetHwAddress buffer.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE: This is NULL TargetHwAddress is NULL</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The requested address is not present in the normal ARP cache but is present in the deny address list. Outgoing traffic to that address is forbidden.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The ARP driver instance has not been configured.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The request has been started and is not finished.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The requested conversion is not supported in this implementation or configuration.</td>
</tr>
</tbody>
</table>

29.1.9 EFI_ARP_PROTOCOL.Cancel()

Summary
Cancels an ARP request session.

Prototype

```c
typedef EFI_STATUS
(EFI_API *EFI_ARP_CANCEL) (     *This,     
    IN EFI_ARP_PROTOCOL         *TargetSwAddress OPTIONAL,     
    IN VOID                     
);```

(continues on next page)
Parameters

This
   A pointer to the EFI_ARP_PROTOCOL instance.

TargetSwAddress
   Pointer to the protocol address in previous request session.

ResolvedEvent
   Pointer to the event that is used as the notification event in previous request session.

Description

The Cancel() function aborts the previous ARP request (identified by This, TargetSwAddress and ResolvedEvent) that is issued by EFI_ARP_PROTOCOL.Request(). If the request is in the internal ARP request queue, the request is aborted immediately and its ResolvedEvent is signaled. Only an asynchronous address request needs to be canceled. If TargetSwAddress and ResolvedEvent are both NULL, all the pending asynchronous requests that have been issued by This instance will be cancelled and their corresponding events will be signaled.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The pending request session(s) is/are aborted and corresponding event(s) is/are signaled.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER| One or more of the following conditions is TRUE:
   • This is NULL.
   • TargetSwAddress is not NULL and ResolvedEvent is NULL
   • TargetSwAddress is NULL and ResolvedEvent is not NULL |
| EFI_NOT_STARTED      | The ARP driver instance has not been configured. |
| EFI_NOT_FOUND        | The request is not issued by EFI_ARP_PROTOCOL.Request(). |

29.2 EFI DHCPv4 Protocol

This section provides a detailed description of the EFI_DHCP4_PROTOCOL and the EFI_DHCP4_SERVICE_BINDING_PROTOCOL. The EFI DHCPv4 Protocol is used to collect configuration information for the EFI IPv4 Protocol drivers and to provide DHCPv4 server and PXE boot server discovery services.

29.2.1 EFI_DHCP4_SERVICE_BINDING_PROTOCOL

Summary

The EFI DHCPv4 Service Binding Protocol is used to locate communication devices that are supported by an EFI DHCPv4 Protocol driver and to create and destroy EFI DHCPv4 Protocol child driver instances that can use the underlying communications device.

GUID
Description

A network application or driver that requires basic DHCPv4 services can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish an EFI DHCPv4 Service Binding Protocol GUID. Each device with a published EFI DHCPv4 Service Binding Protocol GUID supports the EFI DHCPv4 Protocol and may be available for use.

After a successful call to the `EFI_DHCP4_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the newly created EFI DHCPv4 Protocol child driver instance is ready to be used by a network application or driver.

Before a network application or driver terminates execution, every successful call to the `EFI_DHCP4_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI_DHCP4_SERVICE_BINDING_PROTOCOL.DestroyChild()` function.

### 29.2.2 EFI_DHCP4_PROTOCOL

Summary

This protocol is used to collect configuration information for the EFI IPv4 Protocol drivers and to provide DHCPv4 server and PXE boot server discovery services.

GUID

```c
#define EFI_DHCP4_PROTOCOL_GUID \
{0x8a219718,0x4ef5,0x4761,\ 
 {0x91,0xc8,0xc0,0xf0,0x4b,0xda,0x9e,0x56}}
```

Protocol Interface Structure

```c
typedef struct _EFI_DHCP4_PROTOCOL {
    EFI_DHCP4_GET_MODE_DATA GetModeData;
    EFI_DHCP4_CONFIGURE Configure;
    EFI_DHCP4_START Start;
    EFI_DHCP4_RENEW_REBIND RenewRebind;
    EFI_DHCP4_RELEASE Release;
    EFI_DHCP4_STOP Stop;
    EFI_DHCP4_BUILD Build;
    EFI_DHCP4_TRANSMIT_RECEIVE TransmitReceive;
    EFI_DHCP4_PARSE Parse;
} EFI_DHCP4_PROTOCOL;
```

Parameters

**GetModeData**

Gets the EFI DHCPv4 Protocol driver status and operational data. See the `GetModeData()` function description.

**Configure**

Initializes, changes, or resets operational settings for the EFI DHCPv4 Protocol driver. See the `Configure()` function description.

**Start**

Starts the DHCP configuration process. See the `Start()` function description.
RenewRebind
Tries to manually extend the lease time by sending a request packet. See the RenewRebind() function description.

Release
Releases the current configuration and returns the EFI DHCPv4 Protocol driver to the initial state. See the Release() function description.

Stop
Stops the DHCP configuration process no matter what state the driver is in. After being stopped, this driver will not automatically communicate with the DHCP server. See the Stop() function description.

Build
Puts together a DHCP or PXE packet. See the Build() function description.

TransmitReceive
Transmits a DHCP or PXE packet and waits for response packets. See the TransmitReceive() function description.

Parse
Parses the packed DHCP or PXE option data. See the Parse() function description.

Description
The EFI_DHCP4_PROTOCOL is used to collect configuration information for the EFI IPv4 Protocol driver and provide DHCP server and PXE boot server discovery services.

Byte Order Note
All the IPv4 addresses that are described in EFI_DHCP4_PROTOCOL are stored in network byte order. Both incoming and outgoing DHCP packets are also in network byte order. All other parameters that are defined in functions or data structures are stored in host byte order

29.2.3 EFI_DHCP4_PROTOCOL.GetModeData()

Summary
Returns the current operating mode and cached data packet for the EFI DHCPv4 Protocol driver.

Prototype

```c
typedef EFI_STATUS
(EFI_API *EFI_DHCP4_GET_MODE_DATA)(
    IN EFI_DHCP4_PROTOCOL *This,
    OUT EFI_DHCP4_MODE_DATA *Dhcp4ModeData
);
```

Parameters

This
Pointer to the EFI_DHCP4_PROTOCOL instance.

Dhcp4ModeData
Pointer to storage for the EFI_DHCP4_MODE_DATA structure. Type EFI_DHCP4_MODE_DATA is defined in “Related Definitions” below.

Description
The GetModeData() function returns the current operating mode and cached data packet for the EFI DHCPv4 Protocol driver.

Related Definitions
typedef struct {
    EFI_DHCP4_STATE State;
    EFI_DHCP4_CONFIG_DATA ConfigData;
    EFI_IPv4_ADDRESS ClientAddress;
    EFI_MAC_ADDRESS ClientMacAddress;
    EFI_IPv4_ADDRESS ServerAddress;
    EFI_IPv4_ADDRESS RouterAddress;
    EFI_IPv4_ADDRESS SubnetMask;
    UINT32 LeaseTime;
    EFI_DHCP4_PACKET *ReplyPacket;
} EFI_DHCP4_MODE_DATA;

State
The EFI DHCPv4 Protocol driver operating state. Type EFI_DHCP4_STATE is defined below.

ConfigData
The configuration data of the current EFI DHCPv4 Protocol driver instance. Type EFI_DHCP4_CONFIG_DATA is defined in EFI_DHCP4_PROTOCOL::Configure().

ClientAddress
The client IP address that was acquired from the DHCP server. If it is zero, the DHCP acquisition has not completed yet and the following fields in this structure are undefined.

ClientMacAddress
The local hardware address.

ServerAddress
The server IP address that is providing the DHCP service to this client.

RouterAddress
The router IP address that was acquired from the DHCP server. May be zero if the server does not offer this address.

SubnetMask
The subnet mask of the connected network that was acquired from the DHCP server.

LeaseTime
The lease time (in 1-second units) of the configured IP address. The value 0xFFFFFFFF means that the lease time is infinite. A default lease of 7 days is used if the DHCP server does not provide a value.

ReplyPacket
The cached latest DHCPOFFER, DHCPACK, DHCPNAK, or BOOTP Reply packet. May be NULL if no packet is cached.

The EFI_DHCP4_MODE_DATA structure describes the operational data of the current DHCP procedure.
Dhcp4Renewing = 0x5,
Dhcp4Rebinding = 0x6,
Dhcp4InitReboot = 0x7,
Dhcp4Rebooting = 0x8
} EFI_DHCP4_STATE;

Table 29.8: DHCP4 Enumerations

<table>
<thead>
<tr>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dhcp4Stopped</td>
<td>The EFI DHCPv4 Protocol driver is stopped and EFI_DHCP4_PROTOCOL.Configure() needs to be called. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.</td>
</tr>
<tr>
<td>Dhcp4Init</td>
<td>The EFI DHCPv4 Protocol driver is inactive and EFI_DHCP4_PROTOCOL.Start() needs to be called. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.</td>
</tr>
<tr>
<td>Dhcp4Selecting</td>
<td>The EFI DHCPv4 Protocol driver is collecting DHCP offer packets from DHCP servers. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.</td>
</tr>
<tr>
<td>Dhcp4Requesting</td>
<td>The EFI DHCPv4 Protocol driver has sent the request to the DHCP server and is waiting for a response. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.</td>
</tr>
<tr>
<td>Dhcp4Bound</td>
<td>The DHCP configuration has completed. All of the fields in the EFI_DHCP4_MODE_DATA structure are defined.</td>
</tr>
<tr>
<td>Dhcp4Renewing</td>
<td>The DHCP configuration is being renewed and another request has been sent out, but it has not received a response from the server yet. All of the fields in the EFI_DHCP4_MODE_DATA structure are available but may change soon.</td>
</tr>
<tr>
<td>Dhcp4Rebinding</td>
<td>The DHCP configuration has timed out and the EFI DHCPv4 Protocol driver is trying to extend the lease time. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.</td>
</tr>
<tr>
<td>Dhcp4InitReboot</td>
<td>The EFI DHCPv4 Protocol driver is initialized with a previously allocated or known IP address. EFI_DHCP4_PROTOCOL.Start() needs to be called to start the configuration process. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.</td>
</tr>
<tr>
<td>Dhcp4Rebooting</td>
<td>The EFI DHCP4 Protocol driver is seeking to reuse the previously allocated IP address by sending a request to the DHCP server. The rest of the EFI_DHCP4_MODE_DATA structure is undefined in this state.</td>
</tr>
</tbody>
</table>

EFI_DHCP4_STATE defines the DHCP operational states that are described in RFC 2131, which can be obtained at “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “RFC 2131”.

A variable number of EFI DHCPv4 Protocol driver instances can coexist but they share the same state machine. More precisely, each communication device has a separate DHCP state machine if there are multiple communication devices. Each EFI DHCPv4 Protocol driver instance that is created by the same EFI DHCPv4 Service Binding Protocol driver instance shares the same state machine. In this document, when we refer to the state of EFI DHCPv4 Protocol driver, we actually refer to the state of the communication device from which the current EFI DHCPv4 Protocol Driver instance is created.

```c
#pragma pack(1)
typedef struct {  
```
UINT32 Size;
UINT32 Length;
struct{
    EFI_DHCP4_HEADER Header;
    UINT32 Magik;
    UINT8 Option[1];
} Dhcp4;
} FI_DHCP4_PACKET;
#pragma pack()

Size
Size of the EFI_DHCP4_PACKET buffer.

Length
Length of the EFI_DHCP4_PACKET from the first byte of the Header field to the last byte of the Option[] field.

Header
DHCP packet header.

Magik
DHCP magik cookie in network byte order.

Option
Start of the DHCP packed option data. EFI_DHCP4_PACKET defines the format of DHCPv4 packets. See RFC 2131 for more information.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The mode data was returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
</tbody>
</table>

29.2.4 EFI_DHCP4_PROTOCOL.Configure()

Summary
Initializes, changes, or resets the operational settings for the EFI DHCPv4 Protocol driver.

Prototype
typedef
EFI_STATUS
(EIFIAPIC *EFI_DHCP4_CONFIGURE) (  
    IN EFI_DHCP4_PROTOCOL    *This,  
    IN EFI_DHCP4_CONFIG_DATA *Dhcp4CfgData OPTIONAL
);

Parameters

This
Pointer to the EFI_DHCP4_PROTOCOL instance.

Dhcp4CfgData
Pointer to the EFI_DHCP4_CONFIG_DATA. Type EFI_DHCP4_CONFIG_DATA is defined in “Related Definitions” below.
The `Configure()` function is used to initialize, change, or reset the operational settings of the EFI DHCPv4 Protocol driver for the communication device on which the EFI DHCPv4 Service Binding Protocol is installed. This function can be successfully called only if both of the following are true:

- This instance of the EFI DHCPv4 Protocol driver is in the `Dhcp4Stopped`, `Dhcp4Init`, `Dhcp4InitReboot`, or `Dhcp4Bound` states.
- No other EFI DHCPv4 Protocol driver instance that is controlled by this EFI DHCPv4 Service Binding Protocol driver instance has configured this EFI DHCPv4 Protocol driver.

When this driver is in the `Dhcp4Stopped` state, it can transfer into one of the following two possible initial states:

- `Dhcp4Init`
- `Dhcp4InitReboot`

The driver can transfer into these states by calling `Configure()` with a non-NULL `Dhcp4CfgData`. The driver will transfer into the appropriate state based on the supplied client network address in the `ClientAddress` parameter and DHCP options in the `OptionList` parameter as described in RFC 2131.

When `Configure()` is called successfully while `Dhcp4CfgData` is set to NULL, the default configuring data will be reset in the EFI DHCPv4 Protocol driver and the state of the EFI DHCPv4 Protocol driver will not be changed. If one instance wants to make it possible for another instance to configure the EFI DHCPv4 Protocol driver, it must call this function with `Dhcp4CfgData` set to NULL.

**Related Definitions**

```c
typedef struct {
    UINT32 DiscoverTryCount;
    UINT32 *DiscoverTimeout;
    UINT32 RequestTryCount;
    UINT32 *RequestTimeout;
    EFI_IPv4_ADDRESS ClientAddress;
    EFI_DHCP4_CALLBACK Dhcp4Callback;
    VOID *CallbackContext;
    UINT32 OptionCount;
    EFI_DHCP4_PACKET_OPTION **OptionList;
} EFI_DHCP4_CONFIG_DATA;
```

**DiscoverTryCount**
Number of times to try sending a packet during the `Dhcp4SendDiscover` event and waiting for a response during the `Dhcp4RcvdOffer` event. (This value is also the number of entries in the `DiscoverTimeout` array.) Set to zero to use the default try counts and timeout values.

**DiscoverTimeout**
Maximum amount of time (in seconds) to wait for returned packets in each of the retries. Timeout values of zero will default to a timeout value of one second. Set to NULL to use default timeout values.

**RequestTryCount**
Number of times to try sending a packet during the `Dhcp4SendRequest` event and waiting for a response during the `Dhcp4RcvdAck` event before accepting failure. (This value is also the number of entries in the `RequestTimeout` array.) Set to zero to use the default try counts and timeout values.

**RequestTimeout**
Maximum amount of time (in seconds) to wait for return packets in each of the retries. Timeout values of zero will default to a timeout value of one second. Set to NULL to use default timeout values.
ClientAddress

For a DHCPDISCOVER, setting this parameter to the previously allocated IP address will cause the EFI DHCPv4 Protocol driver to enter the Dhcp4InitReboot state. Also, set this field to 0.0.0.0 to enter the Dhcp4Init state. For a DHCPINFORM this parameter should be set to the client network address which was assigned to the client during a DHCPDISCOVER.

Dhcp4Callback

The callback function to intercept various events that occurred in the DHCP configuration process. Set to NULL to ignore all those events. Type EFI_DHCP4_CALLBACK is defined below.

CallbackContext

Pointer to the context that will be passed to Dhcp4Callback when it is called.

OptionCount

Number of DHCP options in the OptionList.

OptionList

List of DHCP options to be included in every packet that is sent during the Dhcp4SendDiscover event. Pad options are appended automatically by DHCP driver in outgoing DHCP packets. If OptionList itself contains pad option, they are ignored by the driver. OptionList can be freed after EFI_DHCP4_PROTOCOL.Configure() returns. Ignored if OptionCount is zero. Type EFI_DHCP4_PACKET_OPTION is defined below.

```c
typedef EFI_STATUS (*EFI_DHCP4_CALLBACK)(
    IN EFI_DHCP4_PROTOCOL *This,
    IN VOID *Context,
    IN EFI_DHCP4_STATE CurrentState,
    IN EFI_DHCP4_EVENT Dhcp4Event,
    IN EFI_DHCP4_PACKET *Packet, OPTIONAL
    OUT EFI_DHCP4_PACKET **NewPacket OPTIONAL
);
```

This

Pointer to the EFI DHCPv4 Protocol instance that is used to configure this callback function.

Context

Pointer to the context that is initialized by EFI_DHCP4_PROTOCOL.Configure().

CurrentState

The current operational state of the EFI DHCPv4 Protocol driver. Type EFI_DHCP4_STATE is defined in EFI_DHCP4_PROTOCOL.GetModeData().

Dhcp4Event

The event that occurs in the current state, which usually means a state transition. Type EFI_DHCP4_EVENT is defined below.

Packet

The DHCP packet that is going to be sent or already received. May be NULL if the event has no associated packet. Do not cache this packet except for copying it. Type EFI_DHCP4_PACKET is defined in EFI_DHCP4_PROTOCOL.GetModeData().

NewPacket

The packet that is used to replace the above Packet. Do not set this pointer exactly to the above Packet or a modified Packet. NewPacket can be NULL if the EFI DHCPv4 Protocol driver does not expect a new packet to be returned. The user may set NewPacket to NULL if no replacement occurs.
EFI_DHCP4_CALLBACK is provided by the consumer of the EFI DHCPv4 Protocol driver to intercept events that occurred in the configuration process. This structure provides advanced control of each state transition of the DHCP process. The returned status code determines the behavior of the EFI DHCPv4 Protocol driver. There are three possible returned values, which are described in the following table.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Tells the EFI DHCPv4 Protocol driver to continue the DHCP process. When it is in the <em>Dhcp4Selecting</em> state, it tells the EFI DHCPv4 Protocol driver to stop collecting additional packets. The driver will exit the <em>Dhcp4Selecting</em> state and enter the <em>Dhcp4Requesting</em> state.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>Only used in the <em>Dhcp4Selecting</em> state. The EFI DHCPv4 Protocol driver will continue to wait for more packets until the retry timeout expires.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>Tells the EFI DHCPv4 Protocol driver to abort the current process and return to the <em>Dhcp4Init</em> or <em>Dhcp4InitReboot</em> state.</td>
</tr>
</tbody>
</table>

```c
typedef enum {
    Dhcp4SendDiscover = 0x01,
    Dhcp4RcvdOffer     = 0x02,
    Dhcp4SelectOffer   = 0x03,
    Dhcp4SendRequest   = 0x04,
    Dhcp4RcvdAck       = 0x05,
    Dhcp4RcvdNak       = 0x06,
    Dhcp4SendDecline   = 0x07,
    Dhcp4BoundCompleted = 0x08,
    Dhcp4EnterRenewing = 0x09,
    Dhcp4EnterRebinding = 0x0a,
    Dhcp4AddressLost   = 0x0b,
    Dhcp4Fail          = 0x0c
} EFI_DHCP4_EVENT;
```

Following is a description of the fields in the above enumeration.

**Dhcp4SendDiscover**

The packet to start the configuration sequence is about to be sent. The packet is passed to *Dhcp4Callback* and can be modified or replaced in *Dhcp4Callback*.

**Dhcp4RcvdOffer**

A reply packet was just received. This packet is passed to *Dhcp4Callback*, which may copy this packet and cache it for selecting a task later. If the callback returns *EFI_SUCCESS*, this driver will finish the selecting state. If *EFI_NOT_READY* is returned, this driver will continue to wait for additional reply packets until the timer expires. In either case, *Dhcp4SelectOffer* will occur for the user to select an offer.

**Dhcp4SelectOffer**

It is time for *Dhcp4Callback* to select an offer. This driver passes the latest received DHCPOFFER packet to the callback. The *Dhcp4Callback* may store one packet in the *NewPacket* parameter of the function that was selected from previously received DHCPOFFER packets. If the latest packet is the selected one or if the user does not care about it, no extra overhead is needed. Simply skipping this event is enough.

**Dhcp4SendRequest**

A request packet is about to be sent. The user can modify or replace this packet.
Dhcp4RcvdAck
A DHCPACK packet was received and will be passed to Dhcp4Callback. The callback may decline this DHCPACK packet by returning EFI_ABORTED. In this case, the EFI DHCPv4 Protocol driver will proceed to the Dhcp4SendDecline event.

Dhcp4RcvdNak
A DHCPNAK packet was received and will be passed to Dhcp4Callback. The EFI DHCPv4 Protocol driver will then return to the Dhcp4Init state no matter what status code is returned from the callback function.

Dhcp4SendDecline
A decline packet is about to be sent. Dhcp4Callback can modify or replace this packet. The EFI DHCPv4 Protocol driver will then be set to the Dhcp4Init state.

Dhcp4BoundCompleted
The DHCP configuration process has completed. No packet is associated with this event.

Dhcp4EnterRenewing
It is time to enter the Dhcp4Renewing state and to contact the server that originally issued the network address. No packet is associated with this event.

Dhcp4EnterRebinding
It is time to enter the Dhcp4Rebinding state and to contact any server. No packet is associated with this event.

Dhcp4AddressLost
The configured IP address was lost either because the lease has expired, the user released the configuration, or a DHCPNAK packet was received in the Dhcp4Renewing or Dhcp4Rebinding state. No packet is associated with this event.

Dhcp4Fail
The DHCP process failed because a DHCPNAK packet was received or the user aborted the DHCP process at a time when the configuration was not available yet. No packet is associated with this event.

```c
//************************************************************
// EFI_DHCP4_HEADER
//************************************************************
#pragma pack(1)
typedef struct{
    UINT8 OpCode;
    UINT8 HwType;
    UINT8 HwAddrLen;
    UINT8 Hops;
    UINT32 Xid;
    UINT16 Seconds;
    UINT16 Reserved;
    EFI_IPv4_ADDRESS ClientAddr;
    EFI_IPv4_ADDRESS YourAddr;
    EFI_IPv4_ADDRESS ServerAddr;
    EFI_IPv4_ADDRESS GatewayAddr;
    UINT8 ClientHwAddr[16];
    CHAR8 ServerName[64];
    CHAR8 BootFileName[128];
} EFI_DHCP4_HEADER;
#pragma pack()
```

**OpCode**
Message type. 1 = BOOTREQUEST, 2 = BOOTREPLY.
HwType
   Hardware address type.

HwAddrLen
   Hardware address length.

Hops
   Maximum number of hops (routers, gateways, or relay agents) that this DHCP packet can go through before it is dropped.

Xid
   DHCP transaction ID.

Seconds
   Number of seconds that have elapsed since the client began address acquisition or the renewal process.

Reserved
   Reserved for future use.

ClientAddr
   Client IP address from the client.

YourAddr
   Client IP address from the server.

ServerAddr
   IP address of the next server in bootstrap.

GatewayAddr
   Relay agent IP address.

ClientHwAddr
   Client hardware address.

ServerName
   Optional server host name.

BootFileName
   Boot file name.

EFI_DHCP4_HEADER describes the semantics of the DHCP packet header. This packet header is in network byte order.

// ..............................................................
// EFI_DHCP4_PACKET_OPTION
// ..............................................................
#pragma pack(1)
typedef struct {
   UINT8 OpCode;
   UINT8 Length;
   UINT8 Data[1];
} EFI_DHCP4_PACKET_OPTION;
#pragma pack()

OpCode
   DHCP option code.

Length
   Length of the DHCP option data. Not present if OpCode is 0 or 255.

Data
   Start of the DHCP option data. Not present if OpCode is 0 or 255 or if Length is zero.
The DHCP packet option data structure is used to reference option data that is packed in the DHCP packets. Use caution when accessing multibyte fields because the information in the DHCP packet may not be properly aligned for the machine architecture.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The EFI DHCPv4 Protocol driver is now in the Dhcp4Init or Dhcp4InitReboot state, if the original state of this driver was Dhcp4Stopped, Dhcp4Init, Dhcp4InitReboot, or Dhcp4Bound and the value of Dhcp4CfgData was not NULL. Otherwise, the state was left unchanged.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>This instance of the EFI DHCPv4 Protocol driver was not in the Dhcp4Stopped, Dhcp4Init, Dhcp4InitReboot, or Dhcp4Bound state.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Another instance of this EFI DHCPv4 Protocol driver is already in a valid configured state.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more following conditions are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• DiscoverTryCount &gt; 0 and DiscoverTimeout is NULL</td>
</tr>
<tr>
<td></td>
<td>• RequestTryCount &gt; 0 and RequestTimeout is NULL</td>
</tr>
<tr>
<td></td>
<td>• OptionCount &gt; 0 and OptionList is NULL</td>
</tr>
<tr>
<td></td>
<td>• ClientAddress is not a valid unicast address.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
</tbody>
</table>

### 29.2.5 EFI_DHCP4_PROTOCOL.Start()

**Summary**

Starts the DHCP configuration process.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_DHCP4_START) (  
    IN EFI_DHCP4_PROTOCOL  *This,  
    IN EFI_EVENT  CompletionEvent OPTIONAL  
);
```

**Parameters**

- **This**  
  Pointer to the EFI_DHCP4_PROTOCOL instance.

- **CompletionEvent**  
  If not NULL, indicates the event that will be signaled when the EFI DHCPv4 Protocol driver is transferred into the Dhcp4Bound state or when the DHCP process is aborted. EFI_DHCP4_PROTOCOL.GetModeData() can be called to check the completion status. If NULL, EFI_DHCP4_PROTOCOL.Start() will wait until the driver is transferred into the Dhcp4Bound state or the process fails.

**Description**

The Start() function starts the DHCP configuration process. This function can be called only when the EFI DHCPv4 Protocol driver is in the Dhcp4Init or Dhcp4InitReboot state.
If the DHCP process completes successfully, the state of the EFI DHCPv4 Protocol driver will be transferred through `Dhcp4Selecting` and `Dhcp4Requesting` to the `Dhcp4Bound` state. The `CompletionEvent` will then be signaled if it is not `NULL`.

If the process aborts, either by the user or by some unexpected network error, the state is restored to the `Dhcp4Init` state. The `Start()` function can be called again to restart the process.

Refer to RFC 2131 for precise state transitions during this process. At the time when each event occurs in this process, the callback function that was set by `EFI_DHCP4_PROTOCOL .Configure()` will be called and the user can take this opportunity to control the process.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The DHCP configuration process has started, or it has completed when <code>CompletionEvent</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td><code>EFI_NOT_STARTED</code></td>
<td>The EFI DHCPv4 Protocol driver is in the <code>Dhcp4Stopped</code> state. <code>EFI_DHCP4_PROTOCOL .Configure()</code> needs to be called.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td><code>This is NULL.</code>.</td>
</tr>
<tr>
<td><code>EFI_OUT_OF_RESOURCES</code></td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td><code>EFI_TIMEOUT</code></td>
<td>The DHCP configuration process failed because no response was received from the server within the specified timeout value.</td>
</tr>
<tr>
<td><code>EFI_ABORTED</code></td>
<td>The user aborted the DHCP process.</td>
</tr>
<tr>
<td><code>EFI_ALREADY_STARTED</code></td>
<td>Some other EFI DHCPv4 Protocol instance already started the DHCP process.</td>
</tr>
<tr>
<td><code>EFI_DEVICE_ERROR</code></td>
<td>An unexpected network or system error occurred.</td>
</tr>
<tr>
<td><code>EFI_NO_MEDIA</code></td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

### 29.2.6 `EFI_DHCP4_PROTOCOL .RenewRebind()`

**Summary**

Extends the lease time by sending a request packet.

**Prototype**

```c
typedef EFI_STATUS
(EIFIAPI *EFI_DHCP4_RENEW_REBIND) (
    IN EFI_DHCP4_PROTOCOL *This,
    IN BOOLEAN RebindRequest,
    IN EFI_EVENT CompletionEvent OPTIONAL
);
```

**Parameters**

**This**

Pointer to the `EFI_DHCP4_PROTOCOL` instance.

**RebindRequest**

If `TRUE`, this function broadcasts the request packets and enters the `Dhcp4Rebinding` state. Otherwise, it sends a unicast request packet and enters the `Dhcp4Renewing` state.

**CompletionEvent**

If not `NULL`, this event is signaled when the renew/rebind phase completes or some error occurs. `EFI_DHCP4_PROTOCOL .GetModeData()` can be called to check the completion status. If `NULL`, `EFI_DHCP4_PROTOCOL .RenewRebind()` will busy-wait until the DHCP process finishes.

---

29.2. EFI DHCPv4 Protocol

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Description

The `RenewRebind()` function is used to manually extend the lease time when the EFI DHCPv4 Protocol driver is in the `Dhcp4Bound` state and the lease time has not expired yet. This function will send a request packet to the previously found server (or to any server when `RebindRequest` is `TRUE`) and transfer the state into the `Dhcp4Renewing` state (or `Dhcp4Rebinding` when `RebindingRequest` is `TRUE`). When a response is received, the state is returned to `Dhcp4Bound`.

If no response is received before the try count is exceeded (the `RequestTryCount` field that is specified in `EFI_DHCP4_CONFIG_DATA`) but before the lease time that was issued by the previous server expires, the driver will return to the `Dhcp4Bound` state and the previous configuration is restored. The outgoing and incoming packets can be captured by the `EFI_DHCP4_CALLBACK` function.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>The EFI DHCPv4 Protocol driver is now in the <code>Dhcp4Renewing</code> state or is</td>
</tr>
<tr>
<td></td>
<td>back to the <code>Dhcp4Bound</code> state.</td>
</tr>
<tr>
<td><strong>EFI_NOT_STARTED</strong></td>
<td>The EFI DHCPv4 Protocol driver is in the <code>Dhcp4Stopped</code> state. <code>EFI_DHCP4_PROTOCOL::Configure()</code> needs to be called.</td>
</tr>
<tr>
<td><strong>EFI_INVALID_PARAMETER</strong></td>
<td>There is <code>NULL</code>.</td>
</tr>
<tr>
<td><strong>EFI_TIMEOUT</strong></td>
<td>There was no response from the server when the try count was exceeded.</td>
</tr>
<tr>
<td><strong>EFI_ACCESS_DENIED</strong></td>
<td>The driver is not in the <code>Dhcp4Bound</code> state.</td>
</tr>
<tr>
<td><strong>EFI_DEVICE_ERROR</strong></td>
<td>An unexpected network or system error occurred.</td>
</tr>
</tbody>
</table>

29.2.7 `EFI_DHCP4_PROTOCOL::Release()`

Summary

Releases the current address configuration.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_DHCP4_RELEASE) (IN EFI_DHCP4_PROTOCOL *This);
```

Parameters

This

* Pointer to the `EFI_DHCP4_PROTOCOL` instance.

Description

The `Release()` function releases the current configured IP address by doing either of the following:

- Sending a DHCPRELEASE packet when the EFI DHCPv4 Protocol driver is in the `Dhcp4Bound` state
- Setting the previously assigned IP address that was provided with the `EFI_DHCP4_PROTOCOL::Configure()` function to 0.0.0.0 when the driver is in `Dhcp4InitReboot` state

After a successful call to this function, the EFI DHCPv4 Protocol driver returns to the `Dhcp4Init` state and any subsequent incoming packets will be discarded silently.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>The EFI DHCPv4 Protocol driver is now in the <code>Dhcp4Init</code> phase.</td>
</tr>
</tbody>
</table>

continues on next page
Table 29.14 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The EFI DHCPv4 Protocol driver is not in the Dhcp4Bound or</td>
</tr>
<tr>
<td></td>
<td>Dhcp4InitReboot state.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network or system error occurred.</td>
</tr>
</tbody>
</table>

29.2.8 EFI_DHCP4_PROTOCOL.Stop()

Summary

Stops the DHCP configuration process.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_DHCP4_STOP) (
    IN EFI_DHCP4_PROTOCOL *This
);
```

Parameters

This

Pointer to the EFI_DHCP4_PROTOCOL instance.

Description

The Stop() function is used to stop the DHCP configuration process. After this function is called successfully, the EFI DHCPv4 Protocol driver is transferred into the Dhcp4Stopped state. EFI_DHCP4_PROTOCOL.Configure() needs to be called before DHCP configuration process can be started again. This function can be called when the EFI DHCPv4 Protocol driver is in any state.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The EFI DHCPv4 Protocol driver is now in the Dhcp4Stopped state.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

29.2.9 EFI_DHCP4_PROTOCOL.Build()

Summary

Builds a DHCP packet, given the options to be appended or deleted or replaced.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_DHCP4_BUILD) ( 
    IN EFI_DHCP4_PROTOCOL *This,
    IN EFI_DHCP4_PACKET SeedPacket,
    IN UINT32 DeleteCount,
    IN UINT8 *DeleteList OPTIONAL,
    IN UINT32 AppendCount,
    IN EFI_DHCP4_PACKET_OPTION *AppendList[] OPTIONAL,
);
```

(continues on next page)
Parameters

This

Pointer to the EFI_DHCP4_PROTOCOL instance.

SeedPacket

Initial packet to be used as a base for building new packet. Type EFI_DHCP4_PACKET is defined in EFI_DHCP4_PROTOCOL.GetModeData().

DeleteCount

Number of opcodes in the DeleteList.

DeleteList

List of opcodes to be deleted from the seed packet. Ignored if DeleteCount is zero.

AppendCount

Number of entries in the OptionList.

AppendList

Pointer to a DHCP option list to be appended to SeedPacket. If SeedPacket also contains options in this list, they are replaced by new options (except pad option). Ignored if AppendCount is zero. Type EFI_DHCP4_PACKET_OPTION is defined in EFI_DHCP4_PROTOCOL.Configure().

NewPacket

Pointer to storage for the pointer to the new allocated packet. Use the EFI Boot Service FreePool() on the resulting pointer when done with the packet.

Description

The Build() function is used to assemble a new packet from the original packet by replacing or deleting existing options or appending new options. This function does not change any state of the EFI DHCPv4 Protocol driver and can be used at any time.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The new packet was built.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Storage for the new packet could not be allocated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td></td>
</tr>
<tr>
<td></td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• SeedPacket is NULL.</td>
</tr>
<tr>
<td></td>
<td>• SeedPacket is not a well-formed DHCP packet.</td>
</tr>
<tr>
<td></td>
<td>• AppendCount is not zero and AppendList is NULL.</td>
</tr>
<tr>
<td></td>
<td>• DeleteCount is not zero and DeleteList is NULL.</td>
</tr>
<tr>
<td></td>
<td>• NewPacket is NULL</td>
</tr>
<tr>
<td></td>
<td>• Both DeleteCount and AppendCount are zero and NewPacket is not NULL.</td>
</tr>
</tbody>
</table>
29.2.10 EFI_DHCP4_PROTOCOL.TransmitReceive()

Summary
Transmits a DHCP formatted packet and optionally waits for responses.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_DHCP4_TRANSMIT_RECEIVE) (
    IN EFI_DHCP4_PROTOCOL *This,
    IN EFI_DHCP4_TRANSMIT_RECEIVE_TOKEN *Token
);
```

Parameters

This
Pointer to the EFI_DHCP4_PROTOCOL instance.

Token
Pointer to the EFI_DHCP4_TRANSMIT_RECEIVE_TOKEN structure. Type EFI_DHCP4_TRANSMIT_RECEIVE_TOKEN is defined in “Related Definitions” below.

Description
The TransmitReceive() function is used to transmit a DHCP packet and optionally wait for the response from servers. This function does not change the state of the EFI DHCPv4 Protocol driver and thus can be used at any time.

Related Definitions

```c
//**************************************************
// EFI_DHCP4_TRANSMIT_RECEIVE_TOKEN
//**************************************************
typedef struct {
    EFI_STATUS Status;
    EFI_EVENT CompletionEvent;
    EFI_IPv4_ADDRESS RemoteAddress;
    UINT16 RemotePort;
    EFI_IPv4_ADDRESS GatewayAddress;
    UINT32 ListenPointCount;
    EFI_DHCP4_LISTEN_POINT *ListenPoints;
    UINT32 TimeoutValue;
    EFI_DHCP4_PACKET *Packet;
    UINT32 ResponseCount;
    EFI_DHCP4_PACKET *ResponseList;
} EFI_DHCP4_TRANSMIT_RECEIVE_TOKEN;
```

Status
The completion status of transmitting and receiving. Possible values are described in the “Status Codes Returned” table below. When CompletionEvent is NULL, this status is the same as the one returned by the TransmitReceive() function.

CompletionEvent
If not NULL, the event that will be signaled when the collection process completes. If NULL, this function will busy-wait until the collection process completes.
RemoteAddress
  Pointer to the server IP address. This address may be a unicast, multicast, or broadcast address.

RemotePort
  Server listening port number. If zero, the default server listening port number (67) will be used.

GatewayAddress
  Pointer to the gateway address to override the existing setting.

ListenPointCount
  The number of entries in ListenPoints. If zero, the default station address and port number 68 are used.

ListenPoints
  An array of station address and port number pairs that are used as receiving filters. The first entry is also used
  as the source address and source port of the outgoing packet. Type EFI_DHCP4_LISTEN_POINT is defined
  below.

TimeoutValue
  Number of seconds to collect responses. Zero is invalid.

Packet
  Pointer to the packet to be transmitted. Type EFI_DHCP4_PACKET is defined in EFI_DHCP4_PROTOCOL
  .GetModeData().

ResponseCount
  Number of received packets.

ResponseList
  Pointer to the allocated list of received packets. The caller must use the EFI Boot Service FreePool() when done
  using the received packets.

ListenAddress
  Alternate listening address. It can be a unicast, multicast, or broadcast address. The TransmitReceive() function
  will collect only those packets that are destined to this address.

SubnetMask
  The subnet mask of above listening unicast/broadcast IP address. Ignored if ListenAddress is a multicast address.
  If it is 0.0.0.0, the subnet mask is automatically computed from unicast ListenAddress. Cannot be 0.0.0.0 if
  ListenAddress is direct broadcast address on subnet.

ListenPort
  Alternate station source (or listening) port number. If zero, then the default station port number (68) will be used.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The packet was successfully queued for transmission.</td>
</tr>
</tbody>
</table>

//************************************************
// EFI_DHCP4_LISTEN_POINT
//************************************************
typedef struct {
  EFI_IPv4_ADDRESS ListenAddress;
  EFI_IPv4_ADDRESS SubnetMask;
  UINT16            ListenPort;
} EFI_DHCP4_LISTEN_POINT;
Table 29.17 – continued from previous page

<table>
<thead>
<tr>
<th>Code Point</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• Token.RemoteAddress is zero.</td>
</tr>
<tr>
<td></td>
<td>• Token.Packet is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• Token.Packet is not a well-formed DHCP packet.</td>
</tr>
<tr>
<td></td>
<td>• The transaction ID in Token.Packet is in use by another DHCP process.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The previous call to this function has not finished yet. Try to call this</td>
</tr>
<tr>
<td></td>
<td>function after collection process completes.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The default station address is not available yet.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation doesn’t support this function</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
<tr>
<td>Others</td>
<td>Some other unexpected error occurred.</td>
</tr>
</tbody>
</table>

### 29.2.11 EFI_DHCP4_PROTOCOL.Parse()

**Summary**

Parses the packed DHCP option data.

**Prototype**

```c
typedef EFI_STATUS
  __EFIAPI EFI_DHCP4_PARSE(    
    IN EFI_DHCP4_PROTOCOL *This,
    IN EFI_DHCP4_PACKET *Packet,
    IN OUT UINT32 *OptionCount,
    IN OUT EFI_DHCP4_PACKET_OPTION *PacketOptionList[] OPTIONAL
  );
```

**Parameters**

**This**

Pointer to the **EFI_DHCP4_PROTOCOL** instance.

**Packet**

Pointer to packet to be parsed. Type **EFI_DHCP4_PACKET** is defined in **EFI_DHCP4_PROTOCOL.GetModeData**().

**OptionCount**

On input, the number of entries in the **PacketOptionList**. On output, the number of entries that were written into the **PacketOptionList**.

**PacketOptionList**

List of packet option entries to be filled in. End option or pad options are not included. Type **EFI_DHCP4_PACKET_OPTION** is defined in **EFI_DHCP4_PROTOCOL.Configure**().

**Description**

The Parse() function is used to retrieve the option list from a DHCP packet. If *OptionCount isn’t zero, and there is enough space for all the DHCP options in the Packet, each element of PacketOptionList is set to point to somewhere in the Packet->Dhcp4.Option where a new DHCP option begins. If RFC3396 is supported, the caller should reassemble
the parsed DHCP options to get the final result. If *OptionCount is zero or there isn't enough space for all of them, the number of DHCP options in the Packet is returned in OptionCount.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The packet was successfully parsed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Packet is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Packet is not a well-formed DHCP packet.</td>
</tr>
<tr>
<td></td>
<td>• OptionCount is NULL.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• *OptionCount is smaller than the number of options that were found in</td>
</tr>
<tr>
<td></td>
<td>the Packet.</td>
</tr>
<tr>
<td></td>
<td>• PacketOptionList is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCE</td>
<td>The packet is failed to parse because of resource shortage.</td>
</tr>
</tbody>
</table>

### 29.3 EFI DHCP6 Protocol

This section provides a detailed description of the `EFI_DHCP6_PROTOCOL` and the `EFI_DHCP6_SERVICE_BINDING_PROTOCOL`.

#### 29.3.1 DHCP6 Service Binding Protocol

#### 29.3.2 EFI_DHCP6_SERVICE_BINDING_PROTOCOL

**Summary**

The EFI DHCPv6 Service Binding Protocol is used to locate communication devices that are supported by an EFI DHCPv6 Protocol driver and to create and destroy EFI DHCPv6 Protocol child instances that can use the underlying communications device.

**GUID**

```c
#define EFI_DHCP6_SERVICE_BINDING_PROTOCOL _GUID \
  {0x9fb9a8a1,0x2f4a,0x43a6,\} \
  {0x88,0x9c,0xd0,0xf7,0xb6,0xc4,0x7a,0xd5}
```

**Description**

A network application or driver that requires basic DHCPv6 services can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish an EFI DHCPv6 Service Binding Protocol GUID. Each device with a published EFI DHCPv6 Service Binding Protocol GUID supports the EFI DHCPv6 Protocol and may be available for use.

After a successful call to the `EFI_DHCP6_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the newly created EFI DHCPv6 Protocol child instance is ready to be used by a network application or driver.
Before a network application or driver terminates execution, every successful call to the `EFI_DHCP6_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI_DHCP6_SERVICE_BINDING_PROTOCOL.DestroyChild()` function.

### 29.3.3 DHCP6 Protocol

#### 29.3.4 EFI_DHCP6_PROTOCOL

**Summary**

The EFI DHCPv6 Protocol is used to get IPv6 addresses and other configuration parameters from DHCPv6 servers.

**GUID**

```c
#define EFI_DHCP6_PROTOCOL_GUID \
{0x87c8bad7,0x595,0x4053,\ 
 {0x82,0x97,0xde,0xde,0x39,0x5f,0x5d,0x5b}}
```

**Protocol Interface Structure**

```c
typedef struct _EFI_DHCP6_PROTOCOL {
    EFI_DHCP6_GET_MODE_DATA GetModeData;
    EFI_DHCP6_CONFIGURE Configure;
    EFI_DHCP6_START Start;
    EFI_DHCP6_INFO_REQUEST InfoRequest;
    EFI_DHCP6_RENEW_REBIND RenewRebind;
    EFI_DHCP6_DECLINE Decline;
    EFI_DHCP6_RELEASE Release;
    EFI_DHCP6_STOP Stop;
    EFI_DHCP6_PARSE Parse;
} EFI_DHCP6_PROTOCOL;
```

**Parameters**

**GetModeData**

Get the current operating mode data and configuration data for the EFI DHCPv6 Protocol instance. See the `GetModeData()` function description.

**Configure**

Initialize or clean up the configuration data for the EFI DHCPv6 Protocol instance. See the `Configure()` function description.

**Start**

Start the DHCPv6 S.A.R.R process. See the `Start()` function description.

**InfoRequest**

Request configuration parameters without the assignment of any IPv6 addresses to the client. See the `InfoRequest()` function description.

**RenewRebind**

Tries to manually extend the valid and preferred lifetimes for the IPv6 addresses of the configured IA by sending Renew or Rebind packet. See the `RenewRebind()` function description.

**Decline**

Inform that one or more addresses assigned by a DHCPv6 server are already in use by another node. See the `Decline()` function description.
Release
   Release one or more addresses associated with the configured IA. See the Release() function description.

Stop
   Stop the DHCPv6 S.A.R.R process. See the Stop() function description.

Parse
   Parses the option data in the DHCPv6 packet. See the Parse() function description.

Description
The EFI DHCPv6 Protocol is used to get IPv6 addresses and other configuration parameters from DHCPv6 servers.

NOTE: Byte Order: All the IPv6 addresses that are described in EFI_DHCP6_PROTOCOL are stored in network byte order. Both incoming and outgoing DHCPv6 packets are also in network byte order. All other parameters that are defined in functions or data structures are stored in host byte order

29.3.5 EFI_DHCP6_PROTOCOL.GetModeData ()

Summary
Retrieve the current operating mode data and configuration data for the EFI DHCPv6 Protocol instance.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_DHCP6_GET_MODE_DATA)(
   IN EFI_DHCP6_PROTOCOL *This,
   OUT EFI_DHCP6_MODE_DATA *Dhcp6ModeData* OPTIONAL,
   OUT EFI_DHCP6_CONFIG_DATA *Dhcp6ConfigData* OPTIONAL
);

Parameters
This
   Pointer to the EFI_DHCP6_PROTOCOL instance.

Dhcp6ModeData
   Pointer to the DHCPv6 mode data structure. The caller is responsible for freeing this structure and each reference buffer. Type EFI_DHCP6_MODE_DATA is defined in “Related Definitions” below.

Dhcp6ConfigData
   Pointer to the DHCPv6 configuration data structure. The caller is responsible for freeing this structure and each reference buffer. Type EFI_DHCP6_CONFIG_DATA is defined in EFI_DHCP6_PROTOCOL.Configure().

Description
Retrieve the current operating mode data and configuration data for the EFI DHCPv6 Protocol instance.

Related Definitions

```
//**************************************************************************************
// EFI_DHCP6_MODE_DATA
//**************************************************************************************
typedef struct {
   EFI_DHCP6_DUID *ClientId;
   EFI_DHCP6_IA *Ia;
} EFI_DHCP6_MODE_DATA;
```
ClientId

Pointer to the DHCPv6 unique identifier. The caller is responsible for freeing this buffer. Type \texttt{EFI\_DHCP6\_DUID} is defined below.

Ia

Pointer to the configured IA of current instance. The caller can free this buffer after using it. Type \texttt{EFI\_DHCP6\_IA} is defined below.

---

```c
typedef struct {
    UINT16 Length;
    UINT8 Duid[1];
} EFI_DHCP6_DUID;
```

Length

Length of DUID in octets.

Duid

Array of DUID octets.

The \texttt{EFI\_DHCP6\_DUID} structure is to specify DHCPv6 unique identifier for either DHCPv6 client or DHCPv6 server. The DUID-UUID shall be used for all transactions.

```c
typedef struct {
    EFI_DHCP6_IA_DESCRIPTOR Descriptor;
    EFI_DHCP6_STATE State;
    EFI_DHCP6_PACKACT *ReplyPacket;
    UINT32 IaAddressCount;
    EFI_DHCP6_IA_ADDRESS IaAddress[1];
} EFI_DHCP6_IA;
```

Descriptor

The descriptor for IA. Type \texttt{EFI\_DHCP6\_IA\_DESCRIPTOR} is defined below.

State

The state of the configured IA. Type \texttt{EFI\_DHCP6\_STATE} is defined below.

ReplyPacket

Pointer to the cached latest Reply packet. May be \texttt{NULL} if no packet is cached.

IaAddressCount

Number of IPv6 addresses of the configured IA.

IaAddress

List of the IPv6 addresses of the configured IA. When the state of the configured IA is in \texttt{Dhcp6Bound}, \texttt{Dhcp6Renewing} and \texttt{Dhcp6Rebinding}, the IPv6 addresses are usable. Type \texttt{EFI\_DHCP6\_IA\_ADDRESS} is defined below.

```c
typedef struct {
    // (continues on next page)
```
UINT16 Type;
UINT32 IaId;
} EFI_DHCP6_IA_DESCRIPTOR;

**Type**
Type for an IA.

**IaId**
The identifier for an IA.

#define EFI_DHCP6_IA_TYPE_NA 3
#define EFI_DHCP6_IA_TYPE_TA 4

**EFI_DHCP6_IA_TYPE_NA**
An IA which carries assigned not temporary address.

**EFI_DHCP6_IA_TYPE_TA**
An IA which carries assigned temporary address.

```c
typedef enum {
    Dhcp6Init = 0x0,
    Dhcp6Selecting = 0x1,
    Dhcp6Requesting = 0x2,
    Dhcp6Declining = 0x3,
    Dhcp6Confirming = 0x4,
    Dhcp6Releasing = 0x5,
    Dhcp6Bound = 0x6,
    Dhcp6Renewing = 0x7,
    Dhcp6Rebinding = 0x8
} EFI_DHCP6_STATE;
```

The Table below, *Field Descriptions*, describes the fields in the above enumeration.

<table>
<thead>
<tr>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dhcp6Init</td>
<td>The EFI DHCPv6 Protocol instance is configured, and start() needs to be called</td>
</tr>
<tr>
<td>Dhcp6Selecting</td>
<td>A Solicit packet is sent out to discover DHCPv6 server, and the EFI DHCPv6 Protocol instance is collecting Advertise packets.</td>
</tr>
<tr>
<td>Dhcp6Requesting</td>
<td>A Request is sent out to the DHCPv6 server, and the EFI DHCPv6 Protocol instance is waiting for Reply packet.</td>
</tr>
<tr>
<td>Dhcp6Declining</td>
<td>A Decline packet is sent out to indicate one or more addresses of the configured IA are in use by another node, and the EFI DHCPv6 Protocol instance is waiting for Reply packet.</td>
</tr>
<tr>
<td>Dhcp6Confirming</td>
<td>A Confirm packet is sent out to confirm the IPv6 addresses of the configured IA, and the EFI DHCPv6 Protocol instance is waiting for Reply packet.</td>
</tr>
<tr>
<td>Dhcp6Releasing</td>
<td>A Release packet is sent out to release one or more IPv6 addresses of the configured IA, and the EFI DHCPv6 Protocol instance is waiting for Reply packet.</td>
</tr>
<tr>
<td>Dhcp6Bound</td>
<td>The DHCPv6 S.A.R.R process is completed for the configured IA.</td>
</tr>
<tr>
<td>Dhcp6Renewing</td>
<td>A Renew packet is sent out to extend lifetime for the IPv6 addresses of the configured IA, and the EFI DHCPv6 Protocol instance is waiting for Reply packet.</td>
</tr>
</tbody>
</table>

continues on next page
A Rebind packet is sent to extend lifetime for the IPv6 addresses of the configured IA, and the EFI DHCPv6 Protocol instance is waiting for Reply packet.

typedef struct {
    EFI_IPv6_ADDRESS IpAddress;
    UINT32 PreferredLifetime;
    UINT32 ValidLifetime;
} EFI_DHCP6_IA_ADDRESS;

IpAddress
The IPv6 address.

PreferredLifetime
The preferred lifetime in unit of seconds for the IPv6 address.

ValidLifetime
The valid lifetime in unit of seconds for the IPv6 address.

The EFI_DHCP6_IA_ADDRESS structure is specify IPv6 address associated with an IA.

typedef struct {
    UINT32 Size;
    UINT32 Length;
    struct{
        EFI_DHCP6_HEADER Header;
        UINT8 Option[1];
    } Dhcp6;
} EFI_DHCP6_PACKET;

Size
Size of the EFI_DHCP6_PACKET buffer.

Length
Length of the EFI_DHCP6_PACKET from the first byte of the Header field to the last byte of the Option[] field.

Header
The DHCPv6 packet header.

Option
Start of the DHCPv6 packed option data.

EFI_DHCP6_PACKET defines the format of the DHCPv6 packet. See RFC 3315 for more information.
UINT32 TransactionId: 24;
UINT32 MessageType: 8;
} EFI_DHCP6_HEADER;
#pragma pack()

TransactionId
The DHCPv6 transaction ID.

MessageType
The DHCPv6 message type.

EFI_DHCP6_HEADER defines the format of the DHCPv6 header. See RFC 3315 for more information.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The mode data was returned.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The EFI DHCPv6 Protocol instance has not been configured when</td>
</tr>
<tr>
<td></td>
<td>Dhcp6ConfigData is not NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more following conditions are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Both Dhcp6ConfigData and Dhcp6ModeData are NULL.</td>
</tr>
</tbody>
</table>

29.3.6 EFI_DHCP6_PROTOCOL.Configure()

Summary
Initialize or clean up the configuration data for the EFI DHCPv6 Protocol instance.

Prototype
typedef
EFI_STATUS
(EIFIAPI *EFI_DHCP6_CONFIGURE) (  
    IN EFI_DHCP6_PROTOCOL *This,  
    IN EFI_DHCP6_CONFIG_DATA *Dhcp6CfgData OPTIONAL  
);

Parameters

This
Pointer to the EFI_DHCP6_PROTOCOL instance.

Dhcp6CfgData
Pointer to the DHCPv6 configuration data structure. Type EFI_DHCP6_CONFIG_DATA is defined in “Related Definitions” below.

Description
The Configure() function is used to initialize or clean up the configuration data of the EFI DHCPv6 Protocol instance

• When Dhcp6CfgData is not NULL and Configure() is called successfully, the configuration data will be initialized in the EFI DHCPv6 Protocol instance and the state of the configured IA will be transferred into Dhcp6Init.

• When Dhcp6CfgData is NULL and Configure() is called successfully, the configuration data will be cleaned up and no IA will be associated with the EFI DHCPv6 Protocol instance.
To update the configuration data for an EFI DHCPv6 Protocol instance, the original data must be cleaned up before setting the new configuration data.

Related Definitions

```c
typedef struct {
    EFI_DHCP6_CALLBACK Dhcp6Callback;
    VOID *CallbackContext;
    UINT32 OptionCount;
    EFI_DHCP6_PACKET_OPTION **OptionList;
    EFI_DHCP6_IA_DESCRIPTOR IaDescriptor;
    EFI_EVENT IaInfoEvent;
    BOOLEAN ReconfigureAccept;
    BOOLEAN RapidCommit;
    EFI_DHCP6_RETRANSMISSION *SolicitRetransmission;
} EFI_DHCP6_CONFIG_DATA;
```

Dhcp6Callback
The callback function is to intercept various events that occur in the DHCPv6 S.A.R.R process. Set to NULL to ignore all those events. Type `EFI_DHCP6_CALLBACK` is defined below.

CallbackContext
Pointer to the context that will be passed to `Dhcp6Callback`.

OptionCount
Number of the DHCPv6 options in the `OptionList`.

OptionList
The buffer can be freed after `EFI_DHCP6_PROTOCOL.Configure()` returns. Ignored if `OptionCount` is zero. `OptionList` should not contain Client Identifier option and any IA option, which will be appended by EFI DHCPv6 Protocol instance automatically. Type `EFI_DHCP6_PACKET_OPTION` is defined below.

IaDescriptor
The descriptor for the IA of the EFI DHCPv6 Protocol instance. Type `EFI_DHCP6_IA_DESCRIPTOR` is defined below.

IaInfoEvent
If not `NULL`, the event will be signaled when any IPv6 address information of the configured IA is updated, including IPv6 address, preferred lifetime and valid lifetime, or the DHCPv6 S.A.R.R process fails. Otherwise, `Start()`, `renewrebind()`, `decline()`, `release()` and `stop()` will be blocking operations, and they will wait for the exchange process completion or failure.

ReconfigureAccept
If `TRUE`, the EFI DHCPv6 Protocol instance is willing to accept Reconfigure packet. Otherwise, it will ignore it. Reconfigure Accept option can not be specified through `OptionList` parameter.

RapidCommit
If `TRUE`, the EFI DHCPv6 Protocol instance will send Solicit packet with Rapid Commit option. Otherwise, Rapid Commit option will not be included in Solicit packet. Rapid Commit option can not be specified through `OptionList` parameter.

SolicitRetransmission
Parameter to control Solicit packet retransmission behavior. Type `EFI_DHCP6_RETRANSMISSION` is defined in “Related Definition” below. The buffer can be freed after `EFI_DHCP6_PROTOCOL.Configure()` returns.
typedef EFI_STATUS (EFIAPI *EFI_DHCP6_CALLBACK)(
    IN EFI_DHCP6_PROTOCOL *This,
    IN VOID *Context,
    IN EFI_DHCP6_STATE CurrentState,
    IN EFI_DHCP6_EVENT Dhcp6Event,
    IN EFI_DHCP6_PACKET *Packet,
    OUT EFI_DHCP6_PACKET **NewPacket OPTIONAL
);

This
Pointer to the EFI_DHCP6_PROTOCOL instance that is used to configure this callback function.

Context
Pointer to the context that is initialized by EFI_DHCP6_PROTOCOL.Configure().

CurrentState
The current state of the configured IA. Type EFI_DHCP6_STATE is defined in EFI_DHCP6_PROTOCOL.GetModeData().

Dhcp6Event
The event that occurs in the current state, which usually means a state transition. Type EFI_DHCP6_EVENT is defined below.

Packet
Pointer to the DHCPv6 packet that is about to be sent or has been received. The EFI DHCPv6 Protocol instance is responsible for freeing the buffer. Type EFI_DHCP6_PACKET is defined in EFI_DHCP6_PROTOCOL.GetModeData().

NewPacket
Pointer to the new DHCPv6 packet to overwrite the Packet. NewPacket can not share the buffer with Packet. If *NewPacket is not NULL, the EFI DHCPv6 Protocol instance is responsible for freeing the buffer.

EFI_DHCP6_CALLBACK is provided by the consumer of the EFI DHCPv6 Protocol instance to intercept events that occurs in the DHCPv6 S.A.R.R process. There are two possible returned values, which are described in the following table.

Table 29.21: Callback Return Values

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Tell the EFI DHCPv6 Protocol instance to continue the DHCPv6 S.A.R.R process.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>Tell the EFI DHCPv6 Protocol instance to abort the DHCPv6 S.A.R.R process, and the state of the configured IA will be transferred to Dhcp6Init.</td>
</tr>
</tbody>
</table>

#pragma pack(1)
typedef struct {
    UINT16 OpCode;
    UINT16 OpLen;
    UINT8 Data[1];
} EFI_DHCP6_PACKET_OPTION;
#pragma pack()
OpCode
The DHCPv6 option code, stored in network order.

OpLen
Length of the DHCPv6 option data, stored in network order. From the first byte to the last byte of the Data field.

Data
The data for the DHCPv6 option.

EFI_DHCP6_PACKET_OPTION defines the format of the DHCPv6 option, stored in network order. See RFC 3315 for more information. This data structure is used to reference option data that is packed in the DHCPv6 packet.

```c
typedef enum {
  Dhcp6SendSolicit = 0x0,
  Dhcp6RcvdAdvertise = 0x1,
  Dhcp6SelectAdvertise = 0x2,
  Dhcp6SendRequest = 0x3,
  Dhcp6RcvdReply = 0x4,
  Dhcp6RcvdReconfigure = 0x5,
  Dhcp6SendDecline = 0x6,
  Dhcp6SendConfirm = 0x7,
  Dhcp6SendRelease = 0x8,
  Dhcp6SendRenew = 0x9,
  Dhcp6SendRebind = 0xa
} EFI_DHCP6_EVENT;
```

Dhcp6SendSolicit
A Solicit packet is about to be sent. The packet is passed to Dhcp6Callback and can be modified or replaced in Dhcp6Callback.

Dhcp6RcvdAdvertise
An Advertise packet is received and will be passed to Dhcp6Callback.

Dhcp6SelectAdvertise
It is time for Dhcp6Callback to determine whether select the default Advertise packet by RFC 3315 policy, or overwrite it by specific user policy.

Dhcp6SendRequest
A Request packet is about to be sent. The packet is passed to Dhcp6Callback and can be modified or replaced in Dhcp6Callback.

Dhcp6RcvdReply
A Reply packet is received and will be passed to Dhcp6Callback.

Dhcp6RcvdReconfigure
A Reconfigure packet is received and will be passed to Dhcp6Callback.

Dhcp6SendDecline
A Decline packet is about to be sent. The packet is passed to Dhcp6Callback and can be modified or replaced in Dhcp6Callback.

Dhcp6SendConfirm
A Confirm packet is about to be sent. The packet is passed to Dhcp6Callback and can be modified or replaced in Dhcp6Callback.

Dhcp6SendRelease
A Release packet is about to be sent. The packet is passed to Dhcp6Callback and can be modified or replaced in Dhcp6Callback.
**Dhcp6Callback**.

**Dhcp6SendRenew**

A Renew packet is about to be sent. The packet is passed to *Dhcp6Callback* and can be modified or replaced in *Dhcp6Callback*.

**Dhcp6SendRebind**

A Rebind packet is about to be sent. The packet is passed to *Dhcp6Callback* and can be modified or replaced in *Dhcp6Callback*.

```c
typedef struct {
    UINT32 Irt;
    UINT32 Mrc;
    UINT32 Mrt;
    UINT32 Mrd;
} EFI_DHCP6_RETRANSMISSION;
```

**Irt**

Initial retransmission timeout.

**Mrc**

Maximum retransmission count for one packet. If *Mrc* is zero, there’s no upper limit for retransmission count.

**Mrt**

Maximum retransmission timeout for each retry. It’s the upper bound of the number of retransmission timeout. If *Mrt* is zero, there is no upper limit for retransmission timeout.

**Mrd**

Maximum retransmission duration for one packet. It’s the upper bound of the numbers the client may retransmit a message. If *Mrd* is zero, there’s no upper limit for retransmission duration.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The mode data was returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more following conditions are <strong>TRUE</strong></td>
</tr>
<tr>
<td></td>
<td>• This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <em>OptionCount &gt; 0</em> and <em>OptionList</em> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <em>OptionList</em> is not <strong>NULL</strong>, and Client Id option, Reconfigure Accept option, Rapid Commit option or any IA option is specified in the <em>OptionList</em>.</td>
</tr>
<tr>
<td></td>
<td>• <em>IaDescriptor. Type</em> is neither Efi_DHCP6_IA_TYPE_NA nor Efi_DHCP6_IA_TYPE_NA.</td>
</tr>
<tr>
<td></td>
<td>• <em>IaDescriptor</em> is not unique.</td>
</tr>
<tr>
<td></td>
<td>• Both <em>IaInfoEvent</em> and <em>SolicitRetransmission</em> are <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <em>SolicitRetransmission</em> is not <strong>NULL</strong>, and both <em>SolicitRetransmission-&gt;Mrc</em> and <em>SolicitRetransmission-&gt;Mrd</em> are zero.</td>
</tr>
</tbody>
</table>

continues on next page
The EFI DHCPv6 Protocol instance has been already configured when `Dhcp6CfgData` is not `NULL`.
The EFI DHCPv6 Protocol instance has already started the DHCPv6 S.A.R.R when `Dhcp6CfgData` is `NULL`.

**Table 29.22 – continued from previous page**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The EFI DHCPv6 Protocol instance has been already configured when <code>Dhcp6CfgData</code> is not <code>NULL</code>. The EFI DHCPv6 Protocol instance has already started the DHCPv6 S.A.R.R when <code>Dhcp6CfgData</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFIDEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
</tbody>
</table>

### 29.3.7 EFI_DHCP6_PROTOCOL.Start()

**Summary**

Start the DHCPv6 S.A.R.R process.

**Prototype**

```c
typedef
EFI_STATUS
(EFI_API *EFI_DHCP6_START) (    
    IN EFI_DHCP6_PROTOCOL  *This
);
```

**Parameters**

This

Pointer to the `EFI_DHCP6_PROTOCOL` instance.

**Description**

The `Start()` function starts the DHCPv6 S.A.R.R process. This function can be called only when the state of the configured IA is in the `Dhcp6Init` state. If the DHCPv6 S.A.R.R process completes successfully, the state of the configured IA will be transferred through `Dhcp6Selecting` and `Dhcp6Requesting` to `Dhcp6Bound` state. The update of the IPv6 addresses will be notified through `EFI_DHCP6_CONFIG_DATA.IaInfoEvent`. At the time when each event occurs in this process, the callback function set by `EFI_DHCP6_PROTOCOL.Configure()` will be called and the user can take this opportunity to control the process. If `EFI_DHCP6_CONFIG_DATA.IaInfoEvent` is `NULL`, the `Start()` function call is a blocking operation. It will return after the DHCPv6 S.A.R.R process completes or aborted by users. If the process is aborted by system or network error, the state of the configured IA will be transferred to `Dhcp6Init`. The `Start()` function can be called again to restart the process.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The DHCPv6 S.A.R.R process is completed and at least one IPv6 address has been bound to the configured IA when <code>EFI_DHCP6_CONFIG_DATA.IaInfoEvent</code> is <code>NULL</code>. The DHCPv6 S.A.R.R process is started when <code>EFI_DHCP6_CONFIG_DATA.IaInfoEvent</code> is not <code>NULL</code>.</td>
</tr>
<tr>
<td>EFIACCESS_DENIED</td>
<td>The EFI DHCPv6 Child instance hasn’t been configured.</td>
</tr>
<tr>
<td>EFINVALID_PARAMETER</td>
<td>This is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The DHCPv6 S.A.R.R process has already started.</td>
</tr>
<tr>
<td>EFIDEVICE_ERROR</td>
<td>An unexpected network or system error occurred.</td>
</tr>
<tr>
<td>EIFI_NO_RESPONSE</td>
<td>The DHCPv6 S.A.R.R process failed because of no response.</td>
</tr>
</tbody>
</table>

continues on next page
Table 29.23 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_NO_MAPPING</td>
<td>No IPv6 address has been bound to the configured IA after the DHCPv6 S.A.R.R process.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>The DHCPv6 S.A.R.R process aborted by user.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

29.3.8 EFI_DHCP6_PROTOCOL.InfoRequest()

Summary

Request configuration information without the assignment of any IA addresses of the client.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_DHCP6_INFO_REQUEST) (  
    IN EFI_DHCP6_PROTOCOL *This,  
    IN BOOLEAN SendClientId,  
    IN EFI_DHCP6_PACKET_OPTION *OptionRequest,  
    IN UINT32 OptionCount,  
    IN EFI_DHCP6_PACKET_OPTION *OptionList[], OPTIONAL,  
    IN EFI_DHCP6_RETRANSMISSION *Retransmission,  
    IN EFI_EVENT TimeoutEvent OPTIONAL,  
    IN EFI_DHCP6_INFO_CALLBACK ReplyCallback,  
    IN VOID *CallbackContext OPTIONAL
);  
```

Parameters

This

Pointer to the EFI_DHCP6_PROTOCOL instance.

SendClientId

If TRUE, the EFI DHCPv6 Protocol instance will build Client Identifier option and include it into Information Request packet. If FALSE, Client Identifier option will not be included. Client Identifier option can not be specified through OptionList parameter.

OptionRequest

Pointer to the Option Request option in the Information Request packet. Option Request option can not be specified through OptionList parameter.

OptionCount

Number of options in OptionList.

OptionList

List of other DHCPv6 options. These options will be appended to the Option Request option. The caller is responsible for freeing this buffer. Type is defined in EFI_DHCP6_PROTOCOL.GetModeData().

Retransmission

Parameter to control Information Request packet retransmission behavior. Type EFI_DHCP6_RETRANSMISSION is defined in “Related Definition” below. The buffer can be freed after EFI_DHCP6_PROTOCOL.InfoRequest() returns.

TimeoutEvent

If not NULL, this event is signaled when the information request exchange aborted because of no response. If NULL, the function call is a blocking operation; and it will return after the information-request exchange process finish or aborted by users.
ReplyCallback
The callback function is to intercept various events that occur in the Information Request exchange process. It should not be set to NULL. Type EFI_DHCP6_INFO_CALLBACK is defined below.

CallbackContext
Pointer to the context that will be passed to ReplyCallback.

Description
The InfoRequest() function is used to request configuration information without the assignment of any IPv6 address of the client. Client sends out Information Request packet to obtain the required configuration information, and DHCPv6 server responds with Reply packet containing the information for the client. The received Reply packet will be passed to the user by ReplyCallback function. If user returns EFI_NOT_READY from ReplyCallback, the EFI DHCPv6 Protocol instance will continue to receive other Reply packets unless timeout according to the Retransmission parameter. Otherwise, the Information Request exchange process will be finished successfully if user returns EFI_SUCCESS from ReplyCallback.

Related Definitions

```
//EFI_DHCP6_CALLBACK
typedef EFI_STATUS (EFIAPI *EFI_DHCP6_INFO_CALLBACK)(
    IN EFI_DHCP6_PROTOCOL *This,
    IN VOID *Context,
    IN EFI_DHCP6_PACKET *Packet,
   );
```

This
Pointer to the EFI_DHCP6_PROTOCOL instance that is used to configure this callback function.

Context
Pointer to the context that is initialized in the EFI_DHCP6_PROTOCOL.InfoRequest().

Packet
Pointer to Reply packet that has been received. The EFI DHCPv6 Protocol instance is responsible for freeing the buffer. Type EFI_DHCP6_PACKET is defined in EFI_DHCP6_PROTOCOL.GetModeData().

EFI_DHCP6_INFO_CALLBACK is provided by the consumer of the EFI DHCPv6 Protocol instance to intercept events that occurs in the DHCPv6 Information Request exchange process. There are three possible returned values, which are described in the following table.

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Tell the EFI DHCPv6 Protocol instance to finish Information Request exchange process.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>Tell the EFI DHCPv6 Protocol instance to continue Information Request exchange process.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>Tell the EFI DHCPv6 Protocol instance to abort the Information Request exchange process</td>
</tr>
</tbody>
</table>

Status Codes Returned

```
EFI_SUCCESS
The DHCPv6 information request exchange process completed when TimeoutEvent is NULL. Information Request packet has been sent to DHCPv6 server when TimeoutEvent is not NULL.
```
One or more following conditions are TRUE:
- This is NULL.
- OptionRequest is NULL or OptionRequest->OpCode is invalid.
- OptionCount > 0 and OptionList is NULL.
- OptionList is not NULL, and Client Identify option or Option Request option is specified in the OptionList.
- Retransmission is NULL.
- Both Retransmission->Mrc and Retransmission->Mrd are zero.
- ReplyCallback is NULL.

An unexpected network or system error occurred.

The DHCPv6 information request exchange process failed because of no response, or not all requested-options are responded by DHCPv6 servers when Timeout happened.

The DHCPv6 information request exchange process aborted by user.

### 29.3.9 EFI_DHCP6_PROTOCOL.RenewRebind ()

**Summary**

Manually extend the valid and preferred lifetimes for the IPv6 addresses of the configured IA and update other configuration parameters by sending Renew or Rebind packet.

**Prototype**

```c
typedef
EFI_STATUS
(EFIAPI *EFI_DHCP6_RENEW_REBIND) (
    IN EFI_DHCP6_PROTOCOL *This,
    IN BOOLEAN RebindRequest
);
```

**Parameters**

This

Pointer to the EFI_DHCP6_PROTOCOL instance.

RebindRequest

If TRUE, it will send Rebind packet and enter the Dhcp6Rebinding state. Otherwise, it will send Renew packet and enter the Dhcp6Renewing state.

**Description**

The RenewRebind () function is used to manually extend the valid and preferred lifetimes for the IPv6 addresses of the configured IA and update other configuration parameters by sending Renew or Rebind packet.

- When RebindRequest is FALSE and the state of the configured IA is Dhcp6Bound, it will send Renew packet to the previously DHCPv6 server and transfer the state of the configured IA to Dhcp6Renewing. If valid Reply packet received, the state transfers to Dhcp6Bound and the valid and preferred timer restarts. If fails, the state transfers to Dhcp6Bound but the timer continues.

- When RebindRequest is TRUE and the state of the configured IA is Dhcp6Bound, it will send Rebind packet. If valid Reply packet received, the state transfers to Dhcp6Bound and the valid and preferred timer restarts. If fails, the state transfers to Dhcp6Init and the IA can’t be used.

---

29.3. EFI DHCP6 Protocol 1350
## Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The DHCPv6 renew/rebind exchange process has completed and at least one IPv6 address of the configured IA has been bound again when EFI_DHCP6_CONFIG_DATA.IaInfoEvent is NULL. The EFI DHCPv6 Protocol instance has sent Renew or Rebind packet when EFI_DHCP6_CONFIG_DATA.IaInfoEvent is not NULL.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The EFI DHCPv6 Child instance hasn’t been configured, or the state of the configured IA is not in Dhcp6Bound.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The state of the configured IA has already entered Dhcp6Renewing when RebindRequest is FALSE. The state of the configured IA has already entered Dhcp6Rebinding when RebindRequest is TRUE.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network or system error occurred.</td>
</tr>
<tr>
<td>EFI_NO_RESPONSE</td>
<td>The DHCPv6 renew/rebind exchange process failed because of no response.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>No IPv6 address has been bound to the configured IA after the DHCPv6 renew/rebind exchange process.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>The DHCPv6 renew/rebind exchange process aborted by user.</td>
</tr>
</tbody>
</table>

### 29.3.10 EFI_DHCP6_PROTOCOL.Decline()

**Summary**
Inform that one or more IPv6 addresses assigned by a server are already in use by another node.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_DHCP6_DECLINE) (  
  IN EFI_DHCP6_PROTOCOL *This,  
  IN UINT32 AddressCount,  
  IN EFI_IPv6_ADDRESS *Addresses
);
```

**Parameters**

- **This**
  Pointer to the EFI_DHCP6_PROTOCOL instance.

- **AddressCount**
  Number of declining IPv6 addresses.

- **Addresses**
  Pointer to the buffer stored all the declining IPv6 addresses.

**Description**

The Decline() function is used to manually decline the assignment of IPv6 addresses, which have been already used by another node. If all IPv6 addresses of the configured IA are declined through this function, the state of
the IA will switch through Dhcp6Declining to Dhcp6Init, otherwise, the state of the IA will restore to Dhcp6Bound after the declining process. The Decline () can only be called when the IA is in Dhcp6Bound state. If the EFI_DHCP6_CONFIG_DATA.IaInfoEvent is NULL, this function is a blocking operation. It will return after the declining process finishes, or aborted by user.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The DHCPv6 decline exchange process has completed when EFI_DHCP6_CONFIG_DATA.IaInfoEvent is NULL. The EFI DHCPv6 Protocol instance has sent Decline packet when EFI_DHCP6_CONFIG_DATA.IaInfoEvent is not NULL.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER     | One or more following conditions are TRUE  
• This is NULL.  
• AddressCount is zero or Addresses is NULL. |
| EFI_NOT_FOUND             | Any specified IPv6 address is not correlated with the configured IA for this instance. |
| EFI_ACCESS_DENIED         | The EFI DHCPv6 Child instance hasn’t been configured, or the state of the configured IA is not in Dhcp6Bound. |
| EFI_DEVICE_ERROR          | An unexpected network or system error occurred.                             |
| EFI_ABORTED               | The DHCPv6 decline exchange process aborted by user.                        |

### 29.3.11 EFI_DHCP6_PROTOCOL.Release ()

**Summary**

Release one or more IPv6 addresses associated with the configured IA for current instance.

**Prototype**

```c
typedef EFI_STATUS
(EIFIAPI *EFI_DHCP6_RELEASE) (  
  IN EFI_DHCP6_PROTOCOL *This,  
  IN UINT32 AddressCount,  
  IN EFI_IPv6_ADDRESS *Addresses)
```

**Parameters**

**This**

Pointer to the EFI_DHCP6_PROTOCOL instance.

**AddressCount**

Number of releasing IPv6 addresses.

**Addresses**

Pointer to the buffer stored all the releasing IPv6 addresses. Ignored if AddressCount is zero.

**Description**

The Release () function is used to manually release the one or more IPv6 address. If AddressCount is zero, it will release all IPv6 addresses of the configured IA. If all IPv6 addresses of the IA are released through this function, the state of the IA will switch through Dhcp6Releasing to Dhcp6Init, otherwise, the state of the IA will restore to Dhcp6Bound after the releasing process. The Release () can only be called when the IA is in Dhcp6Bound state. If
the `EFI_DHCP6_CONFIG_DATA.IaInfoEvent` is NULL, the function is a blocking operation. It will return after the releasing process finishes, or aborted by user.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The DHCPv6 release exchange process has completed when <code>EFI_DHCP6_CONFIG_DATA.IaInfoEvent</code> is NULL. The EFI DHCPv6 Protocol instance has sent Release packet when <code>EFI_DHCP6_CONFIG_DATA.IaInfoEvent</code> is not NULL.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more following conditions are TRUE  
  • This is NULL.  
  • AddressCount is not zero and Addresses is NULL. |
| EFI_NOT_FOUND       | Any specified IPv6 address is not correlated with the configured IA for this instance. |
| EFI_ACCESS_DENIED   | The EFI DHCPv6 Child instance hasn’t been configured, or the state of the configured IA is not in Dhcp6Bound. |
| EFI_DEVICE_ERROR    | An unexpected network or system error occurred. |
| EFI_ABORTED         | The DHCPv6 release exchange process aborted by user. |

#### 29.3.12 EFI_DHCP6_PROTOCOL.Stop ()

**Summary**

Stop the DHCPv6 S.A.R.R process.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_DHCP6_STOP) (  
    IN EFI_DHCP6_PROTOCOL *This  
);  
```

**Parameters**

**This**

Pointer to the `EFI_DHCP6_PROTOCOL` instance.

**Description**

The `Stop ()` function is used to stop the DHCPv6 S.A.R.R process. If this function is called successfully, all the IPv6 addresses of the configured IA will be released and the state of the configured IA will be transferred to Dhcp6Init.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The DHCPv6 S.A.R.R process has been stopped when <code>EFI_DHCP6_CONFIG_DATA.IaInfoEvent</code> is NULL. The EFI DHCPv6 Protocol instance has sent Release packet if need release or has been stopped if needn’t, when <code>EFI_DHCP6_CONFIG_DATA.IaInfoEvent</code> is not NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

---

29.3. EFI DHCP6 Protocol
29.3.13 EFI_DHCP6_PROTOCOL.Parse()

Summary
Parse the option data in the DHCPv6 packet.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_DHCP6_PARSE) (
    IN EFI_DHCP6_PROTOCOL *This,
    IN EFI_DHCP6_PACKET *Packet,
    IN OUT UINT32 *OptionCount,
    IN EFI_DHCP6_PACKET_OPTION *PacketOptionList[] OPTIONAL
);
```

Parameters

- **This**: Pointer to the EFI_DHCP6_PROTOCOL instance.
- **Packet**: Pointer to packet to be parsed. Type EFI_DHCP6_PACKET is defined in EFI_DHCP6_PROTOCOL.GetModeData().
- **OptionCount**: On input, the number of entries in the PacketOptionList. On output, the number of DHCPv6 options in the Packet.
- **PacketOptionList**: List of pointers to the DHCPv6 options in the Packet. Type EFI_DHCP6_PACKET_OPTION is defined in EFI_DHCP6_PROTOCOL.Configuration(). The OpCode and OpLen in EFI_DHCP6_PACKET_OPTION are both stored in network byte order.

Description
The Parse() function is used to retrieve the option list in the DHCPv6 packet.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The packet was successfully parsed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more following conditions are TRUE</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Packet is NULL.</td>
</tr>
<tr>
<td></td>
<td>• Packet is not a well-formed DHCPv6 packet.</td>
</tr>
<tr>
<td></td>
<td>• OptionCount is NULL.</td>
</tr>
<tr>
<td></td>
<td>• * OptionCount is not zero and PacketOptionList is NULL.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>* OptionCount is smaller than the number of options that were found in the Packet.</td>
</tr>
</tbody>
</table>
29.4 EFI DNSv4 Protocol

This section defines the EFI Domain Name Service Binding Protocol interface. It is split into the following two main sections.

- DNSv4 Service Binding Protocol (DNSv4SB)
- DNSv4 Protocol (DNSv4)

29.4.1 EFI_DNS4_SERVICE_BINDING_PROTOCOL

Summary

The DNSv4SB is used to locate communication devices that are supported by a DNS driver and to create and destroy instances of the DNS child protocol driver.

The EFI Service Binding Protocol in *EFI Services Binding* defines the generic Service Binding Protocol functions. This section discusses the details that are specific to the DNSv4.

GUID

```
#define EFI_DNS4_SERVICE_BINDING_PROTOCOL_GUID
{ 0xb625b186, 0xe063, 0x44f7,
   { 0x89, 0x5, 0x6a, 0x74, 0xdc, 0x6f, 0x52, 0xb4}}
```

Description

A network application (or driver) that requires network address resolution can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish a DNSv4SB GUID. Each device with a published DNSv4SB GUID supports DNS and may be available for use.

After a successful call to the `EFI_DNS4_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the child DNS driver instance is in an unconfigured state; it is not ready to resolve addresses.

Before a network application terminates execution, every successful call to the `EFI_DNS4_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI_DNS4_SERVICE_BINDING_PROTOCOL.DestroyChild()` function.

NOTE: All the network addresses that are described in EFI_DNS4_PROTOCOL are stored in network byte order. Both incoming and outgoing DNS packets are also in network byte order. All other parameters that are defined in functions or data structures are stored in host byte order.

29.4.2 EFI_DNS4_PROTOCOL

Summary

This protocol provides the function to get the host name and address mapping, also provides pass through interface to retrieve arbitrary information from DNS.

The EFI_DNS4 Protocol is primarily intended to retrieve host addresses using the standard DNS protocol (RFC1035), and support for this protocol is required. Implementations may optionally also support local network name resolution methods such as LLMNR (RFC4795); however DNS queries shall always take precedence, and any use of local network name protocols would be restricted to cases where resolution using DNS protocol fails.
As stated above, all instances of EFI_DNS4_Proto will utilize a common DNS cache containing the successful results of previous queries on any interface. However, it should be noted that every instance of EFI_DNS4_Proto is associated with a specific network device or interface, and that all network actions initiated using a specific instance of the DNS protocol will occur only via use of the associated network interface. This means, in a system with multiple network interfaces, that a specific DNS server will often only be reachable using a specific network instance, and therefore the protocol user will need to take steps to insure the DNS instance associated with the proper network interface is used. Or alternatively, the caller may perform DNS functions against all interfaces until successful result is achieved.

GUID

```c
#define EFI_DNS4_PROTOCOL_GUID \ 
{ 0xae3d28cc, 0xe05b, 0x4fa1,\ 
{0xa0, 0x11, 0x7e, 0xb5, 0x5a, 0x3f, 0x14, 0x1 }}
```

Protocol Interface Structure

```c
typedef struct _EFI_DNS4_PROTOCOL {
    EFI_DNS4_GET_MODE_DATA GetModeData;
    EFI_DNS4_CONFIGURE Configure;
    EFI_DNS4_HOST_NAME_TO_IP HostNameToIp;
    EFI_DNS4_IP_TO_HOST_NAME IpToHostName;
    EFI_DNS4_GENERAL_LOOKUP GeneralLookUp;
    EFI_DNS4_UPDATE_DNS_CACHE UpdateDnsCache;
    EFI_DNS4_POLL Poll;
    EFI_DNS4_CANCEL Cancel;
} EFI_DNS4_PROTOCOL;
```

29.4.3 EFI_DNS4_PROTOCOL.GetModeData()

Summary

Retrieve the current mode data of this DNS instance.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_DNS4_GET_MODE_DATA)(
    IN EFI_DNS4_PROTOCOL *This,
    OUT EFI_DNS4_MODE_DATA *DnsModeData
);
```

Description

This function is used to retrieve DNS mode data for this DNS instance.

Parameter

This

Pointer to EFI_DNS4_PROTOCOL instance.

DnsModeData

Pointer to the caller-allocated storage for the EFI_DNS4_MODE_DATA structure.

Related Definitions

29.4. EFI DNSv4 Protocol
typedef struct {
    EFI_DNS4_CONFIG_DATA DnsConfigData;
    UINT32 DnsServerCount;
    EFI_IPv4_ADDRESS *DnsServerList;
    UINT32 DnsCacheCount;
    EFI_DNS4_CACHE_ENTRY *DnsCacheList;
} EFI_DNS4_MODE_DATA;

DnsConfigData
The current configuration data of this instance. Type EFI_DNS4_CONFIG_DATA is defined below.

DnsServerCount
Number of configured DNS servers.

DnsServerList
Pointer to common list of addresses of all configured DNS server used by EFI_DNS4_PROTOCOL instances. List will include DNS servers configured by this or any other EFI_DNS4_PROTOCOL instance. The storage for this list is allocated by the driver publishing this protocol, and must be freed by the caller.

DnsCacheCount
Number of DNS Cache entries. The DNS Cache is shared among all DNS instances.

DnsCacheList
Pointer to a buffer containing DnsCacheCount DNS Cache entry structures. The storage for this list is allocated by the driver publishing this protocol and must be freed by caller.

typedef struct {
    UINTN DnsServerListCount;
    EFI_IPv4_ADDRESS *DnsServerList;
    BOOLEAN UseDefaultSetting;
    BOOLEAN EnableDnsCache;
    UINT8 Protocol;
    EFI_IPv4_ADDRESS StationIp;
    EFI_IPv4_ADDRESS SubnetMask;
    UINT16 LocalPort;
    UINT32 RetryCount;
    UINT32 RetryInterval;
} EFI_DNS4_CONFIG_DATA;

DnsServerListCount
Count of the DNS servers. When used with GetModeData(), this field is the count of originally configured servers when Configure() was called for this instance. When used with Configure() this is the count of caller-supplied servers. If the DnsServerListCount is zero, the DNS server configuration will be retrieved from DHCP server automatically.

DnsServerList
Pointer to DNS server list containing DnsServerListCount entries or NULL if DnsServerListCount is 0. For Configure(), this will be NULL when there are no caller-supplied server addresses, and, the DNS instance will retrieve DNS server from DHCP Server. The provided DNS server list is recommended to be filled up in the sequence of preference. When used with GetModeData(), the buffer containing the list will be allocated by
the driver implementing this protocol and must be freed by the caller. When used with `Configure()`, the buffer containing the list will be allocated and released by the caller.

**UseDefaultSetting**

Set to `TRUE` to use the default IP address/subnet mask and default routing table. `<http://www.iana.org/assignments/protocol-numbers>`

**EnableDnsCache**

If `TRUE`, enable DNS cache function for this DNS instance. If `FALSE`, all DNS query will not lookup local DNS cache.

**Protocol**

Use the protocol number defined in “Links to UEFI-Related Documents” (<http://uefi.org/uefi>) under the heading “IANA Protocol Numbers”. Only TCP or UDP are supported, and other protocol values are invalid. An implementation can choose to support only UDP, or both TCP and UDP.

**StationIp**

If `UseDefaultSetting` is `FALSE` indicates the station address to use.

**SubnetMask**

If `UseDefaultSetting` is `FALSE` indicates the subnet mask to use.

**LocalPort**

Local port number. Set to zero to use the automatically assigned port number.

**RetryCount**

Retry number if no response received after `RetryInterval`.

**RetryInterval**

Minimum interval of retry is 2 second. If the retry interval is less than 2 second, then use the 2 second.

```c
typedef struct {
    CHAR16 *HostName;
    EFI_IPv4_ADDRESS *IpAddress;
    UINT32 Timeout;
} EFI_DNS4_CACHE_ENTRY;
```

**HostName**

Host name.

**IpAddress**

IP address of this host.

**Timeout**

Time in second unit that this entry will remain in DNS cache. A value of zero means that this entry is permanent. A nonzero value will override the existing one if this entry to be added is dynamic entry. Implementations may set its default timeout value for the dynamically created DNS cache entry after one DNS resolve succeeds.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>When <code>DnsConfigData</code> is queried, no configuration data is available because this instance has not been configured.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><em>This is NULL or <code>DnsModeData</code> is NULL.</em></td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Failed to allocate needed resources.</td>
</tr>
</tbody>
</table>
29.4.4 EFI_DNS4_PROTOCOL.Configure()

Summary

Configures this DNS instance.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_DNS4_CONFIGURE)(
    IN EFI_DNS4_PROTOCOL *This,
    IN EFI_DNS4_CONFIG_DATA *DnsConfigData
);  

Description

This function is used to configure DNS mode data for this DNS instance.

Parameters

This

Pointer to EFI_DNS4_PROTOCOL instance.

DnsConfigData

Pointer to caller-allocated buffer containing EFI_DNS4_CONFIG_DATA structure containing the desired Configuration data. If NULL, the driver will reinitialize the protocol instance to the unconfigured state.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The designated protocol is not supported.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL. The StationIp address provided in DnsConfigData is not a valid unicast. DnsServerList is NULL while DnsServerListCount is not ZERO. DnsServerListCount is ZERO while DnsServerList is not NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The DNS instance data or required space could not be allocated.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The EFI DNSv4 Protocol instance is not configured.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>Second call to Configure() with DnsConfigData. To reconfigure the instance the caller must call Configure() with NULL first to return driver to unconfigured state.</td>
</tr>
</tbody>
</table>

29.4.5 EFI_DNS4_PROTOCOL.HostNameToIp()

Summary

Host name to host address translation.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_DNS4_HOST_NAME_TO_IP) (  
(continues on next page)
Parameter

This

Pointer to EFI_DNS4_PROTOCOL instance.

Hostname

Pointer to buffer containing fully-qualified Domain Name including Hostname. To resolve successfully, characters within the FQDN string must be chosen according to the format and from within the set of ASCII characters authorized by DNS specifications. Any translation required for reference to domains or hostnames defined as containing Unicode characters, for example use of Punycode, must be performed by caller.

Token

Pointer to the caller-allocated completion token to return at the completion of the process to translate host name to host address. Type EFI_DNS4_COMPLETION_TOKEN is defined in “Related Definitions” below.

Related Definitions

```c
typedef struct {
  EFI_EVENT Event;
  EFI_STATUS Status;
  UINT32 RetryCount;
  UINT32 RetryInterval;
  union {
    DNS_HOST_TO_ADDR_DATA *H2AData;
    DNS_ADDR_TO_HOST_DATA *A2HData;
    DNS_GENERAL_LOOKUP_DATA *GLookupData;
  } RspData;
} EFI_DNS4_COMPLETION_TOKEN;
```

Event

This Event will be signaled after the Status field is updated by the EFI DNS protocol driver. The type of Event must be EFI_NOTIFY_SIGNAL.

Status

Will be set to one of the following values.

- **EFI_SUCCESS**: The host name to address translation completed successfully.
- **EFI_NOT_FOUND**: No matching Resource Record (RR) is found.
- **EFI_TIMEOUT**: No DNS server reachable, or RetryCount was exhausted without response from all specified DNS servers.
- **EFI_DEVICE_ERROR**: An unexpected system or network error occurred.
- **EFI_NO_MEDIA**: There was a media error.

RetryCount

Retry number if no response received after RetryInterval. If zero, use the parameter configured through
Dns.Configure() interface.

**RetryInterval**
Minimum interval of retry is 2 second. If the retry interval is less than 2 second, then use the 2 second. If zero, use the parameter configured through Dns.Configure() interface.

**H2AData**
When the Token is used for host name to address translation, H2AData is a pointer to the DNS_HOST_TO_ADDR_DATA. Type DNS_HOST_TO_ADDR_DATA is defined below.

**A2HData**
When the Token is used for host address to host name translation, A2HData is a pointer to the DNS_ADDR_TO_HOST_DATA. Type DNS_ADDR_TO_HOST_DATA is defined below.

**GLookupDATA**
When the Token is used for a general lookup function, GLookupDATA is a pointer to the DNS_GENERAL_LOOKUP_DATA. Type DNS_GENERAL_LOOKUP_DATA is defined below.

EFI_DNS4_COMPLETION_TOKEN structures are used for host name to address translation, host address to name translation and general lookup operation, the Event, RetryCount and RetryInterval fields filed must be filled by the EFI DNS4 Protocol Client. After the operation completes, the EFI DNS4 protocol driver fill in the RspData and Status field and the Event is signaled.

```c
/*-----------------------------------------------
// DNS_HOST_TO_ADDR_DATA
//-----------------------------------------------
typedef struct {
  UINT32        IpCount;
  EFI_IPv4_Address  *IpList;
} DNS_HOST_TO_ADDR_DATA;

IpCount
  Number of the returned IP addresses.

IpList
  Pointer to the all the returned IP addresses.

/*-----------------------------------------------
// DNS_ADDR_TO_HOST_DATA
//-----------------------------------------------
typedef struct {
  CHAR16       *HostName;
} DNS_ADDR_TO_HOST_DATA;

HostName
  Pointer to the primary name for this host address. It’s the caller’s responsibility to free the response memory.

/*-----------------------------------------------
// DNS_GENERAL_LOOKUP_DATA
//-----------------------------------------------
typedef struct {
  UINTN        RRCount;
  DNS_RESOURCE_RECORD *RRList;
} DNS_GENERAL_LOOKUP_DATA;

RRCount
  Number of returned matching RRs.
```

29.4. EFI DNSv4 Protocol
RRList
   Pointer to the all the returned matching RRs. It’s caller responsibility to free the allocated memory to hold the returned RRs.

```c
//*******************************************************************************
// DNS_RESOURCE_RECORD
//*******************************************************************************
typedef struct {
   CHAR8   *QName;
   UINT16  QType;
   UINT16  QClass;
   UINT32  TTL;
   UINT16  DataLength;
   CHAR8   *RData;
} DNS_RESOURCE_RECORD;
```

QName
   The Owner name.

QType
   The Type Code of this RR.

QClass
   The CLASS code of this RR.

TTL
   32 bit integer which specify the time interval that the resource record may be cached before the source of the information should again be consulted. Zero means this RR cannot be cached.

DataLength
   16 big integer which specify the length of RData.

RData
   A string of octets that describe the resource, the format of this information varies according to QType and QClass difference.

Description
   The HostNameToIp () function is used to translate the host name to host IP address. A type A query is used to get the one or more IP addresses for this host.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation was queued successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE&lt;br&gt;&lt;br&gt;This is NULL.&lt;br&gt;&lt;br&gt;Token is NULL.&lt;br&gt;&lt;br&gt;Token. Event is NULL.&lt;br&gt;&lt;br&gt;HostName is NULL. HostName string is unsupported format.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>There’s no source address is available for use.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This instance has not been started.</td>
</tr>
</tbody>
</table>
29.4.6 EFI_DNS4_PROTOCOL.IpToHostName()

Summary
IPv4 address to host name translation also known as Reverse DNS lookup.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_DNS4_IP_TO_HOST_NAME) (
    IN EFI_DNS4_PROTOCOL *This,
    IN EFI_IPv4_ADDRESS IpAddress,
    IN EFI_DNS4_COMPLETION_TOKEN *Token
);
```

Parameter

This
Pointer to EFI_DNS4_PROTOCOL instance.

IpAddress
IP address.

Token
Pointer to the caller-allocated completion used token to translate host address to host name. Type EFI_DNS4_COMPLETION_TOKEN is defined in “Related Definitions” of above HostNameToIp().

Description
The IpToHostName() function is used to translate the host address to host name. A type PTR query is used to get the primary name of the host. Support of this function is optional.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation was queued successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This function is not supported</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>Token. Event is NULL.</td>
</tr>
<tr>
<td></td>
<td>IpAddress is not valid IP address.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>There’s no source address is available for use.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>This Token is being used in another DNS session.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Failed to allocate needed resources.</td>
</tr>
</tbody>
</table>
29.4.7 EFI_DNS4_PROTOCOL.GeneralLookUp()

Summary
Retrieve arbitrary information from the DNS server.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_DNS4_GENERAL_LOOKUP) (  
    IN EFI_DNS4_PROTOCOL *This,
    IN CHAR8 *QName,
    IN UINT16 QType,
    IN UINT16 QClass,
    IN EFI_DNS4_COMPLETION_TOKEN *Token
);
```

Description

This `GeneralLookUp()` function retrieves arbitrary information from the DNS. The caller supplies a `QNAME`, `QTYPE`, and `QCLASS`, and all of the matching RRs are returned. All RR content (e.g., TTL) was returned. The caller need parse the returned RR to get required information. This function is optional.

Parameters

This
Pointer to `EFI_DNS4_PROTOCOL` instance.

QName
Pointer to Query Name.

QType
Query Type.

QClass
Query Name.

Token
Point to the caller-allocated completion token to retrieve arbitrary information. Type `EFI_DNS4_COMPLETION_TOKEN` is defined in “Related Definitions” of above `HostNameToIp()`.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation was queued successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This function is not supported. Or the requested <code>QType</code> is not supported</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more of the following conditions is TRUE:  
  - `This` is NULL.  
  - `Token` is NULL.  
  - `Token` Event is `NULL`.  
  - `QName` is NULL. |
| EFI_NO_MAPPING | There's no source address is available for use. |

continues on next page
**29.4.8 EFI_DNS4_PROTOCOL.UpdateDnsCache()**

**Summary**
This function is used to update the DNS Cache.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPI *EFI_DNS4_UPDATE_DNS_CACHE) (
    IN EFI_DNS4_PROTOCOL *This,
    IN BOOLEAN DeleteFlag,
    IN BOOLEAN Override,
    IN EFI_DNS4_CACHE_ENTRY DnsCacheEntry
);
```

**Parameters**

- **This**
  Pointer to EFI_DNS4_PROTOCOL instance.

- **DeleteFlag**
  If FALSE, this function is to add one entry to the DNS Cache. If TRUE, this function will delete matching DNS Cache entry.

- **Override**
  If TRUE, the matching DNS cache entry will be overwritten with the supplied parameter. If FALSE, EFI_ACCESS_DENIED will be returned if the entry to be added is already exists.

- **DnsCacheEntry**
  Pointer to DNS Cache entry.

**Description**

The UpdateDnsCache() function is used to add/delete/modify DNS cache entry. DNS cache can be normally dynamically updated after the DNS resolve succeeds. This function provided capability to manually add/delete/modify the DNS cache.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>DnsCacheEntry.HostName is NULL.</td>
</tr>
<tr>
<td></td>
<td>DnsCacheEntry.IpAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>DnsCacheEntry.Timeout is zero.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The DNS cache entry already exists and Override is not TRUE.</td>
</tr>
</tbody>
</table>

---

*Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A*

Table 29.35 – continued from previous page

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>This Token is being used in another DNS session.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Failed to allocate needed resources.</td>
</tr>
</tbody>
</table>
29.4.9 EFI_DNS4_PROTOCOL.Poll()

Summary
Polls for incoming data packets and processes outgoing data packets.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_DNS4_POLL) (  
    IN EFI_DNS4_PROTOCOL *This) ;

Parameters
This
Pointer to EFI_DNS4_PROTOCOL instance.

Description
The Poll() function can be used by network drivers and applications to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

In some systems, the periodic timer event in the managed network driver may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the Poll() function more often.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI DNS Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Data was dropped out of the transmit and/or receive queue. Consider increasing the polling rate.</td>
</tr>
</tbody>
</table>

29.4.10 EFI_DNS4_PROTOCOL.Cancel()

Summary
Abort an asynchronous DNS operation, including translation between IP and Host, and general look up behavior.

Prototype

EFI Protocol

typedef
EFI_STATUS
(EFIAPI *EFI_DNS4_CANCEL) (  
    IN EFI_DNS4_PROTOCOL *This,  
    IN EFI_DNS4_COMPLETION_TOKEN *Token) ;

Parameters
This
Pointer to EFI_DNS4_PROTOCOL instance.
Token

Pointer to a token that has been issued by

\texttt{EFI\_DNS4\_PROTOCOL\_HostNameToIp()},
\texttt{EFI\_DNS4\_PROTOCOL\_IpToHostName()} or
\texttt{EFI\_DNS4\_PROTOCOL\_GeneralLookUp()}. If \texttt{NULL}, all pending tokens are aborted.

Description

The \textit{Cancel()} function is used to abort a pending resolution request. After calling this function, \texttt{Token.Status} will be set to \texttt{EFI\_ABORTED} and then \texttt{Token.Event} will be signaled. If the token is not in one of the queues, which usually means that the asynchronous operation has completed, this function will not signal the token and \texttt{EFI\_NOT\_FOUND} is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\texttt{EFI_SUCCESS}</td>
<td>The asynchronous DNS operation was aborted and \texttt{Token-&gt;Event} is signaled.</td>
</tr>
<tr>
<td>\texttt{EFI_NOT_STARTED}</td>
<td>This EFI DNS4 Protocol instance has not been started.</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>This is \texttt{NULL}.</td>
</tr>
<tr>
<td>\texttt{EFI_NOT_FOUND}</td>
<td>When \texttt{Token} is not \texttt{NULL}, and the asynchronous DNS operation was not found in the transmit queue. It was either completed or was not issued by \texttt{HostNameToIp()}, \texttt{IpToHostName()} or \texttt{GeneralLookUp()}.</td>
</tr>
</tbody>
</table>

29.5 \textbf{EFI DNSv6 Protocol}

This section defines the EFI DNSv6 (Domain Name Service version 6) Protocol. It is split into the following two main sections.

- DNSv6 Service Binding Protocol (DNSv6SB)
- DNSv6 Protocol (DNSv6)

29.5.1 DNS6 Service Binding Protocol

29.5.2 \texttt{EFI\_DNS6\_SERVICE\_BINDING\_PROTOCOL}

Summary

The DNSv6SB is used to locate communication devices that are supported by a DNS driver and to create and destroy instances of the DNS child protocol driver.

The EFI Service Binding Protocol in \textit{EFI Services Binding} defines the generic Service Binding Protocol functions. This section discusses the details that are specific to the DNSv6.

GUID

\verb|\#define EFI_DNS6_SERVICE_BINDING_PROTOCOL_GUID |
\verb| { 0x7f1647c8, 0xb76e, 0x44b2, |
\verb| { 0xa5, 0x65, 0xf7, 0xf, 0xf1, 0x9c, 0xd1, 0x9e} |
Description

A network application (or driver) that requires network address resolution can use one of the protocol handler services, such as BS->LocateHandleBuffer(), to search for devices that publish a DNSv6SB GUID. Each device with a published DNSv6SB GUID supports DNSv6 and may be available for use.

After a successful call to the EFI_DNS6_SERVICE_BINDING_PROTOCOL.CreateChild() function, the child DNS driver instance is in an un-configured state; it is not ready to resolve addresses.

Before a network application terminates execution, every successful call to the EFI_DNS6_SERVICE_BINDING_PROTOCOL.CreateChild() function must be matched with a call to the EFI_DNS6_SERVICE_BINDING_PROTOCOL.DestroyChild() function.

NOTE: All the network addresses that are described in EFI_DNS6_PROTOCOL are stored in network byte order. Both incoming and outgoing DNS packets are also in network byte order. All other parameters that are defined in functions or data structures are stored in host byte order.

29.5.3 DNS6 Protocol

29.5.4 EFI_DNS6_PROTOCOL

Summary

This protocol provides the function to get the host name and address mapping, also provide pass through interface to retrieve arbitrary information from DNSv6.

The EFI_DNS6_Protocol is primarily intended to retrieve host addresses using the standard DNS protocol (RFC3596), and support for this protocol is required. Implementations may optionally also support local network name resolution methods such as LLMNR (RFC4795) however DNS queries shall always take precedence, and any use of local network name protocols would be restricted to cases where resolution using DNS protocol fails.

As stated above, all instances of EFI_DNS6_Protocol will utilize a common DNS cache containing the successful results of previous queries on any interface. However, it should be noted that every instance of EFI_DNS6_Protocol is associated with a specific network device or interface, and that all network actions initiated using a specific instance of the DNS protocol will occur only via use of the associated network interface. This means, in a system with multiple network interfaces, that a specific DNS server will often only be reachable using a specific network instance, and therefore the protocol user will need to take steps to insure the DNS instance associated with the proper network interface is used. Or alternatively, the caller may perform DNS functions against all interfaces until successful result is achieved.

GUID

#define EFI_DNS6_PROTOCOL_GUID \ 
{ 0xca37bc1f, 0xa327, 0x4ae9,\ 
  { 0x82, 0x8a, 0x8c, 0x40, 0xd8, 0x50, 0x6a, 0x17 } }

Protocol Interface Structure

typedef struct _EFI_DNS6_PROTOCOL {
  EFI_DNS6_GET_MODE_DATA GetModeData;
  EFI_DNS6_CONFIGURE Configure;
  EFI_DNS6_HOST_NAME_TO_IP HostNameToIp;
  EFI_DNS6_IP_TO_HOST_NAME IpToHostName;
  EFI_DNS6_GENERAL_LOOKUP GeneralLookUp;
  EFI_DNS6_UPDATE_DNS_CACHE UpdateDnsCache;
  EFI_DNS6_POLL Poll;
}(continues on next page)
29.5.5 EFI_DNS6_PROTOCOL.GetModeData()

Summary
Retrieve mode data of this DNS instance.

Prototype

typedef
EFI_STATUS
(EFI_API *EFI_DNS6_GET_MODE_DATA)(
    IN EFI_DNS6_PROTOCOL *This,
    OUT EFI_DNS6_MODE_DATA *DnsModeData
);

Description
This function is used to retrieve DNS mode data for this DNS instance.

Parameter
This
Pointer to EFI_DNS6_PROTOCOL instance.

DnsModeData
Pointer to the caller-allocated storage for the EFI_DNS6_MODE_DATA data.

Related Definitions

//**********************************************
// EFI_DNS6_MODE_DATA
//**********************************************
typedef struct {
    EFI_DNS6_CONFIG_DATA DnsConfigData;
    UINT32 DnsServerCount;
    EFI_IPv6_ADDRESS *DnsServerList;
    UINT32 DnsCacheCount;
    EFI_DNS6_CACHE_ENTRY *DnsCacheList;
} EFI_DNS6_MODE_DATA;

DnsConfigData
The configuration data of this instance. Type EFI_DNS6_CONFIG_DATA is defined below.

DnsServerCount
Number of configured DNS6 servers.

DnsServerList
Pointer to common list of addresses of all configured DNS server used by EFI_DNS6_PROTOCOL instances. List will include DNS servers configured by this or any other EFI_DNS6_PROTOCOL instance. The storage for this list is allocated by the driver publishing this protocol, and must be freed by the caller.

DnsCacheCount
Number of DNS Cache entries. The DNS Cache is shared among all DNS6 instances.
**DnsCacheList**

Pointer to a buffer containing `DnsCacheCount` DNS Cache entry structures. The storage for this list is allocated by the driver publishing this protocol and must be freed by caller.

```c
typedef struct {
    BOOLEAN EnableDnsCache;
    UINT8 Protocol;
    EFI_IPv6_ADDRESS StationIp;
    UINT16 LocalPort;
    UINT32 DnsServerCount;
    EFI_IPv6_ADDRESS *DnsServerList;
    UINT32 RetryCount;
    UINT32 RetryInterval;
} EFI_DNS6_CONFIG_DATA;
```

**IsDnsServerAuto**

If `TRUE`, the DNS server configuration will be retrieved from DHCP server. If `FALSE`, the DNS server configuration will be manually configured through call of `DNSv6.Configure()` [http://www.iana.org/assignments/protocol-numbers]__ interface.

**EnableDnsCache**

If `TRUE`, enable DNS cache function for this DNS instance. If `FALSE`, all DNS query will not lookup local DNS cache.

**Protocol**

Use the protocol number defined in Links to UEFI-Related Documents” ([http://uefi.org/uefi](http://uefi.org/uefi)) under the heading “IANA Protocol Numbers”. Only TCP or UDP are supported, and other protocol values are invalid. An implementation can choose to support only UDP, or both TCP and UDP.

**StationIp**

The local IP address to use. Set to zero to let the underlying IPv6 driver choose a source address. If not zero it must be one of the configured IP addresses in the underlying IPv6 driver.

**DnsServerCount**

Count of the DNS servers. When used with `GetModeData()`, this field is the count of originally configured servers when `Configure()` was called for this instance. When used with `Configure()` this is the count of caller-supplied servers. If the `DnsServerListCount` is zero, the DNS server configuration will be retrieved from DHCP server automatically.

**DnsServerList**

Pointer to DNS server list containing `DnsServerListCount` entries or `NULL` if `DnsServerListCount` is 0. For `Configure()`, this will be `NULL` when there are no caller-supplied server addresses and the DNS instance will retrieve DNS server from DHCP Server. The provided DNS server list is recommended to be filled up in the sequence of preference. When used with `GetModeData()`, the buffer containing the list will be allocated by the driver implementing this protocol and must be freed by the caller. When used with `Configure()`, the buffer containing the list will be allocated and released by the caller.

**LocalPort**

Local port number. Set to zero to use the automatically assigned port number.

**RetryCount**

Retry number if no response received after `RetryInterval`.

**RetryInterval**

Minimum interval of retry is 2 second. If the retry interval is less than 2 second, then use the 2 second.
### EFI_DNS6_CACHE_ENTRY

```c
typedef struct {
    CHAR16 *HostName;
    EFI_IPv6_ADDRESS *IpAddress;
    UINT32 Timeout;
} EFI_DNS6_CACHE_ENTRY;
```

**HostName**
- Host name. This should be interpreted as Unicode characters.

**IpAddress**
- IP address of this host.

**Timeout**
- Time in second unit that this entry will remain in DNS cache. A value of zero means that this entry is permanent.
- A nonzero value will override the existing one if this entry to be added is dynamic entry. Implementations may set its default timeout value for the dynamically created DNS cache entry after one DNS resolve succeeds.

#### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>When <code>DnsConfigData</code> is queried, no configuration data is available because this instance has not been configured.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL or <code>DnsModeData</code> is NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCE</td>
<td>Failed to allocate needed resources.</td>
</tr>
</tbody>
</table>

### 29.5.6 EFI_DNS6_PROTOCOL.Configure()

**Summary**
Configure this DNS instance

**Prototype**

```c
typedef EFI_STATUS (EFIAPI * EFI_DNS6_CONFIGURE)(
    IN EFI_DNS6_PROTOCOL *This,
    IN EFI_DNS6_CONFIG_DATA *DnsConfigData
);
```

**Description**
The `Configure()` function is used to set and change the configuration data for this EFI DNSv6 Protocol driver instance.

**Parameters**

- **This**
  - Pointer to `EFI_DNS6_PROTOCOL` instance.

- **DnsConfigData**
  - Pointer to the configuration data structure. Type
**EFI_DNS6_CONFIG_DATA** is defined in

*EFI_DNS6_PROTOCOL.GetModeData*. All associated storage to be allocated and released by caller.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><em>This is <strong>NULL</strong>. The StationIp address provided in DnsConfigData is not zero and not a valid unicast.</em></td>
</tr>
<tr>
<td></td>
<td><em>DnsServerList is <strong>NULL</strong> while DnsServerListCount is not ZERO. DnsServerListCount is <strong>ZERO</strong> while DnsServerList is not <strong>NULL</strong>.</em></td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The DNS instance data or required space could not be allocated.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The EFI DNSv6 Protocol instance is not configured.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The designated protocol is not supported.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>Second call to Configure() with DnsConfigData. To reconfigure the instance the caller must call Configure() with <strong>NULL</strong> first to return driver to unconfigured state.</td>
</tr>
</tbody>
</table>

### 29.5.7 EFI_DNS6_PROTOCOL.HostNameToIp()

**Summary**

Host name to host address translation

**Prototype**

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_DNS6_HOST_NAME_TO_IP) (      
    IN EFI_DNS6_PROTOCOL *This,
    IN CHAR16 *HostName,
    IN EFI_DNS6_COMPLETION_TOKEN *Token
);
```

**Parameter**

**This**

Pointer to *EFI_DNS6_PROTOCOL* instance.

**Hostname**

Pointer to buffer containing fully-qualified Domain Name including *Hostname*. To resolve successfully, characters within the FQDN string must be chosen according to the format and from within the set of ASCII characters authorized by DNS specifications. Any translation required for reference to domains or hostnames defined as containing Unicode characters, for example use of Punycode, must be performed by caller.

**Token**

Point to the completion token to translate host name to host address. Type *EFI_DNS6_COMPLETION_TOKEN* is defined in “Related Definitions” below.

**Related Definitions**
/*---------------------------------------------
/* EFI_DNS6_COMPLETION_TOKEN
/*---------------------------------------------
typedef struct {
    EFI_EVENT         Event;
    EFI_STATUS        Status;
    UINT32            RetryCount;
    UINT32            RetryInterval;
    union {
        DNS6_HOST_TO_ADDR_DATA *H2AData;
        DNS6_ADDR_TO_HOST_DATA *A2HData;
        DNS6_GENERAL_LOOKUP_DATA *GLookupData;
    } RspData;
} EFI_DNS6_COMPLETION_TOKEN;

Event
This Event will be signaled after the Status field is updated by the EFI DNSv6 protocol driver. The type of Event must be EFI_NOTIFY_SIGNAL.

Status
Will be set to one of the following values.

EFI_SUCCESS : The host name to address translation completed successfully.
EFI_NOT_FOUND : No matching Resource Record (RR) is found.
EFI_TIMEOUT : No DNS server reachable, or RetryCount was exhausted without response from all specified DNS servers.
EFI_DEVICE_ERROR : An unexpected system or network error occurred.
EFI_NO_MEDIA : There was a media error.

RetryCount
The parameter configured through DNSv6.Configure() interface. Retry number if no response received after RetryInterval.

RetryInterval
The parameter configured through DNSv6.Configure() interface. Minimum interval of retry is 2 second. If the retry interval is less than 2 second, then use the 2 second.

H2AData
When the Token is used for host name to address translation, H2AData is a pointer to the DNS6_HOST_TO_ADDR_DATA. Type DNS6_HOST_TO_ADDR_DATA is defined below.

A2HData
When the Token is used for host address to host name translation, A2HData is a pointer to the DNS6_ADDR_TO_HOST_DATA. Type DNS6_ADDR_TO_HOST_DATA is defined below.

GLookupData
When the Token is used for a general lookup function, GLookupData is a pointer to the DNS6_GENERAL_LOOKUP_DATA. Type DNS6_GENERAL_LOOKUP_DATA is defined below.

EFI_DNS6_COMPLETION_TOKEN structures are used for host name to address translation, host address to name translation and general lookup operation, the Event filed must be filled by the EFI DNSv6 Protocol Client. If the caller attempts to reuse Token before the completion event is triggered or canceled, EFI_ALREADY_STARTED will be returned. After the operation completes, the EFI DNSv6 protocol driver fill in the RspData and Status field and the Event is signaled.
typedef struct {
    UINT32 IpCount;
    EFI_IPv6_ADDRESS *IpList;
} DNS6_HOST_TO_ADDR_DATA;

IpCount
Number of the returned IP address

IpList
Pointer to all the returned IP address

typedef struct {
    CHAR16 *HostName;
} DNS6_ADDR_TO_HOST_DATA;

HostName
Pointer to the primary name for this host address. It’s the caller’s responsibility to free the response memory.

typedef struct {
    UINTN RRCount;
    DNS6_RESOURCE_RECORD *RRList;
} DNS6_GENERAL_LOOKUP_DATA;

RRCount
Number of returned matching RRs.

RRList
Pointer to all the returned matching RRs. It’s the caller’s responsibility to free the allocated memory to hold the returned RRs

typedef struct {
    CHAR8 *QName;
    UINT16 QType;
    UINT16 QClass;
    UINT32 TTL;
    UINT16 DataLength;
    CHAR8 *RData;
} DNS6_RESOURCE_RECORD;

QName
The Owner name.

QType
The Type Code of this RR
QClass
   The CLASS code of this RR.

TTL
   32 bit integer which specify the time interval that the resource record may be cached before the source of the information should again be consulted. Zero means this RR cannot be cached.

DataLength
   16 big integer which specify the length of RData.

RData
   A string of octets that describe the resource, the format of this information varies according to QType and QClass difference.

Description
   The HostNameToIp() function is used to translate the host name to host IP address. A type AAAA record query is used to get the one or more IPv6 addresses for this host.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation was queued successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>Token. Event is NULL.</td>
</tr>
<tr>
<td></td>
<td>HostName is NULL or buffer contained unsupported characters.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>There’s no source address is available for use.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>This Token is being used in another DNS session.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This instance has not been started.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Failed to allocate needed resources.</td>
</tr>
</tbody>
</table>

29.5.8 EFI_DNS6_PROTOCOL.IpToHostName()

Summary
   Host address to host name translation

Prototype
   
   typedef EFI_STATUS
   (EFIAPI *EFI_DNS6_IP_TO_HOST_NAME) ( 
       IN EFI_DNS6_PROTOCOL *This,
       IN EFI_IPv6_ADDRESS IpAddress,
       IN EFI_DNS6_COMPLETION_TOKEN *Token 
   );

Parameter

This
   Pointer to EFI_DNS6_PROTOCOL instance.

IpAddress
   IP address.
Token

Point to the completion token to translate host address to host name. Type EFI_DNS6_COMPLETION_TOKEN is defined in “Related Definitions” of above HostNameToIp().

Description

The IpToHostName() function is used to translate the host address to host name. A type PTR query is used to get the primary name of the host. Implementation can choose to support this function or not.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation was queued successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This function is not supported</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>Token is NULL.</td>
</tr>
<tr>
<td></td>
<td>Token.Event is NULL.</td>
</tr>
<tr>
<td></td>
<td>IpAddress is not valid IP address.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>There’s no source address is available for use.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This instance has not been started.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Failed to allocate needed resources.</td>
</tr>
</tbody>
</table>

29.5.9 EFI_DNS6_PROTOCOL.GeneralLookUp()

Summary

This function provides capability to retrieve arbitrary information from the DNS server.

Prototype

```c
typedef EFI_STATUS
    (EFIAPI *EFI_DNS6_GENERAL_LOOKUP) (
    IN EFI_DNS6_PROTOCOL *This,
    IN CHAR8 *QName,
    IN UINT16 QType,
    IN UINT16 QClass,
    IN EFI_DNS6_COMPLETION_TOKEN *Token
    )
);```

Description

This GeneralLookUp() function retrieves arbitrary information from the DNS. The caller supplies a QNAME, QTYPE, and QCLASS, and all of the matching RRs are returned. All RR content (e.g., TTL) was returned. The caller need parse the returned RR to get required information. The function is optional. Implementation can choose to support it or not.

Parameters

This

Pointer to EFI_DNS6_PROTOCOL instance.

QName

Pointer to Query Name.

29.5. EFI DNSv6 Protocol
QType
Query Type.

QClass
Query Name.

Token
Point to the completion token to retrieve arbitrary information. Type EFI_DNS6_COMPLETION_TOKEN is defined in “Related Definitions” of above HostNameToIp().

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation was queued successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This function is not supported. Or the requested QType is not supported</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE</td>
</tr>
<tr>
<td></td>
<td>This is NULL</td>
</tr>
<tr>
<td></td>
<td>Token is NULL</td>
</tr>
<tr>
<td></td>
<td>Token. Event is NULL</td>
</tr>
<tr>
<td></td>
<td>QName is NULL</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>There's no source address is available for use.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This instance has not been started.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Failed to allocate needed resources.</td>
</tr>
</tbody>
</table>

29.5.10 EFI_DNS6_PROTOCOL.UpdateDnsCache()

Summary
This function is to update the DNS Cache.

Prototype

typedef EFI_STATUS
(EFIAPIC *EFI_DNS6_UPDATE_DNS_CACHE) (  
    IN EFI_DNS6_PROTOCOL *This, 
    IN BOOLEAN DeleteFlag, 
    IN BOOLEAN Override, 
    IN EFI_DNS6_CACHE_ENTRY DnsCacheEntry
);

Parameters

This
Pointer to EFI_DNS6_PROTOCOL instance.

DeleteFlag
If FALSE, this function is to add one entry to the DNS Cache. If TRUE, this function will delete matching DNS Cache entry.

Override
If TRUE, the matching DNS cache entry will be overwritten with the supplied parameter. If FALSE, EFI_ACCESS_DENIED will be returned if the entry to be added is already existed.
DnsCacheEntry
   Pointer to DNS Cache entry.

Description
The UpdateDnsCache() function is used to add/delete/modify DNS cache entry. DNS cache can be normally dynamically updated after the DNS resolve succeeds. This function provided capability to manually add/delete/modify the DNS cache.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>DnsCacheEntry.HostName is NULL.</td>
</tr>
<tr>
<td></td>
<td>DnsCacheEntry.IpAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>DnsCacheEntry.Timeout is ZERO.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The DNS cache entry already exists and Override is not TRUE.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCE</td>
<td>Failed to allocate needed resources.</td>
</tr>
</tbody>
</table>

29.5.11 EFI_DNS6_PROTOCOL.POLL()

Summary
Polls for incoming data packets and processes outgoing data packets.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_DNS6_POLL) (
   IN EFI_DNS6_PROTOCOL *This
);

Parameters
This
   Pointer to EFI_DNS6_PROTOCOL instance.

Description
The Poll() function can be used by network drivers and applications to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

In some systems, the periodic timer event in the managed network driver may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the Poll() function more often.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI DNS Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>There’s no source address is available for use.</td>
</tr>
</tbody>
</table>

continues on next page
Table 29.45 – continued from previous page

<table>
<thead>
<tr>
<th>EFI_DEVICE_ERROR</th>
<th>An unexpected system or network error occurred.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_TIMEOUT</td>
<td>Data was dropped out of the transmit and/or receive queue. Consider increasing the polling rate.</td>
</tr>
</tbody>
</table>

### 29.5.12 EFI_DNS6_PROTOCOL_Cancel()

Abort an asynchronous DNS operation, including translation between IP and Host, and general look up behavior.

**EFI Protocol**

```c
typedef EFI_STATUS (EFIAPI *EFI_DNS6_CANCEL) (IN EFI_DNS6_PROTOCOL *This, IN EFI_DNS6_COMPLETION_TOKEN *Token);
```

**Parameters**

- **This**
  - Pointer to `EFI_DNS6_PROTOCOL` instance.

- **Token**
  - Pointer to a token that has been issued by
    - `EFI_DNS6_PROTOCOL.HostNameToIp()`,
    - `EFI_DNS6_PROTOCOL.IpToHostName()` or
    - `EFI_DNS6_PROTOCOL.GeneralLookUp()`. If **NULL**, all pending tokens are aborted.

**Description**

The `Cancel()` function is used to abort a pending resolution request. After calling this function, Token.Status will be set to `EFI_ABORTED` and `Token.Event` will be signaled. If the token is not in one of the queues, which usually means that the asynchronous operation has completed, this function will not signal the token and `EFI_NOT_FOUND` is returned.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The asynchronous DNS operation was aborted and Token-&gt;Event is signaled.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI DNS6 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>There’s no source address is available for use.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>When Token is not <strong>NULL</strong> and the asynchronous DNS operation was not found in the transmit queue, it is either completed or was not issued by <code>HostNameToIp()</code>, <code>IpToHostName()</code> or <code>GeneralLookUp()</code>.</td>
</tr>
</tbody>
</table>
29.6 EFI HTTP Protocols

This section defines the EFI HTTP Protocol interface. It is split into the following two main sections.

- HTTP Service Binding Protocol (HTTPSB)
- HTTP Protocol (HTTP)

29.6.1 HTTP Service Binding Protocol

29.6.1.1 EFI_HTTP_SERVICE_BINDING_PROTOCOL

Summary

The HTTPSB is used to locate communication devices that are supported by a HTTP driver and to create and destroy instances of the HTTP child protocol driver.

The EFI Service Binding Protocol in *EFI Services Binding* defines the generic Service Binding Protocol functions. This section discusses the details that are specific to the HTTP.

GUID

```
#define EFI_HTTP_SERVICE_BINDING_PROTOCOL_GUID \
  {0xbdc8e6af, 0xd9bc, 0x4379, \
   {0xa7, 0x2a, 0xe0, 0xc4, 0xe7, 0x5d, 0xae, 0x1c}}
```

Description

A network application (or driver) that requires HTTP communication service can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish a HTTPSB GUID. Each device with a published HTTPSB GUID supports HTTP Service Binding Protocol and may be available for use.

After a successful call to the `EFI_HTTP_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the child HTTP driver instance is in an uninitialized state; it is not ready to initiate HTTP data transfer.

Before a network application terminates execution, every successful call to the `EFI_HTTP_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI_HTTP_SERVICE_BINDING_PROTOCOL.DestroyChild()` function.

29.6.2 EFI HTTP Protocol Specific Definitions

29.6.3 EFI_HTTP_PROTOCOL

Protocol GUID

```
#define EFI_HTTP_PROTOCOL_GUID \
  {0x7a59b29b, 0x910b, 0x4171, \
   {0x82, 0x42, 0xa8, 0x5a, 0x0d, 0xf2, 0x5b, 0x5b}}
```

Protocol Interface Structure
typedef struct _EFI_HTTP_PROTOCOL {
    EFI_HTTP_GET_MODE_DATA       GetModeData;
    EFI_HTTP_CONFIGURE           Configure;
    EFI_HTTP_REQUEST             Request;
    EFI_HTTP_CANCEL              Cancel;
    EFI_HTTP_RESPONSE            Response;
    EFI_HTTP_POLL                Poll;
} EFI_HTTP_PROTOCOL;

Parameters

GetModeData
Gets the current operational status. See the GetModeData() function description.

Configure
Initialize, change, or reset operational settings in the EFI HTTP protocol instance. See Configure() for function description.

Request
Queue a request token into the transmit queue. This function is a non-blocking operation. See Request() for function description.

Cancel
Abort a pending request or response operation. See Cancel() for function description.

Response
Queue a response token into the receive queue. This function is a non-blocking operation. See Response() for function description.

Poll
Poll to receive incoming HTTP response and transmit outgoing HTTP request. See Poll() for function description.

Description
The EFI HTTP protocol is designed to be used by EFI drivers and applications to create and transmit HTTP Requests, as well as handle HTTP responses that are returned by a remote host. This EFI protocol uses and relies on an underlying EFI TCP protocol.

29.6.4 EFI_HTTP_PROTOCOL.GetModeData()

Summary
Returns the operational parameters for the current HTTP child instance.

EFI Protocol
typedef
EFI_STATUS
(EFIAPI * EFI_HTTP_GET_MODE_DATA)(
    IN EFI_HTTP_PROTOCOL *This,
    OUT EFI_HTTP_CONFIG_DATA *HttpConfigData
);

Parameters

This
Pointer to EFI_HTTP_PROTOCOL instance.
**HttpConfigData**

Pointer to the buffer for operational parameters of this HTTP instance. Type `EFI_HTTP_CONFIG_DATA` is defined in “Related Definitions” below. It is the responsibility of the caller to allocate the memory for `HttpConfigData` and `HttpConfigData->AccessPoint.IPv6Node/IPv4Node`. In fact, it is recommended to allocate sufficient memory to record IPv6Node since it is big enough for all possibilities.

**Description**

The `GetModeData()` function is used to read the current mode data (operational parameters) for this HTTP protocol instance.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Operation succeeded</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>This is NULL. HttpConfigData is NULL. Http ConfigData-&gt;AccessPoint.IPv4Node or Http ConfigData-&gt;AccessPoint.IPv6Node is NULL</code></td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI HTTP Protocol instance has not been started.</td>
</tr>
</tbody>
</table>

```c
typedef struct {
    EFI_HTTP_VERSION      HttpVersion;
    UINT32                 TimeOutMillisec;
    BOOLEAN                LocalAddressIsIPv6;
    union {
        EFI_HTTPv4_ACCESS_POINT  *IPv4Node;
        EFI_HTTPv6_ACCESS_POINT  *IPv6Node;
    } AccessPoint;
} EFI_HTTP_CONFIG_DATA;
```

**HttpVersion**

HTTP version that this instance will support.

**TimeOutMillisec**

Time out (in milliseconds) when blocking for requests.

**LocalAddressIsIPv6**

Defines behavior of EFI DNS and TCP protocols consumed by this instance. If FALSE, this instance will use `EFI_DNS4_PROTOCOL` and `EFI_TCP4_PROTOCOL`. If TRUE, this instance will use `EFI_DNS6_PROTOCOL` and `EFI_TCP6_PROTOCOL`.

**IPv4Node**

When `LocalAddressIsIPv6` is FALSE, this points to the local address, subnet, and port used by the underlying TCP protocol.

**IPv6Node**

When `LocalAddressIsIPv6` is TRUE, this points to the local IPv6 address and port used by the underlying TCP protocol.
typedef enum {
    HttpVersion10,
    HttpVersion11,
    HttpVersionUnsupported
} EFI_HTTP_VERSION;

typedef struct {
    BOOLEAN UseDefaultAddress;
    EFI_IPv4_ADDRESS LocalAddress;
    EFI_IPv4_ADDRESS LocalSubnet;
    UINT16 LocalPort;
} EFI_HTTPv4_ACCESS_POINT;

UseDefaultAddress
Set to TRUE to instruct the EFI HTTP instance to use the default address information in every TCP connection made by this instance. In addition, when set to TRUE, LocalAddress and LocalSubnet are ignored.

LocalAddress
If UseDefaultAddress is set to FALSE, this defines the local IP address to be used in every TCP connection opened by this instance.

LocalSubnet
If UseDefaultAddress is set to FALSE, this defines the local subnet to be used in every TCP connection opened by this instance.

LocalPort
This defines the local port to be used in every TCP connection opened by this instance.

typedef struct {
    EFI_IPv6_ADDRESS LocalAddress;
    UINT16 LocalPort;
} EFI_HTTPv6_ACCESS_POINT;

LocalAddress
Local IP address to be used in every TCP connection opened by this instance.

LocalPort
Local port to be used in every TCP connection opened by this instance.
29.6.5 EFI_HTTP_PROTOCOL.Configure()

Summary
Initialize or brutally reset the operational parameters for this EFI HTTP instance.

EFI Protocol

typedef
EFI_STATUS
(EIFIAPI *EFI_HTTP_CONFIGURE)(
     IN EFI_HTTP_PROTOCOL *This,
     IN EFI_HTTP_CONFIG_DATA *HttpConfigData OPTIONAL
);

Parameters

This
Pointer to EFI_HTTP_PROTOCOL instance.

HttpConfigData
Pointer to the configure data to configure the instance.

Description
The Configure() function does the following:

- When HttpConfigData is not NULL Initialize this EFI HTTP instance by configuring timeout, local address, port, etc.
- When HttpConfigData is NULL, reset this EFI HTTP instance by closing all active connections with remote hosts, canceling all asynchronous tokens, and flush request and response buffers without informing the appropriate hosts.

No other EFI HTTP function can be executed by this instance until the Configure() function is executed and returns successfully.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Operation succeeded.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE: This is NULL. HttpConfigData-&gt;LocalAddressIsIPv6 is FALSE and HttpConfigData-&gt;AccessPoint.IPv4Node is NULL. HttpConfigData-&gt;LocalAddressIsIPv6 is TRUE and HttpConfigData-&gt;AccessPoint.IPv6Node is NULL.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>Reinitialize this HTTP instance without calling Configure() with NULL to reset it.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate enough system resources when executing Configure().</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>One or more options in ConfigData are not supported in the implementation.</td>
</tr>
</tbody>
</table>
29.6.6 EFI_HTTP_PROTOCOL.Request()

Summary

The Request() function queues an HTTP request to this HTTP instance, similar to *Transmit() function in the EFI TCP driver. When the HTTP request is sent successfully, or if there is an error, Status in token will be updated and Event will be signaled.

EFI Protocol

```c
typedef
EFI_STATUS
(EFIAPI *EFI_HTTP_REQUEST) (
    IN EFI_HTTP_PROTOCOL *This,
    IN EFI_HTTP_TOKEN *Token
);
```

Parameters

This

Pointer to EFI_HTTP_PROTOCOL instance.

Token

Pointer to storage containing HTTP request token. Type EFI_HTTP_TOKEN is defined in “Related Definitions” below.

Related Definitions

```c
//******************************************
// EFI_HTTP_TOKEN
//******************************************
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    EFI_HTTP_MESSAGE *Message;
} EFI_HTTP_TOKEN;
```

Event

This Event will be signaled after the Status field is updated by the EFI HTTP Protocol driver. The type of Event must be EFI_NOTIFY_SIGNAL. The Task Priority Level (TPL) of Event must be lower than or equal to TPL_CALLBACK.

Status

Status will be set to one of the following value if the HTTP request is successfully sent or if an unexpected error occurs:

- **EFI_SUCCESS**: The HTTP request was successfully sent to the remote host.
- **EFI_HTTP_ERROR**: The response message was successfully received but contains a HTTP error. The response status code is returned in Token.
- **EFI_ABORTED**: The HTTP request was canceled by the caller and removed from the transmit queue.
- **EFI_TIMEOUT**: The HTTP request timed out before reaching the remote host.
- **EFI_DEVICE_ERROR**: An unexpected system or network error occurred.
Message
    Pointer to storage containing HTTP message data.

//******************************************************************************
// EFI_HTTP_MESSAGE
//******************************************************************************
typedef struct {
    union {
        EFI_HTTP_REQUEST_DATA *Request;
        EFI_HTTP_RESPONSE_DATA *Response;
    } Data;
    UINTN HeaderCount;
    EFI_HTTP_HEADER *Headers;
    UINTN BodyLength;
    VOID *Body;
} EFI_HTTP_MESSAGE;

Request
    When the token is used to send a HTTP request, Request is a pointer to storage that contains such data as URL and HTTP method.

Response
    When used to await a response, Response points to storage containing HTTP response status code.

HeaderCount
    Number of HTTP header structures in Headers list. On request, this count is provided by the caller. On response, this count is provided by the HTTP driver.

Headers
    Array containing list of HTTP headers. On request, this array is populated by the caller. On response, this array is allocated and populated by the HTTP driver. It is the responsibility of the caller to free this memory on both request and response.

BodyLength
    Length in bytes of the HTTP body. This can be zero depending on the HttpMethod type. Body Body associated with the HTTP request or response. This can be NULL depending on the HttpMethod type.

The HTTP driver will prepare a request string from the information contained in and queue it to the underlying TCP instance to be sent to the remote host. Typically, all fields in the structure will contain content (except Body and BodyLength when HTTP method is not POST or PUT), but there is a special case when using PUT or POST to send large amounts of data. Depending on the size of the data, it may not be able to be stored in a contiguous block of memory, so the data will need to be provided in chunks. In this case, if Body is not NULL and BodyLength is non-zero and all other fields are NULL or 0, the HTTP driver will queue the data to be sent to the last remote host that a token was successfully sent. If no previous token was sent successfully, this function will return EFI_INVALID_PARAMETER.

The HTTP driver is expected to close existing (if any) underlying TCP instance and create new TCP instance if the host name in the request URL is different from previous calls to Request(). This is consistent with RFC 2616 recommendation that HTTP clients should attempt to maintain an open TCP connection between client and host.

//******************************************************************************
// EFI_HTTP_REQUEST_DATA
//******************************************************************************
typedef struct {
    EFI_HTTP_METHOD Method;
    CHAR16 *Url;
} EFI_HTTP_REQUEST_DATA;
Method
The HTTP method (e.g. GET, POST) for this HTTP Request.

Url
The URI of a remote host. From the information in this field, the HTTP instance will be able to determine whether to use HTTP or HTTPS and will also be able to determine the port number to use. If no port number is specified, port 80 (HTTP) is assumed. See RFC 3986 for more details on URI syntax.

```c
// ****************************************************************************
// EFI_HTTP_METHOD
// ****************************************************************************
typedef enum {
    HttpMethodGet,
    HttpMethodPost,
    HttpMethodPatch,
    HttpMethodOptions,
    HttpMethodConnect,
    HttpMethodHead,
    HttpMethodPut,
    HttpMethodDelete,
    HttpMethodTrace,
    HttpMethodMax
} EFI_HTTP_METHOD;

// ****************************************************************************
// EFI_HTTP_RESPONSE_DATA
// ****************************************************************************
typedef struct {
    EFI_HTTP_STATUS_CODE StatusCode;
} EFI_HTTP_RESPONSE_DATA;

StatusCode
Response status code returned by the remote host.

```c
// ****************************************************************************
// EFI_HTTP_HEADER
// ****************************************************************************
typedef struct {
    CHAR8 *FieldName;
    CHAR8 *FieldValue;
} EFI_HTTP_HEADER;

FieldName
NULL terminated string which describes a field name. See RFC 2616 Section 14 for detailed information about field names.

FieldValue
NULL terminated string which describes the corresponding field value. See RFC 2616 Section 14 for detailed information about field values.

```c
typedef enum {
    HTTP_STATUS_UNSUPPORTED_STATUS = 0,
    HTTP_STATUS_100_CONTINUE,
    HTTP_STATUS_101_SWITCHING_PROTOCOLS,
    (continues on next page)
```
HTTP_STATUS_200_OK,
HTTP_STATUS_201_CREATED,
HTTP_STATUS_202_ACCEPTED,
HTTP_STATUS_203_NON_AUTHORITATIVE_INFORMATION,
HTTP_STATUS_204_NO_CONTENT,
HTTP_STATUS_205_RESETCONTENT,
HTTP_STATUS_206_PARTIAL_CONTENT,
HTTP_STATUS_300_MULTIPLE_CHOICES,
HTTP_STATUS_301_MOVED_PERMANENTLY,
HTTP_STATUS_302_FOUND,
HTTP_STATUS_303_SEE_OTHER,
HTTP_STATUS_304_NOT_MODIFIED,
HTTP_STATUS_305_USE_PROXY,
HTTP_STATUS_307_TEMPORARY_REDIRECT,
HTTP_STATUS_400_BAD_REQUEST,
HTTP_STATUS_401_UNAUTHORIZED,
HTTP_STATUS_402_PAYMENT_REQUIRED,
HTTP_STATUS_403_FORBIDDEN,
HTTP_STATUS_404_NOT_FOUND,
HTTP_STATUS_405_METHOD_NOT_ALLOWED,
HTTP_STATUS_406_NOT_ACCEPTABLE,
HTTP_STATUS_407_PROXY_AUTHENTICATION_REQUIRED,
HTTP_STATUS_408_REQUEST_TIME_OUT,
HTTP_STATUS_409_CONFLICT,
HTTP_STATUS_410_GONE,
HTTP_STATUS_411_LENGTH_REQUIRED,
HTTP_STATUS_412_PRECONDITION_FAILED,
HTTP_STATUS_413_REQUEST_ENTITY_TOO_LARGE,
HTTP_STATUS_414_REQUEST_URI_TOO_LARGE,
HTTP_STATUS_415_UNSUPPORTED_MEDIA_TYPE,
HTTP_STATUS_416_REQUESTED_RANGE_NOT_SATISFIED,
HTTP_STATUS_417_EXPECTATION_FAILED,
HTTP_STATUS_500_INTERNAL_SERVER_ERROR,
HTTP_STATUS_501_NOT_IMPLEMENTED,
HTTP_STATUS_502_BAD_GATEWAY,
HTTP_STATUS_503_SERVICE_UNAVAILABLE,
HTTP_STATUS_504_GATEWAY_TIME_OUT,
HTTP_STATUS_505_HTTP_VERSION_NOT_SUPPORTED,
HTTP_STATUS_308_PERMANENT_REDIRECT
} EFI_HTTP_STATUS_CODE;

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI HTTP Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Data was dropped out of the transmit or receive queue.</td>
</tr>
</tbody>
</table>
Table 29.49 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
</table>
| EFI_INVALID_PARAMETER | One or more of the following conditions is TRUE  
This is **NULL**.  
Token is **NULL**.  
Token->Message is **NULL**.  
Token->Message->Body is not **NULL**,  
Token->Message->BodyLength is non-zero, and  
Token->Message->Data is **NULL**, but a previous call to Request() has not been completed successfully. |
| EFI_OUT_OF_RESOURCES  | Could not allocate enough system resources.                                                                                                                                 |
| EFI_UNSUPPORTED      | The HTTP method is not supported in current implementation.                                                                                   |

### 29.6.7 EFI_HTTP_PROTOCOL.Cancel()

**Summary**

Abort an asynchronous HTTP request or response token.

**EFI Protocol**

```c
typedef EFI_STATUS (EFIAPI * EFI_HTTP_CANCEL)(
    IN EFI_HTTP_PROTOCOL *This,
    IN EFI_HTTP_TOKEN *Token,
);
```

**Parameters**

**This**

Pointer to `EFI_HTTP_PROTOCOL` instance.

**Token**

Point to storage containing HTTP request or response token.

**Description**

The `Cancel()` function aborts a pending HTTP request or response transaction. If `Token` is not **NULL** and the token is in transmit or receive queues when it is being cancelled, its `Token->Status` will be set to `EFI_ABORTED` and then `Token->Event` will be signalled. If the token is not in one of the queues, which usually means that the asynchronous operation has completed, `EFI_NOT_FOUND` is returned. If `Token` is **NULL**, all asynchronous tokens issued by `Request()` or `Response()` will be aborted.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Request and Response queues are successfully flushed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This instance hasn’t been configured.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The asynchronous request or response token is not found.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation does not support this function.</td>
</tr>
</tbody>
</table>
29.6.8 EFI_HTTP_PROTOCOL.Response()

Summary

The `Response()` function queues an HTTP response to this HTTP instance, similar to `Receive()` function in the EFI TCP driver. When the HTTP response is received successfully, or if there is an error, `Status` in token will be updated and `Event` will be signaled.

EFI Protocol

typedef EFI_STATUS (EFIAPI *EFI_HTTP_RESPONSE) ( IN EFI_HTTP_PROTOCOL *This, IN EFI_HTTP_TOKEN *Token );

Parameters

This

Pointer to `EFI_HTTP_PROTOCOL` instance.

Token

Pointer to storage containing HTTP response token. See `Request()` function for the definition of `EFI_HTTP_TOKEN`.

Description

The HTTP driver will queue a receive token to the underlying TCP instance. When data is received in the underlying TCP instance, the data will be parsed and `Token` will be populated with the response data. If the data received from the remote host contains an incomplete or invalid HTTP header, the HTTP driver will continue waiting (asynchronously) for more data to be sent from the remote host before signaling `Event` in `Token`.

It is the responsibility of the caller to allocate a buffer for `Body` and specify the size in `BodyLength`. If the remote host provides a response that contains a content body, up to `BodyLength` bytes will be copied from the receive buffer into `Body` and `BodyLength` will be updated with the amount of bytes received and copied to `Body`. This allows the client to download a large file in chunks instead of into one contiguous block of memory. Similar to HTTP request, if `Body` is not `NULL` and `BodyLength` is non-zero and all other fields are `NULL` or `0`, the HTTP driver will queue a receive token to underlying TCP instance. If data arrives in the receive buffer, up to `BodyLength` bytes of data will be copied to `Body`. The HTTP driver will then update `BodyLength` with the amount of bytes received and copied to `Body`.

If the HTTP driver does not have an open underlying TCP connection with the host specified in the response URL, `Response()` will return `EFI_ACCESS_DENIED`. This is consistent with RFC 2616 recommendation that HTTP clients should attempt to maintain an open TCP connection between client and host.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Allocation succeeded</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI HTTP Protocol instance has not been initialized.</td>
</tr>
</tbody>
</table>

continues on next page
Table 29.51 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <strong>TRUE</strong></td>
</tr>
<tr>
<td></td>
<td>*This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>*Token is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>*Token-&gt;Message is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>*Token-&gt;Message-&gt;Body is not <strong>NULL</strong>, Token-&gt;Message-&gt;BodyLength is non-zero, and Token-&gt;Message-&gt;Data is <strong>NULL</strong>, but a previous call to Response() has not been completed successfully</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate enough system resources.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>An open TCP connection is not present with the host specified by response URL</td>
</tr>
</tbody>
</table>

### 29.6.9 EFI_HTTP_PROTOCOL.Poll()

Polls for incoming data packets and processes outgoing data packets.

```c
typedef EFI_STATUS
(EFIAPIC *EFI_HTTP_POLL)(
    IN EFI_HTTP_PROTOCOL *This
);
```

**Parameters**

**This**
- Pointer to EFI_HTTP_PROTOCOL instance.

**Description**

The `Poll()` function can be used by network drivers and applications to increase the rate that data packets are moved between the communication devices and the transmit and receive queues. In some systems, the periodic timer event in the managed network driver may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the `Poll()` function more often.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>*This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>No incoming or outgoing data is processed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI HTTP Protocol instance has not been started.</td>
</tr>
</tbody>
</table>
29.6.9.1 Usage Examples

Here is an example of a client making a HTTP Request to download a driver bundle from Intel Driver Download Center. This example includes sample code for how to support a client that is behind a HTTP proxy server.

```c
#include <Uefi.h>
#include <HttpProtocol.h>

#define BUFFER_SIZE 0x100000

BOOLEAN gRequestCallbackComplete = FALSE;
BOOLEAN gResponseCallbackComplete = FALSE;

VOID
EFI_API
RequestCallback(
    IN EFI_EVENT Event,
    IN VOID *Context
)
{
    gRequestCallbackComplete = TRUE;
}

VOID
EFI_API
ResponseCallback(
    IN EFI_EVENT Event,
    IN VOID *Context
)
{
    gResponseCallbackComplete = TRUE;
}

EFI_STATUS
EFI_API
HttpClientMain(
    IN EFI_HANDLE ImageHandle,
    IN EFI_SYSTEM_TABLE *SystemTable
)
{
    EFI_STATUS Status;
    EFI_SERVICE_BINDING_PROTOCOL *ServiceBinding;
    EFI_HANDLE *Handle;
    EFI_HTTP_PROTOCOL *HttpProtocol;
    EFI_HTTP_CONFIG_DATA ConfigData;
    EFI_HTTPv4_ACCESS_POINT IPv4Node;
    EFI_HTTP_REQUEST_DATA RequestData;
    EFI_HTTP_HEADER RequestHeader;
    EFI_HTTP_MESSAGE RequestMessage;
    EFI_HTTP_RESPONSE_DATA ResponseData;
    EFI_HTTP_MESSAGE ResponseMessage;
```

(continues on next page)
The HTTP driver must first be configured before requests or responses can be processed. This is the same for other network protocols such as TCP.

Status = HttpProtocol->Configure(HttpProtocol, &ConfigData);

// This request message is initialized to request a sample driver bundle from Intel's driver download center. To download a file, we use HTTP GET.
RequestData.Method = HttpMethodGet;
// URI where the file is located that we want to download.
// This header tells the HTTP driver to relay the HTTP request via a proxy server. This header is just used to demonstrate how to relay through a proxy with this driver. The method for obtaining the proxy address is up to the client. The
// HTTP driver does NOT resolve this on its own.
RequestHeader.FieldName = "Host";
RequestHeader.FieldValue = "my.proxyserver.com";
// Message format just contains a pointer to the request data
// and body info, if applicable. In the case of HTTP GET, body
// is not relevant.
RequestMessage.Data.Request = &RequestData;
// Just one header being provided in the HTTP message.
RequestMessage.HeaderCount = 1;
RequestMessage.Headers = &RequestHeader;
RequestMessage.BodyLength = 0;
RequestMessage.Body = NULL;
// Token format is similar to the token format in EFI TCP protocol.
RequestToken.Event = NULL;
Status = gBS->CreateEvent(
    EVT_NOTIFY_SIGNAL,
    TPL_CALLBACK,
    RequestCallback,
    NULL,
    &RequestToken.Event
);
// TODO: Handle error...
RequestToken.Status = EFI_SUCCESS;
RequestToken.Message = &RequestMessage;

gRequestCallbackComplete = FALSE;
// Finally, make HTTP request.
Status = HttpProtocol->Request(HttpProtocol, &RequestToken);
// TODO: Handle error...

Status = gRT->GetTime(&Baseline, NULL);
// TODO: Handle error...

// Optionally, wait for a certain amount of time before cancelling
// the request. In this case, we'll allow the network stack 10
// seconds to send the request successfully.
for (Timer = 0; !gRequestCallbackComplete && Timer < 10; ) {
    // Give the HTTP driver some motivation...
    HttpProtocol->Poll(HttpProtocol);
    // In practice, a call to GetTime() only fails when the total
    // elapsed time between the last call to to GetTime() is less
    // than the resolution of one tick (e.g. 1 second, depending
    // on capabilities of hardware). We only care to check the time
    // when the call succeeds.
    if (!EFI_ERROR(gRT->GetTime(&Current, NULL)) &&
        Current.Second != Baseline.Second)
    {
        // One second has passed, so update Current time and
        // increment the counter.
        Baseline = Current;
        ++Timer;
    }
// Cancel request if we did not get a notification from the HTTP
// driver in a timely manner.
if (!gRequestCallbackComplete) {
    Status = HttpProtocol->Cancel(HttpProtocol, &RequestToken);
    // TODO: Handle error and exit condition...
}
// Assuming we succeed in our request...
// This response message is different that request in that the
// HTTP driver is responsible for allocating the headers during
// a response instead of the caller.
ResponseData.StatusCode = HTTP_STATUS_UNSUPPORTED_STATUS;
ResponseMessage.Data.Response = &ResponseData;
// HeaderCount will be updated by the HTTP driver on response.
ResponseMessage.HeaderCount = 0;
// Headers will be populated by the driver on response.
ResponseMessage.Headers = NULL;
// BodyLength maximum limit is defined by the caller. On response,
// the HTTP driver will update BodyLength to the total number of
// bytes copied to Body. This number will never exceed the initial
// maximum provided by the caller.
ResponseMessage.BodyLength = BUFFER_SIZE;
ResponseMessage.Body = Buffer;
// Token format is similar to the token format in EFI TCP protocol.
ResponseToken.Event = NULL;
Status = gBS->CreateEvent(
    EVT_NOTIFY_SIGNAL,
    TPL_CALLBACK,
    NULL,
    &ResponseToken,
    &ResponseToken.Event
);
ResponseToken.Status = EFI_SUCCESS;
ResponseToken.Message = &ResponseMessage;
gResponseCallbackComplete = FALSE;
// Finally, make HTTP request.
Status = HttpProtocol->Response(HttpProtocol, &ResponseToken);
// TODO: Handle error...

Status = gRT->GetTime(&Baseline, NULL);
// TODO: Handle error...

// Optionally, wait for a certain amount of time before cancelling.
for (Timer = 0; !gResponseCallbackComplete && Timer < 10; ) {
    HttpProtocol->Poll(HttpProtocol);
    if (!EFI_ERROR(gRT->GetTime(&Current, NULL)) &&
        Current.Second != Baseline.Second)
    {
        // One second has passed, so update Current time and
// increment the counter.
Baseline = Current;
++Timer;
}
}

// Remove response token from queue if we did not get a notification
// from the remote host in a timely manner.
if (!gResponseCallbackComplete) {
    Status = HttpProtocol->Cancel(HttpProtocol, &ResponseToken);
    // TODO: Handle error and exit condition...
}

// Assuming we successfully received a response...
for (Index = 0; Index < ResponseMessage.HeaderCount; ++Index) {
    // We can parse the length of the file from the ContentLength header.
    if (!AsciiStriCmp(ResponseMessage.Headers[Index].FieldName, "Content-Length")) {
        ContentLength =
            AsciiStrDecimalToUintn(ResponseMessage.Headers[Index].FieldValue);
    }
}

ContentDownloaded = ResponseMessage.BodyLength;
// TODO:
// Downloaded data exists in Buffer[0..ResponseMessage.BodyLength].
// At this point, depending on business use case, the content can
// be written to a file, stored on the heap, etc.
while (ContentDownloaded < ContentLength) {
    // If we make it here, we haven't yet downloaded the whole file and
    // need to keep going.
    ResponseMessage.Data.Response = NULL;
    if (ResponseMessage.Headers != NULL) {
        // No sense hanging onto this anymore.
        FreePool(ResponseMessage.Headers);
    }
    ResponseMessage.HeaderCount = 0;
    ResponseMessage.BodyLength = BUFFER_SIZE;
    ZeroMem(Buffer, BUFFER_SIZE);

gResponseCallbackComplete = FALSE;
// The HTTP driver accepts a token where Data, Headers, and
// HeaderCount are all 0 or NULL. The driver will wait for a
// response from the last remote host which a transaction occurred
// and copy the response directly into Body, updating BodyLength
// with the total amount copied (downloaded).
Status = HttpProtocol->Response(HttpProtocol, &ResponseToken);
// TODO: Handle error...

Status = gRT->GetTime(&Baseline, NULL);
// TODO: Handle error...

// Optionally, wait for a certain amount of time before cancelling.
for (Timer = 0; !gResponseCallbackComplete && Timer < 10; ) {
    HttpProtocol->Poll(HttpProtocol);
    if (!EFI_ERROR(gRT->GetTime(&Current, NULL)) &&
        Current.Second != Baseline.Second)
    {
        // One second has passed, so update Current time and
        // increment the counter.
        Baseline = Current;
        ++Timer;
    }
}

// Remove response token from queue if we did not get a notification
// from the remote host in a timely manner.
if (!gResponseCallbackComplete) {
    Status = HttpProtocol->Cancel(HttpProtocol, &ResponseToken);
    // TODO: Handle error and exit condition...
}

// Assuming we successfully received a response...
ContentDownloaded += ResponseMessage.BodyLength;
// TODO:
// Downloaded data exists in Buffer[0..ResponseMessage.BodyLength].
// Append data to a file, heap memory, etc.

// Perform any necessary cleanup and handling of downloaded file
// assuming we succeeded at downloading the content. Depending on
// where the data was stored as per business need, that data can
// be consumed at this point. For example, if the data was stored
// to a file system, the file can be opened and consumed.
return EFI_SUCCESS;

29.6.10 HTTP Utilities Protocol

Summary
This section defines the EFI HTTP Utilities Protocol interface.
29.6.11 EFI_HTTP_UTILITIES_PROTOCOL

Protocol GUID

```
#define EFI_HTTP_UTILITIES_PROTOCOL_GUID \
{ 0x3E35C163, 0x4074, 0x45DD,\n  { 0x43, 0x1E, 0x23, 0x98, 0x9D, 0xD8, 0x6B, 0x32 }}
```

Protocol Interface Structure

```c
typedef struct _EFI_HTTP_UTILITIES_PROTOCOL {
  EFI_HTTP_UTILS_BUILD Build;
  EFI_HTTP_UTILS_PARSE Parse;
} EFI_HTTP_UTILITIES_PROTOCOL;
```

Parameters

Build
Create HTTP header based on a combination of seed header, fields to delete, and fields to append.

Parse
Parses HTTP header and produces an array of key/value pairs.

Description
The EFI HTTP utility protocol is designed to be used by EFI drivers and applications to parse HTTP headers from a byte stream. This driver is neither dependent on network connectivity, nor the existence of an underlying network infrastructure.

29.6.12 EFI_HTTP_UTILITIES_PROTOCOL.Build()

Summary
Provides ability to add, remove, or replace HTTP headers in a raw HTTP message.

EFI Protocol

```c
typedef EFI_STATUS
(EFIAPI *EFI_HTTP_UTILS_BUILD) (
  IN EFI_HTTP_UTILITIES_PROTOCOL *This,
  IN UINTN SeedMessageSize
  IN VOID *SeedMessage, OPTIONAL
  IN UINTN DeleteCount
  IN CHAR8 *DeleteList[], OPTIONAL
  IN UINTN AppendCount
  IN EFI_HTTP_HEADER *AppendList[], OPTIONAL
  OUT UINTN *NewMessageSize,
  OUT VOID **NewMessage,
);```

Parameters

This
Pointer to EFI_HTTP_UTILITIES_PROTOCOL instance.

SeedMessageSize
Size of the initial HTTP header. This can be zero.
SeedMessage

Initial HTTP header to be used as a base for building a new HTTP header. If NULL, SeedMessageSize is ignored.

DeleteCount

Number of null-terminated HTTP header field names in DeleteList.

DeleteList

List of null-terminated HTTP header field names to remove from SeedMessage. Only the field names are in this list because the field values are irrelevant to this operation.

AppendCount

Number of header fields in AppendList.

AppendList

List of HTTP headers to populate NewMessage with. If SeedMessage is not NULL, AppendList will be appended to the existing list from SeedMessage in NewMessage.

NewMessageSize

Pointer to number of header fields in NewMessage.

NewMessage

Pointer to a new list of HTTP headers based on

Description

The Build() function is used to manage the headers portion of an HTTP message by providing the ability to add, remove, or replace HTTP headers.

Status Codes Returned

<table>
<thead>
<tr>
<th>EFI_STATUS</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Add, remove, and replace operations succeeded.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate memory for NewMessage.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
</tbody>
</table>

29.6.13 EFI_HTTP_UTILITIES_PROTOCOL.Parse()

Summary

Parse HTTP header into array of key/value pairs.

EFI Protocol

typedef

EFI_STATUS

(EIFIAPI *EFI_HTTP_UTILS_PARSE) (   IN EFI_HTTP_PROTOCOL   *This,   IN CHAR8      *HttpMessage,   IN UINTN     HttpMessageSize,   OUT EFI_HTTP_HEADER **HeaderFields,   OUT UINTN    *FieldCount   );

Parameters
This
    Pointer to EFI_HTTP_UTILITIES_PROTOCOL instance.

HttpMessage
    Contains raw unformatted HTTP header string.

HttpMessageSize
    Size of HTTP header.

HeaderFields
    Array of key/value header pairs.

FieldCount
    Number of headers in HeaderFields.

Description
The Parse() function is used to transform data stored in HttpHeaders into a list of fields paired with their corresponding values.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Allocation succeeded</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI HTTP Protocol instance has not been initialized.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE</td>
</tr>
<tr>
<td></td>
<td>• This is NULL</td>
</tr>
<tr>
<td></td>
<td>• HttpMessage is NULL</td>
</tr>
<tr>
<td></td>
<td>• HeaderFields is NULL</td>
</tr>
<tr>
<td></td>
<td>• FieldCount is NULL</td>
</tr>
</tbody>
</table>

29.7 EFI REST Support Overview

EFI REST(EX) protocols are designed to support REST communication between EFI REST client applications/drivers and REST services. EFI REST client tool uses EFI REST(EX) protocols to send/receive resources to/from REST service to manage systems, configure systems or manipulate resources on REST service. Due to HTTP protocol is commonly used to communicate with REST service in practice, EFI REST(EX) protocols adopt HTTP as the message format to send and receive REST service resource.

EFI REST(EX) driver instance abstracts EFI REST client functionality and provides underlying interface to communicate with REST service. EFI REST(EX) driver instance knows how to communicate with REST service through certain interface after the corresponding configuration is initialized. EFI REST support provides two REST relevant protocols, one is EFI REST protocol which was introduced in UEFI spec 2.5 for providing light-weight EFI REST capability. Another one is EFI REST EX protocol, which is introduced in UEFI spec 2.8 for providing more interoperability between EFI REST client and REST service.

EFI REST and EFI REST EX protocols are not required to coexist on a platform, system integrator determines which EFI REST relevant protocol to be supported on system according to the platform demands. EFI REST support is to provide interoperability between EFI REST client and REST service. The authentication of accessing to REST service is not handled by EFI REST relevant protocols. Different REST service has its own authentication method. EFI REST client has to follow the specification defined by REST service for the authentication process.

Multiple EFI REST(EX) driver instances can be installed on a platform to communicate with different types of REST services or various underlying interfaces to REST services. REST service can be located on the platform locally, or off platform in the remote server. The system integrator can implement In-band EFI REST(EX) driver instance for the
Fig. 29.1: EFI REST Support, Single Protocol
on-platform REST service communications or Out-of-band EFI REST(EX) driver instance for the off-platform REST service communications.

Fig. 29.2: EFI REST Support, Multiple Protocols

29.7.1 EFI REST Support Scenario 1 (PlatformManagement)

The following figure represents a platform which has BMC on board, with the REST service deployed like Redfish service. The In-band EFI REST(EX) protocol (right one) is used by EFI REST client to manage this platform. This platform can also be managed in out of band like from the remote OS REST client. The left one is Out of band EFI REST(EX) protocol which communicate with other REST services like Redfish service in which the resource is belong to other platforms.
Fig. 29.3: EFI REST Support, BMC on Board
29.7.2 EFI REST Support Scenario 2 (PlatformManagement)

The following figure represents a platform which uses remote Redfish service for the platform management. If treats the resource in remote Redfish service as a part of this platform, the In-band EFI REST(EX) protocol could be implemented to communicate with remote Redfish service. This platform can also be managed in out of band from the remote OS REST client.

A variety of possible EFI REST(EX) protocol usages are delineated as below. The EFI REST(EX) driver instance could communicate with REST service through underlying interface like EFI network stack, platform specific interface to BMC or others. The working model of EFI REST support depends on the implementation of EFI REST(EX) driver instance and the design of platform.
29.7.3 EFI REST Protocol

This section defines the EFI REST Protocol interface.

29.7.3.1 EFI REST Protocol Definitions

29.7.4 EFI_REST_PROTOCOL

Protocol GUID

```c
#define EFI_REST_PROTOCOL_GUID \ 
{0x0DB48A36, 0x4E54, 0xEA9C,\ 
 { 0x9B, 0x09, 0x1E, 0xA5, 0xBE, 0x3A, 0x66, 0x0B }}
```

Protocol Interface Structure

```c
typedef struct _EFI_REST_PROTOCOL {
    EFI_REST_SEND_RECEIVE SendReceive;
    EFI_REST_GET_TIME GetServiceTime;
} EFI_REST_PROTOCOL;
```

Parameters

RestSendReceive

Provides an HTTP-like interface to send and receive resources from a REST service.

GetServiceTime

Returns the current time of the REST service.

Description
The EFI REST protocol is designed to be used by EFI drivers and applications to send and receive resources from a RESTful service. This protocol abstracts REST (Representational State Transfer) client functionality. This EFI protocol could be implemented to use an underlying EFI HTTP protocol, or it could rely on other interfaces that abstract HTTP access to the resources.

29.7.5 EFI_REST_PROTOCOL.SendReceive()

Summary

Provides a simple HTTP-like interface to send and receive resources from a REST service.

EFI Protocol

typedef
EFI_STATUS
(EFIAPI *EFI_REST_SEND_RECEIVE)(
    IN EFI_REST_PROTOCOL *This,
    IN EFI_HTTP_MESSAGE *RequestMessage,
    OUT EFI_HTTP_MESSAGE *ResponseMessage
);

Parameters

This
    Pointer to EFI_REST_PROTOCOL instance for a particular REST service.

RequestMessage
    Pointer to the REST request data for this resource

ResponseMessage
    Pointer to the REST response data obtained for this requested.

Description

The SendReceive() function sends a REST request to this REST service, and returns a REST response when the data is retrieved from the service. Both of the REST request and response messages are represented in format of EFI_HTTP_MESSAGE. RequestMessage contains the request to the REST resource identified by UrlRequestMessage->Data.Request->Url. The ResponseMessage is the returned response for that request, including the final HTTP status code, headers and the REST resource represented in the message body.

The memory buffers pointed by ResponseMessage->Data.Response, ResponseMessage->Headers and ResponseMessage->Body are allocated by this function, and it is the caller’s responsibility to free the buffer when the caller no longer requires the buffer’s contents.

It’s the REST protocol’s responsibility to handle HTTP layer details and return the REST resource to the caller, when this function is implemented by using an underlying EFI HTTP protocol. For example, if an HTTP interim response (Informational 1xx in HTTP 1.1) is received from server, the REST protocol should deal with it and keep waiting for the final response, instead of return the interim response to the caller. Same principle should be observed if the REST protocol relies on other interfaces.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>operation succeeded</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This, RequestMessage, or ResponseMessage are NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Receiving response message fail due to timeout.</td>
</tr>
</tbody>
</table>
29.7.6 EFI_REST_PROTOCOL.GetServiceTime()

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_REST_GET_TIME)(
    IN EFI_REST_PROTOCOL *This,
    OUT EFI_TIME *Time
);
```

**Parameters**

**This**

Pointer to `EFI_REST_PROTOCOL` instance.

**Time**

A pointer to storage to receive a snapshot of the current time of the REST service.

**Description**

The `GetServiceTime()` function is an optional interface to obtain the current time from this REST service instance. If this REST service does not support retrieving the time, this function returns `EFI_UNSUPPORTED`.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>operation succeeded</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>This</code> or <code>Time</code> are NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The RESTful service does not support returning the time</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred</td>
</tr>
</tbody>
</table>

29.7.7 EFI REST EX Protocol

This section defines the EFI REST EX Protocol interfaces. It is split into the following two main sections:

- REST EX Service Binding Protocol (RESTEXSB)
- REST EX Protocol (REST EX)

29.7.7.1 REST EX Service Binding Protocol

29.7.8 EFI_REST_EX_SERVICE_BINDING_PROTOCOL

**Summary**

The RESTEXSB is used to locate the REST services those are supported by a REST EX driver instances and to create and destroy instances of REST EX child protocol driver.

The EFI Service Binding Protocol in `EFI Service Binding Protocol` defines the generic Service Binding Protocol functions. This section discusses the details that are specific to the REST EX.

**GUID**

```c
#define EFI_REST_EX_SERVICE_BINDING_PROTOCOL_GUID \
{0x456bbe01, 0x99d0, 0x45ea, \ 
{0xbb, 0x5f, 0x16, 0xd8, 0x4b, 0xed, 0xc5, 0x59}}
```
Description

A REST service client application (or driver) that communicates to REST service can use one of protocol handler services, such as BS->LocateHandleBuffer(), to search for devices that publish a RESTEXSB GUID. Each device with a published RESTEXSB GUID supports REST EX Service Binding Protocol and may be available for use.

After a successful call to the EFI_REST_EX_SERVICE_BINDING_PROTOCOL.CreateChild() function, the child REST EX driver is in the unconfigured state. It is not ready to communicate with REST service at this moment. The child instance is ready to use to communicate with REST service after the successful Configure() is invoked. For EFI REST drivers which don’t require additional configuration process, Configure() is unnecessary to be invoked before using its child instance. This depends on EFI REST EX driver specific implementation.

Before a REST service client application terminates execution, every successful call to the EFI_REST_EX_SERVICE_BINDING_PROTOCOL.CreateChild() function must be matched with a call to the EFI_REST_EX_SERVICE_BINDING_PROTOCOL.DestroyChild() function.

29.7.8.1 REST EX Protocol Specific Definitions

29.7.9 EFI_REST_EX_PROTOCOL

Protocol GUID

#define EFI_REST_EX_PROTOCOL_GUID \
 {0x55648b91, 0xe7d, 0x40a3, \
 {0xa9, 0xb3, 0xa8, 0x15, 0xd7, 0xea, 0xdf, 0x97}}

Protocol Interface Structure

typedef struct _EFI_REST_EX_PROTOCOL {
    EFI_REST_SEND_RECEIVE SendReceive;
    EFI_REST_GET_TIME GetServiceTime;
    EFI_REST_EX_GET_SERVICE GetService;
    EFI_REST_EX_GET_MODE_DATA GetModeData;
    EFI_REST_EX_CONFIGURE Configure;
    EFI_REST_EX_ASYNC_SEND_RECEIVE AsyncSendReceive;
    EFI_REST_EX_EVENT_SERVICE EventService;
} EFI_REST_EX_PROTOCOL;

Parameters

SendReceive

Provides an HTTP-like interface to send and receive resources from a REST service. The functionality of this function is same as EFI_REST_PROTOCOL.SendReceive(). Refer to section EFI REST Protocol Definitions for more details.

GetServiceTime

Returns the current time of the REST service. The functionality of this function is same as EFI_REST_PROTOCOL.GetServiceTime(). Refer to 29.7.1.1 for the details.

GetService

This function returns the type and location of REST service.

GetModeData

This function returns operational configuration of current EFI REST EX child instance.

Configure

This function is used to configure EFI REST EX child instance.
AsyncSendReceive

Provides an HTTP-like interface to send and receive resources. The resource returned from REST service is sent to client asynchronously.

EventService

Provides an interface to subscribe event of specific resource changes on REST service.

Description

The REST EX protocol is designed to use by REST service client applications or drivers to communicate with REST service. REST EX protocol enhances the REST protocol and provides comprehensive interfaces to REST service clients. Akin to REST protocol, REST EX driver instance uses HTTP message for the REST request and response. However, the underlying mechanism of REST EX is not necessary to be HTTP-aware. The underlying mechanism could be any protocols according to the REST service mechanism respectively. REST EX protocol could be used to communicate with In-band or Out-of-band REST service depends on the platform-specific implementation.

29.7.10 EFI_REST_EX_PROTOCOL.SendReceive()

Summary

Provides a simple HTTP-like interface to send and receive resources from a REST service.

EFI Protocol

```c
typedef EFI_STATUS
  (EFIAPI *EFI_REST_SEND_RECEIVE)(
     IN EFI_REST_EX_PROTOCOL *This,
     IN EFI_HTTP_MESSAGE *RequestMessage,
     OUT EFI_HTTP_MESSAGE *ResponseMessage
  );
```

Parameters

Refer to `EFI REST Protocol Definitions` for the details.

Description

Refer to `EFI REST Protocol Definitions` for the details.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>operation succeeded</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This, RequestMessage, or ResponseMessage are NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROT</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The configuration of this instance is not set yet. Configure() must be executed and returns successfully prior to invoke this function.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Receiving response message fail due to timeout.</td>
</tr>
</tbody>
</table>
29.7.11 EFI_REST_EX_PROTOCOL.GetService()

Summary
This function returns the information of REST service provided by this EFI REST EX driver instance.

Protocol Interface

typedef
EFI_STATUS
(EFI_API *EFI_REST_EX_GET_SERVICE)(
    IN EFI_REST_EX_PROTOCOL *This,
    OUT EFI_REST_EX_SERVICE_INFO **RestExServiceInfo
);

Parameters

This
This is the EFI_REST_EX_PROTOCOL instance.

RestExServiceInfo
Pointer to receive a pointer to EFI_REST_EX_SERVICE_INFO structure. The format of
EFI_REST_EX_SERVICE_INFO is version controlled for the future extension. The version of
EFI_REST_EX_SERVICE_INFO structure is returned in the header within this structure. EFI REST
client refers to the correct format of structure according to the version number. The pointer to
EFI_REST_EX_SERVICE_INFO is a memory block allocated by EFI REST EX driver instance. That is
caller’s responsibility to free this memory when this structure is no longer needed. Refer to Related Definitions
below for the definitions of EFI_REST_EX_SERVICE_INFO structure.

Description
This function returns the information of REST service provided by this REST EX driver instance. The information such
as the type of REST service and the access mode of REST EX driver instance (In-band or Out-of-band) are described
in EFI_REST_EX_SERVICE_INFO structure. For the vendor-specific REST service, vendor-specific REST service
information is returned in VendorSpecificData. Besides the REST service information provided by REST EX driver
instance, EFI_DEVICE_PATH_PROTOCOL of the REST service is also provided on the handle of REST EX driver
instance.

EFI REST client can get the information of REST service from REST service EFI device path node in
EFI_DEVICE_PATH_PROTOCOL. EFI_DEVICE_PATH_PROTOCOL which installed on REST EX driver instance
indicates where the REST service is located, such as BMC Device Path, IPv4, IPv6 or others. Refer to REST Service
Device Path for details of the REST service device path node, which is the sub-type (Sub-type = 32) of Messaging
Device Path (type 3).

REST EX driver designer is well know what REST service this REST EX driver instance intends to communicate
with. The designer also well know this driver instance is used to talk to BMC through specific platform mechanism or
talk to REST server through UEFI HTTP protocol. REST EX driver is responsible to fill up the correct information
in EFI_REST_EX_SERVICE_INFO. EFI_REST_EX_SERVICE_INFO is referred by EFI REST clients to pickup the
proper EFI REST EX driver instance to get and set resource. GetService() is a basic and mandatory function which
must be able to use even Configure() is not invoked in previously.

Related Definitions

//**********************************************************************************************
//EFI_REST_EX_SERVICE_INFO_HEADER
//**********************************************************************************************

(continues on next page)
typedef struct {
    UINT32 Length;
    EFI_REST_EX_SERVICE_INFO_VER RestServiceInfoVer;
} EFI_REST_EXSERVICE_INFO_HEADER;

Length
The length of entire EFI_REST_EX_SERVICE_INFO structure. Header size is included.

RestServiceInfoVer
The version of this EFI_REST_SERVICE_INFO structure. See below definitions of EFI_REST_EX_SERVICE_INFO_VER.

typedef struct {
    UINT8 Major;
    UINT8 Minor;
} EFI_REST_EXSERVICE_INFO_VER;

Major
The major version of EFI_REST_EX_SERVICE_INFO.

Minor
The minor version of EFI_REST_EX_SERVICE_INFO.

EFI_REST_EX_SERVICE_INFO is version controlled for the future extensions. Any new information added to this structure requires version increased. EFI REST EX driver instance must provides the correct version of structure in EFI_REST_EX_SERVICE_INFO_VER when it returnsEFI_REST_EX_SERVICE_INFO to caller.
EfiRestExServiceInfoHeader
The header of EFI_REST_EX_SERVICE_INFO.

RestExServiceType
The REST service type. See below definition.

RestServiceAccessMode
The access mode of REST service. See below definition.

VendorRestServiceName
The name of vendor-specific REST service. This field is only valid if RestExServiceType is EFI_REST_EX_SERVICE_VENDOR_SPECIFIC.

VendorSpecificDataLength
The length of vendor-specific REST service information. This field is only valid if RestExServiceType is EFI_REST_EX_SERVICE_VENDOR_SPECIFIC.

VendorSpecificData
A pointer to vendor-specific REST service information. This field is only valid if RestExServiceType is EFI_REST_EX_SERVICE_VENDOR_SPECIFIC. The memory buffer pointed by VendorSpecificData is allocated by EFI REST EX driver instance and must be freed by EFI REST client when it is no longer need.

RestExConfigType
The type of configuration of REST EX driver instance. See GetModeData() and Configure() for the details.

RestExConfigDataLength
The length of REST EX configuration data.

EFI_REST_EX_CONFIG_TYPE
typedef enum {
  EFI_REST_EX_CONFIG_TYPE_UNSPECIFIC = 1,
  EFI_REST_EX_CONFIG_TYPE_REDFISH,
  EFI_REST_EX_CONFIG_TYPE_ODATA,
  EFI_REST_EX_CONFIG_TYPE_VENDOR_SPECIFIC = 0xff,
  EFI_REST_EX_CONFIG_TYPE_MAX
} EFI_REST_EX_CONFIG_TYPE;

EFI_REST_EX_CONFIG_TYPE_UNSPECIFIC indicates this EFI REST EX driver instance is not used to communicate with any particular REST service. The EFI REST EX driver instance which reports this service type is REST service independent and only provides SendReceive() function to EFI REST client. EFI REST client uses this function to send and receive HTTP message to any target URI and handles the follow up actions by itself. The EFI REST EX driver instance in this type must returns EFI_UNSUPPORTED in below REST EX protocol interfaces, GetServiceTime(), AsyncSendReceive() and EventService().

EFI_REST_EX_CONFIG_TYPE_REDFISH indicates this EFI REST EX driver instance is used to communicate with Redfish REST service.

EFI_REST_EX_CONFIG_TYPE_ODATA indicates this EFI REST EX driver instance is used to communicate with Odata REST service.

EFI_REST_EX_CONFIG_TYPE_VENDOR_SPECIFIC indicates this EFI REST EX driver instance is used to communicate with vendor-specific REST service.

29.7. EFI REST Support Overview
// *******************************************************
// EFI_REST_EX_SERVICE_ACCESS_MODE
// *******************************************************
typedef enum {
    EFI_REST_EX_SERVICE_IN_BAND_ACCESS = 1,
    EFI_REST_EX_SERVICE_OUT_OF_BAND_ACCESS = 2,
    EFI_REST_EX_SERVICE_ACCESS_MODE_MAX
} EFI_REST_EX_SERVICE_ACCESS_MODE;

EFI_REST_EX_SERVICE_IN_BAND_ACCESS mode indicates the REST service is invoked in In-band mechanism in the scope of platform. In most of cases, the In-band mechanism is used to communicate with REST service on platform through some particular devices like BMC, Embedded Controller and other infrastructures built on the platform.

EFI_REST_EX_SERVICE_OUT_OF_BAND_ACCESS mode indicates the REST service is invoked in Out-of-band mechanism. The REST service is located out of platform scope. In most of cases, the Out-of-band mechanism is used to communicate with REST service on other platforms through network or other protocols.

// *******************************************************
// EFI_REST_EX_CONFIG_TYPE
// *******************************************************
typedef enum {
    EFI_REST_EX_CONFIG_TYPE_HTTP,
    EFI_REST_EX_CONFIG_TYPE_UNSPECIFIC,
    EFI_REST_EX_CONFIG_TYPE_MAX
} EFI_REST_EX_CONFIG_TYPE;

EFI_REST_EX_CONFIG_TYPE_HTTP indicates the format of the REST EX configuration is EFI_REST_EX_HTTP_CONFIG_DATA. RestExConfigDataLength of this type is the size of EFI_REST_EX_HTTP_CONFIG_DATA. This configuration type is used for the HTTP-aware EFI REST EX driver instance.

// EFI_REST_EX_HTTP_CONFIG_DATA
typedef struct {
    EFI_HTTP_CONFIG_DATA HttpConfigData;
    UINT32 SendReceiveTimeout;
} EFI_REST_EX_HTTP_CONFIG_DATA;

HttpConfigData
Parameters to configure the HTTP child instance.

SendReceiveTimeout
Time out (in milliseconds) when blocking for response after send out request message in EFI_REST_EX_PROTOCOL.SendReceive().

EFI_REST_EX_CONFIG_TYPE_UNSPECIFIC indicates the format of REST EX configuration is unspecific. RestExConfigDataLength of this type depends on the implementation of non HTTP-aware EFI REST EX driver instance such as BMC EFI REST EX driver instance. The format of configuration for this type refers to the system/platform spec which is out of UEFI scope.

Status Codes Returned

EFI_SUCCESS   EFI_REST_EX_SERVICE_INFO is returned in RestExServiceInfo.
continues on next page
29.7.12 EFI_REST_EX_PROTOCOL.GetModeData()

Summary
This function returns operational configuration of current EFI REST EX child instance.

Protocol Interface

```c
typedef EFI_STATUS
  (EFIAPI *EFI_REST_EX_GET_MODE_DATA)(
    IN EFI_REST_EX_PROTOCOL *This,
    OUT EFI_REST_EX_CONFIG_DATA *RestExConfigData
  );
```

Parameters

This
This is the EFI_REST_EX_PROTOCOL instance.

RestExConfigData
Pointer to receive a pointer to EFI_REST_EX_CONFIG_DATA. The memory allocated for configuration data should be freed by caller. See Related Definitions for the details.

Description

This function returns the current configuration of EFI REST EX child instance. The format of operational configuration depends on the implementation of EFI REST EX driver instance. For example, HTTP-aware EFI REST EX driver instance uses EFI HTTP protocol as the underlying protocol to communicate with the REST service. In this case, the type of configuration EFI_REST_EX_CONFIG_TYPE_HTTP is returned from GetService(). EFI_REST_EX_HTTP_CONFIG_DATA is used as EFI REST EX configuration format and returned to the EFI REST client. For those non HTTP-aware REST EX driver instances, the type of configuration EFI_REST_EX_CONFIG_TYPE_UNSPECIFIC is returned from GetService(). In this case, the format of returning data could be non-standard. Instead, the format of configuration data is a system/platform specific definition such as a BMC mechanism used in EFI REST EX driver instance. EFI REST client and EFI REST EX driver instance have to refer to the specific system /platform spec which is out of UEFI scope.

Related Definitions

```c
//******************************************************************************
//EFI_REST_EX_CONFIG_DATA
//******************************************************************************
typedef UINT8 *EFI_REST_EX_CONFIG_DATA;
```

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>EFI_REST_EX_SERVICE_INFO is returned in RestExServiceInfo.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This function is not supported in this REST EX Protocol driver instance.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The configuration of this instance is not set yet. Configure() must be exe-</td>
</tr>
<tr>
<td></td>
<td>cuted and return successfully prior to invoke this function.</td>
</tr>
</tbody>
</table>
29.7.13 EFI_REST_EX_PROTOCOL.Configure()

Summary
This function is used to configure EFI REST EX child instance.

Protocol Interface

typedef EFI_STATUS (EFIAPI *EFI_REST_EX_CONFIGURE)(
  IN EFI_REST_EX_PROTOCOL *This,
  IN EFI_REST_EX_CONFIG_DATA RestExConfigData
);

Parameters

This
This is the EFI_REST_EX_PROTOCOL instance.

RestExConfigData
Pointer to EFI_REST_EX_CONFIG_DATA. See Related Definitions in GetModeData() protocol interface.

Description
This function is used to configure the setting of underlying protocol of REST EX child instance. The type of configuration is according to the implementation of EFI REST EX driver instance. For example, HTTP-aware EFI REST EX driver instance uses EFI HTTP protocol as the underlying protocol to communicate with REST service. The type of configuration is EFI_REST_EX_CONFIG_TYPE_HTTP and RestExConfigData is in the format of EFI_REST_EX_HTTP_CONFIG_DATA.

Akin to HTTP configuration, REST EX child instance can be configure to use different HTTP local access point for the data transmission. Multiple REST clients may use different configuration of HTTP to distinguish themselves, such as to use the different TCP port. For those non HTTP-aware REST EX driver instance, the type of configuration is EFI_REST_EX_CONFIG_TYPE_UNSPECIFIC. RestExConfigData refers to the non industrial standard. Instead, the format of configuration data is system/platform specific definition such as BMC. In this case, EFI REST client and EFI REST EX driver instance have to refer to the specific system/platform spec which is out of the UEFI scope. Besides GetService() function, no other EFI REST EX functions can be executed by this instance until Configure() is executed and returns successfully. All other functions must returns EFI_NOT_READY if this instance is not configured yet. Set RestExConfigData to NULL means to put EFI REST EX child instance into the unconfigured state.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>EFI_REST_EX_CONFIG_DATA is set in successfully.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Configuration for this REST EX child instance is failed with the given EFI_REST_EX_CONFIG_DATA</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This function is not supported in this REST EX Protocol driver instance.</td>
</tr>
</tbody>
</table>

Usage Example
Below illustrations show the usage cases of using different EFI REST EX child instances to communicate with REST service.
In the above case, EFI REST Client A and B use HTTP-aware EFI REST EX driver instance to get and send resource. These two EFI REST clients configure the child instance with specific TCP port. Therefore the data transmission through HTTP can delivered to the proper EFI REST clients.

In the above case, EFI REST Client A creates two EFI REST EX child instances and configures those child instances to connect to two BMCs respectively.

### 29.7.14 EFI_REST_EX_PROTOCOL.AsyncSendReceive()

**Summary**

This function sends REST request to REST service and signal caller’s event asynchronously when the final response is received by REST EX Protocol driver instance. The essential design of this function is to handle asynchronous send/receive implicitly according to REST service asynchronous request mechanism. Caller will get the notification once the final response is returned from the REST service.

**Protocol Interface**

```c
typedef
EFI_STATUS
(EFIAPIC *EFI_REST_EX_ASYNC_SEND_RECEIVE)(
    IN EFI_REST_EX_PROTOCOL *This,
    IN EFI_HTTP_MESSAGE *RequestMessage OPTIONAL,
    IN EFI_REST_EX_TOKEN *RestExToken,

(continues on next page)
```
Parameters

This

This is the `EFI_REST_EX_PROTOCOL` instance.

RequestMessage

This is the REST request message sent to the REST service. Set `RequestMessage` to `NULL` to cancel the previous asynchronous request associated with the corresponding `RestExToken`. See descriptions for the details.

RestExToken

REST EX token which REST EX Protocol instance uses to notify REST client the status of response of asynchronous REST request. See related definition of `EFI_REST_EX_TOKEN`.

TimeOutInMilliSeconds

The pointer to the timeout in milliseconds which REST EX Protocol driver instance refers as the duration to drop asynchronous REST request. `NULL` pointer means no timeout for this REST request. REST EX Protocol driver signals caller’s event with `EFI_STATUS` set to `EFI_TIMEOUT` in `RestExToken` if REST EX Protocol can’t get the response from REST service within `TimeOutInMilliSeconds`.

Description

This function is used to send REST request with asynchronous REST service response within certain timeout declared. REST service sometime takes long time to create resource. Sometimes REST service returns response to REST client late because of the shortage of bandwidth or bad network quality. To prevent from unfriendly user experience due to system stuck while waiting for the response from REST service, `EFI_REST_EX_PROTOCOL.AsyncSendReceive()` provides the capability to send asynchronous REST request. Caller sends the REST request and still can execute some other processes on background while waiting the event signaled by REST EX Protocol driver instance.

The implementation of underlying mechanism of asynchronous REST request depends on the mechanism of REST service. HTTP protocol, In-Band management protocol and other protocols has its own way to support asynchronous REST request. Similar to `EFI_REST_EX_PROTOCOL.SendReceive()`, it’s the REST EX protocol’s responsibility to handle the implementation details and return only the REST resource to the caller. REST EX Protocol driver instance which doesn’t support asynchronous REST request can just return `EFI_UNSUPPORTED` to caller. Also, this function must returns `EFI_UNSUPPORTED` if `EFI_REST_EX_SERVICE_TYPE` returned in `EFI_REST_EX_SERVICE_INFO` from `GetService()` is `EFI_REST_EX_SERVICE_UNSPECIFIC`.

REST clients do not have to know the preprocessors of asynchronous REST request between REST EX Protocol driver instance and REST service. The responsibility of REST EX Protocol driver instance is to monitor the status of resource readiness and to signal caller’s `RestExToken` when the status of returning resource is ready. REST EX Protocol driver instance sets `Status` field in `RestExToken` to `EFI_SUCCESS` and sets `ResponseMessage` pointer to the final response from REST service. Then signal caller’s event to notify REST client the desired REST resource is received. REST EX Protocol driver instance also has to create an EFI timer to handle the timeout situation. REST EX Protocol driver must drops the asynchronous REST request once the timeout is expired. In this case, REST EX Protocol driver instance sets `Status` field in `RestExToken` to `EFI_TIMEOUT` and signal caller’s event token.

REST EX Protocol driver instance must have capability to cancel the in process asynchronous REST request when caller asks to terminate specific asynchronous REST request. REST EX Protocol driver instance may not have capability to force REST service to cancel the specific request, however, REST EX Protocol driver instance at least can clean up its own internal resource of asynchronous REST request. Caller has to set `RequestMessage` to `NULL` with `RestExToken` set to `EFI_REST_EX_TOKEN` which was successfully sent to this function previously. REST EX Protocol driver instance finds the given `EFI_REST_EX_TOKEN` from its private database and clean up the associated resource if `EFI_REST_EX_TOKEN` is an in process asynchronous REST request. REST EX Protocol driver instance then sets `Status` field in `RestExToken` to `EFI_ABORT` and signal caller’s event to indicate the asynchronous REST request has been canceled.

---

**Plain Text Representation**

| IN UINTN *TimeOutInMilliSeconds OPTIONAL |

**Parameters**

**This**

This is the `EFI_REST_EX_PROTOCOL` instance.

**RequestMessage**

This is the REST request message sent to the REST service. Set `RequestMessage` to `NULL` to cancel the previous asynchronous request associated with the corresponding `RestExToken`. See descriptions for the details.

**RestExToken**

REST EX token which REST EX Protocol instance uses to notify REST client the status of response of asynchronous REST request. See related definition of `EFI_REST_EX_TOKEN`.

**TimeOutInMilliSeconds**

The pointer to the timeout in milliseconds which REST EX Protocol driver instance refers as the duration to drop asynchronous REST request. `NULL` pointer means no timeout for this REST request. REST EX Protocol driver signals caller’s event with `EFI_STATUS` set to `EFI_TIMEOUT` in `RestExToken` if REST EX Protocol can’t get the response from REST service within `TimeOutInMilliSeconds`.

**Description**

This function is used to send REST request with asynchronous REST service response within certain timeout declared. REST service sometime takes long time to create resource. Sometimes REST service returns response to REST client late because of the shortage of bandwidth or bad network quality. To prevent from unfriendly user experience due to system stuck while waiting for the response from REST service, `EFI_REST_EX_PROTOCOL.AsyncSendReceive()` provides the capability to send asynchronous REST request. Caller sends the REST request and still can execute some other processes on background while waiting the event signaled by REST EX Protocol driver instance.

The implementation of underlying mechanism of asynchronous REST request depends on the mechanism of REST service. HTTP protocol, In-Band management protocol and other protocols has its own way to support asynchronous REST request. Similar to `EFI_REST_EX_PROTOCOL.SendReceive()`, it’s the REST EX protocol’s responsibility to handle the implementation details and return only the REST resource to the caller. REST EX Protocol driver instance which doesn’t support asynchronous REST request can just return `EFI_UNSUPPORTED` to caller. Also, this function must returns `EFI_UNSUPPORTED` if `EFI_REST_EX_SERVICE_TYPE` returned in `EFI_REST_EX_SERVICE_INFO` from `GetService()` is `EFI_REST_EX_SERVICE_UNSPECIFIC`.

REST clients do not have to know the preprocessors of asynchronous REST request between REST EX Protocol driver instance and REST service. The responsibility of REST EX Protocol driver instance is to monitor the status of resource readiness and to signal caller’s `RestExToken` when the status of returning resource is ready. REST EX Protocol driver instance sets `Status` field in `RestExToken` to `EFI_SUCCESS` and sets `ResponseMessage` pointer to the final response from REST service. Then signal caller’s event to notify REST client the desired REST resource is received. REST EX Protocol driver instance also has to create an EFI timer to handle the timeout situation. REST EX Protocol driver must drops the asynchronous REST request once the timeout is expired. In this case, REST EX Protocol driver instance sets `Status` field in `RestExToken` to `EFI_TIMEOUT` and signal caller’s event token.

REST EX Protocol driver instance must have capability to cancel the in process asynchronous REST request when caller asks to terminate specific asynchronous REST request. REST EX Protocol driver instance may not have capability to force REST service to cancel the specific request, however, REST EX Protocol driver instance at least can clean up its own internal resource of asynchronous REST request. Caller has to set `RequestMessage` to `NULL` with `RestExToken` set to `EFI_REST_EX_TOKEN` which was successfully sent to this function previously. REST EX Protocol driver instance finds the given `EFI_REST_EX_TOKEN` from its private database and clean up the associated resource if `EFI_REST_EX_TOKEN` is an in process asynchronous REST request. REST EX Protocol driver instance then sets `Status` field in `RestExToken` to `EFI_ABORT` and signal caller’s event to indicate the asynchronous REST request has been canceled.
REST EX Protocol driver instance maintains the internal property, state machine, status of transfer of each asynchronous REST request. REST EX Protocol driver instance has to clean up the internal resource associated with each asynchronous REST request no matter the transfer is ended with success or fail.

There are two phases of asynchronous REST request. One is the preprocessor of establishing asynchronous REST request between REST EX Protocol driver instance and REST service. Another phase is to retrieve the final response from REST service and send to REST client.

**Related Definitions**

```c
typedef struct {
  EFI_EVENT Event;
  EFI_STATUS Status;
  EFI_HTTP_MESSAGE *ResponseMessage;
} EFI_REST_EX_TOKEN;
```

**Event**

This event will be signaled after the Status field is updated by the EFI REST EX Protocol driver instance. The type of Event must be `EFI_NOTIFY_SIGNAL`. The Task Priority Level (TPL) of Event must be lower than or equal to `TPL_CALLBACK`, which allows other events to be notified.

**Status**

`Status` will be set to one of the following values if the REST EX Protocol driver instance gets the response from the REST service successfully, or if an unexpected error occurs:

- **`EFI_SUCCESS`**: The resource gets a response from REST service successfully. `ResponseMessage` points to the response in HTTP message structure.
- **`EFI_ABORTED`**: The asynchronous REST request was canceled by the caller.
- **`EFI_TIMEOUT`**: The asynchronous REST request timed out before receiving a response from the REST service.
- **`EFI_DEVICE_ERROR`**: An unexpected error occurred.

**ResponseMessage**

The REST response message pointed to by this pointer is only valid when `Status` is `EFI_SUCCESS`. The memory buffers pointed to by `ResponseMessage`, `ResponseMessage->Data.Response`, `ResponseMessage->Headers` and `ResponseMessage->Body` are allocated by the EFI REST EX driver instance, and it is the caller’s responsibility to free the buffer when the caller no longer requires the buffer’s contents.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>Asynchronous REST request is established.</td>
</tr>
<tr>
<td><code>EFI_UNSUPPORTED</code></td>
<td>This REST EX Protocol driver instance doesn’t support asynchronous request.</td>
</tr>
<tr>
<td><code>EFI_TIMEOUT</code></td>
<td>Asynchronous REST request is not established and timeout is expired.</td>
</tr>
<tr>
<td><code>EFI_ABORT</code></td>
<td>Previous asynchronous REST request has been canceled.</td>
</tr>
<tr>
<td><code>EFI_DEVICE_ERROR</code></td>
<td>Otherwise, returns <code>EFI_DEVICE_ERROR</code> for other errors according to HTTP Status Code.</td>
</tr>
<tr>
<td><code>EFI_NOT_READY</code></td>
<td>The configuration of this instance is not set yet. <code>Configure()</code> must be executed and returns successfully prior to invoke this function.</td>
</tr>
</tbody>
</table>
29.7.15 EFI_REST_EX_PROTOCOL.EventService()

Summary

This function sends REST request to a REST Event service and signals caller’s event token asynchronously when the URI resource change event is received by REST EX Protocol driver instance. The essential design of this function is to monitor event implicitly according to REST service event service mechanism. Caller will get the notification if certain resource is changed.

EFI Protocol

typedef
EFI_STATUS
(EFIAPI *EFI_REST_EX_EVENT_SERVICE)(
    IN EFI_REST_EX_PROTOCOL *This,
    IN EFI_HTTP_MESSAGE *RequestMessage OPTIONAL,
    IN EFI_REST_EX_TOKEN *RestExToken)
);

Parameters

This
This is the EFI_REST_EX_PROTOCOL instance.

RequestMessage
This is the HTTP request message sent to REST service. Set RequestMessage to NULL to cancel the previous event service associated with the corresponding RestExToken. See descriptions for the details.

RestExToken
REST EX token which REST EX Protocol driver instance uses to notify REST client the URI resource which monitored by REST client has been changed. See the related definition of EFI_REST_EX_TOKEN in EFI_REST_EX_PROTOCOL.AsyncSendReceive().

Description

This function is used to subscribe an event through REST Event service if REST service supports event service. This function listens on resource change of specific REST URI resource. The type of URI resource change event is varied and REST service specific, such as URI resource updated, resource added, resource removed, alert, etc. The way to subscribe REST Event service is also REST service specific, usually described in HTTP body. With the implementation of EFI_REST_EX_PROTOCOL.EventService(), REST client can register an REST EX token of particular URI resource change, usually of a time critical nature, until subscription is deleted from REST Event service.

The implementation of underlying mechanism of REST Event service depends on the interface of REST EX Protocol driver instance. HTTP protocol, In-Band management protocols or other protocols can have its own implementation to support REST Event Service request. REST EX Protocol driver instance has knowledge of how to handle the REST Event service. The REST client creates and submits an HTTP-like header/body content in RequestMessage which required by REST Event services. How does REST EX Protocol driver instance handle REST Event service and monitor event is REST service-specific. REST EX driver instance can just returns EFI_UNSUPPORTED if REST service has no event capability. Also, this function must returns EFI_UNSUPPORTED if EFI_REST_EX_SERVICE_TYPE returned in EFI_REST_EX_PROTOCOL.AsyncSendReceive() is EFI_REST_EX_SERVICE_UNSPECIFIC.

The REST EX Protocol driver instance is responsible to monitor the resource change event pushed from REST service. REST EX Protocol driver instance signals caller’s RestExToken when the event of resource change is pushed to REST EX Protocol driver instance. The way how REST service pushes event to REST EX Protocol driver instance is implementation-specific and transparent to REST client. REST EX Protocol driver instance sets Status field in RestExToken to EFI_SUCCESS and sets ResponseMessage pointer to the event resource returned from REST Event service. Then REST EX Protocol driver instance signals caller’s event to notify REST client a new REST event is received. REST EX Protocol driver instance also responsible to terminate event subscription and clear up the internal resource associated with REST Event service if the status of subscription resource is returned error.
REST EX Protocol driver instance must has capability to remove event subscription created by REST client. Caller has to set RequestMessage to NULL with RestExToken set to EFI_REST_EX_TOKEN which was successfully sent to this function previously. REST EX Protocol driver instance finds the given EFI_REST_EX_TOKEN from its private database and delete the associated event from REST service.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Asynchronous REST request is established.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This REST EX Protocol driver instance doesn’t support asynchronous request.</td>
</tr>
<tr>
<td>EFI_ABORT</td>
<td>Previous asynchronous REST request has been canceled or event subscription has been delete from service</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Otherwise, returns EFI_DEVICE_ERROR for other errors according to HTTP Status Code.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The configuration of this instance is not set yet. Configure() must be executed and returns successfully prior to invoke this function.</td>
</tr>
</tbody>
</table>

**29.7.15.1 Usage Example (HTTP-aware REST EX Protocol DriverInstance)**

The following code example shows how a consumer of REST EX driver would use EFI REST EX ServiceBinding Protocol and EFI REST EX Protocol to send and receive the resources from a REST service.

```c
EFI_HANDLE ImageHandle;
EFI_HANDLE *HandleBuffer;
UINTN HandleNum;
UINTN Index;
EFI_REST_EX_SERVICE_BINDING_PROTOCOL *RestExService;
EFI_HANDLE RestExChild;
EFI_REST_EX_PROTOCOL *RestEx;
EFI_REST_EX_SERVICE_INFO *RestExServiceInfo;
EFI_REST_EX_CONFIG_DATA RestExConfigData;
EFI_HTTP_MESSAGE RequestMessage;
EFI_HTTP_MESSAGE ResponseMessage;

// Locate all the handles with RESTEX ServiceBinding Protocol.
//
Status = gBS->LocateHandleBuffer (  
    ByProtocol,  
    &gEfiRestExServiceBindingProtocolGuid,  
    NULL,  
    &HandleNum,  
    &HandleBuffer  
);  
if (EFI_ERROR (Status) || (HandleNum == 0)) {  
    return EFI_ABORTED;  
}

for (Index = 0; Index < HandleNum; Index++) {  
    // Get the RESTEX ServiceBinding Protocol  
    //
    // (continues on next page)
```
Status = gBS->OpenProtocol (HandleBuffer[Index],
&gEfiRestExServiceBindingProtocolGuid,
(VOID **) &RestExService,
ImageHandle,
NULL,
EFI_OPEN_PROTOCOL_GET_PROTOCOL);
if (EFI_ERROR (Status)) {
    return Status;
}

// Create the corresponding REST EX child
// Status = RestExService->CreateChild (RestExService, &RestExChild);
if (EFI_ERROR (Status)) {
    return Status;
}

// Retrieve the REST EX Protocol from child handle
// Status = gBS->OpenProtocol (RestExChild,
// &gEfiRestExProtocolGuid,
// (VOID **) &RestEx,
// ImageHandle,
// NULL,
// EFI_OPEN_PROTOCOL_GET_PROTOCOL);
if (EFI_ERROR (Status)) {
    goto ON_EXIT;
}

// Get the information of REST service provided by this EFI REST EX driver
// Status = RestEx->GetService (RestEx,
// &RestExServiceInfo);
if (EFI_ERROR (Status)) {
    goto ON_EXIT;
}

// Check whether this REST EX service is preferred by consumer:
// 1. RestServiceAccessMode is EFI_REST_EX_SERVICE_OUT_OF_BAND_ACCESS.
// 2. RestServiceType is EFI_REST_EX_SERVICE_REDFISH.
// 3. RestExConfigType is EFI_REST_EX_CONFIG_TYPE_HTTP.

(continues on next page)
if (RestExServiceInfo-> REfiRestExServiceInfoV10.estServiceAccessMode ==
    EFI_REST_EX_SERVICE_OUT_OF_BAND_ACCESS &&
    RestExServiceInfo-> EfiRestExServiceInfoV10.RestServiceType ==
    EFI_REST_EX_SERVICE_REDFISH &&
    RestExServiceInfo-> EfiRestExServiceInfoV10.RestExConfigType ==
    EFI_REST_EX_CONFIG_TYPE_HTTP) {
    break;
}

// Make sure we have found the preferred REST EX driver.
//
if (Index == HandleNum) {
    goto ON_EXIT;
}

// Configure the RESTEX instance.
//
Status = RestEx->Configure (
    RestEx,
    RestExConfigData
);
if (EFI_ERROR (Status)) {
    goto ON_EXIT;
}

// Send and receive the resources from a REST service.
//
Status = RestEx->SendReceive (
    RestEx,
    &RequestMessage,
    &ResponseMessage
);
if (EFI_ERROR (Status)) {
    goto ON_EXIT;
}

ON_EXIT:

RestExService->DestroyChild (RestExService, RestExChild);
return Status;
29.7.15.1.1 EFI_REST_EX_PROTOCOL.AsyncSendReceive()

To those HTTP-aware underlying mechanisms of the REST EX Protocol driver instance and “respond-async” prefer header aware REST service, REST EX Protocol driver instance adds additional HTTP Prefer header field (Refer to IETF RFC7240) which is set to “respond-async” in the RequestMessage. HTTP 202 Accepted Status Code is returned from REST service which indicates the REST request is accepted by REST service, however, the final result is left unknown. The way how REST service returns final response to REST EX Protocol driver instance is REST service implementation-specific and transparent to the REST client. Whether or not the REST service has a proper response to “respond-async” is REST service implementation-specific. AsyncSendReceive() must returns EFI_UNSUPPORTED if the REST service that the REST EX instance communicates with is incapable of asynchronous response.

REST EX Protocol driver instance must returns EFI_SUCCESS to caller once it gets HTTP 202 Accepted Status Code from REST service. The HTTP Location header field can be returned in HTTP 202 Accepted Status Code. REST EX Protocol driver instance may create an EFI timer to poll the status of URI returned in HTTP Location header field. The content of URI which pointed by HTTP Location header is REST service implementation-specific and not defined in REST EX Protocol specification. REST EX Protocol driver instance provider should have knowledge about how to poll the status of returning resource from given HTTP Location header.

The following flowchart describes the flow of establishing asynchronous REST request on HTTP-aware infrastructure:

Once the asynchronous REST request is established, REST EX Protocol driver instance starts to monitor whether resource event change is pushed to REST EX Protocol driver instance from REST service.

29.7.15.1.2 EFI_REST_EX_PROTOCOL.EventService()

The REST client creates and submits an HTTP-like header/body content in RequestMessage which are required by REST Event services. The REST Event Service will return an HTTP 201 (CREATED) and the Location header in the response shall contain a URI giving the location of newly created subscription resource.

The following flowchart describes the flow of subscribing to a REST Event service on HTTP-aware infrastructure:

Once the REST request is submitted successfully and REST EX Protocol driver instance gets the HTTP 201, REST EX Protocol driver instance starts to monitor whether resource event change is pushed to REST EX Protocol driver instance from REST service.

29.7.16 EFI_REST_EX_PROTOCOL.EventService()

The REST client creates and submits an HTTP-like header/body content in RequestMessage which are required by REST Event services. The REST Event Service will return an HTTP 201 (CREATED) and the Location header in the response shall contain a URI giving the location of newly created subscription resource.

The following flowchart describes the flow of subscribing to a REST Event service on HTTP-aware infrastructure:

Once the REST request is submitted successfully and REST EX Protocol driver instance gets the HTTP 201, REST EX Protocol driver instance starts to monitor whether resource event change is pushed to REST EX Protocol driver instance from REST service.
29.7. EFI REST Support Overview
29.7. EFI REST Support Overview

Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A
29.7.17 EFI REST JSON Resource to C Structure Converter

29.7.17.1 Overview

EFI REST JSON Structure Protocol is designed as the centralized REST JSON Resource IN-Structure OUT (JSON-IN Structure-OUT in short) and vice versa converter for EFI REST client drivers or EFI REST client applications. This protocol provides the registration function which is invoked by upper layer EFI driver to register converter as the plug-in converter for the well-known REST JSON resource. The EFI driver which provide REST JSON resource to structure converter is EFI REST JSON structure converter producer. In the other hand, EFI drivers or applications which utilize EFI REST JSON Structure protocol is the consumer of EFI REST JSON structure converter. The convert producer is required to register its converter functions with predefined RESTJSON resource namespace and data type. EFI REST JSON Structure Protocol maintains the database of all plug-in converter and dispatches the consumer request to proper REST JSON resource structure converter. EFI REST JSON Structure Protocol doesn’t have knowledge about the exact structure for the particular REST JSON resource. It just dispatches JSON resource to the correct convert functions and returns the pointer of structure generated by convert producer. This protocol reduces the burdens of JSON resource parsing effort. This also provides the easier way to refer to specific REST JSON property using native C structure reference. Below figure delineates the software stack of EFI REST JSON resource to structure converter architecture.

29.7.17.2 EFI REST JSON Structure Protocol

Summary

EFI REST JSON Structure Protocol provides function to converter producer for the registration of REST JSON resource structure converter. This protocol also provides functions of JSON-IN Structure-OUT and vice versa to converter consumer.

Protocol GUID

```
#define EFI_REST_JSON_STRUCTURE_PROTOCOL_GUID \
{ 0xa9a048f6, 0x48a0, 0x4714, {0xb7, 0xda, 0xa9, 0xad, \
 0x87, 0xd4, 0xda, 0xc9}}
```

Protocol Interface Structure
typedef struct _EFI_REST_JSON_STRUCTURE_PROTOCOL {
    EFI_REST_JSON_STRUCTURE_REGISTER Register;
    EFI_REST_JSON_STRUCTURE_TO_STRUCTURE ToStructure;
    EFI_REST_JSON_STRUCTURE_TO_JSON ToJson;
    EFI_REST_JSON_STRUCTURE_DESTORY_STRUCTURE DestoryStructure;
} EFI_REST_JSON_STRUCTURE_PROTOCOL;

Parameters

Register
    Register REST JSON structure converter producer.

ToStructure
    JSON-IN Structure-OUT function.

ToJson
    Structure-IN JSON-OUT function.

DestoryStructure
    Destroy JSON structure returned from ToStructure function.

Description

Each plug-in JSON resource to structure converter is required to register itself into EFI_REST_JSON_STRUCTURE_PROTOCOL. The plug-in JSON resource to structure converter has to provide corresponding functions for ToStructure(), ToJson() and DestoryStructure() for the specific REST JSON resource. EFI_REST_JSON_STRUCTURE_PROTOCOL maintains converter producer using the JSON resource type and version information when registration. The ToStructure(), ToJson() and DestoryStructure() provided by EFI_REST_JSON_STRUCTURE_PROTOCOL is published to converter consumer for JSON-IN Structure-OUT and vice versa conversion. EFI_REST_JSON_STRUCTURE_PROTOCOL is responsible for dispatching consumer request to the proper converter producer.

29.7.18 EFI_REST_JSON_STRUCTURE.Register ()

Summary

This function provides REST JSON resource to structure converter registration.

Protocol Interface

typedef EFI_STATUS
(EIFIAP1 *EFI_REST_JSON_STRUCTURE_REGISTER)(
    IN EFI_REST_JSON_STRUCTURE_PROTOCOL *This,
    IN EFI_REST_JSON_STRUCTURE_SUPPORTED *JsonStructureSupported,
    IN EFI_REST_JSON_STRUCTURE_TO_STRUCTURE ToStructure,
    IN EFI_REST_JSON_STRUCTURE_TO_JSON ToJson,
    IN EFI_REST_JSON_STRUCTURE_DESTORY_STRUCTURE DestroyStructure
    );

Parameters

This
    This is the EFI_REST_JSON_STRUCTURE_PROTOCOL instance.

JsonStructureSupported
    The type and version of REST JSON resource which this converter supports.
**ToStructure**

The function to convert REST JSON resource to structure.

**ToJson**

The function to convert REST JSON structure to JSON in text format.

**DestroyStructure**

Destroy REST JSON structure returned in `ToStructure()` function.

**Description**

This function is invoked by REST JSON resource to structure converter to register JSON-IN Structure-OUT, Structure-IN JSON-OUT and destroy JSON structure functionalities. The converter producer has to correctly specify REST resource supporting information in `EFI_REST_JSON_STRUCTURE_SUPPORTED`. The information includes the type name, revision and data type of REST resource. Multiple REST JSON resource to structure converters may supported in one drive, refer to below related definition.

**Related Definitions**

```c
typedef CHAR8 *EFI_REST_JSON_RESOURCE_TYPE_DATATYPE;

//*******************************************************************************
// EFI_REST_JSON_RESOURCE_TYPE_NAMESPACE
//*******************************************************************************
typedef struct _EFI_REST_JSON_RESOURCE_TYPE_NAMESPACE {
  CHAR8  *ResourceTypeName;
  CHAR8  *MajorVersion;
  CHAR8  *MinorVersion;
  CHAR8  *ErrataVersion;
} EFI_REST_JSON_RESOURCE_TYPE_NAMESPACE;
```

**Parameters**

**ResourceTypeName**

CHAR8 pointer to the name of this REST JSON Resource.

**MajorVersion**

CHAR8 pointer to the string of REST JSON Resource major version.

**MinorVersion**

CHAR8 pointer to the string of REST JSON Resource minor version.

**ErrataVersion**

CHAR8 pointer to the string of REST JSON Resource errata version.

```c
//*******************************************************************************
// EFI_REST_JSON_RESOURCE_TYPE_IDENTIFIER
//*******************************************************************************
typedef struct _EFI_REST_JSON_RESOURCE_TYPE_IDENTIFIER {
  EFI_REST_JSON_RESOURCE_TYPE_NAMESPACE Namespace;
  EFI_REST_JSON_RESOURCE_TYPE_DATATYPE Datatype;
} EFI_REST_JSON_RESOURCE_TYPE_IDENTIFIER;
```

**Parameters**

**Namespace**

Name space of this REST JSON resource.

**Datatype**

CHAR8 pointer to the string of data type, could be NULL if there is no data type for this REST JSON resource.
// ESI_REST_JSON_STRUCTURE_SUPPORTED
//***************************************************************
typedef struct _EFI_REST_JSON_STRUCTURE_SUPPORTED {
  EFI_REST_JSON_STRUCTURE_SUPPORTED *Next;
  EFI_REST_RESOURCE_TYPE_IDENTIFIER JsonResourceType;
} EFI_REST_JSON_STRUCTURE_SUPPORTED;

Parameters

Next
  Pointer to next EFI_REST_JSON_STRUCTURE_SUPPORTED.

JsonResourceType
  Information of REST JSON resource this converter supports.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Converter is successfully registered</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following is TRUE:</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>JsonStructureSupported is NULL.</td>
</tr>
<tr>
<td></td>
<td>ResourceType in JsonStructureSupported structure is a NULL string</td>
</tr>
<tr>
<td></td>
<td>ToStructure is NULL.</td>
</tr>
<tr>
<td></td>
<td>ToJason is NULL.</td>
</tr>
<tr>
<td></td>
<td>DestroyStructure is NULL.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>If the JSON resource to structure converter is already registered for this</td>
</tr>
<tr>
<td></td>
<td>type and revision of JSON resource.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCE</td>
<td>Not enough resource for the converter registration</td>
</tr>
</tbody>
</table>

29.7.19 EFI_REST_JSON_STRUCTURE.ToStructure()

Summary

JSON-IN Structure-OUT function. Convert the given REST JSON resource into structure.

Protocol Interface

typedef
  EFI_STATUS
  (EFIAPIC *EFI_REST_JSON_STRUCTURE_TO_STRUCTURE)(
    IN EFI_REST_JSON_STRUCTURE_PROTOCOL *This,
    IN EFI_REST_JSON_RESOURCE_TYPE_IDENTIFIER *JsonRsncIdentifier
    OPTIONAL,
    IN CHAR8 *ResourceJsonText,
    OUT EFI_REST_JSON_STRUCTURE_HEADER **JsonStructure
  );

Parameters

This
  This is the EFI_REST_JSON_STRUCTURE_PROTOCOL instance.
JsonRsrcIdentifier

This indicates the resource type and version is given in ResourceJsonText. If JsonRsrcIdentifier is NULL, means the JSON resource type and version information of given ResourceJsonText is unsure. User would like to have EFI_REST_JSON_STRUCTURE_PROTOCOL to look for the proper JSON structure converter.

ResourceJsonText

REST JSON resource in text format.

JsonStructure

Pointer to receive the pointer to EFI_REST_JSON_STRUCTURE_HEADER, refer to related definition for the details.

Description

This function converts the given JSON resource in text format into predefined structure. The definition of structure format is not the scope of EFI_REST_JSON_STRUCTURE_PROTOCOL. EFI_REST_JSON_STRUCTURE_PROTOCOL is a centralized JSON-IN Structure-OUT converter which maintain the registration of a variety of JSON resource to structure converters. The structure definition and the corresponding C header file are written and released by 3rd party, OEM, organization or any open source communities. The JSON resource to structure converter (convert producer) may be released in the source format or binary format. The convert producer registers itself to EFI_REST_JSON_STRUCTURE_PROTOCOL uses Register() and provides EFix JSON resource to structure and vice versa conversion. Consumer has to destroy JsonStructure using DestoryStructure() function. Resource allocated for JsonStructure will be released and cleaned up by convert producer.

When JsonRsrcIdentifier is a non NULL pointer, ResourceType in EFI_REST_JSON_RESOURCE_TYPE_NAMESPACE must be a non NULL string, however the revision in EFI_REST_JSON_RESOURCE_TYPE_NAMESPACE and data type in EFI_REST_JSON_RESOURCE_TYPE could be NULL string if REST JSON resource is non version controlled or no data type is defined. If JsonRsrcIdentifier is a non NULL pointer, EFI_REST_JSON_STRUCTURE_PROTOCOL looks for the proper converter from its database. Invokes the ToStructure() provided by the converter to convert JSON resource to structure.

Another scenario is JsonRsrcIdentifier may passed in as NULL, this means the JSON resource type and version information of given ResourceJsonText is unsure. In this case, EFI_REST_JSON_STRUCTURE_PROTOCOL invokes and passes ResourceJsonText to ToStructure() of each registered converter with JsonRsrcIdentifier set to NULL. Converter producer may or may not automatically determine REST JSON resource type and version. Converter producer should return EFI_UNSUPPORTED if it doesn’t support automatically recognition of REST JSON resource. Or converter producer can recognize the given REST JSON resource by parsing the certain properties. This depends on the implementation of JSON resource to structure converter. If one of the registered converter producers can recognize the given ResourceJsonText, the JsonRsrcIdentifier in EFI_REST_JSON_STRUCTURE_HEADER is filled up with the proper REST JSON resource type, version and data type. With the information provided in EFI_REST_JSON_STRUCTURE_HEADER, consumer has idea about what the exact type of REST JSON structure is.

Related Definitions

```c
//**************************************************************
// EFI_REST_JSON_STRUCTURE_HEADER
//**************************************************************
typedef struct _EFI_REST_JSON_STRUCTURE_HEADER {
    EFI_REST_JSON_RESOURCE_TYPE_IDENTIFIER    JsonRsrcIdentifier;
    //
    // Follow by a pointer points to JSON structure, the content in the
    // JSON structure is implementation-specific according to converter producer.
    //
    VOID *JsonStructurePointer;
} EFI_REST_JSON_STRUCTURE_HEADER;
```

Parameters
JsonRsrcIdentifier
Information of REST JSON structure returned from this converter.

JsonStructurePointer
Pointers to JSON structure, the content in the JSON structure is implementation-specific according to the converter producer.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Pointer to JSON structure is returned in JsonStructure</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following is TRUE:</td>
</tr>
<tr>
<td></td>
<td>This is NULL.</td>
</tr>
<tr>
<td></td>
<td>ResourceJsonText is NULL.</td>
</tr>
<tr>
<td></td>
<td>JsonRsrcIdentifier is not NULL, but the</td>
</tr>
<tr>
<td></td>
<td>ResourceTypeName in JsonRsrcIdentifier is NULL.</td>
</tr>
<tr>
<td></td>
<td>JsonStructure is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No proper JSON resource to structure convert found.</td>
</tr>
</tbody>
</table>

29.7.20 EFI_REST_JSON_STRUCTURE.ToJson ()

Summary
Structure-IN JSON-OUT function. Convert the given REST JSON structure into JSON text. The definition of structure format is not the scope of EFI_REST_JSON_STRUCTURE_PROTOCOL. The structure definition and the corresponding C header file are written and released by 3rd party, OEM, organization or any open source communities. Consumer has to free the memory block allocated for ResourceJsonText if the JSON resource is no longer needed.

Protocol Interface

```c
typedef
EFI_STATUS
(EIFIAPIC *EFI_REST_JSON_STRUCTURE_TO_JSON)(
    IN EFI_REST_JSON_STRUCTURE_PROTOCOL *This,
    IN EFI_REST_JSON_STRUCTURE_HEADER *JsonStructureHeader,
    OUT CHAR8 **ResourceJsonText
);
```

Parameters

This
This is the EFI_REST_JSON_STRUCTURE_PROTOCOL instance.

JsonStructureHeader
The point to EFI_REST_JSON_STRUCTURE_HEADER structure. EFI_REST_JSON_RESOURCE_TYPE_IDENTIFIER in EFI_REST_JSON_STRUCTURE_HEADER must exactly describes the JSON resource type and revision referred by this JSON structure. ResourceTypeName in JsonRsrcIdentifier must be non NULL pointer pointes to string. Revision and data type in JsonRsrcIdentifier could be NULL if REST JSON resource is not version controlled and or data type definition.

ResourceJsonText
Pointer to receive REST JSON resource in text format.

Description
This function converts the given REST JSON structure into REST JSON text format resource.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Pointer to JSON resource in text format is returned in ResourceJsonText</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• <code>This</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td></td>
<td>• <code>JsonStructureHeader</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td></td>
<td>• <code>ResourceJsonText</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No proper JSON structure converter found to convert JSON structure to JSON text format.</td>
</tr>
</tbody>
</table>

### 29.7.21 EFI_REST_JSON_STRUCTURE.DestroyStructure ()

#### Summary

*This function destroys the REST JSON structure.*

#### Protocol Interface

```c
typedef EFI_STATUS
    (EFIAPI *EFI_REST_JSON_STRUCTURE_DESTORY_STRUCTURE)(
    IN EFI_REST_JSON_STRUCTURE_PROTOCOL *This,
    IN EFI_REST_JSON_STRUCTURE_HEADER *JsonStructureHeader
);
```

#### Description

This function destroys the JSON structure generated by `ToStructure()` function. REST JSON resource structure converter is responsible for freeing and cleaning up all resource associated with the give JSON structure.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>JSON structure is successfully destroyed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• <code>This</code> is null.</td>
</tr>
<tr>
<td></td>
<td>• <code>JsonStructureHeader</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No proper JSON structure converter found to destroy JSON structure.</td>
</tr>
</tbody>
</table>
29.7.21.1 EFI Redfish JSON Structure Converter

For writing and using an EFI Redfish JSON Structure Converter, see Section 31.2, using the EFI_REST_JSON_STRUCTURE_PROTOCOL protocol.
30.1 EFI UDP Protocol

This chapter defines the EFI UDP (User Datagram Protocol) Protocol that interfaces over the EFI IP Protocol, and the EFI MTFTP Protocol interface that is built upon the EFI UDP Protocol. Protocols for version 4 and version 6 of UDP and MTFTP are included.

30.1.1 UDP4 Service Binding Protocol

30.1.1.1 EFI_UDP4_SERVICE_BINDING_PROTOCOL

Summary
The EFI UDPv4 Service Binding Protocol is used to locate communication devices that are supported by an EFI UDPv4 Protocol driver and to create and destroy instances of the EFI UDPv4 Protocol child protocol driver that can use the underlying communications device.

GUID

```
#define EFI_UDP4_SERVICE_BINDING_PROTOCOL_GUID
     {0x83f01464,0x99bd,0x45e5,\
      {0xb3,0x83,0xaf,0x63,0x05,0xd8,0xe9,0xe6}}
```

Description
A network application that requires basic UDPv4 I/O services can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish a EFI UDPv4 Service Binding Protocol GUID. Each device with a published EFI UDPv4 Service Binding Protocol GUID supports the EFI UDPv4 Protocol and may be available for use.

After a successful call to the `EFI_UDP4_SERVICE_BINDING_PROTOCOL>CreateChild()` function, the newly created child EFI UDPv4 Protocol driver is in an unconfigured state; it is not ready to send and receive data packets.

Before a network application terminates execution every successful call to the `EFI_UDP4_SERVICE_BINDING_PROTOCOL>CreateChild()` function must be matched with a call to the `EFI_UDP4SERVICE_BINDING_PROTOCOL>DestroyChild()` function.
30.1.2 UDP4 Protocol

30.1.2.1 EFI_UDP4_PROTOCOL

Summary
The EFI UDPv4 Protocol provides simple packet-oriented services to transmit and receive UDP packets.

GUID
#define EFI_UDP4_PROTOCOL_GUID \
{0x3ad9df29,0x4501,0x478d,\ 
{0xb1,0xf8,0x7f,0x7f,0xe7,0x0e,0x50,0xf3}

Protocol Interface Structure

typedef struct _EFI_UDP4_PROTOCOL {
    EFI_UDP4_GET_MODE_DATA   GetModeData;
    EFI_UDP4_CONFIGURE       Configure;
    EFI_UDP4_GROUPS          Groups;
    EFI_UDP4/routes          Routes;
    EFI_UDP4_TRANSMIT        Transmit;
    EFI_UDP4_RECEIVE         Receive;
    EFI_UDP4_CANCELS         Cancel;
    EFI_UDP4_POLL            Poll;
} EFI_UDP4_PROTOCOL;

Parameters

GetModeData
Reads the current operational settings. See the GetModeData() function description.

Configure
Initializes, changes, or resets operational settings for the EFI UDPv4 Protocol. See the Configure() function description.

Groups
Joins and leaves multicast groups. See the Groups() function description.

Routes
Add and deletes routing table entries. See the Routes() function description.

Transmit
Queues outgoing data packets into the transmit queue. This function is a nonblocked operation. See the Transmit() function description.

Receive
Places a receiving request token into the receiving queue. This function is a nonblocked operation. See the Receive() function description.

Cancel
Aborts a pending transmit or receive request. See the Cancel() function description.

Poll
Polls for incoming data packets and processes outgoing data packets. See the Poll() function description.

Description
The EFI_UDP4_PROTOCOL defines an EFI UDPv4 Protocol session that can be used by any network drivers, applications, or daemons to transmit or receive UDP packets. This protocol instance can either be bound to a specified port...
as a service or connected to some remote peer as an active client. Each instance has its own settings, such as the routing table and group table, which are independent from each other.

NOTE: In this document, all IPv4 addresses and incoming/outgoing packets are stored in network byte order. All other parameters in the functions and data structures that are defined in this document are stored in host byte order.

30.1.2.2 EFI_UDP4_PROTOCOL.GetModeData()

Summary

Reads the current operational settings.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_UDP4_GET_MODE_DATA) (  
    IN EFI_UDP4_PROTOCOL *This,  
    OUT EFI_UDP4_CONFIG_DATA *Udp4ConfigData OPTIONAL,  
    OUT EFI_IP4_MODE_DATA *Ip4ModeData OPTIONAL,  
    OUT EFI_MANAGED_NETWORK_CONFIG_DATA *MnpConfigData OPTIONAL,  
    OUT EFI_SIMPLE_NETWORK_MODE *SnpModeData OPTIONAL);
```

Parameters

This

Pointer to the EFI_UDP4_PROTOCOL instance.

Udp4ConfigData

Pointer to the buffer to receive the current configuration data. Type EFI_UDP4_CONFIG_DATA is defined in “Related Definitions” below.

Ip4ModeData*

Pointer to the EFI IPv4 Protocol mode data structure. Type EFI_IP4_MODE_DATA is defined in EFI_IP4_PROTOCOL.GetModeData().

MnpConfigData

Pointer to the managed network configuration data structure. Type EFI_MANAGED_NETWORK_CONFIG_DATA is defined in EFI_MANAGED_NETWORK_PROTOCOL.GetModeData().

SnpModeData

Pointer to the simple network mode data structure. Type EFI_SIMPLE_NETWORK_MODE is defined in the EFI_SIMPLE_NETWORK_PROTOCOL.

Description

The GetModeData() function copies the current operational settings of this EFI UDPv4 Protocol instance into user-supplied buffers. This function is used optionally to retrieve the operational mode data of underlying networks or drivers.

Related Definition

```c
//********************************************************************
// EFI_UDP4_CONFIG_DATA
//********************************************************************
typedef struct {
    //Receiving Filters
```
AcceptBroadcast
   Set to TRUE to accept broadcast UDP packets.

AcceptPromiscuous
   Set to TRUE to accept UDP packets that are sent to any address.

AcceptAnyPort
   Set to TRUE to accept UDP packets that are sent to any port.

AllowDuplicatePort
   Set to TRUE to allow this EFI UDPv4 Protocol child instance to open a port number that is already being used by another EFI UDPv4 Protocol child instance.

TypeOfService
   TypeOfService field in transmitted IPv4 packets.

TimeToLive
   TimeToLive field in transmitted IPv4 packets.

DoNotFragment
   Set to TRUE to disable IP transmit fragmentation.

ReceiveTimeout
   The receive timeout value (number of microseconds) to be associated with each incoming packet. Zero means do not drop incoming packets.

TransmitTimeout
   The transmit timeout value (number of microseconds) to be associated with each outgoing packet. Zero means do not drop outgoing packets.

UseDefaultAddress
   Set to TRUE to use the default IP address and default routing table. If the default IP address is not available yet, then the underlying EFI IPv4 Protocol driver will use EFI_IP4_CONFIG2_PROTOCOL to retrieve the IP address and subnet information. Ignored for incoming filtering if AcceptPromiscuous is set to TRUE.

StationAddress
   The station IP address that will be assigned to this EFI UDPv4 Protocol instance. The EFI UDPv4 and EFI IPv4 Protocol drivers will only deliver incoming packets whose destination matches this IP address exactly. Address 0.0.0.0 is also accepted as a special case in which incoming packets destined to any station IP address are always
delivered. Not used when $UseDefaultAddress$ is **TRUE**. Ignored for incoming filtering if $AcceptPromiscuous$ is **TRUE**.

**SubnetMask**

The subnet address mask that is associated with the station address. Not used when $UseDefaultAddress$ is **TRUE**.

**StationPort**

The port number to which this EFI UDPv4 Protocol instance is bound. If a client of the EFI UDPv4 Protocol does not care about the port number, set $StationPort$ to zero. The EFI UDPv4 Protocol driver will assign a random port number to transmitted UDP packets. Ignored if $AcceptAnyPort$ is set to **TRUE**.

**RemoteAddress**

The IP address of remote host to which this EFI UDPv4 Protocol instance is connecting. If $RemoteAddress$ is not 0.0.0.0, this EFI UDPv4 Protocol instance will be connected to $RemoteAddress$; i.e., outgoing packets of this EFI UDPv4 Protocol instance will be sent to this address by default and only incoming packets from this address will be delivered to client. Ignored for incoming filtering if $AcceptPromiscuous$ is **TRUE**.

**RemotePort**

The port number of the remote host to which this EFI UDPv4 Protocol instance is connecting. If it is not zero, outgoing packets of this EFI UDPv4 Protocol instance will be sent to this port number by default and only incoming packets from this port will be delivered to client. Ignored if $RemoteAddress$ is 0.0.0.0 and ignored for incoming filtering if $AcceptPromiscuous$ is **TRUE**.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The mode data was read.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>When $Udp4ConfigData$ is queried, no configuration data is available because this instance has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>$This$ is <strong>NULL</strong>.</td>
</tr>
</tbody>
</table>

### 30.1.2.3 EFI_UDP4_PROTOCOL.Configure()  

**Summary**

- Initializes, changes, or resets the operational parameters for this instance of the EFI UDPv4 Protocol.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_UDP4_CONFIGURE) (  
  IN EFI_UDP4_PROTOCOL *This,  
  IN EFI_UDP4_CONFIG_DATA *UdpConfigData OPTIONAL  
);
```

**Parameters**

- **This**
  - Pointer to the $EFI_UDP4_PROTOCOL$ instance.

- **UdpConfigData**
  - Pointer to the buffer to receive the current mode data.

**Description**

The $Configure()$ function is used to do the following:

- Initialize and start this instance of the EFI UDPv4 Protocol.
• Change the filtering rules and operational parameters.

• Reset this instance of the EFI UDPv4 Protocol.

Until these parameters are initialized, no network traffic can be sent or received by this instance. This instance can be also reset by calling `Configure()` with `UdpConfigData` set to `NULL`. Once reset, the receiving queue and transmitting queue are flushed and no traffic is allowed through this instance.

With different parameters in `UdpConfigData`, `Configure()` can be used to bind this instance to specified port.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The configuration settings were set, changed, or reset successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more following conditions are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• <code>UdpConfigData.StationAddress</code> is not a valid unicast IPv4 address.</td>
</tr>
<tr>
<td></td>
<td>• <code>UdpConfigData.SubnetMask</code> is not a valid IPv4 address mask. The subnet mask must be contiguous.</td>
</tr>
<tr>
<td></td>
<td>• <code>UdpConfigData.RemoteAddress</code> is not a valid unicast IPv4 address if it is not zero.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The EFI UDPv4 Protocol instance is already started/configured and must be stopped/reset before it can be reconfigured. Only <code>TypeOfService</code>, <code>TimeToLive</code>, <code>DoNotFragment</code>, <code>ReceiveTimeout</code>, and <code>TransmitTimeout</code> can be reconfigured without stopping the current instance of the EFI UDPv4 Protocol.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td><code>UdpConfigData.AllowDuplicatePort</code> is FALSE and <code>UdpConfigData.StationPort</code> is already used by other instance.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The EFI UDPv4 Protocol driver cannot allocate memory for this EFI UDPv4 Protocol instance.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network or system error occurred and this instance was not opened.</td>
</tr>
</tbody>
</table>

### 30.1.2.4 EFI_UDP4_PROTOCOL.Groups()

**Summary**

Joins and leaves multicast groups.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_UDP4_GROUPS) (
    IN EFI_UDP4_PROTOCOL *This, 
    IN BOOLEAN JoinFlag,  
    IN EFI_IPv4_ADDRESS *MulticastAddress OPTIONAL
);
```

**Parameters**

- **This**
  
  Pointer to the `EFI_UDP4_PROTOCOL` instance.
JoinFlag
Set to **TRUE** to join a multicast group. Set to **FALSE** to leave one or all multicast groups.

MulticastAddress
Pointer to multicast group address to join or leave.

Description
The `Groups()` function is used to enable and disable the multicast group filtering.

If the `JoinFlag` is **FALSE** and the `MulticastAddress` is **NULL**, then all currently joined groups are left.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI UDPv4 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate resources to join the group.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER| One or more of the following conditions is TRUE:  
• This is **NULL**.  
• JoinFlag is **TRUE** and `MulticastAddress` is **NULL**.  
• JoinFlag is **TRUE** and `*MulticastAddress` is not a valid multicast address. |
| EFI_ALREADY_STARTED | The group address is already in the group table (when JoinFlag is **TRUE**).                                                  |
| EFI_NOT_FOUND       | The group address is not in the group table (when JoinFlag is **FALSE**).                                                    |
| EFI_DEVICE_ERROR    | An unexpected system or network error occurred.                                                                             |

30.1.2.5 **EFI_UDP4_PROTOCOL.Routes()**

Summary
Adds and deletes routing table entries.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_UDP4_ROUTES) (  
    IN EFI_UDP4_PROTOCOL *This,  
    IN BOOLEAN DeleteRoute,  
    IN EFI_IPv4_ADDRESS *SubnetAddress,  
    IN EFI_IPv4_ADDRESS *SubnetMask,  
    IN EFI_IPv4_ADDRESS *GatewayAddress
);
```

Parameters

This
Pointer to the `EFI_UDP4_PROTOCOL` instance.

DeleteRoute
Set to **TRUE** to delete this route from the routing table. Set to **FALSE** to add this route to the routing table. `DestinationAddress` and `SubnetMask` are used as the key to each route entry.
SubnetAddress
The destination network address that needs to be routed.

SubnetMask
The subnet mask of SubnetAddress.

GatewayAddress
The gateway IP address for this route.

Description
The Routes() function adds a route to or deletes a route from the routing table.

Routes are determined by comparing the SubnetAddress with the destination IP address and arithmetically AND-ing it with the SubnetMask. The gateway address must be on the same subnet as the configured station address.

The default route is added with SubnetAddress and SubnetMask both set to 0.0.0.0. The default route matches all destination IP addresses that do not match any other routes.

A zero GatewayAddress is a nonroute. Packets are sent to the destination IP address if it can be found in the Address Resolution Protocol (ARP) cache or on the local subnet. One automatic nonroute entry will be inserted into the routing table for outgoing packets that are addressed to a local subnet (gateway address of 0.0.0.0).

Each instance of the EFI UDPv4 Protocol has its own independent routing table. Instances of the EFI UDPv4 Protocol that use the default IP address will also have copies of the routing table provided by the EFI_IP4_CONFIG2_PROTOCOL. These copies will be updated automatically whenever the IP driver reconfigures its instances; as a result, the previous modification to these copies will be lost.

NOTE: There is no way to set up routes to other network interface cards (NICs) because each NIC has its own independent network stack that shares information only through EFI UDP4 Variable.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The operation completed successfully.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI UDPv4 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is</td>
</tr>
<tr>
<td></td>
<td>not finished yet.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• SubnetAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>• SubnetMask is NULL.</td>
</tr>
<tr>
<td></td>
<td>• GatewayAddress is NULL.</td>
</tr>
<tr>
<td></td>
<td>• SubnetAddress is not a valid subnet address.</td>
</tr>
<tr>
<td></td>
<td>• SubnetMask is not a valid subnet mask.</td>
</tr>
<tr>
<td></td>
<td>• GatewayAddress is not a valid unicast IP address.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not add the entry to the routing table.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>This route is not in the routing table.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The route is already defined in the routing table.</td>
</tr>
</tbody>
</table>
30.1.2.6 EFI_UDP4_PROTOCOL.Transmit()

Summary
Queues outgoing data packets into the transmit queue.

Prototype

typedef
EFI_STATUS
(EIFIAP I *EFI_UDP4_TRANSMIT) ( 
    IN EFI_UDP4_PROTOCOL *This,
    IN EFI_UDP4_COMPLETION_TOKEN *Token
);

Parameters

This
Pointer to the EFI_UDP4_PROTOCOL instance.

Token
Pointer to the completion token that will be placed into the transmit queue. Type
EFI_UDP4_COMPLETION_TOKEN is defined in “Related Definitions” below.

Description

The Transmit() function places a sending request to this instance of the EFI UDPv4 Protocol, alongside the transmit
data that was filled by the user. Whenever the packet in the token is sent out or some errors occur, the Token.Event will
be signaled and Token.Status is updated. Providing a proper notification function and context for the event will enable
the user to receive the notification and transmitting status.

Related Definitions

//*******************************************************
// EFI_UDP4_COMPLETION_TOKEN
//*******************************************************
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    union {
        EFI_UDP4_RECEIVE_DATA *RxData;
        EFI_UDP4_TRANSMIT_DATA *TxData;
        Packet;
    } Packet;
} EFI_UDP4_COMPLETION_TOKEN;

Event

This Event will be signaled after the Status field is updated by the EFI UDPv4 Protocol driver. The type of
Event must be EVT_NOTIFY_SIGNAL. The Task Priority Level (TPL) of Event must be lower than or equal to
TPL_CALLBACK.

Status

Will be set to one of the following values:

EFI_SUCCESS. The receive or transmit operation completed successfully.
**EFI_ABORTED.** The receive or transmit was aborted.

**EFI_TIMEOUT.** The transmit timeout expired.

**EFI_NETWORK_UNREACHABLE.** The destination network is unreachable. RxData is set to **NULL** in this situation.

**EFI_HOST_UNREACHABLE.** The destination host is unreachable. RxData is set to **NULL** in this situation.

**EFI_PROTOCOL_UNREACHABLE.** The UDP protocol is unsupported in the remote system. RxData is set to **NULL** in this situation.

**EFI_PORT_UNREACHABLE.** No service is listening on the remote port. RxData is set to **NULL** in this situation.

**EFI_ICMP_ERROR.** Some other Internet Control Message Protocol (ICMP) error report was received. For example, packets are being sent too fast for the destination to receive them and the destination sent an ICMP source quench report. RxData is set to **NULL** in this situation.

**EFI_DEVICE_ERROR.** An unexpected system or network error occurred.

**EFI_NO_MEDIA.** There was a media error.

**RxData**

When this token is used for receiving, **RxData** is a pointer to **EFI_UDP4_RECEIVE_DATA**. Type **EFI_UDP4_RECEIVE_DATA** is defined below.

**TxData**

When this token is used for transmitting, **TxData** is a pointer to **EFI_UDP4_TRANSMIT_DATA**. Type **EFI_UDP4_TRANSMIT_DATA** is defined below.

The **EFI_UDP4_COMPLETION_TOKEN** structures are used for both transmit and receive operations.

When used for transmitting, the **Event** and **TxData** fields must be filled in by the EFI UDPv4 Protocol client. After the transmit operation completes, the **Status** field is updated by the EFI UDPv4 Protocol and the **Event** is signaled.

- When used for receiving, only the **Event** field must be filled in by the EFI UDPv4 Protocol client. After a packet is received, **RxData** and **Status** are filled in by the EFI UDPv4 Protocol and the **Event** is signaled.

- The ICMP related status codes filled in **Status** are defined as follows:

```c
#define EFI_NETWORK_UNREACHABLE EFIERR(100)
#define EFI_HOST_UNREACHABLE EFIERR(101)
#define EFI_PROTOCOL_UNREACHABLE EFIERR(102)
#define EFI_PORT_UNREACHABLE EFIERR(103)
```

```c
typedef struct {
    EFI_TIME TimeStamp;
    EFI_EVENT RecycleSignal;
    EFI_UDP4_SESSION_DATA UdpSession;
    UINT32 DataLength;
    UINT32 FragmentCount;
    EFI_UDP4_FRAGMENT_DATA FragmentTable[1];
} EFI_UDP4_RECEIVE_DATA;
```

**TimeStamp**
Time when the EFI UDPv4 Protocol accepted the packet. TimeStamp is zero filled if timestamps are disabled or unsupported

RecycleSignal
Indicates the event to signal when the received data has been processed.

UdpSession
The UDP session data including SourceAddress, SourcePort, DestinationAddress, and DestinationPort. Type EFI_UDP4_SESSION_DATA is defined below.

DataLength
The sum of the fragment data length.

FragmentCount
Number of fragments. May be zero.

FragmentTable
Array of fragment descriptors. IP and UDP headers are included in these buffers if ConfigData.RawData is TRUE. Otherwise they are stripped. May be zero. Type EFI_UDP4_FRAGMENT_DATA is defined below.

EFI_UDP4_RECEIVE_DATA is filled by the EFI UDPv4 Protocol driver when this EFI UDPv4 Protocol instance receives an incoming packet. If there is a waiting token for incoming packets, the CompletionToken.Packet.RxData field is updated to this incoming packet and the CompletionToken.Event is signaled. The EFI UDPv4 Protocol client must signal the RecycleSignal after processing the packet.

- FragmentTable could contain multiple buffers that are not in the continuous memory locations. The EFI UDPv4 Protocol client might need to combine two or more buffers in FragmentTable to form their own protocol header.

```c
typedef struct {
    EFI_IPv4_ADDRESS SourceAddress;
    UINT16 SourcePort;
    EFI_IPv4_ADDRESS DestinationAddress;
    UINT16 DestinationPort;
} EFI_UDP4_SESSION_DATA;
```

SourceAddress
Address from which this packet is sent. If this field is set to zero when sending packets, the address that is assigned in EFI_UDP4_PROTOCOL.Configure() is used.

SourcePort
Port from which this packet is sent. It is in host byte order. If this field is set to zero when sending packets, the port that is assigned in EFI_UDP4_PROTOCOL.Config() is used. If this field is set to zero and unbound, a call to EFI_UDP4_PROTOCOL.Transmit() will fail.

DestinationAddress
Address to which this packet is sent.

DestinationPort
Port to which this packet is sent. It is in host byte order. If this field is set to zero and unconnected, the call to EFI_UDP4_PROTOCOL.Transmit() will fail.

The EFI_UDP4_SESSION_DATA is used to retrieve the settings when receiving packets or to override the existing settings of this EFI UDPv4 Protocol instance when sending packets.

```c
(continues on next page)
```
typedef struct {
    UINT32 FragmentLength;
    VOID *FragmentBuffer;
} EFI_UDP4_FRAGMENT_DATA;

**FragmentLength**

Length of the fragment data buffer.

**FragmentBuffer**

Pointer to the fragment data buffer.

*EFI_UDP4_FRAGMENT_DATA* allows multiple receive or transmit buffers to be specified. The purpose of this structure is to avoid copying the same packet multiple times.

typedef struct {
    EFI_UDP4_SESSION_DATA *UdpSessionData;
    EFI_IPv4_ADDRESS *GatewayAddress;
    UINT32 DataLength;
    UINT32 FragmentCount;
    EFI_UDP4_FRAGMENT_DATA FragmentTable[1];
} EFI_UDP4_TRANSMIT_DATA;

**UdpSessionData**

If not NULL, the data that is used to override the transmitting settings. Type *EFI_UDP4_SESSION_DATA* is defined above.

**GatewayAddress**

The next-hop address to override the setting from the routing table.

**DataLength**

Sum of the fragment data length. Must not exceed the maximum UDP packet size.

**FragmentCount**

Number of fragments.

**FragmentTable**

Array of fragment descriptors. Type *EFI_UDP4_FRAGMENT_DATA* is defined above.

The EFI UDPv4 Protocol client must fill this data structure before sending a packet. The packet may contain multiple buffers that may be not in a continuous memory location.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data has been queued for transmission.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI UDPv4 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
</tbody>
</table>
### EFI_INVALID_PARAMETER

One or more of the following are **TRUE**:

- **This** is **NULL**.
- **Token** is **NULL**.
- **Token.Event** is **NULL**.
- **Token.Packet.TxData** is **NULL**.
- **Token.Packet.TxData.FragmentCount** is zero.
- **Token.Packet.TxData.DataLength** is not equal to the sum of fragment lengths.
- One or more of the **Token.Packet.TxData.FragmentTable[i].FragmentLength** fields is zero.
- One or more of the **Token.Packet.TxData.FragmentTable[i].FragmentBuffer** fields is **NULL**.
- **Token.Packet.TxData.GatewayAddress** is not a unicast IPv4 address if it is not **NULL**.
- **Token.Packet.TxData.UdpSessionData.SourceAddress** is not a valid unicast IPv4 address or **Token.Packet.TxData.UdpSessionData.DestinationAddress** is zero if the **UdpSessionData** is not **NULL**.

### EFI_ACCESS_DENIED

The transmit completion token with the same **Token.Event** was already in the transmit queue.

### EFI_NOT_READY

The completion token could not be queued because the transmit queue is full.

### EFI_OUT_OF_RESOURCES

Could not queue the transmit data.

### EFI_NOT_FOUND

There is no route to the destination network or address.

### EFI_BAD_BUFFER_SIZE

The data length is greater than the maximum UDP packet size. Or the length of the IP header + UDP header + data length is greater than MTU if DoNotFragment is **TRUE**.

### EFI_NO_MEDIA

There was a media error.

### 30.1.2.7 EFI_UDP4_PROTOCOL.Receive()

#### Summary

Places an asynchronous receive request into the receiving queue.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_UDP4_RECEIVE) (  
  IN EFI_UDP4_PROTOCOL *This,  
  IN EFI_UDP4_COMPLETION_TOKEN *Token  
);
```

#### Parameters

**This**

Pointer to the **EFI_UDP4_PROTOCOL** instance.

**Token**

Pointer to a token that is associated with the receive data descriptor. Type **EFI_UDP4_COMPLETION_TOKEN**
is defined in \textit{EFI_UDP4\_PROTOCOL\_Transmit()}.\n
\textbf{Description}\n
The \textit{Receive()} function places a completion token into the receive packet queue. This function is always asynchronous. The caller must fill in the \textit{Token.Event} field in the completion token, and this field cannot be \textbf{NULL}. When the receive operation completes, the EFI UDPv4 Protocol driver updates the \textit{Token.Status} and \textit{Token.Packet.RxData} fields and the \textit{Token.Event} is signaled. Providing a proper notification function and context for the event will enable the user to receive the notification and receiving status. That notification function is guaranteed to not be re-entered.

\textbf{Status Codes Returned}\n
<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The receive completion token was cached.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI UDPv4 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is \textbf{TRUE}:</td>
</tr>
<tr>
<td></td>
<td>$$\bullet$$ \textit{This} is \textbf{NULL}.</td>
</tr>
<tr>
<td></td>
<td>$$\bullet$$ \textit{Token} is \textbf{NULL}.</td>
</tr>
<tr>
<td></td>
<td>$$\bullet$$ \textit{Token.Event} is \textbf{NULL}.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The receive completion token could not be queued due to a lack of system resources (usually memory).</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The EFI UDPv4 Protocol instance has been reset to startup defaults.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>A receive completion token with the same \textit{Token.Event} was already in the receive queue.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The receive request could not be queued because the receive queue is full.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

\textbf{30.1.2.8 EFI\_UDP4\_PROTOCOL\_Cancel()}

\textbf{Summary}\n
Aborts an asynchronous transmit or receive request.

\textbf{Prototype}\n
\begin{verbatim}
typedef EFI\_STATUS
(EFIAPI *EFI\_UDP4\_CANCEL)(
    IN EFI\_UDP4\_PROTOCOL *This,
    IN EFI\_UDP4\_COMPLETION\_TOKEN *Token OPTIONAL);
\end{verbatim}

\textbf{Parameters}\n
\textbf{This}\n
Pointer to the \textit{EFI\_UDP4\_PROTOCOL} instance.

\textbf{Token}\n
Pointer to a token that has been issued by \textit{EFI\_UDP4\_PROTOCOL\_Transmit()} or \textit{EFI\_UDP4\_PROTOCOL\_Receive()}. If \textbf{NULL}, all pending tokens are aborted. Type \textit{EFI\_UDP4\_COMPLETION\_TOKEN} is defined in \textit{EFI\_UDP4\_PROTOCOL\_Transmit()}.\n
30.1. EFI UDP Protocol 1449
Description

The *Cancel()* function is used to abort a pending transmit or receive request. If the token is in the transmit or receive request queues, after calling this function, *Token.Status* will be set to *EFI_ABORTED* and then *Token.Event* will be signaled. If the token is not in one of the queues, which usually means that the asynchronous operation has completed, this function will not signal the token and *EFI_NOT_FOUND* is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The asynchronous I/O request was aborted and <em>Token.Event</em> was signaled. When <em>Token</em> is <strong>NULL</strong>, all pending requests are aborted and their events are signaled.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><em>This</em> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using the default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
</tbody>
</table>
| EFI_NOT_FOUND       | When *Token* is not **NULL**, the asynchronous I/O request was not found in the transmit or receive queue. It has either completed or was not issued by *Transmit()* and *Receive()*.

30.1.2.9 EFI_UDP4_PROTOCOL.Poll()

Summary

Polls for incoming data packets and processes outgoing data packets.

Prototype

```c
typedef EFI_STATUS
(EFIAPI *EFI_UDP4_POLL) (
    IN EFI_UDP4_PROTOCOL       *This
);
```

Parameters

This

Pointer to the *EFI_UDP4_PROTOCOL* instance.

Description

The *Poll()* function can be used by network drivers and applications to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

In some systems, the periodic timer event in the managed network driver may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the *Poll()* function more often.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><em>This</em> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Data was dropped out of the transmit and/or receive queue. Consider increasing the polling rate.</td>
</tr>
</tbody>
</table>
30.2 EFI UDPv6 Protocol

This section defines the EFI UDPv6 (User Datagram Protocol version 6) Protocol that interfaces over the EFI IPv6 Protocol.

30.2.1 UDP6 Service Binding Protocol

30.2.1.1 EFI_UDP6_SERVICE_BINDING_PROTOCOL

Summary

The EFI UDPv6 Service Binding Protocol is used to locate communication devices that are supported by an EFI UDPv6 Protocol driver and to create and destroy instances of the EFI UDPv6 Protocol child instance that uses the underlying communications device.

GUID

```
#define EFI_UDP6_SERVICE_BINDING_PROTOCOL_GUID \
{0x66ed4721, 0x3c98, 0x4d3e,\ 
{0x81, 0xe3, 0xd0, 0x3d, 0xd3, 0x9a, 0x72, 0x54}}
```

Description

A network application that requires basic UDPv6 I/O services can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish a EFI UDPv6 Service Binding Protocol GUID. Each device with a published EFI UDPv6 Service Binding Protocol GUID supports the EFI UDPv6 Protocol and may be available for use.

After a successful call to the `EFI_UDP6_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the newly created child EFI UDPv6 Protocol driver is in an un-configured state; it is not ready to send and receive data packets.

Before a network application terminates execution, every successful call to the `EFI_UDP6_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI_UDP6_SERVICE_BINDING_PROTOCOL.DestroyChild()` function.

30.2.2 EFI UDP6 Protocol

30.2.2.1 EFI_UDP6_PROTOCOL

Summary

The EFI UDPv6 Protocol provides simple packet-oriented services to transmit and receive UDP packets.

GUID

```
#define EFI_UDP6_PROTOCOL_GUID \
{0x4f948815, 0xb4b9, 0x43cb,\ 
{0x8a, 0x33, 0x90, 0xe0, 0x60, 0xb3, 0x49, 0x55}}
```

Protocol Interface Structure

```
typedef struct _EFI_UDP6_PROTOCOL { 
    EFI_UDP6_GET_MODE_DATA GetModeData; 
    EFI_UDP6_CONFIGURE Configure; 
} EFI_UDP6_PROTOCOL;
```

(continues on next page)
Parameters

GetModeData
Reads the current operational settings. See the GetModeData() function description.

Configure
Initializes, changes, or resets operational settings for the EFI UDPv6 Protocol. See the Configure() function description.

Groups
Joins and leaves multicast groups. See the Groups() function description.

Transmit
Queues outgoing data packets into the transmit queue. This function is a non-blocked operation. See the Transmit() function description.

Receive
Places a receiving request token into the receiving queue. This function is a non-blocked operation. See the Receive() function description.

Cancel
Aborts a pending transmit or receive request. See the Cancel() function description.

Poll
Polls for incoming data packets and processes outgoing data packets. See the Poll() function description.

Description
The EFI_UDP6_PROTOCOL defines an EFI UDPv6 Protocol session that can be used by any network drivers, applications, or daemons to transmit or receive UDP packets. This protocol instance can either be bound to a specified port as a service or connected to some remote peer as an active client. Each instance has its own settings, such as group table, that are independent from each other.

Note: Byte Order: In this document, all IPv6 addresses and incoming/outgoing packets are stored in network byte order. All other parameters in the functions and data structures that are defined in this document are stored in host byte order.

30.2.2.2 EFI_UDP6_PROTOCOL.GetModeData()

Summary
Read the current operational settings.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI * EFI_UDP6_GET_MODE_DATA) ( 
```
Parameters

This

Pointer to the EFI_UDP6_PROTOCOL instance.

Udp6ConfigData

The buffer in which the current UDP configuration data is returned. Type EFI_UDP6_CONFIG_DATA is defined in “Related Definitions” below.

Ip6ModeData

The buffer in which the current EFI IPv6 Protocol mode data is returned. Type EFI_IP6_MODE_DATA is defined in EFI_IP6_PROTOCOL.GetModeData().

MnpConfigData

The buffer in which the current managed network configuration data is returned. Type EFI_MANAGED_NETWORK_CONFIG_DATA is defined in EFI_MANAGED_NETWORK_PROTOCOL.GetModeData().

SnpModeData

The buffer in which the simple network mode data is returned. Type EFI_SIMPLE_NETWORK_MODE is defined in the EFI_SIMPLE_NETWORK Protocol.

Description

The GetModeData() function copies the current operational settings of this EFI UDPv6 Protocol instance into user-supplied buffers. This function is used optionally to retrieve the operational mode data of underlying networks or drivers.

Related Definition

```
// EFI_UDP6_CONFIG_DATA
typings struct {
    // Receiving Filters
    BOOLEAN AcceptPromiscuous;
    BOOLEAN AcceptAnyPort;
    BOOLEAN AllowDuplicatePort;
    // I/O parameters
    ;
    UINT8 TrafficClass;
    UINT8 HopLimit;
    ;
    UINT32 ReceiveTimeout;
    UINT32 TransmitTimeout;
    // Access Point
```

(continues on next page)
AcceptPromiscuous
Set to TRUE to accept UDP packets that are sent to any address.

AcceptAnyPort
Set to TRUE to accept UDP packets that are sent to any port.

AllowDuplicatePort
Set to TRUE to allow this EFI UDPv6 Protocol child instance to open a port number that is already being used by another EFI UDPv6 Protocol child instance.

TrafficClass
TrafficClass field in transmitted IPv6 packets.

HopLimit
HopLimit field in transmitted IPv6 packets.

ReceiveTimeout
The receive timeout value (number of microseconds) to be associated with each incoming packet. Zero means do not drop incoming packets.

TransmitTimeout
The transmit timeout value (number of microseconds) to be associated with each outgoing packet. Zero means do not drop outgoing packets.

StationAddress
The station IP address that will be assigned to this EFI UDPv6 Protocol instance. The EFI UDPv6 and EFI IPv6 Protocol drivers will only deliver incoming packets whose destination matches this IP address exactly. Address 0:/128 is also accepted as a special case. Under this situation, underlying IPv6 driver is responsible for binding a source address to this EFI IPv6 protocol instance according to source address selection algorithm. Only incoming packet from the selected source address is delivered. This field can be set and changed only when the EFI IPv6 driver is transitioning from the stopped to the started states. If no address is available for selecting, the EFI IPv6 Protocol driver will use EFI_IP6_CONFIG_PROTOCOL to retrieve the IPv6 address.

StationPort
The port number to which this EFI UDPv6 Protocol instance is bound. If a client of the EFI UDPv6 Protocol does not care about the port number, set StationPort to zero. The EFI UDPv6 Protocol driver will assign a random port number to transmitted UDP packets. Ignored it if AcceptAnyPort is TRUE.

RemoteAddress
The IP address of remote host to which this EFI UDPv6 Protocol instance is connecting. If RemoteAddress is not 0:/128, this EFI UDPv6 Protocol instance will be connected to RemoteAddress; i.e., outgoing packets of this EFI UDPv6 Protocol instance will be sent to this address by default and only incoming packets from this address will be delivered to client. Ignored for incoming filtering if AcceptPromiscuous is TRUE.

RemotePort
The port number of the remote host to which this EFI UDPv6 Protocol instance is connecting. If it is not zero, outgoing packets of this EFI UDPv6 Protocol instance will be sent to this port number by default and only incoming packets from this port will be delivered to client. Ignored if RemoteAddress is 0:/128 and ignored for incoming filtering if AcceptPromiscuous is TRUE.

Status Codes Returned
30.2.2.3 EFI_UDP6_PROTOCOL.Configure()

Summary

Initializes, changes, or resets the operational parameters for this instance of the EFI UDPv6 Protocol.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_UDP6_CONFIGURE) (
    IN EFI_UDP6_PROTOCOL *This,
    IN EFI_UDP6_CONFIG_DATA *UdpConfigData OPTIONAL
);
```

Parameters

This

Pointer to the EFI_UDP6_PROTOCOL instance.

UdpConfigData

Pointer to the buffer contained the configuration data.

Description

The Configure() function is used to do the following:

- Initialize and start this instance of the EFI UDPv6 Protocol.
- Change the filtering rules and operational parameters.
- Reset this instance of the EFI UDPv6 Protocol.

Until these parameters are initialized, no network traffic can be sent or received by this instance. This instance can be also reset by calling Configure() with UdpConfigData set to NULL. Once reset, the receiving queue and transmitting queue are flushed and no traffic is allowed through this instance.

With different parameters in UdpConfigData, Configure() can be used to bind this instance to specified port.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The configuration settings were set, changed, or reset successfully.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The underlying IPv6 driver was responsible for choosing a source address for this instance, but no source address was available for use.</td>
</tr>
</tbody>
</table>
Table 30.10 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
</table>
| EFI_INVALID_PARAMETER  | One or more following conditions are **TRUE**:  
This is **NULL**.  
UdpConfigData.StationAddress neither zero nor one of the configured IP addresses in the underlying IPv6 driver.  
UdpConfigData.RemoteAddress is not a valid unicast IPv6 address if it is not zero. |
| EFI_ALREADY_STARTED    | The EFI UDPv6 Protocol instance is already started/configured and must be stopped/reset before it can be reconfigured. Only TrafficClass, HopLimit, ReceiveTimeout, and TransmitTimeout can be reconfigured without stopping the current instance of the EFI UDPv6 Protocol. |
| EFI_ACCESS_DENIED      | UdpConfigData. AllowDuplicatePort is **FALSE** and UdpConfigData.StationPort is already used by other instance. |
| EFI_OUT_OF_RESOURCES   | The EFI UDPv6 Protocol driver cannot allocate memory for this EFI UDPv6 Protocol instance.             |
| EFI_DEVICE_ERROR       | An unexpected network or system error occurred and this instance was not opened.                       |

### 30.2.2.4 EFI_UDP6_PROTOCOL.Groups()

**Summary**

Joins and leaves multicast groups.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_UDP6_GROUPS) (
    IN EFI_UDP6_PROTOCOL *This,
    IN BOOLEAN JoinFlag,
    IN EFI_IPv6_ADDRESS *MulticastAddress OPTIONAL
);
```

**Parameters**

**This**

Pointer to the **EFI_UDP6_PROTOCOL** instance.

**JoinFlag**

Set to **TRUE** to join a multicast group. Set to **FALSE** to leave one or all multicast groups.

**MulticastAddress**

Pointer to multicast group address to join or leave.

**Description**

The **Groups ()** function is used to join or leave one or more multicast group.

If the **JoinFlag** is **FALSE** and the **MulticastAddress** is **NULL**, then all currently joined groups are left.

**Status Codes Returned**
<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The operation completed successfully.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI UDPv6 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate resources to join the group.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER| One or more of the following conditions is TRUE:  
|                     | This is NULL.  
|                     | JoinFlag is TRUE and MulticastAddress is *NULL*.  
|                     | JoinFlag is TRUE and **MulticastAddress* is not a valid multicast address. |
| EFI_ALREADY_STARTED | The group address is already in the group table (when JoinFlag is TRUE). |
| EFI_NOT_FOUND       | The group address is not in the group table (when JoinFlag is FALSE). |
| EFI_DEVICE_ERROR    | An unexpected system or network error occurred. |

### 30.2.2.5 EFI_UDP6_PROTOCOL.Transmit()

**Summary**

Queues outgoing data packets into the transmit queue.

**Prototype**

```c
typedef EFI_STATUS
  (EFIAPI *EFI_UDP6_TRANSMIT) (  
    IN EFI_UDP6_PROTOCOL *This,  
    IN EFI_UDP6_COMPLETION_TOKEN *Token  
  );
```

**Parameters**

- **This**
  Pointer to the `EFI_UDP6_PROTOCOL` instance.

- **Token**
  Pointer to the completion token that will be placed into the transmit queue. Type `EFI_UDP6_COMPLETION_TOKEN` is defined in “Related Definitions” below.

**Description**

The `Transmit()` function places a sending request to this instance of the EFI UDPv6 Protocol, alongside the transmit data that was filled by the user. Whenever the packet in the token is sent out or some errors occur, the `Token.Event` will be signaled and `Token.Status` is updated. Providing a proper notification function and context for the event will enable the user to receive the notification and transmitting status.

**Related Definitions**

```c
//***************************************************************************
// EFI_UDP6_COMPLETION_TOKEN
//***************************************************************************
typedef struct {
    EFI_EVENT Event;
    EFI_STATUS Status;
    union {
        EFI_UDP6_RECEIVE_DATA *RxData;
    }
} EFI_UDP6_COMPLETION_TOKEN;
```

(continues on next page)
Event

This Event will be signaled after the Status field is updated by the EFI UDPv6 Protocol driver. The type of Event must be EVT_NOTIFY_SIGNAL.

Status

Will be set to one of the following values:

- **EFI_SUCCESS**: The receive or transmit operation completed successfully.
- **EFI_ABORTED**: The receive or transmit was aborted.
- **EFI_TIMEOUT**: The transmit timeout expired.
- **EFI_NETWORK_UNREACHABLE**: The destination network is unreachable. RxData is set to NULL in this situation.
- **EFI_HOST_UNREACHABLE**: The destination host is unreachable. RxData is set to NULL in this situation.
- **EFI_PROTOCOL_UNREACHABLE**: The UDP protocol is unsupported in the remote system. RxData is set to NULL in this situation.
- **EFI_PORT_UNREACHABLE**: No service is listening on the remote port. RxData is set to NULL in this situation.
- **EFI_ICMP_ERROR**: Some other Internet Control Message Protocol (ICMP) error report was received. For example, packets are being sent too fast for the destination to receive them and the destination sent an ICMP source quench report. RxData is set to NULL in this situation.
- **EFI_DEVICE_ERROR**: An unexpected system or network error occurred.
- **EFI_SECURITY_VIOLATION**: The transmit or receive was failed because of IPsec policy check.

RxData

When this token is used for receiving, RxData is a pointer to EFI_UDP6_RECEIVE_DATA. Type EFI_UDP6_RECEIVE_DATA is defined below.

TxData

When this token is used for transmitting, TxData is a pointer to EFI_UDP6_TRANSMIT_DATA. Type EFI_UDP6_TRANSMIT_DATA is defined below.

The EFI_UDP6_COMPLETION_TOKEN structures are used for both transmit and receive operations.

When used for transmitting, the Event and TxData fields must be filled in by the EFI UDPv6 Protocol client. After the transmit operation completes, the Status field is updated by the EFI UDPv6 Protocol and the Event is signaled.

When used for receiving, only the Event field must be filled in by the EFI UDPv6 Protocol client. After a packet is received, RxData and Status are filled in by the EFI UDPv6 Protocol and the Event is signaled.
UINT32 FragmentCount;
EFI_UDP6_FRAGMENT_DATA FragmentTable [1];
} EFI_UDP6_RECEIVE_DATA;

TimeStamp
Time when the EFI UDPv6 Protocol accepted the packet. TimeStamp is zero filled if timestamps are disabled or unsupported.

RecycleSignal
Indicates the event to signal when the received data has been processed.

UdpSession
The UDP session data including SourceAddress, SourcePort, DestinationAddress, and DestinationPort. Type EFI_UDP6_SESSION_DATA is defined below.

DataLength
The sum of the fragment data length.

FragmentCount
Number of fragments. Maybe zero.

FragmentTable
Array of fragment descriptors. Maybe zero. Type EFI_UDP6_FRAGMENT_DATA is defined below.

EFI_UDP6_RECEIVE_DATA is filled by the EFI UDPv6 Protocol driver when this EFI UDPv6 Protocol instance receives an incoming packet. If there is a waiting token for incoming packets, the CompletionToken.Packet.RxData field is updated to this incoming packet and the CompletionToken.Event is signaled. The EFI UDPv6 Protocol client must signal the RecycleSignal after processing the packet.

FragmentTable could contain multiple buffers that are not in the continuous memory locations. The EFI UDPv6 Protocol client might need to combine two or more buffers in FragmentTable to form their own protocol header.

/*----------------------------------------
 // EFI_UDP6_SESSION_DATA
 /*----------------------------------------*/
typedef struct {
    EFI_IPv6_ADDRESS SourceAddress;
    UINT16 SourcePort;
    EFI_IPv6_ADDRESS DestinationAddress;
    UINT16 DestinationPort;
} EFI_UDP6_SESSION_DATA;

SourceAddress
Address from which this packet is sent. This field should not be used when sending packets.

SourcePort
Port from which this packet is sent. It is in host byte order. This field should not be used when sending packets.

DestinationAddress
Address to which this packet is sent. When sending packet, it’ll be ignored if it is zero.

DestinationPort
Port to which this packet is sent. When sending packet, it’ll be ignored if it is zero.

The EFI_UDP6_SESSION_DATA is used to retrieve the settings when receiving packets or to override the existing settings (only DestinationAddress and DestinationPort can be overridden) of this EFI UDPv6 Protocol instance when sending packets.
typedef struct {
    UINT32 FragmentLength;
    VOID *FragmentBuffer;
} EFI_UDP6_FRAGMENT_DATA;

**FragmentLength**
Length of the fragment data buffer.

**FragmentBuffer**
Pointer to the fragment data buffer.

*EFI_UDP6_FRAGMENT_DATA* allows multiple receive or transmit buffers to be specified. The purpose of this structure is to avoid copying the same packet multiple times.

typedef struct {
    EFI_UDP6_SESSION_DATA *UdpSessionData;
    UINT32 DataLength;
    UINT32 FragmentCount;
    EFI_UDP6_FRAGMENT_DATA FragmentTable [1];
} EFI_UDP6_TRANSMIT_DATA;

**UdpSessionData** If not **NULL**, the data that is used to override the transmitting settings. Only the two fields **UdpSessionData.DestinationAddress** and **UdpSessionData.DestinationPort** can be used as the transmitting setting filed. Type **EFI_UDP6_SESSION_DATA** is defined above.

**DataLength**
Sum of the fragment data length. Must not exceed the maximum UDP packet size.

**FragmentCount**
Number of fragments.

**FragmentTable**
Array of fragment descriptors. Type **EFI_UDP6_FRAGMENT_DATA** is defined above.

The EFI UDPv6 Protocol client must fill this data structure before sending a packet. The packet may contain multiple buffers that may not be in a continuous memory location.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data has been queued for transmission.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI UDPv6 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The underlying IPv6 driver was responsible for choosing a source address for this instance, but no source address was available for use.</td>
</tr>
</tbody>
</table>
Table 30.12 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
</table>
| EFI_INVALID_PARAMETER       | One or more of the following are **TRUE**:
|                             | *This* is **NULL**.                                                         |
|                             | *Token* is **NULL**.                                                        |
|                             | *Token.Event* is **NULL**.                                                  |
|                             | *Token.Packet.TxData* is **NULL**.                                          |
|                             | *Token.Packet.TxData.FragmentCount* is zero.                                |
|                             | *Token.Packet.TxData.DataLength* is not equal to the sum of fragment       |
|                             | lengths.                                                                    |
|                             | One or more of the *Token.Packet.TxData.FragmentTable[i].FragmentLength*   |
|                             | fields is zero.                                                            |
|                             | One or more of the *Token.Packet.TxData.FragmentTable[i].FragmentBuffer*   |
|                             | fields is **NULL**.                                                        |
|                             | Token.Packet.TxData.UdpSessionData.DestinationAddress is not zero and       |
|                             | is not valid unicast Ipv6 address if UdpSessionData is not **NULL**.        |
|                             | Token.Packet.TxData.UdpSessionData is **NULL** and this instance’s Udp    |
|                             | ConfigData. RemoteAddress is unspecified.                                   |
|                             | Token.Packet.TxData.UdpSessionData.DestinationAddress is non-zero           |
|                             | when DestinationAddress is configured as non-zero when doing Configure() for |
|                             | this EFI Udp6 protocol instance.                                            |
|                             | Token.Packet.TxData.UdpSessionData.DestinationAddress is zero when          |
|                             | DestinationAddress is unspecified when doing Configure() for this EFI Udp  |
|                             | 6 protocol instance                                                       |
| EFI_ACCESS_DENIED           | The transmit completion token with the same Token.Event was already in the  |
|                             | transmit queue.                                                            |
| EFI_NOT_READY               | The completion token could not be queued because the transmit queue is     |
|                             | full.                                                                      |
| EFI_OUT_OF_RESOURCES        | Could not queue the transmit data.                                         |
| EFI_NOT_FOUND               | There is no route to the destination network or address.                   |
| EFI_BAD_BUFFER_SIZE         | The data length is greater than the maximum UDP packet size.               |
| EFI_NO_MEDIA                | There was a media error.                                                   |

30.2.2.6 EFI_UDP6_PROTOCOL.Receive()

**Summary**

Places an asynchronous receive request into the receiving queue.

**Prototype**

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_UDP6_RECEIVE) (  
    IN EFI_UDP6_PROTOCOL *This,
    IN EFI_UDP6_COMPLETION_TOKEN *Token*
);
```

**Parameters**
This

Pointer to the \textit{EFI_USER6\_PROTOCOL} instance.

Token

Pointer to a token that is associated with the receive data descriptor. Type \textit{EFI_USER6\_COMPLETION\_TOKEN} is defined in \textit{EFI_USER6\_PROTOCOL}.\texttt{Transmit()}. 

Description

The \texttt{Receive()} function places a completion token into the receive packet queue. This function is always asynchronous. The caller must fill in the \texttt{Token.Event} field in the completion token, and this field cannot be \texttt{NULL}. When the receive operation completes, the EFI UDPv6 Protocol driver updates the \texttt{Token.Status} and \texttt{Token.Packet.RxData} fields and the \texttt{Token.Event} is signaled. Providing a proper notification function and context for the event will enable the user to receive the notification and receiving status. That notification function is guaranteed to not be re-entered.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The receive completion token was cached.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI UDPv6 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The underlying IPv6 driver was responsible for choosing a source address for this instance, but no source address was available for use.</td>
</tr>
</tbody>
</table>
| EFI\_INVALID\_PARAMETER   | One or more of the following conditions is \texttt{TRUE}:
|                           | \texttt{This} is \texttt{NULL}.
|                           | \texttt{Token} is \texttt{NULL}.
|                           | \texttt{Token.Event} is \texttt{NULL}.                                    |
| EFI\_OUT\_OF\_RESOURCES  | The receive completion token could not be queued due to a lack of system resources (usually memory). |
| EFI\_DEVICE\_ERROR        | An unexpected system or network error occurred. The EFI UDPv6 Protocol instance has been reset to startup defaults. |
| EFI\_ACCESS\_DENIED       | A receive completion token with the same \texttt{Token.Event} was already in the receive queue. |
| EFI\_NOT\_READY           | The receive request could not be queued because the receive queue is full.  |
| EFI\_NO\_MEDIA            | There was a media error.                                                   |

30.2.2.7 \texttt{EFI\_UDP6\_PROTOCOL}.\texttt{Cancel()}

Summary

Aborts an asynchronous transmit or receive request.

Prototype

\begin{verbatim}
typedef EFI\_STATUS
  (EFI\_API \*EFI\_UDP6\_CANCEL)(
    IN EFI\_UDP6\_PROTOCOL \*This,
    IN EFI\_UDP6\_COMPLETION\_TOKEN \*Token OPTIONAL
  );
\end{verbatim}

Parameters

This

Pointer to the \textit{EFI\_UDP6\_PROTOCOL} instance.
Token
Pointer to a token that has been issued by \textit{EFI_UDP6\_PROTOCOL.Transmit()} or \textit{EFI_UDP6\_PROTOCOL.Receive()}. If \textbf{NULL}, all pending tokens are aborted. Type \textit{EFI\_UDP6\_COMPLETION\_TOKEN} is defined in \textit{EFI_UDP6\_PROTOCOL.Transmit()}.

Description
The Cancel() function is used to abort a pending transmit or receive request. If the token is in the transmit or receive request queues, after calling this function, \textit{Token.Status} will be set to \textbf{EFI\_ABORTED} and then \textit{Token.Event} will be signaled. If the token is not in one of the queues, which usually means that the asynchronous operation has completed, this function will not signal the token and \textbf{EFI\_NOT\_FOUND} is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\textbf{EFI_SUCCESS}</td>
<td>The asynchronous I/O request was aborted and \textit{Token.Event} was signaled. When \textit{Token} is \textbf{NULL}, all pending requests are aborted and their events are signaled.</td>
</tr>
<tr>
<td>\textbf{EFI_INVALID_PARAMETER}</td>
<td>This is \textbf{NULL}.</td>
</tr>
<tr>
<td>\textbf{EFI_NOT_STARTED}</td>
<td>This instance has not been started.</td>
</tr>
<tr>
<td>\textbf{EFI_NOT_FOUND}</td>
<td>When \textit{Token} is not \textbf{NULL}, the asynchronous I/O request was not found in the transmit or receive queue. It has either completed or was not issued by \textit{Transmit()} and \textit{Receive()}.</td>
</tr>
</tbody>
</table>

30.2.2.8 \textbf{EFI\_UDP6\_PROTOCOL.Poll()}

Summary
Polls for incoming data packets and processes outgoing data packets.

Prototype

```c
typedef EFI\_STATUS (EFI\_API *EFI\_UDP6\_POLL) (  
    IN EFI\_UDP6\_PROTOCOL *This  
);
```

Parameters

\textbf{This}
Pointer to the \textit{EFI\_UDP6\_PROTOCOL} instance.

Description

The \textit{Poll()} function can be used by network drivers and applications to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

In some systems, the periodic timer event in the managed network driver may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the \textit{Poll()} function more often.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\textbf{EFI_SUCCESS}</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>\textbf{EFI_INVALID_PARAMETER}</td>
<td>\textit{This} is \textbf{NULL}.</td>
</tr>
<tr>
<td>\textbf{EFI_DEVICE_ERROR}</td>
<td>An unexpected system or network error occurred.</td>
</tr>
</tbody>
</table>

continues on next page
Table 30.15 – continued from previous page

| EFI_TIMEOUT | Data was dropped out of the transmit and/or receive queue. Consider increasing the polling rate. |

### 30.3 EFI MTFTPv4 Protocol

The following sections defines the EFI MTFTPv4 Protocol interface that is built upon the EFI UDPv4 Protocol.

#### 30.3.1 EFI_MTFTP4_SERVICE_BINDING_PROTOCOL

**Summary**

The EFI MTFTPv4 Service Binding Protocol is used to locate communication devices that are supported by an EFI MTFTPv4 Protocol driver and to create and destroy instances of the EFI MTFTPv4 Protocol child protocol driver that can use the underlying communications device.

**GUID**

```
#define EFI_MTFTP4_SERVICE_BINDING_PROTOCOL_GUID {
    0x2e800be, 0x8f01, 0x4aa6,
    {0x94, 0x6b, 0xd7, 0x13, 0x88, 0xe1, 0x83, 0x3f}
```

**Description**

A network application or driver that requires MTFTPv4 I/O services can use one of the protocol handler services, such as `BS->LocateHandleBuffer()`, to search for devices that publish an EFI MTFTPv4 Service Binding Protocol GUID. Each device with a published EFI MTFTPv4 Service Binding Protocol GUID supports the EFI MTFTPv4 Protocol service and may be available for use.

After a successful call to the `EFI_MTFTP4_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the newly created child EFI MTFTPv4 Protocol driver instance is in an unconfigured state; it is not ready to transfer data.

Before a network application terminates execution, every successful call to the `EFI_MTFTP4_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI_MTFTP4_SERVICE_BINDING_PROTOCOL.DestroyChild()` function.

Each instance of the EFI MTFTPv4 Protocol driver can support one file transfer operation at a time. To download two files at the same time, two instances of the EFI MTFTPv4 Protocol driver will need to be created.

#### 30.3.2 EFI_MTFTP4_PROTOCOL

**Summary**

The EFI MTFTPv4 Protocol provides basic services for client-side unicast and/or multicast TFTP operations.

**GUID**

```
#define EFI_MTFTP4_PROTOCOL_GUID {
    0x78247c57, 0x63db, 0x4708,
    {0x99, 0xc2, 0xa8, 0xb4, 0xa9, 0xa6, 0x1f, 0x6b}
```

**Protocol Interface Structure**
typedef struct _EFI_MTFTP4_PROTOCOL {
    EFI_MTFTP4_GET_MODE_DATA GetModeData;
    EFI_MTFTP4_CONFIGURE Configure;
    EFI_MTFTP4_GET_INFO GetInfo;
    EFI_MTFTP4_PARSE_OPTIONS ParseOptions;
    EFI_MTFTP4_READ_FILE ReadFile;
    EFI_MTFTP4_WRITE_FILE WriteFile;
    EFI_MTFTP4_READ_DIRECTORY ReadDirectory;
    EFI_MTFTP4_POLL Poll;
} EFI_MTFTP4_PROTOCOL;

Parameters

GetModeData
Reads the current operational settings. See the GetModeData() function description.

Configure
Initializes, changes, or resets the operational settings for this instance of the EFI MTFTPv4 Protocol driver. See the Configure() function description.

GetInfo
Retrieves information about a file from an MTFTPv4 server. See the GetInfo() function description.

ParseOptions
Parses the options in an MTFTPv4 OACK (options acknowledgement) packet. See the ParseOptions() function description.

ReadFile
Downloads a file from an MTFTPv4 server. See the ReadFile() function description.

WriteFile
Uploads a file to an MTFTPv4 server. This function may be unsupported in some EFI implementations. See the WriteFile() function description.

ReadDirectory
Downloads a related file "directory" from an MTFTPv4 server. This function may be unsupported in some EFI implementations. See the ReadDirectory() function description.

Poll
Polls for incoming data packets and processes outgoing data packets. See the Poll() function description.

Description

The EFI_MTFTP4_PROTOCOL is designed to be used by UEFI drivers and applications to transmit and receive data files. The EFI MTFTPv4 Protocol driver uses the underlying EFI UDPv4 Protocol driver and EFI IPv4 Protocol driver.

30.3.3 EFI_MTFTP4_PROTOCOL.GetModeData()

Summary

Reads the current operational settings.

Prototype

typedef

(continues on next page)
OUT EFI_MTFTP4_MODE_DATA *ModeData
);

Parameters

This

Pointer to the EFI_MTFTP4_PROTOCOL instance.

ModeData

Pointer to storage for the EFI MTFTPv4 Protocol driver mode data. Type EFI_MTFTP4_MODE_DATA is defined in “Related Definitions” below.

Description

The GetModeData() function reads the current operational settings of this EFI MTFTPv4 Protocol driver instance.

Related Definitions

//************************************************
// EFI_MTFTP4_MODE_DATA
//************************************************
typedef struct {
  EFI_MTFTP4_CONFIG_DATA ConfigData;
  UINT8 SupportedOptionCount;
  UINT8 **SupportedOptions;
  UINT8 UnsupportedOptionCount;
  UINT8 **UnsupportedOptions;
} EFI_MTFTP4_MODE_DATA;

ConfigData

The configuration data of this instance. Type EFI_MTFTP4_CONFIG_DATA is defined below.

SupportedOptionCount

The number of option strings in the following SupportedOptions array.

SupportedOptions

An array of pointers to null-terminated ASCII option strings that are recognized and supported by this EFI MTFTPv4 Protocol driver implementation.

UnsupportedOptionCount

An array of pointers to null-terminated ASCII option strings that are recognized but not supported by this EFI MTFTPv4 Protocol driver implementation.

UnsupportedOptions

An array of option strings that are recognized but are not supported by this EFI MTFTPv4 Protocol driver implementation.

The EFI_MTFTP4_MODE_DATA structure describes the operational state of this instance.

//*****************************************************************************
// EFI_MTFTP4_CONFIG_DATA
//*****************************************************************************
typedef struct {
  BOOLEAN UseDefaultSetting;
  EFI_IPv4_ADDRESS StationIp;
  EFI_IPv4_ADDRESS SubnetMask;
  UINT16 LocalPort;
} EFI_MTFTP4_CONFIG_DATA;
UseDefaultSetting
Set to TRUE to use the default station address/subnet mask and the default route table information.

StationIp
If UseDefaultSetting is FALSE, indicates the station address to use.

SubnetMask
If UseDefaultSetting is FALSE, indicates the subnet mask to use.

LocalPort
Local port number. Set to zero to use the automatically assigned port number.

GatewayIp
If UseDefaultSetting is FALSE, indicates the gateway IP address to use.

ServerIp
The IP address of the MTFTPv4 server.

InitialServerPort
The initial MTFTPv4 server port number. Request packets are sent to this port. This number is almost always 69 and using zero defaults to 69.

TryCount
The number of times to transmit MTFTPv4 request packets and wait for a response.

TimeoutValue
The number of seconds to wait for a response after sending the MTFTPv4 request packet.

The EFI_MTFTP4_CONFIG_DATA structure is used to report and change MTFTPv4 session parameters.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Message</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The configuration data was successfully returned.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The required mode data could not be allocated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL or ModeData is NULL.</td>
</tr>
</tbody>
</table>

30.3.4 EFI_MTFTP4_PROTOCOL.Configure()

Summary
Initializes, changes, or resets the default operational setting for this EFI MTFTPv4 Protocol driver instance.

Prototype

typedef
 EFI_STATUS
(EFIAPIC *EFI_MTFTP4_CONFIGURE)(
   IN EFI_MTFTP4_PROTOCOL *This,
   IN EFI_MTFTP4_CONFIG_DATA *MtftpConfigData OPTIONAL
);
Parameters

This
Pointer to the \texttt{EFI\_MTFTP4\_PROTOCOL} instance.

\texttt{MtftpConfigData}
Pointer to the configuration data structure. Type \texttt{EFI\_MTFTP4\_CONFIG\_DATA} is defined in \texttt{EFI\_MTFTP4\_PROTOCOL\_GetModeData()}.

Description

The \texttt{Configure()} function is used to set and change the configuration data for this EFI MTFTPv4 Protocol driver instance. The configuration data can be reset to startup defaults by calling \texttt{Configure()} with \texttt{MtftpConfigData} set to \texttt{NULL}. Whenever the instance is reset, any pending operation is aborted. By changing the EFI MTFTPv4 Protocol driver instance configuration data, the client can connect to different MTFTPv4 servers. The configuration parameters in \texttt{MtftpConfigData} are used as the default parameters in later MTFTPv4 operations and can be overridden in later operations.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>\texttt{EFI_SUCCESS}</td>
<td>The EFI MTFTPv4 Protocol driver was configured successfully.</td>
</tr>
<tr>
<td>\texttt{EFI_INVALID_PARAMETER}</td>
<td>One or more following conditions are \texttt{TRUE}:</td>
</tr>
</tbody>
</table>
|                                    | \begin{itemize}
|                                    |   \item This is \texttt{NULL}.                                                                |
|                                    |   \item \texttt{MtftpConfigData.UseDefaultSetting} is \texttt{FALSE} and \texttt{MtftpConfigData.StationIp} is not a valid IPv4 unicast address. |
|                                    |   \item \texttt{MtftpConfigData.UseDefaultSetting} is \texttt{FALSE} and \texttt{MtftpConfigData.SubnetMask} is invalid. |
|                                    |   \item \texttt{MtftpConfigData.ServerIp} is not a valid IPv4 unicast address.                 |
|                                    |   \item \texttt{MtftpConfigData.UseDefaultSetting} is \texttt{FALSE} and \texttt{MtftpConfigData.GatewayIp} is not a valid IPv4 unicast address or is not in the same subnet with station address. |
| \texttt{EFI\_ACCESS\_DENIED}      | The EFI configuration could not be changed at this time because there is one MTFTP background operation in progress. |
| \texttt{EFI\_NO\_MAPPING}         | When using a default address, configuration (DHCP, BOOTP, RARP, etc.) has not finished yet.   |
| \texttt{EFI\_UNSUPPORTED}         | A configuration protocol (DHCP, BOOTP, RARP, etc.) could not be located when clients choose to use the default address settings. |
| \texttt{EFI\_OUT\_OF\_RESOURCES}  | The EFI MTFTPv4 Protocol driver instance data could not be allocated.                          |
| \texttt{EFI\_DEVICE\_ERROR}       | An unexpected system or network error occurred. The EFI MTFTPv4 Protocol driver instance is not configured. |

30.3.5 \texttt{EFI\_MTFTP4\_PROTOCOL\_GetInfo()}

Summary

Gets information about a file from an MTFTPv4 server.

Prototype

\begin{verbatim}
typedef
EFI\_STATUS
(EIFI\_API \*EFI\_MTFTP4\_GET\_INFO)(
\end{verbatim}
IN EFI_MTFTP4_PROTOCOL *This,
IN EFI_MTFTP4_OVERRIDE_DATA *OverrideData OPTIONAL,
IN UINT8 *Filename,
IN UINT8 *ModeStr OPTIONAL,
IN UINT8 OptionCount,
IN EFI_MTFTP4_OPTION *OptionList OPTIONAL,
OUT UINT32 *PacketLength,
OUT EFI_MTFTP4_PACKET **Packet OPTIONAL
);

Parameters

**This**
Pointer to the *EFI_MTFTP4_PROTOCOL* instance.

**OverrideData**
Data that is used to override the existing parameters. If **NULL**, the default parameters that were set in the *EFI_MTFTP4_PROTOCOL.Configure()* function are used. Type *EFI_MTFTP4_OVERRIDE_DATA* is defined in “Related Definitions” below.

**Filename**
Pointer to a null-terminated ASCII file name string.

**ModeStr**
Pointer to a null-terminated ASCII mode string. If **NULL**, “octet” will be used.

**OptionCount**
Number of option/value string pairs in *OptionList*.

**OptionList**
Pointer to array of option/value string pairs. Ignored if *OptionCount* is zero. Type *EFI_MTFTP4_OPTION* is defined in “Related Definitions” below.

**PacketLength**
The number of bytes in the returned packet.

**Packet**
The pointer to the received packet. This buffer must be freed by the caller. Type *EFI_MTFTP4_PACKET* is defined in “Related Definitions” below.

Description

The *GetInfo()* function assembles an MTFTPv4 request packet with options; sends it to the MTFTPv4 server; and may return an MTFTPv4 OACK, MTFTPv4 ERROR, or ICMP ERROR packet. Retries occur only if no response packets are received from the MTFTPv4 server before the timeout expires.

Related Definitions

```c
//*******************************************************************************
// EFI_MTFTP OVERRIDE_DATA
//*******************************************************************************
typedef struct {
    EFI_IPv4_ADDRESS   GatewayIp;
    EFI_IPv4_ADDRESS   ServerIp;
    UINT16             ServerPort;
    UINT16             TryCount;
    UINT16             TimeoutValue;
} EFI_MTFTP4 OVERRIDE_DATA;
```
GatewayIp
IP address of the gateway. If set to 0.0.0.0, the default gateway address that was set by the EFI_MTFTP4_PROTOCOL.Configure() function will not be overridden.

ServerIp
IP address of the MTFTPv4 server. If set to 0.0.0.0, it will use the value that was set by the EFI_MTFTP4_PROTOCOL.Configure() function.

ServerPort
MTFTPv4 server port number. If set to zero, it will use the value that was set by the EFI_MTFTP4_PROTOCOL.Configure() function.

TryCount
Number of times to transmit MTFTPv4 request packets and wait for a response. If set to zero, it will use the value that was set by the EFI_MTFTP4_PROTOCOL.Configure() function.

TimeoutValue
Number of seconds to wait for a response after sending the MTFTPv4 request packet. If set to zero, it will use the value that was set by the EFI_MTFTP4_PROTOCOL.Configure() function.

The EFI_MTFTP4_OVERRIDE_DATA structure is used to override the existing parameters that were set by the EFI_MTFTP4_PROTOCOL.Configure() function.

```c
typedef struct {
    UINT8 *OptionStr;
    UINT8 *ValueStr;
} EFI_MTFTP4_OPTION;
```

OptionStr
Pointer to the null-terminated ASCII MTFTPv4 option string.

ValueStr
Pointer to the null-terminated ASCII MTFTPv4 value string.

```c
#pragma pack(1)

typedef union {
    UINT16 OpCode;
    EFI_MTFTP4_REQ_HEADER Rrq, Wrq;
    EFI_MTFTP4_OACK_HEADER Oack;
    EFI_MTFTP4_DATA_HEADER Data;
    EFI_MTFTP4_ACK_HEADER Ack;
    EFI_MTFTP4_DATA8_HEADER Data8;
    EFI_MTFTP4_ACK8_HEADER Ack8;
    EFI_MTFTP4_ERROR_HEADER Error;
} EFI_MTFTP4_PACKET;
```
typedef struct {
    UINT16 OpCode;
    UINT8 Filename[1];
} EFI_MTFTP4_REQ_HEADER;

typedef struct {
    UINT16 OpCode;
    UINT8 Data[1];
} EFI_MTFTP4_OACK_HEADER;

typedef struct {
    UINT16 OpCode;
    UINT16 Block;
    UINT8 Data[1];
} EFI_MTFTP4_DATA_HEADER;

typedef struct {
    UINT16 OpCode;
    UINT16 Block[1];
} EFI_MTFTP4_ACK_HEADER;

typedef struct {
    UINT16 OpCode;
    UINT64 Block;
    UINT8 Data[1];
} EFI_MTFTP4_DATA8_HEADER;

typedef struct {
    UINT16 OpCode;
    UINT64 Block[1];
} EFI_MTFTP4_ACK8_HEADER;

(continues on next page)
// *********************************************
// EFI_MTFTP4_ERROR_HEADER
// *********************************************
typedef struct {
    UINT16 OpCode;     
    UINT16 ErrorCode;    
    UINT8 ErrorMessage[1];
} EFI_MTFTP4_ERROR_HEADER;

#pragma pack()

Table, below, Descriptions of Parameters in MTFTPv4 PacketStructures describes the parameters that are listed in the MTFTPv4 packet structure definitions above. All the above structures are byte packed. The pragmas may vary from compiler to compiler. The MTFTPv4 packet structures are also used by the following functions:

- `EFI_MTFTP4_PROTOCOL.ReadFile()`
- `EFI_MTFTP4_PROTOCOL.WriteFile()`
- `EFI_MTFTP4_PROTOCOL.ReadDirectory()`
- The EFI MTFTPv4 Protocol packet check callback functions

**NOTE:** Both incoming and outgoing MTFTPv4 packets are in network byte order. All other parameters defined in functions or data structures are stored in host byte order.

<table>
<thead>
<tr>
<th>Data Structure</th>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_MTFTP4_PACKET</td>
<td>OpCode</td>
<td>Type of packets as defined by the MTFTPv4 packet op-codes. Opcode values are defined below.</td>
</tr>
<tr>
<td></td>
<td>Rrq, Wrq</td>
<td>Read request or write request packet header. See the description for EFI_MTFTP4_REQ_HEADER below in this table.</td>
</tr>
<tr>
<td></td>
<td>Oack</td>
<td>Option acknowledge packet header. See the description for EFI_MTFTP4_OACK_HEADER below in this table.</td>
</tr>
<tr>
<td></td>
<td>Data</td>
<td>Data packet header. See the description for EFI_MTFTP4_DATA_HEADER below in this table.</td>
</tr>
<tr>
<td></td>
<td>Ack</td>
<td>Acknowledgement packet header. See the description for EFI_MTFTP4_ACK_HEADER below in this table.</td>
</tr>
<tr>
<td></td>
<td>Data8</td>
<td>This field should be ignored and treated as reserved. Data packet header with big block number. See the description for EFI_MTFTP4_DATA8_HEADER below in this table.</td>
</tr>
</tbody>
</table>

continues on next page
Table 30.18 – continued from previous page

<table>
<thead>
<tr>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ack8</td>
<td>This field should be ignored and treated as reserved.</td>
</tr>
<tr>
<td></td>
<td>Acknowledgement header with big block number. See the description for EFWI_MTFTP4_ACK8_HEADER below in this table.</td>
</tr>
<tr>
<td>Error</td>
<td>Error packet header. See the description for EFWI_MTFTP4_ERROR_HEADER below in this table.</td>
</tr>
<tr>
<td>EFI_MTFTP4_REQ_HEADER</td>
<td>OpCode For this packet type, OpCode = EFWI_MTFTP4_OPCODE_RRQ for a read request or OpCode = EFWI_MTFTP4_OPCODE_WRQ for a write request.</td>
</tr>
<tr>
<td>Filename</td>
<td>The file name to be downloaded or uploaded.</td>
</tr>
<tr>
<td>EFI_MTFTP4_OACK_HEADER</td>
<td>OpCode For this packet type, OpCode = EFWI_MTFTP4_OPCODE_OACK.</td>
</tr>
<tr>
<td>Data</td>
<td>The option strings in the option acknowledgement packet.</td>
</tr>
<tr>
<td>EFI_MTFTP4_DATA_HEADER</td>
<td>OpCode For this packet type, OpCode = EFWI_MTFTP4_OPCODE_DATA.</td>
</tr>
<tr>
<td>Block</td>
<td>Block number of this data packet.</td>
</tr>
<tr>
<td>Data</td>
<td>The content of this data packet.</td>
</tr>
<tr>
<td>EFI_MTFTP4_ACK_HEADER</td>
<td>OpCode For this packet type, OpCode = EFWI_MTFTP4_OPCODE_ACK.</td>
</tr>
<tr>
<td>Block</td>
<td>The block number of the data packet that is being acknowledged.</td>
</tr>
<tr>
<td>Block</td>
<td>This field should be ignored and treated as reserved.</td>
</tr>
<tr>
<td></td>
<td>The block number of data packet.</td>
</tr>
<tr>
<td>Data</td>
<td>This field should be ignored and treated as reserved.</td>
</tr>
<tr>
<td></td>
<td>The content of this data packet.</td>
</tr>
</tbody>
</table>

continues on next page
Table 30.18 – continued from previous page

<table>
<thead>
<tr>
<th>Block</th>
<th>This field should be ignored and treated as reserved. The block number of the data packet that is being acknowledged.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_MTFTP4_ERROR_HEADER</td>
<td>OpCode</td>
</tr>
<tr>
<td></td>
<td>ErrorCode</td>
</tr>
<tr>
<td></td>
<td>ErrorMessage</td>
</tr>
</tbody>
</table>

// // MTFTP Packet OpCodes
//
#define EFI_MTFTP4_OPCODE_RRQ 1
#define EFI_MTFTP4_OPCODE_WRQ 2
#define EFI_MTFTP4_OPCODE_DATA 3
#define EFI_MTFTP4_OPCODE_ACK 4
#define EFI_MTFTP4_OPCODE_ERROR 5
#define EFI_MTFTP4_OPCODE_OACK 6
#define EFI_MTFTP4_OPCODE_DIR 7
//This field should be ignored and treated as reserved.
#define EFI_MTFTP4_OPCODE_DATA8 8
//This field should be ignored and treated as reserved.
#define EFI_MTFTP4_OPCODE_ACK8 9

Following is a description of the fields in the above definition.

<table>
<thead>
<tr>
<th>EFI_MTFTP4_OPCODE_RRQ</th>
<th>The MTFTPv4 packet is a read request.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_MTFTP4_OPCODE_WRQ</td>
<td>The MTFTPv4 packet is a write request.</td>
</tr>
<tr>
<td>EFI_MTFTP4_OPCODE_DATA</td>
<td>The MTFTPv4 packet is a data packet.</td>
</tr>
<tr>
<td>EFI_MTFTP4_OPCODE_ACK</td>
<td>The MTFTPv4 packet is an acknowledgement packet.</td>
</tr>
<tr>
<td>EFI_MTFTP4_OPCODE_ERROR</td>
<td>The MTFTPv4 packet is an error packet.</td>
</tr>
<tr>
<td>EFI_MTFTP4_OPCODE_OACK</td>
<td>The MTFTPv4 packet is an option acknowledgement packet.</td>
</tr>
<tr>
<td>EFI_MTFTP4_OPCODE_DIR</td>
<td>The MTFTPv4 packet is a directory query packet.</td>
</tr>
<tr>
<td>EFI_MTFTP4_OPCODE_DATA8</td>
<td>This field should be ignored and treated as reserved. The MTFTPv4 packet is a data packet with a big block number.</td>
</tr>
<tr>
<td>EFI_MTFTP4_OPCODE_ACK8</td>
<td>This field should be ignored and treated as reserved. The MTFTPv4 packet is an acknowledgement packet with a big block number.</td>
</tr>
</tbody>
</table>

// // MTFTP ERROR Packet ErrorCodes

(continues on next page)
//
#define EFI_MTFTP4_ERRORCODE_NOT_DEFINED        0
#define EFI_MTFTP4_ERRORCODE_FILE_NOT_FOUND    1
#define EFI_MTFTP4_ERRORCODE_ACCESS_VIOLATION  2
#define EFI_MTFTP4_ERRORCODE_DISK_FULL         3
#define EFI_MTFTP4_ERRORCODE_ILLEGAL_OPERATION 4
#define EFI_MTFTP4_ERRORCODE_UNKNOWN_TRANSFER_ID 5
#define EFI_MTFTP4_ERRORCODE_FILE_ALREADY_EXISTS 6
#define EFI_MTFTP4_ERRORCODE_NO_SUCH_USER      7
#define EFI_MTFTP4_ERRORCODE_REQUEST_DENIED    8

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_MTFTP4_ERRORCODE_NOT_DEFINED</td>
<td>The error code is not defined. See the error message in the packet (if any) for details.</td>
</tr>
<tr>
<td>EFI_MTFTP4_ERRORCODE_FILE_NOT_FOUND</td>
<td>The file was not found.</td>
</tr>
<tr>
<td>EFI_MTFTP4_ERRORCODE_ACCESS_VIOLATION</td>
<td>There was an access violation.</td>
</tr>
<tr>
<td>EFI_MTFTP4_ERRORCODE_DISK_FULL</td>
<td>The disk was full or its allocation was exceeded.</td>
</tr>
<tr>
<td>EFI_MTFTP4_ERRORCODE_ILLEGAL_OPERATION</td>
<td>The MTFTPv4 operation was illegal.</td>
</tr>
<tr>
<td>EFI_MTFTP4_ERRORCODE_UNKNOWN_TRANSFER_ID</td>
<td>The transfer ID is unknown.</td>
</tr>
<tr>
<td>EFI_MTFTP4_ERRORCODE_FILE_ALREADY_EXISTS</td>
<td>The file already exists.</td>
</tr>
<tr>
<td>EFI_MTFTP4_ERRORCODE_NO_SUCH_USER</td>
<td>There is no such user.</td>
</tr>
<tr>
<td>EFI_MTFTP4_ERRORCODE_REQUEST_DENIED</td>
<td>The request has been denied due to option negotiation.</td>
</tr>
</tbody>
</table>

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>An MTFTPv4 OACK packet was received and is in the Packet.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more of the following conditions is TRUE:  
  • This is **NULL**.
  • Filename is **NULL**.
  • OptionCount is not zero and OptionList is **NULL**.
  • One or more options in OptionList have wrong format.
  • PacketLength is **NULL**.
  • One or more IPv4 addresses in OverrideData are not valid unicast IPv4 addresses if OverrideData is not **NULL** and the addresses are not set to all zero. |
| EFI_UNSUPPORTED | • One or more options in the OptionList are in the unsupported list of structure EFI_MTFTP4_MODE_DATA. |
| EFI_NOT_STARTED | The EFI MTFTPv4 Protocol driver has not been started. |
| EFI_NO_MAPPING | When using a default address, configuration (DHCP, BOOTP, RARP, etc.) has not finished yet. |
| EFI_ACCESS_DENIED | The previous operation has not completed yet. |
| EFI_OUT_OF_RESOURCES | Required system resources could not be allocated. |
| EFI_TFTP_ERROR | An MTFTPv4 ERROR packet was received and is in the Packet. |
Table 30.21 – continued from previous page

<table>
<thead>
<tr>
<th></th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>An ICMP network unreachable error packet was received and the Packet is set to NULL.</td>
</tr>
<tr>
<td>EFI_HOST_UNREACHABLE</td>
<td>An ICMP host unreachable error packet was received and the Packet is set to NULL.</td>
</tr>
<tr>
<td>EFI_PROTOCOL_UNREACHABLE</td>
<td>An ICMP protocol unreachable error packet was received and the Packet is set to NULL.</td>
</tr>
<tr>
<td>EFI_PORT_UNREACHABLE</td>
<td>An ICMP port unreachable error packet was received and the Packet is set to NULL.</td>
</tr>
<tr>
<td>EFI_ICMP_ERROR</td>
<td>Some other ICMP ERROR packet was received and the Packet is set to NULL.</td>
</tr>
<tr>
<td>EFI_PROTOCOL_ERROR</td>
<td>An unexpected MTFTPv4 packet was received and is in the Packet.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>No responses were received from the MTFTPv4 server.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network error or system error occurred.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

30.3.6 EFI_MTFTP4_PROTOCOL.ParseOptions()

Summary

Parses the options in an MTFTPv4 OACK packet.

Prototype

```c
typedef EFI_STATUS
  (EFIAPIC *EFI_MTFTP4_PARSE_OPTIONS)(
  IN EFI_MTFTP4_PROTOCOL *This,
  IN UINT32 PacketLen,
  IN EFI_MTFTP4_PACKET *Packet,
  OUT UINT32 *OptionCount,
  OUT EFI_MTFTP4_OPTION **OptionList OPTIONAL
  );
```

Parameters

This

Pointer to the EFI_MTFTP4_PROTOCOL instance.

PacketLen

Length of the OACK packet to be parsed.

Packet

Pointer to the OACK packet to be parsed. Type EFI_MTFTP4_PACKET is defined in EFI_MTFTP4_PROTOCOL.GetInfo().

OptionCount

Pointer to the number of options in following OptionList.

OptionList

Pointer to EFI_MTFTP4_OPTION storage. Call the EFI Boot Service FreePool() to release the OptionList if the options in this OptionList are not needed any more. Type EFI_MTFTP4_OPTION is defined in EFI_MTFTP4_PROTOCOL.GetInfo().

Description
The `ParseOptions()` function parses the option fields in an MTFTPv4 OACK packet and returns the number of options that were found and optionally a list of pointers to the options in the packet.

If one or more of the option fields are not valid, then `EFI_PROTOCOL_ERROR` is returned and `OptionCount` and `OptionList` stop at the last valid option.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The OACK packet was valid and the <code>OptionCount</code> and <code>OptionList</code> parameters have been updated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <code>TRUE</code>:</td>
</tr>
<tr>
<td></td>
<td>• <code>PacketLen</code> is 0.</td>
</tr>
<tr>
<td></td>
<td>• <code>Packet</code> is <code>NULL</code> or <code>Packet</code> is not a valid MTFTPv4 packet.</td>
</tr>
<tr>
<td></td>
<td>• <code>OptionCount</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No options were found in the OACK packet.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Storage for the <code>OptionList</code> array cannot be allocated.</td>
</tr>
<tr>
<td>EFI_PROTOCOL_ERROR</td>
<td>One or more of the option fields is invalid.</td>
</tr>
</tbody>
</table>

### 30.3.7 EFI_MTFTP4_PROTOCOL.ReadFile()

**Summary**

Downloads a file from an MTFTPv4 server.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_MTFTP4_READ_FILE)(
    IN EFI_MTFTP4_PROTOCOL *This,
    IN EFI_MTFTP4_TOKEN *Token
);```

**Parameters**

**This**

Pointer to the `EFI_MTFTP4_PROTOCOL` instance.

**Token**

Pointer to the token structure to provide the parameters that are used in this operation. Type `EFI_MTFTP4_TOKEN` is defined in “Related Definitions” below.

**Description**

The `ReadFile()` function is used to initialize and start an MTFTPv4 download process and optionally wait for completion. When the download operation completes, whether successfully or not, the `Token.Status` field is updated by the EFI MTFTPv4 Protocol driver and then `Token.Event` is signaled (if it is not `NULL`).

Data can be downloaded from the MTFTPv4 server into either of the following locations:

- A fixed buffer that is pointed to by `Token.Buffer`
- A download service function that is pointed to by `Token.CheckPacket`

If both `Token.Buffer` and `Token.CheckPacket` are used, then `Token.CheckPacket` will be called first. If the call is successful, the packet will be stored in `Token.Buffer`. 
Related Definitions

```c
typedef struct {
  EFI_STATUS Status;
  EFI_EVENT Event;
  EFI_MTFTP4_OVERRIDE_DATA *OverrideData;
  UINT8 *Filename;
  UINT8 *ModeStr;
  UINT32 OptionCount;
  EFI_MTFTP4_OPTION *OptionList;
  UINT64 BufferSize;
  VOID *Buffer;
  VOID *Context;
  EFI_MTFTP4_CHECK_PACKET CheckPacket;
  EFI_MTFTP4_TIMEOUT_CALLBACK TimeoutCallback;
  EFI_MTFTP4_PACKET_NEEDED PacketNeeded;
} EFI_MTFTP4_TOKEN;
```

**Status**

The status that is returned to the caller at the end of the operation to indicate whether this operation completed successfully. Defined `Status` values are listed below.

**Event**

The event that will be signaled when the operation completes. If set to `NULL`, the corresponding function will wait until the read or write operation finishes. The type of `Event` must be `EVT_NOTIFY_SIGNAL`. The Task Priority Level (TPL) of `Event` must be lower than or equal to `TPL_CALLBACK`.

**OverrideData**

If not `NULL`, the data that will be used to override the existing configure data. Type `EFI_MTFTP4_OVERRIDE_DATA` is defined in `EFI_MTFTP4_PROTOCOL .GetInfo()`.

**Filename**

Pointer to the null-terminated ASCII file name string.

**ModeStr**

Pointer to the null-terminated ASCII mode string. If `NULL`, “octet” is used.

**OptionCount**

Number of option/value string pairs.

**OptionList**

Pointer to an array of option/value string pairs. Ignored if `OptionCount` is zero. Both a remote server and this driver implementation should support these options. If one or more options are unrecognized by this implementation, it is sent to the remote server without being changed. Type `EFI_MTFTP4_OPTION` is defined in `EFI_MTFTP4_PROTOCOL .GetInfo()`.

**BufferSize**

On input, the size, in bytes, of `Buffer`. On output, the number of bytes transferred

**Buffer**

Pointer to the data buffer. Data that is downloaded from the MTFTPv4 server is stored here. Data that is uploaded to the MTFTPv4 server is read from here. Ignored if `BufferSize` is zero.

**Context**

Pointer to the context that will be used by `CheckPacket`, `TimeoutCallback` and `PacketNeeded`. 
CheckPacket
  Pointer to the callback function to check the contents of the received packet. Type
  `EFI_MTFTP4_CHECK_PACKET` is defined below.

TimeoutCallback
  Pointer to the function to be called when a timeout occurs. Type `EFI_MTFTP4_TIMEOUT_CALLBACK`
  is defined below.

PacketNeeded
  Pointer to the function to provide the needed packet contents. Only used in `WriteFile()` operation. Type
  `EFI_MTFTP4_PACKET_NEEDED` is defined below.

The `EFI_MTFTP4_TOKEN` structure is used for both the MTFTPv4 reading and writing operations. The caller uses
this structure to pass parameters and indicate the operation context. After the reading or writing operation completes,
the EFI MTFTPv4 Protocol driver updates the `Status` parameter and the `Event` is signaled if it is not `NULL`. The
following table lists the status codes that are returned in the `Status` parameter.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data file has been transferred successfully.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>BufferSize is not large enough to hold the downloaded data in downloading</td>
</tr>
<tr>
<td></td>
<td>process.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>Current operation is aborted by user.</td>
</tr>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>An ICMP network unreachable error packet was received.</td>
</tr>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>An ICMP host unreachable error packet was received.</td>
</tr>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>An ICMP protocol unreachable error packet was received.</td>
</tr>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>An ICMP port unreachable error packet was received.</td>
</tr>
<tr>
<td>EFI_ICMP_ERROR</td>
<td>Some other ICMP ERROR packet was received.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>No responses were received from the MTFTPv4 server.</td>
</tr>
<tr>
<td>EFI_TFTP_ERROR</td>
<td>An MTFTPv4 ERROR packet was received.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network error or system error occurred.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

```c
//******************************************************
// EFI_MTFTP4_CHECK_PACKET
//******************************************************

typedef
EFI_STATUS
(EFIAPI *EFI_MTFTP4_CHECK_PACKET)(
    IN EFI_MTFTP4_PROTOCOL *This,
    IN EFI_MTFTP4_TOKEN *Token,
    IN UINT16 PacketLen,
    IN EFI_MTFTP4_PACKET *Packet
);
```

This
  Pointer to the `EFI_MTFTP4_PROTOCOL` instance.

Token
  The token that the caller provided in the `EFI_MTFTP4_PROTOCOL.ReadFile()`, `WriteFile()` or `ReadDirectory()`
  function. Type `EFI_MTFTP4_TOKEN` is defined in `EFI_MTFTP4_PROTOCOL.ReadFile()`.

PacketLen
  Indicates the length of the packet.
Packet

Pointer to an MTFTPv4 packet. Type `EFI_MTFTP4_PACKET` is defined in `EFI_MTFTP4_PROTOCOL.GetInfo()`.

`EFI_MTFTP4_CHECK_PACKET` is a callback function that is provided by the caller to intercept the `EFI_MTFTP4_OPCODE_DATA` or `EFI_MTFTP4_OPCODE_DATA8` packets processed in the `EFI_MTFTP4_PROTOCOL.ReadFile()` function, and alternatively to intercept `EFI_MTFTP4_OPCODE_OACK` or `EFI_MTFTP4_OPCODE_ERROR` packets during a call to `EFI_MTFTP4_PROTOCOL.ReadFile()`, `WriteFile()` or `ReadDirectory()`. Whenever an MTFTPv4 packet with the type described above is received from a server, the EFI MTFTPv4 Protocol driver will call `EFI_MTFTP4_CHECK_PACKET` function to let the caller have an opportunity to process this packet. Any status code other than `EFI_SUCCESS` that is returned from this function will abort the transfer process.

```c
//******************************************************************************/
// EFI_MTFTP4_TIMEOUT_CALLBACK
//******************************************************************************/
typedef EFI_STATUS
  (EFIAPI *EFI_MTFTP4_TIMEOUT_CALLBACK)(
    IN EFI_MTFTP4_PROTOCOL *This,
    IN EFI_MTFTP4_TOKEN *Token
  );

This

Pointer to the `EFI_MTFTP4_PROTOCOL` instance.

Token

The token that is provided in the `EFI_MTFTP4_PROTOCOL.ReadFile()` or `EFI_MTFTP4_PROTOCOL.WriteFile()` or `EFI_MTFTP4_PROTOCOL.ReadDirectory()` functions by the caller. Type `EFI_MTFTP4_TOKEN` is defined in `EFI_MTFTP4_PROTOCOL.ReadFile()`.

`EFI_MTFTP4_TIMEOUT_CALLBACK` is a callback function that the caller provides to capture the timeout event in the `EFI_MTFTP4_PROTOCOL.ReadFile()`, `EFI_MTFTP4_PROTOCOL.WriteFile()` or `EFI_MTFTP4_PROTOCOL.ReadDirectory()` functions. Whenever a timeout occurs, the EFI MTFTPv4 Protocol driver will call the `EFI_MTFTP4_TIMEOUT_CALLBACK` function to notify the caller of the timeout event. Any status code other than `EFI_SUCCESS` that is returned from this function will abort the current download process.

```c
//******************************************************************************/
// EFI_MTFTP4_PACKET_NEEDED
//******************************************************************************/
typedef EFI_STATUS
  (EFIAPI *EFI_MTFTP4_PACKET_NEEDED)(
    IN EFI_MTFTP4_PROTOCOL *This,
    IN EFI_MTFTP4_TOKEN *Token,
    IN OUT UINT16 *Length,
    OUT VOID **Buffer
  );

This

Pointer to the `EFI_MTFTP4_PROTOCOL` instance.
Token
The token provided in the `EFI_MTFTP4_PROTOCOL.WriteFile()` by the caller.

Length
Indicates the length of the raw data wanted on input, and the length the data available on output.

Buffer
Pointer to the buffer where the data is stored.

`EFI_MTFTP4_PACKET_NEEDED` is a callback function that the caller provides to feed data to the `EFI_MTFTP4_PROTOCOL.WriteFile()` function. `EFI_MTFTP4_PACKET_NEEDED` provides another mechanism for the caller to provide data to upload other than a static buffer. The EFI MTFTP4 Protocol driver always calls `EFI_MTFTP4_PACKET_NEEDED` to get packet data from the caller if no static buffer was given in the initial call to `EFI_MTFTP4_PROTOCOL.WriteFile()` function. Setting **Length* to zero signals the end of the session. Returning a status code other than `EFI_SUCCESS` aborts the session.

Status CodesReturned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The data file is being downloaded.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>One or more of the parameters is not valid.</td>
</tr>
<tr>
<td></td>
<td>• <code>This</code> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <code>Token</code> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <code>Token.Filename</code> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <code>Token.OptionCount</code> is not zero and <code>Token.OptionList</code> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• One or more options in <code>Token.OptionList</code> have wrong format.</td>
</tr>
<tr>
<td></td>
<td>• <code>Token.Buffer</code> and <code>Token.CheckPacket</code> are both <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• One or more IPv4 addresses in <code>Token.OverrideData</code> are not valid unicast IPv4 addresses if <code>Token.OverrideData</code> is not <strong>NULL</strong> and the addresses are not set to all zero.</td>
</tr>
<tr>
<td><code>EFI_UNSUPPORTED</code></td>
<td>• One or more options in the <code>Token.OptionList</code> are in the unsupported list of structure <code>EFI_MTFTP4_MODE_DATA</code>.</td>
</tr>
<tr>
<td><code>EFI_NOT_STARTED</code></td>
<td>The EFI MTFTPv4 Protocol driver has not been started.</td>
</tr>
<tr>
<td><code>EFI_NO_MAPPING</code></td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td><code>EFI_ALREADY_STARTED</code></td>
<td>This <code>Token</code> is being used in another MTFTPv4 session.</td>
</tr>
<tr>
<td><code>EFI_ACCESS_DENIED</code></td>
<td>The previous operation has not completed yet.</td>
</tr>
<tr>
<td><code>EFI_OUT_OF_RESOURCES</code></td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td><code>EFI_DEVICE_ERROR</code></td>
<td>An unexpected network error or system error occurred.</td>
</tr>
<tr>
<td><code>EFI_NO_MEDIA</code></td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>
30.3.8 EFI_MTFTP4_PROTOCOL.WriteFile()

Summary
Sends a data file to an MTFTPv4 server. May be unsupported in some EFI implementations.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_MTFTP4_WRITE_FILE)(
    IN EFI_MTFTP4_PROTOCOL *This,
    IN EFI_MTFTP4_TOKEN *Token
);
```

Parameters

This
Pointer to the EFI_MTFTP4_PROTOCOL instance.

Token
Pointer to the token structure to provide the parameters that are used in this function. Type EFI_MTFTP4_TOKEN is defined in EFI_MTFTP4_PROTOCOL.ReadFile().

Description
The WriteFile() function is used to initialize an uploading operation with the given option list and optionally wait for completion. If one or more of the options is not supported by the server, the unsupported options are ignored and a standard TFTP process starts instead. When the upload process completes, whether successfully or not, Token.Event is signaled, and the EFI MTFTPv4 Protocol driver updates Token.Status.

The caller can supply the data to be uploaded in the following two modes:

- Through the user-provided buffer
- Through a callback function

With the user-provided buffer, the Token.BufferSize field indicates the length of the buffer, and the driver will upload the data in the buffer. With an EFI_MTFTP4_PACKET_NEEDED callback function, the driver will call this callback function to get more data from the user to upload. See the definition of EFI_MTFTP4_PACKET_NEEDED for more information. These two modes cannot be used at the same time. The callback function will be ignored if the user provides the buffer.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The upload session has started.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The operation is not supported by this implementation.</td>
</tr>
</tbody>
</table>

continues on next page
Table 30.25 – continued from previous page

<table>
<thead>
<tr>
<th></th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• <em>This</em> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <em>Token</em> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <em>Token.Filename</em> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <em>Token.OptionCount</em> is not zero and <em>Token.OptionList</em> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• One or more options in <em>Token.OptionList</em> have wrong format.</td>
</tr>
<tr>
<td></td>
<td>• <em>Token.Buffer</em> and <em>Token.PacketNeeded</em> are both <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• One or more IPv4 addresses in <em>Token.OverrideData</em> are not valid unicast</td>
</tr>
<tr>
<td></td>
<td>IPv4 addresses if <em>Token.OverrideData</em> is not <strong>NULL</strong> and the addresses</td>
</tr>
<tr>
<td></td>
<td>are not set to all zero.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>• One or more options in the <em>Token.OptionList</em> are in the unsupported list</td>
</tr>
<tr>
<td></td>
<td>of structure <strong>EFI_MTFTP4_MODE_DATA</strong>.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI MTFTP4 Protocol driver has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.)</td>
</tr>
<tr>
<td></td>
<td>is not finished yet.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>This <em>Token</em> is already being used in another MTFTPv4 session.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The previous operation has not completed yet.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network error or system error occurred.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

### 30.3.9 **EFI_MTFTP4_PROTOCOL.ReadDirectory()**

**Summary**
Downloads a data file “directory” from an MTFTPv4 server. May be unsupported in some EFI implementations.

**Prototype**

```c
typedef
EFI_STATUS
(EIFIAP1 *EFI_MTFTP4_READ_DIRECTORY)(
    IN EFI_MTFTP4_PROTOCOL *This,
    IN EFI_MTFTP4_TOKEN *Token
);
```

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>This</strong></td>
<td>Pointer to the <strong>EFI_MTFTP4_PROTOCOL</strong> instance.</td>
</tr>
<tr>
<td><strong>Token</strong></td>
<td>Pointer to the token structure to provide the parameters that are used in</td>
</tr>
<tr>
<td></td>
<td>this function. Type <strong>EFI_MTFTP4_TOKEN</strong> is defined in <strong>EFI_MTFTP4_PROTOCOL.ReadFile()</strong>.</td>
</tr>
</tbody>
</table>

**Description**
The *ReadDirectory()* function is used to return a list of files on the MTFTPv4 server that are logically (or operationally) related to *Token.Filename*. The directory request packet that is sent to the server is built with the option list that was provided by caller, if present.
The file information that the server returns is put into either of the following locations:

- A fixed buffer that is pointed to by `Token.Buffer`
- A download service function that is pointed to by `Token.CheckPacket`

If both `Token.Buffer` and `Token.CheckPacket` are used, then `Token.CheckPacket` will be called first. If the call is successful, the packet will be stored in `Token.Buffer`.

The returned directory listing in the `Token.Buffer` or `EFI_MTFTP4_PACKET` consists of a list of two or three variable-length ASCII strings, each terminated by a null character, for each file in the directory. If the multicast option is involved, the first field of each directory entry is the static multicast IP address and UDP port number that is associated with the file name. The format of the field is `ip:ip:ip:ip:port`. If the multicast option is not involved, this field and its terminating null character are not present.

The next field of each directory entry is the file name and the last field is the file information string. The information string contains the file size and the create/modify timestamp. The format of the information string is `filesize yyyy-mm-dd hh:mm:ss:ffff`. The timestamp is Coordinated Universal Time (UTC; also known as Greenwich Mean Time [GMT]).

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The MTFTPv4 related file “directory” has been downloaded.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The EFI MTFTPv4 Protocol driver does not support this function.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more of these conditions is TRUE:  
  - This is NULL.  
  - Token is NULL.  
  - Token.Filename is NULL.  
  - Token.OptionCount is not zero and Token.OptionList is NULL.  
  - One or more options in Token.OptionList have wrong format.  
  - Token.Buffer and Token.CheckPacket are both NULL.  
  - One or more IPv4 addresses in Token.OverrideData are not valid unicast IPv4 addresses if Token.OverrideData is not NULL and the addresses are not set to all zero. |
| EFI_UNSUPPORTED     | One or more options in the Token.OptionList are in the unsupported list of structure EFI_MTFTP4_MODE_DATA. |
| EFI_NOT_STARTED     | The EFI MTFTPv4 Protocol driver has not been started.                       |
| EFI_NO_MAPPING      | When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet. |
| EFI_ALREADY_STARTED | This Token is already being used in another MTFTPv4 session.               |
| EFI_OUT_OF_RESOURCES| Required system resources could not be allocated.                           |
| EFI_ACCESS_DENIED   | The previous operation has not completed yet.                               |
| EFI_DEVICE_ERROR    | An unexpected network error or system error occurred.                       |
| EFI_NO_MEDIA        | There was a media error.                                                   |
30.3.10 EFI_MTFTP4_PROTOCOL.POLL()

Summary
Polls for incoming data packets and processes outgoing data packets.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_MTFTP4_POLL) (
    IN EFI_MTFTP4_PROTOCOL *This
);
```

Parameters

This
Pointer to the EFI_MTFTP4_PROTOCOL instance.

Description
The Poll() function can be used by network drivers and applications to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

In some systems, the periodic timer event in the managed network driver may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the Poll() function more often.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI MTFTPv4 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>When using a default address, configuration (DHCP, BOOTP, RARP, etc.) is not finished yet.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_TIME_OUT</td>
<td>Data was dropped out of the transmit and/or receive queue. Consider increasing the polling rate.</td>
</tr>
</tbody>
</table>

30.4 EFI MTFTPv6 Protocol

This section defines the EFI MTFTPv6 Protocol interface that is built upon the EFI UDPv6 Protocol.

30.4.1 MTFTP6 Service Binding Protocol

30.4.1.1 EFI_MTFTP6_SERVICE_BINDING_PROTOCOL

Summary
The EFI MTFTPv6 Service Binding Protocol is used to locate communication devices that are supported by an EFI MTFTPv6 Protocol driver and to create and destroy instances of the EFI MTFTPv6 Protocol child instance that can use the underlying communications device.

GUID
#define EFI_MTFTP6_SERVICE_BINDING_PROTOCOL_GUID \
{0xd9760ff3,0x3cca,0x4267,\ 
{0x80,0xf9,0x75,0x27,0xfa,0xfa,0x42,0x23}}

Description

A network application or driver that requires MTFTPv6 I/O services can use one of the protocol handler services, such as BS->LocateHandleBuffer(), to search for devices that publish an EFI MTFTPv6 Service Binding Protocol GUID. Each device with a published EFI MTFTPv6 Service Binding Protocol GUID supports the EFI MTFTPv6 Protocol service and may be available for use.

After a successful call to the EFI_MTFTP6_SERVICE_BINDING_PROTOCOL.CreateChild() function, the newly created child EFI MTFTPv6 Protocol driver instance is in the un-configured state; it is not ready to transfer data.

Before a network application terminates execution, every successful call to the EFI_MTFTP6_SERVICE_BINDING_PROTOCOL.CreateChild() function must be matched with a call to the EFI_MTFTP6_SERVICE_BINDING_PROTOCOL.DestroyChild() function.

Each instance of the EFI MTFTPv6 Protocol driver can support one file transfer operation at a time. To download two files at the same time, two instances of the EFI MTFTPv6 Protocol driver need to be created.

30.4.2 MTFTP6 Protocol

30.4.2.1 EFI_MTFTP6_PROTOCOL

Summary

The EFI MTFTPv6 Protocol provides basic services for client-side unicast and/or multicast TFTP operations.

GUID

#define EFI_MTFTP6_PROTOCOL_GUID \
{0xbf0a78ba,0xec29,0x49cf,\ 
0xa1,0xc9,0x7a,0xe5,0x4e,0xab,0x6a,0x51}}

Protocol Interface Structure

typedef struct _EFI_MTFTP6_PROTOCOL {
    EFI_MTFTP6_GET_MODE_DATA GetModeData;
    EFI_MTFTP6_CONFIGURE Configure;
    EFI_MTFTP6_GET_INFO GetInfo;
    EFI_MTFTP6_PARSE_OPTIONS ;
    EFI_MTFTP6_READ_FILE ReadFile;
    EFI_MTFTP6_WRITE_FILE WriteFile;
    EFI_MTFTP6_READ_DIRECTORY ReadDirectory;
    EFI_MTFTP6_POLL Poll;
} EFI_MTFTP6_PROTOCOL;

Parameters

GetModeData

     Reads the current operational settings. See the GetModeData() function description.

Configure

     Initializes, changes, or resets the operational settings for this instance of the EFI MTFTPv6 Protocol driver. See the Configure() function description.
GetInfo
Retrieves information about a file from an MTFTPv6 server. See the GetInfo() function description. Parses the options in an MTFTPv6 OACK (options acknowledgement) packet. See the () function description.

ReadFile
Downloads a file from an MTFTPv6 server. See the ReadFile() function description.

WriteFile
Uploads a file to an MTFTPv6 server. This function may be unsupported in some EFI implementations. See the WriteFile() function description.

ReadDirectory
Downloads a related file directory from an MTFTPv6 server. This function may be unsupported in some EFI implementations. See the ReadDirectory() function description.

Poll
Polls for incoming data packets and processes outgoing data packets. See the Poll() function description.

Description
The EFI_MTFTP6_PROTOCOL is designed to be used by UEFI drivers and applications to transmit and receive data files. The EFI MTFTPv6 Protocol driver uses the underlying EFI UDPv6 Protocol driver and EFI IPv6 Protocol driver.

30.4.2.2 EFI_MTFTP6_PROTOCOL.GetModeData()

Summary
Read the current operational settings.

Prototype

typedef
EFI_STATUS
(EFI_API *EFI_MTFTP6_GET_MODE_DATA)(
    IN EFI_MTFTP6_PROTOCOL *This,
    OUT EFI_MTFTP6_MODE_DATA *ModeData
);

Parameters
This
Pointer to the EFI_MTFTP6_PROTOCOL instance.

ModeData
The buffer in which the EFI MTFTPv6 Protocol driver mode data is returned. Type EFI_MTFTP6_MODE_DATA is defined in “Related Definitions” below.

Description
The GetModeData () function reads the current operational settings of this EFI MTFTPv6 Protocol driver instance.

Related Definitions

//******************************************************************************
// EFI_MTFTP6_MODE_DATA
//******************************************************************************
typedef struct {
    EFI_MTFTP6_CONFIG_DATA ConfigData;
    UINT8 SupportedOptionCount;
}
UINT8 **SupportedOptions;
}
EFI_MTFTP6_MODE_DATA;

ConfigData
The configuration data of this instance. Type \textit{EFI\_MTFTP6\_CONFIG\_DATA} is defined below.

SupportedOptionCount
The number of option strings in the following \textit{SupportedOptions} array.

SupportedOptions
An array of null-terminated ASCII option strings that are recognized and supported by this EFI MTFTPv6 Protocol driver implementation. The buffer is read only to the caller and the caller should NOT free the buffer.

The \textit{EFI\_MTFTP6\_MODE\_DATA} structure describes the operational state of this instance.

```
//*******************************************************************************
// EFI_MTFTP6_CONFIG_DATA
//*******************************************************************************
typedef struct {
    EFI_IPv6_ADDRESS StationIp;
    UINT16 LocalPort;
    EFI_IPv6_ADDRESS ServerIp;
    UINT16 InitialServerPort;
    UINT16 TryCount;
    UINT16 TimeoutValue;
} EFI_MTFTP6_CONFIG_DATA;
```

StationIp
The local IP address to use. Set to zero to let the underlying IPv6 driver choose a source address. If not zero it must be one of the configured IP addresses in the underlying IPv6 driver.

LocalPort
Local port number. Set to zero to use the automatically assigned port number.

ServerIp
The IP address of the MTFTPv6 server.

InitialServerPort
The initial MTFTPv6 server port number. Request packets are sent to this port. This number is almost always 69 and using zero defaults to 69.

TryCount
The number of times to transmit MTFTPv6 request packets and wait for a response.

TimeoutValue
The number of seconds to wait for a response after sending the MTFTPv6 request packet.

The \textit{EFI\_MTFTP6\_CONFIG\_DATA} structure is used to retrieve and change MTFTPv6 session parameters.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The configuration data was successfully returned.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The required mode data could not be allocated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>\textit{This is NULL} or \textit{ModeData} is \textit{NULL}.</td>
</tr>
</tbody>
</table>

30.4. EFI MTFTPv6 Protocol
30.4.2.3 EFI_MTFTP6_PROTOCOL.Configure()

Summary
Initializes, changes, or resets the default operational setting for this EFI MTFTPv6 Protocol driver instance.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_MTFTP6_CONFIGURE)(
    IN EFI_MTFTP6_PROTOCOL *This,
    IN EFI_MTFTP6_CONFIG_DATA *MtftpConfigData OPTIONAL
);
```

Parameters

This
Pointer to the EFI_MTFTP6_PROTOCOL instance.

MtftpConfigData
Pointer to the configuration data structure. Type EFI_MTFTP6_CONFIG_DATA is defined in EFI_MTFTP6_PROTOCOL.GetModeData().

Description

The Configure() function is used to set and change the configuration data for this EFI MTFTPv6 Protocol driver instance. The configuration data can be reset to startup defaults by calling Configure() with MtftpConfigData set to NULL. Whenever the instance is reset, any pending operation is aborted. By changing the EFI MTFTPv6 Protocol driver instance configuration data, the client can connect to different MTFTPv6 servers. The configuration parameters in MtftpConfigData are used as the default parameters in later MTFTPv6 operations and can be overridden in later operations.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The EFI MTFTPv6 Protocol instance was configured successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more following conditions are TRUE:</td>
</tr>
<tr>
<td></td>
<td>• This is NULL.</td>
</tr>
<tr>
<td></td>
<td>• MtftpConfigData.StationIp is neither zero nor one of the configured IP</td>
</tr>
<tr>
<td></td>
<td>addresses in the underlying IPv6 driver.</td>
</tr>
<tr>
<td></td>
<td>• MtftpConfigData.ServerIp is not a valid IPv6 unicast address.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>• The configuration could not be changed at this time because there is some</td>
</tr>
<tr>
<td></td>
<td>MTFTP background operation in progress.</td>
</tr>
<tr>
<td></td>
<td>• MtftpConfigData.LocalPort is already in use.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The underlying IPv6 driver was responsible for choosing a source address</td>
</tr>
<tr>
<td></td>
<td>for this instance, but no source address was available for use.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The EFI MTFTP6 Protocol driver instance data could not be allocated.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred. The EFI MTFTPv6 Protocol</td>
</tr>
<tr>
<td></td>
<td>driver instance is not configured.</td>
</tr>
</tbody>
</table>
30.4.2.4 EFI_MTFTP6_PROTOCOL.GetInfo()

Summary
Get information about a file from an MTFTPv6 server.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_MTFTP6_GET_INFO)(
  IN EFI_MTFTP6_PROTOCOL *This,
  IN EFI_MTFTP6_OVERRIDE_DATA *OverrideData OPTIONAL,
  IN UINT8 *Filename,
  IN UINT8 *ModeStr OPTIONAL,
  IN UINT8 OptionCount,
  IN EFI_MTFTP6_OPTION *OptionList OPTIONAL,
  OUT UINT32 *PacketLength,
  OUT EFI_MTFTP6_PACKET **Packet OPTIONAL
);
```

Parameters

This
Pointer to the EFI_MTFTP6_PROTOCOL instance.

OverrideData
Data that is used to override the existing parameters. If NULL, the default parameters that were set in the EFI_MTFTP6_PROTOCOL. Configure () function are used. Type EFI_MTFTP6_OVERRIDE_DATA is defined in “Related Definitions” below.

Filename
Pointer to an null-terminated ASCII file name string.

ModeStr
Pointer to an null-terminated ASCII mode string. If NULL, octet will be used.

OptionCount
Number of option/value string pairs in OptionList .

OptionList
Pointer to array of option/value string pairs. Ignored if OptionCount is zero. Type EFI_MTFTP6_OPTION is defined in “Related Definitions” below.

PacketLength
The number of bytes in the returned packet.

Packet
The pointer to the received packet. This buffer must be freed by the caller. Type EFI_MTFTP6_PACKET is defined in “Related Definitions” below.

Description
The GetInfo() function assembles an MTFTPv6 request packet with options, sends it to the MTFTPv6 server, and may return an MTFTPv6 OACK, MTFTPv6 ERROR, or ICMP ERROR packet. Retries occur only if no response packets are received from the MTFTPv6 server before the timeout expires.

Related Definitions
typedef struct {
    EFI_IPv6_ADDRESS ServerIp;
    UINT16 ServerPort;
    UINT16 TryCount;
    UINT16 TimeoutValue;
} EFI_MTFTP6_OVERRIDE_DATA;

ServerIp
IP address of the MTFTPv6 server. If set to all zero, the value that was set by the
EFI_MTFTP6_PROTOCOL.Configure() function will be used.

ServerPort
MTFTPv6 server port number. If set to zero, it will use the value that was set by the
EFI_MTFTP6_PROTOCOL.Configure() function.

TryCount
Number of times to transmit MTFTPv6 request packets and wait for a response. If set to zero, the value that was
set by the EFI_MTFTP6_PROTOCOLConfigurer() function will be used.

TimeoutValue
Number of seconds to wait for a response after sending the MTFTPv6 request packet. If set to zero, the value
that was set by the EFI_MTFTP6_PROTOCOL.Configure() function will be used.

The EFI_MTFTP6_OVERRIDE_DATA structure is used to override the existing parameters that were set by the
EFI_MTFTP6_PROTOCOL.Configure() function.

typedef struct {
    UINT8 *OptionStr;
    UINT8 *ValueStr;
} EFI_MTFTP6_OPTION;

OptionStr
Pointer to the null-terminated ASCII MTFTPv6 option string.

ValueStr
Pointer to the null-terminated ASCII MTFTPv6 value string.

#pragma pack(1)

typedef union {
    UINT16 OpCode;
    EFI_MTFTP6_REQ_HEADER Rrq;
    EFI_MTFTP6_REQ_HEADER Wrq;
    EFI_MTFTP6_OACK_HEADER Oack;
    EFI_MTFTP6_DATA_HEADER Data;
    EFI_MTFTP6_ACK_HEADER Ack;
} EFI_MTFTP6_PACKET;

(continues on next page)
// This field should be ignored and treated as reserved.
EFI_MTFTP6_DATA8_HEADER Data8;
// This field should be ignored and treated as reserved.
EFI_MTFTP6_ACK8_HEADER Ack8;
EFI_MTFTP6_ERROR_HEADER Error;
} EFI_MTFTP6_PACKET;

//*********************************************
// EFI_MTFTP6_REQ_HEADER
//*********************************************
typedef struct {
  UINT16 OpCode;
  UINT8 Filename[1];
} EFI_MTFTP6_REQ_HEADER;

//*********************************************
// EFI_MTFTP6_OACK_HEADER
//*********************************************
typedef struct {
  UINT16 OpCode;
  UINT8 Data[1];
} EFI_MTFTP6_OACK_HEADER;

//*********************************************
// EFI_MTFTP6_DATA_HEADER
//*********************************************
typedef struct {
  UINT16 OpCode;
  UINT16 Block;
  UINT8 Data[1];
} EFI_MTFTP6_DATA_HEADER;

//*********************************************
// EFI_MTFTP6_ACK_HEADER
//*********************************************
typedef struct {
  UINT16 OpCode;
  UINT16 Block[1];
} EFI_MTFTP6_ACK_HEADER;

//*********************************************
// EFI_MTFTP6_DATA8_HEADER
// This field should be ignored and treated as reserved.
//*********************************************
typedef struct {
  UINT16 OpCode;
  UINT64 Block;
  UINT8 Data[1];
} EFI_MTFTP6_DATA8_HEADER;

//*********************************************
// EFI_MTFTP6_ACK8_HEADER
//*********************************************
typedef struct {
  UINT16 OpCode;
  UINT64 Block;
  UINT8 Data[1];
} EFI_MTFTP6_ACK8_HEADER;

(continues on next page)
Table 1 below describes the parameters that are listed in the MTFTPv6 packet structure definitions above. All the above structures are byte packed. The pragmas may vary from compiler to compiler. The MTFTPv6 packet structures are also used by the following functions:

- `EFI_MTFTP6_PROTOCOL.ReadFile()`
- `EFI_MTFTP6_PROTOCOL.WriteFile()`
- `EFI_MTFTP6_PROTOCOL.ReadDirectory()`
- The EFI MTFTPv6 Protocol packet check callback functions

NOTE: BYTE ORDER: Both incoming and outgoing MTFTPv6 packets are in network byte order. All other parameters defined in functions or data structures are stored in host byte order.

<table>
<thead>
<tr>
<th>Data Structure</th>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_MTFTP6_PACKET</code></td>
<td>OpCode</td>
<td>Type of packets as defined by the MTFTPv6 packet op-codes. Opcode values are defined below.</td>
</tr>
<tr>
<td></td>
<td>Rrq, Wrq</td>
<td>Read request or write request packet header. See the description for <code>EFI_MTFTP6_REQ_HEADER</code> below in this table.</td>
</tr>
<tr>
<td></td>
<td>Oack</td>
<td>Option acknowledge packet header. See the description for <code>EFI_MTFTP6_OACK_HEADER</code> below in this table.</td>
</tr>
<tr>
<td></td>
<td>Data</td>
<td>Data packet header. See the description for <code>EFI_MTFTP6_DATA_HEADER</code> below in this table.</td>
</tr>
<tr>
<td></td>
<td>Ack</td>
<td>Acknowledgement packet header. See the description for <code>EFI_MTFTP6_ACK_HEADER</code> below in this table.</td>
</tr>
<tr>
<td></td>
<td>Data8</td>
<td>This field should be ignored and treated as reserved. Data packet header with big block number. See the description for <code>EFI_MTFTP6_DATA8_HEADER</code> below in this table.</td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>Field</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ack8</td>
<td>This field should be ignored and treated as reserved. Acknowledgement header with big block number. See the description for <code>EFI_MTFTP6_ACK8_HEADER</code> below in this table.</td>
</tr>
<tr>
<td>Error</td>
<td>Error packet header. See the description for <code>EFI_MTFTP6_ERROR_HEADER</code> below in this table.</td>
</tr>
<tr>
<td><code>EFI_MTFTP6_REQ_HEADER</code></td>
<td>OpCode For this packet type, <code>OpCode = EFI_MTFTP6_OPCODE_RRQ</code> for a read request or <code>OpCode = EFI_MTFTP6_OPCODE_WRQ</code> for a write request.</td>
</tr>
<tr>
<td>Filename</td>
<td>The file name to be downloaded or uploaded.</td>
</tr>
<tr>
<td><code>EFI_MTFTP6_OACK_HEADER</code></td>
<td>OpCode For this packet type <code>OpCode = EFI_MTFTP6_OPCODE_OACK</code>.</td>
</tr>
<tr>
<td>Data</td>
<td>The option strings in the option acknowledgement packet.</td>
</tr>
<tr>
<td><code>EFI_MTFTP6_DATA_HEADER</code></td>
<td>OpCode For this packet type <code>OpCode = EFI_MTFTP6_OPCODE_DATA</code>.</td>
</tr>
<tr>
<td>Block</td>
<td>Block number of this data packet.</td>
</tr>
<tr>
<td>Data</td>
<td>The content of this data packet.</td>
</tr>
<tr>
<td><code>EFI_MTFTP6_ACK_HEADER</code></td>
<td>OpCode For this packet type <code>OpCode = EFI_MTFTP6_OPCODE_ACK</code>.</td>
</tr>
<tr>
<td>Block</td>
<td>The block number of the data packet that is being acknowledged.</td>
</tr>
<tr>
<td><code>EFI_MTFTP6_DATA8_HEADER</code></td>
<td>OpCode This field should be ignored and treated as reserved. For this packet type, <code>OpCode = EFI_MTFTP6_OPCODE_DATA8</code>.</td>
</tr>
<tr>
<td>Block</td>
<td>This field should be ignored and treated as reserved. The block number of data packet.</td>
</tr>
<tr>
<td>Data</td>
<td>This field should be ignored and treated as reserved. The content of this data packet.</td>
</tr>
<tr>
<td>Block</td>
<td>The block number of the data packet that is being acknowledged.</td>
</tr>
<tr>
<td><code>EFI_MTFTP6_ERROR_HEADER</code></td>
<td>OpCode For this packet type <code>OpCode = EFI_MTFTP6_OPCODE_ERROR</code>.</td>
</tr>
<tr>
<td>ErrorCode</td>
<td>The error number as defined by the MTFTPv6 packet error codes. Values for <code>ErrorCode</code> are defined below.</td>
</tr>
<tr>
<td>ErrorMessage</td>
<td>Error message string.</td>
</tr>
</tbody>
</table>

// // MTFTP Packet OpCodes
//
#define EFI_MTFTP6_OPCODE_RRQ 1
#define EFI_MTFTP6_OPCODE_WRQ 2
#define EFI_MTFTP6_OPCODE_DATA 3
#define EFI_MTFTP6_OPCODE_OACK 6

(continues on next page)
Following is a description of the fields in the above definition.

Table 30.31: MTFTP Packet OpCode Descriptions

<table>
<thead>
<tr>
<th>MTFTP Packet OpCode</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_MTFTP6_OPCODE_RRQ</td>
<td>The MTFTPv6 packet is a read request.</td>
</tr>
<tr>
<td>EFI_MTFTP6_OPCODE_WRQ</td>
<td>The MTFTPv6 packet is a write request.</td>
</tr>
<tr>
<td>EFI_MTFTP6_OPCODE_DATA</td>
<td>The MTFTPv6 packet is a data packet.</td>
</tr>
<tr>
<td>EFI_MTFTP6_OPCODE_ACK</td>
<td>The MTFTPv6 packet is an acknowledgement packet.</td>
</tr>
<tr>
<td>EFI_MTFTP6_OPCODE_ERROR</td>
<td>The MTFTPv6 packet is an error packet.</td>
</tr>
<tr>
<td>EFI_MTFTP6_OPCODE_OACK</td>
<td>The MTFTPv6 packet is an option acknowledgement packet.</td>
</tr>
<tr>
<td>EFI_MTFTP6_OPCODE_DIR</td>
<td>The MTFTPv6 packet is a directory query packet.</td>
</tr>
<tr>
<td>EFI_MTFTP6_OPCODE_DATA8</td>
<td>This field should be ignored and treated as reserved. The MTFTPv6 packet is a data packet with a big block number.</td>
</tr>
<tr>
<td>EFI_MTFTP6_OPCODE_ACK8</td>
<td>This field should be ignored and treated as reserved. The MTFTPv6 packet is an acknowledgement packet with a big block number.</td>
</tr>
</tbody>
</table>

// MTFTP ERROR Packet ErrorCodes

//

#define EFI_MTFTP6_ERRORCODE_NOT_DEFINED 0
#define EFI_MTFTP6_ERRORCODE_FILE_NOT_FOUND 1
#define EFI_MTFTP6_ERRORCODE_ACCESS_VIOLATION 2
#define EFI_MTFTP6_ERRORCODE_DISK_FULL 3
#define EFI_MTFTP6_ERRORCODE_ILLEGAL_OPERATION 4
#define EFI_MTFTP6_ERRORCODE_UNKNOWN_TRANSFER_ID 5
#define EFI_MTFTP6_ERRORCODE_FILE_ALREADY_EXISTS 6
#define EFI_MTFTP6_ERRORCODE_NO_SUCH_USER 7
#define EFI_MTFTP6_ERRORCODE_REQUEST_DENIED 8

Table 30.32: MTFTP ERROR Packet ErrorCode Descriptions

<table>
<thead>
<tr>
<th>MTFTP ERROR Packet ErrorCodes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_MTFTP6_ERRORCODE_NOT_DEFINED</td>
<td>The error code is not defined. See the error message in the packet (if any) for details.</td>
</tr>
<tr>
<td>EFI_MTFTP6_ERRORCODE_FILE_NOT_FOUND</td>
<td>The file was not found.</td>
</tr>
<tr>
<td>EFI_MTFTP6_ERRORCODE_ACCESS_VIOLATION</td>
<td>There was an access violation.</td>
</tr>
<tr>
<td>EFI_MTFTP6_ERRORCODE_DISK_FULL</td>
<td>The disk was full or its allocation was exceeded.</td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>Table 30.32 – continued from previous page</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_MTFTP6_ERRORCODE_ILLEGAL_OPERATION</strong></td>
</tr>
<tr>
<td><strong>EFI_MTFTP6_ERRORCODE_UNKNOWN_TRANSFER_ID</strong></td>
</tr>
<tr>
<td><strong>EFI_MTFTP6_ERRORCODE_FILE_ALREADY_EXISTS</strong></td>
</tr>
<tr>
<td><strong>EFI_MTFTP6_ERRORCODE_NO_SUCH_USER</strong></td>
</tr>
<tr>
<td><strong>EFI_MTFTP6_ERRORCODE_REQUEST_DENIED</strong></td>
</tr>
</tbody>
</table>

## Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>An MTFTPv6 OACK packet was received and is in the Packet.</td>
</tr>
</tbody>
</table>
| **EFI_INVALID_PARAMETER** | One or more of the following conditions is TRUE:  
- *This* is NULL.  
- *Filename* is NULL.  
- *OptionCount* is not zero and *OptionList* is NULL.  
- One or more options in *OptionList* have wrong format.  
- *PacketLength* is NULL.  
- *OverrideData.ServerIp* is not a valid unicast IPv6 address and not set to all zero. |
| **EFI_UNSUPPORTED** | One or more options in the *OptionList* are unsupported by this implementation. |
| **EFI_NOT_STARTED** | The EFI MTFTPv6 Protocol driver has not been started. |
| **EFI_NO_MAPPING** | The underlying IPv6 driver was responsible for choosing a source address for this instance, but no source address was available for use. |
| **EFI_ACCESS_DENIED** | The previous operation has not completed yet. |
| **EFI_OUT_OF_RESOURCES** | Required system resources could not be allocated. |
| **EFI_TFTP_ERROR** | An MTFTPv6 ERROR packet was received and is in the Packet. |
| **EFI_NETWORK_UNREACHABLE** | An ICMP network unreachable error packet was received and the Packet is set to NULL. |
| **EFI_NETWORK_UNREACHABLE** | An ICMP host unreachable error packet was received and the Packet is set to NULL. |
| **EFI_NETWORK_UNREACHABLE** | An ICMP protocol unreachable error packet was received and the Packet is set to NULL. |
| **EFI_NETWORK_UNREACHABLE** | An ICMP port unreachable error packet was received and the Packet is set to NULL. |
| **EFI_ICMP_ERROR** | Some other ICMP ERROR packet was received and the Packet is set to NULL. |
| **EFI_PROTOCOL_ERROR** | An unexpected MTFTPv6 packet was received and is in the Packet. |
| **EFI_TIMEOUT** | No responses were received from the MTFTPv6 server. |
| **EFI_DEVICE_ERROR** | An unexpected network error or system error occurred. |
30.4.2.5 EFI_MTFTP6_PROTOCOL.ParseOptions()

Summary
Parse the options in an MTFTPv6 OACK packet.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_MTFTP6_PARSE_OPTIONS)(
    IN EFI_MTFTP6_PROTOCOL *This,
    IN UINT32 PacketLen,
    IN EFI_MTFTP6_PACKET *Packet,
    OUT UINT32 *OptionCount,
    OUT EFI_MTFTP6_OPTION **OptionList OPTIONAL
);

Parameters

This
Pointer to the EFI_MTFTP6_PROTOCOL instance.

PacketLen
Length of the OACK packet to be parsed.

Packet
Pointer to the OACK packet to be parsed. Type EFI_MTFTP6_PACKET is defined in EFI_MTFTP6_PROTOCOL.GetInfo().

OptionCount
Pointer to the number of options in the following OptionList.

OptionList
Pointer to EFI_MTFTP6_OPTION storage. Each pointer in the OptionList points to the corresponding MTFTP option buffer in the Packet. Call the EFI Boot Service FreePool() to release the OptionList if the options in this OptionList are not needed any more. Type EFI_MTFTP6_OPTION is defined in EFI_MTFTP6_PROTOCOL.GetInfo().

Description
The ParseOptions() function parses the option fields in an MTFTPv6 OACK packet and returns the number of options that were found and optionally a list of pointers to the options in the packet.

If one or more of the option fields are not valid, then EFI_PROTOCOL_ERROR is returned and *OptionCount and *OptionList stop at the last valid option.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The OACK packet was valid and the OptionCount and OptionList parameters have been updated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>• PacketLen is 0.</td>
</tr>
<tr>
<td></td>
<td>• Packet is NULL or Packet is not a valid MTFTPv6 packet.</td>
</tr>
<tr>
<td></td>
<td>• OptionCount is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No options were found in the OACK packet.</td>
</tr>
</tbody>
</table>

continues on next page
Table 30.34 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Storage for the OptionList array can not be allocated.</td>
</tr>
<tr>
<td>EFI_PROTOCOL_ERROR</td>
<td>One or more of the option fields is invalid.</td>
</tr>
</tbody>
</table>

30.4.2.6 EFI_MTFTP6_PROTOCOL.ReadFile()

Summary
Download a file from an MTFTPv6 server.

Prototype

typedef EFI_STATUS
(EIFIAPI *EFI_MTFTP6_READ_FILE)(
    IN EFI_MTFTP6_PROTOCOL *This,
    IN EFI_MTFTP6_TOKEN *Token
);

Parameters
This
Pointer to the EFI_MTFTP6_PROTOCOL instance.

Token
Pointer to the token structure to provide the parameters that are used in this operation. Type EFI_MTFTP6_TOKEN is defined in “Related Definitions” below.

Description
The ReadFile() function is used to initialize and start an MTFTPv6 download process and optionally wait for completion. When the download operation completes, whether successfully or not, the Token.Status field is updated by the EFI MTFTPv6 Protocol driver and then Token.Event is signaled if it is not NULL.

Data can be downloaded from the MTFTPv6 server into either of the following locations:

- A fixed buffer that is pointed to by Token.Buffer
- A download service function that is pointed to by Token.CheckPacket

If both Token.Buffer and Token.CheckPacket are used, then Token.CheckPacket will be called first. If the call is successful, the packet will be stored in Token.Buffer.

Related Definitions

```c
//******************************************************
// EFI_MTFTP6_TOKEN
//******************************************************
typedef struct {
    EFI_STATUS Status;
    EFI_EVENT Event;
    EFI_MTFTP6_OVERRIDE_DATA OverrideData;
    UINT8 *Filename;
    UINT8 *ModeStr;
    UINT32 OptionCount;
    EFI_MTFTP6_OPTION OptionList;
    UINT64 BufferSize;
    VOID *Buffer;
} EFI_MTFTP6_TOKEN;
```
VOID *Context;
EFI_MTFTP6_CHECK_PACKET CheckPacket;
EFI_MTFTP6_TIMEOUT_CALLBACK TimeoutCallback;
EFI_MTFTP6_PACKET_NEEDED PacketNeeded;
} EFI_MTFTP6_TOKEN;

Status
The status that is returned to the caller at the end of the operation to indicate whether this operation completed successfully. Defined Status values are listed below.

Event
The event that will be signaled when the operation completes. If set to NULL, the corresponding function will wait until the read or write operation finishes. The type of Event must be EVT_NOTIFY_SIGNAL.

OverrideData
If not NULL, the data that will be used to override the existing configure data. Type EFI_MTFTP6_OVERRIDE_DATA is defined in EFI_MTFTP6_PROTOCOL.GetInfo().

Filename
Pointer to the null-terminated ASCII file name string.

ModeStr
Pointer to the null-terminated ASCII mode string. If NULL, octet is used.

OptionCount
Number of option/value string pairs.

OptionList
Pointer to an array of option/value string pairs. Ignored if OptionCount is zero. Both a remote server and this driver implementation should support these options. If one or more options are unrecognized by this implementation, it is sent to the remote server without being changed. Type EFI_MTFTP6_OPTION is defined in EFI_MTFTP6_PROTOCOL.GetInfo().

BufferSize
On input, the size, in bytes, of Buffer. On output, the number of bytes transferred.

Buffer
Pointer to the data buffer. Data that is downloaded from the MTFTPv6 server is stored here. Data that is uploaded to the MTFTPv6 server is read from here. Ignored if BufferSize is zero.

Context
Pointer to the context that will be used by CheckPacket, TimeoutCallback and PacketNeeded.

CheckPacket
Pointer to the callback function to check the contents of the received packet. Type EFI_MTFTP6_CHECK_PACKET is defined below.

TimeoutCallback
Pointer to the function to be called when a timeout occurs. Type EFI_MTFTP6_TIMEOUT_CALLBACK is defined below.

PacketNeeded
Pointer to the function to provide the needed packet contents. Only used in WriteFile() operation. Type EFI_MTFTP6_PACKET_NEEDED is defined below.

The EFI_MTFTP6_TOKEN structure is used for both the MTFTPv6 reading and writing operations.

The caller uses this structure to pass parameters and indicate the operation context. After the reading or writing operation completes, the EFI MTFTPv6 Protocol driver updates the Status parameter and the Event is signaled if it is not NULL. The following table lists the status codes that are returned in the Status parameter.
### Status Codes Return in the Status Parameter

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data file has been transferred successfully.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>BufferSize is not zero but not large enough to hold the downloaded data in downloading process.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>Current operation is aborted by user.</td>
</tr>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>An ICMP network unreachable error packet was received.</td>
</tr>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>An ICMP host unreachable error packet was received.</td>
</tr>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>An ICMP protocol unreachable error packet was received.</td>
</tr>
<tr>
<td>EFI_NETWORK_UNREACHABLE</td>
<td>An ICMP port unreachable error packet was received.</td>
</tr>
<tr>
<td>EFI_ICMP_ERROR</td>
<td>Some other ICMP ERROR packet was received.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>No responses were received from the MTFTPv6 server.</td>
</tr>
<tr>
<td>EFI_TFTP_ERROR</td>
<td>An MTFTPv6 ERROR packet was received.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network error or system error occurred.</td>
</tr>
</tbody>
</table>

```c
//***********************************************
// EFI_MTFTP6_CHECK_PACKET
//***********************************************
typedef EFI_STATUS
  (EFIAPI *EFI_MTFTP6_CHECK_PACKET)(
     IN EFI_MTFTP6_PROTOCOL *This,
     IN EFI_MTFTP6_TOKEN *Token,
     IN UINT16 PacketLen,
     IN EFI_MTFTP6_PACKET *Packet
);
```

**This**

Pointer to the `EFI_MTFTP6_PROTOCOL` instance.

**Token**

The token that the caller provided in the `EFI_MTFTP6_PROTOCOL.ReadFile()`, `WriteFile()` or `ReadDirectory()` function. Type `EFI_MTFTP6_TOKEN` is defined in `EFI_MTFTP6_PROTOCOL.ReadFile()`.

**PacketLen**

Indicates the length of the packet.

**Packet**

Pointer to an MTFTPv6 packet. Type `EFI_MTFTP6_PACKET` is defined in `EFI_MTFTP6_PROTOCOL.GetInfo()`.

`EFI_MTFTP6_CHECK_PACKET` is a callback function that is provided by the caller to intercept the `EFI_MTFTP6_OPCODE_DATA` or `EFI_MTFTP6_OPCODE_DATA8` packets processed in the `EFI_MTFTP6_PROTOCOL.ReadFile()` function, and alternatively to intercept `EFI_MTFTP6_OPCODE_OACK` or `EFI_MTFTP6_OPCODE_ERROR` packets during a call to `EFI_MTFTP6_PROTOCOL.ReadFile()`, `WriteFile()` or `ReadDirectory()`. Whenever an MTFTPv6 packet with the type described above is received from a server, the EFI MTFTPv6 Protocol driver will call `EFI_MTFTP6_CHECK_PACKET` function to let the caller have an opportunity to process this packet. Any status code other than `EFI_SUCCESS` that is returned from this function will abort the transfer process.
typedef EFI_STATUS (EFIAPI *EFI_MTFTP6_TIMEOUT_CALLBACK)(
    IN EFI_MTFTP6_PROTOCOL *This,
    IN EFI_MTFTP6_TOKEN *Token
);

This
Pointer to the EFI_MTFTP6_PROTOCOL instance.

Token
The token that is provided in the
EFI_MTFTP6_PROTOCOL.ReadFile() or
EFI_MTFTP6_PROTOCOL.ReadDirectory() functions by the caller. Type
EFI_MTFTP6_TOKEN is defined in
EFI_MTFTP6_PROTOCOL.ReadFile().

EFI_MTFTP6_TIMEOUT_CALLBACK is a callback function that the caller provides to capture the
timeout event in the EFI_MTFTP6_PROTOCOL.ReadFile(), EFI_MTFTP6_PROTOCOL.WriteFile() or
EFI_MTFTP6_PROTOCOL.ReadDirectory() functions. Whenever a timeout occurs, the EFI MTFTPv6 Proto-
col driver will call the EFI_MTFTP6_TIMEOUT_CALLBACK function to notify the caller of the timeout event. Any
status code other than EFI_SUCCESS that is returned from this function will abort the current download process.

typedef EFI_STATUS (EFIAPI *EFI_MTFTP6_PACKET_NEEDED)(
    IN EFI_MTFTP6_PROTOCOL *This,
    IN EFI_MTFTP6_TOKEN Token,
    IN OUT UINT16 *Length,
    OUT VOID **Buffer
);

This
Pointer to the EFI_MTFTP6_PROTOCOL instance.

Token
The token provided in the EFI_MTFTP6_PROTOCOL.WriteFile() by the caller.

Length
Indicates the length of the raw data wanted on input, and the length the data available on output.

Buffer
Pointer to the buffer where the data is stored.

EFI_MTFTP6_PACKET_NEEDED is a callback function that the caller provides to feed data to the
EFI_MTFTP6_PROTOCOL.WriteFile() function. EFI_MTFTP6_PACKET_NEEDED provides another mechan-
ism for the caller to provide data to upload other than a static buffer. The EFI MTFTP6 Protocol driver always calls
EFI_MTFTP6_PACKET_NEEDED to get packet data from the caller if no static buffer was given in the initial call to
**EFI_MTFTP6_PROTOCOL.WriteFile()** function. Setting **Length** to zero signals the end of the session. Returning a status code other than **EFI_SUCCESS** aborts the session.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>The data file is being downloaded.</td>
</tr>
<tr>
<td><strong>EFI_INVALID_PARAMETER</strong></td>
<td>One or more of the parameters is not valid.</td>
</tr>
<tr>
<td></td>
<td>• <em>This</em> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <em>Token</em> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <em>Token.Filename</em> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <em>Token.OptionCount</em> is not zero and <em>Token.OptionList</em> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• One or more options in <em>Token.OptionList</em> have wrong format.</td>
</tr>
<tr>
<td></td>
<td>• <em>Token.Buffer</em> and <em>Token.CheckPacket</em> are both <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <em>Token.OverrideData.ServerIp</em> is not a valid unicast IPv6 address and not set to all zero.</td>
</tr>
<tr>
<td><strong>EFI_UNSUPPORTED</strong></td>
<td>One or more options in the <em>Token.OptionList</em> are not supported by this implementation.</td>
</tr>
<tr>
<td><strong>EFI_NOT_STARTED</strong></td>
<td>The EFI MTFTPv6 Protocol driver has not been started.</td>
</tr>
<tr>
<td><strong>EFI_NO_MAPPING</strong></td>
<td>The underlying IPv6 driver was responsible for choosing a source address for this instance, but no source address was available for use.</td>
</tr>
<tr>
<td><strong>EFI_ALREADY_STARTED</strong></td>
<td>This <em>Token</em> is being used in another MTFTPv6 session.</td>
</tr>
<tr>
<td><strong>EFI_ACCESS_DENIED</strong></td>
<td>The previous operation has not completed yet.</td>
</tr>
<tr>
<td><strong>EFI_OUT_OF_RESOURCES</strong></td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td><strong>EFI_DEVICE_ERROR</strong></td>
<td>An unexpected network error or system error occurred.</td>
</tr>
<tr>
<td><strong>EFI_NO_MEDIA</strong></td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

#### 30.4.2.7 EFI_MTFTP6_PROTOCOL.WriteFile()

**Summary**

Send a file to an MTFTPv6 server. May be unsupported in some implementations.

**Prototype**

```c
typedef EFI_STATUS
  (EFIAPICALL Convention
   EFI_STATUS
    *(EFI_MTFTP6_PROTOCOL_WRITE_FILE)(
        IN EFI_MTFTP6_PROTOCOL  *This,
        IN EFI_MTFTP6_TOKEN     *Token
    );
```

**Parameters**

**This**

Pointer to the **EFI_MTFTP6_PROTOCOL** instance.

**Token**

Pointer to the token structure to provide the parameters that are used in this function. Type **EFI_MTFTP6_TOKEN** is defined in **EFI_MTFTP6_PROTOCOL.ReadFile()**.

**Description**
The `WriteFile()` function is used to initialize an uploading operation with the given option list and optionally wait for completion. If one or more of the options is not supported by the server, the unsupported options are ignored and a standard TFTP process starts instead. When the upload process completes, whether successfully or not, `Token.Event` is signaled, and the EFI MTFTPv6 Protocol driver updates `Token.Status`.

The caller can supply the data to be uploaded in the following two modes:

- Through the user-provided buffer
- Through a callback function

With the user-provided buffer, the `Token.BufferSize` field indicates the length of the buffer, and the driver will upload the data in the buffer. With an `EFI_MTFTP6_PACKET_NEEDED` callback function, the driver will call this callback function to get more data from the user to upload. See the definition of `EFI_MTFTP6_PACKET_NEEDED` for more information. These two modes cannot be used at the same time. The callback function will be ignored if the user provides the buffer.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The upload session has started.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The operation is not supported by this implementation.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following conditions is <strong>TRUE</strong>:</td>
</tr>
<tr>
<td></td>
<td>• This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <code>Token</code> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <code>Token.Filename</code> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <code>Token.OptionCount</code> is not zero and <code>Token.OptionList</code> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• One or more options in <code>Token.OptionList</code> have wrong format.</td>
</tr>
<tr>
<td></td>
<td>• <code>Token.Buffer</code> and <code>Token.PacketNeeded</code> are both <strong>NULL</strong>.</td>
</tr>
<tr>
<td></td>
<td>• <code>Token.OverrideData.ServerIp</code> is not a valid unicast IPv6 address and not</td>
</tr>
<tr>
<td></td>
<td>set to all zero.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>One or more options in the <code>Token.OptionList</code> are not supported by this im-</td>
</tr>
<tr>
<td></td>
<td>plementation.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI MTFTPv6 Protocol driver has not been started.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The underlying IPv6 driver was responsible for choosing a source address</td>
</tr>
<tr>
<td></td>
<td>for this instance, but no source address was available for use.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>This <code>Token</code> is already being used in another MTFTPv6 session.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The previous operation has not completed yet.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network error or system error occurred.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There was a media error.</td>
</tr>
</tbody>
</table>

**30.4.2.8 EFI_MTFTP6_PROTOCOL.ReadDirectory()**

**Summary**

Download a data file directory from an MTFTPv6 server. May be unsupported in some implementations.

**Prototype**

```c
typedef EFI_STATUS
    (EFIAPI *EFI_MTFTP6_READ_DIRECTORY)(
```

(continues on next page)
Parameters

This

Pointer to the EFI_MTFTP6_PROTOCOL instance.

Token

Pointer to the token structure to provide the parameters that are used in this function. Type EFI_MTFTP6_TOKEN is defined in EFI_MTFTP6_PROTOCOL.ReadFile().

Description

The ReadDirectory() function is used to return a list of files on the MTFTPv6 server that are logically (or operationally) related to Token.Filename. The directory request packet that is sent to the server is built with the option list that was provided by caller, if present.

The file information that the server returns is put into either of the following locations:

- A fixed buffer that is pointed to by Token.Buffer
- A download service function that is pointed to by Token.CheckPacket

If both Token.Buffer and Token.CheckPacket are used, then Token.CheckPacket will be called first. If the call is successful, the packet will be stored in Token.Buffer.

The returned directory listing in the Token.Buffer or EFI_MTFTP6_PACKET consists of a list of two or three variable-length ASCII strings, each terminated by a null character, for each file in the directory. If the multicast option is involved, the first field of each directory entry is the static multicast IP address and UDP port number that is associated with the file name. The format of the field is ip:ip:ip:ip:port. If the multicast option is not involved, this field and its terminating null character are not present.

The next field of each directory entry is the file name and the last field is the file information string. The information string contains the file size and the create/modify timestamp. The format of the information string is filesize yyyy-mm-dd hh:mm:ss:ffff. The timestamp is Coordinated Universal Time (UTC; also known as Greenwich Mean Time [GMT]).

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The MTFTPv6 related file “directory” has been downloaded.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The EFI MTFTPv6 Protocol driver does not support this function.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of these conditions is TRUE:</td>
</tr>
<tr>
<td></td>
<td>- <strong>This</strong> is NULL.</td>
</tr>
<tr>
<td></td>
<td>- <strong>Token</strong> is NULL.</td>
</tr>
<tr>
<td></td>
<td>- <strong>Token.Filename</strong> is NULL.</td>
</tr>
<tr>
<td></td>
<td>- <strong>Token.OptionCount</strong> is not zero and <strong>Token.OptionList</strong> is NULL.</td>
</tr>
<tr>
<td></td>
<td>- One or more options in <strong>Token.OptionList</strong> have wrong format.</td>
</tr>
<tr>
<td></td>
<td>- <strong>Token.Buffer</strong> and <strong>Token.CheckPacket</strong> are both NULL.</td>
</tr>
<tr>
<td></td>
<td>- <strong>Token.OverrideData.ServerIp</strong> is not a valid unicast IPv6 address and not set to all zero.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>One or more options in the <strong>Token.OptionList</strong> are not supported by this implementation.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>The EFI MTFTPv6 Protocol driver has not been started.</td>
</tr>
</tbody>
</table>
30.4.2.9 EFI_MTFTP6_PROTOCOL.Poll()

Summary
Polls for incoming data packets and processes outgoing data packets.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_MTFTP6_POLL) (IN EFI_MTFTP6_PROTOCOL *This);
```

Parameters

This
Pointer to the EFI_MTFTP6_PROTOCOL instance.

Description

The Poll() function can be used by network drivers and applications to increase the rate that data packets are moved between the communications device and the transmit and receive queues.

In some systems, the periodic timer event in the managed network driver may not poll the underlying communications device fast enough to transmit and/or receive all data packets without missing incoming packets or dropping outgoing packets. Drivers and applications that are experiencing packet loss should try calling the Poll() function more often.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Incoming or outgoing data was processed.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>This EFI MTFTPv6 Protocol instance has not been started.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>This</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system or network error occurred.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Data was dropped out of the transmit and/or receive queue. Consider increa-</td>
</tr>
<tr>
<td></td>
<td>sing the polling rate.</td>
</tr>
</tbody>
</table>

Table 30.38 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_NO_MAPPING</td>
<td>The underlying IPv6 driver was responsible for choosing a source address</td>
</tr>
<tr>
<td></td>
<td>for this instance, but no source address was available for use.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>This Token is already being used in another MTFTPv6 session.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The previous operation has not completed yet.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected network error or system error occurred.</td>
</tr>
</tbody>
</table>
31.1 EFI Redfish Discover Protocol

31.1.1 Overview

The purpose of the EFI Redfish Discover is to provide a mechanism for EFI Redfish clients to acquire the DMTF Redfish® services provided on the platform or network. See the Redfish Developer Hub at https://redfish.dmtf.org/ for official Redfish schema and specifications. Redfish services can be discovered according to Redfish Host Interface (SMBIOS type 42h) reported on platform, or optionally using Simple Service Discovery Protocol (SSDP) message over UDP port 1900 to search Redfish services which were joined well-known multicast group addresses. EFI Redfish Discover driver discovers Redfish services and creates EFI REST EX protocol instance for each Redfish service it found. It also configures EFI REST EX protocol instance according to the Redfish service information described in Redfish Host Interface or the response of UPnP M-SEARCH request (defined in UPnP Device Architecture, which can be obtained at “Links to UEFI-Related Documents” http://uefi.org/uefi).

EFI Redfish Discover Protocol behaves as a middle protocol which abstracts the creation and configuration of EFI REST EX instance from EFI Redfish clients.

- EFI Redfish Discover Protocol uses EFI UDP protocol to send SSDP message to verify or discover Redfish services. For the Redfish service reported by SMBIOS type 42h, EFI Redfish Discover Protocol can optionally unicast M-SEARCH request to Redfish service in order to verify the existence of service.

- EFI Redfish Discover Protocol can optionally provide the functionality of discovering Redfish services through each network interface installed on platform. Prior to acquiring the list of ready-to-use EFI REST EX protocol instances, the consumer of this protocol can get the network interface list and decide which interface is used for the multicast transmission. EFI Redfish Discover Protocol multicasts M-SEARCH request to multicast group addresses then collects M-SEARCH responses from Redfish services in asynchronous or synchronous manner.

- EFI Redfish Discover Protocol provides the information of each network interface installed on platform through GetNetworkInterfaceList() function. The information such as MAC address, subnet ID, subnet mask and VLAN ID of network interface could be utilized by upper-layer EFI application or driver to identify network interface used for Redfish service discovery. EFI Redfish Discover Protocol abstracts EFI network stack to user which means this protocol should not require user to configure UDP before utilizing services. Network configuration of network interface such as station IP address, subnet ID, subnet mask and other operational parameters should be configured through system firmware specific implementation (for example system utility). This protocol should simply use UDP default station properties.

Multicast across internetworks is handled by multicast router and is not in the scope of EFI Redfish Discover Protocol. The implementation of upper-layer user interface is system firmware design-specific.

- EFI Redfish Discovery Protocol is the helper driver to discover Redfish services on platform or network. The upper level EFI Redfish client could provide its own implementation of how to utilize information returned from this protocol. Such as network interface selection UI, create Redfish host interface (SMBIOS type 42h) according to Redfish services information, configure system BIOS setting using Redfish service or etc.
31.1.2 EFI Redfish Discover Driver

A Redfish Discover Driver installs the Redfish Discover Protocol and EFI Driver Binding Protocol in its driver entry point.

The Driver Binding Protocol contains three services. These are Supported(), Start(), and Stop(). Supported() tests to see if the Redfish Discover Driver can manage a device handle. A Redfish Discover Driver can manage device handle that contain the EFI REST EX Service Binding Protocol, EFI UDP4 Service Binding Protocol or EFI UDP6 Service Binding Protocol, so a Redfish Discover Driver must look for these three protocols on the device handle that is being tested, and return success if any of them is presented.

The Start() function tells the Redfish Discover Driver to start managing a device driver. The device handle should support at least one of the service binding protocols checked in Supported(). The Redfish Discover Driver should create a child handle for each service binding protocol, and open these children with BY_DRIVER attribute.

![Diagram of device handles and service protocols]

The Stop() function tells the Redfish Discover Driver to stop managing a device driver. The Stop() function can destroy one or more of the device handles (or its child handles) that being managed by Redfish Discover Driver. A Redfish Discover Driver should stop the in-process discovery and destroy corresponding child handle which was created in a previous call to Start(), or in AcquireRedfishService().

31.1.3 EFI Redfish Discover Client

An EFI Redfish client invokes EFI Redfish Discover Protocol to acquire the ready-to-use EFI REST EX protocol instance.

Below is the conceptual figure of mechanism of EFI Redfish Discover Protocol. The first scenario is unicast M-SEARCH to verify Redfish service reported in SMBIOS type 42h.

1. EFI Redfish client invokes EFI Redfish Discover Protocol to acquire ready-to-use EFI REST EX for communicating with Redfish services reported in Redfish Host Interface (SMBIOS type 42h)
2. EFI Redfish Discover Protocol optionally verifies the existence of Redfish service by unicaering M-SEARCH to Redfish service according to the Redfish service information provided in Redfish Host Interface.
3. 3EFI Redfish Discover Protocol creates and configures REST EX instance for Redfish service according to the Redfish service information provided in Redfish Host Interface.
4. EFI Redfish clients communicate with Redfish service using EFI REST EX instance returned from EFI Redfish Discover protocol.

EFI Redfish client passes EFI_REDFISH_DISCOVERED_TOKEN and the discovery options to EFI Redfish Discover Protocol. EFI_EVENT is created by EFI Redfish client for retrieving EFI_REDFISH_DISCOVERED_LIST once EFI Redfish Discover Protocol optionally verifies Redfish service reported by Redfish Host Interface. EFI Redfish client
can listen to the notification of verified Redfish service in asynchronous or synchronous according to the setting of options indicated in `EFI_REDFISH_DISCOVER_FLAG`.

The second scenario is optionally provided by EFI Redfish Discover Protocol, which is multicast M-SEARCH to discover Redfish services.

1. EFI Redfish client gets the list of network interfaces if it would like to discover Redfish services on the certain network.
2. EFI Redfish client invokes EFI Redfish Discover Protocol to acquire ready-to-use EFI REST EX for communicating with Redfish services.
3. EFI Redfish Discover Protocol discovers Redfish services through SSDP over UDP.
4. EFI Redfish clients communicate with Redfish service using EFI REST EX instance returned from EFI Redfish Discover protocol.

EFI Redfish client passes `EFI_REDFISH_DISCOVERED_TOKEN` and the discovery options to EFI Redfish Discover Protocol. `EFI_EVENT` is created by EFI Redfish client for retrieving `EFI_REDFISH_DISCOVERED_LIST` when any time EFI Redfish Discover Protocol discovers new Redfish service. EFI Redfish client can listen to the notification of new found Redfish service in asynchronous or synchronous according to the setting of options indicated in `EFI_REDFISH_DISCOVER_FLAG`. Setting `Timeout` to zero in `EFI_REDFISH_DISCOVERED_TOKEN` to waiting for the new discovered Redfish service in synchronously, otherwise asynchronous notification happens when new Redfish service is discovered by EFI Redfish Discover Protocol.
31.1.4 EFI Redfish Discover Protocol

Summary
This protocol is utilized by EFI Redfish clients to acquire the list of Redfish services provided on platform or network.

Protocol GUID

```c
#define EFI_REDFISH_DISCOVER_PROTOCOL_GUID \ 
{0x5db12509, 0x4550, 0x4347, 
{0x96, 0xb3, 0x73, 0xc0, 0xff, 0x6e, 0x86, 0x9f}}
```

Protocol Interface Structure

```c
typedef struct _EFI_REDFISH_DISCOVER_PROTOCOL {
    EFI_REDFISH_DISCOVER_NETWORK_LIST GetNetworkInterfaceList;
    EFI_REDFISH_DISCOVER_ACQUIRE_SERVICE AcquireRedfishService;
    EFI_REDFISH_DISCOVER_ABORT_ACQUIRE AbortAcquireRedfishService;
    EFI_REDFISH_DISCOVER_RELEASE_SERVICE ReleaseRedfishService;
} EFI_REDFISH_DISCOVER_PROTOCOL;
```

Parameters

**GetNetworkInterfaceList**
Get the list of network interfaces on which Redfish services could be discovered.

**AcquireRedfishService**
Acquire the list of Redfish services.
AbortAcquireRedfishService
Abort Redfish services acquire process.

ReleaseRedfishService
Release Redfish services acquired from AcquireRedfishService().

Description
EFI Redfish Discover Protocol provides a mechanism for EFI Redfish clients to acquire the Redfish services provided
on the platform or network as described before.

31.1.4.1 EFI_REDFISH_DISCOVER_PROTOCOL.GetNetworkInterfaceList()

Summary
Get the currently available list of network interfaces on which Redfish services could be discovered.

Protocol Interface

```c
typedef
EFI_STATUS
(EFIAPICALLETYPE)EFI_REDFISH_DISCOVER_NETWORK_LIST(
    IN EFI_REDFISH_DISCOVER_PROTOCOL *This,
    IN EFI_HANDLE ImageHandle,
    OUT UINTN *NumberOfNetworkInterfaces,
    OUT EFI_REDFISH_DISCOVER_NETWORK_INTERFACE **NetworkInterfaces
);
```

Parameters

This
This is the EFI_REDFISH_DISCOVER_PROTOCOL instance.

ImageHandle
EFI image to get network list. The image handle is caller’s image handle.

NumberOfNetworkInterfaces
Number of network interfaces in NetworkInterfaces.

NetworkInterfaces
It’s an array of instances. The number of entries in NetworkInterfaces is indicated by NumberOfNet-
workInterfaces. Caller has to release the memory allocated by Redfish discover protocol with a call to
EFI_BOOT_SERVICES.FreePool().

Description
This function is used to get the list of network interfaces which can be used to send SSDP message over UDP
protocol for the Redfish services discovery. The entry in NetworkInterfaces could be used as the parameter to
EFI_REDFISH_DISCOVER_PROTOCOL.AcquireRedfishService function for discovering Redfish service on specific
network interface.

Related Description

```c
//******************************************************************************
// EFI_REDFISH_DISCOVER_NETWORK_INTERFACE
//******************************************************************************
typedef struct {
    EFI_MAC_ADDRESS MacAddress;
    BOOLEAN IsIpv6;
} EFI_REDFISH_DISCOVER_NETWORK_INTERFACE;
```

(continues on next page)
Parameters

MacAddress
MAC address of this network interface.

IsIpv6
If TRUE, indicates the network interface is running IPv6. Otherwise the network interface is running IPv4.

SubnetId
Subnet of this network.

SubnetPrefixLength
Subnet prefix-length for IPv4 and IPv6.

VlanId
VLAN ID of this network interface.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Network interface is returned in NetworkInterfaces and the number of network interfaces is returned in NumberOfNetworkInterfaces successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One of below parameters is NULL. ImageHandle, NumberOfNetworkInterfaces, and NetworkInterfaces</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Unable to return network interface list.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No network interfaces are found.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCE</td>
<td>Not enough resources to return network interfaces to caller.</td>
</tr>
</tbody>
</table>

31.1.4.2 EFI_REDFISH_DISCOVER_PROTOCOL.AcquireRedfishService()

Summary
This function acquires the list of discovered Redfish services.

Protocol Interface

typedef

EFI_STATUS

(EIFIAPI *EFI_REDFISH_DISCOVER_ACQUIRE_SERVICE)(
    IN EFI_REDFISH_DISCOVER_PROTOCOL     *This,
    IN EFI_HANDLE                      ImageHandle,
    IN EFI_REDFISH_DISCOVER_NETWORK_INTERFACE  *TargetNetworkInterface OPTIONAL,
    IN EFI_REDFISH_DISCOVER_FLAG        Flags,
    IN EFI_REDFISH_DISCOVERED_TOKEN     *Token
);

Parameters

This
This is the EFI_REDFISH_DISCOVER_PROTOCOL instance.
ImageHandle
EFI image acquires Redfish service discovery. The image handle is caller’s image handle.

TargetNetworkInterface
The target Network Interface which is used to discover Redfish services. Set to NULL to discover Redfish services on all network interfaces.

Flags
Options of Redfish service discovery.

Token

EFI_REDFISH_DISCOVERED_TOKEN instance. The memory of
EFI_REDFISH_DISCOVERED_LIST and the strings in
EFI_REDFISH_DISCOVERED_INFORMATION are all allocated by
AcquireRedfishService() and must be freed when caller invokes
ReleaseRedfishService().

Description
This function is used to acquire the list of Redfish services which are discovered according to Redfish Host Interface or through SSDP over UDP. Redfish services discovery through SSDP over UDP could be achieved via network interface specified in TargetNetworkInterface or via all network interfaces if TargetNetworkInterface is specified as NULL. EFI_REDFISH_DISCOVERED_LIST is returned to EFI Redfish client by signaling the EFI event created by client. Each of EFI handle in EFI_REDFISH_DISCOVERED_LIST has the corresponding EFI REST EX instance installed on it. Each REST EX instance is a child instance which is created through EFI REST EX service binding protocol and used by EFI Redfish client for communicating with specific Redfish service. In AcquireRedfishService(), UDP child is created and opened to do SSDP discovery. This UDP child will be destroyed right away after the discovery is done. AcquireRedfishService() also creates and opens REST EX child to configures REST EX instance according to Redfish service information returned in M-SEARCH response or Redfish Host Interface. REST EX child must be closed after REST EX child is configured. EFI Redfish client must open REST EX instance from RedfishRestExHandle returned in EFI_REDFISH_DISCOVERED_INFORMATION and close REST EX instance once EFI Redfish client is no longer communicating with Redfish service.

Related Description

EFI_REDFISH_DISCOVER_FLAG

EFI_REDFISH_DISCOVER_FLAG is used to indicate the options when EFI Redfish clients acquire Redfish discover list through this protocol. Redfish Discover Protocol discovers Redfish service according to Redfish Host Interface when EFI_REDFISH_DISCOVER_HOST_INTERFACE is set to TRUE. Redfish Discover Protocol also optionally discovers Redfish services using SSDP UPnP M-SEARCH request through UDP Port 1900. Redfish Discover Protocol returns EFI_INVALID_PARAMETER if none of EFI_REDFISH_DISCOVER_HOST_INTERFACE and EFI_REDFISH_DISCOVER_SSDP is set to TRUE. Set EFI_REDFISH_DISCOVER_SSDP to indicate using IPv6 as internet protocol. For the Redfish service discovery according to Redfish Host Interface, Redfish service information like IP address is described in Redfish Host Interface. EFI Redfish client can set

31.1. EFI Redfish Discover Protocol
**EFI_REDFISH_DISCOVER_VALIDATION** to **TRUE** to ask Redfish Discover Protocol to validate this Redfish service using IP address described in Redfish Host Interface. Redfish Discover Protocol unicasts UPnP M-SEARCH request to the target Redfish service and verify the response message to determine if the target Redfish service is existing or not. **EFI_REDFISH_DISCOVER_VALIDATION** doesn’t affect the SSDP discovery. For Redfish SSDP discovery, the responses of the multicast UPnP M-SEARCH request imply the valid Redfish services are existing.

According to UPnP device architecture, the maximum waiting time of the response to UPnP M-SEARCH request is indicated in MX message header. The value is greater or equal to 1 to less than 5 inclusive in second. In order to give the chance to those Redfish services which do not respond to M-SEARCH in time, set **EFI_REDFISH_DISCOVER_KEEP_ALIVE** to **TRUE** to tell Redfish Discover Protocol keeps to sending multicast M-SEARCH request. The duration of periodical multicast request is declared in **EFI_REDFISH_DISCOVER_DURATION_MASK**. The value indicated in **EFI_REDFISH_DISCOVER_DURATION_MASK** means 2 to the power of duration. The valid value of duration is greater or equal to 3 and less or equal to 15. The corresponding duration is 8 to 2^15 seconds. Minimum duration is set to 8 seconds in order to keep the duration out of scope of MX value defined in UPnP device architecture. Duration is only valid when **EFI_REDFISH_DISCOVER_KEEP_ALIVE** is set to **TRUE** and **EFI_REDFISH_DISCOVER_SSDP** is set to **TRUE**.

Redfish Discover Protocol maintains an internal database of Redfish services it found. It also maintains the EFI image which owns the EFI REST EX instance of discovered Redfish services. Redfish Discover Protocol only signals EFI Redfish client with new found of Redfish services instead of notifying EFI Redfish clients all found Redfish services, even the Redfish service which was already discovered and notified previously.

```c
//*******************************************************
// EFI_REDFISH_DISCOVERED_TOKEN
//*******************************************************
#define REDFISH_DISCOVERED_TOKEN_SIGNATURE SIGNATURE_32 ('R', 'F', 'T', 'S')
typedef struct {
    UINT32       Signature;
    EFI_REDFISH_DISCOVERED_LIST DiscoveredList;
    EFI_EVENT    Event;
    UINTN        Timeout;
} EFI_REDFISH_DISCOVERED_TOKEN;
```

**Description**

**EFI_REDFISH_DISCOVERED_TOKEN** is created by EFI Redfish client and passed to **AcquireRedfishService()**.

**Parameters**

**Signature**

The token signature should be the value of **REDFISH_DISCOVER_TOKEN_SIGNATURE** defined above.

**DiscoveredList**

Structure of **EFI_REDFISH_DISCOVERED_LIST** to retrieve the discovered Redfish services.

**Event**

EFI event at the **TPL_CALLBACK** level created by EFI Redfish client, which is used to be notified when Redfish services are discovered or any errors occurred during discovery.

**Timeout**

The timeout value declared in **EFI_REDFISH_DISCOVERED_TOKEN** determines the seconds to drop discovery process. Basically, the nearby Redfish services must give the response in >=1 and <= 5 seconds. The valid timeout value used for the asynchronous discovery is >= 1 and <= 5 seconds. Set the timeout to zero means to discover Redfish service synchronously.
typedef struct {
    UINTN NumberOfServiceFound;
    EFI_REDFISH_DISCOVERED_INSTANCE *RedfishInstances;
} EFI_REDFISH_DISCOVERED_LIST;

Description
The content of EFI_REDFISH_DISCOVERED_LIST is filled by AcquireRedfishService() before signaling Event. NumberOfServiceFound must be set to 0 and RedfishInstances must be NULL when client invokes AcquireRedfishService(). The memory block for RedfishInstances is allocated by the EFI Redfish Discover Protocol, and will be freed by the EFI Redfish Discover Protocol as well in ReleaseRedfishService().

Parameters
NumberOfServiceFound
Number of Redfish services are discovered.

RedfishInstances
Pointer to EFI_REDFISH_DISCOVERED_INSTANCE, number of Redfish services are discovered is indicated in NumberOfServiceFound.

typedef struct {
    EFI_STATUS Status;
    EFI_REDFISH_DISCOVERED_INFORMATION Information;
} EFI_REDFISH_DISCOVERED_INSTANCE;

Description
This structure describes the status and the information of discovered Redfish service.

Parameters
Status
EFI status code of Redfish service discovery.

Information
The information of Redfish service discovered. The information is only valid when Status is EFI_SUCCESS. Refer to below description of EFI_REDFISH_DISCOVERED_INSTANCE.

typedef struct {
    EFI_HANDLE RedfishRestExHandle;
    BOOLEAN IsIPv6;
    EFI_IP_ADDRESS RedfishHostIpAddress;
    UINT16 RedfishVersion;
    CHAR16 *Location;
    CHAR16 *Uuid;
    CHAR16 *Os;
    CHAR16 *OsVersion;
} EFI_REDFISH_DISCOVERED_INFORMATION;

(continues on next page)
CHAR16 *Product;
CHAR16 *ProductVersion;
BOOLEAN UseHttps;
}

} EFI_REDFISH_DISCOVERED_INFORMATION;

Description
This structure describes each Redfish service information. The corresponding EFI REST EX protocol instance is
also created and configured by EFI Redfish Discover Protocol for EFI Redfish client. The memory allocated for the
information in this structure will be freed by EFI Redfish Discover Protocol in ReleaseRedfishService().

Parameters
RedfishRestExHandle
EFI handle which has EFI REST EX protocol instance installed on it. The EFI REST EX protocol instance is already configured by EFI Redfish Discover Protocol through EFI_REST_EX_PROTOCOL.Configure() according to the Redfish host information discovered through Redfish Host Interface or SSDP.

IsIPv6
Indicates the Redfish service is reached via IPv6 protocol.

RedfishHostIpAddress
Redfish service host IP address.

RedfishVersion
Redfish service version. The high byte of RedfishVersion is the major Redfish service version, low byte is the minor Redfish version. For example 0x100 is Redfish service. Redfish service version is acquired from “ST” header in the response of M-SEARCH request.

Location
Redfish service host location, this information is acquired from “Server” header returned in the response of M-SEARCH request.

Uuid
The UUID of Redfish service, this information is acquired from “USN” header defined in UPnP Device Architecture specification.

Os
The OS provides Redfish service, this information is acquired from “Server” header returned in the response of M-SEARCH request. Below is the response in “Server” header defined in UPnP Device Architecture specification. SERVER:OS/version UPnP/1.1 product/version OsVersion Redfish service OS version, this information is acquired from “Server” header returned in the response of M-SEARCH request. Below is the response in “Server” header defined in UPnP Device Architecture specification. SERVER:OS/version UPnP/1.1 product/version

Product
Product name, this information is extracted from “Server” header returned in the response of M-SEARCH request. Below is the response in “Server” header defined in UPnP Architecture Device specification. SERVER:OS/version UPnP/1.1 product/version

ProductVersion
Product version, this information is acquired from “Server” header returned in the response of M-SEARCH request. Below is the response in “Server” header defined in UPnP Device Architecture specification. SERVER:OS/version UPnP/1.1 product/version UseHttps Indicates the Redfish service is reached via HTTPS protocol.

Status Codes Returned
### EFI_SUCCESS
Acquire for Redfish service list is successful.

### EFI_INVALID_PARAMETER

One or more of the following is TRUE:
- *This* is `NULL`.
- *ImageHandle* is `NULL`.
- *Flags* is 0 or the improper bit combination of option is set in *Flag*.
- *Token* is `NULL`.
- *Token->Timeout* is greater than 5 seconds.
- *Token->Event* is `NULL`.

On input,
- *Token->DiscoveredList->NumberOfServiceFound* is not 0, or
- *Token-> DiscoveredList->RedfishInstances* is not `NULL`.

### Others
Fail to acquire the list of Redfish service.

#### 31.1.4.3 EFI_REDFISH_DISCOVER_PROTOCOL.AbortAcquireRedfishService()

**Summary**

This function aborts Redfish service discovery on the given network interface.

**Protocol Interface**

```c
typedef EFI_STATUS (EFIAPI *EFI_REDFISH_DISCOVER_ABORT_ACQUIRE)(
  IN EFI_REDFISH_DISCOVER_PROTOCOL *This,
  IN *EFI_REDFISH_DISCOVER_NETWORK_INTERFACE *TargetNetworkInterface OPTIONAL);
```

**Parameters**

- **This**
  - This is the `EFI_REDFISH_DISCOVER_PROTOCOL` instance.

- **TargetNetworkInterface**
  - The target Network Interface on which Redfish services discovery is in process. NULL to abort Redfish service discovery on all network interfaces.

**Description**

In `AbortAcquireRedfishService()`, to abort the in-process Redfish service, discovery is required for preventing unexpected behaviors from happening. This function has to cancel in-process SSDP, the unicast over Udp4/Udp6, close Udp4/Udp6 protocol and destroy the Udp4/Udp6 child. Also closes REST EX opened for configuring REST EX child instance.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Redfish service discovery is aborted.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | One or more of the following is `TRUE`:
- *This* is `NULL`. |
31.1.4.4 EFI_REDFISH_DISCOVER_PROTOCOL.ReleaseRedfishService()

Summary
This function releases the list of Redfish services discovered previously.

Protocol Interface
typedef EFI_STATUS (EFIAPI *EFI_REDFISH_DISCOVER_RELEASE_SERVICE)(
    IN EFI_REDFISH_DISCOVER_PROTOCOL *This,
    IN EFI_REDFISH_DISCOVERED_LIST *List
);

Parameters
This
This is the EFI_REDFISH_DISCOVER_PROTOCOL instance.

List
The pointer to EFI_REDFISH_DISCOVERED_LIST which lists the Redfish services to release.

Description
The Redfish services which listed in List will be released in ReleaseRedfishService(). All memory blocks which were allocated for Redfish service information will be freed in this function. EFI REST EX protocol instance which was created in AcquireRedfishService() will be also destroyed in ReleaseRedfishService(). The Redfish service listed in *List* is not required to be identical or in the same order with EFI_REDFISH_DISCOVERED_LIST retuned from AcquireRedfishService(). List is flexible to list any Redfish services which were discovered by AcquireRedfishService() earlier. In ReleaseRedfishService(), free the resource allocated for the discovered Redfish service indicated in EFI_REDFISH_DISCOVERED_LIST.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Redfish services listed in *<em>List</em> are released successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following is TRUE:</td>
</tr>
<tr>
<td></td>
<td>- <em>This</em> is NULL.</td>
</tr>
<tr>
<td></td>
<td>- <em>List</em> is NULL.</td>
</tr>
<tr>
<td></td>
<td>- Invalid settings in *List.</td>
</tr>
</tbody>
</table>

31.1.5 Implementation Examples

31.1.5.1 Processes to Discover Redfish Services

The following flowchart delineates the EFI Redfish client processes of utilizing EFI Discover Protocol to discover Redfish service, abort discovery and release discovered Redfish service instance.
31.1.5.2 Network Interface Configuration

The EFI Redfish Discover Protocol provides a Redfish service discovery function to discover Redfish service through SMBIOS type 42 or optionally discover Redfish service on specific network interface. EFI Redfish Clients (EFI driver or EFI Application) can utilize the discover function to acquire Redfish service and manipulate Redfish properties to manage a system. For example, applying BIOS settings on the systems managed by Redfish Service. The system could be the one that runs EFI Redfish Client, or other systems on the network. If Redfish service is discovered according to SMBIOS type 42, then the platform developer has to create an SMBIOS type 42 entry with host (station) and Redfish Service information (Refer to DSP0270, Redfish Host Interface Specification). Besides discovering Redfish service using SMBIOS type 42, Redfish services can be also discovered by using SSDP over UDP. However, the network interface must be configured using either DHCP or static configuration prior to discovery of Redfish services. If the network interface is configured statically, then at least the IP address and Subnet mask must be configured for the station. The VLAN ID and new route entry may need to be configured depending on the networking environment if necessary.

Below is the implementation example for configuring network interface. Network interface could be configured in platform-implementation method. For example, platform developer can provide HII network options in BIOS setup utility. Network interface could be configured in statically or dynamically (DHCP) manner and the configuration could be stored in EFI variables or any platform non-volatile storage which may consumed by network stacks when each time system boot. This makes sure certain network interface is configured properly before EFI Redfish Clients utilizing EFI Redfish Discover Protocol.

The alternative of configuring network stack is system boots to EFI Shell and execute ifconfig shell command. This configures the settings of certain network interfaces. After this, network interface is ready to process Redfish service discovery by EFI Redfish Clients. However, this method requires user to configure network interface when each time system boot to EFI shell, unless other implementations of ifconfig EFI shell command is provided.

Once EFI Redfish Client is launched, it gets network interface information using EFI Redfish Discover protocol. EFI Redfish Client may provide selection UI of network interfaces for Redfish service discovery. EFI Redfish Client could manipulate Redfish properties such as BIOS Attributes on the discovered Redfish services for system management or deployment. EFI Redfish Client can also optionally maintain the information, location and other properties of discovered Redfish services in non-volatile storage for next system boots afterward.
31.2 EFI Redfish JSON Structure Converter

31.2.1 The Guidance of Writing EFI Redfish JSONStructure Converter

To provide interoperability between the Redfish service and the EFI environment, EFI Redfish JSON structure converters for each Redfish schema namespace should be implemented for EFI Redfish clients. This recommendation of writing EFI Redfish JSON structure converters is necessary to unify the implementation and capability of the converters.

- One converter supports one Redfish schema resource type; write the converter based on Redfish resource type. Using Redfish schema as an example:

  — AccountService.v1_0_0.json: RedfishAccountService_V1_0_0_Dxe driver

  — AttributeRegistry.v1_2_0.json: RedfishAttributeRegistry_V1_2_0_Dxe driver

  — EthernetInterface.v1_4_0.json: EthernetInterface_V1_4_0_Dxe driver

- Redfish JSON structure converter can be delivered in source code package or binary (library or EFI driver) format.
- A C header file must be released with the Redfish JSON structure converter package. The package could be provisioned to conform to any EFI implementation, such as EFI EDKII open source.
- Provide documents which can describe the usage of structure members defined in REST JSON structure.
- The documentation can be published with a source code package, binary package, web site, online help, etc.
- Write the converter as an EFI DXE driver, and utilize EFI_REST_JSON_STRUCTURE_PROTOCOL to register the converter to provide the corresponding EFI_REST_JSON_STRUCTURE_PROTOCOL functions:
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

— ToStructure()

—ToJson()

—DestoryStructure()

• FI_REST_JSON_RESOURCE_TYPE_IDENTIFIER

Namespace

ResourceTypeName: String to Redfish schema resource type.

MajorVersion:
String to Redfish schema major version, NULL string for non version controlled schema.

MinorVersion:
String to Redfish schema minor version, NULL string for non version controlled schema.

ErrataVersion:
String to Redfish schema errata version, NULL string for non version controlled schema. Datatype

Datatype
String to data type defined in Redfish schema

Examples
AccountService.v1_0_0.json

Namespace

ResourceTypeName: “AccountService” MajorVersion:”1” MinorVersion:”0” ErrataVersion:”0”

Datatype: “AccountService”

Namespace


Datatype: “ComputerSystemCollection”

• Determine Redfish resource type according to the given JsonRsclIdentifier. If the given JsonRsclIdentifier is non-
NULL, the Redfish resource structure converter must convert the JSON resource to the Redfish JSON structure
according to the resource type and revision specified in JsonRsclIdentifier. The converter should not refer to the
resource type and revision according to Redfish namespace and datatype indicated in “odata.type” in JSON text
resource. This prevents from the returned structure format is different with what consumer expects.

• Automatically determine the Redfish resource type. If the given JsonRsclIdentifier is NULL, the EFI
Redfish JSON structure converter should check the namespace and datatype indicated in “odata.type”
in the JSON text resource. Parse this identifier property to retrieve the corresponding Redfish schema
name space and data type, then decode the JSON text resource into the corresponding structure.
EFI_REST_JSON_RESOURCE_TYPE_IDENTIFIER in JsonStructure returned to consumer should be filled
with the correct Redfish schema resource type information following the guidance mentioned above.

• All structure members for Redfish schema must be declared as C pointers. With this, the converter consumer
can get the partial Redfish JSON properties from the converter. The consumer just initializes certain structure
members, and the converter producer only converts non-NULL pointers in the given structure into corresponding
Redfish JSON properties in text format.

31.2. EFI Redfish JSON Structure Converter
31.2.2 The Guidance of Using EFI Redfish JSON Structure Converter

The consumer of EFI Redfish JSON structure converter utilizes EFI_REST_JSON_STRUCTURE_PROTOCOL for converting Redfish JSON resource to Redfish JSON structure and vice versa.

Refer to the converter document to include the C header file of the Redfish JSON structure converter into the build process. For example, include the converter’s EDKII package into an EFI module INF file for the C header file reference, or follow the build rule of other EFI implementations.

There are two ways for a consumer to convert JSON resources using the EFI_REST_JSON_STRUCTURE_PROTOCOL:

- Setup the correct Redfish namespace and datatype in EFI_REST_JSON_RESOURCE_TYPE_IDENTIFIER. This makes sure the EFI REST JSON Structure Protocol uses the exact converter that the consumer prefers for the conversion. In this case, the Redfish namespace and datatype indicated in “odata.type” in the EFI_REST_JSON_RESOURCE_TYPE_IDENTIFIER is set to NULL. This means the converter may recognize the Redfish namespace and datatype indicated in “odata.type” in the JSON text resource, and converts it to the C structure it supports. In this case, the consumer has to be careful when using a C structure pointer to refer to the Redfish JSON structure.

- EFI_REST_JSON_RESOURCE_TYPE_IDENTIFIER set to NULL means the returned structure format may not be in the same form as the consumer’s expectation. The consumer then has to check the EFI_REST_JSON_RESOURCE_TYPE_IDENTIFIER for the Redfish namespace and datatype, and use the correct prototype for structure reference.
32.1 Secure Boot

This protocol is intended to provide access for generic authentication information associated with specific device paths. The authentication information is configurable using the defined interfaces. Successive configuration of the authentication information will overwrite the previously configured information. Once overwritten, the previous authentication information will not be retrievable.

32.1.1 EFI_AUTHENTICATION_INFO_PROTOCOL

Summary

This protocol is used on any device handle to obtain authentication information associated with the physical or logical device.

**GUID**

```c
#define EFI_AUTHENTICATION_INFO_PROTOCOL_GUID  
{0x7671d9d0,0x53db,0x4173,  
{0xaa,0x69,0x23,0x27,0xf2,0x1f,0x0b,0xc7}}
```

Protocol Interface Structure

```c
typedef struct _EFI_AUTHENTICATION_INFO_PROTOCOL {
  EFI_AUTHENTICATION_INFO_PROTOCOL_GET Get;
  EFI_AUTHENTICATION_INFO_PROTOCOL_SET Set;
} EFI_AUTHENTICATION_INFO_PROTOCOL;
```

Parameters

**Get()**

Used to retrieve the Authentication Information associated with the controller handle

**Set()**

Used to set the Authentication information associated with the controller handle

Description

The *EFI_AUTHENTICATION_INFO_PROTOCOL* provides the ability to get and set the authentication information associated with the controller handle.
32.1.2 EFI_AUTHENTICATION_INFO_PROTOCOL.Get()

Summary
Retrieves the Authentication information associated with a particular controller handle.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_AUTHENTICATION_INFO_PROTOCOL_GET) (
    IN EFI_AUTHENTICATION_INFO_PROTOCOL *This,
    IN EFI_HANDLE ControllerHandle,
    OUT VOID **Buffer
);
```

Parameters

This
Pointer to the EFI_AUTHENTICATION_INFO_PROTOCOL

ControllerHandle
Handle to the Controller

Buffer
Pointer to the authentication information. This function is responsible for allocating the buffer and it is the caller's responsibility to free buffer when the caller is finished with buffer.

Description
This function retrieves the Authentication Node for a given controller handle.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Successfully retrieved Authentication information for the given ControllerHandle</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>No matching Authentication information found for the given ControllerHandle</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The authentication information could not be retrieved due to a hardware error.</td>
</tr>
</tbody>
</table>

32.1.3 EFI_AUTHENTICATION_INFO_PROTOCOL.Set()

Summary
Set the Authentication information for a given controller handle.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_AUTHENTICATION_INFO_PROTOCOL_SET) (
    IN EFI_AUTHENTICATION_INFO_PROTOCOL **This,
    IN EFI_HANDLE *ControllerHandle,
    IN VOID **Buffer
);
```

Parameters
This
   Pointer to the EFI_AUTHENTICATION_INFO_PROTOCOL

ControllerHandle
   Handle to the controller.

Buffer
   Pointer to the authentication information.

Description
This function sets the authentication information for a given controller handle. If the authentication node exists correspond- ing to the given controller handle this function overwrites the previously present authentication information.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Successfully set the Authentication node information for the given ControllerHandle.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>If the platform policies do not allow setting of the Authentication information.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The authentication node information could not be configured due to a hardware error.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Not enough storage is available to hold the data.</td>
</tr>
</tbody>
</table>

32.1.4 Authentication Nodes

The authentication node is associated with specific controller paths. There can be various types of authentication nodes, each describing a particular authentication method and associated properties.

32.1.5 Generic Authentication Node Structures

An authentication node is a variable length binary structure that is made up of variable length authentication information. The Table below defines the generic structure. The Authentication type GUID defines the corresponding authentication node.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type GUID</td>
<td>0</td>
<td>16</td>
<td>Authentication Type GUID</td>
</tr>
<tr>
<td>Length</td>
<td>16</td>
<td>2</td>
<td>Length of this structure in bytes.</td>
</tr>
<tr>
<td>Specific Authentication Data</td>
<td>18</td>
<td>n</td>
<td>Specific Authentication Data. Type defines the authentication method and associated type of data. Size of the data is included in the length.</td>
</tr>
</tbody>
</table>

All Authentication Nodes are byte-packed data structures that may appear on any byte boundary. All code references to Authentication Nodes must assume all fields are UNALIGNED. Since every Authentication Node contains a length field in a known place, it is possible to traverse Authentication Node of unknown type.
32.1.6 CHAP (using RADIUS) Authentication Node

This Authentication Node type defines the CHAP authentication using RADIUS information.

**GUID**

```c
#define EFI_AUTHENTICATION_CHAP_RADIUS_GUID \
{0xd6062b50,0x15ca,0x11da,\ 
{0x92,0x19,0x00,0x10,0x83,0xff,0xca,0x4d}}
```

**Node Definition**

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>16</td>
<td>EFI_AUTHENTICATION_CHAP_RADIUS_GUID</td>
</tr>
<tr>
<td>Length</td>
<td>16</td>
<td>2</td>
<td>Length of this structure in bytes. Total length is 58+P+Q+R+S+T</td>
</tr>
<tr>
<td>RADIUS IP Address</td>
<td>18</td>
<td>16</td>
<td>Radius IPv4 or IPv6 Address</td>
</tr>
<tr>
<td>Reserved</td>
<td>34</td>
<td>2</td>
<td>Reserved</td>
</tr>
<tr>
<td>NAS IP Address</td>
<td>36</td>
<td>16</td>
<td>NAS IPv4 or IPv6 Address</td>
</tr>
<tr>
<td>NAS Secret Length</td>
<td>52</td>
<td>2</td>
<td>NAS Secret LengthP</td>
</tr>
<tr>
<td>NAS Secret</td>
<td>54</td>
<td>p</td>
<td>NAS Secret</td>
</tr>
<tr>
<td>CHAP Secret Length</td>
<td>54+P</td>
<td>2</td>
<td>CHAP Secret Length Q</td>
</tr>
<tr>
<td>CHAP Secret</td>
<td>56+P</td>
<td>q</td>
<td>CHAP Secret</td>
</tr>
<tr>
<td>CHAP Name Length</td>
<td>56 +Q</td>
<td>2</td>
<td>CHAP Name Length R</td>
</tr>
<tr>
<td>CHAP Name</td>
<td>58+P+Q</td>
<td>r</td>
<td>CHAP Name String</td>
</tr>
<tr>
<td>Reverse CHAP Name Length</td>
<td>58+P+Q+R</td>
<td>2</td>
<td>Reverse CHAP Name length</td>
</tr>
<tr>
<td>Reverse CHAP Name</td>
<td>60+P+Q+R</td>
<td>S</td>
<td>Reverse CHAP Name</td>
</tr>
<tr>
<td>Reverse CHAP Secret Length</td>
<td>60+P+Q+R+S</td>
<td>2</td>
<td>Reverse CHAP Length</td>
</tr>
<tr>
<td>Reverse CHAP Secret</td>
<td>62+P+Q+R+S</td>
<td>T</td>
<td>Reverse CHAP Secret</td>
</tr>
</tbody>
</table>

**Summary**

RADIUS IP Address...RADIUS Server IPv4 or IPv6 Address
NAS IP Address...Network Access Server IPv4 or IPv6 Address (OPTIONAL)
NAS Secret Length...Network Access Server Secret Length in bytes (OPTIONAL)
NAS Secret...Network Access Server secret (OPTIONAL)
CHAP Secret Length...CHAP Initiator Secret length in bytes
CHAP Secret...CHAP Initiator Secret
CHAP Name...Length CHAP Initiator Name Length in bytes
CHAP Name CHAP Initiator Name
Reverse CHAP name length Reverse CHAP name length
Reverse CHAP Name Reverse CHAP name

32.1. Secure Boot
Reverse CHAP Secret Length  Reverse CHAP secret length
Reverse CHAP Secret  Reverse CHAP secret

**CHAP (using local database) Authentication Node**

This Authentication Node type defines CHAP using local database information.

**GUID**

```c
#define EFI_AUTHENTICATION_CHAP_LOCAL_GUID
{0xc280c73e,0x15ca,0x11da,
{0xb0,0xca,0x00,0x10,0x83,0xff,0xca,0x4d}}
```

**Node Definition**

Table 32.4: CHAP Authentication Node Structure using Local Database

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>0</td>
<td>16</td>
<td>EFI_AUTHENTICATION_CHAP_LOCAL_GUID</td>
</tr>
<tr>
<td>Length</td>
<td>16</td>
<td>2</td>
<td>Length of this structure in bytes. Total length is 58+P+Q+R+S+T</td>
</tr>
<tr>
<td>Reserved</td>
<td>18</td>
<td>2</td>
<td>Reserved for future use</td>
</tr>
<tr>
<td>User Secret</td>
<td>20</td>
<td>2</td>
<td>User Secret Length</td>
</tr>
<tr>
<td>User Secret</td>
<td>22</td>
<td>p</td>
<td>User Secret</td>
</tr>
<tr>
<td>User Name</td>
<td>22+p</td>
<td>2</td>
<td>User Name Length</td>
</tr>
<tr>
<td>User Name</td>
<td>24+p</td>
<td>q</td>
<td>User Name</td>
</tr>
<tr>
<td>CHAP Secret</td>
<td>24+p+q</td>
<td>2</td>
<td>CHAP Secret Length</td>
</tr>
<tr>
<td>CHAP Secret</td>
<td>26+p+q</td>
<td>r</td>
<td>CHAP Secret</td>
</tr>
<tr>
<td>CHAP Name</td>
<td>26+p+q+r</td>
<td>2</td>
<td>CHAP Name Length</td>
</tr>
<tr>
<td>CHAP Name</td>
<td>28+p+q+r</td>
<td>s</td>
<td>CHAP Name String</td>
</tr>
<tr>
<td>Reverse CHAP</td>
<td>58+P+Q+R</td>
<td>2</td>
<td>Reverse CHAP Name length</td>
</tr>
<tr>
<td>Reverse CHAP</td>
<td>60+P+Q+R</td>
<td>S</td>
<td>Reverse CHAP Name</td>
</tr>
<tr>
<td>Reverse CHAP</td>
<td>60+P+Q+R+S</td>
<td>2</td>
<td>Reverse CHAP Length</td>
</tr>
<tr>
<td>Reverse CHAP</td>
<td>62+P+Q+R+S</td>
<td>T</td>
<td>Reverse CHAP Secret</td>
</tr>
</tbody>
</table>

**Summary**

User Secret Length . . . User Secret Length in bytes
User Secret . . . User Secret
User Name Length . . . User Name Length in bytes
User Name . . . User Name
CHAP Secret Length . . . CHAP Initiator Secret length in bytes
CHAP Secret . . . CHAP Initiator Secret
CHAP Name Length . . . CHAP Initiator Name Length in bytes
32.2 UEFI Driver Signing Overview

This section describes a means of generating a digital signature for a UEFI executable, embedding that digital signature within the UEFI executable and verifying that the digital signature is from an authorized source. The UEFI specification provides a standard format for executables. These executables may be located on un-secured media (such as a hard drive or unprotected flash device) or may be delivered via a un-secured transport layer (such as a network) or originate from a un-secured port (such as ExpressCard device or USB device). In each of these cases, the system provider may decide to authenticate either the origin of the executable or its integrity (i.e., it has not been tampered with). This section describes a means of doing so.

32.2.1 Digital Signatures

As a rule, digital signatures require two pieces: the data (often referred to as the message) and a public/private key pair. In order to create a digital signature, the message is processed by a hashing algorithm to create a hash value. This hash value is, in turn, encrypted using a signature algorithm and the private key to create the digital signature.

In order to verify a signature, two pieces of data are required: the original message and the public key. First, the hash must be calculated exactly as it was calculated when the signature was created. Then the digital signature is decoded using the public key and the result is compared against the computed hash. If the two are identical, then you can be sure that message data is the one originally signed and it has not been tampered with.

32.2.2 Embedded Signatures

The signatures used for digital signing of UEFI executables are embedded directly within the executable itself. Within the header is an array of directory entries. Each of these entries points to interesting places within the executable image. The fifth data directory entry contains a pointer to a list of certificates along with the length of the certificate areas. Each certificate may contain a digital signature used for validating the driver. The following diagram illustrates how certificates are embedded in the PE/COFF file:

Within the PE/COFF optional header is a data directory. The 5th entry, if filled, points to a list of certificates. Normally, these certificates are appended to the end of the file.

32.2.3 Creating Image Digests from Images

One of the pieces required for creating a digital signature is the image digest. For a detailed description on how to create image digests from PE/COFF images, refer to the “Creating the PE Image Hash” section of the Microsoft Authenticode Format specification (see References).
Fig. 32.1: Creating A Digital Signature
Fig. 32.2: Verifying a Digital Signature
32.2.4 Code Definitions

This section describes data structures used for signing UEFI executables.

32.2.4.1 WIN_CERTIFICATE

Summary

The WIN_CERTIFICATE structure is part of the PE/COFF specification.

Prototype

```c
typedef struct _WIN_CERTIFICATE {
    UINT32    dwLength;
    UINT16    wRevision;
    UINT16    wCertificateType;
    //UINT8    bCertificate[ANYSIZE_ARRAY];
} WIN_CERTIFICATE;
```

dwLength

The length of the entire certificate, including the length of the header, in bytes.

wRevision

The revision level of the WIN_CERTIFICATE structure. The current revision level is 0x0200.

wCertificateType

The certificate type. See WIN_CERT_TYPE_xxx for the UEFI certificate types. The UEFI specification reserves the range of certificate type values from 0x0EF0 to 0x0EFF.
bCertificate

The actual certificate. The format of the certificate depends on wCertificateType. The format of the UEFI certificates is defined below.

Related Definitions

```
#define WIN_CERT_TYPE_PKCS_SIGNED_DATA 0x0002
#define WIN_CERT_TYPE_EFI_PKCS115 0x0EF0
#define WIN_CERT_TYPE_EFI_GUID 0x0EF1
```

Description

This structure is the certificate header. There may be zero or more certificates.

- If the wCertificateType field is set to WIN_CERT_TYPE_EFI_PKCS115, then the certificate follows the format described in WIN_CERTIFICATE_EFI_PKCS1_I5.
- If the wCertificateType field is set to WIN_CERT_TYPE_EFI_GUID, then the certificate follows the format described in WIN_CERTIFICATE_UEFI_GUID.
- If the wCertificateType field is set to WIN_CERT_TYPE_PKCS_SIGNED_DATA then the certificate is formatted as described in the Authenticode specification.

These certificates can be validated using the contents of the signature database described in Signature Database. The following table illustrates the relationship between the certificates and the signature types in the database.

**NOTE:** In the case of a WIN_CERT_TYPE_PKCS_SIGNED_DATA (or WIN_CERT_TYPE_EFI_GUID where Cert-Type = EFI_CERT_TYPE_PKCS7_GUID) certificate, a match can occur against an entry in the authorized signature database (or the forbidden signature database; UEFI Image Variable GUID & Variable Name) at any level of the chain of X.509 certificates present in the certificate, and matches can occur against any of the applicable signature types defined in (Firmware/OS Key Exchange: Passing Public Keys).

Table 32.5: PE/COFF Certificates Types and UEFI Signature Database Certificate Types

<table>
<thead>
<tr>
<th>Image Certificate Type</th>
<th>Verified Using Signature Database Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>WIN_CERT_TYPE_EFI_PKCS115 (Signature Size = 256 bytes)</td>
<td>EFI_CERT_RSA2048_GUID (public key)</td>
</tr>
<tr>
<td>WIN_CERT_TYPE_EFI_GUID (CertType = EFI_CERT_TYPE_RSA2048_SHA256_GUID*)</td>
<td>EFI_CERT_RSA2048_GUID (public key).</td>
</tr>
<tr>
<td>WIN_CERT_TYPE_EFI_GUID (CertType = EFI_CERT_TYPE_PKCS7_GUID)*</td>
<td>EFI_CERT_X509_GUID, EFI_CERT_RSA2048_GUID (when applicable), EFI_CERT_X509_SHA256_GUID (when applicable), EFI_CERT_X509_SHA384_GUID (when applicable), EFI_CERT_X509_SHA512_GUID (when applicable)</td>
</tr>
</tbody>
</table>

continues on next page
Table 32.5 – continued from previous page

<table>
<thead>
<tr>
<th>WIN_CERT_TYPE_PKCS_SIGNED_DATA</th>
<th>EFI_CERT_X509_GUID</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>EFI_CERT_RSA2048_GUID (when applicable)</td>
</tr>
<tr>
<td></td>
<td>EFI_CERT_X509_SHA256_GUID (when applicable)</td>
</tr>
<tr>
<td></td>
<td>EFI_CERT_X509_SHA384_GUID (when applicable)</td>
</tr>
<tr>
<td></td>
<td>EFI_CERT_X509_SHA512_GUID (when applicable)</td>
</tr>
</tbody>
</table>

(Always applicable regardless of whether a certificate is present or not)

|                                 | EFI_CERT_SHA1_GUID, |
|                                 | EFI_CERT_SHA224_GUID, |
|                                 | EFI_CERT_SHA256_GUID, |
|                                 | EFI_CERT_SHA384_GUID, |
|                                 | EFI_CERT_SHA512_GUID |

In this case, the database contains the hash of the image.

### 32.2.4.2 WIN_CERTIFICATE_EFI_PKCS1_15

**Summary**

Certificate which encapsulates the RSASSA_PKCS1-v1_5 digital signature.

**Prototype**

```c
typedef struct _WIN_CERTIFICATE_EFI_PKCS1_15 {
    WIN_CERTIFICATE Hdr;
    EFI_GUID HashAlgorithm;
    // UINT8 Signature[ANYSIZE_ARRAY];
} WIN_CERTIFICATE_EFI_PKCS1_15;
```

**Hdr**

This is the standard WIN_CERTIFICATE header, where `wCertificateType` is set to `WIN_CERT_TYPE_EFI_PKCS1_15`.

**HashAlgorithm**

This is the hashing algorithm which was performed on the UEFI executable when creating the digital signature. It is one of the enumerated values pre-defined in `EFI Hash Algorithms`. See `EFI_HASH_ALGORITHM_x`.

**Signature**

This is the actual digital signature. The size of the signature is the same size as the key (2048-bit key is 256 bytes) and can be determined by subtracting the length of the other parts of this header from the total length of the certificate as found in `Hdr.dwLength`.

**Description**

The `WIN_CERTIFICATE_EFI_PKCS1_15` structure is derived from `WIN_CERTIFICATE` and encapsulates the information needed to implement the RSASSA-PKCS1-v1_5 digital signature algorithm as specified in RFC2437, sections 8-9.
32.2.4.3 WIN_CERTIFICATE_UEFI_GUID

Summary
Certificate which encapsulates a GUID-specific digital signature.

Prototype

```c
typedef struct _WIN_CERTIFICATE_UEFI_GUID {
    WIN_CERTIFICATE Hdr;
    EFI_GUID CertType;
    UINT8 CertData[ANYSIZE_ARRAY];
} WIN_CERTIFICATE_UEFI_GUID;
```

**Hdr**
This is the standard WIN_CERTIFICATE header, where `wCertificateType` is set to WIN_CERT_TYPE_EFI_GUID.

**CertType**
This is the unique id which determines the format of the `CertData`.

**CertData**
This is the certificate data. The format of the data is determined by the `CertType`.

Related Definitions

```c
#define EFI_CERT_TYPE_RSA2048_SHA256_GUID
{0xa7717414, 0xc616, 0x4977, \n  {0x94, 0x20, 0x84, 0x47, 0x12, 0xa7, 0x35, 0xbf}}
#define EFI_CERT_TYPE_PKCS7_GUID
{0x4aafd29d, 0x68df, 0x49ee, \n  {0x8a, 0xa9, 0x34, 0x7d, 0x37, 0x56, 0x65, 0xa7}}
typedef struct _EFI_CERT_BLOCK_RSA_2048_SHA256 {
    EFI_GUID HashType;
    UINT8 PublicKey[256];
    UINT8 Signature[256];
} EFI_CERT_BLOCK_RSA_2048_SHA256;
```

**PublicKey**
The RSA exponent e for this structure is 0x10001.

**Signature**
This signature block is PKCS 1 version 1.5 formatted.

Description
The WIN_CERTIFICATE_UEFI_GUID certificate type allows new types of certificates to be developed for driver authentication without requiring a new certificate type. The `CertType` defines the format of the `CertData`, which length is defined by the size of the certificate less the fixed size of the WIN_CERTIFICATE_UEFI_GUID structure.

- If `CertType` is EFI_CERT_TYPE_RSA2048_SHA256_GUID then the structure which follows has the format specified by EFI_CERT_BLOCK_RSA_2048_SHA256.
- If `CertType` is EFI_CERT_TYPE_PKCS7_GUID then the `CertData` component shall contain a DER-encoded PKCS #7 version 1.5 [RFC2315] SignedData value.
32.3 Firmware/OS Key Exchange: Creating Trust Relationships

This section describes a means of creating a trust relationship between the platform owner, the platform firmware, and an operating system. This trust relationship enables the platform firmware and one or more operating systems to exchange information in a secure manner. The trust relationship uses two types of asymmetric key pairs:

**Platform Key (PK)**

The platform key establishes a trust relationship between the platform owner and the platform firmware. The platform owner enrolls the public half of the key (PKpub) into the platform firmware. The platform owner can later use the private half of the key (PKpriv) to change platform ownership or to enroll a Key Exchange Key. For UEFI, the recommended Platform Key format is RSA-2048. See “Enrolling The Platform Key” and “Clearing The Platform Key” for more information.

**Key Exchange Key (KEK)**

Key exchange keys establish a trust relationship between the operating system and the platform firmware. Each operating system (and potentially, each 3rd party application which need to communicate with platform firmware) enrolls a public key (KEKpub) into the platform firmware. See “Enrolling Key Exchange Keys” for more information.

While no Platform Key is enrolled, the SetupMode variable shall be equal to 1. While SetupMode == 1, the platform firmware shall not require authentication in order to modify the Platform Key, Key Enrollment Key, OsRecoveryOrder, OsRecovery####, and image security databases.

After the Platform Key is enrolled, the SetupMode variable shall be equal to 0. While SetupMode == 0, the platform firmware shall require authentication in order to modify the Platform Key, Key Enrollment Key, OsRecoveryOrder, OsRecovery####, and image security databases.

While no Platform Key is enrolled, and while the variable AuditMode == 0, the platform is said to be operating in setup mode.

After the Platform Key is enrolled, and while the variable AuditMode == 0, the platform is operating in user mode. The platform will continue to operate in user mode until the Platform Key is cleared, or the system is transitioned to either Audit or Deployed Modes. See “Clearing The Platform Key,” “Transitioning to Audit Mode,” and “Transitioning to Deployed Mode” for more information.

Audit Mode enables programmatic discovery of signature list combinations that successfully authenticate installed EFI images without the risk of rendering a system unbootable. Chosen signature lists configurations can be tested to ensure the system will continue to boot after the system is transitioned out of Audit Mode. Details on how to transition to Audit Mode are detailed below in the section “Transitioning to Audit Mode.” After transitioning to Audit Mode, signature enforcement is disabled such that all images are initialized and enhanced Image Execution Information Table (IEIT) logging is performed including recursive validation for multi-signed images.

Deployed Mode is the most secure mode. For details on transitioning to Deployed Mode see the section “Transitioning to Deployed Mode” below. By design, both User Mode and Audit Mode support unauthenticated transitions to Deployed Mode. However, to move from Deployed Mode to any other mode requires a secure platform-specific method, or deleting the PK, which is authenticated.

Secure Boot Mode transitions to User Mode or Deployed Mode shall take effect immediately. Mode transitions to Setup Mode or Audit Mode may either take effect immediately (recommended) or after a reset. For implementations that require a reset, the mode transition shall be processed prior to the initialization of the SecureBoot variable, and the SetVariable() workflow shall be as follows:

1. If the variable has an authenticated attribute, it shall be authenticated as specified, and failure will result in immediate termination of this workflow by returning the appropriate error.

2. Check secure storage to determine if a Secure Boot Mode transition is already queued. If a transition is already queued, terminate this workflow by returning EFI_ALREADY_STARTED

3. Queue the request to secure storage
4. The Secure Boot Mode and Policy variables SHALL remain unchanged

5. Return EFI_WARN_RESET_REQUIRED.

6. After reboot, if the transition is successful, Secure Boot Mode and Policy variables will change accordingly. If the transition to lower security modes is rejected or fail, the workflow is terminated and the Secure Boot Mode and Policy variables remain unchanged.

### 32.3.1 Enrolling The Platform Key

The platform owner enrolls the public half of the Platform Key (PKpub) by calling the UEFI Boot Service `SetVariable()` as specified in *Using the EFI_VARIABLE_AUTHENTICATION_3 descriptor*. If the platform is in setup mode, then the new PKpub may be signed with its PKpriv counterpart. If the platform is in user mode, then the new PKpub must be signed with the current PKpriv. When the platform is in setup mode, a successful enrollment of a Platform Key shall cause the platform to immediately transition to user mode.

The authenticated PK variable can always be read but can only be written if the platform is in setup mode, or if the platform is in user mode and the provided PKpub is signed with the current PKpriv.

The name and GUID of the Platform Key variable are specified in *Globally Defined Variables* “Globally Defined Variables” The variable has the format of a signature database as described in “Signature Database” below, with exactly one entry.

The platform vendor may provide a default PKpub in the PKDefault variable described in *Globally Defined Variables*. This variable is formatted identically to the Platform Key variable. If present, this key may optionally be used as the public half of the Platform Key when transitioning from setup mode to user mode. If so, it may be read, placed within an `EFI_VARIABLE_AUTHENTICATION2` structure and copied to the Platform Key variable using the `SetVariable()` call.

### 32.3.2 Clearing The Platform Key

The platform owner clears the public half of the Platform Key (PKpub) by deleting the Platform Key variable using UEFI Runtime Service `SetVariable()`. The data buffer submitted to the `SetVariable()` must be signed with the current PKpriv; *Exception for Machine Check, INIT, and NMI* for details. The name and GUID of the Platform Key variable are specified in *Globally Defined Variables*, “Globally Defined Variables” The platform key may also be cleared using a secure platform-specific method. When platform key is cleared, the global variable SetupMode must also be updated to 1.

### 32.3.3 Transitioning to Audit Mode

To enter Audit Mode, a new UEFI variable AuditMode is set to 1. Entering Audit Mode has the side effect of changing SetupMode == 1, PK is cleared, and the new DeployedMode == 0.

**NOTE:** The AuditMode variable is only writable before ExitBootServices() is called when the system is not in Deployed Mode. See *Secure Boot Modes* for more details.
Fig. 32.4: Secure Boot Modes
32.3.4 Transitioning to Deployed Mode

To enter Deployed Mode from Audit Mode, set the variable PK. To enter Deployed Mode from User Mode, set the variable DeployedMode to 1. This transition takes effect immediately with no reset required. Entering Deployed Mode has the side effect of changing SetupMode == 0, AuditMode == 0 and is made read-only, and DeployedMode == 1 and is made read-only. See Secure Boot Modes for more details.

32.3.5 Enrolling Key Exchange Keys

Key exchange keys are stored in a signature database as described in “Signature Database” below. The signature database is stored as an authenticated UEFI variable.

The platform owner enrolls the key exchange keys by either calling SetVariable() as specified in Using the EFI_VARIABLE_AUTHENTICATION_3 descriptor with the EFI_VARIABLE_APPEND_WRITE attribute set and the Data parameter containing the new key(s), or by reading the database using GetVariable(), appending the new key exchange key to the existing keys and then writing the database using SetVariable() as specified in Using the EFI_VARIABLE_AUTHENTICATION_3 descriptor without the EFI_VARIABLE_APPEND_WRITE attribute set.

The authenticated UEFI variable that stores the key exchange keys (KEKs) can always be read but only be written if:

- The platform is in user mode and the provided variable data is signed with the current PK
- The platform is in setup mode (in this case the variable can be written without a signature validation, but the SetVariable() call needs to be formatted in accordance with the procedure for authenticated variables in Using the EFI_VARIABLE_AUTHENTICATION_3 descriptor)

The name and GUID of the Key Exchange Key variable are specified in Globally Defined Variables, “Globally Defined Variables.” The platform vendor may provide a default set of Key Exchange Keys in the KEKDefault variable described in Globally Defined Variables. If present, these keys (or a subset) may optionally be used when performing the initial enrollment of Key Exchange Keys. If any are to be used, they may be parsed from the variable and enrolled as described above.

32.3.6 Platform Firmware Key Storage Requirements

This section describes the platform firmware storage requirements of the different types of keys.

**Platform Keys:**

The public key must be stored in non-volatile storage which is tamper and delete resistant.

**Key Exchange Keys:**

The public key must be stored in non-volatile storage which is tamper resistant. Careful consideration should be given to the security and configuration of any out-of-band management agent (e.g. hypervisor or service processor) such that the platform cannot exploit the management agent in order to circumvent Secure Boot.

32.4 Firmware/OS Key Exchange: Passing Public Keys

This section describes a means of passing public keys from the OS to the platform firmware so that these keys can be used to securely pass information between the OS and the platform firmware. Typically, the OS has been unable to communicate sensitive information or enforce any sort of policy because of the possibility of spoofing by a malicious software agent. That is, the platform firmware has been unable to trust the OS. By enrolling these public keys, authorized by the platform owner, the platform firmware can now check the signature of data passed by the operating system. Of course if the malicious software agent is running as part of the OS, such as a rootkit, then any communication between the firmware and operating system still remains the subject of spoofing as the malicious code has access to the key exchange key.
32.4.1 Signature Database

32.4.1.1 EFI_SIGNATURE_DATA

Summary

The format of a signature database.

Prototype

```c
#pragma pack(1)
typedef struct _EFI_SIGNATURE_DATA {
  EFI_GUID   SignatureOwner;
  UINT8     SignatureData [_];
} EFI_SIGNATURE_DATA;

typedef struct _EFI_SIGNATURE_LIST {
  EFI_GUID   SignatureType;
  UINT32     SignatureListSize;
  UINT32     SignatureHeaderSize;
  UINT32     SignatureSize;
//  UINT8     SignatureHeader [SignatureHeaderSize];
//  EFI_SIGNATURE_DATA Signatures [__][SignatureSize];
} EFI_SIGNATURE_LIST;
#pragma pack()
```

Members

- **SignatureListSize**
  - Total size of the signature list, including this header.

- **SignatureType**
  - Type of the signature. GUID signature types are defined in “Related Definitions” below.

- **SignatureHeaderSize**
  - Size of the signature header which precedes the array of signatures.

- **SignatureSize**
  - Size of each signature. Must be at least the size of `EFI_SIGNATURE_DATA`.

- **SignatureHeader**
  - Header before the array of signatures. The format of this header is specified by the `SignatureType`.

- **Signatures**
  - An array of signatures. Each signature is `SignatureSize` bytes in length. The format of the signature is defined by the `SignatureType`.

- **SignatureOwner**
  - An identifier which identifies the agent which added the signature to the list.

Description

The signature database consists of zero or more signature lists. The size of the signature database can be determined by examining the size of the UEFI variable.

Each signature list is a list of signatures of one type, identified by `SignatureType`. The signature list contains a header and then an array of zero or more signatures in the format specified by the header. The size of each signature in the signature list is specified by `SignatureSize`. 
Each signature has an owner `SignatureOwner`, which is a GUID identifying the agent which inserted the signature in the database. Agents might include the operating system or an OEM-supplied driver or application. Agents may examine this field to understand whether they should manage the signature or not.

### Fig. 32.5: Signature Lists

#### Related Definitions

```c
#define EFI_CERT_SHA256_GUID
{ 0xc1c41626, 0x504c, 0x4092,
  { 0xac, 0xa9, 0x41, 0xf9, 0x36, 0x93, 0x43, 0x28 } };
```

This identifies a signature containing a SHA-256 hash. The `SignatureHeader` size shall always be 0. The `SignatureSize` shall always be 16 (size of `SignatureOwner` component) + 32 bytes.

```c
#define EFI_CERT_RSA2048_GUID
{ 0x3c5766e8, 0x269c, 0x4e34,
  { 0xaa, 0x14, 0xed, 0x77, 0x6e, 0x85, 0xb3, 0xb6 } };
```

This identifies a signature containing an RSA-2048 key. The key (only the modulus since the public key exponent is known to be 0x10001) shall be stored in big-endian order.

The `SignatureHeader` size shall always be 0. The `SignatureSize` shall always be 16 (size of `SignatureOwner` component) + 256 bytes.

```c
#define EFI_CERT_RSA2048_SHA256_GUID
{ 0xe2b36190, 0x879b, 0x4a3d,
  { 0xad, 0xa9, 0x8d, 0xf2, 0xe7, 0xbb, 0xa3, 0x27, 0x84 } };
```

This identifies a signature containing a RSA-2048 signature of a SHA-256 hash. The `SignatureHeader` size shall always be 0. The `SignatureSize` shall always be 16 (size of `SignatureOwner` component) + 256 bytes.
#define EFI_CERT_SHA1_GUID \
{ 0x826ca512, 0xcf10, 0xac9, \
    0xb1, 0x87, 0xbe, 0x01, 0x49, 0x66, 0x31, 0xb3d };

This identifies a signature containing a SHA-1 hash. The SignatureSize shall always be 16 (size of SignatureOwner component) + 20 bytes.

#define EFI_CERT_RSA2048_SHA1_GUID \
{ 0x67f8444f, 0x8743, 0x48f1, \
    0xa3, 0x28, 0x1e, 0xaa, 0xb8, 0x73, 0x60, 0x80 };

This identifies a signature containing a RSA-2048 signature of a SHA-1 hash. The SignatureHeader size shall always be 0. The SignatureSize shall always be 16 (size of SignatureOwner component) + 256 bytes.

#define EFI_CERT_X509_GUID \
{ 0xa5c059a1, 0x94e4, 0xaa7, \
    0x87, 0xb5, 0xab, 0x15, 0x5c, 0x2b, 0xf0, 0x72 };

This identifies a signature based on a DER-encoded X.509 certificate. If the signature is an X.509 certificate then verification of the signature of an image should validate the public key certificate in the image using certificate path verification, up to this X.509 certificate as a trusted root. The SignatureHeader size shall always be 0. The SignatureSize may vary but shall always be 16 (size of the SignatureOwner component) + the size of the certificate itself.

NOTE: This means that each certificate will normally be in a separate EFI_SIGNATURE_LIST.

#define EFI_CERT_SHA224_GUID \
{ 0xb6e5233, 0xa65c, 0x44c9, \
    0x94, 0x07, 0xd9, 0xab, 0x83, 0xbf, 0xc8, 0xbd };

This identifies a signature containing a SHA-224 hash. The SignatureHeader size shall always be 0. The SignatureSize shall always be 16 (size of SignatureOwner component) + 28 bytes.

#define EFI_CERT_SHA384_GUID \
{ 0xff3e5307, 0x9fd0, 0x48c9, \
    0x85, 0xf1, 0xa, 0x1c5, 0x70, 0x1e, 0x01 }; 

This identifies a signature containing a SHA-384 hash. The SignatureHeader size shall always be 0. The SignatureSize shall always be 16 (size of SignatureOwner component) + 48 bytes.

#define EFI_CERT_SHA512_GUID \
{ 0x93e0fae, 0xa6c4, 0x4f50, \
    0x9f, 0x1b, 0xd4, 0x1e, 0x2b, 0x89, 0xc1, 0x9a };

This identifies a signature containing a SHA-512 hash. The SignatureHeader size shall always be 0. The SignatureSize shall always be 16 (size of SignatureOwner component) + 64 bytes.

#define EFI_CERT_X509_SHA256_GUID \
{ 0x3bd2a492, 0x96c0, 0x4079, \
    0x84, 0x20, 0xfc, 0xf, 0x8e, 0xf1, 0x03, 0xed };

This identifies a signature containing a SHA-256 hash. The SignatureHeader size shall always be 0. The SignatureSize shall always be 16 (size of SignatureOwner component) + 64 bytes.

Prototype

#pragma pack(1)
typedef struct _EFI_CERT_X509_SHA256 {
(continues on next page)
Members

**ToBeSignedHash**

The SHA256 hash of an X.509 certificate’s To-Be-Signed contents.

**TimeOfRevocation**

The time that the certificate shall be considered to be revoked.

This identifies a signature containing the SHA256 hash of an X.509 certificate’s To-Be-Signed contents, and a time of revocation. The SignatureHeader size shall always be 0. The SignatureSize shall always be 16 (size of the SignatureOwner component) + 48 bytes for an EFI_CERT_X509_SHA256 structure. If the TimeOfRevocation is non-zero, the certificate should be considered to be revoked from that time and onwards, and otherwise the certificate shall be considered to always be revoked.

## EFI_CERT_X509_SHA384

typedef struct _EFI_CERT_X509_SHA384 {
  EFI_SHA384_HASH ToBeSignedHash;
  EFI_TIME TimeOfRevocation;
} EFI_CERT_X509_SHA384;

Members

**ToBeSignedHash**

The SHA384 hash of an X.509 certificate’s To-Be-Signed contents.

**TimeOfRevocation**

The time that the certificate shall be considered to be revoked.

This identifies a signature containing the SHA384 hash of an X.509 certificate’s To-Be-Signed contents, and a time of revocation. The SignatureHeader size shall always be 0. The SignatureSize shall always be 16 (size of the SignatureOwner component) + 64 bytes for an EFI_CERT_X509_SHA384 structure. If the TimeOfRevocation is non-zero, the certificate should be considered to be revoked from that time and onwards, and otherwise the certificate shall be considered to always be revoked.

## EFI_CERT_X509_SHA512

typedef struct _EFI_CERT_X509_SHA512 {
  EFI_SHA512_HASH ToBeSignedHash;
  EFI_TIME TimeOfRevocation;
} EFI_CERT_X509_SHA512;

Prototype

```
#define EFI_CERT_X509_SHA384_GUID \
{ 0x7076876e, 0x80c2, 0x4ee6, \ 
  { 0xaa, 0xd2, 0x28, 0xb3, 0x49, 0xa6, 0x86, 0x5b } }; 
```

```
#define EFI_CERT_X509_SHA512_GUID \
{ 0x446dbf63, 0x2502, 0x4cda, \ 
  { 0xbc, 0xfa, 0x24, 0x65, 0xd2, 0xb0, 0xfe, 0x9d } }; 
```

32.4. Firmware/OS Key Exchange: Passing Public Keys
Members

**ToBeSignedHash**

The SHA512 hash of an X.509 certificate’s To-Be-Signed contents.

**TimeOfRevocation**

The time that the certificate shall be considered to be revoked.

This identifies a signature containing the SHA512 hash of an X.509 certificate’s To-Be-Signed contents, and a time of revocation. The `SignatureHeader` size shall always be 0. The `SignatureSize` shall always be 16 (size of the `SignatureOwner` component) + 80 bytes for an `EFI_CERT_X509_SHA512` structure. If the `TimeOfRevocation` is non-zero, the certificate should be considered to be revoked from that time and onwards, and otherwise the certificate shall be considered to always be revoked.

```c
#define EFI_CERT_EXTERNAL_MANAGEMENT_GUID
  \{ 0x452e8ced, 0xdfff, 0x4b8c, \{ 0xae, 0x01, 0x51, 0x18, 0x86, 0x2e, 0x68, 0x2c \};
```

This `SignatureType` describes a pseudo-signature which will not facilitate authentication. It is only meaningful within a signature list used for authenticating writes through `SetVariable()`, and is only effective if it is the only signature present in that signature list. It allows a signature list to be populated without providing any means for `SetVariable()` to succeed. This signature type is intended for use on a platform with an external out-of-band management agent (e.g. hypervisor or service processor). When a platform is configured such that only signatures of this `SignatureType` are available for authenticating writes to a variable, that variable may only be modified by the external management agent using a platform-specific interface.

When a write may be authenticated using any signature from multiple signature lists, the presence of this signature in one of those signature lists does not inhibit the use of signatures present in the other signature lists. For example, if this signature is placed in PK, an attempt to write to db using `SetVariable()` will still succeed if it is signed by a valid KEKpriv, but a write to PK or KEK through `SetVariable()` cannot succeed because no PKpriv exists.

The `SignatureHeader` size shall always be 0. The `SignatureSize` shall always be 16 (size of `SignatureOwner` component) + 1 byte. The one byte of `SignatureData` exists only for compatibility reasons; It should be written as zero, and any value read should be ignored.

### 32.4.2 Image Execution Information Table

**Summary**

When `AuditMode==0`, if the image’s signature is not found in the authorized database, or is found in the forbidden database, the image will not be started and instead, information about it will be placed in the `EFI_IMAGE_EXECUTION_INFO_TABLE` (see section 32.5.3.1). {cross-reference needed}

When `AuditMode==1`, an `EFI_IMAGE_EXECUTION_INFO` element is created in the `EFI_IMAGE_EXECUTION_INFO_TABLE` for every certificate found in the certificate table of every image that is validated.

Additionally for every image, an element will be created in the table for every `EFI_CERT_SHA` that is supported by the platform. The contents of* Action for each element are determined by comparing that specific element’s Signature (which will contain exactly 1 EFI_SIGNATURE_DATA) to the currently-configured image security databases and policies, and shall be either *EFI_IMAGE_EXECUTION_AUTH_SIG_PASSED*, *EFI_IMAGE_EXECUTION_AUTH_SIG_FAILED*, *EFI_IMAGEEXECUTION_AUTH_SIG_NOT_FOUND*, *EFI_IMAGE_EXECUTION_AUTH_SIG_FOUND*, or *EFI_IMAGE_EXECUTION_POLICY_FAILED*. 

---

**32.4. Firmware/OS Key Exchange: Passing Public Keys**

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Finally, because the system is in Audit Mode, all modules are initialized even if they fail to authenticate, and the `EFI_IMAGE_EXECUTION_INITIALIZED` bit shall be set in `Action` for all elements.

Prototype

```c
typedef struct {
    EFI_IMAGE_EXECUTION_ACTION Action;
    UINT32 InfoSize;
    // CHAR16 Name [__];
    // EFI_DEVICE_PATH_PROTOCOL DevicePath;
    // EFI_SIGNATURE_LIST Signature;
} EFI_IMAGE_EXECUTION_INFO;
```

Parameters

Action

Describes the action taken by the firmware regarding this image. Type `EFI_IMAGE_EXECUTION_ACTION` is described in “Related Definitions” below.

InfoSize

Size of all of the entire structure.

Name

If this image was a UEFI device driver (for option ROM, for example) this is the null-terminated, user-friendly name for the device. If the image was for an application, then this is the name of the application. If this cannot be determined, then a simple NULL character should be put in this position.

DevicePath

Image device path. The image device path typically comes from the Loaded Image Device Path Protocol installed on the image handle. If image device path cannot be determined, a simple end-of-path device node should be put in this position.

Signature

Zero or more image signatures. If the image contained no signatures, then this field is empty. The type `WIN_CERTIFICATE` is defined in chapter 26.

Prototype

```c
typedef struct {
    UINTN NumberOfImages;
    EFI_IMAGE_EXECUTION_INFO InformationInfo[__]
} EFI_IMAGE_EXECUTION_INFO_TABLE;
```

NumberOfImages

Number of `EFI_IMAGE_EXECUTION_INFO` structures.

InformationInfo

`NumberOfImages` instances of `EFI_IMAGE_EXECUTION_INFO` structures.

Related Definitions

```c
typedef UINT32 EFI_IMAGE_EXECUTION_ACTION;

#define EFI_IMAGE_EXECUTION_AUTHENTICATION 0x00000007
#define EFI_IMAGE_EXECUTION_AUTH_UNTESTED 0x00000000
#define EFI_IMAGE_EXECUTION_AUTH_SIG_FAILED 0x00000001
#define EFI_IMAGE_EXECUTION_AUTH_SIG_PASSED 0x00000002
#define EFI_IMAGE_EXECUTION_AUTH_SIG_NOT_FOUND 0x00000003
```

(continues on next page)
#define EFI_IMAGE_EXECUTION_AUTH_SIG_FOUND 0x00000004
#define EFI_IMAGE_EXECUTION_POLICY_FAILED 0x00000005
#define EFI_IMAGE_EXECUTION_INITIALIZED 0x00000008

**Description**

This structure describes an image in the EFI System Configuration Table. It is only required in the case where image signatures are being checked and the image was not initialized because its signature failed, when AuditMode==1, or was not found in the signature database and an authorized user or the owner would not authorize its execution. It may be used in other cases as well.

In these cases, the information about the image is copied into the EFI System Configuration Table. Information about other images which were successfully initialized may also be included as well, but this is not required.

The *Action* field describes what action the firmware took with regard to the image and what other information it has about the image, including the device which it is related to.

First, this field describes the results of the firmware’s attempt to authenticate the image.

<table>
<thead>
<tr>
<th>Authentication attempt status</th>
<th>Condition met</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_IMAGE_EXECUTION_AUTH_UNTESTED</td>
<td>The image contained no certificates</td>
</tr>
<tr>
<td>EFI_IMAGE_EXECUTION_AUTH_SIG_FAILED</td>
<td>The image has at least one certificate, and either:</td>
</tr>
<tr>
<td></td>
<td>• An image certificate is in the forbidden database, or</td>
</tr>
<tr>
<td></td>
<td>• A digest of an image certificate is in the forbidden database, or</td>
</tr>
<tr>
<td></td>
<td>• The image signature check failed.</td>
</tr>
<tr>
<td>EFI_IMAGE_EXECUTION_AUTH_SIG_PASSED</td>
<td>The image has at least one certificate, and either:</td>
</tr>
<tr>
<td></td>
<td>• An image certificate is in authorized database.</td>
</tr>
<tr>
<td></td>
<td>• The image digest is in the authorized database.</td>
</tr>
<tr>
<td>EFI_IMAGE_EXECUTION_AUTH_SIG_NOT_FOUND</td>
<td>The image has at least one certificate, and:</td>
</tr>
<tr>
<td></td>
<td>• the image certificate is not found in the authorized database, and</td>
</tr>
<tr>
<td></td>
<td>• the image digest is not in the authorized database.</td>
</tr>
<tr>
<td>EFI_IMAGE_EXECUTION_AUTH_SIG_FOUND</td>
<td>The image has at least one certificate, and the image digest is in the forbidden database.</td>
</tr>
<tr>
<td>EFI_IMAGE_EXECUTION_POLICY_FAILED</td>
<td>Authentication failed because of (unspecified) firmware security policy.</td>
</tr>
</tbody>
</table>

Second, this field describes whether the image was initialized or not.

This table can be used by an agent which executes later to audit which images were not loaded and perhaps query other sources to discover whether the image should be authorized. If so, the agent can use the method described in “Signature
Database Update” to update the Signature Database with the image’s signature. Switching the system into Audit Mode generates a more verbose table which provides additional insights to this agent.

If an attempt to boot a legacy non-UEFI OS takes place when the system is in User Mode, the OS load shall fail and a corresponding \textit{EFI_IMAGE_EXECUTION_INFO} entry shall be created with Action set to \textit{EFI_IMAGE_EXECUTION_AUTH_UNTESTED}, Name set to the NULL-terminated “Description String” from the BIOS Boot Specification Device Path and DevicePath set to the BIOS Boot Specification Device Path (\textit{BIOS Boot Specification Device Path}).

### 32.5 UEFI Image Validation

#### 32.5.1 Overview

This section describes a way to use the platform ownership model described in the previous section and the key exchange mechanism to allow the firmware to authenticate a UEFI image, such as an OS loader or an option ROM, using the digital signing mechanisms described here.

The hand-off between the platform firmware and the operating system is a critical part of ensuring secure boot. Since there are large numbers of operating systems and a large number of minor variations in the loaders for those operating systems, it is difficult to carry all possible keys or signatures within the firmware as it ships. This requires some sort of update mechanism, to identify the proper loader. But, as with any update mechanism, there is the risk of allowing malicious software to “authenticate” itself, posing as the real operating system.

Likewise, there are a large number of potential 3rd-party UEFI applications, drivers and option ROMs and it is difficult to carry all possible keys or signatures within the firmware as it ships.

The mechanism described here requires that the platform firmware maintain a signature database, with entries for each authorized UEFI image (the authorized UEFI signature database). The signature database is a single UEFI Variable.

It also requires that the platform firmware maintain a signature database with entries for each forbidden UEFI image. This signature database is also a single UEFI variable.

The signature database is checked when the UEFI Boot Manager is about to start a UEFI image. If the UEFI image’s signature is not found in the authorized database, or is found in the forbidden database, the UEFI image will be deferred and information placed in the Image Execution Information Table. In the case of OS Loaders, the next boot option will be selected. The signature databases may be updated by the firmware, by a pre-OS application or by an OS application or driver.

If a firmware supports the \textit{EFI_CERT_X509_SHA*_GUID} signature types, it should support the RFC3161 timestamp specification. Images whose signature matches one of these types in the forbidden signature database shall only be considered forbidden if the firmware either does not support timestamp verification, or the signature type has a time of revocation equal to zero, or the timestamp does not pass verification against the authorized timestamp and forbidden signature databases, or finally the signature type’s time of revocation is less than or equal to the time recorded in the image signature’s timestamp. If the timestamp’s signature is authorized by the authorized timestamp database and the time recorded in the timestamp is less than the time of revocation, the image shall not be considered forbidden provided it is not forbidden by any other entry in the forbidden signature database. Finally, this requires that firmware supporting timestamp verification must support the authorized timestamp database and have a suitable time stamping authority certificate in that database.
32.5.2 Authorized User

An authorized user (for the purposes of UEFI image security) is one who possesses a key exchange key (KEKpriv). This key is used to sign updates to the signature databases.

32.5.3 Signature Database Update

The Authorized, Forbidden, Timestamp, and Recovery signature databases are stored as UEFI authenticated variables (see Variable Services in Exception for Machine Check, INIT, and NMI) with the GUID

EFI_IMAGE_SECURITY_DATABASE_GUID and the names

EFI_IMAGE_SECURITY_DATABASE,
EFI_IMAGE_SECURITY_DATABASE1,
EFI_IMAGE_SECURITY_DATABASE2, and
EFI_IMAGE_SECURITY_DATABASE3, respectively.

These authenticated UEFI variables that store the signature databases (db, dbx, dbr, or dbt) can always be read but can only be written if:

- The platform is in user mode and the provided variable data is signed with the private half of a previously enrolled key exchange key (KEKpriv *), or the platform private key (PKpriv);
  or if
- The platform is in setup mode (in this case the variables can be written without a signature validation, but the SetVariable() call needs to be formatted in accordance with the procedure for authenticated variables in Using the EFI_VARIABLE_AUTHENTICATION_3 descriptor)

The signature databases are in the form of Signature Databases, as described in “Signature Database” above.

The platform vendor may provide a default set of entries for the Signature Database in the dbDefault, dbxDefault, dbtDefault, and dbrDefault variables described in Globally Defined Variables. If present, these keys (or a subset) may optionally be used when performing the initial enrollment of signature database entries. If any are to be used, they may be parsed from the variable and enrolled as described below.

If, when adding a signature to the signature database, SetVariable() returns EFI_OUT_OF_RESOURCES, indicating there is no more room, the updater may discard the new signature or it may decide to discard one of the database entries. These authenticated UEFI variables that store the signature databases (db, or dbx, dbt, or dbr) can always be read but can only be written if:

The following diagram illustrates the process for adding a new signature by the OS or an application that has access to a previously enrolled key exchange key using SetVariable(). In the diagram, the EFI_VARIABLE_APPEND_WRITE attribute is not used. If EFI_VARIABLE_APPEND_WRITE had been used, then steps 2 and 3 could have been omitted and step 7 would have included setting the EFI_VARIABLE_APPEND_WRITE attribute.

1. The procedure begins by generating a new signature, in the format described by the Signature Database.
2. Call GetVariable() using EFI_IMAGE_SECURITY_DATABASE_GUID for the*VendorGuid* parameter and EFI_IMAGE_SECURITY_DATABASE for the VariableName parameter.
3. If the variable exists, go to step 5.
4. Create an empty authorized signature database.
5. Create a new buffer which contains the authorized signature database, along with the new signature appended to the end.
6. Sign the new signature database using the private half of the Key Exchange Key as described in `SetVariable()`.  
7. Update the authorized signature database using the UEFI Runtime Service `SetVariable()`.  
8. If there was no error, go to step 11.  
9. If there was an error because of no more resources, determine whether the database can be shrunk any more. The algorithm by which an agent decides which signatures may be safely removed is agent-specific. In most cases, agents should not remove signatures where the SignatureOwner field is not the agent’s. If not, then go to step 11, discarding the new signature.  
10. If the signature database could be shrunk further, then remove the entries and go to step 6.  
11. Exit.

32.5.3.1 Using The Image Execution Information Table

During the process of loading UEFI images, the firmware must gather information about which UEFI images were not started. The firmware may additionally gather information about UEFI images which were started. The information is used to create the "EFI_IMAGE_EXECUTION_INFO_TABLE", which is added to the EFI System Configuration Table and assigned the GUID `EFI_IMAGE_SECURITY_DATABASE_GUID`.  

For each UEFI image, the following information is collected:  
- The image hash.  
- The user-friendly name of the UEFI image (if known)  
- The device path  
- The action taken on the device (was it initialized or why was it rejected).

For more information, see the Image Execution Information Table definition above (Image Execution Information Table).

32.5.3.2 Firmware Policy

The firmware may approve UEFI images for other reasons than those specified here. For example: whether the image is in the system flash, whether the device providing the UEFI image is secured (in a case, etc.) or whether the image contains another type of platform-supported digital signature.

32.5.3.3 Authorization Process

This section describes the process by which an unknown UEFI image might be authorized to run. Implementations are not required to support all portions of this. For example, an implementation might defer all UEFI image or none.  
1. Reset. This is when the platform begins initialization during boot.  
2. Key Store Initialization. During the firmware initialization and before any signed UEFI images are initialized, the platform firmware must validate the signature database.  
3. UEFI Image Validation Succeeded? During initialization of an UEFI image, the UEFI Boot Manager decides whether or not the UEFI image should be initialized. By comparing the calculated UEFI image signature against that in one of the signature databases, the firmware can determine if there is a match.  

The security database \( db \) must either contain an entry with a hash value of the image (with a supported hash type), or it must contain an entry with a certificate against which an entry in the image’s certificate table can be verified. In either case verification must not succeed if the security database \( dbx \) contains any record with:
Fig. 32.6: Process for Adding a New Signature by the OS

32.5. UEFI Image Validation
**Fig. 32.7: Authorization Process Flow**

1. **Reset**
2. **Store Initializer**
3. **UEFI Application Validated?**
   - Yes: **UEFI Application Signature Added to Database**
   - No: Deferral
4. **Start UEFI Application**
5. **UEFI Application Approved?**
   - Yes: **UEFI Application Hash Passed in System Configuration Table**
   - No: **Go to Next Boot Option**
6. **OS App Validates UEFI Application**
   - Yes: **UEFI App Signature Updated**
   - No: **No**
7. **End**
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

– A. Any entry with SignatureListType of EFI_CERT_SHA256_GUID with any SignatureData containing the SHA-256 hash of the binary.

– B. Any entry with SignatureListType of EFI_CERT_X509_SHA256, EFI_CERT_X509_SHA384, or EFI_CERT_X509_SHA512, with any SignatureData which reflects the To-Be-Signed hash included in any certificate in the signing chain of the signature being verified.

– C. Any entry with SignatureListType of EFI_CERT_X509_GUID, with SignatureData which contains a certificate with the same Issuer, Serial Number, and To-Be-Signed hash included in any certificate in the signing chain of the signature being verified.

Multiple signatures are allowed to exist in the binary’s certificate table (as per PE/COFF Section “Attribute Certificate Table”). Only one hash or signature is required to be present in db in order to pass validation, so long as neither the SHA-256 hash of the binary nor any present signature is reflected in dbx.

Then, based on this match or its own policy, the firmware can decide whether or not to launch the UEFI image.

4. Start UEFI Image. If the UEFI Image is approved, then it is launched normally.

5. UEFI Image Not Approved. If the UEFI image was not approved the platform firmware may use other methods to discover if the UEFI image is authorized, such as consult a disk-based catalog or ask an authorized user. The result can be one of three responses: Yes, No or Defer.

6. UEFI Image Signature Added To Signature Database. If the user approves of the UEFI image, then the UEFI image’s signature is saved in the firmware’s signature database. If user approval is supported, then the firmware be able to update of the Signature Database. For more information, see Signature Database Update.

7. Go To Next Boot Option. If an UEFI image is rejected, then the next boot option is selected normally and go to step 3. This is in the case where the image is listed as a boot option.

8. UEFI Image Signature Passed In System Configuration Table. If user defers, then the UEFI image signature is copied into the Image Execution Information Table in the EFI System Configuration Table which is available to the operating system.

9. OS Application Validates UEFI Image. An OS application determines whether the image is valid.

10. UEFI Image Signature Added To Signature Database. For more information, see Signature Database Update.

11. End.

32.6 Code Definitions

32.6.1 UEFI Image Variable GUID & Variable Name

Summary

Constants used for UEFI signature database variable access.

Prototype

```c
#define EFI_IMAGE_SECURITY_DATABASE_GUID \ 
{ 0xd719b2cb, 0x3d3a, 0x4596, \ 
{ 0xa3, 0xbc, 0xda, 0xd0, 0x0e, 0x67, 0x6f }}
#define EFI_IMAGE_SECURITY_DATABASE L"db"
#define EFI_IMAGE_SECURITY_DATABASE1 L"dbx"
#define EFI_IMAGE_SECURITY_DATABASE2 L"dbt"
#define EFI_IMAGE_SECURITY_DATABASE3 L"dbr"
```

Description
• This GUID and name are used when calling the EFI Runtime Services `GetVariable()` and `SetVariable()`.

• The `EFI_IMAGE_SECURITY_DATABASE_GUID` and `EFI_IMAGE_SECURITY_DATABASE` are used to retrieve and change the authorized signature database.

• The `EFI_IMAGE_SECURITY_DATABASE_GUID` and `EFI_IMAGE_SECURITY_DATABASE1` are used to retrieve and change the forbidden signature database.

• The `EFI_IMAGE_SECURITY_DATABASE_GUID` and `EFI_IMAGE_SECURITY_DATABASE2` are used to retrieve and change the authorized timestamp signature database.

• The `EFI_IMAGE_SECURITY_DATABASE_GUID` and `EFI_IMAGE_SECURITY_DATABASE3` are used to retrieve and change the authorized recovery signature database.

• Firmware shall support the `EFI_VARIABLE_APPEND_WRITE` flag (except for Machine Check, INIT, and NMI) for the UEFI signature database variables.

• The signature database variables db, dbt, dbx, and dbr must be stored in tamper-resistant non-volatile storage.
CHAPTER
THIRTYTHREE

HUMAN INTERFACE INFRASTRUCTURE OVERVIEW

This section defines the core code and services that are required for an implementation of the Human Interface Infrastructure (HII). This specification does the following:

- Describes the basic mechanisms to manage user input
- Provides code definitions for the HII-related protocols, functions, and type definitions that are architecturally required by the UEFI Specification

33.1 Goals

This chapter describes the mechanisms by which UEFI-compliant systems manage user input. The major areas described include the following:

- String and font management.
- User input abstractions (for keyboards and mice)
- Internal representations of the forms (in the HTML sense) that are used for running a preboot setup.
- External representations (and derivations) of the forms that are used to pass configuration information to runtime applications, and the mechanisms to allow the results of those applications to be driven back into the firmware. General goals include:
  - Simplified localization, the process by which the interface is adapted to a particular language.
  - A “forms” representation mechanism that is rich enough to support the complex configuration issues encountered by platform developers, including stock keeping unit (SKU) management and interrelationships between questions in the forms.
  - Definition of a mechanism to allow most or all the configuration of the system to be performed during boot, at runtime, and remotely. Where possible, the forms describing the configuration should be expressed using existing standards such as XML.
  - Ability for the different drivers (including those from add-in cards) and applications to contribute forms, strings, and fonts in a uniform manner while still allowing innovation in the look and feel for Setup.

Support user-interface on a wide range of display devices:

- Local text display
- Local graphics display
- Remote text display
- Remote graphics display
- Web browser
• OS-present GUI
Support automated configuration without a display.

33.2 Design Discussion

This section describes the basic concepts behind the Human Interface Infrastructure. This is a set of protocols that allow a UEFI driver to provide the ability to register user interface and configuration content with the platform firmware. Unlike legacy option ROMs, the configuration of drivers and controllers is delayed until a platform management utility chooses to use the services of these protocols. UEFI drivers are not allowed to perform setup-like operations outside the context of these protocols. This means that a driver is not allowed to interact with the user outside the context of this protocol.

The following example shows a basic platform configuration or “setup” model. The drivers and applications install elements (such as fonts, strings, images and forms) into the HII Database, which acts as a central repository for the entire platform. The Forms Browser uses these elements to render the user interface on the display devices and receive information from the user via HID devices. When complete, the changes made by the user in the Forms Browser are saved, either to the UEFI global variable storage—(GetVariable() and SetVariable())— or to variable storage provided by the individual drivers.

---

Fig. 33.1: Platform Configuration Overview
33.2.1 Drivers And Applications

The user interface elements in the form of package lists are carried by the drivers and applications. Drivers and applications can create the package lists dynamically, or they can be pre-built and carried as resources in the driver/application image.

If they are stored as resources, then an editor can be used to modify the user interface elements without recompiling. For example, display elements can be modified or deleted, new languages added, and default values modified.

![Diagram of HII Resources In Drivers & Applications]

The means by which the string, font, image and form resources are created is beyond the scope of this specification. The following diagram shows a few possible implementations. In both cases, the GUI design is an optional element and the user-interface elements are stored within a text-based resource file. Eventually, this source file is converted into a RES file (PE/COFF Resource Section) which can be linked with the main application.

33.2.1.1 Platform and Driver Configuration

The intent is for this specification to enable the configuration of various target components in the system. The normally arduous task of managing user interface and configuration can be greatly simplified for the consumers of such functionality by enabling the platform to comprehend some standard user interactions.

33.2.1.2 Pre-O/S applications

There are various scenarios where a platform component must interact in some fashion with the user. Examples of this are when presenting a user with several choices of information (e.g. boot menu) and sending information to the display (e.g. system status, logo, etc.).

33.2.1.3 Description of User Interface Components

Various components listed in this specification are described in greater detail in their own sections. The user interface is composed of several distinct components illustrated below.
Fig. 33.3: Creating UI Resources With Resource Files
Fig. 33.4: Creating UI Resources With Intermediate Source Representation
Fig. 33.5: The Platform and Standard User Interactions

Fig. 33.6: User and Platform Component Interaction
33.2.1.4 Forms

This component describes what type of content needs to be displayed to the user by means of a binary encoding (i.e., Internal Forms Representation) and also has added context information such as how to validate certain input and further describes where to store such input if it is intended to be non-volatile. Applications such as a browser or script engine may use the information with the forms to validate configuration setting values with or without a user interface.

33.2.1.5 Strings

The strings are the text-based (UCS-2 encoded) representations of the information typically being referenced by the forms. The intent of this infrastructure is also to seamlessly enable multiple language support. To that end the strings have the appropriate language designators to differentiate one language from another.

33.2.1.6 Images/Fonts

Since most content is typically intended to have the ability to be rendered on the local system, the human interface infrastructure also supports the ability for images and fonts to be accepted and used by the underlying user interface components.
33.2.1.7 Consumers of the user interface data

The ultimate consumer of the user interface information will be some type of forms browser or forms processor. There are several usage scenarios which should be supported by this specification. These are illustrated below:

33.2.1.8 Connected forms browser/processor

The ability to have the forms processing engine render content when directly connected to the target platform should be apparent. From the forms processing engine perspective, this could be the local machine or a machine that is network attached. In either case, there is a constructed agent which feeds the material to the forms processor for purposes of rendering the user interface and interacting with the user. Note that a forms processor could simply act on the forms data without ever having to render the user interface and interact with the user. This situation is much more akin to script processing and should be a very supportable situation.

Fig. 33.8: Connected Forms Browser/Processor

33.2.1.9 Disconnected Forms Browser/Processor

By enabling the ability to import and export a platform’s settings, this infrastructure can also enable the ability for offline configuration. In this instance, a forms processor can interpret a given platform’s form data and enable (either through user interaction or through automated scripting) the changing of configuration settings. These settings can then be applied to the target platform when a connection is established.

33.2.1.10 O/S-Present Forms Browser/Processor

When it is desired that the forms data be used in the presence of an O/S, this specification describes a means by which to support this capability. By being able to encapsulate the data and export it through standard means such that an O/S agent (e.g. forms browser/processor) can retrieve it, O/S-present usage models can be made available for further value-add implementations.
Fig. 33.9: Disconnected Forms Browser/Processor

Fig. 33.10: O/S-Present Forms Browser/Processor
33.2.1.11 Where are the Results Stored

The forms data encodes how to store the changes per configuration question. The ability to save data to the platform as well as to a proprietary on-board store is provided. The premise is that each of the target non-volatile store components (e.g. motherboard, add-in device, etc.) would advertise an interface as described in this specification so that the forms browser/processor can route changes to the appropriate target.

Fig. 33.11: Platform Data Storage

33.2.2 Localization

Localization is the process by which the interface is adapted to a particular language. The table below discusses issues with localization and provides possible solutions.

<table>
<thead>
<tr>
<th>Issue</th>
<th>Example</th>
<th>Solution</th>
<th>Comment</th>
</tr>
</thead>
<tbody>
<tr>
<td>Directional display</td>
<td>Right to left printing for Hebrew.</td>
<td>Printing direction is a function of the language.</td>
<td>The display engine may or may not support all display techniques. If a language supports a display mechanism that the display engine does not, the language that uses the font must be selected.</td>
</tr>
<tr>
<td>Punctuation</td>
<td>Punctuation is directional. A comma in a right-to-left language is different from a comma in a left-to-right language.</td>
<td>Character choice is the choice of the author or translator.</td>
<td></td>
</tr>
</tbody>
</table>

continues on next page
### 33.2.3 User Input

To limit the number of required glyphs, we must also limit the amount and type of user input.

User input generally comes from the following main types of devices:

- Keyboards
- Mouse-like pointing devices

Input from other devices, such as limited keys on a front panel, can be handled two ways:

- Treat the limited keys as special-purpose devices with completely unique interfaces.
- Programmatically make the limited keys mimic a keyboard or mouse-like pointing device.

Pointing devices require no localization. They are universally understood by the subset of the world population addressed in this specification. For example, if a person does not know how to use a mouse or other pointing device, it is probably not a good idea to allow that person to change a system’s configuration.

On the other hand, keyboards are localized at the keycaps but not in the electronics. In other words, a French keyboard and a German keyboard might have very different keys but the software inside the keyboard—let alone the software in the system at the other end of the wire—cannot know which set of keycaps are installed.

This specification proposes to solve this issue by using the keys that are common between keyboards and ignoring language-specific keys. Keys that are available on USB keyboards in preboot mode include the following:

- Function keys (F1 - F12)
- Number keys (0-9)
- “Upside down T” cursor keys (the arrows, home, end, page up, page down)
• Numeric keypad keys
• The Enter, Space, Tab, and Esc keys
• Modifier keys (shifts, alts, controls, Windows*)
• Number lock

The scan codes for these keys do not vary from language to language. These keys are the standard keys used for browser navigation although most end-users are unaware of this fact. Help for form-entry-specific keys must be provided to enable a useful keys-only interface. The one case where other, language-specific keys may be used is to enter passwords. Because passwords are never displayed, there is no requirement to translate scan code to Unicode character codes (keyboard localization) or scan codes to font glyphs.

Additional data can be provided to enable a richer set of input characters. This input is necessary to support features such as arbitrary text input and passwords.

### 33.2.4 Keyboard Layout

#### 33.2.4.1 Keyboard Mapping

UEFI’s keyboard mapping loosely based definitions on ISO 9995. It bases the naming mechanism on the figure below. The keys highlighted in brown are the keys that nearly all keyboard layouts use for customizations. However, customization does not necessarily mean that all the keys are different. In fact, most of the keys are likely to be the same. When modifying the mapping, one can normally reference the keys in brown as the likely candidates (for whom to create modifications).

![Keyboard Layout](image)

Fig. 33.12: Keyboard Layout

Instead of referencing keys in hardware-specific ways such as scan codes, the HII specification defines an `EFI_KEY` enumeration that allows for a simple method of referencing this hardware abstraction. Type `EFI_KEY` is defined in `EFI_HII_DATABASE_PROTOCOL.GetKeyboardLayout()`. It also provides a way to update the keyboard layout with a great deal of flexibility. Any of the keys can be mapped to any 16-bit Unicode character code or control code value.

When defining the values for a particular key, there are six elements that are pertinent to the key:

- **Key name** — The `EFI_KEY` enumeration defines the names of the above keys.
- **Unicode Character Code** — Defines the Unicode Character Code (if any) of the named key.
- **Shifted Unicode Character Code** — Defines the Unicode Character Code (if any) of the named key while the shift modifier key is being pressed.
- **Alt-GR Unicode Character Code** — Defines the Unicode Character Code (if any) of the named key while the Alt-GR modifier key (if any) is being pressed.
- **Shifted Alt-GR Unicode Character Code** — Defines the Unicode Character Code (if any) of the named key while the Shift and Alt-GR modifier key (if any) is being pressed.
Modifier key value — Defines the nonprintable special function that this key has assigned to it.

- Under normal circumstances, a key that has any Unicode character code definitions generally has a modifier key value of EFI_NULL_MODIFIER. This value means the key has no special function other than the printing of a character. An exception to the rule is if any of the Unicode character codes have a value of 0xFFFF. Although rarely used, this value is the one case in which a key might have both a printable character and an active control key value.

An example of this exception would be the numeric keypad’s insert key. The definition for this key on a standard US keyboard is as follows:

```
Key = EfiKeyZero
Unicode = 0x0030 (basically a ‘0’)  
ShiftedUnicode = 0xFFFF (the exception to the rule)  
AltGrUnicode = 0x0000  
ShiftedAltGrUnicode = 0x0000  
Modifier = EFI_INSERT_MODIFIER
```

This key is one of the few keys that, under normal circumstances, prints something out but also has a special function. These special functions are generally limited to the numeric keypad; however, this general limitation does not prevent someone from having the flexibility of defining these types of variations.

### 33.2.4.2 Modifier Keys

The definitions of the modifier keys allow for special functionality that is not necessarily accomplished by a printable character. Many of these modifier keys are flags to toggle certain state bits on and off inside of a keyboard driver. An example is EFI_CAPS_LOCK_MODIFIER. This state being active could alter what the typing of a particular key produces. Other control keys, such as EFI_LEFT_ARROW_MODIFIER and EFI_END_MODIFIER, affect the position of the cursor. One modifier key is likely unfamiliar to most people who exclusively use US keyboards, and that key is the EFI_ALT_GR_MODIFIER key. This key’s primary purpose is to activate a secondary type of shift modifier that exposes additional printable characters on certain keys. In some keyboard layouts, this key does not exist and is normally the EFI_RIGHT_ALT_MODIFIER key. None of the other modifier key functions should be a mystery to someone familiar with the usage of a standard computer keyboard.

An example of a few descriptor entries would be as follows:

```
Layout = {
  EfiKeyLCtrl,0,0,0,0, *EFI_LEFT_CONTROL_MODIFIER,* //Left control  
      // key
  EfiKeyA0,0,0,0,0,EFI_NULL_MODIFIER, //Not defined  
      // windows key
  EfiKeySpaceBar,0x0020,0x0020,0x0020,0x0020,EFI_NULL_MODIFIER  
      // (Space Bar)
}
```

See “Related Definitions” in EFI_HII_DATABASE_PROTOCOL.GetKeyboardLayout() for the defined modifier values.
33.2.4.3 Non-Spacing Keys

Non-spacing keys are a concept that provides the ability to OR together an accent key and another printable character. Non-spacing keys are defined as special types of modifier characters. They are typically accent keys that do not advance the cursor and in essence are a type of modifier key in that they maintain some level of state.

The way a person uses a non-spacing key is that the non-spacing key that maybe has the function of overlaying an umlaut (two dots) onto whatever the next character might be. The user presses the umlaut non-spacing key and follows it with a capital A, which yields an “Ä.”

An example of a few descriptor entries would be as follows:

```c
//
// If it's a dead key, we need to pass a list of physical key
// names, each with a unicode, shifted, altgr, shiftedaltgr
// character code. Each key name will have a Modifier value of
// EFI_NS_KEY_MODIFIER for the first entry, and then the list of
// EFI_NS_KEY_DEPENDENCY_MODIFIER physical key descriptions.
// This eventually will lead to the next normal non-modifier key
// definition.
//
// This requires defining an additional Modifier value of
// EFI_NS_KEY_DEPENDENCY_MODIFIER to signify
// EFI_NS_KEY_MODIFIER children definitions.
//
// The keyboard driver (consumer of the layouts) will know that
// any key definitions with the EFI_NS_KEY_DEPENDENCY_MODIFIER
// modifier do not redefine the value of the specified EFI_KEY.
// They are simply used as a special case augmentation to the
// original EFI_NS_KEY_MODIFIER.
//
// It is an error condition to define a
// EFI_NS_KEY_MODIFIER without having all the
// EFI_NS_KEY_DEPENDENCY_MODIFIER keys defined serially.
//
// Layout = {
// EfiKeyE0, 0, 0, 0, 0, EFI_NS_KEY_MODIFIER,
// EfiKeyC1, 0x00E2, 0x00C2, 0, 0, EFI_NS_KEY_DEPENDENCY_MODIFIER,
// EfiKeyD3, 0x00EA, 0x00CA, 0, 0, EFI_NS_KEY_DEPENDENCY_MODIFIER,
// EfiKeyD8, 0x00EC, 0x00CC, 0, 0, EFI_NS_KEY_DEPENDENCY_MODIFIER,
// EfiKeyD9, 0x00F4, 0x00D4, 0, 0, EFI_NS_KEY_DEPENDENCY_MODIFIER,
// EfiKeyD7, 0x00FB, 0x00CB, 0, 0, EFI_NS_KEY_DEPENDENCY_MODIFIER
// }
```

In the above example, a key located at E0 is designated as a dead key. Using a common German keyboard layout as the example, a circumflex accent “^” is defined as a dead key at the E0 location. The A, E, I, O, and U characters are valid keys that can be pressed after the dead key and will produce a valid printable character. These characters are located at C1, D3, D8, D9, and D7 respectively.

The results of the Layout definition provided above would allow for the production of the following characters: âÄêÈïÎôÔûÛ.
33.2.5 Forms

This specification describes how a UEFI driver or application may present a forms (or dialogs) based interface. The forms-based interface assumes that each window or screen consists of some window dressing (title & buttons) and a list of questions. These questions represent individual configuration settings for the application or driver, although several GUI controls may be used for one question.

![Forms-based Interface Example](image)

The forms are stored in the HII database, along with the strings, fonts and images. The various attributes of the forms and questions are encoded in IFR (Internal Forms Representation)–with each object and attribute a byte stream.

Other applications (so-called “Forms Processors”) may use the information within the forms to validate configuration setting values without a user interface at all.

The Forms Browser provides a forms-based user interface which understands how to read the contents of the forms, interact with the user, and save the resulting values. The Forms Browser uses forms data installed by an application or driver during initialization in the HII database. The Forms Browser organizes the forms so that a user may navigate between the forms, select the individual questions and change the values using the HID and display devices. When the user has finished making modifications, the Forms Browser saves the values, either to the global EFI variable store or else to a private variable store provided by the driver or application.

33.2.5.1 Form Sets

Form sets are logically-related groups of forms.

Attributes

Each forms set has the following attributes:

**Form Set Identifier** – Uniquely identifies the form set within a package list using a GUID. The Form Set Identifier, along with a device path, uniquely identifies a form set in a system.

**Form Set Class Identifier** – Optional array of up to three GUIDs which identify how the form set should be used or classified. The list of standard form set classes is found in the “Related Definitions” section of `EFI_FORM_BROWSER2_PROTOCOL.SendForm()`.

**Title** – Title text for the form set.

**Help** – Help text for the form set.

**Image** – Optional title image for the form set.

**Animation** – Optional title animation for the form set.

**Description**
33.2. Design Discussion

Fig. 33.14: Platform Configuration Overview
Within a form set, there is one parent form and zero or more child forms. The parent form is the first enabled, visible form in the form set. The child forms are the second or later enabled, visible forms in the form set. In general, the Forms Browser will provide a means to navigate to the parent form. A Cross-Reference is used to navigate between forms within a form set or between forms in different form sets.

Variable stores are declared within a form set. Variable stores describe the means for retrieval and storage of configuration settings, and location information within that variable store. For more information, see Storage.

Default stores are declared within a form set. Default stores group together different types of default settings (normal, manufacturing, etc.) and give them a name. See Defaults for more information.

The form set can control whether or not to process an individual form by nesting it inside of an EFI_IFR_DISABLE_IF expression. Enable/Disable-1 for more information. The form set can control whether or not to display an individual form by nesting it inside of an EFI_IFR_SUPPRESS_IF expression.

Syntax

The form set consists of an EFI_IFR_FORM_SET object, where the body consists of

```plaintext
form-set := EFI_IFR_FORM_SET form-set-list
form-set-list := form form-set-list|
EFI_IFR_IMAGE form-set-list |
EFI_IFR_ANIMATION form-set-list |
EFI_IFR_VARSTORE form-set-list |
EFI_IFR_VARSTORE_EFI form-set-list |
EFI_IFR_VARSTORE_NAME_VALUE form-set-list |
EFI_IFR_DEFAULTSTORE form-set-list |
EFI_IFR_DISABLE_IF expression form-set-list |
<empty>
EFI_IFR_SUPPRESS_IF expression form-set-list |
<empty>
```

33.2.5.2 Forms

Forms are logically-related groups of statements (including questions) designed to be displayed together.

Attributes

Each form has the following attributes:

Form Identifier — A 16-bit unsigned integer, which uniquely identifies the form within the form set. The Form Identifier, along with the device path and Form Set Identifier, uniquely identifies a form within a system.

Title — Title text for the form. The Forms Browser may use this text to describe the nature and purpose of the form in a window title.

Image — Optional title image for the form. The Forms Browser may use this image to display the nature and purpose of the form in a window title.

Animation — Optional title animation for the form set.

Modal — If a form is modal, then the on-form interaction must be completed prior to navigating to another form. See “User Interaction”, User Interaction.

The form can control whether or not to process a statement by nesting it inside of an EFI_IFR_DISABLE_IF expression. See Enable/Disable-2 for more information.

The form can control whether a particular statement is selectable by nesting it inside of an EFI_IFR_GRAY_OUT_IF expression. Statements that cannot be selected are displayed by Form Browsers, but cannot be selected by a user. EFI_IFR_GRAY_OUT_IF causes statements to be displayed with some visual indication. See Evaluation Of Selectable Statements for more information.
The form can control whether to display a statement by nesting it inside of an `EFI_IFR_SUPPRESS_IF` expression. See `EFI_IFR_SUPPRESS_IF` for more information.

**Syntax**

The form consists of an ` EFI_IFR_FORM` object, where the body consists of:

```
form := EFI_IFR_FORM form-tag-list |
       EFI_IFR_FORM_MAP form-tag-list
form-tag-list := form-tag form-tag-list |
                <empty>
form-tag := EFI_IFR_IMAGE |
           EFI_IFR_ANIMATION |
           EFI_IFR_LOCKED |
           EFI_IFR_RULE |
           EFI_IFR_MODAL_TAG |
           statement |
           question |
           cond-statement-list |
<empty>
statement-list := statement statement-list |
                   question statement-list |
                   cond-statement-list |
<empty>
cond-statement-list := EFI_IFR_DISABLE_IF expression statement-list |
                     EFI_IFR_SUPPRESS_IF expression statement-list |
                     EFI_IFR_GRAY_OUT_IF expression statement-list |
                     question-list := question question-list |
<empty>
```

Other unknown opcodes are permitted, but will be ignored.

**33.2.5.2.1 Enable/Disable-1**

Disabled forms will not be processed at all by a Forms Processor. Forms are enabled unless:

- The form nests inside an `EFI_IFR_DISABLE_IF` expression which evaluated to `FALSE`.
- The disabling of forms is evaluated during Forms Processor initialization and is not re-evaluated.

**33.2.5.2.2 Modifiability**

Forms can be locked so that a Forms Editor will not change it. Forms are unlocked unless:

- The form has an `EFI_IFR_LOCKED` in its scope. The locking of statement is evaluated only during Forms Editor initialization.
33.2.5.2.3 Visibility

Suppressed forms will not be displayed. Forms are visible unless:

- The form is disabled (Questions)
- The form is nested inside an EFI_IFR_SUPPRESS_IF expression which evaluates to FALSE.

33.2.5.3 Statements

All displayable items within the body of a form are statements. Statements provide information or capabilities to the user. Questions (Questions) are a specialized form of statement with a value. Statements are used only by Forms Browsers and are ignored by other Forms Processors.

Attributes

Statements have the following attributes:

**Prompt** — The text that will be displayed with the statement.

**Help** — The extended descriptive text that can be displayed with the statement.

**Image** — The optional image that will be displayed with the statement.

**Animation** — The optional animation that will be displayed with the statement.

Other than Questions, there are three types of statements:

- Static Text/Image
- Subtitle
- Cross-Reference

Syntax

```
statement := subtitle | static-text | reset button
statement-tag-list := statement-tag statement-tag-list | <empty>
statement-tag := EFI_IFR_IMAGE |
EFI_IFR_LOCKED
EFI_IFR_ANIMATION
```

33.2.5.3.1 Display

Statement display depends on the Forms Browser. Statements do not describe how the statement must be displayed but rather provide resources (such as text and images) for use by the Forms Browser. The Forms Browser uses this information to create the necessary user interface.

The Forms Browser may use the visibility (Visibility-1) or selectability (Evaluation Of Selectable Statements) of the statements to change the way the item is displayed. The EFI_IFR_GRAY_OUT_IF expression explicitly requires that nested statements have visual differentiation from normal statements.
33.2.5.3.2 Enable/Disable-2

Statements which have been disabled will not be processed at all by a Forms Processor. Statements are enabled unless:

- The parent statement or question is disabled.
- The statement is nested inside an `EFI_IFR_DISABLE_IF` expression which evaluated to `FALSE`.
- The disabling of statements is evaluated during Forms Browser initialization and is not re-evaluated.

33.2.5.3.3 Visibility-1

Suppressed statements will not be displayed. Statements are displayed unless:

- The parent statement or question is suppressed.
- The statement is disabled `Enable/Disable-2`
- The statement is nested inside an `EFI_IFR_SUPPRESS_IF` expression which evaluates to `FALSE`.

The suppression of the statements is evaluated during Forms Browser initialization. Subsequently, the suppression of statements is reevaluated each time a value in any question on the selected form has changed.

33.2.5.3.4 Evaluation of Selectable Statements

A user in a Forms Browser can choose statements which are selectable. Statements are selectable unless:

- The parent statement or question is not selectable.
- The statement is suppressed `Enable/Disable-2`
- The statement is nested inside an `EFI_IFR_GRAY_OUT_IF` expression which evaluated to `FALSE`.

The evaluation of selectable statements takes place during Forms Browser initialization. Subsequently, selectable statements are reevaluated each time a value in any question on the selected form has changed.

33.2.5.3.5 Modifiability

A statement can be locked so that a Forms Editor will not change it. Statements are unlocked unless:

- The parent form or parent statement/question is locked.
- The statement has an `EFI_IFR_LOCKED` in its scope.

The locking of a statement is evaluated only during Forms Editor initialization.

33.2.5.3.6 Static Text/Image

The Forms Browser displays the specified prompt, the specified text and (optionally) the image, but has no user interaction.

Syntax

```
static-text:= EFI_IFR_TEXT statement-tag-list
```
33.2.5.3.7 Subtitle

The subtitle is a means of visually grouping questions by providing a separator, some optional separating text, and an optional image.

Syntax

```
subtitle := EFI_IFR_SUBTITLE statement-tag-list
```

33.2.5.3.8 Reset Button

Attributes

Reset Buttons have the following attributes:

**Default Id** — Specifies the default set to use when restoring defaults to the current form.

Syntax

```
reset button := EFI_IFR_RESET_BUTTON statement-tag-list
```

33.2.5.4 Questions

Questions are statements which have a value. The value corresponds to a configuration setting for the platform or for a device. The question uniquely identifies the configuration setting, describes the possible values, the way the value is stored, and how the question should be displayed.

Attributes

Questions have the following attributes (in addition to those of statements):

**Question Identifier** — A 16-bit unsigned integer which uniquely identifies the question within the form set in which it appears. The Question Identifier, along with the device path and Form Set Identifier, uniquely identifies a question within a system.

**Default Value** — The value used when the user requests that defaults be loaded.

**Manufacturing Value** — The value used when the user requests that manufacturing defaults are loaded.

**Value** — Each question has a current value. See *Values* for more information.

**Value Format** — The format used to store a question’s value.

**Value Storage** — The means by which values are stored. See *Storage Requirements* for more information.

**Refresh Identifiers** — Zero or more GUIDs associated with an event group initialized by the Forms Browser when the form set containing the question is opened. If the event group associated with the GUID is signaled (see *SignalEvent()*), then the question value will be updated from storage.

**Refresh Interval** — The minimum number of seconds that must pass before the Forms Browser will automatically update the current question value from storage. The default value is zero, indicating there will be no automatic refresh.

**Validation** — New values assigned to questions can be validated, using validation expressions, or, if connected, using a callback. See *Validation* for more information.

**Callback** — If set, the callback will be called when the question’s value is changed. In some cases, the presence of these callbacks prevents the question’s value from being edited while disconnected. The question can control whether a particular option can be displayed by nesting it inside of an *EFI_IFR_SUPPRESS_IF* expression. Form Browsers do not display Suppressed Options, but Suppressed Options may still be examined by Form Processors.
Syntax

```plaintext
question := action-button | boolean | date | number | ordered-list | string | time |
cross-reference
question-tag-list := question-tag question-tag-list | <empty>
question-tag := statement-tag |
    EFI_IFR_INCONSISTENT_IF expression |
    EFI_IFR_NO_SUBMIT_IF expression |
    EFI_IFR_WARNING_IF expression |
    EFI_IFR_DISABLE_IF expression question-list |
    EFI_IFR_REFRESH | RefreshEventGroupId |
    EFI_IFR_VARSTORE | DEVICE
question-option-tag := EFI_IFR_SUPPRESS_IF expression |
    EFI_IFR_VALUE optional-expression |
    EFI_IFR_READ expression |
    EFI_IFR_WRITE expression |
    default |
    option
question-option-list := question-tag question-option-list |
    question-option-tag question-option-list |
    <empty>
```

Other unknown opcodes are permitted but are ignored.

### 33.2.5.4.1 Values

Question values are a data type listed in Data Types. During initialization of the Forms Processor or Forms Browser, the values of all enabled questions are retrieved. If the value cannot be retrieved, then the question’s value is Undefined.

A question with the value of type Undefined will be suppressed. This suppression will be reevaluated based on Value Refresh or when any question value on the selected form is changed.

When the form is submitted, the modified values are written to Value Storage. When the form is reset, the question value is set to the default question value. If there is no default question value, the question value is unchanged.

When a question value is retrieved, the following process is used:

1. Set the this internal constant to have the same value as the one read from the question’s storage.**
2. If present, change the current question value to the value returned by a question’s nested EFI_IFR_READ operator.

When a question value is changed, the following process is used:

1. Set the this internal constant to have the same value as the current question value.
2. If present, evaluate the question’s nested EFI_IFR_WRITE (EFI_IFR_WRITE) operator.
3. Write the value to the question’s storage.
Fig. 33.15: Question Value Retrieval Process
Fig. 33.16: Question Value Change Process
33.2.5.4.2 Storage Requirements

Question storage requirements describe the type and size of storage for the value. These storage requirements describe whether the question’s value will be stored as an EFI global variable or using driver local storage. It also describes whether the value is packed together with other values in a buffer, or passed as a name-value pair. See Storage for more information.

33.2.5.4.3 Display

Question display depends on the Forms Browser. Questions do not describe how the question must be displayed. Instead, questions provide resources (such as text and images) and information about visibility and the ability to edit the question. The Forms Browser uses these to create the necessary user interface. Questions can have prompt text, help text and (optionally) an image. The prompt text usually describes the nature of the question. Help text is displayed either in a special display area or only at the request of the user. Questions can also have hints which describe how to visually organize the information.

33.2.5.4.4 Action Button

Action buttons are buttons which cause a pre-defined configuration string to process immediately. There is no storage directly associated with the button.

Attributes

Action buttons have no additional attributes other than the common question attributes.

Storage — There is no storage associated with the action button.

Results — There are no results associated with the action button. If used in an expression, the question value will always be Undefined.

Syntax

```
action-button ::= EFI_IFR_ACTION question-tag-list
```

33.2.5.4.5 Boolean

Boolean questions are those that allow a choice between TRUE and FALSE. The question’s value is Boolean. In general, construct questions so that the prompt text asks questions resulting in ‘yes/enabled/on’ is ‘true’ and ‘no/disabled/off’ is ‘false’.

Boolean questions may be displayed as a check box, two radio buttons, a selection list, a list box, or a drop list box.

Attributes

Boolean questions have no additional attributes other than the common question attributes:

Storage — If the boolean question uses Buffer storage or EFI Variable (see Storage), then the size is exactly one byte, with the FALSE condition is zero and the TRUE value is 1.

Results — The results are represented as either 0 (FALSE) or 1 (TRUE).

Syntax

```
boolean ::= EFI_IFR_CHECKBOX question-option-list
```
33.2.5.4.6 Date

Date questions allow modification of part or all of a standard calendar date. The format of the date display depends on the Forms Browser and any localization.

Attributes
Date questions have the following attributes:

Year Suppressed — The year will not be displayed or updated.
Month Suppressed — The month will not be displayed or updated.
Day Suppressed — The day will not be displayed or updated.

UEFI Storage — In addition to normal question Value Storage, Date questions can optionally be instructed to save the date to either the system time or system wake-up time using the UEFI runtime services `SetTime()` or `SetWakeupTime()`.

Conversion to and from strings to a date depends on the system localization.

The date value is stored an `EFI_HII_TIME` structure. The TimeZone field is always set to `EFI_UNSPECIFIED_TIMEZONE`. The Daylight field is always set to zero. The contents of the other fields are undetermined.

Storage — If the date question uses Buffer storage or EFI Variable storage (Storage), then the stored result will occupy exactly the size of `EFI_HII_DATE`.

Results — Results for date questions are represented as a hex dump of the `EFI_HII_DATE` structure. If used in a question, the value will be a buffer containing the contents of the `EFI_HII_DATE` structure.

Syntax

```plaintext
date := EFI_IFR_DATE question-option-list
```

33.2.5.4.7 Number

Number questions allow modification of an integer value up to 64-bits. Number questions can also specify pre-defined options.

Attributes
Number questions have the following attributes:

Radix — Hint describes the output radix of numbers. The possible values are unsigned decimal, signed decimal or hexadecimal. Numbers displayed in hexadecimal will be prefixed by ‘0x’

Minimum Value — The minimum unsigned value which can be accepted for this question.

Maximum Value — The maximum unsigned value which can be accepted for this question.

Skip Value — Defines the minimum increment between values.

Storage — If the number question uses Buffer storage or EFI Variable storage (Storage), then the buffer size specified by must be 1, 2, 4 or 8. Also, the Forms Processor will do implicit error checking to make sure that the signed or unsigned value can be stored in the Buffer without lost of significant bits. For example, if the buffer size is 1 byte, then the largest unsigned integer value would be 255. Likewise, the largest signed integer value would be 127 and the smallest signed integer value would be -128. The Forms Processor will automatically detect this as an error and generate an appropriate error.

Results — The results are represented as string versions of unsigned hexadecimal values.
Syntax

```
number := EFI_IFR_NUMERIC question-option-list |
          EFI_IFR_ONE_OF question-option-list
```

### 33.2.5.4.8 Set

Sets are questions where \( n \) containers can be filled with any of \( m \) pre-defined choices. This supports both lists where a given value can only appear in one of the slots or where the same choice can appear many times.

Each of the containers takes the form of an option which a name, a value and (optionally) an image.

**Attributes**

Set questions have the following attributes:

- **Container Count** — Specifies the number of available selectable options.
- **Unique** — If set, then each choice may be used at most, once.
- **NoEmpty** — All slots must be filled with a non-zero value.
- **Storage** — The set questions are stored as a Buffer with one byte for each Container.

**Results**

Each Container value is represented as two characters, one for each nibble. All hexadecimal characters (a-f) are in lower-case.

The results are represented as a series of Container values, starting with the lowest Container.

**Syntax**

```
ordered-list := EFI_IFR_ORDERED_LIST question-option-list
```

**Options**

Set questions treat the values specified by nested `EFI_IFR_ONE_OF_OPTION` values as the value for a single Container, not the entire question storage. This is different from other question types.

**Defaults**

Set questions treat the default values specified by nested `EFI_IFR_DEFAULT` or `EFI_IFR_ONE_OF_OPTION` op-codes as the default value for all Containers. The default values must be of type `EFI_IFR_TYPE_BUFFER`, with each byte in the buffer corresponding to a single Container value, starting with the first container. If the buffer contains fewer bytes than `MaxContainers`, then the remaining Containers will be set to a value of 0.

Default values returned from the ALTCFG section when `ExtractConfig()` is called fill the storage starting with the first container.

### 33.2.5.4.9 String

String questions allow modification of a string.

**Attributes**

String questions have the following attributes:

- **Minimum Length** — Hint describes the minimum length of the string, in characters.
- **Maximum Length** — Hint describes the maximum length of the string, in characters.
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

**Multi-Line** — Hint describes that the string might contain multiple lines.

**Output Mask** — If set, the text entered will not be displayed.

**Storage** — The string questions are stored as a NULL-terminated string. If the time question uses Buffer or EFI Variable storage (Storage), then the buffer size must exceed the size of the NULL-terminated string. If the string is shorter than the length of the buffer, the remainder of the buffer is filled with NULL characters.

**Results** — Results for string questions are represented as hex dump of the string, including the terminating NULL character.

**Syntax**

```
string := EFI_IFR_STRING question-option-list | EFI_IFR_PASSWORD question-option-list
```

### 33.2.5.4.10 Cross-Reference

Cross-reference questions provide a selectable means by which users navigate to other forms and/or other questions. The form and question can be in the current form set, another form set or even in a form associated with a different device. If the specified form or question does not exist, the button is not selectable, is grayed-out, or is suppressed.

**Attributes**

Cross references can have the following attributes:

**Form Identifier** — The identifier of the target form.

**Form Set Identifier** — Optionally specifies an alternate form-set which contains the target form. If specified, then the focus will be on form within the form set specified by Form Identifier. If the Form Identifier is not specified, then the first form in the Form Set is used.

**Question Identifier** — Optionally specifies the question identifier of the target question on the target form. If specified then focus will be placed on the question specified by this question identifier. Otherwise, the focus will be on the first question within the specified form.

**Device Path** — Optionally, the device path which contains the Form Identifier. Otherwise, the device path associated with the form set containing this cross-reference will be used.

**Storage** — Storage is optional for a cross-reference question. It is only present when the cross-reference question does not supply any target (i.e., REFS). If the question uses Buffer or EFI Variable storage (Storage), then the buffer size must be exactly the size of the EFI_HII_REF structure.

**Results** — Results for cross-reference questions are represented as a hex dump of the question identifier, form identifier, form set GUID and null-terminated device path text. If used in a question, the question value will be a buffer containing the EFI_HII_REF structure.

**Syntax**

```
*cross-reference* := *EFI_IFR_REF* *statement-tag-list*
```
33.2.5.4.11 Time

Time questions allow modification of part or all of a time. The format of the time display depends on the Forms Browser and any localization.

Attributes

Time questions have the following attributes:

**Hour Suppressed** — The hour will not be displayed or updated.

**Minute Suppressed** — The minute will not be displayed or updated.

**Second Suppressed** — The second will not be displayed or updated.

**UEFI Storage** — In addition to normal question Value Storage, time questions can be instructed to save the time to either the system time or system wake-up time using the UEFI runtime services `SetTime` or `SetWakeupTime`. In these instances, the date and time is read first, the modifications made and changes are then written back.

Conversion to and from strings to a time depends on the system localization.

The time value is stored as part of an `EFI_HII_TIME` structure. The contents of the other fields are undetermined.

**Storage** — If the time question uses Buffer or EFI Variable storage (`Storage`), then the buffer size must be exactly the size of the `EFI_HII_TIME` structure.

**Results** — Results for time questions are represented as a hex dump of the `EFI_HII_TIME` structure. If used in a question, the value will be a buffer containing the contents of the `EFI_HII_TIME` structure.

Syntax

```
time := EFI_IFR_TIME question-option-list
```

33.2.5.5 Options

Use Options within questions to give text or graphic description of a particular question value. They may also describe the choices in the set data type.

Attributes

Options have the following attributes:

**Text** — The text for the option.

**Image** — The optional image for the option.

**Animation** — The optional animation for the option.

**Value** — The value for the option.

**Default** — If set, this is the option selected when the user asks for the defaults. Only one visible option can have this bit set within a question’s scope.

**Manufacturing Default** — If set, this is the option selected when manufacturing defaults are set. Only one visible option can have this bit set within a question’s scope.

Syntax

```
option:= EFI_IFR_ONE_OF_OPTION option-tag-list
option-tag-list := option-tag option-tag-list |
<empty>
```
33.2.5.5.1 Visibility

Options which have been suppressed will not be displayed. Options are displayed unless:

- The parent question is suppressed.
- The option is nested inside an `EFI_IFR_SUPPRESS_IF` expression which evaluated to `FALSE`.

The suppression of the options is evaluated each time the option is displayed.

33.2.5.6 Storage

Question values are stored in Variable Stores, which are application, platform or device repositories for configuration settings. In many cases, this is non-volatile storage. In other cases, it holds only the current behavior of a driver or application.

Question values are retrieved from the variable store when the form is initialized. They are updated periodically based on question settings and stored back in the variable store when the form is submitted.

It is possible for a question to have no associated Variable Store. This happens when the VarStoreId associated with the question is set to zero and, for Date/Time questions, the UEFI Storage is disabled. For questions with no associated Variable Store, the question must either support the RETRIEVE and CHANGED callback actions (`EFI_HII_CONFIG_ACCESS_PROTOCOL.CallBack()`) or contain an embedded READ or WRITE opcode: `EFI_IFR_READ_OP` and `EFI_IFR_WRITE_OP` (`EFI_IFR_READ` and `EFI_IFR_WRITE`).

Because the value associated with a question contained in a Variable Store can be shared by multiple questions, the questions must all treat the shared information as compatible data types. There are four types of variable stores:

**Buffer Storage** — With buffer storage, the application, platform or driver provides the definition of a buffer which contains the values for one or more questions. The size of the entire buffer is defined in the `EFI_IFR_VARSTORE` definition. Each question defines a field in the buffer by providing an offset within the buffer and the size of the required storage. These variable stores are exposed by the app/driver using the `EFI_HII_CONFIG_ACCESS_PROTOCOL`, which is installed on the same handle as the package list. Question values are retrieved via `EFI_HII_CONFIG_ACCESS_PROTOCOL.ExtractConfig()` and updated via `EFI_HII_CONFIG_ACCESS_PROTOCOL.RouteConfig()`. Rather than access the buffer as a whole, Buffer Storage Variable Stores access each field independently, via a list of one or more (field offset, value) pairs encoded as variable length text strings as defined for the `EFI_HII_CONFIG_ACCESS_PROTOCOL`.

**Name/Value Storage** — With name/value storage, the application provides a string which contains the encoded values for a single question. These variable stores are exposed by the app/driver using the `EFI_HII_CONFIG_ACCESS_PROTOCOL`, which is installed on the same handle as the package list.

**EFI Variable Storage** — This is a specialized form of Buffer Storage, which uses the EFI runtime services `GetVariable()` and `SetVariable()` to access the entire buffer defined for the Variable Store as a single binary object.

**EFI Date/Time Storage** — For date and time-related questions, the question values can be retrieved using the EFI runtime services `GetTime()` and `GetWakeupTime()` and stored using the EFI runtime services `SetTime()` and `SetWakeupTime()`.

The following table summarizes the types of information needed for each type of storage and where it is retrieved from.
### Table 33.2: Information for Types of Storage

<table>
<thead>
<tr>
<th>Storage Type</th>
<th>Information Type</th>
<th>Where It Comes From</th>
</tr>
</thead>
<tbody>
<tr>
<td>None</td>
<td>Driver Handle</td>
<td>Handle specified with <code>NewPackageList()</code> or derived from <code>EFI_IFR_VARSTORE_DEVICE.DevicePath</code></td>
</tr>
<tr>
<td>Buffer Storage</td>
<td>Driver Handle</td>
<td>Handle specified with <code>NewPackageList()</code> or derived from <code>EFI_IFR_VARSTORE_DEVICE.DevicePath</code></td>
</tr>
<tr>
<td></td>
<td>Variable ID</td>
<td>Variable store specified by <code>EFI_IFR_QUESTION_HEADER.*VarStoreId.</code></td>
</tr>
<tr>
<td></td>
<td>Variable Name</td>
<td>Variable name specified by <code>EFI_IFR_QUESTION_HEADER.*VarStoreInfo.VarName.</code></td>
</tr>
<tr>
<td></td>
<td>Variable Store Offset</td>
<td>Variable store offset specified by <code>EFI_IFR_QUESTION_HEADER.VarOffset.</code></td>
</tr>
<tr>
<td>Name/Value Storage</td>
<td>Driver Handle</td>
<td>Handle specified with <code>NewPackageList()</code> or derived from <code>EFI_IFR_VARSTORE_DEVICE.DevicePath</code></td>
</tr>
<tr>
<td></td>
<td>Variable ID</td>
<td>Variable store specified by <code>EFI_IFR_QUESTION_HEADER.*VarStoreId.</code></td>
</tr>
<tr>
<td></td>
<td>Variable Name</td>
<td>Variable name specified by <code>EFI_IFR_QUESTION_HEADER.*VarStoreInfo.VarName.</code></td>
</tr>
<tr>
<td></td>
<td>None</td>
<td>None</td>
</tr>
<tr>
<td>EFi Variable Storage</td>
<td>Driver Handle</td>
<td>None</td>
</tr>
<tr>
<td></td>
<td>Variable ID</td>
<td>Variable store specified by <code>EFI_IFR_QUESTION_HEADER.*VarStoreId.</code></td>
</tr>
<tr>
<td></td>
<td>EFi_Variable GUID (for Variable Services)</td>
<td>EFi variable GUID specified by <code>EFI_IFR_VARSTORE_EFI.Guid.</code></td>
</tr>
<tr>
<td></td>
<td>EFi_Variable Name (for Variable Services)</td>
<td>EFi variable name specified by <code>EFI_IFR_VARSTORE_EFI.Name.</code></td>
</tr>
<tr>
<td></td>
<td>Variable Name</td>
<td>Variable name specified by <code>EFI_IFR_QUESTION_HEADER.*VarStoreId.</code></td>
</tr>
<tr>
<td></td>
<td>Variable Store Offset</td>
<td>Variable store offset specified by <code>EFI_IFR_QUESTION_HEADER.VarStoreInfo.VarOffset.</code></td>
</tr>
<tr>
<td>EFi Date/Time Storage</td>
<td>Driver Handle</td>
<td>None</td>
</tr>
<tr>
<td></td>
<td>Variable ID</td>
<td>None</td>
</tr>
<tr>
<td></td>
<td>Variable Name</td>
<td>None</td>
</tr>
</tbody>
</table>

### 33.2.5.7 Expressions

This section describes the expressions used in various expressions in IFR. The expressions are encoded using normal IFR opcodes, but in RPN (Reverse Polish Notation) where the operands occur before the operator.

The opcodes fall into these categories:

**Unary operators.** — Functions taking a single sub-expression.

**Binary operators.** — Functions taking two sub-expressions.

**Ternary operators.** — Functions taking three sub-expressions.

**Built-in functions.** — Operators taking zero or more sub-expressions.

**Constants.** — Numeric and string constants.

**Question Values.** — Specified by their question identifier.

All integer operations are performed at 64-bit precision.
33.2.5.7.1 Expression Encoding

Expressions are usually encoded within the scope of another binary object. If the expression consists of more than a single opcode, the first opcode should open a scope (Header.Scope = 1) and use an EFI_IFR_END opcode to close the scope in order to make sure they can be skipped.

33.2.5.7.2 Expression Stack

When evaluating expressions, the Forms Processor uses a stack to hold intermediate values. Each operator either pushes a value on the stack, pops a value from the stack, or both. For example, the EFI_IFR_ONE operator pushes the integer value 1 on the expression stack. The EFI_IFR_ADD operator pops two integer values from the expression stack, adds them together, and pushes the result back on the stack.

After evaluating an expression, there should be only one value left on the expression stack.

33.2.5.7.3 Rules

Rules are pre-defined expressions attached to the form. These rules may be used in any expression within the form’s scope. Each rule is given a unique identifier (0-255) when it is created by EFI_IFR_RULE. This same identifier is used when the rule is referred to in an expression with EFI_IFR_RULE_REF.

To save space, rules are intended to allow manual or automatic extraction of common sub-expressions from form expressions.

33.2.5.7.4 Data Types

The expressions use five basic data types:

- **Boolean** — TRUE or FALSE.
- **Unsigned Integer** — 64-bit unsigned integer.
- **String** — Null-terminated string.
- **Buffer** — Fixed size array of unsigned 8-bit integers.
- **Undefined** — Undetermined value. Used when the value cannot be calculated or for run-time errors.

Data conversion is not implicit. Explicit data conversion can be performed using the EFI_IFR_TO_STRING, EFI_IFR_TO_UINT and EFI_IFR_TO_BOOLEAN.

The Date and Time question values are converted to the Buffer data type filled with the EFI_HII_DATE and EFI_HII_TIME structure contents (respectively).

The Ref question values are converted to the Buffer data type and filled with the EFI_HII_REF and structure contents.

**Syntax**

The expressions have the following syntax:

```
expression := built-in-function |
constant |
extension unary-op |
extension expression binary-op |
extension expression expression expression ternary-op
expression-pair-list
```

(continues on next page)
EFI_IFR_MAP
expression-pair-list := expression-pair-list expression expression | <empty>

optional-expression := expression | <empty>

built-in-function := EFI_IFR_DUP | EFI_IFR_EQ_ID_VAL | EFI_IFR_EQ_ID_ID | EFI_IFR_EQ_ID_VAL_LIST | EFI_IFR_GET | EFI_IFR_QUESTION_REF1 | EFI_IFR_QUESTION_REF3 | EFI_IFR_RULE_REF | EFI_IFR_STRING_REF1 | EFI_IFR_THIS | EFI_IFR_SECURITY

custom := EFI_IFR_FALSE | EFI_IFR_ONE | ^EFI_IFR_ONES | EFI_IFR_TRUE | EFI_IFR_UINT8 | EFI_IFR_UINT16 | EFI_IFR_UINT32 | EFI_IFR_UINT64 | EFI_IFR_UNDEFINED | EFI_IFR_VERSION | EFI_IFR_ZERO

binary-op := EFI_IFR_ADD | EFI_IFR_AND | EFI_IFR_BITWISE_AND | EFI_IFR_BITWISE_OR | EFI_IFR_CATENATE | EFI_IFR_DIVIDE | EFI_IFR_EQUAL | EFI_IFR_GREATER_EQUAL | EFI_IFR_GREATER_THAN | EFI_IFR_LESS_EQUAL | EFI_IFR_LESS_THAN | EFI_IFR_MATCH | EFI_IFR_MATCH2 | EFI_IFR_MODULO | EFI_IFR_MULTIPLY | EFI_IFR_NOT_EQUAL | EFI_IFR_OR | EFI_IFR_SHIFT_LEFT | EFI_IFR_SHIFT_RIGHT | EFI_IFR_SUBTRACT | unary-op := EFI_IFR_LENGTH | EFI_IFR_NOT |
33.2.5.8 Defaults

To ensure consistent behavior when a platform attempts to restore settings to defaults, each question op-code must have an active default setting. Defaults are pre-defined question values. The question values may be changed to their defaults either through a Forms Processor-defined means or when the user selects an EFI_IFR_RESET_BUTTON statement (Reset Button).

Each question may have zero or more default values, with each default value used for different purposes. For example, there might be a “standard” default value, a default value used for manufacturing and a “safe” default value. A group of default values used to configure a platform or device for a specific purpose is called default store.

Default Stores

There are three standard default stores:

Standard Defaults — These are the defaults used to prepare the system/device for normal operation.

Manufacturing Defaults — These are the defaults used to prepare the system/device for manufacturing.

Safe Defaults — These are the defaults used to boot the system in a “safe” or low-risk mode.

Attributes — Default stores have the following attributes:

Name

Each default store has a user-readable name

Identifier

A 16-bit unsigned integer. The values between 0x0000 and 0x3fff are reserved for use by the UEFI specification. The values between 0x4000 and 0x7fff are reserved for platform providers. The values between 0x8000 and 0xbfff are reserved for hardware vendors. The values between 0xc000 and 0xffff are reserved for firmware vendors.

```
#define EFI_HII_DEFAULT_CLASS_STANDARD 0x0000
#define EFI_HII_DEFAULT_CLASS_MANUFACTURING 0x0001
#define EFI_HII_DEFAULT_CLASS_SAFE 0x0002
#define EFI_HII_DEFAULT_CLASS_PLATFORM_BEGIN 0x4000
#define EFI_HII_DEFAULT_CLASS_PLATFORM_END 0x7fff
#define EFI_HII_DEFAULT_CLASS_HARDWARE_BEGIN 0x8000
#define EFI_HII_DEFAULT_CLASS_HARDWARE_END 0xbfff
#define EFI_HII_DEFAULT_CLASS_FIRMWARE_BEGIN 0xc000
#define EFI_HII_DEFAULT_CLASS_FIRMWARE_END 0xffff
```
Users of these ranges are encouraged to use the specification defined ranges for maximum interoperability. Questions or platforms may support defaults for only a sub-set of the possible default stores. Support for default store 0 (“standard”) is recommended.

Defaulting

When retrieving the default values for a question, the Forms Processor uses one of the following (listed from highest priority to lowest priority):

1. The value returned from the Callback() member function of the Config Access protocol associated with the question when called with the Action set to one of the*EFI_BROWSER_ACTION_DEFAULT_x* values (EFI HII Configuration Access Protocol). It is recommended that this form only be used for questions where the default value alters dynamically at runtime.**

2. The value returned in the Response parameter of the ConfigAccess() member function (using the ALTCFG form). See String Syntax.

3. The value specified by an EFI_IFR_DEFAULT opcodes appear within the scope of a question. (EFI_IFR_DEFAULT)

4. One of the Options (Options) has its Standard Default or Manufacturing Default attribute set.

5. For Boolean questions, the Standard Default or Manufacturing Default values in the Flags field. (Boolean).

Syntax

```
Default := EFI_IFR_DEFAULT
default-tag := EFI_IFR_VALUE | <empty>
```

33.2.5.9 Validation

Validation is the process of determining whether a value can be applied to a configuration setting. Validation takes place at three different points in the editing process: edit-level, question-level and form-level.

33.2.5.9.1 Edit-Level Validation

First, it takes place while the value is being edited with a Forms Browser. The Forms Browser may optionally reject values selected by the user which would fail Question-Level validation. For example, the Forms Browser may limit the length of strings entered so that they meet the Minimum and Maximum Length.

33.2.5.9.2 Question-Level Validation

Second, it takes place when the value has changed, normally when the user attempts to leave the control, navigate between the portions of the control or selects one of the option values. At this point, an error occurs if:

- For a String (String), if the string length is less than the Minimum Length, then the Forms Processor generates an error.
- For a String (String), if the string length is greater than the Maximum Length, then the Forms Processor generates an error.
- For a Number (Number), if the number cannot fit in the specified variable storage without loss of significant bits, then the Forms Processor generates an error.
- For all questions, if an EFI_IFR_INCONSISTENT_IF evaluates to TRUE, then the Forms Processor will display the specified error text.
• For all questions, if an \textit{EFI_IFR\_WARNING\_IF} evaluates to \textbf{TRUE}, then the Forms Processor will display the specified warning text.

33.2.5.9.3 Form-Level Validation

Third, it takes place when exiting the form or when the values are submitted. The error occurs under two conditions:

• For all questions, if an \textit{EFI_IFR\_NO\_SUBMIT\_IF} evaluates to \textbf{TRUE}, then the Forms Processor will display the specified error text.

• If a Forms Processor such as a script processor performs Form-Level validation, where the concept of a form is not maintained, then the Form-Level validation must occur before processing question values from other forms or before completion of the configuration session.

33.2.5.10 Forms Processing

Forms Processors interpret the IFR in order to extract information about configuration settings. This section describes how the IFR should be interpreted and how errors should be handled.

33.2.5.10.1 Error Handling

The Forms Processor may encounter problems in interpreting the IFR. This section describes the standard ways of handling these issues:

\textbf{Unknown Opcodes}. — Unknown opcodes have a type which is not recognized by the Forms Processor. In general, the Forms Processor ignores the opcode, along with any nested opcodes.

\textbf{Malformed Opcodes}. — Malformed objects have a length which is less than the minimum length for that object type. In this case, the entire form is disabled.

\textbf{Extended Opcodes}. — Extended objects have a length longer than that expected by the Forms Processor. In this case, the Forms Processor interprets the object normally and ignores the extra data.

\textbf{Malformed Forms Sets} — Malformed forms sets occur when an object’s length would cause it to extend beyond the end of the forms set, or when the end of the forms set occurs while a scope is still open. In this case, the entire forms set is ignored.

\textbf{Reserved Bits Set}. — The Forms Processor should ignore all set reserved bits.

33.2.5.11 Forms Editing

This section describes considerations for Forms Editors, which are a specialized Forms Processor which can create and manipulate form lists, forms and questions in their binary form.
33.2.5.11.1 Locking

Locking indicates that a question or statement—along with its related options, prompts, help text or images—should not be moved or edited. A statement or question is locked when the IFR_LOCKED opcode is found within its scope.

UEFI-compliant Forms Editors must allow statements or questions within an image to be locked, but should not allow them to be unlocked. UEFI-compliant Forms Editors must not allow modification of locked statements or questions or any of their associated data (including options, text or images).

NOTE: This mechanism cannot prevent unauthorized modification. However, it does clearly state the intent of the driver creator that they should not be modified.

33.2.5.11.2 Moving Forms

When forms are moved between form sets, the related data (such as forms, variable stores and default stores) need to have their references renumbered to avoid conflicts with identifiers in the new form set. For forms, these include:

- EFI_IFR_FORM or EFI_IFR_FORM_MAP (and all references in EFI_IFR_REF)
- EFI_IFR_DEFAULTSTORE (and all references in EFI_IFR_DEFAULT)
- EFI_IFR_VARSTORE_x (and all references within question headers)

33.2.5.11.3 Moving Questions

When questions are moved between form sets, the related data (such as images and strings) need to be moved and references to results-processing and storage may need to be revised. For example:

String and Images. — If the question is being moved to another form set, then all strings and images associated with the question must be moved to the package list containing the form set and removed from the current one.

Form Set. — If the question is moved to a package list installed by a different driver, then the EFI_IFR_VAR_STORAGE_DEVICE (EFI_IFR_VARSTORE_DEVICE) should be nested in the scope of the question, describing the driver installation device path.

Question References. — If a question value in another form set is referred to in any expressions (such as EFI_IFR_INCONSISTENT_IF or EFI_IFR_NO_SUBMIT_IF or EFI_IFR_WARNING_IF) using either EFI_IFR_QUESTION_REF2 (EFI_IFR_Question_REF2) or EFI_IFR_QUESTION_REF1 (EFI_IFR_Question_REF1) then these must be converted to a form of EFI_IFR_QUESTION_REF3 (EFI_IFR_Question_REF3) specifying the EFI_GUID of the form set and/or the device path of the package list containing the form set wherein the question referred to is defined.

When questions are moved between forms, whether in the same form list or another form list, question behavior reliant on the current form may need revision. One example is the use of EFI_IFR_RULE_REF in expressions. Here, rules are shortcuts for common expressions used in a form. If a question is moved to another form, the references to any rules in expressions must be replaced by the expression itself.
33.2.5.12 Forms Processing & Security Privileges

The IFR provides a way for a Forms Processor to identify which forms, statements, questions and even question values are available only to users with specific privilege levels and enforce those privilege levels.

Setup access security privileges are described in terms of GUIDs. The current user profile either has the specified privilege or it does not. The `EFI_IFR_SECURITY` opcode returns whether or not the current user profile has the specified setup access privilege. Combined with the expressions such as `EFI_IFR_DISABLE_IF`, `EFI_IFR_SUPPRESS_IF`, `EFI_IFR_GRAY_OUT_IF`, `EFI_IFR_WARNING_IF`, `EFI_IFR_INCONSISTENT_IF` and `EFI_IFR_NOSUBMIT_IF`, the author of a form can control access to specific forms, statements and questions, or even control whether specific values are valid.

Forms Processors on systems with multiple setup-related user privilege levels must support report these correctly when processing the `EFI_IFR_SECURITY` opcode.

Forms Processors on systems which support the UEFI User Authentication proposal must correctly inquire from the current user profile whether or not it has security privileges on `EFI_USER_INFO_ACCESS_SETUP` and `User Manager Protocol` on `EFI_USER_MANAGER_PROTOCOL.GetInfo()`.

Forms Processors on systems which support re-identification during the platform configuration process must support reevaluation of the `EFI_IFR_SUPPRESS_IF` and `EFI_IFR_GRAY_OUT_IF` upon receipt of notification that the current user profile has been changed by using the UEFI Boot Service `CreateEventEx()` and the `EFI_USER_PROFILE_CHANGED_EVENT_GUID`.

33.2.6 Strings

Strings in the UEFI environment are defined using UCS-2, which is a 16-bit-per-character representation. For user-interface purposes, strings are one of the types of resources which can be installed into the HII Database (HII Database).

In order to facilitate localization, users reference strings by an identifier unique to the package list which the driver installed. Each identifier may have several translations associated with it, such as English, French, and Traditional Chinese. When displaying a string, the Forms Browser selects the actual text to display based on the current platform language setting.

The actual text for each language is stored separately (in a separate package), which makes it possible to add and remove language support just by including or excluding the appropriate package.

Each string may have font information, including the font family name, font size and font style, associated with it. Not all platforms or displays can support fonts and styles beyond the system default font (Fonts), so the font information associated with the string should be viewed as a set of hints.

33.2.6.1 Configuration Language Paradigm

This specification uses the RFC 4646 language naming scheme to identify the language that a given string is associated with. Since RFC 4646 allows for the same Primary language tags to contain a large variation of subtags (e.g. regions), a best matching language algorithm is defined in RFC 4647. Callers of interfaces that require RFC 4646 language codes to retrieve a Unicode string, must use the RFC 4647 algorithm to lookup the Unicode string with the closest matching RFC 4646 language code.

Since the majority of strings discussed in this specification are associated with generating a user interface, the languages that are typically associated with strings have commonly defined languages such as en-US, zh-Hant, and it-IT. The RFC 4646 standard also reserves for private use languages prefixed with a value of “x”.

NOTE: This specification defines for its own purposes one of these private use areas as a special-purpose language that components can use for extracting information out of. Assume that any private-use languages encountered by a compliant implementation will likely consider those languages as configuration languages, and the associated behavior...
STRING IDENTIFIER #33

- ENGLISH: Hello World
- SPANISH: ¡Hola mundo!
- FILIPINO: Mubuhay sa daigdig!
- SIMPLIFIED CHINESE: 你好世界
- RUSSIAN: здравствуйте! Мир

Fig. 33.17: String Identifiers
when referencing those languages will be platform specific. Working with a UEFI Configuration Language describes an example of such a use.

33.2.6.2 Unicode Usage

This section describes how different aspects of the Unicode specification related to the strings within this specification.

33.2.6.2.1 Private Use Area

Unicode defines a private use area of 6500 characters that may be defined for local uses. Suggested uses include Egyptian Hieroglyphics; see Developing International Software For Windows 95* and Windows NT* for more information. UEFI prohibits use of this area in a UEFI environment. This is because a centralized font database accumulated from the various drivers (a valid implementation) would end up with collisions in the private use area, and, generally, an XML browser could not display these characters.

33.2.6.2.2 Surrogate Area

The Unicode specification has two 16-bit character representations: UCS-2 and UTF-16. The UEFI specification uses UCS-2. The primary difference is that UTF-16 defines surrogate areas (see page 56 in Professional XML) that allow for expanded character representations of the 16-bit Unicode. These character representations are very similar to Double Byte Character Set (DBCS)--2048 Unicode values split into two groups (D800-DBFF and DC00-DFFFF). They are defined as having 16 additional bits of value to make up the character, for a total of about one million extra characters. UEFI does not support surrogate characters.

33.2.6.2.3 Non-Spacing Characters

Unicode uses the concept of a nonspacing character. These glyphs are used to add accents, and so on, to other characters by what amounts to logically OR’ing the glyph over the previous glyph. There does not appear to be any predictable range in the Unicode encoding to determine nonspacing characters, yet these characters appear in many languages. Further, these characters enable spelling of several languages including many African languages and Vietnamese.

33.2.6.2.4 Common Control Codes

This specification allows the encoding of font display information within the strings using special control characters. These control codes are meant as display hints, and different platforms may ignore them, depending on display capabilities.

In single-byte encoding, these are in the form 0x7F 0xyy or 0x7F 0x0y 0xzz. Single-byte encoding is used only when coupled with the Standard Compression Scheme for Unicode, described in String Encoding.

In double-byte encoding, these are in the form 0xF6yy, 0xF7zz or 0xF8zz. When converted to UCS-2, all control codes should use the 0xFxyy form.

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
<th>Single-Byte Encoding</th>
<th>Double-Byte Encoding</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>Font Family Select. The subsequent text will be displayed in the font specified by the following byte.</td>
<td>0x7F 0x00 0xzz</td>
<td>0xF7zz</td>
</tr>
</tbody>
</table>

continues on next page
### Table 33.3 – continued from previous page

<table>
<thead>
<tr>
<th>0x01</th>
<th>Font Size Select. The subsequent text will be displayed in the point size, in half points, specified by the following byte.</th>
<th>0x7F 0x01 0xzz</th>
<th>0xFzz</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x20</td>
<td>Bold On.</td>
<td>0x7F 0x20</td>
<td>0xF20</td>
</tr>
<tr>
<td>0x21</td>
<td>Bold Off</td>
<td>0x7F 0x21</td>
<td>0xF21</td>
</tr>
<tr>
<td>0x22</td>
<td>Italic On</td>
<td>0x7F 0x22</td>
<td>0xF22</td>
</tr>
<tr>
<td>0x23</td>
<td>Italic Off</td>
<td>0x7F 0x23</td>
<td>0xF23</td>
</tr>
<tr>
<td>0x24</td>
<td>Underline On</td>
<td>0x7F 0x24</td>
<td>0xF24</td>
</tr>
<tr>
<td>0x25</td>
<td>Underline Off</td>
<td>0x7F 0x25</td>
<td>0xF25</td>
</tr>
<tr>
<td>0x26</td>
<td>Emboss On</td>
<td>0x7F 0x26</td>
<td>0xF26</td>
</tr>
<tr>
<td>0x27</td>
<td>Emboss Off</td>
<td>0x7F 0x27</td>
<td>0xF27</td>
</tr>
<tr>
<td>0x28</td>
<td>Shadow On</td>
<td>0x7F 0x28</td>
<td>0xF28</td>
</tr>
<tr>
<td>0x29</td>
<td>Shadow Off</td>
<td>0x7F 0x29</td>
<td>0xF29</td>
</tr>
<tr>
<td>0x2A</td>
<td>DblUnderline On</td>
<td>0x7F 0x2A</td>
<td>0xF2A</td>
</tr>
<tr>
<td>0x2B</td>
<td>DblUnderline Off</td>
<td>0x7F 0x2B</td>
<td>0xF2B</td>
</tr>
</tbody>
</table>

### 33.2.6.2.5 Line Breaks

This section describes the use of control characters to determine where break opportunities within strings. These guidelines are based on Unicode Technical Report #14, but are significantly simplified.

**Spaces**

In general, any of the following space characters is a line-break opportunity:

| 0020 | SPACE |
| 1680 | OGHAM SPACE MARK |
| 2000 | EN QUAD |
| 2001 | EM QUAD |
| 2002 | EN SPACE |
| 2003 | EM SPACE |
| 2004 | THREE-PER-EM SPACE |
| 2005 | FOUR-PER-EM SPACE |
| 2006 | SIX-PER-EM SPACE |
| 2008 | PUNCTUATION SPACE |
| 2009 | THIN SPACE |
| 200A | HAIR SPACE |
| 205F | MEDIUM MATHEMATICAL SPACE |

When a space is desired without a line-break opportunity, one of the following spaces should be used:

| 00A0 | NO-BREAK SPACE (NBSP) |
| 202F | NARROW NO-BREAK SPACE (NNBSP) |

**In-Word Break Opportunities**

In some cases, allowing line-breaks in a word is desirable. These line break opportunities should be explicitly described using one of the characters from the following list:

| 200B | ZERO WIDTH SPACE (ZWSP) |
Hyphens

The following characters are hyphens and other characters which describe line break opportunities after the character.

<table>
<thead>
<tr>
<th>Character</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>058A</td>
<td>ARMENIAN HYPHEN</td>
</tr>
<tr>
<td>2010</td>
<td>HYPHEN</td>
</tr>
<tr>
<td>2012</td>
<td>FIGURE DASH</td>
</tr>
<tr>
<td>2013</td>
<td>EN DASH</td>
</tr>
<tr>
<td>0F0B</td>
<td>TIBETAN MARK INTERSYLLABIC TSHEG</td>
</tr>
<tr>
<td>1361</td>
<td>ETHIOPIAN WORDSPACE</td>
</tr>
<tr>
<td>17D5</td>
<td>KHMER SIGN BARIYOOSAN</td>
</tr>
</tbody>
</table>

The following characters describe line break opportunities before and after them, but not between a pair of them:

<table>
<thead>
<tr>
<th>Character</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>2014</td>
<td>EM DASH</td>
</tr>
</tbody>
</table>

The following characters describe a hyphen which is not a line-breaking opportunity:

<table>
<thead>
<tr>
<th>Character</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>2011</td>
<td>NON-BREAKING HYPHEN (NBHY)</td>
</tr>
</tbody>
</table>

The following characters force a line-break:

<table>
<thead>
<tr>
<th>Character</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>000A</td>
<td>NEW LINE</td>
</tr>
<tr>
<td>000C</td>
<td>FORM FEED</td>
</tr>
<tr>
<td>000D</td>
<td>CARRIAGE RETURN</td>
</tr>
<tr>
<td>2028</td>
<td>LINE SEPARATOR</td>
</tr>
<tr>
<td>2029</td>
<td>PARAGRAPH SEPARATOR</td>
</tr>
</tbody>
</table>

**Table 33.10: Mandatory Breaks**

33.2.7 Fonts

This section describes how fonts are used within the UEFI environment.

UEFI describes a standard font, which is required for all systems which support text display on bitmapped output devices. The standard font (named ‘system’) is a fixed pitch font, where all characters are either narrow (8x19) or wide (16x19). UEFI also allows for display of other fonts, both fixed-pitch and variable-pitch. Platform support for these fonts is optional.

UEFI fonts are described using either the Simplified Font Package (`Simplified Font Package`) or the normal Font Package (`Font Package`).

33.2. Design Discussion
33.2.7.1 Font Attributes

Fonts have the following attributes:

**Font Name** — The font name describes, in broad terms, the visual style of the font. For example, “Arial” or “Times New Roman” The standard font always has the name “sysdefault”.

**Font Size** — The font size describes the maximum height of the character cell, in p** — s. The standard font always has the font size of 19.

**Font Style** — The font style describes standard visual modifies to the base visual style of a font. Supported font styles include: bold, italic, underline, double-underline, embossed, outline and shadowed. Some font styles may also be simulated by the font rendering engine. The standard font always has no additional font styles.

33.2.7.2 Limiting Glyphs

Strings in the UEFI environment can be presented in environments with very different limitations. The most constrained environment is in the firmware phases prior to discovery of a boot device with a system partition. The main limitation in this environment is storage space. If unexpected strings could be displayed before system partition availability, the UEFI environment would have to store glyphs for all characters in a Unicode font. After system partition discovery, all glyphs could be made available.

Careful user interface design can limit to a manageable number, the quantity of unexpected characters that the system could be called on to display. Knowing what strings the firmware is going to display limits the number of glyphs it is required to carry.

In addition, carefully designed firmware can support a system where a limited number of strings are displayed before system partition availability. This may be done while enabling the input and display of large numbers of characters/glyphs using a full font file stored on the system partition. In such a situation, the designer must ensure that enough information can be displayed. The designer must also insure that the configuration can be changed using only information from firmware-based non-volatile storage to obtain access to a satisfactory system partition.

UEFI requires platform support of a font containing the basic Latin character set.

While the system firmware will carry this standard font, there might be times when a UEFI application or driver requires the printing of a character not contained within the platform firmware. In this case, a UEFI driver or application can carry this font data and add it to the font already present in the HII Database. New font glyphs are accepted when there is no font glyph definition for the Unicode character already in the specified font.

In addition the standard system font and fonts extended by UEFI applications or drivers, it is possible for drivers that implement the EFI HII Font Glyph Generator Protocol to render additional font glyphs with specific font name, style, and size information, and add the new font packages to the HII Database. That is when HII Font Ex searches the glyph block in the existing HII font packages, it will try to locate `EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL` protocol for generating the corresponding glyph block and inserting the new glyph block into HII font package if the glyph block information is not exist in any HII font package. The HII font package which the new glyph block inserted can be an existing HII font package or a new HII font package created by HII Font Ex according to the `EFI_FONT_DISPLAY_INFO` of character.

The figure below shows how fonts interact with the HII database and UEFI drivers, even if the font does not already exist in the database.
Fig. 33.18: Fonts
33.2.7.3 Fixed Font Description

To allow a UEFI application or driver to extend the existing fonts with additional characters, the UEFI driver must be able to provide characters that fit aesthetically with the system font. For this reason the capability to define attributes of different fonts and to suggest a reasonable default target for these parameters is important.

Fonts can vary in width, style, baseline, height, size, and so on. The fixed font definition includes white space and the glyph data, as well as the positioning of the glyph data. This prevents characters of different fixed fonts from being adjusted at runtime to fit aesthetically together. To provide UEFI drivers with a basic description of how to design fixed font characters, a subset of industry standard font terms are defined below:

- **baseline** — The distance from upper left corner of cell to the base of the Caps (A, B, C, . . .)
- **cap_height** — The distance from the base of the Caps to the top of the Caps
- **x_height** — The distance from the baseline to the top of the lower case ‘x’
- **descender** — The distance some characters extended below the baseline (g, j, p, q, y)
- **ascender** — The distance from the top of the lower case ‘x’ to the tall lower case characters (b, d, f, h, k, l)

The following figure illustrates the font description terms:

![Fig. 33.19: Font Description Terms](image)

This 8x19 system font example (above), follows the original VGA 8x16 definition and creating double wide vertical lines, giving a bold look to the font (style = bold). Along with matching the 8x19 base system font, if a UEFI driver wants to extend the DBCS (Double Byte Character Set) font, it must be aware of the parameters that describe the 16x19 font, as shown below.

This 16x19 font example (above) has a style of plain (single width vertical lines) instead of bold like the 8x19 font, since there is not enough horizontal resolution to cleanly define the DBCS glyphs. The 16x19 ASCII characters have also been designed in a style matching the DBCS characters, allowing them to fit aesthetically together. Note that the default 16x19 fixed width characters are not stored like 1-bit images, one row after another; but instead stored with the left column (19 bytes) first, followed by the right column (19 bytes) of character data. The figure below shows how the characters of the previous figure would be laid out in the font structure.
Fig. 33.20: 16 x 19 Font Parameters

Fig. 33.21: Font Structure Layout
33.2.7.3.1 System Fixed Font Design Guidelines

To allow a UEFI application or driver to extend the fixed font character set, the UEFI system fonts must adhere, at least roughly, to the design guidelines in the table below:

<table>
<thead>
<tr>
<th>Term</th>
<th>8 x 19 Font</th>
<th>16 x 19 Font</th>
</tr>
</thead>
<tbody>
<tr>
<td>baseline</td>
<td>15 pixels</td>
<td>14 pixels</td>
</tr>
<tr>
<td>cap_height</td>
<td>12 pixels</td>
<td>11 pixels</td>
</tr>
<tr>
<td>x_height</td>
<td>8 pixels</td>
<td>7 pixels</td>
</tr>
<tr>
<td>descender</td>
<td>3 pixels</td>
<td>4 pixels</td>
</tr>
<tr>
<td>ascender</td>
<td>4 pixels</td>
<td>4 pixels</td>
</tr>
</tbody>
</table>

In the table above lists the terms in priority order. The most critical guideline to match is the baseline, followed by cap_height and x_height. The terms descender and ascender are not as critical to the aesthetic look of the font as are the other terms. These font design parameters are only guidelines. Failing to match them will not prevent reasonable operation of a UEFI driver that attempting to extend the system font.

33.2.7.4 Proportional Fonts Description

Unlike the fixed fonts, proportional fonts do not have a predefined character cell; instead the character cell is created based on the characters that are being displayed in the current line. In a proportional font only the glyph data is defined, no whitespace. Instead, the proportional font defines five parameters (Width, Height, Offset_X, Offset_Y, & Advance), which allow the glyph data to be position in the character cell and calculate the origin of the next character.

In the figure below, you can see these parameters (in ‘[…]’) for the characters shown, in addition you can see the actual byte storage (the padding to the nearest byte is shown shaded).

![Proportional Font Parameters and Byte Padding](image)

Fig. 33.22: Proportional Font Parameters and Byte Padding

To determine font baseline, scan all font glyphs calculating sum of Height and Offset_Y for each glyph. The largest value of the sum defines location of the baseline.

The font line height is calculated by adding baseline with the largest by absolute value negative Offset_Y among all the font glyphs.
33.2.7.4.1 Aligning Glyphs to the Baseline

To display a line of proportional glyphs, baseline and line height have to be determined. If all the characters to be displayed are from the same font, the baseline and line height are the baseline and line height of the font.

If the characters being displayed are from different fonts, scan glyphs of the characters to be displayed calculating sum of Height and Offset_Y for each glyph. The largest value of the sum defines location of the baseline.

The line height is calculated by adding baseline with the largest by absolute value negative Offset_Y among all the characters to be displayed.

As shown in the following figure, once the baseline value is found it is added to the starting position of the line to calculate the Origin. From the Origin, each and every glyph can be generated based on the individual glyph parameters, including the calculation of the next glyph’s Origin.

![Fig. 33.23: Aligning Glyphs](image)

The starting position (upper left hand corner) of the glyph is defined by (Origin_X + Offset_X), (Origin_Y - (Offset_Y + Height)). The Origin of the next glyph is defined by (Origin_X + Advance), (Origin_Y).

In addition to determining the line height and baseline values; the scan of the characters also calculates the line width by totaling up all of the advance values.

33.2.7.4.2 Proportional Font Design Guidelines

This method of aligning glyphs to a baseline allows one to place wildly different characters correctly position on a single line. However there still is a need for the system proportional fonts to roughly adhere to overall font height (19 pixels high character cells) and the placement of the baseline at the bottom of the Caps (if applicable or about 5 pixels up from the bottom of the character cell). These guidelines are not as critical as the fixed font guidelines, since the character cell height are defined at runtime, based on what else is displayed with that character.

33.2.8 Images

The format of the images to be stored in the Human Interface Infrastructure (HII) database have been created to conform to the industry standard 1-bit, 4-bit, 8-bit, and 24-bit video memory layouts. The 24-bit and 32-bit display systems have the exact same display capabilities and the exact same pixel definition. The difference is that the 32-bit pixels are DWORD aligned for improve CPU efficiency when accessing video memory. The extra byte that is inserted from the 24-bit and the 32-bit layout has no bearing on the actual screen.

Video memory is arranged left-to-right, and then top-to-bottom. In a 1-bit or monochrome display, the most significant bit of the first byte defines the screen’s upper left most pixel. In a 4-bit or 16 color, display the most significant nibble of the first byte defines the screen’s upper left most pixel. In a 8-bit or 256 color display, the first byte defines the screen’s upper left most pixel.
In both the 24-bit and 32-bit TrueColor displays, the first three bytes defines the screen’s upper left most pixel. The first byte is the pixel’s blue component value, the next byte is the pixel’s green component value, and the third byte is the pixel’s red component value (B,G,R). Each color component value can vary from 0x00 (color off) to 0xFF (color full on), allowing 16.8 millions colors that can be specified. In the 32-bit TrueColor display modes, the fourth byte is a don’t care.

33.2.8.1 Converting to a 32-bit Display

The UEFI recommended video mode for computer-like devices uses a 32-bit Linear Frame Buffer video mode. All images stored in the HII database will need conversion to 32-bit before display.

To display a 24-bit image into 32-bit video memory, a pixel of the image is retrieved (read DWORD value advance pixel offset by 3) and then written to the video memory (write DWORD value advance pixel offset by 4).

To display any of the non-TrueColor images (1-bit, 4-bit, and 8-bit), there is an extra step of indirection through the palette definition to get the TrueColor pixel value. First retrieve the palette index value by isolating the corresponding bits, then index into the associated palette to retrieve the 24-bit (B,G,R) color entry (read DWORD value), then write it to the video memory (write DWORD value advance pixel offset by 4). For this reason, the palette color entry definition is defined exactly the same as the image color pixel (B,G,R).

33.2.8.2 Non-TrueColor Displays

It is possible to display the HII database images on non-TrueColor video modes. You cannot however, display images beyond the bit depth of the target screen resolution. For example you would be able to display 1-bit, 4-bit, and 8-bit images in a 256 color video mode. To do this you must create a global palette (256 entries), by merging all images color needs to a best fit palette and then programming the hardware palette with that data.

The hardware palette color definition (R,G,B) is backwards from the screen pixel definition (B,G,R), and will have to be swapped before programming. In addition, the hardware palette may only support 6-bit of magnitude per color component instead of the 8-bit defined in the palette information section; therefore the values will have to be shifted before writing.

33.2.9 HII Database

The Human Interface Infrastructure (HII) database is the resource that serves as the repository of all the form, string, image and font data for the system. Drivers that contain information that is appropriate for the database will export this data to the HII database.

For example, one driver might contain all the motherboard-specific data (the traditional “Setup” for the system). Additionally, add-in cards may contain their own drivers, which, in turn, have their own Setup-related data. All of the drivers that contain Setup-related data would export their information to the HII database, as shown in the figure below.

33.2.10 Forms Browser

The UEFI Forms Browser is the service that reads the contents of the HII Database and interprets the forms data in order to present it to the user. For example, the Forms Browser can be used to gather all setup-related data and presents it to the user. This service also takes the user input and allows for changes to be saved into non-volatile storage.

The figure below shows the relationship between the HII database, UEFI drivers, and the UEFI Forms Browser.
Fig. 33.24: HII Database

Fig. 33.25: Setup Browser
33.2.10.1 User Interaction

The Forms Browser implementer has great flexibility as to the type of actual user interface provided. For example, while required to support some forms of navigation (EFI_FORM_BROWSER2_PROTOCOL.SendForm) or the cross-reference question), it may optionally support additional navigation capabilities, such as a back button or a menu bar. This section describes the rules to which the Forms Browser user-interaction must conform.

33.2.10.1.1 Forms Browser Details

The forms browser maintains a collection of one or more forms. The forms browser is required to provide navigation for these forms if there is more than one (EFI_FORM_BROWSER2_PROTOCOL, “Form Browser Protocol”).

The forms browser maintains one or more active forms. An active form is any form where the forms browser is maintaining a set of question values. A form is considered active after all question values have been read from storage and the* EFI_BROWSER_ACTION_FORM_OPEN action has been sent to all questions on the form which require callback. A form is considered inactive after all question values have been either discarded or written to storage and the EFI_BROWSER_ACTION_FORM_CLOSE action has been sent to all questions on the form which require callback.

The forms browser maintains a selected form. The selected form contains the selected question and indicates the primary area of user interaction.

The standards form navigation behaviors are:

Navigate Forms. — When the user chooses this required behavior, a new form is selected and, if any questions on the form are selectable (Evaluation of Selectable Statements), a question is selected. Forms browsers are required to provide navigation to (at least) the first form in all form sets when FormId is zero (Form Browser Protocol). This behavior cannot be selected if the current form is modal (Forms).

Exit Browser/Discard All. — When the user chooses this optional behavior, the question values for active forms are discarded, the active forms are deactivated and the forms browser exits with an action request of EFI_BROWSER_ACTION_REQUEST_EXIT. This behavior cannot be selected if the current form is modal (Forms).

Exit Browser/Submit All. — When the user chooses optional behavior, the question values are written to storage, the active forms are deactivated and the forms browser exits with an action request of EFI_BROWSER_ACTION_REQUEST_SUBMIT or EFI_BROWSER_ACTION_REQUEST_RESET. This behavior cannot be selected if the current form is modal (Forms).

Default. — When the user chooses this optional behavior, the current question values for the questions on the focus form are updated from one of the default stores and then the EFI_IFR_BROWSER_ACTION_REQUEST_DEFAULT_x action is sent for each of the questions with the Callback attribute. This behavior can be initiated by a Reset Button question (Reset Button).

33.2.10.1.2 Selected Form

When a form is made active, the forms browser sends the EFI_BROWSER_ACTION_FORM_OPEN for all questions supporting callback, retrieves the current question values, saves those as the original question values and begins refreshing any questions that support it.

The forms browser maintains a current question value for each question on active forms. The current question value is the last value that the forms browser read from storage/callback (Values) or the last value committed by the user. The form is considered modified if any of the current question values are modified (see Questions, below). The forms browser refreshes the current question values of at least questions on the selected with a non-zero refresh interval.
The forms browser maintains a selected question on the selected form. The selected question is the primary focus of the user’s interaction. When a form is selected, the forms browser must choose a selectable question (Evaluation of Selectable Statements, “Evaluation of Selectable Statements”) as the selected question, if one is present on the form.

The standard active form behaviors are:

**Exit Browser/Discard All.** — When the user chooses this required behavior, the question values for active forms are discarded, the active forms are deactivated and the forms browser exits with an action request of EFI_BROWSER_ACTION_REQUEST_EXIT. This behavior can be initiated by the function associated with a question with the Callback attribute.

**Exit Browser/Submit All.** — When the user chooses this required behavior, the current question values for active forms are validated (see nosubmitif, EFI_IFR_NOT_EQUAL) and, if successful, question values for active forms are written to storage, the active forms are deactivated and the forms browser exits with an action request of EFI_BROWSER_ACTION_REQUEST_SUBMIT. This behavior can be initiated by the function associated with a question with the Callback attribute.

**Exit Browser/Discard All/Reset Platform.** — When the user chooses this required behavior, the question values for active forms are discarded, the active forms are deactivated and the forms browser exits with an action request of EFI_BROWSER_ACTION_REQUEST_RESET. This behavior can be initiated by the function associated with a question with the Callback attribute.

**Exit Form/Submit Form.** — Apply Form. When the user chooses this required behavior, the question values for the selected form are validated (see nosubmitif, BUGBUG) and, if successful, question values for the selected form are written to storage and the selected form is deselected. This behavior can be initiated by the function associated with a question with the Callback attribute.

**Exit Form/Discard Form.** — When the user chooses this required behavior, the question values for the selected form are discarded and the selected form is deselected. This behavior can be initiated by the function associated with a question with the Callback attribute.

**Apply Form.** — When the user chooses this required behavior, the question values for the selected form are validated (see nosubmitif, BUGBUG) and, if successful, question values for the selected form are written to storage. This behavior can be initiated by the function associated with a question with the Callback attribute.

**Discard Form.** — When the user chooses this required behavior, the question values for the selected form are discarded. This behavior can be initiated by the function associated with a question with the Callback attribute.

**Default.** — When the user chooses this required behavior, the current question values for the questions on the selected form are updated from a default store. This behavior can be initiated by a Reset Button question (see Reset Button).

**Navigate To Question.** — When the user chooses this required behavior, the selected question is deselected and another question on the same form is selected. The types of navigation provided between questions on the same form are beyond the scope of this specification.

**Navigate To Form.** — When the user chooses this required behavior, the selected form is deselected and the form specified by the question is selected. This behavior can be initiated by a Cross-Reference question. Note that this behavior is distinct from the Navigate Forms behavior described in Forms Navigation.

From these basic behaviors, more complex behaviors can be constructed. For example, a forms browser might check whether the form is modified and, if so, prompt the user to select between the Exit Browser/Discard All and Exit Browser/Submit All behaviors.
### 33.2.10.1.3 Selected Question

When the user navigates to a question or the forms browser selects a form with a selectable question, the forms browser places the question in the static state. When the user is choosing another question values for the selected question (by typing or from a menu or other means), the forms browser places the question in the changing state. When the user finalizes selection of a question value the forms browser returns the question to the static state.

The forms browser refreshes all questions in at least the selected form with a non-zero refresh interval that are not modified. Typically, a forms browser will not update the displayed question value while the selected question is in the changing state, but will when the selected question is in the static state. A question is considered modified if there is storage associated with the question (i.e., a variable store was specified) and the current question value is different from the original question value.

The standard active question behaviors are:

- **Change** — When the user chooses this required behavior, the forms browser places the selected question in the changing state and allows the user to specify a new current question value for the active question. For example, selecting items in a drop box or beginning to type a new value in an edit box.

  With some question types and user interface styles, this behavior is hidden from the user. For example, with check boxes or radio buttons as found in most windowed user-interfaces, the user changes and commits the value with one action. Likewise, with action buttons, selecting the action button implies both the question value and the commit action.

  This behavior corresponds to the CHANGING browser action request for questions that support callback.

- **Commit** — When the user chooses this required behavior, the forms browser validates the specified question value (see `EFI_IPF_INCONSISTENT_IF`, `EFI_IFR_INCONSISTENT_IF`) and, if successful, places the selected question in the static state and updates the current question value to that specified while in the changing state. If the selected question’s current question value is different than the selected question’s original question value, the selected question is considered modified. The form browser must then re-evaluate the modifiability, selectability and visibility of other questions in the selected form.

  This behavior corresponds to the CHANGED browser action request for questions that support callback.

- **Discard** — When the user chooses this required behavior, the forms browser places the question in the changed state.

### 33.2.11 Configuration Settings

In order to save user changes to configuration settings after the system reset or power-off, there must be some form of non-volatile storage available. There are two types of non-volatile storage: system non-volatile storage or add-in card non-volatile storage. Both types are supported.

In general, settings are not saved to non-volatile storage until the user specifically directs the Forms Browser to do so. There are exceptions, such as when operating in a batch or script mode, setting a system password, and updating the system date and time. The underlying platform support dictates whether or not hardware configuration changes are committed immediately.

As shown in the figure below, when a system reset occurs, the firmware’s initialization routines will launch the UEFI drivers (e.g., option ROMs). Drivers enabled to take direction from a non-volatile setting read the updated settings during their initialization.
Fig. 33.26: Storing Configuration Settings
33.2.11.1 OS Runtime Utilization

Due to the static nature of the data that is contained in the HII Database and the fact that certain classes of non-volatile storage can be updated during OS run-time, it is possible for an application running under an OS to read the HII information, make configuration changes and even make changes.

The figure below shows how an OS makes use of the HII database during runtime. In this case, the contents of the HII Database is exported to a buffer. The pointer to the buffer is placed in the EFI System Configuration Table, where it can be retrieved by an OS application.

![Diagram of OS Runtime Utilization](image)

The process used to allow an OS application to use this is as follows:

Drivers/applications in the system register user interface data into the HII Database

When the platform transitions from pre-boot to runtime phases of operation, the HII `ExportPackageLists()` is called to export the contents of the HII Database into a runtime buffer.

This runtime buffer is advertised in the UEFI Configuration Table using the HII Database Protocol’s GUID so that an OS application can find the data.

The HII `ExportConfig()` is called to export the current configuration into a runtime buffer.

This runtime buffer is advertised in the UEFI Configuration Table using the HII Configuration Routing Protocol’s GUID so that an OS application can find the data.

When an O/S application wants to display pre-boot configuration content, it searches the UEFI Configuration Table for the HII Database Protocol’s GUID entry and renders the contents from the runtime buffer which it points to.

If the OS application needs to update the system configuration, the configuration information can be updated.

For those configuration settings which are stored in UEFI variables (i.e., using `GetVariable()` and `SetVariable()`), the application can update these using the abstraction provided by the operating system.

For those configuration settings which are not stored in UEFI variables, the OS application can use the UEFI Update-Capsule runtime service to change the configuration.
33.2.11.2 Working with a UEFI Configuration Language

By defining the concept of a language that may provide hints to a consumer that the string payload may contain pre-defined standard keyword content, the user of this solution can export their configuration data for evaluation. This evaluation enables the consumer to determine if a particular platform supports a given configuration language, and in-turn be able to adjust known settings that are stored in a platform-specific manner. An example of this is illustrated below which uses various component described in this and the other HII chapters of this specification. In the example, a fictional technology called XYZ exists, and this particular platform supports it. The question is, how does a standard application which is not privy to the platform’s construction know how this setting is stored? To-date, this is not a reasonably solvable problem, but in the illustration below, this example shows how one might go about solving this issue.

![Standard Application Obtaining Setting Example](image)

Fig. 33.28: Standard Application Obtaining Setting Example

33.2.12 Form Callback Logic

Since it has been the design intent that the forms processor not need to understand the underlying hardware implementations or design paradigms of the platform, there were certain needs that could only be met by calling a more platform knowledgeable component. In this case, the component would typically be associated with some hardware device (e.g. motherboard, add-in card, etc.). To facilitate this interaction, some formal interfaces were declared for more platform-specific components to advertise and the forms processor could then call.

Note that the need for the forms processor to call into an alternate component driver should be limited as much as possible. The two primary reasons for this are the cases where off-line or O/S-present configuration is important. The three flow charts which follow describe the typical decisions that a forms processor would make with regards to handling processes which necessitate a callback.
Fig. 33.29: Typical Forms Processor Decisions Necessitating a Callback (1)

33.2. Design Discussion
Fig. 33.30: **Typical Forms Processor Decisions Necessitating a Callback (2)**
Fig. 33.31: Typical Forms Processor Decisions Necessitating a Callback (3)
33.2.13 Driver Model Interaction

The ability for a UEFI driver to interact with a target controller is abstracted through the Configuration Access Protocol. If a particular piece of hardware managed by a controller needs configuration services, it is the responsibility of that controller to provide this configuration abstraction for the given device. Regardless of whether a device driver or bus driver is abstracting the hardware configuration, the interaction with a configured device is identical.

Note that the ability for a driver to provide these access protocols might be done fairly early in the initialization process. Depending on the hardware capabilities, one might be advantaged in providing configuration access very early so that being able to determine a given device’s current settings can be done without a full enumeration of certain bus devices. Also note that the same recommendations that are made in the DriverBinding sections should still be maintained. These cover the Supported, Started, and Stopped functions.

![Fig. 33.32: Driver Model Interactions](image)

33.2.14 Human Interface Component Interactions

The figure below depicts the model used inside a common deployment of HII to manage human interface components.
33.2.15 Standards Map Forms

Configuration settings are configuration settings. But the way in which they are controlled is driven by different requirements. For example, the UEFI HII infrastructure focuses primarily on the way in which the configuration settings can be browsed and manipulated by a user. Other standards such as the DMTF Command-Line Protocol, focus on the way in which configuration settings can be manipulated via text commands.

Each configuration method tends to view the configuration settings a different way. In the end, they are changing the same configuration setting, but their means of exposing the control differs. The means by which a configuration method (HII, DMTF, WMI, SNMP, etc.) exposes an individual configuration setting is called a question.

In many cases, there is a one-to-one mapping between the questions exposed by these different configuration methods. That is, a question, as exposed by one configuration method matches the semantic meaning of the configuration setting exactly.

However, in other cases, there is not a one-to-one mapping. These cases break down into three broad categories:

1. Value Shift. In this case, the configuration setting has the same scope as the question exposed by a configuration method, but the values used to describe them are different. It may be as simple as 1=5, 2=6, 3=7, etc. or something more complicated, where “ON”=1 and “OFF”=0.

2. One-To-Many. In this case, the configuration setting maps to two or more questions exposed by a configuration method. For example the configuration setting might have the following enumerated values:

   a. 0 = Disable Serial Port
   b. 1 = Enable Serial Port, I/O Port 0x3F8, IRQ 4
   c. 2 = Enable Serial Port, I/O Port 0x2F8, IRQ 3
   d. 3 = Enable Serial Port, I/O Port 0x3E8, IRQ 4
But in the configuration method, the serial port is controlled by three separate questions:

- Question #1: 0 = disable, 1 = enable
- Question #2: I/O Port (disabled if Question #1 = 0)
- Question #3: IRQ (disabled if Question #1 = 0)

Changing the configuration method question #1 to a value of 0 requires that the configuration setting be set to 0. In this case, there is the possibly of data loss. After changing the configuration setting to 0, the information about the I/O port and IRQ are not preserved.

So, in order to change the configuration setting to the value of 1 would require three of the configuration method’s questions to change value: Question #1=1, Question #2=0x3F8, Question #3=IRQ 4.

---

3. Many-To-One. In this case, the conditions are reversed from the example described in #2 above. Now there are three configuration settings which map to a single configuration method question.

For example, the configuration settings are described using three separate questions:

a. Question #1: 0 = disable, 1 = enable
b. Question #2: I/O Port (disabled if Question #1 = 0)
c. Question #3: IRQ (disabled if Question #1 = 0).

But in the configuration method, the serial port is controlled by a single question with the following enumerated values:
a. 0 = Disable Serial Port
b. 1 = Enable Serial Port, I/O Port 0x3F8, IRQ 4
c. 2 = Enable Serial Port, I/O Port 0x2F8, IRQ 3
d. 3 = Enable Serial Port, I/O Port 0x3E8, IRQ 4
e. 4 = Enable Serial Port, I/O Port 0x2E8, IRQ 3

So, in order to change the configuration method to the value of 1 would require three configuration settings to change value: Question #1=1, Question #2=0x3F8, Question #3=IRQ 4.

Fig. 33.35: EFI IFR Form Set Question Changes

Some configuration settings may involve more than one of these mappings.

Standards map forms describe the questions exposed by these other configuration methods and how they map back to the configuration settings exposed by the UEFI drivers. Each standards map form describes the mapping for a single configuration method, along with that configuration method’s name and version.

The questions within standards map forms are encoded using IFR in the same fashion as those within other UEFI forms. The prompt strings for these questions are tied back to the names for those questions within the configuration method (e.g., DMTF CLP).
33.2.15.1 Create A Question’s Value By Combining Multiple Configuration Settings

Rather than reading directly from storage, these standards map questions retrieve their value using the `EFI_IFR_READ (EFI_IFR_Read)` operator. This operator can aggregate a value from more than one configuration settings using `EFI_IFR_GET (EFI_IFR_Get)`. This operator can also change the type (integer, string, Boolean) of the value so that, say, a configuration setting with a type of integer can be represented in a standards map form as a string.

For example, to map a single question to three configuration settings (CS1, CS2 and CS3) as described in scenario #3 in *Strings*, above would have the following truth table:

<table>
<thead>
<tr>
<th>CS1</th>
<th>CS2</th>
<th>CS3</th>
<th>Q</th>
</tr>
</thead>
<tbody>
<tr>
<td>FALSE</td>
<td>X</td>
<td>X</td>
<td>0</td>
</tr>
<tr>
<td>TRUE</td>
<td>0x3F8</td>
<td>4</td>
<td>1</td>
</tr>
<tr>
<td>TRUE</td>
<td>0x2F8</td>
<td>3</td>
<td>2</td>
</tr>
<tr>
<td>TRUE</td>
<td>0x3E8</td>
<td>4</td>
<td>3</td>
</tr>
<tr>
<td>TRUE</td>
<td>0x2E8</td>
<td>3</td>
<td>4</td>
</tr>
<tr>
<td>TRUE</td>
<td>any other value</td>
<td>any other value</td>
<td>Undefined</td>
</tr>
</tbody>
</table>

These become the following equations:

\[
\begin{align*}
    x0 & : \text{Get (CS1)} \ ? \ x1 \ : \ 0 \\
    x1 & : ((\text{Get(CS2)} \ & \ 0xF00) \ >> \ 8) \ == \ \text{Get(CS3)} \ + \ 1 \ ? \ x2 \ : \ \text{Undefined} \\
    x2 & : \text{Map(Get(CS2),0x3f8,1,0x2F8,2,0x3E8,3,0x2E8,4)}
\end{align*}
\]

33.2.15.2 Changing Multiple Configuration Settings From One Question’s Value

Rather than writing directly to storage, these standards map questions change their value using the `EFI_IFR_WRITE (EFI_IFR_Write)` operator. This operator can, in turn, use the `EFI_IFR_SET (EFI_IFR_Set)` operator to change one or more configuration settings. This operator can also change the type (integer, string, Boolean, etc.) of the value written so that, say, a configuration setting with a type of integer can be represented in a standards map form as a string question.

For example, in example #2 above, the following table applies:

<table>
<thead>
<tr>
<th>CS1</th>
<th>CS2</th>
<th>CS3</th>
<th>Q</th>
</tr>
</thead>
<tbody>
<tr>
<td>FALSE</td>
<td>X</td>
<td>X</td>
<td>0</td>
</tr>
<tr>
<td>TRUE</td>
<td>0x3F8</td>
<td>4</td>
<td>1</td>
</tr>
<tr>
<td>TRUE</td>
<td>0x2F8</td>
<td>3</td>
<td>2</td>
</tr>
<tr>
<td>TRUE</td>
<td>0x3E8</td>
<td>4</td>
<td>3</td>
</tr>
<tr>
<td>TRUE</td>
<td>0x2E8</td>
<td>3</td>
<td>4</td>
</tr>
</tbody>
</table>

\[
\begin{align*}
    \text{Set (CS1,Q != 0) &&} \\
    \text{Set (CS2,Map(this,1,0x3F8,2,0x3E8,3,0x2F8,4,0x2E8)) &&} \\
    \text{Set (CS3,Map(this,1,4,2,3,3,4,4,3)}
\end{align*}
\]
33.2.15.3 Value Shifting

Value shifting is facilitated by the EFI_IFR_MAP (EFI_IFR_Map) operator. If this operator finds a value in a list, it replaces it with another value from the list, even if the other value is a different type.

For example, consider the following list of values

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>PEI Module</td>
</tr>
<tr>
<td>2</td>
<td>DXE Boot Service Driver</td>
</tr>
<tr>
<td>3</td>
<td>DXE Runtime Driver</td>
</tr>
<tr>
<td>10</td>
<td>UEFI Boot Service Driver</td>
</tr>
<tr>
<td>11</td>
<td>UEFI Runtime Driver</td>
</tr>
<tr>
<td>12</td>
<td>UEFI Application</td>
</tr>
</tbody>
</table>

If the integer value 10 were supplied, the value “UEFI Boot Service Driver” would be returned. If the integer value 20 were supplied, Undefined would be returned.

33.2.15.4 Prompts

In standards map forms, the prompts can be used as the key words for the configuration method. They should be specified in the language i-uefi unless there are multiple translations available. Other standards may use the question identifiers as the means of identifying the standard question.

33.3 Code Definitions

This section describes the binary encoding of the different package types:

- Font Package
- Simplified Font Package
- String Package
- Image Package
- Device Path Package
- Keyboard Layout Package
- GUID Package
- Forms Package

33.3.1 Package Lists and Package Headers

33.3.1.1 EFI_HII_PACKAGE_HEADER

Summary
The header found at the start of each package.

Prototype
typedef struct {
    UINT32 Length:24;
    UINT32 Type:8;
    UINT8 Data[... ];
} EFI_HII_PACKAGE_HEADER;

Members

Length
The size of the package in bytes.

Type
The package type. See EFI_HII_PACKAGE_TYPE_x, below.

Data
The package data, the format of which is determined by Type.

Description
Each package starts with a header, as defined above, which indicates the size and type of the package. When added to a pointer pointing to the start of the header, Length points at the next package. The package lists form a package list when concatenated together and terminated with an EFI_HII_PACKAGE_HEADER with a Type of EFI_HII_PACKAGE_END.

The type EFI_HII_PACKAGE_TYPE_GUID is used for vendor-defined HII packages, whose contents are determined by the Guid.

The range of package types starting with EFI_HII_PACKAGE_TYPE_SYSTEM_BEGIN through EFI_HII_PACKAGE_TYPE_SYSTEM_END are reserved for system firmware implementers.

Related Definitions

#define EFI_HII_PACKAGE_TYPE_ALL 0x00
#define EFI_HII_PACKAGE_TYPE_GUID 0x01
#define EFI_HII_PACKAGE_FORMS 0x02
#define EFI_HII_PACKAGE_STRINGS 0x04
#define EFI_HII_PACKAGE_FONTS 0x05
#define EFI_HII_PACKAGE_IMAGES 0x06
#define EFI_HII_PACKAGE_SIMPLE_FONTS 0x07
#define EFI_HII_PACKAGE_DEVICE_PATH 0x08
#define EFI_HII_PACKAGE_KEYBOARD_LAYOUT 0x09
#define EFI_HII_PACKAGE_ANIMATIONS 0x0A
#define EFI_HII_PACKAGE_END 0xDF
#define EFI_HII_PACKAGE_TYPE_SYSTEM_BEGIN 0xE0
#define EFI_HII_PACKAGE_TYPE_SYSTEM_END 0xFF

Table 33.15: Package Types

<table>
<thead>
<tr>
<th>Package Type</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_HII_PACKAGE_TYPE_ALL</td>
<td>Pseudo-package type used when exporting package lists. See ExportPackageList().</td>
</tr>
<tr>
<td>EFI_HII_PACKAGE_TYPE_GUID</td>
<td>Package type where the format of the data is specified using a GUID immediately following the package header.</td>
</tr>
<tr>
<td>EFI_HII_PACKAGE_FORMS</td>
<td>Forms package.</td>
</tr>
<tr>
<td>EFI_HII_PACKAGE_STRINGS</td>
<td>Strings package</td>
</tr>
<tr>
<td>EFI_HII_PACKAGE_FONTS</td>
<td>Fonts package.</td>
</tr>
</tbody>
</table>

continues on next page
Table 33.15 – continued from previous page

<table>
<thead>
<tr>
<th>EFI_HII_PACKAGE_IMAGES</th>
<th>Images package.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_HII_PACKAGE_SIMPLE_FONTS</td>
<td>Simplified (8x19, 16x19) Fonts package</td>
</tr>
<tr>
<td>EFI_HII_PACKAGE_DEVICE_PATH</td>
<td>Binary-encoded device path.</td>
</tr>
<tr>
<td>EFI_HII_PACKAGE_END</td>
<td>Used to mark the end of a package list.</td>
</tr>
<tr>
<td>EFI_HII_PACKAGE_ANIMATIONS</td>
<td>Animations package.</td>
</tr>
<tr>
<td>EFI_HII_PACKAGE_TYPE_SYSTEM_BEGIN...</td>
<td></td>
</tr>
<tr>
<td></td>
<td>Package types reserved for use by platform firmware imple-</td>
</tr>
<tr>
<td></td>
<td>mentsations.</td>
</tr>
</tbody>
</table>

33.3.1.2 EFI_HII_PACKAGE_LIST_HEADER

Summary
The header found at the start of each package list.

Prototype

```c
typedef struct {
    EFI_GUID PackageListGuid;
    UINT32 PackageLength;
} EFI_HII_PACKAGE_LIST_HEADER;
```

Members

PackageListGuid
The unique identifier applied to the list of packages which follows.

PackageLength
The size of the package list (in bytes), including the header.

Description
This header uniquely identifies the package list and is placed in front of a list of packages. Package lists with the same PackageListGuid value should contain the same data set. Updated versions should have updated GUIDs.

33.3.2 Simplified Font Package

The simplified font package describes the font glyphs for the standard 8x19 pixel (narrow) and 16x19 (wide) fonts. Other fonts should be described using the normal Font Package.

A simplified font package consists of a header and two types of glyph structures–standard-width (narrow) and wide glyphs.

33.3.2.1 EFI_HII_SIMPLE_FONT_PACKAGE_HDR

Summary
A simplified font package consists of a font header followed by a series of glyph structures.

Prototype
typedef struct _EFI_HII_SIMPLE_FONT_PACKAGE_HDR {
    EFI_HII_PACKAGE_HEADER Header;
    UINT16 NumberOfNarrowGlyphs;
    UINT16 NumberOfWideGlyphs;
    EFI_NARROW_GLYPH NarrowGlyphs[];
    EFI_WIDE_GLYPH WideGlyphs[];
} EFI_HII_SIMPLE_FONT_PACKAGE_HDR;

Members

Header
The header contains a Length and Type field. In the case of a font package, the type will be EFI_HII_PACKAGE_SIMPLE_FONTS and the length will be the total size of the font package including the size of the narrow and wide glyphs. See EFI_HII_PACKAGE_HEADER.

NumberOfNarrowGlyphs
The number of NarrowGlyphs that are included in the font package.

NumberOfWideGlyphs
The number of WideGlyphs that are included in the font package.

NarrowGlyphs
An array of EFI_NARROW_GLYPH entries. The number of entries is specified by NumberOfNarrowGlyphs.

WideGlyphs
An array of EFI_WIDE_GLYPH entries. The number of entries is specified by NumberOfWideGlyphs. To calculate the offset of WideGlyphs, use the offset of NarrowGlyphs and add the size of EFI_NARROW_GLYPH multiplied by the NumberOfNarrowGlyphs.

Description
The glyphs must be sorted by Unicode character code.

It is up to developers who manage fonts to choose efficient mechanisms for accessing fonts. The contiguous presentation can easily be used because narrow and wide glyphs are not intermixed, so a binary search is possible (hence the requirement that the glyphs be sorted by weight).

33.3.2.2 EFI_NARROW_GLYPH

Summary
The EFI_NARROW_GLYPH has a preferred dimension (w x h) of 8 x 19 pixels.

Prototype
typedef struct {
    CHAR16 UnicodeWeight;
    UINT8 Attributes;
    UINT8 GlyphCol1[EFI_GLYPH_HEIGHT];
} EFI_NARROW_GLYPH;

Members

UnicodeWeight
The Unicode representation of the glyph. The term weight is the technical term for a character code.

Attributes
The data element containing the glyph definitions; see “Related Definitions” below.

33.3. Code Definitions
GlyphCol1
The column major glyph representation of the character. Bits with values of one indicate that the corresponding pixel is to be on when normally displayed; those with zero are off.

Description
Glyphs are represented by two structures, one each for the two sizes of glyphs. The narrow glyph (EFI_NARROW_GLYPH) is the normal glyph used for text display.

Related Definitions
```c
// Contents of EFI_NARROW_GLYPH.Attributes
#define EFI_GLYPH_NON_SPACING 0x01
#define EFI_GLYPH_WIDE 0x02
#define EFI_GLYPH_HEIGHT 19
#define EFI_GLYPH_WIDTH 8
```

Following is a description of the fields in the above definition:

**EFI_GLYPH_NON_SPACING**
This symbol is to be printed “on top of” (OR’d with) the previous glyph before display.

**EFI_GLYPH_WIDE**
This symbol uses 16x19 formats rather than 8x19.

### 33.3.2.3 EFI_WIDE_GLYPH

**Summary**
The EFI_WIDE_GLYPH has a preferred dimension (w x h) of 16 x 19 pixels, which is large enough to accommodate logographic characters.

**Prototype**
```c
typedef struct {
    CHAR16  UnicodeWeight;
    UINT8   Attributes;
    UINT8   GlyphCol1[EFI_GLYPH_HEIGHT];
    UINT8   GlyphCol2[EFI_GLYPH_HEIGHT];
    UINT8   Pad[3];
} EFI_WIDE_GLYPH;
```

**Members**

**UnicodeWeight**
The Unicode representation of the glyph. The term weight is the technical term for a character code.

**Attributes**
The data element containing the glyph definitions; see “Related Definitions” in EFI_NARROW_GLYPH for attribute values.

**GlyphCol1 and GlyphCol2**
The column major glyph representation of the character. Bits with values of one indicate that the corresponding pixel is to be on when normally displayed; those with zero are off.

**Pad**
Ensures that sizeof(EFI_WIDE_GLYPH) is twice the sizeof(EFI_NARROW_GLYPH). The contents of Pad must be zero.
Description

Glyphs are represented via the two structures, one each for the two sizes of glyphs. The wide glyph (EFI_WIDE_GLYPH) is large enough to display logographic characters.

33.3.3 Font Package

The font package describes the glyphs for a single font with a single family, size and style. The package has two parts: a fixed header and the glyph blocks. All structures described here are byte packed.

33.3.3.1 Fixed Header

The fixed header consists of a standard record header and then the character values in this section, the flags (including the encoding method) and the offsets of the glyph information, the glyph bitmaps and the character map.

```c
typedef struct _EFI_HII_FONT_PACKAGE_HDR {
    EFI_HII_PACKAGE_HEADER Header;
    UINT32 HdrSize;
    UINT32 GlyphBlockOffset;
    EFI_HII_GLYPH_INFO Cell;
    EFI_HII_FONTSTYLE FontStyle;
    CHAR16 FontFamily[];
} EFI_HII_FONT_PACKAGE_HDR;
```

**Header**

The standard package header, where `Header.Type = EFI_HII_PACKAGE_FONTS`.

**HdrSize**

Size of this header.

**GlyphBlockOffset**

The offset, relative to the start of this header, of a series of variable-length glyph blocks, each describing information about the bitmap associated with a glyph.

**Cell**

This contains the measurement of the widest and tallest characters in the font (Cell.Width and Cell.Height). It also contains the default offset to the horizontal and vertical origin point of the character cell (Cell.OffsetX and Cell.OffsetY). Finally, it contains the default AdvanceX.

**FontStyle**

The design style of the font, 1 bit per style. See `EFI_HII_FONTSTYLE`.

**FontFamily**

The null-terminated string with the name of the font family to which the font belongs.

Related Definitions

```c
typedef UINT32 EFI_HII_FONTSTYLE;
#define EFI_HII_FONTSTYLE_NORMAL 0x00000000
#define EFI_HII_FONTSTYLE_BOLD 0x00000001
#define EFI_HII_FONTSTYLEItalic 0x00000002
#define EFI_HII_FONTSTYLE_EMBOSs 0x00010000
#define EFI_HII_FONTSTYLE_OUTLINE 0x00020000
#define EFI_HII_FONTSTYLE_SHADOW 0x00040000
#define EFI_HII_FONTSTYLE_UNDERLINE 0x00080000
#define EFI_HII_FONTSTYLE_DBL_UNDER 0x00100000
```
33.3.3.2 Glyph Information

For each Unicode character code, the glyph information gives the glyph bitmap, the character size and the position of the bitmap relative to the origin of the character cell. The glyph information is encoded as a series of blocks, each with a single byte header. The blocks must be processed in order.

Each block begins with a single byte, which contains the block type.

Prototype

typedef struct _EFI_HII_GLYPH_BLOCK {
    UINT8 BlockType;
    UINT8 BlockBody[];
} EFI_HII_GLYPH_BLOCK;

Members

The following table describes the different block types:

<table>
<thead>
<tr>
<th>Name</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_HII_GIBT_END</td>
<td>0x00</td>
<td>The end of the glyph information.</td>
</tr>
<tr>
<td>EFI_HII_GIBT_GLYPH</td>
<td>0x10</td>
<td>Glyph information for a single character value, bit-packed.</td>
</tr>
<tr>
<td>EFI_HII_GIBT_GLYPHS</td>
<td>0x11</td>
<td>Glyph information for multiple character values.</td>
</tr>
<tr>
<td>EFI_HII_GIBT_GLYPH_DEFAULT</td>
<td>0x12</td>
<td>Glyph information for a single character value, using the default character cell information.</td>
</tr>
<tr>
<td>EFI_HII_GIBT_GLYPHS_DEFAULT</td>
<td>0x13</td>
<td>Glyph information for multiple character values, using the default character cell information.</td>
</tr>
<tr>
<td>EFI_HII_GIBT_GLYPH_VARIABILITY</td>
<td>0x14</td>
<td>Glyph information for the _GIBT_GLYPH_VARIABILITY variable glyph.</td>
</tr>
<tr>
<td>EFI_HII_GIBT_DUPLICATE</td>
<td>0x20</td>
<td>Create a duplicate of an existing glyph but with a new character value.</td>
</tr>
<tr>
<td>EFI_HII_GIBT_SKIP2</td>
<td>0x21</td>
<td>Skip a number (1-65535) character values.</td>
</tr>
<tr>
<td>EFI_HII_GIBT_SKIP1</td>
<td>0x22</td>
<td>Skip a number (1-255) character values.</td>
</tr>
<tr>
<td>EFI_HII_GIBT_DEFAULTS</td>
<td>0x23</td>
<td>Set default glyph information for subsequent glyph blocks.</td>
</tr>
<tr>
<td>EFI_HII_GIBT_EXT1</td>
<td>0x30</td>
<td>For future expansion (one byte length field)</td>
</tr>
</tbody>
</table>

continues on next page
Table 33.16 – continued from previous page

<table>
<thead>
<tr>
<th>EFI_HII_GIBT_EXT2</th>
<th>0x31</th>
<th>For future expansion (two byte length field)</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_HII_GIBT_EXT4</td>
<td>0x32</td>
<td>For future expansion (four byte length field)</td>
</tr>
</tbody>
</table>

**Description**

In order to recreate all glyphs, start at the first block and process them all until a `EFI_HII_GIBT_END` block is found. When processing the glyph blocks, each block refers to the current character value (`CharValueCurrent`), which is initially set to one (1).

Glyph blocks of an unknown type should be skipped. If they cannot be skipped, then processing halts.

**Related Definitions**

```c
typedef struct _EFI_HII_GLYPH_INFO {
    UINT16 Width;
    UINT16 Height;
    INT16 OffsetX;
    INT16 OffsetY;
    INT16 AdvanceX;
} EFI_HII_GLYPH_INFO;
```

- **Width**
  - Width of the character or character cell, in pixels. For fixed-pitch fonts, this is the same as the advance.

- **Height**
  - Height of the character or character cell, in pixels.

- **OffsetX**
  - Offset to the horizontal edge of the character cell.

- **OffsetY**
  - Offset to the vertical edge of the character cell.

- **AdvanceX**
  - Number of pixels to advance to the right when moving from the origin of the current glyph to the origin of the next glyph.

### 33.3.3.2.1 EFI_HII_GIBT_DEFAULTS

**Summary**

Changes the default character cell information.

**Prototype**

```c
typedef struct _EFI_HII_GIBT_DEFAULTS_BLOCK {
    EFI_HII_GLYPH_BLOCK Header;
    EFI_HII_GLYPH_INFO Cell;
} EFI_HII_GIBT_DEFAULTS_BLOCK;
```

**Members**

- **Header**
  - Standard glyph block header, where `Header.BlockType = EFI_HII_GIBT_DEFAULTS`. 
Fig. 33.36: Glyph Information Encoded in Blocks
33.3. Code Definitions

Fig. 33.37: Glyph Block Processing
Cell

The new default cell information which will be applied to all subsequent \texttt{Glyph\_Default} and \texttt{Glyphs\_Default} blocks.

Description

Changes the default cell information used for subsequent \texttt{Efi\_Hii\_Gibt\_Glyph\_Default} and \texttt{Efi\_Hii\_Gibt\_Glyphs\_Default} glyph blocks. The cell information described by \texttt{Cell} remains in effect until the next \texttt{Efi\_Hii\_Gibt\_Defaults} is found. Prior to the first \texttt{Efi\_Hii\_Gibt\_Defaults} block, the cell information in the fixed header are used.

33.3.3.2.2 \texttt{Efi\_Hii\_Gibt\_Duplicate}

Summary

Assigns a new character value to a previously defined glyph.

Prototype

```c
typedef struct _Efi\_Hii\_Gibt\_Duplicate\_Block {
  EFI\_Hii\_Glyph\_Block Header;
  CHAR16 CharValue;
} EFI\_Hii\_Gibt\_Duplicate\_Block;
```

Members

Header

Standard glyph block header, where \texttt{Header.Block\_Type} = \texttt{Efi\_Hii\_Gibt\_Duplicate}.

CharValue

The previously defined character value with the exact same glyph.

Description

Indicates that the glyph with character value \texttt{CharValue\_Current} has the same glyph as a previously defined character value and increments \texttt{CharValue\_Current} by one.

33.3.3.2.3 \texttt{Efi\_Hii\_Gibt\_End}

Summary

Marks the end of the glyph information.

Prototype

```c
typedef struct _Efi\_Glyph\_Gibt\_End\_Block {
  EFI\_Hii\_Glyph\_Block Header;
} EFI\_Glyph\_Gibt\_End\_Block;
```

Members

Header

Standard glyph block header, where \texttt{Header.Block\_Type} = \texttt{Efi\_Hii\_Gibt\_End}.

Description

Any glyphs with a character value greater than or equal to \texttt{CharValue\_Current} are empty.
33.3.3.2.4 EFI_HII_GIBT_EXT1, EFI_HII_GIBT_EXT2, EFI_HII_GIBT_EXT4

Summary
Future expansion block types which have a length byte.

Prototype

```
typedef struct _EFI_HII_GIBT_EXT1_BLOCK {
    EFI_HII_GLYPH_BLOCK   Header;
    UINT8                BlockType2;
    UINT8                Length;
} EFI_HII_GIBT_EXT1_BLOCK;

typedef struct _EFI_HII_GIBT_EXT2_BLOCK {
    EFI_HII_GLYPH_BLOCK   Header;
    UINT8                BlockType2;
    UINT16               Length;
} EFI_HII_GIBT_EXT2_BLOCK;

typedef struct _EFI_HII_GIBT_EXT4_BLOCK {
    EFI_HII_GLYPH_BLOCK   Header;
    UINT8                BlockType2;
    UINT32               Length;
} EFI_HII_GIBT_EXT4_BLOCK;
```

Members

Header
Standard glyph block header, where Header.BlockType = EFI_HII_GIBT_EXT1, EFI_HII_GIBT_EXT2 or EFI_HII_GIBT_EXT4.

Length
Size of the glyph block, in bytes.

BlockType2
Indicates the type of extended block. Currently all extended block types are reserved for future expansion.

Description
These are reserved for future expansion, with length bytes included so that they can be easily skipped.

33.3.3.2.5 EFI_HII_GIBT_GLYPH

Summary
Provide the bitmap for a single glyph.

Prototype

```
typedef struct _EFI_HII_GIBT_GLYPH_BLOCK {
    EFI_HII_GLYPH_BLOCK   Header;
    EFI_HII_GLYPH_INFO    Cell;
    UINT8                BitmapData[1];
} EFI_HII_GIBT_GLYPH_BLOCK;
```

Members

33.3. Code Definitions
Header

Standard glyph block header, where Header.BlockType = EFI_HII_GIBT_GLYPH.

Cell

Contains the width and height of the encoded bitmap (Cell.Width and Cell.Height), the number of pixels (signed) right of the character cell origin where the left edge of the bitmap should be placed (Cell.OffsetX), the number of pixels above the character cell origin where the top edge of the bitmap should be placed (Cell.OffsetY) and the number of pixels (signed) to move right to find the origin for the next character cell (Cell.AdvanceX).

GlyphCount

The number of glyph bitmaps.

BitmapData

The bitmap data specifies a series of pixels, one bit per pixel, left-to-right, top-to-bottom. Each glyph bitmap only encodes the portion of the bitmap enclosed by its character-bounding box, but the entire glyph is padded out to the nearest byte. The number of bytes per bitmap can be calculated as: ((Cell.Width + 7)/8) * Cell.Height.

Description

This block provides the bitmap for the character with the value CharValueCurrent and increments CharValueCurrent by one. Each glyph contains a glyph width and height, a drawing offset, number of pixels to advance after drawing and then the encoded bitmap.

### 33.3.3.2.6 EFI_HII_GIBT_HII_GLYPHS

Summary

Provide the bitmaps for multiple glyphs with the same cell information.

Prototype

```c
typedef struct _EFI_HII_GIBT_GLYPHS_BLOCK {
    EFI_HII_GLYPH_BLOCK    Header;
    EFI_HII_GLYPH_INFO     Cell;
    UINT16                 Count;
    UINT8                  BitmapData[1];
} EFI_HII_GIBT_GLYPHS_BLOCK;
```

Members

Header

Standard glyph block header, where Header.BlockType = EFI_HII_GIBT_GLYPH.

Cell

Contains the width and height of the encoded bitmap (Cell.Width and Cell.Height), the number of pixels (signed) right of the character cell origin where the left edge of the bitmap should be placed (Cell.OffsetX), the number of pixels above the character cell origin where the top edge of the bitmap should be placed (Cell.OffsetY) and the number of pixels (signed) to move right to find the origin for the next character cell (Cell.AdvanceX).

BitmapData

The bitmap data specifies a series of pixels, one bit per pixel, left-to-right, top-to-bottom, for each glyph. Each glyph bitmap only encodes the portion of the bitmap enclosed by its character-bounding box. The number of bytes per bitmap can be calculated as: ((Cell.Width + 7)/8) * Cell.Height.

Description

Provides the bitmaps for the characters with the values CharValueCurrent through CharValueCurrent + Count -1 and increments CharValueCurrent by Count. These glyphs have identical cell information and the encoded bitmaps are exactly the same number of bytes.
33.3.3.2.7 EFI_HII_GIBT_GLYPH_DEFAULT

Summary
Provide the bitmap for a single glyph, using the default cell information.

Prototype

typedef struct _EFI_HII_GIBT_GLYPH_DEFAULT_BLOCK {
    EFI_HII_GLYPH_BLOCK       Header;
    UINT8 BitmapData[];
} EFI_HII_GIBT_GLYPH_DEFAULT_BLOCK;

Members

Header
Standard glyph block header, where Header.BlockType = EFI_HII_GIBT_GLYPH_DEFAULT.

BitmapData
The bitmap data specifies a series of pixels, one bit per pixel, left-to-right, top-to-bottom. Each glyph bitmap only encodes the portion of the bitmap enclosed by its character-bounding box. The number of bytes per bitmap can be calculated as: ((Global.Cell.Width + 7)/8) * Global.Cell.Height.

Description
Provides the bitmap for the character with the value CharValueCurrent and increments CharValueCurrent by 1. This glyph uses the default cell information. The default cell information is found in the font header or the most recently processed EFI_HII_GIBT_DEFAULTS.

33.3.3.2.8 EFI_HII_GIBT_GLYPHS_DEFAULT

Summary
Provide the bitmaps for multiple glyphs with the default cell information

Prototype

typedef struct _EFI_HII_GIBT_GLYPHS_DEFAULT_BLOCK {
    EFI_HII_GLYPH_BLOCK Header;
    UINT16 Count;
    UINT8 BitmapData[];
} EFI_HII_GIBT_GLYPHS_DEFAULT_BLOCK;

**Members**

Header
Standard glyph block header, where Header.BlockType = EFI_HII_GIBT_GLYPHS_DEFAULT.

Count
Number of glyphs in the glyph block.

BitmapData
The bitmap data specifies a series of pixels, one bit per pixel, left-to-right, top-to-bottom, for each glyph. Each glyph bitmap only encodes the portion of the bitmap enclosed by its character-bounding box. The number of bytes per bitmap can be calculated as: ((Global.Cell.Width + 7)/8) * Global.Cell.Height.
Description
Provides the bitmaps for the characters with the values CharValueCurrent through CharValueCurrent + Count -1 and increments CharValueCurrent by Count. These glyphs use the default cell information and the encoded bitmaps have exactly the same number of bytes.

33.3.3.2.9 EFI_HII_GIBT_SKIPx

Summary
Increments the current character value CharValueCurrent by the number specified.

Prototype

```c
typedef struct _EFI_HII_GIBT_SKIP2_BLOCK {
  EFI_HII_GLYPH_BLOCK            Header;
  UINT16                         SkipCount;
} EFI_HII_GIBT_SKIP2_BLOCK;

typedef struct _EFI_HII_GIBT_SKIP1_BLOCK {
  EFI_HII_GLYPH_BLOCK            Header;
  UINT8                          SkipCount;
} EFI_HII_GIBT_SKIP1_BLOCK;
```

Members
Header Standard glyph block header, where BlockType = EFI_HII_GIBT_SKIP1 or EFI_HII_GIBT_SKIP2.
SkipCount
The unsigned 8- or 16-bit value to add to CharValueCurrent.

Description
Increments the current character value CharValueCurrent by the number specified.

33.3.3.2.10 EFI_HII_GIBT_GLYPH_VARIABILITY

Related Definitions

```c
//***************************************************************
// EFI_HII_GIBT_GLYPH_VARIABILITY (0x14)
//***************************************************************

typedef struct _EFI_HII_GIBT_VARIABILITY_BLOCK {
  EFI_HII_GLYPH_BLOCK            Header;
  EFI_HII_GLYPH_INFO             Cell;
  UINT8                         GlyphPackInBits;
  UINT8                         BitmapData [1];
} EFI_HII_GIBT_VARIABILITY_BLOCK;
```

Members
Header Standard glyph block header, where Blocktype = EFI_HII_GIBT_GLYPH_VARIABILITY.
Cell Contains the width and height of the encoded bitmap (Cell.Width and Cell.Height), the number of pixels (signed)
right of the character cell origin where the left edge of the bitmap should be placed (Cell.OffsetX), the number of pixels above the character cell origin where the top edge of the bitmap should be placed (Cell.OffsetY) and the number of pixels (signed) to move right to find the origin for the next character cell (Cell.AdvanceX).

**GlyphPackInBits**
This describes the bit length for each pixel in glyph. With this, the length of BitmapData can be determined according to GlyphPackInBits, cell.width and cell.height.

The valid value is GIBT_VARIABILITY_BLOCK_1_BIT,

\[ GIBT\_VARIABILITY\_BLOCK\_2\_BIT, \]
\[ GIBT\_VARIABILITY\_BLOCK\_4\_BIT, \]
\[ GIBT\_VARIABILITY\_BLOCK\_8\_BIT, \]
\[ GIBT\_VARIABILITY\_BLOCK\_16\_BIT, \]
\[ GIBT\_VARIABILITY\_BLOCK\_24\_BIT, \]
\[ GIBT\_VARIABILITY\_BLOCK\_32\_BIT \]

HII Font Ex protocol has no idea about how to decode the bitmap of glyph if the glyph is declared as EFI_HII_GIBT_GLYPH_VARIABLITY. The bitmap decoding is resolved in EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL. This field is used to determine the length of entire glyph block.

**BitmapData**
The raw data of the glyph pixels. The format of the glyph pixel depends on the glyph generator. Only EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL knows how to draw the glyph.

![Diagram](image-url)

Fig. 33.38: EFI_HII_GIBT_GLYPH_VARIABILITY Glyph Drawing Processing
33.3.4 Device Path Package

Summary
The device path package is used to carry a device path associated with the package list.

Prototype

```c
typedef struct _EFI_HII_DEVICE_PATH_PACKAGE {
    EFI_HII_PACKAGE_HEADER Header;
    EFI_DEVICE_PATH_PROTOCOL DevicePath[];
} EFI_HII_DEVICE_PATH_PACKAGE;
```

Parameters

Header
The standard package header, where `Header.Type = EFI_HII_PACKAGE_TYPE_DEVICE_PATH`.

DevicePath
The Device Path description associated with the driver handle that provided the content sent to the HII database.

Description
This package is created by `NewPackageList()` when the package list is first added to the HII database by locating the `EFI_DEVICE_PATH_PROTOCOL` attached to the driver handle passed in to that function.

33.3.5 GUID Package

The GUID package is used to carry data where the format is defined by a GUID.

Prototype

```c
typedef struct _EFI_HII_GUID_PACKAGE_HDR {
    EFI_HII_PACKAGE_HEADER Header;
    EFI_GUID Guid;
    // Data per GUID definition may follow
} EFI_HII_GUID_PACKAGE_HDR;
```

Members

Header
The standard package header, where `Header.Type = EFI_HII_PACKAGE_TYPE_GUID`.

Guid
Identifier which describes the remaining data within the package.

Description
This is a free-form package type designed to allow extensibility by allowing the format to be specified using `Guid`.
33.3.6 String Package

The Strings package record describes the mapping between string identifiers and the actual text of the strings themselves. The package consists of three parts: a fixed header, the string information and the font information.

33.3.6.1 Fixed Header

The fixed header consists of a standard record header and then the string identifiers contained in this section and the offsets of the string and language information.

Prototype

typedef struct _EFI_HII_STRING_PACKAGE_HDR {
    EFI_HII_PACKAGE_HEADER Header;
    UINT32 HdrSize;
    UINT32 StringInfoOffset;
    CHAR16 LanguageWindow[16];
    EFI_STRING_ID LanguageName;
    CHAR8 Language [... ];
} EFI_HII_STRING_PACKAGE_HDR;

Members

Header
    The standard package header, where Header.Type = EFI_HII_PACKAGE_STRINGS.

HdrSize
    Size of this header.

StringInfoOffset
    Offset, relative to the start of this header, of the string information.

LanguageWindow
    Specifies the default values placed in the static and dynamic windows before processing each SCSU-encoded string.

LanguageName
    String identifier within the current string package of the full name of the language specified by Language.

Language
    The null-terminated ASCII string that specifies the language of the strings in the package. The languages are described as specified by Appendix M — Formats — Language Codes and Language Code Arrays.

Related Definition

#define UEFI_CONFIG_LANG "x-UEFI"
#define UEFI_CONFIG_LANG_2 "x-i-UEFI"
33.3.6.2 String Information

For each string identifier, the string information gives the string’s text and font. The string information is encoded as a series of blocks, each with a single byte header. The blocks must be processed in order, using the current string identifier (StringIdCurrent), which is set initially to one (1). Processing continues until an EFI_SIBT_END block is found.

The types of blocks are: string blocks, duplicate blocks, font blocks, and skip blocks. String blocks specify the text and font for the current string identifier and increment to the next string identifier. Duplicate blocks copy the text of a previous string identifier and increment to the next string identifier. Skip blocks skip string identifiers, leaving them blank.

![Diagram of string blocks](image)

Fig. 33.39: String Information Encoded in Blocks

Each block begins with a single byte, which contains the block type.

```c
typedef struct {
    UINT8 BlockType;
    UINT8 BlockBody[];
} EFI_HII_STRING_BLOCK;
```

The following table describes the different block types:

---

33.3. Code Definitions
### EFI_HII_SIBT_DUPLICATE

**Name** | **Value** | **Description**
---|---|---
EFI_HII_SIBT_END | 0x00 | The end of the string information.
EFI_HII_SIBT_STRING_SCSU | 0x10 | Single string using default font information.
EFI_HII_SIBT_STRING_SCSU_FONT | 0x11 | Single string with font information.
EFI_HII_SIBT_STRINGS_SCSU | 0x12 | Multiple strings using default font information.
EFI_HII_SIBT_STRINGS_SCSU_FONT | 0x13 | Multiple strings with font information.
EFI_HII_SIBT_STRING_UCS2 | 0x14 | Single UCS-2 string using default font information.
EFI_HII_SIBT_STRING_UCS2_FONT | 0x15 | Single UCS-2 string with font information.
EFI_HII_SIBT_STRINGS_UCS2 | 0x16 | Multiple UCS-2 strings using default font information.
EFI_HII_SIBT_STRINGS_UCS2_FONT | 0x17 | Multiple UCS-2 strings with font information.
EFI_HII_SIBT_DUPLICATE | 0x20 | Create a duplicate of an existing string.
EFI_HII_SIBT_SKIP2 | 0x21 | Skip a certain number of string identifiers.
EFI_HII_SIBT_SKIP1 | 0x22 | Skip a certain number of string identifiers.
EFI_HII_SIBT_EXT1 | 0x30 | For future expansion (one byte length field)
EFI_HII_SIBT_EXT2 | 0x31 | For future expansion (two byte length field)
EFI_HII_SIBT_EXT4 | 0x32 | For future expansion (four byte length field)
EFI_HII_SIBT_FONT | 0x40 | Font information.

When processing the string blocks, each block type refers and modifies the current string identifier (`StringIdCurrent`).

#### 33.3.6.2.1 EFI_HII_SIBT_DUPLICATE

**Summary**

Creates a duplicate of a previously defined string.

**Prototype**

```c
typedef struct _EFI_HII_SIBT_DUPLICATE_BLOCK {
  EFI_HII_STRING_BLOCK Header;
  EFI_STRING_ID StringId;
} EFI_HII_SIBT_DUPLICATE_BLOCK;
```

**Members**

**Header**

Standard string block header, where `Header.BlockType = EFI_HII_SIBT_DUPLICATE`.

**StringId**

The string identifier of a previously defined string with the exact same string text.

**Description**

Indicates that the string with string identifier `StringIdCurrent` is the same as a previously defined string and increments `StringIdCurrent` by one.
Fig. 33.40: String Block Processing: Base Processing
33.3.6.2.2 EFI_HII_SIBT_END

Summary
Marks the end of the string information.

Prototype

typedef struct _EFI_HII_SIBT_END_BLOCK {
    EFI_HII_STRING_BLOCK Header;
} EFI_HII_SIBT_END_BLOCK;

Members

Header
Standard extended header, where Header.Header.BlockType = EFI_HII_SIBT_EXT2 and Header.BlockType2 = EFI_HII_SIBT_FONT.

BlockType2
Indicates the type of extended block. See String Information for a list of all block types.

Description
Any strings with a string identifier greater than or equal to StringIdCurrent are empty.
Fig. 33.42: String Block Processing: UTF Processing
### 33.3.6.2.3 EFI_HII_SIBT_EXT1, EFI_HII_SIBT_EXT2, EFI_HII_SIBT_EXT4

**Summary**

Future expansion block types which have a length byte.

**Prototype**

```c
typedef struct _EFI_HII_SIBT_EXT1_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT8 BlockType2;
    UINT8 Length;
} EFI_HII_SIBT_EXT1_BLOCK;

typedef struct _EFI_HII_SIBT_EXT2_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT8 BlockType2;
    UINT16 Length;
} EFI_HII_SIBT_EXT2_BLOCK;

typedef struct _EFI_HII_SIBT_EXT4_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT8 BlockType2;
    UINT32 Length;
} EFI_HII_SIBT_EXT4_BLOCK;
```

**Members**

**Header**

Standard string block header, where `Header.BlockType = EFI_HII_SIBT_EXT1, EFI_HII_SIBT_EXT2 or EFI_HII_SIBT_EXT4`.

**Length**

Size of the string block, in bytes.

**BlockType2**

Indicates the type of extended block. See *String Information* for a list of all block types.

**Description**

These are reserved for future expansion, with length bytes included so that they can be easily skipped.

### 33.3.6.2.4 EFI_HII_SIBT_FONT

**Summary**

Provide information about a single font.

**Prototype**

```c
typedef struct _EFI_HII_SIBT_FONT_BLOCK {
    EFI_HII_SIBT_EXT2_BLOCK Header;
    UINT8 FontId;
    UINT16 FontSize;
    EFI_HII_FONT_STYLE FontStyle;
    CHAR16 FontName[...];
} EFI_HII_SIBT_FONT_BLOCK;
```
Members

Header
Standard extended header, where Header.BlockType2 = EFI_HII_SIBT_FONT.

FontId
Font identifier, which must be unique within the string package.

FontSize
Character cell size, in pixels, of the font.

FontStyle
Font style. Type EFI_HII_FONT_STYLE is defined in “Related Definitions” in EFI_HII_FONT_PACKAGE_HDR.

FontName
Null-terminated font family name.

Description
 Associates a font identifier FontId with a font name FontName, size FontSize and style FontStyle. This font identifier may be used with the string blocks. The font identifier 0 is the default font for those string blocks which do not specify a font identifier.

33.3.6.2.5 EFI_HII_SIBT_SKIP1

Summary
Skips string identifiers.

Prototype

```c
typedef struct _EFI_HII_SIBT_SKIP1_BLOCK {
  EFI_HII_STRING_BLOCK    Header;
  UINT8                   SkipCount;
} EFI_HII_SIBT_SKIP1_BLOCK;
```

Members

Header
Standard string block header, where Header.BlockType = EFI_HII_SIBT_SKIP1.

SkipCount
The unsigned 8-bit value to add to StringIdCurrent.

Description
Increments the current string identifier StringIdCurrent by the number specified.

33.3.6.2.6 EFI_HII_SIBT_SKIP2

Summary
Skips string ids.

Prototype
typedef struct _EFI_HII_SIBT_SKIP2_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT16 SkipCount;
} EFI_HII_SIBT_SKIP2_BLOCK;

Members

Header
    Standard string block header, where Header.BlockType = EFI_HII_SIBT_SKIP2.

SkipCount
    The unsigned 16-bit value to add to StringIdCurrent.

Description
    Increments the current string identifier StringIdCurrent by the number specified.

33.3.6.2.7 EFI_HII_SIBT_STRING_SCSU

Summary
    Describe a string encoded using SCSU, in the default font.

Prototype

typedef struct _EFI_HII_SIBT_STRING_SCSU_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT8 StringText[];
} EFI_HII_SIBT_STRING_SCSU_BLOCK;

Members

Header
    Standard header where Header.BlockType = EFI_HII_SIBT_STRING_SCSU.

StringText
    The string text is a null-terminated string, which is assigned to the string identifier StringIdCurrent.

Description
    This string block provides the SCSU-encoded text for the string in the default font with string identifier StringIdCurrent and increments StringIdCurrent by one.

33.3.6.2.8 EFI_HII_SIBT_STRING_SCSU_FONT

Summary
    Describe a string in the specified font.

Prototype

typedef struct _EFI_HII_SIBT_STRING_SCSU_FONT_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT8 FontIdentifier;
    UINT8 StringText[];
} EFI_HII_SIBT_STRING_SCSU_FONT_BLOCK;

Members
Header
Standard string block header, where Header.BlockType = EFI_HII_SIBT_STRING_SCSU_FONT.

FontIdentifier
The identifier of the font to be used as the starting font for the entire string. The identifier must either be 0 for the default font or an identifier previously specified by an EFI_HII_SIBT_FONT block. Any string characters that deviates from this font family, size or style must provide an explicit control character. See Common Control Codes.

StringText
The string text is a null-terminated encoded string, which is assigned to the string identifier StringIdCurrent.

Description
This string block provides the SCSU-encoded text for the string in the font specified by FontIdentifier with string identifier StringIdCurrent and increments StringIdCurrent by one.

33.3.6.2.9 EFI_HII_SIBT_STRINGS_SCSU

Summary
Describe strings in the default font.

Prototype

```c
typedef struct _EFI_HII_SIBT_STRINGS_SCSU_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT16 StringCount;
    UINT8 StringText[];
} EFI_HII_SIBT_STRINGS_SCSU_BLOCK;
```

Members

Header
Standard header where Header.BlockType = EFI_HII_SIBT_STRINGS_SCSU

StringCount
Number of strings in StringText.

StringText
The strings, where each string is a null-terminated encoded string.

Description
This string block provides the SCSU-encoded text for StringCount strings which have the default font and which have sequential string identifiers. The strings are assigned the identifiers, starting with StringIdCurrent and continuing through StringIdCurrent + StringCount - 1. StringIdCurrent is incremented by StringCount.

33.3.6.2.10 EFI_HII_SIBT_STRINGS_SCSU_FONT

Summary
Describe strings in the specified font.

Prototype
typedef struct _EFI_HII_SIBT_STRINGS_SCSU_FONT_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT8 FontIdentifier;
    UINT16 StringCount;
    UINT8 StringText[];
} EFI_HII_SIBT_STRINGS_SCSU_FONT_BLOCK;

Members

Header
Standard header where Header.BlockType = EFI_HII_SIBT_STRINGS_SCSU_FONT.

StringCount
Number of strings in StringText.

FontIdentifier
The identifier of the font to be used as the starting font for the entire string. The identifier must either be 0 for the default font or an identifier previously specified by an EFI_HII_SIBT_FONT block. Any string characters that deviates from this font family, size or style must provide an explicit control character. See Common Control Codes.

StringText
The strings, where each string is a null-terminated encoded string.

Description
This string block provides the SCSU-encoded text for StringCount strings which have the font specified by FontIdentifier and which have sequential string identifiers. The strings are assigned the identifiers, starting with StringIdCurrent and continuing through StringIdCurrent + StringCount - 1. StringIdCurrent is incremented by StringCount.

33.3.6.2.11 EFI_HII_SIBT_STRING_UCS2

Summary
Describe a string in the default font.

Prototype
typedef struct _EFI_HII_SIBT_STRING_UCS2_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    CHAR16 StringText[];
} EFI_HII_SIBT_STRING_UCS2_BLOCK;

Members

Header
Standard header where Header.BlockType = EFI_HII_SIBT_STRING_UCS2.

StringText
The string text is a null-terminated UCS-2 string, which is assigned to the string identifier StringIdCurrent.

Description
This string block provides the UCS-2 encoded text for the string in the default font with string identifier StringIdCurrent and increments StringIdCurrent by one.
33.3.6.2.12 EFI_HII_SIBT_STRING_UCS2_FONT

Summary
Describe a string in the specified font.

Prototype

```c
typedef struct _EFI_HII_SIBT_STRING_UCS2_FONT_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT8 FontIdentifier;
    CHAR16 StringText[];
} EFI_HII_SIBT_STRING_UCS2_FONT_BLOCK;
```

Members

Header
- Standard header where `Header.BlockType = EFI_HII_SIBT_STRING_UCS2_FONT`.

FontIdentifier
- The identifier of the font to be used as the starting font for the entire string. The identifier must either be 0 for the default font or an identifier previously specified by an `EFI_HII_SIBT_FONT` block. Any string characters that deviate from this font family, size or style must provide an explicit control character. See Common Control Codes.

StringText
- The string text is a null-terminated UCS-2 string, which is assigned to the string identifier `StringIdCurrent`.

Description
This string block provides the UCS-2 encoded text for the string in the font specified by `FontIdentifier` with string identifier `StringIdCurrent` and increments `StringIdCurrent` by one.

33.3.6.2.13 EFI_HII_SIBT_STRINGS_UCS2

Summary
Describes strings in the default font.

Prototype

```c
typedef struct _EFI_HII_SIBT_STRINGS_UCS2_BLOCK {
    EFI_HII_STRING_BLOCK Header;
    UINT16 StringCount;
    CHAR16 StringText[];
} EFI_HII_SIBT_STRINGS_UCS2_BLOCK;
```

Members

Header
- Standard header where `Header.BlockType = EFI_HII_SIBT_STRINGS_UCS2`.

StringCount
- Number of strings in `StringText`.

StringText
- The string text is a series of null-terminated UCS-2 strings, which are assigned to the string identifiers `StringIdCurrent` to `StringIdCurrent + StringCount - 1`.

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Description

This string block provides the UCS-2 encoded text for the strings in the default font with string identifiers StringIdCurrent to StringIdCurrent + StringCount - 1 and increments StringIdCurrent by StringCount.

33.3.6.2.14 EFI_HII_SIBT_STRINGS_UCS2_FONT

Summary

Describes strings in the specified font.

Prototype

```c
typedef struct _EFI_HII_SIBT_STRINGS_UCS2_FONT_BLOCK {
  EFI_HII_STRING_BLOCK       Header;
  UINT8                      FontIdentifier;
  UINT16                     StringCount;
  CHAR16                     StringText[];
} EFI_HII_SIBT_STRINGS_UCS2_FONT_BLOCK;
```

Members

Header

Standard header where Header.BlockType = EFI_HII_SIBT_STRINGS_UCS2_FONT.

FontIdentifier

The identifier of the font to be used as the starting font for the entire string. The identifier must either be 0 for the default font or an identifier previously specified by an EFI_HII_SIBT_FONT block. Any string characters that deviates from this font family, size or style must provide an explicit control character. See Common Control Codes.

StringCount

Number of strings in StringText.

StringText

The string text is a series of null-terminated UCS-2 strings, which are assigned to the string identifiers StringIdCurrent through StringIdCurrent + StringCount - 1.

Description

This string block provides the UCS-2 encoded text for the strings in the font specified by FontIdentifier with string identifiers StringIdCurrent to StringIdCurrent + StringCount - 1 and increments StringIdCurrent by StringCount.

33.3.6.3 String Encoding

Each of the following sections describes part of how string text is encoded.
33.3.6.3.1 Standard Compression Scheme for Unicode (SCSU)

The Unicode consortium provides a standard text compression algorithm, which minimizes the amount of storage required for multiple-language strings. For more information, see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Unicode Compression Scheme”.

This specification extends the technique described in the following ways:

- The strings use the control code 0x7F to introduce the control codes described in Common Control Codes. The following byte is the control code. The character value 0x7F will be encoded as 0x01 (SQ0) 0x7F.
- The language information contains default static and dynamic code windows, whereas SCSU provides fixed values for these.
- Characters between 0xF000 and 0xFCFF should be rejected.

33.3.6.3.2 Unicode 2-Byte Encoding (UCS-2)

The Unicode consortium provides a standard encoding algorithm, which takes two bytes per character. For more information see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Unicode Consortium”.

Characters between 0xF000 and 0xFCFF should be rejected.

33.3.7 Image Package

The Image package record describes the mapping between image identifiers and the pixels of the image themselves. The package consists of three parts: a fixed header, image information and the palette information.

33.3.7.1 Fixed Header

Summary

The fixed header consists of a standard record header and the offsets of the image and palette information.

Prototype

typedef struct _EFI_HII_IMAGE_PACKAGE_HDR {
    EFI_HII_PACKAGE_HEADER Header;
    UINT32 ImageInfoOffset;
    UINT32 PaletteInfoOffset;
} EFI_HII_IMAGE_PACKAGE_HDR;

Members

Header

Standard package header, where Header.Type = EFI_HII_PACKAGE_IMAGES.

ImageInfoOffset

Offset, relative to this header, of the image information. If this is zero, then there are no images in the package.

PaletteInfoOffset

Offset, relative to this header, of the palette information. If this is zero, then there are no palettes in the image package.
33.3.7.2 Image Information

For each image identifier, the image information gives the bitmap and the relevant palette. The image information is encoded as a series of blocks, each with a single byte header. The blocks must be processed in order. Each block begins with a single byte, which contains the block type.

![Image Information Encoded in Blocks]

Fig. 33.43: Image Information Encoded in Blocks

Prototype

```c
typedef struct _EFI_HII_IMAGE_BLOCK {
  UINT8 BlockType;
  UINT8 BlockBody[];
} EFI_HII_IMAGE_BLOCK;
```

The following table describes the different block types:

<table>
<thead>
<tr>
<th>Name</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 33.18: Block Types

continues on next page
Table 33.18 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_HII_IIBT_END</td>
<td>0x00</td>
<td>The end of the image information.</td>
</tr>
<tr>
<td>EFI_HII_IIBT_IMAGE_1BIT</td>
<td>0x10</td>
<td>1-bit w/palette</td>
</tr>
<tr>
<td>EFI_HII_IIBT_IMAGE_1BIT_TRANS</td>
<td>0x11</td>
<td>1-bit w/palette &amp; transparency</td>
</tr>
<tr>
<td>EFI_HII_IIBT_IMAGE_4BIT</td>
<td>0x12</td>
<td>4-bit w/palette</td>
</tr>
<tr>
<td>EFI_HII_IIBT_IMAGE_4BIT_TRANS</td>
<td>0x13</td>
<td>4-bit w/palette &amp; transparency</td>
</tr>
<tr>
<td>EFI_HII_IIBT_IMAGE_8BIT</td>
<td>0x14</td>
<td>8-bit w/palette</td>
</tr>
<tr>
<td>EFI_HII_IIBT_IMAGE_8BIT_TRANS</td>
<td>0x15</td>
<td>8-bit w/palette &amp; transparency</td>
</tr>
<tr>
<td>EFI_HII_IIBT_IMAGE_24BIT</td>
<td>0x16</td>
<td>24-bit RGB</td>
</tr>
<tr>
<td>EFI_HII_IIBT_IMAGE_24BIT_TRANS</td>
<td>0x17</td>
<td>24-bit RGB w/transparency</td>
</tr>
<tr>
<td>EFI_HII_IIBT_IMAGE_JPEG</td>
<td>0x18</td>
<td>JPEG encoded image</td>
</tr>
<tr>
<td>EFI_HII_IIBT_IMAGE_PNG</td>
<td>0x19</td>
<td>PNG encoded image</td>
</tr>
<tr>
<td>EFI_HII_IIBT_DUPLICATE</td>
<td>0x20</td>
<td>Duplicate an existing image identifier</td>
</tr>
<tr>
<td>EFI_HII_IIBT_SKIP2</td>
<td>0x21</td>
<td>Skip a certain number of image identifiers.</td>
</tr>
<tr>
<td>EFI_HII_IIBT_SKIP1</td>
<td>0x22</td>
<td>Skip a certain number of image identifiers.</td>
</tr>
<tr>
<td>EFI_HII_IIBT_EXT1</td>
<td>0x30</td>
<td>For future expansion (one byte length field)</td>
</tr>
<tr>
<td>EFI_HII_IIBT_EXT2</td>
<td>0x31</td>
<td>For future expansion (two byte length field)</td>
</tr>
<tr>
<td>EFI_HII_IIBT_EXT4</td>
<td>0x32</td>
<td>For future expansion (four byte length field)</td>
</tr>
</tbody>
</table>

In order to recreate all images, start at the first block and process them all until an `EFI_HII_IIBT_END_BLOCK` block is found. When processing the image blocks, each block refers to the current image identifier (`ImageIdCurrent`), which is initially set to one (1).

Image blocks of an unknown type should be skipped. If they cannot be skipped, then processing halts.

**33.3.7.2.1 EFI_HII_IIBT_END**

**Summary**

Marks the end of the image information.

**Prototype**

```c
#define EFI_HII_IIBT_END 0x00

typedef struct _EFI_HII_IIBT_END_BLOCK {
    EFI_HII_IMAGE_BLOCK Header;
} EFI_HII_IIBT_END_BLOCK;
```

**Members**

**Header**

Standard image block header, where `Header.BlockType = EFI_HII_IIBT_END_BLOCK`. 

**BlockType2**

Indicates the type of extended block. See String Information for a list of all block types.

**Description**

Any images with an image identifier greater than or equal to `ImageIdCurrent` are empty.
33.3.7.2.2 EFI_HII_IIBT_EXT1, EFI_HII_IIBT_EXT2, EFI_HII_IIBT_EXT4

Summary
Generic prefix for image information with a 1-byte length.

Prototype

```
#define EFI_HII_IIBT_EXT1 0x30
typedef struct _EFI_HII_IIBT_EXT1_BLOCK {
    EFI_HII_IMAGE_BLOCK Header;
    UINT8 BlockType2;
    UINT8 Length;
} EFI_HII_IIBT_EXT1_BLOCK;

#define EFI_HII_IIBT_EXT2 0x31
typedef struct _EFI_HII_IIBT_EXT2_BLOCK {
    EFI_HII_IMAGE_BLOCK Header;
    UINT8 BlockType2;
    UINT16 Length;
} EFI_HII_IIBT_EXT2_BLOCK;

#define EFI_HII_IIBT_EXT4 0x32
typedef struct _EFI_HII_IIBT_EXT4_BLOCK {
    EFI_HII_IMAGE_BLOCK Header;
    UINT8 BlockType2;
    UINT32 Length;
} EFI_HII_IIBT_EXT4_BLOCK;
```

Members

**Header**
Standard image block header, where `Header.BlockType` = `EFI_HII_IIBT_EXT1_BLOCK`, `EFI_HII_IIBT_EXT2_BLOCK` or `EFI_HII_IIBT_EXT4_BLOCK`.

**Length**
Size of the image block, in bytes, including the image block header.

**BlockType2**
Indicates the type of extended block. See *Image Information* for a list of all block types.

**Description**
Future extensions for image records which need a length-byte length use this prefix.
33.3.7.2.3 EFI_HII_IIBT_IMAGE_1BIT

Summary
One bit-per-pixel graphics image with palette information.

Prototype

```c
typedef struct _EFI_HII_IIBT_IMAGE_1BIT_BASE {
    UINT16 Width;
    UINT16 Height;
    UINT8 Data[...];
} EFI_HII_IIBT_IMAGE_1BIT_BASE;
#define EFI_HII_IIBT_IMAGE_1BIT 0x10

typedef struct _EFI_HII_IIBT_IMAGE_1BIT_BLOCK {
    EFI_HII_IMAGE_BLOCK Header;
    UINT8 PaletteIndex;
    EFI_HII_IIBT_IMAGE_1BIT_BASE Bitmap;
} EFI_HII_IIBT_IMAGE_1BIT_BLOCK;
```

Members

**Header**
Standard image header, where `Header.BlockType = EFI_HII_IIBT_IMAGE_1BIT`.

**Width**
Width of the bitmap in pixels.

**Height**
Height of the bitmap in pixels.

**Bitmap**
The bitmap specifies a series of pixels, one bit per pixel, left-to-right, top-to-bottom, and is padded out to the nearest byte. The number of bytes per bitmap can be calculated as: `(Width + 7)/8 * Height`.

**PaletteIndex**
Index of the palette in the palette information.

Description
This record assigns the 1-bit-per-pixel bitmap data to the `ImageIdCurrent` identifier and increment `ImageIdCurrent` by one. The image’s upper left hand corner pixel is the most significant bit of the first bitmap byte. An example of a `EFI_HII_IIBT_IMAGE_1BIT` structure is shown below:

```
0x01 ; Palette Index
0x000B ; Width
0x0013 ; Height
10000000b,00000000b ; Bitmap
11000000b,00000000b
11100000b,00000000b
11110000b,00000000b
11111000b,00000000b
11111100b,00000000b
11111110b,00000000b
11111111b,10000000b
```

(continues on next page)
33.3.7.2.4 EFI_HII_IIBT_IMAGE_1BIT_TRANS

Summary

One bit-per-pixel graphics image with palette information and transparency.

Prototype

```c
#define EFI_HII_IIBT_IMAGE_1BIT_TRANS 0x11

typedef struct _EFI_HII_IIBT_IMAGE_1BIT_TRANS_BLOCK {
    EFI_HII_IMAGE_BLOCK        Header;
    UINT8                      PaletteIndex;
    EFI_HII_IIBT_IMAGE_1BIT_BASE Bitmap;
} EFI_HII_IIBT_IMAGE_1BIT_TRANS_BLOCK;
```

Members

**Header**

Standard image header, where `Header.BlockType = EFI_HII_IIBT_IMAGE_1BIT_TRANS`.

**PaletteIndex**

Index of the palette in the palette information.

**Bitmap**

The bitmap specifies a series of pixels, one bit per pixel, left-to-right, top-to-bottom, and is padded out to the nearest byte. The number of bytes per bitmap can be calculated as: `((Width + 7)/8) * Height`.

Description

This record assigns the 1-bit-per-pixel bitmap data to the `ImageIdCurrent` identifier and increment `ImageIdCurrent` by one. The data in the `EFI_HII_IIBT_IMAGE_1BIT_TRANS` structure is exactly the same as the `EFI_HII_IIBT_IMAGE_1BIT` structure, the difference is how the data is treated.

The bitmap pixel value 0 is the ‘transparency’ value and will not be written to the screen. The bitmap pixel value 1 will be translated to the color specified by Palette.
33.3.7.2.5 EFI_HII_IIBT_IMAGE_24BIT

Summary

A 24 bit-per-pixel graphics image.

Prototype

```
#define EFI_HII_IIBT_IMAGE_24BIT 0x16

typedef struct _EFI_HII_IIBT_IMAGE_24BIT_BASE
    UINT16 Width;
    UINT16 Height;
    EFI_HII_RGB_PIXEL Bitmap[... ];
} EFI_HII_IIBT_IMAGE_24BIT_BASE;

typedef struct _EFI_HII_IIBT_IMAGE_24BIT_BLOCK {
    EFI_HII_IMAGE_BLOCK Header;
    EFI_HII_IIBT_IMAGE_24BIT_BASE Bitmap;
} EFI_HII_IIBT_IMAGE_24BIT_BASE;
```

Members

**Width**

Width of the bitmap in pixels.

**Height**

Height of the bitmap in pixels.

**Header**

Standard image header, where Header.BlockType = EFI_HII_IIBT_IMAGE_24BIT.

**Bitmap**

The bitmap specifies a series of pixels, 24 bits per pixel, left-to-right, top-to-bottom. The number of bytes per bitmap can be calculated as: (Width * 3) * Height. Type EFI_HII_RGB_PIXEL is defined in “Related Definitions” below.

Description

This record assigns the 24-bit-per-pixel bitmap data to the ImageIdCurrent identifier and increment ImageIdCurrent by one. The image’s upper left hand corner pixel is composed of the first three bitmap bytes. The first byte is the pixel’s blue component value, the next byte is the pixel’s green component value, and the third byte is the pixel’s red component value (B,G,R). Each color component value can vary from 0x00 (color off) to 0xFF (color full on), allowing 16.8 millions colors that can be specified.

Related Definitions

```
typedef struct _EFI_HII_RGB_PIXEL {
    UINT8 b;
    UINT8 g;
    UINT8 r;
} EFI_HII_RGB_PIXEL;
```

**b**

The relative intensity of blue in the pixel’s color, from off (0x00) to full-on (0xFF).

**g**

The relative intensity of green in the pixel’s color, from off (0x00) to full-on (0xFF).

**r**

The relative intensity of red in the pixel’s color, from off (0x00) to full-on (0xFF).
33.3.7.2.6 EFI_HII_IIBT_IMAGE_24BIT_TRANS

**Summary**

A 24 bit-per-pixel graphics image with transparency.

**Prototype**

```
#define _EFI_HII_IIBT_IMAGE_24BIT_TRANS 0x17

typedef struct EFI_HII_IIBT_IMAGE_24BIT_TRANS_BLOCK {
    EFI_HII_IMAGE_BLOCK       Header;
    EFI_HII_IIBT_IMAGE_24BIT_BASE    Bitmap;
} EFI_HII_IIBT_IMAGE_24BIT_TRANS_BLOCK;
```

**Members**

- **Header**
  
  Standard image header, where `Header.BlockType = EFI_HII_IIBT_IMAGE_24BIT_TRANS`.

- **Bitmap**
  
  The bitmap specifies a series of pixels, 24 bits per pixel, left-to-right, top-to-bottom. The number of bytes per bitmap can be calculated as: `(Width * 3) * Height`.

- **Width**
  
  Width of the bitmap in pixels.

- **Height**
  
  Height of the bitmap in pixels.

**Description**

This record assigns the 24-bit-per-pixel bitmap data to the `ImageIdCurrent` identifier and increment `ImageIdCurrent` by one. The data in the `EFI_HII_IMAGE_24BIT_TRANS` structure is exactly the same as the `EFI_HII_IMAGE_24BIT` structure, the difference is how the data is treated.

The bitmap pixel value 0x00, 0x00, 0x00 is the ‘transparency’ value and will not be written to the screen. All other bitmap pixel values will be written as defined to the screen. Since the ‘transparency’ value replaces true black, for image to display black they should use the color 0x00, 0x00, 0x01 (very dark red).

33.3.7.2.7 EFI_HII_IIBT_IMAGE_4BIT

**Summary**

Four bits-per-pixel graphics image with palette information.

**Prototype**

```
typedef struct _EFI_HII_IIBT_IMAGE_4BIT_BASE {
    UINT16      Width;
    UINT16      Height;
    UINT8      Data[...];
} EFI_HII_IIBT_IMAGE_4BIT_BASE;

#define EFI_HII_IIBT_IMAGE_4BIT 0x12

typedef struct _EFI_HII_IIBT_IMAGE_4BIT_BLOCK {
    EFI_HII_IMAGE_BLOCK       Header;
} EFI_HII_IIBT_IMAGE_4BIT_BLOCK;
```

(continues on next page)
Members

Width
Width of the bitmap in pixels.

Height
Height of the bitmap in pixels.

Header
Standard image header, where Header.BlockType = EFI_HII_IIBT_IMAGE_4BIT.

PaletteIndex
Index of the palette in the palette information.

Bitmap
The bitmap specifies a series of pixels, four bits per pixel, left-to-right, top-to-bottom, and is padded out to the nearest byte. The number of bytes per bitmap can be calculated as: \((\text{Width} + 1)/2\) * \(\text{Height}\).

Description
This record assigns the 4-bit-per-pixel bitmap data to the ImageIdCurrent identifier using the specified palette and increment ImageIdCurrent by one. The image’s upper left hand corner pixel is the most significant nibble of the first bitmap byte.

33.3.7.2.8 EFI_HII_IIBT_IMAGE_4BIT_TRANS

Summary
Four bits-per-pixel graphics image with palette information and transparency.

Prototype

```c
#define EFI_HII_IIBT_IMAGE_4BIT_TRANS 0x13

typedef struct _EFI_HII_IIBT_IMAGE_4BIT_TRANS_BLOCK {
  EFI_HII_IMAGE_BLOCK Header;
  UINT8 PaletteIndex;
  EFI_HII_IIBT_IMAGE_4BIT_BASE Bitmap;
} EFI_HII_IIBT_IMAGE_4BIT_TRANS_BLOCK;
```

Members

Header
Standard image header, where Header.BlockType = EFI_HII-IIBT_IMAGE_4BIT_TRANS.

PaletteIndex
Index of the palette in the palette information.

Bitmap
The bitmap specifies a series of pixels, four bits per pixel, left-to-right, top-to-bottom, and is padded out to the nearest byte. The number of bytes per bitmap can be calculated as: \((\text{Width} + 1)/2\) * \(\text{Height}\).

Description
This record assigns the 4-bit-per-pixel bitmap data to the *ImageIdCurrent* identifier using the specified palette and increment *ImageIdCurrent* by one. The data in the *EFI_HII-IMAGE_4BIT_TRANS* structure is exactly the same as the *EFI_HII-IMAGE_4BIT* structure, the difference is how the data is treated.

The bitmap pixel value 0 is the ‘transparency’ value and will not be written to the screen. All the other bitmap pixel values will be translated to the color specified by Palette.

### 33.3.7.2.9 EFI_HII-IIBT_IMAGE_8BIT

**Summary**

Eight bits-per-pixel graphics image with palette information.

**Prototype**

```c
#define EFI_HII-IIBT_IMAGE_8BIT 0x14

typedef struct _EFI_HII-IIBT_IMAGE_8BIT_BASE {
  UINT16 Width;
  UINT16 Height;
  UINT8 Data[... ];
} EFI_HII-IIBT_IMAGE_8BIT_BASE;

typedef struct _EFI_HII-IIBT_IMAGE_8BIT_BLOCK {
  EFI_HII-IMAGE_BLOCK Header;
  UINT8 PaletteIndex;
  EFI_HII-IIBT_IMAGE_8BIT_BASE Bitmap;
} EFI_HII-IIBT_IMAGE_8BIT_BLOCK;
```

**Members**

**Width**

Width of the bitmap in pixels.

**Height**

Height of the bitmap in pixels.

**Header**

Standard image header, where *Header.BlockType = EFI_HII_IIBT_IMAGE_8BIT*.

**PaletteIndex**

Index of the palette in the palette information.

**Bitmap**

The bitmap specifies a series of pixels, eight bits per pixel, left-to-right, top-to-bottom. The number of bytes per bitmap can be calculated as: *Width * Height*.

**Description**

This record assigns the 8-bit-per-pixel bitmap data to the *ImageIdCurrent* identifier using the specified palette and increment *ImageIdCurrent* by one. The image’s upper left hand corner pixel is the first bitmap byte.
33.3.7.2.10 EFI_HII_IIBT_IMAGE_8BIT_TRANS

Summary
Eight bits-per-pixel graphics image with palette information and transparency.

Prototype

```
#define EFI_HII_IIBT_IMAGE_8BIT_TRANS 0x15

typedef struct _EFI_HII_IIBT_IMAGE_8BIT_TRANS_BLOCK {
  EFI_HII_IMAGE_BLOCK                Header;
  UINT8                             PaletteIndex;
  EFI_HII_IIBT_IMAGE_8BIT_BASE      Bitmap;
} EFI_HII_IIBT_IMAGE_8BIT_TRANS_BLOCK;
```

Members

Header
Standard image header, where `Header.BlockType = EFI_HII_IIBT_IMAGE_8BIT_TRANS`.

PaletteIndex
Index of the palette in the palette information.

Bitmap
The bitmap specifies a series of pixels, eight bits per pixel, left-to-right, top-to-bottom. The number of bytes per bitmap can be calculated as: `Width * Height`.

Description
This record assigns the 8-bit-per-pixel bitmap data to the `ImageIdCurrent` identifier using the specified palette and increment `ImageIdCurrent` by one. The data in the `EFI_HII_IMAGE_8BIT_TRANS` structure is exactly the same as the `EFI_HII_IIBT_IMAGE_8BIT` structure, the difference is how the data is treated.

The bitmap pixel value 0 is the ‘transparency’ value and will not be written to the screen. All the other bitmap pixel values will be translated to the color specified by Palette.

```
EFI_HII_IIBT_DUPLICATE %%%%%%%%%%%%%%%%%%%%%%5
```

Summary
Assigns a new character value to a previously defined image.

Prototype

```
#define EFI_HII_IIBT_DUPLICATE 0x20

typedef struct _EFI_HII_IIBT_DUPLICATE_BLOCK {
  EFI_HII_IMAGE_BLOCK                Header;
  EFI_IMAGE_ID                       ImageId;
} EFI_HII_IIBT_DUPLICATE_BLOCK;
```

Members

Header
Standard image header, where `Header.BlockType = EFI_HII_IIBT_DUPLICATE`.

ImageId
The previously defined image ID with the exact same image.
Description
Indicates that the image with image ID ImageValueCurrent has the same image as a previously defined image ID and increments ImageValueCurrent by one.

33.3.7.2.11 EFI_HII_IIBT_IMAGE_JPEG

Summary
A true-color bitmap is encoded with JPEG image compression.

Prototype

```
#define EFI_HII_IIBT_IMAGE_JPEG 0x18

typedef struct _EFI_HII_IIBT_JPEG_BLOCK {
  EFI_HII_IMAGE_BLOCK       Header;
  UINT32                    Size;
  UINT8                     Data[... ];
} EFI_HII_IIBT_JPEG;
```

Members

Header
Standard image header, where Header.BlockType = EFI_HII_IIBT_IMAGE_JPEG.

Size
Specifies the size of the JPEG encoded data.

Data
JPEG encoded data with ‘JFIF’ signature at offset 6 in the data block. The JPEG encoded data, specifies type of encoding and final size of true-color image.

Description
This record assigns the JPEG image data to the ImageIdCurrent identifier and increment ImageIdCurrent by one. The JPEG decoder is only required to cover the basic JPEG encoding types, which are produced by standard available paint packages (for example: MSPaint under Windows from Microsoft). This would include JPEG encoding of high (1:1:1) and medium (4:1:1) quality with only three components (R,G,B) - no support for the special gray component encoding.

33.3.7.2.12 EFI_HII_IIBT_SKIP1

Summary
Skips image IDs.

Prototype

```
#define EFI_HII_IIBT_SKIP1 0x22

typedef struct _EFI_HII_IIBT_SKIP1_BLOCK {
  EFI_HII_IMAGE_BLOCK       Header;
  UINT8                     SkipCount;
} EFI_HII_IIBT_SKIP1_BLOCK;
```

Members
Header
Standard image header, where Header.BlockType = EFI_HII_IIBT_SKIP1.

SkipCount
The unsigned 8-bit value to add to ImageIdCurrent.

Description
Increments the current image ID ImageIdCurrent by the number specified.

33.3.7.2.13 EFI_HII_IIBT_SKIP2

Summary
Skips image IDs.

Prototype

```c
#define EFI_HII_IIBT_SKIP2 0x21

typedef struct _EFI_HII_IIBT_SKIP2_BLOCK {
    EFI_HII_IMAGE_BLOCK Header;
    UINT16 SkipCount;
} EFI_HII_IIBT_SKIP2_BLOCK;
```

Members

Header
Standard image header, where Header.BlockType = EFI_HII_IIBT_SKIP2.

SkipCount
The unsigned 16-bit value to add to ImageIdCurrent.

Description
Increments the current image ID ImageIdCurrent by the number specified.

33.3.7.2.14 EFI_HII_IIBT_PNG_BLOCK

Add a new image block structure for EFI_HII_IIBT_IMAGE_PNG. This supports the PNG image format in EFI HII image database.

Related Definitions

```c
//***************************************************************************
// EFI_HII_IIBT_IMAGE_PNG(0x19)
//***************************************************************************
typedef struct _EFI_HII_IIBT_PNG_BLOCK {
    EFI_HII_IMAGE_BLOCK Header;
    UINT32 Size;
    UINT8 Data[1];
} EFI_HII_IIBT_PNG_BLOCK;
```

Members

Header
Standard image block header, where Header.locktype = EFI_HII_IIBT_IMAGE_PNG.
33.3.7.3 Palette Information

Summary
This section describes the palette information within an image package.

Prototype

```c
typedef struct _EFI_HII_IMAGE_PALETTE_INFO_HEADER {
  UINT16 PaletteCount;
} EFI_HII_IMAGE_PALETTE_INFO_HEADER;
```

Members

PaletteCount
Number of palettes.

Description
This fixed header is followed by zero or more variable-length palette information records. The structures are assigned a number 1 to n.

33.3.7.3.1 Palette Information Records

Summary
A single palette

Prototype

```c
typedef struct _EFI_HII_IMAGE_PALETTE_INFO {
  UINT16 PaletteSize;
  EFI_HII_RGB_PIXEL PaletteValue[);
} EFI_HII_IMAGE_PALETTE_INFO;
```

Members

PaletteSize
Size of the palette information.

PaletteValue
Array of color values. Type `EFI_HII_RGB_PIXEL` is described in “Related Definitions” in `EFI_HII_IIBT_IMAGE_24BIT`.

Description
Each palette information record is an array of 24-bit color structures. The first entry (`PaletteValue[0]`) corresponds to color 0 in the source image; the second entry (`PaletteValue[1]`) corresponds to color 1, etc. Each palette entry is a three byte entry, with the first byte equal to the blue component of the color, followed by green, and finally red (B,G,R). Each color component value can vary from 0x00 (color off) to 0xFF (color full on), allowing 16.8 millions colors that can be specified.

A black & white 1-bit image would have the following palette structure:
A 4-bit image would have the following palette structure:

The image palette must only contain the palette entries specified in the bitmap. The bitmap should allocate each color index starting from 0x00, so the palette information can be as small as possible. The following is an example of a palette structure of a 4-bit image that only uses 6 colors:

Each palette entry specifies each unique color in the image. The above figure would be typical of light blue logo on a black background, with several shades of blue for anti-aliasing the blue logo on the black background.
33.8 Forms Package

The Forms package is used to carry forms-based encoding data.

Prototype

```c
typedef struct _EFI_HII_FORM_PACKAGE_HDR {
    EFI_HII_PACKAGE_HEADER *Header;
    //EFI_IFR_OP_HEADER *OpCodeHeader;
    //More op-codes follow
} EFI_HII_FORM_PACKAGE_HDR;
```

Parameters

**Header**

The standard package header, where Header.Type = EFI_HII_PACKAGE_FORMS.

**OpCodeHeader**

The header for the first of what will be a series of op-codes associated with the forms data described in this package. The syntax of the forms can be referenced in *Forms*.

Description

This is a package type designed to represent Internal Forms Representation (IFR) objects as a collection of op-codes.

33.8.1 Binary Encoding

The IFR is a binary encoding for HII-related objects. Every object has (at least) three attributes:

**Opcode.** The enumeration of all of the different HII-related objects.

**Length.** The length of the opcode itself (2-127 bytes).

**Scope.** If set, this opens up a new scope. Certain objects describe attributes or capabilities which only apply to the current scope rather than the entire form. The scope extends up to the special END opcode, which marks the end of the current scope.

The binary objects are encoded as byte stream. Every object begins with a standard header (*EFI_IFR_OP_HEADER*), which describes the opcode type, length and scope.
The simple binary object consists of a standard header, which contains a single 8-bit opcode, a 7-bit length and a 1-bit nesting indicator. The length specifies the number of bytes in the opcode, including the header. The simple binary object may also have zero or more bytes of fixed, object-specific, data.

![Simple Binary Object](image)

Fig. 33.47: Simple Binary Object

When the Scope bit is set, it marks the beginning of a new scope which applies to all subsequent opcodes until the matching EFI_IFR_END opcode is found to close the scope. Those opcodes may, in turn, open new scopes as well, creating nested scopes.

### 33.3.8.2 Standard Headers

#### 33.3.8.2.1 EFI_IFR_OP_HEADER

**Summary**

Standard opcode header

**Prototype**

```c
typedef struct _EFI_IFR_OP_HEADER {
    UINT8 OpCode;
    UINT8 Length:7;
    UINT8 Scope:1;
} EFI_IFR_OP_HEADER;
```

**Members**

**OpCode**

Defines which type of operation is being described by this header. See Opcode Reference for a list of IFR opcodes.

**Length**

Defines the number of bytes in the opcode, including this header.

**Scope**

If this bit is set, the opcode begins a new scope, which is ended by an EFI_IFR_END opcode.

**Description**

Forms are represented in a binary format roughly similar to processor instructions.

Each header contains an opcode, a length and a scope indicator.

If Scope indicator is set, the scope exists until it reaches a corresponding EFI_IFR_END opcode. Scopes may be nested within other scopes.

**Related Definitions**

```c
typedef UINT16 EFI_QUESTION_ID;
typedef UINT16 EFI_IMAGE_ID;
typedef UINT16 EFI_STRING_ID;
typedef UINT16 EFI_FORM_ID;
```

(continues on next page)
typedef UINT16 EFI_VARSTORE_ID;
typedef UINT16 EFI_ANIMATION_ID;

### 33.3.8.2.2 EFI_IFR_QUESTION_HEADER

**Summary**
Standard question header.

**Prototype**

typedef struct _EFI_IFR_QUESTION_HEADER {
    EFI_IFR_STATEMENT_HEADER Header;
    EFI_QUESTION_ID QuestionId;
    EFI_VARSTORE_ID VarStoreId;
    union {
        EFI_STRING_ID VarName;
        UINT16 VarOffset;
    } VarStoreInfo;
    UINT8 Flags;
} EFI_IFR_QUESTION_HEADER;

**Members**

- **Header**
  The standard statement header.

- **QuestionId**
  The unique value that identifies the particular question being defined by the opcode. The value of zero is reserved.

- **Flags**
  A bit-mask that determines which unique settings are active for this question. See “Related Definitions” below for the meanings of the individual bits.

- **VarStoreId**
  Specifies the identifier of a previously declared variable store to use when storing the question’s value. A value of zero indicates no associated variable store.

- **VarStoreInfo**
  If `VarStoreId` refers to Buffer Storage (`EFI_IFR_VARSTORE` or `EFI_IFR_VARSTORE_EFI`), then `VarStoreInfo` contains a 16-bit Buffer Storage offset (VarOffset). If `VarStoreId` refers to Name/Value Storage (`EFI_IFR_VARSTORE_NAME_VALUE`), then `VarStoreInfo` contains the String ID of the name (VarName) for this name/value pair.

**Description**
This is the standard header for questions.

**Related Definitions**

```c
// Flags values
#define EFI_IFR_FLAG_READ_ONLY 0x01
#define EFI_IFR_FLAG_CALLBACK 0x04
#define EFI_IFR_FLAG_RESET_REQUIRED 0x10
```

(continues on next page)
#define EFI_IFR_FLAG_REST_STYLE 0x20
#define EFI_IFR_FLAG_RECONNECT_REQUIRED 0x40
#define EFI_IFR_FLAG_OPTIONS_ONLY 0x80

<table>
<thead>
<tr>
<th>EFI_IFR_FLAG_READ_ONLY</th>
<th>The question is read-only</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_IFR_FLAG_CALLBACK</td>
<td>Designates if a particular opcode is to be treated as something that will initiate a callback to a registered driver.</td>
</tr>
<tr>
<td>EFI_IFR_FLAG_RESET_REQUIRED</td>
<td>If a particular choice is modified, designates that a return flag will be activated upon exiting the browser, which indicates that the changes that the user requested require a reset to enact.</td>
</tr>
<tr>
<td>EFI_IFR_FLAG_REST_STYLE</td>
<td>Designates if a question supports REST architectural style operation. This flag can be omitted if the formset class guid already contains EFI_HII_REST_STYLE_FORMSET_GUID.</td>
</tr>
<tr>
<td>EFI_IFR_FLAG_RECONNECT_REQUIRED</td>
<td>If a particular choice is modified, designates that a return flag will be activated upon exiting the formset or the browser, which indicates that the changes that the user requested require a reconnect to enact.</td>
</tr>
<tr>
<td>EFI_IFR_FLAG_OPTIONS_ONLY</td>
<td>For questions with options, this indicates that only the options will be available for user choice.</td>
</tr>
</tbody>
</table>

### 33.3.8.2.3 EFI_IFR_STATEMENT_HEADER

**Summary**

Standard statement header.

**Prototype**

```c
typedef struct _EFI_IFR_STATEMENT_HEADER {
    EFI_STRING_ID Prompt;
    EFI_STRING_ID Help;
} EFI_IFR_STATEMENT_HEADER;
```

**Members**

**Prompt**

The string identifier of the prompt string for this particular statement. The value 0 indicates no prompt string.

**Help**

The string identifier of the help string for this particular statement. The value 0 indicates no help string.

**Description**

This is the standard header for statements, including questions.
### 33.3.8.3 Opcode Reference

This section describes each of the IFR opcode encodings in detail. The table below lists the opcodes in numeric order while the reference section lists them in alphabetic order.

<table>
<thead>
<tr>
<th>Opcode</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_IFR_FORM_OP</td>
<td>0x01</td>
<td>Form</td>
</tr>
<tr>
<td>EFI_IFR_SUBTITLE_OP</td>
<td>0x02</td>
<td>Subtitle statement</td>
</tr>
<tr>
<td>EFI_IFR_TEXT_OP</td>
<td>0x03</td>
<td>Static text/image statement</td>
</tr>
<tr>
<td>EFI_IFR_IMAGE_OP</td>
<td>0x04</td>
<td>Static image</td>
</tr>
<tr>
<td>EFI_IFR_ONE_OF_OP</td>
<td>0x05</td>
<td>One-of question</td>
</tr>
<tr>
<td>EFI_IFR_CHECKBOX_OP</td>
<td>0x06</td>
<td>Boolean question</td>
</tr>
<tr>
<td>EFI_IFR_NUMERIC_OP</td>
<td>0x07</td>
<td>Numeric question</td>
</tr>
<tr>
<td>EFI_IFR_PASSWORD_OP</td>
<td>0x08</td>
<td>Password string question</td>
</tr>
<tr>
<td>EFI_IFR_ONE_OF_OPTION_OP</td>
<td>0x09</td>
<td>Option</td>
</tr>
<tr>
<td>EFI_IFR_SUPPRESS_IF_OP</td>
<td>0x0A</td>
<td>Suppress if conditional</td>
</tr>
<tr>
<td>EFI_IFR_LOCKED_OP</td>
<td>0x0B</td>
<td>Marks statement/question as locked</td>
</tr>
<tr>
<td>EFI_IFR_ACTION_OP</td>
<td>0x0C</td>
<td>Button question</td>
</tr>
<tr>
<td>EFI_IFR_RESET_BUTTON_OP</td>
<td>0x0D</td>
<td>Reset button statement</td>
</tr>
<tr>
<td>EFI_IFR_FORM_SET_OP</td>
<td>0x0E</td>
<td>Form set</td>
</tr>
<tr>
<td>EFI_IFR_REF_OP</td>
<td>0x0F</td>
<td>Cross-reference statement</td>
</tr>
<tr>
<td>EFI_IFR_NO_SUBMIT_IF_OP</td>
<td>0x10</td>
<td>Error checking conditional</td>
</tr>
<tr>
<td>EFI_IFR_INCONSISTENT_IF_OP</td>
<td>0x11</td>
<td>Error checking conditional</td>
</tr>
<tr>
<td>EFI_IFR_EQ_ID_VAL_OP</td>
<td>0x12</td>
<td>Return TRUE if question value equals UINT16</td>
</tr>
<tr>
<td>EFI_IFR_EQ_ID_ID_OP</td>
<td>0x13</td>
<td>Return TRUE if question value equals another question value</td>
</tr>
<tr>
<td>EFI_IFR_EQ_ID_VAL_LIST_OP</td>
<td>0x14</td>
<td>Return TRUE if question value is found in list of UINT16s</td>
</tr>
<tr>
<td>EFI_IFR_AND_OP</td>
<td>0x15</td>
<td>Push TRUE if both sub-expressions returns TRUE.</td>
</tr>
<tr>
<td>EFI_IFR_OR_OP</td>
<td>0x16</td>
<td>Push TRUE if either sub-expressions returns TRUE.</td>
</tr>
<tr>
<td>EFI_IFR_NOT_OP</td>
<td>0x17</td>
<td>Push FALSE if sub-expression returns TRUE, otherwise return TRUE.</td>
</tr>
<tr>
<td>EFI_IFR_RULE_OP</td>
<td>0x18</td>
<td>Create rule in current form.</td>
</tr>
<tr>
<td>EFI_IFR_GRAY_OUT_IF_OP</td>
<td>0x19</td>
<td>Nested statements, questions or options will not be selectable if expression returns TRUE.</td>
</tr>
<tr>
<td>EFI_IFR_DATE_OP</td>
<td>0x1A</td>
<td>Date question.</td>
</tr>
<tr>
<td>EFI_IFR_TIME_OP</td>
<td>0x1B</td>
<td>Time question.</td>
</tr>
<tr>
<td>EFI_IFR_STRING_OP</td>
<td>0x1C</td>
<td>String question</td>
</tr>
<tr>
<td>EFI_IFR_REFRESH_OP</td>
<td>0x1D</td>
<td>Interval for refreshing a question</td>
</tr>
<tr>
<td>EFI_IFR_DISABLE_IF_OP</td>
<td>0x1E</td>
<td>Nested statements, questions or options will not be processed if expression returns TRUE.</td>
</tr>
<tr>
<td>EFI_IFR_ANIMATION_OP</td>
<td>0x1F</td>
<td>Animation associated with question statement, form or form set.</td>
</tr>
<tr>
<td>EFI_IFR_TO_LOWER_OP</td>
<td>0x20</td>
<td>Convert a string on the expression stack to lower case.</td>
</tr>
<tr>
<td>EFI_IFR_TO_UPPER_OP</td>
<td>0x21</td>
<td>Convert a string on the expression stack to upper case.</td>
</tr>
</tbody>
</table>

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<table>
<thead>
<tr>
<th>EFI_IFR_MAP_OP</th>
<th>0x22</th>
<th>Convert one value to another by selecting a match from a list.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_IFR_ORDERED_LIST_OP</td>
<td>0x23</td>
<td>Set question</td>
</tr>
<tr>
<td>EFI_IFR_VARSTORE_OP</td>
<td>0x24</td>
<td>Define a buffer-style variable storage.</td>
</tr>
<tr>
<td>EFI_IFR_VARSTORE_NAME_VALUE_OP</td>
<td>0x25</td>
<td>Define a name/value style variable storage.</td>
</tr>
<tr>
<td>EFI_IFR_VARSTOREEFI_OP</td>
<td>0x26</td>
<td>Define a UEFI variable style variable storage.</td>
</tr>
<tr>
<td>EFI_IFR_VARSTORE_DEVICE_OP</td>
<td>0x27</td>
<td>Specify the device path to use for variable storage.</td>
</tr>
<tr>
<td>EFI_IFR_VERSION_OP</td>
<td>0x28</td>
<td>Push the revision level of the UEFI Specification to which this Forms Processor is compliant.</td>
</tr>
<tr>
<td>EFI_IFR_END_OP</td>
<td>0x29</td>
<td>Marks end of scope.</td>
</tr>
<tr>
<td>EFI_IFR_MATCH_OP</td>
<td>0x2A</td>
<td>Push TRUE if string matches a pattern.</td>
</tr>
<tr>
<td>EFI_IFR_GET_OP</td>
<td>0x2B</td>
<td>Return a stored value.</td>
</tr>
<tr>
<td>EFI_IFR_SET_OP</td>
<td>0x2C</td>
<td>Change a stored value.</td>
</tr>
<tr>
<td>EFI_IFR_READ_OP</td>
<td>0x2D</td>
<td>Provides a value for the current question or default.</td>
</tr>
<tr>
<td>EFI_IFR_WRITE</td>
<td>0x2E</td>
<td>Change a value for the current question.</td>
</tr>
<tr>
<td>EFI_IFR_EQUAL_OP</td>
<td>0x2F</td>
<td>Push TRUE if two expressions are equal.</td>
</tr>
<tr>
<td>EFI_IFR_NOT_EQUAL_OP</td>
<td>0x30</td>
<td>Push TRUE if two expressions are not equal.</td>
</tr>
<tr>
<td>EFI_IFR_GREATER_THAN_OP</td>
<td>0x31</td>
<td>Push TRUE if one expression is greater than another expression.</td>
</tr>
<tr>
<td>EFI_IFR_GREATER_EQUAL_OP</td>
<td>0x32</td>
<td>Push TRUE if one expression is greater than or equal to another expression.</td>
</tr>
<tr>
<td>EFI_IFR_LESS_THAN_OP</td>
<td>0x33</td>
<td>Push TRUE if one expression is less than another expression.</td>
</tr>
<tr>
<td>EFI_IFR_LESS_EQUAL_OP</td>
<td>0x34</td>
<td>Push TRUE if one expression is less than or equal to another expression.</td>
</tr>
<tr>
<td>EFI_IFR_BITWISE_AND_OP</td>
<td>0x35</td>
<td>Bitwise-AND two unsigned integers and push the result.</td>
</tr>
<tr>
<td>EFI_IFR_BITWISE_OR_OP</td>
<td>0x36</td>
<td>Bitwise-OR two unsigned integers and push the result.</td>
</tr>
<tr>
<td>EFI_IFR_BITWISE_NOT_OP</td>
<td>0x37</td>
<td>Bitwise-NOT an unsigned integer and push the result.</td>
</tr>
<tr>
<td>EFI_IFR_SHIFT_LEFT_OP</td>
<td>0x38</td>
<td>Shift an unsigned integer left by a number of bits and push the result.</td>
</tr>
<tr>
<td>EFI_IFR_SHIFT_RIGHT_OP</td>
<td>0x39</td>
<td>Shift an unsigned integer right by a number of bits and push the result.</td>
</tr>
<tr>
<td>EFI_IFR_ADD_OP</td>
<td>0x3A</td>
<td>Add two unsigned integers and push the result.</td>
</tr>
<tr>
<td>EFI_IFR_SUBTRACT_OP</td>
<td>0x3B</td>
<td>Subtract two unsigned integers and push the result.</td>
</tr>
<tr>
<td>EFI_IFR_MULTIPLY_OP</td>
<td>0x3C</td>
<td>Multiply two unsigned integers and push the result.</td>
</tr>
<tr>
<td>EFI_IFR_DIVIDE_OP</td>
<td>0x3D</td>
<td>Divide one unsigned integer by another and push the result.</td>
</tr>
<tr>
<td>EFI_IFR_MODULO_OP</td>
<td>0x3E</td>
<td>Divide one unsigned integer by another and push the remainder.</td>
</tr>
<tr>
<td>EFI_IFR_RULE_REF_OP</td>
<td>0x3F</td>
<td>Evaluate a rule</td>
</tr>
<tr>
<td>EFI_IFR_QUESTION_REF1_OP</td>
<td>0x40</td>
<td>Push a question’s value</td>
</tr>
<tr>
<td>EFI_IFR_QUESTION_REF2_OP</td>
<td>0x41</td>
<td>Push a question’s value</td>
</tr>
<tr>
<td>EFI_IFR_UINT8_OP</td>
<td>0x42</td>
<td>Push an 8-bit unsigned integer</td>
</tr>
<tr>
<td>EFI_IFR_UINT16_OP</td>
<td>0x43</td>
<td>Push a 16-bit unsigned integer</td>
</tr>
</tbody>
</table>

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<table>
<thead>
<tr>
<th>Opcode</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_IFR_UINT32_OP</td>
<td>0x44</td>
<td>Push a 32-bit unsigned integer</td>
</tr>
<tr>
<td>EFI_IFR_UINT64_OP</td>
<td>0x45</td>
<td>Push a 64-bit unsigned integer.</td>
</tr>
<tr>
<td>EFI_IFR_TRUE_OP</td>
<td>0x46</td>
<td>Push a boolean <strong>TRUE</strong></td>
</tr>
<tr>
<td>EFI_IFR_FALSE_OP</td>
<td>0x47</td>
<td>Push a boolean <strong>FALSE</strong></td>
</tr>
<tr>
<td>EFI_IFR_TO_UINT_OP</td>
<td>0x48</td>
<td>Convert expression to an unsigned integer</td>
</tr>
<tr>
<td>EFI_IFR_TO_STRING_OP</td>
<td>0x49</td>
<td>Convert expression to a string</td>
</tr>
<tr>
<td>EFI_IFR_TO_BOOLEAN_OP</td>
<td>0x4A</td>
<td>Convert expression to a boolean.</td>
</tr>
<tr>
<td>EFI_IFR_MID_OP</td>
<td>0x4B</td>
<td>Extract portion of string or buffer</td>
</tr>
<tr>
<td>EFI_IFR_FIND_OP</td>
<td>0x4C</td>
<td>Find a string in a string.</td>
</tr>
<tr>
<td>EFI_IFR_TOKEN_OP</td>
<td>0x4D</td>
<td>Extract a delimited byte or character string from buffer or string.</td>
</tr>
<tr>
<td>EFI_IFR_STRING_REF1_OP</td>
<td>0x4E</td>
<td>Push a string</td>
</tr>
<tr>
<td>EFI_IFR_STRING_REF2_OP</td>
<td>0x4F</td>
<td>Push a string</td>
</tr>
<tr>
<td>EFI_IFR_CONDITIONAL_OP</td>
<td>0x50</td>
<td>Duplicate one of two expressions depending on result of the first expression.</td>
</tr>
<tr>
<td>EFI_IFR_QUESTION_REF3_OP</td>
<td>0x51</td>
<td>Push a question’s value from a different form.</td>
</tr>
<tr>
<td>EFI_IFR_ZERO_OP</td>
<td>0x52</td>
<td>Push a zero</td>
</tr>
<tr>
<td>EFI_IFR_ONE_OP</td>
<td>0x53</td>
<td>Push a one</td>
</tr>
<tr>
<td>EFI_IFR_ONES_OP</td>
<td>0x54</td>
<td>Push a 0xFFFFFFFFFFFFFFFF.</td>
</tr>
<tr>
<td>EFI_IFR_UNDEFINED_OP</td>
<td>0x55</td>
<td>Push Undefined</td>
</tr>
<tr>
<td>EFI_IFR_LENGTH_OP</td>
<td>0x56</td>
<td>Push length of buffer or string</td>
</tr>
<tr>
<td>EFI_IFR_DUP_OP</td>
<td>0x57</td>
<td>Duplicate top of expression stack</td>
</tr>
<tr>
<td>EFI_IFR_THIS_OP</td>
<td>0x58</td>
<td>Push the current question’s value</td>
</tr>
<tr>
<td>EFI_IFR_SPAN_OP</td>
<td>0x59</td>
<td>Return first matching/non-matching character in a string</td>
</tr>
<tr>
<td>EFI_IFR_VALUE_OP</td>
<td>0x5A</td>
<td>Provide a value for a question</td>
</tr>
<tr>
<td>EFI_IFR_DEFAULT_OP</td>
<td>0x5B</td>
<td>Provide a default value for a question.</td>
</tr>
<tr>
<td>EFI_IFR_DEFAULTSTORE_OP</td>
<td>0x5C</td>
<td>Define a Default Type Declaration</td>
</tr>
<tr>
<td>EFI_IFR_FORM_MAP_OP</td>
<td>0x5D</td>
<td>Create a standards-map form.</td>
</tr>
<tr>
<td>EFI_IFR_CATENATE_OP</td>
<td>0x5E</td>
<td>Push concatenated buffers or strings.</td>
</tr>
<tr>
<td>EFI_IFR_GUID_OP</td>
<td>0x5F</td>
<td>An extensible GUIDed op-code</td>
</tr>
<tr>
<td>EFI_IFR_SECURITY_OP</td>
<td>0x60</td>
<td>Returns whether current user profile contains specified setup access privileges.</td>
</tr>
<tr>
<td>EFI_IFR_MODAL_TAG_OP</td>
<td>0x61</td>
<td>Specify current form is modal</td>
</tr>
<tr>
<td>EFI_IFR_REFRESH_ID_OP</td>
<td>0x62</td>
<td>Establish an event group for refreshing a forms-based element.</td>
</tr>
<tr>
<td>EFI_IFR_WARNING_IF</td>
<td>0x63</td>
<td>Warning conditional</td>
</tr>
<tr>
<td>EFI_IFR_MATCH2_OP</td>
<td>0x64</td>
<td>Push <strong>TRUE</strong> if string matches a Regular Expression pattern.</td>
</tr>
</tbody>
</table>

### Code Definitions

Each of the following sections gives a detailed description of the opcodes’ behavior.

#### 33.3. Code Definitions
### 33.3.8.3.1 EFI_IFR_ACTION

**Summary**

Create an action button.

**Prototype**

```c
#define EFI_IFR_ACTION_OP 0x0C
typedef struct _EFI_IFR_ACTION {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_QUESTION_HEADER Question;
    EFI_STRING_ID QuestionConfig;
} EFI_IFR_ACTION;

typedef struct _EFI_IFR_ACTION_1 {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_QUESTION_HEADER Question;
} _EFI_IFR_ACTION_1;
```

**Members**

- **Header**
  The standard opcode header, where `Header.OpCode = EFI_IFR_ACTION_OP`.

- **Question**
  The standard question header. See `EFI_IFR_QUESTION_HEADER` for more information.

- **QuestionConfig**
  The results string which is in `<ConfigResp>` format will be processed when the button is selected by the user.

**Description**

Creates an action question. When the question is selected, the configuration string specified by `QuestionConfig` will be processed. If `QuestionConfig` is 0 or is not present, then no configuration string will be processed. This is useful when using an action button only for the callback.

If the question is marked read-only (see `EFI_IFR_QUESTION_HEADER`) then the action question cannot be selected.

### 33.3.8.3.2 EFI_IFR_ANIMATION

**Summary**

Creates an image for a statement or question.

**Prototype**

```c
#define EFI_IFR_ANIMATION_OP 0x1F
typedef struct _EFI_IFR_ANIMATION {
    EFI_IFR_OP_HEADER Header;
    EFI_ANIMATION_ID Id;
} EFI_IFR_ANIMATION;
```

**Members**

- **Header**
  Standard opcode header, where `Header.OpCode` is `EFI_IFR_ANIMATION_OP`
Id
Animation identifier in the HII database.

Description
Associates an animation from the HII database with the current question, statement or form. If the specified animation
does not exist in the HII database.

33.3.8.3.3 EFI_IFR_ADD

Summary
Pops two unsigned integers, adds them and pushes the result.

Prototype

```c
#define EFI_IFR_ADD_OP 0x3a
typedef struct _EFI_IFR_ADD {
  EFI_IFR_OP_HEADER       Header;
} EFI_IFR_ADD;
```

Members

**Header**

Standard opcode header, where Header.OpCode = EFI_IFR_ADD_OP.

Description

This opcode performs the following actions:

1. Pop two values from the expression stack. The first popped is the right-hand value. The second popped is the left-hand value.
2. If the two values do not evaluate to unsigned integers, push Undefined.
3. Zero-extend the left-hand and right-hand values to 64-bits.
4. Add the left-hand value to right-hand value.
5. Push the lower 64-bits of the result. Overflow is ignored.

33.3.8.3.4 EFI_IFR_AND

Summary

Pops two booleans, push TRUE if both are TRUE, otherwise push FALSE.

Prototype

```c
#define EFI_IFR_AND_OP 0x15
typedef struct _EFI_IFR_AND {
  EFI_IFR_OP_HEADER       Header;
} EFI_IFR_AND;
```

Members

**Header**

The standard opcode header, where Header.OpCode = EFI_IFR_AND_OP.
Description
This opcode performs the following actions:
1. Pop two expressions from the expression stack.
2. If the two expressions cannot be evaluated as boolean, push Undefined.
3. If both expressions evaluate to TRUE, then push TRUE. Otherwise, push FALSE.

33.3.8.3.5 EFI_IFR_BITWISE_AND

Summary
Pops two unsigned integers, perform bitwise AND and push the result.

Prototype

```c
#define EFI_IFR_BITWISE_AND_OP 0x35
typedef struct _EFI_IFR_BITWISE_AND {
    EFI_IFR_OP_HEADER           Header;
} EFI_IFR_BITWISE_AND;
```

Members

Header
The standard opcode header, where Header.OpCode = EFI_IFR_BITWISE_AND_OP.

Description
This opcode performs the following actions:
1. Pop two expressions from the expression stack.
2. If the two expressions cannot be evaluated as unsigned integers, push Undefined.
3. Otherwise, zero-extend the unsigned integers to 64-bits.
4. Perform a bitwise-AND on the two values.
5. Push the result.

33.3.8.3.6 EFI_IFR_BITWISE_NOT

Summary
Pop an unsigned integer, perform a bitwise NOT and push the result.

Prototype

```c
#define EFI_IFR_BITWISE_NOT_OP 0x37
typedef struct _EFI_IFR_BITWISE_NOT {
    EFI_IFR_OP_HEADER          Header;
} EFI_IFR_BITWISE_NOT;
```

Members

Header
The standard opcode header, where Header.OpCode = EFI_IFR_BITWISE_NOT_OP.
Description
This opcode performs the following actions:
   1. Pop an expression from the expression stack.
   2. If the expression cannot be evaluated as an unsigned integer, push Undefined.
   3. Otherwise, zero-extend the unsigned integer to 64-bits.
   4. Perform a bitwise-NOT on the value.
   5. Push the result.

33.3.8.3.7 EFI_IFR_BITWISE_OR

Summary
Pops two unsigned integers, perform bitwise OR and push the result.

Prototype

```c
#define EFI_IFR_BITWISE_OR_OP 0x36
typedef struct _EFI_IFR_BITWISE_OR {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_BITWISE_OR;
```

Members

Header
   Standard opcode header, where OpCode is EFI_IFR_BITWISE_OR_OP.

Description
This opcode performs the following actions:
   1. Pop two expressions from the expression stack.
   2. If the two expressions cannot be evaluated as unsigned integers, push Undefined.
   3. Otherwise, zero-extend the unsigned integers to 64-bits.
   4. Perform a bitwise-OR of the two values.
   5. Push the result.

33.3.8.3.8 EFI_IFR_CATENATE

Summary
Pops two buffers or strings, concatenates them and pushes the result.

Prototype

```c
#define EFI_IFR_CATENATE_OP 0x5e
typedef struct _EFI_IFR_CATENATE {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_CATENATE;
```

Members
Header
Standard opcode header, where OpCode is EFI_IFR_CATENATE_OP.

Description
This opcode performs the following actions:
1. Pop two expressions from the expression stack. The first expression popped is the left value and the second value popped is the right value.
2. If the left or right values cannot be evaluated as a string or a buffer, push Undefined. If the left or right values are of different types, then push Undefined.
3. If the left and right values are strings, push a new string which contains the contents of the left string (without the NULL terminator) followed by the contents of the right string on to the expression stack.
4. If the left and right values are buffers, push a new buffer that contains the contents of the left buffer followed by the contents of the right buffer on to the expression stack.

33.3.8.3.9 EFI_IFR_CHECKBOX

Summary
Creates a boolean checkbox.

Prototype
```c
#define EFI_IFR_CHECKBOX_OP 0x06
typedef struct _EFI_IFR_CHECKBOX {
  EFI_IFR_OP_HEADER        Header;
  EFI_IFR_QUESTION_HEADER   Question;
  UINT8                     Flags;
} EFI_IFR_CHECKBOX;
```

Members

Header
The standard question header, where Header.OpCode = EFI_IFR_CHECKBOX_OP.

Question
The standard question header. See EFI_IFR_QUESTION_HEADER (EFI_IFR_QUESTION_HEADER) for more information.

Flags
Flags that describe the behavior of the question. All undefined bits should be zero. See EFI_IFR_CHECKBOX_x in “Related Definitions” for more information.

Description
Creates a Boolean checkbox question and adds it to the current form. The checkbox has two values: FALSE if the box is not checked and TRUE if it is.

There are three ways to specify defaults for this question: the Flags field (lowest priority), one or more nested EFI_IFR_ONE_OF_OPTION, or nested EFI_IFR_DEFAULT (highest priority).

An image may be associated with the question using a nested EFI_IFR_IMAGE. An animation may be associated with the option using a nested EFI_IFR_ANIMATION.

Related Definitions
### EFI_IFR_CONDITIONAL

#### Summary

Pops two values and a boolean, pushes one of the values depending on the boolean.

#### Prototype

```c
#define EFI_IFR_CONDITIONAL_OP 0x50
typedef struct _EFI_IFR_CONDITIONAL {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_CONDITIONAL;
```

#### Members

- **Header**
  
  Standard opcode header, where `OpCode` is `EFI_IFR_CONDITIONAL_OP`.

- **Description**
  
  This opcode performs the following actions:

  # Pop three values from the expression stack. The first value popped is the right value. The second expression popped is the middle value. The last expression popped is the left value.

  1. If the left value cannot be evaluated as a boolean, push Undefined.
  2. If the left expression evaluates to `TRUE`, push the right value.
  3. Otherwise, push the middle value.

### EFI_IFR_DATE

#### Summary

Create a date question.

#### Prototype

```c
#define EFI_IFR_DATE_OP 0x1A
typedef struct _EFI_IFR_DATE {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_QUESTION_HEADER Question;
    UINT8 Flags;
} EFI_IFR_DATE;
```

#### Members

- **Header**
  
  The sequence that defines the type of opcode as well as the length of the opcode being defined. `Header.OpCode` = `EFI_IFR_DATE_OP`.

- **Question**
  
  The standard question header. See `EFI_IFR_QUESTION_HEADER` for more information.
Flags

Flags that describe the behavior of the question. All undefined bits should be zero.

```c
#define EFI_QF_DATE_YEAR_SUPPRESS 0x01
#define EFI_QF_DATE_MONTH_SUPPRESS 0x02
#define EFI_QF_DATE_DAY_SUPPRESS 0x04
#define EFI_QF_DATE_STORAGE 0x30
```

For `QF_DATE_STORAGE`, there are currently three valid values:

```c
#define QF_DATE_STORAGE_NORMAL 0x00
#define QF_DATE_STORAGE_TIME 0x10
#define QF_DATE_STORAGE_WAKEUP 0x20
```

Description

Create a Date question (`Date`) and add it to the current form.

There are two ways to specify defaults for this question: one or more nested `EFI_IFR_ONE_OF_OPTION` (lowest priority) or nested `EFI_IFR_DEFAULT` (highest priority). An image may be associated with the option using a nested `EFI_IFR_IMAGE`. An animation may be associated with the question using a nested `EFI_IFR_ANIMATION`.

### 33.3.8.3.12 EFI_IFR_DEFAULT

**Summary**

Provides a default value for the current question

**Prototype**

```c
#define EFI_IFR_DEFAULT_OP 0x5b
typedef struct __EFI_IFR_DEFAULT {
  EFI_IFR_OP_HEADER Header;
  UINT16 DefaultId;
  UINT8 Type;
  EFI_IFR_TYPE_VALUE Value;
} EFI_IFR_DEFAULT;

typedef struct __EFI_IFR_DEFAULT_2 {
  EFI_IFR_OP_HEADER Header;
  UINT16 DefaultId;
  UINT8 Type;
} EFI_IFR_DEFAULT_2;
```

**Members**

**Header**

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_DEFAULT_OP`.

**DefaultId**

Identifies the default store for this value. The default store must have previously been created using `EFI_IFR_DEFAULTSTORE`.

**Type**

The type of data in the Value field. See `EFI_IFR_TYPE_x` in `EFI_IFR_ONE_OF_OPTION`.

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Value
The default value. The actual size of this field depends on Type. If Type is EFI_IFR_TYPE_OTHER, then the default value is provided by a nested EFI_IFR_VALUE.

Description
This opcode specifies a default value for the current question. There are two forms. The first (EFI_IFR_DEFAULT ) assumes that the default value is a constant, embedded directly in the Value member. The second (EFI_IFR_DEFAULT_2 ) assumes that the default value is specified using a nested EFI_IFR_VALUE opcode.

33.3.8.3.13 EFI_IFR_DEFAULTSTORE

Summary
Provides a declaration for the type of default values that a question can be associated with.

Prototype

```c
#define EFI_IFR_DEFAULTSTORE_OP 0x5c
typedef struct _EFI_IFR_DEFAULTSTORE {
    EFI_IFR_OP_HEADER    Header;
    EFI_STRING_ID        DefaultName;
    UINT16               DefaultId;
} EFI_IFR_DEFAULTSTORE;
```

Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, Header.OpCode = EFI_IFR_DEFAULTSTORE_OP

DefaultName
A string token reference for the human readable string associated with the type of default being declared.

DefaultId
The default identifier, which is unique within the current form set. The default identifier creates a group of defaults. See Attributes, listed under xxxx Defaults for the default identifier ranges.

Description
Declares a class of default which can then have question default values associated with.

An EFI_IFR_DEFAULTSTORE with a specified DefaultId must appear in the IFR before it can be referenced by an EFI_IFR_DEFAULT.

33.3.8.3.14 EFI_IFR_DISABLE_IF

Summary
Disable all nested questions and expressions if the expression evaluates to TRUE.

Prototype

```c
#define EFI_IFR_DISABLE_IF_OP 0x1e
typedef struct _EFI_IFR_DISABLE_IF {
    EFI_IFR_OP_HEADER    Header;
} EFI_IFR_DISABLE_IF;
```
Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined.

\( Header.\text{OpCode} = EFI\_IFR\_DISABLE\_IF\_OP. \)

Description
All nested statements, questions, options or expressions will not be processed if the expression appearing as the first nested object evaluates to \textbf{TRUE}. If the expression consists of more than a single opcode, then the first opcode in the expression must have the Scope bit set and the expression must end with \textit{EFI\_IFR\_END}.

When this opcode appears under a form set, the expression must only rely on constants. When this opcode appears under a form, the expression may rely on question values in the same form which are not inside of an \textit{EFI\_DISABLE\_IF} expression.

33.3.8.3.15 EFI\_IFR\_DIVIDE

Summary
Pops two unsigned integers, divide one by the other and pushes the result.

Prototype

```c
#define EFI\_IFR\_DIVIDE\_OP 0x3d
typedef struct _EFI\_IFR\_DIVIDE {
    EFI\_IFR\_OP\_HEADER Header;
} EFI\_IFR\_DIVIDE;
```

Members

Header
Standard opcode header, where OpCode is \textit{EFI\_IFR\_DIVIDE}.

Description
1. Pop two expressions from the expression stack. The first popped is the right-hand expression. The second popped is the left-hand expression.**

2. If the two expressions do not evaluate to unsigned integers, push Undefined. If the right-hand expression is equal to zero, push Undefined.

3. Zero-extend the left-hand and right-hand expressions to 64-bits.

4. Divide the left-hand value to right-hand expression.

5. Push the result.

33.3.8.3.16 EFI\_IFR\_DUP

Summary
Duplicate the top value on the expression stack.

Prototype

```c
#define EFI\_IFR\_DUP\_OP 0x57
typedef struct _EFI\_IFR\_DUP {
```
Members

Header
Standard opcode header, where OpCode is EFI_IFR_DUP_OP.

Description
Duplicate the top expression on the expression stack.

NOTE: This opcode is usually used as an optimization by the tools to help eliminate common sub-expression calculation and make smaller expressions.

33.3.8.3.17 EFI_IFR_END

Summary
End of the current scope.

Prototype

```
#define EFI_IFR_END_OP 0x29
typedef struct _EFI_IFR_END {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_END;
} EFI_IFR_END;
```

Members

Header
Standard opcode header, where OpCode is EFI_IFR_END_OP.

Description
Marks the end of the current scope.

33.3.8.3.18 EFI_IFR_EQUAL

Summary
Pop two values, compare and push TRUE if equal, FALSE if not.

Prototype

```
#define EFI_IFR_EQUAL_OP 0x2f
typedef struct _EFI_IFR_EQUAL {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_EQUAL;
} EFI_IFR_EQUAL;
```

Members

Header
Standard opcode header, where OpCode is EFI_IFR_EQUAL_OP.

Description
The opcode performs the following actions:
1. Pop two values from the expression stack.
2. If the two values are not strings, Booleans or unsigned integers, push Undefined.
3. If the two values are of different types, push Undefined.
4. Compare the two values. Strings are compared lexicographically.
5. If the two values are equal then push \textit{TRUE} on the expression stack. If they are not equal, push \textit{FALSE}.

\textbf{33.3.8.3.19 EFI_IFR_EQ_ID_ID}

\textbf{Summary}
Push \textit{TRUE} if the two questions have the same value or \textit{FALSE} if they are not equal.

\textbf{Prototype}

\begin{verbatim}
#define EFI_IFR_EQ_ID_ID_OP 0x13
typedef struct _EFI_IFR_EQ_ID_ID {
    EFI_IFR_OP_HEADER Header;
    EFI_QUESTION_ID QuestionId1;
    EFI_QUESTION_ID QuestionId2;
} EFI_IFR_EQ_ID_ID;
\end{verbatim}

\textbf{Members}

\textbf{Header}
Standard opcode header, where \textit{OpCode} is \textit{EFI_IFR_EQ_ID_ID_OP}.

\textbf{QuestionId1}, \textbf{QuestionId2} Specifies the identifier of the questions whose values will be compared.

\textbf{Description}
Evaluate the values of the specified questions (\textit{QuestionId1}, \textit{QuestionId2}). If the two values cannot be evaluated or cannot be converted to comparable types, then push Undefined. If they are equal, push \textit{TRUE}. Otherwise push \textit{FALSE}.

\textbf{33.3.8.3.20 EFI_IFR_EQ_ID_VAL_LIST}

\textbf{Summary}
Push \textit{TRUE} if the question’s value appears in a list of unsigned integers.

\textbf{Prototype}

\begin{verbatim}
#define EFI_IFR_EQ_ID_VAL_LIST_OP 0x14
typedef struct _EFI_IFR_EQ_ID_VAL_LIST {
    EFI_IFR_OP_HEADER Header;
    EFI_QUESTION_ID QuestionId;
    UINT16 ListLength;
    UINT16 ValueList[1];
} EFI_IFR_EQ_ID_VAL_LIST;
\end{verbatim}

\textbf{Members}

\textbf{Header}
Standard opcode header, where \textit{OpCode} is \textit{EFI_IFR_EQ_ID_VAL_LIST_OP}.
**QuestionId**
Specifies the identifier of the question whose value will be compared.

**ListLength**
Number of entries in ValueList.

**ValueList**
Zero or more unsigned integer values to compare against.

**Description**
Evaluate the value of the specified question (QuestionId). If the specified question cannot be evaluated as an unsigned integer, then push Undefined. If the value can be found in ValueList, then push TRUE. Otherwise push FALSE.

### 33.3.8.3.21 EFI_IFR_EQ_ID_VAL

**Summary**
Push TRUE if a question’s value is equal to a 16-bit unsigned integer, otherwise FALSE.

**Prototype**

```c
#define EFI_IFR_EQ_ID_VAL_OP 0x12
typedef struct _EFI_IFR_EQ_ID_VAL {
    EFI_IFR_OP_HEADER Header;
    EFI_QUESTION_ID QuestionId;
    UINT16 Value;
} EFI_IFR_EQ_ID_VAL;
```

**Members**

**Header**
Standard opcode header, where OpCode is EFI_IFR_EQ_ID_VAL_OP.

**QuestionId**
Specifies the identifier of the question whose value will be compared.

**Value**
Unsigned integer value to compare against.

**Description**
Evaluate the value of the specified question (QuestionId). If the specified question cannot be evaluated as an unsigned integer, then push Undefined. If they are equal, push TRUE. Otherwise push FALSE.

### 33.3.8.3.22 EFI_IFR_FALSE

**Summary**
Push a FALSE on to the expression stack.

**Prototype**

```c
#define EFI_IFR_FALSE_OP 0x47
typedef struct _EFI_IFR_FALSE {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_FALSE;
```

**Members**
Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, 
Header.OpCode = EFI_IFR_FALSE_OP

Description

Push a FALSE on to the expression stack.

33.3.8.3.23 EFI_IFR_FIND

Summary

Pop two strings and an unsigned integer, find one string in the other and the index where found.

Prototype

```c
#define EFI_IFR_FIND_OP 0x4c
typedef struct _EFI_IFR_FIND {
  EFI_IFR_OP_HEADER Header;
  UINT8 Format;
} EFI_IFR_FIND;
```

Members

Header

Standard opcode header, where OpCode is EFI_IFR_FIND_OP.

Format

The following flags govern the matching criteria:

Related Definitions

```c
#define EFI_IFR_FF_CASE_SENSITIVE 0x00
#define EFI_IFR_FF_CASE_INSENSITIVE 0x01
```

Description

This opcode performs the following actions:

1. Pop three expressions from the expression stack. The first expression popped is the right-hand value and the second value popped is the middle value and the last value popped is the left-hand value.
2. If the left-hand or middle values cannot be evaluated as a string, push Undefined. If the third expression cannot be evaluated as an unsigned integer, push Undefined.
3. The left-hand value is the string to search. The middle value is the string to compare with. The right-hand expression is the zero-based index of the search.
4. If the string is found, push the zero-based index of the found string.
5. Otherwise, if the string is not found or the right-hand value specifies a value which is greater-than or equal to the length of the left-hand value’s string, push 0xFFFFFFFFFFFFFFFF.
33.3.8.3.24 EFI_IFR_FORM

Summary
Creates a form.

Prototype

```
#define EFI_IFR_FORM_OP 0x01
typedef struct _EFI_IFR_FORM {
    EFI_IFR_OP_HEADER Header;
    EFI_FORM_ID FormId;
    EFI_STRING_ID FormTitle;
} EFI_IFR_FORM;
```

Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. `Header.OpCode` = `EFI_IFR_FORM_OP`.

FormId
The form identifier, which uniquely identifies the form within the form set. The form identifier, along with the device path and form set GUID, uniquely identifies a form within a system.

FormTitle
The string token reference to the title of this particular form.

Description
A form is the encapsulation of what amounts to a browser page. The header defines a `FormId`, which is referenced by the form set, among others. It also defines a `FormTitle`, which is a string to be used as the title for the form.

33.3.8.3.25 EFI_IFR_FORM_MAP

Summary
Creates a standards map form.

Prototype

```
#define EFI_IFR_FORM_MAP_OP 0x5D
typedef struct _EFI_IFR_FORM_MAP_METHOD {
    EFI_STRING_ID MethodTitle;
    EFI_GUID MethodIdentifier;
} EFI_IFR_FORM_MAP_METHOD;

typedef struct _EFI_IFR_FORM_MAP {
    EFI_IFR_OP_HEADER Header;
    EFI_FORM_ID FormId;
    //EFI_IFR_FORM_MAP_METHOD Methods[];
} EFI_IFR_FORM_MAP;
```

Parameters

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. `Header.OpCode` = `EFI_IFR_FORM_MAP_OP`. 
FormId
The unique identifier for this particular form.

Methods
One or more configuration method’s name and unique identifier.

MethodTitle
The string identifier which provides the human-readable name of the configuration method for this standards map form.

MethodIdentifier
Identifier which uniquely specifies the configuration methods associated with this standards map form. See “Related Definitions” for current identifiers.

Description
A standards map form describes how the configuration settings are represented for a configuration method identified by MethodIdentifier. It also defines a FormTitle, which is a string to be used as the title for the form.

Related Definitions

```
#define EFI_HII_STANDARD_FORM_GUID
   { 0x3bd2f4ec, 0xe524, 0x46e4,
   { 0xa9, 0xd8, 0x51, 0x01, 0x17, 0x42, 0x55, 0x62 } }
```

An EFI_IFR_FORM_MAP where the method identifier is EFI_HII_STANDARD_FORM_GUID is semantically identical to a normal EFI_IFR_FORM.

### 33.3.8.3.26 EFI_IFR_FORM_SET

Summary
The form set is a collection of forms that are intended to describe the pages that will be displayed to the user.

Prototype

```
#define EFI_IFR_FORM_SET_OP 0x0E

typedef struct _EFI_IFR_FORM_SET {
   EFI_IFR_OP_HEADER  Header;
   EFI_GUID           Guid;
   EFI_STRING_ID      FormSetTitle;
   EFI_STRING_ID      Help;
   UINT8              Flags;
   //EFI_GUID         ClassGuid[ ];
} EFI_IFR_FORM_SET;
```

Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode = EFI_IFR_FORM_SET_OP*.

Guid
The unique GUID value associated with this particular form set. Type EFI_GUID is defined in InstallProtocol-Interface() in this specification.

FormSetTitle
The string token reference to the title of this particular form set.
Help
The string token reference to the help of this particular form set.

Flags
Flags which describe additional features of the form set. Bits 0:1 = number of members in ClassGuid. Bits 2:7 = Reserved. Should be set to zero.

ClassGuid
Zero to four class identifiers. The standard class identifiers are described in EFI_HII_FORM_BROWSER2_PROTOCOL.SendForm(). They do not need to be unique in the form set.

Description
The form set consists of a header and zero or more forms.

33.3.8.3.27 EFI_IFR_GET

Summary
Return a stored value.

Prototype

```
#define EFI_IFR_GET_OP 0x2B
typedef struct _EFI_IFR_GET {
    EFI_IFR_OP_HEADER Header;
    EFI_VARSTORE_ID VarStoreId;
    union {
        EFI_STRING_ID VarName;
        UINT16 VarOffset;
    }
    EFI_VARSTORE_INFO VarStoreInfo;
    UINT8 VarStoreType;
} EFI_IFR_GET;
```

Parameters

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. Header.OpCode = EFI_IFR_GET_OP.

VarStoreId
Specifies the identifier of a previously declared variable store to use when retrieving the value.

VarStoreInfo
Depending on the type of variable store selected, this contains either a 16-bit Buffer Storage offset (VarOffset) or a Name/Value or EFI Variable name (VarName).

VarStoreType
Specifies the type used for storage. The storage types EFI_IFR_TYPE_x are defined in EFI_IFR_ONE_OF_OPTION.

Description
This operator takes the value from storage and pushes it on to the expression stack. If the value could not be retrieved from storage, then Undefined is pushed on to the expression stack.

The type of value retrieved from storage depends on the setting of VarStoreType, as described in the following table:
Table 33.21: VarStoreType Descriptions

<table>
<thead>
<tr>
<th>VarStoreType</th>
<th>Storage Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_IFR_TYPE_NUM_SIZE_8</td>
<td>8-bit unsigned integer</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_NUM_SIZE_16</td>
<td>16-bit unsigned integer</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_NUM_SIZE_32</td>
<td>32-bit unsigned integer</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_NUM_SIZE_64</td>
<td>64-bit unsigned integer</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_BOOLEAN</td>
<td>8-bit boolean (0 = FALSE, 1 = TRUE)</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_TIME</td>
<td>EFI_HII_TIME</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_DATE</td>
<td>EFI_HII_DATE</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_STRING</td>
<td>Null-terminated string</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_OTHER</td>
<td>Invalid</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_ACTION</td>
<td>Null-Terminated string</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_UNDEFINED</td>
<td>Invalid</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_BUFFER</td>
<td>Buffer</td>
</tr>
<tr>
<td>EFI_IFR_TYPE_REF</td>
<td>EFI_HII_REF</td>
</tr>
</tbody>
</table>

33.3.8.3.28 EFI_IFR_GRAY_OUT_IF

Summary

Creates a group of statements or questions which are conditionally grayed-out.

Prototype

```c
#define EFI_IFR_GRAY_OUT_IF_OP 0x19
typedef struct _EFI_IFR_GRAY_OUT_IF {
    EFI_IFR_OP_HEADER              Header;
} EFI_IFR_GRAY_OUT_IF;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined.

\[Header.OpCode = EFI_IFR_GRAY_OUT_IF_OP.\]

Description

All nested statements or questions will be grayed out (not selectable and visually distinct) if the expression appearing as the first nested object evaluates to \textit{TRUE}. If the expression consists of more than a single opcode, then the first opcode in the expression must have the Scope bit set and the expression must end with \textit{EFI_IFR_END}.

Different browsers may support this option to varying degrees. For example, HTML has no similar construct so it may not support this facility.

33.3.8.3.29 EFI_IFR_GREATER_EQUAL

Summary

Pop two values, compare, push \textit{TRUE} if first is greater than or equal the second, otherwise push \textit{FALSE}.

Prototype

```c
#define EFI_IFR_GREATER_EQUAL_OP 0x32
typedef struct _EFI_IFR_GREATER_EQUAL {
    (continues on next page)
```
Members

Header

Standard opcode header, where OpCode is EFI_IFR_GREATER_EQUAL_OP.

Description

This opcode performs the following actions:

1. Pop two values from the expression stack. The first value popped is the right-hand value and the second value popped is the left-hand value.
2. If the two values do not evaluate to string, boolean or unsigned integer, push Undefined.
3. If the two values do not evaluate to the same type, push Undefined.
4. Compare the two values. Strings are compared lexicographically.
5. If the left-hand value is greater than or equal to the right-hand value, push TRUE. Otherwise push FALSE.

33.3.8.3.30 EFI_IFR_GREATER_THAN

Summary

Pop two values, compare, push TRUE if first is greater than the second, otherwise push FALSE.

Prototype

#define EFI_IFR_GREATER_THAN_OP 0x31
typedef struct _EFI_IFR_GREATER_THAN {
    EFI_IFR_OP_HEADER *Header;
} EFI_IFR_GREATER_THAN;

Members

Header

Standard opcode header, where OpCode is EFI_IFR_GREATER_THAN_OP.

Description

This opcode performs the following actions:

1. Pop two values from the expression stack. The first value popped is the right-hand value and the second value popped is the left-hand value.
2. If the two values do not evaluate to string, boolean or unsigned integer, push Undefined.
3. If the two values do not evaluate to the same type, push Undefined.
4. Compare the two values. Strings are compared lexicographically.
5. If the left-hand value is greater than the right-hand value, push TRUE. Otherwise push FALSE.
33.3.8.3.31 EFI_IFR_GUID

Summary
A GUIDed operation. This op-code serves as an extensible op-code which can be defined by the Guid value to have various functionality. It should be noted that IFR browsers or scripts which cannot interpret the meaning of this GUIDed op-code will skip it.

Prototype

```c
#define EFI_IFR_GUID_OP 0x5F
typedef struct _EFI_IFR_GUID {
    EFI_IFR_OP_HEADER Header;
    EFI_GUID Guid;
    //Optional Data Follows
} EFI_IFR_GUID;
```

Parameters

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag,

\[\text{Header.OpCode} = \text{EFI_IFR_GUID_OP}\]

Guid
The GUID value for this op-code. This field is intended to define a particular type of special-purpose function, and the format of the data which immediately follows the Guid field (if any) is defined by that particular GUID.

33.3.8.3.32 EFI_IFR_IMAGE

Summary
Creates an image for a statement or question.

Prototype

```c
#define EFI_IFR_IMAGE_OP 0x04
typedef struct _EFI_IFR_IMAGE {
    EFI_IMAGE_ID Id;
} EFI_IFR_IMAGE;
```

Members

Id
Image identifier in the HII database.

Description
Specifies the image within the HII database.
33.3.8.3.33 EFI_IFR_INCONSISTENT_IF

Summary
Creates a validation expression and error message for a question.

Prototype

```c
#define EFI_IFR_INCONSISTENT_IF_OP 0x011
typedef struct _EFI_IFR_INCONSISTENT_IF {
    EFI_IFR_OP_HEADER Header;
    EFI_STRING_ID Error;
} EFI_IFR_INCONSISTENT_IF;
```

Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined.

Header.OpCode = EFI_IFR_INCONSISTENT_IF_OP.

Error
The string token reference to the string that will be used for the consistency check message.

Description
This tag uses a Boolean expression to allow the IFR creator to check options in a richer manner than provided by the question tags themselves. For example, this tag might be used to validate that two options are not using the same address or that the numbers that were entered align to some pattern (such as leap years and February in a date input field). The tag provides a string to be used in a error display to alert the user to the issue. Inconsistency tags will be evaluated when the user traverses from tag to tag. The user should not be allowed to submit the results of a form inconsistency.

33.3.8.3.34 EFI_IFR_LENGTH

Summary
Pop a string or buffer, push its length.

Prototype

```c
#define EFI_IFR_LENGTH_OP 0x56
typedef struct _EFI_IFR_LENGTH {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_LENGTH;
```

Members

Header Standard opcode header, where OpCode is EFI_IFR_LENGTH_OP.

Description
This opcode performs the following actions:

1. Pop a value from the expression stack.
2. If the value cannot be evaluated as a buffer or string, then push Undefined.
3. If the value can be evaluated as a buffer, push the length of the buffer, in bytes.
4. If the value can be evaluated as a string, push the length of the string, in characters.
33.3.8.3.35 EFI_IFR_LESS_EQUAL

Summary
Pop two values, compare, push \textit{TRUE} if first is less than or equal to the second, otherwise push \textit{FALSE}.

Prototype

```c
#define EFI_IFR_LESS_EQUAL_OP 0x34
typedef struct _EFI_IFR_LESS_EQUAL {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_LESS_EQUAL;
```

Members

Header
Standard opcode header, where \textit{OpCode} is \textit{EFI_IFR_LESS_EQUAL} _\texttt{OP}.

Description
This opcode performs the following actions:

1. Pop two values from the expression stack. The first value popped is the right-hand value and the second value popped is the left-hand value.
2. If the two values do not evaluate to string, boolean or unsigned integer, push Undefined.
3. If the two values do not evaluate to the same type, push Undefined.
4. Compare the two values. Strings are compared lexicographically.
5. If the left-hand value is less than or equal to the right-hand value, push \textit{TRUE}. Otherwise push \textit{FALSE}.

33.3.8.3.36 EFI_IFR_LESS_THAN

Summary
Pop two values, compare, push \textit{TRUE} if the first is less than the second, otherwise push \textit{FALSE}.

Prototype

```c
#define EFI_IFR_LESS_THAN_OP 0x33
typedef struct _EFI_IFR_LESS_THAN {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_LESS_THAN;
```

Members

Header
Standard opcode header, where \textit{OpCode} is \textit{EFI_IFR_LESS_THAN} _\texttt{OP}.

Description
This opcode performs the following actions:

1. Pop two values from the expression stack. The first value popped is the right-hand value and the second value popped is the left-hand value.
2. If the two values do not evaluate to string, boolean or unsigned integer, push Undefined.
3. If the two values do not evaluate to the same type, push Undefined.
4. Compare the two values. Strings are compared lexicographically.

5. If the left-hand value is less than the right-hand value, push TRUE. Otherwise push FALSE.

### 33.3.8.3.37 EFI_IFR_LOCKED

**Summary**

Specifies that the statement or question is locked.

**Prototype**

```c
#define EFI_IFR_LOCKED_OP 0x0B
typedef struct _EFI_IFR_LOCKED {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_LOCKED;
```

**Parameters**

- **Header**
  
  Standard opcode header, where `Header.OpCode` is `EFI_IFR_LOCKED_OP`.

**Members**

None

**Description**

The presence of `EFI_IFR_LOCKED` indicates that the statement or question should not be modified by a Forms Editor.

### 33.3.8.3.38 EFI_IFR_MAP

**Summary**

Pops value, compares against an array of comparison values, pushes the corresponding result value.

**Prototype**

```c
#define EFI_IFR_MAP_OP 0x22
typedef struct _EFI_IFR_MAP {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_MAP;
```

**Parameters**

- **Header**
  
  The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_MAP_OP`.

**Description**

This operator contains zero or more expression pairs nested within its scope. Each expression pair contains a match expression and a return expression.

This opcode performs the following actions:

1. This operator pops a single value from the expression stack.
2. Compare this value against the evaluated result of each of the match expressions.
3. If there is a match, then the evaluated result of the corresponding return expression is pushed on to the expression stack.
4. If there is no match, then Undefined is pushed.

### 33.3.8.3.39 EFI_IFR_MATCH

**Summary**

Pop a source string and a pattern string, push **TRUE** if the source string matches the pattern specified by the pattern string, otherwise push **FALSE**.

**Prototype**

```c
#define EFI_IFR_MATCH_OP 0x2a
typedef struct _EFI_IFR_MATCH {
    EFI_IFR_OP_HEADER     Header;
    EFI_IFR_MATCH;
} EFI_IFR_MATCH;
```

**Members**

**Header**

Standard opcode header, where `Header Opcode` is `EFI_IFR_MATCH_OP`.

**Description**

1. Pop two values from the expression stack. The first value popped is the string and the second value popped is the pattern.
2. If the string or the pattern cannot be evaluated as a string, then push Undefined.
3. Process the string and pattern using the `MetaiMatch` function of the `EFI_UNICODE_COLLATION2_PROTOCOL`.
4. If the result is **TRUE**, then push **TRUE**.
5. If the result is **FALSE**, then push **FALSE**.

### 33.3.8.3.40 EFI_IFR_MID

**Summary**

Pop a string or buffer and two unsigned integers, push an extracted portion of the string or buffer.

**Prototype**

```c
#define EFI_IFR_MID_OP 0x4b
typedef struct _EFI_IFR_MID {
    EFI_IFR_OP_HEADER     Header;
    EFI_IFR_MID;
} EFI_IFR_MID;
```

**Members**

**Header**

Standard opcode header, where `OpCode` is `EFI_IFR_MID_OP`.

**Description**

1. Pop three values from the expression stack. The first value popped is the right value and the second value popped is the middle value and the last expression popped is the left value.**
2. If the left value cannot be evaluated as a string or a buffer, push Undefined. If the middle or right value cannot be evaluated as unsigned integers, push Undefined.

3. If the left value is a string, then the middle value is the 0-based index of the first character in the string to extract and the right value is the length of the string to extract. If the right value is zero or the middle value is greater than or equal the string’s length, then push an Empty string. Push the extracted string on the expression stack. If the right value would cause extraction to extend beyond the end of the string, then only the characters up to and include the last character of the string are in the pushed result.

4. If the left value is a buffer, then the middle value is the 0-based index of the first byte in the buffer to extract and the right value is the length of the buffer to extract. If the right value is zero or the middle value is greater than the buffer’s length, then push an empty buffer. Push the extracted buffer on the expression stack. If the right value would cause extraction to extend beyond the end of the buffer, then only the bytes up to and include the last byte of the buffer are in the pushed result.

33.3.8.3.41 EFI_IFR_MODAL_TAG

Summary
Specify that the current form is a modal form.

Prototype

#define EFI_IFR_MODAL_TAG_OP 0x61
typedef struct _EFI_IFR_MODAL_TAG {
  EFI_IFR_OP_HEADER *Header;
} EFI_IFR_MODAL_TAG;

Members

Header
  Standard opcode header, where OpCode is EFI_IFR_MODAL_TAG_OP.

Description
When this opcode is present within the scope of a form, the form is modal; if the opcode is not present, the form is not modal.

A “modal” form is one that requires specific user interaction before it is deactivated. Examples of modal forms include error messages or confirmation dialogs.

When a modal form is activated, it is also selected. A modal form is deactivated only when one of the following occurs:

- The user chooses a “Navigate To Form” behavior (defined in Selected Form, “Selected Form”). Note that this is distinct from the “Navigate Forms” behavior.
- A question in the form requires callback, and the callback returns one of the following ActionRequest values (defined in EFI_HII_CONFIG_ACCESS_PROTOCOL.CallBack()):

  - EFI_BROWSER_ACTION_REQUEST_RESET
  - EFI_BROWSER_ACTION_REQUEST_SUBMIT
  - EFI_BROWSER_ACTION_REQUEST_EXIT
  - EFI_BROWSER_ACTION_REQUEST_FORM_SUBMIT_EXIT
  - EFI_BROWSER_ACTION_REQUEST_FORM_DISCARD_EXIT
A modal form cannot be deactivated using other navigation behaviors, including:

- Navigate Forms
- Exit Browser/Discard All (except when initiated by a callback as indicated above)
- Exit Browser/Submit All (except when initiated by a callback as indicated above)
- Exit Browser/Discard All/Reset Platform (except when initiated by a callback as indicated above)

### 33.3.8.3.42 EFI_IFR_MODULO

**Summary**

Pop two unsigned integers, divide one by the other and push the remainder.

**Prototype**

```
#define EFI_IFR_MODULO_OP 0x3e
typedef struct _EFI_IFR_MODULO {
    EFI_IFR_OP_HEADER *Header;
} EFI_IFR_MODULO;
```

**Members**

- **Header**
  
  Standard opcode header, where OpCode is EFI_IFR_MODULO_OP.

**Description**

This opcode performs the following actions:

1. Pop two values from the expression stack. The first value popped is the right-hand value and the second value popped is the left-hand value.
2. If the two values do not evaluate to unsigned integers, push Undefined. If the right-hand value to 0, push Undefined.
3. Zero-extend the values to 64-bits. Then, divide the left-hand value by the right-hand value.
4. Push the difference between the left-hand value and the product of the right-hand value and the calculated quotient.

### 33.3.8.3.43 EFI_IFR_MULTIPLY

**Summary**

Multiply one unsigned integer by another and push the result.

**Prototype**

```
#define EFI_IFR_MULTIPLY_OP 0x3c
typedef struct _EFI_IFR_MULTIPLY {
    EFI_IFR_OP_HEADER *Header;
} EFI_IFR_MULTIPLY;
```

**Members**

- **Header**

  Standard opcode header, where OpCode is EFI_IFR_MULTIPLY_OP.
33.3.8.3.44 EFI_IFR_NOT

Summary
Pop a boolean and, if TRUE, push FALSE. If FALSE, push TRUE.

Prototype

```
#define EFI_IFR_NOT_OP 0x17
typedef struct _EFI_IFR_NOT {
    EFI_IFR_OP_HEADER          Header;
} EFI_IFR_NOT;
```

Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = *EFI_IFR_NOT_OP*.

Description
This opcode performs the following actions:

1. Pop one value from the expression stack.
2. If the value cannot be evaluated as a Boolean, push Undefined.
3. If the value evaluates to TRUE, then push FALSE. Otherwise, push TRUE.

33.3.8.3.45 EFI_IFR_NOT_EQUAL

Summary
Pop two values, compare and push TRUE if not equal, otherwise push FALSE.

Prototype

```
#define EFI_IFR_NOT_EQUAL_OP 0x30
typedef struct _EFI_IFR_NOT_EQUAL {
    EFI_IFR_OP_HEADER         Header;
} EFI_IFR_NOT_EQUAL;
```

Members

Header* Standard opcode header, where *OpCode* is *EFI_IFR_NOT_EQUAL_OP*.

Description
This opcode performs the following actions:
1. Pop two values from the expression stack.
2. If the two values are not strings, Booleans or unsigned integers, push Undefined.
3. If the two values are of different types, push Undefined.
4. Compare the two values. Strings are compared lexicographically.
5. If the two values are not equal then push \texttt{TRUE} on the expression stack. If they are equal, push \texttt{FALSE}.

33.3.8.3.46 \texttt{EFI_IFR_NO_SUBMIT_IF}

Summary

Creates a validation expression and error message for a question.

Prototype

```c
#define EFI_IFR_NO_SUBMIT_IF_OP 0x10
typedef struct _EFI_IFR_NO_SUBMIT_IF {
    EFI_IFR_OP_HEADER  Header;
    EFI_STRING_ID      Error;
} EFI_IFR_NO_SUBMIT_IF;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined.

\texttt{Header.OpCode = EFI_IFR_NO_SUBMIT_IF_OP}.

Error

The string token reference to the string that will be used for the consistency check message.

Description

Creates a conditional expression which will be evaluated when the form is submitted. If the conditional evaluates to \texttt{TRUE}, then the error message \texttt{Error} will be displayed to the user and the user will be prevented from submitting the form.

33.3.8.3.47 \texttt{EFI_IFR_NUMERIC}

Summary

Creates a number question.

Prototype

```c
#define EFI_IFR_NUMERIC_OP 0x07
typedef struct _EFI_IFR_NUMERIC {
    EFI_IFR_OP_HEADER  Header;
    EFI_IFR_QUESTION_HEADER Question;
    UINT8 Flags;
    union {
        struct {
            UINT8 MinValue;
            UINT8 MaxValue;
            UINT8 Step;
        }
    }
} EFI_IFR_NUMERIC;
```

(continues on next page)
Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode* = *EFI_IFR_NUMERIC_OP*.

Question
The standard question header. xxxx See *EFI_IFR_QUESTION_HEADER* for more information.

Flags
Specifies flags related to the numeric question. See “Related Definitions”

MinValue
The minimum value to be accepted by the browser for this opcode. The size of the data field may vary from 8 to 64 bits.

MaxValue
The maximum value to be accepted by the browser for this opcode. The size of the data field may vary from 8 to 64 bits.

Step
Defines the amount to increment or decrement the value each time a user requests a value change. If the step value is 0, then the input mechanism for the numeric value is to be free-form and require the user to type in the actual value. The size of the data field may vary from 8 to 64 bits.

Description
Creates a number question on the current form, with built-in error checking and default information. The storage size depends on the *EFI_IFR_NUMERIC_SIZE* portion of the *Flags* field.

There are two ways to specify defaults for this question: one or more nested *EFI_IFR_ONE_OF_OPTION* (lowest priority) or nested *EFI_IFR_DEFAULT* (highest priority). An image may be associated with the option using a nested *EFI_IFR_IMAGE*. An animation may be associated with the question using a nested *EFI_IFR_ANIMATION*.

Related Definitions

```c
#define EFI_IFR_NUMERIC_SIZE 0x03
#define EFI_IFR_NUMERIC_SIZE_1 0x00
```

(continues on next page)
#define EFI_IFR_NUMERIC_SIZE_2   0x01
#define EFI_IFR_NUMERIC_SIZE_4   0x02
#define EFI_IFR_NUMERIC_SIZE_8   0x03

#define EFI_IFR_DISPLAY          0x30
#define EFI_IFR_DISPLAY_INT_DEC   0x00
#define EFI_IFR_DISPLAY_UINT_DEC  0x10
#define EFI_IFR_DISPLAY_UINT_HEX  0x20

**EFI_IFR_NUMERIC_SIZE** — Specifies the size of the numeric value, the storage required and the size of the MinValue, MaxValue and Step values in the opcode header.

**EFI_IFR_DISPLAY** — The value will be displayed in signed decimal, unsigned decimal or unsigned hexadecimal. Input is still allowed in any form.

**NOTE:** IFR expressions do not support signed types (Data Types Data Types). The value of a numeric question is treated during expression evaluation as an unsigned integer even if EFI_IFR_DISPLAY_INT_DEC flag is specified. However, the EFI_IFR_DISPLAY_INT_DEC flag is taken into consideration while validating question’s current or default value against MinValue and MaxValue. When EFI_IFR_DISPLAY_INT_DEC flag is specified, forms processor must treat MinValue, MaxValue, current question value, and default question value as signed integers.

### 33.3.8.3.48 EFI_IFR_ONE

**Summary**

Push a one on to the expression stack.

**Prototype**

```c
#define EFI_IFR_ONE_OP 0x53
typedef struct _EFI_IFR_ONE {
    EFI_IFR_OP_HEADER      Header;
} EFI_IFR_ONE;
```

**Members**

**Header**

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_ONE_OP`

**Description**

Push a one on to the expression stack.

### 33.3.8.3.49 EFI_IFR_ONES

**Summary**

Push 0xFFFFFFFFFFFFFFFF on to the expression stack.

**Prototype**

```c
#define EFI_IFR_ONES_OP 0x54
typedef struct _EFI_IFR_ONES {
```
Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, 
_Header.OpCode = _EFI_IFR_ONES_OP_

Description

Push 0xFFFFFFFFFFFFFFFF on to the expression stack.

33.3.8.3.50 _EFI_IFR_ONE_OF_

Summary

Creates a select-one-of question.

Prototype

```c
#define _EFI_IFR_ONE_OF_OP 0x05

typedef struct _EFI_IFR_ONE_OF {
  _EFI_IFR_OP_HEADER Header;
  _EFI_IFR_QUESTION_HEADER *Question;
  UINT8 Flags;
  union {
    struct {
      UINT8 MinValue;
      UINT8 MaxValue;
      UINT8 Step;
    } u8;
    struct {
      UINT16 MinValue;
      UINT16 MaxValue;
      UINT16 Step;
    } u16;
    struct {
      UINT32 MinValue;
      UINT32 MaxValue;
      UINT32 Step;
    } u32;
    struct {
      UINT64 MinValue;
      UINT64 MaxValue;
      UINT64 Step;
    } u64;
    } data;
} _EFI_IFR_ONE_OF;
```
Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. \textit{Header.OpCode} = \texttt{EFI_IFR\_ONE\_OF\_OP}.

Question
The standard question header. xxxx See \texttt{EFI\_IFR\_QUESTION\_HEADER} for more information.

Flags
Specifies flags related to the numeric question. See “Related Definitions” in \texttt{EFI\_IFR\_NUMERIC}.

MinValue
The minimum value to be accepted by the browser for this opcode. The size of the data field may vary from 8 to 64 bits, depending on the size specified in \texttt{Flags}.

MaxValue
The maximum value to be accepted by the browser for this opcode. The size of the data field may vary from 8 to 64 bits, depending on the size specified in \texttt{Flags}.

Step
Defines the amount to increment or decrement the value each time a user requests a value change. If the step value is 0, then the input mechanism for the numeric value is to be free-form and require the user to type in the actual value. The size of the data field may vary from 8 to 64 bits, depending on the size specified in \texttt{Flags}.

Description
This opcode creates a select-on-of object, where the user must select from one of the nested options. This is identical to \texttt{EFI\_IFR\_NUMERIC}.

There are two ways to specify defaults for this question: one or more nested \texttt{EFI\_IFR\_ONE\_OF\_OPTION} (lowest priority) or nested \texttt{EFI\_IFR\_DEFAULT} (highest priority). An image may be associated with the option using a nested \texttt{EFI\_IFR\_IMAGE}. An animation may be associated with the question using a nested \texttt{EFI\_IFR\_ANIMATION}.

33.3.8.3.51 \texttt{EFI\_IFR\_ONE\_OF\_OPTION}

Summary
Creates a pre-defined option for a question.

Prototype

```c
#define EFI_IFR_ONE_OF_OPTION_OP 0x09
typedef struct _EFI_IFR\_ONE\_OF\_OPTION {
    EFI_IFR\_OP\_HEADER Header;
    EFI\_STRING\_ID Option;
    UINT8 Flags;
    UINT8 Type;
    EFI\_IFR\_TYPE\_VALUE Value;
} EFI\_IFR\_ONE\_OF\_OPTION;
```

Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. \textit{Header.OpCode} = \texttt{EFI\_IFR\_ONE\_OF\_OPTION\_OP}.

Option
The string token reference to the option description string for this particular opcode.

Flags
Specifies the flags associated with the current option. See \texttt{EFI\_IFR\_OPTION\_x}.
Type

Specifies the type of the option’s value. See \texttt{EFI_IFR_TYPE}.

Value

The union of all of the different possible values. The actual contents (and size) of the field depends on \texttt{Type}.

Related Definitions

typedef union {
  UINT8 u8; // \texttt{EFI_IFR_TYPE_NUM_SIZE_8}
  UINT16 u16; // \texttt{EFI_IFR_TYPE_NUM_SIZE_16}
  UINT32 u32; // \texttt{EFI_IFR_TYPE_NUM_SIZE_32}
  UINT64 u64; // \texttt{EFI_IFR_TYPE_NUM_SIZE_64}
  BOOLEAN b; // \texttt{EFI_IFR_TYPE_BOOLEAN}
  EFI_HII_TIME time; // \texttt{EFI_IFR_TYPE_TIME}
  EFI_HII_DATE date; // \texttt{EFI_IFR_TYPE_DATE}
  EFI_STRING_ID string; // \texttt{EFI_IFR_TYPE_STRING}, \texttt{EFI_IFR_TYPE_ACTION}
  EFI_HII_REF ref; // \texttt{EFI_IFR_TYPE_REF}
  // UINT8 buffer[]; // \texttt{EFI_IFR_TYPE_BUFFER}
} EFI_IFR_TYPE_VALUE;

typedef struct {
  UINT8 Hour;
  UINT8 Minute;
  UINT8 Second;
} EFI_HII_TIME;

typedef struct {
  UINT16 Year;
  UINT8 Month;
  UINT8 Day; //
} EFI_HII_DATE;

typedef struct {
  EFI_QUESTION_ID QuestionId;
  EFI_FORM_ID FormId;
  EFI_GUID FormSetGuid;
  EFI_STRING_ID DevicePath;
} EFI_HII_REF;

#define EFI_IFR_TYPE_NUM_SIZE_8 0x00
#define EFI_IFR_TYPE_NUM_SIZE_16 0x01
#define EFI_IFR_TYPE_NUM_SIZE_32 0x02
#define EFI_IFR_TYPE_NUM_SIZE_64 0x03
#define EFI_IFR_TYPE_BOOLEAN 0x04
#define EFI_IFR_TYPE_TIME 0x05
#define EFI_IFR_TYPE_DATE 0x06
#define EFI_IFR_TYPE_STRING 0x07
#define EFI_IFR_TYPE_ACTION 0x0A
#define EFI_IFR_TYPE_BUFFER 0x0B
#define EFI_IFR_TYPE_REF 0x0C

(continues on next page)
#define EFI_IFR_OPTION_DEFAULT 0x10
#define EFI_IFR_OPTION_DEFAULT_MFG 0x20

Description
Create a selection for use in any of the questions.
The value is encoded within the opcode itself, unless EFI_IFR_TYPE_OTHER is specified, in which case the value is
determined by a nested EFI_IFR_VALUE.
An image may be associated with the option using a nested EFI_IFR_IMAGE. An animation may be associated with
the question using a nested EFI_IFR_ANIMATION.

33.3.8.3.52 EFI_IFR_OR

Summary
Pop two Booleans, push TRUE if either is TRUE. Otherwise push FALSE.

Prototype

#define EFI_IFR_OR_OP 0x16
typedef struct _EFI_IFR_OR {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_OR;

Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. Header.OpCode
= EFI_IFR_OR_OP.

Description
This opcode performs the following actions:
1. Pop two values from the expression stack.
2. If either value does not evaluate as a Boolean, then push Undefined.
3. If either value evaluates to TRUE, then push TRUE. Otherwise, push FALSE.

33.3.8.3.53 EFI_IFR_ORDERED_LIST

Summary
Creates a set question using an ordered list.

Prototype

#define EFI_IFR_ORDERED_LIST_OP 0x23
typedef struct _EFI_IFR_ORDERED_LIST {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_QUESTION_HEADER Question;
} EFI_IFR_ORDERED_LIST;
Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined.  
\( \text{Header.OpCode} = \text{EFI_IFR_ORDERED_LIST_OP}. \)

Question
The standard question header. See \textit{EFI_IFR_QUESTION_HEADER} for more information.

MaxContainers
The maximum number of entries for which this tag will maintain an order. This value also identifies the size of the storage associated with this tag’s ordering array.

Flags
A bit-mask that determines which unique settings are active for this opcode.

Description
Create an ordered list question in the current form. One thing to note is that valid values for the options in ordered lists should never be a 0. The value of 0 is used to determine if a particular “slot” in the array is empty. Therefore, if in the previous example 3 was followed by a 4 and then followed by a 0, the valid options to be displayed would be 3 and 4 only.

An image may be associated with the option using a nested \textit{EFI_IFR_IMAGE}. An animation may be associated with the question using a nested \textit{EFI_IFR_ANIMATION}.

Related Definitions

\begin{verbatim}
#define EFI_IFR_UNIQUE_SET 0x01
#define EFI_IFR_NO_EMPTY_SET 0x02
\end{verbatim}

These flags determine whether all entries in the list must be unique (\textit{EFI_IFR_UNIQUE_SET}) and whether there can be any empty items in the ordered list (\textit{EFI_IFR_NO_EMPTY_SET}).

\textbf{33.3.8.3.54 EFI_IFR_PASSWORD}

Summary
Creates a password question

Prototype

\begin{verbatim}
#define EFI_IFR_PASSWORD_OP 0x08
typedef struct _EFI_IFR_PASSWORD {
    EFI_IFR_OP_HEADER    Header;
    EFI_IFR_QUESTION_HEADER  Question;
    UINT16    MinSize;
    UINT16    MaxSize;
} EFI_IFR_PASSWORD;
\end{verbatim}

Members
Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. \( \text{Header.OpCode} = \text{EFI_IFR\_PASSWORD\_OP}. \)

Question
The standard question header. xxxx See \texttt{EFI\_IFR\_QUESTION\_HEADER} for more information.

MinSize
The minimum number of characters that can be accepted for this opcode.

MaxSize
The maximum number of characters that can be accepted for this opcode.

Description
Creates a password question in the current form.

An image may be associated with the option using a nested \texttt{EFI\_IFR\_IMAGE}. An animation may be associated with the question using a nested \texttt{EFI\_IFR\_ANIMATION}. The password question has two modes of operation. The first is when the \texttt{Header.Flags} has the \texttt{EFI\_IFR\_FLAG\_CALLBACK} bit not set. If the bit isn’t set, the browser will handle all password operations itself, including string comparisons as needed. If the password question has the \texttt{EFI\_IFR\_FLAG\_CALLBACK} bit set, then there will be a formal handshake initiated between the browser and the registered driver that would accept the callback. See the flowchart represented in the Figures, below, for details.

(This flowchart is provided in two parts because of page formatting but should be viewed as a single continuous chart.)

### 33.3.8.3.55 EFI\_IFR\_QUESTION\_REF1

Summary
Push a question’s value on the expression stack.

Prototype

```c
#define EFI\_IFR\_QUESTION\_REF1\_OP 0x40
typedef struct _EFI\_IFR\_QUESTION\_REF1 {
    EFI\_IFR\_OP\_HEADER Header;
    EFI\_QUESTION\_ID QuestionId;
} EFI\_IFR\_QUESTION\_REF1;
```

Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined. \( \text{Header.OpCode} = \text{EFI\_IFR\_QUESTION\_REF1\_OP}. \)

QuestionId
The question’s identifier, which must be unique within the form set.

Description
Push the value of the question specified by \texttt{QuestionId} on to the expression stack. If the question’s value cannot be determined or the question does not exist, then push Undefined.
Fig. 33.48: Password Flowchart (part one)
Fig. 33.49: Password Flowchart (part two)
### 33.3.8.3.56 EFI_IFR_QUESTION_REF2

**Summary**

Pop an integer from the expression stack, convert it to a question id, and push the question value associated with that question id onto the expression stack.

**Prototype**

```c
#define EFI_IFR_QUESTION_REF2_OP 0x41
typedef struct _EFI_IFR_QUESTION_REF2 {
    EFI_IFR_OP_HEADER  Header;
} EFI_IFR_QUESTION_REF2;
```

**Members**

**Header**

The byte sequence that defines the type of opcode as well as the length of the opcode being defined.

`Header.OpCode = EFI_IFR_QUESTION_REF2_OP;`

**Description**

This opcode performs the following actions:

1. Pop an integer from the expression stack
2. Convert it to a question id
3. Push the question value associated with that question id onto the expression stack.

If the popped expression cannot be evaluated as an unsigned integer or the value of the unsigned integer is greater than 0xFFFF, then push Undefined onto the expression stack in step 3. If the value of the question specified by the unsigned integer, after converted to a question id, cannot be determined or the question does not exist, also push Undefined onto the expression stack in step 3.

### 33.3.8.3.57 EFI_IFR_QUESTION_REF3

**Summary**

Pop an integer from the expression stack, convert it to a question id, and push the question value associated with that question id onto the expression stack.

**Prototype**

```c
#define EFI_IFR_QUESTION_REF3_OP 0x51
typedef struct _EFI_IFR_QUESTION_REF3 {
    EFI_IFR_OP_HEADER  Header;
} EFI_IFR_QUESTION_REF3;
```

```c
typedef struct _EFI_IFR_QUESTION_REF3_2 {
    EFI_IFR_OP_HEADER  Header;
    EFI_STRING_ID     DevicePath;
} EFI_IFR_QUESTION_REF3_2;
```

```c
typedef struct _EFI_IFR_QUESTION_REF3_3 {
    EFI_IFR_OP_HEADER  Header;
    EFI_STRING_ID     DevicePath;
} EFI_IFR_QUESTION_REF3_3;
```

(continues on next page)
Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined. *Header.OpCode = EFI_IFR_QUESTION_REF3_OP.*

DevicePath
Specifies the text representation of the device path containing the form set where the question is defined. If this is not present or the value is 0 then the device path installed on the *EFI_HANDLE* which was registered with the form set containing the current question is used.

Guid
Specifies the GUID of the form set where the question is defined. If the value is Nil or this field is not present, then the current form set is used (if *DevicePath* is 0) or the only form set attached to the device path specified by *DevicePath* is used. If the value is Nil and there is more than one form set on the specified device path, then the value Undefined will be pushed.

Description
This opcode performs the following actions:

1. Pop an integer from the expression stack
2. Convert it to a question id
3. Push the question value associated with that question id onto the expression stack.

If the popped expression cannot be evaluated as an unsigned integer or the value of the unsigned integer is greater than 0xFFFF, then push Undefined onto the expression stack in step 3. If the value of the question specified by the unsigned integer, after converted to a question id, cannot be determined or the question does not exist, also push Undefined onto the expression stack in step 3.

This version allows question values from other forms to be referenced in expressions.

33.3.8.3.58 EFI_IFR_READ

Summary
Provides a value for the current question or default.

Prototype

```c
#define EFI_IFR_READ_OP 0x2D
typedef struct _EFI_IFR_READ {
    EFI_IFR_OP_HEADER       Header;
} EFI_IFR_READ;
```

Parameters

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, *Header.OpCode = EFI_IFR_READ_OP*

Description
After reading the value for the current question (if any storage was specified) and setting the this constant (see EFI_IFR_THIS), this expression will be evaluated (if present) to return the value. If the FormId and QuestionId are either both not present, or are both set to zero, then the link does nothing.

### 33.3.8.3.59 EFI_IFR_REF

**Summary**

Creates a cross-reference statement.

**Prototype**

```c
#define EFI_IFR_REF_OP 0x0F

typedef struct _EFI_IFR_REF {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_QUESTION_HEADER Question;
    EFI_FORM_ID FormId;
} EFI_IFR_REF;

typedef struct _EFI_IFR_REF2 {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_QUESTION_HEADER Question;
    EFI_FORM_ID FormId;
    EFI_QUESTION_ID QuestionId;
} EFI_IFR_REF2;

typedef struct _EFI_IFR_REF3 {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_QUESTION_HEADER Question;
    EFI_FORM_ID FormId;
    EFI_QUESTION_ID QuestionId;
    EFI_GUID FormSetId;
} EFI_IFR_REF3;

typedef struct _EFI_IFR_REF4 {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_QUESTION_HEADER Question;
    EFI_FORM_ID FormId;
    EFI_QUESTION_ID QuestionId;
    EFI_GUID FormSetId;
    EFI_STRING_ID DevicePath;
} EFI_IFR_REF4;

typedef struct _EFI_IFR_REF5 {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_QUESTION_HEADER Question;
} EFI_IFR_REF5;
```

**Members**

**Header**

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. 

`Header.OpCode = EFI_IFR_REF_OP.`

---

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**Question**
Standard question header. See EFI_IFR_QUESTION_HEADER

**FormId**
The form to which this link is referring. If this is zero, then the link is on the current form. If this is missing, then the link is determined by the nested EFI_IFR_VALUE.

**QuestionId**
The question on the form to which this link is referring. If this field is not present (determined by the length of the opcode) or the value is zero, then the link refers to the top of the form.

**FormSetId**
The form set to which this link is referring. If it is all zeroes or not present, and DevicePath is not present, then the link is to the current form set. If it is all zeroes (or not present) and the DevicePath is present, then the link is to the first form set associated with the DevicePath.

**DevicePath**
The string identifier that specifies the string containing the text representation of the device path to which the form set containing the form specified by FormId. If this field is not present (determined by the opcode’s length) or the value is zero, then the link refers to the current page. The format of the device path string that this field references is compatible with the Text format that is specified in the Text Device Node Reference (Text Device Node Reference).

**Description**
Creates a user-selectable link to a form or a question on a form. There are several forms of this opcode which are distinguished by the length of the opcode.

### 33.3.8.3.60 EFI_IFR_REFRESH

**Summary**
Mark a question for periodic refresh.

**Prototype**

```c
#define EFI_IFR_REFRESH_OP 0x1d
typedef struct _EFI_IFR_REFRESH {
  EFI_IFR_OP_HEADER Header;
  UINT8 RefreshInterval;
} EFI_IFR_REFRESH;
```

**Members**

**Header**
The byte sequence that defines the type of opcode as well as the length of the opcode being defined. Header.OpCode = EFI_IFR_REFRESH_OP.

**RefreshInterval**
Minimum number of seconds before the question value should be refreshed. A value of zero indicates the question should not be refreshed automatically.

**Description**
When placed within the scope of a question, it will force the question’s value to be refreshed at least every RefreshInterval seconds. The value may be refreshed less often, depending on browser policy or capabilities.
33.3.8.3.61 EFI_IFR_REFRESH_ID

Summary

Mark an Question for an asynchronous refresh.

Prototype

```c
#define EFI_IFR_REFRESH_ID_OP 0x62
typedef struct _EFI_IFR_REFRESH_ID {
    EFI_IFR_OP_HEADER Header;
    EFI_GUID RefreshEventGroupId;
} EFI_IFR_REFRESH_ID;
```

Members

Header

The byte sequence that defines the type of opcode as well as the length of the opcode being defined.  
\[\text{Header.OpCode} = \text{EFI_IFR_REFRESH_ID_OP}\].

RefreshEventGroupId

The GUID associated with the event group which will be used to initiate a re-evaluation of an element in a set of forms.

Description

This tag op-code must be placed within the scope of a question or a form. If within the scope of a question and the event is signaled which belongs to the `RefreshEventGroupId`, the question will be refreshed. More than one question may share the same Event Group.

If the tag op-code is placed within the scope of an `EFI_IFR_FORM` op-code and the event is signaled which belongs to the `RefreshEventGroupId`, the entire form’s contents will be refreshed.

- If the contents within a form had an `EFI_IFR_REFRESH_ID` tag op-code placed within the scope of the form, and an event is signalled, all questions associated with the `RefreshEventGroupId` are marked for refresh. The Forms Browser will update the question value from storage, reparse the forms from the HII database and, at some time later, reflect that change if the question is displayed.

When interpreting this op-code, a browser must do the following actions:

- The browser will create an event group via `CreateEventEx()` based on the specified `RefreshEventGroupId` when the form set which contains the op-code is opened by the browser.
- When an event is signaled, all questions associated with the `RefreshEventGroupId` are marked for refresh. The Forms Browser will update the question value from storage and, at some time later, update the question’s display.
- The browser will close the event group which was previously created when the form set which contains the op-code is closed by the browser.

33.3.8.3.62 EFI_IFR_RESET_BUTTON

Summary

Create a reset or submit button on the current form.

Prototype
#define EFI_IFR_RESET_BUTTON_OP 0x0D
typedef struct _EFI_IFR_RESET_BUTTON {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_STATEMENT_HEADER Statement;
    EFI_DEFAULT_ID DefaultId;
} EFI_IFR_RESET_BUTTON;

typedef UINT16 EFI_DEFAULT_ID;

Members

Header
The standard header, where Header.OpCode = EFI_IFR_RESET_BUTTON_OP.

Statement
Standard statement header, including the prompt and help text.

DefaultId
Specifies the set of default store to use when restoring the defaults to the questions on this form. xxxx See EFI_IFR_DEFAULTSTORE for more information.

Description
This opcode creates a user-selectable button that resets the question values for all questions on the current form to the default values specified by DefaultId. If EFI_IFR_FLAGS_CALLBACK is set in the question header, then the callback associated with the form set will be called. An image may be associated with the statement using a nested EFI_IFR_IMAGE. An animation may be associated with the statement using a nested EFI_IFR_ANIMATION.

33.3.8.3.63 EFI_IFR_RULE

Summary
Create a rule for use in a form and associate it with an identifier.

Prototype

```c
#define EFI_IFR_RULE_OP 0x18
typedef struct _EFI_IFR_RULE {
    EFI_IFR_OP_HEADER Header;
    UINT8 RuleId;
} EFI_IFR_RULE;
```

Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined. Header.OpCode = EFI_IFR_RULE_OP.

RuleId
Unique identifier for the rule. There can only one rule within a form with the specified RuleId. If another already exists, then the form is marked as invalid.

Description
Create a rule, which associates an expression with an identifier and attaches it to the currently opened form. These rules allow common sub-expressions to be re-used within a form.
33.3.8.3.64  EFI_IFR_RULE_REF

Summary
Evaluate a form rule and push its result on the expression stack.

Prototype

```c
#define EFI_IFR_RULE_REF_OP 0x3f
typedef struct _EFI_IFR_RULE_REF {
    EFI_IFR_OP_HEADER Header;
    UINT8 RuleId;
} EFI_IFR_RULE_REF;
```

Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined. 

RuleId
The rule’s identifier, which must be unique within the form.

Description
Look up the rule specified by `RuleId` and push the evaluated result on the expression stack. If the specified rule does not exist, then push Undefined.

33.3.8.3.65  EFI_IFR_SECURITY

Summary
Push `TRUE` if the current user profile contains the specified setup access permissions.

Prototype

```c
#define EFI_IFR_SECURITY_OP 0x60
typedef struct _EFI_IFR_SECURITY {
    EFI_IFR_OP_HEADER Header;
    EFI_GUID Permissions;
} EFI_IFR_SECURITY;
```

Members

Header

Permissions
Security permission level.

Description
This opcode pushes whether or not the current user profile contains the specified setup access permissions. This opcode can be used in expressions to disable, suppress or gray-out forms, statements and questions. It can also be used in checking question values to disallow or allow certain values.

This opcode performs the following actions:

1. If the current user profile contains the specified setup access permissions, then push `TRUE`. Otherwise, push `FALSE`.*
### 33.3.8.3.66 EFI_IFR_SET

**Summary**

Change a stored value.

**Prototype**

```c
#define EFI_IFR_SET_OP 0x2C
typedef struct _EFI_IFR_SET {
    EFI_IFR_OP_HEADER Header;
    EFI_VARSTORE_ID VarstoreId;
    union {
        EFI_STRING_ID VarName;
        UINT16 VarOffset;
    }
    VarStoreInfo;
    UINT8 VarStoreType;
} EFI_IFR_SET;
```

**Parameters**

**Header**

The sequence that defines the type of opcode as well as the length of the opcode being defined. `Header.OpCode = EFI_IFR_SET_OP`.

**VarStoreId**

Specifies the identifier of a previously declared variable store to use when storing the question’s value.

**VarStoreInfo**

Depending on the type of variable store selected, this contains either a 16-bit Buffer Storage offset (`VarOffset`) or a Name/Value or EFI Variable name (`VarName`).

**VarStoreType**

Specifies the type used for storage. The storage types `EFI_IFR_TYPE_x` are defined in `EFI_IFR_ONE_OF_OPTION`.

**Description**

This operator pops an expression from the expression stack. The expression popped is the value.

The value is stored into the variable store identified by `VarstoreId` and `VarStoreInfo`.

If the value could be stored successfully, then `TRUE` is pushed on to the expression stack. Otherwise, `FALSE` is pushed on the expression stack.

### 33.3.8.3.67 EFI_IFR_SHIFT_LEFT

**Summary**

Pop two unsigned integers, shift one left by the number of bits specified by the other and push the result.

**Prototype**

```c
#define EFI_IFR_SHIFT_LEFT_OP 0x38
typedef struct _EFI_IFR_SHIFT_LEFT {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_SHIFT_LEFT;
```
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

Header
Standard opcode header, where OpCode is EFI_IFR_SHIFT_LEFT _OP.

Description
This opcode performs the following actions:

1. Pop two values from the expression stack. The first value popped is the right-hand value and the second value popped is the left-hand value.
2. If the two values do not evaluate to unsigned integers, push Undefined.
3. Shift the left-hand value left by the number of bits specified by the right-hand value and push the result.

33.3.8.3.68 EFI_IFR_SHIFT_RIGHT

Summary
Pop two unsigned integers, shift one right by the number of bits specified by the other and push the result.

Prototype

```c
#define EFI_IFR_SHIFT_RIGHT_OP 0x39
typedef struct _EFI_IFR_SHIFT_RIGHT {
  EFI_IFR_OP_HEADER Header;
} EFI_IFR_SHIFT_RIGHT;
```

Members

Header
Standard opcode header, where OpCode is EFI_IFR_SHIFT_RIGHT _OP.

Description
This opcode performs the following actions:

1. Pop two values from the expression stack. The first value popped is the right-hand value and the second value popped is the left-hand value.
2. If the two values do not evaluate to unsigned integers, push Undefined.
3. Shift the left-hand value right by the number of bits specified by the right-hand value and push the result.

33.3.8.3.69 EFI_IFR_SPAN

Summary
Pop two strings and an unsigned integer, find the first character from one string that contains characters found in another and push its index.

Prototype

```c
#define EFI_IFR_SPAN_OP 0x59
typedef struct _EFI_IFR_SPAN {
  EFI_IFR_OP_HEADER Header;
  UINT8 Flags;
} EFI_IFR_SPAN;
```

Members

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Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, 
Header.OpCode = EFI_IFR_SPAN_OP.

Flags
Specifies whether to find the first matching string (EFI_IFR_FLAGS_FIRST_MATCHING) or the first non-
matching string (EFI_IFR_FLAGS_FIRST_NON_MATCHING).

Description
This opcode performs the following actions:
1. Pop three values from the expression stack. The first value popped is the right value and the second value popped
   is the middle value and the last value popped is the left expression.
2. If the left or middle values cannot be evaluated as a string, push Undefined. If the right value cannot be evaluated
   as an unsigned integer, push Undefined.
3. The left string is the string to scan. The middle string consists of character pairs representing the low-end of a
   range and the high-end of a range of characters. The right unsigned integer represents the starting location for
   the scan.
4. The operation will push the zero-based index of the first character after the right value which falls within
   any one of the ranges (EFI_IFR_FLAGS_FIRST_MATCHING) or falls within none of the ranges
   (EFI_IFR_FLAGS_FIRST_NON_MATCHING).

Related Definitions
#define EFI_IFR_FLAGS_FIRST_MATCHING 0x00
#define EFI_IFR_FLAGS_FIRST_NON_MATCHING 0x01

33.3.8.3.70 EFI_IFR_STRING

Summary
Defines the string question.

Prototype
#define EFI_IFR_STRING_OP 0x1C
typedef struct _EFI_IFR_STRING {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_QUESTION_HEADER Question;
    UINT8 MinSize;
    UINT8 MaxSize;
    UINT8 Flags;
} EFI_IFR_STRING;

Members
Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. Header.OpCode
= EFI_IFR_STRING_OP.

Question
The standard question header. xxxx See EFI_IFR_QUESTION_HEADER for more information.
MinSize
The minimum number of characters that can be accepted for this opcode.

MaxSize
The maximum number of characters that can be accepted for this opcode.

Flags
Flags which control the string editing behavior. See “Related Definitions” below.

Description
This creates a string question. The minimum length is MinSize and the maximum length is MaxSize characters.

An image may be associated with the question using a nested EFI_IFR_IMAGE. An animation may be associated with the question using a nested EFI_IFR_ANIMATION.

There are two ways to specify defaults for this question: one or more nested EFI_IFR_ONE_OF_OPTION (lowest priority) or nested EFI_IFR_DEFAULT (highest priority).

If EFI_IFR_STRING_MULTI_LINE is set, it is a hint to the Forms Browser that multi-line text can be allowed. If it is clear, then multi-line editing should not be allowed.

Related Definitions

```c
#define EFI_IFR_STRING_MULTI_LINE 0x01
```

33.3.8.3.71 EFI_IFR_STRING_REF1

Summary
Push a string on the expression stack.

Prototype

```c
#define EFI_IFR_STRING_REF1_OP 0x4e
typedef struct _EFI_IFR_STRING_REF1 {
    EFI_IFR_OP_HEADER Header;
    EFI_STRING_ID StringId;
} EFI_IFR_STRING_REF1;
```

Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined. Header.OpCode = EFI_IFR_STRING_REF1_OP.

StringId
The string’s identifier, which must be unique within the package list.

Description
Push the string specified by StringId on to the expression stack. If the string does not exist, then push an empty string.
33.3.8.3.72 EFI_IFR_STRING_REF2

Summary
Pop a string identifier, push the associated string.

Prototype

```c
#define EFI_IFR_STRING_REF2_OP 0x4f
typedef struct _EFI_IFR_STRING_REF2 {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_STRING_REF2;
```

Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined.  

Description
This opcode performs the following actions:
1. Pop a value from the expression stack.
2. If the value cannot be evaluated as an unsigned integer or the value of the unsigned integer is greater than 0xFFFF, push Undefined.
3. If the string specified by the value (converted to a string identifier) cannot be determined or the string does not exist, push an empty string.
4. Otherwise, push the string on to the expression stack.

33.3.8.3.73 EFI_IFR_SUBTITLE

Summary
Creates a sub-title in the current form.

Prototype

```c
#define EFI_IFR_SUBTITLE_OP 0x02
typedef struct _EFI_IFR_SUBTITLE {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_STATEMENT_HEADER Statement;
    UINT8 Flags;
} EFI_IFR_SUBTITLE;
```

Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_SUBTITLE_OP`.

Flags
Identifies specific behavior for the sub-title.

Description
Subtitle strings are intended to be used by authors to separate sections of questions into semantic groups. If Header.Scope is set, then the Forms Browser may further distinguish the end of the semantic group as including only those statements and questions which are nested.

If EFI_IFR_FLAGS_HORIZONTAL is set, then this provides a hint that the nested statements or questions should be horizontally arranged. Otherwise, they are assumed to be vertically arranged.

An image may be associated with the statement using a nested EFI_IFR_IMAGE. An animation may be associated with the statement using a nested EFI_IFR_ANIMATION.

Related Definitions

```
define EFI_IFR_FLAGS_HORIZONTAL 0x01
```

### 33.3.8.3.74 EFI_IFR_SUBTRACT

**Summary**

Pop two unsigned integers, subtract one from the other, push the result.

**Prototype**

```
define EFI_IFR_SUBTRACT_OP 0x3b
typedef struct _EFI_IFR_SUBTRACT {
    EFI_IFR_OP_HEADER                  Header;
} EFI_IFR_SUBTRACT;
```

**Members**

**Header**

Standard opcode header, where Header.OpCode is EFI_IFR_SUBTRACT _OP.

**Description**

This opcode performs the following operations:

1. Pop two values from the expression stack. The first value popped is the right-hand value and the second value popped is the left-hand value.
2. If the two values do not evaluate to unsigned integers, push Undefined.
3. Zero-extend the values to 64-bits.
4. Subtract the right-hand value from the left-hand value.
5. Push the lower 64-bits of the result.

### 33.3.8.3.75 EFI_IFR_SUPPRESS_IF

**Summary**

Creates a group of statements or questions which are conditionally invisible.

**Prototype**

```
define EFI_IFR_SUPPRESS_IF_OP 0x0a
typedef struct _EFI_IFR_SUPPRESS_IF {
    EFI_IFR_OP_HEADER                  Header;
} EFI_IFR_SUPPRESS_IF;
```
Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined.

\[ Header.\text{OpCode} = \text{EFI_IFR_SUPPRESS_IF_OP}. \]

Description
The suppress tag causes the nested objects to be hidden from the user if the expression appearing as the first nested object evaluates to \textit{TRUE}. If the expression consists of more than a single opcode, then the first opcode in the expression must have the Scope bit set and the expression must end with \textit{EFI_IFR_END}.

This display form is maintained until the scope for this opcode is closed.

33.3.8.3.76 EFI_IFR_TEXT

Summary
Creates a static text and image.

Prototype

```c
#define EFI_IFR_TEXT_OP 0x03
typedef struct _EFI_IFR_TEXT {
    EFI_IFR_OP_HEADER Header;
    EFI_IFR_STATEMENT_HEADER Statement;
    EFI_STRING_ID TextTwo;
} EFI_IFR_TEXT;
```

Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag,

\[ Header.\text{OpCode} = \text{EFI_IFR_TEXT_OP}. \]

Statement
Standard statement header.

TextTwo
The string token reference to the secondary string for this opcode.

Description
This is a static text/image statement.

An image may be associated with the statement using a nested \textit{EFI_IFR_IMAGE}. An animation may be associated with the question using a nested \textit{EFI_IFR_ANIMATION}.

33.3.8.3.77 EFI_IFR_THIS

Summary
Push current question’s value.

Prototype
Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_THIS_OP`.

Description
Push the current question’s value.

33.3.8.3.78 EFI_IFR_TIME

Summary
Create a Time question.

Prototype

```c
#define EFI_IFR_TIME_OP 0x1b
typedef struct _EFI_IFR_TIME {
   EFI_IFR_OP_HEADER Header;
   EFI_IFR_QUESTION_HEADER Question;
   UINT8 Flags;
} EFI_IFR_TIME;
```

Members

Header

Question
The standard question header. See `EFI_IFR_QUESTION_HEADER` for more information.

Flags
A bit-mask that determines which unique settings are active for this opcode.

QF_TIME_HOUR_SUPPRESS 0x01
QF_TIME_MINUTE_SUPPRESS 0x02
QF_TIME_SECOND_SUPPRESS 0x04
QF_TIME_STORAGE 0x30

For QF_TIME_STORAGE, there are currently three valid values:

QF_TIME_STORAGE_NORMAL 0x00
QF_TIME_STORAGE_TIME 0x10
QF_TIME_STORAGE_WAKEUP 0x20
Description
Create a Time question xxxx (Time) and add it to the current form.

An image may be associated with the question using a nestedEFI_IFR_IMAGE. An animation may be associated with the question using a nestedEFI_IFR_ANIMATION.

33.3.8.3.79 EFI_IFR_TOKEN

Summary
Pop two strings and an unsigned integer, then push the nth section of the first string using delimiters from the second string.

Prototype

```c
#define EFI_IFR_TOKEN_OP 0x4d
typedef struct _EFI_IFR_TOKEN {
  EFI_IFR_OP_HEADER Header;
} EFI_IFR_TOKEN;
```

Members

Header
Standard opcode header, where OpCode isEFI_IFR_TOKEN_OP.

Description
This opcode performs the following actions:

1. Pop three values from the expression stack. The first value popped is the right value and the second value popped is the middle value and the last value popped is the left value.

2. If the left or middle values cannot be evaluated as a string, push Undefined. If the right value cannot be evaluated as an unsigned integer, push Undefined.

3. The first value is the string. The second value is a string, where each character is a valid delimiter. The third value is the zero-based index.

4. Push the nth delimited sub-string on to the expression stack (0 = left of the first delimiter). The end of the string always acts a the final delimiter.

5. The no such string exists, an empty string is pushed.

33.3.8.3.80 EFI_IFR_TO_BOOLEAN

Summary
Pop a value, convert to Boolean and push the result.

Prototype

```c
#define EFI_IFR_TO_BOOLEAN_OP 0x4A
typedef struct _EFI_IFR_TO_BOOLEAN{
  EFI_IFR_OP_HEADER Header;
} EFI_IFR_TO_BOOLEAN;
```

Members
### Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_TO_BOOLEAN_OP`

### Description
This opcode performs the following actions:

1. Pop a value from the expression stack. If the value is Undefined or cannot be evaluated as a Boolean, push Undefined. Otherwise, push the Boolean on the expression stack.

2. When converting from an unsigned integer, zero will be converted to `FALSE` and any other value will be converted to `TRUE`.

3. When converting from a string, if case-insensitive compare with “true” is `True`, then push `TRUE`. If a case-insensitive compare with “false” is `TRUE`, then push `FALSE`. Otherwise, push Undefined.

4. When converting from a buffer, if the buffer is all zeroes, then push `FALSE`. Otherwise push `TRUE`.

#### 33.3.8.3.81 EFI_IFR_TO_LOWER

**Summary**
Convert a string on the expression stack to lower case.

**Prototype**
```c
#define EFI_IFR_TO_LOWER_OP 0x20
typedef struct _EFI_IFR_TO_LOWER {
    EFI_IFR_OP_HEADER        Header;
    EFI_IFR_TO_LOWER;
} EFI_IFR_TO_LOWER;
```

**Members**

- **Header**
  The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_TO_LOWER_OP`

**Description**
Pop an expression from the expression stack. If the expression is Undefined or cannot be evaluated as a string, push Undefined. Otherwise, convert the string to all lower case using the `StrLwr` function of the `EFI_UNICODE_COLLATION2_PROTOCOL` and push the string on the expression stack.

#### 33.3.8.3.82 EFI_IFR_TO_STRING

**Summary**
Pop a value, convert to a string, push the result.

**Prototype**
```c
#define EFI_IFR_TO_STRING_OP 0x49
typedef struct _EFI_IFR_TO_STRING{
    EFI_IFR_OP_HEADER        Header;
    UINT8 Format;
} EFI_IFR_TO_STRING;
```

**Members**

---

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Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_TO_STRING_OP`

Format

When converting from unsigned integers, these flags control the format:

- 0 = unsigned decimal
- 1 = signed decimal
- 2 = hexadecimal (lower-case alpha)
- 3 = hexadecimal (upper-case alpha)

When converting from a buffer, these flags control the format:

- 0 = ASCII
- 8 = UCS-2

Description

This opcode performs the following actions:

1. Pop a value from the expression stack.**

# If the value is Undefined or cannot be evaluated as a string, push Undefined.

1. Convert the value to a string. When converting from an unsigned integer, the number will be converted to an unsigned decimal string (Format = 0), signed decimal string (Format = 1) or a hexadecimal string (Format = 2 or 3).

When converting from a boolean, the boolean will be converted to “True” (True) or “False” (False). When converting from a buffer, each 8-bit (Format = 0) or 16-bit (Format = 8) value will be converted into a character and appended to the string, up until the end of the buffer or a NULL character. 4. Push the result.

### 33.3.8.3.83 EFI_IFR_TO_UINT

**Summary**

Pop a value, convert to an unsigned integer, push the result.

**Prototype**

```c
#define EFI_IFR_TO_UINT_OP 0x48
typedef struct _EFI_IFR_TO_UINT {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_TO_UINT;
```

**Members**

**Header**

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_TO_UINT_OP`
Description

1. Pop a value from the expression stack.
2. If the value is Undefined or cannot be evaluated as an unsigned integer, push Undefined.
3. Convert the value to an unsigned integer. When converting from a boolean, if TRUE, push 1 and if FALSE, push 0. When converting from a string, whitespace is skipped. The prefix ‘0x’ or ‘0X’ indicates to convert from a hexadecimal string while the prefix ‘-’ indicates conversion from a signed integer string. When converting from a buffer, if the buffer is greater than 8 bytes in length, push Undefined. Otherwise, zero-extend the contents of the buffer to 64-bits.
4. Push the result.

33.3.8.3.84 EFI_IFR_TO_UPPER

Summary

Convert a string on the expression stack to upper case.

Prototype

```c
#define EFI_IFR_TO_UPPER_OP 0x21
typedef struct _EFI_IFR_TO_UPPER {
   EFI_IFR_OP_HEADER Header;
} EFI_IFR_TO_UPPER;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_TO_UPPER_OP`

Description

Pop an expression from the expression stack. If the expression is Undefined or cannot be evaluated as a string, push Undefined. Otherwise, convert the string to all upper case using the StrUpr function of the EFI_UNICODE_COLLATION2_PROTOCOL and push the string on the expression stack.

33.3.8.3.85 EFI_IFR_TRUE

Summary

Push a TRUE on to the expression stack.

Prototype

```c
#define EFI_IFR_TRUE_OP 0x46
typedef struct _EFI_IFR_TRUE {
   EFI_IFR_OP_HEADER Header;
} EFI_IFR_TRUE;
```

Members

Header

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_TRUE_OP`
Description
Push a TRUE on to the expression stack.

33.3.8.3.86 EFI_IFR_UINT8, EFI_IFR_UINT16, EFI_IFR_UINT32, EFI_IFR_UINT64

Summary
Push an unsigned integer on to the expression stack.

Prototype

```c
#define EFI_IFR_UINT8_OP 0x42
typedef struct _EFI_IFR_UINT8 {
  EFI_IFR_OP_HEADER Header;
  UINT8 Value;
} EFI_IFR_UINT8;

#define EFI_IFR_UINT16_OP 0x43
typedef struct _EFI_IFR_UINT16 {
  EFI_IFR_OP_HEADER Header;
  UINT16 Value;
} EFI_IFR_UINT16;

#define EFI_IFR_UINT32_OP 0x44
typedef struct _EFI_IFR_UINT32 {
  EFI_IFR_OP_HEADER Header;
  UINT32 Value;
} EFI_IFR_UINT32;

#define EFI_IFR_UINT64_OP 0x45
typedef struct _EFI_IFR_UINT64 {
  EFI_IFR_OP_HEADER Header;
  UINT64 Value;
} EFI_IFR_UINT64;
```

Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_UINT8_OP, EFI_IFR_UINT16_OP, EFI_IFR_UINT32_OP` or `EFI_IFR_UINT64_OP`.

Value
The unsigned integer.

Description
Push the specified unsigned integer, zero-extended to 64-bits, on to the expression stack.
33.3.8.3.87 EFI_IFR_UNDEFINED

Summary
Push an Undefined to the expression stack.

Prototype

```c
#define EFI_IFR_UNDEFINED_OP 0x55
typedef struct _EFI_IFR_UNDEFINED {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_UNDEFINED;
```

Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_UNDEFINED_OP`

Description
Push Undefined on to the expression stack.

33.3.8.3.88 EFI_IFR_VALUE

Summary
Provides a value for the current question or default.

Prototype

```c
#define EFI_IFR_VALUE_OP 0x5a
typedef struct _EFI_IFR_VALUE {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_VALUE;
```

Members

Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_VALUE_OP`

Description
Creates a value for the current question or default with no storage. The value is the result of the expression nested in the scope.

If used for a question, then the question will be read-only.
33.3.8.3.89 EFI_IFR_VARSTORE

Summary
Creates a variable storage short-cut for linear buffer storage.

Prototype

```
#define EFI_IFR_VARSTORE_OP 0x24
typedef struct {
  EFI_IFR_OP_HEADER Header;
  EFI_GUID Guid;
  EFI_VARSTORE_ID VarStoreId;
  UINT16 Size;
  //UINT8 Name[];
} EFI_IFR_VARSTORE;
```

Members

**Header**
The byte sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_VARSTORE_OP`.

**Guid**
The variable’s GUID definition. This field comprises one half of the variable name, with the other half being the human-readable aspect of the name, which is represented by the string immediately following the Size field. Type `EFI_GUID` is defined in `InstallProtocolInterface()` in this specification.

**VarStoreId**
The variable store identifier, which is unique within the current form set. This field is the value that uniquely identify this instance from others. Question headers refer to this value to designate which is the active variable that is being used. A value of zero is invalid.

**Size**
The size of the variable store.

**Name**
A null-terminated ASCII string that specifies the name associated with the variable store. The field is not actually included in the structure but is included here to help illustrate the encoding of the opcode. The size of the string, including the null termination, is included in the opcode’s header size.

Description
This opcode describes a Buffer Storage Variable Store within a form set. A question can select this variable store by setting the `VarStoreId` field in its opcode header.

An `EFI_IFR_VARSTORE` with a specified `VarStoreId` must appear in the IFR before it can be referenced by a question.

33.3.8.3.90 EFI_IFR_VARSTORE_NAME_VALUE

Summary
Creates a variable storage short-cut for name/value storage.

Prototype

```
#define EFI_IFR_VARSTORE_NAME_VALUE_OP 0x25
typedef struct _EFI_IFR_VARSTORE_NAME_VALUE {
```

(continues on next page)
Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, 
Header.OpCode = EFI_IFR_VARSTORE_NAME_VALUE_OP.

Guid
The variable’s GUID definition. This field comprises one half of the variable name, with the other half being 
the human-readable aspect of the name, which is specified in the VariableName field in the question’s header 
(see EFI_IFR_QUESTION_HEADER). Type EFI_GUID is defined in InstallProtocolInterface() in the UEFI Specification.

VarStoreId
The variable store identifier, which is unique within the current form set. This field is the value that uniquely 
identifies this variable store definition instance from others. Question headers refer to this value to designate 
which is the active variable that is being used. A value of zero is invalid.

33.3.8.3.91 EFI_IFR_VARSTORE_EFI

Summary
Creates a variable storage short-cut for EFI variable storage.

Prototype

```c
#define EFI_IFR_VARSTORE_EFI_OP 0x26
typedef struct _EFI_IFR_VARSTORE_EFI {
    EFI_IFR_OP_HEADER Header;
    EFI_VARSTORE_ID VarStoreId;
    EFI_GUID Guid;
    UINT32 Attributes
    UINT16 Size;
    //UINT8 Name[];
} EFI_IFR_VARSTORE_EFI;
```

Members

Header
The byte sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, 
Header.OpCode = EFI_IFR_VARSTORE_EFI_OP.

VarStoreId
The variable store identifier, which is unique within the current form set. This field is the value that uniquely
identifies this variable store definition instance from others. Question headers refer to this value to designate which is the active variable that is being used. A value of zero is invalid.

**Guid**

The EFI variable’s GUID definition. This field comprises one half of the EFI variable name, with the other half being the human-readable aspect of the name, which is specified in the Name field below. Type EFI_GUID is defined in InstallProtocolInterface() in this specification.

**Attributes**

Specifies the flags to use for the variable.

**Size**

The size of the variable store.

**Name**

A null-terminated ASCII string that specifies one half of the EFI name for this variable store. The other half is specified in the Guid field (above). The Name field is not actually included in the structure but is included here to help illustrate the encoding of the opcode. The size of the string, including the null termination, is included in the opcode’s header size.

**Description**

This opcode describes an EFI Variable Variable Store within a form set. The Guid and Name specified here will be used with GetVariable() and SetVariable().

- A question can select this variable store by setting the VarStoreId field in its question header.
- A question can refer to a specific offset within the EFI Variable using the VarOffset field in its question header.
- Name must be converted to a CHAR16 string before it is passed to GetVariable() or SetVariable(). An EFI_IFR_VARSTORE_EFI with a specified VarStoreId must appear in the IFR before it can be referenced by a question.

### 33.3.8.3.92 EFI_IFR_VARSTORE_DEVICE

**Summary**

Select the device which contains the variable store.

**Prototype**

```c
#define EFI_IFR_VARSTORE_DEVICE_OP 0x27
typedef struct _EFI_IFR_VARSTORE_DEVICE {
    EFI_IFR_OP_HEADER Header;
    EFI_STRING_ID DevicePath;
} EFI_IFR_VARSTORE_DEVICE;
```

**Members**

**Header**

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, Header.OpCode = EFI_IFR_VARSTOREDEVICE_OP.

**DevicePath**

Specifies the string which contains the device path of the device where the variable store resides.

**Description**

This opcode describes the device path where a variable store resides. Normally, the Forms Processor finds the variable store on the handle specified when the HII database function NewPackageList() was called. However, if this opcode is found in the scope of a question, the handle specified by the text device path DevicePath is used instead.
33.3.8.3.93 EFI_IFR_VERSION

Summary
Push the version of the UEFI specification to which the Forms Processor conforms.

Prototype
```
#define EFI_IFR_VERSION_OP 0x28
typedef struct _EFI_IFR_VERSION {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_VERSION;
```

Members
Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_VERSION_OP`.

Description
Returns the revision level of the UEFI specification with which the Forms Processor is compliant as a 16-bit unsigned integer, with the form:

- [15:8] Major revision
- [7:4] Tens digit of the minor revision
- [3:0] Ones digit of the minor revision

The fields of the version have the following correlation with the revision of the UEFI system table.

- Major revision: `EFI_SYSTEM_TABLE_REVISION >> 16`
- Tens digit of the minor revision: `(EFI_SYSTEM_TABLE_REVISION & 0xFFFF)/10`
- Ones digit of the minor revision: `(EFI_SYSTEM_TABLE_REVISION & 0xFFFF)%10`

33.3.8.3.94 EFI_IFR_WRITE

Summary
Change a value for the current question.

Prototype
```
#define EFI_IFR_WRITE_OP 0x2E
typedef struct _EFI_IFR_WRITE {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_WRITE;
```

Parameters
Header
The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, `Header.OpCode = EFI_IFR_WRITE_OP`.

Description
Before writing the value of the current question to storage (if any storage was specified), the \textit{this} constant is set (see \texttt{EFI_IFR_THIS}) and then this expression is evaluated.

### 33.3.8.3.95 EFI_IFR ZERO

**Summary**

Push a zero on to the expression stack.

**Prototype**

```c
#define EFI_IFR_ZERO_OP 0x52
typedef struct _EFI_IFR_ZERO {
    EFI_IFR_OP_HEADER Header;
} EFI_IFR_ZERO;
```

**Members**

**Header**

The sequence that defines the type of opcode as well as the length of the opcode being defined. For this tag, \texttt{Header.OpCode = EFI_IFR_ZERO_OP}.

**Description**

Push a zero on to the expression stack.

### 33.3.8.3.96 EFI_IFR WARNING IF

**Summary**

Creates a validation expression and warning message for a question.

**Prototype**

```c
#define EFI_IFR_WARNING_IF_OP 0x063
typedef struct _EFI_IFR_WARNING_IF {
    EFI_IFR_OP_HEADER Header;
    EFI_STRING_ID Warning;
    UINT8 TimeOut;
} EFI_IFR_WARNING_IF;
```

**Members**

**Header**

The byte sequence that defines the type of opcode as well as the length of the opcode being defined. \texttt{Header.OpCode = EFI_IFR_WARNING_IF_OP}.

**Warning**

The string token reference to the string that will be used for the warning check message.

**TimeOut**

The number of seconds for the warning message to be displayed before it is timed out or acknowledged by the user. A value of zero indicates that the message is displayed indefinitely until the user acknowledges it.

**Description**

This tag uses a Boolean expression to allow the IFR creator to check options in a question, and provide a warning message if the expression is \texttt{TRUE}. For example, this tag might be used to give a warning if the user attempts to
disable a security setting, or change the value of a sensitive question. The tag provides a string to be used in a warning
display to alert the user of the consequences of changing the question value. Warning tags will be evaluated when
the user traverses from tag to tag. The browser must display the warning text message and not allow the form to be
submitted until either the user acknowledges the message (with some key press for instance) or the number of seconds
in TimeOut elapses. Unlike inconsistency tags, the user should still be allowed to submit the results of a form even if
the warning expression evaluates to TRUE.

### 33.3.8.3.97 EFI_IFR_MATCH2

**Summary**

Pop a source string and a pattern string, push **TRUE** if the source string matches the Regular Expression pattern
specified by the pattern string, otherwise push **FALSE**.

**Prototype**

```c
#define EFI_IFR_MATCH2_OP 0x64
typedef struct _EFI_IFR_MATCH2 {
    EFI_IFR_OP_HEADER Header;
    EFI_GUID SyntaxType;
} EFI_IFR_MATCH2;
```

**Members**

**Header**

Standard opcode header, where `Header.Opcode` is `EFI_IFR_MATCH2_OP`.

**SyntaxType**

A GUID that identifies the regular expression syntax type to use for the *pattern* string. See `EFI_REGULAR_EXPRESSION_PROTOCOL` for current syntax definitions.

**Description**

This opcode performs the following actions:

1. Pop two values from the expression stack. The first value popped is the *string* and the second value popped is the
   *pattern*.
2. If the *string* or the *pattern* cannot be evaluated as a string, then push Undefined.
3. Call `GetInfo` function of each instance of `EFI_REGULAR_EXPRESSION_PROTOCOL`, looking for a `SyntaxType`
   that is listed in the set of supported regular expression syntax types returned by `RegExSyntaxTypeList`. If the type
   specified by `SyntaxType` is not supported in any of the `EFI_REGULAR_EXPRESSION_PROTOCOL` instances,
   or no `EFI_REGULAR_EXPRESSION_PROTOCOL` instance was found, push Undefined.
4. Process the *string* and *pattern* using the `MatchString` function of the `EFI_REGULAR_EXPRESSION_PROTOCOL` instance that supports the `SyntaxType`, where `SyntaxType` is the `SyntaxType` input to `MatchString`.
5. If the returned regular expression `Result` is **TRUE**, then push **TRUE**.
6. If the return regular expression `Result` is **FALSE**, then push **FALSE**.

**NOTE:** To ensure interoperability, drivers that publish HII IFR Forms packages should check the system capabilities by calling the `GetInfo` function of each `EFI_REGULAR_EXPRESSION_PROTOCOL` instance during initialization. If the required regular expression syntax type is not supported, the driver may install its own instance of `EFI_REGULAR_EXPRESSION_PROTOCOL` to add the support. The driver may also choose to fall back to other methods of validation, such as using `EFI_IFR_MATCH` or callbacks.
## 33.3.9 Keyboard Package

```c
typedef struct {
    EFI_HII_PACKAGE_HDR Header;
    UINT16 LayoutCount;
    EFI_HII_KEYBOARD_LAYOUT Layout[];
} EFI_HII_KEYBOARD_PACKAGE_HDR;
```

### Header
The general pack header which defines both the type of pack and the length of the entire pack.

### LayoutCount
The number of keyboard layouts contained in the entire keyboard pack.

### Layout
An array of `LayoutCount` number of keyboard layouts.

## 33.3.10 Animations Package

The Animation package record describes how, when, and which EFI images to display. The package consists of two parts: a fixed header and the animation information.

### 33.3.10.1 Animated Images Package

#### Summary
The fixed header consists of a standard record header and the

#### Prototype
```c
typedef struct _EFI_HII_ANIMATION_PACKAGE_HDR {
    EFI_HII_ANIMATION_PACKAGE Header;
    UINT32 AnimationInfoOffset;
} EFI_HII_ANIMATION_PACKAGE_HDR;
```

#### Members

##### Header
Standard image header, where `Header.BlockType = EFI_HII_PACKAGE_ANIMATIONS`.

##### AnimationInfoOffset
Offset, relative to this header, of the animation information. If this is zero, then there are no animation sequences in the package.
33.3.10.2 Animation Information

For each animated image identifier, the animation information gives a sequence of EFI images to display and how and when to transition to the next image. The animation information is encoded as a series of blocks, with each block prefixed by a single byte header (EFI_HII_ANIMATION_BLOCK) or one of the extension headers (EFI_HII_AIBT_EXTx_BLOCK). The blocks must be processed in order.

![Animation Information Encoded in Blocks](image)

**Prototype**

```c
typedef struct _EFI_HII_ANIMATION_BLOCK {
    UINT8 BlockType;
    //UINT8 BlockBody[];
} EFI_HII_ANIMATION_BLOCK;
```

The following table describes the different block types:

<table>
<thead>
<tr>
<th>Name</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_HII_AIBT_END</td>
<td>0x00</td>
<td>The end of the animation information.</td>
</tr>
<tr>
<td>EFI_HII_AIBT_OVERLAY_IMAGES</td>
<td>0x10</td>
<td>Animate sequence once by displaying the next image in the logical window.</td>
</tr>
<tr>
<td>EFI_HII_AIBT_CLEAR_IMAGES</td>
<td>0x11</td>
<td>Animate sequence once by clearing the logical window before displaying the next image.</td>
</tr>
<tr>
<td>EFI_HII_AIBT_RESTORE_SCRN</td>
<td>0x12</td>
<td>Animate sequence once by clearing the restoring the logical window before displaying the next image.</td>
</tr>
<tr>
<td>EFI_HII_AIBT_OVERLAY_IMAGES_LOOP</td>
<td>0x18</td>
<td>Animate repeating sequence by displaying the next image in the logical window.</td>
</tr>
</tbody>
</table>

continues on next page
In order to recreate all animation sequences, start at the first block and process them all until either an EFI_HII_AIBT_END block is found. When processing the animation blocks, each block refers to the current animation identifier ($AnimationIdCurrent$), which is initially set to one (1).

Animation blocks of an unknown type should be skipped. If they cannot be skipped, then processing halts.

### 33.3.10.2.1 EFI_HII_AIBT_END

**Summary**

Marks the end of the animation information.

**Prototype**

None

**Members**

**Header**

Standard animation header, where $Header.BlockType = EFI_HII_AIBT_END$.

**Discussion**

Any animation sequences with an animation identifier greater than or equal to $AnimationIdCurrent$ are empty. There is no additional data.

### 33.3.10.2.2 EFI_HII_AIBT_EXT1, EFI_HII_AIBT_EXT2, EFI_HII_AIBT_EXT4

**Summary**

Generic prefix for animation information with a 1-byte, 2-byte or 4-byte length.

**Prototype**

```c
typedef struct _EFI_HII_AIBT_EXT1_BLOCK {
    EFI_HII_ANIMATION_BLOCK Header;
    UINT8 BlockType2;
    UINT8 Length;
} EFI_HII_AIBT_EXT1_BLOCK;
```
typedef struct _EFI_HII_AIBT_EXT2_BLOCK {
    EFI_HII_ANIMATION_BLOCK Header;
    UINT8 BlockType2;
    UINT16 Length;
} EFI_HII_AIBT_EXT2_BLOCK;

typedef struct _EFI_HII_AIBT_EXT4_BLOCK {
    EFI_HII_ANIMATION_BLOCK Header;
    UINT8 BlockType2;
    UINT32 Length;
} EFI_HII_AIBT_EXT4_BLOCK;

Members

Header
    Standard animation header, where Header.BlockType = EFI_HII_AIBT_EXT1, EFI_HII_AIBT_EXT2, or
    EFI_HII_AIBT_EXT4.

Length
    Size of the animation block, in bytes, including the animation block header.

BlockType2
    The block type, as described in Table 33-9 :ref:`TODO LINK 81028 in HII.rst`

Discussion
    These records are used for variable sized animation records which need an explicit length.

33.3.10.2.3 EFI_HII_AIBT_OVERLAY_IMAGES

Summary
An animation block to describe an animation sequence that does not cycle, and where one image is simply displayed
over the previous image.

Prototype
typedef struct _EFI_HII_AIBT_OVERLAY_IMAGES_BLOCK {
    EFI_IMAGE_ID DftImageId;
    UINT16 Width;
    UINT16 Height;
    UINT16 CellCount;
    EFI_HII_ANIMATION_CELL AnimationCell[];
} EFI_HII_AIBT_OVERLAY_IMAGES_BLOCK;

Members

DftImageId
    This is image that is to be reference by the image protocols, if the animation function is not supported or disabled.
    This image can be one particular image from the animation sequence (if any one of the animation frames has a
    complete image) or an alternate image that can be displayed alone. If the value is zero, no image is displayed.

Width
    The overall width of the set of images (logical window width).
Height
The overall height of the set of images (logical window height).

CellCount
The number of \texttt{EFI\_HII\_ANIMATION\_CELL} contained in the animation sequence.

AnimationCell
An array of \texttt{CellCount} animation cells. The type \texttt{EFI\_HII\_ANIMATION\_CELL} is defined in “Related Definitions” below.

Description
This record assigns the animation sequence data to the \texttt{AnimationIdCurrent} identifier and increment \texttt{AnimationIdCurrent} by one. This animation sequence is meant to be displayed only once (it is not a repeating sequence). Each image in the sequence will remain on the screen for the specified delay before the next image in the sequence is displayed.

The header type (either \texttt{BlockType} in \texttt{EFI\_HII\_ANIMATION\_BLOCK} or \texttt{BlockType2} in \texttt{EFI\_HII\_AIBT\_EXTx\_BLOCK} ) will be set to \texttt{EFI\_HII\_AIBT\_OVERLAY\_IMAGES}.

Related Definition

\begin{verbatim}
typedef struct _EFI_HII_ANIMATION_CELL {  
    UINT16 OffsetX;  
    UINT16 OffsetY;  
    EFI_IMAGE_ID ImageId;  
    UINT16 Delay;  
} EFI_HII_ANIMATION_CELL;
\end{verbatim}

OffsetX
The X offset from the upper left hand corner of the logical window to position the indexed image.

OffsetY
The Y offset from the upper left hand corner of the logical window to position the indexed image.

ImageId
The image to display at the specified offset from the upper left hand corner of the logical window.

Delay
The number of milliseconds to delay after displaying the indexed image and before continuing on to the next linked image. If value is zero, no delay.

Related Description
The logical window definition allows the animation to be centered, even though the first image might be way off center (bounds the sequence of images). All images will be clipped to the defined logical window, since the logical window is suppose to bound all images, normally there is nothing to clip. The \texttt{DftImageId} definition allows an alternate image to be displayed if animation is currently not supported. The \texttt{DftImageId} image is to be centered in the defined logical window.

\textbf{33.3.10.2.4 EFI\_HII\_AIBT\_CLEAR\_IMAGES}

Summary
An animation block to describe an animation sequence that does not cycle, and where the logical window is cleared to the specified color before the next image is displayed.

Prototype
typedef struct _EFI_HII_AIBT_CLEAR_IMAGES_BLOCK {
    EFI_IMAGE_ID DftImageId;
    UINT16 Width;
    UINT16 Height;
    UINT16 CellCount;
    EFI_HII_RGB_PIXEL BackgndColor;
    EFI_HII_ANIMATION_CELL AnimationCell[];
} EFI_HII_AIBT_CLEAR_IMAGES_BLOCK;

Members

DftImageId
This is image that is to be reference by the image protocols, if the animation function is not supported or disabled. This image can be one particular image from the animation sequence (if any one of the animation frames has a complete image) or an alternate image that can be displayed alone. If the value is zero, no image is displayed.

Width
The overall width of the set of images (logical window width).

Height
The overall height of the set of images (logical window height).

CellCount
The number of EFI_HII_ANIMATION_CELL contained in the animation sequence.

BackgndColor
The color to clear the logical window to before displaying the indexed image.

AnimationCell
An array of CellCount animation cells. The type EFI_HII_ANIMATION_CELL is defined in “Related Definitions” in EFI_HII_AIBT_OVERLAY_IMAGES.

Description
This record assigns the animation sequence data to the AnimationIdCurrent identifier and increment AnimationIdCurrent by one. This animation sequence is meant to be displayed only once (it is not a repeating sequence). Each image in the sequence will remain on the screen for the specified delay before the logical window is cleared to the specified color (BackgndColor) and the next image is displayed. The logical window is also cleared to the specified color before displaying the DftImageId image.

The header type (either BlockType in EFI_HII_ANIMATION_BLOCK or BlockType2 in EFI_HII_AIBT_EXTx_BLOCK) will be set to EFI_HII_AIBT_CLEAR_IMAGES.
33.3.10.2.5 EFI_HII_AIBT_RESTORE_SCRN

Summary
An animation block to describe an animation sequence that does not cycle, and where the screen is restored to the original state before the next image is displayed.

Prototype

```c
typedef struct _EFI_HII_AIBT_RESTORE_SCRN_BLOCK {
    EFI_IMAGE_ID DftImageId;
    UINT16 Width;
    UINT16 Height;
    UINT16 CellCount;
    EFI_HII_ANIMATION_CELL AnimationCell[];
} EFI_HII_AIBT_RESTORE_SCRN_BLOCK;
```

Members

**DftImageId**
This is image that is to be referenced by the image protocols, if the animation function is not supported or disabled. This image can be one particular image from the animation sequence (if any one of the animation frames has a complete image) or an alternate image that can be displayed alone. If the value is zero, no image is displayed.

**Width**
The overall width of the set of images (logical window width).

**Height**
The overall height of the set of images (logical window height).

**CellCount**
The number of EFI_HII_ANIMATION_CELL contained in the animation sequence.

**AnimationCell**
An array of CellCount animation cells. The type EFI_HII_ANIMATION_CELL is defined in “Related Definitions” in EFI_HII_AIBT_OVERLAY_IMAGES.

Description
This record assigns the animation sequence data to the AnimationIdCurrent identifier and increment AnimationIdCurrent by one. This animation sequence is meant to be displayed only once (it is not a repeating sequence). Before the first image is displayed, the entire defined logical window is saved to a buffer. Then each image in the sequence will remain on the screen for the specified delay before the logical window is restored to the original state and the next image is displayed.

If memory buffers are not available to save the logical window, this structure is treated as EFI_HII_AIBT_CLEAR_IMAGES structure, with the BackgndColor value set to black.

The header type (either BlockType in EFI_HII_ANIMATION_BLOCK or BlockType2 in EFI_HII_AIBT_EXTx_BLOCK ) will be set to EFI_HII_AIBT_RESTORE_SCRN.
33.3.10.2.6 EFI_HII_AIBT_OVERLAY_IMAGES_LOOP

Summary
An animation block to describe an animation sequence that continuously cycles, and where one image is simply displayed over the previous image.

Prototype

```c
typedef EFI_HII_AIBT_OVERLAY_IMAGES_BLOCK EFI_HII_AIBT_OVERLAY_IMAGES_LOOP_BLOCK {
    EFI_IMAGE_ID DftImageId;
    UINT16 Width;
    UINT16 Height;
    UINT16 CellCount;
    EFI_HII_ANIMATION_CELL AnimationCell[];
} EFI_HII_AIBT_OVERLAY_IMAGES_LOOP_BLOCK;
```

Members

DftImageId
This is the image that is to be reference by the image protocols, if the animation function is not supported or disabled. This image can be one particular image from the animation sequence (if any one of the animation frames has a complete image) or an alternate image that can be displayed alone. If the value is zero, no image is displayed.

Width
The overall width of the set of images (logical window width).

Height
The overall height of the set of images (logical window height).

CellCount
The number of EFI_HII_ANIMATION_CELL contained in the animation sequence.

AnimationCell
An array of CellCount animation cells. The type EFI_HII_ANIMATION_CELL is defined in “Related Definitions” in EFI_HII_AIBT_OVERLAY_IMAGES.

Description
This record assigns the animation sequence data to the AnimationIdCurrent identifier and increment AnimationIdCurrent by one. This animation sequence is meant to continuously cycle until stopped or paused. Each image in the sequence will remain on the screen for the specified delay before the next image in the sequence is displayed.

The header type (either BlockType in EFI_HII_ANIMATION_BLOCK or BlockType2 in EFI_HII_AIBT_EXTx_BLOCK) will be set to EFI_HII_AIBT_OVERLAY_IMAGES_LOOP.

33.3.10.2.7 EFI_HII_AIBT_CLEAR_IMAGES_LOOP

Summary
An animation block to describe an animation sequence that continuously cycles, and where the logical window is cleared to the specified color before the next image is displayed.

Prototype

```c
typedef EFI_HII_AIBT_CLEAR_IMAGES_BLOCK EFI_HII_AIBT_CLEAR_IMAGES_LOOP_BLOCK {
    EFI_IMAGE_ID DftImageId;
    // (continues on next page)
```
Members

DftImageId
This is the image that is to be reference by the image protocols, if the animation function is not supported or disabled. This image can be one particular image from the animation sequence (if any one of the animation frames has a complete image) or an alternate image that can be displayed alone. If the value is zero, no image is displayed.

Width
The overall width of the set of images (logical window width).

Height
The overall height of the set of images (logical window height).

CellCount
The number of EFI_HII_ANIMATION_CELL contained in the animation sequence.

BackgndColor
The color to clear the logical window to before displaying the indexed image.

AnimationCell
An array of CellCount animation cells. The type EFI_HII_ANIMATION_CELL is defined in “Related Definitions” in EFI_HII_AIBT_OVERLAY_IMAGES

Description
This record assigns the animation sequence data to the AnimationIdCurrent identifier and increment AnimationIdCurrent by one. This animation sequence is meant to continuously cycle until stopped or paused. Each image in the sequence will remain on the screen for the specified delay before the logical window is cleared to the specified color (BackgndColor) and the next image is displayed. The logical window is also cleared to the specified color before displaying the DftImageId image.

The header type (either BlockType in EFI_HII_ANIMATION_BLOCK or BlockType2 in EFI_HII_AIBT_EXTx_BLOCK) will be set to EFI_HII_AIBT_CLEAR IMAGES_LOOP.

33.3.10.2.8 EFI_AIBT_RESTORE_SCRN_LOOP

Summary
An animation block to describe an animation sequence that continuously cycles, and where the screen is restored to the original state before the next image is displayed.

Prototype

```c
typedef EFI_HII_AIBT_RESTORE_SCRN_LOOP_BLOCK
EFI_HII_AIBT_RESTORE_SCRN_LOOP_BLOCK {
    EFI_IMAGE_ID DftImageId;
    UINT16 Width;
    UINT16 Height;
    UINT16 CellCount;
}
```
Members

Header
Standard image header, where Header.BlockType = EFI_HII_AIBT_RESTORE_SCRN_LOOP.

DftImageId
This is an image that is to be referenced by the image protocols, if the animation function is not supported or disabled. This image can be one particular image from the animation sequence (if any one of the animation frames has a complete image) or an alternate image that can be displayed alone. If the value is zero, no image is displayed.

Length
Size of the animation block, in bytes, including the animation block header.

Width
The overall width of the set of images (logical window width).

Height
The overall height of the set of images (logical window height).

CellCount
The number of EFI_HII_ANIMATION_CELL contained in the animation sequence.

AnimationCell
An array of CellCount animation cells. The type EFI_HII_ANIMATION_CELL is defined in “Related Definitions” in EFI_HII_AIBT_OVERLAY_IMAGES

Description
This record assigns the animation sequence data to the AnimationIdCurrent identifier and increments AnimationIdCurrent by one. This animation sequence is meant to continuously cycle until stopped or paused. Before the first image is displayed, the entire defined logical window is saved to a buffer. Then each image in the sequence will remain on the screen for the specified delay before the logical window is restored to the original state and the next image is displayed.

If memory buffers are not available to save the logical window, this structure is treated as EFI_HII_AIBT_CLEAR_IMAGES_LOOP structure, with the BackgndColor value set to black.

The header type (either BlockType in EFI_HII_ANIMATION_BLOCK or BlockType2 in EFI_HII_AIBT_EXTx BLOCK) will be set to EFI_HII_AIBT_RESTORE_SCRN_LOOP.

33.3.10.2.9 EFI_HII_AIBT_DUPLICATE

Summary
Assigns a new character value to a previously defined animation sequence.

Prototype

typedef struct _EFI_HII_AIBT_DUPLICATE_BLOCK {
    EFI_ANIMATION_ID AnimationId;
} EFI_HII_AIBT_DUPLICATE_BLOCK;

Members

AnimationId
The previously defined animation ID with the exact same animation information.
Indicates that the animation sequence with animation ID AnimationIdCurrent has the same animation information as a previously defined animation ID and increments AnimationIdCurrent by one.

The header type (either BlockType in EFI_HII_ANIMATION_BLOCK or BlockType2 in EFI_HII_AIBT_EXTx_BLOCK) will be set to EFI_HII_AIBT_DUPLICATE.

### 33.3.10.2.10 EFI_HII_AIBT_SKIP1

**Summary**

Skips animation IDs.

**Prototype**

```c
typedef struct _EFI_HII_AIBT_SKIP1_BLOCK {
    UINT8 SkipCount;
} EFI_HII_AIBT_SKIP1_BLOCK;
```

**Members**

**SkipCount**

The unsigned 8-bit value to add to AnimationIdCurrent.

**Discussion**

Increments the current animation ID AnimationIdCurrent by the number specified. The header type (either BlockType in EFI_HII_ANIMATION_BLOCK or BlockType2 in EFI_HII_AIBT_EXTx_BLOCK) will be set to EFI_HII_AIBT_SKIP1.

### 33.3.10.2.11 EFI_HII_AIBT_SKIP2

**Summary**

Skips animation IDs.

**Prototype**

```c
typedef struct _EFI_HII_AIBT_SKIP2_BLOCK {
    UINT16 SkipCount;
} EFI_HII_AIBT_SKIP2_BLOCK;
```

**Members**

**SkipCount**

The unsigned 16-bit value to add to AnimationIdCurrent.

**Discussion**

Increments the current animation ID AnimationIdCurrent by the number specified. The header type (either BlockType in EFI_HII_ANIMATION_BLOCK or BlockType2 in EFI_HII_AIBT_EXTx_BLOCK) will be set to EFI_HII_AIBT_SKIP2.
This section provides code definitions for the HII-related protocols, functions, and type definitions, which are the required architectural mechanisms by which UEFI-compliant systems manage user input. The major areas described include the following:

- Font management.
- String management.
- Image management.
- Database management.

### 34.1 Font Protocol

#### 34.1.1 EFI_HII_FONT_PROTOCOL

**Summary**

Interfaces which retrieve font information.

**GUID**

```c
#define EFI_HII_FONT_PROTOCOL_GUID \
{0xe9ca4775, 0x8657, 0x47fc, \ 
 {0x97, 0xe7, 0x7e, 0xd6, 0x5a, 0x8, 0x43, 0x24 }}
```

**Protocol**

```c
typedef struct _EFI_HII_FONT_PROTOCOL {
  EFI_HII_STRING_TO_IMAGE  StringToImage;
  EFI_HII_STRING_ID_TO_IMAGE StringIdToImage;
  EFI_HII_GET_GLYPH GetGlyph;
  EFI_HII_GET_FONT_INFO  GetFontInfo;
} EFI_HII_FONT_PROTOCOL;
```

**Members**

- **StringToImage, StringIdToImage**
  - Render a string to a bitmap or to the display.

- **GetGlyph**
  - Return a specific glyph in a specific font.
GetFontInfo
Return font information for a specific font.

34.1.2 EFI_HII_FONT_PROTOCOL.StringToImage()

Summary
Renders a string to a bitmap or to the display.

Prototype

```
typedef
EFI_STATUS
(EFIAPI *EFI_HII_STRING_TO_IMAGE) (   
    IN CONST EFI_HII_FONT_PROTOCOL *This,
    IN EFI_HII_OUT_FLAGS Flags,
    IN CONST EFI_STRING String,
    IN CONST EFI_FONT_DISPLAY_INFO *StringInfo OPTIONAL,
    IN OUT EFI_IMAGE_OUTPUT **Blt,
    IN UINTN BltX,
    IN UINTN BltY,
    OUT EFI_HII_ROW_INFO **RowInfoArray OPTIONAL,
    OUT UINTN *RowInfoArraySize OPTIONAL,
    OUT UINTN *ColumnInfoArray OPTIONAL
):  
```

Parameters

This
A pointer to the EFI_HII_FONT_PROTOCOL instance.

Flags
Describes how the string is to be drawn. EFI_HII_OUT_FLAGS is defined in Related Definitions, below.

String
Points to the null-terminated string to be displayed.

StringInfo
Points to the string output information, including the color and font. If NULL, then the string will be output in the default system font and color.

Blt
If this points to a non-NULL on entry, this points to the image, which is Blt.Width pixels wide and Blt.Height pixels high. The string will be drawn onto this image and EFI_HII_OUT_FLAG_CLIP is implied. If this points to a NULL on entry, then a buffer will be allocated to hold the generated image and the pointer updated on exit. It is the caller’s responsibility to free this buffer.

BltX, BltY
Specifies the offset from the left and top edge of the image of the first character cell in the image.

RowInfoArray
If this is non-NULL on entry, then on exit, this will point to an allocated buffer containing row information and RowInfoArraySize will be updated to contain the number of elements. This array describes the characters which were at least partially drawn and the heights of the rows. It is the caller’s responsibility to free this buffer.

RowInfoArraySize
If this is non-NULL on entry, then on exit it contains the number of elements in RowInfoArray.
ColumnInfoArray

If this is non-NULL, then on return it will be filled with the horizontal offset for each character in the string on the row where it is displayed. Non-printing characters will have the offset ~0. The caller is responsible to allocate a buffer large enough so that there is one entry for each character in the string, not including the null-terminator. It is possible when character display is normalized that some character cells overlap.

Description

This function renders a string to a bitmap or the screen using the specified font, color and options. It either draws the string and glyphs on an existing bitmap, allocates a new bitmap or uses the screen. The strings can be clipped or wrapped. Optionally, the function also returns the information about each row and the character position on that row.

If EFI_HII_OUT_FLAG_CLIP is set, then text will be formatted only based on explicit line breaks and all pixels which would lie outside the bounding box specified by Blt.Width and Blt.Height are ignored. The information in the RowInfoArray only describes characters which are at least partially displayed. For the final row, the RowInfoArray.LineHeight and RowInfoArray.BaseLine may describe pixels which are outside the limit specified by Blt.Height (unless EFI_HII_OUT_FLAG_CLIP_CLEAN_Y is specified) even though those pixels were not drawn. The LineWidth may describe pixels which are outside the limit specified by Blt.Width (unless EFI_HII_OUT_FLAG_CLIP_CLEAN_X is specified) even though those pixels were not drawn.

If EFI_HII_OUT_FLAG_CLIP_CLEAN_X is set, then it modifies the behavior of EFI_HII_OUT_FLAG_CLIP so that if a character’s right-most on pixel cannot fit, then it will not be drawn at all. This flag requires that EFI_HII_OUT_FLAG_CLIP be set.

If EFI_HII_OUT_FLAG_CLIP_CLEAN_Y is set, then it modifies the behavior of EFI_HII_OUT_FLAG_CLIP so that if a row’s bottom-most pixel cannot fit, then it will not be drawn at all. This flag requires that EFI_HII_OUT_FLAG_CLIP be set.

If EFI_HII_OUT_FLAG_WRAP is set, then text will be wrapped at the right-most line-break opportunity prior to a character whose right-most extent would exceed Blt.Width. If no line-break opportunity can be found, then the text will behave as if EFI_HII_OUT_FLAG_CLIP_CLEAN_X is set. This flag cannot be used with EFI_HII_OUT_FLAG_CLIP_CLEAN_X.

If EFI_HII_OUT_FLAG_TRANSPARENT is set, then StringInfo.BackgroundColor is ignored and all “off” pixels in the character’s drawn will use the pixel value from Blt. This flag cannot be used if Blt is NULL upon entry.

If EFI_HII_IGNORE_IF_NO_GLYPH is set, then characters which have no glyphs are not drawn. Otherwise, they are replaced with Unicode character code 0xFFFD (REPLACEMENT CHARACTER).

If EFI_HII_IGNORE_LINE_BREAK is set, then explicit line break characters will be ignored.

If EFI_HII_DIRECT_TO_SCREEN is set, then the string will be written directly to the output device specified by Screen. Otherwise the string will be rendered to the bitmap specified by Bitmap.

Related Definitions

```c
typedef UINT32 EFI_HII_OUT_FLAGS;
#define EFI_HII_OUT_FLAG_CLIP 0x00000001
#define EFI_HII_OUT_FLAG_WRAP 0x00000002
#define EFI_HII_OUT_FLAG_CLIP_CLEAN_Y 0x00000004
#define EFI_HII_OUT_FLAG_CLIP_CLEAN_X 0x00000008
#define EFI_HII_OUT_FLAG_TRANSPARENT 0x00000010
#define EFI_HII_IGNORE_IF_NO_GLYPH 0x00000020
#define EFI_HII_IGNORE_LINE_BREAK 0x00000040
#define EFI_HII_DIRECT_TO_SCREEN 0x00000080

typedef CHAR16 *EFI_STRING;
```

(continues on next page)
typedef struct _EFI_HII_ROW_INFO {
    UINTN StartIndex;
    UINTN EndIndex;
    UINTN LineHeight;
    UINTN LineWidth;
    UINTN BaselineOffset;
} EFI_HII_ROW_INFO;

StartIndex
The index of the first character in the string which is displayed on the line.

EndIndex
The index of the last character in the string which is displayed on the line.

LineHeight
The height of the line, in pixels.

LineWidth
The width of the text on the line, in pixels.

BaselineOffset
The font baseline offset in pixels from the bottom of the row, or 0 if none.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The string was successfully updated.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to allocate an output buffer for RowInfoArray or Blt.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The String or Blt was NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Flags were invalid combination.</td>
</tr>
</tbody>
</table>

34.1.3 EFI_HII_FONT_PROTOCOL.StringIdToImage()

Summary
Render a string to a bitmap or the screen containing the contents of the specified string.

Prototype

typedef

EFI_STATUS

(EFIAPI *EFI_HII_STRING_ID_TO_IMAGE) (  
   IN const EFI_HII_FONT_PROTOCOL *This,
   IN EFI_HII_OUT_FLAGS Flags,
   IN EFI_HII_HANDLE PackageList,
   IN EFI_STRING_ID StringId,
   IN const char8* Language,
   IN const EFI_FONT_DISPLAY_INFO *StringInfo OPTIONAL,
   IN OUT EFI_IMAGE_OUTPUT **Blt,
   IN UINTN BltX,
   IN UINTN BltY,
   OUT EFI_HII_ROW_INFO **RowInfoArray OPTIONAL,
   OUT UINTN *RowInfoArraySize OPTIONAL,
   OUT UINTN *ColumnInfoArray OPTIONAL
  );
Parameters

This
A pointer to the _EFI_HII_FONT_PROTOCOL_ instance.

Flags
Describes how the string is to be drawn. _EFI_HII_OUT_FLAGS_ is defined in Related Definitions, below.

PackageList
The package list in the HII database to search for the specified string.

StringId
The string’s id, which is unique within PackageList.

Language
Points to the language for the retrieved string. If NULL, then the current system language is used.

StringInfo
Points to the string output information, including the color and font. If NULL, then the string will be output in the default system font and color.

Blt
If this points to a non-NULL on entry, this points to the image, which is _Blt.Width_ pixels wide and _Height_ pixels high. The string will be drawn onto this image and _EFI_HII_OUT_FLAG_CLIP_ is implied. If this points to a NULL on entry, then a buffer will be allocated to hold the generated image and the pointer updated on exit. It is the caller’s responsibility to free this buffer.

BltX, BltY
Specifies the offset from the left and top edge of the output image of the first character cell in the image.

RowInfoArray
If this is non-NULL on entry, then on exit, this will point to an allocated buffer containing row information and _RowInfoArraySize_ will be updated to contain the number of elements. This array describes the characters which were at least partially drawn and the heights of the rows. It is the caller’s responsibility to free this buffer.

RowInfoArraySize
If this is non-NULL on entry, then on exit it contains the number of elements in _RowInfoArray_.

ColumnInfoArray
If non-NULL, on return it is filled with the horizontal offset for each character in the string on the row where it is displayed. Non-printing characters will have the offset ~0. The caller is responsible to allocate a buffer large enough so that there is one entry for each character in the string, not including the null-terminator. It is possible when character display is normalized that some character cells overlap.

Description
This function renders a string as a bitmap or to the screen and can clip or wrap the string. The bitmap is either supplied by the caller or else is allocated by the function. The strings are drawn with the font, size and style specified and can be drawn transparently or opaquely. The function can also return information about each row and each character’s position on the row.

If _EFI_HII_OUT_FLAG_CLIP_ is set, then text will be formatted only based on explicit line breaks and all pixels which would lie outside the bounding box specified by _Width_ and _Height_ are ignored. The information in the _RowInfoArray_ only describes characters which are at least partially displayed. For the final row, the LineHeight and BaseLine may describe pixels which are outside the limit specified by _Height_ (unless _EFI_HII_OUT_FLAG_CLIP_CLEAN_Y_ is specified) even though those pixels were not drawn.

If _EFI_HII_OUT_FLAG_CLIP_CLEAN_X_ is set, then it modifies the behavior of _EFI_HII_OUT_FLAG_CLIP_ so that if a character’s right-most on pixel cannot fit, then it will not be drawn at all. This flag requires that _EFI_HII_OUT_FLAG_CLIP_ be set. If _EFI_HII_OUT_FLAG_CLIP_CLEAN_Y_ is set, then it modifies the behavior of

34.1. Font Protocol
EFI_HII_OUT_FLAG_CLIP so that if a row’s bottom most pixel cannot fit, then it will not be drawn at all. This flag requires that EFI_HII_OUT_FLAG_CLIP be set.

If EFI_HII_OUT_FLAG_WRAP is set, then text will be wrapped at the right-most line-break opportunity prior to a character whose right-most extent would exceed Width. If no line-break opportunity can be found, then the text will behave as if EFI_HII_OUT_FLAG_CLIP_CLEAN_X is set. This flag cannot be used with EFI_HII_OUT_FLAG_CLIP_CLEAN_X.

If EFI_HII_OUT_FLAG_TRANSPARENT is set, then BackgroundColor is ignored and all “off” pixels in the character’s glyph will use the pixel value from Blt. This flag cannot be used if Blt is NULL upon entry.

If EFI_HII_IGNORE_IF_NO_GLYPH is set, then characters which have no glyphs are not drawn. Otherwise, they are replaced with Unicode character code 0xFFFD (REPLACEMENT CHARACTER).

If EFI_HII_IGNORE_LINE_BREAK is set, then explicit line break characters will be ignored.

If EFI_HII_DIRECT_TO_SCREEN is set, then the string will be written directly to the output device specified by Screen. Otherwise the string will be rendered to the bitmap specified by Bitmap.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The string was successfully updated.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to allocate an output buffer for RowInfoArray or Blt.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The StringId or PackageList was NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Flags were invalid combination.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The StringId is not in the specified PackageList. The specified PackageList is not in the Database.</td>
</tr>
</tbody>
</table>

### 34.1.4 EFI_HII_FONT_PROTOCOL.GetGlyph()

**Summary**

Return image and information about a single glyph.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_HII_GET_GLYPH) (  
  IN CONST EFI_HII_FONT_PROTOCOL *This,  
  IN CHAR16 Char,  
  IN CONST EFI_FONT_DISPLAY_INFO *StringInfo,  
  OUT EFI_IMAGE_OUTPUT **Blt,  
  OUT UINTN *Baseline OPTIONAL;  
);  
```

**Parameters**

This

A pointer to the EFI_HII_FONT_PROTOCOL instance.

Char

Character to retrieve.

StringInfo

Points to the string font and color information or NULL if the string should use the default system font and color.
Blt
Thus must point to a NULL on entry. A buffer will be allocated to hold the output and the pointer updated on exit. It is the caller’s responsibility to free this buffer. On return, only Blt.Width, Blt.Height, and Blt.Image.Bitmap are valid.

Baseline
Number of pixels from the bottom of the bitmap to the baseline.

Description
Convert the glyph for a single character into a bitmap.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Glyph bitmap created.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to allocate the output buffer Blt.</td>
</tr>
<tr>
<td>EFI_WARN_UNKNOWN_GLYPH</td>
<td>The glyph was unknown and was replaced with the glyph for Unicode character code 0xFFFD.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Blt is NULL or *Blt is !Null</td>
</tr>
</tbody>
</table>

34.1.5 EFI_HII_FONT_PROTOCOL.GetFontInfo()

Summary
Return information about a particular font.

Prototype

typedef
EFI_STATUS
(EIFI_API *EFI_HII_GET_FONT_INFO) (  
   IN CONST EFI_HII_FONT_PROTOCOL *This,  
   IN OUT EFI_FONT_HANDLE *FontHandle,  
   IN CONST EFI_FONT_DISPLAY_INFO *StringInfoIn, OPTIONAL  
   OUT EFI_FONT_DISPLAY_INFO **StringInfoOut,  
   IN CONST EFI_STRING String OPTIONAL  
);

typedef VOID *EFI_FONT_HANDLE;

Parameters

This
A pointer to the EFI_HII_FONT_PROTOCOL instance.

FontHandle
On entry, points to the font handle returned by a previous call to GetFontInfo() or points to NULL to start with the first font. On return, points to the returned font handle or points to NULL if there are no more matching fonts.

StringInfoIn
Upon entry, points to the font to return information about. If NULL, then the information about the system default font will be returned.

StringInfoOut
Upon return, contains the matching font’s information. If NULL, then no information is returned. This buffer is allocated with a call to the Boot Service AllocatePool(). It is the caller’s responsibility to call the Boot Service FreePool() when the caller no longer requires the contents of StringInfoOut.
String
Points to the string which will be tested to determine if all characters are available. If NULL, then any font is acceptable.

Description
This function iterates through fonts which match the specified font, using the specified criteria. If String is non-NULL, then all of the characters in the string must exist in order for a candidate font to be returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Matching font returned successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No matching font was found.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There were insufficient resources to complete the request.</td>
</tr>
</tbody>
</table>

34.2 EFI HII Font Ex Protocol

The EFI HII Font Ex protocol defines an extension to the EFI HII Font protocol which enables various new capabilities described in this section.

34.2.1 EFI_HII_FONT_EX_PROTOCOL

Summary
Interfaces which retrieve the font information.

GUID

```c
#define EFI_HII_FONT_EX_PROTOCOL_GUID \
{ 0x849e6875, 0xdb35, 0x4df8, 0xb4, \n  {0x1e, 0xc8, 0xf3, 0x37, 0x18, 0x7, 0x3f }}
```

Protocol

```c
typedef struct _EFI_HII_FONT_EX_PROTOCOL {
    EFI_HII_STRING_TO_IMAGE_EX StringToImageEx;
    EFI_HII_STRING_ID_TO_IMAGE_EX StringIdToImageEx;
    EFI_HII_GET_GLYPH_EX GetGlyphEx;
    EFI_HII_GET_FONT_INFO_EX GetFontInfoEx;
    EFI_HII_GET_GLYPH_INFO GetGlyphInfo;
} EFI_HII_FONT_EX_PROTOCOL;
```

Members

StringToImageEx, StringIdToImageEx
Render a string to a bitmap or to the display. This function will try to use the external font glyph generator for generating the glyph if it can’t find the glyph in the font database.

GetGlyphEx
Return a specific glyph in a specific font. This function will try to use the external font glyph generator for generating the glyph if it can’t find the glyph in the font database.

GetFontInfoEx
Return the font information for a specific font, this protocol invokes original EFI_HII_FONT_PROTOCOL.GetFontInfo() implicitly.
GetGLphyInfoEx

Return the glyph information for the single glyph.

### 34.2.2 EFI_HII_FONT_EX_PROTOCOL.StringToImageEx()

**Summary**

Render a string to a bitmap or to the display. The prototype of this extension function is the same with `EFI_HII_FONT_PROTOCOL.StringToImage()`.

**Protocol**

```c
typedef EFI_STATUS
(EIFIAPI *EFI_HII_FONT_EX_PROTOCOL
StringToImageEx(    
    IN CONST EFI_HII_FONT_EX_PROTOCOL *This,
    IN EFI_HII_OUT_FLAGS Flags,
    IN CONST EFI_STRING String,
    IN CONST EFI_FONT_DISPLAY_INFO *StringInfo OPTIONAL,
    IN OUT EFI_IMAGE_OUTPUT **Blt,
    IN UINTN BltX,
    IN UINTN BltY,
    OUT EFI_HII_ROW_INFO **RowInfoArray OPTIONAL,
    OUT UINTN *RowInfoArraySize OPTIONAL,
    OUT UINTN *ColumnInfoArray OPTIONAL
);
```

**Parameters**

Same with `EFI_HII_FONT_PROTOCOL.STRINGTOIMAGE()`.

**Description**

This function is similar to `EFI_HII_FONT_PROTOCOL.StringToImage()`. The difference is that this function will locate all `EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL` instances that are installed in the system when the glyph in the string with the given font information is not found in the current HII glyph database. The function will attempt to generate the glyph information and the bitmap using the first `EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL` instance that supports the requested font information in the `EFI_FONT_DISPLAY_INFO`.

**Status Codes Returned** — Same with `EFI_HII_FONT_PROTOCOL.STRINGTOIMAGE()`.

### 34.2.3 EFI_HII_FONT_EX_PROTOCOL.StringIdToImageEx()

**Summary**

Render a string to a bitmap or the screen containing the contents of the specified string. The prototype of this extension function is the same with `EFI_HII_FONT_PROTOCOL.STRINGTOIMAGE()`.

**Protocol**

```c
typedef EFI_STATUS
(EIFIAPI *EFI_HII_FONT_EX_PROTOCOL
StringIdToImageEx(    
    IN CONST EFI_HII_FONT_EX_PROTOCOL *This,
    IN EFI_HII_OUT_FLAGS Flags,
    IN EFI_HII_HANDLE PackageList,
    ...
    ...
    ...
    ...
);
```

(continues on next page)
Parameters

Same with \texttt{EFI\_HII\_FONT\_PROTOCOL.STRINGTOIMAGE()}.\footnote{Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A}

Description

This function is similar to \texttt{EFI\_HII\_FONT\_PROTOCOL.STRINGTOIMAGE()}.\footnote{Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A} The difference is that this function will locate all \texttt{EFI\_HII\_FONT\_GLYPH\_GENERATOR\_PROTOCOL} instances that are installed in the system when the glyph in the string with the given font information is not found in the current HII glyph database. The function will attempt to generate the glyph information and the bitmap using the first \texttt{EFI\_HII\_FONT\_GLYPH\_GENERATOR\_PROTOCOL} instance that supports the requested font information in the \texttt{EFI\_FONT\_DISPLAY\_INFO}.\footnote{Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A}

Status Codes Returned — Same with \texttt{EFI\_HII\_FONT\_PROTOCOL.STRINGTOIMAGE()}.\footnote{Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A}

34.2.4 \texttt{EFI\_HII\_FONT\_EX\_PROTOCOL.GetGlyphEx()}

Summary

Return image and baseline about a single glyph. The prototype of this extension function is the same with \texttt{EFI\_HII\_FONT\_PROTOCOL.GETGLYPH()}.\footnote{Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A}

Protocol

\begin{verbatim}
typedef
EFI\_STATUS
(EIFIAPI \texttt{EFI\_GET\_GLYPH\_EX})(
    IN CONST EFI\_HII\_FONT\_EX\_PROTOCOL \texttt{This},
    IN CHAR16 Char,
    IN CONST EFI\_FONT\_DISPLAY\_INFO StringInfo,
    IN OUT EFI\_IMAGE\_OUTPUT Blt,
    IN UINTN Baseline OPTIONAL
);
\end{verbatim}

Parameters — Same with \texttt{EFI\_HII\_FONT\_PROTOCOL.GETGLYPH()}.\footnote{Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A}

Description

The difference is that this function will locate all \texttt{EFI\_HII\_FONT\_GLYPH\_GENERATOR\_PROTOCOL} instances that are installed in the system when the glyph in the string with the given font information is not found in the current HII glyph database. The function will attempt to generate the glyph information and the bitmap using the first \texttt{EFI\_HII\_FONT\_GLYPH\_GENERATOR\_PROTOCOL} instance that supports the requested font information in the \texttt{EFI\_FONT\_DISPLAY\_INFO}.\footnote{Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A}

Status Codes Returned — Same as \texttt{EFI\_HII\_FONT\_PROTOCOL.GETGLYPH()}.\footnote{Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A}

34.2. EFI HII Font Ex Protocol

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34.2.5  EFI_HII_FONT_EX_PROTOCOL.GetFontInfoEx()

Summary
Return information about a particular font. The prototype of this extension function is the same with

Protocol

```c
typedef EFI_STATUS
  (EFIAPI *EFI_HII_GET_FONT_INFO_EX)(
    IN CONST EFI_HII_FONT_EX_PROTOCOL *This,
    IN OUT EFI_FONT_HANDLE *FontHandle,
    IN CONST EFI_FONT_DISPLAY_INFO *StringInfoIn, OPTIONAL
    OUT EFI_FONT_DISPLAY_INFO **StringInfoOut,
    IN CONST EFI_STRING String OPTIONAL
  );
```

Parameters — Same with `EFI_HII_FONT_PROTOCOL.GETFONTINFO()`.

Description
Same with `EFI_HII_FONT_PROTOCOL.GETFONTINFO()` . This protocol invokes `EFI_HII_FONT_PROTOCOL.GETFONTINFO()` implicitly.

Status Codes Returned — Same as `EFI_HII_FONT_PROTOCOL.GETFONTINFO()`.

34.2.6  EFI_HII_FONT_EX_PROTOCOL.GetGlyphInfo()

Summary
The function returns the information of the single glyph.

Protocol

```c
typedef EFI_STATUS
  (EFIAPI *EFI_HII_GET_GLYPH_INFO)(
    IN CONST EFI_HII_FONT_EX_PROTOCOL *This,
    IN CHAR16 Char,
    IN CONST EFI_FONT_DISPLAY_INFO *FontDisplayInfo,
    OUT EFI_HII_GLYPH_INFO * GlyphInfo
  );
```

Parameters

This

  `EFI_HII_FONT_EX_PROTOCOL` instance.

Char

  Information of Character to retrieve.

FontDisplayInfo

  Font display information of this character.

GlyphInfo

  Pointer to retrieve the glyph information.
Description

This function returns the glyph information of character in the specific font family. This function will locate all EFI_HII_FONT_GLYPH_GENERATOR protocol instances that are installed in the system, and attempt to use them if it can’t find the glyph information in the font database. It returns EFI_UNSUPPORTED if neither the font database nor any instances of the EFI_HII_FONT_GLYPH_GENERATOR protocols support the font glyph in the specific font family. Otherwise, the EFI_HII_GLYPH_INFO is returned in GlyphInfo. This function only returns the glyph geometry information instead of allocating the buffer for EFI_IMAGE_OUTPUT and drawing the glyph in the buffer.

![Glyph Example](image)

**Fig. 34.1: Glyph Example**

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The glyph information was returned to GlyphInfo.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Memory allocation failed in this function.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The input character was not found in the database.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The font is not supported.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The GlyphInfo or FontDisplayInfo was NULL.</td>
</tr>
</tbody>
</table>

**34.2.7 Code Definitions**

**34.2.7.1 EFI_FONT_DISPLAY_INFO**

**Summary**

Describes font output-related information.

**Prototype**

```c
typedef struct _EFI_FONT_DISPLAY_INFO {
    EFI_GRAPHICS_OUTPUT_BLT_PIXEL ForegroundColor;
    EFI_GRAPHICS_OUTPUT_BLT_PIXEL BackgroundColor;
    EFI_FONT_INFO_MASK FontInfoMask;
    EFI_FONT_INFO FontInfo
} EFI_FONT_DISPLAY_INFO;
```

**Members**

**FontInfo**

The font information. Type EFI_FONT_INFO is defined in EFI_HII_STRING_PROTOCOL.NewString().

**ForegroundColor**

The color of the “on” pixels in the glyph in the bitmap.
BackgroundColor
The color of the “off” pixels in the glyph in the bitmap.

FontInfoMask
The font information mask determines which portion of the font information will be used and what to do if the specific font is not available.

Description
This structure is used for describing the way in which a string should be rendered in a particular font. FontInfo specifies the basic font information and ForegroundColor and BackgroundColor specify the color in which they should be displayed. The flags in FontInfoMask describe where the system default should be supplied instead of the specified information. The flags also describe what options can be used to make a match between the font requested and the font available.

If EFI_FONT_INFO_SYS_FONT is specified, then the font name in FontInfo is ignored and the system font name is used. This flag cannot be used with EFI_FONT_INFO_ANY_FONT.

If EFI_FONT_INFO_SYS_SIZE is specified, then the font height specified in FontInfo is ignored and the system font height is used instead. This flag cannot be used with EFI_FONT_INFO_ANY_SIZE.

If EFI_FONT_INFO_SYSSTYLE is specified, then the font style in FontInfo is ignored and the system font style is used. This flag cannot be used with EFI_FONT_INFO_ANY_STYLE.

If EFI_FONT_INFO_SYS_FORE_COLOR is specified, then ForegroundColor is ignored and the system foreground color is used.

If EFI_FONT_INFO_SYS_BACK_COLOR is specified, then BackgroundColor is ignored and the system background color is used.

If EFI_FONT_INFO_RESIZE is specified, then the system may attempt to stretch or shrink a font to meet the size requested. This flag cannot be used with EFI_FONT_INFO_ANY_SIZE.

If EFI_FONT_INFO_RESTYLE is specified, then the system may attempt to remove some of the specified styles in order to meet the style requested. This flag cannot be used with EFI_FONT_INFO_ANY_STYLE.

If EFI_FONT_INFO_ANY_FONT is specified, then the system may attempt to match with any font. This flag cannot be used with EFI_FONT_INFO_SYS_FONT.

If EFI_FONT_INFO_ANY_SIZE is specified, then the system may attempt to match with any font size. This flag cannot be used with EFI_FONT_INFO_SYS_SIZE or EFI_FONT_INFO_RESIZE.

If EFI_FONT_INFO_ANY_STYLE is specified, then the system may attempt to match with any font style. This flag cannot be used with EFI_FONT_INFO_SYS_STYLE or EFI_FONT_INFO_RESTYLE.

Related Definitions

typedef UINT32 EFI_FONT_INFO_MASK;

#define EFI_FONT_INFO_SYS_FONT 0x00000001
#define EFI_FONT_INFO_SYS_SIZE 0x00000002
#define EFI_FONT_INFO_SYS_STYLE 0x00000004
#define EFI_FONT_INFO_SYS_FORE_COLOR 0x00000010
#define EFI_FONT_INFO_SYS_BACK_COLOR 0x00000020
#define EFI_FONT_INFO_RESIZE 0x00001000
#define EFI_FONT_INFO_RESTYLE 0x00002000
#define EFI_FONT_INFO_ANY_FONT 0x00010000
#define EFI_FONT_INFO_ANY_SIZE 0x00020000
#define EFI_FONT_INFO_ANY_STYLE 0x00040000
34.2.7.2  EFI_IMAGE_OUTPUT

Summary
Describes information about either a bitmap or a graphical output device.

Prototype

typedef struct _EFI_IMAGE_OUTPUT {
    UINT16 Width;
    UINT16 Height;
    union {
        EFI_GRAPHICS_OUTPUT_BLT_PIXEL *Bitmap;
        EFI_GRAPHICS_OUTPUT_PROTOCOL *Screen;
    } Image;
} EFI_IMAGE_OUTPUT;

Members

Width
Width of the output image.

Height
Height of the output image.

Bitmap
Points to the output bitmap.

Screen
Points to the EFI_GRAPHICS_OUTPUT_PROTOCOL which describes the screen on which to draw the specified string.

34.3 String Protocol

34.3.1  EFI_HII_STRING_PROTOCOL

Summary
Interfaces which manipulate string data.

GUID

#define EFI_HII_STRING_PROTOCOL_GUID \ 
{ 0xfd96974, 0x23aa, 0x4cdc,\ 
  { 0xb9, 0xcb, 0x98, 0xd1, 0x77, 0x50, 0x32, 0x2a }}

Protocol

typedef struct _EFI_HII_STRING_PROTOCOL {
    EFI_HII_NEW_STRING NewString;
    EFI_HII_GET_STRING GetString;
    EFI_HII_SET_STRING SetString;
    EFI_HII_GET_LANGUAGES GetLanguages;
    EFI_HII_GET_2ND_LANGUAGES GetSecondaryLanguages;
} EFI_HII_STRING_PROTOCOL;

Members
NewString
Add a new string.

GetString
Retrieve a string and related string information.

SetString
Change a string.

GetLanguages
List the languages for a particular package list.

GetSecondaryLanguages
List supported secondary languages for a particular primary language.

34.3.2 EFI_HII_STRING_PROTOCOL.NewString()

Summary
Creates a new string in a specific language and add it to strings from a specific package list.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_HII_NEW_STRING) (  
  IN CONST EFI_HII_STRING_PROTOCOL *This,
  IN EFI_HII_HANDLE PackageList,
  OUT EFI_STRING_ID *StringId
  IN CONST CHAR8 *Language,
  IN CONST CHAR16 *LanguageName OPTIONAL,
  IN CONST EFI_STRING String,
  IN CONST EFI_FONT_INFO *StringFontInfo
);
```

Parameters

This
A pointer to the EFI_HII_STRING_PROTOCOL instance.

PackageList
Handle of the package list where this string will be added.

Language
Points to the language for the new string. The language information is in the format described by Appendix M — Formats — Language Codes and Language Code Arrays of the UEFI Specification.

LanguageName
Points to the printable language name to associate with the passed in Language field. This is analogous to passing in “zh-Hans” in the Language field and LanguageName might contain “Simplified Chinese” as the printable language.

String
Points to the new null-terminated string.

StringFontInfo
Points to the new string’s font information or NULL if the string should have the default system font, size and style.
StringId
On return, contains the new strings id, which is unique within PackageList. Type EFI_STRING_ID is defined in EFI_IFR_OP_HEADER.

Description
This function adds the string String to the group of strings owned by PackageList, with the specified font information StringFontInfo and returns a new string id. The new string identifier is guaranteed to be unique within the package list. That new string identifier is reserved for all languages in the package list.

Related Definitions

typedef struct {
  EFI_HII_FONT_STYLE FontStyle;
  UINT16 FontSize;
  CHAR16 FontName[...];
} EFI_FONT_INFO;

FontStyle
The design style of the font. Type EFI_HII_FONT_STYLE is defined in Fixed Header.

FontSize
The character cell height, in pixels.

FontName
The null-terminated font family name.

Status Codes Returns

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The new string was added successfully</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not add the string.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>String is NULL or StringId is NULL or Language is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The input package list could not be found in the current database.</td>
</tr>
</tbody>
</table>

34.3.3 EFI_HII_STRING_PROTOCOL.GetString()

Summary
Returns information about a string in a specific language, associated with a package list.

Prototype

typedef

EFI_STATUS

(EIFIAPI *EFI_HII_GET_STRING) (  
  IN  CONST EFI_HII_STRING_PROTOCOL  *This,
  IN  CONST CHAR8  *Language,
  IN  EFI_HII_HANDLE  PackageList,
  IN  EFI_STRING_ID  StringId,
  OUT  EFI_STRING  String,
  IN  OUT UINTN  *StringLength,
  OUT  EFI_FONT_INFO  **StringFontInfo OPTIONAL
  );

Parameters
This
A pointer to the `EFI_HII_STRING_PROTOCOL` instance.

**PackageList**
The package list in the HII database to search for the specified string.

**Language**
Points to the language for the retrieved string. Callers of interfaces that require RFC 4646 language codes to retrieve a Unicode string must use the RFC 4647 algorithm to lookup the Unicode string with the closest matching RFC 4646 language code.

**StringId**
The string’s id, which is unique within `PackageList`.

**String**
Points to the new null-terminated string.

**StringLength**
On entry, points to the size of the buffer pointed to by `String`, in bytes. On return, points to the length of the string, in bytes.

**StringFontInfo**
Points to a buffer that will be callee allocated and will have the string’s font information into this buffer. The caller is responsible for freeing this buffer. If the parameter is NULL a buffer will not be allocated and the string font information will not be returned.

**Description**
This function retrieves the string specified by `StringId` which is associated with the specified `PackageList` in the language `Language` and copies it into the buffer specified by `String`.

If the string specified by `StringId` is not present in the specified `PackageList`, then `EFI_NOT_FOUND` is returned. If the string specified by `StringId` is present, but not in the specified language then `EFI_INVALID_LANGUAGE` is returned.

If the buffer specified by `StringLength` is too small to hold the string, then `EFI_BUFFER_TOO_SMALL` will be returned. `StringLength` will be updated to the size of buffer actually required to hold the string.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>The string was returned successfully.</td>
</tr>
<tr>
<td><code>EFI_NOT_FOUND</code></td>
<td>The string specified by <code>StringId</code> is not available. The specified <code>PackageList</code> is not in the Database.</td>
</tr>
<tr>
<td><code>EFI_INVALID_LANGUAGE</code></td>
<td>The string specified by <code>StringId</code> is available but not in the specified language.</td>
</tr>
<tr>
<td><code>EFI_BUFFER_TOO_SMALL</code></td>
<td>The buffer specified by <code>StringLength</code> is too small to hold the string.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>The <code>Language</code> or <code>StringLength</code> was NULL.</td>
</tr>
<tr>
<td><code>EFI_OUT_OF_RESOURCES</code></td>
<td>The value referenced by <code>StringLength</code> was not zero and <code>String</code> was NULL.</td>
</tr>
<tr>
<td></td>
<td>There were insufficient resources to complete the request.</td>
</tr>
</tbody>
</table>

### 34.3.4 EFI_HII_STRING_PROTOCOL.SetString()

**Summary**
Change information about the string.

**Prototype**

```c
typedef
EFI_STATUS
```

(continues on next page)
(EFI_API *EFI_HII_SET_STRING) (  
  IN CONST EFI_HII_STRING_PROTOCOL  *This,  
  IN EFI_HII_HANDLE PackageList,  
  IN EFI_STRING_ID StringId,  
  IN CONST CHAR8 *Language,  
  IN CONST EFI_STRING String,  
  IN CONST EFI_FONT_INFO *StringFontInfo OPTIONAL
  );

Parameters

 This
   A pointer to the EFI_HII_STRING_PROTOCOL instance.

 PackageList
   The package list containing the strings.

 Language
   Points to the language for the updated string.

 StringId
   The string id, which is unique within PackageList.

 String
   Points to the new null-terminated string.

 StringFontInfo
   Points to the string’s font information or NULL if the string font information is not changed.

Description

This function updates the string specified by StringId in the specified PackageList to the text specified by String and, optionally, the font information specified by StringFontInfo. There is no way to change the font information without changing the string text.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The string was successfully updated.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The string specified by StringId is not in the database. The specified PackageList is not in the Database.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The String or Language was NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The system is out of resources to accomplish the task.</td>
</tr>
</tbody>
</table>

34.3.5 EFI_HII_STRING_PROTOCOL.GetLanguages()

Summary

Returns a list of the languages present in strings in a package list.

Prototype

typedef
  EFI_STATUS
  (EFI_API *EFI_HII_GET_LANGUAGES) (  
  IN  CONST EFI_HII_STRING_PROTOCOL  *This,

(continues on next page)
Parameters

This
A pointer to the EFI_HII_STRING_PROTOCOL instance.

PackageList
The package list to examine.

Languages
Points to the buffer to hold the returned null-terminated ASCII string.

LanguageSize
On entry, points to the size of the buffer pointed to by Languages, in bytes. On return, points to the length of Languages, in bytes.

Description
This function returns the list of supported languages, in the format specified in Appendix M — Formats — Language Codes and Language Code Arrays.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The languages were returned successfully.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The LanguagesSize is too small to hold the list of supported languages. LanguageSize is updated to contain the required size.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified PackageList is not in the Database.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>LanguagesSize is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The value referenced by LanguagesSize is not zero and Languages is NULL.</td>
</tr>
</tbody>
</table>

34.3.6 EFI_HII_STRING_PROTOCOL.GetSecondaryLanguages()

Summary
Given a primary language, returns the secondary languages supported in a package list.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_HII_GET_2ND_LANGUAGES) (  
  IN CONST EFI_HII_STRING_PROTOCOL *This,  
  IN EFI_HII_HANDLE PackageList,  
  IN CONST CHAR8* PrimaryLanguage;  
  IN OUT CHAR8* SecondaryLanguages,  
  IN OUT UINTN *SecondaryLanguagesSize
  );

Parameters

This
A pointer to the EFI_HII_STRING_PROTOCOL instance.
PackageList
   The package list to examine.

Primary Language
   Points to the null-terminated ASCII string that specifies the primary language. Languages are specified in the format specified in Appendix M — Formats — Language Codes and Language Code Arrays of the UEFI Specification.

Secondary Languages
   Points to the buffer to hold the returned null-terminated ASCII string that describes the list of secondary languages for the specified Primary Language. If there are no secondary languages, the function returns successfully, but this is set to NULL.

SecondaryLanguagesSize
   On entry, points to the size of the buffer pointed to by SecondaryLanguages, in bytes. On return, points to the length of SecondaryLanguages in bytes.

Description
   Each string package has associated with it a single primary language and zero or more secondary languages. This routine returns the secondary languages associated with a package list.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Secondary languages correctly returned</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The buffer specified by SecondaryLanguagesSize is too small to hold the returned information. SecondaryLanguagesSize is updated to hold the size of the buffer required.</td>
</tr>
<tr>
<td>EFI_INVALID_LANGUAGE</td>
<td>The language specified by FirstLanguage is not present in the specified package list.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified PackageList is not in the Database.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PrimaryLanguage or SecondaryLanguagesSize is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The value referenced by SecondaryLanguagesSize is not zero and SecondaryLanguages is NULL.</td>
</tr>
</tbody>
</table>

34.4 Image Protocol

34.4.1 EFI_HII_IMAGE_PROTOCOL

Summary
Protocol which allow access to images in the images database.

GUID

```c
#define EFI_HII_IMAGE_PROTOCOL_GUID \
{ 0x31a6406a, 0x6bdf, 0x4e46,\ 
{ 0xb2, 0xa2, 0xeb, 0xaa, 0x89, 0xc4, 0x20 }}
```

Protocol

```c
typedef struct _EFI_HII_IMAGE_PROTOCOL {
   EFI_HII_NEW_IMAGE NewImage;
   EFI_HII_GET_IMAGE GetImage;
   EFI_HII_SET_IMAGE SetImage;
} EFI_HII_IMAGE_PROTOCOL;
```

(continues on next page)
Members

NewImage
Add a new image.

GetImage
Retrieve an image and related font information.

SetImage
Change an image.

34.4.2 EFI_HII_IMAGE_PROTOCOL.NewImage()

Summary
Creates a new image and add it to images from a specific package list.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_HII_NEW_IMAGE) (  
    IN CONST EFI_HII_IMAGE_PROTOCO *This,
    IN EFI_HII_HANDLE PackageList,
    OUT EFI_IMAGE_ID *ImageId,
    IN CONST EFI_IMAGE_INPUT *Image
    );

Parameters

This
A pointer to the EFI_HII_IMAGE_PROTOCOL instance.

PackageList
Handle of the package list where this image will be added.

ImageId
On return, contains the new image id, which is unique within PackageList.

Image
Points to the image.

Description
This function adds the image Image to the group of images owned by PackageList, and returns a new image identifier ( ImageId ).

Related Definitions

typedef UINT16 EFI_IMAGE_ID;

typedef struct {
    UINT32 Flags;
} EFI_HII_IMAGE_PROTOCOL; (continued from previous page)
Flags

Describe image characteristics. If EFI_IMAGE_TRANSPARENT is set, then the image was designed for transparent display. #define EFI_IMAGE_TRANSPARENT 0x00000001

Width

Image width, in pixels.

Height

Image height, in pixels.

Bitmap

A pointer to the actual bitmap, organized left-to-right, top-to-bottom. The size of the bitmap is Width * Height * size of (EFI_GRAPHICS_OUTPUT_BLT_PIXEL).

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The new image was added successfully</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not add the image.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Image is NULL or ImageId is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The PackageList could not be found.</td>
</tr>
</tbody>
</table>

34.4.3 EFI_HII_IMAGE_PROTOCOL.GetImage()

Summary

Returns information about an image, associated with a package list.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_HII_GET_IMAGE) (  
    IN CONST EFI_HII_IMAGE_PROTOCOL *This,  
    IN EFI_HII_HANDLE PackageList,  
    IN EFI_IMAGE_ID ImageId,  
    OUT EFI_IMAGE_INPUT *Image  
);
```

Parameters

This

A pointer to the EFI_HII_IMAGE_PROTOCOL instance.

PackageList

The package list in the HII database to search for the specified image.

ImageId

The image’s id, which is unique within PackageList.

Image

Points to the new image.
Description

This function retrieves the image specified by ImageId which is associated with the specified PackageList and copies it into the buffer specified by Image.

If the image specified by ImageId is not present in the specified PackageList, then EFI_NOT_FOUND is returned.

The actual bitmap (Image->Bitmap) should not be freed by the caller and should not be modified directly.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The image was returned successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The image specified by ImageId is not available. The specified PackageList is not in the Database.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Image was NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>The bitmap could not be retrieved because there was not enough memory.</td>
</tr>
</tbody>
</table>

34.4.4 EFI_HII_IMAGE_PROTOCOL.SetImage()

Summary

Change information about the image.

Prototype

```c
typedef EFI_STATUS
(EIFIAPIC *EFI_HII_SET_IMAGE) (  
    IN CONST EFI_HII_IMAGE_PROTOCOL *This,  
    IN EFI_HII_HANDLE PackageList,  
    IN EFI_IMAGE_ID ImageId,  
    IN CONST EFI_IMAGE_INPUT *Image,  
);  
```

Parameters

This

A pointer to the EFI_HII_IMAGE_PROTOCOL instance.

PackageList

The package list containing the images.

ImageId

The image id, which is unique within PackageList.

Image

Points to the image.

Description

This function updates the image specified by ImageId in the specified PackageListHandle to the image specified by Image.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The image was successfully updated.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The image specified by ImageId is not in the database. The specified PackageList is not in the Database.</td>
</tr>
</tbody>
</table>

continues on next page
34.4.5 EFI_HII_IMAGE_PROTOCOL.DrawImage()

Summary
Renders an image to a bitmap or to the display.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_HII_DRAW_IMAGE) (  
  IN CONST EFI_HII_IMAGE_PROTOCOL *This,
  IN EFI_HII_DRAW_FLAGS Flags,
  IN CONST EFI_IMAGE_INPUT *Image,
  IN OUT EFI_IMAGE_OUTPUT **Blt,
  IN UINTN BltX,
  IN UINTN BltY,
);

Parameters

This
A pointer to the EFI_HII_IMAGE_PROTOCOL instance.

Flags
Describes how the image is to be drawn. EFI_HII_DRAW_FLAGS is defined in Related Definitions, below.

Image
Points to the image to be displayed.

Blt
If this points to a non-NULL on entry, this points to the image, which is Width pixels wide and Height pixels high. The image will be drawn onto this image and EFI_HII_DRAW_FLAG_CLIP is implied. If this points to a NULL on entry, then a buffer will be allocated to hold the generated image and the pointer updated on exit. It is the caller's responsibility to free this buffer.

BltX, BltY
Specifies the offset from the left and top edge of the image of the first pixel in the image.

Description
This function renders an image to a bitmap or the screen using the specified color and options. It draws the image on an existing bitmap, allocates a new bitmap or uses the screen. The images can be clipped.

If EFI_HII_DRAW_FLAG_CLIP is set, then all pixels drawn outside the bounding box specified by Width and Height are ignored.

The EFI_HII_DRAW_FLAG_TRANSPARENT flag determines whether the image will be drawn transparent or opaque. If EFI_HII_DRAW_FLAG_FORCE_TRANS is set then the image's pixels will be drawn so that all “off” pixels in the image will be drawn using the pixel value from BLT and all other pixels will be copied. If EFI_HII_DRAW_FLAG_FORCE_OPAQUE is set, then the image's pixels will be copied directly to the destination. If EFI_HII_DRAW_FLAG_DEFAULT is set, then the image will be drawn transparently or opaque, depending on the image’s transparency setting (see EFI_IMAGE_TRANSPARENT). Images cannot be drawn transparently if Blt is NULL.
If \textit{EFI\_HII\_DIRECT\_TO\_SCREEN} is set, then the image will be written directly to the output device specified by \textit{Screen}. Otherwise the image will be rendered to the bitmap specified by \textit{Bitmap}.

\textbf{Status Codes Returned}

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The image was successfully updated.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to allocate an output buffer for \textit{Blt}.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The \textit{Image} or \textit{Blt} was NULL.</td>
</tr>
</tbody>
</table>

\subsection*{34.4.6 \texttt{EFI\_HII\_IMAGE\_PROTOCOL.DrawImageId()}}

\textbf{Summary}

Render an image to a bitmap or the screen containing the contents of the specified image.

\textbf{Prototype}

\begin{verbatim}
typedef EFI\_STATUS
    (EFI\_API *EFI\_HII\_DRAW\_IMAGE\_ID) (
    IN CONST EFI\_HII\_IMAGE\_PROTOCOL *This,
    IN EFI\_HII\_DRAW\_FLAGS Flags,
    IN EFI\_HII\_HANDLE PackageList,
    IN EFI\_IMAGE\_ID ImageId,
    IN OUT EFI\_IMAGE\_OUTPUT **Blt,
    IN UINTN BltX,
    IN UINTN BltY,
    );
\end{verbatim}

\textbf{Parameters}

\textbf{This}  
A pointer to the \texttt{EFI\_HII\_IMAGE\_PROTOCOL} instance.

\textbf{Flags}  
Describes how the image is to be drawn. \texttt{EFI\_HII\_DRAW\_FLAGS} is defined in Related Definitions, below.

\textbf{PackageList}  
The package list in the HII database to search for the specified image.

\textbf{ImageId}  
The image’s id, which is unique within \texttt{PackageList}.

\textbf{Blt}  
If this points to a non-NULL on entry, this points to the image, which is \textit{Width} pixels wide and \textit{Height} pixels high. The image will be drawn onto this image and \texttt{EFI\_HII\_DRAW\_FLAG\_CLIP} is implied. If this points to a NULL on entry, then a buffer will be allocated to hold the generated image and the pointer updated on exit. It is the caller’s responsibility to free this buffer.

\textbf{BltX, BltY}  
Specifies the offset from the left and top edge of the output image of the first pixel in the image.

\textbf{Description}

This function renders an image to a bitmap or the screen using the specified color and options. It draws the image on an existing bitmap, allocates a new bitmap or uses the screen. The images can be clipped.
If EFI_HII_DRAW_FLAG_CLIP is set, then all pixels drawn outside the bounding box specified by Width and Height are ignored.

The EFI_HII_DRAW_FLAG_TRANSPARENT flag determines whether the image will be drawn transparent or opaque. If EFI_HII_DRAW_FLAG_FORCE_TRANS is set, then the image will be drawn so that all “off” pixels in the image will be drawn using the pixel value from Blt and all other pixels will be copied. If EFI_HII_DRAW_FLAG_FORCE_OPAQUE is set, then the image’s pixels will be copied directly to the destination. If EFI_HII_DRAW_FLAG_DEFAULT is set, then the image will be drawn transparently or opaque, depending on the image’s transparency setting (EFI_IMAGE_TRANSPARENT). Images cannot be drawn transparently if Blt is NULL.

If EFI_HII_DIRECT_TO_SCREEN is set, then the image will be written directly to the output device specified by Screen. Otherwise the image will be rendered to the bitmap specified by Bitmap.

Related Definitions

```c
typedef UINT32 EFI_HII_DRAW_FLAGS;
#define EFI_HII_DRAW_FLAG_CLIP 0x00000001
#define EFI_HII_DRAW_FLAG_TRANSPARENT 0x00000030
#define EFI_HII_DRAW_FLAG_DEFAULT 0x00000000
#define EFI_HII_DRAW_FLAG_FORCE_TRANS 0x00000010
#define EFI_HII_DRAW_FLAG_FORCE_OPAQUE 0x00000020
#define EFI_HII_DIRECT_TO_SCREEN 0x00000080
```

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The image was successfully updated.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to allocate an output buffer for RowInfoArray or Blt.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The image specified by ImageId is not in the database. The specified PackageList is not in the Database</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The Image or Blt was NULL.</td>
</tr>
</tbody>
</table>

### 34.5 EFI HII Image Ex Protocol

The EFI HII Image Ex protocol defines an extension to the EFI HII Image protocol which enables various new capabilities described in this section.

#### 34.5.1 EFI_HII_IMAGE_EX_PROTOCOL

Summary

Protocol which allows access to the images in the images database

GUID

```c
#define EFI_HII_IMAGE_EX_PROTOCOL_GUID \
{0x1a1241e6, 0x8f19, 0x41a9, 0xbc, \ 
 {0xe, 0xe8, 0xef,0x39, 0xe0, 0x65, 0x46}}
```

Protocol

```c
typedef struct _EFI_HII_IMAGE_EX_PROTOCOL {
   EFI_HII_NEW_IMAGE_EX NewImageEx;
   EFI_HII_GET_IMAGE_EX GetImageEx;
} EFI_HII_IMAGE_EX_PROTOCOL;
```

(continues on next page)
Members

NewImageEx
Add a new image. This protocol invokes the original `EFI_HII_IMAGE_PROTOCOL.NewImage()` implicitly.

GetImageEx
Retrieve an image and the related image information. This function will try to locate the `EFI_HII_IMAGE_DECODER_PROTOCOL` if the image decoder for the image is not supported by the EFI HII image EX protocol.

SetImageEx
Change information about the image, this protocol invokes original `EFI_HII_IMAGE_PROTOCOL.SetImage()` implicitly.

DrawImageEx
Renders an image to a bitmap or the display, this protocol invokes original `EFI_HII_IMAGE_PROTOCOL.DrawImage()` implicitly.

DrawImageIdEx
Renders an image to a bitmap or the screen containing the contents of the specified image, this protocol invokes original `EFI_HII_IMAGE_PROTOCOL.DrawImageId()` implicitly.

GetImageInfo
This function retrieves the image information specified by the image ID which is associated with the specified HII package list. This function only returns the geometry of the image instead of allocating the memory buffer and decoding the image to the buffer.

34.5.2 EFI_HII_IMAGE_EX_PROTOCOL.NewImageEx()

Summary
The prototype of this extension function is the same with `EFI_HII_IMAGE_PROTOCOL.NEWIMAGE()`.

Protocol
typedef
EFI_STATUS
(EIFIAPI *EFI_HII_NEW_IMAGE_EX)(
    IN CONST EFI_HII_IMAGE_EX_PROTOCOL *This,
    IN EFI_HII_HANDLE PackageList,
    OUT EFI_IMAGE_ID *ImageId,
    IN OUT EFI_IMAGE_INPUT *Image
);

Parameters
Same with `EFI_HII_IMAGE_PROTOCOL.NEWIMAGE()`.

Description
Same with `EFI_HII_IMAGE_PROTOCOL.NEWIMAGE()` . This protocol invokes `EFI_HII_IMAGE_PROTOCOL.NEWIMAGE()` implicitly.
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

Status Codes Returned — Same as `EFI_HII_IMAGE_PROTOCOL.NEWIMAGE()`.

### 34.5.3 EFI_HII_IMAGE_EX_PROTOCOL.GetImageEx()

**Summary**

Return the information about the image, associated with the package list. The prototype of this extension function is the same with `EFI_HII_IMAGE_PROTOCOL.GETIMAGE()`.

**Protocol**

```c
typedef EFI_STATUS
(EIFIAPI *EFI_HII_GET_IMAGE_EX)(
    IN CONST EFI_HII_IMAGE_EX_PROTOCOL *This,
    IN EFI_HII_HANDLE PackageList,
    IN EFI_IMAGE_ID ImageId,
    OUT EFI_IMAGE_INPUT *Image
);
```

**Parameters** — Same with `EFI_HII_IMAGE_PROTOCOL.GETIMAGE()`.

**Description**

This function is similar to `EFI_HII_IMAGE_PROTOCOL.GETIMAGE()`. The difference is that this function will locate all `EFI_HII_IMAGE_DECODER_PROTOCOL` instances installed in the system if the decoder of the certain image type is not supported by the `EFI_HII_IMAGE_EX_PROTOCOL`. The function will attempt to decode the image to the `EFI_IMAGE_INPUT` using the first `EFI_HII_IMAGE_DECODER_PROTOCOL` instance that supports the requested image type.

**Status Codes Returned** — Same as `EFI_HII_IMAGE_PROTOCOL.GETIMAGE()`.

### 34.5.4 EFI_HII_IMAGE_EX_PROTOCOL.SetImageEx()

**Summary**

Change the information about the image. The prototype of this extension function is the same with `EFI_HII_IMAGE_PROTOCOL.SetImage()`.

**Protocol**

```c
typedef EFI_STATUS
(EIFIAPI *EFI_HII_SET_IMAGE_EX)(
    IN CONST EFI_HII_IMAGE_EX_PROTOCOL *This,
    IN EFI_HII_HANDLE PackageList,
    IN EFI_IMAGE_ID ImageId,
    IN CONST EFI_IMAGE_INPUT *Image
);
```

**Parameters** — Same with `EFI_HII_IMAGE_PROTOCOL.SetImage()`.

**Description**

Same with `EFI_HII_IMAGE_PROTOCOL.SetImage()`, this protocol invokes `EFI_HII_IMAGE_PROTOCOL.SetImage()` implicitly.

**Status Codes Returned** — Same as `EFI_HII_IMAGE_PROTOCOL.SetImage()`.
34.5.5 EFI_HII_IMAGE_EX_PROTOCOL.DrawImageEx()

Summary

Renders an image to a bitmap or to the display. The prototype of this extension function is the same with EFI_HII_IMAGE_PROTOCOL.DrawImageId().

Protocol

```c
typedef EFI_STATUS
(EIFIAPIT *EFI_HII_DRAW_IMAGE_EX)(
    IN CONST EFI_HII_IMAGE_EX_PROTOCOL *This,
    IN EFI_HII_DRAW_FLAGS Flags,
    IN CONST EFI_IMAGE_INPUT *Image,
    IN OUT EFI_IMAGE_OUTPUT **Blt,
    IN UINTN BltX,
    IN UINTN BltY
);
```

Parameters

Same with EFI_HII_IMAGE_PROTOCOL.DrawImageId().

Description

Same with EFI_HII_IMAGE_PROTOCOL.DrawImage(). This protocol invokes EFI_HII_IMAGE_PROTOCOL.DrawImage() implicitly.

Status Codes Returned — Same as EFI_HII_IMAGE_PROTOCOL.DrawImage().

34.5.6 EFI_HII_IMAGE_EX_PROTOCOL.DrawImageIdEx()

Summary

Renders an image to a bitmap or the screen containing the contents of the specified image. The prototype of this extension function is the same with EFI_HII_IMAGE_PROTOCOL.DrawImageId().

Protocol

```c
typedef EFI_STATUS
(EIFIAPIT *EFI_HII_DRAW_IMAGE_ID_EX)(
    IN CONST EFI_HII_IMAGE_EX_PROTOCOL *This,
    IN EFI_HII_DRAW_FLAGS Flags,
    IN EFI_HII_HANDLE PackageList,
    IN EFI_IMAGE_ID ImageId,
    IN OUT EFI_IMAGE_OUTPUT **Blt,
    IN UINTN BltX,
    IN UINTN BltY
);
```

Parameters — Same with EFI_HII_IMAGE_PROTOCOL.DrawImageId().

Description

This function is similar to EFI_HII_IMAGE_PROTOCOL.DrawImageId(). The difference is that this function will locate all EFI_HII_IMAGE_DECODER_PROTOCOL instances installed in the system if the decoder of the certain
image type is not supported by the `EFI_HII_IMAGE_EX_PROTOCOL`. The function will attempt to decode the image to the `EFI_IMAGE_INPUT` using the first `EFI_HII_IMAGE_DECODER_PROTOCOL` instance that supports the requested image type.

**Status Codes Returned** — Same as `EFI_HII_IMAGE_PROTOCOL.DrawImageID()`.

### 34.5.7 EFI_HII_IMAGE_EX_PROTOCOL.GetImageInfo()

**Summary**

The function returns the information of the image. This function differs from the `EFI_HII_IMAGE_EX_PROTOCOL.GetImageEx()` function. This function only returns the geometry of the image instead of decoding the image to the buffer.

**Protocol**

```c
typedef EFI_STATUS
(EFIAPI *EFI_HII_GET_IMAGE_INFO)(
    IN CONST EFI_HII_IMAGE_EX_PROTOCOL *This,
    IN EFI_HII_HANDLE PackageList,
    IN EFI_IMAGE_ID ImageId,
    OUT EFI_IMAGE_OUTPUT *Image
);
```

**Parameters**

- **This**: `EFI_HII_IMAGE_EX_PROTOCOL` instance.
- **PackageList**: The HII package list.
- **ImageId**: The HII image ID.
- **Image**: `EFI_IMAGE_OUTPUT` to retrieve the image information. Only `Image.Width` and `Image.Height` will be updated by this function. `Image.Bitmap` is always set to `NULL`.

**Description**

*This function returns the image information to `EFI_IMAGE_OUTPUT`. Only the width and height are returned to the `EFI_IMAGE_OUTPUT` instead of decoding the image to the buffer. This function is used to get the geometry of the image. This function will try to locate all of the `EFI_HII_IMAGE_DECODER_PROTOCOL` installed on the system if the decoder of image type is not supported by the `EFI_HII_IMAGE_EX_PROTOCOL`.*

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The image information was returned to Image.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Memory allocation failed in this function.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The format of image is not supported.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The image was not found in the database.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The Image was NULL or ImageId was 0.</td>
</tr>
</tbody>
</table>
34.6 EFI HII Image Decoder Protocol

For those HII image block types which don’t have the corresponding image decoder supported in EFI HII image EX protocol, EFI_HII_IMAGE_DECODER_PROTOCOL can be used to provide the proper image decoder. There may be more than one EFI_HII_IMAGE_DECODER_PROTOCOL instance installed in the system. Each image decoder can decode more than on HII image block types. Whether or not the HII image block type of image is supported by the certain image decoder is reported through the EFI_HII_IMAGE_DECODER_PROTOCOL.GetImageDecoderName(). Caller can invoke this function to verify the image is supported by the image decoder before sending the image raw data to the image decoder. There are two image decoder names defined in this specification: EFI_HII_IMAGE_DECODER_NAME_JPEG and EFI_HII_IMAGE_DECODER_NAME_PNG.

The image decoder protocol can publish the support for additional image decoder names other than the ones defined in this specification. This allows the image decoder to support additional image formats that are not defined by the HII image block types. In that case, callers can send the image raw data to the image decoder protocol instance to retrieve the image information or decode the image. Since the HII image block type of such images is not defined, the image may or may not be decoded by that decoder. The decoder can use the signature or data structures in the image raw data to check the format before it processes the image.

The EFI_HII_IMAGE_EX_PROTOCOL uses EFI_HII_IMAGE_DECODER_PROTOCOL as follows:

34.6.1 EFI_HII_IMAGE_DECODER_PROTOCOL.DecodeImage()

Summary

Provides the image decoder for specific image file formats.

GUID

```c
#define EFI_HII_IMAGE_DECODER_PROTOCOL_GUID \ 
  {0x9E66F251, 0x727C, 0x418C, \ 
  {0xBF, 0xD6, 0xC2, 0xB4, 0x25, 0x28, 0x18, 0xEA}}
```

Protocol

```c
typedef struct _EFI_HII_IMAGE_DECODER_PROTOCOL {
  EFI_HII_IMAGE_DECODER_GET_NAME GetImageDecoderName;
  EFI_HII_IMAGE_DECODER_GET_IMAGE_INFO GetImageInfo;
  EFI_HII_IMAGE_DECODER.Decode DecodeImage;
} EFI_HII_IMAGE_DECODER_PROTOCOL;
```

Members

GetImageDecoderName

The function returns the decoder name.

GetImageInfo

The function returns the image information

DecodeImage

The function decodes the image to the EFI_IMAGE_INPUT

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The image information was returned to Bitmap.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The image decoder can’t decode this image.</td>
</tr>
</tbody>
</table>

continues on next page
Table 34.17 – continued from previous page

<table>
<thead>
<tr>
<th>EFI_OUT_OF_RESOURCE</th>
<th>Not enough memory to decode this image.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The Image was NULL or ImageRawDataSize was 0.</td>
</tr>
</tbody>
</table>

### 34.6.2 EFI_HII_IMAGE_DECODER_PROTOCOL.GetImageDecoderName()

**Summary**
This function returns the decoder name.

**Protocol**

```c
typedef
EFI_STATUS
(EFIAPI *EFI_HII_IMAGE_DECODER_GET_NAME)(
    IN CONST EFI_HII_IMAGE_DECODER_PROTOCOL *This,
    IN OUT EFI_GUID **DecoderName,
    OUT UINT16 *NumberOfDecoderName
);
```

**Parameters**

- **This**
  
  `EFI_HII_IMAGE_DECODER_PROTOCOL` instance.

- **DecoderName**
  
  Pointer to a dimension to retrieve the decoder names in `EFI_GUID` format. The number of the decoder names is returned in `NumberOfDecoderName`.

- **NumberOfDecoderName**
  
  Pointer to retrieve the number of decoders which supported by this decoder driver.

**Description**

There could be more than one `EFI_HII_IMAGE_DECODER_PROTOCOL` instances installed in the system for different image formats. This function returns the decoder name which callers can use to find the proper image decoder for the image. It is possible to support multiple image formats in one `EFI_HII_IMAGE_DECODER_PROTOCOL`. The capability of the supported image formats is returned in `DecoderName` and `NumberOfDecoderName`.

**Related Definitions**

```c
//**********************************************************
// EFI_HII_IMAGE_DECODER_NAME
//**********************************************************
#define EFI_HII_IMAGE_DECODER_NAME_JPEG_GUID
{0xefefd093, 0xd9b, 0x46eb, 0xa8,
  {0x56, 0x48, 0x35, 0x7, 0x0, 0xc9, 0x8}}

#define EFI_HII_IMAGE_DECODER_NAME_PNG_GUID
{0xaf060190, 0x5e3a, 0x4025, 0xaf,
  {0xbd, 0xe1, 0xf9, 0x5, 0xbf, 0xa4, 0xc4}}
```

**Status Codes Returned**

34.6. EFI HII Image Decoder Protocol
Fig. 34.2: How EFI_HII_IMAGE_EX_PROTOCOL uses EFI_HII_IMAGE_DECODER_PROTOCOL
34.6.3 EFI_HII_IMAGE_DECODER_PROTOCOL.GetImageInfo()

Summary
The function returns the EFI_HII_IMAGE_DECODER_IMAGE_INFO to the caller.

Protocol

typedef
EFI_STATUS
(EIFIAPI *EFI_HII_IMAGE_DECODER_GET_IMAGE_INFO)(
    IN CONST EFI_HII_IMAGE_DECODER_PROTOCOL *This,
    IN VOID *Image,
    IN UINTN SizeOfImage,
    IN OUT EFI_HII_IMAGE_DECODER_IMAGE_INFO **ImageInfo
);

Parameters

This
EFI_HII_IMAGE_DECODER_PROTOCOL instance.

Image
Pointer to the image raw data

SizeOfImage
Size of the entire image raw data

ImageInfo
Pointer to receive the EFI_HII_IMAGE_DECODER_IMAGE_INFO

Description
This function returns the image information of the given image raw data. This function first checks whether the image raw data is supported by this decoder or not. This function may go through the first few bytes in the image raw data for the specific data structure or the image signature. If the image is not supported by this image decoder, this function returns EFI_UNSUPPORTED to the caller. Otherwise, this function returns the proper image information to the caller. It is the caller’s responsibility to free then*ImageInfo*.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The image information was returned to ImageInfo.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>No image decoder for the given Image or the image decoder can’t decode this image.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCE</td>
<td>Not enough memory to decode this image for getting the image information.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The Image was NULL, SizeOfImage was 0 or the image is corrupted.</td>
</tr>
</tbody>
</table>

Related Definitions

//******************************************************************************************
//EFI_HII_IMAGE_DECODER_COLOR_TYPE
//***************************************************************************************

(continues on next page)
typedef enum {
    EFI_HII_IMAGE_DECODER_COLOR_TYPE_RGB = 0,
    EFI_HII_IMAGE_DECODER_COLOR_TYPE_RGBA = 1,
    EFI_HII_IMAGE_DECODER_COLOR_TYPE_CMYK = 2,
    EFI_HII_IMAGE_DECODER_COLOR_TYPE_UNKNOWN = 0xff,
} EFI_HII_IMAGE_DECODER_COLOR_TYPE

//***************************************************
// EFI_HII_IMAGE_DECODER_IMAGE_INFO_HEADER
//***************************************************
typedef struct _EFI_HII_IMAGE_DECODER_IMAGE_INFO_HEADER {
    EFI_GUID DecoderName;
    UINT16 ImageInfoSize;
    UINT16 ImageWidth;
    UINT16 ImageHeight;
    EFI_HII_IMAGE_DECODER_COLOR_TYPE ColorType;
    UINT8 ColorDepthInBits;
} EFI_HII_IMAGE_DECODER_IMAGE_INFO_HEADER;

DecoderName
Decoder Name

ImageInfoSize
The size of entire image information structure in bytes.

ImageWidth
The image width.

ImageHeight
The image height.

ColorType
The color type, refer to
EFI_HII_IMAGE_DECODER_COLOR_TYPE.

ColorDepthInBits
The color depth in bits.

//***************************************************
// EFI_HII_IMAGE_DECODER_JPEG_INFO
//***************************************************
typedef struct _EFI_HII_IMAGE_DECODER_JPEG_INFO {
    EFI_HII_IMAGE_DECODER_IMAGE_INFO_HEADER Header;
    UINT16 ScanType;
    UINT64 Reserved;
} EFI_HII_IMAGE_DECODER_JPEG_INFO;

Header
EFI_HII_IMAGE_DECODER_IMAGE_INFO_HEADER

ScanType
The scan type of the JPEG image
#define EFI_IMAGE_JPEG_SCANTYPE_PROGRESSION 0x01
#define EFI_IMAGE_JPEG_SCANTYPE_INTERLACED 0x02

Reserved
    Reserved

//****************************************************
// EFI_HII_IMAGE_DECODER_PNG_INFO
//****************************************************
typedef struct _EFI_HII_IMAGE_DECODER_PNG_INFO {
    EFI_HII_IMAGE_DECODER_IMAGE_INFO_HEADER Header;
    UINT16 Channels;
    UINT64 Reserved;
} EFI_HII_IMAGE_DECODER_PNG_INFO;

Header
    EFI_HII_IMAGE_DECODER_IMAGE_INFO_HEADER

Channels
    Number of channels in the PNG image.

Reserved
    Reserved

//****************************************************
// EFI_HII_IMAGE_DECODER_OTHER_INFO
//****************************************************
typedef struct _EFI_HII_IMAGE_DECODER_OTHER_INFO {
    EFI_HII_IMAGE_DECODER_IMAGE_INFO_HEADER Header;
    CHAR16 ImageExtenion[1];
    //
    // Variable length of image file extension name.
    //
} EFI_HII_IMAGE_DECODER_OTHER_INFO;

Header
    EFI_HII_IMAGE_DECODER_IMAGE_INFO_HEADER

ImageExtenion
    The string of the image file extension. For example, “GIF”, “TIFF” or others.

34.6.4 EFI_HII_IMAGE_DECODER_PROTOCOL.Decode()

Summary
    The function decodes the image

Protocol

typedef
    EFI_STATUS
    (EFIAPI *EFI_HII_IMAGE_DECODER_DECODE)(
        IN CONST EFI_HII_IMAGE_DECODER_PROTOCOL *This,
        IN VOID *Image,
        IN UINTN ImageRawDataSize,
        IN OUT EFI_IMAGE_OUTPUT **Bitmap,
    )

(continues on next page)
Parameters

This

    EFI_HII_IMAGE_DECODER_PROTOCOL instance.

Image

    Pointer to the image raw data

ImageRawDataSize

    Size of the entire image raw data

Bitmap

    EFI_IMAGE_OUTPUT to receive the image or overlap the image on the original buffer.

Transparent

    BOOLEAN value indicates whether the image decoder has to handle the transparent image or not.

Description

This function decodes the image which the image type of this image is supported by this EFI_HII_IMAGE_DECODER_PROTOCOL. If Bitmap is not NULL, the caller intends to put the image in the given image buffer. That allows the caller to put an image overlap on the original image. The transparency is handled by the image decoder because the transparency capability depends on the image format. Callers can set Transparent to FALSE to force disabling the transparency process on the image. Forcing Transparent to FALSE may also improve the performance of the image decoding because the image decoder can skip the transparency processing.

If Bitmap is NULL, the image decoder allocates the memory buffer for the EFI_IMAGE_OUTPUT and decodes the image to the image buffer. It is the caller’s responsibility to free the memory for EFI_IMAGE_OUTPUT. Image decoder doesn’t have to handle the transparency in this case because there is no background image given by the caller. The background color in this case is all black (#00000000).

34.7 Font Glyph Generator Protocol

The EFI HII Font glyph generator protocol generates font glyphs of the requested characters according to the given font information. This protocol is utilized by the EFI_HII_FONT_EX_PROTOCOL when the character can’t be found in the existing glyph database. That is when glyph is not found in any HII font package, EFI_HII_FONT_EX_PROTOCOL locates EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL to generate glyph block and insert glyph block into HII font package. The HII font package can be an existing HII font package or a new HII font package. This protocol can be provided by any driver that knows how to generate the glyph for a specific font family. For example, EFI application or driver may provide “Times new roman” font glyph generator driver. With this driver, platform can have “Times new roman” font supported on system.*
34.7.1 EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL

Summary

EFI HII Font glyph generator protocol generates the glyph of the character according to the given font information.

GUID

```
#define EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL_GUID \
{ 0xf7102853, 0x7787, 0x4dc2, 0xa8, \
  {0xa8, 0x21, 0xb5, 0xdd, 0x5, 0xc8, 0x9b }}
```

Protocol

```
typedef struct _EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL {
    EFI_GENERATE_GLYPH GenerateGlyph;
    EFI_GENERATE_IMAGE GenerateGlyphImage;
} EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL;
```

Members

GenerateGlyph

The function generates the glyph information according to the given font information.

GenerateGlyphImage

The function generates the glyph image according to the given font information.

34.7.2 EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL.GenerateGlyph()

Summary

The function generates the glyph information according to the given font information. This function returns the glyph block in EFI_HII_GIBT_GLYPH_VARIABILITY type.

Protocol

```
typedef
    EFI_STATUS
    (EFIAPI *EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL)(
    IN CONST EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL *This,
    IN CHAR16 Char,
    IN CONST EFI_FONT_DISPLAY_INFO *FontInfo,
    OUT EFI_HII_GIBT_VARIABILITY_BLOCK *GlyphBlock);
```

Parameters

This

 EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL instance.

Char

Character to retrieve.

FontInfo

Font display information of this character.

GlyphBlock

Pointer to retrieve the EFI_HII_GIBT_VARIABILITY_BLOCK
Description

This function generates the glyph information of the character in the specific font family. EFI_HII_GIBT_VARIABILITY_BLOCK is returned to GlyphBlock if GlyphBlock is not NULL. GlyphBlock can be called by EFI_HII_FONT_EX_PROTOCOL to retrieve the glyph information which are provided by the font family specific driver, or can be used to build up the HII font package if the HII font package with the specific font family does not exist in the HII database.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The glyph information was returned to GlyphBlock.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The FontInfo or GlyphBlock was NULL.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCE</td>
<td>Not enough memory to generate the glyph information.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The font glyph generator can't generate the glyph for the given Char. This may caused by the unsupported character, font name font style or font size.</td>
</tr>
</tbody>
</table>

34.7.3 EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL.GenerateGlyphImage()

Summary

The function generates the glyph image according to the given font information. This function returns EFI_GRAPHICS_OUTPUT_BLT_PIXEL points to the EFI_IMAGE_OUTPUT buffer. This function is used for glyphs which are reported in the font database as EFI_HII_GIBT_GLYPH_VARIABILITY glyph blocks.

Protocol

```c
typedef EFI_STATUS (EFIAPI *EFI_HII_GENERATE_GLYPH_IMAGE)(
    IN CONST EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL *This,
    IN CONST EFI_HII_GLYPH_INFO *Cell,
    IN UINT8 *GlyphBuffer,
    IN CONST EFI_FONT_DISPLAY_INFO *FontInfo,
    IN OUT EFI_IMAGE_OUTPUT *Image,
    IN INT32 *BltX,
    IN INT32 *BltY,
    IN BOOLEAN Transparent ) ;
```

Parameters

This

EFI_HII_FONT_GLYPH_GENERATOR_PROTOCOL instance.

Cell

Pointer to EFI_HII_GLYPH_INFO

GlyphBuffer

The buffer points to the bitmap of glyph. This pointer points to GlyphBlock.BitmapData which returned from GenerateGlyph()function

FontInfo

Font display information of this glyph.

Image

Image output buffer to retrieve the glyph image.

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BltX
Together with BltY, specifies the offset from the left and top edge of the image of the first character cell in the *Image.*

BltY
Together with BltX, specifies the offset from the left and top edge of the image of the first character cell in the *Image.*

Transparent
If TRUE, the Background color is ignored and all "off" pixels in the character's drawn will use the pixel value from *Image.*

Description
This function generates the glyph image of the character in the specific font family on the given EFI_IMAGE_OUTPUT

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The glyph image was generated in Image.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCE</td>
<td>Not enough memory to generate image of the given glyph.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The font glyph generator can't generate the glyph for the given FontInfo.</td>
</tr>
<tr>
<td></td>
<td>This may caused by the unsupported font name, font style or font size.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more parameters of Cell, GlyphBuffe, FontInfo, Image, BltX or BltY was NULL.</td>
</tr>
</tbody>
</table>

34.8 Database Protocol

34.8.1 EFI_HII_DATABASE_PROTOCOL

Summary
Database manager for HII-related data structures.

GUID

```c
#define EFI_HII_DATABASE_PROTOCOL_GUID \
{ 0xef9fc172, 0xa1b2, 0x4693,\ 
  { 0xb3, 0x27, 0x6d, 0x32, 0xfc, 0x41, 0x60, 0x42 }}
```

Protocol

```c
typedef struct _EFI_HII_DATABASE_PROTOCOL {
  EFI_HII_DATABASE_NEW_PACK NewPackageList;
  EFI_HII_DATABASE_REMOVE_PACK RemovePackageList;
  EFI_HII_DATABASE_UPDATE_PACK UpdatePackageList;
  EFI_HII_DATABASE_LIST_PACKS ListPackageLists;
  EFI_HII_DATABASE_EXPORT_PACKS ExportPackageLists;
  EFI_HII_DATABASE_REGISTER_NOTIFY RegisterPackageNotify;
  EFI_HII_DATABASE_UNREGISTER_NOTIFY UnregisterPackageNotify;
  EFI_HII_FIND_KEYBOARD_LAYOUTS FindKeyboardLayouts;
  EFI_HII_GET_KEYBOARD_LAYOUT GetKeyboardLayout;
  EFI_HII_SET_KEYBOARD_LAYOUT SetKeyboardLayout;
  EFI_HII_DATABASE_GET_PACK_HANDLE GetPackageListHandle;
} EFI_HII_DATABASE_PROTOCOL;
```
Members

**NewPackageList**
Add a new package list to the HII database.

**RemovePackageList**
Remove a package list from the HII database.

**UpdatePackageList**
Update a package list in the HII database.

**ListPackageLists**
List the handles of the package lists within the HII database.

**ExportPackageLists**
Export package lists from the HII database.

**RegisterPackageNotify**
Register notification when packages of a certain type are installed.

**UnregisterPackageNotify**
Unregister notification of packages.

**FindKeyboardLayouts**
Retrieves a list of the keyboard layouts in the system.

**GetKeyboardLayout**
Allows a program to extract the current keyboard layout. See the GetKeyboardLayout() function description.

**SetKeyboardLayout**
Changes the current keyboard layout. See the SetKeyboardLayout() function description.

**GetPackageListHandle**
Return the EFI handle associated with a given package list.

### 34.8.2 EFI_HII_DATABASE_PROTOCOL.NewPackageList()

**Summary**
Adds the packages in the package list to the HII database.

**Prototype**

```c
typedef EFI_STATUS
(EIFIAPI *EFI_HII_DATABASE_NEW_PACK) (  
    IN CONST EFI_HII_DATABASE_PROTOCOL *This,  
    IN CONST EFI_HII_PACKAGE_LIST_HEADER *PackageList,  
    IN CONST EFI_HANDLE DriverHandle, OPTIONAL  
    OUT EFI_HII_HANDLE *Handle
    );
```

**Parameters**

**This**
A pointer to the `EFI_HII_DATABASE_PROTOCOL` instance.

**PackageList**
A pointer to an `EFI_HII_PACKAGE_LIST_HEADER` structure.
DriverHandle
   Associate the package list with this EFI handle

Handle
   A pointer to the EFI_HII_HANDLE instance. Type EFI_HII_HANDLE is defined in “Related Definitions” below.

Description
   This function adds the packages in the package list to the database and returns a handle. If there is a
   EFI_DEVICE_PATH_PROTOCOL associated with the DriverHandle, then this function will create a package of type
   EFI_PACKAGE_TYPE_DEVICE_PATH and add it to the package list.

   For each package in the package list, registered functions with the notification type NEW_PACK and having the same
   package type will be called.

   For each call to NewPackageList(), there should be a corresponding call to
   EFI_HII_DATABASE_PROTOCOL.RemovePackageList().

Related Definitions
   typedef void *EFI_HII_HANDLE:

Status Codes Returns

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The package list associated with the Handle was added to the HII database.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to allocate necessary resources for the new database contents.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PackageList is NULL or Handle is NULL.</td>
</tr>
</tbody>
</table>

34.8.3 EFI_HII_DATABASE_PROTOCOL.RemovePackageList()

Summary
   Removes a package list from the HII database.

Prototype

   typedef
   EFI_STATUS
   (EFIAPIC *EFI_HII_DATABASE_REMOVE_PACK) (  
      IN CONST EFI_HII_DATABASE_PROTOCOL *This,
      IN EFI_HII_HANDLE Handle
   );

Parameters
This
   A pointer to the EFI_HII_DATABASE_PROTOCOL instance.

Handle
   The handle that was registered to the data that is requested for removal. Type EFI_HII_HANDLE is defined in
   EFI_HII_DATABASE_PROTOCOL.NewPackageList() in the Packages section.

Description
   This function removes the package list that is associated with a handle Handle from the HII database. Before removing
   the package, any registered functions with the notification type REMOVE_PACK and the same package type will be called.
For each call to `EFI_HII_DATABASE_PROTOCOL.NewPackageList()`, there should be a corresponding call to `RemovePackageList`.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The data associated with the <code>Handle</code> was removed from the HII database.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified <code>Handle</code> is not in the Database.</td>
</tr>
</tbody>
</table>

### 34.8.4 EFI_HII_DATABASE_PROTOCOL.UpdatePackageList()

**Summary**

Update a package list in the HII database.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_HII_DATABASE_UPDATE_PACK) (  
    IN CONST EFI_HII_DATABASE_PROTOCOL *This,  
    IN EFI_HII_HANDLE Handle,  
    IN CONST EFI_HII_PACKAGE_LIST_HEADER *PackageList,  
);
```

**Parameters**

- **This**
  
  A pointer to the `EFI_HII_DATABASE_PROTOCOL` instance.

- **Handle**
  
  The handle that was registered to the data that is requested to be updated. Type `EFI_HII_HANDLE` is defined in `EFI_HII_DATABASE_PROTOCOL.NewPackageList()` in the Packages section.

- **PackageList**
  
  A pointer to an instance of `EFI_HII_PACKAGE_LIST_HEADER`.

**Description**

This function updates the existing package list (which has the specified `Handle`) in the HII databases, using the new package list specified by `PackageList`. The update process has the following steps:

1. Collect all the package types in the package list specified by `PackageList`. A package type consists of the `Type` field of `EFI_HII_PACKAGE_HEADER` and, if the `Type` is `EFI_HII_PACKAGE_TYPE_GUID`, the `Guid` field, as defined in `EFI_HII_GUID_PACKAGE_HDR`.
2. Iterate through the packages within the existing package list in the HII database specified by `Handle`. If a package's type matches one of the types collected in step 1, then perform the following steps:
   - Call any functions registered with the notification type `REMOVE_PACK`.
   - Remove the package from the package list and the HII database.
3. Add all of the packages within the new package list specified by `PackageList`, using the following steps:
   - Add the package to the package list and the HII database.
   - Call any functions registered with the notification type `ADD_PACK`.

**Status Codes Returned**
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

<table>
<thead>
<tr>
<th>EFI_SUCCESS</th>
<th>The HII database was successfully updated.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to allocate enough memory for the updated database.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PackageList was NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified Handle is not in the Database.</td>
</tr>
</tbody>
</table>

### 34.8.5 EFI_HII_DATABASE_PROTOCOL.ListPackageLists()

**Summary**

Determines the handles that are currently active in the database.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_HII_DATABASE_LIST_PKCS) ( 
    IN CONST EFI_HII_DATABASE_PROTOCOL *This, 
    IN UINT8 PackageType, 
    IN CONST EFI_GUID *PackageGuid, 
    IN OUT UINTN *HandleBufferLength, 
    OUT EFI_HII_HANDLE *Handle 
);
```

**Parameters**

- **This**
  A pointer to the EFI_HII_DATABASE_PROTOCOL instance.

- **PackageType**
  Specifies the package type of the packages to list or EFI_HII_PACKAGE_TYPE_ALL for all packages to be listed.

- **PackageGuid**
  If PackageType is EFI_HII_PACKAGE_TYPE_GUID, then this is the pointer to the GUID which must match the Guid field of EFI_HII_GUID_PACKAGE_HDR. Otherwise, it must be NULL.

- **HandleBufferLength**
  On input, a pointer to the length of the handle buffer. On output, the length of the handle buffer that is required for the handles found.

- **Handle**
  An array of EFI_HII_HANDLE instances returned. Type EFI_HII_HANDLE is defined in EFI_HII_DATABASE_PROTOCOL.NewPackageList() in the Packages section.

**Description**

This function returns a list of the package handles of the specified type that are currently active in the database. The pseudo-type EFI_HII_PACKAGE_TYPE_ALL will cause all package handles to be listed.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>A list of Packages was placed in Handle successfully. HandleBufferLength is updated with the actual length.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The HandleBufferLength parameter indicates that Handle is too small to support the number of handles. HandleBufferLength is updated with a value that will enable the data to fit.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HandleBufferLength was NULL.</td>
</tr>
</tbody>
</table>

continues on next page
Table 34.25 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The value referenced by HandleBufferLength was not zero and Handle was NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PackageType is a EFI_HII_PACKAGE_TYPE_GUID but PackageGuid is not NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PackageType is a EFI_HII_PACKAGE_TYPE_GUID but PackageGuid is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No matching handles were found</td>
</tr>
</tbody>
</table>

34.8.6 EFI_HII_DATABASE_PROTOCOL.ExportPackageLists()

Summary
Exports the contents of one or all package lists in the HII database into a buffer.

Prototype

typedef
EFI_STATUS
(EIFIAPIC *EFI_HII_DATABASE_EXPORT_PCKS) ( |
  IN CONST EFI_HII_DATABASE_PROTOCOL *This, |
  IN EFI_HII_HANDLE Handle, |
  IN OUT UINTN *BufferSize, |
  OUT EFI_HII_PACKAGE_LIST_HEADER *Buffer |
);

Parameters

This
A pointer to the EFI_HII_DATABASE_PROTOCOL instance.

Handle
An EFI_HII_HANDLE that corresponds to the desired package list in the HII database to export or NULL to indicate all package lists should be exported.

BufferSize
On input, a pointer to the length of the buffer. On output, the length of the buffer that is required for the exported data.

Buffer
A pointer to a buffer that will contain the results of the export function.

Description
This function will export one or all package lists in the database to a buffer. For each package list exported, this function will call functions registered with EXPORT_PACK and then copy the package list to the buffer. The registered functions may call EFI_HII_DATABASE_PROTOCOL.UpdatePackageList() to modify the package list before it is copied to the buffer.

If the specified BufferSize is too small, then the status EFI_BUFFER_TOO_SMALL will be returned and the actual package size will be returned in BufferSize.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Package exported.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>BufferSize is too small to hold the package.</td>
</tr>
</tbody>
</table>
Table 34.26 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>BufferSize was NULL</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The value referenced by BufferSize was not zero and Buffer was NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified Handle could not be found in the current database.</td>
</tr>
</tbody>
</table>

### 34.8.7 EFI_HII_DATABASE_PROTOCOL.RegisterPackageNotify()

**Summary**

Registers a notification function for HII database-related events.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_HII_DATABASE_REGISTER_NOTIFY) (  
  IN CONST EFI_HII_DATABASE_PROTOCOL *This,  
  IN UINT8 PackageType,  
  IN CONST EFI_GUID *PackageGuid,  
  IN CONST EFI_HII_DATABASE_NOTIFY PackageNotifyFn,  
  IN EFI_HII_DATABASE_NOTIFY_TYPE NotifyType,  
  OUT EFI_HANDLE *NotifyHandle  
);
```

**Parameters**

- **This**
  A pointer to the `EFI_HII_DATABASE_PROTOCOL` instance.

- **PackageType**
  The package type. See `EFI_HII_PACKAGE_TYPE_x` in `EFI_HII_PACKAGE_HEADER`.

- **PackageGuid**
  If `PackageType` is `EFI_HII_PACKAGE_TYPE_GUID`, then this is the pointer to the GUID which must match the `Guid` field of `EFI_HII_GUID_PACKAGE_HDR`. Otherwise, it must be `NULL`.

- **PackageNotifyFn**
  Points to the function to be called when the event specified by `NotificationType` occurs. See ``.

- **NotifyType**
  Describes the types of notification which this function will be receiving. See `EFI_HII_DATABASE_NOTIFY` for more a list of types.

- **NotifyHandle**
  Points to the unique handle assigned to the registered notification. Can be used in `EFI_HII_DATABASE_PROTOCOL.UnregisterPackageNotify()` to stop notifications.

**Description**

This function registers a function which will be called when specified actions related to packages of the specified type occur in the HII database. By registering a function, other HII-related drivers are notified when specific package types are added, removed or updated in the HII database.

Each driver or application which registers a notification should use `EFI_HII_DATABASE_PROTOCOL.UnregisterPackageNotify()` before exiting.

If a driver registers a `NULL PackageGuid` when `PackageType` is `EFI_HII_PACKAGE_TYPE_GUID`, a notification will occur for every package of type `EFI_HII_PACKAGE_TYPE_GUID` that is registered.
Related Definitions

EFI_HII_PACKAGE_HEADER is defined in EFI_HII_PACKAGE_HEADER.
EFI_HII_DATABASE_NOTIFY is defined in EFI_HII_DATABASE_NOTIFY.
EFI_HII_DATABASE_NOTIFY_TYPE is defined in EFI_HII_DATABASE_NOTIFY_TYPE.

Returned Status Codes

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Notification registered successfully.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Unable to allocate necessary data structures.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>NotifyHandle is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PackageType is not an EFI_HII_PACKAGE_TYPE_GUID but PackageGuid is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PackageType is a EFI_HII_PACKAGE_TYPE_GUID but PackageGuid is NULL.</td>
</tr>
</tbody>
</table>

34.8.8 EFI_HII_DATABASE_PROTOCOL.UnregisterPackageNotify()

Summary

Removes the specified HII database package-related notification.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_HII_DATABASE_UNREGISTER_NOTIFY) (
    IN CONST EFI_HII_DATABASE_PROTOCOL *This,
    IN EFI_HANDLE NotificationHandle
);
```

Parameters

This

A pointer to the EFI_HII_DATABASE_PROTOCOL instance.

NotificationHandle

The handle of the notification function being unregistered.

Returned Status Codes

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Invalidated</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The NotificationHandle could not be found in the database.</td>
</tr>
</tbody>
</table>

34.8.9 EFI_HII_DATABASE_PROTOCOL.FindKeyboardLayouts()

Summary

Retrieves a list of the keyboard layouts in the system.

Prototype
typedef EFI_STATUS (EFIAPI *EFI_HII_FIND_KEYBOARD_LAYOUTS) (  
  IN CONST EFI_HII_DATABASE_PROTOCOL *This,  
  IN OUT UINT16 *KeyGuidBufferLength,  
  OUT EFI_GUID *KeyGuidBuffer  
);

Parameters

This
A pointer to the EFI_HII_DATABASE_PROTOCOL instance.

KeyGuidBufferLength
On input, a pointer to the length of the keyboard GUID buffer. On output, the length of the handle buffer that is required for the handles found.

KeyGuidBuffer
An array of keyboard layout GUID instances returned.

Description
This routine retrieves an array of GUID values for each keyboard layout that was previously registered in the system.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>KeyGuidBuffer was updated successfully.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The KeyGuidBufferLength parameter indicates that KeyGuidBuffer is too small to support the number of GUIDs. KeyGuidBufferLength is updated with a value that will enable the data to fit.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>KeyGuidBufferLength is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The value referenced by KeyGuidBufferLength is not zero and KeyGuidBuffer is NULL.</td>
</tr>
</tbody>
</table>

34.8.10 EFI_HII_DATABASE_PROTOCOL.GetKeyboardLayout()

Summary
Retrieves the requested keyboard layout.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_HII_GET_KEYBOARD_LAYOUT) (  
  IN CONST EFI_HII_DATABASE_PROTOCOL *This,  
  IN EFI_GUID *KeyGuid,  
  IN OUT UINT16 *KeyboardLayoutLength,  
  OUT EFI_HII_KEYBOARD_LAYOUT *KeyboardLayout  
);

Parameters

This
A pointer to the EFI_HII_DATABASE_PROTOCOL instance.
KeyGuid
A pointer to the unique ID associated with a given keyboard layout. If KeyGuid is NULL then the current layout will be retrieved.

KeyboardLayout
A pointer to a buffer containing the retrieved keyboard layout. below.

KeyboardLayoutLength
On input, a pointer to the length of the KeyboardLayout buffer. On output, the length of the data placed into KeyboardLayout.

Description
This routine retrieves the requested keyboard layout. The layout is a physical description of the keys on a keyboard and the character(s) that are associated with a particular set of key strokes.

Related Definitions

```
//**************************************************************
// EFI_HII_KEYBOARD_LAYOUT
//**************************************************************
typedef struct {
  UINT16 LayoutLength;
  EFI_GUID Guid;
  UINT32 LayoutDescriptorStringOffset;
  UINT8 DescriptorCount;
  EFI_KEY_DESCRIPTOR Descriptors[];
} EFI_HII_KEYBOARD_LAYOUT;
```

LayoutLength
The length of the current keyboard layout.

Guid
The unique ID associated with this keyboard layout.

LayoutDescriptorStringOffset
An offset location (0 is the beginning of the EFI_KEYBOARD_LAYOUT instance) of the string which describes this keyboard layout. The data that is being referenced is in EFI_DESCRIPTION_STRING_BUNDLE format.

DescriptorCount
The number of Descriptor entries in this layout.

Descriptors
An array of key descriptors.

```
//**************************************************************
// EFI_DESCRIPTION_STRING - byte packed data
//**************************************************************
CHAR16 Language[];
CHAR16 Space;
//CHAR16 DescriptionString[];
```

Language
The language in RFC 4646 format to associate with DescriptionString.

Space
A space (U-0x0020) character to force as a separator between the Language field and the formal description string.
DescriptionString

A null-terminated description string.

```c
//*******************************************************************************
// EFI_DESCRIPTION_STRING_BUNDLE - byte packed data
//
// Example: 2en-US English Keyboard<null>es-ES Keyboard en ingles<null>
// <null> = U-0000
//*******************************************************************************
UINT16 DescriptionCount;
EFI_DESCRIPTION_STRING DescriptionString[];
```

DescriptionCount

The number of description strings.

DescriptionString

An array of language-specific description strings.

```c
//*******************************************************************************
// EFI_KEY_DESCRIPTOR
//*******************************************************************************
typedef struct {
    EFI_KEY Key;
    CHAR16 Unicode;
    CHAR16 ShiftedUnicode;
    CHAR16 AltGrUnicode;
    CHAR16 ShiftedAltGrUnicode;
    UINT16 Modifier;
    UINT16 AffectedAttribute;
} EFI_KEY_DESCRIPTOR;
```

Key

Used to describe a physical key on a keyboard. Type EFI_KEY is defined below.

Unicode

Unicode character code for the Key.

ShiftedUnicode

Unicode character code for the key with the shift key being held down.

AltGrUnicode

Unicode character code for the key with the Alt-GR being held down.
ShiftedAltGrUnicode

Unicode character code for the key with the Alt-GR and shift keys being held down.

Modifier

Modifier keys are defined to allow for special functionality that is not necessarily accomplished by a printable character. Many of these modifier keys are flags to toggle certain state bits on and off inside of a keyboard driver. Values for Modifier are defined below.

```c
typedef enum {
    EfiKeyLCtrl, EfiKeyA0, EfiKeyLAlt, EfiKeySpaceBar, EfiKeyA2,
    EfiKeyA3, EfiKeyA4, EfiKeyRCtrl, EfiKeyLeftArrow,
    EfiKeyDownArrow, EfiKeyRightArrow, EfiKeyZero, EfiKeyPeriod,
    EfiKeyEnter, EfiKeyLShift, EfiKeyB0, EfiKeyB1, EfiKeyB2,
    EfiKeyB3, EfiKeyB4, EfiKeyB5, EfiKeyB6, EfiKeyB7, EfiKeyB8,
    EfiKeyB9, EfiKeyB10, EfiKeyRShift, EfiKeyUpArrow, EfiKeyOne,
    EfiKeyTwo, EfiKeyThree, EfiKeyCapsLock, EfiKeyC1, EfiKeyC2,
    EfiKeyC3, EfiKeyC4, EfiKeyC5, EfiKeyC6, EfiKeyC7, EfiKeyC8,
    EfiKeyC9, EfiKeyC10, EfiKeyC11, EfiKeyC12, EfiKeyFour,
    EfiKeyFive, EfiKeySix, EfiKeyPlus, EfiKeyTab, EfiKeyD1,
    EfiKeyD2, EfiKeyD3, EfiKeyD4, EfiKeyD5, EfiKeyD6, EfiKeyD7,
    EfiKeyD8, EfiKeyD9, EfiKeyD10, EfiKeyD11, EfiKeyD12, EfiKeyD13,
    EfiKeyDel, EfiKeyEnd, EfiKeyPgDn, EfiKeySeven, EfiKeyEight,
    EfiKeyNine, EfiKeyE0, EfiKeyE1, EfiKeyE2, EfiKeyE3, EfiKeyE4,
    EfiKeyE5, EfiKeyE6, EfiKeyE7, EfiKeyE8, EfiKeyE9, EfiKeyE10,
    EfiKeyE11, EfiKeyE12, EfiKeyBackSpace, EfiKeyIns, EfiKeyHome,
    EfiKeyPgUp, EfiKeyNLck, EfiKeySlash, EfiKeyAsterisk,
    EfiKeyMinus, EfiKeyEsc, EfiKeyF1, EfiKeyF2, EfiKeyF3, EfiKeyF4,
    EfiKeyF5, EfiKeyF6, EfiKeyF7, EfiKeyF8, EfiKeyF9, EfiKeyF10,
    EfiKeyF11, EfiKeyF12, EfiKeyPrint, EfiKeySLck, EfiKeyPause,
    EfiKeyInt10, EfiKeyInt11, EfiKeyInt12, EfiKeyInt13,
    EfiKeyInt14, EfiKeyInt15, EfiKeyInt16, EfiKeyInt17,
    EfiKeyInt18, EfiKeyInt19
} EFI_KEY;
```

See the figure below for which key corresponds to the values in the enumeration above. For example, `EfiKeyLCtrl` corresponds to the left control key in the lower-left corner of the keyboard, `EfiKeyFour` corresponds to the 4 key on the numeric keypad, and `EfiKeySLck` corresponds to the Scroll Lock key in the upper-right corner of the keyboard.

Fig. 34.3: Keyboard Layout
// Modifier values
UPPORTED
/
#define EFI_NULL_MODIFIER 0x0000
#define EFI_LEFT_CONTROL_MODIFIER 0x0001
#define EFI_RIGHT_CONTROL_MODIFIER 0x0002
#define EFI_LEFT_ALT_MODIFIER 0x0003
#define EFI_RIGHT_ALT_MODIFIER 0x0004
#define EFI_ALT_GR_MODIFIER 0x0005
#define EFI_INSERT_MODIFIER 0x0006
#define EFI_DELETE_MODIFIER 0x0007
#define EFI_PAGE_DOWN_MODIFIER 0x0008
#define EFI_PAGE_UP_MODIFIER 0x0009
#define EFI_HOME_MODIFIER 0x000A
#define EFI_END_MODIFIER 0x000B
#define EFI_LEFT_SHIFT_MODIFIER 0x000C
#define EFI_RIGHT_SHIFT_MODIFIER 0x000D
#define EFI_CAPS_LOCK_MODIFIER 0x000E
#define EFI_NUM_LOCK_MODIFIER 0x000F
#define EFI_LEFT_ARROW_MODIFIER 0x0010
#define EFI_RIGHT_ARROW_MODIFIER 0x0011
#define EFI_DOWN_ARROW_MODIFIER 0x0012
#define EFI_UP_ARROW_MODIFIER 0x0013
#define EFI_NS_KEY_MODIFIER 0x0014
#define EFI_NS_KEY_DEPENDENCY_MODIFIER 0x0015
#define EFI_FUNCTION_KEY_ONE_MODIFIER 0x0016
#define EFI_FUNCTION_KEY_TWO_MODIFIER 0x0017
#define EFI_FUNCTION_KEY_THREE_MODIFIER 0x0018
#define EFI_FUNCTION_KEY_FOUR_MODIFIER 0x0019
#define EFI_FUNCTION_KEY_FIVE_MODIFIER 0x001A
#define EFI_FUNCTION_KEY_SIX_MODIFIER 0x001B
#define EFI_FUNCTION_KEY_SEVEN_MODIFIER 0x001C
#define EFI_FUNCTION_KEY_EIGHT_MODIFIER 0x001D
#define EFI_FUNCTION_KEY_NINE_MODIFIER 0x001E
#define EFI_FUNCTION_KEY_TEN_MODIFIER 0x001F
#define EFI_FUNCTION_KEY_ELEVEN_MODIFIER 0x0020
#define EFI_FUNCTION_KEY_TWELVE_MODIFIER 0x0021
/
// Keys that have multiple control functions based on modifier
// settings are handled in the keyboard driver implementation.
// For instance PRINT_KEY might have a modifier held down and
// is still a nonprinting character, but might have an alternate
// control function like SYSREQUEST
/
#define EFI_PRINT_MODIFIER 0x0022
#define EFI_SYS_REQUEST_MODIFIER 0x0023
#define EFI_SCROLL_LOCK_MODIFIER 0x0024
#define EFI_PAUSE_MODIFIER 0x0025
#define EFI_BREAK_MODIFIER 0x0026
#define EFI_LEFT_LOGO_MODIFIER 0x0027
#define EFI_RIGHT_LOGO_MODIFIER 0x0028
#define EFI_MENU_MODIFIER 0x0029
Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The keyboard layout was retrieved successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The requested keyboard layout was not found.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The KeyboardLayoutLength parameter indicates the KeyboardLayout is too small to hold the keyboard layout.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>KeyboardLayoutLength is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The value referenced by KeyboardLayoutLength is not zero and KeyboardLayout is NULL.</td>
</tr>
</tbody>
</table>

34.8.11 EFI_HII_DATABASE_PROTOCOL.SetKeyboardLayout()

Summary
Sets the currently active keyboard layout.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_HII_SET_KEYBOARD_LAYOUT) (IN CONST EFI_HII_DATABASE_PROTOCOL *This,
IN EFI_GUID *KeyGuid);

Parameters
This
A pointer to the EFI_HII_DATABASE_PROTOCOL instance.

KeyGuid
A pointer to the unique ID associated with a given keyboard layout.

Description
This routine sets the default keyboard layout to the one referenced by KeyGuid. When this routine is called, an event will be signaled of the EFI_HII_SET_KEYBOARD_LAYOUT_EVENT_GUID group type. This is so that agents which are sensitive to the current keyboard layout being changed can be notified of this change.

Related Definitions
GUID

#define EFI_HII_SET_KEYBOARD_LAYOUT_EVENT_GUID \ 
{ 0x14982a4f, 0xb0ed, 0x45b8, \ 
  { 0xa8, 0x11, 0x5a, 0x7a, 0x9b, 0xc2, 0x32, 0xdf }}

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The current keyboard layout was successfully set.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The referenced keyboard layout was not found, so action was taken.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>KeyGuid is NULL.</td>
</tr>
</tbody>
</table>
34.8.12 EFI_HII_DATABASE_PROTOCOL.GetPackageListHandle()

Summary
Return the EFI handle associated with a package list.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPIC *EFI_HII_DATABASE_GET_PACK_HANDLE) (EFIAPI
    IN CONST EFI_HII_DATABASE_PROTOCOL *This,
    IN EFI_HII_HANDLE PackageListHandle,
    OUT EFI_HANDLE *DriverHandle
);```

Parameters

**This**
A pointer to the `EFI_HII_DATABASE_PROTOCOL` instance.

**PackageListHandle**
An `EFI_HII_HANDLE` that corresponds to the desired package list in the HII database.

**DriverHandle**
On return, contains the `EFI_HANDLE` which was registered with the package list in `NewPackageList()`.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The <code>DriverHandle</code> was returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>PackageListHandle</code> was not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The <code>DriverHandle</code> must not be NULL.</td>
</tr>
</tbody>
</table>

34.8.13 Database Structures

34.8.13.1 EFI_HII_DATABASE_NOTIFY

Summary
Handle a registered notification for a package change to the database.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPIC *EFI_HII_DATABASE_NOTIFY) (EFIAPI
    IN UINT8 PackageType,
    IN CONST EFI_GUID *PackageGuid,
    IN CONST EFI_HII_PACKAGE_HEADER *Package,
    IN EFI_HII_HANDLE Handle,
    IN EFI_HII_DATABASE_NOTIFY_TYPE NotifyType
);```

Parameters

**PackageType**
Package type of the notification.
PackageGuid
If PackageType is EFI_HII_PACKAGE_TYPE_GUID, then this is the pointer to the GUID from the Guid field of EFI_HII_GUID_PACKAGE_HDR. Otherwise, it must be NULL.

Package
Points to the package referred to by the notification

Handle
The handle of the package list which contains the specified package.

NotifyType
The type of change concerning the database. See EFI_HII_DATABASE_NOTIFY_TYPE.

Description
Functions which are registered to receive notification of database events have this prototype. The actual event is encoded in NotifyType. The following table describes how PackageType, PackageGuid, Handle, and Package are used for each of the notification types.

<table>
<thead>
<tr>
<th>Notification Type</th>
<th>Parameter Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>NEW_PACK</td>
<td>PackageType and PackageGuid are the type of the new package. Package points to the new package. Handle is the handle of the package list which is being added to the database.</td>
</tr>
<tr>
<td>REMOVE_PACK</td>
<td>PackageType and PackageGuid are the type of the package which is being removed. Package points to the package being removed. Handle is the package list from which the package is being removed.</td>
</tr>
<tr>
<td>EXPORT_PACK</td>
<td>PackageType and PackageGuid are the type of the package being exported. Package points to the existing package in the database. Handle is the package list being exported.</td>
</tr>
<tr>
<td>ADD_PACK</td>
<td>PackageType and PackageGuid are the type of the package being added. Package points to the package being added. Handle is the package list to which the package is being added.</td>
</tr>
</tbody>
</table>

34.8.14 EFI_HII_DATABASE_NOTIFY_TYPE

typedef UINTN EFI_HII_DATABASE_NOTIFY_TYPE;

#define EFI_HII_DATABASE_NOTIFY_NEW_PACK 0x00000001
#define EFI_HII_DATABASE_NOTIFY_REMOVE_PACK 0x00000002
#define EFI_HII_DATABASE_NOTIFY_EXPORT_PACK 0x00000004
#define EFI_HII_DATABASE_NOTIFY_ADD_PACK 0x00000008
CHAPTER
THIRTYFIVE

HII CONFIGURATION PROCESSING AND BROWSER PROTOCOL

35.1 Introduction

This section describes the data and APIs used to manage the system’s configuration: the actual data that describes the knobs and settings.

35.1.1 Common Configuration Data Format

The configuration data is stored as name / value string pairs. As in e.g. HTML, the name and value are separated by ‘=’ and the pairs are separated one from the next by ‘&’. The configuration data structures are thus variable length UNICODE (UCS-2) strings.

Certain names and values have limitations on their syntax to manage routing and to enable extended support for common storage mechanisms.

35.1.2 Data Flow

There is a two-way flow through the hierarchy of drivers and protocols that parallels the flow in other parts of HII. Initially, the flow is from the drivers up to the HII database and on to configuration applications. When changes to configuration are accepted, the flow reverses itself, going from the configuration applications through the HII database protocols back to the drivers through separate protocols.

The flow from driver up consists of the current and alternative (default) configurations. The flow down from the configuration applications consists of changed configurations.

The protocol managed by the HII Database is known as the EFI HII Configuration Routing Protocol, while the one presented by the drivers themselves is known as the EFI HII Configuration Access Protocol. The HII Configuration Routing Protocol is the only one that outside callers should invoke.

35.2 Configuration Strings

The configuration strings follow the same general format as HTTP argument strings, which is to say ‘&’ separated name / value pairs. The name and value are separated by ‘=’. The strings are a subset of full HTML argument strings and do not require quoting, the ‘%’ character sequences used to insert spaces, ampersands, equal signs, and the like into HTTP argument strings.
## 35.2.1 String Syntax

Assumptions are typical for BNF with the following extensions

Characters in single quotes, e.g. ‘a’, indicate terminals.

Square brackets immediately followed by a number n indicate that the contents are to be repeated n times, so [‘a’]4 would be “aaaa”.

An italicized non-terminal, e.g. `<AllPrintableASCIICharacters>` is used to indicate a set of terminals whose definition is outside the scope of this document.

The syntax for configuration strings is as follows.

### 35.2.1.1 Basic forms

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>&lt;Dec19&gt;</code></td>
<td>‘1’</td>
</tr>
<tr>
<td><code>&lt;DecCh&gt;</code></td>
<td>‘0’</td>
</tr>
<tr>
<td><code>&lt;HexAf&gt;</code></td>
<td>‘a’</td>
</tr>
<tr>
<td><code>&lt;Hex1f&gt;</code></td>
<td><code>&lt;Dec19&gt;</code></td>
</tr>
<tr>
<td><code>&lt;HexCh&gt;</code></td>
<td><code>&lt;DecCh&gt;</code></td>
</tr>
<tr>
<td><code>&lt;Number&gt;</code></td>
<td><code>&lt;HexCh&gt;</code>+</td>
</tr>
<tr>
<td><code>&lt;Alpha&gt;</code></td>
<td>‘a’</td>
</tr>
</tbody>
</table>

### 35.2.1.2 Types

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>&lt;Guid&gt;</code></td>
<td><code>&lt;HexCh&gt;</code>32</td>
</tr>
<tr>
<td><code>&lt;LabelStart&gt;</code></td>
<td><code>&lt;Alpha&gt;</code></td>
</tr>
<tr>
<td><code>&lt;LabelBody&gt;</code></td>
<td><code>&lt;LabelStart&gt;</code></td>
</tr>
<tr>
<td><code>&lt;Label&gt;</code></td>
<td><code>&lt;LabelStart&gt;</code></td>
</tr>
<tr>
<td><code>&lt;Char&gt;</code></td>
<td><code>&lt;HexCh&gt;</code>4</td>
</tr>
<tr>
<td><code>&lt;String&gt;</code></td>
<td><code>[&lt;Char&gt;]</code>+</td>
</tr>
<tr>
<td><code>&lt;AltCfgId&gt;</code></td>
<td><code>&lt;HexCh&gt;</code>4</td>
</tr>
</tbody>
</table>

### 35.2.1.3 Routing elements

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>&lt;GuidHdr&gt;</code></td>
<td>‘GUID=’&lt;Guid&gt;</td>
</tr>
<tr>
<td><code>&lt;NameHdr&gt;</code></td>
<td>‘NAME=’&lt;String&gt;</td>
</tr>
<tr>
<td><code>&lt;PathHdr&gt;</code></td>
<td>‘PATH=’&lt;UEFI binary Device Path represented as hex number&gt;</td>
</tr>
<tr>
<td><code>&lt;DescHdr&gt;</code></td>
<td>‘ALTCFG=’&lt;AltCfgId&gt;</td>
</tr>
<tr>
<td><code>&lt;ConfigHdr&gt;</code></td>
<td>`&lt;GuidHdr&gt;’&amp;’&lt;NameHdr&gt;’&amp;’&lt;PathHdr&gt;</td>
</tr>
<tr>
<td><code>&lt;AltConfigHdr&gt;</code></td>
<td>`&lt;ConfigHdr&gt; ‘&amp;’&lt;DescHdr&gt;</td>
</tr>
</tbody>
</table>
35.2.1.4 Body elements

<ConfigBody> ::= <ConfigElement>*
<ConfigElement> ::= '&'<BlockConfig> | '&'<NvConfig>
<BlockName> ::= 'OFFSET='<Number>'&WIDTH='<Number>
<BlockConfig> ::= <BlockName>'&VALUE='<Number>
<RequestElement> ::= '&'<BlockName> | '&'<Label>
<NvConfig> ::= <Label>'='<String> | <Label>'='<Number>

35.2.1.5 Configuration strings

<ConfigRequest> ::= <ConfigHdr><RequestElement>*
<MultiConfigRequest> ::= <ConfigRequest>[('&' <ConfigRequest>)*
<ConfigResp> ::= <ConfigHdr><ConfigBody>
<AltResp> ::= <AltConfigHdr><ConfigBody>
<ConfigAltResp> ::= <ConfigResp>[('&' <AltResp>)*
<MultiConfigAltResp> ::= <ConfigAltResp>[('&' <ConfigAltResp>)*
<MultiConfigResp> ::= <ConfigResp>[('&'<ConfigResp>)*

Notes:
The <Number> represents a data buffer and is encoded as a sequence of bytes in the format %02x in the same order as
the buffer bytes reside in memory.
The <Guid> represents a hex encoding of GUID and is encoded as a sequence of bytes in the format %02x in the same
order as the GUID bytes reside in memory.
The syntax for a <Label> is the C label (e.g. Variable) syntax.
The <ConfigHdr> provides routing information. The name field is required even if non-block storage is targeted. In
these cases, it may be used as a way to distinguish like storages from one another when a driver is being used.
The <BlockName> provides addressing information for managing block (e.g. UEFI Variable) storage. The first number
provides the byte offset into the block while the second provides the length of bytes.
The <PathHdr> presents a hex encoding of a UEFI device path. This is not the printable path since the printable path
is optional in UEFI and to enable simpler comparisons. The data is encoded as strings with the format %02x bytes in
the same order as the device path resides in RAM memory.
The <ConfigRequest> provides a mechanism to request the current configuration for one or more elements.
The <AltCfgId> is the identifier of a configuration declared in the corresponding IFR.
The name ‘GUID’ is also used to separate <String> or <ConfigRequest> elements in the equivalent Multi version.
That is:

"GUID=...&NAME=...&fred=12&GUID=...&NAME=...&...&goyle=11"

Indicates two <String>, with one ending with fred=12.
The following are reserved <name> s and cannot be used as names in a <ConfigElement>:

GUID
NAME
PATH
ALT_CFG
OFFSET

(continues on next page)
35.2.1.6 Keyword strings

<table>
<thead>
<tr>
<th>Element</th>
<th>Expression</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>&lt;NameSpaceId&gt;</code></td>
<td>::= 'NAMESPACE=' <code>&lt;String&gt;</code> '&amp;'</td>
</tr>
<tr>
<td><code>&lt;Keyword&gt;</code></td>
<td>::= 'KEYWORD=' <code>&lt;String&gt;</code> [':' '&lt;DecCh&gt;(1/4)']</td>
</tr>
<tr>
<td><code>&lt;DataFilter&gt;</code></td>
<td>::= 'Buffer'</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td><code>&lt;UsageFilter&gt;</code></td>
<td>::= 'ReadOnly'</td>
</tr>
<tr>
<td><code>&lt;Filter&gt;</code></td>
<td>::= <code>&lt;UsageFilter&gt;</code></td>
</tr>
<tr>
<td><code>&lt;ValueRange&gt;</code></td>
<td>::= '&amp;MAX=' '&lt;Number&gt;' &amp; Min=' '&lt;Number&gt;' [ 'STEP=' '&lt;Number&gt;' ]</td>
</tr>
<tr>
<td><code>&lt;ValueOption&gt;</code></td>
<td>::= '&amp;OPTIONVALUE=' '&lt;Number&gt;' &amp; OPTIONSTRING=' '&lt;String&gt;' ['&amp;VALUETYPE=' 'Numeric'</td>
</tr>
<tr>
<td><code>&lt;ValueAttribute&gt;</code></td>
<td>::= ['&amp;OPTIONVALUE=' '&lt;Number&gt;' ] [ 'valueAttribut=' 'Numeric'</td>
</tr>
<tr>
<td><code>&lt;Default&gt;</code></td>
<td>::= ['&amp;STANDARDDEFAULT=' '&lt;Number&gt;' ] [ 'MFGDEFAULT=' '&lt;Number&gt;' ] [ 'SAFEDEFAULT=' '&lt;Number&gt;' ]</td>
</tr>
<tr>
<td><code>&lt;Display&gt;</code></td>
<td>::= '&amp;DISPLAYNAME=' '&lt;String&gt;'</td>
</tr>
<tr>
<td><code>&lt;DataType&gt;</code></td>
<td>::= '&amp;DATATYPE=' `&lt;DataFilter&gt;'</td>
</tr>
<tr>
<td><code>&lt;KeywordInfoFilter&gt;</code></td>
<td>::= 'All'</td>
</tr>
<tr>
<td><code>&lt;Boolean&gt;</code></td>
<td>::= 'True'</td>
</tr>
<tr>
<td><code>&lt;KeywordInfoRequest&gt;</code></td>
<td>::= 'KEYWORDINFO=' '&lt;KeywordInfoFilter&gt;'</td>
</tr>
<tr>
<td><code>&lt;KeywordInfoResp&gt;</code></td>
<td>::= ['&lt;DataType&gt;</td>
</tr>
<tr>
<td><code>&lt;KeywordRequest&gt;</code></td>
<td>::= ['&lt;PathHdr&gt;' '&amp;'</td>
</tr>
<tr>
<td><code>&lt;KeywordResp&gt;</code></td>
<td>::= ['&lt;NameSpaceId&gt;</td>
</tr>
<tr>
<td><code>&lt;MultiKeywordRequest&gt;</code></td>
<td>::= ['&lt;KeywordRequest&gt;'] ['&amp;'&lt;KeywordRequest&gt;] *</td>
</tr>
<tr>
<td><code>&lt;MultiKeywordResp&gt;</code></td>
<td>::= ['&lt;KeywordResp&gt;'] ['&amp;'&lt;KeywordResp&gt;] *</td>
</tr>
</tbody>
</table>

**NOTE:** For Keyword definitions, see the UEFI Configuration Namespace Registry document on [http://uefi.org/uefi](http://uefi.org/uefi).

The `<NameSpaceId>` element is equivalent to the platform configuration language being used for the keyword definition*.

The `<Keyword>` element uses the ‘KEYWORD’ name to designate that immediately following the reserved name is a string value associated with a configuration namespace keyword as defined in the Configuration NameSpace Registry document ([http://uefi.org/uefi](http://uefi.org/uefi)).
Typically, when a Keyword is defined, the value is a solitary string such as “BIOSVendor”. However, when certain Keywords are intended to represent a setting that may have multiple instances (e.g. ChipsetSATAPortEnable), that is when a “:<DecCh>(1/4)” suffix will be appended to the keyword definition. In that case, we might see something like: “ChipsetSATAPortEnable:5” if a particular platform had at least five SATA ports and one of the questions was represented by the aforementioned string. It would also be reasonable to expect that there might also be a “ChipsetSATAPortEnable:1” and a “:2”, “:3” etc.

If the `<PathHdr>` element within `<KeywordRequest>` is omitted, then all instances are returned.

If the Keyboard Handler protocol knows or detects that a particular Keyword is read-only, then the `<KeywordResp>` must include the “&READONLY” tag.

The `<DataFilter>` element specifies the optional filter based on data type to use when a request is made. If no filtering is desired, then this element must be omitted from the `<KeywordRequest>`. Filtering is not guaranteed to work on any platform configuration language that isn’t defined in the UEFI Configuration Namespace Document.

**DataFilter.Buffer**

HII questions with `EFI_IFR_TYPE_BUFFER` type are treated as this type. This is most commonly represented in ‘C’ as a VOID type, or as a more complex type. Other than the `EFI_IFR_TYPE_BOOLEAN` and `EFI_IFR_TYPE_NUM_x` data types, all of the HII configuration data types are treated as a sequence of data.

**DataFilter.Numeric**

A sequence of data that must be interpreted as a one, two, four, or eight-byte wide numeric value. For instance, a definition of “Numeric:2” would indicate that the keyword is a two-byte numeric value. If no byte-size designation is specified, then the value may vary in size.

**DataFilter.String**

HII questions with `EFI_IFR_TYPE_STRING` type are treated as this type.

**DataFilter.Boolean**

HII questions with `EFI_IFR_TYPE_BOOLEAN` type are treated as this type.

**DataFilter.Date**

HII questions with `EFI_IFR_TYPE_DATE` type are treated as this type.

**DataFilter.Time**

HII questions with `EFI_IFR_TYPE_TIME` type are treated as this type.

The `<UsageFilter>` element defines the optional filter to use based on usage type when a request is made. If no filtering is desired, then this element must be omitted from the `<KeywordRequest>`.

**UsageType.ReadOnly**

The data for the keyword cannot be changed. It is intended solely for informational purposes, and can be used to read a setting that may be static or dynamic (e.g. CPU temperature).

**UsageType.ReadWrite**

The data for the keyword can be changed.

The `<KeywordInfoRequest>` element allows the callers to request some additional information of the keyword to be returned. `<KeywordInfoRequest>` element is used when user doesn’t know the information about the keyword and wants to get more information about this keyword. When `<KeywordInfoRequest>` element is specified with `<KeywordRequest>`, the `<KeywordInfoResp>` element will be specified with `<KeywordResp>` to return the info requested by `<KeywordInfoRequest>`.

The `<KeywordInfoFilter>` element is used to specify the additional information that caller wants to know about the keyword. Caller can specify any type of additional information he/she wants to know. When ‘All’ is specified, means all the supported information need to be returned.
The `<DataType>` element specifies the data type of a keyword, can refer to `<DataFilter>` for the detailed info the data types.

The `<ValueAttribute>` element specifies the value attribute of a keyword. Such as the value range of a keyword or the selectable values for a keyword.

`<ValueRange>` element specifies the variation range of a keyword value. Such as it can be specified for a keyword used in `EFI_IFR_NUMERIC_OP`, `EFI_IFR_STRING_OP` opcode. For `EFI_IFR_NUMERIC_OP` opcode, it specifies the maximum value, minimum value and increment or decrement step. For `EFI_IFR_STRING_OP` opcode, it specifies the maximum length and minimum length of the string can be input.

`<ValueOption>` element specifies all the (selectable) values and related string representation of these values for a keyword. Such as it can be specified for keyword used in `EFI_IFR_ONE_OF_OP`, `EFI_IFR_ORDERED_LIST_OP` opcode. For `EFI_IFR_ONE_OF_OP`, it specifies the all selectable values and the string representation of the values. The keyword value can be one of them.

For `EFI_IFR_ORDERED_LIST_OP`, it specifies all values and the string representation of the values. The keyword value can be the permutation and combination of these values. And for `EFI_IFR_ORDERED_LIST_OP`, its data type is Buffer, so can return the value type in a `<ValueOption>` to indicate the data stored in the Buffer is numeric as a one, two, four, or eight-byte wide.

The `<Default>` element specifies the default value of a keyword. Only the three standard defaults stores are supported including the standard defaults, the manufacturing defaults and the Safe defaults. If the keyword doesn’t have any type of defaults, then there is no default info returned. And if the keyword only has the standard default, then only the standard default information will be returned.

The `<Display>` element specifies the displayed prompt string of this keyword in the UI page.

### 35.2.1.6.1 An example of some basic keyword-related strings:

`<KeywordRequest>` to retrieve the current BIOS Vendor name:

``` xml
KEYWORD=BIOSVendor
```

### 35.2.1.6.2 A possible response might look like:

```
x-UEFI-ns&KEYWORD=BIOSVendor&VALUE=AcmeBIOSCompany
```

If a request was made to retrieve all of the settings for a platform, a user would initiate a call to `KeywordHandleràGet-Data()` with the `KeywordString` and `NamespaceId` being `NULL`.

### 35.2.1.6.3 A possible response might look like:

```
x-UEFI-ns&KEYWORD=BIOSVendor&VALUE=AcmeBIOSCompany&x-UEFI-extension
ACME&KEYWORD=SpecialSettingX&VALUE=3
```

In this case, the string returned tells us that there was one discovered keyword called “BIOSVendor” under the standard UEFI namespace and its value was “AcmeBIOS”. There was also an ACME branded namespace element which was discovered that had a keyword called “SpecialSettingX” whose value was 3.
35.2.1.6.4 An example to get more information of a keyword:

```
KEYWORD=BIOSVendor&KEYWORDINFO=All
```

A possible response might look like:

```
x-UEFI-ns&KEYWORD=BIOSVendor&VALUE=AcmeBIOSCompany&DataType=String&MAX=30&MIN=6&STANDARDDEFAULT=AcmeBIOSCompany&MFGDEFAULT=AcmeBIOSCompany
```

35.2.2 String Types

There are six string types. As can be seen from the BNF, the syntax of all is quite similar. The first three are used in communications between drivers and HII. The last three are used for analogous communication between external applications and HII.

- `<ConfigRequest>`: This string is used by HII to request the current and any alternative configurations from a driver. It consists of routing information and only ampersand separated names.
- `<ConfigAltResp>`: A string in this format is returned by the driver in response to a request to fill in a `<ConfigRequest>` string. The string consists of the current configuration followed by possibly several alternative configurations. The alternative configurations have the `ALTCFG` name / value pair in addition to the usual `GUID`, `NAME`, and `PATH` entries in the routing prefix. The `ALTCFG` value is a Default ID which is used to describe the alternative default configuration.
- `<ConfigResp>`: A string in this format is handed by the HII to the driver to cause the driver to change its configuration. It consists of routing information and name / value pairs which correspond to the questions in the driver’s IFR. Only `<ConfigResp>` strings which refer to a driver in question may be handed to that driver. The driver shall reject all others.
- `<MultiConfigRequest>`: A string in this format is handed to HII by an external application in order to request the current and alternate configurations of the system’s drivers. The format of this string is a series of `<ConfigRequest>` strings separated by ampersands. The HII’s job is to separate the requests and hand them off to the appropriate drivers (as indicated by the routing headers).
- `<MultiConfigAltResp>`: A string in this format is handed back to an external application which has requested the current and alternate configurations of the system’s drivers. The format of this string is a series of `<ConfigAltResp>` strings separated by ampersands. The HII creates this string by concatenating the current and alternate configuration strings provided by each driver.
- `<MultiConfigResp>`: A string in this format is handed to the HII in order to update the system’s configuration. Analogous to the other “Multi” string formats, its syntax is a series of ampersand separated `<ConfigResp>` strings. Upon receipt, the HII routes the `<ConfigResp>` strings to the corresponding drivers.

35.3 EFI Configuration Keyword Handler Protocol

This section provides a detailed description of the EFI Configuration Keyword Handler Protocol.
### 35.3.1 EFI_CONFIG_KEYWORD_HANDLER_PROTOCOL

**Summary**

The `EFI_CONFIG_KEYWORD_HANDLER_PROTOCOL` provides the mechanism to set and get the values associated with a keyword exposed through a x-UEFI- prefixed configuration language namespace.

**GUID**

```c
#define EFI_CONFIG_KEYWORD_HANDLER_PROTOCOL_GUID \
{ 0x0a8badd5, 0x03b8, 0x4d19,\ 
  {0xb1, 0x28, 0x7b, 0x8f, 0x0e, 0xda, 0xa5, 0x96 }}
```

**Protocol Interface Structure**

```c
typedef struct _ EFI_CONFIG_KEYWORD_HANDLER_PROTOCOL {
  EFI_CONFIG_KEYWORD_HANDLER_SET_DATA SetData;
  EFI_CONFIG_KEYWORD_HANDLER_GET_DATA GetData;
} EFI_CONFIG_KEYWORD_HANDLER_PROTOCOL;
```

**Parameters**

- **SetData**
  
  Set the data associated with a particular configuration namespace keyword.

- **GetData**
  
  Get the data associated with a particular configuration namespace keyword.

**Description**

The `EFI_CONFIG_KEYWORD_HANDLER_PROTOCOL` allows other components in the platform (e.g. Browser, Manageability Software, etc.) to retrieve and set configuration settings within the system.

Keywords are text elements which are associated with a particular configuration option within the platform. These keywords are intended to add semantic meaning to the configuration option they are attached to. The text associated for the keyword would be encoded in a UEFI configuration language. These languages are like French or German or Japanese, but are not designed for display purposes for an end-user. Instead each language serves as a namespace for the purposes of grouping and manipulating groups of platform configurations options. See [Working with a UEFI Configuration Language](#) for more information.

**NOTE:** Not all configuration options will be associated with a keyword. Associating a keyword with a configuration option is at the discretion of the platform and/or the hardware vendor. For more information about keyword definitions associated with a UEFI namespace, see the UEFI Keyword Namespace Registry link in the UEFI Link Document.

### 35.3.2 EFI_KEYWORD_HANDLER_PROTOCOL.SetData()

**Summary**

Set the data associated with a particular configuration namespace keyword.

**Prototype**

```c
typedef EFI_STATUS
(EFIAPI *EFI_KEYWORD_HANDLER _SET_DATA) (\n  IN EFI_KEYWORD_HANDLER_PROTOCOL *This,\n  IN CONST EFI_STRING KeywordString,\n  OUT EFI_STRING *Progress,\n  ...)
```

(continues on next page)
OUT UINT32 *ProgressErr

Parameters

This

Pointer to the EFI_KEYWORD_HANDLER_PROTOCOL instance.

KeywordString

A null-terminated string in <MultiKeywordResp> format.

Progress

On return, points to a character in the KeywordString. Points to the string’s NULL terminator if the request was successful. Points to the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) if the request was not successful.

ProgressErr

If during the processing of the KeywordString there was a failure, this parameter gives additional information about the possible source of the problem. The various errors are defined in “Related Definitions” below.

Description

This function accepts a <MultiKeywordResp> formatted string, finds the associated keyword owners, creates a <MultiConfigResp> string from it and forwards it to the EFI_HII_ROUTING_PROTOCOL.RouteConfig function.

If there is an issue in resolving the contents of the KeywordString, then the function returns an error and also sets the Progress and ProgressErr with the appropriate information about where the issue occurred and additional data about the nature of the issue.

In the case when KeywordString containing multiple keywords, when an EFI_NOT_FOUND error is generated during processing these second or later keyword element, the system storage associated with earlier keywords is not modified. All elements of the KeywordString must successfully pass all tests for format and access prior to making any modifications to storage.

In the case when EFI_DEVICE_ERROR is returned from the processing of a KeywordString containing multiple keywords, the state of storage associated with earlier keywords is undefined.

Related Definitions

//***************************************************************
// Progress Errors
//***************************************************************
#define KEYWORD_HANDLER_NO_ERROR 0x00000000
#define KEYWORD_HANDLER_NAMESPACE_ID_NOT_FOUND 0x00000001
#define KEYWORD_HANDLER_MALFORMED_STRING 0x00000002
#define KEYWORD_HANDLER_KEYWORD_NOT_FOUND 0x00000004
#define KEYWORD_HANDLER_INCOMPATIBLE_VALUE_DETECTED 0x00000008
#define KEYWORD_HANDLER_ACCESS_NOT_PERMITTED 0x00000010
#define KEYWORD_HANDLER_UNDEFINED_PROCESSING_ERROR 0x80000000

The KEYWORD_HANDLER_x values describe the error values returned in the ProgressErr field.

If no errors were encountered, then KEYWORD_HANDLER_NO_ERROR is returned with no bits are set.

If the <NameSpaceId> specified by the KeywordString was not found in any of the registered configuration data, the KEYWORD_HANDLER_NAMESPACE_ID_NOT_FOUND bit is set.

If there was an error in the parsing of the KeywordString, the KEYWORD_HANDLER_MALFORMED_STRING bit is set.

35.3. EFI Configuration Keyword Handler Protocol
If there was a keyword specified in the KeywordString which was not found in any of the registered configuration data, \textit{KEYWORD_HANDLER\_KEYWORD\_NOT\_FOUND} bit is set.

If the value either passed into \textit{KeywordString} (during a SetData operation) or the value discovered for the Keyword (during a GetData operation) did not match what was known to be valid for the defined keyword, the \textit{KEYWORD\_HANDLER\_INCOMPATIBLE\_VALUE\_DETECTED} bit is set.

If there was an error as a result of a violation of system policy. For example trying to write a read-only element, the \textit{KEYWORD\_HANDLER\_ACCESS\_NOT\_PERMITTED} bit is set.

If there was an undefined type of error in processing the passed in data, the \textit{KEYWORD\_HANDLER\_UNDEFINED\_PROCESSING\_ERROR} bit is set.

\textbf{Status Codes Returned}

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The specified action was completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are \textbf{TRUE}: KeywordString is NULL. Parsing of the KeywordString resulted in an error. See Progress and ProgressErr for more data.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>An element of the KeywordString was not found. See ProgressErr for more data.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated. See ProgressErr for more data.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The action violated system policy. See ProgressErr for more data.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system error occurred. See ProgressErr for more data.</td>
</tr>
</tbody>
</table>

\textbf{35.3.3 EFI\_KEYWORD\_HANDLER\_PROTOCOL\_GetData()}

\textbf{Summary}

Get the data associated with a particular configuration namespace keyword.

\textbf{Prototype}

```c
typedef EFI\_STATUS (EFIAPI *EFI\_KEYWORD\_HANDLER\_GET\_DATA) ( IN EFI\_KEYWORD\_HANDLER\_PROTOCOL *This,
            IN CONST EFI\_STRING NameSpaceId, OPTIONAL
            IN CONST EFI\_STRING KeywordString, OPTIONAL
            OUT EFI\_STRING *Progress,
            OUT UINT32 *ProgressErr,
            OUT EFI\_STRING *Results
        );
```

\textbf{Parameters}

\textbf{This}

Pointer to the \textit{EFI\_KEYWORD\_HANDLER\_PROTOCOL} instance.

\textbf{NameSpaceId}

A null-terminated string containing the platform configuration language to search through in the system. If a NULL is passed in, then it is assumed that any platform configuration language with the prefix of “x-UEFI-” are searched.
**KeywordString**

A null-terminated string in `<MultiKeywordRequest>` format. If a NULL is passed in the `KeywordString` field, all of the known keywords in the system for the `NameSpaceId` specified are returned in the `Results` field.

**Progress**

On return, points to a character in the `KeywordString`. Points to the string’s NULL terminator if the request was successful. Points to the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) if the request was not successful.

**ProgressErr**

If during the processing of the `KeywordString` there was a failure, this parameter gives additional information about the possible source of the problem. See the definitions in `SetData()` for valid value definitions.

**Results**

A null-terminated string in `<MultiKeywordResp>` format is returned which has all the values filled in for the keywords in the `KeywordString`. This is a callee-allocated field, and must be freed by the caller after being used.

**Description**

This function accepts a `<MultiKeywordRequest>` formatted string, finds the underlying keyword owners, creates a `<MultiConfigRequest>` string from it and forwards it to the `EFI_HII_ROUTING_PROTOCOL.ExtractConfig` function.

If there is an issue in resolving the contents of the `KeywordString`, then the function returns an `EFI_INVALID_PARAMETER` and also set the `Progress` and `ProgressErr` with the appropriate information about where the issue occurred and additional data about the nature of the issue.

In the case when `KeywordString` is `NULL`, or contains multiple keywords, or when `EFI_NOT_FOUND` is generated while processing the keyword elements, the `Results` string contains values returned for all keywords processed prior to the keyword generating the error but no values for the keyword with error or any following keywords.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The specified action was completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One or more of the following are TRUE: <code>Progress</code>, <code>ProgressErr</code>, or <code>Results</code> is <code>NULL</code>. Parsing of the <code>KeywordString</code> resulted in an error. See <code>Progress</code> and <code>ProgressErr</code> for more data.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>An element of the <code>KeywordString</code> was not found. See <code>ProgressErr</code> for more data.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The <code>NameSpaceId</code> specified was not found. See <code>ProgressErr</code> for more data.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required system resources could not be allocated. See <code>ProgressErr</code> for more data.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The action violated system policy. See <code>ProgressErr</code> for more data.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An unexpected system error occurred. See <code>ProgressErr</code> for more data.</td>
</tr>
</tbody>
</table>

### 35.4 EFI HII Configuration Routing Protocol

#### 35.4.1 EFI_HII_CONFIG_ROUTING_PROTOCOL

**Summary**

The EFI HII Configuration Routing Protocol manages the movement of configuration data from drivers to configuration applications. It then serves as the single point to receive configuration information from configuration applications, routing the results to the appropriate drivers.

**GUID**
Protocol Interface Structure

typedef struct {
    EFI_HII_EXTRACT_CONFIG ExtractConfig;
    EFI_HII_EXPORT_CONFIG ExportConfig
    EFI_HII_ROUTE_CONFIG RouteConfig;
    EFI_HII_BLOCK_TO_CONFIG BlockToConfig;
    EFI_HII_CONFIG_TO_BLOCK ConfigToBlock;
    EFI_HII_GET_ALT_CFG GetAltConfig;
} EFI_HII_CONFIG_ROUTING_PROTOCOL;

Related Definitions
None

Parameters

Description
This protocol defines the configuration routing interfaces between external applications and the HII.

There may only be one instance of this protocol in the system.

35.4.2 EFI_HII_CONFIG_ROUTING_PROTOCOL.ExtractConfig()

Summary
This function allows a caller to extract the current configuration for one or more named elements from one or more drivers.

Prototype

typedef

EFI_STATUS

(EFIAPI * EFI_HII_EXTRACT_CONFIG ) ( 
    IN CONST EFI_HII_CONFIG_ROUTING_PROTOCOL *This, 
    IN CONST EFI_STRING Request, 
    OUT EFI_STRING *Progress, 
    OUT EFI_STRING *Results 
); 

Parameters

This
Points to the EFI_HII_CONFIG_ROUTING_PROTOCOL instance.

Request
A null-terminated string in <MultiConfigRequest> format.

Progress
On return, points to a character in the Request string. Points to the string’s null terminator if request was successful. Points to the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) if the request was not successful.
Results

A null-terminated string in `<MultiConfigAltResp>` format which has all values filled in for the names in the Request string.

Description

This function allows the caller to request the current configuration for one or more named elements from one or more drivers. The resulting string is in the standard HII configuration string format. If Successful Results contains an equivalent string with “=” and the values associated with all names added in.

The expected implementation is for each `<ConfigRequest>` substring in the Request, call the HII Configuration Access Protocol `ExtractConfig` function for the driver corresponding to the `<ConfigHdr>` at the start of the `<ConfigRequest>` substring. The request fails if no driver matches the `<ConfigRequest>` substring.

**NOTE:** Alternative configuration strings may also be appended to the end of the current configuration string. If they are, they must appear after the current configuration. They must contain the same routing (GUID, NAME, PATH) as the current configuration string. They must have an additional description indicating the type of alternative configuration the string represents, “ALTCFG=AltCfgId”. The `<AltCfgId>` is a reference to a Default ID which stipulates the type of Default being referenced such as EFI_HII_DEFAULT_CLASS_STANDARD.

As an example, assume that the Request string is:

```
GUID=...&PATH=...&Fred&George&Ron&Neville
```

A result might be:

```
GUID=...&PATH=...&Fred=16&George=16&Ron=12&Neville=11&
GUID=...&PATH=...&ALTCFG=0037&Fred=12&Neville=7
```

**NOTE:** For the output Results, the value filled in the names in the Request string with `<MultiConfigAltResp>` format may change when called multiple times due to some data being of a dynamic nature.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Results string is filled with the values corresponding to all requested names.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Not enough memory to store the parts of the results that must be stored awaiting possible future protocols.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Routing data doesn’t match any known driver. Progress set to the “G” in “GUID” of the routing header that doesn’t match. Note: There is no requirement that all routing data be validated before any configuration extraction.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Illegal syntax. Progress set to most recent “&amp;” before the error or the beginning of the string.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>The ExtractConfig function of the underlying HII Configuration Access Protocol returned EFI_INVALID_PARAMETER. Progress set to most recent “&amp;” before the error or the beginning of the string.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The action violated a system policy.</td>
</tr>
</tbody>
</table>
35.4.3 EFI_HII_CONFIG_ROUTING_PROTOCOL.ExportConfig()

Summary
This function allows the caller to request the current configuration for the entirety of the current HII database and returns the data in a null-terminated string.

Prototype

```c
typedef EFI_STATUS (EFIAPI * EFI_HII_EXPORT_CONFIG) (IN CONST EFI_HII_CONFIG_ROUTING_PROTOCOL *This, 
OUT EFI_STRING *Results);
```

Parameters

This
Points to the EFI_HII_CONFIG_ROUTING_PROTOCOL instance.

Results
A null-terminated string in <MultiConfigAltResp> format which has all values filled in for the entirety of the current HII database.

Description
This function allows the caller to request the current configuration for all of the current HII database. The results include both the current and alternate configurations as described in ExtractConfig() above.

EFI_HII_CONFIG_ACCESS_PROTOCOL.ExtractConfig() interfaces below.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The Results string is filled with the values corresponding to all requested names.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Not enough memory to store the parts of the results that must be stored awaiting possible future protocols.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>For example, passing in a NULL for the Results parameter would result in this type of error.</td>
</tr>
</tbody>
</table>

35.4.4 EFI_HII_CONFIG_ROUTING_PROTOCOL.RouteConfig()

Summary
This function processes the results of processing forms and routes it to the appropriate handlers or storage.

Prototype

```c
typedef EFI_STATUS (EFIAPI * EFI_HII_ROUTE_CONFIG) (IN CONST EFI_HII_CONFIG_ROUTING_PROTOCOL *This, 
IN CONST EFI_STRING Configuration, 
OUT EFI_STRING *Progress);
```

Parameters

35.4. EFI HII Configuration Routing Protocol
This
Points to the EFI_HII_CONFIG_ROUTING_PROTOCOL instance.

Configuration
A null-terminated string in <MultiConfigResp> format.

Progress
A pointer to a string filled in with the offset of the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) or the terminating NULL if all was successful.

Description
This function routes the results of processing forms to the appropriate targets. It scans for <ConfigHdr> within the string and passes the header and subsequent body to the driver whose location is described in the <ConfigHdr>. Many <ConfigHdr> s may appear as a single request.

The expected implementation is to hand off the various <ConfigResp> substrings to the Configuration Access Protocol RouteConfig routine corresponding to the driver whose routing information is defined by the <ConfigHdr> in turn.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The results have been distributed or are awaiting distribution.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Not enough memory to store the parts of the results that must be stored awaiting possible future protocols.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETERS</td>
<td>Passing in a NULL for the Configuration parameter would result in this type of error.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Target for the specified routing data was not found</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The action violated a system policy.</td>
</tr>
</tbody>
</table>

35.4.5 EFI_HII_CONFIG_ROUTING_PROTOCOL.BlockToConfig()

Summary
This helper function is to be called by drivers to map configuration data stored in byte array (“block”) formats such as UEFI Variables into current configuration strings.

Prototype

typedef
EFI_STATUS
(EIFIAPI * EFI_HII_BLOCK_TO_CONFIG ) ( |
    IN CONST EFI_HII_CONFIG_ROUTING_PROTOCOL *This, |
    IN CONST EFI_STRING ConfigRequest, |
    IN CONST UINT8 *Block, |
    IN CONST UINTN BlockSize, |
    OUT EFI_STRING *Config, |
    OUT EFI_STRING *Progress |
    );

Parameters
This
Points to the EFI_HII_CONFIG_ROUTING_PROTOCOL instance.

ConfigRequest
A null-terminated string in <ConfigRequest> format.
Block
Array of bytes defining the block’s configuration.

BlockSize
Length in bytes of Block.

Config
Filled-in configuration string. String allocated by the function. Returned only if call is successful. The null-terminated string will be in <ConfigResp> format.

Progress
A pointer to a string filled in with the offset of the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) or the terminating NULL if all was successful.

Description
This function extracts the current configuration from a block of bytes. To do so, it requires that the ConfigRequest string consists of a list of <BlockName> formatted names. It uses the offset in the name to determine the index into the Block to start the extraction and the width of each name to determine the number of bytes to extract. These are mapped to a string using the equivalent of the C “%x” format (with optional leading spaces).

The call fails if, for any (offset, width) pair in ConfigRequest, offset+value >= BlockSize.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The request succeeded. Progress points to the null terminator at the end of ConfigRequest.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Not enough memory to allocate Config. Progress points to the first character of ConfigRequest.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETERS</td>
<td>Passing in a NULL for the ConfigRequest or Block parameter would result in this type of error. Progress points to the first character of ConfigRequest.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Target for the specified routing data was not found. Progress points to the “G” in “GUID” of the errant routing data.</td>
</tr>
<tr>
<td>EFIDEVICE_ERROR</td>
<td>Block not large enough. Progress undefined.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Encountered non &lt;BlockName&gt; formatted string. Block is left updated and Progress points at the ‘&amp;’ preceding the first non-&lt;BlockName&gt;.</td>
</tr>
</tbody>
</table>

35.4.6 EFI_HII_CONFIG_ROUTING_PROTOCOL.ConfigToBlock()

Summary
This helper function is to be called by drivers to map configuration strings to configurations stored in byte array (“block”) formats such as UEFI Variables.

Prototype

typedef
EFI_STATUS
(EFI_API * EFI_HII_CONFIG_TO_BLOCK ) (    (IN CONSTATIC HII_CONFIG_ROUTING_PROTOCOL)
(IN CONSTATIC STRING)
(IN OUT CONSTATIC UINT8)
(IN OUT UINTN)
(OUT EFI_STRING)
);

35.4. EFI HII Configuration Routing Protocol
Parameters

This
Points to the EFI_HII_CONFIG_ROUTING_PROTOCOL instance.

ConfigResp
A null-terminated string in <ConfigResp> format.

Block
A possibly null array of bytes representing the current block. Only bytes referenced in the ConfigResp string in the block are modified. If this parameter is null or if the *BlockSize parameter is (on input) shorter than required by the Configuration string, only the BlockSize parameter is updated and an appropriate status (see below) is returned.

BlockSize
The length of the Block in units of UINT8. On input, this is the size of the Block. On output, if successful, contains the largest index of the modified byte in the Block, or the required buffer size if the Block is not large enough.

Progress
On return, points to an element of the ConfigResp string filled in with the offset of the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) or the terminating NULL if all was successful.

Description
This function maps a configuration containing a series of <BlockConfig> formatted name value pairs in ConfigResp into a Block so it may be stored in a linear mapped storage such as a UEFI Variable. If present, the function skips GUID, NAME, and PATH in <ConfigResp>. It stops when it finds a non-<BlockConfig> name / value pair (after skipping the routing header) or when it reaches the end of the string.

Example
Assume an existing block containing:

| 00 | 01 | 02 | 03 | 04 | 05 |

And the ConfigResp string is:

OFFSET=3 WIDTH=1 &VALUE=7 &OFFSET=0 WIDTH=2 &VALUE=AA55

The results are

| 55 | AA | 02 | 07 | 04 | 05 |

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The request succeeded. Progress points to the null terminator at the end of the ConfigResp string.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Not enough memory to allocate Config. Progress points to the first character of ConfigResp.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Passing in a NULL for the ConfigResp or Block parameter would result in this type of error. Progress points to the first character of ConfigResp.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Target for the specified routing data was not found. Progress points to the “G” in “GUID” of the errant routing data.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>Block not large enough. Progress undefined. BlockSize is updated with the required buffer size.</td>
</tr>
</tbody>
</table>

continues on next page
Table 35.7 – continued from previous page

| EFI_INVALID_PARAMETER | Encountered non <BlockName> formatted name / value pair. Block is left updated and Progress points at the ‘&’ preceding the first non-
|----------------------|-------------------------------------------------------------------------------------------------------------|

35.4.7 EFI_HII_CONFIG_ROUTING_PROTOCOL.GetAltCfg()

**Summary**

This helper function is to be called by drivers to extract portions of a larger configuration string.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI * EFI_HII_GET_ALT_CFG ) ( 
  IN CONST EFI_HII_CONFIG_ROUTING_PROTOCOL *This, 
  IN CONST EFI_STRING ConfigResp, 
  IN CONST EFI_GUID *Guid, 
  IN CONST EFI_STRING Name, 
  IN CONST EFI_DEVICE_PATH_PROTOCOL *DevicePath, 
  IN CONST EFI_STRING AltCfgId, 
  OUT EFI_STRING *AltCfgResp 
);
```

**Parameters**

- **This**
  
  Points to the `EFI_HII_CONFIG_ROUTING_PROTOCOL` instance.

- **ConfigResp**

  A null-terminated string in `<ConfigResp>` format.

- **Guid**

  A pointer to the GUID value to search for in the routing portion of the `ConfigResp` string when retrieving the requested data. If `Guid` is NULL, then all GUID values will be searched for.

- **Name**

  A pointer to the NAME value to search for in the routing portion of the `ConfigResp` string when retrieving the requested data. If `Name` is NULL, then all `Name` values will be searched for.

- **DevicePath**

  A pointer to the PATH value to search for in the routing portion of the `ConfigResp` string when retrieving the requested data. If `DevicePath` is NULL, then all `DevicePath` values will be searched for.

- **AltCfgId**

  A pointer to the ALTCFG value to search for in the routing portion of the `ConfigResp` string when retrieving the requested data. If this parameter is NULL, then the current setting will be retrieved.

- **AltCfgResp**

  A pointer to a buffer which will be allocated by the function which contains the retrieved string as requested. This buffer is only allocated if the call was successful. The null-terminated string will be in `<ConfigResp>` format.

**Description**

This function retrieves the requested portion of the configuration string from a larger configuration string. This function will use the `Guid`, `Name`, and `DevicePath` parameters to find the appropriate section of the `ConfigResp` string. Upon finding this portion of the string, it will use the `AltCfgId` parameter to find the appropriate instance of data in the
ConfigResp string. Once found, the found data will be copied to a buffer which is allocated by the function so that it can be returned to the caller. The caller is responsible for freeing this allocated buffer.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The request succeeded. The requested data was extracted and placed in the newly allocated AltCfgResp buffer.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Not enough memory to allocate AltCfgResp.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Passing in a NULL for the ConfigResp or AltCfgResp would result in this type of error.</td>
</tr>
</tbody>
</table>

### 35.5 EII HII Configuration Access Protocol

#### 35.5.1 EFI_HII_CONFIG_ACCESS_PROTOCOL

**Summary**

The EII configuration routing protocol invokes this type of protocol when it needs to forward requests to a driver’s configuration handler. This protocol is published by drivers providing and receiving configuration data from HII. The ExtractConfig() and RouteConfig() functions are typically invoked by the driver which implements the HII Configuration Routing Protocol. The Callback() function is typically invoked by the Forms Browser.

If the protocol functions modify active form set, they must not change layout and size of the existing variable stores.

The forms browser processes updated IFR package in accordance with the following rules:

1. If active form set no longer exists, the behavior is browser specific. The browser identifies form set using a combination of the form set GUID and device path associated with the package list containing the form set.

2. If form set update has been initiated by the Callback() function, the browser executes action requested by the function. See EFI_HII_CONFIG_ACCESS_PROTOCOL.CallBack() section for additional details regarding browser action requests.

**NOTE:** If browser action implies saving of the modified questions values, the browser will use uncommitted data associated with the old form set instance. The HII Configuration Access implementation is responsible for properly handling such requests.

3. The browser performs standard processing steps that are performed on a form set prior to displaying it (including reading question values and generating EFI_BROWSER_ACTION_FORM_OPEN and EFI_BROWSER_ACTION_FORM_RETRIEVE callbacks).

4. If there is an uncommitted browser data associated with an active form set, the browser applies it, matching variable stores by their identifiers. If variable store no longer exists, the uncommitted data for this store is discarded.

**NOTE:** Changing layout or size of the existing variable stores during form set update is not allowed and can lead to unpredictable results.

5. The browser applies prior browsing history, matching forms by their identifiers. If a form saved in the browsing history no longer exists, the behavior is browser-specific.

6. If all forms in the browsing history have been matched, the browser sets selection on a question that was active prior to the form set update, matching question by its identifier. If question does not exist, the first question on the form is selected.

**NOTE**
Protocol Interface Structure

typedef struct {
    EFI_HII_ACCESS_EXTRACT_CONFIG ExtractConfig;
    EFI_HII_ACCESS_ROUTE_CONFIG RouteConfig;
    EFI_HII_ACCESS_FORM_CALLBACK Callback;
} EFI_HII_CONFIG_ACCESS_PROTOCOL;

Related Definitions

None

Parameters

ExtractConfig

This function breaks apart the request strings routing them to the appropriate drivers. This function is analogous to the similarly named function in the HII Routing Protocol.

RouteConfig

This function breaks apart the results strings and returns configuration information as specified by the request.

Callback

This function is called from the configuration browser to communicate certain activities that were initiated by a user.

Description

This protocol provides a callable interface between the HII and drivers. Only drivers which provide IFR data to HII are required to publish this protocol.

35.5.2 EFI_HII_CONFIG_ACCESS_PROTOCOL.ExtractConfig()

Summary

This function allows a caller to extract the current configuration for one or more named elements from the target driver.

Prototype

typedef

EFI_STATUS

(EFI_API * EFI_HII_ACCESS_EXTRACT_CONFIG ) (  
IN CONST EFI_HII_CONFIG_ACCESS_PROTOCOL  *This,
IN CONST EFI_STRING Request,
OUT EFI_STRING  *Progress,
OUT EFI_STRING  *Results
);

Parameters

This

Points to the EFI_HII_CONFIG_ACCESS_PROTOCOL.

Request

A null-terminated string in <ConfigRequest> format. Note that this includes the routing information as well as the configurable name / value pairs. It is invalid for this string to be in <MultiConfigRequest> format.
If a NULL is passed in for the Request field, all of the settings being abstracted by this function will be returned in the Results field. In addition, if a ConfigHdr is passed in with no request elements, all of the settings being abstracted for that particular ConfigHdr reference will be returned in the Results Field.

**Progress**

On return, points to a character in the Request string. Points to the string’s null terminator if request was successful. Points to the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) if the request was not successful

**Results**

A null-terminated string in `<MultiConfigAltResp>` format which has all values filled in for the names in the Request string. String to be allocated by the called function.

**Description**

This function allows the caller to request the current configuration for one or more named elements. The resulting string is in `<ConfigAltResp>` format.

In order to support forms processors other than a Forms Browser, the configuration returned by this function must not depend on context in which the function is used. In particular, it must not depend on the current state of the Forms Browser (including any uncommitted state information) and actions performed by the driver callbacks invoked prior to the ExtractConfig call. See:numref:`Connected-forms-browser-processor` for more details.

Any and all alternative configuration strings shall also be appended to the end of the current configuration string. If they are, they must appear after the current configuration. They must contain the same routing (GUID, NAME, PATH) as the current configuration string. They must have an additional description indicating the type of alternative configuration the string represents, “ALTCFG=<AltCfgId>”. The <AltCfgId> is a reference to a Default ID which stipulates the type of Default being referenced such as `EFI_HII_DEFAULT_CLASS_STANDARD`.

As an example, assume that the Request string is:

```
GUID=...&PATH=...&Fred&George&Ron&Neville
```

A result might be:

```
GUID=...&PATH=...&Fred=16&George=16&Ron=12&Neville=11&GUID=...&PATH=...&ALTCFG=0037&Fred=12&Neville=7
```

This function allows the caller to request the current configuration for one or more named elements. The resulting string is in `<ConfigAltResp>` format.

Any and all alternative configuration strings shall also be appended to the end of the current configuration string. If they are, they must appear after the current configuration. They must contain the same routing (GUID, NAME, PATH) as the current configuration string. They must have an additional description indicating the type of alternative configuration the string represents, “ALTCFG=<AltCfgId>”. The <AltCfgId> is a reference to a Default ID which stipulates the type of Default being referenced such as `EFI_HII_DEFAULT_CLASS_STANDARD`.

As an example, assume that the Request string is:

```
GUID=...&PATH=...&Fred&George&Ron&Neville
```

A result might be:

```
GUID=...&PATH=...&Fred=16&George=16&Ron=12&Neville=11&GUID=...&PATH=...&ALTCFG=0037&Fred=12&Neville=7
```

**NOTE**: For the output Results, the value filled in the names in the Request string with `<ConfigAltResp>` format may change when called multiple times due to some data being of a dynamic nature.

**Status Codes Returned**
### EFI_HII_CONFIG_ACCESS_PROTOCOL.RouteConfig()

#### Summary
This function processes the results of changes in configuration for the driver that published this protocol.

#### Prototype
```c
typedef EFI_STATUS
(EFI_API * EFI_HII_ACCESS_ROUTE_CONFIG ) (
    IN CONST EFI_HII_CONFIG_ACCESS_PROTOCOL *This,
    IN CONST EFI_STRING Configuration,
    OUT EFI_STRING *Progress
);
```

#### Parameters
- **This**
  Points to the `EFI_HII_CONFIG_ACCESS_PROTOCOL`.

- **Configuration**
  A null-terminated string in `<ConfigResp>` format.

- **Progress**
  A pointer to a string filled in with the offset of the most recent ‘&’ before the first failing name / value pair (or the beginning of the string if the failure is in the first name / value pair) or the terminating NULL if all was successful.

#### Description
This function applies changes in a driver’s configuration. Input is a `Configuration`, which has the routing data for this driver followed by name / value configuration pairs. The driver must apply those pairs to its configurable storage.

In order to support forms processors other than a Forms Browser, the way in which configuration data is applied must not depend on context in which the function is used. In particular, it must not depend on the current state of the Forms Browser (including any uncommitted state information) and actions performed by the driver callbacks invoked prior to the `RouteConfig` call. `Connected Forms Browser/Processor` provides additional details regarding forms browser/processor.

If the driver’s configuration is stored in a linear block of data and the driver’s name / value pairs are in `<BlockConfig>` format, it may use the `ConfigToBlock` helper function (above) to simplify the job.

#### Status Codes Returned
- **EFI_SUCCESS**
  The `Results` string is filled with the values corresponding to all requested names.

- **EFI_OUT_OF_RESOURCES**
  Not enough memory to store the parts of the results that must be stored awaiting possible future protocols.

- **EFI_NOT_FOUND**
  A configuration element matching the routing data is not found. Progress set to the first character in the routing header.

- **EFI_INVALID_PARAMETER**
  Illegal syntax. Progress set to most recent “&” before the error or the beginning of the string.

- **EFI_INVALID_PARAMETER**
  Unknown name. Progress points to the “&” before the name in question.

- **EFI_INVALID_PARAMETER**
  If `Results` or `Progress` is `NULL`.

- **EFI_ACCESS_DENIED**
  The action violated a system policy.

- **EFI_DEVICE_ERROR**
  Failed to extract the current configuration for one or more named elements.
**35.5.4 EFI_HII_CONFIG_ACCESS_PROTOCOL.CallBack()**

**Summary**
This function is called to provide results data to the driver.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_HII_ACCESS_FORM_CALLBACK) (
    IN CONST EFI_HII_CONFIG_ACCESS_PROTOCOL *This,
    IN EFI_BROWSER_ACTION Action,
    IN EFI_QUESTION_ID QuestionId,
    IN UINT8 Type,
    IN OUT EFI_IFR_TYPE_VALUE *Value,
    OUT EFI_BROWSER_ACTION_REQUEST *ActionRequest,
);
```

**Parameters**

**This**
Points to the `EFI_HII_CONFIG_ACCESS_PROTOCOL`.

**Action**
Specifies the type of action taken by the browser. See `EFI_BROWSER_ACTION_x` in “Related Definitions” below.

**QuestionId**
A unique value which is sent to the original exporting driver so that it can identify the type of data to expect. The format of the data tends to vary based on the opcode that generated the callback.

**Type**
The type of value for the question. See `EFI_IFR_TYPE_x` in `EFI_IFR_ONE_OF_OPTION`.

**Value**
A pointer to the data being sent to the original exporting driver. The type is specified by `Type`. Type `EFI_IFR_TYPE_VALUE` is defined in `EFI_IFR_ONE_OF_OPTION`.

**ActionRequest**
On return, points to the action requested by the callback function. Type `EFI_BROWSER_ACTION_REQUEST` is specified in `SendForm()` in the Form Browser Protocol.

**Description**
This function is called by the forms browser in response to a user action on a question which has the `EFI_IFR_FLAG_CALLBACK` bit set in the `EFI_IFR_QUESTION_HEADER`. The user action is specified by `Action`. Depending on the action, the browser may also pass the question value using `Type` and `Value`. Upon return, the callback function may specify the desired browser action.
The browser maintains uncommitted browser data (modified and unsaved question values) across Callback function boundaries. Callback function may change unsaved question values using one of the following methods:

- Current question’s value may be changed by updating the `Value` parameter.
- Values of other questions from the active formset can be changed using `EFI_FORM_BROWSER2_PROTOCOL.BrowserCallback()` interface.

**NOTE**: Modification of the question values by the Callback function without notifying the browser using one of the above mentioned methods can lead to unpredictable browser behavior.

Callback function may request configuration update from the browser by returning an appropriate `ActionRequest`.

In order to save uncommitted data, driver should return one of the `_SUBMIT` actions or `_APPLY` action. The browser will then write all modified question values (in case of the `_SUBMIT` actions) or modified question values from an active form (in case of the `_APPLY` action) to storage using `RouteConfig()` function. This will include questions modified prior to an invocation of the `Callback()` function as well as questions modified by the `Callback()` function.

The behavior of the `ExtractConfig` and `RouteConfig` functions must not depend on the actions performed by this function.

Callback functions should return `EFI_UNSUPPORTED` for all values of `Action` that they do not support.

### Related Definitions

```c
typedef UINTN EFI_BROWSER_ACTION;
#define EFI_BROWSER_ACTION_CHANGING 0
#define EFI_BROWSER_ACTION_CHANGED 1
#define EFI_BROWSER_ACTION_RETRIEVE 2
#define EFI_BROWSER_ACTION_FORM_OPEN 3
#define EFI_BROWSER_ACTION_FORM_CLOSE 4
#define EFI_BROWSER_ACTION_SUBMITTED 5
#define EFI_BROWSER_ACTION_DEFAULT_STANDARD 0x1000
#define EFI_BROWSER_ACTION_DEFAULT_MANUFACTURING 0x1001
#define EFI_BROWSER_ACTION_DEFAULT_SAFE 0x1002
#define EFI_BROWSER_ACTION_DEFAULT_PLATFORM 0x2000
#define EFI_BROWSER_ACTION_DEFAULT_HARDWARE 0x3000
#define EFI_BROWSER_ACTION_DEFAULT_FIRMWARE 0x4000
```

The following table describes the behavior of the callback for each question type.

<table>
<thead>
<tr>
<th>Question Type</th>
<th>Type</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>Action Button</td>
<td><code>EFI_IFR_TYPE_ACTION</code></td>
<td>No special behavior. If the short form of the opcode is used, then the value will be a string identifier of zero.</td>
</tr>
<tr>
<td>Checkbox</td>
<td><code>EFI_IFR_TYPE_BOOLEAN</code></td>
<td>No special behavior</td>
</tr>
<tr>
<td>Cross-Reference</td>
<td><code>EFI_IFR_TYPE_REF</code></td>
<td>CHANGING: If <code>EFI_UNSUPPORTED</code> or <code>EFI_SUCCESS</code>, the updated cross-reference is taken. Any other error the cross-reference will not be taken.</td>
</tr>
<tr>
<td></td>
<td><code>EFI_IFR_TYPE_UNDEFINED</code></td>
<td>CHANGED: Never called. RETRIEVE: Called before displaying the cross-reference. Error codes ignored. The Ref field of the Value parameter is initialized with the REF question’s value prior to CHANGING and RETRIEVE.</td>
</tr>
</tbody>
</table>

continues on next page
Table 35.11 – continued from previous page

<table>
<thead>
<tr>
<th>Date</th>
<th>EFI_IFR_TYPE_DATE</th>
<th>No special behavior</th>
</tr>
</thead>
<tbody>
<tr>
<td>Numeric, One-Of</td>
<td>EFI_IFR_TYPE_NUM_SIZE_8, EFI_IFR_TYPE_NUM_SIZE_16, EFI_IFR_TYPE_NUM_SIZE_32, EFI_IFR_TYPE_NUM_SIZE_64</td>
<td>No special behavior.</td>
</tr>
<tr>
<td>Ordered-List</td>
<td>EFI_IFR_TYPE_BUFFER</td>
<td>No special behavior.</td>
</tr>
<tr>
<td>String, Password</td>
<td>EFI_IFR_TYPE_STRING</td>
<td>No special behavior.</td>
</tr>
<tr>
<td>Time</td>
<td>EFI_IFR_TYPE_DATE</td>
<td>No special behavior.</td>
</tr>
</tbody>
</table>

The value ` EFI_BROWSER_ACTION_CHANGING ` is called before the browser changes the value in the display (for questions which have a value) or takes an action (in the case of an action button or cross-reference). If the callback returns ` EFI_UNSUPPORTED `, then the browser will use the value passed to ` Callback() ` and ignore the value returned by ` Callback() `. If the callback returns ` EFI_SUCCESS `, then the browser will use the value returned by ` Callback() `. If any other error is returned, then the browser will not update the current question value. ` ActionRequest ` is used. The ` Value ` represents the updated value. The changes here should not be finalized until the user submits the results.

The value ` EFI_BROWSER_ACTION_CHANGED ` is called after the browser has changed its internal copy of the question value and displayed it (if appropriate). For action buttons, this is called after the value has been processed. For cross-references, this is never called. Errors returned are ignored. ` ActionRequest ` is used. The changes here should not be finalized until the user submits the results.

The value ` EFI_BROWSER_ACTION_RETRIEVE ` is called after the browser has read the current question value, but before it has been displayed. If the callback returns ` EFI_UNSUPPORTED ` or any other error then the original value is used. If ` EFI_SUCCESS ` is returned, then the updated value is used.

The value ` EFI_BROWSER_ACTION_FORM_OPEN ` is called for each question on a form prior to its value being retrieved or displayed. If a question appears on more than one form, and the Forms Processor supports more than one form being active simultaneously, this may be called more than once, even prior to any ` EFI_BROWSER_ACTION_FORM_CLOSE ` callback.

**NOTE:** `EFI_FORM_BROWSER2_PROTOCOL.BrowserCallback()` cannot be used with this browser action because question values have not been retrieved yet.

The value ` EFI_BROWSER_ACTION_FORM_CLOSE ` is called for each question on a form after the processing of any submit actions for that form. If a question appears on more than one form, and the Forms Processor supports more than one form being active simultaneously, this will be called more than once.

The value ` EFI_BROWSER_ACTION_SUBMITTED ` is called after Browser submits the modified question value. ` ActionRequest ` is ignored.

When ` Action ` specifies one of the “default” actions, such as ` EFI_BROWSER_ACTION_DEFAULT_STANDARD `, etc. it indicates that the Forms Processor is attempting to retrieve the default value for the specified question. The proposed default value is passed in using ` Type ` and ` Value ` and reflects the value which the Forms Processor was able to select based on the lower-priority defaulting methods (see ` Defaults `). If the function returns ` EFI_SUCCESS `, then the updated value will be used. If the function does not have an updated default value for the specified question or specified default store, or does not provide any support for the actions, it should return ` EFI_UNSUPPORTED `, and the returned value will be ignored.

The ` DEFAULT_PLATFORM `, ` DEFAULT_HARDWARE ` and ` DEFAULT_FIRMWARE ` represent ranges of 4096 (0x1000) possible default store identifiers. The ` DEFAULT_STANDARD ` represents the range of 4096 possible action values reserved for UEFI-defined default store identifiers. See ` Defaults ` for more information on defaults.

35.5. EFI HII Configuration Access Protocol 1822
typedef UINTN EFI_BROWSER_ACTION_REQUEST;

#define EFI_BROWSER_ACTION_REQUEST_NONE 0
#define EFI_BROWSER_ACTION_REQUEST_RESET 1
#define EFI_BROWSER_ACTION_REQUEST_SUBMIT 2
#define EFI_BROWSER_ACTION_REQUEST_EXIT 3
#define EFI_BROWSER_ACTION_REQUEST_FORM_SUBMIT_EXIT 4
#define EFI_BROWSER_ACTION_REQUEST_FORM_DISCARD_EXIT 5
#define EFI_BROWSER_ACTION_REQUEST_FORM_APPLY 6
#define EFI_BROWSER_ACTION_REQUEST_FORM_DISCARD 7
#define EFI_BROWSER_ACTION_REQUEST_RECONNECT 8
#define EFI_BROWSER_ACTION_REQUEST_QUESTION_APPLY 9

If the callback function returns with the `ActionRequest` set to _NONE, then the Forms Browser will take no special behavior.

If the callback function returns with the `ActionRequest` set to _RESET, then the Forms Browser will exit and request the platform to reset.

If the callback function returns with the `ActionRequest` set to _SUBMIT, then the Forms Browser will save all modified question values to storage and exit.

If the callback function returns with the `ActionRequest` set to _EXIT, then the Forms Browser will discard all modified question values and exit.

If the callback function returns with the `ActionRequest` set to _FORM_SUBMIT_EXIT, then the Forms Browser will write all modified question values on the selected form to storage and then exit the selected form.

If the callback function returns with the `ActionRequest` set to _FORM_DISCARD_EXIT, then the Forms Browser will discard the modified question values on the selected form and then exit the selected form.

If the callback function returns with the `ActionRequest` set to _FORM_APPLY, then the Forms Browser will write all modified current question values on the selected form to storage.

If the callback function returns with the `ActionRequest` set to _FORM_DISCARD, then the Forms Browser will discard the current question values on the selected form and replace them with the original question values.

If the callback function returns with the `ActionRequest` set to _RECONNECT, a hardware and/or software configuration change was performed by the user, and the controller needs to be reconnected for the driver to recognize the change. Upon the user exiting the formset or the browser, the Forms Browser is required to call the EFI Boot Service `DisconnectController()` followed by the EFI Boot Service `ConnectController()` to reconnect the controller. The controller handle passed to `DisconnectController()` and `ConnectController()` is the handle on which this `EFI_HII_CONFIG_ACCESS_PROTOCOL` is installed.

If the callback function returns with the `ActionRequest` set to _QUESTION_APPLY, then the Forms Browser will write the current modified question value on the selected form to storage.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The callback successfully handled the action.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Not enough storage is available to hold the variable and its data.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The variable could not be saved.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The specified Action is not supported by the callback.</td>
</tr>
</tbody>
</table>
35.6 Form Browser Protocol

The *EFI_FORM_BROWSER2_PROTOCOL* is the interface to call for drivers to leverage the EFI configuration driver interface.

35.6.1 EFI_FORM_BROWSER2_PROTOCOL

Summary

The *EFI_FORM_BROWSER2_PROTOCOL* is the interface to the UEFI configuration driver. This interface will allow the caller to direct the configuration driver to use either the HII database or use the passed-in packet of data.

GUID

```c
#define EFI_FORM_BROWSER2_PROTOCOL_GUID
    { 0xb9d4c360, 0xbcfd, 0x4f9b,
    { 0x92, 0x98, 0x53, 0xc1, 0x36, 0x98, 0x22, 0x58 } }
```

Protocol Interface Structure

```c
typedef struct _EFI_FORM_BROWSER2_PROTOCOL {
    EFI_SEND_FORM2 SendForm;
    EFI_BROWSER_CALLBACK2 BrowserCallback;
} EFI_FORM_BROWSER2_PROTOCOL;
```

Parameters

SendForm

Browse the specified configuration forms. See the *SendForm()* function description.

BrowserCallback

Routine used to expose internal configuration state of the browser. This is primarily used by callback handler routines which were called by the browser and in-turn need to get additional information from the browser itself. See the *BrowserCallback()* function description.

Description

This protocol is the interface to call for drivers to leverage the EFI configuration driver interface.

35.6.2 EFI_FORM_BROWSER2_PROTOCOL.SendForm()

Summary

Initialize the browser to display the specified configuration forms.

Prototype

```c
typedef
EFI_STATUS
(EIFIAP *EFI_SEND_FORM2) (  
    IN CONST EFI_FORM_BROWSER2_PROTOCOL This,
    IN EFI_HII_HANDLE Handles,
```
IN UINTN HandleCount, HandleCount,
IN CONST EFI_GUID *FormsetGuid, OPTIONAL FormsetGuid, OPTIONAL
IN EFI_FORM_ID FormId, OPTIONAL FormId, OPTIONAL
IN CONST EFI_SCREEN_DESCRIPTOR *ScreenDimensions, OPTIONAL ScreenDimensions, OPTIONAL
OUT EFI_BROWSER_ACTION_REQUEST *ActionRequest OPTIONAL ActionRequest OPTIONAL

);

Parameters

This

A pointer to the \textit{EFI\_FORM\_BROWSER2\_PROTOCOL} instance.

Handles

A pointer to an array of HII handles to display. This value should correspond to the value of the HII form package that is required to be displayed. Type \textit{EFI\_HII\_HANDLE} is defined in \textit{EFI\_HII\_DATABASE\_PROTOCOL.NewPackageList()} in \textit{Package Lists and Package Headers}.

HandleCount

The number of handles in the array specified by \textit{Handle}.

FormsetGuid

This field points to the \textit{EFI\_GUID} which must match the \textit{Guid} field or one of the elements of the ClassId field in the \textit{EFI\_IFR\_FORM\_SET} op-code. If \textit{FormsetGuid} is \text{NULL}, then this function will display the form set class \textit{EFI\_HII\_PLATFORM\_SETUP\_FORMSET\_GUID}.

FormId

This field specifies the identifier of the form within the form set to render as the first displayable page. If this field has a value of 0x0000, then the Forms Browser will render the first enabled form in the form set.

ScreenDimensions

Points to recommended form dimensions, including any non-content area, in characters. Type \textit{EFI\_SCREEN\_DECRIPTOR} is defined in “Related Definitions” below.

ActionRequested

Points to the action recommended by the form.

Description

This function is the primary interface to the Forms Browser. The Forms Browser displays the forms specified by \textit{FormsetGuid} and \textit{FormId} from all of HII handles specified by \textit{Handles}. If more than one form can be displayed, the Forms Browser will provide some means for the user to navigate between the forms in addition to that provided by cross-references in the forms themselves.

If ScreenDimensions is non-NULL, then it points to a recommended display size for the form. If browsing in text mode, then these are recommended character positions. If browsing in graphics mode, then these values are converted to pixel locations using the standard font size (8 pixels per horizontal character cell and 19 pixels per vertical character cell).

If ScreenDimensions is \text{NULL} the browser may choose the size based on platform policy. The browser may choose to ignore the size based on platform policy.

If ActionRequested is non-NULL, then upon return, it points to an enumerated value (see \textit{EFI\_BROWSER\_ACTION\_x} in “Related Definitions” below) which describes the action requested by the user. If set to \textit{EFI\_BROWSER\_ACTION\_NONE}, then no specific action was requested by the form. If set to \textit{EFI\_BROWSER\_ACTION\_RESET}, then the form requested that the platform be reset. The browser may, based on platform policy, ignore such action requests.

If \textit{FormsetGuid} is set to \textit{EFI\_HII\_PLATFORM\_SETUP\_FORMSET\_GUID}, it indicates that the form set contains forms designed to be used for platform configuration. If \textit{FormsetGuid} is set to \textit{EFI\_HII\_DRIVER\_HEALTH\_FORMSET\_GUID}, it indicates that the form set contains forms designed to be used for support of the Driver Health Protocol (\textit{EFI Driver Health Protocol}). If \textit{FormsetGuid} is set to
**EFI_HII_USER_CREDENTIAL_FORMSET_GUID**, it indicates that the form set contains forms designed to be used for support of the User Credential Protocol (Credential Provider Protocols). If FormsetGuid is set to **EFI_HII_REST_STYLE_FORMSET_GUID**, it indicates that the form set contains forms designed to be used for support configuration of REST architectural style (see Section 29.7). Other values may be used for other applications.

**Related Definitions**

```
// ****************************************************************************
// EFI_SCREEN_DESCRIPTOR
// ****************************************************************************
typedef struct {
    UINTN  LeftColumn;
    UINTN  RightColumn;
    UINTN  TopRow;
    UINTN  BottomRow;
} EFI_SCREEN_DESCRIPTOR;
```

**LeftColumn**
Value that designates the text column where the browser window will begin from the left-hand side of the screen.

**RightColumn**
Value that designates the text column where the browser window will end on the right-hand side of the screen.

**TopRow**
Value that designates the text row from the top of the screen where the browser window will start.

**BottomRow**
Value that designates the text row from the bottom of the screen where the browser window will end.

```
typedef UINTN EFI_BROWSER_ACTION_REQUEST;
#define EFI_BROWSER_ACTION_REQUEST_NONE  0
#define EFI_BROWSER_ACTION_REQUEST_RESET 1
#define EFI_BROWSER_ACTION_REQUEST_SUBMIT 2
#define EFI_BROWSER_ACTION_REQUEST_EXIT   3
```

The value **EFI_BROWSER_ACTION_REQUEST_NONE** indicates that no specific caller action is required. The value **EFI_BROWSER_ACTION_REQUEST_RESET** indicates that the caller requested a platform reset. The value **EFI_BROWSER_ACTION_REQUEST_SUBMIT** indicates that a callback requested that the browser submit all values and exit. The value **EFI_BROWSER_ACTION_REQUEST_EXIT** indicates that a callback requested that the browser exit without saving all values.

```
#define EFI_HII_PLATFORM_SETUP_FORMSET_GUID  
    { 0x93039971, 0x8545, 0x4b04,  
        { 0xb4, 0x5e, 0x32, 0xeb, 0x83, 0x26, 0x04, 0x0e } }
#endif
#define EFI_HII_DRIVER_HEALTH_FORMSET_GUID   
    { 0xf22fc20c, 0x8cf4, 0x45eb,  
        { 0x8e, 0x06, 0xad, 0x4e, 0x50, 0xb9, 0x5d, 0xd3 } }
#endif
#define EFI_HII_USER_CREDENTIAL_FORMSET_GUID 
    { 0x337f4407, 0x5aee, 0x4b83,  
        { 0xb2, 0xa7, 0xad, 0xca, 0x30, 0x88, 0xcd } }
#endif
#define EFI_HII_REST_STYLE_FORMSET_GUID 
```

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Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The function completed successfully</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No valid forms could be found to display.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>One of the parameters has an invalid value.</td>
</tr>
</tbody>
</table>

### 35.6.3 EFI_FORM_BROWSER2_PROTOCOL.BrowserCallback()

**Summary**
This function is called by a callback handler to retrieve uncommitted state data from the browser.

**Prototype**

```c
EFI_STATUS
    (EFIAPI *EFI_BROWSER_CALLBACK2 ) ( 
    IN CONST EFI_FORM_BROWSER2_PROTOCOL *This,
    IN OUT UINTN *ResultsDataSize,
    IN OUT EFI_STRING ResultsData,
    IN BOOLEAN RetrieveData,
    IN CONST EFI_GUID *VariableGuid, OPTIONAL
    IN CONST CHAR16 *VariableName OPTIONAL
    );
```

**Parameters**

- **This**
  A pointer to the `EFI_FORM_BROWSER2_PROTOCOL` instance.

- **ResultsDataSize**
  A pointer to the size of the buffer associated with `ResultsData`. On input, the size in bytes of `ResultsData`. On output, the size of data returned in `ResultsData`.

- **ResultsData**
  A string returned from an IFR browser or equivalent. The results string will have no routing information in them.

- **RetrieveData**
  A BOOLEAN field which allows an agent to retrieve (if `RetrieveData` = TRUE) data from the uncommitted browser state information or set (if `RetrieveData` = FALSE) data in the uncommitted browser state information.

- **VariableGuid**
  An optional field to indicate the target variable GUID name to use.

- **VariableName**
  An optional field to indicate the target human-readable variable name.

**Description**
This service is typically called by a driver’s callback routine which was in turn called by the browser. The routine called this service in the browser to retrieve or set certain uncommitted state information that resides in the open formsets.

**Status Codes Returned**
35.7 HII Popup Protocol

35.7.1 EFI_HII_POPUP_PROTOCOL

Summary

This protocol provides services to display a popup window.

The protocol is typically produced by the forms browser and consumed by a driver’s callback handler.

GUID

```c
#define EFI_HII_POPUP_PROTOCOL_GUID \
{ 0x4311edc0, 0x6054, 0x46d4, { 0x9e, 0x40, 0x89, 0x3e, 0xa9, 0x52, 0xfc, 0xcc } }
```

Protocol Interface Structure

```c
typedef struct {
    UINT64 Revision;
    EFI_HII_CREATE_POPUP CreatePopup;
} EFI_HII_POPUP_PROTOCOL;
```

Parameters

- **Revision**
  - Protocol revision

- **CreatePopup**
  - Displays a popup window

Related Definitions

```c
#define EFI_HII_POPUP_PROTOCOL_REVISION 1
```

35.7.2 EFI_HII_POPUP_PROTOCOL.CreatePopup()

Summary

Displays a popup window.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI * EFI_HII_CREATE_POPUP) ( 
    IN EFI_HII_POPUP_PROTOCOL Protocol, 
    IN EFI_HII_POPUP_STYLE PopupStyle, 
    IN EFI_HII_POPUP_TYPE PopupType, 
    ... )
```

(continues on next page)
Parameters

This
A pointer to the EFI_HII_POPUP_PROTOCOL instance.

PopupStyle
Popup style to use. EFI_HII_POPUP_STYLE is defined in the “Related Definitions” below.

PopupType
Type of the popup to display. EFI_HII_POPUP_TYPE is defined in the “Related Definitions” below.

HiiHandle
HII handle of the string pack containing Message

Message
A message to display in the popup box.

UserSelection
User selection. EFI_HII_POPUP_SELECTION is defined in the “Related Definitions” below.

Description
The CreatePopup() function displays a modal message box that contains string specified by Message. Explicit line break characters can be used to specify a multi-line message (Common Control Codes). A popup window may contain user selectable options. The option selected by a user is returned via an optional UserSelection parameter.

A list of options presented to a user is defined by the PopupType.

The PopupStyle provides a hint to protocol implementation regarding nature of the message being displayed. The function may optionally use PopupStyle to customize visual appearance of the message box.

EfiHiiPopupTypeOk is a simple popup window with a single user selectable option that can be used to acknowledge the message. If UserSelection is specified, it is set to EfiHiiPopupSelectionOk.

EfiHiiPopupTypeOkCancel is a popup window with two user selectable options: OK and Cancel.

EfiHiiPopupTypeYesNo is a popup window with two user selectable options: Yes and No.

EfiHiiPopupTypeYesNoCancel is a popup window with three user selectable options: Yes, No, and Cancel.

Related Definitions

typedef enum {
    EfiHiiPopupStyleInfo,
    EfiHiiPopupStyleWarning,
    EfiHiiPopupStyleError
} EFI_HII_POPUP_STYLE;
typedef enum {
    EfiHiiPopupTypeOk,
    EfiHiiPopupTypeOkCancel,
    EfiHiiPopupTypeYesNo,
    EfiHiiPopupTypeYesNoCancel
} EFI_HII_POPUP_TYPE;
typedef enum {
    EfiHiiPopupSelectionOk,

(continues on next page)
EfiHiiPopupSelectionCancel,
EfiHiiPopupSelectionYes,
EfiHiiPopupSelectionNo
} EFI_HII_POPUP_SELECTION;

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The popup box was successfully displayed</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HiiHandle and Message do not define is a valid HII string.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PopupType is not one of the values defined by this specification.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There are not enough resources available to display the popup box.</td>
</tr>
</tbody>
</table>
36.1 User Identification Overview

This section describes services which describe the current user of the platform. A user is the entity which is controlling the behavior of the machine. The user may be an individual, a class or group of individuals or another machine.

Each user has a user profile. There is always at least one user profile for a machine. This profile governs the behavior of the user identification process until another user has been selected. The nature and definition of these privileges are beyond the scope of this section. One user profile is always active and describes the platform’s current user.

New user profiles are introduced into the system through enrollment. During enrollment, information about a new user is gathered. Some of this information identifies the user for specific purposes, such as a user’s name or a user’s network domain. Other information is gathered in the form of credentials, which is information which can be used at a later time to verify the identity of a user. Credentials are generally divided into three categories: something you know (password), something you have (smart card, smart token, RFID), something you are (fingerprint). The means by which a platform determines the user’s identity based on credentials is user identification.

In the simplest case, a single set of credentials are required to establish a user’s identity. This is called single-factor authentication. In more rigorous cases, multiple credentials might be required to establish a user’s identity or different privilege levels given if only a single factor is available. This is called multi-factor authentication.

If the credentials are checked only once, this is called static authentication. For example, a sign-on box where the user enters a password and provides a fingerprint would be examples of static authentication. However, if credentials (and thus the user’s identity) can be changed during system execution, this is called dynamic authentication. For example, a smart token which can be hot-removed from the system or an RFID tag which is moved in and out of range would be examples of dynamic authentication.

The user identity manager is the optional UEFI driver which manages the process of determining the user’s identity and storing information about the user.

The user enrollment manager is the optional application which adds or enrolls new users, gathering the necessary information to ascertain their identity in the future.

The credential provider driver manages a single class of credentials. Examples include a USB fingerprint sensor, a smart card or a password. The means by which these drivers are selected and invoked is beyond the scope of this specification.
36.1.1 User Identify

The process of identifying the user occurs after platform initialization has made the services described in the EFI System Table available. Before the Boot Manager behavior described in chapter 3, a user profile must be established. The user profile established might be:

- A default user profile, giving a standard set of privileges. This is similar to a “guest” login.
- A default user profile, based on a User Credential Provider where Default() returns AutoLogon = TRUE.
- A specific user profile, established using the Identify() function of the User Manager.

Every time the user profile is modified, the User Identity Manager will signal the EFI_EVENT_GROUP_USER_PROFILE_CHANGED event. The current user profile can only be changed by calling the User Identity Manager’s Identify() function or as the result of a credential provider calling the Notify() function (when dynamic authentication is supported). The Identify() function changes the current user profile after examining the credentials provided by the various credential providers and comparing these against those found in the user profile database.

When the UEFI Boot Manager signals the EFI_EVENT_GROUP_READY_TO_BOOT event group, the User Identity Manager publishes the current user profile information in the EFI System Configuration Table.

Depending on the security considerations in the implementation (see Security Considerations), user identification can continue into different phases of execution.
1. Boot Manager, Once. In this scenario, identification is permitted until the EFI_EVENT_GROUP_READY_TO_BOOT is signaled by the Boot Manager. After this time, user identification is not allowed again. This is the simplest, since the user profile database can be locked at this time using a simple one-time lock.

2. Boot Manager, Multiple. In this scenario, identification is permitted until the EFI_EVENT_GROUP_READY_TO_BOOT is signaled by the Boot Manager. After this time, if the boot option returns back into the Boot Manager, identification is allowed again. This scenario requires that the user profile database only be updatable while in the Boot Manager.

3. Until ExitBootServices. In this scenario, identification is permitted until the EFI_EVENT_GROUP_EXIT_BOOT_SERVICES is signaled by the Boot Manager. This scenario requires that the user profile database cannot be updated by unauthorized executables.

36.1.2 User Profiles

The user profiles are collections of information about users. There is always a current user (and thus, a currently selected user profile). The user profiles are stored in a user profile database.

Each user profile has the following attributes:

§ User Identifier

User identifiers are unique to a particular user profile. The uniqueness of the user profile identifier must persist across reboots. Credentials return this identifier during the identification process.

§ User Identification Policy

The user identification policy determines which credentials must be presented in order to establish the user’s identity and set the user profile as the current user profile. The policy consists of a boolean expression consisting of credential handles and the operators AND, OR and NOT. This allows the user profile to be selected, for example, depending on a password credential OR a fingerprint credential. Or the profile might be selected depending on a password credential AND a fingerprint credential.

§ User Privileges

The user privileges control what the user can and cannot do. For example, can the user enroll other users, boot off of a selected device, etc.

§ User Information

User information consists of typed data records attached to the user profile handle. Some of this information is non-volatile. Some of this information may be provided by a specific credential driver. User information is classified as public, private or protected:

- Public user information is available at any time.
- Private user information is only available while it is part of the current user profile.
- Protected user information is only available once user has been authenticated by a credential provider.

Drivers and applications can be notified when the current user profile is changed, by using the UEFI Boot Service CreateEventEx() and the EFI_EVENT_GROUP_USER_PROFILE_CHANGED

User profiles are available while the User Identity Manager is running, but only the current user profile is available after the UEFI Boot Manager has started execution.

36.1. User Identification Overview
36.1.2.1 User Profile Database

The user profile database is a repository of all users known to the user identity manager. The user profile database should be maintained in non-volatile memory and this memory must be protected against corruption and erasure.

The user profile database is considered “open” if the user profile database can still be updated and the current profile can still be changed using the EFI User Manager Protocol. The user profile database is considered “closed” if the user profile database cannot be updated nor the current user profile changes using the EFI User Manager Protocol.

36.1.2.2 User Identification Policy

The user identification policy is a boolean expression which determines which class of credential or which credential providers must assert the user’s identity in order to a user profile to be eligible for selection as the current user profile.

For example, assume that you want a password:

<table>
<thead>
<tr>
<th>CredentialClass(Password)</th>
</tr>
</thead>
</table>

This expression would assert TRUE if any credential provider asserts that a user has successfully entered a password.

<table>
<thead>
<tr>
<th>CredentialClass(Password) &amp;&amp; CredentialClass(Fingerprint)</th>
</tr>
</thead>
</table>

This expression would require the user to present both a fingerprint AND a password in order to select this user profile.

| CredentialClass(Password) || CredentialClass(Fingerprint) |
|---------------------------|

This expression, on the other hand, allows the user to present a fingerprint OR a password in order to select this user profile.

Let’s say you only want the Phoenix password provider:

<table>
<thead>
<tr>
<th>CredentialClass(Password) &amp;&amp; CredentialProvider(Phoenix)</th>
</tr>
</thead>
</table>

In all of these cases, the class of credential and the provider of the credential are actually GUIDs. The standard credential class GUIDs are assigned by this specification. The credential provider identifiers are generated by the companies creating the credential providers.

36.1.3 Credential Providers

The User Credential Provider drivers follow the UEFI driver model. During initialization, they install an instance of the EFI Driver Binding Protocol. For hardware devices, the User Credential Provider may consume the bus I/O protocol and produce the User Credential Protocol. For software-based User Credential Providers, the User Credential Protocol could be installed on the image handler. The exact implementation depends on the number of separate credential types that the User Identity Manager will display.

When Start() is called, they:

1. Install one instance of the EFI_USER_CREDENTIAL2_PROTOCOL for each simultaneous user which might be authenticated. For example, if more than one smart token were inserted, then one instance might be created for each token. However, for a fingerprint sensor, one instance might be created for all fingerprint sensors managed by the same driver.

2. Install the user-interface forms used for interacting with the user using the HII Database Protocol. The form must be encoded using the GUID EFI_USER_CREDENTIAL2_PROTOCOL_GUID.
3. Install the EFI HII Configuration Access Protocol to handle interaction with the UEFI forms browser. This protocol is called to retrieve the current information from the credential provider. It is also called when the user presses OK to save the current form values. It also provides the callback functionality which allows real-time processing of the form values.

User Credential Providers are responsible for creating a one-to-one mapping between a device, fingerprint or password and a user identifier.

This specification does not explicitly support passing of user credential information related to operating system logon to an OS-present environment. For example, User Credential Providers may encrypt the user credential information and pass it, either as a part of the User Information Table or the EFI System Configuration Table, to an OS-present driver or application.

This specification does not explicitly support OS-present update of user credential information or user identification policy. Such support may be implemented in many ways, including the usage of write-authenticated EFI variables (see SetVariable()) or capsules (see UpdateCapsule()).

### 36.1.4 Security Considerations

Since the current profile details a number of security-related privileges, it is important that the User Identity Manager and User Credential Providers and the environment in which they execute are trusted.

This includes:

- Protecting the storage area where these drivers are stored
- Protecting the means by which these drivers are selected.
- Protecting the execution environment of these drivers from unverified drivers.
- The data structures used by these drivers should not be corrupted by unauthorized drivers while they are still being used.

In many cases, the User Identity Manager, the User Credential drivers and the on-board drivers are located in a protected location (e.g. a write-protected flash device) and the platform policy for these locations allows them to be trusted.

However, other drivers may be loaded from unprotected location or may be loaded from devices (such as PCI cards) or a hard drive which are easily replaced. Therefore, all drivers loaded prior to the User Identity Manager should be verified. No unverified drivers or applications should be allowed to execute while decisions based on the current user policy are still being made.

For example, either the default platform policy must successfully be able to verify drivers listed in the $Driver## load options, or else the user must be identified prior to processing these drivers. Otherwise, the drivers’ execution should be deferred. If the user profile is changed through a subsequent call to Identify() or through dynamic authentication, the $Driver## options may not be processed again.

In systems where the user profile database and current user profile can be protected from corruption, the user profile database is closed when the system signals the event EFI_EXIT_BOOT_SERVICES_EVENT_GUID. In systems where the user profile database and current user profile cannot be protected from corruption, the user profile database is closed when the system signals the event EFI_READY_TO_BOOT_EVENT_GUID.
Fig. 36.2: User Identity Manager
36.1.5 Deferred Execution

The platform may need to defer the execution of an image because of security considerations. For example, see Load-Image(). Information about the images which are not executed because of security considerations may be recorded and then reported by installing an instance of the EFI_DEFERRED_IMAGE_LOAD_PROTOCOL (see Deferred Image Load Protocol). There may be more than one producer of the protocol.

The firmware’s boot manager may use the instances of this protocol in order to automatically load drivers whose execution was deferred because of inadequate privileges once the current user profile contains adequate security privileges.

This boot manager can reevaluate the deferred images each time that the event EFI_EVENT_GROUP_USER_IDENTITY_CHANGED is signaled.

Images which have been loaded may not be unloaded when the current user profile is changed, even if the new user profile would have prevented that driver from being loaded.

36.2 User Identification Process

This section describes the typical initialization steps required for the user identification process.

36.2.1 User Identification Process

1. The User Identity Manager is launched. This driver reads all of the user profiles from the user profile database, sets the default user profile as the current profile, and installs an instance of the EFI_USER_MANAGER_PROTOCOL.

2. Each credential provider driver registers their user-interface related forms and installs an instance of the EFI_USER_CREDENTIAL2_PROTOCOL.

3. The User Identity Manager’s Identify() function is called to select the current user.

4. The User Identity Manager enumerates all of the User Credential Providers required by the User Identification Policy.

   a. Select the User Credential Provider which returns Default = TRUE from the Default() function. If more than one return TRUE or none return TRUE, choose a default based on implementation-specific criteria (last-logged-on, etc.)

   b. If that credential provider also returns AutoLogon = TRUE from the Default() function, then call User(). If no error was returned and a user profile with the specified user identifier exists, select the specified user profile as the current user profile and jump to step 9.

5. The User Identity Manager enumerates all of the User Credential Providers required by the User Identification Policy:

   a. Call the Title() and (optionally) the Tile() function to retrieve the text and image indicated for each User Credential Provider.

   b. Call the Form() function to retrieve the form indicated for each User Credential Provider.
c. Create the user interface to allow the user to select between the different User Credential Providers.

d. Highlight the default User Credential Provider, as specified in step 4.a.

6. If the user selects one of the User Credential Providers, call Select(). If AutoLogon = TRUE on return, then call User(). If no error was returned and a user profile with the specified user identifier exists, select the specified user profile as the current user profile and jump to step 9.

7. Interact with the user. Regular interaction can occur using the Callback() functions. If another User Credential Provider is selected then Deselect() is called for the current User Credential Provider and Select() is called for the newly selected User Credential Provider.

8. If the user presses OK then the User Manager will saved settings using the EFI Configuration Access protocol. Then it will call the User() function of each credential provider. If it returns successfully and one of the user policies evaluates to TRUE, then select the specified user profile as the current user profile and go to step 9. Otherwise display an error and go back.

9. Go through all of the credential providers using GetNextInfo() and GetInfo() and add the information to the current user profile.

10. Exit

36.2.2 Changing The Current User Profile

This section describes the typical actions taken when the current user profile is changed.

1. If there was already a valid current user profile, then all records marked as private in that profile are no longer available.

2. All records marked as private in the new user profile will be available.

3. The handle of the current user profile is changed.

4. An event with the GUID EFI_EVENT_GROUP_USER_IDENTITY_CHANGED is signaled to indicate that the current user profile has been changed.

36.2.3 Ready To Boot

Before the boot manager is read to pass control to the boot option and signals the EFI_EVENT_GROUP_READY_TO_BOOT event group, the User Identity Manager will publish the current user profile into the EFI System Configuration Table with the EFI_USER_MANAGER_PROTOCOL_GUID. The format is described in the User Information Table (User Information Table). It will also save all non-volatile profile information.

User Credential drivers with non-volatile storage should also store non-volatile credential information which has changed.
36.3 Code Definitions

36.3.1 User Manager Protocol

36.3.1.1 EFI_USER_MANAGER_PROTOCOL

Summary
Reports information about a user.

GUID

```c
#define EFI_USER_MANAGER_PROTOCOL_GUID
\{
  0x6fd5b00c, 0xd426, 0x4283,
\{
  0x98, 0x87, 0x6c, 0xf5, 0xcf, 0x1c, 0xb1, 0xfe
\};
```

Protocol Interface Structure

```c
typedef struct _EFI_USER_MANAGER_PROTOCOL {
  EFI_USER_PROFILE_CREATE Create;
  EFI_USER_PROFILE_DELETE Delete;
  EFI_USER_PROFILE_GET_NEXT GetNext;
  EFI_USER_PROFILE_CURRENT Current;
  EFI_USER_PROFILE_IDENTIFY Identify;
  EFI_USER_PROFILE_NOTIFY Notify;
  EFI_USER_PROFILE_GET_INFO GetInfo;
  EFI_USER_PROFILE_SET_INFO SetInfo;
  EFI_USER_PROFILE_DELETE_INFO DeleteInfo;
  EFI_USER_PROFILE_GET_NEXT_INFO GetNextInfo;
} EFI_USER_MANAGER_PROTOCOL;
```

Parameters

Create
Create a new user profile.

Delete
Delete an existing user profile.

GetNext
Cycle through all user profiles.

Current
Return the current user profile.

Identify
Identify a user and set the current user profile using credentials.

Find
Find a user by a piece of user information.

Notify
Notify the user manager driver that credential information has changed.

GetInfo
Return information from a user profile.
SetInfo
Change information in a user profile.

DeleteInfo
Delete information from a user profile.

GetNextInfo
Cycle through all information from a user profile.

Description
This protocol manages user profiles.

36.3.1.2 EFI_USER_MANAGER_PROTOCOL.Create()

Summary
Create a new user profile.

Prototype

```
typedef
EFI_STATUS
(EIFIAPI *EFI_USER_PROFILE_CREATE) (  
  IN CONST EFI_USER_MANAGER_PROTOCOL *This,
  OUT EFI_USER_PROFILE_HANDLE *User
);
```

Parameters

This
Points to this instance of the EFI_USER_MANAGER_PROTOCOL.

User
On return, points to the new user profile handle. The user profile handle is unique only during this boot.

Description
This function creates a new user profile with only a new user identifier attached and returns its handle. The user profile is non-volatile, but the handle User can change across reboots.

If the current user profile does not permit creation of new user profiles then EFI_ACCESS_DENIED will be returned.
If creation of new user profiles is not supported, then EFI_UNSUPPORTED is returned.

Related Definitions

```
typedef VOID *EFI_USER_PROFILE_HANDLE;
```

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>User profile was successfully created.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Current user does not have sufficient permissions to create a user profile.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Creation of new user profiles is not supported.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>User is NULL.</td>
</tr>
</tbody>
</table>
36.3.1.3 EFI_USER_MANAGER_PROTOCOL.Delete()

Summary
Delete an existing user profile.

Prototype

```c
typedef
EFI_STATUS
(EEFIAPI *EFI_USER_PROFILE_DELETE) (  
    IN CONST EFI_USER_MANAGER_PROTOCOL *This,
    IN EFI_USER_PROFILE_HANDLE User
);
```

Parameters

This
Points to this instance of the EFI_USER_MANAGER_PROTOCOL.

User
User profile handle. Type EFI_USER_PROFILE_HANDLE is defined in Create().

Description
Delete an existing user profile. If the current user profile does not permit deletion of user profiles then EFI_ACCESS_DENIED will be returned. If there is only a single user profile then EFI_ACCESS_DENIED will be returned. If deletion of user profiles is not supported, then EFI_UNSUPPORTED will be returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>User profile was successfully deleted.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Current user does not have sufficient permissions to delete a user profile or there is only one user profile.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Deletion of new user profiles is not supported.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>User does not refer to a valid user profile.</td>
</tr>
</tbody>
</table>

36.3.1.4 EFI_USER_MANAGER_PROTOCOL.GetNext()

Summary
Enumerate all of the enrolled users on the platform.

Prototype

```c
typedef
EFI_STATUS
(EEFIAPI *EFI_USER_PROFILE_GET_NEXT) (  
    IN CONST EFI_USER_MANAGER_PROTOCOL *This,
    IN OUT EFI_USER_PROFILE_HANDLE *User
);
```

Parameters

This
Points to the instance of this EFI_USER_MANAGER_PROTOCOL.

36.3. Code Definitions
User
On entry, points to the previous user profile handle or NULL to start enumeration. On exit, points to the next user profile handle or NULL if there are no more user profiles.

Description
This function returns the next enrolled user profile. To retrieve the first user profile handle, point User at a NULL. Each subsequent call will retrieve another user profile handle until there are no more, at which point User will point to NULL.

NOTE: There is always at least one user profile.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Next enrolled user profile successfully returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>User is NULL.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Next enrolled user profile was not successfully returned.</td>
</tr>
</tbody>
</table>

### 36.3.1.5 EFI_USER_MANAGER_PROTOCOL.Current()

Summary
Return the current user profile handle.

Prototype

```c
typedef EFI_STATUS
(EIFIAPIC *EFI_USER_PROFILE_CURRENT)(
    IN CONST EFI_USER_MANAGER_PROTOCOL *This,
    OUT EFI_USER_PROFILE_HANDLE *CurrentUser
);
```

Parameters

This
Points to this instance of the EFI_USER_MANAGER_PROTOCOL.

CurrentUser
On return, points to the current user profile handle.

Description
This function returns the current user profile handle.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Current user profile handle returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>CurrentUser is NULL.</td>
</tr>
</tbody>
</table>
36.3.1.6 EFI_USER_MANAGER_PROTOCOL.Identify()

Summary
Identify a user.

Prototype

```
typedef EFI_STATUS (EFIAPI *EFI_USER_IDENTIFY) (  
    IN CONST EFI_USER_MANAGER_PROTOCOL *This,  
    OUT EFI_USER_PROFILE_HANDLE *User  
);```

Parameters

This
Points to the instance of the EFI_USER_MANAGER_PROTOCOL.

User
On return, points to the user profile handle for the current user profile.

Description
Identify the user and, if authenticated, returns the user handle and changes the current user profile.

All user information marked as private in a previously selected profile is no longer available for inspection.

Whenever the current user profile is changed then the an event with the GUID EFI_EVENT_GROUP_USER_PROFILE_CHANGED is signaled.

The function can only be called at TPL_APPLICATION.

Related Definitions

```
#define EFI_EVENT_GROUP_USER_PROFILE_CHANGED  
   { 0xbaf1e6de, 0x209e, 0x4adb,  
     { 0x8d, 0x96, 0xfd, 0x8b, 0x71, 0xf3, 0xf6, 0x83 } }
```

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>User was successfully identified.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>User is NULL.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>User was not successfully identified.</td>
</tr>
</tbody>
</table>

36.3.1.7 EFI_USER_MANAGER_PROTOCOL.Find()

Summary
Find a user using a user information record.

Prototype

```
typedef EFI_STATUS (EFIAPI *EFI_USER_PROFILE_FIND)(  
    IN CONST EFI_USER_MANAGER_PROTOCOL *This,  
);```

(continues on next page)
IN OUT EFI_USERPROFILEHANDLE *User,  
IN OUT EFI_USERINFOHANDLE *UserInfo OPTIONAL,  
IN CONST EFI_USERINFO *Info,  
IN UINTN InfoSize  
);

Parameters

This  
Points to this instance of the EFI_USER_MANAGER_PROTOCOL.

User  
On entry, points to the previously returned user profile handle or NULL to start searching with the first user profile. On return, points to the user profile handle or NULL if not found.

UserInfo  
On entry, points to the previously returned user information handle or NULL to start searching with the first. On return, points to the user information handle of the user information record or NULL if not found. Can be NULL, in which case only one user information record per user can be returned. Type EFI_USERINFOHANDLE is defined in “Related Definitions” below.

Info  
Points to the buffer containing the user information to be compared to the user information record. If the user information record data is empty, then only the user information record type is compared.

If InfoSize is 0, then the user information record data must be empty.

InfoSize  
The size of Info, in bytes.

Description

This function searches all user profiles for the specified user information record. The search starts with the user information record handle following UserInfo and continues until either the information is found or there are no more user profiles.

A match occurs when the Info.InfoType field matches the user information record type and the user information record data matches a portion of Info.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>User information was found. User points to the user profile handle and UserInfo points to the user information handle.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>User information was not found. User points to NULL and UserInfo points to NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>User is NULL. Or Info is NULL.</td>
</tr>
</tbody>
</table>

Related Definitions

typedef VOID *EFI_USERINFOHANDLE;
36.3.1.8 EFI_USER_MANAGER_PROTOCOL.Notify()

Summary
Called by credential provider to notify of information change.

Prototype

```c
typedef EFI_STATUS
  (EFIAPIC *EFI_USER_PROFILE_NOTIFY)(
     IN CONST EFI_USER_MANAGER_PROTOCOL *This,
     IN EFI_HANDLE Changed
  );
```

Parameters

This
Points to this instance of the EFI_USER_MANAGER_PROTOCOL.

Changed
Handle on which is installed an instance of the EFI_USER_CREDENTIAL2_PROTOCOL where the user has changed.

Description
This function allows the credential provider to notify the User Identity Manager when user status has changed.

If the User Identity Manager doesn’t support asynchronous changes in credentials, then this function should return EFI_UNSUPPORTED.

If current user does not exist, and the credential provider can identify a user, then make the user to be current user and signal the EFI_EVENT_GROUP_USER_PROFILE_CHANGED event.

If current user already exists, and the credential provider can identify another user, then switch current user to the newly identified user, and signal the EFI_EVENT_GROUP_USER_PROFILE_CHANGED event.

If current user was identified by this credential provider and now the credential provider cannot identify current user, then logout current user and signal the EFI_EVENT_GROUP_USER_PROFILE_CHANGED event.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The User Identity Manager has handled the notification.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>The function was called while the specified credential provider was not selected.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The User Identity Manager doesn’t support asynchronous notifications.</td>
</tr>
</tbody>
</table>

36.3.1.9 EFI_USER_MANAGER_PROTOCOL.GetInfo()

Summary
Return information attached to the user.

Prototype

```c
typedef EFI_STATUS
  (EFIAPIC *EFI_USER_PROFILE_GET_INFO)(
     IN CONST EFI_USER_MANAGER_PROTOCOL *This,
     (continues on next page)
```
Parameters

This

Points to this instance of the `EFI_USER_MANAGER_PROTOCOL`.

User

Handle of the user whose profile will be retrieved.

UserInfo

Handle of the user information data record. Type `EFI_USER_INFO_HANDLE` is defined in `GetInfo()`.

Info

On entry, points to a buffer of at least `*InfoSize` bytes. On exit, holds the user information. If the buffer is too small to hold the information, then `EFI_BUFFER_TOO_SMALL` is returned and `InfoSize` is updated to contain the number of bytes actually required. Type `EFI_USER_INFO` is described in “Related Definitions” below.

InfoSize

On entry, points to the size of `Info`. On return, points to the size of the user information.

Description

This function returns user information. The format of the information is described in User Information. The function may return `EFI_ACCESS_DENIED` if the information is marked private and the handle specified by `User` is not the current user profile. The function may return `EFI_ACCESS_DENIED` if the information is marked protected and the information is associated with a credential provider for which the user has not been authenticated.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>Information returned successfully.</td>
</tr>
<tr>
<td><code>EFI_ACCESS_DENIED</code></td>
<td>The information about the specified user cannot be accessed by the current user.</td>
</tr>
<tr>
<td><code>EFI_BUFFER_TOO_SMALL</code></td>
<td>The number of bytes specified by <code>*InfoSize</code> is too small to hold the returned data. The actual size required is returned in <code>*InfoSize</code>.</td>
</tr>
<tr>
<td><code>EFI_NOT_FOUND</code></td>
<td><code>User</code> does not refer to a valid user profile or <code>UserInfo</code> does not refer to a valid user info handle.</td>
</tr>
<tr>
<td><code>EFIINVALID_PARAMETER</code></td>
<td><code>Info</code> is <strong>NULL</strong> or <code>InfoSize</code> is <strong>NULL</strong></td>
</tr>
</tbody>
</table>

Related Definitions

```c
typedef struct {
    EFI_GUID Credential;
    UINT8 InfoType;
    UINT8 Reserved1;
    EFI_USER_INFO_ATTRIBS InfoAttribs;
    UINT32 InfoSize;
} EFI_USER_INFO;
```

Credential

The user credential identifier associated with this user information or else Nil if the information is not associated with any specific credential.
InfoType
The type of user information. See EFI_USER_INFO_x_RECORD in User Information for a description of the different types of user information.

Reserved1
Must be set to 0.

InfoAttribs
The attributes of the user profile information.

InfoSize
The size of the user information, in bytes, including this header.

```c
typedef UINT16 EFI_USER_INFO_ATTRIBS;

#define EFI_USER_INFO_STORAGE 0x000F
#define EFI_USER_INFO_STORAGE_VOLATILE 0x0000
#define EFI_USER_INFO_STORAGE_CREDENTIAL_NV 0x0001
#define EFI_USER_INFO_STORAGE_PLATFORM_NV 0x0002
#define EFI_USER_INFO_ACCESS 0x0070
#define EFI_USER_INFO_PUBLIC 0x0010
#define EFI_USER_INFO_PRIVATE 0x0020
#define EFI_USER_INFO_PROTECTED 0x0030
#define EFI_USER_INFO_EXCLUSIVE 0x0080
```

The EFI_USER_INFO_STORAGE_x values describe how the user information should be stored. If EFI_USER_INFO_STORAGE_VOLATILE is specified, then the user profile information will be lost after a reboot. If EFI_USER_INFO_STORAGE_CREDENTIAL_NV is specified, then the information will be stored by the driver which created the handle Credential. If USER_INFO_STORAGE_PLATFORM_NV is specified, then the information will be stored by the User Identity Manager in platform non-volatile storage.

There are three levels of access to information associated with the user profile: public, private or protected. If EFI_USER_INFO_PUBLIC is specified, then the user profile information is available always. If EFI_USER_INFO_PRIVATE is specified, then the user profile information is only available if the user has been authenticated (whether or not they are the current user). If EFI_USER_INFO_PROTECTED is specified, then the user profile information is only available if the user has been authenticated and is the current user.

If EFI_USER_INFO_EXCLUSIVE is specified then there can only be one user information record of this type in the user profile. Attempts to use SetInfo() will fail.

### 36.3.1.10 EFI_USER_MANAGER_PROTOCOL.SetInfo()

**Summary**
Add or update user information.

**Prototype**
```c
typedef EFI_STATUS
(EIFIAPI *EFI_USERPROFILE_SET_INFO) (  
    IN  CONST EFI_USER_MANAGER_PROTOCOL    *This,
    IN  EFI_USERPROFILE_HANDLE            User,
    IN  OUT EFI_USERINFO_HANDLE           *UserInfo,
    IN  CONST EFI_USERINFO                *Info,
);```
Parameters

This
Points to this instance of the EFI_USER_MANAGER_PROTOCOL.

User
Handle of the user whose profile will be changed.

UserInfo
On entry, points to the handle of the user information record to change or NULL if the user information should be added to the user profile. On exit, points to the handle of the user credential information record.

Info
Points to the user information. See EFI_USER_INFO for more information.

InfoSize
The size of Info, in bytes.

Description
This function changes user information. If NULL is pointed to by UserInfo, then a new user information record is created and its handle is returned in UserInfo. Otherwise, the existing one is replaced.

If EFI_USER_INFO_IDENTITY_POLICY_RECORD is changed, it is the caller’s responsibility to keep it to be synced with the information on credential providers.

If EFI_USER_INFO_EXCLUSIVE is specified in Info and a user information record of the same type already exists in the user profile, then EFI_ACCESS_DENIED will be returned and UserInfo will point to the handle of the existing record.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>User profile information was successfully changed/added.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The record is exclusive.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The current user does not have permission to change the specified user profile or user information record.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>User does not refer to a valid user profile or UserInfo does not refer to a valid user info handle.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Info is NULL or InfoSize is NULL</td>
</tr>
</tbody>
</table>

36.3.1.11 EFI_USER_MANAGER_PROTOCOL.DeleteInfo()

Summary
Delete user information.

Prototype

typedef

EFI_STATUS
(EIFIAPI *EFI_USER_PROFILE_DELETE_INFO) (  
    IN CONST EFI_USER_MANAGER_PROTOCOL *This,  
    IN EFI_USER_PROFILE_HANDLE User,  
);
IN  EFI_USER_INFO_HANDLE  UserInfo  
);

Parameters

This
Points to this instance of the EFI_USER_MANAGER_PROTOCOL.

User
Handle of the user whose information will be deleted.

UserInfo
Handle of the user information to remove.

Description
Delete the user information attached to the user profile specified by the UserInfo.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code Definition</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>User information deleted successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>User information record UserInfo does not exist in the user profile.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The current user does not have permission to delete this user information.</td>
</tr>
</tbody>
</table>

36.3.1.12 EFI_USER_MANAGER_PROTOCOL.GetNextInfo()

Summary
Enumerate all of the enrolled users on the platform.

Prototype

typedef
EFI_STATUS
(EIFIAP1  *EFI_USER_PROFILE_GET_NEXT_INFO)(
    IN  CONST  EFI_USER_MANAGER_PROTOCOL  *This,
    IN  EFI_USER_PROFILE_HANDLE  User,
    IN  OUT  EFI_USER_INFO_HANDLE  UserInfo
);

Parameters

This
Points to the instance of this EFI_USER_MANAGER_PROTOCOL.

User
Handle of the user whose information will be enumerated

UserInfo
On entry, points to the previous user information handle or NULL to start enumeration. On exit, points to the next user information handle or NULL if there is no more user information.

Description
This function returns the next user information record. To retrieve the first user information record handle, point UserInfo at a NULL. Each subsequent call will retrieve another user information record handle until there are no more, at which point UserInfo will point to NULL.

Status Codes Returned
### 36.3.2 Credential Provider Protocols

#### 36.3.2.1 EFI_USER_CREDENTIAL2_PROTOCOL

**Summary**

Provide support for a single class of credentials

**GUID**

```
#define EFI_USER_CREDENTIAL2_PROTOCOL_GUID \
{ 0xe98adb03, 0xb8b9, 0x4af8, \ 
{ 0xba, 0x20, 0x26, 0xe9, 0x11, 0x4c, 0xbc, 0xe5 } }
```

**Prototype**

```c
typedef struct _EFI_USER_CREDENTIAL2_PROTOCOL {
    EFI_GUID Identifier;
    EFI_GUID Type;
    EFI_CREDENTIAL_ENROLL Enroll;
    EFI_CREDENTIAL_FORM Form;
    EFI_CREDENTIAL_TILE Tile;
    EFI_CREDENTIAL_TITLE Title;
    EFI_CREDENTIAL_USER User;
    EFI_CREDENTIAL_SELECT Select;
    EFI_CREDENTIAL_DESELECT Deselect;
    EFI_CREDENTIAL_DEFAULT Default;
    EFI_CREDENTIAL_GET_INFO GetInfo;
    EFI_CREDENTIAL_GET_NEXT_INFO GetNextInfo;
    EFI_CREDENTIAL_CAPABILITIES Capabilities;
    EFI_CREDENTIAL_DELETE Delete;
} EFI_USER_CREDENTIAL2_PROTOCOL;
```

**Parameters**

**Identifier**

Uniquely identifies this credential provider.

**Type**

Identifies this class of User Credential Provider. See `EFI_CREDENTIAL_CLASS_x` in “Related Definitions” below.

**Enroll**

Enroll a user using this credential provider.

**Form**

Return the form set and form identifier for the form.

**Tile**

Returns an optional bitmap image used to identify this credential provider.
Title
Returns a string used to identify this credential provider.

User
Returns the user profile identifier ascertained by using this credential.

Select
Called when a credential provider is selected.

Deselect
Called when a credential provider is deselected.

Default
Returns whether the credential provider can provide the default credential.

GetInfo
Return user information provided by the credential provider.

GetNextInfo
Cycle through all user information available from the credential provider.

Capabilities
Bitmask which describes the capabilities supported by the credential provider. Type 
EFI_CREDENTIAL_CAPABILITIES is defined in “Related Definitions” below.

Delete
Delete a user on this credential provider.

Description
Attached to a device handle, this protocol identifies a single means of identifying the user.

If EFI_CREDENTIAL_CAPABILITIES_ENROLL is specified, then this credential provider supports the ability to enroll new user identification information using the Enroll() function.

Related Definitions

#define EFI_USER_CREDENTIAL_CLASS_UNKNOWN
{ 0x5cf32e68, 0x7660, 0x449b, 
 { 0x80, 0xe6, 0x7e, 0xa3, 0x6e, 0x3, 0xf6, 0xa8 } };

#define EFI_USER_CREDENTIAL_CLASS_PASSWORD
{ 0xf8e5058c, 0xccb6, 0x4714, 
 { 0xb2, 0x20, 0x3f, 0x7e, 0x3a, 0x64, 0xb, 0xd1 } };

#define EFI_USER_CREDENTIAL_CLASS_SMART_CARD
{ 0x5f03ba33, 0x8c6b, 0x4c24, 
 { 0xaa, 0xe2, 0x14, 0xa2, 0x65, 0x7b, 0xd4, 0x54 } };

#define EFI_USER_CREDENTIAL_CLASS_FINGERPRINT
{ 0x32cba21f, 0xf308, 0x4cbc, 
 { 0x9a, 0xb5, 0xf5, 0xa3, 0x69, 0x9f, 0x4, 0x4a } };

#define EFI_USER_CREDENTIAL_CLASS_HANDPRINT
{ 0x5917ef16, 0xf723, 0x4bb9, 
 { 0xa6, 0xb4, 0xd8, 0xc5, 0x32, 0xf4, 0xd8, 0xb5 } };

#define EFI_USER_CREDENTIAL_CLASS_SECURE_CARD
{ 0x8a6b4a83, 0x42fe, 0x45d2, 

typedef UINT64 EFI_CREDENTIAL_CAPABILITIES;
#define EFI_CREDENTIAL_CAPABILITIES_ENROLL 0x0000000000000001

36.3.2.2 EFI_USER_CREDENTIAL2_PROTOCOL.Enroll()

Summary
Enroll a user on a credential provider.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_CREDENTIAL2_ENROLL)(
    IN CONST EFI_USER_CREDENTIAL2_PROTOCOL *This,
    IN EFI_USER_PROFILE_HANDLE User
);

Parameters
This
Points to this instance of the EFI_USER_CREDENTIAL2_PROTOCOL.

User
The user profile to enroll.

Description
This function enrolls a user on this credential provider. If the user exists on this credential provider, update the user information on this credential provider; otherwise add the user information on credential provider.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>User profile was successfully enrolled</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Current user profile does not permit enrollment on the user profile handle.</td>
</tr>
<tr>
<td></td>
<td>Either the user profile cannot enroll on any user profile or cannot enroll on</td>
</tr>
<tr>
<td></td>
<td>a user profile other than the current user profile.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This credential provider does not support enrollment in the pre-OS.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The new credential could not be created because of a device error.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>User does not refer to a valid user profile handle.</td>
</tr>
</tbody>
</table>

36.3.2.3 EFI_USER_CREDENTIAL2_PROTOCOL.Form()

Summary
Returns the user interface information used during user identification.

Prototype
typedef
EFI_STATUS
(EFIAPI *EFI_CREDENTIAL_FORM)(
    IN CONST EFI_USER_CREDENTIAL2_PROTOCOL *This,
    OUT EFI_HII_HANDLE *Hii,
    OUT EFI_GUID *FormSetId,
    OUT EFI_FORM_ID *FormId
);

Parameters

This
Points to this instance of the EFI_USER_CREDENTIAL2_PROTOCOL.

Hii
On return, holds the HII database handle. Type EFI_HII_HANDLE is defined in EFI_HII_DATABASE_PROTOCOL.NewPackageList() in the Packages section.

FormSetId
On return, holds the identifier of the form set which contains the form used during user identification.

FormId
On return, holds the identifier of the form used during user identification.

Description
This function returns information about the form used when interacting with the user during user identification. The form is the first enabled form in the form-set class EFI_HII_USER_CREDENTIAL_FORMSET_GUID installed on the HII handle HiiHandle. If the user credential provider does not require a form to identify the user, then this function should return EFI_NOT_FOUND.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Form returned successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Form not returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Hii is NULL or FormSetId is NULL or FormId is NULL</td>
</tr>
</tbody>
</table>

36.3.2.4 EFI_USER_CREDENTIAL2_PROTOCOL.Tile()

Summary
Returns bitmap used to describe the credential provider type.

Prototype

typedef
EFI_STATUS
(EFIAPI *EFI_CREDENTIAL_TILE)(
    IN CONST EFI_USER_CREDENTIAL2_PROTOCOL *This,
    IN OUT UINTN *Width,
    IN OUT UINTN *Height,
    IN OUT EFI_HII_HANDLE *Hii,
    OUT EFI_IMAGE_ID *Image
);

Parameters
This
   Points to this instance of the EFI_USER_CREDENTIAL2_PROTOCOL.

Width
   On entry, points to the desired bitmap width. If NULL then no bitmap information will be returned. On exit, points to the width of the bitmap returned.

Height
   On entry, points to the desired bitmap height. If NULL then no bitmap information will be returned. On exit, points to the height of the bitmap returned.

Hii
   On return, holds the HII database handle. Type EFI_HII_HANDLE is defined in EFI_HII_DATABASE_PROTOCOL.NewPackageList() in the Packages section.

Image
   On return, holds the HII image identifier. Type EFI_IMAGE_ID is defined in this specification, Image Protocol.

Description
This optional function returns a bitmap which is less than or equal to the number of pixels specified by Width and Height. If no such bitmap exists, then EFI_NOT_FOUND is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Image identifier returned successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Image identifier not returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Hii is NULL or Image is NULL.</td>
</tr>
</tbody>
</table>

36.3.2.5 EFI_USER_CREDENTIAL2_PROTOCOL.Title()

Summary
Returns string used to describe the credential provider type.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_CREDENTIAL_TITLE)(
   IN CONST EFI_USER_CREDENTIAL2_PROTOCOL *This,
   OUT EFI_HII_HANDLE *Hii,
   OUT EFI_STRING_ID *String
);
```

Parameters

This
   Points to this instance of the EFI_USER_CREDENTIAL2_PROTOCOL.

Hii
   On return, holds the HII database handle. Type EFI_HII_HANDLE is defined in EFI_HII_DATABASE_PROTOCOL.NewPackageList() in the Packages section.

String
   On return, holds the HII string identifier. Type EFI_STRING_ID is defined in EFI_IFR_OP_HEADER.
Description
This function returns a string which describes the credential provider. If no such string exists, then EFI_NOT_FOUND is returned.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>String identifier returned successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>String identifier not returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>$hi$ is NULL or $string$ is NULL.</td>
</tr>
</tbody>
</table>

36.3.2.6 EFI_USER_CREDENTIAL2_PROTOCOL.User()

Summary
Return the user identifier associated with the currently authenticated user.

Prototype

define EFI_STATUS (EFIAPI *EFI_CREDENTIAL_USER)(
    IN CONST EFI_USER_CREDENTIAL2_PROTOCOL *This,
    IN EFI_USER_PROFILE_HANDLE User,
    OUT EFI_USER_INFO_IDENTIFIER *Identifier
);

Parameters

This
Points to this instance of the EFI_USER_CREDENTIAL2_PROTOCOL.

User
The user profile handle of the user profile currently being considered by the user identity manager. If NULL, then no user profile is currently under consideration.

Identifier
On return, points to the user identifier. Type EFI_USER_INFO_IDENTIFIER is defined in “Related Definitions” below.

Description
This function returns the user identifier of the user authenticated by this credential provider. This function is called after the credential-related information has been submitted on a form OR after a call to Default() has returned that this credential is ready to log on.

This function can return one of five possible responses:

- If no user profile can yet be identified, then EFI_NOT_READY is returned.
- If the user has been locked out, then EFI_ACCESS_DENIED is returned.
- If the user specified by $User$ is identified, then Identifier returns with the user identifier associated with that handle and EFI_SUCCESS is returned.
- If Identifier is NULL, then EFI_INVALID_PARAMETER is returned.
- If specified $User$ does not refer to a valid user profile, then EFI_NOT_FOUND is returned.
Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>User identifier returned successfully.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>No user identifier can be returned.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>The user has been locked out of this user credential.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>User is not NULL, and the specified user handle can’t be found in user profile database</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Identifier is NULL.</td>
</tr>
</tbody>
</table>

36.3.2.7 EFI_USER_CREDENTIAL2_PROTOCOL.Select()

Summary
Indicate that user interface interaction has begun for the specified credential.

Prototype

typedef EFI_STATUS
(EFIAPIC *EFI_CREDENTIAL_SELECT)(
    IN CONST EFI_USER_CREDENTIAL2_PROTOCOL *This,
    OUT EFI_CREDENTIAL_LOGON_FLAGS *AutoLogon
);

Parameters

This
Points to this instance of the EFI_USER_CREDENTIAL2_PROTOCOL.

AutoLogon
On return, points to the credential provider’s capabilities after the credential provider has been selected by the user. Type EFI_CREDENTIAL_LOGON_FLAGS is defined in “Related Definitions” below.

Description
This function is called when a credential provider is selected by the user. If AutoLogon returns FALSE, then the user interface will be constructed by the User Identity Manager.

Related Definitions

typedef UINT32 EFI_CREDENTIAL_LOGON_FLAGS;

#define EFI_CREDENTIAL_LOGON_FLAG_AUTO 0x00000001
#define EFI_CREDENTIAL_LOGON_FLAG_DEFAULT 0x00000002

If EFI_CREDENTIAL_LOGON_FLAG_AUTO is set, then the User Identity Manager may use this as a hint to try logging on immediately. If not set, then the User Identity Manager may use this as an indication to wait for the user to submit the information.

If EFI_CREDENTIAL_LOGON_FLAG_DEFAULT is set, then the User Identity Manager may use this as a hint to use this credential provider as the default credential provider. If more than one credential provider returns with this set, then the selection is implementation specific. If EFI_CREDENTIAL_LOGON_FLAG_DEFAULT is set and EFI_CREDENTIAL_LOGON_FLAG_AUTO is set then the User Identity Manager may use this as a hint to log the user on immediately.

Status Codes Returned
### 36.3.2.8 EFI_USER_CREDENTIAL2_PROTOCOL.Deselect()  

**Summary**  
Indicate that user interface interaction has ended for the specified credential.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_CREDENTIAL_DESELECT)(
  IN CONST EFI_USER_CREDENTIAL2_PROTOCOL *This
);
```

**Parameters**

- **This**  
  Points to this instance of the `EFI_USER_CREDENTIAL2_PROTOCOL`.

**Description**

This function is called when a credential provider is deselected by the user.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Credential provider successfully selected.</td>
</tr>
</tbody>
</table>

### 36.3.2.9 EFI_USER_CREDENTIAL2_PROTOCOL.Default()  

**Summary**

Return the default logon behavior for this user credential.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_CREDENTIAL_DEFAULT)(
  IN CONST EFI_USER_CREDENTIAL2_PROTOCOL *This,
  OUT EFI_CREDENTIAL_LOGON_FLAGS *AutoLogon
);
```

**Parameters**

- **This**  
  Points to this instance of the `EFI_USER_CREDENTIAL2_PROTOCOL`.

- **AutoLogon**  
  On return, holds whether the credential provider should be used by default to automatically logon the user. Type `EFI_CREDENTIAL_LOGON_FLAGS` is defined in `EFI_USER_CREDENTIAL2_PROTOCOL.Select()`.

**Description**

This function reports the default login behavior regarding this credential provider.
Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Default information successfully returned.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>AutoLogon is NULL</td>
</tr>
</tbody>
</table>

36.3.2.10 EFI_USER_CREDENTIAL2_PROTOCOL.GetInfo()

Summary

Return information attached to the credential provider.

Prototype

```c
typedef
EFI_STATUS
(EFIAPIC *EFI_CREDENTIAL_GET_INFO)(
    IN CONST EFI_USER_CREDENTIAL2_PROTOCOL *This,
    IN EFI_USER_INFO_HANDLE UserInfo,
    OUT EFI_USER_INFO *Info,
    IN OUT UINTN *InfoSize
);
```

Parameters

This

Points to this instance of the EFI_USER_CREDENTIAL2_PROTOCOL.

UserInfo

Handle of the user information data record. Type EFI_USER_INFO_HANDLE is defined in GetInfo().

Info

On entry, points to a buffer of at least **InfoSize* bytes. On exit, holds the user information. If the buffer is too small to hold the information, then EFI_BUFFER_TOO_SMALL is returned and InfoSize is updated to contain the number of bytes actually required. Type EFI_USER_INFO is described in “Related Definitions” below.

InfoSize

On entry, points to the size of Info. On return, points to the size of the user information.

Description

This function returns user information.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Information returned successfully.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The size specified by InfoSize is too small to hold all of the user information. The size required is returned in * InfoSize.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The specified UserInfo does not refer to a valid user info handle</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Info is NULL or InfoSize is NULL</td>
</tr>
</tbody>
</table>
### 36.3.2.11 EFI_USER_CREDENTIAL2_PROTOCOL.GetNextInfo()

**Summary**

Enumerate all of the user information records on the credential provider.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_USER_CREDENTIAL_GET_NEXT_INFO)(
    IN CONST EFI_USER_CREDENTIAL2_PROTOCOL *This,
    IN OUT EFI_USER_INFO_HANDLE *UserInfo
);
```

**Parameters**

- **This**
  
  Points to the instance of this `EFI_USER_CREDENTIAL2_PROTOCOL`.

- **UserInfo**
  
  On entry, points to the previous user information handle or NULL to start enumeration. On exit, points to the next user information handle or NULL if there is no more user information.

**Description**

This function returns the next user information record. To retrieve the first user information record handle, point `UserInfo` to NULL. Each subsequent call will retrieve another user information record handle until there are no more, at which point `UserInfo` will point to NULL.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>User information returned.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>No more user information found.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>UserInfo</code> is NULL.</td>
</tr>
</tbody>
</table>

### 36.3.2.12 EFI_USER_CREDENTIAL2_PROTOCOL.Delete()

**Summary**

Delete a user on a credential provider.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_CREDENTIAL_DELETE)(
    IN CONST EFI_USER_CREDENTIAL2_PROTOCOL *This,
    IN EFI_USER_PROFILE_HANDLE User
);
```

**Parameters**

- **This**
  
  Points to this instance of the `EFI_USER_CREDENTIAL2_PROTOCOL`.

- **User**
  
  The user profile handle to delete.
Description

This function deletes a user on this credential provider.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>User profile was successfully deleted.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Current user profile does not permit deletion on the user profile handle. Either the user profile cannot delete on any user profile or cannot delete on a user profile other than the current user profile.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This credential provider does not support deletion in the pre-OS.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The new credential could not be deleted because of a device error.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>User does not refer to a valid user profile handle.</td>
</tr>
</tbody>
</table>

36.3.3 Deferred Image Load Protocol

36.3.3.1 EFI_DEFERRED_IMAGE_LOAD_PROTOCOL

Summary

Enumerates images whose load was deferred due to security considerations.

GUID

```c
#define EFI_DEFERRED_IMAGE_LOAD_PROTOCOL_GUID \
    { 0x15853d7c, 0x3ddf, 0x43e0, \
    { 0xa1, 0xcb, 0xeb, 0xf8, 0x5b, 0x8f, 0x87, 0x2c } };```

Protocol Interface Structure

```c
typedef struct _EFI_DEFERRED_IMAGE_LOAD_PROTOCOL {  
    EFI_DEFERRED_IMAGE_INFO GetImageInfo();  
} EFI_DEFERRED_IMAGE_LOAD_PROTOCOL;
```

Members

GetImageInfo

Return information about a single deferred image. See GetImageInfo() for more information.

Description

This protocol returns information about images whose load was denied because of security considerations. This information can be used by the Boot Manager or another agent to reevaluate the images when the current security profile has been changed, such as when the current user profile changes. There can be more than one instance of this protocol installed.
36.3.3.2 EFI_DEFERRED_IMAGE_LOAD_PROTOCOL.GetImageInfo()

Summary

Returns information about a deferred image.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_DEFERRED_IMAGE_INFO)(
  IN EFI_DEFERRED_IMAGE_LOAD_PROTOCOL *This,
  IN UINTN ImageIndex,
  OUT EFI_DEVICE_PATH_PROTOCOL **ImageDevicePath,
  OUT VOID **Image,
  OUT UINTN *ImageSize,
  OUT BOOLEAN *BootOption
);
```

Parameters

This

Points to this instance of the EFI_DEFERRED_IMAGE_LOAD_PROTOCOL.

ImageIndex

Zero-based index of the deferred index.

ImageDevicePath

On return, points to a pointer to the device path of the image. The device path should not be freed by the caller.

Image

On return, points to the first byte of the image or NULL if the image is not available. The image should not be freed by the caller unless LoadImage() has been called successfully.

ImageSize

On return, the size of the image, or 0 if the image is not available.

BootOption

On return, points to TRUE if the image was intended as a boot option or FALSE if it was not intended as a boot option.

Description

This function returns information about a single deferred image. The deferred images are numbered consecutively, starting with 0. If there is no image which corresponds to ImageIndex, then EFI_NOT_FOUND is returned. All deferred images may be returned by iteratively calling this function until EFI_NOT_FOUND is returned.

Image may be NULL and ImageSize set to 0 if the decision to defer execution was made because of the location of the executable image rather than its actual contents.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Image information returned successfully.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>ImageIndex does not refer to a valid image.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ImageDevicePath is NULL or Image is NULL or ImageSize is NULL or BootOption is NULL</td>
</tr>
</tbody>
</table>
36.4 User Information

This section describes the different user information and the format of the data. Each of the following records is prefixed with the EFI_USER_INFO structure. The format of the record is determined by the type specified by the InfoType field in the structure, as listed in the table below:

Record values and descriptions

<table>
<thead>
<tr>
<th>Name</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_USER_INFO_EMPTY_RECORD</td>
<td>0x00</td>
<td>No information.</td>
</tr>
<tr>
<td>EFI_USER_INFO_NAME_RECORD</td>
<td>0x01</td>
<td>User’s name</td>
</tr>
<tr>
<td>EFI_USER_INFO_CREATE_DATE_RECORD</td>
<td>0x02</td>
<td>Date which the user profile was created.</td>
</tr>
<tr>
<td>EFI_USER_INFO_USAGE_DATE_RECORD</td>
<td>0x03</td>
<td>Date which the user profile was last modified.</td>
</tr>
<tr>
<td>EFI_USER_INFO_USAGE_COUNT_RECORD</td>
<td>0x04</td>
<td>Number of times the credential has been used.</td>
</tr>
<tr>
<td>EFI_USER_INFO_IDENTIFIER_RECORD</td>
<td>0x05</td>
<td>User’s unique identifier *</td>
</tr>
<tr>
<td>EFI_USER_INFO_CREDENTIAL_TYPE_RECORD</td>
<td>0x06</td>
<td>Credential type.</td>
</tr>
<tr>
<td>EFI_USER_INFO_CREDENTIAL_TYPE_NAME_RECORD</td>
<td>0x07</td>
<td>Credential type name.</td>
</tr>
<tr>
<td>EFI_USER_INFO_CREDENTIAL_PROVIDER_RECORD</td>
<td>0x08</td>
<td>Credential provider</td>
</tr>
<tr>
<td>EFI_USER_INFO_CREDENTIAL_PROVIDER_NAME_RECORD</td>
<td>0x09</td>
<td>Credential provider name</td>
</tr>
<tr>
<td>EFI_USER_INFO_PKCS11_RECORD</td>
<td>0x0A</td>
<td>PKCS11 Data Object</td>
</tr>
<tr>
<td>EFI_USER_INFO_CBEFF_RECORD</td>
<td>0x0B</td>
<td>ISO 19785 (Common Biometric Exchange Formats Framework) Data Object</td>
</tr>
<tr>
<td>EFI_USER_INFO_FAR_RECORD</td>
<td>0x0C</td>
<td>How exact a match is required for biometric identification, measured in percentage.</td>
</tr>
<tr>
<td>EFI_USER_INFO_RETRY_RECORD</td>
<td>0x0D</td>
<td>Number of retries allowed during verification.</td>
</tr>
<tr>
<td>EFI_USER_INFO_ACCESS_POLICY_RECORD</td>
<td>0x0E</td>
<td>Access control information.</td>
</tr>
<tr>
<td>EFI_USER_INFO_IDENTITY_POLICY_RECORD</td>
<td>0x0F</td>
<td>User identity expression.</td>
</tr>
<tr>
<td>EFI_USER_INFO_GUID_RECORD</td>
<td>0xFF</td>
<td>Extended profile information, qualified by a GUID in the header.</td>
</tr>
</tbody>
</table>

36.4.1 EFI_USER_INFO_ACCESS_POLICY_RECORD

Summary

Provides the user’s pre-OS access rights.

Prototype

```c
#define EFI_USER_INFO_ACCESS_POLICY_RECORD 0x0E

typedef EFI_USER_INFO_ACCESS_CONTROL EFI_USER_INFO_ACCESS_POLICY;
```

Description

This structure described the access policy for the user. There can be, at most, one access policy record per credential (including NULL credential). Policy records with a credential specified means that the policy is associated specifically with the credential.

The policy is detailed in a series of encapsulated records of type EFI_USER_INFO_ACCESS_CONTROL.
Related Definitions

typedef struct {
    UINT32 Type;
    UINT32 Size;
} EFI_USER_INFO_ACCESS_CONTROL;

Type
    Specifies the type of user access control. See EFI_USER_INFO_ACCESS_x for more information.

Size
    Specifies the size of the user access control record, in bytes, including this header.

36.4.1.1 EFI_USER_INFO_ACCESS_FORBID_LOAD

Summary
    Forbids the user from booting or loading executables from the specified device path or any child device paths.

Prototype

#define EFI_USER_INFO_ACCESS_FORBID_LOAD 0x00000001

Description
    This record prohibits the user from loading any executables from zero or device paths or any child device paths. The device paths may contain a specific executable name, in which case the prohibition applies to only that executable.
    The record is a series of normal UEFI device paths (not multi-instance device paths).
    This prohibition is overridden by the EFI_USER_INFO_ACCESS_PERMIT_LOAD record.

36.4.1.2 EFI_USER_INFO_ACCESS_PERMIT_LOAD

Summary
    Permits the user from booting or loading executables from the specified device path or any child device paths.

Prototype

#define EFI_USER_INFO_ACCESS_PERMIT_LOAD 0x00000002

Description
    This record allows the user to load executables from locations specified by zero or more device paths or child paths. The device paths may contain specific executable names, in which case, the permission applies only to that executable.
    The record is a series of normal UEFI device paths (not multi-instance device paths).
    This prohibition overrides any restrictions put in place by the EFI_USER_INFO_ACCESS_FORBID_LOAD record.
36.4.1.3 EFI_USER_INFO_ACCESS_ENROLL_SELF

Summary
Presence of this record indicates that a user can update enrollment information.

Prototype
```
#define EFI_USER_INFO_ACCESS_ENROLL_SELF 0x00000003
```

Description
If this record is present, then the pre-OS environment will allow the user to initiate an update of authentication information for his/her own profile, but not other user information or other user’s information. This would allow, for example, fingerprint update or password change.

There is no data for this record.

36.4.1.4 EFI_USER_INFO_ACCESS_ENROLL_OTHERS

Summary
Presence of this record indicates that a user can enroll new users.

Prototype
```
#define EFI_USER_INFO_ACCESS_ENROLL_OTHERS 0x00000004
```

Description
If this record is present, then the pre-OS environment will allow the user to initiate enrollment of new user profiles. It does not give permission to update existing user profiles.

There is no data for this record.

36.4.1.5 EFI_USER_INFO_ACCESS_MANAGE

Summary
Presence of this record indicates that a user can update the user information of any user.

Prototype
```
#define EFI_USER_INFO_ACCESS_MANAGE 0x00000005
```

Description
If this record is present, then the pre-OS environment will allow the user to update any information about his/her own profile or other profiles.

There is no data for this record.
36.4.1.6 EFI_USER_INFO_ACCESS_SETUP

Summary
Describes permissions usable when configuring the platform.

Prototype
```
#define EFI_USER_INFO_ACCESS_SETUP 0x00000006
```

Description
This record describes access permission for use in configuring the platform using an UEFI Forms Processor using zero or more GUIDs. There are three standard values (see below) and any number of others may be added.

Standard values for access to configure the platform

<table>
<thead>
<tr>
<th>EFI_USER_INFO_ACCESS_SETUP_ADMIN_GUID</th>
<th>System administrator only.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_USER_INFO_ACCESS_SETUP_NORMAL_GUID</td>
<td>Normal user.</td>
</tr>
<tr>
<td>EFI_USER_INFO_ACCESS_SETUP_RESTRICTED_GUID</td>
<td>Restricted user.</td>
</tr>
</tbody>
</table>

Related Definitions
```
#define EFI_USER_INFO_ACCESS_SETUP_ADMIN_GUID \  { 0x85b75607, 0xf7ce, 0x471e, \  { 0xb7, 0xe4, 0x2a, 0xea, 0x5f, 0x72, 0x32, 0xee } };
#define EFI_USER_INFO_ACCESS_SETUP_NORMAL_GUID \  { 0x1db29ae0, 0x9dcb, 0x43bc, \  { 0x8d, 0x87, 0x5d, 0xa1, 0x49, 0x64, 0x8d, 0xe2 } };
#define EFI_USER_INFO_ACCESS_SETUP_RESTRICTED_GUID \  { 0xbdb38125, 0x4d63, 0x49f4, \  { 0x82, 0x12, 0x61, 0xcf, 0x5a, 0x19, 0x0a, 0xf8 } };
```

36.4.1.7 EFI_USER_INFO_ACCESS_FORBID_CONNECT

Summary
Forbids UEFI drivers from being started from the specified device path(s) or any child device paths.

Prototype
```
#define EFI_USER_INFO_ACCESS_FORBID_CONNECT 0x00000007
```

Description
This record prohibits UEFI drivers from being started from the specified device path(s) or any of their child device path(s). This is enforced in the `ConnectController()` function.

This record prohibits the user from loading a device driver associated with zero or more device paths or their child paths.

The record is a series of normal UEFI device paths (not multi-instance device paths).

This prohibition is overridden by the `EFI_USER_INFO_ACCESS_PERMIT_CONNECT` record.
36.4.1.8 EFI_USER_INFO_ACCESS_PERMIT_CONNECT

Summary
Permits UEFI drivers to be started on the specified device path(s) or any child device paths.

Prototype
#define EFI_USER_INFO_ACCESS_PERMIT_CONNECT 0x00000008

Description
This record allows loading of device drivers associated with zero or more device paths or their child paths. The record is a series of normal UEFI device paths (not multi-instance device paths). This prohibition overrides any restrictions put in place by the EFI_USER_INFO_ACCESS_FORBID_CONNECT record.

36.4.1.9 EFI_USER_INFO_ACCESS_BOOT_ORDER

Summary
Modifies the boot order.

Prototype
#define EFI_USER_INFO_ACCESS_BOOT_ORDER 0x00000009
typedef UINT32 EFI_USER_INFO_ACCESS_BOOT_ORDER_HDR;
#define EFI_USER_INFO_ACCESS_BOOT_ORDER_MASK 0x000F
#define EFI_USER_INFO_ACCESS_BOOT_ORDER_INSERT 0x0000
#define EFI_USER_INFO_ACCESS_BOOT_ORDER_APPEND 0x0001
#define EFI_USER_INFO_ACCESS_BOOT_ORDER_REPLACE 0x0002
#define EFI_USER_INFO_ACCESS_BOOT_ORDER_NODEFAULT 0x0010

Description
This exclusive record allows the user profile to insert new boot options at the beginning of the boot order (EFI_USER_INFO_ACCESS_BOOT_ORDER_INSERT), append new boot options to the end of the boot order (EFI_USER_INFO_ACCESS_BOOT_ORDER_APPEND) or replace the entire boot order (EFI_USER_INFO_ACCESS_BOOT_ORDER_REPLACE). If EFI_USER_INFO_ACCESS_BOOT_ORDER_NODEFAULT is specified then the Boot Manager will not attempt find a default boot device when the default boot order does not lead to a bootable device.

The boot options specified by this record are still subject to the permissions specified by EFI_USER_INFO_ACCESS_FORBID_LOAD and EFI_USER_INFO_ACCESS_PERMIT_LOAD.

The record consists of a single EFI_USER_INFO_ACCESS_BOOT_ORDER_HDR followed by zero or more UEFI device paths.
36.4.2 EFI_USER_INFO_CBEFF_RECORD

Summary
Provides standard biometric information in the format specified by the ISO 19785 (Common Biometric Exchange Formats Framework) specification.

Prototype

```c
#define EFI_USER_INFO_CBEFF_RECORD 0x0B
typedef VOID *EFI_USER_INFO_CBEFF;
```

36.4.3 EFI_USER_INFO_CREATE_DATE_RECORD

Summary
Provides the date and time when the user profile was created.

Prototype

```c
#define EFI_USER_INFO_CREATE_DATE_RECORD 0x02
typedef EFI_TIME EFI_USER_INFO_CREATE_DATE;
```

Description
The optional record describing the date and time when the user profile was created. Type EFI_TIME is defined in `GetTime()` in this specification.

36.4.4 EFI_USER_INFO_CREDENTIAL_PROVIDER_RECORD

Summary
Specifies the credential provider.

Prototype

```c
#define EFI_USER_INFO_CREDENTIAL_PROVIDER_RECORD 0x08
typedef EFI_GUID EFI_USER_INFO_CREDENTIAL_PROVIDER;
```

Description
This record specifies the credential provider via a unique GUID. The credential’s handle is found in the EFI_USER_INFO structure associated with this user information record.

36.4.5 EFI_USER_INFO_CREDENTIAL_PROVIDER_NAME_RECORD

Summary
Specifies the user-readable name of a particular credential’s provider.

Prototype

```c
#define EFI_USER_INFO_CREDENTIAL_PROVIDER_NAME_RECORD 0x09
typedef CHAR16 *EFI_USER_INFO_CREDENTIAL_PROVIDER_NAME;
```
Description
This record specifies the null-terminated name of a particular credential provider. The credential’s handle is found in the `EFI_USER_INFO` structure associated with this user information record.

36.4.6 EFI_USER_INFO_CREDENTIAL_TYPE_RECORD

Summary
Specifies the type of a particular credential associated with the user profile.

Prototype
```
#define EFI_USER_INFO_CREDENTIAL_TYPE_RECORD 0x06
typedef EFI_GUID EFI_USER_INFO_CREDENTIAL_TYPE;
```

Description
This record specifies the type of a particular credential. The credential’s identifier is found in the `Credential` field of the `EFI_USER_INFO` structure. The credential types are listed with the `EFI_USER_CREDENTIAL2_PROTOCOL`.

36.4.7 EFI_USER_INFO_CREDENTIAL_TYPE_NAME_RECORD

Summary
Specifies the user-readable name of a particular credential type.

Prototype
```
#define EFI_USER_INFO_CREDENTIAL_TYPE_NAME_RECORD 0x07
typedef CHAR16 *EFI_USER_INFO_CREDENTIAL_TYPE_NAME;
```

Description
This record specifies the null-terminated name of a particular credential type. The credential’s handle is found in the `EFI_USER_INFO` structure associated with this user information record.

36.4.8 EFI_USER_INFO_GUID_RECORD

Summary
Provides placeholder for additional user profile information identified by a GUID.

Prototype
```
#define EFI_USER_INFO_GUID_RECORD 0xFF
typedef EFI_GUID EFI_USER_INFO_GUID;
```

Description
This record type provides extensibility by prefixing further data fields in the record with a GUID which identifies the format.
36.4.9 EFI_USER_INFO_FAR_RECORD

Summary
Indicates how close of a match the fingerprint must be in order to be considered a match.

Prototype
```
#define EFI_USER_INFO_FAR_RECORD 0x0C
typedef UINT8 EFI_USER_INFO_FAR;
```

Description
This record specifies how accurate the fingerprint template match must be in order to be considered a match, as a percentage from 0 (no match) to 100 (perfect match). The accuracy may be for all fingerprint sensors (EFI_USER_INFO.Credential is zero) or for a particular fingerprint sensor (EFI_USER_INFO.Credential is non-zero).

Access:
Exclusive: No
Modify: Only with user-enrollment permissions.
Visibility: Public

36.4.10 EFI_USER_INFO_IDENTIFIER_RECORD

Summary
Provides a unique non-volatile user identifier for each enrolled user.

Prototype
```
#define EFI_USER_INFO_IDENTIFIER_RECORD 0x05
typedef UINT8 EFI_USER_INFO_IDENTIFIER[16];
```

Description
The user identifier is unique to each enrolled user and non-volatile. Each user profile must have exactly one of these user information records installed. The format of the value is not specified.

Access
Exclusive: Yes
Modify: Only with user-enrollment permissions.
Visibility: Public.

36.4.11 EFI_USER_INFO_IDENTITY_POLICY_RECORD

Summary
Provides the expression which determines which credentials are required to assert user identity.

Prototype
#define EFI_USER_INFO_IDENTITY_POLICY_RECORD 0x0F
typedef struct {
    UINT32 Type;
    UINT32 Length;
} EFI_USER_INFO_IDENTITY_POLICY;

Parameters

Type
Specifies either an operator or a data item. See EFI_USER_INFO_IDENTITY_x in “Related Definitions” below.

Length
The length of this block, in bytes, including this header.

Description
The user identity policy is an expression made up of operators and data items. If the expression evaluates to TRUE, then this user profile can be selected as the current profile. If the expression evaluates to FALSE, then this user profile cannot be selected as the current profile.

Data items are pushed onto an expression stack. Operators pop items off of the expression stack, perform an operator and push the results back.

NOTE: If there is no user profile, then FALSE is assumed.

Access
Exclusive: Yes
Modify: Only with user-enrollment permissions.
Visibility: Public.

Related Definitions

<table>
<thead>
<tr>
<th>Type Name</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_USER_INFO_IDENTITY_FALSE</td>
<td>Push FALSE on to the expression stack.</td>
</tr>
<tr>
<td>EFI_USER_INFO_IDENTITY_TRUE</td>
<td>Push TRUE on to the expression stack.</td>
</tr>
<tr>
<td>EFI_USER_INFO_IDENTITY_CREDENTIAL_TYPE</td>
<td>If a credential provider with the specified class asserts the user’s identity, push TRUE. Otherwise push FALSE. The EFI_USER_INFO_IDENTITY_POLICY structure is followed immediately by a GUID.</td>
</tr>
<tr>
<td>EFI_USER_INFO_IDENTITY_CREDENTIAL_PROVIDER</td>
<td>If a credential provider with the specified provider identifier asserts the user’s identity, push TRUE. Otherwise, push FALSE. The EFI_USER_INFO_IDENTITY_POLICY structure is followed immediately by a GUID.</td>
</tr>
<tr>
<td>EFI_USER_INFO_IDENTITY_NOT</td>
<td>Pop a boolean off the stack. If TRUE, then push FALSE. If FALSE, then push TRUE.</td>
</tr>
</tbody>
</table>

continues on next page
Table 36.17 – continued from previous page

<table>
<thead>
<tr>
<th>EFI_USER_INFO_IDENTITY_AND</th>
<th>Pop two Booleans off the stack. If both are TRUE, then push TRUE. Otherwise push FALSE.</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_USER_INFO_IDENTITY_OR</td>
<td>Pop two Booleans off the stack. If either is TRUE, then push TRUE. Otherwise push FALSE.</td>
</tr>
</tbody>
</table>

36.4.12 EFI_USER_INFO_NAME_RECORD

Summary
Provide the user’s name for the enrolled user.

Prototype

```c
#define EFI_USER_INFO_NAME_RECORD 0x01
typedef CHAR16 *EFI_USER_INFO_NAME;
```

Description
The user’s name is a NULL-terminated string.

Access
Exclusive: Yes
Visibility: Public.

36.4.13 EFI_USER_INFO_PKCS11_RECORD

Summary
Provides PKCS#11 credential information from a smart card.

Prototype

```c
#define EFI_USER_INFO_PKCS11_RECORD 0x0A
```

36.4.14 EFI_USER_INFO_RETRY_RECORD

Summary
Indicates how many attempts the user has to with a particular credential before the system prevents further attempts.

Prototype

```c
#define EFI_USER_INFO_RETRY_RECORD 0x0D
typedef UINT8 EFI_USER_INFO_RETRY;
```

Description
This record indicates the number of times the user may fail identification with all credential providers (`EFI_USER_INFO.Credential` is zero) or a particular credential provider (`EFI_USER_INFO.Credential` is non-zero).

Access:
Exclusive: No
Modify: Only with user-enrollment permissions.
36.4.15 EFI_USER_INFO_USAGE_DATE_RECORD

Summary
Provides the date and time when the user profile was selected.

Prototype
#define EFI_USER_INFO_USAGE_DATE_RECORD 0x03
typedef EFI_TIME EFI_USER_INFO_USAGE_DATE;

Description
The optional record describing the date and time when the user profile was last selected. Type EFI_TIME is defined in GetTime() in this specification.

36.4.16 EFI_USER_INFO_USAGE_COUNT_RECORD

Summary
Provides the number of times that the user profile has been selected.

Prototype
#define EFI_USER_INFO_USAGE_COUNT 0x04
typedef UINT64 EFI_USER_INFO_USAGE_COUNT;

Description
The optional record describing the number of times that the user profile was selected.

36.5 User Information Table

Summary
A collection of EFI_USER_INFO records, prefixed with this header.

Prototype
typedef struct {
    UINT64 Size;
} EFI_USER_INFO_TABLE;

Members
Size
Total size of the user information table, in bytes.

Description
This header is followed by a series of records. Each record is prefixed by the EFI_USER_INFO structure. The total size of this header and all records is equal to Size.
37.1 Hash Overview

For the purposes of this specification, a hash function takes a variable length input and generates a fixed length hash value. In general, hash functions are collision-resistant, which means that it is infeasible to find two distinct inputs which produce the same hash value. Hash functions are generally one-way which means that it is infeasible to find an input based on the output hash value.

This specification describes a protocol which allows a driver to produce a protocol which supports zero or more hash functions.

37.1.1 Hash References

The following references define the standard means of creating the hashes used in this specification:


For more information
  • see “Links to UEFI-Related Documents” at http://uefi.org/uefi under the heading “Archived FIPS publication”.
  • see “Links to UEFI-Related Documents” at http://uefi.org/uefi under the heading “MD5 Message-Digest Algorithm”. EFI Hash Protocols

37.1.1.1 EFI_HASH_SERVICE_BINDING_PROTOCOL

Summary

The EFI Hash Service Binding Protocol is used to locate hashing services support provided by a driver and create and destroy instances of the EFI Hash Protocol so that a multiple drivers can use the underlying hashing services.

The EFI Service Binding Protocol that is defined in EFI Services Binding defines the generic Service Binding Protocol functions. This section discusses the details that are specific to the EFI Hash Protocol.

GUID

```
#define EFI_HASH_SERVICE_BINDING_PROTOCOL_GUID
{
0x42881c98,0xa4f3,0x44b0,0xa3,0x9d,0xdf,0xa1,0x86,0x67,0xd8,0xcd
}
```

Description

An application (or driver) that requires hashing services can use one of the protocol handler services, such as BS->LocateHandleBuffer(), to search for devices that publish an EFI Hash Service Binding Protocol.
After a successful call to the `EFI_HASH_SERVICE_BINDING_PROTOCOL.CreateChild()` function, the child EFI Hash Protocol driver instance is ready for use. The instance of `EFI_HASH_PROTOCOL` must be obtained by performing `HandleProtocol()` against the handle returned by `CreateChild()`. Use of other methods, such as `LocateHandle()`, are not supported.

Once obtained, the driver may use the `EFI_HASH_PROTOCOL` instance for any number of non-overlapping hash operations. Overlapping hash operations require an additional call to `EFI_HASH_SERVICE_BINDING_PROTOCOL.CreateChild()` for a new instance.

Before a driver or application terminates execution, every successful call to the `EFI_HASH_SERVICE_BINDING_PROTOCOL.CreateChild()` function must be matched with a call to the `EFI_HASH_SERVICE_BINDING_PROTOCOL.DestroyChild()` function.

### 37.1.1.2 EFI_HASH_PROTOCOL

**Summary**

This protocol describes standard hashing functions.

**GUID**

```
#define EFI_HASH_PROTOCOL_GUID
{0xc5184932,0xdba5,0x46db,
 {0xa5,0xba,0xcc,0x0b,0xda,0x9c,0x14,0x35}
```

**Protocol Interface Structure**

```
typedef _EFI_HASH_PROTOCOL {
    EFI_HASH_GET_HASH_SIZE GetHashSize;
    EFI_HASH_HASH Hash;
} EFI_HASH_PROTOCOL;
```

**Parameters**

**GetHashSize**

Return the size of a specific type of resulting hash.

**Hash**

Create a hash for the specified message.

**Description**

This protocol allows creating a hash of an arbitrary message digest using one or more hash algorithms. The `GetHashSize` returns the expected size of the hash for a particular algorithm and whether or not that algorithm is, in fact, supported. The `Hash` actually creates a hash using the specified algorithm.

**Related Definitions**

None.
37.1.1.3 EFI_HASH_PROTOCOL.GetHashSize()

Summary
Returns the size of the hash which results from a specific algorithm.

Prototype

```c
EFI_STATUS
EFIAPI
GetHashSize(
    IN CONST EFI_HASH_PROTOCOL *This,
    IN CONST EFI_GUID *HashAlgorithm,
    OUT UINTN *HashSize
);
```

Parameters

This
Points to this instance of `EFI_HASH_PROTOCOL`.

HashAlgorithm
Points to the `EFI_GUID` which identifies the algorithm to use. See ` EFI Hash Algorithms`.

HashSize
Holds the returned size of the algorithm’s hash.

Description
This function returns the size of the hash which will be produced by the specified algorithm.

Related Definitions
None

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Hash size returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HashSize is NULL or HashAlgorithm is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The algorithm specified by HashAlgorithm is not supported by this driver.</td>
</tr>
</tbody>
</table>

37.1.1.4 EFI_HASH_PROTOCOL.Hash()

Summary
Creates a hash for the specified message text.

Prototype

```c
EFI_STATUS
EFIAPI
Hash(
    IN CONST EFI_HASH_PROTOCOL *This,
    IN CONST EFI_GUID *HashAlgorithm,
    IN BOOLEAN Extend,
    IN CONST UINT8 *Message,
    IN UINT64 MessageSize,
    IN OUT EFI_HASH_OUTPUT *Hash
);
```
Parameters

This
PointstothisinstanceofEFI_HASH_PROTOCOL.

HashAlgorithm
PointstotheEFI_GUIDwhichidentifiesthealgorithmtouse. SeeEFI Hash Algorithms.

Extend
Specifyswetheretocreateanewhash(FALSE)orextendthespecifiedexistinghash(TRUE).

Message
Pointstothestartothemessage.

MessageSize
ThesizeofMessage,inbytes.Mustbeintegermultipleofblocksize.

Hash
Oninput,ifExtendisTRUE,thenthisparameterholdsapointeratoapointertoanarraycontainingthehash toextend.IfExtendisFALSE,thenthisparameterholdsapointeratoapointertocaller-allocatedarraythatwill receivetheresultofthehashcomputation.Onoutput(regardlessofthevalueofExtend),thearraywillcontain theresultofthehashcomputation.

Description
ThisfunctioncreatesthehashofthespecifiedmessagetextbasedonthespecifiedalgorithmHashAlgorithm andcopies theresulttothecaller-providedbufferHash. If Extend is TRUE, then the hash specified on input by Hash is extended. If Extend is FALSE, then the starting hash value will be that specified by the algorithm.

NOTE: For the all algorithms used with EFI_HASH_PROTOCOL, the following apply:

• TheEFI_HASH_PROTOCOL.Hash()functiondoesnotperformpaddingofmessage data for these algorithms. Hence, MessageSize shall always be an integer multiple of the HashAlgorithm block size, and the final supplied Message in a sequence of invocations shall contain caller-provided padding. This will ensure that the final Hash output will be the correct hash of the provided message(s).

• TheresultofaHash()callforoneoftheseealgorithmswhenthecallerdoesnotsupplymessagedatawhose lengthis an integer multiple of the algorithm’s block size is a returned error.

• TheEFI_HASH_OUTPUToptionsforthesetwoalgorithmsshallbeEFI_SHA1_HASHandeFI_SHA256_HASH, respectively.

• CallersusingtheseealgorithmsmayconsulttheaforementionedSecureHashStandardfordetailsonhow to perform proper padding required by standard prior to final invocation.

Related Definitions
EFI_HASH_OUTPUT

StatusCodesReturned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Hash returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Message or Hash,HashAlgorithm is NULL or MessageSize is 0. MessageSize is not an integer multiple of block size.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The algorithm specified by HashAlgorithm is not supported by this driver. Includes HashAlgorithm being passed as a null error.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Extend is TRUE and the algorithm doesn’t support extending the hash.</td>
</tr>
</tbody>
</table>
37.1.2 Other Code Definitions

37.1.2.1 EFI_SHA1_HASH, EFI_SHA224_HASH, EFI_SHA256_HASH, EFI_SHA384_HASH, EFI_SHA512_HASH, EFI_MD5_HASH

Summary
Data structure which holds the result of the hash.

Prototype

```c
typedef UINT8 EFI_MD5_HASH[16];
typedef UINT8 EFI_SHA1_HASH[20];
typedef UINT8 EFI_SHA224_HASH[28];
typedef UINT8 EFI_SHA256_HASH[32];
typedef UINT8 EFI_SHA384_HASH[48];
typedef UINT8 EFI_SHA512_HASH[64];
typedef union _EFI_HASH_OUTPUT {
    EFI_MD5_HASH *Md5Hash;
    EFI_SHA1_HASH *Sha1Hash;
    EFI_SHA224_HASH *Sha224Hash;
    EFI_SHA256_HASH *Sha256Hash;
    EFI_SHA384_HASH *Sha384Hash;
    EFI_SHA512_HASH *Sha512Hash;
} EFI_HASH_OUTPUT;
```

Description
These prototypes describe the expected hash output values from the Hash function of the EFI_HASH_PROTOCOL.

Related Definitions
None

37.1.2.2 EFI Hash Algorithms

The following table gives the EFI_GUID for standard hash algorithms and the corresponding ASN.1 OID (Object Identifier):

**NOTE:** Use of the following algorithms with EFI_HASH_PROTOCOL is deprecated.

- EFI_HASH_ALGORITHM_SHA1_GUID
- EFI_HASH_ALGORITHM_SHA224_GUID
- EFI_HASH_ALGORITHM_SHA256_GUID
- EFI_HASH_ALGORITHM_SHA384_GUID
- EFI_HASH_ALGORITHM_SHA512_GUID
- EFI_HASH_ALGORITHM_MD5_GUID

<table>
<thead>
<tr>
<th>Algorithm</th>
<th>EFI_GUID</th>
<th>OID</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Table 37.1: EFI Hash Algorithms

continues on next page
### Table 37.1 – continued from previous page

<table>
<thead>
<tr>
<th>Algorithm</th>
<th>EFI_HASH_ALGORITHM_SHA1_NOPAD_GUID</th>
<th>id-sha1 OBJECT IDENTIFIER ::= { iso(1) identified-organization(3) oiw(14) secsig(3) algorithms(2) 26 }</th>
</tr>
</thead>
<tbody>
<tr>
<td>SHA-1 (No padding done by implementation)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
#define EFI_HASH_ALGORITHM_SHA1_NOPAD_GUID {0x24c5dc2f, 0x53e2, 0x40ca, {0x9e, 0xd6, 0xa5, 0xd9, 0xa4, 0x9f, 0x46, 0x3b}} | |
| SHA-256 (No padding done by implementation) | 
#define EFI_HASH_ALGORITHM_SHA256_NOPAD_GUID {0x8628752a, 0x6cb7, 0x4814, {0x96, 0xfc, 0x24, 0xa8, 0x15, 0xac, 0x22, 0x26}} | id-sha256 OBJECT IDENTIFIER ::= { joint-iso-itu-t (2) country (16) us (840) organization (1) gov (101) csor (3) nistalgorithm (4) hashalgs (2) 1 } |

**NOTE:** For the EFI_HASH_ALGORITHM_SHA1_NOPAD_GUID and the EFI_HASH_ALGORITHM_SHA256_NOPAD_GUID, the following apply:

- The `EFI_HASH_PROTOCOL.Hash()` function does not perform padding of message data for these algorithms. Hence, `MessageSize` shall always be an integer multiple of the `HashAlgorithm` block size, and the final supplied `Message` in a sequence of invocations shall contain caller-provided padding. This will ensure that the final `Hash` output will be the correct hash of the provided message(s).

- The result of a `Hash()` call for one of these algorithms when the caller does not supply message data whose length is an integer multiple of the algorithm’s block size is undefined.

- The `EFI_HASH_OUTPUT` options for these two algorithms shall be `EFI_SHA1_HASH` and `EFI_SHA256_HASH`, respectively.

- Callers using these algorithms may consult the aforementioned Secure Hash Standard for details on how to perform proper padding.

### 37.2 Hash2 Protocols

#### 37.2.1 EFI Hash2 Service Binding Protocol

##### 37.2.1.1 EFI_HASH2_SERVICE_BINDING_PROTOCOL

**Summary**

The EFI Hash2 Service Binding Protocol is used to locate `EFI_HASH2_PROTOCOL` hashing services support provided by a driver and create and destroy instances of the `EFI_HASH2_PROTOCOL` Protocol so that a multiple drivers can use the underlying hashing services.

The EFI Service Binding Protocol that is defined in `EFI Services Binding` defines the generic Service Binding Protocol functions. This section discusses the details that are specific to the EFI Hash Protocol.

**GUID**

```c
#define EFI_HASH2_SERVICE_BINDING_PROTOCOL_GUID \ 
{0xda836f8d, 0x217f, 0x4ca0, 0x99, 0xc2, 0x1c, \ 
0xa4, 0xe1, 0x60, 0x77, 0xea}
```

**Description**

An application (or driver) that requires hashing services can use one of the protocol handler services, such as `BS-LocateHandleBuffer()`, to search for devices that publish an `EFI_HASH2_SERVICE_BINDING_PROTOCOL`.

After a successful call to the `EFI_HASH2_SERVICE_BINDING_PROTOCOL` member `CreateChild()` function, the child instance of `EFI_HASH2_PROTOCOL` Protocol driver instance is ready for use. The instance of
EFI_HASH2_PROTOCOL must be obtained by performing HandleProtocol() against the handle returned by CreateChild(). Use of other methods, such as LocateHandle() is not supported.

Once obtained, the driver may use the EFI_HASH2_PROTOCOL instance for any number of non-overlapping hash operations. Overlapping hash operations require an additional call to EFI_HASH_SERVICE_BINDING_PROTOCOL.CreateChild() for a new instance.

Before a driver or application using the instance terminates execution, every successful call to the EFI_HASH_SERVICE_BINDING_PROTOCOL.CreateChild() function must be matched with a call to the EFI_HASH_SERVICE_BINDING_PROTOCOL.DestroyChild() function.

### 37.2.2 EFI Hash2 Protocol

#### 37.2.2.1 EFI_HASH2_PROTOCOL

**Summary**

This protocol describes hashing functions for which the algorithm-required message padding and finalization are performed by the supporting driver. In previous versions of the specification, the algorithms supported by EFI_HASH2_PROTOCOL were also available for use with EFI_HASH_PROTOCOL but this usage has been deprecated.

**GUID**

```c
#define EFI_HASH2_PROTOCOL_GUID
{
0x55b1d734, 0xc5e1, 0x49db, 0x96, 0x47, 0xb1, 0x6a,
0xfb, 0xe, 0x30, 0x5b}
```

**Protocol Interface Structure**

```c
typedef _EFI_HASH2_PROTOCOL {
EFI_HASH2_GET_HASH_SIZE GetHashSize;
EFI_HASH2_HASH Hash;
EFI_HASH2_HASH_INIT HashInit;
EFI_HASH2_HASH_UPDATE HashUpdate;
EFI_HASH2_HASH_FINAL HashFinal;
} EFI_HASH2_PROTOCOL;
```

**Parameters**

- **GetHashSize**
  
  Return the result size of a specific type of resulting hash.

- **Hash**
  
  Create a final non-extendable hash for a single message block in a single call.

- **HashInit**
  
  Initializes an extendable multi-part hash calculation

- **HashUpdate**
  
  Continues a hash in progress by supplying the first or next sequential portion of the message text

- **HashFinal**
  
  Finalizes a hash in progress by padding as required by algorithm and returning the hash output.

**Description**

37.2. Hash2 Protocols
This protocol allows creating a hash of an arbitrary message digest using one or more hash algorithms. The `GetHashSize()` function returns the expected size of the hash for a supported algorithm and an error if that algorithm is not supported. The `Hash()` function creates a final, non-extendable, hash of a single message block using the specified algorithm. The three functions `HashInit()`, `HashUpdate()`, `HashFinal()`, generates the hash of a multi-part message, with input composed of one or more message pieces.

For a specific handle representing an instance of `EFI_HASH2_PROTOCOL`, if `Hash()` is called after a call to `HashInit()` and prior to the matching call to `HashFinal()`, the multi-part hash started by `HashInit()` will be canceled and calls to `HashUpdate()` or `HashFinal()` will return an error status unless proceeded by a new call to `HashInit()`.

**NOTE:** Algorithms `EFI_HASH_ALGORITHM_SHA1_NOPAD` and `EFI_HASH_ALGORITHM_SHA256_NOPAD_GUID` are not compatible with `EFI_HASH2_PROTOCOL` and will return `EFI_UNSUPPORTED` if used with any `EFI_HASH2_PROTOCOL` function.

**Related Definitions**

None

**NOTE:** The following hash function invocations will produce identical hash results for all supported `EFI_HASH2_PROTOCOL` algorithms. The data in quotes is the message.

<table>
<thead>
<tr>
<th>Table 37.2: Identical Hash Results</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>Hash(&quot;ABCDEF&quot;)</code></td>
</tr>
<tr>
<td><code>HashUpdate(&quot;ABCDEF&quot;)</code></td>
</tr>
<tr>
<td><code>HashFinal()</code></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
</tbody>
</table>

### 37.2.2.2 EFI_HASH2_PROTOCOL.GetHashSize()

**Summary**

Returns the size of the hash which results from a specific algorithm.

**Prototype**

```c
EFI_STATUS
EFIAPI
GetHashSize(
    IN CONST EFI_HASH2_PROTOCOL *This,
    IN CONST EFI_GUID *HashAlgorithm,
    OUT UINTN *HashSize
);
```

**Parameters**

- **This**
  Points to this instance of `EFI_HASH2_PROTOCOL`.

- **HashAlgorithm**
  Points to the `EFI_GUID` which identifies the algorithm to use. See Other Code Definitions.

- **HashSize**
  Holds the returned size of the algorithm’s hash.

**Description**

This function returns the size of the hash result buffer which will be produced by the specified algorithm.
Fig. 37.1: Hash workflow
Related Definitions

None

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Hash size returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This or HashSize is NULL</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The algorithm specified by HashAlgorithm is not supported by this driver or HashAlgorithm is NULL.</td>
</tr>
</tbody>
</table>

### 37.2.2.3 EFI_HASH2_PROTOCOL.Hash()

**Summary**

Creates a hash for a single message text. The hash is not extendable. The output is final with any algorithm-required padding added by the function.

**Prototype**

```c
EFI_STATUS
EFI_API
Hash(
    IN CONST EFI_HASH2_PROTOCOL *This,
    IN CONST EFI_GUID *HashAlgorithm,
    IN CONST UINT8 *Message,
    IN UINTN MessageSize,
    IN OUT EFI_HASH2_OUTPUT *Hash
);
```

**Parameters**

**This**

Points to this instance of `EFI_HASH2_PROTOCOL`.

**HashAlgorithm**

Points to the `EFI_GUID` which identifies the algorithm to use. See Table, *Algorithms that may be used with EFI_HASH2_PROTOCOL*.

**Message**

Points to the start of the message.

**MessageSize**

The size of `Message`, in bytes.

**Hash**

On input, points to a caller-allocated buffer of the size returned by `GetHashSize()` for the specified `HashAlgorithm`. On output, the buffer holds the resulting hash computed from the message.

**Description**

This function creates the hash of specified single block message text based on the specified algorithm `HashAlgorithm` and copies the result to the caller-provided buffer `Hash`. The resulting hash cannot be extended. All padding required by `HashAlgorithm` is added by the implementation.

**Related Definitions**

- `EFI_HASH2_OUTPUT`

**Status Codes Returned**

37.2. Hash2 Protocols
### 37.2.4 EFI_HASH2_PROTOCOL.HashInit()

#### Summary
This function must be called to initialize a digest calculation to be subsequently performed using the `EFI_HASH2_PROTOCOL` functions `HashUpdate()` and `HashFinal()`.

#### Prototype
```c
EFI_STATUS
EFIAPI
HashInit(
    IN CONST EFI_HASH2_PROTOCOL *This,
    IN CONST EFI_GUID *HashAlgorithm,
);
```

#### Parameters
- **This**
  Points to instance of `EFI_HASH2_PROTOCOL`.
- **HashAlgorithm**
  Points to the `EFI_GUID` which identifies the algorithm to use. See Table, *Algorithms that may be used with EFI_HASH2_PROTOCOL*.

#### Description
This function

#### Related Definitions

#### Status Codes Returned
<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Initialized successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>This</code>, or <code>Hash</code> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The algorithm specified by <code>HashAlgorithm</code> is not supported by this function or <code>HashAlgorithm</code> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Process failed due to lack of required resource.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>This function is called when the operation in progress is still in processing <code>Hash()</code>, or <code>HashInit()</code> is already called before and not terminated by <code>HashFinal()</code> yet on the same instance.</td>
</tr>
</tbody>
</table>

---

_EFI_SUCCESS_  
Hash returned successfully.

_EFI_INVALID_PARAMETER_  
This, or Hash is **NULL**.

_EFI_UNSUPPORTED_  
The algorithm specified by HashAlgorithm is not supported by this driver or HashAlgorithm is Null.

_EFI_OUT_OF_RESOURCES_  
Some resource required by the function is not available or MessageSize is greater than platform maximum.
37.2.2.5 EFI_HASH2_PROTOCOL.HashUpdate()

Summary
Updates the hash of a computation in progress by adding a message text.

Prototype

```
EFI_STATUS
EFIAPI
HashUpdate(
    IN CONST EFI_HASH2_PROTOCOL *This,
    IN CONST UINT8 *Message,
    IN UINTN MessageSize
);
```

Parameters

**This**
Points to instance of `EFI_HASH2_PROTOCOL`.

**Message**
Points to the start of the message.

**MessageSize**
The size of `Message`, in bytes.

Description
This function extends the hash of ongoing hash operation with the supplied message text. This function should be called one or more times with portions of the total message text to be hashed. A zero-length message input will return `EFI_SUCCESS` and has no impacts on the ongoing hash instance.

Related Definitions

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Digest in progress updated successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This or Hash is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Some resource required by the function is not available or <code>MessageSize</code> is greater than platform maximum.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>This call was not preceded by a valid call to <code>HashInit()</code>, or the operation in progress was terminated by a call to <code>Hash()</code> or <code>HashFinal()</code> on the same instance.</td>
</tr>
</tbody>
</table>
37.2.2.6 EFI_HASH2_PROTOCOL.HashFinal()

Summary
Finalizes a hash operation in progress and returns calculation result. The output is final with any necessary padding added by the function. The hash may not be further updated or extended after HashFinal().

Prototype

```c
 EFI_STATUS
EFI_API
HashFinal(
    IN CONST EFI_HASH2_PROTOCOL *This,
    IN OUT EFI_HASH2_OUTPUT *Hash
);
```

Parameters

**This**
Points to instance of EFI_HASH2_PROTOCOL.

**Hash**
On input, points to a caller-allocated buffer of the size returned by GetHashSize() for the specified HashAlgorithm specified in preceding HashInit(). On output, the buffer holds the resulting hash computed from the message.

Description
This function finalizes the hash of a hash operation in progress. The resulting final hash cannot be extended.

Related Definitions
EFI_HASH2_OUTPUT

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Hash returned successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This or Hash is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>This call was not preceded by a valid call to HashInit() and at least one call to HashUpdate(), or the operation in progress was canceled by a call to Hash() on the same instance.</td>
</tr>
</tbody>
</table>

Table 37.8: Algorithms that may be used with EFI_HASH2_PROTOCOL

<table>
<thead>
<tr>
<th>GUID</th>
<th>OID</th>
</tr>
</thead>
<tbody>
<tr>
<td>SHA-1</td>
<td>#define EFI_HASH _ALGORITHM_SHA1_GUID {0x2ae9d80f, 0x3fb2, 0x4095, { 0xb7, 0xb1, 0xe9, 0x31, 0x57, 0xb9, 0x46, 0xb6}}</td>
</tr>
<tr>
<td>SHA-224</td>
<td>#define EFI_HASH _ALGORITHM_SHA224_GUID {0x8df01a06, 0x9bd5, 0x4bf7, {0xb0, 0x21, 0xdb, 0x4f, 0xd9, 0xcc, 0xf4, 0xb6}}</td>
</tr>
<tr>
<td>SHA-256</td>
<td>#define EFI_HASH _ALGORITHM_SHA256_GUID {0x51aa59de, 0xfdf2, 0x4ea3, {0xbc, 0x63, 0x87, 0x5f, 0xb7, 0x84, 0x2e, 0xe9 }}</td>
</tr>
</tbody>
</table>

continues on next page
NOTE: SHA-1 and MD5 are included for backwards compatibility. New driver implementations are encouraged to consider stronger algorithms.

37.2.3 Other Code Definitions

37.2.3.1 EFI_HASH2_OUTPUT

Summary

Data structure which holds the result of the hash operation from EFI_HASH2_PROTOCOL hash operations.

Prototype

```c
typedef UINT8 EFI_MD5_HASH2[16];
typedef UINT8 EFI_SHA1_HASH2[20];
typedef UINT8 EFI_SHA224_HASH2[28];
typedef UINT8 EFI_SHA256_HASH2[32];
typedef UINT8 EFI_SHA384_HASH2[48];
typedef UINT8 EFI_SHA512_HASH2[64];
typedef union _EFI_HASH2_OUTPUT {
    EFI_MD5_HASH2 Md5Hash;
    EFI_SHA1_HASH2 Sh1Hash;
    EFI_SHA224_HASH2 Sha224Hash;
    EFI_SHA256_HASH2 Sha256Hash;
    EFI_SHA384_HASH2 Sha384Hash;
    EFI_SHA512_HASH2 Sha512Hash;
} EFI_HASH2_OUTPUT;
```

Description

These prototypes describe the expected hash output values from the hashing functions of the EFI_HASH2_PROTOCOL.

Related Definitions

None
37.3 Key Management Service

37.3.1 EFI_KEY_MANAGEMENT_SERVICE_PROTOCOL

Summary

The Key Management Service (KMS) protocol provides services to generate, store, retrieve, and manage cryptographic keys. The intention is to specify a simple generic protocol that could be used for many implementations.

The management keys have a simple construct - they consist of key identifier and key data, both of variable size.

A driver implementing the protocol may need to provide basic key service that consists of a key store and cryptographic key generation capability. It may connect to an external key server over the network, or to a Hardware Security Module (HSM) attached to the system it runs on, or anything else that is capable of providing the key management service.

Authentication and access control is not addressed by this protocol. It is assumed it is addressed at the system level and done by the driver implementing the protocol, if applicable to the implementation.

GUID

```
#define EFI_KMS_PROTOCOL_GUID
   {0xEC3A978D,0x7C4E, 0x48FA,
    {0x9A,0xBE,0x6A,0xD9,0x1C,0xC8,0xF8,0x11}}
```

Protocol Interface Structure

```
#define EFI_KMS_DATA_TYPE_NONE     0
#define EFI_KMS_DATA_TYPE_BINARY    1
#define EFI_KMS_DATA_TYPE_ASCII     2
#define EFI_KMS_DATA_TYPE_UNICODE   4
#define EFI_KMS_DATA_TYPE_UTF8      8
```

Where appropriate, `EFI_KMS_DATA_TYPE` values may be combined using a bitwise ‘OR’ operation to indicate support for multiple data types.

```
typedef struct _EFI_KMS_SERVICE_PROTOCOL {
    EFI_KMS_GET_SERVICE_STATUS GetServiceStatus;
    EFI_KMS_REGISTER_CLIENT RegisterClient;
    EFI_KMS_CREATE_KEY CreateKey;
    EFI_KMS_GET_KEY GetKey;
    EFI_KMS_ADD_KEY AddKey;
    EFI_KMS_DELETE_KEY DeleteKey;
    EFI_KMS_GET_KEY_ATTRIBUTES GetKeyAttributes;
    EFI_KMS_ADD_KEY_ATTRIBUTES AddKeyAttributes;
    EFI_KMS_DELETE_KEY_ATTRIBUTES DeleteKeyAttributes;
    EFI_KMS_GET_KEY_BY_ATTRIBUTES GetKeyByAttributes;
    UINT32 ProtocolVersion;
    EFI_GUID ServiceId;
    CHAR16 *ServiceName;
    UINT32 ServiceVersion;
    BOOLEAN ServiceAvailable;
    BOOLEAN ClientIdSupported;
    BOOLEAN ClientIdRequired;
    UINT16 ClientIdMaxSize;
    UINT8 ClientNameStringTypes;
} EFI_KMS_SERVICE_PROTOCOL;
```

(continues on next page)
Parameters

GetServiceStatus
Get the current status of the key management service. If the implementation has not yet connected to the KMS, then a call to this function will initiate a connection. This is the only function that is valid for use prior to the service being marked available.

RegisterClient
Register a specific client with the KMS.

CreateKey
Request the generation of a new key and retrieve it.

GetKey
Retrieve an existing key.

AddKey
Add a local key to the KMS database. If there is an existing key with this key identifier in the KMS database, it will be replaced with the new key.

DeleteKey
Delete an existing key from the KMS database.

AddKeyAttributes
Add attributes to an existing key in the KMS database.

GetKeyAttributes
Get attributes for an existing key in the KMS database.

DeleteKeyAttributes
Delete attributes for an existing key in the KMS database.

GetKeyByAttributes
Get existing key(s) with the specified attributes.

ProtocolVersion
The version of this EFI_KMS_PROTOCOL structure. This must be set to 0x00020040 for the initial version of this protocol.

ServiceId
Optional GUID used to identify a specific KMS. This GUID may be supplied by the provider, by the implementation, or may be null. If it is null, then the *ServiceName* must not be null.
**ServiceName**
Optional pointer to a unicode string which may be used to identify the KMS or provide other information about the supplier.

**ServiceVersion**
Optional 32-bit value which may be used to indicate the version of the KMS provided by the supplier.

**ServiceAvailable**
TRUE if and only if the service is active and available for use. To avoid unnecessary delays in POST, this protocol may be installed without connecting to the service. In this case, the first call to the `GetServiceStatus()` function will cause the implementation to connect to the supported service and mark it as available. The capabilities of this service as defined in the remainder of this protocol are not guaranteed to be valid until the service has been marked available.

FALSE otherwise.

**ClientIdSupported**
TRUE if and only if the service supports client identifiers. Client identifiers may be used for auditing, access control or any other purpose specific to the implementation.

FALSE otherwise.

**ClientIdRequired**
TRUE if and only if the service requires a client identifier in order to process key requests.

FALSE otherwise.

**ClientIdMaxSize**
The maximum size in bytes for the client identifier.

**ClientNameStringTypes**
The client name string type(s) supported by the KMS service. If client names are not supported, this field will be set to EFI_KMS_DATA_TYPE_NONE. Otherwise, it will be set to the inclusive ‘OR’ of all client name formats supported. Client names may be used for auditing, access control or any other purpose specific to the implementation.

**ClientNameRequired**
TRUE if and only if the KMS service requires a client name to be supplied to the service.

FALSE otherwise.

**ClientNameMaxCount**
The maximum number of characters allowed for the client name.

**ClientDataSupported**
TRUE if and only if the service supports arbitrary client data requests. The use of client data requires the caller to have specific knowledge of the individual KMS service and should be used only if absolutely necessary.

FALSE otherwise.

**ClientDataMaxSize**
The maximum size in bytes for the client data. If the maximum data size is not specified by the KMS or it is not known, then this field must be filled with all ones.

**KeyIdVariableLenSupported**
TRUE if variable length key identifiers are supported.

FALSE if a fixed length key identifier is supported.

**KeyIdMaxLen**
If `KeyIdVariableLenSupported` is TRUE, this is the maximum supported key identifier length in bytes. Otherwise this is the fixed length of key identifier supported. Key ids shorter than the fixed length will be padded on the right with blanks.
**KeyFormatsCount**
The number of key format/size GUIDs returned in the `KeyFormats` field.

**KeyFormats**
A pointer to an array of `EFI_GUID` values which specify key formats/sizes supported by this KMS. Each format/size pair will be specified by a separate `EFI_GUID`. At least one key format/size must be supported. All formats/sizes with the same hashing algorithm must be contiguous in the array, and for each hashing algorithm, the key sizes must be in ascending order. See “Related Definitions” for GUIDs which identify supported key formats/sizes.

“This list of GUIDs supported by the KMS is not required to be exhaustive, and the KMS may provide support for additional key formats/sizes. Users may request key information using an arbitrary GUID, but any GUID not recognized by the implementation or not supported by the KMS will return an error code of `EFI_UNSUPPORTED`.

**KeyAttributesSupported**
TRUE if key attributes are supported.
FALSE if key attributes are not supported.

**KeyAttributeIdStringTypes**
The key attribute identifier string type(s) supported by the KMS service. If key attributes are not supported, this field will be set to `EFI_KMS_DATA_TYPE_NONE`. Otherwise, it will be set to the inclusive ‘OR’ of all key attribute identifier string types supported. `EFI_KMS_DATA_TYPE_BINARY` is not valid for this field.

**KeyAttributeIdMaxCount**
The maximum number of characters allowed for the client name.

**KeyAttributesCount**
The number of predefined `KeyAttributes` structures returned in the `KeyAttributes` parameter. If the KMS does not support predefined key attributes, or if it does not provide a method to obtain predefined key attributes data, then this field must be zero.

**KeyAttributes**
A pointer to an array of `KeyAttributes` structures which contains the predefined attributes supported by this KMS. Each structure must contain a valid key attribute identifier and should provide any other information as appropriate for the attribute, including a default value if one exists. This variable must be set to `NULL` if the `KeyAttributesCount` variable is zero. It must point to a valid buffer if the `KeyAttributesCount` variable is non-zero.

This list of predefined attributes is not required to be exhaustive, and the KMS may provide additional predefined attributes not enumerated in this list. The implementation does not distinguish between predefined and used defined attributes, and therefore, predefined attributes not enumerated will still be processed to the KMS.

**Related Definitions**
Functions defined for this protocol typically require the caller to provide information about the client, the keys to be processed, and/or attributes of the keys to be processed. Four structures, `EFI_KMS_CLIENT_INFO`, `EFI_KMS_KEY_DESCRIPTOR`, `EFI_KMS_DYNAMIC_ATTRIBUTE`, and `EFI_KMS_KEY_ATTRIBUTE` define the information to be passed to these functions.

```c
typedef struct {  
    UINT16 ClientIdSize;  
    VOID *ClientId;  
    UINT8 ClientNameType;  
    UINT8 ClientNameCount;  
    VOID *ClientName;  
} EFI_KMS_CLIENT_INFO;
```

**ClientIdSize**
The size in bytes for the client identifier.
ClientId
   Pointer to a valid client identifier.

ClientNameType
   The client name string type used by this client. The string type set here must be one of the string types reported in the ClientNameStringTypes field of the KMS protocol. If the KMS does not support client names, this field should be set to EFI_KMS_DATA_TYPE_NONE.

ClientNameCount
   The size in characters for the client name. This field will be ignored if ClientNameStringType is set to EFI_KMS_DATA_TYPE_NONE. Otherwise, it must contain number of characters contained in the ClientName field.

ClientName
   Pointer to a client name. This field will be ignored if ClientNameStringType is set to EFI_KMS_DATA_TYPE_NONE. Otherwise, it must point to a valid string of the specified type.

The key formats recognized by the KMS protocol are defined by an EFI_GUID which specifies a (key-algorithm, key-size) pair. The names of these GUIDs are in the format EFI_KMS_KEY_(key-algorithm)_(key-size)_GUID, where the key-size is expressed in bits. The key formats recognized fall into three categories, generic (no algorithm), hash algorithms, and encrypted algorithms.

Generic Key Data:

The following GUIDs define formats that contain generic key data of a specific size in bits, but which is not associated with any specific key algorithm(s).

```
#define EFI_KMS_FORMAT_GENERIC_128_GUID    
  {0xec8a3d69,0x6ddf,0x4108,\ 
    {0x94,0x76,0x73,0x37,0xfc,0x52,0x21,0x36}}
#define EFI_KMS_FORMAT_GENERIC_160_GUID    
  {0xa3b3e6f8,0xefca,0x4bc1,\ 
    {0x88,0xfb,0xcb,0x87,0x33,0x9b,0x25,0x79}}
#define EFI_KMS_FORMAT_GENERIC_256_GUID    
  {0x70f64793,0xc323,0x4261,\ 
    {0xac,0x2c,0xd8,0x76,0xf2,0x7c,0x53,0x45}}
#define EFI_KMS_FORMAT_GENERIC_512_GUID    
  {0x978fe043,0xd7af,0x422e,\ 
    {0x8a,0x92,0x2b,0x48,0xe4,0x63,0xbd,0xe6}}
#define EFI_KMS_FORMAT_GENERIC_1024_GUID   
  {0x43be0b44,0x874b,0xe4ad,\ 
    {0xb0,0x9c,0x24,0x1a,0x4f,0xbd,0xe7,0xb3}}
#define EFI_KMS_FORMAT_GENERIC_2048_GUID   
  {0xa0093f23,0x630c,0x4626,\ 
    {0xc9,0x48,0x40,0x37,0x3b,0x19,0xcb,0xbe}}
#define EFI_KMS_FORMAT_GENERIC_3072_GUID   
  {0xb9237513,0x6c44,0x4411,\ 
    {0xa9,0x90,0x21,0xe5,0x56,0xe0,0x5a,0xde}}
#define EFI_KMS_FORMAT_GENERIC_DYNAMIC_GUID
```

(continues on next page)
The `EFI_KMS_FORMAT_GENERIC_DYNAMIC_GUID` is defined for the key data with a size not defined by a certain key format GUID. The key value specified by this GUID is in format of structure `EFI_KMS_FORMAT_GENERIC_DYNAMIC`.

```c
typedef struct {
    UINT32 KeySize;
    UINT8 KeyData[1];
} EFI_KMS_FORMAT_GENERIC_DYNAMIC;
```

**KeySize**
Length in bytes of the `KeyData`.

**KeyData**
The data of the key.

**Hash Algorithm Key Data:**
These GUIDS define key data formats that contain data generated by basic hash algorithms with no cryptographic properties.

```c
#define EFI_KMS_FORMAT_MD2_128_GUID \
{0x78be11c4,0xee44,0x4a22,\ 
  {0x9f,0x05,0x03,0x85,0x2e,0xc5,0xc9,0x78}}

#define EFI_KMS_FORMAT_MDC2_128_GUID \
{0xf7ad60f8,0xefa8,0x44a3,\ 
  {0x91,0x13,0x23,0x1f,0x39,0x9e,0xb4,0xc7}}

#define EFI_KMS_FORMAT_MD4_128_GUID \
{0xd1c17aa1,0xcac5,0x400f,0xbe,\ 
  {0x17,0xe2,0xa2,0xae,0x06,0x67,0x7c}}

#define EFI_KMS_FORMAT_MDC4_128_GUID \
{0x3fa4f847,0xd8eb,0x4df4,\ 
  {0xbd,0x49,0x10,0x3a,0x0a,0x84,0x7b,0xbc}}

#define EFI_KMS_FORMAT_MD5_128_GUID \
{0xdcbc3662,0x9cda,0x4b52,\ 
  {0xa0,0x4c,0x82,0xeb,0x1d,0x23,0x48,0xc7}}

#define EFI_KMS_FORMAT_MD5SHA_128_GUID \
{0xcac52b17,0x6c92,0x47a8,\ 
  {0x0d,0x36,0x67,0xce,0x8e,0xf9,0x4f,0x76}}

#define EFI_KMS_FORMAT_SHA1_160_GUID \
{0xa4447c9d,0x0b16,0x48e9,\ 
  {0x87,0xc9,0x59,0x41,0xf3,0xa3,0x8a,0xc2}}

#define EFI_KMS_FORMAT_SHA256_256_GUID \
{0x6bb4f5cd,0x8022,0x448d,\ 
  {0xbc,0x6d,0x77,0x1b,0xae,0x93,0x5f,0xc6}}
```

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Encryption Algorithm Key Data:

These GUIDs define key data formats that contain data generated by cryptographic key algorithms. There may or may not be a separate data hashing algorithm associated with the key algorithm.

The encryption algorithms defined above have the following properties

<table>
<thead>
<tr>
<th>EFI_KMS_FORMAT</th>
<th>Encryption Description</th>
<th>Key Data Size</th>
<th>Hash Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>AESXTS_128</td>
<td>Symmetric encryption using XTS-AES 128 bit keys</td>
<td>Key data is a concatenation of two fields of equal size for a total size of 256 bits</td>
<td>N/A</td>
</tr>
</tbody>
</table>
**Table 37.9 – continued from previous page**

<table>
<thead>
<tr>
<th>Algorithm</th>
<th>Description</th>
<th>Key Size</th>
<th>Status</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>AESXTS_256</strong></td>
<td>Symmetric encryption using block cipher</td>
<td>XTS-AES 256 bit</td>
<td>N/A</td>
</tr>
<tr>
<td><strong>AESCBC_128</strong></td>
<td>Symmetric encryption using block cipher</td>
<td>AES-CBC 128 bit</td>
<td>N/A</td>
</tr>
<tr>
<td><strong>AESCBC_256</strong></td>
<td>Symmetric encryption using block cipher</td>
<td>AES-CBC 256 bit</td>
<td>N/A</td>
</tr>
<tr>
<td><strong>RSASHA1_1024</strong></td>
<td>Asymmetric encryption using block cipher</td>
<td>RSA 1024 bit</td>
<td>SHA1</td>
</tr>
<tr>
<td><strong>RSASHA1_2048</strong></td>
<td>Asymmetric encryption using block cipher</td>
<td>RSA 2048 bit</td>
<td>SHA1</td>
</tr>
<tr>
<td><strong>RSASHA256_2048</strong></td>
<td>Asymmetric encryption using block cipher</td>
<td>RSA 2048 bit</td>
<td>SHA256</td>
</tr>
<tr>
<td><strong>RSASHA256_3072</strong></td>
<td>Asymmetric encryption using block cipher</td>
<td>RSA 3072 bit</td>
<td>SHA256</td>
</tr>
</tbody>
</table>

```c
typedef struct {
    UINT8 KeyIdentifierSize;
    VOID *KeyIdentifier;
    EFI_GUID KeyFormat;
    VOID *KeyValue;
    EFI_STATUS KeyStatus;
} EFI_KMS_KEY_DESCRIPTOR;
```

**KeyIdentifierSize**
The size of the `KeyIdentifier` field in bytes. This field is limited to the range 0 to 255.

**KeyIdentifier**
Pointer to an array of `KeyIdentifierType` elements.

**KeyFormat**
An EFI_GUID which specifies the algorithm and key value size for this key.

**KeyValue**
Pointer to a key value for a key specified by the `KeyFormat` field. A NULL value for this field indicates that no key is available.

**KeyStatus**
Specifies the results of KMS operations performed with this descriptor. This field is used to indicate the status of individual operations when a KMS function is called with multiple `EFI_KMS_KEY_DESCRIPTOR` structures.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Successfully processed this key.</td>
</tr>
<tr>
<td>EFI_WARN_STALE_DATA</td>
<td>Successfully processed this key, however, the key’s parameters exceed internal policies/limits and should be replaced.</td>
</tr>
<tr>
<td>EFI_COMPROMISED_DATA</td>
<td>Successfully processed this key, but the key may have been compromised and must be replaced.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Key format is not supported by the service.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate resources for the key processing.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Timed out waiting for device or key server.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Device or key server error.</td>
</tr>
</tbody>
</table>

continues on next page
### Table 37.10 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>KeyFormat is invalid.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The key does not exist on the KMS.</td>
</tr>
</tbody>
</table>

```c
#define EFI_KMS_ATTRIBUTE_TYPE_NONE 0x00
#define EFI_KMS_ATTRIBUTE_TYPE_INTEGER 0x01
#define EFI_KMS_ATTRIBUTE_TYPE_LONG_INTEGER 0x02
#define EFI_KMS_ATTRIBUTE_TYPE_BIG_INTEGER 0x03
#define EFI_KMS_ATTRIBUTE_TYPE_ENUMERATION 0x04
#define EFI_KMS_ATTRIBUTE_TYPE_BOOLEAN 0x05
#define EFI_KMS_ATTRIBUTE_TYPE_BYTE_STRING 0x06
#define EFI_KMS_ATTRIBUTE_TYPE_TEXT_STRING 0x07
#define EFI_KMS_ATTRIBUTE_TYPE_DATE_TIME 0x08
#define EFI_KMS_ATTRIBUTE_TYPE_INTERVAL 0x09
#define EFI_KMS_ATTRIBUTE_TYPE_STRUCTURE 0x0A
#define EFI_KMS_ATTRIBUTE_TYPE_DYNAMIC 0x0B
```

```c
typedef struct {
    UINT32 FieldCount;
    EFI_KMS_DYNAMIC_FIELD Field[1];
} EFI_KMS_DYNAMIC_ATTRIBUTE;
```

**FieldCount**

The number of members in the `EFI_KMS_DYNAMIC_ATTRIBUTE` structure.

**Field**

An array of `EFI_KMS_DYNAMIC_FIELD` structures.

```c
typedef struct {
    UINT16 Tag;
    UINT16 Type;
    UINT32 Length;
    UINT8 KeyAttributeData[1];
} EFI_KMS_DYNAMIC_FIELD;
```

**Tag**

Part of a tag-type-length triplet that identifies the `KeyAttributeData` formatting. The definition of the value is outside the scope of this standard and may be defined by the KMS.

**Type**

Part of a tag-type-length triplet that identifies the `KeyAttributeData` formatting. The definition of the value is outside the scope of this standard and may be defined by the KMS.

**Length**

Length in bytes of the `KeyAttributeData`.

**KeyAttributeData**

An array of bytes to hold the attribute data associated with the `KeyAttributeIdentifier`.

```c
typedef struct {
    UINT8 KeyAttributeIdentifierType;
    UINT8 KeyAttributeIdentifierCount;
    VOID *KeyAttributeIdentifier;
    UINT16 KeyAttributeInstance;
} EFI_KMS_ATTRIBUTE_IDENTIFIER;
```

(continues on next page)


```c
UINT16   KeyAttributeType;
UINT16   KeyAttributeValueSize;
VOID *   *KeyAttributeValue;
EFI_STATUS   KeyAttributeStatus;
} EFI_KMS_KEY_ATTRIBUTE;
```

### KeyAttributeIdentifierType

The data type used for the `KeyAttributeIdentifier` field. Values for this field are defined by the `EFI_KMS_DATA_TYPE` constants, except that `EFI_KMS_DATA_TYPE_BINARY` is not valid for this field.

### KeyAttributeIdentifierCount

The length of the `KeyAttributeIdentifier` field in units defined by `KeyAttributeIdentifierType` field. This field is limited to the range 0 to 255.

### KeyAttributeIdentifier

Pointer to an array of `KeyAttributeIdentifierType` elements. For string types, there must not be a null-termination element at the end of the array.

### KeyAttributeInstance

The instance number of this attribute. If there is only one instance, the value is set to one. If this value is set to 0xFFFF (all binary 1’s) then this field should be ignored if an output or treated as a wild card matching any value if it is an input. If the attribute is stored with this field, it will match any attribute request regardless of the setting of the field in the request. If set to 0xFFFF in the request, it will match any attribute with the same `KeyAttributeIdentifier`.

### KeyAttributeType

The data type of the `KeyAttributeValue` (e.g. struct, bool, etc.). See the list of `KeyAttributeType` definitions.

### KeyAttributeValueSize

The size in bytes of the `KeyAttribute` field. A value of zero for this field indicates that no key attribute value is available.

### KeyAttributeValue

Pointer to a key attribute value for the attribute specified by the `KeyAttributeIdentifier` field. If the `KeyAttributeValueSize` field is zero, then this field must be `NULL`.

### KeyAttributeStatus

Specifies the results of KMS operations performed with this attribute. This field is used to indicate the status of individual operations when a KMS function is called with multiple `EFI_KMS_KEY_ATTRIBUTE` structures. KeyAttributeStatus codes returned for the individual key attribute requests are:

<table>
<thead>
<tr>
<th>Status Codes Returned</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
</tr>
<tr>
<td>EFI_WARN_STALE_DATA</td>
</tr>
<tr>
<td>EFI_COMPROMISED_DATA</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
</tr>
</tbody>
</table>

### Description

37.3. Key Management Service
The \texttt{EFI_KMS_SERVICE_PROTOCOL} defines a UEFI protocol that can be used by UEFI drivers and applications to access cryptographic keys associated with their operation that are stored and possibly managed by a remote key management service (KMS). For example, a storage device driver may require a set of one or more keys to enable access to regions on the storage devices that it manages.

The protocol can be used to request the generation of new keys from the KMS, to register locally generated keys with the KMS, to retrieve existing keys from the KMS, and to delete obsolete keys from the KMS. It also allows the device driver to manage attributes associated with individual keys on the KMS, and to retrieve keys based on those attributes.

A platform implementing this protocol may use internal or external key servers to provide the functionality required by this protocol. For external servers, the protocol implementation is expected to supply and maintain the connection parameters required to connect and authenticate to the remote server. The connection may be made during the initial installation of the protocol, or it may be delayed until the first \texttt{GetServiceStatus()} request is received.

Each client using the KMS protocol may identify itself to the protocol implementation using a \texttt{EFI_KMS_CLIENT_INFO} structure. If the KMS supported by this protocol requires the client to provide a client identifier, then this structure must be provided on all function calls.

While this protocol is intended to abstract the functions associated with storing and managing keys so that the protocol user does not have to be aware of the specific KMS providing the service, it can also be used by callers which must interact directly with a specific KMS. For these users, the protocol manages the connection to the KMS while the user controls the operational interface via a client data pass thru function.

The \texttt{EFI_KMS_SERVICE_PROTOCOL} provides the capability for the caller to pass arbitrary data to the KMS or to receive such data back from the KMS via parameters on most functions. The use of such data is at the discretion of the caller, but it should only be used sparingly as it reduces the interoperability of the caller’s software.

### 37.3.2 \texttt{EFI_KMS_PROTOCOL.GetServiceStatus()}

#### Summary
Get the current status of the key management service.

#### Prototype

```c
typedef EFI_STATUS
(EFIAPIC *EFI_KMS_GET_SERVICE_STATUS) (
    IN EFI_KMS_PROTOCOL *This
);
```

#### Parameters

- **This**
  
  Pointer to the \texttt{EFI_KEY_MANAGEMENT_SERVICE_PROTOCOL} instance.

#### Description

The \texttt{GetServiceStatus()} function allows the user to query the current status of the KMS and should be called before attempting any operations to the KMS. If the protocol has not been marked as available, then the user must call this function to attempt to initiate the connection to the KMS as it may have been deferred to the first user by the system firmware.

If the connection to the KMS has not yet been established by the system firmware, then this function will attempt to establish the connection, update the protocol structure content as appropriate, and mark the service as available.

#### Status Codes Returned
### 37.3.2.1 EFI_KMS_PROTOCOL.RegisterClient()

**Summary**
Register client information with the supported KMS.

**Prototype**
```c
typedef EFI_STATUS
(EFIAPI *EFI_KMS_REGISTER_CLIENT) (
    IN EFI_KMS_PROTOCOL *This,
    IN EFI_KMS_CLIENT_INFO *Client,
    IN OUT UINTN *ClientDataSize OPTIONAL,
    IN OUT VOID **ClientData OPTIONAL
);
```

**Parameters**

**This**
Pointer to the `EFI_KEY_MANAGEMENT_SERVICE_PROTOCOL` instance.

**Client**
Pointer to a valid `EFI_KMS_CLIENT_INFO` structure.

**ClientDataSize**
Pointer to the size, in bytes, of an arbitrary block of data specified by the `ClientData` parameter. This parameter may be `NULL`, in which case the `ClientData` parameter will be ignored and no data will be transferred to or from the KMS. If the parameter is not `NULL`, then `ClientData` must be a valid pointer. If the value pointed to is 0, no data will be transferred to the KMS, but data may be returned by the KMS. For all non-zero values `ClientData` will be transferred to the KMS, which may also return data to the caller. In all cases, the value upon return to the caller will be the size of the data block returned to the caller, which will be zero if no data is returned from the KMS.

**ClientData**
Pointer to a pointer to an arbitrary block of data of `ClientDataSize` that is to be passed directly to the KMS if it supports the use of client data. This parameter may be `NULL` if and only if the `ClientDataSize` parameter is also `NULL`. Upon return to the caller, `ClientData points to a block of data of * *ClientDataSize` that was returned from the KMS. If the returned value for `ClientDataSize` is zero, then the returned value for `ClientData` must be `NULL` and should be ignored by the caller. The KMS protocol consumer is responsible for freeing all valid buffers used for client data regardless of whether they are allocated by the caller for input to the function or by the implementation for output back to the caller.

**Description**
The `RegisterClient()` function registers client information with the KMS using a `EFI_KMS_CLIENT_INFO` structure.

There are two methods of handling client information. The caller may supply a client identifier in the `EFI_KMS_CLIENT_INFO` structure prior to making the call along with an optional name string. The client identifier will be passed on to the KMS if it supports client identifiers. If the KMS accepts the client id, then the
**EFI_KMS_CLIENT_INFO** structure will be returned to the caller unchanged. If the KMS does not accept the client id, it may simply reject the request, or it may supply an alternate identifier of its own.

The caller may also request a client identifier from the KMS by passing NULL values in the **EFI_KMS_CLIENT_INFO** structure. If the KMS supports this action, it will generate the identifier and return it in the structure. Otherwise, the implementation may generate a unique identifier, returning it in the structure, or it may indicate that the function is unsupported.

The **ClientDataSize** and **ClientData** parameters allow the caller to pass an arbitrary block of data to/from the KMS for uses such as auditing or access control. The KMS protocol implementation does not alter this data block other than to package it for transmission to the KMS. The use of these parameters is optional.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EFI_SUCCESS</strong></td>
<td>The client information has been accepted by the KMS.</td>
</tr>
<tr>
<td><strong>EFI_NOT_READY</strong></td>
<td>No connection to the KMS is available.</td>
</tr>
<tr>
<td><strong>EFI_NO_RESPONSE</strong></td>
<td>There was no response from the device or the key server.</td>
</tr>
<tr>
<td><strong>EFI_ACCESS_DENIED</strong></td>
<td>Access was denied by the device or the key server.</td>
</tr>
<tr>
<td><strong>EFI_DEVICE_ERROR</strong></td>
<td>An error occurred when attempting to access the KMS.</td>
</tr>
<tr>
<td><strong>EFI_OUT_OF_RESOURCES</strong></td>
<td>Required resources were not available to perform the function.</td>
</tr>
<tr>
<td><strong>EFI_INVALID_PARAMETER</strong></td>
<td>This is NULL.</td>
</tr>
<tr>
<td><strong>EFI_UNSUPPORTED</strong></td>
<td>The KMS does not support the use of client identifiers.</td>
</tr>
</tbody>
</table>

### 37.3.2.2 EFI_KMS_PROTOCOL.CreateKey()

**Summary**

Request that the KMS generate one or more new keys and associate them with key identifiers. The key value(s) is returned to the caller.

**Prototype**

```c
typedef
EFI_STATUS
(EIFIAPI *EFI_KMS_CREATE_KEY) (  
    IN  EFI_KMS_PROTOCOL      *This,    
    IN  EFI_KMS_CLIENT_INFO   *Client,  
    IN OUT UINT16             *KeyDescriptorCount,  
    IN OUT EFI_KMS_KEY_DESCRIPTOR   *KeyDescriptors,  
    IN OUT UINTN              *ClientDataSize OPTIONAL,  
    IN OUT VOID               **ClientData OPTIONAL
);
```

**Parameters**

**This**

Pointer to this **EFI_KMS_PROTOCOL** instance.

**Client**

Pointer to a valid **EFI_KMS_CLIENT_INFO** structure.

**KeyDescriptorCount**

Pointer to a count of the number of key descriptors to be processed by this operation. On return, this number will be updated with the number of key descriptors successfully processed.

**KeyDescriptors**

Pointer to an array of **EFI_KMS_KEY_DESCRIPTOR** structures which describe the keys to be generated.
On input, the KeyIdentifierSize and the KeyIdentifier may specify an identifier to be used for the key, but this is not required. The KeyFormat field must specify a key format GUID reported as supported by the KeyFormats field of the EFI_KMS_PROTOCOL. The value for this field in the first key descriptor will be considered the default value for subsequent key descriptors requested in this operation if those key descriptors have a NULL GUID in the key format field.

On output, the KeyIdentifierSize and KeyIdentifier fields will specify an identifier for the key which will be either the original identifier if one was provided, or an identifier generated either by the KMS or the KMS protocol implementation. The KeyFormat field will be updated with the GUID used to generate the key if it was a NULL GUID, and the KeyValue field will contain a pointer to memory containing the key value for the generated key. Memory for both the KeyIdentifier and the KeyValue fields will be allocated with the BOOT_SERVICES_DATA type and must be freed by the caller when it is no longer needed. Also, the KeyStatus field must reflect the result of the request relative to that key.

ClientDataSize

Pointer to the size, in bytes, of an arbitrary block of data specified by the ClientData parameter. This parameter may be NULL in which case the ClientData parameter will be ignored and no data will be transferred to or from the KMS. If the parameter is not NULL, then ClientData must be a valid pointer. If the value pointed to is 0, no data will be transferred to the KMS, but data may be returned by the KMS. For all non-zero values ClientData will be transferred to the KMS, which may also return data to the caller. In all cases, the value upon return to the caller will be the size of the data block returned to the caller, which will be zero if no data is returned from the KMS.

ClientData

Pointer to a pointer to an arbitrary block of data of *ClientDataSize that is to be passed directly to the KMS if it supports the use of client data. This parameter may be NULL if and only if the ClientDataSize parameter is also NULL. Upon return to the caller, *ClientData points to a block of data of *ClientDataSize that was returned from the KMS. If the returned value for *ClientDataSize is zero, then the returned value for *ClientData must be NULL and should be ignored by the caller. The KMS protocol consumer is responsible for freeing all valid buffers used for client data regardless of whether they are allocated by the caller for input to the function or by the implementation for output back to the caller.

Description

The CreateKey() method requests the generation of one or more new keys, and key identifier and key values are returned to the caller. The support of this function is optional as some key servers do not provide a key generation capability.

The Client parameter identifies the caller to the key management service. This identifier may be used for auditing or access control. This parameter is optional unless the KMS requires a client identifier in order to perform the requested action.

The KeyDescriptorCount and KeyDescriptors parameters are used to specify the key algorithm, size, and attributes for the requested keys. Any number of keys may be requested in a single operation, regardless of whether the KMS supports multiple key definitions in a single request or not. The KMS protocol implementation is responsible for generating the appropriate requests (single/multiple) to the KMS.

The ClientDataSize and ClientData parameters allow the caller to pass an arbitrary block of data to/from the KMS for uses such as auditing or access control. The KMS protocol implementation does not alter this data block other than to package it for transmission to the KMS. The use of these parameters is optional.

Status Codes Returned

The CreateKey() function will return a status which indicates the overall status of the request. Note that this may be different from the status reported for individual key requests.

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Successfully generated and retrieved all requested keys.</td>
</tr>
</tbody>
</table>

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Table 37.14 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>This function is not supported by the KMS. –OR– One (or more) of the key requests submitted is not supported by the KMS. Check individual key request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Required resources were not available for the operation.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Timed out waiting for device or key server. Check individual key request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Access was denied by the device or the key server; OR a ClientId is required by the server and either no id was provided or an invalid id was provided</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An error occurred when attempting to access the KMS. Check individual key request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL, ClientId is required but it is NULL, KeyDescriptorCount is NULL, or Keys is NULL</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>One or more EFI_KMS_KEY_DESCRIPTOR structures could not be processed properly. KeyDescriptorCount contains the number of structures which were successfully processed. Individual structures will reflect the status of the processing for that structure.</td>
</tr>
</tbody>
</table>

37.3.2.3 EFI_KMS_PROTOCOL.GetKey()

Summary
Retrieve an existing key.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_KMS_GET_KEY) (
    IN EFI_KMS_PROTOCOL *This,
    IN EFI_KMS_CLIENT_INFO *Client,
    IN OUT UINT16 *KeyDescriptorCount,
    IN OUT EFI_KMS_KEY_DESCRIPTOR *KeyDescriptors,
    IN OUT UINTN *ClientDataSize OPTIONAL,
    IN OUT VOID **ClientData OPTIONAL
    );
```

Parameters

This
Pointer to this EFI_KMS_PROTOCOL instance.

Client
Pointer to a valid EFI_KMS_CLIENT_INFO structure.

KeyDescriptorCount
Pointer to a count of the number of keys to be processed by this operation. On return, this number will be updated with number of keys successfully processed.

KeyDescriptors
Pointer to an array of EFI_KMS_KEY_DESCRIPTOR structures which describe the keys to be retrieved from the KMS. On input, the KeyIdentifierSize and the KeyIdentifier must specify an identifier to be used to retrieve a specific key. All other fields in the descriptor should be NULL. On output, the KeyIdentifierSize and KeyIdentifier fields will be unchanged, while the KeyFormat and KeyValue fields will be updated values associated with this key identifier. Memory for the KeyValue field will be allocated with the BOOT_SERVICES_DATA type and must

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be freed by the caller when it is no longer needed. Also, the KeyStatus field will reflect the result of the request relative to the individual key descriptor.

ClientDataSize

 Pointer to the size, in bytes, of an arbitrary block of data specified by the ClientData parameter. This parameter may be NULL in which case the ClientData parameter will be ignored and no data will be transferred to or from the KMS. If the parameter is not NULL, then ClientData must be a valid pointer. If the value pointed to is 0, no data will be transferred to the KMS, but data may be returned by the KMS. For all non-zero values **ClientData* will be transferred to the KMS, which may also return data to the caller. In all cases, the value upon return to the caller will be the size of the data block returned to the caller, which will be zero if no data is returned from the KMS.

ClientData

 Pointer to a pointer to an arbitrary block of data of * ClientDataSize that is to be passed directly to the KMS if it supports the use of client data. This parameter may be NULL if and only if the ClientDataSize parameter is also NULL. Upon return to the caller, * ClientData points to a block of data of * ClientDataSize that was returned from the KMS. If the returned value for **ClientDataSize* is zero, then the returned value for **ClientData* must be NULL and should be ignored by the caller. The KMS protocol consumer is responsible for freeing all valid buffers used for client data regardless of whether they are allocated by the caller for input to the function or by the implementation for output back to the caller.

Description

The GetKey() function retrieves one or more existing keys from the KMS and returns the key values to the caller. This function must be supported by every KMS protocol instance.

The Client parameter identifies the caller to the key management service. It may be used for auditing or access control. The use of this parameter is optional unless the KMS requires it in order to perform the requested action.

The KeyDescriptorCount and KeyDescriptors parameters are used to specify the identifier(s) to be used to retrieve the key values, which will be returned in the KeyFormat and KeyValue fields of each EFI_KMS_KEY_DESCRIPTOR structure. Any number of keys may be requested in a single operation, regardless of whether the KMS supports multiple key definitions in a single request or not. The KMS protocol implementation is responsible for generating the appropriate requests (single/multiple) to the KMS.

The ClientDataSize and ClientData parameters allow the caller to pass an arbitrary block of data to/from the KMS for uses such as auditing or access control. The KMS protocol implementation does not alter this data block other than to package it for transmission to the KMS. The use of these parameters is optional.

Status Codes Returned

The GetKey() function will return a status which indicates the overall status of the request. Note that this may be different from the status reported for individual key requests.

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Successfully retrieved all requested keys.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate resources for the method processing.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Timed out waiting for device or key server. Check individual key request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>If multiple keys are associated with a single identifier, and the KeyValue buffer does not contain enough structures (KeyDescriptorCount) to contain all the key data, then the available structures will be filled and KeyDescriptorCount will be updated to indicate the number of keys which could not be processed.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Access was denied by the device or the key server; OR a ClientId is required by the server and either none or an invalid id was provided</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Device or key server error. Check individual key request(s) to see which ones may have been processed.</td>
</tr>
</tbody>
</table>

continues on next page
Table 37.15 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL, ClientId is required but it is NULL, KeyDescriptorCount is NULL, or Keys is NULL</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>One or more EFI_KMS_KEY_DESCRIPTOR structures could not be processed properly. KeyDescriptorCount contains the number of structures which were successfully processed. Individual structures will reflect the status of the processing for that structure.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation/KMS does not support this function</td>
</tr>
</tbody>
</table>

37.3.2.4 EFI_KMS_PROTOCOL.AddKey()

Summary
Add a new key.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_KMS_ADD_KEY) (  
    IN EFI_KMS_PROTOCOL *This,  
    IN EFI_KMS_CLIENT_INFO *Client,  
    IN OUT UINT16 *KeyDescriptorCount,  
    IN OUT EFI_KMS_KEY_DESCRIPTOR *KeyDescriptors,  
    IN OUT UINTN *ClientDataSize OPTIONAL,  
    IN OUT VOID **ClientData OPTIONAL  
);

Parameters

This
Pointer to this EFI_KMS_PROTOCOL instance.

Client
Pointer to a valid EFI_KMS_CLIENT_INFO structure.

KeyDescriptorCount
Pointer to a count of the number of keys to be processed by this operation. On normal returns, this number will be updated with number of keys successfully processed.

KeyDescriptors
Pointer to an array of EFI_KMS_KEY_DESCRIPTOR structures which describe the keys to be added. On input, the KeyId field for first key must contain valid identifier data to be used for adding a key to the KMS. The values for these fields in this key definition will be considered default values for subsequent keys requested in this operation. A value of 0 in any subsequent KeyId field will be replaced with the current default value. The KeyFormat and KeyValue fields for each key to be added must contain consistent values to be associated with the given KeyId. On return, the KeyStatus field will reflect the result of the operation for each key request.

ClientDataSize
Pointer to the size, in bytes, of an arbitrary block of data specified by the ClientData parameter. This parameter may be NULL, in which case the ClientData parameter will be ignored and no data will be transferred to or from the KMS. If the parameter is not NULL, then ClientData must be a valid pointer. If the value pointed to is 0, no data will be transferred to the KMS, but data may be returned by the KMS. For all non-zero values **ClientData* will be transferred to the KMS, which may also return data to the caller. In all cases, the value upon return to the caller will be the size of the data block returned to the caller, which will be zero if no data is returned from the KMS.
ClientData

Pointer to a pointer to an arbitrary block of data of **ClientDataSize** that is to be passed directly to the KMS if it supports the use of client data. This parameter may be NULL if and only if the ClientDataSize parameter is also NULL. Upon return to the caller, **ClientData** points to a block of data of **ClientDataSize** that was returned from the KMS. If the returned value for **ClientDataSize** is zero, then the returned value for **ClientData** must be NULL and should be ignored by the caller. The KMS protocol consumer is responsible for freeing all valid buffers used for client data regardless of whether they are allocated by the caller for input to the function or by the implementation for output back to the caller.

Description

The AddKey() function registers a new key with the key management service. The support for this method is optional, as not all key servers support importing keys from clients.

The Client parameter identifies the caller to the key management service. It may be used for auditing or access control. The use of this parameter is optional unless the KMS requires it in order to perform the requested action.

The KeyDescriptorCount and KeyDescriptors parameters are used to specify the key identifier, key format and key data to be registered on the. Any number of keys may be registered in a single operation, regardless of whether the KMS supports multiple key definitions in a single request or not. The KMS protocol implementation is responsible for generating the appropriate requests (single/multiple) to the KMS.

The ClientDataSize and ClientData parameters allow the caller to pass an arbitrary block of data to/from the KMS for uses such as auditing or access control. The KMS protocol implementation does not alter this data block other than to package it for transmission to the KMS. The use of these parameters is optional.

Status Codes Returned

The AddKey() function will return a status which indicates the overall status of the request. Note that this may be different from the status reported for individual key requests.

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Successfully added all requested keys.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate required resources.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Timed out waiting for device or key server. Check individual key request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>If multiple keys are associated with a single identifier, and the KeyValue buffer does not contain enough structures (KeyDescriptorCount) to contain all the key data, then the available structures will be filled and KeyDescriptorCount will be updated to indicate the number of keys which could not be processed.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Access was denied by the device or the key server; OR a ClientId is required by the server and either none or an invalid id was provided</td>
</tr>
<tr>
<td>EFIDEVICE_ERROR</td>
<td>Device or key server error. Check individual key request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL, ClientId is required but it is NULL, <em>KeyDescriptorCount</em> is NULL, or Keys is NULL</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>One or more EFI_KMS_KEY_DESCRIPTOR structures could not be processed properly. KeyDescriptorCount contains the number of structures which were successfully processed. Individual structures will reflect the status of the processing for that structure.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation/KMS does not support this function</td>
</tr>
</tbody>
</table>
37.3.2.5 EFI_KMS_PROTOCOL.DeleteKey()

Summary
Delete an existing key from the KMS database.

Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_KMS_DELETE_KEY) (
    IN EFI_KMS_PROTOCOL *This,
    IN EFI_KMS_CLIENT_INFO *Client,
    IN OUT UINT16 *KeyDescriptorCount,
    IN OUT EFI_KMS_KEY_DESCRIPTOR *KeyDescriptors,
    IN OUT UINTN *ClientDataSize OPTIONAL,
    IN OUT VOID **ClientData OPTIONAL
);
```

Parameters

**This**
Pointer to this EFI_KMS_PROTOCOL instance.

**Client**
Pointer to a valid EFI_KMS_CLIENT_INFO structure.

**KeyDescriptorCount**
Pointer to a count of the number of keys to be processed by this operation. On normal returns, this number will be updated with number of keys successfully processed.

**KeyDescriptors**
Pointer to an array of EFI_KMS_KEY_DESCRIPTOR structures which describe the keys to be deleted. On input, the KeyId field for first key must contain valid identifier data to be used for adding a key to the KMS. The values for these fields in this key definition will be considered default values for subsequent keys requested in this operation. A value of 0 in any subsequent KeyId field will be replaced with the current default value. The KeyFormat and KeyValue fields are ignored, but should be 0. On return, the KeyStatus field will reflect the result of the operation for each key request.

**ClientDataSize**
Pointer to the size, in bytes, of an arbitrary block of data specified by the ClientData parameter. This parameter may be NULL, in which case the ClientData parameter will be ignored and no data will be transferred to or from the KMS. If the parameter is not NULL, then ClientData must be a valid pointer. If the value pointed to is 0, no data will be transferred to the KMS, but data may be returned by the KMS. For all non-zero values **ClientData** will be transferred to the KMS, which may also return data to the caller. In all cases, the value upon return to the caller will be the size of the data block returned to the caller, which will be zero if no data is returned from the KMS.

**ClientData**
Pointer to a pointer to an arbitrary block of data of **ClientDataSize* that is to be passed directly to the KMS if it supports the use of client data. This parameter may be NULL if and only if the ClientDataSize parameter is also NULL. Upon return to the caller, **ClientData* points to a block of data of **ClientDataSize* that was returned from the KMS. If the returned value for **ClientDataSize* is zero, then the returned value for **ClientData* must be NULL and should be ignored by the caller. The KMS protocol consumer is responsible for freeing all valid buffers used for client data regardless of whether they are allocated by the caller for input to the function or by the implementation for output back to the caller.
Description

The `DeleteKey()` function deregisters an existing key from the device or KMS. The support for this method is optional, as not all key servers support deleting keys from clients.

The `Client` parameter identifies the caller to the key management service. It may be used for auditing or access control. The use of this parameter is optional unless the KMS requires it in order to perform the requested action.

The `KeyDescriptorCount` and `KeyDescriptors` parameters are used to specify the key identifier(s) for the keys to be deleted. Any number of keys may be deleted in a single operation, regardless of whether the KMS supports multiple key definitions in a single request or not. The KMS protocol implementation is responsible for generating the appropriate requests (single/multiple) to the KMS.

The `ClientDataSize` and `ClientData` parameters allow the caller to pass an arbitrary block of data to/from the KMS for uses such as auditing or access control. The KMS protocol implementation does not alter this data block other than to package it for transmission to the KMS. The use of these parameters is optional.

Status Codes Returned

The `DeleteKey()` function will return a status which indicates the overall status of the request. Note that this may be different from the status reported for individual key requests.

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Successfully deleted all requested keys.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate required resources.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Timed out waiting for device or key server. Check individual key request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Access was denied by the device or the key server; OR a ClientId is required by the server and either none or an invalid id was provided</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Device or key server error. Check individual key request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL, ClientId is required but it is NULL, KeyDescriptorCount is NULL, or Keys is NULL</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>One or more EFI_KMS_KEY_DESCRIPTOR structures could not be processed properly. KeyDescriptorCount contains the number of structures which were successfully processed. Individual structures will reflect the status of the processing for that structure.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation/KMS does not support this function</td>
</tr>
</tbody>
</table>

37.3.2.6 EFI_KMS_PROTOCOL.GetKeyAttributes()

Summary

Get one or more attributes associated with a specified key identifier. If none are found, the returned attributes count contains a value of zero.

Prototype

```c
typedef EFI_STATUS
    (EFIAPI *EFI_KMS_GET_KEY_ATTRIBUTES) ( 
    IN EFI_KMS_PROTOCOL *This, 
    IN EFI_KMS_CLIENT_INFO *Client, 
    IN UINT8 *KeyIdentifierSize, 
    IN CONST VOID *KeyIdentifier, 
    IN OUT UINT16 *KeyAttributesCount, 
    IN OUT EFI_KMS_KEY_ATTRIBUTE *KeyAttributes)
```

(continues on next page)
Parameters

This

Pointer to this EFI_KMS_PROTOCOL instance.

Client

Pointer to a valid EFI_KMS_CLIENT_INFO structure.

KeyIdentifierSize

Pointer to the size in bytes of the KeyIdentifier variable.

KeyIdentifier

Pointer to the key identifier associated with this key.

KeyAttributesCount

Pointer to the number of EFI_KMS_KEY_ATTRIBUTE structures associated with the Key identifier. If none are found, the count value is zero on return. On input this value reflects the number of KeyAttributes that may be returned. On output, the value reflects the number of completed KeyAttributes structures found.

KeyAttributes

Pointer to an array of EFI_KMS_KEY_ATTRIBUTE structures associated with the Key Identifier. On input, the fields in the structure should be NULL. On output, the attribute fields will have updated values for attributes associated with this key identifier.

ClientDataSize

Pointer to the size, in bytes, of an arbitrary block of data specified by the ClientData parameter. This parameter may be NULL, in which case the ClientData parameter will be ignored and no data will be transferred to or from the KMS. If the parameter is not NULL, then ClientData must be a valid pointer. If the value pointed to is 0, no data will be transferred to the KMS, but data may be returned by the KMS. For all non-zero values *ClientData will be transferred to the KMS, which may also return data to the caller. In all cases, the value upon return to the caller will be the size of the data block returned to the caller, which will be zero if no data is returned from the KMS.

ClientData

Pointer to a pointer to an arbitrary block of data of *ClientDataSize that is to be passed directly to the KMS if it supports the use of client data. This parameter may be NULL if and only if the ClientDataSize parameter is also NULL. Upon return to the caller, *ClientData points to a block of data of *ClientDataSize that was returned from the KMS. If the returned value for *ClientDataSize is zero, then the returned value for *ClientData must be NULL and should be ignored by the caller. The KMS protocol consumer is responsible for freeing all valid buffers used for client data regardless of whether they are allocated by the caller for input to the function or by the implementation for output back to the caller.

Description

The GetKeyAttributes() function returns one or more attributes for a key.

The ClientIdentifierSize and ClientIdentifier parameters identify the caller to the key management service. It may be used for auditing or access control. The use of this parameter is optional unless the KMS requires it in order to perform the requested action.

The KeyIdentifierSize and KeyIdentifier parameters identify the key whose attributes are to be returned by the key management service. They may be used to retrieve additional information about a key, whose format is defined by the KeyAttribute. Attributes returned may be of the same or different names.
The `ClientDataSize` and `ClientData` parameters allow the caller to pass an arbitrary block of data to/from the KMS for uses such as auditing or access control. The KMS protocol implementation does not alter this data block other than to package it for transmission to the KMS. The use of these parameters is optional unless the KMS requires it in order to perform the requested action.

### Status Codes Returned

The `GetKeyAttributes()` function will return a status which indicates the overall status of the request. Note that this may be different from the status reported for individual key attribute requests.

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Successfully retrieved all key attributes.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate resources for the method processing.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Timed out waiting for device or key server. Check individual key attribute request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>If multiple key attributes are associated with a single identifier, and the Key-Attributes buffer does not contain enough structures (KeyAttributesCount) to contain all the key attributes data, then the available structures will be filled and KeyAttributesCount will be updated to indicate the number of key attributes which could not be processed.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Access was denied by the device or the key server; OR a ClientId is required by the server and either none or an invalid id was provided.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Device or key server error. Check individual key attribute request(s) (i.e., key attribute status for each) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL, ClientId is required but it is NULL, KeyIdentifierSize is NULL, or KeyIdentifier is NULL, or KeyAttributes is NULL, or KeyAttributesSize is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The KeyIdentifier could not be found. KeyAttributesCount contains zero. Individual structures will reflect the status of the processing for that structure.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation/KMS does not support this function.</td>
</tr>
</tbody>
</table>

### 37.3.2.7 EFI_KMS_PROTOCOL.AddKeyAttributes()

#### Summary

Add one or more attributes to a key specified by a key identifier.

#### Prototype

```c
typedef
EFI_STATUS
(EFIAPI *EFI_KMS_ADD_KEY_ATTRIBUTES) (  
   IN EFI_KMS_PROTOCOL This,  
   IN EFI_KMS_CLIENT_INFO Client,  
   IN UINT KeyIdentifierSize,  
   IN CONST VOID KeyIdentifier,  
   IN OUT UINT16 KeyAttributesCount,  
   IN OUT EFI_KMS_KEY_ATTRIBUTE KeyAttributes,  
   IN OUT UINTW ClientDataSize OPTIONAL,  
   IN OUT VOID **ClientData OPTIONAL
);
```

#### Parameters
This
  Pointer to this EFI_KMS_PROTOCOL instance.

Client
  Pointer to a valid EFI_KMS_CLIENT_INFO structure.

KeyIdentifierSize
  Pointer to the size in bytes of the KeyIdentifier variable.

KeyIdentifier
  Pointer to the key identifier associated with this key.

KeyAttributesCount
  Pointer to the number of EFI_KMS_KEY_ATTRIBUTE structures to associate with the Key. On normal returns, this number will be updated with the number of key attributes successfully processed.

KeyAttributes
  Pointer to an array of EFI_KMS_KEY_ATTRIBUTE structures providing the attribute information to associate with the key. On input, the values for the fields in the structure are completely filled in. On return the KeyAttributeStatus field will reflect the result of the operation for each key attribute request.

ClientDataSize
  Pointer to the size, in bytes, of an arbitrary block of data specified by the ClientData parameter. This parameter may be NULL, in which case the ClientData parameter will be ignored and no data will be transferred to or from the KMS. If the parameter is not NULL, then ClientData must be a valid pointer. If the value pointed to is 0, no data will be transferred to the KMS, but data may be returned by the KMS. For all non-zero values *ClientData will be transferred to the KMS, which may also return data to the caller. In all cases, the value upon return to the caller will be the size of the data block returned to the caller, which will be zero if no data is returned from the KMS.

ClientData
  Pointer to a pointer to an arbitrary block of data of *ClientDataSize that is to be passed directly to the KMS if it supports the use of client data. This parameter may be NULL if and only if the ClientDataSize parameter is also NULL. Upon return to the caller, *ClientData points to a block of data of *ClientDataSize that was returned from the KMS. If the returned value for *ClientDataSize is zero, then the returned value for *ClientData must be NULL and should be ignored by the caller. The KMS protocol consumer is responsible for freeing all valid buffers used for client data regardless of whether they are allocated by the caller for input to the function or by the implementation for output back to the caller.

Description
The AddKeyAttributes() function adds one or more key attributes. If this function is not supported by a KMS protocol instance then it is assumed that there is an alternative means available for attribute management in the KMS.

The Client parameters identify the caller to the key management service. It may be used for auditing or access control. The use of this parameter is optional unless the KMS requires it in order to perform the requested action.

The KeyIdentifierSize and KeyIdentifier parameters identify the key whose attributes are to be modified by the key management service.

The KeyAttributesCount and KeyAttributes parameters are used to specify the key attributes data to be registered on the KMS. Any number of attributes may be registered in a single operation, regardless of whether the KMS supports multiple key attribute definitions in a single request or not. The KMS protocol implementation is responsible for generating the appropriate requests (single/multiple) to the KMS. In certain error situations, the status of each attribute is updated indicating if that attribute was successfully registered or not.

The ClientDataSize and ClientData parameters allow the caller to pass an arbitrary block of data to/from the KMS for uses such as auditing or access control. The KMS protocol implementation does not alter this data block other than to package it for transmission to the KMS. The use of these parameters is optional unless the KMS requires it in order to perform the requested action.
Status Codes Returned

The `AddKeyAttributes()` function will return a status which indicates the overall status of the request. Note that this may be different from the status reported for individual key attribute requests. Status codes returned for `AddKeyAttributes()` are:

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>Successfully added all requested key attributes.</td>
</tr>
<tr>
<td><code>EFI_OUT_OF_RESOURCES</code></td>
<td>Could not allocate required resources.</td>
</tr>
<tr>
<td><code>EFI_TIMEOUT</code></td>
<td>Timed out waiting for device or key server. Check individual key attribute request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td><code>EFI_BUFFER_TOO_SMALL</code></td>
<td>If multiple keys attributes are associated with a single key identifier, and the attributes buffer does not contain enough structures (<code>KeyAttributesCount</code>) to contain all the data, then the available structures will be filled and <code>KeyAttributesCount</code> will be updated to indicate the number of key attributes which could not be processed. The status of each key attribute is also updated indicating success or failure for that attribute in case there are other errors for those attributes that could be processed.</td>
</tr>
<tr>
<td><code>EFI_ACCESS_DENIED</code></td>
<td>Access was denied by the device or the key server; OR a <code>ClientId</code> is required by the server and either none or an invalid id was provided.</td>
</tr>
<tr>
<td><code>EFI_DEVICE_ERROR</code></td>
<td>Device or key server error. Check individual key attribute request(s) (i.e., <code>KeyAttributesCount</code>) to see which ones may have been processed.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td>This is NULL, <code>ClientId</code> is required but it is NULL, <code>KeyAttributesCount</code> is NULL, or <code>KeyAttributes</code> is NULL, or <code>KeyIdentifierSize</code> is NULL, or <code>KeyIdentifier</code> is NULL.</td>
</tr>
<tr>
<td><code>EFI_NOT_FOUND</code></td>
<td>The <code>KeyIdentifier</code> could not be found. On return the <code>KeyAttributesCount</code> contains the number of attributes processed. Individual structures will reflect the status of the processing for that structure.</td>
</tr>
<tr>
<td><code>EFI_UNSUPPORTED</code></td>
<td>The implementation/KMS does not support this function.</td>
</tr>
</tbody>
</table>

37.3.2.8 `EFI_KMS_PROTOCOL.DeleteKeyAttributes()`

Summary

Delete attributes to a key specified by a key identifier.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_KMS_DELETE_KEY_ATTRIBUTES) ( 
    IN EFI_KMS_PROTOCOL *This, 
    IN EFI_KMS_CLIENT_INFO *Client, 
    IN UINT8 *KeyIdentifierSize, 
    IN CONST VOID *KeyIdentifier, 
    IN OUT UINT16 *KeyAttributesCount, 
    IN OUT EFI_KMS_KEY_ATTRIBUTE *KeyAttributes, 
    IN OUT UINTN *ClientDataSize OPTIONAL, 
    IN OUT VOID **ClientData OPTIONAL 
);
```

Parameters

This

Pointer to this `EFI_KMS_PROTOCOL` instance.
Client
   Pointer to a valid EFI_KMS_CLIENT_INFO structure.

KeyIdentifierSize
   Pointer to the size in bytes of the KeyIdentifier variable.

KeyIdentifier
   Pointer to the key identifier associated with this key.

KeyAttributesCount
   Pointer to the number of EFI_KMS_KEY_ATTRIBUTE structures associated with the Key. On input, the count value is one or more. On normal returns, this number will be updated with the number of key attributes successfully processed.

KeyAttributes
   Pointer to an array of EFI_KMS_KEY_ATTRIBUTE structures associated with the key. On input, the values for the fields in the structure are completely filled in. On return the KeyAttributeStatus field will reflect the result of the operation for each key attribute request.

ClientDataSize
   Pointer to the size, in bytes, of an arbitrary block of data specified by the ClientData parameter. This parameter may be NULL, in which case the ClientData parameter will be ignored and no data will be transferred to or from the KMS. If the parameter is not NULL, then ClientData must be a valid pointer. If the value pointed to is 0, no data will be transferred to the KMS, but data may be returned by the KMS. For all non-zero values *ClientData will be transferred to the KMS, which may also return data to the caller. In all cases, the value upon return to the caller will be the size of the data block returned to the caller, which will be zero if no data is returned from the KMS.

ClientData
   Pointer to a pointer to an arbitrary block of data of *ClientDataSize that is to be passed directly to the KMS if it supports the use of client data. This parameter may be NULL if and only if the ClientDataSize parameter is also NULL. Upon return to the caller, *ClientData points to a block of data of *ClientDataSize that was returned from the KMS. If the returned value for ClientDataSize is zero, then the returned value for *ClientData must be NULL and should be ignored by the caller. The KMS protocol consumer is responsible for freeing all valid buffers used for client data regardless of whether they are allocated by the caller for input to the function or by the implementation for output back to the caller.

Description
The DeleteKeyAttributes() function removes key attributes for a key with the key management service.

The Client parameter identifies the caller to the key management service. It may be used for auditing or access control. The use of this parameter is optional unless the KMS requires it in order to perform the requested action.

The KeyIdentifierSize and KeyIdentifier parameters identify the key whose attributes are to be modified by the key management service.

The KeyAttributesCount and KeyAttributes parameters are used to specify the key attributes data to be deleted on the KMS. Any number of attributes may be deleted in a single operation, regardless of whether the KMS supports multiple key attribute definitions in a single request or not. The KMS protocol implementation is responsible for generating the appropriate requests (single/multiple) to the KMS. In certain error situations, the status of each attribute is updated indicating if that attribute was successfully deleted or not.

The KeyAttributesCount and KeyAttributes parameters are used to specify the key attributes data to be deleted on the KMS. Any number of attributes may be deleted in a single operation, regardless of whether the KMS supports multiple key attribute definitions in a single request or not. The KMS protocol implementation is responsible for generating the appropriate requests (single/multiple) to the KMS. In certain error situations, the status of each attribute is updated indicating if that attribute was successfully deleted or not.

The ClientDataSize and ClientData parameters allow the caller to pass an arbitrary block of data to/from the KMS for
uses such as auditing or access control. The KMS protocol implementation does not alter this data block other than to package it for transmission to the KMS. The use of these parameters is optional unless the KMS requires it in order to perform the requested action.

**Status Codes Returned**

The DeleteKeyAttributes() function will return a status which indicates the overall status of the request. Note that this may be different from the status reported for individual key attribute requests. Status codes returned for the method are:

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Successfully deleted all requested key attributes.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate required resources.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Timed out waiting for device or key server. Check individual key attribute request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Access was denied by the device or the key server; OR a ClientId is required by the server and either none or an invalid id was provided</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Device or key server error. Check individual key attribute request(s) (i.e., key attribute status for each) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL, ClientId is required but it is NULL, KeyAttributesCount is NULL, or KeyAttributes is NULL, or KeyIdentifierSize is NULL, or KeyIdentifier is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>The KeyIdentifier could not be found or the attribute could not be found. On return the KeyAttributesCount contains the number of attributes processed. Individual structures will reflect the status of the processing for that structure.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation/KMS does not support this function</td>
</tr>
</tbody>
</table>

### 37.3.2.9 EFI_KMS_PROTOCOL.GetKeyByAttributes()

**Summary**

Retrieve one or more key that has matched all of the specified key attributes.

**Prototype**

```c
typedef EFI_STATUS (EFIAPIC *EFI_KMS_GET_KEY_BY_ATTRIBUTES) (  
    IN EFI_KMS_PROTOCOL *This,  
    IN EFI_KMS_CLIENT_INFO *Client,  
    IN UINTN *KeyAttributeCount,  
    IN OUT EFI_KMS_KEY_ATTRIBUTE *KeyAttributes,  
    IN OUT UINTN *KeyDescriptorCount,  
    IN OUT EFI_KMS_KEY_DESCRIPTOR *KeyDescriptors,  
    IN OUT UINTN *ClientDataSize OPTIONAL,  
    IN OUT VOID **ClientData OPTIONAL  
);  
```

**Parameters**

- **This**
  - Pointer to this EFI_KMS_PROTOCOL instance.

- **Client**
  - Pointer to a valid EFI_KMS_CLIENT_INFO structure.
KeyAttributeCount
   Pointer to a count of the number of key attribute structures that must be matched for each returned key descriptor. On input the count value is one or more. On normal returns, this number will be updated with the number of key attributes successfully processed.

KeyAttributes
   Pointer to an array of EFI_KMS_KEY_ATTRIBUTE structure to search for. On input, the values for the fields in the structure are completely filled in. On return the KeyAttributeStatus field will reflect the result of the operation for each key attribute request.

KeyDescriptorCount
   Pointer to a count of the number of key descriptors matched by this operation. On entry, this number will be zero. On return, this number will be updated to the number of key descriptors successfully found.

KeyDescriptors
   Pointer to an array of EFI_KMS_KEY_DESCRIPTOR structures which describe the keys from the KMS having the KeyAttribute(s) specified. On input, this pointer will be NULL. On output, the array will contain an EFI_KMS_KEY_DESCRIPTOR structure for each key meeting the search criteria. Memory for the array and all KeyValue fields will be allocated with the EfiBootServicesData type and must be freed by the caller when it is no longer needed. Also, the KeyStatus field of each descriptor will reflect the result of the request relative to that key descriptor.

ClientDataSize
   Pointer to the size, in bytes, of an arbitrary block of data specified by the ClientData parameter. This parameter may be NULL, in which case the ClientData parameter will be ignored and no data will be transferred to or from the KMS. If the parameter is not NULL, then ClientData must be a valid pointer. If the value pointed to is 0, no data will be transferred to the KMS, but data may be returned by the KMS. For all non-zero values **ClientData* will be transferred to the KMS, which may also return data to the caller. In all cases, the value upon return to the caller will be the size of the data block returned to the caller, which will be zero if no data is returned from the KMS.

ClientData
   Pointer to a pointer to an arbitrary block of data of **ClientDataSize* that is to be passed directly to the KMS if it supports the use of client data. This parameter may be NULL if and only if the ClientDataSize parameter is also NULL. Upon return to the caller, **ClientData* points to a block of data of **ClientDataSize* that was returned from the KMS. If the returned value for **ClientDataSize* is zero, then the returned value for **ClientData* must be NULL and should be ignored by the caller. The KMS protocol consumer is responsible for freeing all valid buffers used for client data regardless of whether they are allocated by the caller for input to the function or by the implementation for output back to the caller.

Description
   The GetKeyByAttributes() function returns the keys found by searches for matching key attribute(s). This function must be supported by every KMS protocol instance that supports the use of key attributes as indicated in the protocol’s KeyAttributesSupported field.

   The Client parameter identifies the caller to the key management service. It may be used for auditing or access control. The use of this parameter is optional unless the KMS requires it in order to perform the requested action.

   The KeyAttributesCount and KeyAttributes parameters are used to specify the key attributes data to be searched for on the KMS. Any number of attributes may be searched for in a single operation, regardless of whether the KMS supports multiple key attribute definitions in a single request or not. The KMS protocol implementation is responsible for generating the appropriate requests (single/multiple) to the KMS. In certain error situations, the status of each attribute is updated indicating if that attribute was successfully found or not. If an attribute specifies a wildcard KeyAttributeInstance value, then the provider returns all instances of the attribute.

   The KeyDescriptorCount and KeyDescriptors parameters are used to return the EFI_KMS_KEY_DESCRIPTOR structures for keys meeting the search criteria. Any number of keys may be returned in a single operation, regardless of
whether the KMS supports multiple key definitions in a single request or not. The KMS protocol implementation is responsible for generating the appropriate requests (single/multiple) to the KMS.

The ClientDataSize and ClientData parameters allow the caller to pass an arbitrary block of data to/from the KMS for uses such as auditing or access control. The KMS protocol implementation does not alter this data block other than to package it for transmission to the KMS. The use of these parameters is optional unless the KMS requires it in order to perform the requested action.

Status Codes Returned

The GetKeyByAttributes() function will return a status which indicates the overall status of the request. Note that this may be different from the status reported for individual keys.

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Successfully retrieved all requested keys.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>Could not allocate required resources.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>Timed out waiting for device or key server. Check individual key attribute request(s) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>If multiple keys are associated with the attribute(s), and the KeyValue buffer does not contain enough structures (KeyDescriptorCount) to contain all the key data, then the available structures will be filled and KeyDescriptorCount will be updated to indicate the number of keys which could not be processed.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Access was denied by the device or the key server; OR a ClientId is required by the server and either none or an invalid id was provided.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Device or key server error. Check individual key attribute request(s) (i.e., key attribute status for each) to see which ones may have been processed.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL, ClientId is required but it is NULL, KeyDescriptorCount is NULL, or KeyDescriptors is NULL or KeyAttributes is NULL, or KeyAttributesCount is NULL.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>One or more EFI_KMS_KEY_ATTRIBUTE structures could not be processed properly. KeyAttributeCount contains the number of structures which were successfully processed. Individual structures will reflect the status of the processing for that structure.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The implementation/KMS does not support this function.</td>
</tr>
</tbody>
</table>

37.4 PKCS7 Verify Protocol

37.4.1 EFI_PKCS7_VERIFY_PROTOCOL

Summary

EFI_PKCS7_VERIFY_PROTOCOL (See: http://tools.ietf.org/html/rfc2315) may be used to verify data signed with PKCS#7 formatted authentication. The PKCS#7 data to be verified must be binary DER encoded. Additional information on the supported ASN.1 formatting is provided below.

Drivers that supply PKCS7 verification function should publish the |EFI_PKCS7_VERIFY_PROTOCOL. Drivers wishing to use the |EFI_PKCS7_VERIFY_PROTOCOL may get a reference with LocateProtocol().

GUID

```c
#define EFI_PKCS7_VERIFY_PROTOCOL_GUID \
  { 0x47889fb2, 0xd671, 0x4fab,\ 
    { 0xa0, 0xca, 0xdf, 0xe, 0x44,\ 0xdf, 0x70, 0xd6 }}
```

Protocol Interface Structure
typedef struct _EFI_PKCS7_VERIFY_PROTOCOL {
    EFI_PKCS7_VERIFY_BUFFER *VerifyBuffer;
    EFI_PKCS7_VERIFY_SIGNATURE *VerifySignature;
} EFI_PKCS7_VERIFY_PROTOCOL;

Parameters

**VerifyBuffer**
Examine a DER-encoded PKCS7-signed memory buffer with signature containing embedded data content, or buffer with detached signature and separate data content buffer, and verify using supplied signature lists.

**VerifySignature**
Examine a DER-encoded PKCS7-signed memory buffer with signature and, using caller-supplied hash value for signed data, verify using supplied signature lists.

Description
The *EFI_PKCS7_VERIFY_PROTOCOL* is used to verify data signed using PKCS7 structure. PKCS7 is a general-purpose cryptographic standard (see references). The PKCS7 data to be verified must be ASN.1 (DER) encoded. Implementation must support SHA256 as digest algorithm with RSA digest encryption. Support of other hash algorithms is optional. See the Table below.

Table 37.22: Details of Supported Signature Format

<table>
<thead>
<tr>
<th>Signature Buffer Format Details</th>
<th>Encoding</th>
<th>Binary DER</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>ASN.1 root of Embedded Signed Data</td>
<td>ContentInfo with <em>SignedData</em> content type</td>
</tr>
<tr>
<td></td>
<td>ASN.1 root of Detached Signature</td>
<td><em>SignedData</em> or ContentInfo with <em>SignedData</em> content type</td>
</tr>
<tr>
<td>Embedded Data Type</td>
<td></td>
<td>Typically &quot;Data&quot; (1.2.840.113549.1.7.1) or other defined OID type (however caller should not depend upon specialized OID processing during PKCS validation.)</td>
</tr>
<tr>
<td>Digest (Hash) Algorithm (VerifyBuffer function)</td>
<td></td>
<td>Support of SHA-256 (2.16.840.1.101.3.4.2.1) is required, other algorithms are optional</td>
</tr>
<tr>
<td>Digest Encryption</td>
<td></td>
<td>RSA (1.2.840.113549.1.1.1)</td>
</tr>
<tr>
<td>Certificate validity dates</td>
<td></td>
<td>See <em>TimeStampDb</em> description</td>
</tr>
<tr>
<td>Signature authenticated Attributes</td>
<td></td>
<td>Ignored by function</td>
</tr>
<tr>
<td>Timestamping</td>
<td></td>
<td>See <em>TimeStampDb</em> description</td>
</tr>
</tbody>
</table>

References
PKCS7 is defined by RFC2315. For more information see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “RFC2315 (defines PKCS7)”.

37.4. PKCS7 Verify Protocol
37.4.2 EFI_PKCS7_VERIFY_PROTOCOL.VerifyBuffer()

Summary
This function processes a buffer containing binary DER-encoded PKCS7 signature. The signed data content may be embedded within the buffer or separated. Function verifies the signature of the content is valid and signing certificate was not revoked and is contained within a list of trusted signers.

Prototype

typedef
EFI_STATUS
(EFIAPI *VerifyBuffer)(
  IN EFI_PKCS7_VERIFY_PROTOCOL *This,
  IN VOID *SignedData,
  IN UINTN SignedDataSize,
  IN VOID *InData OPTIONAL,
  IN UINTN InDataSize
  IN EFI_SIGNATURE_LIST **AllowedDb,
  IN EFI_SIGNATURE_LIST **RevokedDb OPTIONAL,
  IN EFI_SIGNATURE_LIST **TimeStampDb OPTIONAL,
  OUT VOID *Content OPTIONAL,
  IN OUT UINTN *ContentSize
);

Parameters

This
  Pointer to EFI_PKCS7_VERIFY_PROTOCOL instance.

SignedData
  Points to buffer containing ASN.1 DER-encoded PKCS signature.

SignedDataSize
  The size of SignedData buffer in bytes.

InData
  In case of detached signature, InData points to buffer containing the raw message data previously signed and to be verified by function. In case of SignedData containing embedded data, InData must be NULL.

InDataSize
  When InData is used, the size of InData buffer in bytes.
  When InData is NULL, this parameter must be 0.

AllowedDb
  Pointer to a list of pointers to EFI_SIGNATURE_LIST structures. The list is terminated by a null pointer. The EFI_SIGNATURE_LIST structures contain lists of X.509 certificates of approved signers. See Chapter 27 for definition of EFI_SIGNATURE_LIST. Function recognizes signer certificates of type EFI_CERT_X509_GUID. Any hash certificate in AllowedDb list is ignored by this function. Function returns success if signer of the buffer is within this list (and not within RevokedDb). This parameter is required.

RevokedDb
  Optional pointer to a list of pointers to EFI_SIGNATURE_LIST structures. The list is terminated by a null pointer. List of X.509 certificates of revoked signers and revoked file hashes. Except as noted in description of TimeStampDb, signature verification will always fail if the signer of the file or the hash of the data component of the buffer is in RevokedDb list. This list is optional and caller may pass Null or pointer to NULL if not required.
**TimeStampDb**

Optional pointer to a list of pointers to `EFI_SIGNATURE_LIST` structures. The list is terminated by a null pointer. This parameter can be used to pass a list of X.509 certificates of trusted time stamp signers. This list is optional and caller may pass null or pointer to NULL if not required.

**Content**

On input, points to an optional caller-allocated buffer into which the function will copy the content portion of the file after verification succeeds. This parameter is optional and if NULL, no copy of content from file is performed.

**ContentSize**

On input, points to the size in bytes of the optional buffer `Content` previously allocated by caller. On output, if the verification succeeds, the value referenced by `ContentSize` will contain the actual size of the content from signed file. If `ContentSize` indicates the caller-allocated buffer is too small to contain content, an error is returned, and `ContentSize` will be updated with the required size. This parameter must be 0 if `Content` is NULL.

**Description**

This function processes the buffer `SignedData` for PKCS7 verification. The data that was signed using PKCS is referred to as the ‘Message’. In the process of creating a signature of the message, a SHA256 or other hash of the message bytes, called the ‘Message Digest’, is encrypted using a private key held in secret by the signer. The encrypted hash and the X.509 public key certificate of the signer are formatted according to the ASN.1 PKCS#7 Schema (See References). For the buffer type with the embedded data, the ASN.1 syntax is also used to wrap the data and combine the message data with the signature structure.

The `SignedData` buffer must be ASN.1 DER-encoded format with structure according to the subset defined in the introduction to this protocol. Both embedded content and detached signature formats are supported. In case of embedded content, `SignedData` contains both the PKCS7 signature structure and the message content that was signed. In the case of detached signature, `SignedData` contains only the signature data and `InData` is used to supply the data to be verified. To pass verification the X.509 public certificate of the signer of the file must be found in `AllowedDb` and not be present in `RevokedDb`. Additionally if `RevokedDb` contains a specific hash signature that matches the hash calculated for the content, the file will also fail verification. The message content will be copied to the caller-supplied buffer `Content` (when present) with `ContentSize` updated to reflect the total size in bytes of the extracted content.

The `VerifyBuffer()` function performs several steps. First, the buffer containing the user-provided signature is parsed, the content is located and a hash calculated, and the PKCS7 signature of that hash is verified by decrypting the hash calculated at time of signing. Match of current hash with decrypted hash provides indication the structure contained in buffer has not been modified since signing. Next the protocol function attempts to match the signing certificate included within the signed data again the members of an (optional) list of caller-provided revoked certificates (`RevokedDb`). The hash of the data is also compared against any hash items contained in `RevokedDb` list. Next the signing certificate is matched against the caller-provided list of trusted signatures. If the signature is valid, the certificate or hash are not in the revoked list, and the certificate is in the trusted list, the file passes verification.

When `TimeStampDb` list is present this information modifies the processing of revoked certificates found in both `AllowedDb` and `RevokedDb`. When PKCS7 signings that are time-stamped by trusted signer in `TimeStampDb` list, and which time-stamping occurred prior to the time of certificate revocation noted in certificate in `RevokedDb` list, the signing will be allowed and return `EFI_SUCCESS`. `TimeStampDb` parameter is optional and may be NULL, or a pointer to NULL when not used. Except in the processing of certificates found in both `AllowedDb` and `RevokedDb`, `TimeStampDb` is not used and time-stamping is not otherwise required for signings verified by certificate only in `AllowedDb`.

**NOTE:** This method is intended to be suitable to implement Secure Boot image validation, and as such the contents of `AllowedDb`, `RevokedDb`, and `TimeStampDb` must also conform with the requirements of Authorization Process, bullet item 3 (UEFI Image Validation Succeeded).

The verification function can handle both embedded data or detached signature formats. In case of embedded data, the function will optionally extract the original signed data and supply back to caller in caller-supplied buffer. For a detached signature the caller must provide the original message data in buffer pointed to by `InData`. For consistency, when both `InData` and `Content` are provided, the function will copy contents of `InData` to `Content`. 

**37.4. PKCS7 Verify Protocol**
In case where the `ContentSize` indicated by caller is too small to contain the entire content extracted from the file, `EFI_BUFFER_TOO_SMALL` error is returned, and `ContentSize` is updated to reflect the required size.

**NOTE:** When signing certificate is matched to `AllowedDb` or `RevokedDb` lists, a match can occur against an entry in the list at any level of the chain of X.509 certificates present in the PCKS certificate list. This supports signing with a certificate that chains to one of the certificates in the `AllowedDb` or `RevokedDb` lists.

**Related Definitions**
None

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>Content signature was verified against hash of content, the signer’s certificate was not found in <code>RevokedDb</code>, and was found in <code>AllowedDb</code> or if in signer is found in both <code>AllowedDb</code> and <code>RevokedDb</code>, the signing was allowed by reference to <code>TimeStampDb</code> as described above, and no hash matching content hash was found in <code>RevokedDb</code>.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>The <code>SignedData</code> buffer was correctly formatted but signer was in <code>RevokedDb</code> or not in <code>AllowedDb</code>. Also returned if matching content hash found in <code>RevokedDb</code>.</td>
</tr>
<tr>
<td>EFI_COMPROMISED_DATA</td>
<td>Calculated hash differs from signed hash.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>SignedData</code> is <code>NULL</code> or <code>SignedDataSize</code> is zero. <code>AllowedDb</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Content is not <code>NULL</code> and <code>ContentSize</code> is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>Unsupported or invalid format in <code>TimeStampDb</code>, <code>RevokedDb</code> or <code>AllowedDb</code> list contents was detected.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>Content not found because <code>InData</code> is <code>NULL</code> and no content embedded in <code>SignedData</code>.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The <code>SignedData</code> buffer was not correctly formatted for processing by the function.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Signed data embedded in <code>SignedData</code> but <code>InData</code> is not <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The size of buffer indicated by <code>ContentSize</code> is too small to hold the content. <code>ContentSize</code> updated to required size.</td>
</tr>
</tbody>
</table>

**37.4.2.1 EFI_PKCS7_VERIFY_PROTOCOL.VerifySignature()**

**Summary**

This function processes a buffer containing binary DER-encoded detached PKCS7 signature. The hash of the signed data content is calculated and passed by the caller. Function verifies the signature of the content is valid and signing certificate was not revoked and is contained within a list of trusted signers.

**NOTE:** the current UEFI specification allows for a variety of hashes. In order to be secure, the users of this protocol should loop over each hash to see if the binary signature is authorized.

**Prototype**

```c
typedef EFI_STATUS
(EFI_API *VerifySignature)(
    IN EFI_PKCS7_VERIFY_PROTOCOL *This,
    IN VOID *Signature,
    IN UINTN SignatureSize,
    IN VOID *InHash,
    IN UINTN InHashSize
)
```

(continues on next page)
Parameters

This

Pointer to _EFI_PKCS7_VERIFY_PROTOCOL_ instance.

Signature

Points to buffer containing ASN.1 DER-encoded PKCS detached signature.

SignatureSize

The size of _Signature_ buffer in bytes.

InHash

_InHash_ points to buffer containing the caller calculated hash of the data. This parameter may not be NULL.

InHashSize

The size in bytes of _InHash_ buffer.

AllowedDb

Pointer to a list of pointers to _EFI_SIGNATURE_LIST_ structures. The list is terminated by a null pointer. The _EFI_SIGNATURE_LIST_ structures contain lists of X.509 certificates of approved signers. See Chapter 27 for definition of _EFI_SIGNATURE_LIST_. Function recognizes signer certificates of type _EFI_CERT_X509_GUID_. Any hash certificate in _AllowedDb_ list is ignored by this function. Function returns success if signer of the buffer is within this list (and not within _RevokedDb_). This parameter is required.

RevokedDb

Pointer to a list of pointers to _EFI_SIGNATURE_LIST_ structures. The list is terminated by a null pointer. List of X.509 certificates of revoked signers and revoked file hashes. Signature verification will always fail if the signer of the file or the hash of the data component of the buffer is in _RevokedDb_ list. This parameter is optional and caller may pass Null if not required.

TimeStampDb

Optional pointer to a list of pointers to _EFI_SIGNATURE_LIST_ structures. The list is terminated by a null pointer. This parameter can be used to pass a list of X.509 certificates of trusted time stamp counter-signers.

Description

This function processes the buffer _Signature_ for PKCS7 verification using hash of the data calculated and pass by caller in the _InHash_ buffer. The data that was signed using PKCS is referred to as the ‘Message’. In the process of creating a signature of the message, a hash of the message bytes, called the ‘Message Digest’, is encrypted using a private key held in secret by the signer. The encrypted hash and the X.509 public key certificate of the signer are formatted according to the ASN.1 PKCS#7 Schema (See References). Any data embedded within the PKCS structure is ignored by the function. This function does not support extraction of signature from executable file formats. The address of the PKCS Signature block must be located and passed by the called.

The hash size passed in _InHashSize_ must match the size of the signed hash embedded within the PKCS signature structure or an error is returned.

The _SignedData_ buffer must be ASN.1 DER-encoded format with structure according to the subset defined in the introduction to this protocol. Both embedded content and detached signature formats are supported however embedded data is ignored. To pass verification the X.509 public certificate of the signer of the file must be found in _AllowedDb_ and not be present in _RevokedDb_. Additionally, if _RevokedDb_ contains a specific Hash signature that matches the hash calculated for the content, the file will also fail verification.
When `TimeStampDb` list is present this information modifies the processing of revoked certificates found in both `AllowedDb` and `RevokedDb`. When PCKS7 signings that are time-stamped by trusted signer in `TimeStampDb` list, and which time-stamping occurred prior to the time of certificate revocation noted in certificate in `RevokedDb` list, the signing will be allowed and return `EFI_SUCCESS`. `TimeStampDb` parameter is optional and may be NULL or a pointer to NULL when not used. Except in the processing of certificates found in both `AllowedDb` and `RevokedDb`, `TimeStampDb` is not used and time-stamping is not otherwise required for signigns verified by certificate only in `AllowedDb`.

The `VerifySignature()` function performs several steps. First, the buffer containing the user-provided signature is parsed, (any embedded content is ignored), and the PKCS7 signature of hash data is verified by decrypting the hash calculated at time of signing. Match of caller provided hash with decrypted hash provides indication the signed data has not been modified since signing. Next the protocol function attempts to match the signing certificate included within the signed data again the members of an (optional) list of caller-provided revoked certificates (`RevokedDb`). The hash of the data is also compared against any hash items contained in `RevokedDb` list. Next the signing certificate is matched against the caller-provided list of trusted signatures. If the signature is valid, the certificate or hash are not in the revoked list, and the certificate is in the trusted list, the file passes verification.

**Note:** When a signing certificate is matched to `AllowedDb` or `RevokedDb` lists, a match can occur against an entry in the list at any level of the chain of X.509 certificates present in the PCKS certificate list. This supports signing with a certificate that chains to one of the certificates in the `AllowedDb` or `RevokedDb` lists.

**Note:** Because this function uses hashes and the specification contains a variety of hash choices, you should be aware that the check against the `RevokedDb` list will improperly succeed if the signature is revoked using a different hash algorithm. For this reason, you should either cycle through all UEFI supported hashes to see if one is forbidden, or rely on a single hash choice only if the UEFI signature authority only signs and revokes with a single hash (currently this hash choice is SHA256).

**Related Definitions**

None

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>EFI_SUCCESS</code></td>
<td>Signed hash was verified against caller-provided hash of content, the signer’s certificate was not found in <code>RevokedDb</code>, and was found in <code>AllowedDb</code> or if in signer is found in both <code>AllowedDb</code> and <code>RevokedDb</code>, the signing was allowed by reference to <code>TimeStampDb</code> as described above, and no hash matching content hash was found in <code>RevokedDb</code>.</td>
</tr>
<tr>
<td><code>EFI_SECURITY_VIOLATION</code></td>
<td>The <code>SignedData</code> buffer was correctly formatted but signer was in <code>RevokedDb</code> or not in <code>AllowedDb</code>. Also returned if matching content hash found in <code>RevokedDb</code>.</td>
</tr>
<tr>
<td><code>EFI_COMPROMISED_DATA</code></td>
<td>Caller provided hash differs from signed hash. Or, caller and encrypted hash are different sizes.</td>
</tr>
<tr>
<td><code>EFI_INVALID_PARAMETER</code></td>
<td><code>Signature</code> is NULL or <code>SignatureSize</code> is zero. <code>InHash</code> is NULL or <code>InhashSize</code> is zero. <code>AllowedDb</code> is NULL.</td>
</tr>
<tr>
<td><code>EFI_ABORTED</code></td>
<td>Unsupported or invalid format in <code>TimeStampDb</code>, <code>RevokedDb</code> or <code>AllowedDb</code> list contents was detected.</td>
</tr>
<tr>
<td><code>EFI_UNSUPPORTED</code></td>
<td>The <code>Signature</code> buffer was not correctly formatted for processing by the function.</td>
</tr>
</tbody>
</table>
37.5 Random Number Generator Protocol

This section defines the Random Number Generator (RNG) protocol. This protocol is used to provide random numbers for use in applications, or entropy for seeding other random number generators. Consumers of the protocol can ensure that drivers implementing the protocol produce RNG values in a well-known manner.

When a Deterministic Random Bit Generator (DRBG) is used on the output of a (raw) entropy source, its security level must be at least 256 bits.

37.5.1 EFI_RNG_PROTOCOL

Summary

This protocol provides standard RNG functions. It can be used to provide random bits for use in applications, or entropy for seeding other random number generators.

GUID

```
#define EFI_RNG_PROTOCOL_GUID
{ 0x3152bca5, 0xeade, 0x433d,
 {0x86, 0x2e, 0xc0, 0x1c, 0xdc, 0x29, 0x1f, 0x44}}
```

Protocol Interface Structure

```
typedef struct _EFI_RNG_PROTOCOL {
    EFI_RNG_GET_INFO              GetInfo
    EFI_RNG_GET_RNG               GetRNG;
} EFI_RNG_PROTOCOL;
```

Parameters

GetInfo

Returns information about the random number generation implementation.

GetRNG

Returns the next set of random numbers.

Description

This protocol allows retrieval of RNG values from an UEFI driver. The GetInfo service returns information about the RNG algorithms the driver supports. The GetRNG service creates a RNG value using an (optionally specified) RNG algorithm.
37.5.2 EFI_RNG_PROTOCOL.GetInfo

Summary

Returns information about the random number generation implementation.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_RNG_GET_INFO) (
    IN EFI_RNG_PROTOCOL *This,
    IN OUT UINTN *RNGAlgorithmListSize,
    OUT EFI_RNG_ALGORITHM *RNGAlgorithmList
);
```

Parameters

This

A pointer to the EFI_RNG_PROTOCOL instance.

RNGAlgorithmListSize

On input, the size in bytes of RNGAlgorithmList. On output with a return code of EFI_SUCCESS, the size in bytes of the data returned in RNGAlgorithmList.

On output with a return code of EFI_BUFFER_TOO_SMALL, the size of RNGAlgorithmList required to obtain the list.

RNGAlgorithmList

A caller-allocated memory buffer filled by the driver with one EFI_RNG_ALGORITHM element for each supported RNG algorithm. The list must not change across multiple calls to the same driver. The first algorithm in the list is the default algorithm for the driver.

Description

This function returns information about supported RNG algorithms.

A driver implementing the RNG protocol need not support more than one RNG algorithm, but shall support a minimum of one RNG algorithm.

Related Definitions

```c
typedef EFI_GUID EFI_RNG_ALGORITHM;
```

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The RNG algorithm list was returned successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The service is not supported by this driver.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>The list of algorithms could not be retrieved due to a hardware or firmware error.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The buffer RNGAlgorithmList is too small to hold the result.</td>
</tr>
</tbody>
</table>
37.5.3 EFI_RNG_PROTOCOL.GetRNG

Summary

 Produces and returns an RNG value using either the default or specified RNG algorithm.

Prototype

```c
typedef EFI_STATUS
(EFI_API *EFI_RNG_GET_RNG) (IN EFI_RNG_PROTOCOL *This,
   IN EFI_RNG_ALGORITHM *RNGAlgorithm, OPTIONAL
   IN UINTN RNGValueLength,
   OUT UINT8 *RNGValue);
```

Parameters

**This**

A pointer to the EFI_RNG_PROTOCOL instance.

**RNGAlgorithm**

A pointer to the EFI_RNG_ALGORITHM that identifies the RNG algorithm to use. May be NULL in which case the function will use its default RNG algorithm.

**RNGValueLength**

The length in bytes of the memory buffer pointed to by RNGValue. The driver shall return exactly this number of bytes.

**RNGValue**

A caller-allocated memory buffer filled by the driver with the resulting RNG value.

Description

This function fills the RNGValue buffer with random bytes from the specified RNG algorithm. The driver must not reuse random bytes across calls to this function. It is the caller’s responsibility to allocate the RNGValue buffer.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The RNG value was returned successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>The algorithm specified by RNGAlgorithm is not supported by this driver.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An RNG value could not be retrieved due to a hardware or firmware error.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>There is not enough random data available to satisfy the length requested by RNGValueLength.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>RNGValue is null or RNGValueLength is zero.</td>
</tr>
</tbody>
</table>
37.5.4 EFI RNG Algorithm Definitions

Summary

This sub-section provides EFI_GUID values for a selection of EFI_RNG_PROTOCOL algorithms. The algorithms listed are optional, not meant to be exhaustive and may be augmented by vendors or other industry standards.

The “raw” algorithm, when supported, is intended to provide entropy directly from the source, without it going through some deterministic random bit generator.

Prototype

```c
#define EFI_RNG_ALGORITHM_SP800_90_HASH_256_GUID \
{0xa7af67cb, 0x603b, 0x4d42,\n {0xba, 0x21, 0x70, 0xb6, 0x29, 0x3f, 0x96}}

#define EFI_RNG_ALGORITHM_SP800_90_HMAC_256_GUID \
{0xc5149b43, 0xae85, 0x4f53,\n {0x99, 0x82, 0xb9, 0x43, 0x35, 0xd3, 0xa9, 0xe7}}

#define EFI_RNG_ALGORITHM_SP800_90_CTR_256_GUID \
{0x44f0de6e, 0x4d8c, 0x4045,\n {0xa8, 0xc7, 0x4d, 0xd1, 0x68, 0x85, 0x6b, 0x9e}}

#define EFI_RNG_ALGORITHM_X9_31_3DES_GUID \
{0x63c4785a, 0xca34, 0x4012,\n {0xa3, 0xc8, 0xb0, 0x6a, 0x32, 0x4f, 0x55, 0x46}}

#define EFI_RNG_ALGORITHM_X9_31_AES_GUID \
{0xacd03321, 0x777e, 0x4d3d,\n {0xb1, 0xc8, 0x20, 0xcf, 0xd8, 0x88, 0x20, 0xc9}}

#define EFI_RNG_ALGORITHM_RAW \
{0xe43176d7, 0xb6e8, 0x4827,\n {0xb7, 0x84, 0xf7, 0xfe, 0xc4, 0xb6, 0x85, 0x61}}
```

37.5.5 RNG References


NIST, “Recommended Random Number Generator Based on ANSI X9.31 Appendix A.2.4 Using the 3-Key Triple DES and AES Algorithms,” January 2005. See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Recommended Random Number Generator Based on ANSI X9.31”.
37.6 Smart Card Reader and Smart Card Edge Protocol

The UEFI Smart Card Reader Protocol provides an abstraction for device to provide smart card reader support. This protocol is very close to Part 5 of PC/SC workgroup specifications and provides an API to applications willing to communicate with a smart card or a smart card reader.

37.6.1 Smart Card Reader Protocol

37.6.1.1 EFI_SMART_CARD_READER_PROTOCOL Summary

Smart card aware application invokes this protocol to get access to an inserted smart card in the reader or to the reader itself.

GUID

```
#define EFI_SMART_CARD_READER_PROTOCOL_GUID \
{0x2a4d1adf, 0x21dc, 0x4b81,\ 
 {0xa4, 0x2f, 0x8b, 0x8e, 0xe2, 0x38, 0x00, 0x60}}
```

Protocol Interface Structure

```
typedef struct _EFI_SMART_CARD_READER_PROTOCOL {
    EFI_SMART_CARD_READER_CONNECT SCardConnect;
    EFI_SMART_CARD_READER_DISCONNECT SCardDisconnect;
    EFI_SMART_CARD_READER_STATUS SCardStatus;
    EFI_SMART_CARD_READER_TRANSMIT SCardTransmit;
    EFI_SMART_CARD_READER_CONTROL SCardControl;
    EFI_SMART_CARD_READER_GET_ATTRIB SCardGetAttrib;
} EFI_SMART_CARD_READER_PROTOCOL;
```

Members

SCardConnect
Requests a connection to the smart card or smart card reader.

SCardDisconnect
Closes the previously open connection.

SCardStatus
Provides informations on smart card status and reader name.

SCardTransmit
Exchanges data with smart card or smart card reader.

SCardControl
Gives direct control to the smart card reader.

SCardGetAttrib
Retrieves reader characteristics.

Description

This protocol allows UEFI applications to communicate and get/set all necessary information to the smart card reader.

Overview

This document aims at defining a standard way for UEFI applications to use a smart card. The key points are:
• Provide an API as close as possible to Part 5 of the existing PC/SC interface. See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “PC/SC Workgroup Specifications”.

• Remove any unnecessary complexity of PC/SC implementation in a classic OS:

  — Assume no connection sharing
  — No resource manager
  — Reduced set of APIs

Note that this document only focuses on PC/SC Part 5 (access to smart card/smart card reader from an application). Abstracting the smart card (Parts 6/9) is not the scope of this document.

Main differences with existing PC/SC implementation on Linux/MacOS/Windows:

• There is no resource manager, driver exposes Part 5 instead of Part 3

• It is not possible to share a smart card between UEFI applications/drivers

• Reader enumeration is different:

  — On classic PC/SC, SCardListReaders is used
  — In UEFI, reader list is available via OpenProtocol/ScardStatus calls

### 37.6.2 EFI_SMART_CARD_READER_PROTOCOL.SCardConnect()

**Summary**

This function requests connection to the smart card or the reader, using the appropriate reset type and protocol.

**Prototype**

```c
EFI_STATUS
EFIAPI *(EFI_SMART_CARD_READER_PROTOCOL_CONNECT) (*This,
  IN EFI_SMART_CARD_READER_PROTOCOL *This,
  IN UINT32 AccessMode,
  IN UINT32 CardAction,
  IN UINT32 PreferredProtocols,
  OUT UINT32 *ActiveProtocol
);```

**Parameters**

This

Indicates a pointer to the calling context. Type `EFI_SMART_CARD_READER_PROTOCOL` is defined in the `EFI_SMART_CARD_READER_PROTOCOL` description.

AccessMode

See “Related Definitions” below.

CardAction

```c
SCARD_CA_NORESET,
SCARD_CA_COLDRESET or
SCARD_CA_WARMRESET.
```
PreferredProtocols

   Bitmask of acceptable protocols. See “Related Definitions” below.

ActiveProtocol

   A flag that indicates the active protocol. See “Related Definitions” below.

Related Definitions

```c
// Codes for access mode
#define SCARD_AM_READER 0x0001 // Exclusive access to reader
#define SCARD_AM_CARD 0x0002 // Exclusive access to card

// Codes for card action
#define SCARD_CA_NORESET 0x0000 // Don’t reset card
#define SCARD_CA_COLDRESET 0x0001 // Perform a cold reset
#define SCARD_CA_WARMRESET 0x0002 // Perform a warm reset
#define SCARD_CA_UNPOWER 0x0003 // Power off the card
#define SCARD_CA_EJECT 0x0004 // Eject the card

// Protocol types
#define SCARD_PROTOCOL_UNDEFINED 0x0000
#define SCARD_PROTOCOL_T0 0x0001
#define SCARD_PROTOCOL_T1 0x0002
#define SCARD_PROTOCOL_RAW 0x0004
```

Description

The `SCardConnect` function requests access to the smart card or the reader. Upon success, it is then possible to call `SCardTransmit`.

If `AccessMode` is set to `SCARD_AM_READER`, `PreferredProtocols` must be set to `SCARD_PROTOCOL_UNDEFINED` and `CardAction` to `SCARD_CA_NORESET` else function fails with `EFI_INVALID_PARAMETER`.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is <strong>NULL</strong></td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>AccessMode</code> is not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>CardAction</code> is not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Invalid combination of <code>AccessMode</code> / <code>CardAction</code> / <code>PreferredProtocols</code>.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>A smart card is inserted but failed to return an ATR.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td><code>PreferredProtocols</code> does not contain an available protocol to use.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td><code>AccessMode</code> is set to <code>SCARD_AM_CARD</code> but there is no smart card inserted.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Access is already locked by a previous <code>SCardConnect</code> call.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Any other error condition, typically a reader removal.</td>
</tr>
</tbody>
</table>
37.6.3 EFI_SMART_CARD_READER_PROTOCOL.SCardDisconnect()

Summary
This function releases a connection previously taken by SCardConnect.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_SMART_CARD_READER_PROTOCOL_DISCONNECT) (
   IN EFI_SMART_CARD_READER_PROTOCOL *This,
   IN UINT32 CardAction
);
```

Parameters

This
Indicates a pointer to the calling context. Type EFI_SMART_CARD_READER_PROTOCOL is defined in the EFI_SMART_CARD_READER_PROTOCOL description.

CardAction
See “Related Definitions” for CardAction in SCardConnect description.

Description
The SCardDisconnect function releases the lock previously taken by SCardConnect. In case the smart card has been removed before this call, this function returns EFI_SUCCESS. If there is no previous call to SCardConnect, this function returns EFI_SUCCESS.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>CardAction value is unknown.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Reader does not support Eject card feature (disconnect was not performed).</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Any other error condition, typically a reader removal.</td>
</tr>
</tbody>
</table>

37.6.4 EFI_SMART_CARD_READER_PROTOCOL.SCardStatus()

Summary
This function retrieves some basic information about the smart card and reader.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_SMART_CARD_READER_PROTOCOL_STATUS) (
   IN EFI_SMART_CARD_READER_PROTOCOL *This,
   OUT CHAR16 *ReaderName OPTIONAL,
   IN OUT UINTN *ReaderNameLength OPTIONAL,
   OUT UINT32 *State OPTIONAL,
   OUT UINT32 *CardProtocol OPTIONAL,
   OUT UINT8 *Atr OPTIONAL,
   IN OUT UINTN *AtrLength OPTIONAL
);
```
Parameters

This
Indicates a pointer to the calling context. Type $\text{EFI_SMART_CARD_READER_PROTOCOL}$ is defined in the $\text{EFI_SMART_CARD_READER_PROTOCOL}$ description.

ReaderName
A pointer to a NULL terminated string that will contain the reader name.

ReaderNameLength
On input, a pointer to the variable that holds the maximal size, in bytes, of $\text{ReaderName}$.
On output, the required size, in bytes, for $\text{ReaderName}$.

State
Current state of the smart card reader. See “Related Definitions” below.

CardProtocol
Current protocol used to communicate with the smart card. See “Related Definitions” in $\text{SCardConnect}$.

Atr
A pointer to retrieve the ATR of the smart card.

AtrLength
On input, a pointer to hold the maximum size, in bytes, of $\text{Atr}$ (usually 33).
On output, the required size, in bytes, for the smart card ATR.

Related Definitions

```c
// Codes for state type
#define SCARD_UNKNOWN 0x0000 /* state is unknown */
#define SCARD_ABSENT 0x0001 /* Card is absent */
#define SCARD_INACTIVE 0x0002 /* Card is present and not powered*/
#define SCARD_ACTIVE 0x0003 /* Card is present and powered */
```

Description
The $\text{SCardStatus}$ function retrieves basic reader and card information.

If $\text{ReaderName}$, $\text{State}$, $\text{CardProtocol}$ or $\text{Atr}$ is NULL, the function does not fail but does not fill in such variables.

If $\text{EFI_SUCCESS}$ is not returned, $\text{ReaderName}$ and $\text{Atr}$ contents shall not be considered as valid.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\text{EFI_SUCCESS}$</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>$\text{EFI_INVALID_PARAMETER}$</td>
<td>This is NULL</td>
</tr>
<tr>
<td>$\text{EFI_INVALID_PARAMETER}$</td>
<td>ReaderName is not NULL but ReaderNameLength is NULL</td>
</tr>
<tr>
<td>$\text{EFI_INVALID_PARAMETER}$</td>
<td>Atr is not NULL but AtrLength is NULL</td>
</tr>
<tr>
<td>$\text{EFI_BUFFER_TOO_SMALL}$</td>
<td>ReaderNameLength is not big enough to hold the reader name. ReaderNameLength has been updated to the required value.</td>
</tr>
<tr>
<td>$\text{EFI_BUFFER_TOO_SMALL}$</td>
<td>AtrLength is not big enough to hold the ATR. AtrLength has been updated to the required value.</td>
</tr>
<tr>
<td>$\text{EFI_DEVICE_ERROR}$</td>
<td>Any other error condition, typically a reader removal.</td>
</tr>
</tbody>
</table>
37.6.5 EFI_SMART_CARD_READER_PROTOCOL.SCardTransmit()

Summary
This function sends a command to the card or reader and returns its response.

Prototype

```
typedef EFI_STATUS (EFIAPI *EFI_SMART_CARD_READER_PROTOCOL_TRANSMIT) (
    IN EFI_SMART_CARD_READER_PROTOCOL *This,       // This,
    IN UINT8 *CAPDU,                                // CAPDU,
    IN UINTN CAPDULength,                          // CAPDULength,
    OUT UINT8 *RAPDU,                               // RAPDU,
    IN OUT UINTN *RAPDULength                      // RAPDULength
);                                                //
```

Parameters

**This**
Indicates a pointer to the calling context. Type `EFI_SMART_CARD_READER_PROTOCOL` is defined in the `EFI_SMART_CARD_READER_PROTOCOL` description.

**CAPDU**
A pointer to a byte array that contains the Command APDU to send to the smart card or reader.

**CAPDULength**
Command APDU size, in bytes.

**RAPDU**
A pointer to a byte array that will contain the Response APDU.

**RAPDULength**
On input, the maximum size, in bytes, of the Response APDU. On output, the size, in bytes, of the Response APDU.

Description

This function sends a command to the card or reader and returns its response. The protocol to use to communicate with the smart card has been selected through `SCardConnect` call.

In case `RAPDULength` indicates a buffer too small to hold the response APDU, the function fails with `EFI_BUFFER_TOO_SMALL`.

**NOTE:** the caller has to call previously `SCardConnect` to make sure the reader/card is not already accessed by another application or driver.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>CAPDU is NULL or CAPDULength is 0.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>RAPDULength is not big enough to hold the response APDU. RAPDULength has been updated to the required value.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no card in the reader.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>Card is not powered.</td>
</tr>
<tr>
<td>EFI_PROTOCOL_ERROR</td>
<td>A protocol error has occurred.</td>
</tr>
</tbody>
</table>

continues on next page
Table 37.30 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_TIMEOUT</td>
<td>The reader did not respond.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>A communication with the reader/card is already pending.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Any other error condition, typically a reader removal.</td>
</tr>
</tbody>
</table>

### 37.6.6 EFI_SMART_CARD_READER_PROTOCOL.SCardControl()

#### Summary
This function provides direct access to the reader.

#### Prototype
```c
typedef EFI_STATUS (EFIAPI *EFI_SMART_CARD_READER_PROTOCOL_CONTROL) (
    IN EFI_SMART_CARD_READER_PROTOCOL *This,
    IN UINT32 ControlCode,
    IN UINT8 *InBuffer OPTIONAL,
    IN UINTN InBufferLength OPTIONAL,
    OUT UINT8 *OutBuffer OPTIONAL,
    IN OUT UINTN *OutBufferLength OPTIONAL
);
```

#### Parameters
- **This**: Indicates a pointer to the calling context. Type `EFI_SMART_CARD_READER_PROTOCOL` is defined in the `EFI_SMART_CARD_READER_PROTOCOL` description.
- **ControlCode**: The control code for the operation to perform. See “Related Definitions” below.
- **InBuffer**: A pointer to the input parameters.
- **InBufferLength**: Size, in bytes, of input parameters.
- **OutBuffer**: A pointer to the output parameters.
- **OutBufferLength**: On input, maximal size, in bytes, to store output parameters.
  On output, the size, in bytes, of output parameters.

#### Description
This function gives direct control to send commands to the driver or the reader.

The `ControlCode` to use is vendor dependant; the only standard code defined is the one to get PC/SC part 10 features. See “Related Definitions” below.

`InBuffer` and `OutBuffer` may be NULL when `ControlCode` operation does not require them.

**NOTE**: the caller has to call previously `SCardConnect` to make sure the reader/card is not already accessed by another application or driver.
Related Definitions

```c
//
// Macro to generate a ControlCode & PC/SC part 10 control code
//
#define SCARD_CTL_CODE(code) (0x42000000 + (code))
#define CM_IOCTL_GET_FEATURE_REQUEST SCARD_CTL_CODE(3400)
```

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ControlCode requires input parameters but:</td>
</tr>
<tr>
<td></td>
<td>• InBuffer is NULL or InBufferLength is NULL -or-</td>
</tr>
<tr>
<td></td>
<td>• InBuffer is not NULL but InBufferLength is less than</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>OutBuffer is not NULL but OutBufferLength is NULL.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>ControlCode is not supported.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>OutBufferLength is not big enough to hold the output parameters.</td>
</tr>
<tr>
<td></td>
<td>OutBufferLength has been updated to the required value.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no card in the reader and the control code specified requires one.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>ControlCode requires a powered card to operate.</td>
</tr>
<tr>
<td>EFI_PROTOCOL_ERROR</td>
<td>A protocol error has occurred.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The reader did not respond.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>A communication with the reader/card is already pending.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Any other error condition, typically a reader removal.</td>
</tr>
</tbody>
</table>

37.6.7 EFI_SMART_CARD_READER_PROTOCOL.SCardGetAttrib()

Summary

This function retrieves a reader or smart card attribute.

Prototype

```c
typedef EFI_STATUS
    (EFIAPI *EFI_SMART_CARD_READER_PROTOCOL_GET_ATTRIB) (  
    IN EFI_SMART_CARD_READER_PROTOCOL *This,  
    IN UINT32 Attrib,  
    OUT UINT8 *OutBuffer,  
    IN OUT UINTN *OutBufferLength  
    );
```

Parameters

**This**

Indicates a pointer to the calling context. Type `EFI_SMART_CARD_READER_PROTOCOL` is defined in the `EFI_SMART_CARD_READER_PROTOCOL` description.
Attrib
Identifier for the attribute to retrieve. See “Related Definitions” below. Note that all attributes might not be implemented.

OutBuffer
A pointer to a buffer that will contain attribute data.

OutBufferLength
On input, maximal size, in bytes, to store attribute data.
On output, the size, in bytes, of attribute data.

Related Definitions
Possibly supported attrib values are listed in the PC/SC Specification, Part 3. See Appendix Q — References for document link.

Description
The SCardGetAttrib function retrieves an attribute from the reader driver.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>OutBuffer is NULL or OutBufferLength is 0.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>OutBufferLength is not big enough to hold the output parameters. OutBuffer-</td>
</tr>
<tr>
<td></td>
<td>Length has been updated to the required value.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>Attrib is not supported.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>There is no card in the reader and Attrib value requires one.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>Attrib requires a powered card to operate.</td>
</tr>
<tr>
<td>EFI_PROTOCOL_ERROR</td>
<td>A protocol error has occurred.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>The reader did not respond.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>Any other error condition, typically a reader removal.</td>
</tr>
</tbody>
</table>

37.6.8 Smart Card Edge Protocol

The Smart Card Edge Protocol provides an abstraction for device to provide Smart Card support.

37.6.8.1 EFI_SMART_CARD_EDGE_PROTOCOL

Summary
Smart Card aware application invokes this protocol to get access to an inserted Smart Card in the reader.

GUID

```
#define EFI_SMART_CARD_EDGE_PROTOCOL_GUID \
{ 0xd317f29b, 0xa325, 0x4712,\ 
{ 0x9b, 0xf1, 0xc6, 0x19, 0x54, 0xdc, 0x19, 0x8c } }
```

Protocol Interface Structure
typedef struct _EFI_SMART_CARD_EDGE_PROTOCOL {
    EFI_SMART_CARD_EDGE_GET_CONTEXT GetContext;
    EFI_SMART_CARD_EDGE_CONNECT Connect;
    EFI_SMART_CARD_EDGE_DISCONNECT Disconnect;
    EFI_SMART_CARD_EDGE_GET_CSN GetCsn;
    EFI_SMART_CARD_EDGE_GET_READER_NAME GetReaderName;
    EFI_SMART_CARD_EDGE_VERIFY_PIN VerifyPin;
    EFI_SMART_CARD_EDGE_GET_PIN_REMAINING GetPinRemaining;
    EFI_SMART_CARD_EDGE_GET_DATA GetData;
    EFI_SMART_CARD_EDGE_GET_CREDENTIAL GetCredential;
    EFI_SMART_CARD_EDGE_SIGN_DATA SignData;
    EFI_SMART_CARD_EDGE_DECRYPT_DATA DecryptData;
    EFI_SMART_CARD_EDGE_BUILD_DH_AGREEMENT BuildDHAgreement;
} EFI_SMART_CARD_EDGE_PROTOCOL;

Members

GetContext
    Request the driver context.

Connect
    Request a connection to the Smart Card.

Disconnect
    Close a previously open connection.

GetCSN
    Get Card Serial Number.

GetReaderName
    Get name of Smart Card reader used.

VerifyPin
    Verify Smart Card PIN.

GetPinRemaining
    Get number of remaining PIN tries.

GetData
    Get specific data.

GetCredential
    Get credentials the Smart Card holds.

SignData
    Sign a data.

DecryptData
    Decrypt a data.

BuildDHAgreement
    Construct a DH (Diffie Hellman) agreement for key derivation.

Description

This protocol allows UEFI applications to interface with a Smart Card during boot process for authentication or data signing / decryption, especially if the application has to make use of PKI.

Overview
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

This document aims at defining a standard way for UEFI applications to use a Smart Card in PKI (Public Key Infrastructure) context. The key points are:

- Each Smart Card or set of Smart Card have specific behavior.
- Smart Card applications often interface with PKCS #11 API or other cryptographic interface like CNG.
- During boot process not all the possibility of a cryptographic interface, like PKCS #11, are useful, for example it is neither the moment to perform Smart Card administration or Smart Card provisioning nor to process debit or credit operation with Smart Card.

Consequently this protocol focused on those points:

- Offering standard access to Smart Card functionalities that:
  - Authenticate User
  - Sign data
  - Decrypt data
  - Get certificates

- With an API that is enough close with PKCS#11 API that it could be considered as a brick to build a “tiny PKCS#11”.
- An implementation of the protocol can be dedicated to a specific Smart Card or a specific set of Smart Card.
- An implementation of the protocol shall poll for Smart Card reader attachment and removal.
- An implementation of the protocol shall poll for Smart Card insertion and removal. On insertion the protocol shall check if it supports this Smart Card.

Typically an implementation of this protocol will lean on a Smart Card reader protocol (EFI_SMART_CARD_READER_PROTOCOL).

37.6.8.2 EFI_SMART_CARD_EDGE_PROTOCOL.GetContext()

Summary
This function retrieves the context driver.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_SMART_CARD_EDGE_GET_CONTEXT) (  
  IN EFI_SMART_CARD_EDGE_PROTOCOL *This,
  OUT UINTN *NumberAidSupported,
  IN OUT UINTN *AidTableSize OPTIONAL,
  OUT SMART_CARD_AID *AidTable OPTIONAL,
  OUT UINTN *NumberSCPresent,
  IN OUT UINTN *CsnTableSize OPTIONAL,
  OUT SMART_CARD_CSN *CsnTable OPTIONAL,
  OUT UINT32 *VersionScEdgeProtocol OPTIONAL
);
This

Indicates a pointer to the calling context. Type EFI_SMART_CARD_EDGE_PROTOCOL is defined in the EFI_SMART_CARD_EDGE_PROTOCOL description.

NumberAidSupported

Number of AIDs this protocol supports.

AidTableSize

On input, number of items allocated for the AID table.
On output, number of items returned by protocol.

AidTable

Table of the AIDs supported by the protocol.

NumberSCPresent

Number of currently present Smart Cards that are supported by protocol.

CsnTableSize

On input, the number of items the buffer CSN table can contain.
On output, the number of items returned by the protocol.

CsnTable

Table of the CSN of the Smart Card present and supported by protocol.

VersionScEdgeProtocol

EFI_SMART_CARD_EDGE_PROTOCOL version.

Related Definitions

```c
// Maximum size for a Smart Card AID (Application IDentifier)
#define SCARD_AID_MAXSIZE 0x0010

// Size of CSN (Card Serial Number)
#define SCARD_CSN_SIZE 0x0010

// Current specification version 1.00
#define SMART_CARD_EDGE_PROTOCOL_VERSION_1 0x00000100

// Parameters type definition
typedef UINT8 SMART_CARD_AID[SCARD_AID_MAXSIZE];
typedef UINT8 SMART_CARD_CSN[SCARD_CSN_SIZE];
```

Description

The GetContext function returns the context of the protocol, the application identifiers supported by the protocol and the number and the CSN unique identifier of Smart Cards that are present and supported by protocol.

If AidTableSize, AidTable, CsnTableSize, CsnTable or VersionProtocol is NULL, the function does not fail but does not fill in such variables.
In case `AidTableSize` indicates a buffer too small to hold all the protocol AID table, only the first `AidTableSize` items of the table are returned in `AidTable`.

In case `CsnTableSize` indicates a buffer too small to hold the entire table of Smart Card CSN present, only the first `CsnTableSize` items of the table are returned in `CsnTable`.

`VersionScEdgeProtocol` returns the version of the `EFI_SMART_CARD_EDGE_PROTOCOL` this driver uses. For this protocol specification value is `SMART_CARD_EDGE_PROTOCOL_VERSION_1`.

In case of Smart Card removal the internal CSN list is immediately updated, even if a connection is opened with that Smart Card.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is <code>NULL</code>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>NumberSCPresent</code> is <code>NULL</code>.</td>
</tr>
</tbody>
</table>

### 37.6.8.3 `EFI_SMART_CARD_EDGE_PROTOCOL`. Connect()

#### Summary

This function establish a connection with a Smart Card the protocol support.

#### Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_SMART_CARD_EDGE_CONNECT) (  
    IN EFI_SMART_CARD_EDGE_PROTOCOL *This,  
    OUT EFI_HANDLE *SCardHandle,  
    IN UINT8 *ScardCsn OPTIONAL,  
    OUT UINT8 *ScardAid OPTIONAL  
);
```

#### Parameters

- **This**
  - Indicates a pointer to the calling context. Type `EFI_SMART_CARD_EDGE_PROTOCOL` is defined in the `EFI_SMART_CARD_EDGE_PROTOCOL` description.

- **SCardHandle**
  - Handle on Smart Card connection.

- **ScardCsn**
  - CSN of the Smart Card the connection has to be established.

- **ScardAid**
  - AID of the Smart Card the connection has been established.

#### Description

The `Connect` function establishes a connection with a Smart Card.

In case of success the `SCardHandle` can be used.

If the `ScardCsn` is `NULL` the connection is established with the first Smart Card the protocol finds in its table of Smart Card present and supported. Else it establish context with the Smart Card whose CSN given by `ScardCsn`.

If `ScardAid` is not `NULL` the function returns the Smart Card AID the protocol supports.
After a successful connect the $SCardHandle$ will remain existing even in case Smart Card removed from Smart Card reader, but all function invoking this $SCardHandle$ will fail. $SCardHandle$ is released only on Disconnect.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>$SCardHandle$ is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>No Smart Card supported by protocol is present, Smart Card with CSN $ScardCsn$ or Reader has been removed. A Disconnect should be performed.</td>
</tr>
</tbody>
</table>

#### 37.6.8.4 EFI_SMART_CARD_EDGE_PROTOCOL.Disconnect()

**Summary**

This function releases a connection previously established by Connect.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *EFI_SMART_CARD_EDGE_DISCONNECT) (
    IN EFI_SMART_CARD_EDGE_PROTOCOL *This,
    IN EFI_HANDLE SCardHandle
);
```

**Parameters**

**This**

Indicates a pointer to the calling context. Type EFI_SMART_CARD_EDGE_PROTOCOL is defined in the EFI_SMART_CARD_EDGE_PROTOCOL description.

**SCardHandle**

Handle on Smart Card connection to release.

**Description**

The Disconnect function releases the connection previously established by a Connect. In case the Smart Card or the Smart Card reader has been removed before this call, this function returns EFI_SUCCESS.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>No connection for $SCardHandle$ value.</td>
</tr>
</tbody>
</table>
37.6.8.5 EFI_SMART_CARD_EDGE_PROTOCOL.GetCsn

Summary
This function returns the Smart Card serial number.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_SMART_CARD_EDGE_GET_CSN) (  
    IN EFI_SMART_CARD_EDGE_PROTOCOL *This,  
    IN EFI_HANDLE SCardHandle,  
    OUT UINT8 Csn[SCARD_CSN_SIZE]  
);

Parameters
This
Indicates a pointer to the calling context. Type EFI_SMART_CARD_EDGE_PROTOCOL is defined in the EFI_SMART_CARD_EDGE_PROTOCOL description.

SCardHandle
Handle on Smart Card connection.

Csn
The Card Serial number, 16 bytes array.

Description
The GetCsn function returns the 16 bytes Smart Card Serial number.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>No connection for SCardHandle value.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>Smart Card or Reader of SCardHandle connection has been removed. A Disconnect should be performed.</td>
</tr>
</tbody>
</table>

37.6.8.6 EFI_SMART_CARD_EDGE_PROTOCOL.GetReaderName

Summary
This function returns the name of the Smart Card reader used for this connection.

Prototype

typedef
EFI_STATUS
(EIFIAPI *EFI_SMART_CARD_EDGE_GET_READER_NAME) (  
    IN EFI_SMART_CARD_EDGE_PROTOCOL *This,  
    IN EFI_HANDLE SCardHandle,  
    IN OUT UINTN ReaderNameLength,  
);

(continues on next page)
Parameters

This
Indicates a pointer to the calling context. Type EFI_SMART_CARD_EDGE_PROTOCOL is defined in the EFI_SMART_CARD_EDGE_PROTOCOL description.

SCardHandle
Handle on Smart Card connection.

ReaderNameLength
On input, a pointer to the variable that holds the maximal size, in bytes, of ReaderName.
On output, the required size, in bytes, for ReaderName.

ReaderName
A pointer to a NULL terminated string that will contain the reader name.

Description
The GetReaderName function returns the name of the Smart Card reader used for this connection.

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>No connection for SCardHandle value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ReaderNameLength is NULL.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>Smart Card or Reader of SCardHandle connection has been removed. A Disconnect should be performed.</td>
</tr>
</tbody>
</table>

37.6.8.7 EFI_SMART_CARD_EDGE_PROTOCOL.VerifyPin()

Summary
This function authenticates a Smart Card user by presenting a PIN code.

Prototype

```c
typedef EFI_STATUS
  (EFIAPI *EFI_SMART_CARD_EDGE_VERIFY_PIN) (
    IN EFI_SMART_CARD_EDGE_PROTOCOL *This,
    IN EFI_HANDLE SCardHandle,
    IN INT32 PinSize,
    IN UINT8 *PinCode,
    OUT BOOLEAN *PinResult,
    OUT UINT32 *RemainingAttempts OPTIONAL
  );
```

Parameters
This
Indicates a pointer to the calling context. Type EFI_SMART_CARD_EDGE_PROTOCOL is defined in the EFI_SMART_CARD_EDGE_PROTOCOL description.

SCardHandle
Handle on Smart Card connection.

PinSize
PIN code buffer size.

PinCode
PIN code to present to the Smart Card.

PinResult
Result of PIN code presentation to the Smart Card.
TRUE when Smart Card founds the PIN code correct.

RemainingAttempts
Number of attempts still possible.

Description
The VerifyPin function presents a PIN code to the Smart Card.
If Smart Card found the PIN code correct the user is considered authenticated to current application, and the function returns TRUE.
Negative or null PinSize value rejected if PinCode is not NULL.
A NULL PinCode buffer means the application didn’t know the PIN, in that case:
- If PinSize value is negative the caller only wants to know if the current chain of the elements Smart Card Edge protocol, Smart Card Reader protocol and Smart Card Reader supports the Secure Pin Entry PCSC V2 functionality.
- If PinSize value is positive or null the caller ask to perform the verify PIN using the Secure PIN Entry functionality.
In PinCode buffer, the PIN value is always given in plaintext, in case of secure messaging the SMART_CARD_EDGE_PROTOCOL will be in charge of all intermediate treatments to build the correct Smart Card APDU.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>PinSize &lt; 0 and Secure PIN Entry functionality not supported.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>No connection for SCardHandle value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Bad value for PinSize : value not supported by Smart Card or, negative with PinCode not null.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PinResult is NULL.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>Smart Card or Reader of SCardHandle connection has been removed. A Disconnect should be performed.</td>
</tr>
</tbody>
</table>
### 37.6.8.8 EFI_SMART_CARD_EDGE_PROTOCOL.GetPinRemaining()

**Summary**
This function gives the remaining number of attempts for PIN code presentation.

**Prototype**
```c
typedef EFI_STATUS (EFIAPI *EFI_SMART_CARD_EDGE_GET_PIN_REMAINING) (  
    IN EFI_SMART_CARD_EDGE_PROTOCOL *This,  
    IN EFI_HANDLE SCardHandle,  
    OUT UINT32 *RemainingAttempts  
);
```

**Parameters**
- **This**
  Indicates a pointer to the calling context. Type `EFI_SMART_CARD_EDGE_PROTOCOL` is defined in the `EFI_SMART_CARD_EDGE_PROTOCOL` description.
- **SCardHandle**
  Handle on Smart Card connection.
- **RemainingAttempts**
  Number of attempts still possible.

**Description**
The number of attempts to present a correct PIN is limited and depends on Smart Card and on PIN. This function will retrieve the number of remaining possible attempts.

**Status Codes Returned**
<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>No connection for <code>SCardHandle</code> value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>RemainingAttempts</code> is NULL.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>Smart Card or Reader of <code>SCardHandle</code> connection has been removed. A Disconnect should be performed.</td>
</tr>
</tbody>
</table>

### 37.6.8.9 EFI_SMART_CARD_EDGE_PROTOCOL.GetData()

**Summary**
This function returns a specific data from Smart Card.

**Prototype**
```c
typedef EFI_STATUS (EFIAPI *EFI_SMART_CARD_EDGE_GET_DATA) (  
    IN EFI_SMART_CARD_EDGE_PROTOCOL *This,  
    OUT UINT32 *Data  
);
```
### Parameters

**This**
Indicates a pointer to the calling context. Type `EFI_SMART_CARD_EDGE_PROTOCOL` is defined in the `EFI_SMART_CARD_EDGE_PROTOCOL` description.

**SCardHandle**
Handle on Smart Card connection.

**DataId**
The type identifier of the data to get.

**DataSize**
On input, in bytes, the size of `Data`. On output, in bytes, the size of buffer required to store the specified data.

**Data**
The data buffer in which the data is returned. The type of the data buffer is associated with the `DataId`. Ignored if `DataSize` is 0.

### Description
This function returns a data from Smart Card. The function is generic for any kind of data, but driver and application must share an EFI_GUID that identify the data.

### Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>No connection for SCardHandle value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>DataId</code> is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>DataSize</code> is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><code>Data</code> is NULL, and <code>DataSize</code> is not zero.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td><code>DataId</code> unknown for this driver.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The size of <code>Data</code> is too small for the specified data and the required size is returned in <code>DataSize</code>.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Operation not performed, conditions not fulfilled. PIN not verified.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>Smart Card or Reader of SCardHandle connection has been removed. A Disconnect should be performed.</td>
</tr>
</tbody>
</table>
37.6.8.10 EFI_SMART_CARD_EDGE_PROTOCOL.GetCredentials()

Summary
This function retrieve credentials store into the Smart Card.

Prototype

```c
typedef EFI_STATUS (EFIAPI *EFI_SMART_CARD_EDGE_GET_CREDENTIAL) ( 
    IN EFI_SMART_CARD_EDGE_PROTOCOL *This, 
    IN EFI_HANDLE SCardHandle, 
    IN OUT UINTN *CredentialSize, 
    OUT UINT8 *CredentialList OPTIONAL 
);
```

Parameters

This
Indicates a pointer to the calling context. Type EFI_SMART_CARD_EDGE_PROTOCOL is defined in the EFI_SMART_CARD_EDGE_PROTOCOL description.

SCardHandle
Handle on Smart Card connection.

CredentialSize
On input, in bytes, the size of buffer to store the list of credentials.
On output, in bytes, the size of buffer required to store the entire list of credentials.

CredentialList
List of credentials stored into the Smart Card. A list of TLV (Tag Length Value) elements organized in containers array.

Related Definitions

```c
//Type of data elements in credentials list
#define SC_EDGE_TAG_HEADER 0x0000 // value of tag field for header, 
    // the number of containers 
#define SC_EDGE_TAG_CERT 0x0001 // value of tag field for certificate 
#define SC_EDGE_TAG_KEY_ID 0x0002 // value of tag field for key index 
    // associated with certificate 
#define SC_EDGE_TAG_KEY_TYPE 0x0003 // value of tag field for key type 
#define SC_EDGE_TAG_KEY_SIZE 0x0004 // value of tag field for key size 

//Length of L fields of TLV items 
#define SC_EDGE_L_SIZE_HEADER 1 // size of L field for header 
#define SC_EDGE_L_SIZE_CERT 2 // size of L field for certificate (big endian) 
#define SC_EDGE_L_SIZE_KEY_ID 1 // size of L field for key index 
#define SC_EDGE_L_SIZE_KEY_TYPE 1 // size of L field for key type 
#define SC_EDGE_L_SIZE_KEY_SIZE 2 // size of L field for key size (big endian) 

//Some TLV items have a fixed value for L field 
#define SC_EDGE_L_VALUE_HEADER 1 // value of L field for header
```

(continues on next page)
#define SC_EDGE_L_VALUE_KEY_ID 1 // value of L field for key index  
#define SC_EDGE_L_VALUE_KEY_TYPE 1 // value of L field for key type  
#define SC_EDGE_L_VALUE_KEY_SIZE 2 // value of L field for key size

//Possible values for key type  
#define SC_EDGE_RSA_EXCHANGE 0x01 //RSA decryption  
#define SC_EDGE_RSA_SIGNATURE 0x02 //RSA signature  
#define SC_EDGE_ECDSA_256 0x03 //ECDSA signature  
#define SC_EDGE_ECDSA_384 0x04 //ECDSA signature  
#define SC_EDGE_ECDSA_521 0x05 //ECDSA signature  
#define SC_EDGE_ECDH_256 0x06 //ECDH agreement  
#define SC_EDGE_ECDH_384 0x07 //ECDH agreement  
#define SC_EDGE_ECDH_521 0x08 //ECDH agreement

Description

The function returns a series of items in TLV (Tag Length Value) format.

First TLV item is the header item that gives the number of following containers (0x00, 0x01, Nb containers).

All these containers are a series of 4 TLV items:

- The certificate item (0x01, certificate size, certificate)
- The Key identifier item (0x02, 0x01, key index)
- The key type item (0x03, 0x01, key type)
- The key size item (0x04, 0x02, key size), key size in number of bits.

Numeric multi-bytes values are on big endian format, most significant byte first:

- The L field value for certificate (2 bytes)
- The L field value for key size (2 bytes)
- The value field for key size (2 bytes)

Status Codes Returned

<table>
<thead>
<tr>
<th>Status Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>No connection for SCardHandle value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>CredentialSize is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>CredentialList is NULL, if CredentialSize is not zero.</td>
</tr>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>The size of CredentialList is too small for the specified data and the required size is returned in CredentialSize.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>Smart Card or Reader of SCardHandle connection has been removed. A Disconnect should be performed.</td>
</tr>
</tbody>
</table>
37.6.8.11 EFI_SMART_CARD_EDGE_PROTOCOL::SignData()

Summary

This function signs an already hashed data with a Smart Card private key.

Prototype

typedef EFI_STATUS
(EIFIAPI *EFI_SMART_CARD_EDGE_SIGN_DATA) (  
  IN EFI_SMART_CARD_EDGE_PROTOCOL *This,  
  IN EFI_HANDLE SCardHandle,  
  IN UINTN KeyId,  
  IN UINTN KeyType,  
  IN EFI_GUID *HashAlgorithm,  
  IN EFI_GUID *PaddingMethod,  
  IN UINT8 *HashedData,  
  OUT UINT8 *SignatureData
);  

Parameters

This

Indicates a pointer to the calling context. Type EFI_SMART_CARD_EDGE_PROTOCOL is defined in the EFI_SMART_CARD_EDGE_PROTOCOL description.

SCardHandle

Handle on Smart Card connection.

KeyId

Identifier of the key container, retrieved in a key index item of credentials.

KeyType

The key type, retrieved in a key type item of credentials.

HashAlgorithm

Hash algorithm used to hash the, one of:

  • EFI_HASH_ALGORITHM_SHA1_GUID
  • EFI_HASH_ALGORITHM_SHA256_GUID
  • EFI_HASH_ALGORITHM_SHA384_GUID
  • EFI_HASH_ALGORITHM_SHA512_GUID

PaddingMethod

Padding method used jointly with hash algorithm, one of:

  • EFI_PADDING_RSASSA_PKCS1V15_GUID
  • EFI_PADDING_RSASSA_PSS_GUID

HashedData

Hash of the data to sign. Size is function of the HashAlgorithm.
SignatureData
Resulting signature with private key KeyId. Size is function of the KeyType and key size retrieved in the associated key size item of credentials.

Related Definitions

```c
// Padding methods GUIDs for signature

// RSASSA-PKCS#1-V1.5 padding method, for signature
#define EFI_PADDING_RSASSA_PKCS1V1P5_GUID
{0x9317ec24,0x7cb0,0x4d0e,
 {0x8b,0x32,0x2e,0xd9,0x20,0x9c,0xd8,0xaf}}

// RSASSA-PSS padding method, for signature
#define EFI_PADDING_RSASSA_PSS_GUID
{0x7b2349e0,0x522d,0x4f8e,
 {0xb9,0x27,0x69,0xd9,0x7c,0x9e,0x79,0x5f}}
```

Description
This function signs data, actually it is the hash of these data that is given to the function.

SignatureData buffer shall be big enough for signature. Signature size is function key size and key type.

Status Codes Returned

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>No connection for SCardHandle value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>KeyId is not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>KeyType is not valid or not corresponding to KeyId.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HashAlgorithm is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HashAlgorithm is not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PaddingMethod is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PaddingMethod is not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HashedData is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>SignatureData is NULL.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Operation not performed, conditions not fulfilled. PIN not verified.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>Smart Card or Reader of SCardHandle connection has been removed. A Disconnect should be performed.</td>
</tr>
</tbody>
</table>
37.6.8.12 EFI_SMART_CARD_EDGE_PROTOCOL.DecryptData()

Summary

This function decrypts data with a PKI/RSA Smart Card private key.

Prototype

typedef EFI_STATUS (EFIAPI *EFI_SMART_CARD_EDGE_DECRYPT_DATA) (  
    IN EFI_SMART_CARD_EDGE_PROTOCOL *This,  
    IN EFI_HANDLE SCardHandle,  
    IN UINTN KeyId,  
    IN EFI_GUID *HashAlgorithm,  
    IN EFI_GUID *PaddingMethod,  
    IN UINTN EncryptedSize,  
    IN UINT8 *EncryptedData,  
    IN OUT UINTN *PlaintextSize,  
    OUT UINT8 *PlaintextData
);

Parameters

This
Indicates a pointer to the calling context. Type EFI_SMART_CARD_EDGE_PROTOCOL is defined in the EFI_SMART_CARD_EDGE_PROTOCOL description.

SCardHandle
Handle on Smart Card connection.

KeyId
Identifier of the key container, retrieved in a key index item of credentials.

HashAlgorithm
Hash algorithm used to hash the, one of:

- EFI_HASH_ALGORITHM_SHA1_GUID
- EFI_HASH_ALGORITHM_SHA256_GUID
- EFI_HASH_ALGORITHM_SHA384_GUID
- EFI_HASH_ALGORITHM_SHA512_GUID

PaddingMethod
Padding method used jointly with hash algorithm, one of:

- EFI_PADDING_NONE_GUID
- EFI_PADDING_RSAES_PKCS1V1P5_GUID
- EFI_PADDING_RSAES_OAEP_GUID

EncryptedSize
Size of data to decrypt

EncryptedData
Data to decrypt

PlaintextSize
On input, in bytes, the size of buffer to store the decrypted data.
On output, in bytes, the size of buffer required to store the decrypted data.

**PlaintextData**
Buffer for decrypted data, padding removed.

**Related Definitions**

```csharp
//
// Padding methods GUIDs for decryption
//
// No padding, for decryption
//
#define EFI_PADDING_NONE_GUID
{0x3629ddb1,0x228c,0x452e,0x72,0x39,0x93,0x79,0xed,0xb6,0x16,0x9f,0xed,0x31,0x6a,0x97,0x00}

// RSAES-PKCS#1-V1.5 padding, for decryption
//
#define EFI_PADDING_RSAES_PKCS1V1P5_GUID
{0xe1c1d0a9,0x40b1,0x4632,0xbd,0xcc,0xd9,0xd6,0xe5,0x29,0x56,0x31}

// RSAES-OAEP padding, for decryption
//
#define EFI_PADDING_RSAES_OAEP_GUID
{0xc1e63ac4,0xd0cf,0x4ce6,0x83,0x5b,0xe8,0xd0,0xe6,0xa8,0xa4,0x5b}
```

**Description**
The function decrypts some PKI / RSA encrypted data with private key securely stored into the Smart Card.
The `KeyId` must reference a key of type SC_EDGE_RSA_EXCHANGE.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>No connection for SCardHandle value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>KeyId is not valid or associated key not of type SC_EDGE_RSA_EXCHANGE.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HashAlgorithm is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>HashAlgorithm is not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PaddingMethod is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PaddingMethod is not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>EncryptedSize is 0.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>EncryptedData is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PlaintextSize is NULL.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>PlaintextData is NULL.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Operation not performed, conditions not fulfilled. PIN not verified.</td>
</tr>
</tbody>
</table>

continues on next page
Table 37.43 – continued from previous page

<table>
<thead>
<tr>
<th>Error Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>PlaintextSize is too small for the plaintext data and the required size is returned in PlaintextSize.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>Smart Card or Reader of SCardHandle connection has been removed. A Disconnect should be performed.</td>
</tr>
</tbody>
</table>

37.6.8.13 EFI_SMART_CARD_EDGE_PROTOCOL.BuildDHAgreement()

Summary

This function performs a secret Diffie Hellman agreement calculation that would be used to derive a symmetric encryption / decryption key.

Prototype

typedef EFI_STATUS (EFIAPI EFI_SMART_CARD_EDGE_BUILD_DH_AGREEMENT) ( 
  IN EFI_SMART_CARD_EDGE_PROTOCOL *This, 
  IN EFI_HANDLE SCardHandle, 
  IN UINTN KeyId, 
  IN UINT8 *dataQx, 
  IN UINT8 *dataQy, 
  OUT UINT8 *DHAgreement 
);

Parameters

This
Indicates a pointer to the calling context. Type EFI_SMART_CARD_EDGE_PROTOCOL is defined in the EFI_SMART_CARD_EDGE_PROTOCOL description.

SCardHandle
Handle on Smart Card connection.

KeyId
Identifier of the key container, retrieved in a key index item of credentials.

dataQx
Public key x coordinate. Size is the same as key size for KeyId. Stored in big endian format.

dataQy
Public key y coordinate. Size is the same as key size for KeyId. Stored in big endian format.

DHAgreement
Buffer for DH agreement computed. Size must be bigger or equal to key size for KeyId.

Description

The function compute a DH agreement that should be diversified to generate a symmetric key to proceed encryption or decryption.

The application and the Smart Card shall agree on the diversification process.

The KeyId must reference a key of one of the types: SC_EDGE_ECDH_256, SC_EDGE_ECDH_384 or SC_EDGE_ECDH_521.

Status Codes Returned
<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The requested command completed successfully.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>This is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>No connection for <strong>SCardHandle</strong> value.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><strong>KeyId</strong> is not valid.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><strong>dataQx</strong> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><strong>dataQy</strong> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td><strong>DHAgreement</strong> is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>Operation not performed, conditions not fulfilled. PIN not verified.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>Smart Card or Reader of <strong>SCardHandle</strong> connection has been removed. <strong>A Disconnect</strong> should be performed.</td>
</tr>
</tbody>
</table>
38.1 EFI Timestamp Protocol

38.1.1 EFI_TIMESTAMP_PROTOCOL

Summary
The Timestamp protocol provides a platform independent interface for retrieving a high resolution timestamp counter.

GUID

```c
#define EFI_TIMESTAMP_PROTOCOL_GUID \
  { 0xafbfde41, 0x2e6e, 0x4262, \
    { 0xba, 0x65, 0x62, 0xb9, 0x23, 0x6e, 0x54, 0x95 }}
```

Protocol Interface Structure

```c
typedef struct _ EFI_TIMESTAMP_PROTOCOL {
  TIMESTAMP_GET GetTimestamp;
  TIMESTAMP_GET_PROPERTIES GetProperties;
} EFI_TIMESTAMP_PROTOCOL;
```

38.1.2 EFI_TIMESTAMP_PROTOCOL.GetTimestamp()

Summary
Retrieves the current timestamp counter value.

Prototype

```c
typedef
UINT64
(EIFIAPI *TIMESTAMP_GET) ( 
  VOID 
);
```

Description
Retrieves the current value of a 64-bit free running timestamp counter.

The counter shall count up in proportion to the amount of time that has passed. The counter value will always roll over to zero. The properties of the counter can be retrieved from GetProperties().
The caller should be prepared for the function to return the same value twice across successive calls. The counter value will not go backwards other than when wrapping, as defined by EndValue in GetProperties().

The frequency of the returned timestamp counter value must remain constant. Power management operations that affect clocking must not change the returned counter frequency. The quantization of counter value updates may vary as long as the value reflecting time passed remains consistent.

**Return Value**
The current value of the free running timestamp counter.

### 38.1.3 EFI_TIMESTAMP_PROTOCOL.GetProperties()

**Summary**
Obtains timestamp counter properties including frequency and value limits.

**Prototype**

```c
typedef EFI_STATUS (EFIAPI *TIMESTAMP_GET_PROPERTIES) (OUT EFI_TIMESTAMP_PROPERTIES *Properties);
```

**Parameters**
- **Properties**
  The properties of the timestamp counter. See “Related Definitions” below.

**Description**
Retrieves the timestamp counter properties structure.

**Related Definitions**

```c
typedef struct {
    UINT64 Frequency;
    UINT64 EndValue;
} EFI_TIMESTAMP_PROPERTIES;
```

**Frequency**
The frequency of the timestamp counter in Hz.

**EndValue**
The value that the timestamp counter ends with immediately before it rolls over. For example, a 64-bit free running counter would have an EndValue of 0xFFFFFFFFFFFFFFFF. A 24-bit free running counter would have an EndValue of 0xFFFFFF.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The properties were successfully retrieved.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>An error occurred trying to retrieve the properties of the timestamp counter subsystem. Properties is not updated.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>Properties is NULL.</td>
</tr>
</tbody>
</table>
38.2 Reset Notification Protocol

38.2.1 EFI_RESET_NOTIFICATION_PROTOCOL

Summary
This protocol provides services to register for a notification when ResetSystem is called.

GUID

```c
#define EFI_RESET_NOTIFICATION_PROTOCOL_GUID \
{ 0x9da34ae0, 0xeaf9, 0x4bbf, \
{ 0x8e, 0xc3, 0xfd, 0x60, 0x22, 0x6c, 0x44, 0xbe } }
```

Protocol Interface Structure

```c
typedef struct _EFI_RESET_NOTIFICATION_PROTOCOL {
  EFI_REGISTER_RESET_NOTIFY RegisterResetNotify;
  EFI_UNREGISTER_RESET_NOTIFY UnRegisterResetNotify;
} EFI_RESET_NOTIFICATION_PROTOCOL;
```

Parameters

**RegisterResetNotify**
- Register a notification function to be called when ResetSystem() is called.

**UnRegisterResetNotify**
- Removes a reset notification function that has been previously registered with RegisterResetNotify().

38.2.2 EFI_RESET_NOTIFICATION_PROTOCOL.RegisterResetNotify()

Summary
Register a notification function to be called when ResetSystem() is called.

Prototype

```c
typedef
EFI_STATUS
(EIFIAPIC *EFI_REGISTER_RESET_NOTIFY) ( 
  IN EFI_RESET_NOTIFICATION_PROTOCOL *This,
  IN EFI_RESET_SYSTEM *ResetFunction,
);```

Parameters

**This**
- A pointer to the EFI_RESET_NOTIFICATION_PROTOCOL instance.

**ResetFunction**
- Points to the function to be called when a ResetSystem() is executed.

Description
The RegisterResetNotify() function registers a notification function that is called when ResetSystem() is called and prior to completing the reset of the platform.
The registered functions must not perform a platform reset themselves. These notifications are intended only for the notification of components which may need some special-purpose maintenance prior to the platform resetting.

The list of registered reset notification functions are processed if `ResetSystem()` is called before `ExitBootServices()` . The list of registered reset notification functions is ignored if `ResetSystem()` is called after `ExitBootServices()` .

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The reset notification function was successfully registered.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ResetFunction is <strong>NULL</strong>.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>There are not enough resources available to register the reset notification function.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>The reset notification function specified by ResetFunction has already been registered.</td>
</tr>
</tbody>
</table>

### 38.2.3 EFI_RESET_NOTIFICATION_PROTOCOL.UnregisterResetNotify()

**Summary**

Unregister a notification function.

**Prototype**

```c
typedef EFI_STATUS
    (EFIAPI *EFI_UNREGISTER_RESET_NOTIFY) (
    IN EFI_RESET_NOTIFICATION_PROTOCOL *This,
    IN EFI_RESET_SYSTEM *ResetFunction
    );
```

**Parameters**

**This**

A pointer to the EFI_RESET_NOTIFICATION_PROTOCOL instance.

**ResetFunction**

The pointer to the ResetFunction being unregistered.

**Description**

The `UnregisterResetNotify()` function removes the previously registered notification using `RegisterResetNotify()`.

**Status Codes Returned**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>The reset notification function was unregistered.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>ResetFunction is <strong>NULL</strong>.</td>
</tr>
</tbody>
</table>
| EFI_INVALID_PARAMETER | The reset notification function specified by ResetFunction was not previously registered using `RegisterResetNotify()`.
```
APPENDIX A — GUID AND TIME FORMATS

All EFI GUIDs (Globally Unique Identifiers) have the format described in RFC 4122 and comply with the referenced algorithms for generating GUIDs. It should also be noted that TimeLow, TimeMid, TimeHighAndVersion fields in the EFI are encoded as little endian. The following table defines the format of an EFI GUID (128 bits).

Table A.1: EFI GUID Format

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>TimeLow</td>
<td>0</td>
<td>4</td>
<td>The low field of the timestamp.</td>
</tr>
<tr>
<td>TimeMid</td>
<td>4</td>
<td>2</td>
<td>The middle field of the timestamp.</td>
</tr>
<tr>
<td>TimeHigh-AndVersion</td>
<td>6</td>
<td>2</td>
<td>The high field of the timestamp multiplexed with the version number.</td>
</tr>
<tr>
<td>ClockSeqHighAndReserved</td>
<td>8</td>
<td>1</td>
<td>The high field of the clock sequence multiplexed with the variant.</td>
</tr>
<tr>
<td>ClockSeqLow</td>
<td>9</td>
<td>1</td>
<td>The low field of the clock sequence.</td>
</tr>
<tr>
<td>Node</td>
<td>10</td>
<td>6</td>
<td>The spatially unique node identifier. This can be based on any IEEE 802 address obtained from a network card. If no network card exists in the system, a cryptographic-quality random number can be used.</td>
</tr>
</tbody>
</table>

This appendix for GUID defines a 60-bit timestamp format that is used to generate the GUID. All EFI time information is stored in 64-bit structures that contain the following format: The timestamp is a 60-bit value containing a count of 100-nanosecond intervals since 00:00:00.00, 15 October 1582 (the date of Gregorian reform to the Christian calendar). This time value will not roll over until the year 3400 AD. It is assumed that a future version of the EFI specification can deal with the year-3400 issue by extending this format if necessary.

This specification also defines a standard text representation of the GUID. This format is also sometimes called the “registry format”. It consists of 36 characters, as follows:

```
aabbccdd-eeff-gghh-iijj-kkllmnnnopp:
```

The pairs `aa` - `pp` are two characters in the range ‘0’-‘9’, ‘a’-‘f’ or ‘A’-‘F’, with each pair representing a single byte hexadecimal value.

The following table describes the relationship between the text representation and a 16-byte buffer, the structure defined in `EFI GUID Format` and the EFI_GUID structure.
### Table A.2: Text representation relationships

<table>
<thead>
<tr>
<th>String</th>
<th>Offset In Buffer</th>
<th>Relationship to EFI GUID Format</th>
<th>Relationship To EFI_GUID</th>
</tr>
</thead>
<tbody>
<tr>
<td>bb</td>
<td>2</td>
<td>TimeLow[16:23]</td>
<td>Data1[16:23]</td>
</tr>
<tr>
<td>cc</td>
<td>1</td>
<td>TimeLow[8:15]</td>
<td>Data1[8:15]</td>
</tr>
<tr>
<td>dd</td>
<td>0</td>
<td>TimeLow[0:7]</td>
<td>Data1[0:7]</td>
</tr>
<tr>
<td>ee</td>
<td>5</td>
<td>TimeMid[8:15]</td>
<td>Data2[8:15]</td>
</tr>
<tr>
<td>ff</td>
<td>4</td>
<td>TimeMid[0:7]</td>
<td>Data2[0:7]</td>
</tr>
<tr>
<td>hh</td>
<td>6</td>
<td>TimeHigh hAndVersion[0:7]</td>
<td>Data3[0:7]</td>
</tr>
<tr>
<td>ii</td>
<td>8</td>
<td>ClockSeqHigh AndReserved[0:7]</td>
<td>Data4[0:7]</td>
</tr>
<tr>
<td>jj</td>
<td>9</td>
<td>ClockSeqLow[0:7]</td>
<td>Data4[8:15]</td>
</tr>
<tr>
<td>kk</td>
<td>10</td>
<td>Node[0:7]</td>
<td>Data4[16:23]</td>
</tr>
<tr>
<td>mm</td>
<td>12</td>
<td>Node[16:23]</td>
<td>Data4[32:39]</td>
</tr>
<tr>
<td>pp</td>
<td>15</td>
<td>Node[40:47]</td>
<td>Data4[56:63]</td>
</tr>
</tbody>
</table>
The EFI console was designed to allow input from a wide variety of devices. This appendix provides examples of the mapping of keyboard input from various types of devices to EFI scan codes. While representative of common console devices in use today, it is not intended to be a comprehensive list. EFI application programmers can use this table to identify the EFI Scan Code generated by a specific key press. The description of the example device input data that generates a EFI Scan Code may be useful to EFI driver writers, as well as showing the limitations on which EFI Scan codes can be generated by different types of console input devices.

The EFI console was designed so that it could map to common console devices. This appendix explains how an EFI console could map to a VGA with PC AT 101/102, PC ANSI, or ANSI X3.64 consoles.

### B.1 EFI_SIMPLE_TEXT_INPUT_PROTOCOL and EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL

Tables **EFI Scan Codes for EFI_SIMPLE_TEXT_INPUT_PROTOCOL** and **EFI Scan Codes for EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL** give examples of how input from a set of common input devices is mapped to EFI scan codes. Terminals and terminal emulators generally report function and editing keys as escape or control sequences. These sequences are formed by a control character followed by one or more additional graphic characters that indicate what the sequence means. ANSI X3.64 terminals generally require an ANSI parser to determine how to interpret a sequence and how to determine that the sequence is complete. These terminals can generate sequences using either 8-bit controls or 7-bit control sequences. Older terminal types, such as the VT100+ have a simpler set of sequences that can be interpreted using simple case statements. These terminals usually generate only 7-bit data, and 7-bit control sequences.

In the tables below, the CSI character is the 8-bit control character 0x9B, and is equivalent to the 7-bit control sequence “ESC [” (the 0x1B control ESC followed by the left bracket character 0x5B). The sequences are shown with spaces for readability, but do not contain the space character.

The VT100+ column represents a common class of terminal emulation that is a superset of the Digital Equipment Corporation (DEC) VT100 terminal. This includes VT-UTF8 (Hyperterm) and PC_ANSI terminal types. The ANSI X3.64 column shows the sequences generated by the DEC VT200 through VT500 terminals, which are an ANSI X3.64 / ISO 6429 compliant.

The USB HID and AT 101/102 columns show the scan codes generated by two common directly attached keyboards. These keyboards are generally used in combination with a VGA text display to form a “VGA Console”.

In the table below, the cells with N/A contained in them are simply intended to reflect that the key may be defined for that terminal or keyboard, but there is no industry standard or consistent mapping for the key. Some input devices might not implement all of these keys.
Table B.1: EFI Scan Codes for EFI_SIMPLE_TEXT_INPUT_PROTOCOL

<table>
<thead>
<tr>
<th>EFI Scan Code</th>
<th>Description</th>
<th>ANSI X3.64 / DEC VT200-500 (8-bit mode)</th>
<th>VT100+ (7-bit mode)</th>
<th>USB Keyboard HID Values</th>
<th>AT 101/102 Keyboard Scan Codes</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>Null scan code</td>
<td>N/A</td>
<td>N/A</td>
<td>0x00</td>
<td>N/A</td>
</tr>
<tr>
<td>0x01</td>
<td>UP ARROW</td>
<td>CSI A</td>
<td>ESC [ A</td>
<td>0x52</td>
<td>0xe0, 0x48</td>
</tr>
<tr>
<td>0x02</td>
<td>DOWN ARROW</td>
<td>CSI B</td>
<td>ESC [ B</td>
<td>0x51</td>
<td>0xe0, 0x50</td>
</tr>
<tr>
<td>0x03</td>
<td>RIGHT ARROW</td>
<td>CSI C</td>
<td>ESC [ C</td>
<td>0x4F</td>
<td>0xe0, 0x4d</td>
</tr>
<tr>
<td>0x04</td>
<td>LEFT ARROW</td>
<td>CSI D</td>
<td>ESC [ D</td>
<td>0x50</td>
<td>0xe0, 0x4b</td>
</tr>
<tr>
<td>0x05</td>
<td>Home</td>
<td>CSI 1 ~</td>
<td>ESC h</td>
<td>0x4A</td>
<td>0xe0, 0x47</td>
</tr>
<tr>
<td>0x06</td>
<td>End</td>
<td>CSI 4 ~</td>
<td>ESC k</td>
<td>0x4D</td>
<td>0xe0, 0x4f</td>
</tr>
<tr>
<td>0x07</td>
<td>Insert</td>
<td>CSI 2 ~</td>
<td>ESC +</td>
<td>0x49</td>
<td>0xe0, 0x52</td>
</tr>
<tr>
<td>0x08</td>
<td>Delete</td>
<td>CSI 3 ~</td>
<td>ESC -</td>
<td>0x4C</td>
<td>0xe0, 0x53</td>
</tr>
<tr>
<td>0x09</td>
<td>Page Up</td>
<td>CSI 5 ~</td>
<td>ESC ?</td>
<td>0x4B</td>
<td>0xe0, 0x49</td>
</tr>
<tr>
<td>0x0a</td>
<td>Page Down</td>
<td>CSI 6 ~</td>
<td>ESC /</td>
<td>0x4E</td>
<td>0xe0, 0x51</td>
</tr>
<tr>
<td>0x0b</td>
<td>Function 1</td>
<td>CSI 1 1 ~</td>
<td>ESC 1</td>
<td>0x3A</td>
<td>0x3b</td>
</tr>
<tr>
<td>0x0c</td>
<td>Function 2</td>
<td>CSI 1 2 ~</td>
<td>ESC 2</td>
<td>0x3B</td>
<td>0x3c</td>
</tr>
<tr>
<td>0x0d</td>
<td>Function 3</td>
<td>CSI 1 3 ~</td>
<td>ESC 3</td>
<td>0x3C</td>
<td>0x3d</td>
</tr>
<tr>
<td>0x0e</td>
<td>Function 4</td>
<td>CSI 1 4 ~</td>
<td>ESC 4</td>
<td>0x3D</td>
<td>0x3e</td>
</tr>
<tr>
<td>0x0f</td>
<td>Function 5</td>
<td>CSI 1 5 ~</td>
<td>ESC 5</td>
<td>0x3E</td>
<td>0x3f</td>
</tr>
<tr>
<td>0x10</td>
<td>Function 6</td>
<td>CSI 1 7 ~</td>
<td>ESC 6</td>
<td>0x3F</td>
<td>0x40</td>
</tr>
<tr>
<td>0x11</td>
<td>Function 7</td>
<td>CSI 1 8 ~</td>
<td>ESC 7</td>
<td>0x40</td>
<td>0x41</td>
</tr>
<tr>
<td>0x12</td>
<td>Function 8</td>
<td>CSI 1 9 ~</td>
<td>ESC 8</td>
<td>0x41</td>
<td>0x42</td>
</tr>
<tr>
<td>0x13</td>
<td>Function 9</td>
<td>CSI 2 0 ~</td>
<td>ESC 9</td>
<td>0x42</td>
<td>0x43</td>
</tr>
<tr>
<td>0x14</td>
<td>Function 10</td>
<td>CSI 2 1 ~</td>
<td>ESC 0</td>
<td>0x43</td>
<td>0x44</td>
</tr>
<tr>
<td>0x15</td>
<td>Escape</td>
<td>ESC</td>
<td>ESC</td>
<td>0x29</td>
<td>0x01</td>
</tr>
</tbody>
</table>

Table B.2: EFI Scan Codes for EFI_SIMPLE_TEXT_INPUT_EX_PROTOCOL

<table>
<thead>
<tr>
<th>EFI Scan Code</th>
<th>Description</th>
<th>ANSI X3.64 / DEC VT200-500 (8-bit mode)</th>
<th>VT100+ (7-bit mode)</th>
<th>USB Keyboard HID Values</th>
<th>AT 101/102 Keyboard Scan Codes</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x15</td>
<td>Function 11</td>
<td>CSI 2 3 ~</td>
<td>ESC !</td>
<td>0x44</td>
<td>0x57</td>
</tr>
<tr>
<td>0x16</td>
<td>Function 12</td>
<td>CSI 2 4 ~</td>
<td>ESC @</td>
<td>0x45</td>
<td>0x58</td>
</tr>
<tr>
<td>0x48</td>
<td>Pause</td>
<td>N/A</td>
<td>N/A</td>
<td>0x48</td>
<td>0xe1, 0x1d, 0x45</td>
</tr>
<tr>
<td>0x68</td>
<td>Function 13</td>
<td>CSI 2 5 ~</td>
<td>N/A</td>
<td>0x68</td>
<td>N/A</td>
</tr>
<tr>
<td>0x69</td>
<td>Function 14</td>
<td>CSI 2 6 ~</td>
<td>N/A</td>
<td>0x69</td>
<td>N/A</td>
</tr>
<tr>
<td>0x6A</td>
<td>Function 15</td>
<td>CSI 2 7 ~</td>
<td>N/A</td>
<td>0x6A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x6B</td>
<td>Function 16</td>
<td>CSI 2 8 ~</td>
<td>N/A</td>
<td>0x6B</td>
<td>N/A</td>
</tr>
<tr>
<td>0x6C</td>
<td>Function 17</td>
<td>CSI 2 9 ~</td>
<td>N/A</td>
<td>0x6C</td>
<td>N/A</td>
</tr>
<tr>
<td>0x6D</td>
<td>Function 18</td>
<td>CSI 3 0 ~</td>
<td>N/A</td>
<td>0x6D</td>
<td>N/A</td>
</tr>
<tr>
<td>0x6E</td>
<td>Function 19</td>
<td>CSI 3 1 ~</td>
<td>N/A</td>
<td>0x6E</td>
<td>N/A</td>
</tr>
<tr>
<td>0x6F</td>
<td>Function 20</td>
<td>CSI 3 2 ~</td>
<td>N/A</td>
<td>0x6F</td>
<td>N/A</td>
</tr>
<tr>
<td>0x70</td>
<td>Function 21</td>
<td>N/A</td>
<td>N/A</td>
<td>0x70</td>
<td>N/A</td>
</tr>
<tr>
<td>0x71</td>
<td>Function 22</td>
<td>N/A</td>
<td>N/A</td>
<td>0x71</td>
<td>N/A</td>
</tr>
<tr>
<td>0x72</td>
<td>Function 23</td>
<td>N/A</td>
<td>N/A</td>
<td>0x72</td>
<td>N/A</td>
</tr>
</tbody>
</table>

continues on next page
Table B.2 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Function</th>
<th>Control Code</th>
<th>Code</th>
<th>Function</th>
<th>Control Code</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x73</td>
<td>Function 24</td>
<td>N/A</td>
<td>0x73</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x7F</td>
<td>Mute</td>
<td>N/A</td>
<td>0x7F</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x80</td>
<td>Volume Up</td>
<td>N/A</td>
<td>0x80</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x81</td>
<td>Volume Down</td>
<td>N/A</td>
<td>0x81</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x100</td>
<td>B rightness Up</td>
<td>N/A</td>
<td>0x100</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x101</td>
<td>B rightness Down</td>
<td>N/A</td>
<td>0x101</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x102</td>
<td>Suspend</td>
<td>N/A</td>
<td>0x102</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x103</td>
<td>Hibernate</td>
<td>N/A</td>
<td>0x103</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x104</td>
<td>Toggle Display</td>
<td>N/A</td>
<td>0x104</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x105</td>
<td>Recovery</td>
<td>N/A</td>
<td>0x105</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x106</td>
<td>Eject</td>
<td>N/A</td>
<td>0x106</td>
<td>N/A</td>
<td>N/A</td>
</tr>
<tr>
<td>0x80</td>
<td>00-0xFFFF</td>
<td>OEM Reserved</td>
<td>N/A</td>
<td>N/A</td>
<td>N/A</td>
</tr>
</tbody>
</table>

B.2 EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL for PC ANSI or ANSI X3.64 terminals

Table below defines how the programmatic methods of the EFI_SIMPLE_TEXT_OUTPUT_PROTOCOLs could be implemented as PC ANSI or ANSI X3.64 terminals. Detailed descriptions of PC ANSI and ANSI X3.64 escape sequences are as follows. The same type of operations can be supported via a PC AT type INT 10h interface.

<table>
<thead>
<tr>
<th>Codes</th>
<th>ANSI X3.64 Codes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ESC [ 2 J</td>
<td>CSI 2 J</td>
<td>Clear Display Screen.</td>
</tr>
<tr>
<td>ESC [ 0 m</td>
<td>CSI 0 m</td>
<td>Normal Text.</td>
</tr>
<tr>
<td>ESC [ 1 m</td>
<td>CSI 1 m</td>
<td>Bright Text.</td>
</tr>
<tr>
<td>ESC [ 7 m</td>
<td>CSI 7 m</td>
<td>Reversed Text.</td>
</tr>
<tr>
<td>ESC [ 30 m</td>
<td>CSI 30 m</td>
<td>Black foreground, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 31 m</td>
<td>CSI 31 m</td>
<td>Red foreground, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 32 m</td>
<td>CSI 32 m</td>
<td>Green foreground, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 33 m</td>
<td>CSI 33 m</td>
<td>Yellow foreground, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 34 m</td>
<td>CSI 34 m</td>
<td>Blue foreground, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 35 m</td>
<td>CSI 35 m</td>
<td>Magenta foreground, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 36 m</td>
<td>CSI 36 m</td>
<td>Cyan foreground, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 37 m</td>
<td>CSI 37 m</td>
<td>White foreground, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 40 m</td>
<td>CSI 40 m</td>
<td>Black background, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 41 m</td>
<td>CSI 41 m</td>
<td>Red background, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 42 m</td>
<td>CSI 42 m</td>
<td>Green background, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 43 m</td>
<td>CSI 43 m</td>
<td>Yellow background, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 44 m</td>
<td>CSI 44 m</td>
<td>Blue background, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 45 m</td>
<td>CSI 45 m</td>
<td>Magenta background, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 46 m</td>
<td>CSI 46 m</td>
<td>Cyan background, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ 47 m</td>
<td>CSI 47 m</td>
<td>White background, compliant with ISO Standard 6429.</td>
</tr>
<tr>
<td>ESC [ = 3 h</td>
<td>CSI = 3 h</td>
<td>Set Mode 80x25 color.</td>
</tr>
</tbody>
</table>

continues on next page
## Table B.3 – continued from previous page

<table>
<thead>
<tr>
<th>ESC [ row;col H</th>
<th>CSI row;col H</th>
<th>Set cursor position to row;col. Row and col are strings of ASCII digits.</th>
</tr>
</thead>
</table>

## Table B.4: Example Keyboard Layout

<table>
<thead>
<tr>
<th>Usage</th>
<th>EFI_KEY enum value</th>
<th>USB Keyboard HID Values</th>
<th>Typical AT-101 key position</th>
</tr>
</thead>
<tbody>
<tr>
<td>Key a and A</td>
<td>EfiKeyC1</td>
<td>0x04</td>
<td>31</td>
</tr>
<tr>
<td>Key b and B</td>
<td>EfiKeyB5</td>
<td>0x05</td>
<td>50</td>
</tr>
<tr>
<td>Key c and C</td>
<td>EfiKeyB3</td>
<td>0x06</td>
<td>48</td>
</tr>
<tr>
<td>Key d and D</td>
<td>EfiKeyC3</td>
<td>0x07</td>
<td>33</td>
</tr>
<tr>
<td>Key e and E</td>
<td>EfiKeyD3</td>
<td>0x08</td>
<td>19</td>
</tr>
<tr>
<td>Key f and F</td>
<td>EfiKeyC4</td>
<td>0x09</td>
<td>34</td>
</tr>
<tr>
<td>Key g and G</td>
<td>EfiKeyC5</td>
<td>0x0A</td>
<td>35</td>
</tr>
<tr>
<td>Key h and H</td>
<td>EfiKeyC6</td>
<td>0x0B</td>
<td>36</td>
</tr>
<tr>
<td>Key i and I</td>
<td>EfiKeyD8</td>
<td>0x0C</td>
<td>24</td>
</tr>
<tr>
<td>Key j and J</td>
<td>EfiKeyC7</td>
<td>0x0D</td>
<td>37</td>
</tr>
<tr>
<td>Key k and K</td>
<td>EfiKeyC8</td>
<td>0x0E</td>
<td>38</td>
</tr>
<tr>
<td>Key l and L</td>
<td>EfiKeyC9</td>
<td>0x0F</td>
<td>39</td>
</tr>
<tr>
<td>Key m and M</td>
<td>EfiKeyB7</td>
<td>0x10</td>
<td>52</td>
</tr>
<tr>
<td>Key n and N</td>
<td>EfiKeyB6</td>
<td>0x11</td>
<td>51</td>
</tr>
<tr>
<td>Key o and O</td>
<td>EfiKeyD9</td>
<td>0x12</td>
<td>25</td>
</tr>
<tr>
<td>Key p and p</td>
<td>EfiKeyD10</td>
<td>0x13</td>
<td>26</td>
</tr>
<tr>
<td>Key q and Q</td>
<td>EfiKeyD1</td>
<td>0x14</td>
<td>17</td>
</tr>
<tr>
<td>Key r and R</td>
<td>EfiKeyD4</td>
<td>0x15</td>
<td>20</td>
</tr>
<tr>
<td>Key s and S</td>
<td>EfiKeyC2</td>
<td>0x16</td>
<td>32</td>
</tr>
<tr>
<td>Key t and T</td>
<td>EfiKeyD5</td>
<td>0x17</td>
<td>21</td>
</tr>
<tr>
<td>Key u and U</td>
<td>EfiKeyD7</td>
<td>0x18</td>
<td>23</td>
</tr>
<tr>
<td>Key v and V</td>
<td>EfiKeyB4</td>
<td>0x19</td>
<td>49</td>
</tr>
<tr>
<td>Key w and W</td>
<td>EfiKeyD2</td>
<td>0x1A</td>
<td>18</td>
</tr>
<tr>
<td>Key x and X</td>
<td>EfiKeyB2</td>
<td>0x1B</td>
<td>47</td>
</tr>
<tr>
<td>Key y and Y</td>
<td>EfiKeyD6</td>
<td>0x1C</td>
<td>22</td>
</tr>
<tr>
<td>Key z and Z</td>
<td>EfiKeyB1</td>
<td>0x1D</td>
<td>46</td>
</tr>
<tr>
<td>Key 1 and !</td>
<td>EfiKeyE1</td>
<td>0x1E</td>
<td>2</td>
</tr>
<tr>
<td>Key 2 and @</td>
<td>EfiKeyE2</td>
<td>0x1F</td>
<td>3</td>
</tr>
<tr>
<td>Key 3 and #</td>
<td>EfiKeyE3</td>
<td>0x20</td>
<td>4</td>
</tr>
<tr>
<td>Key 4 and $</td>
<td>EfiKeyE4</td>
<td>0x21</td>
<td>5</td>
</tr>
<tr>
<td>Key 5 and %</td>
<td>EfiKeyE5</td>
<td>0x22</td>
<td>6</td>
</tr>
<tr>
<td>Key 6 and ^</td>
<td>EfiKeyE6</td>
<td>0x23</td>
<td>7</td>
</tr>
<tr>
<td>Key 7 and &amp;</td>
<td>EfiKeyE7</td>
<td>0x24</td>
<td>8</td>
</tr>
<tr>
<td>Key 8 and *</td>
<td>EfiKeyE8</td>
<td>0x25</td>
<td>9</td>
</tr>
<tr>
<td>Key 9 and (</td>
<td>EfiKeyE9</td>
<td>0x26</td>
<td>10</td>
</tr>
<tr>
<td>Key 0 and )</td>
<td>EfiKeyE10</td>
<td>0x27</td>
<td>11</td>
</tr>
<tr>
<td>Enter*</td>
<td>EfiKeyEnter</td>
<td>0x28</td>
<td>43</td>
</tr>
<tr>
<td>Escape *</td>
<td>EfiKeyEsc</td>
<td>0x29</td>
<td>110</td>
</tr>
<tr>
<td>Del */ Backspace *</td>
<td>EfiKeyBackSpace</td>
<td>0x2A</td>
<td>15</td>
</tr>
<tr>
<td>Tab *</td>
<td>EfiKeyTab</td>
<td>0x2B</td>
<td>16</td>
</tr>
<tr>
<td>Spacebar</td>
<td>EfiKeySpaceBar</td>
<td>0x2C</td>
<td>61</td>
</tr>
<tr>
<td>Key - and _</td>
<td>EfiKeySpaceBar</td>
<td>0x2D</td>
<td>12</td>
</tr>
</tbody>
</table>

continues on next page
| Key = and + | EfiKeySpaceBar | 0x2E | 13 |
| Key [ and { | EfiKeySpaceBar | 0x2F | 27 |
| Key ] and } | EfiKeyD12 | 0x30 | 28 |
| Key and | EfiKeyD13 | 0x31 | 29 |
| Key ; and : | EfiKeyC10 | 0x33 | 40 |
| Key ‘ and ” | EfiKeyC11 | 0x34 | 41 |
| Key ‘ and ~ | EfiKeyE0 | 0x35 | 1 |
| Key . and < | EfiKeyB8 | 0x36 | 53 |
| Key . and > | EfiKeyB9 | 0x37 | 54 |
| Key / and ? | EfiKeyB10 | 0x38 | 55 |
| Capslock * | EfiKeyCapsLock | 0x39 | 30 |
| F1* | EfiKeyF1 | 0x3A | 112 |
| F2* | EfiKeyF2 | 0x3B | 113 |
| F3* | EfiKeyF3 | 0x3C | 114 |
| F4* | EfiKeyF4 | 0x3D | 115 |
| F5* | EfiKeyF5 | 0x3E | 116 |
| F6* | EfiKeyF6 | 0x3F | 117 |
| F7* | EfiKeyF7 | 0x40 | 118 |
| F8* | EfiKeyF8 | 0x41 | 119 |
| F9* | EfiKeyF9 | 0x42 | 120 |
| F10* | EfiKeyF10 | 0x43 | 121 |
| F11* | EfiKeyF11 | 0x44 | 122 |
| F12* | EfiKeyF12 | 0x45 | 123 |
| PrintScreen* | EfiKeyPrint | 0x46 | 124 |
| ScrollLock* | EfiKeySLck | 0x47 | 125 |
| Pause* | EfiKeyPAuse | 0x48 | 126 |
| Insert* | EfiKeyIns | 0x49 | 75 |
| Home* | EfiKeyHome | 0x4A | 80 |
| PageUp* | EfiKeyPgUp | 0x4B | 85 |
| Delete* | EfiKeyDel | 0x4C | 76 |
| End* | EfiKeyEnd | 0x4D | 81 |
| PageDown* | EfiKeyPgDn | 0x4E | 86 |
| RightArrow* | EfiKeyRightArrow | 0x4F | 89 |
| LeftArrow* | EfiKeyLeftArrow | 0x50 | 79 |
| DownArrow* | EfiKeyDownArrow | 0x51 | 84 |
| UpArrow* | EfiKeyUpArrow | 0x52 | 83 |
| NumLock* | EfiKeyNLck | 0x53 | 90 |
| Keypad / | EfiKeySlash | 0x54 | 95 |
| Keypad * | EfiKeyAsterisk | 0x55 | 100 |
| Keypad - | EfiKeyMinus | 0x56 | 105 |
| Keypad + | EfiKeyPlus | 0x57 | 106 |
| Keypad Enter* | EfiKeyEnter | 0x58 | 108 |
| Keypad 1 and End* | EfiKeyOne | 0x59 | 93 |
| Keypad 2 and DownArrow* | EfiKeyTwo | 0x5A | 98 |
| Keypad 3 and | EfiKeyThree PageDown* | 0x5B | 103 |
| Keypad 4 and LeftArrow* | EfiKeyFour | 0x5C | 92 |
| Keypad 5 | EfiKeyFive | 0x5D | 97 |
| Keypad 6 and RightArrow* | EfiKeySix | 0x5E | 102 |

continues on next page
| Keypad 7 and Home *          | EfiKeySeven       | 0x5F | 91 |
| Keypad 8 and UpArrow*       | EfiKeyEight       | 0x60 | 96 |
| Keypad 9 and PageUp *       | EfiKeyNine        | 0x61 | 101|
| Keypad 0 and Insert *       | EfiKeyZero        | 0x62 | 99 |
| Keypad . and Delete *       | EfiKeyPeriod      | 0x63 | 104|
| Menu                         | EfiKeyA4          | 0x76 | n/a|
| LeftControl*                | EfiKeyLCtrl       | 0xE0 | 58 |
| LeftShift*                  | EfiKeyLShift      | 0xE1 | 44 |
| LeftAlt*                    | EfiKeyLAlt        | 0xE2 | 60 |
| LeftLogo*                   | EfiKeyA0          | 0xE3 | 127|
| RightControl*               | EfiKeyRCtrl       | 0xE4 | 64 |
| RightShift*                 | EfiKeyRShift      | 0xE5 | 57 |
| RightAlt*                   | EfiKeyA2          | 0xE6 | 62 |
| RightLogo*                  | EfiKeyA3          | 0xE7 | 128|
| Non-US # and ~              | EfiKeyC12         | 0x32 | 42 |
| Non-US and |                | EfiKeyIntl0       | 0x64 | 45 |
| Non-US and _                | EfiKeyIntl1       | 0x87 | 56 |
| Non-US ¥ and |               | EfiKeyIntl3       | 0x89 | n/a|

An * indicates a non-printable character or keyboard behavior
This appendix presents an example EFI Device Path and explains its relationship to the ACPI name space. An example system design is presented along with its corresponding ACPI name space. These physical examples are mapped back to EFI Device Paths.

### C.1 Example Computer System

The Figure below, *Example Computer System*, represents a hypothetical computer system architecture that will be used to discuss the construction of EFI Device Paths. The system consists of a memory controller that connects directly to the processors’ front side bus. The memory controller is only part of a larger chipset, and it connects to a root PCI host bridge chip, and a secondary root PCI host bridge chip. The secondary PCI host bridge chip produces a PCI bus that contains a PCI to PCI bridge. The root PCI host bridge produces a PCI bus, and also contains USB, ATA66, and AC ’97 controllers. The root PCI host bridge also contains an LPC bus that is used to connect a SIO (Super IO) device. The SIO contains a PC-AT-compatible floppy disk controller, and other PC-AT-compatible devices like a keyboard controller.

The remainder of this appendix describes how to construct a device path for three example devices from the system in *Example Computer System*. The following is a list of the examples used:

- Legacy floppy
- IDE Disk
- Secondary root PCI bus with PCI to PCI bridge

The Figure below is a partial ACPI name space for the system in the *Example Computer System*. Figure *Partial ACPI Name Space for Example System* is based on Figure 5-3 in the *Advanced Configuration and Power Interface Specification*.

### C.2 Legacy Floppy

The legacy floppy controller is contained in the SIO chip that is connected root PCI bus host bridge chip. The root PCI host bridge chip produces PCI bus 0, and other resources that appear directly to the processors in the system.

In ACPI this configuration is represented in the _SB, system bus tree, of the ACPI name space. PCI0 is a child of _SB and it represents the root PCI host bridge. The SIO appears to the system to be a set of ISA devices, so it is represented as a child of PCI0 with the name ISA0. The floppy controller is represented by FLPY as a child of the ISA0 bus.

The EFI Device Path for the legacy floppy is defined in the Table below, *Legacy Floppy Device Path*. It would contain entries for the following things:

- Root PCI Bridge. ACPI Device Path _HID PNP0A03, _UID 0. ACPI name space \_SB\PCI0
Fig. C.1: Example Computer System

Fig. C.2: Partial ACPI Name Space for Example System

C.2. Legacy Floppy
• PCI to ISA Bridge. PCI Device Path with device and function of the PCI to ISA bridge. ACPI name space _SB\PCI0\ISA0
• Floppy Plug and Play ID. ACPI Device Path _HID PNP0303, _UID 0. ACPI name space _SB\PCI0\ISA0\FLPY
• End Device Path

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>1</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>2</td>
<td>2</td>
<td>0x0C</td>
<td>Length</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>0x41D0, 0x0A03</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is encoded in the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>8</td>
<td>4</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>C</td>
<td>1</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>D</td>
<td>1</td>
<td>0x01</td>
<td>Sub type PCI Device Path</td>
</tr>
<tr>
<td>E</td>
<td>2</td>
<td>0x06</td>
<td>Length</td>
</tr>
<tr>
<td>10</td>
<td>1</td>
<td>0x00</td>
<td>PCI Function</td>
</tr>
<tr>
<td>11</td>
<td>1</td>
<td>0x10</td>
<td>PCI Device</td>
</tr>
<tr>
<td>12</td>
<td>1</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>13</td>
<td>1</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>14</td>
<td>2</td>
<td>0x0C</td>
<td>Length</td>
</tr>
<tr>
<td>16</td>
<td>4</td>
<td>0x41D0, 0x0303</td>
<td>_HID PNP0303</td>
</tr>
<tr>
<td>1A</td>
<td>4</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>1E</td>
<td>1</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>1F</td>
<td>1</td>
<td>0xFF</td>
<td>Sub type - End Device Path</td>
</tr>
<tr>
<td>20</td>
<td>2</td>
<td>0x04</td>
<td>Length</td>
</tr>
</tbody>
</table>

### Table C.1: Legacy Floppy Device Path

**C.3 IDE Disk**

The IDE Disk controller is a PCI device that is contained in a function of the root PCI host bridge. The root PCI host bridge is a multi function device and has a separate function for chipset registers, USB, and IDE. The disk connected to the IDE ATA bus is defined as being on the primary or secondary ATA bus, and of being the master or slave device on that bus.

In ACPI this configuration is represented in the _SB, system bus tree, of the ACPI name space. PCI0 is a child of _SB and it represents the root PCI host bridge. The IDE controller appears to the system to be a PCI device with some legacy properties, so it is represented as a child of PCI0 with the name IDE0. PRIM is a child of IDE0 and it represents the primary ATA bus of the IDE controller. MAST is a child of PRIM and it represents that this device is the ATA master device on this primary ATA bus.

The EFI Device Path for the PCI IDE controller is defined in the Table IDE Disk Device Path. It would contain entries for the following things:

- Root PCI Bridge. ACPI Device Path _HID PNP0A03, _UID 0. ACPI name space _SB\PCI0
- PCI IDE controller. PCI Device Path with device and function of the IDE controller. ACPI name space _SB\PCI0\IDE0
- ATA Address. ATA Messaging Device Path for Primary bus and Master device. ACPI name space _SB\PCI0\IDE0\PRIM\MAST
• End Device Path

Table C.2: IDE Disk Device Path

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>1</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>2</td>
<td>2</td>
<td>0x0C</td>
<td>Length</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>0x41D0</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string 'PNP' and is encoded in</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0x0A03</td>
<td>the low order bytes. The compression method is described in the ACPI Specifi</td>
</tr>
<tr>
<td>8</td>
<td>4</td>
<td>0x0000</td>
<td>_UID</td>
</tr>
<tr>
<td>C</td>
<td>1</td>
<td>0x1</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>D</td>
<td>1</td>
<td>0x01</td>
<td>Sub type PCI Device Path</td>
</tr>
<tr>
<td>E</td>
<td>2</td>
<td>0x06</td>
<td>Length</td>
</tr>
<tr>
<td>10</td>
<td>1</td>
<td>0x01</td>
<td>PCI Function</td>
</tr>
<tr>
<td>11</td>
<td>1</td>
<td>0x10</td>
<td>PCI Device</td>
</tr>
<tr>
<td>12</td>
<td>1</td>
<td>0x03</td>
<td>Generic Device Path Header - Messaging Device Path</td>
</tr>
<tr>
<td>13</td>
<td>1</td>
<td>0x01</td>
<td>Sub type - ATAPI Device Path</td>
</tr>
<tr>
<td>14</td>
<td>2</td>
<td>0x06</td>
<td>Length</td>
</tr>
<tr>
<td>16</td>
<td>1</td>
<td>0x00</td>
<td>Primary =0, Secondary = 1</td>
</tr>
<tr>
<td>17</td>
<td>1</td>
<td>0x00</td>
<td>Master = 0, Slave = 1</td>
</tr>
<tr>
<td>18</td>
<td>2</td>
<td>0x0000</td>
<td>LUN</td>
</tr>
<tr>
<td>1A</td>
<td>1</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>1B</td>
<td>1</td>
<td>0xFF</td>
<td>Sub type - End Device Path</td>
</tr>
<tr>
<td>TC</td>
<td>2</td>
<td>0x04</td>
<td>Length</td>
</tr>
</tbody>
</table>

C.4 Secondary Root PCI Bus with PCI to PCI Bridge

The secondary PCI host bridge materializes a second set of PCI buses into the system. The PCI buses on the secondary PCI host bridge are totally independent of the PCI buses on the root PCI host bridge. The only relationship between the two is they must be configured to not consume the same resources. The primary PCI bus of the secondary PCI host bridge also contains a PCI to PCI bridge. There is some arbitrary PCI device plugged in behind the PCI to PCI bridge in a PCI slot.

In ACPI this configuration is represented in the _SB, system bus tree, of the ACPI name space. PCI1 is a child of _SB and it represents the secondary PCI host bridge. The PCI to PCI bridge and the device plugged into the slot on its primary bus are not described in the ACPI name space. These devices can be fully configured by following the applicable PCI specification.

The EFI Device Path for the secondary root PCI bridge with a PCI to PCI bridge is defined in the Table Secondary Root PCI Bus with PCI to PCI Bridge Device Path. It would contain entries for the following things:

• Root PCI Bridge. ACPI Device Path _HID PNP0A03, _UID 1. ACPI name space \_SB\PCI1
• PCI to PCI Bridge. PCI Device Path with device and function of the PCI Bridge. ACPI name space \_SB\PCI1, PCI to PCI bridges are defined by PCI specification and not ACPI.
• PCI Device. PCI Device Path with the device and function of the PCI device. ACPI name space \_SB\PCI1, PCI devices are defined by PCI specification and not ACPI.
• End Device Path.
Table C.3: Secondary Root PCI Bus with PCI to PCI Bridge Device Path

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Data</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>1</td>
<td>0x02</td>
<td>Generic Device Path Header - Type ACPI Device Path</td>
</tr>
<tr>
<td>1</td>
<td>1</td>
<td>0x01</td>
<td>Sub type - ACPI Device Path</td>
</tr>
<tr>
<td>2</td>
<td>2</td>
<td>0x0C</td>
<td>Length</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>0x41D0</td>
<td>_HID PNP0A03 - 0x41D0 represents the compressed string ‘PNP’ and is encoded in \ the low order bytes. The compression method is described in the ACPI Specification.</td>
</tr>
<tr>
<td>8</td>
<td>4</td>
<td>0x0001</td>
<td>_UID</td>
</tr>
<tr>
<td>C</td>
<td>1</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>D</td>
<td>1</td>
<td>0x01</td>
<td>Sub type PCI Device Path</td>
</tr>
<tr>
<td>E</td>
<td>2</td>
<td>0x06</td>
<td>Length</td>
</tr>
<tr>
<td>10</td>
<td>1</td>
<td>0x00</td>
<td>PCI Function for PCI to PCI bridge</td>
</tr>
<tr>
<td>11</td>
<td>1</td>
<td>0x0c</td>
<td>PCI Device for PCI to PCI bridge</td>
</tr>
<tr>
<td>12</td>
<td>1</td>
<td>0x01</td>
<td>Generic Device Path Header - Type Hardware Device Path</td>
</tr>
<tr>
<td>13</td>
<td>1</td>
<td>0x01</td>
<td>Sub type PCI Device Path</td>
</tr>
<tr>
<td>14</td>
<td>2</td>
<td>0x08</td>
<td>Length</td>
</tr>
<tr>
<td>16</td>
<td>1</td>
<td>0x00</td>
<td>PCI Function for PCI Device</td>
</tr>
<tr>
<td>17</td>
<td>1</td>
<td>0x00</td>
<td>PCI Device for PCI Device</td>
</tr>
<tr>
<td>18</td>
<td>1</td>
<td>0x7F</td>
<td>Generic Device Path Header - Type End of Hardware Device Path</td>
</tr>
<tr>
<td>19</td>
<td>1</td>
<td>0xFF</td>
<td>Sub type - End Device Path</td>
</tr>
<tr>
<td>1A</td>
<td>2</td>
<td>0x04</td>
<td>Length</td>
</tr>
</tbody>
</table>

C.5 ACPI Terms

Names in the ACPI name space that start with an underscore (“_”) are reserved by the ACPI specification and have architectural meaning. All ACPI names in the name space are four characters in length. The following four ACPI names are used in this specification.

_**ADR.** The Address on a bus that has standard enumeration. An example would be PCI, where the enumeration method is described in the PCI Local Bus specification.

_**CRS.** The current resource setting of a device. A _**CRS** is required for devices that are not enumerated in a standard fashion. _**CRS** is how ACPI converts nonstandard devices into Plug and Play devices.

_**HID.** Represents a device’s Plug and Play hardware ID, stored as a 32-bit compressed EISA ID. _**HID** objects are optional in ACPI. However, a _**HID** object must be used to describe any device that will be enumerated by the ACPI driver in the OS. This is how ACPI deals with non-Plug and Play devices.

_**UID.** Is a serial number style ID that does not change across reboots. If a system contains more than one device that reports the same _**HID**, each device must have a unique _**UID**. The _**UID** only needs to be unique for device that have the exact same _**HID** value.
C.6 EFI Device Path as a Name Space

The Figure below shows the EFI Device Path for the example system represented as a name space. The Device Path can be represented as a name space, but EFI does support manipulating the Device Path as a name space. You can only access Device Path information by locating the `DEVICE_PATH_INTERFACE` from a handle. Not all the nodes in a Device Path will have a handle.

![ EFI Device Path as a Name Space Diagram ]

Fig. C.3: EFI Device Path Displayed As a Name Space
APPENDIX D — STATUS CODES

EFI interfaces return an \textit{EFI_STATUS} code. See \textit{EFI_STATUS Success Codes (High Bit Clear)} , \textit{EFI_STATUS Error Codes (High Bit Set)} , \textit{EFI_STATUS Warning Codes (High Bit Clear)} list these codes for success, errors, and warnings, respectively. The range of status codes that have the highest bit set and the next to highest bit clear are reserved for use by EFI. The range of status codes that have both the highest bit set and the next to highest bit set are reserved for use by OEMs. Success and warning codes have their highest bit clear, so all success and warning codes have positive values. The range of status codes that have both the highest bit clear and the next to highest bit clear are reserved for use by EFI. The range of status code that have the highest bit clear and the next to highest bit set are reserved for use by OEMs. The Table below lists the status code ranges described above.

<table>
<thead>
<tr>
<th>Supported 32-bit Range</th>
<th>Supported 64-bit Architecture Ranges</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00000000-0x1fffffff</td>
<td>0x0000000000000000-0xfffffffffffff</td>
<td>Warning codes reserved for use by UEFI main specification.</td>
</tr>
<tr>
<td>0x20000000-0x3fffffff</td>
<td>0x2000000000000000-0xfffffffffffff</td>
<td>Warning codes reserved for use by the Platform Initialization Architecture Specification.</td>
</tr>
<tr>
<td>0x40000000-0x7fffffff</td>
<td>0x4000000000000000-0x7fffffffffffff</td>
<td>Warning codes reserved for OEM usage.</td>
</tr>
<tr>
<td>0x80000000-0x9fffffff</td>
<td>0x8000000000000000-0x9fffffffffffff</td>
<td>Error codes reserved for use by UEFI main specification.</td>
</tr>
<tr>
<td>0xa0000000-0xbfffffff</td>
<td>0xa000000000000000-0xbfffffffffffff</td>
<td>Error codes reserved for use by the Platform Initialization Architecture Specification.</td>
</tr>
<tr>
<td>0xc0000000-0xffffffffff</td>
<td>0xc000000000000000-0xcfffffffffffff</td>
<td>Error codes reserved for OEM usage.</td>
</tr>
</tbody>
</table>

Table D.2: EFI_STATUS Success Codes (High Bit Clear)

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_SUCCESS</td>
<td>0</td>
<td>The operation completed successfully.</td>
</tr>
</tbody>
</table>

Table D.3: EFI_STATUS Error Codes (High Bit Set)

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_LOAD_ERROR</td>
<td>1</td>
<td>The image failed to load.</td>
</tr>
<tr>
<td>EFI_INVALID_PARAMETER</td>
<td>2</td>
<td>A parameter was incorrect.</td>
</tr>
<tr>
<td>EFI_UNSUPPORTED</td>
<td>3</td>
<td>The operation is not supported.</td>
</tr>
<tr>
<td>EFI_BAD_BUFFER_SIZE</td>
<td>4</td>
<td>The buffer was not the proper size for the request.</td>
</tr>
</tbody>
</table>

continues on next page
Table D.3 – continued from previous page

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_BUFFER_TOO_SMALL</td>
<td>5</td>
<td>The buffer is not large enough to hold the requested data. The required buffer size is returned in the appropriate parameter when this error occurs.</td>
</tr>
<tr>
<td>EFI_NOT_READY</td>
<td>6</td>
<td>There is no data pending upon return.</td>
</tr>
<tr>
<td>EFI_DEVICE_ERROR</td>
<td>7</td>
<td>The physical device reported an error while attempting the operation.</td>
</tr>
<tr>
<td>EFI_WRITE_PROTECTED</td>
<td>8</td>
<td>The device cannot be written to.</td>
</tr>
<tr>
<td>EFI_OUT_OF_RESOURCES</td>
<td>9</td>
<td>A resource has run out.</td>
</tr>
<tr>
<td>EFI_VOLUME_CORRUPTED</td>
<td>10</td>
<td>An inconstancy was detected on the file system causing the operating to fail.</td>
</tr>
<tr>
<td>EFI_VOLUME_FULL</td>
<td>11</td>
<td>There is no more space on the file system.</td>
</tr>
<tr>
<td>EFI_NO_MEDIA</td>
<td>12</td>
<td>The device does not contain any medium to perform the operation.</td>
</tr>
<tr>
<td>EFI_MEDIA_CHANGED</td>
<td>13</td>
<td>The medium in the device has changed since the last access.</td>
</tr>
<tr>
<td>EFI_NOT_FOUND</td>
<td>14</td>
<td>The item was not found.</td>
</tr>
<tr>
<td>EFI_ACCESS_DENIED</td>
<td>15</td>
<td>Access was denied.</td>
</tr>
<tr>
<td>EFI_NO_RESPONSE</td>
<td>16</td>
<td>The server was not found or did not respond to the request.</td>
</tr>
<tr>
<td>EFI_NO_MAPPING</td>
<td>17</td>
<td>A mapping to a device does not exist.</td>
</tr>
<tr>
<td>EFI_TIMEOUT</td>
<td>18</td>
<td>The timeout time expired.</td>
</tr>
<tr>
<td>EFI_NOT_STARTED</td>
<td>19</td>
<td>The protocol has not been started.</td>
</tr>
<tr>
<td>EFI_ALREADY_STARTED</td>
<td>20</td>
<td>The protocol has already been started.</td>
</tr>
<tr>
<td>EFI_ABORTED</td>
<td>21</td>
<td>The operation was aborted.</td>
</tr>
<tr>
<td>EFI_ICMP_ERROR</td>
<td>22</td>
<td>An ICMP error occurred during the network operation.</td>
</tr>
<tr>
<td>EFI_TFTP_ERROR</td>
<td>23</td>
<td>A TFTP error occurred during the network operation.</td>
</tr>
<tr>
<td>EFI_PROTOCOL_ERROR</td>
<td>24</td>
<td>A protocol error occurred during the network operation.</td>
</tr>
<tr>
<td>EFI_INCOMPATIBLE_VERSION</td>
<td>25</td>
<td>The function encountered an internal version that was incompatible with a version requested by the caller.</td>
</tr>
<tr>
<td>EFI_SECURITY_VIOLATION</td>
<td>26</td>
<td>The function was not performed due to a security violation.</td>
</tr>
<tr>
<td>EFI_CRC_ERROR</td>
<td>27</td>
<td>A CRC error was detected.</td>
</tr>
<tr>
<td>EFI_END_OF_MEDIA</td>
<td>28</td>
<td>Beginning or end of media was reached.</td>
</tr>
<tr>
<td>EFI_END_OF_FILE</td>
<td>31</td>
<td>The end of the file was reached.</td>
</tr>
<tr>
<td>EFI_INVALID_LANGUAGE</td>
<td>32</td>
<td>The language specified was invalid.</td>
</tr>
<tr>
<td>EFI_COMPROMISED_DATA</td>
<td>33</td>
<td>The security status of the data is unknown or compromised and the data must be updated or replaced to restore a valid security status.</td>
</tr>
<tr>
<td>EFI_IP_ADDRESS_CONFLICT</td>
<td>34</td>
<td>There is an address conflict address allocation</td>
</tr>
<tr>
<td>EFI_HTTP_ERROR</td>
<td>35</td>
<td>A HTTP error occurred during the network operation.</td>
</tr>
</tbody>
</table>

Table D.4: EFI_STATUS Warning Codes (High Bit Clear)

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>continues on next page</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### Table D.4 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_WARN_UNKNOWN_GLYPH</td>
<td>1</td>
<td>The string contained one or more characters that the device could not render and were skipped.</td>
</tr>
<tr>
<td>EFI_WARN_DELETE_FAILURE</td>
<td>2</td>
<td>The handle was closed, but the file was not deleted.</td>
</tr>
<tr>
<td>EFI_WARN_WRITE_FAILURE</td>
<td>3</td>
<td>The handle was closed, but the data to the file was not flushed properly.</td>
</tr>
<tr>
<td>EFI_WARN_BUFFER_TOO_SMALL</td>
<td>4</td>
<td>The resulting buffer was too small, and the data was truncated to the buffer size.</td>
</tr>
<tr>
<td>EFI_WARN_STALE_DATA</td>
<td>5</td>
<td>The data has not been updated within the time-frame set by local policy for this type of data.</td>
</tr>
<tr>
<td>EFI_WARN_FILE_SYSTEM</td>
<td>6</td>
<td>The resulting buffer contains UEFI-compliant file system.</td>
</tr>
<tr>
<td>EFI_WARN_RESET_REQUIRED</td>
<td>7</td>
<td>The operation will be processed across a system reset.</td>
</tr>
</tbody>
</table>
APPENDIX E — UNIVERSAL NETWORK DRIVER INTERFACES

E.1 Introduction

This appendix defines the 32/64-bit H/W and S/W Universal Network Driver Interfaces (UNDIs). These interfaces provide one method for writing a network driver; other implementations are possible.

E.1.1 Definitions

E-1 Definitions

<table>
<thead>
<tr>
<th>Term</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>BC</td>
<td><strong>BaseCode</strong>&lt;br&gt;The PXE BaseCode, included as a core protocol in EFI, is comprised of a simple network stack (UDP/IP) and a few common network protocols (DHCP, Bootserver Discovery, TFTP) that are useful for remote booting machines.</td>
</tr>
<tr>
<td>LOM</td>
<td><strong>LAN On Motherboard</strong>&lt;br&gt;This is a network device that is built onto the motherboard (or baseboard) of the machine.</td>
</tr>
<tr>
<td>NBP</td>
<td><strong>Network Bootstrap Program</strong>&lt;br&gt;This is the first program that is downloaded into a machine that has selected a PXE capable device for remote boot services.&lt;br&gt;A typical NBP examines the machine it is running on to try to determine if the machine is capable of running the next layer (OS or application).&lt;br&gt;If the machine is not capable of running the next layer, control is returned to the EFI boot manager and the next boot device is selected.&lt;br&gt;If the machine is capable, the next layer is downloaded and control can then be passed to the downloaded program.&lt;br&gt;Though most NBPs are OS loaders, NBPs can be written to be standalone applications such as diagnostics, backup/restore, remote management agents, browsers, etc.</td>
</tr>
</tbody>
</table>
### NIC

**Network Interface Card**

Technically, this is a network device that is inserted into a bus on the motherboard or in an expansion board. For the purposes of this document, the term NIC will be used in a generic sense, meaning any device that enables a network connection (including LOMs and network devices on external busses (USB, 1394, etc.).)

### ROM

**Read-Only Memory**

When used in this specification, ROM refers to a nonvolatile memory storage device on a NIC.

### PXE

**Preboot Execution Environment**

The complete PXE specification covers three areas; the client, the network and the server.

**Client**

- Makes network devices into bootable devices.
- Provides APIs for PXE protocol modules in EFI and for universal drivers in the OS.

**Network**

- Uses existing technology: DHCP, TFTP, etc.
- Adds “vendor specific” tags to DHCP to define PXE specific operation within DHCP.
- Adds multicast TFTP for high bandwidth remote boot applications.
- Defines Bootserver discovery based on DHCP packet format.

**Server**

- **Bootserver**: Responds to Bootserver discovery requests and serves up remote boot images.
- **proxyDHCP**: Used to ease the transition of PXE clients and servers into existing network infrastructure. proxyDHCP provides the additional DHCP information that is needed by PXE clients and Bootservers without making changes to existing DHCP servers.
- **MTFTP**: Adds multicast support to a TFTP server.
- **Plug-In Modules**: Example proxyDHCP and Bootservers provided in the PXE SDK (software development kit) have the ability to take plug-in modules (PIMs). These PIMs are used to change/enhance the capabilities of the proxyDHCP and Bootservers.

### UNDI

**Universal Network Device Interface**

UNDI is an architectural interface to NICs. Traditionally NICs have had custom interfaces and custom drivers (each NIC had a driver for each OS on each platform architecture).

Two variations of UNDI are defined in this specification: H/W UNDI and S/W UNDI. H/W UNDI is an architectural hardware interface to a NIC. S/W UNDI is a software implementation of the H/W UNDI.
E.1.2 Referenced Specifications

When implementing PXE services, protocols, ROMs or drivers, it is a good idea to understand the related network protocols and BIOS specifications. The Table, below includes all of the specifications referenced in this document.

Referenced Specifications

<table>
<thead>
<tr>
<th>Acronym</th>
<th>Protocol/Specification</th>
</tr>
</thead>
</table>
| ARP     | Address Resolution Protocol  
|         | • Required reading for those implementing the PXE Base Code Protocol.  
|         | • See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Address Resolution Protocol”. |
| Assigned Numbers | Lists the reserved numbers used in the RFCs and in this specification.  
|         | • See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Assigned Numbers”. |
| BIOS    | Basic Input/Output System  
|         | • Contact your BIOS manufacturer for reference and programming manuals. |
| BOOTP   | Bootstrap Protocol -  
|         | • See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Bootstrap Protocol (BOOTP)”.  
|         | These references are included for backward compatibility. BC protocol supports DHCP and BOOTP:  
|         | • See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “BOOTP Clarifications and Extensions”.  
|         | • See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Bootstrap Protocol (BOOTP) Interoperation Between DHCP and BOOTP”.  
|         | Required reading for those implementing the PXE Base Code Protocol BC protocol or PXE Bootservers. |
| DHCP    | Dynamic Host Configuration Protocol  
|         | • See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “DHCP”.  
|         | • See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Index of RFC (IETF)”.  
|         | • See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “DHCP Reconfigure Extension”.  
|         | • See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “DHCP for Ipv4”.  
|         | • See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “Interoperations between DHCP and BOOTP”.  
<p>|         | Required reading for those implementing the PXE Base Code Protocol or PXE Bootservers. |</p>
<table>
<thead>
<tr>
<th><strong>EFI</strong></th>
<th><strong>Extensible Firmware Interface</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “Intel Developer Centers”. Required reading for those implementing NBPs, OS loaders and preboot applications for machines with the EFI preboot environment.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th><strong>ICMP</strong></th>
<th><strong>Internet Control Message Protocol</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “ICMP for Ipv4”.</td>
</tr>
<tr>
<td></td>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “ICMP for Ipv6”. Required reading for those implementing the BC protocol.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th><strong>IETF</strong></th>
<th><strong>Internet Engineering Task Force</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “Internet Engineering Task Force (IETF)”. This is a good starting point for obtaining electronic copies of Internet standards, drafts, and RFCs.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th><strong>IGMP</strong></th>
<th><strong>Internet Group Management Protocol</strong></th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th><strong>IP</strong></th>
<th><strong>Internet Protocol</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Ipv4: <a href="http://www.ietf.org/rfc/rfc0791.txt">http://www.ietf.org/rfc/rfc0791.txt</a></td>
</tr>
<tr>
<td></td>
<td>• “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “Ipv4”.</td>
</tr>
<tr>
<td></td>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “Ipv6”. Required reading for those implementing the BC protocol.</td>
</tr>
</tbody>
</table>

| **MTFTP** | **Multicast TFTP** - Defined in the 16-bit PXE specification. Required reading for those implementing the PXE Base Code Protocol. |

<table>
<thead>
<tr>
<th><strong>PCI</strong></th>
<th><strong>Peripheral Component Interface</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “Peripheral Component Interface (PCI)”. Source for PCI specifications. Required reading for those implementing S/W or H/W UNDI on a PCI NIC or LOM.</td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>PnP</th>
<th>Plug-and-Play</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “Plug and Play”.</td>
</tr>
<tr>
<td></td>
<td>Source for PnP specifications.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PXE</th>
<th>Preboot eXecution Environment</th>
</tr>
</thead>
<tbody>
<tr>
<td>16-bit PXE v2.1:</td>
<td></td>
</tr>
<tr>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “Preboot eXecution Environment (PXE)”.</td>
<td></td>
</tr>
<tr>
<td>Required reading.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>RFC</th>
<th>Request For Comments</th>
</tr>
</thead>
<tbody>
<tr>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “Request for Comments”.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>TCP</th>
<th>Transmission Control Protocol</th>
</tr>
</thead>
<tbody>
<tr>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “TCPv4”.</td>
<td></td>
</tr>
<tr>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “TCPv6”.</td>
<td></td>
</tr>
<tr>
<td>Required reading for those implementing the PXE Base Code Protocol.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>TFTP</th>
<th>Trivial File Transfer Protocol</th>
</tr>
</thead>
<tbody>
<tr>
<td>TFTP</td>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “TFTP Protocol”.</td>
</tr>
<tr>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “TFTP Option Extension”.</td>
<td></td>
</tr>
<tr>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “TFTP Blocksize Option”.</td>
<td></td>
</tr>
<tr>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “TFTP Timeout Interval and Transfer Size Options”.</td>
<td></td>
</tr>
<tr>
<td>Required reading for those implementing the PXE Base Code Protocol.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>UDP</th>
<th>User Datagram Protocol</th>
</tr>
</thead>
<tbody>
<tr>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “UDP over IPv4”.</td>
<td></td>
</tr>
<tr>
<td>• See “Links to UEFI-Related Documents” (<a href="http://uefi.org/uefi">http://uefi.org/uefi</a>) under the heading “UDP over IPv6”.</td>
<td></td>
</tr>
<tr>
<td>Required reading for those implementing the PXE Base Code Protocol.</td>
<td></td>
</tr>
</tbody>
</table>
E.1.3 OS Network Stacks

This is a simplified overview of three OS network stacks that contain three types of network drivers: Custom, S/W UNDI and H/W UNDI. The Figure, below, depicts an application bound to an OS protocol stack, which is in turn bound to a protocol driver that is bound to three NICs. The Table, below, *Driver Types: Pros and Cons* gives a brief list of pros and cons about each type of driver implementation.

![Image of network stacks](image.png)

Fig. E.1: Network Stacks with Three Classes of Drivers

**Driver Types: Pros and Cons**

<table>
<thead>
<tr>
<th>Driver</th>
<th>Pro</th>
<th>Con</th>
</tr>
</thead>
</table>
| Custom     | • Can be very fast and efficient. NIC vendor tunes driver to OS & device.  
• OS vendor does not have to write NIC driver. | • New driver for each OS/architecture must be maintained by NIC vendor.  
• OS vendor must trust code supplied by third-party.  
• OS vendor cannot test all possible driver/NIC versions.  
• Driver must be installed before NIC can be used.  
• Possible performance sink if driver is poorly written.  
• Possible security risk if driver has back door. |

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### Table E.3 – continued from previous page

<table>
<thead>
<tr>
<th>S/W UNDI</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>• S/W UNDI driver is simpler than a Custom driver. Easier to test outside of the OS environment.</td>
<td>• Slightly slower than Custom or H/W UNDI because of extra call layer between protocol stack and NIC.</td>
</tr>
<tr>
<td>• OS vendor can tune the universal protocol driver for best OS performance.</td>
<td>• S/W UNDI driver must be loaded before NIC can be used.</td>
</tr>
<tr>
<td>• NIC vendor only has to write one driver per processor architecture.</td>
<td>• OS vendor has to write the universal driver.</td>
</tr>
<tr>
<td>• S/W UNDI driver must be loaded before NIC can be used.</td>
<td>• Possible performance sink if driver is poorly written.</td>
</tr>
<tr>
<td>• OS vendor has to write the universal driver.</td>
<td>• Possible security risk if driver has back door.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>H/W UNDI</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>• H/W UNDI provides a common architectural interface to all network devices.</td>
<td>• OS vendor has to write the universal driver (this might also be a Pro, depending on your point of view).</td>
</tr>
<tr>
<td>• OS vendor controls all security and performance issues in network stack.</td>
<td></td>
</tr>
<tr>
<td>• NIC vendor does not have to write any drivers.</td>
<td></td>
</tr>
<tr>
<td>• NIC can be used without an OS or driver installed (preboot management).</td>
<td></td>
</tr>
</tbody>
</table>

### E.2 Overview

There are three major design changes between this specification and the 16-bit UNDI in version 2.1 of the PXE Specification:

• A new architectural hardware interface has been added.
• All UNDI commands use the same command format.
• BC is no longer part of the UNDI ROM.

### E.2.1 32/64-bit UNDI Interface

The !PXE structures are used locate and identify the type of 32/64-bit UNDI interface (H/W or S/W), as shown in the Figure, below. These structures are normally only used by the system BIOS and universal network drivers.

**Major Minor reserved**

The !PXE structures used for H/W and S/W UNDIs are similar but not identical. The difference in the format is tied directly to the differences required by the implementation. The !PXE structures for 32/64-bit UNDI are not compatible with the !PXE structure for 16-bit UNDI.

The !PXE structure for H/W UNDI is built into the NIC hardware. The first nine fields (from offsets 0x00 to 0x0F) are implemented as read-only memory (or ports). The last three fields (from Len to Len + 0x0F) are implemented as read/write memory (or ports). The optional reserved field at 0x10 is not defined in this specification and may be used for vendor data.

The !PXE structure for S/W UNDI can be loaded into system memory from one of three places; ROM on a NIC, system nonvolatile storage, or external storage. Since there are no direct memory or I/O ports available in the S/W UNDI !PXE structure, an indirect callable entry point is provided. S/W UNDI developers are free to make their internal designs...
as simple or complex as they desire, as long as all of the UNDI commands in this specification are implemented. Descriptions of the fields in the Table below.

Table E.4: !PXE Structure Field Definitions

<table>
<thead>
<tr>
<th>Identifier</th>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Signature</td>
<td>“!PXE”</td>
<td>!PXE structure signature. This field is used to locate an UNDI hardware or software interface in system memory (or I/O) space. ‘!’ is in the first (lowest address) byte, ‘P’ is in the second byte, ‘X’ in the third and ‘E’ in the last. This field must be aligned on a 16-byte boundary (the last address byte must be zero).</td>
</tr>
</tbody>
</table>
| Len        | Varies| Number of !PXE structure bytes to checksum. When computing the checksum of this structure the Len field MUST be used as the number of bytes to checksum. The !PXE structure checksum is computed by adding all of the bytes in the structure, starting with the first byte of the structure Signature: ‘!’.
If the 8-bit sum of all of the unsigned bytes in this structure is not zero, this is not a valid !PXE structure. |
| Fudge      | Varies| This field is used to make the 8-bit checksum of this structure equal zero. |
| Rev        | 0x03  | Revision of this structure. |

Fig. E.2: !PXE Structures for H/W and S/W UNDI
This field reports the number (minus one) of physical external network connections that are controlled by this !PXE interface. (If there is one network connector, this field is zero. If there are two network connectors, this field is one.) For !PXE structure revision 0x03 or higher, in addition to this field, the value in IFcntExt field must be left-shifted by 8-bits and ORed with IFcnt to get the 16-bit value for the total number (minus one) of physical external network connections that are controlled by this !PXE interface.

<table>
<thead>
<tr>
<th>Minor</th>
<th>Varies</th>
</tr>
</thead>
</table>
| UNDI command interface. Minor revision number.  
0x00 (Alpha): This version of UNDI does not operate as a runtime driver. The callback interface defined in the UNDI Start command is required.  
0x10 (Beta): This version of UNDI can operate as an OS runtime driver. The callback interface defined in the UNDI Start command is required. |

<table>
<thead>
<tr>
<th>Reserved</th>
<th>0x00</th>
</tr>
</thead>
<tbody>
<tr>
<td>This field is reserved and must be set to zero.</td>
<td></td>
</tr>
</tbody>
</table>
Table E.4 – continued from previous page

<table>
<thead>
<tr>
<th>Implementation</th>
<th>Varies</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Identifies type of UNDI (S/W or H/W, 32 bit or 64 bit) and what features have been implemented. The implementation bits are defined below. Undefined bits must be set to zero by UNDI implementers. Applications/drivers must not rely on the contents of undefined bits (they may change later revisions). Bit 0x00: Command completion interrupts supported (1) or not supported (0) Bit 0x01: Packet received interrupts supported (1) or not supported (0) Bit 0x02: Transmit complete interrupts supported (1) or not supported (0) Bit 0x03: Software interrupt supported (1) or not supported (0) Bit 0x04: Filtered multicast receives supported (1) or not supported (0) Bit 0x05: Broadcast receives supported (1) or not supported (0) Bit 0x06: Promiscuous receives supported (1) or not supported (0) Bit 0x07: Promiscuous multicast receives supported (1) or not supported (0) Bit 0x08: Station MAC address settable (1) or not settable (0) Bit 0x09: Statistics supported (1) or not supported (0) Bit 0x0A,0x0B: NvData not available (0), read only (1), sparse write supported (2), bulk write supported (3) Bit 0x0C: Multiple frames per command supported (1) or not supported (0) Bit 0x0D: Command queuing supported (1) or not supported (0) Bit 0x0E: Command linking supported (1) or not supported (0) Bit 0x0F: Packet fragmenting supported (1) or not supported (0) Bit 0x10: Device can address 64 bits (1) or only 32 bits (0) Bit 0x11E: S/W UNDI: Entry point is virtual address (1) or unsigned offset from start of !PXE structure (0). Bit 0x1F: Interface type: H/W UNDI (1) or S/W UNDI (0)</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>H/W UNDI Fields</th>
<th>Reserved</th>
<th>Varies</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>This field is optional and may be used for OEM &amp; vendor unique data. If this field is present its length must be a multiple of 16 bytes and must be included in the !PXE structure checksum. This field, if present, will always start on a 16-byte boundary. Note: The size/contents of the !PXE structure may change in future revisions of this specification. Do not rely on OEM &amp; vendor data starting at the same offset from the beginning of the !PXE structure. It is recommended that the OEM &amp; vendor data include a signature that drivers/applications can search for.</td>
<td></td>
</tr>
</tbody>
</table>
Table E.4 – continued from previous page

<table>
<thead>
<tr>
<th>Status</th>
<th>Varies</th>
</tr>
</thead>
<tbody>
<tr>
<td>UNDI operation, command and interrupt status flags. This is a read-only port. Undefined status bits must be set to zero. Reading this port does NOT clear the status. Bit 0x00: Command completion interrupt pending (1) or not pending (0) Bit 0x01: Packet received interrupt pending (1) or not pending (0) Bit 0x02: Transmit complete interrupt pending (1) or not pending (0) Bit 0x03: Software interrupt pending (1) or not pending (0) Bit 0x04: Command completion interrupts enabled (1) or disabled (0) Bit 0x05: Packet receive interrupts enabled (1) or disabled (0) Bit 0x06: Transmit complete interrupts enabled (1) or disabled (0) Bit 0x07: Software interrupts enabled (1) or disabled (0) Bit 0x08: Unicast receive enabled (1) or disabled (0) Bit 0x09: Filtered multicast receive enabled (1) or disabled (0) Bit 0x0A: Broadcast receive enabled (1) or disabled (0) Bit 0x0B: Promiscuous receive enabled (1) or disabled (0) Bit 0x0C: Promiscuous multicast receive enabled (1) or disabled (0) Bit 0x1D: Command failed (1) or command succeeded (0) Bits 0x1F:0x1E: UNDI state: Stopped (0), Started (1), Initialized (2), Busy (3)</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Command</th>
<th>Varies</th>
</tr>
</thead>
<tbody>
<tr>
<td>Use to execute commands, clear interrupt status and enable/disable receive levels. This is a read/write port. Read reflects the last write. Bit 0x00: Clear command completion interrupt (1) or NOP (0) Bit 0x01: Clear packet received interrupt (1) or NOP (0) Bit 0x02: Clear transmit complete interrupt (1) or NOP (0) Bit 0x03: Clear software interrupt (1) or disable (0) Bit 0x04: Command completion interrupt enable (1) or disable (0) Bit 0x05: Packet receive interrupt enable (1) or disable (0) Bit 0x06: Transmit complete interrupt enable (1) or disable (0) Bit 0x07: Software interrupt enable (1) or disable (0). Setting this bit to (1) also generates a software interrupt. Bit 0x08: Unicast receive enable (1) or disable (0) Bit 0x09: Filtered multicast receive enable (1) or disable (0) Bit 0x0A: Broadcast receive enable (1) or disable (0) Bit 0x0B: Promiscuous receive enable (1) or disable (0) Bit 0x0C: Promiscuous multicast receive enable (1) or disable (0) Bit 0x1F: Operation type: Clear interrupt and/or filter (0), Issue command (1)</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>CDBaddr</th>
<th>Varies</th>
</tr>
</thead>
<tbody>
<tr>
<td>Write the physical address of a CDB to this port. (Done with one 64-bit or two 32-bit writes, depending on processor architecture.) When done, use one 32-bit write to the command port to send this address into the command queue. Unused upper address bits must be set to zero.</td>
<td></td>
</tr>
</tbody>
</table>

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Table E.4 – continued from previous page

<table>
<thead>
<tr>
<th>S/W UNDI Fields</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>EntryPoint</strong></td>
<td>Varies</td>
</tr>
<tr>
<td></td>
<td>S/W UNDI API entry point address. This is either a virtual address or an offset from the start of the !PXE structure. Protocol drivers will push the 64-bit virtual address of a CDB on the stack and then call the UNDI API entry point. When control is returned to the protocol driver, the protocol driver must remove the address of the CDB from the stack.</td>
</tr>
<tr>
<td><strong>Reserved</strong></td>
<td>Zero</td>
</tr>
<tr>
<td></td>
<td>Reserved for future use.</td>
</tr>
<tr>
<td><strong>BusTypeCnt</strong></td>
<td>Varies</td>
</tr>
<tr>
<td></td>
<td>This field is the count of 4-byte BusType entries in the next field.</td>
</tr>
<tr>
<td><strong>BusType</strong></td>
<td>Varies</td>
</tr>
<tr>
<td></td>
<td>This field defines the type of bus S/W UNDI is written to support: “PCIR,” “PCCR,” “USBR” or “1394.” This field is formatted like the Signature field. If the S/W UNDI supports more than one BusType there will be more than one BusType identifier in this field.</td>
</tr>
</tbody>
</table>

E.2.1.1 Issuing UNDI Commands

How commands are written and status is checked varies a little depending on the type of UNDI (H/W or S/W) implementation being used. The command flowchart shown in the Figure, below, is a high-level diagram on how commands are written to both H/W and S/W UNDI.

E.2.2 UNDI Command Format

The format of the CDB is the same for all UNDI commands. The Figure, below, shows the structure of the CDB. Some of the commands do not use or always require the use of all of the fields in the CDB. When fields are not used they must be initialized to zero or the UNDI will return an error. The StatCode and StatFlags fields must always be initialized to zero or the UNDI will return an error. All reserved fields (and bit fields) must be initialized to zero or the UNDI will return an error. Basically, the rule is: Do it right, or don’t do it at all.

Descriptions of the CDB fields are shown in the table below.

Table E.5: UNDI CDB Field Definitions

<table>
<thead>
<tr>
<th>Identifier</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>OpCode</strong></td>
<td><strong>Operation Code</strong> (Function Number, Command Code, etc.)</td>
</tr>
<tr>
<td></td>
<td>This field is used to identify the command being sent to the UNDI. The meanings of some of the bits in the OpFlags and StatFlags fields, and the format of the CPB and DB structures depends on the value in the OpCode field. Commands sent with an OpCode value that is not defined in this specification will not be executed and will return a StatCode of PXE_STATCODE_INVALID_CDB.</td>
</tr>
<tr>
<td>OpFlags</td>
<td><strong>Operation Flags</strong></td>
</tr>
<tr>
<td>---------</td>
<td>---------------------</td>
</tr>
<tr>
<td></td>
<td>This bit field is used to enable/disable different features in a specific command operation. It is also used to change the format/contents of the CPB and DB structures. Commands sent with reserved bits set in the OpFlags field will not be executed and will return a StatCode of PXE_STATCODE_INVALID_CDB.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>CPBsize</th>
<th><strong>Command Parameter Block Size</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>This field should be set to a number that is equal to the number of bytes that will be read from CPB structure during command execution. Setting this field to a number that is too small will cause the command to not be executed and a StatCode of PXE_STATCODE_INVALID_CDB will be returned. The contents of the CPB structure will not be modified.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>DBsize</th>
<th><strong>Data Block Size</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>This field should be set to a number that is equal to the number of bytes that will be written into the DB structure during command execution. Setting this field to a number that is smaller than required will cause an error. It may be zero in some cases where the information is not needed.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>CPBaddr</th>
<th><strong>Command Parameter Block Address</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>For H/W UNDI, this field must be the physical address of the CPB structure. For S/W UNDI, this field must be the virtual address of the CPB structure. If the operation does not have/use a CPB, this field must be initialized to PXE_CPBADDR_NOT_USED. Setting up this field incorrectly will cause command execution to fail and a StatCode of PXE_STATCODE_INVALID_CDB will be returned.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>DBaddr</th>
<th><strong>Data Block Address</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>For H/W UNDI, this field must be the physical address of the DB structure. For S/W UNDI, this field must be the virtual address of the DB structure. If the operation does not have/use a CPB, this field must be initialized to PXE_DBADDR_NOT_USED. Setting up this field incorrectly will cause command execution to fail and a StatCode of PXE_STATCODE_INVALID_CDB will be returned.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>StatCode</th>
<th><strong>Status Code</strong></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>This field is used to report the type of command completion: success or failure (and the type of failure). This field must be initialized to zero before the command is issued. The contents of this field is not valid until the PXE_STATFLAGS_COMMAND_COMPLETE status flag is set. If this field is not initialized to PXE_STATCODE_INITIALIZE the UNDI command will not execute and a StatCode of PXE_STATCODE_INVALID_CDB will be returned.</td>
</tr>
</tbody>
</table>
### E.3 UNDI C Definitions

The definitions in this section are used to aid in the portability and readability of the example 32/64-bit S/W UNDI source code and the rest of this specification.

#### E.3.1 Portability Macros

These macros are used for storage and communication portability.

**E.3.1.1 PXE_INTEL_ORDER or PXE_NETWORK_ORDER**

This macro is used to control conditional compilation in the S/W UNDI source code. One of these definitions needs to be uncommented in a common PXE header file.

```c
// #define PXE_INTEL_ORDER 1 // little-endian
// #define PXE_NETWORK_ORDER 1 // big-endian
```
Fig. E.3: Issuing UNDI Commands
E.3.1.2 PXE_UINT64_SUPPORT or PXE_NO_UINT64_SUPPORT

This macro is used to control conditional compilation in the PXE source code. One of these definitions must to be uncommented in the common PXE header file.

//
#define PXE_UINT64_SUPPORT 1 // UINT64 supported
#define PXE_NO_UINT64_SUPPORT 1 // UINT64 not supported

E.3.1.3 PXE_BUSTYPE

Used to convert a 4-character ASCII identifier to a 32-bit unsigned integer.

#if PXE_INTEL_ORDER
#define PXE_BUSTYPE(a,b,c,d) \
    (((PXE_UINT32)(d) & 0xFF) << 24) | \ 
    (((PXE_UINT32)(c) & 0xFF) << 16) | \ 
    (((PXE_UINT32)(b) & 0xFF) << 8) | \ 
    ((PXE_UINT32)(a) & 0xFF))
#else
#define PXE_BUSTYPE(a,b,c,d) \
    (((PXE_UINT32)(a) & 0xFF) << 24) | \ 
    (((PXE_UINT32)(b) & 0xFF) << 16) | \ 
    (((PXE_UINT32)(c) & 0xFF) << 8) | \ 
    ((PXE_UINT32)(d) & 0xFF))
#endif

//******************************************************
// UNDI ROM ID and device ID signature
(continues on next page)
E.3.1.4 PXE_SWAP_UINT16

This macro swaps bytes in a 16-bit word.

```c
#ifndef PXE_INTEL_ORDER
#define PXE_SWAP_UINT16(n) \(((PXE_UINT16)(n) & 0x00FF) << 8) | ((PXE_UINT16)(n) & 0xFF00) >> 8))
#else
#define PXE_SWAP_UINT16(n) (n)
#endif
```

E.3.1.5 PXE_SWAP_UINT32

This macro swaps bytes in a 32-bit word.

```c
#ifndef PXE_INTEL_ORDER
#define PXE_SWAP_UINT32(n) \(((PXE_UINT32)(n) & 0x000000FF) << 24) | ((PXE_UINT32)(n) & 0x0000FF00) << 8) | ((PXE_UINT32)(n) & 0x00FF0000) >> 8) | ((PXE_UINT32)(n) & 0xFF000000) >> 24)
#else
#define PXE_SWAP_UINT32(n) (n)
#endif
```

E.3.1.6 PXE_SWAP_UINT64

This macro swaps bytes in a 64-bit word for compilers that support 64-bit words.

```c
#ifndef PXE_INTEL_ORDER
#define PXE_SWAP_UINT64(n) \(((PXE_UINT64)(n) & 0x00000000000000FF) << 56) | ((PXE_UINT64)(n) & 0x000000000000FF00) << 40) | ((PXE_UINT64)(n) & 0x0000000000FF0000) << 24) | ((PXE_UINT64)(n) & 0x00000000FF000000) << 8) | ((PXE_UINT64)(n) & 0x000000FF00000000) >> 8)
#else
#define PXE_SWAP_UINT64(n) (n)
#endif
```

(continues on next page)
This macro swaps bytes in a 64-bit word, in place, for compilers that do not support 64-bit words. This version of the 64-bit swap macro cannot be used in expressions.

```c
#if PXE_NO_UINT64_SUPPORT != 0
#if PXE_INTEL_ORDER
#define PXE_SWAP_UINT64(n) \
{ \
PXE_UINT32 tmp = (PXE_UINT64)(n)[1]; \
(PXE_UINT64)(n)[1] = PXE_SWAP_UINT32((PXE_UINT64)(n)[0]); \
(PXE_UINT64)(n)[0] = PXE_SWAP_UINT32(tmp); \
} 
#else
#define PXE_SWAP_UINT64(n) (n)
#endif // PXE_NO_UINT64_SUPPORT
#else
#define PXE_SWAP_UINT64(n) (n)
#endif // PXE_UINT64_SUPPORT
```

**E.3.2 Miscellaneous Macros**

**E.3.2.1 Miscellaneous**

```c
#define PXE_CPBSIZE_NOT_USED 0 // zero
#define PXE_DBSIZE_NOT_USED 0 // zero
#define PXE_CPBADDR_NOT_USED (PXE_UINT64)0 // zero
#define PXE_DBADDR_NOT_USED (PXE_UINT64)0 // zero
```

**E.3.3 Portability Types**

The examples given below are just that, examples. The actual typedef instructions used in a new implementation may vary depending on the compiler and processor architecture.

The storage sizes defined in this section are critical for PXE module inter-operation. All of the portability typedefs define little endian (Intel® format) storage. The least significant byte is stored in the lowest memory address and the most significant byte is stored in the highest memory address, as shown in See *Storage Types*.
E.3.3.1 PXE_CONST

The const type does not allocate storage. This type is a modifier that is used to help the compiler optimize parameters that do not change across function calls.

```
#define PXE_CONST const
```

E.3.3.2 PXE_VOLATILE

The volatile type does not allocate storage. This type is a modifier that is used to help the compiler deal with variables that can be changed by external procedures or hardware events.

```
#define PXE_VOLATILE volatile
```

E.3.3.3 PXE_VOID

The void type does not allocate storage. This type is used only to prototype functions that do not return any information and/or do not take any parameters.

```
typedef void PXE_VOID;
```

E.3.3.4 PXE_UINT8

Unsigned 8-bit integer.

```
typedef unsigned char PXE_UINT8;
```
E.3.3.5 PXE_UINT16

Unsigned 16-bit integer.

```c
typedef unsigned short PXE_UINT16;
```

E.3.3.6 PXE_UINT32

Unsigned 32-bit integer.

```c
typedef unsigned PXE_UINT32;
```

E.3.3.7 PXE_UINT64

Unsigned 64-bit integer.

```c
#if PXE_UINT64_SUPPORT != 0
typedef unsigned long PXE_UINT64;
#endif // PXE_UINT64_SUPPORT
```

If a 64-bit integer type is not available in the compiler being used, use this definition:

```c
#if PXE_NO_UINT64_SUPPORT != 0
typedef PXE_UINT32 PXE_UINT64[2];
#endif // PXE_NO_UINT64_SUPPORT
```

E.3.3.8 PXE_UINTN

Unsigned integer that is the default word size used by the compiler. This needs to be at least a 32-bit unsigned integer.

```c
typedef unsigned PXE_UINTN;
```

E.3.4 Simple Types

The PXE simple types are defined using one of the portability types from the previous section.

E.3.4.1 PXE_BOOL

Boolean (true/false) data type. For PXE zero is always false and nonzero is always true.

```c
typedef PXE_UINT8 PXE_BOOL;
#define PXE_FALSE 0 // zero
#define PXE_TRUE (!PXE_FALSE)
```
E.3.4.2 PXE_OPCODE

UNDI OpCode (command) descriptions are given in the next chapter. There are no BC OpCodes, BC protocol functions are discussed later in this document.

typedef PXE_UINT16 PXE_OPCODE;

// Return UNDI operational state.
#define PXE_OPCODE_GET_STATE 0x0000

// Change UNDI operational state from Stopped to Started.
#define PXE_OPCODE_START 0x0001

// Change UNDI operational state from Started to Stopped.
#define PXE_OPCODE_STOP 0x0002

// Get UNDI initialization information.
#define PXE_OPCODE_GET_INIT_INFO 0x0003

// Get NIC configuration information.
#define PXE_OPCODE_GET_CONFIG_INFO 0x0004

// Change UNDI operational state from Started to Initialized.
#define PXE_OPCODE_INITIALIZE 0x0005

// Reinitialize the NIC H/W.
#define PXE_OPCODE_RESET 0x0006

// Change the UNDI operational state from Initialized to Started.
#define PXE_OPCODE_SHUTDOWN 0x0007

// Read & change state of external interrupt enables.
#define PXE_OPCODE_INTERRUPT_ENABLES 0x0008

// Read & change state of packet receive filters.
#define PXE_OPCODE_RECEIVE_FILTERS 0x0009

// Read & change station MAC address.
#define PXE_OPCODE_STATION_ADDRESS 0x000A

// Read traffic statistics.
#define PXE_OPCODE_STATISTICS 0x000B

// Convert multicast IP address to multicast MAC address.
#define PXE_OPCODE_MCAST_IP_TO_MAC 0x000C

// Read or change nonvolatile storage on the NIC.
#define PXE_OPCODE_NVDATA 0x000D

// Get & clear interrupt status.
#define PXE_OPCODE_GET_STATUS 0x000E

// Fill media header in packet for transmit.

(continues on next page)
E.3.4.3 PXE_OPFLAGS

typedef PXE_UINT16 PXE_OPFLAGS;

#define PXE_OPFLAGS_NOT_USED 0x0000

//UNDI Get State
//**************************************************************************************
// No OpFlags
//**************************************************************************************

//UNDI Start
//**************************************************************************************
// No OpFlags
//**************************************************************************************

//UNDI Stop
//**************************************************************************************
// No OpFlags
//**************************************************************************************

//UNDI Get Init Info
//**************************************************************************************
// No Opflags
//**************************************************************************************

//UNDI Get Config Info
//**************************************************************************************
// No Opflags
//**************************************************************************************

//UNDI Initialize
//**************************************************************************************
#define PXE_OPFLAGS_INITIALIZE_CABLE_DETECT_MASK 0x0001
#define PXE_OPFLAGS_INITIALIZE_DETECT_CABLE 0x0000
#define PXE_OPFLAGS_INITIALIZE_DO_NOT_DETECT_CABLE 0x0001

//******************************************************************************
// UNDI Reset
//******************************************************************************

#define PXE_OPFLAGS_RESET_DISABLE_INTERRUPTS 0x0001
#define PXE_OPFLAGS_RESET_DISABLE_FILTERS 0x0002

//******************************************************************************
// UNDI Shutdown
//******************************************************************************

// No OpFlags

//******************************************************************************
// UNDI Interrupt Enables
//******************************************************************************

// Select whether to enable or disable external interrupt
// signals. Setting both enable and disable will return
// PXE_STATCODE_INVALID_OPFLAGS.

#define PXE_OPFLAGS_INTERRUPT_OPMASK 0xC000
#define PXE_OPFLAGS_INTERRUPT_ENABLE 0x8000
#define PXE_OPFLAGS_INTERRUPT_DISABLE 0x4000
#define PXE_OPFLAGS_INTERRUPT_READ 0x0000

// Enable receive interrupts. An external interrupt will be
// generated after a complete non-error packet has been received.

#define PXE_OPFLAGS_INTERRUPT_RECEIVE 0x0001

// Enable transmit interrupts. An external interrupt will be
// generated after a complete non-error packet has been
// transmitted.

#define PXE_OPFLAGS_INTERRUPT_TRANSMIT 0x0002

// Enable command interrupts. An external interrupt will be
// generated when command execution stops.

#define PXE_OPFLAGS_INTERRUPT_COMMAND 0x0004

// Generate software interrupt. Setting this bit generates an
// external interrupt, if it is supported by the hardware.

#define PXE_OPFLAGS_INTERRUPT_SOFTWARE 0x0008

(continues on next page)
UNDI C Definitions 1996

// UNDI Receive Filters

// Select whether to enable or disable receive filters. Setting both enable and disable will return PXE_STATCODE_INVALID_OPCODE.

#define PXE_OPFLAGS_RECEIVE_FILTER_OPMASK 0xC000
#define PXE_OPFLAGS_RECEIVE_FILTER_ENABLE 0x8000
#define PXE_OPFLAGS_RECEIVE_FILTER_DISABLE 0x4000
#define PXE_OPFLAGS_RECEIVE_FILTER_READ 0x0000

// To reset the contents of the multicast MAC address filter list, set this OpFlag:

#define PXE_OPFLAGS_RECEIVE_FILTERS_RESET_MCAST_LIST 0x2000

// Enable unicast packet receiving. Packets sent to the current station MAC address will be received.

#define PXE_OPFLAGS_RECEIVE_FILTER_UNICAST 0x0001

// Enable broadcast packet receiving. Packets sent to the broadcast MAC address will be received.

#define PXE_OPFLAGS_RECEIVE_FILTER_BROADCAST 0x0002

// Enable filtered multicast packet receiving. Packets sent to any of the multicast MAC addresses in the multicast MAC address filter list will be received. If the filter list is empty, no multicast

#define PXE_OPFLAGS_RECEIVE_FILTER_FILTERED_MULTICAST 0x0004

// Enable promiscuous packet receiving. All packets will be received.

#define PXE_OPFLAGS_RECEIVE_FILTER_PROMISCUOUS 0x0008

// Enable promiscuous multicast packet receiving. All multicast packets will be received.

#define PXE_OPFLAGS_RECEIVE_FILTER_ALL_MULTICAST 0x0010

// UNDI Station Address

#define PXE_OPFLAGS_STATION_ADDRESS_READ 0x0000
#define PXE_OPFLAGS_STATION_ADDRESS_WRITE 0x0000
#define PXE_OPFLAGS_STATION_ADDRESS_RESET 0x0001

// UNDI Statistics

#define PXE_OPFLAGS_STATISTICS_READ 0x0000
#define PXE_OPFLAGS_STATISTICS_RESET 0x0001

// UNDI MCast IP to MAC

// Identify the type of IP address in the CPB.

#define PXE_OPFLAGS_MCAST_IP_TO_MAC_OPMASK 0x0003
#define PXE_OPFLAGS_MCAST_IPV4_TO_MAC 0x0000
#define PXE_OPFLAGS_MCAST_IPV6_TO_MAC 0x0001

// UNDI NvData

// Select the type of nonvolatile data operation.

#define PXE_OPFLAGS_NVDATA_OPMASK 0x0001
#define PXE_OPFLAGS_NVDATA_READ 0x0000
#define PXE_OPFLAGS_NVDATA_WRITE 0x0001

// Return current interrupt status. This will also clear any interrupts that are currently set. This can be used in a polling routine. The interrupt flags are still set and cleared even when the interrupts are disabled.

#define PXE_OPFLAGS_GET_INTERRUPT_STATUS 0x0001

// Return list of transmitted buffers for recycling. Transmit buffers must not be changed or unallocated until they have recycled. After issuing a transmit command, wait for a transmit complete interrupt. When a transmit complete interrupt is received, read the transmitted buffers. Do not plan on getting one buffer per interrupt. Some NICs and UNDIS may transmit multiple buffers per interrupt.

#define PXE_OPFLAGS_GET_TRANSMITTED_BUFFERS 0x0002

// Return current media status.

(continues on next page)
#define PXE_OPFLAGS_GET_MEDIA_STATUS 0x0004

// UNDI Fill Header

#define PXE_OPFLAGS_FILL_HEADER_OPMASK 0x0001
#define PXE_OPFLAGS_FILL_HEADER_FRAGMENTED 0x0001
#define PXE_OPFLAGS_FILL_HEADER_WHOLE 0x0000

// UNDI Transmit

#define PXE_OPFLAGS_SWUNDI_TRANSMIT_OPMASK 0x0001
#define PXE_OPFLAGS_TRANSMIT_BLOCK 0x0001
#define PXE_OPFLAGS_TRANSMIT_DONT_BLOCK 0x0000

#define PXE_OPFLAGS_TRANSMIT_OPMASK 0x0002
#define PXE_OPFLAGS_TRANSMIT_FRAGMENTED 0x0002
#define PXE_OPFLAGS_TRANSMIT_WHOLE 0x0000

// UNDI Receive

// No OpFlags

E.3.4.4 PXE_STATFLAGS

typedef PXE_UINT16 PXE_STATFLAGS;

#define PXE_STATFLAGS_INITIALIZE 0x0000

#define PXE_STATFLAGS_STATUS_MASK 0xC000
#define PXE_STATFLAGS_COMMAND_COMPLETE 0xC000
#define PXE_STATFLAGS_COMMAND_FAILED 0x8000
#define PXE_STATFLAGS_COMMAND_QUEUED 0x4000

// The COMMAND_COMPLETE and COMMAND_FAILED status flags must be
// implemented by all UNDIs. COMMAND_QUEUED is only needed by
// UNDIs that support command queuing.

#define PXE_STATFLAGS_STATUS_MASK 0xC000
#define PXE_STATFLAGS_COMMAND_COMPLETE 0xC000
#define PXE_STATFLAGS_COMMAND_FAILED 0x8000
#define PXE_STATFLAGS_COMMAND_QUEUED 0x4000
// ****************************************************
// UNDI Get State
// ****************************************************

#define PXE_STATFLAGS_GET_STATE_MASK 0x0003
#define PXE_STATFLAGS_GET_STATE_INITIALIZED 0x0002
#define PXE_STATFLAGS_GET_STATE_STARTED 0x0001
#define PXE_STATFLAGS_GET_STATE_STOPPED 0x0000

// ****************************************************
// UNDI Start
// ****************************************************

// No additional StatFlags

// ****************************************************
// UNDI Get Init Info
// ****************************************************

#define PXE_STATFLAGS_CABLE_DETECT_MASK 0x0001
#define PXE_STATFLAGS_CABLE_DETECT_NOT_SUPPORTED 0x0000
#define PXE_STATFLAGS_CABLE_DETECT_SUPPORTED 0x0001
#define PXE_STATFLAGS_GET_STATUS_NO_MEDIA_MASK 0x0002
#define PXE_STATFLAGS_GET_STATUS_NO_MEDIA_NOT_SUPPORTED 0x0000
#define PXE_STATFLAGS_GET_STATUS_NO_MEDIA_SUPPORTED 0x0002

// ****************************************************
// UNDI Initialize
// ****************************************************

#define PXE_STATFLAGS_INITIALIZED_NO_MEDIA 0x0001

// ****************************************************
// UNDI Reset
// ****************************************************

#define PXE_STATFLAGS_RESET_NO_MEDIA 0x0001

// ****************************************************
// UNDI Shutdown
// ****************************************************

// No additional StatFlags

// ****************************************************
// UNDI Interrupt Enables
// ****************************************************

// If set, receive interrupts are enabled.
#define PXE_STATFLAGS_INTERRUPT_RECEIVE 0x0001

(continues on next page)
// If set, transmit interrupts are enabled.
#define PXE_STATFLAGS_INTERRUPT_TRANSMIT 0x0002

// If set, command interrupts are enabled.
#define PXE_STATFLAGS_INTERRUPT_COMMAND 0x0004

// UNDI Receive Filters

// If set, unicast packets will be received.
#define PXE_STATFLAGS_RECEIVE_FILTER_UNICAST 0x0001

// If set, broadcast packets will be received.
#define PXE_STATFLAGS_RECEIVE_FILTER_BROADCAST 0x0002

// If set, multicast packets that match up with the multicast address filter list will be received.
#define PXE_STATFLAGS_RECEIVE_FILTER_FILTERED_MULTICAST 0x0004

// If set, all packets will be received.
#define PXE_STATFLAGS_RECEIVE_FILTER_PROMISCUOUS 0x0008

// If set, all multicast packets will be received.
#define PXE_STATFLAGS_RECEIVE_FILTER_ALL_MULTICAST 0x0010

// UNDI Station Address

// No additional StatFlags

// UNDI Statistics

// No additional StatFlags

// UNDI MCast IP to MAC

// No additional StatFlags

// UNDI NvData

// No additional StatFlags

// UNDI Get Status
// Use to determine if an interrupt has occurred.
#define PXE_STATFLAGS_GET_STATUS_INTERRUPT_MASK 0x000F
#define PXE_STATFLAGS_GET_STATUS_NO_INTERRUPTS 0x0000

// If set, at least one receive interrupt occurred.
#define PXE_STATFLAGS_GET_STATUS_RECEIVE 0x0001

// If set, at least one transmit interrupt occurred.
#define PXE_STATFLAGS_GET_STATUS_TRANSMIT 0x0002

// If set, at least one command interrupt occurred.
#define PXE_STATFLAGS_GET_STATUS_COMMAND 0x0004

// If set, at least one software interrupt occurred.
#define PXE_STATFLAGS_GET_STATUS_SOFTWARE 0x0008

// This flag is set if the transmitted buffer queue is empty.
// This flag will be set if all transmitted buffer addresses
// get written into the DB.
#define PXE_STATFLAGS_GET_STATUS_TXBUF_QUEUE_EMPTY 0x0010

// This flag is set if no transmitted buffer addresses were
// written into the DB. (This could be because DBsize was
// too small.)
#define PXE_STATFLAGS_GET_STATUS_NO_TXBUFS_WRITTEN 0x0020

// This flag is set if there is no media detected
#define PXE_STATFLAGS_GET_STATUS_NO_MEDIA 0x0040

// No additional StatFlags

// UNDI Fill Header
// No additional StatFlags

// UNDI Transmit
// No additional StatFlags.

// UNDI Receive
// No additional StatFlags.

// No additional StatFlags.
E.3.4.5 PXE_STATCODE

typedef PXE_UINT16 PXE_STATCODE;

#define PXE_STATCODE_INITIALIZE 0x0000

//******************************************************************************
// Common StatCodes returned by all UNDI commands, UNDI protocol
// functions and BC protocol functions.
//******************************************************************************

#define PXE_STATCODE_SUCCESS 0x0000
#define PXE_STATCODE_INVALID_CDB 0x0001
#define PXE_STATCODE_INVALID_CPB 0x0002
#define PXE_STATCODE_BUSY 0x0003
#define PXE_STATCODE_QUEUE_FULL 0x0004
#define PXE_STATCODE_ALREADY_STARTED 0x0005
#define PXE_STATCODE_NOT_STARTED 0x0006
#define PXE_STATCODE_NOT_SHUTDOWN 0x0007
#define PXE_STATCODE_ALREADY_INITIALIZED 0x0008
#define PXE_STATCODE_NOT_INITIALIZED 0x0009
#define PXE_STATCODE_DEVICE_FAILURE 0x000A
#define PXE_STATCODE_NVDATA_FAILURE 0x000B
#define PXE_STATCODE_UNSUPPORTED 0x000C
#define PXE_STATCODE_BUFFER_FULL 0x000D
#define PXE_STATCODE_INVALID_PARAMETER 0x000E
#define PXE_STATCODE_INVALID_UNDI 0x000F
#define PXE_STATCODE_IPV4_NOT_SUPPORTED 0x0010
#define PXE_STATCODE_IPV6_NOT_SUPPORTED 0x0011
#define PXE_STATCODE_NOT_ENOUGH_MEMORY 0x0012
#define PXE_STATCODE_NO_DATA 0x0013

E.3.4.6 PXE_IFNUM

typedef PXE_UINT16 PXE_IFNUM;

// This interface number must be passed to the S/W UNDI Start
// command.

#define PXE_IFNUM_START 0x0000

// This interface number is returned by the S/W UNDI Get State
// and Start commands if information in the CDB, CPB or DB is
// invalid.

#define PXE_IFNUM_INVALID 0x0000
E.3.4.7 PXE_CONTROL

typedef PXE_UINT16 PXE_CONTROL;

// Setting this flag directs the UNDI to queue this command for
// later execution if the UNDI is busy and it supports command
// queuing. If queuing is not supported, a
// PXE_STATCODE_INVALID_CONTROL error is returned. If the queue
// is full, a PXE_STATCODE_CDB_QUEUE_FULL error is returned.

#define PXE_CONTROL_QUEUE_IF_BUSY 0x0002

// These two bit values are used to determine if there are more
// UNDI CDB structures following this one. If the link bit is
// set, there must be a CDB structure following this one.
// Execution will start on the next CDB structure as soon as this
// one completes successfully. If an error is generated by this
// command, execution will stop.

#define PXE_CONTROL_LINK 0x0001
#define PXE_CONTROL_LAST_CDB_IN_LIST 0x0000

E.3.4.8 PXE_FRAME_TYPE

typedef PXE_UINT8 PXE_FRAME_TYPE;

#define PXE_FRAME_TYPE_NONE 0x00
#define PXE_FRAME_TYPE_UNICAST 0x01
#define PXE_FRAME_TYPE_BROADCAST 0x02
#define PXE_FRAME_TYPE_FILTERED_MULTICAST 0x03
#define PXE_FRAME_TYPE_PROMISCUOUS 0x04
#define PXE_FRAME_TYPE_PROMISCUOUS_MULTICAST 0x05

E.3.4.9 PXE_IPV4

This storage type is always big endian, not little endian.

typedef PXE_UINT32 PXE_IPV4;

E.3.4.10 PXE_IPV6

This storage type is always big endian, not little endian.

typedef struct s_PXE_IPV6 {
PXE_UINT32 "num" [4];
} PXE_IPV6;
**E.3.4.11 PXE_MAC_ADDR**

This storage type is always big endian, not little endian.

```c
typedef struct {
    PXE_UINT8 *num* [32];
} PXE_MAC_ADDR;
```

**E.3.4.12 PXE_IFTYPE**

The interface type is returned by the Get Initialization Information command and is used by the BC DHCP protocol function. This field is also used for the low order 8-bits of the H/W type field in ARP packets. The high order 8-bits of the H/W type field in ARP packets will always be set to 0x00 by the BC.

```c
typedef PXE_UINT8 PXE_IFTYPE;

// This information is from the ARP section of RFC 3232.

// 1 Ethernet (10Mb)
// 2 Experimental Ethernet (3Mb)
// 3 Amateur Radio AX.25
// 4 Proteon ProNET Token Ring
// 5 Chaos
// 6 IEEE 802 Networks
// 7 ARCNET
// 8 Hyperchannel
// 9 Lanstar
// 10 Autonet Short Address
// 11 LocalTalk
// 12 LocalNet (IBM PCNet or SYTEK LocalNET)
// 13 Ultra link
// 14 SMDS
// 15 Frame Relay
// 16 Asynchronous Transmission Mode (ATM)
// 17 HDLC
// 18 Fibre Channel
// 19 Asynchronous Transmission Mode (ATM)
// 20 Serial Line
// 21 Asynchronous Transmission Mode (ATM)

#define PXE_IFTYPE_ETHERNET 0x01
#define PXE_IFTYPE_TOKENRING 0x04
#define PXE_IFTYPE_FIBRE_CHANNEL 0x12
```
E.3.4.13 PXE_MEDIA_PROTOCOL

Protocol type. This will be copied into the media header without doing byte swapping. Protocol type numbers can be obtained from the assigned numbers RFC 3232.

```c
typedef UINT16 PXE_MEDIA_PROTOCOL;
```

E.3.5 Compound Types

All PXE structures must be byte packed.

E.3.5.1 PXE_HW_UNDI

This section defines the C structures and #defines for the !PXE H/W UNDI interface.

```c
#pragma pack(1)
typedef struct s_pxe_hw_undi {
    PXE_UINT32 Signature; // PXE_ROMID_SIGNATURE
    PXE_UINT8  Len; // sizeof(PXE_HW_UNDI)
    PXE_UINT8  Fudge; // makes 8-bit cksum equal zero
    PXE_UINT8  Rev;  // PXE_ROMID_REV
    PXE_UINT8  IFcnt; // physical connector count
                   lower byte
    PXE_UINT8  MajorVer; // PXE_ROMID_MAJORVER
    PXE_UINT8  MinorVer; // PXE_ROMID_MINORVER
    PXE_UINT8  IFcntExt; // physical connector count
                   upper byte
    PXE_UINT8  reserved; // zero, not used
    PXE_UINT32 Implementation; // implementation flags
} PXE_HW_UNDI;
#pragma pack()
```

// Status port bit definitions

// UNDI operation state

#define PXE_HWSTAT_STATE_MASK 0xC0000000
#define PXE_HWSTAT_BUSY 0xC0000000
#define PXE_HWSTAT_INITIALIZED 0x80000000
#define PXE_HWSTAT_STARTED 0x40000000
#define PXE_HWSTAT_STOPPED 0x00000000

// If set, last command failed
#define PXE_HWSTAT_COMMAND_FAILED 0x20000000

// If set, identifies enabled receive
filters <http://www.ietf.org/rfc/rfc1700.txt>
#define PXE_HWSTAT_PROMISCUOUS_MULTICAST_RX_ENABLED 0x00001000
#define PXE_HWSTAT_PROMISCUOUS_RX_ENABLED 0x00000800
```

(continues on next page)
#define PXE_HWSTAT_BROADCAST_RX_ENABLED 0x00000400
#define PXE_HWSTAT_MULTICAST_RX_ENABLED 0x00000200
#define PXE_HWSTAT_UNICAST_RX_ENABLED 0x00000100

// If set, identifies enabled external interrupts

#define PXE_HWSTAT_SOFTWARE_INT_ENABLED 0x00000080
#define PXE_HWSTAT_TX_COMPLETE_INT_ENABLED 0x00000040
#define PXE_HWSTAT_PACKET_RX_INT_ENABLED 0x00000020
#define PXE_HWSTAT_CMD_COMPLETE_INT_ENABLED 0x00000010

// If set, identifies pending interrupts

#define PXE_HWSTAT_SOFTWARE_INT_PENDING 0x00000008
#define PXE_HWSTAT_TX_COMPLETE_INT_PENDING 0x00000004
#define PXE_HWSTAT_PACKET_RX_INT_PENDING 0x00000002
#define PXE_HWSTAT_CMD_COMPLETE_INT_PENDING 0x00000001

// Command port definitions

// If set, CDB identified in CDBaddr port is given to UNDI
// If not set, other bits in this word will be processed.

#define PXE_HWCMD_ISSUE_COMMAND 0x80000000
#define PXE_HWCMD_INTS_AND_FILTS 0x00000000

// Use these to enable/disable receive filters.

#define PXE_HWCMD_PROMISCUOUS_MULTICAST_RX_ENABLE 0x00001000
#define PXE_HWCMD_PROMISCUOUS_RX_ENABLE 0x00000800
#define PXE_HWCMD_BROADCAST_RX_ENABLE 0x00000400
#define PXE_HWCMD_MULTICAST_RX_ENABLE 0x00000200
#define PXE_HWCMD_UNICAST_RX_ENABLE 0x00000100

// Use these to enable/disable external interrupts

#define PXE_HWCMD_SOFTWARE_INT_ENABLE 0x00000080
#define PXE_HWCMD_TX_COMPLETE_INT_ENABLE 0x00000040
#define PXE_HWCMD_PACKET_RX_INT_ENABLE 0x00000020
#define PXE_HWCMD_CMD_COMPLETE_INT_ENABLE 0x00000010

// Use these to clear pending external interrupts

#define PXE_HWCMD_CLEAR_SOFTWARE_INT 0x00000008
#define PXE_HWCMD_CLEAR_TX_COMPLETE_INT 0x00000004
#define PXE_HWCMD_CLEAR_PACKET_RX_INT 0x00000002
#define PXE_HWCMD_CLEAR_CMD_COMPLETE_INT 0x00000001
E.3.5.2 PXE_SW_UNDI

This section defines the C structures and #defines for the !PXE S/W UNDI interface.

```c
#pragma pack(1)
typedef struct s_pxe_sw_undi {
    PXE_UINT32 Signature; // PXE_ROMID_SIGNATURE
    PXE_UINT8 Len; // sizeof(PXE_SW_UNDI)
    PXE_UINT8 Fudge; // makes 8-bit cksum zero
    PXE_UINT8 Rev; // PXE_ROMID_REV
    PXE_UINT8 Fcnt; // physical connector count
    lower byte
    PXE_UINT8 MajorVer; // PXE_ROMID_MAJORVER
    PXE_UINT8 MinorVer; // PXE_ROMID_MINORVER
    PXE_UINT8 IFcntExt; // physical connector count
    upper byte
    PXE_UINT8 reserved1; // zero, not used
    PXE_UINT32 Implementation; // Implementation flags
    PXE_UINT64 EntryPoint; // API entry point
    PXE_UINT8 reserved2[3]; // zero, not used
    PXE_UINT8 BusCnt; // number of bustypes supported
    PXE_UINT32 BusType[1]; // list of supported bustypes
} PXE_SW_UNDI;
#pragma pack()
```

E.3.5.3 PXE_UNDI

PXE_UNDI combines both the H/W and S/W UNDI types into one typedef and has #defines for common fields in both H/W and S/W UNDI types.

```c
#pragma pack(1)
typedef union u_pxe_undi {
    PXE_HW_UNDI hw;
    PXE_SW_UNDI sw;
} PXE_UNDI;
#pragma pack()

// Signature of !PXE structure
#define PXE_ROMID_SIGNATURE PXE_BUSTYPE ('!', 'P', 'X', 'E')

// !PXE structure format revision *)*
// See "Links to UEFI-Related Documents" (http://uefi.org/uefi)
// under the heading "UDP over IPv6".
#define PXE_ROMID_REV 0x02

// UNDI command interface revision. These are the values that
// get sent in option 94 (Client Network Interface Identifier) in
// the DHCP Discover and PXE Boot Server Request packets.
// See "Links to UEFI-Related Documents" (http://uefi.org/uefi)
// under the heading "IETF Organization".
```

(continues on next page)
#define PXE_ROMID_MAJORVER 0x03
#define PXE_ROMID_MINORVER 0x01

// Implementation flags
#define PXE_ROMID_IMP_HW_UNDI 0x80000000
#define PXE_ROMID_IMP_SW_VIRT_ADDR 0x40000000
#define PXE_ROMID_IMP_64BIT_DEVICE 0x00010000
#define PXE_ROMID_IMP_FRAG_SUPPORTED 0x00008000
#define PXE_ROMID_IMP_CMD_LINK_SUPPORTED 0x00004000
#define PXE_ROMID_IMP_CMD_QUEUE_SUPPORTED 0x00002000
#define PXE_ROMID_IMP_64BIT_DEVICE 0x00010000
#define PXE_ROMID_IMP_MULTI_FRAME_SUPPORTED 0x00001000
#define PXE_ROMID_IMP_NVDATA_SUPPORT_MASK 0x00000C00
#define PXE_ROMID_IMP_NVDATA_BULK_WRITABLE 0x00000C00
#define PXE_ROMID_IMP_NVDATA_SPARSE_WRITABLE 0x00000800
#define PXE_ROMID_IMP_NVDATA_READ_ONLY 0x00000400
#define PXE_ROMID_IMP_NVDATA_NOT_AVAILABLE 0x00000000
#define PXE_ROMID_IMP_STATISTICS_SUPPORTED 0x00000200
#define PXE_ROMID_IMP_STATION_ADDR_SETTABLE 0x00000100
#define PXE_ROMID_IMP_PROMISCUOUS_MULTICAST_RX_SUPPORTED 0x00000080
#define PXE_ROMID_IMP_PROMISCUOUS_RX_SUPPORTED 0x00000040
#define PXE_ROMID_IMP_BROADCAST_RX_SUPPORTED 0x00000020
#define PXE_ROMID_IMP_FILTERED_MULTICAST_RX_SUPPORTED 0x00000010
#define PXE_ROMID_IMP_SOFTWARE_INT_SUPPORTED 0x00000008
#define PXE_ROMID_IMP_TX_COMPLETE_INT_SUPPORTED 0x00000004
#define PXE_ROMID_IMP_PACKET_RX_INT_SUPPORTED 0x00000002
#define PXE_ROMID_IMP_CMD_COMPLETE_INT_SUPPORTED 0x00000001

E.3.5.4 PXE_CDB

PXE UNDI command descriptor block.

```c
#pragma pack(1)
typedef struct s_pxe_cdb {
    PXE_OPCODE OpCode;
    PXE_OPFLAGS OpFlags;
    PXE_UINT16 CPBsize;
    PXE_UINT16 DBsize;
    PXE_UINT64 CPBaddr;
    PXE_UINT64 DBaddr;
    PXE_STATCODE StatCode;
    PXE_STATFLAGS StatFlags;
    PXE_UINT16 IFnum;
    PXE_CONTROL Control;
} PXE_CDB;
#pragma pack()
```

If the UNDI driver enables hardware VLAN support, UNDI driver could use `IFnum` to identify the real NICs and VLAN created virtual NICs.
E.3.5.5 PXE_IP_ADDR

This storage type is always big endian, not little endian.

```c
#pragma pack(1)
typedef union u_pxe_ip_addr {
    PXE_IPV6 IPv6;
    PXE_IPV4 IPv4;
} PXE_IP_ADDR;
#pragma pack()
```

E.3.5.6 PXE_DEVICE

This typedef is used to identify the network device that is being used by the UNDI. This information is returned by the Get Config Info command.

```c
#pragma pack(1)
typedef union pxe_device {
    // PCI and PC Card NICs are both identified using bus, device
    // and function numbers. For PC Card, this may require PC
    // Card services to be loaded in the BIOS or preboot
    // environment.
    struct {
        // See S/W UNDI ROMID structure definition for PCI and
        // PCC BusType definitions.
        PXE_UINT32 BusType;
        // Bus, device & function numbers that locate this device.
        PXE_UINT16 Bus;
        PXE_UINT8 Device;
        PXE_UINT8 Function;
    } PCI, PCC;
} PXE_DEVICE;
#pragma pack()
```

E.4 UNDI Commands

All 32/64-bit UNDI commands use the same basic command format, the CDB (Command Descriptor Block). CDB fields that are not used by a particular command must be initialized to zero by the application/driver that is issuing the command. (See “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “DMTF BIOS specifications”.)

All UNDI implementations must set the command completion status (PXE_STATFLAGS_COMMAND_COMPLETE) after command execution completes. Applications and drivers must not alter or rely on the contents of any of the CDB, CPB or DB fields until the command completion status is set.

All commands return status codes for invalid CDB contents and, if used, invalid CPB contents. Commands with invalid parameters will not execute. Fix the error and submit the command again.

See the Figure, below, UNDI States, Transitions & Valid Commands describes the different UNDI states (Stopped, Started and Initialized), shows the transitions between the states and which UNDI commands are valid in each state.
Fig. E.6: UNDI States, Transitions & Valid Commands
**Note:** All memory addresses including the CDB address, CPB address, and the DB address submitted to the S/W UNDI by the protocol drivers must be processor-based addresses. All memory addresses submitted to the H/W UNDI must be device based addresses.

**Note:** Additional requirements for S/W UNDI implementations: Processor register contents must be unchanged by S/W UNDI command execution (The application/driver does not have to save processor registers when calling S/W UNDI). Processor arithmetic flags are undefined (application/driver must save processor arithmetic flags if needed). Application/driver must remove CDB address from stack after control returns from S/W UNDI.

**Note:** Additional requirements for 32-bit network devices: All addresses given to the S/W UNDI must be 32-bit addresses. Any address that exceeds 32 bits (4 GiB) will result in a return of one of the following status codes: PXE_STATCODE_INVALID_PARAMETER, PXE_STATCODE_INVALID_CDB or PXE_STATCODE_INVALID_CPB.

When executing linked commands, command execution will stop at the end of the CDB list (when the PXE_CONTROL_LINK bit is not set) or when a command returns an error status code.

**Note:** Buffers requested via the MemoryRequired field in s_pxe_db_get_init_info (See DB) will be allocated via PCI_IO.AllocateBuffer(). However, the buffers passed to various UNDI commands are not guaranteed to be allocated via AllocateBuffer().

**Note:** Calls to Map_Mem() of type TO_AND_FROMDEVICE must only be used for common DMA buffers. Such buffers must be requested via the MemoryRequired field in s_pxe_db_get_init_info and provided through the Initialize command.

### E.4.1 Command Linking and Queuing

When linking commands, the CDBs must be stored consecutively in system memory without any gaps in between. Do not set the Link bit in the last CDB in the list. As shown in the Figure, below, the Link bit must be set in all other CDBs in the list.

When the H/W UNDI is executing commands, the State bits in the Status field in the !PXE structure will be set to Busy (3).

When H/W or S/W UNDI is executing commands and a new command is issued, a StatCode of PXE_STATCODE_BUSY and a StatFlag of PXE_STATFLAG_COMMAND_FAILURE is set in the CDB. For linked commands, only the first CDB will be set to Busy, all other CDBs will be unchanged. When a linked command fails, execution on the list stops. Commands after the failing command will not be run.

As shown in the Figure, below, when queuing commands, only the first CDB needs to have the Queue Control flag set. If queuing is supported and the UNDI is busy and there is room in the command queue, the command (or list of commands) will be queued.

When a command is queued a StatFlag of PXE_STATFLAG_COMMAND_QUEUED is set (if linked commands are queued only the StatFlag of the first CDB gets set). This signals that the command was added to the queue. Commands in the queue will be run on a first-in, first-out, basis. When a command fails, the next command in the queue is run. When a linked command in the queue fails, execution on the list stops. The next command, or list of commands, that was added to the command queue will be run.

### E.4. UNDI Commands 2011
Fig. E.7: Linked CDBs

Fig. E.8: Queued CDBs
E.4.2 Get State

This command is used to determine the operational state of the UNDI. An UNDI has three possible operational states:

- **Stopped.** A stopped UNDI is free for the taking. When all interface numbers (IFnum) for a particular S/W UNDI are stopped, that S/W UNDI image can be relocated or removed. A stopped UNDI will accept Get State and Start commands.

- **Started.** A started UNDI is in use. A started UNDI will accept Get State, Stop, Get Init Info, and Initialize commands.

- **Initialized.** An initialized UNDI is in used. An initialized UNDI will accept all commands except: Start, Stop, and Initialize.

Drivers and applications must not start using UNDIs that have been placed into the Started or Initialized states by another driver or application.

3.0 and 3.1 S/W UNDI: No callbacks are performed by this UNDI command.

### E.4.2.1 Issuing the Command

To issue a Get State command, create a CDB and fill it in as shown in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Get State command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_GET_STATE</td>
</tr>
<tr>
<td>OpFlags</td>
<td>PXE_OPFLAGS_NOT_USED</td>
</tr>
<tr>
<td>CPBsize</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBsize</td>
<td>PXE_DBSIZE_NOT_USED</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>PXE_CPBADDR_NOT_USED</td>
</tr>
<tr>
<td>DBaddr</td>
<td>PXE_DBADDR_NOT_USED</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to ( !\text{PXE.IFcnt} \mid !\text{PXE.IFcntExt} \ll 8 )).</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed</td>
</tr>
</tbody>
</table>

### E.4.2.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the `CDB.StatFlags` field. Until these bits change to report `PXE_STATFLAGS_COMMAND_COMPLETE` or `PXE_STATFLAGS_COMMAND_FAILED`, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. StatFlags contain operational state.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued. All other fields are unchanged.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has not been executed or queued.</td>
</tr>
</tbody>
</table>
E.4.2.3 Checking Command Execution Results

After command execution completes, either successfully or not, the \textit{CDB.StatCode} field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. StatFlags contain operational state.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
</tbody>
</table>

If the command completes successfully, use \textit{PXE_STATFLAGS_GET_STATE_MASK} to check the state of the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>STOPPED</td>
<td>The UNDI is stopped.</td>
</tr>
<tr>
<td>STARTED</td>
<td>The UNDI is started, but not initialized.</td>
</tr>
<tr>
<td>INITIALIZED</td>
<td>The UNDI is initialized.</td>
</tr>
</tbody>
</table>

E.4.3 Start

This command is used to change the UNDI operational state from stopped to started. No other operational checks are made by this command. Protocol driver makes this call for each network interface supported by the UNDI with a set of call back routines and a unique identifier to identify the particular interface. UNDI does not interpret the unique identifier in any way except that it is a 64-bit value and it will pass it back to the protocol driver as a parameter to all the call back routines for any particular interface. If this is a S/W UNDI, the callback functions Delay(), Virt2Phys(), Map_Mem(), UnMap_Mem(), and Sync_Mem() functions will not be called by this command.

E.4.3.1 Issuing the Command

To issue a Start command for H/W UNDI, create a CDB and fill it in as shows in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a H/W UNDI Start command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_START</td>
</tr>
<tr>
<td>OpFlags</td>
<td>PXE_OPFLAGS_NOT_USED</td>
</tr>
<tr>
<td>CPBsize</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBsize</td>
<td>PXE_DBSIZE_NOT_USED</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>PXE_CPBADDR_NOT_USED</td>
</tr>
<tr>
<td>DBaddr</td>
<td>PXE_DBADDR_NOT_USED</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to ( !PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed</td>
</tr>
</tbody>
</table>

To issue a Start command for S/W UNDI, create a CDB and fill it in as shows in the table below:
### E.4.3.2 Preparing the CPB

For the 3.1 S/W UNDI Start command, the CPB structure shown below must be filled in and the CDB must be set to `sizeof(struct s_pxe_cpb_start_31)`.

```c
#pragma pack(1)
typedef struct s_pxe_cpb_start_31 {
    UINT64 Delay;
    // Address of the Delay() callback service.
    // This field cannot be set to zero.
    //
    // VOID
    // Delay(
    // IN UINT64 UniqueId,
    // IN UINT64 Microseconds);
    //
    // UNDI will never request a delay smaller than 10 microseconds
    // and will always request delays in increments of 10
    // microseconds. The Delay() callback routine must delay
    // between n and n + 10 microseconds before returning control
    // to the UNDI.
    //
    UINT64 Block;
    //
    // Address of the Block() callback service.
    // This field cannot be set to zero.
    //
    // VOID
    // Block(
    // IN UINT64 UniqueId,
    // IN UINT32 Enable);
    //
    // UNDI may need to block multithreaded/multiprocessor access
    // to critical code sections when programming or accessing the
    // network device. When UNDI needs a block, it will call the
    // Block() callback service with Enable set to a non-zero value.
    // When UNDI no longer needs the block, it will call Block()
} s_pxe_cpb_start_31;
```

(continues on next page)
// with Enable set to zero.

UINT64 Virt2Phys;
//
// Convert a virtual address to a physical address.
// This field can be set to zero if virtual and physical
// addresses are identical.
//
// VOID
// Virt2Phys(
// IN UINT64 UniqueId,
// IN UINT64 Virtual,
// OUT UINT64 PhysicalPtr);
//
// UNDI will pass in a virtual address and a pointer to storage
// for a physical address. The Virt2Phys() service converts
// the virtual address to a physical address and stores the
// resulting physical address in the supplied buffer. If no
// conversion is needed, the virtual address must be copied
// into the supplied physical address buffer.
//

UINT64 Mem_IO;
//
// Read/Write network device memory and/or I/O register space.
// This field cannot be set to zero.
//
// VOID
// Mem_IO(
// IN UINT64 UniqueId,
// IN UINT8 AccessType,
// IN UINT8 Length,
// IN UINT64 Port,
// IN OUT UINT64 BufferPtr);
//
// UNDI uses the Mem_IO() service to access the network device
// memory and/or I/O registers. The AccessType is one of the
// PXE_IO_xxx or PXE_MEM_xxx constants defined at the end of
// this section. The Length is 1, 2, 4 or 8. The Port number
// is relative to the base memory or I/O address space for this
// device. BufferPtr points to the data to be written to the
// Port or will contain the data that is read from the Port.
//

UINT64 Map_Mem;
//
// Map virtual memory address for DMA.
// This field can be set to zero if there is no mapping
// service.
//
// VOID

(continues on next page)
// Map_Mem(
// IN UINT64 UniqueId,
// IN UINT64 Virtual,
// IN UINT32 Size,
// IN UINT32 Direction,
// OUT UINT64 PhysicalPtr);
//
// When UNDI needs to perform a DMA transfer it will request a
// virtual-to-physical mapping using the Map_Mem() service. The
// Virtual parameter contains the virtual address to be mapped.
// The minimum Size of the virtual memory buffer to be mapped.
// Direction is one of the TO_DEVICE, FROM_DEVICE or
// TO_AND_FROM_DEVICE constants defined at the end of this
// section. PhysicalPtr contains the mapped physical address or
// a copy of the Virtual address if no mapping is required.
//

UINT64 UnMap_Mem;
//
// Un-map previously mapped virtual memory address.
// This field can be set to zero only if the Map_Mem() service
// is also set to zero.
//
// VOID
// UnMap_Mem(
// IN UINT64 UniqueId,
// IN UINT64 Virtual,
// IN UINT32 Size,
// IN UINT32 Direction,
// IN UINT64 PhysicalPtr);
//
// When UNDI is done with the mapped memory, it will use the
// UnMap_Mem() service to release the mapped memory.
//

UINT64 Sync_Mem;
//
// Synchronise mapped memory.
// This field can be set to zero only if the Map_Mem() service
// is also set to zero.
//
// VOID
// Sync_Mem(
// IN UINT64 UniqueId,
// IN UINT64 Virtual,
// IN UINT32 Size,
// IN UINT32 Direction,
// IN UINT64 PhysicalPtr);
//
// When the virtual and physical buffers need to be
// synchronized, UNDI will call the Sync_Mem() service.
UINT64 UniqueId;
//
// UNDI will pass this value to each of the callback services.
// A unique ID number should be generated for each instance of
// the UNDI driver that will be using these callback services.
//
} PXE_CPB_START_31;
#pragma pack()

For the 3.0 S/W UNDI Start command, the CPB structure shown below must be filled in and the CDB must be set to
sizeof(struct s_pxe_cpb_start_30).

#pragma pack(1)
typedef struct s_pxe_cpb_start_30 {
    UINT64 Delay;
    //
    // Address of the Delay() callback service.
    // This field cannot be set to zero.
    //
    // VOID
    // Delay(
    // IN UINT64 Microseconds);
    //
    // UNDI will never request a delay smaller than 10 microseconds
    // and will always request delays in increments of 10.
    // microseconds The Delay() callback routine must delay between
    // n and n + 10 microseconds before returning control to the
    // UNDI.
    //

    UINT64 Block;
    //
    // Address of the Block() callback service.
    // This field cannot be set to zero.
    //
    // VOID
    // Block(
    // IN UINT32 Enable);
    //
    // UNDI may need to block multithreaded/multiprocessor access
    // to critical code sections when programming or accessing the
    // network device. When UNDI needs a block, it will call the
    // Block()callback service with Enable set to a non-zero value.
    // When UNDI no longer needs the block, it will call Block()
    // with Enable set to zero.
    //

    UINT64 Virt2Phys;
    //
    // Convert a virtual address to a physical address.
    // This field can be set to zero if virtual and physical
// addresses are identical.
//
// VOID
// Virt2Phys(
// IN UINT64 Virtual,
// OUT UINT64 PhysicalPtr);
//
// UNDI will pass in a virtual address and a pointer to storage
// for a physical address. The Virt2Phys() service converts
// the virtual address to a physical address and stores the
// resulting physical address in the supplied buffer. If no
// conversion is needed, the virtual address must be copied
// into the supplied physical address buffer.
//
UINT64 Mem_IO;
//
// Read/Write network device memory and/or I/O register space.
// This field cannot be set to zero.
//
// VOID
// Mem_IO(
// IN UINT8 AccessType,
// IN UINT8 Length,
// IN UINT64 Port,
// IN OUT UINT64 BufferPtr);
//
// UNDI uses the Mem_IO() service to access the network device
// memory and/or I/O registers. The AccessType is one of the
// PXE_IO_xxx or PXE_MEM_xxx constants defined at the end of
// this section. The Length is 1, 2, 4 or 8. The Port number
// is relative to the base memory or I/O address space for this
// device. BufferPtr points to the data to be written to the
// Port or will contain the data that is read from the Port.
//
} PXE_CPB_START_30;
#pragma pack()
E.4.3.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the CDB.StatFlags field. Until these bits change to report PXE_STATFLAGS_COMMAND_COMPLETE or PXE_STATFLAGS_COMMAND_FAILED, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. UNDI is now started.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

E.4.3.4 Checking Command Execution Results

After command execution completes, either successfully or not, the CDB.StatCode field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. UNDI is now started.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>ALREADY_STARTED</td>
<td>The UNDI is already started.</td>
</tr>
</tbody>
</table>

E.4.4 Stop

This command is used to change the UNDI operational state from started to stopped.

E.4.4.1 Issuing the Command

To issue a Stop command, create a CDB and fill it in as shows in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Stop command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_STOP</td>
</tr>
<tr>
<td>OpFlags</td>
<td>PXE_OPFLAGS_NOT_USED</td>
</tr>
<tr>
<td>CPBsize</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBsize</td>
<td>PXE_DBSIZE_NOT_USED</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>PXE_CPBADDR_NOT_USED</td>
</tr>
<tr>
<td>DBaddr</td>
<td>PXE_DBADDR_NOT_USE</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZ</td>
</tr>
<tr>
<td>Ifnum</td>
<td>A valid interface number from zero to ( !PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed</td>
</tr>
</tbody>
</table>
E.4.4.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the CDB.StatFlags field. Until these bits change to report PXE_STATFLAGS_COMMAND_COMPLETE or PXE_STATFLAGS_COMMAND_FAILED, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. UNDI is now stopped.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has not been executed or queued.</td>
</tr>
</tbody>
</table>

E.4.4.3 Checking Command Execution Results

After command execution completes, either successfully or not, the CDB.StatCode field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. UNDI is now stopped.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_SHUTDOWN</td>
<td>The UNDI is initialized and must be shutdown before it can be stopped.</td>
</tr>
</tbody>
</table>

E.4.5 Get Init Info

This command is used to retrieve initialization information that is needed by drivers and applications to initialized UNDI.

E.4.5.1 Issuing the Command

To issue a Get Init Info command, create a CDB and fill it in as shows in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Get Init Info command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_GET_INIT_INFO</td>
</tr>
<tr>
<td>OpFlags</td>
<td>PXE_OPFLAGS_NOT_USED</td>
</tr>
<tr>
<td>CPBsize</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBsize</td>
<td>sizeof(PXE_DB_INIT_INFO)</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>PXE_CPBADDR_NOT_USED</td>
</tr>
<tr>
<td>DBaddr</td>
<td>Address of a PXE_DB_INIT_INFO structure.</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to ( !PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>
E.4.5.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the CDB.StatFlags field. Until these bits change to report PXE_STATFLAGS_COMMAND_COMPLETE or PXE_STATFLAGS_COMMAND_FAILED, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND COMPLETE</td>
<td>Command completed successfully. DB can be used.</td>
</tr>
<tr>
<td>COMMAND QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

E.4.5.3 Checking Command Execution Results

After command execution completes, either successfully or not, the CDB.StatCode field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. DB can be used.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
</tbody>
</table>

E.4.5.4 StatFlags

To determine if cable detection is supported by this UNDI/NIC, use these macros with the value returned in the CDB.StatFlags field:

- PXE_STATFLAGS_CABLE_DETECT_MASK
- PXE_STATFLAGS_CABLE_DETECT_NOT_SUPPORTED
- PXE_STATFLAGS_CABLE_DETECT_SUPPORTED
- PXE_STATFLAGS_GET_STATUS_NO_MEDIA_MASK
- PXE_STATFLAGS_GET_STATUS_NO_MEDIA_NOT_SUPPORTED
- PXE_STATFLAGS_GET_STATUS_NO_MEDIA_SUPPORTED

E.4.5.5 DB

```c
#pragma pack(1)
typedef struct s_pxe_db_get_init_info {
  // Minimum length of locked memory buffer that must be given to
  // the Initialize command. Giving UNDI more memory will
  // generally give better performance.
  // If MemoryRequired is zero, the UNDI does not need and will
  // not use system memory to receive and transmit packets.

(continues on next page)```
// Maximum frame data length for Tx/Rx excluding the media header.
// Supported link speeds are in units of mega bits. Common ethernet values are 10, 100 and 1000. Unused LinkSpeeds[] entries are zero filled.

// Number of nonvolatile storage items.

// Width of nonvolatile storage item in bytes. 0, 1, 2 or 4

// Media header length. This is the typical media header length for this UNDI. This information is needed when allocating receive and transmit buffers.

// Maximum number of multicast MAC addresses in the multicast MAC address filter list.

// Default number and size of transmit and receive buffers that will be allocated by the UNDI. If MemoryRequired is nonzero, this allocation will come out of the memory buffer given to the Initialize command. If MemoryRequired is zero, this allocation will come out of memory on the NIC.

// Hardware interface types defined in the Assigned Numbers RFC and used in DHCP and ARP packets. See the PXE_IFTYPE typedef and PXE_IFTYPE_xxx macros.

// Hardware interface types defined in the Assigned Numbers RFC and used in DHCP and ARP packets.
E.4.6 Get Config Info

This command is used to retrieve configuration information about the NIC being controlled by the UNDI.

E.4.6.1 Issuing the Command

To issue a Get Config Info command, create a CDB and fill it in as shown in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Get Config Info command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_GET_CONFIG_INFO</td>
</tr>
<tr>
<td>OpFlags</td>
<td>PXE_OPFLAGS_NOT_USED</td>
</tr>
<tr>
<td>CPBsize</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBsize</td>
<td>sizeof(PXE_DB_CONFIG_INFO)</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>PXE_CPBADDR_NOT_USED</td>
</tr>
<tr>
<td>DBaddr</td>
<td>Address of a PXE_DB_CONFIG_INFO structure</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to (!PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed</td>
</tr>
</tbody>
</table>
E.4.6.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the `CDB.StatFlags` field. Until these bits change to report `PXE_STATFLAGS_COMMAND_COMPLETE` or `PXE_STATFLAGS_COMMAND_FAILED`, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. DB has been written.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

E.4.6.3 Checking Command Execution Results

After command execution completes, either successfully or not, the `CDB.StatCode` field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. DB has been written.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
</tbody>
</table>

E.4.6.4 DB

```c
#pragma pack(1)
typedef struct s_pxe_pci_config_info {

    // This is the flag field for the PXE_DB_GET_CONFIG_INFO union.
    // For PCI bus devices, this field is set to PXE_BUSTYPE_PCI.
    PXE_UINT32 BusType;

    // This identifies the PCI network device that this UNDI
    // interface is bound to.
    PXE_UINT16 Bus;
    PXE_UINT8 Device;
    PXE_UINT8 Function;

    // This is a copy of the PCI configuration space for this
    // network device.

    union {
        PXE_UINT8 Byte[256];
    }

}(continues on next page)```
typedef struct s_pxe_pcc_config_info {
    // This is the flag field for the PXE_DB_GET_CONFIG_INFO union.
    // For PCC bus devices, this field is set to PXE_BUSTYPE_PCC.
    PXE_UINT32 BusType;

    // This identifies the PCC network device that this UNDI interface is bound to.
    PXE_UINT16 Bus;
    PXE_UINT8 Device;
    PXE_UINT8 Function;

    // This is a copy of the PCC configuration space for this network device.
    union {
        PXE_UINT8 Byte[256];
        PXE_UINT16 Word[128];
        PXE_UINT32 Dword[64];
    } Config;
} PXE_PCC_CONFIG_INFO;

E.4.7 Initialize

This command resets the network adapter and initializes UNDI using the parameters supplied in the CPB. The Initialize command must be issued before the network adapter can be setup to transmit and receive packets. This command will not enable the receive unit or external interrupts.

Once the memory requirements of the UNDI are obtained by using the Get Init Info command, a block of kernel (nonswappable) memory may need to be allocated by the protocol driver. The address of this kernel memory must be passed to UNDI using the Initialize command CPB. This memory is used for transmit and receive buffers and internal processing.

Initializing the network device will take up to four seconds for most network devices and in some extreme cases (usually poor cables) up to twenty seconds. Control will not be returned to the caller and the COMMAND_COMPLETE status flag will not be set until the NIC is ready to transmit.
E.4.7.1 Issuing the Command

To issue an Initialize command, create a CDB and fill it in as shows in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for an Initialize command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_INITIALIZE</td>
</tr>
<tr>
<td>CPBsize</td>
<td>sizeof(PXE_CPB_INITIALIZE)</td>
</tr>
<tr>
<td>DBsize</td>
<td>sizeof(PXE_DB_INITIALIZE)</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>Address of a PXE_CPB_INITIALIZE structure.</td>
</tr>
<tr>
<td>Dbaddr</td>
<td>Address of a PXE_DB_INITIALIZE structure.</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>Ifnum</td>
<td>A valid interface number from zero to ( !PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>

E.4.7.2 OpFlags

Cable detection can be enabled or disabled by setting one of the following OpFlags:

- PXE_OPFLAGS_INITIALIZE_CABLE_DETECT
- PXE_OPFLAGS_INITIALIZE_DO_NOT_DETECT_CABLE

E.4.7.3 Preparing the CPB

If the MemoryRequired field returned in the PXE_DB_GET_INIT_INFO structure is zero, the Initialize command does not need to be given a memory buffer or even a CPB structure. If the MemoryRequired field is nonzero, the Initialize command does need a memory buffer.

```
#pragma pack(1)
typedef struct s_pxe_cpb_initialize {

    // Address of first (lowest) byte of the memory buffer.
    // This buffer must be in contiguous physical memory and cannot
    // be swapped out. The UNDI will be using this for transmit
    // and receive buffering. This address must be a processor-
    // based address for S/W UNDI and a device-based address for
    // H/W UNDI.
    PXE_UINT64 MemoryAddr;

    // MemoryLength must be greater than or equal to MemoryRequired
    // returned by the Get Init Info command.
    PXE_UINT32 MemoryLength;

    // Desired link speed in Mbit/sec. Common ethernet values are
    // 10, 100 and 1000. Setting a value of zero will auto-detect
    // and/or use the default link speed (operation depends on
    // UNDI/NIC functionality).
    PXE_UINT32 LinkSpeed;
}
```

(continues on next page)
// Suggested number and size of receive and transmit buffers to
// allocate. If MemoryAddr and MemoryLength are nonzero, this
// allocation comes out of the supplied memory buffer. If
// MemoryAddr and MemoryLength are zero, this allocation comes
// out of memory on the NIC.

// If these fields are set to zero, the UNDI will allocate
// buffer counts and sizes as it sees fit.

PXE_UINT16 TxBufCnt;
PXE_UINT16 TxBufSize;
PXE_UINT16 RxBufCnt;
PXE_UINT16 RxBufSize;

// The following configuration parameters are optional and must
// be zero to use the default values.
// The possible values for these parameters are defined below.

PXE_UINT8 DuplexMode;
PXE_UINT8 LoopBackMode;

} PXE_CPB.Initialize;
#pragma pack()

#define PXE_DUPLEX_AUTO_DETECT 0x00
#define PXE_FORCE_FULL_DUPLEX 0x01
#define PXE_FORCE_HALF_DUPLEX 0x02
#define PXE_LOOPBACK_NORMAL 0
#define PXE_LOOPBACK_INTERNAL 1
#define PXE_LOOPBACK_EXTERNAL 2

E.4.7.4 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the CDB.StatFlags field. Until these bits change to report
PXE_STATFLAGS_COMMAND_COMPLETE or PXE_STATFLAGS_COMMAND_FAILED, the command has not
been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. UNDI and network device is now initialized. DB has been written.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>
E.4.7.5 Checking Command Execution Results

After command execution completes, either successfully or not, the \textit{CDB.StatCode} field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. UNDI and network device is now initialized. DB has been written. Check StatFlags.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>INVALID_CPB</td>
<td>One of the CPB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>ALREADY_INITIALIZED</td>
<td>The UNDI is already initialized.</td>
</tr>
<tr>
<td>DEVICE_FAILURE</td>
<td>The network device could not be initialized.</td>
</tr>
<tr>
<td>NVDATA_FAILURE</td>
<td>The nonvolatile storage could not be read.</td>
</tr>
</tbody>
</table>

E.4.7.6 StatFlags

Check the StatFlags to see if there is an active connection to this network device. If the no media StatFlag is set, the UNDI and network device are still initialized. \textit{PXE_STATFLAGS_INITIALIZED_NO_MEDIA}

E.4.7.7 Before Using the DB

```c
#pragma pack(1)
typedef struct s_pxe_db_initialize {

    // Actual amount of memory used \textit{from the} supplied memory
    // buffer. This may be less that the amount of memory
    // supplied and may be zero \textit{if the UNDI and network device
    // do not use external memory buffers. Memory used by the
    // UNDI and network device is allocated \textit{from the} lowest
    // memory buffer address.
    PXE_UINT32 MemoryUsed;

    // Actual number and size of receive and transmit buffers that
    // were allocated.
    PXE_UINT16 TxBufCnt;
PXE_UINT16 TxBufSize;
PXE_UINT16 RxBufCnt;
PXE_UINT16 RxBufSize
} PXE_DB_INITIALIZE;
#pragma pack()
```

E.4. UNDI Commands
E.4.8 Reset

This command resets the network adapter and reinitializes the UNDI with the same parameters provided in the Initialize command. The transmit and receive queues are emptied and any pending interrupts are cleared. Depending on the state of the OpFlags, the receive filters and external interrupt enables may also be reset.

Resetting the network device may take up to four seconds and in some extreme cases (usually poor cables) up to twenty seconds. Control will not be returned to the caller and the COMMAND_COMPLETE status flag will not be set until the NIC is ready to transmit.

E.4.8.1 Issuing the Command

To issue a Reset command, create a CDB and fill it in as shows in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Reset command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_RESET</td>
</tr>
<tr>
<td>OpFlags</td>
<td>Set as needed.</td>
</tr>
<tr>
<td>CPBsize</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBsize</td>
<td>PXE_DBSIZE_NOT_USED</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBaddr</td>
<td>PXE_DBSIZE_NOT_USED</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to ((!PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>

E.4.8.2 OpFlags

Normally the settings of the receive filters and external interrupt enables are unchanged by the Reset command. These two OpFlags will alter the operation of the Reset command.

PXE_OPFLAGS_RESET_DISABLE_INTERRUPTS
PXE_OPFLAGS_RESET_DISABLE_FILTERS

E.4.8.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the CDB.StatFlags field. Until these bits change to report PXE_STATFLAGS_COMMAND_COMPLETE or PXE_STATFLAGS_COMMAND_FAILED, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. UNI DI and network device have been reset. Check StatFlags.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>
E.4.8.4 Checking Command Execution Results

After command execution completes, either successfully or not, the $CDB.StatCode$ field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully.</td>
</tr>
<tr>
<td></td>
<td>UNDI and network device have been reset. Check StatFlags.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_INITIALIZED</td>
<td>The UNDI is not initialized.</td>
</tr>
<tr>
<td>DEVICE_FAILURE</td>
<td>The network device could not be initialized.</td>
</tr>
<tr>
<td>NVDATA_FAILURE</td>
<td>The nonvolatile storage is not valid.</td>
</tr>
</tbody>
</table>

E.4.8.5 StatFlags

Check the StatFlags to see if there is an active connection to this network device. If the no media StatFlag is set, the UNDI and network device are still reset. $PXE_STATFLAGS_RESET_NO_MEDIA$

E.4.9 Shutdown

The Shutdown command resets the network adapter and leaves it in a safe state for another driver to initialize. Any pending transmits or receives are lost. Receive filters and external interrupt enables are reset (disabled). The memory buffer assigned in the Initialize command can be released or reassigned.

Once UNDI has been shutdown, it can then be stopped or initialized again. The Shutdown command changes the UNDI operational state from initializeMake htmled to started.

E.4.9.1 Issuing the Command

To issue a Shutdown command, create a CDB and fill it in as shown in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Shutdown command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_SHUTDOWN</td>
</tr>
<tr>
<td>OpFlags</td>
<td>PXE_OPPFLAGS_NOT_USED</td>
</tr>
<tr>
<td>CPBsize</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBsize</td>
<td>PXE_DBSIZE_NOT_USED</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBaddr</td>
<td>PXE_DBSIZE_NOT_USED</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to ($PXE.IFcnt$</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>
E.4.9.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the CDB.StatFlags field. Until these bits change to report PXE_STATFLAGS_COMMAND_COMPLETE or PXE_STATFLAGS_COMMAND_FAILED, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. UNDI and network device are shutdown.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

E.4.9.3 Checking Command Execution Results

After command execution completes, either successfully or not, the CDB.StatCode field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. UNDI and network device are shutdown.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_INITIALIZED</td>
<td>The UNDI is not initialized.</td>
</tr>
</tbody>
</table>

E.4.10 Interrupt Enables

The Interrupt Enables command can be used to read and/or change the current external interrupt enable settings. Disabling an external interrupt enable prevents an external (hardware) interrupt from being signaled by the network device, internally the interrupt events can still be polled by using the Get Status command.

E.4.10.1 Issuing the Command

To issue an Interrupt Enables command, create a CDB and fill it in as shows in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for an Interrupt Enables command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_INTERRUPT_ENABLES</td>
</tr>
<tr>
<td>OpFlags</td>
<td>Set as needed.</td>
</tr>
<tr>
<td>CPBsize</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBsize</td>
<td>PXE_DBSIZE_NOT_USED</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>PXE_CPBADDR_NOT_USED</td>
</tr>
<tr>
<td>DBaddr</td>
<td>PXE_DBADDR_NOT_USED</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to ( !PXE.IFnct</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>
E.4.10.2 OpFlags

To read the current external interrupt enables settings set CDB.OpFlags to:

| PXE_OPFLAGS_INTERRUPT_READ |

To enable or disable external interrupts set one of these OpFlags:

| PXE_OPFLAGS_INTERRUPT_DISABLE |
| PXE_OPFLAGS_INTERRUPT_ENABLE |

When enabling or disabling interrupt settings, the following additional OpFlag bits are used to specify which types of external interrupts are to be enabled or disabled:

| PXE_OPFLAGS_INTERRUPT_RECEIVE |
| PXE_OPFLAGS_INTERRUPT_TRANSMIT |
| PXE_OPFLAGS_INTERRUPT_COMMAND |
| PXE_OPFLAGS_INTERRUPT_SOFTWARE |

Setting PXE_OPFLAGS_INTERRUPT_SOFTWARE does not enable an external interrupt type, it generates an external interrupt.

E.4.10.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the CDB.StatFlags field. Until these bits change to report PXE_STATFLAGS_COMMAND_COMPLETE or PXE_STATFLAGS_COMMAND_FAILED, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. Check StatFlags.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

E.4.10.4 Checking Command Execution Results

After command execution completes, either successfully or not, the CDB.StatCode field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. Check StatFlags.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_INITIALIZED</td>
<td>The UNDI is not initialized.</td>
</tr>
</tbody>
</table>
E.4.10.5 StatFlags

If the command was successful, the CDB.StatFlags field reports which external interrupt enable types are currently set. Possible CDB.StatFlags bit settings are:

- `PXE_STATFLAGS_INTERRUPT_RECEIVE`
- `PXE_STATFLAGS_INTERRUPT_TRANSMIT`
- `PXE_STATFLAGS_INTERRUPT_COMMAND`

The bits set in CDB.StatFlags may be different than those that were requested in CDB.OpFlags. For example: If transmit and receive share an external interrupt line, setting either the transmit or receive interrupt will always enable both transmit and receive interrupts. In this case both transmit and receive interrupts will be reported in CDB.StatFlags. Always expect to get more than you ask for!

E.4.11 Receive Filters

This command is used to read and change receive filters and, if supported, read and change the multicast MAC address filter list. Control will not be returned to the caller and the COMMAND_COMPLETE status flag will not be set until the NIC is ready to receive.

E.4.11.1 Issuing the Command

To issue a Receive Filters command, create a CDB and fill it in as shown in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Receive Filters command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td><code>PXE_OPCODE_RECEIVE_FILTERS</code></td>
</tr>
<tr>
<td>OpFlags</td>
<td>Set as needed.</td>
</tr>
<tr>
<td>CPBsize</td>
<td><code>sizeof(PXE_CPB_RECEIVE_FILTERS)</code></td>
</tr>
<tr>
<td>DBsize</td>
<td><code>sizeof(PXE_DB_RECEIVE_FILTERS)</code></td>
</tr>
<tr>
<td>CPBaddr</td>
<td>Address of PXE_CPB_RECEIVE_FILTERS structure.</td>
</tr>
<tr>
<td>DBaddr</td>
<td>Address of PXE_DB_RECEIVE_FILTERS structure.</td>
</tr>
<tr>
<td>StatCode</td>
<td><code>PXE_STATCODE_INITIALIZE</code></td>
</tr>
<tr>
<td>StatFlags</td>
<td><code>PXE_STATFLAGS_INITIALIZE</code></td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to (`!PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>

E.4.11.2 OpFlags

To read the current receive filter settings set the CDB.OpFlags field to:

- `PXE_OPFLAGS_RECEIVE_FILTER_READ`

To change the current receive filter settings set one of these OpFlag bits:

- `PXE_OPFLAGS_RECEIVE_FILTER_ENABLE`
- `PXE_OPFLAGS_RECEIVE_FILTER_DISABLE`

When changing the receive filter settings, at least one of the OpFlag bits in this list must be selected:

- `PXE_OPFLAGS_RECEIVE_FILTER_UNICAST`
- `PXE_OPFLAGS_RECEIVE_FILTER_BROADCAST`
- `PXE_OPFLAGS_RECEIVE_FILTER_FILTERED_MULTICAST`
• **PXE_OPFLAGS_RECEIVE_FILTER_PROMISCUOUS**
• **PXE_OPFLAGS_RECEIVE_FILTER_ALL_MULTICAST**

To clear the contents of the multicast MAC address filter list, set this OpFlag:
• **PXE_OPFLAGS_RECEIVE_FILTER_RESET_MCAST_LIST**

### E.4.11.3 Preparing the CPB

The receive filter CPB is used to change the contents multicast MAC address filter list. To leave the multicast MAC address filter list unchanged, set the `CDB.CPBsize` field to **PXE_CPBSIZE_NOT_USED** and `CDB.CPBaddr` to **PXE_CPBADDR_NOT_USED**.

To change the multicast MAC address filter list, set `CDB.CPBsize` to the size, in bytes, of the multicast MAC address filter list and set `CDB.CPBaddr` to the address of the first entry in the multicast MAC address filter list.

```c
typedef struct s_pxe_cpb_receive_filters {
    // List of multicast MAC addresses. This list, if present,
    // will replace the existing multicast MAC address filter list.
    PXE_MAC_ADDR MCastList[n];
} PXE_CPB_RECEIVE_FILTERS;
```

### E.4.11.4 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the `CDB.StatFlags` field. Until these bits change to report **PXE_STATFLAGS_COMMAND_COMPLETE** or **PXE_STATFLAGS_COMMAND_FAILED**, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. Check StatFlags. DB is written.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

### E.4.11.5 Checking Command Execution Results

After command execution completes, either successfully or not, the `CDB.StatCode` field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. Check StatFlags. DB is written.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>INVALID_CPB</td>
<td>One of the CPB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_INITIALIZED</td>
<td>The UNDI is not initialized.</td>
</tr>
</tbody>
</table>
E.4.11.6 StatFlags

The receive filter settings in CDB.StatFlags are:

- PXE_STATFLAGS_RECEIVE_FILTER_UNICAST
- PXE_STATFLAGS_RECEIVE_FILTER_BROADCAST
- PXE_STATFLAGS_RECEIVE_FILTER_FILTERED_MULTICAST
- PXE_STATFLAGS_RECEIVE_FILTER_PROMISCUOUS
- PXE_STATFLAGS_RECEIVE_FILTER_ALL_MULTICAST

Unsupported receive filter settings in OpFlags are promoted to the next more liberal receive filter setting. For example: If broadcast or filtered multicast are requested and are not supported by the network device, but promiscuous is; the promiscuous status flag will be set.

E.4.11.7 DB

The DB is used to read the current multicast MAC address filter list. The CDB.DBsize and CDB.DBaddr fields can be set to PXE_DBSIZE_NOT_USED and PXE_DBADDR_NOT_USED if the multicast MAC address filter list does not need to be read. When reading the multicast MAC address filter list extra entries in the DB will be filled with zero.

```c
typedef struct s_pxe_db_receive_filters {
    // Filtered multicast MAC address list.
    PXE_MAC_ADDR MCastList[n];
} PXE_DB_RECEIVE_FILTERS;
```

E.4.12 Station Address

This command is used to get current station and broadcast MAC addresses and, if supported, to change the current station MAC address.

E.4.12.1 Issuing the Command

To issue a Station Address command, create a CDB and fill it in as shows in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Station Address command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_STATION_ADDRESS</td>
</tr>
<tr>
<td>OpFlags</td>
<td>Set as needed.</td>
</tr>
<tr>
<td>CPBsize</td>
<td>sizeof(PXE_CPB_STATION_ADDRESS)</td>
</tr>
<tr>
<td>DBsize</td>
<td>sizeof(PXE_DB_STATION_ADDRESS)</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>Address of PXE_CPB_STATION_ADDRESS structure.</td>
</tr>
<tr>
<td>DBaddr</td>
<td>Address of PXE_DB_STATION_ADDRESS structure.</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to ( !PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>
E.4.12.2 OpFlags

To read current station and broadcast MAC addresses set the OpFlags field to:

- `PXE_OPFLAGS_STATION_ADDRESS_READ`

To change the current station to the address given in the CPB set the OpFlags field to:

- `PXE_OPFLAGS_STATION_ADDRESS_WRITE`

To reset the current station address back to the power on default, set the OpFlags field to:

- `PXE_OPFLAGS_STATION_ADDRESS_RESET`

E.4.12.3 Preparing the CPB

To change the current station MAC address the `CDB.CPBsize` and `CDB.CPBaddr` fields must be set.

```c
typedef struct s_pxe_cpb_station_address {
    // If supplied and supported, the current station MAC address
    // will be changed.
    PXE_MAC_ADDR StationAddr;
} PXE_CPB_STATION_ADDRESS;
```

E.4.12.4 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the `CDB.StatFlags` field. Until these bits change to report `PXE_STATFLAGS_COMMAND_COMPLETE` or `PXE_STATFLAGS_COMMAND_FAILED`, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. DB is written.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

E.4.12.5 Checking Command Execution Results

After command execution completes, either successfully or not, the `CDB.StatCode` field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>INVALID_CPB</td>
<td>One of the CPB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_INITIALIZED</td>
<td>The UNDI is not initialized.</td>
</tr>
</tbody>
</table>

continues on next page
### E.4.12.6 Before Using the DB

The DB is used to read the current station, broadcast and permanent station MAC addresses. The `CDB.DBsize` and `CDB.DBaddr` fields can be set to `PXE_DBSIZE_NOT_USED` and `PXE_DBADDR_NOT_USED` if these addresses do not need to be read.

```c
typedef struct s_pxe_db_station_address {
    // Current station MAC address.
    PXE_MAC_ADDR StationAddr;

    // Station broadcast MAC address.
    PXE_MAC_ADDR BroadcastAddr;

    // Permanent station MAC address.
    PXE_MAC_ADDR PermanentAddr;
} PXE_DB_STATION_ADDRESS;
```

### E.4.13 Statistics

This command is used to read and clear the NIC traffic statistics. Before using this command check to see if statistics is supported in the `!PXE.Implementation` flags.

#### E.4.13.1 Issuing the Command

To issue a Statistics command, create a CDB and fill it in as shown in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Statistics command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_STATISTICS</td>
</tr>
<tr>
<td>OpFlags</td>
<td>Set as needed.</td>
</tr>
<tr>
<td>CPBsize</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBsize</td>
<td>sizeof(PXE_DB_STATISTICS)</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>PXE_CPBADDR_NOT_USED</td>
</tr>
<tr>
<td>DBaddr</td>
<td>Address of PXE_DB_STATISTICS structure.</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to (`!PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>
E.4.13.2 OpFlags

To read the current statistics counters set the OpFlags field to:

PXE_OPFLAGS_STATISTICS_READ

To reset the current statistics counters set the OpFlags field to:

PXE_OPFLAGS_STATISTICS_RESET

E.4.13.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the CDB.StatFlags field. Until these bits change to report PXE_STATFLAGS_COMMAND_COMPLETE or PXE_STATFLAGS_COMMAND_FAILED, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. DB is written.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

E.4.13.4 Checking Command Execution Results

After command execution completes, either successfully or not, the CDB.StatCode field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. DB is written.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_INITIALIZED</td>
<td>The UNDI is not initialized.</td>
</tr>
<tr>
<td>UNSUPPORTED</td>
<td>This command is not supported.</td>
</tr>
</tbody>
</table>

E.4.13.5 DB

Unsupported statistics counters will be zero filled by UNDI.

typedef struct s_pxe_db_statistics {
    // Bit field identifying what statistic data is collected by
    // the UNDI/NIC.
    // If bit 0x00 is set, Data[0x00] is collected.
    // If bit 0x01 is set, Data[0x01] is collected.
}
// If bit 0x20 is set, Data[0x20] is collected.
// If bit 0x21 is set, Data[0x21] is collected.
// Etc.
PXE_UINT64 Supported;

// Statistic data.

PXE_UINT64 Data[64];
}
PXE_DB_STATISTICS;

// Total number of frames received. Includes frames with errors and dropped frames.
#define PXE_STATISTICS_RX_TOTAL_FRAMES 0x00

// Number of valid frames received and copied into receive buffers.
#define PXE_STATISTICS_RX_GOOD_FRAMES 0x01

// Number of frames below the minimum length for the media. This would be <64 for ethernet.
#define PXE_STATISTICS_RX_UNDERSIZE_FRAMES 0x02

// Number of frames longer than the maximum length for the media. This would be >1500 for ethernet.
#define PXE_STATISTICS_RX_OVERSIZE_FRAMES 0x03

// Valid frames that were dropped because receive buffers were full.
#define PXE_STATISTICS_RX_DROPPED_FRAMES 0x04

// Number of valid unicast frames received and not dropped.
#define PXE_STATISTICS_RX_UNICAST_FRAMES 0x05

// Number of valid broadcast frames received and not dropped.
#define PXE_STATISTICS_RX_BROADCAST_FRAMES 0x06

// Number of valid multicast frames received and not dropped.
#define PXE_STATISTICS_RX_MULTICAST_FRAMES 0x07

// Number of frames w/ CRC or alignment errors.
#define PXE_STATISTICS_RX_CRC_ERROR_FRAMES 0x08

// Total number of bytes received. Includes frames with errors and dropped frames.
#define PXE_STATISTICS_RX_TOTAL_BYTES 0x09

// Transmit statistics.
#define PXE_STATISTICS_TX_TOTAL_FRAMES 0x0A
#define PXE_STATISTICS_TX_GOOD_FRAMES 0x0B
#define PXE_STATISTICS_TX_UNDERSIZE_FRAMES 0x0C
#define PXE_STATISTICS_TX_OVERSIZE_FRAMES 0x0D
#define PXE_STATISTICS_TX_DROPPED_FRAMES 0x0E
#define PXE_STATISTICS_TX_UNICAST_FRAMES 0x0F
#define PXE_STATISTICS_TX_BROADCAST_FRAMES 0x10
#define PXE_STATISTICS_TX_MULTICAST_FRAMES 0x11
#define PXE_STATISTICS_TX_CRC_ERROR_FRAMES 0x12
#define PXE_STATISTICS_TX_TOTAL_BYTES 0x13

// Number of collisions detection on this subnet.
#define PXE_STATISTICS_COLLISIONS 0x14

// Number of frames destined for unsupported protocol.
#define PXE_STATISTICS_UNSUPPORTED_PROTOCOL 0x15

// Number of valid frames received that were duplicated.
#define PXE_STATISTICS_RX_DUPLICATED_FRAMES 0x16

// Number of encrypted frames received that failed to decrypt.
#define PXE_STATISTICS_RX_DECRYPT_ERROR_FRAMES 0x17

// Number of frames that failed to transmit after exceeding the retry limit.
#define PXE_STATISTICS_TX_ERROR_FRAMES 0x18

// Number of frames transmitted successfully after more than one attempt.
#define PXE_STATISTICS_TX_RETRY_FRAMES 0x19

## E.4.14 MCast IP To MAC

Translate a multicast IPv4 or IPv6 address to a multicast MAC address.

### E.4.14.1 Issuing the Command

To issue a MCast IP To MAC command, create a CDB and fill it in as shown in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a MCast IP To MAC command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_MCAST_IP_TO_MAC</td>
</tr>
<tr>
<td>OpFlags</td>
<td>Set as needed.</td>
</tr>
<tr>
<td>CPBsize</td>
<td>sizeof(PXE_CPB_MCAST_IP_TO_MAC)</td>
</tr>
<tr>
<td>DBsize</td>
<td>sizeof(PXE_DB_MCAST_IP_TO_MAC)</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>Address of PXE_CPB_MCAST_IP_TO_MAC structure.</td>
</tr>
<tr>
<td>Dbaddr</td>
<td>Address of PXE_DB_MCAST_IP_TO_MAC structure.</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>Ifnum</td>
<td>A valid interface number from zero to (!PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>
E.4.14.2 OpFlags

To convert a multicast IP address to a multicast MAC address the UNDI needs to know the format of the IP address. Set one of these OpFlags to identify the format of the IP addresses in the CPB:

- PXE_OPFLAGS_MCAST_IPV4_TO_MAC
- PXE_OPFLAGS_MCAST_IPV6_TO_MAC

E.4.14.3 Preparing the CPB

Fill in an array of one or more multicast IP addresses. Be sure to set the `CDB.CPBsize` and `CDB.CPBaddr` fields accordingly.

```c
typedef struct s_pxe_cpb_mcast_ip_to_mac {
    // Multicast IP address to be converted to multicast
    // MAC address.
    PXE_IP_ADDR IP[n];
} PXE_CPB_MCAST_IP_TO_MAC;
```

E.4.14.4 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the `CDB.StatFlags` field. Until these bits change to report `PXE_STATFLAGS_COMMAND_COMPLETE` or `PXE_STATFLAGS_COMMAND_FAILED`, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. DB is written.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

E.4.14.5 Checking Command Execution Results

After command execution completes, either successfully or not, the `CDB.StatCode` field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. DB is written.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>INVALID_CPB</td>
<td>One of the CPB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
</tbody>
</table>

continues on next page
Table E.34 – continued from previous page

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a NvData command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_NVDATA</td>
</tr>
<tr>
<td>OpFlags</td>
<td>Set as needed.</td>
</tr>
<tr>
<td>CPBsize</td>
<td>sizeof(PXE_CPB_NVDATA)</td>
</tr>
<tr>
<td>DBsize</td>
<td>sizeof(PXE_DB_NVDATA)</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>Address of PXE_CPB_NVDATA structure.</td>
</tr>
<tr>
<td>Dbaddr</td>
<td>Address of PXE_DB_NVDATA structure.</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>Ifnum</td>
<td>A valid interface number from zero to (!PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>

E.4.15 NvData

This command is used to read and write (if supported by NIC H/W) nonvolatile storage on the NIC. Nonvolatile storage could be EEPROM, FLASH or battery backed RAM.

E.4.15.1 Issuing the Command

To issue a NvData command, create a CDB and fill it in as shown in the table below:

E.4.15.2 Preparing the CPB

There are two types of nonvolatile data CPBs, one for sparse updates and one for bulk updates. Sparse updates allow updating of single nonvolatile storage items. Bulk updates always update all nonvolatile storage items. Check the !PXE.Implementation flags to see which type of nonvolatile update is supported by this UNDI and network device.

If you do not need to update the nonvolatile storage set the CDB.CPBsize and CDB.CPBaddr fields to PXE_CPBSIZE_NOT_USED and PXE_CPBADDR_NOT_USED.
E.4.15.2.1 Sparse NvData CPB

typedef struct s_pxe_cpb_nvdata_sparse {
    // NvData item list. Only items in this list will be updated.
    struct {
        // Nonvolatile storage address to be changed.
        PXE_UINT32 Addr;

        // Data item to write into above storage address.
        union {
            PXE_UINT8 Byte;
            PXE_UINT16 Word;
            PXE_UINT32 Dword;
        } Data;
    } Item[n];
} PXE_CPB_NVDATA_SPARSE;

E.4.15.2.2 Bulk NvData CPB

// When using bulk update, the size of the CPB structure must be
// the same size as the nonvolatile NIC storage.

typedef union u_pxe_cpb_nvdata_bulk {
    // Array of byte-wide data items.
    PXE_UINT8 Byte[n];

    // Array of word-wide data items.
    PXE_UINT16 Word[n];

    // Array of dword-wide data items.
    PXE_UINT32 Dword[n];
} PXE_CPB_NVDATA_BULK;

E.4.15.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the $CDB.StatFlags$ field. Until these bits change to report $PXE_STATFLAGS_COMMAND_COMPLETE$ or $PXE_STATFLAGS_COMMAND_FAILED$, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. Nonvolatile data is updated from CPB and/or written to DB.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>
E.4.15.4 Checking Command Execution Results

After command execution completes, either successfully or not, the CDB.StatCode field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. Nonvolatile data is updated from CPB and/or written to DB.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>INVALID_CPB</td>
<td>One of the CPB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_INITIALIZED</td>
<td>The UNDI is not initialized.</td>
</tr>
<tr>
<td>UNSUPPORTED</td>
<td>Requested operation is unsupported.</td>
</tr>
</tbody>
</table>

E.4.15.4.1 DB

Check the width and number of nonvolatile storage items. This information is returned by the Get Init Info command.

typedef struct s_pxe_db_nvdata {

    // Arrays of data items from nonvolatile storage.
    union {

        // Array of byte-wide data items.
        PXE_UINT8 Byte[n];

        // Array of word-wide data items.
        PXE_UINT16 Word[n];

        // Array of dword-wide data items.
        PXE_UINT32 Dword[n];
    } Data;
} PXE_DB_NVDATA;

E.4.16 Get Status

This command returns the current interrupt status and/or the transmitted buffer addresses and the current media status. If the current interrupt status is returned, pending interrupts will be acknowledged by this command. Transmitted buffer addresses that are written to the DB are removed from the transmitted buffer queue.

This command may be used in a polled fashion with external interrupts disabled.
E.4.16.1 Issuing the Command

To issue a Get Status command, create a CDB and fill it in as shown in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Get Status command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_GET_STATUS</td>
</tr>
<tr>
<td>OpFlags</td>
<td>Set as needed.</td>
</tr>
<tr>
<td>CPBsize</td>
<td>PXE_CPBSIZE_NOT_USED</td>
</tr>
<tr>
<td>DBsize</td>
<td>Sizeof(PXE_DB_GET_STATUS)</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>PXE_CPBADDR_NOT_USED</td>
</tr>
<tr>
<td>DBaddr</td>
<td>Address of PXE_DB_GET_STATUS structure.</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to ($PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>

E.4.16.1.1 Setting OpFlags

Set one or a combination of the OpFlags below to return the interrupt status and/or the transmitted buffer addresses and/or the media status.

- PXE_OPFLAGS_GET_INTERRUPT_STATUS
- PXE_OPFLAGS_GET_TRANSMITTED_BUFFERS
- PXE_OPFLAGS_GET_MEDIA_STATUS

E.4.16.2 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the CDB.StatFlags field. Until these bits change to report PXE_STATFLAGS_COMMAND_COMPLETE or PXE_STATFLAGS_COMMAND_FAILED, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. StatFlags and/or DB are updated.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

E.4.16.3 Checking Command Execution Results

After command execution completes, either successfully or not, the CDB.StatCode field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. StatFlags and/or DB are updated.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
</tbody>
</table>

continues on next page
Table E.40 – continued from previous page

<table>
<thead>
<tr>
<th>Enum</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_INITIALIZED</td>
<td>The UNDI is not initialized.</td>
</tr>
</tbody>
</table>

E.4.16.4 StatFlags

If the command completes successfully and the `PXE_OPFLAGS_GET_INTERRUPT_STATUS` OpFlag was set in the CDB, the current interrupt status is returned in the `CDB.StatFlags` field and any pending interrupts will have been cleared.

The StatFlags above may not map directly to external interrupt signals. For example: Some NICs may combine both the receive and transmit interrupts to one external interrupt line. When a receive and/or transmit interrupt occurs, use the Get Status to determine which type(s) of interrupt(s) occurred.

This flag is set if the transmitted buffer queue is empty. This flag will be set if all transmitted buffer addresses get written into the DB.

```
PXE_STATFLAGS_GET_STATUS_TXBUF_QUEUE_EMPTY
```

This flag is set if no transmitted buffer addresses were written into the DB.

```
PXE_STATFLAGS_GET_STATUS_NO_TXBUFS_WRITTEN
```

This flag is set if there is no media present.

```
PXE_STATFLAGS_GET_STATUS_NO_MEDIA
```

E.4.16.5 Using the DB

When reading the transmitted buffer addresses there should be room for at least one 64-bit address in the DB. Once a complete transmitted buffer address is written into the DB, the address is removed from the transmitted buffer queue. If the transmitted buffer queue is full, attempts to use the Transmit command will fail.

```
#pragma pack(1)
typedef struct s_pxe_db_get_status {
    // Length of next receive frame (header + data). If this is zero, there is no next receive frame available.
    PXE_UINT32 RxFrameLen;
    // Reserved, set to zero.
    PXE_UINT32 reserved;
    // Addresses of transmitted buffers that need to be recycled.
    PXE_UINT64 xBuffer[n];
}
```

(continues on next page)
E.4.17 Fill Header

This command is used to fill the media header(s) in transmit packet(s).

E.4.17.1 Issuing the Command

To issue a Fill Header command, create a CDB and fill it in as shown in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Fill Header command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_FILL_HEADER</td>
</tr>
<tr>
<td>OpFlags</td>
<td>Set as needed.</td>
</tr>
<tr>
<td>CPBsize</td>
<td>PXE_CPB_FILL_HEADER</td>
</tr>
<tr>
<td>DBsize</td>
<td>PXE_DBSIZE_NOT_USED</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>Address of a PXE_CPB_FILL_HEADER structure.</td>
</tr>
<tr>
<td>DBaddr</td>
<td>PXE_DBADDR_NOT_USED</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to (!PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>

E.4.17.2 OpFlags

Select one of the OpFlags below so the UNDI knows what type of CPB is being used.

PXE_OPFLAGS_FILL_HEADER_WHOLE
PXE_OPFLAGS_FILL_HEADER_FRAGMENTED

E.4.17.3 Preparing the CPB

If multiple frames per command are supported (see PXE.Implementation flags), multiple CPBs can be packed together. The CDB.CPBsize field lets the UNDI know how many CPBs are packed together.

E.4.17.4 Nonfragmented Frame

```c
#pragma pack(1)
typedef struct s_pxe_cpb_fill_header {
    // Source and destination MAC addresses. These will be copied
    // into the media header without doing byte swapping.
    PXE_MAC_ADDR SrcAddr;
    PXE_MAC_ADDR DestAddr;
    // Address of first byte of media header. The first byte of
```
E.4.17.5 Fragmented Frame

```
#pragma pack(1)
typedef struct s_pxe_cpb_fill_header_fragmented {
    // Source and destination MAC addresses. These will be copied
    // into the media header without doing byte swapping.
    PXE_MAC_ADDR SrcAddr;
    PXE_MAC_ADDR DestAddr;

    // Length of packet data in bytes (not including the media
    // header).
    PXE_UINT32 PacketLen;

    // Protocol type. This will be copied into the media header
    // without doing byte swapping. Protocol type numbers can be
    // obtained from the Assigned Numbers RFC 3232.
    PXE_MEDIA_PROTOCOL Protocol;

    // Length of the media header in bytes.
    PXE_UINT16 MediaHeaderLen;
}

#pragma pack()  
#define PXE_PROTOCOL_ETHERNET_IP 0x0800  
#define PXE_PROTOCOL_ETHERNET_ARP 0x0806
```

---

E.4. UNDI Commands

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(continues on next page)
E.4.17.6 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the CDB.StatFlags field. Until these bits change to report PXE_STATFLAGS_COMMAND_COMPLETE or PXE_STATFLAGS_COMMAND_FAILED, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. Frame is ready to transmit.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

E.4.17.7 Checking Command Execution Results

After command execution completes, either successfully or not, the CDB.StatCode field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. Frame is ready to transmit.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>INVALID_CPB</td>
<td>One of the CPB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Try again later.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_INITIALIZED</td>
<td>The UNDI is not initialized.</td>
</tr>
</tbody>
</table>
E.4.18 Transmit

The Transmit command is used to place a packet into the transmit queue. The data buffers given to this command are to be considered locked and the application or universal network driver loses the ownership of those buffers and must not free or relocate them until the ownership returns.

When the packets are transmitted, a transmit complete interrupt is generated (if interrupts are disabled, the transmit interrupt status is still set and can be checked using the Get Status command).

Some UNDI implementations and network adapters support transmitting multiple packets with one transmit command. If this feature is supported, multiple transmit CPBs can be linked in one transmit command.

Though all UNDIs support fragmented frames, the same cannot be said for all network devices or protocols. If a fragmented frame CPB is given to UNDI and the network device does not support fragmented frames (see !PXE.Implementation flags), the UNDI will have to copy the fragments into a local buffer before transmitting.

E.4.18.1 Issuing the Command

To issue a Transmit command, create a CDB and fill it in as shown in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Transmit command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_TRANSMIT</td>
</tr>
<tr>
<td>OpFlags</td>
<td>Set as needed.</td>
</tr>
<tr>
<td>CPBsize</td>
<td>sizeof(PXE_CPB_TRANSMIT)</td>
</tr>
<tr>
<td>DBsize</td>
<td>PXE_DBSIZE_NOT_USED</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>Address of a PXE_CPB_TRANSMIT structure.</td>
</tr>
<tr>
<td>DBaddr</td>
<td>PXE_DBADDR_NOT_USED</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to ( !PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>

E.4.18.2 OpFlags

Check the !PXE.Implementation flags to see if the network device support fragmented packets. Select one of the OpFlags below so the UNDI knows what type of CPB is being used.

| PXE_OPFLAGS_TRANSMIT_WHOLE   |
| PXE_OPFLAGS_TRANSMIT_FRAGMENTED |

In addition to selecting whether or not fragmented packets are being given, S/W UNDI needs to know if it should block until the packets are transmitted. H/W UNDI cannot block, these two OpFlag settings have no affect when used with H/W UNDI.

| PXE_OPFLAGS_TRANSMIT_BLOCK   |
| PXE_OPFLAGS_TRANSMIT_DONT_BLOCK |
E.4.18.3 Preparing the CPB

If multiple frames per command are supported (see PXE.Implementation flags), multiple CPBs can be packed together. The CDB.CPBsize field lets the UNDI know how many frames are to be transmitted.

E.4.18.4 Nonfragmented Frame

```c
#pragma pack(1)
typedef struct s_pxe_cpb_transmit {
    PXE_UINT64 FrameAddr;
    PXE_UINT32 DataLen;
    PXE_UINT16 MediaheaderLen;
    PXE_UINT16 reserved;
} PXE_CPB_TRANSMIT;
#pragma pack()
```

E.4.18.5 Fragmented Frame

```c
#pragma pack(1)
typedef struct s_pxe_cpb_transmit.fragments {
    PXE_UINT32 FrameLen;
    PXE_UINT16 MediaheaderLen;
    PXE_UINT16 FragCnt;
    struct {
        PXE_UINT64 FragAddr;
    } FragDesc;
} PXE_CPB_TRANSMIT.fragments;
#pragma pack()
```
E.4.18.6 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the `CDB.StatFlags` field. Until these bits change to report `PXE_STATFLAGS_COMMAND_COMPLETE` or `PXE_STATFLAGS_COMMAND_FAILED`, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. Use the Get Status command to see when frame buffers can be reused.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has been not executed or queued.</td>
</tr>
</tbody>
</table>

E.4.18.7 Checking Command Execution Results

After command execution completes, either successfully or not, the `CDB.StatCode` field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. Use the Get Status command to see when frame buffers can be reused.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>INVALID_CPB</td>
<td>One of the CPB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Wait for queued commands to complete. Try again later.</td>
</tr>
<tr>
<td>BUFFER_FULL</td>
<td>Transmit buffer is full. Call Get Status command to empty buffer.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_INITIALIZED</td>
<td>The UNDI is not initialized.</td>
</tr>
</tbody>
</table>

E.4.19 Receive

When the network adapter has received a frame, this command is used to copy the frame into driver/application storage. Once a frame has been copied, it is removed from the receive queue.
E.4.19.1 Issuing the Command

To issue a Receive command, create a CDB and fill it in as shown in the table below:

<table>
<thead>
<tr>
<th>CDB Field</th>
<th>How to initialize the CDB structure for a Receive command</th>
</tr>
</thead>
<tbody>
<tr>
<td>OpCode</td>
<td>PXE_OPCODE_RECEIVE</td>
</tr>
<tr>
<td>OpFlags</td>
<td>Set as needed.</td>
</tr>
<tr>
<td>CPBsize</td>
<td>sizeof(PXE_CPB_RECEIVE)</td>
</tr>
<tr>
<td>DBsize</td>
<td>sizeof(PXE_DB_RECEIVE)</td>
</tr>
<tr>
<td>CPBaddr</td>
<td>Address of a PXE_CPB_RECEIVE structure.</td>
</tr>
<tr>
<td>DBaddr</td>
<td>Address of a PXE_DB_RECEIVE structure.</td>
</tr>
<tr>
<td>StatCode</td>
<td>PXE_STATCODE_INITIALIZE</td>
</tr>
<tr>
<td>StatFlags</td>
<td>PXE_STATFLAGS_INITIALIZE</td>
</tr>
<tr>
<td>IFnum</td>
<td>A valid interface number from zero to (!PXE.IFcnt</td>
</tr>
<tr>
<td>Control</td>
<td>Set as needed.</td>
</tr>
</tbody>
</table>

E.4.19.2 Preparing the CPB

If multiple frames per command are supported (see !PXE.Implementation flags), multiple CPBs can be packed together. For each complete received frame, a receive buffer large enough to contain the entire unfragmented frame needs to be described in the CPB. Note that if a smaller than required buffer is provided, only a portion of the packet is received into the buffer, and the remainder of the packet is lost. Subsequent attempts to receive the same packet with a corrected (larger) buffer will be unsuccessful, because the packet will have been flushed from the queue.

```c
#pragma pack(1)
typedef struct s_pxe_cpb_receive {
    // Address of first byte of receive buffer. This is also the
    // first byte of the frame header. This address must be a
    // processor-based address for S/W UNDI and a device-based
    // address for H/W UNDI.
    PXE_UINT64 BufferAddr;

    // Length of receive buffer. This must be large enough to hold
    // the received frame (media header + data). If the length of
    // smaller than the received frame, data will be lost.
    PXE_UINT32 BufferLen;

    // Reserved, must be set to zero.
    PXE_UINT32 reserved;
} PXE_CPB_RECEIVE;
#pragma pack()
```
E.4.19.3 Waiting for the Command to Execute

Monitor the upper two bits (14 & 15) in the CDB.StatFlags field. Until these bits change to report PXE_STATFLAGS_COMMAND_COMPLETE or PXE_STATFLAGS_COMMAND_FAILED, the command has not been executed by the UNDI.

<table>
<thead>
<tr>
<th>StatFlags</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>COMMAND_COMPLETE</td>
<td>Command completed successfully. Frames received and DB is written.</td>
</tr>
<tr>
<td>COMMAND_QUEUED</td>
<td>Command has been queued.</td>
</tr>
<tr>
<td>INITIALIZE</td>
<td>Command has not been executed or queued.</td>
</tr>
</tbody>
</table>

E.4.19.4 Checking Command Execution Results

After command execution completes, either successfully or not, the CDB.StatCode field contains the result of the command execution.

<table>
<thead>
<tr>
<th>StatCode</th>
<th>Reason</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUCCESS</td>
<td>Command completed successfully. Frames received and DB is written.</td>
</tr>
<tr>
<td>INVALID_CDB</td>
<td>One of the CDB fields was not set correctly.</td>
</tr>
<tr>
<td>INVALID_CPB</td>
<td>One of the CPB fields was not set correctly.</td>
</tr>
<tr>
<td>BUSY</td>
<td>UNDI is already processing commands. Try again later.</td>
</tr>
<tr>
<td>QUEUE_FULL</td>
<td>Command queue is full. Wait for queued commands to complete. Try again later.</td>
</tr>
<tr>
<td>NO_DATA</td>
<td>Receive buffers are empty.</td>
</tr>
<tr>
<td>NOT_STARTED</td>
<td>The UNDI is not started.</td>
</tr>
<tr>
<td>NOT_INITIALIZED</td>
<td>The UNDI is not initialized.</td>
</tr>
</tbody>
</table>

E.4.19.5 Using the DB

If multiple frames per command are supported (see !PXE.Implementation flags), multiple DBs can be packed together.

```c
#pragma pack(1)
typedef struct s_pxe_db_receive {
    // Source and destination MAC addresses from media header.
    PXE_MAC_ADDR SrcAddr;
    PXE_MAC_ADDR DestAddr;

    // Length of received frame. May be larger than receive buffer size. The receive buffer will not be overwritten. This is how to tell if data was lost because the receive buffer was too small.
    PXE_UINT32 FrameLen;

    // Protocol type from media header.
    PXE_PROTOCOL Protocol;

    // Length of media header in received frame.
    PXE_UINT16 MediaHeaderLen;
}
```

(continues on next page)
// Type of receive frame.
PXE_FRAME_TYPE Type;

// Reserved, must be zero.
PXE_UINT8 reserved[7];
} PXE_DB_RECEIVE;
#pragma pack()
E.4.20.3 Issue #3 - PXE Vendor Options Existence

The PXE 2.1 specification is ambiguous about whether the following PXE Vendor Options need to be provided in DHCP messages. These options are marked as “Required” in Table 2-1 “PXE DHCP Options (Full List)”, but other parts of the specification state that these options may not be supplied in certain condition.

This section clarifies the existence of these PXE Vendor Options:

1. **PXE_DISCOVERY_CONTROL (Tag 6)**
   
   Where the PXE 2.1 specification reads:
   
   - Required, Note #3
   - If this tag is not supplied all bits assumed to be 0.

   The behavior should be clarified as:
   
   - This tag is not mandatory required. If not supplied, all bits are assumed to be 0.

2. **PXE_BOOT_SERVERS (Tag 8)**
   
   Where the PXE 2.1 specification reads:
   
   - Required for PXE client. Note #3
   - PXE_DISCOVERY_CONTROL (Tag 6), bit 2 = If set, only use/accept servers in PXE_BOOT_SERVERS.

   The behavior should be clarified as:
   
   - This tag is required only if bit 2 of PXE_DISCOVERY_CONTROL (Tag 6) is set.

3. **PXE_BOOT_MENU (Tag 9)**
   
   Where the PXE 2.1 specification reads:
   
   - Required, Note #4
   - Note #4: These options define the information, if any, displayed by the client during a network boot.

   The behavior should be clarified as:
   
   - This tag is required only if the PXE client wants to display boot menu information during a network boot.

4. **PXE_CREDENTIAL_TYPES (Tag 12)**
   
   Where the PXE 2.1 specification reads:
   
   - Required for security. Note #5
   - This option is required for security requests and acknowledges between the client and the server.

   The behavior should be clarified as:
   
   - This tag is not required if PXE client does not apply security requests.

5. **PXE_BOOT_ITEM (Tag 71)**
   
   Where the PXE 2.1 specification reads:
- Required. Note #6
- If this tag is missing, type 0 and layer 0 is assumed.**

The behavior should be clarified as:

- This tag is not mandatory required. If not supplied, type 0 and layer 0 is assumed.

6. **Vendor Options (Tag 43)**
   The PXE 2.1 specification is not clear whether this option is required.
   The behavior should be clarified as:

   - Vendor Options (Tag 43) is required only if encapsulated PXE options need be supplied.
The Simple Pointer Protocol is intended to provide a simple mechanism for an application to interact with the user with some type of pointer device. To keep this interface simple, many of the custom controls that are typically present in an OS-present environment were left out. This includes the ability to adjust the double-click speed and the ability to adjust the pointer speed. Instead, the recommendations for how the Simple Pointer Protocol should be used are listed here.

**X-Axis Movement:**
If the Simple Pointer Protocol is being used to move a pointer or cursor around on an output display, the movement along the x-axis should move the pointer or cursor horizontally.

**Y-Axis Movement:**
If the Simple Pointer Protocol is being used to move a pointer or cursor around on an output display, the movement along the y-axis should move the pointer or cursor vertically.

**Z-Axis Movement:**
If the Simple Pointer Protocol is being used to move a pointer or cursor around on an output display, and the application that is using the Simple Pointer Protocol supports scrolling, then the movement along the z-axis should scroll the output display.

**Double Click Speed:**
If two clicks of the same button on a pointer occur in less than 0.5 seconds, then a double-click event has occurred. If a the same button is pressed with more than 0.5 seconds between clicks, then this is interpreted as two single-click events.

**Pointer Speed:**
The Simple Pointer Protocol returns the movement of the pointer device along an axis in counts. The Simple Pointer Protocol also contains a set of resolution fields that define the number of counts that will be received for each millimeter of movement of the pointer device along an axis. From these two values, the consumer of this protocol can determine the distance the pointer device has been moved in millimeters along an axis. For most applications, movement of a pointer device will result in the movement of a pointer on the screen. For each millimeter of motion by the pointer device in the x-axis, the pointer on the screen will be moved 2 percent of the screen width. For each millimeter of motion by the pointer device in the y-axis, the pointer on the screen will be moved 2 percent of the screen height.
APPENDIX G — USING THE EFI EXTENDED SCSI PASS THRU PROTOCOL

This appendix describes how an EFI utility might gain access to the EFI SCSI Pass Thru interfaces. The basic concept is to use the `EFI_BOOT_SERVICES.LocateHandle()` boot service to retrieve the list of handles that support the `EFI_EXT_SCSI_PASS_THRU_PROTOCOL`. Each of these handles represents a different SCSI channel present in the system. Each of these handles can then be used to retrieve the `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` interface with the `EFI_BOOT_SERVICES.HandleProtocol()` boot service. The `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` interface provides the services required to access any of the SCSI devices attached to a SCSI channel. The services of the `EFI_EXT_SCSI_PASS_THRU_PROTOCOL` are then to loop through the Target IDs of all the SCSI devices on the SCSI channel.

```c
#include "efi.h"
#include "efilib.h"

#include EFI_PROTOCOL_DEFINITION(ExtScsiPassThru)

EFI_GUID gEfiExtScsiPassThruProtocolGuid =
    EFI_EXT_SCSI_PASS_THRU_PROTOCOL_GUID;

EFI_STATUS
UtilityEntryPoint(
    EFI_HANDLE ImageHandle,
    EFI_SYSTEM_TABLE SystemTable
)
{
    EFI_STATUS Status;
    UINTN NoHandles;
    EFI_HANDLE *HandleBuffer;
    UINTN Index;
    EFI_EXT_SCSI_PASS_THRU_PROTOCOL *ExtScsiPassThruProtocol;

    // Initialize EFI Library
    InitializeLib (ImageHandle, SystemTable);

    // Get list of handles that support the
    // EFI_EXT_SCSI_PASS_THRU_PROTOCOL
    NoHandles = 0;
    (continues on next page)
```
handlebuffer = NULL;
status = liblocatehandle(
    byprotocol,
    &gEfiExtScsiPassThruProtocolGuid,
    NULL,
    &nohandles,
    &handlebuffer
);
if ( EFI_ERROR ( status ) ) { 
    bs->exit ( imagehandle, EFI_SUCCESS, 0, NULL );
}
//
// loop through all the handles that support
// EFI_EXT_SCSI_PASS_THRU
//
for ( index = 0; index < nohandles; index++ ) { 

    //
    // get the EFI_EXT_SCSI_PASS_THRU_PROTOCOL interface
    // on each handle
    //
    bs->handleprotocol(
        handlebuffer [ index ],
        &gEfiExtScsiPassThruProtocolGuid,
        ( VOID ** ) &extscsiPassThruProtocol
    );
    if ( !EFI_ERROR ( status ) ) { 

        //
        // use the EFI_EXT_SCSI_PASS_THRU interface to
        // perform tests
        //
        status = doscstests ( scsiPassThruProtocol );
    }
}
return EFI_SUCCESS;
}

EFI_STATUS
DoScsiTests(
    EFI_EXT_SCSI_PASS_THRU_PROTOCOL *ExtScsiPassThruProtocol
)
{

    EFI_STATUS Status;
    UINT32 Target;
    UINT64 Lun;
    EFI_EXT_SCSI_PASS_THRU_SCSI_REQUEST_PACKET Packet;
    EFI_EVENT Event;
// Get first Target ID and LUN on the SCSI channel

Target = 0xffffffff;
Lun = 0;
Status = ExtScsiPassThruProtocol->GetNextTargetLun(
    ExtScsiPassThruProtocol,
    &Target,
    &Lun
);

// Loop through all the SCSI devices on the SCSI channel
//
while (!EFI_ERROR (Status)) {

    // Blocking I/O example.
    // Fill in Packet before calling PassThru()
    //
    Status = ExtScsiPassThruProtocol->PassThru(
        ExtScsiPassThruProtocol,
        Target,
        Lun,
        &Packet,
        NULL
    );

    // Non Blocking I/O
    // Fill in Packet and create Event before calling PassThru()
    //
    Status = ExtScsiPassThruProtocol->PassThru(
        ExtScsiPassThruProtocol,
        Target,
        Lun,
        &Packet,
        &Event
    );

    // Get next Target ID and LUN on the SCSI channel
    //
    Status = ExtScsiPassThruProtocol->GetNextTargetLun(
        ExtScsiPassThruProtocol,
        &Target,
        &Lun
    );
}

return EFI_SUCCESS;
APPENDIX H — COMPRESSION SOURCE CODE

/*++
Copyright (c) 2001-2002 Intel Corporation
Module Name:
Compress.c
Abstract:
Compression routine. The compression algorithm is a mixture of LZ77
and Huffman Coding. LZ77 transforms the source data into a sequence
of Original Characters and Pointers to repeated strings. This sequence
is further divided into Blocks and Huffman codings are applied to each Block.
Revision History:
--*/

#include <string.h>
#include <stdlib.h>
#include "eficommon.h"

// // Macro Definitions //

typedef INT16 NODE;
#define UINT8_MAX 0xff
#define UINT8_BIT 8
#define THRESHOLD 3
#define INIT_CRC 0
#define WNDBIT 13
#define WNDSIZ (1U << WNDBIT)
#define MAXMATCH 256
#define PERC_FLAG 0x8000U
#define CODE_BIT 16
#define NIL 0
#define MAX_HASH_VAL (3 * WNDSIZ + (WNDSIZ / 512 + 1) * UINT8_MAX)
#define HASH(p, c) ((p) + ((c) << (WNDBIT - 9)) + WNDSIZ * 2)
#define CRCPOLY 0xA001

(continues on next page)
#define UPDATE_CRC(c) mCrc = mCrcTable[(mCrc ^ (c)) & 0xFF] ^ (mCrc >> UINT8_BIT)

//
// C: the CharLen Set; P: the Position Set; T: the exTra Set
//
#define NC (UINT8_MAX + MAXMATCH + 2 - THRESHOLD)
#define CBIT 9
#define NP (WNDBIT + 1)
#define PRIT 4
#define NT (CODE_BIT + 3)
#define TBIT 5
#if NT > NP
  #define NPT NT
#else
  #define NPT NP
#endif

// Function Prototypes
//
STATIC
VOID
PutDword(
    IN UINT32 Data
);

STATIC
EFI_STATUS
AllocateMemory (  
);

STATIC
VOID
FreeMemory (  
);

STATIC
VOID
InitSlide (  
);

STATIC
NODE
Child (  
    IN NODE q,  
    IN UINT8 c
  )
;

STATIC
VOID
MakeChild (;
    IN NODE q,
    IN UINT8 c,
    IN NODE r
);

STATIC
VOID
Split (;
    IN NODE Old
);

STATIC
VOID
InsertNode (;
    );

STATIC
VOID
DeleteNode (;
    );

STATIC
VOID
GetNextMatch (;
    );

STATIC
EFI_STATUS
Encode (;
    );

STATIC
VOID
CountTFreq (;
    );

STATIC
VOID
WritePTLen (;
    IN INT32 n,
    IN INT32 nbit,
    IN INT32 Special
    );

STATIC
VOID
WriteCLen (;
    );

STATIC
VOID
  EncodeC (  
    IN INT32 c
  );

STATIC
VOID
  EncodeP (  
    IN UINT32 p
  );

STATIC
VOID
  SendBlock (  
  );

STATIC
VOID
  Output (  
    IN UINT32 c,  
    IN UINT32 p
  );

STATIC
VOID
  HufEncodeStart (  
  );

STATIC
VOID
  HufEncodeEnd (  
  );

STATIC
VOID
  MakeCrcTable (  
  );

STATIC
VOID
  PutBits (  
    IN INT32 n,  
    IN UINT32 x
  );

STATIC
INT32
  FreadCrc (  
    OUT UINT8 *p,  
    IN INT32 n
  );
STATIC VOID InitPutBits(
);

STATIC VOID CountLen(
    IN INT32 i
);

STATIC VOID MakeLen(
    IN INT32 Root
);

STATIC VOID DownHeap(
    IN INT32 i
);

STATIC VOID MakeCode(
    IN INT32 n,
    IN UINT8 Len[],
    OUT UINT16 Code[]
);

STATIC INT32 MakeTree(
    IN INT32 NParm,
    IN UINT16 FreqParm[],
    OUT UINT8 LenParm[],
    OUT UINT16 CodeParm[]
);

// // Global Variables //

STATIC UINT8 *mSrc, *mDst, *mSrcUpperLimit, *mDstUpperLimit;

STATIC UINT8 *mLevel, *mText, *mChildCount, *mBuf, mClen[NC], mPTlen[NPT], *mLen;
STATIC INT16 mHeap[NC + 1];
STATIC INT32 mRemainder, mMatchLen, mBitCount, mHeapSize, mN;
STATIC UINT32 mBufSiz = 0, moutputPos, moutputMask, mSubBitBuf, mCrc;
STATIC UINT32 mCompSize, mOrigSize;

(continues on next page)
STATIC UINT16 *mFreq, *mSortPtr, mLenCnt[17], mLeft[2 * NC - 1], mRight[2 * NC - 1],
mCrcTable[UINT8_MAX + 1], mCFreq[2 * NC - 1], mCTable[4096], mCode[NC],
mpFreq[2 * NP - 1], mPCode[NPT], mTFreq[2 * NT - 1];

STATIC NODE mPos, mMatchPos, mAvail, *mPosition, *mParent, *mPrev, *mNext = NULL;

//
// functions
//

EFI_STATUS
Compress ( IN UINT8 *SrcBuffer,
IN UINT32 SrcSize,
IN UINT8 *DstBuffer,
IN OUT UINT32 *DstSize )

/*++

Routine Description:

The main compression routine.

Arguments:

SrcBuffer - The buffer storing the source data
SrcSize - The size of the source data
DstBuffer - The buffer to store the compressed data
DstSize - On input, the size of DstBuffer; On output,
          the size of the actual compressed data.

Returns:

 EFI_BUFFER_TOO_SMALL - The DstBuffer is too small. In this case,
                        DstSize contains the size needed.
 EFI_SUCCESS - Compression is successful.

--*/
{
   EFI_STATUS Status = EFI_SUCCESS;

   //
   // Initializations
   //

   mBufSiz = 0;
   mBuf = NULL;
   mText = NULL;
   mLevel = NULL;
   mChildCount = NULL;
}
mPosition = NULL;
mParent = NULL;
mPrev = NULL;
mNext = NULL;

mSrc = SrcBuffer;
mSrcUpperLimit = mSrc + SrcSize;

mDst = DstBuffer;
mDstUpperLimit = mDst + *DstSize;

PutDword(0L);
PutDword(0L);

MakeCrcTable();

mOrigSize = mCompSize = 0;
mCrc = INIT_CRC;

//
// Compress it
//

Status = Encode();
if (EFI_ERROR (Status)) {
    return EFI_OUT_OF_RESOURCES;
}

//
// Null terminate the compressed data
//
if (mDst < mDstUpperLimit) {
    *mDst++ = 0;
}

//
// Fill in compressed size and original size
//
if (mCompSize + 1 + 8 > *DstSize) {
    *DstSize = mCompSize + 1 + 8;
    return EFI_BUFFER_TOO_SMALL;
} else {
    *DstSize = mCompSize + 1 + 8;
    return EFI_SUCCESS;
}
STATIC VOID
PutDword( 
    IN UINT32 Data 
 )
/*++

Routine Description:

Put a dword to output stream

Arguments:

Data - the dword to put

Returns: (VOID)

--*/
{
    if (mDst < mDstUpperLimit) {
        *mDst++ = (UINT8)(((UINT8)(Data)) & 0xff);
    }

    if (mDst < mDstUpperLimit) {
        *mDst++ = (UINT8)(((UINT8)(Data >> 0x08)) & 0xff);
    }

    if (mDst < mDstUpperLimit) {
        *mDst++ = (UINT8)(((UINT8)(Data >> 0x10)) & 0xff);
    }

    if (mDst < mDstUpperLimit) {
        *mDst++ = (UINT8)(((UINT8)(Data >> 0x18)) & 0xff);
    }
}

STATIC EFI_STATUS
AllocateMemory ()
/*++

Routine Description:

Allocate memory spaces for data structures used in compression process

Arguments: (VOID)

Returns:

(continues on next page)
EFI_SUCCESS - Memory is allocated successfully
EFI_OUT_OF_RESOURCES - Allocation fails

--*/
{
  UINT32 i;

  mText = malloc (WNDSIZ * 2 + MAXMATCH);
  for (i = 0; i < WNDSIZ * 2 + MAXMATCH; i++) {
    mText[i] = 0;
  }
  mLevel = malloc ((WNDSIZ + UINT8_MAX + 1) * sizeof(*mLevel));
  mChildCount = malloc ((WNDSIZ + UINT8_MAX + 1) * sizeof(*mChildCount));
  mPosition = malloc ((WNDSIZ + UINT8_MAX + 1) * sizeof(*mPosition));
  mParent = malloc (WNDSIZ * 2 * sizeof(*mParent));
  mPrev = malloc (WNDSIZ * 2 * sizeof(*mPrev));
  mNext = malloc ((MAX_HASH_VAL + 1) * sizeof(*mNext));

  mBufSiz = 16 * 1024U;
  while ((mBuf = malloc(mBufSiz)) == NULL) {
    mBufSiz = (mBufSiz / 10U) * 9U;
    if (mBufSiz < 4 * 1024U) {
      return EFI_OUT_OF_RESOURCES;
    }
  }
  mBuf[0] = 0;
  return EFI_SUCCESS;
}

VOID
FreeMemory ()
/*++

Routine Description:

Called when compression is completed to free memory previously allocated.

Arguments: (VOID)

Returns: (VOID)
--*/
{
  if (mText) {
    free (mText);
  }

  if (mLevel) {
    free (mLevel);
  }

(continues on next page)
if (mChildCount) {
    free (mChildCount);
}

if (mPosition) {
    free (mPosition);
}

if (mParent) {
    free (mParent);
}

if (mPrev) {
    free (mPrev);
}

if (mNext) {
    free (mNext);
}

if (mBuf) {
    free (mBuf);
}

return;
}

STATIC VOID

InitSlide ()

/\*++

Routine Description:

Initialize String Info Log data structures

Arguments: (VOID)

Returns: (VOID)

--*/
{
    NODE i;

    for (i = WNDSIZ; i <= WNDSIZ + UINT8_MAX; i++) {
        mLLevel[i] = 1;
        mPosition[i] = NIL; /* sentinel */
    }

    for (i = WNDSIZ; i < WNDSIZ * 2; i++) {
        mParent[i] = NIL;
    }

    (continues on next page)
mAvail = 1;
for (i = 1; i < WNDSIZ - 1; i++) {
    mNext[i] = (NODE)(i + 1);
}

mNext[WNDSIZ - 1] = NIL;
for (i = WNDSIZ * 2; i <= MAX_HASH_VAL; i++) {
    mNext[i] = NIL;
}

STATIC
NODE
Child (IN NODE q, IN UINT8 c)
/**<*
Routine Description:
Find child node given the parent node and the edge character
Arguments:
q - the parent node
c - the edge character
Returns:
The child node (NIL if not found)
/**<*/
{
    NODE r;

    r = mNext[HASH(q, c)];
    mParent[NIL] = q; /* sentinel */
    while (mParent[r] != q) {
        r = mNext[r];
    }

    return r;
}

STATIC
VOID
MakeChild (IN NODE q, IN UINT8 c, IN NODE r)
(continues on next page)
Routine Description:

Create a new child for a given parent node.

Arguments:

q - the parent node
c - the edge character
r - the child node

Returns: (VOID)

/***/
{
    NODE h, t;

    h = (NODE)HASH(q, c);
    t = mNext[h];
    mNext[h] = r;
    mNext[r] = t;
    mPrev[t] = r;
    mPrev[r] = h;
    mParent[r] = q;
    mChildCount[q]++;
}

STATIC
VOID
Split (NODE Old)
/***/

Routine Description:

Split a node.

Arguments:

Old - the node to split

Returns: (VOID)

/***/
{
    NODE New, t;

    New = mAvail;
    mAvail = mNext[New];
    mChildCount[New] = 0;
t = mPrev[Old];
mPrev[New] = t;
mNext[t] = New;
t = mNext[Old];
mNext[New] = t;
mPrev[t] = New;
mParent[New] = mParent[Old];
mLevel[New] = (UINT8)mMatchLen;
mPosition[New] = mPos;
MakeChild(New, mText[mMatchPos + mMatchLen], Old);
MakeChild(New, mText[mPos + mMatchLen], mPos);
}

STATIC
VOID
InsertNode ()
/*++
Routine Description:

Insert string info for current position into the String Info Log
Arguments: (VOID)
Returns: (VOID)
--*/
{
    NODE q, r, j, t;
    UINT8 c, *t1, *t2;

    if (mMatchLen >= 4) {

        // We have just got a long match, the target tree
        // can be located by MatchPos + 1. Traverse the tree
        // from bottom up to get to a proper starting point.
        // The usage of PERC_FLAG ensures proper node deletion
        // in DeleteNode() later.
        //

        mMatchLen--;
        r = (INT16)((mMatchPos + 1) \ WNDSIZ);
        while ((q = mParent[r]) == NIL) {
            r = mNext[r];
        }
        while (mLevel[q] >= mMatchLen) {
            r = q; q = mParent[q];
        }
        t = q;
        while (mPosition[t] < 0) {
            mPosition[t] = mPos;
    }
}
t = mParent[t];
}
if (t < WNDSIZ) {
    mPosition[t] = (NODE)(mPos | PERC_FLAG);
}
else {

    // Locate the target tree
    //
    q = (INT16)(mText[mPos] + WNDSIZ);
    c = mText[mPos + 1];
    if ((r = Child(q, c)) == NIL) {
        MakeChild(q, c, mPos);
        mMatchLen = 1;
        return;
    }
    mMatchLen = 2;
}

    // Traverse down the tree to find a match.
    // Update Position value along the route.
    // Node split or creation is involved.
    //
    for (; ; ) {
        if (r >= WNDSIZ) {
            j = MAXMATCH;
            mMatchPos = r;
        } else {
            j = mLevel[r];
            mMatchPos = (NODE)(mPosition[r] & ~PERC_FLAG);
        }
        if (mMatchPos >= mPos) {
            mMatchPos -= WNDSIZ;
        }
        t1 = &mText[mPos + mMatchLen];
        t2 = &mText[mMatchPos + mMatchLen];
        while (mMatchLen < j) {
            if (*t1 != *t2) {
                Split(r);
                return;
            }
            mMatchLen++;
            t1++;
            t2++;
        }
        if (mMatchLen >= MAXMATCH) {
            break;
        }
    }
mPosition[r] = mPos;
q = r;
if ((r = Child(q, *t1)) == NIL) {
    MakeChild(q, *t1, mPos);
    return;
}
mMatchLen++;
} 

\[
\begin{align*}
&\text{t = mPrev[r];} \\
&\text{mPrev[mPos] = t;} \\
&\text{mNext[t] = mPos;} \\
&\text{t = mNext[r];} \\
&\text{mNext[mPos] = t;} \\
&\text{mPrev[t] = mPos;} \\
&\text{mParent[mPos] = q;} \\
&\text{mParent[r] = NIL;}
\end{align*}
\]

// Special usage of 'next'
// mNext[r] = mPos;

STATIC VOID DeleteNode ()
/**+
Routine Description:
Delete outdated string info. (The Usage of PERC_FLAG ensures a clean deletion)
Arguments: (VOID)
Returns: (VOID)
--*/
{
    NODE q, r, s, t, u;
    if (mParent[mPos] == NIL) {
        return;
    }
    r = mPrev[mPos];
    s = mNext[mPos];
    mNext[r] = s;
    mPrev[s] = r;
    r = mParent[mPos];
    mParent[mPos] = NIL;
}
if (r >= WNDSIZ || --mChildCount[r] > 1) {
    return;
}

t = (NODE)(mPosition[r] & ~PERC_FLAG);
if (t >= mPos) {
    t -= WNDSIZ;
}

s = t;
q = mParent[r];
while ((u = mPosition[q]) & PERC_FLAG) {
    u &= ~PERC_FLAG;
    if (u >= mPos) {
        u -= WNDSIZ;
    }
    if (u > s) {
        s = u;
    }
    mPosition[q] = (INT16)(s \ WNDSIZ);
    q = mParent[q];
}
if (q < WNDSIZ) {
    if (u >= mPos) {
        u -= WNDSIZ;
    }
    if (u > s) {
        s = u;
    }
    mPosition[q] = (INT16)(s \ WNDSIZ \| PERC_FLAG);
}

s = Child(r, mText[t + mLevel[r]]);
t = mPrev[s];
u = mNext[s];
mNext[t] = u;
mPrev[u] = t;
t = mPrev[r];
mNext[t] = s;
mPrev[s] = t;
t = mNext[r];
mPrev[t] = s;
mNext[s] = t;
mParent[s] = mParent[r];
mParent[r] = NIL;
mNext[r] = mAvail;
mAvail = r;
}

STATIC
VOID
GetNextMatch ()
/
++

Routine Description:
Advance the current position (read in new data if needed).
Delete outdated string info. Find a match string for current position.

Arguments: (VOID)

Returns: (VOID)

```c
{ /*-*/
  INT32 n;
  mRemainder--;
  if (++mPos == WNDSIZ * 2) {
    memmove(&mText[0], &mText[WNDSIZ], WNDSIZ + MAXMATCH);
    n = FreadCrc(&mText[WNDSIZ + MAXMATCH], WNDSIZ);
    mRemainder += n;
    mPos = WNDSIZ;
  }
  DeleteNode();
  InsertNode();
}

STATIC EFI_STATUS Encode ()
/*++
Routine Description:

The main controlling routine for compression process.

Arguments: (VOID)

Returns:

  EFI_SUCCESS - The compression is successful
  EFI_OUT_OF_RESOURCES - Not enough memory for compression process

-*/
{
  EFI_STATUS Status;
  INT32 LastMatchLen;
  NODE LastMatchPos;

  Status = AllocateMemory();
  if (EFI_ERROR(Status)) {
    FreeMemory();
    return Status;
  }

  InitSlide();
```
HufEncodeStart();

mRemainder = FreadCrc(&mText[WNDSIZ], WNDSIZ + MAXMATCH);

mMatchLen = 0;
mPos = WNDSIZ;
InsertNode();
if (mMatchLen > mRemainder) {
    mMatchLen = mRemainder;
}
while (mRemainder > 0) {
    LastMatchLen = mMatchLen;
    LastMatchPos = mMatchPos;
    GetNextMatch();
    if (mMatchLen > mRemainder) {
        mMatchLen = mRemainder;
    }
    if (mMatchLen > LastMatchLen \||| LastMatchLen < THRESHOLD) {
        //
        // Not enough benefits are gained by outputting a pointer,
        // so just output the original character
        //
        Output(mText[mPos - 1], 0);
    } else {
        //
        // Outputting a pointer is beneficial enough, do it.
        //
        Output(LastMatchLen + (UINT8_MAX + 1 - THRESHOLD),
               (mPos - LastMatchPos - 2) & (WNDSIZ - 1));
        while (--LastMatchLen > 0) {
            GetNextMatch();
        }
        if (mMatchLen > mRemainder) {
            mMatchLen = mRemainder;
        }
    }
}

HufEncodeEnd();
FreeMemory();
return EFI_SUCCESS;
}

STATIC
VOID
CountTFreq ()
/**+

Routine Description:

Count the frequencies for the Extra Set

Arguments: (VOID)

Returns: (VOID)

/*--*/
{
    INT32 i, k, n, Count;

    for (i = 0; i < NT; i++) {
        mTFreq[i] = 0;
    }
    n = NC;
    while (n > 0 && mCLen[n - 1] == 0) {
        n--;
    }
    i = 0;
    while (i < n) {
        k = mCLen[i++];
        if (k == 0) {
            Count = 1;
            while (i < n && mCLen[i] == 0) {
                i++;
                Count++;
            }
        } else if (Count <= 2) {
            mTFreq[0] = (UINT16)(mTFreq[0] + Count);
        } else if (Count <= 18) {
            mTFreq[1]++;
        } else if (Count == 19) {
            mTFreq[0]++;
            mTFreq[1]++;
        } else {
            mTFreq[2]++;
        }
        mTFreq[k + 2]++;
    }
}

STATIC
VOID
WritePTLen (IN INT32 n, IN INT32 nbit, IN INT32 Special

(continues on next page)
Routine Description:

Outputs the code length array for the Extra Set or the Position Set.

Arguments:

n - the number of symbols
nbit - the number of bits needed to represent 'n'
Special - the special symbol that needs to be take care of

Returns: (VOID)

---*/
{
    INT32 i, k;

    while (n > 0 && mPTLen[n - 1] == 0) {
        n--;
    }
    PutBits(nbit, n);
    i = 0;
    while (i < n) {
        k = mPTLen[i++];
        if (k <= 6) {
            PutBits(3, k);
        } else {
            PutBits(k - 3, (1U << (k - 3)) - 2);
        }
        if (i == Special) {
            while (i < 6 && mPTLen[i] == 0) {
                i++;
            }
            PutBits(2, (i - 3) & 3);
        }
    }
}

STATIC VOID WriteCLen ()
    /*++

Routine Description:

Outputs the code length array for Char&Length Set

Arguments: (VOID)

Returns: (VOID)
```c
/*
{  
  INT32 i, k, n, Count;

  n = NC;
  while (n > 0 && mCLen[n - 1] == 0) {
    n--;
  }
  PutBits(CBIT, n);
  i = 0;
  while (i < n) {
    k = mCLen[i++];
    if (k == 0) {
      Count = 1;
      while (i < n && mCLen[i] == 0) {
        i++;
        Count++;
      }
      if (Count <= 2) {
        for (k = 0; k < Count; k++) {
          PutBits(mPTLen[0], mPTCode[0]);
        }
      } else if (Count <= 18) {
        PutBits(mPTLen[1], mPTCode[1]);
        PutBits(4, Count - 3);
      } else if (Count == 19) {
        PutBits(mPTLen[0], mPTCode[0]);
        PutBits(mPTLen[1], mPTCode[1]);
        PutBits(4, 15);
      } else {
        PutBits(mPTLen[2], mPTCode[2]);
        PutBits(CBIT, Count - 20);
      }
    } else {
      PutBits(mPTLen[k + 2], mPTCode[k + 2]);
    }
  }
}

STATIC
VOID
EncodeC (  
  IN INT32 c
)
{
  PutBits(mCLen[c], mCCode[c]);
}

STATIC
VOID
EncodeP (  
```
IN UINT32 p
{
    UINT32 c, q;
    c = 0;
    q = p;
    while (q) {
        q >>= 1;
        c++;
    }
    PutBits(mPTLen[c], mPTCode[c]);
    if (c > 1) {
        PutBits(c - 1, p & (0xFFFFU >> (17 - c)));
    }
}

STATIC
VOID
SendBlock ()
/*++
Routine Description:

Huffman code the block and output it.

Argument: (VOID)

Returns: (VOID)

--*/
{
    UINT32 i, k, Flags, Root, Pos, Size;
    Flags = 0;
    Root = MakeTree(NC, mCFreq, mCLen, mCCode);
    Size = mCFreq[Root];
    PutBits(16, Size);
    if (Root >= NC) {
        CountTFreq();
        Root = MakeTree(NT, mTFreq, mPTLen, mPTCode);
        if (Root >= NT) {
            WritePTLen(NT, TBIT, 3);
        } else {
            PutBits(TBIT, 0);
            PutBits(TBIT, Root);
        }
        WriteCLen();
    } else {
        PutBits(TBIT, 0);
        PutBits(TBIT, 0);
    }
PutBits(CBIT, 0);
PutBits(CBIT, Root);
}
Root = MakeTree(NP, mPFreq, mPTLen, mPTCode);
if (Root >= NP) {
    WritePTLen(NP, PBIT, -1);
} else {
    PutBits(PBIT, 0);
    PutBits(PBIT, Root);
}
Pos = 0;
for (i = 0; i < Size; i++) {
    if (i % UINT8_BIT == 0) {
        Flags = mBuf[Pos++];
    } else {
        Flags <<= 1;
    }
    if (Flags & (1U << (UINT8_BIT - 1))) {
        EncodeC(mBuf[Pos++] + (1U << UINT8_BIT));
        k = mBuf[Pos++] << UINT8_BIT;
        k += mBuf[Pos++];
        EncodeP(k);
    } else {
        EncodeC(mBuf[Pos++]);
    }
}
for (i = 0; i < NC; i++) {
    mCFreq[i] = 0;
}
for (i = 0; i < NP; i++) {
    mPFreq[i] = 0;
}
}

STATIC
VOID
Output (IN UINT32 c, IN UINT32 p)

/*++
Routine Description:

Outputs an Original Character or a Pointer

Arguments:

c - The original character or the 'String Length' element of a Pointer
p - The 'Position' field of a Pointer

Returns: (VOID)

(continues on next page)
/*

{STATIC UINT32 CPos;

if ((mOutputMask >>= 1) == 0) {
    mOutputMask = 1U << (UINT8_BIT - 1);
    if (mOutputPos >= mBufSiz - 3 * UINT8_BIT) {
        SendBlock();
        mOutputPos = 0;
    }
    CPos = mOutputPos++;
    mBuf[CPos] = 0;
}

mBuf[mOutputPos++] = (UINT8) c;
mcFreq[c]++;
if (c >= (1U << UINT8_BIT)) {
    mBuf[CPos] |= mOutputMask;
    mBuf[mOutputPos++] = (UINT8)(p >> UINT8_BIT);
    mBuf[mOutputPos++] = (UINT8) p;
    c = 0;
    while (p) {
        p >>= 1;
        c++;
    }
    mPFreq[c]++;
}
}

STATIC VOID HufEncodeStart ()
{
    INT32 i;

    for (i = 0; i < NC; i++) {
        mCFreq[i] = 0;
    }
    for (i = 0; i < NP; i++) {
        mPFreq[i] = 0;
    }
    mOutputPos = mOutputMask = 0;
    InitPutBits();
    return;
}

STATIC VOID HufEncodeEnd ()
{
    SendBlock();
}
// Flush remaining bits
//
PutBits(UINT8_BIT - 1, 0);
return;
}

STATIC
VOID
MakeCrcTable()
{
UINT32 i, j, r;

for (i = 0; i <= UINT8_MAX; i++) {
    r = i;
    for (j = 0; j < UINT8_BIT; j++) {
        if (r & 1) {
            r = (r >> 1) ^ CRCPOLY;
        } else {
            r >>= 1;
        }
    }
    mCrcTable[i] = (UINT16)r;
}
}

STATIC
VOID
PutBits(
    IN INT32 n,
    IN UINT32 x
)
/*++
Routine Description:

Outputs rightmost n bits of x

Arguments:

n - the rightmost n bits of the data is used
x - the data

Returns: (VOID)

/*--*/
{
    UINT8 Temp;
    if (n < mBitCount) {
        mSubBitBuf |= x << (mBitCount - n);
} else {

    Temp = (UINT8)(mSubBitBuf | (x >> (n -= mBitCount)));
    if (mDst < mDstUpperLimit) {
        *mDst++ = Temp;
    }
    mCompSize++;

    if (n < UINT8_BIT) {
        mSubBitBuf = x << (mBitCount = UINT8_BIT - n);
    } else {

        Temp = (UINT8)x >> (n - UINT8_BIT);
        if (mDst < mDstUpperLimit) {
            *mDst++ = Temp;
        }
        mCompSize++;

        mSubBitBuf = x << (mBitCount = 2 * UINT8_BIT - n);
    }
    }
}

STATIC
INT32
FreadCrc(
    OUT UINT8 *p,
    IN INT32 n
)
/*++

Routine Description:

Read in source data

Arguments:

p - the buffer to hold the data
n - number of bytes to read

Returns:

number of bytes actually read

--*/
{
    INT32 i;

    for (i = 0; mSrc < mSrcUpperLimit && i < n; i++) {
        *p++ = mSrc++;
    }
    n = i;
p -= n;
mOrigSize += n;
while (--i >= 0) {
    UPDATE_CRC(*p++);
}
return n;
}

STATIC
VOID
InitPutBits ()
{
    mBitCount = UINT8_BIT;
mSubBitBuf = 0;
}

STATIC
VOID
CountLen (IN INT32 i)
    /*++
Routine Description:
Count the number of each code length for a Huffman tree.
Arguments:
i - the top node
Returns: (VOID)
--*/
{
    STATIC INT32 Depth = 0;
    if (i < mN) {
        mLenCnt[(Depth < 16) ? Depth : 16]++;
    } else {
        Depth++;
        CountLen(mLeft [i]);
        CountLen(mRight[i]);
        Depth--;
    }
}

STATIC
VOID
MakeLen (IN INT32 Root
Routine Description:

Create code length array for a Huffman tree

Arguments:

Root - the root of the tree

----------

{  
  INT32 i, k;
  UINT32 Cum;
  
  for (i = 0; i <= 16; i++) {
    mLenCnt[i] = 0;
  }
  CountLen(Root);

  //  
  // Adjust the length count array so that  
  // no code will be generated longer than the designated length  
  //  
  Cum = 0;
  for (i = 16; i > 0; i--) {
    Cum += mLenCnt[i] << (16 - i);
  }
  while (Cum != (1U << 16)) {
    mLenCnt[16]--;
    for (i = 15; i > 0; i--) {
      if (mLenCnt[i] != 0) {
        mLenCnt[i]--;
        mLenCnt[i+1] += 2;
        break;
      }
    }
    Cum--;
  }
  for (i = 16; i > 0; i--) {
    k = mLenCnt[i];
    while (--k >= 0) {
      mLen[*mSortPtr++] = (UINT8)i;
    }
  }
}

STATIC
VOID
DownHeap ( 
  IN INT32 i
)
\begin{verbatim}
{  INT32 j, k;

  // priority queue: send i-th entry down heap
  //

  k = mHeap[i];
  while ((j = 2 * i) <= mHeapSize) {
    if (j < mHeapSize && mFreq[mHeap[j]] > mFreq[mHeap[j + 1]]) {
      j++;
    }
    if (mFreq[k] <= mFreq[mHeap[j]]) {
      break;
    }
    mHeap[i] = mHeap[j];
    i = j;
  }
  mHeap[i] = (INT16)k;
}

STATIC VOID
MakeCode (IN INT32 n,
  IN UINT8 Len[],
  OUT UINT16 Code[])
/*++
Routine Description:

Assign code to each symbol based on the code length array

Arguments:

  n - number of symbols
  Len - the code length array
  Code - stores codes for each symbol

Returns: (VOID)
--*/
{
  INT32 i;
  UINT16 Start[18];

  Start[1] = 0;
  for (i = 1; i <= 16; i++) {
    Start[i + 1] = (UINT16)((Start[i] + mLenCnt[i]) << 1);
  }
}
\end{verbatim}
for (i = 0; i < n; i++) {
    Code[i] = Start[Len[i]]++;
}

}  

}  

/*++
Routine Description:
Generates Huffman codes given a frequency distribution of symbols

Arguments:
NParm - number of symbols
FreqParm - frequency of each symbol
LenParm - code length for each symbol
CodeParm - code for each symbol

Returns:
Root of the Huffman tree.

-*/
{
    INT32 i, j, k, Avail;

    // make tree, calculate len[], return root
    //
    mN = NParm;
    mFreq = FreqParm;
    mLen = LenParm;
    Avail = mN;
    mHeapSize = 0;
    mHeap[1] = 0;
    for (i = 0; i < mN; i++) {
        mLen[i] = 0;
        if (mFreq[i]) {
            mHeap[++mHeapSize] = (INT16)i;
        }
    }
    if (mHeapSize < 2) {
        CodeParm[mHeap[1]] = 0;
    }
return mHeap[1];

} for (i = mHeapSize / 2; i >= 1; i--) {

  //
  // make priority queue
  //
  DownHeap(i);
}
mSortPtr = CodeParm;
do {
i = mHeap[1];
  if (i < mN) {
    *mSortPtr++ = (UINT16)i;
  }
mHeap[1] = mHeap[mHeapSize--];
DownHeap(1);
j = mHeap[1];
  if (j < mN) {
    *mSortPtr++ = (UINT16)j;
  }
k = Avail++;
mFreq[k] = (UINT16)(mFreq[i] + mFreq[j]);
mHeap[1] = (INT16)k;
DownHeap(1);
mLeft[k] = (UINT16)i;
mRight[k] = (UINT16)j;
} while (mHeapSize > 1);

mSortPtr = CodeParm;
MakeLen(k);
MakeCode(NParm, LenParm, CodeParm);

//
// return root
//
return k;
}
APPENDIX I — DECOMPRESSION SOURCE CODE

/*++
Copyright (c) 2001-2002 Intel Corporation

Module Name:

Decompress.c

Abstract:

Decompressor.

--*/

#include "EfiCommon.h"

#define BITBUFSIZ 16
#define WNDBIT 13
#define WNDSZ (1U << WNDBIT)
#define MAXMATCH 256
#define THRESHOLD 3
#define CODE_BIT 16
#define UINT8_MAX 0xff
#define BAD_TABLE -1

//
// C: Char&Len Set; P: Position Set; T: exTra Set
//
#define NC (0xff + MAXMATCH + 2 - THRESHOLD)
#define CBIT 9
#define NP (WNDBIT + 1)
#define NT (CODE_BIT + 3)
#define PBIT 4
#define TBIT 5
#if NT > NP
    #define NPT NT
#else
    #define NPT NP
#endif

(continues on next page)
typedef struct {
    UINT8 *mSrcBase; //Starting address of compressed data
    UINT8 *mDstBase; //Starting address of decompressed data
    UINT16 mBytesRemain;
    UINT16 mBitCount;
    UINT16 mBitBuf;
    UINT16 mSubBitBuf;
    UINT16 mBufSiz;
    UINT16 mBlockSize;
    UINT32 mDataIdx;
    UINT32 mCompSize;
    UINT32 mOrigSize;
    UINT32 mOutBuf;
    UINT32 mInBuf;
    UINT16 mBadTableFlag;
    UINT8 mBuffer[WNDsz];
    UINT16 mLeft[2 * NC - 1];
    UINT16 mRight[2 * NC - 1];
    UINT32 mBuf;
    UINT8 mClen[NC];
    UINT8 mPTLlen[NPT];
    UINT16 mCTable[4096];
    UINT16 mPTTable[256];
} SCRATCH_DATA;

//
// Function Prototypes
//

STATIC VOID FillBuf ( IN SCRATCH_DATA *Sd, IN UINT16 NumOfBits );

STATIC VOID Decode ( SCRATCH_DATA *Sd, UINT16 NumOfBytes );

//
// Functions
//

EFI_STATUS

EFIAPI
GetInfo(
    IN EFI_DECOMPRESS_PROTOCOL *This,
    IN VOID *Source,
    IN UINT32 SrcSize,
    OUT UINT32 *DstSize,
    OUT UINT32 *ScratchSize
)
/*++
Routine Description:

The implementation of EFI_DECOMPRESS_PROTOCOL.GetInfo().

Arguments:

This - Protocol instance pointer.
Source - The source buffer containing the compressed data.
SrcSize - The size of source buffer
DstSize - The size of destination buffer.
ScratchSize - The size of scratch buffer.

Returns:

EFI_SUCCESS - The size of destination buffer and the size of scratch
buffer are successful retrieved.
EFI_INVALID_PARAMETER - The source data is corrupted

--*/
{
    UINT8 *Src;

    *ScratchSize = sizeof (SCRATCH_DATA);

    Src = Source;
    if (SrcSize < 8) {
        return EFI_INVALID_PARAMETER;
    }

    return EFI_SUCCESS;
}

EFI_STATUS
EFIAPI
Decompress(
    IN EFI_DECOMPRESS_PROTOCOL *This,
    IN VOID *Source,
    IN UINT32 SrcSize,
    IN OUT VOID *Destination,
    IN UINT32 DstSize,
    IN OUT VOID *Scratch,
IN UINT32 ScratchSize
}
/*++
Routine Description:
The implementation of EFI_DECOMPRESS_PROTOCOL.Decompress().
Arguments:
This - The protocol instance.
Source - The source buffer containing the compressed data.
SrcSize - The size of the source buffer
Destination - The destination buffer to store the decompressed data
DstSize - The size of the destination buffer.
Scratch - The buffer used internally by the decompress routine. This
buffer is needed to store intermediate data.
ScratchSize - The size of scratch buffer.

Returns:
EFI_SUCCESS - Decompression is successful
EFI_INVALID_PARAMETER - The source data is corrupted
--*/
{
    UINT32 Index;
    UINT16 Count;
    UINT32 CompSize;
    UINT32 OrigSize;
    UINT8 *Dst1;
    EFI_STATUS Status;
    SCRATCH_DATA *Sd;
    UINT8 *Src;
    UINT8 *Dst;

    Status = EFI_SUCCESS;
    Src = Source;
    Dst = Destination;
    Dst1 = Dst;

    if (ScratchSize < sizeof (SCRATCH_DATA)) {
        return EFI_INVALID_PARAMETER;
    }

    Sd = (SCRATCH_DATA *)Scratch;

    if (SrcSize < 8) {
        return EFI_INVALID_PARAMETER;
    }


if (SrcSize < CompSize + 8) {
    return EFI_INVALID_PARAMETER;
}

Src = Src + 8;

for (Index = 0; Index < sizeof(SCRATCH_DATA); Index++) {
    ((UINT8*)Sd)[Index] = 0;
}

Sd->mBytesRemain = (UINT16)(-1);
Sd->mSrcBase = Src;
Sd->mDstBase = Dst;
Sd->mCompSize = CompSize;
Sd->mOrigSize = OrigSize;

    // Fill the first two bytes
    //
    FillBuf(Sd, BITBUFSIZ);

while (Sd->mOrigSize > 0) {
    Count = (UINT16) (WNDSIZ < Sd->mOrigSize? WNDSIZ: Sd->mOrigSize);
    Decode (Sd, Count);
    if (Sd->mBadTableFlag != 0) {
        // Something wrong with the source
        //
        return EFI_INVALID_PARAMETER;
    }

    for (Index = 0; Index < Count; Index ++) {
        if (Dst1 < Dst + DstSize) {
            *(Dst1++) = Sd->mBuffer[Index];
        } else {
            return EFI_INVALID_PARAMETER;
        }
    }

    Sd->mOrigSize -= Count;
}

if (Sd->mBadTableFlag != 0) {
    Status = EFI_INVALID_PARAMETER;
} else {
    Status = EFI_SUCCESS;
}
return Status;
}.

STATIC VOID FillBuf (  
    IN SCRATCH_DATA *Sd,
    IN UINT16 NumOfBits
)  
/++

Routine Description:

Shift mBitBuf NumOfBits left. Read in NumOfBits of bits from source.

Arguments:

    Sd - The global scratch data
    NumOfBit - The number of bits to shift and read.

Returns: (VOID)

--*/
{
    Sd->mBitBuf = (UINT16)(Sd->mBitBuf << NumOfBits);

    while (NumOfBits > Sd->mBitCount) {

        Sd->mBitBuf |= (UINT16)(Sd->mSubBitBuf <<
            (NumOfBits = (UINT16)(NumOfBits - Sd->mBitCount)));

        if (Sd->mCompSize > 0) {

            //
            // Get 1 byte into SubBitBuf
            //
            Sd->mCompSize --;
            Sd->mSubBitBuf = 0;
            Sd->mSubBitBuf = Sd->mSrcBase[Sd->mInBuf ++];
            Sd->mBitCount = 8;

        } else {

            Sd->mSubBitBuf = 0;
            Sd->mBitCount = 8;

        }

    }

    Sd->mBitCount = (UINT16)(Sd->mBitCount - NumOfBits);
    Sd->mBitBuf &= Sd->mSubBitBuf >> Sd->mBitCount;
}
STATIC
UINT16
GetBits(
   IN SCRATCH_DATA *Sd,
   IN UINT16 NumOfBits
)
/*++
Routine Description:
Get NumOfBits of bits out from mBitBuf. Fill mBitBuf with subsequent
NumOfBits of bits from source. Returns NumOfBits of bits that are
popped out.
Arguments:
Sd - The global scratch data.
NumOfBits - The number of bits to pop and read.
Returns:
The bits that are popped out.
--*/
{
   UINT16 OutBits;
   OutBits = (UINT16)(Sd->mBitBuf >> (BITBUFSIZ - NumOfBits));
   FillBuf (Sd, NumOfBits);
   return OutBits;
}

STATIC
UINT16
MakeTable (
   IN SCRATCH_DATA *Sd,
   IN UINT16 NumOfChar,
   IN UINT8 *BitLen,
   IN UINT16 TableBits,
   OUT UINT16 *Table
)
/*++
Routine Description:
Creates Huffman Code mapping table according to code length array.
Arguments:
Sd - The global scratch data
(continues on next page)
NumOfChar - Number of symbols in the symbol set
BitLen - Code length array
TableBits - The width of the mapping table
Table - The table

Returns:

0 - OK.
BAD_TABLE - The table is corrupted.

*/
{
  UINT16 Count[17];
  UINT16 Weight[17];
  UINT16 Start[18];
  UINT16 *p;
  UINT16 k;
  UINT16 i;
  UINT16 Len;
  UINT16 Char;
  UINT16 JuBits;
  UINT16 Avail;
  UINT16 NextCode;
  UINT16 Mask;

  for (i = 1; i <= 16; i++) {
    Count[i] = 0;
  }

  for (i = 0; i < NumOfChar; i++) {
    Count[BitLen[i]]++;
  }

  Start[1] = 0;

  for (i = 1; i <= 16; i++) {
    Start[i + 1] = (UINT16)(Start[i] + (Count[i] << (16 - i)));
  }

  if (Start[17] != 0) {/*(1U << 16)*/
    return (UINT16)BAD_TABLE;
  }

  JuBits = (UINT16)(16 - TableBits);

  for (i = 1; i <= TableBits; i++) {
    Start[i] >>= JuBits;
    Weight[i] = (UINT16)(1U << (TableBits - i));
  }

  while (i <= 16) {
    Weight[i++] = (UINT16)(1U << (16 - i));
  }
\[\begin{align*}
&i = (\text{UINT16})(\text{Start}[\text{TableBits} + 1] >> \text{JuBits}); \\
&\text{if } (i \neq 0) \{ \\
&\quad k = (\text{UINT16})(1U << \text{TableBits}); \\
&\quad \text{while } (i \neq k) \{ \\
&\quad\quad \text{Table}[i++] = 0; \\
&\quad \} \\
&\}
\end{align*}\]

\[\begin{align*}
&\text{Avail} = \text{NumOfChar}; \\
&\text{Mask} = (\text{UINT16})(1U << (15 - \text{TableBits})); \\
&\text{for } (\text{Char} = 0; \text{Char} < \text{NumOfChar}; \text{Char}++) \{ \\
&\quad \text{Len} = \text{BitLen}[\text{Char}]; \\
&\quad \text{if } (\text{Len} == 0) \{ \\
&\quad\quad \text{continue;} \\
&\quad \} \\
&\quad \text{NextCode} = (\text{UINT16})(\text{Start}[\text{Len}] + \text{Weight}[\text{Len}]); \\
&\quad \text{if } (\text{Len} <= \text{TableBits}) \{ \\
&\quad\quad \text{for } (i = \text{Start}[\text{Len}]; i < \text{NextCode}; i++) \{ \\
&\quad\quad\quad \text{Table}[i] = \text{Char}; \\
&\quad\quad \} \\
&\quad \} \text{ else } \{ \\
&\quad\quad \text{k} = \text{Start}[\text{Len}]; \\
&\quad\quad \text{p} = &\text{Table}[k >> \text{JuBits}]; \\
&\quad\quad \text{i} = (\text{UINT16})(\text{Len} - \text{TableBits}); \\
&\quad\quad \text{while } (i != 0) \{ \\
&\quad\quad\quad \text{if } (*p == 0) \{ \\
&\quad\quad\quad\quad \text{Sd->mRight[Avail]} = \text{Sd->mLeft[Avail]} = 0; \\
&\quad\quad\quad\quad *p = \text{Avail} ++; \\
&\quad\quad\quad \} \\
&\quad\quad\quad \text{if } (k & \text{Mask}) \{ \\
&\quad\quad\quad\quad \text{p} = &\text{Sd->mRight[}*p]; \\
&\quad\quad\quad \} \text{ else } \{ \\
&\quad\quad\quad\quad \text{p} = &\text{Sd->mLeft[}*p]; \\
&\quad\quad\quad \} \\
&\quad\quad \quad k <<= 1; \\
&\quad\quad \quad i --; \\
&\quad\quad \} \\
&\quad \} \\
&\quad \} \\
&\} \\
\end{align*}\]
Start[Len] = NextCode;

// Succeeds
// return 0;

STATIC
UINT16
DecodeP (
    IN SCRATCH_DATA *Sd
)
/*++
Routine description:

Decodes a position value.

Arguments:

Sd - the global scratch data

Returns:

The position value decoded.

--*/
{
    UINT16 Val;
    UINT16 Mask;
    Val = Sd->mPTTable[Sd->mBitBuf >> (BITBUFSIZ - 8)];
    if (Val >= NP) {
        Mask = 1U << (BITBUFSIZ - 1 - 8);
        do {
            if (Sd->mBitBuf & Mask) {
                Val = Sd->mRight[Val];
            } else {
                Val = Sd->mLeft[Val];
            }
        }
    Mask >>= 1;
} while (Val >= NP);
}
// Advance what we have read
//
FillBuf (Sd, Sd->mPTLen[Val]);

if (Val) {
    Val = (UINT16)((1U << (Val - 1)) + GetBits (Sd, (UINT16)(Val - 1)));
}

return Val;
}

STATIC
UINT16
ReadPTLen (IN SCRATCH_DATA *Sd,
            IN UINT16 nn,
            IN UINT16 nbit,
            IN UINT16 Special)
/*!++

Routine Description

Reads code lengths for the Extra Set or the Position Set

Arguments:

Sd - The global scratch data
nn - Number of symbols
nbit - Number of bits needed to represent nn
Special - The special symbol that needs to be taken care of

Returns:

0 - OK.
BAD_TABLE - Table is corrupted.

-+-*/
{
    UINT16 n;
    UINT16 c;
    UINT16 i;
    UINT16 Mask;

    n = GetBits (Sd, nbit);

    if (n == 0) {
        c = GetBits (Sd, nbit);

        for (i = 0; i < 256; i++) {
            Sd->mPTTable[i] = c;
        }
    }
}
for (i = 0; i < nn; i++) {
    Sd->mPTLen[i] = 0;
}

return 0;
}

i = 0;
while (i < n) {

c = (UINT16)(Sd->mBitBuf >> (BITBUFSIZ - 3));

if (c == 7) {
    Mask = 1U << (BITBUFSIZ - 1 - 3);
    while (Mask & Sd->mBitBuf) {
        Mask >>= 1;
        c += 1;
    }
}

FillBuf (Sd, (UINT16)((c < 7) ? 3 : c - 3));

Sd->mPTLen[i++] = (UINT8)c;

if (i == Special) {
    c = GetBits (Sd, 2);
    while (((INT16)(--c) >= 0) {
        Sd->mPTLen[i++] = 0;
    }
}
}

while (i < nn) {
    Sd->mPTLen[i++] = 0;
}

return ( MakeTable (Sd, nn, Sd->mPTLen, 8, Sd->mPTTable) );
}

STATIC VOID
ReadCLen ( SCRATCH_DATA *Sd )
/*++
Routine Description:
*/
Reads code lengths for Char&Len Set.

Arguments:

Sd - the global scratch data

Returns: (VOID)

--*--
{
    UINT16 n;
    UINT16 c;
    UINT16 i;
    UINT16 Mask;

    n = GetBits(Sd, CBIT);

    if (n == 0) {
        c = GetBits(Sd, CBIT);

        for (i = 0; i < NC; i++) {
            Sd->mCLen[i] = 0;
        }

        for (i = 0; i < 4096; i++) {
            Sd->mCTable[i] = c;
        }

        return;
    }

    i = 0;
    while (i < n) {

        c = Sd->mPTTable[Sd->mBitBuf >> (BITBUFSIZ - 8)];
        if (c >= NT) {
            Mask = 1U << (BITBUFSIZ - 1 - 8);
            do {
                if (Mask & Sd->mBitBuf) {
                    c = Sd->mRight[c];
                } else {
                    c = Sd->mLeft[c];
                }

                Mask >>= 1;
            } while (c >= NT);
        }

    //

    (continues on next page)
// Advance what we have read
//
FillBuf (Sd, Sd->mPTLen[c]);

if (c <= 2) {
    if (c == 0) { c = 1; }
    else if (c == 1) {
        c = (UINT16)(GetBits (Sd, 4) + 3);
    } else if (c == 2) {
        c = (UINT16)(GetBits (Sd, CBIT) + 20);
    }

    while ((INT16)(--c) >= 0) {
        Sd->mCLen[i++] = 0;
    }
}

else {
    Sd->mCLen[i++] = (UINT8)(c - 2);
}

while (i < NC) {
    Sd->mCLen[i++] = 0;
}

MakeTable (Sd, NC, Sd->mCLen, 12, Sd->mCTable);

return;
}

STATIC
UINT16
DecodeC (SCRATCH_DATA *Sd)
/*++
Routine Description:

Decode a character/length value.

Arguments:

Sd - The global scratch data.

Returns:

The value decoded.
*/

(continues on next page)
```c
/*
{UINT16 j;
 UINT16 Mask;

if (Sd->mBlockSize == 0) {
    //
    // Starting a new block
    //
    Sd->mBlockSize = GetBits(Sd, 16);
    Sd->mBadTableFlag = ReadPTLen (Sd, NT, TBIT, 3);
    if (Sd->mBadTableFlag != 0) {
        return 0;
    }
}

ReadCLen (Sd);

Sd->mBadTableFlag = ReadPTLen (Sd, NP, PBIT, (UINT16)(-1));
if (Sd->mBadTableFlag != 0) {
    return 0;
}
} }

Sd->mBlockSize --;
j = Sd->mCTable[Sd->mBitBuf >> (BITBUFSIZ - 12)];

if (j >= NC) {
    Mask = 1U << (BITBUFSIZ - 1 - 12);
    do {
        if (Sd->mBitBuf & Mask) {
            j = Sd->mRight[j];
        } else {
            j = Sd->mLeft[j];
        }
        Mask >>= 1;
    } while (j >= NC);
}

//
// Advance what we have read
//
FillBuf(Sd, Sd->mCLen[j]);

return j;
} }

STATIC
```
VOID
Decode (SCRATCH_DATA *Sd, UINT16 NumOfBytes)
/**++

Routine Description:

Decode NumOfBytes and put the resulting data at starting point of mBuffer. The buffer is circular.

Arguments:

Sd - The global scratch data
NumOfBytes - Number of bytes to decode

Returns: (VOID)

{UINT16 di;
 UINT16 r;
 UINT16 c;

r = 0;
di = 0;

Sd->mBytesRemain --;
while ((INT16)(Sd->mBytesRemain) >= 0) {
    Sd->mBuffer[di++] = Sd->mBuffer[Sd->mDataIdx++];

    if (Sd->mDataIdx >= WNDSIZ) {
        Sd->mDataIdx -= WNDSIZ;
    }
    r ++;
    if (r >= NumOfBytes) {
        return;
    }
    Sd->mBytesRemain --;
}

for (;;) {
    c = DecodeC (Sd);
    if (Sd->mBadTableFlag != 0) {
        return;
    }

    if (c < 256) {
        //
    }

}
// Process an Original character
//
Sd->mBuffer[di++] = (UINT8)c;
r ++;
if (di >= WNDSIZ) {
    return;
}
}

else {

    // Process a Pointer
    //
    c = (UINT16)(c - (UINT8_MAX + 1 - THRESHOLD));
    Sd->mBytesRemain = c;

    Sd->mDataIdx = (r - DecodeP(Sd) - 1) & (WNDSIZ - 1); //Make circular

    di = r;

    Sd->mBytesRemain --;
    while ((INT16)(Sd->mBytesRemain) >= 0) {
        Sd->mBuffer[di++] = Sd->mBuffer[Sd->mDataIdx++];
        if (Sd->mDataIdx >= WNDSIZ) {
            Sd->mDataIdx -= WNDSIZ;
        }
        r ++;
        if (di >= WNDSIZ) {
            return;
        } 
        Sd->mBytesRemain --;
    }

    return;
}
APPENDIX J — EFI BYTE CODE VIRTUAL MACHINE OPCODE LIST

The following table lists the opcodes for EBC instructions. Note that opcodes only require 6 bits of the opcode byte of EBC instructions. The other two bits are used for other encodings that are dependent on the particular instruction.

<table>
<thead>
<tr>
<th>Opcode</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td><strong>BREAK</strong> [break code]</td>
</tr>
<tr>
<td>0x01</td>
<td><strong>JMP</strong> [cs {@}R1 {Immed32]</td>
</tr>
<tr>
<td>0x02</td>
<td><strong>JMP8</strong> {cs Immed8</td>
</tr>
<tr>
<td>0x03</td>
<td><strong>CALL</strong> [EX]{a} {@}R1 {Immed32</td>
</tr>
<tr>
<td>0x04</td>
<td><strong>RET</strong></td>
</tr>
<tr>
<td>0x05</td>
<td><strong>CMP</strong> [32 R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x06</td>
<td><strong>CMP</strong> [32 R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x07</td>
<td><strong>CMP</strong> [32 R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x08</td>
<td><strong>CMP</strong> [32 R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x09</td>
<td><strong>CMP</strong> [32 R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x0A</td>
<td><strong>NOT</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x0B</td>
<td><strong>NEG</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x0C</td>
<td><strong>ADD</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x0D</td>
<td><strong>SUB</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x0E</td>
<td><strong>MUL</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x0F</td>
<td><strong>MULU</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x10</td>
<td><strong>DIV</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x11</td>
<td><strong>DIVU</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x12</td>
<td><strong>MOD</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x13</td>
<td><strong>MODU</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x14</td>
<td><strong>AND</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x15</td>
<td><strong>OR</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x16</td>
<td><strong>XOR</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x17</td>
<td><strong>SHL</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x18</td>
<td><strong>SHR</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x19</td>
<td><strong>ASHR</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x1A</td>
<td><strong>EXTNDB</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x1B</td>
<td><strong>EXTNDW</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x1C</td>
<td><strong>EXTNDD</strong> [32 [@]R1, {@}R2 {Index16</td>
</tr>
<tr>
<td>0x1D</td>
<td><strong>MOV</strong> bw [@]R1 {Index16], {@}R2 {Index16]</td>
</tr>
<tr>
<td>0x1E</td>
<td><strong>MOV</strong> ww [@]R1 {Index16], {@}R2 {Index16]</td>
</tr>
<tr>
<td>0x1F</td>
<td><strong>MOV</strong> dw [@]R1 {Index16], {@}R2 {Index16]</td>
</tr>
<tr>
<td>0x20</td>
<td><strong>MOV</strong> qw [@]R1 {Index16], {@}R2 {Index16]</td>
</tr>
</tbody>
</table>

continues on next page
Table J.1 – continued from previous page

<table>
<thead>
<tr>
<th>Code</th>
<th>Instruction</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x21</td>
<td>MOV bd</td>
<td>[@]R1 [Index32], [@]R2 [Index32]</td>
</tr>
<tr>
<td>0x22</td>
<td>MOV wd</td>
<td>[@]R1 [Index32], [@]R2 [Index32]</td>
</tr>
<tr>
<td>0x23</td>
<td>MOV dd</td>
<td>[@]R1 [Index32], [@]R2 [Index32]</td>
</tr>
<tr>
<td>0x24</td>
<td>MOV qd</td>
<td>[@]R1 [Index32], [@]R2 [Index32]</td>
</tr>
<tr>
<td>0x25</td>
<td>MOVsn w</td>
<td>[@]R1 [Index16], [@]R2 [Index16]</td>
</tr>
<tr>
<td>0x26</td>
<td>MOVsn d</td>
<td>[@]R1 [Index32], [@]R2 [Index32]</td>
</tr>
<tr>
<td>0x27</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>0x28</td>
<td>MOV qq</td>
<td>[@]R1 [Index64], [@]R2 [Index64]</td>
</tr>
<tr>
<td>0x29</td>
<td>LOADSP</td>
<td>[Flags], R2</td>
</tr>
<tr>
<td>0x2A</td>
<td>STORESP</td>
<td>R1, [IP][Flags]</td>
</tr>
<tr>
<td>0x2B</td>
<td>PUSH</td>
<td>[32] [@]R1 [Index16]</td>
</tr>
<tr>
<td>0x2C</td>
<td>POP</td>
<td>[32] [@]R1 [Index16]</td>
</tr>
<tr>
<td>0x2D</td>
<td>CMPI</td>
<td>[32] [@]R1 [Index16], Immed16</td>
</tr>
<tr>
<td>0x2E</td>
<td>CMPI</td>
<td>[32] [@]R1 [Index16], Immed16</td>
</tr>
<tr>
<td>0x2F</td>
<td>CMPI</td>
<td>[32] [@]R1 [Index16], Immed16</td>
</tr>
<tr>
<td>0x30</td>
<td>CMPI</td>
<td>[32] [@]R1 [Index16], Immed16</td>
</tr>
<tr>
<td>0x31</td>
<td>CMPI</td>
<td>[32] [@]R1 [Index16], Immed16</td>
</tr>
<tr>
<td>0x32</td>
<td>MOVn w</td>
<td>[@]R1 [Index16], [@]R2 [Index16]</td>
</tr>
<tr>
<td>0x33</td>
<td>MOVn d</td>
<td>[@]R1 [Index32], [@]R2 [Index32]</td>
</tr>
<tr>
<td>0x34</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>0x35</td>
<td>PUSHn</td>
<td>[@]R1 [Index16]</td>
</tr>
<tr>
<td>0x36</td>
<td>POPn</td>
<td>[@]R1 [Index16]</td>
</tr>
<tr>
<td>0x37</td>
<td>MOV</td>
<td>[b] [@]R1 [Index16], Immed16</td>
</tr>
<tr>
<td>0x38</td>
<td>MOVn</td>
<td>[w] [@]R1 [Index16], Index16</td>
</tr>
<tr>
<td>0x39</td>
<td>MOVREL</td>
<td>[w] [@]R1 [Index16], Immed16</td>
</tr>
<tr>
<td>0x3A</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>0x3B</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>0x3C</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>0x3D</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>0x3E</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>0x3F</td>
<td>Reserved</td>
<td></td>
</tr>
</tbody>
</table>
APPENDIX K — ALPHABETIC FUNCTION LISTS

This appendix was redacted in version 2.6.
APPENDIX L — EFI 1.10 PROTOCOL CHANGES AND DEPRECATION LIST

L.1 Protocol and GUID Name Changes from EFI 1.10

This appendix lists the Protocol, GUID, and revision identifier name changes and the deprecated protocols compared to the EFI Specification 1.10. The protocols listed are not Runtime, Reentrant or MP Safe. Protocols are listed by EFI 1.10 name.

For protocols in the table whose TPL is not <= TPL_NOTIFY:

This function must be called at a TPL level less then or equal to %%%.

%%% is TPL_CALLBACK or TPL_APPLICATION. The <= is done via text.

Table L.1: Protocol Name changes

<table>
<thead>
<tr>
<th>EFI 1.10 Protocol Name</th>
<th>UEFI Specification Protocol Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_LOADED_IMAGE</td>
<td>EFI_LOADED_IMAGE_PROTOCOL</td>
</tr>
<tr>
<td>TPL</td>
<td>&lt;= TPL_NOTIFY</td>
</tr>
<tr>
<td>New GUID name</td>
<td>EFI_LOADED_IMAGE_PROTOCOL_GUID</td>
</tr>
<tr>
<td>EFI_DEVICE_PATH</td>
<td>EFI_DEVICE_PATH_PROTOCOL</td>
</tr>
<tr>
<td>TPL</td>
<td>&lt;= TPL_NOTIFY</td>
</tr>
<tr>
<td>New GUID name</td>
<td>EFI_DEVICE_PATH_PROTOCOL_GUID</td>
</tr>
<tr>
<td>SIMPLE_INPUT_INTERFACE</td>
<td>EFI_SIMPLE_INPUT_PROTOCOL</td>
</tr>
<tr>
<td>TPL</td>
<td>&lt;= TPL_APPLICATION</td>
</tr>
<tr>
<td>New GUID name</td>
<td>EFI_SIMPLE_INPUT_PROTOCOL_GUID</td>
</tr>
<tr>
<td>SIMPLE_TEXT_OUTPUT_INTERFACE</td>
<td>EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL</td>
</tr>
<tr>
<td>TPL</td>
<td>&lt;= TPL_CALLBACK</td>
</tr>
<tr>
<td>New GUID name</td>
<td>EFI_SIMPLE_TEXT_OUTPUT_PROTOCOL_GUID</td>
</tr>
<tr>
<td>SERIAL_IO_INTERFACE</td>
<td>EFI_SERIAL_IO_PROTOCOL</td>
</tr>
<tr>
<td>TPL</td>
<td>&lt;= TPL_CALLBACK</td>
</tr>
<tr>
<td>New GUID name</td>
<td>EFI_SERIAL_IO_PROTOCOL_GUID</td>
</tr>
<tr>
<td>EFI_LOAD_FILE_INTERFACE</td>
<td>EFI_LOAD_FILE_PROTOCOL</td>
</tr>
<tr>
<td>TPL</td>
<td>&lt;= TPL_NOTIFY</td>
</tr>
<tr>
<td>New GUID name</td>
<td>EFI_LOAD_FILE_PROTOCOL_GUID</td>
</tr>
<tr>
<td>EFI_FILE_IMP_INTERFACE</td>
<td>EFI_SIMPLE_FILE_SYSTEM_PROTOCOL</td>
</tr>
<tr>
<td>TPL</td>
<td>&lt;= TPL_CALLBACK</td>
</tr>
<tr>
<td>New GUID name</td>
<td>EFI_FILE_SYSTEM_PROTOCOL_GUID</td>
</tr>
<tr>
<td>EFI_FILE</td>
<td>EFI_FILE_PROTOCOL</td>
</tr>
<tr>
<td>TPL</td>
<td>&lt;= TPL_CALLBACK</td>
</tr>
<tr>
<td>New GUID name</td>
<td>EFI_FILE_PROTOCOL</td>
</tr>
</tbody>
</table>

continues on next page
Table L.1 – continued from previous page

<table>
<thead>
<tr>
<th>New GUID name</th>
<th>EFI_DISK_IO_PROTOCOL_GUID</th>
</tr>
</thead>
<tbody>
<tr>
<td>New GUID name</td>
<td>EFI_BLOCK_IO_PROTOCOL_GUID</td>
</tr>
<tr>
<td>UNICODE_COLLATION_INTERFACE</td>
<td>EFI_UNICODE_COLLATION_PROTOCOL</td>
</tr>
<tr>
<td>EFI_DEVICE_IO_INTERFACE</td>
<td>EFI_DEVICE_IO_PROTOCOL_GUID</td>
</tr>
</tbody>
</table>

Table L.2: Revision Identifier Name Changes

<table>
<thead>
<tr>
<th>EFI 1.10 Revision Identifier Name</th>
<th>UEFI Specification Revision Identifier Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>EFI_LOADED_IMAGE_INFORMATION_REVISION</td>
<td>EFI_LOADED_IMAGE_PROTOCOL_REVISION</td>
</tr>
<tr>
<td>SERIAL_IO_INTERFACE_REVISION</td>
<td>EFI_SERIAL_IO_PROTOCOL_REVISION</td>
</tr>
<tr>
<td>EFI_FILE_IO_INTERFACE_REVISION</td>
<td>EFI_SIMPLE_FILE_SYSTEM_PROTOCOL_REVISION</td>
</tr>
<tr>
<td>EFI_FILE_REVISION</td>
<td>EFI_FILE_PROTOCOL_REVISION</td>
</tr>
<tr>
<td>EFI_DISK_IO_INTERFACE_REVISION</td>
<td>EFI_DISK_IO_PROTOCOL_REVISION</td>
</tr>
<tr>
<td>EFI_BLOCK_IO_INTERFACE_REVISION</td>
<td>EFI_BLOCK_IO_PROTOCOL_REVISION</td>
</tr>
<tr>
<td>EFI_SIMPLE_NETWORK_INTERFACE_REVISION</td>
<td>EFI_SIMPLE_NETWORK_PROTOCOL_REVISION</td>
</tr>
<tr>
<td>EFI_NETWORK_INTERFACE_IDENTIFIER_INTERFACE_REVISION</td>
<td>EFI_NETWORK_INTERFACE_IDENTIFIER_PROTOCOL_REVISION</td>
</tr>
<tr>
<td>EFI_PXE_BASE_CODE_CALLBACK_INTERFACE_REVISION</td>
<td>EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL_REVISION</td>
</tr>
<tr>
<td>EFI_PXE_BASE_CODE_CALLBACK_INTERFACE_REVISION</td>
<td>EFI_PXE_BASE_CODE_CALLBACK_PROTOCOL_REVISION</td>
</tr>
</tbody>
</table>

L.2 Deprecated Protocols

Device I/O Protocol - The support of the Device I/O Protocol (see EFI 1.1 Chapter 18) has been replaced by the use of the PCI Root Bridge I/O protocols which are described in PCI Root Bridge I/O Protocol of the UEFI Specification. Note: certain “legacy” EFI applications such as some of the ones that reside in the EFI Toolkit assume the presence of Device I/O.

UGA I/O + UGA Draw Protocol - The support of the UGA * Protocols (see EFI 1.1 Section 10.7) have been replaced by the use of the EFI Graphics Output Protocol described in Protocols — Console Support of the UEFI Specification.

USB Host Controller Protocol (version that existed for EFI 1.1) - The support of the USB Host Controller Protocol
(see EFI 1.1 Section 14.1) has been replaced by the use of a UEFI instance that covers both USB 1.1 and USB 2.0 support, and is described in Protocols — USB Support of the UEFI Specification. It replaces the pre-existing protocol definition.

**SCSI Passthru Protocol** - The support of the SCSI Passthru Protocol (see EFI 1.1 Section 13.1) has been replaced by the use of the Extended SCSI Passthru Protocol, which is described in Section 15.7.

**BIS Protocol** - Remains as an optional protocol.

**Driver Configuration Protocol** - the `EFI_DRIVER_CONFIGURATION_PROTOCOL` has been removed.
This appendix lists the formats for language codes and language code arrays.

M.1 Specifying individual language codes

The preferred representation of a language code is done via an RFC 4646 language code identifier*.

**Alias codes supported in addition to RFC 4646**

<table>
<thead>
<tr>
<th>RFC string</th>
<th>Supported Alias String</th>
</tr>
</thead>
<tbody>
<tr>
<td>zh-Hans</td>
<td>zh-chs</td>
</tr>
<tr>
<td>zh-Hant</td>
<td>zh-cht</td>
</tr>
</tbody>
</table>

An RFC 4646 language code is represented as a null-terminated ASCII string.

An RFC 4646 language string must be constructed according to the tag creation rules in section 2.3 of RFC 4646. For example, when constructing the primary language tag for a locale identifier, if a 2 character ISO 639-1 language code exists along with a 3 character ISO 639-2 language code, then the ISO 639-1 language code must be used. Further, if an ISO 639-1 tag does not exist, then the ISO 639-2/T (Terminology) tag must be for the primary locale before an ISO 639-2/B (Bibliographic) tag may be used. See RFC 4646 for a complete discussion of this topic.

To provide backwards compatibility with preexisting EFI 1.10 drivers, a UEFI platforms may support deprecated protocols which represent languages in the ISO 639-2 format. This includes the following protocols: `UNICODE_COLLATION_INTERFACE`, `EZI_DRIVER_CONFIGURATION_PROTOCOL`, `EFI_DRIVER_DIAGNOSTICS_PROTOCOL`, and `EFI_COMPONENT_NAME_PROTOCOL`. The deprecated `LangCodes` and `Lang` global variables may also be supported by a platform for backwards compatibility.

M.1.1 Specifying language code arrays:

Native RFC 4646 format array:

An array of RFC 4646 character codes is represented as a NULL terminated char8 array of RFC 4646 language code strings. Each of these strings is delimited by a semicolon (‘;’) character. For example, an array of US English and Traditional Chinese would be represented as the NULL-terminated string “en-us;zh-Hant”.

An RFC 4646 language code is represented as a null-terminated ASCII string.

An RFC 4646 language string must be constructed according to the tag creation rules in section 2.3 of RFC 4646. For example, when constructing the primary language tag for a locale identifier, if a 2 character ISO 639-1 language code exists along with a 3 character ISO 639-2 language code, then the ISO 639-1 language code must be used. Further, if an ISO 639-1 tag does not exist, then the ISO 639-2/T (Terminology) tag must be for the primary locale before an ISO 639-2/B (Bibliographic) tag may be used. See RFC 4646 for a complete discussion of this topic.

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An RFC 4646 language code is represented as a null-terminated ASCII string.

An RFC 4646 language string must be constructed according to the tag creation rules in section 2.3 of RFC 4646. For example, when constructing the primary language tag for a locale identifier, if a 2 character ISO 639-1 language code exists along with a 3 character ISO 639-2 language code, then the ISO 639-1 language code must be used. Further, if an ISO 639-1 tag does not exist, then the ISO 639-2/T (Terminology) tag must be for the primary locale before an ISO 639-2/B (Bibliographic) tag may be used. See RFC 4646 for a complete discussion of this topic.

To provide backwards compatibility with preexisting EFI 1.10 drivers, a UEFI platforms may support deprecated protocols which represent languages in the ISO 639-2 format. This includes the following protocols: `UNICODE_COLLATION_INTERFACE`, `EZI_DRIVER_CONFIGURATION_PROTOCOL`, `EFI_DRIVER_DIAGNOSTICS_PROTOCOL`, and `EFI_COMPONENT_NAME_PROTOCOL`. The deprecated `LangCodes` and `Lang` global variables may also be supported by a platform for backwards compatibility.
APPENDIX N - COMMON PLATFORM ERROR RECORD (CPER)

N.1 Introduction

This appendix describes the common platform error record (CPER) format for representing platform hardware errors.

N.2 Format

The general format of the common platform error record is illustrated in the Figure below. The record consists of a header; followed by one or more section descriptors; and for each descriptor, an associated section which may contain either error or informational data.

Fig. N.1: Error Record Format
N.2.1 Record Header

The record header includes information which uniquely identifies a hardware error record on a given system. The contents of the record header are described in the Table below. The header is immediately followed by an array of one or more section descriptors. Sections may be either error sections, which contain error information retrieved from hardware, or they may be informational sections, which contain contextual information relevant to the error. An error record must contain at least one section.

Table N.1: Error record header

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Signature Start</td>
<td>0</td>
<td>4</td>
<td>ASCII 4-character array “CPER” (0x43,0x50,0x45,0x52). Identifies this structure as a hardware error record.</td>
</tr>
</tbody>
</table>
| Revision         | 4           | 2           | This is a 2-byte field representing a major and minor version number for the error record definition in BCD format. The interpretation of the major and minor version number is as follows:  
  • Byte 0 - Minor (01): An increase in this revision indicates that changes to the headers and sections are backward compatible with software that use earlier revisions. Addition of new GUID types, errata fixes or clarifications are covered by a bump up.  
  • Byte 1 - Major (01): An increase in this revision indicates that the changes are not backward compatible from a software perspective. |
| Signature End    | 6           | 4           | Must be 0xFFFFFFFF |
| Section Count    | 10          | 2           | This field indicates the number of valid sections associated with the record, corresponding to each of the following section descriptors. |
| Error Severity   | 12          | 4           | Indicates the severity of the error condition. The severity of the error record corresponds to the most severe error section.  
  0 - Recoverable (also called non-fatal uncorrected)  
  1 - Fatal  
  2 - Corrected  
  3 - Informational  
  All other values are reserved.  
  Note that severity of “Informational” indicates that the record could be safely ignored by error handling software. |
<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Validation Bits</td>
<td>16</td>
<td>4</td>
<td>This field indicates the validity of the following fields:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 0 - If 1, the PlatformID field contains valid information</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 1 - If 1, the TimeStamp field contains valid information</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 2 - If 1, the PartitionID field contains valid information</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bits 3-31: Reserved, must be zero.</td>
</tr>
<tr>
<td>Record Length</td>
<td>20</td>
<td>4</td>
<td>Indicates the size of the actual error record, including the size of the record header, all section descriptors, and section bodies.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>The size may include extra buffer space to allow for the dynamic addition of error sections descriptors and bodies.</td>
</tr>
<tr>
<td>Timestamp</td>
<td>24</td>
<td>8</td>
<td>The timestamp correlates to the time when the error information was collected by the system software and may not necessarily represent the</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>time of the error event. The timestamp contains the local time in BCD format.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte 7 - Byte 0:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte 0: Seconds</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte 1: Minutes</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte 2: Hours</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte 3:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 0 - Timestamp is precise if this bit is set and correlates to the time of the error event.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 7:1 - Reserved</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte 4: Day</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte 5: Month</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte 6: Year</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte 7: Century</td>
</tr>
<tr>
<td>Platform ID</td>
<td>32</td>
<td>16</td>
<td>This field uniquely identifies the platform with a GUID. The platform’s SMBIOS UUID should be used to populate this field. Error analysis</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>software may use this value to uniquely identify a platform.</td>
</tr>
<tr>
<td>Partition ID</td>
<td>48</td>
<td>16</td>
<td>If the platform has multiple software partitions, system software may associate a GUID with the partition on which the error occurred.</td>
</tr>
<tr>
<td>Creator ID</td>
<td>64</td>
<td>16</td>
<td>This field contains a GUID indicating the creator of the error record. This value may be overwritten by subsequent owners of the record.</td>
</tr>
</tbody>
</table>

continues on next page
### Table N.1 – continued from previous page

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Notification Type</td>
<td>80</td>
<td>16</td>
<td>This field holds a pre-assigned GUID value indicating the record association with an error event notification type. The defined types are:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>CMC                                                                                                               {0x2DCE8BB1, 0xBDD7, 0x450e, {0xB9, 0xAD, 0x9C, 0xF4, 0xEB, 0xD4, 0xF8, 0x90}}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>CPE                                                                                                               {0x4E292F96, 0xD843, 0x4a55, {0xA8, 0xC2, 0xD4, 0x81, 0xF2, 0x7E, 0xBE, 0xEE}}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>MCE                                                                                                               {0xE8F56FFE, 0x919C, 0x4cc5, {0xBA, 0x88, 0x65, 0xAB, 0xE1, 0x49, 0x13, 0xBB}}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>PCIe                                                                                                              {0xCF93C01F, 0x1A16, 0x4dfc, {0xB8, 0xBC, 0x9C, 0x4D, 0xAF, 0x67, 0xC1, 0x04}}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>INIT                                                                                                              {0xCC5263E8, 0x9308, 0x454a, {0x89, 0xD0, 0x34, 0x0B, 0xD3, 0x9B, 0xC9, 0x8E}}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>NMI                                                                                                               {0x5BAD89FF, 0xB7E6, 0x42c9, {0x81, 0x4A, 0xCF, 0x24, 0x85, 0xD6, 0xE9, 0x8A}}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Boot                                                                                                              {0x3D61A466, 0xAB40, 0x409a, {0xA6, 0x98, 0xF3, 0x62, 0xD4, 0x64, 0xB3, 0x8F}}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>DMAr                                                                                                              {0x667DD791, 0xC6B3, 0x4c27, {0x8A, 0x6B, 0x0F, 0x8E, 0x72, 0x2D, 0xEB, 0x41}}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SEA                                                                                                               {0x9A78788A, 0xBBE8, 0x11E4, {0x80, 0x9E, 0x67, 0x61, 0x1E, 0x5D, 0x46, 0xB0}}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>SEI                                                                                                               {0x5C284C81, 0xB0AE, 0x4E87, {0xA3, 0x22, 0xB0, 0x4C, 0x85, 0x62, 0x43, 0x23}}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>PEI                                                                                                               {0x09A9D5AC, 0x5204, 0x4214, {0x96, 0xE5, 0x94, 0x99, 0x2E, 0x75, 0x2B, 0xCF}}</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>CXL Component                                                      {0x69293BC9, 0x41DF, 0x49A3 {0xB4, 0xBD, 0x4F, 0xB0, 0xDB, 0x30, 0x41, 0xF6}}</td>
</tr>
</tbody>
</table>
Table N.1 – continued from previous page

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Record ID</td>
<td>96</td>
<td>8</td>
<td>This value, when combined with the Creator ID, uniquely identifies the error record across other error records on a given system.</td>
</tr>
<tr>
<td>Flags</td>
<td>104</td>
<td>4</td>
<td>Flags field contains information that describes the error record. See Table 2 for defined flags.</td>
</tr>
<tr>
<td>Persistence Information</td>
<td>108</td>
<td>8</td>
<td>This field is produced and consumed by the creator of the error record identified in the Creator ID field. The format of this field is defined by the creator and it is out of scope of this specification.</td>
</tr>
<tr>
<td>Reserved</td>
<td>116</td>
<td>12</td>
<td>Reserved. Must be zero.</td>
</tr>
<tr>
<td>Section Descriptor</td>
<td>128</td>
<td>Nx72</td>
<td>An array of SectionCount descriptors for the associated sections. The number of valid sections is equivalent to the SectionCount. The buffer size of the record may include more space to dynamically add additional Section Descriptors to the error record.</td>
</tr>
</tbody>
</table>

Error Record Header Flags

The following table lists flags that can be used to qualify an error record in the Error Record Header’s Flags field.

Table N.2: Error Record Header Flags

<table>
<thead>
<tr>
<th>Value</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>HW_ERROR_FLAGS_RECOVERED: Qualifies an error condition as one that has been recovered by system software.</td>
</tr>
<tr>
<td>2</td>
<td>HW_ERROR_FLAGS_PREVERR: Qualifies an error condition as one that occurred during a previous session. For instance, of the OS detects an error and determines that the system must be reset; it will save the error record before stopping the system. Upon restarting the OS marks the error record with this flag to know that the error is not live.</td>
</tr>
<tr>
<td>4</td>
<td>HW_ERROR_FLAGS_SIMULATED: Qualifies an error condition as one that was intentionally caused. This allows system software to recognize errors that are injected as a means of validating or testing error handling mechanisms.</td>
</tr>
</tbody>
</table>

N.2.1.1 Notification Type

A notification type identifies the mechanism by which an error event is reported to system software. This information helps consumers of error information (e.g. management applications or humans) by identifying the source of the error information. This allows, for instance, all CMC error log entries to be filtered from an error event log.

Listed below are the standard notification types. Each standard notification type is identified by a GUID. For error notification types that do not conform to one of the standard types, a platform-specific GUID may be defined to identify the notification type.

- Machine Check Exception (MCE): \{0xE8F56FFE, 0x919C, 0x4cc5, 0xBA, 0x88, 0x65, 0xAB, 0xE1, 0x49, 0x13, 0xBB\} A Machine Check Exception is a processor-generated exception class interrupt used to system software of the presence of a fatal or recoverable error condition.

- Corrected Machine Check (CMC): \{0x2DCE8BB1, 0xBDD7, 0x450e, 0xB9, 0xAD, 0x9C, 0xF4, 0xEB, 0xD4, 0xF8, 0x90\} Corrected Machine Checks identify error conditions that have been corrected by hardware or system firmware. CMCs are reported by the processor and may be reported via interrupt or by polling error status registers.

N.2. Format
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

- **Corrected Platform Error (CPE):** \{0x4E292F96, 0xD843, 0x4a55, \{0xA8, 0xC2, 0xD4, 0x81, 0xF2, 0x7E, 0xBE, 0xEE\}\} Corrected Platform Errors identify corrected errors from the platform (i.e., external memory controller, system bus, etc.). CPEs can be reported via interrupt or by polling error status registers.

- **Non-Maskable Interrupt (NMI):** \{0x5BAD89FF, 0xB7E6, 0x42c9, \{0x81, 0x4A, 0xCF, 0x24, 0x85, 0xD6, 0xE9, 0x8A\}\} Non-Maskable Interrupts are used on X64 platforms to report fatal or recoverable platform error conditions. NMIs are reported via interrupt vector 2 on IA32 and X64 processor architecture platforms.

- **PCI Express Error (PCIe):** \{0xCF93C01F, 0x1A16, 0x4dfc, \{0xB8, 0xBC, 0x9C, 0x4D, 0xAF, 0x67, 0xC1, 0x04\}\} See the PCI Express standard v1.1 for details regarding PCI Express Error Reporting. This notification type identifies errors that were reported to the system via an interrupt on a PCI Express root port.

- **INIT Record (INIT):** \{0xCC5263E8, 0x9308, 0x454a, \{0x89, 0xD0, 0x34, 0x0B, 0xD3, 0x9B, 0xC9, 0x8E\}\} IPF Platforms optionally implement a mechanism (switch or button on the chassis) by which an operator may reset a system and have the system generate an INIT error record. This error record is documented in the IPF SAL specification. System software retrieves an INIT error record by querying the SAL for existing INIT records.

- **BOOT Error Record (BOOT):** \{0x3D61A466, 0xAB40, 0x409a, \{0xA6, 0x98, 0xF3, 0x62, 0xD4, 0x64, 0xB3, 0x8F\}\} The BOOT Notification Type represents error conditions which are unhandled by system software and which result in a system shutdown/reset. System software retrieves a BOOT error record during boot by querying the platform for existing BOOT records. As an example, consider an x64 platform which implements a service processor. In some scenarios, the service processor may detect that the system is either hung or is in such a state that it cannot safely proceed without risking data corruption. In such a scenario the service processor may record some minimal error information in its system event log (SEL) and unilaterally reset the machine without notifying the OS or other system software. In such scenarios, system software is unaware of the condition that caused the system reset. A BOOT error record would contain information that describes the error condition that led to the reset so system software can log the information and use it for health monitoring.

- **DMA Remapping Error (DMAr):** \{0x667DD791, 0xC6B3, 0x427, \{0x8A, 0x6B, 0x0F, 0x8E, 0x72, 0x2D, 0xEB, 0x41\}\} The DMA Remapping Notification Type identifies fault conditions generated by the DMAr unit when processing un-translated, translation and translated DMA requests. The fault conditions are reported to the system using a message signaled interrupt.

- **Synchronous External Abort (SEA):** \{0x9A78788A, 0xBBE8, 0x11E4, \{0x80, 0x9E, 0x67, 0x61, 0x1E, 0x5D, 0x46, 0xB0\}\} Synchronous External Aborts represent precise processor error conditions on ARM systems (uncorrectable and/or recoverable) as described in D3.5 of the ARMv8 ARM reference manual. This notification may be triggered by one of the following scenarios: cache parity error, cache ECC error, external bus error, micro-architectural error, data poisoning, and other platform errors.

- **SError Interrupt (SEI):** \{0x5C284C81, 0xB0AE, 0x4E87, \{0xA3, 0x22, 0xB0, 0x4C, 0x85, 0x62, 0x43, 0x23\}\} SError Interrupts represent asynchronous imprecise (or possibly precise) processor error conditions on ARM systems (corrected, uncorrectable, and recoverable) as described in D3.5 of the ARM ARM reference manual. This notification may be triggered by one of the following scenarios: cache parity error, cache ECC error, external bus error, micro-architectural error, data poisoning, and other platform errors.

- **Platform Error Interrupt (PEI):** \{0x9A9D5AC, 0x5204, 0x4214, \{0x96, 0xE5, 0x94, 0x99, 0x2E, 0x75, 0x2B, 0xCD\}\} Platform Error Interrupt represent asynchronous imprecise platform error conditions on ARM systems that may be triggered by the following scenarios: system memory ECC error, ECC errors in system cache (e.g. shared high-level caches), vendor specific chip errors, external platform errors.

- **Compute Express Link (CXL) Component:** \{0x6929BC9, 0x41DF, 0x49A3 \{0xB4, 0xBD, 0x4F, 0xB0, 0xDB, 0x30, 0x41, 0xF6\}\} This Notification Type identifies errors that were reported to the system by CXL components that support error reporting via the CXL RAS Mailbox interface. See the CXL Specification, Rev 2.0 or later, for details regarding CXL Error Reporting.

N.2. Format
N.2.1.2 Error Status

The error status definition provides the capability to abstract information from implementation-specific error registers into generic error codes.

Table N.3: Error Status Fields

<table>
<thead>
<tr>
<th>Bit Position</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>7:0</td>
<td>Reserved</td>
</tr>
<tr>
<td>15:8</td>
<td>Encoded value for the Error_Type. See Table 20 Error Types for details.</td>
</tr>
<tr>
<td>16</td>
<td>Address: Error was detected on the address signals or on the address portion of the transaction.</td>
</tr>
<tr>
<td>17</td>
<td>Control: Error was detected on the control signals or in the control portion of the transaction.</td>
</tr>
<tr>
<td>18</td>
<td>Data: Error was detected on the data signals or in the data portion of the transaction.</td>
</tr>
<tr>
<td>19</td>
<td>Responder: Error was detected by the responder of the transaction.</td>
</tr>
<tr>
<td>20</td>
<td>Requester: Error was detected by the requester of the transaction.</td>
</tr>
<tr>
<td>21</td>
<td>First Error: If multiple errors are logged for a section type, this is the first error in the chronological sequence. Setting of this bit is optional.</td>
</tr>
<tr>
<td>22</td>
<td>Overflow: Additional errors occurred and were not logged due to lack of logging resources.</td>
</tr>
<tr>
<td>63:23</td>
<td>Reserved.</td>
</tr>
</tbody>
</table>

Table N.4: Error Types

<table>
<thead>
<tr>
<th>Encoding</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>ERR_INTERNAL Error detected internal to the component.</td>
</tr>
<tr>
<td>16</td>
<td>ERR_BUS Error detected in the bus.</td>
</tr>
<tr>
<td>Detailed Internal Errors</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>ERR_MEM Storage error in memory (DRAM).</td>
</tr>
<tr>
<td>5</td>
<td>ERR_TLB Storage error in TLB.</td>
</tr>
<tr>
<td>6</td>
<td>ERR_CACHE Storage error in cache.</td>
</tr>
<tr>
<td>7</td>
<td>ERR_FUNCTION Error in one or more functional units.</td>
</tr>
<tr>
<td>8</td>
<td>ERR_SELFTEST component failed self test.</td>
</tr>
<tr>
<td>9</td>
<td>ERR_FLOW Overflow or undervalue of internal queue.</td>
</tr>
<tr>
<td>Detailed Bus Errors</td>
<td></td>
</tr>
<tr>
<td>17</td>
<td>ERR_MAP Virtual address not found on IO-TLB or IO-PDIR.</td>
</tr>
<tr>
<td>18</td>
<td>ERR_IMPROPER Improper access error.</td>
</tr>
<tr>
<td>19</td>
<td>ERR_UNIMPL Access to a memory address which is not mapped to any component.</td>
</tr>
<tr>
<td>20</td>
<td>ERR_LOL Loss of Lockstep</td>
</tr>
<tr>
<td>21</td>
<td>ERR_RESPONSE Response not associated with a request</td>
</tr>
<tr>
<td>22</td>
<td>ERR_PARITY Bus parity error (must also set the A, C, or D Bits).</td>
</tr>
<tr>
<td>23</td>
<td>ERR_PROTOCOL Detection of a protocol error.</td>
</tr>
<tr>
<td>24</td>
<td>ERR_ERROR Detection of a PATH_ERROR</td>
</tr>
<tr>
<td>25</td>
<td>ERR_TIMEOUT Bus operation timeout.</td>
</tr>
<tr>
<td>26</td>
<td>ERR_POISONED A read was issued to data that has been poisoned.</td>
</tr>
<tr>
<td>All Others</td>
<td>Reserved</td>
</tr>
</tbody>
</table>

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**N.2.2 Section Descriptor**

Table N.5: Section Descriptor

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Section Off-</td>
<td>0</td>
<td>4</td>
<td>Offset in bytes of the section body from the base of the record header.</td>
</tr>
<tr>
<td>set</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Section</td>
<td>4</td>
<td>4</td>
<td>The length in bytes of the section body.</td>
</tr>
<tr>
<td>Length</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Revision</td>
<td>8</td>
<td>2</td>
<td>This is a 2-byte field representing a major and minor version number for the</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>error record definition in BCD format. The interpretation of the major and</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>minor version number is as follows:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte 0 — Minor (00): An increase in this revision indicates that changes</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>to the headers and sections are backward compatible with software that uses</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>earlier revisions. Addition of new GUID types, errata fixes or clarifications</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>are covered by a bump up.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte 1 — Major (01): An increase in this revision indicates that the</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>changes are not backward compatible from a software perspective</td>
</tr>
<tr>
<td>Validation</td>
<td>10</td>
<td>1</td>
<td>This field indicates the validity of the following fields:</td>
</tr>
<tr>
<td>Bits</td>
<td></td>
<td></td>
<td>• Bit 0 - If 1, the FRUId field contains valid information</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bit 1 - If 1, the FRUString field contains valid information</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Bits 7:2 - Reserved, must be zero.</td>
</tr>
<tr>
<td>Reserved</td>
<td>11</td>
<td>1</td>
<td>Must be zero.</td>
</tr>
</tbody>
</table>

continues on next page
Flag field contains information that describes the error section as follows:

<table>
<thead>
<tr>
<th>Flags</th>
<th>12</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bit 0 - Primary: If set, identifies the section as the section to be associated with the error condition. This allows for FRU determination and for error recovery operations. By identifying a primary section, the consumer of an error record can determine which section to focus on. It is not always possible to identify a primary section so this flag should be taken as a hint.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 1 - Containment Warning: If set, the error was not contained within the processor or memory hierarchy and the error may have propagated to persistent storage or network.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 2 - Reset: If set, the component has been reset and must be re-initialized or re-enabled by the operating system prior to use.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 3 - Error threshold exceeded: If set, OS may choose to discontinue use of this resource.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 4 - Resource not accessible: If set, the resource could not be queried for error information due to conflicts with other system software or resources. Some fields of the section will be invalid.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 5 - Latent error: If set this flag indicates that action has been taken to ensure error containment (such a poisoning data), but the error has not been fully corrected and the data has not been consumed. System software may choose to take further corrective action before the data is consumed.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 6 - Propagated: If set this flag indicates the section is to be associated with an error that has been propagated due to hardware poisoning. This implies the error is a symptom of another error. It is not always possible to ascertain whether this is the case for an error, therefore if the flag is not set, it is unknown whether the error was propagated. This helps determining FRU when dealing with HW failures.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 7 - Overflow: If set this flag indicates the firmware has detected an overflow of buffers/queues that are used to accumulate, collect, or report errors (e.g. the error status control block exposed to the OS). When this occurs, some error records may be lost.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Bit 8 through 31 - Reserved.
This field holds a pre-assigned GUID value indicating that it is a section of a particular error. The different error section types are as defined below:

**Processor Generic**
- `{0x9876CCAD, 0x47B4, 0x4bdb, {0xB6, 0x5E, 0x16, 0xF1, 0x93, 0xC4, 0xF3, 0xDB}}`

**Processor Specific**
- IA32/X 64: `{0xDC3EA0B0, 0xA144, 0x4797, {0xB9, 0x5B, 0x53, 0xFA, 0x24, 0x2B, 0x6E, 0x1D}}`
- IPF: `{0xe429faf1, 0x3cb7, 0x11d4, {0xb, 0xca, 0x7, 0x00, 0x80, 0xc7, 0x3c, 0x88, 0x81}}` (see footnote 1 at the end of Appendix N)
- ARM: `{0xE19E3D16, 0xBC11, 0x11E4, {0x9C, 0xAA, 0xC2, 0x05, 0x1D, 0x5D, 0x46, 0xB0}}`

**Platform Memory**
- `{0xA5BC1114, 0x6F64, 0x4EDE, {0xB8, 0x63, 0x3E, 0x83, 0xED, 0x7C, 0x83, 0xB1}}`

**PCIe**
- `{0xD995E954, 0xBBC1, 0x430F, {0xAD, 0x91, 0xB4, 0x4D, 0xCB, 0x3C, 0x6F, 0x35}}`

**Firmware Error Record Reference**
- `{0x81212A96, 0x09ED, 0x4996, {0x94, 0x71, 0x8D, 0x72, 0x9C, 0x8E, 0x69, 0xED}}`

**PCI/PCI-X Bus**
- `{0xC5753963, 0x3B84, 0x4095, {0xBF, 0x78, 0xED, 0xDA, 0xD3, 0xF9, 0xC9, 0xDD}}`

**PCI Component/Device**
- `{0xEB5E4685, 0xCA66, 0x4769, {0xB6, 0xA2, 0x26, 0x06, 0x8B, 0x00, 0x13, 0x26}}`

**DMAr Generic**
- `{0x5B51FEF7, 0xC79D, 0x4434, {0x8F, 0x1B, 0xAA, 0x62, 0xDE, 0x3E, 0x2C, 0x64}}`

**Intel® VT for Directed I/O specific DMAr section**
- `{0x71761D37, 0x32B2, 0x45cd, {0xA7, 0xD0, 0xB0, 0xFE 0xDD, 0x93, 0xE8, 0xCF}}`

**IOMMU specific DMAr section**
- `{0x036F84E1, 0x7F37, 0x428c, {0xA7, 0x9E, 0x57, 0x5F, 0xDF, 0x4E, 0x84, 0xEC}}`
Table N.5 – continued from previous page

| FRU Id | 32 | 16 | GUID representing the FRU ID, if it exists, for the section reporting the error. The default value is zero indicating an invalid FRU ID. System software can use this to uniquely identify a physical device for tracking purposes. Association of a GUID to a physical device is done by the platform in an implementation-specific way (i.e., PCIe Device can lock a GUID to a PCIe Device ID). |
| Section Severity | 48 | 4 | This field indicates the severity associated with the error section. 0 - Recoverable (also called non-fatal uncorrected) 1 - Fatal 2 - Corrected 3 - Informational All other values are reserved. Note that severity of “Informational” indicates that the section contains extra information that can be safely ignored by error handling software. |
| FRU Text | 52 | 20 | ASCII string identifying the FRU hardware. |

Note:

1. For an IPF processor-specific error section, the GUID listed is the value from the SAL specification. The format of the data for this section is same as the Processor Device Error Info in the SAL specification.

N.2.3 Non-standard Section Body

Information that does not conform to one the standard formats (i.e., those defined in sections 2.4 through 2.9 of this document) may be recorded in the error record in a non-standard section. The type (e.g., format) of a non-standard section is identified by the GUID populated in the Section Descriptor’s Section Type field. This allows the information to be decoded by consumers if the format is externally documented. Examples of information that might be placed in a non-standard section include the IPF raw SAL error record, Error information recorded in implementation-specific PCI configuration space, and IPMI error information recorded in an IPMI SEL.

N.2.4 Processor Error Sections

The processor error sections are divided into two different components as described below:

1. Processor Generic Error Section: This section holds information about processor errors in a generic form and will be common across all processor architectures. An example or error information provided is the generic information of cache, tlb, etc., errors.

2. Processor Specific Error Section: This section consists of error information, which is specific to a processor architecture. In addition, certain processor architecture state at the time of error may also be captured in this section. This section is unique to each processor architecture (Itanium Processor Family, IA32/X64, ARM).

N.2.4.1 Generic Processor Error Section

The Generic Processor Error Section describes processor reported hardware errors for logical processors in the system.

Section Type: \{0x9876CCAD, 0x47B4, 0x4bdb, \{0xB6, 0x5E, 0x16, 0xF1, 0x93, 0xC4, 0xF3, 0xDB\}\}
The validation bit mask indicates whether or not each of the following fields is valid in this section.

<table>
<thead>
<tr>
<th>Bit</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>Processor Type Valid</td>
</tr>
<tr>
<td>1</td>
<td>Processor ISA Valid</td>
</tr>
<tr>
<td>2</td>
<td>Processor Error Type Valid</td>
</tr>
<tr>
<td>3</td>
<td>Operation Valid</td>
</tr>
<tr>
<td>4</td>
<td>Flags Valid</td>
</tr>
<tr>
<td>5</td>
<td>Level Valid</td>
</tr>
<tr>
<td>6</td>
<td>CPU Version Valid</td>
</tr>
<tr>
<td>7</td>
<td>CPU Brand Info Valid</td>
</tr>
<tr>
<td>8</td>
<td>CPU Id Valid</td>
</tr>
<tr>
<td>9</td>
<td>Target Address Valid</td>
</tr>
<tr>
<td>10</td>
<td>Requester Identifier Valid</td>
</tr>
<tr>
<td>11</td>
<td>Responder Identifier Valid</td>
</tr>
<tr>
<td>12</td>
<td>Instruction IP Valid</td>
</tr>
<tr>
<td></td>
<td>All other bits are reserved and must be zero.</td>
</tr>
</tbody>
</table>

Identifies the type of the processor architecture.

<table>
<thead>
<tr>
<th>Processor Type</th>
<th>8</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>IA32/X64</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>IA64</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>ARM</td>
<td></td>
</tr>
<tr>
<td></td>
<td>All other values reserved.</td>
<td></td>
</tr>
</tbody>
</table>

Identifies the type of the instruction set executing when the error occurred:

<table>
<thead>
<tr>
<th>Processor ISA</th>
<th>9</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>IA32</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>IA64</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>X64</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>ARM A32/T32</td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>ARM A64</td>
<td></td>
</tr>
<tr>
<td></td>
<td>All other values are reserved.</td>
<td></td>
</tr>
</tbody>
</table>

Indicates the type of error that occurred:

<table>
<thead>
<tr>
<th>Processor Error Type</th>
<th>10</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>Unknown</td>
<td></td>
</tr>
<tr>
<td>0x01</td>
<td>Cache Error</td>
<td></td>
</tr>
<tr>
<td>0x02</td>
<td>TLB Error</td>
<td></td>
</tr>
<tr>
<td>0x04</td>
<td>Bus Error</td>
<td></td>
</tr>
<tr>
<td>0x08</td>
<td>Micro-Architectural Error</td>
<td></td>
</tr>
<tr>
<td></td>
<td>All other values reserved.</td>
<td></td>
</tr>
</tbody>
</table>

continues on next page
| Operation | 11 | 1 | Indicates the type of operation:  
0: Unknown or generic  
1: Data Read  
2: Data Write  
3: Instruction Execution  
All other values reserved. |
|-----------|----|---|---|
| Flags     | 12| 1 | Indicates additional information about the error:  
Bit 0: Restartable - If 1, program execution can be restarted reliably after the error.  
Bit 1: Precise IP - If 1, the instruction IP captured is directly associated with the error.  
Bit 2: Overflow - If 1, a machine check overflow occurred (a second error occurred while the results of a previous error were still in the error reporting resources).  
Bit 3: Corrected - If 1, the error was corrected by hardware and/or firmware.  
All other bits are reserved and must be zero. |
| Level     | 13| 1 | Level of the structure where the error occurred, with 0 being the lowest level of cache. |
| Reserved  | 14| 2 | Must be zero. |
| CPU Version Info | 16| 8 | This field represents the CPU Version Information and returns Family, Model, and stepping information (e.g. As provided by CPUID instruction with EAX=1 input with output values from EAX on the IA32/X64 processor or as provided by CPUID Register 3 register - Version Information on IA64 processors).  
On ARM processors, this field will be provided as:  
Bits 127:64 - Reserved and must be zero  
Bits 63:0 - MIDR_EL1 of the processor |
| CPU Brand String | 24| 128 | This field represents the null-terminated ASCII Processor Brand String (e.g. As provided by the CPUID instruction with EAX=0x80000002 and ECX=0x80000003 for IA32/X64 processors or the return from PAL_BRAND_INFO for IA64 processors).  
This field is optional for ARM processors. |

continues on next page
### Table N.6 – continued from previous page

| Processor ID | 152 | 8 | This value uniquely identifies the logical processor (e.g. As programmed into the local APIC ID register on IA32/X64 processors or programmed into the LID register on IA64 processors). On ARM processors, this field will be provided as programmed in the architected MPIDR_EL1. |
| Target Address | 160 | 8 | Identifies the target address associated with the error. |
| Requestor Identifier | 168 | 8 | Identifies the requestor associated with the error. |
| Responder Identifier | 176 | 8 | Identifies the responder associated with the error. |
| Instruction IP | 184 | 8 | Identifies the instruction pointer when the error occurred. |

### N.2.4.2 IA32/X64 Processor Error Section

Type: \{0xDC3EA0B0, 0xA144, 0x4797, \{0xB9, 0x5B, 0x53, 0xFA, 0x24, 0x2B, 0x6E, 0x1D\}\}

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
</table>
| Validation Bits | 0 | 8 | The validation bit mask indicates each of the following field is valid in this section:  
Bit0 - LocalAPIC_ID Valid  
Bit1 - CPUID Info Valid  
Bits 2-7 - Number of Processor Error Information Structure (PROC_ERR_INFO_NUM)  
Bit 8-13 Number of Processor Context Information Structure (PROC_CONTEXT_INFO_NUM)  
Bits 14-63 - Reserved |
| Local APIC_ID | 8 | 8 | This is the processor APIC ID programmed into the APIC ID registers. |
| CPUID Info | 16 | 48 | This field represents the CPU ID structure of 48 bytes and returns Model, Family, and stepping information as provided by the CPUID instruction with EAX=1 input and output values from EAX, EBX, ECX, and EDX null extended to 64-bits. |
| Processor Error Info | 64 | Nx64 | This is a variable-length structure consisting of N different 64 byte structures, each representing a single processor error information structure. The value of N ranges from 0-63 and is as indicated by PROC_ERR_INFO_NUM. |
| Processor Context | 64+Nx64 | NxX | This is a variable size field providing the information for the processor context state such as MC Bank MSRs and general registers. The value of N ranges from 0-63 and is as indicated by PROC_CONTEXT_INFO_NUM. Each processor context information structure is padded with zeros if the size is not a multiple of 16 bytes. |
N.2.4.2.1 IA32/X64 Processor Error Information Structure

As described above, the processor error section contains a collection of structures called Processor Error Information Structures that contain processor structure specific error information. This section details the layout of the Processor Error Information Structure and the detailed check information which is contained within.

Table N.8: IA32/X64 Processor Error Information Structure

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Error Structure Type</td>
<td>0</td>
<td>16</td>
<td>This field holds a pre-assigned GUID indicating the type of Processor Error Information structure. The following Processor Error Information Structure Types have pre-defined GUID. • Cache Error Information (Cache Check) • TLB Error Information (TLB Check) • Bus Error Information (Bus Check) • Micro-architecture Specific Error Information (MS Check)</td>
</tr>
<tr>
<td>Validation Bits</td>
<td>16</td>
<td>8</td>
<td>Bit 0 - Check Info Valid Bit 1 - Target Address Identifier Valid Bit 2 - Requestor Identifier Valid Bit 3 - Responder Identifier Valid Bit 4 - Instruction Pointer Valid Bits 5-63 - Reserved</td>
</tr>
<tr>
<td>Check Information</td>
<td>24</td>
<td>8</td>
<td>StructureErrorType specific error check structure.</td>
</tr>
<tr>
<td>Target Identifier</td>
<td>32</td>
<td>8</td>
<td>Identifies the target associated with the error.</td>
</tr>
<tr>
<td>Requestor Identifier</td>
<td>40</td>
<td>8</td>
<td>Identifies the requestor associated with the error.</td>
</tr>
<tr>
<td>Responder Identifier</td>
<td>48</td>
<td>8</td>
<td>Identifies the responder associated with the error.</td>
</tr>
<tr>
<td>Instruction Pointer</td>
<td>56</td>
<td>8</td>
<td>Identifies the instruction executing when the error occurred.</td>
</tr>
</tbody>
</table>

N.2.4.2.2 IA32/X64 Cache Check Structure

Type:{0xA55701F5, 0xE3EF, 0x43de, {0xAC, 0x72, 0x24, 0x9B, 0x3F, 0xAD, 0x2C}}

Table N.9: IA32/X64 Cache Check Structure

<table>
<thead>
<tr>
<th>Field Name</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>continues on next page</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Field</td>
<td>Offset</td>
<td>Description</td>
</tr>
<tr>
<td>------------------</td>
<td>--------</td>
<td>-----------------------------------------------------------------------------</td>
</tr>
<tr>
<td>Validation Bits</td>
<td>15:0</td>
<td>Indicates which fields in the Cache Check structure are valid:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 0 - Transaction Type Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 1 - Operation Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 2 - Level Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 3 - Processor Context Corrupt Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 4 - Uncorrected Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 5 - Precise IP Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 6 - Restartable Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 7 - Overflow Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bits 8 - 15 Reserved</td>
</tr>
<tr>
<td>Transaction Type</td>
<td>17:16</td>
<td>Type of cache error:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 - Instruction</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - Data Access</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 - Generic</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All other values are reserved</td>
</tr>
<tr>
<td>Operation</td>
<td>21:18</td>
<td>Type of cache operation that caused the error:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 - generic error (type of error cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - generic read (type of instruction or data request cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 - generic write (type of instruction or data request cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3 - data read</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4 - data write</td>
</tr>
<tr>
<td></td>
<td></td>
<td>5 - instruction fetch</td>
</tr>
<tr>
<td></td>
<td></td>
<td>6 - prefetch</td>
</tr>
<tr>
<td></td>
<td></td>
<td>7 - eviction</td>
</tr>
<tr>
<td></td>
<td></td>
<td>8 - snoop</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All other values are reserved</td>
</tr>
<tr>
<td>Level</td>
<td>24:22</td>
<td>Cache Level</td>
</tr>
<tr>
<td>Processor Context Corrupt</td>
<td>25</td>
<td>This field indicates that the processor context might have been corrupted.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 - Processor context not corrupted</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - Processor context corrupted</td>
</tr>
<tr>
<td>Uncorrected</td>
<td>26</td>
<td>This field indicates whether the error was corrected or uncorrected:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0: Corrected</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1: Uncorrected</td>
</tr>
<tr>
<td>Precise IP</td>
<td>27</td>
<td>This field indicates that the instruction pointer pushed onto the stack is directly associated with the error</td>
</tr>
<tr>
<td>Restartable IP</td>
<td>28</td>
<td>This field indicates that program execution can be restarted reliably at the instruction pointer pushed onto the stack</td>
</tr>
</tbody>
</table>
Overflow | 29 |
---|---|
This field indicates an error overflow occurred
0 - Overflow not occurred
1 - Overflow occurred

63:30 | Reserved |

### N.2.4.2.3 IA32/X64 TLB Check Structure

Type: `{0xFC06B535, 0x5E1F, 0x4562, {0x9F, 0x25, 0x0A, 0x3B, 0x9A, 0xDB, 0x63, 0xC3}}`

#### Table N.10: IA32/X64 TLB Check Structure

<table>
<thead>
<tr>
<th>Field Name</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Validation Bits</td>
<td>15:0</td>
<td>Indicate which fields in the Cache_Check structure are valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 0 - Transaction Type Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 1 - Operation Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 2 - Level Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 3 - Processor Context Corrupt Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 4 - Uncorrected Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 5 - Precise IP Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 6 - Restartable IP Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 7 - Overflow Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 8 - 15 Reserved</td>
</tr>
<tr>
<td>Transaction Type</td>
<td>17:16</td>
<td>Type of TLB error</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 - Instruction</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - Data Access</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 - Generic</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All other values are reserved</td>
</tr>
<tr>
<td>Operation</td>
<td>21:18</td>
<td>Type of TLB access operation that caused the machine check:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 - generic error (type of error cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - generic read (type of instruction or data request cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 - generic write (type of instruction or data request cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3 - data read</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4 - data write</td>
</tr>
<tr>
<td></td>
<td></td>
<td>5 - instruction fetch</td>
</tr>
<tr>
<td></td>
<td></td>
<td>6 - prefetch</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All other values are reserved</td>
</tr>
<tr>
<td>Level</td>
<td>24:22</td>
<td>TLB Level</td>
</tr>
</tbody>
</table>

continues on next page
### Processor Context Corrupt 25
This field indicates that the processor context might have been corrupted.

- 0: Processor context not corrupted
- 1: Processor context corrupted

### Uncorrected 26
This field indicates whether the error was corrected or uncorrected:

- 0: Corrected
- 1: Uncorrected

### PreciseIP 27
This field indicates that the instruction pointer pushed onto the stack is directly associated with the error.

### Restartable IP 28
This field indicates the program execution can be restarted reliably at the instruction pointer pushed onto the stack.

### Overflow 29
This field indicates an error overflow occurred

- 0: Overflow not occurred
- 1: Overflow occurred

### Reserved 63:30

---

### N.2.4.2.4 IA32/X64 Bus Check Structure

Type: `{0xCF3F8B3, 0xC5B1, 0x49a2, {0xAA, 0x59, 0x5E, 0xEF, 0x92, 0xFF, 0xA6, 0x3C}}`

#### Table N.11: IA32/X64 Bus Check Structure

<table>
<thead>
<tr>
<th>Field Name</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Validation Bits</td>
<td>15:0</td>
<td>Indicate which fields in the Bus_Check structure are valid</td>
</tr>
<tr>
<td>Bit 0 - Transaction Type Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 1 - Operation Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 2 - Level Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 3 - Processor Context Corrupt Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 4 - Uncorrected Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 5 - Precise IP Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 6 - Restartable IP Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 7 - Overflow Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 8 - Participation Type Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 9 - Time Out Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 10 - Address Space Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 11 - 15 Reserved</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

continues on next page
| Transaction Type | 17:16 | Type of Bus error  
0 - Instruction  
1 - Data Access  
2 - Generic  
All other values are reserved |
|------------------|-------|-------------------------|
| Operation        | 21:18 | Type of bus access operation that caused the machine check:  
0 - generic error (type of error cannot be determined)  
1 - generic read (type of instruction or data request cannot be determined)  
2 - generic write (type of instruction or data request cannot be determined)  
3 - data read  
4 - data write  
5 - instruction fetch  
6 - prefetch All other values are reserved. |
| Level            | 24:22 | Indicate which level of the bus hierarchy the error occurred in. |
| Processor Context Corrupt | 25 | This field indicates that the processor context might have been corrupted.  
0 - Processor context not corrupted  
1 - Processor context corrupted |
| Uncorrected      | 26   | This field indicates whether the error was corrected or uncorrected:  
0: Corrected  
1: Uncorrected |
| PreciseIP        | 27   | This field indicates that the instruction pointer pushed onto the stack is directly associated with the error. |
| Restartable IP   | 28   | This field indicates the program execution can be restarted reliably at the instruction pointer pushed onto the stack. |
| Overflow         | 29   | This field indicates an error overflow occurred  
0 - Overflow not occurred  
1 - Overflow occurred |
| Participation Type | 31:30 | Type of Participation  
0 - Local Processor originated request  
1 - Local processor Responded to request  
2 - Local processor Observed  
3 - Generic |
| Time Out         | 32   | This field indicates that the request timed out. |

continues on next page
### Table N.11 – continued from previous page

<table>
<thead>
<tr>
<th>Address Space</th>
<th>34:33</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x0</td>
<td></td>
<td>0 - Memory Access</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - Reserved</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 - I/O</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3 - Other Transaction</td>
</tr>
<tr>
<td>63:35</td>
<td></td>
<td>Reserved</td>
</tr>
</tbody>
</table>

#### N.2.4.2.5 IA32/X64 MS Check Field Description

Type: \{0x48AB7F57, 0xDC34, 0x4f6c, \{0xA7, 0xD3, 0xB0, 0xB5, 0xB0, 0xA7, 0x43, 0x14\}\}

**Table N.12: IA32/X64 MS Check Field Description**

<table>
<thead>
<tr>
<th>Field Name</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Validation Bits</td>
<td>15:0</td>
<td>Indicate which fields in the Cache_Check structure are valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 0 - Error Type Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 1 - Processor Context Corrupt Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 2 - Uncorrected Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 3 - Precise IP Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 4 - Restartable IP Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 5 - Overflow Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 6 - 15 Reserved</td>
</tr>
<tr>
<td>Error Type</td>
<td>18:16</td>
<td>Identifies the operation that caused the error:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 - No Error</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - Unclassified</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 - Microcode ROM Parity Error</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3 - External Error</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4 - FRC Error</td>
</tr>
<tr>
<td></td>
<td></td>
<td>5 - Internal Unclassified</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All other value are processor specific.</td>
</tr>
<tr>
<td>Processor Context Corrupt</td>
<td>19</td>
<td>This field indicates that the processor context might have been corrupted.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 - Processor context not corrupted</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - Processor context corrupted</td>
</tr>
<tr>
<td>Uncorrected</td>
<td>20</td>
<td>This field indicates whether the error was corrected or uncorrected:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0: Corrected</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1: Uncorrected</td>
</tr>
<tr>
<td>Precise IP</td>
<td>21</td>
<td>This field indicates that the instruction pointer pushed onto the stack is directly associated with the error.</td>
</tr>
</tbody>
</table>
Table N.12 – continued from previous page

| Restartable IP | 22 | This field indicates the program execution can be restarted reliably at the instruction pointer pushed onto the stack. |
| Overflow | 23 | This field indicates an error overflow occurred  
0 - Overflow not occurred  
1 - Overflow occurred |
| 63:24 | Reserved |

**N.2.4.2.6 IA32/X64 Processor Context Information Structure**

As described above, the processor error section contains a collection of structures called Processor Context Information that contain processor context state specific to the IA32/X64 processor architecture. This section details the layout of the Processor Context Information Structure and the detailed processor context type information.

Table N.13: IA32/X64 Processor Context Information

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
</table>
| Register Context Type | 0 | 2 bytes | Value indicating the type of processor context state being reported:  
0 - Unclassified Data  
1 - MSR Registers (Machine Check and other MSRs)  
2 - 32-bit Mode Execution Context  
3 - 64-bit Mode Execution Context  
4 - FXSAVE Context  
5 - 32-bit Mode Debug Registers (DR0-DR7)  
6 - 64-bit Mode Debug Registers (DR0-DR7)  
7 - Memory Mapped Registers  
Others - Reserved |
| Register Array Size | 2 | 2 bytes | Represents the total size of the array for the Data Type being reported in bytes. |
| MSR Address | 4 | 4 bytes | This field contains the starting MSR address for the type 1 register context. |
| MM Register Address | 8 | 8 bytes | This field contains the starting memory address for the type 7 register context. |
| Register Array | 16 | N bytes | This field will provide the contents of the actual registers or raw data. The number of Registers or size of the raw data reported is determined by (Array Size / 8) or otherwise specified by the context structure type definition. |

The Table below shows the register context type 2, 32-bit mode execution context.

Table N.14: IA32 Register State

<table>
<thead>
<tr>
<th>Offset</th>
<th>Length</th>
<th>Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>4 bytes</td>
<td>EAX</td>
</tr>
<tr>
<td>4</td>
<td>4 bytes</td>
<td>EBX</td>
</tr>
</tbody>
</table>

continues on next page
### Table N.14 – continued from previous page

<table>
<thead>
<tr>
<th>Offset</th>
<th>Length</th>
<th>Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>8</td>
<td>4 bytes</td>
<td>ECX</td>
</tr>
<tr>
<td>12</td>
<td>4 bytes</td>
<td>EDX</td>
</tr>
<tr>
<td>16</td>
<td>4 bytes</td>
<td>ESI</td>
</tr>
<tr>
<td>20</td>
<td>4 bytes</td>
<td>EDI</td>
</tr>
<tr>
<td>24</td>
<td>4 bytes</td>
<td>EBP</td>
</tr>
<tr>
<td>28</td>
<td>4 bytes</td>
<td>ESP</td>
</tr>
<tr>
<td>32</td>
<td>2 bytes</td>
<td>CS</td>
</tr>
<tr>
<td>34</td>
<td>2 bytes</td>
<td>DS</td>
</tr>
<tr>
<td>36</td>
<td>2 bytes</td>
<td>SS</td>
</tr>
<tr>
<td>38</td>
<td>2 bytes</td>
<td>ES</td>
</tr>
<tr>
<td>40</td>
<td>2 bytes</td>
<td>FS</td>
</tr>
<tr>
<td>42</td>
<td>2 bytes</td>
<td>GS</td>
</tr>
<tr>
<td>44</td>
<td>4 bytes</td>
<td>EFLAGS</td>
</tr>
<tr>
<td>48</td>
<td>4 bytes</td>
<td>EIP</td>
</tr>
<tr>
<td>52</td>
<td>4 bytes</td>
<td>CR0</td>
</tr>
<tr>
<td>56</td>
<td>4 bytes</td>
<td>CR1</td>
</tr>
<tr>
<td>60</td>
<td>4 bytes</td>
<td>CR2</td>
</tr>
<tr>
<td>64</td>
<td>4 bytes</td>
<td>CR3</td>
</tr>
<tr>
<td>68</td>
<td>4 bytes</td>
<td>CR4</td>
</tr>
<tr>
<td>72</td>
<td>8 bytes</td>
<td>GDTR</td>
</tr>
<tr>
<td>80</td>
<td>8 bytes</td>
<td>IDTR</td>
</tr>
<tr>
<td>88</td>
<td>2 bytes</td>
<td>LDTR</td>
</tr>
<tr>
<td>90</td>
<td>2 bytes</td>
<td>TR</td>
</tr>
</tbody>
</table>

See the Table below for the register context type 3, 64-bit mode execution context.

### Table N.15: X64 Register State

<table>
<thead>
<tr>
<th>Offset</th>
<th>Length</th>
<th>Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>8 bytes</td>
<td>RAX</td>
</tr>
<tr>
<td>8</td>
<td>8 bytes</td>
<td>RBX</td>
</tr>
<tr>
<td>16</td>
<td>8 bytes</td>
<td>RCX</td>
</tr>
<tr>
<td>24</td>
<td>8 bytes</td>
<td>RDX</td>
</tr>
<tr>
<td>32</td>
<td>8 bytes</td>
<td>RSI</td>
</tr>
<tr>
<td>40</td>
<td>8 bytes</td>
<td>RDI</td>
</tr>
<tr>
<td>48</td>
<td>8 bytes</td>
<td>RBP</td>
</tr>
<tr>
<td>56</td>
<td>8 bytes</td>
<td>RSP</td>
</tr>
<tr>
<td>64</td>
<td>8 bytes</td>
<td>R8</td>
</tr>
<tr>
<td>72</td>
<td>8 bytes</td>
<td>R9</td>
</tr>
<tr>
<td>80</td>
<td>8 bytes</td>
<td>R10</td>
</tr>
<tr>
<td>88</td>
<td>8 bytes</td>
<td>R11</td>
</tr>
<tr>
<td>96</td>
<td>8 bytes</td>
<td>R12</td>
</tr>
<tr>
<td>104</td>
<td>8 bytes</td>
<td>R13</td>
</tr>
<tr>
<td>112</td>
<td>8 bytes</td>
<td>R14</td>
</tr>
<tr>
<td>120</td>
<td>8 bytes</td>
<td>R15</td>
</tr>
<tr>
<td>128</td>
<td>2 bytes</td>
<td>CS</td>
</tr>
<tr>
<td>130</td>
<td>2 bytes</td>
<td>DS</td>
</tr>
<tr>
<td>132</td>
<td>2 bytes</td>
<td>SS</td>
</tr>
<tr>
<td>134</td>
<td>2 bytes</td>
<td>ES</td>
</tr>
<tr>
<td>136</td>
<td>2 bytes</td>
<td>FS</td>
</tr>
<tr>
<td>138</td>
<td>2 bytes</td>
<td>GS</td>
</tr>
</tbody>
</table>

continues on next page
Table N.15 – continued from previous page

<table>
<thead>
<tr>
<th>Offset</th>
<th>8 bytes</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>144</td>
<td>Reserved</td>
<td></td>
</tr>
<tr>
<td>152</td>
<td>EIP</td>
<td></td>
</tr>
<tr>
<td>160</td>
<td>CR0</td>
<td></td>
</tr>
<tr>
<td>168</td>
<td>CR1</td>
<td></td>
</tr>
<tr>
<td>176</td>
<td>CR2</td>
<td></td>
</tr>
<tr>
<td>184</td>
<td>CR3</td>
<td></td>
</tr>
<tr>
<td>192</td>
<td>CR4</td>
<td></td>
</tr>
<tr>
<td>200</td>
<td>CR8</td>
<td></td>
</tr>
<tr>
<td>208</td>
<td>GDTR</td>
<td></td>
</tr>
<tr>
<td>224</td>
<td>IDTR</td>
<td></td>
</tr>
<tr>
<td>240</td>
<td>LDTR</td>
<td></td>
</tr>
<tr>
<td>242</td>
<td>TR</td>
<td></td>
</tr>
</tbody>
</table>

### N.2.4.3 IA64 Processor Error Section

Refer to the Intel Itanium Processor Family System Abstraction Layer specification for finding the IA64 specific error section body definition.

### N.2.4.4 ARM Processor Error Section

Type: `{0xE19E3D16, 0xBC11, 0x11E4, {0x9C, 0xAA, 0xC2, 0x05, 0x1D, 0x5D, 0x46, 0xB0}}`

The ARM Processor Error Section may contain multiple instances of error information structures associated to a single error event. An error may propagate to other hardware components (e.g. poisoned data) or cause subsequent errors, all of which may be captured in a single ARM processor error section. The processor context information describes the observed state of the processor at the point of error detection.

It is optional for vendors to capture processor context information. The specifics of capturing processor context is vendor specific. Vendors must take care when handling errors that have originated whilst a processor was executing in a secure exception level. In those cases providing processor context information to non-secure agents could be unsafe and lead to security attacks.

Table N.16: ARM Processor Error Section

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Validation Bit</td>
<td>0</td>
<td>4</td>
<td>The validation bit mask indicates whether or not each of the following fields is valid in this section. Bit 0 - MPIDR Valid Bit 1 - Error affinity level Valid Bit 2 - Running State Bit 3 - Vendor Specific Info Valid All other bits are reserved and must be zero.</td>
</tr>
<tr>
<td>ERR_INFO_NUM</td>
<td>2</td>
<td></td>
<td>ERR_INFO_NUM is the number of Processor Error Information Structures (must be 1 or greater)</td>
</tr>
<tr>
<td>CONTEXT_INFO_NUM</td>
<td>6</td>
<td>2</td>
<td>C ONTEXT_INFO_NUM is the number of Context Information Structures</td>
</tr>
</tbody>
</table>

continues on next page
This describes the total size of the ARM processor error section

<table>
<thead>
<tr>
<th>Section</th>
<th>Length</th>
<th>This describes the total size of the ARM processor error section</th>
</tr>
</thead>
<tbody>
<tr>
<td>Error affinity level</td>
<td>12</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td></td>
<td>For example, a vendor may choose to define affinity levels as follows:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Level 0: errors that can be precisely attributed to a specific CPU (e.g. due to a synchronous external abort)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Level 1: Cache parity and/or ECC errors detected at cache of affinity level 1 (e.g. only attributed to higher level cache due to prefetching and/or error propagation)</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>NOTE</strong>: Detailed meanings and groupings of affinity level are chip and/or platform specific. The affinity level described here must be consistent with the platform definitions used MPIDR. For cache/TLB errors, the cache/TLB level is provided by the cache/TLB error structure, which may differ from affinity level.</td>
</tr>
<tr>
<td>Reserved</td>
<td>13</td>
<td>3</td>
</tr>
<tr>
<td>MPIR_EL1</td>
<td>16</td>
<td>8</td>
</tr>
<tr>
<td>MIDR_EL1</td>
<td>24</td>
<td>8</td>
</tr>
<tr>
<td>Running State</td>
<td>32</td>
<td>4</td>
</tr>
<tr>
<td>PSCI State</td>
<td>36</td>
<td>4</td>
</tr>
<tr>
<td>Processor Error Information Structure</td>
<td>40</td>
<td>Nx32</td>
</tr>
<tr>
<td>Processor Context</td>
<td>40 + Nx32</td>
<td>MxP</td>
</tr>
<tr>
<td>Vendor Specific Error Info</td>
<td>40 + Nx32 + MxP</td>
<td>vendor specific</td>
</tr>
</tbody>
</table>
N.2.4.4.1 ARM Processor Error Information

As described above, the processor error section contains a collection of *Processor Error Information* structures that contain processor specific error information. This section details the layout of the Processor Error Information structure and the detailed information which is contained within.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Version</td>
<td>0</td>
<td>1</td>
<td>0 (revision of this table)</td>
</tr>
<tr>
<td>Length</td>
<td>1</td>
<td>1</td>
<td>32 (length in bytes)</td>
</tr>
<tr>
<td>Validation Bit</td>
<td>2</td>
<td>2</td>
<td>The validation bit mask indicates whether or not each of the following fields is valid in this section. Bit 0 - Multiple Error (Error Count) Valid Bit 1 - Flags Valid Bit 2 - Error Information Valid Bit 3 - Virtual Fault Address Bit 4 - Physical Fault Address All other bits are reserved and must be zero.</td>
</tr>
<tr>
<td>Type</td>
<td>4</td>
<td>1</td>
<td>Bit 1 - Cache Error Bit 2 - TLB Error Bit 3 - Bus Error Bit 4 - Micro-architectural Error All other values are reserved</td>
</tr>
<tr>
<td>Multiple Error (Error Count)</td>
<td>5</td>
<td>2</td>
<td>This field indicates whether multiple errors have occurred. In the case of multiple error with a valid count, this field will specify the error count. The value of this field is defined as follows: 0: Single Error 1: Multiple Errors 2-65535: Error Count (if known)</td>
</tr>
<tr>
<td>Flags</td>
<td>7</td>
<td>1</td>
<td>This field indicates flags that describe the error attributes. The value of this field is defined as follows: Bit 0 - First error captured Bit 1 - Last error captured Bit 2 - Propagated Bit 3 - Overflow All other bits are reserved and must be zero <strong>Note:</strong> The overflow bit indicates when firmware/hardware error buffers experience an overflow, so it is possible that some error information has been lost.</td>
</tr>
</tbody>
</table>

continues on next page
Table N.17 – continued from previous page

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Error Information</td>
<td>8</td>
<td>8</td>
<td>The error information structure is specific to each error type (described in tables below)</td>
</tr>
<tr>
<td>Virtual Fault Address</td>
<td>16</td>
<td>8</td>
<td>If known, this field indicates a virtual fault address associated with the error (e.g. when an error occurs in virtually indexed cache)</td>
</tr>
<tr>
<td>Physical Fault Address</td>
<td>24</td>
<td>8</td>
<td>If known, this field indicates a physical fault address associated with the error</td>
</tr>
</tbody>
</table>

See the 4 Tables directly below for more error information: *Arm Cache Error Structure*, *ARM TLB Error Structure*, *ARM Bus Error Structure*, and *ARM Processor Error Context Information Header Structure*.

Table N.18: ARM Cache Error Structure

<table>
<thead>
<tr>
<th>Name</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Validation Bit</td>
<td>15:0</td>
<td>Indicates which fields in the Cache Check structure are valid:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 0 - Transaction Type Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 1 - Operation Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 2 - Level Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 3 - Processor Context Corrupt Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 4 - Corrected Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 5 - Precise PC Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Bit 6 - Restartable PC Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All other bits are reserved and must be zero.</td>
</tr>
<tr>
<td>Transaction Type</td>
<td>17:16</td>
<td>Type of cache error:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 - Instruction</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - Data Access</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 - Generic</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All other values are reserved</td>
</tr>
</tbody>
</table>

continues on next page
#### Table N.18 – continued from previous page

<table>
<thead>
<tr>
<th>Operation</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>21:18</td>
<td>Type of cache operation that caused the error:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 - generic error (type of error cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - generic read (type of instruction or data request cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 - generic write (type of instruction or data request cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3 - data read</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4 - data write</td>
</tr>
<tr>
<td></td>
<td></td>
<td>5 - instruction fetch</td>
</tr>
<tr>
<td></td>
<td></td>
<td>6 - prefetch</td>
</tr>
<tr>
<td></td>
<td></td>
<td>7 - eviction</td>
</tr>
<tr>
<td></td>
<td></td>
<td>8 - snooping (the processor described in this record initiated a cache snoop that resulted in an error)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>9 - snooped (The processor described in this record raised a cache error caused by another processor or device snooping into its cache)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>10 - management</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All other values are reserved.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Level</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>24:22</td>
<td>Cache level</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Processor Context Corrupt</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>25</td>
<td>This field indicates that the processor context might have been corrupted.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0 - Processor context not corrupted</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - Processor context corrupted</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Corrected</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>26</td>
<td>This field indicates whether the error was corrected or uncorrected:</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1: Corrected</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0: Uncorrected</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Precise PC</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>27</td>
<td>This field indicates that the program counter that is directly associated with the error</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Restartable PC</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>28</td>
<td>This field indicates that program execution can be restarted reliably at the PC associated with the error</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Reserved</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>63:29</td>
<td>Must be zero</td>
</tr>
</tbody>
</table>

#### Table N.19: ARM TLB Error Structure

<table>
<thead>
<tr>
<th>Name</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Validation Bit</td>
<td>15:0</td>
<td>Indicates which fields in the TLB error structure are valid:</td>
</tr>
<tr>
<td>Transaction Type</td>
<td>17:16</td>
<td>Type of TLB error: 0 - Instruction 1 - Data Access 2 - Generic All other values are reserved</td>
</tr>
</tbody>
</table>

continues on next page
Table N.19 – continued from previous page

<table>
<thead>
<tr>
<th>Operation</th>
<th>21:18</th>
<th>Type of TLB operation that caused the error:</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>0 - generic error (type of error cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>1 - generic read (type of instruction or data request cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>2 - generic write (type of instruction or data request cannot be determined)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3 - data read</td>
</tr>
<tr>
<td></td>
<td></td>
<td>4 - data write</td>
</tr>
<tr>
<td></td>
<td></td>
<td>5 - instruction fetch</td>
</tr>
<tr>
<td></td>
<td></td>
<td>6 - prefetch</td>
</tr>
<tr>
<td></td>
<td></td>
<td>7 - local management operation (the processor described in this record initiated a TLB management operation that resulted in an error)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>8 - external management operation (the processor described in this record raised a TLB error caused by another processor or device broadcasting TLB operations)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>All other values are reserved.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Level</th>
<th>24:22</th>
<th>TLB level</th>
</tr>
</thead>
</table>

| Processor Context Corrupt | 25 | This field indicates that the processor context might have been corrupted. |
|                          |    | 0 - Processor context not corrupted |
|                          |    | 1 - Processor context corrupted |

| Corrected | 26 | This field indicates whether the error was corrected or uncorrected: 1: Corrected 0: Uncorrected |

| Precise PC | 27 | This field indicates that the program counter that is directly associated with the error |

| Restartable PC | 28 | This field indicates that program execution can be restarted reliably at the PC associated with the error. |

| Reserved | 63:29 | Must be zero. |

Table N.20: ARM Bus Error Structure

<table>
<thead>
<tr>
<th>Name</th>
<th>Bits</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>continues on next page</td>
</tr>
</tbody>
</table>
Table N.20 – continued from previous page

<table>
<thead>
<tr>
<th>Validation Bit</th>
<th>15:0</th>
</tr>
</thead>
<tbody>
<tr>
<td>Indicates which fields in the Bus error structure are valid: Bit</td>
<td></td>
</tr>
<tr>
<td>0 - Transaction Type Valid</td>
<td></td>
</tr>
<tr>
<td>Bit 1 - Operation Valid</td>
<td></td>
</tr>
<tr>
<td>Bit 2 - Level Valid</td>
<td></td>
</tr>
<tr>
<td>Bit 3 - Processor Context Corrupt Valid</td>
<td></td>
</tr>
<tr>
<td>Bit 4 - Corrected Valid</td>
<td></td>
</tr>
<tr>
<td>Bit 5 - Precise PC Valid</td>
<td></td>
</tr>
<tr>
<td>Bit 6 - Restartable PC Valid</td>
<td></td>
</tr>
<tr>
<td>Bit 7 - Participation Type Valid</td>
<td></td>
</tr>
<tr>
<td>Bit 8 - Time Out Valid</td>
<td></td>
</tr>
<tr>
<td>Bit 9 - Address Space Valid</td>
<td></td>
</tr>
<tr>
<td>Bit 10 - Memory Attributes Valid</td>
<td></td>
</tr>
<tr>
<td>Bit 11 - Access Mode valid</td>
<td></td>
</tr>
<tr>
<td>All other bits are reserved and must be zero.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Transaction Type</th>
<th>17:16</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type of bus error:</td>
<td></td>
</tr>
<tr>
<td>0 - Instruction</td>
<td></td>
</tr>
<tr>
<td>1 - Data Access</td>
<td></td>
</tr>
<tr>
<td>2 - Generic</td>
<td></td>
</tr>
<tr>
<td>All other values are reserved</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Operation</th>
<th>21:18</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type of bus operation that caused the error:</td>
<td></td>
</tr>
<tr>
<td>0 - generic error (type of error cannot be determined)</td>
<td></td>
</tr>
<tr>
<td>1 - generic read (type of instruction or data request cannot be determined)</td>
<td></td>
</tr>
<tr>
<td>2 - generic write (type of instruction or data request cannot be determined)</td>
<td></td>
</tr>
<tr>
<td>3 - data read</td>
<td></td>
</tr>
<tr>
<td>4 - data write</td>
<td></td>
</tr>
<tr>
<td>5 - instruction fetch</td>
<td></td>
</tr>
<tr>
<td>6 - prefetch</td>
<td></td>
</tr>
<tr>
<td>All other values are reserved.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Level</th>
<th>24:22</th>
</tr>
</thead>
<tbody>
<tr>
<td>Affinity level at which the bus error occurred</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Processor Context Corrupt</th>
<th>25</th>
</tr>
</thead>
<tbody>
<tr>
<td>This field indicates that the processor context might have been corrupted.</td>
<td></td>
</tr>
<tr>
<td>0 - Processor context not corrupted</td>
<td></td>
</tr>
<tr>
<td>1 - Processor context corrupted</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Corrected</th>
<th>26</th>
</tr>
</thead>
<tbody>
<tr>
<td>This field indicates whether the error was corrected or uncorrected: 1: Corrected</td>
<td></td>
</tr>
<tr>
<td>0: Uncorrected</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Precise PC</th>
<th>27</th>
</tr>
</thead>
<tbody>
<tr>
<td>This field indicates that the program counter that is directly associated with the error</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Restartable PC</th>
<th>28</th>
</tr>
</thead>
<tbody>
<tr>
<td>This field indicates that program execution can be restarted reliably at the PC associated with the error.</td>
<td></td>
</tr>
</tbody>
</table>

continues on next page
### Table N.20 – continued from previous page

<table>
<thead>
<tr>
<th>Participation Type</th>
<th>30:29</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type of Participation</td>
<td></td>
</tr>
<tr>
<td>0 - Local Processor originated request</td>
<td></td>
</tr>
<tr>
<td>1 - Local processor Responded to request</td>
<td></td>
</tr>
<tr>
<td>2 - Local processor Observed</td>
<td></td>
</tr>
<tr>
<td>3 - Generic</td>
<td></td>
</tr>
</tbody>
</table>

The usage of this field depends on the vendor, but the examples below provide some guidance on how this field is to be used:
- If bus error occurs on an LDR instruction, the local processor originated the request.
- If the bus error occurs due to a snoop operation, local processor responded to the request.
- If a bus error occurs due to cache prefetching and an SEI was sent to a particular CPU to notify this bus error has occurred, then the local processor only observed the error.

<table>
<thead>
<tr>
<th>Time Out</th>
<th>31</th>
</tr>
</thead>
<tbody>
<tr>
<td>This field indicates that the request timed out.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Address Space</th>
<th>33:32</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 - External Memory Access (e.g. DDR)</td>
<td></td>
</tr>
<tr>
<td>1 - Internal Memory Access (e.g. internal chip ROM)</td>
<td></td>
</tr>
<tr>
<td>3 - Device Memory Access</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Memory Access Attributes</th>
<th>42:34</th>
</tr>
</thead>
<tbody>
<tr>
<td>Memory attribute as described in the ARM ARM specification.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Access Mode</th>
<th>43</th>
</tr>
</thead>
<tbody>
<tr>
<td>Indicates whether the access was a secure or normal bus request</td>
<td></td>
</tr>
<tr>
<td>0 - secure</td>
<td></td>
</tr>
<tr>
<td>1 - normal</td>
<td></td>
</tr>
</tbody>
</table>

**Note:** A platform may choose to hide some or all of the error information for errors that are consumed/detected in the secure context.

<table>
<thead>
<tr>
<th>Reserved</th>
<th>63:44</th>
</tr>
</thead>
<tbody>
<tr>
<td>Must be zero.</td>
<td></td>
</tr>
</tbody>
</table>

### N.2.4.4.1.1 ARM Vendor Specific Micro-Architecture Error Structure

This is a vendor specific structure. Please refer to your hardware vendor documentation for the format of this structure.
N.2.4.4.2 ARM Processor Context Information

As described above, the processor error section contains a collection of structures called Processor Context Information. These provide processor context state specific to the ARM processor architecture. This section details the layout of the Processor Error Context Information Header Structure (See Table N-21, ARM Processor Error Context Information HeaderStructure) and the detailed processor context type information structures (See Table N-21 through Table N-30).

Care must be taken when reporting context information structures. The amount of context reported depends on the agent that is going to observe the data. The following are recommended guidelines:

1. If the error happens whilst the processor is in the secure world, EL3, Secure EL1 or secure EL0, context information can contain sensitive data, and should not be exposed to unauthorized parties.

2. If the error information is being provided to a software agent running at EL2, then the context information should only include any registers visible in EL2, e.g. GPR, EL1 and EL2 registers.

3. If the error information is being provided to a software agent running at EL1, then the context information should only include any registers visible in EL1, e.g. GPR, EL1 and registers.

For context information on processor running in AArch64 mode, even though some registers are defined as 4 bytes in length, following tables provide 8 bytes space to account for possible future expansion.

Table N.21: ARM Processor Error Context Information HeaderStructure

<table>
<thead>
<tr>
<th>Name</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Version</td>
<td>0</td>
<td>2</td>
<td>0 (revision of this table)</td>
</tr>
<tr>
<td>Register Context Type</td>
<td>2</td>
<td>2</td>
<td>Value indicating the type of processor context state being reported:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0 — AArch32 GPRs (General Purpose Registers).</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>1 — AArch32 EL1 context registers</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>2 — AArch32 EL2 context registers</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>3 — AArch32 secure context registers</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>4 — AArch64 GPRs</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>5 — AArch64 EL1 context registers</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>6 — AArch64 EL2 context registers</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>7 — AArch64 EL3 context registers</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>8 — Misc. System Register Structure</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>All other values are reserved.</td>
</tr>
<tr>
<td>Register Array Size</td>
<td>4</td>
<td>4</td>
<td>Represents the total size of the array for the Data Type being reported in bytes.</td>
</tr>
<tr>
<td>Register Array</td>
<td>8</td>
<td>N</td>
<td>This field will provide the contents of the actual registers or raw data. The contents of the array depends on the Type, with the structures described in Tables 266 - 274.</td>
</tr>
</tbody>
</table>
Table N.22: ARMv8 AArch32 GPRs (Type 0)

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>4</td>
<td>R0</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>R1</td>
</tr>
<tr>
<td>8</td>
<td>4</td>
<td>R2</td>
</tr>
<tr>
<td>12</td>
<td>4</td>
<td>R3</td>
</tr>
<tr>
<td>16</td>
<td>4</td>
<td>R4</td>
</tr>
<tr>
<td>20</td>
<td>4</td>
<td>R5</td>
</tr>
<tr>
<td>24</td>
<td>4</td>
<td>R6</td>
</tr>
<tr>
<td>28</td>
<td>4</td>
<td>R7</td>
</tr>
<tr>
<td>32</td>
<td>4</td>
<td>R8</td>
</tr>
<tr>
<td>36</td>
<td>4</td>
<td>R9</td>
</tr>
<tr>
<td>40</td>
<td>4</td>
<td>R10</td>
</tr>
<tr>
<td>44</td>
<td>4</td>
<td>R11</td>
</tr>
<tr>
<td>48</td>
<td>4</td>
<td>R12</td>
</tr>
<tr>
<td>52</td>
<td>4</td>
<td>R13 (SP)</td>
</tr>
<tr>
<td>56</td>
<td>4</td>
<td>R14 (LR)</td>
</tr>
<tr>
<td>60</td>
<td>4</td>
<td>R15 (PC)</td>
</tr>
</tbody>
</table>

Table N.23: ARM AArch32 EL1 Context System Registers (Type 1)

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>4</td>
<td>DFAR</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>DFSR</td>
</tr>
<tr>
<td>8</td>
<td>4</td>
<td>IFAR</td>
</tr>
<tr>
<td>12</td>
<td>4</td>
<td>ISR</td>
</tr>
<tr>
<td>16</td>
<td>4</td>
<td>MAIR0</td>
</tr>
<tr>
<td>20</td>
<td>4</td>
<td>MAIR1</td>
</tr>
<tr>
<td>24</td>
<td>4</td>
<td>MIDR</td>
</tr>
<tr>
<td>28</td>
<td>4</td>
<td>MPIDR</td>
</tr>
<tr>
<td>32</td>
<td>4</td>
<td>NMRR</td>
</tr>
<tr>
<td>36</td>
<td>4</td>
<td>PRRR</td>
</tr>
<tr>
<td>40</td>
<td>4</td>
<td>SCTLR (NS)</td>
</tr>
<tr>
<td>44</td>
<td>4</td>
<td>SPSR</td>
</tr>
<tr>
<td>48</td>
<td>4</td>
<td>SPSR_abt</td>
</tr>
<tr>
<td>52</td>
<td>4</td>
<td>SPSR_fiq</td>
</tr>
<tr>
<td>56</td>
<td>4</td>
<td>SPSR_irq</td>
</tr>
<tr>
<td>60</td>
<td>4</td>
<td>SPSR_sve</td>
</tr>
<tr>
<td>64</td>
<td>4</td>
<td>SPSR Und</td>
</tr>
<tr>
<td>68</td>
<td>4</td>
<td>TPIDPRPRW</td>
</tr>
<tr>
<td>72</td>
<td>4</td>
<td>TPIDRUR0</td>
</tr>
<tr>
<td>76</td>
<td>4</td>
<td>TPIDRURW</td>
</tr>
<tr>
<td>80</td>
<td>4</td>
<td>TTBCR</td>
</tr>
<tr>
<td>84</td>
<td>4</td>
<td>TTBR0</td>
</tr>
<tr>
<td>88</td>
<td>4</td>
<td>TTBR1</td>
</tr>
<tr>
<td>92</td>
<td>4</td>
<td>DACR</td>
</tr>
</tbody>
</table>
Table N.24: ARM AArch32 EL2 Context System Registers (Type 2)

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>4</td>
<td>ELR_hyp</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>HAMAIR0</td>
</tr>
<tr>
<td>8</td>
<td>4</td>
<td>HAMAIR1</td>
</tr>
<tr>
<td>12</td>
<td>4</td>
<td>HCR</td>
</tr>
<tr>
<td>16</td>
<td>4</td>
<td>HCR2</td>
</tr>
<tr>
<td>20</td>
<td>4</td>
<td>HDFAR</td>
</tr>
<tr>
<td>24</td>
<td>4</td>
<td>HIFAR</td>
</tr>
<tr>
<td>28</td>
<td>4</td>
<td>HPFAR</td>
</tr>
<tr>
<td>32</td>
<td>4</td>
<td>HSR</td>
</tr>
<tr>
<td>36</td>
<td>4</td>
<td>HTCR</td>
</tr>
<tr>
<td>40</td>
<td>4</td>
<td>HTPIDR</td>
</tr>
<tr>
<td>44</td>
<td>4</td>
<td>HTTBR</td>
</tr>
<tr>
<td>48</td>
<td>4</td>
<td>SPSR_hyp</td>
</tr>
<tr>
<td>52</td>
<td>4</td>
<td>VTCR</td>
</tr>
<tr>
<td>56</td>
<td>4</td>
<td>VTTBR</td>
</tr>
<tr>
<td>60</td>
<td>4</td>
<td>DACR32_EL2</td>
</tr>
</tbody>
</table>

Table N.25: ARM AArch32 secure Context System Registers (Type3)

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>4</td>
<td>SCTLR (S)</td>
</tr>
<tr>
<td>4</td>
<td>4</td>
<td>SPSR_mon</td>
</tr>
</tbody>
</table>

Table N.26: ARMv8 AArch64 GPRs (Type 4)

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>8</td>
<td>X0</td>
</tr>
<tr>
<td>8</td>
<td>8</td>
<td>X1</td>
</tr>
<tr>
<td>16</td>
<td>8</td>
<td>X2</td>
</tr>
<tr>
<td>24</td>
<td>8</td>
<td>X3</td>
</tr>
<tr>
<td>32</td>
<td>8</td>
<td>X4</td>
</tr>
<tr>
<td>40</td>
<td>8</td>
<td>X5</td>
</tr>
<tr>
<td>48</td>
<td>8</td>
<td>X6</td>
</tr>
<tr>
<td>56</td>
<td>8</td>
<td>X7</td>
</tr>
<tr>
<td>64</td>
<td>8</td>
<td>X8</td>
</tr>
<tr>
<td>72</td>
<td>8</td>
<td>X9</td>
</tr>
<tr>
<td>80</td>
<td>8</td>
<td>X10</td>
</tr>
<tr>
<td>88</td>
<td>8</td>
<td>X11</td>
</tr>
<tr>
<td>96</td>
<td>8</td>
<td>X12</td>
</tr>
<tr>
<td>104</td>
<td>8</td>
<td>X13</td>
</tr>
<tr>
<td>112</td>
<td>8</td>
<td>X14</td>
</tr>
<tr>
<td>120</td>
<td>8</td>
<td>X15</td>
</tr>
<tr>
<td>128</td>
<td>8</td>
<td>X16</td>
</tr>
<tr>
<td>136</td>
<td>8</td>
<td>X17</td>
</tr>
<tr>
<td>144</td>
<td>8</td>
<td>X18</td>
</tr>
<tr>
<td>152</td>
<td>8</td>
<td>X19</td>
</tr>
<tr>
<td>160</td>
<td>8</td>
<td>X20</td>
</tr>
<tr>
<td>168</td>
<td>8</td>
<td>X21</td>
</tr>
</tbody>
</table>

continues on next page
Table N.26 – continued from previous page

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>176</td>
<td>8</td>
<td>X22</td>
</tr>
<tr>
<td>184</td>
<td>8</td>
<td>X23</td>
</tr>
<tr>
<td>192</td>
<td>8</td>
<td>X24</td>
</tr>
<tr>
<td>200</td>
<td>8</td>
<td>X25</td>
</tr>
<tr>
<td>208</td>
<td>8</td>
<td>X26</td>
</tr>
<tr>
<td>216</td>
<td>8</td>
<td>X27</td>
</tr>
<tr>
<td>224</td>
<td>8</td>
<td>X28</td>
</tr>
<tr>
<td>232</td>
<td>8</td>
<td>X29</td>
</tr>
<tr>
<td>240</td>
<td>8</td>
<td>X30</td>
</tr>
<tr>
<td>248</td>
<td>8</td>
<td>SP</td>
</tr>
</tbody>
</table>

Table N.27: ARM AArch64 EL1 Context System Registers (Type 5)

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>8</td>
<td>ELR_EL1</td>
</tr>
<tr>
<td>8</td>
<td>8</td>
<td>ESR_EL1</td>
</tr>
<tr>
<td>16</td>
<td>8</td>
<td>FAR_EL1</td>
</tr>
<tr>
<td>24</td>
<td>8</td>
<td>ISR_EL1</td>
</tr>
<tr>
<td>32</td>
<td>8</td>
<td>MAIR_EL1</td>
</tr>
<tr>
<td>40</td>
<td>8</td>
<td>MIDR_EL1</td>
</tr>
<tr>
<td>48</td>
<td>8</td>
<td>MPIDR_EL1</td>
</tr>
<tr>
<td>56</td>
<td>8</td>
<td>SCTLR_EL1</td>
</tr>
<tr>
<td>64</td>
<td>8</td>
<td>SP_EL0</td>
</tr>
<tr>
<td>72</td>
<td>8</td>
<td>SP_EL1</td>
</tr>
<tr>
<td>80</td>
<td>8</td>
<td>SPSR_EL1</td>
</tr>
<tr>
<td>88</td>
<td>8</td>
<td>TCR_EL1</td>
</tr>
<tr>
<td>96</td>
<td>8</td>
<td>TPIDR_EL0</td>
</tr>
<tr>
<td>104</td>
<td>8</td>
<td>TPIDR_EL1</td>
</tr>
<tr>
<td>112</td>
<td>8</td>
<td>TPIDRRO_EL0</td>
</tr>
<tr>
<td>120</td>
<td>8</td>
<td>TTBR0_EL1</td>
</tr>
<tr>
<td>128</td>
<td>8</td>
<td>TTBR1_EL1</td>
</tr>
</tbody>
</table>

Table N.28: ARM AArch64 EL2 Context System Registers (Type 6)

<table>
<thead>
<tr>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Field</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>8</td>
<td>ELR_EL2</td>
</tr>
<tr>
<td>8</td>
<td>8</td>
<td>ESR_EL2</td>
</tr>
<tr>
<td>16</td>
<td>8</td>
<td>FAR_EL2</td>
</tr>
<tr>
<td>24</td>
<td>8</td>
<td>HACR_EL2</td>
</tr>
<tr>
<td>32</td>
<td>8</td>
<td>HCR_EL2</td>
</tr>
<tr>
<td>40</td>
<td>8</td>
<td>HPRAR_EL2</td>
</tr>
<tr>
<td>48</td>
<td>8</td>
<td>MAIR_EL2</td>
</tr>
<tr>
<td>56</td>
<td>8</td>
<td>SCTLR_EL2</td>
</tr>
<tr>
<td>64</td>
<td>8</td>
<td>SP_EL2</td>
</tr>
<tr>
<td>72</td>
<td>8</td>
<td>SPSR_EL2</td>
</tr>
<tr>
<td>80</td>
<td>8</td>
<td>TCR_EL2</td>
</tr>
<tr>
<td>88</td>
<td>8</td>
<td>TPIDR_EL2</td>
</tr>
<tr>
<td>96</td>
<td>8</td>
<td>TTBR0_EL2</td>
</tr>
<tr>
<td>104</td>
<td>8</td>
<td>VTCR_EL2</td>
</tr>
<tr>
<td>112</td>
<td>8</td>
<td>VTTBR_EL2</td>
</tr>
</tbody>
</table>
The following structure (Table 275) describes additional AArch64/AArch32 miscellaneous system registers captured from the perspective of the processor that took the hardware error exception. Each register array entry will be per the following table. The number of register entries present in the register array is based on the register array size (i.e. N/10).

### Table N.30: ARM Misc. Context System Register (Type 8) - SingleRegister Entry

<table>
<thead>
<tr>
<th>Name</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>MRS encoding</td>
<td>0</td>
<td>2</td>
<td>This field defines MRS instruction encoding.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 0:2 – Op2</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 3:6 - CRm</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 7:10 - CRn</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 11:13 - Op1</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 14 - 00</td>
</tr>
<tr>
<td>Value</td>
<td>2</td>
<td>8</td>
<td>Value read from system register</td>
</tr>
</tbody>
</table>

### N.2.5 Memory Error Section

Type: \{0xA5BC1114, 0x6F64, 0x4EDE, \{0xB8, 0x63, 0x3E, 0x83, 0xED, 0x7C, 0x83, 0xB1\}\}

### Table N.31: Memory Error Record

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
</table>
| continues on next page
Table N.31 – continued from previous page

<table>
<thead>
<tr>
<th>Validation Bits</th>
<th>0</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Indicates which fields in the memory error record are valid.</td>
<td></td>
</tr>
<tr>
<td>Bit 0 - Error Status Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 1 - Physical Address Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 2 - Physical Address Mask Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 3 - Node Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 4 - Card Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 5 - Module Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 6 - Bank Valid (When Bank is addressed via group/address, refer to Bit 19 and 20)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 7 - Device Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 8 - Row Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1 - the Row field at Offset 42 contains row number (15:0) and row number (17:16) are 00b</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0 - the Row field at Offset 42 is not used, or is defined by Bit 18 (Extended Row Bit 16 and 17 Valid).</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 9 - Column Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 10 - Bit Position Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 11 - Platform Requestor Id Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 12 - Platform Responder Id Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 13 - Memory Platform Target Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 14 - Memory Error Type Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 15 - Rank Number Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 16 - Card Handle Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 17 - Module Handle Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 18 - Extended Row Bit 16 and 17 Valid (refer to Byte Offset 42 and 73 below)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1 - the Row field at Offset 42 contains row number (15:0) and the Extended field at Offset 73 contains row number (17:16)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0 - the Extended field at Offset 73 and the Row field at Offset 42 are not used, or the Rowfield at Offset 42 is defined by Bit 8 (Row Valid). When this bit is set to 1, Bit 8 (Row Valid) must be set to 0.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 19 - Bank Group Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 20 - Bank Address Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 21 - Chip Identification Valid</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 22-63 Reserved</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Error Status</th>
<th>8</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>Error Status</td>
<td>Memory error status information. See See Error Status for error status details.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Physical Address</th>
<th>16</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>Physical Address</td>
<td>The physical address at which the memory error occurred.</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Physical Address Mask</th>
<th>24</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>Defines the valid address bits in the Physical Address field. The mask specifies the granularity of the physical address which is dependent on the hw/ implementation factors such as interleaving.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Node</th>
<th>32</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td>In a multi-node system, this value identifies the node containing the memory in error.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Card</th>
<th>34</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td>The card number of the memory error location.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

continues on next page
<table>
<thead>
<tr>
<th>Module</th>
<th>36</th>
<th>2</th>
<th>The module or rank number of the memory error location. (NODE, CARD, and MODULE should provide the information necessary to identify the failing FRU).</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bank</td>
<td>38</td>
<td>2</td>
<td>The bank number of the memory associated with the error. When Bank is addressed via group/address Bit 7:0 - Bank Address Bit 15:8 - Bank Group</td>
</tr>
<tr>
<td>Device</td>
<td>40</td>
<td>2</td>
<td>The device number of the memory associated with the error.</td>
</tr>
<tr>
<td>Row</td>
<td>42</td>
<td>2</td>
<td>First 16 bits (15:0) of the row number of the memory error location. This field is valid if either “Row Valid” or “Extended Row Bit 16 and 17” Validation Bits at Offset 0 is set to 1.</td>
</tr>
<tr>
<td>Column</td>
<td>44</td>
<td>2</td>
<td>The column number of the memory error location.</td>
</tr>
<tr>
<td>Bit Position</td>
<td>46</td>
<td>2</td>
<td>The bit position at which the memory error occurred.</td>
</tr>
<tr>
<td>Requestor ID</td>
<td>48</td>
<td>8</td>
<td>Hardware address of the device that initiated the transaction that took the error.</td>
</tr>
<tr>
<td>Responder ID</td>
<td>56</td>
<td>8</td>
<td>Hardware address of the device that responded to the transaction.</td>
</tr>
<tr>
<td>Target ID</td>
<td>64</td>
<td>8</td>
<td>Hardware address of the intended target of the transaction.</td>
</tr>
<tr>
<td>Memory Error Type</td>
<td>72</td>
<td>1</td>
<td>Identifies the type of error that occurred: 0 - Unknown 1 - No error 2 - Single-bit ECC 3 - Multi-bit ECC 4 - Single-symbol ChipKill ECC 5 - Multi-symbol ChipKill ECC 6 - Master abort 7 - Target abort 8 - Parity Error 9 - Watchdog timeout 10 - Invalid address 11 - Mirror Broken 12 - Memory Sparing 13 - Scrub corrected error 14 - Scrub uncorrected error 15 - Physical Memory Map-out event All other values reserved.</td>
</tr>
</tbody>
</table>
Table N.31 – continued from previous page

| Extended | 73 | 1 | Bit 0 - Bit 16 of the row number of the memory error location.  
- This field is valid if “Extended Row Bit 16 and 17” Validation Bits at Offset 0 is set to 1.  
Bit 1 - Bit 17 of the row number of the memory error location.  
- This field is valid if “Extended Row Bit 16 and 17” Validation Bits at Offset 0 is set to 1.  
Bit 4:2 - Reserved  
Bit 7:5 - Chip Identification. |
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Rank Number</td>
<td>74</td>
<td>2</td>
<td>The Rank number of the memory error location.</td>
</tr>
<tr>
<td>Card Handle</td>
<td>76</td>
<td>2</td>
<td>If bit 16 in Validation Bits is 1, this field contains the SMBIOS handle for the Type 16 Memory Array Structure that represents the memory card.</td>
</tr>
<tr>
<td>Module Handle</td>
<td>78</td>
<td>2</td>
<td>If bit 17 in Validation Bits is 1, this field contains the SMBIOS handle for the Type 17 Memory Device Structure that represents the Memory Module.</td>
</tr>
</tbody>
</table>

N.2.6 Memory Error Section 2

Type: { 0x61EC04FC, 0x48E6, 0xD813, { 0x25, 0xC9, 0x8D, 0xAA, 0x44, 0x75, 0x0B, 0x12 } };

Table N.32: Memory Error Record 2

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>continues on next page</td>
</tr>
</tbody>
</table>
Table N.32 – continued from previous page

<table>
<thead>
<tr>
<th>Validation Bits</th>
<th>0</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Indicates which fields in the memory error record are valid.</td>
</tr>
<tr>
<td>Bit 0</td>
<td></td>
<td>Error Status Valid</td>
</tr>
<tr>
<td>Bit 1</td>
<td></td>
<td>Physical Address Valid</td>
</tr>
<tr>
<td>Bit 2</td>
<td></td>
<td>Physical Address Mask Valid</td>
</tr>
<tr>
<td>Bit 3</td>
<td></td>
<td>Node Valid</td>
</tr>
<tr>
<td>Bit 4</td>
<td></td>
<td>Card Valid</td>
</tr>
<tr>
<td>Bit 5</td>
<td></td>
<td>Module Valid</td>
</tr>
<tr>
<td>Bit 6</td>
<td></td>
<td>Bank Valid</td>
</tr>
<tr>
<td>Bit 7</td>
<td></td>
<td>Device Valid</td>
</tr>
<tr>
<td>Bit 8</td>
<td></td>
<td>Row Valid</td>
</tr>
<tr>
<td>Bit 9</td>
<td></td>
<td>Column Valid</td>
</tr>
<tr>
<td>Bit 10</td>
<td></td>
<td>Rank Valid</td>
</tr>
<tr>
<td>Bit 11</td>
<td></td>
<td>Bit Position Valid</td>
</tr>
<tr>
<td>Bit 12</td>
<td></td>
<td>Chip Identification Valid</td>
</tr>
<tr>
<td>Bit 13</td>
<td></td>
<td>Memory Error Type Valid</td>
</tr>
<tr>
<td>Bit 14</td>
<td></td>
<td>Status Valid</td>
</tr>
<tr>
<td>Bit 15</td>
<td></td>
<td>Requestor ID Valid</td>
</tr>
<tr>
<td>Bit 16</td>
<td></td>
<td>Responder ID Valid</td>
</tr>
<tr>
<td>Bit 17</td>
<td></td>
<td>Target ID Valid</td>
</tr>
<tr>
<td>Bit 18</td>
<td></td>
<td>Card Handle Valid</td>
</tr>
<tr>
<td>Bit 19</td>
<td></td>
<td>Module Handle Valid</td>
</tr>
<tr>
<td>Bit 20</td>
<td></td>
<td>Bank Group Valid</td>
</tr>
<tr>
<td>Bit 21</td>
<td></td>
<td>Bank Address Valid</td>
</tr>
<tr>
<td>Bit 22-63</td>
<td></td>
<td>Reserved</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Error Status</th>
<th>8</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Memory error status information. See See Error Status for error status details.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Physical Address</th>
<th>16</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The physical address at which the memory error occurred.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Physical Address Mask</th>
<th>24</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Defines the valid address bits in the Physical Address field. The mask specifies the granularity of the physical address which is dependent on the hardware implementation factors such as interleaving.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Node</th>
<th>32</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>In a multi-node system, this value identifies the node containing the memory in error.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Card</th>
<th>34</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The card number of the memory error location.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Module</th>
<th>36</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The module number of the memory error location. (NODE, CARD, and MODULE should provide the information necessary to identify the failing FRU).</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Bank</th>
<th>38</th>
<th>2</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The bank number of the memory associated with the error. When Bank is addressed via group/address (e.g., DDR4) Bit 7:0 - Bank Address Bit 15:8 - Bank Group</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Device</th>
<th>40</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The device number of the memory associated with the error.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Row</th>
<th>44</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The row number of the memory error location.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Column</th>
<th>48</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The column number of the memory error location.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Rank</th>
<th>52</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The rank number of the memory error location.</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Bit Position</th>
<th>56</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>The bit position at which the memory error occurred.</td>
</tr>
</tbody>
</table>

continues on next page
Table N.32 – continued from previous page

<table>
<thead>
<tr>
<th>Chip Identification</th>
<th>60</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td>The Chip Identification. This is an encoded field used to address the die in 3DS packages.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Memory Error Type</th>
<th>61</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Identifies the type of error that occurred:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0 - Unknown</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1 - No error</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2 - Single-bit ECC</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3 - Multi-bit ECC</td>
<td></td>
<td></td>
</tr>
<tr>
<td>4 - Single-symbol ChipKill ECC</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5 - Multi-symbol ChipKill ECC</td>
<td></td>
<td></td>
</tr>
<tr>
<td>6 - Master abort</td>
<td></td>
<td></td>
</tr>
<tr>
<td>7 - Target abort</td>
<td></td>
<td></td>
</tr>
<tr>
<td>8 - Parity Error</td>
<td></td>
<td></td>
</tr>
<tr>
<td>9 - Watchdog timeout</td>
<td></td>
<td></td>
</tr>
<tr>
<td>10 - Invalid address</td>
<td></td>
<td></td>
</tr>
<tr>
<td>11 - Mirror Broken</td>
<td></td>
<td></td>
</tr>
<tr>
<td>12 - Memory Sparing</td>
<td></td>
<td></td>
</tr>
<tr>
<td>13 - Scrub corrected error</td>
<td></td>
<td></td>
</tr>
<tr>
<td>14 - Scrub uncorrected error</td>
<td></td>
<td></td>
</tr>
<tr>
<td>15 - Physical Memory Map-out event</td>
<td></td>
<td></td>
</tr>
<tr>
<td>All other values reserved.</td>
<td></td>
<td></td>
</tr>
<tr>
<td>16 - 255 Reserved</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Status</th>
<th>62</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bit 0:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>If set to 0, the memory error is corrected; if set to 1, the memory error is uncorrected</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Bit 1-7: Reserved values are 0</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Reserved</th>
<th>63</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reserved values are 0</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Requestor ID</th>
<th>64</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>Hardware address of the device that initiated the transaction that took the error.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Responder ID</th>
<th>72</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>Hardware address of the device that responded to the transaction.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Target ID</th>
<th>80</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td>Hardware address of the intended target of the transaction.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Card Handle</th>
<th>88</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>This field contains the SMBIOS handle for the Type 16 Memory Array Structure that represents the memory card.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Module Handle</th>
<th>92</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>This field contains the SMBIOS handle for the Type 17 Memory Device Structure that represents the Memory Module.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### N.2.7 PCI Express Error Section

Type: \{0x995E954, 0xBBBC1, 0x430F, \{0xAD, 0x91, 0xB4, 0x4D, 0xCB, 0x3C, 0x6F, 0x35\}\}

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Validation Bits</td>
<td>0</td>
<td>8</td>
<td>Indicates which of the following fields is valid:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 0 - Port Type Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 1 - Version Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 2 - Command Status Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 3 - Device ID Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 4 - Device Serial Number Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 5 - Bridge Control Status Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 6 - Capability Structure Status Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 7 - AER Info Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 8-63 - Reserved</td>
</tr>
<tr>
<td>Port Type</td>
<td>8</td>
<td>4</td>
<td>PCIe Device/Port Type as defined in the PCI Express capabilities register:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0: PCI Express End Point</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>1: Legacy PCI End Point Device</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>4: Root Port 5: Upstream Switch Port</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>6: Downstream Switch Port</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>7: PCI Express to PCI/PCI-X Bridge</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>8: PCI/PCI-X to PCI Express Bridge</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>9: Root Complex Integrated Endpoint Device</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>10: Root Complex Event Collector</td>
</tr>
<tr>
<td>Version</td>
<td>12</td>
<td>4</td>
<td>PCIe Spec. version supported by the platform:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 0-1: PCIe Spec. Version Number</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte0: Minor Version in BCD</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>• Byte1: Major Version in BCD</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte2-3: Reserved</td>
</tr>
<tr>
<td>Command Status</td>
<td>16</td>
<td>4</td>
<td>Byte0-1: PCI Command Register</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte2-3: PCI Status Register</td>
</tr>
<tr>
<td>Reserved</td>
<td>20</td>
<td>4</td>
<td>Must be zero</td>
</tr>
</tbody>
</table>

Table N.33: PCI Express Error Record
<table>
<thead>
<tr>
<th>Table</th>
<th>Device ID</th>
<th>24</th>
<th>16</th>
<th>PCIe Root Port PCI/bridge PCI compatible device number and bus number information to uniquely identify the root port or bridge. Default values for both the bus numbers is zero. Byte 0-1: Vendor ID Byte 2-3: Device ID Byte 4-6: Class Code Byte 7: Function Number Byte 8: Device Number Byte 9-10: Segment Number Byte 11: Root Port/Bridge Primary Bus Number or device bus number Byte 12: Root Port/Bridge Secondary Bus Number Byte 13-14: Bit0:2: Reserved Bit3:15 Slot Number Byte 15 Reserved</th>
</tr>
</thead>
<tbody>
<tr>
<td>Device Serial Number</td>
<td>40</td>
<td>8</td>
<td>Byte 0-3: PCIe Device Serial Number Lower DW Byte 4-7: PCIe Device Serial Number Upper DW</td>
<td></td>
</tr>
<tr>
<td>Bridge Control Status</td>
<td>48</td>
<td>4</td>
<td>This field is valid for bridges only. Byte 0-1: Bridge Secondary Status Register Byte 2-3: Bridge Control Register</td>
<td></td>
</tr>
<tr>
<td>Capability Structure</td>
<td>52</td>
<td>60</td>
<td>PCIe Capability Structure. - The 60-byte structure is used to report device capabilities. This structure is used to report the 36-byte PCIe 1.1 Capability Structure (See Figure 7-9 of the PCI Express Base Specification, Rev 1.1) with the last 24 bytes padded. - This structure is also used to report the 60-byte PCIe 2.0 Capability Structure (See Figure 7-9 of the PCI Express 2.0 Base Specification.) - The fields in the structure vary with different device types. - The “Next CAP pointer” field should be considered invalid and any reserved fields of the structure are reserved for future use. Note that PCIe devices without AER (PCI e_AER_INFO_STRUCTURE.Valid Bit=0) may report status using this structure.</td>
<td></td>
</tr>
<tr>
<td>AER Info</td>
<td>112</td>
<td>96</td>
<td>PCIe Advanced Error Reporting Extended Capability Structure.</td>
<td></td>
</tr>
</tbody>
</table>
N.2.8 PCI/PCI-X Bus Error Section

Type: \{0xC5753963, 0x3B84, 0x4095, \{0xBF, 0x78, 0xED, 0xDA, 0xD3, 0xF9, 0xC9, 0xDD\}\}

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Validation Bits</td>
<td>0</td>
<td>8</td>
<td>Indicates which of the following fields is valid:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 0 - Error Status Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 1 - Error Type Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 2 - Bus Id Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 3 - Bus Address Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 4 - Bus Data Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 5 - Command Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 6 - Requestor Id Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 7 - Completer Id Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 8 - Target Id Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 9-63 Reserved</td>
</tr>
<tr>
<td>Error Status</td>
<td>8</td>
<td>8</td>
<td>PCI Bus Error Status. See See Error Status for details.</td>
</tr>
<tr>
<td>Error Type</td>
<td>16</td>
<td>2</td>
<td>PCI Bus error Type</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 0:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>0 - Unknown or OEM system specific error</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>1 - Data Parity Error</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>2 - System Error</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>3 - Master Abort</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>4 - Bus Timeout or No Device Present (No DEVSEL#)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>5 - Master Data Parity Error</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>6 - Address Parity Error</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>7 - Command Parity Error</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Others - Reserved</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 1: Reserved</td>
</tr>
<tr>
<td>Bus Id</td>
<td>18</td>
<td>2</td>
<td>Bits 0:7 - Bus Number</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bits 8:15 - Segment Number</td>
</tr>
<tr>
<td>Reserved</td>
<td>20</td>
<td>4</td>
<td></td>
</tr>
<tr>
<td>Bus Address</td>
<td>24</td>
<td>8</td>
<td>Memory or I/O address on the bus at the time of the error.</td>
</tr>
<tr>
<td>Bus Data</td>
<td>32</td>
<td>8</td>
<td>Data on the PCI bus at the time of the error.</td>
</tr>
<tr>
<td>Bus Command</td>
<td>40</td>
<td>8</td>
<td>Bus command or operation at the time of the error.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 7: Bits 7-1: Reserved (should be zero)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 7: Bit 0: If 0, then the command is a PCI command.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>If 1, the command is a PCI-X command.</td>
</tr>
</tbody>
</table>

continues on next page
Table N.34 – continued from previous page

<table>
<thead>
<tr>
<th>Bus Requestor Id</th>
<th>48</th>
<th>8</th>
<th>PCI Bus Requestor Id.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bus Completer Id</td>
<td>56</td>
<td>8</td>
<td>PCI Bus Responder Id.</td>
</tr>
<tr>
<td>Target Id</td>
<td>64</td>
<td>8</td>
<td>PCI Bus intended target identifier.</td>
</tr>
</tbody>
</table>

N.2.9 PCI/PCI-X Component Error Section

Type: \( \{0xEB5E4685, 0xCA66, 0x4769, \{0xB6, 0xA2, 0x26, 0x06, 0x8B, 0x00, 0x13, 0x26\}\} \)

Table N.35: PCI/PCI-X Component Error Section

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Validation Bits</td>
<td>0</td>
<td>8</td>
<td>Indicate which fields are valid: Bit 0 - Error Status Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 1 - Id Info Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 2 - Memory Number Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 3 - IO Number Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 4 - Register Data Pair Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 5-63 Reserved</td>
</tr>
</tbody>
</table>

| Error Status   | 8          | 8           | PCI Component Error Status. See \textit{Error Status} for details.           |
| Id Info        | 16         | 16          | Identification Information: Bytes 0-1: Vendor Id                             |
|               |            |             | Bytes 1-2: Device Id                                                        |
| Memory Number  | 32         | 4           | Number of PCI Component Memory Mapped register address/data pair values present in this structure. |
| IO Number      | 36         | 4           | Number of PCI Component Programmed IO register address/data pair values present in this structure. |
| Register Data Pairs | 40     | 2x8xN       | An array of address/data pair values. The address and data information may be from 2 to 8 bytes of actual data represented in the 8 byte array locations. |
N.2.10 Firmware Error Record Reference

Type: \{0x81212A96, 0x09ED, 0x4996, {0x94, 0x71, 0x8D, 0x72, 0x9C, 0x8E, 0x69, 0xED}\}

Table N.36: Firmware Error Record Reference

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Firmware Error Record Type</td>
<td>0</td>
<td>1</td>
<td>Identifies the type of firmware error record that is referenced by this section: 0: IPF SAL Error Record 1: SOC Firmware error record Type1 reserved and used by Legacy CrashLog support 2: SOC Firmware error record Type2 All other values reserved</td>
</tr>
<tr>
<td>Revision</td>
<td>1</td>
<td>1</td>
<td>Indicates the Header Revision. For this Revision of the specification value is 2.</td>
</tr>
<tr>
<td>Reserved</td>
<td>1</td>
<td>7</td>
<td>Must be zero.</td>
</tr>
<tr>
<td>Record Identifier</td>
<td>8</td>
<td>8</td>
<td>This value uniquely identifies the firmware error record referenced by this section. This value may be used to retrieve the referenced firmware error record using means appropriate for the error record type. <strong>Note:</strong> value is ignored for Revision &gt;=1 of the header and must be set to NULL.</td>
</tr>
<tr>
<td>Record Identifier GUID exten-</td>
<td>16</td>
<td>16</td>
<td>This value uniquely identifies the firmware error record referenced by this section. This value may be used to retrieve the referenced firmware error record using means appropriate for the error record type. <strong>Note:</strong> in case if Error Record Type == 2 then this field indicates the GUID. For Error Record Type 0 and Type 1 this field is ignored.</td>
</tr>
</tbody>
</table>

N.2.11 DMAr Error Sections

The DMAr error sections are divided into two different components as described below:

**DMAr Generic Error Section:**
This section holds information about DMAr errors in a generic form and will be common across all DMAr unit architectures.

**Architecture specific DMAr Error Section:**
This section consists of DMA remapping errors specific to the architecture. In addition, certain state information of the DMAr unit is captured at the time of error. This section is unique for each DMAr architecture (VT-d, IOMMU).
### N.2.11.1 DMAr Generic Error Section

Type: \{0x5B51FEF7, 0xC79D, 0x4434, \{0x8F, 0x1B, 0xAA, 0x62, 0xDE, 0x3E, 0x2C, 0x64}\}

<table>
<thead>
<tr>
<th>Table N.37: DMAr Generic Errors</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Mnemonic</strong></td>
</tr>
<tr>
<td>Requester-ID</td>
</tr>
<tr>
<td>Segment Number</td>
</tr>
<tr>
<td>Fault Reason</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Access Type</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Address Type</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Architecture Type</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Device Address</td>
</tr>
<tr>
<td></td>
</tr>
<tr>
<td>Reserved</td>
</tr>
<tr>
<td></td>
</tr>
</tbody>
</table>
N.2.11.2 Intel® VT for Directed I/O specific DMAr Error Section

Type: \{0x71761D37, 0x32B2, 0x45Cd, \{0xA7, 0xD0, 0xB0, 0xFE, 0xDD, 0x93, 0xE8, 0xCF\}\} All fields in this error section are specific to Intel’s VT-d architecture. This error section has a fixed size.

Table N.38: Intel® VT for Directed I/O specific DMAr Errors

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Version</td>
<td>0</td>
<td>1</td>
<td>Value of version register as defined in VT-d architecture</td>
</tr>
<tr>
<td>Revision</td>
<td>1</td>
<td>1</td>
<td>Value of revision field in VT-d specific DMA remapping reporting structure</td>
</tr>
<tr>
<td>OemId</td>
<td>2</td>
<td>6</td>
<td>Value of OEM ID field in VT-d specific DMA remapping reporting structure</td>
</tr>
<tr>
<td>Capability</td>
<td>8</td>
<td>8</td>
<td>Value of capability register in VT-d architecture</td>
</tr>
<tr>
<td>Extended Capability</td>
<td>16</td>
<td>8</td>
<td>Value of extended capability register in VT-d architecture</td>
</tr>
<tr>
<td>Global Command</td>
<td>24</td>
<td>4</td>
<td>Value of Global Command register in VT-d architecture programmed by the operating system</td>
</tr>
<tr>
<td>Global Status</td>
<td>28</td>
<td>4</td>
<td>Value of Global Status register in VT-d architecture</td>
</tr>
<tr>
<td>Fault Status</td>
<td>32</td>
<td>4</td>
<td>Value of Fault Status register in VT-d architecture</td>
</tr>
<tr>
<td>Reserved</td>
<td>36</td>
<td>12</td>
<td>Must be 0</td>
</tr>
<tr>
<td>Fault record</td>
<td>48</td>
<td>16</td>
<td>Fault record as defined in the VT-d specification</td>
</tr>
<tr>
<td>Root Entry</td>
<td>64</td>
<td>16</td>
<td>Value from the root entry table for the given requester-ID</td>
</tr>
<tr>
<td>Context Entry</td>
<td>80</td>
<td>16</td>
<td>Value from the context entry table for the given requester-ID.</td>
</tr>
<tr>
<td>Level 6 Page Table Entry</td>
<td>96</td>
<td>8</td>
<td>PTE entry for device virtual address in page level 6</td>
</tr>
<tr>
<td>Level 5 Page Table Entry</td>
<td>104</td>
<td>8</td>
<td>PTE entry for device virtual address in page level 5</td>
</tr>
<tr>
<td>Level 4 Page Table Entry</td>
<td>112</td>
<td>8</td>
<td>PTE entry for device virtual address in page level 4</td>
</tr>
<tr>
<td>Level 3 Page Table Entry</td>
<td>120</td>
<td>8</td>
<td>PTE entry for device virtual address in page level 3</td>
</tr>
<tr>
<td>Level 2 Page Table Entry</td>
<td>128</td>
<td>8</td>
<td>PTE entry for device virtual address in page level 2.</td>
</tr>
<tr>
<td>Level 1 Page Table Entry</td>
<td>136</td>
<td>8</td>
<td>PTE entry for device virtual address in page level 1</td>
</tr>
</tbody>
</table>

N.2.11.3 IOMMU Specific DMAr Error Section

Type: \{0x036F84E1, 0x7F37, 0x428c, \{0xA7, 0x9E, 0x57, 0x5F, 0xDF, 0xAA, 0x84, 0xEC\}\} All fields in this error record are specific to AMD’s IOMMU specification. This error section has a fixed size.

Table N.39: IOMMU-specific DMAr Errors

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Revision</td>
<td>0</td>
<td>1</td>
<td>Specifies the IOMMU specification revision</td>
</tr>
<tr>
<td>Reserved</td>
<td>1</td>
<td>7</td>
<td>Must be 0</td>
</tr>
<tr>
<td>Control</td>
<td>8</td>
<td>8</td>
<td>IOMMU control register</td>
</tr>
<tr>
<td>Status</td>
<td>16</td>
<td>8</td>
<td>IOMMU status register</td>
</tr>
<tr>
<td>Reserved</td>
<td>24</td>
<td>8</td>
<td>Must be 0</td>
</tr>
</tbody>
</table>
Table N.39 – continued from previous page

<table>
<thead>
<tr>
<th>Event Log Entry</th>
<th>Reserved</th>
<th>Device Table Entry</th>
<th>Level 6 Page Table Entry</th>
<th>Level 5 Page Table Entry</th>
<th>Level 4 Page Table Entry</th>
<th>Level 3 Page Table Entry</th>
<th>Level 2 Page Table Entry</th>
<th>Level 1 Page Table Entry</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>32</td>
<td>16</td>
<td>48</td>
<td>64</td>
<td>96</td>
<td>104</td>
<td>112</td>
<td>120</td>
</tr>
<tr>
<td></td>
<td>16</td>
<td>IOMMU fault related event log entry as defined in the IOMMU specification</td>
<td>Must be 0</td>
<td>Value from the device table for a given Requester ID</td>
<td>PTE entry for device virtual address in page level 6</td>
<td>PTE entry for device virtual address in page level 5</td>
<td>PTE entry for device virtual address in page level 4</td>
<td>PTE entry for device virtual address in page level 3</td>
</tr>
</tbody>
</table>

**N.2.12 CCIX PER Log Error Section**

Type:{0x91335EF6, 0xEBFB, 0x4478, {0xA6, 0xA6, 0x88, 0xB7, 0x28, 0xCF, 0x75, 0xD7}}

Table N.40: CCIX PER Log Error Record

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Length</td>
<td>0</td>
<td>4</td>
<td>Length in bytes for entire structure.</td>
</tr>
<tr>
<td>Validation Bits</td>
<td>4</td>
<td>8</td>
<td>Indicates which of the following fields is valid:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 0 - CCIX Source ID Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 1 - CCIX Port ID Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 2 - CCIX PER Log Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 3-63 - Reserved</td>
</tr>
<tr>
<td>CCIX Source ID</td>
<td>12</td>
<td>1</td>
<td>If the agent type is an HA, SA, or RA: This field indicates the CCIX Agent ID of the component that reported this error. In this case bits 7:6 must be zero, since Agent ID is only 6 bits. Otherwise, this field specifies the CCIX Device ID (i.e. in the case of Port, CCIX Link, or device errors).</td>
</tr>
<tr>
<td>CCIX Port ID</td>
<td>13</td>
<td>1</td>
<td>This field indicates the CCIX Port ID that reported this error. Bits 7:5 must be zero, since CCIX Port ID is only 5 bits.</td>
</tr>
<tr>
<td>Reserved</td>
<td>14</td>
<td>2</td>
<td>Must be zero.</td>
</tr>
</tbody>
</table>

continues on next page
Table N.40 – continued from previous page

| CCIX PER Log | 16 | 20…n | DWORD (32-bit) entries in CCIX PER Log Structure, as described in Section 7.3.2 of the CCIX Base Specification - Revision 1.0. 
NOTE: The Per Log Structure contains a header describing the number of DWORDs in the error record. |

## N.2.13 Compute Express Link (CXL) Protocol Error Section

Type: \{ 0x80B9EFB4, 0x52B5, 0x4DE3, \{ 0xA7, 0x77, 0x68, 0x78, 0x4B, 0x77, 0x10, 0x48 \} \} 

<table>
<thead>
<tr>
<th>Table N.41: CXL Protocol Error Section</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Mnemonic</strong></td>
</tr>
</tbody>
</table>
| Validation Bits | 0 | 8 | Indicates which of the following fields is valid:  
Bit 0 - CXL Agent Type field is valid  
Bit 1 - CXL Agent Address field is valid  
Bit 2 - Device ID field is valid  
Bit 3 - Device Serial Number field is valid  
Bit 4 - Capability Structure field is valid  
Bit 5 - CXL DVSEC field is valid  
Bit 6 - CXL Error Log field is valid  
Bits 7:63 - Reserved |

| CXL Agent Type | 8 | 1 | 0 - This error was detected by a CXL 1.1 device  
1 - This error was detected by a CXL 1.1 host downstream port  
2 - This error was detected by CXL 2.0 device  
3 - This error was detected by CXL 2.0 Logical Device  
4 - This error was detected by CXL 2.0 Fabric Manager managed Logical device  
5 - This error was detected by CXL 2.0 Root Port  
6 - This error was detected by CXL 2.0 Downstream Switch Port  
7 - This error was detected by CXL 2.0 Upstream Switch Port  
8-255 - Reserved |

In this table, the term “CXL Device” is used to refer to CXL 1.1 Device, CXL 2.0 Device, CXL 2.0 Logical Device or a CXL 2.0 Fabric Manager Managed Logical Device.  
In this table, the term “CXL Port” is used to refer to CXL 1.1 host downstream port, CXL Root Port, CXL Downstream Switch Port and Upstream Switch Port.  

| Reserved | 9 | 7 | Must be zero |
If this CXL agent is a CXL device, CXL Root Port, CXL Downstream Switch Port or CXL Upstream Switch Port, then the PCIe compatible device/function number, bus number, and segment number information are used to uniquely identify the Component:
- Byte 0 - Function number
- Byte 1 - Device number
- Byte 2 - Bus number
- Bytes 3-4 - Segment number
- Bytes 5-7 - Reserved

If CXL agent is a CXL 1.1 host downstream port:
- Byte 0-7 - CXL Port RCRB Base address

If this CXL agent is a CXL device, CXL Root Port, CXL Downstream Switch Port, or CXL Upstream Switch Port, then this field provides various identifiers for the device:
- Bytes 0-1: Vendor ID
- Bytes 2-3: Device ID
- Bytes 4-5: Subsystem Vendor ID
- Bytes 6-7: Subsystem Device ID
- Bytes 8-9: Class Code
- Byte 10-11:
  - Bits 0-2: Reserved
  - Bits 3-15: Slot Number
- Byte 12-15: Reserved

If this CXL agent is a CXL device:
- Byte 0-3: CXL Device Serial Number Lower DW
- Byte 4-7: CXL Device Serial Number Upper DW

<table>
<thead>
<tr>
<th>CXL Agent Address</th>
<th>16</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Device ID</th>
<th>24</th>
<th>16</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Device Serial Number</th>
<th>40</th>
<th>8</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

continues on next page
If this CXL agent is a CXL device, PCIe Capability Structure, CXL Root Port, CXL Downstream Switch Port, or CXL Upstream Switch Port, this is the PCIe Capability Structure of the agent.

- The 60-byte structure is used to report device capabilities. This structure is used to report the 36-byte PCIe 1.1 Capability Structure (See Figure 7-9 of the PCI Express Base Specification, Rev 1.1) with the last 24 bytes padded.
- This structure is also used to report the 60-byte PCIe 2.0 Capability Structure (See Figure 7-9 of the PCI Express 2.0 Base Specification.)
- The fields in the structure vary with different device types.
- The “Next CAP pointer” field should be considered invalid and any reserved fields of the structure are reserved for future use. Note that PCIe devices without AER (PCIe_AER_INFO_STRUCTURE_VALID_BIT=0) may report status using this structure.

<table>
<thead>
<tr>
<th>Capability Structure Length</th>
<th>108</th>
<th>2</th>
<th>The length in bytes of the CXL DVSEC field.</th>
</tr>
</thead>
<tbody>
<tr>
<td>CXL Error Log Length</td>
<td>110</td>
<td>2</td>
<td>The length in bytes of the CXL Error Log field.</td>
</tr>
<tr>
<td>Reserved</td>
<td>112</td>
<td>4</td>
<td>Must be zero.</td>
</tr>
<tr>
<td>CXL DVSEC</td>
<td>116</td>
<td>Varies</td>
<td>The length of this variable-length structure is defined by the CXL DVSEC Length field.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>If the CXL agent is a CXL device, this field contains a copy of the CXL Device DVSEC, as defined by the “PCIe DVSEC for Flex Bus Device” structure in the CXL Specification.</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>If the CXL agent is a CXL port, this field contains a copy of the CXL Port DVSEC, as defined by the “CXL DVSEC for Flex Bus Port” structure in the CXL specification.</td>
</tr>
<tr>
<td>CXL Error Log</td>
<td>Varies</td>
<td>Varies</td>
<td>The length of this variable-length structure is defined by the CXL Error Log Length field. For CXL devices and CXL ports, this field contains a copy of the “CXL RAS Capability Structure”, as defined in the CXL Specification.</td>
</tr>
</tbody>
</table>
N.2.14 CXL Component Events Section

Refer to the Events Record Format for CXL components in the CXL Specification, Rev 2.0 or later.

- For the Section Type GUID: Refer to the Event Record Identifier field (Offset 0) of the Events Record Format for each CXL component.
- For the CXL Component Event Log: Refer to the Common Event Record field (Offset 16) of the Events Record Format for each CXL component.

<table>
<thead>
<tr>
<th>Mnemonic</th>
<th>Byte Offset</th>
<th>Byte Length</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Length</td>
<td>0</td>
<td>4</td>
<td>Length in bytes for entire structure.</td>
</tr>
<tr>
<td>Validation Bits</td>
<td>4</td>
<td>8</td>
<td>Bit 0 - Device ID Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 1 - Device Serial Number Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 2 - CXL Component Event Log Valid</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 3-63 - Reserved</td>
</tr>
<tr>
<td>Device ID</td>
<td>12</td>
<td>12</td>
<td>PCIe Device Identifiers of CXL Component:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 0-1: Vendor ID</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 2-3: Device ID</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 4: Function Number</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 5: Device Number</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 6: Bus Number</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 7-8: Segment Number</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 9-10:</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 0:2: Reserved</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Bit 3:15 Slot Number</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 11 Reserved</td>
</tr>
<tr>
<td>Device Serial Number</td>
<td>24</td>
<td>8</td>
<td>Byte 0-3: PCIe Device Serial Number Lower DW</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Byte 4-7: PCIe Device Serial Number Upper DW</td>
</tr>
<tr>
<td>CXL Component Event Log</td>
<td>32</td>
<td>•</td>
<td>CXL Component Event Log, starting with the Common Event Record field</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>corresponding to the Component specified by the Section Type GUID. The</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Length of this field may vary.</td>
</tr>
</tbody>
</table>
To prevent ACPI namespace collision, a UEFI ACPI table format is defined. This allows creation of ACPI tables without colliding with tables reserved in the namespace.

Table O.1: UEFI Table Structure

<table>
<thead>
<tr>
<th>Field</th>
<th>Byte Length</th>
<th>Byte Offset</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Header</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Signature</td>
<td>4</td>
<td>0</td>
<td>‘UEFI’ (0x55, 0x45, 0x46, 0x49). Signature for UEFI drivers that produce ACPI tables.</td>
</tr>
<tr>
<td>Length</td>
<td>4</td>
<td>4</td>
<td>Length, in bytes, of the entire UEFI Table</td>
</tr>
<tr>
<td>Revision</td>
<td>1</td>
<td>8</td>
<td>1</td>
</tr>
<tr>
<td>Checksum</td>
<td>1</td>
<td>9</td>
<td>Entire table must sum to zero.</td>
</tr>
<tr>
<td>OEMID</td>
<td>6</td>
<td>10</td>
<td>OEM ID.</td>
</tr>
<tr>
<td>OEM ID Table ID</td>
<td>8</td>
<td>16</td>
<td>For the UEFI Table, the table ID is the manufacture model ID.</td>
</tr>
<tr>
<td>OEM Revision</td>
<td>4</td>
<td>24</td>
<td>OEM revision of UEFI table for supplied OEM Table ID.</td>
</tr>
<tr>
<td>Creator ID</td>
<td>4</td>
<td>28</td>
<td>Vendor ID of utility that created the table.</td>
</tr>
<tr>
<td>Creator Revision</td>
<td>4</td>
<td>32</td>
<td>Revision of utility that created the table.</td>
</tr>
<tr>
<td>Identifier</td>
<td>16</td>
<td>36</td>
<td>This value contains a GUID which identifies the remaining table contents.</td>
</tr>
<tr>
<td>DataOffset</td>
<td>2</td>
<td>52</td>
<td>Specifies the byte offset to the remaining data in the UEFI table.</td>
</tr>
<tr>
<td>Data</td>
<td>X</td>
<td>DataOffset</td>
<td>Contains the rest of the UEFI table contents</td>
</tr>
</tbody>
</table>

The first use of this UEFI ACPI table format is the SMM Communication ACPI Table. This table describes a special software SMI that can be used to initiate inter-mode communication in the OS present environment by non-firmware agents with SMM code.

**NOTE:** The use of the SMM Communication ACPI table is deprecated in UEFI spec. 2.7. This is due to the lack of a use case for inter-mode communication by non-firmware agents with SMM code and support for initiating this form of communication in common OSes.

Table O.2: SMM Communication ACPI Table.

<table>
<thead>
<tr>
<th>Field</th>
<th>Byte Length</th>
<th>Byte Offset</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Signature</td>
<td>4</td>
<td>0</td>
<td>‘UEFI’ (0x55, 0x45, 0x46, 0x49) Signature for UEFI drivers that produce ACPI tables.</td>
</tr>
</tbody>
</table>
Unified Extensible Firmware Interface (UEFI) Specification, Release 2.9A

Table O.2 – continued from previous page

<table>
<thead>
<tr>
<th>Field</th>
<th>Length</th>
<th>Offset</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Length</td>
<td>4</td>
<td>0</td>
<td>Length, in bytes, of the entire Table. N is a length of the optional implementation specific data that can be included in this table.</td>
</tr>
<tr>
<td>Revision</td>
<td>1</td>
<td>4</td>
<td>66+N. Length, in bytes, of the entire Table. N is a length of the optional implementation specific data that can be included in this table.</td>
</tr>
<tr>
<td>Checksum</td>
<td>1</td>
<td>8</td>
<td>Entire table must sum to zero.</td>
</tr>
<tr>
<td>OEMID</td>
<td>6</td>
<td>10</td>
<td>OEM ID.</td>
</tr>
<tr>
<td>OEM Table ID</td>
<td>8</td>
<td>16</td>
<td>For the UEFI Table, the table ID is the manufacturer model ID.</td>
</tr>
<tr>
<td>OEM Revision</td>
<td>4</td>
<td>24</td>
<td>OEM revision of UEFI table for supplied OEM Table ID.</td>
</tr>
<tr>
<td>Creator ID</td>
<td>4</td>
<td>28</td>
<td>Vendor ID of utility that created the table.</td>
</tr>
<tr>
<td>Creator Revision</td>
<td>4</td>
<td>32</td>
<td>Revision of utility that created the table.</td>
</tr>
<tr>
<td>Identifier</td>
<td>16</td>
<td>36</td>
<td>GUID {0xc68ed8e2, 0x9dc6, 0x4cbd, 0x9d, 0x94, 0xdb, 0x65, \ 0xac, 0xc5, 0xc3, 0x32}</td>
</tr>
<tr>
<td>DataOffset</td>
<td>2</td>
<td>52</td>
<td>Must be 54 for this version of the specification. Specifies the byte offset of the SW SMI Number field, relative to the start of this table. Future expansion may place additional fields between DataOffset and SW SMI Number, so this offset should always be used to calculate the location of SW SMI Number.</td>
</tr>
<tr>
<td>SW SMI Number</td>
<td>4</td>
<td>54</td>
<td>Number to write into software SMI triggering port.</td>
</tr>
<tr>
<td>Buffer Ptr Address</td>
<td>8</td>
<td>58</td>
<td>Address of the communication buffer pointer. The pointer address (this field) and the pointer value (the actual address of the communication buffer) are 64-bit physical addresses. The creator of this table must initialize pointer value with 0. The communication buffer must begin with the EFI_SMM_COMMUNICATE_HEADER defined in the “Related Definitions” section below. The communication buffer must be physically contiguous.</td>
</tr>
<tr>
<td>Invocation register</td>
<td>12</td>
<td>66</td>
<td>Generic Address Structure (GAS) which provides the address of a register that must be written to with the address of a communication buffer to invoke a management mode service. Using this method of invocation is optional, and if not present this span of the table should be populated with zeros. See ACPI6.0 “Generic Address Structure”</td>
</tr>
</tbody>
</table>

O.1 Invocation method

There are two methods of invocation provided by this specification:

1. Using invocation register

If the invocation register is non-zero, this then this method takes precedence and the SW SMI number field and DataOffset fields must be ignored. The invocation register entry provides the address of a register that must be written to in order to invoke the SMM service. The caller must write the communication buffer address into the register. This will cause an SMM invocation. Upon return from the SMM service call the value in the register provides a return error codes from the SMM invocation. See PI/SMM Vol 4 version xx.yy EFI_SMM_COMMUNICATION_PROTOCOL.Communicate function for valid error codes.

The invocation address field uses generic address structure to specify the register address. GAS allows the address space of the register to be Functional Fixed Hardware (FFH). If this address space is used please refer to CPU architecture specific documentation for ascertaining how the write to the register should be performed. For more details on the GAS format please see the ACPI Specification.
Note that for implementations that support concurrent invocation of SMM from multiple processors, the register provided must be a per processor register. In such implementation, the calling execution context must not migrate from one CPU to another between writing to the register, to make the SMM call, and reading the value of the register, to read the error return code.

2. Using the SW SMI number

This method is specific to x86 CPUs.

In order to initiate inter-mode communication OS present agent has to perform the following tasks:

- Prepare communication data buffer that starts with the \textit{EFI_SMM_COMMUNICATE_HEADER}.
- Check the value of the communication buffer pointer (a value at the address specified by the Buffer Ptr Address field). If the pointer’s value is zero, update it with the address of the communication buffer. If the pointer’s value is non-zero, another inter-mode communication transaction is in progress, and the current communication attempt has to be postponed or canceled.

\textbf{NOTE}: \textit{These steps must be performed as an atomic transaction. For example, on IA-32/x64 platforms this can be done using the CMPXCHG CPU instruction.}

- Generate software SMI using value from the SMM Communication ACPI Table. The actual means of generating the software SMI is platform-specific.
- Set communication buffer pointer’s value to zero.

\textbf{Related Definitions}

\begin{verbatim}
typedef struct {
    EFI_GUID HeaderGuid;
    UINTN MessageLength;
    UINT8 Data[ANYSIZE_ARRAY];
} EFI_SMM_COMMUNICATE_HEADER;
\end{verbatim}

- **HeaderGuid**
  Allows for disambiguation of the message format. Type \textit{EFI_GUID} is defined in \textit{InstallProtocolInterface()}.

- **MessageLength**
  Describes the size of \textit{Data} (in bytes) and does not include the size of the header.

- **Data**
  Designates an array of bytes that is \textit{MessageLength} in size
APPENDIX P — HARDWARE ERROR RECORD PERSISTENCE

USAGE

The OS determines if a platform implements support for Hardware Error Record Persistence by reading the HwErrRecSupport globally defined variable. If the attempt to read this variable returns EFI_NOT_FOUND (14), then the OS will infer that the platform does not implement Hardware Error Record Persistence. If the attempt to read this variable succeeds, then the OS uses the returned value to determine whether the platform supports Hardware Error Record Persistence. A non-zero value indicates that the platform supports Hardware Error Record Persistence.

P.1 Determining space

To determine the amount of space (in bytes) guaranteed by the platform for saving hardware error records, the OS invokes QueryVariableInfo, setting the HR bit in the Attributes bitmask.

P.2 Saving Hardware error records

To save a hardware error record, the OS invokes SetVariable, supplying EFI_HARDWARE_ERROR_VARIABLE as the VendorGuid and setting the HR bit in the Attributes bitmask. The VariableName will be constructed by the OS by concatenating an index to the string “HwErrRec” (i.e., HwErrRec0001). The index portion of the variable name is determined by reading all of the hardware error record variables currently stored on the platform and choosing an appropriate index value based on the names of the existing variables. The platform saves the supplied Data. If insufficient space is present to store the record, the platform will return EFI_OUT_OF_RESOURCES, in which case, the OS may clear an existing record and retry. A retry attempt may continue to fail with status EFI_OUT_OF_RESOURCES if a reboot is required to coalesce resources after deletion. The OS may only save error records after ExitBootServices is called. Firmware may also use the Hardware Error Record Persistence interface to write error records, but it may only do so before ExitBootServices is called. If firmware uses this interface to write an error record, it must use the VariableName format used by the OS as described above and the error records it creates must contain the firmware’s CreatorId. Firmware may overwrite error records whose CreatorId matches the firmware’s CreatorId. Firmware may overwrite error records that have been cleared by other components.

During OS initialization, the OS discovers the names of all persisted error record variables by enumerating the current variable names using GetNextVariableName. Having identified the names of all error record variables, the OS will then read and process all of the error records from the store. After the OS processes an error record, it clears the variable if it was the creator of the variable (determined by checking the CreatorId field of the error record).
P.3 Clearing error record variables

To clear error record variables, the OS invokes SetVariable, supplying `EFI_HARDWARE_ERROR_VARIABLE` as the VendorGuid and setting the HR bit in the Attributes bitmask. The supplied DataSize, and Data parameters will all be set to zero to indicate that the variable is to be cleared. The supplied VariableName identifies which error record variable is to be cleared. The OS may only clear error records after ExitBootServices has been called. The OS itself may only clear error records which it created (e.g. error records whose CreatorId matches that of the OS). However, a management application running on the OS may clear error records created by other components. This enables error records created by firmware or other OSes to be cleared by the currently running OS.
Q.1 Related Information

The following publications and sources of information may be useful to you or are referred to by this specification:

- “8802.1x Port-based access control” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
- “Advanced Configuration and Power Interface Specification, 3.0” at “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading
- “Address Resolution Protocol; Refer to Appendix E,”32/64-Bit UNDI Specification” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
- “BLUETOOTH SPECIFICATION, version 4.1” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
- Bootstrap Protocol; This reference is included for backward compatibility. BC protocol supports DHCP and BOOTP. Refer to Appendix E, “32/64-Bit UNDI Specification, RFC 0951” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
- Compute Express Link (CXL) Specification: see download link at <https://uefi.org/uefi#cxl-specification>.

APPENDIX Q — REFERENCES

• “EFI Specification Version 1.02” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi).


• File Verification Using CRC, Mark R. Nelson, Dr. Dobbs, May 1994


• “Information Technology – BIOS Enhanced Disk Drive Services (EDD), working draft T13/ 1386D, Revision 5a” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi).


• “iSCSI Boot Firmware Table (iBFT) as defined in ACPI 3.0b Specification, Version 1.01,” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi).

• “ISO Standard 9995, Keyboard layouts for text and office systems” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi).


• “Itanium® Architecture Software Developer’s Manual, Volume 3: Instruction Set Reference, Rev. 2.2” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi).


• ITU-T Rec. V.42, Error-Correcting Procedures for DCEs using asynchronous-to-synchronous conversion, October, 1996

• “Microsoft Windows Authenticode Portable Executable Signature Format, Version 1.0” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
• “osta Universal Disk Format Specification, Revision 2.00” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
• “PCI BIOS Specification, Revision 3.0” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
• “Part11: Wireless LAN Medium Access Control (MAC) and Physical Layer (PHY) Specifications” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
• “PCI Express Base Specification, Revision 2.1” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
• “PCI Hot-Plug Specification, Revision 1.0,” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
• “PCI Local Bus Specification, Revision 3.0” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
• “Microsoft’s PEAP version 0” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
• “Processor Architecture Type” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
• “Protected EAP Protocol (PEAP)” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
• “Protected EAP Protocol (PEAP) Version 2” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).
• “Request For Comments” heading at “Links to UEFI-Related Documents” (http://uefi.org/uefi). Refer to Appendix E, “32/64-Bit UNDI Specification,” for more information.
Q.1. Related Information


• “[RFC 2818] HTTP Over TLS” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).

• “[RFC 3004] The User Class option for DHCP” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).


• “[RFC 3720] Internet Small Computer Systems Interface (iSCSI)” at “Links to UEFI-Related Documents” (http://uefi.org/uefi).


• “[RFC 4347] Datagram Transport Layer Security” at “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading.


• “[RFC 5216] The EAP-TLS Authentication Protocol” at “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading.


Q.2 Prerequisite Specifications

In general, this specification requires that functionality defined in a number of other existing specifications be present on a system that implements this specification. This specification requires that those specifications be implemented at least to the extent that all the required elements are present.

This specification prescribes the use and extension of previously established industry specification tables whenever possible. The trend to remove runtime call-based interfaces is well documented. The ACPI (Advanced Configuration and Power Interface) specification is an example of new and innovative firmware technologies that were designed on the premise that OS developers prefer to minimize runtime calls into firmware. ACPI focuses on no runtime calls to the BIOS.

Q.2.1 ACPI Specification

The interface defined by the Advanced Configuration and Power Interface (ACPI) Specification is the primary OS runtime interface for IA-32, x64 and Itanium platforms. ACPI fully defines the methodology that allows the OS to discover and configure all platform resources. ACPI allows the description of non-Plug and Play motherboard devices in a plug and play manner. ACPI also is capable of describing power management and hot plug events to the OS. (For more information on ACPI, see “Links to UEFI-Related Documents” (http://uefi.org/uefi) under the heading “ACPI”; see also http://uefi.org/acpi).
Q.2.2 Additional Considerations for Itanium-Based Platforms

Any information or service that is available in Itanium architecture firmware specifications supersedes any requirement in the common supported 32-bit and Itanium architecture specifications listed above. The Itanium architecture firmware specifications (currently the Itanium® System Abstraction Layer Specification and portions of the Intel® Itanium® Architecture Software Developer’s Manual, volumes 1-3) define the baseline functionality required for all Itanium architecture platforms. The major addition that UEFI makes to these Itanium architecture firmware specifications is that it defines a boot infrastructure and a set of services that constitute a common platform definition for high-volume Itanium architecture-based systems to implement based on the more generalized Itanium architecture firmware specifications.

The following specifications are the required Intel Itanium architecture specifications for all Itanium architecture-based platforms:

- “Itanium® System Abstraction Layer Specification” heading at “Links to UEFI-Related Documents” ([http://uefi.org/uefi](http://uefi.org/uefi)).
- “Itanium® Architecture Software Developer’s Manual, Volume 3: Instruction Set Reference, Rev. 2.2” heading at “Links to UEFI-Related Documents” ([http://uefi.org/uefi](http://uefi.org/uefi)).
APPENDIX R — GLOSSARY

_ADR
A reserved name in ACPI name space. It refers to an address on a bus that has standard enumeration. An example would be PCI, where the enumeration method is described in the PCI Local Bus specification.

_CRS
A reserved name in ACPI name space. It refers to the current resource setting of a device. A _CRS is required for devices that are not enumerated in a standard fashion. _CRS is how ACPI converts nonstandard devices into Plug and Play devices.

_HID
A reserved name in ACPI name space. It represents a device’s plug and play hardware ID and is stored as a 32-bit compressed EISA ID. _HID objects are optional in ACPI. However, a _HID object must be used to describe any device that will be enumerated by the ACPI driver in the OS. This is how ACPI deals with non–Plug and Play devices.

_UID
A reserved name in ACPI name space. It is a serial number style ID that does not change across reboots. If a system contains more than one device that reports the same _HID, each device must have a unique _UID. The _UID only needs to be unique for device that have the exact same _HID value.

ACPI Device Path
A Device Path that is used to describe devices whose enumeration is not described in an industry-standard fashion. These devices must be described using ACPI AML in the ACPI name space; this type of node provides linkage to the ACPI name space.

ACPI
Refers to the Advanced Configuration and Power Interface Specification and to the concepts and technology it discusses. The specification defines a new interface to the system board that enables the operating system to implement operating system-directed power management and system configuration.

Alt-GR Unicode
Represents the character code of a key when the Alt-GR modifier key is held down. This key (A2) in some keyboard layouts is defined as the right alternate key and serves the same function as the left alternate key. However, in many other layouts it is a secondary modifier key similar to shift. For instance, key C1 is equated to the letter a and its Unicode character code in the typical U.K. keyboard is a non-shifted character code of 0x0061. When holding down the Alt-GR key in conjunction with the pressing of key C1, the value on the same keyboard often produces an á, which is a character code 0x00E1.

Base Code (BC)
The PXE Base Code, included as a core protocol in EFI, is comprised of a simple network stack (UDP/IP) and a few common network protocols (DHCP, Bootserver Discovery, TFTP) that are useful for remote booting machines.

BC
See Base Code (BC)
Big Endian  
A memory architecture in which the low-order byte of a multibyte datum is at the highest address, while the high-order byte is at the lowest address. See Little Endian.

BIOS Boot Specification Device Path  
A Device Path that is used to point to boot legacy operating systems; it is based on the BIOS Boot Specification, Version 1.01.

BIOS Parameter Block (BPB)  
The first block (sector) of a partition. It defines the type and location of the FAT File System on a drive.

BIOS  

Block I/O Protocol  
A protocol that is used during boot services to abstract mass storage devices. It allows boot services code to perform block I/O without knowing the type of a device or its controller.

Block Size  
The fundamental allocation unit for devices that support the Block I/O Protocol. Not less than 512 bytes. This is commonly referred to as sector size on hard disk drives.

Boot Device  
The Device Handle that corresponds to the device from which the currently executing image was loaded.

Boot Manager  
The part of the firmware implementation that is responsible for implementing system boot policy. Although a particular boot manager implementation is not specified in this document, such code is generally expected to be able to enumerate and handle transfers of control to the available OS loaders as well as UEFI applications and drivers on a given system. The boot manager would typically be responsible for interacting with the system user, where applicable, to determine what to load during system startup. In cases where user interaction is not indicated, the boot manager would determine what to load and, if multiple items are to be loaded, what the sequencing of such loads would be.

Block Size  
The fundamental allocation unit for devices that support the Block I/O Protocol. Not less than 512 bytes. This is commonly referred to as sector size on disk drives.

Boot Services Table  
A table that contains the firmware entry points for accessing boot services functions such as Task Priority Services and Memory Allocation Services. The table is accessed through a pointer in the System Table.

Boot Services Time  
The period of time between platform initialization and the call to ExitBootServices(). During this time, UEFI Driver and applications are loaded iteratively and the system boots from an ordered list of EFI OS loaders.

Boot Services  
The collection of interfaces and protocols that are present in the boot environment. The services minimally provide an OS loader with access to platform capabilities required to complete OS boot. Services are also available to drivers and applications that need access to platform capability. Boot services are terminated once the operating system takes control of the platform.

BPB  
See BIOS Parameter Block (BPB).

BTT  
Block Translation Table: A software mechanism for adding single block write atomicity to any Block Mode ranges or byte-addressable Persistent Memory ranges.

Callback
Target function which augments the Forms Processor’s ability to evaluate or process configuration settings. Call-backs are not available when the Forms Processor is operating in a Disconnected state.

CIM
See Common Information Model (CIM).

Cluster
A collection of disk sectors. Clusters are the basic storage units for disk files. See File Allocation Table (FAT).

COFF
Common Object File Format, a standard file format for binary images.

Coherency Domain
(1) The global set of resources that is visible to at least one processor in a platform.
(2) The address resources of a system as seen by a processor. It consists of both system memory and I/O space.

Common Information Model (CIM)
An object-oriented schema defined by the DMTF. CIM is an information model that provides a common way to describe and share management information enterprise-wide.

Console I/O Protocol
A protocol that is used during Boot Services to handle input and output of text-based information intended for the system administrator. It has two parts, a Simple Input Protocol that is used to obtain input from the ConsoleIn device and a Simple Text Output Protocol that is used to control text-based output devices. The Console I/O Protocol is also known as the EFI Console I/O Protocol.

ConsoleIn
The device handle that corresponds to the device used for user input in the boot services environment. Typically the system keyboard.

ConsoleOut
The device handle that corresponds to the device used to display messages to the user from the boot services environment. Typically a display screen.

DBCS
Double Byte Character Set.

Desktop Management Interface (DMI)
A platform management information framework, built by the DMTF and designed to provide manageability for desktop and server computing platforms by providing an interface that is:
(1) independent of any specific desktop operating system, network operating system, network protocol, management protocol, processor, or hardware platform;
(2) easy for vendors to implement; and
(3) easily mapped to higher-level protocols.

DMTF (formerly Desktop Management Task Force)
The DMTF is a standards organization comprised of companies from all areas of the computer industry. DMTF creates open manageability standards spanning diverse emerging and traditional IT infrastructures including cloud, virtualization, network, servers and storage.

Device Handle
A handle points to a list of one or more protocols that can respond to requests for services for a given device referred to by the handle.

Device I/O Protocol
A protocol that is used during boot services to access memory and I/O. Also called the EFI Device I/O Protocol.
Device Path Instance
When an environment variable represents multiple devices, it is possible for a device path to contain multiple
device paths. An example of this would be the ConsoleOut environment variable that consists of both a VGA
console and a serial output console. This environment variable would describe a console output stream that
would send output to both devices and therefore has a Device Path that consists of two complete device paths.
Each of these paths is a device path instance.

Device Path Node
A variable-length generic data structure that is used to build a device path. Nodes are distinguished by type,
subtype, length, and path-specific data. See Device Path.

Device Path Protocol
A protocol that is used during boot services to provide the information needed to construct and manage Device
Paths. Also called the EFI Device Path Protocol.

Device Path
A variable-length binary data structure that is composed of variable-length generic device path nodes and is
used to define the programmatic path to a logical or physical device. There are six major types of device paths:
Hardware Device Path, ACPI Device Path, Messaging Device Path, Media Device Path, BIOS Boot Specification
Device Path, and End of Hardware Device Path.

DHCP
See Dynamic Host Configuration Protocol (DHCP).

Disconnected
The state when a Forms Processor is manipulating a form set without being connected to the Target’s pre-OS
environment. For example, after booting an OS, a Forms Processor cannot execute call-backs or read the config-
uration settings. For example, when running a Forms Browser while on a remote machine that is not connected
to the Target. In these cases, the Forms Processor has limited knowledge of the Target’s current configuration
settings and limited or no ability to use call-backs.

Disk I/O Protocol
A protocol that is used during boot services to abstract Block I/O devices to allow non-block-sized I/O operations.
Also called the EFI Disk I/O Protocol.

DMI
See DBCS.

DMTF
See DMTF (formerly Desktop Management Task Force).

DNS
Domain Name System. A protocol used manipulating and translating hostname and IP address

DTLS
Datagram Transport Layer Security. A protocol to provide communication privacy above UDP.

Dynamic Host Configuration Protocol (DHCP)
A protocol that is used to get information from a configuration server. DHCP is defined by the DMTF (formerly
Desktop Management Task Force), not EFI.

EAP
Extensible Authentication Protocol. An authentication framework which supports multiple authentication meth-
ods

EBC Image
Executable EBC image following the PE32 file format.

EBC
See EFI Byte Code (EBC).
EFI
Extensible Firmware Interface. An interface between the operating system (OS) and the platform firmware.

EFI Byte Code (EBC)
The binary encoding of instructions as output by the EBC C compiler and linker. The EBC Image is executed by the interpreter.

EFI File
A container consisting of a number of blocks that holds an image or a data file within a file system that complies with this specification.

EFI Hard Disk
A hard disk that supports the new EFI partitioning scheme (GUID Partition).

EFI-compliant
Refers to a platform that complies with this specification.

EFI-conformant
See EFI-compliant.

End of Hardware Device Path
A Device Path which, depending on the subtype, is used to indicate the end of the Device Path instance or Device Path structure.

Enhanced Mode (EM)
The 64-bit architecture extension that makes up part of the Intel® Itanium® architecture.

Event Services
The set of functions used to manage events. Includes EFI_BOOT_SERVICES.CheckEvent(), EFI_BOOT_SERVICES.CreateEvent(), EFI_BOOT_SERVICES.CloseEvent(), EFI_BOOT_SERVICES.SignalEvent(), and EFI_BOOT_SERVICES.WaitForEvent().

Event
An EFI data structure that describes an “event”—for example, the expiration of a timer.

Event Services
The set of functions used to manage events. Includes EFI_BOOT_SERVICES.CheckEvent(), EFI_BOOT_SERVICES.CreateEvent(), EFI_BOOT_SERVICES.CloseEvent(), EFI_BOOT_SERVICES.SignalEvent(), and EFI_BOOT_SERVICES.WaitForEvent().

FAT File System
The file system on which the EFI File system is based. See File Allocation Table (FAT) and GUID Partition Table (GPT).

FAT
See File Allocation Table (FAT).

File Allocation Table (FAT)
A table that is used to identify the clusters that make up a disk file. File allocation tables come in three flavors: FAT12, which uses 12 bits for cluster numbers; FAT16, which uses 16 bits; and FAT32, which allots 32 bits but only uses 28 (the other 4 bits are reserved for future use).

File Handle Protocol
A component of the File System Protocol. It provides access to a file or directory. Also called the EFI File Handle Protocol.

File System Protocol
A protocol that is used during boot services to obtain file-based access to a device. It has two parts, a Simple File System Protocol that provides a minimal interface for file-type access to a device, and a File Handle Protocol that provides access to a file or directory.
**Firmware**
Any software that is included in read-only memory (ROM).

**Font**
A graphical representation corresponding to a character set, in this case Unicode. For more information and examples, see [https://en.wikipedia.org/wiki/Font](https://en.wikipedia.org/wiki/Font).

**Font glyph**
The individual elements of a font corresponding to single characters are called font glyphs or simply glyphs. The first character in each of the above three lines is a glyph for the letter “A” in three different fonts.

**Form**
Logical grouping of questions with a unique identifier.

**Form Set**
An HII database package describing a group of forms, including one parent form and zero or more child forms.

**Forms Browser**
A Forms Processor capable of displaying the user-interface information a display and interacting with a user.

**Forms Processor**
An application capable of reading and processing the forms data within a forms set.

**Globally Unique Identifier (GUID)**
A 128-bit value used to differentiate services and structures in the boot services environment. The format of a GUID is defined in Appendix A. See Protocol.

**Glyph**
The individual elements of a font corresponding to single characters. May also be called font keyboard layout glyphs. Also see font glyph above.

**GPT**
See GUID Partition Table (GPT).

**GPT disk layout:**
The data layout on a disk consisting of a protective MBR in LBA 0, a GPT Header in LBA 1, and additional GPT structures and partitions in the remaining LBAs. See chapter 5.

**GPTHeader**
The header in a GUID Partition Table (GPT). Among other things, it contains the number of GPT Partition Entries and the first and last LBAs that can be used for the entries.

**GPT Partition Entry**
A data structure that characterizes a Partition in the GPT disk layout. Among other things, it specifies the starting and ending LBA of the partition.

**GUID Partition Table (GPT)**
A data structure that describes one or more partitions. It consists of a GPTHeader and, typically, at least one GPTPartition Entry. There are two GUID partition tables: the Primary Partition Table (located in LBA 1 of the disk) and a Backup Partition Table (located in the last LBA of the disk). The Backup Partition Table is a copy of the Primary Partition Table.

**GPTPartition Entry**
A data structure that characterizes a GUID Partition. Among other things, it specifies the starting and ending LBA of the partition.

**GUID Partition**
A contiguous group of sectors on an EFI Hard Disk.

**Handle**
See Device Handle.
Hardware Device Path
A Device Path that defines how a hardware device is attached to the resource domain of a system (the resource domain is simply the shared memory, memory mapped I/O, and I/O space of the system).

HII
Human Interface Infrastructure.

HII Database
The centralized repository for HII-related information, organized as package lists.

HTML
Hypertext Markup Language. A particular implementation of SGML focused on hypertext applications. HTML is a fairly simple language that enables the description of pages (generally Internet pages) that include links to other pages and other data types (such as graphics). When applied to a larger world, HTML has many shortcomings, including localization (q.v.) and formatting issues. The HTML form concept is of particular interest to this application.

HTTP
Hypertext transfer protocol. HTTP functions as request-response protocol in the client-server computing rule.

IA-32
See Intel® Architecture-32 (IA-32).

IFR
Internal Form Representation. Used to represent forms in EFI so that it can be interpreted as is or expanded easily into XHTML.

Image Handle
A handle for a loaded image; image handles support the loaded image protocol.

Image Handoff State
The information handed off to a loaded image as it begins execution; it consists of the image’s handle and a pointer to the image’s system table.

Image Header
The initial set of bytes in a loaded image. They define the image’s encoding.

Image Services
The set of functions used to manage EFI images. Includes EFI_BOOT_SERVICES.LoadImage(), EFI_BOOT_SERVICES.StartImage(), EFI_BOOT_SERVICES.UnloadImage(), EFI_BOOT_SERVICES.Exit(), EFI_BOOT_SERVICES.ExitBootServices(), and EFI_IMAGE_ENTRY_POINT.

Image
(1) An executable file stored in a file system that complies with this specification. Images may be drivers, applications or OS loaders. Also called an EFI Image.

(2) Executable binary file containing EBC and data. Output by the EBC linker.

IME
Input Method Editor. A program or subprogram that is used to map keystrokes to logographic characters. For example, IMEs are used (possibly with user intervention) to map the Kana (Hirigana or Katakana) characters on Japanese keyboards to Kanji.

Intel® Architecture-32 (IA-32)

Intel® Itanium® Architecture
The Intel architecture that has 64-bit instruction capabilities, new performance-enhancing features, and support
for the IA-32 instruction set. This architecture is described in the Itanium™ Architecture Software Developer’s Manual.

**internationalization**

In this context, is the process of making a system usable across languages and cultures by using universally understood symbols. Internationalization is difficult due to the differences in cultures and the difficulty of creating obvious symbols; for example, why does a red octagon mean “Stop”?

**Interpreter**

The software implementation that decodes EBC binary instructions and executes them on a VM. Also called EBC interpreter.

**Keyboard layout**

The physical representation of a user’s keyboard. The usage of this is in conjunction to a structure that equates the physical key(s) and the associated action it represents. For instance, key C1 is equated to the letter a and its Unicode value in the typical U.K. keyboard is a non-shifted value of 0x0061.

**LAN On Motherboard (LOM)**

This is a network device that is built onto the motherboard (or baseboard) of the machine.

**LBA:**

See Logical Block Address (LBA).

**Legacy Platform**

A platform which, in the interests of providing backward-compatibility, retains obsolete technology.

**LFN**

See Long File Names (LFN).

**Little Endian**

A memory architecture in which the low-order byte of a multibyte datum is at the lowest address, while the high-order byte is at the highest address. See Big Endian.

**Load File Protocol**

A protocol that is used during boot services to find and load other modules of code.

**Loaded Image Protocol**

A protocol that is used during boot services to obtain information about a loaded image. Also called the EFI Loaded Image Protocol.

**Loaded Image**

A file containing executable code. When started, a loaded image is given its image handle and can use it to obtain relevant image data.

**Localization**

The process of focusing a system in so that it works using the symbols of a language/culture. To a major extent the following design is influenced by the requirements of localization.

**Logical Block Address (LBA):**

The address of a logical block on a disk. The first LBA on a disk is LBA 0.

**Logographic**

A character set that uses characters to represent words or parts of words rather than syllables or sounds. Kanji is logographic but Kana characters are not.

**LOM**

See LAN On Motherboard (LOM).

**Long File Names (LFN)**

Refers to an extension to the FAT File System that allows file names to be longer than the original standard (eight characters plus a three-character extension).
Machine Check Abort (MCA)
The system management and error correction facilities built into the Intel Itanium processors.

Master Boot Record (MBR)
The data structure that resides on the LBA 0 of a hard disk and defines the partitions on the disk.

MBR
See Master Boot Record (MBR).

MBR boot code:
x86 code in the first LBA of a disk.

MBR disk layout:
The data layout on a disk consisting of an MBR in LBA 0 and partitions described by the MBR in the remaining LBAs. See chapter 5 and Appendix NEW.

MBR Partition Record
A data structure that characterizes a Partition in the MBR disk layout.

MCA
See Machine Check Abort (MCA).

Media Device Path
A Device Path that is used to describe the portion of a medium that is being abstracted by a boot service. For example, a Media Device Path could define which partition on a hard drive was being used.

Memory Allocation Services
The set of functions used to allocate and free memory, and to retrieve the memory map. Includes EFI_BOOT_SERVICES.AllocatePages(), EFI_BOOT_SERVICES.FreePages(), EFI_BOOT_SERVICES.AllocatePool(), EFI_BOOT_SERVICES.FreePool(), and EFI_BOOT_SERVICES.GetMemoryMap().

Memory Map
A collection of structures that defines the layout and allocation of system memory during the boot process. Drivers and applications that run during the boot process prior to OS control may require memory. The boot services implementation is required to ensure that an appropriate representation of available and allocated memory is communicated to the OS as part of the hand-off of control.

Memory Type
One of the memory types defined by UEFI for use by the firmware and UEFI applications. Among others, there are types for boot services code, boot services data, Runtime Services code, and runtime services data. Some of the types are used for one purpose before EFI_BOOT_SERVICES.ExitBootServices() is called and another purpose after.

Messaging Device Path
A Device Path that is used to describe the connection of devices outside the Coherency Domain of the system. This type of node can describe physical messaging information (e.g., a SCSI ID) or abstract information (e.g., networking protocol IP addresses).

Miscellaneous Service
Various functions that are needed to support the EFI environment. Includes EFI_BOOT_SERVICES.InstallConfigurationTable(), ResetSystem(), EFI_BOOT_SERVICES.Stall(), EFI_BOOT_SERVICES.SetWatchdogTimer(), EFI_BOOT_SERVICES.GetNextMonotonicCount(), and GetNextHighMonotonicCount().

MTFTP
See Multicast Trivial File Transfer Protocol (MTFTP).

Multicast Trivial File Transfer Protocol (MTFTP)
A protocol used to download a Network Boot Program to many clients simultaneously from a TFTP server.
Name Space or Namespace
A namespace defines a contiguously-addressed range of Non-Volatile Memory conceptually similar to a SCSI Logical Unit (LUN) or a NVM Express namespace. In general, a collection of device paths; in an EFI Device Path.

Native Code
Low level instructions that are native to the host processor. As such, the processor executes them directly with no overhead of interpretation. Contrast this with EBC, which must be interpreted by native code to operate on a VM.

NBP
See Network Bootstrap Program (NBP) or Network Boot Program.

Network Boot Program
A remote boot image downloaded by a PXE client using the Trivial File Transport Protocol (TFTP) or the Multicast Trivial File Transfer Protocol (MTFTP). See Network Bootstrap Program (NBP).

Network Bootstrap Program (NBP)
This is the first program that is downloaded into a machine that has selected a PXE capable device for remote boot services. A typical NBP examines the machine it is running on to try to determine if the machine is capable of running the next layer (OS or application). If the machine is not capable of running the next layer, control is returned to the EFI boot manager and the next boot device is selected. If the machine is capable, the next layer is downloaded and control can then be passed to the downloaded program. Though most NBPs are OS loaders, NBPs can be written to be standalone applications such as diagnostics, backup/restore, remote management agents, browsers, etc.

Network Interface Card (NIC)
Technically, this is a network device that is inserted into a bus on the motherboard or in an expansion board. For the purposes of this document, the term NIC will be used in a generic sense, meaning any device that enables a network connection - including LOMs and network devices on external buses (USB, 1394, etc.).

NIC
See Network Interface Card (NIC).

Non-spacing key
Typically an accent key that does not advance the cursor and is used to create special characters similar to ÄäÉé. This function is provided only on certain keyboard layouts.

NV
Nonvolatile.

Package
HII information with a unique type, such as strings, fonts, images or forms.

Package List
Group of packages identified by a GUID.

Page Memory
A set of contiguous pages. Page memory is allocated by EFI_BOOT_SERVICES.AllocatePages() and returned by EFI_BOOT_SERVICES.FreePages().

Partition Discovery
The process of scanning a block device to determine whether it contains a Partition.

Partition
A contiguous set of LBAs on a disk, described by the MBR and/or GPT disk layouts.

PC-AT
Refers to a PC platform that uses the AT form factor for their motherboards.
PCI Bus Driver
Software that creates a handle for every PCI Controller on a PCI Host Bus Controller and installs both the PCI I/O Protocol and the Device Path Protocol onto that handle. It may optionally perform PCI Enumeration if resources have not already been allocated to all the PCI Controllers on a PCI Host Bus Controller. It also loads and starts any UEFI drivers found in any PCI Option ROMs discovered during PCI Enumeration. If a driver is found in a PCI Option ROM, the PCI Bus Driver will also attach the Bus Specific Driver Override Protocol to the handle for the PCI Controller that is associated with the PCI Option ROM that the driver was loaded from.

PCI Bus
A collection of up to 32 physical PCI Devices that share the same physical PCI bus. All devices on a PCI Bus share the same PCI Configuration Space.

PCI Configuration Space
The configuration channel defined by PCI to configure PCI Devices into the resource domain of the system. Each PCI device must produce a standard set of registers in the form of a PCI Configuration Header, and can optionally produce device specific registers. The registers are addressed via Type 0 or Type 1 PCI Configuration Cycles as described by the PCI Specification. The PCI Configuration Space can be shared across multiple PCI Buses. On most PC-AT architecture systems and typical Intel® chipsets, the PCI Configuration Space is accessed via I/O ports 0xCF8 and 0xCFC. Many other implementations are possible.

PCI Controller
A hardware component that is discovered by a PCI Bus Driver, and is managed by a PCI Device Driver. PCI Functions and PCI Controller are used equivalently in this document.

PCI Device Driver
Software that manages one or more PCI Controllers of a specific type. A driver will use the PCI I/O Protocol to produce a device I/O abstraction in the form of another protocol (i.e., Block I/O, Simple Network, Simple Input, Simple Text Output, Serial I/O, Load File).

PCI Devices
A collection of up to 8 PCI Functions that share the same PCI Configuration Space. A PCI Device is physically connected to a PCI Buses.

PCI Enumeration
The process of assigning resources to all the PCI Controllers on a given PCI Host Bus Controller. This includes PCI Bus Number assignments, PCI Interrupt assignments, PCI I/O resource allocation, the PCI Memory resource allocation, the PCI Prefetchable Memory resource allocation, and miscellaneous PCI DMA settings.

PCI Functions
A controller that provides some type of I/O services. It consumes some combination of PCI I/O, PCI Memory, and PCI Prefetchable Memory regions, and up to 256 bytes of the PCI Configuration Space. The PCI Function is the basic unit of configuration for PCI.

PCI Host Bus Controller
A chipset component that produces PCI I/O, PCI Memory, and PCI Prefetchable Memory regions in a single Coherency Domain. A PCI Host Bus Controller is composed of one or more PCI Root Bridges.

PCI I/O Protocol
A software interface that provides access to PCI Memory, PCI I/O, and PCI Configuration spaces for a PCI Controller. It also provides an abstraction for PCI Bus Master DMA.

PCI Option ROM
A ROM device that is accessed through a PCI Controller, and is described in the PCI Controller’s Configuration Header. It may contain one or more PCI Device Drivers that are used to manage the PCI Controller.

PCI Root Bridge I/O Protocol
A software abstraction that provides access to the PCI I/O, PCI Memory, and PCI Prefetchable Memory regions in a single Coherency Domain.
PCI Root Bridge
A chipset component(s) that produces a physical PCI Local Bus.

PCI Segment
A collection of up to 256 PCI Buses that share the same PCI Configuration Space. PCI Segment is defined in the ACPI Specification as the _SEG object. The SAL_PCI_CONFIG_READ and SAL_PCI_CONFIG_WRITE procedures defined in chapter 9 of the SAL Specification define how to access the PCI Configuration Space in a system that supports multiple PCI Segments. If a system only supports a single PCI Segment the PCI Segment number is defined to be zero. The existence of PCI Segments enables the construction of systems with greater than 256 PCI buses.

Pool Memory
A set of contiguous bytes. A pool begins on, but need not end on, an “8-byte” boundary. Pool memory is allocated in pages—that is, firmware allocates enough contiguous pages to contain the number of bytes specified in the allocation request. Hence, a pool can be contained within a single page or extend across multiple pages. Pool memory is allocated by EFI_BOOT_SERVICES.AllocatePool() and returned by EFI_BOOT_SERVICES.FreePool().

Preboot Execution Environment (PXE)
A means by which agents can be loaded remotely onto systems to perform management tasks in the absence of a running OS. To enable the interoperability of clients and downloaded bootstrap programs, the client preboot code must provide a set of services for use by a downloaded bootstrap. It also must ensure certain aspects of the client state at the point in time when the bootstrap begins executing.
The complete PXE specification covers three areas; the client, the network and the server.

Client
- Makes network devices into bootable devices.
- Provides APIs for PXE protocol modules in EFI and for universal drivers in the OS.

Network
- Uses existing technology: DHCP, TFTP, etc.
- Adds “vendor-specific” tags to DHCP to define PXE-specific operation within DHCP.
- Adds multicast TFTP for high bandwidth remote boot applications.
- Defines Bootserver discovery based on DHCP packet format.

Server
- Bootserver: Responds to Bootserver discovery requests and serves up remote boot images.
- proxyDHCP: Used to ease the transition of PXE clients and servers into existing network infrastructure.
  proxyDHCP provides the additional DHCP information that is needed by PXE clients and Bootservers without making changes to existing DHCP servers.
- Plug-In Modules: Example proxyDHCP and Bootservers provided in the PXE SDK (software development kit) have the ability to take plug-in modules (PIMs). These PIMs are used to change/enhance the capabilities of the proxyDHCP and Bootservers.

Protocol Handler Services
The set of functions used to manipulate handles, protocols, and protocol interfaces. Includes EFI_BOOT_SERVICES.InstallProtocolInterface(), EFI_BOOT_SERVICES.UninstallProtocolInterface(), EFI_BOOT_SERVICES.ReinstallProtocolInterface(), EFI_BOOT_SERVICES.HandleProtocol(), EFI_BOOT_SERVICES.RegisterProtocolNotify(), EFI_BOOT_SERVICES.LocateHandle(), and EFI_BOOT_SERVICES.LocateDevicePath().

Protocol Handler
A function that responds to a call to a HandleProtocol request for a given handle. A protocol handler returns a
Protocol Interface Structure
The set of data definitions and functions used to access a particular type of device. For example, BLOCK_IO is a protocol that encompasses interfaces to read and write blocks from mass storage devices. See Protocol.

Protocol Revision Number
The revision number associated with a protocol. See Protocol.

Protocol
The information that defines how to access a certain type of device during boot services. A protocol consists of a Globally Unique Identifier (GUID), a protocol revision number, and a protocol interface structure. The interface structure contains data definitions and a set of functions for accessing the device. A device can have multiple protocols. Each protocol is accessible through the device’s handle.

PXE Base Code Protocol
A protocol that is used to control PXE-compatible devices. It may be used by the firmware’s boot manager to support booting from remote locations. Also called the EFI PXE Base Code Protocol.

PXE
See Preboot Execution Environment (PXE).

Question
IFR which describes how a single configuration setting should be presented, stored, and validated.

Read-Only Memory (ROM)
When used with reference to the UNDI specification, ROM refers to a nonvolatile memory storage device on a NIC.

Reset
The action which forces question values to be reset to their defaults.

ROM
See Question.

Runtime Services Table
A table that contains the firmware entry points for accessing runtime services functions such as Time Services and Virtual Memory Services. The table is accessed through a pointer in the System Table.

Runtime Services
Interfaces that provide access to underlying platform specific hardware that may be useful during OS runtime, such as timers. These services are available during the boot process but also persist after the OS loader terminates boot services.

SAL
See System Abstraction Layer (SAL).

scan code
A value representing the location of a key on a keyboard. Scan codes may also encode make (key press) and break (key release) and auto-repeat information.

Serial Protocol
A Protocol that is used during boot services to abstract byte stream devices—that is, to communicate with character-based I/O devices.

SGML

shifted Unicode
Shifted Unicode represents the Unicode character code of a key when the shift modifier key is held down. For
instance, key C1 is equated to the letter a and its Unicode character code in the typical U.K. keyboard is a non-shifted value of 0x0061. When the shift key is held down in conjunction with the pressing of key C1, however, the value on the same keyboard often produces an A, which is a the Unicode character code 0x0041.

A Protocol that is used during boot services to abstract byte stream devices—that is, to communicate with character-based I/O devices.

**Simple File System Protocol**
A component of the File System Protocol. It provides a minimal interface for file-type access to a device.

**Simple Input Protocol**
A protocol that is used to obtain input from the ConsoleIn device. It is one of two protocols that make up the Console I/O Protocol.

**Simple Network Protocol**
A protocol that is used to provide a packet-level interface to a network adapter. Also called the EFI Simple Network Protocol.

**Simple Text Output Protocol**
A protocol that is used to control text-based output devices. It is one of two protocols that make up the Console I/O Protocol.

**SKU**
Stock keeping unit. An acronym commonly used to reference a “version” of a particular platform. An example might be “We have three different SKUs of this platform.”

**SMBIOS**
See System Management BIOS (SMBIOS).

**SNIA**
Storage Network Industry Association.(www.snia.org)

**SNIA Common RAID Disk Data Format**

**SSL**
Secure Sockets Layer. A security protocol that provides communications privacy over the Internet. It is predecessor to TLS.

**StandardError**
The device handle that corresponds to the device used to display error messages to the user from the boot services environment.

**Status Codes**
Success, error, and warning codes returned by boot services and runtime services functions.

**string**
A null-terminated array of 16-bit UCS-2 encoded Unicode characters. All strings in this specification are encoded using UCS-2 unless otherwise specified.

**Submit**
The action which forces modified question values to be written back to storage.

**System Abstraction Layer (SAL)**
Firmware that abstracts platform implementation differences, and provides the basic platform software interface to all higher level software.

**System Management BIOS (SMBIOS)**
A table-based interface that is required by the Wired for Management Baseline Specification. It is used to relate platform-specific management information to the OS or to an OS-based management agent.
System Table
Table that contains the standard input and output handles for a UEFI application, as well as pointers to the boot services and runtime services tables. It may also contain pointers to other standard tables such as the ACPI, SMBIOS, and SAL System tables. A loaded image receives a pointer to its system table when it begins execution. Also called the EFI System Table.

Target
The system being configured.

Task Priority Level (TPL)
The boot services environment exposes three task priority levels: “normal,” “callback,” and “notify.”

Task Priority Services
The set of functions used to manipulate task priority levels. Includes EFI_BOOT_SERVICES.RaiseTPL() and EFI_BOOT_SERVICES.RestoreTPL().

TFTP
See Trivial File Transport Protocol (TFTP).

Time Format
The format for expressing time in an EFI-compliant platform. For more information, see Appendix A.

Time Services
The set of functions used to manage time. Includes GetTime(), SetTime(), GetWakeupTime(), and SetWakeupTime().

Timer Services
The set of functions used to manipulate timers. Contains a single function, EFI_BOOT_SERVICES.SetTimer().

TLS
Transport Layer Security. A protocol to provide privacy and data integrity between two communicating applications above TCP.

TPL
See Target.

Trivial File Transport Protocol (TFTP)
A protocol used to download a Network Boot Program from a TFTP server.

UEFI
Unified Extensible Firmware Interface. The interface between the operating system (OS) and the platform firmware defined by this specification.

UEFI Application
Modular code that may be loaded in the boot services environment to accomplish platform specific tasks within that environment. Examples of possible applications might include diagnostics or disaster recovery tools shipped with a platform that run outside the OS environment. UEFI applications may be loaded in accordance with policy implemented by the platform firmware to accomplish a specific task. Control is then returned from the UEFI application to the platform firmware.

UEFI Boot Service Driver
A UEFI driver that is loaded into boot services memory and stays resident until boot services terminate.

UEFI Driver
A module of code typically inserted into the firmware via protocol interfaces. Drivers may provide device support during the boot process or they may provide platform services. It is important not to confuse UEFI drivers with OS drivers that load to provide device support once the OS takes control of the platform.

UEFI OS Loader
A UEFI application that is the first piece of operating system code loaded by the firmware to initiate the OS boot
process. This code is loaded at a fixed address and then executed. The OS takes control of the system prior to completing the OS boot process by calling the interface that terminates all boot services.

**UEFI Runtime Services Driver**
A UEFI driver that is loaded into runtime services memory and stays resident during runtime.

**Unaccepted Memory**
Some Virtual Machine platforms, such as AMD SEV-SNP, introduce the concept of memory acceptance, requiring memory to be accepted before it can be used by the guest. This protects against a class of attacks by the virtual machine platform.

**UNDI**
See Universal Network Device Interface (UNDI).

**Unicode Collation Protocol**
A protocol that is used during boot services to perform case-insensitive comparisons of strings.

**Unicode**
An industry standard internationalized character set used for human readable message display.

**Universal Network Device Interface (UNDI)**
UNDI is an architectural interface to NICs. Traditionally NICs have had custom interfaces and custom drivers (each NIC had a driver for each OS on each platform architecture). Two variations of UNDI are defined in this specification: H/W UNDI and S/W UNDI. H/W UNDI is an architectural hardware interface to a NIC. S/W UNDI is a software implementation of the H/W UNDI.

**Universal Serial Bus (USB)**
A bi-directional, isochronous, dynamically attachable serial interface for adding peripheral devices such as serial ports, parallel ports, and input devices on a single bus.

**URI**
Uniform resource identifier. URI is a string of characters used to identify a name of a resource.

**USB Bus Driver**
Software that enumerates and creates a handle for each newly attached USB Controller and installs both the USB I/O Protocol and the Device Path Protocol onto that handle, starts that device driver if applicable. For each newly detached USB Controller, the device driver is stopped, the USB I/O Protocol and the Device Path Protocol are uninstalled from the device handle, and the device handle is destroyed.

**USB Bus**
A collection of up to 127 physical USB Devices that share the same physical USB bus. All devices on a USB Bus share the bandwidth of the USB Bus.

**USB Controller**
A hardware component that is discovered by a USB Bus Driver, and is managed by a USB Device Driver. USB Interface and USB Controller are used equivalently in this document.

**USB Device Driver**
Software that manages one or more USB Controller of a specific type. A driver will use the USB I/O Protocol to produce a device I/O abstraction in the form of another protocol (i.e., Block I/O, Simple Network, Simple Input, Simple Text Output, Serial I/O, Load File).

**USB Device**
A USB peripheral that is physically attached to the USB Bus.

**USB Enumeration**
A periodical process to search the USB Bus to detect if there have been any USB Controller attached or detached. If an attach event is detected, then the USB Controllers device address is assigned, and a child handle is created. If a detach event is detected, then the child handle is destroyed.
USB Host Controller
Moves data between system memory and devices on the USB Bus by processing data structures and generating the USB transactions. For USB 1.1, there are currently two types of USB Host Controllers: UHCI and OHCI.

USB Hub
A special USB Device through which more USB devices can be attached to the USB Bus.

USB I/O Protocol
A software interface that provides services to manage a USB Controller, and services to move data between a USB Controller and system memory.

USB Interface
The USB Interface is the basic unit of a physical USB Device.

USB
See Universal Serial Bus (USB).

Variable Services
The set of functions used to manage variables. Includes GetVariable(), SetVariable(), and GetNextVariable-Name().

Virtual Memory Services
The set of functions used to manage virtual memory. Includes SetVirtualAddressMap() and ConvertPointer().

VM
The Virtual Machine, a pseudo processor implementation consisting of registers which are manipulated by the interpreter when executing EBC instructions.

Watchdog Timer
An alarm timer that may be set to go off. This can be used to regain control in cases where a code path in the boot services environment fails to or is unable to return control by the expected path.

WfM
See Wired for Management (WfM).

Wired for Management (WfM)
Refers to the Wired for Management Baseline Specification. The Specification defines a baseline for system manageability issues; its intent is to help lower the cost of computer ownership.

x64
Processors that are compatible with instruction sets and operation modes as exemplified by the AMD64 or Intel® Extended Memory 64 Technology (Intel® EM64T) architecture.

XHTML
Extensible HTML. XHTML “will obey all of the grammar rules of XML (properly nested elements, quoted attributes, and so on), while conforming to the vocabulary of HTML (the elements and attributes that are available for use ant their relationships to one another).” [PXML, pg., 153]. Although not completely defined, XHTML is basically the intersection of XML and HTML and does support forms.

XML
Extensible Markup Language. A subset of SGML. Addresses many of the problems with HTML but does not currently (1.0) support forms in any specified way.